SPECIFICATIONS:				
STEPS PER REVOLUTION: 200	ROTOR INERTIA: 57.0 G-CM ² (.31 OZ-IN ²) REF			
STEP ANGLE: 1.8°	DETENT TORQUE: 152.9 G-CM (2.120Z-IN) MIN			
STEP TO STEP ACCURACY:±.09 DEGREES 1,2	INSULATION CLASS: B			
POSITIONAL ACCURACY: ±.09 DEGREES 1,3	BEARINGS: ABEC 3, DOUBLE SHIELDED			
HYSTERESIS: - %	WEIGHT: 280 G (9.8 OZ) APPROXIMATE			
SHAFT RUNOUT: 0.03 T.I.R.	TEMP. RISE: 80 °C MAX.			
RADIAL PLAY: 0.02 MAX W/A .5KG RADIAL LOAD	OPERATING TEMP. RANGE: -20 TO +50 °C			
END PLAY: 0.08 MAX W/A .5KG AXIAL LOAD	STORAGE TEMP. RANGE: -30 TO +70 °C			
	RELATIVE HUMIDITY RANGE: 15 TO 85 %			

REVISIONS								
ECO NO.	REV	DESCRIPTION	DATE	APPROVED				
5976	А	INITIAL RELEASE	8/28/09	J KORDIK				
6090	В	STANDARDIZE ENCODER HOLES	3/29/10	J KORDIK				
7247	С	ADD UL TO LABEL	1/26/16	J KORDIK				
7446	D	REVISE NOTE 10	6/6/16	J KORDIK				
8209	E	DOCUMENT CLEANUP	4/29/19	J KORDIK				
8277	F	REMOVE ENCODER HOLES	7/3/19	J.KORDIK				

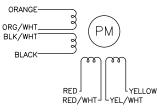
HT17-27

			7				_
SPECIFICATION	NUMBER	RESISTANCE	INDUCTANCE	RATED	RATED	HOLDING	
	OF	PER PHASE	PER PHASE	CURRENT	VOLTAGE	TORQUE	
CONNECTION	PHASE	OHM ±10%	mH ±20%	Amp	V	N.m Min	1
BI-POLAR SERIES	2	7.0	12.0	0.85	6.0	0.37	
BI-POLAR PARALLEL	2	1.7	3.0	1.70	2.9	0.37	
UNI-POLAR	4	3.5	3.0	1.20	4.2	0.29	

NOTES, UNLESS OTHERWISE SPECIFIED:

- 1 MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.
- 2 BETWEEN ANY TWO ADJACENT STEP POSITIONS.
- 3 MAXIMUM ERROR IN 360°.
- 4. HIPOT 500 VAC, 60 Hz FOR ONE MINUTE.
- 5. LEADS: 8, 26 AWG, 7 STRAND MIN., UL AND CSA APPROVED, UL 1430 OR UL 3265.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED USING AN A.C. INDUCTANCE BRIDGE, AT 1KHz.
- 8 AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED VOLTAGE APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- SHAFT OPTION: IF DOUBLE SHAFT REQUIRED ADD "D" TO END OF PART NUMBER, DOUBLE SHAFT REQUIRES ADDED HOLES FOR ENCODER OPTIONS.
- 10. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU ROHS DIRECTIVE.
- MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.

	WIRING	DIAGRAM
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LABEL DETAIL	
HT17-271 XX-XX SERIES - 0.85A/7.0 OHM PARALLEL - 1.70A/1.7 OHM HOLDING TORQUE - 0.37 N.m ROHS MADE IN X	

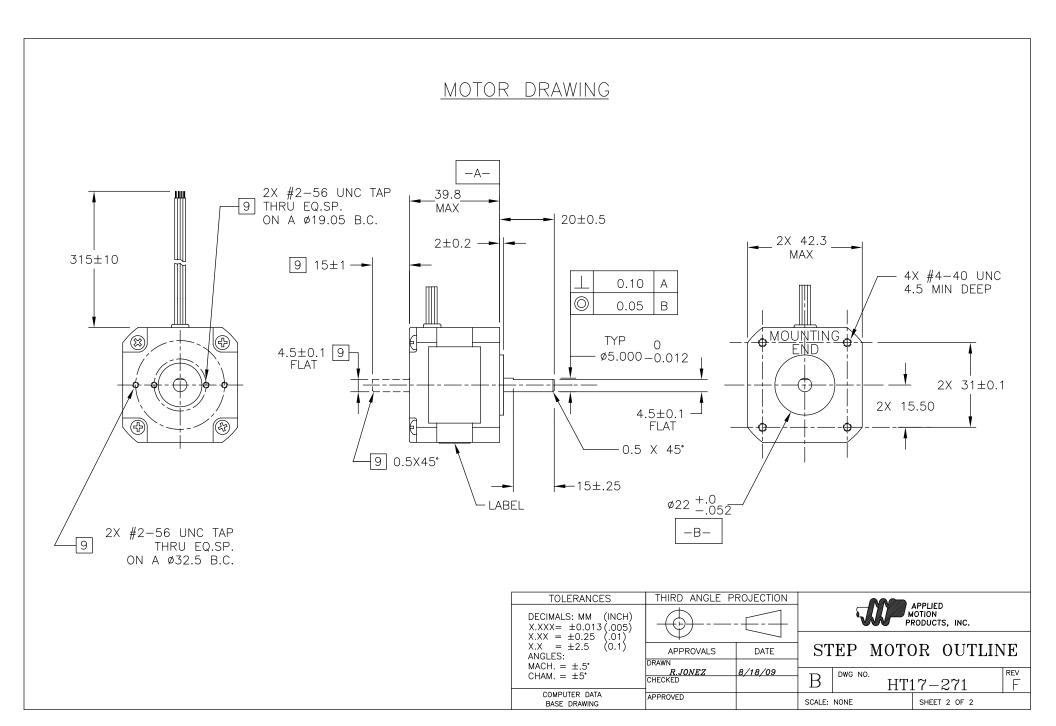
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CONTRACT NO.					APPLIED MOTION PRODUCTS,	INC.	
APPROVALS	DATE						
DRAWN R.JONEZ	8/19/09	S	TEF	' MO	TOR	OUTLINE	l I
CHECKED			i				
		D	COMPU	TER DATA	DWG NO.		REV
APPROVED		В	BASE	DRAWING]	HT17-271	F
APPROVED		SCALE:	NONE			SHEET 1 OF 2	

DRIVE SEQUENCE MODEL BI-POLAR FULL STEP

I	STEP	ORANGE & BLK/WHT	BLACK & ORG/WHT	RED & YEL/WHT	YELLOW & RED/WHT	CCW
	1	+		+	—	l 🕴
	2	—	+	+	—	
•	3	—	+	—	+	
:w	4	+		_	+	

CW(CLOCKWISE) AND CCW(COUNTER-CLOCKWISE) ROTATION WHEN SEEN FROM THE FLANGE SIDE OF THE MOTOR



Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Applied Motion: <u>HT17-271</u>