SPECIFICATIONS:								
NUMBER OF PHASES: 2	ROTOR INERTIA: 20 g-cm ² (0.11 oz-in ²) NOM							
STEPS PER REVOLUTION: 400	DETENT TORQUE: 5 mNm (0.71 oz-in) MIN							
STEP ANGLE: 0.9°	BEARINGS: 625ZZ							
STEP TO STEP ACCURACY: ±0.045 1,2	INSULATION CLASS: B							
POSITIONAL ACCURACY: ±5% 1,3	HYSTERESIS: N/A%							
SHAFT RUNOUT: 0.03 mm T.I.R. MAX	TEMP. RISE: 80 °C MAX.							
RADIAL PLAY: 0.02 mm MAX (.5KG RADIAL LOAD)	OPERATING TEMP. RANGE: -20 TO +50 °C							
END PLAY: 0.08 mm MAX (.5KG AXIAL LOAD)	STORAGE TEMP. RANGE: -30 TO+70 °C							
MAXIMUM RADIAL LOAD: 21N (4.72lb)	RELATIVE HUMIDITY RANGE: 15 TO 85 %							
MAXIMUM AXIAL LOAD: 10 N (2.25 lb)	WEIGHT: 0.12 kg (0.26 lb)							
7 8								

INDUCTANCE

PER PHASE

 $(mH \pm 20\%)$

9.5

RATED

CURRENT

(amp)

0.65

HOLDING

TORQUE

(Nm MIN)

0.09

HOLDING

TORQUE

(oz-in Min)

12.75

ECO NO. REV DESCRIPTION DATE APPROVED 6888 A PRELIMINARY RELEASE 12/17/13 J.KORDIK 6947 B REVISED/REDRAWN D.MACLEOD 7048 LC ERROR CORRECTION 8/11/14 D.MACLEOD **REVISE NOTE 12** 7446 D 6-6-16 J KORDIK _

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REVISIONS

NOTES, UNLESS OTHERWISE SPECIFIED:

1 MEASURMENTS MADE AT RATED CURRENT IN EACH PHASE.

RESISTANCE

PER PHASE

 $(ohm \pm 10\%)$

6.6

- BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.
- 3 MAXIMUM ERROR IN 360°.

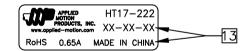
SPECIFICATION

CONNECTION

BI-POLAR SERIES

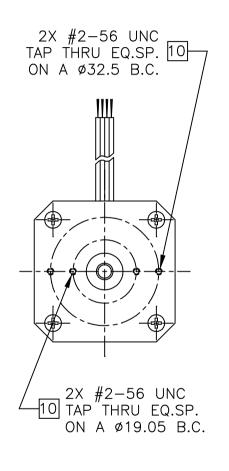
- 4. HIPOT 500 VAC. 60 Hz FOR ONE MINUTE.
- 5. LEADS: 4, AWG 26, 7 STRAND MIN., UL AND CSA APPROVED, UL 1061
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED ACROSS EACH PHASE.
- 8 AS MEASURED ACROSS EACH PHASE USING AN A.C. INDUCTANCE BRIDGE AT 1 KHz.
- AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED CURRENT APPLIED TO 2 PHASES: WITH MOTOR AT REST.
- MED "D" TO END OF PART NUMBER IF DOUBLE SHAFT IS REQUIRED. ENCODER HOLES INCLUDED WITH REAR SHAFT VERSION ONLY.
- 11. ROTOR & STATOR LAMINATED CONSTRUCTION.
- 12. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU RoHS DIRECTIVE.
- 3 MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, AMP P/N, 'MADE IN (COUNTRY OF ORIGIN)', AND DATE CODE.
- 14. HIGH TORQUE MOTOR DESIGN

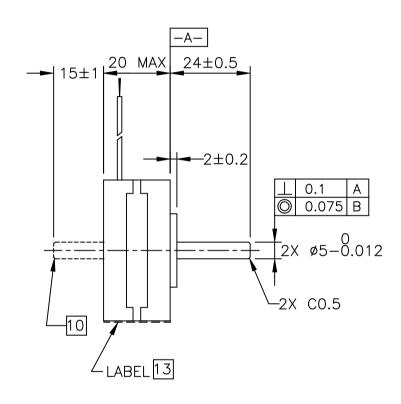
LABEL DETAIL

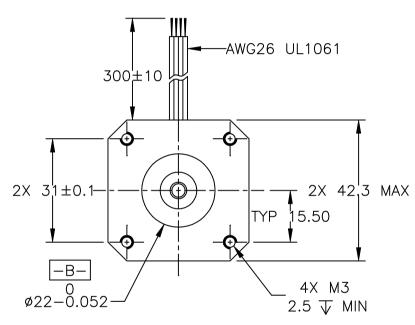


							PHASE DETAIL			
								BLACK A+ 2		
					NG SEQUE MOUNTING		_	g (PM)		
		STEP	A+	A-	B+	B-	CCW	GREEN A- 3		
		0	+	_	+	_] ↓	روووی		
		1		+	+					
	Ţ	2	1	+	_	+		B+ B-		
	1	3	+	_	_	+		RED BLUE		
	CW	4	+	_	+	_				

CONTRACT NO.	APPLIED MOTION PRODUCTS, INC.						
APPROVALS	DATE						_
DRAWN K.KESLER 8/11/14		STEP MOTOR			OUTLINE		
CHECKED	ECKED						
	-	COMPU		JTER DATA	DWG NO.		REV
APPROVED	_		BASE	DRAWING		HT17-222	D
APPROVED	_	SCALE:	NONE			SHEET 1 OF 2	







TOLERANCES	THIRD ANGLE P	ROJECTION			ADDUED	
*ALL DIMENSIONS IN MM DECIMALS: MM	APPROVALS DATE		APPLIED MOTION PRODUCTS, INC.			
X.XX = ±0.13 X.X = ±0.25 ANGLES:			STEP MOTOR OUTLINE			
MACH. = ±0.5° CHAM. = ±5°	DRAWN K.KESLER CHECKED	8/11/14	В	DWG NO.	17-222	REV D
COMPUTER DATA BASE DRAWING	APPROVED	_	SCALE: NONE		SHEET 2 OF 2	

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Applied Motion:

HT17-222 HT17-222D