# 8Servos Unit

#### SKU:U165



## Description

**8Servos Unit** is an 8-channel servo driver unit that uses the **STM32F030F4** master control to generate multiple PWM signals for servo drive and communicate with the M5 host through I2C (addr: 0x25). Built-in total power MOSTUBE switch circuit, support programming dynamic control motor release/lock;Built-in total current acquisition circuit, the total circuit parameters can be known. Supports two sets of power inputs (9-24V / 5V). This product is suitable for servo control, robot control, intelligent toys, etc.

## Features

- 8-channel servo drive
- Programmable motor power supply
- I2C Protocol Control (0x25)
- Reverse power supply protection
- Total current harvesting function

#### Includes

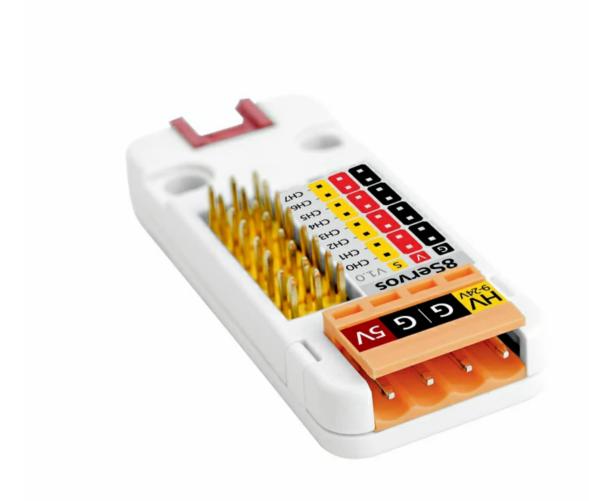
- ∘ 1 × 8Servo Unit
- 1 × HT3.96-4P

# Applications

- Servo controller
- Robot control

# Specification

Resources	Parameters									
Current acquisition chip	INA199A1DCKR									
Servo drive channel	8-channel									
Maximum drive load capacity	8-channel maximum load capacity: DC5V@1.3A									
I2C Address	0x25 55*24*11.5mm 136* 92* 13mm									
Product Size										
Package Size										
Product Weight	10.1g									
Package Weight	17.6g									



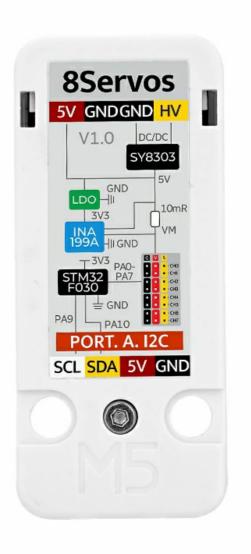












#### Products related to this item

CoreS3 (K128)

CORE2 (K010)

**TOUGH (K034)** 

BASIC-V27 (K001-V27)

M5StickC PLUS (K016-P)

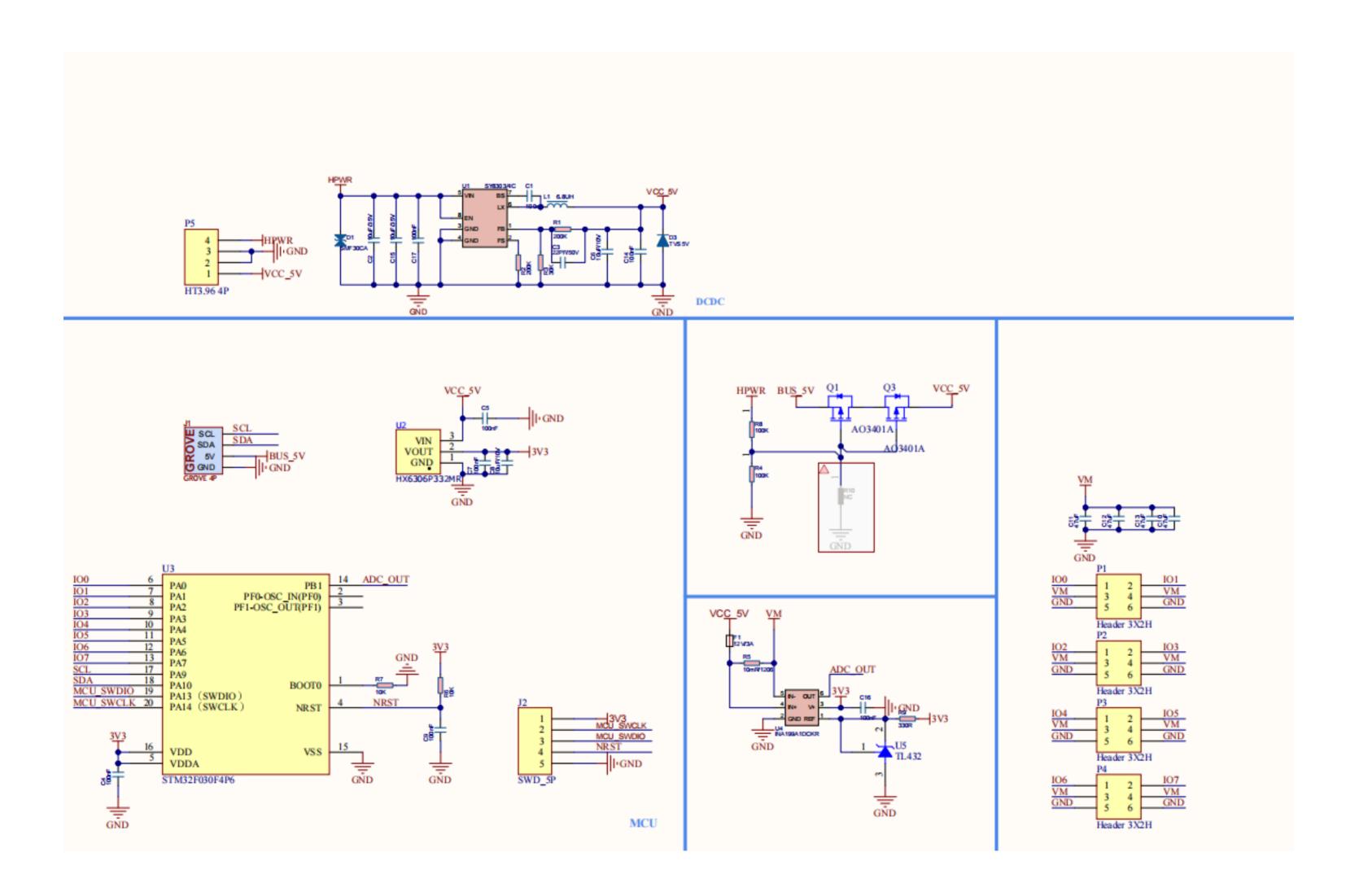
ATOM Lite (C008)

AtomS3 Lite (C124)

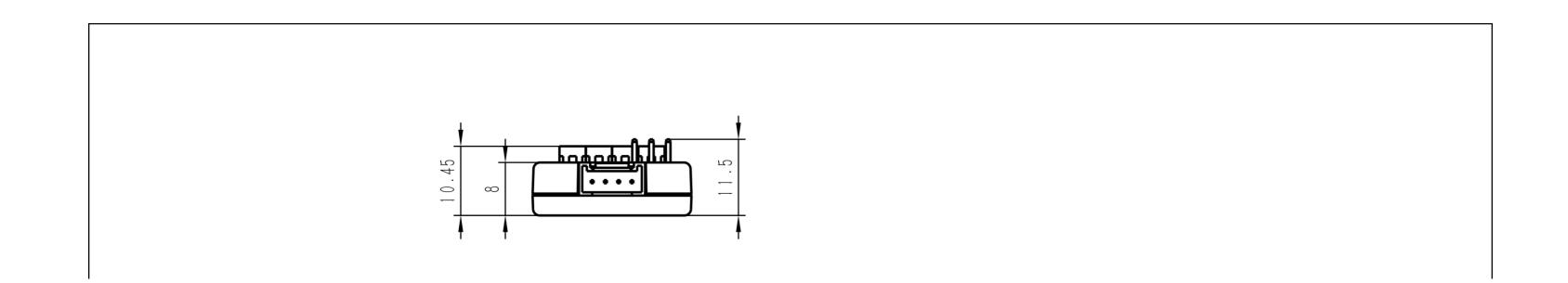
#### Related Link

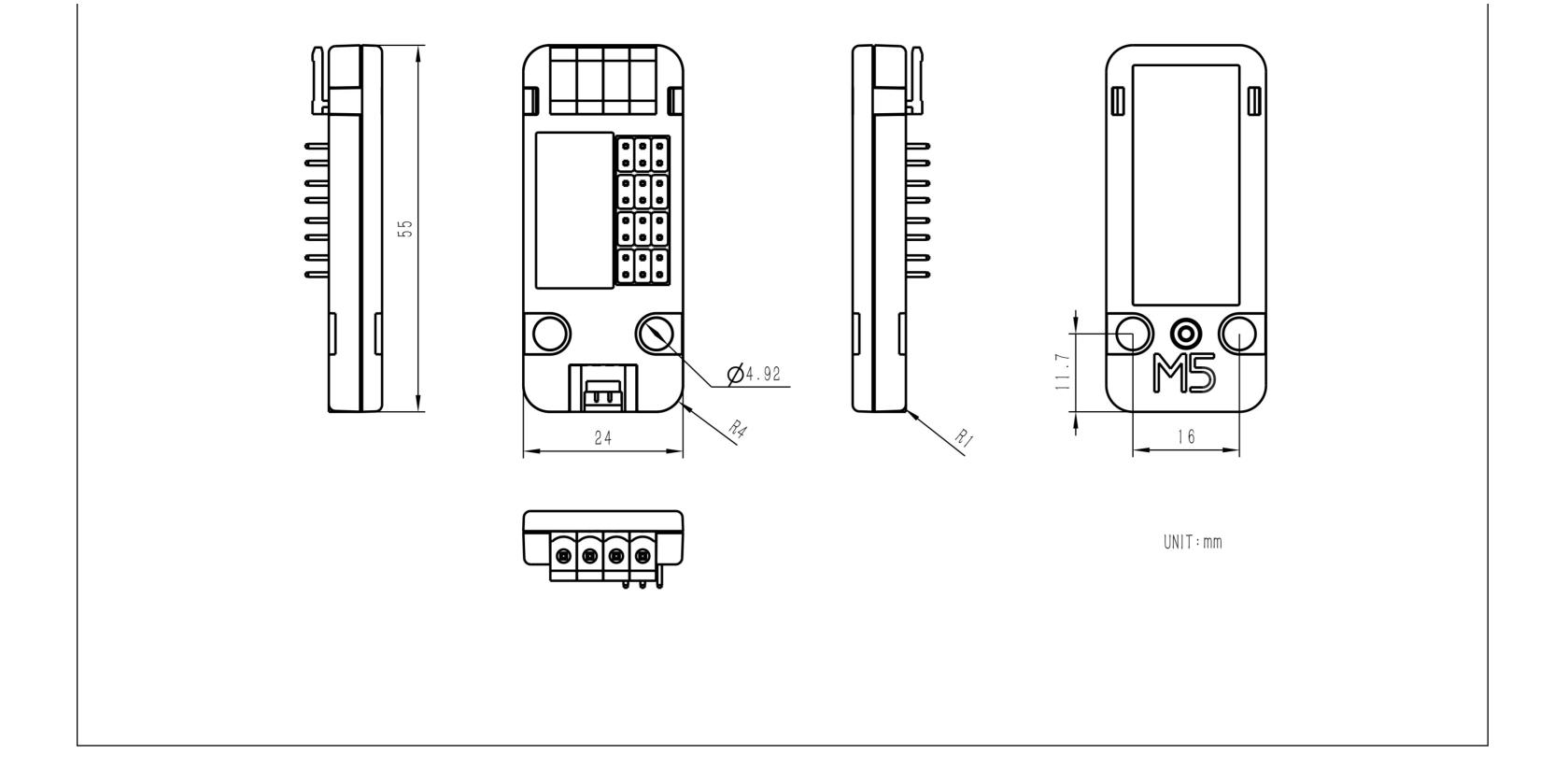
• INA199A1DCKR

### Schematic



#### Module Size





# Examples

#### Arduino

- 8Servo Unit Firmware Download
- 8Servo Unit Example

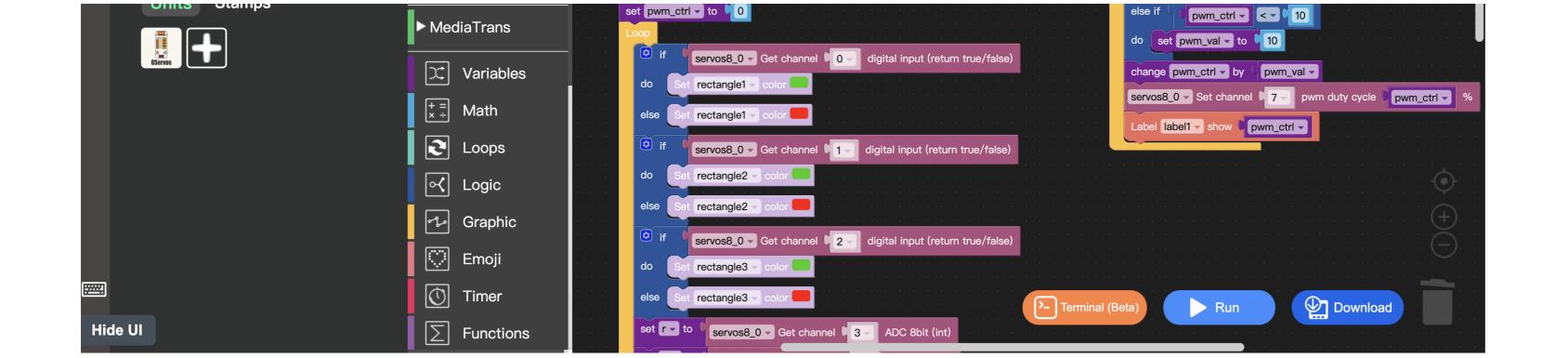
M5Stack Unit 8Servo I2C Protocol												V1 (FW Version) 2023/3/24							
REG MAP (Addr:0x25)		0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F	note	
	MODE SETTING	0x00 W/R	100	IO1	102	IO3	104	105	106	107									Mode:0~4 <sup>[1]</sup>
1	OUTPUT CTRL	0x10 W	100	IO1	102	IO3	104	IO5	106	107									0:LOW ; 1:HIGH
0	DIGITAL INPUT	0x20 R	100	IO1	102	IO3	104	105	106	107									0:LOW; 1:HIGH
2	ANALOG INPUT-8Bits	0x30 R	100	101	102	IO3	104	105	106	107			value:0~255						
	ANALOG INPUT-12Bits	0x40 R	IO0-L	<u>О</u> Н	IO1-L	101-H	IO2-L	102 <b>-</b> H	IO3-L	<u>O</u> 3- T	IO4-L	104 <b>-</b> H	IO5-L	105- H	IO6-L	<u>О</u> 6- Н	107-L	107- H	value:0~4095
3	SERVO 8Bits	0x50 W/R	100	101	102	IO3	104	105	106	107									value:0~180degree
3	SERVO 16Bits	0x60 W/R	IO0-L	100- H	IO1-L	101-H	IO2-L	IO2- H	IO3-L	Ю3- Н	104-L	104- H	105 <b>-</b> L	H	106-L	106- H	107-L	Ю7- Н	value:500~2500us
	RGB \\24Bits \C	0x70 W/R	100- R	100- G	100 <b>-</b> B	IO1-R	IO1-G	IO1-B	102 <b>-</b> R	102 <b>-</b> G	IO2-B	IO3- R	103- G	IO3-B	104 <b>-</b> R	104 <b>-</b> G	IO4- B	105- R	D/C/D-0 255
4		0x80 W/R	105 <b>-</b> G	105 <b>-</b> B	106- R	106- G	106-B	107-R	107- G	107 <b>-</b> B									R/G/B:0~255
5	PWM DutyCycle	0x90 W/R	pwm 0	pwm1	pwm 2	pwm 3	pwm 4	pwm 5	pwm 6	pwm 7									DutyCycle:0~100 (frequency:1KHz)
S	Servo Current		nt-	curre nt- byte1	nt-	curre nt- byte3													float
12	2C ADDRESS SETTING	0xF0 W/R																Addr	value: 0~127 default:0x25
Firmware 0xF0 version R															Versi on		Version: firmware version		

[1] 0: Input, 1: Output, 2: ADC, 3: Servo, 4: NeoPixel, 5: PWM

#### **UIFlow**

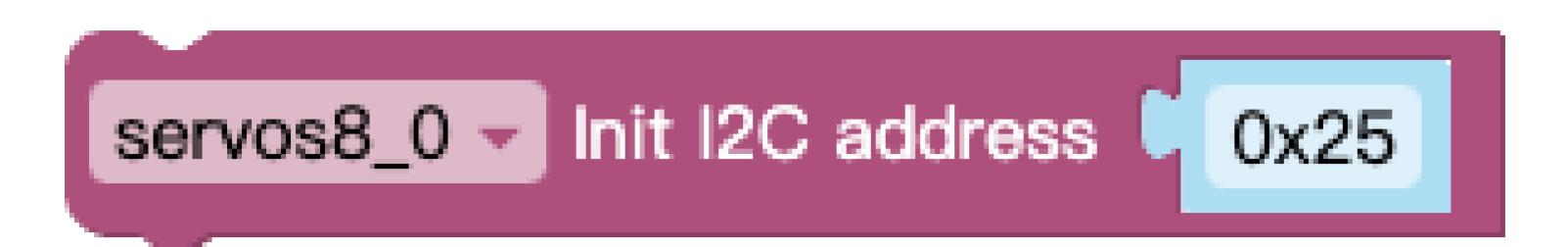
8Servos Unit UIFlow Demo





#### UIFlow Blocks

Init I2C address



Set config mode



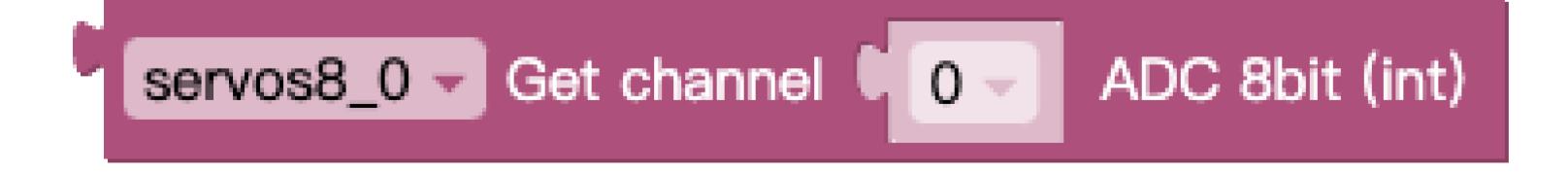
Get config mode



Get digital input



Get ADC 8bit

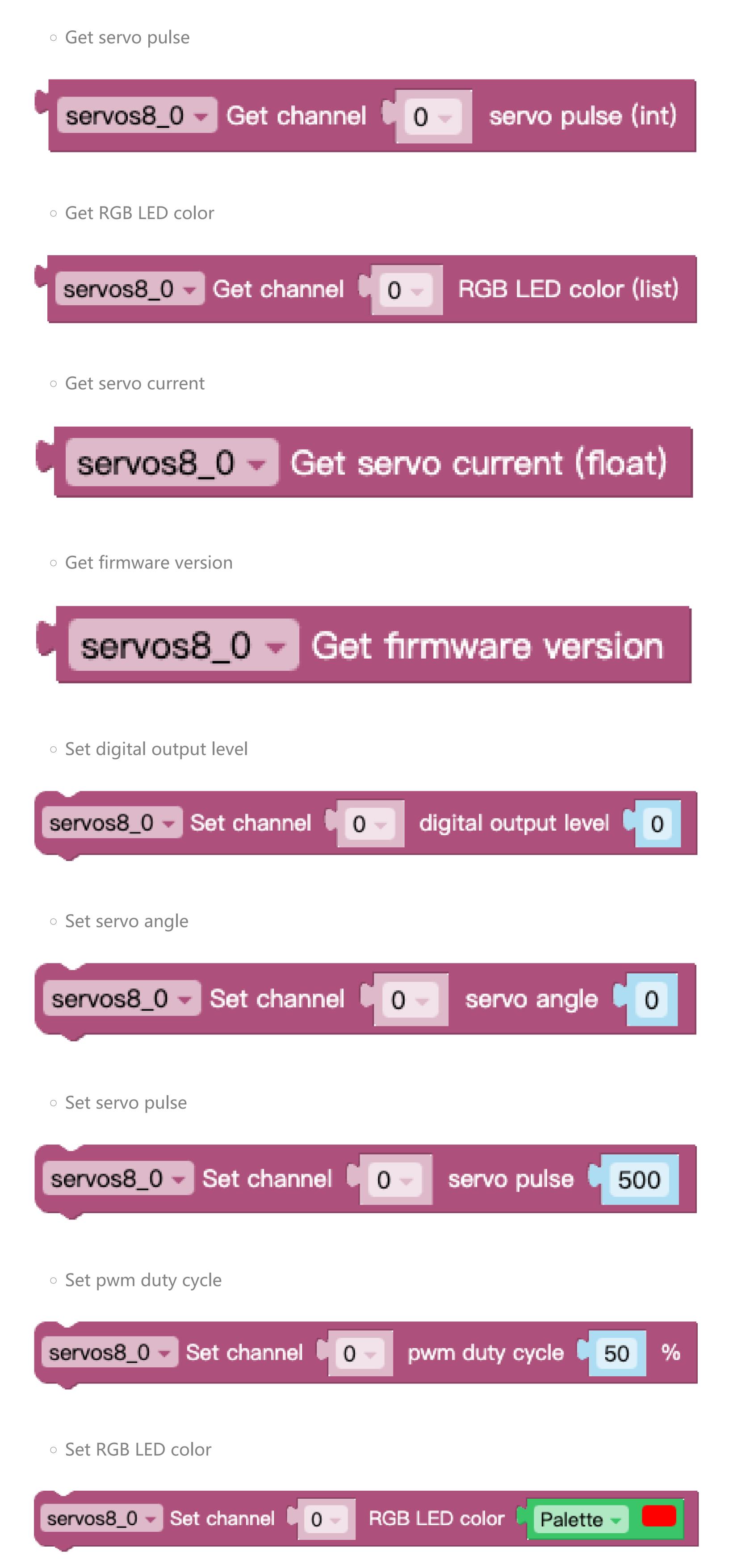


Get ADC 12bit



Get servo angle







## Video

control 8 servos demo