

gen4 Primary Displays for Raspberry Pi

# DATASHEET

DOCUMENT DATE: 1<sup>st</sup> July 2021  
DOCUMENT REVISION: 1.5



gen4-4DPi-43T (4.3 " Resistive Touch)  
gen4-4DPi-50T (5.0 " Resistive Touch)  
gen4-4DPi-70T (7.0 " Resistive Touch)  
gen4-4DPi-43CT-CLB (4.3 " Resistive Touch)  
gen4-4DPi-50CT-CLB (5.0 " Resistive Touch)  
gen4-4DPi-70CT-CLB (7.0 " Resistive Touch)

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Please refer to the 4D Systems website for the latest  
Revision of this document

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## 1. Description

The gen4-4DPi range are Primary Display's for the Raspberry Pi\* A+, B+, Pi2, Pi3, Pi3 B+, Pi4, Pi Zero and Pi Zero W, which display the primary output of the Raspberry Pi, like what is normally sent to the HDMI or Composite output. It features an integrated Resistive Touch panel or Capacitive Touch panel, enabling the gen4-4DPi to function with the Raspberry Pi without the need for a mouse.

Communication between the gen4-4DPi and the Raspberry Pi is interfaced with a high speed 48 MHz SPI connection, which utilises an on-board processor for direct command interpretation and SPI communication compression, and features a customised DMA enabled kernel. This combination allows this display to output high frame rate compared to other SPI display solutions, when displaying a typical image/video, and can achieve higher depending on if the image can be compressed.

The gen4-4DPi is designed to work with the Raspbian Operating System running on the Raspberry Pi, as that is the official Raspberry Pi operating system. It is also compatible with Pixel and Scratch.

Please note that the display resolution of the 4.3" is 480x272 pixels, while the 5.0 and the 7.0" are 800x480 pixels, and thus may not display all menus in the Raspbian Desktop fully, without some downscaling.

The gen4-4DPi range connect to the Raspberry Pi's 40 pin header using the gen4-4DPi Adaptor, which then connects to the gen4-4DPi display module using a 30-way FFC Cable.

**Note\*:** Raspberry Pi is a trademark of the Raspberry Pi Foundation, and all references to the words 'Raspberry Pi' or the use of its logo/marks are strictly in reference to the Raspberry Pi product, and how *this* product is compatible with but is not associated with the Raspberry Pi Foundation in any way.

## 2. Features

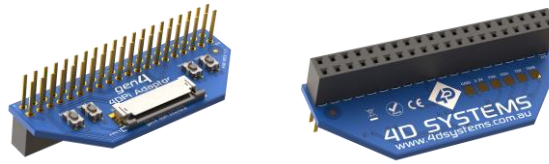
- Universal Primary Display for the Raspberry Pi.
- Compatible with Raspberry Pi A+, B+, Pi2, Pi3, Pi3 B+, Pi4, Pi Zero and Pi Zero W.
- 480x272 Resolution (4.3")
- 800x480 Resolution (5.0" & 7.0")
- TFT Screen with integrated 4-wire Resistive Touch Panel (T), or Capacitive Touch Panel (CT) with Cover Lens Bezel (CLB).
- Display GUI output / primary output, just like a monitor connected to the Raspberry Pi
- High Speed 48MHz SPI connection to the Raspberry Pi, featuring SPI compression technology.
- Typical frame rate of 20 Frames per second (FPS) – 4.3", or 7 Frames per second (5" & 7"), higher if image can be compressed further by the kernel. Lower if no compression is possible.
- Powered directly off the Raspberry Pi, no external power supply is required.
- On board EEPROM for board identification, following the HAT standard.
- 4x 4.0mm Mounting holes on Non-Touch and Resistive Touch modules, or via adhesive for Capacitive Touch model.
- RoHS and CE Compliant – note CE EMC has not been conducted on these modules.



Resistive Touch Display configuration shown.



### 3. Pin Configuration and Summary



H1 Pinout (Raspberry Pi Connector on gen4-4DPI-Adaptor) – Female Connector			
Pin	Symbol	I/O	Description
1	+5V	P	+5V Supply Pin, connected to the main 5V supply of the Raspberry Pi.
2	+3.3V	P	+3.3V Supply Pin, connected to the main 3.3V supply of the Raspberry Pi.
3	+5V	P	+5V Supply Pin, connected to the main 5V supply of the Raspberry Pi.
4	SDA1	I/O	I2C SDA1
5	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi.
6	SCL1	O	I2C SCL1
7	GPIO14	I/O	GPIO on the Raspberry Pi - <b>unused</b>
8	GPIO4	I/O	GPIO on the Raspberry Pi - <b>unused</b>
9	GPIO15	I/O	GPIO on the Raspberry Pi - <b>unused</b>
10	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi.
11	GPIO18	I/O	GPIO on the Raspberry Pi – Can be used for PWM Backlight, else <b>unused</b>
12	PENIRQ	I	Interrupt for the touchscreen controller
13	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
14	KEYIRQ	I	Interrupt for the push buttons
15	GPIO23	I/O	GPIO on the Raspberry Pi - <b>unused</b>
16	GPIO22	I/O	GPIO on the Raspberry Pi - <b>unused</b>
17	GPIO24	I/O	GPIO on the Raspberry Pi - <b>unused</b>
18	+3.3V	P	+3.3V Supply Pin, connected to the main 3.3V supply of the Raspberry Pi
19	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
20	MOSI	O	SPI MOSI Pin
21	GPIO25	I/O	GPIO on the Raspberry Pi - <b>unused</b>
22	MISO	I	SPI MISO Pin
23	SPI-CS0	O	SPI Chip Select 0 – Used for Xilinx Processor for Display, to Raspberry Pi
24	SCK	O	SPI SCK Clock Pin
25	SPI-CS1	O	SPI Chip Select 1 – <b>unused</b>
26	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
27	ID-SC	O	I2C ID EEPROM
28	ID-SD	I/O	I2C ID EEPROM
29	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
30	GPIO5	I/O	GPIO on the Raspberry Pi - <b>unused</b>
31	GPIO12	I/O	GPIO on the Raspberry Pi - <b>unused</b>
32	GPIO6	I/O	GPIO on the Raspberry Pi - <b>unused</b>
33	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
34	GPIO13	I/O	GPIO on the Raspberry Pi – <b>unused</b>
35	GPIO16	I/O	GPIO on the Raspberry Pi - <b>unused</b>
36	GPIO19	I/O	GPIO on the Raspberry Pi - <b>unused</b>
37	GPIO20	I/O	GPIO on the Raspberry Pi - <b>unused</b>
38	GPIO26	I/O	GPIO on the Raspberry Pi - <b>unused</b>
39	GPIO21	I/O	GPIO on the Raspberry Pi - <b>unused</b>
40	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi

I = Input, O = Output, P = Power

**Note:** The on-board Xilinx processor of the gen4-4DPi utilises one of the Chip Select (CS) pins on the Raspberry Pi's SPI Bus (SPI-CS0). There is SPI-CS1 still available for use by the User.

**Note:** The on-board Resistive Touch Screen Controller or on-board Capacitive Touch Controller, utilises the I2C bus (SDA1, SCL1) to communicate to the Raspberry Pi. The I2C bus is capable of communicating with other devices also, so isn't restricted to only the 4DPi's touch controller.

gen4-4DPi 30-way FFC Interface, between gen4-4DPi-Adaptor and gen4-4DPi Display			
Pin	Symbol	I/O	Description
1	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
2	SDA1	I/O	I2C SDA1
3	SCL1	O	I2C SCL1
4	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
5	MOSI	O	SPI MOSI Pin
6	SCK	O	SPI SCK Clock Pin
7	MISO	I	SPI MISO Pin
8	SPI-CS0	O	SPI Chip Select 0 – Used for Xilinx Processor for Display, to Raspberry Pi
9	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
10	ID-SC	O	I2C ID EEPROM
11	ID-SD	I/O	I2C ID EEPROM
12	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
13	PENIRQ	I	Interrupt for the touchscreen controller
14	KEYIRQ	I	Interrupt for the push buttons
15	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
16	SW5	I	Button 5 (Not present on Adaptor), connected to Xilinx Processor on display
17	SW4	I	Button 4 on gen4-4DPi-Adaptor, connected to Xilinx Processor on display
18	SW3	I	Button 3 on gen4-4DPi-Adaptor, connected to Xilinx Processor on display
19	SW2	I	Button 2 on gen4-4DPi-Adaptor, connected to Xilinx Processor on display
20	SW1	I	Button 1 on gen4-4DPi-Adaptor, connected to Xilinx Processor on display
21	JTAG-TMS	-	Special Pins for Factory Programming of Xilinx Processor only – <b>Do Not Connect</b>
22	JTAG-TDI	-	Special Pins for Factory Programming of Xilinx Processor only – <b>Do Not Connect</b>
23	JTAG-TDO	-	Special Pins for Factory Programming of Xilinx Processor only – <b>Do Not Connect</b>
24	JTAG-TCK	-	Special Pins for Factory Programming of Xilinx Processor only – <b>Do Not Connect</b>
25	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi
26	+5V	P	+5V Supply Pin, connected to the main 5V supply of the Raspberry Pi
27	+5V	P	+5V Supply Pin, connected to the main 5V supply of the Raspberry Pi
28	+3.3V	P	+3.3V Supply Pin, connected to the main 3.3V supply of the Raspberry Pi
29	+3.3V	P	+3.3V Supply Pin, connected to the main 3.3V supply of the Raspberry Pi
30	GND	P	Ground Pin, connected to the main system Ground of the Raspberry Pi

I = Input, O = Output, P = Power

## 4. Connecting the Display to the Pi

### 4.1. Hardware Connection

The gen4-4DPi is easily connected to a Raspberry Pi. Ensure the Raspberry Pi is powered off when connecting the gen4-4DPi display or adaptor.

Simply align the Female 40-way header on the gen4-4DPi-Adaptor with the Raspberry Pi's Male 40-way header and connecting them together – ensuring the alignment is correct and all pins are seated fully and correctly. The gen4-4DPi-Adaptor should be overhanging inward of the Raspberry Pi.

Next simply connect the 30-way FFC cable between the FFC Connector of the gen4-4DPi and the gen4-4DPi-Adaptor, ensuring the copper pins are facing upward in the connector.

Please note that hardware connection to the Pi is not recommended until the Pi has been set up. Please see instructions below.

### 4.2. Software Download/Installation

4D Systems has prepared a custom DMA enabled kernel for use with the Raspbian Operating System, which is available for download as a single Package. This can be installed over your existing Raspbian installation, or it can be applied over a fresh image. It is recommended to apply over a fresh image.

If you are starting from a fresh image, start from Step 1, else skip to step 3 if you already have a Raspbian Image and which to apply this kernel to that. Please note, it is impossible for us to know what you have done to your Raspbian image, if you are not installing from a fresh image – so if you encounter issues, please try and use a fresh image to determine, modifications are conflicting with our kernel release. If you are running a Raspbian version with a Kernel version later than our Kernel Pack, you are very likely to encounter problems. Please contact support if you have problems.

- 1) Download the Raspbian Image from the Raspberry Pi website that corresponds to the Kernel Pack from our repository. You cannot use the latest Raspbian image if we do not have a Kernel Pack to match that kernel release:

[http://downloads.raspberrypi.org/raspbian\\_latest](http://downloads.raspberrypi.org/raspbian_latest)

**Note:** If you encounter any issues with the latest version, it is advisable to use the Raspbian OS release with matching kernel version as one of the latest 4DPi packages that you plan to use.

This is the current latest release which matches our Kernel Pack. Please utilize this image unless you are compiling your own Kernel or know what you are doing:

[https://downloads.raspberrypi.org/raspbian\\_armhf/images/raspbian\\_armhf-2020-08-24/](https://downloads.raspberrypi.org/raspbian_armhf/images/raspbian_armhf-2020-08-24/)

This image has Kernel **5.4.51-v7+**, and therefore is compatible with our Kernel Pack, **5.4.6.8** – which is used further in these instructions.

- 2) Load the Raspberry Pi image onto a SD card, using the instructions provided on the Raspberry Pi website for Linux, Mac or PC:

<http://www.raspberrypi.org/documentation/installation/installing-images/README.md>

- 3) Insert the SD card into the Raspberry Pi. Do not connect the gen4-4DPi yet. You will need an external monitor / keyboard / network connection, else simply a network connection to the Pi and the rest can be done over an SSH connection. Start up the Pi with at minimum an Ethernet connection connected.
- 4) Either log into the Raspberry Pi from your keyboard/monitor using the standard 'pi' and 'raspberrypi' credentials, else SSH into your raspberrypi and log in via your SSH session.

SSH typically has to be enabled manually from raspi-config, or it can be enabled by putting a blank file named 'ssh' (without the quotes, no extension) onto the boot drive of the microSD card before you take it out of your PC after flashing the image to the card, which will enable it without needing raspi-config.

If logging in with Keyboard/Mouse/Monitor directly to the Pi, you can follow the Wizard the pops up on the desktop if you wish and set up your Keyboard/Location/Wifi details (Pi3/Pi4 etc). **However do NOT do the system update.** Please skip the update. Reboot the pi if prompted.

- 5) Typically, on modern versions of the Pi OS, this step is not required or is done automatically. However it is here for reference.



Expand the file system on downloaded image using raspi-config (submenu Expand Filesystem). After exiting raspi-config a reboot is needed.

```
sudo raspi-config
```

```
sudo reboot
```

- 6) Once rebooted, do **NOT** do an apt-get upgrade, as this will almost certainly update the OS kernel version, which will cause an incompatibility with the kernel from our kernel pack. The Kernel pack must be applied to a kernel very very close if not identical to the kernel your OS is running, or there will be issues.

**Warning:** An upgrade should only be done after making sure that the latest kernel is supported by the latest kernel pack from 4D. Otherwise, installing the 4D kernel pack will downgrade the kernel and problems are almost certain to occur.

- 7) Log into your Raspberry Pi again, you will need to download and install the kernel which supports the gen4-4DPi. The following step requires sudo 'root' access.
- 8) To download and install files, enter the following commands in terminal/shell /SSH to download the kernel from the 4D Systems Server:

```
wget https://4dsystems.com.au/media/downloads/4DPi/All/gen4-hats_5-4-68.tar.gz
```

Then extract the kernel pack:

```
sudo tar --no-same-owner -xzvf gen4-hats_5-4-68.tar.gz -C /
```

The package selects the kernel required for Pi1, Pi2, Pi3 or Pi4 automatically. If you want to check for the kernel packages released by 4D systems, proceed to [Section: Latest Kernel Versions](#)

- 9) On newer Raspbian images, by default the system boots to Desktop GUI.

Booting to command line can be selected using the raspi-config tool, submenu Boot Options.

```
sudo raspi-config
```

- 10) Shutdown the Raspberry Pi safely and remove the power after it has completed its shutdown. For shutting down use the following command

```
sudo poweroff
```

or

```
sudo halt
```

Shutdown can take a while, since many files have to be written from cache to SD card.

- 11) Connect the gen4-4DPi to the Raspberry Pi and reapply power. The terminal should begin to show on the gen4-4DPi and will be ready to use once the Raspberry Pi has booted.

### 4.3. Calibrating the Touch Screen

Each gen4-4DPi which is shipped from the 4D Systems factory is slightly different, in the sense that each of the touch screens has a slightly different calibration. In order to get the best from your gen4-4DPi, you will need to calibrate the display, so it is as accurate as possible.

To calibrate the touch screen, the xinput\_calibrator is required, and the following steps should be carried out. Make sure the Desktop is not running before you start, quit desktop if it is and return to the terminal prompt. Please note that only resistive touch display modules could be calibrated.

- 1) Install xinput\_calibrator (if not installed by default) by running this from terminal:

```
sudo apt-get install xinput-calibrator
```

- 2) Install the event device input driver:

```
sudo apt-get install xserver-xorg-input-evdev
```

- 3) Rename 10-evdev.conf file to 45-evdev.conf.

```
sudo mv /usr/share/X11/xorg.conf.d/10-evdev.conf /usr/share/X11/xorg.conf.d/45-evdev.conf
```



- 4) Check if evdev.conf has a higher number than libinput.conf.

```
ls /usr/share/X11/xorg.conf.d/
```

The user should get something like this:

```
10-quirks.conf      40-libinput.conf      45-
evdev.conf  99-fbturbo.conf
```

- 5) Perform a reboot

```
sudo reboot now
```

- 6) Reconnect to SSH and run xinput calibrator.

```
DISPLAY=:0.0 xinput_calibrator
```

Perform the calibration and copy results. The result should be something like this:

```
Section "InputClass"
    Identifier      "calibration"
    MatchProduct    "AR1020 Touchscreen"
    Option "Calibration" "98 4001 175
3840"
    Option "SwapAxes" "0"
EndSection
```

- 7) You may test the changes after xinput calibrator ends. To make the changes permanent, paste the results to  
/etc/X11/xorg.conf.d/99-calibration.conf

```
sudo nano /etc/X11/xorg.conf.d/99-calibratio
n.conf
```

- 8) Save the file and perform a reboot

```
sudo reboot now
```

The Display should now be calibrated.

## 4.4. Change the Display Orientation

To change the display orientation, simply edit the /boot/cmdline.txt file

Add the parameter below after the console parts in the parameter list:

```
4d_hats.rotate = 90
```

And change this to have the value of 0, 90, 180 or 270. It should look something like:

```
console=serial0,115200 console=tty1
4d_hats.rotate=90 root= (etc etc)
```

Save the file and restart your Raspberry Pi.

The touch screen will automatically remap the alignment thanks to the custom kernel.

After changing the Display Orientation, you need to calibrate again the screen.

## 4.5. gen4-4DPi-Adaptor Push Button

The gen4-4DPi-Adaptor features 4 push buttons, which are connected to the Xilinx Processor. These can be used to trigger events on the Raspberry Pi. Please refer to the Appendix for code examples on how to utilize these buttons.

## 4.6. SPI Frequency and Compression

The gen4-4DPi can be adjusted to work with a range of SPI Frequencies and levels of compression, depending on the requirements of the product/project.

Increasing the frequency can result in a higher Frame Rate (FPS), however will use more power and processor time. Increasing the level of the compression can also result in a higher FPS but may cause the display to corrupt. By default, a SPI Frequency of 48Mhz is used, with a Compression level of 7.

The following parameters are the defaults in the /boot/cmdline.txt file and can be edited to adjust the Frequency and Compression level.

```
4d_hats.sclk=48000000
4d_hats.compress=7
```

Setting compress to be 1 will enable the kernel to control the level of compression based on the frequency selected. This however is not guaranteed to have a good result and may require manually setting

the compression level if corruption on the display is experienced.

If corruption or display anomalies occur at any given compression level, try to lower it by 1 value and check if this has improved.

Note, changing the frequency and compression require a restart of the Raspberry Pi.

## 4.7. Backlight Control

The backlight brightness can be controlled from the terminal, or from a bash script. The following command can be used to set the backlight from 0 to 100%.

```
sudo sh -c 'echo 31 > /sys/class/backlight/4d-hats/brightness'
```

The above will set the backlight to 100% (default). Simply change the 'echo 31' to be anything from 0 to 31.

## 4.8. Parameters Listing

The following is a list of all the custom parameters used by the gen4-4DPi.

**rotate:** Screen rotation 0/90/180/270 (int)  
**compress:** SPI compression 0/1/2/3/4/5/6/7 (int)  
**sclk:** SPI clock frequency (long)

Valid SPI Frequency values (4d-hats.sclk):  
 Values can be almost anything. This has been tested up to 64Mhz. Common values would include 64000000 (64MHz), 48000000 (Default), 32000000, 24000000 etc.

Valid Compression values (4d-hats.compress):  
 0 (compression off)  
 1 (compression on, auto set based on sclk value)  
 2 (lowest), 3, 4, 5, 6, 7 (highest compression)

These parameters can be set or read from the /boot/cmdline.txt file, and they can be read from the /sys/module/4d\_hats/parameters/ directory.

For example:

```
cat /sys/module/4d_hats/parameters/rotate
```

Will display the current rotation saved.

## 4.9. HDMI or 4DPi Output

To switch the X Windows output being displayed on 4DPi or HDMI output, X can be launched using either of the following commands:

```
startx -- -layout TFT
```

```
startx -- -layout HDMI
```

Alternatively, these commands do the same thing:

```
FRAMEBUFFER=/dev/fb1 startx
```

```
startx
```

## 4.10. DPI Adjustment

It is possible to change the DPI output of the 4DPi the same way as other LXDE based systems.

login as pi and open terminal

Check the current DPI settings by

```
xrdb -query -all
```

The current dpi is listed next to the **xft.dpi** listing.

To change the DPI, it can be done like this. Edit the following file, and then merge it:

```
nano ~/.Xresources
```

Add this line:  
**xft.dpi:** 75

This will set the DPI to be 75

Save and exit the file.

Merge it so the value gets used, by doing the following:

```
xrdb -merge ~/.Xresources
```

Check again by doing the query

```
xrdb -query -all
```

Reboot the Pi, and your changes should take effect.

Changing the DPI can make the screen blurry, so take care when adjusting these values. If you get to a point where it is unreadable, SSH into your Pi and change the value back to something reasonable.

Ideally DPI is set based on your resolution, however for small resolution displays, it can be desirable to make the DPI smaller so you can fit more on the screen.

## 5. Display Module Part Numbers

The following is a breakdown on the part numbers and what they mean.

### Example:

gen4-4DPi-70CT-CLB

gen4 - gen4 Display Range  
4DPi - Display Family  
70 - Display size (7.0")  
T - Resistive Touch.  
CT - Capacitive Touch  
CLB - Cover Lens Bezel

- For part numbers which do not include T or CT, these are non-touch variants.
- Cover Lens Bezels (CLB) are glass fronts for the display module with overhanging edges, which allow the display module to be mounted directly into a panel using special adhesive on the overhanging glass. These are available for Capacitive Touch only.

## 6. Cover Lens Bezel Mounting

The perimeter of the CLB display modules features double-sided adhesive tape, designed to stick directly onto a panel, enclosure, box etc without the need for any mounting screws or hardware.

The tape used is 3M 9495LE tape, which uses the well-known and strong 3M 300LSE adhesive.

The double-sided adhesive has a thickness of 0.17mm once the backing has been removed.

More information on this adhesive can be found on the 3M website.

<http://multimedia.3m.com/mws/media/7716830/3mtm-double-coated-tapes-9474le-9495le.pdf>

## 7. Standard FFC cable specification

Between the gen4-4DPi-Adaptor and the gen4-4DPi Display Module, the following FFC cable is supplied:

30 Pin Flexible Flat Cable, 150mm Long, 0.5mm (0.02") pitch

Cable Type: AWM 20624 80C 60V VW-1

Heat Resistance 80 Degrees Celsius

Connections on the **opposite side** at each end (Type B)

All FFC connectors on the gen4-4DPi are 'Top Contact' meaning the FFC cable has the metal 'fingers' pointing upward in the connector, blue stiffener on the back of the FFC cable is down on the PCB side.

## 8. Latest Kernel Versions

Here is the list of the kernel patches released by 4D systems.

Latest release:

[gen4-hats\\_5-4-68.tar.gz](http://gen4-hats_5-4-68.tar.gz)

Previous releases:

[gen4-hats\\_4-19-57-v7l+ v1.0.tar.gz](http://gen4-hats_4-19-57-v7l+ v1.0.tar.gz)

[gen4-hats\\_4-14-34 v1.1.tar.gz](http://gen4-hats_4-14-34 v1.1.tar.gz)

[gen4-hats\\_4-9-80 v1.1.tar.gz](http://gen4-hats_4-9-80 v1.1.tar.gz)

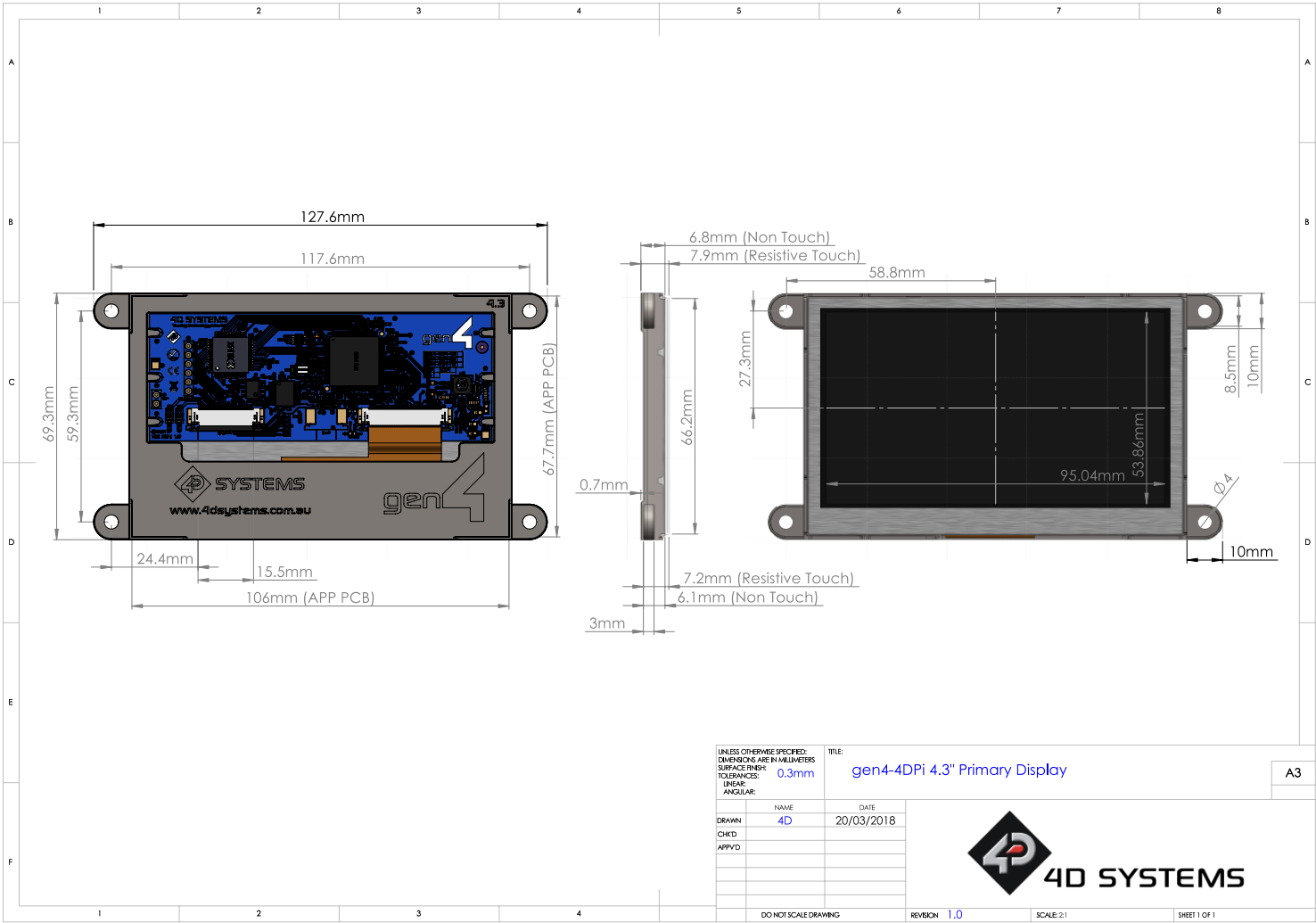
[gen4-hats\\_4-9-59 v1.2.tar.gz](http://gen4-hats_4-9-59 v1.2.tar.gz)

**Note:** (1) It is highly advisable to use a Raspbian OS release with **matching kernel version** as the kernel patches you decide to use. Please refer to section 4.2 point #1 regarding the current recommended OS.

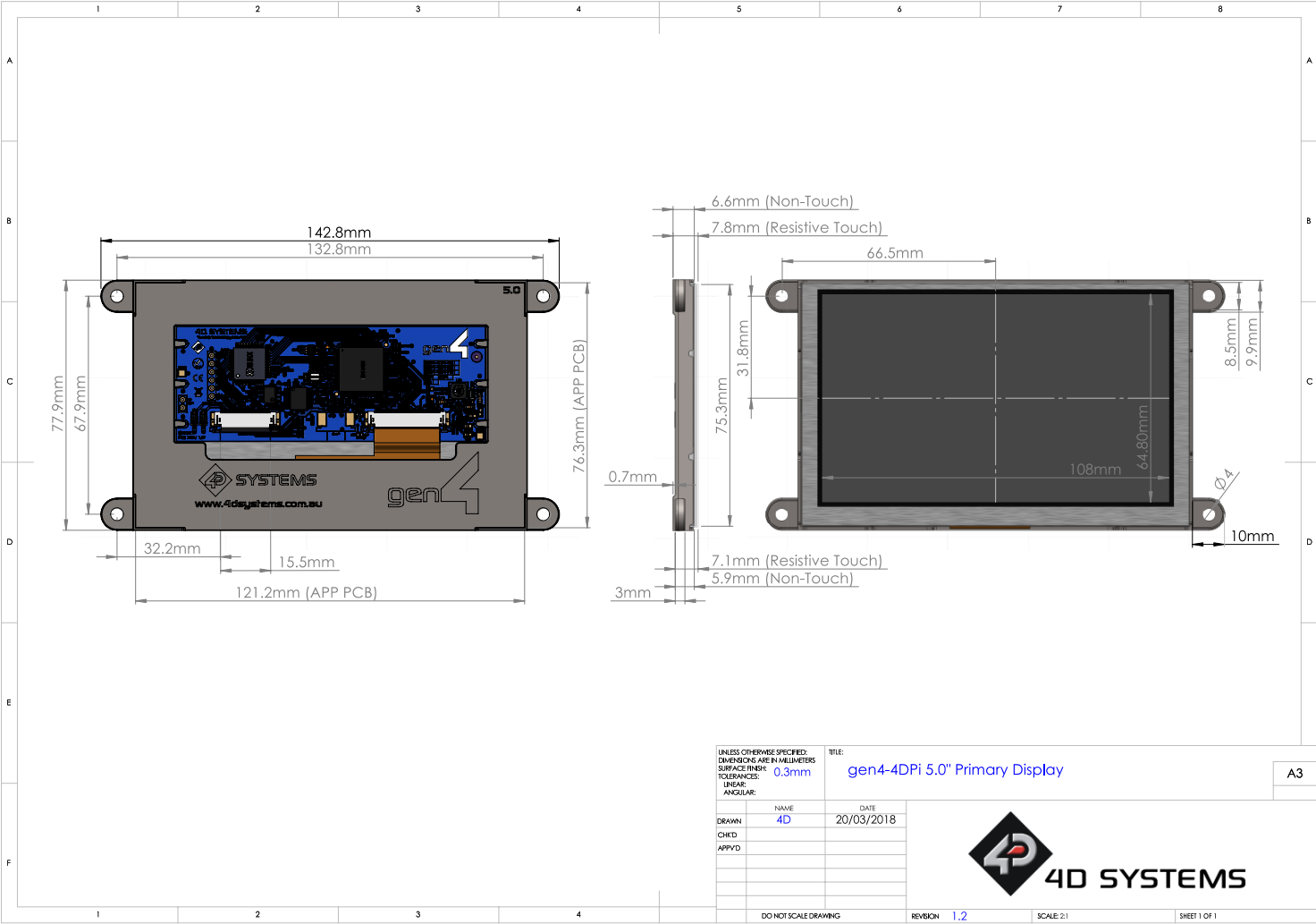
**Note:** (2) Some older kernel releases may be available upon request. Please contact 4D Systems Support Team for more information:

[www.4dsystems.com.au/support](http://www.4dsystems.com.au/support)

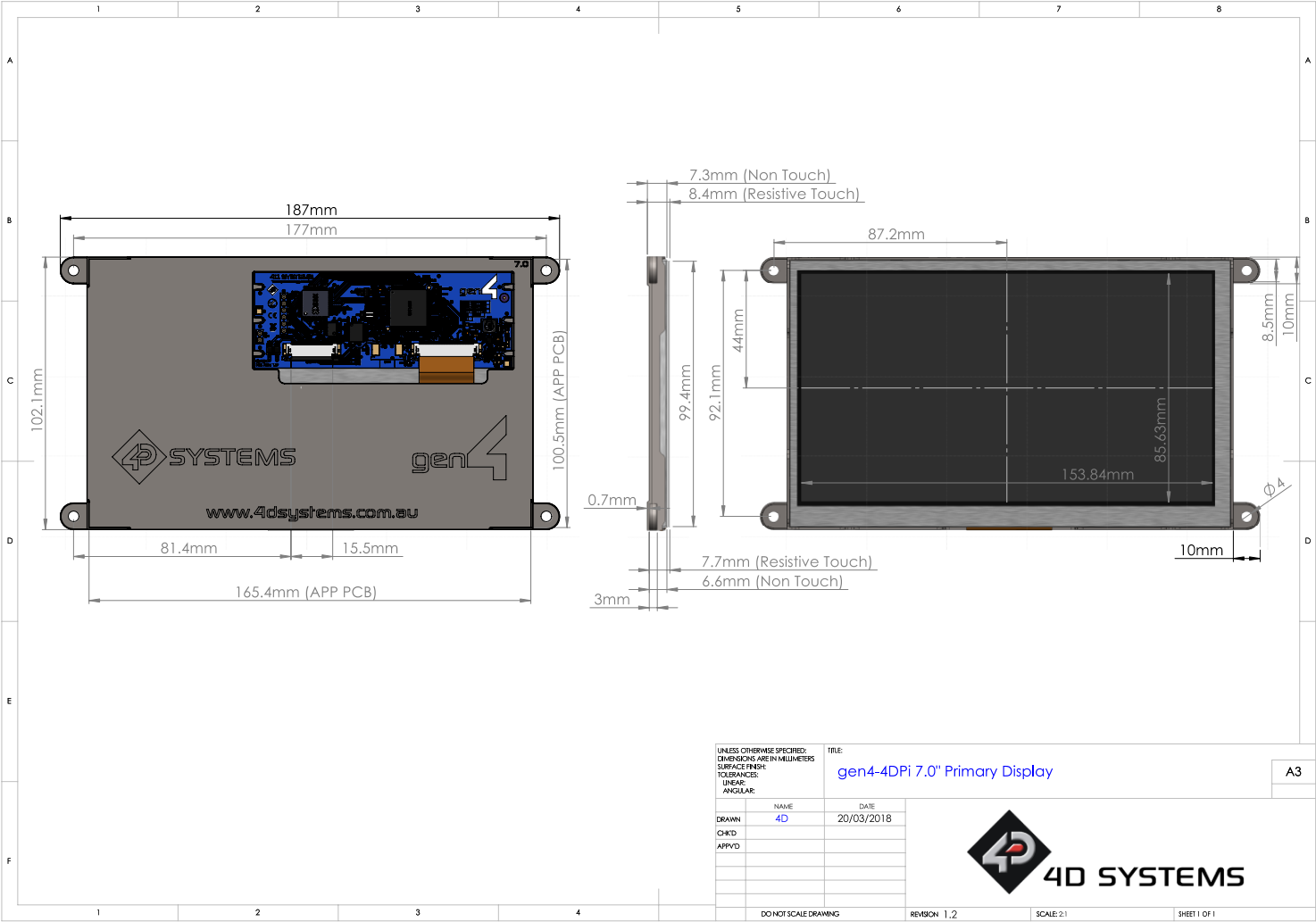
9. Mechanical Details gen4-4DPi-43T



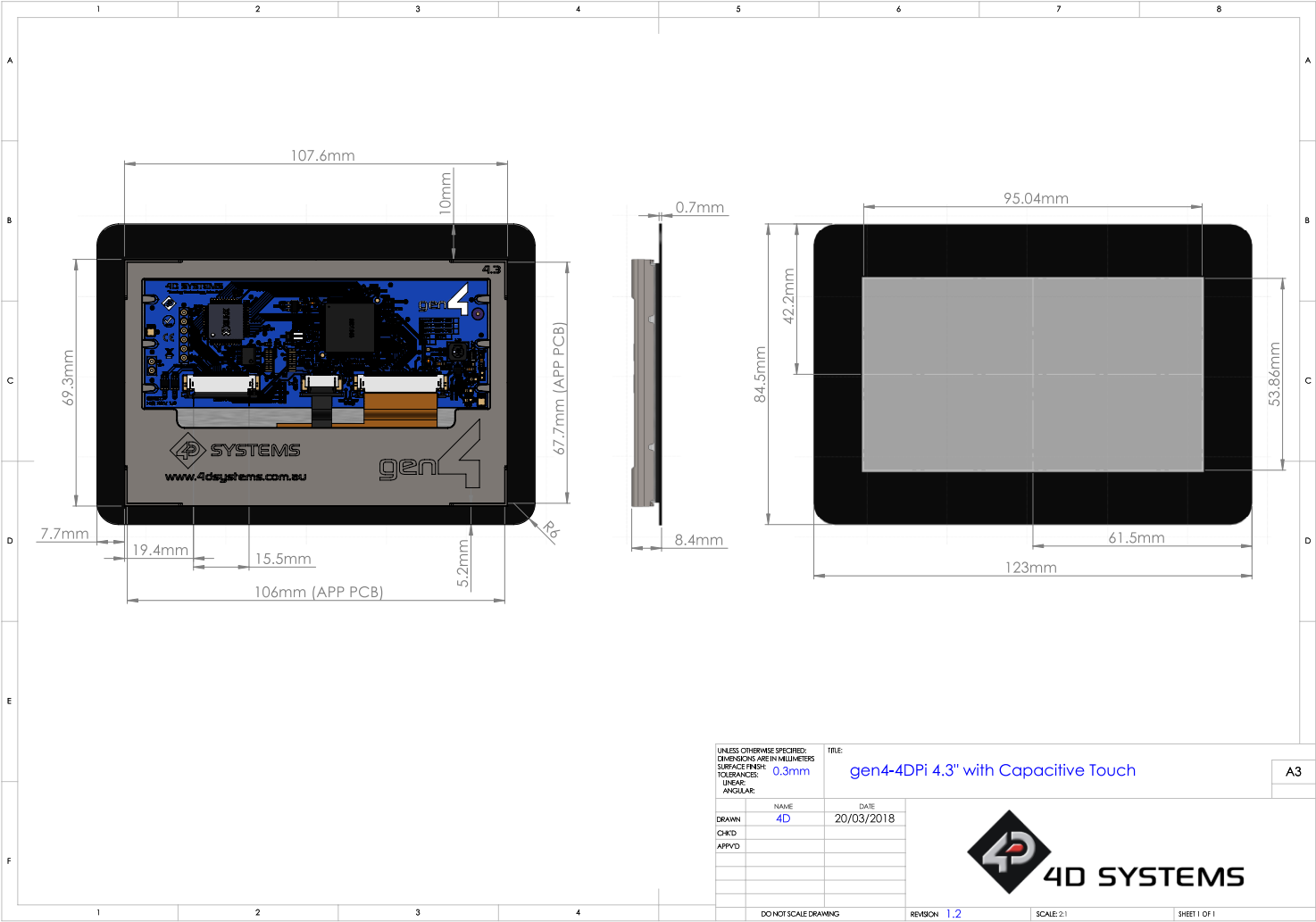
## 10. Mechanical Details gen4-4DPi-50T



11. Mechanical Details gen4-4DPi-70T

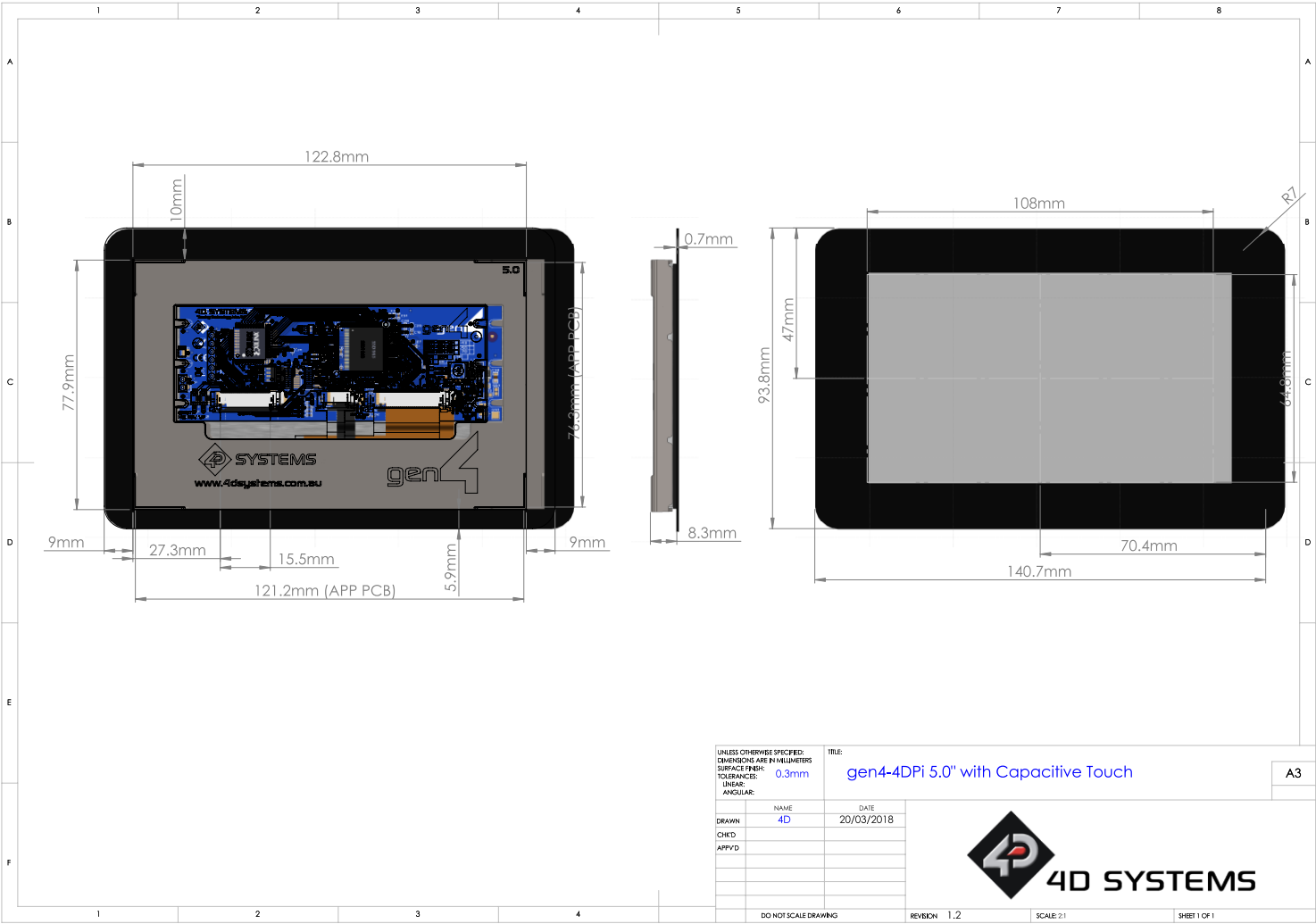


12. Mechanical Details gen4-4DPi-43CT-CLB





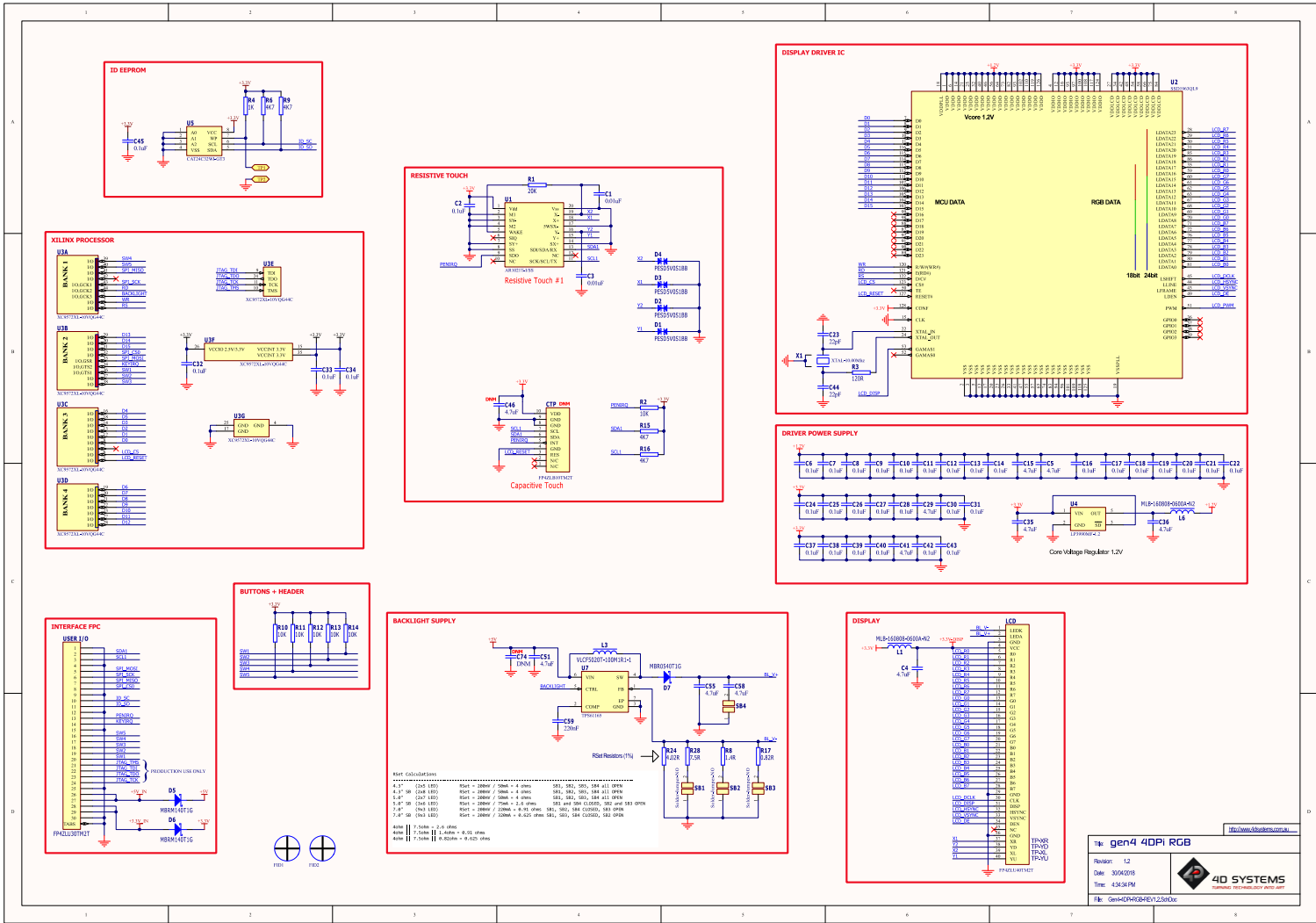
13. Mechanical Details gen4-4DPi-50CT-CLB



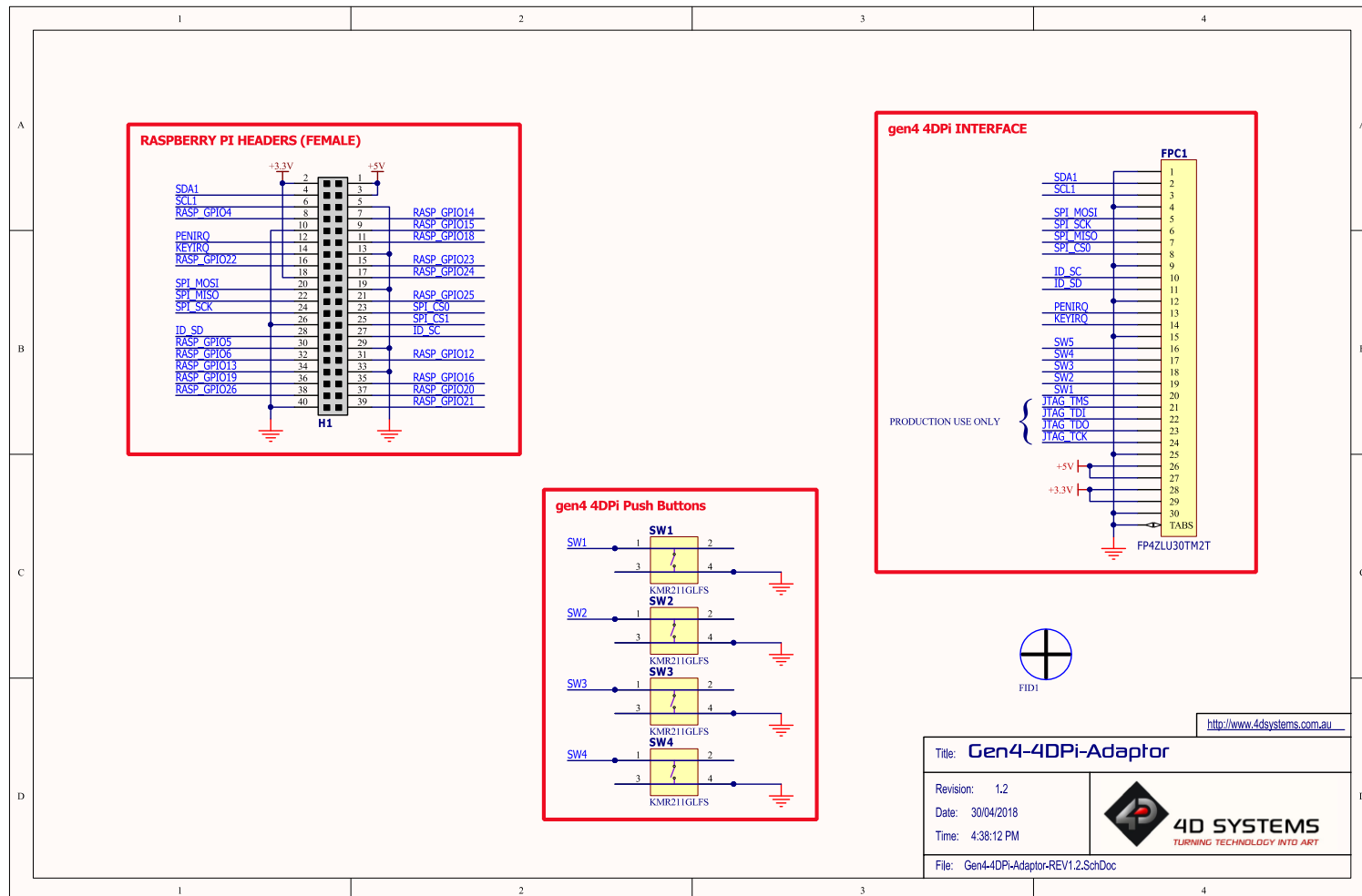
## 14. Mechanical Details gen4-4DPi-70CT-CLB



## 15. Schematic Diagram gen4-4DPi (Display module)



## 16. Schematic Diagram gen4-4DPi-Adaptor (Display Adaptor)



## 17. Specifications

### ABSOLUTE MAXIMUM RATINGS

Operating ambient temperature .....	-20°C to +70°C
Storage temperature .....	-30°C to +80°C

**NOTE:** Stresses above those listed here may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the recommended operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

### RECOMMENDED OPERATING CONDITIONS

Parameter	Conditions	Min	Typ	Max	Units
Supply Voltage (+3.3V)	Stable supply from Raspberry Pi Bus	3.0	3.3	4.0	V
Supply Voltage (+5V)	Stable supply from Raspberry Pi Bus	4.5	5.0	5.5	V

### GLOBAL CHARACTERISTICS BASED ON OPERATING CONDITIONS

Parameter	Conditions	Min	Typ	Max	Units
Supply Current Estimates (Display portion only) (RPI current not included) Idle home screen	gen4-4DPi-43T (Max Brightness)	--	250	--	mA
	gen4-4DPi-43CT-CLB (Max Brightness)	--	270	--	mA
	gen4-4DPi-50T (Max Brightness)	--	360	--	mA
	gen4-4DPi-50CT-CLB (Max Brightness)	--	380	--	mA
	gen4-4DPi-70T (Max Brightness)	--	640	--	mA
	gen4-4DPi-70CT-CLB (Max Brightness)	--	750	--	mA
Display Endurance	Hours of operation, measured to when display is 50% original brightness	30000	--	--	H
Touch Screen Endurance (Resistive Touch)	Number of touches/hits with a 12.5mm tip at a rate of 2x per second with 250gf force	--	1M	--	Touches
	Slide stylus on screen, 100gf force, 60mm/s speed with a 0.8mm polyacetal tip stylus pen	--	100K	--	Slides
Touch Screen Transparency	Resistive Touch	82	--	--	%
	Capacitive Touch	90	--	--	%
Touch Screen Operational Force (Resistive Touch)	Only use Finger or Stylus, do not use anything sharp or metal	20	--	100	Gf
CLB Hardness (Capacitive Touch)	Cover Lens Bezel Glass Hardness	--	6	--	H

LCD DISPLAY INFORMATION (TN DISPLAY)		
Parameter	Conditions	Specification
Display Type	All displays produced before IPS release date in IPS table below, or any modules not specified are therefore TN type displays.	TN - TFT Transmissive LCD
Display Sizes		4.3", 5.0" or 7.0" Diagonal
Display Resolution		480 x 272 (Landscape Viewing) – 4.3" 800 x 480 (Landscape Viewing) – 5" & 7"
Display Brightness	gen4-4DPi-43T (Max Brightness)	400 cd/m2
	gen4-4DPi-43CT-CLB (Max Brightness)	475 cd/m2
	gen4-4DPi-50T (Max Brightness)	400 cd/m2
	gen4-4DPi-50CT-CLB (Max Brightness)	475 cd/m2
	gen4-4DPi-70T (Max Brightness)	400 cd/m2
	gen4-4DPi-70CT-CLB (Max Brightness)	475 cd/m2
Display Contrast Ratio	Typical	500:1
Display Viewing Angles	Above Centre	70 Degrees
	Below Centre	60 Degrees
	Left of Centre	70 Degrees
	Right of Centre	70 Degrees
Display Viewing Direction	TN displays	12 o'clock Display (Optimal viewing is from above when in Landscape/Wide mode)
Display Backlighting	gen4-4DPi-43xx Models	2x5 Parallel LED's
	gen4-4DPi-50xx Models	2x6 Parallel LED's
	gen4-4DPi-70xx Models	9x3 Parallel LED's
Pixel Pitch	4.3"	0.198 x 0.198mm (Square pixels)
	5.0"	0.135 x 0.135mm (Square pixels)
	7.0"	0.1925 x 0.179mm (non-Square pixels)
Pixel Density (Number of pixels in 1 row in 25.4mm)	4.3"	128 DPI/PPI
	5.0"	183 DPI/PPI
	7.0"	132 DPI/PPI (Horizontal) 142 DPI/PPI (Vertical)

LCD DISPLAY INFORMATION (IPS DISPLAY)		
Parameter	Conditions	Specification
Display Type	<b>gen4-4DPi-43T</b> – Modules produced March 2021 onwards. <b>gen4-4DPi-43CT-CLB</b> – Modules produced March 2021 onwards. <b>gen4-4DPi-50T</b> – Modules produced March 2021 onwards. <b>gen4-4DPi-50CT-CLB</b> – Modules produced September 2020 onwards.	<b>IPS</b> - TFT Transmissive LCD
Display Sizes		4.3", 5.0" or 7.0" Diagonal
Display Resolution		480 x 272 (Landscape Viewing) – 4.3" 800 x 480 (Landscape Viewing) – 5" & 7"
Display Brightness	gen4-4DPi-43T (Max Brightness)	510 cd/m2
	gen4-4DPi-43CT-CLB (Max Brightness)	540 cd/m2
	gen4-4DPi-50T (Max Brightness)	510 cd/m2
	gen4-4DPi-50CT-CLB (Max Brightness)	540 cd/m2
Display Contrast Ratio	gen4-4DPi-43xx Models – Typical	800:1
	gen4-4DPi-50xx Models - Typical	1000:1
Display Viewing Angles	Above Centre	80 Degrees
	Below Centre	80 Degrees
	Left of Centre	80 Degrees
	Right of Centre	80 Degrees
Display Viewing Direction	IPS Displays	ALL (Viewing from all directions)
Display Backlighting	gen4-4DPi-43xx Models	2x5 Parallel LED's
	gen4-4DPi-50xx Models	3x6 Parallel LED's
Pixel Pitch	4.3"	0.198 x 0.198mm (Square pixels)
	5.0"	0.135 x 0.135mm (Square pixels)
Pixel Density (Number of pixels in 1 row in 25.4mm)	4.3"	128 DPI/PPI
	5.0"	183 DPI/PPI

PERFORMANCE					
Parameter	Conditions	Min	Typ	Max	Units
Frame Rate (FPS) (4.3" only)	Video Playback, Full Screen, 480x272. A higher FPS can be achieved if display outputting lots of blocks of the same colour. See Section 4.6	--	20	--	FPS
Frame Rate (FPS) (5.0" & 7.0" only)	Video Playback, Full Screen, 800x480. A higher FPS can be achieved if display outputting lots of blocks of the same colour. See Section 4.6	--	7	--	FPS



**ORDERING INFORMATION****Order Code:**

gen4-4DPi-43T

gen4-4DPi-50T

gen4-4DPi-70T

gen4-4DPi-43CT-CLB

gen4-4DPi-50CT-CLB

gen4-4DPi-70CT-CLB

**Packaging:** Module sealed in a 4D Systems Box

## 18. Appendix 1 – Code Examples – Push Buttons

### 18.1. Example for communicating to Push Buttons, for C:

```
// test program to read state of buttons on 4D Systems 4DPi displays

#include <stdio.h>
#include <sys/types.h>
#include <fcntl.h>
#include <unistd.h>
#include <string.h>
#include <sys/ioctl.h>

#define LCD4DPI_GET_KEYS _IOR('K', 1, unsigned char *)

void print_keys(int fd)
{
    unsigned char keys;

    if (ioctl(fd, LCD4DPI_GET_KEYS, &keys) == -1)
    {
        perror("_apps ioctl get");
    }
    else
    {
        printf("Keys : %2x\n", keys);
    }
}

int main(int argc, char *argv[])
{
    char *file_name = "/dev/fb1";
    int fd;

    fd = open(file_name, O_RDWR);
    if (fd == -1)
    {
        perror("_apps open");
        return 2;
    }

    print_keys(fd);
    printf("Ioctl Number: (dec)%d  (hex)%x\n", LCD4DPI_GET_KEYS, LCD4DPI_GET_KEYS);

    close (fd);
    return 0;
}
```

## 18.2. Example for communicating to Push Buttons, for Python:

```
#!/usr/bin/python
import array, fcntl
from time import sleep
# test program to read state of buttons on 4D Systems 4DPi displays

#LCD4DPI_GET_KEYS = -2147202303

_IOC_NRBITS    = 8
_IOC_TYPEBITS  = 8
_IOC_SIZEBITS  = 14
_IOC_DIRBITS   = 2
_IOC_DIRMASK   = (1 << _IOC_DIRBITS) - 1
_IOC_NRMASK    = (1 << _IOC_NRBITS) - 1
_IOC_TYPEMASK  = (1 << _IOC_TYPEBITS) - 1
_IOC_NRSHIFT   = 0
_IOC_TYPESHIFT = _IOC_NRSHIFT+ _IOC_NRBITS
_IOC_SIZESHIFT = _IOC_TYPESHIFT+ _IOC_TYPEBITS
_IOC_DIRSHIFT  = _IOC_SIZESHIFT+ _IOC_SIZEBITS
_IOC_NONE     = 0
_IOC_WRITE    = 1
_IOC_READ     = 2

def _IOC(dir, type, nr, size):
# print 'dirshift {}, typeshift {}, nrshift {}, sizeshift {}'.format(_IOC_DIRSHIFT,
_IOC_TYPESHIFT, _IOC_NRSHIFT, _IOC_SIZESHIFT)
ioc = (dir << _IOC_DIRSHIFT) | (type << _IOC_TYPESHIFT) | (nr << _IOC_NRSHIFT) |
(size << _IOC_SIZESHIFT)
if ioc > 2147483647: ioc -= 4294967296
return ioc
#def _IO(type, nr):
# return _IOC(_IOC_NONE, type, nr, 0)
def _IOR(type,nr,size):
return _IOC(_IOC_READ, type, nr, size)
#def _IOW(type,nr,size):
# return _IOC(_IOC_WRITE, type, nr, sizeof(size))

LCD4DPI_GET_KEYS = _IOR(ord('K'), 1, 4)
buf = array.array('h',[0])

print 'Press Top & Bottom buttons simultaneously to exit'

with open('/dev/fb1', 'rw') as fd:

while True:
    fcntl.ioctl(fd, LCD4DPI_GET_KEYS, buf, 1) # execute ioctl call to read the keys
    keys = buf[0]

    if not keys & 0b00001:
        print "KEY1" ,
    if not keys & 0b00010:
        print "KEY2" ,
    if not keys & 0b00100:
        print "KEY3" ,
    if not keys & 0b01000:
        print "KEY4" ,
    if not keys & 0b10000:
        print "KEY5" ,

    if keys != 0b11111:
        print
    if keys == 0b01110: # exit if top and bottom pressed
        break

    sleep(0.1)
```

### 18.3. Example for Shutdown and Reset buttons, for C:

```
// test program to Shutdown or Restart Pi using buttons on 4D Systems 4DPi displays

#include <stdio.h>
#include <sys/types.h>
#include <fcntl.h>
#include <unistd.h>
#include <string.h>
#include <sys/ioctl.h>

#define LCD4DPI_GET_KEYS _IOR('K', 1, unsigned char *)

int get_keys(int fd, unsigned char *keys)
{
    if (ioctl(fd, LCD4DPI_GET_KEYS, keys) == -1)
    {
        perror("_apps ioctl get");
        return 1;
    }
    *keys &= 0b11111;
    return 0;
}

int main(int argc, char *argv[])
{
    char *file_name = "/dev/fb1";
    int fd;
    unsigned char key_status;

    fd = open(file_name, O_RDWR);
    if (fd == -1)
    {
        perror("_apps open");
        return 2;
    }

    key_status = 0b11111;
    while(key_status & 0b00001) // press key 1 to exit
    {
        if(get_keys(fd, &key_status) != 0)
            break;

        // printf("key_status: %x\n", key_status);

        if(!(key_status & 0b10000))
        {
            system("sudo shutdown -h now");
            break;
        }

        if(!(key_status & 0b01000))
        {
            system("sudo reboot");
            break;
        }

        sleep(0.1);
    }

    close(fd);
    return 0;
}
```

## 18.4. Example for Shutdown and Reset buttons, for Python:

```
#!/usr/bin/python
import array, fcntl, os
from time import sleep
# test program to Shutdown or Restart Pi using buttons on 4D Systems 4DPi displays

#LCD4DPI_GET_KEYS = -2147202303

_IOC_NRBITS    = 8
_IOC_TYPEBITS  = 8
_IOC_SIZEBITS  = 14
_IOC_DIRBITS   = 2

_IOC_DIRMASK   = (1 << _IOC_DIRBITS) - 1
_IOC_NRMASK    = (1 << _IOC_NRBITS) - 1
_IOC_TYPEMASK  = (1 << _IOC_TYPEBITS) - 1

_IOC_NRSHIFT   = 0
_IOC_TYPESHIFT = _IOC_NRSHIFT+_IOC_NRBITS
_IOC_SIZESHIFT = _IOC_TYPESHIFT+_IOC_TYPEBITS
_IOC_DIRSHIFT  = _IOC_SIZESHIFT+_IOC_SIZEBITS

_IOC_NONE = 0
_IOC_WRITE = 1
_IOC_READ = 2

def _IOC(dir, type, nr, size):
    # print 'dirshift {}, typeshift {}, nrshift {}, sizeshift {}'.format(_IOC_DIRSHIFT,
    # _IOC_TYPESHIFT, _IOC_NRSHIFT, _IOC_SIZESHIFT)
    ioc = (dir << _IOC_DIRSHIFT) | (type << _IOC_TYPESHIFT) | (nr << _IOC_NRSHIFT) |
    (size << _IOC_SIZESHIFT)
    if ioc > 2147483647: ioc -= 4294967296
    return ioc
#def _IO(type, nr):
#    return _IOC(_IOC_NONE, type, nr, 0)
def _IOR(type,nr,size):
    return _IOC(_IOC_READ, type, nr, size)
#def _IOW(type,nr,size):
#    return _IOC(_IOC_WRITE, type, nr, sizeof(size))

LCD4DPI_GET_KEYS = _IOR(ord('K'), 1, 4)
#print 'ssd {} {:12} {:0>8x} {:0>32b}'.format(ssd1289, hex(ssd1289), ssd1289, ssd1289)
buf = array.array('h',[0])

with open('/dev/fb1', 'rw') as fd:

    while True:
        fcntl.ioctl(fd, LCD4DPI_GET_KEYS, buf, 1) # execute ioctl call to read the keys
        keys = buf[0]

        if not keys & 0b00001:
            break

        if not keys & 0b10000:
            os.system("sudo shutdown -h now")
            break

        if not keys & 0b01000:
            os.system("sudo reboot")
            break;

        sleep(0.1)
```

## 19. Hardware Revision History

PCB Revision Number	Date	Description
1.2	30/04/2018	Initial Public Release Version
	Sep 2020	5.0" CTP-CLB Displays started being produced with IPS displays rather than TN displays. Positive change, wider viewing angles, brighter display.
	March 2021	4.3" RTP and CTP-CLB Displays, and 5" RTP Displays started being produced with IPS displays rather than TN displays. Positive change, wider viewing angles, brighter display.

## 20. Document Revision History

Revision Number	Date (dd/mm/yyyy)	Description
1.0	06/05/2018	Initial Public Release Version
1.1	28/03/2019	Cosmetic Changes to gen4 Primary Displays for Raspberry Pi
1.2	02/08/2019	Cosmetic Changes to gen4 Primary Displays for Raspberry Pi and addition of Section – Latest Kernel Versions
1.3	14/04/2020	Cosmetic Changes to gen4 Primary Displays for Raspberry Pi and addition of Section – Latest Kernel Versions
1.4	27/08/2020	Added notes regarding using matching kernel versions
1.5	22/06/2021	Added more information regarding Kernel versions, updated commands which have changed due to OS changes, improved wording in some sections, adding missing IPS display information.



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