

0.5 Amp or Less Reversible Motor Drivers (Single Motor)

BH6578FVM BD7931F

General Description

The BH6578FVM and BD7931F are reversible motor drivers with a wide output dynamic range, with power MOS used for the output transistor. The motor drivers can be set to four output modes 1) forward (normal) rotation, 2) reverse rotation, 3) stop (idling or OFF) and 4) brake using 2 logic inputs.

Features

- Wide dynamic range loading driver with MOS
 - output, $R_{ON} = 1.0\Omega$ (Top + Bottom)
- With loading driver voltage setting terminal
- Built-in Thermal Shutdown Circuit (TSD)

Applications

Tray loading of CD/DVD, applications using DC motors

Key Specifications

- Supply Voltage Range: BH6578FVM BD7931F
- Standby Current: BH6578FVM 0.4mA (Typ) BD7931F 0μA (Typ)
 ON-Resistance(Top + Bottom): 1.0Ω (Typ)
- Operating Temperature Range: BH6578FVM BD7931F

-35°C to +85°C -40°C to +85°C

4.5V to 5.5V

4.5V to 14V

Packages

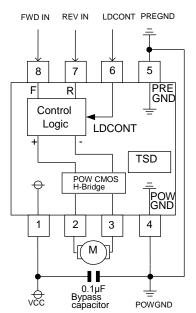
W(Typ) x D(Typ) x H(Max)



Typical Application Circuit, Block Diagram, Pin Configuration and Pin Descriptions

BH6578FVM, BD7931F (in common)

TOP VIEW



Pin No.	Pin Name	Function
1	VCC	Supply voltage
2	OUT+	FWD output
3	OUT-	REV output
4	GND	Power ground
5	GND_S	Signal ground
6	LDCONT	Loading driver voltage setting pin
7	INREV	REV input
8	INFWD	FWD input

OProduct structure : Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Ra	Unit	
Faranieter	Symbol	BH6578FVM	BD7931F	Unit
Supply Voltage	Vcc	7	15	V
Power Dissipation	Pd	0.55 (Note 1)	0.69 (Note 2)	W
Operating Temperature	Topr	-35 to +85	-40 to +85	°C
Storage Temperature	Tstg	-55 to +150		°C
Output Current	Іоит	500		mA
Junction Temperature	Tjmax	1:	50	°C

(Note 1) When 70 mm x 70 mm x 1.6 mm thick glass epoxy substrate with less than 3% copper foil occupancy ratio is mounted. When used at Ta=25°C or higher, derated at 4.4 mW/°C.

(Note 2) When 70 mm x 70 mm x 1.6 mm thick glass epoxy substrate with less than 3% copper foil occupancy ratio is mounted. When used at Ta=25°C or higher, derated at 5.5 mW/°C.
Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions

Parameter	Symbol	BH6578FVM			BD7931F			単位
Farameter	Symbol	Min	Тур	Max	Min	Тур	Max	中世
Supply Voltage	Vcc	4.5	5	5.5	4.5	8	14	V

Truth Table

BH6578FVM, BD7931F

INPUT		OUT	PUT	Function
INFWD	INREV	OUT+	OUT-	Function
L	L	Hi-Z	Hi-Z	High Impedance
L	Н	L	Н	REV mode
Н	L	Н	L	FWD mode
Н	Н	L	L	Brake mode

Hi-Z : Hi-impedance

Electrical Characteristics

BH6578FVM (Unless otherwise specified, Ta=25°C, V_{CC}=5V)

Parameter	Sympol	Limit			Unit	Conditions
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Standby Current	lcc	-	0.4	0.8	mA	No load
(Loading Driver)						
Output Offset Voltage	Vofsl	-15	0	+15	mV	Brake mode
Input Voltage H Level	Vін	2.0	-	Vcc	V	
Input Voltage L Level	VIL	GND	-	0.5	V	
ON-Resistance	Ron	-	1.0	1.8	Ω	Iout=500mA,Top + Bottom
Voltage Gain	Gvld	4.5	6.0	7.5	dB	(Note 1)
Voltage Gain Difference	ΔGvld	-2.0	0	+2.0	dB	
Input Bias Current	linl	-	86	120	μA	VFIN=5V,VRIN=5V
LDCONT Bias Current	ILDC	-	-	300	nA	V _{CONT} =2V

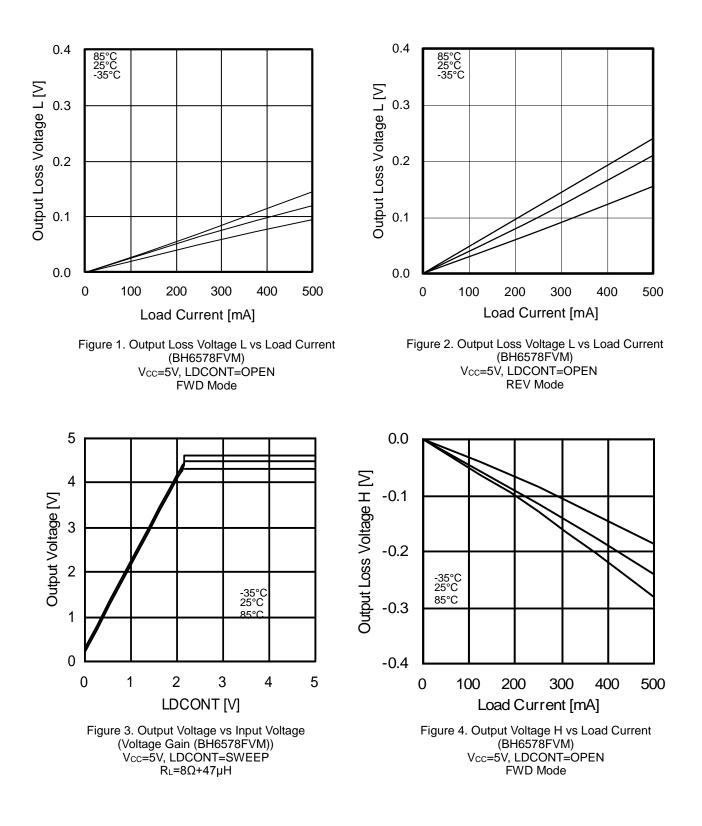
(Note 1) Let VO1 denote output-to-output voltage when V_{CONT}=1V and VO2 denote output-to-output Voltage when V_{CONT}=3.5V, voltage gain can be expressed by the following equation: G_{VLD}=20log| (VO2-VO1)/2.5|

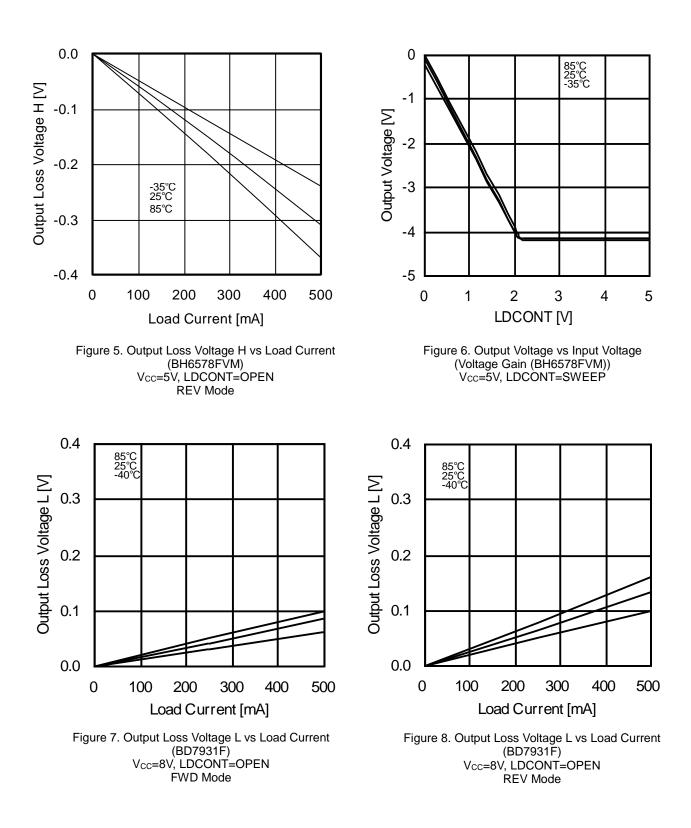
Deverseter	Cump al		Limit		Linit	Conditions
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Standby Current	I _{CC1}	-	0	5	μA	
Supply Current 1	Icc2	-	1.1	2.2	mA	V _{FIN} =5V,V _{RIN} =0V
Supply Current 2	Іссз	-	0.8	1.6	mA	VFIN=VRIN=5V
(Loading Driver)						
Output Offset Voltage	Vofsl	-35	0	+35	mV	Brake mode
Input Voltage H Level	Vih	2.0	-	Vcc	V	
Input Voltage L Level	VIL	GND	-	0.5	V	
ON-Resistance	Ron	-	1.0	1.8	Ω	Iout=500mA,Top+Bottom
Voltage Gain	Gvld	4.0	6.0	8.0	dB	(Note 2)
Voltage Gain Difference	ΔG_{VLD}	-2.0	0	+2.0	dB	
Input Bias Current	I _{INL}	-	165	250	μA	V _{FIN} =5V,V _{RIN} =5V
LDCONT Bias Current	ILDC	-	-	300	nA	V _{CONT} =5V

BD7931F (Unless otherwise specified, Ta=25°C, Vcc=8V)

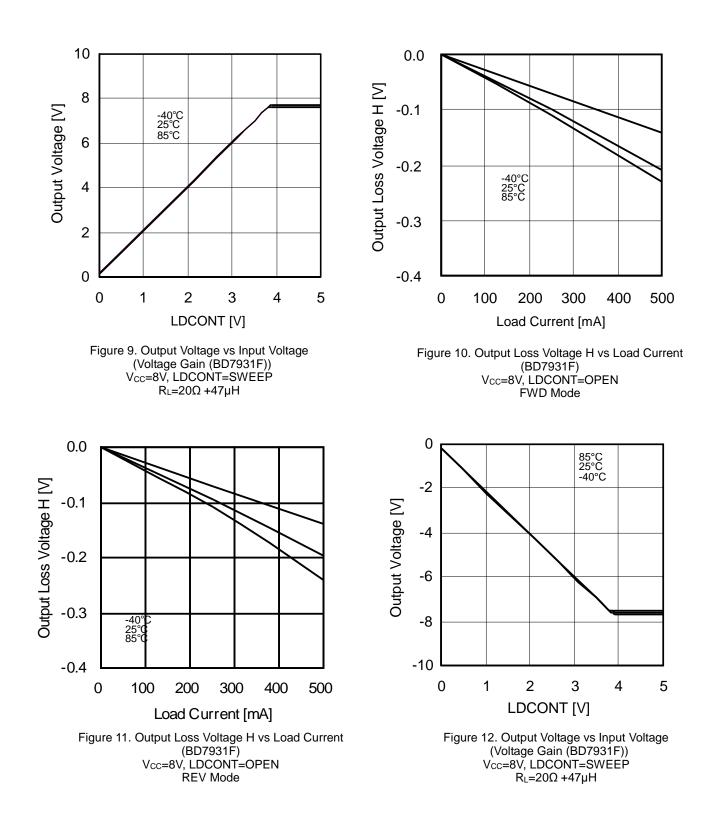
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Typical Performance Curves

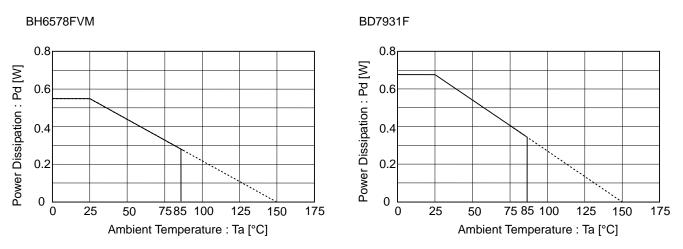




Typical Performance Curves – continued

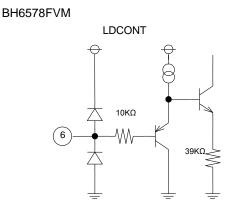


Power Dissipation

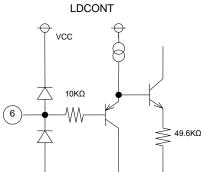


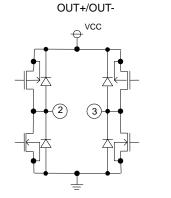
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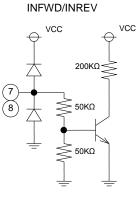
I/O Equivalent Circuits

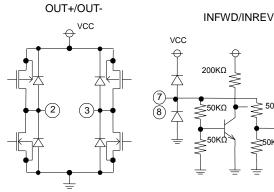


BD7931F









Control and Operation

1. OUTPUT MODE CONTROL AND OPERATION

Control and operation of each output mode is described as follows:

When INFWD is "HIGH" and INREV is "LOW", the output is at normal rotation mode. In normal rotation mode, current flows from OUT+ to OUT-. When both INFWD and INREV are "HIGH", the output is at brake mode. In brake mode, the top-side transistor is OFF to stop the supply of motor drive current while the bottom-side transistor is ON to absorb the reverse EMF of motor and apply brake to the motor. When both INFWD and INREV are "LOW", OUT+ and OUT-become high-impedance and the motor stops.

2. OUTPUT VOLTAGE CONTROL

Controlling the output voltage can vary the voltage applied to the motor and thus control motor speed. The output HIGH voltage can be controlled (gain 6dB Typ), using the voltage applied to the CONT terminal. The output voltage never exceeds the power supply voltage even if the voltage applied to CONT terminal exceeds (VCC Max).

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Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition. However, pins that drive inductive loads (e.g. motor driver outputs, DC-DC converter outputs) may inevitably go below ground due to back EMF or electromotive force. In such cases, the user should make sure that such voltages going below ground will not cause the IC and the system to malfunction by examining carefully all relevant factors and conditions such as motor characteristics, supply voltage, operating frequency and PCB wiring to name a few.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

Operational Notes – continued

12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

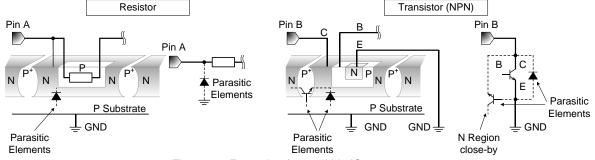


Figure 13. Example of monolithic IC structure

13. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

14. Thermal Shutdown Circuit(TSD)

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

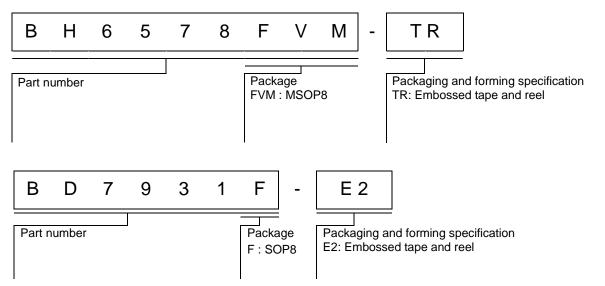
Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

	TSD ON temperature [°C]	Hysteresis temperature [°C]
	(typ)	(typ)
BH6578FVM, BD7931F	175	25

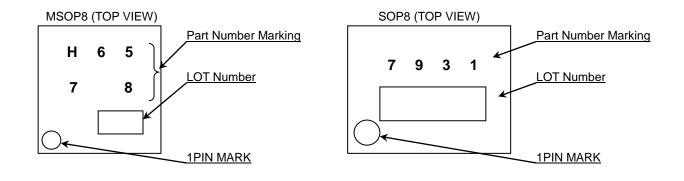
15. Capacitor Across Output and GND

In the event a large capacitor is connected across output and GND, when VCC and IN are short-circuited with 0V or GND for some reason, the charge stored in the capacitor flows into the output and may destroy the IC. Use a capacitor smaller than 0.1 μ F between output and GND.

Ordering Information

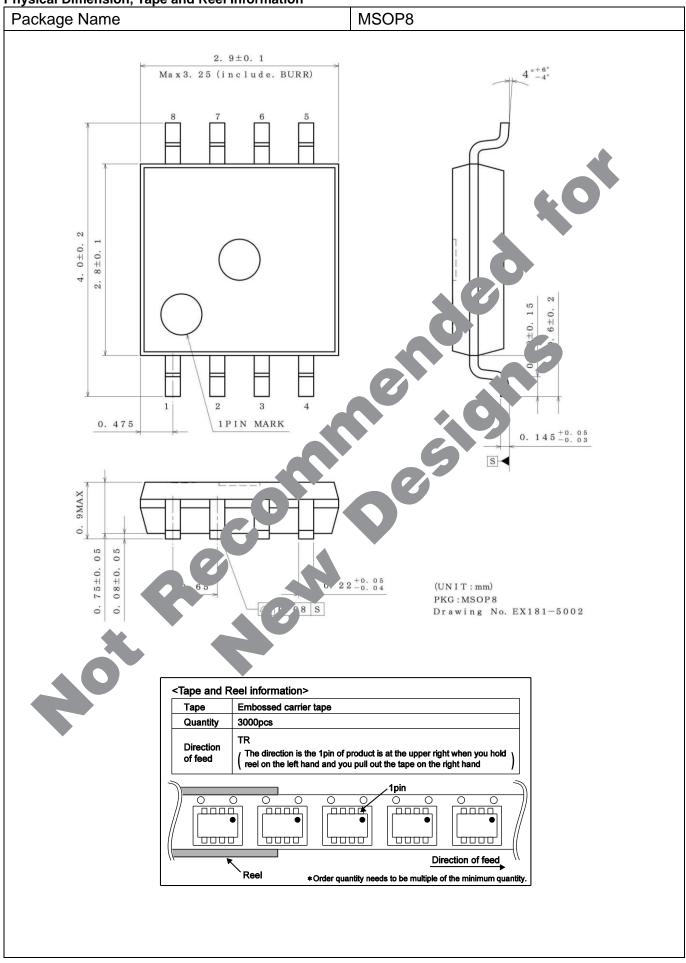


Marking Diagrams

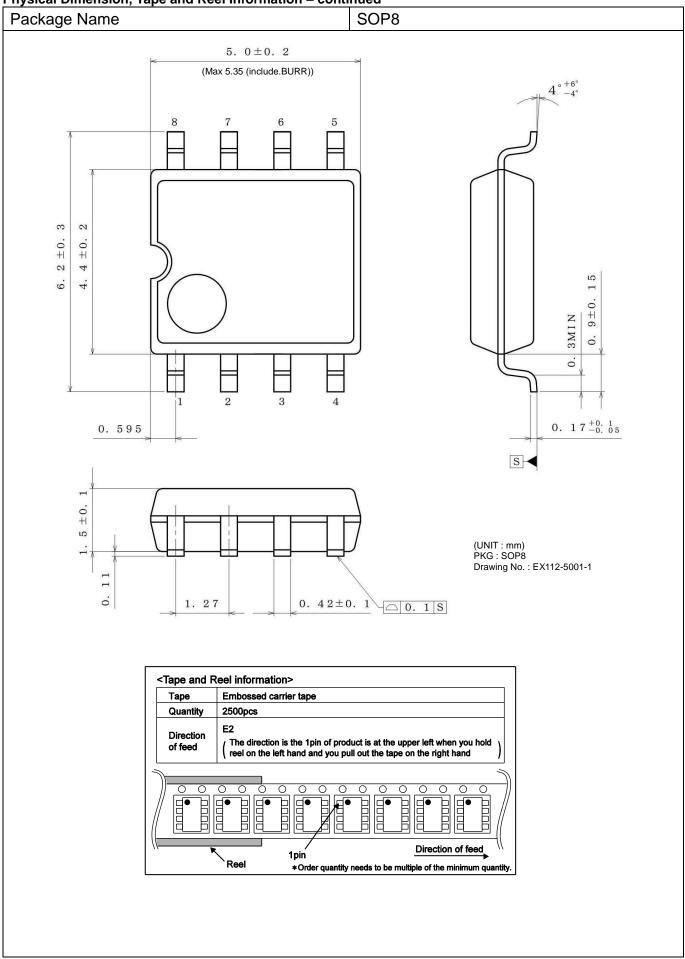


Datasheet

Physical Dimension, Tape and Reel Information



Physical Dimension, Tape and Reel Information – continued



Revision History

Date	Revision	Changes
04.Nov.2015	001	New Release

Notice

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(Note1) Medical Equipment Classification of the Specific Applications

JÁPAN	USA EU		CHINA
CLASSⅢ	CLASSⅢ	CLASS II b	CLASSII
CLASSⅣ	CLASSII	CLASSⅢ	CLASSI

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 - [f] Sealing or coating our Products with resin or other coating materials
 - [g] Use of our Products without cleaning residue of flux (Exclude cases where no-clean type fluxes is used. However, recommend sufficiently about the residue.); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
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- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse, is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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 - [d] the Products are exposed to high Electrostatic
- 2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
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