Panasonic INDUSTRY

CMOS Type Self-Monitoring Sensor

Thru-beam Type Digital Displacement Sensor

HG-TSERIES

C€ FDA

The Industry's Highest-Class* Measurement Accuracy Is Now Yours.



Equipped with Self-monitoring Function

Ultra-slim

HG-T series

8 mm 0.315 in

The ultra-slim unit with a thickness of 8 mm 0.315 in allows easy installation in a limited space such as the inside of equipment.

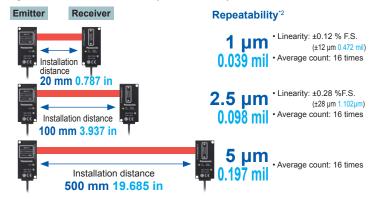
Wide-angle measurement

The belt-shaped laser beam with a measurement width of 10 mm 0.394 in is used for measurement of dimensions and positions.



Industry's highest*1 measurement accuracy

The **HG-T** series boasts repeatability $^{\cdot 2}$ of 1 μ m 0.039 mil and offers the highest*1 measurement accuracy in the industry.



- •Sampling cycle setting can be selected from two options
- Standard: 1 ms, High speed: 0.5 ms. •Average count setting can be selected from 11 options.
- 1 time, 2 times, 4 times, 8 times, 16 times, 32 times, 64 times, 128 times, 256 times, 512 times, 1,024 times
- *1 As of November 2020, in-company survey
- *2 This is the P-P value of digital measurement value with half shading at the middle position of the

Two types of sensor heads are available.

Two types of sensor heads, one with a standard type receiver and the other with a slim type receiver, are available.







Side view attachment is available (optional), HG-T1010

Side view attachment (optional) is available for the standard type sensor head HG-T1010. This attachment can bend the laser beam at a right angle to allow flexible installation of the sensor head.



Two M2 (length 4 mm 0.157 in) screws with washers are attached.



■Application example: Lithium-ion battery winding section

Conventional sensor head Sensor head mounted with side view attachment HG-T1010 Illustration prepared to show the difference.

Use of the side view attachment enables the installation of the sensor head closer to the winding section than when a conventional sensor head is used, thus contributing to the improvement of winding accuracy.

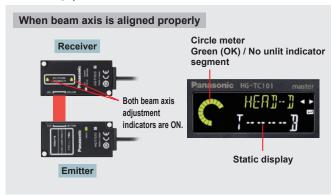
- * Two side view attachment units are required when using the attachment on both emitter and receiver
- * The slim type sensor head **HG-T1110** cannot be mounted with the side view attachment.
- * Be sure to confirm proper detection using actual equipment in advance when using the side view attachment.

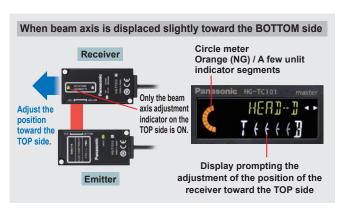
Ease of Installation

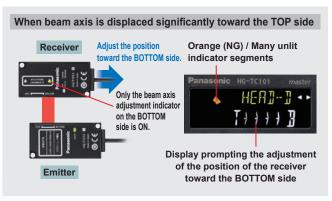
Beam axis adjustment assist function

The standard type sensor head HG-T1010 indicates the direction of receiver displacement relative to the emitter on the controller's display screen and with the beam axis adjustment indicators on the receiver in an easy-to-understand fashion.

* The slim type sensor head HG-T1110 displays the displacement information only on the controller's display section.

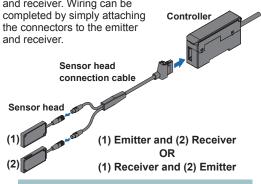






Automatic emitter / receiver cable recognition

The **HG-T** series automatically recognizes the positional relationship of the emitter and receiver connected to the sensor head connection cable at the time the controller is turned ON. This function eliminates the need for identifying the correct cables to connect to the emitter and receiver. Wiring can be



Emitter and receiver can be connected to either connectors!

* The sensor head connection cable is branched into two cables on the sensor head connecting side, but the two cables can be connected interchangeably to the emitter and receiver.

Die-cast aluminum case

The sensor head case is made of light and strong die-cast aluminum. It minimizes measurement fluctuations due to temperature effects. The die-cast aluminum case does not easily become distorted in shape by tightening of mounting screws as compared to a resin case. It is highly resistant to deterioration due to ageing. This robust case helps prevent deviations of beam axis alignment.





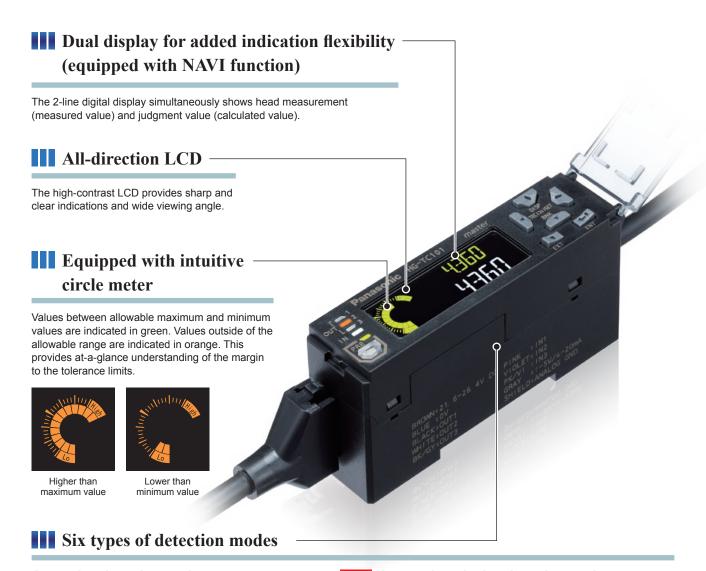
IP67 protection

The **HG-T** series features a protection structure of IP67 (IEC) so it can be used in a place where the product may be exposed to water or large amounts of dust.



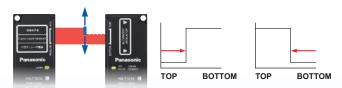
- * Note that if the beam emitting / receiving surfaces of the sensor head are adhered with water or dust, correct measurements become inaccurate
- The sensor head is watertight, but the connectors are not structurally resistant to dust, water or corrosion. Therefore, the HG-T series cannot be submerged in water or placed under falling water for measurement operation. Be sure to use the product in an appropriate environment.

High-performance Controller



Auto edge detection mode

Edge detection can be started from either the TOP or BOTTOM without registering the detection direction. This eliminates the need for checking the detection direction.



Edge detection mode



Inside diameter / gap detection mode



NEW User assigned edge detection mode

* Provided in products manufactured in November 2020 and after

The user can select any two edges from multiple edges on the measurement target and obtain the measurement of the distance between the two edges.



External form / width detection mode

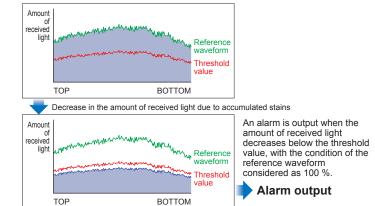


Central position detection mode

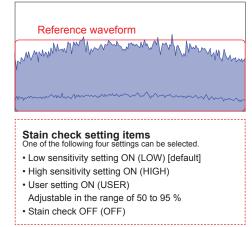


Monitoring of effects caused by stains

Notifies when the detection performance decreases due to accumulated stains.



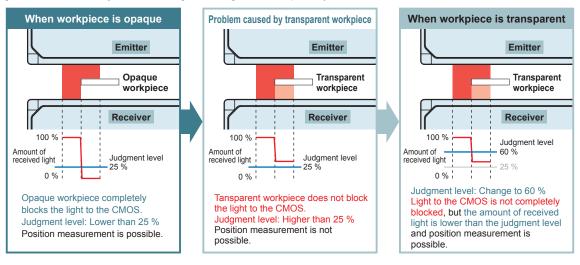
Checks the degree of contamination based on the amount of light of the reference waveform (considered as 100 %).



* The reference waveform can be confirmed by using a combination of the "HG-T Configuration Too!" USB-based PC setting software and USB communication unit SC-HG1-USB or RS-485 communication unit SC-HG1-485. For details, refer to page 15.

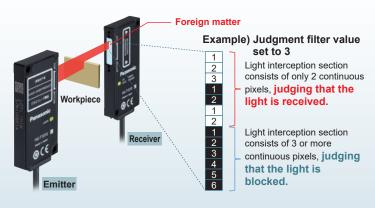
III Stable measurement of even transparent workpieces

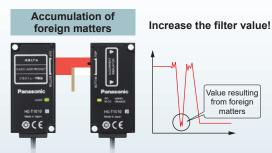
The judgment level can be adjusted according to the degree of transparency.



Elimination of effects caused by fine foreign matters

The judgment filter value can be adjusted for the prevention of erroneous detections due to fine foreign matters. The judgment filter value can be set to a desired value between 3 and 50.

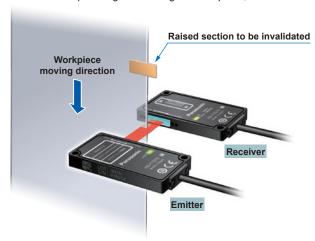




Increasing the filter value ignores values resulting from foreign matters.

Invalidation of abrupt changes in measurements * Provided in products manufactured in November

If there is an abrupt change at the edge of workpiece, this function invalidates the change and stabilizes the judgment value.



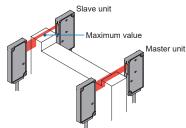


Equipped with 5 arithmetic functions

Calculation is performed using the measurements obtained by the connected controller. The judgment result can be displayed on the digital display of the master unit or output from the master unit. Connect only the controller to be used for calculation purposes.

1 Maximum value

The largest measured value among those in the master and slave units is set as calculated

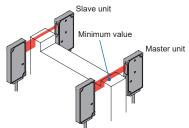


[Master unit] Calculated value

- = Largest [Slave unit] Measured value
- * None of the connected slave units outputs judgment (Always OFF)

2 Minimum value

The smallest measured value among those in the master and slave units is set as calculated



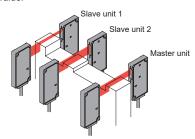
In above case:

[Master unit] Calculated value

- = Smallest [Master unit] Measured value
- * None of the connected slave units outputs judgment (Always OFF)

3 Average value

The average value of the measured values in the master and slave units is set as calculated



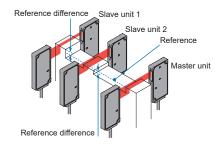
[Master unit] Calculated value = ([Master unit] + [Slave unit 1] + ... + [Slave unit n]) / (1 + n) n = Number of slave units

* None of the connected slave units outputs judgment result. (Always OFF)

Reference value

Each slave unit sets the difference between its measured value and the master unit's measured value as calculated value.

Each slave unit outputs judgment result.



In above case:

[Slave unit 1] Calculated value =

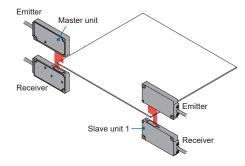
[Slave unit 1] Measured value – [Master unit] Measured value [Slave unit 2] Calculated value =

[Slave unit 2] Measured value - [Master unit] Measured value

- * The master unit performs judgment operation without performing calculation.
- * The master unit cannot use the hold function

5 Thickness / width

Two sensor heads clamp the detection target and computes its thickness/width



Calculated value = [Master unit] Measured value + [Slave unit 1] Measured value

- * The slave unit close to the master unit does not output the judgment result. (Always OFF)
- * When two or more slave units are connected, the second and subsequent slave units perform ordinary judgment operations without performing calculation.

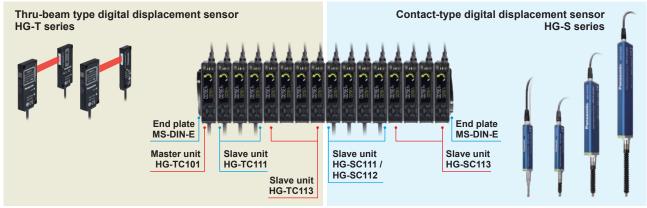
Connectable to compact-type digital displacement sensor HG-S series

When the $\mathbf{HG}\text{-}\mathbf{TC}_{\square}^{*1}$ controller is combined with the $\mathbf{HG}\text{-}\mathbf{SC}_{\square}^{*1}$ controller for contact-type digital displacement sensor $\mathbf{HG}\text{-}\mathbf{S}$ series, up to 15 slave units (up to 14 slave units if communication unit for digital displacement sensors is connected) can be connected to one master

Connect the same-series slave units close to the master unit and connect slave units of other series on the far side.

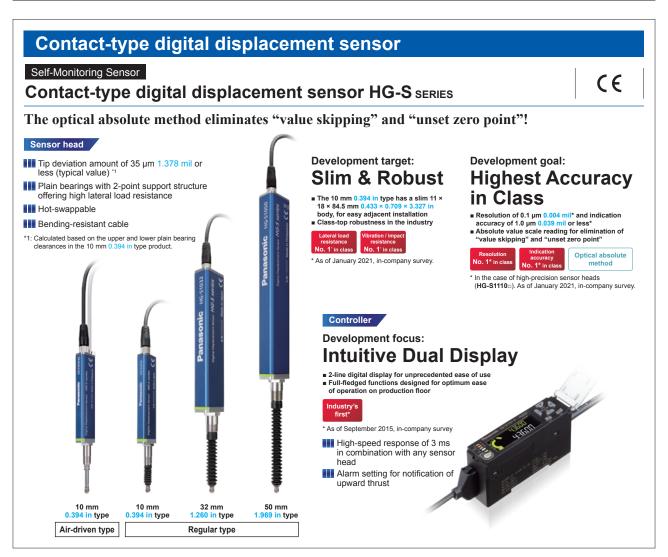
*1 Be sure to use controllers manufactured in or after February 2019.

< Example: Connection of 8 units of HG-S series to 8 units of HG-T series (NPN output type) >



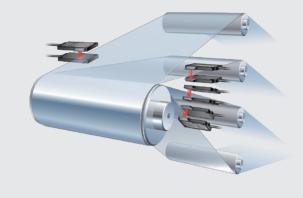
- When connecting slave units to a master unit, connect only NPN output types, or only PNP output types. Dissimilar output types cannot be connected together.
- * After the connection, attach end plates (optional) to both ends of the controller for secure installation.
 * If HG-TC
 □ and HG-SC
 □ controllers are used in combination, there are limitations on the functions below.

Item	Description of limitation
Calculation function	Calculation is only performed when the slave unit is the same series as the master unit. Calculation is not performed when the slave unit series is different from the master unit series. "CALC" does not appear in the display of a slave unit of a different series.
Input all	The master unit only performs input all when the slave units are the same series. A slave unit of a different series from the master unit does not perform input even when the external input settings match those of the master unit.
Copy function	Copying is only performed when the slave unit is the same series as the master unit. When copying is executed, "NOW COPY" appears even on the display of a slave unit of a different series from the master unit, but copying is not performed.



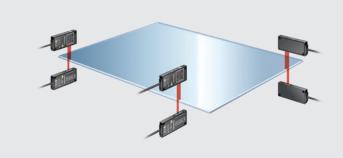
Applications





Use of the side view attachment (optional) enables the mounting of the sensor near the winding core for improved meander measurement accuracy.

Glass substrate positioning



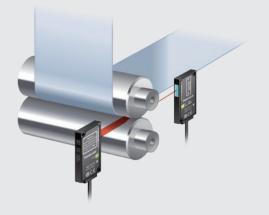
The judgment level adjustment function ensures stable detection and measurement of even transparent workpieces.

Detection of lifted bearing parts



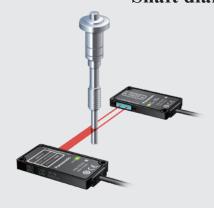
Use of the side view attachment (optional) enables the flexible installation of the sensor in a limited space

Detection of clearance between rollers



The clearance between rollers can be measured for stabilizing the workpiece quality. The compact head is easy to install.

Shaft diameter measurement



Shaft diameters can be measured. The original head structure and proprietary algorithm achieve stable detection without being affected by secondary reflections by metal surfaces.

Measurement of motor shaft eccentricity



Shaft eccentricity can be measured by using the central position detection mode and measuring the distance to the shaft center.

Communication unit for digital displacement sensors

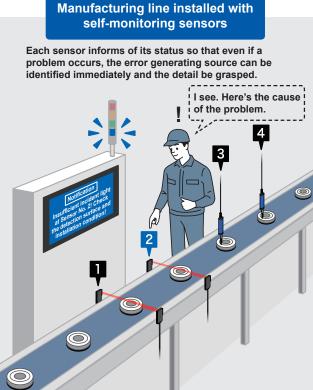
Compatible with selfmonitoring function

Suitable for use on manufacturing lines Sensor equipped with a new self-monitoring function!

A sensor with a self-monitoring function diagnoses its own state and notifies when readjustment of settings / setup is required or when maintenance is needed.

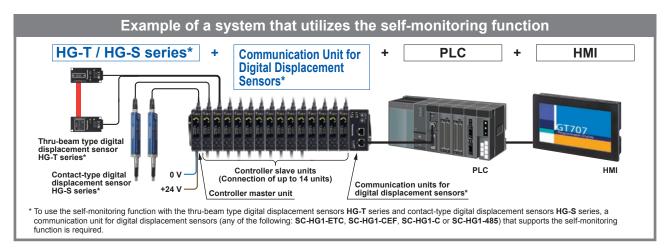
The sensor determines its status and indicates "Normal," "Notification," "Caution" or "Fault." When not in normal status, the sensor checks the cause of problem and corrective measure, thus reducing equipment downtime and maintenance workload.





■ Self-monitoring function: Four types of status indication and judgment of state

Status	Judgement of the state			
Normal	Operation is normal.			
Notification	Check the settings. Detected state is unstable.	* Recover to the normal state through checking installation and settings. Reduction in the incident light intensity.		
Caution	Getting close to the end of service life. Reached the state where the device should be replaced.	* Limitation in the writing frequency into the memory or in the operation hours, etc.		
Fault	Short-circuited or broken. Reached the state where it is impossible to control as a device.	* Short-circuited output, damaged EEPROM, etc.		



Identification of malfunctioning location and cause

The sensor self-diagnoses its state, so if a malfunction occur, it is easy to identify the problem location and discover the cause of the problem. Therefore, even if there is no experienced worker or skilled technician at the site to respond to the problem, it is possible to take an appropriate measure immediately. This minimizes the restoration time and reduces the maintenance workload.

Reduction of downtime

Reduction of maintenance workload

Positional deviation



Dirty detection surface



End-of-life / damaged sensor

Easy planning of maintenance schedule

Conventional sensors can generate unexpected malfunctions and require many hours for maintenance and replacement; thus, an unscheduled shutdown of the manufacturing line may be required from time to time. The self-monitoring function notifies the sensor replacement timing, thus allowing for planning the most efficient maintenance and replacement schedule. This helps prevent unexpected shutdowns of the manufacturing line and improves productivity.

Improved productivity

Predictive maintenance

■ Details of self-monitoring function

	HG-T series' self-monitoring function						
			Controller	r HG-TC□			
Status	Response parameter	Measures	Error code (Note 1)	Measurement alarm (Note 1)			
	Sensor head unconnected	Status check	E200	_			
	Connected sensor head incompatible	Status check	E230	_			
	Connected unit count check error	Status check	E160 (For master units only)	_			
	NPN / PNP output type mixture error	Status check	E100 (For master units only)	_			
	Calculated unlit count error	Status check	E110 (For master units only)	_			
Notification	copy excountries (clare unit problem)	Status check	E170 (For master units only)	_			
	Detection capability limit (obtained edge information) (Note 2)	Sensing object check	_	Measurement alarm 1			
	The amount of entering light is too much due to the influences of ambient light, etc. (Note 2)	Status check	_	Measurement alarm 1			
	The amount of entering light decreases due to stain on the detection surface, beam axis misalignment, etc.	Sensing object check	_	Measurement alarm 2			
	The specified measurement direction differs from the insertion direction of the detected object.	Status check / Sensing object check	_	Measurement alarm 2			
	Controller cumulative run time exceeded (87,600 hours)	Controller replacement	_	_			
Caution	Sensor head cumulative run time exceeded (87,600 hours)	Sensor head replacement	_	_			
Caution	Controller memory saving count exceeded (1,000,000 times)	Controller replacement	_	_			
	Sensor head memory saving count exceeded (for receivers only, 1,000,000 times)	Sensor head replacement	_	_			
			E600				
	Controller memory function damaged	Controller replacement	E610	_			
			E620				
	Sensor head memory function damaged	Sensor head replacement	E630 (For receivers only) E640 (For emitters only)	_			
Fault	Output section short-circuit error	Status check / Replacement	E700	_			
	Detection circuit damaged	Sensor head replacement	E240	_			
			E900				
			E910				
	System error	Controller replacement	E911	_			
			E912				
			E920				

Notes: 1) Error codes and alarms are displayed on HG-TC□ controllers.

²⁾ If "Alarm condition selection (ALM.CND)" is set to "Hold last value (HOLD)", Measurement alarm 1 is not notified.

Communication unit for digital displacement sensors

Compatible with selfmonitoring function

Direct transfer of measurement data obtained by multiple sensors to host device!

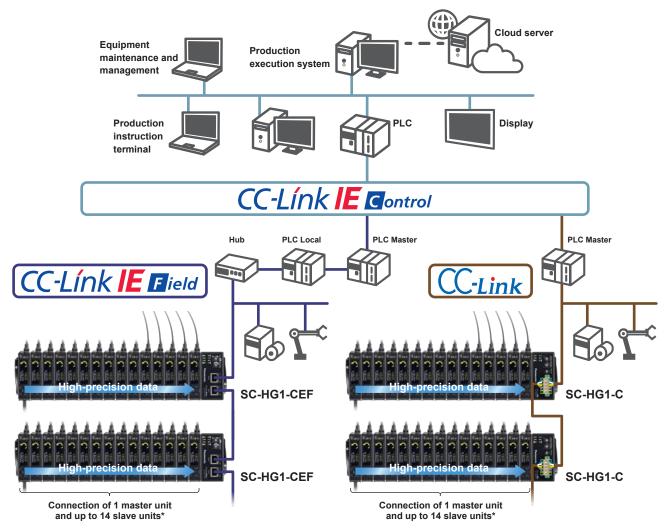
CC-Link IE Field Communication Unit / CC-Link Communication Unit

Compatible with self-monitoring function

Use of our communication unit for digital displacement sensors allows direct connection to the CC-Link / CC-Link IE Field network.

This enables real-time acquisition of digital data and ON / OFF information without any program.

Furthermore, it can be used to change controller settings and log measurement data via CC-Link / CC-Link IE Field network, for example, for predictive maintenance of digital displacement sensors.



^{*} When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.





^{*} CC-Link IE Field and CC-Link are trademarks of Mitsubishi Electric Corporation, and are controlled by the CC-Link Partner Association.

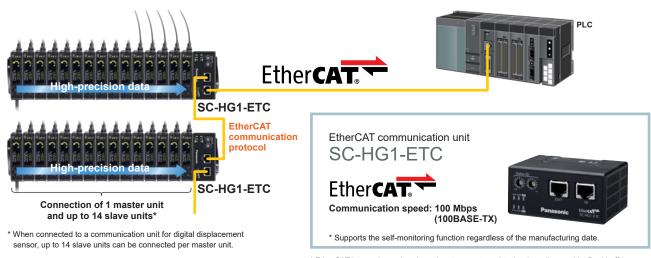
EtherCAT Communication Unit

Compatible with self-monitoring function

Our product line also includes a communication unit that enables connection with EtherCAT.

This unit communicates measurement (judgment) data and error codes cyclically at a high-speed sampling rate and transfers the data to the host device with accuracy intact.

Furthermore, settings of multiple sensors can be read and written, and the bank can be switched via EtherCAT.

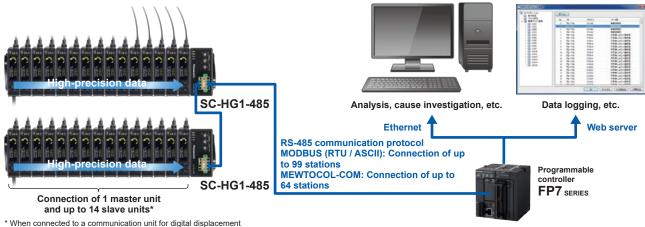


EtherCAT is a registered trademark patent-protected technology, licensed by Beckhoff Automation GmbH of Germany

RS-485 Communication Unit

Compatible with self-monitoring function

For use of high-precision measurement results as traceability data. Transfers not only measurements results obtained at multiple points but also setting statuses as digital data in a batch. Provides powerful support to the management of inspection records and identification of failure causes.



* When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.



USB-based PC setting software

HG-T Configuration Tool

- Compatible communication unit: SC-HG1-USB / SC-HG1-485 Compatible OS: Microsoft Windows[®] 8 (8.1) (32 bit / 64 bit), Microsoft Windows® 10 (32 bit / 64 bit)
- Required RAM: 2 GB or more
 Required hard disk space: 200 MB or more
- Communication interface: USB2.0 (SC-HG1-USB), RS-485 (SC-HG1-485)
- SC-HG1-485 supported by Ver. 1.20 or newer version of HG-T Configuration Tool
- For the detail of the USB-based PC setting software, refer to page 15.
- Microsoft and Windows are registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

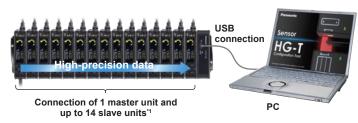


Communication unit for digital displacement sensors

USB communication unit

The USB communication unit provides convenient functions that facilitate the setting of the HG-T series while observing the waveform of received light by operating the dedicated USB-based PC setting software. The USB-based PC setting software can be downloaded free from our website.

* Not compatible with self-monitoring function.



* When connected to the communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.

USB communication unit SC-HG1-USB



Communication specification: USB 2.0 Full Speed*2 Communication protocol: Proprietary protocol USB port: USB Mini-B (1 port)

USB-based PC setting software

HG-T Configuration Tool

- Compatible communication unit: SC-HG1-USB / SC-HG1-485
- Compatible OS: Microsoft Windows® 8 (8.1) (32 bit / 64 bit),
 Microsoft Windows® 10 (32 bit / 64 bit)
- Required RAM: 2 GB or more
- Required hard disk space: 200 MB or more
- Communication interface: USB2.0 (SC-HG1-USB), RS-485 (SC-HG1-485)
- * SC-HG1-485 supported by Ver. 1.20 or newer version of HG-T Configuration
- * For the detail of the USB-based PC setting software, refer to page 15.
- * Microsoft and Windows are registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

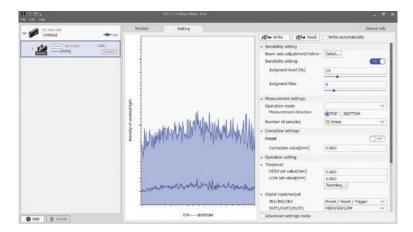
^{*1} Dependent on PC environment.

Convenient Tool Software

When the USB-based PC setting software, "HG-T Configuration Tool," is used together with the USB communication unit SC-HG1-USB or RS-485 communication unit SC-HG1-485, current values and settings in the HG-T series can be confirmed and changed using a PC.

USB-based PC setting software

HG-T Configuration Tool



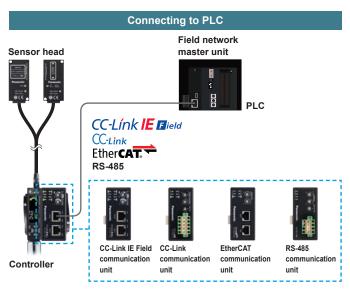
Settings such as name, judgment level and filter value can be changed for each controller while observing the waveform.



- Measuring the master workpiece nce (±)[mm] 0.100
- Compatible communication unit 123: SC-HG1-USB, SC-HG1-485
- Compatible OS'4'5: Microsoft Windows® 8 (8.1) (32 bit / 64 bit), Microsoft Windows® 10 (32 bit / 64 bit)
- Required RAM: 2 GB or more
- Required hard disk space: 200 MB or more
- Communication interface: USB2.0 (SC-HG1-USB), RS-485 (SC-HG1-485)
- *1: SC-HG1-485 supported by Ver. 1.20 or newer version of HG-T Configuration
- *2: SC-HG1-USB and SC-HG1-485 cannot be used simultaneously.
- *3: To connect SC-HG1-485 via USB, the customer must arrange a USB2.0→RS-485 converter.
- *4: Microsoft and Windows are registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.
- *5: OS versions of which Microsoft has ended support are excluded

The USB-based PC setting software, "HG-T Configuration Tool," can be downloaded free from our website.

System configuration



Our product lineup includes communication units compatible with a variety of field networks such as CC-Link, CC-Link IE Field and EtherCAT. They can link with a production system and enable the incorporation and utilization of IoT.

Connecting to PC Sensor head Sensor head communication unit RS-485 communication unit **USB-based PC setting software** (HG-T Configuration Tool) RS-485 connection/ Controller USB connection

- * USB communication unit and RS-485 communication unit cannot be used simultaneously.

 To connect RS-485 communication unit via USB, the customer must arrange a
- USB2.0→RS-485 converter

ORDER GUIDE

Sensor heads

Туре	e	Appearance	Measurement width	Installation distance	Repeatability (Note 1)	Laser class	Model No.
Measurement width	Standard type	Emitter: 8 × 30 × 60 mm 0.315 × 1.181 × 2.362 in Receiver: 8 × 30 × 60 mm 0.315 × 1.181 × 2.362 in	10 mm	0 to 500 mm	1 µm 0.039 mil (Installation distance: 20 mm 0.787 in) 2.5 µm 0.098 mil (Installation)	Class 1 ∫IEC / JIS / ි	HG-T1010
10 mm 0.394 in	Slim type	Emitter: 8 × 30 × 60 mm 0.315 × 1.181 × 2.362 in Receiver: 8 × 20 × 60 mm 0.315 × 0.787 × 2.362 in	0.394 in	0 to 19.685 in	distance: 100 mm 3.937 in 5 µm 0.197 mil (Installation distance: 500 mm 19.685 in)	GB / FDA (Note 2)	HG-T1110

Notes: 1) This is the P-P value of digital measurement value with half shading at the middle position of the installation distance.

2) This product complies with 21 CFR 1040.10 and 1040.11 Laser Notice No. 50, dated June 24, 2007, issued by CDRH (Center for Devices and Radiological Health) under the FDA (Food and Drug Administration).

Sensor head connection cables

Туре	Appearance	Model No.	Cable length	Description
		CN-HT-C2	2 m 6.562 ft	
Sensor head	connection	CN-HT-C5	5 m 16.404 ft	This cable is used to connect the sensor head to the controller. The cable is branched into two cables on the sensor
cables		CN-HT-C10	10 m 32.808 ft	head connecting side, but the two cables can be connected interchangeably to the emitter and receiver.
	-	CN-HT-C20	20 m 65.617 ft	

Controllers

Туре		Appearance	Model No.	Output	Maximum number of connectable controllers
Master	High performance type		HG-TC101	NPN open-collector transistor	
unit	riigii perioriilarice type		HG-TC101-P	PNP open-collector transistor	
			HG-TC111	NPN open-collector transistor	Up to 15 slave units can be connected
Slave	High performance type		HG-TC111-P	PNP open-collector transistor	per master unit (Note)
units	Wire-saving type		HG-TC113	_	

Note: When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.

ORDER GUIDE

Communication units for digital displacement sensors

Туре	Appearance	Model No.	Description
CC-Link IE Field communication unit Compatible with self-monitoring function (Note 1)	STORY OF THE PARTY	SC-HG1-CEF	Can directly send high-precision measurement values to a CC-Link IE Field host device. • Communication method: CC-Link IE Field • Number of connected units Host (CC-Link IE Field): Max. 121 units (1 master station, 120 slave stations) Controllers: Maximum of 15 units (1 master, 14 slaves) per SC-HG1-CEF unit
CC-Link communication unit Compatible with self-monitoring function (Note 1)		Can directly send high-precision measurement values to CC-Link • Communication method Switchable CC-Link Ver.1.10 or 2.00 • Number of occupied station CC-Link Ver.1.10: 4 stations, CC-Link Ver.2.00: Switchable 2 or • Number of connected units Controllers: Maximum of 15 units (1 master, 14 slaves) per SC-	
EtherCAT communication unit Compatible with self-monitoring function (Note 1)	GG C C C C C C C C C C C C C C C C C C	SC-HG1-ETC	Can directly send high-precision measurement values to EtherCAT Master. • Communication protocol: EtherCAT • Number of connected units Controllers: Maximum of 15 units (1 master, 14 slaves) per SC-HG1-ETC unit
RS-485 communication unit Compatible with self-monitoring function (Note 1)	All Page 100	SC-HG1-485	Can directly send high-precision measurement values by RS-485 communication. • Communication protocol: MODBUS (RTU / ASCII) / MEWTOCOL-COM • Number of connected units Host (RS-485): 1 to 99 units when MODBUS (RTU / ASCII) is used, 1 to 64 units when MEWTOCOL-COM is used Controllers: Maximum of 15 units (1 master, 14 slaves) per SC-HG1-485 unit When used together with the "HG-T Configuration Tool" USB-based PC setting software (Ver. 1.20 or newer), current values and settings in the HG-T series can be confirmed or changed on the PC screen. * The USB-based PC setting software, "HG-T Configuration Tool," can be downloaded free from our website.
USB communication unit (Note 2)		SC-HG1-USB	When used together with the "HG-T Configuration Tool" USB-based PC setting software, current values and settings in the HG-T series can be confirmed or changed on the PC screen. * The USB-based PC setting software, "HG-T Configuration Tool," can be downloaded free from our website. • Communication specification: USB 2.0 Full Speed (Note 3) • Communication protocol: Proprietary protocol • USB port: USB Mini-B (1 port) • Number of connectable units Controller: Up to 15 units (1 master unit, 14 slave units) per SC-HG1-USB unit

Notes: 1) The following products support the self-monitoring function:
SC-HG1-CEF: Products shipped in and after December 2019, SC-HG1-C: Products manufactured in and after December 2019, SC-HG1-ETC: All,
SC-HG1-485: Products manufactured on and after November 18, 2019.

2) The USB communication unit cannot be used with contact-type digital displacement sensors HG-S series.

3) Dependent on PC environment.

End plates

Туре	Appearance	Model No.	Description
End plates		MS-DIN-E	End plates are used to securely hold the controller and communication unit for digital displacement sensors connected on a DIN rail by pressing from both ends. Be sure to use the end plates when connecting units. 2 pcs per set

OPTIONS

Туре	Appearance	Model No.	Description
Side view attachment		HG-TSV10	Designed for exclusive use with the HG-T1010 standard type sensor head. This attachment can bend the laser beam at a right angle, thus allowing flexible installation of the sensor head. Two M2 (length 4 mm 0.157 in) screws with washers are attached. * Two pieces of attachment are required when using the attachment on both emitter and receiver. * Be sure to confirm proper detection using actual equipment in advance when using the attachment.

Sensor heads

		Туре	Measurement width 10 mm 0.394 in / Standard type	Measurement width 10 mm 0.394 in / Slim type			
Item		Model No.	HG-T1010	HG-T1110			
Regulatory compliance			EMC Directive, RoHS Directive, FDA regulations				
Compatible controller		oller	HG-TC101 (-P), HG-TC111 (-P), HG-TC113				
Posi	tion detection	n method	CMOS	-based			
Insta	ıllation distar	ice	0 to 500 mm (0 to 19.685 in			
Mea	surement wid	dth	10 mm (0.394 in			
Light	t source		Red semiconductor laser: Class Maximum output: 0.3 mW, Peal				
Repeatability (Note 3)		ote 3)	1 μm 0.039 mil (Installation o 2.5 μm 0.098 mil (Installation 5 μm 0.197 mil (Installation o	n distance: 100 mm 3.937 in)			
Line	arity (Note 4))		±0.12 % F.S. (Installation distance: 20 mm 0.787 in) ±0.28 % F.S. (Installation distance: 100 mm 3.937 in)			
Minimum sensing object (Note 5)		g object (Note 5)	ø0.5 mm ø0.020 in (Installation distance: 500 mm 19.685 in)				
Tem	perature char	acteristics (Note 6)	±0.03 % F.S./°C				
_		Emitter	Laser radiation indicator (Green)				
Ope	ration ator	Receiver	Beam axis adjustment indicator (Orange / Green), Judgment output indicator (Orange / Green)	Judgment output indicator (Orange / Green)			
Pollu	ıtion degree		2				
Ope	rating altitude	е	2,000 m 6,561.68 ft or less (Note 7)				
е	Protection		IP67 (IEC) (Excluding connectors)				
stanc	Ambient ter	mperature	-10 to +45 °C +14 to +113 °F (No dew condensation of	or icing allowed), Storage: -20 to +60 °C -4 to +140 °F			
resis	Ambient hu	midity	35 to 85 % RH, Storage: 35 to 85 % RH				
ental	Ambient illu	minance	Incandescent light: 5,000 lx or less at the light-receiving face (Note 8)				
onme	Insulation re	esistance	20 MΩ or higher, using 250 V DC me	gger (between all terminals and case)			
Environmental resistance	Vibration re	sistance	10 to 55 Hz frequency, 1.5 mm 0.059 in double am	•			
	Shock resis	tance	196 m/s² acceleration in X, Y an	nd Z directions three times each			
Grou	inding metho	od	Capacitor	grounding			
Mate	erial		Case: Die-cast aluminum, Light emitti	ng and light receiving surfaces: Glass			
Cabl	е		0.2 m 0.656 ft 4-core shielded	d cable with round connectors			
Net	weight		Emitter: 30 g approx., Receiver: 30 g approx.	Emitter: 30 g approx., Receiver: 25 g approx.			

Notes: 1) Specification values are based on the digital measurement values obtained by the sensor head and controller HG-TC ... Where measurement conditions have not been specified precisely, the conditions used were as follows: ambient temperature = +20 °C +68 °F, controller's average count setting 16 times, measurement target = nontransparent knife edge, installation distance = 100 mm 3.937 in, positional condition of measurement target = Half

- times, measurement target = nontransparent knile edge, installation distance = 100 min 3.537 m, position of ineasurement target = shading at the middle position of installation distance.

 2) This product complies with 21 CFR 1040.10 and 1040.11 Laser Notice No. 50, dated June 24, 2007, issued by CDRH (Center for Devices and Radiological Health) under the FDA (Food and Drug Administration).

 3) This is the P-P value of digital measurement value with half shading at the middle position of the installation distance.

 4) Indicates an error with the ideal straight line of digital measured values.

 5) When the light is blocked at the center position of 500 mm 10.685 in installation distance.

- 5) When the light is blocked at the center position of 500 mm 19,685 in installation distance 6) When the light is half-blocked at the center position of 100 mm 3.937 in installation distance
- 7) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m. 8) When the sampling cycle of the controller is set to "standard sampling"

Controller

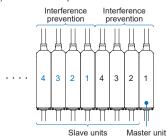
			Master unit	Slave unit				
		Туре			140			
	\		High performance type	High performance type	Wire-saving type			
	Model No.	NPN output	HG-TC101	HG-TC111	HG-TC113			
Item	ı \ №	PNP output	HG-TC101-P	HG-TC111-P				
Regu	ulatory com	pliance	EMC I	Directive, RoHS Directive				
Com	patible sen	sor head	HG-T1010, HG-T1110					
	Number of connectable units		Up to 15 slave units ca	an be connected to a master unit. (Note 2)				
	oly voltage ent consum	nption (Note 3)	24 V DC ±10 %, including ripple 0.5 V	(P-P) / 100 mA or less (when sensor head is connected	d)			
Analoutpi	uts	Analog voltage output	Voltage output range: 1 to 5 V/F.S. (default value) Linearity: ±0.05 % F.S.	 Output when alarm occurs: 5.2 V Output impedance: 100 Ω max. 	_			
	tching) (Note 4)	Analog current output	Current output range: 4 to 20 mA/F.S. (default value) Linearity: ±0.25 % F.S.	 Output when alarm occurs: 0 mA Load impedance: 250 Ω max. 	_			
	rol outputs out 1, Outp	ut 2, Output 3)	<npn output="" type=""> NPN open-collector transistor Maximum sink current: 50 mA (Note 5) Applied voltage: 30 V DC or less (between output and 0 V) Residual voltage: 1.5 V or less (at 50 mA sink current) Leakage current: 0.1 mA or less </npn>	<pnp output="" type=""> PNP open-collector transistor • Maximum source current: 50 mA (Note 5) • Applied voltage: 30 V DC or less (between output and +V) • Residual voltage: 1.5 V or less (at 50 mA source current) • Leakage current: 0.1 mA or less</pnp>	_			
	Short-circ	uit protection	Incorporated (auto	omatic reset type)				
	Judgment	output	N.O. / N.C. s	witching type				
	Alarm out	put	Open when a	alarm occurs				
Exte	rnal output	switching	Output 1, Output 2, and Output 3 can be swit	tched to 3-value, 2-value, Logic, and Logic 2.	_			
	External inputs (Input 1, Input 2, Input 3)		<npn output="" type=""> Non-contact input or NPN open-collector transistor Input conditions Invalid: +8 V to +V DC or open Valid: 0 to +1.2 V DC Input impedance: 10 kΩ approx. </npn>	<pnp output="" type=""> Non-contact input or PNP open-collector transistor • Input conditions Invalid: 0 to +0.6 V DC or open Valid: +4 V to +V DC • Input impedance: 10 kΩ approx.</pnp>	_			
	Input time		Trigger input: 2 ms or more (ON) Laser emission stop input, preset input, reset input,	bank input A/B(Note 6): 20 ms or more (ON)				
Exter	nal input s	witching	Input 1, Input 2, and Input 3 can be switched to "Pre Select (Preset, Reset, Trigger)", or "Laser emission:		_			
Sam	pling cycle		1 ms (standard san	1 ms (standard sampling) / 0.5 ms (high-speed sampling)				
Aver		(response time)		mes (9 ms), 16 times (17 ms), 32 times (33 ms), 64 times (513 ms), and 1,024 times (1,025 ms) switching type				
Disp	lay resoluti	on		1 μm 0.039 mil				
Disp	lay range		-199.999 to	199.999 mm -7.874 to 7.874 in				
Inter	ference pre	vention function	Incorporated (Note 7)	-				
Pollut		Operating altitude	2 / 2,000	m 6561.68 ft or less (Note 8)				
e	Protection			IP40 (IEC)				
istance		emperature	·	ation or icing allowed) (Note 5), Storage: -20 to +60 °C	4 to +140 °F			
resi	Ambient h		35 to 85 % RH, Storage: 35 to 85 % RH					
ental		ithstandability resistance	1,000 V AC for one minute between all supply terminals connected together and enclosure 20 MΩ, or more, with 250 V DC megger between all supply terminals connected together and enclosure					
Environmental res		resistance		aplitude (10 to 58 Hz), Maximum acceleration 49 m/s ² (
Щ	Shock res	istance		approx.) in X, Y and Z directions five times each				
Mate			,	Cover: Polycarbonate, Switches: Polyacetal				
Cabl			0.2 mm ² 2-core (brown and blue lead wires) / 0.15 mm ² 7-core composite cable, 2 m 6.562 ft long	0.15 mm ² 7-core composite cable, 2 m 6.562 ft long	_			
Net v	weight		140 g approx.	140 g approx.	60 g approx.			
			J Trr	U - FF -	1 0 FF -			

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage +24 V DC, ambient temperature +20 $^{\circ}\text{C}$ +68 $^{\circ}\text{F}.$
 - 2) When connected to a communication unit for digital displacement sensor, up to 14 slave units can be connected per master unit.
 - 3) Current consumption does not include analog current output.

 - A) Linearity is a value calculated from digitally measured values at F.S. = 16 mA for current output or F.S. = 4 V for voltage output.
 When slave units are connected to the master unit, the maximum sink current / source current of control output and ambient temperature vary depending on the number of connected slave units as shown below.

Number of connected slave units When communication unit is connected		Maximum sink current and source current of control output	
1 to 7 units	1 to 6 units	20 mA	-10 to +45 °C
8 to 15 units	7 to 14 units	10 mA	+14 to +113 °F

- 6) Average count (response time) is for when the sampling cycle is set to 1 ms (standard sampling). Response times differ when the sampling cycle is set to 0.5 ms (high-speed sampling).7) This function operates for each set of 4 connected controllers.



8) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

Communication unit for digital displacement sensors

	Designation	CC-Link IE Field communication unit		
Iter	m Model No.	Model No. SC-HG1-CEF		
Regulatory compliance		EMC Directive, RoHS Directive		
Compatible controllers		HG-TC□, HG-SC□		
Maximum number of connectable controllers		Maximum of 15 controllers (one master, 14 slaves) per SC-HG1-CEF unit		
Sup	ply voltage (Note 2)	24 V DC ±10 %, including 0.5 V ripple (P-P)		
Cur	rent consumption	200 mA or less		
Cor	nmunication method	CC-Link IE Field		
Rer	mote station type	Remote device station		
Net	work No. setting	1 to 239 (decimal) [1 to EF (hex)] (0 and 240 or more: Error) (Note 3)		
Cyclic transmission (Maximum number of links per station)		RX / RY:128 points each (128 bits), 16 bytes, RWr / RWw: 64 points each (64 words), 128 bytes		
Tra	nsient transmission	Server function only, data size 1024 bytes		
Sta	tion No. setting	1 to 120 (decimal) (0 and 121 or more: Error)		
Cor	mmunication speed	1 Gbps		
Transmission line type		Line, star (mixing of line and star types is possible), ring		
Maximum transmission distance		100 m 328.084 ft		
Maximum number of units connectable		121 units (1 master station, 120 slave stations)		
Cascade connection levels		Maximum 20		
Pol	ution degree	2		
Operating altitude		2,000 m 6561.68 ft or less (Note 4)		
	Protection	IP40 (IEC)		
	Ambient temperature	-10 to +45°C +14 to +113 °F (No dew condensation or icing allowed), Storage: -20 to +60°C -4 to +140°F		
ance	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH		
resista	Voltage withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure		
Environmental resistance	Insulation resistance	$20~\text{M}\Omega$ or more, with 250 V DC megger between all supply terminals connected together and enclosure		
	Vibration resistance	10 to 150 Hz frequency, 0.75 mm 0.030 in double amplitude (10 to 58Hz), maximum acceleration 49 m/s² (58 to 150 Hz) in X, Y and Z directions for two hours each		
	Shock resistance	98 m/s² acceleration (10 G approx.) in X, Y and Z directions five times each		
Material		Enclosure: Polycarbonate		
Communication cable		Ethernet cable that satisfies 1000BASE-T standard Category 5e or higher (Double-shielded / STP, straight cable) (Note 5)		
We	ight	Net weight: 100 g approx., Gross weight: 150 g approx.		
Nlote	Notes: 1) Where measurement conditions have not been specified precisely			

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were ambient temperature +20 °C +68

- 2) Power is supplied from a connected controller / master controller.
- 3) For the network number setting on this product, convert the network number to hex and set the hex value.
- 4) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

 5) Use CC-Link Partner Association recommended cable.

_						
	Designation	CC-Link communication unit				
Iter	m Model No.	SC-HG1-C				
Reg	gulatory compliance	EMC Directive (Note 2), RoHS Directive				
Cor	mpatible controllers		HG	-TC□, HG-	SC□	
	kimum number of	Maximum of 15 controllers (one master, 14 slaves)				
	nectable controllers	per SC-HG1-C unit				
	ply voltage (Note 3)	24 V DC ±10 %, including 0.5 V ripple (P-P)				
	rent consumption	80 mA or less				
Con	nmunication method	Switchable CC-Link Ver.1.10 or 2.00				00
Rer	note station type			te device s		
	mber of occupied	CC-Link Ver.1.10: 4 stations,				
stat			CC-Link Ver.2.00: Switchable 2 or 4 stations			
	tion No. setting	1 to 64 (0 and 65 or more: Error)				
	nmunication speed	10 Mbps	5 Mbps		625 kbps	156 kbps
Maximum transmission		100 m	160 m	400 m	900 m	1,200 m
	ance	328.084 ft	524.934 ft		2,952.756 ft	3,937.008 ft
	lution degree	ļ		2		
Оре	erating altitude	2,000 m 6561.68 ft or less (Note 4)				
	Protection	IP40 (IEC) -10 to +45°C +14 to +113 °F (No dew condensation				
Φ	Ambient					
S	temperature	or icing allowed), Storage: -20 to +60°C -4 to +140°F				
sta	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH				
esi	Voltage	1,000 V AC for one min. between all supply				
<u>=</u>	withstandability Insulation	terminals connected together and enclosure				
ent	resistance	20 MΩ or more, with 250 V DC megger between all				
Environmental resistance	resistance	supply terminals connected together and enclosure				
5	Vibration	10 to 150 Hz frequency, 0.75 mm 0.030 in double amplitude (10 to 58 Hz), maximum acceleration 49 m/s ²				
ΙŽ	resistance	(58 to 150 Hz) in X, Y and Z directions for two hours each				
Ш		98 m/s ² acceleration (10 G approx.) in X, Y and Z				
	Shock resistance	directions five times each				
Material		Enclosure: Polycarbonate				
Communication cable		Specified cable (shielded twisted cable) (Note 5)				
Weight		Net weight: 80 g approx., Gross weight: 130 g approx.				

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were ambient temperature +20 °C +68 °F.

 2) If our product will be incorporated in a customer product that will comply with the EMC Directive, install our product in a conductive box in accordance with "PLC User's Manual [Published by Mitsubishi Electric Corporation]".

 3) Power is supplied from a connected controller / master controller.

 4) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

 5) Use only a special-use communication cable that is approved by the CC-Link Partner Association.

	Designation	EtherCAT communication unit		
Item Model No.		SC-HG1-ETC		
Regulatory compliance		EMC Directive, RoHS Directive		
Cor	npatible controllers	HG-TC□, HG-SC□		
Max	kimum number of	Maximum of 15 controllers (one master, 14 slaves)		
	nectable controllers	per SC-HG1-ETC unit		
Sup	ply voltage (Note 2)	24 V DC ±10 %, including ripple 0.5 V (P-P)		
	rent consumption	100 mA or less		
	nmunication protocol	EtherCAT		
Compliance		IEEE 802.3u (100BASE-TX)		
	nmunication speed	100 Mbps (100BASE-TX)		
Communication connector		RJ-45 × 2		
Node-to-node distance		100 m 328.084 ft or less		
Supported functions		Process data object communication (cyclic communication) Mailbox communication (message communication) CoE Explicit Device Identification Station Alias		
Poll	ution degree	2		
Operating altitude (Note 3)		2,000 m 6,561.68 ft or less		
	Ambient	-10 to +45 °C +14 to +113 °F (No dew condensation		
Se	temperature	or icing allowed), Storage: -20 to +60 °C -4 to +140 °F		
tan	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH		
Sist	Voltage	1,000 V AC for one min. between all supply		
<u>ē</u>	withstandability	terminals connected together and enclosure		
Environmental resistance	Insulation	20 MΩ or higher, using 250 V DC megger between all		
Jer	resistance	supply terminals connected together and enclosure		
nn	Vibration resistance	10 to 150 Hz frequency, 0.75 mm 0.030 in double amplitude (10 to 58Hz), maximum acceleration 49 m/s ²		
vir		(58 to 150 Hz) in X, Y and Z directions for two hours each		
En		98 m/s ² (10 G approx.) acceleration in X, Y, and Z		
	Shock resistance	directions five times each		
Grounding method		Casing: Floating type		
	erial	Enclosure: Polycarbonate		
Communication cable		Category 5e (shielded twisted pair cable recommended)		
Weight		Net weight: 90 g approx., Gross weight: 150 g appox.		

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C +68 °F.

 2) Power is supplied from a connected controller / master controller.

 3) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

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Designation			RS-485 communication unit		
Item Model No.		Model No.	SC-HG1-485		
Regulatory compliance		compliance	EMC Directive, RoHS Directive		
Cor	mpatible	controllers	HG-TC□, HG-SC□		
Sup	ply volta	ge (Note 2)	24 V DC ±10 %, Ripple (P-P) 10 % or less (Within specified power supply voltage range)		
Cur	rent con	sumption	40 mA or less		
Con	nmunicat	ion method	Two-wire half duplex communication		
Syn	chroniza	tion method	Start-stop synchronization		
Con	nmunicat	ion protocol	MODBUS (RTU / ASCII) / MEWTOCOL-COM		
Communication speed		tion speed	1.2 kbps / 2.4 kbps / 4.8 kbps / 9.6 kbps / 19.2 kbps / 38.4 kbps / 57.6 kbps / 115.2 kbps		
Elec	ctrical cha	aracteristics	Complies with EIA RS-485		
	nber of	Host (RS-485)	1 to 99 units when MODBUS (RTU / ASCII) is used, 1 to 64 units when MEWTOCOL-COM is used		
unit	nectable s	Controllers	Maximum of 15 controllers (one master, 14 slaves) per SC-HG1-485 unit		
Sto	p bit leng	gth	1 bit / 2 bits		
Par	ity check	(Even / Odd / None		
Dat	a bit len	gth	8 bits (RTU) / 7 bits (ASCII)		
Poll	lution de	gree	2		
Оре	erating a	Ititude	2,000 m 6561.68 ft or less (Note 3)		
	Protection		IP40 (IEC)		
	Ambient temperature		-10 to +45 °C +14 to +113 °F (No dew condensation or icing allowed), Storage: -20 to +60 °C -4 to +140 °F		
nce	Ambient humidity		35 to 85 % RH, Storage: 35 to 85 % RH		
resista	Voltage withstandability		1,000 V AC for one min. between all supply terminals connected together and enclosure		
nental	Insulation resistance		$20~\text{M}\Omega$ or more, with 250 V DC megger between all supply terminals connected together and enclosure		
Environmental resistance	Vibration resistance		10 to 150 Hz frequency, 0.75 mm 0.030 in double amplitude (10 to 58Hz), maximum acceleration 49 m/s² (58 to 150 Hz) in X, Y and Z directions for two hours each		
	Shock resistance		98 m/s ² acceleration (10 G approx.) in X, Y and Z directions five times each		
Mat	terial		Enclosure: Polycarbonate		
Total extension distance		ion	Communication cable: 1,200 m 3,937.008 ft or less between SC-HG1-485 (terminal) and PLC		
Weight			Net weight: 75 g approx., Gross weight: 120 g approx		
Accessories			Termination resistor switching jumper pin: 1 pc.		
_					

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were ambient temperature +20 °C +68

- 2) Power is supplied from a connected controller / master controller.
- 3) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

	Designation	USB communication unit		
Iter	\	SC-HG1-USB		
Regulatory compliance		EMC Directive (Note 2), RoHS Directive		
Compatible controllers		HG-TC□		
Maximum number of connectable controllers		Maximum of 15 controllers (one master, 14 slaves per SC-HG1-USB unit		
Supply voltage (Note 3)		24 V DC ±10 %, Ripple (P-P) 10 % or less (Within specified power supply voltage range)		
Cur	rent consumption	50 mA or less		
Communication method		USB 2.0 Full Speed (Note 4)		
	mmunication tocol	Our dedicated protocol		
USI	B port	USB Mini-B (1 port) (Note 5)		
Poll	lution degree	2		
Оре	erating altitude	2,000 m 6561.680 ft or less (Note 6)		
	Protection	IP40 (IEC)		
	Ambient temperature	-10 to +45 °C +14 to +113 °F (No dew condensation or icing allowed), Storage: -20 to +60 °C -4 to +140 °F		
nce	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH		
resista	Voltage withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure		
nental	Insulation resistance	20 MΩ or more, with 250 V DC megger		
Environmental resistance	Vibration resistance	10 to 150 Hz frequency, 0.75 mm 0.030 in double amplitude (10 to 58 Hz), Maximum acceleration 49 m/s² (58 to 150 Hz) in X, Y and Z directions for two hours each		
	Shock resistance	98 m/s ² acceleration (10 G approx.) in X, Y and Z directions five times each		
Material		Enclosure: Polycarbonate		
Weight		Net weight: 35 g approx., Gross weight: 95 g approx		

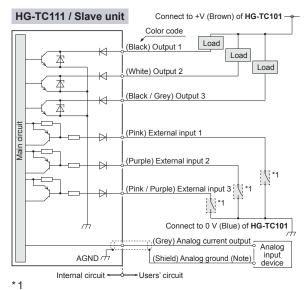
Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C +68 °F.

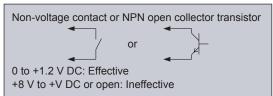
2) Applicable to products shipped in October 2019 and after.

3) Power is supplied from a connected controller / master unit.

- 4) Dependent on PC environment.
- 5) USB 2.0 (Mini-B) cable for the connection of a PC is not provided with the product. Please purchase a USB 2.0 (Mini-B) cable.
- 6) Do not use or store in an environment that has been pressurized to an air pressure higher than the atmospheric pressure at 0 m.

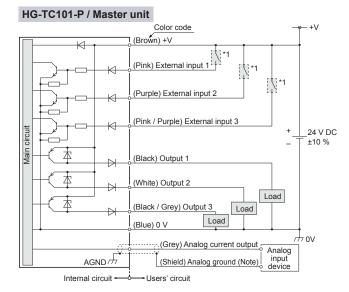
NPN output type **HG-TC101 / Master unit** Color code (Brown) +V (Black) Output 1 Load (White) Output 2 (Black / Grey) Output 3 24 V DC ±10 % (Pink) External input 1 Purple) External input 2 (Pink / Purple) External input 3 (Grey) Analog current output (Shield) Analog ground (Note) Internal circuit Users' circuit

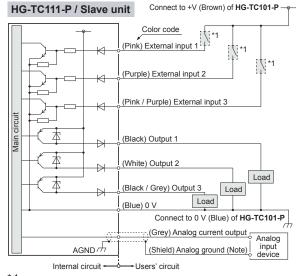


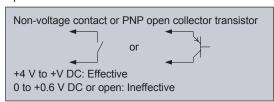


Note: Use shielded wire for the analog output.

PNP output type







Note: Use shielded wire for the analog output.

Refer to the instruction manual for details. The instruction manual can be downloaded from our website.

PRECAUTIONS FOR PROPER USE

 This catalog is a guide to select a suitable product. Be sure to read instruction manual attached to the product prior to its use.



- Never use this product as a sensing device for personnel protection.
- When using sensing devices for personnel protection, use products that meet the laws and standards for personnel protection that apply in each region or country, such as OSHA, ANSI and IEC.

User's Manual available for download

The **HG-T** series User's Manual is available for download from our website.

Cautions for laser beams



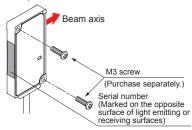
- This product is classified as a Class 1 Laser Product in IEC / JIS / GB standards and in FDA* regulations. Do not look at the laser beam through optical system such as a lens.
- The warning label and the proof label are attached to the product. Handle the product according to the instruction given on the label.
- [†] This product complies with 21 CFR 1040.10 and 1040.11 Laser Notice No. 50, dated June 24, 2007, issued by CDRH (Center for Devices and Radiological Health) under the FDA (Food and Drug Administration).

PRECAUTIONS FOR PROPER USE

Sensor head

Mounting

- The light emitting and receiving surfaces of the sensor head must be free of water, oil, fingerprints, and other substances that refract light as well as dust, grit, and other objects that intercept light.
- Do not allow ambient light such as sunlight to directly hit
 the light receiving section of the sensor head. In particular,
 if precision is required, use this product by mounting a
 douser (or similar material) on the sensor head.
- A serial number is marked on each opposite surface of the light emitting and receiving surfaces of the sensor head.
 Use a pair of emitter and receiver that have the same serial number.
- For the installation of sensor heads, use M3 screws and tighten to the torque of 0.5 N·m. M3 screws are not provided with the product.

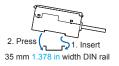


Controller

Mounting

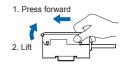
Mounting

- Insert the rear of the mounting part into the DIN rail.
- While pressing down on the rear of the mounting part, insert the front of the mounting part into the DIN rail.



Removal method

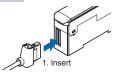
- 1. Grasp the product and push forward.
- 2. Lift the front to remove.



Attaching the sensor head connection cable

Mounting

 Insert the sensor head connection cable into the connector for the sensor head connection cable on the controller



Removal method

 Grasp the controller, and while pressing on the lock release lever on the connector of the sensor head connection cable, pull toward you to disconnect.



Note: If you attempt to disconnect the cable by pulling it without pressing the lock release lever, cable wire breakage and connector damage may occur.

Connection

- Always shut off the power before connecting a slave unit to or disconnecting a slave unit from the master unit. Risk of controller damage if you attempt connection with the power on.
- Insert the male connector firmly into the female connector.
 Risk of controller damage if not completely connected.
- When connecting slave units to a master unit, connect only NPN output types, or only PNP output types.
 Dissimilar output types cannot be connected together.

- To connect units, the units must be mounted on a DIN rail. Attach end plates MS-DIN-E (optional) so as to enclose the connected units at the ends.
- If the HG-TC□ controller is used together with the HG-SC□ controller for contact-type digital displacement sensor HG-S series, make sure to use the HG-SC□ controller manufactured in or after February, 2019. Furthermore, connect the slaves units of the same series to the side closer to the master unit and the slave units of the other series to the far side.

Common

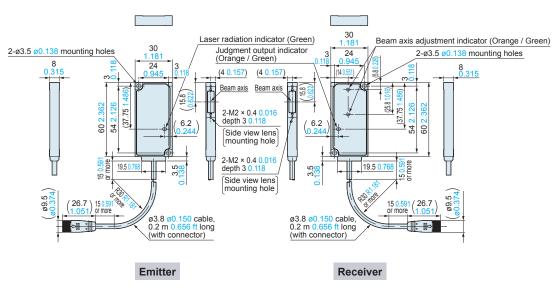
Wiring

- The product is designed to fulfill the specifications when combined with the HG-T□ sensor head and HG-TC□ controller. If the product is used in combination with other products, it not only fails to meet the specifications but also generates a malfunction in some cases.
- For the controller DC power supply, only use a power supply that is isolated by means of an isolation transformer or otherwise.
- Risk of short-circuiting and damage to the controller or power supply if a transformer such as an auto transformer is used. Risk of short-circuiting and damage to the controller or power supply if incorrectly mounted or connected.
- Make sure that the power supply is off while performing wiring or expansion work.
- After you have completed wiring work, check the wiring carefully before switching on the power.
- Do not run the wires together with high-voltage lines or power lines or put them in the same raceway. This can cause malfunction due to induction.
- · Verify that the supply voltage variation is within the rating.
- If power is supplied from a commercial switching regulator, ensure that the frame ground (F.G.) terminal of the power supply is connected to an actual ground.
- Make sure that stress by forcible bend or pulling is not applied directly to the sensor cable joint.

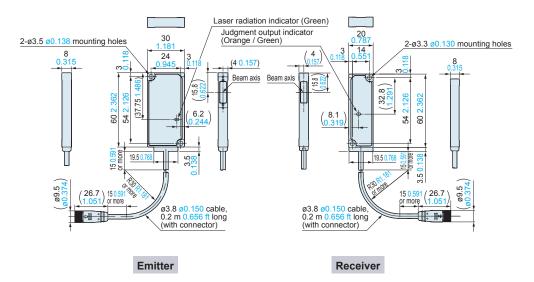
Others

- This device has been developed / produced for industrial use only.
- Do not use this product outside the range of the specifications. Risk of an accident and product damage. There is also a risk of a noticeable reduction of service life.
- Do not use during the initial transient time after the power supply is switched on.
- To ensure performance, use the product at least 30 minutes (warm-up time) after the power is turned ON.
- This product (controller and sensor head receiver) uses an EEPROM. The EEPROM has a service life of one million setting operations.
- This product is suitable for indoor use only.
- Avoid dust, dirt, and steam.
- Take care that the product does not come in direct contact with organic solvents such as thinner.
- Take care that the product does not come in direct contact with strong acid or alkaline.
- Take care that the product does not come in direct contact with oil or grease.
- Do not use in an environment containing inflammable or explosive gases.
- Performance may not be satisfactory in a strong electromagnetic field.
- The sensor head is watertight, but the connector is not dustproof, waterproofing, or corrosion-resistant due to its structural reasons, so measurements cannot be taken under the water or in the rain. Pay attention to the environment where the product is used.
- This product is a precision device. Do not drop or otherwise subject to shock. Risk of product damage.
- Never attempt to disassemble, repair, or modify the product.

HG-T1010 Sensor head (Standard type)



HG-T1110 Sensor head (Slim type)



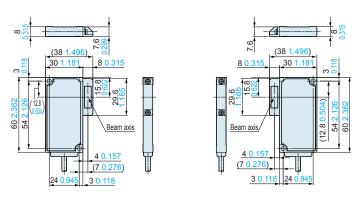
HG-TSV10 Side view attachment (Optional)

HG-T1010 mounting surface 29.6 1.165 25 20 0.787 2-ø2.3 ø0.091 mounting holes 0.7 0.028 1.5 0.059

Two M2 (length 4 mm 0.157 in) screws with washers are attached.

Assembly dimensions

The diagram shows the attachment mounted on the receiver of the standard type sensor head **HG-T1010**. Can be installed in either direction.

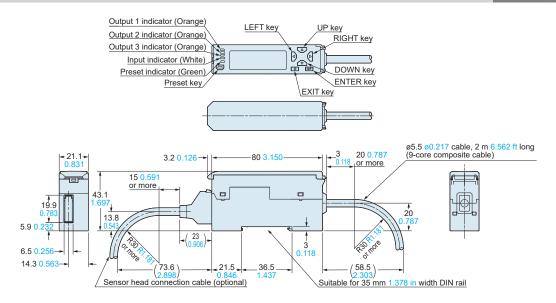


Notes: 1) The attachment cannot be installed to the slim type sensor head **HG-T1110**.

2) Be sure to confirm proper detection using actual equipment in advance when using the attachment.

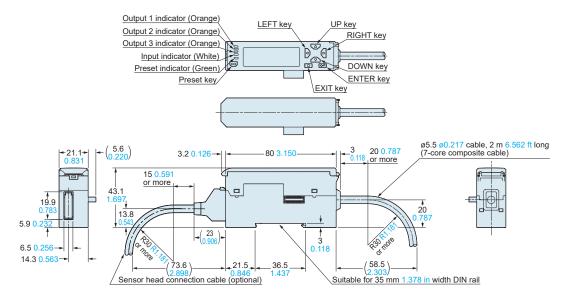
HG-TC101 HG-TC101-P

Controller (Master unit)

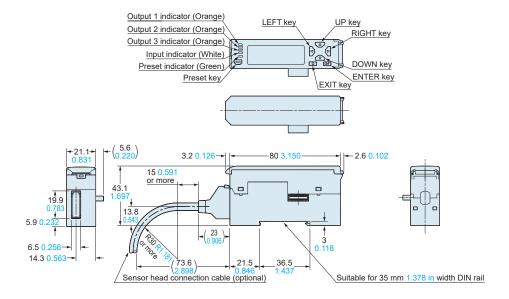


HG-TC111 HG-TC111-P

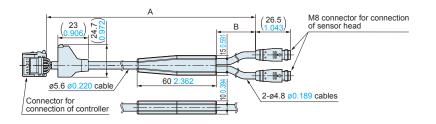
Controller (Slave unit)



HG-TC113 Controller (Slave unit)

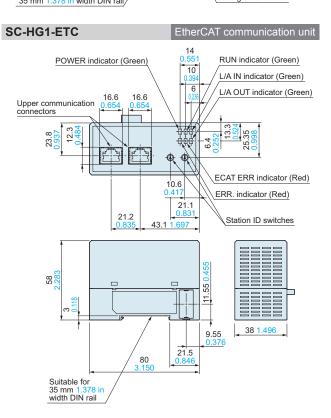


CN-HT-C□ Sensor head connection cable



Model	А	В	
CN-HT-C2	2,000 78.740	500 19.685	
CN-HT-C5	5,000 196.850	500 19.685	
CN-HT-C10	10,000 393.701	1,000 39.370	
CN-HT-C20	20,000	1,000 39,370	

SC-HG1-CEF CC-Link IE Field communication unit RD indicator (Green) D LINK indicator (Green) STS1 indicator (Green) Power indicator (Green) RUN indicator (Green) 16.6 Upper communication connector Port1 LINK indicator (Green) ERROR indicator (Red) 10.6 Port 1 ERR. indicator (Yellow) SD indicator (Green) Station No. / Network No. setting switch Port 2 LINK indicator (Green) 21.2 Port 2 ERR. indicator (Yellow) 55 58 38 1.496 21.5 Suitable for 35 mm 1.378 in width DIN rail/ Setting switch cover



SC-HG1-C CC-Link communication unit L_RUN (communication operation) indicator (Green) RD (data reception) indicator (Green) Power indicator (Green) ERR. indicator (Red) <u>∞</u> 0,0,0 L_ERR (communication error) indicator (Red) SD (data transmission) indicator (Green) 35.7 Upper communication Communication setting switches connector 55.9 2.201 Communication

Power indicator (Green) Communication indicator (Green) Upper communication error indicator (Red) Lower communication error indicator (Red) Upper communication error indicator (Red) Upper communication error indicator (Red) Upper communication setting switches Upper communication S8.5 2.303 Termination resistor switching jumper pin (Note) Switch cover

9.55

80 3.15

SC-HG1-485

38 1,496

RS-485 communication unit

38 1.496

Suitable for 35 mm 1.378 in width DIN rail

Suitable for 35 mm 1.378 in width DIN rail

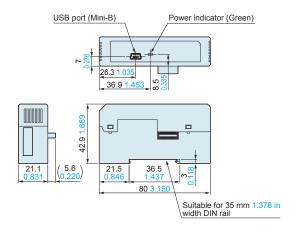
Note: The termination resistor switching jumper pin is not attached to the product at the factory. Attach the termination resistor switching jumper pin to the unit at the terminating end. Make sure that the termination resistor switching jumper pin have been removed from all units except the one at the terminating end.

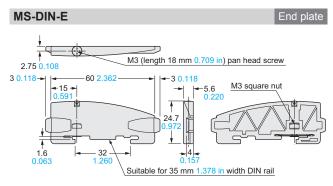
80 3.15

21.5 0.846 9.55

DIMENSIONS (Unit: mm in)

SC-HG1-USB USB communication unit





Material: Polycarbonate

Contact-type digital displacement sensor

Self-Monitoring Sensor

Contact-type digital displacement sensor HG-S SERIES

 ϵ

The optical absolute method eliminates "value skipping" and "unset zero point"!



Development target:

Slim & Robust

- The 10 mm 0.394 in type has a slim 11 × 18 × 84.5 mm 0.433 × 0.709 × 3.327 in body, for easy adjacent installation
- body, for easy adjacent installation

 Class-top robustness in the industry





* As of January 2021, in-company survey.

Development goal:

Highest Accuracy in Class

- Resolution of 0.1 µm 0.004 mil* and indication accuracy of 1.0 µm 0.039 mil or less*
- accuracy of 1.0 µm 0.039 mil or less*
 Absolute value scale reading for elimination of "value skipping" and "unset zero point"



Indication accuracy
No. 1* in class

Optical absolute method

In the case of high-precision sensor heads (HG-S1110 =). As of January 2021, in-company survey.

Controller

Development focus:

Intuitive Dual Display

■ 2-line digital display for unprecedented ease of use ■ Full-fledged functions designed for optimum ease of operation on production floor



* As of September 2015, in-company survey

High-speed response of 3 ms in combination with any sensor head

Alarm setting for notification of upward thrust



Please contact

Panasonic Corporation

Industrial Device Business Division

■ 7-1-1, Morofuku, Daito-shi, Osaka 574-0044, Japan industrial.panasonic.com/ac/e/



Mouser Electronics

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Panasonic:

HG-T1010 HG-TC111-P HG-TC111 HG-TC113 HG-TC101 HG-TC101-P HG-T1110 HG-TSV10