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SPECIFICATIONS:					
NUMBER OF PHASES: 4		ROTOR INERTIA: 460 g-cm ² (2.515 oz-in ²) NOM			
STEPS PER REVOLUTION: 200		DETENT TORQUE: 713.8 g-cm (9.91 oz-in) MIN			
STEP ANGLE: 1.8°		INSULATION CLASS: B			
STEP TO STEP ACCURACY: 0.09°		1	,	2	BEARINGS: ABEC 3, DOUBLE SHIELDED
POSITION ACCURACY: 0.09°		1	,	3	
HYSTERESIS: N/A%		TEMP. RISE: 80°C MAX. 9			
SHAFT RUNOUT: 0.03 mm T.I.R. MAX		OPERATING TEMP. RANGE: -20 TO +50°C			
RADIAL PLAY: 0.02 mm MAX (0.5 kg RADIAL LOAD)		STORAGE TEMP. RANGE: -30 TO +70°C			
END PLAY: 0.08 mm MAX (0.5 kg AXIAL LOAD)		RELATIVE HUMIDITY RANGE 15 TO 85%			
		WEIGHT: 1000 G (35.2 oz) APPROXIMATE			
CONNECTION	RESISTANCE PER PHASE (ohm ±10%) 7	INDUCTANCE PER PHASE (mH ±20%) 8	RATED CURRENT (Amp)	HOLDING TORQUE (Nm MIN) 1	HOLDING TORQUE (oz-in) 1
BI-POLAR SERIES	2.0	6.8	2.12	1.90	269
BI-POLAR PARALLEL	0.5	1.75	4.24	1.90	269
UNI-POLAR	1.0	1.75	3.00	1.35	191

NOTES, UNLESS OTHER WISE SPECIFIED:

1 MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.

2 BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.

3 MAXIMUM ERROR IN 360°.

4. HIPOT 500 VAC, 60Hz FOR ONE MINUTE.

5 LEADS: 8, 22 AWG, 7 STRAND MIN. UL AND CSA APPROVED. UL 1430 OR UL 3265

6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.

7 AS MEASURED ACROSS EACH PHASE.

8 AS MEASURED ACROSS EACH PHASE USING AN A.C. INDUCTANCE BRIDGE AT 1KHz.

9 AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED CURRENT APPLIED TO 2 PHASES: WITH MOTOR AT REST.

10 ENCODER 970-1028 INSTALLED PER AMP ASSEMBLY PRACTICES. ENCODER CABLE SOLD SEPARATELY.

11. ROTOR AND STATOR LAMINATED CONSTRUCTION.

12. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH CURRENT EU RoHS DIRECTIVE.

13 MOTOR LABEL TO INCLUDE AMP LOGO, AMP WEBSITE ADDRESS, "RoHS" COMPLIANCE LOGO, AMP P/N, "MADE IN (COUNTRY)", AND DATE CODE.

14. OTHER TAPPED HOLES MAY BE PRESENT ON REAR OF MOTOR.

REVISIONS				
ECO #	REV.	DESCRIPTION	DATE	APPROVED
7747	A	INITIAL RELEASE	12/20/17	J. KORDIK
8705	B	END BELL THK FROM 5+/- 0.5 TO 4.8+/-0.3	8/23/21	L. LIU
8787	C	REVISED MODEL & UPDATED SHEET FORMAT	5/20/22	L. LIU

WIRING DIAGRAM

DRIVE SEQUENCE MODEL
BI-POLAR PARALLEL FULL STEP

STEP	(A+) ORG & BKL/WHT	(A-) BLK & ORG/WHT	(B+) RED & YEL/WHT	(B-) YEL & RED/WHT
1	+	-	+	-
2	-	+	+	-
3	-	+	-	+
4	+	-	-	+
1	+	-	+	-

CW (CLOCKWISE) AND CCW (COUNTER-CLOCKWISE) ROTATION WHEN SEEN FROM THE MOUNTING FACE END OF THE MOTOR

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	THIRD ANGLE PROJECTION		NAME	DATE	TITLE: STEPPER MOTOR				
	UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN MILLIMETERS TOLERANCES: - ANGULAR: ± 0.5 - ONE DECIMAL PLACE: ± 0.25 - TWO DECIMAL PLACES: ± 0.13	DRAWN	Y. LAPNET	5/20/22					
		PRE.CHECK							
		PRE.APPROVAL							
		MATERIAL	FINISH	DO NOT SCALE DRAWING	FIN.CHECK		C. BREUNINGER	5/20/22	SIZE B
SAP: 4611110060898									
ALT DWG. NO.:									
ALT SAP:			SCALE: 1:1		SHEET 1 OF 2				

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