# DCM™ DC-DC Converter

## DCM3623x50T13A6y7z

## Isolated, Regulated DC Converter

## Features & Benefits

- Isolated, regulated DC-DC converter
- Up to 160W, 13.40A continuous
- 91.5% peak efficiency
- 412W/in³ power density
- Wide input range 9 – 50$V_{DC}$
- Safety Extra Low Voltage (SELV) 12.0V nominal output
- 2250$V_{DC}$ isolation
- ZVS high-frequency switching
  - Enables low-profile, high-density filtering
- Fully operational current limit
- OV, OC, UV, short circuit and thermal shut down

## Typical Applications

- Industrial
- Process Control
- Transportation / Heavy Equipment
- Defense / Aerospace

### Product Ratings

| Product Ratings | |
|---|---|
| $V_{IN}$ = 9 – 50V | $P_{OUT}$ = 160W |
| $V_{OUT}$ = 12.0V (7.2 – 13.2V Trim) | $I_{OUT}$ = 13.40A |

## Product Description

The DCM Isolated, Regulated DC Converter is a DC-DC converter, operating from an unregulated, wide-range input to generate an isolated 12.0$V_{DC}$ output. With its high-frequency zero-voltage switching (ZVS) topology, the DCM converter consistently delivers high efficiency across the input line range. Modular DCM converters and downstream DC-DC products support efficient power distribution, providing superior power system performance and connectivity from a variety of unregulated power sources to the point-of-load.

Leveraging the thermal and density benefits of Vicor ChiP™ packaging technology, the DCM module offers flexible thermal management options with very low top- and bottom-side thermal impedances. Thermally-adept ChiP-based power components enable customers to achieve cost effective power system solutions with previously unattainable system size, weight and efficiency attributes, quickly and predictably.
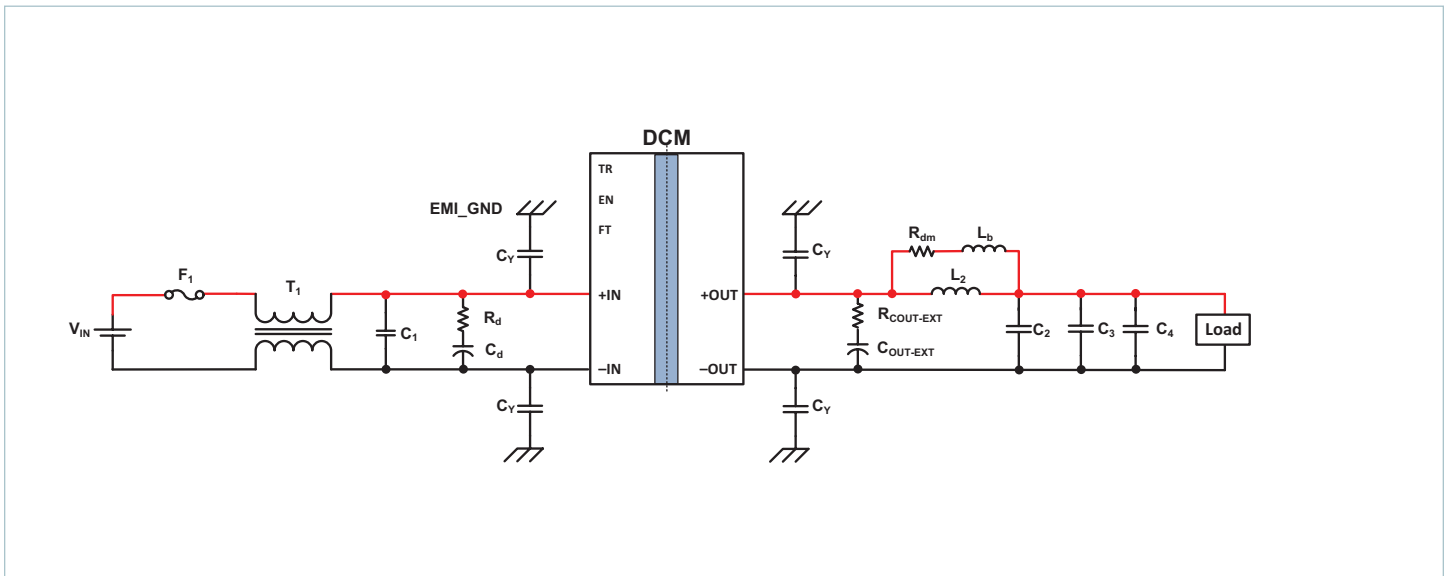
## Package Information

- Through-hole ChiP package
  - 1.524 x 0.898 x 0.284in [38.72 x 22.80 x 7.21mm]
  - Weight: 24.0g [0.85oz]

**Note:** Product images may not highlight current product markings and cosmetic features.
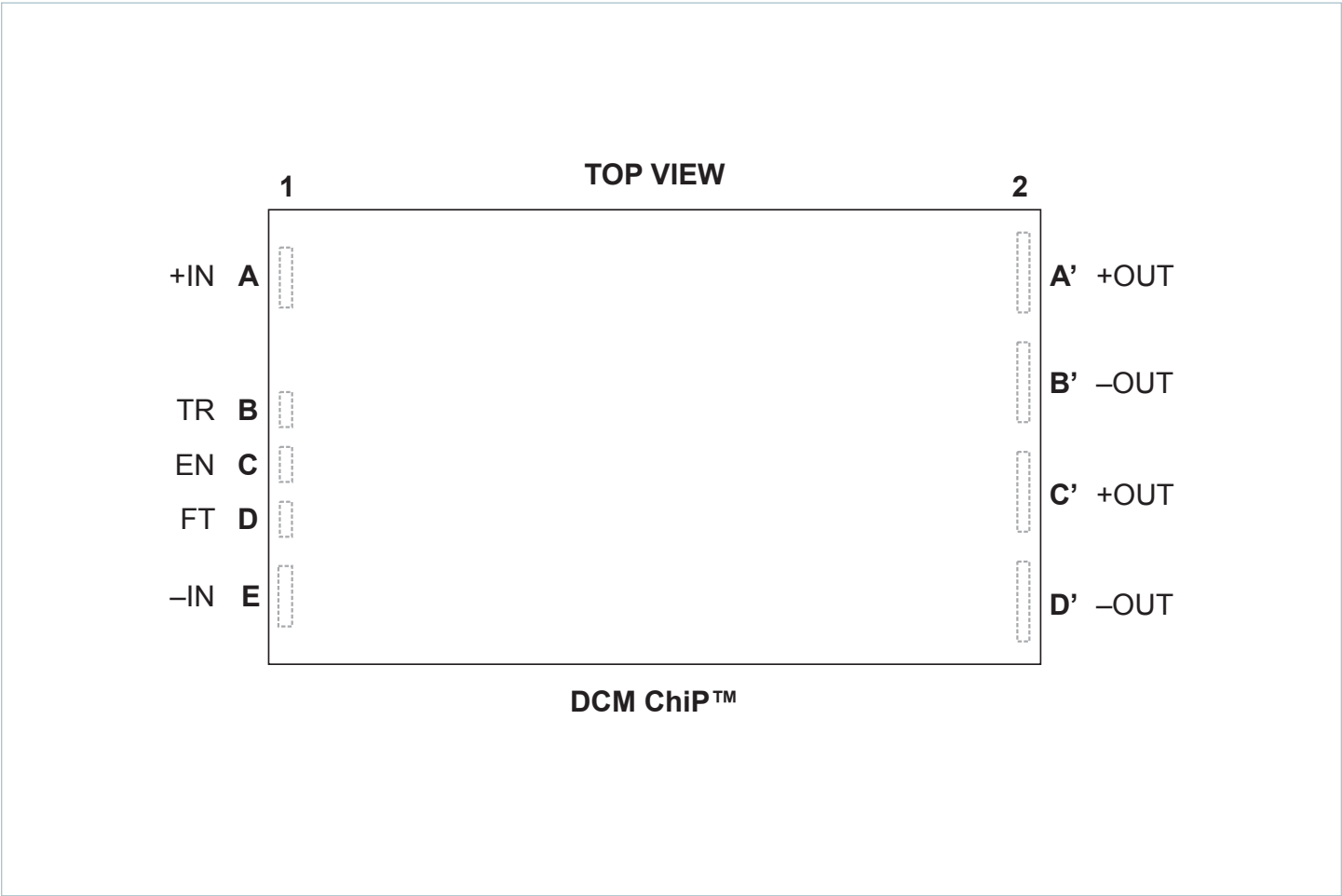
## Typical Applications
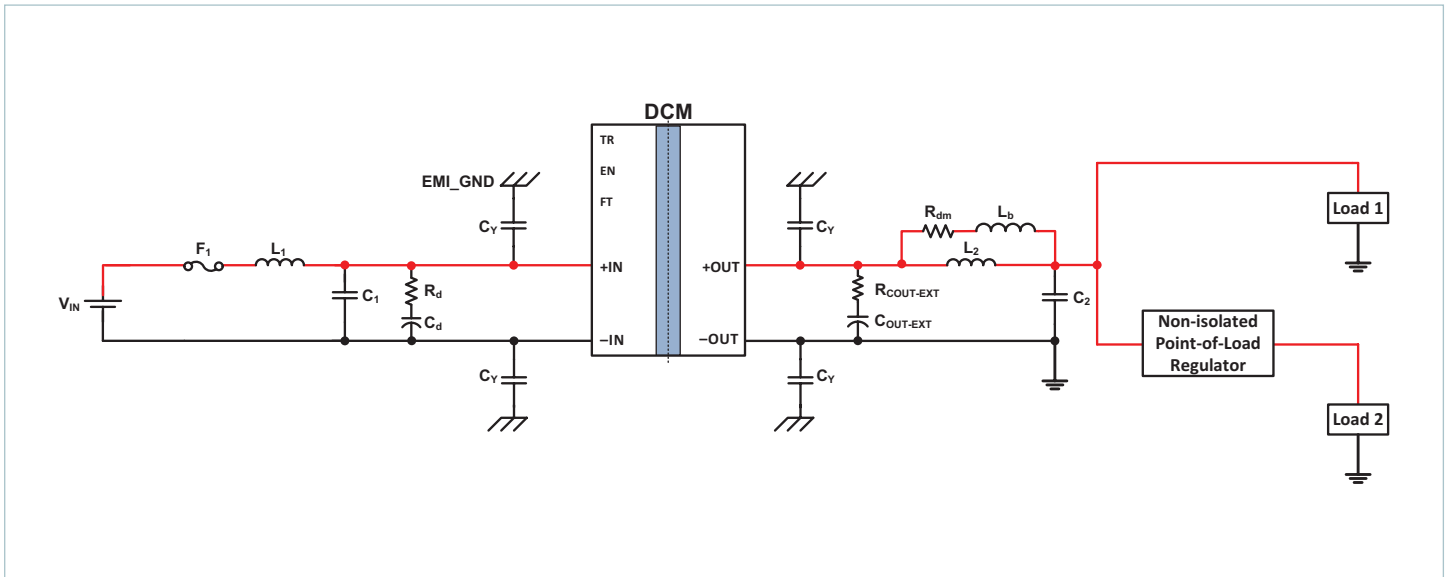


*Typical application 1: single DCM3623x50T13A6y7z to a non-isolated regulator and direct to load*



*Typical application 2: single DCM3623x50T13A6y7z with common- and differential-mode input filters*

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## Pin Configuration

**TOP VIEW**

**1**                                                        **2**

+IN  **A**                                                   **A'**  +OUT

TR  **B**                                                    **B'**  –OUT

EN  **C**                                                    **C'**  +OUT

FT  **D**

–IN  **E**                                                   **D'**  –OUT

**DCM ChiP™**

## Pin Descriptions

| Pin Number | Signal Name | Type | Function |
|---|---|---|---|
| A1 | +IN | INPUT POWER | Positive input power terminal |
| B1 | TR | INPUT | Enables and disables trim functionality; adjusts output voltage when trim active |
| C1 | EN | INPUT | Enables and disables power supply |
| D1 | FT | OUTPUT | Fault monitoring |
| E1 | –IN | INPUT POWER RETURN | Negative input power terminal |
| A'2, C'2 | +OUT | OUTPUT POWER | Positive output power terminal |
| B'2, D'2 | –OUT | OUTPUT POWER RETURN | Negative output power terminal |

## Part Ordering Information

| Part Number | Temperature Grade | Option | Tray Size |
|---|---|---|---|
| DCM3623T50T13A6**T70** | **T** = –40 to 125°C | **70** = Enhanced V$_{OUT}$ Regulation / Analog Control Interface Version | 323 x 136 x 16mm 24 parts per tray |
| DCM3623T50T13A6**M70** | **M** = –55 to 125°C | | |

## Storage and Handling Information

Note: For compressive loading refer to Application Note AN:036, "Recommendations for Maximum Compressive Force of Heat Sinks."
For handling and assembly processing refer to Application Note AN:031, "Through-Hole ChiP™ Package Soldering Guidelines."

| Parameter | Comments | | Specification |
|---|---|---|---|
| Storage Temperature Range | T-Grade | | –40 to 125°C |
| | M-Grade | | –65 to 125°C |
| Operating Internal Temperature Range (T$_{INT}$) | T-Grade | | –40 to 125°C |
| | M-Grade | | –55 to 125°C |
| Peak Temperature Top Case (Soldering) [a] | For further information, please contact factory applications | | 135°C |
| Lead Finish | Nickel | | 0.51 – 2.03μm |
| | Palladium | | 0.02 – 0.15μm |
| | Gold | | 0.003 – 0.051μm |
| Weight | | | 24.0g [0.85oz] |
| MSL Rating | Not applicable to through-hole ChiP products | | N/A |
| ESD Rating | Method per Human Body Model (HBM) Test ESDA / JEDEC JDS-001-2012 | | Class 1C |
| | Charged Device Model (CDM) JESD22-C101E | | Class 2 |

[a] Product is not intended for reflow solder attach.

## Safety, Reliability and Agency Approvals

| Parameter | Comments | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| Dielectric Withstand Test | IN to OUT | **2250** | | | V$_{DC}$ |
| | IN to CASE | **2250** | | | V$_{DC}$ |
| | OUT to CASE | **707** | | | V$_{DC}$ |
| Insulation Resistance | IN to OUT, IN to CASE, OUT to CASE at 500V$_{DC}$, 1 minute | 10 | | | MΩ |
| MTBF | MIL-HDBK-217 FN2 Parts Count  25°C Ground Benign, Stationary, Indoors / Computer | | 3.39 | | MHrs |
| | Telcordia Issue 2, Method I Case 3, 25°C, 100% D.C., GB, GC | | 5.68 | | |
| Agency Approvals/Standards | cURus, 60950-1 Information Technology Equipment, Component Recognition | | | | |
| | | | | | |
| | cTÜVus, EN IEC 62368-1, UL 62368-1, CSA-C22.2 No. 62368-1 | | | | |
| | UKCA, electrical equipment (safety) regulations | | | | |
| | CE Marked for Low Voltage Directive and RoHS Recast Directive, as applicable | | | | |

## Absolute Maximum Ratings

The absolute maximum ratings below are stress ratings only. Operation at or beyond these maximum ratings can cause permanent damage to the device. Electrical specifications do not apply when operating beyond rated operating conditions.

| Parameter | Comments | Min | Max | Unit |
|---|---|---|---|---|
| Input Voltage (+IN to –IN) | | -0.5 | 65.0 | V |
| Input Voltage Slew Rate | | -1 | 1 | V/μs |
| TR to –IN | | -0.3 | 3.5 | V |
| EN to –IN | | -0.3 | 3.5 | V |
| FT to –IN | | -0.3 | 3.5 | V |
| | | | 5 | mA |
| Output Voltage (+OUT to –OUT) | | -0.5 | 15.6 | V |
| Dielectric Withstand (Input to Output) | Basic insulation | 2250 | | $V_{DC}$ |
| Average Output Current | | | 22.0 | A |

## Electrical Specifications

Specifications apply over all line, trim and load conditions, internal temperature $T_{INT}$ = 25°C, unless otherwise noted. **Boldface** specifications apply over the temperature range of –40°C < $T_{INT}$ < 125°C for T-Grade and –55°C < $T_{INT}$ < 125°C for M-Grade.

| Attribute | Symbol | Conditions / Notes | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| | | | | | | |
| | | **Power Input Specifications** | | | | |
| Input Voltage Range | $V_{IN}$ | Continuous operation | **9** | **30** | **50** | V |
| Inrush Current (Peak) | $I_{INRP}$ | With maximum $C_{OUT\text{-}EXT}$, full resistive load | | | **25.0** | A |
| Input Capacitance (Internal) | $C_{IN\text{-}INT}$ | Effective value at nominal input voltage | | 28.6 | | µF |
| Input Capacitance (Internal) ESR | $R_{CIN\text{-}INT}$ | At 1MHz | | 0.39 | | mΩ |
| Input Inductance (External) | $L_{IN}$ | Differential mode, with no further line bypassing | | | **1** | µH |
| | | | | | | |
| | | **No-Load Specifications** | | | | |
| Input Power – Disabled | $P_Q$ | Nominal line, see Figure 3 | | 0.5 | 1.0 | W |
| | | Worst case line, see Figure 3 | | | **1.5** | |
| Input Power – Enabled with No Load | $P_{NL}$ | Nominal line, see Figure 5 | | 1.3 | 3.4 | W |
| | | Worst case line, see Figure 5 | | | **4.6** | |
| | | | | | | |
| | | **Power Output Specifications** | | | | |
| Output Voltage Set Point | $V_{OUT\text{-}NOM}$ | $V_{IN}$ = 30V, nominal trim, at 100% load | 11.94 | 12.0 | 12.06 | V |
| Rated Output Voltage Trim Range | $V_{OUT\text{-}TRIMMING}$ | Trim range over temp at full load; Specifies the low, nominal and high trim conditions | **7.2** | **12.0** | **13.2** | V |
| Output Voltage Load Regulation | $\Delta V_{OUT\text{-}REGULATION}$ | Nominal line, nominal trim, full load and ambient temperature | -0.5 | | 0.5 | % |
| | | Nominal line, nominal trim and:<br>• Load >20% of full load and ambient temperature<br>• Full load and over temperature | -1.0 | | 1.0 | |
| | | All other conditions<br>(does not include light-load regulation) | -2.0 | | 2.0 | |
| Output Voltage Accuracy | $\%V_{OUT\text{-}ACCURACY}$ | The total output voltage set-point accuracy from the calculated $V_{OUT}$ based on load, temp and trim; Excludes:<br>• $\Delta V_{OUT\text{-}LL}$<br>• $\%V_{OUT\text{-}REGULATION}$ | **-3.0** | | **3.0** | % |
| Output Voltage Light-Load Regulation | $\Delta V_{OUT\text{-}LL}$ | 0 – 10% load, additional $V_{OUT}$, relative to $V_{OUT}$ accuracy; see Design Guidelines section | **0.00** | | **2.40** | V |
| Rated Output Power | $P_{OUT}$ | Continuous, $V_{OUT} \geq$ 12.0V | **160** | | | W |
| Rated Output Current | $I_{OUT}$ | Continuous, $V_{OUT} \leq$ 12.0V | **13.40** | | | A |
| Output Current Limit | $I_{OUT\text{-}LIM}$ | Of rated $I_{OUT}$ max. Fully operational current limit, for nominal trim and below. | 100 | 120 | 150 | % |
| Current Limit Delay | $t_{IOUT\text{-}LIM}$ | The module will power limit in a fast transient event. | | 1 | | ms |
| Efficiency | η | Full load, nominal line, nominal trim | 90.8 | 91.5 | | % |
| | | Full load, over line and temperature, nominal trim | **88.9** | | | |
| | | 50% load, over rated line, temperature and trim | **86.0** | | | |
| Output Voltage Ripple | $V_{OUT\text{-}PP}$ | 20MHz bandwidth. At nominal trim, minimum $C_{OUT\text{-}EXT}$ and at least 10% rated load | | 420 | | mV |

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# Electrical Specifications (Cont.)

Specifications apply over all line, trim and load conditions, internal temperature $T_{INT}$ = 25°C, unless otherwise noted. **Boldface** specifications apply over the temperature range of –40°C < $T_{INT}$ < 125°C for T-Grade and –55°C < $T_{INT}$ < 125°C for M-Grade.

| Attribute | Symbol | Conditions / Notes | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| | | | | | | |
| **Power Output Specifications (Cont.)** | | | | | | |
| Output Capacitance (Internal) | $C_{OUT-INT}$ | Effective value at nominal output voltage | | 123 | | µF |
| Output Capacitance ESR (Internal) | $R_{COUT-INT}$ | At 1MHz | | 2.900 | | mΩ |
| Output Capacitance (External) | $C_{OUT-EXT}$ | For load transients that remain >10% rated load; excludes component temperature coefficient | **1000** | | **10000** | µF |
| | $C_{OUT-EXT-TRANS}$ | For load transients down to 0% rated load, with static trim; excludes component temperature coefficient | **10000** | | **10000** | µF |
| | $C_{OUT-EXT-TRANS-TRIM}$ | For load transients down to 0% rated load, with dynamic trimming; excludes component temperature coefficient | **10000** | | **10000** | µF |
| Output Capacitance ESR (External) | $R_{COUT-EXT}$ | At 10kHz, excludes component tolerances | **10** | | | mΩ |
| Initialization Delay | $t_{INIT}$ | See state diagram | | 25 | **40** | ms |
| Output Turn-On Delay | $t_{ON}$ | From rising edge EN, with $V_{IN}$ pre-applied; see timing diagram | | 200 | | µs |
| Output Turn-Off Delay | $t_{OFF}$ | From falling edge EN; see timing diagram | | | **600** | µs |
| Soft-Start Ramp Time | $t_{SS}$ | At full rated resistive load with minimum $C_{OUT-EXT}$ | | 31 | | ms |
| Output Voltage Threshold for Max Rated Load Current | $V_{OUT-FL-THRESH}$ | During start up, $V_{OUT}$ must achieve this threshold before output can support full rated current | | | **6.0** | V |
| Output Current at Start Up | $I_{OUT-START}$ | Max load current at start up while $V_{OUT}$ is below $V_{OUT-FL\_THRESH}$ | **1.33** | | | A |
| Monotonic Soft-Start Threshold Voltage | $V_{OUT-MONOTONIC}$ | Output voltage rise becomes monotonic with 10% of preload once it crosses $V_{OUT-MONOTONIC}$ | | | **6.0** | V |
| Minimum Required Disabled Duration | $t_{OFF-MIN}$ | This refers to the minimum time a module needs to be in the disabled state before it will attempt to start via EN | | | **2** | ms |
| Minimum Required Disabled Duration for Predictable Restart | $t_{OFF-MONOTONIC}$ | This refers to the minimum time a module needs to be in the disabled state before it is guaranteed to exhibit monotonic soft-start and have predictable start-up timing | | | **100** | ms |
| Voltage Deviation (Transient) | $\%V_{OUT-TRANS}$ | Minimum $C_{OUT\_EXT}$ (10 ↔ 90% load step) | | <10 | | % |
| Settling Time | $t_{SETTLE}$ | | | 9.7 | | ms |

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## Electrical Specifications (Cont.)

Specifications apply over all line, trim and load conditions, internal temperature $T_{INT}$ = 25°C, unless otherwise noted. **Boldface** specifications apply over the temperature range of –40°C < $T_{INT}$ < 125°C for T-Grade and –55°C < $T_{INT}$ < 125°C for M-Grade.

| Attribute | Symbol | Conditions / Notes | Min | Typ | Max | Unit |
|-----------|--------|--------------------|-----|-----|-----|------|
| | | | | | | |
| | | **Powertrain Protections** | | | | |
| Input Voltage Initialization Threshold | $V_{IN\text{-}INIT}$ | Threshold to start $t_{INIT}$ delay | | | **6** | V |
| Input Voltage Reset Threshold | $V_{IN\text{-}RESET}$ | Latching faults will clear once $V_{IN}$ falls below $V_{IN\text{-}RESET}$ | **3** | | | V |
| Input Undervoltage Lockout Threshold | $V_{IN\text{-}UVLO-}$ | | **5.40** | | **8.55** | V |
| Input Undervoltage Recovery Threshold | $V_{IN\text{-}UVLO+}$ | See timing diagram | | | **9.00** | V |
| Input Overvoltage Lockout Threshold | $V_{IN\text{-}OVLO+}$ | | | | **55** | V |
| Input Overvoltage Recovery Threshold | $V_{IN\text{-}OVLO-}$ | See timing diagram | **50** | | | V |
| Output Overvoltage Threshold | $V_{OUT\text{-}OVP}$ | From 25 to 100% load; latched shut down | **15.00** | | | V |
| | $V_{OUT\text{-}OVP\text{-}LL}$ | From 0 to 25% load; latched shut down | **15.60** | | | V |
| Minimum Current Limited $V_{OUT}$ | $V_{OUT\text{-}UVP}$ | Over all operating steady-state line and trim conditions | | | **4.49** | V |
| Overtemperature Threshold (Internal) | $T_{INT\text{-}OTP}$ | | **125** | | | °C |
| Power Limit | $P_{LIM}$ | | | | **320** | W |
| Input Voltage Overvoltage to Cessation of Powertrain Switching | $t_{OVLO\text{-}SW}$ | Independent of fault logic | | 2.3 | | μs |
| Input Voltage Overvoltage Response Time | $t_{OVLO}$ | For fault logic only | | | **200** | μs |
| Input Voltage Undervoltage Response Time | $t_{UVLO}$ | | | | **100** | ms |
| Short Circuit Response Time | $t_{SC}$ | Powertrain on, operational state | | | **200** | μs |
| Short Circuit, or Temperature Fault Recovery Time | $t_{FAULT}$ | See timing diagram | | 1 | | s |

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## Electrical Specifications (Cont.)

Specifications apply over all line, trim and load conditions, internal temperature $T_{INT}$ = 25°C, unless otherwise noted. **Boldface** specifications apply over the temperature range of –40°C < $T_{INT}$ < 125°C for T-Grade and –55°C < $T_{INT}$ < 125°C for M-Grade.

| Attribute | Symbol | Conditions / Notes | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| | | | | | | |
| **Trim: TR** | | | | | | |
| TR Trim Disable Threshold | $V_{TRIM-DIS-TH}$ | Trim disabled when TR above this threshold at power up | | | **3.20** | V |
| TR Trim Enable Threshold | $V_{TRIM-EN-TH}$ | Trim enabled when TR below this threshold at power up | **3.15** | | | V |
| Internally Generated $V_{CC}$ | $V_{CC}$ | | **3.21** | 3.30 | **3.39** | V |
| TR Pin Functional Range | $V_{TRIM-EN}$ | | 0.00 | 2.46 | 3.16 | V |
| $V_{OUT}$ Referred TR Pin Resolution | $V_{OUT-RES}$ | With $V_{CC}$ = 3.3V | | 15 | | mV |
| TR Internal Pull-Up Resistance to $V_{CC}$ | $R_{TRIM-INT}$ | | **9.9** | 10.0 | **10.1** | kΩ |
| | | | | | | |
| **Enable: EN** | | | | | | |
| EN Enable Threshold | $V_{ENABLE-EN-TH}$ | | | | **2.31** | V |
| EN Disable Threshold | $V_{ENABLE-DIS-TH}$ | | **0.99** | | | V |
| Internally Generated $V_{CC}$ | $V_{CC}$ | | **3.21** | 3.30 | **3.39** | V |
| EN internal Pull-Up Resistance to $V_{CC}$ | $R_{ENABLE-INT}$ | | **9.9** | 10.0 | **10.1** | kΩ |
| | | | | | | |
| **Fault: FT** | | | | | | |
| FT Internal Pull-Up Resistance to $V_{CC}$ | $R_{FAULT-INT}$ | | **494** | 499 | **504** | kΩ |
| FT Voltage | $V_{FAULT-ACTIVE}$ | At rated current drive capability | **3.0** | | | V |
| FT Current Drive Capability | $I_{FAULT-ACTIVE}$ | Overload beyond the ABSOLUTE MAXIMUM ratings may cause module damage | **4** | | | mA |
| FT Response Time | $t_{FT-ACTIVE}$ | Delay from cessation of switching to FT Pin Active | | | **200** | µs |
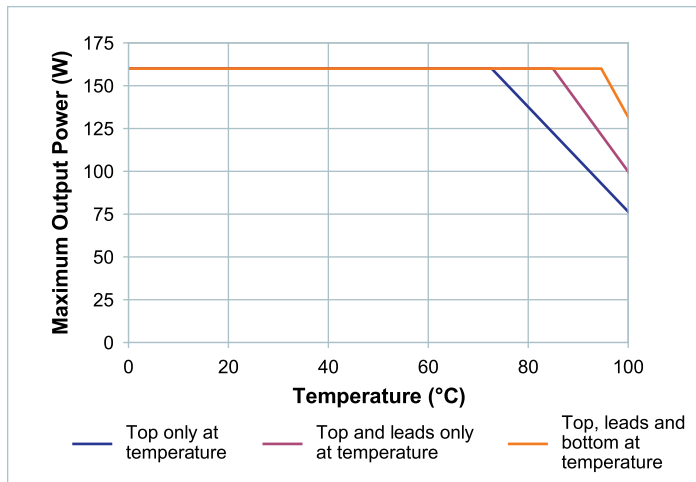


*Figure 1 —* *Thermal specified operating area: max output power vs. case temp, single unit at minimum full-load efficiency*
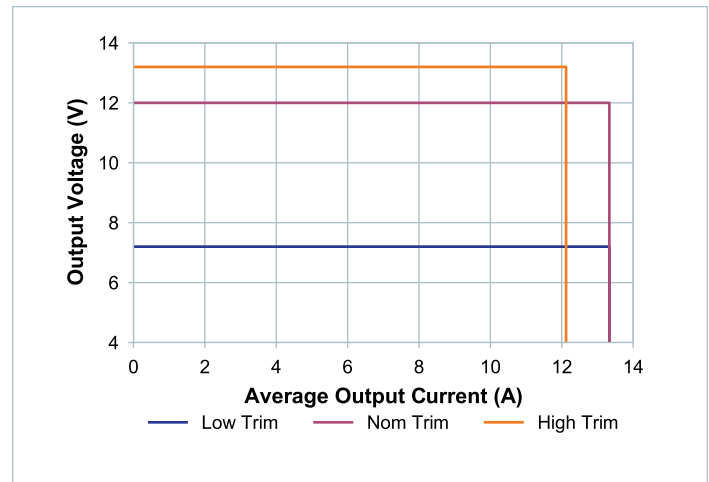


*Figure 2 —* *Electrical specified operating area; Enhanced $V_{OUT}$ Regulation Mode*

## High-Level Functional State Diagram

Conditions that cause state transitions are shown along arrows. Sub-sequence activities listed inside the state bubbles.
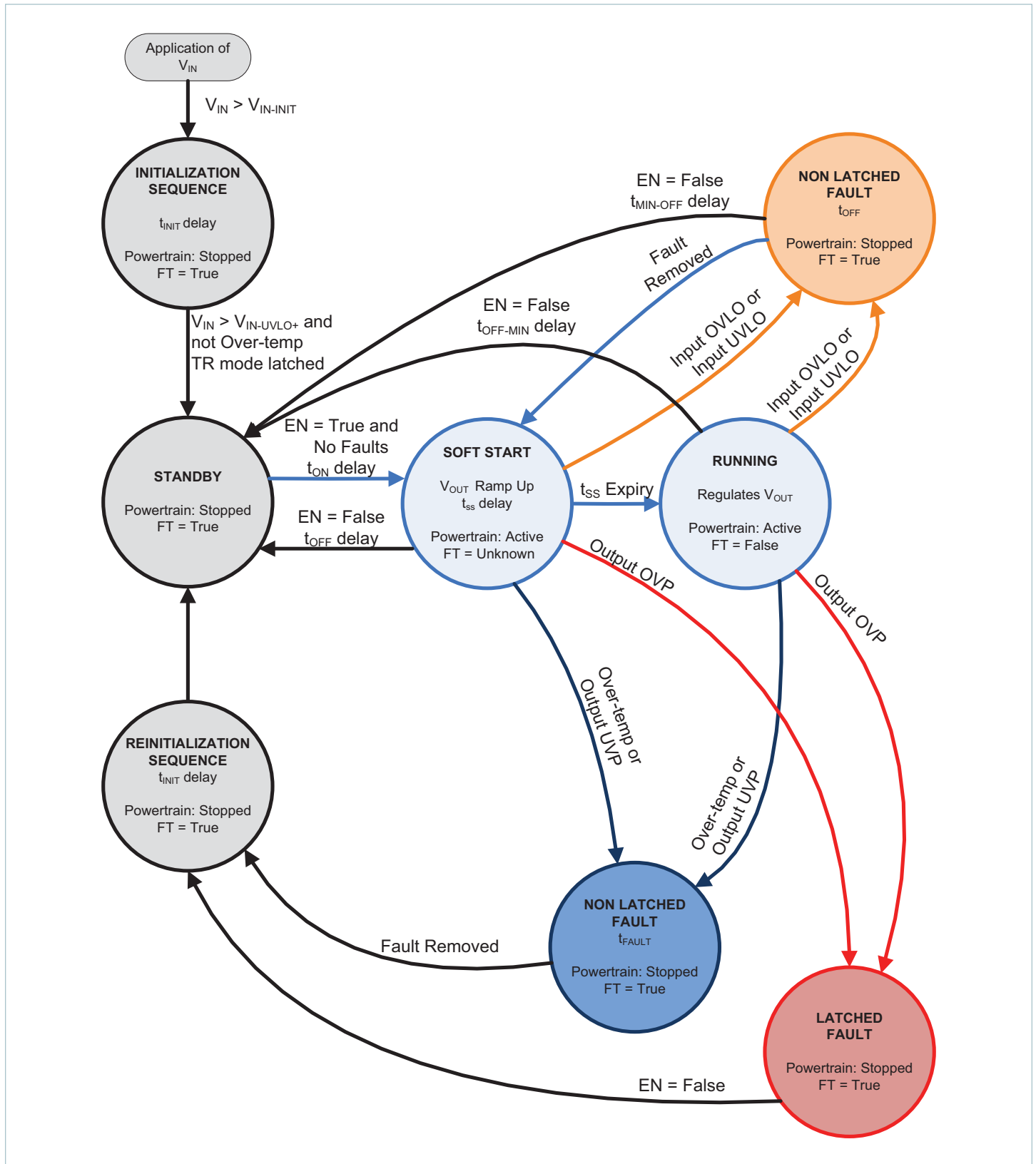
## Timing Diagrams

Module inputs are shown in blue; module outputs are shown in brown.
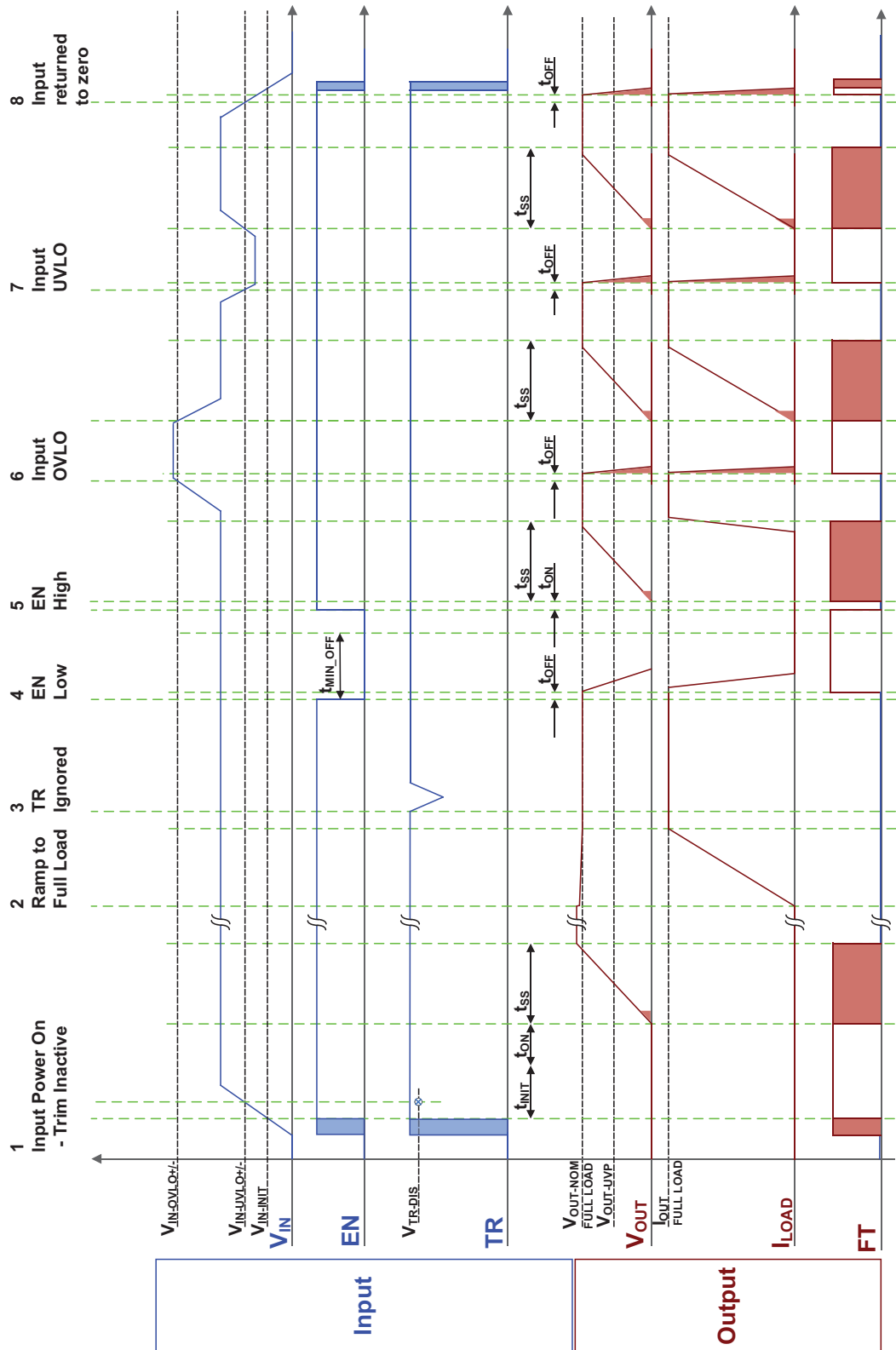
## Timing Diagrams (Cont.)

Module inputs are shown in blue; module outputs are shown in brown.
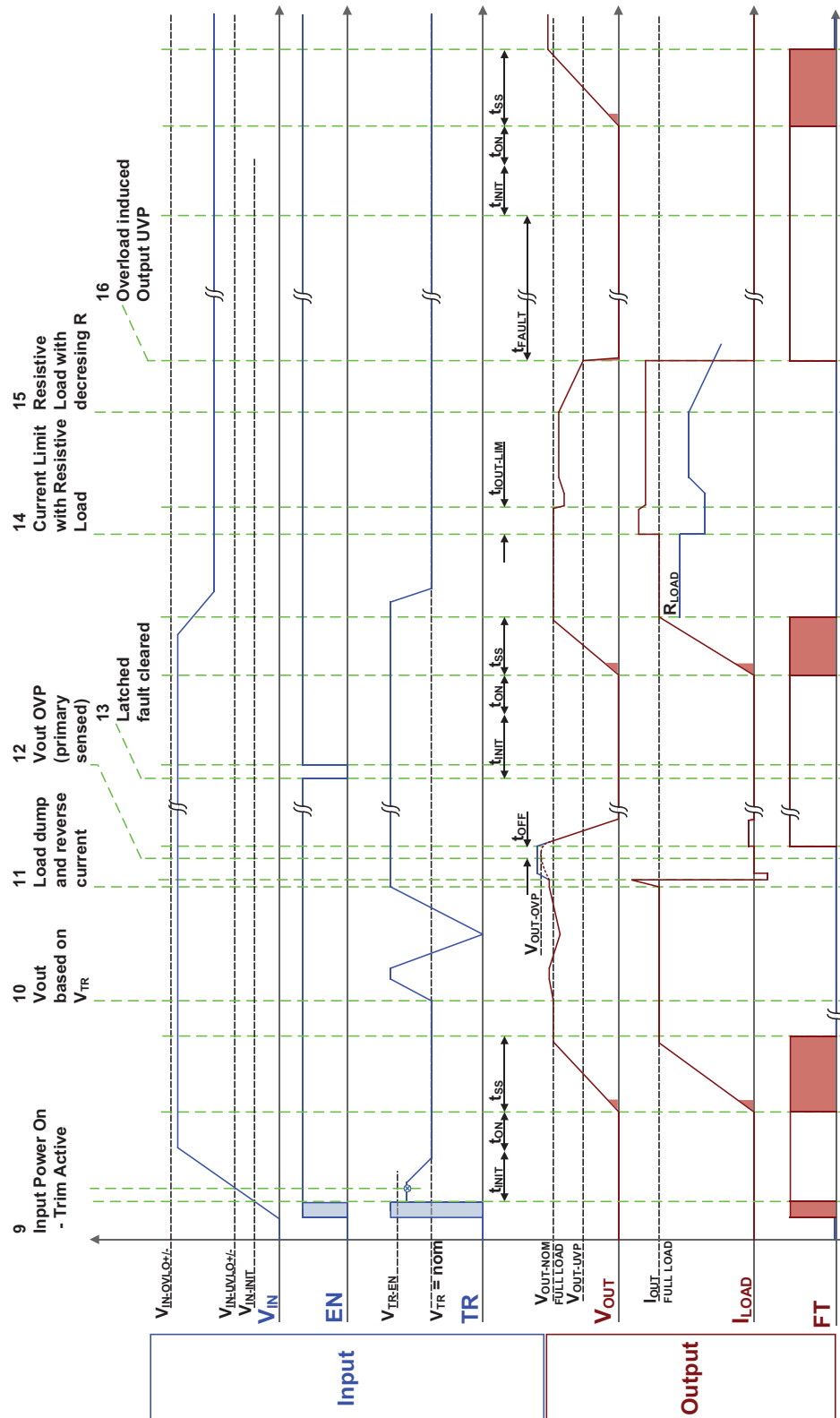
## Typical Performance Characteristics

The following figures present typical performance at $T_C = 25°C$, unless otherwise noted. See associated figures for general trend data.
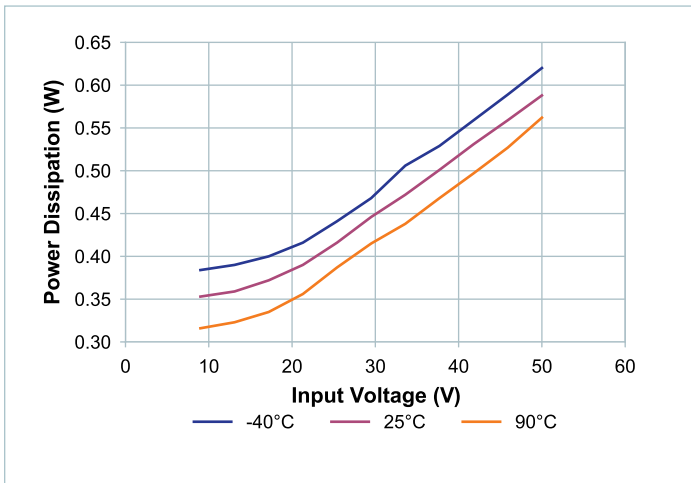


*Figure 3 — Disabled power dissipation vs. $V_{IN}$*
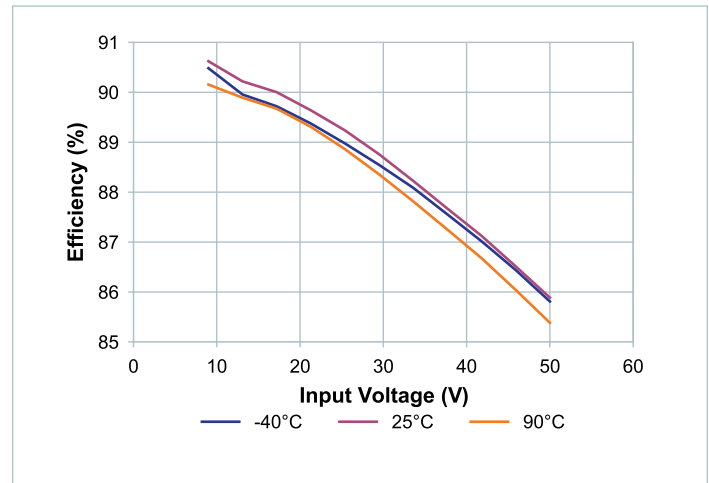


*Figure 4 — Full-load efficiency vs. $V_{IN}$, at low trim*
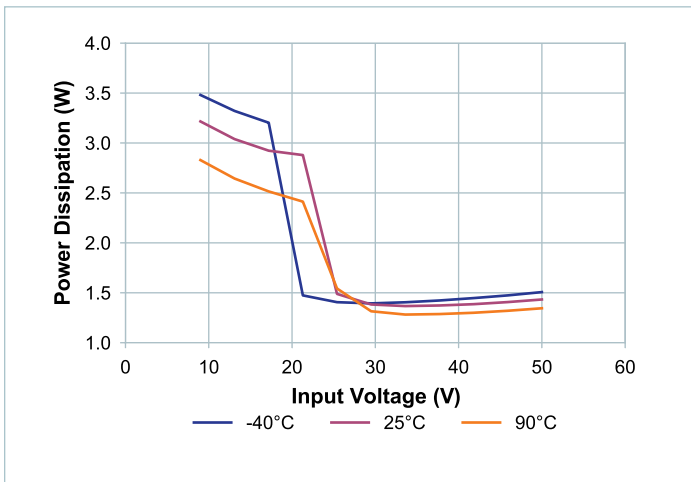


*Figure 5 — No-load power dissipation vs. $V_{IN}$, at nominal trim*
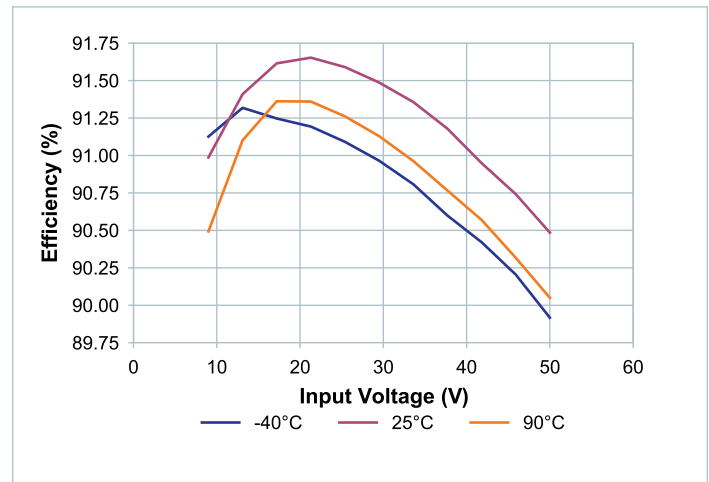


*Figure 6 — Full-load efficiency vs. $V_{IN}$, at nominal trim*
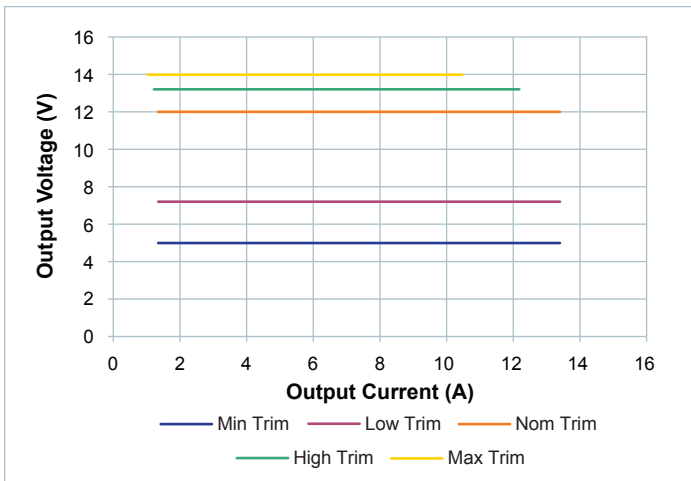


*Figure 7 — Ideal $V_{OUT}$ vs. load current, at 25°C case*
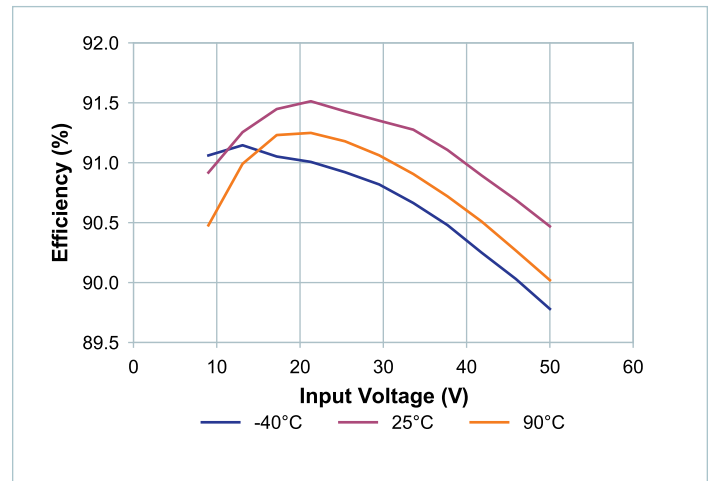


*Figure 8 — Full-load efficiency vs. $V_{IN}$, at high trim*

## Typical Performance Characteristics (Cont.)

The following figures present typical performance at $T_C$ = 25°C, unless otherwise noted. See associated figures for general trend data.
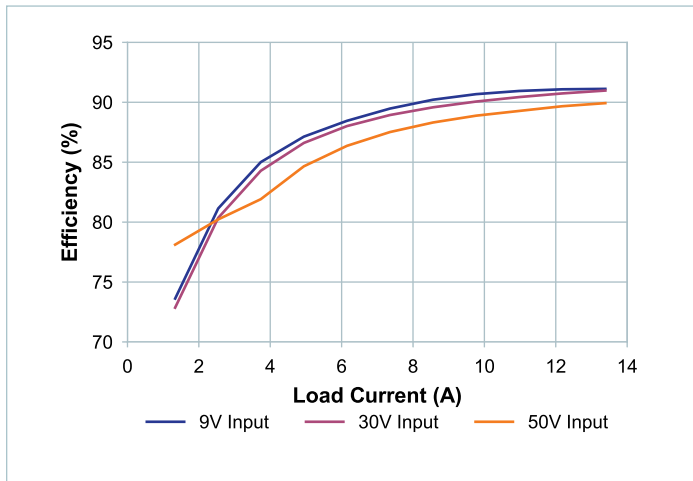


Figure 9 — *Efficiency vs. load at $T_{CASE}$ = -40°C, nominal trim*
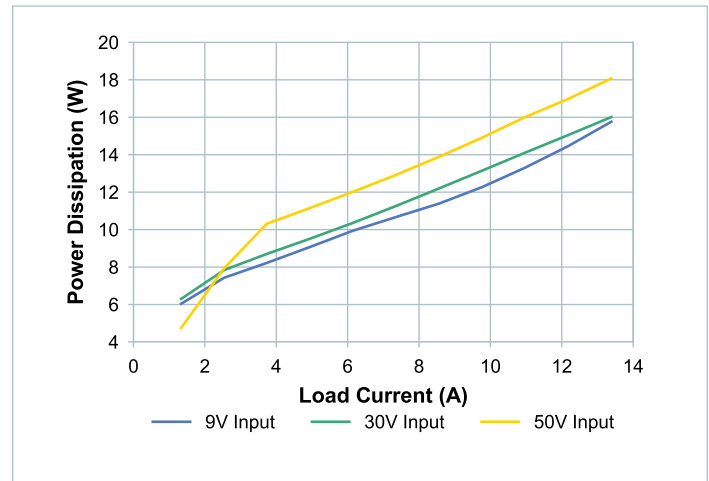


Figure 10 — *Power dissipation vs. load at $T_{CASE}$ = -40°C, nominal trim*
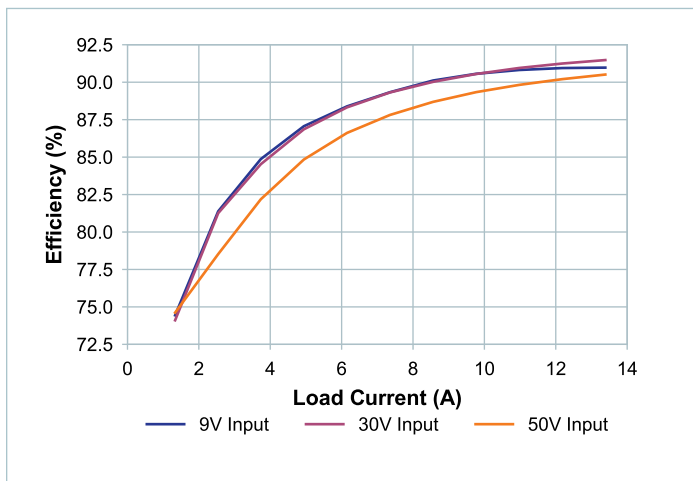


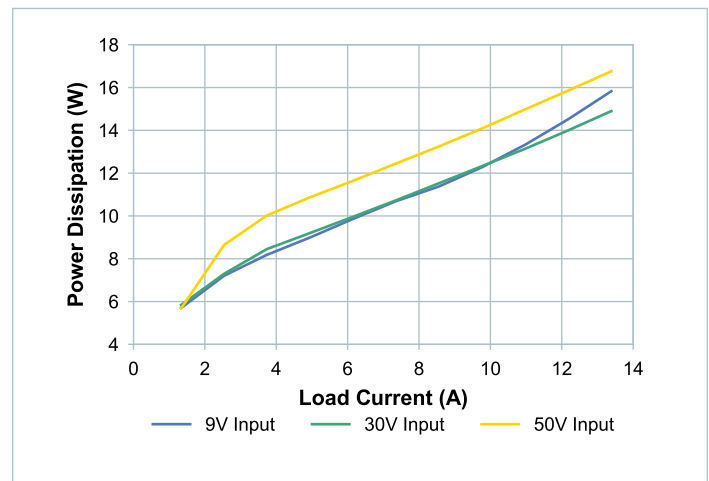Figure 11 — *Efficiency vs. load at $T_{CASE}$ = 25°C, nominal trim*



Figure 12 — *Power dissipation vs. load at $T_{CASE}$ = 25°C, nominal trim*
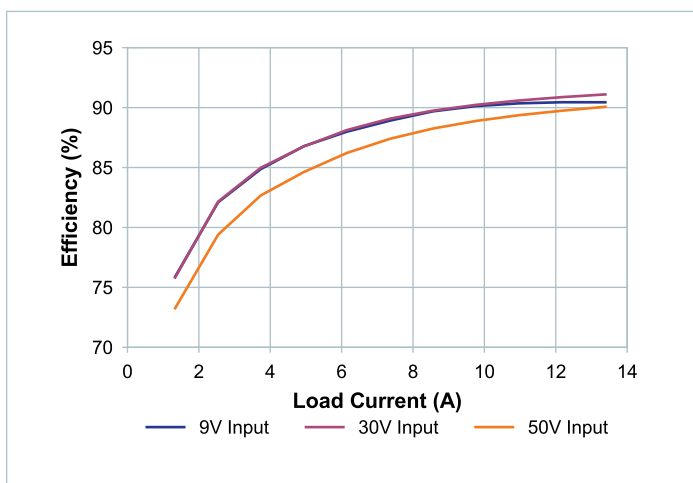


Figure 13 — *Efficiency vs. load at $T_{CASE}$ = 90°C, nominal trim*
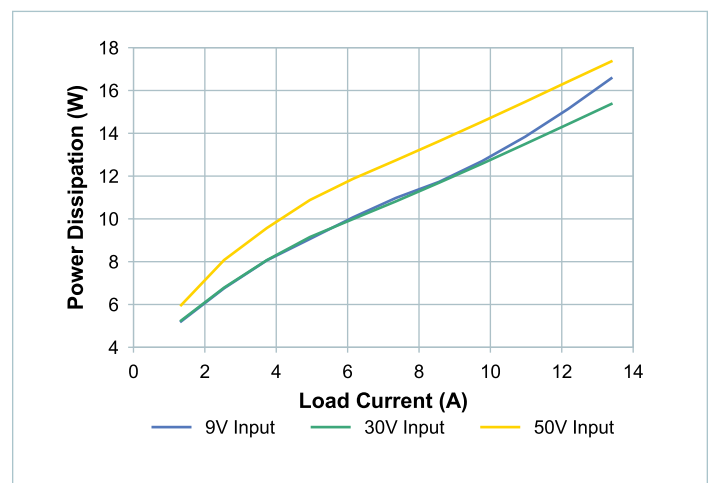


Figure 14 — *Power dissipation vs. load at $T_{CASE}$ = 90°C, nominal trim*

## Typical Performance Characteristics (Cont.)

The following figures present typical performance at $T_C$ = 25°C, unless otherwise noted. See associated figures for general trend data.
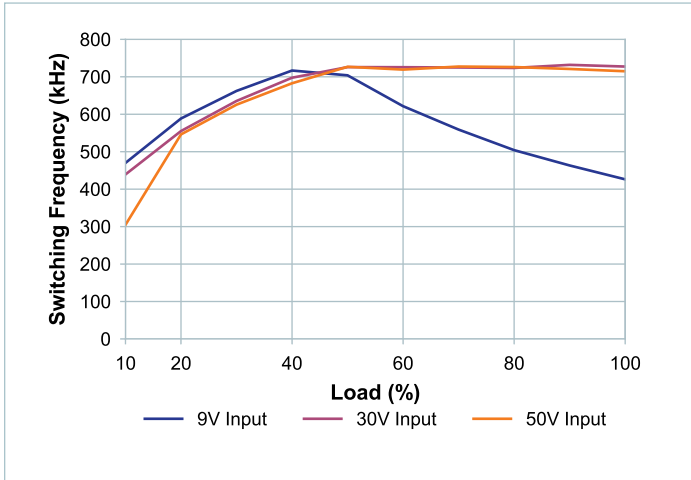


*Figure 15* — *Nominal powertrain switching frequency vs. load, at nominal trim*
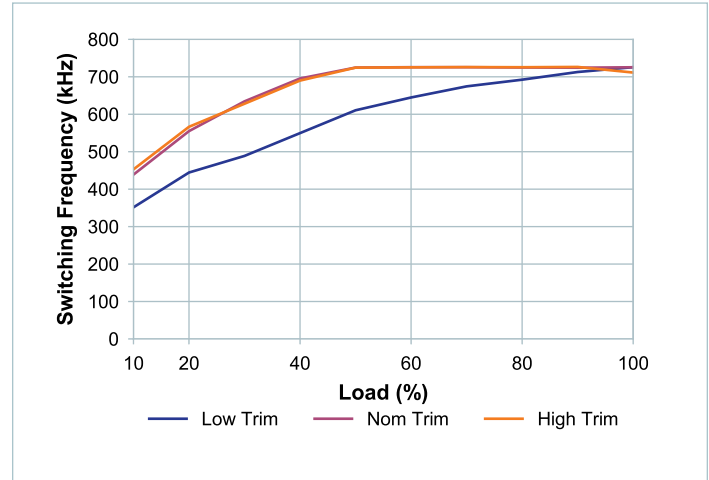


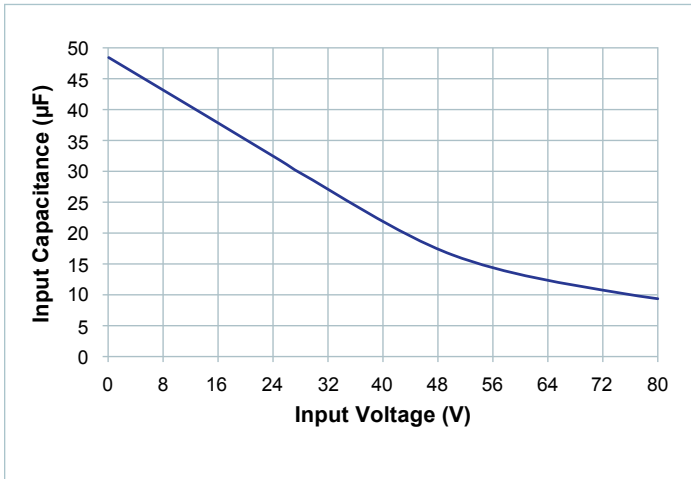*Figure 16* — *Nominal powertrain switching frequency vs. load, at nominal $V_{IN}$*



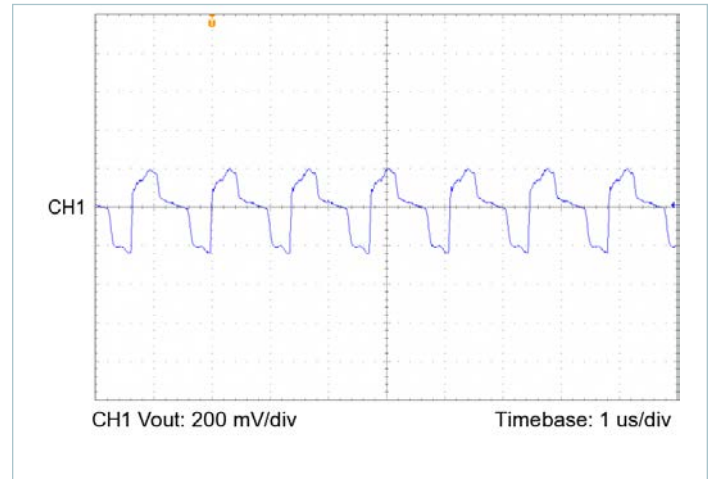*Figure 17* — *Effective internal input capacitance vs. applied voltage*



*Figure 18* — *Output voltage ripple, $V_{IN}$ = 30V, $V_{OUT}$ = 12.0V, $C_{OUT\_EXT}$ = 1000μF, $R_{LOAD}$ = 0.896Ω*
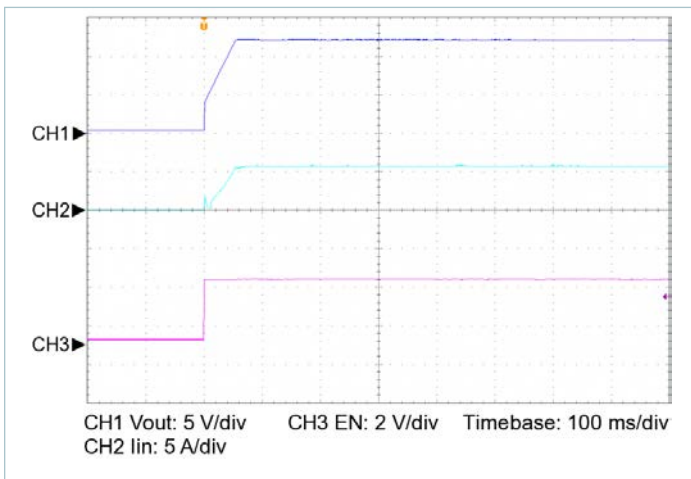


*Figure 19* — *Start up from EN, $V_{IN}$ = 30V, $C_{OUT\_EXT}$ = 10000μF, $R_{LOAD}$ = 0.896Ω*

## Pin Functions

### +IN, –IN

Input power pins. –IN is the reference for all control pins, and therefore a Kelvin connection for the control signals is recommended as close as possible to the pin on the package, to reduce effects of voltage drop due to –IN currents.

### +OUT, –OUT

Output power pins.

### EN (Enable)

This pin enables and disables the DCM converter; when held low the unit will be disabled. It is referenced to the –IN pin of the converter. The EN pin has an internal pull-up to $V_{CC}$ through a 10kΩ resistor.

- Output enable: When EN is allowed to pull up above the enable threshold, $V_{ENABLE-EN-TH}$, the module will be enabled. If leaving EN floating, it is pulled up to $V_{CC}$ and the module will be enabled.

- Output disable: EN may be pulled down externally below $V_{ENABLE-DIS-TH}$ in order to disable the module.

- EN is an input only, it does not pull low in the event of a fault.

### TR (Trim)

The TR pin is used to select the trim mode and to trim the output voltage of the DCM converter. The TR pin has an internal pull-up to $V_{CC}$ through a 10.0kΩ resistor.

The DCM will latch trim behavior at application of $V_{IN}$ (once $V_{IN}$ exceeds $V_{IN-UVLO+}$), and persist in that same behavior until loss of input voltage

- At application of $V_{IN}$, if TR is sampled at above $V_{TRIM-DIS-TH}$, the module will latch in a non-trim mode, and will ignore the TR input for as long as $V_{IN}$ is present.

- At application of $V_{IN}$, if TR is sampled at below $V_{TRIM-EN-TH}$, the TR will serve as an input to control the real time output voltage, relative to full load, 25°C. It will persist in this behavior until $V_{IN}$ is no longer present.

If trim is active when the DCM is operating, the TR pin provides dynamic trim control at a typical 30Hz of –3dB bandwidth over the output voltage. TR also decreases the current limit threshold when trimming above $V_{OUT-NOM}$.

### FT (Fault)

The FT pin provides a Fault signal.

Any time the module is enabled and has not recognized a fault, the FT pin is inactive. FT has an internal 499kΩ pull-up to $V_{CC}$, therefore a shunt resistor, $R_{SHUNT}$, of approximately 50kΩ can be used to ensure the LED is completely off when there is no fault, per the diagram below.

Whenever the powertrain stops (due to a fault protection or disabling the module by pulling EN low), the FT pin becomes active and provides current to drive an external circuit.

When active, FT pin drives to $V_{CC}$, with up to 4mA of external loading. Module may be damaged from an overcurrent FT drive, thus a resistor in series for current limiting is recommended.

The FT pin becomes active momentarily when the module starts up.

## Typical External Circuits for Signal Pins (TR, EN, FT)
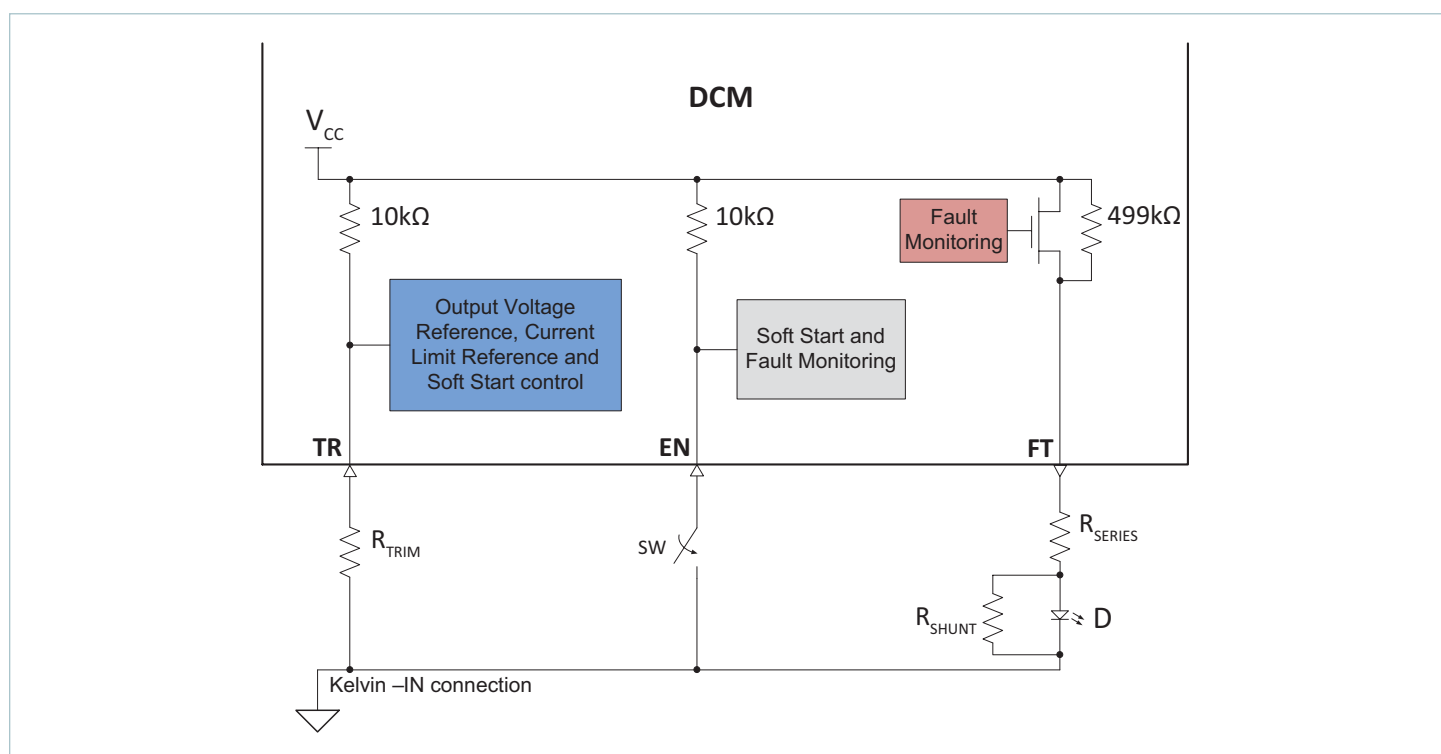
# Design Guidelines

## Building Blocks and System Design

The DCM converter input accepts the full 9 – 50V range, and it generates an isolated trimmable $12.0V_{DC}$ output.

The DCM converter provides a tightly regulated output voltage; please refer to the Output Voltage Load Regulation specification in the Electrical Specifications table.

The DCM3623x50T13A6y7z is designed to be used in applications where the output power requirements are up to 160W.

## Soft Start

When the DCM starts, it will go through a soft start. The soft-start routine ramps the output voltage by modulating the internal error amplifier reference. This causes the output voltage to approximate a piecewise linear ramp. The output ramp finishes when the voltage reaches either the nominal output voltage, or the trimmed output voltage in cases where trim mode is active.

During soft start, the maximum load current capability is reduced. Until $V_{OUT}$ achieves at least $V_{OUT-FL-THRESH}$, the output current must be less than $I_{OUT-START}$ in order to guarantee start up. Note that this is current available to the load, above that which is required to charge the output capacitor.

## Trim Mode and Output Trim Control

When the input voltage is initially applied to a DCM, and after $t_{INIT}$ elapses, the trim pin voltage $V_{TR}$ is sampled. The TR pin has an internal pull up resistor to $V_{CC}$, so unless external circuitry pulls the pin voltage lower, it will pull up to $V_{CC}$. If the initially sampled trim pin voltage is higher than $V_{TRIM-DIS-TH}$, then the DCM will disable trimming as long as the $V_{IN}$ remains applied. In this case, for all subsequent operation the output voltage will be programmed to the nominal. This minimizes the support components required for applications that only require the nominal rated $V_{OUT}$, and also provides the best output set-point accuracy, as there are no additional errors from external trim components.

If at initial application of $V_{IN}$, the TR pin voltage is prevented from exceeding $V_{TRIM-EN-TH}$, then the DCM will activate trim mode, and it will remain active for as long as $V_{IN}$ is applied.

$V_{OUT}$ set point under full load and room temperature can be calculated using the equation below:

$$V_{OUT-FL} \text{ at } 25°C = 4.99 + (9.390 • V_{TR} / V_{CC}) \qquad (1)$$

Or using the online tool, DCM Trim Calculator, find the value of $V_{TR}$ or trim resistor to set the desired $V_{OUT}$.

Note that the trim mode is not changed when a DCM recovers from any fault condition or being disabled.

Module performance is guaranteed through output voltage trim range $V_{OUT-TRIMMING}$. If $V_{OUT}$ is trimmed above this range, then certain combinations of line and load transient conditions may trigger the output OVP.

## Overall Output Voltage Transfer Function

Taking trim (Equation 1) into account, the general equation relating the DC $V_{OUT}$ to programmed trim (when active), load and temperature is given by:

$$V_{OUT} = 4.99 + (9.390 • V_{TR} / V_{CC}) + \Delta V_{OUT-LL} \qquad (2)$$

Finally, note that when the load current is below 10% of the rated capacity, there is an additional $\Delta V$ which may add to the output voltage, depending on the line voltage which is related to light-load boosting. Please see the section on light-load boosting below for details.

Use 0V for $\Delta V_{OUT-LL}$ when load is above 10% of rated load. See section on light-load boosting operation for light-load effects on output voltage.

## Output Current Limit

The DCM features a fully operational current limit which effectively keeps the module operating inside the Safe Operating Area (SOA) for all valid trim and load profiles. The current limit approximates a "brick wall" limit, where the output current is prevented from exceeding the current limit threshold by reducing the output voltage via the internal error amplifier reference. The current limit threshold at nominal trim and below is typically 120% of rated output current, but it can vary between 100% to 150%. In order to preserve the SOA, when the converter is trimmed above the nominal output voltage, the current limit threshold is automatically reduced to limit the available output power.

When the output current exceeds the current limit threshold, current limit action is held off by 1ms, which permits the DCM to momentarily deliver higher peak output currents to the load. Peak output power during this time is still constrained by the internal Power Limit of the module. The fast Power Limit and relatively slow Current Limit work together to keep the module inside the SOA. Delaying entry into current limit also permits the DCM to minimize droop voltage for load steps.

Sustained operation in current limit is permitted, and no de-rating of output power is required.

Some applications may benefit from well matched current distribution, in which case fine tuning sharing via the trim pins permits control over sharing. The DCM does not require this for proper operation, due to the power limit and current limit behaviors described here.

Current limit can reduce the output voltage to as little as the UVP threshold ($V_{OUT-UVP}$). Below this minimum output voltage compliance level, further loading will cause the module to shut down due to the output undervoltage fault protection.

**Line Impedance, Input Slew Rate and Input Stability Requirements**

Connect a high-quality, low-noise power supply to the +IN and –IN terminals. Additional capacitance may have to be added between +IN and –IN to make up for impedances in the interconnect cables as well as deficiencies in the source.

Excessive source impedance can bring about system stability issues for a regulated DC-DC converter, and must either be avoided or compensated by filtering components. A 1000µF input capacitor is the minimum recommended in case the source impedance is insufficient to satisfy stability requirements.

For selecting optimum value of decoupling capacitor, refer to section 2 of the DCM Design Guide.

Additional information can be found in the filter design application note AN:023.

Please refer to this input filter design tool to ensure input stability.

Ensure that the input voltage slew rate is less than 1V/µs, otherwise a pre-charge circuit is required for the DCM input to control the input voltage slew rate and prevent overstress to input-stage components.

**Input Fuse Selection**

The DCM is not internally fused in order to provide flexibility in configuring power systems. Input line fusing is recommended at the system level, in order to provide thermal protection in case of catastrophic failure. The fuse shall be selected by closely matching system requirements with the following characteristics:

- Current rating
  (usually greater than the DCM converter's maximum current)

- Maximum voltage rating
  (usually greater than the maximum possible input voltage)

- Ambient temperature

- Breaking capacity per application requirements

- Nominal melting I²t

- Recommended fuse:
  See Safety Approvals for recommended fuse

**Fault Handling**

*Input Undervoltage Fault Protection (UVLO)*

The converter's input voltage is monitored to detect an input under voltage condition. If the converter is not already running, then it will ignore enable commands until the input voltage is greater than $V_{IN-UVLO+}$. If the converter is running and the input voltage falls below $V_{IN-UVLO-}$, the converter recognizes a fault condition, the powertrain stops switching, and the output voltage of the unit falls.

Input voltage transients which fall below UVLO for less than $t_{UVLO}$ may not be detected by the fault protection logic, in which case the converter will continue regular operation. No protection is required in this case.

Once the UVLO fault is detected by the fault protection logic, the converter shuts down and waits for the input voltage to rise above $V_{IN-UVLO+}$. Provided the converter is still enabled, it will then restart.

*Input Overvoltage Fault Protection (OVLO)*

The converter's input voltage is monitored to detect an input overvoltage condition. When the input voltage is more than the $V_{IN-OVLO+}$, a fault is detected, the powertrain stops switching, and the output voltage of the converter falls.

After an OVLO fault occurs, the converter will wait for the input voltage to fall below $V_{IN-OVLO-}$. Provided the converter is still enabled, the powertrain will restart.

The powertrain controller itself also monitors the input voltage. Transient OVLO events which have not yet been detected by the fault sequence logic may first be detected by the controller if the input slew rate is sufficiently large. In this case, powertrain switching will immediately stop. If the input voltage falls back in range before the fault sequence logic detects the out of range condition, the powertrain will resume switching and the fault logic will not interrupt operation. Regardless of whether the powertrain is running at the time or not, if the input voltage does not recover from OVLO before $t_{OVLO}$, the converter fault logic will detect the fault.

*Output Undervoltage Fault Protection (UVP)*

The converter determines that an output overload or short circuit condition exists by measuring its primary sensed output voltage and the output of the internal error amplifier. In general, whenever the powertrain is switching and the primary-sensed output voltage falls below $V_{OUT-UVP}$ threshold, a short circuit fault will be registered. Once an output undervoltage condition is detected, the powertrain immediately stops switching, and the output voltage of the converter falls. The converter remains disabled for a time $t_{FAULT}$. Once recovered and provided the converter is still enabled, the powertrain will again enter the soft-start sequence after $t_{INIT}$ and $t_{ON}$.

*Temperature Fault Protections (OTP)*

The fault logic monitors the internal temperature of the converter. If the measured temperature exceeds $T_{INT-OTP}$, a temperature fault is registered. As with the undervoltage fault protection, once a temperature fault is registered, the powertrain immediately stops switching, the output voltage of the converter falls, and the converter remains disabled for at least time $t_{FAULT}$. Then, the converter waits for the internal temperature to return to below $T_{INT-OTP}$ before recovering. Provided the converter is still enabled, the DCM will restart after $t_{INIT}$ and $t_{ON}$.

*Output Overvoltage Fault Protection (OVP)*

The converter monitors the output voltage during each switching cycle by a corresponding voltage reflected to the primary side control circuitry. If the primary sensed output voltage exceeds $V_{OUT-OVP}$, the OVP fault protection is triggered. The control logic disables the powertrain, and the output voltage of the converter falls.

This type of fault is latched, and the converter will not start again until the latch is cleared. Clearing the fault latch is achieved by either disabling the converter via the EN pin, or else by removing the input power such that the input voltage falls below $V_{IN-INIT}$.

## External Output Capacitance

The DCM converter internal compensation requires a minimum external output capacitor. An external capacitor in the range of 1000 – 10000µF with ESR of 10mΩ is required, per DCM for control loop compensation purposes.

However, some DCM models require an increase in the minimum external output capacitor value in certain loading and trim conditions. In applications where the load can go below 10% of rated load but the output trim is held constant, the range of output capacitor required is given by $C_{OUT-EXT-TRANS}$ in the Electrical Specifications table. If the load can go below 10% of rated load and the DCM output trim is also dynamically varied, the range of output capacitor required is given by $C_{OUT-EXT-TRANS-TRIM}$ in the Electrical Specifications table.

## Light-Load Boosting

Under light-load conditions, the DCM converter may operate in light-load boosting depending on the line voltage. Light-load boosting occurs whenever the internal power consumption of the converter combined with the external output load is less than the minimum power transfer per switching cycle. In order to maintain regulation, the error amplifier will switch the powertrain off and on repeatedly, to effectively lower the average switching frequency, and permit operation with no external load. During the time when the powertrain is off, the module internal consumption is significantly reduced, and so there is a notable reduction in no-load input power in light-load boosting. When the load is less than 10% of rated $I_{OUT}$, the output voltage may rise by a maximum of 2.40V, above the output voltage calculated from trim, temperature and load line conditions.

## Thermal Considerations

Based on the thermal specified operating area shown on page 9, the full rated power of the DCM3623x50T13A6y7z can be processed provided that the top, bottom and leads are all held below 95°C. These curves highlight the benefits of dual-sided thermal management, but also demonstrate the flexibility of the Vicor ChiP™ platform for customers who are limited to cooling only the top or the bottom surface.

The OTP sensor is located on the top side of the internal PCB structure. Therefore in order to ensure effective overtemperature fault protection, the case bottom temperature must be constrained by the thermal solution such that it does not exceed the temperature of the case top.

The ChiP package provides a high degree of flexibility in that it presents three pathways to remove heat from internal power dissipating components. Heat may be removed from the top surface, the bottom surface and the leads. The extent to which these three surfaces are cooled is a key component for determining the maximum power that is available from a ChiP, as can be seen from Figure 20.

Since the ChiP has a maximum internal temperature rating, it is necessary to estimate this internal temperature based on a real thermal solution. Given that there are three pathways to remove heat from the ChiP, it is helpful to simplify the thermal solution into a roughly equivalent circuit where power dissipation is modeled as a current source, isothermal surface temperatures are represented as voltage sources and the thermal resistances are represented as resistors. Figure 20 shows the "thermal circuit" for a DCM3623 ChiP, in an application where both case top and case bottom, and leads are cooled. In this case, the DCM power dissipation is $PD_{TOTAL}$ and the three surface temperatures are represented as $T_{CASE\_TOP}$, $T_{CASE\_BOTTOM}$, and $T_{LEADS}$. This thermal system can now be very easily analyzed with simple resistors, voltage sources, and a current source.

This analysis provides an estimate of heat flow through the various pathways as well as internal temperature.
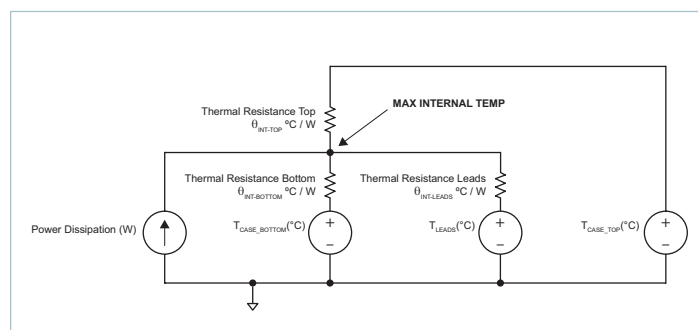


***Figure 20*** *— Double-side cooling and leads thermal model*

Alternatively, equations can be written around this circuit and analyzed algebraically:

$$T_{INT} - PD_1 \cdot \theta_{INT\text{-}TOP} = T_{CASE\_TOP}$$

$$T_{INT} - PD_2 \cdot \theta_{INT\text{-}BOTTOM} = T_{CASE\_BOTTOM}$$

$$T_{INT} - PD_3 \cdot \theta_{INT\text{-}LEADS} = T_{LEADS}$$

$$PD_{TOTAL} = PD_1 + PD_2 + PD_3$$

Where $T_{INT}$ represents the internal temperature and $PD_1$, $PD_2$, and $PD_3$ represent the heat flow through the top side, bottom side, and leads respectively.
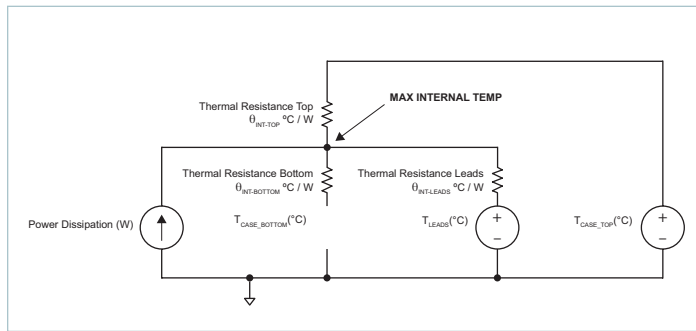


***Figure 21*** — *One-side cooling and leads thermal model*

Figure 21 shows a scenario where there is no bottom side cooling. In this case, the heat flow path to the bottom is left open and the equations now simplify to:

$$T_{INT} - PD_1 \cdot \theta_{INT\text{-}TOP} = T_{CASE\_TOP}$$

$$T_{INT} - PD_3 \cdot \theta_{INT\text{-}LEADS} = T_{LEADS}$$
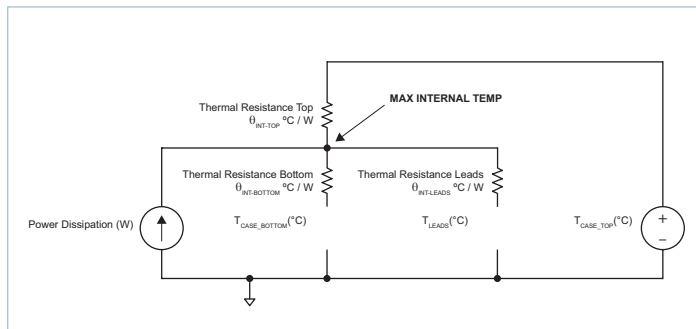
$$PD_{TOTAL} = PD_1 + PD_3$$



***Figure 22*** — *One-side cooling thermal model*

Figure 22 shows a scenario where there is no bottom side and leads cooling. In this case, the heat flow path to the bottom is left open and the equations now simplify to:

$$T_{INT} - PD_1 \cdot \theta_{INT\text{-}TOP} = T_{CASE\_TOP}$$

$$PD_{TOTAL} = PD_1$$

Vicor provides a suite of online tools, including a simulator and thermal estimator which greatly simplify the task of determining whether or not a DCM thermal configuration is sufficient for a given condition. These tools can be found at: www.vicorpower.com/powerbench.

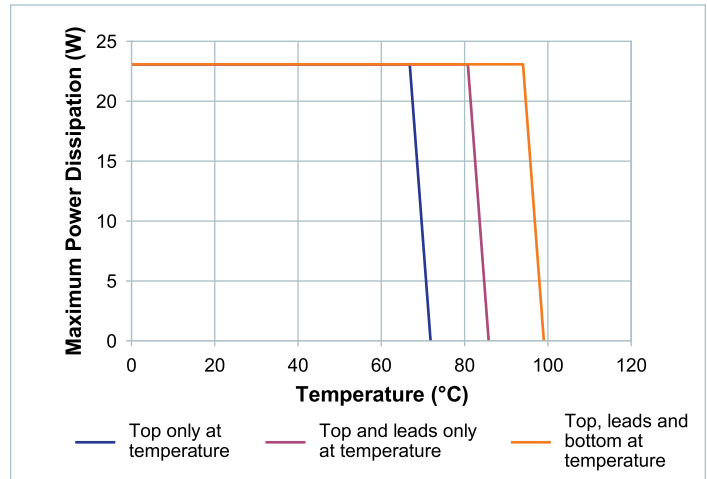| Symbol | Thermal Impedance (°C/W) | Definition of Estimated Thermal Resistance |
|---|---|---|
| $\theta_{INT\text{-}TOP}$ | 2.0 | to maximum-temperature internal component from isothermal top |
| $\theta_{INT\text{-}LEADS}$ | 4.4 | to maximum-temperature internal component from isothermal leads |
| $\theta_{INT\text{-}BOTTOM}$ | 2.4 | to maximum-temperature internal component from isothermal bottom |
| **Thermal Capacity** | | |
| 17.7Ws/°C | | |

***Table 1*** — *Thermal data*



***Figure 23*** — *Thermal specified operating area: max power dissipation vs. case temp for arrays or current-limited operation*

## Standalone Operation

The following Figure 24 shows the configuration of the Enhanced $V_{OUT}$ DCM. An input filter is required to attenuate noise coming from the input source. In case of the excessive line inductance, a properly-sized decoupling capacitor $C_{DECOUPLE}$ is required as shown in the following figure.

If signal pins (TR, EN, FT) are not used, they can be left floating, and DCM will work in the nominal output condition.

When common-mode noise in the input side is not a concern, TR and EN can be driven and FT received using –IN as a reference.

### Filter components

**Input filter:** The choice of the input filter components varies up on the low line and maximum output power of the DCM. Refer to the Filtering Guidelines Introduction section in the DCM Design Guide to design an input filter.

**Output filter:**

| Reference Designator | Value | Mfg. Part Number & Count/DCM |
|---|---|---|
| $C_2$ | 80µF | GRM32EC72A106KE05L, #8 |
| $L_2$ | 0.33µH | 744309033, #1 |
| $R_{dm}$ | 0.05Ω | RL2512FK-070R05L, #1 |
| $L_{b1}$ | 72nH | IFLR2727EZER72NM01, #1 |

$C_{OUT-EXT}$: electrolytic or tantalum capacitor, 1000µF $\leq C_3 \leq$ 10000µF;

$C_3, C_4$: additional ceramic /electrolytic capacitors, if needed for output ripple filtering;

*In order to help sensitive signal circuits reject potential noise, additional components are recommended:*
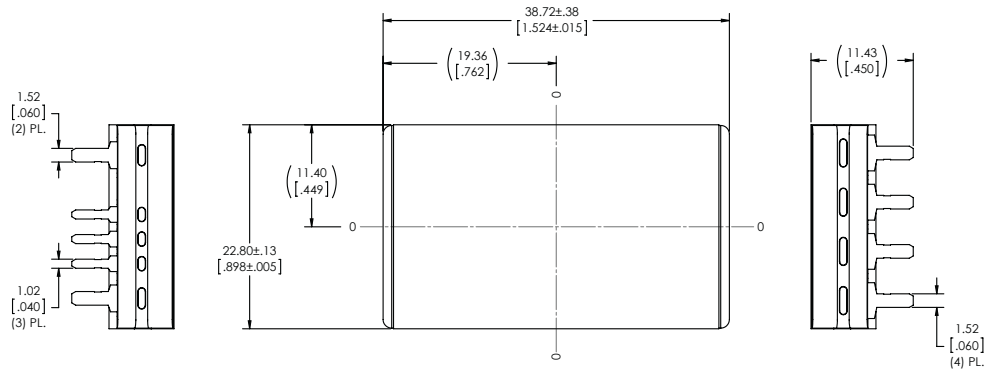
$R_2$: 301Ω, facilitate noise attenuation for TR pin;

$FB_1, C_5$: $FB_1$ is a ferrite bead with an impedance of at least 10Ω at 100MHz. $C_5$ can be a ceramic capacitor of 0.1µF. Facilitate noise attenuation for EN pin.
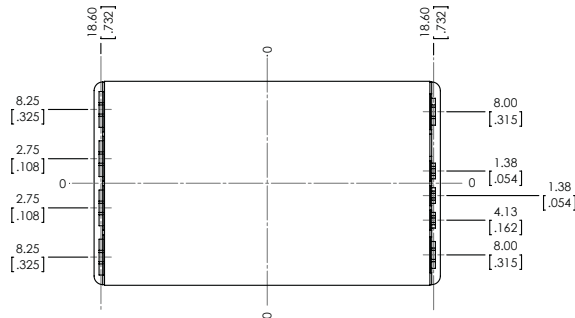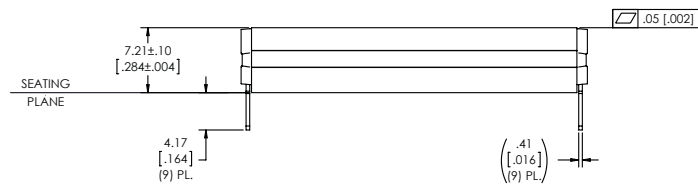
Note: Use an RCR filter network as suggested in the application note AN:030 to reduce the noise on the signal pins.



**Figure 24** — *Enhanced $V_{OUT}$ DCM configuration circuit*

## DCM Module Product Outline Drawing Recommended PCB Footprint and Pinout

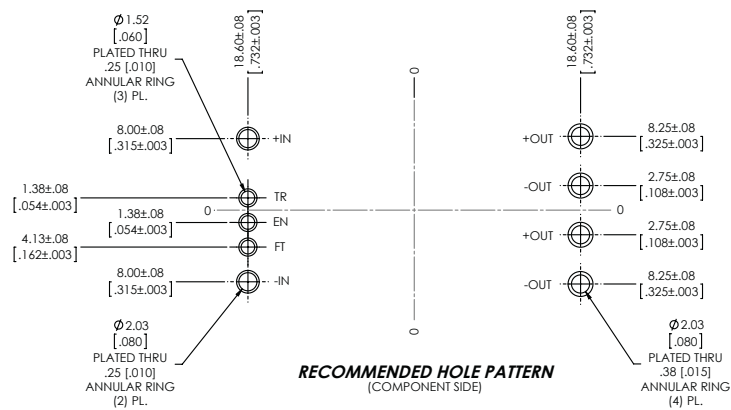*3623 THRU HOLE*
(Reference DWG # 40260 Rev 5)

**TOP VIEW (COMPONENT SIDE)**

**BOTTOM VIEW**

**RECOMMENDED HOLE PATTERN**
(COMPONENT SIDE)

Ø1.52 [.060] PLATED THRU .25 [.010] ANNULAR RING (3) PL.

Ø2.03 [.080] PLATED THRU .25 [.010] ANNULAR RING (2) PL.

Ø2.03 [.080] PLATED THRU .38 [.015] ANNULAR RING (4) PL.

+IN
TR
EN
FT
-IN

+OUT
-OUT
+OUT
-OUT

8.00±.08 [.315±.003]
1.38±.08 [.054±.003]
1.38±.08 [.054±.003]
4.13±.08 [.162±.003]
8.00±.08 [.315±.003]
18.60±.08 [.732±.003]
18.60±.08 [.732±.003]

8.25±.08 [.325±.003]
2.75±.08 [.108±.003]
2.75±.08 [.108±.003]
8.25±.08 [.325±.003]

NOTES:
1- UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE MM [INCH]
2- TOLERANCES ARE:
   DECIMALS
      X.XX [X.XX] = ±0.25 [0.01]
      X.XXX [X.XXX] = ±0.127 [0.005]
   ANGLES = ±1°

## Revision History

| Revision | Date | Description | Page Number(s) |
|---|---|---|---|
| 1.0 | 12/15/17 | Initial release | N/A |
| 1.1 | 01/27/20 | Output voltage regulation specification format change<br>Updated state and timing diagrams<br>Updated trim descriptions and typical external circuits diagram | 5<br>8 - 10<br>16, 17 |
| 1.2 | 07/03/24 | Updated agency approvals<br>Added insulation resistance specification<br>Updated format, pages added<br>Updated typical applications<br>Revised thermal specified operating area<br>Revised switching frequency presentation<br>Updated standalone operation | 1, 4<br>4<br>ALL<br>2<br>9<br>15<br>21 |

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