

### STEVAL-IHM040V1

# BLDC/PMSM driver demonstration board based on STM32 and the SLLIMM™ nano

Data brief

#### **Features**

- Extended AC input mains range: 115 or 230
  VAC nominal at 50/60 Hz, or DC input voltage between 150 and 350 VDC
- Output current: 0.5 A<sub>RMS</sub> to the motor
- Power stage: 3-phase inverter bridge implemented using the STGIPN3H60 SLLIMMnano intelligent power module
- RoHS compliant

#### **Description**

The STEVAL-IHM040V1 is a 3-phase permanent magnet brushless motor driver designed to drive a motor using either the six step or field oriented control (FOC) commutation technique. The board can operate from an AC mains of either 115 or 230  $V_{AC}$  nominal at 50/60 Hz, or from a DC input voltage between 150 and 350 VDC. The board can supply a continuous output current of 0.5  $A_{BMS}$  to the motor.

The circuit consists of three main blocks. The first is the digital control block, which uses the STM32F100C8T6 microcontroller to implement the control algorithms and to generate the control signals for the power stage. The main outputs of the control block are the signals for the power stage.

The second block is the power stage, a 3-phase inverter bridge implemented using the STGIPN3H60 SLLIMM-nano intelligent power module. The SLLIMM includes the 6 IGBTs, gate drivers and level shift required to interface the logic signals from the digital control to the motor terminals. The SLLIMM also provides a hardware overcurrent shutdown and an op-amp used to scale and bias the current sensing.



The third block is the power supply, which employs the VIPER16 to convert the high voltage DC bus to a regulated 15 V supply that supplies the SLLIMM and analog circuitry on the board. The 15 V supply also supplies an L78L33 linear regulator that provides the 3.3 V logic supply for the microcontroller.

Two firmware control programs are available, one for six steps and one for FOC, which run on the same hardware platform.

Schematic diagrams STEVAL-IHM040V1

### 1 Schematic diagrams

Figure 1. SLLIMM-based BLDC driver (1 of 3)

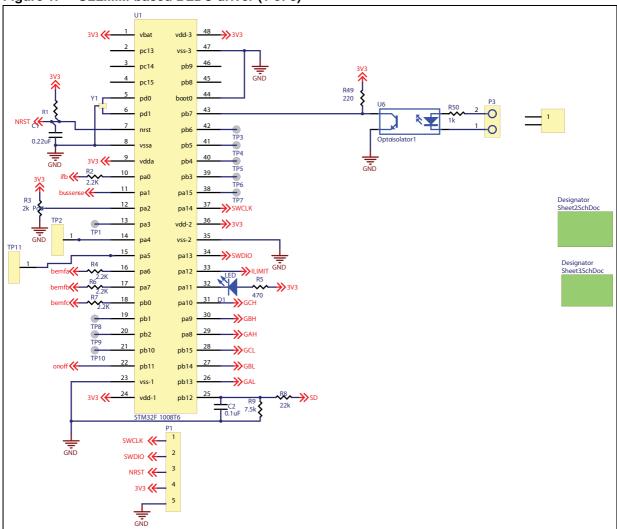


Figure 2. SLLIMM-based BLDC driver (2 of 3) >>> dcbus 220uF 200V R10 C3 -R11≥ 470k W1 2 100k R12 >>> bussense **Mating Connector** D2 4 R13 100k C5 - 220uF 200V -R14 J1A 6A 400V \_\_C6 47nF 8.2k <del>\_</del> GND U2 8 out in gnd gnd gnd gnd 5 NC NC L78L33 GND R15 R16 100 100 1 mH Inductor 16 dcbus(<del>C</del> drain gnd <del>>>></del>15∨ STTH1R06A 100uF 35V 15 2 C25 drain gnd STTH1R06A 1.0uF 3 drain nc **D**4 13 4 C9 1.0uF C8 0.1uF drain na GND GND 12 R17 2.8K R18 10K Vdd nc R19 11 nc lim 0.01uF **₩** 10 fb nc C11 8 R20 9 0.1uF

comp

VIPer16

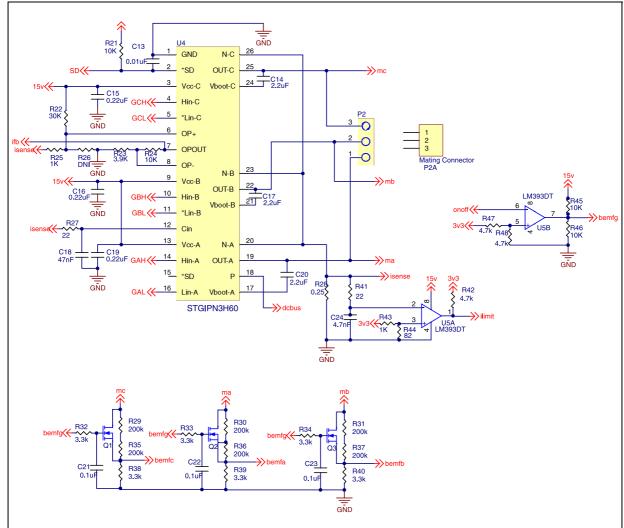
10K

2.2nF C12

nc

Schematic diagrams STEVAL-IHM040V1

Figure 3. SLLIMM-based BLDC driver (3 of 3)



STEVAL-IHM040V1 Revision history

# 2 Revision history

Table 1. Document revision history

| Date        | Revision | Changes          |
|-------------|----------|------------------|
| 19-Dec-2012 | 1        | Initial release. |

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