ATV12PU40M3

variable speed drive ATV12 - 4kW - 5hp - 3ph - 200..240V - on base plate

Product availability: Non-Stock - Not normally stocked in distribution facility



Range Produ

Range of product	Altivar 12
Product or component type	Variable speed drive
Product destination	Asynchronous motors
Product specific application	Simple machine
Assembly style	On base plate
Component name	ATV12
Quantity per set	Set of 1
EMC filter	Without EMC filter
Built-in fan	Without
Phase	3 phases
[Us] rated supply voltage	200240 V - 1510 %
Motor power kW	4 kW
Motor power kW Motor power hp	4 kW 5 hp
Motor power hp Communication port	5 hp
Motor power hp Communication port protocol	5 hp Modbus 23.8 A 200 V
Motor power hp Communication port protocol Line current	5 hp Modbus 23.8 A 200 V 19.9 A 240 V
Motor power hp Communication port protocol Line current Speed range	5 hp Modbus 23.8 A 200 V 19.9 A 240 V 120 150170 % of nominal motor torque depending on
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Motor power hp Communication port protocol Line current Speed range Transient overtorque Asynchronous motor control profile	5 hp Modbus 23.8 A 200 V 19.9 A 240 V 120 150170 % of nominal motor torque depending on drive rating and type of motor Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/frequency ratio (V/f)

Complementary

Complementary		
Supply frequency	50/60 Hz +/- 5 %	
Connector type	1 RJ45 Modbus on front face	
Physical interface	2-wire RS 485 Modbus	
Transmission frame	RTU Modbus	
Transmission rate	4800 bit/s 9600 bit/s 19200 bit/s 38400 bit/s	
Number of addresses	1247 Modbus	
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/Write multiple registers (23) 4/4 words Read device identification (43)	
Prospective line Isc	<= 5 kA	
Continuous output current	16.7 A 4 kHz	
Maximum transient current	25 A 60 s	
Speed drive output frequency	0.5400 Hz	
Nominal switching frequency	4 kHz	
Switching frequency	216 kHz adjustable 416 kHz with derating factor	

Braking torque	Up to 70 % of nominal motor torque without braking resistor
Motor slip compensation	Adjustable
	Preset in factory
Output voltage	200240 V 3 phases
Electrical connection	Terminal 5.5 mm ² AWG 10 L1, L2, L3, U, V, W, PA, PC
Tightening torque	10.62 lbf.in (1.2 N.m)
Insulation	Electrical between power and control
Supply	Internal supply for reference potentiometer 5 V DC 4.755.25 V 10 mA overload and short-circuit protection Internal supply for logic inputs 24 V DC 20.428.8 V 100 mA overload and short-circuit protection
Analogue input number	1
Analogue input type	Configurable voltage AI1 010 V 30 kOhm Configurable voltage AI1 05 V 30 kOhm Configurable current AI1 020 mA 250 Ohm
Discrete input number	4
Discrete input type	Programmable LI1LI4 24 V 1830 V
Discrete input logic	Negative logic (sink) > 16 V < 10 V 3.5 kOhm Positive logic (source) 0< 5 V > 11 V
Sampling duration	20 ms +/- 1 ms logic input 10 ms analogue input
Linearity error	+/- 0.3 % of maximum value analogue input
Analogue output number	1
Analogue output type	Software-configurable voltage AO1 010 V 470 Ohm 8 bits Software-configurable current AO1 020 mA 800 Ohm 8 bits
Discrete output number	2
Discrete output type	Logic output LO+, LO- Protected relay output R1A, R1B, R1C 1 C/O
Minimum switching current	5 mA 24 V DC logic relay
Maximum switching current	2 A 250 V AC inductive cos phi = 0.4 L/R = 7 ms logic relay 2 A 30 V DC inductive cos phi = 0.4 L/R = 7 ms logic relay 3 A 250 V AC resistive cos phi = 1 L/R = 0 ms logic relay 4 A 30 V DC resistive cos phi = 1 L/R = 0 ms logic relay
Acceleration and deceleration ramps	Linear from 0 to 999.9 s
·	\$
Deal to the standard	U P. PO Ministra 4 200
Braking to standstill	By DC injection <= 30 s
Protection type	Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases
Frequency resolution	0.1 Hz display unit Converter A/D, 10 bits analog input
Time constant	20 ms +/- 1 ms for reference change
Marking	CE
Operating position	Vertical +/- 10 degree
Height	7.24 in (184 mm)
Width	5.51 in (140 mm)
Depth	3.94 in (100.2 mm)
Product weight	3.53 lb(US) (1.6 kg)
Variable speed drive application selection	Commercial equipment : mixer Commercial equipment : other application Textile : ironing
Motor starter type	Variable speed drive

Environment

Electromagnetic compatibility	Immunity to conducted disturbances level 3 EN/IEC 61000-4-6 Surge immunity test level 3 EN/IEC 61000-4-5 Voltage dips and interruptions immunity test EN/IEC 61000-4-11 Electrical fast transient/burst immunity test level 4 EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 EN/IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 EN/IEC 61000-4-3
Electromagnetic emission	Radiated emissions environment 1 category C2 EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions EN/IEC 61800-3
Product certifications	CSA C-Tick GOST NOM UL
Vibration resistance	1 gn EN/IEC 60068-2-6 13200 Hz 1.5 mm peak to peak EN/IEC 60068-2-6 313 Hz drive unmounted on symmetrical DIN rail
Shock resistance	15 gn EN/IEC 60068-2-27 11 ms
Relative humidity	595 % without condensation IEC 60068-2-3 595 % without dripping water IEC 60068-2-3
Ambient air temperature for storage	-13158 °F (-2570 °C)
Ambient air temperature for operation	14104 °F (-1040 °C) protective cover from the top of the drive removed 104140 °F (4060 °C) with current derating 2.2 % per °C
Operating altitude	> 3280.849842.52 ft (> 10003000 m) with current derating 1 % per 100 m <= 3280.84 ft (1000 m) without derating

Ordering and shipping details

Category	22042 - ATV12 DRIVE AND ACCESSORIES
Discount Schedule	CP4B
GTIN	00785901727606
Nbr. of units in pkg.	1
Package weight(Lbs)	5.7199999999998
Returnability	N
Country of origin	ID

Offer Sustainability

RoHS (date code: YYWW)	Compliant - since 0901 - Schneider Electric declaration of conformity Schneider Electric declaration of conformity
REACh	Reference not containing SVHC above the threshold
California proposition 65	WARNING: This product can expose you to chemicals including:
Substance 1	Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.
Substance 2	Bisphenol A (BPA), which is known to the State of California to cause birth defects or other reproductive harm.
More information	For more information go to www.p65warnings.ca.gov

Contractual warranty

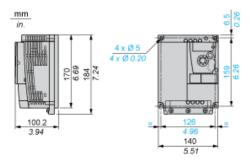
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Warranty pariod	18 months
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Product data sheet Dimensions Drawings

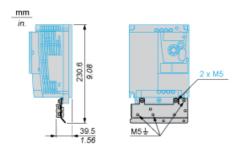
ATV12PU40M3

Dimensions

Drive without EMC Conformity Kit



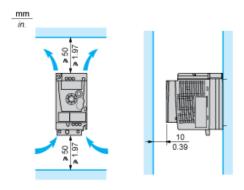
Drive with EMC Conformity Kit



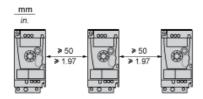
ATV12PU40M3

Mounting Recommendations

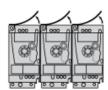
Clearance for Vertical Mounting



Mounting Type A

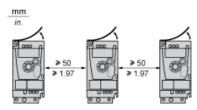


Mounting Type B



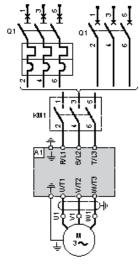
Remove the protective cover from the top of the drive.

Mounting Type C



Remove the protective cover from the top of the drive.

Three-Phase Power Supply Wiring Diagram



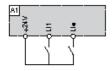
A1 Drive

KM1 Contactor (only if a control circuit is needed)

Q1 Circuit breaker

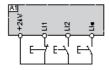
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



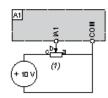
LI1: Forward LI•: Reverse A1: Drive

3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive

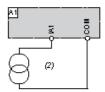
Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 $k\Omega$...10 $k\Omega$ reference potentiometer

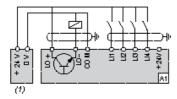
A1: Drive

Analog Input Configured for Current with Internal Power Supply



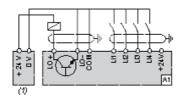
(2) 0-20 mA 4-20 mA supply A1: Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vd A1 : Drive 24 vdc supply

Connected as Negative Logic (Sink) with External 24 vdc supply

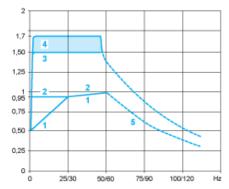


(1) 24 vdc supply A1: Drive

Product data sheet Performance Curves

ATV12PU40M3

Torque Curves



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.

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