

# ACT4523A

Rev 0, 25-Jul-13

## Wide-Input Sensorless CC/CV Step-Down DC/DC Converter

#### **FEATURES**

- 40V Input Voltage Surge
- 36V Steady State Operation
- Up to 3.5A Output Current
- Output Voltage up to 12V
- 250kHz Switching Frequency
- 91% Efficiency (Vout = 5V@3.5A at Vin = 12V)
- Patented ActiveCC Sensorless Constant Current Control
  - Integrated Current Control Improves
     Efficiency, Lowers Cost, and Reduces
     Component Count
- Resistor Programmable
  - Current Limit from 1.5A to 4.0A
  - Patented Cable Compensation from 0 to 0.25Ω
- ±6.5% CC Accuracy
  - Compensation of Input /Output Voltage Change
  - Temperature Compensation
  - Independent of inductance and Inductor DCR
- 2% Feedback Voltage Accuracy
- Advanced Feature Set
  - Integrated Soft Start
  - Thermal Shutdown
  - Secondary Cycle-by-Cycle Current Limit
  - Protection Against Shorted ISET Pin
- SOP-8EP Package

## **APPLICATIONS**

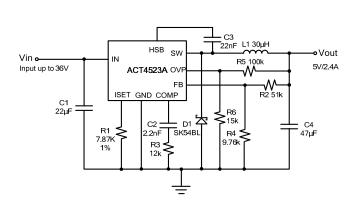
- · Car Charger/ Adaptor
- Rechargeable Portable Devices
- General-Purpose CC/CV Supply

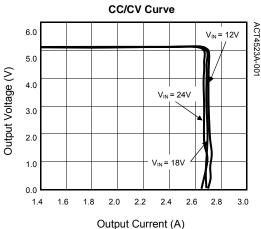
#### GENERAL DESCRIPTION

ACT4523A is a wide input voltage, high efficiency ActiveCC step-down DC/DC converter that operates in either CV (Constant Output Voltage) mode or CC (Constant Output Current) mode. ACT4523A provides up to 3.5A output current at 250kHz switching frequency.

Active CC is a patented control scheme to achieve highest accuracy with sensorless constant current control. ActiveCC eliminates the expensive, high accuracy current sense resistor, making it ideal for battery charging applications and adaptors with accurate current limit. The ACT4523A achieves higher efficiency than traditional constant current switching regulators by eliminating its associated power loss on the sensing resistor. ACT4523A provides OVP pin for output over voltage protection.

Protection features include cycle-by-cycle current limit, thermal shutdown, and frequency foldback at short circuit. The devices are available in a SOP-8EP package and require very few external devices for operation.



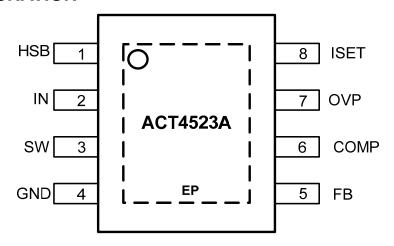




## **ORDERING INFORMATION**

PART NUMBER	OPERATION TEMPERATURE RANGE	PACKAGE	PINS	NS PACKING	
ACT4523AYH-T	-40°C to 85°C	SOP-8EP	8	TAPE & REEL	

## **PIN CONFIGURATION**



**SOP-8EP** 

## **PIN DESCRIPTIONS**

PIN	NAME	DESCRIPTION	
1	HSB	High Side Bias Pin. This provides power to the internal high-side MOSFET gate driver. Connect a 22nF capacitor from HSB pin to SW pin.	
2	Power Supply Input. Bypass this pin with a 10μF ceramic capacitor to GND, place close to the IC as possible.		
3	SW	Power Switching Output to External Inductor.	
4	GND	Ground. Connect this pin to a large PCB copper area for best heat dissipation. Return FB, COMP, and ISET to this GND, and connect this GND to power GND at a single point for best noise immunity.	
		Feedback Input. The voltage at this pin is regulated to 0.808V. Connect to the resistor divider between output and GND to set the output voltage.	
6 COMP Error Amplifier Output. This pin is used to compensate the co		Error Amplifier Output. This pin is used to compensate the converter.	
7	OVP	OVP input. If the voltage at this pin exceeds 0.8V, the IC shuts down high-side switch.	
		Output Current Setting Pin. Connect a resistor from ISET to GND to program the output current.	
	Exposed Pad	Heat Dissipation Pad. Connect this exposed pad to large ground copper area with copper and vias.	



# **ABSOLUTE MAXIMUM RATINGS®**

PARAMETER	VALUE	UNIT
IN to GND	-0.3 to 40	V
SW to GND	-1 to V <sub>IN</sub> + 1	V
HSB to GND	$V_{SW}$ - 0.3 to $V_{SW}$ + 7	V
FB, ISET, COMP to GND	-0.3 to + 6	V
Junction to Ambient Thermal Resistance	46	°C/W
Operating Junction Temperature	-40 to 150	°C
Storage Junction Temperature	-55 to 150	°C
Lead Temperature (Soldering 10 sec.)	300	°C

①: Do not exceed these limits to prevent damage to the device. Exposure to absolute maximum rating conditions for long periods may affect device reliability.



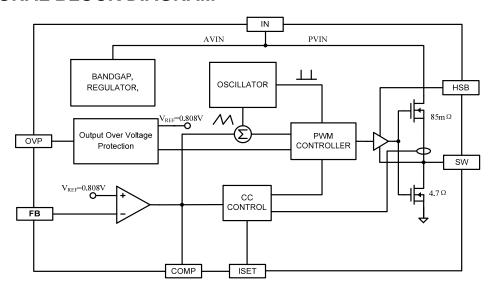
## **ELECTRICAL CHARACTERISTICS**

( $V_{IN}$  = 12V,  $T_A$  = 25°C, unless otherwise specified.)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage		10		36	V
Input Voltage Surge				40	V
V <sub>IN</sub> UVLO Turn-On Voltage	Input Voltage Rising	9.0	9.4	9.7	V
V <sub>IN</sub> UVLO Hysteresis	Input Voltage Falling		1.1		V
Standby Supply Current	V <sub>FB</sub> = 1V		0.9	1.4	mA
Feedback Voltage		792	808	824	mV
Internal Soft-Start Time			400		μs
Error Amplifier Transconductance	$V_{FB} = V_{COMP} = 0.8V,$ $\Delta I_{COMP} = \pm 10\mu A$		650		μΑ/V
Error Amplifier DC Gain			4000		V/V
Switching Frequency	V <sub>FB</sub> = 0.808V		250		kHz
Foldback Switching Frequency	V <sub>FB</sub> = 0V		36		kHz
Maximum Duty Cycle			85		%
Minimum On-Time			190		ns
COMP to Current Limit Transconductance	V <sub>COMP</sub> = 1.2V		3.9		A/V
Secondary Cycle-by-Cycle Current Limit	Duty = 0.5		5.2		Α
Slope Compensation	Duty = D <sub>MAX</sub>		1.4		Α
ISET Voltage			1.0		V
ISET to IOUT DC Room Temp Current Gain	IOUT / ISET, $R_{ISET} = 7.87 k\Omega$		20000		A/A
CC Controller DC Accuracy	$R_{ISET} = 7.87 k\Omega, V_{OUT} = 4.0 V$		2650		mA
OVP pin Voltage	OVP Pin Rising		8.0		V
High-Side Switch ON-Resistance			85		mΩ
SW Off Leakage Current	$V_{in} = V_{SW} = 0V$		1	10	μΑ
Thermal Shutdown Temperature	Temperature Rising		155		°C
Thermal Shutdown Temperature Hysteresis	Temperature Falling		25		°C



#### **FUNCTIONAL BLOCK DIAGRAM**



#### FUNCTIONAL DESCRIPTION

#### CV/CC Loop Regulation

As seen in *Functional Block Diagram*, the ACT4523A is a peak current mode pulse width modulation (PWM) converter with CC and CV control. The converter operates as follows:

A switching cycle starts when the rising edge of the Oscillator clock output causes the High-Side Power Switch to turn on and the Low-Side Power Switch to turn off. With the SW side of the inductor now connected to IN, the inductor current ramps up to store energy in the magnetic field. The inductor current level is measured by the Current Sense Amplifier and added to the Oscillator ramp signal. If the resulting summation is higher than the COMP voltage, the output of the PWM Comparator goes high. When this happens or when Oscillator clock output goes low, the High-Side Power Switch turns off.

At this point, the SW side of the inductor swings to a diode voltage below ground, causing the inductor current to decrease and magnetic energy to be transferred to output. This state continues until the cycle starts again. The High-Side Power Switch is driven by logic using HSB as the positive rail. This pin is charged to  $V_{\rm SW}$  + 5V when the Low-Side Power Switch turns on. The COMP voltage is the integration of the error between FB input and the internal 0.808V reference. If FB is lower than the reference voltage, COMP tends to go higher to increase current to the output. Output current will increase until it reaches the CC limit set by the ISET resistor. At this point, the device will transition from

regulating output voltage to regulating output current, and the output voltage will drop with increasing load.

The Oscillator normally switches at 250kHz. However, if FB voltage is less than 0.6V, then the switching frequency decreases until it reaches a typical value of 36kHz at  $V_{FB} = 0.15V$ .

#### **Over Voltage Protection**

The ACT4523A has an OVP pin. If the voltage at this pin exceeds 0.8V, the IC shuts down high side switch.

#### Thermal Shutdown

The ACT4523A disables switching when its junction temperature exceeds 155°C and resumes when the temperature has dropped by 25°C.



#### APPLICATIONS INFORMATION

## **Output Voltage Setting**

#### Figure 1:

**Output Voltage Setting** 

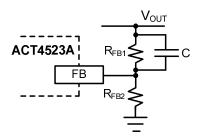


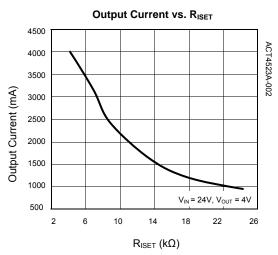
Figure 1 shows the connections for setting the output voltage. Select the proper ratio of the two feedback resistors  $R_{FB1}$  and  $R_{FB2}$  based on the output voltage. Adding a capacitor in parallel with  $R_{FB1}$  helps the system stability. Typically, use  $R_{FB2} \approx 10 k \Omega$  and determine  $R_{FB1}$  from the following equation:

$$R_{FB1} = R_{FB2} \left( \frac{V_{OUT}}{0.808V} - 1 \right) \tag{1}$$

## **CC Current Setting**

ACT4523A constant current value is set by a resistor connected between the ISET pin and GND. The CC output current is linearly proportional to the current flowing out of the ISET pin. The voltage at ISET is roughly 1.1V and the current gain from ISET to output is roughly 21000 (21mA/1 $\mu$ A). To determine the proper resistor for a desired current, please refer to Figure 2 below.

Figure 2: Curve for Programming Output CC Current



#### **Inductor Selection**

The inductor maintains a continuous current to the output load. This inductor current has a ripple that is dependent on the inductance value:

Higher inductance reduces the peak-to-peak ripple current. The trade off for high inductance value is the increase in inductor core size and series resistance, and the reduction in current handling capability. In general, select an inductance value L based on ripple current requirement:

$$L = \frac{V_{OUT} \times (V_{IN}^{-} V_{OUT})}{V_{IN} f_{SW} I_{LOADMAX} K_{RIPPLE}}$$
(2)

where  $V_{\text{IN}}$  is the input voltage,  $V_{\text{OUT}}$  is the output voltage,  $f_{\text{SW}}$  is the switching frequency,  $I_{\text{LOADMAX}}$  is the maximum load current, and  $K_{\text{RIPPLE}}$  is the ripple factor. Typically, choose  $K_{\text{RIPPLE}} = 30\%$  to correspond to the peak-to-peak ripple current being 30% of the maximum load current.

With a selected inductor value the peak-to-peak inductor current is estimated as:

$$I_{LPK-PK} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{L \times V_{IN} \times f_{SW}}$$
(3)

The peak inductor current is estimated as:

$$I_{LPK} = I_{LOADMAX} + \frac{1}{2}I_{LPK-PK} \tag{4}$$

The selected inductor should not saturate at  $I_{LPK}$ . The maximum output current is calculated as:

$$I_{OUTMAX} = I_{LIM} - \frac{1}{2} I_{LPK-PK}$$
 (5)

 $L_{\text{LIM}}$  is the internal current limit, which is typically 4.5A, as shown in Electrical Characteristics Table.

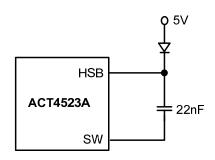
#### **External High Voltage Bias Diode**

It is recommended that an external High Voltage Bias diode be added when the system has a 5V fixed input or the power supply generates a 5V output. This helps improve the efficiency of the regulator. The High Voltage Bias diode can be a low cost one such as IN4148 or BAT54.

Figure 3:
External High Voltage Bias Diode



#### APPLICATIONS INFORMATION CONT'D



This diode is also recommended for high duty cycle operation and high output voltage applications.

#### Input Capacitor

The input capacitor needs to be carefully selected to maintain sufficiently low ripple at the supply input of the converter. A low ESR capacitor is highly recommended. Since large current flows in and out of this capacitor during switching, its ESR also affects efficiency.

The input capacitance needs to be higher than  $10\mu F$ . The best choice is the ceramic type, however, low ESR tantalum or electrolytic types may also be used provided that the RMS ripple current rating is higher than 50% of the output current. The input capacitor should be placed close to the IN and G pins of the IC, with the shortest traces possible. In the case of tantalum or electrolytic types, they can be further away if a small parallel  $0.1\mu F$  ceramic capacitor is placed right next to the IC.

#### **Output Capacitor**

The output capacitor also needs to have low ESR to keep low output voltage ripple. The output ripple voltage is:

$$V_{RIPPLE} = I_{OUTMAX} K_{RIPPLE} R_{ESR} + \frac{V_{IN}}{28 \times f_{SW}^2 L C_{OUT}}$$
 (6)

Where  $I_{\text{OUTMAX}}$  is the maximum output current,  $K_{\text{RIPPLE}}$  is the ripple factor,  $R_{\text{ESR}}$  is the ESR of the output capacitor,  $f_{\text{SW}}$  is the switching frequency, L is the inductor value, and  $C_{\text{OUT}}$  is the output capacitance. In the case of ceramic output capacitors,  $R_{\text{ESR}}$  is very small and does not contribute to the ripple. Therefore, a lower capacitance value can be used for ceramic type. In the case of tantalum or electrolytic capacitors, the ripple is dominated by  $R_{\text{ESR}}$  multiplied by the ripple current. In that case, the output capacitor is chosen to have sufficiently low ESR.

For ceramic output capacitor, typically choose a capacitance of about 22 $\mu$ F. For tantalum or electrolytic capacitors, choose a capacitor with less than 50m $\Omega$  ESR.

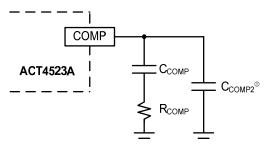
#### **Rectifier Diode**

Use a Schottky diode as the rectifier to conduct current when the High-Side Power Switch is off. The Schottky diode must have current rating higher than the maximum output current and a reverse voltage rating higher than the maximum input voltage.



### STABILITY COMPENSATION

Figure 4: Stability Compensation



①: C<sub>COMP2</sub> is needed only for high ESR output capacitor

The feedback loop of the IC is stabilized by the components at the COMP pin, as shown in Figure 4. The DC loop gain of the system is determined by the following equation:

$$A_{VDC} = \frac{0.808 \text{ V}}{I_{OUT}} A_{VEA} G_{COMP}$$
 (7)

The dominant pole P1 is due to  $C_{COMP}$ :

$$f_{P1} = \frac{G_{EA}}{2 \pi A_{VEA} C_{COMP}}$$
 (8)

The second pole P2 is the output pole:

$$f_{P2} = \frac{I_{OUT}}{2\pi V_{OUT} C_{OUT}} \tag{9}$$

The first zero Z1 is due to R<sub>COMP</sub> and C<sub>COMP</sub>:

$$f_{Z1} = \frac{1}{2\pi R_{COMP} C_{COMP}} \tag{10}$$

And finally, the third pole is due to  $R_{COMP}$  and  $C_{COMP2}$  (if  $C_{COMP2}$  is used):

$$f_{P3} = \frac{1}{2\pi R_{COMP} C_{COMP2}} \tag{11}$$

The following steps should be used to compensate the IC:

STEP 1. Set the cross over frequency at 1/10 of the switching frequency via  $R_{COMP}$ :

$$R_{_{COMP}} \ = \frac{2 \pi V_{_{OUT}} \, C_{_{OUT}} \, f_{_{SW}}}{10 \, G_{_{EA}} G_{_{COMP}} \, \times 0.808 \, V}$$

$$= 5.12 \times 10^7 V_{OUT} C_{OUT} \qquad (\Omega)$$
 (12)

STEP 2. Set the zero  $f_{Z1}$  at 1/4 of the cross over frequency. If  $R_{COMP}$  is less than 15k $\Omega$ , the equation for  $C_{COMP}$  is:

$$C_{COMP} = \frac{2.83 \times 10^{-5}}{R_{COMP}}$$
 (F) (13)

If  $R_{COMP}$  is limited to 15k $\Omega$ , then the actual cross over frequency is 6.58 / ( $V_{OUT}C_{OUT}$ ). Therefore:

$$C_{COMP} = 6.45 \times 10^{-6} V_{OUT} C_{OUT}$$
 (F) (14)

STEP 3. If the output capacitor's ESR is high enough to cause a zero at lower than 4 times the cross over frequency, an additional compensation capacitor  $C_{\text{COMP2}}$  is required. The condition for using  $C_{\text{COMP2}}$  is:

$$R_{\text{ESRCOUT}} \geq \left(Min \; \frac{1.77 \times 10^{-6}}{C_{\text{OUT}}}, 0.006 \times V_{\text{OUT}}\right) \; \; (\Omega) \; \; \; \; (15)$$

And the proper value for  $C_{COMP2}$  is:

$$C_{COMP 2} = \frac{C_{OUT} R_{ESRCOUT}}{R_{COMP}}$$
 (16)

Though  $C_{\text{COMP2}}$  is unnecessary when the output capacitor has sufficiently low ESR, a small value  $C_{\text{COMP2}}$  such as 100pF may improve stability against PCB layout parasitic effects.

Table 1 shows some calculated results based on the compensation method above.

Table 1:

Typical Compensation for Different Output Voltages and Output Capacitors

V <sub>out</sub>	C <sub>OUT</sub>	R <sub>COMP</sub>	C <sub>COMP</sub>	C <sub>COMP2</sub> <sup>①</sup>
2.5V	47µF Ceramic CAP	5.6kΩ	2.2nF	None
3.3V	47µF Ceramic CAP	6.2kΩ	2.2nF	None
5V	47µF Ceramic CAP	12kΩ	2.2nF	None
2.5V	220μF/10V/30mΩ	20kΩ	2.2nF	47pF
3.3V	220μF/10V/30mΩ	20kΩ	2.2nF	47pF
5V	220μF/10V/30mΩ	20kΩ	2.2nF	47pF

①:  $C_{COMP2}$  is needed for high ESR output capacitor.  $C_{COMP2} \le 47pF$  is recommended.

#### **CC Loop Stability**

The constant-current control loop is internally compensated over the 1500mA-3000mA output range. No additional external compensation is required to stabilize the CC current.

#### **Output Cable Resistance Compensation**

To compensate for resistive voltage drop across the charger's output cable, the ACT4523A integrates a simple, user-programmable cable voltage drop compensation using the impedance at the FB pin. Use the curve in Figure 5 to choose the proper feedback resistance values for cable compensation.



#### STABILITY COMPENSATION CONT'D

R<sub>FB1</sub> is the high side resistor of voltage divider.

In the case of high  $R_{\text{FB1}}$  used, the frequency compensation needs to be adjusted correspondingly. As show in Figure 6, adding a capacitor in paralleled with  $R_{\text{FB1}}$  or increasing the compensation capacitance at COMP pin helps the system stability.

Figure 5:
Cable Compensation at Various Resistor Divider Values

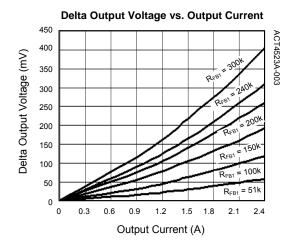
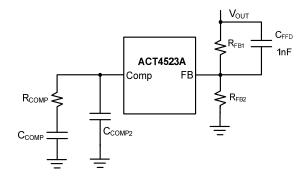


Figure 6: Frequency Compensation for High  $R_{\text{FB1}}$ 

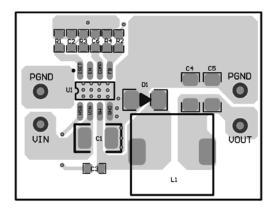


## PC Board Layout Guidance

When laying out the printed circuit board, the following checklist should be used to ensure proper operation of the IC.

- 1) Arrange the power components to reduce the AC loop size consisting of  $C_{\rm IN}$ , IN pin, SW pin and the schottky diode.
- 2) Place input decoupling ceramic capacitor C<sub>IN</sub> as close to IN pin as possible. C<sub>IN</sub> is connected

- power GND with vias or short and wide path.
- Return FB, COMP and ISET to signal GND pin, and connect the signal GND to power GND at a single point for best noise immunity. Connect exposed pad to power ground copper area with copper and vias.
- 4) Use copper plane for power GND for best heat dissipation and noise immunity.
- 5) Place feedback resistor close to FB pin.
- 6) Use short trace connecting HSB-C<sub>HSB</sub>-SW loop Figure 7 shows an example of PCB layout.



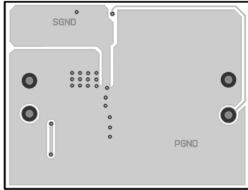


Figure 7: PCB Layout

Figure 9 gives one typical car charger application schematic and associated BOM list.



Figure 8: Typical Application Circuit for 5V/2.4A Car Charger

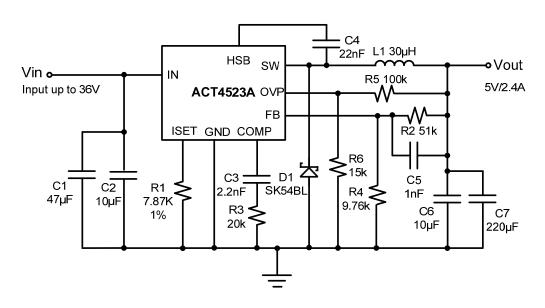


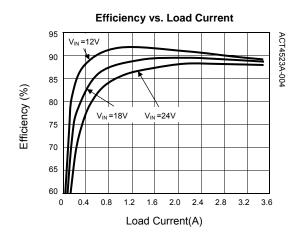
Table 2: BOM List for 5V/2.4A Car Charger

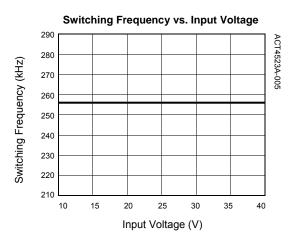
ITEM	REFERENCE	DESCRIPTION	MANUFACTURER	QTY
1	U1	IC, ACT4523AYH, SOP-8EP	Active-Semi	1
2	C1	Capacitor, Electrolytic, 47µF/50V, 6.3x7mm	Murata, TDK	1
3	C2	Capacitor, Ceramic, 10µF/50V, 1206, SMD	Murata, TDK	1
4	C3	Capacitor, Ceramic, 2.2nF/6.3V, 0603, SMD	Murata, TDK	1
5	C4	Capacitor, Ceramic, 22nF/50V, 1206, SMD	Murata, TDK	1
6	C5	Capacitor, Ceramic, 1nF/10V, 0603, SMD	Murata, TDK	1
7	C6	Capacitor, Ceramic, 10uF/10V, 0603, SMD	Murata, TDK	1
8	C7	Capacitor, Electrolytic, 220uF/10V, 6.3x7mm	Murata, TDK	1
9	L1	Inductor, 30µH, 5A, 20%, SMD	Tyco Electronics	1
10	D1	Diode, Schottky, 40V/5A, SK54BL	Diodes	1
11	R1	Chip Resistor, 7.87kΩ, 0603, 1%	Murata, TDK	1
12	R2	Chip Resistor, 51kΩ, 0603, 1%	Murata, TDK	1
13	R3	Chip Resistor, 20kΩ, 0603, 5%	Murata, TDK	1
14	R4	Chip Resistor, 9.76kΩ, 0603, 1%	Murata, TDK	1
15	R5	Chip Resistor, 100kΩ, 0603, 1%	Murata, TDK	1
16	R6	Chip Resistor, 15kΩ, 0603, 1%	Murata, TDK	1

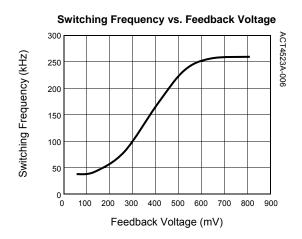


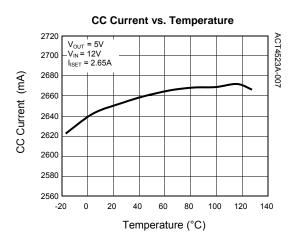
## TYPICAL PERFORMANCE CHARACTERISTICS

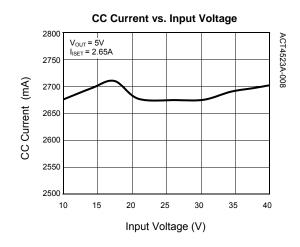
(Schematic as show in Figure 8, Ta = 25°C, unless otherwise specified)

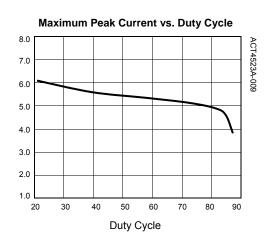








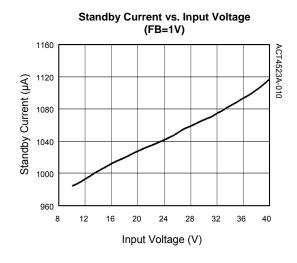


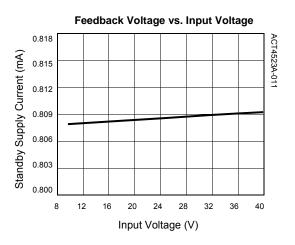


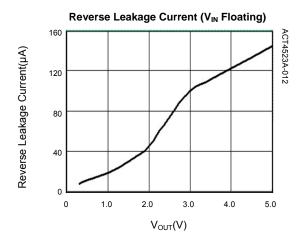


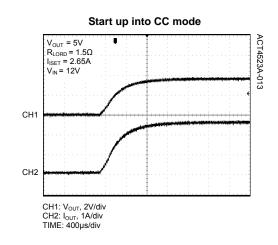
## TYPICAL PERFORMANCE CHARACTERISTICS CONT'D

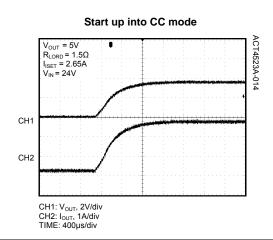
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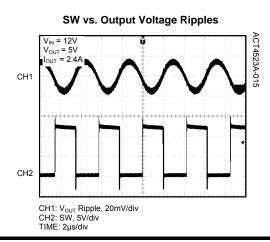












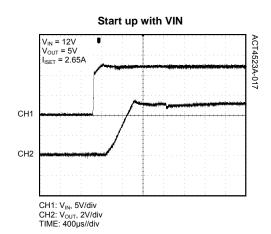


## TYPICAL PERFORMANCE CHARACTERISTICS CONT'D

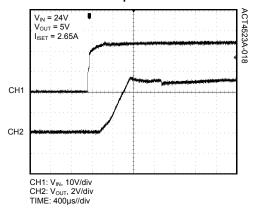
(Schematic as show in Figure 8, Ta = 25°C, unless otherwise specified)

# SW vs. Output Voltage Ripple $V_{IN} = 24V$ $V_{OUT} = 5V$ $I_{OUT} = 2.4A$ CH1 CH2

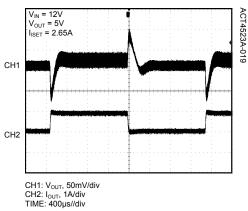
CH1: V<sub>RIPPLE</sub>, 20mV/div CH2: SW, 10V/div TIME: 2µs/div



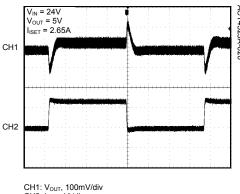
#### Start up with VIN



Load transient (80mA-1A-80mA)

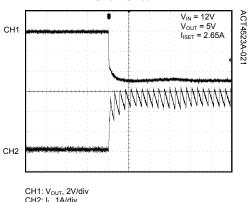


#### Load transient (1A-2.4A-1A)



CH1: V<sub>OUT</sub>, 100mV/div CH2: I<sub>OUT</sub>, 1A/div TIME: 400µs//div

#### **Short Circuit**

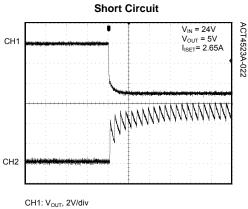


 $\begin{array}{l} \text{CH1: V}_{\text{OUT}},\, 2\text{V/div} \\ \text{CH2: I}_{\text{L}},\, 1\text{A/div} \\ \text{TIME: } 100\mu\text{s//div} \end{array}$ 

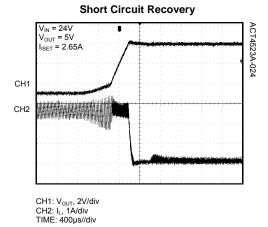


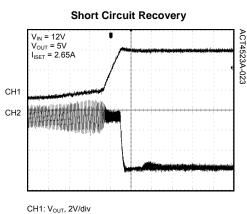
## TYPICAL PERFORMANCE CHARACTERISTICS CONT'D

(Schematic as show in Figure 8, Ta = 25°C, unless otherwise specified)

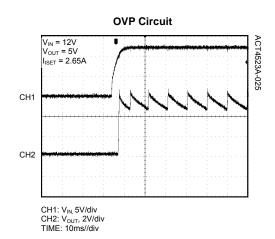








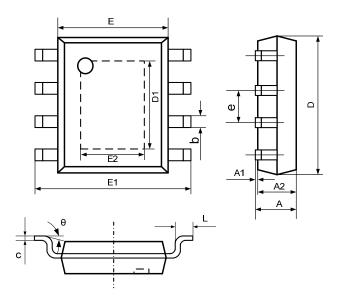






### **PACKAGE OUTLINE**

#### **SOP-8EP PACKAGE OUTLINE AND DIMENSIONS**



SYMBOL	DIMENSION IN MILLIMETERS		DIMENSION IN INCHES		
	MIN	MAX	MIN	MAX	
Α	1.350	1.700	0.053	0.067	
A1	0.000	0.100	0.000	0.004	
A2	1.350	1.550	0.053	0.061	
b	0.330	0.510	0.013	0.020	
С	0.170	0.250	0.007	0.010	
D	4.700	5.100	0.185	0.200	
D1	3.202	3.402	0.126	0.134	
Е	3.800	4.000	0.150	0.157	
E1	5.800	6.200	0.228	0.244	
E2	2.313	2.513	0.091	0.099	
е	1.270 TYP		0.050 TYP		
L	0.400	1.270	0.016	0.050	
θ	0°	8°	0°	8°	

#### Note:

- Dimension D does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15mm per end.
- 2. Dimension E does not include interlead flash or protrusion. Interlead flash or protrusion shall not exceed 0.25mm per side.

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