

NTS0101

Dual supply translating transceiver; open drain; auto direction sensing

Rev. 5 — 11 August 2014

Product data sheet

1. General description

The NTS0101 is a 1-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 1-bit input-output ports (A and B), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.65 V and 3.6 V. $V_{CC(B)}$ can be supplied at any voltage between 2.3 V and 5.5 V. This flexibility makes the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and OE are referenced to $V_{CC(A)}$ and pin B is referenced to $V_{CC(B)}$. A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

2. Features and benefits

- Wide supply voltage range:
 - ◆ $V_{CC(A)}$: 1.65 V to 3.6 V and $V_{CC(B)}$: 2.3 V to 5.5 V
- Maximum data rates:
 - ◆ Push-pull: 50 Mbps
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
 - ◆ HBM JESD22-A114E Class 3B exceeds 8000 V for B port
 - ◆ MM JESD22-A115-A exceeds 200 V
 - ◆ CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ and $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

3. Applications

- I²C/SMBus
- UART
- GPIO



4. Ordering information

Table 1. Ordering information

| Type number | Package | | | |
|-------------|-------------------|-------|---------------------------------------------------------------------------------------------|---------|
| | Temperature range | Name | Description | Version |
| NTS0101GW | −40 °C to +125 °C | SC-88 | plastic surface-mounted package; 6 leads | SOT363 |
| NTS0101GM | −40 °C to +125 °C | XSON6 | plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm | SOT886 |
| NTS0101GF | −40 °C to +125 °C | XSON6 | plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1 × 0.5 mm | SOT891 |
| NTS0101GS | −40 °C to +125 °C | XSON6 | extremely thin small outline package; no leads; 6 terminals; body 1.0 × 1.0 × 0.35 mm | SOT1202 |

5. Marking

Table 2. Marking

| Type number | Marking code ^[1] |
|-------------|-----------------------------|
| NTS0101GW | s1 |
| NTS0101GM | s1 |
| NTS0101GF | s1 |
| NTS0101GS | s1 |

[1] The pin 1 indicator is on the lower left corner of the device, below the marking code.

6. Functional diagram

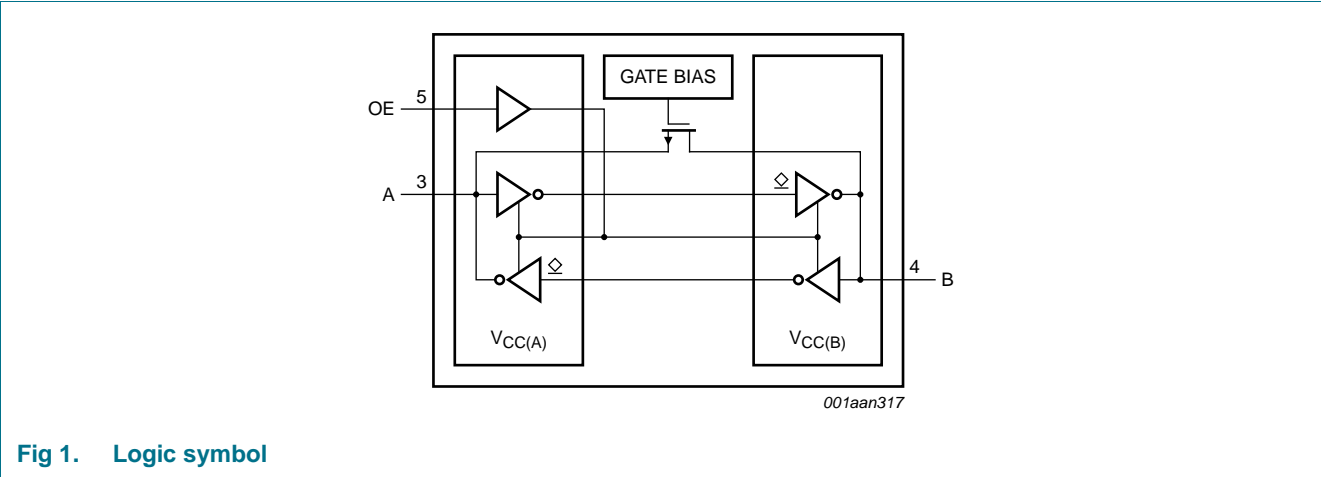
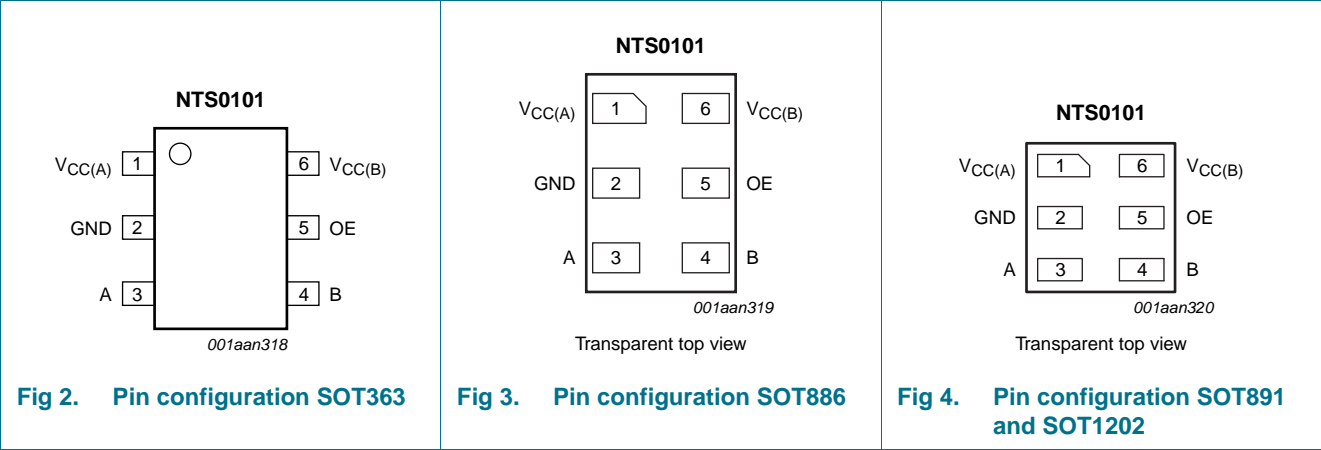


Fig 1. Logic symbol

7. Pinning information

7.1 Pinning



7.2 Pin description

Table 3. Pin description

| Symbol | Pin | Description |
|--------------------|-----|----------------------------------------------------------------------|
| V _{CC(A)} | 1 | supply voltage A |
| GND | 2 | ground (0 V) |
| A | 3 | data input or output (referenced to V _{CC(A)}) |
| B | 4 | data input or output (referenced to V _{CC(B)}) |
| OE | 5 | output enable input (active HIGH; referenced to V _{CC(A)}) |
| V _{CC(B)} | 6 | supply voltage B |

8. Functional description

Table 4. Function table^[1]

| Supply voltage | | Input | Input/output | |
|------------------------------|--------------------|-------|-----------------|-----------------|
| V _{CC(A)} | V _{CC(B)} | OE | A | B |
| 1.65 V to V _{CC(B)} | 2.3 V to 5.5 V | L | Z | Z |
| 1.65 V to V _{CC(B)} | 2.3 V to 5.5 V | H | input or output | output or input |
| GND ^[2] | GND ^[2] | X | Z | Z |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either V_{CC(A)} or V_{CC(B)} is at GND level, the device goes into power-down mode.

9. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-------------|-------------------------|-----------------------------------|------|-----------------|------|
| $V_{CC(A)}$ | supply voltage A | | -0.5 | +6.5 | V |
| $V_{CC(B)}$ | supply voltage B | | -0.5 | +6.5 | V |
| V_I | input voltage | A port and OE input [1][2] | -0.5 | +6.5 | V |
| | | B port [1][2] | -0.5 | +6.5 | V |
| V_O | output voltage | Active mode [1][2] | | | |
| | | A or B port | -0.5 | $V_{CCO} + 0.5$ | V |
| | | Power-down or 3-state mode [1] | | | |
| | | A port | -0.5 | +4.6 | V |
| | | B port | -0.5 | +6.5 | V |
| I_{IK} | input clamping current | $V_I < 0$ V | -50 | - | mA |
| I_{OK} | output clamping current | $V_O < 0$ V | -50 | - | mA |
| I_O | output current | $V_O = 0$ V to V_{CCO} [2] | - | ± 50 | mA |
| I_{CC} | supply current | $I_{CC(A)}$ or $I_{CC(B)}$ | - | 100 | mA |
| I_{GND} | ground current | | -100 | - | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| P_{tot} | total power dissipation | $T_{amb} = -40$ °C to +125 °C [3] | - | 250 | mW |

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCO} is the supply voltage associated with the output.

[3] For SC-88 and SC-74A packages: above 87.5 °C the value of P_{tot} derates linearly with 4.0 mW/K.
For XSON6 packages: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K.

10. Recommended operating conditions

Table 6. Recommended operating conditions[1][2]

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------------|-------------------------------------|----------------------------------------------------------------|------|------|------|
| $V_{CC(A)}$ | supply voltage A | | 1.65 | 3.6 | V |
| $V_{CC(B)}$ | supply voltage B | | 2.3 | 5.5 | V |
| T_{amb} | ambient temperature | | -40 | +125 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | A or B port; push-pull driving | | | |
| | | $V_{CC(A)} = 1.65$ V to 3.6 V; $V_{CC(B)} = 2.3$ V to 5.5 V | - | 10 | ns/V |
| | | OE input | | | |
| | | $V_{CC(A)} = 1.65$ V to 3.6 V; $V_{CC(B)} = 2.3$ V to 5.5 V | - | 10 | ns/V |

[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

11. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); $T_{amb} = 25\text{ }^{\circ}\text{C}$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------|---------------------------|-------------------------------------------------------------------------------------------------------------------------------------------|-----|-----|---------|---------------|
| I_I | input leakage current | OE input; $V_I = 0\text{ V to }3.6\text{ V}$; $V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ | - | - | ± 1 | μA |
| I_{OZ} | OFF-state output current | A or B port; $V_O = 0\text{ V or }V_{CCO}$; $V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ [1] | - | - | ± 1 | μA |
| I_{OFF} | power-off leakage current | A port; V_I or $V_O = 0\text{ V to }3.6\text{ V}$; $V_{CC(A)} = 0\text{ V}$; $V_{CC(B)} = 0\text{ V to }5.5\text{ V}$ | - | - | ± 1 | μA |
| | | B port; V_I or $V_O = 0\text{ V to }5.5\text{ V}$; $V_{CC(B)} = 0\text{ V}$; $V_{CC(A)} = 0\text{ V to }3.6\text{ V}$ | - | - | ± 1 | μA |
| C_I | input capacitance | OE input; $V_{CC(A)} = 3.3\text{ V}$; $V_{CC(B)} = 3.3\text{ V}$ | - | 1 | - | pF |
| $C_{I/O}$ | input/output capacitance | A port | - | 4 | - | pF |
| | | B port | - | 7.5 | - | pF |
| | | A or B port; $V_{CC(A)} = 3.3\text{ V}$; $V_{CC(B)} = 3.3\text{ V}$ | - | 11 | - | pF |

[1] V_{CCO} is the supply voltage associated with the output.

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); $T_{amb} = 25\text{ }^{\circ}\text{C}$.

| V _{CC(A)} | V _{CC(B)} | | | | | | Unit |
|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|------|
| | 2.5 V | | 3.3 V | | 5.0 V | | |
| | I _{CC(A)} | I _{CC(B)} | I _{CC(A)} | I _{CC(B)} | I _{CC(A)} | I _{CC(B)} | |
| 1.8 V | 0.1 | 0.5 | 0.1 | 1.5 | 0.1 | 4.6 | μA |
| 2.5 V | 0.1 | 0.1 | 0.1 | 0.8 | 0.1 | 3.8 | μA |
| 3.3 V | - | - | 0.1 | 0.1 | 0.1 | 2.8 | μA |

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | $-40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$ | | $-40\text{ }^{\circ}\text{C to }+125\text{ }^{\circ}\text{C}$ | | Unit |
|----------|--------------------------|-----------------------------------------------------------------------------------------------|--------------------------------------------------------------|-----|---------------------------------------------------------------|-----|------|
| | | | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | A port | | | | | |
| | | $V_{CC(A)} = 1.65\text{ V to }1.95\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ [1] | $V_{CCI} - 0.2$ | - | $V_{CCI} - 0.2$ | - | V |
| | | $V_{CC(A)} = 2.3\text{ V to }3.6\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ [1] | $V_{CCI} - 0.4$ | - | $V_{CCI} - 0.4$ | - | V |
| | | B port | | | | | |
| | | $V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ [1] | $V_{CCI} - 0.4$ | - | $V_{CCI} - 0.4$ | - | V |
| | | OE input | | | | | |
| | | $V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ | $0.65V_{CC(A)}$ | - | $0.65V_{CC(A)}$ | - | V |

Dual supply translating transceiver; open drain; auto direction sensing

Table 9. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | –40 °C to +85 °C | | –40 °C to +125 °C | | Unit |
|------------------|---------------------------|---------------------------------------------------------------------------------------------------------------------------------------------|----------------------|------------------------|----------------------|------------------------|------|
| | | | Min | Max | Min | Max | |
| V _{IL} | LOW-level input voltage | A or B port | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 0.15 | - | 0.15 | V |
| | | OE input | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 0.35V _{CC(A)} | - | 0.35V _{CC(A)} | V |
| V _{OH} | HIGH-level output voltage | I _O = –20 µA | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V [2] | 0.67V _{CCO} | - | 0.67V _{CCO} | - | V |
| V _{OL} | LOW-level output voltage | A or B port; I _O = 1 mA [2] | | | | | |
| | | V _I ≤ 0.15 V; V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 0.4 | - | 0.4 | V |
| I _I | input leakage current | OE input; V _I = 0 V to 3.6 V; V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | ±2 | - | ±12 | µA |
| I _{OZ} | OFF-state output current | A or B port; V _O = 0 V or V _{CCO} ; V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V [2] | - | ±2 | - | ±12 | µA |
| I _{OFF} | power-off leakage current | A port; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V; V _{CC(B)} = 0 V to 5.5 V | - | ±2 | - | ±12 | µA |
| | | B port; V _I or V _O = 0 V to 3.6 V; V _{CC(B)} = 0 V; V _{CC(A)} = 0 V to 3.6 V | - | ±2 | - | ±12 | µA |
| I _{CC} | supply current | V _I = 0 V or V _{CCI} ; I _O = 0 A [1] | | | | | |
| | | I _{CC(A)} | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 2.4 | - | 15 | µA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | 2.2 | - | 15 | µA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | –1 | - | –8 | µA |
| | | I _{CC(B)} | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 12 | - | 30 | µA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | –1 | - | –5 | µA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | 1 | - | 6 | µA |
| | | I _{CC(A)} + I _{CC(B)} | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 14.4 | - | 30 | µA |

[1] V_{CCI} is the supply voltage associated with the input.[2] V_{CCO} is the supply voltage associated with the output.

12. Dynamic characteristics

Table 10. Dynamic characteristics for temperature range $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ ^[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 7](#); for wave forms, see [Figure 5](#) and [Figure 6](#).

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|-------------------------------------|------------------------------------|-----------------------------------------------|--------------------|------|---------------|-----|---------------|------|------|
| | | | 2.5 V ± 0.2 V | | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = 1.8 V ± 0.15 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 4.6 | - | 4.7 | - | 5.8 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 6.8 | - | 6.8 | - | 7.0 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 4.4 | - | 4.5 | - | 4.7 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 5.3 | - | 4.5 | - | 0.5 | ns |
| t _{en} | enable time | OE to A; B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | 25 | - | 25 | - | 25 | ns |
| | | OE to B; no external load [2] | - | 25 | - | 25 | - | 25 | ns |
| | | OE to A | - | 230 | - | 230 | - | 230 | ns |
| | | OE to B | - | 200 | - | 200 | - | 200 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | 3.2 | 9.5 | 2.3 | 9.3 | 1.8 | 7.6 | ns |
| | | B port | 3.3 | 10.8 | 2.7 | 9.1 | 2.7 | 7.6 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | 2.0 | 5.9 | 1.9 | 6.0 | 1.7 | 13.3 | ns |
| | | B port | 2.9 | 7.6 | 2.8 | 7.5 | 2.8 | 10.0 | ns |
| t _W | pulse width | data inputs | 20 | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | 50 | - | 50 | - | 50 | Mbps |
| V _{CC(A)} = 2.5 V ± 0.2 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 3.2 | - | 3.3 | - | 3.4 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 3.5 | - | 4.1 | - | 4.4 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 3.0 | - | 3.6 | - | 4.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 2.5 | - | 1.6 | - | 0.7 | ns |
| t _{en} | enable time | OE to A; B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | 20 | - | 20 | - | 20 | ns |
| | | OE to B; no external load [2] | - | 20 | - | 20 | - | 20 | ns |
| | | OE to A | - | 200 | - | 200 | - | 200 | ns |
| | | OE to B | - | 200 | - | 200 | - | 200 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | 2.8 | 7.4 | 2.6 | 6.6 | 1.8 | 6.2 | ns |
| | | B port | 3.2 | 8.3 | 2.9 | 7.9 | 2.4 | 6.8 | ns |

Table 10. Dynamic characteristics for temperature range $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ ^[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 7](#); for wave forms, see [Figure 5](#) and [Figure 6](#).

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|------------------------------------|------------------------------------|-----------------------------------------------|--------------------|-----|---------------|-----|---------------|-----|------|
| | | | 2.5 V ± 0.2 V | | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Max | |
| t _{THL} | HIGH to LOW output transition time | A port | 1.9 | 5.7 | 1.9 | 5.5 | 1.8 | 5.3 | ns |
| | | B port | 2.2 | 7.8 | 2.4 | 6.7 | 2.6 | 6.6 | ns |
| t _W | pulse width | data inputs | 20 | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | 50 | - | 50 | - | 50 | Mbps |
| V _{CC(A)} = 3.3 V ± 0.3 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | - | - | 2.4 | - | 3.1 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | - | - | 4.2 | - | 4.4 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | - | - | 2.5 | - | 3.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | - | - | 2.5 | - | 2.6 | ns |
| t _{en} | enable time | OE to A; B | - | - | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | - | 15 | - | 15 | ns |
| | | OE to B; no external load [2] | - | - | - | 15 | - | 15 | ns |
| | | OE to A | - | - | - | 260 | - | 260 | ns |
| | | OE to B | - | - | - | 200 | - | 200 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | - | - | 2.3 | 5.6 | 1.9 | 5.9 | ns |
| | | B port | - | - | 2.5 | 6.4 | 2.1 | 7.4 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | - | - | 2.0 | 5.4 | 1.9 | 5.0 | ns |
| | | B port | - | - | 2.3 | 7.4 | 2.4 | 7.6 | ns |
| t _W | pulse width | data inputs | - | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | - | - | 50 | - | 50 | Mbps |

[1] t_{en} is the same as t_{pZL} and t_{pZH} .

t_{dis} is the same as t_{pLZ} and t_{pHZ} .

[2] Delay between OE going LOW and when the outputs are disabled.

Dual supply translating transceiver; open drain; auto direction sensing

Table 11. Dynamic characteristics for temperature range –40 °C to +125 °C^[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 7](#); for wave forms, see [Figure 5](#) and [Figure 6](#).

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|-------------------------------------|------------------------------------|-----------------------------------------------|--------------------|------|---------------|------|---------------|------|------|
| | | | 2.5 V ± 0.2 V | | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = 1.8 V ± 0.15 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 5.8 | - | 5.9 | - | 7.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 8.5 | - | 8.5 | - | 8.8 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 5.5 | - | 5.7 | - | 5.9 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 6.7 | - | 5.7 | - | 0.7 | ns |
| t _{en} | enable time | OE to A; B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | 30 | - | 30 | - | 30 | ns |
| | | OE to B; no external load [2] | - | 30 | - | 30 | - | 30 | ns |
| | | OE to A | - | 250 | - | 250 | - | 250 | ns |
| | | OE to B | - | 220 | - | 220 | - | 220 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | 3.2 | 11.9 | 2.3 | 11.7 | 1.8 | 9.5 | ns |
| | | B port | 3.3 | 13.5 | 2.7 | 11.4 | 2.7 | 9.5 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | 2.0 | 7.4 | 1.9 | 7.5 | 1.7 | 16.7 | ns |
| | | B port | 2.9 | 9.5 | 2.8 | 9.4 | 2.8 | 12.5 | ns |
| t _W | pulse width | data inputs | 20 | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | 50 | - | 50 | - | 50 | Mbps |
| V _{CC(A)} = 2.5 V ± 0.2 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 4.0 | - | 4.2 | - | 4.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 4.4 | - | 5.2 | - | 5.5 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 3.8 | - | 4.5 | - | 5.4 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 3.2 | - | 2.0 | - | 0.9 | ns |
| t _{en} | enable time | OE to A; B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | 25 | - | 25 | - | 25 | ns |
| | | OE to B; no external load [2] | - | 25 | - | 25 | - | 25 | ns |
| | | OE to A | - | 220 | - | 220 | - | 220 | ns |
| | | OE to B | - | 220 | - | 220 | - | 220 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | 2.8 | 9.3 | 2.6 | 8.3 | 1.8 | 7.8 | ns |
| | | B port | 3.2 | 10.4 | 2.9 | 9.7 | 2.4 | 8.3 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | 1.9 | 7.2 | 1.9 | 6.9 | 1.8 | 6.7 | ns |
| | | B port | 2.2 | 9.8 | 2.4 | 8.4 | 2.6 | 8.3 | ns |

Table 11. Dynamic characteristics for temperature range $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$ ^[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 7](#); for wave forms, see [Figure 5](#) and [Figure 6](#).

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|------------------------------------|------------------------------------|-----------------------------------------------|--------------------|-----|---------------|-----|---------------|-----|------|
| | | | 2.5 V ± 0.2 V | | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Max | |
| t _W | pulse width | data inputs | 20 | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | 50 | - | 50 | - | 50 | Mbps |
| V _{CC(A)} = 3.3 V ± 0.3 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | - | - | 3.0 | - | 3.9 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | - | - | 5.3 | - | 5.5 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | - | - | 3.2 | - | 4.2 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | - | - | 3.2 | - | 3.3 | ns |
| t _{en} | enable time | OE to A; B | - | - | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | - | 20 | - | 20 | ns |
| | | OE to B; no external load [2] | - | - | - | 20 | - | 20 | ns |
| | | OE to A | - | - | - | 280 | - | 280 | ns |
| | | OE to B | - | - | - | 220 | - | 220 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | - | - | 2.3 | 7.0 | 1.9 | 7.4 | ns |
| | | B port | - | - | 2.5 | 8.0 | 2.1 | 9.3 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | - | - | 2.0 | 6.8 | 1.9 | 6.3 | ns |
| | | B port | - | - | 2.3 | 9.3 | 2.4 | 9.5 | ns |
| t _W | pulse width | data inputs | - | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | - | - | 50 | - | 50 | Mbps |

[1] t_{en} is the same as t_{PZL} and t_{PZH} .

t_{dis} is the same as t_{PLZ} and t_{PHZ} .

[2] Delay between OE going LOW and when the outputs are disabled.

13. Waveforms

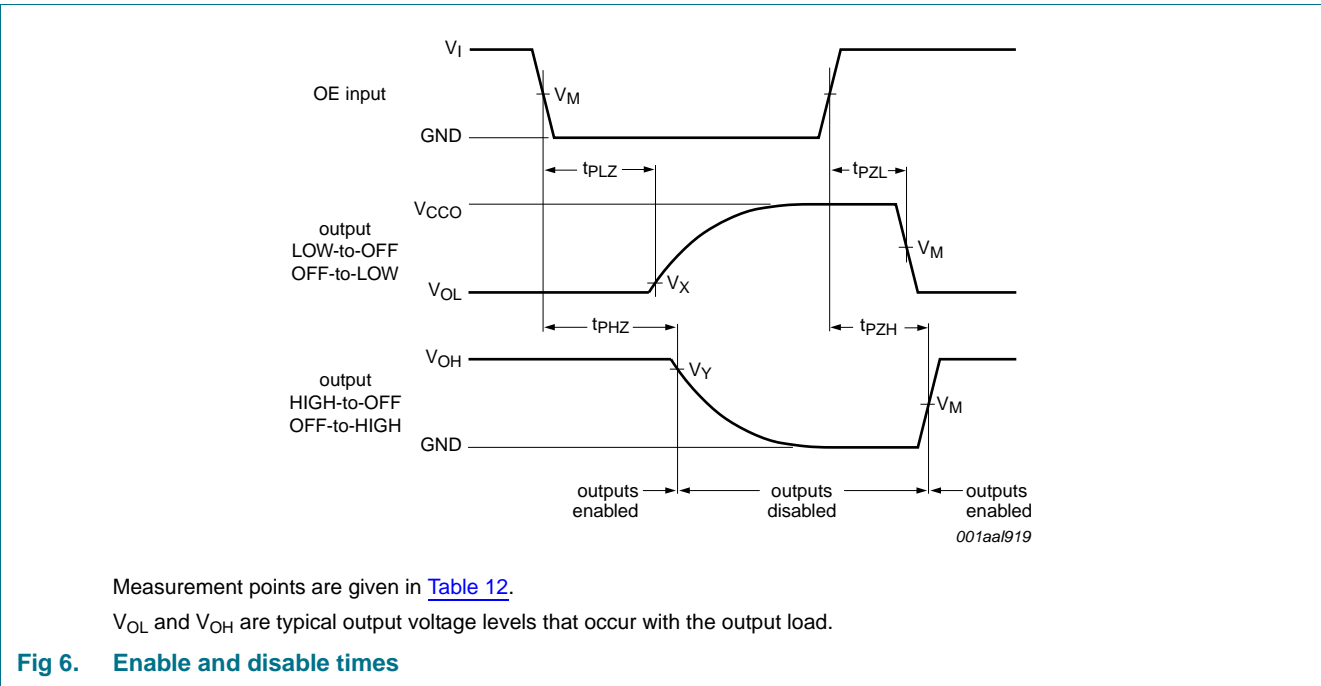
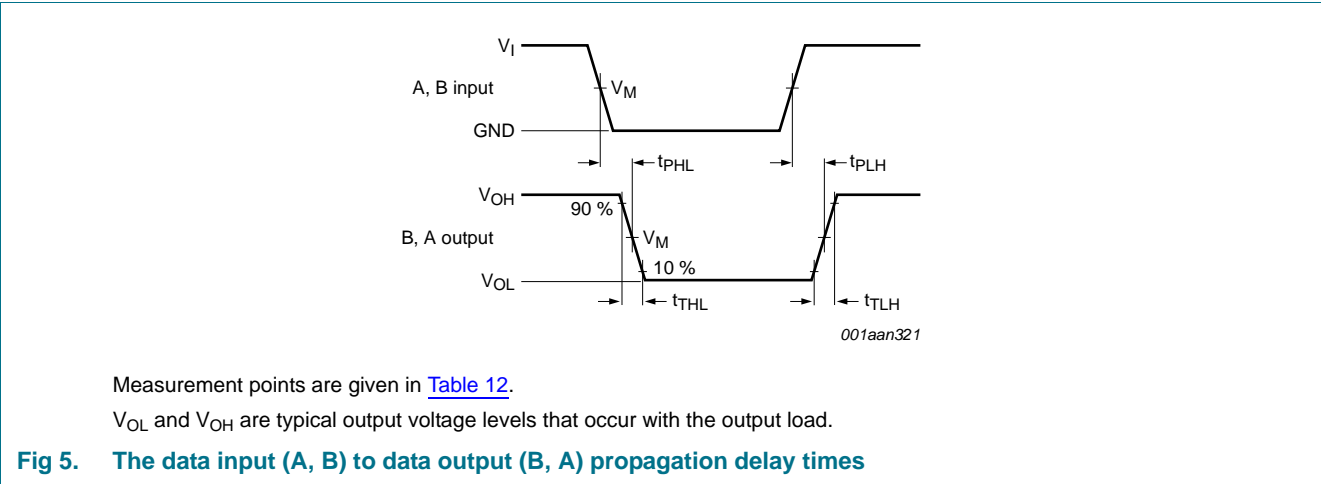
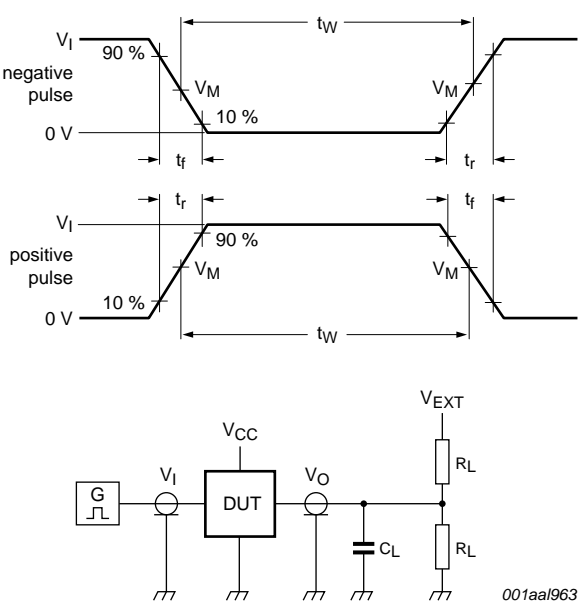


Table 12. Measurement points^{[1][2]}

| Supply voltage | Input | Output | | |
|----------------|---------------------|---------------------|--------------------------|--------------------------|
| V_{CCO} | V_M | V_M | V_X | V_Y |
| 1.8 V ± 0.15 V | 0.5V _{CCI} | 0.5V _{CCO} | $V_{OL} + 0.15\text{ V}$ | $V_{OH} - 0.15\text{ V}$ |
| 2.5 V ± 0.2 V | 0.5V _{CCI} | 0.5V _{CCO} | $V_{OL} + 0.15\text{ V}$ | $V_{OH} - 0.15\text{ V}$ |
| 3.3 V ± 0.3 V | 0.5V _{CCI} | 0.5V _{CCO} | $V_{OL} + 0.3\text{ V}$ | $V_{OH} - 0.3\text{ V}$ |
| 5.0 V ± 0.5 V | 0.5V _{CCI} | 0.5V _{CCO} | $V_{OL} + 0.3\text{ V}$ | $V_{OH} - 0.3\text{ V}$ |

[1] V_{CCI} is the supply voltage associated with the input.

[2] V_{CCO} is the supply voltage associated with the output.



Test data is given in [Table 13](#).
All input pulses are supplied by generators having the following characteristics: PRR ≤ 10 MHz; Z_O = 50 Ω; dV/dt ≥ 1.0 V/ns.
R_L = Load resistance.
C_L = Load capacitance including jig and probe capacitance.
V_{EXT} = External voltage for measuring switching times.

Fig 7. Test circuit for measuring switching times

Table 13. Test data

| Supply voltage | | Input | | Load | | V _{EXT} | | |
|--------------------|--------------------|-------------------------------|------------|----------------|-------------------------------|-------------------------------------|-------------------------------------|----------------------------------------------------|
| V _{CC(A)} | V _{CC(B)} | V _I ^[1] | Δt/ΔV | C _L | R _L ^[2] | t _{PLH} , t _{PHL} | t _{PZH} , t _{PHZ} | t _{PZL} , t _{PLZ} ^[3] |
| 1.65 V to 3.6 V | 2.3 V to 5.5 V | V _{CCI} | ≤ 1.0 ns/V | 15 pF | 50 kΩ, 1 MΩ | open | open | 2V _{CCO} |

- [1] V_{CCI} is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, R_L = 1 MΩ. For measuring enable and disable times, R_L = 50 KΩ.
- [3] V_{CCO} is the supply voltage associated with the output.

14. Application information

14.1 Applications

Voltage level-translation applications. The NTS0101 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I²C or 1-wire which use open-drain drivers. It may also be used in applications where push-pull drivers are connected to the ports, however the NTB0101 may be more suitable.

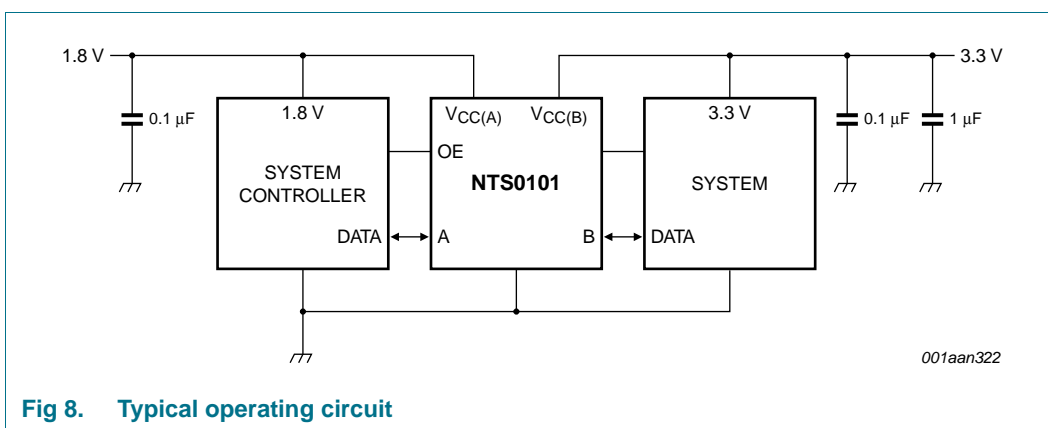


Fig 8. Typical operating circuit

14.2 Architecture

The architecture of the NTS0101 is shown in Figure 9. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.

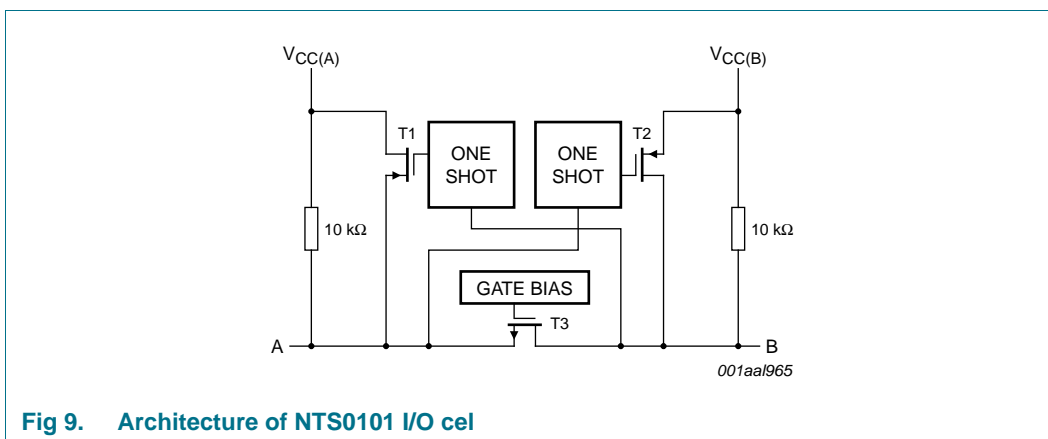


Fig 9. Architecture of NTS0101 I/O cel

The NTS0101 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

1. A pass-gate transistor (N-channel) that ties the ports together.
2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the V_{CC} level of the low-voltage side. During a LOW-to-HIGH transition, the output one-shot accelerates the output transition by switching on the PMOS transistors (T1, T2). It bypasses the 10 k Ω pull-up resistors and increases the current drive capability. The one-shot is activated once the input transition reaches approximately $V_{CC}/2$; it is de-activated approximately 50 ns after the output reaches $V_{CC}/2$. During the acceleration time, the driver output resistance is between approximately 50 Ω and 70 Ω . To avoid signal contention and minimize dynamic I_{CC} , the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

14.3 Input driver requirements

As the NTS0101 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system. The max data rate, HIGH-to-LOW output transition time (t_{THL}), and propagation delay (t_{PHL}), are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the data sheet assume a driver with output impedance below 50 Ω is used.

14.4 Output load considerations

The maximum lumped capacitive load that can be driven is dependant upon the one-shot pulse duration. In cases with very heavy capacitive loading, there is a risk that the output does not reach the positive rail within the one-shot pulse duration.

To avoid excessive capacitive loading and to ensure correct triggering of the one-shot, use short trace lengths and low capacitance connectors on NTS0101 PCB layouts. The length of the PCB trace should be such that the round-trip delay of any reflection is within the one-shot pulse duration (approximately 50 ns). It ensures low impedance termination and avoids output signal oscillations and one-shot retriggering.

14.5 Power-up

During operation, $V_{CC(A)}$ must never be higher than $V_{CC(B)}$. However, during power-up, $V_{CC(A)} \geq V_{CC(B)}$ does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTS0101 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

14.6 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor. The current-sourcing capability of the driver determines the minimum value of the resistor.

14.7 Pull-up or pull-down resistors on I/Os lines

The A port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(A)}$. The B port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(B)}$. If a smaller value of pull-up resistor is required, add an external resistor in parallel to the internal 10 k Ω . This pull-up resistor effects the V_{OL} level. When OE goes LOW, the internal pull-ups of the NTS0101 are disabled.

15. Package outline

Plastic surface-mounted package; 6 leads

SOT363

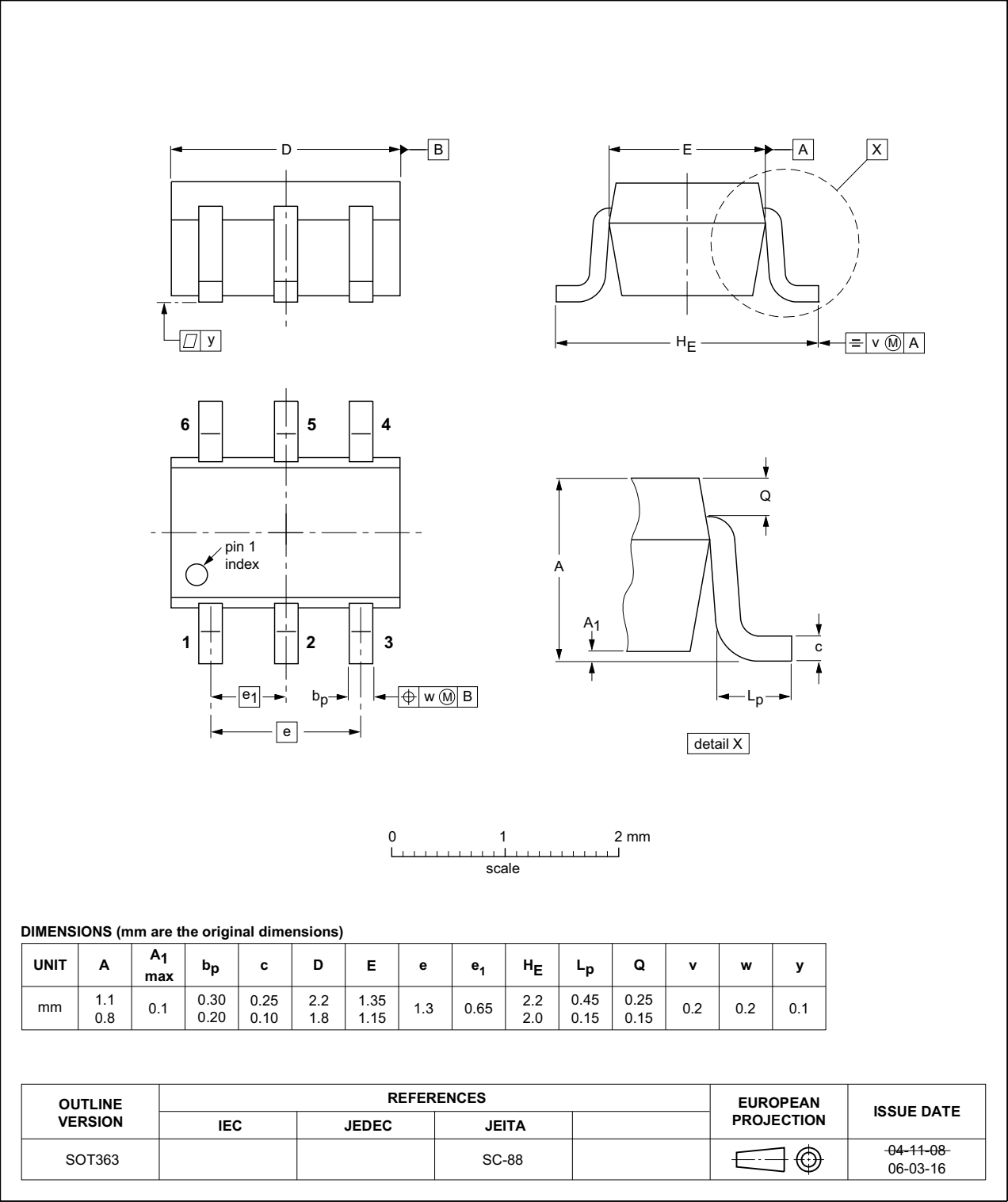


Fig 10. Package outline SOT363 (SC-88)

XSON6: plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1.45 x 0.5 mm

SOT886

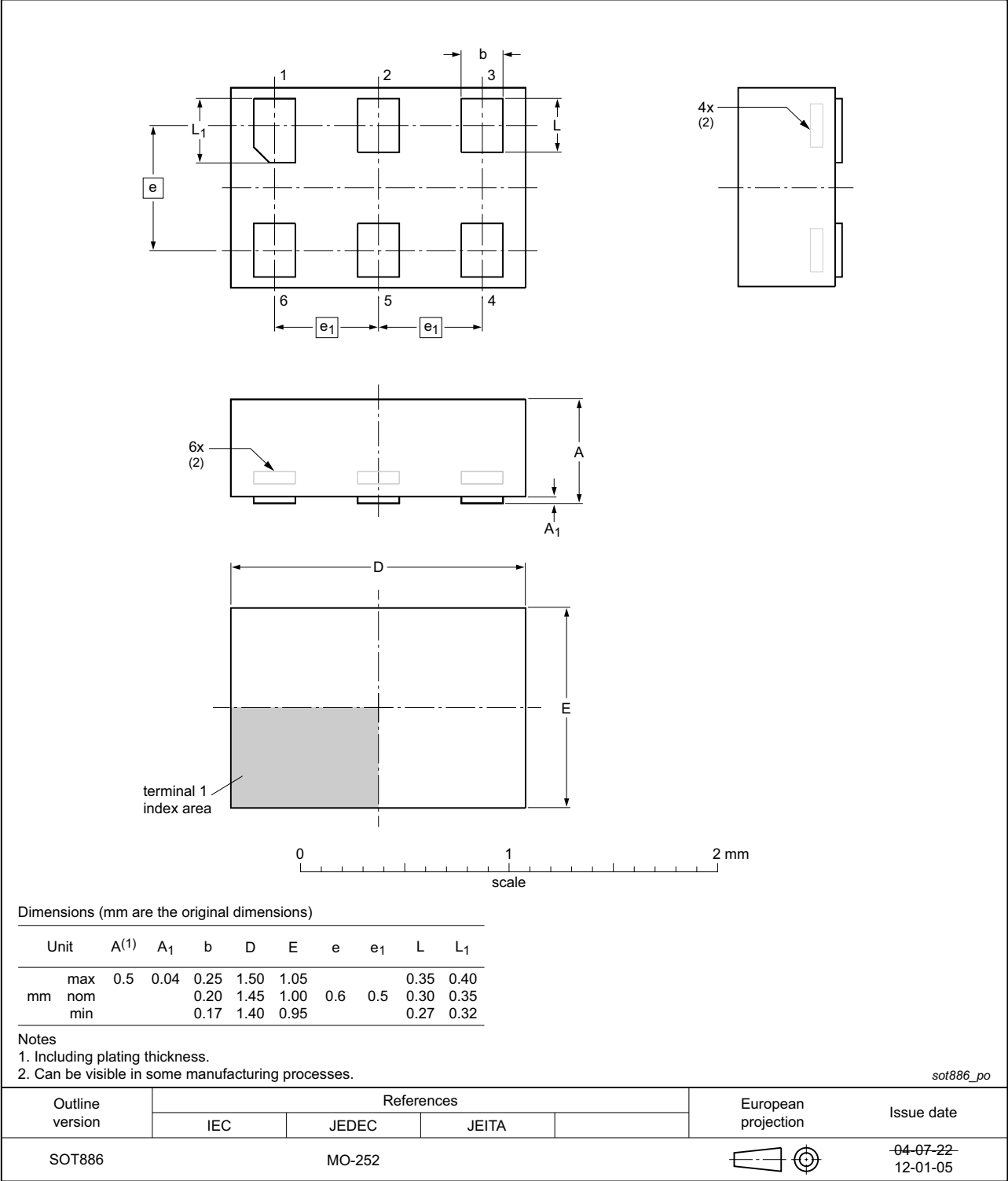


Fig 11. Package outline SOT886 (XSON6)

XSON6: plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1 x 0.5 mm

SOT891

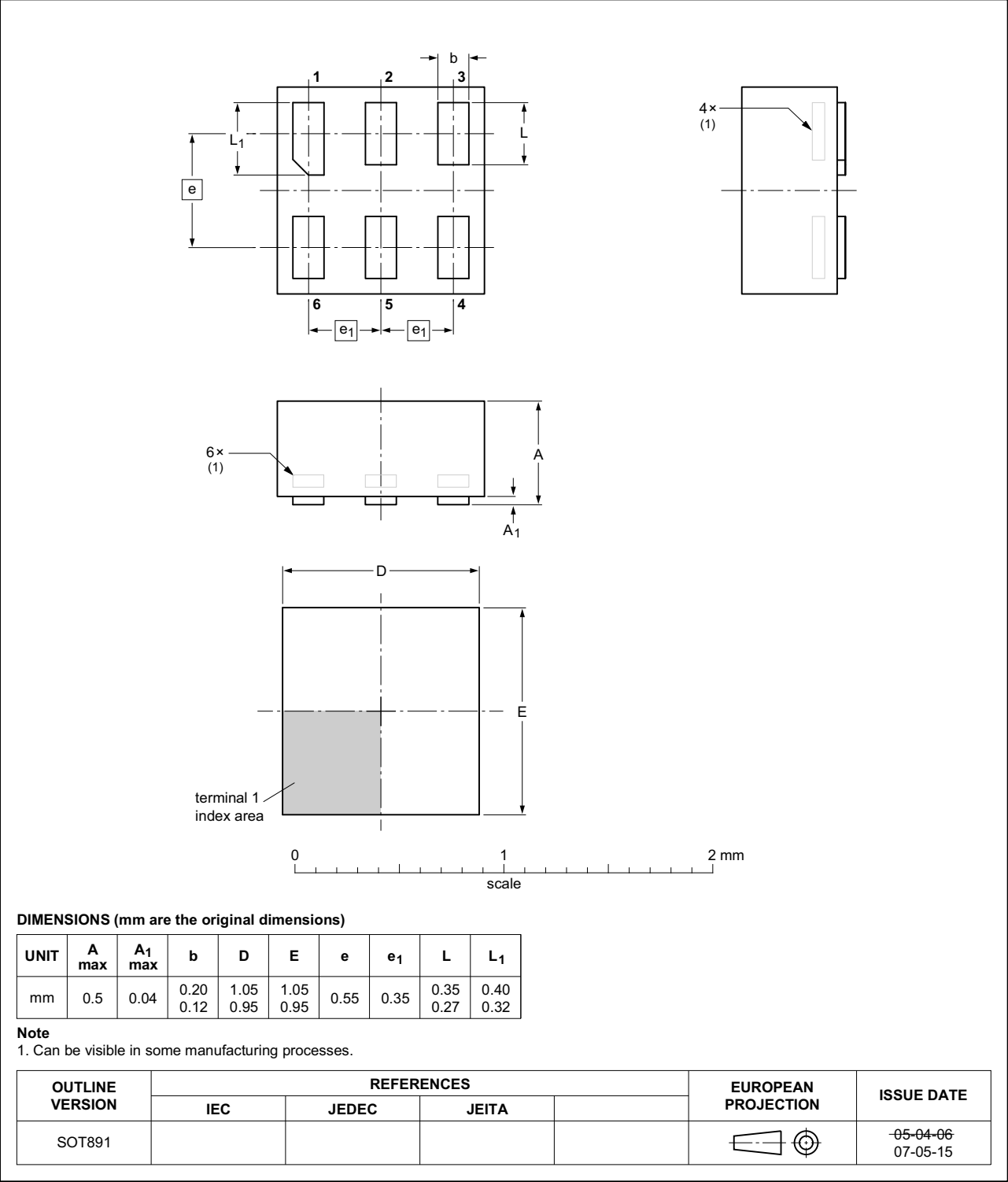
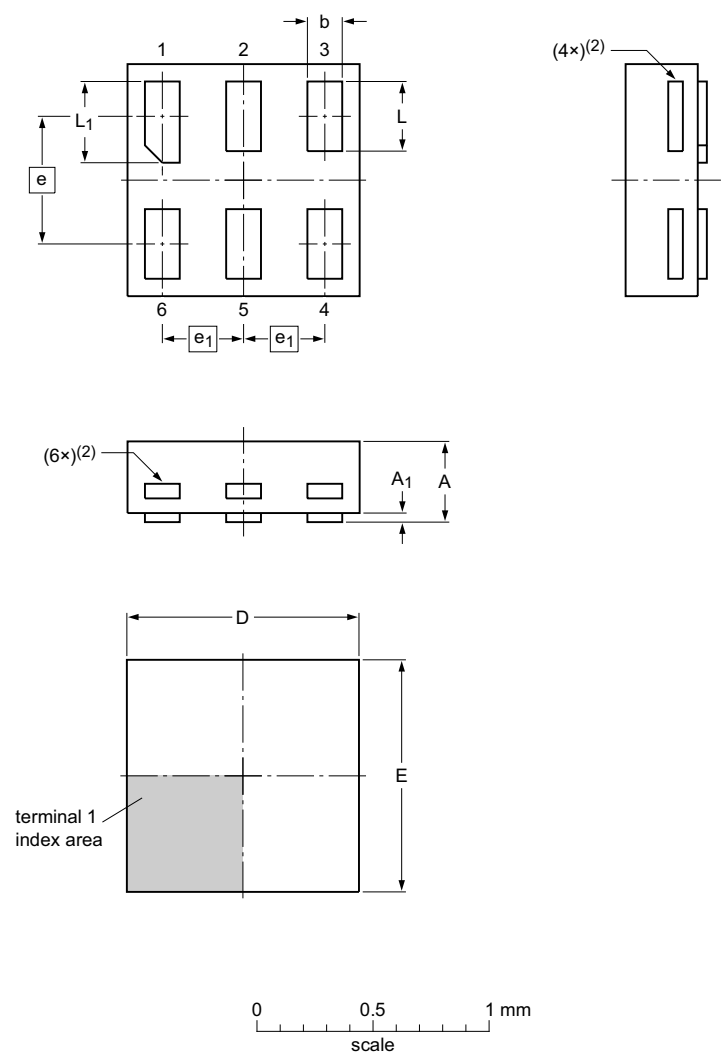


Fig 12. Package outline SOT891 (XSON6)

XSON6: extremely thin small outline package; no leads;
6 terminals; body 1.0 x 1.0 x 0.35 mm

SOT1202



Dimensions

| Unit | A ⁽¹⁾ | A ₁ | b | D | E | e | e ₁ | L | L ₁ |
|------|------------------|----------------|------|------|------|------|----------------|------|----------------|
| mm | max | 0.35 | 0.04 | 0.20 | 1.05 | 1.05 | | 0.35 | 0.40 |
| | nom | | | 0.15 | 1.00 | 1.00 | 0.55 | 0.30 | 0.35 |
| | min | | | 0.12 | 0.95 | 0.95 | | 0.27 | 0.32 |

Note

- 1. Including plating thickness.
- 2. Visible depending upon used manufacturing technology.

sot1202_po


| Outline version | References | | | | European projection | Issue date |
|-----------------|------------|-------|-------|--|---------------------------------------------------------------------------------------|---------------------------------|
| | IEC | JEDEC | JEITA | | | |
| SOT1202 | | | | |  | 10-04-02 10-04-06 |

Fig 13. Package outline SOT1202 (XSON6)

16. Abbreviations

Table 14. Abbreviations

| Acronym | Description |
|------------------|---------------------------------------------|
| CDM | Charged Device Model |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| GPIO | General Purpose Input Output |
| HBM | Human Body Model |
| I ² C | Inter-Integrated Circuit |
| MM | Machine Model |
| PCB | Printed-Circuit Board |
| PMOS | Positive Metal Oxide Semiconductor |
| SMBus | System Management Bus |
| UART | Universal Asynchronous Receiver Transmitter |

17. Revision history

Table 15. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|-----------------------------------------------------------|--------------------|---------------|-------------|
| NTS0101 v.5 | 20140811 | Product data sheet | - | NTS0101 v.4 |
| Modifications: | • Type number NTS0101GV has been removed | | | |
| NTS0101 v.4 | 20120514 | Product data sheet | - | NTS0101 v.3 |
| Modifications: | • Package outline drawing of SOT886 (Figure 11) modified. | | | |
| NTS0101 v.3 | 20111110 | Product data sheet | - | NTS0101 v.2 |
| Modifications: | • Legal pages updated. | | | |
| NTS0101 v.2 | 20110427 | Product data sheet | - | NTS0101 v.1 |
| NTS0101 v.1 | 20101230 | Product data sheet | - | - |

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| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---------------------------------------------------------------------------------------|
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| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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20. Contents

| | | |
|-----------|-------------------------------------------------|-----------|
| 1 | General description | 1 |
| 2 | Features and benefits | 1 |
| 3 | Applications | 1 |
| 4 | Ordering information | 2 |
| 5 | Marking | 2 |
| 6 | Functional diagram | 2 |
| 7 | Pinning information | 3 |
| 7.1 | Pinning | 3 |
| 7.2 | Pin description | 3 |
| 8 | Functional description | 3 |
| 9 | Limiting values | 4 |
| 10 | Recommended operating conditions | 4 |
| 11 | Static characteristics | 5 |
| 12 | Dynamic characteristics | 7 |
| 13 | Waveforms | 11 |
| 14 | Application information | 13 |
| 14.1 | Applications | 13 |
| 14.2 | Architecture | 13 |
| 14.3 | Input driver requirements | 14 |
| 14.4 | Output load considerations | 14 |
| 14.5 | Power-up | 14 |
| 14.6 | Enable and disable | 14 |
| 14.7 | Pull-up or pull-down resistors on I/Os lines .. | 15 |
| 15 | Package outline | 16 |
| 16 | Abbreviations | 20 |
| 17 | Revision history | 20 |
| 18 | Legal information | 21 |
| 18.1 | Data sheet status | 21 |
| 18.2 | Definitions | 21 |
| 18.3 | Disclaimers | 21 |
| 18.4 | Trademarks | 22 |
| 19 | Contact information | 22 |
| 20 | Contents | 23 |

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