# High Voltage, High and Low Side Driver

The NCV5106 is a high voltage gate driver IC providing two outputs for direct drive of 2 N-channel power MOSFETs or IGBTs arranged in a half-bridge configuration version B (version B on demand only) or any other high-side + low-side configuration version A.

It uses the bootstrap technique to ensure a proper drive of the high–side power switch. The driver works with 2 independent inputs.

#### Features

- High Voltage Range: Up to 600 V
- dV/dt Immunity ±50 V/nsec
- Negative Current Injection Characterized Over the Temperature Range
- Gate Drive Supply Range from 10 V to 20 V
- High and Low Drive Outputs
- Output Source / Sink Current Capability 250 mA / 500 mA
- 3.3 V and 5 V Input Logic Compatible
- Up to V<sub>CC</sub> Swing on Input Pins
- Extended Allowable Negative Bridge Pin Voltage Swing to -10 V for Signal Propagation
- Matched Propagation Delays Between Both Channels
- Outputs in Phase with the Inputs
- Independent Logic Inputs to Accommodate All Topologies (Version A)
- Cross Conduction Protection with 100 ns Internal Fixed Dead Time (Version B on demand only)
- Under V<sub>CC</sub> LockOut (UVLO) for Both Channels
- Pin-to-Pin Compatible with Industry Standards
- These are Pb–Free Devices

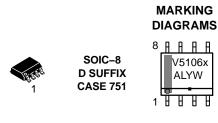
#### **Typical Applications**

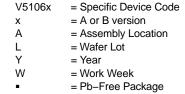
- Half-Bridge Power Converters
- Any Complementary Drive Converters (Asymmetrical Half–Bridge, Active Clamp) (A Version Only).
- Full-Bridge Converters



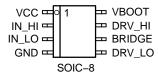
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#### **ORDERING INFORMATION**

See detailed ordering and shipping information on page 16 of this data sheet.

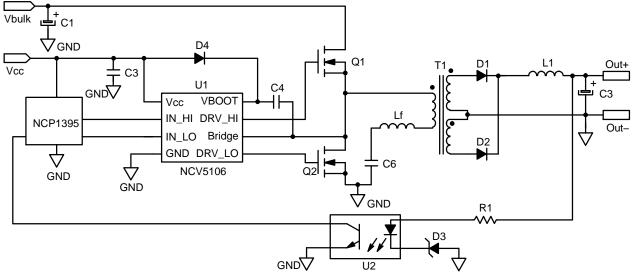


Figure 1. Typical Application Resonant Converter (LLC type)

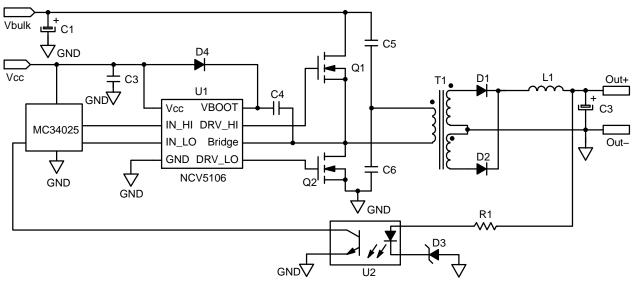


Figure 2. Typical Application Half Bridge Converter

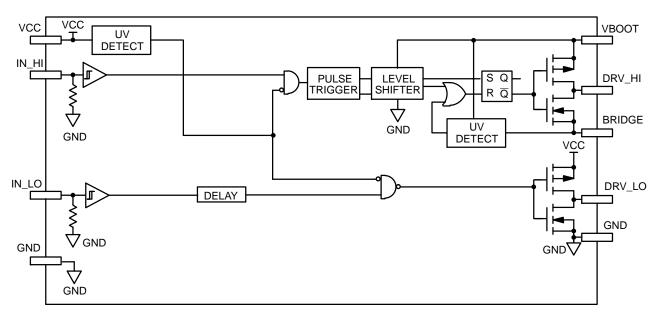


Figure 3. Detailed Block Diagram: Version A

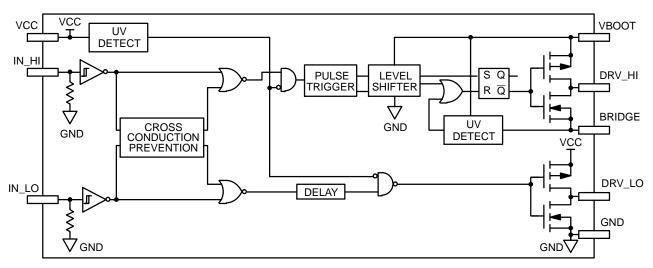


Figure 4. Detailed Block Diagram: Version B

Pin Name	Description		
IN_HI	Logic Input for High Side Driver Output in Phase		
IN_LO	Logic Input for Low Side Driver Output in Phase		
GND	Ground		
DRV_LO	Low Side Gate Drive Output		
V <sub>CC</sub>	Low Side and Main Power Supply		
V <sub>BOOT</sub>	Bootstrap Power Supply		
DRV_HI	High Side Gate Drive Output		
BRIDGE	Bootstrap Return or High Side Floating Supply Return		
NC	Removed for creepage distance (DFN package only)		

#### **PIN DESCRIPTION**

#### MAXIMUM RATINGS

Rating	Symbol	Value	Unit
V <sub>CC</sub>	Main power supply voltage	-0.3 to 20	V
V <sub>CC_transient</sub>	Main transient power supply voltage: IV <sub>CC_max</sub> = 5 mA during 10 ms	23	V
V <sub>BRIDGE</sub>	VHV: High Voltage BRIDGE pin	-1 to 600	V
V <sub>BRIDGE</sub>	Allowable Negative Bridge Pin Voltage for IN_LO Signal Propagation to DRV_LO (see characterization curves for detailed results)	-10	V
$V_{BOOT-}V_{BRIDGE}$	VHV: Floating supply voltage	-0.3 to 20	V
V <sub>DRV_HI</sub>	VHV: High side output voltage	V <sub>BRIDGE</sub> – 0.3 to V <sub>BOOT</sub> + 0.3	V
V <sub>DRV_LO</sub>	Low side output voltage	-0.3 to V <sub>CC</sub> + 0.3	V
dV <sub>BRIDGE</sub> /dt	Allowable output slew rate	50	V/ns
V <sub>IN_XX</sub>	Inputs IN_HI, IN_LO	-1.0 to V <sub>CC</sub> + 0.3	V
	ESD Capability: – HBM Model (all pins) – CDM Model	750 1000	V V
	Latch up capability per JEDEC JESD78		
$R_{ hetaJA}$	Power dissipation and Thermal characteristics SO–8: Thermal Resistance, Junction–to–Air	178	°C/W
T <sub>ST</sub>	Storage Temperature Range	-55 to +150	°C
T <sub>J_max</sub>	Maximum Operating Junction Temperature	+150	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

<b>ELECTRICAL CHARACTERISTIC</b> ( $V_{CC} = V_{boot} = 15 V$ , $V_{GND} = V_{bridge}$ , $-40^{\circ}C < T_J < 125^{\circ}C$ , Outputs loaded with 1 nF)
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		T <sub>J</sub> –40°C to 125°C			
Rating	Symbol	Min	Тур	Max	Units
OUTPUT SECTION					
Output high short circuit pulsed current V <sub>DRV</sub> = 0 V, PW $\leq$ 10 µs (Note 1)	I <sub>DRVsource</sub>	_	250	-	mA
Output low short circuit pulsed current V <sub>DRV</sub> = V <sub>CC</sub> , PW $\leq$ 10 µs (Note 1)	I <sub>DRVsink</sub>	_	500	-	mA
Output resistor (Typical value @ 25°C) Source	R <sub>OH</sub>	_	30	60	Ω
Output resistor (Typical value @ 25°C) Sink	R <sub>OL</sub>	_	10	20	Ω
High level output voltage, V <sub>BIAS</sub> –V <sub>DRV_XX</sub> @ I <sub>DRV_XX</sub> = 20 mA	V <sub>DRV_H</sub>	_	0.7	1.6	V
Low level output voltage V <sub>DRV_XX</sub> @ I <sub>DRV_XX</sub> = 20 mA	V <sub>DRV_L</sub>	_	0.2	0.6	V
DYNAMIC OUTPUT SECTION	1			•	
Turn-on propagation delay (Vbridge = 0 V)	t <sub>ON</sub>	-	100	170	ns
Turn–off propagation delay (Vbridge = 0 V or 50 V) (Note 2)	t <sub>OFF</sub>	_	100	170	ns
Output voltage rise time (from 10% to 90% @ V <sub>CC</sub> = 15 V) with 1 nF load	tr	_	85	160	ns
Output voltage fall time (from 90% to 10% $@V_{CC} = 15 \text{ V}$ ) with 1 nF load	tf	-	35	75	ns
Propagation delay matching between the High side and the Low side @ 25°C (Note 3)	Δt	-	20	35	ns
Internal fixed dead time (only valid for B version) (Note 4)	DT	65	100	190	ns
Minimum input width that changes the output	t <sub>PW1</sub>	_	-	50	ns
Maximum input width that does not change the output	t <sub>PW2</sub>	15	-	-	ns
INPUT SECTION					
Low level input voltage threshold	V <sub>IN</sub>	-	-	0.8	V
Input pull–down resistor (V <sub>IN</sub> < 0.5 V)	R <sub>IN</sub>	-	200	-	kΩ
High level input voltage threshold	V <sub>IN</sub>	2.3	-	-	V
Logic "1" input bias current @ $V_{IN_XX} = 5 V$ @ $25^{\circ}C$	I <sub>IN+</sub>	_	5	25	μΑ
Logic "0" input bias current @ V <sub>IN_XX</sub> = 0 V @ 25°C	I <sub>IN-</sub>	-	-	2.0	μΑ
SUPPLY SECTION	· · · · · ·				
V <sub>CC</sub> UV Start-up voltage threshold	V <sub>CC</sub> _stup	8.0	8.9	9.9	V
V <sub>CC</sub> UV Shut–down voltage threshold	V <sub>CC</sub> _shtdwn	7.3	8.2	9.1	V
Hysteresis on V <sub>CC</sub>	V <sub>CC</sub> _hyst	0.3	0.7	-	V
Vboot Start–up voltage threshold reference to bridge pin (Vboot_stup = Vboot – Vbridge)	Vboot_stup	8.0	8.9	9.9	V
Vboot UV Shut-down voltage threshold	Vboot_shtdwn	7.3	8.2	9.1	V
Hysteresis on Vboot	Vboot_shtdwn	0.3	0.7	-	V
Leakage current on high voltage pins to GND (V <sub>BOOT</sub> = V <sub>BRIDGE</sub> = DRV_HI = 600 V)	I <sub>HV_LEAK</sub>	_	5	40	μΑ
Consumption in active mode ( $V_{CC}$ = Vboot, fsw = 100 kHz and 1 nF load on both driver outputs)	ICC1	-	4	5	mA
Consumption in inhibition mode (V <sub>CC</sub> = Vboot)	ICC2	-	250	400	μΑ
V <sub>CC</sub> current consumption in inhibition mode	ICC3	_	200	_	μA
Vboot current consumption in inhibition mode	ICC4	_	50	_	μA

Parameter guaranteed by design.
Turn–off propagation delay @ Vbridge = 600 V is guaranteed by design.
See characterization curve for Δt parameters variation on the full range temperature.

4. Version B integrates a dead time in order to prevent any cross conduction between DRV\_HI and DRV\_LO. See timing diagram of Figure 10.

 Timing diagram definition see: Figure 7, Figure 8 and Figure 9.
Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

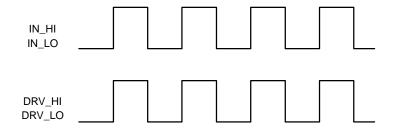


Figure 5. Input/Output Timing Diagram (A Version)

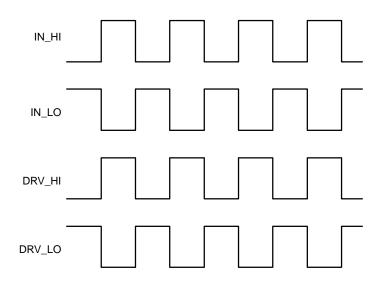


Figure 6. Input/Output Timing Diagram (B Version)

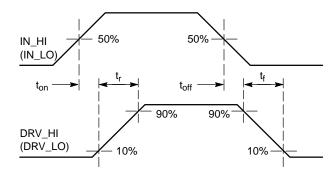
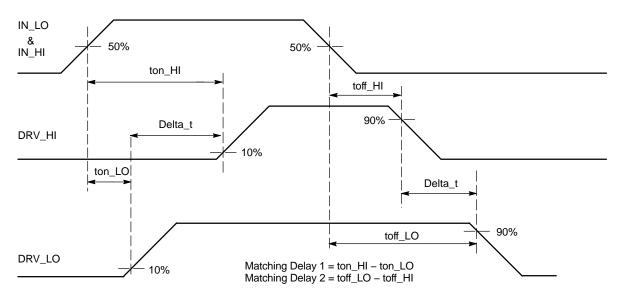
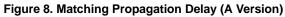
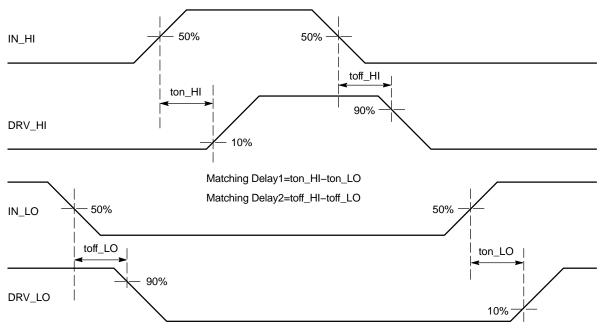


Figure 7. Propagation Delay and Rise / Fall Time Definition









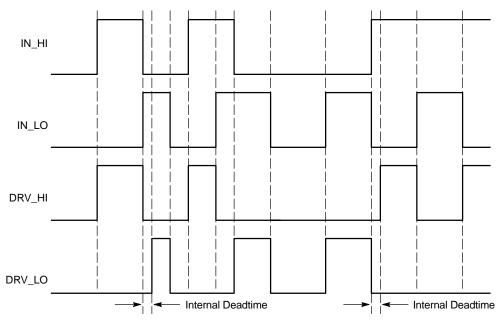
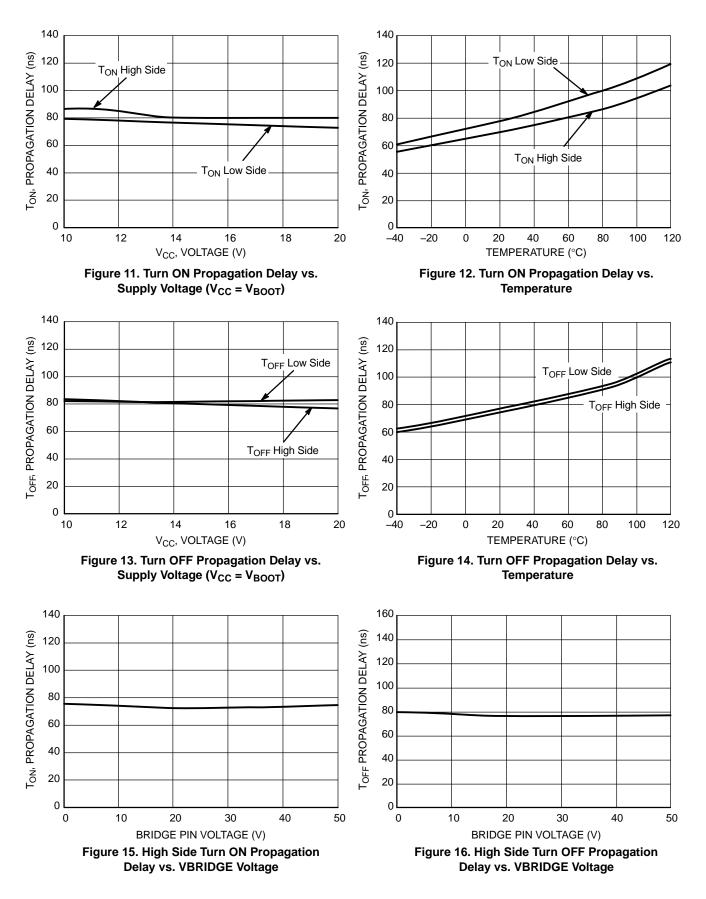
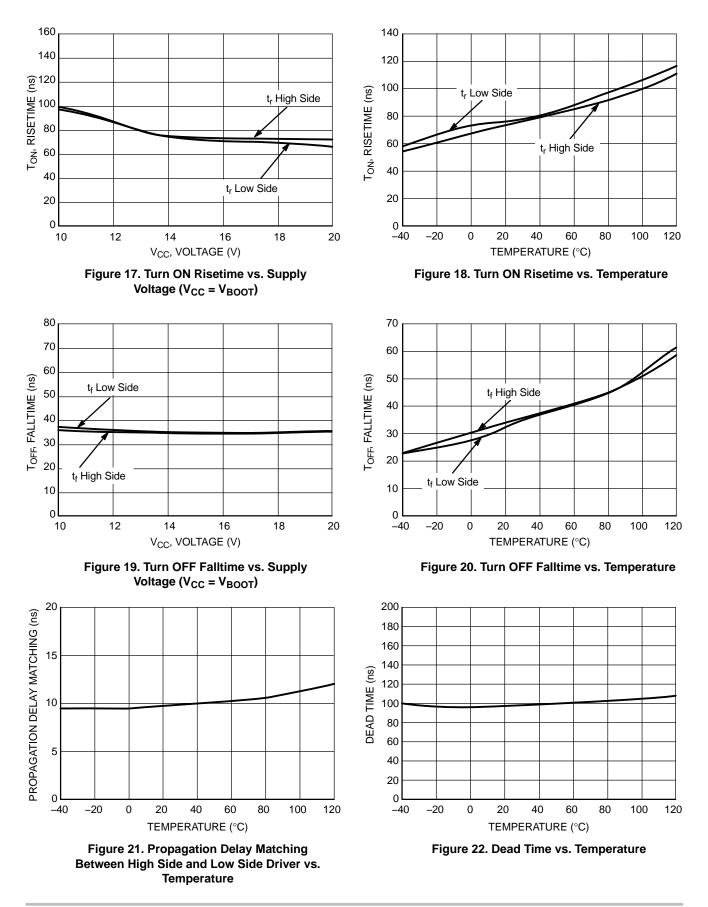
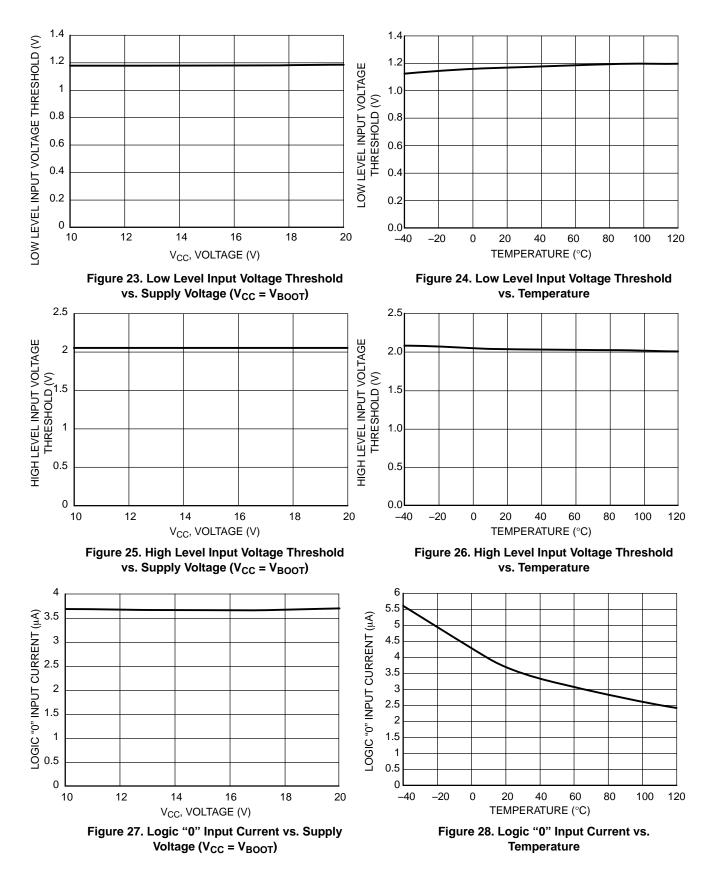
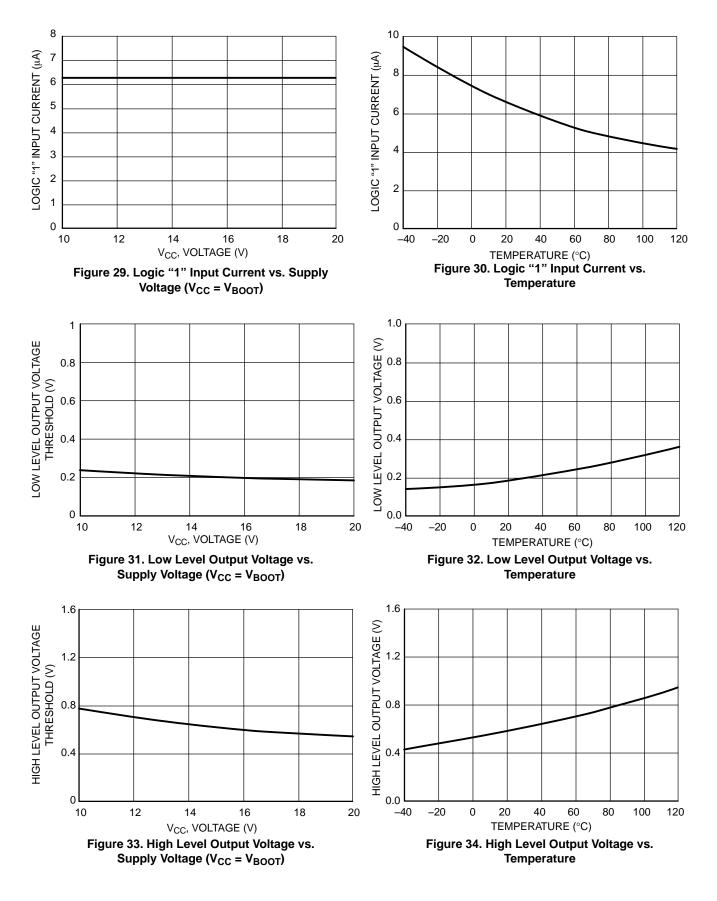


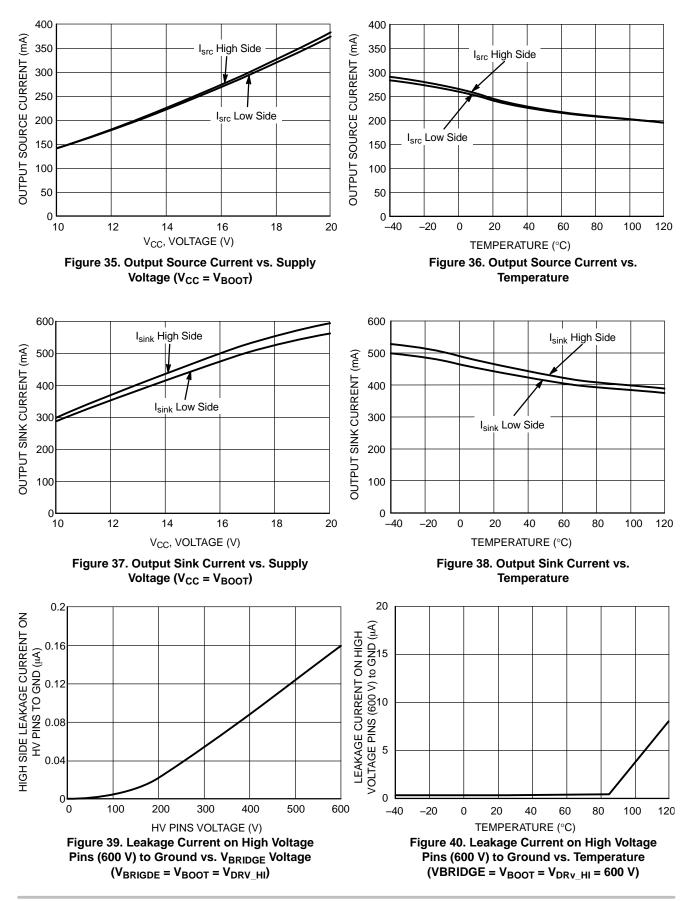
Figure 10. Input/Output Cross Conduction Output Protection Timing Diagram (B Version)

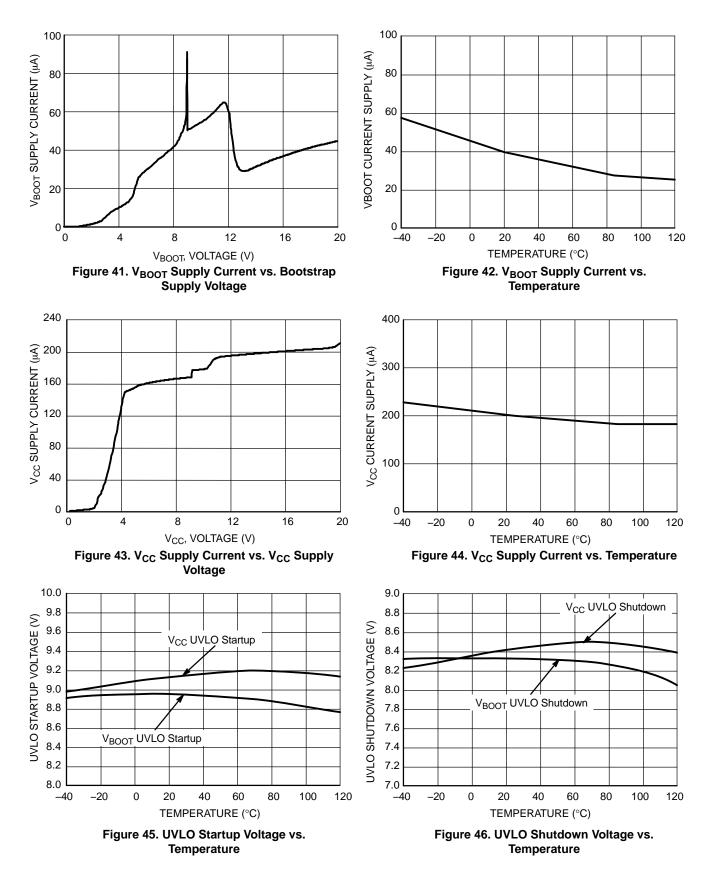


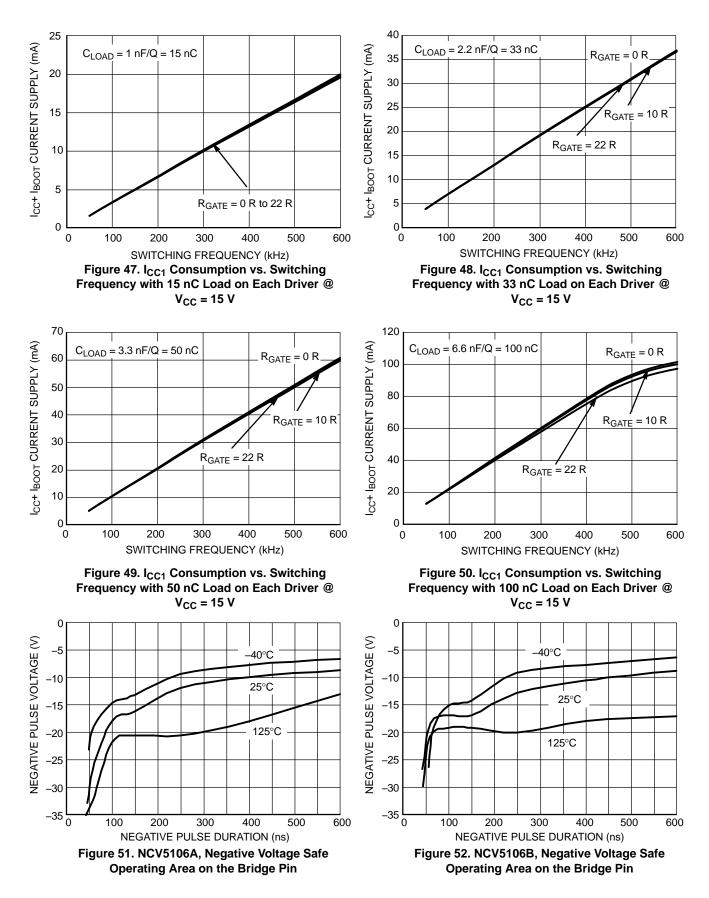












#### **APPLICATION INFORMATION**

#### Negative Voltage Safe Operating Area

When the driver is used in a half bridge configuration, it is possible to see negative voltage appearing on the bridge pin (pin 6) during the power MOSFETs transitions. When the high-side MOSFET is switched off, the body diode of the low-side MOSFET starts to conduct. The negative voltage applied to the bridge pin thus corresponds to the forward voltage of the body diode. However, as pcb copper tracks and wire bonding introduce stray elements (inductance and capacitor), the maximum negative voltage of the bridge pin will combine the forward voltage and the oscillations created by the parasitic elements. As any CMOS device, the deep negative voltage of a selected pin can inject carriers into the substrate, leading to an erratic behavior of the concerned component. ON Semiconductor provides characterization data of its half-bridge driver to show the maximum negative voltage the driver can safely operate with. To prevent the negative injection, it is the designer duty to verify that the amount of negative voltage pertinent to his/her application does not exceed the characterization curve we provide, including some safety margin.

In order to estimate the maximum negative voltage accepted by the driver, this parameter has been characterized over full the temperature range of the component. A test fixture has been developed in which we purposely negatively bias the bridge pin during the freewheel period of a buck converter. When the upper gate voltage shows signs of an erratic behavior, we consider the limit has been reached.

Figure 51 (or 52), illustrates the negative voltage safe operating area. Its interpretation is as follows: assume a negative 10 V pulse featuring a 100 ns width is applied on the bridge pin, the driver will work correctly over the whole die temperature range. Should the pulse swing to -20 V, keeping the same width of 100 ns, the driver will not work properly or will be damaged for temperatures below  $125^{\circ}$ C.

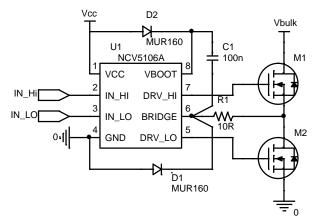
#### **ORDERING INFORMATION**

Summary:

- If the negative pulse characteristic (negative voltage level & pulse width) is above the curves the driver runs in safe operating area.
- If the negative pulse characteristic (negative voltage level & pulse width) is below one or all curves the driver will NOT run in safe operating area.

Note, each curve of the Figure 51 (or 52) represents the negative voltage and width level where the driver starts to fail at the corresponding die temperature.

If in the application the bridge pin is too close of the safe operating limit, it is possible to limit the negative voltage to the bridge pin by inserting one resistor and one diode as follows:



## Figure 53. R1 and D1 Improves the Robustness of the Driver

R1 and D1 should be placed as close as possible of the driver. D1 should be connected directly between the bridge pin (pin 6) and the ground pin (pin 4). By this way the negative voltage applied to the bridge pin will be limited by D1 and R1 and will prevent any wrong behavior.

Device	Package	Shipping <sup>†</sup>
NCV5106ADR2G	SOIC-8 (Pb-Free)	2500 / Tape & Reel
NCV5106BDR2G (On demand only, not released in production)	SOIC-8 (Pb-Free)	2500 / Tape & Reel

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.





\*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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STYLE 3: PIN 1. DRAIN, DIE #1 DRAIN, #1 2. DRAIN, #2 З. 4. DRAIN, #2 GATE, #2 5. SOURCE, #2 6. 7 GATE #1 8. SOURCE, #1 STYLE 7: PIN 1. INPUT 2. EXTERNAL BYPASS THIRD STAGE SOURCE GROUND З. 4. 5. DRAIN 6. GATE 3 SECOND STAGE Vd 7. FIRST STAGE Vd 8. STYLE 11: PIN 1. SOURCE 1 GATE 1 SOURCE 2 2. 3. GATE 2 4. 5. DRAIN 2 6. DRAIN 2 DRAIN 1 7. 8. DRAIN 1 STYLE 15: PIN 1. ANODE 1 2. ANODE 1 ANODE 1 3 ANODE 1 4. 5. CATHODE, COMMON CATHODE, COMMON CATHODE, COMMON 6. 7. CATHODE, COMMON 8. STYLE 19: PIN 1. SOURCE 1 GATE 1 SOURCE 2 2. 3. GATE 2 4. 5. DRAIN 2 6. MIRROR 2 DRAIN 1 7. 8. **MIRROR 1** STYLE 23: PIN 1. LINE 1 IN COMMON ANODE/GND COMMON ANODE/GND 2. 3 LINE 2 IN 4. LINE 2 OUT 5. COMMON ANODE/GND COMMON ANODE/GND 6. 7. LINE 1 OUT 8. STYLE 27: PIN 1. ILIMIT 2 OVI 0 UVLO З. 4. INPUT+ 5. SOURCE SOURCE 6. SOURCE 7. 8 DRAIN

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