

### MSDL (Mobile Shrink Data Link) Transceivers for Mobile Phones

# Data rate 1350Mbps RGB Interface



BU7963GUW No.10058EAT05

#### Description

BU7963GUW is a differential serial interface connecting mobile phone LCD modules to the host CPU. Unique technology is utilized for lower power consumption and EMI. MSDL minimizes the number of wires required - an important consideration in hinge phones - resulting in greater reliability and design flexibility.

#### Features

- 1) MSDL3 high-speed differential interface with a maximum transfer rate of 1350 Mbps.
- 2) Compatible with 24-bit RGB video mode for LCD controller-to-LCD interface.
- 3) Pixel clock frequency range from 4 to 45MHz.
- 4) Depending on the data transfer rate, one, two or three differential data channels can be selected.

#### Applications

Serial Interface for LCD Display Interface of Mobile Devices Application.

#### Absolute Maximum Ratings:

Parameter	Symbol	Ratings	Unit	Remarks
Power Supply Voltage	DVDD	-0.3 ~ +2.5	V	-
Fower Supply Voltage	MSVDD	-0.3 ~ +2.5	V	-
Input Voltage	VIN	-0.3 ~ MSVDD+0.3	V	I/O terminals of MSVDD line
input voltage	VIIN	-0.3 ~ DVDD+0.3	V	I/O terminals of DVDD line
Output Voltage	VOUT	-0.3 ~ MSVDD+0.3	V	I/O terminals of MSVDD line
Output Voltage	VO01	-0.3 ~ DVDD+0.3	V	I/O terminals of DVDD line
Input Current	IIN	-10 ~ +10	mA	-
Output Current	IOUT	-70 ~ <b>+</b> 70	mA	-
Preservation Temperature	Tstg	-55 ~ +125	°C	-

#### Operating Conditions:

Parameter	Symbol	Ratings			Unit	Conditions
Farameter	Symbol	Min	Тур	Max	Ullit	Conditions
Supply Voltage for DVDD	$V_{DVDD}$	1.65	1.80	1.95	V	V - V
Supply Voltage for MSVDD	V <sub>MSVDD</sub>	1.65	1.80	1.95	V	$V_{DVDD} = V_{MSVDD}$
Data Transmission Rate	DR	120	-	450	Mbps/ch	-
Operating Temperature Range	T <sub>opr</sub>	-30	25	85	°C	-

Technical Note

#### ●Package View

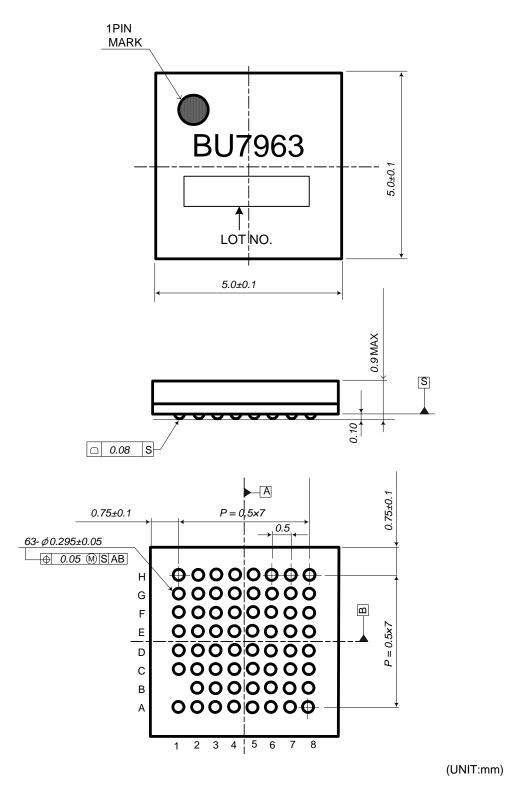


Fig.1. Package View (VBGA063W050)

#### Block Diagram

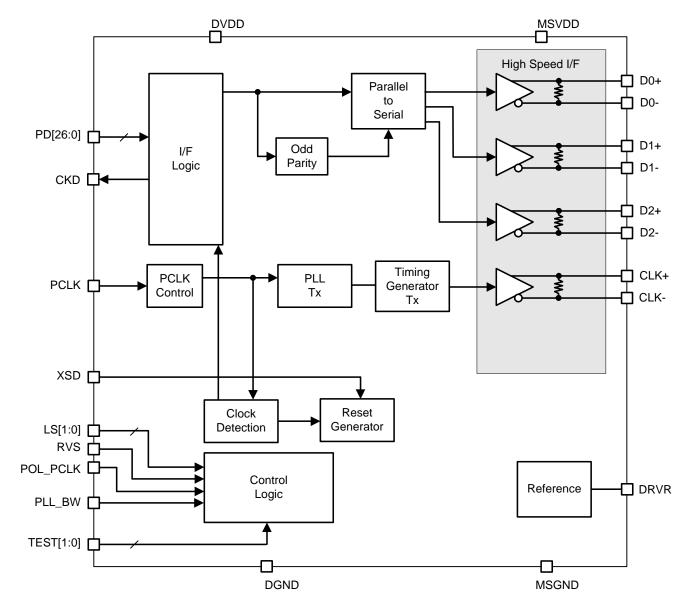


Fig.2. Block Diagram

### ●Pin Layout

	1	2	3	4	5	6	7	8
А	TEST0	PD19	PD17	PD16	PD14	PD13	PD10	CKD
В		PCLK	PD18	PD15	PD12	PD11	PD9	PD8
С	PD22	PD20	PLL_BW	DVDD	N.C.	RVS	PD7	PD6
D	PD23	PD21	N.C.	DGND	DGND	DVDD	PD4	PD5
E	PD25	PD24	DVDD	DGND	MSGND	N.C.	PD1	PD3
F	PD26	LS0	MSVDD	MSGND	MSVDD	N.C.	XSD	PD2
G	LS1	POL_ PCLK	D2+ (D0+)	D1+ (CLK+)	CLK+ (D1+)	D0+ (D2+)	N.C.	PD0
н	N.C.	N.C.	D2- (D0-)	D1- (CLK-)	CLK- (D1-)	D0- (D2-)	DRVR	TEST1

Fig.3. Pin Layout (Top View)

#### Pin Functions

Table 1. Power Supply and Ground

		Table 1.1 ener eapply and electric				
Power Supply / Ground : 10-pin						
Name	Width	Functions				
DVDD	3	CMOS I/O and logic core power supply.				
MSVDD	2	Analog core power supply.				
DGND	3	CMOS I/O and logic core ground.				
MSGND	2	Analog core ground.				

#### Table 2. MSDL3

High-Speed	High-Speed Serial Interface 8-pin						
Name	Width	Level	I/O	Functions	Shutdown	Equivalent Schematic	
CLK+	1	Analog	0	CLK+ pin When RVS = 'L' : CLK+ When RVS = 'H' : D1+	Hi-Z	D	
CLK-	1	Analog	0	CLK- pin When RVS = 'L' : CLK- When RVS = 'H' : D1-	Hi-Z	D	
D0+	1	Analog	0	D0+ pin When RVS = 'L' : D0+ When RVS = 'H' : D2+	Hi-Z	D	
D0-	1	Analog	0	D0- pin When RVS = 'L' : D0- When RVS = 'H' : D2-	Hi-Z	D	
D1+	1	Analog	0	D1+ pin When RVS = 'L' : D1+ When RVS = 'H' : CLK+	Hi-Z	D	
D1-	1	Analog	0	D1- pin When RVS = 'L' : D1- When RVS = 'H' : CLK-	Hi-Z	D	
D2+	1	Analog	0	D2+ pin When RVS = 'L' : D2+ When RVS = 'H' : D0+	Hi-Z	D	
D2-	1	Analog	0	D2- pin When RVS = 'L' : D2- When RVS = 'H' : D0-	Hi-Z	D	

### Table 3. Analog

Analog	1-pin					
Name	Width	Level	I/O	Functions	Shutdown	Equivalent Schematic
DRVR	1	Analog	-	10kΩ±5% register should be connected between DRVR and MSGND.	-	D

Table 4. Parallel Data Interface

Parallel Data	Parallel Data Interface 29-pin							
Name	Width	Level	I/O	Functions	Shutdown	Equivalent Schematic		
PCLK	1	CMOS	I	PCLK interface.	Input	А		
PD[26:0]	27	CMOS	I	Parallel data interface.	Input	А		
CKD	1	CMOS	0	Output of PCLK detection result. 'L': clock stop. 'H': clock detect.	'L'	С		

Table 5. Control

Control	8-pin					
Name	Width	Level	I/O	Functions	Shutdown	Equivalent Schematic
XSD	1	CMOS	ı	Shutdown pin. 'L': shutdown. 'H': normal operation.	Input	А
LS0	1	Selection of the number of data channel and the data format.  * Refer to "Selection of the number of MSDL3 channels".  * Set the same number of data channel between the TX device and the RX device.		the data format.  * Refer to "Selection of the number of	Input	A
LS1	1			* Set the same number of data channel	·	
RVS	1	CMOS	I	Selection of MSDL3 pins assignment. 'L': Default matrix. 'H': Flipped matrix.	Input	А
PLL_BW	1	CMOS	I	Selection of PLL bandwidth.	Input	А
POL_PCLK	1	CMOS	I	Selection of input clock polarity. 'L': sample parallel data at falling. 'H': sample parallel data at rising.	Input	А
TEST0	1	Pull		Test mode pin. 'L': normal mode.	Input	В
TEST1	down			'H': test mode. Must be 'L.'	Input	В

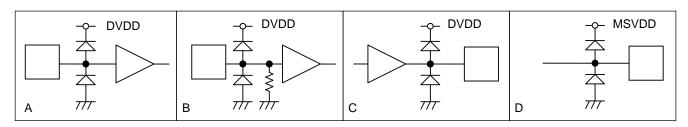


Fig.4. Equivalent Schematics

#### Operation Control

MSDL3 Channel Count Selection

Pin LS is used to control the high-speed data channel count and data format. The LS pin settings (i.e., high-speed data channel count, data format) should be the same between the transmitting and receiving devices (the BU7963GUW and BU7964GUW, respectively). Table 6 shows the PCLK input frequency ranges and transmission data rate ranges for the LS pin settings.

Table 6. The Range of The Transmission Data rate

LS1	LS0	The Number of Data Channel	The Range of PCLK Input Frequency [MHz]	The Range of The Data Transmission Rate [Mbits/sec]			
'L'	'L'	1-channel	4.0-15.0	120-450			
'L'	'H'	2-channel	8.0-30.0	240-900			
'H'	'L'	3-channel	12.0-45.0	360-1350			
'H'	'H'	Inhibit setting.					

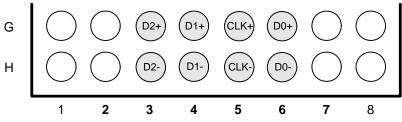
#### MSDL3 Pin Assignment

RVS determines the assignment of MSDL3 pins, CLK+ / CLK-, D0+ / D0-, D1+ / D1- and D2+ / D2-. Only the MSDL3 high-speed signaling pins are affected by RVS, while pin assignment of other functions does not change. User can select the assignment from 'straight' (default) and 'flipped' assignment in order to minimize channel-to-channel skew in PWB design. Table 7 shows the MSDL3 pin assignment, and Fig.5 shows the 'straight' and 'flipped'

Table 7. MSDL3 Pin Assignment

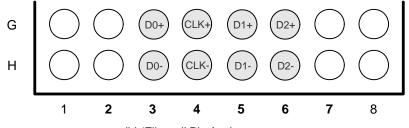
1 0 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1						
RVS MSDL3 Pin Assignment						
'L'	'Straight' (default matrix)					
'H'	'Flipped'					

# Top View RVS='L' Default MSDL3 terminal assignment



(a) 'Straight' Pin Assignment

# Top View RVS='H' Flipped MSDL3 terminal assignment



(b) 'Flipped' Pin Assignment

Fig.5. MSDL3 Pin Assignment

Technical Note

#### PCLK Polarity Selection

BU7963GUW controls PCLK input polarity by POL\_PCLK setting. Table 8 shows PCLK input polarity.

Table 8. PCLK Polarity Selection

DOL DOLK	Darallal Data Conturing Delarity
POL_PCLK	Parallel Data Capturing Polarity
'L'	Capture parallel data at falling edge.
'H' (default)	Capture parallel data at rising edge.

#### PLL Bandwidth Selection

BU7963GUW controls the range of the CLK+ / CLK- input frequency (= PCLK output frequency) by the setting of the data format (LS1, and LS0) of the high-speed data channel and the bandwidth setting of PLL\_BW.

Table 9. PLL BW Setting

Table 9. PLL_BW Setting								
LS1	LS0	PLL_BW	CLK+ / CLK- Frequency Range [MHz] (PCLK Input Frequency)					
		_	Min	Max				
'L'	'L'	'L'	4	8				
'L'	'L'	'H'	7	15				
'L'	'H'	'L'	8	16				
'L'	'H'	'H'	14	30				
'H'	'L'	Ľ	12	24				
'H'	'L'	'H'	21	45				

#### ●Power Modes

BU7963GUW has three power modes.

#### 1) Shutdown Mode

BU7963GUW goes to Shutdown Mode when XSD = 'L'. All logic circuits are initialized in the Shutdown Mode. All high-speed signaling channels are disabled, and the outputs keep Hi-Z status.

#### 2) Standby Mode

BU7963GUW goes to Standby Mode when XSD = 'H' and PCLK is not provided. All high-speed signaling channel outputs keep Hi-Z status. BU7963GUW is monitoring whether PCLK input is running or not and the link switches to Active Mode when PCLK running is detected.

#### 3) Active Mode

BU7963GUW goes to Active Mode when XSD = 'H' and PCLK is running. All high-speed signaling channels are enabled.

Table 10. Power Modes

Power Mode	Inp	out	Operation		
Power Mode	XSD	PCLK	Functions	MSDL3 Terminals	
Shutdown	'L'	Static ('L' or 'H')	Initialized	Disabled (Hi-Z)	
Standby	'H'	Static ('L' or 'H')	PCLK detection	Disabled (Hi-Z)	
			PCLK detection		
Active	'H'	Clock input is active	Normal operation	Enabled	
			(P2S conv)		

#### 4) Power Modes Transition

Fig.6 shows the transition of power modes.

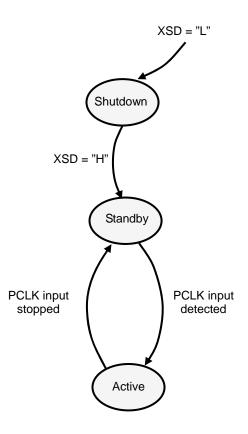


Fig.6. Power Modes Transition

#### ●High-Speed Data Channel Protocols

Fig.7, Fig.8 and Fig.9 show high-speed data channel protocols.

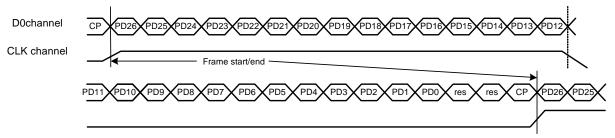


Fig.7. MSDL3 Protocol for 1-channel Data (27-bit)

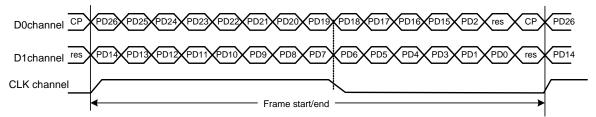


Fig.8. MSDL3 Protocol for 2-channel Data (27-bit)

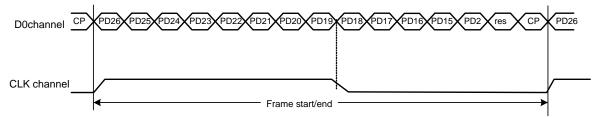


Fig.9. MSDL3 Protocol for 1-channel Data (13-bit)

"res" is reserved bit for the future use, the default state of those is '0.'
CP is the parity bit of data payload. BU7961GUW adds an odd parity on CP of the high-speed channel data.

- · When the number of 'H' bits in parallel data is even, CP bit is 'H.'
- When the number of 'H' bits in parallel data is odd, CP bits is 'L.'

**Technical Note** 

#### ● Electrical Characteristics

1) DC Characteristics

Table 11. Digital Input / Output DC Characteristics

Ta=25°C, DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.

Parameter	Symbol		Limits		Unit	Conditions	
Faiametei	Symbol	Min	Тур	Max	Offic	Conditions	
'L' Input Voltage 1	VIL1	DGND	1	0.3 x DVDD	V	PCLK, PD[26:0], LS[1:0], RVS, POL_PCLK, XSD, PLL_BW, TEST[1:0] pin	
'H' Input Voltage 1	VIH1	0.7 x DVDD	-	DVDD	V	PCLK, PD[26:0], LS[1:0], RVS, POL_PCLK, PLL_BW, TEST[1:0] pin	
'L' Input Current 1	IIL1	-5	-	+5	μΑ	VIN = DGND	
'H' Input Current 1	IIH1	-5	-	+5	μΑ	VIN = DVDD	
'L' Input Current 2	IIL2	-5	-	+5	μΑ	VIN = MSGND	
'H' Input Current 2	IIH2	-5	-	+5	μΑ	VIN = MSVDD	
'L' Output Voltage 1	VOL1	DGND	ı	0.3 x DVDD	V	IO = 1mA,CKD pin	
'H' Output Voltage 1	VOH1	0.7 x DVDD	-	DVDD	V	IO = -1mA,CKD pin	

Table 12 Current Consumption Ta=25°C, DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.

Ta=25°C, DVDD=MSVDD=1.80V and		Limits			11.70	O IV	
Parameter	Symbol	Min	Тур	Max	Unit	Conditions	
Shutdown Current	I <sub>op_sht_rx</sub>	-	0.2	10	μA	XSD = 'L', IDVDD + IMSVDD	
Standby Current	I <sub>op_stb_rx</sub>	-	0.2	10	μΑ	XSD = 'H', IDVDD + IMSVDD	
Active Current 1-channel / 27-bit Format	I <sub>op_act_rx1</sub>	-	14.0	18.5	mA	LS[1:0] = 'LL,' PLL_BW[1:0] = 'H' DVDD = MSVDD PCLK=15MHz,XSD='H CL=10pF Total operating current (IDVDD + IMSVDD ) with PD[26:0] inputs to ggling 0x2AAAAAA and 0x5555555	
Active Current 2-channel / 27-bit Format	I <sub>op_act_rx2</sub>	-	19.7	25.7	mA	LS[1:0] = 'LH,' PLL_BW[1:0] = 'H' DVDD = MSVDD PCLK=30MHz,XSD='H' CL=10pF Total operating current (IDVDD + IMSVDD) with PD[26:0] inputs to ggling 0x2AAAAAA and 0x5555555	
Active Current 3-channel/ 27-bit Format	I <sub>op_act_rx3</sub>	-	25.4	32.9	mA	LS[1:0] = 'HL,' PLL_BW[1:0] = 'H' DVDD = MSVDD PCLK=45MHz,XSD='H' CL=10pF Total operating current (IDVDD + IMSVDD) with PD[26:0] inputs to ggling 0x2AAAAAA and 0x5555555	

### 2) AC Characteristics Parallel Data Input Timing

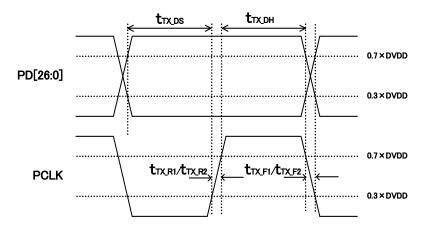


Fig.10 Parallel Data Input AC Timing

Table 13. Parallel Data Input AC Timing

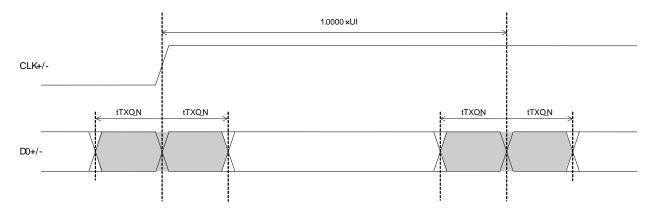
Fa=25°C. DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.

Ta=25°C, DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.								
Parameter	Symbol	Limits			Unit	Conditions		
Farameter			Max	Unit	Conditions			
	f <sub>TX_PCLK1</sub>	4	-	15	MHz	LS0=L, LS1=L		
PCLK Input Frequency	f <sub>TX_PCLK2</sub>	8	-	30	MHz	LS0=H, LS1=L		
	f <sub>TX_PCLK3</sub>	12	-	45	MHz	LS0=L, LS1=H		
PCLK Input Duty Cycle	t <sub>TX_DUTY</sub>	33	-	67	%			
Input Data Setup Time	t <sub>TX_DS</sub>	5.0	-	-	ns	POL_PCLK=H		
Input Data Hold Time	t <sub>TX_DH</sub>	5.0	-	-	ns	POL_PCLK=H		
Input Signal Rise Time 1	t <sub>TX_R1</sub>	-	-	10	ns	PCLK Frequency≦30MHz		
Input Signal Rise Time 2	t <sub>TX_R2</sub>	-	-	5	ns	PCLK Frequency>30MHz		
Input Signal Fall Time 1	t <sub>TX_F1</sub>	-	-	10	ns	PCLK Frequency≦30MHz		
Input Signal Fall Time 2	t <sub>TX F2</sub>	-	-	5	ns	PCLK Frequency>30MHz		

**Technical Note** 

#### 3) Serial Data Input Timing

Fig.11 and Table 14 shows Serial Data Input Timing of BU7963GUW.



UI = (1 cycle time of CLK+/-)/30 $N = \text{Bit position } (0 \le N \le 30)$ 

Fig.11. Serial Data input AC Timing

Table 14. Serial Data input AC Timing Ta=25°C, DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.

1=25 C, DVDD=103VDD=1.00V and DGND=10.00V, driess otherwise noted.								
Parameter	Cumbal		Limits	Unit	Conditions			
Falametei	Symbol	Min	Тур	Max	Offic	Conditions		
Output location CLKL+/- of N bit	t <sub>TXO_N</sub>	-0.1845×UI + UI×N	UI×N	0.1845×UI + UI×N	sec			

#### 4) Power-On / Off Sequence

#### Power-On Sequence

Fig.12 shows power-on sequence of BU7963GUW.

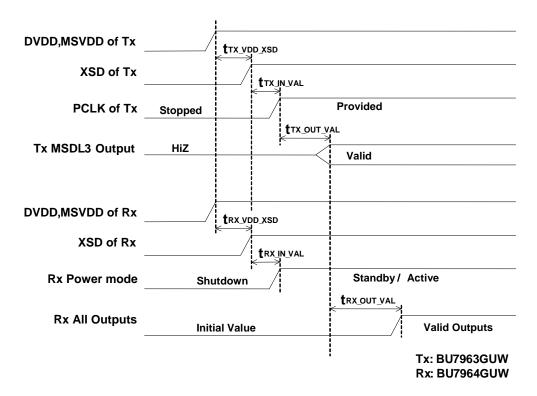


Fig.12. Power-On / Off Sequence

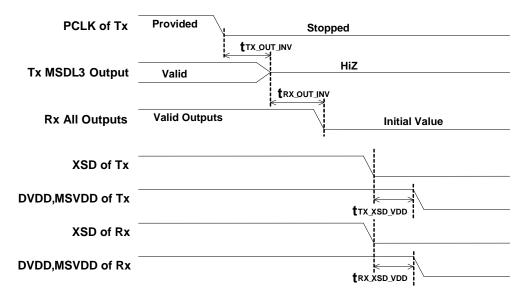
Table 15. Power-On Sequence Timing

Ta=25°C, DVDD=MS VDD=1.80V, and DGND=MSGND=0.00V, unless otherwise noted.

Parameter	Symbol		Limits		Unit	Conditions
Falametei	Symbol	Min	Тур	Max	Offic	
Core power supply startup time	t <sub>TX_VDD_IOV</sub>	0.0	-	2	ms	
Reset Valid After Power Supplied	t <sub>TX_VDD_XSD</sub>	10	-	-	μs	
PCLK clock input startup time	t <sub>TX_IN_VAL</sub>	10	-	-	μs	
MSDL3 output delay time	t <sub>TX_OUT_VAL</sub>	-	-	2	ms	

Power-Off Sequence

Fig.13 shows the power-off sequence of BU7963GUW.



Tx: BU7963GUW Rx: BU7964GUW

Fig.13. Power-Off Sequence

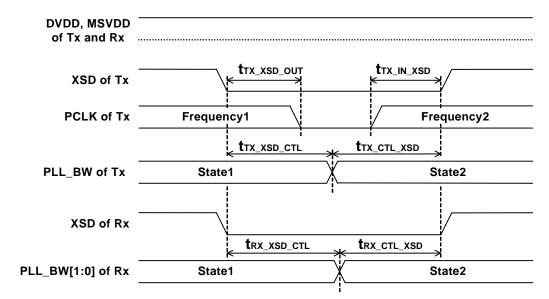
Table 16. Power-Off Sequence Timing

Ta=25°C, DVDD=MSVDD=1.80V, and DGND=MSGND=0.00V, unless otherwise noted.

Parameter	Cymphol		Limits			Conditions
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
MSDL3 output delay time	t <sub>TX_OUT_INV</sub>	-	-	100	μs	
XSD hold time	t <sub>TX_XSD_VDD</sub>	10	-	-	μs	
Core power off time	t <sub>TX_VDD_IOV</sub>	0.0	-	2	ms	

Frequency Change Sequence

Fig.14 shows the frequency change sequence of BU7963GUW.



Tx:BU7963GUW Rx:BU7964GUW

Fig.14. Frequency Change Sequence

Table 17. Frequency Change Sequence

Ta=25°C, DVDD=MSVDD=1.80V, and DGND=MSGND=0.00V, unless otherwise noted.

Davamatas	Cymala al		Limits		l lmi4	Conditions
Parameter	Symbol	Min	Тур	Max	Unit	
PCLK Clock Input Suspend Time	t <sub>TX_XSD_OUT</sub>	1.0	-	-	μs	
PCLK Clock Input Restart Time	t <sub>TX_IN_XSD</sub>	1.0	-	-	μs	
Control Signal Hold Time	t <sub>TX_XSD_CTL</sub>	2.0	-	-	μs	
Control Signal Setup Time	try or ven	2.0	_	_	IIS	

#### ● High-speed Channel Characteristic

#### Table 18. High-speed channel characteristic

Ta=25°C, DVDD=MSVDD=1.80V and DGND=MSGND=0.00V, unless otherwise noted.

Parameter	Symbol	Limits			Unit	Canditions
raiaillelei	Symbol	Min	Тур	Max	Unit	Conditions
Differential Voltage Range	$V_{diff\_tx}$	100	150	200	mVpp	
Common Mode Voltage Range	V <sub>cm_tx</sub>	0.8	0.9	1.0	V	
Vdiff_tx Rise Time	t <sub>r_tx</sub>	200	-	500	ps	
Vdiff_tx Fall Time	t <sub>f_tx</sub>	200	-	500	ps	
Operating Frequency	f <sub>opr_tx</sub>	-	-	225	MHz	
TX Hi-Z State Leak Current	I <sub>LEAK_TX</sub>	-3	1	3	μA	Shutdown mode or standby mode

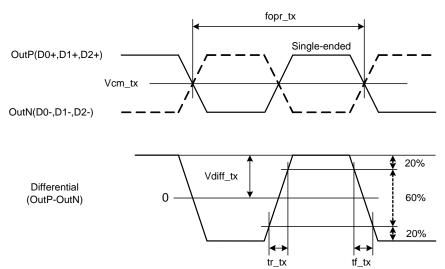


Fig.15. High-Speed Channel Electrical Characteristics

Fig.16 shows high-speed channel equivalent schematic.

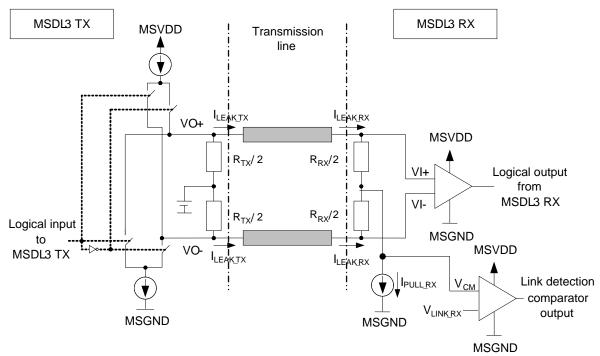


Fig.16. high-speed channel equivalent schematic.

#### Application Circuit Example

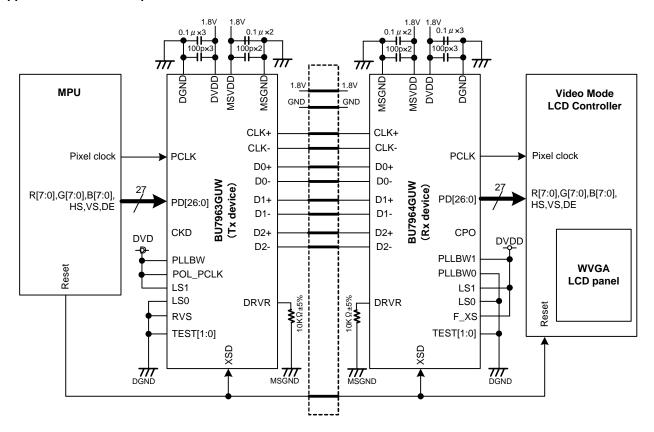


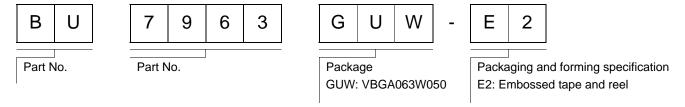
Fig.17. Application circuit

#### ●PCB Layout for MSDL3

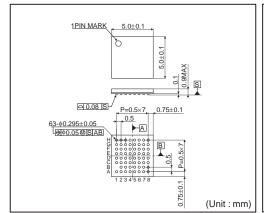
The following points should be considered about the wiring for PCB of MSDL3.

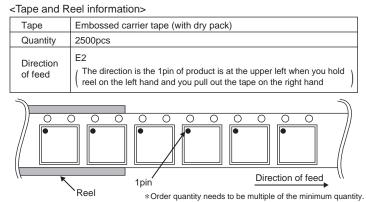
- · Wire for the PCB wiring pattern of high-speed channel (CLK, D0+/-, D1+/-, D2+/-) as short as possible.
- · The PCB wiring for high-speed channel must not use the through-hole.
- · Do not bend the wiring for high-speed channel squarely.
- · Make the wiring length of each high-speed channel the same length (within 0.5mm).

#### Ordering Part Number



#### VBGA063W050





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(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA	
CLASSⅢ	CL ACCTI	CLASS II b	CLASSⅢ	
CLASSIV	CLASSIII	CLASSⅢ	CLASSIII	

- 2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
  - [a] Installation of protection circuits or other protective devices to improve system safety
  - [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- 3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
  - [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
  - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
  - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl<sub>2</sub>, H<sub>2</sub>S, NH<sub>3</sub>, SO<sub>2</sub>, and NO<sub>2</sub>
  - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

#### **Precautions Regarding Application Examples and External Circuits**

- If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

#### **Precaution for Electrostatic**

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

#### **Precaution for Storage / Transportation**

- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
  - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
  - [b] the temperature or humidity exceeds those recommended by ROHM
  - the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- 2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

#### **Precaution for Product Label**

QR code printed on ROHM Products label is for ROHM's internal use only.

#### **Precaution for Disposition**

When disposing Products please dispose them properly using an authorized industry waste company.

#### **Precaution for Foreign Exchange and Foreign Trade act**

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

#### **Precaution Regarding Intellectual Property Rights**

- 1. All information and data including but not limited to application example contained in this document is for reference only. ROHM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such information or data. ROHM shall not be in any way responsible or liable for infringement of any intellectual property rights or other damages arising from use of such information or data.:
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#### **General Precaution**

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