

TCW4 CANopen

CANOPEN ABSOLUTE MULTI-TURN MODULAR



Features

- With its two-part design, the ACW4 CANopen absolute single-turn offers maximum flexibility for installation
- Rugged and excellent resistance to shock and vibration
- Robust, proven magnetic technology
- Environmentally resistanct, IP 67 standard (IP69K option)
- Extended operating range from -30° C to 85° C
- Uses universal supply 5 to 30 VDC CAN open output
- Available resolution 12 bits per turn by 16 bits of turns counting
- Variety of magnet holders available
- Standard PVC cable with SUBD9 connector

Applications

- Factory Automation
- Process Automation





Mechanical

Terminations	PVC Cable with SUBD9 connector					
Housing	Macromelt PA638					
Weight	0,150 kg					

Electrical

Electrical Angle	360°					
Output Function	CANopen					
Minimal Cycle Time	< 400μs					
Resolution	Multi-turn 12 bits per turn and up to 16 bits of turns counting					
Accuracy	+/-0.3% on 360°					
Repeatability	+/-0.1% on 360°					
Supply Voltage	5 to 30 Vdc					
Start-up	<1 s					
Current Requirements	< 40mA					
Protection	Overvoltage Protection: Yes Reverse Polarity Protection: Yes Short Circuit Protection: Yes					
EMC	IEC 61000-4-2 Electrostatic discharge (ESD) 4 kV, 8 kV IEC 61000-4-3 Electromagnetic fields 10 V/m (80MHz - 1GHz), 3V/m (1.4GHz - 2GHz), 1V/m (2GHz - 2.7GHz) IEC 61000-4-4 Electrical fast transients (burst) 1 kV IEC 61000-4-6 Conducted disturbances, induced by RF-fields 10 Veff.					





Programmable Parameters

Resolution: Defines the resolution per revolution (0 to 4 096).

Transmission Speed: Programmable from 10kBaud (1 000m) to 1 Mbaud (25 m); value per default: 20 Kbaud.

Address: Defines the software address of the encoder on the bus (1 to 127, Value per default : id = 1).

Direction: Defines the direction of count of the encoder.

RAX: Defines the value of the current position (with the shaft held stationary)

Cames: High and low limits.

Communication Modes

Sensor configuration: Reading/Writing of the sensor objects dictionary (SDO mode).

3 modes are available to interrogate the encoder position/speed:

CYCLIC Mode: The sensor transmits its position in an asynchronous manner. The frequency of the transmission is defined by the programmable cyclic timer register

from 0 to 65 535 ms.

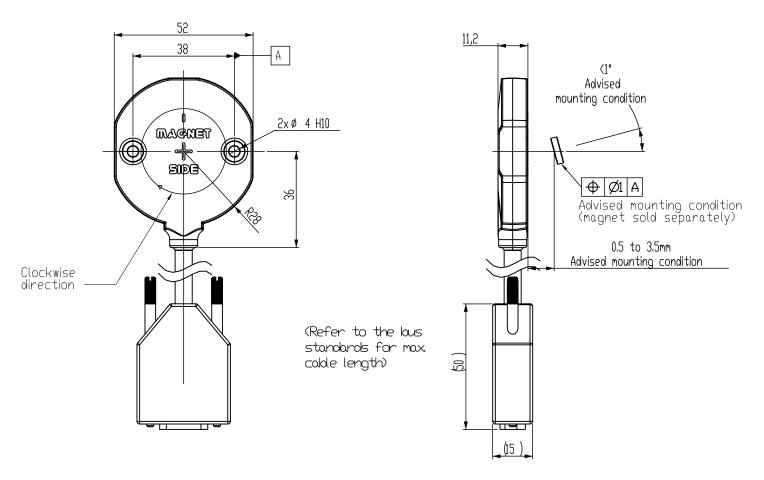
SYNCHRO Mode: The Sensor transmits its position on a synchronous demand by the master.

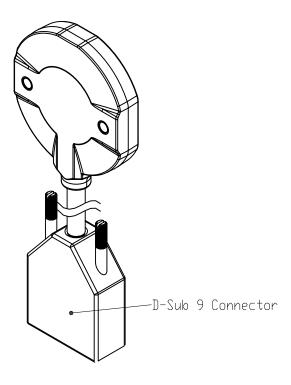
POOLING Mode (Answer to a RTR signal): The sensor only answers to a request.



All Dimensions are in millimeters.

Shaft system with magnet to be ordered separately (see Accessories).







CANOPEN CONNECTION, CABLE + DB9 CONNECTOR

		N.C	CAN LOW	CAN GND / OV	N.C.	N.C.	OV	CAN HIGH	N.C.	5/30Vdc	Ground
BB	PVC Cable + DB9	1	2	3	4	5	6	7	8	9	General Shielding

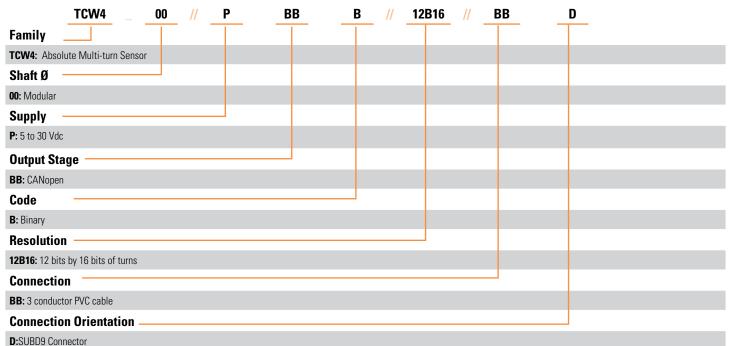


Stray magnetic fields can interfere with accuracy and repeatability of the signal.



Example: ACW4 00//PBBB//12B16//BBD

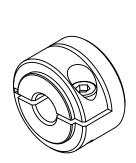
(Contact the factory for special versions, ex: dimensions, connections...)

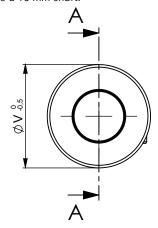


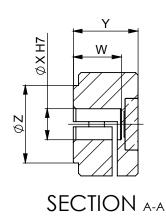


Female magnet support + Magnet 8810/013 Ordering p/n : M9105/Kxx

KXX: Where XX is the shaft mounting diameter in mm. Standards are 06, 08, 10, 11, and 14 mm. i.e M9105/K10 mounts to a 10 mm shaft.

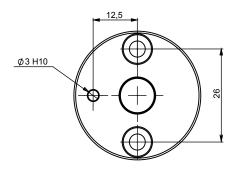


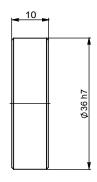


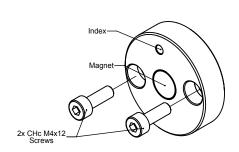


	M9105/K06	M9105/K08	M9105/K10	M9105/K11	M9105/K14
W	6 H7	8 H7	10 H7	11 H7	14 H7
X	20	20	26	26	29
Y	12,5	12,5	14	14	14
Z	15	15	15	15	18

Frontal magnet support + Magnet 8810/013 Ordering p/n : M9105/F26

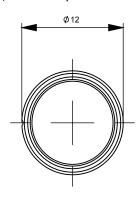


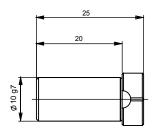




Male magnet support + Magnet 8810/013

Ordering p/n: M9105/M10-01

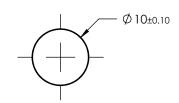


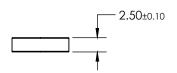




Magnet Ordering p/n: 8810/013







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