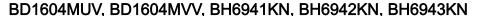


LED Drivers for LED Backlights

Backlight LED Driver for Small LCD Panels (Charge Pump Type)



No.11040EAT23

Description

This LSI series is a 4-6 white LED driver for small LCD backlight. At the charge pump type, the number of external devices is minimized.

Features

- 1) 4~6 parallel LED driver is mounted.
- 2) The LED current can be controlled via an external resistance.
- 3) Maximum current is 120mA (30mA × 4) (BD1604MUV/MVV).
- 4) Maximum of 20mA in each LED channel can be set (BH6941/42/43KN).
- 5) LED1 to LED4 can be turned on or off via an external control pin (BD1604MUV/MVV).
- 6) LEDs can be turned on or off via an external pin or the LED current can be changed in 4 steps (BH6941/42/43KN).
- 7) The relative current accuracy among LEDs (LED1 to LED4) is 3%.
- 8) Automatically transition to each mode (×1.0, ×1.5, ×2.0).
- 9) High efficiency (90% or more at maximum) is achieved.
- Various protection functions such as output voltage protection function, current overload limiter and thermal shutdown circuit are mounted.

Applications

This driver provides for:

- Backlight using white LED
- Auxiliary lights for mobile phone cameras and simplified flash (BD1604MUV/MVV)

Lineup

iloup					
Parameter	BH6941KN	BH6942KN	BH6943KN	BD1604MUV	BD1604MVV
Number of LED channels	4ch	5ch	6ch	4ch	4ch
Maximum current	80mA	75mA	90mA	120mA	120mA
Package	VQFN20 4.20mm×4.20mm	VQFN20 4.20mm×4.20mm	VQFN20 4.20mm×4.20mm	VQFN016V3030 3.00mm×3.00mm	SQFN016V4040 4.00mm×4.00mm

● Absolute Maximum Rating (Ta=25°C)

Paramet	er	Symbol	Ratings	Unit	
Dower gupply voltage	BH6941/42/43KN	Vmax	6.5	V	
Power supply voltage	BD1604MUV/MVV	VIIIax	7	V	
	BH6941/42/43KN		530 * ¹		
Allowable loss	BD1604MUV	Pd	700 * ²	mW	
	BD1604MVV		780 * ³		
Operating temperature range	BH6941/42/43KN	Tonr	-30~80	တ	
Operating temperature range	BD1604MUV/MVV	Topr	-30~85		
Storago tomporaturo rango	BH6941/42/43KN	Tstr	-55~125	သိ	
Storage temperature range	BD1604MUV/MVV	150	-55~150	C	

- *1 When a glass epoxy substrate (70mm×70mm×1.6mm) has been mounted, this loss will decrease 5.3mW/°C if Ta is higher than or equal to 25°C.
- *2 When a glass epoxy substrate (70mm×70mm×1.6mm) has been mounted, this loss will decrease 5.6mW/°C if Ta is higher than or equal to 25°C.
- *3 When a glass epoxy substrate (70mm×70mm×1.6mm) has been mounted, this loss will decrease 6.24mW°C if Ta is higher than or equal to 25°C.

Recommended Operation Range

Paramet	Symbol	Ratings	Unit	Condition	
BH6941/42/43KN		VBAT	2.8~4.5	\/	VBAT voltage
Operating supply voltage	BD1604MUV/MVV	VDAI	2.7~5.5	V	VBAT voltage

●Electrical Characteristics

[BH6941/42/43KN Circuit Current]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Symbol	Limits			Units	Condition
Farameter	Symbol	Min.	Тур.	Max.	Ullits	Condition
[Circuit current]						
Circuit current 0	IQ0	-	0	2	μA	Stand-by mode LED_SEL,CC1,CC2="L"
Circuit current 1.0	IQ1.0	-	1.2	-	mA	DC/DC CONVERTER ON, 1.0times mode,lo=0mA
Circuit current 1.5	IQ1.5	1	3.6	-	mA	DC/DC CONVERTER ON, 1.5times mode,lo=0mA
Circuit current 2.0	IQ2.0	-	3.4	-	mA	DC/DC CONVERTER ON, 2.0times mode,lo=0mA

[BD1604MUV/MVV Circuit Current]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Cymbal	Limits			Units	O and distant
	Symbol	Min.	Тур.	Max.	Units	Condition
[Circuit current]						
Circuit current 0	IQ0	-	0.1	1	μA	EN=0V
Circuit current 1.0	IQ1.0	-	1.0	2.0	mA	x1.0 Mode, lout = 0mA
Circuit current 1.5	IQ1.5	-	2.3	3.3	mA	x1.5 Mode, lout = 0mA
Circuit current 2.0	IQ2.0	-	2.5	3.5	mA	X2.0 Mode, lout = 0mA

[BH6941/42/43KN Current Driver]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Cumbal	Limits			Units	Condition				
	Symbol	Min.	Тур.	Max.	Units	Condition				
[Current driver]	[Current driver]									
Output current 1	lo1	-	1	-	mA	MIN Setting, Rref=100kΩ				
Output current 2	l02	-	10	-	mA	MID Setting, Rref=100kΩ				
Output current 3	Юз	-	20	-	mA	MAX Setting, Rref=100kΩ				
Output current 4	l04	-	15	-	mA	All ON Setting, Rref=100kΩ				
OFF leak current	ILEAK	-	-	±1.0	μA	V _{LED} =V _{CP} at power OFF				

[BD1604MUV/MVV Current Driver]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Cumbal	Limits			Units	Condition
	Symbol	Min.	Тур.	Max.	Units	Condition
[Current driver]						
LED maximum current	ILEDmax	-	-	30	mA	
LED current accuracy	ILEDdiff	-	0.5	5.0	%	ILED=10mA
LED current matching	ILEDmatch	-	0.5	3.0	%	ILED=10mA *1)
LED pin control voltage	VLED	0.08	0.10	0.20	V	Minimum voltage at LED1~LED4 pins
ISET voltage	ISET	0.5	0.6	0.7	V	
Oscillation frequency	Fosc	8.0	1.0	1.2	MHz	
Over current limiter	lov	-	600	900	mA	
LED current limiter	ILEDOV	40	60	100	mA	

^{*1)} LED current matching = (ILEDmax-ILEDmin)/(ILEDmax+ILEDmin)*100

ILEDmax : Maximum value of LED1-4 current ILEDmin : Minimum value of LED1-4 current

[BH6941/42/43KN Control Signal] Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Symbol		Limits		Units	Condition		
Parameter	Symbol	Min.	Тур.	Max.	Units	Condition		
[Control Signal etc.]								
Input 'H' voltage	VIH	1.4	-	VBAT+0.3	V			
Input 'L' voltage	VIL	-0.3	_	0.4	V			
Input 'H' current	Іін	-	0	±1	μΑ			
Input 'L' current	lıL	-	0	±1	μΑ			

[BD1604MUV/MVV Control Signal]

Unless otherwise specified, Ta is 25°C and VBAT is 5.5V.

Parameter	Symbol	Limits			Units	Condition	
Parameter	Symbol	Min.	Тур.	Max.	Ullits	Condition	
[Control Signal etc.]							
Input 'H' voltage	VIH	1.4	-	-	V	EN,SEL0,SEL1,SEL2	
Input 'L' voltage	VIL	-	-	0.4	V	EN,SEL0,SEL1,SEL2	
Input 'H' current1	IIH1	-	18.3	30	μA	EN=5.5V	
Input 'H' current2	IIH2	-	0	1	μA	SEL0,SEL1,SEL2=5.5V	
Input 'L' current	lıL	-1	0	-	μA	EN,SEL0,SEL1,SEL2=0V	

[BH6941/42/43KN UVLO]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Symbol	Limits			Units	Condition	
Farameter	Symbol	Min.	Тур.	Max.	Units	Condition	
[Control Signal etc.]							
UVLO detecting voltage	Vuvlo	2.1	-	2.6	V		

[BD1604MUV/MVV UVLO]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Doromotor	Cumbal	Limits			Units	Condition	
Parameter Symbol		Min.	Тур.	Max.	Units	Condition	
[Control Signal etc.]							
UVLO detecting voltage	Vuvlo	1.9	2.2	2.5	V		

[BH6941KN DC/DC Converter]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Symbol		Limits		- Units	Condition			
Farameter	Symbol	Min.	Тур.	Max.	Ullits				
[DC/DC converter]									
CPOUT voltage 1.0	VCP1.0	-	4.0	-	V	×1.0 mode ICPOUT=80mA, VBAT=4.2V			
CPOUT voltage 1.5	VCP1.5	4.35	4.5	4.65	V	×1.5 mode ICPOUT=1mA			
CPOUT current 1.5	ICP1.5	-	-	80	mA	×1.5 mode VCPOUT>4V, VBAT=3.6V			
CPOUT voltage 2.0	VCP2.0	4.35	4.5	4.65	V	×2.0 mode ICPOUT=1mA			
CPOUT current 2.0	ICP2.0	-	-	80	mA	×2.0 mode VCPOUT>4V, VBAT=3.0V			
Oscillation frequency	Fosc	-	1.2	-	MHz				

[BH6942KN DC/DC Converter]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Parameter	Cumbal	Limits		Units	O a readition	
Parameter	Symbol	Min.	Тур.	Max.	Units	Condition
[DC/DC converter]						
CPOUT voltage 1.0	VCP1.0	-	4.0	-	V	×1.0 mode ICPOUT=75mA, VBAT=4.2V
CPOUT voltage 1.5	VCP1.5	4.35	4.5	4.65	V	×1.5 mode ICPOUT=1mA
CPOUT current 1.5	ICP1.5	-	-	75	mA	×1.5 mode VCPOUT>4V, VBAT=3.6V
CPOUT voltage 2.0	VCP2.0	4.35	4.5	4.65	V	×2.0 mode ICPOUT=1mA
CPOUT current 2.0	ICP2.0	-	-	75	mA	×2.0 mode VCPOUT>4V, VBAT=3.0V
Oscillation frequency	Fosc	-	1.2	-	MHz	

[BH6943KN DC/DC converter]

Unless otherwise specified, Ta is 25°C and VBAT is 3.6V.

Devementer	C) mala al	Limits		Lleite	Consultátions	
Parameter	Symbol	Min.	Тур.	Max.	Units	Condition
[DC/DC converter]						
CPOUT voltage 1.0	VCP1.0	-	4.0	-	V	×1.0 mode ICPOUT=90mA, VBAT=4.2V
CPOUT voltage 1.5	VCP1.5	4.35	4.5	4.65	V	×1.5 mode ICPOUT=1mA
CPOUT current 1.5	ICP1.5	-	-	90	mA	×1.5 mode VCPOUT>4V, VBAT=3.6V
CPOUT voltage 2.0	VCP2.0	4.35	4.5	4.65	V	×2.0 mode ICPOUT=1mA
CPOUT current 2.0	ICP2.0	-	-	90	mA	×2.0 mode VCPOUT>4V, VBAT=3.0V
Oscillation frequency	Fosc	-	1.2	-	MHz	

●Reference Data

[BH6941/42/43KN] Evaluation under LED V_F=3.2V

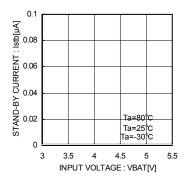


Fig.1 Circuit Current (BH6943KN Standby)

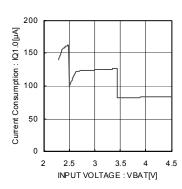


Fig.2 Circuit Current (BH6943KN Operation)

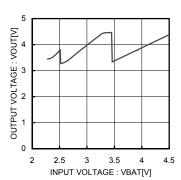


Fig.3 Output Voltage (BH6943KN Operation)

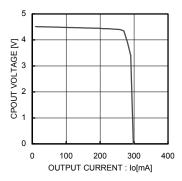


Fig.4 CPOUT Output Voltage vs.
Output Current
(BH6943KN)

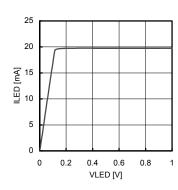


Fig.5 LED Output Current vs. Terminal Voltage (BH6943KN)

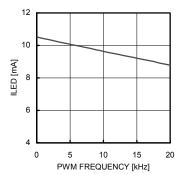


Fig.6 LED Output Current vs. PWM Frequency (BH6943KN)

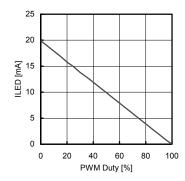


Fig.7 LED Output Current vs. PWM Duty (BH6943KN)

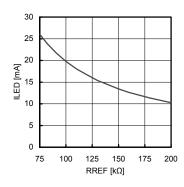


Fig.8 LED LED Output Current vs. RREF (BH6943KN)

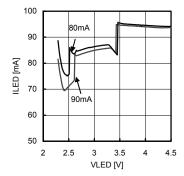
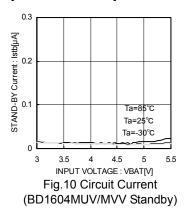
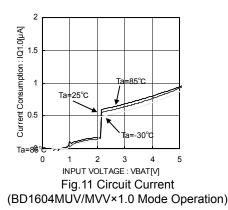


Fig.9 Efficiency (BH6943KN)

Evaluation under LED V_F=3.2V [BD1604MUV/MVV]





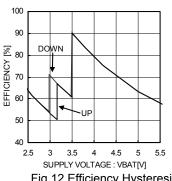
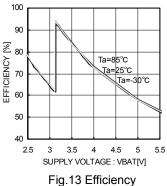
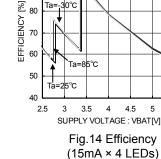


Fig.12 Efficiency Hysteresis (20mA × 4 LEDs) (BD1604MUV/MVV)



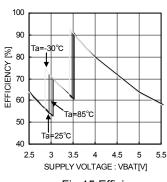
(5mA × 4 LEDs)

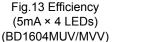


100

90

80





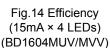
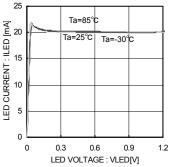
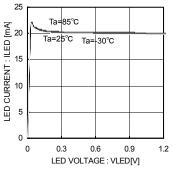


Fig.15 Efficiency (20mA × 4 LEDs) (BD1604MUV/MVV)





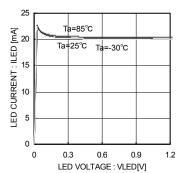
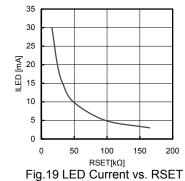


Fig.16 LED Current (20mA) (BD1604MUV/MVV VBAT=2.7V)

Fig.17 LED Current (20mA) (BD1604MUV/MVV VBAT=3.6V)

Fig.18 LED Current (20mA) (BD1604MUV/MVV VBAT=5.5V)



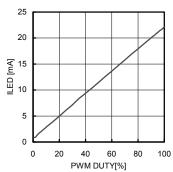


Fig.20 LED Current vs. PWM Duty (BD1604MUV/MVV Cycle 100Hz)

(BD1604MUV/MVV Ta=25°C)

Block Diagram, Recommended Circuit Example and Pin Location Diagram [BH6941/42/43KN]

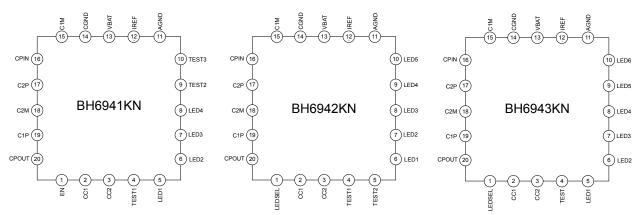


Fig.21 Pin Location Diagram (BH6941KN TOP View)

Fig.22 Pin Location Diagram (BH6942KN TOP View)

Fig.23 Pin Location Diagram (BH6943KN TOP View)

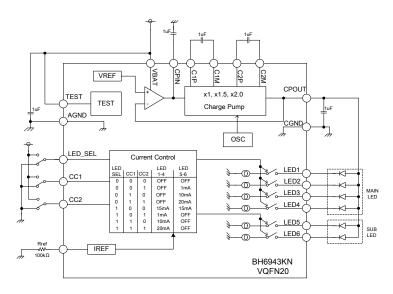


Fig.24 Block Diagram and Recommended Circuit Diagram (BH6943KN)

[BD1604MUV/MVV]

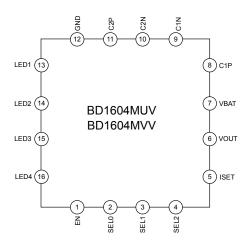


Fig.25 Pin Location Diagram (BD1604MUV/MVV Top View)

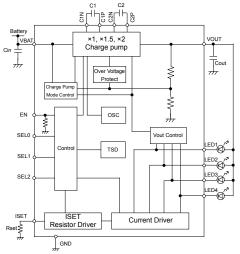


Fig.26 Block Diagram and Recommended Circuit Diagram (BD1604MUV/MVV)

[Pin table]				
Pin		Pin circuit		
name	BH6941KN	BH6942KN	BH6943KN	diagram
EN	1	-	-	L
LEDSEL	-	1	1	L
CC1	2	2	2	L
CC2	3	3	3	L
TEST	-	-	4	M
TEST1	4	4	-	M
TEST2	9	5	-	M
TEST3	10	-	-	M
LED1	5	6	5	0
LED2	6	7	6	0
LED3	7	8	7	0
LED4	8	9	8	0
LED5	-	10	9	0
LED6	-	-	10	0
AGND	11	11	11	I
IREF	12	12	12	N
VBAT	13	13	13	Н
CGND	14	14	14	I
C1M	15	15	15	Α
CPIN	16	16	16	J
C2P	17	17	17	Н
C2M	18	18	18	Н
C2P	19	19	19	Н
CPOUT	20	20	20	K

Pin	Pin nu	umber	Pin circuit
name	BD1604MUV	BD1604MVV	diagram
EN	1	1	F
SEL0	2	2	Е
SEL1	3	3	Е
SEL2	4	4	Е
ISET	5	5	G
VOUT	6	6	С
VBAT	7	7	Н
C1P	8	8	В
C1N	9	9	Α
C2N	10	10	Α
C2P	11	11	В
GND	12	12	I
LED1	13	13	D
LED2	14	14	D
LED3	15	15	D
LED4	16	16	D

●I/O Equivalence Circuit Diagram

The following shows I/O equivalence circuits.

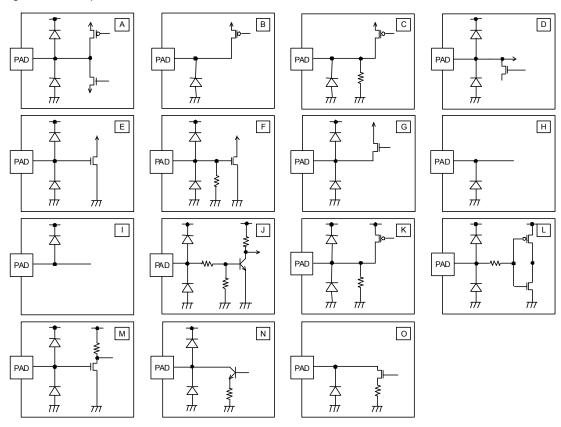


Fig.27 Pin Diagram

Description of Block Operations

1)LED light control and current control

When LED lights are controlled, H- or L-level voltage is applied to respective control pins.

Current control in the BH6941/42/43KN can take place via a control pin, and that in the BD1604MUV/MVV can take place via a resistance connected to the ISET pin.

[BH6941KN]

EN	CC1	CC2	LED1~4
0	0	0	OFF
1	0	0	15mA
1	0	1	1mA
1	1	0	10mA
1	1	1	20mA

Rref=100kΩ, 0 : 0V, 1 : VBAT

[BH6942/43KN]

[D110372/731(11]				
LEDSEL	CC1	CC2	LED1~3(4:43KN)	LED4~5(5~6:43KN)
0	0	0	OFF	OFF
0	0	1	OFF	1mA
0	1	0	OFF	10mA
0	1	1	OFF	20mA
1	0	0	15mA	15mA
1	0	1	1mA	OFF
1	1	0	10mA	OFF
1	1	1	20mA	OFF

Rref=100k Ω , 0 : 0V, 1 : VBAT

[BD1604MUV/MVV]

ON/OFF control

SEL2	SEL1	SEL0	LED1	LED2	LED3	LED4
0	0	0	OFF	OFF	OFF	ON
0	0	1	OFF	OFF	ON	OFF
0	1	0	OFF	ON	OFF	OFF
0	1	1	ON	OFF	OFF	OFF
1	0	0	OFF	OFF	ON	ON
1	0	1	OFF	ON	ON	ON
1	1	0	ON	ON	ON	ON
1	1	1	OFF	OFF	OFF	OFF

Rset: See the following table. 0: 0V, 1: VBAT

When handling pins, the LED pins must be connected to VBAT so long as LED is always OFF.

Current control

	• •					
Rset	165kΩ	97.6kΩ	48.7kΩ	32.4kΩ	24.3kΩ	16.2kΩ
ILED	3mA	5mA	10mA	15mA	20mA	30mA

The LED current can be changed by the Rset value.

ILED=480/Rset

The above expression can be used for approximation.

2)Low supply voltage detection circuit (UVLO)

When the IC-applied supply voltage drops, all the circuits including the DC/DC converter are stopped. When supply voltage drops to a detecting voltage, UVLO is activated. When it rises, UVLO is automatically released.

3) Soft start by DC/DC converter startup

When a DC/DC converter is started, soft start is enabled so that output voltage can be increased gradually to prevent output voltage overshooting.

Application Parts Selection Method

[BH6941/42/43KN]

Capacitor (Use the ceramics parts with good frequency and temperature characteristics.)

Symbol	Recommended value	Recommended part	Туре
Cpout, Cpin, Cin,C1,C2	1µF	GRM188B11A105KA61B(MURATA)	Ceramics capacitor

Resistance

Symbol	Recommended value	Recommended part
Rref	100kΩ	MCR006YZPF1003(ROHM)

Connect an input bypass capacitor (CIN) between VBAT and GNDA pin in proximity. In addition, connect an output capacitor between CPOUT and GND pins in proximity. Connect a capacitor between C1M and C1P and also a capacitor between C2M and C2P in proximity to the chips. Connect a resistance to the IREF pin in proximity. Connect the AGND pin to the CGND pin directly. When these pins are not directly connected near the chips, the performance of BH6943 to BH6941KN is affected and the current drive performance may be limited.

[BD1604MUV/MVV]

Capacitor (Use the ceramics parts with good frequency and temperature characteristics.)

Symbol	Recommended value	Recommended part	Туре
Cout,Cin,C1,C2	1µF	GRM188B11A105KA61B(MURATA)	Ceramics capacitor

Resistance

Symbol	Recommended value	Recommended part	Set Current Value
	16kΩ		30mA
Rset	~	MCR006YZPF Series (ROHM)	~
	240kΩ		2mA

Connect an input bypass capacitor (CIN) between VBAT and GND pin in proximity. In addition, connect an output capacitor between VOUT and GND pins in proximity. Connect a capacitor between C1P and C1N and also a capacitor between C2P and C2N in proximity to the chips. Connect a resistance in proximity to the ISET pin.

When other than these parts are used, the equivalent parts must be used.

Cautions on layout pattern

When designing a layout pattern, lay out wires to a power line in a way that the layout pattern impedance can be minimized and connect a bypass capacitor if necessary.

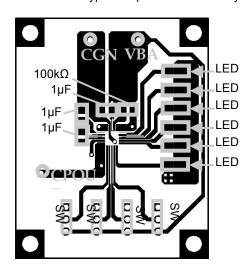


Fig.28 Example of BH6943KN Layout Pattern (Front, Top View) (Rear, Top View)

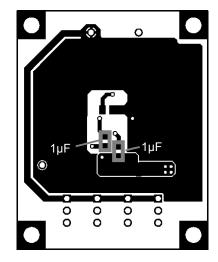
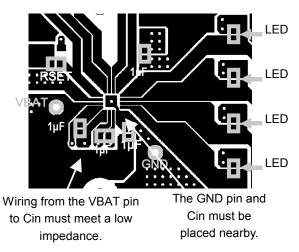


Fig.29 Example of BH6943KN Layout Pattern



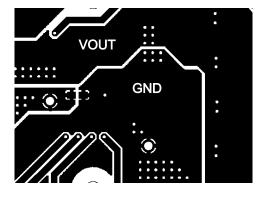


Fig.30 Example of BD1604MUV Layout Pattern (Front, Top View) (Rear, Top View)

Fig.31 Example of BD1604MUV Layout Pattern

●LED Current Control

There are two methods for LED current control. One method uses an external PWM signal and another changes the resistance value of RREF (RSET) connected to the IREF (ISET) pin. For details, refer to the respective circuit examples. Don't make the setting of 20mA or more per channel for BH6941/42/43KN and the setting of 30mA or more per channel for MD1604MUV/MVV.

[BH6941/42/43KN]

- 1) Controlling the current by using the PWM method
 - As seen from Fig.32, LED current control can be performed via the PWM signal (amplitude: 0V to VBAT) input to the Rref controller. This PWM signal must be input 15msec later because the time is taken for charge pump circuit activation, soft start and pressor magnification determination after the current control logic is input to the LED control pins (LEDSEL, CC1 and CC2).
- 2) Controlling the current by changing the RSET resistance value Rref=Rref1//Rref2// //Rrefn.

This means that the current can be adjusted more finely by adding the types of resistance values.

ILED =
$$\frac{1V}{\text{Rref}} \times 2000 [A]$$
 : When 20mA is set

The LED pin current can be obtained from the above expression.

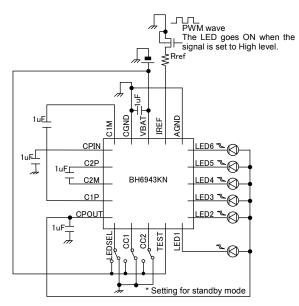


Fig.32 Controlling the Current in the BH6941/42/43KN by Using the PWN Method

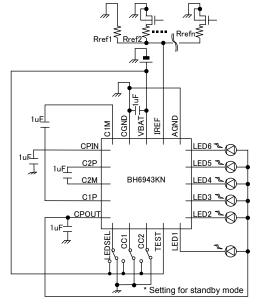


Fig.33 Controlling the Current in the BH6941/42/43KN by Changing the Resistance Value

[BD1604MUV/MVV]

1)Controlling the current by using the PWM method

The PWN signal must be input to the EN pin.

PWM signal "H" level: 1.4V or more PWM signal "L" level: 0.4V or less

When PWM Duty is used in an area of 10% or less, the PWM cycle must be a range from 100Hz to 200Hz. When extremely high-speed PWM control takes place, the linearity of LED current value to PWM duty is lost if the PWM duty is small (for example, 10% or less) or it is large (for example, 90% or more).

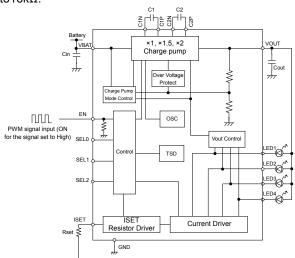
2) Controlling the current by changing the SET resistance value

Rset-Rset1=Rset2// ... //Restn.

This means that the current can be adjusted more finely by adding the types of resistance values.

ILED=480/Rset [A]

The approximate LED current can be obtained from the above expression. Because the current of 30mA or more per LED is not permitted, make the setting in a way that the Rset resistance value can be maintained to be greater than or equal $to16k\Omega$.



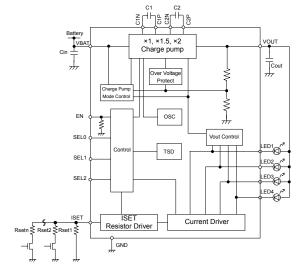


Fig.34 Controlling the Current in the BD1604MUV/MVV by Using the PWM Method

Fig.35 Controlling the Current in the BD1604MUV/MVV by Changing the Resistance Value

Notes for Use

(1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

(2) Operating conditions

These conditions represent a range within which characteristics can be provided approximately as expected. The electrical characteristics are quaranteed under the conditions of each parameter.

(3) Reverse connection of power supply connector

The reverse connection of power supply connector can break down ICs. Take protective measures against the breakdown due to the reverse connection, such as mounting an external diode between the power supply and the IC's power supply terminal.

(4) Power supply line

Design PCB pattern to provide low impedance for the wiring between the power supply and the GND lines. In this regard, for the digital block power supply and the analog block power supply, even though these power supplies has the same level of potential, separate the power supply pattern for the digital block from that for the analog block, thus suppressing the diffraction of digital noises to the analog block power supply resulting from impedance common to the wiring patterns. For the GND line, give consideration to design the patterns in a similar manner.

Furthermore, for all power supply terminals to ICs, mount a capacitor between the power supply and the GND terminal. At the same time, in order to use an electrolytic capacitor, thoroughly check to be sure the characteristics of the capacitor to be used present no problem including the occurrence of capacity dropout at a low temperature, thus determining the constant.

(5) GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

(6) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

(7) Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.

(8) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

(9) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals, such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the power supply voltage or within the guaranteed value of electrical characteristics.

(10) Ground wiring pattern

If small-signal GND and large-current GND are provided, It will be recommended to separate the large-current GND pattern from the small-signal GND pattern and establish a single ground at the reference point of the set PCB so that resistance to the wiring pattern and voltage fluctuations due to a large current will cause no fluctuations in voltages of the small-signal GND. Pay attention not to cause fluctuations in the GND wiring pattern of external parts as well.

(11) External capacitor

In order to use a ceramic capacitor as the external capacitor, determine the constant with consideration given to a degradation in the nominal capacitance due to DC bias and changes in the capacitance due to temperature, etc.

(12) Not connecting input terminals

In terms of extremely high impedance of CMOS gate, to open the input terminals causes unstable state. Unstable state occurs from the inside gate voltage of p-channel or n-channel transistor into active. As a result, power supply current may increase. And unstable state can also cause unexpected operation of IC. So unless otherwise specified, input terminals not being used should be connected to the power supply or GND line.

(13) Thermal shutdown circuit (TSD)

When junction temperatures become setting temperature or higher, the thermal shutdown circuit operates and turns a switch OFF. The thermal shutdown circuit, which is aimed at isolating the LSI from thermal runaway as much as possible, is not aimed at the protection or guarantee of the LSI. Therefore, do not continuously use the LSI with this circuit operating or use the LSI assuming its operation.

(14) Thermal design

Perform thermal design in which there are adequate margins by taking into account the permissible dissipation (Pd) in actual states of use.

Thermal Loss

The following conditions must be met for thermal design. (Because the following temperature is only the assured temperature, be sure to consider the margin for design.)

- 1. The ambient temperature Ta must be 80°C for BH6941/42/43KN or 85°C for BD1604MUV/MVV.
- 2. The IC loss must be smaller than an allowable loss (Pd).

●Power dissipation character

The following shows the power dissipation character.

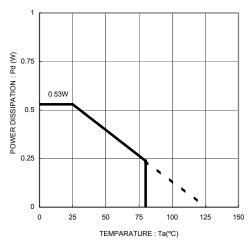


Fig.36 BH6941/42/43KN

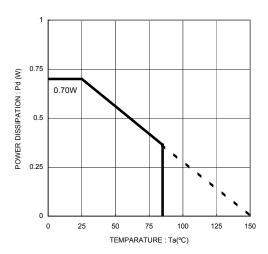


Fig.38 BD1604MUV

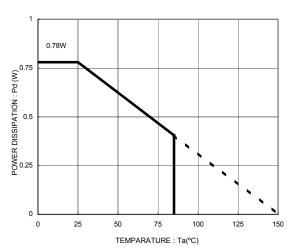
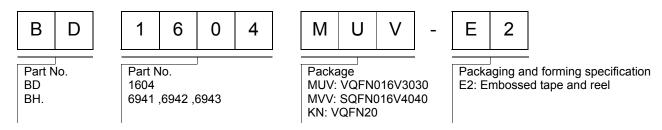


Fig.37 BD1604MVV

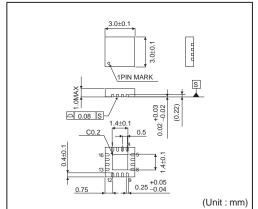
Mount board specification
Material: Glass epoxy

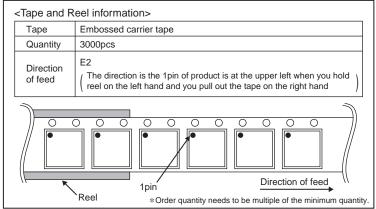
size: 70mm × 70mm × 1.6mm

Ordering part number

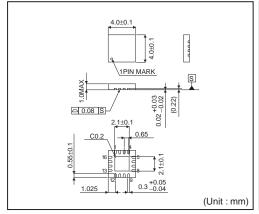


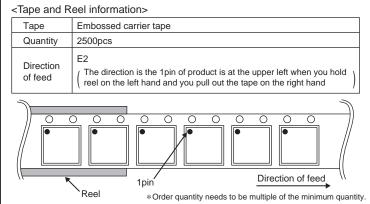
VQFN016V3030



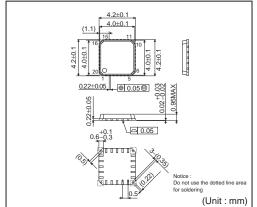


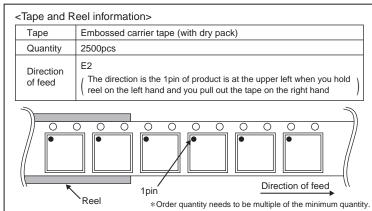
SQFN016V4040





VQFN20





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