

Main

type Product specific application Component name ATV71 Motor power kW 0.37 kWa 0.75 kW a 0.75 kW a 0.75 kW a 0.5 hpat 2 0.5 hpa	
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tion Component name ATV71 Motor power kW 0.37 kWa 0.75 kW a 0.75 kW a Motor power hp 1 hp at 20 0.5 hpat 2 Motor cable length <= 164.04 <= 328.08 Power supply voltage Phase 3 phases Single ph. Line current 5.3 Afor 2 5.8 Afor 2 6.9 Afor 2 6.9 Afor 2 EMC filter Integrated Assembly style With heat Apparent power 1.4 kVAat 2.2 kVAat Prospective line lsc <= 5 kA, 3 <= 5 kA, 3 Nominal output current 4.5 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency Switching frequency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile EMC filter Integrated 1.4 kVAat 2.2 kVAat 2.2 kVAat 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Switching frequency Line Control profile ENA (Ene	peed drive
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Motor cable length <= 164.04 <= 328.08 Power supply voltage 200240 Phase 3 phases Single phase Single phase Single phase 5.8 Afor 2 6.1 Afor 2 6.9 Afor 2 EMC filter Integrated Assembly style With heat 2.2 kVAat 2.2 kVAat 2.2 kVAat 2.2 kVAat 4.8 Aat 4 Maximum transient current 3 Aat 4 kt 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency 116 kHz 416 kHz 4	200240 V single phase t 200240 V 3 phases
<= 328.06	0240 V 3 phases 00240 V single phase
Phase Single phase	ft (50 m) Shielded cable ft (100 m) Unshielded cable
Single ph. Line current 5.3 Afor 2 5.8 Afor 2 6.1 Afor 2 6.9 Afor 2 EMC filter Integrated Assembly style With heat Apparent power 1.4 kVAat 2.2 kVAat Prospective line lsc <= 5 kA, 3 <= 5 kA, 5 Nominal output current 3 Aat 4 kt 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency Nominal switching frequency Switching frequency Asynchronous motor control profile 5.3 Afor 2 6.9 Afor 2 7.2 kVAat 2.2 kVAat 4.8 Aat 4 Asynchronous motor control profile ENA (Enerola loads Flux vector Flux vector First Single ph. Single ph. 5.3 Afor 2 6.1 Afor 2 6.9 Afor 2 7.2 kVAat 2.2 kVAat 4.8 Aat 4 4.8 Aat 4 4.8 Aat 4 4.8 Aat 4 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 7.9 Afor 3 7.9 Afor 2 7.9 Afor 3 7.9	V (- 1510 %)
5.8 Afor 2 6.1 Afor 2 6.9 Afor 2 EMC filter Integrated Assembly style With heat Apparent power 1.4 kVAat 2.2 kVAat Prospective line Isc <= 5 kA, 3 <= 5 kA, 5 Nominal output current 3 Aat 4 kt 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency 416 kHz Asynchronous motor control profile loads Flux vector	ase
Assembly style Apparent power Apparent power 1.4 kVAat 2.2 kVAat Prospective line Isc <= 5 kA, s <= 5 kA, s Nominal output current 3 Aat 4 kt 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile ENA (Ene	40 V 3 phases 0.75 kW / 1 hp 40 V single phase 0.37 kW / 0.5 hp 00 V 3 phases 0.75 kW / 1 hp 00 V single phase 0.37 kW / 0.5 hp
Apparent power 1.4 kVAat 2.2 kVAat 2.2 kVAat Prospective line Isc <= 5 kA, 3 <= 5 kA, 5 Nominal output current 3 Aat 4 kt 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency Nominal switching frequency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile 14 kVAat 2.2 kVAat 4.5 kVAa	
Prospective line Isc <= 5 kA, s <= 5 kA, s Nominal output current 3 Aat 4 kH 4.8 Aat 4 Maximum transient current 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency 4 kHz Switching frequency 116 kHz 416 kHz Asynchronous motor control profile loads Flux vectors	sink
Nominal output current 3 Aat 4 kl. 4.8 Aat 4 Maximum transient current 4.5 Afor 6 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency Switching frequency 4 kHz 416 kHz 416 kHz Asynchronous motor control profile Ioads Flux vector Flux vector	240 V single phase 0.37 kW / 0.5 hp 240 V 3 phases 0.75 kW / 1 hp
Asynchronous motor control profile Maximum transient cur- 4.8 Aat 4 Maximum transient cur- 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 0.1599 A kHz 4 kHz 116 kHz 416 kHz Asynchronous motor control profile loads Flux vectors	phases ingle phase
rent 4.9 Afor 2 7.2 Afor 6 7.9 Afor 2 Output frequency 0.1599 Nominal switching frequency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile loads Flux vector	dz 230 V single phase 0.37 kW / 0.5 hp kHz 230 V 3 phases 0.75 kW / 1 hp
Nominal switching frequency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile RNA (Energy loads Flux vectors Flux vectors	0 s single phase 0.37 kW / 0.5 hp s single phase 0.37 kW / 0.5 hp 0 s 3 phases 0.75 kW / 1 hp s 3 phases 0.75 kW / 1 hp
quency Switching frequency 116 kHz 416 kHz Asynchronous motor control profile RNA (Ene loads Flux vector	
Asynchronous motor ENA (Ene control profile loads Flux vector	
control profile loads Flux vector	adjustable with derating factor
Sensorles current ve	rgy adaptation) system for unbalanced or control (FVC) with sensor (current vecs flux vector control (SFVC) (voltage or ctor) equency ratio (2 or 5 points)
Type of polarization No imped	ance Modbus

Complementary

Product destination	Asynchronous motors Synchronous motors
Power supply voltage limits	170264 V
Power supply frequency	5060 Hz (- 55 %)
Power supply frequency limits	47.563 Hz
Speed range	1100 asynchronous motor in open-loop mode, without speed feedback150 synchronous motor in open-loop mode, without speed feedback11000 asynchronous motor in closed-loop mode with encoder feedback

+/- 0.01 % of nominal speed 0.2 Tn to Tn torque variation in closed-loop mode with encoder feedback +/- 10 % of nominal slip 0.2 Tn to Tn torque variation without speed feedback				
+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback				
220 % of nominal motor torque +/- 10 %for 2 s 170 % of nominal motor torque +/- 10 %for 60 s every 10 minutes				
<= 150 % with braking or hoist resistor 30 % without braking resistor				
Vector control without speed feedback				
Adjustable PI regulator				
Adjustable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Suppressable				
1 LED red presence of drive voltage				
<= power supply voltage				
Electrical between power and control				
With a NEMA Type1 kit: 3-strand UL 508 cableat 104 °F (40 °C), copper 75 °C PVC				
With an IP21 or an IP31 kit: 3-strand IEC cableat 104 °F (40 °C), copper 70 °C PVC				
Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 70 °C PVC Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 90 °C XLPE/EPR				
Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR terminal 2.5				
mm² / AWG 14 L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 4 mm² / AWG 10				
AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR 5.31 lbf.in (0.6				
N.m) L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 12.39 lbf.in (1.4 N.m) / 12.3 lb.in				
Internal supply for reference potentiometer (1 to 10 kOhm), 10.5 V DC +/- 5 %, <= 10 mAfor overload and short-circuit protection Internal supply, 24 V DC, voltage limits 2127 V, <= 200 mAfor overload and short-circuit protection				
2				
Al1-/Al1+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign Al2 software-configurable current 020 mA, impedance 242 Ohm, resolution 11 bits Al2 software-configurable voltage 010 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits				
AI1-/AI1+ 2 ms, +/- 0.5 ms analog input(s)				
Al2 2 ms, +/- 0.5 ms analog input(s) LI1LI5 2 ms, +/- 0.5 ms discrete input(s) LI6 (if configured as logic input) 2 ms, +/- 0.5 ms discrete input(s)				
<= 100 ms in STO (Safe Torque Off) AO1 2 ms, tolerance +/- 0.5 ms analog output(s) R1A, R1B, R1C 7 ms, tolerance +/- 0.5 ms discrete output(s) R2A, R2B 7 ms, tolerance +/- 0.5 ms discrete output(s)				
Al1-/Al1+ +/- 0.6 % for a temperature variation 60 °C Al2 +/- 0.6 % for a temperature variation 60 °C AO1 +/- 1 % for a temperature variation 60 °C				
Al1-/Al1+, Al2 +/- 0.15 % of maximum value AO1 +/- 0.2 %				
1				
AO1 software-configurable current 020 mA, impedance 500 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V <= 20 mA AO1 software-configurable voltage 010 V DC, impedance 470 Ohm, resolution 10 bits				
2				
R1A, R1B, R1C configurable relay logic NO/NC, electrical durability 100000 cy-				

Maximum switching current	R1, R2 on resistive load, 5 Aat 250 V AC, cos phi = 1, R1, R2 on resistive load, 5 Aat 30 V DC, cos phi = 1, R1, R2 on inductive load, 2 Aat 250 V AC, cos phi = 0.4, R1, R2 on inductive load, 2 Aat 30 V DC, cos phi = 0.4,				
Discrete input number	7				
Discrete input type	LI6: switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm PWR: safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d LI1LI5: programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI6: switch-configurable PTC probe 06, impedance: 1500 Ohm				
Discrete input logic	LI1LI5 positive logic (source), < 5 V (state 0), > 11 V (state 0) LI1LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 0) LI6 (if configured as logic input) positive logic (source), < 5 V (state 0), > 11 V (state 0) LI6 (if configured as logic input) negative logic (sink), > 16 V (state 0), < 10 V (state 0)				
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S, U or customized				
Braking to standstill	By DC injection				
Protection type	Drive against exceeding limit speed Drive against input phase loss Drive break on the control circuit Drive input phase breaks Drive line supply overvoltage Drive line supply undervoltage Drive line supply undervoltage Drive overcurrent between output phases and earth Drive overheating protection Drive overvoltages on the DC bus Drive short-circuit between motor phases Drive thermal protection Motor motor phase break Motor power removal Motor thermal protection				
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth				
Frequency resolution	Analog input 0.024/50 Hz Display unit 0.1 Hz				
Communication port protocol	CANopen Modbus				
Connector type	1 RJ45 Modbus on front face 1 RJ45 Modbus on terminal Male SUB-D 9 on RJ45 CANopen				
Physical interface	2-wire RS 485 Modbus				
Transmission frame	RTU Modbus				
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps CANopen 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps Modbus on terminal 9600 bps, 19200 bps Modbus on front face				
Data format	8 bits, 1 stop, even parity Modbus on front face 8 bits, odd even or no configurable parity Modbus on terminal				
Number of addresses	1247 Modbus 1127 CANopen				
Method of access	Slave CANopen				
Marking	CE				
Operating position	Vertical +/- 10 degree				
Height	9.06 in (230 mm)				
Depth	6.89 in (175 mm)				
Width	5.12 in (130 mm)				
Product weight	6.61 lb(US) (3 kg)				
Functionality	Full				

Specific application	Other applications		
Option card	CC-Link communication card		
·	Controller inside programmable card		
	DeviceNet communication card		
	Ethernet/IP communication card		
	Fipio communication card		
	I/O extension card		
	Interbus-S communication card		
	Interface card for encoder		
	Modbus Plus communication card		
	Modbus TCP communication card		
	Modbus/Uni-Telway communication card		
	Overhead crane card		
	Profibus DP communication card		
	Profibus DP V1 communication card		

Environment

Noise level	43 dB conforming to 86/188/EEC
Dielectric strength	2830 V DC between earth and power terminals 4230 V DC between control and power terminals
Electromagnetic compatibility	Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 1.2/50 µs - 8/20 µs surge immunity test conforming to IEC 61000-4-5 level 3
Standards	EN 55011 class A group 1 EN 61800-3 environments 1 category C2 EN 61800-3 environments 2 category C2 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1
Product certifications	CSA C-Tick GOST NOM 117 UL
Pollution degree	2 conforming to EN/IEC 61800-5-1
IP degree of protection	IP20
Vibration resistance	1.5 mm peak to peak (f = 313 Hz) conforming to EN/IEC 60068-2-6 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for operation	14122 °F (-1050 °C) without derating
Ambient air temperature for storage	-13158 °F (-2570 °C)
Operating altitude	<= 3280.84 ft (1000 m) without derating 3280.849842.52 ft (10003000 m) with current derating 1 % per 100 m

Ordering and shipping details

Category	22130 - ATV71 - 1/2 THRU 5HP DRIVES		
Discount Schedule	CP4C		
GTIN	00785901428855		
Nbr. of units in pkg.	1		
Package weight(Lbs)	8.68999999999995		
Returnability	Y		
Country of origin	ID		

Offer Sustainability

California proposition 65	WARNING: This product can expose you to chemicals including:
Substance 1	Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.
Substance 2	Bisphenol A (BPA), which is known to the State of California to cause birth defects or other reproductive harm.
More information	For more information go to www.p65warnings.ca.gov

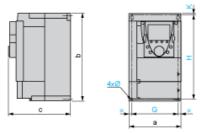
Contractual warranty

Product data sheet Dimensions Drawings

ATV71H075M3

UL Type 1/IP 20 Drives

Dimensions without Option Card



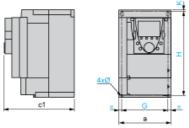
Dimensions in mm

а	b	С	G	Н	К	Ø
130	230	175	113.5	220	5	5

Dimensions in in.

а	b	С	G	Н	К	Ø
5.11	9.05	6.89	4.46	8.66	0.19	0.19

Dimensions with 1 Option Card (1)



Dimensions in mm

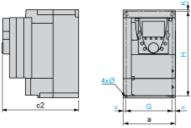
а	c1	G	Н	К	Ø
130	198	113.5	220	5	5

Dimensions in in.

а	c1	G	Н	К	Ø
5.11	7.79	4.46	8.66	0.19	0.19

⁽¹⁾ Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Dimensions with 2 Option Cards (1)



Dimensions in mm

а	c2	G	Н	К	Ø
130	221	113.5	220	5	5

Dimensions in in.

а	c2	G	Н	К	Ø
5.11	8.70	4.46	8.66	0.19	0.19

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Product data sheet Mounting and Clearance

ATV71H075M3

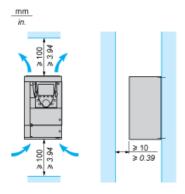
Mounting Recommendations

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

Install the unit vertically:

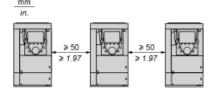
- · Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

Clearance

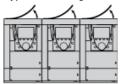


Mounting Types

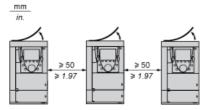
Type A Mounting



Type B Mounting



Type C Mounting



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

The protective blanking cover may vary according to the drive model (refer to the user guide).

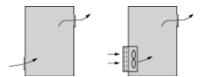
The protective blanking cover must be removed from ATV 71P ••• N4Z drives when they are mounted in a dust and damp proof enclosure.

Specific Recommendations for Mounting the Drive in an Enclosure

Ventilation

To ensure proper air circulation in the drive:

- · Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide
 a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

Dust and Damp Proof Metal Enclosure (IP 54)

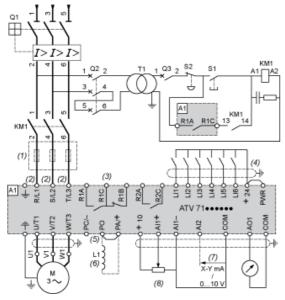
The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

ATV71H075M3

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor



A1 ATV71 drive

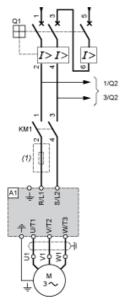
KM1 Contactor

- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05
- S1, XB4 B or XB5 A pushbuttons
- S2
- T1 100 VA transformer 220 V secondary
- (1) Line choke (three-phase); mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Power Section for Single-Phase Power Supply



A1 ATV71 drive

KM1 Contactor

Q1 Circuit-breaker

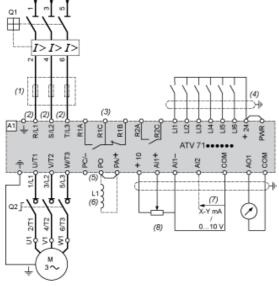
Q2 GV2 L rated at twice the nominal primary current of T1

(1) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector

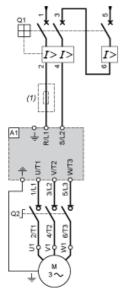


- A1 ATV71 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Power Section for Single-Phase Power Supply

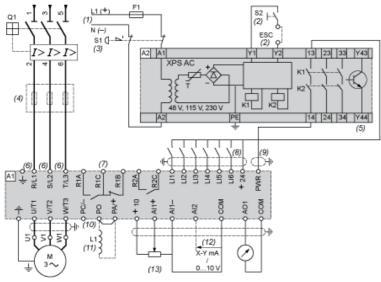


- A1 ATV71 drive
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement

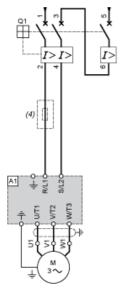


- A1 ATV71 drive
- A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 48 Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (11) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

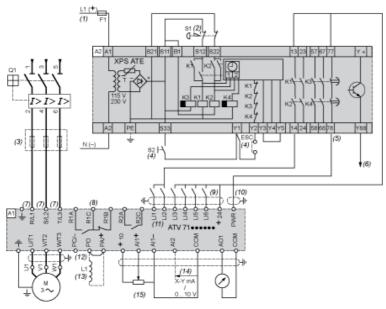
Power Section for Single-Phase Power Supply



- A1 ATV71 drive
- Q1 Circuit-breaker
- (4) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply. All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine

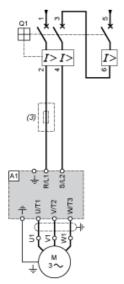


- A1 ATV71 drive
- A2 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal"
- (5) safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 N/C contacts
- S2 Run button
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (6) The logic output can be used to signal that the machine is in a safe state.
- (7) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (13) Optional DC choke for ATV71H••••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Power Section for Single-Phase Power Supply



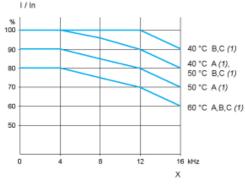
- A1 ATV71 drive
- Q1 Circuit-breaker
- (3) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply. All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Product data sheet Performance Curves

ATV71H075M3

Derating Curves

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type. For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.



- X Switching frequency
- (1) Mounting type

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