

1.65V to 3.6V

±15.0mT(Typ)

0.9mT(Typ)

50ms(Typ)

5.0µA (Typ)

-40°C to +85°C

CMOS

Omnipolar Detection Hall IC

(Dual Outputs for both S and N Pole Polarity Detection)

BU52177GXZ

General Description

The BU52177GXZ is omnipolar Hall IC incorporating a polarity determination circuit that enables separate operation (output) of both the South and North poles. This Hall IC product can be in tablets, smart phones, and

other applications in order to detect open and close of the cover.

And this Hall IC product can be in digital video cameras and other applications involving display panels in order to detect the front/back location or determine the rotational direction of the panel.

Features

- Omnipolar Detection (Polarity Detection for both S and N Poles with Separate. Dual Outputs)
- Micro Power Operation (Small Current Using Intermittent Operation Method)
- Ultra-compact CSP4 Package (XCSP30L1)
- Polarity Judgment and Separate Output on both Poles (OUT1=S-pole Output; OUT2=N-pole Output)

Applications

Tablets, Smart Phones, Notebook Computers, Digital Video Cameras, Digital Still Cameras, etc.

Key Specifications

- V_{DD} Voltage Range:
- Operate Point:
- Hysteresis: Period:
- Supply Current (AVG):
- Output Type:
- **Operating Temperature Range:**

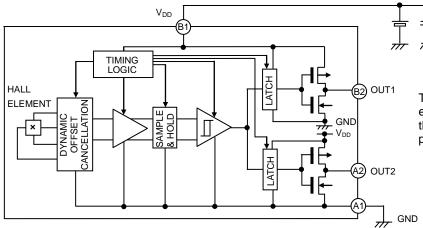
W(Typ) x D(Typ) x H(Max)

Package XCSP30L1

0.65mm x 0.65mm x 0.33mm



Typical Application Circuit, Block Diagram, Pin Configurations and Pin Descriptions



0.1µF Adjust the bypass capacitor value as necessary, according to voltage

noise conditions, etc.

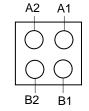
The CMOS output terminals enable direct connection to the PC, with no external pull-up resistor required.

Pin No. Pin Name Function A1 GND Ground A2 OUT2 Output (React to the north pole) B1 V_{DD} Power supply B2 OUT1 Output (React to the south pole)





(BOTTOM VIEW)



OProduct structure : Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

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Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Rating	Unit
Power Supply Voltage	V _{DD}	-0.1 to +4.5 ^(Note 1)	V
Output Current	I _{OUT}	±0.5	mA
Power Dissipation	Pd	0.44 ^(Note 2)	W
Operating Temperature Range	T _{opr}	-40 to +85	°C
Storage Temperature Range	T _{stg}	-40 to +125	°C

(Note 1) Not to exceed Pd

(Note 2) Derate by 4.4mW/°C when operating above Ta=25°C (when mounted in 60mm x 60mm x 1.6mm size glass epoxy board). **Caution:** Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions (Ta= -40°C to +85°C)

Parameter	Symbol	Min	Тур	Max	Unit
Power Supply Voltage	V_{DD}	1.65	1.80	3.60	V

Magnetic, Electrical Characteristics (Unless otherwise specified V_{DD}=1.80V Ta=25°C)

Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Or angle Deint	BopS	-	15.0	19.0	mT	Output: OUT1 (React to the south pole)
Operate Point	B _{opN}	-19.0	-15.0	-		Output: OUT2 (React to the north pole)
Release Point	B _{rpS}	10.1	14.1	-	mT	Output: OUT1 (React to the south pole)
	B _{rpN}	-	-14.1	-10.1		Output: OUT2 (React to the north pole)
Hysteresis	B _{hysS}	-	0.9	-	mT	
	B _{hysN}	-	0.9	-		
Period	Tp	-	50	100	ms	
Output High Voltage	V _{OH}	V _{DD} -0.2	-	-	V	B _{rpN} <b<b<sub>rpS ^(Note 3) I_{OUT}=-0.5mA</b<b<sub>
Output Low Voltage	V _{OL}	-	-	0.2	V	B <b<sub>opN, B_{opS}<b <sup="">(Note 3) I_{OUT}=+0.5mA</b<sub>
Supply Current	I _{DD(AVG)}	-	5	8	μA	Average
Supply Current During Startup Time	I _{DD(EN)}	-	2.8	-	mA	During startup time value
Supply Current During Standby Time	I _{DD(DIS)}	-	1.8	-	μA	During standby time value

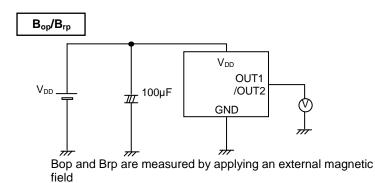
(Note 3) B = Magnetic Flux Density

1mT=10Gauss

Positive ("+") polarity flux is defined as the magnetic flux from south pole which is direct toward to the branded face of the sensor.

After applying power supply, it takes one cycle of period (T_P) to become definite output.

Measurement Circuit





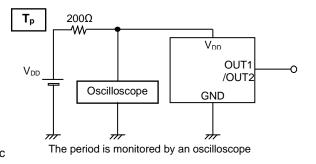


Figure 2. T_{p} Measurement Circuit

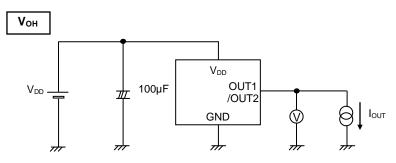


Figure 3. V_{OH} Measurement Circuit

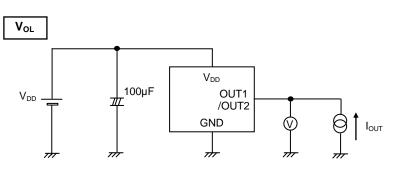


Figure 4. VoL Measurement Circuit

IDD

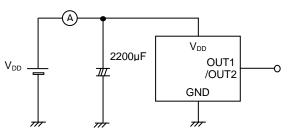


Figure 5. IDD Measurement Circuit

Typical Performance Curves

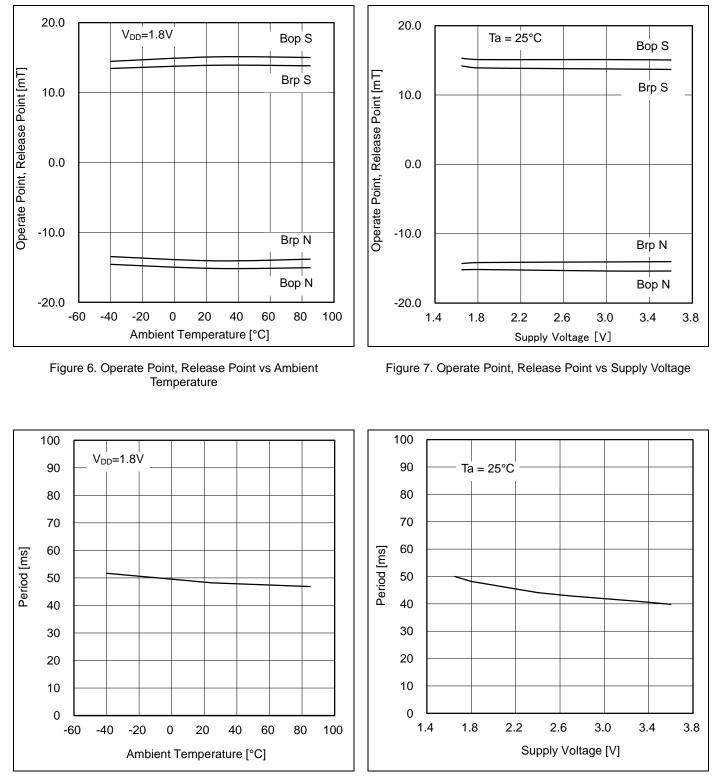


Figure 8. Period vs Ambient Temperature

Figure 9. Period vs Supply Voltage

Typical Performance Curves - continued

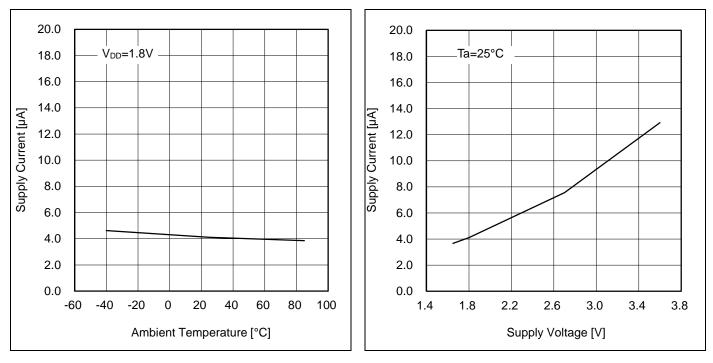
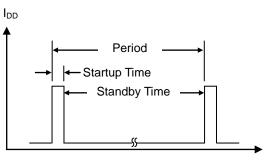


Figure 10. Supply Current vs Ambient Temperature

Figure 11. Supply Current vs Supply Voltage

Description of Operations

Micropower Operation (Small Current Consumption Using Intermittent Sensing)

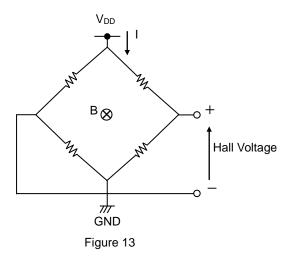




The dual output omnipolar detection Hall IC uses intermittent sensing save energy. At startup the Hall elements, amplifier, comparator, and other detection circuits power on and magnetic detection begins. During standby, the detection circuits power off, thereby reducing current consumption. The detection results are held while standby is active, and then output.

Reference Period: 50ms (MAX100ms) Reference Startup Time: 48µs

(Offset Cancellation)



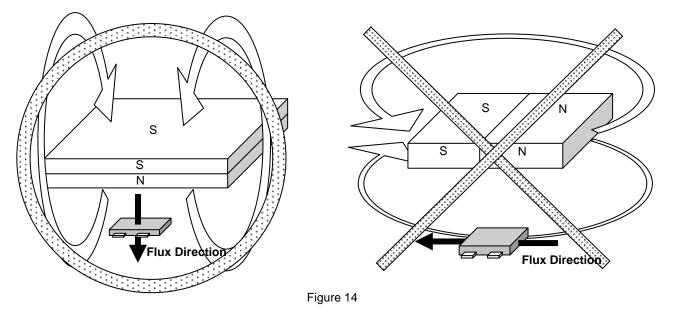
The Hall elements form an equivalent Wheatstone (resistor) bridge circuit. Offset voltage may be generated by a differential in this bridge resistance, or can arise from changes in resistance due to package or bonding stress. A dynamic offset cancellation circuit is employed to cancel this offset voltage.

When the Hall elements are connected as shown in Figure 13 and a magnetic field is applied perpendicular to the Hall elements, a voltage is generated at the mid-point terminal of the bridge. This is known as Hall voltage.

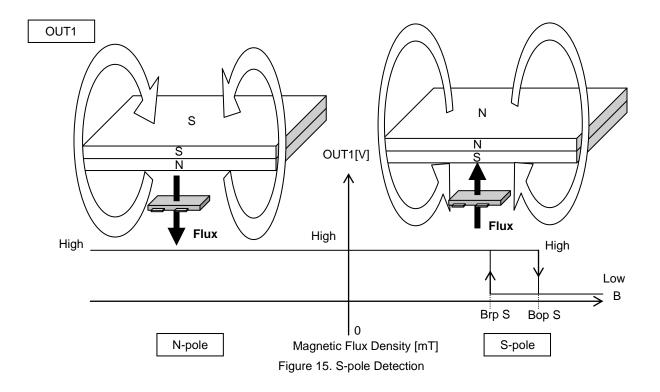
Dynamic cancellation switches the wiring (shown in the figure) to redirect the current flow to a 90° angle from its original path, and thereby cancels the Hall voltage.

The magnetic signal (only) is maintained in the sample/hold circuit during the offset cancellation process and then released.

(Magnetic Field Detection Mechanism)



The Hall IC cannot detect magnetic fields that run horizontal to the package top layer. Be certain to configure the Hall IC so that the magnetic field is perpendicular to the top layer.



The OUT1 pin detects and outputs for the S-pole only. Since the OUT1 pin output is unipolar, the output does not respond to the N-pole.

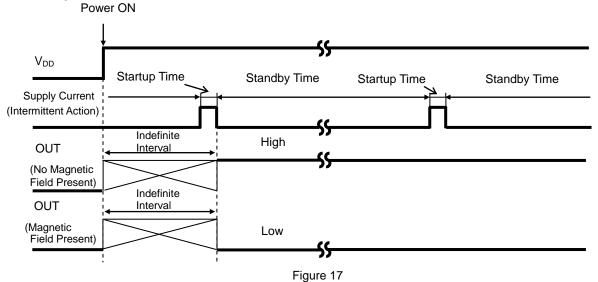
BU52177GXZ

OUT2 N S S Ν OUT2[V] Flux Flux High High High Low В Brp N Bop N 0 N-pole S-pole Magnetic Flux Density [mT] Figure 16. N-pole Detection

The OUT2 pin detects and outputs for the N-pole only. Since the OUT2 pin output is unipolar, the output does not respond to the S-pole. The dual output omnipolar detection Hall IC detects magnetic fields running perpendicular to the top surface of the package. There is an inverse relationship between magnetic flux density and the distance separating the magnet and the Hall IC: when distance increases magnetic density falls. When it drops below the operate point (Bop), output goes HIGH. When the magnet gets closer to the IC and magnetic density rises to the operate point, the output switches LOW. In LOW output mode, the distance from the magnet to the IC increases again until the magnetic density falls to a point just below Bop, and output returns HIGH. The point where magnetic flux density restores a HIGH output is known as the release point, Brp. This detection and adjustment mechanism is designed to prevent noise, oscillation, and other erratic system operation.

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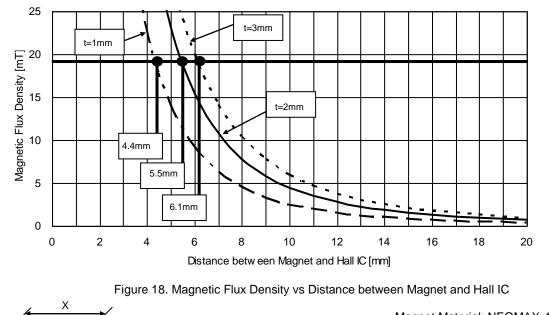
Intermittent Operation at Power ON



The dual output omnipolar detection Hall IC adopts an intermittent operation method in detecting the magnetic field during startup, as shown in Figure 17. The IC outputs to the appropriate terminal based on the detection result and maintains the output condition during the standby period. The time from power ON until the end of the initial startup period is an indefinite interval, but it cannot exceed the maximum period of 100ms. To accommodate the system design, the Hall IC output read should be programmed within 100ms of power ON, but after the time allowed for the period, ambient temperature, and supply voltage.

Magnet Selection

Of the two representative varieties of permanent magnet, neodymium generally offers greater magnetic power per volume than ferrite, thereby enabling the highest degree of miniaturization, thus, neodymium is best suited for small equipment applications. Figure 18 shows the relation between the size (volume) of a neodymium magnet and magnetic flux density. The graph plots the correlation between the distance (L) from three versions of a 4mm x 4mm cross-section neodymium magnet (1mm, 2mm, and 3mm thick) and magnetic flux density. Figure 19 shows Hall IC detection distance – a good guide for determining the proper size and detection distance of the magnet. Based on the BU52177GXZ operating point max of 19.0mT, the minimum detection distance for the 1mm, 2mm and 3mm magnets would be 4.4mm, 5.5mm, and 6.1mm, respectively. To increase the magnet's detection distance, either increases the magnet's thickness or sectional area.



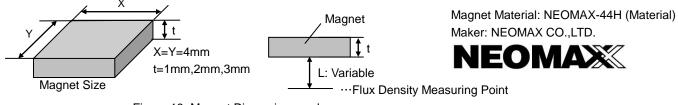
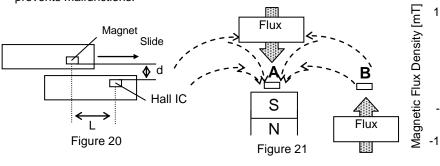


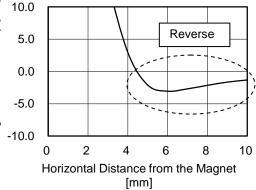
Figure 19. Magnet Dimensions and Flux Density Measuring Point

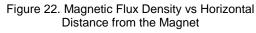
Slide-by Position Sensing

BU52177GXZ

Figure 20 depicts the slide-by configuration employed for position sensing. Note that when the gap (d) between the magnet and the Hall IC is narrowed, the reverse magnetic field generated by the magnet can cause the IC to malfunction. As seen in Figure 21, the magnetic field runs in opposite directions at Point A and Point B. Since the dual output omnipolar detection Hall IC can detect the S-pole at Point A and the N-pole at Point B, the sensor can switch the output ON as the magnet slides by in the process of position detection. Figure 22 plots magnetic flux density during the magnet slide-by. Although a reverse magnetic field was generated in the process, the magnetic flux density decreases compared with the center of the magnet. This demonstrates that slightly widening the gap (d) between the magnet and Hall IC reduces the reverse magnetic field and prevents malfunctions.

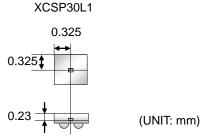






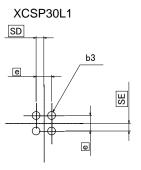
Position of the Hall Element

(Reference)



Footprint Dimensions

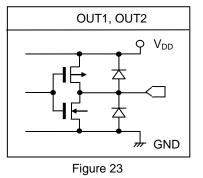
(Optimize footprint dimensions to the board design and soldering condition)



Symbol	Reference value
е	0.35
b3	φ0.18
SD	0.175
SE	0.175

(UNIT: mm)

I/O Equivalence Circuit



The Hall ICs output pins are configured for CMOS (inverter) output removing the need for external resistance and allow direct connection to the host. Removing the need for external resistors allows for reduction of the current that would otherwise flow to the external resistor during magnetic field detection thereby supporting an overall lower current (micropower) operation.

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

Operational Notes – continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

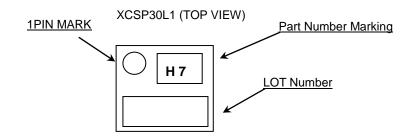
15. Disturbance light

In a device where a portion of silicon is exposed to light such as in a WL-CSP, IC characteristics may be affected due to photoelectric effect. For this reason, it is recommended to come up with countermeasures that will prevent the chip from being exposed to light.

Ordering Information

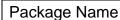


Marking Diagrams

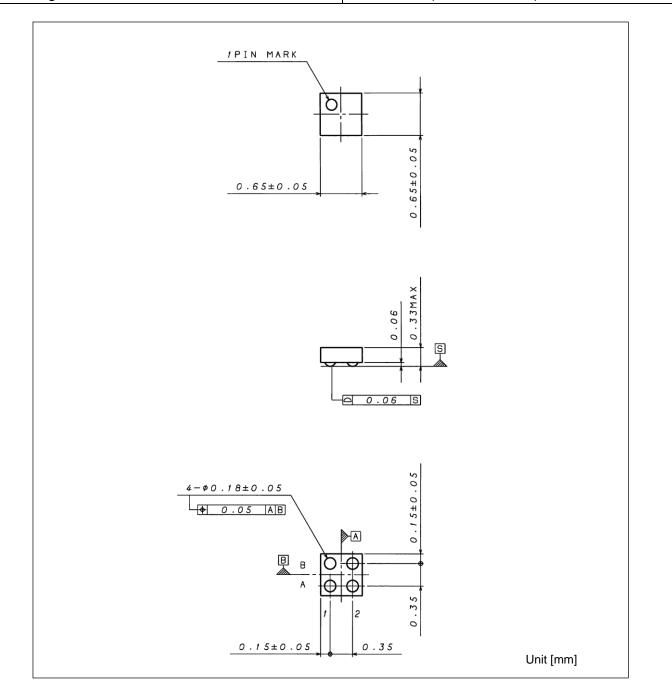


Datasheet

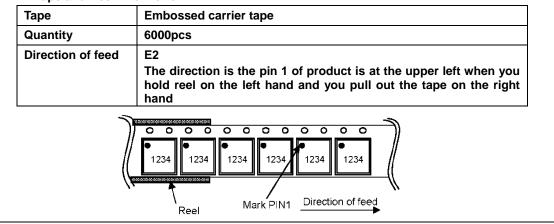




XCSP30L1(BU52177GXZ)



< Tape and Reel Information >



Revision History

Date	Revision	Changes
6.Feb.2015	001	New Release
25.Jul.2016	002	Change of the physical dimension tolerance

Notice

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JÁPAN	USA	EU	CHINA	
CLASSⅢ	CLASSII	CLASS II b		
CLASSⅣ	CLASSII	CLASSⅢ	CLASSII	

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 - [f] Sealing or coating our Products with resin or other coating materials
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- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
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- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

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- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
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 - [c] the Products are exposed to direct sunshine or condensation
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- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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