

# SG6902

## CCM PFC/Flyback PWM Combination Controller

### Features

- Green-Mode PFC and PWM Operation
- No Switching of PFC at Light Loads Saves Power
- Low Startup and Operating Current
- Innovative Switching-Charge Multiplier-Divider
- Multi-Vector Control for Improved PFC Output Transient Response
- Interleaved PFC/PWM Switching
- Programmable Two-Level PFC Output Voltage
- Average-Current-Mode Control for PFC
- Cycle-by-Cycle Current Limiting for PFC/PWM
- PFC Over-Voltage and Under-Voltage Protections
- PFC and PWM Feedback Open-Loop Protection
- Brownout Protection
- Over-Temperature Protection

### Applications

- Switching Power Supplies with Active PFC and Standby Power
- High-Power Adaptors

### Description

The highly integrated SG6902 is designed for power supplies with boost PFC and flyback PWM. It requires few external components to achieve green mode operation and versatile protections. It is available in a 20-pin SOIC package.


The proprietary interleave-switching feature synchronizes the PFC and PWM stages and reduces switching noise. At light loads, the switching frequency is continuously decreased to reduce power consumption. If output loading is further reduced, the PFC stage is turned off to reduce power consumption.

For PFC stage, the proprietary multi-vector control scheme provides a fast transient response in a low-bandwidth PFC loop, in which the overshoot and undershoot of the PFC voltage are clamped. If the feedback loop is broken, the SG6902 shuts off PFC to prevent extra-high voltage on output. Programmable two-level output voltage control reduces the PFC output voltage at low line input to increase the efficiency of the power supply.

For the flyback PWM, the synchronized slope compensation ensures the stability of the current loop under continuous-conduction-mode operation. Built-in line-voltage compensation maintains a constant output power limit. Hiccup operation during output overloading is also guaranteed.

In addition, SG6902 provides protection functions, such as brownout and RI pin open/short protections.

### Ordering Information

Part Number	Operating Temperature Range	 Eco Status	Package	Packing Method
SG6902SZ	-30°C to +85°C	RoHS	20-Lead, Small Outline Integrated Circuit (SOIC), JEDEC MS013, .300 inch, Wide Bod	Tape & Reel

 For Fairchild's definition of "green" Eco Status, please visit: [http://www.fairchildsemi.com/company/green/rohs\\_green.html](http://www.fairchildsemi.com/company/green/rohs_green.html).

## Application Circuit

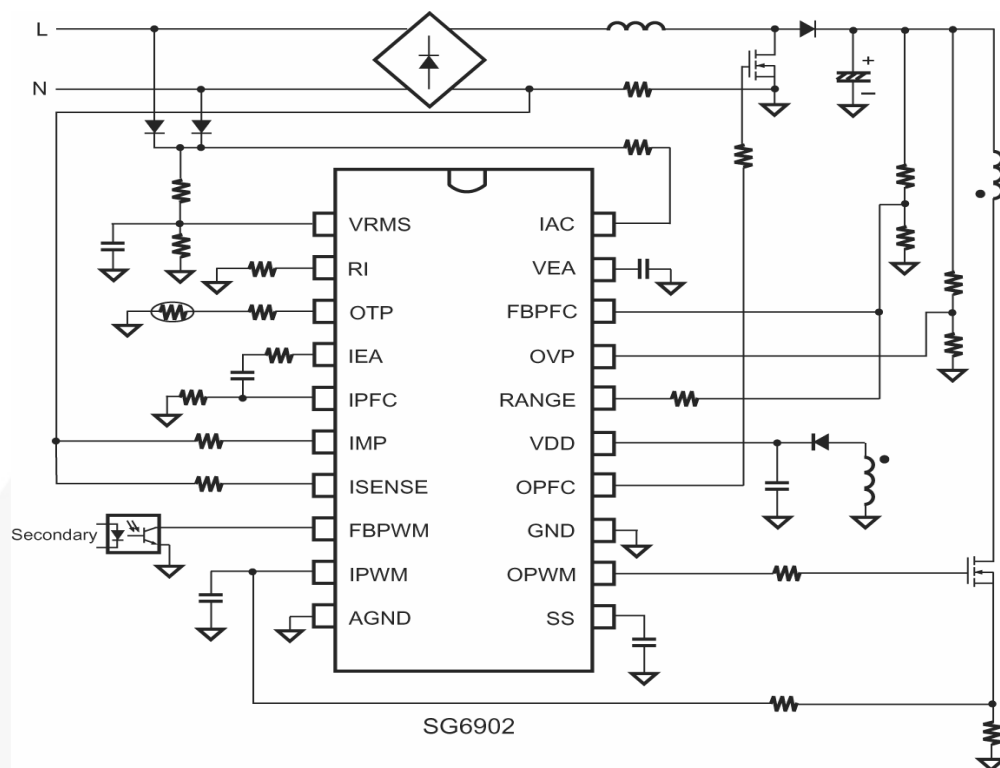


Figure 1. Typical Application

# Block Diagram

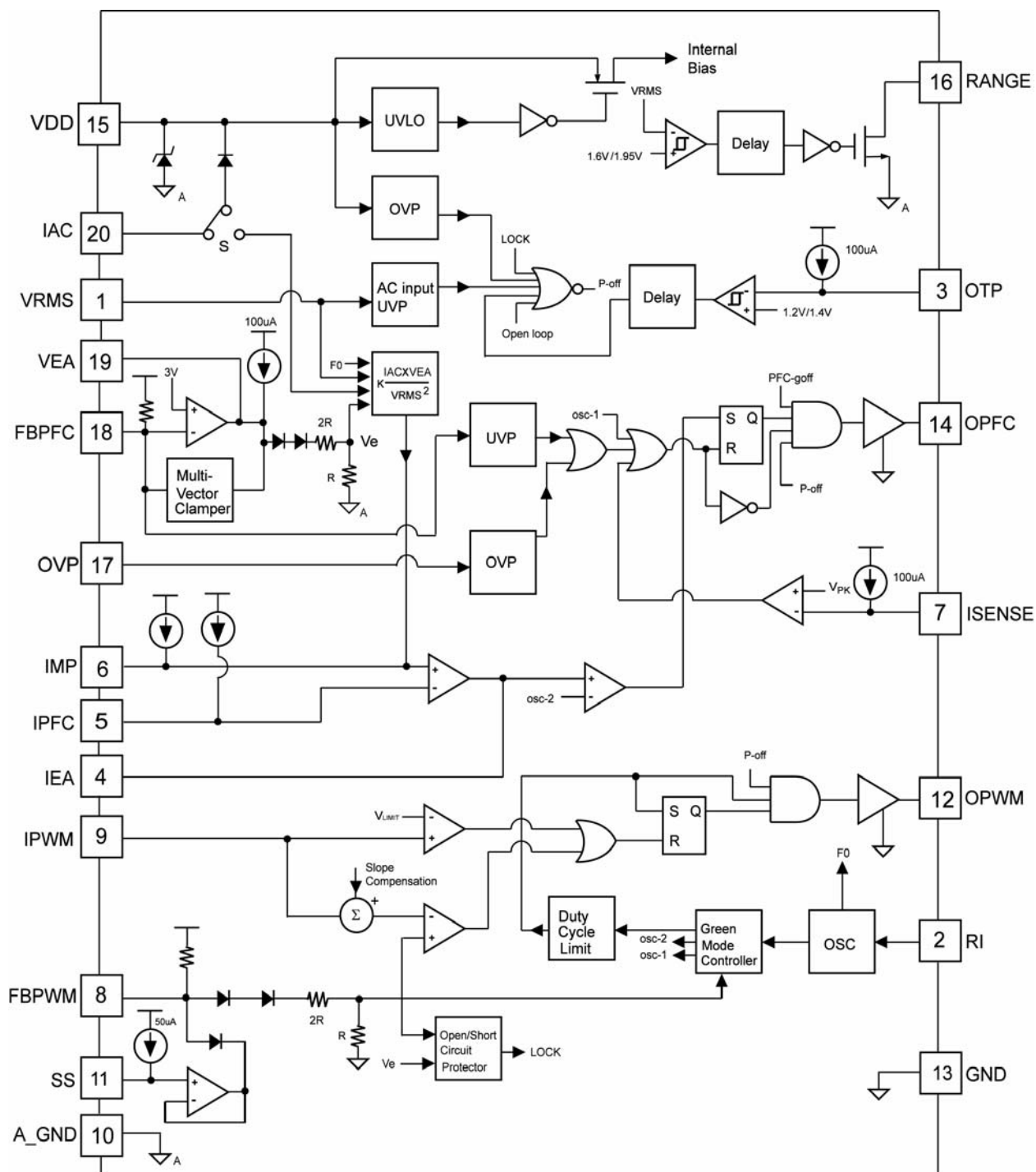


Figure 2. Block Diagram

## Marking Information



T- S=SOP  
 P- Z=Lead Free  
 Null=Regular Package  
 XXXXXXXX- Wafer Lot  
 Y: Year; WW: Week  
 V: Assembly Location

Figure 3. Top Mark

## Pin Configuration

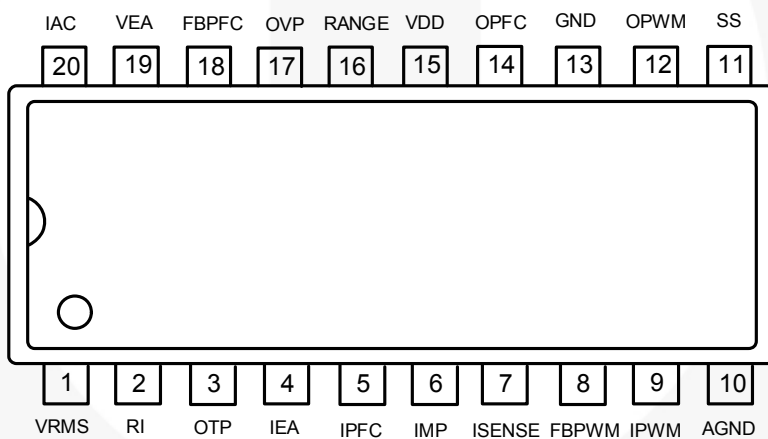


Figure 4. Pin Configuration

## Pin Definitions

Pin #	Name	Description
1	VRMS	<b>Line Voltage Detection.</b> The pin is used for PFC multiplier, RANGE control of PFC output voltage, and brownout protection. For brownout protection, the controller is disabled after a delay time when the $V_{RMS}$ voltage drops below a threshold.
2	RI	<b>Reference Setting.</b> One resistor connected between RI and ground determines the switching frequency. The switching frequency is equal to $[1560 / R_i]$ KHz, where $R_i$ is in $K\Omega$ . For example, if $R_i$ is equal to $24K\Omega$ , the switching frequency is 65KHz.
3	OTP	<b>Over-Temperature Protection.</b> A constant current is output from this pin. An external NTC thermistor must be connected from this pin to ground. The impedance of the NTC thermistor decreases whenever the temperature increases. Once the voltage of the OTP pin drops below the OTP threshold, the SG6902 is disabled.
4	IEA	<b>PFC Current Amplifier Output.</b> The signal from this pin is compared with an internal sawtooth to determine the pulse width for PFC gate drive.
5	IPFC	<b>Inverting Input of the PFC Current Amplifier.</b> Proper external compensation circuits result in excellent input power factor via average-current-mode control.
6	IMP	<b>Non-Inverting Input of the PFC Current Amplifier and the Output of Multiplier.</b> Proper external compensation circuits results in excellent input power factor via average-current-mode control.
7	ISENSE	<b>Current Limit.</b> A resistor from this pin to GND sets the current limit.
8	FBPWM	<b>Control Input for Voltage-Loop Feedback of PWM Stage.</b> It is internally pulled high through a $6.5k\Omega$ resistance. Usually an external opto-coupler from secondary feedback circuit is connected to this pin.
9	IPWM	<b>Current-Sense Input for the flyback PWM.</b> Via a current sense resistor, this pin provides the control input for peak-current-mode control and cycle-by-cycle current limiting.
10	AGND	<b>Signal Ground.</b>
11	SS	<b>Soft-Start.</b> During startup, the SS pin charges an external capacitor with a $50\mu A$ ( $R_i=24K\Omega$ ) constant current source. The voltage on FBPWM is clamped by SS during startup. In the event of a protection condition occurring and/or PWM being disabled, the SS pin quickly discharges.
12	OPWM	<b>Totem-Pole Output Drive for the Flyback PWM MOSFET.</b> This pin is internally clamped under 17V to protect the MOSFET.
13	GND	<b>Power Ground.</b>
14	OPFC	<b>Totem-Pole Output Drive for the PFC MOSFET.</b> This pin is internally clamped under 17V to protect the MOSFET.
15	VDD	<b>Power Supply Pin.</b>
16	RANGE	<b>RANGE Pin.</b> High impedance whenever the $V_{RMS}$ voltage is lower than a threshold.
17	OVP	<b>PFC Stage Over-Voltage Input.</b> The comparator disables the PFC output driver if the voltage at this input exceeds a threshold. This pin can be connected to FBPFC or it can be connected to the PFC boost output through a divider network.
18	FBPFC	<b>Feedback Input for PFC Voltage Loop.</b> The inverting input of PFC error amplifier. This pin is connected to the PFC output through a divider network.
19	VEA	<b>Error Amplifier Output for PFC Voltage Feedback Loop.</b> A compensation network (usually a capacitor) is connected between this pin and ground. A large capacitor value results in a narrow bandwidth and improves the power factor.
20	IAC	<b>Input used to Provide Current Reference for the Multiplier.</b>

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

Symbol	Parameter	Min.	Max.	Unit
V <sub>VDD</sub>	DC Supply Voltage		25	V
I <sub>AC</sub>	Input AC Current		2	mA
V <sub>HIGH</sub>	OPWM, OPFC, IAC	-0.3	25.0	V
V <sub>LOW</sub>	Others	-0.3	7.0	V
P <sub>D</sub>	Power Dissipation at T <sub>A</sub> < 50°C (SOP)		1.15	W
T <sub>J</sub>	Operating Junction Temperature	-40	+125	°C
T <sub>STG</sub>	Storage Temperature Range	-55	+150	°C
θ <sub>JC</sub>	Thermal Resistance (Junction-to-case)		23.64	°C/W
T <sub>L</sub>	Lead Temperature (Soldering)		+260	°C
ESD	Electrostatic Discharge Capability	Machine Model, JESD22-A115	4.5	KV
		HBM Model, JESD22-A114	250	V

### Notes:

1. All voltage values, except differential voltage, are given with respect to GND pin.
2. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device.

## Recommended Operating Conditions

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.

Symbol	Parameter	Min.	Max.	Unit
T <sub>A</sub>	Operating Ambient Temperature	-30	+85	°C

## Electrical Characteristics

$V_{DD}=15V$  and  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>V<sub>DD</sub> SECTION</b>						
$V_{DD-OP}$	Continuously Operating Voltage				20	V
$I_{DD-ST}$	Startup Current	$0V < V_{DD} < V_{DD-ON}$		10	25	$\mu A$
$I_{DD-OP}$	Operating Current	$V_{DD}=15V$ ; OPFC, OPWM Open; $R_I=24K\Omega$		6	10	mA
$V_{DD-ON}$	Start Threshold Voltage		15	16	17	V
$V_{DD-OFF}$	Minimum Operating Voltage		9	10	11	V
$V_{DD-OVP}$	$V_{DD}$ OVP Threshold		23.5	24.5	25.5	V
$t_{D-VDDOVP}$	Debounce Time of $V_{DD}$ OVP	$R_I=24K\Omega$	8		25	$\mu s$
$V_{DD-TH-G}$	$V_{DD}$ Low-Threshold Voltage to Exit Green-off Mode		$V_{DD-OFF}+0.9$	$V_{DD-OFF}+1.5$	$V_{DD-OFF}+2.1$	V
<b>OSCILLATOR SECTION</b>						
$f_{OSC}$	PWM Frequency	$R_I=24K\Omega$	62	65	68	KHz
$f_{OSC-MINFREQ}$	PWM Frequency	$R_I=24K\Omega$	18.0	20.0	22.5	KHz
$R_I$	RI Pin Resistance Range		15.6		47.0	$K\Omega$
$V_{RI}$	RI Voltage		1.176	1.200	1.224	V
$R_{I-OPEN}$	RI Pin Open Protection	If $R_I > R_{I-OPEN}$ , SG6902 Turns off		200		$K\Omega$
$R_{I-SHORT}$	RI Pin Short Protection	If $R_I < R_{I-SHORT}$ , SG6902 Turns off		2		$K\Omega$

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## Electrical Characteristics

$V_{DD}=15V$  and  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>V<sub>RMS</sub> SECTION (for UVP and RANGE)</b>						
$V_{RMS-UVP-1}$	RMS AC Voltage Under-Voltage Protection Threshold (with $t_{UVP}$ Delay)		0.75	0.80	0.85	V
$V_{RMS-UVP-2}$	Recovery Level on $V_{RMS}$		$V_{RMS-UVP-1} + 0.16V$	$V_{RMS-UVP-1} + 0.18V$	$V_{RMS-UVP-1} + 0.2V$	V
$t_{D-PWM}$	When UVP Occurs, Interval from PFC Off to PWM Off	$R_I=24K\Omega$	$t_{UVP-Min}+9$		$t_{UVP-Min}+14$	ms
$t_{UVP}$	Under-Voltage Protection Delay Time <sup>(3)</sup>	$R_I=24K\Omega$	150	195	240	ms
$V_{RMS-H}$	High $V_{RMS}$ Threshold for RANGE Comparator		1.90	1.95	2.00	V
$V_{RMS-L}$	Low $V_{RMS}$ Threshold for RANGE Comparator		1.55	1.60	1.65	V
$t_{RANGE}$	Range-Enable Delay Time	$R_I=24K\Omega$	140	170	200	ms
$V_{OL}$	Output Low Voltage of RANGE Pin	$I_O=1mA$			0.5	V
$I_{OH}$	Output High Leakage Current of RANGE Pin	RANGE=5V			50	nA
<b>PFC STAGE</b>						
<b>Voltage Error Amplifier</b>						
$V_{REF}$	Reference Voltage		2.95	3.00	3.05	V
$A_v$	Open-Loop Gain			60		dB
$Z_o$	Output Impedance			110		$K\Omega$
$OVP_{PFC}$	PFC Over-Voltage Protection (OVP Pin)		3.20	3.25	3.30	V
$\Delta OVP_{PFC}$	PFC Feedback Voltage Protection Hysteresis		60	90	120	mV
$t_{OVP-PFC}$	Debounce Time of PFC OVP	$R_I=24K\Omega$	40	70	120	$\mu s$
$V_{FBPFC-H}$	Clamp-High Feedback Voltage		3.10	3.15	3.20	V
$G_{FBPFC-H}$	Clamp-High Gain			0.5		$\mu A/mV$
$V_{FBPFC-L}$	Clamp-Low Feedback Voltage		2.75	2.85	2.90	V
$G_{FBPFC-L}$	Clamp-Low Gain			6.5		$mA/mV$
$I_{FBPFC-L}$	Maximum Source Current		1.5	2.0		mA
$I_{FBPFC-H}$	Maximum Sink Current		70	110		$\mu A$
$UVP_{FBPFC}$	PFC Feedback Under-Voltage Protection		0.35	0.40	0.45	V
$V_{FBHIGH}$	FB Open Voltage		6	7	8	V
$t_{UVP-FBPFC}$	Debounce Time of PFC UVP	$R_I=24K\Omega$	40	70	120	$\mu s$

### Note:

3. No delay time at startup.

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## Electrical Characteristics

$V_{DD}=15V$  and  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>CURRENT ERROR AMPLIFIER</b>						
$V_{OFFSET}$	Input Offset Voltage			8		mV
$A_I$	Open-Loop Gain			60		dB
BW	Unit Gain Bandwidth			1.5		MHz
CMRR	Common Mode Rejection Ratio	$V_{CM}=0$ to $+1.5V$		70		dB
$V_{OUT-HIGH}$	Output High Voltage		3.2			V
$V_{OUT-LOW}$	Output Low Voltage				0.2	V
$I_{MR1}, I_{MR2}$	Reference Current Source	$R_I=24K\Omega$ ( $I_{MR}=20+I_{RI}\cdot 0.8$ )	50		70	$\mu A$
$I_L$	Maximum Source Current		3			mA
$I_H$	Maximum Sink Current			0.25		mA
<b>PEAK CURRENT LIMIT</b>						
$I_P$	Constant Current Output	$R_I=24K\Omega$	90	100	110	$\mu A$
$V_{PK}$	Peak Current Limit Threshold Voltage Cycle-by-Cycle Limit ( $V_{SENSE} < V_{PK}$ )	$V_{RMS}=1.05V$	0.15	0.20	0.25	V
		$V_{RMS}=3V$	0.35	0.40	0.45	V
$t_{PD-PFC}$	Propagation Delay				200	ns
$t_{LEB-PFC}$	Leading-Edge Blanking Time		270	350	450	ns
<b>MULTIPLIER</b>						
$I_{AC}$	Input AC Current	Multiplier Linear Range	0		360	$\mu A$
$I_{MO-max}$	Maximum Multiplier Current Output	$R_I=24K\Omega$		250		$\mu A$
$I_{MO-1}$	Multiplier Current Output (Low-Line, High-power)	$V_{RMS}=1.05V$ ; $I_{AC}=90\mu A$ ; $V_{EA}=7.5V$ ; $R_I=24K\Omega$	200	250	280	$\mu A$
$I_{MO-2}$	Multiplier Current Output (High-Line, High-power)	$V_{RMS}=3V$ ; $I_{AC}=264\mu A$ ; $V_{EA}=7.5V$ ; $R_I=24K\Omega$	65	85		$\mu A$
$V_{IMP}$	Voltage of IMP Open		3.4	3.9	4.4	V
<b>PFC OUTPUT DRIVER</b>						
$V_{Z-PFC}$	Output Voltage Maximum (Clamp)	$V_{DD}=20V$		16	18	V
$V_{OL-PFC}$	Output Voltage Low	$V_{DD}=15V$ ; $I_O=100mA$			1.5	V
$t_{PFC}$	Interval OPFC Lags Behind OPWM at Startup		9.0	11.5	14.0	ms
$V_{OH-PFC}$	Output Voltage High	$V_{DD}=13V$ ; $I_O=100mA$	8			V
$t_{R-PFC}$	Rising Time	$V_{DD}=15V$ ; $C_L=5nF$ ; OPFC=2V to 9V	40	70	120	ns
$t_{F-PFC}$	Falling Time	$V_{DD}=15V$ ; $C_L=5nF$ ; OPFC=9V to 2V	40	60	110	ns
$DCY_{MAX}$	Maximum Duty Cycle		93		98	%

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## Electrical Characteristics

$V_{DD}=15V$  and  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>PWM STAGE</b>						
<b>FBPWM</b>						
$A_{V-PWM}$	FB to Current Comparator Attenuation		2.5	3.1	3.5	V/V
$Z_{FB}$	Input Impedance <sup>(4)</sup>		4	5	7	K $\Omega$
$I_{FB}$	Maximum Source Current		0.8	1.2	1.5	mA
$FB_{OPEN-LOOP}$	PWM Open-Loop Protection Voltage		4.2	4.5	4.8	V
$t_{OPEN-PWM}$	PWM Open-Loop Protection Delay Time		45	56	70	ms
$V_{PFC-OFF1}$	PFC Off Voltage at FBPWM	RANGE=Ground		$V_G+0.2V$		V
$V_{PFC-OFF2}$	PFC Off Voltage at FBPWM	RANGE=Open		$V_G+0.2V$		V
$t_{PFC-OFF}$	PFC Off Delay Time	$R_I=24k\Omega$	500	650	800	ms
$V_{PFC-ON 1.6}$	PFC On Voltage at FBPWM	RANGE=Ground $V_{RMS}=1.6V$		$V_G+0.35V$		V
$V_{PFC-ON 2.85}$	PFC On Voltage at FBPWM	RANGE=Ground $V_{RMS}=2.85V$		$V_G+0.35V$		V
$V_{PFC-ON 0.8}$	PFC On Voltage at FBPWM	RANGE=Open $V_{RMS}=0.8V$		$V_G+0.85V$		V
$V_{PFC-ON 1.95}$	PFC On Voltage at FBPWM	RANGE=Open $V_{RMS}=1.95V$		$V_G+0.5V$		V
$V_N$	Frequency Reduction Threshold on FBPWM	RANGE=Ground	1.9	2.1	2.3	V
$S_G$	Green Mode Modulation Slope <sup>(4)</sup>		60	75	90	Hz/V
$V_G$	Voltage on FBPWM at $f_s=20KHz$		1.35	1.60	1.75	V
<b>PWM CURRENT SENSE</b>						
$t_{PD-PWM}$	Propagation Delay to Output	$V_{DD}=15V$ , $OPWM \leq 9V$	60		120	ns
$V_{LIMIT-1}$	Peak Current Limit Threshold Voltage1	RANGE=Open	0.65	0.70	0.75	V
$V_{LIMIT-2}$	Peak Current Limit Threshold Voltage2	RANGE=Ground	0.60	0.65	0.70	V
$t_{BNK-PWM}$	Leading-Edge Blanking Time		270	350	450	ns
$\Delta V_{SLOPE}$	Slope Compensation	$\Delta V_S = \Delta V_{SLOPE} \times (t_{ON}/t)$ $\Delta V_S$ : Compensation Voltage Added to Current Sense	0.45	0.50	0.55	V

**Note:**

4. Guaranteed by design.

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## Electrical Characteristics

$V_{DD}=15V$  and  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>PWM OUTOUT DRIVER</b>						
$V_{Z-PWM}$	Output Voltage Maximum (Clamp)	$V_{DD}=20V$		16	18	V
$V_{OL-PWM}$	Output Voltage Low	$V_{DD}=15V$ ; $I_O=100mA$			1.5	V
$V_{OH-PWM}$	Output Voltage High	$V_{DD}=13V$ ; $I_O=100mA$	8			V
$t_{R-PWM}$	Rising Time	$V_{DD}=15V$ ; $C_L=5nF$ ; $OPWM=2V$ to $9V$	30	60	120	ns
$t_{F-PWM}$	Falling Time	$V_{DD}=15V$ ; $C_L=5nF$ ; $OPWM=9V$ to $2V$	30	50	110	ns
$DCY_{MAXPWM}$	Maximum Duty Cycle		73	78	83	%
<b>OTP SECTION</b>						
$I_{OTP}$	OTP Pin Output Current	$R_I=24K\Omega$	90	100	110	$\mu A$
$V_{OTP-ON}$	Recovery Level on OTP		1.35	1.40	1.45	V
$V_{OTP-OFF}$	OTP Threshold Voltage		1.15	1.20	1.25	V
$t_{OTP}$	OTP Debounce Time		8		25	$\mu s$
<b>SOFT-START SECTION</b>						
$I_{SS}$	Constant Current Output for Soft-Start	$R_I=24K\Omega$	44	50	56	$\mu A$
$R_D$	Discharge $R_{DS(on)}$			470		$\Omega$

## Typical Performance Characteristics

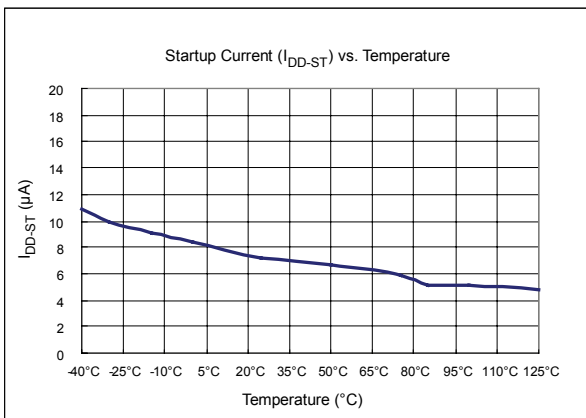


Figure 5. Startup Current

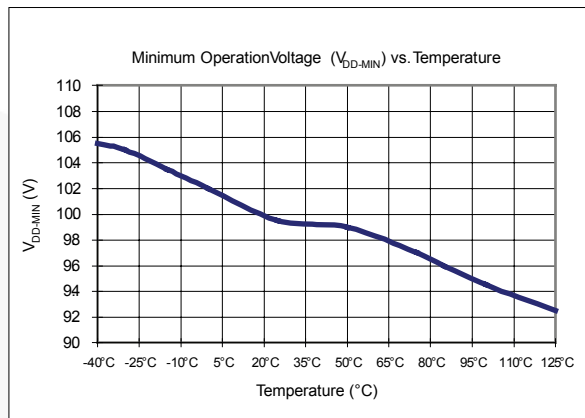


Figure 6. V<sub>DD-MIN</sub> Threshold Voltage

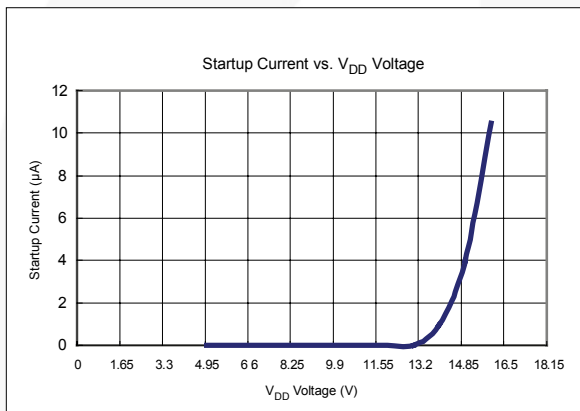


Figure 7. Startup Current vs. V<sub>DD</sub> Voltage

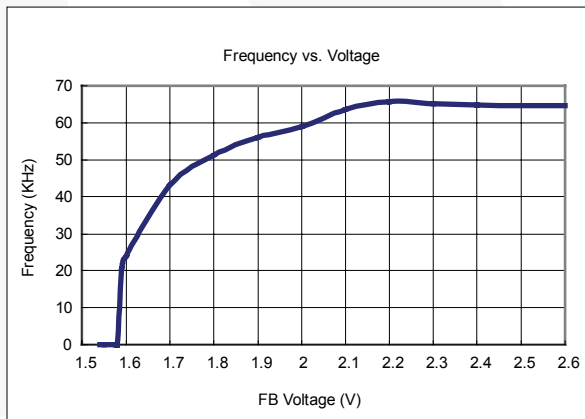


Figure 8. PWM Frequency vs. FB Voltage

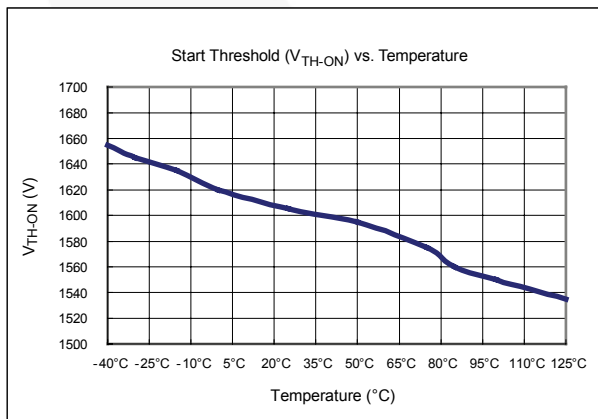


Figure 9. V<sub>TH-ON</sub> Threshold Voltage

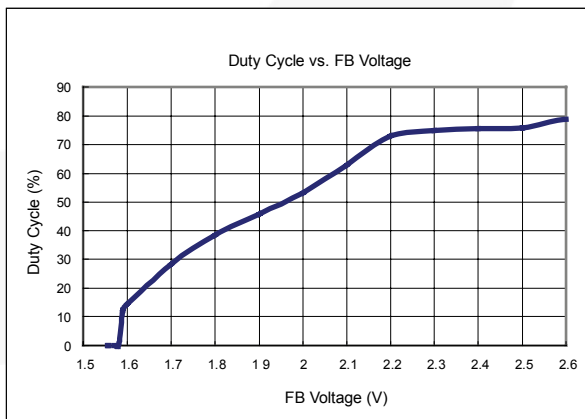


Figure 10. Duty Cycle vs. FB Voltage

# Typical Performance Characteristics (Continued)

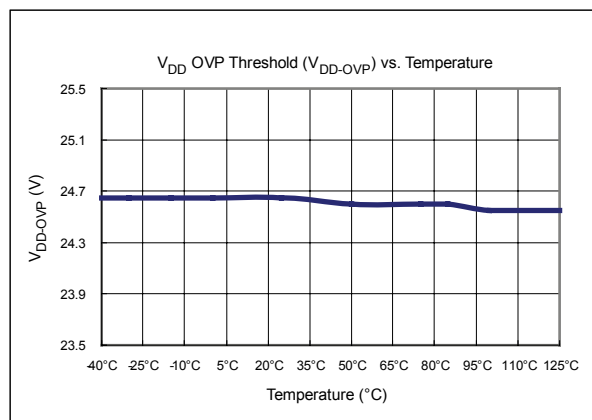


Figure 11. V<sub>DD</sub> OVP

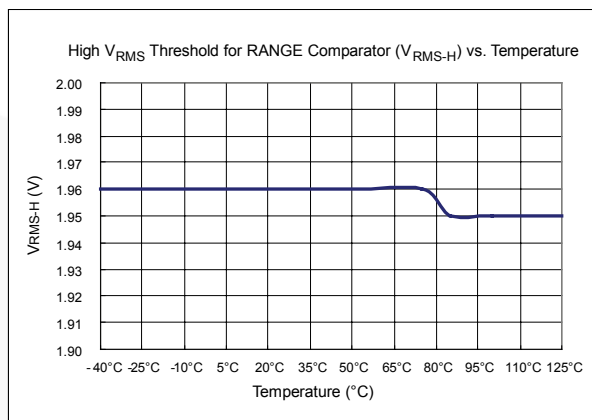


Figure 12. High V<sub>RMS</sub> Threshold for RANGE

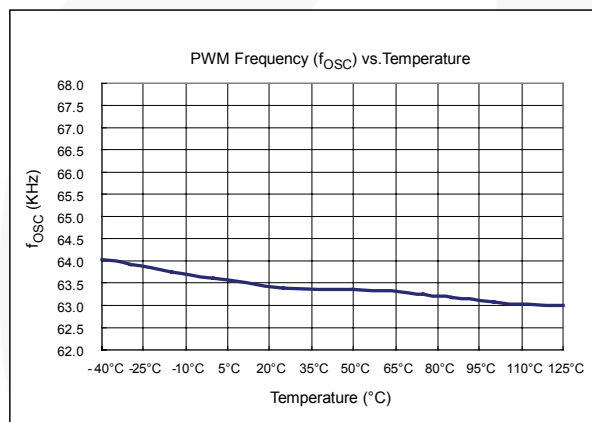


Figure 13. PWM Frequency

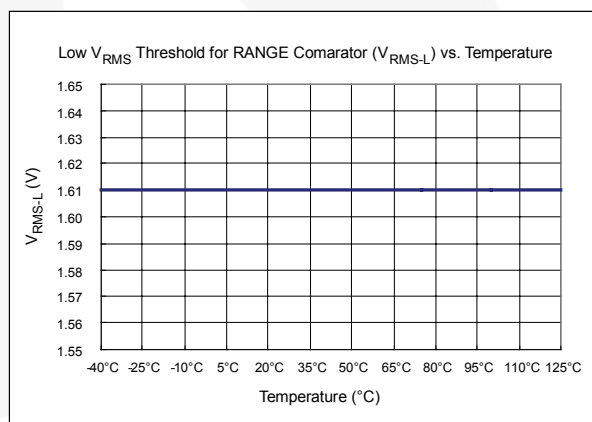


Figure 14. Low V<sub>RMS</sub> Threshold for RANGE

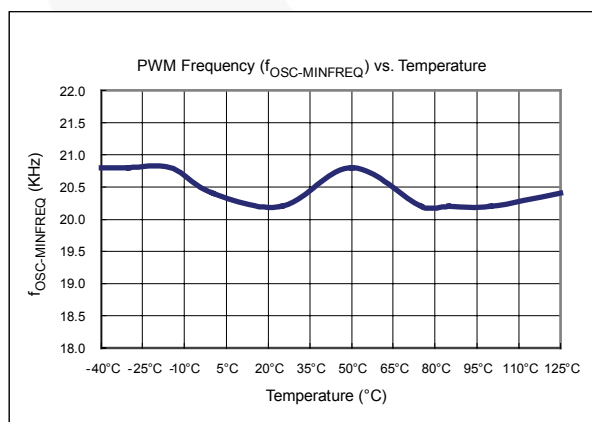


Figure 15. PWM Frequency (f<sub>OSC-MINFREQ</sub>)

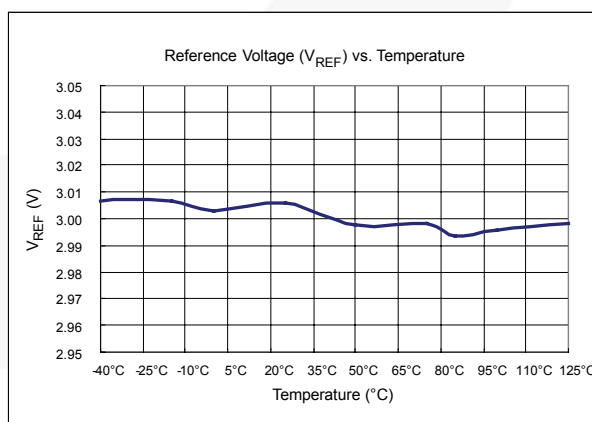


Figure 16. Reference Voltage

# Typical Performance Characteristics (Continued)

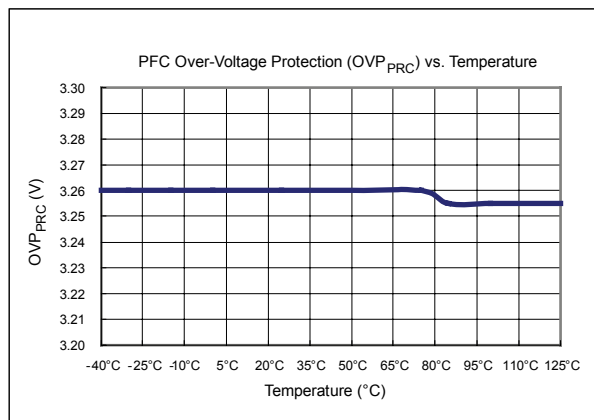


Figure 17. PFC Over-Voltage Protection

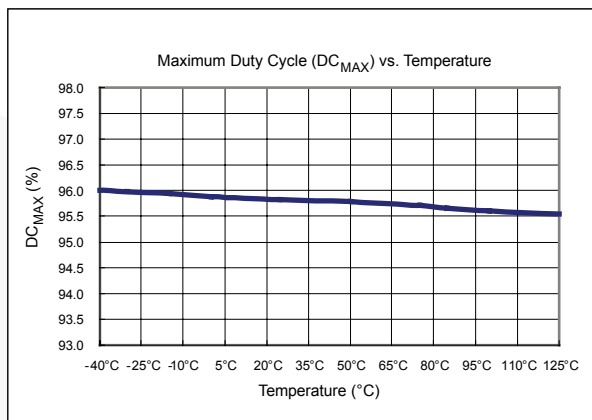


Figure 18. Maximum Duty Cycle (OPFC)

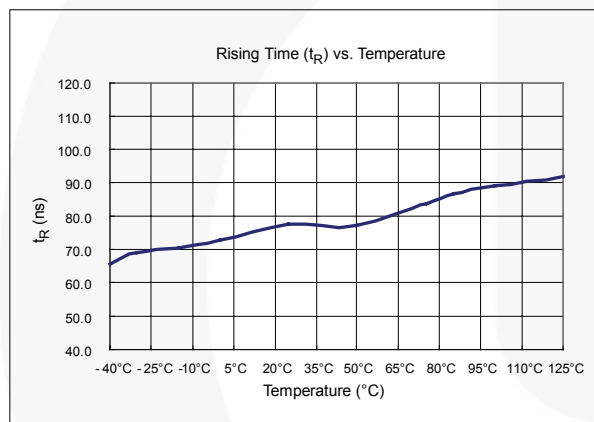


Figure 19. Rising Time (OPFC)

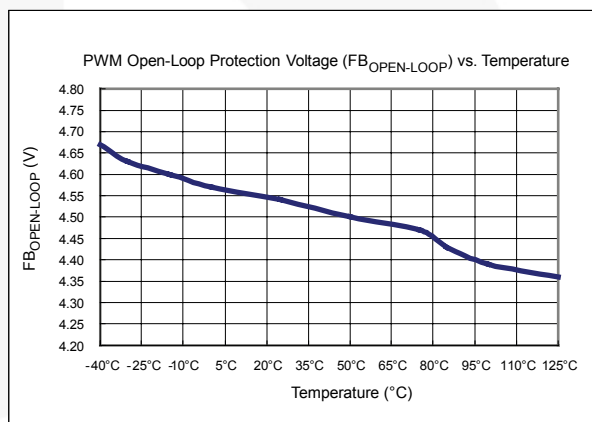


Figure 20. PWM Open-Loop Protection

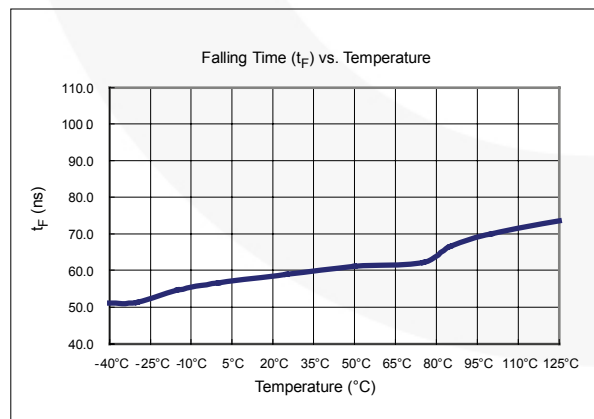


Figure 21. Falling Time (OPFC)

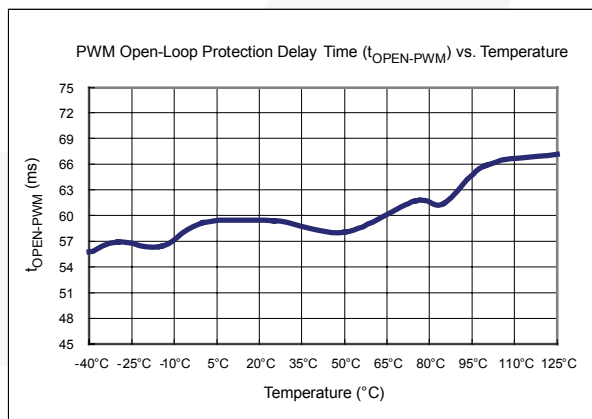


Figure 22. PWM Open-Loop Protection Delay Time

# Typical Performance Characteristics (Continued)

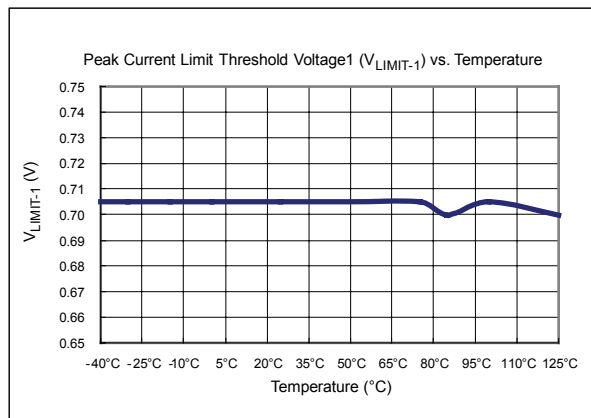


Figure 23. Peak Current Limit Threshold Voltage

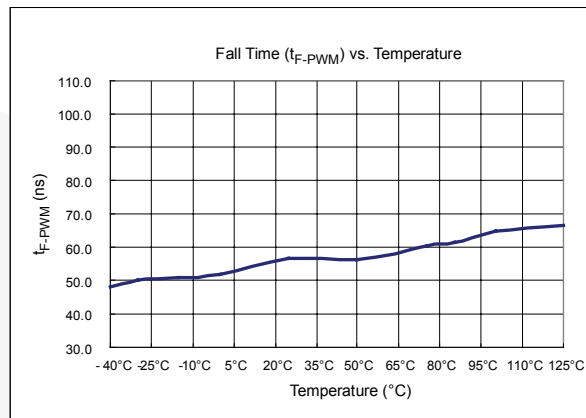


Figure 24. Falling Time (OPWM)

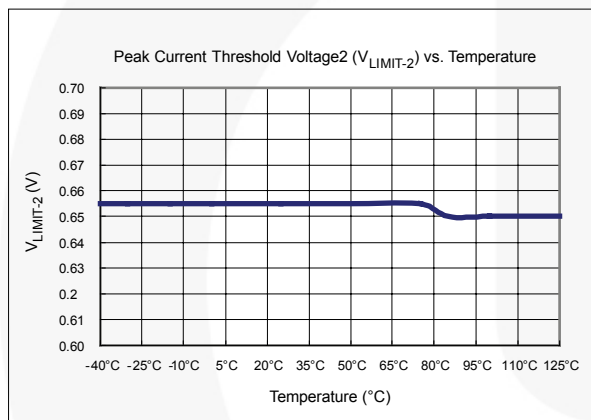


Figure 25. Peak Current Limit-2 Threshold Voltage

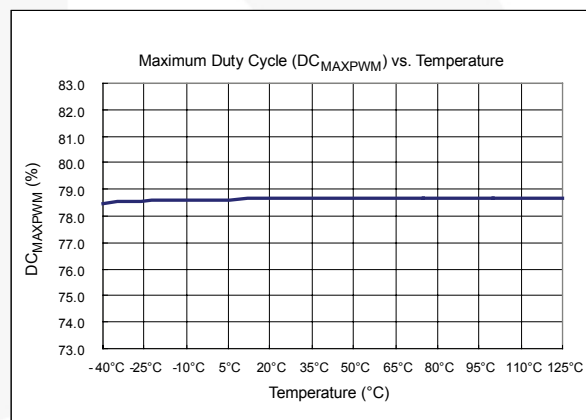


Figure 26. Maximum Duty Cycle (OPWM)

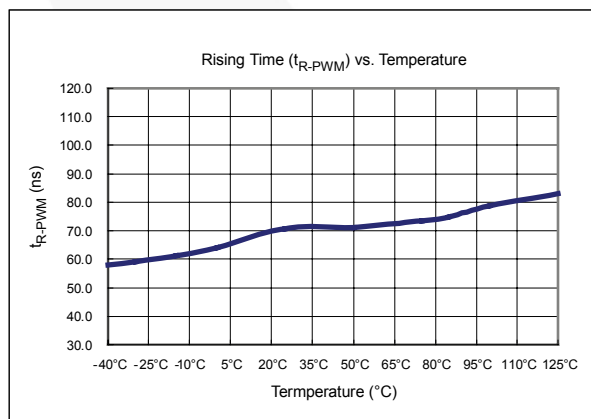


Figure 27. Rising Time (OPWM)

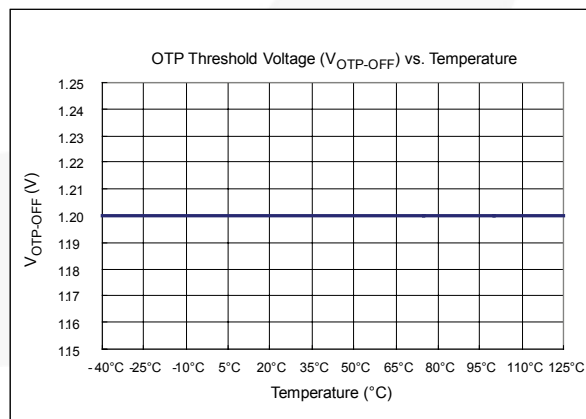


Figure 28. OTP Threshold Voltage

## Functional Description

The highly integrated SG6902 is designed for power supplies with boost PFC and flyback PWM. It requires very few external components to achieve green-mode operation and versatile protections / compensation.

The proprietary interleave-switching feature synchronizes the PFC and PWM stages and reduces switching noise. At light loads, the switching frequency is continuously decreased to reduce power consumption. If output loading is reduced, the PFC stage is turned off to reduce power consumption.

The PFC function is implemented by average-current-mode control. The proprietary switching charge multiplier-divider provides a high-degree noise immunity for the PFC circuit. The proprietary multi-vector output voltage control scheme provides a fast transient response in a low-bandwidth PFC loop, in which the overshoot and undershoot of the PFC voltage are clamped. If the feedback loop is broken, the SG6902 shuts off PFC to prevent extra-high voltage on output. Programmable two-level output voltage control reduces the PFC output voltage at low line input to increase the efficiency of the power supply.

For the flyback PWM, the synchronized slope compensation ensures the stability of the current loop under continuous-mode operation. Built-in line-voltage compensation maintains constant output power limit. Hiccup operation during output overloading is also guaranteed. To prevent the power supply from drawing large current during startup, the startup for PFC stage is delayed 11.5ms after the operation of PWM stage.

In addition, SG6902 provides complete protection functions, such as brownout, over-voltage, and RI pin open/short protections.

## Startup

Figure 29 shows the startup circuit. A resistor  $R_{AC}$  is utilized to charge  $V_{DD}$  capacitor through S1. The turn-on and turn-off thresholds are fixed internally at 16V and 10V. During startup, the hold-up capacitor must be charged to 16V through the startup resistor to enable SG6902. The hold-up capacitor continues to supply  $V_{DD}$  before the energy can be delivered from auxiliary winding of the main transformer.  $V_{DD}$  must not drop below 10V during this startup process. This UVLO hysteresis window ensures that hold-up capacitor is adequate to supply  $V_{DD}$  during startup. Since SG6902 consumes less than 25 $\mu$ A startup current, the value of  $R_{AC}$  can be large to reduce power consumption. One 10 $\mu$ F capacitor should hold enough energy for successful startup. After startup, S1 switches so that the current  $I_{AC}$  is the input for PFC multiplier. This helps reduce circuit complexity and power consumption.

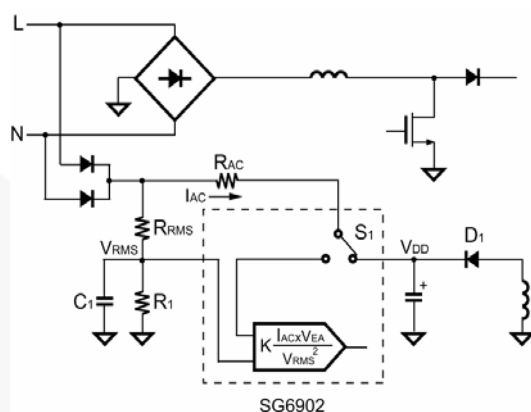


Figure 29. Startup Circuit

## Switching Frequency and Current Sources

The switching frequency can be programmed by the resistor  $R_I$  connected between  $R_I$  pin and GND. The relationship is:

$$f_{OSC} = \frac{1560}{R_I \text{ (k}\Omega\text{)}} \text{ (kHz)} \quad (1)$$

For example, a 24K $\Omega$  resistor  $R_I$  results in a 65KHz switching frequency. Accordingly, a constant current,  $I_T$ , flows through  $R_I$ :

$$I_T = \frac{1.2V}{R_I \text{ (k}\Omega\text{)}} \text{ (mA)} \quad (2)$$

$I_T$  is used to generate internal current reference.

## Line Voltage Detection (VRMS)

Figure 30 shows a resistive divider with low-pass filtering for line-voltage detection on the  $VR_{MS}$  pin. The  $VR_{MS}$  voltage is used for the PFC multiplier, brownout protection, and range control.

For brownout protection, the SG6902 is disabled with a 195ms delay time if the voltage  $V_{RMS}$  drops below 0.8V.

For PFC multiplier and range control, refer to the PFC Operation section below for details.

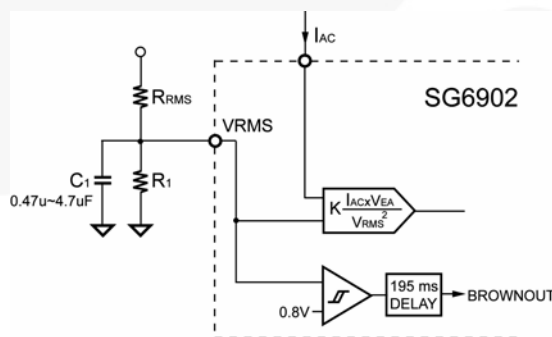


Figure 30. Line-Voltage Detection Circuit



## Interleave Switching and Green Mode

The SG6902 uses interleaved switching to synchronize the PFC and flyback stages, which reduces switching noise and spreads the EMI emissions. Figure 31 shows off-time,  $t_{OFF}$ , inserted between the turn-off of the PFC gate drive and the turn-on of the PWM.

The off-time  $t_{OFF}$  is increased in response to the decreasing of the voltage level of FBPWM. Therefore, the PWM switching frequency is continuously decreased to reduce switching losses. To further reduce power losses under extra light-load conditions, the PFC stage is turned off with a 650ms delay time.

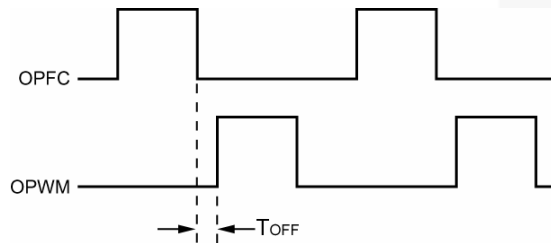


Figure 31. Interleaved Switching Pattern

## PFC Operation

The purpose of a boost active power factor corrector (PFC) is to shape the input current of a power supply. The input current waveform and phase follow that of the input voltage. Average-current-mode control is utilized for continuous-current-mode operation for the PFC booster. With the innovative multi-vector control for voltage loop and switching charge multiplier-divider for current reference, excellent input power factor is achieved with good noise immunity and transient response. Figure 32 shows the total control loop for the average-current-mode control circuit.

The current source output from the switching charge multiplier-divider can be expressed as:

$$I_{MO} = K \times \frac{I_{AC} \times V_{EA}}{V_{RMS}^2} (\mu A) \quad (4)$$

$I_{IMP}$ , the current output from the IMP pin, is the summation of  $I_{MO}$  and  $I_{MR1}$ .  $I_{MR1}$  and  $I_{MR2}$  are identical fixed-current sources.  $R_2$  and  $R_3$  are also identical. They are used to pull high the operating point of the IMP and IPFC pins since the voltage across  $R_S$  goes negative with respect to ground. The constant current sources  $I_{MR1}$  and  $I_{MR2}$  are typically 60 $\mu A$ .

Through the differential amplification of the signal across  $R_S$ , better noise immunity is achieved. The output of  $I_{EA}$  is compared with an internal sawtooth and the pulse width for PFC is determined. Through the average current-mode control loop, the input current,  $I_S$ , is proportional to  $I_{MO}$ :

$$I_{MO} \times R_2 = I_S \times R_S \quad (5)$$

According to Equation 5, the minimum value of  $R_2$  and maximum of  $R_S$  can be determined, because  $I_{MO}$  should not exceed the specified maximum value.

There are different concerns in determining the value of the sense resistor  $R_S$ . The value of  $R_S$  should be small enough to reduce power consumption, but large enough to maintain the resolution. A current transformer (CT) can improve the efficiency of high-power converters.

To achieve good power factor, the voltage for  $V_{RMS}$  and  $V_{EA}$  should be kept as DC as possible, according to Equation 6. Good RC filtering for  $V_{RMS}$  and narrow bandwidth (lower than the line frequency) for voltage loop are suggested for better input current shaping. The transconductance error amplifier has output impedance  $Z_O$  ( $>90k\Omega$ ) and a capacitor  $C_{EA}$  ( $1\mu F \sim 10\mu F$ ) that should be connected to ground (as shown in Figure 32). This establishes a dominant pole  $f_1$  for the voltage loop:

$$f_1 = \frac{1}{2\pi \times Z_O \times C_{EA}} \quad (6)$$

The average total input power can be expressed as:

$$\begin{aligned} P_{in} &= V_{IN(rms)} \times I_{IN(rms)} \\ &\propto V_{RMS} \times I_{MO} \\ &\propto V_{RMS} \times \frac{I_{AC} \times V_{EA}}{V_{RMS}^2} \\ &\propto V_{RMS} \times \frac{V_{in}}{R_{AC}} \times V_{EA} \\ &= \sqrt{2} \times \frac{V_{EA}}{R_{AC}} \end{aligned} \quad (7)$$

$V_{EA}$ , the output of the voltage error amplifier, controls the total input power and the power delivered to the load.

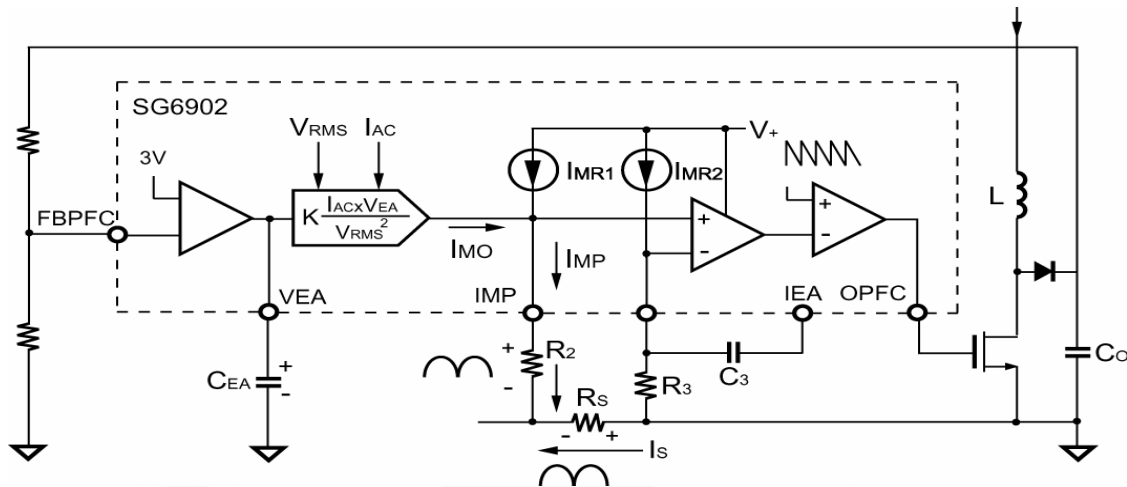


Figure 32. Average-Current-Mode Control Loop

### Multi-Vector Error Amplifier

The voltage-loop error amplifier is transconductance, which has high output impedance ( $> 90k\Omega$ ). A capacitor  $C_{EA}$  ( $1\mu \sim 10\mu F$ ) connected from  $V_{EA}$  to ground provides a dominant pole for the voltage loop. Although the PFC stage has a low bandwidth voltage loop for better input power factor, the innovative multi-vector error amplifier provides a fast transient response to clamp the overshoot and undershoot of the PFC output voltage.

Figure 33 shows the block diagram of the multi-vector error amplifier. When the variation of the feedback voltage exceeds  $\pm 5\%$  of the reference voltage, the transconductance error amplifier adjusts its output impedance to increase the loop response. If  $R_A$  is opened, SG6902 shuts off immediately to prevent extra-high voltage on the output capacitor.

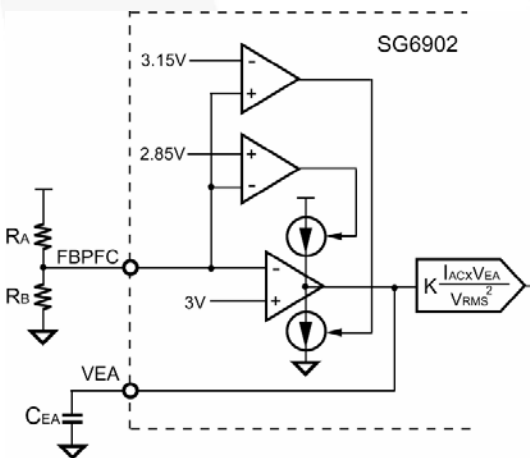


Figure 33. Multi-Vector Error Amplifier

### PFC Over-Voltage Protection

When the OVP feedback voltage exceeds the over-voltage threshold, the SG6902 inhibits the PFC switching signal. This protection also prevents the PFC power converter from operating abnormally while the FBPFC pin is open.

### Cycle-by-Cycle Current Limiting

SG6902 provides cycle-by-cycle current limiting for both PFC and PWM stages. Figure 34 shows the peak current limit for the PFC stage. The PFC gate drive is terminated once the voltage on the ISENSE pin goes below  $V_{PK}$ .

The voltage of  $V_{RMS}$  determines the voltage of  $V_{PK}$ . The relationship between  $V_{PK}$  and  $V_{RMS}$  is shown in Figure 34.

The amplitude of the constant current,  $I_P$ , is determined by the internal current reference,  $I_T$ , according to the following equation:

$$I_P = 2 \times I_T = 2 \times \frac{1.2V}{R_I} \quad (8)$$

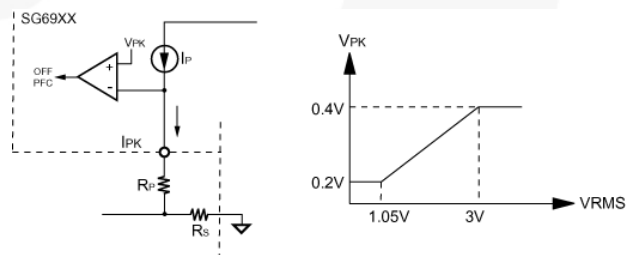


Figure 34.  $V_{RMS}$  Controlled Current Limiting

The peak current of the ISENSE is given by ( $V_{RMS} < 1.05V$ ):

$$I_{S\_peak} = \frac{(I_P \times R_P) - 0.2V}{R_S} \quad (9)$$

### Flyback PWM and Slope Compensation

As shown in Figure 35, peak-current-mode control is utilized for flyback PWM. The SG6902 inserts a synchronized 0.5V ramp at the beginning of each switching cycle. This built-in slope compensation ensures stable operation for continuous-current-mode operation.

When the IPWM voltage across the sense resistor, reaches the threshold voltage, 0.65V or 0.7V selected by RANGE, the OPWM is turned off after a small propagation delay,  $t_{PD-PWM}$ . This propagation delay introduces additional current, proportional to  $t_{PD-PWM} \cdot V_{PFC} / L_P$ , where  $V_{PFC}$  is the output voltage of PFC and  $L_P$  is the magnetized inductance of the flyback transformer. Since the propagation delay is nearly constant, higher  $V_{PFC}$  results in a larger additional current and the output power limit is higher than under low  $V_{PFC}$ . To compensate for this variation, the peak current threshold is modulated by the RANGE output. When RANGE is shorted to GND, the PFC output voltage is high and the corresponding threshold is 0.65V. When RANGE is opened, the PFC output voltage is low and the corresponding threshold is 0.7V.

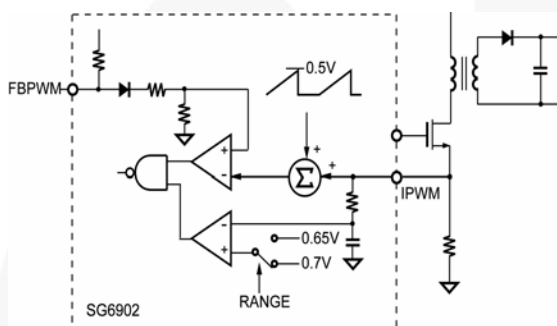


Figure 35. Peak Current Control Loop

### Limited Power Control

Every time the output of power supply is shorted or overloaded, the FBPWM voltage increases. If the FB voltage is higher than a designed threshold, 4.5V, for longer than 56ms, the OPWM is turned off. As OPWM is turned off, the supply voltage  $V_{DD}$  begins decreasing.

When  $V_{DD}$  is lower than the turn-off threshold, such as 10V, SG6902 is totally shut down. Due to the startup resistor,  $V_{DD}$  is charged up to the turn-on threshold voltage, 16V, until enabled again. If the overloading condition persists, the protection occurs repeatedly to prevent the power supply from being overheated during overload condition.

### Over-Temperature Protection

An OTP pin provides over-temperature protection. A constant current is output from this pin. If  $R_i$  is equal to 24k $\Omega$ , the magnitude of the constant current is 100 $\mu$ A. An external NTC thermistor must be connected from this pin to ground, as shown as Figure 36. When the OTP voltage drops below 1.2V, SG6902 is disabled until the OTP voltage exceeds 1.4V.

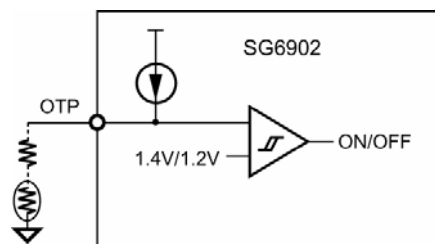


Figure 36. OTP Function

### Soft-Start

During startup of PWM stage, the SS pin charges an external capacitor with a constant current source. The voltage on FBPWM is clamped by SS voltage during startup. In the event of a protection condition and/or PWM being disabled, the SS pin quickly discharges.

### Gate Driver

SG6902 output stage is a fast totem-pole gate driver. The output driver is clamped by an internal 18V Zener diode to protect the power MOSFET.

## PCB Layout

SG6902 has two ground pins. Good high-frequency or RF layout practices should be followed. Avoid long PCB traces and component leads. Locate decoupling capacitors near the SG6902. A resistor (5 ~ 20 $\Omega$ ) is recommended, connected in series from the OPFC and OPWM, to the gate of the MOSFET.

Isolating the interference between the PFC and PWM stages is also important. Figure 37 shows an example of the PCB layout. The ground trace connected from the AGND pin to the decoupling capacitor should be low impedance and as short as possible. The ground trace 1 provides a signal ground and should be connected directly to the decoupling capacitor  $V_{DD}$  and/or to the AGND pin. The ground trace 2 shows that the AGND pins should connect to the PFC output capacitor  $C_O$  independently. The ground trace 3 is independently tied from the PGND to the PFC output capacitor  $C_O$ . The ground in the output capacitor  $C_O$  is the major ground reference for power switching. To

provide a good ground reference and reduce switching noise of both the PFC and PWM stages, the ground traces 6 and 7 should be located very near and be low impedance.

The IPFC pin is connected directly to  $R_S$  through  $R_3$  to improve noise immunity (do not incorrectly connect to ground trace 2). The IMP and ISENSE pins should be connected directly via the resistors  $R_2$  and  $R_P$  to another terminal of  $R_S$ . Because ground traces 4 and 5 are PFC and PWM stages of the current loop, they should be as short as possible.

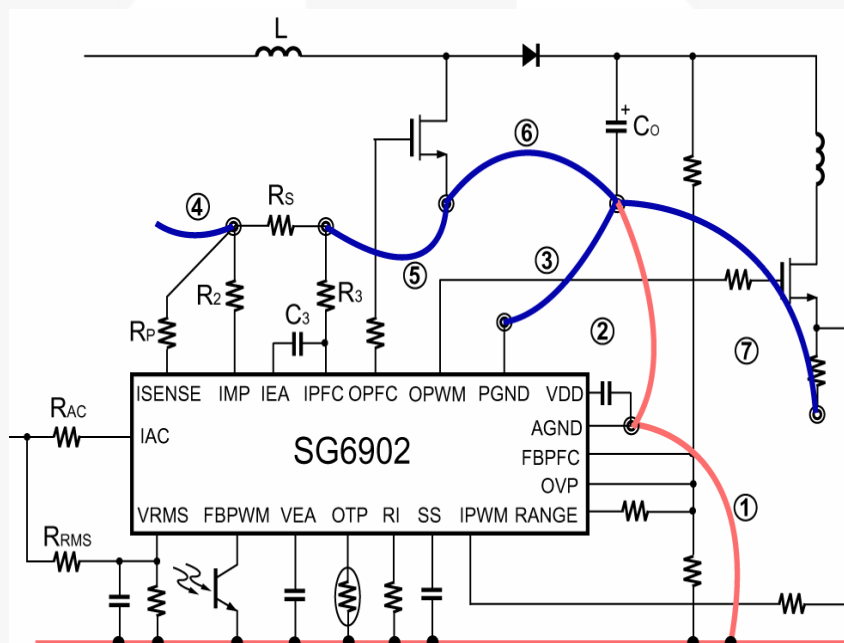


Figure 37. Layout Considerations

## Physical Dimensions

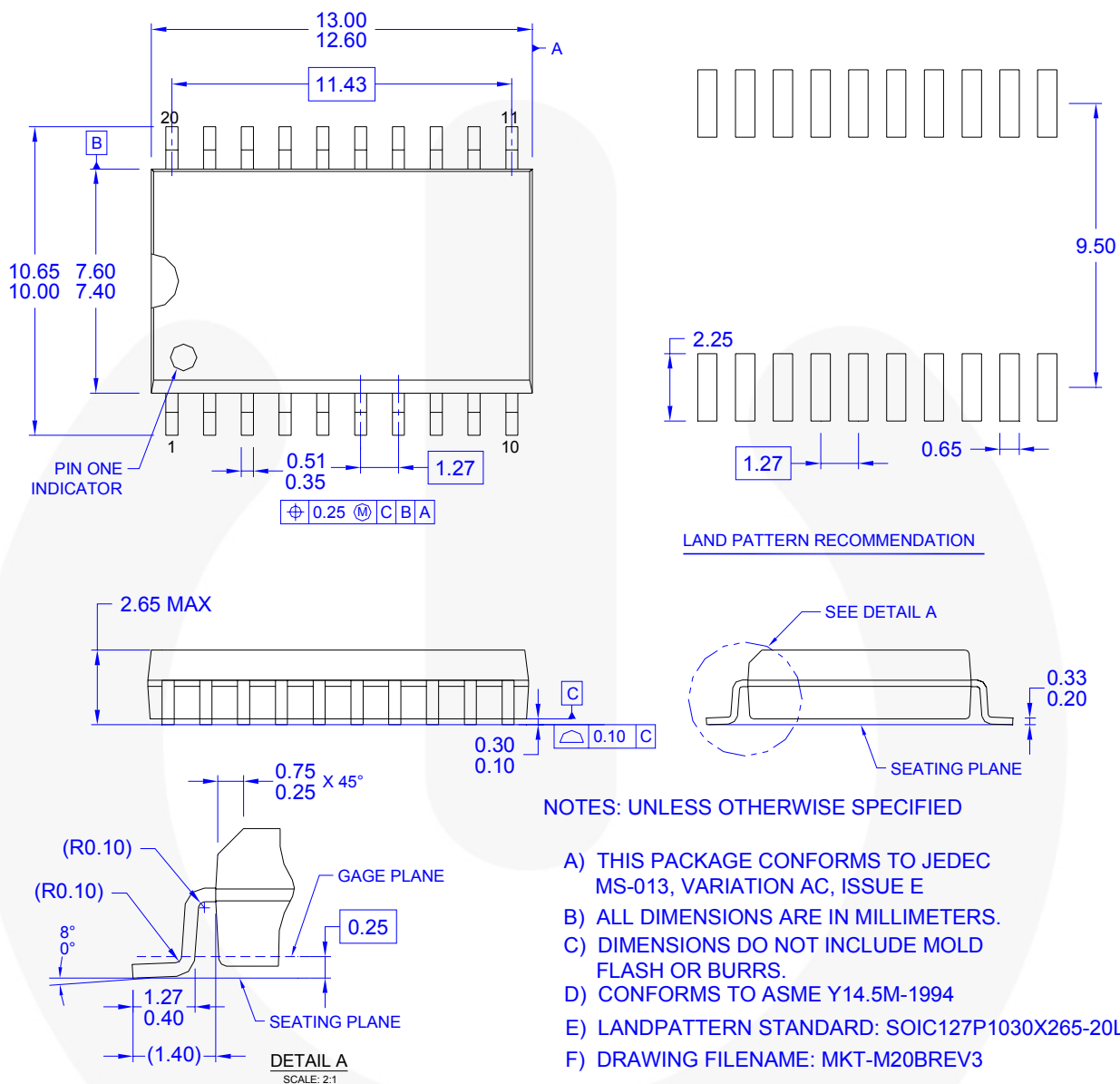


Figure 38. 20-Pin, Small Outline Package (SOIC)

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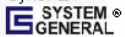


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