

Safety Power System Basis Chip with CAN FD and LIN Transceivers

Rev. 1.0 — 14 December 2017

Short data sheet: advance information

1 General description

The FS6500/FS4500 SMARTMOS devices are a multi-output, power supply, integrated circuit, including CAN Flexible Data (FD) and/or LIN transceivers, dedicated to the automotive market.

Multiple switching and linear voltage regulators, including low-power mode (32 μ A) are available with various wake-up capabilities. An advanced power management scheme is implemented to maintain high efficiency over a wide range of input voltages (down to 2.7 V) and output current ranges (up to 2.2 A).

The FS6500/FS4500 includes configurable fail-safe/fail silent safety behavior and features, with two fail-safe outputs, becoming a full part of a safety oriented system partitioning, to reach a high integrity safety level (up to ASIL D).

The built-in CAN FD interface fulfills the ISO 11898-2 and -5 standards. The LIN interface fulfills LIN protocol specifications 2.0, 2.1, 2.2, and SAEJ2602-2.

2 Features

- Battery voltage sensing and MUX output pin
- Highly flexible SMPS pre-regulator, allowing two topologies: non-inverting buck-boost and standard buck
- Family of devices to supply MCU core from 1.0 V to 5.0 V, with SMPS (0.8 A, 1.5 A or 2.2 A) or LDO (0.5 A)
- 36 V maximum input operating voltage
- Linear voltage regulator dedicated to auxiliary functions, or to sensor supply (V_{CCA} tracker or independent), 5.0 V or 3.3 V
- Linear voltage regulator dedicated to MCU A/D reference voltage or I/Os supply (V $_{\rm CCA}), 5.0$ V or 3.3 V
- 3.3 V keep alive memory supply available in low-power mode
- Long duration timer, counting up to 6 months with 1.0 s resolution
- · Multiple wake-up sources in low-power mode: CAN, LIN, IOs, LDT
- Five configurable I/Os

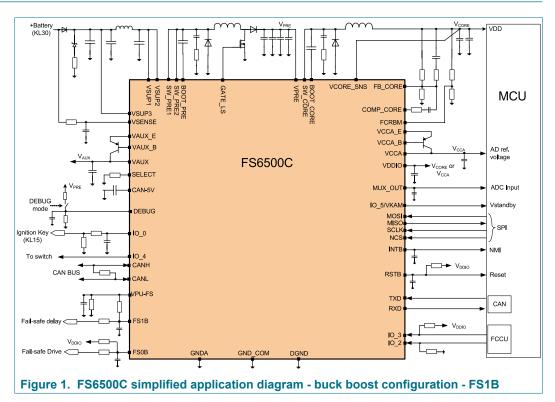
3 Applications

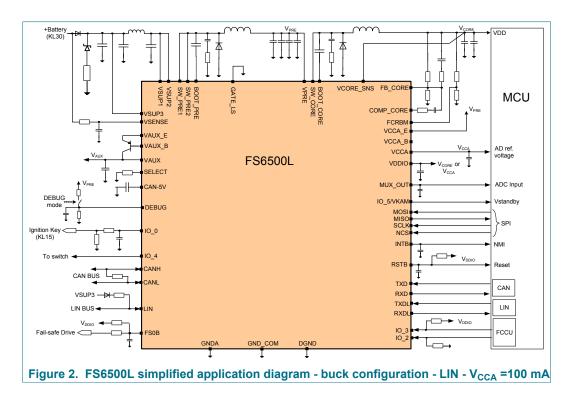
- Drive train electrification (BMS, hybrid EV and HEV, inverter, DCDC, alterno starter)
- Drive train chassis and safety (active suspension, steering, safety domain gateway)
- Power train (EMS, TCU, gear box)
- ADAS (LDW, Radar, sensor fusion safety area)



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4 Simplified application diagram



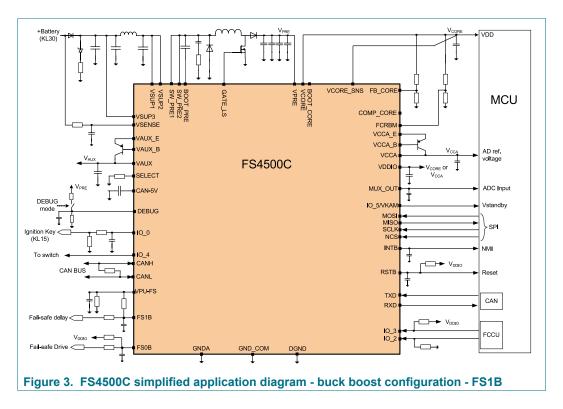


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5 Ordering information

5.1 Part numbers definition

MC33FS <u>c</u> 5 <u>x</u> <u>y</u> <u>z</u> AE/R2

Table 1. Part number breakdown

Code	Option	Variable	Description		
с	4 series	V tuno	Linear		
6 series	V _{CORE} type	DCDC			
х	0		0.5 A or 0.8 A		
	1	V _{CORE} current	1.5 A		
2			2.2 A		
у	0		none		
	1		FS1B		
	2	Functions	LDT		
3 4			FS1B, LDT		
			LDT, VKAM ON by default		
z	N		none		
	С	Physical interface	CAN FD		
	L		CAN FD and LIN		

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5.2 Part numbers list

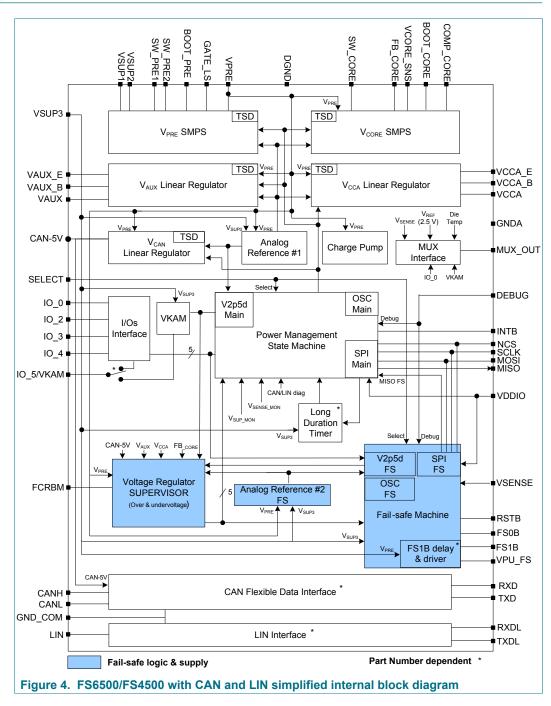
Part number	Temperature (T _A)	Package	FS1B	LDT	VCORE	VCORE type	VKAM on	CAN FD	LIN	Notes
MC33FS4500CAE			0	0	0.5 A	Linear	by SPI	1	0	
AC33FS4500LAE	-		0	0	0.5 A	Linear	by SPI	1	1	
MC33FS4500NAE	_		0	0	0.5 A	Linear	by SPI	0	0	
MC33FS4501CAE	_		1	0	0.5 A	Linear	by SPI	1	0	
MC33FS4501NAE	_		1	0	0.5 A	Linear	by SPI	0	0	
MC33FS4502CAE	_		0	1	0.5 A	Linear	by SPI	1	0	
MC33FS4502LAE			0	1	0.5 A	Linear	by SPI	1	1	
MC33FS4502NAE			0	1	0.5 A	Linear	by SPI	0	0	
MC33FS4503CAE			1	1	0.5 A	Linear	by SPI	1	0	
MC33FS4503NAE			1	1	0.5 A	Linear	by SPI	0	0	
MC33FS6500CAE	1		0	0	0.8 A	DC DC	by SPI	1	0	
MC33FS6500LAE			0	0	0.8 A	DC DC	by SPI	1	1	
MC33FS6500NAE			0	0	0.8 A	DC DC	by SPI	0	0	
MC33FS6501CAE			1	0	0.8 A	DC DC	by SPI	1	0	
MC33FS6501NAE			1	0	0.8 A	DC DC	by SPI	0	0	
MC33FS6502CAE			0	1	0.8 A	DC DC	by SPI	1	0	
MC33FS6502LAE			0	1	0.8 A	DC DC	by SPI	1	1	
IC33FS6502NAE			0	1	0.8 A	DC DC	by SPI	0	0	
AC33FS6503CAE			1	1	0.8 A	DC DC	by SPI	1	0	
IC33FS6503NAE			1	1	0.8 A	DC DC	by SPI	0	0	
MC33FS6504LAE	-40 °C to 125 °C	48-pin LQFP	0	1	0.8 A	DC DC	by default	1	1	[1] [2]
MC33FS6510CAE	-40 C to 125 C	exposed pad	0	0	1.5 A	DC DC	by SPI	1	0	
MC33FS6510LAE			0	0	1.5 A	DC DC	by SPI	1	1	
MC33FS6510NAE			0	0	1.5 A	DC DC	by SPI	0	0	
MC33FS6511CAE			1	0	1.5 A	DC DC	by SPI	1	0	
MC33FS6511NAE			1	0	1.5 A	DC DC	by SPI	0	0	
MC33FS6512CAE			0	1	1.5 A	DC DC	by SPI	1	0	
MC33FS6512LAE			0	1	1.5 A	DC DC	by SPI	1	1	
MC33FS6512NAE			0	1	1.5 A	DC DC	by SPI	0	0	
MC33FS6513CAE			1	1	1.5 A	DC DC	by SPI	1	0	
MC33FS6513NAE			1	1	1.5 A	DC DC	by SPI	0	0	
MC33FS6514LAE			0	1	1.5 A	DC DC	by default	1	1	
MC33FS6520CAE			0	0	2.2 A	DC DC	by SPI	1	0	
MC33FS6520LAE			0	0	2.2 A	DC DC	by SPI	1	1	
AC33FS6520NAE			0	0	2.2 A	DC DC	by SPI	0	0	
AC33FS6521CAE			1	0	2.2 A	DC DC	by SPI	1	0	
MC33FS6521NAE			1	0	2.2 A	DC DC	by SPI	0	0	
MC33FS6522CAE			0	1	2.2 A	DC DC	by SPI	1	0	
AC33FS6522LAE			0	1	2.2 A	DC DC	by SPI	1	1	
MC33FS6522NAE			0	1	2.2 A	DC DC	by SPI	0	0	
MC33FS6523CAE			1	1	2.2 A	DC DC	by SPI	1	0	
MC33FS6523NAE			1	1	2.2 A	DC DC	by SPI	0	0	

[1] [2] To order parts in tape and reel, add the R2 suffix to the part number.

LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS1B is not, and vice versa. VKAM on by default is available on certain part numbers only.

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6 Block diagram

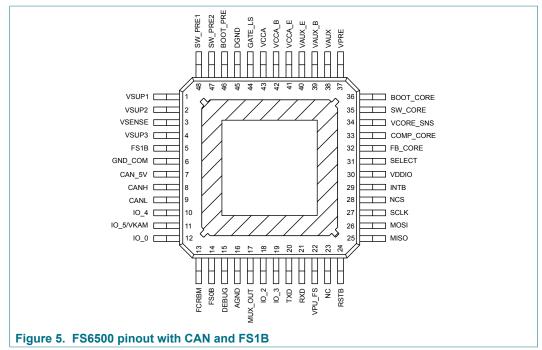


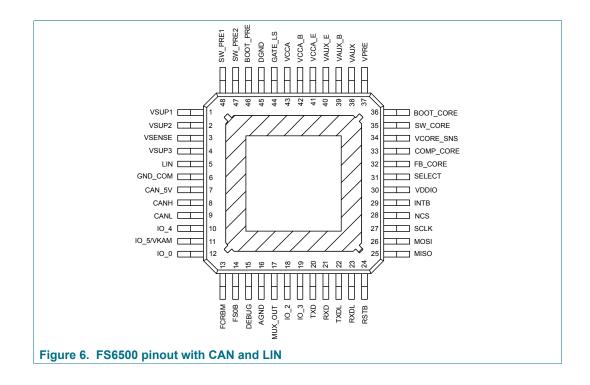
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7 Pinning information

7.1 Pinning



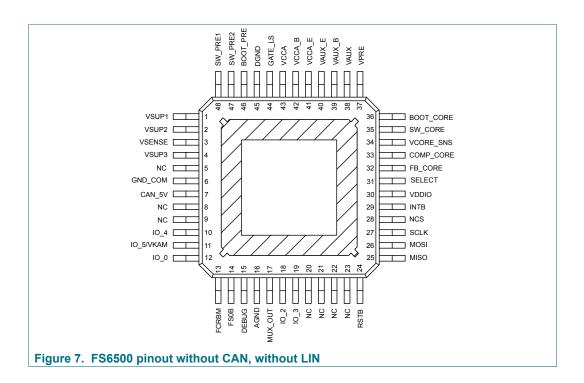


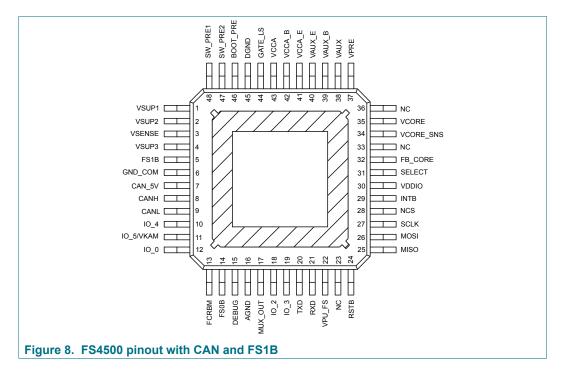
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7.2 Pin description

Table 3. FS6500/FS4500 pin definition

Pin	Symbol	Туре	Definition
1	VSUP1	A_IN	Power supply of the device. An external reverse battery protection diode in series is mandatory.

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Pin	Symbol	Туре	Definition			
2	VSUP2	A_IN	Second power supply. Protected by the external reverse battery protection diode used for VSUP1. VSUP1 and VSUP2 must be connected together externally.			
3	VSENSE	A_IN	Sensing of the battery voltage. Must be connected prior to the reverse battery protection diode.			
4	VSUP3	A_IN	Third power supply dedicated to the device supply. Protected by the external reverse battery protection diode used for VSUP1. Must be connected between the reverse protection diode and the input PI filter.			
	LIN	A_IN/OUT	LIN single-wire bus transmitter and receiver			
5	or FS1B	D_OUT	Second output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected, with a configurable delay or duration versus FS0B output terminal. Open drain structure.			
			xclusive. The differentiation is made by part numbers. When LIN is available, FS1B is not, nor FS1B functions are used, this pin must be left open.			
6	GND_COM	GROUND	Dedicated ground for physical layers			
7	CAN_5V	A_OUT	Output voltage for the embedded CAN FD interface			
8	CANH	A_IN/OUT	CAN output high. If CAN function is not used, this pin must be left open.			
9	CANL	A_IN/OUT	CAN output low. If CAN function is not used, this pin must be left open.			
10	IO_4	D_IN A_OUT	Can be used as digital input (load dump proof) with wake-up capability or as an output gate driver Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used in conjunction with IO_5). Wake-up capability: Can be selectable to wake-up on edges or levels Output gate driver: Can drive a logic level low-side NMOS transistor. Controlled by the SPI.			
11	IO_5/VKAM	A_IN D_IN A_OUT	Can be used as digital input with wake-up capability or as an analog output providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used in conjunction with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels Supply output: Provide keep alive memory supply in low-power mode			
	VKAM can be	enabled or disa	bled by default at power up. The differentiation is made by part numbers.			
12	10_0	A_IN D_IN	Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI Wake-up capability: Can be selectable to wake-up on edges or levels			
13	FCRBM	A_IN	Feedback core resistor bridge monitoring: For safety purposes, this pin is used to monitor the middle point of a redundant resistor bridge connected on V_{CORE} (in parallel to the one used to set the V_{CORE} voltage). If not used, this pin must be connected directly to FB_CORE.			
14	FS0B	D_OUT	First output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected. Open drain structure.			
15	DEBUG	D_IN	Debug mode entry input			
16	AGND	GROUND	Analog ground connection			
17	MUX_OUT	A_OUT	Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI.			
18 19	IO_2:3	D_IN	Digital input pin with wake-up capability (logic level compatible) Digital input: Pin status can be read through the SPI. Can be used to monitor FCCU error signals from MCU for safety purposes. Wake-up capability: Can be selectable to wake-up on edges or levels			

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Pin	Symbol	Туре	Definition			
20	TXD	D_IN	Transceiver input from the MCU which controls the state of the CAN bus. Internal pull- up to VDDIO. If CAN function is not used, this pin must be left open.			
21	RXD	D_OUT	Receiver output which reports the state of the CAN bus to the MCU If CAN function is not used, this pin must be left open			
²² TXDL D_		D_IN	Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-up to VDDIO.			
	or VPU_FS	A_OUT	Pull-up output for FS1B function			
			xclusive. The differentiation is made by part numbers. When LIN is available, FS1B is not, nor FS1B functions are used, this pin must be left open.			
23	RXDL	D_OUT	Receiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.			
24	RSTB	D_OUT	This output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to detect external reset and fault condition. Open drain structure.			
25	MISO	D_OUT	SPI bus. Master input slave output			
26	MOSI	D_IN	SPI bus. Master output slave input			
27	SCLK	D_IN	SPI Bus. Serial clock			
28	NCS	D_IN	Not chip select (active low)			
29	INTB	D_OUT	This output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.			
30	VDDIO	A_IN	Input voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.			
31	SELECT	D_IN	Hardware selection pin for VAUX and VCCA output voltages			
32	FB_CORE	A_IN	VCORE voltage feedback. Input of the error amplifier.			
33	COMP_COR E	A_OUT	Compensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).			
34	VCORE_SNS	A_IN	VCORE input voltage sense			
35	SW_CORE	A_OUT	VCORE output switching point for FS6500 series			
	or VCORE	A_OUT	VCORE output voltage for FS4500 series			
36	BOOT_COR E	A_IN/OUT	Bootstrap capacitor for VCORE internal NMOS gate drive. For FS4500 series, this pin must be left open (NC).			
37	VPRE	A_IN	VPRE input voltage sense			
38	VAUX	A_OUT	VAUX output voltage. External PNP ballast transistor. Collector connection			
39	VAUX_B	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Base connection			
40	VAUX_E	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Emitter connection			
41	VCCA_E	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Emitter connection			
42	VCCA_B	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Base connection			
43	VCCA	A_OUT	VCCA output voltage. External PNP ballast transistor. Collector connection			
44	GATE_LS	A_OUT	Low-side MOSFET gate drive for non-inverting buck-boost configuration			
45	DGND	GROUND	Digital ground connection			
46	BOOT_PRE	A_IN/OUT	Bootstrap capacitor for the VPRE internal NMOS gate drive			
47	SW_PRE2	A_OUT	Second pre-regulator output switching point			
48	SW_PRE1	A_OUT	First pre-regulator output switching point			

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8 Maximum ratings

Table 4. Maximum ratings

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Symbol	Ratings	Value	Unit	Notes
Electrical ratin	lgs			
V _{SUP1/2/3}	DC voltage at power supply pins	-1.0 to 40	V	[1]
V _{SENSE}	DC voltage at battery sense pin (with ext R in series mandatory)	-14 to 40	V	
V _{SW1,2}	DC voltage at SW_PRE1 and SW_PRE2 pins	-1.0 to 40	V	
V _{PRE}	DC voltage at VPRE pin	–0.3 to 8	V	
V _{GATE_LS}	DC voltage at Gate_LS pin	–0.3 to 8	V	
V _{BOOT_PRE}	DC voltage at BOOT_PRE pin	-1.0 to 50	V	
V _{SW_CORE}	DC voltage at SW_CORE pin	-1.0 to 8	V	
V _{CORE_SNS}	DC voltage at VCORE_SNS pin	0.0 to 8	V	
V _{BOOT_CORE}	DC voltage at BOOT_CORE pin	0.0 to 15	V	
V _{FB_CORE}	DC voltage at FB_CORE pin	-0.3 to 2.5	V	
V _{COMP_CORE}	DC voltage at COMP_CORE pin	-0.3 to 2.5	V	
V _{FCRBM}	DC voltage at FCRBM pin	–0.3 to 8	V	
V _{AUX_B,E}	DC voltage at VAUX_B, VAUX_E pins	-0.3 to 40	V	
V _{AUX}	DC voltage at VAUX pin	-2.0 to 40	V	
V _{CCA_B,E}	DC voltage at VCCA_B, VCCA_E pins	–0.3 to 8	V	
V _{CCA}	DC voltage at VCCA pin	–0.3 to 8	V	
V _{DDIO}	DC voltage at VDDIO pin	–0.3 to 8	V	
V _{CAN_5V}	DC voltage on CAN_5V pin	–0.3 to 8	V	
V _{PU_FS}	DC voltage at VPU_FS pin	–0.3 to 8	V	
V _{FSxB}	DC voltage at FS0B, FS1B pins (with ext R in series mandatory)	–0.3 to 40	V	
V _{DEBUG}	DC voltage at DEBUG pin	–0.3 to 40	V	
V _{IO_0,4}	DC voltage at IO_0, IO_4 pins (with ext R in series mandatory)	–0.3 to 40	V	
V _{IO_5}	DC voltage at IO_5 pin	-0.3 to 20	V	
V _{KAM}	DC voltage at VKAM pin	–0.3 to 8	V	
V _{DIG}	DC voltage at INTB, RSTB, MISO, MOSI, NCS, SCLK, MUX_OUT, RXD, TXD, IO_2, IO_3 pins	–0.3 to 8	V	
V _{SELECT}	DC voltage at SELECT pin	–0.3 to 8	V	
V _{BUS_CAN}	DC voltage on CANL, CANH pins	-27 to 40	V	
V _{BUS_LIN}	DC voltage on LIN pin	–18 to 40	V	
I_I _{SENSE}	V _{SENSE} maximum current capability	-5.0 to 5.0	mA	
I_IO _{0, 4, 5}	IOs maximum current capability (IO_0, IO_4, IO_5)	-5.0 to 5.0	mA	

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Symbol	Ratings	Value	Unit	Notes
ESD voltage				
Vesd-hbm1 Vesd-hbm2 Vesd-hbm3 Vesd-hbm4	Human body model (JESD22/A114) – 100 pF, 1.5 kΩ • All pins • VSUP1,2,3, VSENSE, VAUX, IO_0,4, FS0B, FS1B, DEBUG • CANH, CANL • LIN	±2.0 ±4.0 ±6.0 ±8.0	kV KV KV	[2]
VESD-CDM1 VESD-CDM2	Charge device model (JESD22/C101): All pins Corner pins System level ESD (gun test) VSUP1, 2, 3, VSENSE, VAUX, IO_0, 4, 5, FS0B, FS1B 	±500 ±750		_
V _{ESD-GUN1}	330 Ω /150 pF unpowered according to IEC61000-4-2	±8.0	kV	
V _{ESD-GUN2}	330 $\Omega/150~\text{pF}$ unpowered according to OEM LIN, CAN, FLexray Conformance	±8.0	kV	
V _{ESD-GUN3}	2.0 kΩ/150 pF unpowered according to ISO10605.2008	±8.0	kV	
V _{ESD-GUN4}	2.0 kΩ/330 pF powered according to ISO10605.2008CANH, CANL	±8.0	kV	
V _{ESD-GUN5}	330 Ω /150 pF unpowered according to IEC61000-4-2	±15.0	kV	
V _{ESD-GUN6}	$330\ \Omega/150\ \text{pF}$ unpowered according to OEM LIN, CAN, FLexray conformance	±12.0	kV	
V _{ESD-GUN7}	2.0 kΩ/150 pF unpowered according to ISO10605.2008	±15.0	kV	
V _{ESD-GUN8}	2.0 kΩ/330 pF powered according to ISO10605.2008 • LIN	±12.0	kV	
V _{ESD-GUN9}	330 Ω/150 pF unpowered according to IEC61000-4-2:	±12.0	kV	
V _{ESD-GUN10}	330 Ω /150 pF unpowered according to OEM LIN, CAN, flexray conformance	±12.0	kV	
V _{ESD-GUN11}	2.0 k Ω /150 pF unpowered according to ISO10605.2008	±12.0	kV	
V _{ESD-GUN12}	2.0 kΩ/330 pF powered according to ISO10605.2008	±12.0	kV	
Thermal rating	gs			
T _A	Ambient temperature	-40 to 125	°C	
TJ	Junction temperature	-40 to 150	°C	
T _{STG}	Storage temperature	–55 to 150	°C	
Thermal resis	tance			
R _{θJA}	Thermal resistance junction to ambient	30	°C/W	[3]
R _{ØJCTOP}	Thermal resistance junction to case top	23.8	°C/W	[4]
R _{0JCBOTTOM}	Thermal resistance junction to case bottom	0.9	°C/W	[5]

All VSUPs (V_{SUP1/2/3}) must be connected to the same supply Compared to AGND Per JEDEC JESD51-6 with the board (JESD51-7) horizontal [1] [2] [3]

Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC - 883 Method 1012.1). Thermal resistance between the die and the solder pad on the bottom of the packaged based on simulation without any interface resistance.

[4] [5]

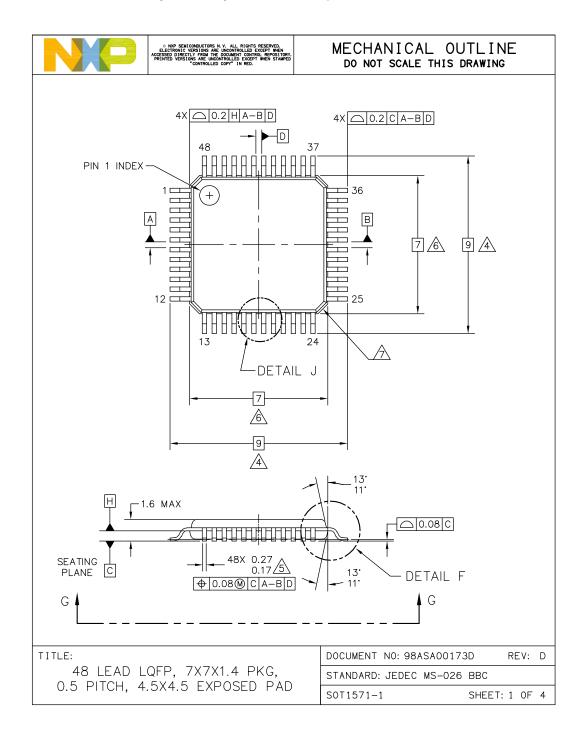
9 Packaging

9.1 Package mechanical dimensions

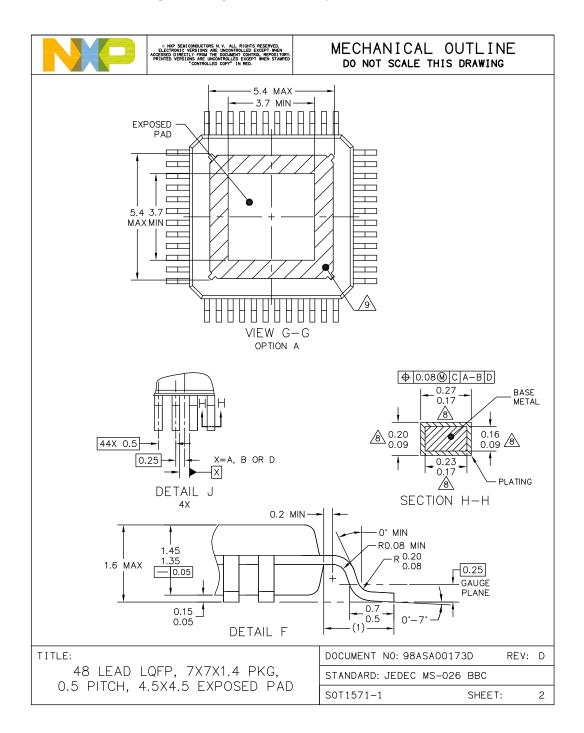
Package dimensions are provided in package drawings. To find the most current package outline drawing, go to www.nxp.com and perform a keyword search for the drawing's document number.

 Table 5. Package mechanical dimensions

Package	Suffix	Package outline drawing number
7.0 × 7.0, 48–Pin LQFP exposed pad, with 0.5 mm pitch, and a 4.5 × 4.5 exposed pad	AE	98ASA00173D



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NOTES:									
1. DIMENSIONS ARE IN MILLIMETERS.									
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.									
3. DATUMS A, B AND D TO BE DETERMINED AT	DATUM PLANE H.								
A DIMENSION TO BE DETERMINED AT SEATING PL	_ANE C.								
PROTRUSION SHALL NOT CAUSE THE LEAD WI BY MORE THAN 0.08MM AT MAXIMUM MATERI LOCATED ON THE LOWER RADIUS OR THE FOO	THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08MM AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07MM.								
THIS DIMENSION DOES NOT INCLUDE MOLD PR IS 0.25MM PER SIDE. THIS DIMENSION IS MAX INCLUDING MOLD MISMATCH.									
\triangle exact shape of each corner is optional									
THESE DIMENSIONS APPLY TO THE FLAT SECT AND 0.25MM FROM THE LEAD TIP.	ION OF THE LEAD BETWEEN	D.1MM							
A HATCHED AREA TO BE KEEP OUT ZONE FOR	PCB ROUTING.								
TITLE:	DOCUMENT NO: 98ASAOO	173D REV:							
48 LEAD LQFP, 7X7X1.4 PKG,	STANDARD: JEDEC MS-0								
0.5 PITCH, 4.5X4.5 EXPOSED PAD	S0T1571-1	SHEET:	3						

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10 References

The following are URLs where you can obtain information on related NXP products and application solutions.

NXP.com support pages	Description	URL		
AN5238	Hardware design and product guidelines	http://www.nxp.com/AN5238-DOWNLOAD		
AN4388	Quad flat package (QFP)	http://www.nxp.com/files/analog/doc/app_note/AN4388.pdf		
Power dissipation tool (Excel	file)	http://www.nxp.com/files/analog/software_tools/FS6500-FS4500-power- dissipation-calculator.xlsx		
V _{CORE} compensation network	simulation tool (CNC)	Upon demand		
FMEDA	FS6500/FS4500 FMEDA	Upon demand		
FS6500-FS4500SMUG	FS6500/FS4500 Safety Manual – user guide	https://www.nxp.com/webapp/Download?colCode=FS6500-FS4500SMUC		
FS6500-FS4500	Power System Basis Chip with CAN Flexible Data and LIN Transceivers data sheet	https://www.nxp.com/webapp/Download?colCode=FS6500-FS4500		
KITFS6522LAEEVM	FS6500 evaluation board with LIN (no FS1B)	http://www.nxp.com/KITFS6522LAEEVM		
KITFS4503CAEEVM	FS4500 evaluation board with FS1B (no LIN)	http://www.nxp.com/KITFS4503CAEEVM		
KITFS6523CAEEVM	FS6500 evaluation board with FS1B (no LIN)	http://www.nxp.com/KITFS6523CAEEVM		
FS6500 product summary page	ge	http://www.nxp.com/FS6500		
FS4500 product summary page	ge	http://www.nxp.com/FS4500		
Analog power management h	ome page	http://www.nxp.com/products/power-management		

11 Revision history

Table 6. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
FS6500-FS4500SDS v.1.0	20171214	Data sheet: advance information		—

12 Legal information

12.1 Data sheet status

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