

Electrical Characteristics (@ 25 °C)

Features

- Non-contacting magnetic technology
- Highly resistant to vibration/shock
- Highly resistant to fluid/dust ingress
- Programmable at factory for zero position
- Robust design for industrial applications
- Highly repeatable

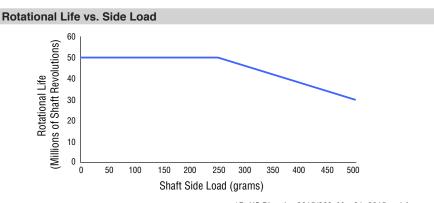
■ RoHS compliant*

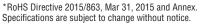
AMS22B Non-Contacting Analog Rotary Position Sensor

Electrical Characteristics ¹ (@ :	25 °C)
VDD Supply Voltage	5 V ± 10 %
Supply Current	20 mA max.
Output Signal (Single)	Analog
Independent Linearity	±0.5 % (±0.3 % available on request)
Hysteresis	0.2 % VDD max.
Effective Electrical Angle 2	340 °
	1 to 99 % VDD ±1 %
	12 bit @ 360 °
0	+20 VDC
Reverse Voltage Protection	10 VDC
Environmental Characteristics	3
Operating Temperature	40 ° to +125 °C
Moisture Resistance	MIL-STD-202, Method 106
	500 MΩ min.
	50 million
	15 G
	50 G
	IP50
ESD Hating	2 kV max.
Mechanical Characteristics (@	25 °C)
	Continuous (340 ° +4/-0 stops available)
	500 RPM max.
Torque	
	1.06 N-cm. (1.5 oz-in.) max.
	Brass / 100 % matte tin over Ni Strike (e3)
	Bronze sleeve
Soldering Condition	00.50 (0.04 (0.50));
Manual Soldering	
Maya Caldarina	rosin cored wire; 370 °C (700 °F) max. for 3 seconds

¹At room ambient: +25 °C nominal and 50 % relative humidity nominal, except as noted.

Wash processes

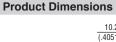




260 °C (500 °F) max. for 5 seconds

.....Not recommended

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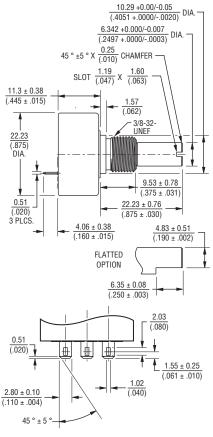
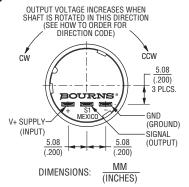
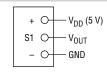


Figure 1









 $^{^{\}rm 2}$ Other Effective Electrical Angles available. See How to Order selection guide.

Users should verify actual device performance in their specific applications.

Applications

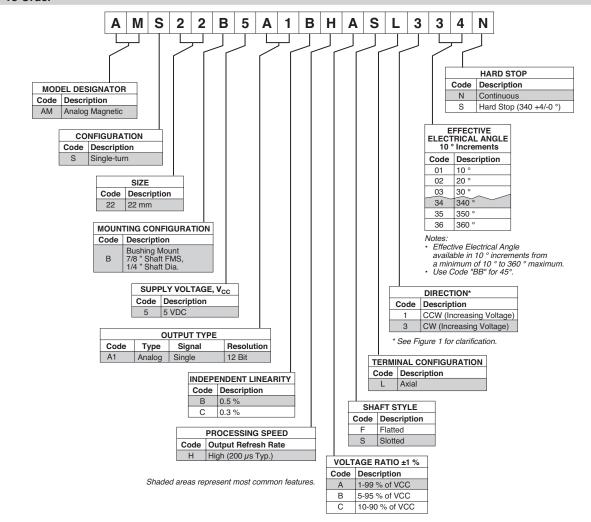
- Patient platform positioning feedback
- Pneumatic control valve position feedback
- Draw wire position sensors
- Remote communications antenna positioning
- Actuator motor position feedback
- Automated manufacturing robotics

- Tilt control and tilt positioning feedback
- Foot pedal, steering, lift-and-shuttle and suspension systems

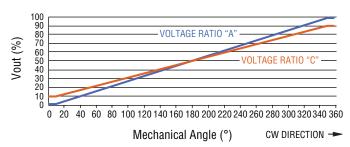
AMS22B Non-Contacting Analog Rotary Position Sensor

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How To Order



Standard Output: 1-Turn CW Increasing (Code 334 Shown)



Resolution

EEA	Resolution		EEA	Resolution		EEA	Ι
10	114		130	1479		260	L
20	228		140	1593		270	
30	341		150	1707		280	
40	455		160	1820		290	L
45	512		170	1934		300	
50	569		180	2048		310	L
60	683		190	2162		320	L
70	796		200	2276		330	
80	910		210	2389		340	
90	1024		220	2503		350	I
100	1138		230	2617		360	
110	1252		240	2731			
120	1365		250	2844			

EEA	Resolution
260	2958
270	3072
280	3186
290	3300
300	3413
310	3527
320	3641
330	3755
340	3868
350	3982
360	4096

REV. 06/20

Specifications are subject to change without notice.

Users should verify actual device performance in their specific applications.

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