TC35679FSG-002 Bluetooth[®] low energy IC

Rev 1.20





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1. General Description

1.1. Product Concept

TC35679FSG (Later omitted TC35679.) is compliant with Bluetooth[®] core specification 4.2. RF analog parts and baseband digital parts are built in it, and TC35679 provides Bluetooth[®] HCI (Host Control Interface) functions and Bluetooth[®] low energy GATT profile functions defined by Bluetooth[®] specifications. TC35679 works as an application using Bluetooth[®] low energy communication system by connected with external host processor or external non-volatile memory.

1.2. Features

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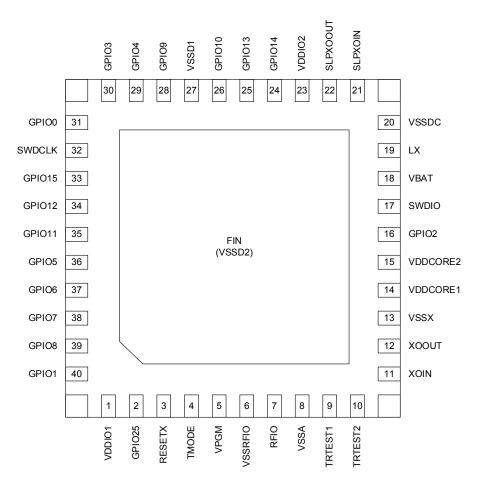
- \succ Compliant with Bluetooth[®] Ver4.2 low energy
 - \diamond Built-in ARM[®] Cortex[®]-M0 (13 MHz or 26 MHz operation frequency is able to select to run)
 - ♦ On-chip mask ROM for Bluetooth[®] program (384 KB)
 - ♦ On-chip work RAM for Bluetooth[®] Baseband process (192 KB)
 - ♦ Supports patch program loader function
- General Purpose IO (17 ports)
- > General Purpose Serial Interfaces
 - ♦ SPI interface (1 ch shared with a General Purpose IO)
 - \diamond I²C interface (1 ch shared with a General Purpose IO)
- Host CPU Interface
 - ♦ UART interface (9600 bps to 921.6 kbps, 2 ch shared with GPIOs)
 - ♦ SPI interface
- > Emulator debug control interface
 - ♦ SWD (Serial Wire Debug) 2-wire (1 ch)
- Wake-up Interface (2 ch shared with General Purpose IOs)
 - ♦ Wake-up input function from sleep and deep sleep
 - PWM Interface (4 ch assigned to General Purpose IOs)
- Reference Clock Input (26 MHz)
 - ♦ Built-in oscillator for crystal oscillator connection
- Sleep Clock Input (32.768 kHz)
 - ♦ External oscillator input supported
 - ♦ Built-in oscillator for crystal oscillator connection
- > Works as external host control and standalone
 - (Please refer to the software application notes and programming guide for the method of control software design.)
- Sleep and Deep Sleep Functions
- Built-in DCDC converter and LDO
 - Wide range of input power supply voltages supported (1.8 to 3.6 V, Built-in low battery voltage detection.)
- Built-in general purpose ADC
 - External analog inputs (5 ch shared with General Purpose IOs)
 - Internal Power supply voltage monitoring (1 ch connected inside)
- > External radio front-end control
 - Radio transmitting and receiving timing signal output (1 ch shared with a General Purpose IO)
- Package:

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♦ TC35679FSG: QFN Package [40 pin, 5 x 5 mm, 0.4 mm pitch, 0.9 mm thickness]

2. Pin Function

2.1. TC35679FSG Pin Assignment (Top View)





2.2. Pin Function Descriptions

Table 2-1 shows attributes, input/output states for operating modes and descriptions for pin functions. Table 2-4 shows descriptions about power supply pins.

Pin name	Pin No.	Attribute	Condition	Functional description
		VDD category	Default	
		Direction	(during reset)	
		Туре		
			Reset interface	
RESETX	3	VDDIO	—	Hardware reset input pin.
		IN		Setting this pin to Low level put the system at reset
		Schmitt trigger		state.
			Clock interface	
XOIN	11	VDDCORE	IN	Reference clock input pin. Please use oscillator with
		IN		26 MHz and < 50 ppm accuracy.
		OSC		A feedback resistor is built in between XOIN pin and
				XOOUT pin and a capacity array which can set
				parameters in the crystal oscillation circuit is built-in,
				so that external feedback resistances and
				capacities are unnecessary.
XOOUT	12	VDDCORE	OUT	Oscillator output for Baseband and RF reference
		OUT		clock (26 MHz) pin.
		OSC		A feedback resistor is built in between XOIN pin and
				XOOUT pin and a capacity array which can set
				parameters in the crystal oscillation circuit is built-in,
				so that external feedback resistances and
				capacities are unnecessary.
SLPXOIN	21	VDDIO	IN	Sleep clock input pin from oscillator. Please use an
		IN		oscillator with 32.768 kHz and < 500 ppm accuracy.
		OSC		A feedback resistor is built in between SLPXOIN pin
				and SLPXOOUT pin and a capacity array which
				can set parameters in the crystal oscillation circuit is
				built-in, so that external feedback resistances and
				capacities are unnecessary. An external clock can
				be input from this pin. When the crystal oscillator is
				not used and do not supply a clock from the
				outside, this pin should be connected to the GND.
SLPXOOUT	22	VDDIO	OUT	Sleep clock output pin from oscillator.
		IN/OUT		A feedback resistor is built in between SLPXOIN pin
		OSC		and SLPXOOUT pin and a capacity array which
				can set parameters in the crystal oscillation circuit is
				built-in, so that external feedback resistances and
				capacities are unnecessary.
				When the crystal oscillator is not used and do not
				supply a clock from the outside, this pin should be
				connected to the GND.

Table 2-1 Pin Functions

Pin name	Pin No.	Attribute	Condition	Functional description
		VDD category	Default	
		Direction	(during reset)	
		Туре		
			RF interface	
RFIO	7	VDDCORE	—	RF I/O pins.
		IN/OUT		This product incorporates the 50 Ω matching circuit,
		Analog		so that external matching circuit is unnecessary.
				The RF output pattern should wire with the 50 Ω
				transmission line.
				For details, refer to the hardware application note of
				this product.
			General purpose I/O	port
GPIO0	31	VDDIO	Hi-Z	General purpose I/O pin.
		IN/OUT		During reset, the pull-up and pull-down resistors are
		Pull-up		unconnected (input disable state). The same state
		Pull-down		continues just after the reset is released, and it will
		Schmitt trigger		be controlled by software after that. After the pin
				configuration by software processing, it works as a
				GPIO pin of the input and output or Table 2-2
				function.
				Pin processing when not using this function are
				listed in Table 2-2. (Note)
GPIO1	40	VDDIO	Pull-up	General purpose I/O pins.
GPIO2	16	IN/OUT		During reset, the pull-up resistor is connected (input
GPIO5	36	Pull-up		disable state). The pull-up resistor is connected
GPIO6	37	Pull-down		(input state) just after the reset is released, and it will
GPIO7	38	Schmitt trigger		be controlled by software after that. After the pin
GPIO8	39			configuration by software processing, it works as a
GPIO11	35			GPIO pin of the input and output or Table 2-2
GPIO12	34			function.
GPIO25	2			Pin processing when not using this function are
				listed in Table 2-2. In addition, GPIO1 pin is used in
				the case of switching operation modes. (Note)
GPIO3	30	VDDIO	Hi-Z	ADC input and general purpose I/O pins.
GPIO4	29	IN/OUT		During reset, the pull-up and pull-down resistors are
GPIO9	28	Pull-up		unconnected (input disable state). The same state
GPIO10	26	Pull-down		continues just after the reset is released, and it will
GPIO14	24	Schmitt trigger		be controlled by software after that. Then the
				software configures pull-up/pull-down resistors, and
				the pin can function as general ADC input, or
				general purpose IO.
				Pin processing when not using this function are
				listed in Table 2-2. (Note)

Pin name	Pin No.	Attribute	Condition	Functional description
		VDD category	Default	
		Direction	(during reset)	
		Туре		
GPIO13	25	VDDIO	Pull-up	General purpose IO pin.
		IN/OUT		During reset, the pull-up resistor is connected (input
		Pull-up		disable state). The pull-up and pull-down resistors
		Pull-down		are unconnected (input disable state) just after the
		Schmitt trigger		reset is released, and it will be controlled by
				software after that.
				After the pin configuration by software processing, it
				works as a GPIO pin of the input and output or
				Table 2-2 function. (Note)
GPIO15	33	VDDIO	Hi-Z	General purpose I/O pin.
		IN/OUT		During reset, the pull-up and pull-down resistors are
		Pull-up		unconnected (input disable state). The pull-up
		Pull-down		resistor is connected (input state) just after the reset
		Schmitt trigger		is released, and it will be controlled by software after
				that. After the pin configuration by software
				processing, it works as a GPIO pin of the input and
				output or Table 2-2 function.
				Pin processing when not using this function are
				listed in Table 2-2. (Note))
		Em	ulator debug control ir	nterface
SWDCLK	32	VDDIO	Pull-down	Serial Wire debugger clock pin.
		IN		During reset, the pull-down resistor is connected
		Pull-up		(input state). After the reset is released, the serial
		Pull-down		wire debugger clock is inputted.
		Schmitt trigger		When not used, this pin should be open.
SWDIO	17	VDDIO	Pull-up	Serial Wire Debugger data pin and operation
		IN/OUT		switching pin.
		Pull-up		During reset, the pull-up resistor is connected (input
		Pull-down		state). After the reset is released, the serial wire
		Schmitt trigger		debugger data is inputted and outputted.
				When not used, this pin should be open.
			IC test interface	
TMODE	4	VDDIO	—	Test mode setting pin.
		IN		This pin is used for IC manufacturing test and
		Schmitt trigger		needs to be connected to GND when assembled
				on a board.
TRTEST1	9	VDD12A	—	Analog test pins.
TRTEST2	10	IN/OUT		These pins are used for IC manufacturing test and
		Analog		need to be connected to GND when assembled on
				a board.

Note: The state of the GPIO pin corresponds to the usage state in the user application mode. Since states differ partially when the operation is powered on with the HCI mode, please refer to the software application note about the detailed state and its setting method of each pin.

2.3. GPIO function list

GPIO pins can be assigned to UART I/Fs, serial memory I/Fs and etc. by TC35679 firmware or command from the external Host. Table 2-2 shows available functions for each GPIO pin, and Table 2-3 examples of GPIO function settings. About what function name shown in Table 2-2 is assigned to a plurality of pins in the same, please note that it cannot be assigned to select a plurality of pins at the same time.

Pin name	Function 1	Function 2	Function 3	Function 4	Analog input	The pins of Unused
GPIO0	WakeUp0 Input	—	_	—	—	Open
GPIO1	PWM0 Output	—	_	—	—	Open (Note)
GPIO2	PWM1 Output	—	—	—	—	Open
GPIO3	PWM2 Output	SPI-DOUT Output	_	—	ADC1 Input	Open
GPIO4	PWM3 Output	SPI-DIN Input	_	—	ADC2 Input	Open
GPIO5	UART1-TX Output	SPI-DOUT Output	_	—	—	Open
GPIO6	UART1-RX Input	SPI-DIN Input	—	—	—	Open
GPI07	I2C-SCL Output	UART2-TX Output	SPI-SCS	UART1-RTSX	—	Open
GFIO7	12C-SCL Output	UARTZ-TX Oulpul	Output	Output		
	GPIO8 I2C-SDA I/O UART		SPI-SCLK	UART1-CTSX		Open
01100	120-30A 1/0	UART2-RX Input	Output	Input		
GPIO9	_	_			ADC3 Input	Open
GPIO10	_	—	—		ADC4 Input	Open
GPIO11	I2C-SCL Output	SPI-DOUT Output	—	—	—	Open
GPIO12	I2C-SDA I/O	SPI-DIN Input	—	—	—	Open
GPIO13	UART1-RTSX					Open
GFI013	Output	—		_	_	
GPIO14	UART1-CTSX Input	—	—	—	ADC5 Input	Open
GPIO15	WakeUp1 Input		_			Open
GPIO25	—	—	—	—		Open

Table 2-2 Available functions for GPIO

Note: Handle with care because of using operation mode switching.

Pin name	Basic example	Example of	Example of SPI +	Example of
		SPI unused	I ² C	UART + SPI + I ² C
GPIO0	WakeUp0	WakeUp0	WakeUp0	WakeUp0
GPIO1	PWM0	PWM0	PWM0	PWM0
GPIO2	PWM1	PWM1	PWM1	PWM1
GPIO3	SPI-DOUT	PWM2	PWM2	SPI-DOUT
GPIO4	SPI-DIN	ADC2	PWM3	SPI-DIN
GPIO5	UART1-TX	UART1-TX	SPI-DOUT	UART1-TX
GPIO6	UART1-RX	UART1-RX	SPI-DIN	UART1-RX
GPIO7	SPI-SCS	UART1-RTSX	SPI-SCS	SPI-SCS
GPIO8	SPI-SCLK	UART1-CTSX	SPI-SCLK	SPI-SCLK
GPIO9	ADC3	ADC3	ADC3	ADC3
GPIO10	ADC4	ADC4	ADC4	ADC4
GPIO11	I2C-SCL	I2C-SCL	I2C-SCL	I2C-SCL
GPIO12	I2C-SDA	I2C-SDA	I2C-SDA	I2C-SDA
GPIO13	UART1-RTSX	GPIO13	GPIO13	GPIO13
GPIO14	UART1-CTSX	ADC5	ADC5	ADC5
GPIO15	WakeUp1	WakeUp1	WakeUp1	WakeUp1
GPIO25	GPIO25	GPIO25	GPIO25	GPIO25

Table 2-3 GPIO function list (example)

Note: There are other functions than the above examples. About the detail of the other functions, refer to firmware specification.

2.4. Power Supply Pins

Table 2-4 shows the attributes and descriptions of power supply pins for normal operations.

Table 2-4 Power supply pins

Pin name	Pin	Attribute	Description
	number		
		Туре	
		VDD/GND	
			VDD / GND
VPGM	5	TEST	Test pin
		—	Please connect VPGM to GND.
VBAT	18	VBAT	Power supply pin for DCDC and sleep circuit.
		VDD	Connect the external power source for DCDC and LDO built
			into the IC.
LX	19	VBAT	DCDC output pin.
		VDD	Please connect to external inductor for DCDC.
VDDCORE1	14	—	DCDC for feedback input, analog circuit power supply pin.
		VDD	Please connect to external inductor for DCDC.
VDDCORE2	15	—	DCDC for feedback input, digital circuit power supply pin.
		VDD	Please connect to external inductor for DCDC.
VDDIO1	1	VDDIO	IO power supply.
VDDIO2	23	VDD	Power supply pin for GPIO.
VSSA	8	Analog	GND pin for analog, this pin needs to be connected to GND.
		GND	
VSSRFIO	6	Analog	GND pin for RFIO, this pin needs to be connected to GND.
		GND	
VSSX	13	Analog	GND pin for OSC, this pin needs to be connected to GND.
		GND	
VSSDC	20	Digital	GND pin for DCDC, this pin needs to be connected to GND.
		GND	
VSSD1	27	Analog, Digital	GND pin for analog, digital common, this pin needs to be
VSSD2	FIN	GND	connected to GND.
			Connect the exposed Die Pad to GND because this pad is
			digital ground as well.

3. System Configuration

3.1. Block Diagram

Figure 3-1 shows block diagram of TC35679. TC35679 is powered by single voltage between 1.8 V and 3.6 V. The chip has built-in DCDC and LDO requiring external capacitors. It uses 26 MHz reference clock and 32.768 kHz sleep clock. External memory Interface is SPI or I²C, and host CPU interface is UART.

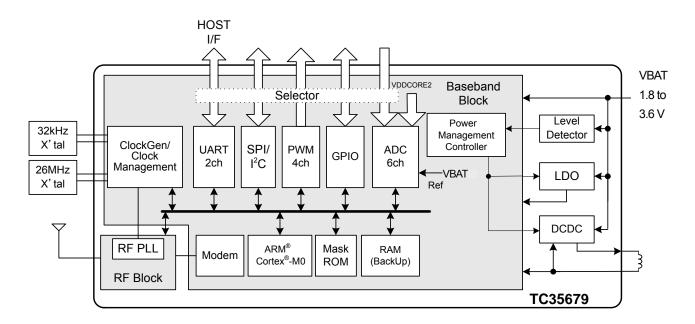


Figure 3-1 Example of the TC35679 internal block diagram and the peripheral components connection diagram

4. Functional Specifications

4.1. Bluetooth[®] Function

The Bluetooth[®] function is realized by using the hardware which is configured with RF analog and baseband, and the software on a mask ROM. Only connecting a crystal oscillator and some discrete parts externally, the Bluetooth[®] wireless communication can work.

4.1.1. Supported Function

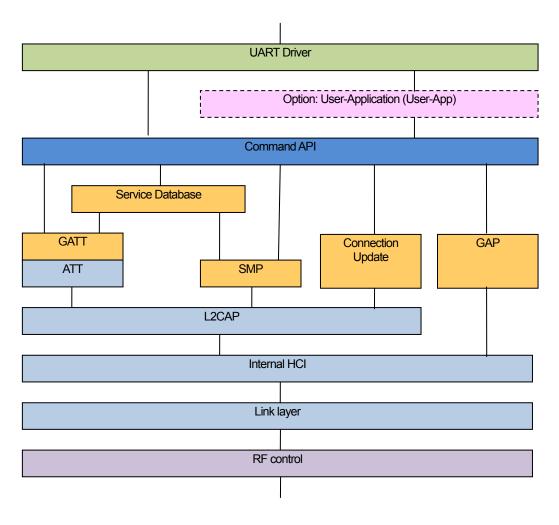
This function is compliant with Bluetooth[®] V4.2 low energy standard. Main supported functions are shown below.

Items	Description	Notes
Bluetooth [®] Core	4.2	LE is supported.
v4.0 features	res Central	
	Peripheral	Supported
	Multi Profile/point	Supported
	Connection Update	Supported
	Random Address	Supported
	WhiteList	Supported
	Security Property (Just Works)	Supported
	Security Property (PassKey Entry)	Supported
	Security Property (OOB)	Supported
	Security Property (Numeric Comparison)	Supported
	GATT-Client	Supported
	GATT-Server	Supported
	Broadcaster	Supported
	Observer	Supported
v4.1 features	Low Duty Cycle Directed Advertising	Supported
	32-bit UUID support in LE	Supported
	LE L2CAP Connection Oriented Channel Support	Supported
	LE Privacy v1.1	Supported
	Connection Parameter Request Procedure	Supported
	Extended Reject Indication	Supported
	Slave-initiated Features Exchange	Supported
	LE Ping	Supported
	Act as LE Master and LE Slave at the same time	Supported
	Act as LE Slave to more than one LE Master at the same time	Supported
v4.2 features	LE Data Packet Length Extension	Supported
	LE Secure Connections	Supported
	Link Layer Privacy	Supported
	Link Layer Extended Scanner Filter Policies	Supported

Table 4–1 List of supported functions

4.1.2. Support Protocol Layer

Following figure shows the Bluetooth Protocol and Profile Layer supported. It has RF control, Link layer, internal HCI, L2CAP, ATT, SMP and GATT.





4.1.3. RF

Since the RF analog part of TC35679 builds in not only transmission and reception circuits but also the RF switch and the matching circuit, the RFIO pin which is a single I/O does not need an external matching circuit. The wireless device which suits for RF-PHY specifications of Bluetooth low energy can be realized easily by connecting to 50Ω wiring.

The transmission power can be selected from intended power between 0 and -20 dBm (4 dB steps). Not only default transmission power but also transmission power to the specified destination can be set. The RSSI of reception block has an accuracy of ± 2 dB (typ.) to the input signal between -90 and -10 dBm.

4.1.4. Auto Advertise Function

Using an auto advertise function enables repeating transmissions of advertise packets with very small power. The auto advertise function is a function which transmits intended advertise packets without waking CPU up in Backup mode. Then, a scan request and a connection request can be also received. The response to the remote device can be preset in case of receiving a scan request, and when one connection request is received, this function wakes CPU up and leaves a subsequent process to the user software.

4.2. Reset Interface (Power up sequence)

4.2.1. Features

Reset interface has the following features.

- 1.8 to 3.6 V operation
- Level sensitive asynchronous reset (Low level: reset)

When the power supply is applied, the external reset signal connected to the TC35679 should be held the reset state (RESETX = Low). Please release the reset (RESETX = High) after the power supply voltage reaches 1.8 V or more and becomes stable. Then, the oscillation of a crystal oscillator is started, and the internal reset is released by the internal timer after the oscillation-stable time of the crystal oscillator is passed.

4.2.2. Connection Example

Figure 4-2 shows connection example where TC35679 is powered through RC time constant circuit.

Reset signal can be given from power supply through RC time constant circuit, or can be connected with an IC which has asynchronous and level sensitive reset function. Figure 4-3 shows the timings to reset and reset-release for the power supply.

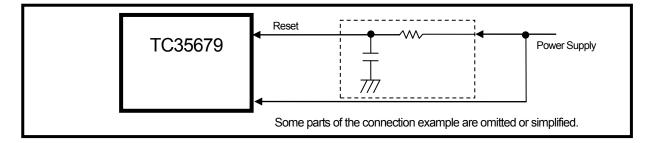


Figure 4-2 Reset signal connection example

VBAT Power supply	1.8 V or more at startup
VDDIO Power supply	So as not to VBAT <vddio< td=""></vddio<>
Reset signal	-> Necessary for a reset release after VDDIO stabilization
Internal LDO DC/DC converter	LDO On DC/PC On System changes an internal power after sleep clock detection (It enters temporarily to Sleep mode.)
Reference clock	Oscillation Boot completion Operation starts
Sleep clock (in case of crystal oscillator connection)	Oscillation
Sleep clock (in case of external oscillator connection)	It may be input after stabilization of reference clock

Figure 4-3 Power-on reset release sequence

4.3. UART Interface

4.3.1. Features

TC35679 UART interface has the following features.

- > 1.8 to 3.6 V operation
- Full-duplex four-wire start-stop synchronization data transfer (Reception data, Transmission data, Reception flow control, and Transmission flow control)
- Selectable between 2-line start-stop synchronous transfer (Reception data and Transmission data) and 4-line start-stop synchronous transfer (Reception data, Transmission data, Reception flow control, and Transmission flow control)
- Start bit field (1 bit), data bit field (8 bits, LSB first), stop bit field (1 bit), no parity bit
- > UART transmit and receive data pins can be switched by the command of HCI mode. (UART2 function)
- > Programmable baud rate: 9600 bps to 921.6 kbps.
- 3 (or more) character interval should be inserted between one transmission message and another transmission message.
 The length of the interval can be changed by a command.
- > Error detection (Reception character timeout, Reception overrun error, Reception framing error)
- Host wake up function

TC35679 communicates commands, status, and data with a host CPU through UART interfaces. The UART interfaces are shared with GPIO pins, and during boot process after a reset, TC35679 firmware assigns UART functions to the GPIOs. The UART interfaces can operate at 1.8 to 3.6 V depending on the VDDIO power supply voltage. Because the power supply pin is shared with UART interface and the other hardware interfaces, UART interface cannot operate at a different voltage from the others.

4.3.2. Connection Example

TC35679 UART can be connected with an UART interface on a host CPU. Figure 4-4 shows an example of two-wire start-stop synchronization data transfer connection with an external host CPU. The timing chart to assign the GPIO pins to the UART function is shown in Figure 4-5.

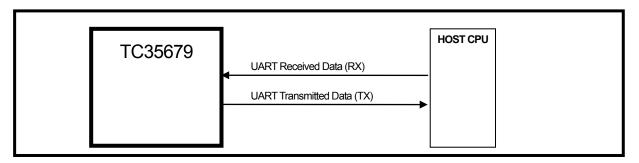


Figure 4-4 UART connection example

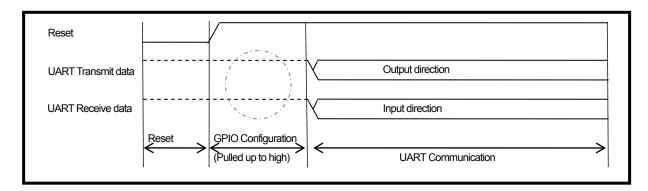


Figure 4-5 Timing for UART function assignment

4.3.3. Frame Format

TC35679 supports the following format:

- Number of data bits: 8 bits (LSB first)
- Parity bit: no parity
- Stop bit: 1 stop bit
- Flow control: RTSX/CTSX

Figure 4-6 shows UART data frame.

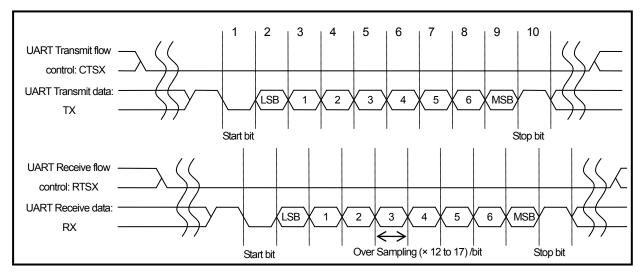


Figure 4-6 UART data frame

4.3.4. Flow Control Function

Hardware flow control is available when TC35679 UART interface is assigned to GPIO5 to GPIO8 (GPIO5, 6, 13, 14) as four-wire start-stop synchronization data transfer. Transmit flow control (CTSX) and receive flow control (RTSX). Figure 4-7 shows signals input and output direction.

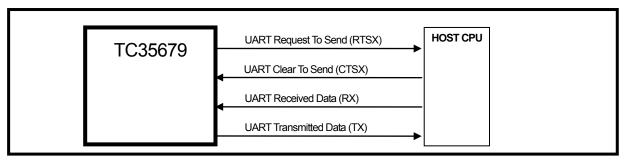


Figure 4-7 UART connection example

CTSX (Clear to Send) input signal is used for UART transmitting. Low input indicates the peer device (for example, the host in the Figure 4-7) is ready to receive data, and TC35679 sends data if it has data to transmit. On the other hand, TC35679 stops transmitting on the basis of UART unit frame when CTSX input is high.

RTSX (Request to Send) output signal is used for UART receiving. Low output indicates TC35679 is ready to receive data and requests data to the peer device. TC35679 outputs RTSX low when ready to receive data. When the UART becomes busy and cannot receive data, TC35679 outputs RTSX high, and stops UART communication on the basis of UART unit frame.

Response time of UART transmitting and receiving to flow control signals is between 1 frame to 4 frames depending on the baud rate and internal process status of frame.

4.3.5. UART Baud Rate Setting

TC35679 UART interface has a programmable baud rate setting function. The UART baud rate is generated from 26 MHz clock, and can be set according to the following equation depending on over sampling number and dividing ratio.

Table 4-2 shows examples of UART Baud rate settings. If other target baud rates are required, please contact our engineering department.

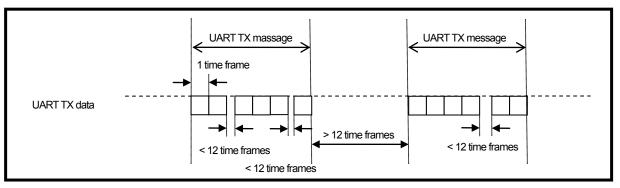
Target baud rate [bps]	Actual baud rate [bps]	Over sampling rate	Frequency dividing ratio
9600	9587.021	12	226
14400	14396.46	14	129
19200	19174.04	12	113
28800	28856.83	17	53
38400	38461.54	13	52
57600	57777.78	15	30
76800	76923.08	13	26
115200	115555.6	15	15
153600	153846.15	13	13
230400	232142.9	16	7
307200	305882.4	17	5
460800	464285.7	14	4
921600	928571.4	14	2

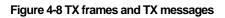
Table 4-2 UART Baud rate settings

Note: Error of target baud rate and the actual baud rate is to be set to within 1 %.

4.3.6. TX message spacing function

TC35679 spaces more than 12 time frames between different TX messages making less than 12 time frames between TX frames in a TX message when several TX frames belong to one TX message. Host CPU is able to know the boundaries between TX messages by measuring time frames between TX frames.





4.3.7. Error Detecting Functions

TC35679 UART interface has 3 kinds of error detecting functions.

- Receiver timeout error
- Receiver over run error
- Receiver frame error

Receiver timeout error detection judges an error if an UART RX message made from several RX frames has an RX frame interval longer than a certain value. The interval is counted by internal timer. Keep the interval between RX frames less than 12 time frames that belong to an RX message. For UART1, keep intervals between different RX messages more than 12 time frames. For example, 115200 bps has 0.087 ms for 1 frame, the interval between RX messages should be longer than 0.087 ms \times 12 = 1.04 ms. RX messages that has intervals less than 12 time frames gives an error because TC35679 sees them as one UART RX message. Interval of the received frame is the default in the 12 time frame, but it can be changed by the command. In the case of UART2, of different UART receive message interval is more than 14 ms.

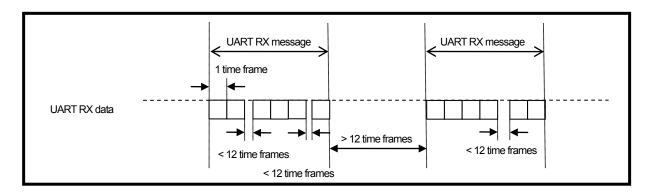


Figure 4-9 RX frames and RX messages

Receiver over run error judges if UART receive frame buffer internal TC35679 is overflowed. Normally, this overflow does not happen when the flow control mentioned in 4.2.4 is activated for data communication.

Receiver frame error judges if failing recognize the unit frame. A frame formation is judged as failure when its start bit is detected and the corresponding stop bit is detected as "0".

4.3.8. Host Wake up Function

TC35679 can wakes up its host before sending UART data to the host. This function is disabled by default, but can be assigned to GPIO by command. Host wake up time can be changed by command (10 ms by default).

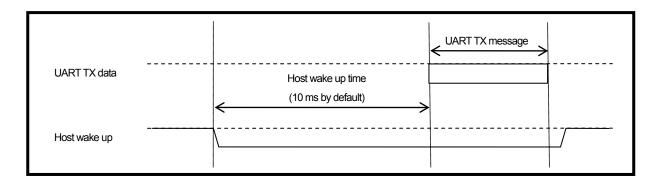


Figure 4-10 Host wake up

4.3.9. HCI mode

When TC35679 is used in the HCI mode, UART is the host interface to receive HCI commands.

The Bluetooth[®] wireless performance can be tested in HCI mode by the measurement equipment which connects the UART directly.

4.3.9.1. HCI Reset

To process the following commands successfully, it is needed that the host waits at least $150 \ \mu s$ from the command complete event after sending a HCI reset command.

4.4. SPI Interface

4.4.1. Features

TC35679 has the following main features for a serial memory interface

Operation voltage:		1.8 to 3.6 V
SPI interface		
\triangleright	Chip select:	1 ch
\triangleright	Chip select polarity:	Selectable: High-active and Low-active
\triangleright	Serial clock master operation:	Polarity and phase are adjustable (4 combinations are selectable)
\triangleright	Serial clock frequency:	25 Hz to 6.5 MHz
\triangleright	Serial data transfer mode:	MSB-first, LSB-first

SPI interface can operate at 1.8 to 3.6 V depending on VDDIO, however, because the power supply pin is shared with SPI interface and the other hardware interfaces, SPI interface cannot operate at a different voltage from the others.

4.4.2. Connection Example

TC35679 SPI interface can be connected to serial EEPROMs and serial Flash-ROMs and has 1 chip select port. Figure 4-11 shows a connection example, where a serial Flash-ROM is connected to TC35679 SPI interface.

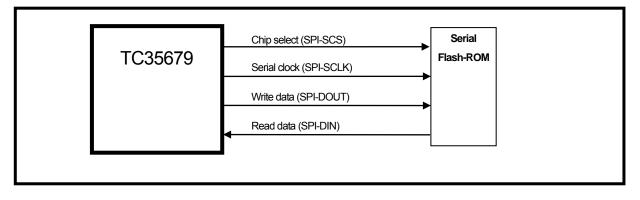


Figure 4-11 Connection example for serial Flash-ROM using SPI interface

4.4.3. Frame Format

When the SPI interface is connected to external ICs, the first 8 bit (X7 to X0) specifies the address and read or write mode. The command recognition code type and the address bit width should be determined by the external IC in use. For more information in detail, please refer to the technical documents for the external IC.

Figure 4-12 shows an example where 8-bit address is written and then 8-bit data is read. Figure 4-13 shows an example where 8-bit address is written and then 8-bit data is written.

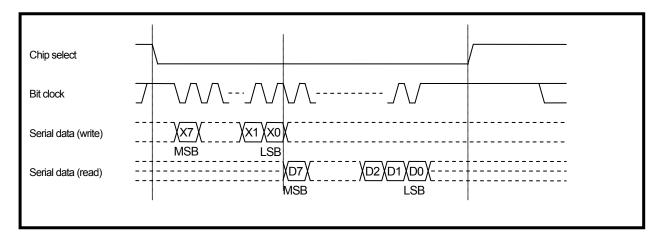


Figure 4-12 SPI format (single byte read)

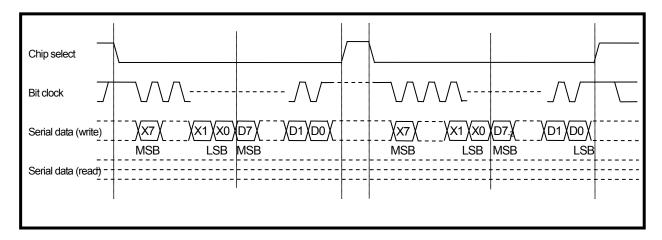


Figure 4-13 SPI format (single byte write)

4.5. I²C Interface

4.5.1. Features

TC35679 has the following main features for a serial memory interface.

- > Operation voltage: 1.8 to 3.6 V
- ➢ I²C interface

 \triangleright

 \geq

- I²C bus master
- Serial clock (I2C-SCL) frequency: Standard mode (Max 100 kHz), Fast mode (Min 100 kHz to Max 400 kHz)
- > Output mode:

Operation mode:

- Open-drain output, CMOS output
- Device address format: 7 bits address (10 bits address is not supported)

 I^2C interface can operate at 1.8 to 3.6 V depending on VDDIO, however, because the power supply pin is shared with I^2C interface and the other hardware interfaces, I^2C interface cannot operate at a different voltage from the others.

4.5.2. Connection Example

Figure 4-14 shows a connection example of a serial EEPROM using I²C bus interface of the open-drain mode. External pull-up resistors (Rext) are necessary for both serial clock line and serial data line.

Figure 4-15 shows another connection example where I²C bus is in the CMOS output mode. Only the serial data line needs Rext because this line can be driven by neither TC35679 nor a serial EEPROM.

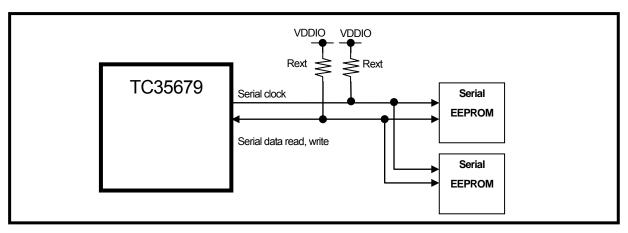


Figure 4-14 Connection example for serial EEPROM with I²C-bus interface (Open-drain output)

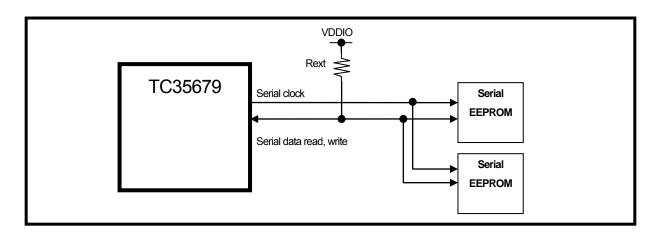


Figure 4-15 Connection example for serial EEPROM with I²C-bus interface (CMOS output)

4.5.3. Selection of External Pull-up Resistor Value

An external pull-up resistor value needs to be selected by the following equations in case of I^2C bus interface. Its maximum value is defined by equation (1), in which t_r is rise time of serial clock and data and C_b is I^2C bus capacity. Its minimum value is defined by equation (2), in which VDDIO is a supply voltage for TC35679, V_{ol_max} is the maximum value of low level output voltage, and I_{ol} is the low level output current. Please set the pull-up resistor value between these lower and upper limits.

$$R_{\text{ext}_\text{max}} = \frac{t_r}{0.8473 \times C_b} \tag{1}$$

$$R_{\text{ext}_\min} = \frac{VDDIO - V_{ol}_\max}{I_{ol}}$$
(2)

TC35679 supports I^2C bus standard mode (Max 100 kHz) and I^2C bus fast mode (Min 100 kHz to Max 400 kHz). The rise time t_r is 1000 ns for the standard mode and it is 300 ns for the fast mode. C_b can vary depending on the IC board and how it is implemented. Table 4-3 and Table 4-4 show examples when I^2C bus capacity is 20 pF.

I ² C bus frequency		Max 100 kHz							
tr [ns]		1000							
Cb [pF]		20							
VDDIO [V]	1.8			3.0			3.6		
Vol_max [V]	0.3			0.4			0.4		
lol [mA]	1	2	4	1	2	4	1	2	4
Rext_min [k Ω]	1.50	0.75	0.38	2.60	1.30	0.65	3.20	1.60	0.80
Rext_max [k Ω]					59.01				

Table 4-3 External pull-up resistor value for I²C standard mode (Cb = 20 pF)

I ² C bus frequency		Min 100 to Max 400 kHz							
tr [ns]		300							
Cb [pF]		20							
VDDIO [V]		1.8 3.0					3.6		
Vol_max [V]	0.3			0.4			0.4		
lol [mA]	1	2	4	1	2	4	1	2	4
Rext_min [k Ω]	1.50	0.75	0.38	2.60	1.30	0.65	3.20	1.60	0.80
Rext_max [kΩ]					17.70				

4.5.4. Frame Format

For I²C format, TC35679 first generates start condition. Then, it sends device recognition address (7 bit: [A6:A0]) and the first byte address ([B7:B0]) for the access target. Next, it goes for read or write sequence. For I²C, every data is sent as MSB first. How to specify the value and byte address of the device identification address, and it has been determined in accordance with the device to be connected. In order to be connected, it must match the device to be connected. For read operation, TC35679 returns to the serial memory either receive acknowledge bit (ACK) or receive not acknowledge bit (NACK) every time it receives one byte. For write operation, TC35679 receives either ACK or NACK from the serial memory every time it sends one byte. It can handle not only one byte but also several bytes in a row. TC35679 generates stop condition when it has finished all the read or write of data.

Figure 4-16 shows an example where TC35679 reads two-byte data. Figure 4-17 shows an example where TC35679 writes two-byte data. In these examples, gray texts and lines indicate signals that are given by the serial memory. For read operation, after having read the final byte data, TC35679 returns NACK with which the serial memory gets to know the completion of the read operation.

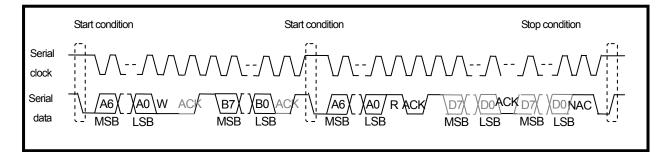


Figure 4-16 I²C format (Serial memory, read)

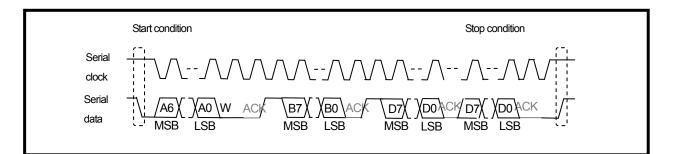


Figure 4-17 I²C format (Serial memory, write)

4.6. PWM Interface

TC35679 has a PWM interface that can be used for LED, buzzer control, etc.

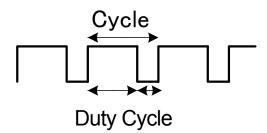
The PWM interface has the following features.

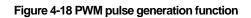
- Arbitrary pulse generation function
- It can select the source clock from 13 MHz and 32.768 kHz
- It has 12 bits clock division setting up to 1/4096 8 Hz to 16.384 kHz (32.768 kHz), 3.17 kHz to 6.5 MHz (13 MHz)
- The pulse output can be masked by the regular pattern which period is one second with 50 ms unit width (rhythm function)
- The interrupt can be generated in synchronization with the cycle of 1 s rhythm pattern.
- It can switch the pulse output to Low / High active
- Duty of the pulse output is adjustable.

4.6.1. Pulse Generation Function

Figure 4-18 shows a brief explanation of the pulse generation. TC35679 can adjust output pulse frequency by changing its cycle. Also it can adjust on/off ratio by changing its duty.

The frequency (cycle) can be set from 8 Hz to 16.384 kHz for 32.768 kHz clock, and from 3.17 kHz to 6.5 MHz for 13 MHz clock. The duty can be set from 0 % to 100 %.





4.6.2. Rhythm Function (Output Masking)

Figure 4-19 shows the brief explanation of PWM rhythm function. In addition to the one for pulse generation, TC35679 has another timer that has 50 ms \times 20 = 1 s (rhythm counter). That timer has 20 bits register (pattern register), each bit corresponds to the rhythm counter that counts down in every 50 ms. When the pattern register is zero, the PWM output is masked to zero or one. Using this function, LED or buzzer can be on with 1 s periodical pattern.

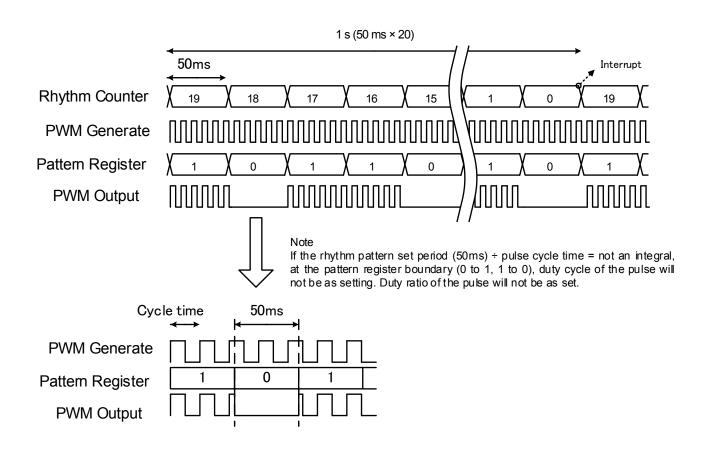


Figure 4-19 PWM Rhythm Function

4.7. ADC

4.7.1. Features

TC35679 has 6 ch of 10 bits ADCs for battery monitoring, analog inputs from external sensors, for example. The ADC has the following features.

- > 5 ch for analog inputs (shared with GPIO pins)
- > 1 ch for VBAT voltage monitor
 - Note: The reference input is internally connected to VBAT, and the analog input is to built-in VDDCORE2 output. Please refer to 4.7.2 for how to calculate voltage value.
- Maximum conversion rate: 1 MS/s

4.7.2. Descriptions

The ADC has 10 bits conversion accuracy and can work for input voltages from 0 V to 3.6 V (VBAT). It has 6 ch of analog inputs, and the ch0 is connected to VDDCORE2 output, and the ch1 to ch5 are shared with GPIO pins.

When a battery is used as power source, the reference voltage can slide over time because the battery is connected as reference voltage. In that case, the VDDCORE2 output voltage connected to ch0 can be used as a reference voltage. The input voltage to ch1 to ch5 is converted by the reference voltage of ch0 and the converted value is used to calculate a correct digital value by the CPU. The following shows the conversion method of the input voltage.

Voltage A at time T can be calculated as follows

- (1) VDDCORE2 output voltage (VDDCORE2) on Ch0 should be converted by the ADC. The converted digital value is X.
- (2) The analog signal on Ch1 is converted and the converted digital value is Y.
- (3) When the absolute value of the analog signal on Ch1 is defined as A(V), VDDCORE2 (V) / A(V) = X / Y. So,

 $A(V) = VDDCORE2(V) \times Y / X$

Calculation example:

Suppose ch0 (for ex. VDDCORE2 output is 1.1 V) is converted to 0x0134, and ch1 (measurement target) is converted to 0x0188, the absolute voltage at ch1 A (V) is given by $1.1 \times 0x0188 / 0x0134 = 1.1 \times 392 / 308 = 1.4$ (V).

Figure 4-20 shows conceptual of voltage conversion.

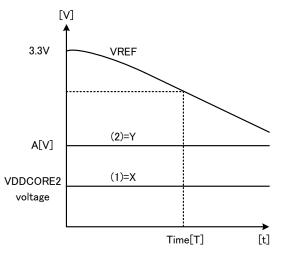


Figure 4-20 Voltage conversion concept

The ADC converts input voltage of ch selected by register settings. When a conversion has finished, the CPU detects it by the interrupt or register polling, and then reads the conversion results. The maximum sampling rate depends on software load on the CPU.

Hexadecimal number: 0xABC

Note: The numerical values are expressed as follows.

4.8. IC Reference Clock Interface

4.8.1. Features

TC35679 has the following features for IC reference clock interface.

Clock frequency: 26 MHz (please adjust the accuracy to < 50 ppm at the temperature in use)

TC35679 doesn't require external feedback resistors and load capacitor because it has an internal feedback resistor and capacitor array between XOIN and XOOUT. Please adjust capacitor array based on PCB layout and assembly if necessary within the range of the crystal's specification.

4.8.2. Crystal oscillator connection example

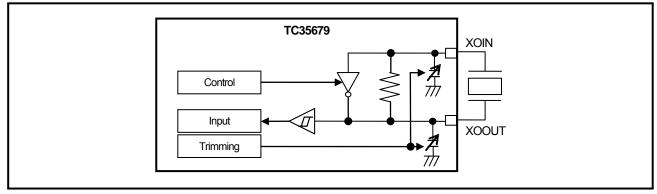


Figure 4-21 Crystal oscillator connection example

4.9. Sleep Clock Interface

TC35679 has the following features for sleep clock interface.

- Crystal oscillator can be connected.
- Clock frequency: 32.768 kHz (please adjust the frequency accuracy to < 500 ppm at the temperature in use)

Crystal oscillator is connected between SLPXOIN pin and SLPXOOUT pin. TC35679 doesn't require external feedback resistors and load capacitor because it has an internal feedback resistor and capacitor array between SLPXOIN pin and SLPXOOUT pin. Please adjust capacitor array based on PCB layout and assembly if necessary within the range of the crystal's specification. When an external oscillator is connected, connect it to SLPXOIN and SLPXOOUT should be connected to the GND. When oscillator is not used and do not supply a clock from the outside, these pins need to be connected to the GND.

4.9.1. Crystal oscillator connection example

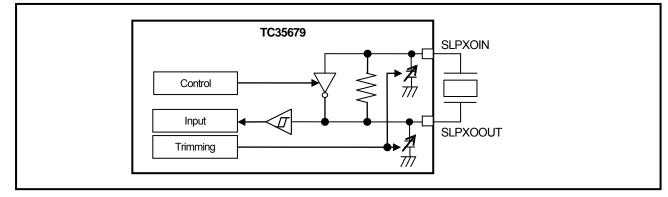


Figure 4-22 Crystal oscillator connection example

4.9.2. External oscillator connection example

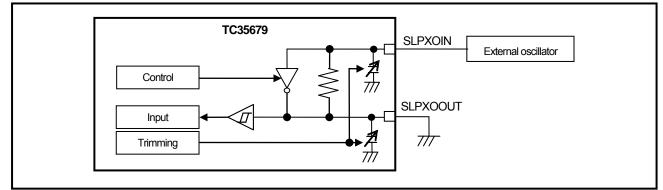


Figure 4-23 External oscillator connection example

5. Electric Characteristics

5.1. Absolute Maximum Ratings

Absolute maximum ratings must not be exceeded even for a moment. Voltages, currents, and temperatures that exceed the absolute maximum ratings can cause break-downs, degradations, and damages not only for ICs but also for other components and boards. Please make sure application designs not to exceed the absolute maximum ratings in any situation.

Items		Rat	Linit		
items	Symbols (Power supply system)	Min	Max +3.9 VDDIO + 0.3 (Note2) VDDIO + 0.3 (Note2) +10 +6	Unit	
Power supply	VBAT VDDIO (Note1)	-0.3	+3.9	V	
Input voltage	V _{IN}	-0.3	VDDIO + 0.3 (Note2)	V	
Output voltage	V _{OUT}	-0.3	VDDIO + 0.3 (Note2)	V	
I/O pin Input current	I _{IN}	-10	+10	mA	
Input power	RFIO	—	+6	dBm	
Storage temperature	Tstg	-40	+125	°C	

Table 5-1 Absolute maximum ratings (VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)

Note1: It is not supposed that VBAT is grounded while VDDIO is supplied. It can trigger current path from VDDIO to VBAT through internal circuitry, and may cause degradations and break-downs.

Note2: Keep VDDIO + 0.3 V < 3.9 V.

5.2. Operating Conditions

TC35679 can operate normally with proven quality under the operating ranges. Any diversion from the operating ranges may cause false operation. Thus, please make sure application design to comply these operating ranges.

(VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)									
		Symbols							
	Items	(Pin names,	Min	Тур.	Max	Unit			
		conditions)							
	VBAT Operating Voltage1(Note1)	VBATopr1	1.80	3.00	3.60	V			
Power supply	VDDIO Operating Voltage(Note2)	VDDIOopr	1.80	3.00	3.60	V			
	VDDCORE Voltage(Note2)	VDDCORE1/ VDDCORE2	_	1.1 / 1.2 (Note3)		V			
	RF frequency	Fc	2400	—	2483.5	MHz			
	Neak fragmancias	Reference clock Fck	25.99870	26.00000	26.00130	MHz			
L L	Clock frequencies	Sleep clock fslclk	32.751616	32.768000	32.784384	kHz			
	Ambient temp.	Та	-40	+25	+85	°C			

Table 5-2 Operating conditions (VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)

Note1: The VBAT pin has low voltage detection function and needs more than the minimum voltage of the VBATopr1 at the boot up.

Note2: Please refer to other documents (application note) for our connection examples.

Note3: During RF block operation and 26 MHz operation of CPU, this voltage is 1.2 V (typ.).

In other operation it becomes 1.1 V (typ.).

5.3. DC electric characteristics

5.3.1. Current Consumption (Design value)

This section shows current consumption. When the operating temperature (Ta) is 25°C, and the operation of each power supply pin is in the recommendation connection state of our company, the current consumption is an average value.

(VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)									
ltonoo	Cumpholo	Conditions	Pins	Ratings			Linit		
Items	Symbols	Conditions	(Note)	Min	Тур.	Max 	Unit		
Disitel exerction	IDD _{DIG}				0.7				
Digital operation	(Active1)	—		_	0.7	_			
RX	IDD _{RX}		VBAT		3.3		mA		
RA.	(Active2)	—	VDAI		3.5	_	ШA		
ТХ	IDD _{TX}	Output Power=			3.3				
IA	(Active3)	0 dBm			3.3				
		26 MHz crystal oscillator disabled							
Low power mode	IDDS1	32 kHz crystal oscillator enabled			1.8				
With Connection	(Sleep)	When 144 KB-RAM retention is			1.0				
		performed							
		26 MHz crystal oscillator disabled	VBAT						
Low power mode	IDDS2	32 kHz crystal oscillator enabled	VDAI		1.3		μA		
Without Connection	(Backup)	When 64 KB-RAM retention is			1.5				
		performed							
Low power mode	IDDS	26 MHz crystal oscillator disabled			0.05				
Without Connection	(Deep Sleep)	32 kHz crystal oscillator disabled			0.05				

Table 5-3 Current consumption (VBAT = VDDIO1=VDDIO2 = 3.0 V) (VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)

Note: Current consumption of IO part in Active operation can be changed by buffer setting.

Table 5-4 shows DC electric characteristics for each pin at 25°C ambient temperature.

Table 5-4 DC Electric Characteristics (VBAT = VDDIO1= VDDIO2 = 3.0 V))
---	---

		Con	dition		-	Rating			
Item	Symbol	I/F Voltage	Other Condition	Measuring Pin (Note 1)	Min	Тур.	Max	Unit	
High Level Input Voltage	VIH	3.0 V	LVCMOS	VDDIO	0.8×VDDIO	_	—	V	
Low Level Input Voltage	VIL	3.0 V	LVCMOS	VDDIO	_	_	0.2×VDDIO	V	
High Level	IIH		Pull-down Off		-10	—	10		
Input Current	VDDIO =	Pull-down On	VDDIO	10	_	200			
Low Level	ш	Input Voltage of each pin	Pull-up Off	VIDIO	-10	_	10	μA	
Input Current	nput Current IIL F	Pull-up On		-200	_	-10			
High Level Output Voltage	VOH	3.0 V	IOH = 1 mA	VDDIO	VDDIO-0.6	_	_	V	
Low Level Output Voltage	VOL	3.0 V	IOL = 1 mA	VDDIO	_	_	0.4	V	
External 32 kHz Clock	VIH SLPCLK	3.0 V	_	SLPXOIN	0.8×VDDIO	_	_	V	
Input level (Note2)	VIL SLPCLK	3.0 V		SLPXOIN	_	_	0.2×VDDIO	V	

Note1: Please refer to Table 2-4 for power supply line for each pin. It shows the power supply system of each functional pin.

Note 2: External oscillator is used for this case instead of crystal oscillator.

5.4. Built-in Regulator Characteristics

(VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)

ltem	Symbol Pin names and conditions		Ratings			Unit	
llem	Symbol		Min Typ. Max	Unit			
	Vout1	VDDCORE1/		1.1 / 1.2	—	V	
Output voltages	VOULT	VDDCORE2		(Note)		v	

Note: During RF block operation and 26 MHz operation of CPU, this voltage is 1.2 V (typ.).

In other operation it becomes 1.1 V (typ.).

5.5. ADC Characteristics

Table 5-6 ADC characteristics (VBAT = 1.8 to 3.6 V) (VSSX=VSSDC=VSSRFIO=VSSA=VSSD1=VSSD2=0 V)

Item	Symbol	Condition		Ratings		
licin	Symbol	Condition	Min	Тур.	Max	Unit
Analog reference voltage	VREFH	—	1.8	3.0	3.6	V
Analog input voltage	VAIN		VSSD	_	VREFH	V

5.6. RF Characteristics

The following conditions are applicable unless otherwise specified.

- ➤ Ta = 25°C
- > VBAT = 3.0 V
- > fx'tal = 26 MHz (Frequency accuracy is adjusted to ±2 ppm at normal temperature)
- > PAOUT=0 dBm

Table 5-7, Table 5-8 shows RF receiving characteristics and RF transmitting characteristics based on Bluetooth[®] Core Spec. V4.2 low energy.

About some the characteristics data here are design values.

Toot Hore	Deskat	Packet bit ch.		Condition			Spec.	1.1-24		
Test Item	Packel Dil		cn.			Min	Тур.	Max	Unit	
Output Power	255 octets	0,12, PRBS9 19,39 -		peak		_	_	Pavg+ 3 dB	dBm	
	001013		19,59	ave	erage	—	0	_		
				-5	MHz	_	-60	-30		
				-4	MHz	_	-55	-30		
				-3	MHz	_	-53	-30		
In-band Emissions	255	PRBS9	0,12, 19,39	-2	MHz	_	-48	-20	dBm	
	octets			2	MHz	_	-50	-20	UDITI	
				3	MHz	_	-53	-30		
				4	MHz	_	-56	-30		
				5	MHz	_	-60	-30		
		11110000	0.40	Δf1avg (11110000)	225	249.3	275	kHz	
Modulation Characteristics		10101010	0,12, 19,39	Δf2max	k (99.9 %)	99.9	100	_	%	
Characteristics	001013	_	10,00	∆f2avç	g /∆f1avg	0.8	0.90	-	Ratio	
Carrier frequency	255	10101010		average			4.4	_		
offset (CFO)	octets	10101010		w	vorst	-150	_	150	kHz	
Carrier frequency	255	10101010	0,12,	Absolute	emaximum	_	4.9	50	kHz	
drift	octets		19,39							
Carrier frequency drift Rate	255 octets	10101010		Absolute maximum		_	4.9	20	kHz/50 μs	

Table 5-7 RF Characteristics

Test Item	Sub Item	Packet	bit	ch.	Condition	Min	Тур.	Max	Unit
Rx Sensitivity	_	37 octets	_	0,12, 19,3	PER=30.8 % at 1500 packets with dirty	_	-93.5	_	dBm
					≤ -7 MHz		-38 or less	_	
					-6 MHz	—	-32	_	
					-5 MHz	—	-26	_	
					-4 MHz	_	-30	_	
					-3 MHz	_	-32	_	
C/I and Receiver	PER=30.8 %		D wave: PRBS9	0,2,12,	-2 MHz	—	-35	_	dB
Selectivity	at 1500	255 octats	255 octets U wave: GFSK PRBS15	U wave: 19,37, GFSK 39	-1 MHz	_	-2	_	
Performance	packets with dirty	200 Octets			0 MHz	—	8	_	
1 onormanoo					1 MHz	—	-2	_	
					2 MHz	—	-30	_	
					3 MHz	—	-38	_	
					4 MHz	—	-40	_	
					5 MHz	—	-44	—	
					≥6 MHz	_	-38 or less	_	
	— 255 octets		D wave:		30-2000 MHz	-30		_	
Blocking		PRBS9 U wave: CW	12 2484-2997 MI	2003-2399 MHz	-35		_	dBm	
Performance				2484-2997 MHz	-35	—	_	abiii	
				3000 M-12.75 GHz	-30	—	_		
	1500 packets 255 octets un-modulation				-4 MHz				
Intermodulation Performance		0,12, 19,39	+4 MHz	30.8	0	—	%		
Maximum input signal level	PER	255 octets	PRBS9	0,12, 19,39	-10 dBm	30.8	0	_	%
PER Report Integrity	PER	255 octets	PRBS9	0,12, 19,39	-30 dBm	50	50	65.4	%

Table 5-8 RF Characteristics

Note: C/I characteristic and blocking characteristic has the relief specs of the logo attestation test of Bluetooth[®] maybe applied. The blocking characteristic measures D wave as 12 ch.

5.7. AC Interface Characteristics (Design value)

5.7.1. UART Interface

Table 5-9 UART Interface AC characteristics

Symbols	Items	Min	Тур.	Max	Unit
tCLDTDLY	Transmit Data ON from CTSX Low level	192	_	_	ns
tCHDTDLY	Transmit Data OFF from CTSX High level			2	byte
tRLDTDLY	Received Data ON from RTSX Low level	0			ns
tRHDTDLY	Received Data OFF from RTSX High level			8	byte

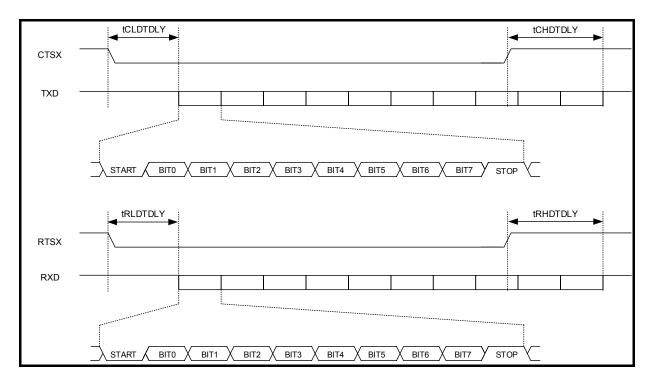


Figure 5-1 UART Interface Timing Diagram

5.7.2. I²C Interface

5.7.2.1. Normal Mode

Table 5-10 I ² C Interface Normal mode AC Characteristics
--

Symbols	Items	Min	Тур.	Max	Unit
tDATS	Data setup time	250	_	—	ns
tDATH	Data hold time	300	_	_	ns
tDATVD	Data validity period	_	_	3450	ns
tACKVD	ACK validity period	_	_	3450	ns
tSTAS	Restart condition setup time	4700	_	_	ns
tSTAH	Restart condition hold time	4000	_	_	ns
tSTOS	Stop condition setup time	4000	_	_	ns
tBUF	Bus open period from stop condition to start condition	4700	_	_	ns
tr	Rise up time	_	_	1000	ns
ťf	Fall down time	_	_	300	ns
tHIGH	Serial clock period of High	4000	_	_	ns
tLOW	Serial clock period of Low	4700	_	_	ns
Cb	Bus load capacitance	_	_	400	pF

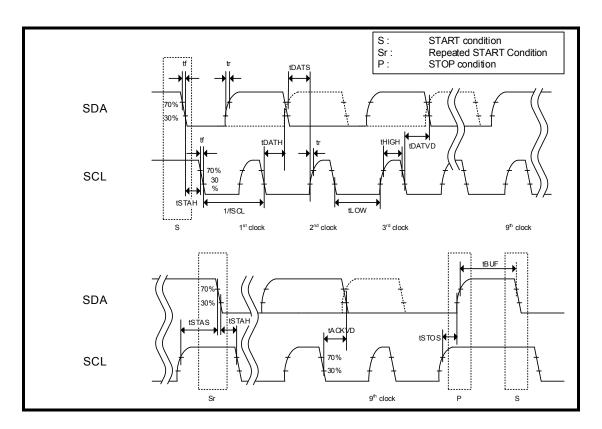


Figure 5-2 I²C Interface Normal mode Timing diagram

5.7.2.2. Fast mode

Symbols	ltems	Min	Тур.	Max	Unit
tDATS	Data setup time	100		_	ns
tDATH	Data hold time	300	_	_	ns
tDATVD	Data validity period	—	—	900	ns
tACKVD	ACK validity period	—	—	900	ns
tSTAS	Restart condition setup time	600	_	_	ns
tSTAH	Restart condition hold time	600	_	_	ns
tSTOS	Stop condition setup time	600	—	—	ns
tBUF	Bus open period from stop condition to start condition	1300	_	_	ns
tr	Rise up time	20 + 0.1 Cb	_	300	ns
ť	Fall down time	20 + 0.1 Cb	_	300	ns
tSP	Spike pulse width that can be removed	0	—	50	ns
tHIGH	Serial clock period of High	—	1423	—	ns
tLOW	Serial clock period of Low	—	1423	_	ns
Cb	Bus load capacitance	—	_	400	pF

Table 5-11 I²C Interface Fast mode AC Characteristics

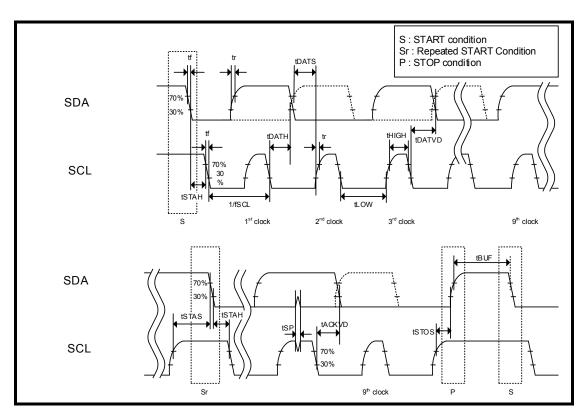


Figure 5-3 I²C Interface Fast mode Timing diagram

5.7.3. SPI Interface

Table 5-12 SPI Interface

Symbols	Items	Min	Тур.	Max	Unit
tSPICLKCYC	SPI clock cycle	154	_	_	ns
tSPICLKHPW	SPI clock high pulse width	77	_	_	ns
tSPICLKLPW	SPI clock low pulse width	77	—	—	ns
tSPICSS	SPI chip select setup time	38	—	—	ns
tSPICSH	SPI chip select hold time	77	—	—	ns
tSPIIW	SPI transfer idle pulse width	54		_	ns
tSPIAS	SPI address setup time	38	_	—	ns
tSPIAH	SPI address hold time	77		_	ns
tSPIDS	SPI data setup time	38		_	ns
tSPIDH	SPI data hold time	77	_	_	ns

Note: SPI Interface operates on the basis of 1/n frequency of half the frequency of ARM[®] Cortex[®]-M0 core clock (6.5 MHz for 13 MHz core clock)

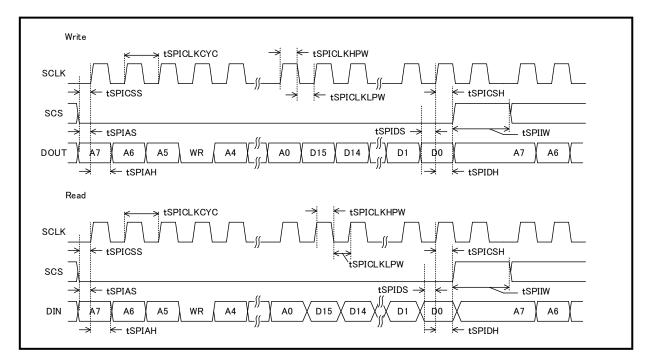


Figure 5-4 SPI Interface timing diagram

6. System Configuration Example

An example of system configuration is shown in the following figures.

6.1. In case of Host CPU connection

- Host interface=UART and 26 MHz Reference Clock= XOSC Connection.
- XOSC (32.768 kHz) of the dotted line enclosure is unnecessary when the external input (HOST common use) is chosen.

The connections of GPIO and SWD are the example of when they are not in use.

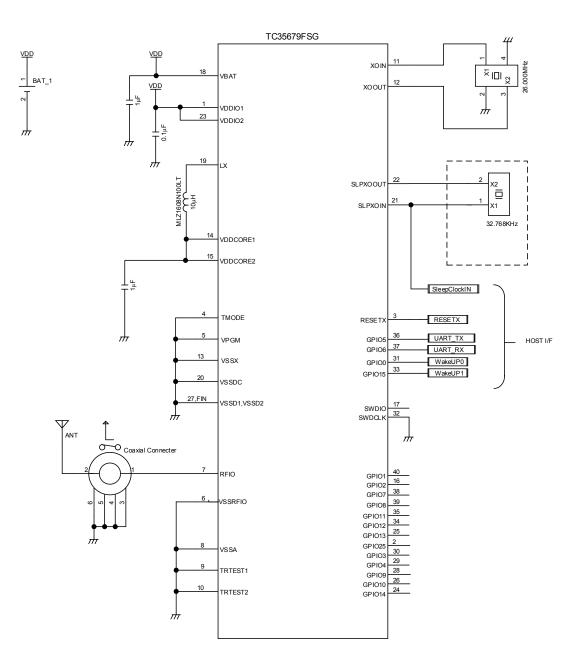


Figure 6-1 Example of TC35679FSG system configuration (HOST CPU connection)

6.2. In case of Standalone

- XOSC (32.768 kHz) of the dotted line enclosure is unnecessary when the external input is chosen.
- The connections of GPIO and SWD are the example of when they are not in use.

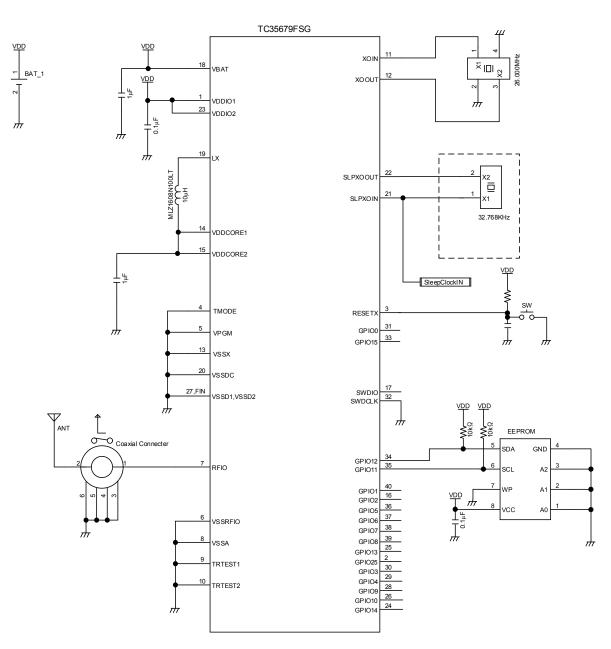
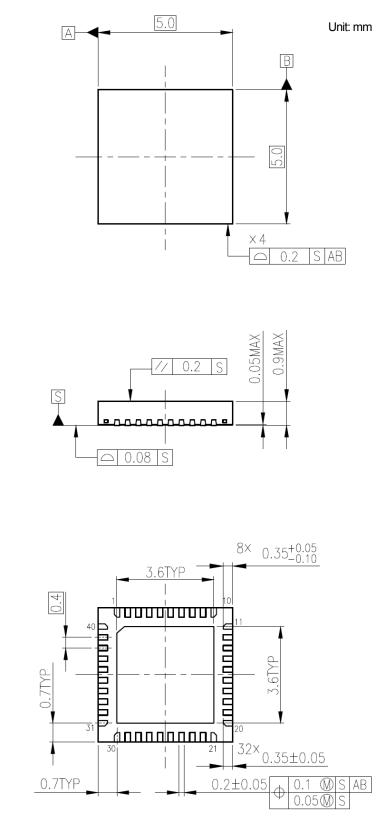


Figure 6-2 Example of TC35679FSG system configuration (Stand-alone)

7. Package outline

7.1. Outline dimensional drawing TC35679FSG-002 (P-VQFN40-0505-0.40-005/F01)



Weight: 0.068 g (Typ.)

Figure 7-1 Package outline (P-VQFN40-0505-0.40-005/F01)

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