| SPECIFICATIONS:                              |  |  |  |  |  |
|--|--|--|--|--|--|
| NUMBER OF PHASES: 2                          | ROTOR INERTIA: 260 g-cm <sup>2</sup> ( 1.42 oz-in <sup>2</sup> ) NOM |  |  |  |  |
| STEPS PER REVOLUTION: 200                    | INSULATION CLASS: B  |  |  |  |  |
| STEP ANGLE: 1.8°                             | TEMP. RISE: 80 °C MAX.   |  |  |  |  |
| STEP TO STEP ACCURACY: ±0.09 1, 2            | OPERATING TEMP. RANGE: -20 TO +50 °C 9                               |  |  |  |  |
| POSITIONAL ACCURACY: ±5% 1,3                 | STORAGE TEMP. RANGE: -30 TO+70 °C                                    |  |  |  |  |
| AXIAL MOVEMENT: 0.1mm MAX (100N AXIAL FORCE) | RELATIVE HUMIDITY RANGE: 15 TO 85 %                                  |  |  |  |  |
| BEARING SIZE: 28*15*7 mm                     | WEIGHT: 0.6 kg (1.32 lb)   |  |  |  |  |
| SHAFT MATERIAL: SUS303                       |  |  |  |  |  |

|                 | 7          | 8                       |                  | 1                 | 1                 |
|-----------------|------------|-------------------------|------------------|-------------------|-------------------|
| SPECIFICATION   | PER PHASE  | INDUCTANCE<br>PER PHASE | RATED<br>CURRENT | HOLDING<br>TORQUE | HOLDING<br>TORQUE |
| CONNECTION      | (ohm ±10%) | (mH ±20%)               | (amp)            | (Nm MIN)          | (oz—in Min)       |
| BI-POLAR SERIES | 1.6        | 6.9                     | 2.2              | 1.5               | 212.4             |

|         | REVISIONS |                     |          |           |  |  |
|---------|-----------|---------------------|----------|-----------|--|--|
| ECO NO. | REV       | DATE                | APPROVED |           |  |  |
| 7068    | Α         | PRELIMINARY RELEASE | 10/24/14 | D.MACLEOD |  |  |
| 7445    | В         | REVISE NOTE 11      | 6/6/16   | J.KORDIK  |  |  |
| 8359    | $\circ$   | 1ST ANGLE TO 3RD    | 10/31/19 | J.KORDIK  |  |  |
| 1       | ı         | _                   | _        | ı         |  |  |
| 1       | 1         | _                   | _        | -         |  |  |
|         |           | _                   | _        | _         |  |  |
| -       | ı         | _                   | _        | ı         |  |  |
| 1       | 1         | _                   | _        | -         |  |  |
|         |           | _                   | _        | _         |  |  |
|         |           | _                   | _        | -         |  |  |
|         |           | _                   |          | _         |  |  |

## NOTES, UNLESS OTHERWISE SPECIFIED:

- 1 MEASURMENTS MADE AT RATED CURRENT IN EACH PHASE.
- 2 BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.
- 3 MAXIMUM ERROR IN 360°.
- 4 HIPOT 500 VAC, 60 Hz FOR ONE MINUTE.
- 5 CONNECTOR: JSTS6B-XH-A-1(LF)(SN)
- 6 INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED ACROSS EACH PHASE.
- 8 AS MEASURED ACROSS EACH PHASE USING AN A.C. INDUCTANCE BRIDGE AT 1 KHz.
- 9 AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED

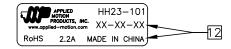
CURRENT APPLIED TO 2 PHASES; WITH MOTOR AT REST.

- 10 ROTOR & STATOR LAMINATED CONSTRUCTION.
- 11 THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU RoHS DIRECTIVE.
- 12 MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, AMP P/N, 'MADE IN (COUNTRY OF ORIGIN)', AND DATE CODE.
- 13 HIGH TORQUE MOTOR DESIGN.

## LABEL DETAIL

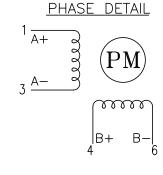
0

HH2.

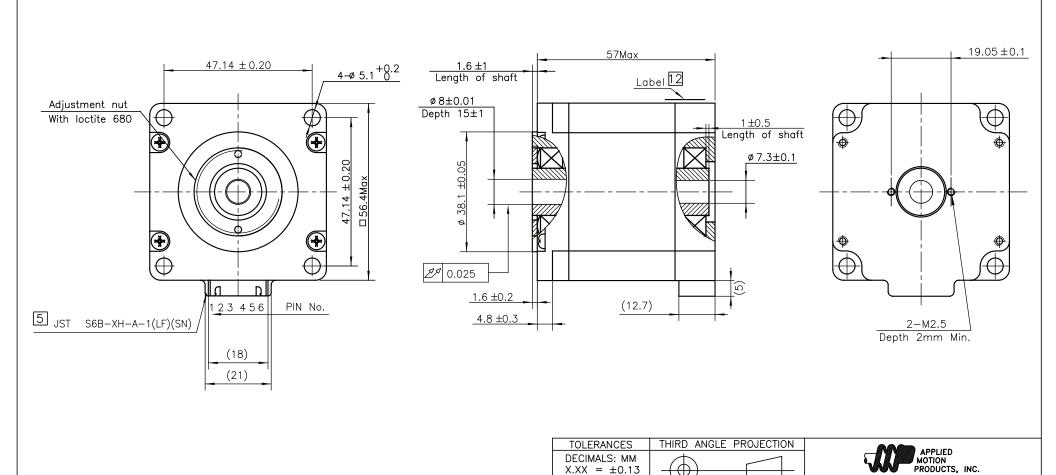


## FULL STEP SWITCHING SEQUENCE BI-POLAR. FACING MOUNTING END

|    |      |    | . , , , , , , , , , , , , , , , , , , , |    |    |     |
|----|------|----|---|----|----|-----|
|    | STEP | A+ | A-                                      | B+ | B- | CCW |
|    | 0    | +  | _                                       | +  | _  | ↓   |
|    | 1    | _  | +                                       | +  | _  |     |
|    | 2    | _  | +                                       | _  | +  |     |
| ١  | 3    | +  | _                                       | _  | +  |     |
| СW | 4    | +  | _                                       | +  | _  |     |



| CONTRACT NO.                    | APPLIED MOTION PRODUCTS, INC. |             |     |                      |             |              |          |
|---------------------------------|-------------------------------|-------------|-----|----------------------|-------------|--------------|----------|
| APPROVALS                       | DATE                          |             |     |                      |             |              |          |
| DRAWN K.KESLER CHECKED          | 10/31/19                      |             | TEF | P MO                 | TOR OUTLINE |              |          |
| R.JONEZ<br>APPROVED<br>J.KORDIK | 10/31/19<br>10/31/19          | В           |     | JTER DATA<br>DRAWING | DWG NO.     | HH23-101     | REV<br>C |
| APPROVED                        |                               | SCALE: NONE |     |                      |             | SHEET 1 OF 2 |          |



\*ALL DIMENSIONS IN MM

DECIMALS: MM  $X.XX = \pm 0.13$   $X.X = \pm 0.25$   $X = \pm 0.5$ 

COMPUTER DATA

BASE DRAWING

ANGLES: MACH. =  $\pm 0.5^{\circ}$ CHAM. =  $\pm 5^{\circ}$  **APPROVALS** 

K.KESLER

CHECKED R.JONEZ

APPROVED

DATE

10/31/19

10/31/19

В

SCALE: NONE

DWG NO.

STEP MOTOR OUTLINE

HH23-101

SHEET 2 OF 2

REV

С

## **Mouser Electronics**

**Authorized Distributor** 

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Applied Motion: HH23-101