# Accessories

# Couplings

# **Coupling Materials and Characteristics**

OMRON provides two types of couplings for different application conditions: Resin and metal. Select the best type for the application.

As a general rule, use metal couplings for high resolution and resin couplings for low resolution. (As a rough guide, a high resolution is one that exceeds 3,600 ppr.)

Even for applications requiring relatively low resolution, a metal coupling will provide more reliability in applications involving rapid acceleration/deceleration or for Encoders with high starting torque.

### **Comparison of Specifications for 6-mm Shafts**

Material Machine specification	Resin (standard type)	Metal (aluminum, helical)
Eccentricity (mm)	0.5	0.25
Eccentricity (degrees)	5	5
Deviation in shaft direction (mm)	±0.4	±0.25
Allowable torque (N·m)	0.8	1
Torsion rigidity (Nm/rad)	16	8.2
Moment of inertia (kg·m²)	1.2 × 10 <sup>-7</sup>	7 × 10 <sup>-7</sup>
Weight (g)	4	13

Note: Note: The above specifications are for the coupling by itself. When the coupling is used together with a Rotary Encoder, allow for the precautions for all Rotary Encoders and for the specifications of the Encoder.

### Characteristics

Material	Advantages	Disadvantages
Resin (standard type)	<ul> <li>Low cost.</li> <li>Easy shaft alignment when mounting.</li> <li>Lightweight and low moment of inertia, placing a smaller load on the drive system.</li> </ul>	<ul> <li>Low torsion rigidity and thus not suitable for high resolution.</li> <li>Mounting is possible even if the shafts are greatly misaligned, which can cause damage from fatigue over long periods of application.</li> </ul>
Metal (aluminum, helical)	<ul> <li>High torsion rigidity and thus suitable for high resolution.</li> <li>Transmitted allowable torque is large.</li> </ul>	<ul> <li>High cost.</li> <li>Heavy and thus place a large load on the drive system.</li> <li>The allowable shaft misalignment is small, so accurate positioning is required when mounting.</li> </ul>

### **Coupling Suitability Table**

O: Suitable and provided with product,  $\Delta$ : Suitable and sold separately, ---: Not suitable.

Couplings	Specification		Resin, standard type diffe				Re different e	Resin, different end diameter		Metal	
	Shaft interior (tolerance *) exterior dia.	2 dia. (Height: 8), 9 dia.	4 dia. (Height: 8), 13 dia.	6 dia. (Height: 8), 15 dia.	8 dia. (Height: 8), 19 dia.	10 dia. (Height: 8), 22 dia.	6 dia., 8 dia., (Height: 8), 19 dia.	6 dia., 10 dia., (Height: 8), 22 dia.	6 dia. (Height: 8), 19.1 dia.	10 dia. (Height: 8), 25.4 dia.	
Rotary Encoder Model/shaft dia.	Model	E69-C02B	E69-C04B	E69-C06B	E69-C08B	E69-C10B	E69-C68B	E69-C610B	E69-C06M	E69-C10M	
E6A2-C 4 dia.			0								
E6B2-C 6 dia.				0			Δ	Δ	Δ		
E6C2-C 6 dia.				Δ			Δ	Δ	Δ		
E6C3-C 8 dia.					Δ		Δ				
E6D-C 6 dia.				0			Δ	Δ	Δ		
E6F-C 10 dia.						Δ		Δ		Δ	
E6H-C Hollow shaft inter	ior dia.: 8 mm	Hollow-shaft Model; Coupling not required.									
E6J-C 2 dia.		0									
E6CP-A 6 dia.				○ Sold separately only for E6CP- AG5C-C.			Δ	Δ	Δ		
E6C3-A 8 dia.					Δ		Δ				
E6F-A 10 dia.						O Only Pre-wired Models		Δ		Δ	
E6J-A 4 dia.			0								

\*Tolerance conforms to JIS standard: JIS B 0401.  $\rightarrow$  Refer to page 2.

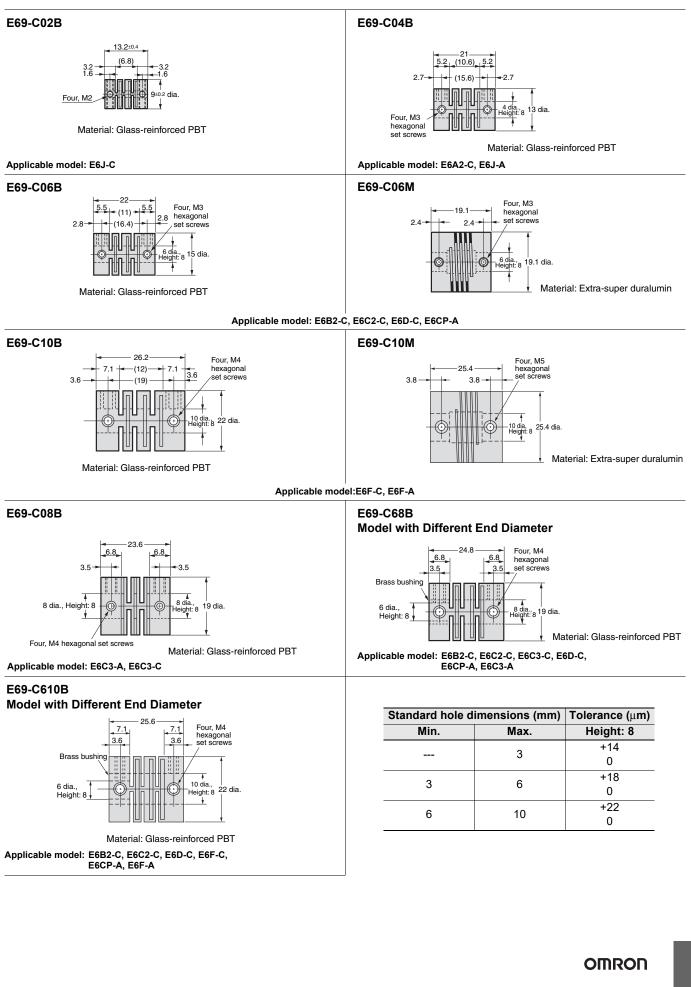
# **Rotary Encoders**

(Unit: mm)

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## Coupling Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.



# **Flanges and Servo Mounting Brackets**

Flange and Servo Mounting Bracket Suitability Table

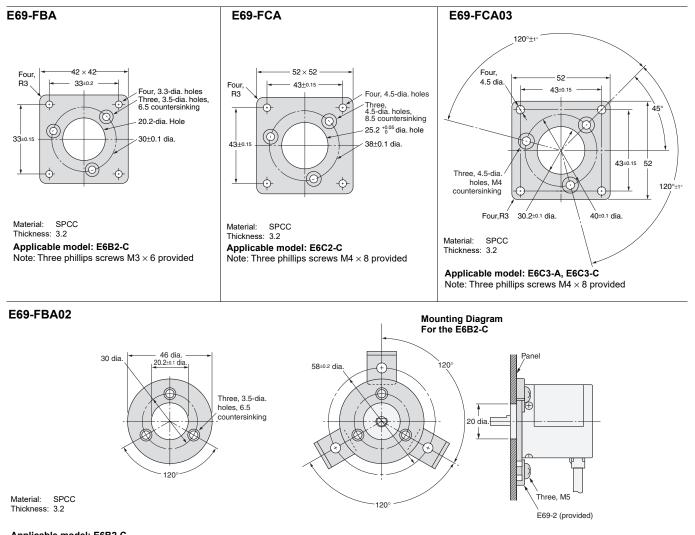
O: Suitable and provided with product,  $\Delta$ : Suitable and sold separately, ---: Not suitable.

Rotary	Туре	Flange							Servo Mounting Bracket	
Encoder Model		E69-FBA	E69-FCA	E69-FCA03	E69-FBA02	E69-FCA02	E69-FCA04	E69-1	E69-2	
Model	Remarks	E09-FBA	E05-FCA	E09-FCA05	E69-2 Servo	Mounting Brac	200-1			
E6A2-C								O Provided with the E6A2-CWZ.		
E6B2-C		Δ			Δ				Δ	
E6C2-C			Δ			Δ			Δ	
E6C3-C				Δ			Δ		Δ	
E6D-C									0	
E6F-C									Δ	
E6H-C		Hollow-shaft Model; Flange not required.								
E6CP-A									0	
E6C3-A				Δ			Δ		Δ	
E6F-A									0	

# **Flange Dimensions**

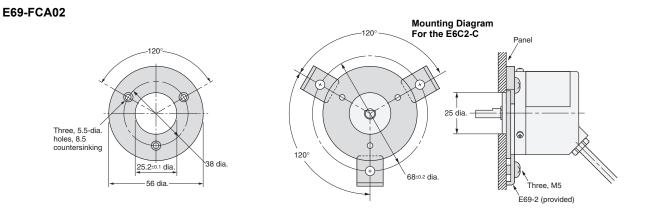
(Unit: mm)

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.



Applicable model: E6B2-C Note: Three phillips screws M3  $\times$  10 provided, E69-2 Servo Mounting Bracket provided

# **Rotary Encoders**

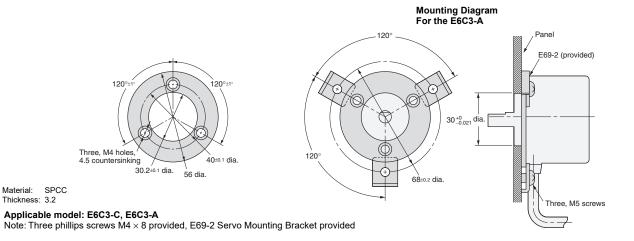


Material: SPCC Thickness: 3.2

Applicable model: E6C2-C

Note: Three phillips screws M4  $\times$  10 provided, E69-2 Servo Mounting Bracket provided

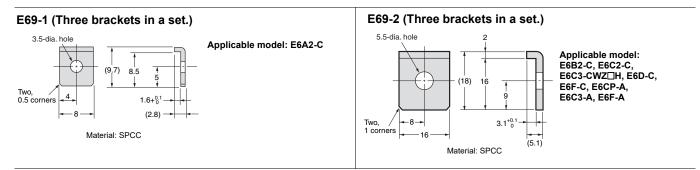
# E69-FCA04



### **Servo Mounting Bracket Dimensions**

(Unit: mm)

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.



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