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August 2010

USB1T11A — Universal Serial Bus Transceiver

Features

- Complies with Universal Serial Bus Specification 1.1
- Utilizes Digital Inputs and Outputs to Transmit and Receive USB Cable Data
- Supports 12Mbit/s "Full Speed" and 1.5Mbit/s "Low Speed" Serial Data Transmission
- Compatible with the VHDL "Serial Interface Engine" from USB Implementers' Forum
- Supports Single-ended Data Interface
- Single 3.3V Supply
- ESD Performance: Human Body Model >9.5kV on D-, D+ pins only >4kV on all other pins

Description

The USB1T11A is a one-chip, generic USB transceiver. It is designed to allow 5.0V or 3.3V programmable and standard logic to interface with the physical layer of the Universal Serial Bus. It is capable of transmitting and receiving serial data at both full-speed (12Mbit/s) and low-speed (1.5Mbit/s) data rates.

The input and output signals of the USB1T11A conform with the "Serial Interface Engine." Implementation of the serial interface engine allows designers to make USB-compatible devices with off-the-shelf logic to modify and update the application.

Ordering Information

| Part Number | Operating Temperature Range | Package | Packing Method |
|--------------|-----------------------------------|---|-------------------|
| USB1T11AM | | 14-Lead, Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150-Inch Narrow | Tube |
| USB1T11AMX | -40 to +85°C | 14-Lead, Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150-Inch Narrow | Tape and Reel |
| USB1T11AMTC | -40 to +65 C | 14-Lead, Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide | Tube |
| USB1T11AMTCX | | 14-Lead, Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide | Tape and Reel |

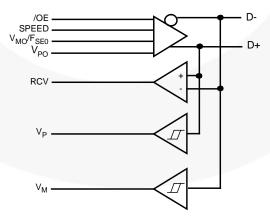


Figure 1. Logic Diagram

Pin Configuration

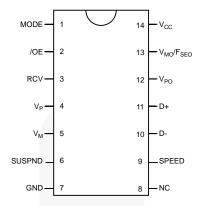


Figure 2. TSSOP and SOIC Pin Assignments

Pin Descriptions

| Pin Names | I/O | | Desc | cription | | | | |
|--------------------------|----------|--|---|--|---|--|--|--|
| RCV | 0 | Receive Data. CMOS | Receive Data. CMOS level output for USB differential input. | | | | | |
| /OE | 1 | | Output Enable. Active LOW, enables the transceiver to transmit data on the bus. When not active, the transceiver is in receive mode. | | | | | |
| Mode | 1 | | Mode . When left unconnected, a weak pull-up transistor pulls it to V_{CC} and, in this GND, the V_{MO}/F_{SEO} pin takes the function of F_{SEO} (force SEO). | | | | | |
| | | Inputs to differential d | river. (Outputs from | SIE.) | | | | |
| | | Mode | V_{PO} | V _{MO} /F _{SEO} | RESULT | | | |
| | | 0 | 0 | 0 | Logic "0" | | | |
| | | 0 | 0 | 1 | /SEO | | | |
| $V_{PO}, V_{MO}/F_{SEO}$ | | 0 | 1 | 0 | Logic "1" | | | |
| V PO, V MO/T SEO | | 0 | 1 | 1 | /SEO | | | |
| | | 1 | 0 | 0 | /SEO | | | |
| | | 1 0 | | 1 | Logic "0" | | | |
| | | 1 | 1 | 0 | Logic "1" | | | |
| | | 1 | 1 | 1 | Illegal Code | | | |
| | | Buffered version of D- single ended zero (/SI | and D+. Outputs a EO), error condition | re logic "0" and logs, and interconnec | gic "1." Used to detect sted speed. (Input to SIE). | | | |
| | | V _P | | V _M | RESULT | | | |
| V_P,V_M | 0 | 0 | | 0 | /SEO | | | |
| | | 0 | | 1 | Low Speed | | | |
| | | 1 | | 0 | Full Speed | | | |
| | | 0 | | 1 | Error | | | |
| D+, D- | AI/O | Data+, Data Differen | tial data bus confor | ming to the Univer | sal Serial Bus standard. | | | |
| SUSPND | 1 | Suspend . Enables a I suspend pin is active, STATE. | ow-power state whi it drives the RCV p | lle the USB bus is in to a logic "0" sta | inactive. While the tte. Both D+ and D- are 3- | | | |
| Speed | I | Edge Rate Control. Logic "1" operates at edge rates for "full speed." Logic "0" operates edge rates for "low speed." | | | | | | |
| Vcc | | 3.0 to 3.6 power supp | ly. | | | | | |
| GND | <u> </u> | Ground reference. | | | | | | |

Functional Truth Table

| | Input | | | I/ | O | | Outp | uts | | |
|---------------|---------------|-----------------------------------|-----|--------|---------|---------|--------------------|--------------------|--------------------|-----------------|
| Mode | V_{PO} | V _{MO} /F _{SEO} | /OE | SUSPND | D+ | D- | RCV | V _P | V _M | Result |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | Logic "0" |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | Undefined State | 0 | 0 | /SEO |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | Logic "1" |
| 0 | 1 | 1 | 0 | 0 | 0 | 0 | Undefined State | 0 | 0 | /SEO |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | Undefined State | 0 | 0 | /SEO |
| 1 | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | Logic "0" |
| 1 | 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | Logic "1" |
| 1 | 1 | 1 | 0 | 0 | 1 | 1 | Undefined State | Undefined State | Undefined State | Illegal Code |
| Don't Care | Don't Care | Don't Care | 1 | 0 | 3-State | 3-State | Undefined State | Undefined State | Undefined State | D+/D- Hi-Z |
| Don't Care | Don't Care | Don't Care | 1 | 1 | 3-State | 3-State | Undefined State | Undefined State | Undefined State | D+/D- Hi-Z |

Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Paramet | Parameter | | | |
|------------------------------------|---|--|-----------------------|-----------------------|------|
| V _{CC} | DC Supply Voltage | | 0.5 | 7.0 | V |
| I _{IK} | DC Input Diode Current, V _{IN} <0V | | | -50 | mA |
| V_{IN} | Input Voltage ⁽¹⁾ | 0.5 | 5.5 | V | |
| V _{I/O} | Input Voltage | 0.5 | V _{CC} + 0.5 | ٧ | |
| lok | Output Diode Current, Vo>Vcc or \ | | ±50 | mA | |
| Vo | Output Voltage | | 0.5 | V _{CC} + 0.5 | V |
| 1- | Output Source or Sink Current | V _P , V _M , RCV Pins | | ±15 | mA |
| lo | $(V_O = 0 \text{ to } V_{CC})$ | D+/D- Pins | | ±50 | IIIA |
| I _{CC} / I _{GND} | V _{CC} / GND Current | | | ±100 | mA |
| T _{STG} | Storage Temperature Range | | -60 | +150 | °C |

Note:

The input and output negative voltage ratings may be exceeded if the input and output diode current ratings are
observed.

Recommended Operating Conditions

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.

| Symbol | Parameter | Min. | Max. | Unit |
|-------------------|---|------|----------|------|
| Vcc | Power Supply Operating | 3.0 | 3.6 | V |
| V_{IN} | Input Voltage | 0 | 5.5 | V |
| V _{AI/O} | Input Range for AI/0 | 0 | V_{CC} | V |
| Vo | Output Voltage | 0 | V_{CC} | V |
| T _A | Operating Ambient Temperature, Free Air | -40 | +85 | °C |

DC Electrical Characteristics Digital Pins

Over recommended range of supply voltage and operating free air temperature unless otherwise noted. $V_{\rm CC}$ = 3.0V to 3.6V.

| Cumbal | Doromotor | Conditions | T _A =-40 to +85°C | | | l lusit a |
|-------------------|----------------------------|--|------------------------------|------|------|-----------|
| Symbol | Parameter | Conditions | Min. | Тур. | Max. | Units |
| Input Leve | ls | | | | | • |
| V _{IL} | Low-Level Input Voltage | | | | 0.8 | V |
| V _{IH} | High-Level Input Voltage | | 2 | | | V |
| Output Lev | rels | | | | | |
| | 1 10 10 11 11 | I _{OL} =4mA | | | 0.4 | V |
| V _{OL} | Low-Level Output Voltage | I _{OL} =20µA | | | 0.1 |] |
| | High Lavel Output Valtage | I _{OH} =4mA | 2.5 | | | V |
| V _{OH} | High-Level Output Voltage | I _{OH} =20μA | V _{CC} -0.1 | | | V |
| Leakage C | urrent | | | | | |
| I _{IN} | Input Leakage Current | V _{CC} =3.0 to 3.6 | | | ±5 | μΑ |
| I _{CCFS} | Supply Current, Full Speed | V _{CC} =3.0 to 3.6 | | | 5 | mA |
| I _{CCLS} | Supply Current, Low Speed | V _{CC} =3.0 to 3.6 | | | 5 | mA |
| Iccq | Quiescent Supply Current | V _{CC} =3.0 to 3.6, V _{IN} =V _{CC} or GND | | | 5 | mA |
| Iccs | Supply Current in Suspend | V _{CC} =3.0 to 3.6, Mode=V _{CC} | | 9 | 10 | μΑ |

DC Electrical Characteristics D+/D- Pins

Over recommended range of supply voltage and operating free air temperature unless otherwise noted. $V_{CC} = 3.0 V$ to 3.6 V.

| Symbol | Danamatan | 0 1141 | T _A = | | | |
|--------------------------------|--|---------------------------------|------------------|------|------|-------|
| | Parameter | Conditions | Min. | Тур. | Max. | Units |
| Input Leve | ls | | | | | |
| V_{DI} | Differential Input Sensitivity | (D+) - (D-) | 0.2 | | | V |
| V_{CM} | Differential Common-Mode Range | Includes V _{DI} Range | 0.8 | į. | 2.5 | V |
| V _{SE} | Single-Ended Receiver Threshold | | 0.8 | | 2.0 | V |
| Output Lev | vels | | | | | |
| V _{OL} | Static Output Low-Voltage | | | | 0.3 | V |
| V _{OH} | Static Output High-Voltage | R_L of $1.5k\Omega$ to $3.6V$ | 2.8 | | 3.6 | V |
| V_{CR} | Differential Crossover | R_L of $1.5k\Omega$ to GND | 1.3 | | 2.0 | V |
| Leakage C | urrent | | | 7 | | |
| l _{OZ} | High Z-State Data Line Leakage Current | 0V <v<sub>IN<3.3V</v<sub> | | | ±5 | μA |
| Capacitano | ce control of the con | | | | | |
| C _{IN} ⁽²⁾ | Transceiver Capacitance | Pin to GND | | | 10 | pF |
| C _{IN} , , | Capacitance Match | | | | 10 | % |
| Output Res | sistance | | | | • | |
| ¬ (3) | Driver Output Resistance | Steady-State Drive | 4 | | 20 | Ω |
| $Z_{DRV}^{(3)}$ | Resistance Match | | | | 10 | % |

Notes:

- 2. This specification is guaranteed by design and statistical process distribution.
- 3. Excludes external resistor. To comply with USB specification 1.1, external series resistors of 24W ±1% each on D+ and D- are recommended.

AC Electrical Characteristics D+/D- Pins, Full Speed

Over recommended range of supply voltage and operating free air temperature unless otherwise noted. V_{CC} = 3.0V to 3.6V, C_L = 50Pf; R_L = $k\Omega$ on D+ to V_{CC} .

| O. mala al | Doromotor | O a malitia ma | T _A = | 11 | | |
|-------------------------------------|--|---------------------------------|------------------|------|------|-------|
| Symbol | Parameter | Conditions | Min. | Тур. | Max. | Units |
| Driver Cha | racteristics | | | | | • |
| t _R , t _F | Rise and Fall Time | 10 and 90%, Figure 4 | 4 | | 20 | ns |
| t _{RFM} | Rise/Fall Time Matching | t _R / t _F | 90 | | 110 | % |
| V _{CRS} | Output Signal Crossover Voltage | | 1.3 | | 2.0 | V |
| Driver Time | ngs | | | | | |
| t _{PLH} | Driver Propagation Delay (V _{PO} ,V _{MO} /F _{SEO} to D+/D-) | Figure 4 | | | 18 | ns |
| t _{PHZ} , t _{PLZ} | Driver Disable Delay (/OE to D+/D-) | Figure 6 | | | 13 | ns |
| t _{PZH} , t _{PZL} | Driver Enable Delay (/OE to D+/D-) | Figure 6 | | | 17 | ns |
| Receiver T | imings | | | | | |
| t _{PLH} | Receiver Propagation Delay | Figure 5 | | | 16 | ns |
| t _{PHL} | D+/D- to RVC | Figure 5 | | | 19 | ns |
| t _{PLH} , t _{PHL} | Single-ended Receiver Delay (D+/D- to V _P , V _M) | Figure 5 | | | 8 | ns |

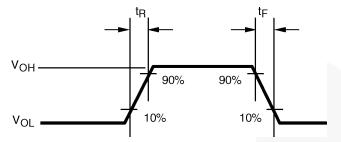
AC Electrical Characteristics D+/D- Pins, Low Speed

Over recommended range of supply voltage and operating free air temperature unless otherwise noted. V_{CC} = 3.0V to 3.6V, C_L = 200pF to 600pF; R_L = 1.5k Ω on D- to V_{CC} .

| Cumbal | Donomotor | Conditions | T _A = | 11 | | |
|-------------------------------------|--|---------------------------------|------------------|------|------|-------|
| Symbol | Parameter | Conditions | Min. | Тур. | Max. | Units |
| Driver Cha | racteristics | | | | | |
| t _{LR} , t _{LF} | Rise and Fall Time | 10 and 90%, Figure 4 | 75 | | 300 | ns |
| t _{RFM} | Rise/Fall Time Matching | t _R / t _F | 80 | | 120 | % |
| V _{CRS} | Output Signal Crossover Voltage | | 1.3 | | 2.0 | V |
| Driver Tim | ings | | | | | |
| t _{PLH} , t _{PHL} | Driver Propagation Delay (V _{PO} ,V _{MO} /F _{SEO} to D+/D-) | Figure 4 | | | 300 | ns |
| t _{PHZ} , t _{PLZ} | Driver Disable Delay (/OE to D+/D-) | Figure 6 | | | 13 | ns |
| t _{PZH} , t _{PZL} | Driver Enable Delay (/OE to D+/D-) | Figure 6 | | | 205 | ns |
| Receiver T | imings | | | | | D |
| t _{PLH} , t _{PHL} | Receiver Propagation Delay (D+/D- to RVC) | Figure 5 | | | 18 | ns |
| t _{PLH} , t _{PHL} | Single-ended Receiver Delay (D+/D- to V _P , V _M) | Figure 5 | | | 28 | ns |

AC Loadings and Waveforms

V_{OL} and V_{OH} are the typical output voltage drops that occur with the output load. V_{CC} never goes below 3.0V.



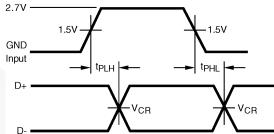
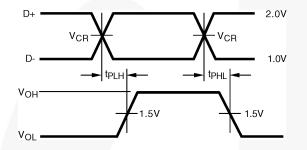


Figure 3. Rise and Fall Times

Figure 4. V_{PO}, V_{MO}/F_{SEO} to D+/D-



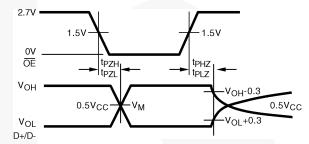


Figure 5. D+/D- to RCV, V_P/V_M

Figure 6. /OE to D+/D-

Test Circuits and Waveforms

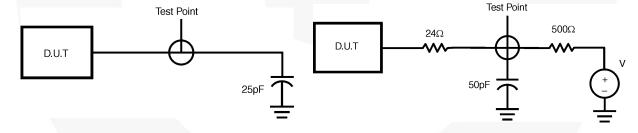
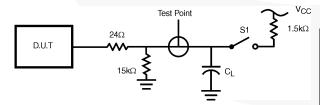


Figure 7. Load for V_M/V_P and RCV

Figure 8. Load for Enable and Disable Times



| Test | S1 |
|-------|-------|
| D-/LS | Close |
| D+/LS | Open |
| D-/FS | Open |
| D+/FS | Close |

C_L=50pF, Full Speed

C_L=200pF, Full Speed (Minimum Timing)

C_L=600pF, Full Speed (Maximum Timing)

 $1.5k\Omega$ on D-(Low Speed) or D+ (Full Speed) only.

Figure 9. Load for D+/D-

Physical Dimensions

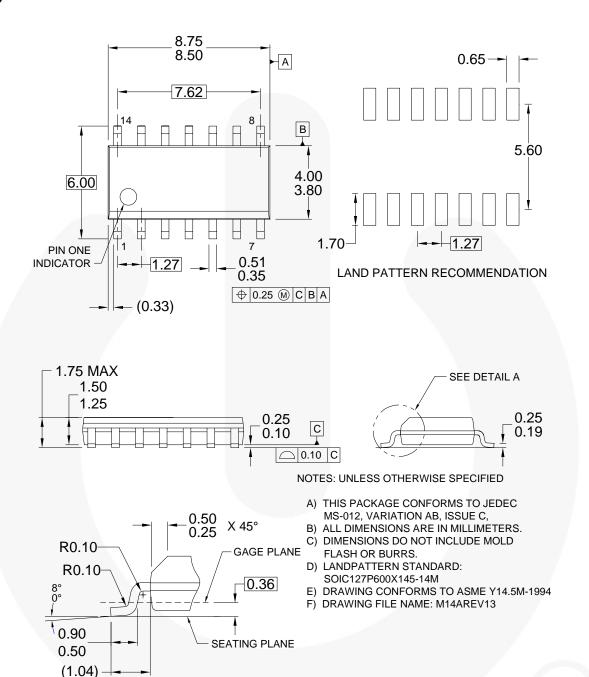


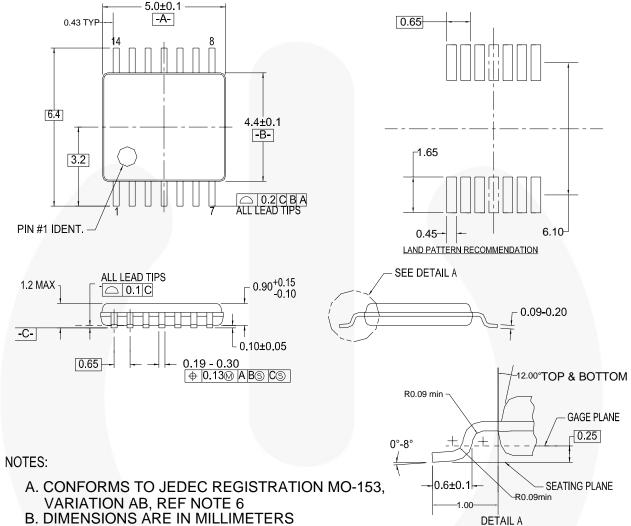
Figure 10. 14-Lead, Small Outline Integrated Circuit (SOIC) MO-012, 0.150-inch Wide

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Physical Dimensions



- C. DIMENSIONS ARE EXCLUSIVE OF BURRS, MOLD FLASH,
- AND TIE BAR EXTRUSIONS D. DIMENSIONING AND TOLERANCES PER ANSI
- Y14.5M, 1982
- E. LANDPATTERN STANDARD: SOP65P640X110-14M
- F. DRAWING FILE NAME: MTC14REV6

Figure 11. 14-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide

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