

NTB0101A

Auto direction sensing dual supply

Rev. 1 — 14 July 2015

Product data sheet

1. General description

The NTB0101A is a 1-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It consists of two 1-bit I/O ports (A and B), one output enable input ($\overline{\text{OE}}$) and two supply pins ($V_{\text{CC(A)}}$ and $V_{\text{CC(B)}}$). $V_{\text{CC(A)}}$ can be supplied at any voltage between 1.2 V and 3.6 V. $V_{\text{CC(B)}}$ can be supplied at any voltage between 1.65 V and 5.5 V. This flexibility allows translation between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins A and $\overline{\text{OE}}$ are referenced to $V_{\text{CC(A)}}$ and pin B is referenced to $V_{\text{CC(B)}}$. A HIGH level at pin $\overline{\text{OE}}$ causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing damage of the device due to backflow current, when it is powered down.

2. Features and benefits

- Wide supply voltage range:
 - ◆ $V_{\text{CC(A)}}$: 1.2 V to 3.6 V and $V_{\text{CC(B)}}$: 1.65 V to 5.5 V
- I_{OFF} circuitry provides partial power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for port A
 - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for port B
 - ◆ MM JESD22-A115-A exceeds 200 V
 - ◆ CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ and $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$



3. Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
NTB0101AGW	SC-88	plastic surface-mounted package; 6 leads	SOT363

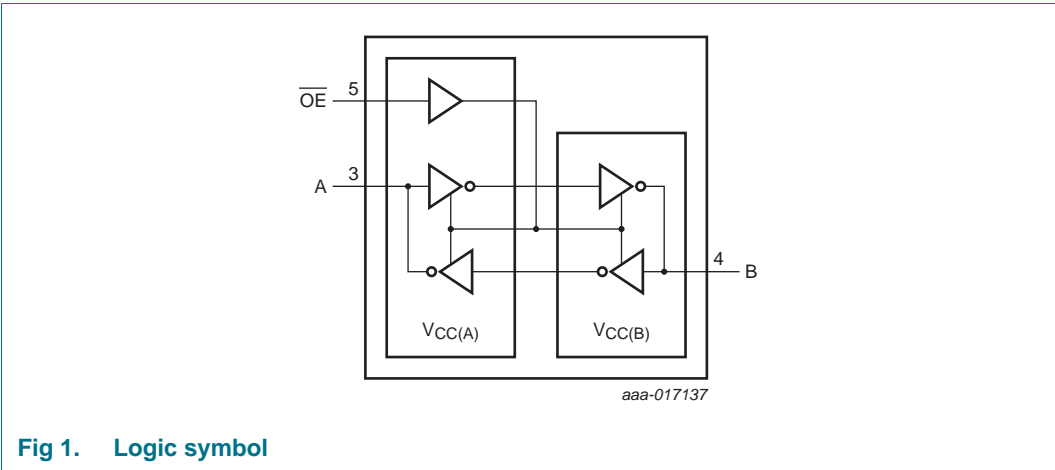
4. Marking

Table 2. Marking codes

Type number	Marking code ^[1]
NTB0101AGW	tL

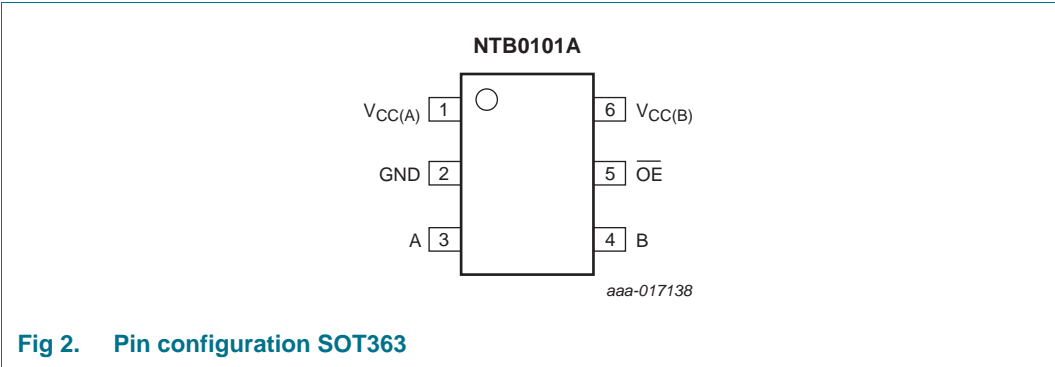
[1] The pin 1 indicator is on the lower left corner of the device, below the marking code.

5. Functional diagram



6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
$V_{CC(A)}$	1	supply voltage A
GND	2	ground (0 V)
A	3	data input or output (referenced to $V_{CC(A)}$)
B	4	data input or output (referenced to $V_{CC(B)}$)
\overline{OE}	5	output enable input (active LOW; referenced to $V_{CC(A)}$)
$V_{CC(B)}$	6	supply voltage B

7. Functional description

Table 4. Function table^[1]

Supply voltage		Input	Input/output	
$V_{CC(A)}$	$V_{CC(B)}$	\overline{OE}	A	B
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	H	Z	Z
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	L	input or output	output or input
GND ^[2]	GND ^[2]	X	Z	Z

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either $V_{CC(A)}$ or $V_{CC(B)}$ is at GND level, the device goes into power-down mode.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
$V_{CC(B)}$	supply voltage B		-0.5	+6.5	V
V_I	input voltage		-0.5	+6.5	V
V_O	output voltage	active mode	-0.5	$V_{CCO} + 0.5$	V
		power-down or 3-state mode	-0.5	+6.5	V
I_{IK}	input clamping current	$V_I < 0$ V	-50	-	mA
I_{OK}	output clamping current	$V_O < 0$ V	-50	-	mA
I_O	output current	$V_O = 0$ V to V_{CCO}	-	± 50	mA
I_{CC}	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
I_{GND}	ground current		-100	-	mA
T_{stg}	storage temperature		-65	+150	°C
P_{tot}	total power dissipation	$T_{amb} = -40$ °C to +125 °C	-	250	mW

[1] If the input and output current ratings are observed, the minimum input and minimum output voltage ratings may be exceeded.

[2] V_{CCO} is the supply voltage associated with the output.

[3] $V_{CCO} + 0.5$ V should not exceed 6.5 V.

[4] Above 87.5 °C, the value of P_{tot} derates linearly with 4.0 mW/K.

9. Recommended operating conditions

Table 6. Operating conditions^{[1][2]}

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.2	3.6	V
$V_{CC(B)}$	supply voltage B		1.65	5.5	V
V_I	input voltage		0	5.5	V
V_O	output voltage	power-down or 3-state mode; $V_{CC(A)} = 1.2\text{ V to }3.6\text{ V};$ $V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$			
		port A	0	3.6	V
		port B	0	5.5	V
T_{amb}	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CC(A)} = 1.2\text{ V to }3.6\text{ V};$ $V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	40	ns/V

[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or GND.

[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

10. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; $T_{amb} = 25\text{ °C}$; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{OH}	HIGH-level output voltage	port A; $V_{CC(A)} = 1.2\text{ V}; I_O = -20\text{ }\mu\text{A}$	-	1.1	-	V
V_{OL}	LOW-level output voltage	port A; $V_{CC(A)} = 1.2\text{ V}; I_O = 20\text{ }\mu\text{A}$	-	0.09	-	V
I_I	input leakage current	\overline{OE} input; $V_I = 0\text{ V to }3.6\text{ V}; V_{CC(A)} = 1.2\text{ V to }3.6\text{ V};$ $V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	-	± 1	μA
I_{OZ}	OFF-state output current	port A or B; $V_O = 0\text{ V to }V_{CCO}; V_{CC(A)} = 1.2\text{ V to }3.6\text{ V};$ ^[1] $V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	-	± 1	μA
I_{OFF}	power-off leakage current	port A; V_I or $V_O = 0\text{ V to }3.6\text{ V};$ $V_{CC(A)} = 0\text{ V}; V_{CC(B)} = 0\text{ V to }5.5\text{ V}$	-	-	± 1	μA
		port B; V_I or $V_O = 0\text{ V to }5.5\text{ V};$ $V_{CC(B)} = 0\text{ V}; V_{CC(A)} = 0\text{ V to }3.6\text{ V}$	-	-	± 1	μA
C_I	input capacitance	\overline{OE} input; $V_{CC(A)} = 1.2\text{ V to }3.6\text{ V}; V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	1.0	-	pF
$C_{I/O}$	input/output capacitance	port A; $V_{CC(A)} = 1.2\text{ V to }3.6\text{ V}; V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	4.0	-	pF
		port B; $V_{CC(A)} = 1.2\text{ V to }3.6\text{ V}; V_{CC(B)} = 1.65\text{ V to }5.5\text{ V}$	-	7.5	-	pF

[1] V_{CCO} is the supply voltage associated with the output.

Table 8. Typical supply currentAt recommended operating conditions; $T_{amb} = 25\text{ }^{\circ}\text{C}$; voltages are referenced to GND (ground = 0 V).

V _{CC(A)}	V _{CC(B)}								Unit
	1.8 V		2.5 V		3.3 V		5.0 V		
	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	
1.2 V	10	10	10	10	10	20	10	1050	nA
1.5 V	10	10	10	10	10	10	10	650	nA
1.8 V	10	10	10	10	10	10	10	350	nA
2.5 V	-	-	10	10	10	10	10	40	nA
3.3 V	-	-	-	-	10	10	10	10	nA

Table 9. Static characteristics^[1]

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	$T_{amb} = -40\text{ }^{\circ}\text{C to } +85\text{ }^{\circ}\text{C}$		$T_{amb} = -40\text{ }^{\circ}\text{C to } +125\text{ }^{\circ}\text{C}$		Unit
			Min	Max	Min	Max	
V_{IH}	HIGH-level input voltage	port A or port B and \overline{OE} input; $V_{CC(A)} = 1.2\text{ V to } 3.6\text{ V}$; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	$0.65V_{CCI}$	-	$0.65V_{CCI}$	-	V
V_{IL}	LOW-level input voltage	port A or port B and \overline{OE} input; $V_{CC(A)} = 1.2\text{ V to } 3.6\text{ V}$; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	-	$0.35V_{CCI}$	-	$0.35V_{CCI}$	V
V_{OH}	HIGH-level output voltage	$I_O = -20\text{ }\mu\text{A}$					
		port A; $V_{CC(A)} = 1.4\text{ V to } 3.6\text{ V}$	$V_{CCO} - 0.4$	-	$V_{CCO} - 0.4$	-	V
		port B; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	$V_{CCO} - 0.4$	-	$V_{CCO} - 0.4$	-	V
V_{OL}	LOW-level output voltage	$I_O = 20\text{ }\mu\text{A}$					
		port A; $V_{CC(A)} = 1.4\text{ V to } 3.6\text{ V}$	-	0.4	-	0.4	V
		port B; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	-	0.4	-	0.4	V
I_I	input leakage current	\overline{OE} input; $V_I = 0\text{ V to } 3.6\text{ V}$; $V_{CC(A)} = 1.2\text{ V to } 3.6\text{ V}$; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	-	± 2	-	± 5	μA
I_{OZ}	OFF-state output current	port A or port B; $V_O = 0\text{ V or } V_{CCO}$; $V_{CC(A)} = 1.2\text{ V to } 3.6\text{ V}$; $V_{CC(B)} = 1.65\text{ V to } 5.5\text{ V}$	-	± 2	-	± 10	μA
I_{OFF}	power-off leakage current	port A; V_I or $V_O = 0\text{ V to } 3.6\text{ V}$; $V_{CC(A)} = 0\text{ V}$; $V_{CC(B)} = 0\text{ V to } 5.5\text{ V}$	-	± 2	-	± 10	μA
		port B; V_I or $V_O = 0\text{ V to } 5.5\text{ V}$; $V_{CC(B)} = 0\text{ V}$; $V_{CC(A)} = 0\text{ V to } 3.6\text{ V}$	-	± 2	-	± 10	μA

Table 9. Static characteristics^[1] ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	T _{amb} = -40 °C to +85 °C		T _{amb} = -40 °C to +125 °C		Unit
			Min	Max	Min	Max	
I _{CC}	supply current	V _I = 0 V or V _{CCI} ; I _O = 0 A					
		I _{CC(A)}					
		$\overline{\text{OE}}$ = HIGH; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V	-	3	-	15	μA
		$\overline{\text{OE}}$ = LOW; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V	-	3	-	20	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	2	-	15	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V	-	-2	-	-15	μA
		I _{CC(B)}					
		$\overline{\text{OE}}$ = HIGH; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V	-	5	-	15	μA
		$\overline{\text{OE}}$ = LOW; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V	-	5	-	20	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	-2	-	-15	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V	-	2	-	15	μA
		I _{CC(A)} + I _{CC(B)}					
		V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V	-	8	-	40	μA

[1] V_{CCI} is the supply voltage associated with the input and V_{CCO} is the supply voltage associated with the output.

11. Dynamic characteristics

Table 10. Typical dynamic characteristics^[1]Voltages are referenced to GND (ground = 0 V); typical values are measured with V_{CC(A)} = 1.2 V and T_{amb} = 25 °C; for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}				Unit
			1.8 V	2.5 V	3.3 V	5.0 V	
t _{pd}	propagation delay	A to B	5.9	4.8	4.4	4.2	ns
		B to A	5.6	4.8	4.5	4.4	ns
t _{en}	enable time	$\overline{\text{OE}}$ to A, B	0.5	0.5	0.5	0.5	μs
t _{dis}	disable time	$\overline{\text{OE}}$ to A; no external load ^[2]	6.9	6.9	6.9	6.9	ns
		$\overline{\text{OE}}$ to B; no external load ^[2]	9.5	8.6	8.5	8.0	ns
		$\overline{\text{OE}}$ to A	81	69	83	68	ns
		$\overline{\text{OE}}$ to B	81	69	83	68	ns
t _t	transition time	port A	4.0	4.0	4.1	4.1	ns
		port B	2.6	2.0	1.7	1.4	ns
t _W	pulse width	data inputs	15	13	13	13	ns
f _{data}	data rate		70	80	80	80	Mbit/s

- [1] t_{pd} is the same as t_{PLH} and t_{PHL} .
 t_{en} is the same as t_{PZL} and t_{PZH} .
 t_{dis} is the same as t_{PLZ} and t_{PHZ} .
 t_t is the same as t_{THL} and t_{TLH} .
- [2] Delay between \overline{OE} going HIGH and when the outputs are disabled.

Table 11. Dynamic characteristics for temperature range $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ ^[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}								Unit
			1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	
V _{CC(A)} = 1.5 V ± 0.1 V											
t _{pd}	propagation delay	A to B	1.4	12.9	1.2	10.1	1.1	10.0	0.8	9.9	ns
		B to A	0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t _{en}	enable time	\overline{OE} to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t _{dis}	disable time	\overline{OE} to A; no external load [2]	1.0	11.9	1.0	11.9	1.0	11.9	1.0	11.9	ns
		\overline{OE} to B; no external load [2]	1.0	16.9	1.0	15.2	1.0	14.1	1.0	13.8	ns
		\overline{OE} to A	-	320	-	260	-	260	-	280	ns
		\overline{OE} to B	-	200	-	200	-	200	-	200	ns
t _t	transition time	port A	0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
		port B	0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t _W	pulse width	data inputs	25	-	25	-	25	-	25	-	ns
f _{data}	data rate		-	40	-	40	-	40	-	40	Mbit/s
V _{CC(A)} = 1.8 V ± 0.15 V											
t _{pd}	propagation delay	A to B	1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
		B to A	1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t _{en}	enable time	\overline{OE} to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t _{dis}	disable time	\overline{OE} to A; no external load [2]	1.0	11.0	1.0	11.0	1.0	11.0	1.0	11.0	ns
		\overline{OE} to B; no external load [2]	1.0	15.4	1.0	13.5	1.0	12.4	1.0	12.1	ns
		\overline{OE} to A	-	260	-	230	-	230	-	230	ns
		\overline{OE} to B	-	200	-	200	-	200	-	200	ns
t _t	transition time	port A	0.8	4.1	0.8	4.1	0.8	4.1	0.8	4.1	ns
		port B	0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t _W	pulse width	data inputs	20	-	17	-	17	-	17	-	ns
f _{data}	data rate		-	49	-	60	-	60	-	60	Mbit/s
V _{CC(A)} = 2.5 V ± 0.2 V											
t _{pd}	propagation delay	A to B	-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
		B to A	-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t _{en}	enable time	\overline{OE} to A, B	-	-	-	1.0	-	1.0	-	1.0	μs

Table 11. Dynamic characteristics for temperature range -40°C to $+85^{\circ}\text{C}$ ^[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}								Unit
			1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	
t _{dis}	disable time	OE to A; no external load [2]	-	-	1.0	9.2	1.0	9.2	1.0	9.2	ns
		OE to B; no external load [2]	-	-	1.0	11.9	1.0	10.7	1.0	10.2	ns
		OE to A	-	-	-	200	-	200	-	200	ns
		OE to B	-	-	-	200	-	200	-	200	ns
t _t	transition time	port A	-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
		port B	-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t _W	pulse width	data inputs	-	-	12	-	10	-	10	-	ns
f _{data}	data rate		-	-	-	85	-	100	-	100	Mbit/s
V _{CC(A)} = 3.3 V ± 0.3 V											
t _{pd}	propagation delay	A to B	-	-	-	-	0.9	4.7	0.8	4.0	ns
		B to A	-	-	-	-	1.0	4.9	0.9	3.8	ns
t _{en}	enable time	OE to A, B	-	-	-	-	-	1.0	-	1.0	μs
t _{dis}	disable time	OE to A; no external load [2]	-	-	-	-	1.0	9.2	1.0	9.2	ns
		OE to B; no external load [2]	-	-	-	-	1.0	10.1	1.0	9.6	ns
		OE to A	-	-	-	-	-	260	-	260	ns
		OE to B	-	-	-	-	-	200	-	200	ns
t _t	transition time	port A	-	-	-	-	0.7	2.5	0.7	2.5	ns
		port B	-	-	-	-	0.5	2.5	0.4	2.7	ns
t _W	pulse width	data inputs	-	-	-	-	10	-	10	-	ns
f _{data}	data rate		-	-	-	-	-	100	-	100	Mbit/s

[1] t_{pd} is the same as t_{PLH} and t_{PHL} .

t_{en} is the same as t_{PZL} and t_{PZH} .

t_{dis} is the same as t_{PLZ} and t_{PHZ} .

t_t is the same as t_{THL} and t_{TLH} .

[2] Delay between $\overline{\text{OE}}$ going HIGH and when the outputs are disabled.

Table 12. Dynamic characteristics for temperature range -40°C to $+125^{\circ}\text{C}$ ^[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}								Unit
			1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	
V _{CC(A)} = 1.5 V ± 0.1 V											
t _{pd}	propagation delay	A to B	1.4	15.9	1.2	13.1	1.1	13.0	0.8	12.9	ns
		B to A	0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t _{en}	enable time	$\overline{\text{OE}}$ to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs

Table 12. Dynamic characteristics for temperature range -40°C to $+125^{\circ}\text{C}$ [\[1\]](#) ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}								Unit
			1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	
t _{dis}	disable time	$\overline{\text{OE}}$ to A; no external load [2]	1.0	12.5	1.0	12.5	1.0	12.5	1.0	12.5	ns
		$\overline{\text{OE}}$ to B; no external load [2]	1.0	18.1	1.0	16.2	1.0	14.9	1.0	14.6	ns
		$\overline{\text{OE}}$ to A	-	340	-	280	-	280	-	300	ns
		$\overline{\text{OE}}$ to B	-	220	-	220	-	220	-	220	ns
t _t	transition time	port A	0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
		port B	0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t _W	pulse width	data inputs	25	-	25	-	25	-	25	-	ns
f _{data}	data rate		-	40	-	40	-	40	-	40	Mbit/s
V _{CC(A)} = 1.8 V ± 0.15 V											
t _{pd}	propagation delay	A to B	1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
		B to A	1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
t _{en}	enable time	$\overline{\text{OE}}$ to A, B	-	1.0	-	1.0	-	1.0	-	1.0	μs
t _{dis}	disable time	$\overline{\text{OE}}$ to A; no external load [2]	1.0	11.5	1.0	11.5	1.0	11.5	1.0	11.5	ns
		$\overline{\text{OE}}$ to B; no external load [2]	1.0	16.5	1.0	14.5	1.0	13.3	1.0	12.7	ns
		$\overline{\text{OE}}$ to A	-	280	-	250	-	250	-	250	ns
		$\overline{\text{OE}}$ to B	-	220	-	220	-	220	-	220	ns
t _t	transition time	port A	0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
		port B	0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t _W	pulse width	data inputs	22	-	19	-	19	-	19	-	ns
f _{data}	data rate		-	45	-	55	-	55	-	55	Mbit/s
V _{CC(A)} = 2.5 V ± 0.2 V											
t _{pd}	propagation delay	A to B	-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
		B to A	-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t _{en}	enable time	$\overline{\text{OE}}$ to A, B	-	-	-	1.0	-	1.0	-	1.0	μs
t _{dis}	disable time	$\overline{\text{OE}}$ to A; no external load [2]	-	-	1.0	9.6	1.0	9.6	1.0	9.6	ns
		$\overline{\text{OE}}$ to B; no external load [2]	-	-	1.0	12.6	1.0	11.4	1.0	10.8	ns
		$\overline{\text{OE}}$ to A	-	-	-	220	-	220	-	220	ns
		$\overline{\text{OE}}$ to B	-	-	-	220	-	220	-	220	ns
t _t	transition time	port A	-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
		port B	-	-	0.7	4.6	0.5	4.8	0.4	4.7	ns
t _W	pulse width	data inputs	-	-	14	-	13	-	10	-	ns
f _{data}	data rate		-	-	-	75	-	80	-	100	Mbit/s
V _{CC(A)} = 3.3 V ± 0.3 V											
t _{pd}	propagation delay	A to B	-	-	-	-	0.9	7.7	0.8	7.0	ns
		B to A	-	-	-	-	1.0	7.9	0.9	6.8	ns
t _{en}	enable time	$\overline{\text{OE}}$ to A, B	-	-	-	-	-	1.0	-	1.0	μs

Table 12. Dynamic characteristics for temperature range -40°C to $+125^{\circ}\text{C}$ ^[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 5](#); for waveforms, see [Figure 3](#) and [Figure 4](#).

Symbol	Parameter	Conditions	V _{CC(B)}								Unit
			1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	
t _{dis}	disable time	$\overline{\text{OE}}$ to A; no external load [2]	-	-	-	-	1.0	9.5	1.0	9.5	ns
		$\overline{\text{OE}}$ to B; no external load [2]	-	-	-	-	1.0	10.7	1.0	9.6	ns
		$\overline{\text{OE}}$ to A	-	-	-	-	-	280	-	280	ns
		$\overline{\text{OE}}$ to B	-	-	-	-	-	220	-	220	ns
t _t	transition time	port A	-	-	-	-	0.7	4.5	0.7	4.5	ns
		port B	-	-	-	-	0.5	4.1	0.4	4.7	ns
t _W	pulse width	data inputs	-	-	-	-	10	-	10	-	ns
f _{data}	data rate		-	-	-	-	-	100	-	100	Mbit/s

- [1] t_{pd} is the same as t_{PLH} and t_{PHL} .
 t_{en} is the same as t_{PZL} and t_{PZH} .
 t_{dis} is the same as t_{PLZ} and t_{PHZ} .
 t_t is the same as t_{THL} and t_{TLH} .

- [2] Delay between $\overline{\text{OE}}$ going HIGH and when the outputs are disabled.

Table 13. Typical power dissipation capacitance table^{[1][2]}

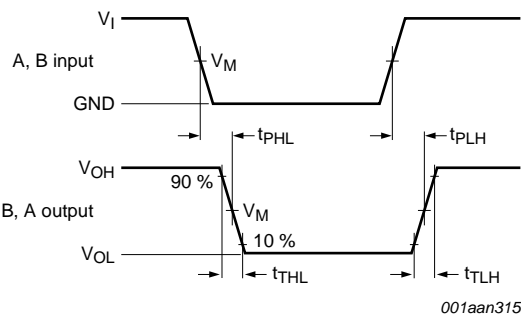
Tested at $T_{\text{amb}} = 25^{\circ}\text{C}$; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	V _{CC(A)}							Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
			V _{CC(B)}							
			1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
C _{PD}	power dissipation capacitance	outputs enabled; $\overline{\text{OE}} = \text{GND}$								
		port A: (direction A to B)	5	5	5	5	5	5	5	pF
		port A: (direction B to A)	8	8	8	8	8	8	8	pF
		port B: (direction A to B)	18	18	18	18	18	18	18	pF
		port B: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; $\overline{\text{OE}} = \text{V}_{\text{CC(A)}}$								
		port A: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		port A: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		port B: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		port B: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

- [1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).
 $P_D = C_{\text{PD}} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o)$ where:
 f_i = input frequency in MHz;
 f_o = output frequency in MHz;
 C_L = load capacitance in pF;
 V_{CC} = supply voltage in V;
 N = number of inputs switching;
 $\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

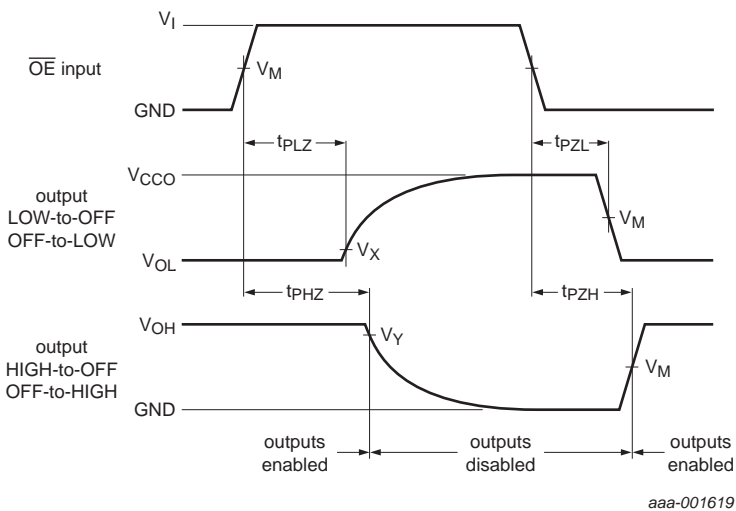
- [2] $f_i = 10\text{ MHz}$; $V_i = \text{GND to } V_{CC}$; $t_r = t_f = 1\text{ ns}$; $C_L = 0\text{ pF}$; $R_L = \infty\ \Omega$.

12. Waveforms



Measurement points are given in [Table 14](#).
 V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

Fig 3. Data input (A, B) to data output (B, A) propagation delay times



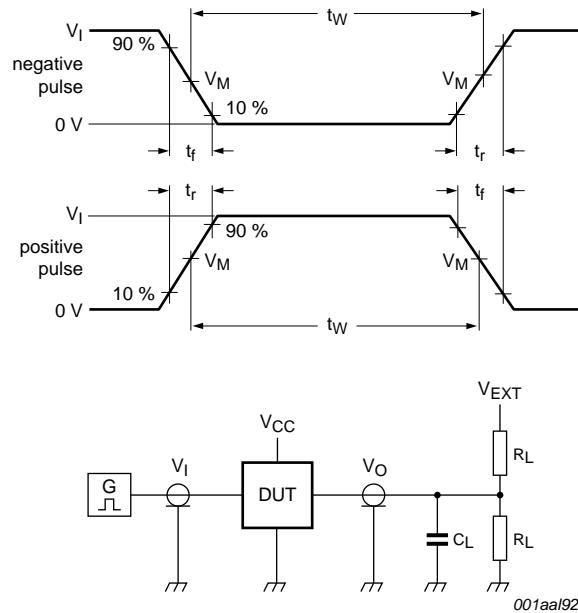
Measurement points are given in [Table 14](#).
 V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

Fig 4. Enable and disable times

Table 14. Measurement points^[1]

Supply voltage	Input	Output		
		V_M	V_X	V_Y
V_{CCO}	V_M	V_M	V_X	V_Y
1.2 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.1\text{ V}$	$V_{OH} - 0.1\text{ V}$
$1.5\text{ V} \pm 0.1\text{ V}$	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.1\text{ V}$	$V_{OH} - 0.1\text{ V}$
$1.8\text{ V} \pm 0.15\text{ V}$	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.15\text{ V}$	$V_{OH} - 0.15\text{ V}$
$2.5\text{ V} \pm 0.2\text{ V}$	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.15\text{ V}$	$V_{OH} - 0.15\text{ V}$
$3.3\text{ V} \pm 0.3\text{ V}$	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.3\text{ V}$	$V_{OH} - 0.3\text{ V}$
$5.0\text{ V} \pm 0.5\text{ V}$	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.3\text{ V}$	$V_{OH} - 0.3\text{ V}$

[1] V_{CCI} is the supply voltage associated with the input and V_{CCO} is the supply voltage associated with the output.



Test data is given in [Table 15](#).

All input pulses are supplied by generators having the following characteristics: $PRR \leq 10$ MHz; $Z_O = 50 \Omega$; $dV/dt \geq 1.0$ V/ns.

R_L = Load resistance.

C_L = Load capacitance including jig and probe capacitance.

V_{EXT} = External voltage for measuring switching times.

Fig 5. Test circuit for measuring switching times

Table 15. Test data

Supply voltage		Input		Load		V_{EXT}		
$V_{CC(A)}$	$V_{CC(B)}$	V_I ^[1]	$\Delta t/\Delta V$	C_L	R_L ^[2]	t_{PLH} , t_{PHL}	t_{PZH} , t_{PHZ}	t_{PZL} , t_{PLZ} ^[3]
1.2 V to 3.6 V	1.65 V to 5.5 V	V_{CCI}	≤ 1.0 ns/V	15 pF	50 k Ω , 1 M Ω	open	open	$2V_{CCO}$

[1] V_{CCI} is the supply voltage associated with the input.

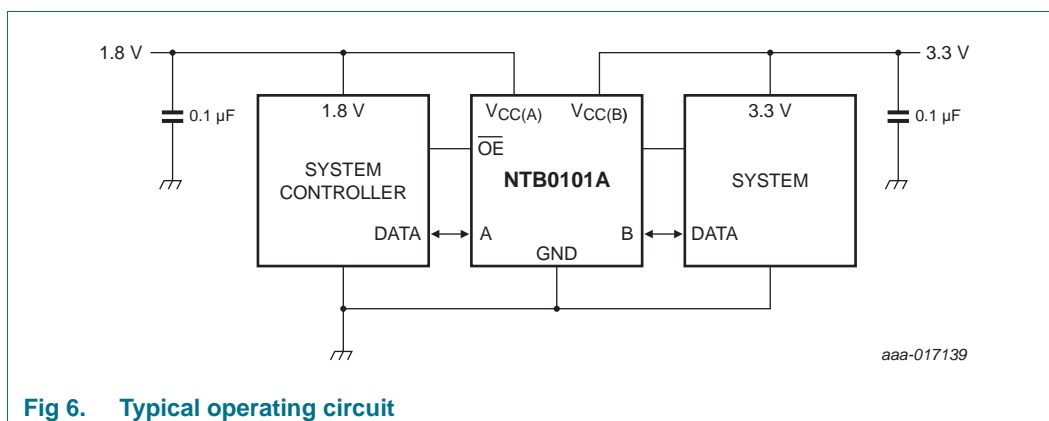
[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1$ M Ω . For measuring enable and disable times, $R_L = 50$ k Ω .

[3] V_{CCO} is the supply voltage associated with the output.

13. Application information

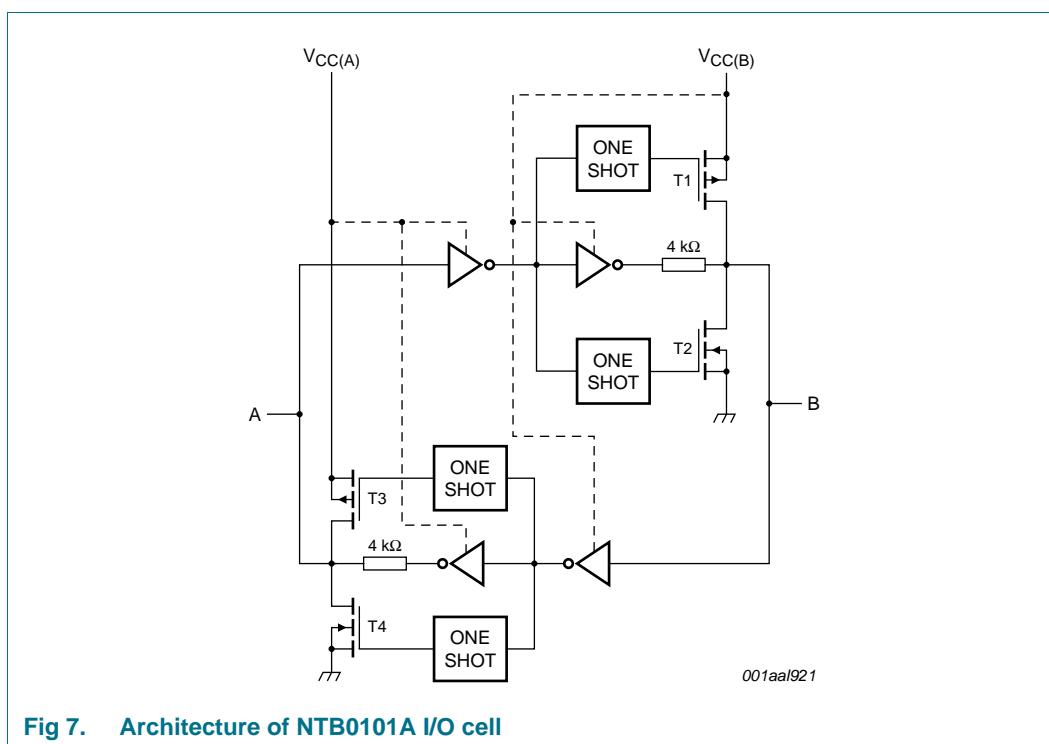
13.1 Applications

Voltage level-translation applications. The NTB0101A can be used to interface between devices or systems operating at different supply voltages. See [Figure 6](#) for a typical operating circuit using the NTB0101A.



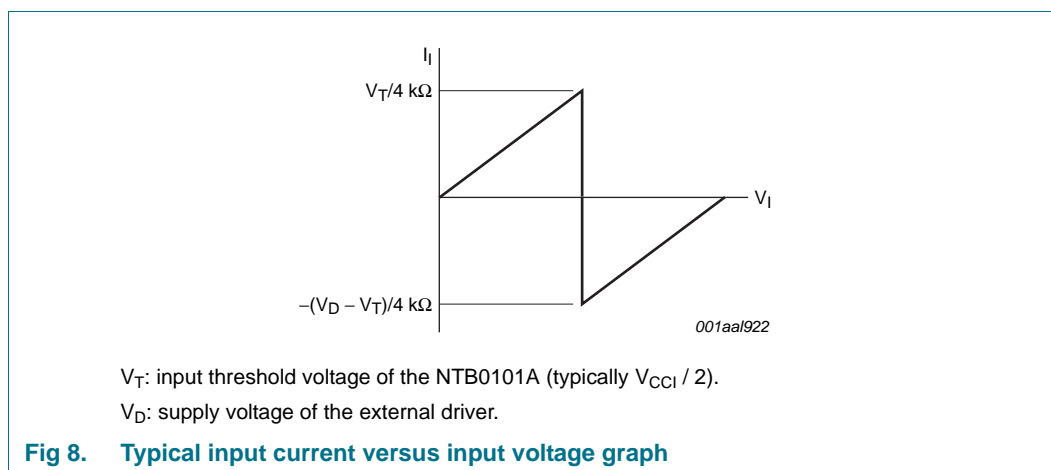
13.2 Architecture

The architecture of the NTB0101A is shown in Figure 7. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTB0101A can maintain a defined output level, but the output architecture is weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output of one-shot circuits detect rising or falling edges on the ports A or B. During a rising edge, the one-shot circuits turn on the PMOS transistors (T1, T3) for a short duration, accelerating the LOW-to-HIGH transition. Similarly, during a falling edge, the one-shot circuits turn on the NMOS transistors (T2, T4) for a short duration, accelerating the HIGH-to-LOW transition. During output transitions, the typical output impedance is $70\ \Omega$ at $V_{CCO} = 1.2\ \text{V}$ to $1.8\ \text{V}$. It is $50\ \Omega$ at $V_{CCO} = 1.8\ \text{V}$ to $3.3\ \text{V}$ and $40\ \Omega$ at $V_{CCO} = 3.3\ \text{V}$ to $5.0\ \text{V}$.



13.3 Input driver requirements

For correct operation, the device that drives the data I/Os of the NTB0101A must have a minimum drive capability of ± 2 mA. See [Figure 8](#) for a plot of typical input current versus input voltage.



13.4 Power-up

$V_{CC(A)}$ must never be higher than $V_{CC(B)}$ during operation. However during power-up, $V_{CC(A)} \geq V_{CC(B)}$ does not damage the device. Either of the power supplies can be ramped up first and hence no special power-up sequencing is required. The NTB0101A includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

13.5 Enable and disable

An output enable input (\overline{OE}) is used to disable the device. Setting $\overline{OE} = \text{HIGH}$ causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when \overline{OE} goes HIGH and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for a one-shot circuitry to become operational after \overline{OE} is taken LOW. To ensure a high-impedance OFF-state during power-up or power-down, pin \overline{OE} should be tied to $V_{CC(A)}$ through a pull-up resistor. The minimum value of the resistor determines the current-sourcing capability of the driver.

13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously, the NTB0101A is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, all pull-up or pull-down resistors used, must be above 50 kΩ. For this reason, NTB0101A is not recommended for use in open-drain driver applications such as 1-Wire or I²C-bus. For these applications, the NTS0101 level translator is recommended.

14. Package outline

Plastic surface-mounted package; 6 leads

SOT363

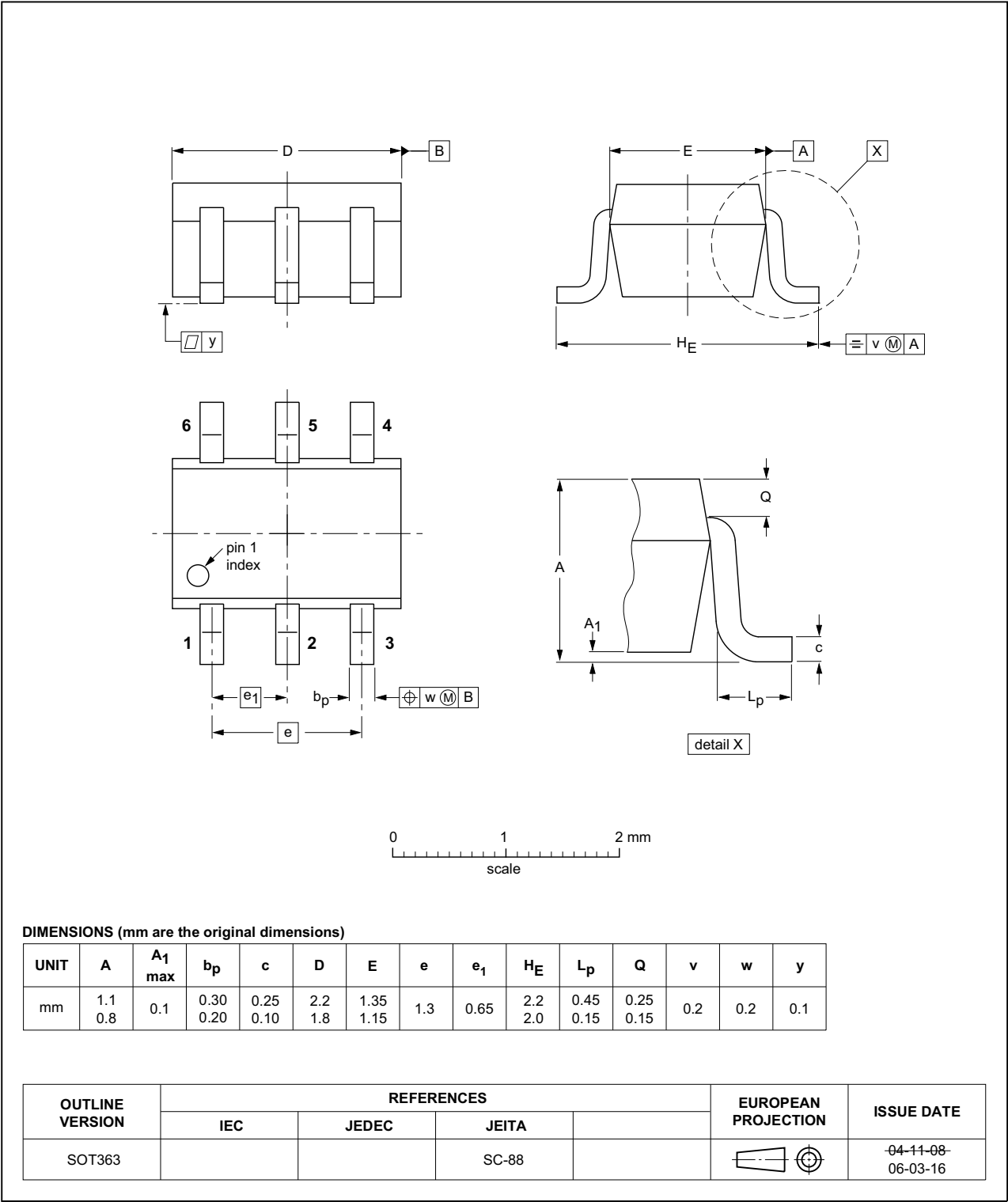


Fig 9. Package outline SOT363 (SC-88)

15. Abbreviations

Table 16. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model
NMOS	N-type Metal Oxide Semiconductor
PMOS	P-type Metal Oxide Semiconductor
PRR	Pulse Repetition Rate

16. Revision history

Table 17. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTB0101A v.1	20150714	Product data sheet	-	-

17. Legal information

17.1 Data sheet status

Document status ^{[1][2]}	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

17.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

17.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond

NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

Translations — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

17.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

18. Contact information

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

19. Contents

1	General description	1
2	Features and benefits	1
3	Ordering information	2
4	Marking	2
5	Functional diagram	2
6	Pinning information	2
6.1	Pinning	2
6.2	Pin description	3
7	Functional description	3
8	Limiting values	3
9	Recommended operating conditions	4
10	Static characteristics	4
11	Dynamic characteristics	6
12	Waveforms	11
13	Application information	12
13.1	Applications	12
13.2	Architecture	13
13.3	Input driver requirements	14
13.4	Power-up	14
13.5	Enable and disable	14
13.6	Pull-up or pull-down resistors on I/O lines ...	14
14	Package outline	15
15	Abbreviations	16
16	Revision history	16
17	Legal information	17
17.1	Data sheet status	17
17.2	Definitions	17
17.3	Disclaimers	17
17.4	Trademarks	18
18	Contact information	18
19	Contents	19

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP Semiconductors N.V. 2015.

All rights reserved.

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 14 July 2015

Document identifier: NTB0101A

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

[NXP:](#)

[NTB0101GW,125](#) [NTB0101GF,132](#) [NTB0101GM,115](#) [NTB0101GS,132](#) [NTB0101GN,132](#) [NTB0101GW-Q100H](#)
[NTB0101AGWH](#) [NTB0101GS1XL](#) [NTB0101GS1Z](#)