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SPECIFICATION					
NUMBER OF PHASES: 4		ROTOR INERTIA: 82 g-cm ² (0.44 oz-in ²) NOM			
STEPS PER REVOLUTION: 200		DETENT TORQUE: 244 g-cm (3.39 oz-in) MIN			
STEP ANGLE: 1.8°		INSULATION CLASS: B			
STEP TO STEP ACCURACY: 0.09°		1	,	2	BEARINGS: ABEC 3, DOUBLE SHIELDED
POSITION ACCURACY: 0.09°		1	,	3	TEMP. RISE: 80°C MAX. 9
HYSTERESIS: N/A%		OPERATING TEMP. RANGE: -20 TO +50 °C			
SHAFT RUNOUT: 0.03 mm T.I.R. MAX		STORAGE TEMP. RANGE: -30 TO +70 °C			
RADIAL PLAY: 0.02 mm MAX (0.5 kg RADIAL LOAD)		RELATIVE HUMIDITY RANGE: 15 TO 85%			
END PLAY: 0.08 mm MAX (0.5 kg AXIAL LOAD)		WEIGHT: 340 g (12.0 oz) APPROXIMATE			
CONNECTION	RESISTANCE PER PHASE (ohm ±10%) 7	INDUCTANCE PER PHASE (mH ±20%) 8	RATED CURRENT (Amp)	HOLDING TORQUE (Nm MIN) 1	HOLDING TORQUE (oz-in MIN) 1
BI-POLAR SERIES	6.6	10	0.85	0.44	62.3
BI-POLAR PARALLEL	1.7	2.5	1.70	0.44	62.3
UNI-POLAR	3.3	2.5	1.20	0.31	43.8

NOTES, UNLESS OTHER WISE SPECIFIED:

1

MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.

2

BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.

3

MAXIMUM ERROR IN 360°.

4.

HI POT 500 VAC, 60Hz FOR ONE MINUTE.

5

LEADS: 8, 26 AWG, 7 STRAND MIN. UL AND CSA APPROVED. UL 1430

6.

INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.

7

AS MEASURED ACROSS EACH PHASE.

8

AS MEASURED ACROSS EACH PHASE USING AN A.C. INDUCTANCE BRIDGE AT 1KHz.

9

AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED CURRENT APPLIED TO 2 PHASES: WITH MOTOR AT REST.

10.

ROTOR AND STATOR LAMINATED CONSTRUCTION.

11.

12

MOTOR LABEL TO INCLUDE AMP LOGO, AMP WEBSITE ADDRESS, "RoHS" COMPLIANCE LOGO, AMP P/N, "MADE IN (COUNTRY)", AND DATE CODE.

REVISIONS				
ECO #	REV.	DESCRIPTION	DATE	APPROVED
5976	A	INITIAL RELEASE	8/28/09	J. KORDIK
6036	B	REVISE SPECS	12/10/09	J. KORDIK
6090	C	STANDARDIZE ENCODER HOLES	3/10/10	J. KORDIK
7247	D	ADDED UL TO LABEL	1/26/16	J. KORDIK
7446	E	REVISED NOTE 10	6/6/16	J. KORDIK
8209	F	DOCUMENT CLEAN UP	4/22/19	J. KORDIK
8277	G	REMOVE ENCODER HOLES	7/3/19	J. KORDIK
8675	H	RE-DRAW IN SOLIDWORKS, ENCODER HOLE DEPTH CHANGED	6/15/21	L. LIU
9023	J	SEPARATE DUAL SHAFT DRAWING, REVISED WINDING SPECS	01/18/24	K. KESLER

WIRING DIAGRAM

DRIVE SEQUENCE MODEL
BI-POLAR PARALLEL FULL STEP

STEP	ORG & BLK/WHT	BLK & ORG/WHT	RED & YEL/WHT	YEL & RED/WHT
1	+	-	+	-
2	-	+	+	-
3	-	+	-	+
4	+	-	-	+
1	+	-	+	-

CW (CLOCKWISE) AND CCW (COUNTER-CLOCKWISE) ROTATION WHEN SEEN FROM THE FLANGE SIDE OF THE MOTOR

Applied Motion Products

A MOONS' COMPANY

PROPRIETARY AND CONFIDENTIAL

THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF APPLIED MOTION PRODUCTS. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF APPLIED MOTION PRODUCTS IS PROHIBITED.

THIRD ANGLE PROJECTION		NAME	DATE	TITLE: STEPPER MOTOR		
UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN MILLIMETERS TOLERANCES: - ANGULAR: ± 0.5 - ONE DECIMAL PLACE: ± 0.25 - TWO DECIMAL PLACES: ± 0.13	DRAWN	C.BREUNINGER	01/17/24			
	PRE.CHECK					
	PRE.APPROVAL					
	FIN.CHECK	E.MERINO	01/17/24			
MATERIAL	SAP: 4611110029089			SIZE B	DWG. NO. HT17-275	REV J
FINISH	ALT DWG. NO.:					
DO NOT SCALE DRAWING	ALT SAP:					

SCALE: 1:1

SHEET 1 OF 2

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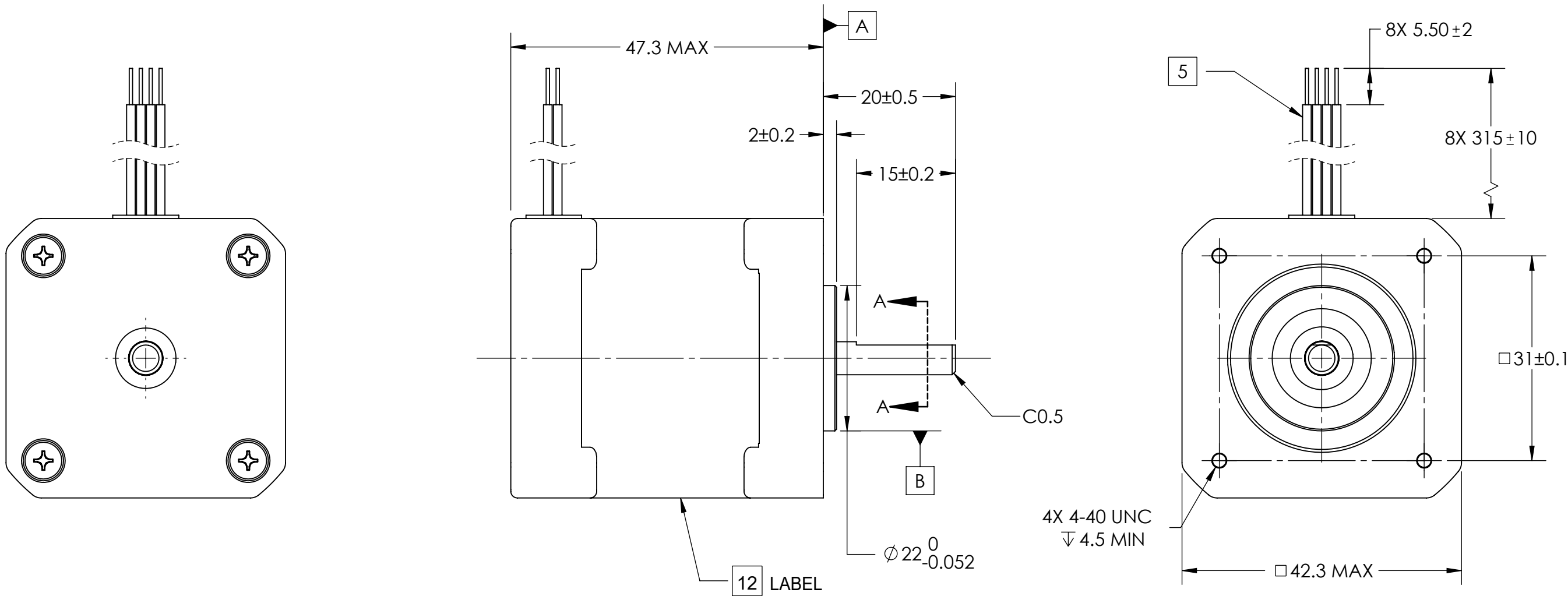
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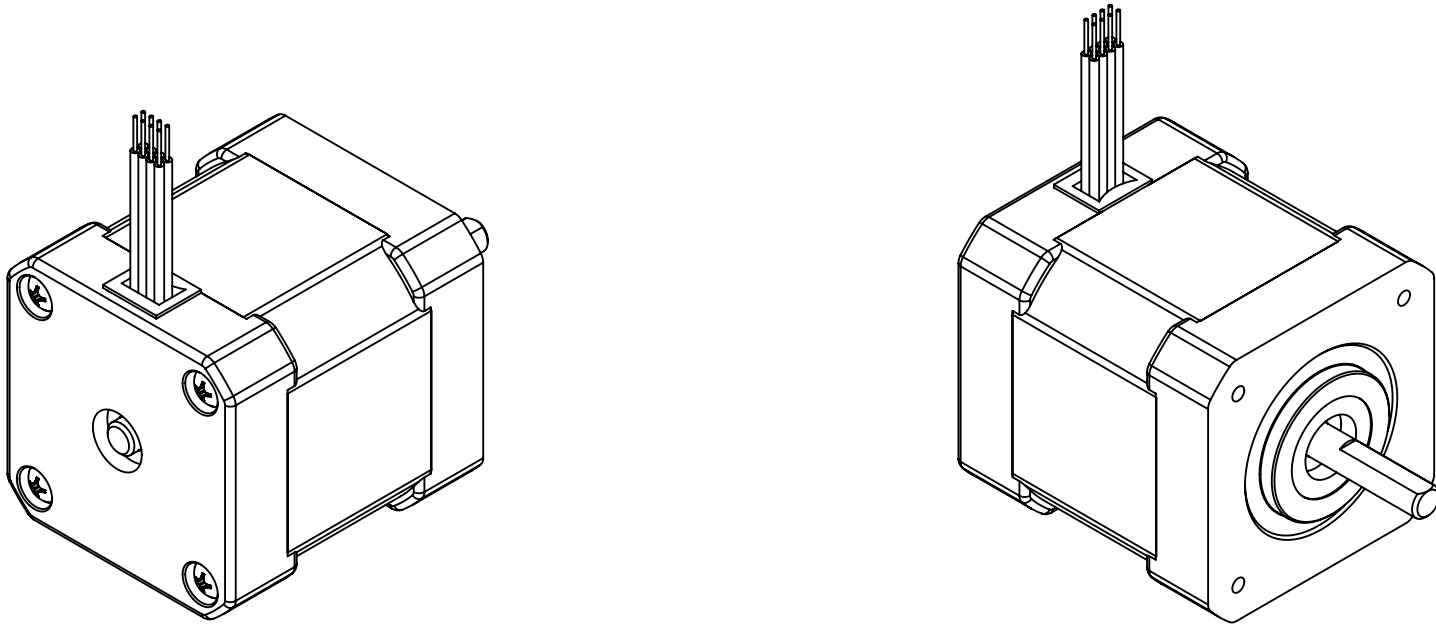
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	FINISH		ALT DWG. NO.:			B	HT17-275	J
	DO NOT SCALE DRAWING		ALT SAP:					
						SCALE: 1:2		SHEET 2 OF 2