

Stepping Motor Driver series

High Performance, High Reliability 36V Stepping Motor Driver Series



BD6383EFV, BD6385EFV, BD6387EFV, BD6389FM

No.12009EAT04

●Description

BD6387EFV, BD6385EFV, BD6383EFV, BD6389FM are the high-grade type that provides the highest function and highest reliance in the ROHM stepping motor driver series. This series has the perfect various protection circuits and reduces IC's generation of heat by adopting low-ON resistance DMOS and high heat-radiation power package.

As for its basic function, it is a low power consumption bipolar PWM constant current-drive driver with power supply's rated voltage of 36V and rated output current of 1.0A~2.2A. For the input interface, the CLK-IN drive mode and the parallel IN drive mode are compatible with each other, so please choose an input mode according to needs of application. There are excitation modes of FULL STEP & HALF STEP (2 kinds), QUARTER STEP mode, and for current decay mode, the ratio of FAST DECAY & SLOW DECAY can be freely set, so the optimum control conditions for every motor can be realized. In addition, being able to drive with one system of power supply makes contribution to the set design's getting easy.

●Feature

- 1) Power supply: one system drive (rated voltage of 36V)
- 2) Rated output current: 1.0A, 1.5A, 2.0A, 2.2A
- 3) Low ON resistance DMOS output
- 4) CLK-IN drive mode (built-in translator circuit)
- 5) Parallel IN drive mode
- 6) Stepping motor/DC motor(×2) drives are selectable
- 7) PWM constant current control (self oscillation)
- 8) Built-in spike noise cancel function (external noise filter is unnecessary)
- 9) FULL STEP & HALF STEP (two kinds), applicable to QUARTER STEP
- 10) Applicable to the μSTEP drive
- 11) Current decay mode switching function (linearly variable FAST/SLOW DECAY ratio)
- 12) Normal rotation & reverse rotation switching function
- 13) Power save function
- 14) Built-in logic input pull-down resistor
- 15) Power-on reset function
- 16) Thermal shutdown circuit (TSD)
- 17) Over current protection circuit (OCP)
- 18) Under voltage lock out circuit (UVLO)
- 19) Over voltage lock out circuit (OVLO)
- 20) Malfunction prevention at the time of no applied power supply (Ghost Supply Prevention)
- 21) Electrostatic discharge: 6kV (HBM specification)
- 22) Adjacent pins short protection
- 23) Inverted mounting protection
- 24) Microminiature, ultra-thin and high heat-radiation (exposed metal type) HTSSOP package (BD6387EFV/BD6385EFV/BD6383EFV)
- 25) FIN heat-radiating type HSOP package (BD6389FM)
- 26) Pin-compatible line-up (BD6387EFV/BD6385EFV/BD6383EFV or BD6389FM)

●Application

PPC, multi-function printer, laser beam printer, ink jet printer, monitoring camera, WEB camera, sewing machine, photo printer, FAX, scanner, mini printer, toy, and robot etc.

●Absolute maximum ratings(Ta=25°C)

| Item | Symbol | BD6387EFV | BD6385EFV | BD6383EFV | BD6389FM | Unit |
|-------------------------------|----------------------|-------------------|-------------------|-------------------|-------------------|---------|
| Supply voltage | V _{CC0,1,2} | -0.2~+36.0 | | | | V |
| Power dissipation | P _d | 1.6 ^{※1} | | | 2.8 ^{※3} | W |
| | | 4.7 ^{※2} | | | 5.2 ^{※4} | W |
| Input voltage for control pin | V _{IN} | -0.2~+5.5 | | | | V |
| RNF maximum voltage | V _{RNF} | 0.5 | | | | V |
| Maximum output current | I _{OUT} | 2.0 ^{※5} | 1.5 ^{※5} | 1.0 ^{※5} | 2.2 ^{※5} | A/phase |
| Operating temperature range | T _{opr} | -25~+75 | | | | °C |
| Storage temperature range | T _{stg} | -55~+150 | | | | °C |
| Junction temperature | T _{jmax} | 150 | | | | °C |

※1 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 12.8mW/°C for operating above Ta=25°C.

※2 4-layer recommended board. Derating in done at 37.6mW/°C for operating above Ta=25°C.

※3 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 22.4mW/°C for operating above Ta=25°C.

※4 4-layer recommended board. Derating in done at 41.6mW/°C for operating above Ta=25°C.

※5 Do not, however exceed P_d, A_{SO} and T_{jmax}=150°C.

●Operating conditions(Ta= -25~+75°C)

| Item | Symbol | BD6387EFV | BD6385EFV | BD6383EFV | BD6389FM | Unit |
|--------------------|----------------------|-------------------|-------------------|-------------------|-------------------|---------|
| Supply voltage | V _{CC0,1,2} | 10~28 | | | | V |
| Output current(DC) | I _{OUT} | 1.7 ^{※6} | 1.2 ^{※6} | 0.7 ^{※6} | 1.9 ^{※6} | A/phase |

※6 Do not however exceed P_d, A_{SO}.

●Electrical characteristics

Applicable to all the series (Unless otherwise specified Ta=25°C, V_{CC0,1,2}=24V)

| Item | Symbol | Limit | | | Unit | Condition |
|---|--------------------|-------|------|------|------|---|
| | | Min. | Typ. | Max. | | |
| Whole | | | | | | |
| Circuit current at standby | I _{CCST} | - | 1.0 | 3.0 | mA | PS=L |
| Circuit current | I _{CC} | - | 4.5 | 10 | mA | PS=H, VREFX=2V |
| Control input (SELECT, CW_CCW, CLK, PS, MODE0, MODE1, ENABLE) | | | | | | |
| H level input voltage | V _{INH} | 2.0 | - | - | V | |
| L level input voltage | V _{INL} | - | - | 0.8 | V | |
| H level input current | I _{INH} | 35 | 50 | 85 | μA | V _{IN} =5V |
| L level input current | I _{INL} | -10 | 0 | - | μA | V _{IN} =0V |
| Output (OUT1A, OUT1B, OUT2A, OUT2B) | | | | | | |
| Output ON resistance (BD6387EFV) | R _{ON} | - | 0.8 | 1.04 | Ω | I _{OUT} = ±1.5A, Sum of upper and lower |
| Output ON resistance (BD6385EFV) | R _{ON} | - | 1.0 | 1.3 | Ω | I _{OUT} = ±1.0A, Sum of upper and lower |
| Output ON resistance (BD6383EFV) | R _{ON} | - | 1.5 | 1.95 | Ω | I _{OUT} = ±0.5A, Sum of upper and lower |
| Output ON resistance (BD6389FM) | R _{ON} | - | 0.7 | 0.91 | Ω | I _{OUT} = ±1.7A, Sum of upper and lower |
| Output leak current | I _{LEAK} | - | - | 10 | μA | |
| Current control | | | | | | |
| RNFXS input current | I _{RNFS} | -2.0 | -0.2 | - | μA | RNFXS =0V |
| RNFX input current | I _{RNF} | -40 | -20 | - | μA | RNFX=0V |
| VREFX input current | I _{VREF} | -2.0 | -0.1 | - | μA | VREFX=0V |
| VREFX input voltage range | V _{REF} | 0 | - | 2.0 | V | |
| MTHX input current | I _{MTH} | -2.0 | -0.1 | - | μA | MTHX=0V |
| MTHX input voltage range | V _{MTH} | 0 | - | 3.5 | V | |
| Comparator threshold | V _{CTH} | 0.36 | 0.4 | 0.44 | V | VREFX=2V |
| Minimum on time | t _{ONMIN} | 0.3 | 0.7 | 1.2 | μs | R=39kΩ, C=1000pF |

●Terminal function

1) BD6387EFV / BD6385EFV / BD6383EFV

| Pin No. | Pin name | Function | Pin No. | Pin name | Function |
|---------|----------|--|---------|----------|--|
| 1 | NC | Non connection | 21 | VCC0 | Power supply terminal |
| 2 | RNF1 | Connection terminal of resistor for output current detection | 22 | NC | Non connection |
| 3 | RNF1S | Input terminal of current limit comparator | 23 | GND | Ground terminal |
| 4 | NC | Non connection | 24 | MODE0 | Motor excitation mode setting terminal |
| 5 | OUT1B | H bridge output terminal | 25 | MODE1 | Motor excitation mode setting terminal |
| 6 | NC | Non connection | 26 | ENABLE | Output enable terminal |
| 7 | OUT1A | H bridge output terminal | 27 | VREF2 | Output current value setting terminal |
| 8 | NC | Non connection | 28 | MTH2 | Current decay mode setting terminal |
| 9 | VCC1 | Power supply terminal | 29 | NC | Non connection |
| 10 | NC | Non connection | 30 | CR2 | Connection terminal of CR for setting PWM frequency |
| 11 | CR1 | Connection terminal of CR for setting PWM frequency | 31 | NC | Non connection |
| 12 | NC | Non connection | 32 | VCC2 | Power supply terminal |
| 13 | MTH1 | Current decay mode setting terminal | 33 | NC | Non connection |
| 14 | VREF1 | Output current value setting terminal | 34 | OUT2A | H bridge output terminal |
| 15 | SELECT | Input mode select terminal | 35 | NC | Non connection |
| 16 | CW_CCW | Motor rotating direction setting terminal | 36 | OUT2B | H bridge output terminal |
| 17 | NC | Non connection | 37 | NC | Non connection |
| 18 | CLK | Clock input terminal for advancing the electrical angle. | 38 | RNF2S | Input terminal of current limit comparator |
| 19 | PS | Power save terminal | 39 | RNF2 | Connection terminal of resistor for output current detection |
| 20 | TEST | Terminal for testing (used by connecting with GND) | 40 | GND | Ground terminal |

2) BD6389FM

| Pin No. | Pin name | Function | Pin No. | Pin name | Function |
|---------|----------|--|---------|----------|--|
| 1 | NC | Non connection | 19 | VCC2 | Power supply terminal |
| 2 | CR1 | Connection terminal of CR for setting PWM frequency | 20 | NC | Non connection |
| 3 | MTH1 | Current decay mode setting terminal | 21 | NC | Non connection |
| 4 | VREF1 | Output current value setting terminal | 22 | OUT2A | H bridge output terminal |
| 5 | SELECT | Input mode select terminal | 23 | NC | Non connection |
| 6 | CW_CCW | Motor rotating direction setting terminal | 24 | OUT2B | H bridge output terminal |
| 7 | CLK | Clock input terminal for advancing the electrical angle. | 25 | NC | Non connection |
| 8 | PS | Power save terminal | 26 | RNF2S | Input terminal of current limit comparator |
| 9 | TEST | Terminal for testing (used by connecting with GND) | 27 | RNF2 | Connection terminal of resistor for output current detection |
| FIN | FIN | Fin terminal (used by connecting with GND) | FIN | FIN | Fin terminal (used by connecting with GND) |
| 10 | GND | Ground terminal | 28 | RNF1 | Connection terminal of resistor for output current detection |
| 11 | MODE0 | Motor excitation mode setting terminal | 29 | RNF1S | Input terminal of current limit comparator |
| 12 | MODE1 | Motor excitation mode setting terminal | 30 | NC | Non connection |
| 13 | ENABLE | Output enable terminal | 31 | OUT1B | H bridge output terminal |
| 14 | VREF2 | Output current value setting terminal | 32 | NC | Non connection |
| 15 | MTH2 | Current decay mode setting terminal | 33 | OUT1A | H bridge output terminal |
| 16 | CR2 | Connection terminal of CR for setting PWM frequency | 34 | NC | Non connection |
| 17 | NC | Non connection | 35 | VCC1 | Power supply terminal |
| 18 | NC | Non connection | 36 | VCC0 | Power supply terminal |

●Block diagram・Application circuit diagram・Input output equivalent circuit diagram

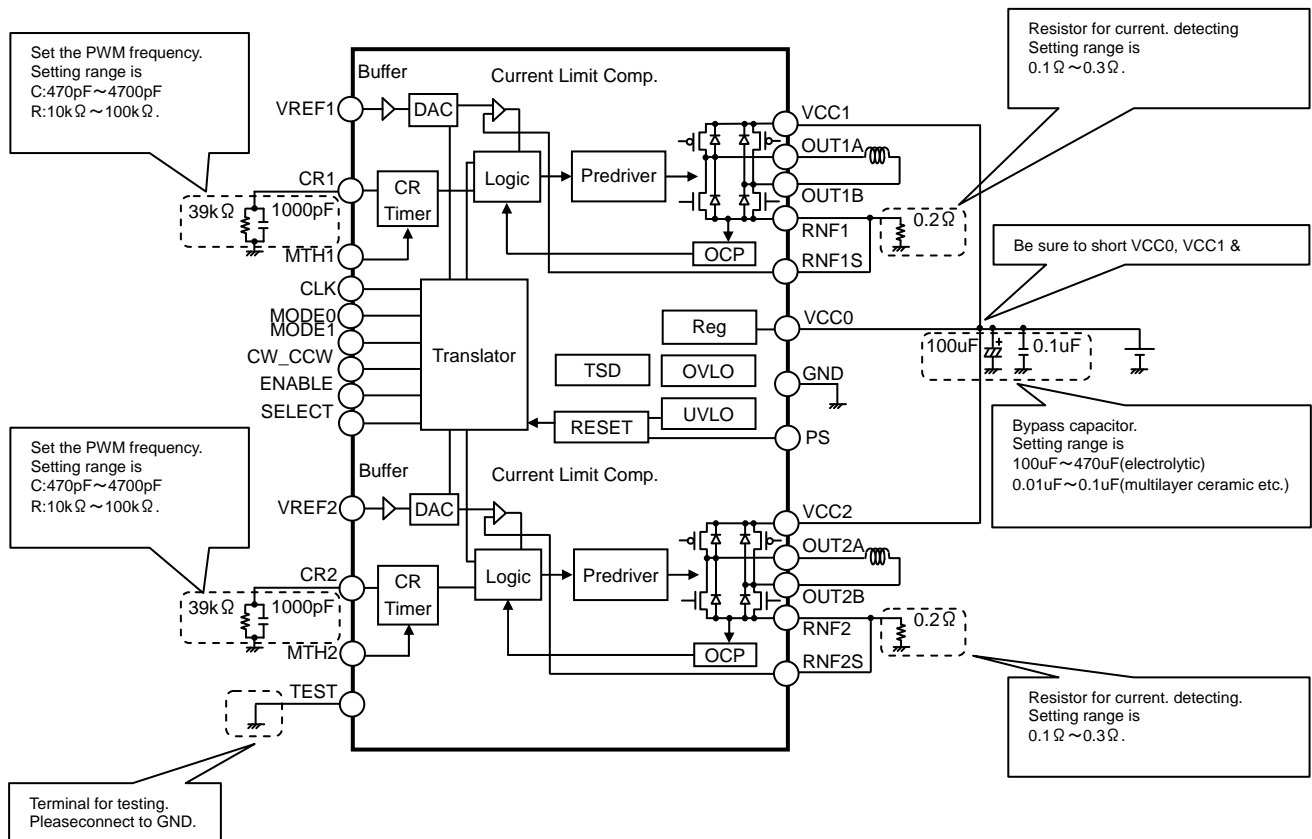


Fig.1 Block diagram & Application circuit diagram of BD6387EFV/BD6385EFV/BD6383EFV/BD6389FM

●Points to notice for terminal description

○CLK/Clock input terminal for advancing the electrical angle

CLK is reflected at rising edge. The Electrical angle advances by one for each CLK input.

Motor's misstep will occur if noise is picked up at the CLK terminal, so please design the pattern in such a way that there is no noise plunging.

○MODE0,MODE1/Motor excitation mode setting terminal

Set the motor excitation mode.

| MODE0 | MODE1 | Excitation mode |
|-------|-------|-----------------|
| L | L | FULL STEP |
| H | L | HALF STEP A |
| L | H | HALF STEP B |
| H | H | QUARTER STEP |

○CW_CCW Terminal/Motor rotating direction setting terminal

Set the motor's rotating direction. Change in setting is reflected at the CLK's rising edge immediately after the change in setting

| CW_CCW | Rotating direction |
|--------|--|
| L | Clockwise (CH2's current is outputted with a phase lag of 90° in regard to CH1's current) |
| H | Counter Clockwise (CH2's current is outputted with a phase lead of 90° in regard to CH1's current) |

○ENABLE Terminal/Output enable terminal

Turn off forcibly all the output transistors (motor output is open).

At the time of ENABLE=L, electrical angle or operating mode is maintained even if CLK is inputted.

Please be careful because the electrical angle at the time of ENABLE being released (ENABLE=L→H) is different from the released occasion at the section of CLK=H and from the released occasion at the section of CLK=L.

| ENABLE | Motor output |
|--------|------------------------------------|
| L | OPEN (electrical angle maintained) |
| H | ACTIVE |

OPS/Power save terminal

PS can make circuit standby state and make motor output OPEN. In standby state, translator circuit is reset (initialized) and electrical angle is initialized.

Please be careful because there is a delay of 40μs(max.) before it is returned from standby state to normal state and the motor output becomes ACTIVE.

| PS | State |
|----|-----------------------|
| L | Standby state (RESET) |
| H | ACTIVE |

The electrical angle (initial electrical angle) of each excitation mode immediately after RESET is as follows.

Please be careful because the initial state at the time of FULL STEP is different from those of other excitation modes.

| Excitation mode | Initial electrical angle |
|-----------------|--------------------------|
| FULL STEP | 45° |
| HALFSTEP A | 0° |
| HALFSTEP B | 0° |
| QUARTER STEP | 0° |

OSELECT Terminal/ Input mode switching terminal

This is the terminal to set the input mode.

| SELECT | Input mode |
|--------|-------------------|
| L | CLK-IN drive |
| H | Parallel IN drive |

●Power dissipation

OHTSSOP-B40 Package (BD6387EFV/BD6385EFV/BD6383EFV)

HTSSOP-B40 has exposed metal on the back, and it is possible to dissipate heat from a through hole in the back. Also, the back of board as well as the surfaces has large areas of copper foil heat dissipation patterns, greatly increasing power dissipation. The back metal is shorted with the back side of the IC chip, being a GND potential, therefore there is a possibility for malfunction if it is shorted with any potential other than GND, which should be avoided. Also, it is recommended that the back metal is soldered onto the GND to short. Please note that it has been assumed that this product will be used in the condition of this back metal performed heat dissipation treatment for increasing heat dissipation efficiency.

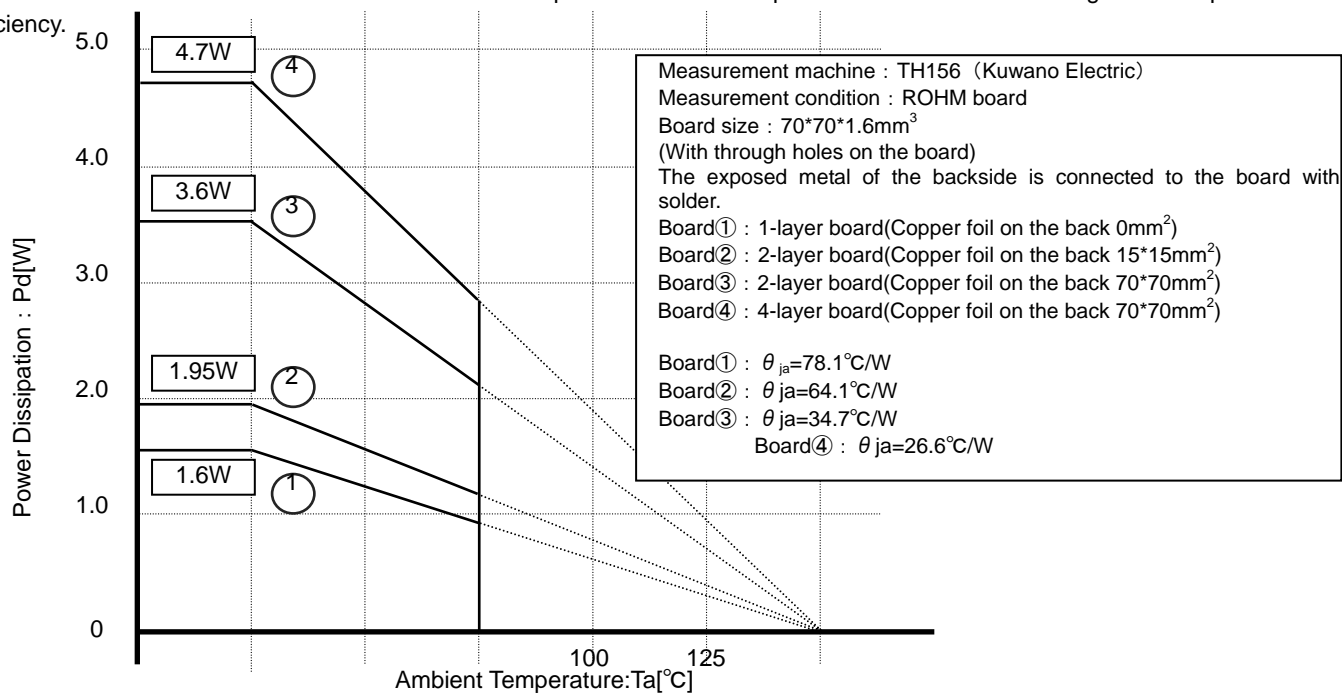
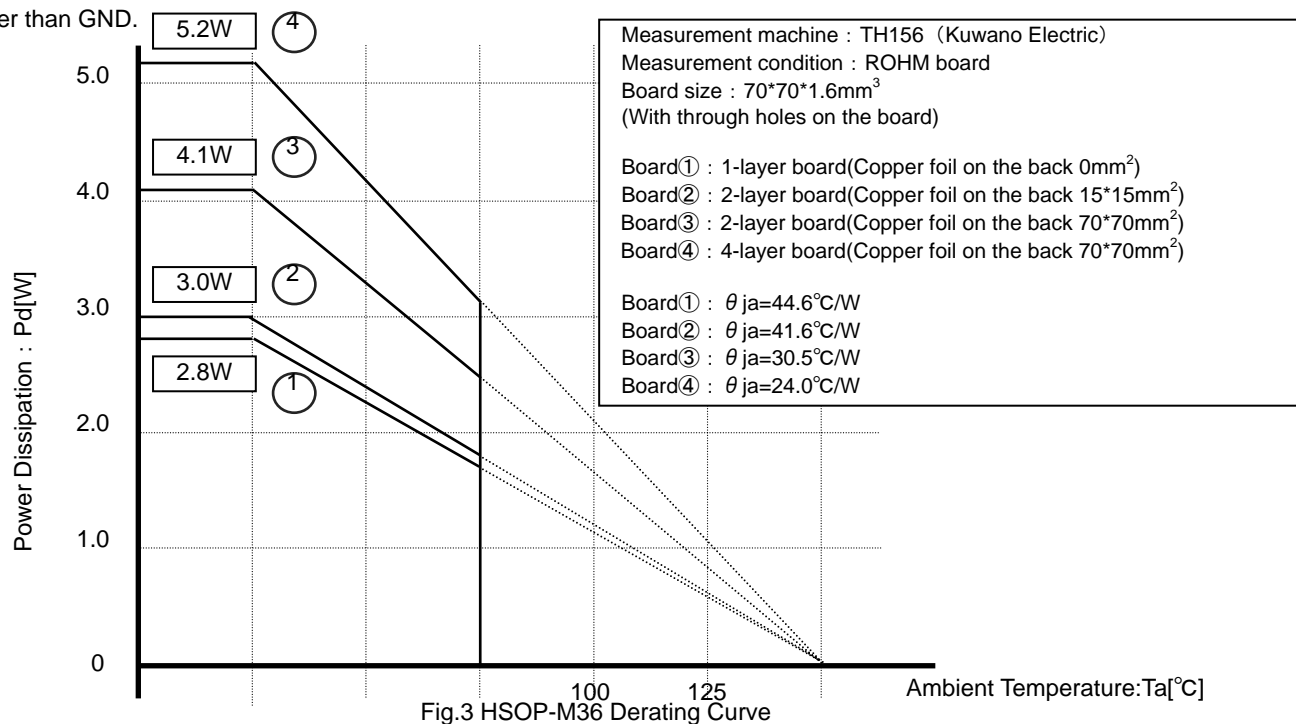


Fig.2 HTSSOP-B40 Derating Curve

OHSOP-M36 Package (BD6389FM/BD6388FM)

HSOP-M36 has a heat-dissipating FIN terminal on the IC side, but it is possible to greatly increase power dissipation by taking a large heat dissipation pattern, such as with copper foil, on the back as well as the surface of the board. Also, this terminal is a GND potential, therefore there is a possibility for malfunction or destruction if it is shorted with any potential other than GND.



Usage Notes

(1) Absolute maximum ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down the devices, thus making impossible to identify breaking mode, such as a short circuit or an open circuit. If any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.

(2) Connecting the power supply connector backward

Connecting of the power supply in reverse polarity can damage IC. Take precautions when connecting the power supply lines. An external direction diode can be added.

(3) Power supply Lines

Design PCB layout pattern to provide low impedance GND and supply lines. To obtain a low noise ground and supply line, separate the ground section and supply lines of the digital and analog blocks. Furthermore, for all power supply terminals to ICs, connect a capacitor between the power supply and the GND terminal. When applying electrolytic capacitors in the circuit, not that capacitance characteristic values are reduced at low temperatures.

(4) GND Potential

The potential of GND pin must be minimum potential in all operating conditions.

(5) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions. Users should be aware that BD6387EFV, BD6385EFV and BD6383EFV have been designed to expose their frames at the back of the package, and should be used with suitable heat dissipation treatment in this area to improve dissipation. As large a dissipation pattern should be taken as possible, not only on the front of the baseboard but also on the back surface. BD6389FM and BD6388FM are both equipped with FIN heat dissipation terminals, but dissipation efficiency can be improved by applying heat dissipation treatment in this area. It is important to consider actual usage conditions and to take as large a dissipation pattern as possible.

(6) Inter-pin shorts and mounting errors

When attaching to a printed circuit board, pay close attention to the direction of the IC and displacement. Improper attachment may lead to destruction of the IC. There is also possibility of destruction from short circuits which can be caused by foreign matter entering between outputs or an output and the power supply or GND.

(7) Operation in a strong electric field

Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction.

(8) ASO

When using the IC, set the output transistor so that it does not exceed absolute maximum ratings or ASO.

(9) Thermal shutdown circuit

The IC has a built-in thermal shutdown circuit (TSD circuit). If the chip temperature becomes $T_{jmax}=150^{\circ}\text{C}$, and higher, coil output to the motor will be open. The TSD circuit is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect or indemnify peripheral equipment. Do not use the TSD function to protect peripheral equipment.

| TSD on temperature [$^{\circ}\text{C}$] (Typ.) | Hysteresis Temperature [$^{\circ}\text{C}$] (Typ.) |
|--|--|
| 175 | 25 |

(10) Inspection of the application board

During inspection of the application board, if a capacitor is connected to a pin with low impedance there is a possibility that it could cause stress to the IC, therefore an electrical discharge should be performed after each process. Also, as a measure against electrostatic discharge, it should be earthed during the assembly process and special care should be taken during transport or storage. Furthermore, when connecting to the jig during the inspection process, the power supply should first be turned off and then removed before the inspection.

(11) Input terminal of IC

This IC is a monolithic IC, and between each element there is a P+ isolation for element partition and a P substrate.

This P layer and each element's N layer make up the P-N junction, and various parasitic elements are made up.

For example, when the resistance and transistor are connected to the terminal as shown in figure 4,

○When $\text{GND} > (\text{Terminal A})$ at the resistance and $\text{GND} > (\text{Terminal B})$ at the transistor (NPN), the P-N junction operates as a parasitic diode.

○Also, when $\text{GND} > (\text{Terminal B})$ at the transistor (NPN)

The parasitic NPN transistor operates with the N layers of other elements close to the aforementioned parasitic diode.

Because of the IC's structure, the creation of parasitic elements is inevitable from the electrical potential relationship. The operation of parasitic elements causes interference in circuit operation, and can lead to malfunction and destruction. Therefore, be careful not to use it in a way which causes the parasitic elements to operate, such as by applying voltage that is lower than the GND (P substrate) to the input terminal.

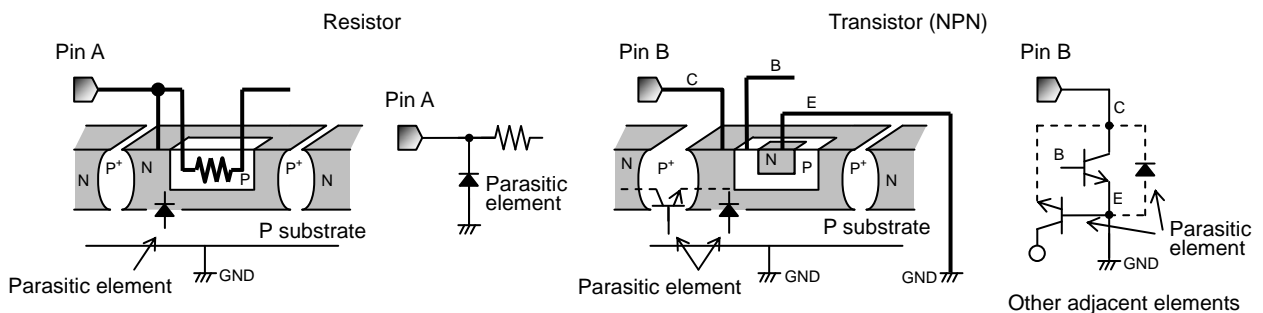


Fig. 4 Pattern Diagram of Parasitic Element

(12) Ground Wiring Patterns

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the application's reference point so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern potential of any external components, either.

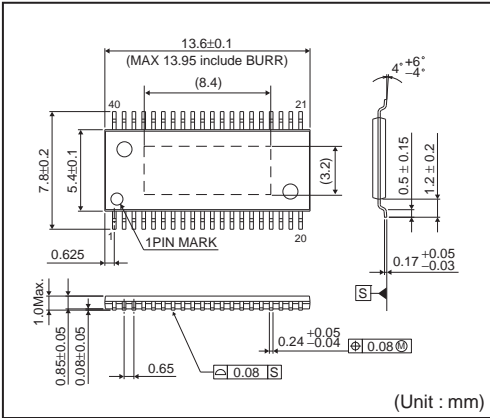
(13) TEST Terminal

Be sure to connect TEST pin to GND.

●Ordering part number

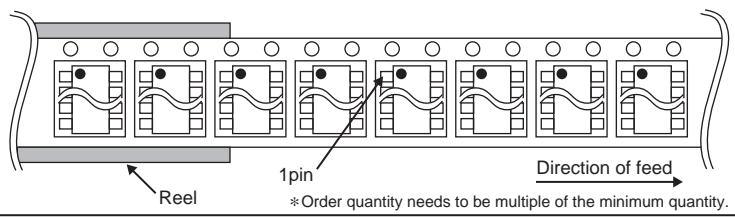
| | | |
|-------------------|--|----------------------------------|
| B D 6 3 8 3 E F V | - | E 2 |
| 形名 | パッケージ EFV : HTSSOP-B40 FM : HSOP-M36 | 包装、フォーミング仕様 E2: リール状エンボステーピング |

HTSSOP-B40

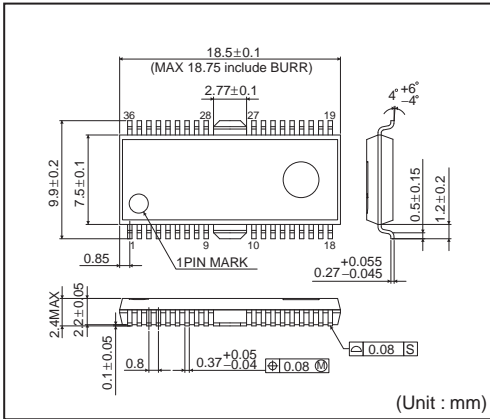


<Tape and Reel information>

| | |
|-------------------|---|
| Tape | Embossed carrier tape (with dry pack) |
| Quantity | 2000pcs |
| Direction of feed | E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand) |

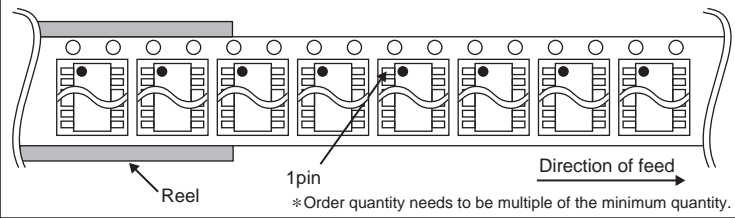


HSOP-M36



<Tape and Reel information>

| | |
|-------------------|---|
| Tape | Embossed carrier tape (with dry pack) |
| Quantity | 1500pcs |
| Direction of feed | E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand) |



Notice

Precaution on using ROHM Products

- Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment ^(Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

| JAPAN | USA | EU | CHINA |
|-----------|-----------|------------|-----------|
| CLASS III | CLASS III | CLASS II b | CLASS III |
| CLASS IV | | CLASS III | |

- ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
 - Installation of protection circuits or other protective devices to improve system safety
 - Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc. prior to use, must be necessary:
 - Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
 - Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
 - Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl₂, H₂S, NH₃, SO₂, and NO₂
 - Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
 - Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - Sealing or coating our Products with resin or other coating materials
 - Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - Use of the Products in places subject to dew condensation
- The Products are not subject to radiation-proof design.
- Please verify and confirm characteristics of the final or mounted products in using the Products.
- In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- Confirm that operation temperature is within the specified range described in the product specification.
- ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

- When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of ionizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
 - [a] the Products are exposed to sea winds or corrosive gases, including Cl₂, H₂S, NH₃, SO₂, and NO₂
 - [b] the temperature or humidity exceeds those recommended by ROHM
 - [c] the Products are exposed to direct sunshine or condensation
 - [d] the Products are exposed to high Electrostatic
2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

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