

## Zero Drift, High Voltage, Programmable Gain Instrumentation Amplifier with Charge Pump

### FEATURES

- ▶ Integrated bipolar charge pump
  - ▶ Simplified isolation requirements
  - ▶ Wide input range on low voltage supplies
- ▶ Dedicated output amplifier supplies for ADC protection
- ▶ Low power: 83 mW (DVDD = 3 V, VDDCP = 5 V)
- ▶ 36 precision gains from 1/16 V/V to 176 V/V
- ▶ Robust  $\pm 60$  V protected 2:1 input multiplexer
- ▶ Excellent dc precision
  - ▶ Low input offset voltage:  $\pm 14$   $\mu$ V maximum
  - ▶ Low input offset voltage drift:  $\pm 0.08$   $\mu$ V/ $^{\circ}$ C maximum
  - ▶ Gain calibration via internal memory
  - ▶ Low gain drift:  $\pm 1$  ppm/ $^{\circ}$ C maximum
  - ▶ High CMRR: 111 dB minimum,  $G = 1$  V/V
- ▶ Low input bias current:  $\pm 1.5$  nA maximum at  $T_A = 25^{\circ}$ C
- ▶ Integrated input EMI filtering
- ▶ 7 GPIOx ports with special functions
- ▶ Sequential chip select mode
- ▶ Excitation current source
- ▶ SPI port with checksum (CRC) support
- ▶ Internal/external fault detection
- ▶ Compact 28-lead, 5 mm  $\times$  5 mm LFCSP
- ▶ Specified temperature range:  $-40^{\circ}$ C to  $+105^{\circ}$ C

### APPLICATIONS

- ▶ Universal process control front ends
- ▶ Data acquisition systems
- ▶ Test and measurement systems
- ▶ System power monitoring

### GENERAL DESCRIPTION

The ADA4255 is a precision programmable gain instrumentation amplifier (PGIA) with integrated bipolar charge pumps. With its integrated charge pumps, the ADA4255 internally produces the high voltage bipolar supplies needed to achieve a wide input voltage range (38 V typical with VDDCP = 5 V) without lowering input impedance. The charge pump topology of the ADA4255 allows channels to be isolated with only low voltage components, reducing complexity, size, and implementation time in industrial and process control systems.

The zero drift PGIA topology of the ADA4255 self calibrates dc errors and lower frequency 1/f noise, achieving excellent dc precision over the entire specified temperature range. The combination of 36 precision gains ranging from 1/16 V/V to 176 V/V within the ADA4255 and high voltage, high impedance inputs allow a wide range of inputs to be scaled to the range of the analog-to-digital converter (ADC). By integrating all gain setting and level shifting resistors, the ADA4255 achieves excellent common-mode rejection ratio (CMRR) performance (111 dB minimum at  $G = 1$  V/V) and extremely low gain drift ( $\pm 1$  ppm/ $^{\circ}$ C maximum). This high level of precision maximizes dynamic range and greatly reduces calibration requirements in many applications.

The  $\pm 60$  V input protection, integrated electromagnetic interference (EMI) filtering and various safety features make the ADA4255 an ideal choice for robust industrial systems. Seven general-purpose input and output (GPIOx) pins, which can be configured to provide various special functions, are included in the ADA4255. An excitation current source output is available to bias sensors such as resistance temperature detectors (RTDs).

The ADA4255 is specified over the  $-40^{\circ}$ C to  $+105^{\circ}$ C temperature range and is offered in a compact 5 mm  $\times$  5 mm, 28-lead LFCSP.

### SIMPLIFIED FUNCTIONAL BLOCK DIAGRAM

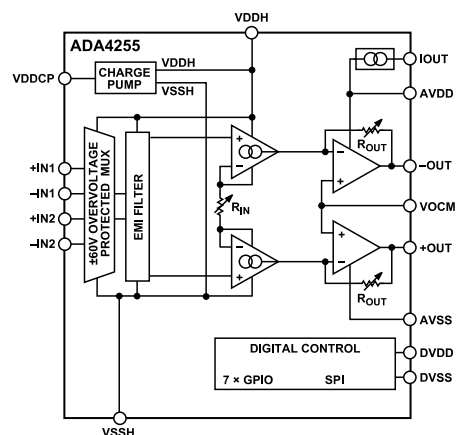


Figure 1. Simplified Functional Block Diagram

### COMPANION PRODUCTS

- ▶ **ADCs:** AD4007, AD7768, AD7175-2, AD7124-4
- ▶ **ADC Drivers:** ADA4945-1, LTC6363
- ▶ **Voltage References:** ADR4550, ADR3450, LT6656
- ▶ **Isolators:** ADuM6421A Family, ADuM140D Family

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**REVISION HISTORY**

**7/2021—Revision 0: Initial Version**

## SPECIFICATIONS

$T_A = 25^\circ\text{C}$ ,  $V_{DDCP} = 5\text{ V}$ ,  $AVDD = 5\text{ V}$ ,  $AVSS = 0\text{ V}$ ,  $DVDD = 3.3\text{ V}$ ,  $DVSS = 0\text{ V}$ ,  $V_{OCM} = AVDD/2$ , scaling gain = 1, and no load, unless otherwise noted.

Table 1.

| Parameter   | Test Conditions/Comments   | Min | Typ              | Max         | Unit                         |
|---|--|-----|------------------|-------------|------------------------------|
| OFFSET VOLTAGE  | Total offset, referred to input (RTI) = $V_{OSI} + (V_{OSO}/\text{Gain})$  |     |                  |             |                              |
| Differential Offset Voltage                           |  |     |                  |             |                              |
| Input Offset Voltage ( $V_{OSI}$ )                    |  |     | $\pm 3$          | $\pm 14$    | $\mu\text{V}$                |
| Output Offset Voltage ( $V_{OSO}$ )                   |  |     | $\pm 40$         | $\pm 125$   | $\mu\text{V}$                |
| Differential Offset Voltage Drift                     | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ , total offset drift, $\text{RTI} = V_{OSI}/T + (V_{OSO}/T)/\text{Gain}$ |     |                  |             |                              |
| $V_{OSI}/T$   |  |     | $\pm 0.03$       | $\pm 0.08$  | $\mu\text{V}/^\circ\text{C}$ |
| $V_{OSO}/T$   |  |     | $\pm 0.98$       | $\pm 2.5$   | $\mu\text{V}/^\circ\text{C}$ |
| Differential Offset Voltage vs. $V_{DDCP}$            | $V_{DDCP} = 2.7\text{ V}$ to $5.5\text{ V}$  |     |                  |             |                              |
| Power Supply Rejection Ratio (PSRR), RTI              |  |     |                  |             |                              |
|   | Gain ( $G$ ) = $1/16\text{ V/V}$   | 60  | 73               |             | dB                           |
|   | $G = 1\text{ V/V}$   | 84  | 97               |             | dB                           |
|   | $G = 128\text{ V/V}$   | 113 | 130              |             | dB                           |
| Differential Offset Voltage vs. $AVDD$ (PSRR), RTI    | $AVDD - AVSS = 2.7\text{ V}$ to $5.5\text{ V}$   |     |                  |             |                              |
|   | $G = 1/16\text{ V/V}$  | 68  | 76               |             | dB                           |
|   | $G = 1\text{ V/V}$   | 92  | 100              |             | dB                           |
|   | $G = 128\text{ V/V}$   | 115 | 130              |             | dB                           |
| Differential Offset vs. External Clock Frequency, RTI | Clock frequency = $0.8\text{ MHz}$ to $1.2\text{ MHz}$   |     |                  |             |                              |
|   | $G = 1/16\text{ V/V}$  |     | $\pm 0.2$        |             | $\mu\text{V/kHz}$            |
|   | $G = 1\text{ V/V}$   |     | $\pm 0.1$        |             | $\mu\text{V/kHz}$            |
|   | $G = 128\text{ V/V}$   |     | $\pm 0.002$      |             | $\mu\text{V/kHz}$            |
| CMRR, RTI   | $+IN = -IN = (V_{SSH} + 3\text{ V})$ to $(V_{DDH} - 3\text{ V})$   |     |                  |             |                              |
|   | $G = 1/16\text{ V/V}$  | 87  | 98               |             | dB                           |
|   | $G = 1\text{ V/V}$   | 111 | 122              |             | dB                           |
|   | $G = 128\text{ V/V}$   | 138 | 150              |             | dB                           |
| GAIN  | Output voltage ( $V_{OUT}$ ) = $9.5\text{ V p-p}^2$  |     |                  |             |                              |
| Input Gain Range                                      |  |     | $1/16$ to $128$  |             | $\text{V/V}$                 |
| Output Scaling Gain Settings                          |  |     | $1, 1.25, 1.375$ |             | $\text{V/V}$                 |
| Gain Error  |  |     |                  |             |                              |
| Before Calibration                                    | All gains  |     | $<\pm 0.06$      | $\pm 0.12$  | %                            |
| Using Calibration Coefficient                         | All gains  |     | $<\pm 0.01$      | $\pm 0.025$ | %                            |
| Gain Drift  |  |     |                  |             |                              |
| All Gains Except the Following:                       | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$  |     | $<\pm 0.3$       | $\pm 1$     | $\text{ppm}/^\circ\text{C}$  |
|   | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ , $G = 1/16\text{ V/V}$ , all scaling gains                              |     | $<\pm 0.5$       | $\pm 1.5$   | $\text{ppm}/^\circ\text{C}$  |
|   | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ , $G = 32\text{ V/V}$ , all scaling gains                                |     | $<\pm 0.4$       | $\pm 1.5$   | $\text{ppm}/^\circ\text{C}$  |
|   | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ , $G = 64\text{ V/V}$ , all scaling gains                                |     | $<\pm 0.6$       | $\pm 2$     | $\text{ppm}/^\circ\text{C}$  |
|   | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ , $G = 128\text{ V/V}$ , all scaling gains                               |     | $<\pm 1.5$       | $\pm 4$     | $\text{ppm}/^\circ\text{C}$  |
| Nonlinearity  | All gains except $32\text{ V/V}$ , $64\text{ V/V}$ , and $128\text{ V/V}^{2,3}$  |     | 5                | 15          | ppm                          |
|   | $G = 32\text{ V/V}$  |     | 7.5              |             | ppm                          |
|   | $G = 64\text{ V/V}$  |     | 12               |             | ppm                          |
|   | $G = 128\text{ V/V}$   |     | 15               |             | ppm                          |

## SPECIFICATIONS

Table 1.

| Parameter   | Test Conditions/Comments   | Min                        | Typ         | Max                        | Unit   |
|---|--|----------------------------|-------------|----------------------------|--------|
| NOISE   | $Total\ Noise,\ RTI = \sqrt{e_{ni}^2 + \left(\frac{e_{no}}{Gain}\right)^2}$                      |                            |             |                            |        |
| Voltage Noise, 1 kHz, RTI                           |  |                            |             |                            |        |
| Input Noise ( $e_{ni}$ )                            |  |                            | 17          |                            | nV/√Hz |
| Output Noise ( $e_{no}$ )                           |  |                            | 253         |                            | nV/√Hz |
| 0.1 Hz to 10 Hz, RTI                                |  |                            |             |                            |        |
| G = 1/16 V/V  |  |                            | 95          |                            | μV p-p |
| G = 1 V/V   |  |                            | 5.75        |                            | μV p-p |
| G = 128 V/V   |  |                            | 330         |                            | nV p-p |
| 0.01 Hz to 10 Hz, RTI                               |  |                            |             |                            |        |
| G = 1/16 V/V  |  |                            | 100         |                            | μV p-p |
| G = 1 V/V   |  |                            | 6.8         |                            | μV p-p |
| G = 128 V/V   |  |                            | 395         |                            | nV p-p |
| Current Noise                                       |  |                            |             |                            |        |
| 10 Hz   |  |                            | 100         |                            | fA/√Hz |
| 0.1 Hz to 10 Hz                                     |  |                            | 3.1         |                            | pA p-p |
| 0.01 Hz to 10 Hz                                    |  |                            | 4           |                            | pA p-p |
| INPUT CHARACTERISTICS                               |  |                            |             |                            |        |
| Input Bias Current                                  |  |                            | ±0.45       | ±1.5                       | nA     |
| $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}^1$  |  |                            |             | ±4                         | nA     |
| $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ |  |                            |             | ±14                        | nA     |
| Input Offset Current                                |  |                            | ±0.2        | ±1.3                       | nA     |
| $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}^1$  |  |                            |             | ±2.5                       | nA     |
| $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}^1$ |  |                            |             | ±3.5                       | nA     |
| Input Impedance                                     |  |                            |             |                            |        |
| Common mode   |  |                            | >1  11      |                            | GΩ  pF |
| Differential  |  |                            | >1  4.7     |                            | GΩ  pF |
| Input Operating Voltage Range                       | Guaranteed by CMRR   | VSSH + 3                   |             | VDDH - 3                   | V      |
| MUX_OVER_VOLT_ERR                                   | Any input  |                            |             |                            |        |
| Positive Threshold                                  |  |                            | VDDH - 0.9  |                            | V      |
| Negative Threshold                                  |  |                            | VSSH + 0.9  |                            | V      |
| INPUT_ERR/G_RST                                     | Selected input, Common-mode applied  |                            |             |                            |        |
| Positive Threshold                                  |  |                            | VDDH - 1.5  |                            | V      |
| Negative Threshold                                  |  |                            | VSSH + 1.5  |                            | V      |
| Switch Ax and Switch Bx Resistance                  | See Figure 86 for additional information   |                            | 560         |                            | Ω      |
| Switch D12 Resistance                               | See Figure 86 for additional information   |                            | 4.05        |                            | kΩ     |
| ANALOG OUTPUTS                                      |  |                            |             |                            |        |
| Output Voltage Swing from Each Rail                 | AVDD = 5 V, load resistor ( $R_L$ ) = 2.49 kΩ to 2.5 V<br>AVDD = 2.7 V, $R_L$ = 1.8 kΩ to 1.35 V | AVSS + 0.06<br>AVSS + 0.05 |             | AVDD - 0.08<br>AVDD - 0.06 | V<br>V |
| Capacitive Load Drive                               |  |                            | 500         |                            | pF     |
| Short-Circuit Current                               | To 2.5 V, G = 1.375, AVDD = 2.7 V to 5 V   | 3.5                        | 11          | 25                         | mA     |
| OUTPUT_ERR  |  |                            |             |                            |        |
| Positive Threshold                                  |  |                            | AVDD - 0.03 |                            | V      |
| Negative Threshold                                  |  |                            | AVSS + 0.03 |                            | V      |
| VOCM DYNAMIC PERFORMANCE                            |  |                            |             |                            |        |
| -3 dB Bandwidth                                     |  |                            | 2.3         |                            | MHz    |
| Slew Rate   |  |                            | 1.9         |                            | V/μs   |
| Voltage Noise                                       | Frequency = 1 kHz  |                            | 160         |                            | nV/√Hz |
| Gain  |  |                            | 1           |                            | V/V    |

## SPECIFICATIONS

Table 1.

| Parameter                        | Test Conditions/Comments                        | Min  | Typ                                     | Max      | Unit   |
|----------------------------------|---|------|---|----------|--------|
| VOCM INPUT CHARACTERISTICS       |   |      |   |          |        |
| Input Voltage Range              |   | AVSS |   | AVDD – 1 | V      |
| Input Resistance                 |   |      | 10                                      |          | GΩ     |
| Common-Mode Offset Voltage       |   |      | 20                                      |          | μV     |
| Common-Mode Offset Voltage Drift |   |      | 2.5                                     |          | μV/°C  |
| Input Bias Current               |   |      | 500                                     |          | pA     |
| DYNAMIC RESPONSE                 |   |      |   |          |        |
| Small Signal ±3 dB Bandwidth     |   |      |   |          |        |
|                                  | G = 1/16 V/V                                    |      | 15                                      |          | kHz    |
|                                  | G = 1/8 V/V                                     |      | 28                                      |          | kHz    |
|                                  | G = 1/4 V/V                                     |      | 67                                      |          | kHz    |
|                                  | G = 1/2 V/V                                     |      | 138                                     |          | kHz    |
|                                  | G = 1 V/V                                       |      | 1800                                    |          | kHz    |
|                                  | G = 2 V/V                                       |      | 513                                     |          | kHz    |
|                                  | G = 4 V/V                                       |      | 341                                     |          | kHz    |
|                                  | G = 8 V/V                                       |      | 319                                     |          | kHz    |
|                                  | G = 16 V/V                                      |      | 297                                     |          | kHz    |
|                                  | G = 32 V/V                                      |      | 275                                     |          | kHz    |
|                                  | G = 64 V/V                                      |      | 257                                     |          | kHz    |
|                                  | G = 128 V/V                                     |      | 209                                     |          | kHz    |
| Settling Time 0.01%              | V <sub>OUT</sub> = 8 V p-p                      |      |   |          |        |
|                                  | G = 1 V/V                                       |      | 10                                      |          | μs     |
|                                  | G = 8 V/V                                       |      | 8                                       |          | μs     |
|                                  | G = 128 V/V                                     |      | 5                                       |          | μs     |
| Settling Time 0.0015% (16-Bit)   | V <sub>OUT</sub> = 8 V p-p                      |      |   |          |        |
|                                  | G = 1 V/V                                       |      | 18                                      |          | μs     |
|                                  | G = 8 V/V                                       |      | 15                                      |          | μs     |
|                                  | G = 128 V/V                                     |      | 15                                      |          | μs     |
| Slew Rate                        | V <sub>OUT</sub> = 8 V p-p <sup>2</sup>         |      |   |          |        |
|                                  | G = 1/16 V/V                                    |      | 0.06                                    |          | V/μs   |
|                                  | G = 1 V/V                                       |      | 0.8                                     |          | V/μs   |
|                                  | G = 128 V/V                                     |      | 3.1                                     |          | V/μs   |
| THD                              | V <sub>OUT</sub> = 8 V p-p at frequency = 1 kHz |      |   |          |        |
|                                  | G = 1 V/V                                       |      | –104                                    |          | dB     |
|                                  | G = 8 V/V                                       |      | –96                                     |          | dB     |
|                                  | G = 128 V/V                                     |      | –80                                     |          | dB     |
| Overload Recovery Time           |   |      |   |          |        |
| Input                            | Input voltage (V <sub>IN</sub> ) = 56 V p-p     |      | 40                                      |          | μs     |
| Output                           | G = 1 V/V, V <sub>IN</sub> = 10 V p-p           |      | 6                                       |          | μs     |
| EXCITATION CURRENT SOURCE (IOUT) |   |      |   |          |        |
| Output Current Range             |   | 100  |   | 1500     | μA     |
| Initial Tolerance                |   |      | ±3                                      | ±10      | %      |
| Drift                            | T <sub>A</sub> = –40°C to +105°C                |      | ±200                                    |          | ppm/°C |
| WIRE BREAK CURRENTS              |   |      |   |          |        |
| Output Current Range             |   | 0.25 |   | 16       | μA     |
| Impedance Threshold              |   |      | (VDDH – 4)/I <sub>WB</sub> <sup>4</sup> |          | Ω      |
| Initial Tolerance                |   |      | ±12                                     |          | %      |
| Drift                            | T <sub>A</sub> = –40°C to +105°C                |      | ±250                                    |          | ppm/°C |

## SPECIFICATIONS

Table 1.

| Parameter                     | Test Conditions/Comments  | Min               | Typ    | Max   | Unit          |
|-------------------------------|---|-------------------|--------|-------|---------------|
| DIGITAL INPUTS                |   |                   |        |       |               |
| Low ( $V_{INL}$ )             |   | 0                 |        | 0.8   | V             |
| High ( $V_{INH}$ )            |   | $0.6 \times DVDD$ |        | DVDD  | V             |
| Digital Input Pin Capacitance |   |                   | 5      |       | pF            |
| DIGITAL OUTPUT                |   |                   |        |       |               |
| Low ( $V_{OL}$ )              | Sinking 4 mA  |                   |        | 0.7   | V             |
| High ( $V_{OH}$ )             | Sourcing 2 mA   | $DVDD - 0.8$      |        |       | V             |
| INTERNAL/EXTERNAL CLOCK       |   |                   |        |       |               |
| Internal Clock Frequency      |   | 0.8               | 1      | 1.2   | MHz           |
| Duty Cycle                    |   |                   | 50     |       | %             |
| Internal Clock Divider Range  |   | 1                 |        | 32    | MHz/ MHz      |
| CHARGE PUMP                   |   |                   |        |       |               |
| VDDH Output                   | VDDCP = 5 V   | 21.8              | 22.3   | 22.8  | V             |
|                               | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$                   | 21.7              |        | 22.9  | V             |
|                               | $T_A = 25^\circ\text{C}$ , VDDCP = 5 V, 500 $\mu\text{A}$ VDDH load | 19.9              | 21.3   | 22    | V             |
|                               | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$                   | 19.8              |        | 22.1  | V             |
| VSSH Output                   | VDDCP = 5 V   | -22.8             | -21.7  | -20.8 | V             |
|                               | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$                   | -22.9             |        | -20.7 | V             |
|                               | $T_A = 25^\circ\text{C}$ , VDDCP = 5 V, 500 $\mu\text{A}$ VSSH load | -23               | -20.6  | -19.8 | V             |
|                               | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$                   | -23.1             |        | -19.7 | V             |
| POWER SUPPLY                  |   |                   |        |       |               |
| VDDCP – DVSS                  |   | 2.7               |        | 5     | V             |
| AVDD – AVSS                   |   | 2.7               |        | 5     | V             |
| DVDD – DVSS                   |   | 2.7               |        | 5     | V             |
| VDDCP Current, $I_{VDDCP}$    |   |                   | 15.6   | 16.75 | mA            |
| DVSS Current, $I_{DVSS}$      |   |                   | -15.17 |       | mA            |
| DVDD Current, $I_{DVDD}$      | DVDD = 3 V  |                   | 170    | 205   | $\mu\text{A}$ |
| AVDD Current, $I_{AVDD}$      |   |                   | 980    | 1305  | $\mu\text{A}$ |
| Static Power Dissipation      | DVDD = 3 V, VDDCP = 5 V   |                   | 83     | 91    | mW            |
|                               | DVDD = 3 V, VDDCP = 2.7 V   |                   | 34     | 53    | mW            |

<sup>1</sup> Guaranteed by design. These specifications are not production tested but are supported by characterization data at the initial product release.

<sup>2</sup> For gains less than 1/2, a smaller output swing is used.

<sup>3</sup> Only  $G = 1 \text{ V/V}$  is production tested.

<sup>4</sup>  $I_{WB}$  means wire break current.

## SPECIFICATIONS

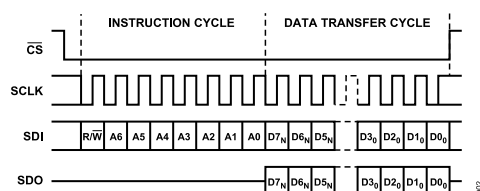
## TIMING SPECIFICATIONS

VDDCP = 5 V, AVDD = 5 V, AVSS = 0 V, DVDD = 3.3V, DVSS = 0 V, and VO<sub>CM</sub> = AVDD/2 V.

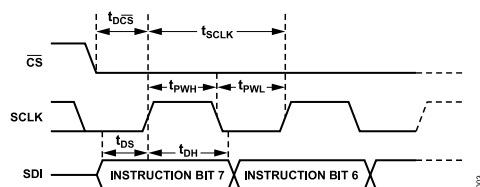
**Table 2. Digital Values and Serial Peripheral Interface (SPI) Timing Specifications**

| Parameter                           | Symbol    | Min | Typ | Max | Unit |
|-------------------------------------|-----------|-----|-----|-----|------|
| Maximum Clock Rate (SCLK)           |           |     |     | 5   | MHz  |
| Minimum Pulse Width (SCLK)          |           |     |     |     |      |
| High                                | $t_{PWH}$ | 75  |     |     | ns   |
| Low                                 | $t_{PWL}$ | 75  |     |     | ns   |
| SDI/SDO to SCLK Setup Time          | $t_{DS}$  | 10  |     |     | ns   |
| SDI/SDO to SCLK Hold Time           | $t_{DH}$  | 10  |     |     | ns   |
| Data Valid, SDO to SCLK             | $t_{DV}$  | 50  |     |     | ns   |
| Setup Time, $\overline{CS}$ to SCLK | $t_{DCS}$ | 30  |     |     | ns   |

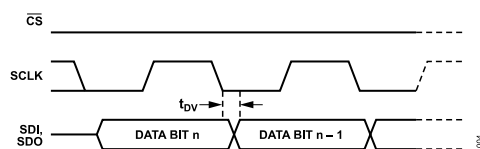
## Timing Diagrams



**Figure 2. SPI Timing Diagram, MSB First**



**Figure 3. SPI Register Write Timing Diagram**



**Figure 4. SPI Register Read Timing Diagram**



## ABSOLUTE MAXIMUM RATINGS

Table 3.

| Parameter   | Rating   |
|---|--|
| VDDH  | VSSH – 0.3 V to VSSH + 60 V                                |
| VDDCP   | DVSS – 0.3 V to DVSS + 5.5 V                               |
| AVDD  | AVSS – 0.3 V to AVSS + 5.5 V                               |
| DVDD  | DVSS – 0.3 V to DVSS + 5.5 V                               |
| AVSS or DVSS  |  |
| Voltage   | VSSH – 0.3 V to VSSH + 30 V<br>VDDH – 30 V to VDDH + 0.3 V |
| Current   | ±10 mA   |
| VDDH/VSSH Current   | ±10 mA   |
| Input Voltage (+IN1, –IN1, +IN2, or –IN2)   | VSSH – 60 V to VSSH + 60 V                                 |
| Differential Input Voltage Between Any Two Amplifier Inputs (+IN1, –IN1, +IN2, or –IN2) | 60 V   |
| –OUT, +OUT Short-Circuit Current  | Indefinite   |
| VOCM  |  |
| Voltage   | AVSS – 0.3 V to AVDD + 0.3 V                               |
| Current   | ±10 mA   |
| Digital Inputs Voltage and Outputs Voltage (SPI and GPIO)                               | DVSS – 0.3 V to DVDD + 0.3 V                               |
| Digital Inputs Current (SPI and GPIO)   | ±10 mA   |
| IOUT  |  |
| Voltage   | AVSS – 0.3 V to AVDD + 0.3 V                               |
| Current   | ±10 mA   |
| Temperature   |  |
| Operating Range   | –40°C to +125°C  |
| Specified Range   | –40°C to +105°C  |
| Maximum Junction  | 150°C  |
| Storage Range   | –65°C to +150°C  |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.

$\theta_{JA}$  is the natural convection, junction to ambient, thermal resistance measured in a one cubic foot sealed enclosure.  $\theta_{JC}$  is the junction to case thermal resistance.

Table 4. Thermal Resistance

| Package Type <sup>1</sup> | $\theta_{JA}$ | $\theta_{JC}$ | Unit |
|---------------------------|---------------|---------------|------|
| CP-28-11                  | 36.9          | 1.9           | °C/W |

<sup>1</sup> The thermal resistance values specified in Table 4 are simulated based on JEDEC specifications (unless specified otherwise) and must be used in compliance with JESD51-12.

Refer to the [ESD Map](#) section for a schematic of ESD diodes and paths.

## ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

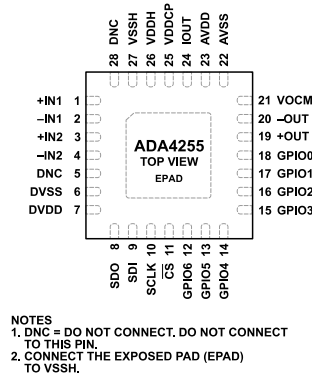


Figure 5. Pin Configuration

Table 5. Pin Function Descriptions

| Pin No. | Mnemonic        | Pin Description  |
|---------|-----------------|--|
| 1       | +IN1            | Channel 1 Positive Input.  |
| 2       | -IN1            | Channel 1 Negative Input.  |
| 3       | +IN2            | Channel 2 Positive Input.  |
| 4       | -IN2            | Channel 2 Negative Input.  |
| 5, 28   | DNC             | Do Not Connect. Do not connect to this pin.  |
| 6       | DVSS            | Negative Digital Supply Voltage.   |
| 7       | DVDD            | Positive Digital Supply Voltage.   |
| 8       | SDO             | SPI Serial Data Output.  |
| 9       | SDI             | SPI Serial Data Input.   |
| 10      | SCLK            | SPI Serial Clock Input.  |
| 11      | $\overline{CS}$ | SPI Chip Select Input.   |
| 12      | GPIO6           | GPIO6/SCS6.  |
| 13      | GPIO5           | GPIO5/SCS5.  |
| 14      | GPIO4           | GPIO4/SCS4/Clock Input or Output.  |
| 15      | GPIO3           | GPIO3/SCS3/Fault Interrupt Output.   |
| 16      | GPIO2           | GPIO2/SCS2/Calibration Busy Out.   |
| 17      | GPIO1           | GPIO1/SCS1/External Multiplexer Control 1.   |
| 18      | GPIO0           | GPIO0/SCS0/External Multiplexer Control 0.   |
| 19      | +OUT            | Positive Output.   |
| 20      | -OUT            | Negative Output.   |
| 21      | VOCM            | Output Amplifier Common-Mode Voltage Input. The VOCM pin is high impedance and is not internally biased. |
| 22      | AVSS            | Output Amplifier Negative Supply Voltage.  |
| 23      | AVDD            | Output Amplifier Positive Supply Voltage.  |
| 24      | IOUT            | Excitation Current Source Output.  |
| 25      | VDDCP           | Charge Pump Supply Voltage.  |
| 26      | VDDH            | Positive High Voltage Charge Pump Output. VDDH handles 500 $\mu$ A load.                                 |
| 27      | VSSH            | Negative High Voltage Charge Pump Output. VSSH handles 500 $\mu$ A load.                                 |
| EPAD    |                 | Exposed Pad. Connect the exposed pad (EPAD) to VSSH.   |

## TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ\text{C}$ ,  $V_{DDCP} = 5\text{ V}$ ,  $AV_{DD} = 5\text{ V}$ ,  $AV_{SS} = 0\text{ V}$ ,  $DV_{DD} = 3.3\text{ V}$ ,  $DV_{SS} = 0\text{ V}$ ,  $V_{OCM} = AV_{DD}/2$ , and no load, unless otherwise noted.

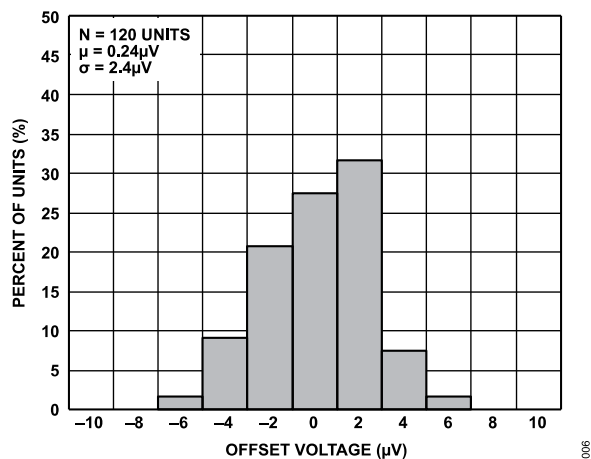


Figure 6. Offset Voltage Distribution, RTI (Gain = 128 V/V)

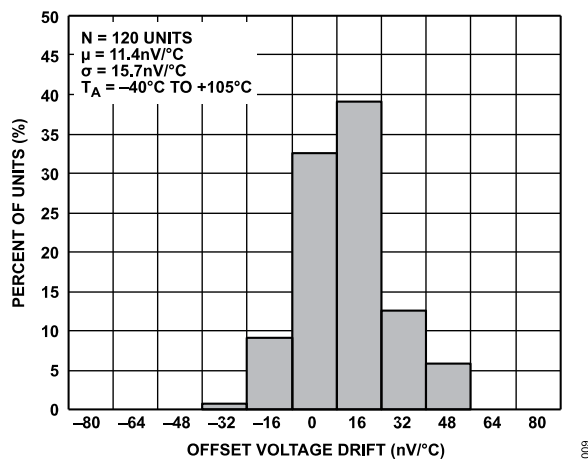


Figure 9. Offset Voltage Drift Distribution, RTI (Gain = 128 V/V)

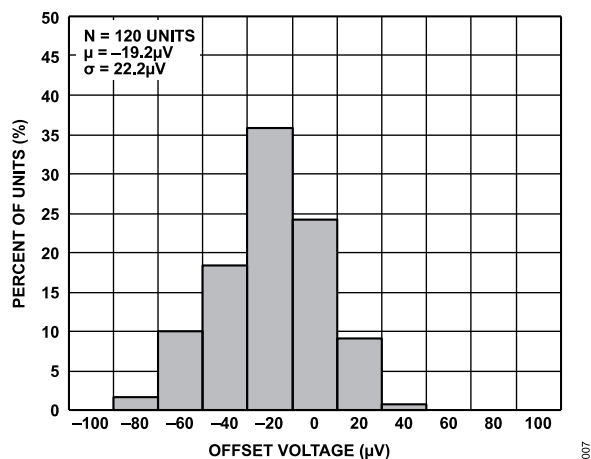


Figure 7. Offset Voltage Distribution, RTI (Gain = 1 V/V)

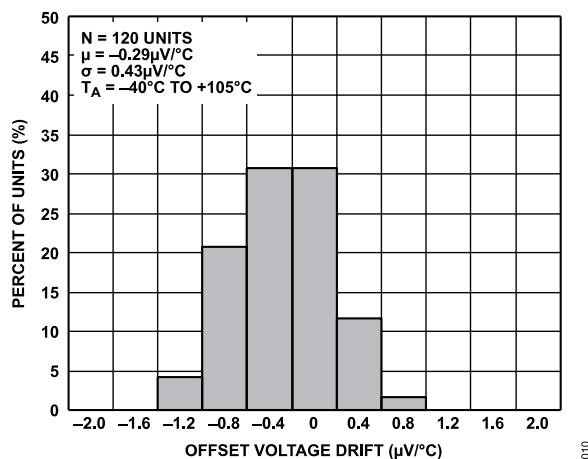


Figure 10. Offset Voltage Drift Distribution, RTI (Gain = 1 V/V)

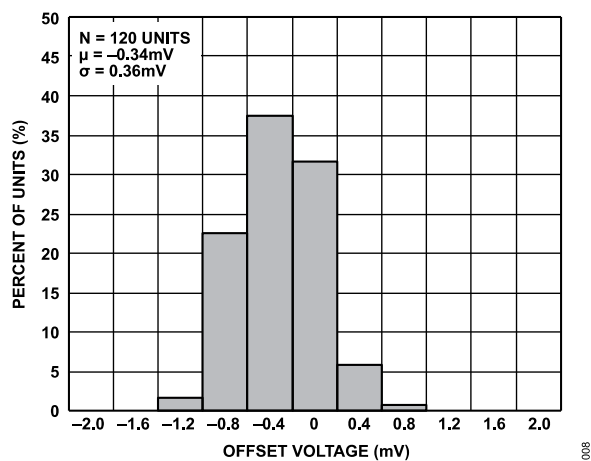


Figure 8. Offset Voltage Distribution, RTI (Gain = 1/16 V/V)

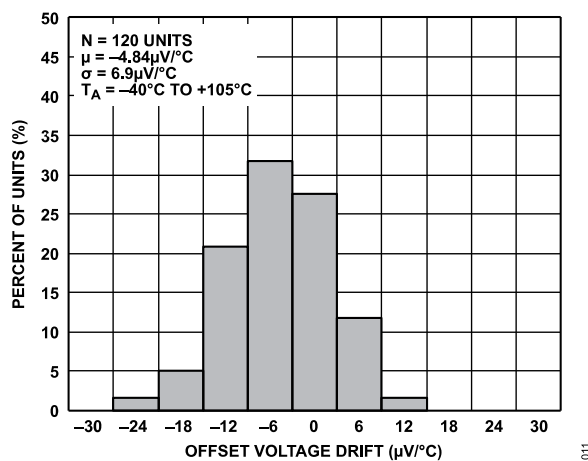


Figure 11. Offset Voltage Drift Distribution, RTI (Gain = 1/16 V/V)

## TYPICAL PERFORMANCE CHARACTERISTICS

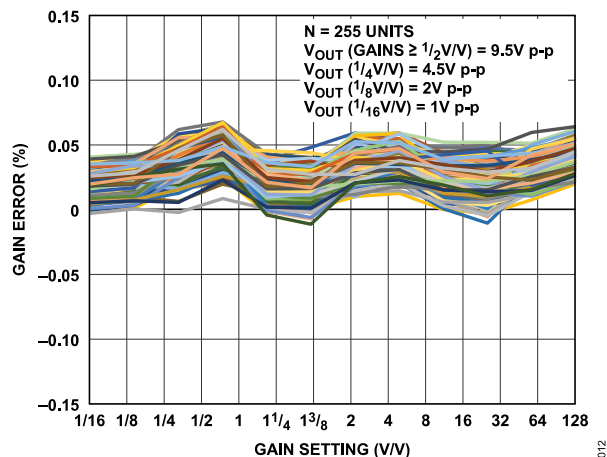


Figure 12. Gain Error vs. Gain Setting

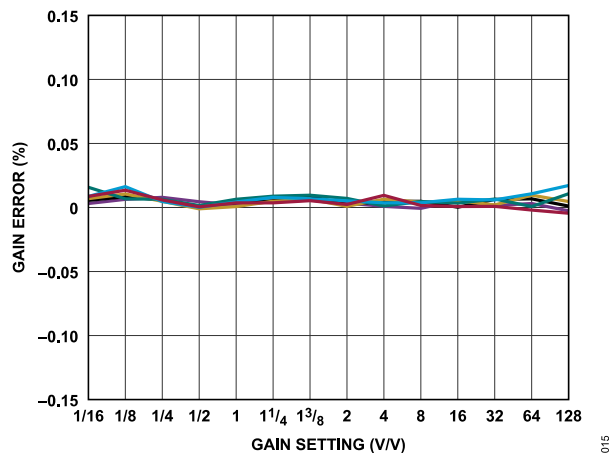


Figure 15. Gain Error vs. Gain Setting Using Calibration Coefficients

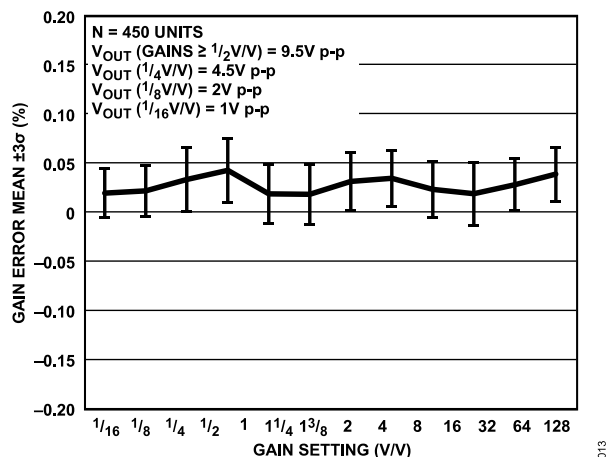
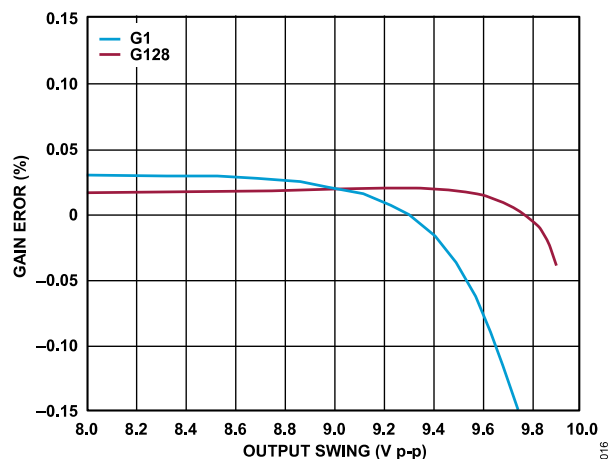
Figure 13. Gain Error Mean  $\pm 3\sigma$  vs. Gain Setting

Figure 16. Gain Error vs. Output Swing

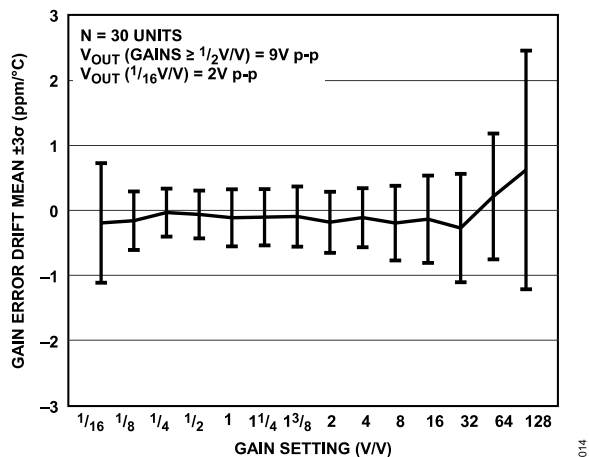
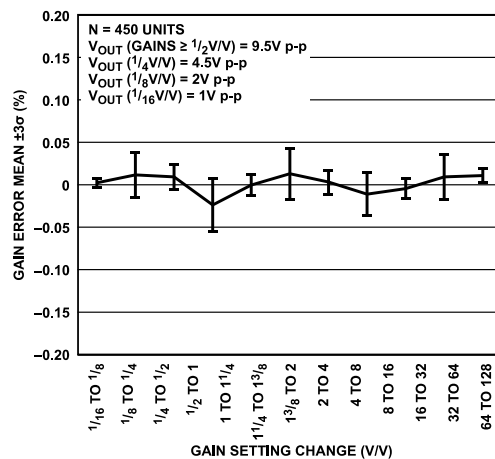
Figure 14. Gain Error Drift Mean  $\pm 3\sigma$  vs. Gain Setting

Figure 17. Gain Error Deviation Between Sequential Gain Settings

TYPICAL PERFORMANCE CHARACTERISTICS

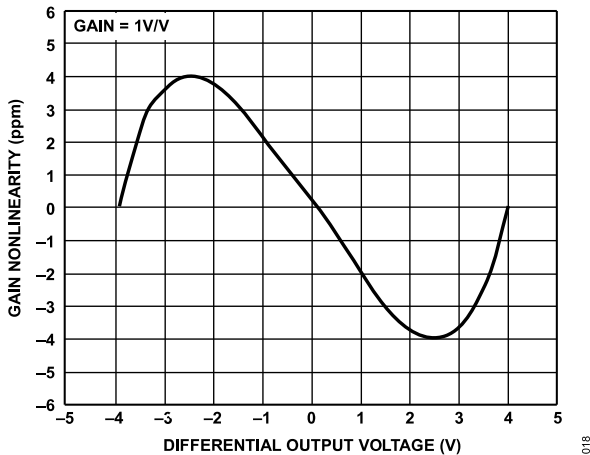


Figure 18. Gain Nonlinearity vs. Differential Output Voltage

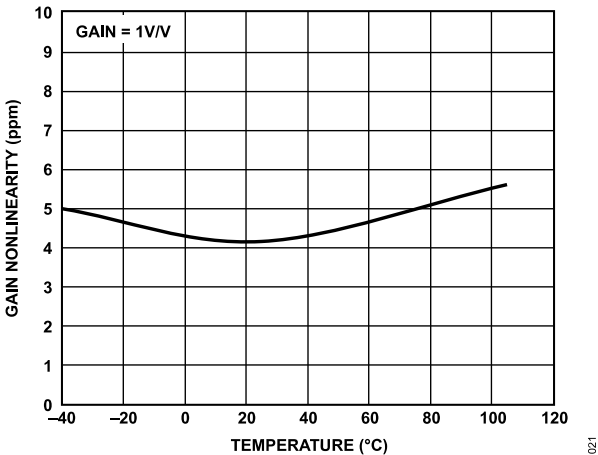


Figure 21. Gain Nonlinearity vs. Temperature

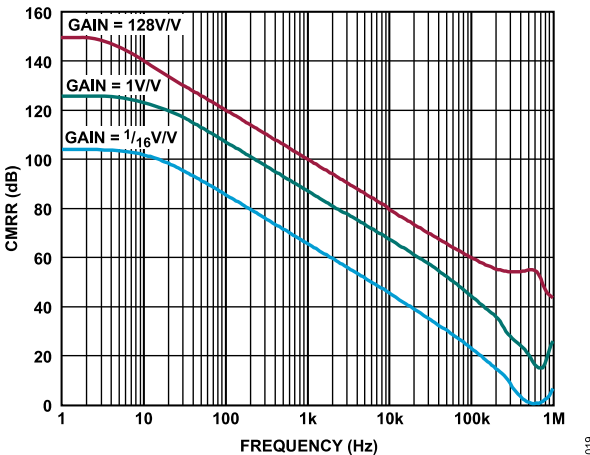


Figure 19. CMRR vs. Frequency

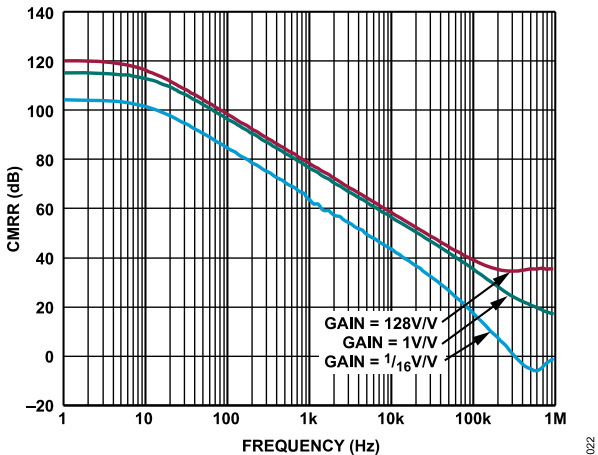


Figure 22. CMRR vs. Frequency with 1 kΩ Imbalance

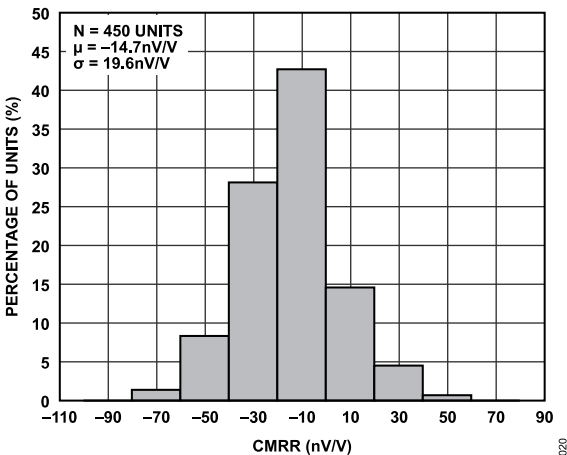


Figure 20. CMRR Distribution (Gain = 128 V/V)

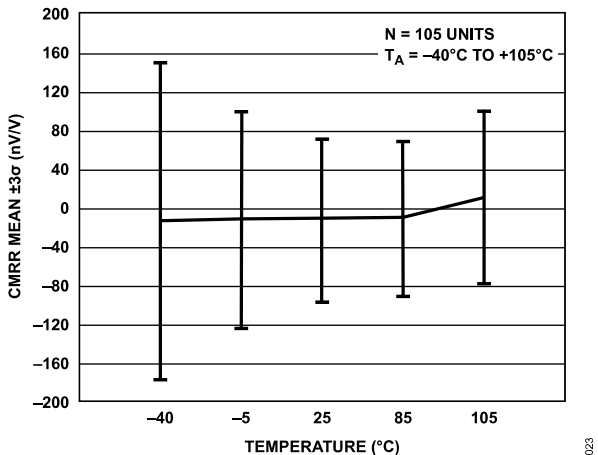


Figure 23. CMRR Mean  $\pm 3\sigma$  vs. Temperature (Gain = 128 V/V)

## TYPICAL PERFORMANCE CHARACTERISTICS

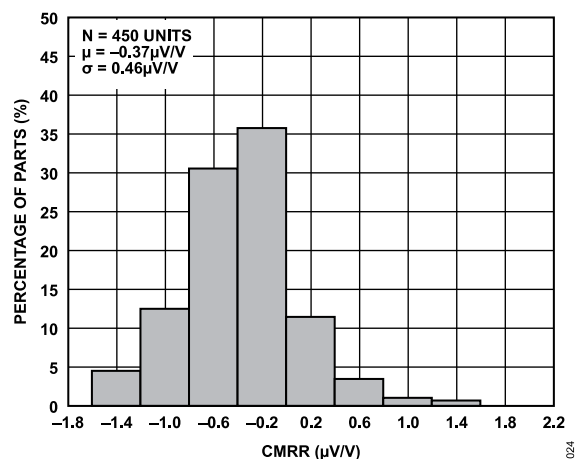


Figure 24. CMRR Distribution (Gain = 1 V/V)

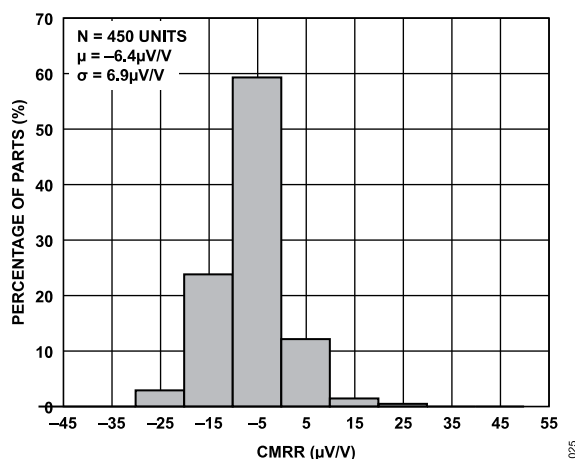


Figure 25. CMRR Distribution (Gain = 1/16 V/V)

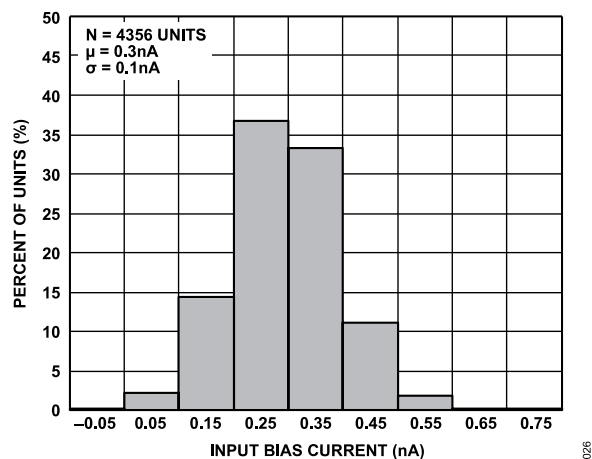


Figure 26. Input Bias Current Distribution

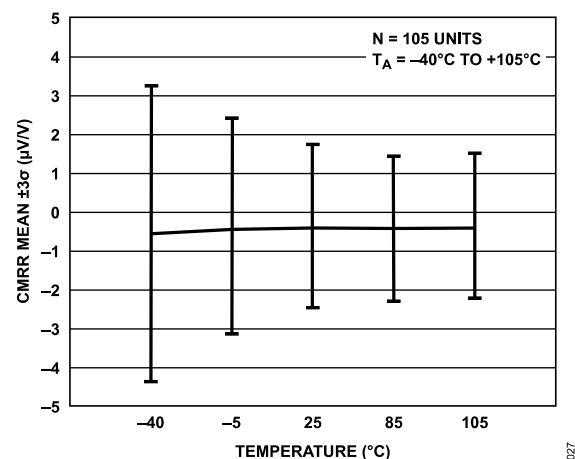
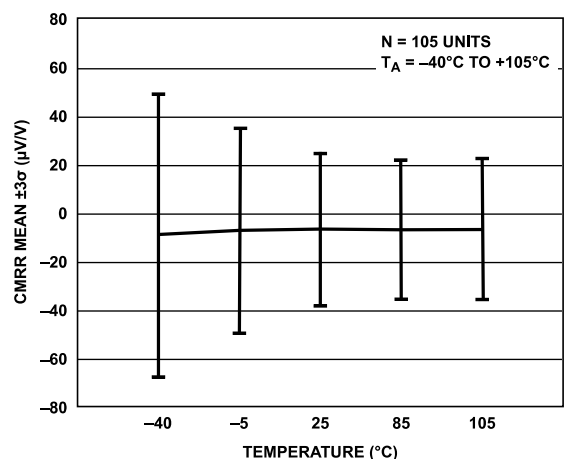
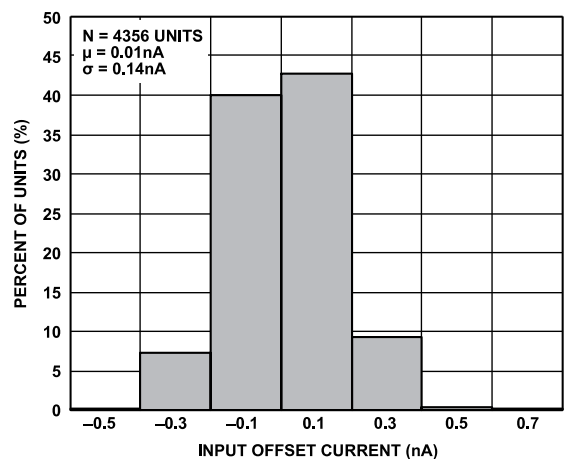
Figure 27. CMRR Mean  $\pm 3\sigma$  vs. Temperature (Gain = 1 V/V)Figure 28. CMRR Mean  $\pm 3\sigma$  vs. Temperature (Gain = 1/16 V/V)

Figure 29. Input Offset Current Distribution

## TYPICAL PERFORMANCE CHARACTERISTICS

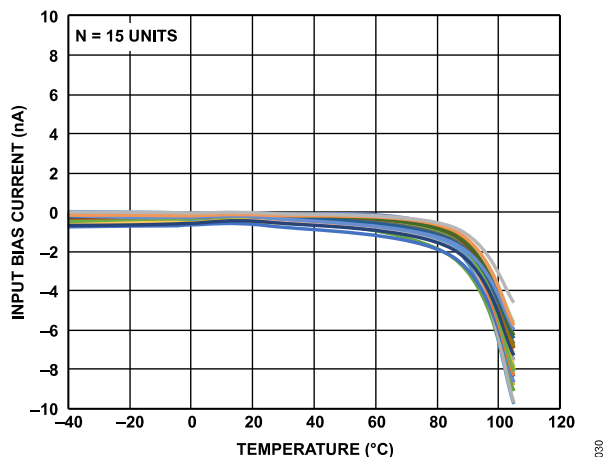


Figure 30. Input Bias Current vs. Temperature

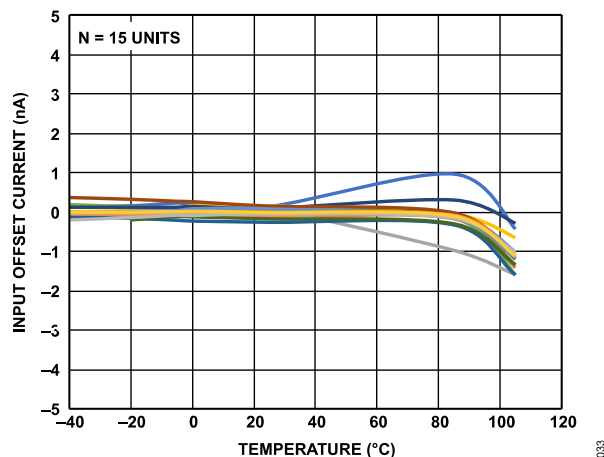


Figure 33. Input Offset Current vs. Temperature

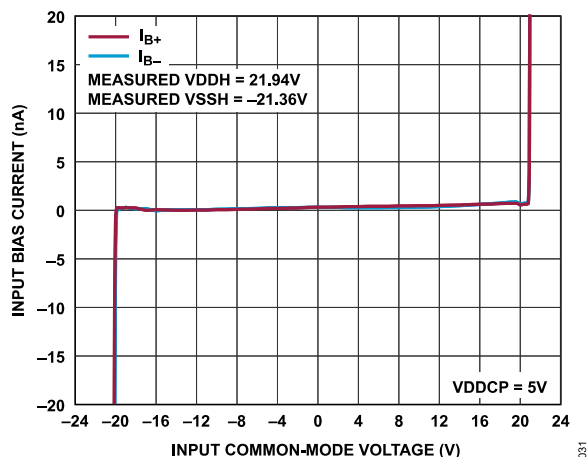


Figure 31. Input Bias Current vs. Input Common-Mode Voltage

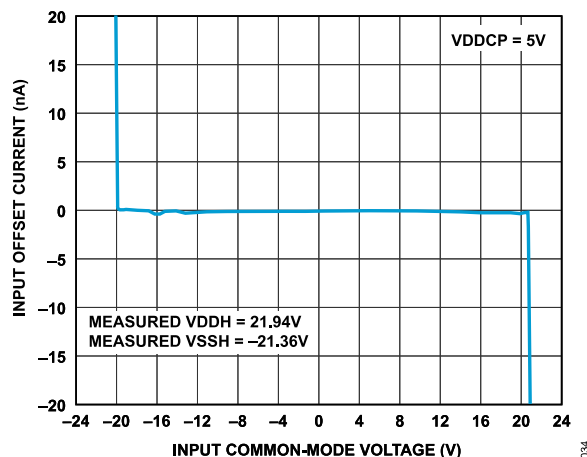


Figure 34. Input Offset Current vs. Input Common-Mode Voltage

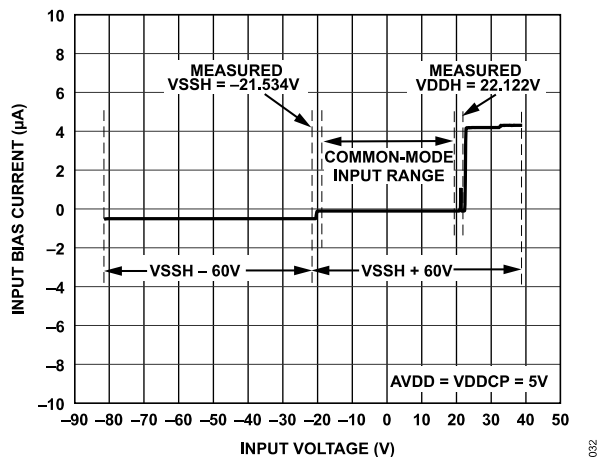


Figure 32. Input Bias Current vs. Input Voltage, VDDCP = AVDD = 5 V

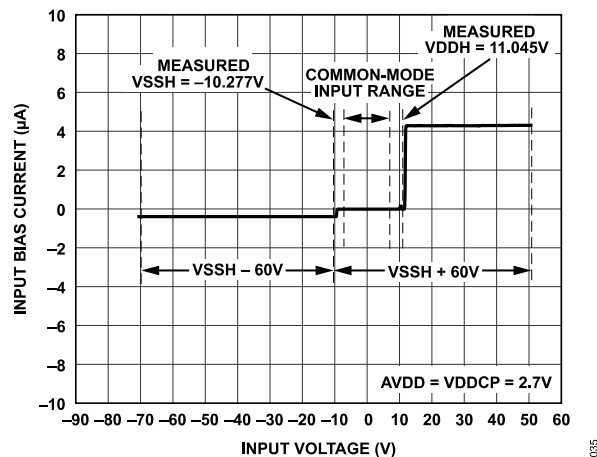


Figure 35. Input Bias Current vs. Input Voltage, VDDCP = AVDD = 2.7 V

## TYPICAL PERFORMANCE CHARACTERISTICS

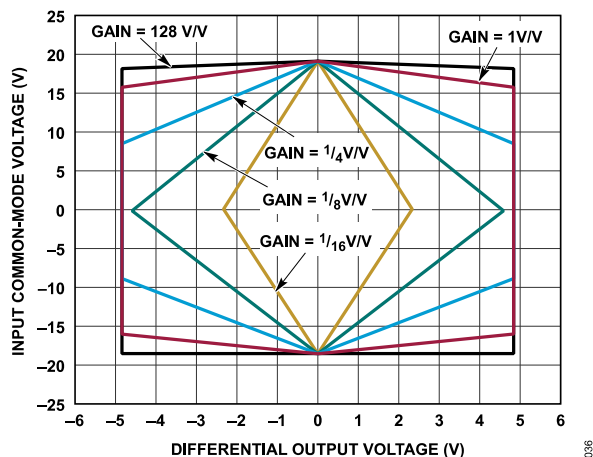


Figure 36. Input Common-Mode Voltage vs. Differential Output Voltage

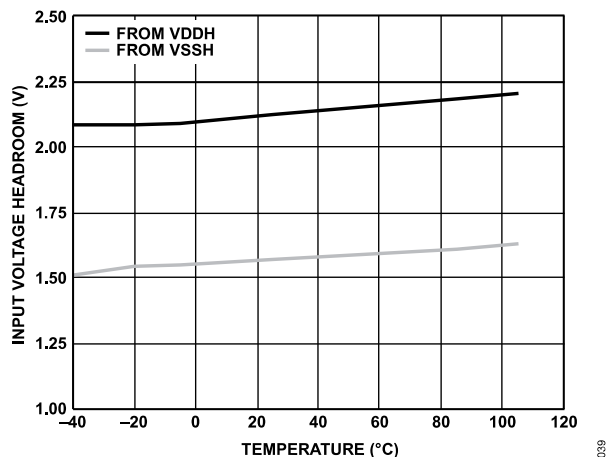


Figure 39. Input Voltage Headroom vs. Temperature

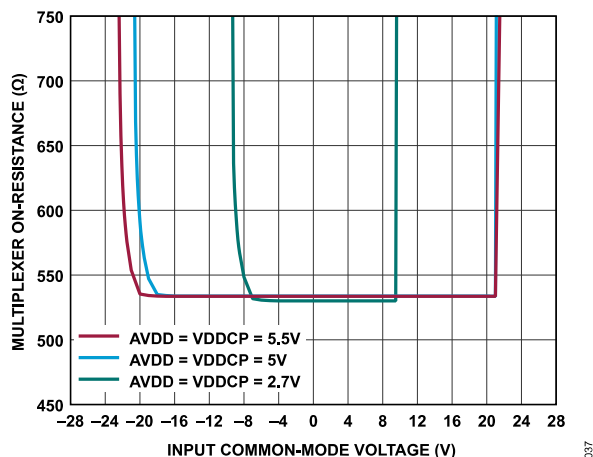


Figure 37. Multiplexer On-Resistance vs. Input Common-Mode Voltage

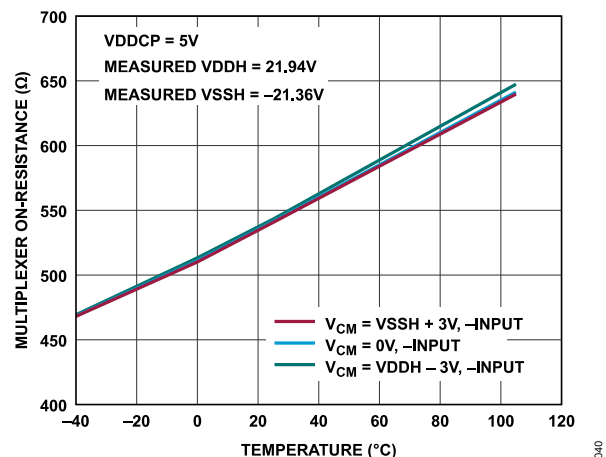


Figure 40. Multiplexer On-Resistance vs. Temperature

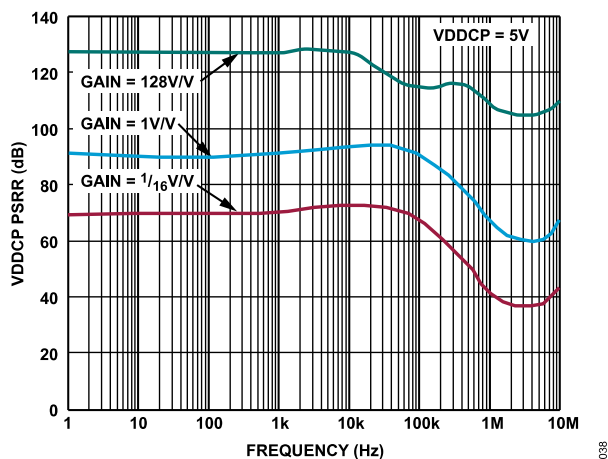


Figure 38. VDDCP PSRR vs. Frequency

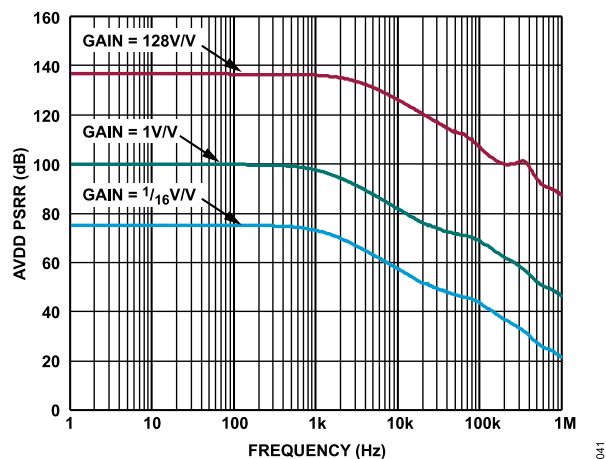


Figure 41. AVDD PSRR vs. Frequency



## TYPICAL PERFORMANCE CHARACTERISTICS

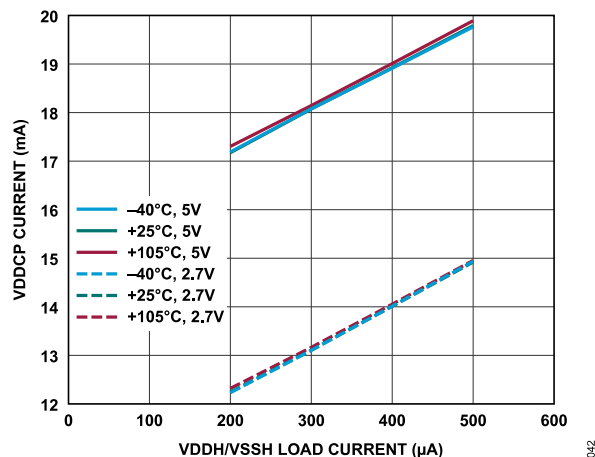


Figure 42. VDDCP Current vs. VDDH/VSSH Load Current

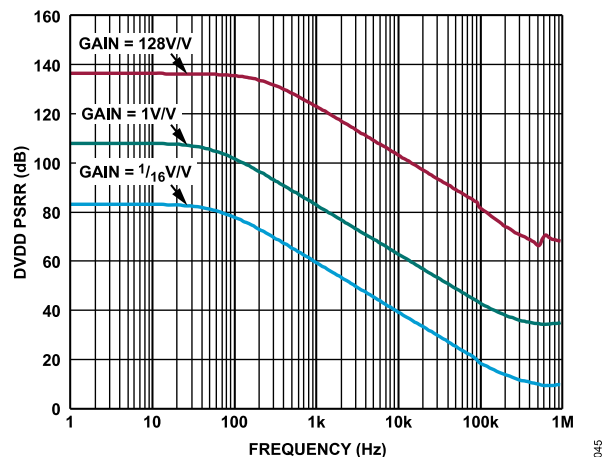


Figure 45. DVDD PSRR vs. Frequency

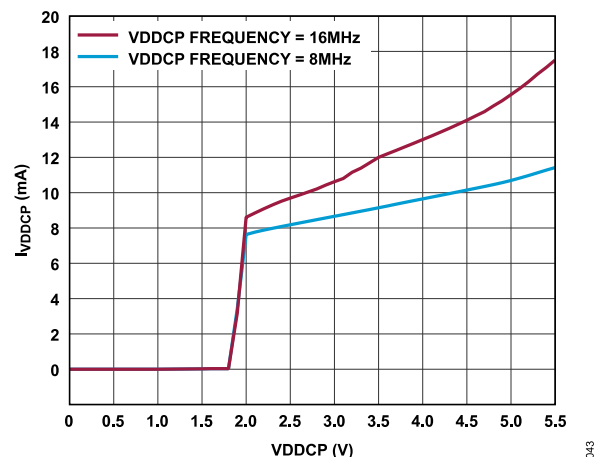
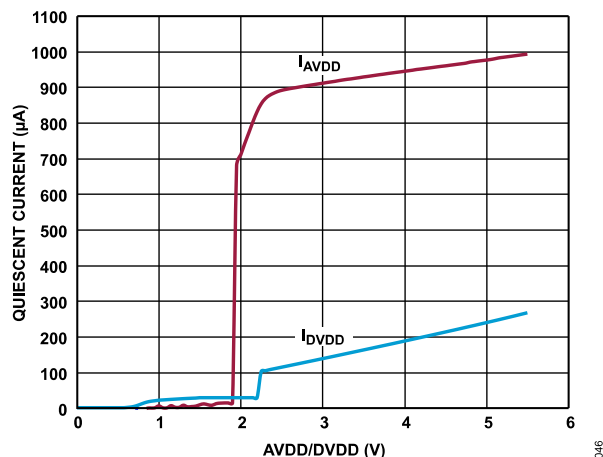
Figure 43.  $I_{VDDCP}$  vs. VDDCP

Figure 46. Quiescent Current vs. AVDD and DVDD

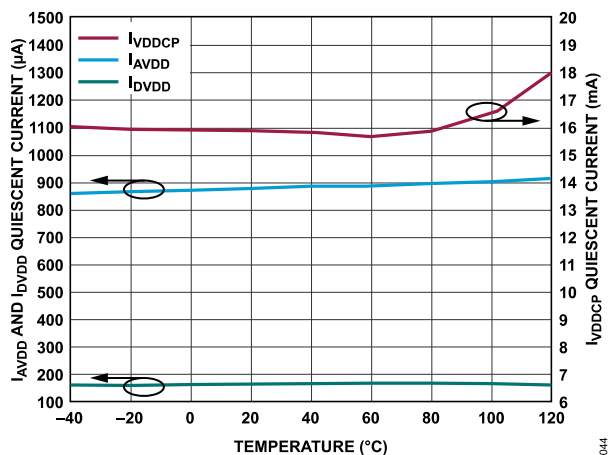
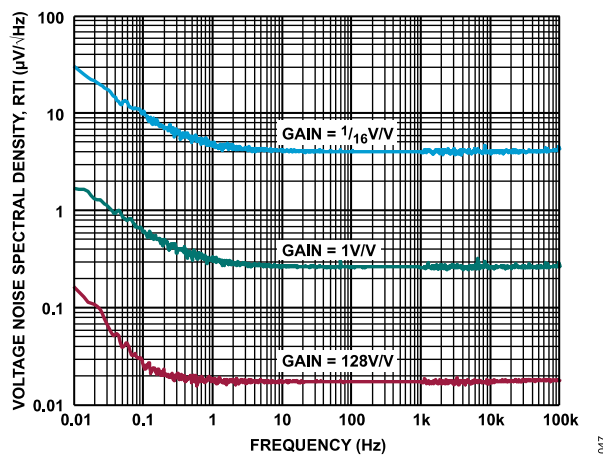
Figure 44.  $I_{AVDD}$ ,  $I_{DVDD}$ , and  $I_{VDDCP}$  Quiescent Current vs. Temperature

Figure 47. Voltage Noise Spectral Density, RTI vs. Frequency

## TYPICAL PERFORMANCE CHARACTERISTICS

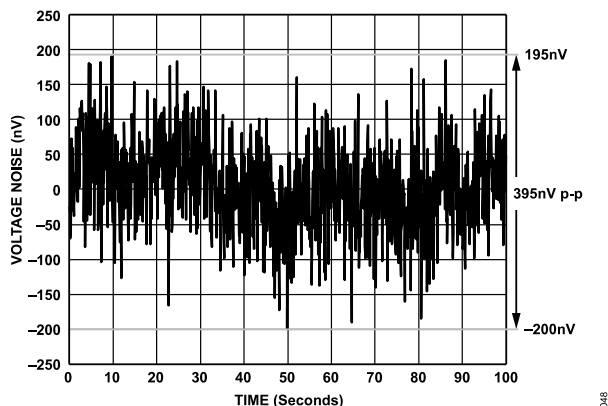


Figure 48. 0.01 Hz to 10 Hz Voltage Noise, RTI (Gain = 128 V/V)

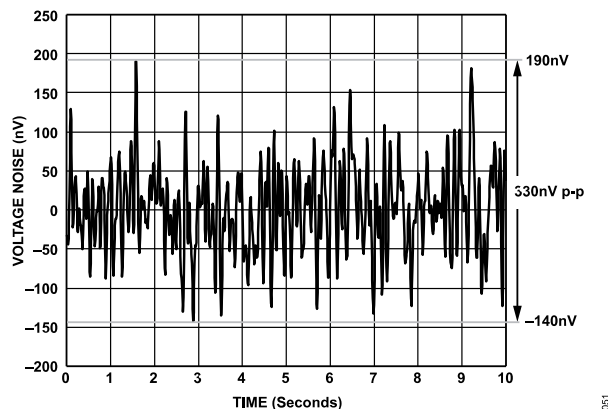


Figure 51. 0.1 Hz to 10 Hz Voltage Noise, RTI (Gain = 128 V/V)

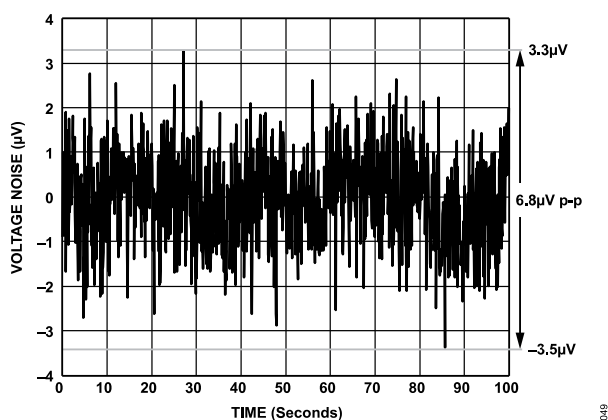


Figure 49. 0.01 Hz to 10 Hz Voltage Noise, RTI (Gain = 1 V/V)

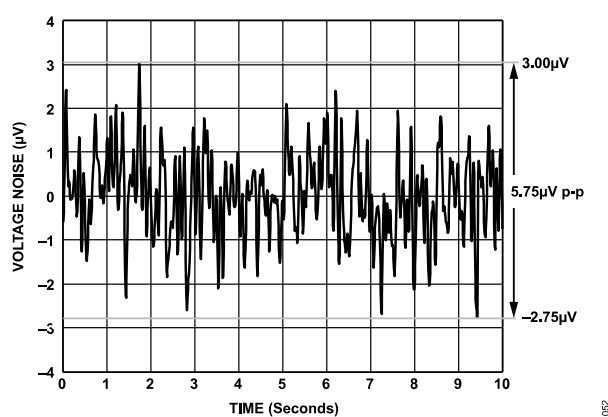


Figure 52. 0.1 Hz to 10 Hz Voltage Noise, RTI (Gain = 1 V/V)

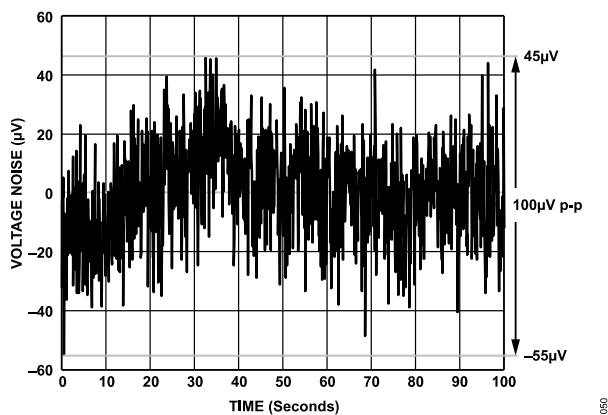


Figure 50. 0.01 Hz to 10 Hz Voltage Noise, RTI (Gain = 1/16 V/V)

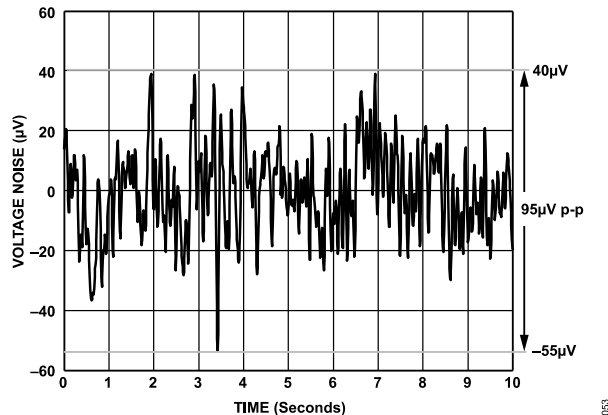


Figure 53. 0.1 Hz to 10 Hz Voltage Noise, RTI (Gain = 1/16 V/V)

## TYPICAL PERFORMANCE CHARACTERISTICS

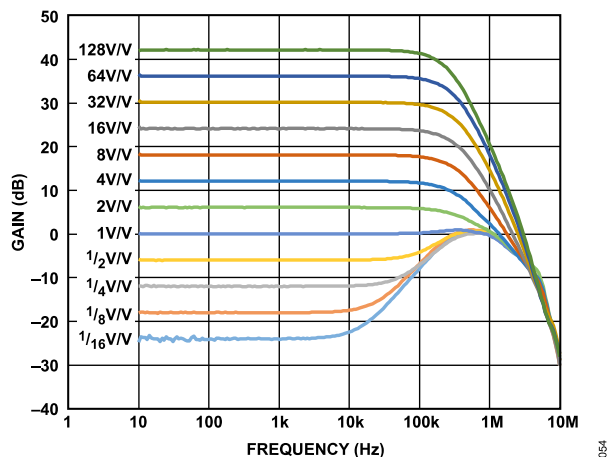


Figure 54. Small Signal Frequency Response

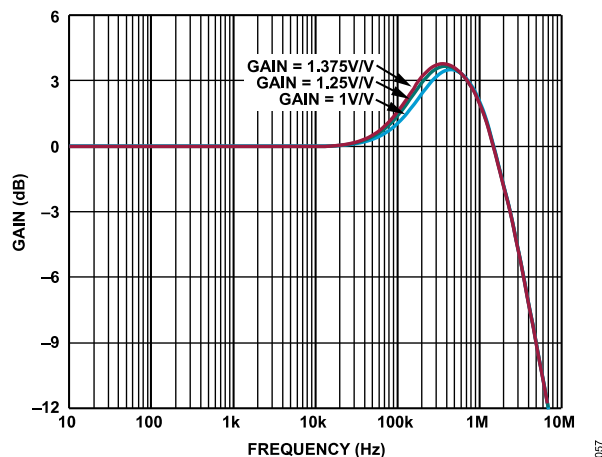


Figure 57. VOCM Small Signal Frequency Response

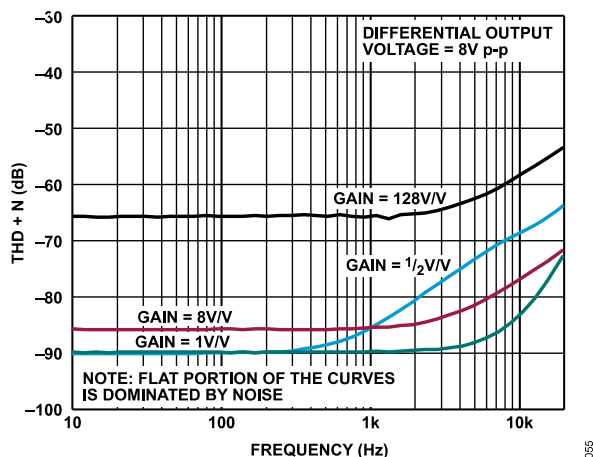
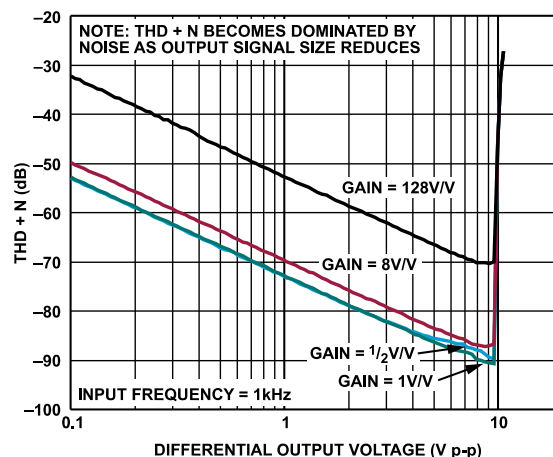
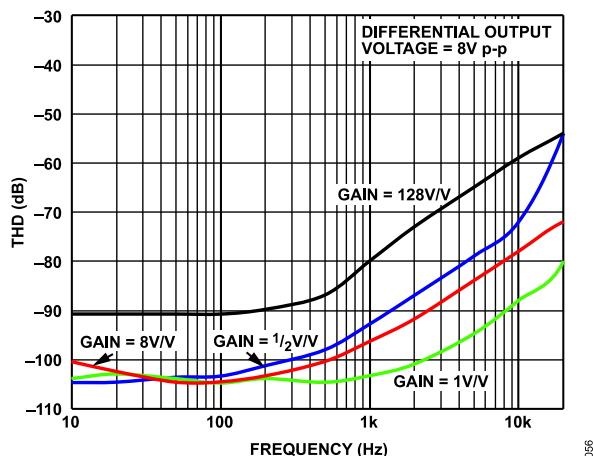
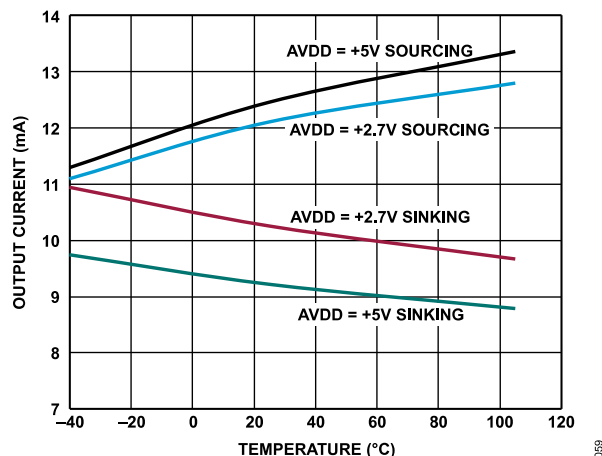
Figure 55. Total Harmonic Distortion Plus Noise (THD + N) vs. Frequency with 100 kHz Filter, Differential Load Resistor ( $R_{L, DIFF}$ ) = 5 k $\Omega$ Figure 58. THD + N vs. Differential Output Voltage with 100 kHz Filter,  $R_{L, DIFF}$  = 5 k $\Omega$ Figure 56. THD vs. Frequency,  $R_{L, DIFF}$  = 5 k $\Omega$ 

Figure 59. Sinking and Sourcing Short-Circuit Output Current vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS

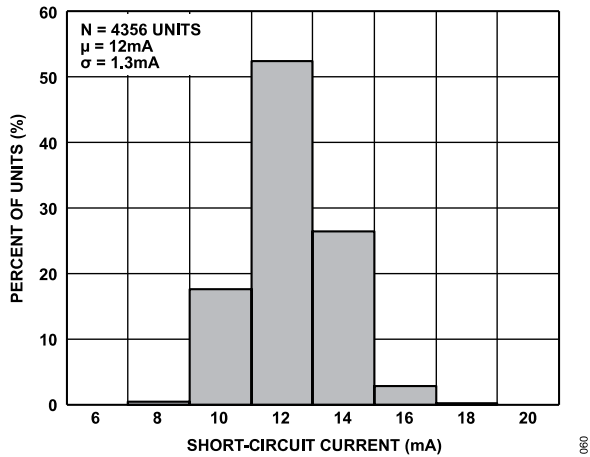


Figure 60. Sourcing Short-Circuit Current Distribution

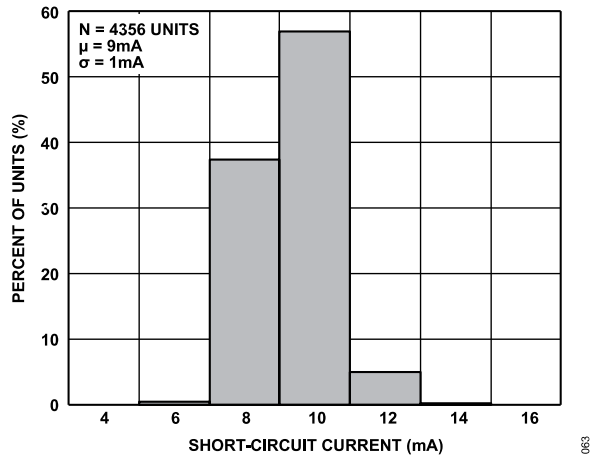


Figure 63. Sinking Short-Circuit Current Distribution

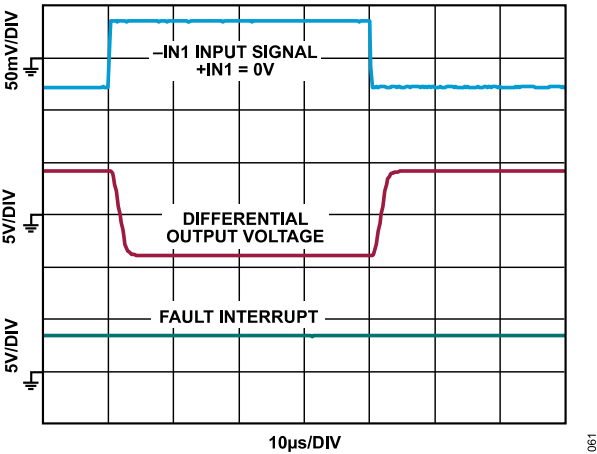


Figure 61. Large Signal Step Response (Gain = 128 V/V)

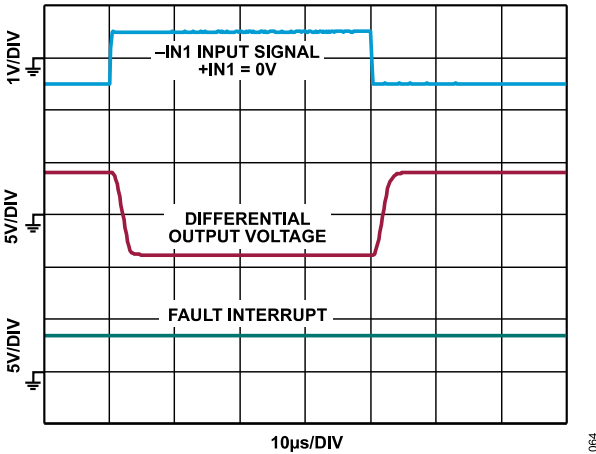


Figure 64. Large Signal Step Response (Gain = 8 V/V)

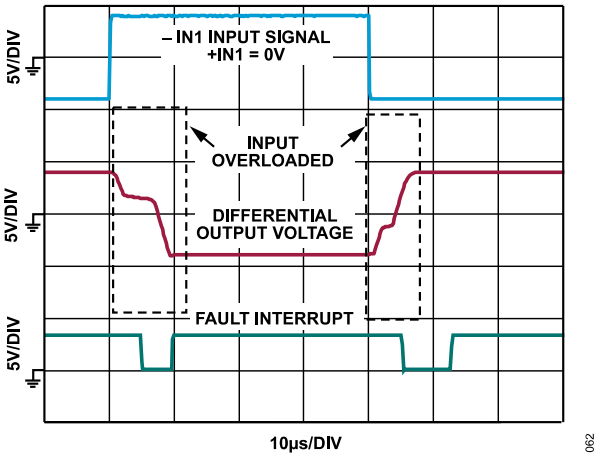


Figure 62. Input Overload Recovery Step Response (Gain = 1 V/V)

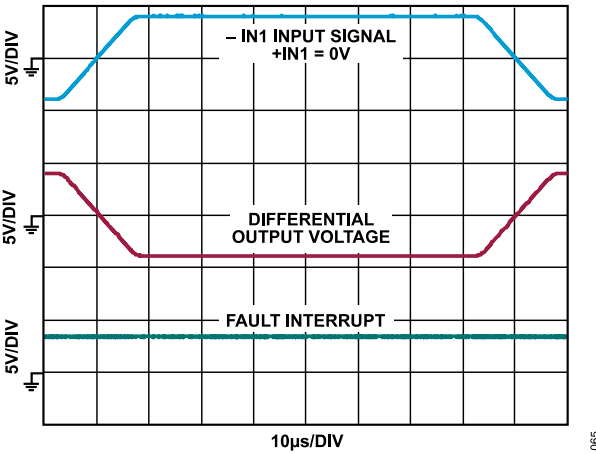


Figure 65. Large Signal Step Response (Gain = 1 V/V)

## TYPICAL PERFORMANCE CHARACTERISTICS

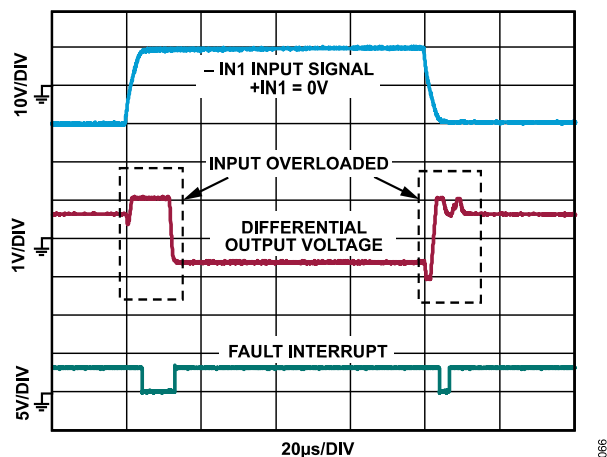


Figure 66. Input Overload Recovery Step Response (Gain = 1/16 V/V)

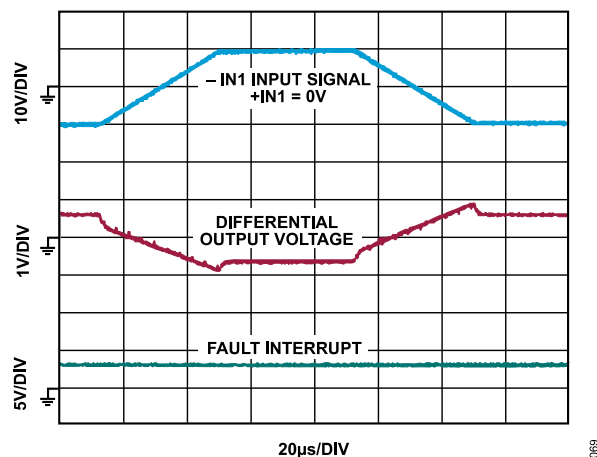


Figure 69. Large Step Response (Gain = 1/16 V/V)

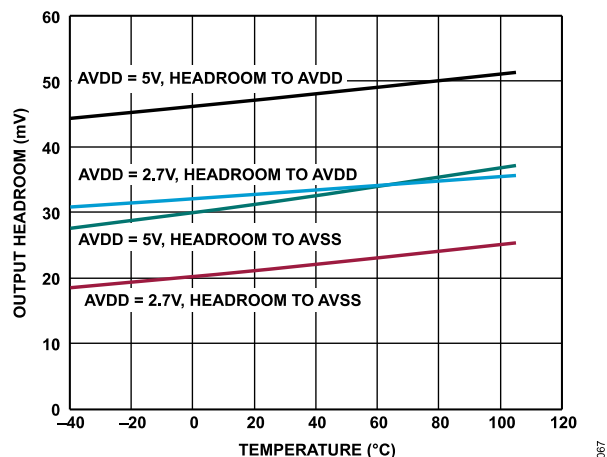


Figure 67. Output Headroom vs. Temperature

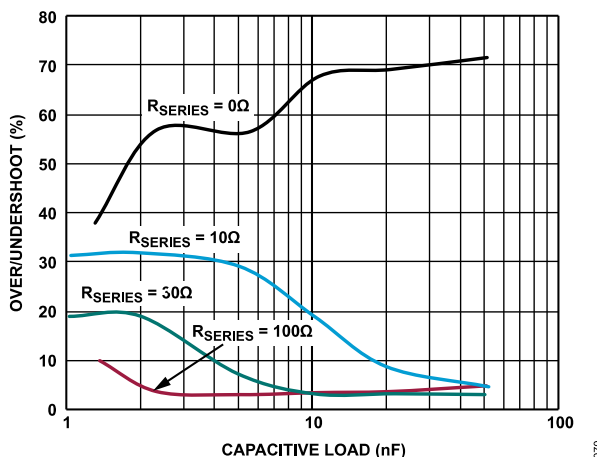


Figure 70. Overshoot and Undershoot vs. Capacitive Load

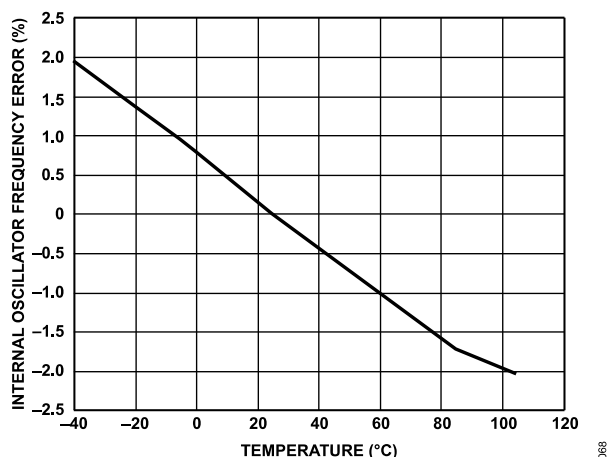


Figure 68. Internal Oscillator Frequency Error vs. Temperature

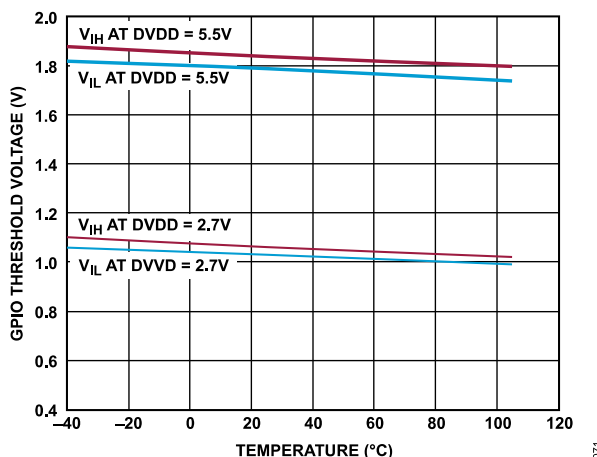


Figure 71. GPIO Threshold Voltage vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS

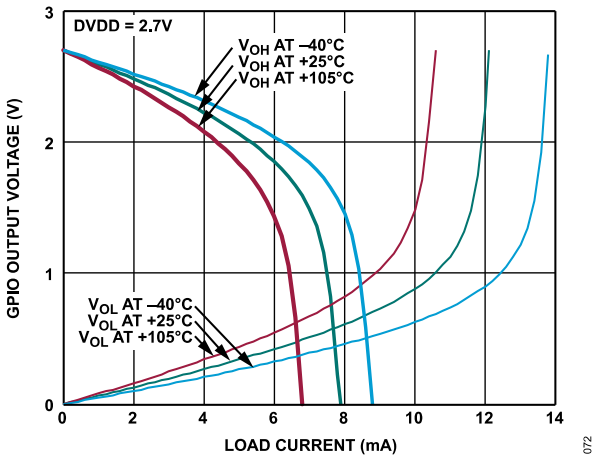


Figure 72. GPIO Output Voltage ( $V_{OH}/V_{OL}$ ) vs. Load Current for Various Temperatures, DVDD = 2.7 V

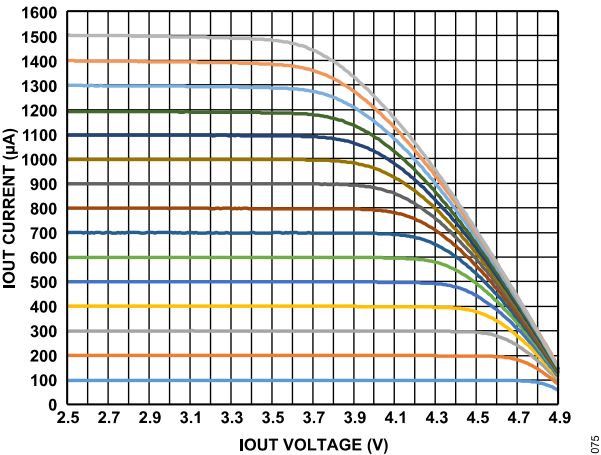


Figure 75. IOUT Current vs. IOUT Voltage

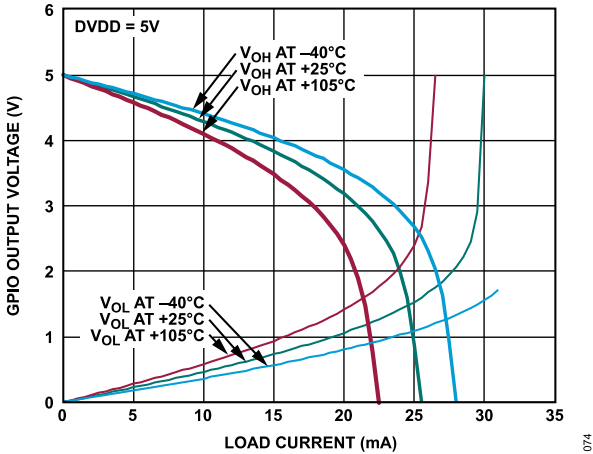


Figure 73. GPIO Output Voltage ( $V_{OH}/V_{OL}$ ) vs. Load Current for Various Temperatures, DVDD = 5 V

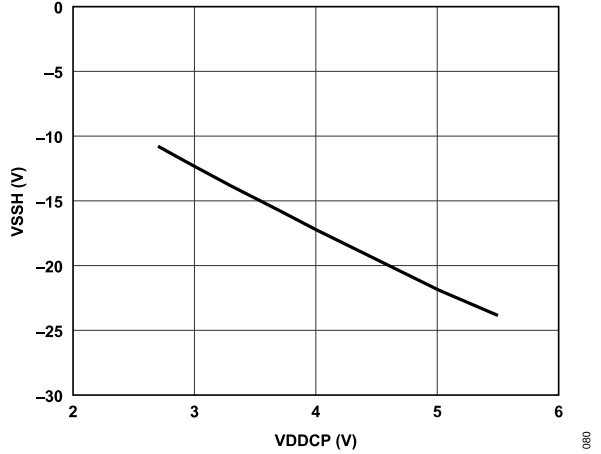


Figure 76. VSSH vs. VDDCP

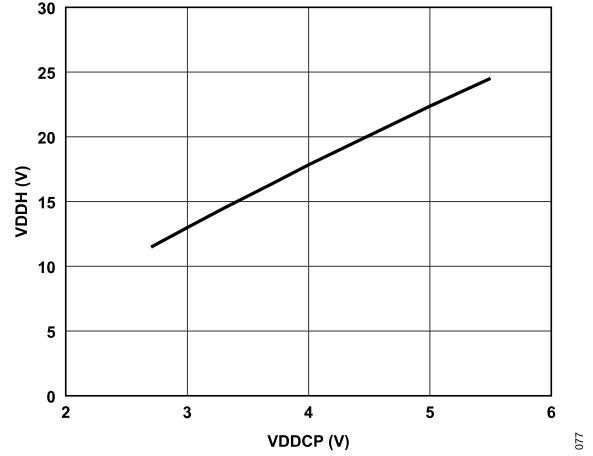


Figure 74. VDDH vs. VDDCP

## TYPICAL PERFORMANCE CHARACTERISTICS

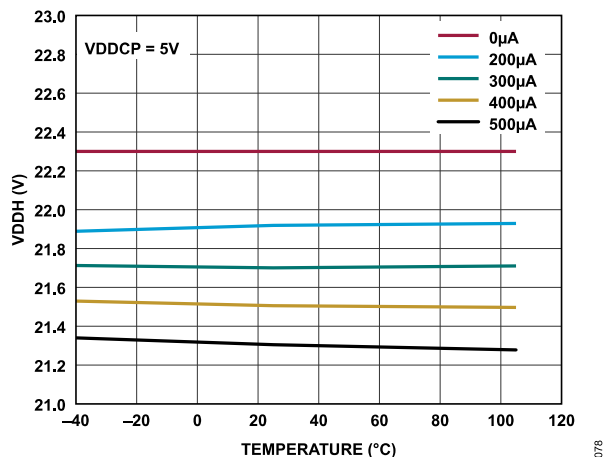


Figure 77. VDDH vs. Temperature for Various VDDH Loads, VDDCP = 5 V

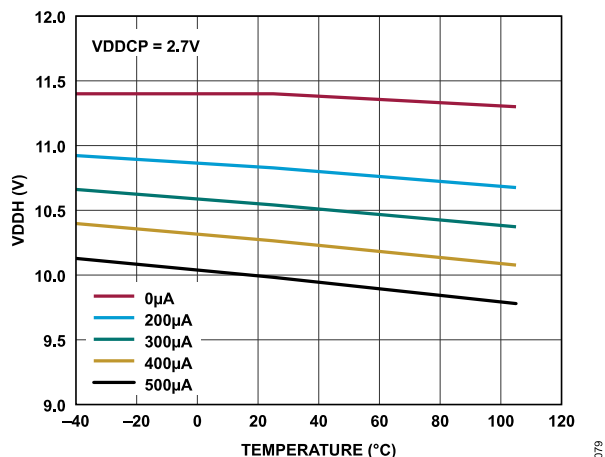


Figure 78. VDDH vs. Temperature for Various VDDH Loads, VDDCP = 2.7 V

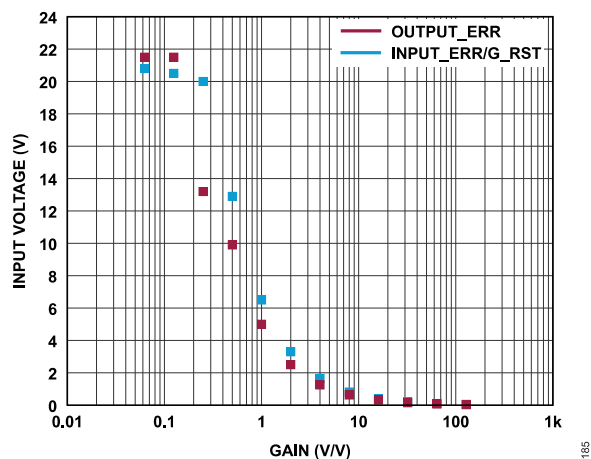


Figure 79. Positive Error Trip Thresholds with Single-Ended Input

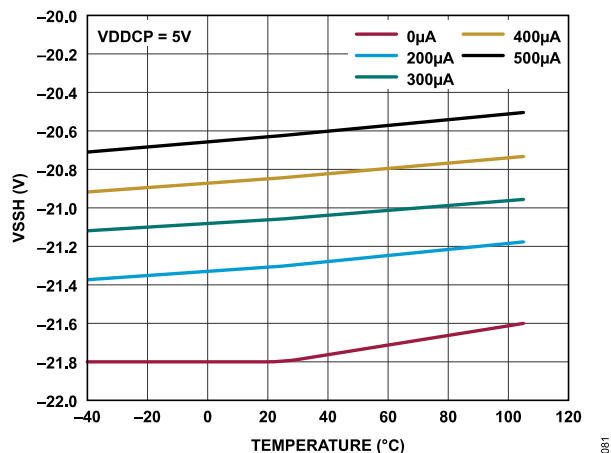


Figure 80. VSSH vs. Temperature for Various VSSH Loads, VDDCP = 5 V

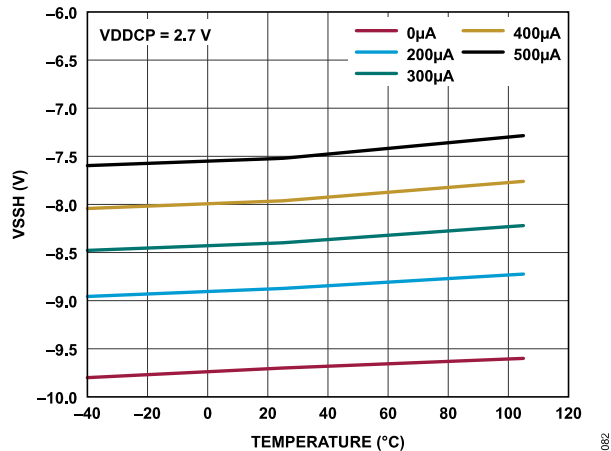


Figure 81. VSSH vs. Temperature for Various VSSH Loads, VDDCP = 2.7 V

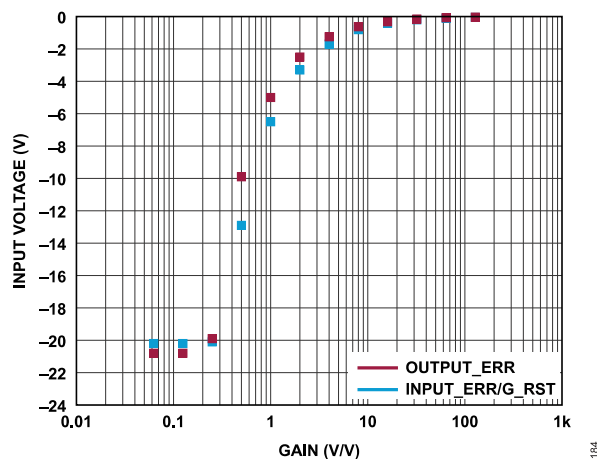


Figure 82. Negative Error Trip Thresholds with Single-Ended Input

TYPICAL PERFORMANCE CHARACTERISTICS

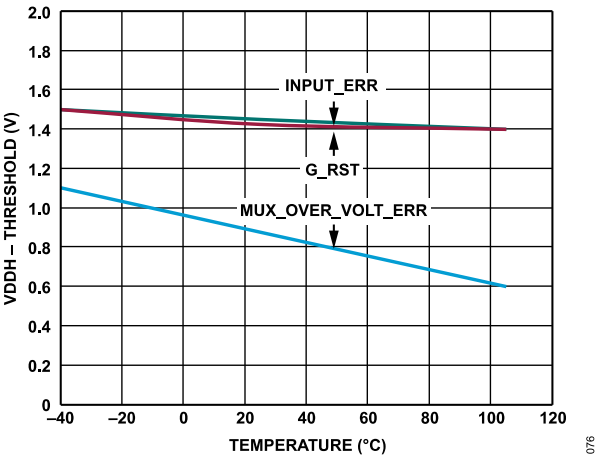


Figure 83. Error Flag Positive Trip Voltage (VDDH – Threshold) vs. Temperature

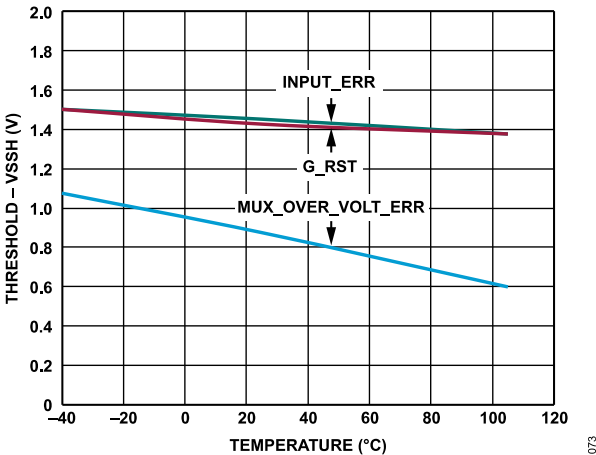


Figure 84. Error Flag Negative Trip Voltage (Threshold – VSSH) vs. Temperature



## THEORY OF OPERATION

## PROGRAMMABLE GAIN INSTRUMENTATION AMPLIFIER

The ADA4255 is a direct current mode instrumentation amplifier implemented with zero drift amplifiers. The ADA4255 topology ensures precision operation over temperature. Refer to the simplified architecture shown in Figure 85 to understand the following circuit description.

The input multiplexer connects the inputs to Amplifier A3 and Amplifier A7, which are configured to replicate these input voltages on the  $R_{IN}$  input resistor. The A1, A2, A5, and A6 amplifiers are configured to replicate the internal reference voltage,  $V_{REF}$ , on R1, R2, R5, and R6, creating four nominally equal dc bias currents in the drains of M1, M2, M5, and M6. Amplifier A4 and Amplifier A8 are configured to replicate the currents in R3 and R7 in the drains of M4 and M8, respectively, forming current mirrors.

When a positive voltage is applied to the ADA4255 inputs, a proportional current is conducted by  $R_{IN}$ . The drain currents of M3 and M4 increase by this amount, and the drain currents of M7 and M8 reduce by this amount. This portion of the amplifier operates as a transconductance with differential output, each having a gain of  $1/R_{IN}$ . Output Amplifier A9 is configured as a transimpedance amplifier with a gain of  $R_{OUT}$ . A9 provides a common-mode level shift to the output and produces the differential output voltage ( $V_{OUT, DIFF}$ ) as follows:

$$V_{OUT, DIFF} = \frac{(V_{+IN} - V_{-IN}) \times R_{OUT} \times 2}{R_{IN}} \quad (1)$$

where:

$V_{+IN}$  is the positive input voltage.

$V_{-IN}$  is the negative input voltage.

The overall gain of the ADA4255 amplifier is  $2 \times R_{OUT}/R_{IN}$ . The different gain settings are achieved by internally switching in different values for  $R_{OUT}$  and  $R_{IN}$ .

The value of  $R_{IN}$  can be set to 12 different values via the G3 to G0 bits, resulting in 12 binary weighted input gains. The value of  $R_{OUT}$  can also be set to three different values via G4 and G5, resulting in three output scaling gains. Table 6 shows the 36 possible gain configurations, making the ADA4255 versatile when interfacing with a wide selection of sensors and ADCs.

Table 6. Possible Gain Settings

| Input Gain | Output Scaling Gain (V/V) |          |          |
|------------|---------------------------|----------|----------|
|            | 1                         | 1.25     | 1.375    |
| 0.0625     | 0.0625                    | 0.078125 | 0.085938 |
| 0.125      | 0.125                     | 0.15625  | 0.171875 |
| 0.25       | 0.25                      | 0.3125   | 0.34375  |
| 0.5        | 0.5                       | 0.625    | 0.6875   |
| 1          | 1                         | 1.25     | 1.375    |
| 2          | 2                         | 2.5      | 2.75     |
| 4          | 4                         | 5        | 5.5      |
| 8          | 8                         | 10       | 11       |
| 16         | 16                        | 20       | 22       |
| 32         | 32                        | 40       | 44       |
| 64         | 64                        | 80       | 88       |
| 128        | 128                       | 160      | 176      |

Each amplifier used in the ADA4255 uses a proprietary, zero drift architecture to ensure low offset voltage, offset voltage drift, and 1/f noise.

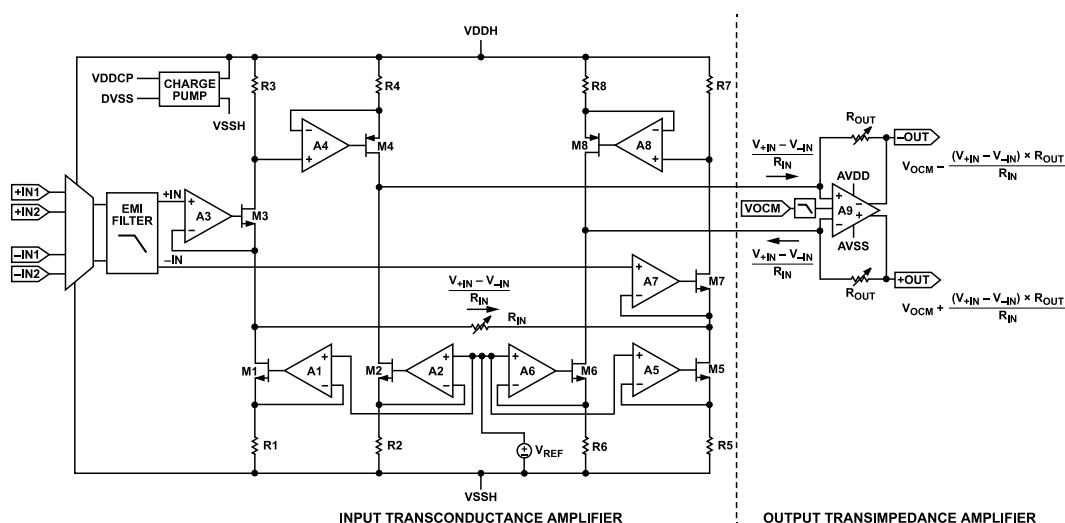


Figure 85. Simplified ADA4255 Programmable Gain Instrumentation Amplifier Topology

## THEORY OF OPERATION

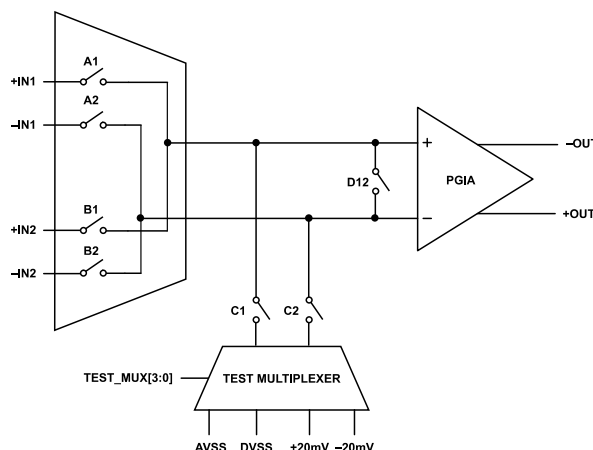


Figure 86. Input Switch Configuration

## INPUT MULTIPLEXER

The ADA4255 input multiplexer withstands input voltages up to  $\pm 60$  V with respect to VSSH and 60 V differentially. As shown in Figure 86, the multiplexer switches between the two sets of inputs and features additional switch functionality on the output of the multiplexer. Input switching is controlled via the INPUT\_MUX register. The A1, A2, B1, and B2 switches connect the different inputs to the amplifier. The C1 and C2 switches connect the multiplexer outputs to the test multiplexer. Switch D12 connects both inputs together. The input multiplexer features <140 dB of crosstalk.

If excessive input voltage is detected by the input multiplexer, MUX\_OVER\_VOLT\_ERR in the ANALOG\_ERR register trips. When this error flag is set, the multiplexer automatically opens A1, A2, B1, and B2 to protect the input amplifier and input resistor network. This error flag can be disabled by setting MUX\_OVER\_VOLT\_ERR\_DIS (Register ANALOG\_ERR\_DIS). By default, both sets of inputs cannot be selected simultaneously. This protection can be overridden via the MUX\_PROT\_DIS bit in the ANALOG\_ERR\_DIS register.

## EMI REDUCTION AND THE INTERNAL EMI FILTER

In many industrial and data acquisition applications, the ADA4255 amplifies small signals accurately in the presence of large common-mode voltages or high levels of noise. Typically, the sources of these small signals (in the order of microvolts or millivolts) are sensors that may be a significant distance from the signal conditioning circuit. Although these sensors may be connected to signal conditioning circuitry using shielded or unshielded twisted pair cabling, the cabling may act as an antenna, conveying high frequency interference directly to the inputs of the ADA4255.

The amplitude and frequency of this high frequency interference can have an adverse effect on the input stage of the instrumentation amplifier due to unwanted dc shift in the input offset voltage of the amplifier. This well known effect is called EMI rectification and

is produced when out of band interference is coupled (inductively, capacitively, or via radiation) and rectified by the input transistors of the instrumentation amplifier. These transistors act as high frequency signal detectors, in the same way diodes were used as RF envelope detectors in early radio designs. Regardless of the type of interference or the method by which it is coupled to the circuit, an out of band error signal appears in series with the inputs of the instrumentation amplifier.

To minimize this effect, the ADA4255 has 35 MHz on-chip EMI filters to attenuate high frequencies before interacting with the input transistors. These on-chip filters are well matched due to their monolithic construction, which minimizes degradation in ac CMRR. To reduce any further effect of these out of band signals on the input offset voltage of the ADA4255, an additional external low-pass filter can be used at the inputs. Locate the filter very close to the input pins of the circuit. An effective filter configuration is shown in Figure 87 where three capacitors are added to the ADA4255 inputs. The filter limits the input signal according to the following relationship:

$$\text{Filter Frequency}_{DIFF} = \frac{1}{2\pi R(2C_D + C_C)} \quad (2)$$

$$\text{Filter Frequency}_{CM} = \frac{1}{2\pi RC_C} \quad (3)$$

where:

$C_D$  is the differential capacitor and is  $\geq 10C_C$ .

$C_C$  is the common-mode capacitor.

$C_D$  affects the difference signal, and  $C_C$  affects the common-mode signal. Any mismatch in  $R \times C_C$  degrades the ADA4255 CMRR. To avoid inadvertently reducing CMRR bandwidth performance, ensure that  $C_C$  is at least one magnitude smaller than  $C_D$ . The effect of mismatched  $C_C$  values is reduced with a larger  $C_D:C_C$  ratio.

## THEORY OF OPERATION

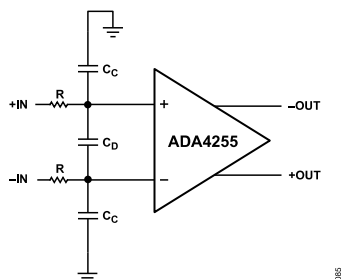


Figure 87. External EMI Filter Improves Noise Rejection

## INPUT AMPLIFIER

The ADA4255 input amplifier operates on internally generated high voltage power supplies, VDDH and VSSH. On-chip charge pumps are used by the ADA4255 to generate VDDH and VSSH from the VDDCP supply.

The input amplifiers are internally monitored for clipping due to excessive signal swing. If excessive output swing is detected by any part of the input amplifier (A1 to A8 in Figure 85), the INPUT\_ERR flag trips. If INPUT\_ERR is tripped for more than 200  $\mu$ s, the gain settings in the GAIN\_MUX register are reset to their default values and the G\_RST flag trips. By default, the G\_RST event sets all gain bits in the GAIN\_MUX register to their default values, which may also result in a MM\_CRC\_ERR. The gain reset function can be disabled via the G\_RST\_DIS bit.

## OUTPUT AMPLIFIER

The ADA4255 features a fully differential output amplifier running from the dedicated low voltage supplies, AVDD and AVSS. Use AVDD and AVSS in a single-supply configuration. By running the output amplifier on low voltage supplies, circuitry connected to the output of the ADA4255 is inherently protected. The common-mode output voltage is set by the VOCM input voltage. VOCM has a high input impedance and is not biased internally. VOCM also features a 29 MHz EMI filter to minimize EMI interference. Typically, VOCM is biased to midsupply through a voltage divider between AVDD and AVSS to allow the widest swing on the output. The output amplifier can be set to three different scaling gains via G4 or G5: 1 V/V, 1.25 V/V, or 1.375 V/V. On power-up or soft reset, the output amplifier scaling gain defaults to 1 V/V. The output amplifier is monitored for clipping due to excessive signal swing. When the output saturates to either supply, the OUTPUT\_ERR flag trips.

The differential output stage of the ADA4255 allows the device to be directly connected to high precision ADCs, such as the AD7768 and the AD4007. When making such a connection, it is recommended to use a low-pass filter to minimize noise and aliasing, as shown in Figure 88. The LTC6363 is configured as a 3-pole, low-pass filter with a cutoff frequency of 40 kHz.

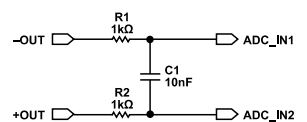


Figure 88. Simple Output Filter Preventing Aliasing and Filters Switching Noise

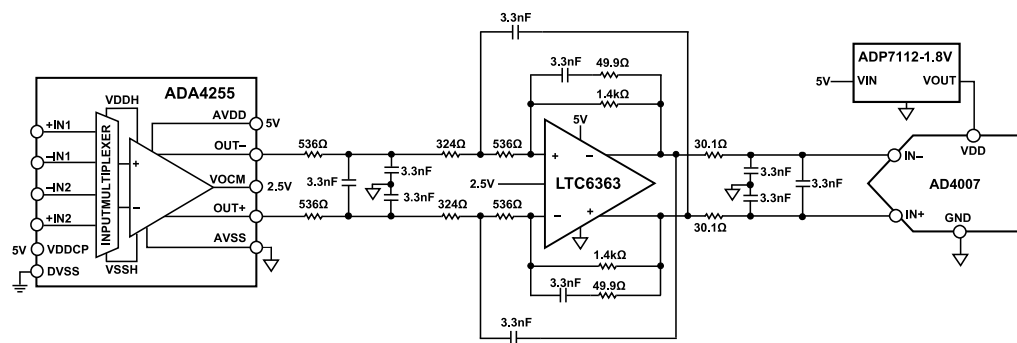


Figure 89. LTC6363 Used as a Low-Pass Filter and Driver

## THEORY OF OPERATION

## POWER SUPPLIES

The ADA4255 requires that three low voltages supplies be powered: the low voltage charge pump supply (VDDCP), the low voltage analog output amplifier supply (AVDD), and the low voltage digital supply (DVDD).

The low voltage charge pump supply is used internally to generate high voltage, bipolar supplies VDDH and VSSH, which power the input amplifier of the ADA4255. On-chip high voltage supply generation allows the ADA4255 to be isolated using only low voltage components while maintaining high voltage, high impedance input operation. The equations for typical VDDH and VSSH are as follows:

$$\begin{aligned} VDDH &= 4.65 \times VDDCP - 0.9 \text{ V} \\ VSSH &= -4.65 \times VDDCP + 1.6 \text{ V} \end{aligned}$$

VDDH and VSSH are output to pins so that the required external decoupling capacitance can be applied. This decoupling is not optional and is required to stabilize VDDH and VSSH. Figure 90 shows the minimum recommended 10  $\mu\text{F}$  and 0.1  $\mu\text{F}$  decoupling capacitors connected to VDDH and VSSH. Up to 500  $\mu\text{A}$  of additional load current can be sourced by VDDH or sunk by VSSH with the charge pump clock at its default of 16 MHz. The charge pump frequency can be reduced to 8 MHz, which results in lower current consumption on VDDCP.

VSSH is connected to the substrate of the ADA4255. Therefore, VSSH must be connected to the most negative supply voltage in the circuit, and VSSH must not exceed AVSS. It is recommended to use a Schottky diode to clamp VSSH to AVSS. The Schottky diode must have a forward bias voltage of 0.3 V or lower at 1 mA and withstand  $-28 \text{ V}$  of reverse voltage. The ADA4255 monitors the VDDH and VSSH supplies to detect if the VDDH or VSSH drops below 8 V and sets the POR\_HV flag.

The low voltage analog output amplifier supply, AVDD and AVSS, powers the output amplifier of the ADA4255. AVSS must be within  $VSSH - 0.3 \text{ V}$  to  $VSSH + 30 \text{ V}$  and  $VDDH - 30 \text{ V}$  to  $VDDH + 0.3 \text{ V}$ . AVDD - AVSS is typically a 5 V single supply, compatible with most high precision ADCs. Use 0.1  $\mu\text{F}$  and 10  $\mu\text{F}$  decoupling capacitors between AVDD and AVSS as close as possible to the AVDD and AVSS supply pins.

The digital supplies, DVDD and DVSS, power the digital circuitry inside the ADA4255. DVSS must be the same potential as AVSS. Use 0.1  $\mu\text{F}$  and 10  $\mu\text{F}$  decoupling capacitors from DVDD to DVSS as close as possible to the DVDD and DVSS supply pins. Figure 90 shows a typical ADA4255 supply configuration. The recommended decoupling values described in this section are minimum recommendations. Depending on amplifier loading and system noise, higher capacitance values and/or additional lower capacitor values may improve performance.

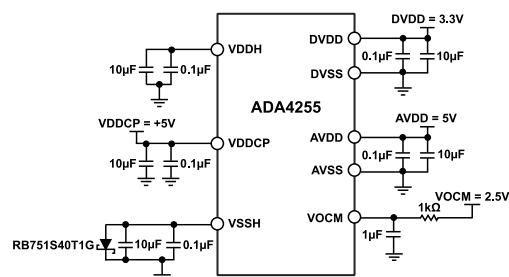


Figure 90. Typical ADA4255 Power Supply Configuration

## ESD MAP

Figure 91 shows the various ESD diode paths inside the ADA4255. Figure 91, in conjunction with the Absolute Maximum Ratings section, helps in understanding current paths during power-on and fault conditions.

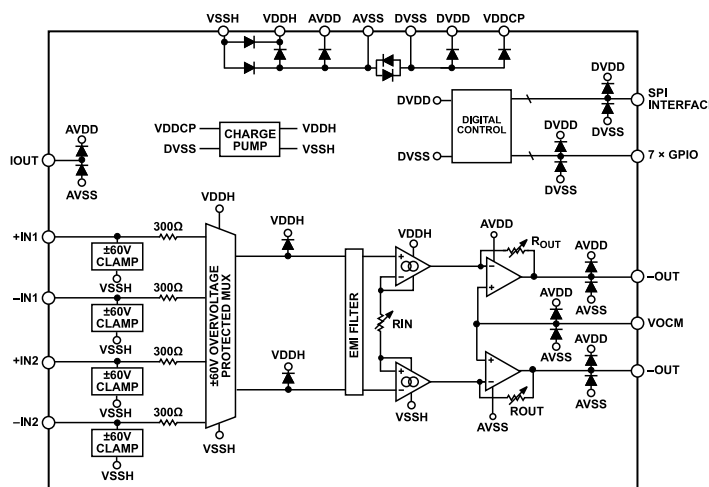


Figure 91. ESD Map

## THEORY OF OPERATION

### OUTPUT RIPPLE CALIBRATION CONFIGURATION

The amplifiers inside the ADA4255 achieve zero drift by using a technique commonly referred to as chopping. When chopping is used to null the offset of an amplifier, the unchopped offsets are modulated to the frequency at which the chopping is performed. All chopping amplifiers feature this phenomenon, which is commonly referred to as ripple.

The ADA4255 instrumentation amplifier features a proprietary calibration routine that reduces the residual voltage ripple at the output of the ADA4255 by nulling the internal offsets of all amplifiers. This calibration occurs automatically when the ADA4255 is initially powered on, after a POR\_HV event, or after a soft reset occurs. Further calibrations can be performed either on a scheduled or triggered basis.

While the ADA4255 is calibrating, the SW\_A1, SW\_A2, SW\_B1, and SW\_B2 bits (Register INPUT\_MUX) are temporarily opened and the amplifier inputs are internally connected to AVSS through the SW\_C1 and SW\_C2 bits (Register INPUT\_MUX). After a calibration completes, the switches return to their previous states. Two calibration types can be selected via the CAL\_SEL bit (Register TEST\_MUX): full calibration or quick calibration.

A full calibration sequentially calibrates each individual amplifier and fully computes a new calibration code. This calibration takes approximately 85 ms. Full calibration always occurs after power-up, after a POR\_HV event, or after a soft reset.

A quick calibration calculates a new calibration code for all amplifiers at the same time. The calibration code of each amplifier is then adjusted by an incremental amount. This type of calibration takes approximately 8 ms.

By default, calibrations only occur after power-up, after a POR\_HV event, or after a reset. Additional scheduled calibrations are configured via CAL\_EN (Register TEST\_MUX), or are triggered via the TRIG\_CAL bit (Register TRIG\_CAL).

When scheduled calibrations are configured via the CAL\_EN bits (Register TEST\_MUX), the selected calibration type occurs at the rate configured via the CAL\_EN bits.

Calibrations can also be manually triggered via the TRIG\_CAL bit (Register TRIG\_CAL).

The internal offsets, which are nulled by the ADA4255 calibration routine, can change when the circuit or the environmental conditions change. Changes in temperature, supply voltage, common-mode input voltage, time, and so on, can all cause an increase in output ripple. Recalibrations, either triggered or scheduled, renul internal offsets and reduce residual output ripple.

During a calibration, noise can limit the ability of the ADA4255 to fully null internal offsets and fully reduce the residual output ripple. Proper decoupling and shielding techniques help ensure ac-

curate calibrations. Avoid large input transients during calibrations. Calibrations typically reduce the output ripple to <200  $\mu$ V rms, but results as high as 5 mV rms can be observed in the presence of noise or input transients. If excessive residual ripple is detected, subsequent calibrations can be performed to reduce the output ripple.

ADC synchronization and simple filtering, either passive or active, are also effective methods in reducing residual output ripple. These techniques are discussed in detail in the [External Clock Synchronization](#) section and the [Output Amplifier](#) section.

### GENERAL-PURPOSE INPUTS AND OUTPUTS (GPIOs)

The ADA4255 features several multifunction GPIOx pins. These GPIOx pins can be configured to either read a logic input or output a logic signal. A GPIOx pin is configured as an input or an output using the GPIO\_DIR register. The bit position in the GPIO\_DIR register corresponds to the GPIOx pin number. For example, the bit at Position 0 controls the GPIO0 direction.

The GPIO\_DATA register sets the GPIO output when a GPIOx pin is configured as an output. The GPIO\_DATA register also reads the data at the GPIOx pin when a GPIO is configured as an input. The bit field position in the GPIO\_DATA register corresponds to the GPIOx pin number. For example, the bit at Position 0 corresponds to GPIO0.

The ADA4255 GPIOx pins can be configured to perform additional special functions.

Each GPIO can be configured as an output to extend the chip select signal from the SPI master to other slave devices. This special functionality is referred to as sequential chip select and is particularly useful in limiting the number of communication lines that need to be routed and/or isolated in a system. This special functionality is controlled by the SCS register.

GPIO0 and GPIO1 can also be configured as external multiplexer control signals. This function is enabled in the special function register, SF\_CFG. After GPIO0 and GPIO1 are configured as outputs, the EXT\_MUX bit field in the GAIN\_MUX register controls the state of GPIO0 and GPIO1, allowing the gain and the external mux setting to be modified with one write operation.

GPIO2 can be configured to output a calibration busy signal. This function is enabled via the CAL\_BUSY\_OUT bit (Register SF\_CFG). The calibration busy signal indicates that the ADA4255 is performing a calibration routine. GPIO2 must be configured as an output to use this special function.

GPIO3 can be configured to output a fault interrupt signal. This signal is an OR function of all the analog and digital error indicators found in the ANALOG\_ERR and DIGITAL\_ERR registers. This function is enabled via the FAULT\_INT\_OUT bit (Register SF\_CFG). GPIO3 must be configured as an output to use this special function.



## THEORY OF OPERATION

When configured as an output, GPIO4 can be configured to output the 1 MHz master clock or the 125 kHz chopping clock. This output is configured via the INT\_CLK\_OUT bit (Register SF\_CFG) and the CLK\_OUT\_SEL bit (Register SYNC\_CFG). When configured as an input, GPIO4 can also accept an external clock. This function is configured via the EXT\_CLK\_IN bit (Register SF\_CFG).

### EXCITATION CURRENTS

The ADA4255 features a configurable excitation current source, IOUT. This current source can be used to excite external circuitry, such as resistive bridges or RTD sensors.

The current output is controlled via the EX\_CURRENT bits (Register EX\_CURRENT\_CFG).

### EXTERNAL CLOCK SYNCHRONIZATION

The ADA4255 uses an internal 1 MHz master clock. The master clock is used to derive the 125 kHz chopping clock used by the internal amplifiers and the 16 MHz clock used by the charge pumps.

Either the 1 MHz or the 125 kHz clock can be brought out on the GPIO4 pin to allow synchronization of external systems. Use the following procedure to enable the external clock synchronization feature:

1. Configure GPIO4 as an output by setting Bit 4 in the GPIO\_DIR register to 1.
2. Enable the internal oscillator output special function by setting the INT\_CLK\_OUT bit to 1 and the EXT\_CLK\_IN bit to 0 in the SF\_CFG register.
3. To output the 125 kHz clock, set the CLK\_OUT\_SEL bit in the SYNC\_CFG register to 1. To output the 1 MHz clock, set the CLK\_OUT\_SEL bit to 0.

The ADA4255 can alternatively be configured to accept an external clock on GPIO4. The ADA4255 allows external clocks ranging from 1 MHz up to 32 MHz. In the case of an external clock that is higher than 1 MHz, the input clock must be divided down to 1 MHz using the internal clock divider. The edge on which the ADA4255 synchronizes can also be configured.

Use the following procedure to configure the ADA4255 to accept an external clock on GPIO4:

1. Configure GPIO4 as an input by setting Bit 4 in the GPIO\_DIR register to 0.
2. Set the EXT\_CLK\_IN bit to 1 and ensure that the INT\_CLK\_OUT bit is set to 0 in the SF\_CFG register.
3. Depending on the frequency of the input clock, configure the internal clock divider value such that the resulting clock is 1 MHz. The internal clock divider value is controlled by the SYNC bits in the SYNC\_CFG register.
4. For synchronizing on the rising edge, set the SYNC\_POL bit in the SYNC\_CFG register to 1. For synchronizing on the falling edge, set SYNC\_POL to 0.

To maintain the performance of the ADA4255, the external clock must be in the specified range, must always be present, and must have a duty-cycle of 50%. The quality of the clock used may affect the device performance. Prevent any overshoot or undershoot on the clock used, and provide an equal rise and fall to minimize the impact on the offset voltage.

### SEQUENTIAL CHIP SELECT (SCS)

SCS is one of the special functions on the ADA4255 that can be configured on the GPIOx pins. This mode simplifies isolation requirements by allowing multiple slave devices to communicate over the SPI using a single host chip select ( $\overline{CS}$ ) line. This communication also supports cyclical redundancy check (CRC) checksums transparently.

A GPIO is configured for SCS by first setting the GPIOx pin as an output using the GPIO\_DIR bit (Register GPIO\_DIR), and then setting the respective bit in the SCS register. Configuring a GPIOx pin for SCS mode is blocked if the GPIOx pin is already configured for another function from the special functions register, SF\_CFG.

When using SCS, the  $\overline{CS}$  signal from the SPI host controller is provided to the  $\overline{CS}$  pin of the ADA4255. The serial data input (SDI), serial data output (SDO), and serial clock (SCLK) are shared connections with other SPI devices. The ADA4255 SDO pin supports tristate operation. Slave SDO pins can be directly connected to SDO if the slave pins support tristate operation. For slave devices with SDO pins that do not support tristate operation, an OR gate can be used to combine the SDO signals. If external logic is used to combine SDO lines, pull-down or pull-up resistors are recommended to avoid floating logic gate inputs. [Figure 92](#) and [Figure 93](#) show typical implementations. It is recommended to place pull-up resistors on the GPIOx pins configured in SCS mode to prevent any unintended communication with the slave devices when configuring the ADA4255 in SCS mode.

## THEORY OF OPERATION

When configured for SCS mode, communication with the ADA4255 and all slave devices follows a predefined pattern. The first  $\overline{CS}$  pulse is passed to the first GPIOx that is set up for SCS mode, effectively communicating with the first slave device. Subsequent  $\overline{CS}$  pulses progress through any GPIOx pins configured for SCS mode in ascending order. The last  $\overline{CS}$  pulse addresses the ADA4255 itself. This pattern repeats until SCS mode is disabled.

Figure 92 and Figure 93 show the ADA4255 operating in SCS mode with GPIO0 and GPIO1 communicating with two slave devices. GPIO0 is connected to the  $\overline{CS}$  line of an ADC, and GPIO1 is connected to the  $\overline{CS}$  line of a digital-to-analog converter (DAC).

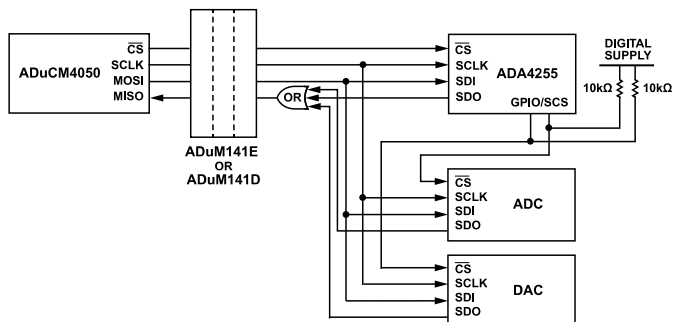


Figure 92. Typical SCS Implementation with Devices Without SDO Tristate Support

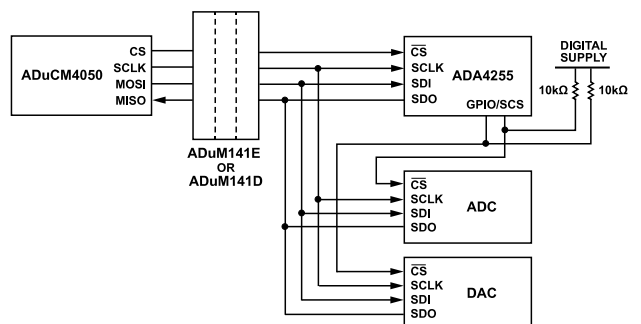


Figure 93. Typical SCS Implementation with All Devices Supporting SDO Tristate

## THEORY OF OPERATION

In Figure 94, five distinct  $\overline{CS}$  pulses can be seen. The first  $\overline{CS}$  pulse writes 0x03 to the GPIO\_DIR register to configure GPIO0 and GPIO1 as outputs. The second  $\overline{CS}$  pulse writes 0x03 to SCS to configure GPIO0 and GPIO1 for SCS mode. The third  $\overline{CS}$  pulse is replicated on GPIO0 and communicates with the first slave device, an ADC in this case. The fourth  $\overline{CS}$  pulse is replicated on GPIO1 and communicates with the second slave device, a DAC in this case. The fifth  $\overline{CS}$  pulse communicates with the ADA4255 itself. This pattern of communication continues in order of ADC, DAC, and ADA4255 until SCS is changed.

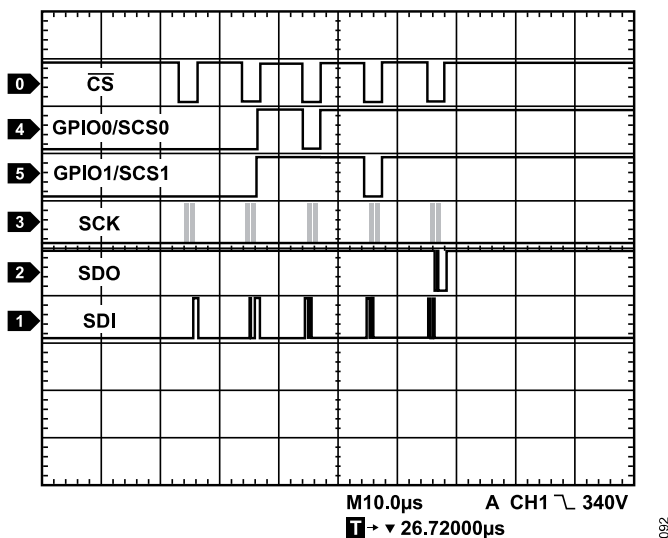


Figure 94. SCS Configuration and Operation with Two Slave Devices

Table 7. Gain Calibration Register Contents<sup>1</sup>

| Register | Name       | G[3:0] | G4 | G5 | Contents  |
|----------|------------|--------|----|----|---|
| 0x10     | GAIN_CAL1  | 0b0000 | 0  | 0  | Gain error for $G = 1/16 \text{ V/V} \times 1 \text{ V/V}$  |
| 0x11     | GAIN_CAL2  | 0b0001 | 0  | 0  | Gain error for $G = 1/8 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x12     | GAIN_CAL3  | 0b0010 | 0  | 0  | Gain error for $G = 1/4 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x13     | GAIN_CAL4  | 0b0011 | 0  | 0  | Gain error for $G = 1/2 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x14     | GAIN_CAL5  | 0b0100 | 0  | 0  | Gain error for $G = 1 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x15     | GAIN_CAL6  | 0b0101 | 0  | 0  | Gain error for $G = 2 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x16     | GAIN_CAL7  | 0b0110 | 0  | 0  | Gain error for $G = 4 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x17     | GAIN_CAL8  | 0b0111 | 0  | 0  | Gain error for $G = 8 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x18     | GAIN_CAL9  | 0b1000 | 0  | 0  | Gain error for $G = 16 \text{ V/V} \times 1 \text{ V/V}$  |
| 0x19     | GAIN_CAL10 | 0b1001 | 0  | 0  | Gain error for $G = 32 \text{ V/V} \times 1 \text{ V/V}$  |
| 0x1A     | GAIN_CAL11 | 0b1010 | 0  | 0  | Gain error for $G = 64 \text{ V/V} \times 1 \text{ V/V}$  |
| 0x1B     | GAIN_CAL12 | 0b1011 | 0  | 0  | Gain error for $G = 128 \text{ V/V} \times 1 \text{ V/V}$   |
| 0x1C     | GAIN_CAL13 | 0b000x | 1  | X  | Additional gain error for $G = 1/16 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 1/8 \text{ V/V} \times 1.375 \text{ V/V}$ |
| 0x1D     | GAIN_CAL14 | 0b001x | 1  | X  | Additional gain error for $G = 1/4 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 1/2 \text{ V/V} \times 1.375 \text{ V/V}$  |
| 0x1E     | GAIN_CAL15 | 0b010x | 1  | X  | Additional gain error for $G = 1 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 2 \text{ V/V} \times 1.375 \text{ V/V}$      |
| 0x1F     | GAIN_CAL16 | 0b011x | 1  | X  | Additional gain error for $G = 4 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 8 \text{ V/V} \times 1.375 \text{ V/V}$      |
| 0x20     | GAIN_CAL17 | 0b100x | 1  | X  | Additional gain error for $G = 16 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 32 \text{ V/V} \times 1.375 \text{ V/V}$    |
| 0x21     | GAIN_CAL18 | 0b101x | 1  | X  | Additional gain error for $G = 64 \text{ V/V} \times 1.375 \text{ V/V}$ or $G = 128 \text{ V/V} \times 1.375 \text{ V/V}$   |
| 0x22     | GAIN_CAL19 | 0b000x | 0  | 1  | Additional gain error for $G = 1/16 \text{ V/V} \times 1.25 \text{ V/V}$ or $G = 1/8 \text{ V/V} \times 1.25 \text{ V/V}$   |
| 0x23     | GAIN_CAL20 | 0b001x | 0  | 1  | Additional gain error for $G = 1/4 \text{ V/V} \times 1.25 \text{ V/V}$ or $G = 1/2 \text{ V/V} \times 1.25 \text{ V/V}$    |
| 0x24     | GAIN_CAL21 | 0b010x | 0  | 1  | Additional gain error for $G = 1 \text{ V/V} \times 1.25 \text{ V/V}$ or $G = 2 \text{ V/V} \times 1.25 \text{ V/V}$        |

## GAIN ERROR CALIBRATION

The ADA4255 includes measured gain errors for all 32 gain combinations, readable from the on-chip, read only memory (ROM). These errors are measured at 25°C and are stored in Register 0x10 through Register 0x27 at the time of production. Using this technology improves gain accuracy by a factor of 5, improving system accuracy and reducing additional calibration requirements.

Each register contains five bits. MSB represents the polarity of the error, with a setting of 1 indicating a negative polarity and a setting of 0 indicating a positive polarity. The remaining four bits contain the magnitude based on a LSB of 100 ppm for GAIN\_CAL1 through GAIN\_CAL12 and 50 ppm for GAIN\_CAL13 through GAIN\_CAL24.

GAIN\_CAL1 through GAIN\_CAL12 directly provide the measured gain errors of all 12 gain values with the scaling gain set to 1 V/V. GAIN\_CAL13 through GAIN\_CAL24 provide additional gain error incurred when using other scalar gains. This is tabulated in Table 7.



# THEORY OF OPERATION

**Table 7. Gain Calibration Register Contents<sup>1</sup>**

| Register | Name       | G[3:0] | G4 | G5 | Contents  |
|----------|------------|--------|----|----|---|
| 0x25     | GAIN_CAL22 | 0b011x | 0  | 1  | Additional gain error for G = 4 V/V × 1.25 V/V or G = 8 V/V × 1.25 V/V    |
| 0x26     | GAIN_CAL23 | 0b100x | 0  | 1  | Additional gain error for G = 16 V/V × 1.25 V/V or G = 32 V/V × 1.25 V/V  |
| 0x27     | GAIN_CAL24 | 0b101x | 0  | 1  | Additional gain error for G = 64 V/V × 1.25 V/V or G = 128 V/V × 1.25 V/V |

<sup>1</sup> X means don't care.

For all gains using 1 V/V scalar, calculate the gain error using the following equation:

$$\text{Gain Error} = ((-1) \times \text{GAIN\_CALx, Bit 4} + (100) \times \text{GAIN\_CALx, Bits[3:0]}) \text{ (ppm)}$$

For all gain values using 1.375 V/V or 1.25 V/V scalars, an additional gain error (GE') must be added, using this equation:

$$\text{GE}' = \text{Gain Error} + ((-1) \times \text{GAIN\_CALx, Bit 4} + (50) \times \text{GAIN\_CALx, Bits[3:0]}) \text{ (ppm)}$$

For example, assume that the ADA4255 is set to a gain of 32 V/V and a scaling gain of 1.375 V/V. To calculate the stored gain error, read the gain error stored in the GAIN\_CAL10 register and calculate the error in ppm. In this example, assume this readback is 10101, corresponding to a gain error of -500 ppm.

Then, read the additional gain error stored in GAIN\_CAL17 and calculate the error in ppm. In this example, assume this readback is 00010, corresponding to an additional gain error of 100 ppm. The two errors are added to give a total gain error of -400 ppm.

## THEORY OF OPERATION

## WIRE BREAK DETECTION

The ADA4255 contains two programmable current sources that can be configured to 0.25  $\mu\text{A}$ , 2  $\mu\text{A}$ , 4  $\mu\text{A}$ , or 16  $\mu\text{A}$  via the WB\_CURRENT bits (Register WB\_DETECT). Both currents are conducted from VDDH. These currents, in conjunction with the on-chip comparators, enable continuity testing on the ADA4255 inputs.

The currents are switched to the amplifier inputs using F1 and F2, as shown in Figure 95. The voltage to which these currents bias the amplifier inputs is monitored internally by the ADA4255. When this

voltage is within 4 V of VDDH, the WB\_ERR (Register ANALOG\_ERR\_DIS) flag trips.

When F1 or F2 are closed, the amplifier gain settings in the GAIN\_MUX register are temporarily overridden to the default values to avoid saturating the amplifier output in the event of an open-circuit input. Reads of the GAIN\_MUX register during this time do not reflect this. When F1 and F2 are open, the GAIN\_MUX register values automatically return to their previous values. This override can be disabled via the WB\_G\_RST\_DIS bit (Register WB\_DETECT).

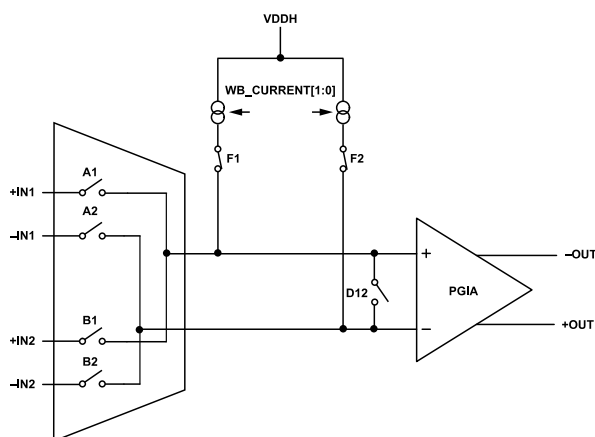


Figure 95. Wire Break Current Connectivity

## THEORY OF OPERATION

## TEST MULTIPLEXER

The ADA4255 contains an internal test multiplexer, as shown in [Figure 96](#), that connects the inputs of the ADA4255 to useful voltages. To use the test multiplexer, the C1 and C2 switches must be closed. These switches are controlled using the INPUT\_MUX register. It is recommended that the input multiplexer be disconnected from any external inputs by opening the A1, A2, B1, and B2 switches.

The TEST\_MUX bits in the TEST\_MUX register control the test multiplexer. The test multiplexer can be configured in three different states as follows:

- In the default state, the test multiplexer connects the ADA4255 inputs to AVSS. This configuration can be used during a full system calibration to null out errors, such as offset voltage.
- The test multiplexer can connect the noninverting input to DVSS and the inverting input to AVSS, or vice versa. This configuration

can be used to detect any voltage difference between AVSS and DVSS, which indicates poor connection.

- The test multiplexer can also provide a +20 mV or -20 mV differential signal to the inputs of the ADA4255. This configuration can be used to verify the gain setting of the ADA4255 and the PGIA functionality without applying an external signal.

## EXTERNAL MUX CONTROL

The ADA4255 is able to configure GPIO0 and GPIO1 to control an external multiplexer. Writes to the EXT\_MUX bits in the GAIN\_MUX register set the state of GPIO0 and GPIO1, which in turn controls an external multiplexer. This setup allows amplifier gain and external multiplexer settings to be configured with a single SPI write, avoiding overload conditions. The external mux special function can be configured via the EXT\_MUX\_EN bits (Register SF\_CFG) and setting GPIO0 and GPIO1 to outputs, as shown in [Figure 97](#).

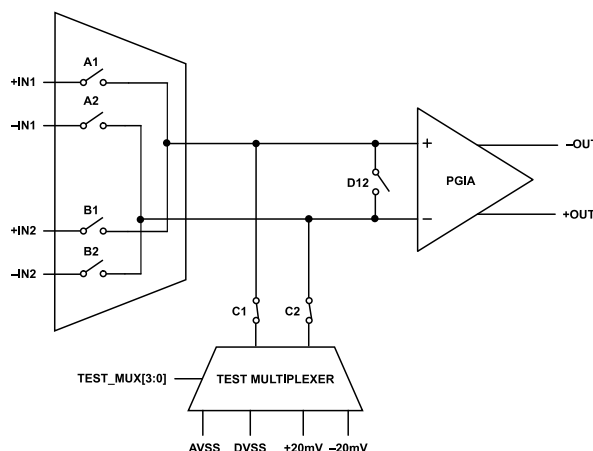


Figure 96. Text Multiplexer Connectivity

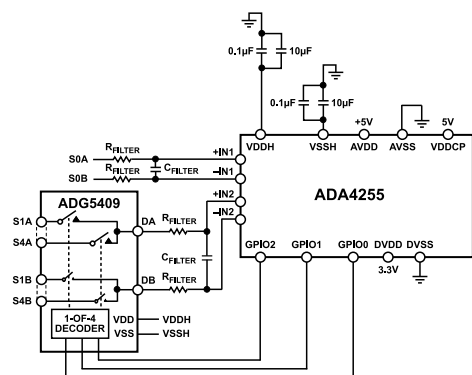


Figure 97. External Multiplexer Control Example

DIGITAL INTERFACE

SPI

The ADA4255 features a 4-wire SPI. This interface operates in SPI Mode 0 and can be operated with  $\overline{CS}$  tied low. In SPI Mode 0, SCLK idles low, the falling edge of SCLK is the driving edge, and the rising edge of SCLK is the sampling edge. This setup means that data is clocked out on the falling (driving) edge and clocked in on the rising (sampling) edge.

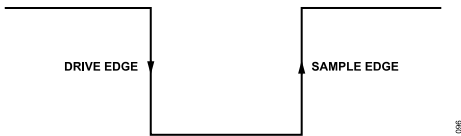


Figure 98. SPI Mode 0 SCLK Edges

ACCESSING THE ADA4255 REGISTER MAP

The ADA4255 SPI uses 16-bit instructions, plus an optional 8-bit CRC checksum. Each instruction contains a read or write bit, a 7-bit address, 8 bits of data, and an 8-bit CRC checksum if the SPI\_CRC\_ERR bit (Register DIGITAL\_ERR) is configured.

Table 8. ADA4255 Instruction Format

| R/W | ADDR, Bits[6:0] | Data, Bits[7:0] | CRC, Bits[7:0] |
|-----|-----------------|-----------------|----------------|
|-----|-----------------|-----------------|----------------|

R/W determines whether a read or write operation is performed (1 means read and 0 means write). ADDR, Bits[6:0], is the register address being read from or written to. R/W and the ADDR, Bits[6:0] together are referred to as an 8-bit command. For write operations, DATA, Bits[7:0], is the data being written, and CRC, Bits[7:0], is a user provided checksum for that data.

The ADA4255 internal address counter is automatically incremented after each read and/or write operation, allowing a continuous read and/or write mode. After an initial read operation, if  $\overline{CS}$  stays low, the next 8 SCLK pulses read back the contents of the next register address. After an initial write operation, if  $\overline{CS}$  stays low, the

next 8 SCLK pulses load the data on the SDI to the next register address.

CHECKSUM PROTECTION

The ADA4255 features a checksum mode that can be used to improve interface robustness. Using the checksum ensures that only valid data is written to a register and allows data read from a register to be validated. If an error occurs during a register write, the SPI\_CRC\_ERR bit (Register DIGITAL\_ERR) trips and no data is written. To ensure that a register write is successful, the register contents can be read, and the checksum can be verified.

For CRC checksum calculations, the following polynomial is always used:

$$x^8 + x^2 + x + 1$$

The SPI\_CRC\_ERR\_DIS bit (Register DIGITAL\_ERR) enables and disables this checksum. The 8-bit checksum is appended to the end of each read and write transaction. The checksum calculation for the write transaction is calculated using the 8-bit command word and the 8-bit data. For a read transaction, the checksum is calculated using the command word and the 8-bit data output. Figure 99 and Figure 100 show SPI write and read transactions, respectively.

In continuous write mode, the first write command CRC is calculated as described previously in this section. Subsequent CRCs are clocked in after every register data. The CRC in continuous write mode is calculated based on the register value it is associated with. In continuous read mode, the first read command CRC is calculated as described previously. Subsequent CRCs are clocked out after every register data. The CRC in continuous read mode is calculated based only on the register value it is associated with. Figure 101 and Figure 102 show SPI continuous write and read transactions, respectively.

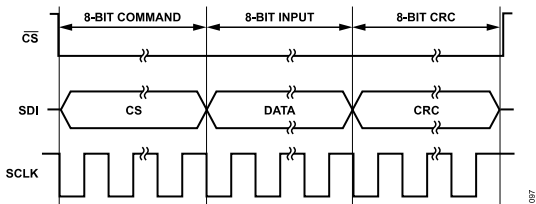


Figure 99. Writing to a Register with CRC

DIGITAL INTERFACE

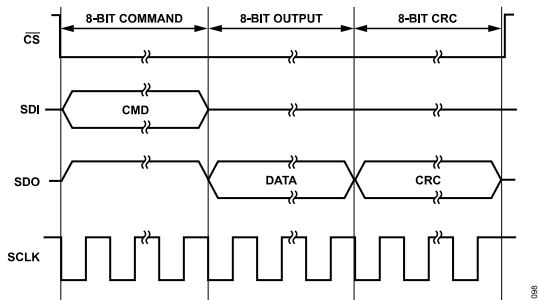


Figure 100. Reading from a Register with CRC

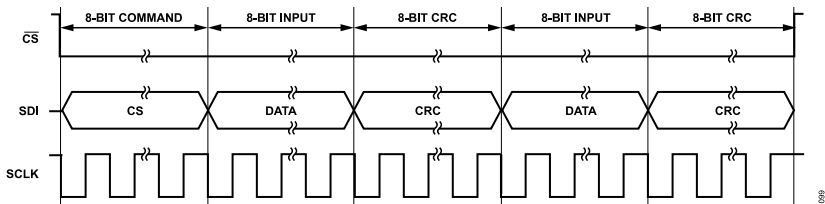


Figure 101. Continuous Write Mode with CRC

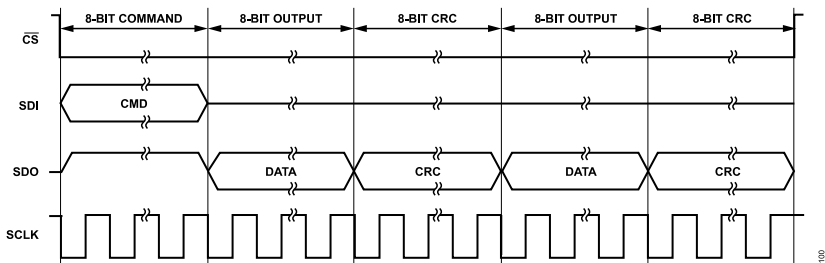


Figure 102. Continuous Read Mode with CRC

## DIGITAL INTERFACE

## CRC CALCULATION

The checksum, which is 8 bits wide, is generated using the following polynomial (with a seed of 0x00):

$$x^8 + x^2 + x + 1 \text{ (0b100000111)}$$

To generate the checksum, the data is left shifted by 8 bits to create a number ending in eight Logic 0s. The polynomial is aligned so that its MSB is adjacent to the leftmost Logic 1 of the data. An exclusive OR (XOR) function is applied to the data to produce a new, shorter number. The polynomial is again aligned so that its MSB is adjacent to the leftmost Logic 1 of the new result, and the procedure is repeated. This process is repeated until the original data is reduced to a value less than the polynomial. This is the 8-bit checksum.

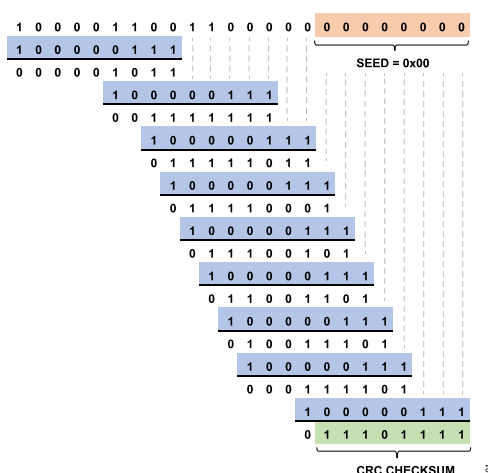


Figure 103. Calculating a CRC Checksum

## MEMORY MAP CHECKSUM PROTECTION

For added robustness, a CRC calculation is performed on the on-chip registers as well. Register 0x03, Register 0x04, and Register 0x05 are not included in this check because the contents of these registers change, independent of SPI writes. The CRC is performed at a rate of 15.26 Hz. Each time the register map is changed using an SPI write, the CRC is recalculated.

The memory map CRC function is enabled by default. This function can be disabled via the MM\_CRC\_ERR\_DIS bit (Register DIGITAL\_ERR\_DIS). If an error occurs, the MM\_CRC\_ERR bit (Register DIGITAL\_ERR) trips.

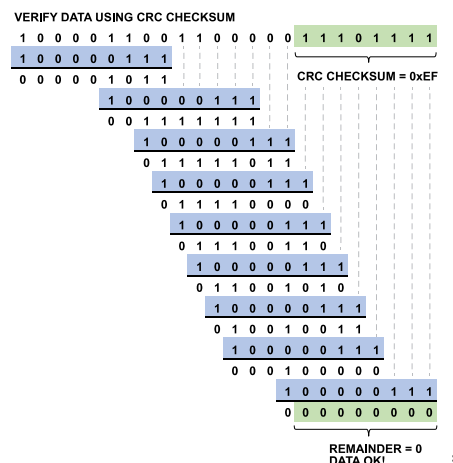


Figure 104. Verifying Data with a CRC Checksum

## READ-ONLY MEMORY (ROM) CHECKSUM PROTECTION

On power-up, all fuse registers are set to the default values. These default values are held in ROM. For added robustness, a CRC calculation is performed on the ROM contents as well. This CRC check is performed on power-up. The ROM CRC function is enabled by default. This function can be disabled via the ROM\_CRC\_ERR\_DIS bit (Register DIGITAL\_ERR\_DIS). If an error occurs, the ROM\_CRC\_ERR bit (Register DIGITAL\_ERR) trips.

## SPI READ AND WRITE ERROR DETECTION

The ADA4255 can detect if an invalid register is being addressed. A read or write to an invalid address trips the SPI\_RW\_ERR bit (Register DIGITAL\_ERR). The SPI\_RW\_ERR bit is enabled by default, and this bit can be disabled via the SPI\_RW\_ERR\_DIS bit (Register DIGITAL\_ERR\_DIS).

## SPI COMMAND LENGTH ERROR DETECTION

When communicating with the ADA4255, the number of clock edges on SCLK is monitored to ensure that, when CS returns high, the total number of clock edges received is divisible by 8. If the number of SCLK edges is insufficient or in excess, the SPI\_SCLK\_CNT\_ERR bit (Register DIGITAL\_ERR) trips. The SPI\_SCLK\_CNT\_ERR is enabled by default, and this bit can be disabled via the SPI\_SCLK\_CNT\_ERR\_DIS bit (Register DIGITAL\_ERR\_DIS).

## APPLICATIONS INFORMATION

## INPUT AND OUTPUT OFFSET VOLTAGE AND NOISE

The offset voltage of the ADA4255 has two main components: the input offset voltage due to the input amplifiers and the output offset due to the output amplifier. The total offset voltage  $RTI$  is found by dividing the output offset by the programmed gain and adding this value to the input offset voltage. At high gains, the input offset voltage dominates, whereas at low gains, the output offset voltage dominates. The total offset voltage is

$$\text{Total Input Offset Voltage (RTI)} = V_{OSI} + (V_{OSQ}/\text{GAIN})$$

$$\text{Total Output Offset Voltage (Referred to Output (RTO))} = V_{OSI} \times \text{Gain} + V_{OSQ}$$

The preceding equations can also be used to calculate the offset drift in a similar manner.

The noise of the ADA4255 behaves similarly to the voltage offset. There are two components: the input voltage noise due to the input amplifiers and the output voltage noise due to the output amplifiers. The total noise RTI is found by dividing the output voltage noise by the programmed gain and root-sum-squaring with the input voltage noise. At high gains the input voltage noise dominates, whereas at low gains the output voltage noise dominates. The total voltage noise is

$$\begin{aligned} & \text{Total Input Voltage Noise (RTI)} \\ &= \sqrt{e_{ni}^2 + \left(\frac{e_{no}}{\text{Gain}}\right)^2} \end{aligned} \quad (4)$$

$$\begin{aligned} & \text{Total Output Voltage Noise (RTO)} \\ &= \sqrt{(e_{ni} \times \text{Gain})^2 + (e_{no})^2} \end{aligned} \quad (5)$$

## ADC CLOCK SYNCHRONIZATION

The ADA4255 incorporates several clock synchronization features that allow the internal clock to be synchronized with other circuitry, such as an ADC. Synchronizing the system filters residual ripple due to the internal chopping of the ADA4255. When using these synchronization features, GPIO4 is configured to accept an external clock signal or output one of the internal clock signals.

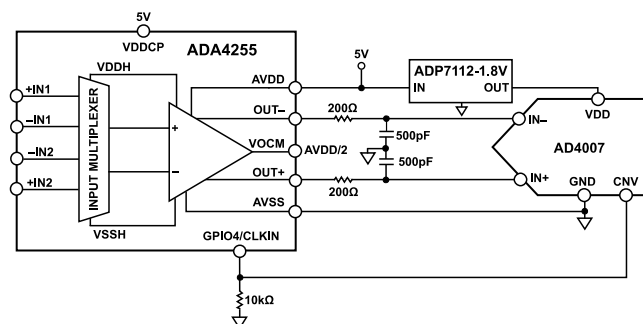
When an external clock is provided to the ADA4255, an on-chip clock divider is configured via the SYNC bits (Register SYNC\_CFG) to achieve a nominal 1 MHz clock. The 1 MHz clock is further divided by 8 to 125 kHz and controls the device chopping. The chopping clock edges can be configured to coincide with either the rising or falling edges of the provided clock via SYNC\_POL bit (Register SYNC\_CFG). This configuration is recommended for ADC synchronization. The ADA4255, when configured to accept an external clock, requires that this clock always be active and have a duty cycle of 50% to maintain charge pump operation.

Alternatively, the internal clock can be output to GPIO4 so that other circuits can use it. Either 1 MHz or 125 kHz can be selected via the CLK\_OUT\_SEL bit (Register SYNC\_CFG).

When the ADA4255 is driving the AD4007 1 MSPS successive approximation register (SAR) ADC as shown in Figure 105, the recommended configuration is to provide the 50% duty cycle convert signal to the ADA4255 as a clock input. In this case, SYNC is set to 0b000 because the CNV period is 1  $\mu$ s. Set the SYNC\_POL bit to 1 to synchronize the chopping clock to the rising edge of the CNV signal. When configured in this way, the output of the ADA4255 has the maximum time to settle after a chopping edge, and chopping edges do not occur during the ADC conversion phase. It is recommended to enable the high-Z mode of the AD4007 to maximize system performance.

When the ADA4255 is driving the [AD7768](#)  $\Sigma$ - $\Delta$  ADC as shown in [Figure 106](#), the recommended configuration is to provide the internal 32 MHz clock of the AD7768 to the ADA4255 as a clock input. In this case, SYNC is set to 0b101 to divide 32 MHz down to 1 MHz for the ADA4255. The SYNC setting has no impact on performance with  $\Sigma$ - $\Delta$  converters due to the way the converters operate internally. When driving the AD7768 directly with the ADA4255, enable the internal buffers of the AD7768. Alternatively, a dedicated ADC driver and amplifier can be configured between the ADA4255 and the AD7768.

In both configurations, it is recommended that two reads from the M\_CLK\_CNT register are performed to ensure that the master clock counter is incrementing, indicating that the ADA4255 is receiving an external clock.



**Figure 105. Clock Synchronization with the AD4007**

## APPLICATIONS INFORMATION

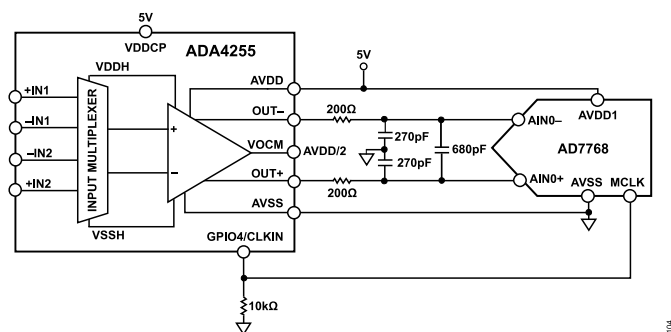


Figure 106. Clock Synchronization with the AD7768



## APPLICATIONS INFORMATION

PROGRAMMABLE LOGIC CONTROLLER (PLC)  
VOLTAGE AND CURRENT INPUT

The circuit in [Figure 107](#) shows the ADA4255 used to convert a typical PLC input signal ranges ( $\pm 10$  V,  $\pm 5$  V, or 20 mA) to an output voltage from 0 V to +5 V, compatible with high precision ADCs, such as the [AD7768](#). To perform a voltage measurement, the ADA4255 input multiplexer is configured to Channel 1, +IN1 and -IN1, by writing 0x60 to the INPUT\_MUX register. The MOSFET switch must be turned off by setting GPIO0 to logic level low. GPIO0 must be configured as an output by setting the corresponding bit field to 1 in the GPIO\_DIR register. The state of GPIO0 is controlled by the corresponding bit field in the GPIO\_DATA register. The ADA4255 gain can be configured through the GAIN\_MUX register, depending on the input voltage level.

To perform a current measurement, the circuit shown in [Figure 107](#) provides two different shunt resistors, 250  $\Omega$  and 100  $\Omega$ . To select a 250  $\Omega$  resistor, the metal-oxide semiconductor field effect transistor (MOSFET) switch must be switched on by setting GPIO0 to logic level high using the GPIO\_DATA register. The measurement is performed using Channel 1 of the ADA4255. To select 100  $\Omega$ , the MOSFET must be turned off by setting GPIO0 to logic level low. Channel 2 must be selected in this mode by writing 0x18 to the INPUT\_MUX register.

The ADA4255 internal chopping circuitry can be synchronized to the companion ADC, which keeps the residual chopping noise at the correct frequency and prevents it from folding back to a frequency band of interest. To use the synchronization functionality, configure GPIO4 to be an input by setting the corresponding bit field in the GPIO\_DIR register. Set the ADA4255 to accept an external clock by setting the EXT\_CLK\_IN bit in the SF\_CFG register. Adjust the clock divider such that the resulting clock is equal to 1 MHz. The divider can be adjusted in the SYNC\_CFG register. The SYNC\_CFG register also controls the synchronizing edge polarity. It is recommended that two reads from the M\_CLK\_CNT register are performed to ensure that the master clock counter is incrementing, indicating that the ADA4255 is receiving an external clock.

The ADA4255 on-chip diagnostics allow the user to check the circuit connections. In PLC applications, the circuit connections are verified using the wire break detection capabilities of the ADA4255. The WB\_DETECT register flag is set if one of the input connections is missing. Finally, the CRC check, SCLK counter, and SPI read and/or write check make the interface more robust as any read and/or write operations that are not valid are detected. The CRC check highlights if any bits are corrupted when transmitted between the processor and the ADA4255.

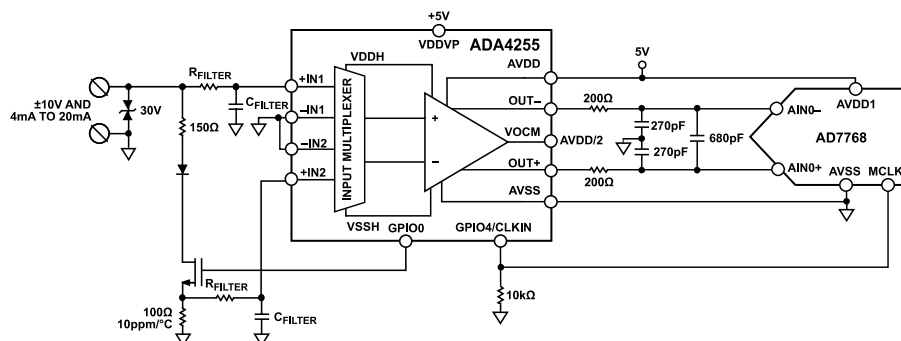


Figure 107. Voltage and Current Input Application

## APPLICATIONS INFORMATION

## 3-WIRE RTD WITH CURRENT EXCITATION

3-wire RTDs are commonly used for precision temperature measurement. Figure 108 shows how the ADA4255 can be used to accurately measure temperature using a 3-wire RTD sensor. In this implementation, the current source of the ADA4255, IOUT, is used to drive the RTD. RL1, RL2, and RL3 represent the parasitic lead resistances of the RTD. Through a sequence of three voltage measurements and by assuming all RLx resistors are equal, a temperature measurement can be made that is insensitive to the parasitic resistances of RL1, RL2 and RL3. Refer to Figure 108 to aid in the following measurement description.

The excitation current flows through RL1, RTD, RL3, and R<sub>REF</sub>. R<sub>REF</sub> serves as a current sense resistor used to measure the true value of IOUT. Because of this, the tolerance and drift of R<sub>REF</sub> are important in achieving system accuracy specifications. The combined voltage on RTD and RL1 can be measured between +IN1 and -IN1. Note that the portion of this measured voltage that is on RL1 is an error term, and it matches the voltage on RL3 because RL1 matches RL3, and the same current flows in both. Next, measure the voltage between -IN2 and +IN2 with the known value of R<sub>REF</sub> to calculate the true value of IOUT. A final measurement of the voltage between -IN1 and +IN2 results in the combined voltage on RL3 and R<sub>REF</sub>. From these three voltage measurements, the voltage across RTD and the current conducted in RTD are determined, and the RTD value is calculated and used to determine temperature.

The gain of the ADA4255 must be optimized for each of these three measurements to maximize resolution. To achieve some of the switch combinations, the MUX\_PROT\_DIS bit (Register ANALOG\_ERR\_DIS) must also be set.

The ADA4255 internal chopping circuitry can be synchronized to the companion ADC to help keep the residual chopping noise at its frequency and to prevent the noise from folding back into a frequency band of interest. To use the synchronization functionality, configure GPIO4 to be an input by setting its corresponding bit in the GPIO\_DIR register. Set the ADA4255 to accept an external clock by setting the EXT\_CLK\_IN bit in the SF\_CFG register. Adjust the clock divider such that the resulting clock is equal to 1 MHz. The divider can be adjusted in SYNC\_CFG register. The SYNC\_CFG register also controls the syncing edge polarity. It is recommended that two reads from the M\_CLK\_CNT register are performed to ensure that the master clock counter is incrementing, indicating that the ADA4255 is getting an external clock.

The ADA4255 on-chip diagnostics allow the user to check the circuit connections. In RTD applications, the circuit connections are verified using the wire break detection capabilities of the ADA4255. The WB\_DETECT register flag is set if one of the RTD wires is missing. Finally, the CRC check, SCLK counter, and SPI read and/or write check make the interface more robust because any read and/or write operations that are not valid are detected. The CRC check highlights if any bits are corrupted when transmitted between the processor and the ADA4255.

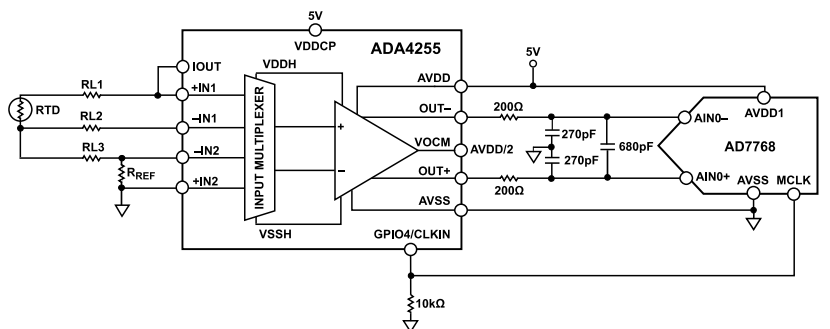


Figure 108. 3-Wire RTD Application

## APPLICATIONS INFORMATION

## HIGH RAIL CURRENT SENSING

Figure 109 shows a high-side current sense amplifier implemented with ADA4255. The integrated charge pump PGIA topology of the ADA4255 allows this circuit to sense bidirectional current over a 38 V range on a single 5 V supply voltage. The low offset voltage, low offset voltage drift, low input current, and excellent linearity allow this configuration to achieve very high dynamic range.

While the ADA4255 features an integrated EMI filter, an additional low-pass filter can be used externally as shown. The ADA4255 has low input bias current and input bias offset current that minimizes the error introduced by the input bias current flowing through the filter resistor. The matching of the filter resistors and capacitors is required to minimize the errors and preserve AC CMRR.

The ADA4255 on-chip diagnostics allow the user to check the circuit connections. In current sensing applications, the circuit connections are verified using the wire break detection capabilities of the ADA4255. The WB\_DETECT register flag is set if one of the connections to the shunt resistors is missing. Finally, the CRC check, SCLK counter, and SPI read and/or write check make the interface more robust because any read and/or write operations that are not valid are detected. The CRC check highlights if any bits are corrupted when transmitted between the processor and the ADA4255.

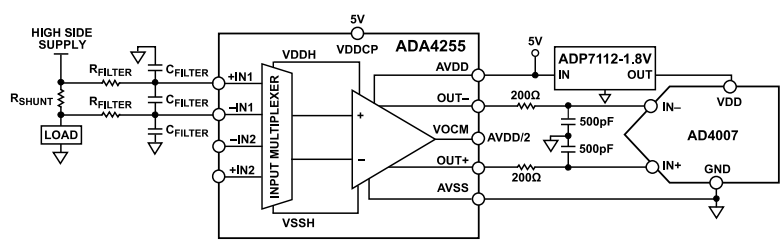


Figure 109. High Voltage, Bidirectional, Current Sense Application

## REGISTER SUMMARY

Table 9. Register Summary

| Reg. | Name                   | Bit 7               | Bit 6          | Bit 5           | Bit 4           | Bit 3                | Bit 2             | Bit 1           | Bit 0                 |
|------|------------------------|---------------------|----------------|-----------------|-----------------|----------------------|-------------------|-----------------|-----------------------|
| 0x00 | GAIN_MUX               | G4                  | G[3:0]         |                 |                 |                      | Reserved          | EXT_MUX[1:0]    |                       |
| 0x01 | Reset                  | Reserved            |                |                 |                 |                      |                   |                 | RST                   |
| 0x02 | SYNC_CFG               | CLK_CP_SEL          | CLK_OUT_SEL    | Reserved        | SYNC_POL        | Reserved             | SYNC[2:0]         |                 |                       |
| 0x03 | DIGITAL_ERR            | Reserved            | CAL_BUSY       | SPI_CRC_ERR     | SPI_RW_ERR      | SPI_SCLK_CNT_ERR     | Reserved          | MM_CRC_ERR      | ROM_CRC_ERR           |
| 0x04 | ANALOG_ERR             | G_RST               | POR_HV         | Reserved        | WB_ERR          | FAULT_INT            | OUTPUT_ERR        | INPUT_ERR       | MUX_OVER_VOLT_ERR     |
| 0x05 | GPIO_DATA              | Reserved            | GPIO_DATA[6:0] |                 |                 |                      |                   |                 |                       |
| 0x06 | INPUT_MUX              | Reserved            | SW_A1          | SW_A2           | SW_B1           | SW_B2                | SW_C1             | SW_C2           | SW_D12                |
| 0x07 | WB_DETECT              | WB_G_RST_DIS        | Reserved       |                 |                 | SW_F1                | SW_F2             | WB_CURRENT[1:0] |                       |
| 0x08 | GPIO_DIR               | Reserved            | GPIO_DIR[6:0]  |                 |                 |                      |                   |                 |                       |
| 0x09 | SCS                    | Reserved            | SCS[6:0]       |                 |                 |                      |                   |                 |                       |
| 0x0A | ANALOG_ERR_DIS         | G_RST_DIS           | POR_HV_DIS     | Reserved        | WB_ERR_DIS      | MUX_PROT_DIS         | OUTPUT_ERR_DIS    | INPUT_ERR_DIS   | MUX_OVER_VOLT_ERR_DIS |
| 0x0B | DIGITAL_ERR_DIS        | Reserved            | CAL_BUSY_DIS   | SPI_CRC_ERR_DIS | SPI_RW_ERR_DIS  | SPI_SCLK_CNT_ERR_DIS | M_CLK_CNT_ERR_DIS | MM_CRC_ERR_DIS  | ROM_CRC_ERR_DIS       |
| 0x0C | SF_CFG                 | Reserved            |                | INT_CLK_OUT     | EXT_CLK_IN      | FAULT_INT_OUT        | CAL_BUSY_OUT      | EXT_MUX_EN[1:0] |                       |
| 0x0D | ERR_CFG                | ERR_LATCH_DIS       | Reserved       |                 |                 | ERR_DELAY[3:0]       |                   |                 |                       |
| 0x0E | TEST_MUX               | G5                  | CAL_SEL        | CAL_EN[1:0]     |                 | TEST_MUX[3:0]        |                   |                 |                       |
| 0x0F | EX_CURRENT_CFG         | EX_CURRENT_SEL[1:0] |                | Reserved        |                 | EX_CURRENT[3:0]      |                   |                 |                       |
| 0x10 | GAIN_CALx <sup>1</sup> | Reserved            |                |                 | GAIN_CAL1[4:0]  |                      |                   |                 |                       |
| 0x11 |                        | Reserved            |                |                 | GAIN_CAL2[4:0]  |                      |                   |                 |                       |
| 0x12 |                        | Reserved            |                |                 | GAIN_CAL3[4:0]  |                      |                   |                 |                       |
| 0x13 |                        | Reserved            |                |                 | GAIN_CAL4[4:0]  |                      |                   |                 |                       |
| 0x14 |                        | Reserved            |                |                 | GAIN_CAL5[4:0]  |                      |                   |                 |                       |
| 0x15 |                        | Reserved            |                |                 | GAIN_CAL6[4:0]  |                      |                   |                 |                       |
| 0x16 |                        | Reserved            |                |                 | GAIN_CAL7[4:0]  |                      |                   |                 |                       |
| 0x17 |                        | Reserved            |                |                 | GAIN_CAL8[4:0]  |                      |                   |                 |                       |
| 0x18 |                        | Reserved            |                |                 | GAIN_CAL9[4:0]  |                      |                   |                 |                       |
| 0x19 |                        | Reserved            |                |                 | GAIN_CAL10[4:0] |                      |                   |                 |                       |
| 0x1A |                        | Reserved            |                |                 | GAIN_CAL11[4:0] |                      |                   |                 |                       |
| 0x1B |                        | Reserved            |                |                 | GAIN_CAL12[4:0] |                      |                   |                 |                       |
| 0x1C |                        | Reserved            |                |                 | GAIN_CAL13[4:0] |                      |                   |                 |                       |
| 0x1D |                        | Reserved            |                |                 | GAIN_CAL14[4:0] |                      |                   |                 |                       |
| 0x1E |                        | Reserved            |                |                 | GAIN_CAL15[4:0] |                      |                   |                 |                       |
| 0x1F |                        | Reserved            |                |                 | GAIN_CAL16[4:0] |                      |                   |                 |                       |
| 0x20 |                        | Reserved            |                |                 | GAIN_CAL17[4:0] |                      |                   |                 |                       |
| 0x21 | Reserved               |                     |                | GAIN_CAL18[4:0] |                 |                      |                   |                 |                       |
| 0x22 | Reserved               |                     |                | GAIN_CAL19[4:0] |                 |                      |                   |                 |                       |
| 0x23 | Reserved               |                     |                | GAIN_CAL20[4:0] |                 |                      |                   |                 |                       |
| 0x24 | Reserved               |                     |                | GAIN_CAL21[4:0] |                 |                      |                   |                 |                       |
| 0x25 | Reserved               |                     |                | GAIN_CAL22[4:0] |                 |                      |                   |                 |                       |
| 0x26 | Reserved               |                     |                | GAIN_CAL23[4:0] |                 |                      |                   |                 |                       |

## REGISTER SUMMARY

Table 9. Register Summary

| Reg. | Name       | Bit 7    | Bit 6 | Bit 5 | Bit 4           | Bit 3 | Bit 2           | Bit 1 | Bit 0    |
|------|------------|----------|-------|-------|-----------------|-------|-----------------|-------|----------|
| 0x27 |            | Reserved |       |       | GAIN_CAL24[4:0] |       |                 |       |          |
| 0x2A | TRIG_CAL   | Reserved |       |       |                 |       |                 |       | TRIG_CAL |
| 0x2E | M_CLK_CNT  |          |       |       |                 |       | M_CLK_CNT[7:0]  |       |          |
| 0x2F | DIE_REV_ID |          |       |       |                 |       | DIE_REV_ID[7:0] |       |          |
| 0x64 | PART_ID    |          |       |       |                 |       | PART_ID[39:32]  |       |          |
| 0x65 |            |          |       |       |                 |       | PART_ID[31:24]  |       |          |
| 0x66 |            |          |       |       |                 |       | PART_ID[23:16]  |       |          |
| 0x67 |            |          |       |       |                 |       | PART_ID[15:8]   |       |          |
| 0x68 |            |          |       |       |                 |       | PART_ID[7:0]    |       |          |

<sup>1</sup> x is 1 to 24.

## REGISTER DETAILS

GAIN MULTIPLEXER REGISTER (GAIN\_MUX)  
DETAILS

Table 10. GAIN\_MUX Register Details (Register 0x00)

|          | Bit 7 | Bit 6 | Bit 5 | Bit 4  | Bit 3 | Bit 2    | Bit 1 | Bit 0        |
|----------|-------|-------|-------|--------|-------|----------|-------|--------------|
| Bit Name | G4    |       |       | G[3:0] |       | Reserved |       | EXT_MUX[1:0] |
| Access   | R/W   |       |       | R/W    |       | Reserved |       | R/W          |
| Reset    | 0     | 0     | 0     | 0      | 0     | Reserved | 0     | 0            |

**Bit 7, G4—Output Amplifier Scaling Gain  
(1.375 V/V)**

Setting the G4 bit to 1 configures the output amplifier in a scaling gain of 1.375 V/V. This configuration scales the input amplifier gain, G[3:0] (Bits[6:3]), by 1.375 V/V. The G4 bit takes precedence over the G5 bit, located in the TEST\_MUX register. Setting the G4 bit to 0 configures the output amplifier in either a gain of 1 V/V or 1.25 V/V, depending on the value written to the G5 bit. These gain settings are summarized in Table 11.

Table 11. Output Amplifier Scaling Gain Settings

| G5 Bit         | G4 Bit | Output Amplifier Scaling Gain (V/V) |
|----------------|--------|-------------------------------------|
| 0              | 0      | 1                                   |
| X <sup>1</sup> | 1      | 1.375                               |
| 1              | 0      | 1.25                                |

<sup>1</sup> X means don't care.

**Bits[1:0], EXT\_MUX[1:0]—External Multiplexer Control**

When external multiplexer control is enabled using the EXT\_MUX\_EN bits in Register 0x0C, and GPIO1 and/or GPIO0 are configured as outputs using the GPIO\_DIR bits in Register 0x08, EXT\_MUX[1:0] sets the output of GPIO1 and/or GPIO0. This setup simplifies communication in externally multiplexed applications because both the gain and the external multiplexer can be configured with a single SPI write to the GAIN\_MUX register. Multiplexers larger than 4 to 1 are supported by using additional GPIOx pins and additional SPI writes.

**Bits[6:3], G[3:0]—Input Amplifier Gain Setting**

The G[3:0] bits set the gain of the input amplifier, as shown in Table 12. The overall gain is scaled by the output amplifier scaling gain, which is configured using the G4 bit and the G5 bit. The default input amplifier gain is 1/16 V/V.

Table 12. Register Values for Input Amplifier Gains

| Input Amplifier Gain (V/V) | Bits in the G[3:0] Bit Field |    |    |    |
|----------------------------|------------------------------|----|----|----|
|                            | G3                           | G2 | G1 | G0 |
| 1/16                       | 0                            | 0  | 0  | 0  |
| 1/8                        | 0                            | 0  | 0  | 1  |
| 1/4                        | 0                            | 0  | 1  | 0  |
| 1/2                        | 0                            | 0  | 1  | 1  |
| 1                          | 0                            | 1  | 0  | 0  |
| 2                          | 0                            | 1  | 0  | 1  |
| 4                          | 0                            | 1  | 1  | 0  |
| 8                          | 0                            | 1  | 1  | 1  |
| 16                         | 1                            | 0  | 0  | 0  |
| 32                         | 1                            | 0  | 0  | 1  |
| 64                         | 1                            | 0  | 1  | 0  |
| 128                        | 1                            | 0  | 1  | 1  |
| Reserved                   | 1                            | 1  | 0  | 0  |
| Reserved                   | 1                            | 1  | 0  | 1  |
| Reserved                   | 1                            | 1  | 1  | 0  |
| Reserved                   | 1                            | 1  | 1  | 1  |

## REGISTER DETAILS

SOFTWARE RESET REGISTER (RESET)  
DETAILS

Table 13. Reset Register Details (Register 0x01)

|          | Bit 7 | Bit 6 | Bit 5 | Bit 4    | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|-------|-------|-------|----------|-------|-------|-------|-------|
| Bit Name |       |       |       | Reserved |       |       |       | RST   |
| Access   |       |       |       | Reserved |       |       |       | W     |
| Reset    |       |       |       | Reserved |       |       |       | 0     |

**Bit 0, RST—Soft Reset**

A soft reset can be initiated by setting the RST bit to 1. A soft reset clears all internal registers and sets them to their default values. The RST bit is self clearing. The RST bit performs the same operation as a power-on reset (POR) and a start-up calibration occurs.

## REGISTER DETAILS

CLOCK SYNCHRONIZATION CONFIGURATION  
REGISTER (SYNC\_CFG) DETAILS

Table 14. SYNC\_CFG Register Details (Register 0x02)

|          | Bit 7      | Bit 6       | Bit 5    | Bit 4    | Bit 3    | Bit 2     | Bit 1 | Bit 0 |
|----------|------------|-------------|----------|----------|----------|-----------|-------|-------|
| Bit Name | CLK_CP_SEL | CLK_OUT_SEL | Reserved | SYNC_POL | Reserved | SYNC[2:0] |       |       |
| Access   | R/W        | R/W         | Reserved | RW       | Reserved | R/W       |       |       |
| Reset    | 0          | 0           | Reserved | 0        | Reserved | 1         | 0     | 0     |

**Bit 7, CLK\_CP\_SEL—Charge Pump Clock Select**

The charge pump of the ADA4255 runs at 16 MHz by default. Alternatively, setting CLK\_CP\_SEL to 1 changes the charge pump frequency to 8 MHz.

**Bit 6, CLK\_OUT\_SEL—Clock Output Select**

The ADA4255 1 MHz master clock is divided down to 125 kHz internally and is used by the zero drift amplifiers. When the INT\_CLK\_OUT bit in Register 0x0C is set to 1, setting CLK\_OUT\_SEL to 1 outputs the divided down 125 kHz clock on GPIO4. Clearing CLK\_OUT\_SEL to 0 outputs the 1 MHz master clock on GPIO4.

**Bit 4, SYNC\_POL—Clock Synchronization Polarity**

When an external clock source is provided to the ADA4255, this bit is used to configure whether the rising or falling edge is used for synchronization. The synchronization edge is the edge at which the ADA4255 performs the chopping. Writing a 1 to this bit synchronizes the ADA4255 to the positive edge of the provided clock. Writing a 0 synchronizes the ADA4255 to the negative edge of the provided clock.

**Bits[2:0], SYNC[2:0]—Internal Clock Divider Value**

When an external clock is provided to the ADA4255, the SYNC[2:0] bits set the internal clock divider value. If an external clock is supplied to the ADA4255, the clock value must be 1 MHz or must be divided down by the ADA4255 to 1 MHz using the clock divider. Table 15 lists the available divider values.

Table 15. Clock Divider Values

| Divider Value | Bits in the SYNC[2:0] Bit Field |       |       |
|---------------|---------------------------------|-------|-------|
|               | SYNC2                           | SYNC1 | SYNC0 |
| ÷1            | 0                               | 0     | 0     |
| ÷2            | 0                               | 0     | 1     |
| ÷4            | 0                               | 1     | 0     |
| ÷8            | 0                               | 1     | 1     |
| ÷16           | 1                               | 0     | 0     |
| ÷32           | 1                               | 0     | 1     |
| Reserved      | 1                               | 1     | 0     |
| Reserved      | 1                               | 1     | 1     |



## REGISTER DETAILS

DIGITAL ERROR REGISTER (DIGITAL\_ERR)  
DETAILS

Table 16. DIGITAL\_ERR Register Details (Register 0x03)

|          | Bit 7    | Bit 6    | Bit 5       | Bit 4      | Bit 3            | Bit 2    | Bit 1      | Bit 0       |
|----------|----------|----------|-------------|------------|------------------|----------|------------|-------------|
| Bit Name | Reserved | CAL_BUSY | SPI_CRC_ERR | SPI_RW_ERR | SPI_SCLK_CNT_ERR | Reserved | MM_CRC_ERR | ROM_CRC_ERR |
| Access   | Reserved | R        | R/W         | R/W        | R/W              | Reserved | R/W        | R/W         |
| Reset    | Reserved | 0        | 0           | 0          | 0                | Reserved | 0          | 0           |

**Bit 6, CAL\_BUSY—Calibration Busy (Read Only)**

CAL\_BUSY indicates that the PGIA is undergoing a calibration and self trim operation. Until this flag is clear, the ADA4255 output is not accurate. Writing a 1 or 0 to CAL\_BUSY has no effect. CAL\_BUSY can be output on GPIO2 when GPIO2 is configured as an output using the corresponding GPIO\_DIR bit and when the CAL\_BUSY\_OUT bit is set to 1.

**Bit 5, SPI\_CRC\_ERR—SPI CRC Error**

The SPI\_CRC\_ERR error flag indicates that an error occurred during SPI communication with the ADA4255. This error occurs when the user provided CRC does not match the ADA4255 CRC calculation. Clear this error flag by writing a 1 to the SPI\_CRC\_ERR bit.

**Bit 4, SPI\_RW\_ERR—SPI Read/Write Error**

The SPI\_RW\_ERR error flag indicates that a SPI read and/or write operation is attempted on an invalid address. This error flag can be cleared by writing a 1 to this bit.

**Bit 3, SPI\_SCLK\_CNT\_ERR—SPI SCLK Count Error**

The SPI\_SCLK\_CNT\_ERR error flag indicates that, during SPI communication while  $\overline{CS}$  is low, the number of SCLK edges is either insufficient or excessive. This error flag can be cleared by writing a 1 to this bit.

**Bit 1, MM\_CRC\_ERR—Memory Map CRC Error**

The MM\_CRC\_ERR error flag indicates that the current internal memory map does not match the result from the previous SPI write. If this error occurs, it is recommended to reprogram the ADA4255 registers. This error flag can be cleared by writing a 1 to this bit.

**Bit 0, ROM\_CRC\_ERR—ROM CRC Error**

The ROM\_CRC\_ERR error flag indicates that the internal ROM did not pass the CRC check. If this error occurs, it is strongly recommended to reset or power cycle the device. If the error does not reset with a power cycle or a soft reset, it is possible that the device is permanently damaged.

## REGISTER DETAILS

ANALOG ERROR REGISTER (ANALOG\_ERR)  
DETAILS

Table 17. ANALOG\_ERR Register Details (Register 0x04)

|          | Bit 7 | Bit 6  | Bit 5    | Bit 4  | Bit 3     | Bit 2      | Bit 1     | Bit 0             |
|----------|-------|--------|----------|--------|-----------|------------|-----------|-------------------|
| Bit Name | G_RST | POR_HV | Reserved | WB_ERR | FAULT_INT | OUTPUT_ERR | INPUT_ERR | MUX_OVER_VOLT_ERR |
| Access   | R/W   | R/W    | Reserved | R/W    | R/W       | R/W        | R/W       | R/W               |
| Reset    | 0     | 0      | Reserved | 0      | 0         | 0          | 0         | 0                 |

**Bit 7, G\_RST—Gain Reset Flag**

The G\_RST flag indicates that the gain settings in the GAIN\_MUX register have been reset to their defaults due to an overvoltage event in one or more of the input amplifiers that lasted more than 200  $\mu$ s. Bit G5 in the TEST\_MUX register is not reset by this event. This safety measure protects the input resistor network from overvoltage. This flag can be cleared by writing a 1 to this bit. Clearing this flag does not restore gain settings to the previous values.

**Bit 6, POR\_HV—Power-On Reset HV Supply**

The POR\_HV flag indicates that an event occurred on VDDH, VSSH, or VDDCP, causing the power-on reset circuit to trip. When the supply voltage returns to a valid state, the ADA4255 runs a calibration. Clear this error flag by writing a 1 to this bit position.

**Bit 4, WB\_ERR—Wire Break Detect Error**

When performing a wire break test using the WB\_DETECT register, the WB\_ERR flag indicates a fault on the inputs of the amplifier. Clear this error by writing a 1 to this bit position.

**Bit 3, FAULT\_INT—Fault Interrupt**

An OR function is performed on all unmasked error flags in the ANALOG\_ERR register and the DIGITAL\_ERR register to generate the FAULT\_INT fault interrupt. Configuring GPIO3 as an output using the corresponding GPIO\_DIR bit and setting the FAULT\_INT\_OUT bit (Register SF\_CFG) to 1 outputs this signal to GPIO3. Clear this error by writing a 1 to this bit position. In this mode, GPIO3 is active low.

**Bit 2, OUTPUT\_ERR—Output Amplifier Error**

The OUTPUT\_ERR flag indicates that the output amplifier is overloaded. The cause of this overload condition is either the output voltage saturating or excessive current being conducted from the output of the amplifier. Clear this error by writing a 1 to this bit position.

**Bit 1, INPUT\_ERR—Input Amplifier Error**

The INPUT\_ERR flag indicates that one of the input amplifiers is overloaded. The cause of this overload condition is either saturation of one of the amplifier outputs, or a violation of the input voltage range. When this error flag is tripped for longer than 200  $\mu$ s, gain settings in the GAIN\_MUX register reset to the default values and the G\_RST flag is set to 1. Bit G5 is not reset. Clear this error by writing a 1 to this bit position.

**Bit 0, MUX\_OVER\_VOLT\_ERR—Input Multiplexer Overvoltage Error**

The MUX\_OVER\_VOLT\_ERR flag indicates that excessive voltage is detected by the input multiplexer. The multiplexer turns all channels off to protect the input amplifier. Reads of the INPUT\_MUX register during this time do not reflect this. The threshold for this detection is typically  $VSSH + 0.9$  V and  $VDDH - 0.9$  V. When the input voltage returns to the valid range after 20  $\mu$ s, the multiplexer returns to the previous settings. If latched mode is in use, the error flag remains until reset. If nonlatched mode is used, the error flag clears when the multiplexer returns to the previous settings.

REGISTER DETAILS

GPIO DATA REGISTER (GPIO\_DATA) DETAILS

Table 18. GPIO\_DATA Register Details (Register 0x05)

|          | Bit 7    | Bit 6          | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|----------|----------------|-------|-------|-------|-------|-------|-------|
| Bit Name | Reserved | GPIO_DATA[6:0] |       |       |       |       |       |       |
| Access   | Reserved | R/W            |       |       |       |       |       |       |
| Reset    | Reserved | 0              | 0     | 0     | 0     | 0     | 0     | 0     |

Bits[6:0], GPIO\_DATA[6:0]—GPIO Data Values

When a GPIOx pin is configured as an output, writing a 1 to the corresponding GPIO\_DATA bit causes that GPIOx pin to output a logic high. Conversely, writing a 0 to the corresponding GPIO\_DATA bit causes that GPIOx pin to output a logic low.

When a GPIOx pin is configured as an input, each GPIO\_DATA bit indicates whether the voltage on the corresponding GPIOx pin is a logic high or logic low. Reading a 1 indicates a logic high, and reading a 0 indicates a logic low. Writing to the GPIO\_DATA bits that are configured as inputs has no effect.

## REGISTER DETAILS

INTERNAL MUX CONTROL REGISTER  
(INPUT\_MUX) DETAILS

Table 19. INPUT\_MUX Register Details (Register 0x06)

|          | Bit 7    | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0  |
|----------|----------|-------|-------|-------|-------|-------|-------|--------|
| Bit Name | Reserved | SW_A1 | SW_A2 | SW_B1 | SW_B2 | SW_C1 | SW_C2 | SW_D12 |
| Access   | Reserved | R/W   | R/W   | R/W   | R/W   | R/W   | R/W   | R/W    |
| Reset    | Reserved | 1     | 1     | 0     | 0     | 0     | 0     | 0      |

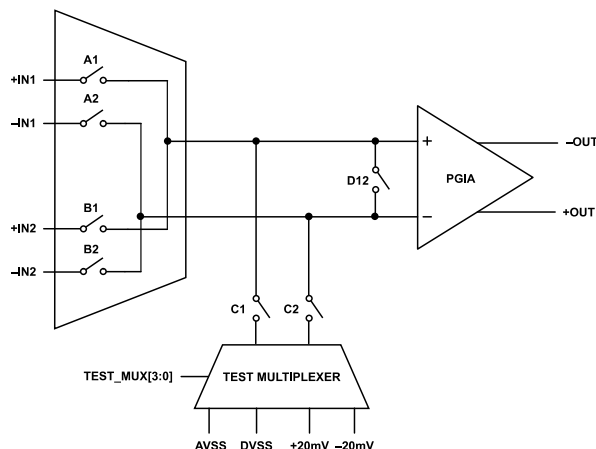


Figure 110. Input Mux Switch Configuration

**Bit 6, SW\_A1, and Bit 5, SW\_A2—Channel 1 Input Switches**

The SW\_A1 bit and the SW\_A2 bit control the Channel 1 input switches, A1 and A2, respectively (see Figure 110). Setting these bits to 1 closes the respective switch. SW\_A1 and SW\_A2 cannot be connected at the same time as SW\_B1 and SW\_B2, unless the MUX\_PROT\_DIS bit (Register ANALOG\_ERR\_DIS) is set to 1.

**Bit 4, SW\_B1, and Bit 3, SW\_B2—Channel 2 Input Switches**

The SW\_B1 bit and the SW\_B2 bit control the Channel 2 input switches, B1 and B2, respectively (see Figure 110). Setting these bits to 1 closes the respective switch. SW\_B1 and SW\_B2 cannot be connected at the same time as SW\_A1 and SW\_A2, unless the MUX\_PROT\_DIS bit (Register ANALOG\_ERR\_DIS) is set to 1.

**Bit 2, SW\_C1, and Bit 1, SW\_C2—PGIA Input Test Multiplexer Switches**

The SW\_C1 bit and the SW\_C2 bit can be set to 1 to connect either PGIA input to the output of the input test multiplexer (which is AVSS by default) via the C1 and C2 switches (see Figure 110).

**Bit 0, SW\_D12—PGIA Input Short Switch**

The SW\_D12 bit can be set to 1 to connect both PGIA inputs together via the D12 switch.

# REGISTER DETAILS

## WIRE BREAK DETECT REGISTER (WB\_DETECT) DETAILS

Table 20. WB\_DETECT Register Details (Register 0x07)

|          | Bit 7        | Bit 6 | Bit 5    | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0           |
|----------|--------------|-------|----------|-------|-------|-------|-------|-----------------|
| Bit Name | WB_G_RST_DIS |       | Reserved |       | SW_F1 | SW_F2 |       | WB_CURRENT[1:0] |
| Access   | R/W          |       | Reserved |       | R/W   | R/W   |       | R/W             |
| Reset    | 0            |       | Reserved |       | 0     | 0     | 1     | 0               |

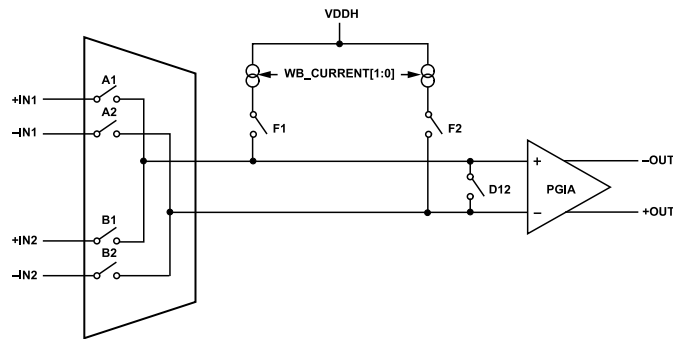


Figure 111. Wire Break Current Connectivity

### Bit 7, WB\_G\_RST\_DIS—Wire Break Gain Reset Disable

The WB\_G\_RST\_DIS bit can be set to 1 to prevent the gain settings in the GAIN\_MUX register from being overridden to 1/16 V/V when the SW\_F1 bit or the SW\_F2 bit are set to 1.

### Bit 3, SW\_F1, and Bit 2, SW\_F2—Fault Switch Selection

The SW\_F1 bit and the SW\_F2 bit are used to connect the wire break current sources to the inputs, as shown in Figure 111. Setting SW\_F1 or SW\_F2 to 1 closes each corresponding switch. Both switches can be closed simultaneously. When SW\_F1 or SW\_F2 are set to 1 and WB\_G\_RST\_DIS is cleared to 0, the gain settings in the GAIN\_MUX register are temporarily overridden to the default values. Reading the GAIN\_MUX register while SW\_F1 or SW\_F2 are set to 1 does not show this temporary override. When SW\_F1 or SW\_F2 are cleared to 0, the gain is also restored to the previous value.

### Bits[1:0], WB\_CURRENT—Detection Current Selection

Table 21 shows four different current values that can be used for wire break detection. Both current sources are set to the programmed value. The comparator used to detect a wire break event has a threshold at approximately 4 V from VDDH.

Table 21. Wire Break Detect Current Values

| WB_CURRENT[1:0] Bits |       | Current Source Value | Threshold VDDCP = 5 V |
|----------------------|-------|----------------------|-----------------------|
| Bit 1                | Bit 0 |                      |                       |
| 0                    | 0     | 250 nA               | 73.2 MΩ               |
| 0                    | 1     | 2 μA                 | 9.15 MΩ               |
| 1                    | 0     | 4 μA (default)       | 4.58 MΩ               |
| 1                    | 1     | 16 μA                | 1.14 MΩ               |

# REGISTER DETAILS

## GPIO DIRECTION REGISTER (GPIO\_DIR) DETAILS

Table 22. GPIO\_DIR Register Details (Register 0x08)

|          | Bit 7    | Bit 6         | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|----------|---------------|-------|-------|-------|-------|-------|-------|
| Bit Name | Reserved | GPIO_DIR[6:0] |       |       |       |       |       |       |
| Access   | Reserved | R/W           |       |       |       |       |       |       |
| Reset    | Reserved | 0             | 0     | 0     | 0     | 0     | 0     | 0     |

### Bits[6:0], GPIO\_DIR—GPIO Direction Configuration

The GPIO\_DIR bit field is used to configure each GPIOx pin as either an input or an output. Setting a bit in this bit field to 1 configures the corresponding GPIOx pin as an output. Clearing a bit in this bit field to 0 configures the corresponding GPIOx as an input.

## SEQUENTIAL CHIP SELECT REGISTER (SCS) DETAILS

Table 23. SCS Register Details (Register 0x09)

|          | Bit 7    | Bit 6    | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|----------|----------|-------|-------|-------|-------|-------|-------|
| Bit Name | Reserved | SCS[6:0] |       |       |       |       |       |       |
| Access   | Reserved | R/W      |       |       |       |       |       |       |
| Reset    | Reserved | 0        | 0     | 0     | 0     | 0     | 0     | 0     |

### Bits[6:0], SCS—Sequential Chip Select Configuration

Bits[6:0] configure the GPIOx pins as sequential chip select (SCS) pins. Setting any bit in SCS6 to SCS0 to 1 and configuring the respective GPIOx pin as an output via the GPIO\_DIR register makes that GPIOx function as a chip select pin for a slave device. When SCS is used, the first  $\overline{CS}$  pulse addresses the first GPIOx configured for SCS. Subsequent  $\overline{CS}$  pulses address the remainder of the GPIOx pins configured for SCS, and the last  $\overline{CS}$  pulse addresses the ADA4255. This sequence repeats in a round robin format until the ADA4255 is configured otherwise. This process is shown in Figure 112.

Slave SCS lines may require pull-up resistors to avoid inadvertently communicating with slave devices during SCS configuration.

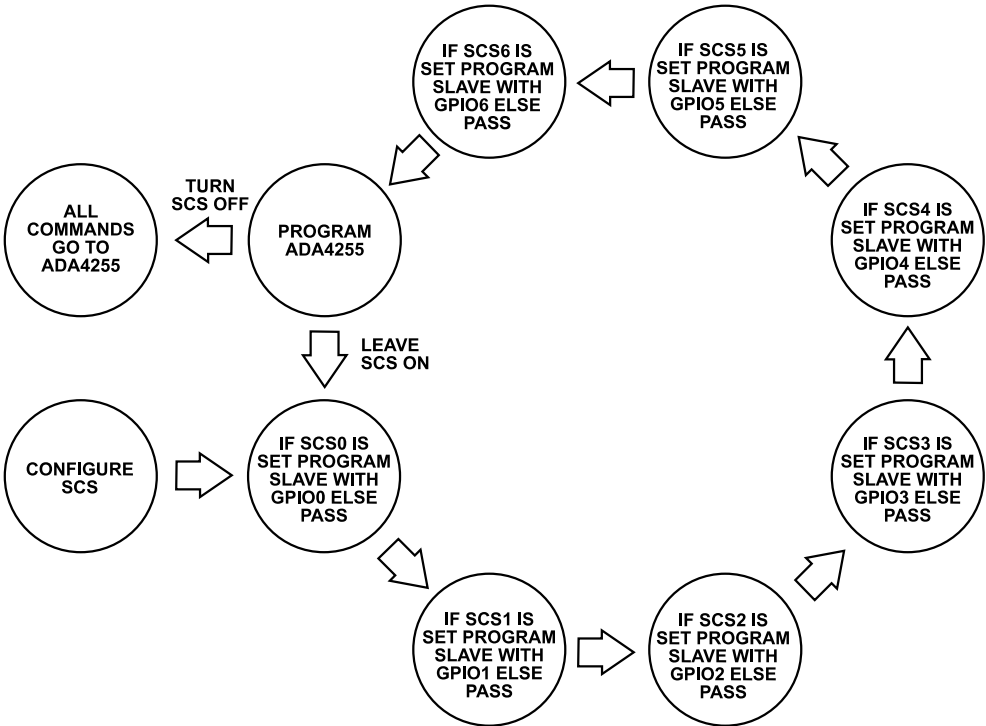


Figure 112. Sequential Chip Select Flowchart

## REGISTER DETAILS

ANALOG ERROR MASK REGISTER  
(ANALOG\_ERR\_DIS) DETAILS

The ANALOG\_ERR\_DIS register can be used to mask individual error flags in the ANALOG\_ERR register. Setting bits in ANALOG\_ERR\_DIS to 1 disables the corresponding error flag.

Table 24. ANALOG\_ERR\_DIS Register Details (Register 0x0A)

|          | Bit 7     | Bit 6      | Bit 5    | Bit 4      | Bit 3        | Bit 2          | Bit 1         | Bit 0                 |
|----------|-----------|------------|----------|------------|--------------|----------------|---------------|-----------------------|
| Bit Name | G_RST_DIS | POR_HV_DIS | Reserved | WB_ERR_DIS | MUX_PROT_DIS | OUTPUT_ERR_DIS | INPUT_ERR_DIS | MUX_OVER_VOLT_ERR_DIS |
| Access   | R/W       | R/W        | Reserved | R/W        | R/W          | R/W            | R/W           | R/W                   |
| Reset    | 0         | 0          | Reserved | 0          | 0            | 0              | 0             | 0                     |

**Bit 7, G\_RST\_DIS—Disable Gain Reset Error Flag**

The G\_RST\_DIS bit disables the G\_RST error flag.

**Bit 6, POR\_HV\_DIS—Disable High Voltage Power Reset Flag**

The POR\_HV\_DIS bit disables the POR\_HV error flag.

**Bit 4, WB\_ERR\_DIS—Disable Wire Break Detection Flag**

The WB\_ERR\_DIS bit disables the WB\_ERR error flag.

**Bit 3, MUX\_PROT\_DIS—Disable Input Multiplexer Protection**

By default, the input multiplexer does not allow both sets of inputs to be connected at the same time (this is a safety feature). This protection can be disabled by setting MUX\_PROT\_DIS to 1.

**Bit 2, OUTPUT\_ERR\_DIS—Disable Output Amplifier Error Flag**

The OUTPUT\_ERR\_DIS bit disables the OUTPUT\_ERR error flag.

**Bit 1, INPUT\_ERR\_DIS—Disable Input Amplifier Error Flag**

The INPUT\_ERR\_DIS bit disables the INPUT\_ERR error flag.

**Bit 0, MUX\_OVER\_VOLT\_ERR\_DIS—Disable Multiplexer Overvoltage Flag**

The MUX\_OVER\_VOLT\_ERR\_DIS bit disables the MUX\_OVER\_VOLT\_ERR error flag.

## REGISTER DETAILS

DIGITAL ERROR MASK REGISTER  
(DIGITAL\_ERR\_DIS) DETAILS

The DIGITAL\_ERR\_DIS register can be used to mask individual error flags in the DIGITAL\_ERR register. Setting bits in the DIGITAL\_ERR\_DIS register to 1 disables the error flag.

Table 25. DIGITAL\_ERR\_DIS Register Details (Register 0x0B)

|          | Bit 7    | Bit 6        | Bit 5           | Bit 4          | Bit 3                | Bit 2             | Bit 1          | Bit 0           |
|----------|----------|--------------|-----------------|----------------|----------------------|-------------------|----------------|-----------------|
| Bit Name | Reserved | CAL_BUSY_DIS | SPI_CRC_ERR_DIS | SPI_RW_ERR_DIS | SPI_SCLK_CNT_ERR_DIS | M_CLK_CNT_ERR_DIS | MM_CRC_ERR_DIS | ROM_CRC_ERR_DIS |
| Access   | Reserved | R/W          | R/W             | R/W            | R/W                  | R/W               | R/W            | R/W             |
| Reset    | Reserved | 0            | 1               | 0              | 0                    | 0                 | 0              | 0               |

**Bit 6, CAL\_BUSY\_DIS—Disable Calibration Busy Error Flag**

The CAL\_BUSY\_DIS bit disables the CAL\_BUSY error flag.

**Bit 5, SPI\_CRC\_ERR\_DIS—Disable SPI CRC Error Flag**

When SPI\_CRC\_ERR\_DIS is cleared to 0, the ADA4255 expects an additional checksum byte with write commands and transmits an extra checksum byte with read commands. By default, SPI\_CRC\_ERR\_DIS is set to 1, and this functionality is disabled. After enabling CRC, a manual check can be performed to ensure that the CRC configuration command was properly communicated. If the CRC is used, it is recommended to configure the CRC before other registers so that all subsequent communication receives the CRC.

**Bit 4, SPI\_RW\_ERR\_DIS—Disable SPI Read/Write Error Flag**

The SPI\_RW\_ERR\_DIS bit disables the SPI\_RW\_ERR error flag.

**Bit 3, SPI\_SCLK\_CNT\_ERR\_DIS—Disable SPI SCLK Count Error Flag**

The SPI\_SCLK\_CNT\_ERR\_DIS bit disables the SPI\_SCLK\_CNT\_ERR error flag.

**Bit 2, M\_CLK\_CNT\_ERR\_DIS—Disable Master Clock Count Output**

When the M\_CLK\_CNT\_ERR\_DIS bit is set to 0, the master clock is updated in the M\_CLK\_CNT register. Setting this bit to 1 stops M\_CLK\_CNT from incrementing.

**Bit 1, MM\_CRC\_ERR\_DIS—Disable Memory Map CRC Error Flag**

The MM\_CRC\_ERR\_DIS bit disables the MM\_CRC\_ERR error flag.

**Bit 0, ROM\_CRC\_ERR\_DIS—Disable ROM CRC Error Flag**

The ROM\_CRC\_ERR\_DIS bit disables the ROM\_CRC\_ERR error flag.



## REGISTER DETAILS

SPECIAL FUNCTION CONFIGURATION  
REGISTER (SF\_CFG) DETAILS

Table 26. SF\_CFG Register Details (Register 0x0C)

|          | Bit 7 | Bit 6    | Bit 5       | Bit 4      | Bit 3         | Bit 2        | Bit 1 | Bit 0        |
|----------|-------|----------|-------------|------------|---------------|--------------|-------|--------------|
| Bit Name |       | Reserved | INT_CLK_OUT | EXT_CLK_IN | FAULT_INT_OUT | CAL_BUSY_OUT |       | EXT_MUX[1:0] |
| Access   |       | Reserved | R/W         | R/W        | R/W           | R/W          |       | R/W          |
| Reset    |       | Reserved | 0           | 0          | 0             | 0            | 0     | 0            |

**Bit 5, INT\_CLK\_OUT—Internal Oscillator Output**

When GPIO4 is configured as an output via GPIO\_DIR and INT\_CLK\_OUT is set to 1, one of the internal clocks is output to GPIO4. The CLK\_OUT\_SEL bit in the SYNC\_CFG register determines which internal clock is on GPIO4.

**Bit 4, EXT\_CLK\_IN—External Oscillator Input**

When GPIO4 is configured as an input via GPIO\_DIR and EXT\_CLK\_IN is set to 1, an external clock can be provided via GPIO4. If this clock frequency is not 1 MHz, the on-chip clock divider must be used to divide the clock via the SYNC[2:0] bits. The default setting for the internal clock divider is 16. The clock must always be present and have a 50% duty cycle to ensure charge pump operation.

**Bit 3, FAULT\_INT\_OUT—Fault Interrupt Output**

When GPIO3 is configured as an output via GPIO\_DIR and FAULT\_INT\_OUT is set to 1, the value in the FAULT\_INT bit (Register ANALOG\_ERR) appears on GPIO3.

**Bit 2, CAL\_BUSY\_OUT—Calibration Busy Output**

When GPIO2 is configured as an output via GPIO\_DIR and CAL\_BUSY\_OUT is set to 1, the value in the CAL\_BUSY bit (Register DIGITAL\_ERR) appears on GPIO2.

**Bits[1:0], EXT\_MUX\_EN[1:0]—Enable External Multiplexer Control**

Each bit in the EXT\_MUX\_EN[1:0] bit range enables GPIO1 and/or GPIO0 to be controlled via the EXT\_MUX bits in the GAIN\_MUX register.

## REGISTER DETAILS

ERROR CONFIGURATION REGISTER  
(ERR\_CFG) DETAILS

Table 27. ERR\_CFG Register Details (Register 0x0D)

|          | Bit 7         | Bit 6    | Bit 5 | Bit 4 | Bit 3          | Bit 2 | Bit 1 | Bit 0 |
|----------|---------------|----------|-------|-------|----------------|-------|-------|-------|
| Bit Name | ERR_LATCH_DIS | Reserved |       |       | ERR_DELAY[3:0] |       |       |       |
| Access   | R/W           | Reserved |       |       | R/W            | R/W   | R/W   | R/W   |
| Reset    | 0             | Reserved |       |       | 0              | 1     | 0     | 0     |

**Bit 7, ERR\_LATCH\_DIS—Disable Error Latching**

By default, ERR\_LATCH\_DIS is cleared to 0 and error flags are latched and require resetting. Setting ERR\_LATCH\_DIS to 1 makes the errors appear transparently (nonlatching) on the respective outputs. When ERR\_LATCH\_DIS is set to 1, errors can be suppressed for the time interval configured by the ERR\_DELAY bits.

**Bits[3:0], ERR\_DELAY[3:0] —Error Suppression Time**

When ERR\_LATCH\_DIS is set to 1, ERR\_DELAY determines the number of clock cycles an error must remain present before the error flag is tripped, which eliminates false trips due to noise and transients.

Table 28. Error Flag Suppression Time

| ERR_DELAY[3:0] | Clock Cycles (μs) |
|----------------|-------------------|
| 0x0            | 0                 |
| 0x1            | 1                 |
| 0x2            | 2                 |
| 0x3            | 3                 |
| 0x4            | 4                 |
| 0x5            | 5                 |
| 0x6            | 6                 |
| 0x7            | 7                 |
| 0x8            | 8                 |
| 0x9            | 12                |
| 0xA            | 16                |
| 0xB            | 24                |
| 0xC            | 32                |
| 0xD            | 48                |
| 0xE            | 64                |
| 0xF            | 127               |

# REGISTER DETAILS

## TEST MULTIPLEXER REGISTER (TEST\_MUX) DETAILS

Table 29. TEST\_MUX Register Details (Register 0x0E)

|          | Bit 7 | Bit 6   | Bit 5       | Bit 4 | Bit 3         | Bit 2 | Bit 1 | Bit 0 |
|----------|-------|---------|-------------|-------|---------------|-------|-------|-------|
| Bit Name | G5    | CAL_SEL | CAL_EN[1:0] |       | TEST_MUX[3:0] |       |       |       |
| Access   | R/W   | RW      | R/W         |       | R/W           |       |       |       |
| Reset    | 0     | 0       | 0           | 0     | 0             | 0     | 0     | 0     |

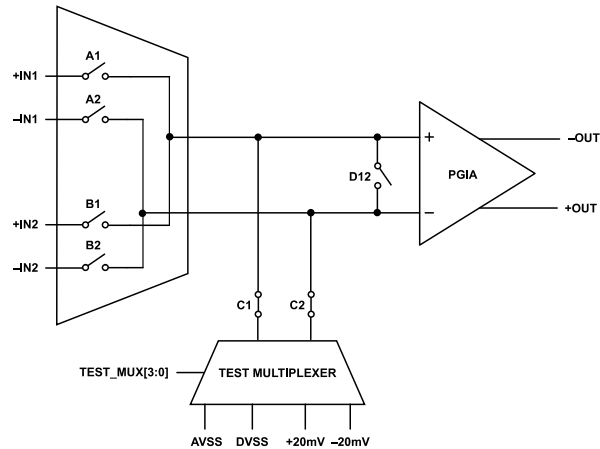


Figure 113. Test Multiplexer Connectivity

### Bit 7, G5—Output Amplifier Scaling Gain = 1.25 V/V

Clearing Bit G4 to 0 and setting Bit G5 to 1 configures the output amplifier to a scaling gain value of 1.25 V/V. This setting scales the input amplifier gain configured in the GAIN\_MUX register by 1.25 V/V.

Table 30. Output Amplifier Scaling Gain Settings

| G5             | G4 | Output Amplifier Scaling Gain (V/V) |
|----------------|----|-------------------------------------|
| 0              | 0  | 1                                   |
| X <sup>1</sup> | 1  | 1.375                               |
| 1              | 0  | 1.25                                |

<sup>1</sup> X means don't care.

### Bit 6, CAL\_SEL—Calibration Type Configuration

Clearing the CAL\_SEL bit to 0 configures the ADA4255 to perform quick calibrations. Setting CAL\_SEL to 1 configures the ADA4255 to perform full calibrations.

### Bits[5:4], CAL\_EN[1:0]—Scheduled Calibration Enable and Interval

CAL\_EN enables scheduled calibrations and configures the interval on which these calibrations execute. While calibrations are executing, the inputs of the PGIA are not connected to the input pins. The CAL\_BUSY signal indicates when a calibration is executing. CAL\_BUSY can be output to GPIO2 by configuring GPIO2 as an output via the GPIO\_DIR bits (Register GPIO\_DIR) and setting the CAL\_BUSY\_OUT bit (Register SF\_CFG) to 1. Minimize and avoid noise and input transients during calibrations.

Table 31. Scheduled Calibration Configurations

| CAL_EN, Bit 1 | CAL_EN, Bit 0 | Scheduled Calibration Configuration |
|---------------|---------------|-------------------------------------|
| 0             | 0             | Disabled                            |
| 0             | 1             | Enabled, 33 sec interval            |
| 1             | 0             | Enabled, 132 sec interval           |
| 1             | 1             | Enabled, 495 sec interval           |

REGISTER DETAILS

Bits[3:0], TEST\_MUX[3:0]—Input Test Multiplexer Configuration

The TEST\_MUX[3:0] bits are used to configure the input test multiplexers, which can switch four different signals to either of the inputs for diagnostic and calibration purposes. These potentials are AVSS, DVSS, +20 mV, and -20 mV. SW\_C1 and SW\_C2 must also be set to 1 for the outputs of these multiplexers to be connected to the amplifier inputs.

Table 32. Test Multiplexer Configurations

| TEST_MUX[3:0] | Noninverting Input | Inverting Input |
|---------------|--------------------|-----------------|
| 0000          | AVSS               | AVSS            |
| 0001          | DVSS               | AVSS            |
| 0100          | AVSS               | DVSS            |
| 0101          | DVSS               | DVSS            |
| 1010          |                    | +20 mV          |
| 1111          |                    | -20 mV          |

## REGISTER DETAILS

EXCITATION CURRENT CONFIGURATION  
REGISTER (EX\_CURRENT\_CFG) DETAILS

Table 33. EX\_CURRENT\_CFG Register Details (Register 0x0F)

|          | Bit 7               | Bit 6 | Bit 5 | Bit 4    | Bit 3 | Bit 2           | Bit 1 | Bit 0 |
|----------|---------------------|-------|-------|----------|-------|-----------------|-------|-------|
| Bit Name | EX_CURRENT_SEL[1:0] |       |       | Reserved |       | EX_CURRENT[3:0] |       |       |
| Access   | R/W                 |       |       | Reserved |       | R/W             |       |       |
| Reset    | 0                   | 0     |       | Reserved | 0     | 0               | 0     | 0     |

Bits[7:6], EX\_CURRENT\_SEL[1:0]—Excitation  
Current Connection Configuration

EX\_CURRENT\_SEL[1:0] configures internal current source IOUT. [Table 34](#) shows all available configurations. When IOUT is used, the source of this current is AVDD.

Table 34. Excitation Current Source Connections

| EX_CURRENT_SEL[1:0] | Current Source |
|---------------------|----------------|
| 0b00                | None           |
| 0b01                | IOUT           |
| 0b10                | None           |
| 0b11                | IOUT           |

Bits[3:0], EX\_CURRENT[3:0]—Excitation  
Current Value

The EX\_CURRENT[3:0] bits configure the current source value connected via the EX\_CURRENT\_SEL bits. [Table 35](#) shows all the possible current values.

Table 35. Excitation Current Values

| EX_CURRENT[3:0] | Excitation Current Value |
|-----------------|--------------------------|
| 0x0             | 0 $\mu$ A                |
| 0x1             | 100 $\mu$ A              |
| 0x2             | 200 $\mu$ A              |
| 0x3             | 300 $\mu$ A              |
| 0x4             | 400 $\mu$ A              |
| 0x5             | 500 $\mu$ A              |
| 0x6             | 600 $\mu$ A              |
| 0x7             | 700 $\mu$ A              |
| 0x8             | 800 $\mu$ A              |
| 0x9             | 900 $\mu$ A              |
| 0xA             | 1 mA                     |
| 0xB             | 1.1 mA                   |
| 0xC             | 1.2 mA                   |
| 0xD             | 1.3 mA                   |
| 0xE             | 1.4 mA                   |
| 0xF             | 1.5 mA                   |

## REGISTER DETAILS

GAIN CALIBRATION REGISTERS (GAIN\_CALX)  
DETAILS

The gain calibration registers contain the measured gain error of each individual ADA4255. Refer to the [Gain Error Calibration](#) section for details on how to use these values. GAIN\_CAL1 through GAIN\_CAL12 store gain error results for each input gain setting with a scaling gain of 1 V/V. When a scaling gain of 1 V/V is used, these gain error values are used directly. GAIN\_CAL13 through

GAIN\_CAL24 store any additional gain error incurred when 1.375 V/V or 1.25 V/V scaling gains are used. When scaling gains other than 1 V/V are used, the gain error read from the appropriate GAIN\_CAL1 through GAIN\_CAL12 register must be summed with the corresponding additional gain error read from the appropriate GAIN\_CAL13 through GAIN\_CAL24. For example, if the input gain is 2 V/V and the 1.25 V/V scalar is used, the total gain error is GAIN\_CAL6 + GAIN\_CAL21.

**Table 36. GAIN\_CAL Registers Details (Register 0x10 to Register 0x27)**

| Register | Name      | Bit 7 | Bit 6    | Bit 5 | Bit 4 | Bit 3 | Bit 2           | Bit 1 | Bit 0 |
|----------|-----------|-------|----------|-------|-------|-------|-----------------|-------|-------|
| 0x10     | GAIN_CALx |       | Reserved |       |       |       | GAIN_CAL1[4:0]  |       |       |
| 0x11     |           |       |          |       |       |       | GAIN_CAL2[4:0]  |       |       |
| 0x12     |           |       |          |       |       |       | GAIN_CAL3[4:0]  |       |       |
| 0x13     |           |       |          |       |       |       | GAIN_CAL4[4:0]  |       |       |
| 0x14     |           |       |          |       |       |       | GAIN_CAL5[4:0]  |       |       |
| 0x15     |           |       |          |       |       |       | GAIN_CAL6[4:0]  |       |       |
| 0x16     |           |       |          |       |       |       | GAIN_CAL7[4:0]  |       |       |
| 0x17     |           |       |          |       |       |       | GAIN_CAL8[4:0]  |       |       |
| 0x18     |           |       |          |       |       |       | GAIN_CAL9[4:0]  |       |       |
| 0x19     |           |       |          |       |       |       | GAIN_CAL10[4:0] |       |       |
| 0x1A     |           |       |          |       |       |       | GAIN_CAL11[4:0] |       |       |
| 0x1B     |           |       |          |       |       |       | GAIN_CAL12[4:0] |       |       |
| 0x1C     |           |       |          |       |       |       | GAIN_CAL13[4:0] |       |       |
| 0x1D     |           |       |          |       |       |       | GAIN_CAL14[4:0] |       |       |
| 0x1E     |           |       |          |       |       |       | GAIN_CAL15[4:0] |       |       |
| 0x1F     |           |       |          |       |       |       | GAIN_CAL16[4:0] |       |       |
| 0x20     |           |       |          |       |       |       | GAIN_CAL17[4:0] |       |       |
| 0x21     |           |       |          |       |       |       | GAIN_CAL18[4:0] |       |       |
| 0x22     |           |       |          |       |       |       | GAIN_CAL19[4:0] |       |       |
| 0x23     |           |       |          |       |       |       | GAIN_CAL20[4:0] |       |       |
| 0x24     |           |       |          |       |       |       | GAIN_CAL21[4:0] |       |       |
| 0x25     |           |       |          |       |       |       | GAIN_CAL22[4:0] |       |       |
| 0x26     |           |       |          |       |       |       | GAIN_CAL23[4:0] |       |       |
| 0x27     |           |       |          |       |       |       | GAIN_CAL24[4:0] |       |       |
| Access   |           |       | Reserved |       |       |       | R               |       |       |

## REGISTER DETAILS

TRIGGER CALIBRATION REGISTER  
(TRIG\_CAL) DETAILS

Table 37. TRIG\_CAL Registers Details (Register 0x2A)

|          | Bit 7    | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0    |
|----------|----------|-------|-------|-------|-------|-------|-------|----------|
| Bit Name | Reserved |       |       |       |       |       |       | TRIG_CAL |
| Access   | Reserved |       |       |       |       |       |       | W        |
| Reset    | Reserved |       |       |       |       |       |       | 0        |

## Bit 0, TRIG\_CAL—Trigger Calibration Input

Setting TRIG\_CAL to 1 initiates a calibration sequence when scheduled calibrations are disabled via CAL\_EN. The type of calibration that is triggered can be configured via the CAL\_SEL bits (Register TEST\_MUX). The TRIG\_CAL bit is self clearing.

MASTER CLOCK COUNT REGISTER  
(M\_CLK\_CNT) DETAILS

Table 38. M\_CLK\_CNT Registers Details (Register 0x2E)

|          | Bit 7          | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|----------------|-------|-------|-------|-------|-------|-------|-------|
| Bit Name | M_CLK_CNT[7:0] |       |       |       |       |       |       |       |
| Access   | R              |       |       |       |       |       |       |       |

## Bits[7:0], M\_CLK\_CNT[7:0]—Master Clock Count

M\_CLK\_CNT contains a master clock counter that increments when M\_CLK\_CNT\_ERR is cleared to 0. The counter is updated every 512  $\mu$ s. Setting M\_CLK\_CNT\_ERR to 1 stops this register from updating.

DIE REVISION IDENTIFICATION REGISTER  
(DIE\_REV\_ID) DETAILS

Table 39. DIE\_REV\_ID Registers Details (Register 0x2F)

|          | Bit 7           | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|-----------------|-------|-------|-------|-------|-------|-------|-------|
| Bit Name | DIE_REV_ID[7:0] |       |       |       |       |       |       |       |
| Access   | R               |       |       |       |       |       |       |       |
| Reset    | 0               | 0     | 1     | 1     | 0     | 0     | 0     | 0     |

## Bits[7:0], DIE\_REV\_ID[7:0]—Die Revision Identification Number

DIE\_REV\_ID contains a fixed value of 0x30 that can be used to verify the SPI communication with the ADA4255.

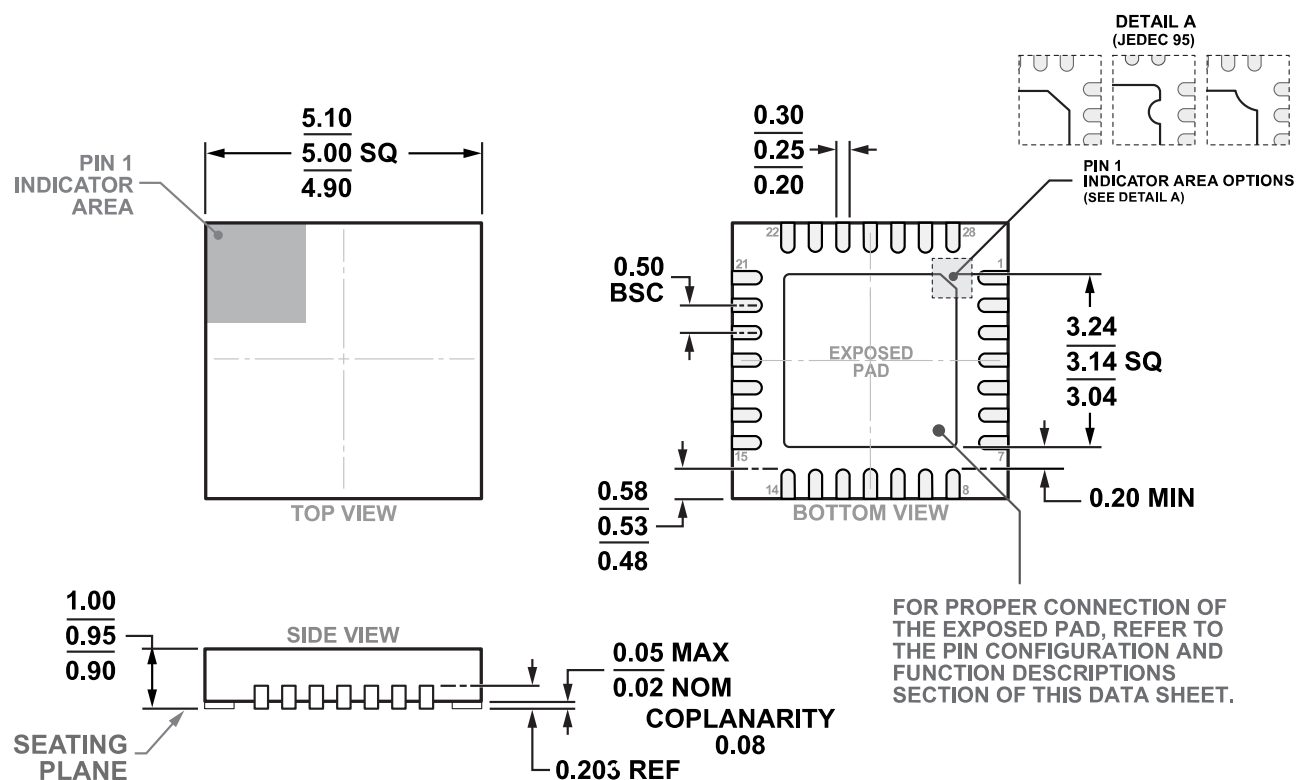
DEVICE IDENTIFICATION REGISTERS  
(PART\_ID) DETAILSTable 40. PART\_ID Registers Details (Register 0x64 through Register 0x68)<sup>1</sup>

| Register | Bit 7          | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|----------|----------------|-------|-------|-------|-------|-------|-------|-------|
| 0x64     | PART_ID[39:32] |       |       |       |       |       |       |       |
| 0x65     | PART_ID[31:24] |       |       |       |       |       |       |       |
| 0x66     | PART_ID[23:16] |       |       |       |       |       |       |       |
| 0x67     | PART_ID[15:8]  |       |       |       |       |       |       |       |
| 0x68     | PART_ID[7:0]   |       |       |       |       |       |       |       |
| Access   | R              |       |       |       |       |       |       |       |

## PART\_ID[39:0]—Part ID Number

The PART\_ID register contains a unique device identification number that is programmed at the factory.

## OUTLINE DIMENSIONS



PKG-005234

09-10-2018-A

## COMPLIANT TO JEDEC STANDARDS MO-220-VHHD-1

Figure 114. 28-Lead Lead Frame Chip Scale Package [LFCSP],  
5 mm × 5 mm Body and 0.95 mm Package Height  
(CP-28-11)

Dimensions shown in millimeters

## ORDERING GUIDE

| Model <sup>1</sup> | Temperature Range | Package Description                           | Package Option |
|--------------------|-------------------|---|----------------|
| ADA4255ACPZ        | -40°C to +105°C   | 28-Lead Lead Frame Chip Scale Package [LFCSP] | CP-28-11       |
| ADA4255ACPZ-R7     | -40°C to +105°C   | 28-Lead Lead Frame Chip Scale Package [LFCSP] | CP-28-11       |
| ADA4255ACPZ-RL     | -40°C to +105°C   | 28-Lead Lead Frame Chip Scale Package [LFCSP] | CP-28-11       |

<sup>1</sup> Z = RoHS Compliant Part.

## EVALUATION BOARDS

| Model <sup>1</sup> | Description      |
|--------------------|------------------|
| ADA4255CP-EBZ      | Evaluation Board |

<sup>1</sup> Z = RoHS Compliant Part.



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