

## CCM PFC controller with high voltage startup



#### **Features**

- · Peak current mode CCM-operated
- · 800 V high voltage startup with integrated input voltage sensing
- · Active input filter capacitor discharge
- Proprietary multiplier "emulator" with minimum THD of line current in all operating conditions (CCM and DCM)
- · Extremely few external components
- Protections: feedback loop failure, OVP, OCP, inductor saturation, brown-in, brownout (compliant to medical SMPS standards)
- · Inductor current sense
- Disable and low consumption function
- · In-rush current monitoring
- Soft-start for smooth startup
- 1.2% (@ Tj = 25 °C) internal reference voltage
- 65 kHz (A version) and 130 kHz (B version) switching frequency
- SO8 package

## **Application**

- · PFC pre-regulators for:
  - IEC61000-3-2 and JEIDA-MITI compliant SMPS in excess of 1 kW
  - Desktop PC, server, web server, game console
  - High power LED luminaries
  - Industrial and medical SMPS according to IEC 60601-1-2

Product status link
L4985
L4985A
L4985B
L4985ATR
L4985BTR

Product summary					
Order codes	Packaging				
L4985A		Tube			
L4985B		Tube			
L4985ATR	SO-8	Tape and reel			
L4985BTR		Tape and reel			

#### **Description**

The L4985 is a peak current-mode PFC controller for boost converter with a proprietary multiplier "emulator" which in addition to the innovative THD optimizers guarantee very low Total Harmonic Distortion (THD) performance in all operating conditions. The device comes in a pin SO package and offers a high performance/low-component count solution for CCM-operated boost PFC pre-regulators in EN61000-3-2 and JEIDA-MITI compliant applications, in a power range that spans from few hundred W to some kW.

The device, thanks to a proprietary off-time modulator, operates in quasi-fixed frequency in all operating conditions. Two options are available, 65 kHz for A and 130 kHz for B.

The 800V high voltage start-up block includes also the circuitry to discharge the X-capacitors of the EMI filter to a safe level. This allows the unit to meet safety regulation (such as IEC 61010-1 or IEC 62368-1) without using the traditional discharge resistor in parallel to the X-capacitors.

The device features low consumption and disable functions allowing usage in applications supposed to comply even with the latest energy saving requirements issued by Energy Star, the Department of Energy (DoE) in the United States, the European Code of Conduct, the European Union's Ecodesign Directive, and other guidelines.





In addition to an overvoltage protection able to keep the output voltage under control during transient conditions, the IC is provided also with a protection against feedback loop failures or erroneous settings and boost inductor saturation. The brownout protection function allows to design medical equipment according to the latest regulations driven by IEC 60601-1-2 which requires the output regulation in case of mains dips lasting up to 500 msec. Soft-start limits the peak current.

The totem-pole output stage, capable of 0.7 A source and 1.5 A sink current, is suitable for big MOSFET or IGBT drives.

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GND



# 1 Block diagram and typical application

CS VCC HV

HVON XCAP

SEE O VCS OCC HV

NC

SSO VCS OCC HV

NC

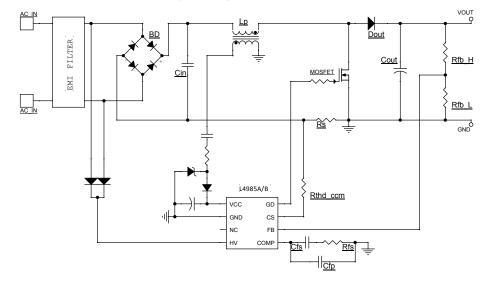
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Figure 1. Block diagram

Figure 2. Typical application

OVP, FBD , IDLE

OFF-TIME modulator



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# 2 Pin connection and functions

FΒ

5

Figure 3. Pin connection (top view)

Table 1. Pin description

No.	Name	Function
1	VCC	Supply voltage. The internal high voltage start-up generator charges an electrolytic capacitor connected between this pin and GND as long as the voltage on the pin is below the start-up threshold of the IC, after it is disabled and the chip turns on. A bypass capacitor to GND has to be placed close to the pins to get a clean bias voltage.
2	GD	Gate driver output. The output stage is able to drive power MOSFETs and IGBTs; it is capable of 0.7 A source current and 1.5 A sink current (typical values).
3	GND	IC ground. Current return for both the signal/bias part of the IC and the gate driver current. All of the ground connections of the bias components should be tied to a track going to this pin and kept separate from any pulsed current return.
		Current sense input. The inductor current is sensed through a resistor $R_S$ on the current return side. The resulting negative voltage is applied to this pin and compared to an internal sinusoidal-shaped reference to determine the turn-off instant of the external power switch. The pin is equipped with an internal current generator (sourced current during power switch on-time); it can be used, by simply adding a series resistor ( $R_{THD\_CCM}$ ) for improved THD in CCM operation.
4	CS	If the voltage on the pin goes below $V_{CS\_OCP1}$ (-0.49 V typ.) the internal overcurrent comparator is triggered and terminates the conduction cycle of the external power switch before the normal PWM circuit does. In this way, the peak inductor current is limited at a maximum of 0.49/R <sub>S</sub> .
		A second overcurrent level set at $V_{CS\_OCP2}$ (-0.75 V typ.) detects abnormal current values (e.g. due to boost inductor saturation) and, on this occurrence, activates a safety procedure that immediately stops the converter activity until the current level reaches the zero-current threshold $V_{CS\_ZCD}$ (-10 mV typical value). It allows safe operations also during current surges occurring at power-up or after a mains dip or missing cycle; in fact it allows switching start/restart only when the overcurrent event is definitively over.
		Inverting input of the trans-conductance Error Amplifier (OTA).
5	FB	The information on the output voltage of the PFC regulator is fed into the pin through a resistor divider so that its voltage is proportional to the instantaneous value of the high voltage bus ( $V_{BULK}$ ). Under steady-state conditions the voltage on pin sits at the internal reference of the error amplifier (VREF = 2.5 V). If the voltage exceeds the steady-state value by 7% ( $V_{FB} > V_{FB\_S}$ ), e.g. due to an output voltage overshoot, the switching activity is stopped until $V_{FB} < V_{FB\_R}$ (2.55V typ.).
		If the voltage at the FB pin is below V <sub>FB_FF/EBM</sub> (0.5 V typ.) either a failure of the output divider is assumed or the device is externally forced in burst-mode operation. In both cases the PFC controller is stopped with low consumption. See Section 5.7 Idle operation (external burst-mode function) and Section 5.9.6 Feedback failure detection for further details.

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No.	Name	Function
6	COMP	Output pin of the trans-conductance Error Amplifier (OTA). A compensation network is placed between this pin and GND to allow stability of the control loop and ensure high PF and THD. To avoid uncontrolled rise of the output voltage at light or zero load, when $V_{COMP} < V_{COMP\_S}$ (1 V typ. Burst Mode condition) the gate driver pin (GD) is forced low and the switching activity is stopped. If the Burst Mode condition is triggered when GD is high, the system is allowed to complete the current on-time and the system stoppage takes place after GD falling edge.  The pin can be also used to disable the device by forcing $V_{COMP} < V_{COMP\_DIS}$ (0.7 V typ.) by means of
		an external pull-down active network.
7	N.C.	High voltage spacer. This pin is not internally connected to isolate the high voltage section and ease compliance with safety regulations (creepage distance) on the PCB.
		High voltage start-up generator input / AC voltage sensing input. The pin, able to withstand 800 V, has to be connected to the AC side of the input bridge via a pair of diodes (1N400x type) to sense the AC input voltage. If the voltage on the pin is higher than $V_{HV\_START}$ (29 V typ.), an internal pull-up circuit charges the capacitor connected between the pin VCC and GND. Initially the current is low for safety in case of a shorted VCC, and then it goes to the normal level as far as the VCC pin reaches the start-up threshold ( $V_{CC\_ON}$ ). The generator is re-enabled when the voltage on the VCC pin falls below the UVLO threshold ( $V_{CC\_OFF}$ ).
8	HV	The pin is used also to sense the AC voltage, which is used by the AC brownout, the input voltage feedforward and the THD-CCM optimizer functions.
		An internal logic circuit detects that the unit has been detached from the power line; if this event occurs then, the HV pin sinks a current to discharge the X-capacitors of the EMI filter to a safe level. This allows the unit to meet safety regulations (such as IEC 61010-1 or IEC 62368-1) without using the traditional discharge resistor in parallel to the X-capacitor, thus saving the associated power losses and enabling ultra-low consumption in standby conditions. In case an AC brownout condition is detected the internal generator is alternatively turned on and off and, as a consequence, the voltage at VCC pin cycles between the start-up threshold and the UVLO threshold.

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# 3 Electrical data

# 3.1 Absolute maximum ratings

Table 2. Absolute maximum ratings

Symbol	Pin	Parameter	Value	Unit
VCC	1	Supply voltage	-0.3 to 30	V
ICC	1	Maximum supply current	0 to 25	mA
GD	2	Gate driver	-0.3 to VCC	V
CS	4	Current sense	-10 to 3.6	V
FB	5	Input feedback ( <sub>IFB</sub> < 1 mA)	-0.3 to self-limited	V
COMP	6	OTA output	-0.3 to 6	V
HV	8	Line voltage input (referred to GND)	-1 to 800	V

Table 3. Recommended operating conditions.

Symbol	Pin	Parameter	Min.	Max.	Unit	Remarks
VCC	1	IC supply voltage	-0.3	24.5	V	Internal clamp at 24.5 V min.
CS	4	Current sense input	-10	3.3	V	
FB	5	Feedback input	-0.3	3.0	V	Internal clamp at 3 V min.
COMP	6	OTA output	-0.3	5.3	V	Values referred to an externally forced condition
HV	8	High voltage input	-1	600	V	

## 3.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Max. value	Unit
R <sub>th j-amb</sub>	Thermal resistance, junction-to-ambient	150	°C/W
P <sub>tot</sub>	Power dissipation @Tamb = 50 °C	0.65	W
Tj	Junction temperature operating range	-40 to 150	°C
T <sub>stg</sub>	Storage temperature	-55 to 150	°C

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# 4 Electrical characteristics

 $\rm T_{j}$  = -25 to 125 °C,  $\rm V_{CC}$  = 15 V,  $\rm C_{GD}$  = 1 nF unless otherwise specified.

Table 5. Electrical characteristics

Symbol	Parameter Test Condition		Min.	Тур.	Max.	Unit
SUPPLY VOLTAGE						
V <sub>CC</sub>	Operating range	After turn-on	10		24.5	V
V <sub>CC_ON</sub>	Turn-on threshold	Voltage rising <sup>(1)</sup>	13	14	15	V
V <sub>CC_OFF</sub>	Turn-off threshold	Voltage falling (1)	8.5	9.0	9.5	V
Vcc_hvstup_ovp	Turn-on threshold of HVSTUP in OVP state	Voltage falling <sup>(1)</sup>		11.5	12.2	V
V <sub>Z</sub>	$V_{CC}$ clamp voltage $I_{VCC} = 20 \text{ mA}^{(2)}$		24.5	26	27	V
SUPPLY CURRENT		'	1			
I <sub>START_UP</sub>	Start-up current	Before turn-on, V <sub>CC</sub> = 14 V		400	550	μA
		V <sub>FB</sub> < V <sub>FB_FF/EBM</sub>		0.6	0.8	mA
1.	Quiescent current	V <sub>FB</sub> = 2.5 V,		0.65	0.95	m 1
IQ	Quiescent current	V <sub>COMP</sub> < V <sub>COMP_S</sub>		0.65	0.85	mA
		V <sub>FB</sub> > V <sub>FB_S</sub>		0.65	0.85	mA
		L4985A, T <sub>ON</sub> =T <sub>ON_MIN</sub> <sup>(3)</sup>		2.2	2.8	mA
	Operating supply current	L4985A, HV*T <sub>ON</sub> = 1.3 ms <sup>(4)</sup>		3.8	4.7	mA
Icc		L4985B, T <sub>ON</sub> =T <sub>ON_MIN</sub> <sup>(3)</sup>		3.4	4.0	mA
		L4985B, HV*T <sub>ON</sub> = 0.65 ms <sup>(4)</sup>		4.6	5.5	mA
I <sub>DIS</sub>	Quiescent in disable	V <sub>COMP</sub> < V <sub>COMP_DIS</sub>		450	600	μA
HIGH-VOLTAGE STAR	RT-UP GENERATOR					
$V_{HV}$	Breakdown voltage	I <sub>HV</sub> < 100 μA	800			V
V <sub>HV_START</sub>	Start voltage	I <sub>VCC</sub> < 100 μA	22	29	40	V
V <sub>CC_SO</sub>	VCC switchover threshold		0.55	1	1.4	V
		V <sub>HV</sub> > 40 V, V <sub>CC</sub> < V <sub>CC_SO</sub>	0.7	1	1.3	mA
	ON-state charge current	V <sub>HV</sub> > 40 V,				
I <sub>HV</sub> ON	ON-state charge current	$V_{CC} > V_{CC\_SO}$	5	7	10	mA
		V <sub>FB</sub> < V <sub>FB_HVSTUPOFF</sub>				
V <sub>FB_HVSTUPOFF</sub>	Generator shutdown threshold at FB pin		1.65	1.75	1.85	V
T <sub>TOUT</sub>	Generator shutdown timeout	After V <sub>CC</sub> exceeds V <sub>CC_ON</sub> & 80 V <sub>FB</sub> < V <sub>FB_HVSTUPOFF</sub>		100	120	ms
I <sub>HV_OFF</sub>	OFF-state current consumption	V <sub>HV</sub> = 400 V		20	25	μA
AC BROWNOUT PRO	TECTION			I.		
V <sub>HVPK_BO</sub>	Brownout threshold	V <sub>HV</sub> peak voltage falling <sup>(1)</sup>	94	100	106	V
V <sub>HVPK_BI</sub>	Brown-in threshold	V <sub>HV</sub> peak voltage rising <sup>(1)</sup>	106	114	121	V
	Brownout debounce time		505	630	755	ms
T <sub>DB_ACBO</sub>	Brownout debounce time		505	630	755	

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Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
		First time V <sub>CC</sub> > V <sub>CC_ON</sub>	0.8	1	1.2	ms
T <sub>DB_ACBI</sub>	Brown-in debounce time		32	40	48	ms
C-CAPACITOR DISC	HARGE FUNCTION					
V <sub>HV_MIN</sub>	Peak residual voltage	I <sub>HV_DIS</sub> > 5 mA			45	V
I <sub>HV_DIS</sub>	Discharge current	V <sub>HV</sub> = 45 V	5			mA
T <sub>DECT_XCAP</sub>	Detection time		51	64	77	ms
ERROR AMPLIFIER						
		T <sub>j</sub> = 25 °C	2.47	2.5	2.53	V
$V_{REF}$	Voltage feedback input threshold	10 V < V <sub>CC</sub> < 24.5 V(1)	2.45		2.57	V
I <sub>FB</sub>	Input bias current	V <sub>FB</sub> = 0 to 3 V	-0.1	0	0.1	μA
V <sub>FBCLAMP</sub>	Internal clamp level	I <sub>FB</sub> = 1 mA	3.0	3.3		V
gm	Transconductance gain	V <sub>REF</sub> -150 mV < V <sub>FB</sub> < V <sub>REF</sub> +150 mV	160	200	240	μS
R <sub>O</sub>	Output impedance		5			МΩ
	Source current	V <sub>COMP</sub> = 3 V, V <sub>FB</sub> =1.9 V	0.7	1	1.45	mA
I <sub>COMP</sub>	Sink current	V <sub>COMP</sub> = 3 V, V <sub>FB</sub> =3.0 V	0.7	1	1.45	mA
	Upper saturation voltage	I <sub>SOURCE</sub> = 0.2 mA	5.0			
$V_{COMP}$	Lower clamp voltage	V <sub>FB</sub> = 3.0 V	0.8		0.9	V
OYNAMIC (D OVP)	and STATIC (S_OVP) OVERVOLTAGE					
	Burst mode threshold					
$V_{COMP\_S}$	S_OVP (Static OVP)	Voltage falling <sup>(1)</sup>	0.95	1.00	1.05	V
V	Restart threshold	Vallage vising(1)	1	1.05	1.1	V
V <sub>COMP_R</sub>	after S_OVP	Voltage rising <sup>(1)</sup>	1	1.05	1.1	V
$V_{FB\_S}$	D_OVP disable threshold	10 V < V <sub>CC</sub> < 24.5 V	2.595	2.675	2.755	V
$V_{FB\_R}$	Restart threshold after D_OVP	10 V < V <sub>CC</sub> < 24.5 V	2.44	2.55	2.65	V
DISABLE	_					
V <sub>COMP DIS</sub>	Disable threshold	Voltage falling <sup>(1)</sup>	0.65	0.7	0.75	V
V <sub>COMP_EN</sub>	Enable threshold	Voltage rising <sup>(1)</sup>	0.85	0.9	0.95	V
I <sub>COMP_DIS</sub>	Pull-up current at disable	· · · · · · · · · · · · · · · · · · ·	8	12	16	μA
CURRENT SENSING	· ·					-
		V <sub>CS</sub> = -0.5 V		15	21	μA
I <sub>CS</sub>	Leakage bias current	V <sub>CS</sub> = 0.235 V	7.5	10	14	μА
V <sub>CS OFS</sub>	CS level shifter offset	CS = 0 V	3	10	17	mV
V <sub>CS_GAIN</sub>	CS level shifter gain	C = -0.5 V	0.94	0.98	1.02	V/V
VCS_GAIN VCS_OCP1	1 <sup>st</sup> level overcurrent threshold	3 0.0 0	-510	-490	-470	mV
*CS_OCP1			-510	-430	-470	1110
T <sub>SS_OCP1</sub>	1st level OCP threshold ramp up time		104	130	156	ms
T <sub>BLK</sub>	Leading edge blanking	HV > 73 V rising	120	150	180	ns
· DLN	Loading odgo blanking	HV < 45 V falling	235	310	335	ns
td <sub>(H-L)</sub>	Delay to output				110	ns
V <sub>CS_OCP2</sub>	2 <sup>nd</sup> level overcurrent threshold		-0.80	-0.75	-0.70	V
V <sub>CS_ZCD</sub>	Zero current threshold		-15	-10	-5	mV

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Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
CURRENT SENSE D	ISCONNECTION			'		
V <sub>CSD</sub>	Current sense disconnection threshold	Voltage rising	165	200	235	mV
	Disconnection		8	10	12	
T <sub>CSD_DB</sub> debounce time			0	10	12	μs
QUIVALENT MULT	IPLIER					
IZ.	Equivalent multiplier gain	V <sub>HVPK</sub> < 200 V <sup>(1)</sup>	0.405	0.44	0.475	V/V
$K_M$	Equivalent manipher gam	V <sub>HVPK</sub> > 235 V <sup>(1)</sup>	0.092	0.10	0.108	V/\
THD CCM-OPTIMIZE	ER .					
K <sub>CCM</sub>			0.51	0.55	0.59	Н
EEDBACK FAILUR	E PROTECTION/EXTERNAL BURST	MODE (EBM)				
	Feedback failure protection	Voltage falling <sup>(1)</sup>	460	500	540	m۷
$V_{FB\_FF/EBM}$	(on FB) / External burst mode threshold	Hysteresis		50		m۷
T <sub>FF/EBM_DB</sub>	FFP/EBM debounce time		1.25	1.8	2.35	μs
	FB current during EBM	V <sub>FB</sub> < V <sub>FB_FF/EBM</sub>	70	100	135	μΑ
I <sub>FB</sub> _EBM	FB current at exit EBM	V <sub>FB_FF/EBM</sub> < V <sub>FB</sub> < V <sub>REF</sub>	0.75	1	1.25	m/
SWITCHING FREQU	ENCY					
F <sub>SW</sub>	Switching frequency (L4985A)	T <sub>ON</sub> = 9μs, V <sub>HVPK</sub> < 200 V		65	71	
		T <sub>ON</sub> = 3μs, V <sub>HVPK</sub> > 235 V	60			kH
	Switching frequency	T <sub>ON</sub> = 4.5µs, V <sub>HVPK</sub> < 200 V		130	142	
	(L4985B)	T <sub>ON</sub> = 1.5µs, V <sub>HVPK</sub> > 235 V	120			kH
MAXIMUM ON-TIME						
		L4985A	32	40	50	μs
T <sub>ON_MAX</sub>	Maximum on-time	L4985B	16	20	26	μs
MINIMUM OFF-TIME						-
		L4985A	0.75	1.0	1.35	μs
T <sub>OFF_MIN</sub>	Minimum off-time	L4985B	0.35	0.5	0.75	μs
GATE DRIVER						
		I <sub>sink</sub> = 200 mA			0.7	V
$V_{OL}$	Output low voltage	I <sub>sink</sub> = 5 mA			0.02	V
		15V <vcc<24.5 i<sub="" v,="">source = 5 mA</vcc<24.5>	11	12	13	V
V <sub>OH</sub>	Output high voltage	V <sub>CC</sub> = 9 V, I <sub>source</sub> = 5 mA	7.85			V
I <sub>srcpk</sub>	Peak source current			-0.7		Α
I <sub>snkpk</sub>	Peak sink current			1.5		Α
t <sub>f</sub>	Voltage fall time	V <sub>GD</sub> from 8 V to 1 V	3	7	15	ns
t <sub>r</sub>	Voltage rise time	V <sub>GD</sub> from 1 V to 8 V	5	10	15	ns
7	UVLO saturation	$V_{CC} = 0 \text{ V to } V_{CC \text{ ON}}, I_{sink} = 1 \text{ mA}$			1.1	V
	O VEO Saturation	VCC - O V TO VCC_ON, ISINK - I TITA			1.1	V

- 1. Parameters tracking each other.
- 2. The VCC pin is self-limited by an internal clamp when the device is in switching modality.
- 3. Equivalent to just before burst-mode condition.
- 4. Equivalent to full-load condition.

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## 5 Application information

## 5.1 Theory of operation

The L4985A/B implements a conventional peak current mode control, based on fixed-off-time (FOT) control technique, with some proprietary circuitries that permit to ideally achieve the same performance of the more complex/expensive average current mode control.

Referring to Figure 4, the power switch on-time  $(T_{ON})$  is programmed by the output voltage control loop comparing the current sense signal  $V_{CS}$  with the internal current reference  $V_{CS\_REF}$  in order to keep the VOUT regulation; whereas the power switch off-time  $(T_{OFF})$  is programmed by the "OFF-TIME modulator" circuitry in order to keep quasi-fixed the switching frequency FSW in all operating conditions (see "Section 5.1 OFF-time modulator" section for more details).

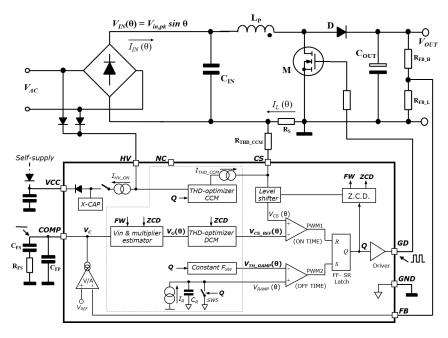


Figure 4. Control loop connections

The trans-conductance Error Amplifier V/A compares a portion of the output voltage  $V_{OUT}$ , brought at its inverting input externally available on pin FB via the resistor divider  $R_3$ - $R_4$ , with an accurate internal reference  $V_{REF}$  (2.5 V typ.) connected to the non-inverting input, and generates an error signal  $V_C$  proportional to their difference. If the bandwidth of the error amplifier, essentially determined by the frequency compensation network connected between pin COMP and ground, is narrow enough – typically below 20 Hz – and a steady-state operation is assumed, the  $V_C$  error signal available at pin COMP can be regarded as a DC level, at least as a first approximation. The  $V_C$  voltage is then used by the "Vin & multiplier estimator" circuitry that, based also on the FW and ZCD signals (see Figure 5 and Figure 6for more details), generates a voltage expressed by:

**Equation 1** 

 $V_G(\theta) = V_C K_1 \frac{V_{IN}(\theta)}{V_{OUT}}$  (1)

where  $K_1$  is the circuitry gain (constant term) and  $V_{IN}(\theta) = V_{in,pk} \sin \theta$  (with  $0 \le \theta \le \pi$ , as a result of the rectification operated by the input bridge) is the instantaneous line input voltage.

Equation 1 shows as the  $V_G(\theta)$  voltage is proportional to the  $V_{IN}(\theta)$  input voltage and to the  $V_C$  control voltage like in a standard current-mode PFC, but without using the standard multiplier block and without the AC line sensing.

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The  $V_G(\theta)$  voltage is then managed by the "THD-DCM optimizer" circuitry that acts as a simple gain  $(K_2)$  in CCM operation whereas in DCM operation opportunely shapes the  $V_G(\theta)$  voltage in order to achieve ideally sinusoidal input current.

Considering the CCM operation, the  $V_{CS}$  REF( $\theta$ ) voltage is then expressed by:

#### **Equation 2**

$$V_{CS\_REF}(\theta)^{CCM} = V_G(\theta) K_2 = \frac{K_M}{V_{OUT}} V_C V_{IN}(\theta)$$
(2)

where  $K_M = K_1 K_2$  is the equivalent multiplier gain (see Electrical characteristics table for details).

The internal current reference voltage  $V_{CS\_REF}(\theta)$  is then compared with the current sense  $V_{CS}(\theta)$  pin voltage (which is internally translated due to negative inductor current sensing) that is opportunely shaped by the "THD-CCM optimizer" in order to achieve sinusoidal input current in CCM operation.

In particular, referring to Section 5.1 Figure 4 and Section 5.1 Figure 5, during the power switch-on time the "THD-CCM optimizer" circuitry sources a current  $I_{THD\_CCM}(\theta)$  to the CS pin, generating a voltage across the external  $R_{THD\_CCM}$  resistor that is subtracted to the inductor current sense voltage  $R_S$   $I_L(\theta)$ .

The resulting  $V_{CS}(\theta)$  voltage, at external power switch turn-off condition, is then:

#### **Equation 3**

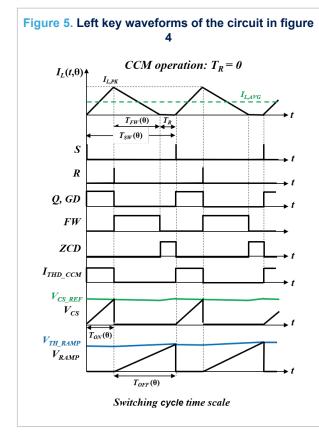
$$V_{CS}(\theta) = R_S I_{L,PK}(\theta) - R_{THD\_CCM} I_{THD\_CCM}(\theta) = V_{CS\_REF}(\theta)$$
(3)

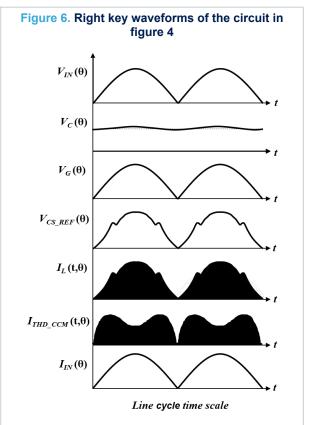
where the sourced  $I_{THD\ CCM}(\theta)$  current is:

#### **Equation 4**

$$I_{THD\_CCM}(\theta) = \frac{L_P}{2 \, K_{CCM}} \, \Delta I_L \! \left( \theta \right) \tag{4}$$

 $L_P$  is the inductor value,  $\Delta I_L(\theta)$  is the inductor current ripple,  $K_{CCM}$  (0.55 typ.) is the circuitry gain.





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Now considering that the input current  $I_{IN}(\theta)$  of the converter is the average value of the inductor current in a switching cycle results:

#### **Equation 5**

 $\Delta I_{I}(\theta) \tag{5}$ 

$$I_{IN}(\theta)^{CCM} = I_{L,PK}(\theta) - \frac{\Delta I_L(\theta)}{2}$$

Selecting the THD-CCM optimizer resistor equal to:

#### **Equation 6**

 $R_{\mathcal{S}} = R_{\mathcal{S}}$ 

$$R_{THD\_CCM} = K_{CCM} \frac{R_S}{L_P}$$

and replacing equations #2 and #4 in equation #3, after some calculations the inductor peak current results:

#### **Equation 7**

 $I_{L,PK}(\theta) = \frac{1}{R_S} \frac{K_M}{V_{OUT}} V_C V_{IN}(\theta) + \frac{\Delta I_L(\theta)}{2}$ (7)

Finally replacing equation #7 in equation #5, the input current of the converter results:

#### **Equation 8**

 $I_{IN}(\theta)^{CCM} = \frac{1}{R_S} \frac{K_M}{V_{OUT}} V_C V_{IN}(\theta)$ (8)

which is sinusoidal and in phase with the  $V_{IN}(\theta)$  input voltage (ideally zero-THD and unity-PF)

Considering the DCM operation ( $T_R>0$ ), through geometrical consideration, the input current  $I_{IN}(\theta)$  of the converter can be expressed by:

#### **Equation 9**

 $I_{IN}(\theta)^{DCM} = \frac{1}{2} I_{L,PK}(\theta) \frac{T_{ON}(\theta) + T_{FW}(\theta)}{T_{ON}(\theta) + T_{FW}(\theta) + T_{R}(\theta)}$  (9)

Equation 9 shows that the term TR>0 introduces distortion if  $I_{L,PK}(\theta)$  has a sinusoidal shape like in a standard PFC. Referring to Figure 4, the sinusoidal voltage  $V_G\left(\theta\right) = V_C \ K_1 \ \frac{V_{IN}(\theta)}{V_{OUT}}$  is then opportunely shaped by the "THD-DCM" optimizer block, which generates the current reference voltage expressed by:

#### **Equation 10**

 $V_{CS\_REF}(\theta)^{DCM} = V_G(\theta) \frac{T_{ON}(\theta) + T_{FW}(\theta) + T_R(\theta)}{T_{ON}(\theta) + T_{FW}(\theta)}$ (10)

Replacing equation #1 in equation #10, and considering that in DCM operation the peak of the inductor current is  $I_{L,PK}(\theta) = \Delta I_L(\theta)$ , after some calculations results:

## **Equation 11**

 $I_{IN}(\theta)^{DCM} = \frac{1}{R_S} \frac{K_M}{V_{OUT}} V_C V_{IN}(\theta)$ (11)

which is sinusoidal and in phase with the  $VI_N(\theta)$  input voltage (ideally zero-THD and unity-PF), and it has the same gain like in CCM operation.

### 5.2 OFF-time modulator

The device embeds a novel OFF-time modulator which is able to achieve quasi-fixed switching frequency in all operating conditions (CCM and DCM operation) and independent from the input/output voltage, the load conditions and the converter's parasitic as the existing modulators.

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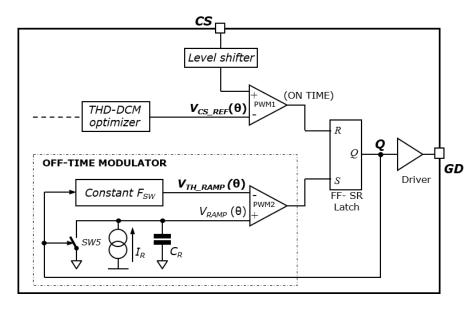
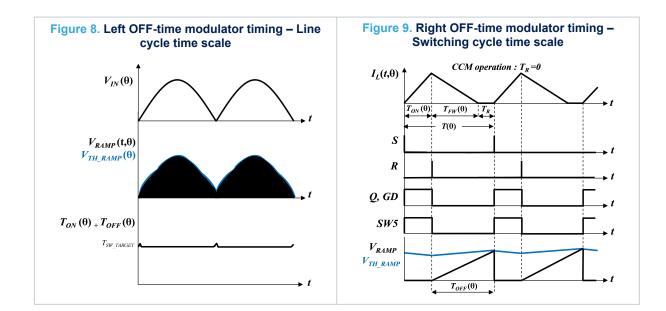


Figure 7. OFF-time modulator - details

Referring to Figure 7, once the power switch ON-time is ended (Q signal goes low) the internal switch  $S_{W5}$  is open and the constant current generator  $I_R$  starts to charge linearly the capacitor  $C_R$ . The resulting voltage  $V_{RAMP}$  is compared with the voltage  $V_{TH\_RAMP}$ , which is generated by the "Constant  $F_{SW}$ " circuitry based on the Q signal duration ( $T_{ON}$ ). As soon as the ramp voltage  $V_{RAMP}$  reaches the  $V_{TH\_RAMP}$  voltage, the flip-flop is set and the external power switch is turned on (Q signal goes high).

In other words, the power switch off-time ( $T_{OFF}$ ) is modulated based on the on-time information ( $T_{ON}$ ) to keep cycle-by-cycle constant the resulting switching frequency ( $F_{SW}$ =1/ $T_{SW}$  TARGET):

 $T_{OFF} = T_{SW\_TARGET} - T_{ON}$ .



## 5.3 High voltage startup

The device embeds a High Voltage (HV) start-up circuitry, based on a high voltage N-channel FET as shown in Figure 10, in order to supply the IC during the initial start-up phase before the self-supply winding is operating.

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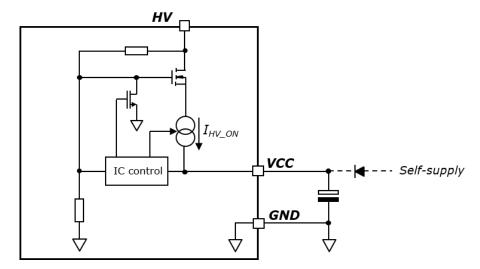


Figure 10. Embedded high voltage start-up circuitry

As soon as the voltage on the HV pin is higher than  $V_{HV\_START}$  (29 V typ.), the HV-start-up circuitry turns on and starts to source an  $I_{HV\_ON}$  current (7 mA typ.). This current, minus the device consumption  $I_{START\_UP}$  before startup (400  $\mu$ A typ.), charges the external bypass capacitor connected between VCC pin and ground increasing its voltage almost linearly up to the device turn-on threshold  $V_{CC\_ON}$  (14 V typ.). To protect the HV-start-up circuitry from excessive power consumption, e.g. for a short-circuit on the VCC pin, the  $I_{HV\_ON}$  current sourced is 1 mA typical till the VCC pin voltage is lower than  $V_{CC\_SO}$  (1 V typ.).

Once the VCC pin voltage reaches  $V_{CC\_ON}$  the device starts operating and to guarantee a reliable startup of the system, the HV current generator  $I_{HV\_ON}$  is kept on till the output voltage reaches 70% typ. of the programmed value (FB pin higher than  $V_{FB\_HVSTUP}$  threshold). To protect the HV-start-up circuitry from excessive power consumption, e.g. in case of an overcurrent request, the HV current generator is in any case automatically turned off after the  $T_{TOUT}$  timeout (100 ms typ.)

After the start-up phase, the system application should guarantee  $V_{CC} > V_{CC\_OFF}$ . In fact, if the VCC pin voltage drops to  $V_{CC\_OFF}$  the device shutdown and the HV-startup is turned on to bring the VCC pin to a voltage  $V_{CC\_ON}$  and restart the operations performing the soft-start.

#### 5.4 Input line discharge (X-cap discharge function)

In order to guarantee safety regulations such as IEC 61010-1/IEC 62368-1 without using the traditional discharge resistor in parallel to the X-capacitor, and thus saving also the associated power losses enabling ultra-low consumption in standby conditions, the device embeds an internal logic circuit that detects when the unit has been detached from the power line; if this event occurs then the high voltage start-up generator is turned on to discharge the X capacitors of the EMI filter to a safe level.

In particular, after a detection time  $T_{DECT\_XCAP}$  (64 ms typ.) from the AC mains disconnection, the X-cap discharge operation is triggered and the internal HV current generator is turned on: a discharge current  $I_{HV\_ON}$  (5 mA minimum) is drawn from the HV pin ensuring the X-cap discharge until the voltage on the HV pin falls below a safe level (45 V maximum,  $V_{HV\_MIN}$  parameter in Section 4 Electrical characteristics, Table 5), within the regulation maximum discharging time.

#### 5.5 Soft-start

To limit the in-rush current of the converter at the startup, the device implements a soft startup increasing the peak of the inductor current from zero up to the required value programmed by the control loop to regulate the output voltage.

In particular, the device changes the reference threshold of the first overcurrent comparator (OCP1) from zero up to  $V_{CS\ OCP1}$  (-0.49 V typ.) in  $T_{SS\ OCP1}$  time (130 ms typ.), as shown in Figure 11 .

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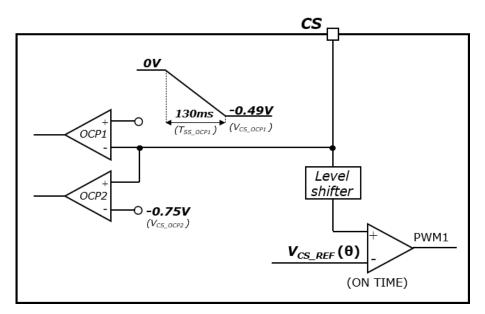


Figure 11. Soft-start circuitry details

## 5.6 No load operation (burst-mode function)

To avoid uncontrolled rise of the output voltage at light or zero load, when  $V_{COMP} < V_{COMP\_S}$  (1 V typ.) the device stops the switching activity and reduces its power consumption. As soon as the  $V_{COMP} > V_{COMP\_R}$  (1.05 V typical and in tracking with the threshold  $V_{COMP\_S}$ ) the device restarts the switching activity.

If the burst-mode condition is triggered when the gate driver GD is "high", the device completes the current ON-time and the system stoppage takes place after GD falling edge.

During the burst-mode operation, the system application should guarantee  $V_{CC} > V_{CC\_OFF}$ . In fact, if the VCC pin voltage drops down to  $V_{CC\_OFF}$ , the device shutdown and the HV-startup is turned on to bring the VCC pin to a voltage  $V_{CC\_ON}$  and restart the operation performing the soft-start.

## 5.7 Idle operation (external burst-mode function)

The FB pin can be used to implement an external burst-mode (EBM), forcing the pin lower than the internal threshold  $V_{FB\_FF/EBM}$  (500 mV typ.): the switching activity is stopped and the IC power consumption is reduced (Error Amplifier is also turned off and the COMP pin is forced to "high impedance"). The device restarts switching, without implementing the soft-start, as soon as the FB voltage exceeds the  $V_{FB\_FF/EBM}$  threshold by 50 mV typ. De-bounce time  $T_{FF/EBM\_DB}$  (1.8  $\mu$ s typ.) is provided to avoid false triggering. Referring to Figure 12, it is worth noting that as soon as the device enters the EBM state (the internal signal EBM\_INT is high) a weak pull-up current  $I_{FB\_EBM}$  (100  $\mu$ A typ.) is sourced from the FB pin in order to speed up the FB voltage rising edge when the external pull-down is released. In addition, once the FB voltage exceeds  $V_{FB\_FF/EBM} + 50$  mV the  $I_{FB\_EBM}$  current of 100  $\mu$ A is increased to 1 mA till the FB pin voltage reaches the final target of 2.5 V (internal  $V_{REF}$ ). When using the EBM function, the suggested value of the FB filter capacitor  $C_{FB}$  is 3.3 nF.

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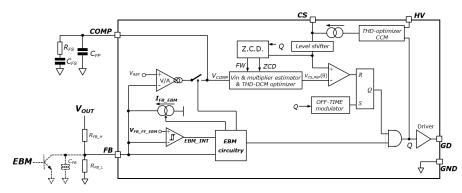


Figure 12. External Burst-Mode (EBM) function – circuit details

During the external burst-mode condition (FB <  $V_{FB\_FF/EBM}$ ), the system application should guarantee  $V_{CC}$  >  $V_{CC\_OFF}$  to minimize the power consumption. In fact, in case the VCC pin voltage approaches the device turn-off threshold the internal HV-startup is turned on to bring  $V_{CC}$  voltage to the turn-on threshold  $V_{CC\_ON}$ .

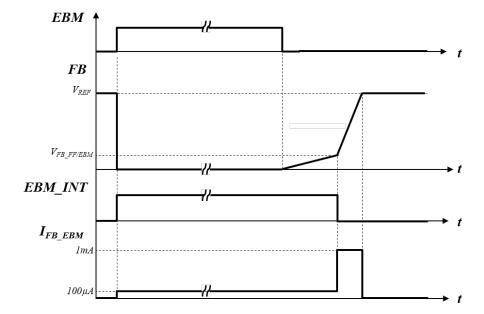


Figure 13. External Burst-Mode (EBM) function - timing

## 5.8 Disable operation (DISABLE function)

Forcing the COMP pin lower than the internal threshold  $V_{COMP\_DIS}$  (0.7 V typ.), the device stops the operation and enters into low power consumption. The Error Amplifier is turned off and a weak internal pull-up current  $I_{COMP\_DIS}$  (10  $\mu$ A typ.) is activated. De-bounce time  $T_{COMP\_DIS\_DB}$  (50  $\mu$ s typ.) is provided to avoid false triggering.

Referring to Figure 14, releasing the external pull-down the internal pull-up current ICOMP\_DIS charges the compensation network connected between COMP pin and ground and the COMP voltage starts to increase. As soon as the VCC pin voltage reaches the  $V_{CC\_ON}$  turn-on threshold, the device checks the COMP pin: if the COMP pin is higher than the enable threshold  $V_{COMP\_EN}$  (0.9 V typ.) the device restarts the operation implementing the soft-start, otherwise it waits for the next  $V_{CC\_ON}$  crossing to check the COMP pin value.

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DISABLE  $V_{OUT}$   $V_{COMP\_DIS}$   $V_{COMP\_DIS}$  V

Figure 14. DISABLE function – circuit details

During the disable condition, due to the absence of energy transferred from the auxiliary winding, the internal HV-startup is intermittently turned on to keep the device supplied between  $V_{CC\ OFF}$  and  $V_{CC\ ON}$ .

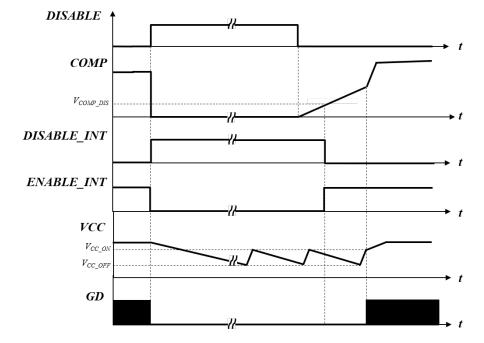


Figure 15. DISABLE function – timing

## 5.9 Protections

A comprehensive set of protections is embedded to ensure a high level of reliability of the final application without adding extra components and/or circuitry.

## 5.9.1 AC brown-in (BI function)

At startup, as soon as the VCC pin voltage reaches the  $V_{CC\_ON}$  turn-on threshold the device monitors the AC line input voltage through the HV pin and starts the operation if the input voltage is higher than the  $V_{HVPK\_BI}$  brown-in threshold (around 81 Vac).

De-bounce time  $T_{DB\_ACBI}$  of 1 ms typ. is provided to avoid false triggering at the first startup. After that, the de-bounce time is increased to 40 ms.

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#### 5.9.2 AC brownout (BO function)

During the normal operation, in order to protect the PFC pre-regulator from excessive RMS current, if the AC line voltage falls below the  $V_{HVPK\_BO}$  brownout threshold (around 71 Vac) for at least 630 ms typ. (see  $T_{DB\_ACBO}$  parameter in Table 5. Electrical characteristics), the switching activity is stopped.

A recycle of VCC between the turn-off threshold ( $V_{CC\_OFF}$ ) and the turn-on threshold ( $V_{CC\_ON}$ ) is needed to restart the converter.

#### 5.9.3 Output overvoltage (OVP function)

To limit an output voltage overshoot, e.g. due to a heavy load release or at startup with light-load, the device stops the switching activity as soon as the instantaneous output voltage  $V_{OUT}$  is higher than 7% typ. in respect to the programmed value.

In fact, the device detects an overvoltage condition monitoring the FB pin which is proportional to the instantaneous value of the output voltage  $V_{OUT}$  and in steady-state conditions sits at the internal reference of the error amplifier ( $V_{REF} = 2.5 \text{ V}$ ).

As soon as the FB voltage exceeds the steady-state value by 7% ( $V_{FB} > V_{FB\_S}$ ), the switching activity is stopped until it gets back close to it ( $V_{FB} < V_{FB\_R}$ ).

De-bounce time T<sub>DOVP DB</sub> (50 µs typ.) is provided to avoid false activation of the protection.

During the OVP condition, to avoid undesired IC shutdown, as soon as the VCC pin voltage falls below the  $V_{CC\_HVSTUP\_OVP}$  threshold (11.5 V typ.) the internal HV-startup is turned on to bring  $V_{CC}$  voltage to the turn-on threshold  $V_{CC\_ON}$ .

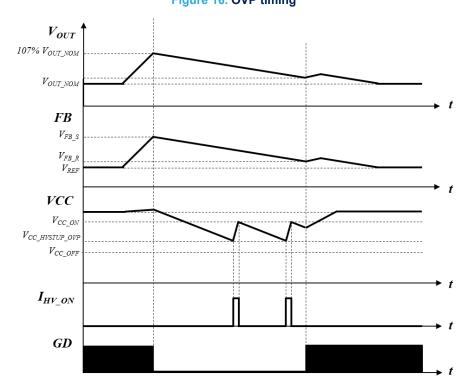


Figure 16. OVP timing

## 5.9.4 Overcurrent (OCP1 function)

To limit the peak inductor current in case of extra request (e.g. heavy load changes), the device implements a cycle-by-cycle overcurrent protection. The device monitors the CS pin during the power switch on-time and as soon as the voltage on the CS pin goes below  $V_{CS\_OCP1}$  (-0.49 V typ.), the internal overcurrent comparator is triggered and terminates the conduction cycle of the power switch before the normal PWM circuit does. In this way, the peak inductor current is limited to a maximum of 0.49/RS.

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#### 5.9.5 Inductor saturation detection (OCP2 function)

A second overcurrent level set at  $V_{CS\_OCP2}$  (-0.75 V typ.) detects abnormal current values (e.g. due to boost inductor saturation) and, on this occurrence for two consecutive switching cycles, activates a safety procedure that immediately stops the converter activity until the current level reaches the zero-current threshold ( $V_{CS\_ZCD}$ ).

The zero-current threshold monitor allows safe operations also during current surges occurring at power-up or after a mains dip or missing cycle; in fact it allows switching start/restart only when the overcurrent event is definitively over.

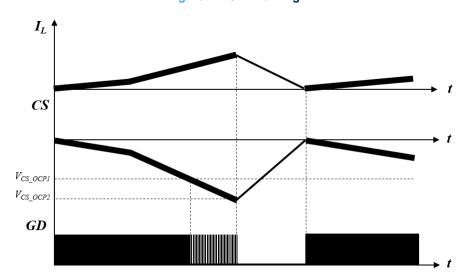


Figure 17. OCP2 timing

#### 5.9.6 Feedback failure detection

The device handles the possible disconnection of both output voltage feedback and input current monitoring. At startup, as soon as the VCC pin voltage reaches the  $V_{CC\_ON}$  turn-on threshold, the device checks the FB and CS pins:

- if the FB pin voltage is lower than the internal V<sub>FB\_FF/EBM</sub> threshold (0.5 V typ.) a failure of the output divider resistor is assumed (e.g. R<sub>FB\_H</sub> resistor not mounted), then the device stops the switching activity and reduces its consumption.
  - De-bounce time T<sub>FF/EBM</sub> DB (1.8 μs typ.) is provided to avoid false triggering.
- if the CS pin voltage is higher than the internal V<sub>CSD</sub> threshold (200 mV typ.) a failure of the current sensing resistors is assumed (e.g. R<sub>THD\_CCM</sub> resistor not mounted and/or RS resistor burned), then the device stops the switching activity and reduces its consumption.

De-bounce time  $T_{CSD\_DB}$  (10  $\mu$ s typ.) is provided to avoid false triggering and a recycle of  $V_{CC}$  between the turn-off threshold ( $V_{CC\ OFF}$ ) and the turn-on threshold ( $V_{CC\ ON}$ ) is needed to restart the converter

#### 5.10 Line feedforward

To keep the maximum output power deliverable by the converter almost constant with respect to the AC input voltage, a two-level discrete voltage feedforward is integrated in the controller. Basically, the AC input voltage is monitored through the HV pin and internally compared with a fixed threshold to properly set the value of equivalent multiplier gain  $K_M$  (see Table 5. Electrical characteristics for details). The proper operation of the converter, with the right  $K_M$  multiplier gain, is guaranteed for an AC input voltage below 142 Vrms and above 166 Vrms.

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# 6 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

# 6.1 SO-8 package information

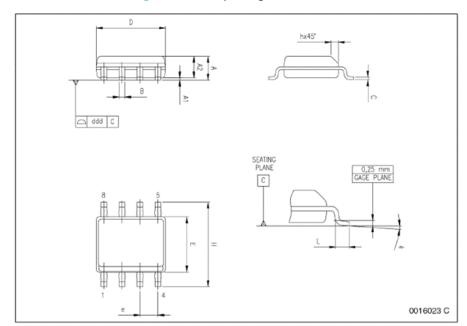


Figure 18. SO-8 package dimensions

Table 6. SO-8 mechanical data

Dim.		mm.			inch		
Dilli.	Min.	Тур.	Max.	Min.	Тур.	Max.	
А	1.35		1.75	0.053		0.069	
A1	0.10		0.25	0.004		0.010	
A2	1.10		1.65	0.043		0.065	
В	0.33		0.51	0.013		0.020	
С	0.19		0.25	0.007		0.010	
D <sup>(1)</sup>	4.80		5.00	0.189		0.197	
Е	3.80		4.00	0.15		0.157	
е		1.27			0.050		
Н	5.80		6.20	0.228		0.244	
h	0.25		0.50	0.010		0.020	
L	0.40		1.27	0.016		0.050	
k	0° (min.), 8° (max.)						
ddd			0.10			0.004	

Dimensions D does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15 mm (.006 inch) in total (both side).

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# 7 Ordering information

Table 7. Order codes

Order code	Package	Package marking	Packaging
L4985A	SO-8	L4985A	Tube
L4985B	SO-8	L4985B	Tube
L4985ATR	SO-8	L4985A	Tape and reel
L4985BTR	SO-8	L4985B	Tape and reel

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# **Revision history**

**Table 8. Document revision history** 

Date	Version	Changes
16-Jul-2021	1	Initial release.
12-Aug-2021	2	Updated Table 5. Electrical characteristics

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