

UJA1167A

Mini high-speed CAN system basis chip with Standby/Sleep modes & watchdog

Rev. 1 — 23 August 2019

Product data sheet

1. General description

The UJA1167A is a mini high-speed CAN System Basis Chip (SBC) containing an ISO 11898-2:2016 and SAE J2284-1 to SAE J2284-5 compliant HS-CAN transceiver and an integrated 5 V/100 mA supply for a microcontroller. It also features a watchdog and a Serial Peripheral Interface (SPI). The UJA1167A can be operated in very-low-current Standby and Sleep modes with bus and local wake-up capability and supports ISO 11898-2:2016 compliant autonomous CAN biasing. The microcontroller supply is switched off in Sleep mode.

The UJA1167ATK variant contains a battery-related high-voltage output (INH) for controlling an external voltage regulator, while the UJA1167ATK/X is equipped with a 5 V sensor supply (VEXT).

This implementation enables reliable communication in the CAN FD fast phase at data rates up to 5 Mbit/s.

A number of configuration settings are stored in non-volatile memory, allowing the SBC to be adapted for use in a specific application. This makes it possible to configure the power-on behavior of the UJA1167A to meet the requirements of different applications.

2. Features and benefits

2.1 General

- ISO 11898-2:2016 and SAE J2284-1 to SAE J2284-5 compliant high-speed CAN transceiver
- Hardware and software compatible with the UJA116x product family and with improved EMC performance
- Loop delay symmetry timing enables reliable communication at data rates up to 5 Mbit/s in the CAN FD fast phase
- Autonomous bus biasing according to ISO 11898-6
- Fully integrated 5 V/100 mA low-drop voltage regulator for 5 V microcontroller supply (V1)
- Bus connections are truly floating when power to pin BAT is off

2.2 Designed for automotive applications

- ± 8 kV ElectroStatic Discharge (ESD) protection, according to the Human Body Model (HBM) on the CAN bus pins
- ± 6 kV ESD protection, according to IEC TS 62228 on the CAN bus pins, the sensor supply output VEXT and on pins BAT and WAKE



- CAN bus pins short-circuit proof to ± 58 V
- Battery and CAN bus pins protected against automotive transients according to ISO 7637-3
- Very low quiescent current in Standby and Sleep modes with full wake-up capability
- Leadless HVSON14 package (3.0 mm \times 4.5 mm) with improved Automated Optical Inspection (AOI) capability and low thermal resistance
- Dark green product (halogen free and Restriction of Hazardous Substances (RoHS) compliant)

2.3 Low-drop voltage regulator for 5 V microcontroller supply (V1)

- 5 V nominal output; ± 2 % accuracy
- 100 mA output current capability
- Current limiting above 150 mA
- On-resistance of 5 Ω (max)
- Support for microcontroller RAM retention down to a battery voltage of 2 V
- Undervoltage reset with selectable detection thresholds: 60 %, 70 %, 80 % or 90 % of output voltage
- Excellent transient response with a 4.7 μ F ceramic output capacitor
- Short-circuit to GND/overload protection on pin V1
- Turned off in Sleep mode

2.4 Power Management

- Standby mode featuring very low supply current; voltage V1 remains active to maintain the supply to the microcontroller
- Sleep mode featuring very low supply current with voltage V1 switched off
- Remote wake-up capability via standard CAN wake-up pattern
- Local wake-up via the WAKE pin
- Wake-up source recognition
- Local and/or remote wake-up can be disabled to reduce current consumption
- High-voltage output (INH) for controlling an external voltage (UJA1167ATK)

2.5 System control and diagnostic features

- Mode control via the Serial Peripheral Interface (SPI)
- Overtemperature warning and shutdown
- Watchdog with independent clock source
- Watchdog can be operated in Window, Timeout and Autonomous modes
- Optional cyclic wake-up in watchdog Timeout mode
- Watchdog automatically re-enabled when wake-up event captured
- Watchdog period selectable between 8 ms and 4 s
- Supports remote flash programming via the CAN bus
- 16-, 24- and 32-bit SPI for configuration, control and diagnosis
- Bidirectional reset pin with variable power-on reset length to support a variety of microcontrollers
- Configuration of selected functions via non-volatile memory

2.6 Sensor supply voltage (pin VEXT of UJA1167ATK/X)

- 5 V nominal output; ± 2 % accuracy
- 30 mA output current capability
- Current limiting above 30 mA
- Excellent transient response with a 4.7 μ F ceramic output load capacitor
- Protected against short-circuits to GND and to the battery
- High ESD robustness of ± 6 kV according to IEC TS 62228
- Can handle negative voltages as low as -18 V

3. Product family overview

Table 1. Feature overview of UJA1167A SBC family

| Device | Modes | | | Supplies | | | Host Interface | | Additional Features | | |
|--------------|------------------------|------------|------------|--------------------------|---------------------------|--------------------------|--------------------------------|-----------------|---------------------|----------------|---------------------|
| | Normal & Standby modes | Sleep mode | Reset mode | V1: 5 V, μ C and CAN | VEXT: 5 V, external loads | INH: high-voltage output | SPI: for control & diagnostics | RSTN: reset pin | Watchdog | Local WAKE pin | Non-volatile memory |
| UJA1167ATK | • | • | • | • | | • | • | • | • | • | • |
| UJA1167ATK/X | • | • | • | • | • | | • | • | • | • | • |

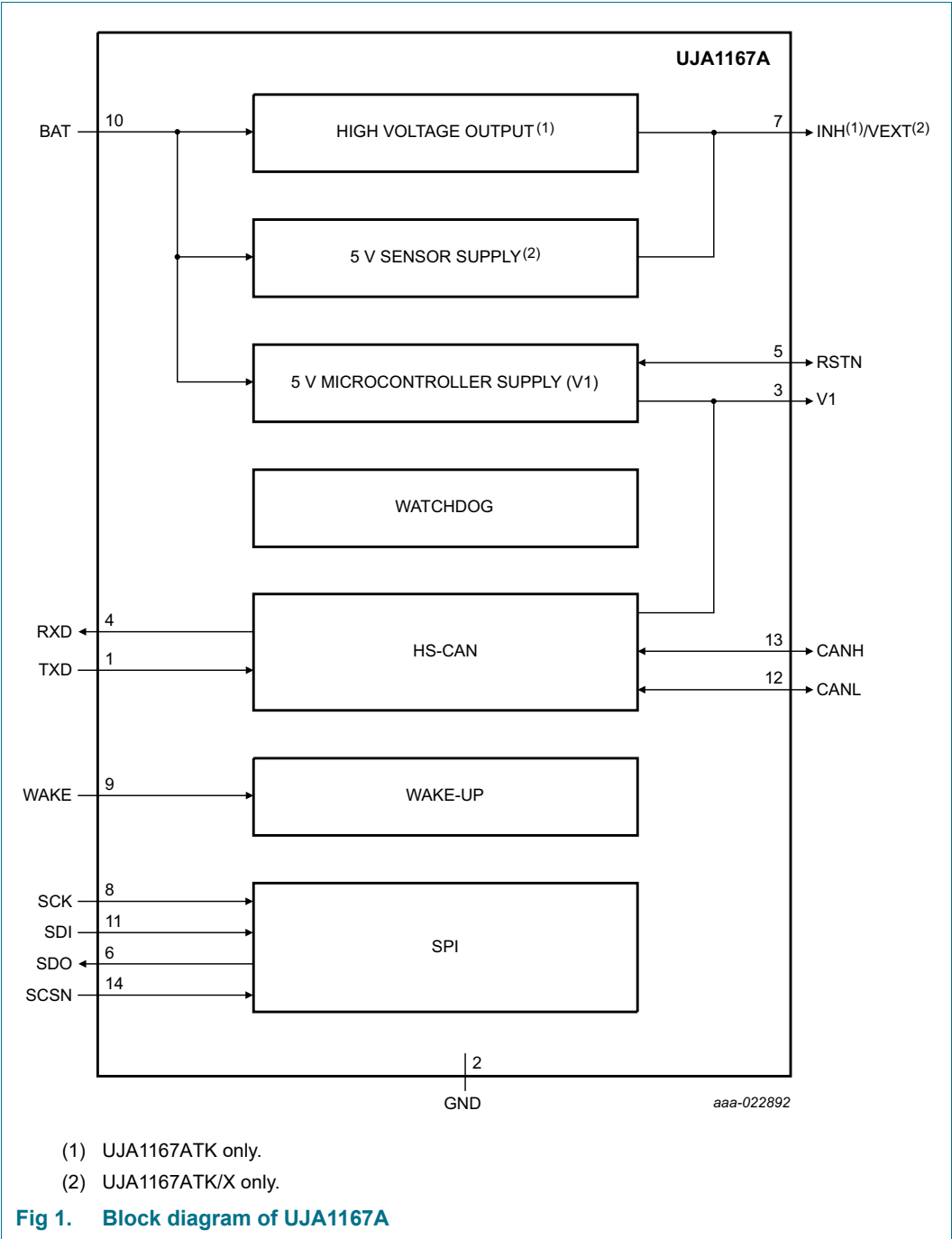
4. Ordering information

Table 2. Ordering information

| Type number ^[1] | Package | | |
|----------------------------|---------|--|-----------|
| | Name | Description | Version |
| UJA1167ATK | HVSON14 | plastic thermal enhanced very thin small outline package; no leads; 14 terminals; body 3 × 4.5 × 0.85 mm | SOT1086-2 |
| UJA1167ATK/X | | | |

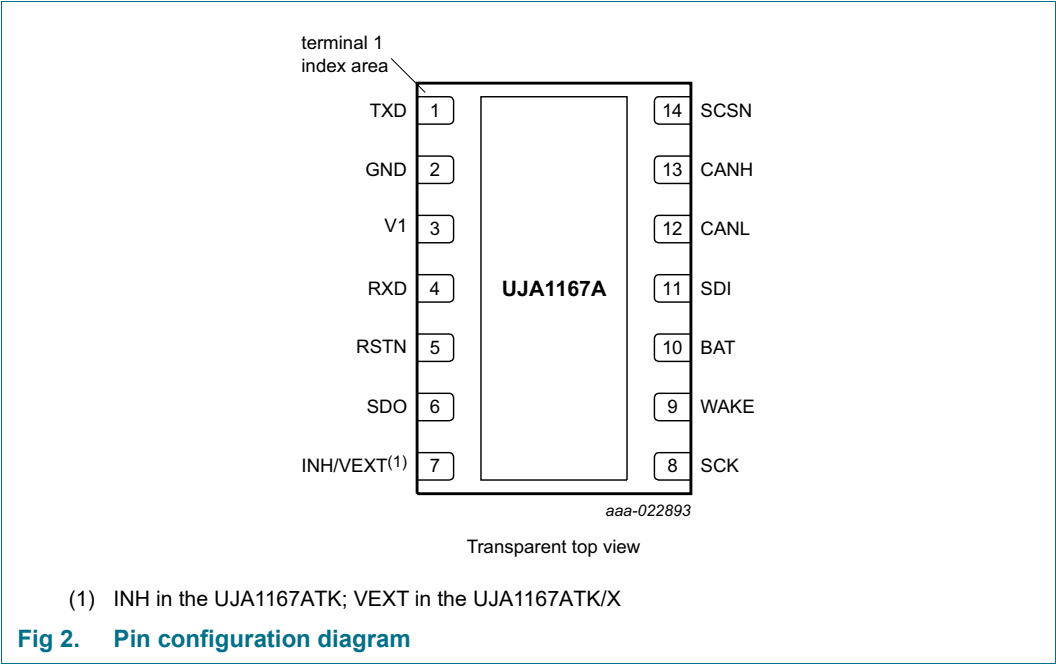
[1] UJA1167ATK contains a high-voltage output for controlling an external voltage regulator; UJA1167ATK/X includes a 5 V/30 mA sensor supply.

5. Block diagram



6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3. Pin description

| Symbol | Pin | Description |
|--------|------------------|--|
| TXD | 1 | transmit data input |
| GND | 2 ^[1] | ground |
| V1 | 3 | 5 V microcontroller supply voltage |
| RXD | 4 | receive data output; reads out data from the bus lines |
| RSTN | 5 | reset input/output |
| SDO | 6 | SPI data output |
| INH | 7 | high-voltage output for switching external regulators (UJA1167ATK) |
| VEXT | 7 | sensor supply voltage (UJA1167ATK/X) |
| SCK | 8 | SPI clock input |
| WAKE | 9 | local wake-up input |
| BAT | 10 | battery supply voltage |
| SDI | 11 | SPI data input |
| CANL | 12 | LOW-level CAN bus line |
| CANH | 13 | HIGH-level CAN bus line |
| SCSN | 14 | SPI chip select input |

[1] The exposed die pad at the bottom of the package allows for better heat dissipation and grounding from the SBC via the printed circuit board. For enhanced thermal and electrical performance, it is recommended to solder the exposed die pad to GND.

7. Functional description

7.1 System controller

The system controller manages register configuration and controls the internal functions of the UJA1167A. Detailed device status information is collected and made available to the microcontroller.

7.1.1 Operating modes

The system controller contains a state machine that supports seven operating modes: Normal, Standby, Sleep, Reset, Forced Normal, Overtemp and Off. The state transitions are illustrated in [Figure 3](#).

7.1.1.1 Normal mode

Normal mode is the active operating mode. In this mode, all the hardware on the device is available and can be activated (see [Table 4](#)). Voltage regulator V1 is enabled to supply the microcontroller.

The CAN interface can be configured to be active and thus to support normal CAN communication. Depending on the SPI register settings, the watchdog may be running in Window or Timeout mode and the INH/VEXT output may be active.

Normal mode can be selected from Standby mode via an SPI command (MC = 111).

7.1.1.2 Standby mode

Standby mode is the first-level power-saving mode of the UJA1167A, offering reduced current consumption. The transceiver is unable to transmit or receive data in Standby mode. The SPI remains enabled and V1 is still active; the watchdog is active (in Timeout mode) if enabled. The behavior of INH/VEXT is determined by the SPI setting.

If remote CAN wake-up is enabled (CWE = 1; see [Table 27](#)), the receiver monitors bus activity for a wake-up request. The bus pins are biased to GND (via $R_{i(cm)}$) when the bus is inactive for $t > t_{to(silence)}$ and at approximately 2.5 V when there is activity on the bus (autonomous biasing).

Pin RXD is forced LOW when any enabled wake-up event is detected. This can be either a regular wake-up (via the CAN bus or pin WAKE) or a diagnostic wake-up such as an overtemperature event (see [Section 7.10](#)).

The UJA1167A switches to Standby mode via Reset mode:

- from Off mode if the battery voltage rises above the power-on detection threshold ($V_{th(det)pon}$)
- from Overtemp mode if the chip temperature falls below the overtemperature protection release threshold, $T_{th(rel)otp}$
- from Sleep mode on the occurrence of a regular or diagnostic wake-up event

Standby mode can also be selected from Normal mode via an SPI command (MC = 100).

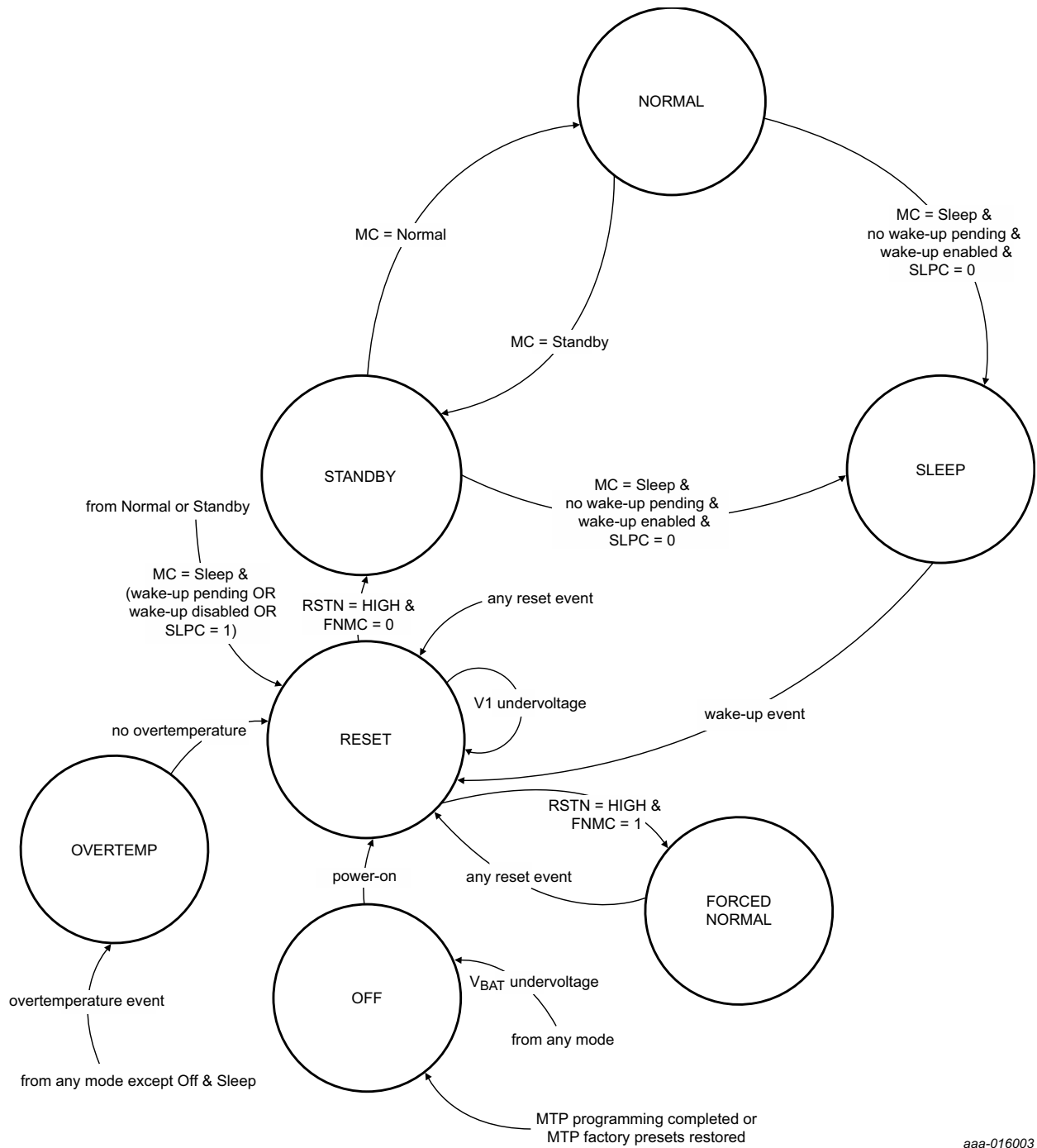


Fig 3. UJA1167A system controller state diagram

7.1.1.3 Sleep mode

Sleep mode is the second-level power-saving mode of the UJA1167A. The difference between Sleep and Standby modes is that V1 is off in Sleep mode and temperature protection is inactive.

Any enabled regular wake-up via CAN or WAKE or any diagnostic wake-up event will cause the UJA1167A to wake up from Sleep mode. The behavior of INH/VEXT is determined by the SPI settings. The SPI is disabled. Autonomous bus biasing is active. See [Table 7](#) for a description of watchdog behavior in Sleep mode.

Sleep mode can be selected from Normal or Standby mode via an SPI command (MC = 001). The UJA1167A will switch to Sleep mode on receipt of this command, provided there are no pending wake-up events and at least one regular wake-up source is enabled. Any attempt to enter Sleep mode while one of these conditions has not been met will cause the UJA1167A to switch to Reset mode and set the reset source status bits (RSS) to 10100 ('illegal Sleep mode command received'; see [Table 6](#)).

Since V1 is off in Sleep mode, the only way the SBC can exit Sleep mode is via a wake-up event (see [Section 7.10](#)).

Sleep mode can be permanently disabled in applications where, for safety reasons, the supply voltage to the host controller must never be cut off. Sleep mode is permanently disabled by setting the Sleep control bit (SLPC) in the SBC configuration register (see [Table 9](#)) to 1. This register is located in the non-volatile memory area of the device. When SLPC = 1, a Sleep mode SPI command (MC = 001) triggers an SPI failure event instead of a transition to Sleep mode.

7.1.1.4 Reset mode

Reset mode is the reset execution state of the SBC. This mode ensures that pin RSTN is pulled down for a defined time to allow the microcontroller to start up in a controlled manner.

The transceiver is unable to transmit or receive data in Reset mode. The behavior of INH/VEXT is determined by the settings of bits VEXTC and VEXTSUC (see [Section 7.6](#)). The SPI is inactive; the watchdog is disabled; V1 and overtemperature detection are active.

The UJA1167A switches to Reset mode from any mode in response to a reset event (see [Table 6](#) for a list of reset sources).

The UJA1167A exits Reset mode:

- and switches to Standby mode if pin RSTN is released HIGH
- and switches to Forced Normal mode if bit FNMC = 1
- if the SBC is forced into Off or Overtemp mode

If a V1 undervoltage event forced the transition to Reset mode, the UJA1167A will remain in Reset mode until the voltage on pin V1 has recovered.

7.1.1.5 Off mode

The UJA1167A switches to Off mode when the battery is first connected or from any mode when $V_{BAT} < V_{th(det)poff}$. Only power-on detection is enabled; all other modules are inactive. The UJA1167A starts to boot up when the battery voltage rises above the power-on detection threshold $V_{th(det)pon}$ (triggering an initialization process) and switches to Reset mode after $t_{startup}$. In Off mode, the CAN pins disengage from the bus (zero load; high-ohmic).

7.1.1.6 Overtemp mode

Overtemp mode is provided to prevent the UJA1167A being damaged by excessive temperatures. The UJA1167A switches immediately to Overtemp mode from any mode (other than Off mode or Sleep mode) when the global chip temperature rises above the overtemperature protection activation threshold, $T_{th(otp)}$.

To help prevent the loss of data due to overheating, the UJA1167A issues a warning when the IC temperature rises above the overtemperature warning threshold ($T_{th(warn)otp}$). When this happens, status bit OTWS is set and an overtemperature warning event is captured (OTW = 1), if enabled (OTWE = 1).

In Overtemp mode, the CAN transmitter and receiver are disabled and the CAN pins are in a high-ohmic state. No wake-up event will be detected, but a pending wake-up will still be signalled by a LOW level on pin RXD, which will persist after the overtemperature event has been cleared. V1 is off and pin RSTN is driven LOW.

VEXT is off in the UJA1167ATK/X. In the UJA1167ATK, INH remains unchanged when the SBC enters Overtemp mode.

The UJA1167A exits Overtemp mode:

- and switches to Reset mode if the chip temperature falls below the overtemperature protection release threshold, $T_{th(rel)otp}$
- if the device is forced to switch to Off mode ($V_{BAT} < V_{th(det)poff}$)

7.1.1.7 Forced Normal mode

Forced Normal mode simplifies SBC testing and is useful for initial prototyping and failure detection, as well as first flashing of the microcontroller. The watchdog is disabled in Forced Normal mode. The low-drop voltage regulator (V1) is active, VEXT/INH is enabled and the CAN transceiver is active.

Bit FNMC is factory preset to 1, so the UJA1167A initially boots up in Forced Normal mode (see [Table 9](#)). This allows a newly installed device to be run in Normal mode without a watchdog. So the microcontroller can be flashed via the CAN bus in the knowledge that a watchdog timer overflow will not trigger a system reset.

The register containing bit FNMC (address 74h) is stored in non-volatile memory (see [Section 7.11](#)). So once bit FNMC is programmed to 0, the SBC will no longer boot up in Forced Normal mode, allowing the watchdog to be enabled.

Even in Forced Normal mode, a reset event (e.g. an external reset or a V1 undervoltage) will trigger a transition to Reset mode with normal Reset mode behavior (except that the transmitter remains active if there is no V1 undervoltage). However, the UJA1167A will return to Forced Normal mode instead of switching to Standby mode when it exits Reset mode.

In Forced Normal mode, only the Main status register, the Watchdog status register, the Identification register and registers stored in non-volatile memory can be read. The non-volatile memory area is fully accessible for writing as long as the UJA1167A is in the factory preset state (for details see [Section 7.11](#)).

The UJA1167A switches from Reset mode to Forced Normal mode if bit FNMC = 1.

7.1.1.8 Hardware characterization for the UJA1167A operating modes

Table 4. Hardware characterization by functional block

| Block | Operating mode | | | | | | |
|----------|--------------------|----------------|--|--|---------------------------------------|--------------------------------------|----------------------------------|
| | Off | Forced Normal | Standby | Normal | Sleep | Reset | Overtemp |
| V1 | off ^[1] | on | on | on | off | on | off |
| VEXT/INH | off | on | determined by bits VEXTC and VEXTSUC (see Table 13) | determined by bits VEXTC and VEXTSUC | determined by bits VEXTC and VEXTSUC | determined by bits VEXTC and VEXTSUC | VEXT off; INH unchanged |
| RSTN | LOW | HIGH | HIGH | HIGH | LOW | LOW | LOW |
| SPI | disabled | active | active | active | disabled | disabled | disabled |
| Watchdog | off | off | determined by bits WMC (see Table 8) ^[2] | determined by bits WMC | determined by bits WMC ^[2] | off | off |
| CAN | off | Active | Offline | Active/ Offline/ Listen-only (determined by bits CMC; see Table 15) | Offline | Offline | off |
| RXD | V1 level | CAN bit stream | V1 level/LOW if wake-up detected | CAN bit stream if CMC = 01/10/11; otherwise same as Standby/Sleep | V1 level/LOW if wake-up detected | V1 level/LOW if wake-up detected | V1 level/LOW if wake-up detected |

[1] When the SBC switches from Reset, Standby or Normal mode to Off mode, V1 behaves as a current source during power down while V_{BAT} is between 3 V and 2 V.

[2] Window mode is only active in Normal mode.

7.1.2 System control registers

The operating mode is selected via bits MC in the Mode control register. The Mode control register is accessed via SPI address 0x01 (see [Section 7.15](#)).

Table 5. Mode control register (address 01h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---------------|
| 7:3 | reserved | R | - | |
| 2:0 | MC | R/W | | mode control: |
| | | | 001 | Sleep mode |
| | | | 100 | Standby mode |
| | | | 111 | Normal mode |

The Main status register can be accessed to monitor the status of the overtemperature warning flag and to determine whether the UJA1167A has entered Normal mode after initial power-up. It also indicates the source of the most recent reset event.

Table 6. Main status register (address 03h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7 | reserved | R | - | |
| 6 | OTWS | R | | overtemperature warning status: |
| | | | 0 | IC temperature below overtemperature warning threshold |
| | | | 1 | IC temperature above overtemperature warning threshold |
| 5 | NMS | R | | Normal mode status: |
| | | | 0 | UJA1167A has entered Normal mode (after power-up) |
| | | | 1 | UJA1167A has powered up but has not yet switched to Normal mode |
| 4:0 | RSS | R | | reset source status: |
| | | | 00000 | exited Off mode (power-on) |
| | | | 00001 | CAN wake-up in Sleep mode |
| | | | 00100 | wake-up via WAKE pin in Sleep mode |
| | | | 01100 | watchdog overflow in Sleep mode (Timeout mode) |
| | | | 01101 | diagnostic wake-up in Sleep mode |
| | | | 01110 | watchdog triggered too early (Window mode) |
| | | | 01111 | watchdog overflow (Window mode or Timeout mode with WDF = 1) |
| | | | 10000 | illegal watchdog mode control access |
| | | | 10001 | RSTN pulled down externally |
| | | | 10010 | exited Overtemp mode |
| | | | 10011 | V1 undervoltage |
| | | | 10100 | illegal Sleep mode command received |

7.2 Watchdog

The UJA1167A contains a watchdog that supports three operating modes: Window, Timeout and Autonomous. In Window mode (available only in SBC Normal mode), a watchdog trigger event within a closed watchdog window resets the watchdog timer. In Timeout mode, the watchdog runs continuously and can be reset at any time within the timeout time by a watchdog trigger. Watchdog timeout mode can also be used for cyclic wake-up of the microcontroller. In Autonomous mode, the watchdog can be off or in Timeout mode (see [Section 7.2.4](#)).

The watchdog mode is selected via bits WMC in the Watchdog control register ([Table 8](#)). The SBC must be in Standby mode when the watchdog mode and/or period is changed. If Window mode is selected (WMC = 100), the watchdog will remain in (or switch to) Timeout mode until the SBC enters Normal mode. Any attempt to change the watchdog operating mode (via WMC) or period (via NWP) while the SBC is in Normal mode will cause the UJA1167A to switch to Reset mode. The reset source status bits (RSS) will be set to 10000 ('illegal watchdog mode control access'; see [Table 6](#)) and an SPI failure (SPIF) event triggered, if enabled.

Eight watchdog periods are supported, from 8 ms to 4096 ms. The watchdog period is programmed via bits NWP. The selected period is valid for both Window and Timeout modes. The default watchdog period is 128 ms.

Mini high-speed CAN system basis chip with Standby/Sleep modes & watchdog

A watchdog trigger event resets the watchdog timer. A watchdog trigger event is any valid write access to the Watchdog control register. If the watchdog mode or the watchdog period have changed as a result of the write access, the new values are immediately valid.

Table 7. Watchdog configuration

| Operating/watchdog mode | | | | | | |
|--|--|--------------|---------------|------------------|------------------|------|
| FNMC (Forced Normal mode control) | | 0 | 0 | 0 | 0 | 1 |
| SDMC (Software Development mode control) | | x | x | 0 | 1 | x |
| WMC (watchdog mode control) | | 100 (Window) | 010 (Timeout) | 001 (Autonomous) | 001 (Autonomous) | n.a. |
| SBC Operating Mode | Normal mode | Window | Timeout | Timeout | off | off |
| | Standby mode (RXD HIGH) ^[1] | Timeout | Timeout | off | off | off |
| | Standby mode (RXD LOW) ^[1] | Timeout | Timeout | Timeout | off | off |
| | Sleep mode | Timeout | Timeout | off | off | off |
| | Other modes | off | off | off | off | off |

[1] RXD LOW signals a pending wake-up.

Table 8. Watchdog control register (address 00h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|---------------------|-------------------------|
| 7:5 | WMC | R/W | | watchdog mode control: |
| | | | 001 ^[1] | Autonomous mode |
| | | | 010 ^[2] | Timeout mode |
| | | | 100 ^[3] | Window mode |
| 4 | reserved | R | - | |
| 3:0 | NWP | R/W | | nominal watchdog period |
| | | | 1000 | 8 ms |
| | | | 0001 | 16 ms |
| | | | 0010 | 32 ms |
| | | | 1011 | 64 ms |
| | | | 0100 ^[2] | 128 ms |
| | | | 1101 | 256 ms |
| | | | 1110 | 1024 ms |
| | | | 0111 | 4096 ms |

[1] Default value if SDMC = 1 (see [Section 7.2.1](#))

[2] Default value.

[3] Selected in Standby mode but only activated when the SBC switches to Normal mode.

The watchdog is a valuable safety mechanism, so it is critical that it is configured correctly. Two features are provided to prevent watchdog parameters being changed by mistake:

- redundant states of configuration bits WMC and NWP
- reconfiguration protection in Normal mode

Redundant states associated with control bits WMC and NWP ensure that a single bit error cannot cause the watchdog to be configured incorrectly (at least two bits must be changed to reconfigure WMC or NWP). If an attempt is made to write an invalid code to WMC or NWP (e.g. 011 or 1001 respectively), the SPI operation is abandoned and an SPI failure event is captured, if enabled (see [Section 7.10](#)).

Two operating modes have a major impact on the operation of the watchdog: Forced Normal mode and Software Development mode (Software Development mode is provided for test purposes and is not an SBC operating mode; the UJA1167A can be in any mode with Software Development mode enabled; see [Section 7.2.1](#)). These modes are enabled and disabled via bits FNMC and SDMC respectively in the SBC configuration control register (see [Table 9](#)). Note that this register is located in the non-volatile memory area (see [Section 7.10](#)). In Forced Normal mode (FNM), the watchdog is completely disabled. In Software Development mode (SDM), the watchdog can be disabled or activated for test purposes.

Information on the status of the watchdog is available from the Watchdog status register ([Table 10](#)). This register also indicates whether Forced Normal and Software Development modes are active.

Table 9. SBC configuration control register (address 74h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------------------|---|
| 7:6 | reserved | R | - | |
| 5:4 | V1RTSUC | R/W | | V1 reset threshold (defined by bit V1RTC) at start-up: |
| | | | 00 ^[1] | V1 undervoltage detection at 90 % of nominal value at start-up (V1RTC = 00) |
| | | | 01 | V1 undervoltage detection at 80 % of nominal value at start-up (V1RTC = 01) |
| | | | 10 | V1 undervoltage detection at 70 % of nominal value at start-up (V1RTC = 10) |
| | | | 11 | V1 undervoltage detection at 60 % of nominal value at start-up (V1RTC = 11) |
| 3 | FNMC | R/W | | Forced Normal mode control: |
| | | | 0 | Forced Normal mode disabled |
| | | | 1 ^[1] | Forced Normal mode enabled |
| 2 | SDMC | R/W | | Software Development mode control: |
| | | | 0 ^[1] | Software Development mode disabled |
| | | | 1 | Software Development mode enabled |
| 1 | reserved | R | - | |
| 0 | SLPC | R/W | | Sleep control: |
| | | | 0 ^[1] | the SBC supports Sleep mode |
| | | | 1 | Sleep mode commands will be ignored |

[1] Factory preset value.

Table 10. Watchdog status register (address 05h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7:4 | reserved | R | - | |
| 3 | FNMS | R | 0 | SBC is not in Forced Normal mode |
| | | | 1 | SBC is in Forced Normal mode |
| 2 | SDMS | R | 0 | SBC is not in Software Development mode |
| | | | 1 | SBC is in Software Development mode |
| 1:0 | WDS | R | | watchdog status: |
| | | | 00 | watchdog is off |
| | | | 01 | watchdog is in first half of window |
| | | | 10 | watchdog is in second half of window |
| | | | 11 | reserved |

7.2.1 Software Development mode

Software Development mode is provided to simplify the software design process. When Software Development mode is enabled, the watchdog starts up in Autonomous mode (WMC = 001) and is inactive after a system reset, overriding the default value (see [Table 8](#)). The watchdog is always off in Autonomous mode if Software Development mode is enabled (SDMC = 1; see [Table 11](#)).

Software can be run without a watchdog in Software Development mode. However, it is possible to activate and deactivate the watchdog for test purposes by selecting Window or Timeout mode via bits WMC while the SBC is in Standby mode (note that Window mode will only be activated when the SBC switches to Normal mode). Software Development mode is activated via bits SDMC in non-volatile memory (see [Table 9](#)).

7.2.2 Watchdog behavior in Window mode

The watchdog runs continuously in Window mode. The watchdog will be in Window mode if WMC = 100 and the UJA1167A is in Normal mode.

In Window mode, the watchdog can only be triggered during the second half of the watchdog period. If the watchdog overflows, or is triggered in the first half of the watchdog period (before $t_{\text{trig(wd)1}}$), a system reset is performed. After the system reset, the reset source (either 'watchdog triggered too early' or 'watchdog overflow') can be read via the reset source status bits (RSS) in the Main Status register ([Table 6](#)). If the watchdog is triggered in the second half of the watchdog period (after $t_{\text{trig(wd)1}}$ but before $t_{\text{trig(wd)2}}$), the watchdog timer is restarted.

7.2.3 Watchdog behavior in Timeout mode

The watchdog runs continuously in Timeout mode. The watchdog will be in Timeout mode if WMC = 010 and the UJA1167A is in Normal, Standby or Sleep mode. The watchdog will also be in Timeout mode if WMC = 100 and the UJA1167A is in Standby or Sleep mode. If Autonomous mode is selected (WMC = 001), the watchdog will be in Timeout mode if one of the conditions for Timeout mode listed in [Table 11](#) has been satisfied.

In Timeout mode, the watchdog timer can be reset at any time by a watchdog trigger. If the watchdog overflows, a watchdog failure event (WDF) is captured. If a WDF is already pending when the watchdog overflows, a system reset is performed. In Timeout mode, the

watchdog can be used as a cyclic wake-up source for the microcontroller when the UJA1167A is in Standby or Sleep mode. In Sleep mode, a watchdog overflow generates a wake-up event.

When the SBC is in Sleep mode with watchdog Timeout mode selected, a wake-up event is generated after the nominal watchdog period (NWP). If bit WDF is set, RXD is forced LOW and V1 is turned on. The application software can then clear the WDF bit and trigger the watchdog before it overflows.

7.2.4 Watchdog behavior in Autonomous mode

Autonomous mode is selected when WMC = 001. In Autonomous mode, the watchdog is either off or in Timeout mode, according to the conditions detailed in [Table 11](#).

Table 11. Watchdog status in Autonomous mode

| UJA1167A operating mode | Watchdog status | |
|-------------------------|-----------------|----------|
| | SDMC = 0 | SDMC = 1 |
| Normal | Timeout mode | off |
| Standby; RXD HIGH | off | off |
| Sleep | off | off |
| any other mode | off | off |
| Standby; RXD LOW | Timeout mode | off |

When Autonomous mode is selected, the watchdog will be in Timeout mode if the SBC is in Normal mode or Standby mode with RXD LOW, provided Software Development mode has been disabled (SDMC = 0). Otherwise the watchdog will be off.

In Autonomous mode, the watchdog will not be running when the SBC is in Standby (RXD HIGH) or Sleep mode. If a wake-up event is captured, pin RXD is forced LOW to signal the event and the watchdog is automatically restarted in Timeout mode. If the SBC was in Sleep mode when the wake-up event was captured, it switches to Standby mode.

7.3 System reset

When a system reset occurs, the SBC switches to Reset mode and initiates a process that generates a low-level pulse on pin RSTN.

7.3.1 Characteristics of pin RSTN

Pin RSTN is a bidirectional open drain low side driver with integrated pull-up resistance, as shown in [Figure 4](#). With this configuration, the SBC can detect the pin being pulled down externally, e.g. by the microcontroller. The input reset pulse width must be at least $t_{w(rst)}$.

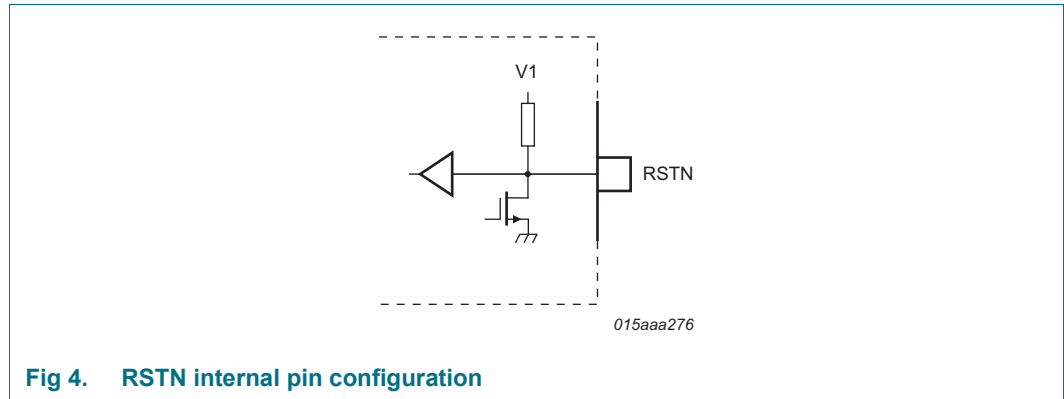


Fig 4. RSTN internal pin configuration

7.3.2 Selecting the output reset pulse width

The duration of the output reset pulse is selected via bits RLC in the Start-up control register (Table 12). The SBC distinguishes between a cold start and a warm start. A cold start is performed if the reset event was combined with a V1 undervoltage event (power-on reset, reset during Sleep mode, over-temperature reset, V1 undervoltage before entering or while in Reset mode). The output reset pulse width for a cold start is determined by the setting of bits RLC.

If any other reset event occurs without a V1 undervoltage (external reset, watchdog failure, watchdog change attempt in Normal mode, illegal Sleep mode command) the SBC uses the shortest reset length ($t_{w(rst)} = 1 \text{ ms to } 1.5 \text{ ms}$). This is called a warm start of the microcontroller.

Table 12. Start-up control register (address 73h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------------------|--|
| 7:6 | reserved | R | - | |
| 5:4 | RLC | R/W | | RSTN output reset pulse width: |
| | | | 00 ^[1] | $t_{w(rst)} = 20 \text{ ms to } 25 \text{ ms}$ |
| | | | 01 | $t_{w(rst)} = 10 \text{ ms to } 12.5 \text{ ms}$ |
| | | | 10 | $t_{w(rst)} = 3.6 \text{ ms to } 5 \text{ ms}$ |
| | | | 11 | $t_{w(rst)} = 1 \text{ ms to } 1.5 \text{ ms}$ |
| 3 | VEXTSUC | R/W | | VEXT/INH start-up control: |
| | | | 0 ^[1] | bits VEXTC set to 00 at power-up |
| | | | 1 | bits VEXTC set to 11 at power-up |
| 2:0 | reserved | R | - | |

[1] Factory preset value.

7.3.3 Reset sources

The following events will cause the UJA1167A to switch to Reset mode:

- V_{V1} drops below the selected V1 undervoltage threshold defined by bits V1RTC
- pin RSTN is pulled down externally
- the watchdog overflows in Window mode
- the watchdog is triggered too early in Window mode (before $t_{trig(wd)1}$)

- the watchdog overflows in Timeout mode with WDF = 1 (watchdog failure pending)
- an attempt is made to reconfigure the Watchdog control register while the SBC is in Normal mode
- the SBC leaves Off mode
- local or CAN bus wake-up in Sleep mode
- diagnostic wake-up in Sleep mode
- the SBC leaves Overtemp mode
- illegal Sleep mode command received

7.4 Global temperature protection

The temperature of the UJA1167A is monitored continuously, except in Sleep and Off modes. The SBC switches to Overtemp mode if the temperature exceeds the overtemperature protection activation threshold, $T_{th(act)otp}$. In addition, pin RSTN is driven LOW and V1, VEXT and the CAN transceiver are switched off. When the temperature drops below the overtemperature protection release threshold, $T_{th(rel)otp}$, the SBC switches to Standby mode via Reset mode.

In addition, the UJA1167A provides an overtemperature warning. When the IC temperature rises about the overtemperature warning threshold ($T_{th(warn)otp}$), status bit OTWS is set and an overtemperature warning event is captured (OTW = 1).

7.5 Power supplies

7.5.1 Battery supply voltage (V_{BAT})

The internal circuitry is supplied from the battery via pin BAT. The device needs to be protected against negative supply voltages, e.g. by using an external series diode. If V_{BAT} falls below the power-off detection threshold, $V_{th(det)poff}$, the SBC switches to Off mode. However, the microcontroller supply voltage (V1) remains active until V_{BAT} falls below 2 V.

The SBC switches from Off mode to Reset mode $t_{startup}$ after the battery voltage rises above the power-on detection threshold, $V_{th(det)pon}$. Power-on event status bit PO is set to 1 to indicate the UJA1167A has powered up and left Off mode (see [Table 21](#)).

7.5.2 Low-drop voltage supply for 5 V microcontroller (V1)

V1 is intended to supply the microcontroller and the internal CAN transceiver and delivers up to 150 mA at 5 V. The output voltage on V1 is monitored. A system reset is generated if the voltage on V1 drops below the selected undervoltage threshold (60 %, 70 %, 80 % or 90 % of the nominal V1 output voltage, selected via V1RTC in the V1 and INH/VEXT control register; see [Table 13](#)).

The internal CAN transceiver consumes 50 mA (max) when the bus is continuously dominant, leaving 100 mA available for the external load on pin V1. In practice, the typical current consumption of the CAN transceiver is lower (≈ 25 mA), depending on the application, leaving more current available for the load.

The default value of the undervoltage threshold at power-up is determined by the value of bits V1RTSUC in the SBC configuration control register ([Table 9](#)). The SBC configuration control register is in non-volatile memory, allowing the user to define the undervoltage threshold (V1RTC) at start-up.

In addition, an undervoltage warning (a V1U event; see [Section 7.10](#)) is generated if the voltage on V1 falls below 90 % of the nominal value (and V1U event detection is enabled, V1UE = 1; see [Table 26](#)). This information can be used as a warning, when the 60 %, 70 % or 80 % threshold is selected, to indicate that the level on V1 is outside the nominal supply range. The status of V1, whether it is above or below the 90 % undervoltage threshold, can be read via bit V1S in the Supply voltage status register ([Table 14](#)).

Table 13. V1 and INH/VEXT control register (address 10h)

| Bit | Symbol | Access | Value | Description |
|-----|----------------------|--------|-------|--|
| 7:4 | reserved | R | - | |
| 3:2 | VEXTC ^[1] | R/W | | VEXT/INH configuration: |
| | | | 00 | VEXT/INH off in all modes |
| | | | 01 | VEXT/INH on in Normal mode |
| | | | 10 | VEXT/INH on in Normal, Standby and Reset modes |
| | | | 11 | VEXT/INH on in Normal, Standby, Sleep and Reset modes |
| 1:0 | V1RTC ^[2] | R/W | | set V1 reset threshold: |
| | | | 00 | reset threshold set to 90 % of V1 nominal output voltage |
| | | | 01 | reset threshold set to 80 % of V1 nominal output voltage |
| | | | 10 | reset threshold set to 70 % of V1 nominal output voltage |
| | | | 11 | reset threshold set to 60 % of V1 nominal output voltage |

[1] Default value at power-up defined by setting of bits VEXTSUC (see [Table 12](#)).

[2] Default value at power-up defined by setting of bits V1RTSUC (see [Table 9](#)).

Table 14. Supply voltage status register (address 1Bh)

| Bit | Symbol | Access | Value | Description |
|-----|----------------------|--------|-------------------|---|
| 7:3 | reserved | R | - | |
| 2:1 | VEXTS ^[1] | R | | VEXT status: |
| | | | 00 ^[2] | VEXT voltage ok |
| | | | 01 | VEXT output voltage below undervoltage threshold |
| | | | 10 | VEXT output voltage above overvoltage threshold |
| | | | 11 | VEXT disabled |
| 0 | V1S | R | | V1 status: |
| | | | 0 ^[2] | V1 output voltage above 90 % undervoltage threshold |
| | | | 1 | V1 output voltage below 90 % undervoltage threshold |

[1] UJA1167ATK/X only; status will always be 00 in the UJA1167ATK.

[2] Default value at power-up.

7.6 High voltage output and external sensor supply

Depending on the device version, pin 7 is a high voltage output (INH) or an external sensor supply (VEXT).

In the UJA1167ATK, the INH pin can be used to control external devices, such as voltage regulators. Depending on the setting of bits VEXTC, pin INH will either be disabled (to disable external devices) or at a battery-related HIGH level (to enable external devices) in

selected SBC operating modes (see [Table 13](#)). To ensure external devices are not disabled due to an overtemperature event, pin INH does not change state when the SBC switches to Overtemp mode.

In the UJA1167ATK/X, the VEXT pin is a voltage output intended to supply external components, delivering up to 30 mA at 5 V. Like INH, VEXT is also configured via bits VEXTC in the V1 and INH/VEXT control register ([Table 13](#)).

The default value of VEXTC at power-on is defined by bits VEXTSUC in non-volatile memory (see [Section 7.11](#)).

In contrast to pin INH, pin VEXT is disabled when the SBC switches to Overtemp mode. The status of VEXT can be read from the Supply voltage status register ([Table 14](#)).

7.7 High-speed CAN transceiver

The integrated high-speed CAN transceiver is designed for active communication at bit rates up to 1 Mbit/s, providing differential transmit and receive capability to a CAN protocol controller. The transceiver is ISO 11898-2:2016 compliant. The CAN transmitter is supplied from V1. The UJA1167A includes additional timing parameters on loop delay symmetry to ensure reliable communication in fast phase at data rates up to 5 Mbit/s, as used in CAN FD networks.

The CAN transceiver supports autonomous CAN biasing, which helps to minimize RF emissions. CANH and CANL are always biased to 2.5 V when the transceiver is in Active or Listen-only modes (CMC = 01/10/11).

Autonomous biasing is active in CAN Offline mode - to 2.5 V if there is activity on the bus (CAN Offline Bias mode) and to GND if there is no activity on the bus for $t > t_{to(silence)}$ (CAN Offline mode).

This is useful when the node is disabled due to a malfunction in the microcontroller. The SBC ensures that the CAN bus is correctly biased to avoid disturbing ongoing communication between other nodes. The autonomous CAN bias voltage is derived directly from V_{BAT} .

7.7.1 CAN operating modes

The integrated CAN transceiver supports four operating modes: Active, Listen-only, Offline and Offline Bias (see [Figure 5](#)). The CAN transceiver operating mode depends on the UJA1167A operating mode and on the setting of bits CMC in the CAN control register ([Table 15](#)).

When the UJA1167A is in Normal mode, the CAN transceiver operating mode (Active, Listen-only or Offline) can be selected via bits CMC in the CAN control register ([Table 15](#)). When the UJA1167A is in Standby or Sleep modes, the transceiver is forced to Offline or Offline Bias mode (depending on bus activity).

7.7.1.1 CAN Active mode

In CAN Active mode, the transceiver can transmit and receive data via CANH and CANL. The differential receiver converts the analog data on the bus lines into digital data, which is output on pin RXD. The transmitter converts digital data generated by the CAN controller (input on pin TXD) into analog signals suitable for transmission over the CANH and CANL bus lines.

CAN Active mode is selected when CMC = 01 or 10. When CMC = 01, V1/CAN undervoltage detection is enabled and the transceiver will go to CAN Offline or CAN Offline Bias mode when the voltage on V1 drops below the 90 % threshold. When CMC = 10, V1/CAN undervoltage detection is disabled. The transmitter will remain active until the voltage on V1 drops below the V1 reset threshold (selected via bits V1RTC). The SBC will then switch to Reset mode and the transceiver will switch to CAN Offline or CAN Offline Bias mode.

The CAN transceiver is in Active mode when:

- the UJA1167A is in Normal mode (MC = 111) and the CAN transceiver has been enabled by setting bits CMC in the CAN control register to 01 or 10 (see [Table 15](#)) and:
 - if CMC = 01, the voltage on pin V1 is above the 90 % undervoltage threshold
 - if CMC = 10, the voltage on pin V1 is above the V1 reset threshold

If pin TXD is held LOW (e.g. by a short-circuit to GND) when CAN Active mode is selected via bits CMC, the transceiver will not enter CAN Active mode but will switch to or remain in CAN Listen-only mode. It will remain in Listen-only mode until pin TXD goes HIGH in order to prevent a hardware and/or software application failure from driving the bus lines to an unwanted dominant state.

In CAN Active mode, the CAN bias voltage is derived from V1.

The application can determine whether the CAN transceiver is ready to transmit/receive data or is disabled by reading the CAN Transceiver Status (CTS) bit in the Transceiver Status Register ([Table 16](#)).

7.7.1.2 CAN Listen-only mode

CAN Listen-only mode allows the UJA1167A to monitor bus activity while the transceiver is inactive, without influencing bus levels. This facility could be used by development tools that need to listen to the bus but do not need to transmit or receive data or for software-driven selective wake-up. Dedicated microcontrollers could be used for selective wake-up, providing an embedded low-power CAN engine designed to monitor the bus for potential wake-up events.

In Listen-only mode the CAN transmitter is disabled, reducing current consumption. The CAN receiver and CAN biasing remain active. This enables the host microcontroller to switch to a low-power mode in which an embedded CAN protocol controller remains active, waiting for a signal to wake up the microcontroller.

The CAN transceiver is in Listen-only mode when:

- the UJA1167A is in Normal mode and CMC = 11

The CAN transceiver will not leave Listen-only mode while TXD is LOW or CAN Active mode is selected with CMC = 01 while the voltage on V1 is below the 90 % undervoltage threshold.

7.7.1.3 CAN Offline and Offline Bias modes

In CAN Offline mode, the transceiver monitors the CAN bus for a wake-up event, provided CAN wake-up detection is enabled (CWE = 1). CANH and CANL are biased to GND.

CAN Offline Bias mode is the same as CAN Offline mode, with the exception that the CAN bus is biased to 2.5 V. This mode is activated automatically when activity is detected on the CAN bus while the transceiver is in CAN Offline mode. The transceiver will return to CAN Offline mode if the CAN bus is silent (no CAN bus edges) for longer than $t_{to(silence)}$.

The CAN transceiver switches to CAN Offline mode from CAN Active mode or CAN Listen-only mode if:

- the SBC switches to Reset or Standby or Sleep mode OR
- the SBC is in Normal mode and CMC = 00

provided the CAN-bus has been inactive for at least $t_{to(silence)}$. If the CAN-bus has been inactive for less than $t_{to(silence)}$, the CAN transceiver switches first to CAN Offline Bias mode and then to CAN Offline mode once the bus has been silent for $t_{to(silence)}$.

The CAN transceiver switches to CAN Offline/Offline Bias mode from CAN Active mode if CMC = 01 and the voltage on V1 drops below the 90 % undervoltage threshold or CMC = 10 and the voltage on V1 drops below the V1 reset threshold.

The CAN transceiver switches to CAN Offline mode:

- from CAN Offline Bias mode if no activity is detected on the bus (no CAN edges) for $t > t_{to(silence)}$ OR
- when the SBC switches from Off or Overtemp mode to Reset mode

The CAN transceiver switches from CAN Offline mode to CAN Offline Bias mode if:

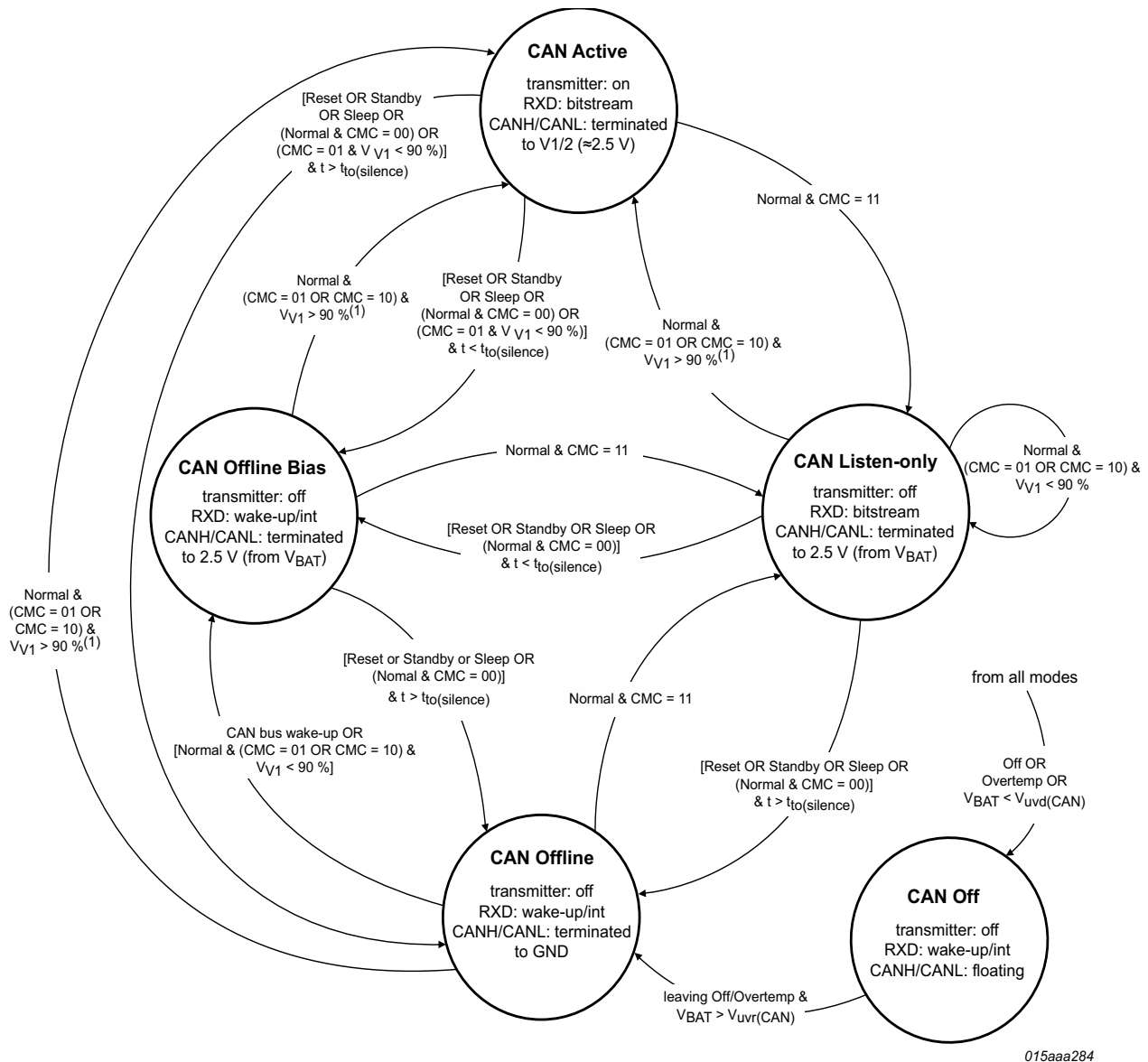
- a standard wake-up pattern is detected on the CAN bus OR
- the SBC is in Normal mode, CMC = 01 or 10 and $V_{V1} < 90\%$

7.7.1.4 CAN Off mode

The CAN transceiver is switched off completely with the bus lines floating when:

- the SBC switches to Off or Overtemp mode OR
- V_{BAT} falls below the CAN receiver undervoltage detection threshold, $V_{uvd(CAN)}$

It will be switched on again on entering CAN Offline mode when V_{BAT} rises above the undervoltage recovery threshold ($V_{uvr(CAN)}$) and the SBC is no longer in Off/Overtemp mode. CAN Off mode prevents reverse currents flowing from the bus when the battery supply to the SBC is lost.



- (1) To prevent the bus lines being driven to a permanent dominant state, the transceiver will not switch to CAN Active mode or CAN Listen-only mode if pin TXD is held LOW (e.g. by a short-circuit to GND)

Fig 5. CAN transceiver state machine (with FNMC = 0)

7.7.2 CAN standard wake-up

If the CAN transceiver is in Offline mode and CAN wake-up is enabled (CWE = 1), the UJA1167A will monitor the bus for a wake-up pattern.

A filter at the receiver input prevents unwanted wake-up events occurring due to automotive transients or EMI. A dominant-recessive-dominant wake-up pattern must be transmitted on the CAN bus within the wake-up timeout time ($t_{to(wake)}$) to pass the wake-up filter and trigger a wake-up event (see Figure 6; note that additional pulses may occur between the recessive/dominant phases). The recessive and dominant phases must last at least $t_{wake(busrec)}$ and $t_{wake(busdom)}$, respectively.

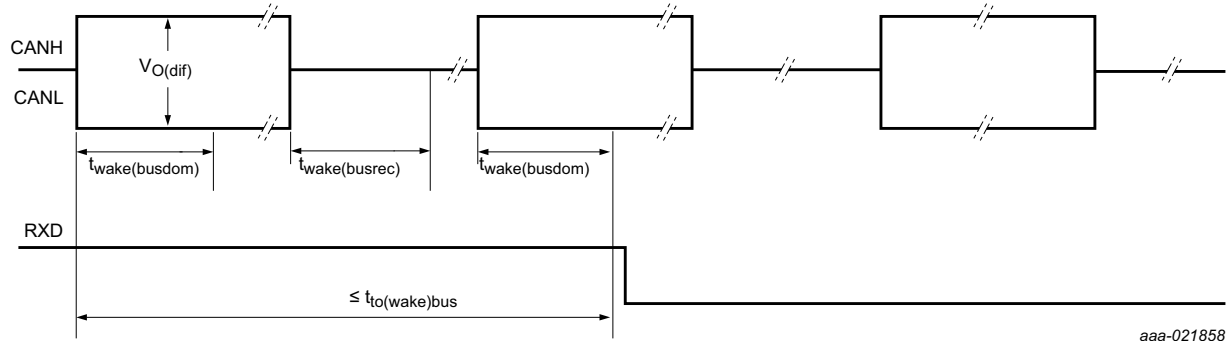


Fig 6. CAN wake-up timing

When a valid CAN wake-up pattern is detected on the bus, wake-up bit CW in the Transceiver event status register is set (see [Table 23](#)) and pin RXD is driven LOW. If the SBC was in Sleep mode when the wake-up pattern was detected, V1 is enabled to supply the microcontroller and the SBC switches to Standby mode via Reset mode.

7.7.3 CAN control and Transceiver status registers

Table 15. CAN control register (address 20h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7:2 | reserved | R/W | - | |
| 1:0 | CMC | R/W | | CAN transceiver operating mode selection (available when UJA1167A is in Normal mode; MC = 111): |
| | | | 00 | Offline mode |
| | | | 01 | Active mode; see Section 7.7.1.1 and Section 7.7.1.3 |
| | | | 10 | Active mode; see Section 7.7.1.1 and Section 7.7.1.3 |
| | | | 11 | Listen-only mode |

Table 16. Transceiver status register (address 22h)

| Bit | Symbol | Access | Value | Description |
|-----|--------------------|--------|-------|--|
| 7 | CTS | R | 0 | CAN transceiver not in Active mode |
| | | | 1 | CAN transceiver in Active mode |
| 6:4 | reserved | R | - | |
| 3 | CBSS | R | 0 | CAN bus active (communication detected on bus) |
| | | | 1 | CAN bus inactive (for longer than $t_{to(silence)}$) |
| 2 | reserved | R | - | |
| 1 | VCS ^[1] | R | 0 | the output voltage on V1 is above the 90 % threshold |
| | | | 1 | the output voltage on V1 is below the 90 % threshold |
| 0 | CFS | R | 0 | no TXD dominant timeout event detected |
| | | | 1 | CAN transmitter disabled due to a TXD dominant timeout event |

[1] Only active when CMC = 01.

7.8 CAN fail-safe features

7.8.1 TXD dominant timeout

A TXD dominant time-out timer is started when pin TXD is forced LOW while the transceiver is in CAN Active Mode. If the LOW state on pin TXD persists for longer than the TXD dominant time-out time ($t_{to(dom)TXD}$), the transmitter is disabled, releasing the bus lines to recessive state. This function prevents a hardware and/or software application failure from driving the bus lines to a permanent dominant state (blocking all network communications). The TXD dominant time-out timer is reset when pin TXD goes HIGH. The TXD dominant time-out time also defines the minimum possible bit rate of 4.4 kbit/s.

When the TXD dominant time-out time is exceeded, a CAN failure event is captured ($CF = 1$; see [Table 23](#)), if enabled ($CFE = 1$; see [Table 27](#)). In addition, the status of the TXD dominant timeout can be read via the CFS bit in the Transceiver status register ([Table 16](#)) and bit CTS is cleared.

7.8.2 Pull-up on TXD pin

Pin TXD has an internal pull-up towards V1 to ensure a safe defined recessive driver state in case the pin is left floating.

7.8.3 V1 undervoltage event

When $CMC = 01$, a CAN failure event is captured ($CF = 1$) and status bit VCS is set to 1 when the supply to the CAN transceiver (V_{V1}) falls below 90 % of its nominal value (assuming CAN failure detection is enabled; $CFE = 1$).

7.8.4 Loss of power at pin BAT

A loss of power at pin BAT has no influence on the bus lines or on the microcontroller. No reverse currents will flow from the bus.

7.9 Local wake-up via WAKE pin

Local wake-up is enabled via bits WPRE and WPFE in the WAKE pin event capture enable register (see [Table 28](#)). A wake-up event is triggered by a LOW-to-HIGH (if $WPRE = 1$) and/or a HIGH-to-LOW (if $WPFE = 1$) transition on the WAKE pin. This arrangement allows for maximum flexibility when designing a local wake-up circuit. In applications that don't make use of the local wake-up facility, local wake-up should be disabled and the WAKE pin connected to GND to ensure optimal EMI performance.

Table 17. WAKE status register (address 4Bh)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|--|
| 7:2 | reserved | R | - | |
| 1 | WPVS | R | | WAKE pin status: |
| | | | 0 | voltage on WAKE pin below switching threshold ($V_{th(sw)}$) |
| | | | 1 | voltage on WAKE pin above switching threshold ($V_{th(sw)}$) |
| 0 | reserved | R | - | |

While the SBC is in Normal mode, the status of the voltage on pin WAKE can always be read via bit WPVS. Otherwise, WPVS is only valid if local wake-up is enabled ($WPRE = 1$ and/or $WPFE = 1$).

7.10 Wake-up and interrupt event diagnosis via pin RXD

Wake-up and interrupt event diagnosis in the UJA1167A is intended to provide the microcontroller with information on the status of a range of features and functions. This information is stored in the event status registers ([Table 21](#) to [Table 23](#)) and is signaled on pin RXD, if enabled.

A distinction is made between regular wake-up events and interrupt events (at least one regular wake-up source must be enabled to allow the UJA1167A to switch to Sleep mode; see [Section 7.1.1.3](#)).

Table 18. Regular events

| Symbol | Event | Power-on | Description |
|--------|--------------------------|----------|---|
| CW | CAN wake-up | disabled | a CAN wake-up event was detected while the transceiver was in CAN Offline mode. |
| WPR | rising edge on WAKE pin | disabled | a rising-edge wake-up was detected on pin WAKE |
| WPF | falling edge on WAKE pin | disabled | a falling-edge wake-up was detected on pin WAKE |

Table 19. Diagnostic events

| Symbol | Event | Power-on | Description |
|----------------------|-------------------------|----------------|---|
| PO | power-on | always enabled | the UJA1167A has exited Off mode (after battery power has been restored/connected) |
| OTW | overtemperature warning | disabled | the IC temperature has exceeded the overtemperature warning threshold (not in Sleep mode) |
| SPIF | SPI failure | disabled | SPI clock count error (only 16-, 24- and 32-bit commands are valid), illegal WMC, NWP or MC code or attempted write access to locked register (not in Sleep mode) |
| WDF | watchdog failure | always enabled | watchdog overflow in Window or Timeout mode or watchdog triggered too early in Window mode; a system reset is triggered immediately in response to a watchdog failure in Window mode; when the watchdog overflows in Timeout mode, a system reset is only performed if a WDF is already pending (WDF = 1) |
| VEXTO ^[1] | VEXT overvoltage | disabled | VEXT overvoltage detected |
| VEXTU ^[1] | VEXT undervoltage | disabled | VEXT undervoltage detected |
| V1U | V1 undervoltage | disabled | voltage on V1 has dropped below the 90 % undervoltage threshold when V1 is active (event is not captured in Sleep mode because V1 is off). V1U event capture is independent of the setting of bits V1RTC. |
| CBS | CAN bus silence | disabled | no activity on CAN bus for $t_{to(silence)}$ (detected only when CBSE = 1 while bus active) |
| CF | CAN failure | disabled | one of the following CAN failure events detected: <ul style="list-style-type: none"> - CAN transceiver deactivated due to a V1 undervoltage - CAN transceiver deactivated due to a dominant clamped TXD (not in Sleep mode) |

[1] UJA1167ATK/X only.

PO and WDF interrupts are always captured. Wake-up and interrupt detection can be enabled/disabled for the remaining events individually via the event capture enable registers ([Table 25](#) to [Table 27](#)).

If an event occurs while the associated event capture function is enabled, the relevant event status bit is set. If the transceiver is in CAN Offline mode with V1 active (SBC Normal or Standby mode), pin RXD is forced LOW to indicate that a wake-up or interrupt event has been detected. If the UJA1167A is in sleep mode when the event occurs, the microcontroller supply, V1, is activated and the SBC switches to Standby mode (via Reset mode).

The microcontroller can monitor events via the event status registers. An extra status register, the Global event status register ([Table 20](#)), is provided to help speed up software polling routines. By polling the Global event status register, the microcontroller can quickly determine the type of event captured (system, supply, transceiver or WAKE pin) and then query the relevant table ([Table 21](#), [Table 22](#), [Table 23](#) or [Table 24](#) respectively).

After the event source has been identified, the status flag should be cleared (set to 0) by writing 1 to the relevant bit (writing 0 will have no effect). A number of status bits can be cleared in a single write operation by writing 1 to all relevant bits.

It is strongly recommended to clear only the status bits that were set to 1 when the status registers were last read. This precaution ensures that events triggered just before the write access are not lost.

7.10.1 Interrupt/wake-up delay

If interrupt or wake-up events occur very frequently while the transceiver is in CAN Offline mode, they can have a significant impact on the software processing time (because pin RXD is repeatedly driven LOW, requiring a response from the microcontroller each time an interrupt/wake-up is generated). The UJA1167A incorporates an event delay timer to limit the disturbance to the software.

When one of the event capture status bits is cleared, pin RXD is released (HIGH) and a timer is started. If further events occur while the timer is running, the relevant status bits are set. If one or more events are pending when the timer expires after $t_{d(event)}$, pin RXD goes LOW again to alert the microcontroller.

In this way, the microcontroller is interrupted once to process a number of events rather than several times to process individual events.

If all events are cleared while the timer is running, RXD remains HIGH after the timer expires, since there are no pending events. The event capture registers can be read at any time.

The event capture delay timer is stopped immediately when pin RSTN goes low (triggered by a HIGH-to-LOW transition on the pin). RSTN is driven LOW when the SBC enters Reset, Sleep, Overtemp and Off modes. A pending event is signaled on pin RXD when the SBC enters Sleep mode.

7.10.2 Sleep mode protection

The wake-up event capture function is critical when the UJA1167A is in Sleep mode, because the SBC will only leave Sleep mode in response to a captured wake-up event. To avoid potential system deadlocks, the SBC distinguishes between regular and diagnostic events (see [Section 7.10](#)). Wake-up events (via the CAN bus or the WAKE pin) are classified as regular events; diagnostic events signal failure/error conditions or state

changes. At least one regular wake-up event must be enabled before the UJA1167A can switch to Sleep mode. Any attempt to enter Sleep mode while all regular wake-up events are disabled will trigger a system reset.

Another condition that must be satisfied before the UJA1167A can switch to Sleep mode is that all event status bits must be cleared. If an event is pending when the SBC receives a Sleep mode command (MC = 001), it will immediately switch to Reset mode. This condition applies to both regular and diagnostic events.

Sleep mode can be permanently disabled in applications where, for safety reasons, the supply voltage to the host controller must never be cut off. Sleep mode is permanently disabled by setting the Sleep control bit (SLPC) in the SBC configuration register (see [Table 9](#)) to 1. This register is located in the non-volatile memory area of the device. When SLPC = 1, a Sleep mode SPI command (MC = 001) will trigger an SPI failure event instead of a transition to Sleep mode.

7.10.3 Event status and event capture registers

After an event source has been identified, the status flag should be cleared (set to 0) by writing 1 to the relevant status bit (writing 0 will have no effect).

Table 20. Global event status register (address 60h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7:4 | reserved | R | - | |
| 3 | WPE | R | 0 | no pending WAKE pin event |
| | | | 1 | WAKE pin event pending at address 0x64 |
| 2 | TRXE | R | 0 | no pending transceiver event |
| | | | 1 | transceiver event pending at address 0x63 |
| 1 | SUPE | R | 0 | no pending supply event |
| | | | 1 | supply event pending at address 0x62 |
| 0 | SYSE | R | 0 | no pending system event |
| | | | 1 | system event pending at address 0x61 |

Table 21. System event status register (address 61h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|--|
| 7:5 | reserved | R | - | |
| 4 | PO | R/W | 0 | no recent power-on |
| | | | 1 | the UJA1167A has left Off mode after power-on |
| 3 | reserved | R | - | |
| 2 | OTW | R/W | 0 | overtemperature not detected |
| | | | 1 | the global chip temperature has exceeded the overtemperature warning threshold ($T_{th(warn)otp}$) |
| 1 | SPIF | R/W | 0 | no SPI failure detected |
| | | | 1 | SPI failure detected |
| 0 | WDF | R/W | 0 | no watchdog failure event captured |
| | | | 1 | watchdog failure event captured |

Table 22. Supply event status register (address 62h)

| Bit | Symbol | Access | Value | Description |
|-----|----------------------|--------|-------|-------------------------------------|
| 7:3 | reserved | R | - | |
| 2 | VEXTO ^[1] | R/W | 0 | no VEXT overvoltage event captured |
| | | | 1 | VEXT overvoltage event captured |
| 1 | VEXTU ^[1] | R/W | 0 | no VEXT undervoltage event captured |
| | | | 1 | VEXT undervoltage event captured |
| 0 | V1U | R/W | 0 | no V1 undervoltage event captured |
| | | | 1 | V1 undervoltage event captured |

[1] UJA1167ATK/X only; reserved in the UJA1167ATK.

Table 23. Transceiver event status register (address 63h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7:5 | reserved | R | - | |
| 4 | CBS | R/W | 0 | CAN bus active |
| | | | 1 | no activity on CAN bus for $t_{to(silence)}$ |
| 3:2 | reserved | R | - | |
| 1 | CF | R/W | 0 | no CAN failure detected |
| | | | 1 | (CMC = 01 & CAN transceiver deactivated due to V1 undervoltage) OR dominant clamped TXD |
| 0 | CW | R/W | 0 | no CAN wake-up event detected |
| | | | 1 | CAN wake-up event detected while the transceiver is in CAN Offline Mode |

Table 24. WAKE pin event capture status register (address 64h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|--------------------------------------|
| 7:2 | reserved | R | - | |
| 1 | WPR | R/W | 0 | no rising edge detected on WAKE pin |
| | | | 1 | rising edge detected on WAKE pin |
| 0 | WPF | R/W | 0 | no falling edge detected on WAKE pin |
| | | | 1 | falling edge detected on WAKE pin |

Table 25. System event capture enable register (address 04h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|--|
| 7:3 | reserved | R | - | |
| 2 | OTWE | R/W | | overtemperature warning event capture: |
| | | | 0 | overtemperature warning disabled |
| | | | 1 | overtemperature warning enabled |
| 1 | SPIFE | R/W | | SPI failure detection: |
| | | | 0 | SPI failure detection disabled |
| | | | 1 | SPI failure detection enabled |
| 0 | reserved | R | - | |

Table 26. Supply event capture enable register (address 1Ch)

| Bit | Symbol | Access | Value | Description |
|-----|-----------------------|--------|-------|--------------------------------------|
| 7:3 | reserved | R | - | |
| 2 | VEXTOE ^[1] | R/W | | VEXT overvoltage detection: |
| | | | 0 | VEXT overvoltage detection disabled |
| | | | 1 | VEXT overvoltage detection enabled |
| 1 | VEXTUE ^[1] | R/W | | VEXT undervoltage detection: |
| | | | 0 | VEXT undervoltage detection disabled |
| | | | 1 | VEXT undervoltage detection enabled |
| 0 | V1UE | R/W | | V1 undervoltage detection: |
| | | | 0 | V1 undervoltage detection disabled |
| | | | 1 | V1 undervoltage detection enabled |

[1] UJA1167ATK/X only; reserved in the UJA1167ATK.

Table 27. Transceiver event capture enable register (address 23h)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|------------------------------------|
| 7:5 | reserved | R | - | |
| 4 | CBSE | R/W | | CAN bus silence detection: |
| | | | 0 | CAN bus silence detection disabled |
| | | | 1 | CAN bus silence detection enabled |
| 3:2 | reserved | R | - | |
| 1 | CFE | R/W | | CAN failure detection |
| | | | 0 | CAN failure detection disabled |
| | | | 1 | CAN failure detection enabled |
| 0 | CWE | R/W | | CAN wake-up detection: |
| | | | 0 | CAN wake-up detection disabled |
| | | | 1 | CAN wake-up detection enabled |

Table 28. WAKE pin event capture enable register (address 4Ch)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7:2 | reserved | R | - | |
| 1 | WPRE | R/W | | rising-edge detection on WAKE pin: |
| | | | 0 | rising-edge detection on WAKE pin disabled |
| | | | 1 | rising-edge detection on WAKE pin enabled |
| 0 | WPFE | R/W | | falling-edge detection on WAKE pin: |
| | | | 0 | falling-edge detection on WAKE pin disabled |
| | | | 1 | falling-edge detection on WAKE pin enabled |

7.11 Non-volatile SBC configuration

The UJA1167A contains Multiple Time Programmable Non-Volatile (MTPNV) memory cells that allow some of the default device settings to be reconfigured. The MTPNV memory address range is from 0x73 to 0x74. An overview of the MTPNV registers is given in [Table 29](#).

Table 29. Overview of MTPNV registers

| Address | Register Name | Bit: | | | | | | | |
|---------|---|----------|---|---------|---|---------|----------|----------|------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x73 | Start-up control (see Table 12) | reserved | | RLC | | VEXTSUC | reserved | | |
| 0x74 | SBC configuration control (see Table 9) | reserved | | V1RTSUC | | FNMC | SDMC | reserved | SLPC |

7.11.1 Programming MTPNV cells

The UJA1167A must be in Forced Normal mode and the MTPNV cells must contain the factory preset values before the non-volatile memory can be reprogrammed. The UJA1167A will switch to Forced Normal mode after a reset event (e.g. pin RSTN LOW) when the MTPNV cells contain the factory preset values (since FNMC = 1).

The factory presets may need to be restored before reprogramming can begin (see [Section 7.11.2](#)). When the factory presets have been restored, a system reset is generated automatically and UJA1167A switches to Forced Normal mode. This ensures that the programming cycle cannot be interrupted by the watchdog.

Programming of the non-volatile memory registers is performed in two steps. First, the required values are written to addresses 0x73 and 0x74. In the second step, reprogramming is confirmed by writing the correct CRC value to the MTPNV CRC control register (see [Section 7.11.1.1](#)). The SBC starts reprogramming the MTPNV cells as soon as the CRC value has been validated. If the CRC value is not correct, reprogramming is aborted. On completion, a system reset is generated to indicate that the MTPNV cells have been reprogrammed successfully. Note that the MTPNV cells cannot be read while they are being reprogrammed.

After an MTPNV programming cycle has been completed, the non-volatile memory is protected from being overwritten via a standard SPI write operation.

The MTPNV cells can be reprogrammed a maximum of 200 times ($N_{cy(W)MTP}$; see [Table 47](#)). Bit NVMP5 in the MTPNV status register ([Table 30](#)) indicates whether the non-volatile cells can be reprogrammed. This register also contains a write counter, WRCNTS, that is incremented each time the MTPNV cells are reprogrammed (up to a maximum value of 111111; there is no overflow; performing a factory reset also increments the counter). This counter is provided for information purposes only; reprogramming will not be rejected when it reaches its maximum value.

An error correction code status bit, ECCS, is set to indicate that the CRC check mechanism in the SBC has detected a single bit failure in non-volatile memory. If more than one bit failure is detected, the SBC will not restart after MTPNV reprogramming. Check the ECCS flag at the end of the production cycle to verify the content of non-volatile memory. When this flag is set, it indicates a device or ECU failure.

Table 30. MTPNV status register (address 70h)

| Bit | Symbol | Access | Value | Description |
|-----|--------|--------|------------------|---|
| 7:2 | WRCNTS | R | xxxxxx | write counter status: contains the number of times the MTPNV cells were reprogrammed |
| 1 | ECCS | R | 0 | error correction code status: no bit failure detected in non-volatile memory |
| | | | 1 | bit failure detected and corrected in non-volatile memory |
| 0 | NVMPS | R | 0 | non-volatile memory programming status: MTPNV memory cannot be overwritten |
| | | | 1 ^[1] | MTPNV memory is ready to be reprogrammed |

[1] Factory preset value.

7.11.1.1 Calculating the CRC value for MTP programming

The cyclic redundancy check value stored in bits CRCC in the MTPNV CRC control register is calculated using the data written to registers 0x73 and 0x74.

Table 31. MTPNV CRC control register (address 75h)

| Bit | Symbol | Access | Value | Description |
|-----|--------|--------|-------|------------------|
| 7:0 | CRCC | R/W | - | CRC control data |

The CRC value is calculated using the data representation shown in Figure 7 and the modulo-2 division with the generator polynomial: $X^8 + X^5 + X^3 + X^2 + X + 1$. The result of this operation must be bitwise inverted.

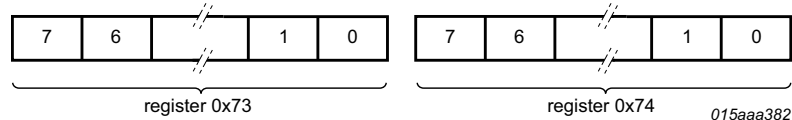


Figure 7. Data representation for CRC calculation

The following parameters can be used to calculate the CRC value (e.g. via the Autosar method):

Table 32. Parameters for CRC coding

| Parameter | Value |
|-----------------------|--------|
| CRC result width | 8 bits |
| Polynomial | 0x2F |
| Initial value | 0xFF |
| Input data reflected | no |
| Result data reflected | no |
| XOR value | 0xFF |

Alternatively, the following algorithm can be used:

```
data = 0 // unsigned byte
crc = 0xFF
```



```

for i = 0 to 1
    data = content_of_address(0x73 + i) EXOR crc
    for j = 0 to 7
        if data ≥ 128
            data = data * 2 // shift left by 1
            data = data EXOR 0x2F
        else
            data = data * 2 // shift left by 1
        next j
    crc = data
next i
crc = crc EXOR 0xFF

```

7.11.2 Restoring factory preset values

Factory preset values are restored if the following conditions apply for at least $t_{d(MTPNV)}$ during power-up:

- pin RSTN is held LOW
- CANH is pulled up to V_{BAT}
- CANL is pulled down to GND

After the factory preset values have been restored, the SBC performs a system reset and enters Forced normal Mode. Since the CAN bus is clamped dominant, pin RXDC is forced LOW. During the factory preset restore process, this pin is forced HIGH; a falling edge on this pin caused by bit PO being set after power-on then clearly indicates that the process has been completed.

Note that the write counter, WRCNTS, in the MTPNV status register is incremented every time the factory presets are restored.

7.12 Device ID

A byte is reserved at address 0x7E for a UJA1167A identification code.

Table 33. Identification register (address 7Eh)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|--|
| 7:0 | IDS[7:0] | R | D8h | device identification code - UJA1167ATK |
| | | | C8h | device identification code -UJA1167ATK/X |

7.13 Lock control register

Sections of the register address area can be write-protected to protect against unintended modifications. Note that this facility only protects locked bits from being modified via the SPI and will not prevent the UJA1167A updating status registers etc.

Table 34. Lock control register (address 0Ah)

| Bit | Symbol | Access | Value | Description |
|-----|----------|--------|-------|---|
| 7 | reserved | R | - | cleared for future use |
| 6 | LK6C | R/W | | lock control 6: address area 0x68 to 0x6F |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |

Table 34. Lock control register (address 0Ah)

| Bit | Symbol | Access | Value | Description |
|-----|--------|--------|-------|--|
| 5 | LK5C | R/W | | lock control 5: address area 0x50 to 0x5F |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |
| 4 | LK4C | R/W | | lock control 4: address area 0x40 to 0x4F - WAKE pin control |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |
| 3 | LK3C | R/W | | lock control 3: address area 0x30 to 0x3F |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |
| 2 | LK2C | R/W | | lock control 2: address area 0x20 to 0x2F - transceiver control |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |
| 1 | LK1C | R/W | | lock control 1: address area 0x10 to 0x1F - regulator control |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |
| 0 | LK0C | R/W | | lock control 0: address area 0x06 to 0x09 - general purpose memory |
| | | | 0 | SPI write-access enabled |
| | | | 1 | SPI write-access disabled |

7.14 General purpose memory

UJA1167A allocates 4 bytes of RAM as general purpose registers for storing user information. The general purpose registers can be accessed via the SPI at address 0x06 to 0x09 (see [Table 35](#)).

7.15 SPI

7.15.1 Introduction

The Serial Peripheral Interface (SPI) provides the communication link with the microcontroller, supporting multi-slave operations. The SPI is configured for full duplex data transfer, so status information is returned when new control data is shifted in. The interface also offers a read-only access option, allowing registers to be read back by the application without changing the register content.

The SPI uses four interface signals for synchronization and data transfer:

- SCSN: SPI chip select; active LOW
- SCK: SPI clock; default level is LOW due to low-power concept (pull-down)
- SDI: SPI data input
- SDO: SPI data output; floating when pin SCSN is HIGH

Bit sampling is performed on the falling edge of the clock and data is shifted in/out on the rising edge, as illustrated in [Figure 8](#).

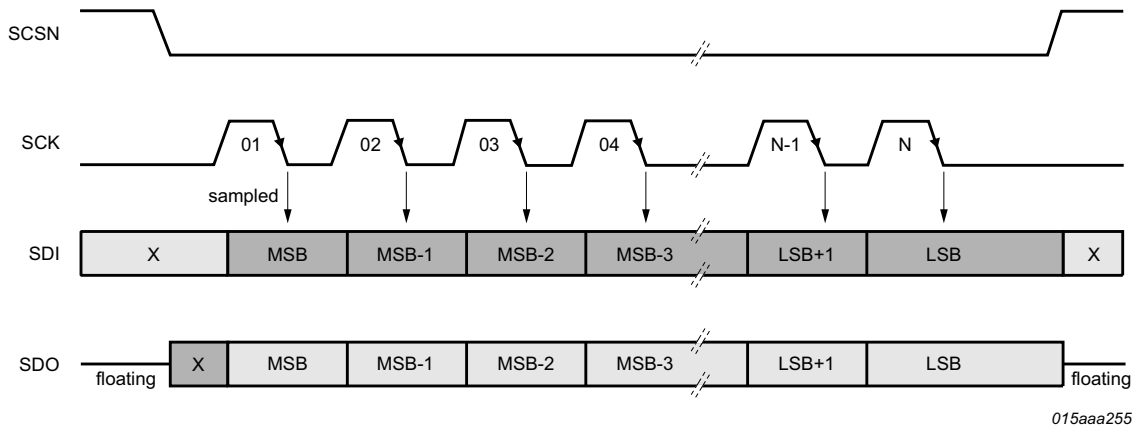


Fig 8. SPI timing protocol

The SPI data in the UJA1167A is stored in a number of dedicated 8-bit registers. Each register is assigned a unique 7-bit address. Two bytes must be transmitted to the SBC for a single register write operation. The first byte contains the 7-bit address along with a 'read-only' bit (the LSB). The read-only bit must be 0 to indicate a write operation (if this bit is 1, a read operation is assumed and any data on the SDI pin is ignored). The second byte contains the data to be written to the register.

24- and 32-bit read and write operations are also supported. The register address is automatically incremented, once for a 24-bit operation and twice for a 32-bit operation, as illustrated in Figure 9.

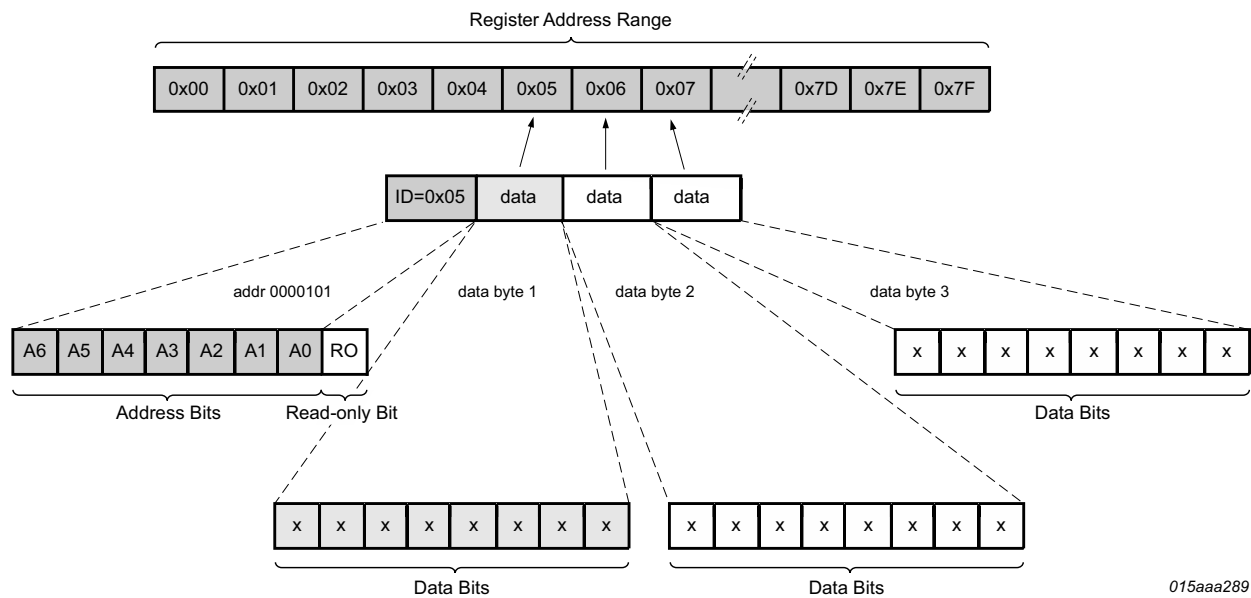


Fig 9. SPI data structure for a write operation (16-, 24- or 32-bit)

During an SPI data read or write operation, the contents of the addressed register(s) is returned via pin SDO.

The UJA1167A tolerates attempts to write to registers that don't exist. If the available address space is exceeded during a write operation, the data above the valid address range is ignored (without generating an SPI failure event).

During a write operation, the UJA1167A monitors the number of SPI bits transmitted. If the number recorded is not 16, 24 or 32, then the write operation is aborted and an SPI failure event is captured (SPIF = 1).

If more than 32 bits are clocked in on pin SDI during a read operation, the data stream on SDI is reflected on SDO from bit 33 onwards.

7.15.2 Register map

The addressable register space contains 128 registers with addresses from 0x00 to 0x7F. An overview of the register mapping is provided in [Table 35](#) to [Table 43](#). The functionality of individual bits is discussed in more detail in relevant sections of the data sheet.

Table 35. Overview of primary control registers

| Address | Register Name | Bit: | | | | | | | |
|---------|---------------------|------------|------|------|----------|------|------|-------|----------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x00 | Watchdog control | WMC | | | reserved | NWP | | | |
| 0x01 | Mode control | reserved | | | | | MC | | |
| 0x03 | Main status | reserved | OTWS | NMS | RSS | | | | |
| 0x04 | System event enable | reserved | | | | | OTWE | SPIFE | reserved |
| 0x05 | Watchdog status | reserved | | | | FNMS | SDMS | WDS | |
| 0x06 | Memory 0 | GPM[7:0] | | | | | | | |
| 0x07 | Memory 1 | GPM[15:8] | | | | | | | |
| 0x08 | Memory 2 | GPM[23:16] | | | | | | | |
| 0x09 | Memory 3 | GPM[31:24] | | | | | | | |
| 0x0A | Lock control | reserved | LK6C | LK5C | LK4C | LK3C | LK2C | LK1C | LK0C |

Table 36. Overview of V1 and INH/VEXT and transceiver control registers

| Address | Register Name | Bit: | | | | | | | |
|---------|--------------------------|----------|----------|---|------|----------|----------|--------|------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x10 | V1 and INH/VEXT control | reserved | | | | VEXTC | | V1RTC | |
| 0x1B | Supply status | reserved | | | | | VEXTS | | V1S |
| 0x1C | Supply event enable | reserved | | | | | VEXTOE | VEXTUE | V1UE |
| 0x20 | CAN control | reserved | | | | | | | CMC |
| 0x22 | Transceiver status | CTS | reserved | | | CBSS | reserved | VCS | CFS |
| 0x23 | Transceiver event enable | reserved | | | CBSE | reserved | | CFE | CWE |

Table 37. Overview of WAKE pin control and status registers

| Address | Register Name | Bit: | | | | | | | |
|---------|-----------------|----------|---|---|---|---|---|------|----------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x4B | WAKE pin status | reserved | | | | | | WPVS | reserved |
| 0x4C | WAKE pin enable | reserved | | | | | | WPRE | WPFE |

Table 38. Overview of event capture registers

| Address | Register Name | Bit: | | | | | | | |
|---------|--------------------------|----------|---|---|-----|----------|-------|-------|------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x60 | Global event status | reserved | | | | WPE | TRXE | SUPE | SYSE |
| 0x61 | System event status | reserved | | | PO | reserved | OTW | SPIF | WDF |
| 0x62 | Supply event status | reserved | | | | | VEXTO | VEXTU | V1U |
| 0x63 | Transceiver event status | reserved | | | CBS | reserved | | CF | CW |
| 0x64 | WAKE pin event status | reserved | | | | | | WPR | WPF |

Table 39. Overview of MTPNV status register

| Address | Register Name | Bit: | | | | | | | |
|---------|---------------|--------|---|---|---|---|---|------|-------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x70 | MTPNV status | WRCNTS | | | | | | ECCS | NVMPS |

Table 40. Overview of Startup control register

| Address | Register Name | Bit: | | | | | | | |
|---------|-----------------|----------|---|-----|---|---------|---|----------|---|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x73 | Startup control | reserved | | RLC | | VEXTSUC | | reserved | |

Table 41. Overview of SBC configuration control register

| Address | Register Name | Bit: | | | | | | | |
|---------|---------------------------|----------|---|---------|---|------|------|----------|------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x74 | SBC configuration control | reserved | | V1RTSUC | | FNMC | SDMC | reserved | SLPC |

Table 42. Overview of CRC control register

| Address | Register Name | Bit: | | | | | | | |
|---------|-------------------|-----------|---|---|---|---|---|---|---|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x75 | MTPNV CRC control | CRCC[7:0] | | | | | | | |

Table 43. Overview of Identification register

| Address | Register Name | Bit: | | | | | | | |
|---------|----------------|----------|---|---|---|---|---|---|---|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0x7E | Identification | IDS[7:0] | | | | | | | |

7.15.3 Register configuration in UJA1167A operating modes

A number of register bits may change state automatically when the UJA1167A switches from one operating mode to another. This is particularly evident when the UJA1167A switches to Off mode. These changes are summarized in [Table 44](#). If an SPI transmission is in progress when the UJA1167A changes state, the transmission is ignored (automatic state changes have priority).

Table 44. Register bit settings in UJA1167A operating modes

| Symbol | Off (power-on default) | Standby | Normal | Sleep | Overtemp | Reset |
|--------|------------------------|--------------|--------------|--------------|--------------|--------------|
| CBS | 0 | no change | no change | no change | no change | no change |
| CBSE | 0 | no change | no change | no change | no change | no change |
| CBSS | 1 | actual state | actual state | no change | actual state | actual state |
| CF | 0 | no change | no change | no change | no change | no change |
| CFE | 0 | no change | no change | no change | no change | no change |
| CFS | 0 | actual state | actual state | actual state | actual state | actual state |
| CMC | 00 | no change | no change | no change | no change | no change |
| CRCC | 00000000 | no change | no change | no change | no change | no change |
| CTS | 0 | 0 | actual state | 0 | 0 | 0 |
| CW | 0 | no change | no change | no change | no change | no change |

Table 44. Register bit settings in UJA1167A operating modes ...continued

| Symbol | Off (power-on default) | Standby | Normal | Sleep | Overtemp | Reset |
|-----------------------|------------------------------|--------------|--------------|--------------|--------------|--------------|
| CWE | 0 | no change | no change | no change | no change | no change |
| ECCS | actual state | actual state | actual state | actual state | actual state | actual state |
| FNMC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| FNMS | 0 | actual state | actual state | actual state | actual state | actual state |
| GPMn | 00000000 | no change | no change | no change | no change | no change |
| IDS | see Table 33 | no change | no change | no change | no change | no change |
| LKnC | 0 | no change | no change | no change | no change | no change |
| MC | 100 | 100 | 111 | 001 | don't care | 100 |
| NMS | 1 | no change | 0 | no change | no change | no change |
| NVMPs | actual state | actual state | actual state | actual state | actual state | actual state |
| NWP | 0100 | no change | no change | no change | 0100 | 0100 |
| OTW | 0 | no change | no change | no change | no change | no change |
| OTWE | 0 | no change | no change | no change | no change | no change |
| OTWS | 0 | actual state | actual state | actual state | actual state | actual state |
| PO | 1 | no change | no change | no change | no change | no change |
| RLC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| RSS | 00000 | no change | no change | no change | 10010 | reset source |
| SDMC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| SDMS | 0 | actual state | actual state | actual state | actual state | actual state |
| SLPC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| SPIF | 0 | no change | no change | no change | no change | no change |
| SPIFE | 0 | no change | no change | no change | no change | no change |
| SUPE | 0 | no change | no change | no change | no change | no change |
| SYSE | 1 | no change | no change | no change | no change | no change |
| TRXE | 0 | no change | no change | no change | no change | no change |
| V1RTC | defined by V1RTSUC | no change | no change | no change | no change | no change |
| V1RTSUC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| V1S | 0 | actual state | actual state | actual state | actual state | actual state |
| V1UE | 0 | no change | no change | no change | no change | no change |
| V1U | 0 | no change | no change | no change | no change | no change |
| VCS | 0 | actual state | actual state | actual state | actual state | actual state |
| VEXTC | defined by VEXTSUC | no change | no change | no change | no change | no change |
| VEXTO ^[1] | 0 | no change | no change | no change | no change | no change |
| VEXTOE ^[1] | 0 | no change | no change | no change | no change | no change |
| VEXTS ^[1] | 00 | actual state | actual state | actual state | actual state | actual state |
| VEXTSUC | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV | MTPNV |
| VEXTU ^[1] | 0 | no change | no change | no change | no change | no change |
| VEXTUE ^[1] | 0 | no change | no change | no change | no change | no change |
| WDF | 0 | no change | no change | no change | no change | no change |

Table 44. Register bit settings in UJA1167A operating modes ...continued

| Symbol | Off (power-on default) | Standby | Normal | Sleep | Overtemp | Reset |
|--------|------------------------|--------------|--------------|--------------|--------------|--------------|
| WDS | 0 | actual state | actual state | actual state | actual state | actual state |
| WMC | [2] | no change | no change | no change | no change | [2] |
| WPE | 0 | no change | no change | no change | no change | no change |
| WPF | 0 | no change | no change | no change | no change | no change |
| WPR | 0 | no change | no change | no change | no change | no change |
| WPFE | 0 | no change | no change | no change | no change | no change |
| WPRE | 0 | no change | no change | no change | no change | no change |
| WPVS | 0 | no change | no change | no change | no change | no change |
| WRCNTS | actual state | actual state | actual state | actual state | actual state | actual state |

[1] UJA1167ATK/X only.

[2] 001 if SDMC = 1; otherwise 010.

8. Limiting values

Table 45. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------------|---------------------------------------|---|------|-----------------------|------|
| V _x | voltage on pin x ^[1] | pin V1 ^[2] | −0.2 | +6 | V |
| | | pins TXD, RXD, SDI, SDO, SCK, SCSN, RSTN ^[3] | −0.2 | V _{V1} + 0.2 | V |
| | | pins INH, VEXT, WAKE | −18 | +40 | V |
| | | pin BAT | −0.2 | +40 | V |
| | | pins CANH and CANL with respect to any other pin | −58 | +58 | V |
| V _(CANH-CANL) | voltage between pin CANH and pin CANL | | −40 | +40 | V |
| V _{trt} | transient voltage | on pins CANL, CANH, WAKE, VEXT, BAT ^[4] | | | |
| | | pulse 1 | −100 | - | V |
| | | pulse 2a | - | 75 | V |
| | | pulse 3a | −150 | - | V |
| | | pulse 3b | - | 100 | V |
| V _{ESD} | electrostatic discharge voltage | IEC 61000-4-2 (150 pF, 330 Ω) discharge circuit ^[5] | | | |
| | | on pins CANH and CANL; pin BAT with capacitor; pin WAKE with 10 nF capacitor and 10 kΩ resistor; pin VEXT with 2.2 μF capacitor | −6 | +6 | kV |
| | | Human Body Model (HBM) | | | |
| | | on any pin ^[6] | −2 | +2 | kV |
| | | on pins BAT, WAKE, VEXT ^[7] | −4 | +4 | kV |
| | | on pins CANH, CANL ^[8] | −8 | +8 | kV |
| | | Machine Model (MM) ^[9] | | | |
| | | on any pin | −100 | +100 | V |
| | | Charged Device Model (CDM) ^[10] | | | |
| | | on corner pins | −750 | +750 | V |
| | | on any other pin | −500 | +500 | V |
| T _{vj} | virtual junction temperature | ^[11] | −40 | +150 | °C |
| | | when programming the MTPNV cells | 0 | +125 | °C |
| T _{stg} | storage temperature | | −55 | +150 | °C |

- [1] The device can sustain voltages up to the specified values over the product lifetime, provided applied voltages (including transients) never exceed these values.
- [2] When the device is not powered up, I_{V1} (max) = 25 mA.
- [3] Maximum voltage should never exceed 6 V.
- [4] Verified by an external test house according to IEC TS 62228, Section 4.2.4; parameters for standard pulses defined in ISO7637 part 2.
- [5] Verified by an external test house according to IEC TS 62228, Section 4.3.
- [6] According to AEC-Q100-002.
- [7] Pins stressed to reference group containing all grounds, emulating the application circuit (Figure 14). HBM pulse as specified in AEC-Q100-002 used.
- [8] Pins stressed to reference group containing all ground and supply pins, emulating the application circuit (Figure 14). HBM pulse as specified in AEC-Q100-002 used.
- [9] According to AEC-Q100-003.

[10] According to AEC-Q100-011.

[11] In accordance with IEC 60747-1. An alternative definition of virtual junction temperature is: $T_{vj} = T_{amb} + P \times R_{th(j-a)}$, where $R_{th(j-a)}$ is a fixed value used in the calculation of T_{vj} . The rating for T_{vj} limits the allowable combinations of power dissipation (P) and ambient temperature (T_{amb}).

9. Thermal characteristics

Table 46. Thermal characteristics

| Symbol | Parameter | Conditions | Typ | Unit |
|----------------|---|-----------------------------|-----|------|
| $R_{th(vj-a)}$ | thermal resistance from virtual junction to ambient | HVSON14 [1] | 60 | K/W |

[1] According to JEDEC JESD51-2, JESD51-5 and JESD51-7 at natural convection on 2s2p board. Board with two inner copper layers (thickness: 35 μm) and thermal via array under the exposed pad connected to the first inner copper layer (thickness: 70 μm).

10. Static characteristics

Table 47. Static characteristics

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [\[1\]](#)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------|---------------------------------------|---|-----|---------------------|------|---------------|
| Supply; pin BAT | | | | | | |
| $V_{th(det)pon}$ | power-on detection threshold voltage | V_{BAT} rising | 4.2 | - | 4.55 | V |
| $V_{th(det)poff}$ | power-off detection threshold voltage | V_{BAT} falling | 2.8 | - | 3 | V |
| $V_{uvr(CAN)}$ | CAN undervoltage recovery voltage | V_{BAT} rising | 4.5 | - | 5 | V |
| $V_{uvd(CAN)}$ | CAN undervoltage detection voltage | V_{BAT} falling | 4.2 | - | 4.55 | V |
| I_{BAT} | battery supply current | Normal mode; MC = 111; CAN Active mode | | | | |
| | | CAN recessive; $V_{TXD} = V_{V1}$ | - | 4 | 7.5 | mA |
| | | CAN dominant; $V_{TXD} = 0\text{ V}$ | - | 46 | 67 | mA |
| | | Sleep mode; MC = 001; CAN Offline mode; $V_{BAT} = 7\text{ V}$ to 18 V ; $-40\text{ }^{\circ}\text{C} < T_{vj} < 85\text{ }^{\circ}\text{C}$ | - | [2] | 65 | μA |
| | | Standby mode; MC = 100; CWE = 1; CAN Offline mode; $I_{V1} = 0\text{ }\mu\text{A}$; $V_{BAT} = 7\text{ V}$ to 18 V ; $-40\text{ }^{\circ}\text{C} < T_{vj} < 85\text{ }^{\circ}\text{C}$ | - | [2] | 91 | μA |
| | | additional current in CAN Offline Bias mode; $-40\text{ }^{\circ}\text{C} < T_{vj} < 85\text{ }^{\circ}\text{C}$ | - | 38 | 55 | μA |
| | | additional current from WAKE input; WPRE = WPFE = 1; $-40\text{ }^{\circ}\text{C} < T_{vj} < 85\text{ }^{\circ}\text{C}$ | | 2 | 3 | μA |

Table 47. Static characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|--|--|-----------------|-------|--------------|------------|
| Voltage source: pin V1 | | | | | | |
| V_O | output voltage | $V_{BAT} = 5.5\text{ V}$ to 28 V ; $I_{V1} = -120\text{ mA}$ to 0 mA ; $V_{TXD} = V_{V1}$ | 4.9 | 5 | 5.1 | V |
| | | $V_{BAT} = 5.65\text{ V}$ to 28 V ; $I_{V1} = -150\text{ mA}$ to 0 mA ; $V_{TXD} = V_{V1}$ | 4.9 | 5 | 5.1 | V |
| | | $V_{BAT} = 5.65\text{ V}$ to 28 V ; $I_{V1} = -100\text{ mA}$ to 0 mA ; $V_{TXD} = 0\text{ V}$; $V_{CANH} = 0\text{ V}$ | 4.9 | 5 | 5.1 | V |
| $\Delta V_{ret(RAM)}$ | RAM retention voltage difference | between V_{BAT} and V_{V1} | | | | |
| | | $V_{BAT} = 2\text{ V}$ to 3 V ; $I_{V1} = -2\text{ mA}$ | - | - | 100 | mV |
| | | $V_{BAT} = 2\text{ V}$ to 3 V ; $I_{V1} = -200\text{ }\mu\text{A}$ [3] | | | 10 | mV |
| $R_{(BAT-V1)}$ | resistance between pin BAT and pin V1 | $V_{BAT} = 4\text{ V}$ to 6 V ; $I_{V1} = -120\text{ mA}$ | - | - | 5 | Ω |
| | | $V_{BAT} = 3\text{ V}$ to 4 V ; $I_{V1} = -40\text{ mA}$ | - | 2.625 | - | Ω |
| V_{uvd} | undervoltage detection voltage | $V_{uvd(nom)} = 90\text{ }\%$ | 4.5 | - | 4.75 | V |
| | | $V_{uvd(nom)} = 80\text{ }\%$ | 4 | - | 4.25 | V |
| | | $V_{uvd(nom)} = 70\text{ }\%$ | 3.5 | - | 3.75 | V |
| | | $V_{uvd(nom)} = 60\text{ }\%$ | 3 | - | 3.25 | V |
| V_{uvr} | undervoltage recovery voltage | | 4.5 | - | 4.75 | V |
| $I_{O(sc)}$ | short-circuit output current | | -300 | - | -150 | mA |
| $I_{CAN(int)V1}$ | internal CAN supply current from V1 | Normal mode; MC = 111; CAN Active mode; CAN dominant; $V_{TXD} = 0\text{ V}$; short-circuit on bus lines; $-3\text{ V} < (V_{CANH} = V_{CANL}) < +18\text{ V}$ | - | - | 59 | mA |
| Voltage source: VEXT (UJA1167ATK/X only) | | | | | | |
| V_O | output voltage | $V_{BAT} = 6.5\text{ V}$ to 28 V ; $I_{VEXT} = -30\text{ mA}$ to 0 mA | 4.9 | 5 | 5.1 | V |
| V_{uvd} | undervoltage detection voltage | | 4.5 | - | 4.75 | V |
| V_{ovd} | overvoltage detection voltage | | 6.5 | - | 7 | V |
| $I_{O(sc)}$ | short-circuit output current | | -125 | - | -30 | mA |
| Voltage source: INH (UJA1167ATK only) | | | | | | |
| V_O | output voltage | $I_{INH} = -180\text{ }\mu\text{A}$ | $V_{BAT} - 0.8$ | - | V_{BAT} | V |
| R_{pd} | pull-down resistance | Sleep mode | 3 | 4 | 5 | M Ω |
| Serial peripheral interface inputs; pins SDI, SCK and SCSN | | | | | | |
| $V_{th(sw)}$ | switching threshold voltage | | $0.25V_{V1}$ | - | $0.75V_{V1}$ | V |
| $V_{th(sw)hys}$ | switching threshold voltage hysteresis | | $0.05V_{V1}$ | - | - | V |
| $R_{pd(SCK)}$ | pull-down resistance on pin SCK | | 40 | 60 | 80 | k Ω |
| $R_{pu(SCSN)}$ | pull-up resistance on pin SCSN | | 40 | 60 | 80 | k Ω |
| $R_{pd(SDI)}$ | pull-down resistance on pin SDI | $V_{SDI} < V_{th(sw)}$ | 40 | 60 | 80 | k Ω |
| $R_{pu(SDI)}$ | pull-up resistance on pin SDI | $V_{SDI} > V_{th(sw)}$ | 40 | 60 | 80 | k Ω |

Table 47. Static characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|--|---|----------------|-----|--------------|------------------|
| Serial peripheral interface data output; pin SDO | | | | | | |
| V_{OH} | HIGH-level output voltage | $I_{OH} = -4\text{ mA}$ | $V_{V1} - 0.4$ | - | - | V |
| V_{OL} | LOW-level output voltage | $I_{OL} = 4\text{ mA}$ | - | - | 0.4 | V |
| $I_{LO(off)}$ | off-state output leakage current | $V_{SCSN} = V_{V1}$; $V_O = 0\text{ V}$ to V_{V1} | -5 | - | +5 | μA |
| CAN transmit data input; pin TXD | | | | | | |
| $V_{th(sw)}$ | switching threshold voltage | | $0.25V_{V1}$ | - | $0.75V_{V1}$ | V |
| $V_{th(sw)hys}$ | switching threshold voltage hysteresis | | $0.05V_{V1}$ | - | - | V |
| R_{pu} | pull-up resistance | | 40 | 60 | 80 | $\text{k}\Omega$ |
| CAN receive data output; pin RXD | | | | | | |
| V_{OH} | HIGH-level output voltage | $I_{OH} = -4\text{ mA}$ | $V_{V1} - 0.4$ | - | - | V |
| V_{OL} | LOW-level output voltage | $I_{OL} = 4\text{ mA}$ | - | - | 0.4 | V |
| R_{pu} | pull-up resistance | CAN Offline mode | 40 | 60 | 80 | $\text{k}\Omega$ |
| Local wake input; pin WAKE | | | | | | |
| $V_{th(sw)r}$ | rising switching threshold voltage | | 2.8 | - | 4.1 | V |
| $V_{th(sw)f}$ | falling switching threshold voltage | | 2.4 | - | 3.75 | V |
| $V_{hys(i)}$ | input hysteresis voltage | | 250 | - | 800 | mV |
| I_i | input current | $T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ | - | - | 1.5 | μA |
| High-speed CAN bus lines; pins CANH and CANL | | | | | | |
| $V_{O(dom)}$ | dominant output voltage | CAN Active mode; $V_{TXD} = 0\text{ V}$; $t < t_{to(dom)TXD}$ | | | | |
| | | pin CANH; $R_L = 50\text{ }\Omega$ to $65\text{ }\Omega$ | 2.75 | 3.5 | 4.5 | V |
| | | pin CANL; $R_L = 50\text{ }\Omega$ to $65\text{ }\Omega$ | 0.5 | 1.5 | 2.25 | V |
| $V_{dom(TX)sym}$ | transmitter dominant voltage symmetry | $V_{dom(TX)sym} = V_{V1} - V_{CANH} - V_{CANL}$; $V_{V1} = 5\text{ V}$ | -400 | - | +400 | mV |
| V_{TXsym} | transmitter voltage symmetry | $V_{TXsym} = V_{CANH} + V_{CANL}$; [3] $f_{TXD} = 250\text{ kHz}$, 1 MHz or 2.5 MHz ; [4] $C_{SPLIT} = 4.7\text{ nF}$ | $0.9V_{V1}$ | - | $1.1V_{V1}$ | V |
| $V_{O(dif)}$ | differential output voltage | CAN Active mode (dominant); $V_{TXD} = 0\text{ V}$; $V_{V1} = 4.75\text{ V}$ to 5.5 V ; $t < t_{to(dom)TXD}$ | | | | |
| | | $R_L = 50\text{ }\Omega$ to $65\text{ }\Omega$ | 1.5 | - | 3 | V |
| | | $R_L = 45\text{ }\Omega$ to $70\text{ }\Omega$ | 1.4 | - | 3.3 | V |
| | | $R_L = 2240\text{ }\Omega$ | 1.5 | - | 5 | V |
| | | recessive; $R_L = \text{no load}$ | | | | |
| | | CAN Active/Listen-only/Offline Bias mode; $V_{TXD} = V_{V1}$ | -50 | - | +50 | mV |
| | | CAN Offline mode | -0.2 | - | +0.2 | V |

Table 47. Static characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------|--|---|-------------------|-------------|--------------------|---------------|
| $V_{O(rec)}$ | recessive output voltage | CAN Active mode; $V_{TXD} = V_{V1}$ $R_L = \text{no load}$ | 2 | $0.5V_{V1}$ | 3 | V |
| | | CAN Offline mode; $R_L = \text{no load}$ | -0.1 | - | +0.1 | V |
| | | CAN Offline Bias/Listen-only modes; $R_L = \text{no load}$ | 2 | 2.5 | 3 | V |
| $I_{O(sc)dom}$ | dominant short-circuit output current | CAN Active mode; $V_{TXD} = 0\text{ V}$; $V_{V1} = 5\text{ V}$ | | | | |
| | | pin CANH; $V_{CANH} = -3\text{ V}$ to $+27\text{ V}$ | -55 | - | - | mA |
| | | pin CANL; $V_{CANL} = -15\text{ V}$ to $+18\text{ V}$ | - | - | +55 | mA |
| $I_{O(sc)rec}$ | recessive short-circuit output current | $V_{CANL} = V_{CANH} = -27\text{ V}$ to $+32\text{ V}$; $V_{TXD} = V_{V1}$ | -3 | - | +3 | mA |
| $V_{th(RX)dif}$ | differential receiver threshold voltage | $-12\text{ V} \leq V_{CANL} \leq +12\text{ V}$; $-12\text{ V} \leq V_{CANH} \leq +12\text{ V}$ | | | | |
| | | CAN Active/Listen-only modes | 0.5 | 0.7 | 0.9 | V |
| | | CAN Offline mode | 0.4 | 0.7 | 1.15 | V |
| $V_{rec(RX)}$ | receiver recessive voltage | $-12\text{ V} \leq V_{CANL} \leq +12\text{ V}$; $-12\text{ V} \leq V_{CANH} \leq +12\text{ V}$ | | | | |
| | | CAN Active/Listen-only modes | -4 ^[3] | - | +0.5 | V |
| | | CAN Offline/Offline Bias modes | -4 ^[3] | - | +0.4 | V |
| $V_{dom(RX)}$ | receiver dominant voltage | $-12\text{ V} \leq V_{CANL} \leq +12\text{ V}$; $-12\text{ V} \leq V_{CANH} \leq +12\text{ V}$ | | | | |
| | | CAN Active/Listen-only modes | 0.9 | - | 9.0 ^[3] | V |
| | | CAN Offline/Offline Bias modes | 1.15 | - | 9.0 ^[3] | V |
| $V_{hys(RX)dif}$ | differential receiver hysteresis voltage | CAN Active/Listen-only modes; $-12\text{ V} \leq V_{CANL} \leq +12\text{ V}$; $-12\text{ V} \leq V_{CANH} \leq +12\text{ V}$ | 1 | 30 | 60 | mV |
| R_i | input resistance | $-2\text{ V} \leq V_{CANL} \leq +7\text{ V}$; $-2\text{ V} \leq V_{CANH} \leq +7\text{ V}$ | 9 | 15 | 28 | k Ω |
| ΔR_i | input resistance deviation | $0\text{ V} \leq V_{CANL} \leq +5\text{ V}$; $0\text{ V} \leq V_{CANH} \leq +5\text{ V}$ | -1 | - | +1 | % |
| $R_{i(dif)}$ | differential input resistance | $-2\text{ V} \leq V_{CANL} \leq +7\text{ V}$; $-2\text{ V} \leq V_{CANH} \leq +7\text{ V}$ | 19 | 30 | 52 | k Ω |
| $C_{i(cm)}$ | common-mode input capacitance | ^[3] | - | - | 20 | pF |
| $C_{i(dif)}$ | differential input capacitance | ^[3] | - | - | 10 | pF |
| I_L | leakage current | $V_{BAT} = V_{V1} = 0\text{ V}$ or $V_{BAT} = V_{V1} = \text{shorted to ground via } 47\text{ k}\Omega$; $V_{CANH} = V_{CANL} = 5\text{ V}$ | -5 | - | +5 | μA |

Temperature protection

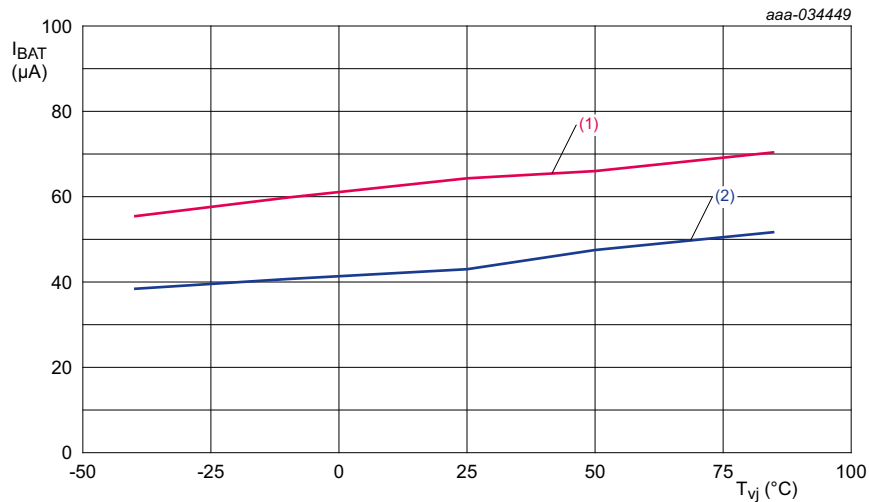
| | | | | | | |
|------------------|---|--|-----|-----|-----|--------------------|
| $T_{th(act)otp}$ | overtemperature protection activation threshold temperature | | 167 | 177 | 187 | $^{\circ}\text{C}$ |
|------------------|---|--|-----|-----|-----|--------------------|

Table 47. Static characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------------------|--|---|--------------|-----|--------------|--------------------|
| $T_{th(rel)otp}$ | overtemperature protection release threshold temperature | | 127 | 137 | 147 | $^{\circ}\text{C}$ |
| $T_{th(warn)otp}$ | overtemperature protection warning threshold temperature | | 127 | 137 | 147 | $^{\circ}\text{C}$ |
| Reset output; pin RSTN | | | | | | |
| V_{OL} | LOW-level output voltage | $V_{V1} = 1.0\text{ V}$ to 5.5 V ; pull-up resistor to $V_{V1} \geq 900\text{ }\Omega$ | 0 | - | $0.2V_{V1}$ | V |
| R_{pu} | pull-up resistance | | 40 | 60 | 80 | $k\Omega$ |
| $V_{th(sw)}$ | switching threshold voltage | | $0.25V_{V1}$ | - | $0.75V_{V1}$ | V |
| $V_{th(sw)hys}$ | switching threshold voltage hysteresis | | $0.05V_{V1}$ | - | - | V |
| MTP non-volatile memory | | | | | | |
| $N_{cy(W)MTP}$ | number of MTP write cycles | $V_{BAT} = 6\text{ V}$ to 28 V ; $T_{vj} = 0\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$ | - | - | 200 | - |

- [1] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.
- [2] See [Figure 10](#).
- [3] Not tested in production; guaranteed by design.
- [4] The test circuit used to measure the bus output voltage symmetry (which includes C_{SPLIT}) is shown in [Figure 17](#).



(1) Standby Mode: MC = 100, CWE = 1, CAN Offline mode, $V_{BAT} = 12\text{ V}$, $I_{V1} = 0\text{ }\mu\text{A}$.

(2) Sleep mode: MC = 001, CAN Offline mode, $V_{BAT} = 12\text{ V}$.

Fig 10. UJA1167A typical Standby and Sleep mode quiescent current (μA)

11. Dynamic characteristics

Table 48. Dynamic characteristics

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|--|---|-----|-----|-----|---------------|
| Voltage source; pin V1 | | | | | | |
| $t_{startup}$ | start-up time | from V_{BAT} exceeding the power-on detection threshold until V_{V1} exceeds the 90 % undervoltage threshold; $C_{V1} = 4.7\text{ }\mu\text{F}$ | - | 2.8 | 4.7 | ms |
| $t_{d(uvd)}$ | undervoltage detection delay time | | 6 | - | 54 | μs |
| $t_{d(uvd-RSTNL)}$ | delay time from undervoltage detection to RSTN LOW | undervoltage on V1 | - | - | 63 | μs |
| $t_{d(buswake-VOH)}$ | delay time from bus wake-up to HIGH-level output voltage | HIGH = $0.8V_{O(V1)}$; $I_{V1} \leq 100\text{ mA}$ | - | - | 5 | ms |
| Voltage source; pin VEXT | | | | | | |
| $t_{d(uvd)}$ | undervoltage detection delay time | | 6 | - | 39 | μs |
| $t_{d(ovd)}$ | overvoltage detection delay time | | 6 | - | 39 | μs |
| Serial peripheral interface timing; pins SCSN, SCK, SDI and SDO; see Figure 13 | | | | | | |
| $t_{cy(clk)}$ | clock cycle time | | 250 | - | - | ns |
| $t_{SPILEAD}$ | SPI enable lead time | | 50 | - | - | ns |
| t_{SPILAG} | SPI enable lag time | | 50 | - | - | ns |
| $t_{clk(H)}$ | clock HIGH time | | 100 | - | - | ns |
| $t_{clk(L)}$ | clock LOW time | | 100 | - | - | ns |
| $t_{su(D)}$ | data input set-up time | | 50 | - | - | ns |
| $t_{h(D)}$ | data input hold time | | 50 | - | - | ns |
| $t_{v(Q)}$ | data output valid time | pin SDO; $C_L = 20\text{ pF}$ | - | - | 50 | ns |
| $t_{d(SDI-SDO)}$ | SDI to SDO delay time | SPI address bits and read-only bit; $C_L = 20\text{ pF}$ | - | - | 50 | ns |
| $t_{WH(S)}$ | chip select pulse width HIGH | pin SCSN | 250 | - | - | ns |
| $t_{d(SCKL-SCSNL)}$ | delay time from SCK LOW to SCSN LOW | | 50 | - | - | ns |
| CAN transceiver timing; pins CANH, CANL, TXD and RXD | | | | | | |
| $t_{d(TXD-busdom)}$ | delay time from TXD to bus dominant | [2] | - | 80 | - | ns |
| $t_{d(TXD-busrec)}$ | delay time from TXD to bus recessive | [2] | - | 80 | - | ns |
| $t_{d(busdom-RXD)}$ | delay time from bus dominant to RXD | [2] | - | 105 | - | ns |
| $t_{d(busrec-RXD)}$ | delay time from bus recessive to RXD | [2] | - | 120 | - | ns |
| $t_{d(TXDL-RXDL)}$ | delay time from TXD LOW to RXD LOW | $t_{bit(TXD)} = 200\text{ ns}$ [3] | - | - | 255 | ns |

Table 48. Dynamic characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|---------------------------------------|--|------------------------------|-----|------------------------------|---------------|
| $t_{d(TXDH-RXDH)}$ | delay time from TXD HIGH to RXD HIGH | $t_{bit(TXD)} = 200\text{ ns}$ [3] | - | - | 255 | ns |
| $t_{bit(bus)}$ | transmitted recessive bit width | $t_{bit(TXD)} = 500\text{ ns}$ [3] | 435 | - | 530 | ns |
| | | $t_{bit(TXD)} = 200\text{ ns}$ [3] | 155 | - | 210 | ns |
| $t_{bit(RXD)}$ | bit time on pin RXD | $t_{bit(TXD)} = 500\text{ ns}$ [3] | 400 | - | 550 | ns |
| | | $t_{bit(TXD)} = 200\text{ ns}$ [3] | 120 | - | 220 | ns |
| Δt_{rec} | receiver timing symmetry | $t_{bit(TXD)} = 500\text{ ns}$ | -65 | - | +40 | ns |
| | | $t_{bit(TXD)} = 200\text{ ns}$ | -45 | - | +15 | ns |
| $t_{wake(busdom)}$ | bus dominant wake-up time | first pulse (after first recessive) for wake-up on pins CANH and CANL; CAN Offline mode | 0.5 | - | 1.8 | μs |
| | | second pulse for wake-up on pins CANH and CANL | 0.5 | - | 1.8 | μs |
| $t_{wake(busrec)}$ | bus recessive wake-up time | first pulse for wake-up on pins CANH and CANL; CAN Offline mode | 0.5 | - | 1.8 | μs |
| | | second pulse (after first dominant) for wake-up on pins CANH and CANL | 0.5 | - | 1.8 | μs |
| $t_{to(wake)bus}$ | bus wake-up time-out time | between first and second dominant pulses; CAN Offline mode | 0.8 | - | 10 | ms |
| $t_{to(dom)TXD}$ | TXD dominant time-out time | CAN Active mode; $V_{TXD} = 0\text{ V}$ | 2.7 | - | 3.3 | ms |
| $t_{to(silence)}$ | bus silence time-out time | recessive time measurement started in all CAN modes | 0.95 | - | 1.17 | s |
| $t_{d(busact-bias)}$ | delay time from bus active to bias | | - | - | 200 | μs |
| $t_{startup(CAN)}$ | CAN start-up time | when switching to Active mode (CTS = 1) | - | - | 220 | μs |
| Pin RXD: event capture timing (valid in CAN Offline mode only) | | | | | | |
| $t_{d(event)}$ | event capture delay time | CAN Offline mode | 0.9 | - | 1.1 | ms |
| t_{blank} | blanking time | when switching from Offline to Active/Listen-only mode | - | - | 25 | μs |
| Watchdog | | | | | | |
| $t_{trig(wd)1}$ | watchdog trigger time 1 | Normal mode; watchdog Window mode only [4] | $0.45 \times \text{NWP}$ [5] | - | $0.55 \times \text{NWP}$ [5] | ms |
| $t_{trig(wd)2}$ | watchdog trigger time 2 | Normal/Standby mode [6] | $0.9 \times \text{NWP}$ [5] | - | $1.11 \times \text{NWP}$ [5] | ms |
| $t_{d(SCSNH-RSTNL)}$ | delay time from SCSN HIGH to RSTN LOW | rising edge to falling edge; watchdog in window mode, triggered in the first half of the watchdog period (before $t_{trig(wd)1}$) [7] | - | - | 0.2 | ms |

Table 48. Dynamic characteristics ...continued

$T_{vj} = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$; $V_{BAT} = 3\text{ V}$ to 28 V ; $R_L = R_{(CANH-CANL)} = 60\text{ }\Omega$; all voltages are defined with respect to ground; positive currents flow into the IC; typical values are given at $V_{BAT} = 13\text{ V}$; unless otherwise specified. [1]

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------------|-----------------------------------|---|-----|-----|------|------|
| Pin RSTN: reset pulse width | | | | | | |
| t _{w(rst)} | reset pulse width | output pulse width | | | | |
| | | RLC = 00 | 20 | - | 25 | ms |
| | | RLC = 01 | 10 | - | 12.5 | ms |
| | | RLC = 10 | 3.6 | - | 5 | ms |
| | | RLC = 11 | 1 | - | 1.5 | ms |
| | input pulse width | 18 | - | - | μs | |
| Pin WAKE | | | | | | |
| t _{wake} | wake-up time | | 50 | - | - | μs |
| MTP non-volatile memory | | | | | | |
| t _{ret(data)} | data retention time | T _{vj} = 90 °C | 20 | - | - | year |
| t _{prog(MTPNV)} | MTPNV programming time | correct CRC code received at address 0x75; V _{BAT} = 6 V to 28 V | 10 | 12 | 14 | ms |
| t _{d(MTPNV)} | MTPNV delay time | before factory presets are restored; V _{BAT} = 6 V to 28 V | 0.9 | - | 1.1 | s |
| Mode transition | | | | | | |
| t _{d(act)norm} | normal mode activation delay time | MC = 111; delay before CAN transceiver gets activated after the SBC switches to Normal mode | - | - | 320 | μs |

- [1] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.
- [2] See [Figure 11](#) and [Figure 16](#).
- [3] See [Figure 12](#) and [Figure 16](#).
- [4] A system reset will be performed if the watchdog is in Window mode and is triggered less than $t_{trig(wd)1}$ after the start of the watchdog period (or in the first half of the watchdog period).
- [5] The nominal watchdog period is programmed via the NWP control bits.
- [6] The watchdog will be reset if it is in window mode and is triggered at least $t_{trig(wd)1}$, but not more than $t_{trig(wd)2}$, after the start of the watchdog period (or in the second half of the watchdog period). A system reset will be performed if the watchdog is triggered more than $t_{trig(wd)2}$ after the start of the watchdog period (watchdog overflows).
- [7] Not tested in production; guaranteed by design.

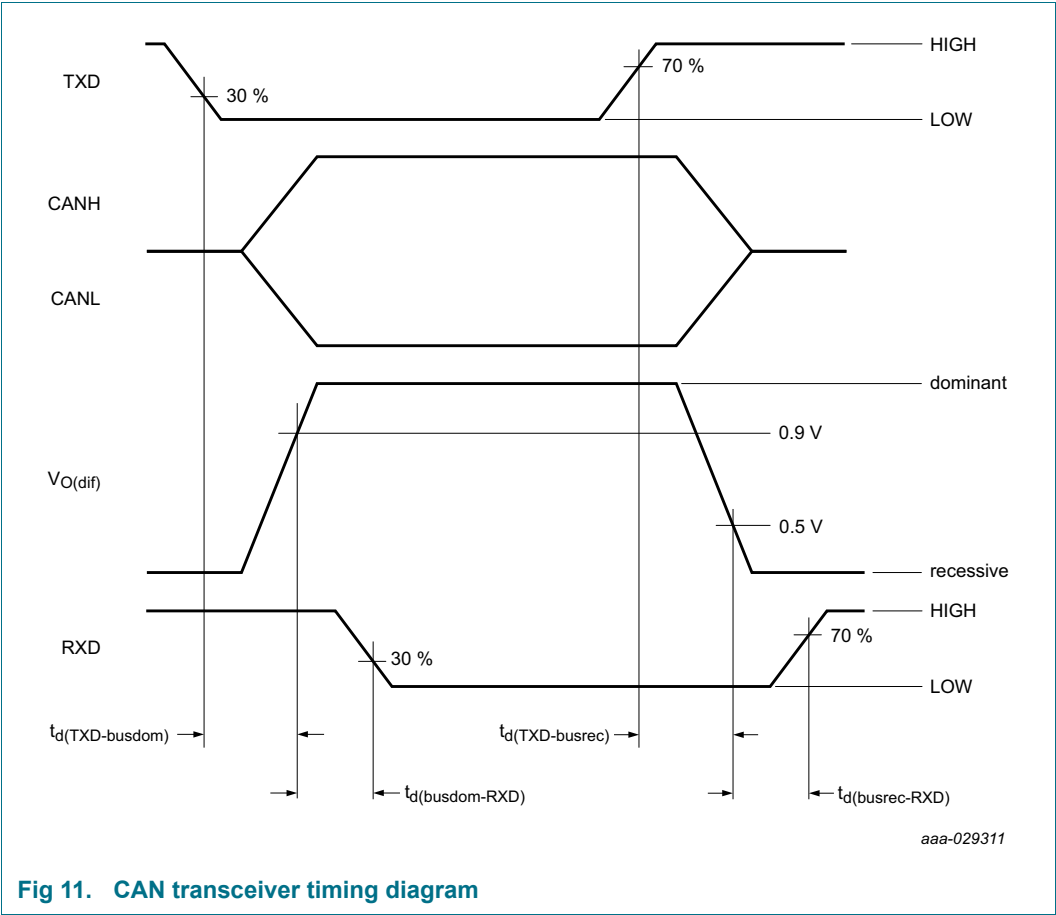


Fig 11. CAN transceiver timing diagram

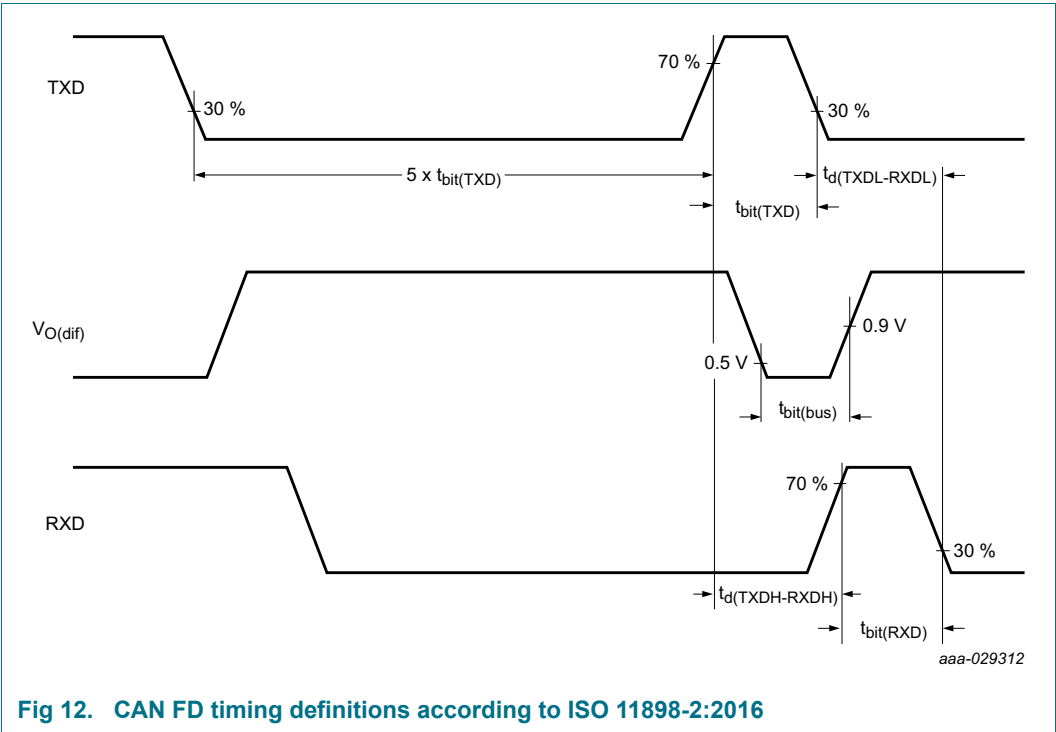
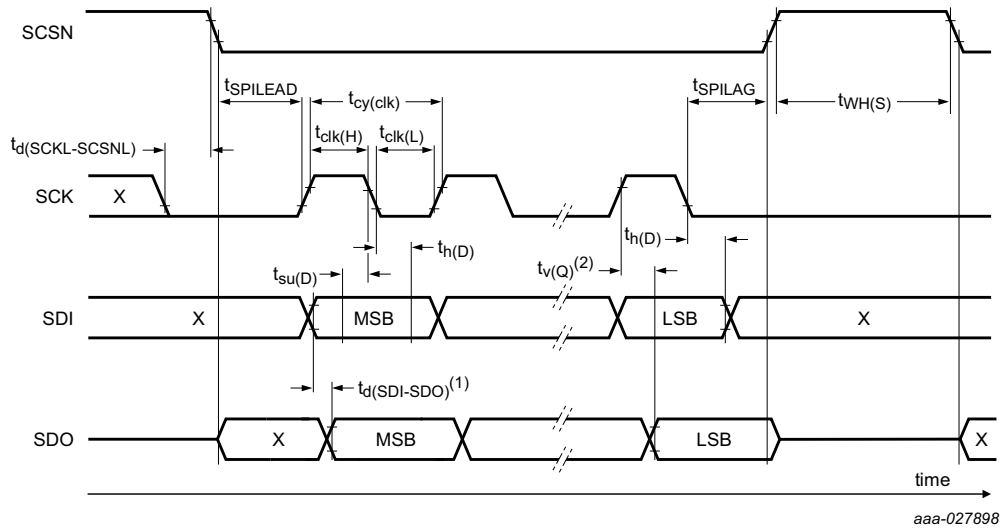


Fig 12. CAN FD timing definitions according to ISO 11898-2:2016

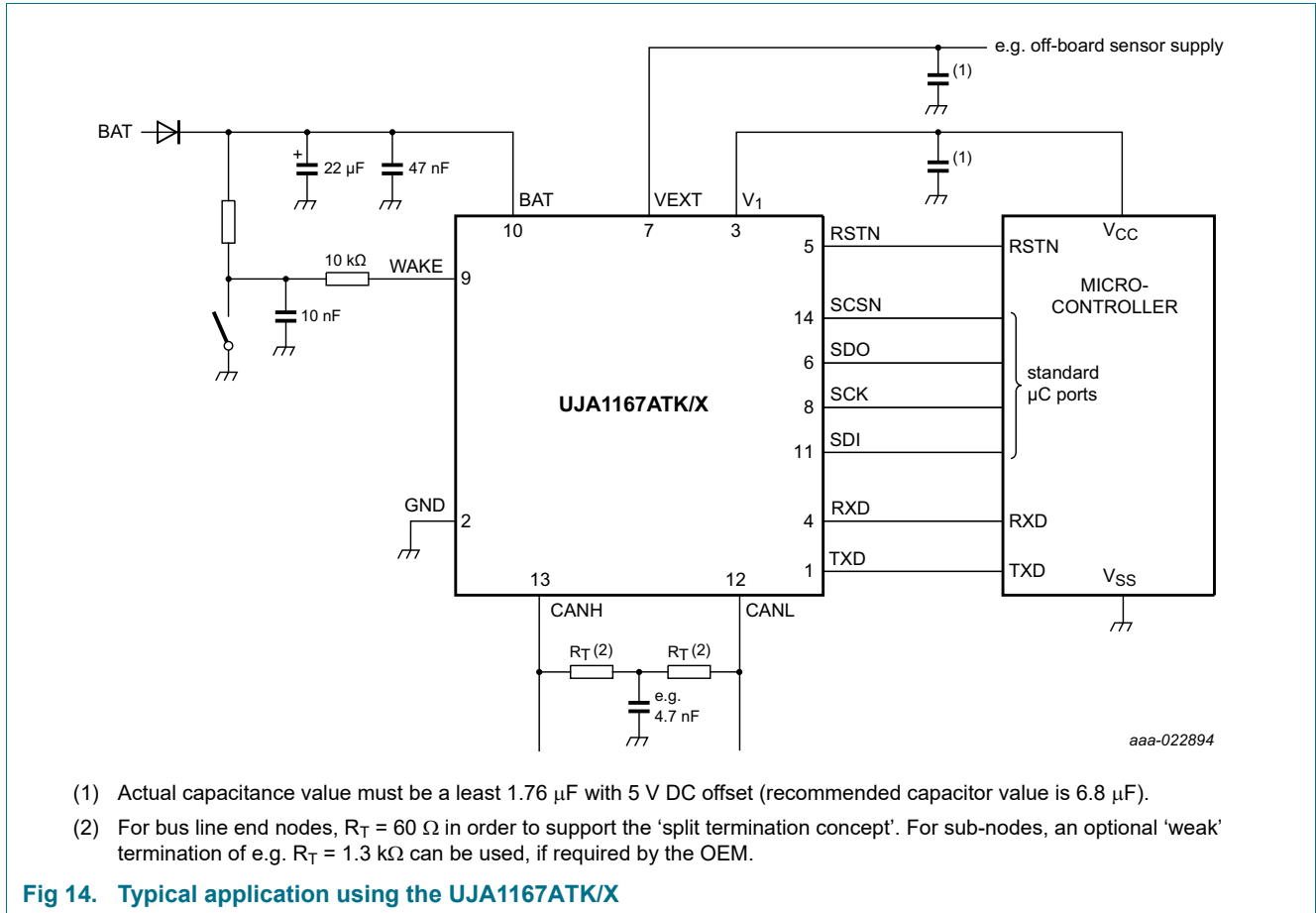


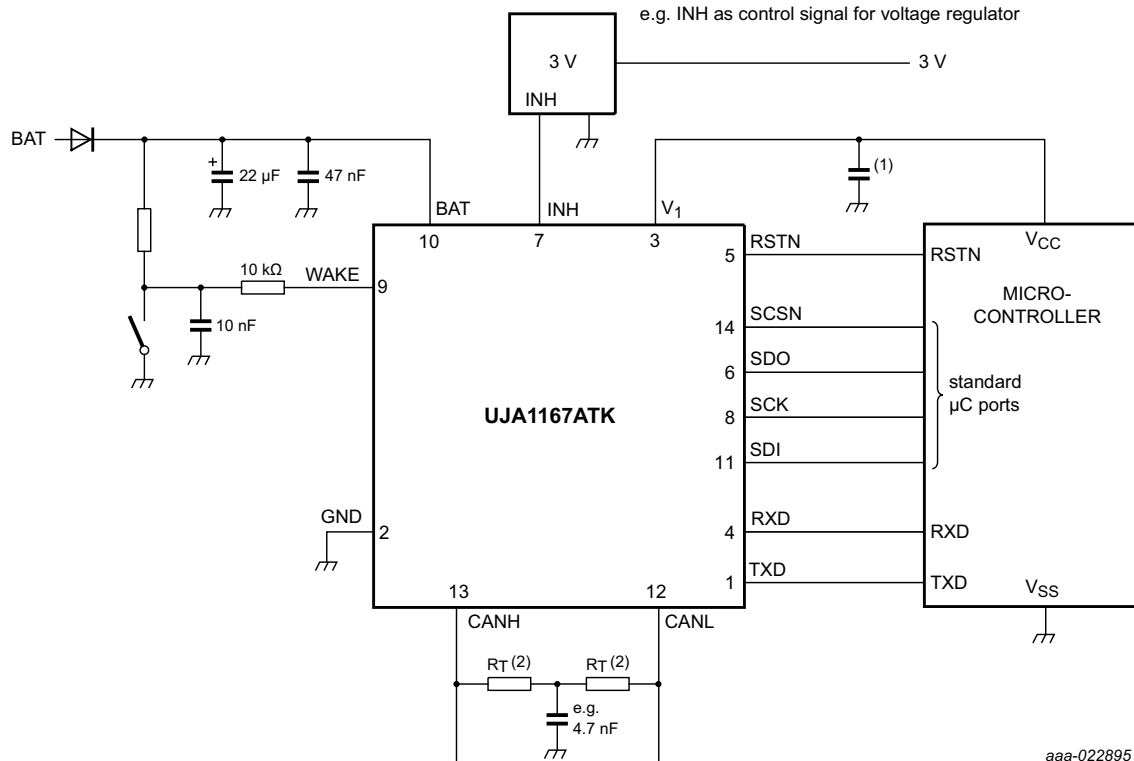
- (1) The SDI to SDO delay time is valid for SPI address bits and the read-only bit.
- (2) The data output valid time is valid for the SPI data bits.

Fig 13. SPI timing diagram

12. Application information

12.1 Application diagram





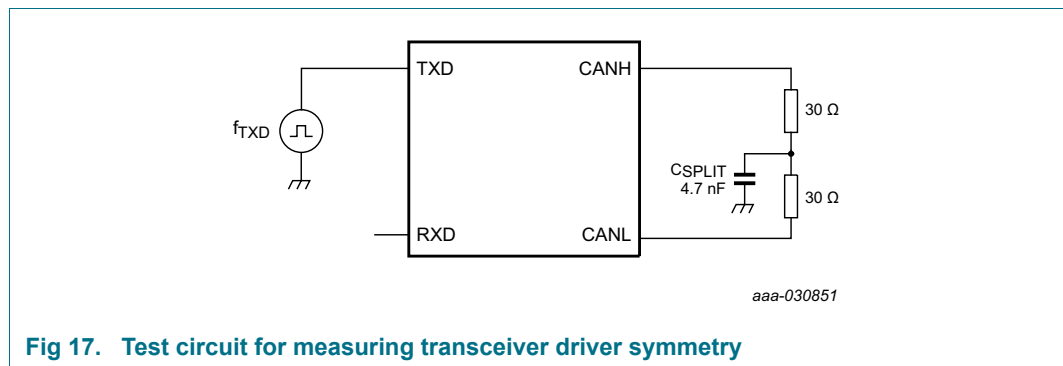
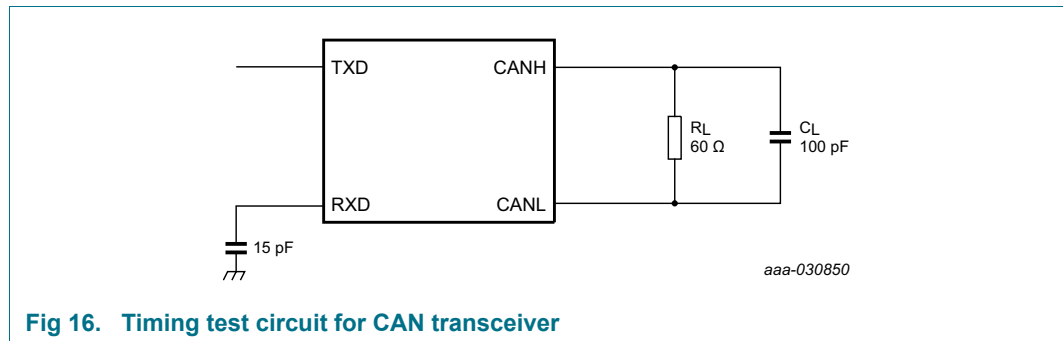
- (1) Actual capacitance value must be a least 1.76 μF with 5 V DC offset (recommended capacitor value is 6.8 μF).
- (2) For bus line end nodes, $R_T = 60 \Omega$ in order to support the 'split termination concept'. For sub-nodes, an optional 'weak' termination of e.g. $R_T = 1.3 \text{ k}\Omega$ can be used, if required by the OEM.

Fig 15. Typical application using the UJA1167ATK

12.2 Application hints

Further information on the application of the UJA1167A can be found in the NXP application hints document *AH1902 Application Hints - Mini high speed CAN system basis chips UJA116xA*.

13. Test information



13.1 Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q100 Rev-G - *Failure mechanism based stress test qualification for integrated circuits*, and is suitable for use in automotive applications.

14. Package outline

HVSON14: plastic, thermal enhanced very thin small outline package; no leads;
 14 terminals; body 3 x 4.5 x 0.85 mm

SOT1086-2

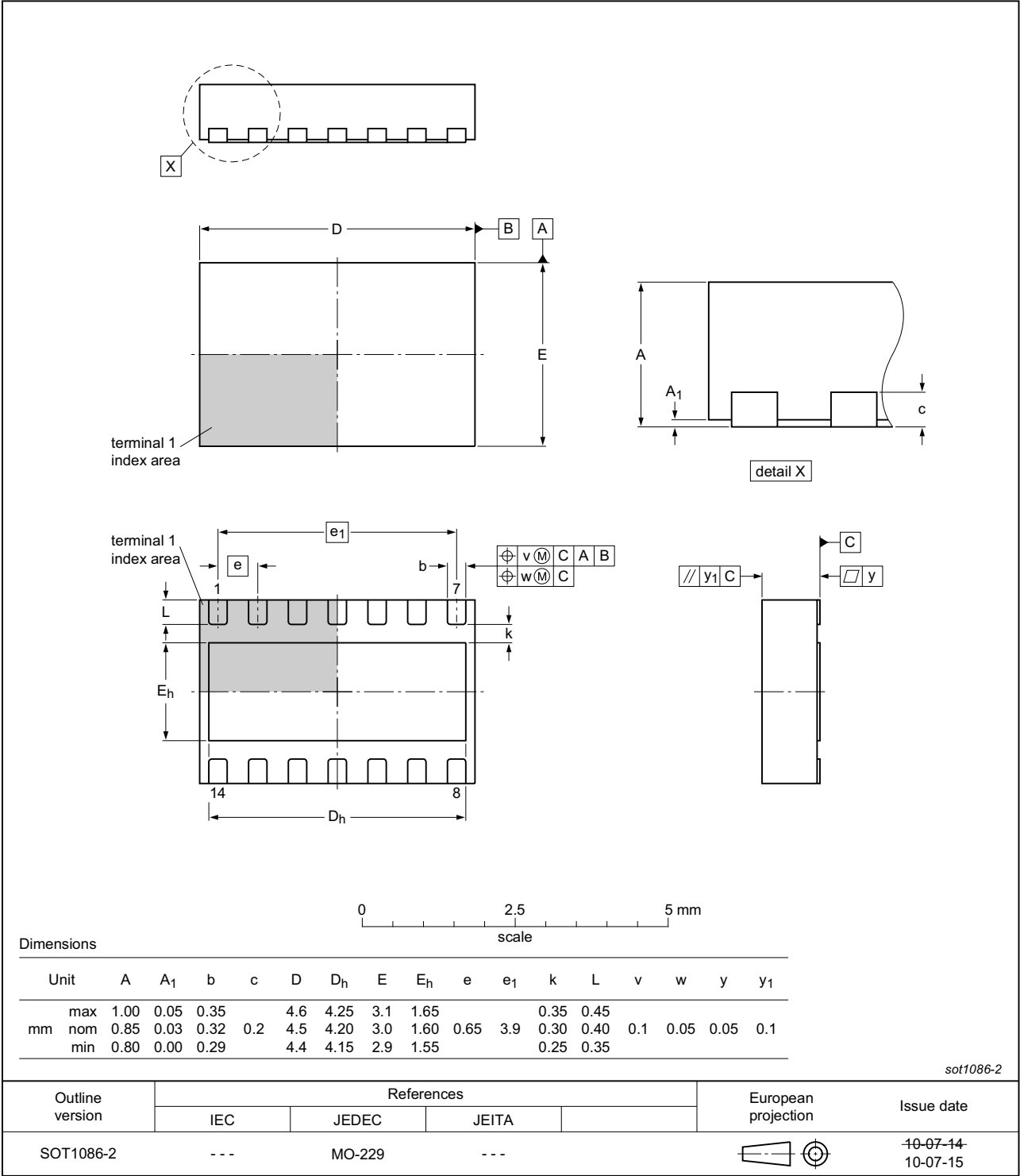


Fig 18. Package outline SOT1086-2 (HVSON14)

15. Handling information

All input and output pins are protected against ElectroStatic Discharge (ESD) under normal handling. When handling ensure that the appropriate precautions are taken as described in *JESD625-A* or equivalent standards.

16. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

16.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

16.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

16.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

16.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 19](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 49](#) and [50](#)

Table 49. SnPb eutectic process (from J-STD-020D)

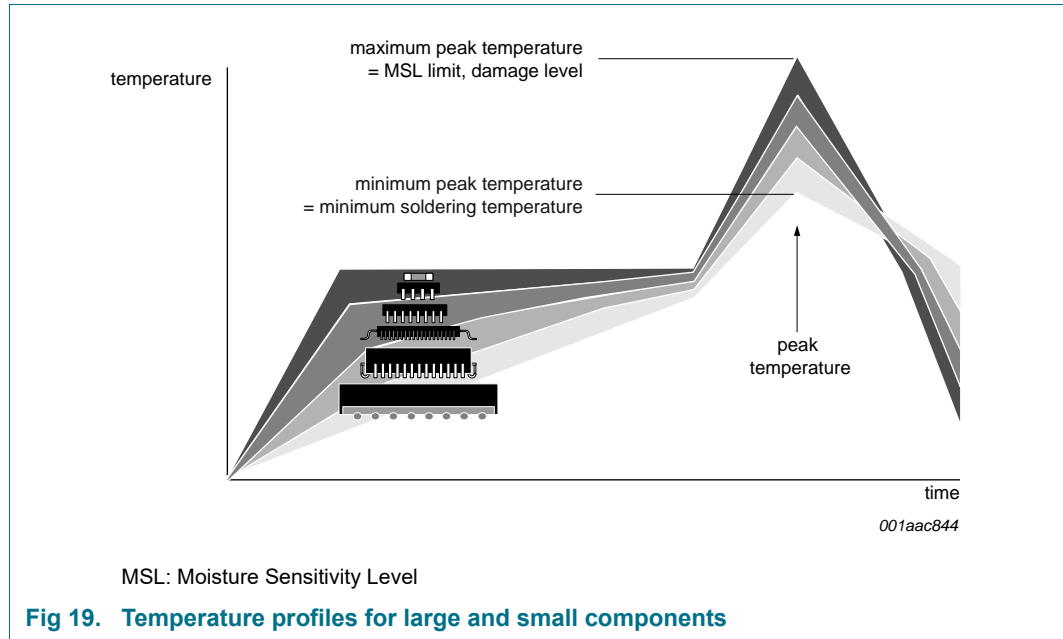
| Package thickness (mm) | Package reflow temperature (°C) | |
|------------------------|---------------------------------|-------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |
| ≥ 2.5 | 220 | 220 |

Table 50. Lead-free process (from J-STD-020D)

| Package thickness (mm) | Package reflow temperature (°C) | | |
|------------------------|---------------------------------|-------------|--------|
| | Volume (mm ³) | | |
| | < 350 | 350 to 2000 | > 2000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 19](#).



For further information on temperature profiles, refer to Application Note *AN10365* “Surface mount reflow soldering description”.

17. Soldering of HVSON packages

[Section 16](#) contains a brief introduction to the techniques most commonly used to solder Surface Mounted Devices (SMD). A more detailed discussion on soldering HVSON leadless package ICs can be found in the following application notes:

- *AN10365* “Surface mount reflow soldering description”
- *AN10366* “HVQFN application information”

18. Appendix: ISO 11898-2:201x parameter cross-reference list

Table 51. ISO 11898-2:201x to NXP data sheet parameter conversion

| ISO 11898-2:201x | | NXP data sheet | |
|---|--|---------------------------|---|
| Parameter | Notation | Symbol | Parameter |
| HS-PMA dominant output characteristics | | | |
| Single ended voltage on CAN_H | V _{CAN_H} | V _{O(dom)} | dominant output voltage |
| Single ended voltage on CAN_L | V _{CAN_L} | | |
| Differential voltage on normal bus load | V _{Diff} | V _{O(dif)} | differential output voltage |
| Differential voltage on effective resistance during arbitration | | | |
| Optional: Differential voltage on extended bus load range | | | |
| HS-PMA driver symmetry | | | |
| Driver symmetry | V _{SYM} | V _{TXsym} | transmitter voltage symmetry |
| Maximum HS-PMA driver output current | | | |
| Absolute current on CAN_H | I _{CAN_H} | I _{O(sc)dom} | dominant short-circuit output current |
| Absolute current on CAN_L | I _{CAN_L} | | |
| HS-PMA recessive output characteristics, bus biasing active/inactive | | | |
| Single ended output voltage on CAN_H | V _{CAN_H} | V _{O(rec)} | recessive output voltage |
| Single ended output voltage on CAN_L | V _{CAN_L} | | |
| Differential output voltage | V _{Diff} | V _{O(dif)} | differential output voltage |
| Optional HS-PMA transmit dominant timeout | | | |
| Transmit dominant timeout, long | t _{dom} | t _{to(dom)TXD} | TXD dominant time-out time |
| Transmit dominant timeout, short | | | |
| HS-PMA static receiver input characteristics, bus biasing active/inactive | | | |
| Recessive state differential input voltage range Dominant state differential input voltage range | V _{Diff} | V _{th(RX)dif} | differential receiver threshold voltage |
| | | V _{rec(RX)} | receiver recessive voltage |
| | | V _{dom(RX)} | receiver dominant voltage |
| HS-PMA receiver input resistance (matching) | | | |
| Differential internal resistance | R _{Diff} | R _{i(dif)} | differential input resistance |
| Single ended internal resistance | R _{CAN_H} R _{CAN_L} | R _i | input resistance |
| Matching of internal resistance | MR | ΔR _i | input resistance deviation |
| HS-PMA implementation loop delay requirement | | | |
| Loop delay | t _{Loop} | t _{d(TXDH-RXDH)} | delay time from TXD HIGH to RXD HIGH |
| | | t _{d(TXDL-RXDL)} | delay time from TXD LOW to RXD LOW |
| Optional HS-PMA implementation data signal timing requirements for use with bit rates above 1 Mbit/s up to 2 Mbit/s and above 2 Mbit/s up to 5 Mbit/s | | | |
| Transmitted recessive bit width @ 2 Mbit/s / @ 5 Mbit/s, intended | t _{Bit(Bus)} | t _{bit(bus)} | transmitted recessive bit width |
| Received recessive bit width @ 2 Mbit/s / @ 5 Mbit/s | t _{Bit(RXD)} | t _{bit(RXD)} | bit time on pin RXD |
| Receiver timing symmetry @ 2 Mbit/s / @ 5 Mbit/s | Δt _{Rec} | Δt _{rec} | receiver timing symmetry |

Table 51. ISO 11898-2:201x to NXP data sheet parameter conversion

| ISO 11898-2:201x | | NXP data sheet | |
|---|--|--|---------------------------------------|
| Parameter | Notation | Symbol | Parameter |
| HS-PMA maximum ratings of V _{CAN_H} , V _{CAN_L} and V _{Diff} | | | |
| Maximum rating V _{Diff} | V _{Diff} | V _(CANH-CANL) | voltage between pin CANH and pin CANL |
| General maximum rating V _{CAN_H} and V _{CAN_L} | V _{CAN_H} | V _x | voltage on pin x |
| Optional: Extended maximum rating VCAN_H and VCAN_L | V _{CAN_L} | | |
| HS-PMA maximum leakage currents on CAN_H and CAN_L, unpowered | | | |
| Leakage current on CAN_H, CAN_L | I _{CAN_H} I _{CAN_L} | I _L | leakage current |
| HS-PMA bus biasing control timings | | | |
| CAN activity filter time, long | t _{Filter} | t _{wake(busdom)} ^[1] | bus dominant wake-up time |
| CAN activity filter time, short | | t _{wake(busrec)} ^[1] | bus recessive wake-up time |
| Wake-up timeout, short | t _{Wake} | t _{to(wake)bus} | bus wake-up time-out time |
| Wake-up timeout, long | | | |
| Timeout for bus inactivity | t _{Silence} | t _{to(silence)} | bus silence time-out time |
| Bus Bias reaction time | t _{Bias} | t _{d(busact-bias)} | delay time from bus active to bias |

[1] $t_{fltr(wake)bus}$ - bus wake-up filter time, in devices with basic wake-up functionality

19. Revision history

Table 52. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|--------------|--------------|--------------------|---------------|------------|
| UJA1167A v.1 | 20190823 | Product data sheet | - | - |

20. Legal information

20.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
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[2] The term 'short data sheet' is explained in section "Definitions".

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