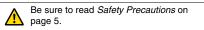
Low-cost Encoder with Diameter of 50 mm

E6CP-A

General-purpose Absolute Encoder with External Diameter of 50 mm

- Absolute model.
- External diameter of 50 mm.
- Resolution: 256 (8-bit).
- Lightweight construction using plastic body.





Ordering Information

Encoders [Refer to Dimensions on page 5.]

Power supply voltage	Output configuration	Resolution (divisions)	Connector for H8PS Cam Positioner	Model
5 to 12 VDC	Open-collector output		None	E6CP-AG3C 256P/R 2M
12 to 24 VDC		256 (8-bit)		E6CP-AG5C 256P/R 2M
12 10 24 VDC			Supported	E6CP-AG5C-C 256P/R 2M

Note: When connecting to the H8PS, use the E6CP-AG5C-C, which is connected using a connector. It cannot be used on other models.

Accessories (Order Separately)

[Dimensions: Refer to Accessories for coupling dimensions and to page 5 for the dimensions of other accessories.]

Name	Model		Remarks	
Couplings	E69-C06B	Provided w	Provided with the E6CP-AG3C and E6CP-AG5C.	
	E69-C68B	Different er	Different end diameter	
	E69-C610B	Different er	Different end diameter	
	E69-C06M	Metal cons	Metal construction	
Servo Mounting Bracket	E69-2	Provided with the product. (Three brackets in a set.)		
Extension Cable	E69-DF5	5 m		
	E69-DF10	10 m	Models are also available with 15-m and 98-m cables.	
	E69-DF20	20 m]	

Refer to Accessories for details.

E6CP-A

Ratings and Specifications

ltem	Model	E6CP-AG3C	E6CP-AG5C	E6CP-AG5C-C		
Power sup	ply voltage	5 VDC -5% to 12 VDC +10%, ripple (p-p): 5% max.	12 VDC -10% to 24 VDC -	15%, ripple (p-p): 5% max.		
Current consumption*1		90 mA max. 70 mA max.				
Resolution (rotations)		256 (8-bit)				
Output co	de	Gray code				
Output co	nfiguration	Open-collector output				
Output capacity		Applied voltage: 28 VDC max. Sink current: 16 mA max. Residual voltage: 0.4 V max. (at sink current of 16 mA)				
Maximum frequency		5 kHz				
Logic		Negative logic (high = 0, low = 1)				
Accuracy ±1° max.						
Direction	irection of rotation Output code incremented by CW (as viewed from the end of the shaft)					
Rise and f output	all times of	es of 1 μ s max. (Control output voltage: 16 V, Load resistance: 1 k Ω , Output cable: 2 m max.)		ax.)		
Starting torque 0.98 mN·m max.						
Moment of inertia		$1 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.}$				
Shaft	Radial	30 N				
oading	Thrust	20 N				
Maximum speed	permissible	1,000 r/min				
Ambient temperature (Operating: -10 to 55°C (with no icing), Storage: -25 to 85°C (with no icing)				
Ambient humidity range Operating/Storage: 35% to 85% (with no conde		Operating/Storage: 35% to 85% (with no condensation))			
nsulation	ulation resistance 20 MΩ min. (at 500 VDC) between current-carrying parts and case					
Dielectric	electric strength 500 VAC, 50/60 Hz for 1 min between current-carrying parts and case					
Vibration	resistance	ce Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions		irections		
Shock res	Destruction: 1,000 m/s ² 3 times each in X, Y, and Z directions					
Degree of protection*3 IEC 60529 IP50						
Connection method		Pre-wired Models (Standard cable length: 2 m)		Connector Models (Stan- dard cable length: 2 m)		
Material C		Case: ABS, Main unit: PPS, Shaft: SUS416, Mounting Bracket: Galvanized iron				
Weight (pa	acked state)	Approx. 200 g				
Accessori		Coupling (excluding Connector Models), Servo Mountir	a Bracket Instruction manua	I		

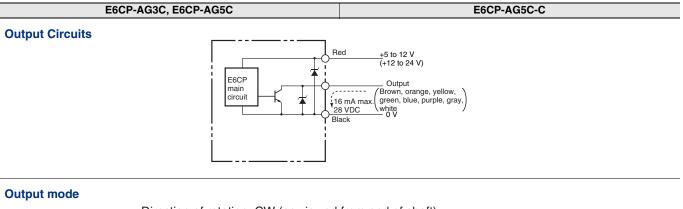
*1. An inrush current of approximately 8 A will flow for approximately 0.3 ms when the power is turned ON.
 *2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum response frequency Maximum electrical response speed (rpm) = -- × 60 Resolution

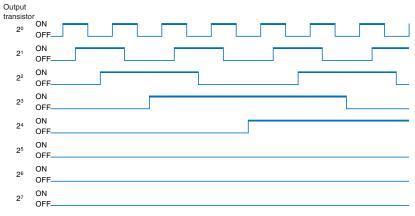
This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

E6CP-A

I/O Circuit Diagrams



Direction of rotation: CW (as viewed from end of shaft)



Address 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28

Connection

Color	E6CP-AG3C	E6CP-AG5C	
Red	Power supply 5 to 12 VDC	Power supply 12 to 24 VDC	
Black	0 V (co	mmon)	
Brown	Output 2 ⁰		
Orange	Output 2 ¹		
Yellow	Output 2 ²		
Green	Output 2 ³		
Blue	Output 2 ⁴		
Purple	Output 2 ⁵		
Gray	Output 2 ⁶		
White	Output 2 ⁷		

Note: The circuit is the same for all bit outputs. Each E6CP Rotary Encoder has one main circuit.

Terminal No.	E6CP-AG5C-C	
1	Connected internally	
2	Connected internally	
3	Output 2 ⁵	
4	Output 2 ¹	
5	Output 2 ⁰	
6	Output 2 ⁷	
7	Output 2 ⁴	
8	Output 2 ²	
9	Output 2 ³	
10	Output 2 ⁶	
11		
12	Power supply: 12 to 24 VDC	
13	0 V (common)	

Each E6CP Rotary Encoder has one main circuit.

Positioner Connection Example

H8PS Cam Positioner Connection



Note: The E6CP-AG5C cannot be connected to the H8PS.

Ordering Information

Model
H8PS-8A
H8PS-8AP
H8PS-8AF
H8PS-8AFP
H8PS-16A
H8PS-16AP
H8PS-16AF
H8PS-16AFP
H8PS-32A
H8PS-32AP
H8PS-32AF
H8PS-32AFP

Specifications

Rated voltage	24 VDC	
Cam precision	0.5° (for 720 resolution), 1° (for 256/360 resolution)	
No. of output points	8-point output type: 8 cam outputs, 1 RUN output, 1 pulse output 16-point output type: 16 cam outputs, 1 RUN output, 1 pulse output 32-point output type: 32 cam outputs, 1 RUN output, 1 pulse output	
Encoder response	RUN mode, test mode: 256/360 resolution 1,600 r/min max. (1,200 r/min when advance compensation is set for four cams or more) 720 resolution 800 r/min max. (600 r/min when advance compensation is set for four cams or more)	
Additional functions	 Origin compensation (zeroing) Rotation direction switching Angle display switching Teaching Pulse output Angle/number of rotations display switching Puncture * Angle advance Number of rotations alarm output Setting with support software (order separately) * 	

Note: For 16-point and 32-point output types only

Programmable Controller Connection

Connection is possible with the CQM1H-CPU51 and CQM1H-ABB21.

Refer to the CQM1H Programmable Controller Catalog (P050) for details on the CQM1H Programmable Controller.

Safety Precautions

Refer to Warranty and Limitations of Liability.

<u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Mounting

For front-surface mounting, the maximum tightening torque is 1.76 N·m. (Effective screw length: 7 mm min.)

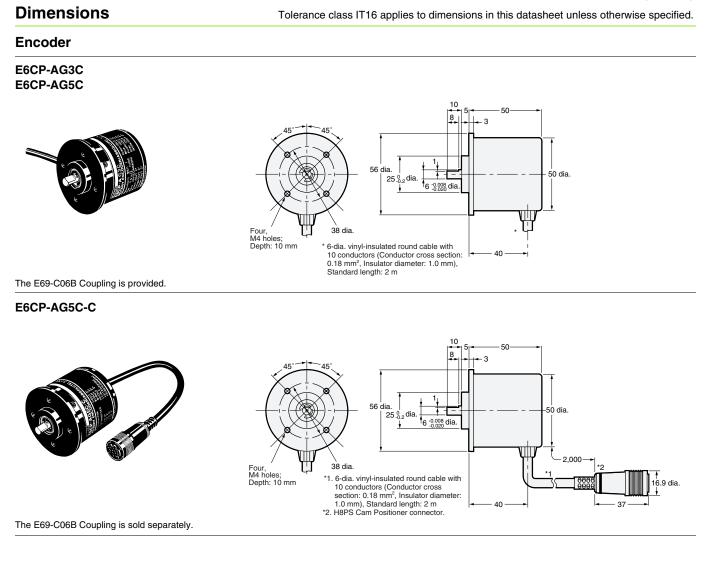
Wiring

Spurious pulses may be generated for outputs when power is turned ON. Wait at least 1 s after turning ON the power to the Encoder before using the connected device.

Connection

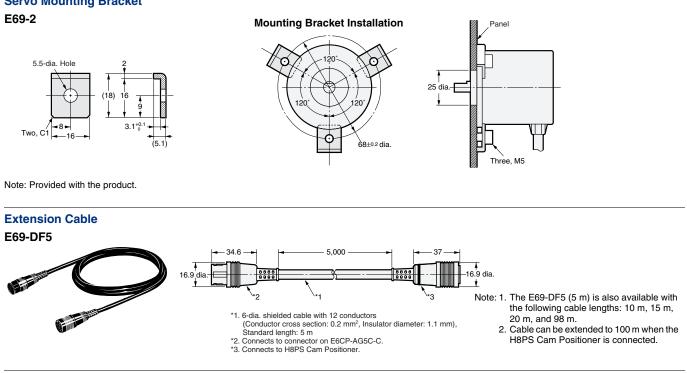
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)



Accessories (Order Separately)

Servo Mounting Bracket



Couplings

E69-C06B E69-C68B E69-C610B E69-C06M Refer to *Accessories* for details.

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