

## 50MHz, 800V/µs Op Amp

#### **FEATURES**

- 50MHz Gain Bandwidth
- 800V/µs Slew Rate
- 5mA Maximum Supply Current
- 9nV/√Hz Input Noise Voltage
- Unity-Gain Stable
- C-Load<sup>TM</sup> Op Amp Drives All Capacitive Loads
- 1mV Maximum Input Offset Voltage
- 1µA Maximum Input Bias Current
- 250nA Maximum Input Offset Current
- ±13V Minimum Output Swing into 500Ω
- ±3.2V Minimum Output Swing into 150Ω
- 4.5V/mV Minimum DC Gain, R<sub>I</sub> =1k
- 60ns Settling Time to 0.1%, 10V Step
- 0.2% Differential Gain,  $A_V=2$ ,  $R_I=150\Omega$
- 0.3° Differential Phase,  $A_V=2$ ,  $R_I=150\Omega$
- Specified at ±2.5V, ±5V, and ±15V

#### **APPLICATIONS**

- Wideband Amplifiers
- Buffers
- Active Filters
- Video and RF Amplification
- Cable Drivers
- Data Acquisition Systems

#### DESCRIPTION

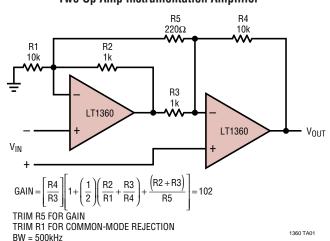
The LT1360 is a high speed, very high slew rate operational amplifier with excellent DC performance. The LT1360 features reduced supply current, lower input offset voltage, lower input bias current and higher DC gain than devices with comparable bandwidth. The circuit topology is a voltage feedback amplifier with the slewing characteristics of a current feedback amplifier. The amplifier is a single gain stage with outstanding settling characteristics which makes the circuit an ideal choice for data acquisition systems. The output drives a  $500\Omega$  load to  $\pm 3.2 \text{V}$  on  $\pm 5 \text{V}$  supplies. The amplifier is also capable of driving any capacitive load which makes it useful in buffer or cable driver applications.

The LT1360 is a member of a family of fast, high performance amplifiers using this unique topology and employing Linear Technology Corporation's advanced bipolar complementary processing. For dual and quad amplifier versions of the LT1360 see the LT1361/LT1362 data sheet. For 70MHz amplifiers with 6mA of supply current per amplifier see the LT1363 and LT1364/LT1365 data sheets. For lower supply current amplifiers with bandwidths of 12MHz and 25MHz see the LT1354 through LT1359 data sheets. Singles, duals and quads of each amplifier are available.

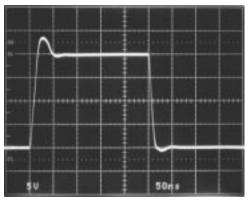
(C-Load LT are registered trademarks of Linear Technology Corporation. C-Load is a trademark of Linear Technology Corporation.

### TYPICAL APPLICATION

Two Op Amp Instrumentation Amplifier



 $A_V = -1$  Large-Signal Response



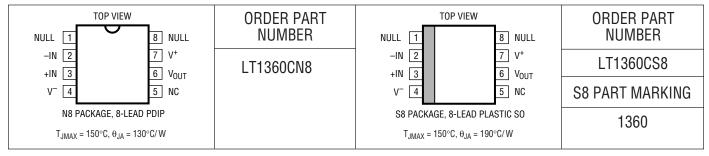
1360 TA0

## **ABSOLUTE MAXIMUM RATINGS** (Note 1)

Total Supply Voltage (V <sup>+</sup> to V <sup>-</sup> )	36V
Differential Input Voltage	
(Transient Only) (Note 2) ±	10V
Input Voltage	±V <sub>S</sub>
Output Short Circuit Duration (Note 3) Indefi	inite

Operating Temperature Range (Note 8) ... – 40°C to 85°C Specified Temperature Range (Note 9) .... – 40°C to 85°C Maximum Junction Temperature (See Below)

#### PACKAGE/ORDER INFORMATION



Consult factory for Industrial and Military grade parts.

## **ELECTRICAL CHARACTERISTICS** $T_A = 25^{\circ}C$ , $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	V <sub>SUPPLY</sub>	MIN	TYP	MAX	UNITS
V <sub>OS</sub>	Input Offset Voltage	(Note 4)	±15V		0.3	1.0	mV
			±5V		0.3	1.0	mV
			±2.5V		0.4	1.2	mV
I <sub>OS</sub>	Input Offset Current		±2.5V to ±15V		80	250	nA
I <sub>B</sub>	Input Bias Current		±2.5V to ±15V		0.3	1.0	μА
e <sub>n</sub>	Input Noise Voltage	f = 10kHz	±2.5V to ±15V		9		nV/√ <del>Hz</del>
in	Input Noise Current	f = 10kHz	±2.5V to ±15V		0.9		pA/√Hz
R <sub>IN</sub>	Input Resistance	V <sub>CM</sub> = ±12V	±15V	20	50		MΩ
	Input Resistance	Differential	±15V		5		MΩ
C <sub>IN</sub>	Input Capacitance		±15V		3		pF
	Input Voltage Range +		±15V	12.0	13.4		V
			±5V	2.5	3.4		V
			±2.5V	0.5	1.1		V
	Input Voltage Range -		±15V		-13.2	-12.0	V
			±5V		-3.2	-2.5	V
			±2.5V		-0.9	-0.5	V
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> = ±12V	±15V	86	92		dB
		$V_{CM} = \pm 2.5V$	±5V	79	84		dB
		$V_{CM} = \pm 0.5V$	±2.5V	68	74		dB
PSRR	Power Supply Rejection Ratio	$V_S = \pm 2.5 V \text{ to } \pm 15 V$		93	105		dB



## **ELECTRICAL CHARACTERISTICS** $T_A = 25^{\circ}C$ , $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	V <sub>SUPPLY</sub>	MIN TYP MAX	UNITS
A <sub>VOL</sub>	Large-Signal Voltage Gain	$\begin{array}{c} V_{OUT} = \pm 12 V, \; R_L = 1 k \\ V_{OUT} = \pm 10 V, \; R_L = 500 \Omega \\ V_{OUT} = \pm 2.5 V, \; R_L = 500 \Omega \\ V_{OUT} = \pm 2.5 V, \; R_L = 150 \Omega \\ V_{OUT} = \pm 1 V, \; R_L = 500 \Omega \end{array}$	±15V ±15V ±5V ±5V ±2.5V	4.5 9.0 3.0 6.5 3.0 6.4 1.5 4.2 2.5 5.2	V/mV V/mV V/mV V/mV V/mV
V <sub>OUT</sub>	Output Swing	$\begin{array}{l} R_L = 1 k,  V_{IN} = \pm 40 mV \\ R_L = 500 \Omega,  V_{IN} = \pm 40 mV \\ R_L = 500 \Omega,  V_{IN} = \pm 40 mV \\ R_L = 150 \Omega,  V_{IN} = \pm 40 mV \\ R_L = 500 \Omega,  V_{IN} = \pm 40 mV \end{array}$	±15V ±15V ±5V ±5V ±2.5V	13.5 13.9 13.0 13.6 3.5 4.0 3.2 3.8 1.3 1.7	±V ±V ±V ±V ±V
I <sub>OUT</sub>	Output Current	$V_{OUT} = \pm 13V$ $V_{OUT} = \pm 3.2V$	±15V ±5V	26 34 21 29	mA mA
I <sub>SC</sub>	Short-Circuit Current	$V_{OUT} = 0V, V_{IN} = \pm 3V$	±15V	40 54	mA
SR	Slew Rate	A <sub>V</sub> = -2, (Note 5)	±15V ±5V	600 800 250 350	V/μs V/μs
	Full Power Bandwidth	10V Peak, (Note 6) 3V Peak, (Note 6)	±15V ±5V	12.7 18.6	MHz MHz
GBW	Gain Bandwidth	f = 1MHz	±15V ±5V ±2.5V	50 37 32	MHz MHz MHz
$t_r$ , $t_f$	Rise Time, Fall Time	A <sub>V</sub> = 1, 10%-90%, 0.1V	±15V ±5V	3.1 4.3	ns ns
	Overshoot	A <sub>V</sub> = 1, 0.1V	±15V ±5V	35 27	% %
	Propagation Delay	50% V <sub>IN</sub> to 50% V <sub>OUT</sub> , 0.1V	±15V ±5V	5.2 6.4	ns ns
t <sub>s</sub>	Settling Time	10V Step, 0.1%, $A_V = -1$ 10V Step, 0.01%, $A_V = -1$ 5V Step, 0.1%, $A_V = -1$	±15V ±15V ±5V	60 90 65	ns ns ns
	Differential Gain	$f = 3.58MHz, A_V = 2, R_L = 150\Omega$ $f = 3.58MHz, A_V = 2, R_L = 1k$	±15V ±5V ±15V ±5V	0.20 0.20 0.04 0.02	% % % %
	Differential Phase	$f = 3.58MHz, A_V = 2, R_L = 150\Omega$ $f = 3.58MHz, A_V = 2, R_L = 1k$	±15V ±5V ±15V ±5V	0.40 0.30 0.07 0.26	Deg Deg Deg Deg
$R_0$	Output Resistance	A <sub>V</sub> = 1, f = 1MHz	±15V	1.4	Ω
I <sub>S</sub>	Supply Current		±15V ±5V	4.0 5.0 3.8 4.8	mA mA



# **ELECTRICAL CHARACTERISTICS** The ullet denotes the specifications which apply over the temperature range $0^{\circ}C \leq T_{A} \leq 70^{\circ}C$ , $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	V <sub>SUPPLY</sub>		MIN	TYP	MAX	UNITS
$\overline{V_{0S}}$	Input Offset Voltage	(Note 4)	±15V	•			1.5	mV
			±5V	•			1.5	mV
			±2.5V	•			1.7	mV
	Input V <sub>OS</sub> Drift	(Note 7)	±2.5V to ±15V	•		9	12	μV/°C
I <sub>OS</sub>	Input Offset Current		±2.5V to ±15V	•			350	nA
I <sub>B</sub>	Input Bias Current		±2.5V to ±15V	•			1.5	μА
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> = ±12V	±15V	•	84			dB
		$V_{CM} = \pm 2.5 V$	±5V	•	77			dB
		$V_{CM} = \pm 0.5V$	±2.5V	•	66			dB
PSRR	Power Supply Rejection Ratio	$V_S = \pm 2.5 V \text{ to } \pm 15 V$		•	91			dB
A <sub>VOL</sub>	Large-Signal Voltage Gain	$V_{OUT} = \pm 12V, R_L = 1k$	±15V	•	3.6			V/mV
		$V_{OUT} = \pm 10V, R_L = 500\Omega$	±15V	•	2.4			V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 500 \Omega$	±5V	•	2.4			V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 150 \Omega$	±5V	•	1.0			V/mV
		$V_{OUT} = \pm 1V$ , $R_L = 500\Omega$	±2.5V	•	2.0			V/mV
$V_{OUT}$	Output Swing	$R_L = 1k, V_{IN} = \pm 40mV$	±15V	•	13.4			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±15V	•	12.8			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±5V	•	3.4			±V
		$R_L = 150\Omega$ , $V_{IN} = \pm 40$ mV	±5V	•	3.1			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±2.5V	•	1.2			<u>±V</u>
l <sub>OUT</sub>	Output Current	$V_{OUT} = \pm 12.8V$	±15V	•	25			mA
		$V_{OUT} = \pm 3.1V$	±5V	•	20			mA
I <sub>SC</sub>	Short-Circuit Current	$V_{OUT} = 0V$ , $V_{IN} = \pm 3V$	±15V	•	32			mA
SR	Slew Rate	$A_V = -2$ , (Note 5)	±15V	•	475			V/µs
			±5V	•	185			V/µs
Is	Supply Current		±15V	•			5.8	mA
			±5V	•			5.6	mA



# **ELECTRICAL CHARACTERISTICS** The $\bullet$ denotes the specifications which apply over the temperature range $-40^{\circ}\text{C} \le T_{A} \le 85^{\circ}\text{C}$ , $V_{CM} = 0V$ unless otherwise noted. (Note 9)

SYMBOL	PARAMETER	CONDITIONS	V <sub>SUPPLY</sub>		MIN	TYP	MAX	UNITS
$V_{0S}$	Input Offset Voltage	(Note 4)	±15V	•			2.0	mV
			±5V	•			2.0	mV
			±2.5V	•			2.2	mV
	Input V <sub>OS</sub> Drift	(Note 7)	±2.5V to ±15V	•		9	12	μV/°C
I <sub>OS</sub>	Input Offset Current		±2.5V to ±15V	•			400	nA
I <sub>B</sub>	Input Bias Current		±2.5V to ±15V	•			1.8	μΑ
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> = ±12V	±15V	•	84			dB
		$V_{CM} = \pm 2.5 V$	±5V	•	77			dB
		$V_{CM} = \pm 0.5V$	±2.5V		66			dB
PSRR	Power Supply Rejection Ratio	$V_S = \pm 2.5 V \text{ to } \pm 15 V$		•	90			dB
A <sub>VOL</sub>	Large-Signal Voltage Gain	$V_{OUT} = \pm 12V, R_L = 1k$	±15V	•	2.5			V/mV
		$V_{OUT} = \pm 10V$ , $R_L = 500\Omega$	±15V	•	1.5			V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 500 \Omega$	±5V	•	1.5			V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 150 \Omega$	±5V	•	0.6			V/mV
		$V_{OUT} = \pm 1V$ , $R_L = 500\Omega$	±2.5V	•	1.3			V/mV
$V_{OUT}$	Output Swing	$R_L = 1k\Omega$ , $V_{IN} = \pm 40mV$	±15V	•	13.4			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±15V	•	12.0			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±5V		3.4			±V
		$R_L = 150\Omega$ , $V_{IN} = \pm 40$ mV	±5V	•	3.0			±V
		$R_L = 500\Omega$ , $V_{IN} = \pm 40$ mV	±2.5V	•	1.2			<u>±V</u>
$I_{OUT}$	Output Current	$V_{OUT} = \pm 12.0V$	±15V	•	24			mA
		$V_{OUT} = \pm 3.0V$	±5V	•	20			mA
I <sub>SC</sub>	Short-Circuit Current	$V_{OUT} = 0V$ , $V_{IN} = \pm 3V$	±15V	•	30			mA
SR	Slew Rate	$A_V = -2$ , (Note 5)	±15V	•	450			V/µs
			±5V	•	175			V/µs
Is	Supply Current		±15V	•			6.0	mA
			±5V	•			5.8	mA

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

**Note 2:** Differential inputs of  $\pm 10$ V are appropriate for transient operation only, such as during slewing. Large, sustained differential inputs will cause excessive power dissipation and may damage the part. See Input Considerations in the Applications Information section of this data sheet for more details.

**Note 3:** A heat sink may be required to keep the junction temperature below absolute maximum when the output is shorted indefinitely.

**Note 4:** Input offset voltage is pulse tested and is exclusive of warm-up drift.

**Note 5:** Slew rate is measured between  $\pm 10V$  on the output with  $\pm 6V$  input for  $\pm 15V$  supplies and  $\pm 2V$  on the output with  $\pm 1.75V$  input for  $\pm 5V$  supplies.

**Note 6:** Full power bandwidth is calculated from the slew rate measurement: FPBW =  $SR/2\pi V_P$ .

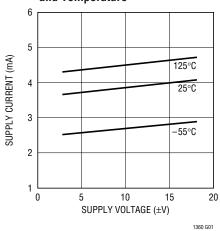
Note 7: This parameter is not 100% tested.

**Note 8:** The LT1360C is guaranteed functional over the operating temperature range of  $-40^{\circ}$ C to  $85^{\circ}$ C.

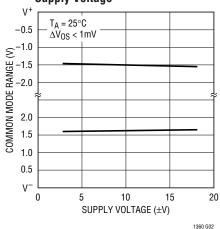
**Note 9:** The LT1360C is guaranteed to meet specified performance from  $0^{\circ}$ C to  $70^{\circ}$ C. The LT1360C is designed, characterized and expected to meet specified performance from  $-40^{\circ}$ C to  $85^{\circ}$ C, but is not tested or QA sampled at these temperatures. For guaranteed I-grade parts, consult the factory.



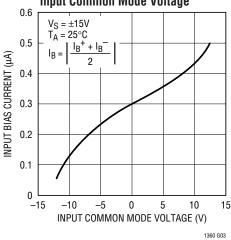




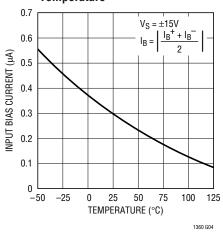
#### Input Common Mode Range vs Supply Voltage



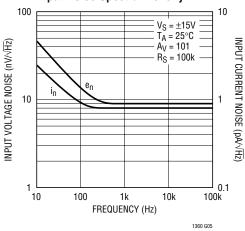
#### Input Bias Current vs Input Common Mode Voltage



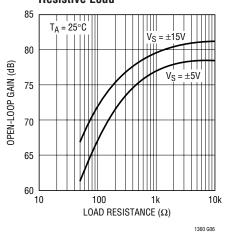
#### Input Bias Current vs Temperature



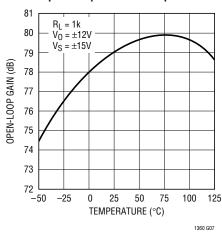
**Input Noise Spectral Density** 



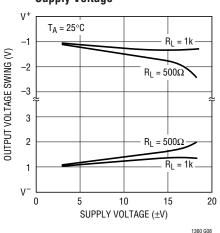
Open-Loop Gain vs Resistive Load



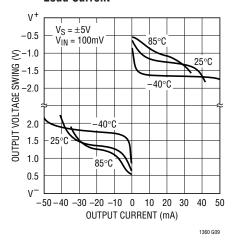
#### **Open-Loop Gain vs Temperature**



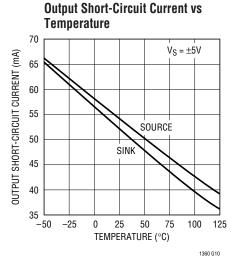
Output Voltage Swing vs Supply Voltage

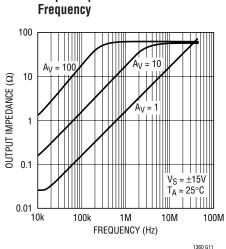


Output Voltage Swing vs Load Current

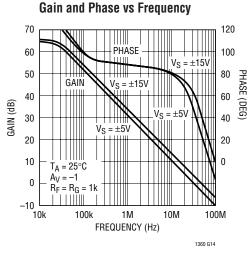




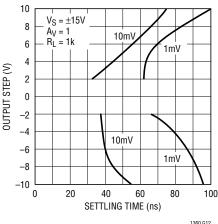


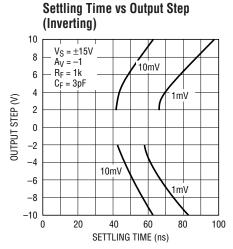


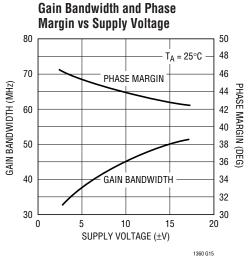
**Output Impedance vs** 



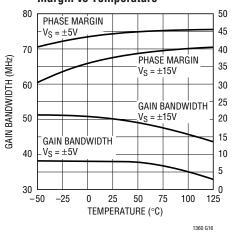
Settling Time vs Output Step (Noninverting)

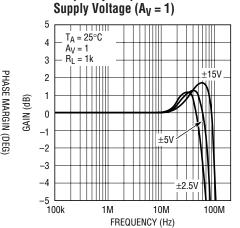






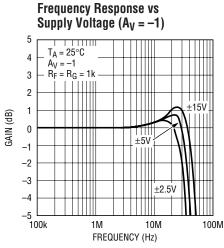
Gain Bandwidth and Phase Margin vs Temperature



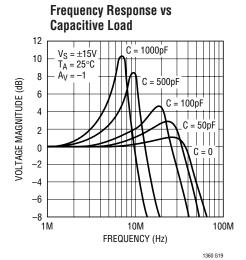


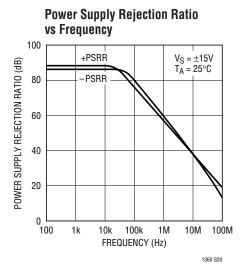
1360 G17

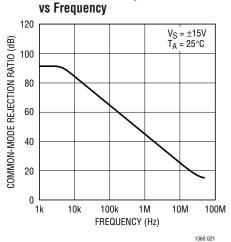
Frequency Response vs



1360 G18

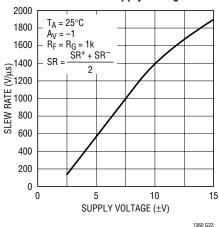


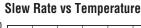


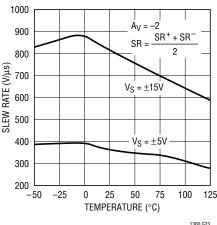


**Common Mode Rejection Ratio** 

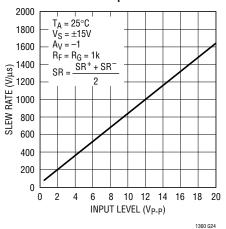




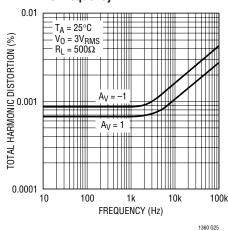




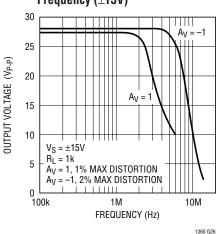
Slew Rate vs Input Level



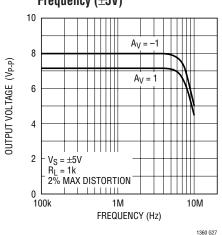
## Total Harmonic Distortion vs Frequency



## Undistorted Output Swing vs Frequency (±15V)

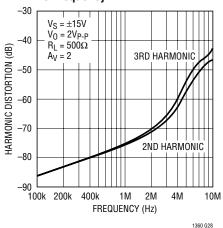


#### Undistorted Output Swing vs Frequency (±5V)

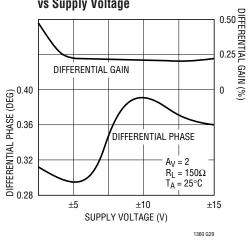




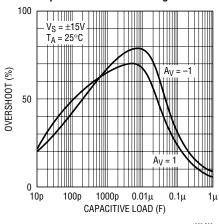
2nd and 3rd Harmonic Distortion vs Frequency



**Differential Gain and Phase** vs Supply Voltage

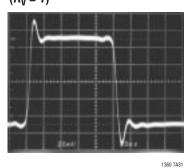


**Capacitive Load Handling** 

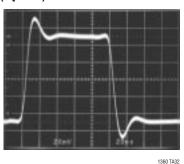


1360 G30

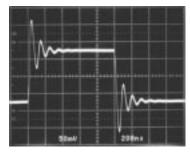
**Small-Signal Transient**  $(A_V = 1)$ 



**Small-Signal Transient**  $(A_V = -1)$ 

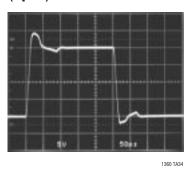


**Small-Signal Transient**  $(A_V = -1, C_L = 500pF)$ 

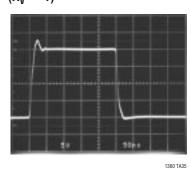


1360 TA33

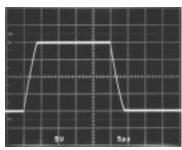
**Large-Signal Transient**  $(A_V = 1)$ 



**Large-Signal Transient**  $(A_V = -1)$ 



**Large-Signal Transient**  $(A_V = 1, C_L = 10,000pF)$ 

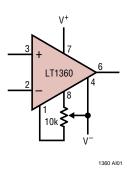


1360 TA36

#### APPLICATIONS INFORMATION

The LT1360 may be inserted directly into AD817, AD847, EL2020, EL2044, and LM6361 applications improving both DC and AC performance, provided that the nulling circuitry is removed. The suggested nulling circuit for the LT1360 is shown below.

#### Offset Nulling



#### **Layout and Passive Components**

The LT1360 amplifier is easy to apply and tolerant of less than ideal layouts. For maximum performance (for example fast settling time) use a ground plane, short lead lengths, and RF-quality bypass capacitors (0.01 $\mu$ F to 0.1 $\mu$ F). For high drive current applications use low ESR bypass capacitors (1 $\mu$ F to 10 $\mu$ F tantalum). Sockets should be avoided when maximum frequency performance is required, although low profile sockets can provide reasonable performance up to 50MHz. For more details see Design Note 50.

The parallel combination of the feedback resistor and gain setting resistor on the inverting input can combine with the input capacitance to form a pole which can cause peaking or oscillations. For feedback resistors greater than 5kW, a parallel capacitor of value

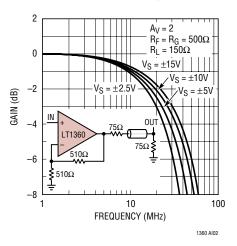
$$C_F > R_G \times C_{IN}/R_F$$

should be used to cancel the input pole and optimize dynamic performance. For unity-gain applications where a large feedback resistor is used,  $C_F$  should be greater than or equal to  $C_{\text{IN}}$ .

#### **Capacitive Loading**

The LT1360 is stable with any capacitive load. This is accomplished by sensing the load induced output pole and adding compensation at the amplifier gain node. As the capacitive load increases, both the bandwidth and phase margin decrease so there will be peaking in the frequency domain and in the transient response as shown in the typical performance curves. The photo of the small-signal response with 500pF load shows 60% peaking. The large-signal response with a 10,000pF load shows the output slew rate being limited to 5V/ $\mu$ s by the short-circuit current. Coaxial cable can be driven directly, but for best pulse fidelity a resistor of value equal to the characteristic impedance of the cable (i.e., 75 $\Omega$ ) should be placed in series with the output. The other end of the cable should be terminated with the same value resistor to ground.

#### **Cable Driver Frequency Response**



#### APPLICATIONS INFORMATION

#### **Input Considerations**

Each of the LT1360 inputs is the base of an NPN and a PNP transistor whose base currents are of opposite polarity and provide first-order bias current cancellation. Because of variation in the matching of NPN and PNP beta, the polarity of the input bias current can be positive or negative. The offset current does not depend on NPN/PNP beta matching and is well controlled. The use of balanced source resistance at each input is recommended for applications where DC accuracy must be maximized.

The inputs can withstand transient differential input voltages up to 10V without damage and need no clamping or source resistance for protection. Differential inputs, however, generate large supply currents (tens of mA) as required for high slew rates. If the device is used with sustained differential inputs, the average supply current will increase, excessive power dissipation will result and the part may be damaged. The part should not be used as a comparator, peak detector or other open-loop application with large, sustained differential inputs. Under normal, closed-loop operation, an increase of power dissipation is only noticeable in applications with large slewing outputs and is proportional to the magnitude of the differential input voltage and the percent of the time that the inputs are apart. Measure the average supply current for the application in order to calculate the power dissipation.

#### **Power Dissipation**

The LT1360 combines high speed and large output drive in a small package. Because of the wide supply voltage range, it is possible to exceed the maximum junction temperature under certain conditions. Maximum junction temperature  $(T_J)$  is calculated from the ambient temperature  $(T_A)$  and power dissipation  $(P_D)$  as follows:

LT1360CN8: 
$$T_J = T_A + (P_D \times 130^{\circ}C/W)$$
  
LT1360CS8:  $T_J = T_A + (P_D \times 190^{\circ}C/W)$ 

Worst case power dissipation occurs at the maximum supply current and when the output voltage is at 1/2 of either supply voltage (or the maximum swing if less than 1/2 supply voltage). Therefore  $P_{DMAX}$  is:

$$P_{DMAX} = (V^+ - V^-)(I_{SMAX}) + (V^+/2)^2/R_L$$
  
Example: LT1360CS8 at 70°C,  $V_S = \pm 15V$ ,  $R_L = 250W$   
 $P_{DMAX} = (30V)(5.8mA) + (7.5V)^2/250W = 399mW$   
 $T_{JMAX} = 70°C + (399mW)(190°C/W) = 146°C$ 



#### APPLICATIONS INFORMATION

#### **Circuit Operation**

The LT1360 circuit topology is a true voltage feedback amplifier that has the slewing behavior of a current feedback amplifier. The operation of the circuit can be understood by referring to the simplified schematic. The inputs are buffered by complementary NPN and PNP emitter followers which drive a  $500\Omega$  resistor. The input voltage appears across the resistor generating currents which are mirrored into the high impedance node. Complementary followers form an output stage which buffers the gain node from the load. The bandwidth is set by the input resistor and the capacitance on the high impedance node. The slew rate is determined by the current available to charge the gain node capacitance. This current is the differential input voltage divided by R1, so the slew rate is proportional to the input. Highest slew rates are therefore seen in the lowest gain configurations. For example, a 10V output step in a gain of 10 has only a 1V input step, whereas the same output step in unity gain has a 10 times greater input step. The curve of Slew Rate vs Input Level illustrates this relationship. The LT1360 is tested for slew rate in a gain of -2 so higher slew rates can be expected in gains of 1 and -1, and lower slew rates in higher gain configurations.

The RC network across the output stage is bootstrapped when the amplifier is driving a light or moderate load and has no effect under normal operation. When driving a capacitive load (or a low value resistive load) the network

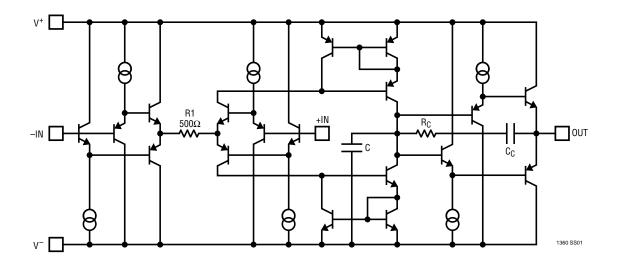
is incompletely bootstrapped and adds to the compensation at the high impedance node. The added capacitance slows down the amplifier which improves the phase margin by moving the unity-gain frequency away from the pole formed by the output impedance and the capacitive load. The zero created by the RC combination adds phase to ensure that even for very large load capacitances, the total phase lag can never exceed 180 degrees (zero phase margin) and the amplifier remains stable.

#### **Comparison to Current Feedback Amplifiers**

The LT1360 enjoys the high slew rates of Current Feedback Amplifiers (CFAs) while maintaining the characteristics of a true voltage feedback amplifier. The primary differences are that the LT1360 has two high impedance inputs and its closed loop bandwidth decreases as the gain increases. CFAs have a low impedance inverting input and maintain relatively constant bandwidth with increasing gain. The LT1360 can be used in all traditional op amp configurations including integrators and applications such as photodiode amplifiers and I-to-V converters where there may be significant capacitance on the inverting input. The frequency compensation is internal and not dependent on the value of the feedback resistor. For CFAs, the feedback resistance is fixed for a given bandwidth and capacitance on the inverting input can cause peaking or oscillations. The slew rate of the LT1360 in noninverting gain configurations is also superior in most cases.



## SIMPLIFIED SCHEMATIC



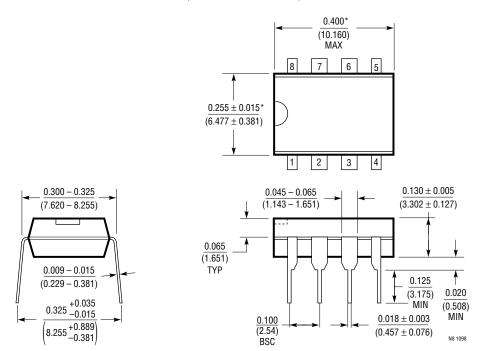


## PACKAGE DESCRIPTION

Dimension in inches (millimeters) unless otherwise noted.

N8 Package 8-Lead PDIP (Narrow 0.300)

(LTC DWG # 05-08-1510)



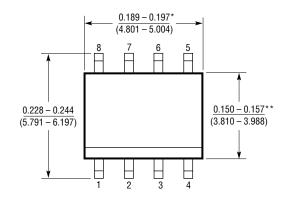
\*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.010 INCH (0.254mm)

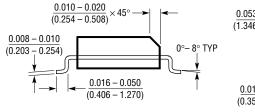
## PACKAGE DESCRIPTION

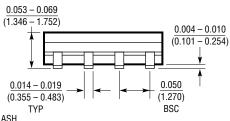
Dimension in inches (millimeters) unless otherwise noted.

S8 Package 8-Lead Plastic Small Outline (Narrow 0.150)

(LTC DWG # 05-08-1610)







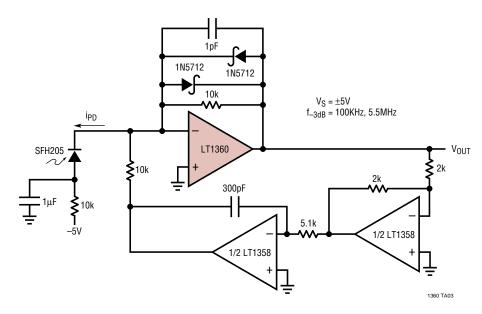
<sup>\*</sup>DIMENSION DOES NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.006" (0.152mm) PER SIDE

S08 1298

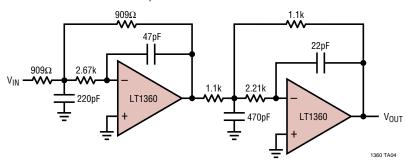
<sup>\*\*</sup>DIMENSION DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED 0.010" (0.254mm) PER SIDE

## TYPICAL APPLICATIONS

#### **Photodiode Preamp with AC Coupling Loop**



#### 1MHz, 4th Order Butterworth Filter



## **RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS
LT1361/LT1362 Dual and Quad 50MHz, 800V/μs Op Amps Dual and Quad Versions of LT1360		Dual and Quad Versions of LT1360
LT1363	70MHz, 1000V/μs Op Amp	Faster Version of LT1360, $V_{OS} = 1.5$ mV, $I_S = 6.3$ mA
LT1357	25MHz, 600V/μs Op Amp	Lower Power Version of LT1360, V <sub>OS</sub> = 0.6mV, I <sub>S</sub> = 2mA
LT1812	100MHz, 750V/μs Op Amp	Low Voltage, Low Power LT1360, V <sub>OS</sub> = 1mV, I <sub>S</sub> = 3mA

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