# 8-bit Microcontroller 8K-byte Flash ROM / 384-byte RAM / 24-pin

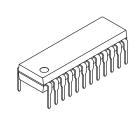


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# Overview

LC87F0K08A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 83.3 ns, integrates on a single chip a number of hardware features such as 8K-byte flash ROM (onboard programmable), 384-byte RAM, an on-chip debugger function, two sophisticated 16-bit timers/counters (may be divided into 8-bit timers), two 8-bit timers with a prescaler, a synchronous SIO interface, a UART port(full duplex), a 5-channel AD converter with 12/8-bit resolution selector, eight analog comparators, two AMP circuits, PPG, a watchdog timer, an internal reset circuit, a system clock frequency divider, and a 21-source 10-vector interrupt feature.



PDIP24 / DIP24S(300mil)

#### **Features**

#### ■ Flash ROM

- Capable of on-board programming with a power voltage range of 4.5 to 5.5 V
- Block-erasable in 128 byte units
- Writing in 2-byte units
- $8192 \times 8$  bits

#### ■ RAM

•  $384 \times 9$  bits

### ■ Package form

• DIP24S, Pb-Free type

#### ■ Minimum bus cycle time

• 83.3 ns (12 MHz)

Note: The bus cycle time here refers to the ROM read speed.

### ■ Minimum instruction cycle time

• 250 ns (12 MHz)

#### ■ Ports

• I/O ports

Ports whose I/O direction can be designated in 1 bit units: 9 (P00 to P07, P30)

• Dedicated PPG output ports 1 (PPG0)

Dedicated AMP/ CMP I/O ports
 9 (CMP1IA, CMP1IB, CMP2I, CMP4I, CMP45I,

CM5I, CMP6I, AMP1I, AMP2O)

Reset pin
Dedicated on-chip debugger pin
Regulator output pin
1 (OWP0)
1 (VDC)

• Power pins 2 (VSS1, VDD1)

#### ORDERING INFORMATION

See detailed ordering and shipping information on page 24 of this data sheet.

<sup>\*</sup> This product is licensed from Silicon Storage Technology, Inc. (USA).

#### ■ Timers

• Timer 0 : 16-bit timer/counter with a capture register

Mode 0: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register)  $\times 2$  channels Mode 1: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) + 8-bit

counter (with an 8-bit capture register)

Mode 2: 16-bit timer with an 8-bit programmable prescaler (with a 16-bit capture register)

Mode 3: 16-bit counter (with a 16-bit capture register)

• Timer 1 : 16-bit timer/counter

Mode 0: 8-bit timer with an 8-bit prescaler + 8-bit timer/counter with an 8-bit prescaler

 $Mode\ 2:\ 16\text{-bit\ timer/counter\ with\ an\ 8-bit\ prescaler}$ 

Mode 3: 16-bit timer with an 8-bit prescaler

- Timer 6 : 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Timer 7: 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Base timer
  - 1) The clock is selectable from the system clock and timer 0 prescaler output.
  - 2) Interrupts are programmable in 5 different time schemes

#### ■ Serial interface

• SIO1 : 8-bit synchronous serial interface

Mode 0 : Synchronous 8-bit serial I/O (2-wire configuration, 2 to 512 Tcyc transfer clocks)

Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 Tcyc transfer clocks)

Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

#### **■ UART**

- Full duplex
- 7 / 8 / 9 bit data bits selectable
- 1 stop bit (2 bits in continuous data transmission)
- Built-in baudrate generator

#### ■ AD converter: 12 bits × 5 channels

• 12 / 8-bit AD converter resolution selectable

### ■ Remote control receiver circuit (multiplexed with P07 / INT3 / T0IN pin)

• Noise rejection function (noise filter time constant selectable from 1 Tcyc / 32 Tcyc / 128 Tcyc)

### ■ Analog comparator : 8 channels

• CMP1 : "+" and "-" input pins

Output: For PPG output timing generation and capture timer input (INT2)

• CMP2 : "+" input pin,

"-" input is the internal Vref (user selectable options : 5/12, 6/12, or 7/12 VDD).

Output for interrupt flag setting (CMP2)

• CMP3 : "+" input is the output of AMP1.

"-" input is the internal Vref (user selectable options: 1/6, 2/6, 3/6, or 4/6 VDD).

Output for the PPG output control (only the existing cycle set to OFF), capture trigger of

pulse on time and interrupt flag set (CMP3)

• CMP4 : "+" and "-" input pins

Output for the PPG output control (forced OFF)

• CMP5 : "—" input pin, "+" input is multiplexed with the "—" input pin of CMP4

Output for the PPG output control (forced OFF)

• CMP6 : "+" input pin, "-" input is the internal Vref (register setting: 1/6, 2/6, 3/6, or 4/6 VDD)

Output for the PPG output control (forced OFF) and interrupt flag set (CMP6)

• CMP7 : "+" input is multiplexed with the "+" input pin of CMP2

"-" input is the internal Vref (user selectable options: 6/12, 7/12, or 8/12 VDD)

Output for the PPG output control (forced OFF) and interrupt flag set (CMP7).

• CMP8 : "+" input is multiplexed with the "+" input pin of CMP3

"—" input is the internal Vref (register setting: 1/6, 2/6, 3/6, or 4/6 VDD) Output for capture trigger of pulse on time and interrupt flag set (CMP8)

### ■ AMP circuit: 2 channels

• AMP1: The gain is set by user selectable options  $(6 \times / 8 \times / 10 \times)$ .

Input pin (AMP1I)

Output is CMP3 input, CMP8 input and AMP2 input.

• AMP2 : The gain  $(1 \times / 2 \times / 4 \times)$  is set by using a register.

Input is AMP1 output. Output pin (AMP2O)

### ■ IGBT control circuit (PPG2) : 1 channel

• Output sync signal switching : Set by a register (1-pulse output / continuous pulse output synchronized with the CMP1 output)

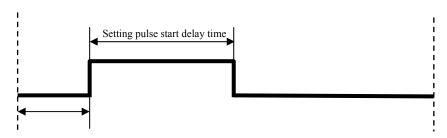
• Duty control: Pulse start delay time and pulse on time with respect to a sync signal are set by using a register.

• PPG output control using CMP3 to CMP7 outputs

• Surge detection using CMP4 / 5 / 6 outputs

• CMP1 output : Pulse signal timing detection

• Output polarity selectable : User selectable options



### ■ Clock output function

Capable of generating a clock output with a frequency of  $\frac{1}{1}$ ,  $\frac{1}{2}$ ,  $\frac{1}{4}$ ,  $\frac{1}{8}$ ,  $\frac{1}{16}$ ,  $\frac{1}{32}$ , or  $\frac{1}{64}$  of the source oscillator clock selected as the system clock.

### ■ Watchdog timer

- Can generate an internal reset signal on an overflow of timer that is running on the internal low-speed RC oscillation clock (30 kHz).
- Allows selection of continue, stop, or hold mode operation of the counter on entry into the HALT/HOLD mode.

### **■** Interrupts

- 21 sources, 10 vector addresses
  - 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt request of the level equal to or lower than the current interrupt is not accepted.
  - 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, an interrupt into the smallest vector address is given priority.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	CMP2 / CMP7
2	0000BH	X or L	CMP3 / CMP8
3	00013H	H or L	INT2 / T0L / INT4
4	0001BH	H or L	INT3 / base timer
5	00023H	H or L	ТОН
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	UART receive
8	0003BH	H or L	SIO1 / UART transmit
9	00043H	H or L	ADC / T6 / T7 / CMP1TO
10	0004BH	H or L	CMP6 / Surge detection

- Priority levels X > H > L
- For interrupts of the same level, an interrupt with a smaller vector address is given priority.

### ■ Subroutine stack levels : Up to 192 levels (the stack is allocated in RAM.)

### ■ Internal high-speed multiplication/division instructions

16 bits × 8 bits
24 bits × 16 bits
16 bits ÷ 8 bits
24 bits ÷ 16 bits
Tcyc execution time)

#### ■ Oscillation circuits

• Internal oscillation circuits

Low-speed RC oscillation circuit : For system clock /Watch dog timer (30 kHz)

Medium-speed RC oscillation circuit : For system clock (1 MHz)

High-speed RC oscillation circuit : For system clock /PPG clock (24 MHz)

\*The clock divided by two is used for system clock (12 MHz).

#### ■ System clock divider function

- Can run on low current.
- The minimum instruction cycle selectable from 250 ns, 500 ns, 1  $\mu$ s, 2  $\mu$ s, 4  $\mu$ s, 8  $\mu$ s, 16  $\mu$ s, 32  $\mu$ s, and 64  $\mu$ s (at a main clock rate of 12 MHz).

#### ■ Internal reset circuit

- Power-on reset (POR) function
  - 1) POR reset is generated only at power-on time.
  - 2) The POR release level can be selected from 5 levels (2.37 V, 2.57 V, 2.87 V, 3.86 V, and 4.35 V) by configuring options.
- Low-voltage detection reset (LVD) function
  - 1) LVD and POR functions are combined to generate resets when power is turned on and when power voltage falls below a certain level.
  - 2) The use/disuse of the LVD function and the low voltage threshold level (5 levels: 2.31 V, 2.51 V, 2.81 V, 3.79 V, 4.28 V) selectable by configuring options.

### ■ Standby function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
  - 1) Oscillation is not halted automatically.
  - 2) There are three ways of releasing the HALT mode.
    - (1) Setting the reset pin to the low level
    - (2) System resetting by watchdog timer or low-voltage detection
    - (3) Occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
  - 1) The RC oscillators automatically stop operation.
  - 2) There are three ways of releasing the HOLD mode.
    - (1) Setting the reset pin to the low level.
    - (2) System resetting by watchdog timer or low-voltage detection
    - (3) Having an interrupt source established at either INT2 or INT4.

### ■ On-chip debugger

• Supports software debugging with the IC mounted on the target board.

# ■ Data security function

• Protects the program data stored in flash memory from unauthorized read or copy.

Note: This data security function does not necessarily provide absolute data security.

### ■ Development tools

• On-chip debugger: TCB87 Type C + LC87F0K08A

### ■ Programming board

Package	Programming board
DIP24S	W87F0KD

### ■ Flash ROM programmer

Mak	er	Model	Supported version	Device
ON	Single/Gang SKK/SKK Type B Programmer (SanyoFWS)		Application version: 1.08 or later	
Semiconductor	Gang Programmer	SKK-4G (SanyoFWS)	Chip data version: 2.44 or later	LC87F0K08

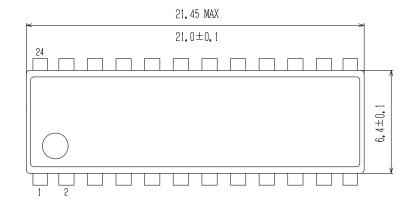
Note: Be sure to check for the latest version.

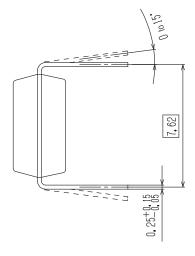
# **Package Dimensions**

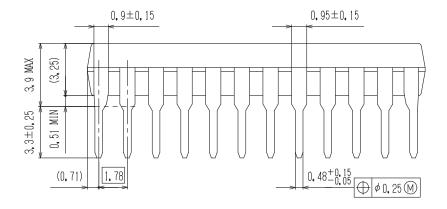
unit: mm

### PDIP24 / DIP24S (300 mil)

CASE 646AW ISSUE A







# GENERIC MARKING DIAGRAM\*



XXXXX = Specific Device Code

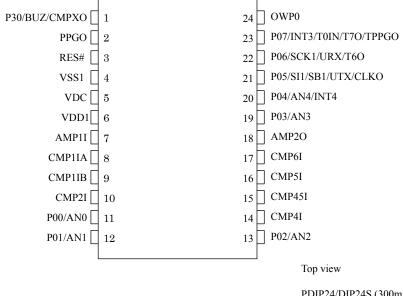
Y = Year

M = Month

DDD = Additional Traceability Data

<sup>\*</sup>This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "■", may or may not be present.

# **Pin Assignment**

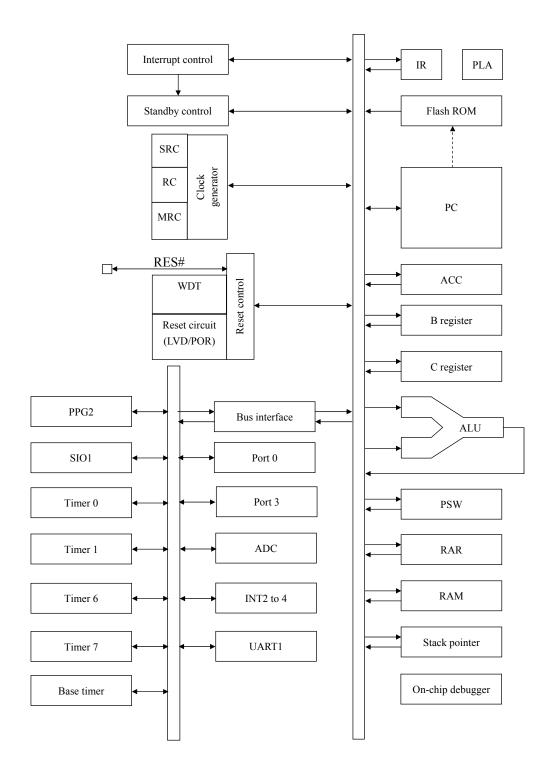


PDIP24/DIP24S (300mil) "Pb-Free type"

DIP24S	NAME
1	P30/BUZ/CMPXO
2	PPGO
3	RES#
4	VSS1
5	VDC
6	VDD1
7	AMP1I
8	CMP1IA
9	CMP1IB
10	CMP2I
11	P00/AN0
12	P01/AN1

DIP24S	NAME
13	P02/AN2
14	CMP4I
15	CMP45I
16	CMP5I
17	CMP6I
18	AMP2O
19	P03/AN3
20	P04/AN4/INT4
21	P05/SI1/SB1/UTX/CLKO
22	P06/SCK11/URX/T6O
23	P07/INT3/T0IN/T70/TPPGO
24	OWP0

# **System Block Diagram**



# **Pin Function Chart**

VSS1 — VDD1 — Port 0 I/O P00 to P07	+ power su  • 8-bit I/O   • I/O speci • Pull-up re • Pin functi P04: II  P05: S P06: S P07: II  P00(Al Interrupt a	pply pin port fiable in 1 bi esistors can ons NT4 input / F Timer 0L ca IO1 data I/O IO1 clock I/O NT3 input (w Fimer 0H ca / PPGO out NO) to P04(/ acknowledge	be turned of HOLD release apture input D / Bus I-O / O / UART re with noise filt pture input put (for mor AN4): AD co	on and off in 1 bit u se input / Timer 1 of t / Timer 0H captur / UART transmit / Seceive / Timer 6 to ter) / Timer 0 even / Timer 7 toggle ou nitor) onvertor input port	event input e input System clo ggle outpu t input	ck output	No No Yes
Port 0 I/O	Pull-up re Pin funct P04: If P05: S P06: S P07: If P00(Al Interrupt a	port fiable in 1 bi esistors can ons NT4 input / F Timer 0L ca IO1 data I/O IO1 clock I/O NT3 input (w Fimer 0H ca / PPGO out NO) to P04(A acknowledge	be turned of HOLD release apture input D / Bus I-O / O / UART re with noise filt pture input put (for mor AN4): AD co	se input / Timer 1 of the captur / Timer 0H captur / UART transmit / Seceive / Timer 6 to the captur / Timer 7 toggle outlitor)	event input e input System clo ggle outpu t input	ck output	
	Pull-up re Pull-up re Pin functi P04: If P05: S P06: S P07: If P00(Al Interrupt a	fiable in 1 bit esistors can ons NT4 input / Fimer 0L can I/O IO1 clock I/O IT3 input (worder OH can I/O IO1 clock I/O IO1 clock I/O IT3 input (worder OH can I/O IO1 clock III cloc	be turned of HOLD release apture input D / Bus I-O / O / UART re with noise filt pture input put (for mor AN4): AD co	se input / Timer 1 of the captur / Timer 0H captur / UART transmit / Seceive / Timer 6 to the captur / Timer 7 toggle outlitor)	event input e input System clo ggle outpu t input	ck output	Yes
P00 to P07	Pull-up re Pin funct P04: If P05: S P06: S P07: If P00(Al Interrupt a	esistors can ons NT4 input / H Timer 0L ca IO1 data I/O IO1 clock I/O NT3 input (w Fimer 0H ca / PPGO out NO) to P04(/ acknowledge	be turned of HOLD release apture input D / Bus I-O / O / UART re with noise filt pture input put (for mor AN4): AD co	se input / Timer 1 of the captur / Timer 0H captur / UART transmit / Seceive / Timer 6 to the captur / Timer 7 toggle outlitor)	event input e input System clo ggle outpu t input	ck output	
	Pin function P04: If P05: S P06: S P07: If P00(Al Interrupt a	ons NT4 input / H Timer 0L ca IO1 data I/O IO1 clock I/O NT3 input (w Timer 0H ca / PPGO out N0) to P04(A acknowledge	HOLD release apture input of / Bus I-O / O / UART revith noise filt pture input four for more AN4): AD co	se input / Timer 1 of the captur / Timer 0H captur / UART transmit / Seceive / Timer 6 to the captur / Timer 7 toggle outlitor)	event input e input System clo ggle outpu t input	ck output	
	P04: If P05: S P06: S P07: If P00(Al Interrupt a	NT4 input / I Timer 0L ca IO1 data I/O IO1 clock I/O NT3 input (w Fimer 0H ca / PPGO out NO) to P04(A acknowledge	apture input  O / Bus I-O /  O / UART re  rith noise filt  pture input  put (for mor  AN4): AD co	t / Timer 0H captur ' UART transmit / Seceive / Timer 6 to ter) / Timer 0 even / Timer 7 toggle ou nitor)	e input System clo ggle outpu t input	ck output	
	P05: S P06: S P07: II P00(Al Interrupt a	Timer 0L ca IO1 data I/O IO1 clock I/O IT3 input (w Fimer 0H ca / PPGO out N0) to P04(A acknowledge	apture input  O / Bus I-O /  O / UART re  rith noise filt  pture input  put (for mor  AN4): AD co	t / Timer 0H captur ' UART transmit / Seceive / Timer 6 to ter) / Timer 0 even / Timer 7 toggle ou nitor)	e input System clo ggle outpu t input	ck output	
	P05: S P06: S P07: II P00(Al Interrupt a	IO1 data I/C IO1 clock I/O IT3 input (w Fimer 0H ca / PPGO out N0) to P04(/ acknowledge	D / Bus I-O / O / UART revith noise filt pture input put (for mor AN4): AD co	UART transmit / Seceive / Timer 6 to ter) / Timer 0 even / Timer 7 toggle ounitor)	System clo ggle outpu t input	•	
	P06: S P07: II P00(Al Interrupt a	IO1 clock I/0 NT3 input (w Fimer 0H ca / PPGO out N0) to P04(/ acknowledge	O / UART revith noise filt pture input pout (for mor AN4): AD co	eceive / Timer 6 to ter) / Timer 0 even / Timer 7 toggle ou nitor)	ggle outpu t input	•	
	P07: Interrupt a	NT3 input (w Fimer 0H ca / PPGO out N0) to P04(/ acknowledge	rith noise filt pture input put (for mor AN4): AD co	ter) / Timer 0 even / Timer 7 toggle ou nitor)	t input		
	P00(Al Interrupt a	/ PPGO out N0) to P04(/ acknowledge	put (for mor AN4): AD co	nitor)	ıtput		
	P00(Al Interrupt a	N0) to P04(A	AN4): AD co	,			
	Interrupt a	acknowledge	,	onvertor input port			
			е туре				
		1					1
		Rising	Falling	Rising & Falling	H level	L level	
	INT3	0	0	0	Х	Х	
	INT4	0	0	0	Х	Х	
							-
Port 3 I/O							Yes
P30	·	fiable in 1 bi					
	Pull-up re     Pin functi		be turned c	on and off in 1 bit u	inits.		
		zzer output	/ Comparate	or output			
AMP1I I		•	Comparat	or output			No
AMP2O O	-	-					No
CMP1IA I	-						No
CMP1IB I	CMP1 (+) i	nput pin					No
CMP2I I	CMP2 (+)	CMP7 (+) i	nput pin				No
CMP4I I	CMP4 (+)	nput pin					No
CMP45I I	CMP4 (-),	CMP5 (+) ir	nput pin				No
CMP5I I	CMP5 (-) i	nput pin					No
CMP6I I	CMP6(+) ir	nput pin					No
PPGO O	PPG outpu	t port					Yes
RES# I/O	External re	set Input / ir	nternal rese	t output pin			No
OWP0 I/O	Debugger-	dedicated p	in				No
VDC O		output pin					No

# **Port Output Types**

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.

Data can be read into any input port even if it is in the output mode.

Port Name	Option Selected in Units of	Option Type	Output Type	Pull-up Resistor	
P00 to P07	1 bit	1	CMOS	Programmable	
F00 10 F07	1 DIL	2	N-channel open drain	Programmable	
P30	1 bit	1	CMOS	Programmable	
F30	i bit	2	N-channel open drain	Programmable	
PPGO		1	CMOS	No	
PPGO	_	2	N-channel open drain	No	

# **User Option Table**

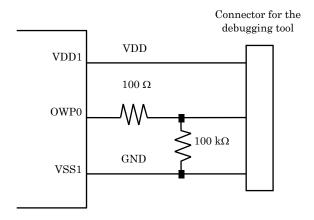
Option Name	Option to Be Applied on	Flash-ROM Version	Option Selected in Units of	Option Selection
	P00 to P07	0	1 bit	CMOS
	P00 t0 P07		1 DIL	N-channel open drain
Port output type	P30	0	1 bit	CMOS
Fort output type	1 30		1 Dit	N-channel open drain
	PPGO	0		CMOS
	FFGO		_	N-channel open drain
PPGO output	PPGO	0	1 bit	Not inverted
polarity	11 00		1 Dit	Inverted
				6x
AMP gain	AMP1	0	1 bit	8x
				10x
				5/12VDD
CMP2Vref	_	0	-	6/12VDD
				7/12VDD
				1/6VDD
CMD2\/rof		0		2/6VDD
CMP3Vref	_	O	_	3/6VDD
				4/6VDD
				6/12VDD
CMP7Vref	_	0	_	7/12VDD
				6/12VDD
				080h
				100h
				180h
				200h
				280h
				300h
				380h
PPG Pulse On	PPG-Pulse-On time upper	_		400h
time	limit	0	_	480h
				500h
				580h
				600h
				680h
				700h
				780h
				7FFh
Low voltage				Enabled: Use
Low-voltage detection reset	Detection function	0	_	Disabled: Disuse
function	Detection level	0	_	5-level
Power-on reset function	Power-on reset level	0	-	5-level

#### **Recommended Unused Pin Connections**

Port Name	Recommended Unused Pin Connections			
Port Name	Board	Software		
P00 to P07	Open	Output low		
P30	Open	Output low		
AMP1I,				
CMP1AI, CMP1IB,				
CMP2I,	Pull down with a 100 $k\Omega$ resistor or less.	_		
CMP4I, CMP45I				
CMP5I, CMP6I				
AMP2O	Open	_		

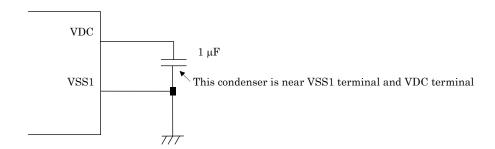
# **On-chip Debugger Pin Connection Requirements**

Install and connect a limiting resistor (100  $\Omega$ ) to the on-chip debugger dedicated pin (OWP0) on the user board and pull the pin down (100 k $\Omega$ ). It is recommended to install a dedicated connector to accept the cable to the debugging tool (TCB87 Type C). The connector must accommodate three lines, i.e., VSS1, OWP0, and VDD1.



### **Regulator Output Pin Connection Requirements**

The Regulator output pin (VDC) must be connected a condenser (1  $\mu$ F) on the user's board.



# 1. Absolute Maximum Ratings at Ta = 25°C, VSS1 = 0 V

	)	Cumbal	Din / Damarka	Conditions		Specification			
F	arameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Maxi	imum supply	VDDMAX	VDD1			-0.3	-	+6.5	٧
Input voltage		VI	RES#, AMP1I, CMP1IA, CMP1IB, CMP2I, CMP4I, CMP45I, CMP5I, CMP6I			-0.3	_	VDD+0.3	
Outp	out voltage	VO	AMP2O, PPGO			-0.3	_	VDD+0.3	
Inpu	t/output voltage	VIO	Ports 0, 3 OWP0			-0.3	_	VDD+0.3	
utput	Peak output current	IOPH	Ports 0, 3, PPGO, OWP0	CMOS output select Per 1 applicable pin		-10			mA
High level output current	Mean output current (Note 1-1)	IOMH	Ports 0, 3, PPGO, OWP0	CMOS output select Per 1 applicable pin		-7.5			
High	Total output current	ΣΙΟΑΗ	Ports 0, 3, PPGO, OWP0	Total of all applicable pins		-25			
	Peak output current	IOPL (1)	P02 to P07, Ports 3, PPGO, OWP0	Per 1 applicable pin				20	
ent		IOPL (2)	P00, P01	Per 1 applicable pin				30	
Low level output current	Mean output current (Note 1-1)	IOML (1)	P02 to P07, Ports 3, PPGO, OWP0	Per 1 applicable pin				15	
no		IOML (2)	P00, P01	Per 1 applicable pin				20	
eve	Total output	ΣIOAL (1)	P00 to P03	Total of all applicable pins				40	
Low	current	ΣIOAL (2)	P04 to P07, Ports 3, PPGO, OWP0	Total of all applicable pins				40	
		ΣIOAL (3)	Ports 0, 3,PPGO, OWP0	Total of all applicable pins				70	
dissi	Illowable power issipation  Pdmax  DIP24S  Ta = -40 to +85°C  Mounted on thermal resistance test board (Note 1-2)			460	mW				
	rating ambient perature	Topr				-40	-	+85	°C
	age ambient perature	Tstg				-55	-	+125	

Note 1-1: The mean output current is a mean value measured over 100 ms.

Note 1-2 : SEMI standards thermal resistance board (size: 76.1 ×114.3 ×1.6 t mm, glass epoxy) is used.

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

### 2. Allowable Operating Conditions at Ta = -40 to +85°C, VSS1 = 0 V

		- · · - ·	0 1111			Specif	ication	on
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Operating supply voltage	VDD	VDD1	0.242 µs ≤ tCYC ≤ 200 µs		4.5		5.5	V
Memory sustaining supply voltage	VHD	VDD1	RAM and register contents sustained in HOLD mode.		2.0			
High level input voltage	VIH (1)	Ports 0, 3, OWP0		4.5 to 5.5	0.3VDD +0.7		VDD	
	VIH (2)	RES#		4.5 to 5.5	0.75VDD		VDD	
Low level input voltage	VIL (1)	Ports 3, OWP0		4.5 to 5.5	VSS		0.1VDD +0.4	
	VIL (2)	Port 0		4.5 to 5.5	VSS		0.15VDD +0.4	
	VIL (3)	RES#		4.5 to 5.5	VSS		0.25VDD	
Instruction cycle time (Note 2-1)	tCYC (Note 2-1)			4.5 to 5.5	0.242		200	μs
Oscillation frequency range	FmMRC		Internal high-speed RC oscillation. (Note 2-2)	4.5 to 5.5	23.28	24.0	24.72	MHz
	FmRC		Internal medium-speed RC oscillation	4.5 to 5.5	0.5	1.0	2.0	
	FmSRC2		Internal low-speed RC oscillation	4.5 to 5.5	15	30	60	kHz

Note 2-1 : Relationship between tCYC and oscillation frequency is 3/FmMRC at a division ratio of 1/1 and 6/FmMRC at a division ratio of 1/2.

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

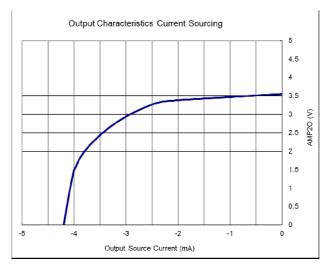
Note 2-2: When switching the system clock, allow <u>an oscillation stabilization time of 100 μs or longer</u> after the high-speed RC oscillator circuit transmits from the "oscillation stopped" to "oscillation enabled" state. The signal that divided high-speed RC oscillator clock by two is used for system clock (Typ. 12 MHz).

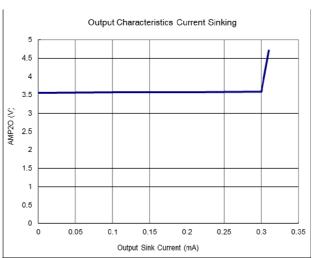
# 3. Electrical Characteristics at Ta = -40 to +85°C, VSS1 = 0 V

Davamatav	Cumbal	Din / Demonts	Canditions			Specifi	cation	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
High level input current	IIH	Ports 0, 3, AMP1I, CMP1IA, CMP1IB, CMP2I, CMP4I, CMP45I, CMP5I, CMP6I, RES#	Output disabled Pull-up resistor off VIN = VDD (Including output Tr's off leakage current)	4.5 to 5.5			1	Α
Low level input current	IIL	Ports 0, 3, AMP1I, CMP1IA, CMP1IB, CMP2I, CMP4I, CMP45I, CMP5I, CMP6I, RES#	Output disabled Pull-up resistor off VIN = VSS (Including output Tr's off leakage current)	4.5 to 5.5	-1			
AMP allowable output current (Note 3-1)	IAMP	AMP2O	AMP 1 gain is 8x and AMP 2 gain is 1x selected AMP1I = 0.445 V	5.0	-2.0		0.30	mA
High level output	VOH (1)	Ports 0	IOH = -1 mA	4.5 to 5.5	VDD-1			V
voltage	VOH (2)	Ports 3, PPGO, OWP0	IOH = -6 mA	4.5 to 5.5	VDD-1			
Low level output voltage	VOL (1)	P02 to P07, Port 3, PPGO, OWP0	IOL = 10 mA	4.5 to 5.5			1.5	
	VOL (2)	P00, P01	IOL = 25 mA	4.5 to 5.5			1.5	
Pull-up resistance	Rpu	Ports 0, 3	VOH = 0.9VDD	4.5 to 5.5	15	35	80	kΩ
Hysteresis voltage	VHYS	Ports 0,RES#, OWP0	P04 only when detecting INT4 interrupt	4.5 to 5.5		0.1VDD		V
Pin capacitance	СР	All pins	For pins other than that under test: VIN = VSS f = 1 MHz, Ta = 25°C	4.5 to 5.5		10		pF

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Note 3-1:





# **4. Serial I/O Characteristics** at Ta = -40 to +85°C, VSS1 = 0 V (Note 4-1)

	В	arameter	Symbol	Pin /	Conditions			Speci	fication	
		aranneter	Syllibol	Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
	k	Frequency	tSCK (1)	SCK1 (P06)	· See Fig. 2.	4.5 to 5.5	2			tCYC
	Input clock	Low level pulse width	tSCKL (1)				1			
clock	ll	High level pulse width	tSCKH (1)				1			
Serial clock	×	Frequency	tSCK (2)	SCK1 (P06)	· CMOS output selected · See Fig. 2.	4.5 to 5.5	2			
	Output clock	Low level pulse width	tSCKL (2)		000 . ig. <u>1</u> .			1/2		tSCK
	On	High level pulse width	tSCKH (2)					1/2		
input	Da	ta setup time	tsDI	SB1 (P05)	Must be specified with respect to rising edge of SIOCLK.	4.5 to 5.5	(1/3)tCYC +0.01			μs
Serial input	Da	ta hold time	thDI		· See Fig. 2.		0.03			
Serial output	Ou	tput delay time	tdD0	SB1 (P05)	Must be specified with respect to falling edge of SIOCLK.     Must be specified as the time to the beginning of output state change in open drain output mode.     See Fig. 2	4.5 to 5.5			(1/2)tCYC +0.05	

Note 4-1: These specifications are theoretical values. Be sure to add margin depending on its use.

# **5. Pulse Input Conditions** at Ta = -40 to +85°C, VSS1 = 0 V

Daramatar	Cumbal	Din / Domorko	Conditions			Specif	ication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
High/low level pulse width	tPIH (1) tPIL (1)	INT3 (P07) when no noise filter is used, INT4 (P04)	Interrupt source flag can be set.     Event inputs for timer 0 or 1 are enabled.	4.5 to 5.5	1			tCYC
	tPIH (2) tPIL (2)	INT3 (P07) when noise filter time constant is 1/1.	Interrupt source flag can be set.     Event inputs for timer 0 are enabled.	4.5 to 5.5	2			
	tPIH (3) tPIL (3)	INT3 (P07) when noise filter time constant is 1/32.	Interrupt source flag can be set.     Event inputs for timer 0 are enabled.	4.5 to 5.5	64			
	tPIH (4) tPIL (4)	INT3 (P07) when noise filter time constant is 1/128.	Interrupt source flag can be set.     Event inputs for timer 0 are enabled.	4.5 to 5.5	256			
	tPIL (5)	RES#	· Resetting is enabled.	4.5 to 5.5	200			μs

#### 6. AD Converter Characteristics at VSS1 = 0 V

### <12 bits AD Converter Mode at Ta = -40 to +85°C >

		D: /D	O Property			Specif	ication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Resolution	N	AN0 (P00) to		4.5 to 5.5		12		bit
Absolute accuracy	ET	AN4 (P04)	(Note 6-1)	4.5 to 5.5			±16	LSB
Conversion time	TCAD		See conversion time calculation formulas. (Note 6-2)	4.5 to 5.5	32		115	μs
Analog input voltage range	VAIN			4.5 to 5.5	VSS		VDD	V
Analog port	IAINH		VAIN = VDD	4.5 to 5.5			1	μΑ
input current	IAINL		VAIN = VSS	4.5 to 5.5	-1			

#### <8 bits AD Converter Mode at Ta = -40 to +85°C >

Downestan	Cumbal	Din / Damarka	Canditions			Specif	ication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Resolution	N	AN0 (P00) to		4.5 to 5.5		8		bit
Absolute accuracy	ET	AN4 (P04)	(Note 6-1)	4.5 to 5.5			±1.5	LSB
Conversion time	TCAD		See conversion time calculation formulas. (Note 6-2)	4.5 to 5.5	20		90	μs
Analog input voltage range	VAIN			4.5 to 5.5	VSS		VDD	V
Analog port	IAINH		VAIN = VDD	4.5 to 5.5			1	μΑ
input current	IAINL		VAIN = VSS	4.5 to 5.5	-1			

Conversion time calculation formulas:

12 bits AD Converter Mode: TCAD (Conversion time) = ((52 / (AD division ratio)) + 2) × (1/3) × tCYC

8 bits AD Converter Mode: TCAD (Conversion time) =  $((32 / (AD \text{ division ratio})) + 2) \times (1/3) \times tCYC$ 

### <Recommended Operating Conditions>

Internal oscillation	Operating supply voltage range	System division ratio	Cycle time (tCYC)	AD division ratio	AD conversion time (TCAD)		
(FmMRC)	(VDD)	(SYSDIV)	(1010)	(ADDIV)	12-bit AD	8-bit AD	
12 MHz	4.5 V to 5.5 V	1/1	250 ns	1/8	34.8 µs	21.5 µs	

- Note 6-1: The quantization error  $(\pm 1/2LSB)$  must be excluded from the absolute accuracy. The absolute accuracy must be measured in the microcontroller's state in which no I/O operations occur at the pins adjacent to the analog input channel.
- Note 6-2: The conversion time refers to the period from the time an instruction for starting a conversion process till the time the conversion results register(s) are loaded with a complete digital conversion value corresponding to the analog input value.

The conversion time is 2 times the normal-time conversion time when :

- The first AD conversion is performed in the 12-bit AD conversion mode after a system reset.
- The first AD conversion is performed after the AD conversion mode is switched from 8-bit to 12-bit conversion mode.

### 7. Power-on Reset (POR) Characteristics at Ta = -40 to +85°C, VSS1 = 0 V

						Specifi	cation	
Parameter	Symbol	Pin / Remarks	Conditions	Option selected voltage	min.	typ.	max.	unit
POR release	PORRL		· Select from options.	2.37 V	2.25	2.37	2.49	V
voltage			(Note 7-1)	2.57 V	2.45	2.57	2.69	
				2.87 V	2.73	2.85	2.97	
				3.86 V	3.69	3.84	3.99	
				4.35 V	4.15	4.33	4.50	
Detection voltage unknown state	POUKS		· See Fig. 4. (Note 7-2)			0.7	0.95	
Power supply rise time	PORIS		• Power supply rise time from VDD = 0 V to 1.6 V.				100	ms

Note7-1: The POR release level can be selected out of 5 levels when the LVD reset function is disabled.

Note7-2: POR is in an unknown state before transistors start operation.

### 8. Low Voltage Detection Reset (LVD) Characteristics at Ta = -40 to +85°C, VSS1 = 0 V

						Specifi	cation	
Parameter	Symbol	Pin / Remarks	Conditions	Option selected voltage	min.	typ.	max.	unit
LVD reset	LVDET		Select from options.	2.31 V	2.21	2.31	2.41	V
voltage			See Fig. 5.	2.51 V	2.41	2.51	2.61	
(Note 8-2)			(Note 8-1)	2.81 V	2.66	2.81	2.96	
			(Note 8-3)	3.79 V	3.61	3.79	3.97	
				4.28 V	4.10	4.28	4.46	
LVD detection	LVHYS			2.31 V		50		mV
voltage				2.51 V		50		
hysteresis				2.81 V		50		
				3.79 V		50		
				4.28 V		50		
Detection voltage unknown state	LVUKS		See Fig. 5. (Note 8-4)			0.7	0.95	٧
Low voltage detection minimum width (Reply sensitivity)	TLVDW		LVDET-0.5 V See Fig. 6.		0.2			ms

Note8-1: The LVD reset level can be selected out of 5 levels when the LVD reset function is enabled.

Note8-2: LVD reset voltage specification values do not include hysteresis voltage.

Note8-3 : LVD reset voltage may exceed its specification values when port output state changes and/or when a large current flows through port.

Note8-4: LVD is in an unknown state before transistors start operation.

# 9. Amplifier and Comparator Characteristics at Ta = -40 to +85°C, VSS1 = 0 V

Downwater	Cumbal	Din / Damanka	Conditions			Specif	ication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Common-mod e input voltage (Note 9-1)	VCMIN	CMP1IA,CMP1IB, CMP2I, CMP4I, CMP45I, CMP5I, CMP6I		4.5 to 5.5	VSS		VDD -1.5 V	\ \
Internal reference voltage error	VREF	CMP2, CMP3, CMP6, CMP7, CMP8		4.5 to 5.5	-0.02		+0.02	
AMP input voltage range (Note 9-2)	VAMIN	AMP1I		4.5 to 5.5	VSS		(VDD -1.5 V) /AMP gain	
Offset voltage	VOFF(1)	CMP1IA, CMP1IB (CMP1) CMP4I, CMP45I (CMP4) CMP45I, CMP5I (CMP5)	Within common-mode input voltage range	4.5 to 5.5			±20	mV
	VOFF(2)	CMP2I (CMP2,CMP7), CMP6I (CMP6)	Within common-mode input voltage range     Including VREF error	4.5 to 5.5			±40	
	VOFF(3)	AMP1I (CMP3,CMP8)	Within AMP Input voltage range     AMP1 gain set at 8x     Including AMP1 output error and VREF error	4.5 to 5.5			±28	
AMP output error	VAER(1)	AMP2O	· AMP1I = 0.41 V · AMP1 gain set at 8x · AMP2 gain set at 1x			±155	±180	
CMP1/CMP4/ CMP5 response time	tC145RT	PPGO, CMPXO(P30)	Within common-mode input voltage range     Input amplitude = 100 mV     Over drive = 50 mV	4.5 to 5.5		200		ns
CMP3/CMP8 response time	tC38RT	PPGO, CMPXO(P30)	· AMP1 gain set at 8x · AMP1I rising time · MP1I = (VREF ±100 mV) / 8 · See Fig. 7.	4.5 to 5.5		600		
CMP2 response time	tC2RT	CMPXO(P30)	· CMP input pin rising time     · CMP input = VREF ±50 mV	4.5 to 5.5		200		
CMP6/CMP7 response time	tC67RT	PPGO, CMPXO(P30)	CMP input pin rising time     CMP input = VREF ±50 mV     See Fig. 7.	4.5 to 5.5		200		

Note 9-1 : When VDD = 5 V, the comparator input voltage is effective from 0 to 3.5 V.

Note 9-2 : AMP gain = AMP1 gain × AMP2 gain

When VDD = 5 V, AMP1 gain = 8x, AMP2 gain = 1x, the AMP input voltage is effective from 0 to 0.4375 V.

Note 9-3 : PPG output for CMP1 has a delay of 1/6 tCYC to 1/2 tCYC from CMPXO falling timing for synchronization with system clock, when the pulse start delay setup register is set to 000H.

# 10. Consumption Current Characteristics at $Ta = -40 \text{ to } +85^{\circ}\text{C}$ , VSS1 = 0 V

						Specif	ication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	Max.	unit
Normal mode consumption current (Note 10-1)	IDDOP(1)	VDD1	System clock set to internal high speed RC oscillator     Internal low speed / medium speed RC oscillator stopped.     1/1 frequency division ratio	4.5 to 5.5		5.6	7.7	mA
(Note 10-2)	IDDOP(2)		System clock set to internal medium speed RC oscillator     Internal low speed / high speed RC oscillator stopped.     1/2 frequency division ratio	4.5 to 5.5		1.8	2.9	
	IDDOP(3)		<ul> <li>System clock set to internal low speed RC oscillator</li> <li>Internal medium speed / high speed RC oscillator stopped.</li> <li>1/1 frequency division ratio</li> </ul>	4.5 to 5.5		1.7	2.7	
Halt mode consumption current (Note 10-1) (Note 10-2)	IDDHALT(1)		<ul> <li>HALT mode</li> <li>System clock set to internal high speed RC oscillator</li> <li>Internal low speed / medium speed RC oscillator stopped.</li> <li>1/1 frequency division ratio</li> </ul>	4.5 to 5.5		3.5	4.9	
	IDDHALT(2)		HALT mode     System clock set to internal medium speed RC oscillator     Internal low speed / high speed RC oscillator stopped.     1/2 frequency division ratio	4.5 to 5.5		1.7	2.7	
	IDDHALT(3)		HALT mode     System clock set to internal low speed RC oscillator     Internal medium speed / high speed RC oscillator stopped.     1/1 frequency division ratio	4.5 to 5.5		1.6	2.7	
HOLD mode consumption current (Note 10-1) (Note 10-2) (Note 10-3)	IDDHOLD		HOLD mode.     When LVD option selected	4.5 to 5.5		1.6	2.7	

Note10-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

Note10-2: The consumption current values do not include operational current of LVD function if not specified.

Note10-3: AMP and CMP circuits are operating in HOLD mode.

### 11. F-ROM Programming Characteristics at Ta = +10 to +55°C, VSS1 = 0 V

						Speci	fication	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Onboard programming current	IDDFW	VDD1	Excluding current consumption of the microcontroller block	4.5 to 5.5		7	11	mA
Programming	tFW (1)		· Erasing operation	4.5 to 5.5		12	15	ms
time	tFW (2)		· Programming operation			35	45	μs

### 12. UART (Full Duplex) Operating Conditions at Ta = -40 to +85°C, VSS1 = 0 V

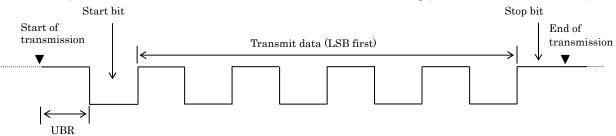
						Specific	cation	
Parameter	Symbol	Pin / Remarks	Conditions	VDD [V]	min.	typ.	max.	unit
Transfer rate	UBR	UTX (P05) URX (P06)		4.5 to 5.5	16/3		8192/3	tCYC

Data length : 7 / 8 / 9 bits (LSB first)

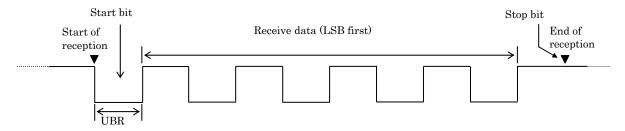
Stop bits : 1 bit (2-bit in continuous data transmission)

Parity bits : None

# Example of Continuous 8-bit Data Transmission Mode Processing (First Transmit Data = 55H)



# Example of Continuous 8-bit Data Reception Mode Processing (First Receive Data = 55H)



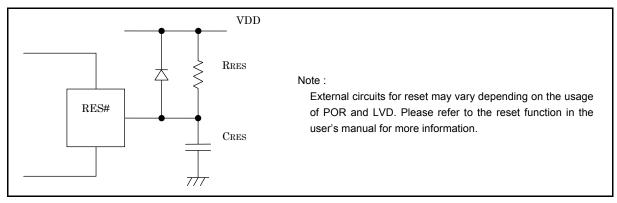


Figure 1 Sample Reset Circuit

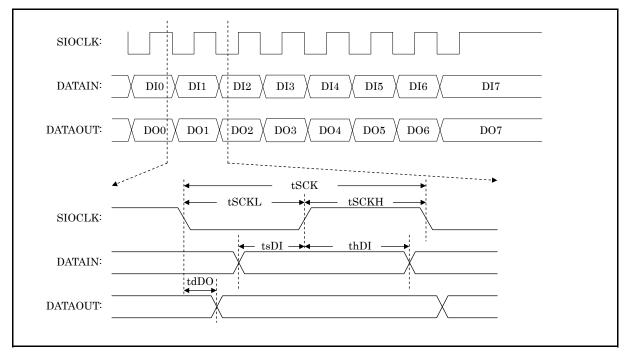


Figure 2 Serial I/O Waveforms

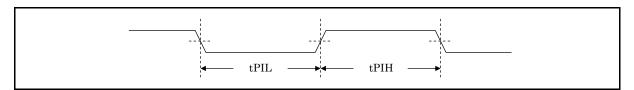
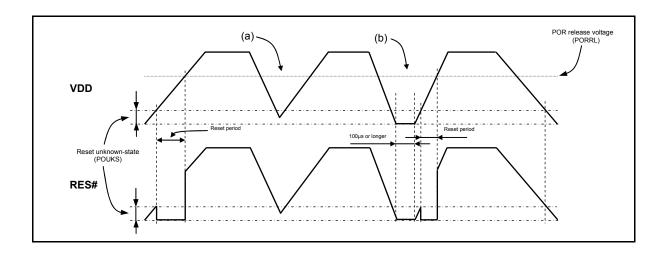


Figure 3 Pulse Input Timing Signal Waveform

Figure 4 Example of waveforms observed when only POR is used (LVD not used) (RESET pin : Pull-up resistor  $R_{RES}$  only)

- The POR function generates a reset only when power is turned on starting at the VSS level.
- No stable reset will be generated if power is turned on again when the power level does not go down to the VSS level as shown in (a). If such a case is anticipated, use the LVD function together with the POR function or implement an external reset circuit.
- A reset is generated only when the power level goes down to the VSS level as shown in (b) and power is turned on again after this condition continues for 100µs or longer.



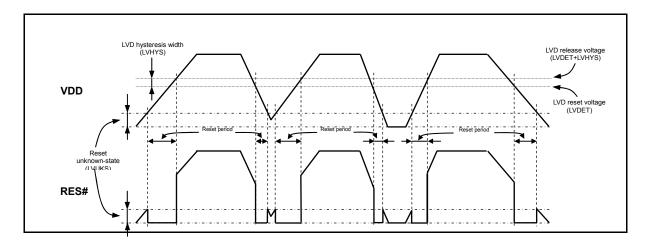


Figure 5 Example of waveforms observed when both POR and LVD functions are used (RESET pin: Pull-up resistor R<sub>RES</sub> only)

- Resets are generated both when power is turned on and when the power level lowers.
- <u>A hysteresis width (LVHYS) is provided to prevent the repetitions of reset release and entry cycles near the detection level.</u>

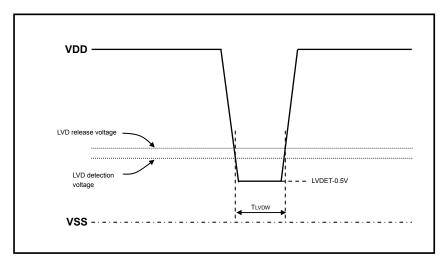


Figure 6 Low voltage detection minimum width (Example of momentary power loss / Voltage variation waveform)

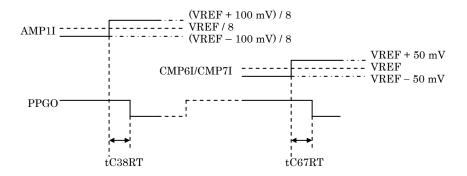


Figure 7 CMP response time

#### ORDERING INFORMATION

Device	Package	Shipping (Qty / Packing)
LC87F0K08AUDA-E	DIP24S(300mil) (Pb-Free)	1100 / Fan-Fold

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