

Product data sheet

Specifications



Variable speed drive, Altivar Process ATV900, ATV930, 55kW/75 hp, 500V/690 V, IP00

ATV930D55Y6

Main

Range of product	Altivar Process ATV900
Device application	Industrial application
Product or component type	Variable speed drive
Product destination	Asynchronous motors Synchronous motors
Product specific application	Process for industrial
Variant	With braking chopper Standard version
Network number of phases	3 phases
Mounting mode	Wall mount
Communication port protocol	Modbus serial EtherNet/IP Modbus TCP
[Us] rated supply voltage	500...690 V - 15...10 %
Nominal output current	66.0 A
Motor power kW	45.0 kW for normal duty 37.0 kW for heavy duty
Motor power hp	60.0 hp for normal duty 50.0 hp for heavy duty
Continuous output current	66 A at 2.5 kHz for normal duty 55 A at 2.5 kHz for heavy duty
EMC filter	Integrated With EMC plate option
IP degree of protection	IP21
Degree of protection	UL type 1
Option module	Slot A: communication module for Profibus DP V1 Slot A: communication module for Profinet Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink

Complementary

Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC (≤ 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (≤ 30 V) STOA, STOB safe torque off, 24 V DC (≤ 30 V), impedance: > 2.2 kOhm
Discrete input logic	16 preset speeds
Discrete output number	2
Discrete output type	Logic output DQ+ 0...1 kHz ≤ 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz ≤ 30 V DC 20 mA Logic output DQ- 0...1 kHz ≤ 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
Maximum switching current	Relay output R1 on resistive load, $\cos \phi = 1$: 3 A at 250 V AC Relay output R1 on resistive load, $\cos \phi = 1$: 3 A at 30 V DC Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, $\cos \phi = 1$: 5 A at 250 V AC Relay output R2, R3 on resistive load, $\cos \phi = 1$: 5 A at 30 V DC Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Physical interface	Ethernet 2-wire RS 485
Connector type	2 RJ45 1 RJ45
Method of access	Slave Modbus TCP
Transmission rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
4 quadrant operation possible	True
Asynchronous motor control profile	Variable torque standard Optimized torque mode Constant torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s S, U or customized
Motor slip compensation	Can be suppressed Automatic whatever the load Adjustable Not available in permanent magnet motor law
Switching frequency	1...4.9 kHz adjustable 2.5...4.9 kHz with derating factor

Nominal switching frequency	2.5 kHz
Braking to standstill	By DC injection
Brake chopper integrated	True
Line current	65.5 A at 500 V (normal duty) 55.6 A at 500 V (heavy duty) 62.5 A at 690 V (normal duty) 54.4 A at 690 V (heavy duty)
Maximum input current	65.5 A
Maximum output voltage	690.0 V
Apparent power	74.7 kVA at 690 V (normal duty) 65 kVA at 690 V (heavy duty)
Maximum transient current	79.2 A during 60 s (normal duty) 82.5 A during 60 s (heavy duty)
Network frequency	50...60 Hz
Relative symmetric network frequency tolerance	5 %
Prospective line I _{sc}	70 kA
Base load current at high overload	55.0 A
Base load current at low overload	66.0 A
Power dissipation in W	Forced convection: 858 W at 500 V, switching frequency 2.5 kHz Natural convection: 227 W at 500 V, switching frequency 2.5 kHz
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake management (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive

Quantity per set	1
Width	331 mm
Height	630 mm
Depth	297 mm
Net weight	53 kg
Electrical connection	Control: screw terminal 0.5...1.5 mm²/AWG 20...AWG 16 Line side: screw terminal 25...50 mm²/AWG 4...AWG 1 Motor: screw terminal 25...50 mm²/AWG 4...AWG 1 DC bus: screw terminal 25...50 mm²/AWG 4...AWG 1
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	Local diagnostic: 3 LED (mono/dual colour) Presence of voltage: 1 LED (red) Embedded communication status: 3 LED (dual colour) Communication module status: 4 LED (dual colour)
Input compatibility	DI1...DI8: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Sampling duration	2 ms +/- 0.5 ms (DI1...DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals
Environment	
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	CSA UL TÜV
Marking	CE
Standards	UL 508C EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Assembly style	Enclosed
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4

	1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	406 m³/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	56 dB conforming to 86/188/EEC
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...50 °C (without derating) 50...60 °C (with derating factor)
Noise level	56 dB
Pollution degree	2
Ambient air transport temperature	-40...70 °C
Ambient air temperature for storage	-40...70 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Weight	42 kg
Package 1 Height	58 cm
Package 1 width	44 cm
Package 1 Length	111 cm
Unit Type of Package 2	PAL
Number of Units in Package 2	1
Package 2 Weight	52 kg
Package 2 Height	29.7 cm
Package 2 width	33.1 cm
Package 2 Length	63 cm

Offer Sustainability

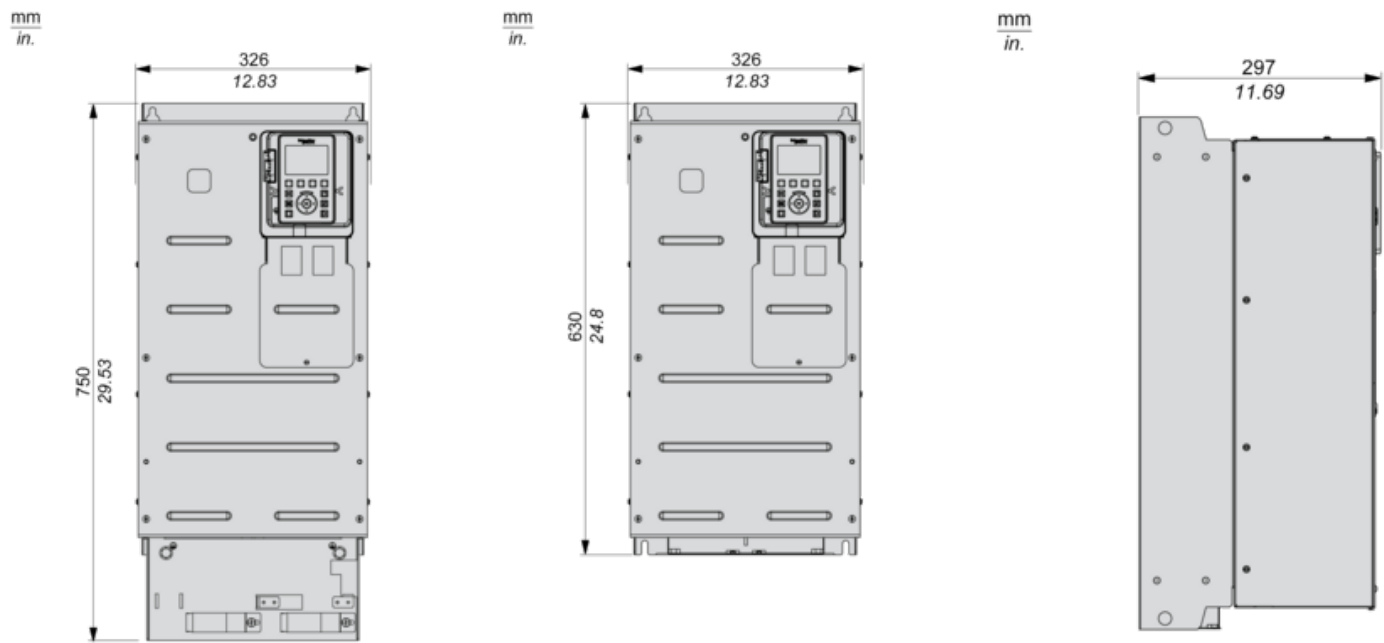
Sustainable offer status	Green Premium product
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REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov
Upgradeability	Upgraded components available ↗

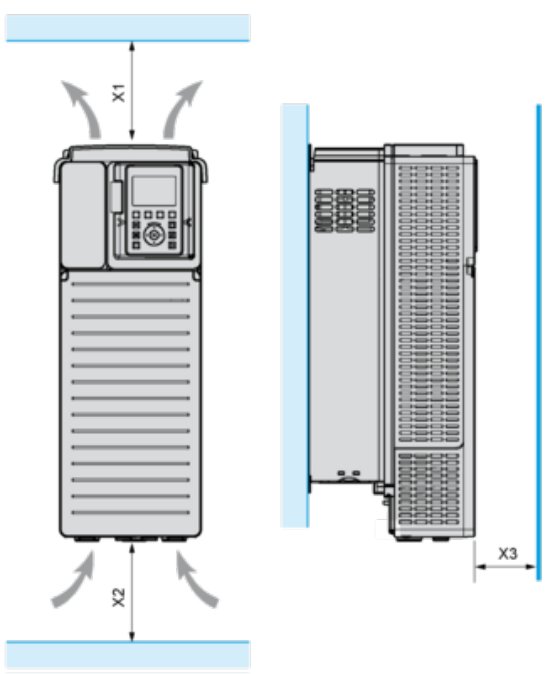
Dimensions

Drives without Top Cover

Front View with EMC Plate, Front, Left and Rear View without EMC Plate



Clearances

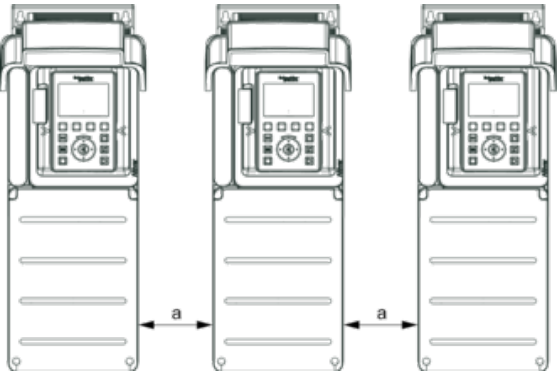


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- Mount the device in a vertical position (±10°). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

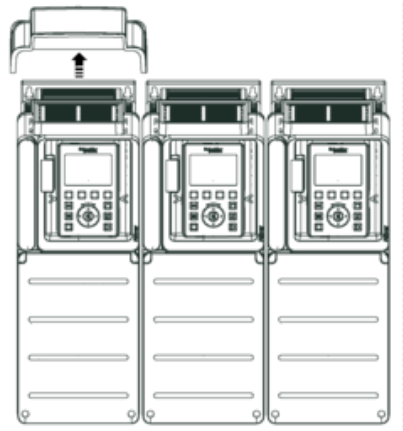
Mounting Types

Mounting Type A: Individual IP21

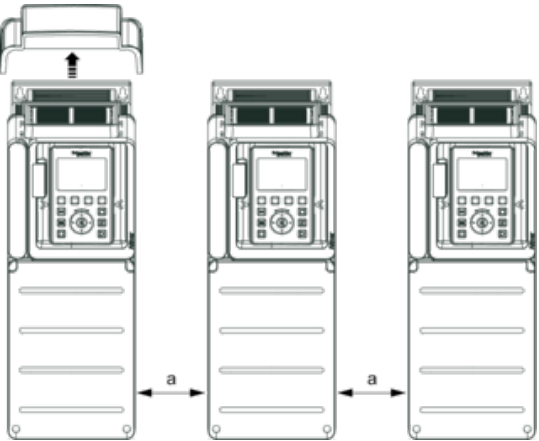


a ≥ 0

Mounting Type B: Side by Side IP20



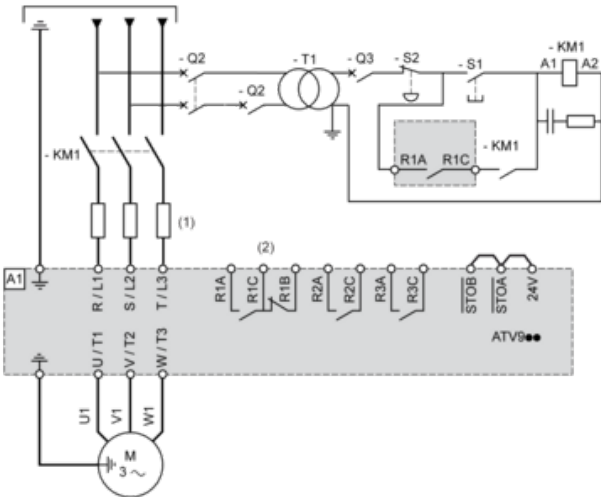
Mounting Type C: Individual IP20



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Three-Phase Power Supply with Upstream Breaking via Line Contactor

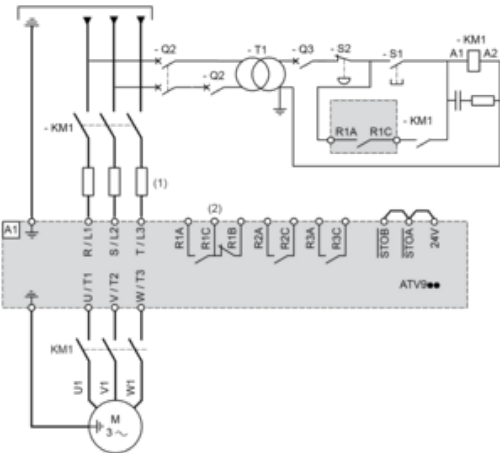
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
 - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive
- KM1 : Line Contactor
- Q2, Q3 : Circuit breakers
- S1, S2 : Pushbuttons
- T1 : Transformer for control part

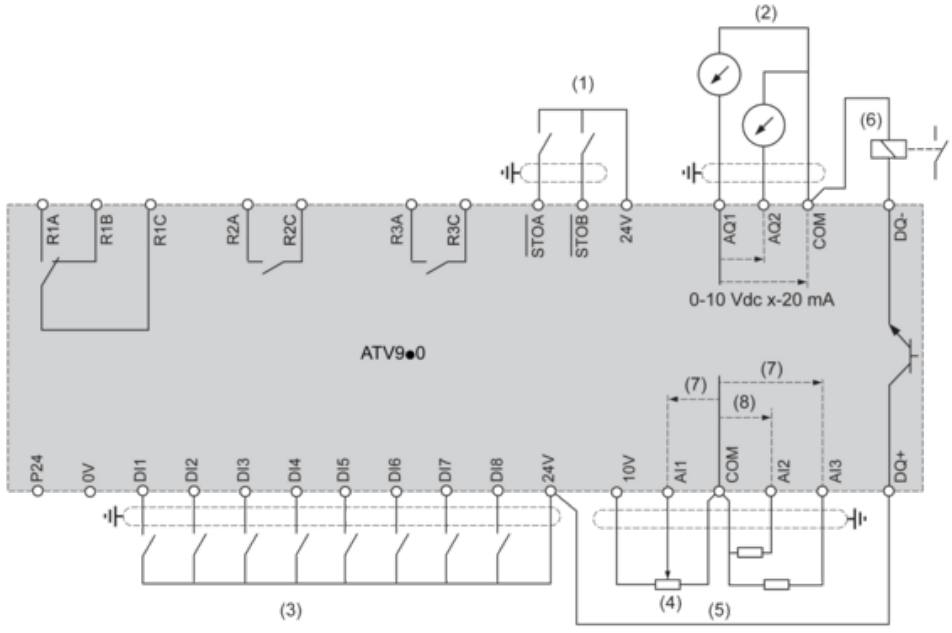
Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
 - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive
- KM1 : Contactor

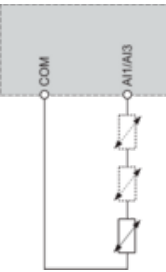
Control Block Wiring Diagram



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- (6) Digital Output
- (7) 0-10 Vdc, x-20 mA
- (8) 0-10 Vdc, -10 Vdc...+10 Vdc

R1A, R1B, R1C : Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

Sensor Connection



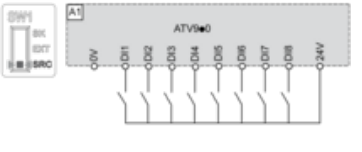
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

Sink / Source Switch Configuration

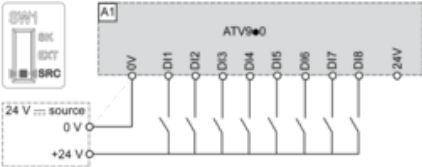
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

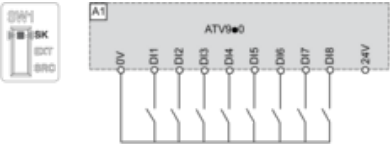
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



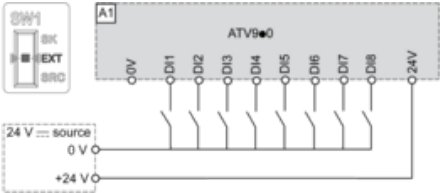
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



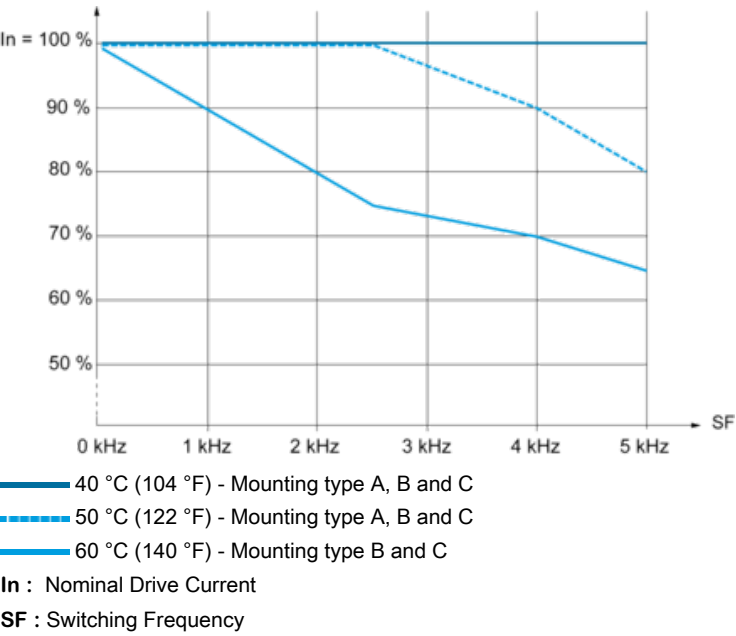
Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves



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