## 280ps High-Speed Comparator, Ultra-Low Dispersion with LVDS Outputs

### **General Description**

The MAX40025 and MAX40026 are single-supply, high-speed comparators with a typical propagation delay of 280ps. The overdrive dispersion is extremely low (typical 25ps), making these comparators ideal for time-of-flight distance measurement applications.

The input common mode range of 1.5V to  $V_{DD}$  + 0.1V is compatible with the output swings of several widely used high-speed trans-impedance amplifiers, such as the MAX40658.

The output stage is LVDS (Low-Voltage Differential Signaling), which helps to minimize power dissipation and interfaces directly with many FPGAs and CPUs. Complementary outputs help in suppression of common-mode noise on each output line.

The MAX40025 is offered in a space-saving, tiny, 1.218mm x 0.818mm, 6-bump wafer-level package (WLP), while the MAX40026 is available in a 2mm x 2mm 8-pin TDFN side-wettable package and meets AEC-Q100 automotive qualification requirements. The MAX40025/MAX40026 operate over -40°C to +125°C temperature range and run from a single supply voltage of 2.7V to 3.6V.

### **Applications**

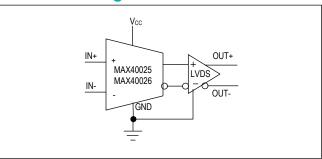
- Distance Sensing in LIDAR, RADAR, and SONAR
- Time-of-Flight Sensors
- High-Speed Differential Line Receivers
- High-Speed Triggering in Oscilloscopes
- Communications
- Oscillators
- Threshold Detectors
- High-Speed Level-Shifting
- Test and Measurement
- Automotive Applications

#### **Benefits and Features**

- Fast Propagation Delay: 280ps, Typ
- Low Overdrive Dispersion: 25ps (V<sub>OD</sub> = 10mV to 1V)
- Supply Voltage 2.7V to 3.6V
- 39.4mW at 2.7V Supply
- Power-Efficient LVDS Outputs
- -40°C to +125°C Temperature Range
- Automotive AEC-Q100 Qualified (TDFN-8 Version)
- Internal 1.5mV Hysteresis: MAX40026
- Internal 2.5mV Hysteresis: MAX40025A

<u>Ordering Information</u> appears at end of data sheet.

### **Functional Diagram**





# 280ps High-Speed Comparator, Ultra-Low Dispersion with LVDS Outputs

### **Absolute Maximum Ratings**

V <sub>CC</sub> to GND	0.3V to +3.6V
Either IN+ or IN- to GND	0.3V to $V_{CC}$ + 0.3V
Either OUT+ or OUT- to GND	$-0.3V$ to $V_{DD} + 0.3V$
OUT+ to OUT	0.5V to +0.5V
Current Into Any Pin (Continuous)	10mA
Continuous Power Dissipation (Multilayer	Board) (WLP) $(T_A =$
+70°C, derate 10.51mW/°C above +70°C).	816mW

Continuous Power Dissipation (Multilay	er Board) (TDFN) (T <sub>A</sub> =
+70°C, derate 9.8mW/°C above +70°C.	784mW
Operating Temperature Range	40°C to +125°C
Junction Temperature	+150°C
Storage Temperature Range	40°C to +150°C
Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **Package Information**

#### **WLP**

Package Code	W60D1+1
Outline Number	21-100296
Land Pattern Number	Refer to Application Note 1891
Thermal Resistance, Four-Layer Board:	
Junction-to-Ambient (θ <sub>JA</sub> )	95.15°C/W
Junction-to-Case Thermal Resistance (θ <sub>JC</sub> )	N/A

#### 8-TDFN

Package Code	T822Y+3
Outline Number	<u>21-100185</u>
Land Pattern Number	90-100070
Thermal Resistance, Single-Layer Board:	
Junction-to-Ambient (θ <sub>JA</sub> )	130°C/W
Junction-to-Case Thermal Resistance (θ <sub>JC</sub> )	8°C/W
Thermal Resistance, Four-Layer Board:	
Junction-to-Ambient (θ <sub>JA</sub> )	102°C/W
Junction-to-Case Thermal Resistance (θ <sub>JC</sub> )	8°C/W

For the latest package outline information and land patterns (footprints), go to <a href="https://www.maximintegrated.com/packages">www.maximintegrated.com/packages</a>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <a href="https://www.maximintegrated.com/thermal-tutorial">www.maximintegrated.com/thermal-tutorial</a>.

#### **Electrical Characteristics**

 $(V_{CC}$  = 3.3V,  $V_{CM}$  = 2.5V,  $R_{LOAD}$  = 100 $\Omega$ , connected from OUT+ to OUT-,  $T_A$  = -40°C to +125°C (Note 1))

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Supply Voltage (Note 2)	V <sub>CC</sub>	Guaranteed by PSRR specification	2.7		3.6	٧
Supply Current	Icc			17	23	mA

### **Electrical Characteristics (continued)**

 $(V_{CC}$  = 3.3V,  $V_{CM}$  = 2.5V,  $R_{LOAD}$  = 100 $\Omega$ , connected from OUT+ to OUT-,  $T_A$  = -40°C to +125°C (Note 1))

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Power-Up Time	t <sub>ON</sub>	Measured using supply current >75% of final value		20		μs
Power Supply Rejection Ratio (Note 2)	PSRR	2.7V ≤ V <sub>CC</sub> ≤ 3.6V	50	80		dB
Input Common Mode Range (Note 2)	V <sub>CM</sub>	Guaranteed by CMRR specification	1.5		V <sub>CC</sub> + 0.1	V
Input Offset Voltage (Note 2)	V <sub>OS</sub>	Over the Input common mode range		0.5	5	mV
Common Mode Rejection Ratio (Note 2)	CMRR	Over the Input common mode range	52	80		dB
Input Hystorosis	V. n <b>2</b>	MAX40025A		2.5		mV
Input Hysteresis	$V_{HYS}$	MAX40026		1.5		IIIV
Input Bias Current	Ι <sub>Β</sub>	Over the Input common mode range. Inputs shorted together.		1.3	10	μA
Input Offset Current	Ios	$V_{IN+} = V_{IN-}$		0.1	4	μA
Input Capacitance	C <sub>IN</sub>	Either input, over entire Input common mode range		2		pF
Output Differential Voltage	V <sub>OUTDIFF</sub>	V <sub>OUT+</sub> - V <sub>OUT-</sub>	247	350	454	mV
Output Differential Voltage Match		V <sub>OUT+</sub> - V <sub>OUT-</sub>	-50		+50	mV
Output Common-Mode Voltage	V <sub>CMOUT</sub>	Either output polarity	1.125	1.23	1.375	V
Output Common-Mode Voltage Match		Either output polarity	-50		+50	mV
Output Common-Mode Transient		Either output transition polarity		18		mVp-p
Output Short-Circuit Current	I <sub>SC</sub>	Either output shorted to ground, either polarity			24	mA
Current		Outputs shorted together, either polarity	-12		+12	
		20mV overdrive		270		
Propagation Delay	$t_{PD}$	100mV overdrive		280		ps
		200mV overdrive		280		
Jitter	t <sub>JITTER</sub>	Measured using square wave with Rise and Fall Time = 150ps, 100mV overdrive		2		ps
Overalis of Discours		10mV to 1V		25		
Overdrive Dispersion	t <sub>OD-disp</sub>	20mV to 100mV		10		ps
Rise Time	t <sub>R</sub>	From 25% to 75% output swing		150		ps
Fall Time	t⊨	From 75% to 25% output swing		165		ps

### **Electrical Characteristics (continued)**

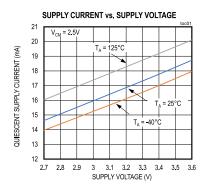
 $(V_{CC}$  = 3.3V,  $V_{CM}$  = 2.5V,  $R_{LOAD}$  = 100 $\Omega$ , connected from OUT+ to OUT-,  $T_A$  = -40°C to +125°C (Note 1))

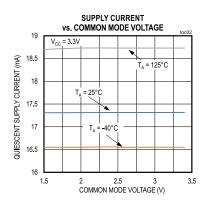
PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Output Skew		Measured using square wave with Rise and Fall Time = 150ps, 100mV overdrive	Propagation Delay difference between OUT+ and OUT-		10		ps
Maximum Taggla Data	<b>T</b> _	V <sub>OUT</sub> = 550mV,	MAX40025		4		Gbps
Maximum Toggle Rate T <sub>R</sub>	V <sub>OD</sub> = 100mV	MAX40026		3		Gups	
Minimum Pulse Width		both MAX40025/ MAX40026			330		ps

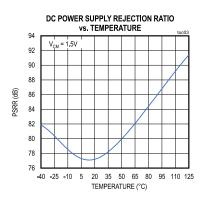
Note 1: Limits are 100% tested at  $T_A$  = +25°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization.

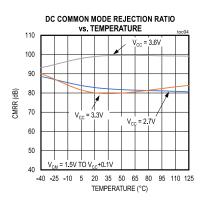
Note 2: Specifications are guaranteed by design and characterization and not production tested.

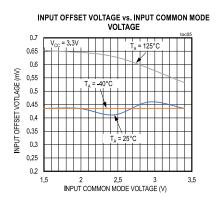
### **Typical Operating Characteristics**

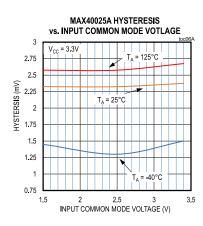


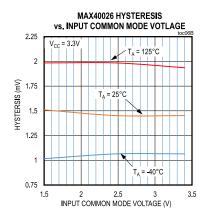


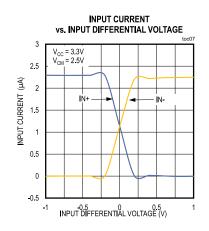


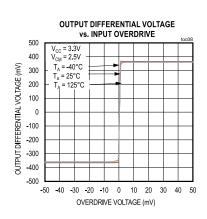




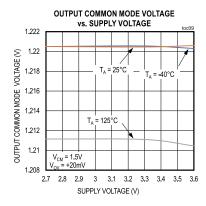


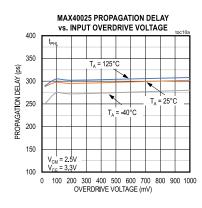


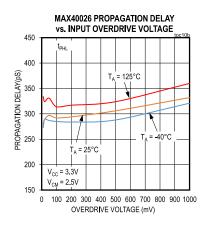


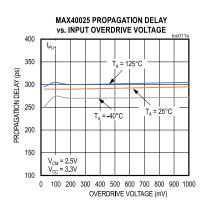


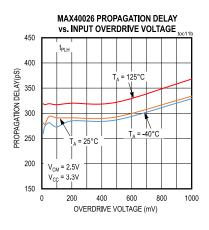
### **Typical Operating Characteristics (continued)**

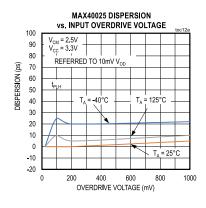


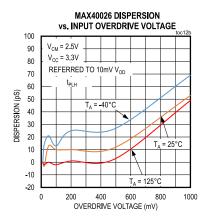


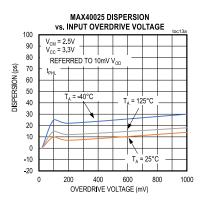


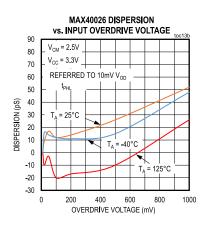




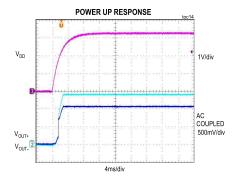






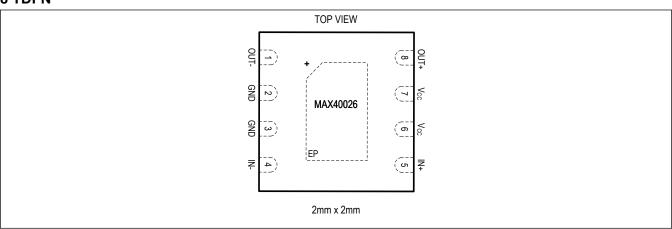


### **Typical Operating Characteristics (continued)**

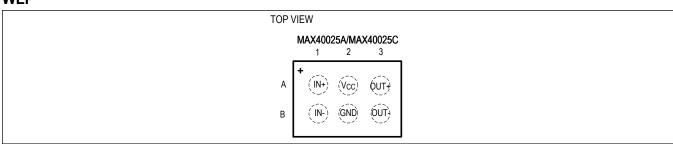


## **Pin Configurations**

### 8 TDFN



### **WLP**



# 280ps High-Speed Comparator, Ultra-Low Dispersion with LVDS Outputs

## **Pin Description**

Р	IN			
MAX40026	MAX40025A/ MAX40025C	NAME	FUNCTION	
1	В3	OUT-	Inverting LVDS Output. Connect a 100 $\Omega$ termination resistor between OUT- and OUT+. OUT- is at logic-low if V <sub>IN+</sub> is at higher voltage compared to V <sub>IN-</sub> .	
2, 3	B2	GND	Ground. Signal and power return (for TDFN-8: connect pins 2 and 3 together externally).	
4	B1	IN-	Inverting Input	
5	A1	IN+	Non-Inverting Input	
6,7	A2	V <sub>CC</sub>	Positive Supply. For TDFN-8, connect pins 6 and 7 together externally.	
8	А3	OUT+	Non-Inverting LVDS Output. Connect a $100\Omega$ termination resistor between OUT+ and OUT OUT+ is at logic-high if $V_{IN+}$ is at higher voltage compared to $V_{IN-}$ .	
EP	_	Exposed Paddle	Exposed Pad (TDFN-8 Only). This pad must be connected to ground.	

### **Detailed Description**

The MAX40025 and MAX40026 are single-supply, high-speed comparators with a typical propagation delay of 280ps. The overdrive dispersion is extremely low (25ps, typ.), making these comparators ideal for time-of-flight distance measurement applications.

The input common-mode range of 1.5V to  $V_{DD}$  + 0.1V is compatible with the outputs of several widely used high-speed transimpedance amplifiers, such as the MAX40658. The output stage is LVDS (Low-Voltage Differential Signaling), which helps to minimize power dissipation and interfaces directly with many modern FPGAs and CPUs.

The MAX40025 and MAX40026 operate from a +2.7V to +3.6V power supply voltage while typically consuming only 17mA quiescent current at 3.3V. The MAX40025 and MAX40026 are available in space-saving 6-WLP and 8-TDFN packages, respectively.

#### **LVDS Outputs**

Each LVDS output has a switched 3.25 mA current source. The outputs are differentially terminated with an external  $100\Omega$  resistor, which produces a  $\pm 350$  mV differential output. The power delivered to the  $100\Omega$  load resistor is only 1.1mW while enabling transmission data rates up to a few hundreds of Megabits per second. The output common-mode voltage is maintained at 1.23 V on both outputs, and is independent of power supply voltage. The fully differential LVDS outputs provide high-speed digital signalling with reduced EMI compared to single-ended outputs.

#### **System Timing Definitions**

### **Table 1. Timing Definitions**

SYMBOL	SPECIFICATION	DESCRIPTION
V <sub>OD</sub>	Overdrive Voltage	Differential voltage applied across inputs during test
t <sub>PDH</sub>	Propagation Delay High on OUT+	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input V <sub>OS</sub> ) to the 50% point in the output low-to-high transition on OUT+
t <sub>PDL</sub>	Propagation Delay Low on OUT-	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input $V_{OS}$ ) to the 50% point in the output high-to-low transition on OUT-
Δt <sub>PDHO</sub>	Propagation Delay Skew on High	Difference in propagation delay on output transition from low to high on OUT+ to propagation delay from high to low on OUT-
Δt <sub>PDLO</sub>	Propagation Delay Skew on Low	Difference in propagation delay on output transition from high to low on OUT+ to propagation delay from low to high on OUT-
t <sub>R</sub>	Output Rise Time	Time taken by either OUT+ or OUT- to rise from 25% of final output voltage to 75% of final output voltage
t <sub>F</sub>	Output Fall Time	Time taken by either OUT+ or OUT- to fall from 75% of final output voltage to 25% of final output voltage
t <sub>PD</sub> _	Propagation Delay Low on OUT-	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input V <sub>OS</sub> ) to the 50% point in the output high-to-low transition on OUT-
t <sub>PDH</sub>	Propagation Delay High on OUT-	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input $V_{OS}$ ) to the 50% point in the output low-to-high transition on OUT-
t <sub>PDHD</sub>	Differential Propagation Delay High	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input V <sub>OS</sub> ) to the 50% point in the output differential signal across OUT+ to OUT- while switching low to high

### **Table 1. Timing Definitions (continued)**

t <sub>PDLD</sub>	Differential Propagation Delay Low	Propagation delay measured from the time the differential input signal changes polarity ( $\pm$ input V <sub>OS</sub> ) to the 50% point in the output differential signal across OUT+ to OUT- while switching high to low
V <sub>OH</sub>	Output Voltage High	Comparator output high state voltage level
V <sub>OL</sub>	Output Voltage Low	Comparator output low state voltage level

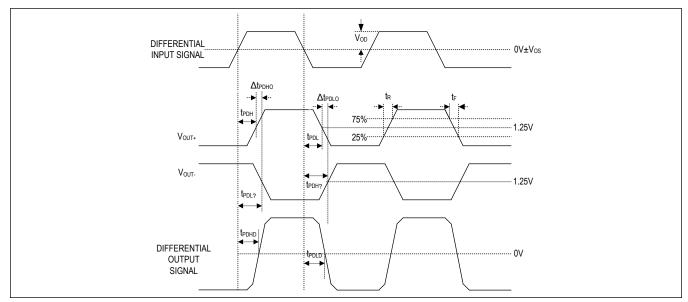


Figure 1. System Timing Diagram

### **Propagation Delay**

The propagation delay is defined as the delay between the differential comparator input voltage changing polarity and the output(s) reaching the mid-point of the high-to-low or low-to-high transition. The low-to-high propagation delay is  $t_{PDH}$  on OUT+ and  $t_{PDH}$  on OUT-, whereas the high-to-low propagation delay is  $t_{PDL}$  on OUT+ and  $t_{PDL}$  on OUT-. These high-to-low and low-to-high timing parameters will differ slightly due to mismatches between the two complementary outputs. As a result, this difference in propagation delay is considered to be a skew for a given combination of low-to-high transitions on OUT+ and high-to-low transitions on OUT-.

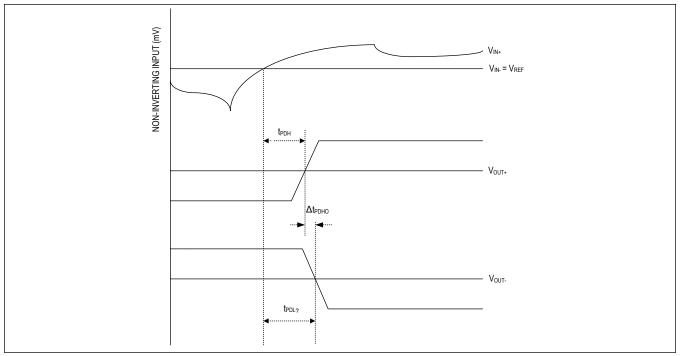


Figure 2. Propagation Delay

### **Propagation Delay Dispersion**

Dispersion, or variation of the propagation delay under different conditions, is affected by the amount of overdrive voltage applied to the comparator inputs. As can be seen in the Typical Operating Characteristics, the dispersion is typically under 25ps for 10mV to 1V, a wide range of input overdrive values.

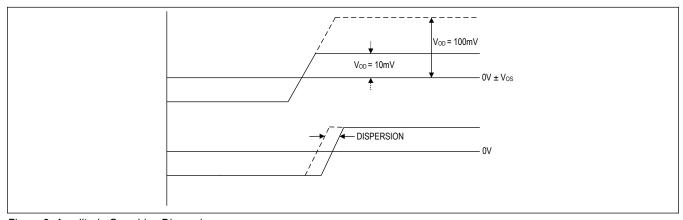


Figure 3. Amplitude Overdrive Dispersion

Dispersion is also affected by the input slew rate. As the slew rate of the input signal changes, the propagation delay also changes. The dispersion is typically under 15ps from  $0.4V/\mu s$  to  $1V/\mu s$  input slew rates.

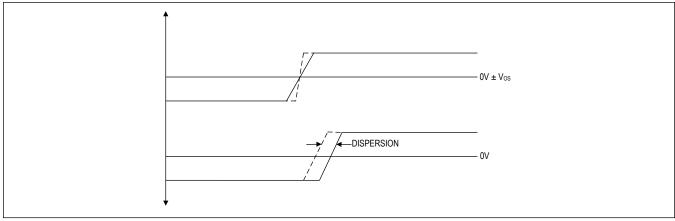


Figure 4. Slew Rate Dispersion

#### **Hysteresis**

Adding a small amount hysteresis to a comparator in a noisy environment is useful when input signals are slow-moving and have small noise levels superimposed on them. However, hysteresis must be used carefully when signals are small because it can cause valid signals to be ignored. <u>Figure 5</u> shows the input signal and output response for a comparator with hysteresis applied.

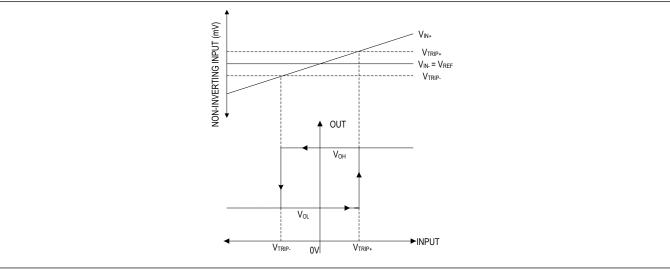


Figure 5. Hysteresis Transfer Function

The MAX40025C is optimized for detecting very small, fast-changing signals and therefore has no internal hysteresis. The MAX40025A has fixed internal 2.5mV hysteresis and the MAX40026 has fixed internal 1.5mV hysteresis, which improves their usefulness for detecting larger differential input signals in the presence of noise. This helps to avoid the external components and potential stability degradation associated with external positive feedback paths.

#### Input Stage Circuitry

The MAX40025/MAX40026 include internal protection circuitry that prevents damage to the precision input stage from large differential input voltages. This protection circuitry consists of two groups of two front-to-back diodes between IN+ and IN-, as well as two  $50\Omega$  resistors (<u>Figure 6</u>). The diodes limit the differential voltage applied to the comparator's internal circuitry to no more than  $2V_F$ , where  $V_F$  is the diode's forward-voltage drop (about 0.7V at +25°C).

# 280ps High-Speed Comparator, Ultra-Low Dispersion with LVDS Outputs

For a large differential input voltage (exceeding 2V<sub>F</sub>), this protection circuitry increases the input bias current at IN+ (source) and IN- (sink).

INPUT CURRENT = 
$$\frac{\left(V_{\text{IN}} + -V_{\text{IN}} - \right) - 2 \times V_F}{2 \times 50}$$

Input currents with large differential input voltages should not be confused with input bias currents ( $I_B$ ). As long as the differential input voltage is less than  $2V_F$ , this input current is less than  $2I_B$ .

The input circuitry allows the MAX40025/MAX40026's input common-mode range to extend 100mV beyond the positive power-supply rail. The output remains in the correct logic state if one or both inputs are within the common-mode range. Taking either input outside the common-mode range causes the input to saturate and the propagation delay to increase.

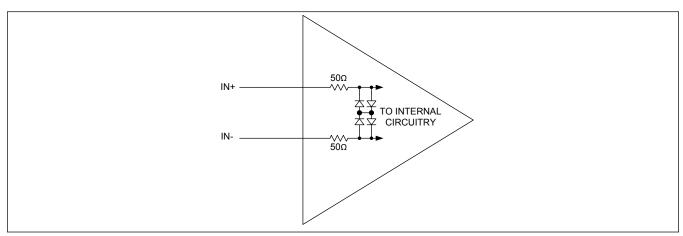


Figure 6. Input Stage Circuitry

### **Applications Information**

#### **Critical Layout Guidelines**

Some critical Layout guidelines are listed below.

- Use a PC board with a low-impedance ground plane.
- Mount one or more 10nF ceramic capacitors between GND and V<sub>CC</sub>, as close to the pins as possible. Multiple bypass
  capacitors help to reduce the effect of trace impedance and capacitor ESR.
- Choose bypass capacitors for minimum inductance and ESR.
- Use a 100Ω termination resistor for the LVDS output, connected directly between OUT+ and OUT-, if practical. If the
  destination LVDS inputs can't be located adjacent to the outputs, use a 100Ω microstrip between the output pins and
  the termination resistor, which should be close to the LVDS inputs of the FPGA or other destination component. This
  will avoid the creation of stub beyond the termination resistor, which will cause reflections. The added length of the
  differential trace has less degrading affects than added stub length.
- Ensure that there is no parasitic coupling between the inputs and the outputs. Such coupling serves as feedback, and can result in oscillation.
- Minimize any parasitic layout inductance.
- It is recommended to use higher performance substrate materials (for example, Rogers).
- A differential micro-strip is the recommended layout for MAX40025/MAX40026 with terminations done close to the
  inputs and outputs of the MAX40025 or MAX40026. Care must be taken to avoid unwanted stubs by removing ground
  below the traces that are not part of the 50Ω termination line leading into input pins. The parasitic capacitance created
  between traces and ground slow down and even distort the signals by creating reflections on the path.
- Below is an example from the MAX40025EVKIT#, where ground has been etched/removed underneath a stub as shown in the layer below top layer.

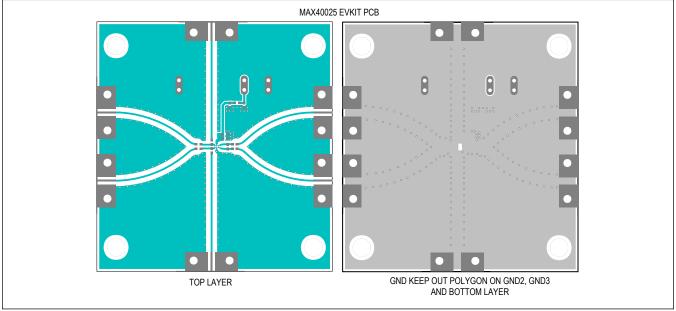


Figure 7. Layout Guidelines—Ground Keep-Out to Avoid Stubs.

#### **Input Slew Rate**

With slower slew rates, when the input voltage is near the threshold any parasitic feedback paths can cause oscillation. In addition, the comparator's input noise will cause the output to undergo transitions. Eliminating feedback paths will stop

oscillation. To avoid noise-induced chattering, the input slew rate should be greater than 1V/µs.

#### **Typical Application Circuits**

Receiver Section of Differential Time-of-Flight Measurement Circuit:

In <u>Figure 8</u>, the photodiode, shown at the far right, converts light incident upon it into current that drives the input of the MAX40658 Transimpedance Amplifier (TIA). The MAX40658 then converts photodiode current to voltage, amplifies it, and passes a replica of the incident light to input of the MAX40025 high-speed comparator. By default, the MAX40658 has -27mV differential output offset voltage when there is no input current. This offset can be adjusted using the MAX40658's offset pin. The MAX40025 produces differential output pulses whenever an incident light pulse has intensity sufficient to change the polarity of the comparator input signal.

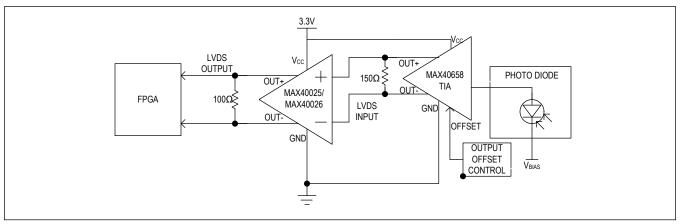


Figure 8. Differential-Ended Output Receiver

Receiver Section of Single-Ended Time-of-Flight Measurement Circuit:

<u>Figure 9</u> has a single-ended output configuration on the transimpedance amplifier, which drives one input of the comparator. This functionality is the same as that of the differential configuration discussed above, except that the threshold voltage can be adjusted by selecting the values of R1 and R2.

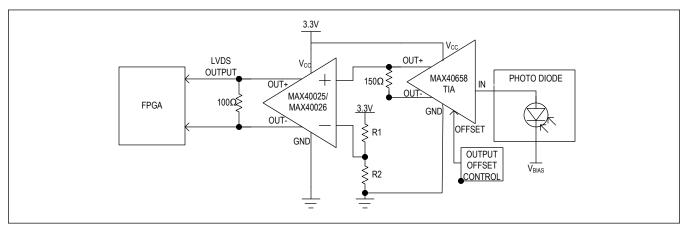


Figure 9. Single-Ended Output Receiver

# 280ps High-Speed Comparator, Ultra-Low Dispersion with LVDS Outputs

## **Ordering Information**

PART NUMBER	TEMPERATURE RANGE	PIN-PACKAGE	TOP MARK	HYSTERESIS
MAX40025AAWT+	-40°C to +125°C	6-WLP	+AAC	2.5mv
MAX40025CAWT+	-40°C to +125°C	6-WLP	+AAB	No Hysterisis
MAX40026ATA/VY+	-40°C to +125°C	8-TDFN	+BSS	1.5mV
MAX40026ATA+	-40°C to +125°C	8-TDFN	+BTF	1.5mV

<sup>+</sup>Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

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### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	11/18	Initial release	_
1	12/18	Updated part numbers in title and equation in Detailed Description	1–17
2	1/19	Updated Pin Configuration Diagram and Pin Description	7
3	2/19	Updated data sheet for release of MAX40026	1–18
4	3/19	Updated data sheet for release of MAX40025A	1–18
5	9/19	Updated Ordering Information table	18

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