nRF9160

Objective Product Specification

v0.7.1



nRF9160 features

Features:

Microcontroller:

- ARM Cortex -M33
 - 243 EEMBC CoreMark score running from flash memory
 - Data watchpoint and trace (DWT), embedded trace macrocell (ETM), and instrumentation trace macrocell (ITM)
 - Serial wire debug (SWD)
 - Trace port
- 1 MB flash
- 256 kB low leakage RAM
- ARM[®] Trustzone[®]
- ARM Cryptocell 310
- 4x SPI master/slave with EasyDMA
- 4x I2C compatible two-wire master/slave with EasyDMA
- 4x UART (CTS/RTS) with EasyDMA
- I2S with EasyDMA
- Digital microphone interface (PDM) with EasyDMA
- 4x pulse width modulator (PWM) unit with EasyDMA
- 12-bit, 200 ksps ADC with EasyDMA eight configurable channels with programmable gain
- 2x 32-bit timer with counter mode
- 2x real-time counter (RTC)
- Programmable peripheral interconnect (PPI)
- 32 general purpose I/O pins
- Single supply voltage: 3.0 5.5 V

Note: 3.3 - 5.5 V for RF 3GPP compliancy

- All necessary clock sources integrated
- Package: 10 × 16 x 1.2 mm LGA

LTE modem:

- Transceiver and baseband
- 3GPP LTE release 13 Cat-M1 and Cat-NB1 compliant
- 3GPP LTE release 14 Cat-NB1 and Cat-NB2 compliant
- RF transceiver for global coverage
 - Transceiver HW capability 700-2200 MHz
 - Up to 23 dBm output power
 - -108 dBm sensitivity (LTE-M)
 - Single 50 Ω antenna interface
- LTE band support (certified):
 - Cat-M1
 - USA and Canada: B4, B13
 - Europe: B3, B20
 - Cat-NB1
 - Europe: B3, B20
- ETSI TS 102 221 compatible UICC interface
- DRX, eDRX, PSM
- 3GPP release 13 coverage enhancement
- IP v4/v6 stack
- Secure socket API

Applications:

- Sensor networks
- Logistics and asset tracking
- Smart energy
- Smart building automation
- Smart agriculture

- Industrial
- Retail and monitor devices
- Medical devices
- Wearables



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1 Revision history

Date	Version	Description	
December 2018	0.7.1	The following content has been added or updated:	
		Corrected wrong frequency range in Introduction on page 13.	
December 2018	0.7	Preliminary release	



2 About this document

This document is organized into chapters that are based on the modules and peripherals available in the IC

2.1 Document status

The document status reflects the level of maturity of the document.

Document name	Description	
Objective Product Specification (OPS)	Applies to document versions up to 1.0. This document contains target specifications for product development.	
Product Specification (PS)	Applies to document versions 1.0 and higher. This document contains final product specifications. Nordic Semiconductor ASA reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.	

Table 1: Defined document names

2.2 Peripheral chapters

Every peripheral has a unique capitalized name or an abbreviation of its name, e.g. TIMER, used for identification and reference. This name is used in chapter headings and references, and it will appear in the ARM[®] Cortex[®] Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer to identify the peripheral.

The peripheral instance name, which is different from the peripheral name, is constructed using the peripheral name followed by a numbered postfix, starting with 0, for example, TIMERO. A postfix is normally only used if a peripheral can be instantiated more than once. The peripheral instance name is also used in the CMSIS to identify the peripheral instance.

The chapters describing peripherals may include the following information:

- A detailed functional description of the peripheral
- · Register configuration for the peripheral
- Electrical specification tables, containing performance data which apply for the operating conditions described in Peripheral chapters on page 10.

2.3 Register tables

Individual registers are described using register tables. These tables are built up of two sections. The first three colored rows describe the position and size of the different fields in the register. The following rows describe the fields in more detail.



2.3.1 Fields and values

The **Id** (Field Id) row specifies the bits that belong to the different fields in the register. If a field has enumerated values, then every value will be identified with a unique value id in the **Value Id** column.

A blank space means that the field is reserved and read as undefined, and it also must be written as 0 to secure forward compatibility. If a register is divided into more than one field, a unique field name is specified for each field in the **Field** column. The **Value Id** may be omitted in the single-bit bit fields when values can be substituted with a Boolean type enumerator range, e.g. true/false, disable(d)/enable(d), on/off, and so on.

Values are usually provided as decimal or hexadecimal. Hexadecimal values have a 0x prefix, decimal values have no prefix.

The Value column can be populated in the following ways:

- Individual enumerated values, for example 1, 3, 9.
- Range of values, e.g. [0..4], indicating all values from and including 0 and 4.
- Implicit values. If no values are indicated in the **Value** column, all bit combinations are supported, or alternatively the field's translation and limitations are described in the text instead.

If two or more fields are closely related, the **Value Id**, **Value**, and **Description** may be omitted for all but the first field. Subsequent fields will indicate inheritance with '..'.

A feature marked **Deprecated** should not be used for new designs.

2.3.2 Permissions

Different fields in a register might have different access permissions enforced by hardware.

The access permission for each register field is documented in the Access column in the following ways:

Access	Description	Hardware behavior	
RO	Read-only	Field can only be read. A write will be ignored.	
wo	Write-only	Field can only be written. A read will return an undefined value.	
RW	Read-write	Field can be read and written multiple times.	
W1	Write-once	Field can only be written once per reset. Any subsequent write will be ignored. A read will return an undefined value.	
RW1	Read-write-once	Field can be read multiple times, but only written once per reset. Any subsequent write will be ignored.	

Table 2: Register field permission schemes

2.4 Registers

Register	Offset	Security	Description
DUMMY 0x514			Example of a register controlling a dummy feature

Table 3: Register overview

2.4.1 DUMMY

Address offset: 0x514

Example of a register controlling a dummy feature



Bit r	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID		D D I	D C C C B A A		
Res	et 0x00050002		0 0 0 0 0 0	0 0 0 0 0 0 1 0 1 0 0 0 0 0 0 0 0 0 0 0	
Α	RW FIELD_A			Example of a read-write field with several enumerated	
				values	
		Disabled	0	The example feature is disabled	
		NormalMode	1	The example feature is enabled in normal mode	
		ExtendedMode	2	The example feature is enabled along with extra	
				functionality	
В	RW FIELD_B			Example of a deprecated read-write field Deprecated	
		Disabled	0	The override feature is disabled	
		Enabled	1	The override feature is enabled	
С	RW FIELD_C			Example of a read-write field with a valid range of values	
		ValidRange	[27]	Example of allowed values for this field	
D	RW FIELD_D			Example of a read-write field with no restriction on the	
				values	



3 Product overview

3.1 Introduction

The nRF9160 is a low power cellular IoT (internet of things) solution, integrating an ARM[®] Cortex-M33 processor with advanced security features, a range of peripherals, as well as a complete LTE modem compliant with 3GPP LTE release 13 Cat-M1 and Cat-NB1, and 3GPP LTE release 14 Cat-NB1 and Cat-NB2 standards.

The ARM[®] Cortex-M33 processor is exclusively for user application software, and it offers 1 MB of flash and 256 kB of RAM dedicated to this use. The M33 application processor shares the power, clock and peripheral architecture with Nordic Semiconductor nRF51 and nRF52 Series of PAN/LAN SoCs, ensuring minimal porting efforts.

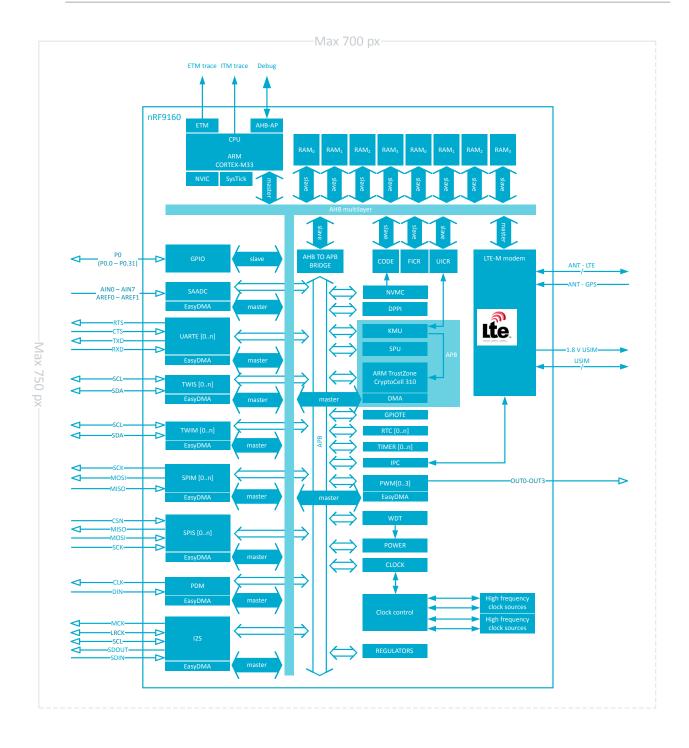
The peripheral set offers a variety of analog and digital functionality enabling single-chip implementation of a wide range of cellular IoT (internet of things) applications. ARM® TrustZone® technology, Cryptocell 310 and supporting blocks for system protection and key management, are embedded to enable advanced security needed for IoT applications.

The LTE modem integrates a very flexible transceiver that in hardware supports frequency range from 700 to 2200 MHz (through a single $50~\Omega$ antenna pin), and a baseband processor handling LTE Cat-M1/NB1/NB2 protocol layers L1-L3 as well as IP upper layers offering secure socket API for the application. The modem is supported by pre-qualified software builds available for free from Nordic Semiconductor.

3.2 Block diagram

This block diagram illustrates the overall system. Arrows with white heads indicate signals that share physical pins with other signals.







3.3 Peripheral interface

Peripherals are controlled by the CPU by writing to configuration registers and task registers. Peripheral events are indicated to the CPU by event registers and interrupts if they are configured for a given event.

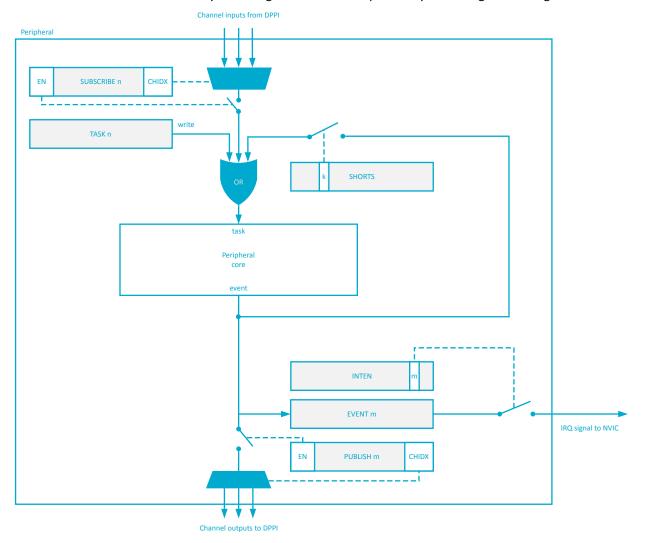


Figure 2: Tasks, events, shortcuts, publish, subscribe and interrupts

Note: For more information on DPPI channels, see DPPI - Distributed programmable peripheral interconnect on page 78.

3.3.1 Peripheral ID

Every peripheral is assigned a fixed block of 0x1000 bytes of address space, which is equal to 1024 x 32 bit registers.

See Instantiation on page 23 for more information about which peripherals are available and where they are located in the address map.

There is a direct relationship between peripheral ID and base address. For example, a peripheral with base address 0x40000000 is assigned ID=0, a peripheral with base address 0x40001000 is assigned ID=1, and a peripheral with base address 0x4001F000 is assigned ID=31.

Peripherals may share the same ID, which may impose one or more of the following limitations:



- Some peripherals share some registers or other common resources.
- Operation is mutually exclusive. Only one of the peripherals can be used at a time.
- Switching from one peripheral to another must follow a specific pattern (disable the first, then enable the second peripheral).

3.3.2 Peripherals with shared ID

In general (with the exception of ID 0), peripherals sharing an ID and base address may not be used simultaneously. The user can only enable one peripheral at the time on this specific ID.

When switching between two peripherals sharing an ID, the user should do the following to prevent unwanted behavior:

- Disable the previously used peripheral.
- Disable any publish/subscribe connection to the DPPI system for the peripheral that is being disabled.
- Clear all bits in the INTEN register, i.e. INTENCLR = 0xFFFFFFFF.
- Explicitly configure the peripheral that you are about to enable, and do not rely on configuration values that may be inherited from the peripheral that was disabled.
- · Enable the now configured peripheral.

See which peripherals are sharing ID in Instantiation on page 23.

3.3.3 Peripheral registers

Most peripherals feature an ENABLE register. Unless otherwise is specified in the chapter, the peripheral registers must be configured before enabling the peripheral.

PSEL registers need to be set before a peripheral is enabled or started. Updating PSEL registers while the peripheral is running has no effect. In order to connect a peripheral to a different GPIO, the peripheral must be disabled, the PSEL register updated and the peripheral re-enabled. It takes four CPU cycles between the PSEL register update and the connection between a peripheral and a GPIO becoming effective.

Note that the peripheral must be enabled before tasks and events can be used.

Most of the register values are lost during System OFF or when a reset is triggered. Some registers will retain their values in System OFF or for some specific reset sources. These registers are marked as retained in the register description for a given peripheral. For more info on these retained registers' behavior, see chapter Reset on page 54.

3.3.4 Bit set and clear

Registers with multiple single-bit bit fields may implement the set-and-clear pattern. This pattern enables firmware to set and clear individual bits in a register without having to perform a read-modify-write operation on the main register.

This pattern is implemented using three consecutive addresses in the register map, where the main register is followed by dedicated SET and CLR registers (in that exact order).

The SET register is used to set individual bits in the main register, while the CLR register is used to clear individual bits in the main register. Writing 1 to a bit in SET or CLR register will set or clear the same bit in the main register respectively. Writing 0 to a bit in SET or CLR register has no effect. Reading the SET or CLR register returns the value of the main register.

Note: The main register may not be visible and hence not directly accessible in all cases.



3.3.5 Tasks

Tasks are used to trigger actions in a peripheral, for example to start a particular behavior. A peripheral can implement multiple tasks with each task having a separate register in that peripheral's task register group.

A task is triggered when firmware writes 1 to the task register, or when the peripheral itself or another peripheral toggles the corresponding task signal. See the figure Tasks, events, shortcuts, publish, subscribe and interrupts on page 15.

3.3.6 Events

Events are used to notify peripherals and the CPU about events that have happened, for example a state change in a peripheral. A peripheral may generate multiple events, where each event has a separate register in that peripheral's event register group.

An event is generated when the peripheral itself toggles the corresponding event signal, and the event register is updated to reflect that the event has been generated (see figure Tasks, events, shortcuts, publish, subscribe and interrupts on page 15). An event register is only cleared when firmware writes 0 to it. Events can be generated by the peripheral even when the event register is set to 1.

3.3.7 Shortcuts

A shortcut is a direct connection between an event and a task within the same peripheral. If a shortcut is enabled, the associated task is automatically triggered when its associated event is generated.

Using shortcuts is equivalent to making the connection outside the peripheral and through the DPPI. However, the propagation delay when using shortcuts is usually shorter than the propagation delay through the DPPI.

Shortcuts are predefined, which means that their connections cannot be configured by firmware. Each shortcut can be individually enabled or disabled through the shortcut register, one bit per shortcut, giving a maximum of 32 shortcuts for each peripheral.

3.3.8 Publish / Subscribe

Events and tasks from different peripherals can be connected together through the DPPI system. See Tasks, events, shortcuts, publish, subscribe and interrupts on page 15. This is done through publish / subscribe registers in each peripheral. An event can be published onto a DPPI channel by configuring the event's PUBLISH register. Similarly a task can subscribe to a DPPI channel by configuring the task's SUBSCRIBE register.

See for details.

3.3.9 Interrupts

All peripherals support interrupts. Interrupts are generated by events.

A peripheral only occupies one interrupt, and the interrupt number follows the peripheral ID. For example, the peripheral with ID=4 is connected to interrupt number 4 in the nested vectored interrupt controller (NVIC).

Using registers INTEN, INTENSET, and INTENCLR, every event generated by a peripheral can be configured to generate that peripheral's interrupt. Multiple events can be enabled to generate interrupts simultaneously. To resolve the correct interrupt source, the event registers in the event group of peripheral registers will indicate the source.

Some peripherals implement only INTENSET and INTENCLR registers, and the INTEN register is not available on those peripherals. See the individual peripheral chapters for details. In all cases, reading back the INTENSET or INTENCLR register returns the same information as in INTEN.



Each event implemented in the peripheral is associated with a specific bit position in the INTEN, INTENSET and INTENCLR registers.

The relationship between tasks, events, shortcuts, and interrupts is illustrated in figure Tasks, events, shortcuts, publish, subscribe and interrupts on page 15.

Interrupt clearing

Interrupts should always be cleared.

Clearing an interrupt by writing 0 to an event register, or disabling an interrupt using the INTENCLR register, may take a number of CPU clock cycles to take effect. This means that an interrupt may reoccur immediately, even if a new event has not come, if the program exits an interrupt handler after the interrupt is cleared or disabled but before it has taken effect.

Note: To avoid an interrupt reoccurring before a new event has come, the program should perform a read from one of the peripheral registers. For example, the event register that has been cleared, or the INTENCLR register that has been used to disable the interrupt.

Care should be taken to ensure that the compiler does not remove the read operation as an optimization.

3.3.10 Secure/non-secure peripherals

For some peripherals, the security configuration can change from secure to non-secure, or vice versa. Care must be taken when changing the security configuration of a peripheral, to prevent security information leakage and ensure correct operation.

The following sequence should be followed, where applicable, when configuring and changing the security settings of a peripheral in the SPU - System protection unit on page 257:

- 1. Stop peripheral operation
- 2. Disable the peripheral
- 3. Remove pin connections
- 4. Disable DPPI connections
- 5. Clear sensitive registers (e.g. writing back default values)
- 6. Change peripheral security setting in the SPU System protection unit on page 257
- 7. Re-enable the peripheral



4 Application core

4.1 CPU

The ARM[®] Cortex-M33 processor has a 32-bit instruction set (Thumb[®]-2 technology) that implements a superset of 16 and 32-bit instructions to maximize code density and performance.

This processor implements several features that enable energy-efficient arithmetic and high-performance signal processing, including:

- Digital signal processing (DSP) instructions
- Single-cycle multiply and accumulate (MAC) instructions
- · Hardware divide
- 8- and 16-bit single instruction, multiple data (SIMD) instructions
- Single-precision floating-point unit (FPU)
- Memory Protection Unit (MPU)
- ARM[®] TrustZone[®] for ARMv8-M

The ARM[®] Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer for the ARM[®] Cortex processor series is implemented and available for the M33 CPU.

Real-time execution is highly deterministic in thread mode, to and from sleep modes, and when handling events at configurable priority levels via the nested vectored interrupt controller (NVIC).

Executing code from internal or external flash will have a wait state penalty. The instruction cache can be enabled to minimize flash wait states when fetching instructions. For more information on cache, see Cache on page 31. The section Electrical specification on page 20 shows CPU performance parameters including the wait states in different modes, CPU current and efficiency, and processing power and efficiency based on the CoreMark® benchmark.

4.1.1 CPU and support module configuration

The ARM® Cortex®-M33 processor has a number of CPU options and support modules implemented on the device.



Option / Module	Description	Implemented
Core options		
NVIC	Nested vectored interrupt controller	
PRIORITIES	Priority bits	3
WIC	Wake-up interrupt controller	NO
Endianness	Memory system endianness	Little endian
DWT	Data watchpoint and trace	YES
Modules		
MPU_NS	Number of non-secure memory protection unit (MPU) regions	16
MPU_S	Number of secure MPU regions	16
SAU	Number of security attribution unit (SAU) regions	0, see SPU for more information about
		secure regions.
FPU	Floating-point unit	YES
DSP	Digital signal processing extension	YES
ARMv8-M TrustZone®	ARMv8-M security extensions	YES
CPIF	Co-processor interface	NO
ETM	Embedded trace macrocell	YES
ITM	Instrumentation trace macrocell	YES
МТВ	Micro trace buffer	NO
СТІ	Cross trigger interface	YES
BPU	Breakpoint unit	YES
HTM	AMBA [™] AHB trace macrocell	NO

4.1.2 Electrical specification

4.1.2.1 CPU performance

The CPU clock speed is 64 MHz. Current and efficiency data is taken when in System ON and the CPU is executing the CoreMark $^{^{\text{TM}}}$ benchmark. It includes power regulator and clock base currents. All other blocks are IDLE.

Symbol	Description	Min.	Тур.	Max.	Units
W _{FLASH}	CPU wait states, running from flash, cache disabled	0		4	
W _{FLASHCACHE}	CPU wait states, running from flash, cache enabled	0		2	
W_{RAM}	CPU wait states, running from RAM			0	
CM _{FLASH}	CoreMark ¹ , running from flash, cache enabled		243		Corel
CM _{FLASH/MHz}	CoreMark per MHz, running from flash, cache enabled		3.79		CoreMark/
					MHz
CM _{FLASH/mA}	CoreMark per mA, running from flash, cache enabled, DC/		84		Corel
	DC				mA

4.2 Memory

The application microcontroller has embedded 1024 kB flash and 256 kB RAM for application code and data storage.

As illustrated in Memory layout on page 21, both CPU and EasyDMA are able to access RAM via the AHB multilayer interconnect. See AHB multilayer interconnect on page 47 and EasyDMA on page 44 for more information about AHB multilayer interconnect and EasyDMA respectively. The LTE modem can access all application MCU memory, but typically a small portion of RAM is dedicated to data exchange between application MCU and the modem baseband controller.



¹ Using IAR compiler

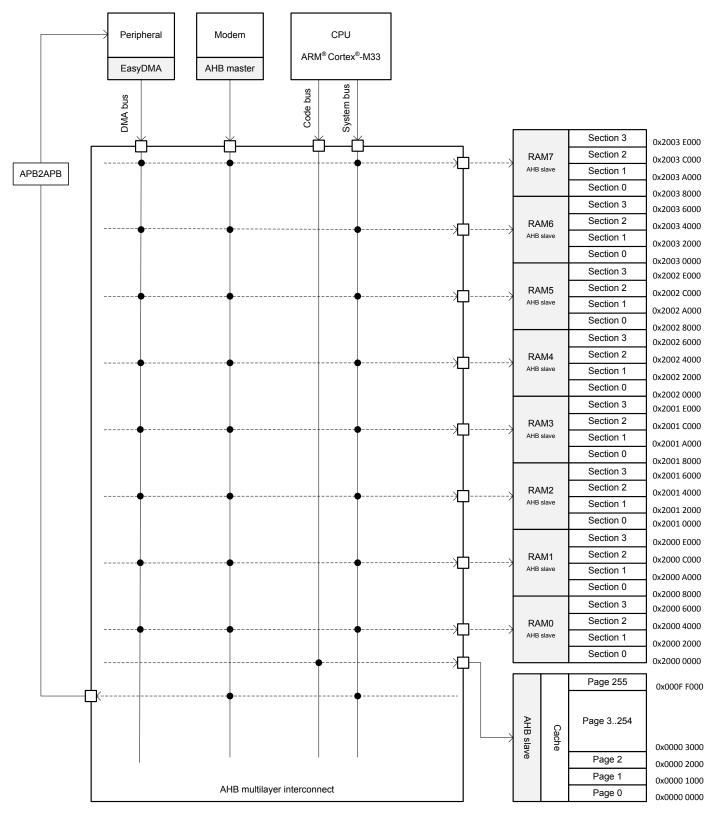


Figure 3: Memory layout

RAM - Random access memory

RAM can be read and written an unlimited number of times by the CPU and the EasyDMA.

Each RAM AHB slave is connected to one or more RAM sections. See Memory layout on page 21 for more information.



The RAM blocks power states and retention states in System ON and System OFF modes are controlled by the VMC.

Flash - Non-volatile memory

Flash can be read an unlimited number of times by the CPU and is accessible via the AHB interface connected to the CPU, see Memory layout on page 21 for more information. There are restrictions on the number of times flash can be written and erased, and also on how it can be written. Writing to flash is managed by the non-volatile memory controller (NVMC).

4.2.1 Memory map

All memory and registers are found in the same address space, as illustrated in the device memory map below.



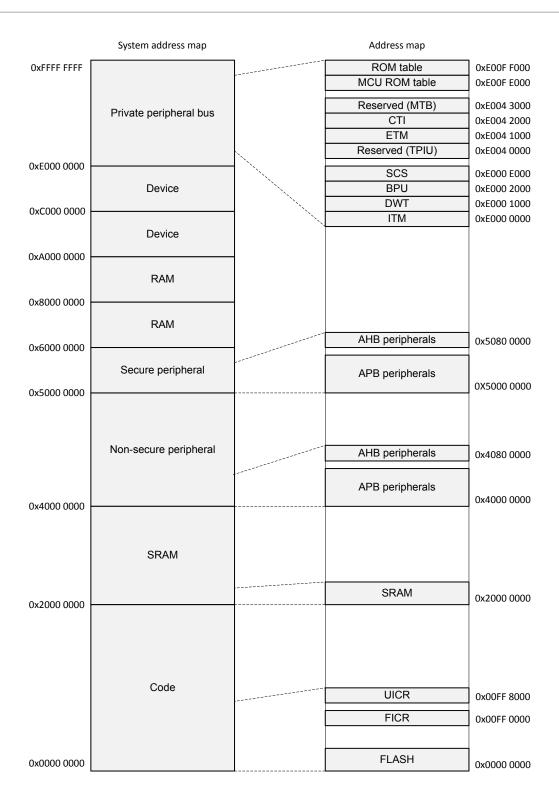


Figure 4: Memory map

Some of the registers are retained (their values kept). Read more about retained registers in Retained registers on page 54 and Reset behavior on page 55.

4.2.2 Instantiation

ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
3	0x50003000	SPU	SPU	S	NA	System Protection Unit



Mathematical Regulations REGULATIONS REGULATIONS NA Regulation configuration Regulations NA Regulation configuration Regulations NA Regulation configuration Regulations NA Regulation configuration Regulations	ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
Decided Control Decide Control CLOCK CLOCK : S	4	0x50004000	REGULATORS	REGULATORS : S	US	NA	Regulator configuration
5 Ox.000000000000000000000000000000000000	7		REGOLATORS			TV/	negatation configuration
5 0x40005000 POWER POWER: NS US NA Power control 6 0x50008000 CFRLAPPERI CFRLAPPERI S NA CTRLAPPERI 0x50008000 SPIM SPIM0 : NS US SA SPI Invarier 0 0x50008000 SPIS SPI90 : NS US SA SPI Slave 0 0x50008000 TVIMIN DESTRUCTIONS US SA Two-wire interface master 0 0x50008000 TVIMIN DESTRUCTIONS US SA Two-wire interface slave 0 0x50008000 UARTE UARTED : S US SA Two-wire interface slave 0 0x50008000 UARTE UARTED : S US SA SPI slave 1 0x50009000 SPIMI SPINI : S US SA SPI slave 1 0x50009000 TVIMIN SPINI : S US SA SPI slave 1 0x50009000 TVIMIN SPINI : S US SA Two-wire interface slave 1 0x50009000 TVIMIN SPINI : S US SA Two-wire interface slave 1 0x50009000 TV	5		CLOCK		US	NA	Clock control
8 0x50000000 billion (NS) SPIMO (S) billion (NS) US SA SPI Insister O 8 0x50000000 billion (NS) SPIS (SPIS) Signo (NS) US SA SPI slave O 8 0x50000000 billion (NS) TWIND (SS) Signo (NS) US SA Two write interface moster O 8 0x50000000 billion (NS) TWIND (NS) Signo (NS) US SA Two write interface slave O 8 0x50000000 billion (NS) Signo	5		POWER		US	NA	Power control
Dick Dick Dick SPIMO NS	6	0x50006000	CTRLAPPERI	CTRL_AP_PERI	S	NA	CTRL-AP-PERI
8 0x40000000 SPISO : NS US SA SPIsare 0 8 0x50008000 TWIM "TWIMO : S US SA Two-wire interface master 0 8 0x50008000 TWIS TWISO : SS US SA Two-wire interface slave 0 0x50008000 UARTEO : SS US SA Universal asynchronous receiver/transmitter with Easy0MA 0 0x50009000 SPIM SPIM : S US SA SPI master 1 0x50009000 SPIM : SPIS : SS US SA SPI dave 1 0x50009000 SPIM : SPIS : SS US SA SPI dave 1 0x50009000 TWIM : SS US SA Two-wire interface master 1 0x50009000 TWIM : SS US SA Two-wire interface slave 1 0x50009000 TWIS : SS US SA Universal asynchronous receiver/transmitter with Easy0MA 1 0x50009000 TWIS : SS US SA Universal asynchronous receiver/transmitter with Easy0MA 2 0x50000000 DASODOROOO SPIM : SPIS : SS US <td< td=""><td>8</td><td></td><td>SPIM</td><td></td><td>US</td><td>SA</td><td>SPI master 0</td></td<>	8		SPIM		US	SA	SPI master 0
8 0x40008000 TWIM TWIMO : NS US SA Two-wire interface master 0 8 0x50008000 TWIS TWISO : S TWISO : S UARTE : S UARTE : S 0x40008000 UARTE : S UARTE : S 0x40008000 UARTE : S UARTE : S SPINI :	8		SPIS		US	SA	SPI slave 0
8 0x40008000 TWIS TVISO : NS US SA Two-wire interface slave 0 8 0x50008000 UARTE UARTE 0 : NS US SA Universal asynchronous receiver/transmitter 9 0x50009000 SPIM SPIM1 : NS US SA SPI master 1 9 0x50009000 SPIS SPIS1 : S SPIS1 : NS US SA SPI slave 1 0x50009000 TWIM TWIMI : NS US SA Two-wire interface master 1 0x50009000 TWIS TWIST : NS US SA Two-wire interface slave 1 0x50009000 TWIS TWIST : NS US SA Universal asynchronous receiver/transmitter 0x50009000 TWIM TWIST : NS US SA Universal asynchronous receiver/transmitter 0x50009000 TWIM SPIM2 : NS US SA SPI master 2 0x50000000 PSPIM SPIM2 : NS US SA SPI master 2 0x50000000 PSPIM SPIM2 : NS US SA SPI maste	8		TWIM		US	SA	Two-wire interface master 0
B	8		TWIS		US	SA	Two-wire interface slave 0
9 0.440009000	8		UARTE		US	SA	
9 0x40009000 SPIS SPIS1 : NS US SA SPI slave 1 9 0x50009000 TVIIM TWIM1 : S US SA Two-wire interface master 1 9 0x50009000 TWIS1 : NS US SA Two-wire interface slave 1 9 0x50009000 UARTE UARTE1 : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 1 10 0x50000000 SPIM2 : S US SA SPI master 2 0x50000000 SPIM3 : SPIM2 : S US SA SPI slave 2 0x50000000 SPIS : SPIS2 : S US SA SPI slave 2 0x50000000 TWIM : SPIM3 : S US SA Two-wire interface master 2 0x50000000 TWIM : SPIM3 : S US SA Two-wire interface slave 2 0x50000000 TWIM : TWIS2 : NS US SA Two-wire interface slave 2 0x50000000 TWIM : TWIS2 : NS US SA Two-wire interface slave 2 0x500000000 TWIM : TWIM3 : S US SA	9		SPIM		US	SA	SPI master 1
9 0x40009000 TMIM TWIMIT:NS US SA Two-wire interface master: 1 9 0x50009000 TWIS TWIST:NS US SA Two-wire interface slave: 1 0x50009000 UARTE:NS US SA Universal asynchronous receiver/transmitter with EasyDMA: 1 0x5000A000 VARTE:NS US SA Universal asynchronous receiver/transmitter with EasyDMA: 1 0x5000A000 SPIM SPIM2:S US SA SPI master: 2 0x5000A000 SPIS SPIS:S:NS US SA SPI slave: 2 0x5000A000 TWIM TWIM2:NS US SA Two-wire interface master: 2 0x5000A000 TWIN TWISC:S US SA Two-wire interface slave: 2 0x5000A000 TWIN TWISC:S US SA Two-wire interface slave: 2 0x5000A000 TWIN TWISC:S US SA Universal asynchronous receiver/transmitter with EasyDMA: 2 0x5000A000 VARTE: NS US SA Universal asynchronous receiver/transmitter with EasyDMA: 2	9		SPIS		US	SA	SPI slave 1
9 0x40009000 TWIS TWIS1: NS US SA Two-wire interface slave 1 9 0x50009000 UARTE UARTE1: NS US SA Universal asynchronous receiver/transmitter with EasyDMA 1 10 0x500000000	9		TWIM		US	SA	Two-wire interface master 1
0x40009000	9		TWIS		US	SA	Two-wire interface slave 1
10	9		UARTE		US	SA	
10	10		SPIM		US	SA	SPI master 2
10	10		SPIS		US	SA	SPI slave 2
10	10		TWIM		US	SA	Two-wire interface master 2
10	10		TWIS		US	SA	Two-wire interface slave 2
11 0x40008000 SPIM SPIM3 : NS US SA SPI master 3 11 0x50008000 0x40008000 SPIS SPIS3 : S SPIS3 : NS US SA SPI slave 3 11 0x50008000 0x40008000 TWIM TWIM3 : S TWIM3 : NS US SA Two-wire interface master 3 11 0x50008000 0x40008000 TWIS TWIS3 : S TWIS3 : NS US SA Two-wire interface slave 3 11 0x50008000 0x40008000 UARTE UARTE3 : S UARTE3 : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000B000 0x4000B000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC 0x4000E000 SAADC : S SAADC : NS SA Analog to digital converter 15 0x5000F000 TIMER TIMER O: S US NA Timer 0	10		UARTE		US	SA	, ·
11 0x4000B000 SPIS US SA SPI slave 3 11 0x5000B000 0x4000B000 TWIM TWIM3 : S TWIS3 : S US SA Two-wire interface master 3 11 0x5000B000 0x4000B000 TWIS TWIS3 : S TWIS3 : NS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3 : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC : S SAADC : NS US SA Analog to digital converter 15 0x5000F000 TIMER TIMERO : S US NA Timer 0	11		SPIM		US	SA	SPI master 3
11 Ox4000B000 TWIM US SA Two-wire interface master 3 11 Ox5000B000 TWIS TWIS3 : S US SA Two-wire interface slave 3 11 Ox5000B000 UARTE UARTE3 : S US SA Universal asynchronous receiver/transmitter 11 Ox5000B000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 13 Ox5000E000 SAADC : S SAADC : S SAADC : S SAADC : NS 14 Ox5000F000 TIMER TIMERO : S US NA Timer 0	11		SPIS		US	SA	SPI slave 3
11 0x4000B000 TWIS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3 : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC SAADC : NS SA Analog to digital converter 15 0x5000F000 TIMER TIMERO : S US NA Timer 0	11		TWIM		US	SA	Two-wire interface master 3
11 0x4000B000 UARTE UARTE3: NS US SA with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC: S SAADC: NS US SA Analog to digital converter 15 0x5000F000 TIMER TIMERO: S US NA Timer 0	11		TWIS		US	SA	Two-wire interface slave 3
0x5000E000	11		UARTE		US	SA	
14	13	0x5000D000	GPIOTE	GPIOTE0	S	NA	Secure GPIO tasks and events
15 TIMER US NA Timer 0	14		SAADC		US	SA	Analog to digital converter
	15		TIMER		US	NA	Timer 0



ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
16	0x50010000	TIMER	TIMER1:S	US	NA	Timer 1
10	0x40010000	THIVE	TIMER1 : NS	03	10.1	inici 1
17	0x50011000 0x40011000	TIMER	TIMER2 : S TIMER2 : NS	US	NA	Timer 2
20	0x50014000 0x40014000	RTC	RTC0 : S RTC0 : NS	US	NA	Real time counter 0
21	0x50015000 0x40015000	RTC	RTC1:S RTC1:NS	US	NA	Real time counter 1
23	0x50017000 0x40017000	DPPIC	DPPIC : S DPPIC : NS	SPLIT	NA	DPPI controller
24	0x50018000 0x40018000	WDT	WDT : S WDT : NS	US	NA	Watchdog timer
27	0x5001B000 0x4001B000	EGU	EGU0 : S EGU0 : NS	US	NA	Event generator unit 0
28	0x5001C000 0x4001C000	EGU	EGU1 : S EGU1 : NS	US	NA	Event generator unit 1
29	0x5001D000 0x4001D000	EGU	EGU2 : S EGU2 : NS	US	NA	Event generator unit 2
30	0x5001E000 0x4001E000	EGU	EGU3 : S EGU3 : NS	US	NA	Event generator unit 3
31	0x5001F000 0x4001F000	EGU	EGU4 : S EGU4 : NS	US	NA	Event generator unit 4
32	0x50020000 0x40020000	EGU	EGU5 : S EGU5 : NS	US	NA	Event generator unit 5
33	0x50021000 0x40021000	PWM	PWM0 : S PWM0 : NS	US	SA	Pulse width modulation unit 0
34	0x50022000 0x40022000	PWM	PWM1 : S PWM1 : NS	US	SA	Pulse width modulation unit 1
35	0x50023000 0x40023000	PWM	PWM2 : S PWM2 : NS	US	SA	Pulse width modulation unit 2
36	0x50024000 0x40024000	PWM	PWM3 : S PWM3 : NS	US	SA	Pulse width modulation unit 3
38	0x50026000 0x40026000	PDM	PDM:S PDM:NS	US	SA	Pulse density modulation (digital microphone) interface
40	0x50028000 0x40028000	125	12S : S 12S : NS	US	SA	Inter-IC Sound
42	0x5002A000 0x4002A000	IPC	IPC : S IPC : NS	US	NA	Interprocessor communication
44	0x5002C000 0x4002C000	FPU	FPU: S FPU: NS	US	NA	Floating-point unit
49	0x40031000	GPIOTE	GPIOTE1	NS	NA	Non Secure GPIO tasks and events
57	0x50039000 0x40039000	KMU	KMU : S KMU : NS	SPLIT	NA	Key management unit
57	0x50039000 0x40039000	NVMC	NVMC : S NVMC : NS	SPLIT	NA	Non-volatile memory controller
58	0x5003A000 0x4003A000	VMC	VMC : S VMC : NS	US	NA	Volatile memory controller
64	0x50840000	CRYPTOCELL	CRYPTOCELL	S	NSA	CryptoCell sub-system control interface
66	0x50842500 0x40842500	GPIO	P0 : S P0 : NS	SPLIT	NA	General purpose input and output
N/A	0x00FF0000	FICR	FICR	S	NA	Factory information configuration
N/A	0x00FF8000	UICR	UICR	S	NA	User information configuration
N/A	0xE0080000	TAD	TAD	S	NA	Trace and debug control



Table 4: Instantiation table

4.2.3 Peripheral access control capabilities

Information about the peripheral access control capabilities can be found in the instantiation table.

The instantiation table has two columns containing the information about access control capabilities for a peripheral:

- Secure mapping: This column defines configuration capabilities for TrustZone[®]-M secure attribute.
- DMA security: This column indicates if the peripheral has DMA capabilities, and if DMA transfer can be assigned to a different security attribute than the peripheral itself.

For details on options in secure mapping column and DMA security column, see the following tables respectively.

Abbreviation	Description
NS	Non-secure: This peripheral is always accessible as a non-secure peripheral.
S	Secure: This peripheral is always accessible as a secure peripheral.
US	User-selectable: Non-secure or secure attribute for this peripheral is defined by the PERIPHID[0].PERM register.
SPLIT	Both non-secure and secure: The same resource is shared by both secure and non-secure code.

Table 5: Secure mapping column options

Abbreviation	Description						
NA	Not applicable: Peripheral has no DMA capability.						
NSA	No separate attribute: Peripheral has DMA, and DMA transfers always have the same security attribute as assigned to the peripheral.						
SA	Separate attribute: Peripheral has DMA, and DMA transfers can have a different security attribute than the one assigned to the peripheral.						

Table 6: DMA security column options

4.3 VMC — Volatile memory controller

The volatile memory controller (VMC) provides power control of RAM blocks.

Each of the available RAM blocks, which can contain multiple RAM sections, can be turned on or off independently in System ON mode, using the RAM[n]registers. These registers also control if a RAM block, or some of its sections, is retained in System OFF mode. See Memory chapter for more information about RAM blocks and sections.



4.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5003A000	VMC	VMC : S	US	NA	Volatile memory controller	
0x4003A000	VIVIC	VMC : NS	03	NA	voiatile memory controller	

Table 7: Instances

Register	Offset	Security	Description
RAM[0].POWER	0x600		RAM0 power control register
RAM[0].POWERSET	0x604		RAM0 power control set register
RAM[0].POWERCLR	0x608		RAM0 power control clear register
RAM[1].POWER	0x610		RAM1 power control register
RAM[1].POWERSET	0x614		RAM1 power control set register
RAM[1].POWERCLR	0x618		RAM1 power control clear register
RAM[2].POWER	0x620		RAM2 power control register
RAM[2].POWERSET	0x624		RAM2 power control set register
RAM[2].POWERCLR	0x628		RAM2 power control clear register
RAM[3].POWER	0x630		RAM3 power control register
RAM[3].POWERSET	0x634		RAM3 power control set register
RAM[3].POWERCLR	0x638		RAM3 power control clear register
RAM[4].POWER	0x640		RAM4 power control register
RAM[4].POWERSET	0x644		RAM4 power control set register
RAM[4].POWERCLR	0x648		RAM4 power control clear register
RAM[5].POWER	0x650		RAM5 power control register
RAM[5].POWERSET	0x654		RAM5 power control set register
RAM[5].POWERCLR	0x658		RAM5 power control clear register
RAM[6].POWER	0x660		RAM6 power control register
RAM[6].POWERSET	0x664		RAM6 power control set register
RAM[6].POWERCLR	0x668		RAM6 power control clear register
RAM[7].POWER	0x670		RAM7 power control register
RAM[7].POWERSET	0x674		RAM7 power control set register
RAM[7].POWERCLR	0x678		RAM7 power control clear register

Table 8: Register overview

4.3.1.1 RAM[n].POWER (n=0..7)

Address offset: $0x600 + (n \times 0x10)$

RAMn power control register



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			H G F E D C B A
Reset 0x0000FFFF		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field			Description
A-D RW S[i]POWER (i=03)			Keep RAM section Si of RAM n on or off in System ON mode
			All RAM sections will be switched off in System OFF mode
	Off	0	Off
	On	1	On
E-H RW S[i]RETENTION (i=03)			Keep retention on RAM section Si of RAM n when RAM
			section is switched off
	Off	0	Off
	On	1	On

4.3.1.2 RAM[n].POWERSET (n=0..7)

Address offset: $0x604 + (n \times 0x10)$

RAMn power control set register

When read, this register will return the value of the POWER register.

Bit ni	Bit number			31 30 29 28 27 26 25 24	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					H G F E D C B A
Rese	t 0x0	000FFFF		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1
ID					
A-D	W	S[i]POWER (i=03)			Keep RAM section Si of RAM n on or off in System ON mode
			On	1	On
E-H	W	S[i]RETENTION (i=03)			Keep retention on RAM section Si of RAM n when RAM
					section is switched off
			On	1	On

4.3.1.3 RAM[n].POWERCLR (n=0..7)

Address offset: $0x608 + (n \times 0x10)$ RAMn power control clear register

When read, this register will return the value of the POWER register.

Bit nu	ımbe	er		31 30 29 28	27 26 2	25 24	23	22 21	1 20	19 1	.8 17	16	15 1	.4 13	12	11 1	9	8	7 6	5 5	4	3	2	1 0
ID										Н	G F	Ε										D	С	ВА
Rese	t 0x0	000FFFF		0 0 0 0	0 0	0 0	0	0 0	0	0	0 0	0	1 :	1 1	1	1 1	. 1	1	1 1	1	. 1	1	1 :	1 1
ID																								
A-D	W	S[i]POWER (i=03)					Kee	ep RA	AM s	section	on Si	of I	RAM	n or	n or	off i	n Sys	tem	٥N	mo	ode			
			Off	1			Off	F																
E-H	W	S[i]RETENTION (i=03)					Kee	ep re	tent	ion o	on RA	AΜ	secti	ion S	i of	RAIV	l n w	hen	RA	М				
							sec	tion	is sv	witch	ed o	ff												
			Off	1			Off																	

4.4 NVMC — Non-volatile memory controller

The non-volatile memory controller (NVMC) is used for writing and erasing of the internal flash memory and the user information configuration register (UICR).



The NVMC is a split security peripheral. This means that when the NVMC is configured as non-secure, only a subset of the registers is available from the non-secure code. See SPU - System protection unit on page 257 and Registers on page 31 for more details.

When the NVMC is configured to be a secure peripheral, only secure code has access.

Before a write can be performed, the NVMC must be enabled for writing in CONFIG.WEN. Similarly, before an erase can be performed, the NVMC must be enabled for erasing in CONFIG.EEN, see CONFIG on page 32. The user must make sure that writing and erasing are not enabled at the same time. Failing to do so may result in unpredictable behavior.

4.4.1 Writing to flash

When writing is enabled, in CONFIG register for secure region, or in CONFIGNS register for non-secure region, flash is written by writing a full 32-bit word to a word-aligned address in flash.

Secure code has access to both secure and non-secure regions, by using the appropriate configuration of CONFIG and CONFIGNS registers. Non-secure code, in constrast, has access to non-secure regions only. Thus, non-secure code only needs CONFIGNS.

The NVMC is only able to write '0' to erased bits in flash, that is bits set to '1'. It cannot write a bit back to '1'.

As illustrated in Memory on page 20, flash is divided into multiple pages. The same address in flash can only be written n_{WRITE} number of times before a page erase must be performed.

Only full 32-bit words can be written to flash using the NVMC interface. To write less than 32 bits to flash, write the data as a word, and set all the bits that should remain unchanged in the word to '1'. Note that the restriction about the number of writes (see above) still applies in this case.

The time it takes to write a word to flash is specified by t_{WRITE} . If CPU executes code from flash while the NVMC is writing to flash, the CPU will be stalled.

Only word-aligned writes are allowed. Byte or half-word-aligned writes will result in a bus fault.

4.4.2 Erasing a secure page in flash

When secure region erase is enabled (in CONFIG register), a flash page can be erased by writing 0xFFFFFFF into the first 32-bit word in a flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by t_{ERASEPAGE}. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

See Partial erase of a page in flash for information on splitting the erase time in smaller chunks.

4.4.3 Erasing a non-secure page in flash

When non-secure region erase is enabled, a non-secure flash page can be erased by writing 0xFFFFFFFF into the first 32-bit word of the flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by t_{ERASEPAGE}. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.4 Writing to user information configuration registers (UICR)

User information configuration registers (UICR) are written in the same way as flash. After UICR has been written, the new UICR configuration will only take effect after a reset.



UICR is only accessible by secure code. Any write from non-secure code will be faulted. In order to lock the chip after uploading non-secure code, non-secure debugger needs to use the WRITEUICRNS register inside the NVMC in order to set APPROTECT (APPROTECT will be written to 0x00000000).

UICR can only be written nwRITE number of times before an erase must be performed using ERASEALL.

The time it takes to write a word to the UICR is specified by t_{WRITE} . The CPU is stalled if the CPU executes code from the flash while the NVMC is writing to the UICR.

4.4.5 Frase all

When erase is enabled, the whole flash and UICR can be erased in one operation by using the ERASEALL register. ERASEALL will not erase the factory information configuration registers (FICR).

This functionality can be blocked by some configuration of the UICR protection bits, see the table NVMC blocking on page 30.

The time it takes to perform an ERASEALL on page 33 command is specified by t_{ERASEALL}. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.6 NVMC protection mechanisms

This chapter describes the different protection mechanisms for the non-volatile memory.

4.4.6.1 NVMC blocking

UICR integrity is assured through use of multiple levels of protection. UICR protection bits can be configured to allow or block certain operations.

The table below shows the different status of UICR protection bits, and which operations are allowed or blocked.

	UICR protection bit	NVM	NVMC protection			
SECUREAPPR	ROTECT APPROTECT	ERASEPROTECT	CTRL-AP	NVMC		
			ERASEALL	ERASEALL		
0	0	0	Available	Available		
1	X	0	Available	Blocked		
Х	1	0	Available	Blocked		
Χ	X	1	Blocked	Blocked		

Table 9: NVMC protection (1 - Enabled, 0 - Disabled, X - Don't care)

Note: Erase can still be performed through CTRL-AP, regardless of the above settings. See CTRL-AP - Control access port on page 368 for more information.

Uploading code with secure debugging blocked

Non-secure code can program non-secure flash regions. In order to perform these operations, the NVMC has the following non-secure registers: CONFIGNS, READY and READYNEXT.

Register CONFIGNS on page 34 works as the CONFIG register but it is used only for non-secure transactions. Both page erase and writing inside the flash require a write transaction (see Erasing a secure page in flash on page 29 or Erasing a non-secure page in flash on page 29). Because of this, the SPU - System protection unit on page 257 will guarantee that the non-secure code cannot write inside a secure page, since the transaction will never reach the NVMC controller.



4.4.6.2 NVMC power failure protection

NVMC power failure protection is possible through use of power-fail comparator that is monitoring power supply.

If the power-fail comparator is enabled, and the power supply voltage is below V_{POF} threshold, the power-fail comparator will prevent the NVMC from performing erase or write operations in non-volatile memory (NVM).

If a power failure warning is present at the start of an NVM write or erase operation, the NVMC will block the operation and a bus error will be signalled. If a power failure warning occurs during an ongoing NVM write operation, the NVMC will try to finish the operation. And if the power failure warning persists, consecutive NVM write operations will be blocked by the NVMC, and a bus error will be signalled. If a power failure warning occurs during an NVM erase operation, the operation is aborted and a bus error is signalled.

4.4.7 Cache

An instruction cache (I-Cache) can be enabled for the ICODE bus in the NVMC.

See Memory map on page 22 for the location of flash.

A cache hit is an instruction fetch from the cache, and it has a 0 wait-state delay. The number of wait-states for a cache miss, where the instruction is not available in the cache and needs to be fetched from flash, depends on the processor frequency and is shown in CPU on page 19.

Enabling the cache can increase the CPU performance, and reduce power consumption by reducing the number of wait cycles and the number of flash accesses. This will depend on the cache hit rate. Cache draws current when enabled. If the reduction in average current due to reduced flash accesses is larger than the cache power requirement, the average current to execute the program code will be reduced.

When disabled, the cache does not draw current and its content is not retained.

It is possible to enable cache profiling to analyze the performance of the cache for your program using the register ICACHECNF. When profiling is enabled, registers IHIT and IMISS are incremented for every instruction cache hit or miss respectively.

4.4.8 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50039000	NVMC	NVMC : S	SPLIT	NA	Non-volatile memory	
0x40039000	INVIVIC	NVMC : NS	JFLI1	INA	controller	

Table 10: Instances

Register	Offset	Security	Description
READY	0x400	NS	Ready flag
READYNEXT	0x408	NS	Ready flag
CONFIG	0x504	S	Configuration register
ERASEALL	0x50C	S	Register for erasing all non-volatile user memory
ERASEPAGEPARTIALCFG	0x51C	S	Register for partial erase configuration
ICACHECNF	0x540	S	I-code cache configuration register
IHIT	0x548	S	I-code cache hit counter
IMISS	0x54C	S	I-code cache miss counter
CONFIGNS	0x584	NS	
WRITEUICRNS	0x588	NS	Non-secure APPROTECT enable register
FORCEONNVM	0x700	S	Force on all NVM supplies. Also see the internal section in the NVMC chapter.



Register	Offset	Security	Description
FORCEOFFNVM	0x728	S	Force off NVM supply. Also see the internal section in the NVMC chapter.

Table 11: Register overview

4.4.8.1 READY

Address offset: 0x400

Ready flag

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000001		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R READY			NVMC is ready or busy
	Busy	0	NVMC is busy (on-going write or erase operation)
	Ready	1	NVMC is ready

4.4.8.2 READYNEXT

Address offset: 0x408

Ready flag

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000001		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R READYNEXT			NVMC can accept a new write operation
		Busy	0	NVMC cannot accept any write operation
		Ready	1	NVMC is ready

4.4.8.3 CONFIG

Address offset: 0x504 Configuration register This register is one hot

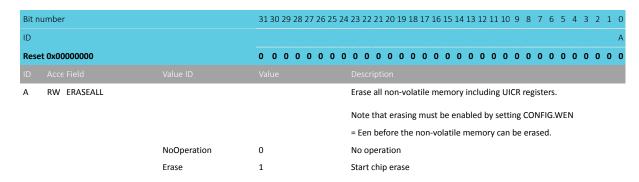
Bit number		31 30 29 28 2	27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				ААА
Reset 0x00000000		0 0 0 0	0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field				Description
A RW WEN				Program memory access mode. It is strongly recommended
				to only activate erase and write modes when they are
				actively used.
				Enabling write or erase will invalidate the cache and keep it
				invalidated.
	Ren	0		Read only access
	Wen	1		Write enabled
	Een	2		Erase enabled
	PEen	4		Partial erase enabled



4.4.8.4 ERASEALL

Address offset: 0x50C

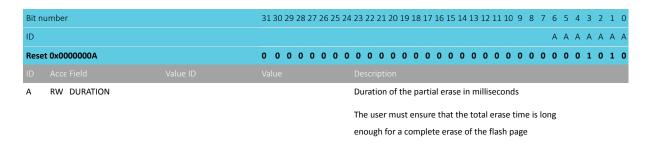
Register for erasing all non-volatile user memory



4.4.8.5 ERASEPAGEPARTIALCFG

Address offset: 0x51C

Register for partial erase configuration



4.4.8.6 ICACHECNF

Address offset: 0x540

I-code cache configuration register

Bit n	umber		31 30 29 28 27 2	6 25 2	4 23 2	22 21	20 1	9 18	3 17	16	15	14	13	12 :	11 1	.0 9	8	7	6	5	4	3	2	1 0
ID																	В							Α
Rese	et 0x00000000		0 0 0 0 0 0	0 0	0 0	0 0	0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0
ID																								
Α	RW CACHEEN				Cacl	he en	able																	
		Disabled	0		Disa	ble c	ache	. Inv	valio	date	es a	II c	ach	e ei	ntrie	es.								
		Enabled	1		Ena	ble ca	iche																	
В	RW CACHEPROFEN				Cacl	he pro	ofilin	ng er	nabl	le														
		Disabled	0		Disa	ble c	ache	pro	ofilir	ng														
		Enabled	1		Ena	ble ca	che	pro	filin	g														

4.4.8.7 IHIT

Address offset: 0x548

I-code cache hit counter



Reset 0x000000000	
<u> </u>	
A A A A A A A A A A A A A A A A A A A	
	A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8	7 6 5 4 3 2 1

4.4.8.8 IMISS

Address offset: 0x54C I-code cache miss counter

Α	RW MISSES	Number of cache misses	
ID			
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0
ID		A A A A A A A A A A A A A A A A A A A	A A A
Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	2 1 0

4.4.8.9 CONFIGNS

Address offset: 0x584
This register is one hot

Bit number	31 30 29 28	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		АА
Reset 0x00000000	0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Description
A RW WEN		Program memory access mode. It is strongly recommended
		to only activate erase and write modes when they are
		actively used.
		Enabling write or erase will invalidate the cache and keep it
		invalidated.
Re	n 0	Read only access
We	en 1	Write enabled
Ee	n 2	Erase enabled

4.4.8.10 WRITEUICRNS

Address offset: 0x588

Non-secure APPROTECT enable register

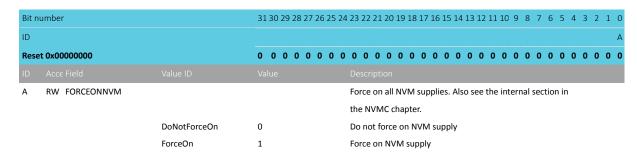
Bit no	umbe	er		31	30	29 :	28 2	27 2	6 2	25 2	24	23 :	22 :	21 2	20 1	19 1	8 1	7 1	6 15	5 14	13	12	11 :	10 !	9 8	3 7	7 6	5	4	3	2 1	. 0
ID				В	В	В	В	В	3	В	В	В	В	В	В	ВЕ	3 E	3 E	ВВ	В	В	В	В	В	ВЕ	B E	3 B	В	В			Α
Rese	t 0x0	0000000		0	0	0	0	0 () ו	0	0	0	0	0	0	0 () () (0	0	0	0	0	0	0 0) (0	0	0	0	0 (0
ID												Des																				
Α	W	SET										Allo	w	nor	-se	cur	e co	ode	to	set	APF	PRO	TEC	Т								
			Set	1								Set	val	lue																		
В	W	KEY										Key	to	wr	te i	in o	rde	r to	va	lida	te t	he י	writ	e o _l	oera	tio	n					

4.4.8.11 FORCEONNVM

Address offset: 0x700



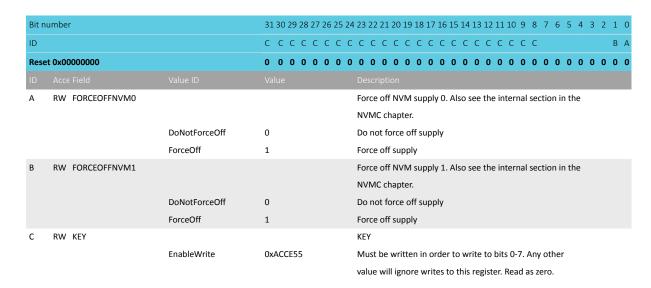
Force on all NVM supplies. Also see the internal section in the NVMC chapter.



4.4.8.12 FORCEOFFNVM

Address offset: 0x728

Force off NVM supply. Also see the internal section in the NVMC chapter.



4.4.9 Electrical specification

4.4.9.1 Flash programming

Symbol	Description	Min.	Тур.	Max.	Units
n _{WRITE}	Number of times a 32-bit word can be written before erase			2	
n _{ENDURANCE}	Erase cycles per page	10,000			
t _{WRITE}	Time to write one 32-bit word			43	μs
t _{ERASEPAGE}	Time to erase one page			87	ms
t _{ERASEALL}	Time to erase all flash			173	ms
t _{ERASEPAGEPARTIAL,set}	uf Setup time for one partial erase			1.08	ms

4.4.9.2 Cache size

Symbol	Description	Min.	Тур.	Max.	Units
Size _{ICODE}	I-Code cache size		2048		Bytes



4.5 FICR — Factory information configuration registers

Factory information configuration registers (FICR) are pre-programmed in factory and cannot be erased by the user. These registers contain chip-specific information and configuration.

4.5.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x00FF0000	FICR	FICR	S	NA	Factory information	
					configuration	

Table 12: Instances

Register	Offset	Security	Description
INFO.DEVICEID[0]	0x204		Device identifier
INFO.DEVICEID[1]	0x208		Device identifier
INFO.PART	0x20C		Part code
INFO.VARIANT	0x210		Part Variant, Hardware version and Production configuration
INFO.PACKAGE	0x214		Package option
INFO.RAM	0x218		RAM variant
INFO.FLASH	0x21C		Flash variant
INFO.CODEPAGESIZE	0x220		Code memory page size
INFO.CODESIZE	0x224		Code memory size
INFO.DEVICETYPE	0x228		Device type
TRIMCNF[n].ADDR	0x300		Address
TRIMCNF[n].DATA	0x304		Data
TRNG90B.BYTES	0xC00		Amount of bytes for the required entropy bits
TRNG90B.RCCUTOFF	0xC04		Repetition counter cutoff
TRNG90B.APCUTOFF	0xC08		Adaptive proportion cutoff
TRNG90B.STARTUP	0xC0C		Amount of bytes for the startup tests
TRNG90B.ROSC1	0xC10		Sample count for ring oscillator 1
TRNG90B.ROSC2	0xC14		Sample count for ring oscillator 2
TRNG90B.ROSC3	0xC18		Sample count for ring oscillator 3
TRNG90B.ROSC4	0xC1C		Sample count for ring oscillator 4

Table 13: Register overview

4.5.1.1 INFO.DEVICEID[n] (n=0..1)

Address offset: $0x204 + (n \times 0x4)$

Device identifier

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field	
A R DEVICEID	64 bit unique device identifier

DEVICEID[0] contains the least significant bits of the device identifier. DEVICEID[1] contains the most significant bits of the device identifier.



4.5.1.2 INFO.PART

Address offset: 0x20C

Part code

Bit number	31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A	
Reset 0x00009160	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 1 0 0 1 0 0 1 0 1 1 0 0 0 0
ID Acce Field		
A R PART		Part code

4.5.1.3 INFO.VARIANT

Address offset: 0x210

Part Variant, Hardware version and Production configuration

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			AAAAAA	
Rese	t 0x0FFFFFFF		0 0 0 0 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	R VARIANT			Part Variant, Hardware version and Production
				configuration, encoded as ASCII
		AAAA	0x41414141	AAAA
		AAA0	0x41414130	AAAO

4.5.1.4 INFO.PACKAGE

Address offset: 0x214

Package option

Bit number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A	. A A A A A A A A A A A A A A A A A A A
Reset 0x00002000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A R PACKAGE			Package option
	CC	0x2000	CCxx - 236 ball wICSP

4.5.1.5 INFO.RAM

Address offset: 0x218

RAM variant

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	. A A A A A A A A A A A A A A A A A A A
Reset 0x00000100	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R RAM		RAM variant
K256	0x100	256 kByte RAM
Unspecified	0xFFFFFFF	Unspecified





4.5.1.6 INFO.FLASH

Address offset: 0x21C

Flash variant

Bit number		31 30 29 28 27 26 25	$24\ 23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID		A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0x00000400		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R FLASH			Flash variant
	K1024	0x400	1 MByte FLASH

4.5.1.7 INFO.CODEPAGESIZE

Address offset: 0x220 Code memory page size

Bit number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0x00001000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0
ID Acce Field Value ID		

A R CODEPAGESIZE

Code memory page size

4.5.1.8 INFO.CODESIZE

Address offset: 0x224 Code memory size

Α	A R CODESIZE												Coc	de r	nen	nory	siz	e in	nur	mbe	er o	f pa	ges										
ID																																	
Res	Reset 0x00000100					0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0 (0 (0	0	0	1	0	0	0	0	0 0	0	0
ID					А	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α,	Δ Δ	A	Α	Α	Α	Α ,	Δ .	Α Α	Α	Α	Α	Α	Α	Α	Α.	4 Δ	A	Α
Bit r	Bit number D					1 30	29	28	27	' 26	25	24	23 :	22 :	21 2	0 19	9 18	3 17	16	15 1	14 1	.3 1	2 1:	l 10	9	8	7	6	5	4	3 2	1	0

Code memory size in number of pages

Total code space is: CODEPAGESIZE * CODESIZE

4.5.1.9 INFO.DEVICETYPE

Address offset: 0x228

Device type

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field			
A R DEVICETYPE			Device type
	Die	0x0000000	Device is an physical DIE
	FPGA	0xFFFFFFF	Device is an FPGA

4.5.1.10 TRIMCNF[n].ADDR (n=0..255)

Address offset: $0x300 + (n \times 0x8)$



Address



4.5.1.11 TRIMCNF[n].DATA (n=0..255)

Address offset: $0x304 + (n \times 0x8)$

Data

A R Data		Data
ID Acce Field		
Reset 0xFFFFFFF	1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID	A A A A A A	
Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

4.5.1.12 TRNG90B.BYTES

Address offset: 0xC00

Amount of bytes for the required entropy bits



4.5.1.13 TRNG90B.RCCUTOFF

Address offset: 0xC04

Repetition counter cutoff

										_																			
ID																													
Rese	t OxFFFFFFFF		1	1 1	L 1	1	1	1	1	1	1	1	1 1	1	1	1 :	1 1	1	1	1 1	l 1	1	1	1	1	1	1 1	1	1
ID			Α	A A	A A	Α	Α	Α	Α	Α	Α	Α.	A A	A	Α	A	Δ Δ	Α	Α	A A	A A	Α	Α	Α	Α	A	4 Α	A	Α
Bit n	it number				9 28	3 27	26	25	24	23	22 :	21 2	20 19	9 18	17	16 1	5 1	4 13	12	11 1	0 9	8	7	6	5	4	3 2	1	0

A R RCCUTOFF Repetition counter cutoff

4.5.1.14 TRNG90B.APCUTOFF

Address offset: 0xC08

Adaptive proportion cutoff



Bit number	31	30	29	28	27 :	26	25 :	24	23	22	21 2	20 1	9 1	3 17	16	15	14 :	13 1	2 11	. 10	9	8	7	6	5 .	4 3	2	1 0
ID	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α /	Δ Δ	A	Α	Α	Α	A	A A	Α	Α	Α	Α	Α	A	4 A	Α	A A
Reset 0xFFFFFFF	1	1	1	1	1	1	1	1	1	1	1	1 :	l 1	. 1	1	1	1	1	l 1	1	1	1	1	1	1	1 1	1	1 1
ID Acce Field									Des																			

A R APCUTOFF

Adaptive proportion cutoff

4.5.1.15 TRNG90B.STARTUP

Address offset: 0xC0C

Amount of bytes for the startup tests

Bit	number	31	30 2	29 2	8 27	26	25 :	24 2	23 2	2 2	1 20	19	18 1	7 16	5 15	14	13	12 1	11	0 9	8	7	6	5	4	3 2	1	0	
ID			Α	A	A A	4 A	Α	Α	Α	A A	Δ Δ	A	Α	A A	\ A	Α	Α	Α	A	A /	A A	Α	Α	Α	Α	Α /	A A	Α	Α
Res	et 0x00000210		0	0	0 (0	0	0	0	0 (0	0	0	0 0	0	0	0	0	0 () () 1	0	0	0	0	1 (0	0	0
ID																													

A R STARTUP

Amount of bytes for the startup tests

4.5.1.16 TRNG90B.ROSC1

Address offset: 0xC10

Sample count for ring oscillator 1

Bit number	31 3	30 2	9 2	8 2	7 26	6 2	5 24	23	3 22	21	20	19	18 1	7 1	6 15	5 14	13	12	11	10	9	8	7	6	5	4	3 2	2 1	0
ID	Α /	A A	Δ Α	Δ .	4 Α	. 4	A A	Α	Α	Α	Α	Α	A A	\ <i>A</i>	A	Α	Α	Α	Α	Α	Α	Α.	A	Α	Α	Α /	Δ Δ	A A	Α
Reset 0xFFFFFFF	1	1 :	1 1	1 1	1 1	. 1	1	1	1	1	1	1	1 1	. 1	. 1	1	1	1	1	1	1	1	1	1	1	1	1 1	1	1
ID Acce Field																													
A R ROSC1								Sa	mp	le d	coui	nt fo	or rii	ng d	scil	late	or 1												

4.5.1.17 TRNG90B.ROSC2

Address offset: 0xC14

Sample count for ring oscillator 2

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field	Value Description
A R ROSC2	Sample count for ring oscillator 2

4.5.1.18 TRNG90B.ROSC3

Address offset: 0xC18

Sample count for ring oscillator 3

Bit number	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID Acce Field Value ID	Value	Description

A R ROSC3

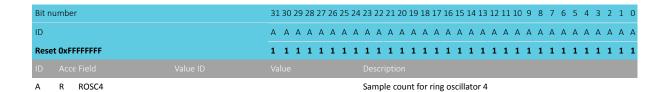
Sample count for ring oscillator 3



4.5.1.19 TRNG90B.ROSC4

Address offset: 0xC1C

Sample count for ring oscillator 4



4.6 UICR — User information configuration registers

The user information configuration registers (UICRs) are non-volatile memory (NVM) registers for configuring user specific settings.

For information on writing UICR registers, see the NVMC — Non-volatile memory controller on page 28 and Memory on page 20 chapters.

4.6.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x00FF8000	UICR	UICR	S	NA	User information	
					configuration	

Table 14: Instances

Register	Offset	Security	Description	
APPROTECT	0x000		Access port protection	
UNUSED0	0x004			Reserved
UNUSED1	0x008			Reserved
UNUSED2	0x00C			Reserved
UNUSED3	0x010			Reserved
XOSC32M	0x014		Oscillator control	
HFXOSRC	0x01C		HFXO clock source selection	
HFXOCNT	0x020		HFXO startup counter	
SECUREAPPROTECT	0x02C		Secure access port protection	
ERASEPROTECT	0x030		Erase protection	
OTP[n]	0x108		OTP bits [31+n*32:0+n*32].	
KEYSLOT.CONFIG[n].DEST	0x400		Destination address where content of the key value registers	
			(KEYSLOT.KEYn.VALUE[0-3]) will be pushed by KMU. Note that this address MUST	
			match that of a peripherals APB mapped write-only key registers, else the KMU	
			can push this key value into an address range which the CPU can potentially read! $ \\$	
KEYSLOT.CONFIG[n].PERM	0x404		Define permissions for the key slot with ID=n+1. Bits 0-15 and 16-31 can only be	
			written once.	
KEYSLOT.KEY[n].VALUE[0]	0x800		Define bits [31:0] of value assigned to KMU key slot ID=n+1	
KEYSLOT.KEY[n].VALUE[1]	0x804		Define bits [63:32] of value assigned to KMU key slot ID=n+1	
KEYSLOT.KEY[n].VALUE[2]	0x808		Define bits [95:64] of value assigned to KMU key slot ID=n+1	
KEYSLOT.KEY[n].VALUE[3]	0x80C		Define bits [127:96] of value assigned to KMU key slot ID=n+1	

Table 15: Register overview



4.6.1.1 APPROTECT

Address offset: 0x000 Access port protection

Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	A A A A A A A A A A A A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW PALL		Blocks debugger read/write access to all CPU registers and
		memory mapped addresses
Unprotected	0xFFFFFFF	Unprotected
Protected	0x00000000	Protected

4.6.1.2 XOSC32M

Address offset: 0x014

Oscillator control

Α	RW CTRL				Pie	rce c	urren	t DA	C cor	ntrol	signa	als									
ID																					
Rese	et 0xFFFFFFCF	1 1 1 1	l 1 1	1 1	. 1	1 1	. 1 :	1 1	1 1	1 1	1 :	1 1	1 1	1	1	1	1 (0	1	1	1 1
ID																	A	A	Α	Α	АА
Bit n	umber	31 30 29 2	8 27 26	25 24	4 23 2	22 21	1 20 1	19 18	17 1	6 15	14 1	.3 12	11 1	0 9	8	7	6 5	5 4	3	2	1 0

4.6.1.3 HFXOSRC

Address offset: 0x01C

HFXO clock source selection

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW HFXOSRC			HFXO clock source selection
		XTAL	1	32 MHz crystal oscillator
		TCXO	0	32 MHz temperature compensated crystal oscillator (TCXO)

4.6.1.4 HFXOCNT

Address offset: 0x020 HFXO startup counter

Bit n	umber		313	30 2:	9 28	3 27	26 2	25 2	4 2	3 22	21	20 :	19 1	8 17	7 16	15	14	13 1	.2 13	l 10	9	8 7	· 6	5 5	4	3	2	1 0
ID																						Δ	. 4	A	Α	Α	Α	АА
Rese	et OxFFFFFFF		1	1 1	. 1	1	1	1 :	1 1	l 1	1	1	1 1	l 1	1	1	1	1 1	1 1	1	1	1 1	. 1	1	1	1	1	1 1
ID																												
Α	RW HFXOCNT								H	IFXO	sta	rtup	о со	unte	er. T	otal	de	boui	nce	time	e = F	IFXC	CN	IT*6	54			
									u	s + (0.5 ι	JS																
		MinDebounceTime	0						Ν	∕lin c	debo	oun	ce ti	me	= (0)*64	l us	+ 0.	5 us	5)								
		MaxDebounceTime	255						٨	∕lax (deb	oun	ce ti	ime	= (2	255 ³	*64	us +	+ 0.5	us)								



4.6.1.5 SECUREAPPROTECT

Address offset: 0x02C

Secure access port protection

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW PALL		Blocks debugger read/write access to all secure CPU
		registers and secure memory mapped addresses
Unprotected	0xFFFFFFF	Unprotected
Protected	0x00000000	Protected

4.6.1.6 ERASEPROTECT

Address offset: 0x030

Erase protection

Bit n	umber		31	30	29	28 2	27 2	6 2	5 2	4 2	3 2	2 2	1 2	0 1	9 18	3 17	16	15	14	13	12	11 1	10 9	9 8	7	6	5	4	3	2	1 0
ID			Α	Α	Α	Α	A A	\ <i>A</i>	Δ Α	A A	۱ ۸	Δ Δ	Α Α	Α Α	Α	Α	Α	Α	Α	Α	Α	Α	A A	Α Α	A	Α	Α	Α	Α	Α	А А
Rese	t 0x00000000		0	0	0	0	0 () (0 () () (0 0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0
ID																															
Α	RW PALL									В	loc	ks I	NVI	ИC	ERA	ASE	٩LL	an	d C	TRL	AP	ERA	\SE/	ALL	fun	ctio	nal	ity			
		Unprotected	0x	FFF	FFF	FF				U	Inp	rot	ecte	ed																	
		Protected	0x	000	0000	000				Р	rot	ect	ed																		

4.6.1.7 OTP[n] (n=0..189)

Address offset: $0x108 + (n \times 0x4)$ OTP bits [31+n*32:0+n*32].

Δ	RW OTP		Bits [31+n*32·0	0+n*32] of OTP reg	ion			
ID								
Reset	0xFFFFFFF	1 1 1 1 1 1	111111	1 1 1 1 1 1	1 1 1 1 1	1 1 1	1 1 1	1 1
ID		A A A A A A	A A A A A A	A A A A A	A A A A A .	A A A	A A A	А А
Bit nu	mber	31 30 29 28 27 26 2	5 24 23 22 21 20 19	18 17 16 15 14 13	12 11 10 9 8	7 6 5	4 3 2	1 0

4.6.1.8 KEYSLOT.CONFIG[n].DEST (n=0..127)

Address offset: $0x400 + (n \times 0x8)$

Destination address where content of the key value registers (KEYSLOT.KEYn.VALUE[0-3]) will be pushed by KMU. Note that this address MUST match that of a peripherals APB mapped write-only key registers, else the KMU can push this key value into an address range which the CPU can potentially read!

A A A A A A A A A A	
ID A A A A A A A A A A A A A A A A A A A	1 1 1 1 1
	AAAAA
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	4 3 2 1 0





4.6.1.9 KEYSLOT.CONFIG[n].PERM (n=0..127)

Address offset: $0x404 + (n \times 0x8)$

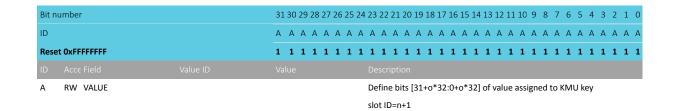
Define permissions for the key slot with ID=n+1. Bits 0-15 and 16-31 can only be written once.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW WRITE			Write permission for key slot
		Disabled	0	Disable write to the key value registers
		Enabled	1	Enable write to the key value registers
В	RW READ			Read permission for key slot
		Disabled	0	Disable read from key value registers
		Enabled	1	Enable read from key value registers
С	RW PUSH			Push permission for key slot
		Disabled	0	Disable pushing of key value registers over secure APB, but
				can be read if field READ is Enabled
		Enabled	1	Enable pushing of key value registers over secure APB.
				Register KEYSLOT.CONFIGn.DEST must contain a valid
				destination address!
D	RW STATE			Revocation state for the key slot
				Note that it is not possible to undo a key revocation by
				writing the value '1' to this field
		Revoked	0	Key value registers can no longer be read or pushed
		Active	1	Key value registers are readable (if enabled) and can be
				pushed (if enabled)

4.6.1.10 KEYSLOT.KEY[n].VALUE[o] (n=0..127) (o=0..3)

Address offset: $0x800 + (n \times 0x10) + (o \times 0x4)$

Define bits [31+o*32:0+o*32] of value assigned to KMU key slot ID=n+1



4.7 EasyDMA

EasyDMA is a module implemented by some peripherals to gain direct access to Data RAM.

EasyDMA is an AHB bus master similar to CPU and is connected to the AHB multilayer interconnect for direct access to Data RAM. EasyDMA is not able to access flash.

A peripheral can implement multiple EasyDMA instances to provide dedicated channels. For example, for reading and writing of data between the peripheral and RAM. This concept is illustrated in EasyDMA example on page 45.



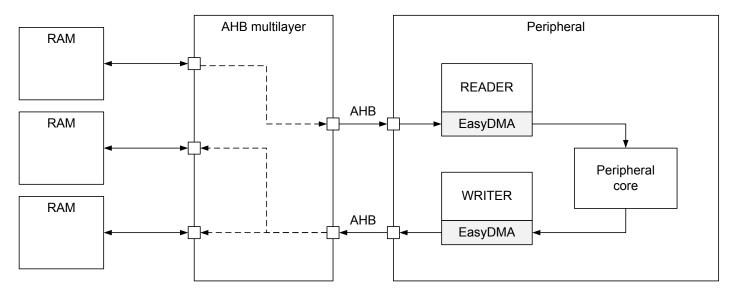


Figure 5: EasyDMA example

An EasyDMA channel is usually implemented like illustrated by the code below, but some variations may occur:

```
READERBUFFER_SIZE 5
WRITERBUFFER_SIZE 6

uint8_t readerBuffer[READERBUFFER_SIZE] __at__ 0x20000000;
uint8_t writerBuffer[WRITERBUFFER_SIZE] __at__ 0x20000005;

// Configuring the READER channel
MYPERIPHERAL->READER.MAXCNT = READERBUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &readerBuffer;

// Configure the WRITER channel
MYPERIPHERAL->WRITER.MAXCNT = WRITEERBUFFER_SIZE;
MYPERIPHERAL->WRITER.PTR = &writerBuffer;
```

This example shows a peripheral called MYPERIPHERAL that implements two EasyDMA channels - one for reading called READER, and one for writing called WRITER. When the peripheral is started, it is assumed that the peripheral will:

- Read 5 bytes from the readerBuffer located in RAM at address 0x20000000.
- Process the data.
- Write no more than 6 bytes back to the writerBuffer located in RAM at address 0x20000005.

The memory layout of these buffers is illustrated in EasyDMA memory layout on page 46.



0x20000000	readerBuffer[0]	readerBuffer[1]	readerBuffer[2]	readerBuffer[3]
0x20000004	readerBuffer[4]	writerBuffer[0]	writerBuffer[1]	writerBuffer[2]
0x20000008	writerBuffer[3]	writerBuffer[4]	writerBuffer[5]	

Figure 6: EasyDMA memory layout

The WRITER.MAXCNT register should not be specified larger than the actual size of the buffer (writerBuffer). Otherwise, the channel would overflow the writerBuffer.

Once an EasyDMA transfer is completed, the AMOUNT register can be read by the CPU to see how many bytes were transferred. For example, CPU can read MYPERIPHERAL->WRITER.AMOUNT register to see how many bytes WRITER wrote to RAM.

4.7.1 EasyDMA array list

EasyDMA is able to operate in a mode called array list.

The array list does not provide a mechanism to explicitly specify where the next item in the list is located. Instead, it assumes that the list is organized as a linear array where items are located one after the other in RAM.

The EasyDMA array list can be implemented by using the data structure ArrayList_type as illustrated in the code example below:

```
#define BUFFER_SIZE 4

typedef struct ArrayList
{
   uint8_t buffer[BUFFER_SIZE];
} ArrayList_type;

ArrayList_type ReaderList[3];

READER.MAXCNT = BUFFER_SIZE;
READER.PTR = &ReaderList;
```

The data structure only includes a buffer with size equal to the size of READER.MAXCNT register. EasyDMA uses the READER.MAXCNT register to determine when the buffer is full.

READER.PTR = &ReaderList

 0x20000000 : ReaderList[0]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

 0x20000004 : ReaderList[1]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

 0x20000008 : ReaderList[2]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

Figure 7: EasyDMA array list



4.8 AHB multilayer interconnect

On the AHB multilayer interconnect, the application CPU and all EasyDMA instances are AHB bus masters while RAM, cache and peripherals are AHB slaves. External MCU subsystems can be seen both as master and slave on the AHB multilayer interconnect.

Multiple AHB masters can access slave resources within the AHB multilayer interconnect as illustrated in Memory on page 20. Access rights to each of the AHB slaves are resolved using the natural priority of the different bus masters in the system.



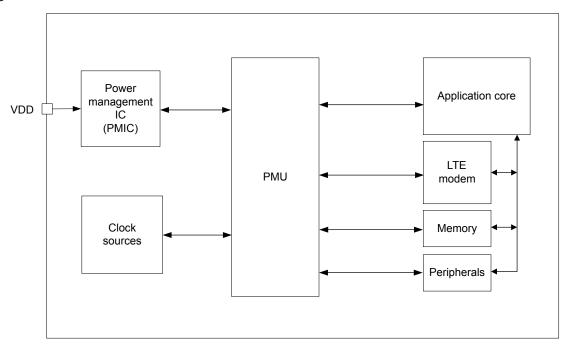
5

Power and clock management

5.1 Functional description

The power and clock management system automatically ensures maximum power efficiency.

The core of the power and clock management is the power management unit (PMU) illustrated in the image below.



The PMU automatically tracks the power and clock resources required by the different components in the system. It then starts/stops and chooses operation modes in supply regulators and clock sources, without user interaction, to achieve the lowest power consumption possible.

5.1.1 Power management

The power management unit (PMU) handles two system-wide power modes - System ON and System OFF.

Internal blocks of the device are automatically powered by the PMU as they are required by the application.

5.1.1.1 System ON mode

System ON is the power mode entered after a power-on reset.

While in System ON, the system can reside in one of two sub modes:

- · Low power
- Constant latency

The low power mode is default after power-on reset.

In low power mode, whenever no application or wireless activity takes place, function blocks like the application CPU, LTE modem and all peripherals are in IDLE state. That particular state is referred to as System ON IDLE. In this state, all function blocks retain their state and configuration, so they are ready to become active once configured by the CPU.



If any application or modem activity occurs, the system leaves the System ON IDLE state. Once a given activity in a function block is completed, the system automatically returns to IDLE, retaining its configuration.

As long as the system resides in low power mode, the PMU ensures that the appropriate regulators and clock sources are started or stopped based on the needs of the function blocks active at any given time.

This automatic power management can be overridden by switching to constant latency mode. In this mode, the CPU wakeup latency and the PPI task response are constant and kept at a minimum. This is secured by keeping a set of base resources that are always enabled. The advantage of having a constant and predictable latency will be at the cost of having significantly increased power consumption compared to the low power mode. The constant latency mode is enabled by triggering the CONSTLAT task (TASKS_CONSTLAT on page 59).

While the system is in constant latency mode, the low power mode can be enabled by triggering LOWPWR task (TASKS_LOWPWR on page 59).

To reduce power consumption while in System ON IDLE, RAM blocks can be turned off in System ON mode while enabling the retention of these RAM blocks in RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 55. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

5.1.1.2 System OFF mode

System OFF is the deepest power saving mode the system can enter.

In this mode, the core system functionality is powered down and ongoing tasks terminated, and only the reset and the wakeup functions are available and responsive.

The device is put into System OFF mode using the REGULATORS register interface. When in System OFF mode, one of the following signals/actions will wake up the device:

- 1. DETECT signal, generated by the GPIO peripheral
- 2. RESET
- 3. start of debug session

When the device wakes up from System OFF mode, a system reset is performed.

One or more RAM blocks can be retained in System OFF mode depending on the settings in the RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 55. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

Before entering System OFF mode, the user must make sure that all on-going EasyDMA transactions have completed. This can be accomplished by making sure that EasyDMA enabled peripherals have stopped and END events from them received. The LTE modem also needs to be stopped, by issuing a command through the modem API, before entering System OFF mode. Once the command is issued, one should wait for the modem to respond that it actually has stopped, as there may be a delay until modem is disconnected from the network.

5.1.1.2.1 Emulated System OFF mode

If the device is in debug interface mode, System OFF will be emulated to secure that all required resources needed for debugging are available during System OFF.

See Overview on page 365 chapter for more information. Required resources needed for debugging include the following key components: Overview on page 365, CLOCK — Clock control on page 64, POWER — Power control on page 58, NVMC — Non-volatile memory controller on page 28, CPU on page 19, flash, and RAM. Since the CPU is kept on in emulated System OFF mode, it is required to add an infinite loop directly after entering System OFF, to prevent the CPU from executing code that normally should not be executed.



5.1.2 Power supply

The device has a single main power supply VDD, and the internal components are powered by integrated voltage regulators. The PMU manages these regulators automatically, no voltage regulator control needs to be included in application firmware.

5.1.2.1 General purpose I/O supply

The input/output (I/O) drivers of P0.00 - P0.31 pins are supplied independently of VDD through VDD_GPIO. This enables easy match to signal voltage levels in the printed circuit board design.

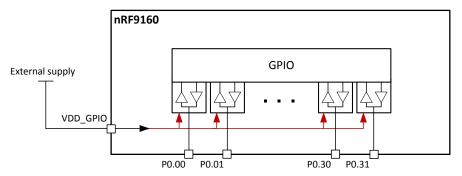


Figure 8: GPIO supply input (VDD_GPIO)

The I/Os are supplied via VDD_GPIO pin as shown in figure above. VDD_GPIO pin supports voltage levels within range given in table Recommended operating conditions on page 386

5.1.3 Power supply monitoring

Power monitor solutions are available in the device, in order to survey the VDD (battery voltage).

5.1.3.1 Power supply supervisor

The power supply supervisor enables monitoring of the connected power supply.

Two functionalities are implemented:

- Power-on reset (POR): Generates a reset when the supply is applied to the device, and ensures that the device starts up in a known state
- Brownout reset (BOR): Generates a reset when the supply drops below the minimum voltage required for safe operations

Two BOR levels are used:

- V_{BOROFF}, used in System OFF
- V_{BORON}, used in System ON

The power supply supervisor is illustrated in the image below.



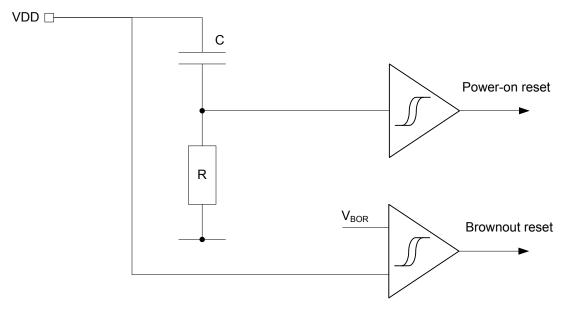


Figure 9: Power supply supervisor

5.1.3.2 Battery monitoring on VDD

A battery voltage (VDD) monitoring capability is provided via a modem API

Note: For details regarding the modem API, please refer to *nRF Connect SDK* document and *nRF91* AT Commands, Command Reference Guide document.

5.1.3.3 Electrical specification

5.1.4 Clock management

The clock control system can source the system clocks from a range of high and low frequency oscillators, and distribute them to modules based upon a module's individual requirements. Clock generation and distribution is handled automatically by PMU to optimize current consumption.

Listed here are the available clock signal sources:

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)
- 32.768 kHz RC oscillator (LFRC)
- 32.768 kHz high accuracy oscillator (LFXO)

The clock and oscillator resources are configured and controlled via the CLOCK peripheral as illustrated below.



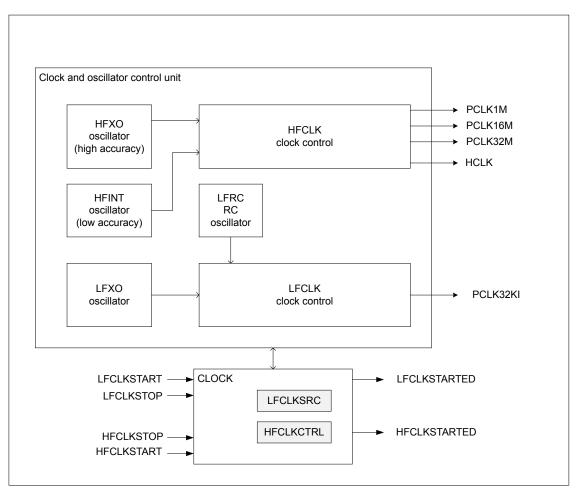


Figure 10: Clock and oscillator setup

5.1.4.1 HFCLK clock controller

The HFCLK clock controller provides several clocks in the system.

These are as follows:

- HCLK: 64 MHz CPU clock
- PCLK1M: 1 MHz peripheral clock
- PCLK16M: 16 MHz peripheral clock
- PCLK32M: 32 MHz peripheral clock

The HFCLK controller uses the following high frequency clock (HFCLK) sources:

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)

For illustration, see Clock and oscillator setup on page 52.

The HFCLK controller will automatically provide the clock(s) requested by the system. If the system does not request any clocks from the HFCLK controller, the controller will switch off all its clock sources and enter a power saving mode.

The HFINT source will be used when HFCLK is requested and HFXO has not been started.

The HFXO is started by triggering the HFCLKSTART task and stopped using the HFCLKSTOP task. A HFCLKSTARTED event will be generated when the HFXO has started and its frequency is stable.

5.1.4.2 LFCLK clock controller

The system supports several low frequency clock sources.



As illustrated in Clock and oscillator setup on page 52, the system supports the following low frequency clock sources:

- LFRC: 32.768 kHz RC oscillator
- LFXO: 32.768 kHz high accuracy oscillator

The LFCLK clock controller and all LFCLK clock sources are always switched off when in System OFF mode.

The LFCLK clock is started by first selecting the preferred clock source in the LFCLKSRC on page 71 register and then triggering the LFCLKSTART task. LFXO is recommended as the LFCLK clock source.

Note: The LTE modem requires using LFXO as the LFCLK source.

Switching between LFCLK clock sources can be done without stopping the LFCLK clock. A LFCLK clock source which is running prior to triggering the LFCLKSTART task will continue to run until the selected clock source has been available. After that the clock sources will be switched. Switching between clock sources will never introduce a glitch but it will stretch a clock pulse by 0.5 to 1.0 clock cycle (i.e. will delay rising edge by 0.5 to 1.0 clock cycle).

Note: If the watchdog timer (WDT) is running, the default LFCLK clock source (LFRC - see LFCLKSRC on page 71) is started automatically (LFCLKSTART task doesn't have to be triggered).

A LFCLKSTARTED event will be generated when the selected LFCLK clock source has started.

A LFCLKSTOP task will stop global requesting of the LFCLK clock. However, if any system component (e.g. WDT, modem) requires the LFCLK, the clock won't be stopped. The LFCLKSTOP task should only be triggered after the STATE field in the LFCLKSTAT register indicates a LFCLK running-state.

5.1.4.2.1 32.768 kHz RC oscillator (LFRC)

The default source of the low frequency clock (LFCLK) is the 32.768 kHz RC oscillator (LFRC).

The LFRC frequency will be affected by variation in temperature.

5.1.4.3 Electrical specification

5.1.4.3.1 64 MHz internal oscillator (HFINT)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFINT}	Nominal output frequency		64		MHz
f _{TOL_HFINT}	Frequency tolerance		+-1	+-5	%
t _{START HEINT}	Startup time		3.2		μs

5.1.4.3.2 64 MHz high accuracy oscillator (HFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFXO}	Nominal output frequency		64		MHz
f_{TOL_HFXO}	Frequency tolerance		+-1		ppm
t _{START HFXO}	Startup time		TBA		ms

5.1.4.3.3 32.768 kHz high accuracy oscillator (LFXO)



Symbol	Description	Min.	Тур.	Max.	Units
f_{NOM_LFXO}	Frequency		32.768		kHz
f_{TOL_LFXO}	Frequency tolerance		+-20		ppm
t _{START_LFXO}	Startup time		TBA		S

5.1.4.3.4 32.768 kHz RC oscillator (LFRC)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFRC}	Nominal frequency		32.768		kHz
f _{TOL_LFRC}	Frequency tolerance		+-2		%
t _{START_LFRC}	Startup time		600		μs

5.1.5 Reset

There are multiple reset sources that may trigger a reset of the system. After a reset the CPU can query the RESETREAS (reset reason register) to find out which source generated the reset.

5.1.5.1 Power-on reset

The power-on reset generator initializes the system at power-on. The system is held in reset state until the supply has reached the minimum operating voltage and the internal voltage regulators have started.

5.1.5.2 Pin reset

A pin reset is generated when the physical reset pin (nRESET) on the device is pulled low.

To ensure that reset is issued correctly, the reset pin should be held low for time given in .

nRESET pin has an always-on internal pull-up resistor connected to VDD. The value of the pull-up resistor is given in .

5.1.5.3 Wakeup from System OFF mode reset

The device is reset when it wakes up from System OFF mode.

The Debug access port is not reset following a wake up from System OFF mode if the device is in debug interface mode, see Overview on page 365 chapter for more information.

5.1.5.4 Soft reset

A soft reset is generated when the SYSRESETREQ bit of the application interrupt and reset control register (AIRCR register) in the ARM $^{\otimes}$ core is set.

5.1.5.5 Watchdog reset

A watchdog reset is generated when the watchdog timer (WDT) times out.

See WDT — Watchdog timer on page 352 chapter for more information.

5.1.5.6 Brownout reset

The brownout reset generator puts the system in reset state if the supply voltage drops below the brownout reset threshold.

5.1.5.7 Retained registers

A retained register is a register that will retain its value in System OFF mode, and through a reset depending on reset source. See individual peripheral chapters for information of which registers are retained for the different peripherals.



5.1.5.8 Reset behavior

Reset behavior depends on the reset source.

The reset behavior is summarized in the table below.

Reset source	Reset target	Reset target						
	СРИ	Modem	Debug ²	SWJ-DP	Not retain	ned Retained	WDT	RESETREAS
					RAM ³	RAM ³		
CPU lockup ⁴	х	х						
Soft reset	х	х						
Wakeup from System OFF	х	x	x ⁵		x		x	
mode reset								
Watchdog reset ⁶	х	x	Х		x		х	
Pin reset	х	x	х	x	x		x	
Brownout reset	х	x	х	x	x	х	x	Х
Power-on reset	x	x	x	х	х	X	х	

Table 16: Reset behavior for the main components

Note: The RAM is never reset but its content may be corrupted after reset in the cases given in the table above.

Reset source	Reset target					
	Regular peripheral	GPIO, SPU	NVMC	NVMC	REGULATORS,	POWER.GPREGRET
	registers		WAITSTATENUM	1 IFCREADDELAY	OSCILLATORS	
CPU lockup ⁴	х	x	x			
Soft reset	х	х	х			
Wakeup from System OFF mode reset	х		х			
Watchdog reset ⁶	х	х	х		х	
Pin reset	х	х	х		х	
Brownout reset	х	х	х	х	х	х
Power-on reset	х	x	x	x	х	х

Table 17: Reset behavior for the retained registers

5.1.5.9 Electrical specification

5.1.5.9.1 Pin reset

Symbol	Description	Min.	Тур.	Max.	Units
t _{HOLDRESET}	Hold time for reset pin when doing a pin reset				μs
R _{PULL-UP}	Value of the internal pull-up resistor	**			kΩ

² All debug components excluding SWJ-DP. See Overview on page 365 chapter for more information about the different debug components in the system.



RAM can be configured to be retained using registers in VMC — Volatile memory controller on page 26

⁴ Reset from CPU lockup is disabled if the device is in debug interface mode. CPU lockup is not possible in System OFF.

The debug components will not be reset if the device is in debug interface mode.

⁶ Watchdog reset is not available in System OFF.

5.2 Current consumption

As the system is being constantly tuned by the PMU described in Functional description on page 48, estimating the current consumption of an application can be challenging if the designer is not able to perform measurements directly on the hardware. To facilitate the estimation process, a set of current consumption scenarios are provided to show the typical current drawn from the VDD supply.

Each scenario specifies a set of operations and conditions applying to the given scenario. Current consumption scenarios, common conditions on page 56 shows a set of common conditions used in all scenarios, unless otherwise is stated in the description of a given scenario. Current consumption scenarios, common conditions on page 56 describes the conditions used for the modem current consumption specifications. All scenarios are listed in Electrical specification on page 56

Condition	Value
Supply	3.7 V
Temperature	25 °C
CPU	WFI (wait for interrupt)/WFE (wait for event) sleep
Peripherals	All idle
Clock	Not running
RAM	No retention
Cache enabled	Yes

Table 18: Current consumption scenarios, common conditions

Condition
Cat-M1 HD FDD mode
Ideal channel, no errors in DL/UL communication
Network response times at minimum
UICC current consumption excluded
Output power at antenna port, single-ended 50 Ω

Table 19: Current consumption scenarios, common conditions

5.2.1 Electrical specification

5.2.1.1 Sleep

Symbol	Description	Min.	Тур.	Max.	Units
I _{MCUOFF0}	MCU off, modem off, no RAM retention, wake on GPIO and		1.4		μΑ
	reset				
I _{MCUON0}	MCU on IDLE, modem off, RTC off		1.8		μΑ
I _{MCUON1}	MCU on IDLE, modem off, RTC on		2.35		μΑ



5.2.1.2 Application CPU active current consumption

Symbol	Description	Min.	Тур.	Max.	Units
I _{CPU0_FLASH}	CPU running CoreMark @64 MHz from flash, clock = HFXO,		2.88		mA
	cache enabled				
I _{COREMARK_PER_MA_F}	L/ CoreMark per mA, executing from flash, CoreMark=243		84		Corel
					mA
I _{CPU0_RAM}	CPU running CoreMark @64 MHz from RAM, clock = HFXO,		2.32		mA
	cache enabled				
I _{COREMARK_PER_MA_R}	A CoreMark per mA, executing from RAM, CoreMark=235		101		Corel
					mA

5.2.1.3 I2S

Symbol	Description	Min.	Тур.	Max.	Units
I _{12S0}	I2S transferring data @ 2 x 16 bit x 16 kHz		TBA		μΑ
	(CONFIG.MCKFREQ = 32MDIV63, CONFIG.RATIO = 32X)				

5.2.1.4 PDM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PDM}	PDM receiving and processing data @ 1 Msps		TBA		μΑ

5.2.1.5 PWM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PWM0}	PWM running @ 125 kHz, fixed duty cycle		TBA		μΑ
I _{PWM1}	PWM running @ 16 MHz, fixed duty cycle		1160.77		μΑ

5.2.1.6 SAADC

Symbol	Description	Min.	Тур.	Max.	Units
I _{SAADC}	SAADC sampling @ 16 ksps, acquisition time = 20 μ s		302.34		μΑ

5.2.1.7 TIMER

5.2.1.8 SPIM

5.2.1.9 SPIS

Symbol	Description	Min.	Тур.	Max.	Units
Ispiso	SPIS transferring data @ 2 Mbps		TBA		μА



5.2.1.10 TWIM

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIM0}	TWIM running @ 100 kbps		TBA		μΑ

5.2.1.11 TWIS

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIS,RUN0}	TWIS transferring data @ 100 kbps		TBA		μΑ
I _{TWIS1,RUN1}	TWIS transferring data @ 400 kbps,		TBA		μΑ

5.2.1.12 UARTE

Symbol	Description	Min.	Тур.	Max.	Units
I _{UARTE}	UARTE transferring data @ 1200 bps		TBA		μΑ
I _{UARTE}	UARTE transferring data @ 115200 bps		TBA		μΑ

5.2.1.13 WDT

Symbol	Description	Min.	Тур.	Max.	Units
I _{WDT}	WDT started		3.95		μΑ

5.2.1.14 Modem current consumption

Symbol	Description	B13	B20	В3	B4	Units		
Modem sleep current consumption								
I _{PSM}	PSM floor current	2.7	2.7	2.7	2.7	μΑ		
Radio resource control (RRC) mode								
I _{EDRX}	eDRX average current, 81.92 s	27	27	27	27	μΑ		
I _{IDRX}	Idle DRX average current, 2.56 s	239	239	239	239	μΑ		
I _{RMC_0DBM}	Uplink 180 kbit/s, Pout 0 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	45	45	45	45	mA		
I _{RMC_10DBM}	Uplink 180 kbit/s, Pout 10 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	50	50	55	55	mA		
I _{RMC_23DBM}	Uplink 180 kbit/s, Pout 23 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	105	110	140	140	mA		
Modem active current cor	nsumption							
I _{TX_0DBM}	TX subframe, Pout 0 dBm	60	60	65	65	mA		
I _{TX_10DBM}	TX subframe, Pout 10 dBm	80	85	95	90	mA		
I _{TX_23DBM}	TX subframe, Pout 23 dBm	255	275	380	365	mA		
I _{TX90DBM}	TX subframe, Pout -90 dBm	45	45	45	45	mA		
I _{TX_TRANSIENT}	TX transient	40	45	50	50	mA/μs		
Modem peak current cons	sumption							
I _{TX_PEAK}	TX subframe, Pout >21 dBm, Ant VSWR3	335	360	455	450	mA		
I _{TX_PEAK}	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.5 V, Temp 85 °C	350	380	460	450	mA		
I _{TX_PEAK}	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.0 V, Temp 85 °C	410	445	535	525	mA		

5.3 Register description

5.3.1 POWER — Power control

The POWER module provides an interface to tasks, events, interrupt and reset related configuration settings of the power management unit.



Note: Registers INTEN on page 62, INTENSET on page 62, and INTENCLR on page 63 are the same registers (at the same address) as corresponding registers in CLOCK — Clock control on page 64.

5.3.1.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50005000		POWER: S	US		Power control	
0x40005000	POWER OUSSIDE POWER : NS		03	NA	Power control	

Table 20: Instances

Register	Offset	Security	Description
TASKS_CONSTLAT	0x78		Enable constant latency mode.
TASKS_LOWPWR	0x7C		Enable low power mode (variable latency)
SUBSCRIBE_CONSTLAT	0xF8		Subscribe configuration for task CONSTLAT
SUBSCRIBE_LOWPWR	0xFC		Subscribe configuration for task LOWPWR
EVENTS_POFWARN	0x108		Power failure warning
EVENTS_SLEEPENTER	0x114		CPU entered WFI/WFE sleep
EVENTS_SLEEPEXIT	0x118		CPU exited WFI/WFE sleep
PUBLISH_POFWARN	0x188		Publish configuration for event POFWARN
PUBLISH_SLEEPENTER	0x194		Publish configuration for event SLEEPENTER
PUBLISH_SLEEPEXIT	0x198		Publish configuration for event SLEEPEXIT
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RESETREAS	0x400		Reset reason
POWERSTATUS	0x440		Modem domain power status
GPREGRET[0]	0x51C		General purpose retention register
GPREGRET[1]	0x520		General purpose retention register

Table 21: Register overview

5.3.1.1.1 TASKS_CONSTLAT

Address offset: 0x78

Enable constant latency mode.

Bit n	umber		31 30 29 28 27 2	26 25 24	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5	4 3 2	1 0
ID							Α
Rese	et 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0	0 0
ID							
Α	W TASKS_CONSTLAT				Enable constant latency mode.		
		Trigger	1		Trigger task		

5.3.1.1.2 TASKS_LOWPWR

Address offset: 0x7C

Enable low power mode (variable latency)



Bit n	umk	per		313	30 29	28	3 27	26	25	24	23 2	2 2	1 2	0 19	9 18	8 17	' 16	15	14	13 1	12 1	1 10	9	8	7	6	5 4	3	2	1 0
ID																														А
Rese	t Ox	00000000		0	0 0	0	0	0	0	0	0 () (0	0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0 (0	0	0 0
ID											Desc																			
Α	W	TASKS_LOWPWR									Enal	ble	lov	v po	we	r m	ode	e (v	aria	ble	late	ncy))							
			Trigger	1							Trigg	ger	tas	sk																

5.3.1.1.3 SUBSCRIBE_CONSTLAT

Address offset: 0xF8

Subscribe configuration for task CONSTLAT

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5	4 3 2 1 0
ID			В		AAAA
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0
ID					
Α	RW CHIDX		[150]	Channel that task CONSTLAT will subscribe to	
В	RW EN				
		Disabled	0	Disable subscription	
		Enabled	1	Enable subscription	

5.3.1.1.4 SUBSCRIBE_LOWPWR

Address offset: 0xFC

Subscribe configuration for task LOWPWR

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task LOWPWR will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

5.3.1.1.5 EVENTS_POFWARN

Address offset: 0x108 Power failure warning

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_POFWARN			Power failure warning
	NotGenerated	0	Event not generated
	Generated	1	Event generated

5.3.1.1.6 EVENTS_SLEEPENTER

Address offset: 0x114

CPU entered WFI/WFE sleep



Bit numbe	r		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Reset 0x00	0000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce				
A RW	EVENTS_SLEEPENTER			CPU entered WFI/WFE sleep
		NotGenerated	0	Event not generated
		Generated	1	Event generated

5.3.1.1.7 EVENTS_SLEEPEXIT

Address offset: 0x118

CPU exited WFI/WFE sleep

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_SLEEPEXIT			CPU exited WFI/WFE sleep
		NotGenerated	0	Event not generated
		Generated	1	Event generated

5.3.1.1.8 PUBLISH_POFWARN

Address offset: 0x188

Publish configuration for event POFWARN

Bit n	Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event POFWARN will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

5.3.1.1.9 PUBLISH_SLEEPENTER

Address offset: 0x194

Publish configuration for event SLEEPENTER

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event SLEEPENTER will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

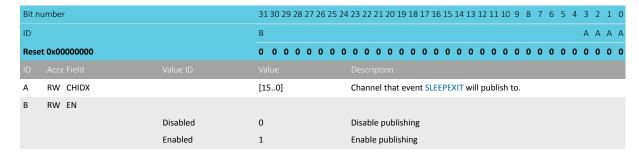
5.3.1.1.10 PUBLISH_SLEEPEXIT

Address offset: 0x198





Publish configuration for event SLEEPEXIT



5.3.1.1.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW POFWARN			Enable or disable interrupt for event POFWARN
		Disabled	0	Disable
		Enabled	1	Enable
С	RW SLEEPENTER			Enable or disable interrupt for event SLEEPENTER
		Disabled	0	Disable
		Enabled	1	Enable
D	RW SLEEPEXIT			Enable or disable interrupt for event SLEEPEXIT
		Disabled	0	Disable
		Enabled	1	Enable

5.3.1.1.12 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW POFWARN			Write '1' to enable interrupt for event POFWARN
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW SLEEPENTER			Write '1' to enable interrupt for event SLEEPENTER
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW SLEEPEXIT			Write '1' to enable interrupt for event SLEEPEXIT
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



5.3.1.1.13 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW POFWARN			Write '1' to disable interrupt for event POFWARN
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW SLEEPENTER			Write '1' to disable interrupt for event SLEEPENTER
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW SLEEPEXIT			Write '1' to disable interrupt for event SLEEPEXIT
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

5.3.1.1.14 RESETREAS

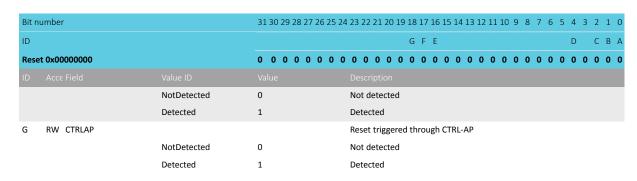
Address offset: 0x400

Reset reason

Unless cleared, the RESETREAS register will be cumulative. A field is cleared by writing '1' to it. If none of the reset sources are flagged, this indicates that the chip was reset from the on-chip reset generator, which will indicate a power-on reset or a brownout reset.

Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				G F E D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW RESETPIN			Reset from pin reset detected
		NotDetected	0	Not detected
		Detected	1	Detected
В	RW DOG			Reset from global watchdog detected
		NotDetected	0	Not detected
		Detected	1	Detected
С	RW OFF			Reset due to wakeup from System OFF mode, when wakeup
				is triggered by DETECT signal from GPIO
		NotDetected	0	Not detected
		Detected	1	Detected
D	RW DIF			Reset due to wakeup from System OFF mode, when wakeup
				is triggered by entering debug interface mode
		NotDetected	0	Not detected
		Detected	1	Detected
Е	RW SREQ			Reset from AIRCR.SYSRESETREQ detected
		NotDetected	0	Not detected
		Detected	1	Detected
F	RW LOCKUP			Reset from CPU lock-up detected

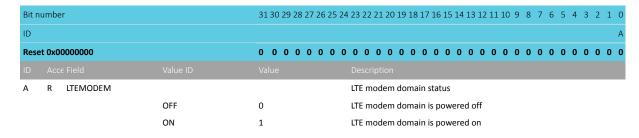




5.3.1.1.15 POWERSTATUS

Address offset: 0x440

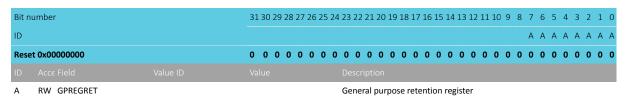
Modem domain power status



5.3.1.1.16 GPREGRET[n] (n=0..1)

Address offset: $0x51C + (n \times 0x4)$

General purpose retention register



This register is a retained register

5.3.2 CLOCK — Clock control

The CLOCK module provides one of the interfaces to power and clock management configuration settings.

Through CLOCK module it is able to configure the following:

- LFCLK clock source setup
- LFCLK and HFCLK status
- Tasks and events
- Interrupts
- Reset

Note: Registers INTEN on page 68, INTENSET on page 69, and INTENCLR on page 69 are the same registers (at the same address) as corresponding registers in POWER — Power control on page 58.



5.3.2.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50005000	CLOCK	CLOCK : S	US	NA	Clock control	
0x40005000	CLUCK	CLOCK : NS	U3	IVA	CIOCK COILLIOI	

Table 22: Instances

Register	Offset	Security	Description
TASKS_HFCLKSTART	0x000		Start HFCLK source
TASKS_HFCLKSTOP	0x004		Stop HFCLK source
TASKS_LFCLKSTART	0x008		Start LFCLK source
TASKS_LFCLKSTOP	0x00C		Stop LFCLK source
SUBSCRIBE_HFCLKSTART	0x080		Subscribe configuration for task HFCLKSTART
SUBSCRIBE_HFCLKSTOP	0x084		Subscribe configuration for task HFCLKSTOP
SUBSCRIBE_LFCLKSTART	0x088		Subscribe configuration for task LFCLKSTART
SUBSCRIBE_LFCLKSTOP	0x08C		Subscribe configuration for task LFCLKSTOP
EVENTS_HFCLKSTARTED	0x100		HFCLK oscillator started
EVENTS_LFCLKSTARTED	0x104		LFCLK started
PUBLISH_HFCLKSTARTED	0x180		Publish configuration for event HFCLKSTARTED
PUBLISH_LFCLKSTARTED	0x184		Publish configuration for event LFCLKSTARTED
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
HFCLKRUN	0x408		Status indicating that HFCLKSTART task has been triggered
HFCLKSTAT	0x40C		The register shows if HFXO has been requested by triggering HFCLKSTART task and
			if it has been started (STATE)
LFCLKRUN	0x414		Status indicating that LFCLKSTART task has been triggered
LFCLKSTAT	0x418		The register shows which LFCLK source has been requested (SRC) when triggering
			LFCLKSTART task and if the source has been started (STATE)
LFCLKSRCCOPY	0x41C		Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered
LFCLKSRC	0x518		Clock source for the LFCLK. LFCLKSTART task starts a clock source selected
			with this register.

Table 23: Register overview

5.3.2.1.1 TASKS_HFCLKSTART

Address offset: 0x000 Start HFCLK source

Bit n	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_HFCLKSTART			Start HFCLK source
		Trigger	1	Trigger task

5.3.2.1.2 TASKS_HFCLKSTOP

Address offset: 0x004 Stop HFCLK source



Bit nu	umb	er		313	80 29	28	27	26 2	25 2	24 :	23 :	22 2	21	20 1	9 1	8 17	7 16	5 15	14	13 1	2 1	1 10	9	8	7	6	5	4	3 2	1	0
ID																															Α
Rese	t OxC	00000000		0	0 0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0	0	0
ID											Des																				
Α	W	TASKS_HFCLKSTOP								:	Sto	рΗ	IFC	LK s	our	ce															
			Trigger	1							Trig	ger	r ta	sk																	

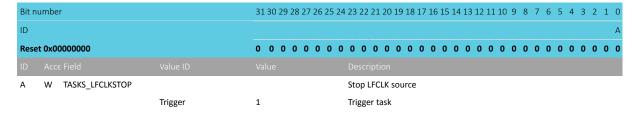
5.3.2.1.3 TASKS_LFCLKSTART

Address offset: 0x008 Start LFCLK source

Bit n	um	nber		31	30 2	29 2	8 27	26	25 24	12	3 22	21	20 1	19 1	8 17	16	15 :	14 1	3 12	11	10 9	8	7	6	5	4 3	2	1 0
ID																												Α
Rese	et O	x00000000		0	0	0 (0 0	0	0 0	(0	0	0	0 0	0	0	0	0 0	0	0	0 0	0	0	0	0	0 (0	0 0
ID																												
Α	٧	V TASKS_LFCLKSTART								S	tart	LFC	LK s	our	ce													
			Trigger	1						Т	rigge	er ta	ask															

5.3.2.1.4 TASKS_LFCLKSTOP

Address offset: 0x00C Stop LFCLK source



5.3.2.1.5 SUBSCRIBE_HFCLKSTART

Address offset: 0x080

Subscribe configuration for task HFCLKSTART

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task HFCLKSTART will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

5.3.2.1.6 SUBSCRIBE_HFCLKSTOP

Address offset: 0x084

Subscribe configuration for task HFCLKSTOP



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task HFCLKSTOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

5.3.2.1.7 SUBSCRIBE_LFCLKSTART

Address offset: 0x088

Subscribe configuration for task LFCLKSTART

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID			В	A A	A A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID					
Α	RW CHIDX		[150]	Channel that task LFCLKSTART will subscribe to	
В	RW EN				
		Disabled	0	Disable subscription	
		Enabled	1	Enable subscription	

5.3.2.1.8 SUBSCRIBE_LFCLKSTOP

Address offset: 0x08C

Subscribe configuration for task LFCLKSTOP

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task LFCLKSTOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

5.3.2.1.9 EVENTS_HFCLKSTARTED

Address offset: 0x100

HFCLK oscillator started

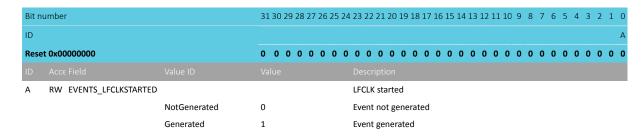
Bit n	Bit number				29 2	8 2	7 2	6 2	5 2	4 23	3 22	2 2:	1 20	19	18	17	16	15	14	13	12 :	l1 1	0 9	8	7	6	5	4	3	2	1 0
ID																															Α
Rese	Reset 0x00000000			0	0	0 (0	0) (0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0
ID																															
Α	RW EVENTS_HFCLKSTARTED	1								Н	FCL	LK c	scil	lato	or s	tart	ed														
		NotGenerated	0							E٧	/en	it n	ot g	ene	erat	ed															
		Generated	1							E۷	/en	t ge	ene	rate	ed																



5.3.2.1.10 EVENTS_LFCLKSTARTED

Address offset: 0x104

LFCLK started



5.3.2.1.11 PUBLISH_HFCLKSTARTED

Address offset: 0x180

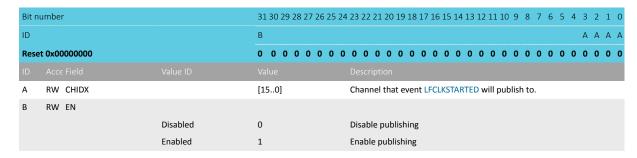
Publish configuration for event HFCLKSTARTED

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event HFCLKSTARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

5.3.2.1.12 PUBLISH_LFCLKSTARTED

Address offset: 0x184

Publish configuration for event LFCLKSTARTED



5.3.2.1.13 INTEN

Address offset: 0x300

Enable or disable interrupt



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW HFCLKSTARTED			Enable or disable interrupt for event HFCLKSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
В	RW LFCLKSTARTED			Enable or disable interrupt for event LFCLKSTARTED
		Disabled	0	Disable
		Enabled	1	Enable

5.3.2.1.14 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	umber		31 30 29 28 27 26	5 25 2	4 23 2	2 21	20 1	9 18	3 17 :	16 1	L5 1	4 13	12	11 1	0 9	8	7	6	5	4 3	2	1	0
ID																						В	Α
Rese	et 0x00000000		0 0 0 0 0 0	0 0	0 0	0	0 (0 0	0	0 (0 0	0	0	0 (0	0	0	0	0	0 (0	0	0
ID																							
Α	RW HFCLKSTARTED				Writ	e '1'	to e	nab	le int	erru	upt 1	for e	ven	t HF	CLK	STA	RTE	D					
		Set	1		Enab	ole																	
		Disabled	0		Read	d: Di	sable	d															
		Enabled	1		Read	d: En	nable	d															
В	RW LFCLKSTARTED				Writ	e '1'	to e	nab	le int	erru	upt 1	for e	ven	t LF	CLKS	TAF	RTE	D					
		Set	1		Enab	ole																	
		Disabled	0		Read	d: Di	sable	ed															
		Enabled	1		Read	d: En	nable	d															

5.3.2.1.15 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number	31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		B A
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW HFCLKSTARTED		Write '1' to disable interrupt for event HFCLKSTARTED
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled
B RW LFCLKSTARTED		Write '1' to disable interrupt for event LFCLKSTARTED
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled

5.3.2.1.16 INTPEND

Address offset: 0x30C Pending interrupts

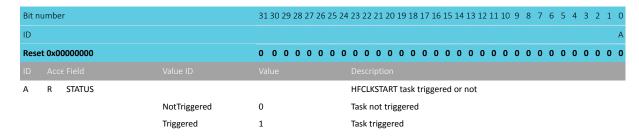


Dit			24 20 20 20 27 26 25 2	M 22 22 21 20 10 10 17 16 15 14 12 12 11 10 0 0 7 6 F A 2 2 1 0
BIT N	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R HFCLKSTARTED			Read pending status of interrupt for event HFCLKSTARTED
		NotPending	0	Read: Not pending
		Pending	1	Read: Pending
В	R LFCLKSTARTED			Read pending status of interrupt for event LFCLKSTARTED
		NotPending	0	Read: Not pending
		Pending	1	Read: Pending

5.3.2.1.17 HFCLKRUN

Address offset: 0x408

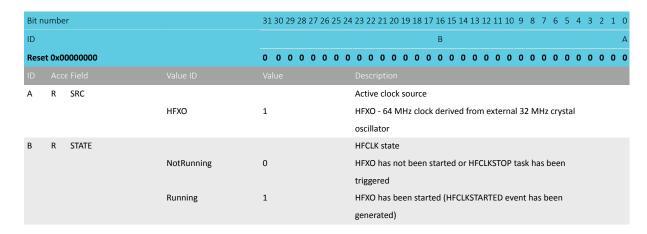
Status indicating that HFCLKSTART task has been triggered



5.3.2.1.18 HFCLKSTAT

Address offset: 0x40C

The register shows if HFXO has been requested by triggering HFCLKSTART task and if it has been started (STATE)

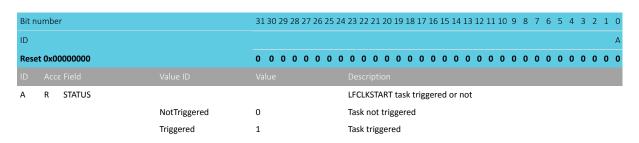


5.3.2.1.19 LFCLKRUN

Address offset: 0x414

Status indicating that LFCLKSTART task has been triggered





5.3.2.1.20 LFCLKSTAT

Address offset: 0x418

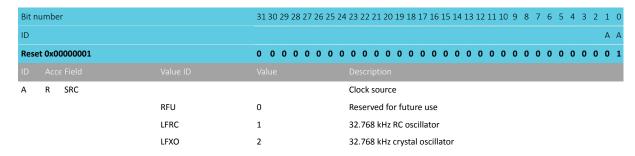
The register shows which LFCLK source has been requested (SRC) when triggering LFCLKSTART task and if the source has been started (STATE)

Bit nu	ımber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				B A A
Reset	0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	R SRC			Active clock source
		RFU	0	Reserved for future use
		LFRC	1	32.768 kHz RC oscillator
		LFXO	2	32.768 kHz crystal oscillator
В	R STATE			LFCLK state
		NotRunning	0	Requested LFCLK source has not been started or LFCLKSTOP
				task has been triggered
		Running	1	Requested LFCLK source has been started (LFCLKSTARTED
				event has been generated)

5.3.2.1.21 LFCLKSRCCOPY

Address offset: 0x41C

Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered

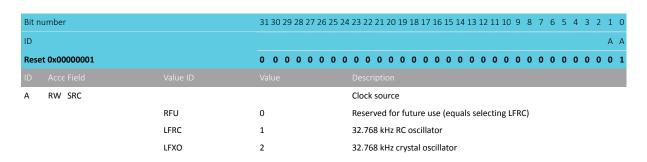


5.3.2.1.22 LFCLKSRC

Address offset: 0x518

Clock source for the LFCLK. LFCLKSTART task starts a clock source selected with this register.





5.3.3 REGULATORS — Voltage regulators control

The REGULATORS module provides an interface to certain configuration settings of on-chip voltage regulators.

5.3.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
		REGULATORS :				
0x50004000	REGULATORS	S		NA	Degulator configuration	
0x40004000		REGULATORS :	US	NA	Regulator configuration	
		NS				

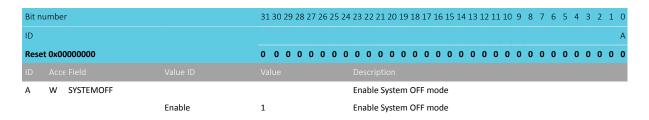
Table 24: Instances

Register	Offset	Security	Description
SYSTEMOFF	0x500		System OFF register
DCDCEN	0x578		Enable DC/DC mode of the main voltage regulator

Table 25: Register overview

5.3.3.1.1 SYSTEMOFF

Address offset: 0x500 System OFF register



5.3.3.1.2 DCDCEN

Address offset: 0x578

Enable DC/DC mode of the main voltage regulator



Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW DCDCEN			Enable DC/DC converter
	Disabled	0	DC/DC mode is disabled
	Enabled	1	DC/DC mode is enabled



6 Peripherals

6.1 CRYPTOCELL — ARM TrustZone CryptoCell 310

ARM[®] TrustZone[®] CryptoCell 310 (CRYPTOCELL) is a security subsystem which provides root of trust (RoT) and cryptographic services for a device.

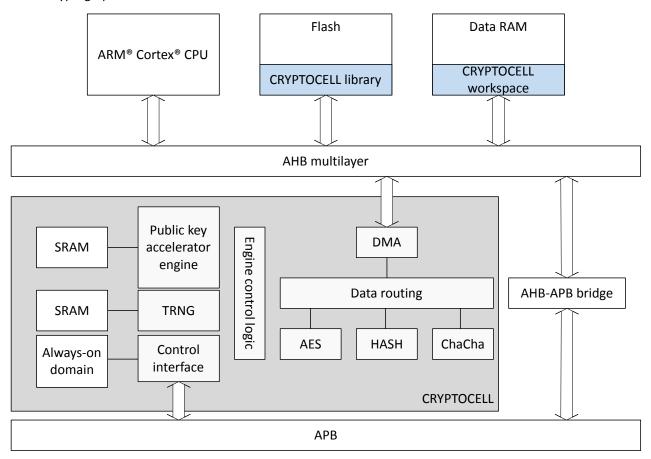


Figure 11: Block diagram for CRYPTOCELL

The following cryptographic features are provided:

- True random number generator (TRNG) compliant with NIST 800-90B⁷, AIS-31, and FIPS 140-2/3⁷.
- Pseudorandom number generator (PRNG) using underlying AES engine compliant with NIST 800-90A
- RSA public key cryptography
 - Up to 2048-bit key size
 - PKCS#1 v2.1/v1.5
 - Optional CRT support
- Elliptic curve cryptography (ECC)
 - NIST FIPS 186-4 recommended curves using pseudorandom parameters, up to 521 bits:
 - Prime field: P-192, P-224, P-256, P-384, P-521
 - SEC 2 recommended curves using pseudorandom parameters, up to 521 bits:



⁷ Not finalized at time of publishing (draft)

- Prime field: secp160r1, secp192r1, secp224r1, secp256r1, secp384r1, secp521r1
- Koblitz curves using fixed parameters, up to 256 bits:
 - Prime field: secp160k1, secp192k1, secp224k1, secp256k1
- Edwards/Montgomery curves:
 - Ed25519, Curve25519
- ECDH/ECDSA support
- Secure remote password protocol (SRP)
 - Up to 3072-bit operations
- · Hashing functions
 - SHA-1, SHA-2 up to 256 bits
 - Keyed-hash message authentication code (HMAC)
- · AES symmetric encryption
 - General purpose AES engine (encrypt/decrypt, sign/verify)
 - 128-bit key size
 - Supported encryption modes: ECB, CBC, CMAC/CBC-MAC, CTR, CCM/CCM*
- ChaCha20/Poly1305 symmetric encryption
 - Supported key size: 128 and 256 bits
 - · Authenticated encryption with associated data (AEAD) mode

6.1.1 Usage

The CRYPTOCELL state is controlled via a register interface. The cryptographic functions of CRYPTOCELL are accessible by using a software library provided in the device SDK, not directly via a register interface.

To enable CRYPTOCELL, use register **ENABLE** on page 77.

6.1.2 Always-on (AO) power domain

The CRYPTOCELL subsystem has an internal always-on (AO) power domain for retaining device secrets when CRYPTOCELL is disabled.

The following information is retained by the AO power domain:

- 4 bits indicating the configured CRYPTOCELL life-cycle state (LCS)
- 1 bit indicating if RTL key K_{PRTL} is available for use
- 128-bit device root key K_{DR}

A reset from any reset source will erase the content in the AO power domain.

6.1.3 Lifecycle state (LCS)

Lifecycle refers to multiple states a device goes through during its lifetime. Two valid lifecycle states are offered for the device - debug and secure.

The CRYPTOCELL subsystem lifecycle state (LCS) is controlled through register. A valid LCS is configured by writing either value <code>Debug</code> or <code>Secure</code> into the LCS field of this register. A correctly configured LCS can be validated by reading back the read-only field LCS_IS_VALID from the abovementioned register. The LCS_IS_VALID field value will change from <code>Invalid</code> to <code>Valid</code> once a valid LCS value has been written.



LCS field value	LCS_IS_VALID field value	Description
Secure	Invalid	Default reset value indicating that LCS has not been configured.
Secure	Valid	$LCS\ set\ to\ secure\ mode, and\ LCS\ is\ valid.\ Registers\ HOST_IOT_KDR[03]\ can\ only\ be\ written\ once\ per\ reset\ cycle.$
		Any additional writes will be ignored.
Debug	Valid	LCS set to debug mode, and LCS is valid. Registers HOST_IOT_KDR[03] can be written multiple times.

Table 26: Lifecycle states

6.1.4 Cryptographic key selection

The CRYPTOCELL subsystem can be instructed to operate on different cryptographic keys.

Through register, the following key types can be selected for cryptographic operations:

- RTL key K_{PRTI}
- Device root key K_{DR}
- · Session key

K_{PRTL} and K_{DR} are configured as part of the CRYPTOCELL initialization process, while session keys are provided by the application through the software library API.

6.1.4.1 RTL key

The ARM[®] TrustZone[®] CryptoCell 310 IP contains one hard-coded RTL key referred to as K_{PRTL}. This key is set to the same value for all devices with the same part code in the hardware design and cannot be changed.

The K_{PRTL} key can be requested for use in cryptographic operations by the CRYPTOCELL, without revealing the key value itself. Access to use of K_{PRTL} in cryptographic operations can be disabled until next reset by writing to register . If a locked K_{PRTL} key is requested for use, a zero vector key will be routed to the AES engine instead.

6.1.4.2 Device root key

The device root key K_{DR} is a 128-bit AES key programmed into the CRYPTOCELL subsystem using firmware. It is retained in the AO power domain until the next reset.

Once configured, it is possible to perform cryptographic operations using the the CRYPTOCELL subsystem where K_{DR} is selected as key input without having access to the key value itself. The K_{DR} key value must be written to registers HOST_IOT_KDR[0..3]. These 4 registers are write-only if LCS is set to debug mode, and write-once if LCS is set to secure mode. The K_{DR} key value is successfully retained when the read-back value of register changes to 1.

6.1.5 Direct memory access (DMA)

The CRYPTOCELL subsystem implements direct memory access (DMA) for accessing memory without CPU intervention.

The following table shows which memory type(s) can be accessed using the DMA:

Any data stored in memory type(s) not accessible by the DMA engine must be copied to SRAM before it can be processed by the CRYPTOCELL subsystem. Maximum DMA transaction size is limited to 2¹⁶-1 bytes.

6.1.6 Standards

ARM® TrustZone® CryptoCell 310 (CRYPTOCELL) supports a number of cryptography standards.



Algorithm family	Identification code	Document title
TRNG	NIST SP 800-90B	Recommendation for the Entropy Sources Used for Random Bit Generation
	AIS-31	A proposal for: Functionality classes and evaluation methodology for physical random number generators
	FIPS 140-2	Security Requirements for Cryptographic Modules
PRNG	NIST SP 800-90A	Recommendation for Random Number Generation Using Deterministic Random Bit Generators
Stream cipher	Chacha	ChaCha, a variant of Salsa20, Daniel J. Bernstein, January 28th 2008
MAC	Poly1305	The Poly1305-AES message-authentication code, Daniel J. Bernstein
		Cryptography in NaCl, Daniel J. Bernstein
Key agreement	SRP	The Secure Remote Password Protocol, Thomas Wu, November 11th 1997
AES	FIPS-197	Advanced Encryption Standard (AES)
	NIST SP 800-38A	Recommendation for Block Cipher Modes of Operation - Methods and Techniques
	NIST SP 800-38B	Recommendation for Block Cipher Modes of Operation: The CMAC Mode for Authentication
	NIST SP 800-38C	Recommendation for Block Cipher Modes of Operation: The CCM Mode for Authentication and Confidentiality
	ISO/IEC 9797-1	AES CBC-MAC per ISO/IEC 9797-1 MAC algorithm 1
	IEEE 802.15.4-2011	IEEE Standard for Local and metropolitan area networks - Part 15.4: Low-Rate Wireless Personal Area
		Networks (LR-WPANs), Annex B.4: Specification of generic CCM* mode of operation
Hash	FIPS 180-3	Secure Hash Standard (SHA1, SHA-224, SHA-256)
	RFC2104	HMAC: Keyed-Hashing for Message Authentication
RSA	PKCS#1	Public-Key Cryptography Standards (PKCS) #1: RSA Cryptography Specifications v1.5/2.1
Diffie-Hellman	ANSI X9.42	Public Key Cryptography for the Financial Services Industry: Agreement of Symmetric Keys Using Discrete
		Logarithm Cryptography
	PKCS#3	Diffie-Hellman Key-Agreement Standard
ECC	ANSI X9.63	Public Key Cryptography for the Financial Services Industry - Key Agreement and Key Transport Using
		Elliptic Curve Cryptography
	IEEE 1363	Standard Specifications for Public-Key Cryptography
	ANSI X9.62	Public Key Cryptography For The Financial Services Industry: The Elliptic Curve Digital Signature Algorithm (ECDSA)
	Ed25519	Edwards-curve, Ed25519: high-speed high-security signatures, Daniel J. Bernstein, Niels Duif, Tanja Lange,
		Peter Schwabe, and Bo-Yin Yang
	Curve25519	Montgomery curve, Curve25519: new Diffie-Hellman speed records, Daniel J. Bernstein
	FIPS 186-4	Digital Signature Standard (DSS)
	SEC 2	Recommended Elliptic Curve Domain Parameters, Certicom Research
	NIST SP 800-56A rev. 2	Recommendation for Pair-Wise Key Establishment Schemes Using Discrete Logarithm Cryptography
General	FIPS 140-2	Security Requirements for Cryptographic Modules

Table 27: CRYPTOCELL cryptography standards

6.1.7 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50840000	CRYPTOCELL	CRYPTOCELL	S	NSA	CryptoCell sub-system contro	I
					interface	

Table 28: Instances

Register	Offset	Security	Description
ENABLE	0x500		Enable CRYPTOCELL subsystem

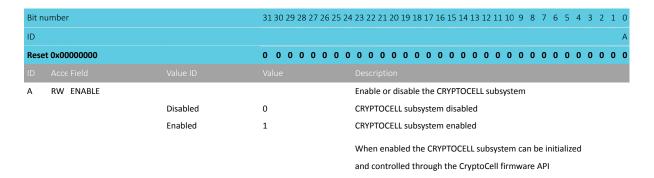
Table 29: Register overview

6.1.7.1 ENABLE

Address offset: 0x500



Enable CRYPTOCELL subsystem



6.1.8 Host interface

This chapter describe host registers used for controlling the CRYPTOCELL subsystem behavior.

6.1.8.1 HOST_RGF block

The HOST_RGF block contains registers for configuring LCS and device root key K_{DR}, in addition to selecting which cryptographic key is connected to the AES engine.

6.2 DPPI - Distributed programmable peripheral interconnect

The distributed programmable peripheral interconnect (DPPI) enables peripherals to interact autonomously with each other, using tasks and events, without any intervention from the CPU. DPPI allows precise synchronization between peripherals when real-time application constraints exist, and eliminates the need of CPU involvement to implement behavior which can be predefined using the DPPI.

DPPI has the following features:

- · Peripheral tasks can subscribe to channels
- · Peripheral events can be published on channels
- Publish/subscribe pattern enabling multiple connection options:
 - One-to-one
 - One-to-many
 - Many-to-one
 - Many-to-many

The DPPI system consists of several PPIBus modules, which are connected to a fixed number of DPPI channels and a DPPI controller (DPPIC):



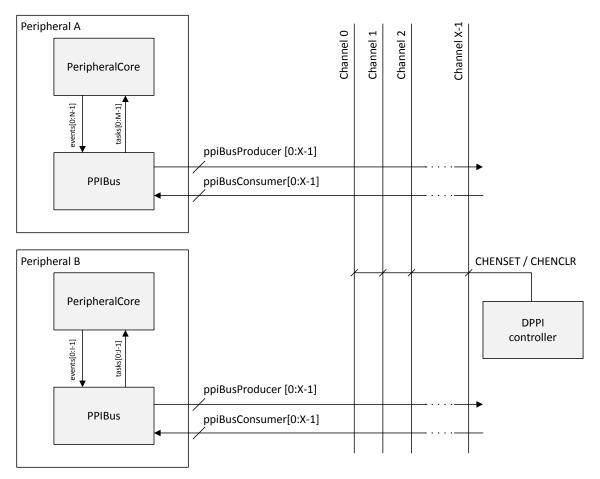


Figure 12: DPPI overview

6.2.1 Subscribing to and publishing on channels

The PPIBus can route peripheral events onto the channels (publishing), or route events from the channels into peripheral tasks (subscribing).

All peripherals include:

- One subscribe register per task
- One publish register per event

Publish and subscribe registers use channel index field to determine the channel to which the event is published or tasks subscribed. In addition, there is an enable bit for the subscribe and publish registers that needs to be enabled before the subscription or publishing takes effect.

One event can trigger multiple tasks by subscribing different tasks to the same channel. Similarly, one task could be triggered by multiple events by publishing different events to the same channel. For advanced use cases, multiple events and multiple tasks could be connected to the same channel forming a many-to-many connection. If multiple events are published on the same channel at the same time, the events will be merged and only one event is routed through the DPPI system.

DPPI events flow on page 80 shows how peripheral events are routed onto different channels based on the publish registers.



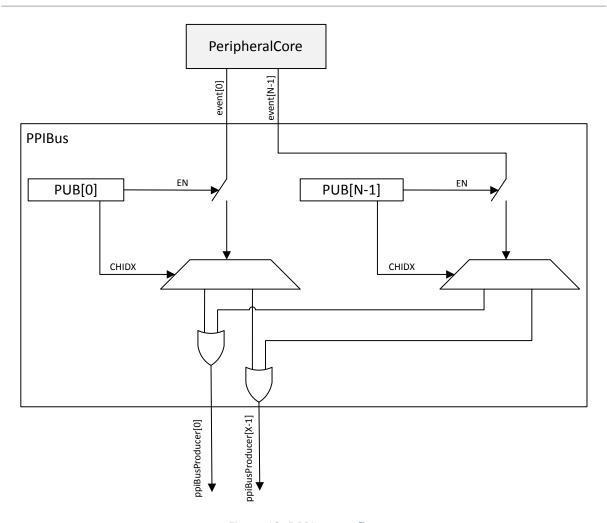


Figure 13: DPPI events flow

DPPI tasks flow on page 81 shows how peripheral tasks are triggered from different channels based on the subscribe registers.



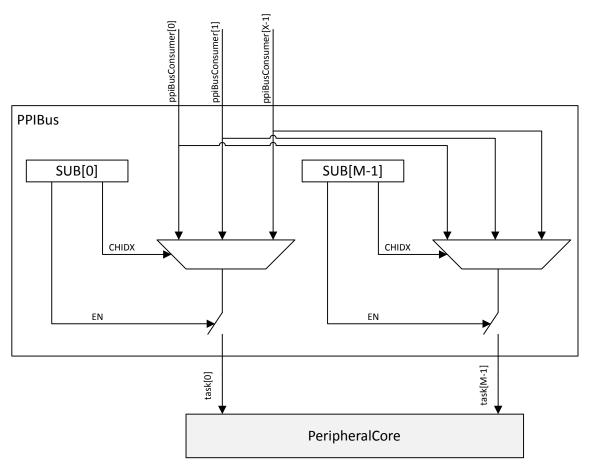


Figure 14: DPPI tasks flow

6.2.2 DPPI controller

Enabling/disabling and control of DPPI channels are handled locally at every peripheral and through the centralized DPPI controller peripheral.

There are two ways of enabling and disabling global channels using the DPPIC:

- Enable or disable channels individually using the CHEN, CHENSET and CHENCLR registers.
- Enable or disable channels in channel groups using the groups' ENABLE and DISABLE tasks. Prior triggering these tasks, it needs to be defined which channels belong to which channel groups.

Important: When a channel belongs to two (or more) groups, for example group m and n, and the tasks CHG[m].EN and CHG[n].DIS occur simultaneously (m and n can be equal or different), the CHG[m].EN task on that channel has priority. Meaning that enable tasks are prioritized over disable tasks.

DPPIC tasks (for example CHG[0].EN) can be triggered through the DPPI system like any other task, which means they can be hooked to a DPPI channel through the subscribe registers.

In order to write to CHG[x], the corresponding CHG[x].EN and CHG[x].DIS subscribe registers must be disabled. Writes to CHG[x] are ignored when either subscribe register is enabled.

6.2.3 Connection examples

DPPI offers several connection options. Examples are given for how to create one-to-one and many-to-many connections.



One-to-one connection

This example shows how to create a one-to-one connection between TIMER compare register and SAADC start task.

The channel configuration is set up first, TIMERO will publish its COMPAREO event on channel 0, and SAADC will subscribe its START task to events on the same channel. After that, the channel is enabled in the DPPI controller.

Many-to-many connection

The example shows how to create a many-to-many connection, also showcasing the use of the channel group functionality of the DPPI controller.

A channel group, including only channel 0, is set up first. Then GPIOTE and TIMERO configure their INO and COMPAREO events respectively to be published on channel 0, while SAADC configures its START task to subscribe to events on channel 0. The DPPI controller configures its CHGO disable task to subscribe to events on channel 0. This will effectively disable channel 0 after an event is received on channel 0. Finally, channel 0 is enabled using the DPPI controller task to enable a channel group.

6.2.4 Special considerations for system implementing TrustZone for Cortex-M[®] processors

In a system implementing the TrustZone for Cortex-M[®] technology, DPPI channels can be defined as "Secure" or "Non-Secure" using the SPU - System protection unit on page 257:

- A peripheral configured with a non-secure security attribute will only be able to subscribe or publish to non secure DPPI channels.
- A peripheral configured as secure will be able to access all DPPI channels



The DPPIC is implemented as a "split-security" peripheral. It is therefore accessible by both secure and non-secure accesses but the DPPIC behaves differently depending of the access type:

- A non-secure peripheral access will only be able to configure and control DPPI channels defined as non-secure in the SPU.DPPI.PERM[] register(s).
- A secure peripheral access can control all the DPPI channels, independently of the SPU.DPPI.PERM[] register(s).

The DPPIC allows the creation of a group of channels to be able to simultaneously enable or disable all channels within a group . The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all the channels (enabled or not) of a group are non-secure, then the group is considered as non-secure
- If at least one of the channels (enabled or not) of the group is secure, then the group is considered as secure

A non-secure access to a DPPIC register or a bitfield controlling a channel marked as secure in SPU.DPPI[].PERM register(s) will be ignored:

- Write accesses will have no effect
- Read accesses will always return a zero value

No exception is triggered when a non-secure access targets a register or bitfield controlling a secure channel

For example, if the bit i is set in the SPU.DPPI[0].PERM register (declaring DPPI channel i as secure), then

- Non-secure write accesses to CHEN, CHENSET and CHENCLR registers will not be able to write to bit i of those registers
- Non-secure write accesses to TASK_CHG[j].EN and TASK_CHG[j].DIS registers will be ignored if the channel group j contains at least a channel defined as secure (it can be the channel i itself or any channel declared as secure)
- Non-secure read accesses to registers CHEN, CHENSET and CHENCLR will always read a 0 for the bit at
 position i

For the channel configuration registers (DPPIC.CHG[]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a DPPIC.CHG[g] register included one or more secure channel, then the group g is considered as secure and only a secure transfer can read or write DPPIC.CHG[g]. A non-secure write access will be ignored and a non-secure read access will return 0.

The DPPIC can subscribe to both secure or non-secure channel through the SUBSCRIBE_CHG[] registers in order to trigger task for enabling or disabling groups of channels. But an event from a non-secure channel will be ignored if the group subscribing to this channel is secure. A event from a secure channel can trigger both secure and non-secure tasks.

6.2.5 Registers

Base ac	ddress Pe	eripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5001		PPIC	DPPIC : S	SPLIT	NA	DPPI controller	
0x4001		FFIC	DPPIC : NS	JF LI I	IVA	DEFI CONTIONE	

Table 30: Instances

Register	Offset	Security	Description
TASKS_CHG[0].EN	0x000		Enable channel group 0
TASKS_CHG[0].DIS	0x004		Disable channel group 0



Register	Offset	Security	Description
TASKS_CHG[1].EN	0x008		Enable channel group 1
TASKS_CHG[1].DIS	0x00C		Disable channel group 1
TASKS_CHG[2].EN	0x010		Enable channel group 2
TASKS_CHG[2].DIS	0x014		Disable channel group 2
TASKS_CHG[3].EN	0x018		Enable channel group 3
TASKS_CHG[3].DIS	0x01C		Disable channel group 3
TASKS_CHG[4].EN	0x020		Enable channel group 4
TASKS_CHG[4].DIS	0x024		Disable channel group 4
TASKS_CHG[5].EN	0x028		Enable channel group 5
TASKS_CHG[5].DIS	0x02C		Disable channel group 5
SUBSCRIBE_CHG[0].EN	0x080		Subscribe configuration for task CHG[0].EN
SUBSCRIBE_CHG[0].DIS	0x084		Subscribe configuration for task CHG[0].DIS
SUBSCRIBE_CHG[1].EN	0x088		Subscribe configuration for task CHG[1].EN
SUBSCRIBE_CHG[1].DIS	0x08C		Subscribe configuration for task CHG[1].DIS
SUBSCRIBE_CHG[2].EN	0x090		Subscribe configuration for task CHG[2].EN
SUBSCRIBE_CHG[2].DIS	0x094		Subscribe configuration for task CHG[2].DIS
SUBSCRIBE_CHG[3].EN	0x098		Subscribe configuration for task CHG[3].EN
SUBSCRIBE_CHG[3].DIS	0x09C		Subscribe configuration for task CHG[3].DIS
SUBSCRIBE_CHG[4].EN	0x0A0		Subscribe configuration for task CHG[4].EN
SUBSCRIBE_CHG[4].DIS	0x0A4		Subscribe configuration for task CHG[4].DIS
SUBSCRIBE_CHG[5].EN	0x0A8		Subscribe configuration for task CHG[5].EN
SUBSCRIBE_CHG[5].DIS	0x0AC		Subscribe configuration for task CHG[5].DIS
CHEN	0x500		Channel enable register
CHENSET	0x504		Channel enable set register
CHENCLR	0x508		Channel enable clear register
CHG[0]	0x800		Channel group 0
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[0].EN/DIS are
			enabled.
CHG[1]	0x804		Channel group 1
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[1].EN/DIS are
			enabled.
CHG[2]	0x808		Channel group 2
CHO[2]	0,000		Channel group 2
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[2].EN/DIS are
			enabled.
CHG[3]	0x80C		Channel group 3
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[3].EN/DIS are
			enabled.
CHG[4]	0x810		Channel group 4
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[4].EN/DIS are
			enabled.
CHG[5]	0x814		Channel group 5
			Note: Writes to this register is ignored if either SUBSCRIBE_CHG[5].EN/DIS are
			enabled.

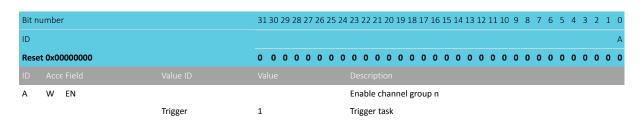
Table 31: Register overview

6.2.5.1 TASKS_CHG[n].EN (n=0..5)

Address offset: $0x000 + (n \times 0x8)$

Enable channel group n

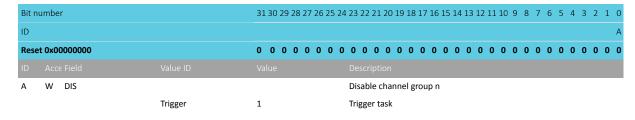




6.2.5.2 TASKS_CHG[n].DIS (n=0..5)

Address offset: $0x004 + (n \times 0x8)$

Disable channel group n



6.2.5.3 SUBSCRIBE_CHG[n].EN (n=0..5)

Address offset: $0x080 + (n \times 0x8)$

Subscribe configuration for task CHG[n].EN

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task CHG[n].EN will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.2.5.4 SUBSCRIBE_CHG[n].DIS (n=0..5)

Address offset: $0x084 + (n \times 0x8)$

Subscribe configuration for task CHG[n].DIS

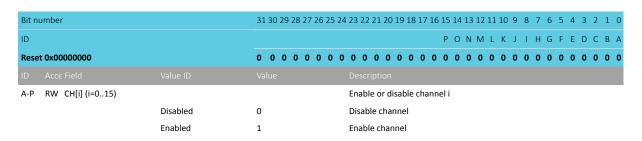
Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task CHG[n].DIS will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.2.5.5 CHEN

Address offset: 0x500

Channel enable register





6.2.5.6 CHENSET

Address offset: 0x504

Channel enable set register

Read: reads value of CH{i} field in CHEN register.

Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			PONMLKJIHGFEDCBA
Reset 0x00000000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID Acce Field			Description
A-P RW CH[i] (i=015)			Channel i enable set register. Writing '0' has no effect
	Disabled	0	Read: channel disabled
	Enabled	1	Read: channel enabled
	Set	1	Write: Enable channel

6.2.5.7 CHENCLR

Address offset: 0x508

Channel enable clear register

Read: reads value of CH{i} field in CHEN register.

Bit number		31 30 2	9 28 2	27 2	6 25	24	23 2	2 21	20 :	19 18	3 17	16	15 1	4 1	3 12	11 10	9	8	7	6	5 4	4 3	2	1 0
ID													Р (1 C	I M	L K	J	1	Н	G	FI	E D	С	ВА
Reset 0x00000000		0 0 0	0	0 (0 0	0	0 0	0	0	0 0	0	0	0 (0 (0	0 0	0	0	0	0	0 (0 0	0	0 0
ID Acce Field Val																								
A-P RW CH[i] (i=015)							Char	nnel	i en	able	clea	ır re	gist	er. \	Vriti	ng '0	has	no	eff	ect				
Dis	abled	0					Read	d: ch	ann	el di	sable	ed												
Ena	abled	1					Read	d: ch	ann	el er	able	ed												
Cle	ar	1					Writ	e: di	sabl	e ch	anne	el												

6.2.5.8 CHG[n] (n=0..5)

Address offset: $0x800 + (n \times 0x4)$

Channel group n

Note: Writes to this register is ignored if either SUBSCRIBE_CHG[n].EN/DIS are enabled.



Bit number		31 30 29 28 2	27 26 25 24	23 22	21 20	19 18	3 17 1	L6 15	14 13	3 12 :	11 10	9	8	7 (5 5	4	3 2	1 0
ID								Р	O N	М	L K	J	1	Н	6 F	Ε	D C	ВА
Reset 0x00000000		0 0 0 0	0 0 0 0	0 0	0 0	0 0	0	0 0	0 0	0	0 0	0	0	0 (0	0	0 0	0 0
ID Acce Field																		
A-P RW CH[i] (i=015)				Includ	e or e	xclud	e cha	innel	i									
	Excluded	0		Exclud	le													
	Included	1		Includ	e													

6.3 EGU — Event generator unit

The Event generator unit (EGU) provides support for inter-layer signaling. This means support for atomic triggering of both CPU execution and hardware tasks from both firmware (by CPU) and hardware (by PPI). This feature can, for instance, be used for triggering CPU execution at a lower priority execution from a higher priority execution, or to handle a peripheral's ISR execution at a lower priority for some of its events. However, triggering any priority from any priority is possible.

Listed here are the main EGU features:

- Enables SW triggering of interrupts
- Separate interrupt vectors for every EGU instance
- Up to 16 separate event flags per interrupt for multiplexing

Each instance of The EGU implements a set of tasks which can individually be triggered to generate the corresponding event, i.e., the corresponding event for TASKS_TRIGGER[n] is EVENTS_TRIGGERED[n].

Refer to Instances on page 87 for a list of the various EGU instances

6.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5001B000	EGU	EGU0:S	US	NA	Event generator unit 0	
0x4001B000	LGO	EGU0: NS	03	NA .	Event generator unit o	
0x5001C000	EGU	EGU1:S	US	NA	Event generator unit 1	
0x4001C000	LOO	EGU1: NS	03	NA .	Event generator unit 1	
0x5001D000	EGU	EGU2:S	US	NA	Event generator unit 2	
0x4001D000	100	EGU2 : NS	03	NA.	Event generator unit 2	
0x5001E000	EGU	EGU3:S	US	NA	Event generator unit 3	
0x4001E000	100	EGU3: NS	03	101	Event generator and 3	
0x5001F000	EGU	EGU4:S	US	NA	Event generator unit 4	
0x4001F000	200	EGU4 : NS		1971	Event generator ante 4	
0x50020000	EGU	EGU5:S	US	NA	Event generator unit 5	
0x40020000	100	EGU5 : NS	00	1471	Event generator unit 3	

Table 32: Instances

Register	Offset	Security	Description
TASKS_TRIGGER[0]	0x000		Trigger 0 for triggering the corresponding TRIGGERED[0] event
TASKS_TRIGGER[1]	0x004		Trigger 1 for triggering the corresponding TRIGGERED[1] event
TASKS_TRIGGER[2]	0x008		Trigger 2 for triggering the corresponding TRIGGERED[2] event
TASKS_TRIGGER[3]	0x00C		Trigger 3 for triggering the corresponding TRIGGERED[3] event
TASKS_TRIGGER[4]	0x010		Trigger 4 for triggering the corresponding TRIGGERED[4] event
TASKS_TRIGGER[5]	0x014		Trigger 5 for triggering the corresponding TRIGGERED[5] event
TASKS_TRIGGER[6]	0x018		Trigger 6 for triggering the corresponding TRIGGERED[6] event
TASKS_TRIGGER[7]	0x01C		Trigger 7 for triggering the corresponding TRIGGERED[7] event



Register	Offset Security	Description
TASKS_TRIGGER[8]	0x020	Trigger 8 for triggering the corresponding TRIGGERED[8] event
TASKS_TRIGGER[9]	0x024	Trigger 9 for triggering the corresponding TRIGGERED[9] event
TASKS TRIGGER[10]	0x028	Trigger 10 for triggering the corresponding TRIGGERED[10] event
TASKS TRIGGER[11]	0x02C	Trigger 11 for triggering the corresponding TRIGGERED[11] event
TASKS TRIGGER[12]	0x030	Trigger 12 for triggering the corresponding TRIGGERED[12] event
TASKS_TRIGGER[13]	0x034	Trigger 13 for triggering the corresponding TRIGGERED[13] event
TASKS TRIGGER[14]	0x038	Trigger 14 for triggering the corresponding TRIGGERED[14] event
TASKS_TRIGGER[15]	0x03C	Trigger 15 for triggering the corresponding TRIGGERED[15] event
SUBSCRIBE_TRIGGER[0]	0x080	Subscribe configuration for task TRIGGER[0]
SUBSCRIBE_TRIGGER[1]	0x084	Subscribe configuration for task TRIGGER[1]
SUBSCRIBE_TRIGGER[2]	0x088	Subscribe configuration for task TRIGGER[2]
SUBSCRIBE_TRIGGER[3]	0x08C	Subscribe configuration for task TRIGGER[3]
SUBSCRIBE_TRIGGER[4]	0x090	Subscribe configuration for task TRIGGER[4]
	0x094	Subscribe configuration for task TRIGGER[5]
SUBSCRIBE_TRIGGER[5]		Subscribe configuration for task TRIGGER[6]
SUBSCRIBE_TRIGGER[6]	0x098	
SUBSCRIBE_TRIGGER[7]	0x09C	Subscribe configuration for task TRIGGER[7]
SUBSCRIBE_TRIGGER[8]	0x0A0	Subscribe configuration for task TRIGGER[8]
SUBSCRIBE_TRIGGER[9]	0x0A4	Subscribe configuration for task TRIGGER[9]
SUBSCRIBE_TRIGGER[10]	0x0A8	Subscribe configuration for task TRIGGER[10]
SUBSCRIBE_TRIGGER[11]	0x0AC	Subscribe configuration for task TRIGGER[11]
SUBSCRIBE_TRIGGER[12]	0x0B0	Subscribe configuration for task TRIGGER[12]
SUBSCRIBE_TRIGGER[13]	0x0B4	Subscribe configuration for task TRIGGER[13]
SUBSCRIBE_TRIGGER[14]	0x0B8	Subscribe configuration for task TRIGGER[14]
SUBSCRIBE_TRIGGER[15]	0x0BC	Subscribe configuration for task TRIGGER[15]
EVENTS_TRIGGERED[0]	0x100	Event number 0 generated by triggering the corresponding TRIGGER[0] task
EVENTS_TRIGGERED[1]	0x104	Event number 1 generated by triggering the corresponding TRIGGER[1] task
EVENTS_TRIGGERED[2]	0x108	Event number 2 generated by triggering the corresponding TRIGGER[2] task
EVENTS_TRIGGERED[3]	0x10C	Event number 3 generated by triggering the corresponding TRIGGER[3] task
EVENTS_TRIGGERED[4]	0x110	Event number 4 generated by triggering the corresponding TRIGGER[4] task
EVENTS_TRIGGERED[5]	0x114	Event number 5 generated by triggering the corresponding TRIGGER[5] task
EVENTS_TRIGGERED[6]	0x118	Event number 6 generated by triggering the corresponding TRIGGER[6] task
EVENTS_TRIGGERED[7]	0x11C	Event number 7 generated by triggering the corresponding TRIGGER[7] task
EVENTS_TRIGGERED[8]	0x120	Event number 8 generated by triggering the corresponding TRIGGER[8] task
EVENTS_TRIGGERED[9]	0x124	Event number 9 generated by triggering the corresponding TRIGGER[9] task
EVENTS_TRIGGERED[10]	0x128	Event number 10 generated by triggering the corresponding TRIGGER[10] task
EVENTS_TRIGGERED[11]	0x12C	Event number 11 generated by triggering the corresponding TRIGGER[11] task
EVENTS_TRIGGERED[12]	0x130	Event number 12 generated by triggering the corresponding TRIGGER[12] task
EVENTS_TRIGGERED[13]	0x134	Event number 13 generated by triggering the corresponding TRIGGER[13] task
EVENTS_TRIGGERED[14]	0x138	Event number 14 generated by triggering the corresponding TRIGGER[14] task
EVENTS_TRIGGERED[15]	0x13C	Event number 15 generated by triggering the corresponding TRIGGER[15] task
PUBLISH_TRIGGERED[0]	0x180	Publish configuration for event TRIGGERED[0]
PUBLISH_TRIGGERED[1]	0x184	Publish configuration for event TRIGGERED[1]
PUBLISH_TRIGGERED[2]	0x188	Publish configuration for event TRIGGERED[2]
PUBLISH_TRIGGERED[3]	0x18C	Publish configuration for event TRIGGERED[3]
PUBLISH_TRIGGERED[4]	0x190	Publish configuration for event TRIGGERED[4]
PUBLISH_TRIGGERED[5]	0x194	Publish configuration for event TRIGGERED[5]
PUBLISH_TRIGGERED[6]	0x198	Publish configuration for event TRIGGERED[6]
PUBLISH_TRIGGERED[7]	0x19C	Publish configuration for event TRIGGERED[7]
PUBLISH_TRIGGERED[8]	0x1A0	Publish configuration for event TRIGGERED[8]
PUBLISH_TRIGGERED[9]	0x1A4	Publish configuration for event TRIGGERED[9]
PUBLISH_TRIGGERED[10]	0x1A8	Publish configuration for event TRIGGERED[10]
	0x1AC	Dublish configuration for quant TRICCEPED[41]
PUBLISH_TRIGGERED[11]	UXIAC	Publish configuration for event TRIGGERED[11]



Register	Offset	Security	Description
PUBLISH_TRIGGERED[13]	0x1B4		Publish configuration for event TRIGGERED[13]
PUBLISH_TRIGGERED[14]	0x1B8		Publish configuration for event TRIGGERED[14]
PUBLISH_TRIGGERED[15]	0x1BC		Publish configuration for event TRIGGERED[15]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt

Table 33: Register overview

6.3.1.1 TASKS_TRIGGER[n] (n=0..15)

Address offset: $0x000 + (n \times 0x4)$

Trigger n for triggering the corresponding TRIGGERED[n] event

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W TASKS_TRIGGER			Trigger n for triggering the corresponding TRIGGERED[n]
			event
	Trigger	1	Trigger task

6.3.1.2 SUBSCRIBE_TRIGGER[n] (n=0..15)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task TRIGGER[n]

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	2 1 0
ID			В	А	A A A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0
ID					
Α	RW CHIDX		[150]	Channel that task TRIGGER[n] will subscribe to	
В	RW EN				
		Disabled	0	Disable subscription	
		Enabled	1	Enable subscription	

6.3.1.3 EVENTS_TRIGGERED[n] (n=0..15)

Address offset: $0x100 + (n \times 0x4)$

Event number n generated by triggering the corresponding TRIGGER[n] task

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_TRIGGERED			Event number n generated by triggering the corresponding
				TRIGGER[n] task
		NotGenerated	0	Event not generated
		Generated	1	Event generated



6.3.1.4 PUBLISH_TRIGGERED[n] (n=0..15)

Address offset: $0x180 + (n \times 0x4)$

Publish configuration for event TRIGGERED[n]

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event TRIGGERED[n] will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.3.1.5 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	ımber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				PONMLKJIHGFEDCBA
Rese	0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
A-P	RW TRIGGERED[i] (i=015)			Enable or disable interrupt for event TRIGGERED[i]
		Disabled	0	Disable
		Enabled	1	Enable

6.3.1.6 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-P RW TRIGGERED[i] (i=01	5)		Write '1' to enable interrupt for event TRIGGERED[i]
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.3.1.7 INTENCLR

Address offset: 0x308

Disable interrupt



Bit number		31 30 29	28 2	7 2	6 25	5 24	23	22	21 2	20 1	19 :	18	17	16	15	14	13	2 1	1 1	9	8	7	6	5	4	3	2	1 0
ID															Р	0	N	M I	L k	J	-1	Н	G	F	Ε	D	C I	ВА
Reset 0x00000000		0 0 0	0 () (0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 (0 0
ID Acce Field																												
A-P RW TRIGGERED[i] (i=015)							Wr	ite	'1' t	:o c	lisa	ble	int	eri	rup	t fo	r e	ent	TR	IGG	ERI	ED[i	i]					
	Clear	1					Dis	abl	e																			
	Clear Disabled	1 0							e Disa	abl	ed																	

6.3.2 Electrical specification

6.3.2.1 EGU Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{EGU,EVT}	Latency between setting an EGU event flag and the system		1		cycles
	setting an interrupt				

6.4 GPIO — General purpose input/output

The general purpose input/output pins (GPIOs) are grouped as one or more ports with each port having up to 32 GPIOs.

The number of ports and GPIOs per port might vary with product variant and package. Refer to Registers on page 95 and Pin assignments on page 379 for more information about the number of GPIOs that are supported.

GPIO has the following user-configurable features:

- Up to 32 GPIO pins per GPIO port
- · Configurable output drive strength
- Internal pull-up and pull-down resistors
- Wake-up from high or low level triggers on all pins
- Trigger interrupt on state changes on any pin
- All pins can be used by the PPI task/event system
- One or more GPIO outputs can be controlled through PPI and GPIOTE channels
- All pins can be individually mapped to interface blocks for layout flexibility
- GPIO state changes captured on SENSE signal can be stored by LATCH register
- Support for Secure and Non-Secure attributes for pins in conjunction with the System Protection Unit (SPU - System protection unit on page 257)

The GPIO port peripheral implements up to 32 pins, PIN0 through PIN31. Each of these pins can be individually configured in the PIN_CNF[n] registers (n=0..31).

The following parameters can be configured through these registers:

- Direction
- Drive strength
- Enabling of pull-up and pull-down resistors
- · Pin sensing
- Input buffer disconnect
- Analog input (for selected pins)

The PIN_CNF registers are retained registers. See POWER — Power control on page 58 chapter for more information about retained registers.



6.4.1 Pin configuration

Pins can be individually configured, through the SENSE field in the PIN_CNF[n] register, to detect either a high level or a low level on their input.

When the correct level is detected on any such configured pin, the sense mechanism will set the DETECT signal high. Each pin has a separate DETECT signal. Default behavior, defined by the DETECTMODE register, is that the DETECT signals from all pins in the GPIO port are combined into one common DETECT signal that is routed throughout the system, which then can be utilized by other peripherals. This mechanism is functional in both System ON mode and System OFF mode. See GPIO port and the GPIO pin details on page 92.

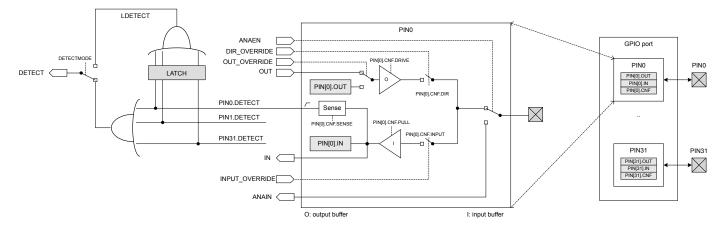


Figure 15: GPIO port and the GPIO pin details

In systems implementing a System Protection Unit, an extra DETECTMODE_SEC register is available to control the behaviour associated to pin marked as Secure, while the DETECTMODE register is restricted to pin marked as Non-Secure. Please refer to GPIO security on page 94 for more details.

GPIO port and the GPIO pin details on page 92 illustrates the GPIO port containing 32 individual pins, where PINO is illustrated in more detail as a reference. All signals on the left side in the illustration are used by other peripherals in the system and therefore not directly available to the CPU.

Make sure that a pin is in a level that cannot trigger the sense mechanism before enabling it. The DETECT signal will go high immediately if the SENSE condition configured in the PIN_CNF registers is met when the sense mechanism is enabled. This will trigger a PORT event if the DETECT signal was low before enabling the sense mechanism. See GPIOTE — GPIO tasks and events on page 101.

See the following peripherals for more information about how the DETECT signal is used:

- POWER: uses the DETECT signal to exit from System OFF mode.
- GPIOTE: uses the DETECT signal to generate the PORT event. (GPIOTE_SEC is used for PORT event related to secure pins)

When a pin's PINx.DETECT signal goes high, a flag will be set in the LATCH register. For example, when the PINO.DETECT signal goes high, bit 0 in the LATCH register will be set to '1'. If the CPU performs a clear operation on a bit in the LATCH register when the associated PINx.DETECT signal is high, the bit in the LATCH register will not be cleared. The LATCH register will only be cleared if the CPU explicitly clears it by writing a '1' to the bit that shall be cleared, i.e. the LATCH register will not be affected by a PINx.DETECT signal being set low.

The LDETECT signal will be set high when one or more bits in the LATCH register are '1'. The LDETECT signal will be set low when all bits in the LATCH register are successfully cleared to '0'.

If one or more bits in the LATCH register are '1' after the CPU has performed a clear operation on the LATCH registers, a rising edge will be generated on the LDETECT signal. This is illustrated in DETECT signal behavior on page 93.



Important: The CPU can read the LATCH register at any time to check if a SENSE condition has been met on one or more of the the GPIO pins, even if that condition is no longer met at the time the CPU queries the LATCH register. This mechanism will work even if the LDETECT signal is not used as the DETECT signal.

The LDETECT signal is by default not connected to the GPIO port's DETECT signal, but via the DETECTMODE register it is possible to change from default behavior to DETECT signal being derived directly from the LDETECT signal instead. See GPIO port and the GPIO pin details on page 92. DETECT signal behavior on page 93 illustrates the DETECT signal behavior for these two alternatives.

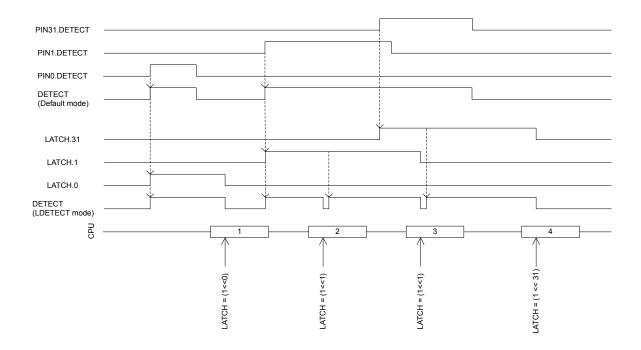


Figure 16: DETECT signal behavior

The input buffer of a GPIO pin can be disconnected from the pin to enable power savings when the pin is not used as an input, see GPIO port and the GPIO pin details on page 92. Inputs must be connected to get a valid input value in the IN register, and for the sense mechanism to get access to the pin.

Other peripherals in the system can connect to GPIO pins and override their output value and configuration, or read their analog or digital input value. See GPIO port and the GPIO pin details on page 92.

Selected pins also support analog input signals, see ANAIN in GPIO port and the GPIO pin details on page 92. The assignment of the analog pins can be found in Pin assignments on page 379.

The following delays should be taken into considerations:

- There is 2 CPU clock cycles delay from the GPIO pad to the GPIO.IN register
- The GPIO pad must be low (or high depending on the SENSE polarity) for 3 CPU clock cycles after DETECT has gone high in order to generate a new DETECT signal

Important: When a pin is configured as digital input, care has been taken to minimize increased current consumption when the input voltage is between V_{IL} and V_{IH} . However, it is a good practice to ensure that the external circuitry does not drive that pin to levels between V_{IL} and V_{IH} for a long period of time.



6.4.2 GPIO security

The General purpose input/output peripheral (GPIO) is implemented as a "split-security" peripheral. If marked as non-secure, it can be access by both secure and non-secure accesses but will behave differently depending of the access type:

A non-secure peripheral access will only be able to configure and control pins defined as non-secure in the System Protection Unit (SPU) GPIOPORT.PERM[] register(s).

A non-secure access to a register or a bitfield controlling a pin marked as secure in GPIO.PERM[] register(s) will be ignored:

- write accesses will have no effect
- · read accesses will always return a zero value

No exception is triggered when a non-secure access targets a register or bitfield controlling a secure pin.

For example, if the bit i is set in the SPU.GPIO.PERM[0] register (declaring Pin PO.i as secure), then

- non-secure write accesses to OUT, OUTSET, OUTCLR, DIR, DIRSET, DIRCLR and LATCH registers will not be able to write to bit i of those registers
- non-secure write accesses to registers PIN[i].OUT and PIN_CNF[i] will be ignored
- non-secure read accesses to registers OUT, OUTSET, OUTCLR, IN, DIR, DIRSET, DIRCLR and LATCH will always read a 0 for the bit at position *i*
- non-secure read accesses to registers PIN[i].OUT, PIN[i].OUT and PIN_CNF[i] will always return 0

The GPIO.DETECTMODE and GPIO.DETECTMODE_SEC registers are handled differently than the other registers mentioned before. When accessed by a secure access, the DETECTMODE_SEC register control the source for the DETECT_SEC signal for the pins marked as secure. When accessed by a non-secure access, the DETECTMODE_SEC is read as zero and write accesses are ignored. The GPIO.DETECTMODE register controls the source for the DETECT_NSEC signal for the pins defined as non-secure.

The DETECT_NSEC signal is routed to the GPIOTE peripheral, allowing generation of events and interrupts from pins marked as non-secure. The DETECT_SEC signal is routed to the GPIOTESEC peripheral, allowing generation of events and interrupts from pins marked as secure. Principle of direct pin access on page 95 illustrates how the DETECT_NSEC and DETECT_SEC signals are generated from the GPIO PIN[].DETECT signals.



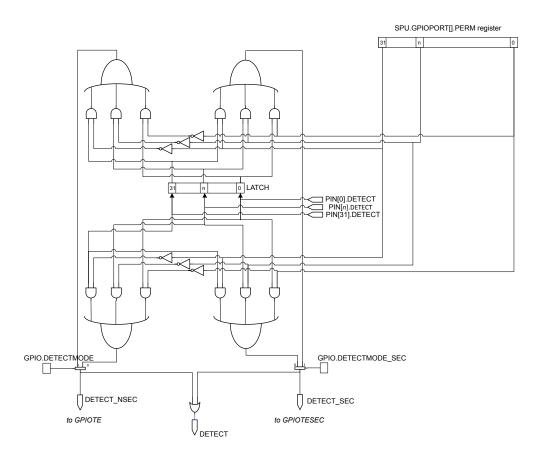


Figure 17: Principle of direct pin access

6.4.3 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50842500	GPIO	P0:S	SPLIT	NA	General purpose input and	
0x40842500	GFIO	P0 : NS	JF LI I	IVA	output	

Table 34: Instances

Register	Offset	Security	Description
OUT	0x004		Write GPIO port
OUTSET	0x008		Set individual bits in GPIO port
OUTCLR	0x00C		Clear individual bits in GPIO port
IN	0x010		Read GPIO port
DIR	0x014		Direction of GPIO pins
DIRSET	0x018		DIR set register
DIRCLR	0x01C		DIR clear register
LATCH	0x020		Latch register indicating what GPIO pins that have met the criteria set in the
			PIN_CNF[n].SENSE registers
DETECTMODE	0x024		Select between default DETECT signal behaviour and LDETECT mode (For non-
			secure pin only)
DETECTMODE_SEC	0x028		Select between default DETECT signal behaviour and LDETECT mode (For secure
			pin only)
PIN_CNF[0]	0x200		Configuration of GPIO pins
PIN_CNF[1]	0x204		Configuration of GPIO pins



Register	Offset	Security	Description
PIN_CNF[2]	0x208		Configuration of GPIO pins
PIN_CNF[3]	0x20C		Configuration of GPIO pins
PIN_CNF[4]	0x210		Configuration of GPIO pins
PIN_CNF[5]	0x214		Configuration of GPIO pins
PIN_CNF[6]	0x218		Configuration of GPIO pins
PIN_CNF[7]	0x21C		Configuration of GPIO pins
PIN_CNF[8]	0x220		Configuration of GPIO pins
PIN_CNF[9]	0x224		Configuration of GPIO pins
PIN_CNF[10]	0x228		Configuration of GPIO pins
PIN_CNF[11]	0x22C		Configuration of GPIO pins
PIN_CNF[12]	0x230		Configuration of GPIO pins
PIN_CNF[13]	0x234		Configuration of GPIO pins
PIN_CNF[14]	0x238		Configuration of GPIO pins
PIN_CNF[15]	0x23C		Configuration of GPIO pins
PIN_CNF[16]	0x240		Configuration of GPIO pins
PIN_CNF[17]	0x244		Configuration of GPIO pins
PIN_CNF[18]	0x248		Configuration of GPIO pins
PIN_CNF[19]	0x24C		Configuration of GPIO pins
PIN_CNF[20]	0x250		Configuration of GPIO pins
PIN_CNF[21]	0x254		Configuration of GPIO pins
PIN_CNF[22]	0x258		Configuration of GPIO pins
PIN_CNF[23]	0x25C		Configuration of GPIO pins
PIN_CNF[24]	0x260		Configuration of GPIO pins
PIN_CNF[25]	0x264		Configuration of GPIO pins
PIN_CNF[26]	0x268		Configuration of GPIO pins
PIN_CNF[27]	0x26C		Configuration of GPIO pins
PIN_CNF[28]	0x270		Configuration of GPIO pins
PIN_CNF[29]	0x274		Configuration of GPIO pins
PIN_CNF[30]	0x278		Configuration of GPIO pins
PIN_CNF[31]	0x27C		Configuration of GPIO pins

Table 35: Register overview

6.4.3.1 OUT

Address offset: 0x004

Write GPIO port

Bit number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		fedcba 2	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-f RW PIN[i] (i=	=031)		Pin i
	Low	0	Pin driver is low
	High	1	Pin driver is high

6.4.3.2 OUTSET

Address offset: 0x008

Set individual bits in GPIO port

Read: reads value of OUT register.



Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		fedcbaZYXWVUTSRQPONMLKJIHGFEDCBA
Reset 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field		Value Description
A-f RW PIN[i] (i=031)		Pin i
	Low	0 Read: pin driver is low
	High	1 Read: pin driver is high
	Set	1 Write: writing a '1' sets the pin high; writing a '0' has no
		effect

6.4.3.3 OUTCLR

Address offset: 0x00C

Clear individual bits in GPIO port Read: reads value of OUT register.

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0											
ID			f e d c b a Z	Y X W V U T S R Q P O N M L K J I H G F E D C B A											
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0											
ID															
A-f	RW PIN[i] (i=031)			Pin i											
		Low	0	Read: pin driver is low											
		High	1	Read: pin driver is high											
		Clear	1	Write: writing a '1' sets the pin low; writing a '0' has no											
				effect											

6.4.3.4 IN

Address offset: 0x010 Read GPIO port

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		fedcba Z	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-f R PIN[i] (i=031)			Pin i
	Low	0	Pin input is low
	High	1	Pin input is high

6.4.3.5 DIR

Address offset: 0x014

Direction of GPIO pins

Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	2 1 0
ID		fedcbaZYXWVUTSRQPONMLKJIHGFEDO	ВА
Reset 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID Acce Field			
A-f RW PIN[i] (i=031)		Pin i	
	Input	0 Pin set as input	
	Output	1 Pin set as output	



6.4.3.6 DIRSET

Address offset: 0x018

DIR set register

Read: reads value of DIR register.

Bit nu	mber		31	1 30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13 :	L2 1	1 1	9	8	7	6	5	4	3	2	1 0
ID			f	е	d	С	b	а	Z	Υ	Χ	W	٧	U	Т	S	R	Q	Р	0	N I	M	L k	J	-1	Н	G	F	Ε	D	С	ВА
Reset	0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0 0
ID																																
A-f	RW PIN[i] (i=031)										Se	t as	ou	tpu	ıt pi	in i																
		Input	0								Re	ad:	pin	se	t as	in	put															
		Output	1								Re	ad:	pin	se	t as	οι	ıtpı	ut														
		Set	1								Wı	rite:	: wr	itin	ng a	'1'	se	ts p	oin	to c	utp	ut;	wri	ting	g a '	0' h	ıas	no				
											eff	ect																				

6.4.3.7 DIRCLR

Address offset: 0x01C

DIR clear register

Read: reads value of DIR register.

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0											
ID			f edcbaZ	Y X W V U T S R Q P O N M L K J I H G F E D C B A											
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0											
ID															
A-f	RW PIN[i] (i=031)			Set as input pin i											
		Input	0	Read: pin set as input											
		Output	1	Read: pin set as output											
		Clear	1	Write: writing a '1' sets pin to input; writing a '0' has no											
				effect											

6.4.3.8 LATCH

Address offset: 0x020

Latch register indicating what GPIO pins that have met the criteria set in the PIN_CNF[n].SENSE registers

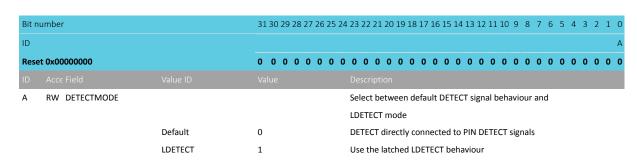
Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	fedcbaZ	Y X W V U T S R Q P O N M L K J I H G F E D C B A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A-f RW PIN[i] (i=031)		Status on whether PINi has met criteria set in
		PIN_CNFi.SENSE register. Write '1' to clear.
NotLatched	0	Criteria has not been met
Latched	1	Criteria has been met

6.4.3.9 DETECTMODE

Address offset: 0x024

Select between default DETECT signal behaviour and LDETECT mode (For non-secure pin only)

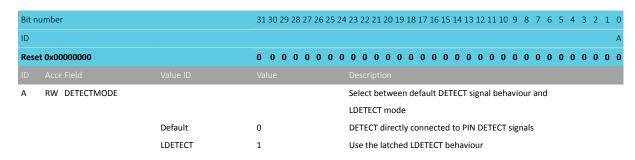




6.4.3.10 DETECTMODE SEC

Address offset: 0x028

Select between default DETECT signal behaviour and LDETECT mode (For secure pin only)



6.4.3.11 PIN_CNF[n] (n=0..31)

Address offset: $0x200 + (n \times 0x4)$

Configuration of GPIO pins

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E E DDD CCBA
Rese	et 0x00000002		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW DIR			Pin direction. Same physical register as DIR register
		Input	0	Configure pin as an input pin
		Output	1	Configure pin as an output pin
В	RW INPUT			Connect or disconnect input buffer
		Connect	0	Connect input buffer
		Disconnect	1	Disconnect input buffer
С	RW PULL			Pull configuration
		Disabled	0	No pull
		Pulldown	1	Pull down on pin
		Pullup	3	Pull up on pin
D	RW DRIVE			Drive configuration
		SOS1	0	Standard '0', standard '1'
		H0S1	1	High drive '0', standard '1'
		S0H1	2	Standard '0', high drive '1'
		H0H1	3	High drive '0', high 'drive '1"
		D0S1	4	Disconnect '0' standard '1' (normally used for wired-or
				connections)
		D0H1	5	Disconnect '0', high drive '1' (normally used for wired-or
				connections)
		SOD1	6	Standard '0'. disconnect '1' (normally used for wired-and
				connections)



Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			E E DDD CCBA
Reset 0x00000002		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	H0D1	7	High drive '0', disconnect '1' (normally used for wired-and
			connections)
E RW SENSE			Pin sensing mechanism
	Disabled	0	Disabled
	High	2	Sense for high level
	Low	3	Sense for low level

6.4.4 Electrical specification

6.4.4.1 GPIO Electrical Specification

NH Input high voltage 0.7 x VIDD	Symbol	Description	Min.	Тур.	Max.	Units
Vit. Input low voltage VSS 0.3 x Very VDD VOM.5D Output high voltage, standard drive, 0.5 mA, VDD ≥1.7 VDD-0.4 VDD V VOM.5DM Output high voltage, high drive, 5 mA, VDD >= 2.7 V VDD-0.4 VDD V VOH.HOLD Output high voltage, high drive, 5 mA, VDD >= 1.7 V VDD-0.4 VDD V VOLLION Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLLHOL Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS+0.4 V VOLLHOL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLLHOL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLLHOL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLLHOL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V S 1 2 4 mA IOLLHOL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V S 2 4 mA INFLIDH Current at VDD-0.4 V, output set high, hig	V _{IH}	Input high voltage	0.7 x		VDD	V
VOH.SD Output high voltage, standard drive, 0.5 mA, VDD ≥1.7 VDD-0.4 VDD V VOH.MD Output high voltage, high drive, 5 mA, VDD >= 2.7 V VDD-0.4 VDD V VOH.MDL Output high voltage, high drive, 3 mA, VDD >= 1.7 V VDD-0.4 VDD V VOL.SD Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS+0.4 V VOL.HDL Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS+0.4 V VOL.HDL Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOL.HDL Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V IoL,SD Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V V S VSS+0.4 V IoL,BDL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V B 1 2 4 mA IoL,HDL Current at VDD-0.4 V, output set high, standard drive, VDD >= 1.7 V B 1 2 4 mA IoL,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V B 9 <td></td> <td></td> <td>VDD</td> <td></td> <td></td> <td></td>			VDD			
VOH,50 Output high voltage, standard drive, 0.5 mA, VDD ≥1.7 VDD-0.4 VDD V VOH,HDH Output high voltage, high drive, 5 mA, VDD >= 2.7 V VDD-0.4 VDD V VOH,HDL Output high voltage, high drive, 3 mA, VDD >= 1.7 V VDD-0.4 VDD V VOL,5D Output low voltage, standard drive, 0.5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOL,HDL Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOL,HDL Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOL,HDL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V IOL,BDL Current at VSS+0.4 V, output set low, standard drive, VDD 2.7 B 10 15 mA IOL,HDL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V B 10 15 mA IOH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 2.7 V B 1 2 4 mA IOH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 1	V_{IL}	Input low voltage	VSS		0.3 x	V
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VOM-HOL VOLSD Output high voltage, high drive, 3 mA, VDD >= 1.7 V VDD-0.4 VDD V VOLSD Output low voltage, standard drive, 0.5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLHDH Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS+0.4 V VOLHDL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V IoL,5D Current at VSS+0.4 V, output set low, standard drive, VDD 1 2 4 mA IoL,HDH Current at VSS+0.4 V, output set low, high drive, VDD >= 2.7 V 3 5 mA IoH,HDH Current at VDD-0.4 V, output set high, standard drive, VDD >= 1.7 V 3 5 mA IoH,HDH Current at VDD-0.4 V, output set high, high drive, VDD >= 2.7 V 6 9 14 mA IoH,HDH Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 5 mA IoH,HDH Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 5 mA IoH,HDH Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 1 1 1	V _{OH,SD}	Output high voltage, standard drive, 0.5 mA, VDD ≥1.7	VDD-0.4		VDD	V
VOLSO Output low voltage, standard drive, 0.5 mA, VDD ≥1.7 VSS VSS+0.4 V VOLHOH Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS+0.4 V VOLHOL Output low voltage, high drive, 5 mA, VDD >= 1.7 V VSS VSS+0.4 V VOLHOL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V IoL,SD Current at VSS+0.4 V, output set low, standard drive, VDD >= 2.7 V 6 10 15 mA IoL,HDL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V 3 □ □ mA IoH,HDL Current at VDD-0.4 V, output set high, standard drive, VDD >= 1.7 V 1 2 4 mA IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 □ 14 mA IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 □ 14 mA IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 1 1 1 1 1 1 1 1 1 1 1	V _{OH,HDH}	Output high voltage, high drive, 5 mA, VDD >= 2.7 V	VDD-0.4		VDD	V
VOLHOH Output low voltage, high drive, 5 mA, VDD >= 2.7 V VSS VSS-04 V VOLHOL Output low voltage, high drive, 3 mA, VDD >= 1.7 V VSS VSS+0.4 V IoL,5D Current at VSS+0.4 V, output set low, standard drive, VDD 1 2 4 mA IoL,HDL Current at VSS+0.4 V, output set low, high drive, VDD >= 2.7 V 6 10 15 mA IoL,HDL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V 3 2 4 mA IoH,5D Current at VDD-0.4 V, output set high, standard drive, VDD >= 1.7 V 6 9 14 mA IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 4 mA IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 9 19 nS IoH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 6 9 19 nS IoH,HDL Rise/fall time, standard drive mode, 10-90%, 25 pF load¹ 10 13 30 nS IoH,50pF Rise/fall time, standard drive mode, 10-90%, 50 pF load¹ <t< td=""><td>V_{OH,HDL}</td><td>Output high voltage, high drive, 3 mA, VDD >= 1.7 V</td><td>VDD-0.4</td><td></td><td>VDD</td><td>V</td></t<>	V _{OH,HDL}	Output high voltage, high drive, 3 mA, VDD >= 1.7 V	VDD-0.4		VDD	V
VOLHOL Output low voltage, high drive, 3 mA, VDD>= 1.7 V VSS VSS+0.4 V Io_LSD Current at VSS+0.4 V, output set low, standard drive, VDD 1 2 4 mA Io_LHDH Current at VSS+0.4 V, output set low, high drive, VDD>= 2.7 V 6 10 15 mA Io_LHDL Current at VSS+0.4 V, output set low, high drive, VDD>= 1.7 V 3 mA Io_H,SD Current at VDD-0.4 V, output set high, standard drive, VDD 1 2 4 mA Io_H,HDH Current at VDD-0.4 V, output set high, high drive, VDD>= 2.7 V 6 9 14 mA Io_H,HDL Current at VDD-0.4 V, output set high, high drive, VDD>= 1.7 V 3 mA Io_H,HDL Current at VDD-0.4 V, output set high, high drive, VDD>= 1.7 V 3 mA Io_H,HDL Current at VDD-0.4 V, output set high, high drive, VDD>= 1.7 V 3 mA Is_155pF Rise/fall time, standard drive mode, 10-90%, 15 pF load¹ 10 13 30 ns Is_HRF,15pF Rise/fall time, high	$V_{OL,SD}$	Output low voltage, standard drive, 0.5 mA, VDD ≥1.7	VSS		VSS+0.4	V
OLSD Current at VSS+0.4 V, output set low, standard drive, VDD 21.7 OL,HDH Current at VSS+0.4 V, output set low, high drive, VDD >= 2.7 V OL,HDH Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V OL,HDL Current at VDD-0.4 V, output set low, high drive, VDD >= 1.7 V OL,HDL Current at VDD-0.4 V, output set high, standard drive, VDD 1 2 4	V _{OL,HDH}	Output low voltage, high drive, 5 mA, VDD >= 2.7 V	VSS		VSS+0.4	V
21.7	$V_{OL,HDL}$	Output low voltage, high drive, 3 mA, VDD >= 1.7 V	VSS		VSS+0.4	V
IOL,HDH Current at VSS+0.4 V, output set low, high drive, VDD >= 2.7 V 6 10 15 mA IOL,HDL Current at VSS+0.4 V, output set low, high drive, VDD >= 1.7 V 3 mA IOH,SD Current at VDD-0.4 V, output set high, standard drive, VDD >= 2.7 V 6 9 14 mA IOH,HDH Current at VDD-0.4 V, output set high, high drive, VDD >= 2.7 V 3 mA IOH,HDL Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V 3 mA IRE,15pF Rise/fall time, standard drive mode, 10-90%, 15 pF load¹ 6 9 19 ns IRE,50pF Rise/fall time, standard drive mode, 10-90%, 25 pF load¹ 18 25 61 ns IHRE,15pF Rise/Fall time, high drive mode, 10-90%, 15 pF load¹ 2 4 8 ns IHRE,25pF Rise/Fall time, high drive mode, 10-90%, 25 pF load¹ 3 5 11 ns IHRE,25pF Rise/Fall time, high drive mode, 10-90%, 25 pF load¹ 5 8 19 ns IHRE,50pF Rise/Fall time, high drive mode, 10-90%, 50 pF load¹ </td <td>$I_{OL,SD}$</td> <td>Current at VSS+0.4 V, output set low, standard drive, VDD</td> <td>1</td> <td>2</td> <td>4</td> <td>mA</td>	$I_{OL,SD}$	Current at VSS+0.4 V, output set low, standard drive, VDD	1	2	4	mA
V V V V V V V V V V		≥1.7				
$l_{OL,HDL} \begin{array}{lllllllllllllllllllllllllllllllllll$	I _{OL,HDH}		6	10	15	mA
V I _{OH,SD} Current at VDD-0.4 V, output set high, standard drive, VDD $≥ 1.7$						
$l_{OH,SD}$ Current at VDD-0.4 V, output set high, standard drive, VDD ≥1.7124mA $l_{OH,HDH}$ Current at VDD-0.4 V, output set high, high drive, VDD >= 2.7 V6914mA $l_{OH,HDL}$ Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V3mA $t_{RF,15pF}$ Rise/fall time, standard drive mode, 10-90%, 15 pF load¹6919ns $t_{RF,25pF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load¹101330ns $t_{RF,50pF}$ Rise/fall time, standard drive mode, 10-90%, 50 pF load¹182561ns $t_{HRF,15pF}$ Rise/fall time, high drive mode, 10-90%, 15 pF load¹248ns $t_{HRF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load¹3511ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns	I _{OL,HDL}	to the second se	3			mA
≥1.7 $I_{OH,HDH} $						
$l_{OH,HDH}$ Current at VDD-0.4 V, output set high, high drive, VDD >= 2.7 V6914mA $l_{OH,HDL}$ Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V3mA $t_{RF,15pF}$ Rise/fall time, standard drive mode, 10-90%, 15 pF load¹6919ns $t_{RF,25pF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load¹101330ns $t_{RF,50pF}$ Rise/fall time, standard drive mode, 10-90%, 50 pF load¹182561ns $t_{HRF,15pF}$ Rise/Fall time, high drive mode, 10-90%, 15 pF load¹248ns $t_{HRF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load¹3511ns $t_{HRF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns	I _{OH,SD}		1	2	4	mA
V I _{OH,HDL} Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V t _{RF,15pF} Rise/fall time, standard drive mode, 10-90%, 15 pF load ¹ t _{RF,25pF} Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹ t _{RF,50pF} Rise/fall time, standard drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ t _{RF,50pF} Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹			_	_		
$I_{OH,HDL}$ Current at VDD-0.4 V, output set high, high drive, VDD >= 1.7 V3mA $t_{RF,1SpF}$ Rise/fall time, standard drive mode, 10-90%, 15 pF load¹6919ns $t_{RF,2SpF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load¹101330ns $t_{RF,50pF}$ Rise/fall time, standard drive mode, 10-90%, 50 pF load¹182561ns $t_{HRF,1SpF}$ Rise/Fall time, high drive mode, 10-90%, 15 pF load¹248ns $t_{HRF,2SpF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load¹3511ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load¹5819ns t_{PU} Pull-up resistance111316kΩ	I _{OH,HDH}		6	9	14	mA
V $t_{RF,15pF}$ Rise/fall time, standard drive mode, 10-90%, 15 pF load ¹ $t_{RF,25pF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹ $t_{RF,25pF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹ $t_{RF,50pF}$ Rise/fall time, standard drive mode, 10-90%, 50 pF load ¹ $t_{RF,15pF}$ Rise/Fall time, high drive mode, 10-90%, 15 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ $t_{RF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹			2			
tRF,15pF Rise/fall time, standard drive mode, 10-90%, 15 pF load¹ 6 9 19 ns tRF,25pF Rise/fall time, standard drive mode, 10-90%, 25 pF load¹ 10 13 30 ns tRF,50pF Rise/fall time, standard drive mode, 10-90%, 50 pF load¹ 18 25 61 ns tHRF,15pF Rise/Fall time, high drive mode, 10-90%, 15 pF load¹ 2 4 8 ns tHRF,25pF Rise/Fall time, high drive mode, 10-90%, 25 pF load¹ 3 5 11 ns tHRF,50pF Rise/Fall time, high drive mode, 10-90%, 50 pF load¹ 5 8 19 ns RPU Pull-up resistance 11 13 16 kΩ	IOH,HDL	, , , , , , , , , , , , , , , , , , , ,	3			mA
$t_{RF,2SpF}$ Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹ 10 13 30 ns $t_{RF,50pF}$ Rise/fall time, standard drive mode, 10-90%, 50 pF load ¹ 18 25 61 ns $t_{RF,50pF}$ Rise/fall time, high drive mode, 10-90%, 15 pF load ¹ 2 4 8 ns $t_{RF,2SpF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ 3 5 11 ns $t_{RF,2SpF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ 5 8 19 ns $t_{RF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ 5 8 19 ns t_{RPU} Pull-up resistance	•		6	0	10	nc
$t_{RF,50pF}$ Rise/Fall time, standard drive mode, 10-90%, 50 pF load ¹ 18 25 61 ns $t_{HRF,15pF}$ Rise/Fall time, high drive mode, 10-90%, 15 pF load ¹ 2 4 8 ns $t_{HRF,25pF}$ Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ 3 5 11 ns $t_{HRF,50pF}$ Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ 5 8 19 ns $t_{HRF,50pF}$ Pull-up resistance 11 13 16 $k\Omega$						
thref,15pF Rise/Fall time, high drive mode, 10-90%, 15 pF load ¹ 2 4 8 ns thref,25pF Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹ 3 5 11 ns thref,50pF Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹ 5 8 19 ns Rpu Pull-up resistance 11 13 16 $k\Omega$	t _{RF,25pF}	Rise/fall time, standard drive mode, 10-90%, 25 pF load ¹	10	13	30	ns
thref.25pf Rise/Fall time, high drive mode, 10-90%, 25 pF load 1 3 5 11 ns thref.25pf Rise/Fall time, high drive mode, 10-90%, 50 pF load 1 5 8 19 ns RPU Pull-up resistance 11 13 16 1 1	t _{RF,50pF}	Rise/fall time, standard drive mode, 10-90%, 50 pF load ¹	18	25	61	ns
three, Foother Rise/Fall time, high drive mode, 10-90%, 50 pF load 1 5 8 19 ns 1 Rpu Pull-up resistance 11 13 16 k Ω	t _{HRF,15pF}	Rise/Fall time, high drive mode, 10-90%, 15 pF load ¹	2	4	8	ns
R_{PU} Pull-up resistance 11 13 16 $k\Omega$	t _{HRF,25pF}	Rise/Fall time, high drive mode, 10-90%, 25 pF load ¹	3	5	11	ns
	t _{HRF,50pF}	Rise/Fall time, high drive mode, 10-90%, 50 pF load ¹	5	8	19	ns
	R _{PU}	Pull-up resistance	11	13	16	kΩ
npD ruii-uowii resistante 11 13 16 KΩ	R _{PD}	Pull-down resistance	11	13	16	kΩ
C _{PAD} Pad capacitance 3 pF		Pad capacitance		3		pF



¹ Rise and fall times based on simulations

6.5 GPIOTE — GPIO tasks and events

The GPIO tasks and events (GPIOTE) module provides functionality for accessing GPIO pins using tasks and events. Each GPIOTE channel can be assigned to one pin.

A GPIOTE block enables GPIOs to generate events on pin state change which can be used to carry out tasks through the PPI system. A GPIO can also be driven to change state on system events using the PPI system. Low power detection of pin state changes is possible when in System ON or System OFF.

Instance	Number of GPIOTE channels
GPIOTE	8

Table 36: GPIOTE properties

Up to three tasks can be used in each GPIOTE channel for performing write operations to a pin. Two tasks are fixed (SET and CLR), and one (OUT) is configurable to perform following operations:

- Set
- Clear
- Toggle

An event can be generated in each GPIOTE channel from one of the following input conditions:

- · Rising edge
- Falling edge
- Any change

6.5.1 Pin events and tasks

The GPIOTE module has a number of tasks and events that can be configured to operate on individual GPIO pins.

The tasks (SET[n], CLR[n] and OUT[n]) can be used for writing to individual pins, and the events (IN[n]) can be generated from changes occurring at the inputs of individual pins.

The SET task will set the pin selected in GPIOTE.CONFIG[n].PSEL to high.

The CLR task will set the pin low.

The effect of the OUT task on the pin is configurable in CONFIG[n].POLARITY, and can either set the pin high, set it low, or toggle it.

The tasks and events are configured using the CONFIG[n] registers. Every set of SET, CLR and OUT[n] tasks and IN[n] events has one CONFIG[n] register associated with it.

As long as a SET[n], CLR[n] and OUT[n] task or an IN[n] event is configured to control a pin **n**, the pin's output value will only be updated by the GPIOTE module. The pin's output value as specified in the GPIO will therefore be ignored as long as the pin is controlled by GPIOTE. Attempting to write a pin as a normal GPIO pin will have no effect. When the GPIOTE is disconnected from a pin, see MODE field in CONFIG[n] register, the associated pin will get the output and configuration values specified in the GPIO module.

When conflicting tasks are triggered simultaneously (i.e. during the same clock cycle) in one channel, the precedence of the tasks will be as described in Task priorities on page 102.



Priority	Task	
1	ОИТ	
2	CLR	
3	SET	

Table 37: Task priorities

When setting the CONFIG[n] registers, MODE=Disabled does not have the same effect as MODE=Task and POLARITY=None. In the latter case, a CLR or SET task occurring at the exact same time as OUT will end up with no change on the pin, according to the priorities described in the table above.

When a GPIOTE channel is configured to operate on a pin as a task, the initial value of that pin is configured in the OUTINIT field of CONFIG[n].

6.5.2 Port event

PORT is an event that can be generated from multiple input pins using the GPIO DETECT signal.

The event will be generated on the rising edge of the DETECT signal. See GPIO — General purpose input/output on page 91 for more information about the DETECT signal.

Putting the system into System ON IDLE while DETECT is high will not cause DETECT to wake the system up again. Make sure to clear all DETECT sources before entering sleep. If the LATCH register is used as a source, if any bit in LATCH is still high after clearing all or part of the register (for instance due to one of the PINx.DETECT signal still high), a new rising edge will be generated on DETECT, see Pin configuration on page 92.

Trying to put the system to System OFF while DETECT is high will cause a wakeup from System OFF reset.

This feature is always enabled although the peripheral itself appears to be IDLE, that is, no clocks or other power intensive infrastructure have to be requested to keep this feature enabled. This feature can therefore be used to wake up the CPU from a WFI or WFE type sleep in System ON with all peripherals and the CPU idle, that is, lowest power consumption in System ON mode.

In order to prevent spurious interrupts from the PORT event while configuring the sources, the user shall first disable interrupts on the PORT event (through INTENCLR.PORT), then configure the sources (PIN_CNF[n].SENSE), clear any potential event that could have occurred during configuration (write '1' to EVENTS_PORT), and finally enable interrupts (through INTENSET.PORT).

6.5.3 Tasks and events pin configuration

Each GPIOTE channel is associated with one physical GPIO pin through the CONFIG.PSEL field.

When Event mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an input, overriding the DIR setting in GPIO. Similarly, when Task mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an output overriding the DIR setting and OUT value in GPIO. When Disabled is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will use its configuration from the PIN[n].CNF registers in GPIO.

Only one GPIOTE channel can be assigned to one physical pin. Failing to do so may result in unpredictable behavior.



6.5.4 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000D000	GPIOTE	GPIOTE0	S	NA	Secure GPIO tasks and events	:
0x40031000	GPIOTE	GPIOTE1	NS	NA	Non Secure GPIO tasks and	
					events	

Table 38: Instances

Register	Offset	Security	Description
TASKS_OUT[0]	0x000		Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is configured in
			CONFIG[0].POLARITY.
TASKS_OUT[1]	0x004		Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is configured in
			CONFIG[1].POLARITY.
TASKS_OUT[2]	0x008		Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is configured in
			CONFIG[2].POLARITY.
TASKS_OUT[3]	0x00C		Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is configured in
			CONFIG[3].POLARITY.
TASKS_OUT[4]	0x010		Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is configured in
			CONFIG[4].POLARITY.
TASKS_OUT[5]	0x014		Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is configured in
			CONFIG[5].POLARITY.
TASKS_OUT[6]	0x018		Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is configured in
			CONFIG[6].POLARITY.
TASKS_OUT[7]	0x01C		Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is configured in
			CONFIG[7].POLARITY.
TASKS_SET[0]	0x030		Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is to set it high.
TASKS_SET[1]	0x034		Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is to set it high.
TASKS_SET[2]	0x038		Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is to set it high.
TASKS_SET[3]	0x03C		Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is to set it high.
TASKS_SET[4]	0x040		Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is to set it high.
TASKS_SET[5]	0x044		Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is to set it high.
TASKS_SET[6]	0x048		Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is to set it high.
TASKS_SET[7]	0x04C		Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is to set it high.
TASKS_CLR[0]	0x060		Task for writing to pin specified in CONFIG[0].PSEL. Action on pin is to set it low.
TASKS_CLR[1]	0x064		Task for writing to pin specified in CONFIG[1].PSEL. Action on pin is to set it low.
TASKS_CLR[2]	0x068		Task for writing to pin specified in CONFIG[2].PSEL. Action on pin is to set it low.
TASKS_CLR[3]	0x06C		Task for writing to pin specified in CONFIG[3].PSEL. Action on pin is to set it low.
TASKS_CLR[4]	0x070		Task for writing to pin specified in CONFIG[4].PSEL. Action on pin is to set it low.
TASKS_CLR[5]	0x074		Task for writing to pin specified in CONFIG[5].PSEL. Action on pin is to set it low.
TASKS_CLR[6]	0x078		Task for writing to pin specified in CONFIG[6].PSEL. Action on pin is to set it low.
TASKS_CLR[7]	0x07C		Task for writing to pin specified in CONFIG[7].PSEL. Action on pin is to set it low.
SUBSCRIBE_OUT[0]	0x080		Subscribe configuration for task OUT[0]
SUBSCRIBE_OUT[1]	0x084		Subscribe configuration for task OUT[1]
SUBSCRIBE_OUT[2]	0x088		Subscribe configuration for task OUT[2]
SUBSCRIBE_OUT[3]	0x08C		Subscribe configuration for task OUT[3]
SUBSCRIBE_OUT[4]	0x090		Subscribe configuration for task OUT[4]
SUBSCRIBE_OUT[5]	0x094		Subscribe configuration for task OUT[5]
SUBSCRIBE_OUT[6]	0x098		Subscribe configuration for task OUT[6]
SUBSCRIBE_OUT[7]	0x09C		Subscribe configuration for task OUT[7]
SUBSCRIBE_SET[0]	0x0B0		Subscribe configuration for task SET[0]
SUBSCRIBE_SET[1]	0x0B4		Subscribe configuration for task SET[1]
SUBSCRIBE_SET[2]	0x0B8		Subscribe configuration for task SET[2]



Register	Offset	Security	Description
SUBSCRIBE_SET[3]	0x0BC		Subscribe configuration for task SET[3]
SUBSCRIBE_SET[4]	0x0C0		Subscribe configuration for task SET[4]
SUBSCRIBE_SET[5]	0x0C4		Subscribe configuration for task SET[5]
SUBSCRIBE_SET[6]	0x0C8		Subscribe configuration for task SET[6]
SUBSCRIBE SET[7]	0x0CC		Subscribe configuration for task SET[7]
SUBSCRIBE_CLR[0]	0x0E0		Subscribe configuration for task CLR[0]
SUBSCRIBE_CLR[1]	0x0E4		Subscribe configuration for task CLR[1]
SUBSCRIBE_CLR[2]	0x0E8		Subscribe configuration for task CLR[2]
SUBSCRIBE_CLR[3]	0x0EC		Subscribe configuration for task CLR[3]
SUBSCRIBE_CLR[4]	0x0F0		Subscribe configuration for task CLR[4]
SUBSCRIBE_CLR[5]	0x0F4		Subscribe configuration for task CLR[5]
SUBSCRIBE_CLR[6]	0x0F8		Subscribe configuration for task CLR[6]
SUBSCRIBE_CLR[7]	0x0FC		Subscribe configuration for task CLR[7]
EVENTS_IN[0]	0x100		Event generated from pin specified in CONFIG[0].PSEL
EVENTS_IN[1]	0x104		Event generated from pin specified in CONFIG[1].PSEL
EVENTS_IN[2]	0x108		Event generated from pin specified in CONFIG[2].PSEL
EVENTS_IN[3]	0x10C		Event generated from pin specified in CONFIG[3].PSEL
EVENTS_IN[4]	0x110		Event generated from pin specified in CONFIG[4].PSEL
EVENTS_IN[5]	0x114		Event generated from pin specified in CONFIG[5].PSEL
EVENTS_IN[6]	0x118		Event generated from pin specified in CONFIG[6].PSEL
EVENTS_IN[7]	0x11C		Event generated from pin specified in CONFIG[7].PSEL
EVENTS_PORT	0x17C		Event generated from multiple input GPIO pins with SENSE mechanism enabled
PUBLISH_IN[0]	0x180		Publish configuration for event IN[0]
PUBLISH_IN[1]	0x184		Publish configuration for event IN[1]
PUBLISH_IN[2]	0x188		Publish configuration for event IN[2]
PUBLISH_IN[3]	0x18C		Publish configuration for event IN[3]
PUBLISH_IN[4]	0x190		Publish configuration for event IN[4]
PUBLISH_IN[5]	0x194		Publish configuration for event IN[5]
PUBLISH_IN[6]	0x198		Publish configuration for event IN[6]
PUBLISH_IN[7]	0x19C		Publish configuration for event IN[7]
PUBLISH_PORT	0x1FC		Publish configuration for event PORT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
CONFIG[0]	0x510		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[1]	0x514		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[2]	0x518		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[3]	0x51C		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[4]	0x520		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[5]	0x524		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[6]	0x528		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event
CONFIG[7]	0x52C		Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event

Table 39: Register overview

6.5.4.1 TASKS_OUT[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in CONFIG[n].POLARITY.



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W TASKS_OUT			Task for writing to pin specified in CONFIG[n].PSEL. Action
			on pin is configured in CONFIG[n].POLARITY.
	Trigger	1	Trigger task

6.5.4.2 TASKS_SET[n] (n=0..7)

Address offset: $0x030 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it high.

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W TASKS_SET			Task for writing to pin specified in CONFIG[n].PSEL. Action
			on pin is to set it high.
	Trigger	1	Trigger task

6.5.4.3 TASKS_CLR[n] (n=0..7)

Address offset: $0x060 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it low.

Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A W TASKS_	CLR		Task for writing to pin specified in CONFIG[n].PSEL. Action
			on pin is to set it low.
	Trigger	1	Trigger task

6.5.4.4 SUBSCRIBE_OUT[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task OUT[n]

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task OUT[n] will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.5.4.5 SUBSCRIBE_SET[n] (n=0..7)

Address offset: $0x0B0 + (n \times 0x4)$

Subscribe configuration for task SET[n]



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task SET[n] will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.5.4.6 SUBSCRIBE_CLR[n] (n=0..7)

Address offset: $0x0E0 + (n \times 0x4)$

Subscribe configuration for task CLR[n]

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task CLR[n] will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.5.4.7 EVENTS_IN[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

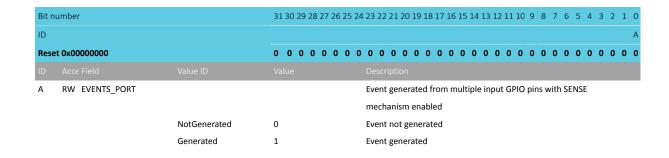
Event generated from pin specified in CONFIG[n].PSEL

Bit n	umber		31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_IN			Event generated from pin specified in CONFIG[n].PSEL
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.5.4.8 EVENTS_PORT

Address offset: 0x17C

Event generated from multiple input GPIO pins with SENSE mechanism enabled





6.5.4.9 PUBLISH_IN[n] (n=0..7)

Address offset: $0x180 + (n \times 0x4)$

Publish configuration for event IN[n]

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event IN[n] will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.5.4.10 PUBLISH_PORT

Address offset: 0x1FC

Publish configuration for event PORT

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event PORT will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.5.4.11 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		T	HGFEDCBA
Reset 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			Description
A-H RW IN[i] (i=07)			Write '1' to enable interrupt for event IN[i]
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
I RW PORT			Write '1' to enable interrupt for event PORT
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.5.4.12 INTENCLR

Address offset: 0x308

Disable interrupt



	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	1	HGFEDCBA
	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Description
		Write '1' to disable interrupt for event IN[i]
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled
		Write '1' to disable interrupt for event PORT
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled
	Clear Disabled Enabled Clear Disabled	

6.5.4.13 CONFIG[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$

Configuration for OUT[n], SET[n] and CLR[n] tasks and IN[n] event

Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E DD BBBB AA
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW MODE			Mode
		Disabled	0	Disabled. Pin specified by PSEL will not be acquired by the
				GPIOTE module.
		Event	1	Event mode
				The pin specified by PSEL will be configured as an input and
				the IN[n] event will be generated if operation specified in
				POLARITY occurs on the pin.
		Task	3	Task mode
				The GPIO specified by PSEL will be configured as an output
				and triggering the SET[n], CLR[n] or OUT[n] task will
				perform the operation specified by POLARITY on the pin.
				When enabled as a task the GPIOTE module will acquire the
				pin and the pin can no longer be written as a regular output
				pin from the GPIO module.
В	RW PSEL		[031]	GPIO number associated with SET[n], CLR[n] and OUT[n]
				tasks and IN[n] event
D	RW POLARITY			When In task mode: Operation to be performed on output
				when OUT[n] task is triggered. When In event mode:
				Operation on input that shall trigger IN[n] event.
		None	0	Task mode: No effect on pin from OUT[n] task. Event mode:
				no IN[n] event generated on pin activity.
		LoToHi	1	Task mode: Set pin from OUT[n] task. Event mode: Generate
				IN[n] event when rising edge on pin.
		HiToLo	2	Task mode: Clear pin from OUT[n] task. Event mode:
				Generate IN[n] event when falling edge on pin.
		Toggle	3	Task mode: Toggle pin from OUT[n]. Event mode: Generate
				IN[n] when any change on pin.
Ε	RW OUTINIT			When in task mode: Initial value of the output when the
				GPIOTE channel is configured. When in event mode: No
				effect.
		Low	0	Task mode: Initial value of pin before task triggering is low



	High		Task mode: Initial value of pin before task triggering is high
ID Acce Field			Description
Reset 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID			E DD BBBBB AA
Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.5.5 Electrical specification

6.6 IPC — Inter-Processor Communication

The IPC peripheral is used to send and receive events between processors in the system.

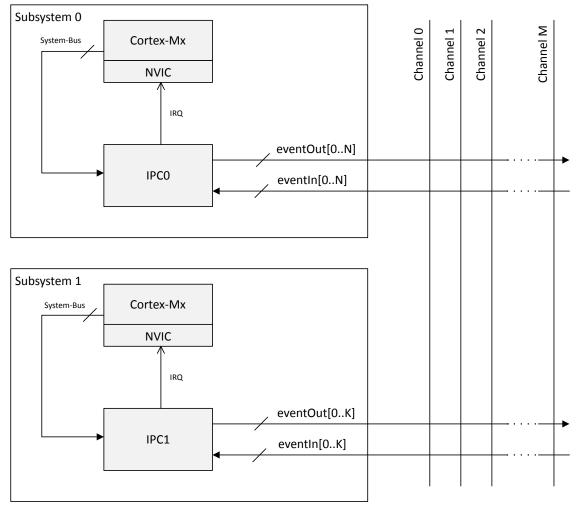


Figure 18: IPC block diagram

Functional description

IPC block diagram on page 109 illustrates the Inter-Processor Communication (IPC) peripheral. In a multi-core system, every CPU instance shall have one dedicated IPC peripheral. The IPC peripheral can be used to send and receive events to and from other IPC peripherals. An instance of the IPC peripheral can have #N send tasks and #N receive events. A single send task can be configured to signal an event on one or more channels, and a receive event can be configured to listen on one or more channels. The channels that are triggered in a send task can be configured through the SEND_CNF registers, and the channels that trigger a receive event is configured through the RECEIVE_CNF registers. A send task can be viewed as broadcasting events onto one or more channels, and a receive event can be seen as subscribing to a

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subset of channels. It is possible for multiple IPCs to trigger events onto the same channel at the same time, in this case it will look as a single event from the IPC subscriber.

The number of channels and send/receive events per IPC are implementation specific, and needs to be looked up in the reference manual for your specific device.

An event itself often does not contain any relevant information itself other than to signal that "something has occurred". Shared memory can be used to carry additional information between processors, e.g. in the form of command/event queues. It is up to software to assign a logical functionality to a channel. For instance one channel can be used to signal that a command is ready to be executed and any processor in the system can subscribe to that particular channel and decode/execute the command.

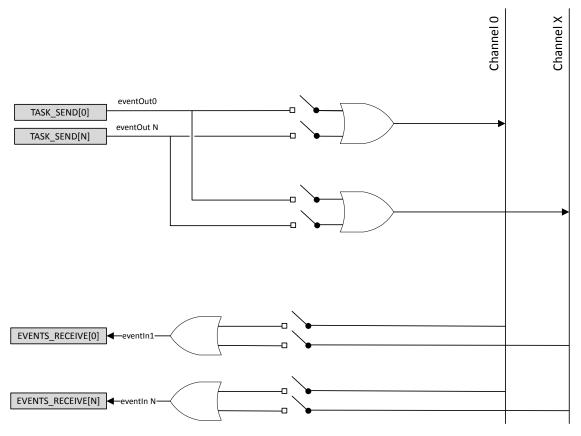


Figure 19: IPC SEND_CNF and RECEIVE_CNF

IPC SEND_CNF and RECEIVE_CNF on page 110 illustrates how the SEND_CNF and RECEIVE_CNF registers work. A send task be connected to all channels, and a receive event can be connected to all channels.

6.6.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5002A000	IPC	IPC:S	US	NA	Interprocessor	
0x4002A000	irc	IPC : NS	03	NA .	communication	

Table 40: Instances

Register	Offset	Security	Description
TASKS_SEND[0]	0x000		Trigger events on channel enabled in SEND_CNF[0].
TASKS_SEND[1]	0x004		Trigger events on channel enabled in SEND_CNF[1].
TASKS_SEND[2]	0x008		Trigger events on channel enabled in SEND_CNF[2].
TASKS_SEND[3]	0x00C		Trigger events on channel enabled in SEND_CNF[3].



Register	Offset	Security	Description
TASKS_SEND[4]	0x010		Trigger events on channel enabled in SEND_CNF[4].
TASKS_SEND[5]	0x014		Trigger events on channel enabled in SEND_CNF[5].
TASKS_SEND[6]	0x018		Trigger events on channel enabled in SEND_CNF[6].
TASKS SEND[7]	0x01C		Trigger events on channel enabled in SEND_CNF[7].
SUBSCRIBE_SEND[0]	0x080		Subscribe configuration for task SEND[0]
SUBSCRIBE_SEND[1]	0x084		Subscribe configuration for task SEND[1]
SUBSCRIBE_SEND[2]	0x088		Subscribe configuration for task SEND[2]
SUBSCRIBE_SEND[3]	0x08C		Subscribe configuration for task SEND[3]
SUBSCRIBE SEND[4]	0x090		Subscribe configuration for task SEND[4]
SUBSCRIBE_SEND[5]	0x094		Subscribe configuration for task SEND[5]
SUBSCRIBE_SEND[6]	0x098		Subscribe configuration for task SEND[6]
SUBSCRIBE_SEND[7]	0x09C		Subscribe configuration for task SEND[7]
EVENTS_RECEIVE[0]	0x100		Event received on one or more of the enabled channels in RECEIVE_CNF[n].
EVENTS_RECEIVE[1]	0x104		Event received on one or more of the enabled channels in RECEIVE CNF[n].
EVENTS_RECEIVE[2]	0x108		Event received on one or more of the enabled channels in RECEIVE CNF[n].
EVENTS_RECEIVE[3]	0x10C		Event received on one or more of the enabled channels in RECEIVE_CNF[n].
EVENTS RECEIVE[4]	0x10C		Event received on one or more of the enabled channels in RECEIVE_CNN [n].
EVENTS RECEIVE[5]	0x110		Event received on one or more of the enabled channels in RECEIVE_CNN [n].
EVENTS RECEIVE[6]	0x114 0x118		Event received on one or more of the enabled channels in RECEIVE_CNF[n].
EVENTS RECEIVE[7]	0x11C		Event received on one or more of the enabled channels in RECEIVE_CNF[n].
PUBLISH_RECEIVE[0]	0x11C		Publish configuration for event RECEIVE[0]
PUBLISH_RECEIVE[1]	0x180		Publish configuration for event RECEIVE[1]
_	0x184 0x188		Publish configuration for event RECEIVE[1] Publish configuration for event RECEIVE[2]
PUBLISH_RECEIVE[2]	0x18C		* ' ' '
PUBLISH_RECEIVE[3]	0x18C 0x190		Publish configuration for event RECEIVE[3] Publish configuration for event RECEIVE[4]
PUBLISH_RECEIVE[4]	0x190 0x194		-
PUBLISH_RECEIVE[5]	0x194 0x198		Publish configuration for event RECEIVE[5] Publish configuration for event RECEIVE[6]
PUBLISH_RECEIVE[6]	0x198 0x19C		*
PUBLISH_RECEIVE[7]			Publish configuration for event RECEIVE[7]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
SEND_CNF[0]	0x510		Send event configuration for TASKS_SEND[0].
SEND_CNF[1]	0x514		Send event configuration for TASKS_SEND[1].
SEND_CNF[2]	0x518		Send event configuration for TASKS_SEND[2].
SEND_CNF[3]	0x51C		Send event configuration for TASKS_SEND[3].
SEND_CNF[4]	0x520		Send event configuration for TASKS_SEND[4].
SEND_CNF[5]	0x524		Send event configuration for TASKS_SEND[5].
SEND_CNF[6]	0x528		Send event configuration for TASKS_SEND[6].
SEND_CNF[7]	0x52C		Send event configuration for TASKS_SEND[7].
RECEIVE_CNF[0]	0x590		Receive event configuration for EVENTS_RECEIVE[0].
RECEIVE_CNF[1]	0x594		Receive event configuration for EVENTS_RECEIVE[1].
RECEIVE_CNF[2]	0x598		Receive event configuration for EVENTS_RECEIVE[2].
RECEIVE_CNF[3]	0x59C		Receive event configuration for EVENTS_RECEIVE[3].
RECEIVE_CNF[4]	0x5A0		Receive event configuration for EVENTS_RECEIVE[4].
RECEIVE_CNF[5]	0x5A4		Receive event configuration for EVENTS_RECEIVE[5].
RECEIVE_CNF[6]	0x5A8		Receive event configuration for EVENTS_RECEIVE[6].
RECEIVE_CNF[7]	0x5AC		Receive event configuration for EVENTS_RECEIVE[7].
GPMEM[0]	0x610		General purpose memory.
GPMEM[1]	0x614		General purpose memory.
GPMEM[2]	0x618		General purpose memory.
GPMEM[3]	0x61C		General purpose memory.

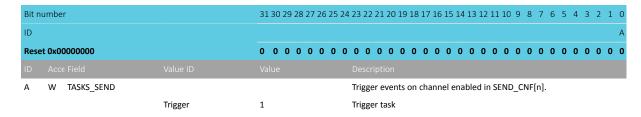
Table 41: Register overview



6.6.1.1 TASKS_SEND[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

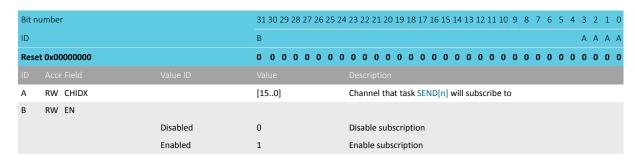
Trigger events on channel enabled in SEND_CNF[n].



6.6.1.2 SUBSCRIBE SEND[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

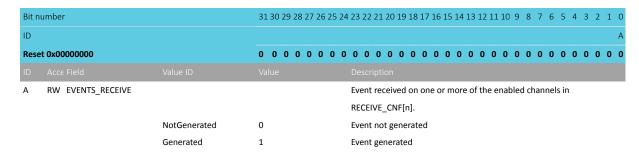
Subscribe configuration for task SEND[n]



6.6.1.3 EVENTS_RECEIVE[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

Event received on one or more of the enabled channels in RECEIVE_CNF[n].



6.6.1.4 PUBLISH_RECEIVE[n] (n=0..7)

Address offset: $0x180 + (n \times 0x4)$

Publish configuration for event RECEIVE[n]



Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event RECEIVE[n] will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.6.1.5 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			HGFEDCBA
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-H RW RECEIVE[i] (i=07)			Enable or disable interrupt for event RECEIVE[i]
	Disabled	0	Disable
	Enabled	1	Enable

6.6.1.6 INTENSET

Address offset: 0x304

Enable interrupt

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				HGFEDCBA
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
А-Н	RW RECEIVE[i] (i=07)			Write '1' to enable interrupt for event RECEIVE[i]
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.6.1.7 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			HGFEDCBA
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A-H RW RECEIVE[i] (i=07)			Write '1' to disable interrupt for event RECEIVE[i]
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled



6.6.1.8 INTPEND

Address offset: 0x30C Pending interrupts

Bit number	31 30 29 28 27 26 25 24 23	3 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		HGFEDCBA
Reset 0x00000000	0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		escription
A-H R RECEIVE[i] (i=07)	Re	ead pending status of interrupt for event RECEIVE[i]
NotPending	0 Re	ead: Not pending
Pending	1 R	ead: Pending

6.6.1.9 SEND_CNF[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$

Send event configuration for TASKS_SEND[n].

Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A-H RW CHEN[i] (i=07)			Enable broadcasting on channel i.
	Disable	0	Disable broadcast.
	Enable	1	Enable broadcast.

6.6.1.10 RECEIVE_CNF[n] (n=0..7)

Address offset: $0x590 + (n \times 0x4)$

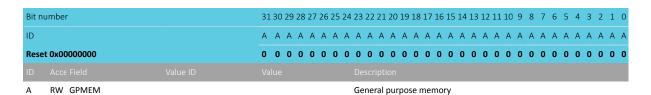
Receive event configuration for EVENTS_RECEIVE[n].

Bit nu	ımber		31	30	29	28	27 2	26 2	5 2	24 2	23 :	22	21	20	19	18	17	16	15	14	13	12 :	.1 1	0 9	8	7	6	5	4	3	2	1 0
ID																										Н	G	F	Ε	D	С	ВА
Rese	0x00000000		0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0
ID																																
A-H	RW CHEN[i] (i=07)									E	Ena	able	e su	ıbs	crip	tio	n t	о с	har	nne	l i.											
		Disable	0							[Dis	abl	e e	ver	nts.																	
		Enable	1							E	Ena	able	e ev	/en	ts.																	

6.6.1.11 GPMEM[n] (n=0..3)

Address offset: $0x610 + (n \times 0x4)$

General purpose memory.





$6.7 \, \text{l}^2\text{S}$ — Inter-IC sound interface

The I²S (Inter-IC Sound) module, supports the original two-channel I²S format, and left or right-aligned formats. It implements EasyDMA for sample transfer directly to and from RAM without CPU intervention.

The I²S peripheral has the following main features:

- Master and Slave mode
- Simultaneous bi-directional (TX and RX) audio streaming
- Original I²S and left- or right-aligned format
- 8, 16 and 24-bit sample width
- · Low-jitter Master Clock generator
- Various sample rates

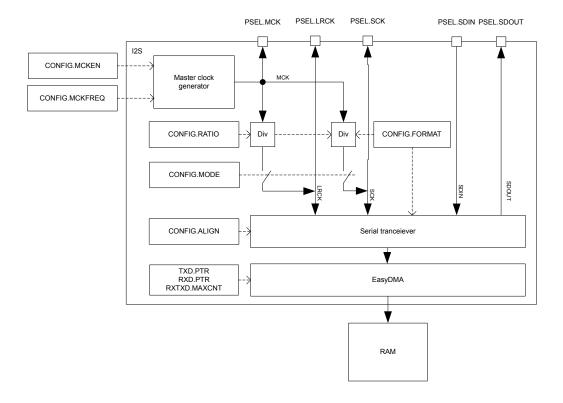


Figure 20: I²S master

6.7.1 Mode

The I²S protocol specification defines two modes of operation, Master and Slave.

The I²S mode decides which of the two sides (Master or Slave) shall provide the clock signals LRCK and SCK, and these signals are always supplied by the Master to the Slave.

6.7.2 Transmitting and receiving

The I²S module supports both transmission (TX) and reception (RX) of serial data. In both cases the serial data is shifted synchronously to the clock signals SCK and LRCK.

TX data is written to the SDOUT pin on the falling edge of SCK, and RX data is read from the SDIN pin on the rising edge of SCK. The most significant bit (MSB) is always transmitted first.



TX and RX are available in both Master and Slave modes and can be enabled/disabled independently in the CONFIG.TXEN on page 130 and CONFIG.RXEN on page 129.

Transmission and/or reception is started by triggering the START task. When started and transmission is enabled (in CONFIG.TXEN on page 130), the TXPTRUPD event will be generated for every RXTXD.MAXCNT on page 133 number of transmitted data words (containing one or more samples). Similarly, when started and reception is enabled (in CONFIG.RXEN on page 129), the RXPTRUPD event will be generated for every RXTXD.MAXCNT on page 133 received data words.

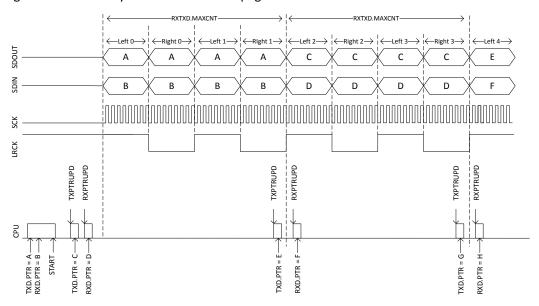


Figure 21: Transmitting and receiving. CONFIG.FORMAT = Aligned, CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo, RXTXD.MAXCNT = 1.

6.7.3 Left right clock (LRCK)

The Left Right Clock (LRCK), often referred to as "word clock", "sample clock" or "word select" in I²S context, is the clock defining the frames in the serial bit streams sent and received on SDOUT and SDIN, respectively.

In I2S mode, each frame contains one left and right sample pair, with the left sample being transferred during the low half period of LRCK followed by the right sample being transferred during the high period of LRCK.

In Aligned mode, each frame contains one left and right sample pair, with the left sample being transferred during the high half period of LRCK followed by the right sample being transferred during the low period of LRCK.

Consequently, the LRCK frequency is equivalent to the audio sample rate.

When operating in Master mode, the LRCK is generated from the MCK, and the frequency of LRCK is then given as:

```
LRCK = MCK / CONFIG.RATIO
```

LRCK always toggles around the falling edge of the serial clock SCK.

6.7.4 Serial clock (SCK)

The serial clock (SCK), often referred to as the serial bit clock, pulses once for each data bit being transferred on the serial data lines SDIN and SDOUT.



When operating in Master mode the SCK is generated from the MCK, and the frequency of SCK is then given as:

```
SCK = 2 * LRCK * CONFIG.SWIDTH
```

The falling edge of the SCK falls on the toggling edge of LRCK.

When operating in Slave mode SCK is provided by the external I²S master.

6.7.5 Master clock (MCK)

The master clock (MCK) is the clock from which LRCK and SCK are derived when operating in Master mode.

The MCK is generated by an internal MCK generator. This generator always needs to be enabled when in Master mode, but the generator can also be enabled when in Slave mode. Enabling the generator when in slave mode can be useful in the case where the external Master is not able to generate its own master clock.

The MCK generator is enabled/disabled in the register CONFIG.MCKEN on page 130, and the generator is started or stopped by the START or STOP tasks.

In Master mode the LRCK and the SCK frequencies are closely related, as both are derived from MCK and set indirectly through CONFIG.RATIO on page 131 and CONFIG.SWIDTH on page 131.

When configuring these registers, the user is responsible for fulfilling the following requirements:

1. SCK frequency can never exceed the MCK frequency, which can be formulated as:

```
CONFIG.RATIO >= 2 * CONFIG.SWIDTH
```

2. The MCK/LRCK ratio shall be a multiple of 2 * CONFIG.SWIDTH, which can be formulated as:

```
Integer = (CONFIG.RATIO / (2 * CONFIG.SWIDTH))
```

The MCK signal can be routed to an output pin (specified in PSEL.MCK) to supply external I²S devices that require the MCK to be supplied from the outside.

When operating in Slave mode, the I²S module does not use the MCK and the MCK generator does not need to be enabled.

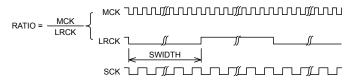


Figure 22: Relation between RATIO, MCK and LRCK.



Desired LRCK [Hz]	CONFIG.SWID	CONFIG.RATIO	CONFIG.MCKF	MCK [Hz]	LRCK [Hz]	LRCK error [%]
16000	16Bit	32X	32MDIV63	507936.5	15873.0	-0.8
16000	16Bit	64X	32MDIV31	1032258.1	16129.0	0.8
16000	16Bit	256X	32MDIV8	4000000.0	15625.0	-2.3
32000	16Bit	32X	32MDIV31	1032258.1	32258.1	0.8
32000	16Bit	64X	32MDIV16	2000000.0	31250.0	-2.3
44100	16Bit	32X	32MDIV23	1391304.3	43478.3	-1.4
44100	16Bit	64X	32MDIV11	2909090.9	45454.5	3.1

Table 42: Configuration examples

6.7.6 Width, alignment and format

The CONFIG.SWIDTH register primarily defines the sample width of the data written to memory. In master mode, it then also sets the amount of bits per frame. In Slave mode it controls padding/trimming if required. Left, right, transmitted, and received samples always have the same width. The CONFIG.FORMAT register specifies the position of the data frames with respect to the LRCK edges in both Master and Slave modes.

When using I²S format, the first bit in a half-frame (containing one left or right sample) gets sampled on the second rising edge of the SCK after a LRCK edge. When using Aligned mode, the first bit in a half-frame gets sampled on the first rising edge of SCK following a LRCK edge.

For data being received on SDIN the sample value can be either right or left-aligned inside a half-frame, as specified in CONFIG.ALIGN on page 131. CONFIG.ALIGN on page 131 affects only the decoding of the incoming samples (SDIN), while the outgoing samples (SDOUT) are always left-aligned (or justified).

When using left-alignment, each half-frame starts with the MSB of the sample value (both for data being sent on SDOUT and received on SDIN).

When using right-alignment, each half-frame of data being received on SDIN ends with the LSB of the sample value, while each half-frame of data being sent on SDOUT starts with the MSB of the sample value (same as for left-alignment).

In Master mode, the size of a half-frame (in number of SCK periods) equals the sample width (in number of bits), and in this case the alignment setting does not care as each half-frame in any case will start with the MSB and end with the LSB of the sample value.

In slave mode, however, the sample width does not need to equal the frame size. This means you might have extra or fewer SCK pulses per half-frame than what the sample width specified in CONFIG.SWIDTH requires.

In the case where we use **left-alignment** and the number of SCK pulses per half-frame is **higher** than the sample width, the following will apply:

- For data received on SDIN, all bits after the LSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0.

In the case where we use **left-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

Data sent and received on SDOUT and SDIN will be truncated with the LSBs being removed first.

In the case where we use **right-alignment** and the number of SCK pulses per frame is **higher** than the sample width, the following will apply:



- For data received on SDIN, all bits before the MSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0 (same behavior as for left-alignment).

In the case where we use **right-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

- Data received on SDIN will be sign-extended to "sample width" number of bits before being written to memory.
- Data sent on SDOUT will be truncated with the LSBs being removed first (same behavior as for leftalignment).

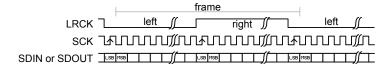


Figure 23: 1²S format. CONFIG.SWIDTH equalling half-frame size.

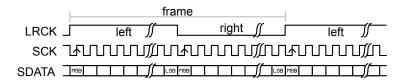


Figure 24: Aligned format. CONFIG.SWIDTH equalling half-frame size.

6.7.7 EasyDMA

The I²S module implements EasyDMA for accessing internal Data RAM without CPU intervention.

The source and destination pointers for the TX and RX data are configured in TXD.PTR on page 132 and RXD.PTR on page 132. The memory pointed to by these pointers will only be read or written when TX or RX are enabled in CONFIG.TXEN on page 130 and CONFIG.RXEN on page 129.

The addresses written to the pointer registers TXD.PTR on page 132 and RXD.PTR on page 132 are double-buffered in hardware, and these double buffers are updated for every RXTXD.MAXCNT on page 133 words (containing one or more samples) read/written from/to memory. The events TXPTRUPD and RXPTRUPD are generated whenever the TXD.PTR and RXD.PTR are transferred to these double buffers.

If TXD.PTR on page 132 is not pointing to the Data RAM region when transmission is enabled, or RXD.PTR on page 132 is not pointing to the Data RAM region when reception is enabled, an EasyDMA transfer may result in a HardFault and/or memory corruption. See Memory on page 20 for more information about the different memory regions.

Due to the nature of I²S, where the number of transmitted samples always equals the number of received samples (at least when both TX and RX are enabled), one common register RXTXD.MAXCNT on page 133 is used for specifying the sizes of these two memory buffers. The size of the buffers is specified in a number of 32-bit words. Such a 32-bit memory word can either contain four 8-bit samples, two 16-bit samples or one right-aligned 24-bit sample sign extended to 32 bit.

In stereo mode (CONFIG.CHANNELS=Stereo), the samples are stored as "left and right sample pairs" in memory. Figure Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo. on page 120, Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo. on page 120 and Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo. on page 121 show how the samples are mapped to memory in this mode. The mapping is valid for both RX and TX.

In mono mode (CONFIG.CHANNELS=Left or Right), RX sample from only one channel in the frame is stored in memory, the other channel sample is ignored. Illustrations Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left. on page 120, Memory mapping for 16 bit mono, left



channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left. on page 120 and Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left. on page 121 show how RX samples are mapped to memory in this mode.

For TX, the same outgoing sample read from memory is transmitted on both left and right in a frame, resulting in a mono output stream.

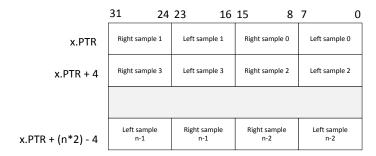


Figure 25: Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo.

	31 24	23 16	15 8	7 0
x.PTR	Left sample 3	Left sample 2	Left sample 1	Left sample 0
x.PTR + 4	Left sample 7	Left sample 6	Left sample 5	Left sample 4
x.PTR + n - 4	Left sample n-1	Left sample n-2	Left sample n-3	Left sample n-4

Figure 26: Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left.

	31 16	15 0
x.PTR	Right sample 0	Left sample 0
x.PTR + 4	Right sample 1	Left sample 1
x.PTR + (n*4) - 4	Right sample n - 1	Left sample n - 1

Figure 27: Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo.

	31 16	15 0
x.PTR	Left sample 1	Left sample 0
x.PTR + 4	Left sample 3	Left sample 2
x.PTR + (n*2) - 4	Left sample n - 1	Left sample n - 2

Figure 28: Memory mapping for 16 bit mono, left channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left.



	31	23 0
x.PTR	Sign ext.	Left sample 0
x.PTR + 4	Sign ext.	Right sample 0
x.PTR + (n*8) - 8	Sign ext.	Left sample n - 1
x.PTR + (n*8) - 4	Sign ext.	Right sample n - 1

Figure 29: Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo.

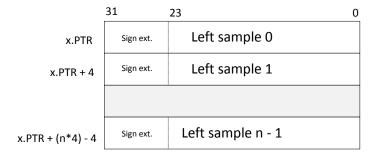


Figure 30: Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left.

6.7.8 Module operation

Described here is a typical operating procedure for the I²S module.



1. Configure the I²S module using the CONFIG registers

```
// Enable reception
NRF_I2S->CONFIG.RXEN = (I2S_CONFIG_RXEN_RXEN_Enabled <<
                                     I2S CONFIG RXEN RXEN Pos);
// Enable transmission
NRF I2S->CONFIG.TXEN = (I2S CONFIG TXEN TXEN Enabled <<
                                      12S CONFIG TXEN TXEN Pos);
// Enable MCK generator
NRF_I2S->CONFIG.MCKEN = (I2S_CONFIG_MCKEN_MCKEN_Enabled <<
                                      12S CONFIG MCKEN MCKEN Pos);
// MCKFREQ = 4 MHz
NRF I2S->CONFIG.MCKFREQ = I2S CONFIG MCKFREQ MCKFREQ 32MDIV8 <<
                                      i2s_config_mckfreq_mckfreq pos;
// Ratio = 256
NRF I2S->CONFIG.RATIO = I2S CONFIG RATIO RATIO 256X <<
                                      12S CONFIG RATIO RATIO Pos;
// MCKFREQ = 4 MHz and Ratio = 256 gives sample rate = 15.625 \text{ ks/s}
// Sample width = 16 bit
NRF_I2S->CONFIG.SWIDTH = I2S_CONFIG_SWIDTH_SWIDTH_16Bit <<
                                      12S CONFIG SWIDTH SWIDTH Pos;
// Alignment = Left
NRF_I2S->CONFIG.ALIGN = I2S_CONFIG_ALIGN_ALIGN_Left <<
                                      12S CONFIG ALIGN ALIGN Pos;
// Format = I2S
NRF_I2S->CONFIG.FORMAT = I2S_CONFIG_FORMAT_FORMAT_I2S <<
                                       I2S CONFIG FORMAT FORMAT Pos;
// Use stereo
NRF I2S->CONFIG.CHANNELS = I2S CONFIG CHANNELS CHANNELS Stereo <<
                                      12S CONFIG CHANNELS CHANNELS Pos;
```

2. Map IO pins using the PINSEL registers

```
// MCK routed to pin 0
NRF I2S->PSEL.MCK = (0 << I2S PSEL MCK PIN Pos) |
                    (I2S_PSEL_MCK_CONNECT_Connected <<
                                                I2S PSEL MCK CONNECT Pos);
// SCK routed to pin 1
NRF_I2S->PSEL.SCK = (1 << I2S_PSEL_SCK_PIN_Pos) |
                   (I2S PSEL SCK CONNECT Connected <<
                                                I2S PSEL SCK CONNECT Pos);
// LRCK routed to pin 2
NRF I2S->PSEL.LRCK = (2 << I2S PSEL LRCK PIN Pos) |
                     (I2S_PSEL_LRCK_CONNECT_Connected <<
                                                 I2S PSEL LRCK CONNECT Pos);
// SDOUT routed to pin 3
NRF I2S->PSEL.SDOUT = (3 << I2S_PSEL_SDOUT_PIN_Pos) |
                      (I2S PSEL SDOUT CONNECT Connected <<
                                                I2S PSEL SDOUT CONNECT Pos);
// SDIN routed on pin 4
NRF I2S->PSEL.SDIN = (4 << I2S PSEL SDIN PIN Pos) |
                     (I2S PSEL SDIN CONNECT Connected <<
                                                12S PSEL SDIN CONNECT Pos);
```



3. Configure TX and RX data pointers using the TXD, RXD and RXTXD registers

```
NRF_I2S->TXD.PTR = my_tx_buf;
NRF_I2S->RXD.PTR = my_rx_buf;
NRF_I2S->TXD.MAXCNT = MY_BUF_SIZE;
```

4. Enable the I²S module using the ENABLE register

```
NRF_I2S->ENABLE = 1;
```

5. Start audio streaming using the START task

```
NRF_I2S->TASKS_START = 1;
```

6. Handle received and transmitted data when receiving the TXPTRUPD and RXPTRUPD events

```
if(NRF_I2S->EVENTS_TXPTRUPD != 0)
{
    NRF_I2S->TXD.PTR = my_next_tx_buf;
    NRF_I2S->EVENTS_TXPTRUPD = 0;
}

if(NRF_I2S->EVENTS_RXPTRUPD != 0)
{
    NRF_I2S->RXD.PTR = my_next_rx_buf;
    NRF_I2S->EVENTS_RXPTRUPD = 0;
}
```

6.7.9 Pin configuration

The MCK, SCK, LRCK, SDIN and SDOUT signals associated with the I²S module are mapped to physical pins according to the pin numbers specified in the PSEL.x registers.

These pins are acquired whenever the I²S module is enabled through the register ENABLE on page 129.

When a pin is acquired by the I²S module, the direction of the pin (input or output) will be configured automatically, and any pin direction setting done in the GPIO module will be overridden. The directions for the various I²S pins are shown below in GPIO configuration before enabling peripheral (master mode) on page 123 and GPIO configuration before enabling peripheral (slave mode) on page 124.

To secure correct signal levels on the pins when the system is in OFF mode, and when the I²S module is disabled, these pins must be configured in the GPIO peripheral directly.

I ² S signal	I ² S pin	Direction	Output value	Comment
МСК	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Output	0	
SCK	As specified in PSEL.SCK	Output	0	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 43: GPIO configuration before enabling peripheral (master mode)



I ² S signal	I ² S pin	Direction	Output value	Comment
МСК	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Input	Not applicable	
SCK	As specified in PSEL.SCK	Input	Not applicable	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 44: GPIO configuration before enabling peripheral (slave mode)

6.7.10 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50028000	12S	12S : S	US	Ç A	Inter-IC Sound	
0x40028000	123	12S : NS	03	SA	inter-ic sound	

Table 45: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Starts continuous I2S transfer. Also starts MCK generator when this is enabled.
TASKS_STOP	0x004		Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the
			STOPPED event to be generated.
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
EVENTS_RXPTRUPD	0x104		The RXD.PTR register has been copied to internal double-buffers. When the
			12S module is started and RX is enabled, this event will be generated for every
			RXTXD.MAXCNT words that are received on the SDIN pin.
EVENTS_STOPPED	0x108		12S transfer stopped.
EVENTS_TXPTRUPD	0x114		The TDX.PTR register has been copied to internal double-buffers. When the
			12S module is started and TX is enabled, this event will be generated for every
			RXTXD.MAXCNT words that are sent on the SDOUT pin.
PUBLISH_RXPTRUPD	0x184		Publish configuration for event RXPTRUPD
PUBLISH_STOPPED	0x188		Publish configuration for event STOPPED
PUBLISH_TXPTRUPD	0x194		Publish configuration for event TXPTRUPD
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		Enable I2S module.
CONFIG.MODE	0x504		I2S mode.
CONFIG.RXEN	0x508		Reception (RX) enable.
CONFIG.TXEN	0x50C		Transmission (TX) enable.
CONFIG.MCKEN	0x510		Master clock generator enable.
CONFIG.MCKFREQ	0x514		Master clock generator frequency.
CONFIG.RATIO	0x518		MCK / LRCK ratio.
CONFIG.SWIDTH	0x51C		Sample width.
CONFIG.ALIGN	0x520		Alignment of sample within a frame.
CONFIG.FORMAT	0x524		Frame format.
CONFIG.CHANNELS	0x528		Enable channels.
RXD.PTR	0x538		Receive buffer RAM start address.
TXD.PTR	0x540		Transmit buffer RAM start address.
RXTXD.MAXCNT	0x550		Size of RXD and TXD buffers.
PSEL.MCK	0x560		Pin select for MCK signal.
PSEL.SCK	0x564		Pin select for SCK signal.
PSEL.LRCK	0x568		Pin select for LRCK signal.



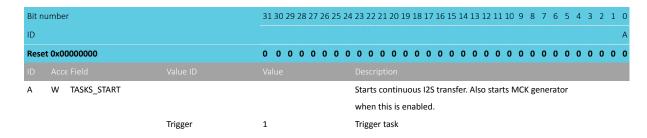
Register	Offset	Security	Description
PSEL.SDIN	0x56C		Pin select for SDIN signal.
PSEL.SDOUT	0x570		Pin select for SDOUT signal.

Table 46: Register overview

6.7.10.1 TASKS_START

Address offset: 0x000

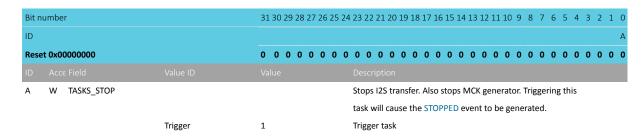
Starts continuous I2S transfer. Also starts MCK generator when this is enabled.



6.7.10.2 TASKS_STOP

Address offset: 0x004

Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the STOPPED event to be generated.



6.7.10.3 SUBSCRIBE START

Address offset: 0x080

Subscribe configuration for task START

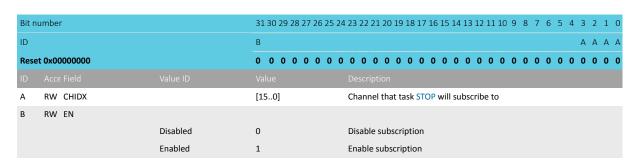
Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.7.10.4 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

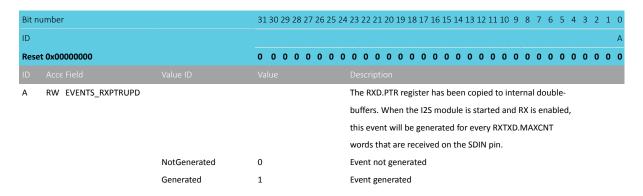




6.7.10.5 EVENTS RXPTRUPD

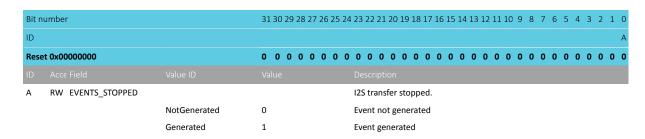
Address offset: 0x104

The RXD.PTR register has been copied to internal double-buffers. When the I2S module is started and RX is enabled, this event will be generated for every RXTXD.MAXCNT words that are received on the SDIN pin.



6.7.10.6 EVENTS STOPPED

Address offset: 0x108 I2S transfer stopped.



6.7.10.7 EVENTS_TXPTRUPD

Address offset: 0x114

The TDX.PTR register has been copied to internal double-buffers. When the I2S module is started and TX is enabled, this event will be generated for every RXTXD.MAXCNT words that are sent on the SDOUT pin.



Bit r	number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW EVENTS_TXPTRUPD			The TDX.PTR register has been copied to internal double-
				buffers. When the I2S module is started and TX is enabled,
				this event will be generated for every RXTXD.MAXCNT
				words that are sent on the SDOUT pin.
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.7.10.8 PUBLISH_RXPTRUPD

Address offset: 0x184

Publish configuration for event RXPTRUPD

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event RXPTRUPD will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.7.10.9 PUBLISH_STOPPED

Address offset: 0x188

Publish configuration for event STOPPED

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event STOPPED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.7.10.10 PUBLISH_TXPTRUPD

Address offset: 0x194

Publish configuration for event TXPTRUPD

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event TXPTRUPD will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing





6.7.10.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F CB
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
В	RW RXPTRUPD			Enable or disable interrupt for event RXPTRUPD
		Disabled	0	Disable
		Enabled	1	Enable
С	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
F	RW TXPTRUPD			Enable or disable interrupt for event TXPTRUPD
		Disabled	0	Disable
		Enabled	1	Enable

6.7.10.12 INTENSET

Address offset: 0x304

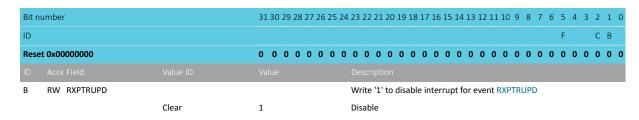
Enable interrupt

Bit n	umber		4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID				F C B
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
В	RW RXPTRUPD			Write '1' to enable interrupt for event RXPTRUPD
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW TXPTRUPD			Write '1' to enable interrupt for event TXPTRUPD
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.7.10.13 INTENCLR

Address offset: 0x308

Disable interrupt





Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F CB
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW TXPTRUPD			Write '1' to disable interrupt for event TXPTRUPD
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.7.10.14 ENABLE

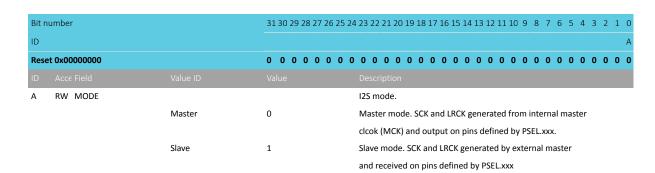
Address offset: 0x500 Enable I2S module.

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW ENABLE		Enable I2S module.
Disabled	0	Disable
Enabled	1	Enable

6.7.10.15 CONFIG.MODE

Address offset: 0x504

I2S mode.



6.7.10.16 CONFIG.RXEN

Address offset: 0x508

Reception (RX) enable.



Bit number	31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field Value ID		Description
A RW RXEN		Reception (RX) enable.
Disabled	0	Reception disabled and now data will be written to the
		RXD.PTR address.
Enabled	1	Reception enabled.

6.7.10.17 CONFIG.TXEN

Address offset: 0x50C

Transmission (TX) enable.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000001		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW TXEN			Transmission (TX) enable.
		Disabled	0	Transmission disabled and now data will be read from the
				RXD.TXD address.
		Enabled	1	Transmission enabled.

6.7.10.18 CONFIG.MCKEN

Address offset: 0x510

Master clock generator enable.

Bit number			31 30 29 28 27 26 25	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1									
ID				A									
Rese	et 0x00000001		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0									
ID													
Α	RW MCKEN			Master clock generator enable.									
		Disabled	0	Master clock generator disabled and PSEL.MCK not									
				connected(available as GPIO).									
		Enabled	1	Master clock generator running and MCK output on									
				PSEL.MCK.									

6.7.10.19 CONFIG.MCKFREQ

Address offset: 0x514

Master clock generator frequency.

Bit numb	per		313	30 29	9 28	27	26	25	24 2	23 :	22 2	21 2	0 1	9 1	3 17	16	15	14	13	12	11 1	.0 9	8 (7	6	5	4	3	2	1 0
ID			Α .	ΑД	A	Α	Α	Α	Α	Α	Α	A A	Δ .	Δ Δ	A	Α	Α	Α	Α	Α	Α.	Δ ,	Δ Δ	A	Α	Α	Α	Α	A .	A A
Reset 0x	20000000		0	0 1	. 0	0	0	0	0	0	0	0 (0 (0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0
ID Ac																														
A RV	W MCKFREQ								-	Ma	ste	r clc	ck	gen	era	tor	fre	que	ncy	' .										
		32MDIV8	0x2	000	0000	0			3	32	МН	z / 8	8 =	4.0	MH	lz														
		32MDIV10	0x1	800	0000	0			3	32	МН	z / :	10 =	= 3.	2 M	Hz														
		32MDIV11	0x1	600	0000	0			3	32	МН	z / :	11 :	= 2.	909	090)9 N	ЛHz	:											
		32MDIV15	0x1	100	0000	0			3	32	МН	z / :	15 :	= 2.	133	333	33 N	/IHz												





Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0x20000000		0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field		Value Description
	32MDIV16	0x10000000 32 MHz / 16 = 2.0 MHz
	32MDIV21	0x0C000000 32 MHz / 21 = 1.5238095
	32MDIV23	0x0B000000 32 MHz / 23 = 1.3913043 MHz
	32MDIV30	0x08800000 32 MHz / 30 = 1.0666667 MHz
	32MDIV31	0x08400000 32 MHz / 31 = 1.0322581 MHz
	32MDIV32	0x08000000 32 MHz / 32 = 1.0 MHz
	32MDIV42	0x06000000 32 MHz / 42 = 0.7619048 MHz
	32MDIV63	0x04100000 32 MHz / 63 = 0.5079365 MHz
	32MDIV125	0x020C0000 32 MHz / 125 = 0.256 MHz

6.7.10.20 CONFIG.RATIO

Address offset: 0x518 MCK / LRCK ratio.

Bit number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Reset 0x000	000006		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW	RATIO			MCK / LRCK ratio.
		32X	0	LRCK = MCK / 32
		48X	1	LRCK = MCK / 48
		64X	2	LRCK = MCK / 64
		96X	3	LRCK = MCK / 96
		128X	4	LRCK = MCK / 128
		192X	5	LRCK = MCK / 192
		256X	6	LRCK = MCK / 256
		384X	7	LRCK = MCK / 384
		512X	8	LRCK = MCK / 512

6.7.10.21 CONFIG.SWIDTH

Address offset: 0x51C

Sample width.

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17	16 15 1	.4 13 1	2 11 10	9 8	3 7	6	5	4	3 2	1	0
ID														Α	Α
Rese	et 0x00000001		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0	0 0	0 0 (0 0	0 0	0	0	0	0	0 0	0	1
ID															
Α	RW SWIDTH			Sample width.											
Α	RW SWIDTH	8Bit	0	Sample width. 8 bit.											
A	RW SWIDTH	8Bit 16Bit	0	·											

6.7.10.22 CONFIG.ALIGN

Address offset: 0x520

Alignment of sample within a frame.

Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		
A RW ALIGN		Alignment of sample within a frame.
Left	0	Left-aligned.
Right	1	Right-aligned.

6.7.10.23 CONFIG.FORMAT

Address offset: 0x524

Frame format.

Bit number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW FORMAT			Frame format.
	125	0	Original I2S format.
	Aligned	1	Alternate (left- or right-aligned) format.

6.7.10.24 CONFIG.CHANNELS

Address offset: 0x528

Enable channels.

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHANNELS			Enable channels.
		Stereo	0	Stereo.
		Left	1	Left only.

6.7.10.25 RXD.PTR

Address offset: 0x538

Receive buffer RAM start address.

		words containing samples will be written to this address
Α	RW PTR	Receive buffer Data RAM start address. When receiving,
ID		
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

words containing samples will be written to this address.

This address is a word aligned Data RAM address.

6.7.10.26 TXD.PTR

Address offset: 0x540

Transmit buffer RAM start address.

NORDIC

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Rese	t 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		Value Description
Α	RW PTR	Transmit buffer Data RAM start address. When transmitting,
		words containing samples will be fetched from this address.

This address is a word aligned Data RAM address.

6.7.10.27 RXTXD.MAXCNT

Address offset: 0x550

Size of RXD and TXD buffers.

Α	RW MAXCNT	Size of RXD and TXD buffers in number of 32 bit words.
ID		Value Description
Rese	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.7.10.28 PSEL.MCK

Address offset: 0x560

Pin select for MCK signal.

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.7.10.29 PSEL.SCK

Address offset: 0x564

Pin select for SCK signal.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	ID		С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.7.10.30 PSEL.LRCK

Address offset: 0x568

Pin select for LRCK signal.



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C	A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.7.10.31 PSEL.SDIN

Address offset: 0x56C

Pin select for SDIN signal.

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.7.10.32 PSEL.SDOUT

Address offset: 0x570

Pin select for SDOUT signal.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.7.11 Electrical specification

6.7.11.1 I2S timing specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{S_SDIN}	SDIN setup time before SCK rising	20			ns
t _{H_SDIN}	SDIN hold time after SCK rising	15			ns
t _{S_SDOUT}	SDOUT setup time after SCK falling	40			ns
t _{H_SDOUT}	SDOUT hold time before SCK falling	6			ns
t _{SCK_LRCK}	SCLK falling to LRCK edge	-5	0	5	ns
f _{MCK}	MCK frequency			4000	kHz
f_{LRCK}	LRCK frequency			48	kHz
f_{SCK}	SCK frequency			2000	kHz
DC_{CK}	Clock duty cycle (MCK, LRCK, SCK)	45		55	%



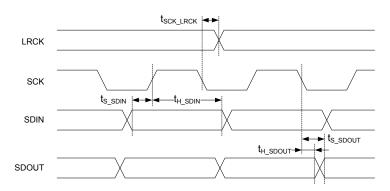


Figure 31: I2S timing diagram

6.8 KMU — Key management unit

Key management unit (KMU) is a component of the NVMC for secure key handling. KMU uses a subset of the flash referred to as user information configuration register (UICR) for its secure storage. This UICR subset can be used for both establishing a device root of trust (RoT) during chip and OEM manufacturing, and for storage and use of any device specific keys.

Access and use of information stored in UICR is controlled through the KMU. Even though the KMU and UICR are tightly coupled, they do not share a common memory map:

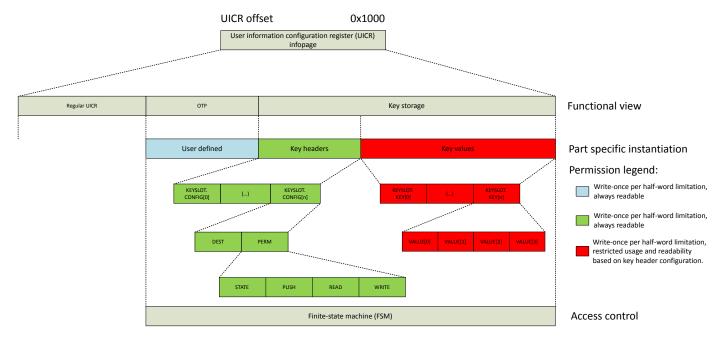


Figure 32: Memory map overview

The KMU is mapped as a stand-alone peripheral on the APB bus, while UICR is addressable on AHB and is located in flash memory map. Access to the KMU and keys stored in UICR is only allowed in secure mode. Access to the UICR memory map is equivalent to any other flash page access, except that the KMU will enforce usage and read/write restrictions to different regions of the UICR memory map depending on configuration.

For more information about the user information configuration registers, see chapter UICR — User information configuration registers on page 41.

6.8.1 Functional view



From a functional view UICR is divided into two different regions:

- One-time programmable (OTP) memory
- Key storage

OTP

One-time programmable (OTP) memory is typically used for holding values that are written once, and then never to be changed throughout the life-time of the product. The OTP region of UICR is emulated by placing a write-once per halfword limitation on registers defined here.

Key storage

The key storage region contains multiple key slots, where each slot consists of a key header and an associated key value. The key value is limited to 128 bits. Any key size greater than 128 bits must be divided and distributed over multiple key slot instances.

Key headers are allocated an address range of 0x400 in the UICR memory map, allowing for a total of 128 keys to be addressable inside the key storage region.

Note: Use of the key storage region in UICR should be limited to keys with a certain life-span, and not per-session derived keys where the CPU is involved in the key exchange.

6.8.2 Access control

Access control to the underlying UICR infopage in the flash is enforced by a hardware finite-state machine (FSM). FSM can allow or block transactions depending both on the security of the transaction (secure or non-secure) and the type of register being written and/or read.

Access type	Key headers	Key values
Read	Allowed	Restricted
Write	Restricted	Restricted

Table 47: Access control

Any restricted access requires an explicit key slot selection through the KMU register interface. Any illegal access to restricted key slot registers will be blocked and word <code>OxDEADDEAD</code> will be returned on AHB.

The OTP region has individual access control behavior, while access control to the key storage region is configured on a per key slot basis. KMU FSM operates on only one key slot instance at a time, and the permissions and usage restriction for a key value associated with a key slot can be configured individually.

Note: Even if the KMU can be configured as non-secure, all non-secure transactions will be blocked.

6.8.3 Protecting UICR content

UICR content can be protected against device-internal NVMC->ERASEALL requests, in addition to device-external ERASEALL requests, through the CTRL-AP interface. This feature is useful if the firmware designers want to prevent the OTP region from being erased.

Since enabling this step will permanently disable erase for UICR, the procedure require an implementation defined 32-bit word to be written into the UICR->ERASEPROTECT register.

In case of field return handling it is still possible to erase UICR even if ERASEPROTECT is set. If this functionality is desired, the secure boot code must implement a secure communication channel over the



CTRL-AP mailbox interface. Upon successful authentication of the external party, the secure boot code can temporarily re-enable the CTRL-AP ERASEALL functionality.

6.8.4 Usage

This section describe specific KMU and UICR behavior in more detail, in order to help the reader to get a better overview of its features and intended usage.

6.8.4.1 OTP

The OTP region of UICR contains user-defined static configuration of the device. The KMU emulates the OTP functionality by placing a write-once per halfword limitation of registers defined in this region, i.e. only halfwords containing all '1' can be written.

An OTP write transaction must consist of a full 32-bit word. Both halfwords can either be written simultaneously or individually. The KMU FSM will block any write to a halfword in the OTP region if the initial value of this half-word is not $0 \times FFFF$. When writing halfwords individually, the non-active halfword must be masked as $0 \times FFFF$ else the request will be blocked. I.e. writing $0 \times 1234 \times XXX$ to an OTP destination address which already contain the value $0 \times FFFFAABB$ must be configured as $0 \times 1234 FFFF$. The OTP destination address will contain the value $0 \times 1234 AABB$ after both write transactions have been processed.

The KMU will also only allow AHB write transactions into the OTP region of UICR if the transaction is secure. Any AHB write transaction to this region that does not satisfy the above requirements will be ignored, and the STATUS.BLOCKED register will be set to '1'.

6.8.4.2 Key storage

The key storage region of UICR can contain multiple keys of different type, including symmetrical keys, hashes, public/private key pairs and other device secrets. One of the key features of the KMU, is that these device secrets can be installed and made available for use in cryptographic operations without revealing the actual secret values.

Keys in this region will typically have a certain life-span, and is not designed to be used for per-session derived keys where the non-secure side (i.e. application) is participating in the key exchange.

All key storage is done through the concept of multiple key slots, where one key slot instance consists of one key header and an associated key value. Each key header supports configuration of usage permissions and an optional secure destination address.

The key header secure destination address option enables the KMU to push the associated key value over a dedicated secure APB to a pre-configured secure location within the memory map. Such locations typically include write-only key register of a HW cryptograhic accelerator, allowing the KMU to distribute keys within the system without compromising the key values.

One key slot instance can store a key value of maximum 128 bits. If a key size exceeds this limit, the key value itself must be split over multiple key slot instances.

The following usage and read permissions scheme is applicable for each key slot:



State	Push	Read	Write	Description
Active (1)	Enabled	Enabled	Enabled	Default flash erase value. Key slot cannot be pushed, write is enabled.
	(1)	(1)	(1)	
Active (1)	Enabled	Enabled	Disabled	Key slot is active, push is enabled. Key slot VALUE registers can be read, but write is disabled.
	(1)	(1)	(0)	
Active (1)	Enabled	Disabled	Disabled	Key slot is active, push is enabled. Read and write to key slot VALUE registers is disabled.
	(1)	(0)	(0)	
Active (1)	Disabled	Enabled	Disabled	Key slot is active, push is disabled. Key slot VALUE registers can be read, but write is disabled.
	(0)	(1)	(0)	
Revoked	-	-	-	Key slot is revoked. Cannot be read or pushed over Secure APB regardless of permission settings.
(0)				

Table 48: Valid key slot permission schemes

6.8.4.2.1 Selecting a key slot

The KMU FSM is designed to process only one key slot at a time, effectively operating as a memory protection unit for the key storage region. Whenever a key slot is selected, the KMU will allow access to writing, reading, and/or pushing the associated key value according to the selected slot configuration.

A key slot **must** be selected prior to use by writing the key slot ID into the KMU->SELECTKEYSLOT register. Because the reset value of this register is 0×00000000 , there is no key slot associated with ID=0 and no slot is selected by default. All key slots are addressed using IDs from 1 to 128.

SELECTED status is set, when a key slot is selected and a read or write acccess to that keyslot occurs.

BLOCKED status is set, when any illegal access to key slot registers is detected.

When the use of the particular key slot is stopped, the key slot selection in KMU->SELECTKEYSLOT must be set back to '0'.

By default all KMU key slots will consist of a 128 bit key value of '1', where the key headers have no secure destination address or any usage and read restrictions.

6.8.4.2.2 Writing to a key slot

Writing a key slot into UICR is a five-step process.

- 1. Select which key slot the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT. The selected key slot must be empty in order to add a new entry to UICR.
- 2. If the key value shall be pushable over secure APB, the destination address of the recipient must be configured in register KEYSLOT.CONFIG[ID-1].DEST.
- **3.** Write the 128-bit key value into KEYSLOT.KEY[ID-1].VALUE[0-3].
- **4.** Write the desired key slot permissions into KEYSLOT.CONFIG[ID-1].PERM, including any applicable usage restrictions.
- **5.** Select key slot 0.

In case the total key size is greater than 128 bits, the key value itself must be split into 128-bit segments and written to multiple key slot instances. Steps 1 through 5 above must be repeated for the entire key size.

Note: If a key slot is configured as readable, and KEYSLOT.CONFIG[ID-1].DEST is not to be used, it is recommended to disable the push bit in KEYSLOT.CONFIG[ID-1].PERM when configuring key slot permissions.

Note: A key value distributed over multiple key slots should use the same key slot configuration in its key headers, but the secure destination address for each key slot instance must be incremented by 4 words (128 bits) for each key slot instance spanned.



Note: Write to flash must be enabled in NVMC->CONFIG prior to writing keys to flash, and subsequently disabled once writing is complete.

Steps 1 through 5 above will be blocked if any of the following violations are detected:

- · No key slot selected
- Non-empty key slot selected
- · NVM destination address not empty
- AHB write to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot

6.8.4.2.3 Reading a key value

Key slots that are configured as readable can have their key value read directly from the UICR memory map by the CPU.

Readable keys are typically used during the secure boot sequence, where the CPU is involved in falsifying or verifying the integrity of the system. Since the CPU is involved in this decision process, it makes little sense not to trust the CPU having access to actual key value but ultimately trust the decision of the integrity check. Another use-case for readable keys is if the key type in question does not have a HW peripheral in the platform that is able to accept such keys over secure APB.

Reading a key value from UICR is a three-step process:

- 1. Select the key slot which the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT.
- 2. If STATE and READ permission requirements are fulfilled as defined in KEYSLOT.CONFIG[ID-1].PERM, the key value can be read from region KEYSLOT.KEY[ID-1].VALUE[0-3] for selected key slot.
- **3.** Select key slot 0.

Step 2 will be blocked and word <code>0xDEADDEAD</code> will be returned on AHB if any of the following violations are detected:

- No key slot selected
- Key slot not configured as readable
- Key slot is revoked
- AHB read to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot

6.8.4.2.4 Push over secure APB

Key slots that are configured as non-readable cannot be read by the CPU regardless of mode the system is in, and must be pushed over secure APB in order to use the key value for cryptographic operations.

The secure APB destination address is set in the key slot configuration DEST register. Such destination addresses are typically write-only key registers in a hardware cryptographic accelerators memory map. The secure APB allows key slots to be utilized by the software side, without exposing the key value itself.



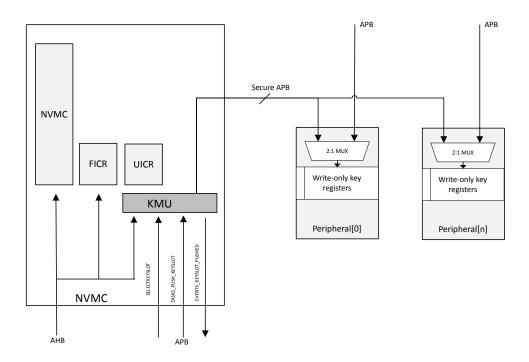


Figure 33: Tasks and events pattern for key slots

Pushing a key slot over secure APB is a four-step process:

- 1. Select the key slot on which the KMU shall operate by writing the desired key slot ID into KMU>SELECTKEYSLOT
- 2. Start TASKS_PUSH_KEYSLOT to initiate a secure APB transaction writing the 128-bit key value associated with the selected key slot into address defined in KEYSLOT.CONFIG[ID-1].DEST
- **3.** After completing the secure APB transaction, the 128-bit key value is ready for use by the peripheral and EVENTS KEYSLOT PUSHED is triggered
- **4.** Select key slot 0

Note: If a key value is distributed over multiple key slots due to its key size, exceeding the maximum 128-bit key value limitation, then each distributed key slot must be pushed individually in order to transfer the entire key value over secure APB.

Step 3 will trigger other events than EVENTS_KEYSLOT_PUSHED if the following violations are detected:

- EVENTS KEYSLOT ERROR:
 - If no key slot is selected
 - · If a key slot has no destination address configured
 - If when pushing a key slot, flash or peripheral returns an error
 - If pushing a key slot when push permissions are disabled
 - If attempting to push a key slot with default permissions
- EVENTS KEYSLOT REVOKED if a key slot is marked as revoked in its key header configuration

6.8.4.2.5 Revoking key slots

All key slots within the key storage area can be marked as revoked by writing to the STATE field in the KEYSLOT.CONFIG[ID-1]. PERM register. The following rules apply to keys that have been revoked:



- 1. Key values that are not readable by the CPU, and thus depend on the tasks/events pattern to be used by a peripheral, can no longer be pushed. If a revoked key slot is selected and task TASKS PUSH KEYSLOT is started, the event EVENTS KEYSLOT REVOKED will be triggered.
- 2. Key values that are readable by the CPU can have their revoke bit set in order to instruct the KMU to block future read requests for this key value. Any subsequent read operation to a revoked key value will return word <code>0xDEADDEAD</code>.
- **3.** Published keys stored in a peripheral write-only key register are not affected by key revocation. If secure code wants to enforce that a revoked key is no longer used by a peripheral for cryptographic operations, the secure code need to reset the device and thus prevent the revoked key slot from being published again.

6.8.4.3 STATUS register

The KMU uses a KMU->STATUS register to indicate its status of operation. The SELECTED bit will be asserted whenever the currently selected key slot is successfully read from or written to.

All read or write operations to other key slots than what is currently selected in KMU->SELECTKEYSLOT will assert the BLOCKED bit. The BLOCKED bit will also be asserted if the KMU fails to select a key slot, or if a request has been blocked due to an access violation. Normal operation using the KMU should never trigger the BLOCKED bit. If this bit is triggered during the development phase, this indicate that code is using the KMU incorrectly.

The KMU->STATUS register is reset every time register KMU->SELECTKEYSLOT is written.

6.8.5 Registers

Base addres	ss Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50039000) KMU	KMU : S	SPLIT	NA	Kay managament unit	
0x40039000		KMU : NS	SPLII	NA	Key management unit	

Table 49: Instances

Register	Offset	Security	Description
TASKS_PUSH_KEYSLOT	0x0000		Push a key slot over secure APB
EVENTS_KEYSLOT_PUSHED	0x100		Key successfully pushed over secure APB
EVENTS_KEYSLOT_REVOKE	D0x104		Key has been revoked and cannot be tasked for selection
EVENTS_KEYSLOT_ERROR	0x108		No key slot selected, no destination address defined, or error during push
			operation
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
STATUS	0x40C		Status bits for KMU operation
SELECTKEYSLOT	0x500		Select key slot ID to be read over AHB or pushed over secure APB when
			TASKS_PUSH_KEYSLOT is started

Table 50: Register overview

6.8.5.1 TASKS PUSH KEYSLOT

Address offset: 0x0000

Push a key slot over secure APB



Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID				Description
Α	W TASKS_PUSH_KEYSLOT			Push a key slot over secure APB
	Trigger		1	Trigger task

6.8.5.2 EVENTS_KEYSLOT_PUSHED

Address offset: 0x100

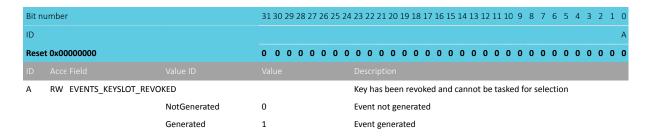
Key successfully pushed over secure APB

Bit n	umber		31	30	29 2	8 27	7 26	25	24 :	23 2	22 2	1 20	0 19	18	17	16 1	L5 1	4 1	3 12	11	10 9	8 6	7	6	5	4	3 2	2 1	0
ID																													Α
Rese	et 0x00000000		0	0	0 (0 0	0	0	0	0 (0 (0 0	0	0	0	0	0 (0 0	0	0	0 (0	0	0	0	0	0 (0	0
ID																													
Α	RW EVENTS_KEYSLOT_PUS	HED								Key	suc	ces	sful	ly p	ush	ed o	ove	r se	cure	AP	В								
		NotGenerated	0						ı	Ever	nt n	ot g	gen	erat	ed														
		Generated	1						-	Ever	nt g	gene	erat	ed															

6.8.5.3 EVENTS_KEYSLOT_REVOKED

Address offset: 0x104

Key has been revoked and cannot be tasked for selection



6.8.5.4 EVENTS_KEYSLOT_ERROR

Address offset: 0x108

No key slot selected, no destination address defined, or error during push operation

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_KEYSLOT_ERRO	DR		No key slot selected, no destination address defined, or
				error during push operation
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.8.5.5 INTEN

Address offset: 0x300

Enable or disable interrupt



Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		СВА
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW KEYSLOT_PUSHED		Enable or disable interrupt for event KEYSLOT_PUSHED
Disabled	0	Disable
Enabled	1	Enable
B RW KEYSLOT_REVOKED		Enable or disable interrupt for event KEYSLOT_REVOKED
Disabled	0	Disable
Enabled	1	Enable
C RW KEYSLOT_ERROR		Enable or disable interrupt for event KEYSLOT_ERROR
Disabled	0	Disable
Enabled	1	Enable

6.8.5.6 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW KEYSLOT_PUSHED			Write '1' to enable interrupt for event KEYSLOT_PUSHED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW KEYSLOT_REVOKED			Write '1' to enable interrupt for event KEYSLOT_REVOKED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW KEYSLOT_ERROR			Write '1' to enable interrupt for event KEYSLOT_ERROR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.8.5.7 INTENCLR

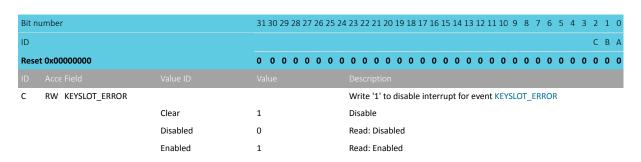
Address offset: 0x308

Disable interrupt

Bit number		31 30 29 28	8 27 2	6 25	24	23 22	2 21	1 20 :	19 1	8 17	16	15	14 1	3 12	11 3	.0 9	8	7	6	5 -	4 3	2	1 0
ID																						С	ВА
Reset 0x00000000		0 0 0 0	0 0	0	0	0 0	0	0	0 0	0	0	0	0 (0	0	0 0	0	0	0	0	0	0	0 0
ID Acce Field																							
A RW KEYSLOT_PUSHED						Write	e '1	' to c	disab	le ir	iter	rup	t for	eve	nt K	YSL	OT_	PUS	SHE	D			
	Clear	1				Disab	ble																
	Disabled	0				Read	l: D	isabl	ed														
	Enabled	1				Read	l: Er	nable	ed														
B RW KEYSLOT_REVOKED						Write	e '1	' to c	disab	le ir	iter	rup	t for	eve	nt K	YSL	OT_	RE	/OK	ED			
	Clear	1				Disab	ble																
	Disabled	0				Read	l: D	isabl	ed														
	Enabled	1				Read	l: Er	nable	ed														







6.8.5.8 INTPEND

Address offset: 0x30C Pending interrupts

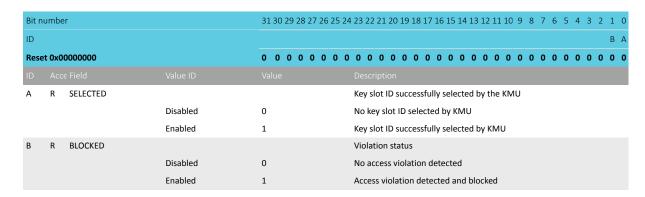
Bit numb	per		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Reset 0x	00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Ac				Description
A R	KEYSLOT_PUSHED			Read pending status of interrupt for event
				KEYSLOT_PUSHED
		NotPending	0	Read: Not pending
		Pending	1	Read: Pending
B R	KEYSLOT_REVOKED			Read pending status of interrupt for event
				KEYSLOT_REVOKED
		NotPending	0	Read: Not pending
		Pending	1	Read: Pending
C R	KEYSLOT_ERROR			Read pending status of interrupt for event KEYSLOT_ERROR
		NotPending	0	Read: Not pending
		Pending	1	Read: Pending
		Pending	1	KEYSLOT_REVOKED Read: Not pending Read: Pending Read pending status of interrupt for event KEYSLOT_ERROR

6.8.5.9 STATUS

Address offset: 0x40C

Status bits for KMU operation

This register is reset and re-written by the KMU whenever SELECTKEYSLOT is written

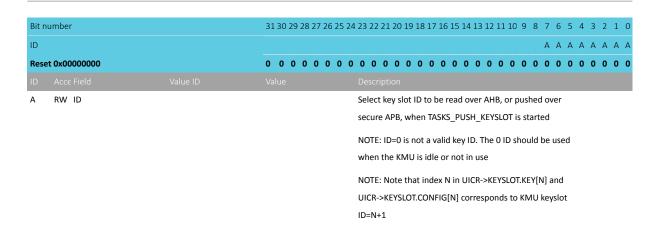


6.8.5.10 SELECTKEYSLOT

Address offset: 0x500

Select key slot ID to be read over AHB or pushed over secure APB when TASKS_PUSH_KEYSLOT is started





6.9 PDM — Pulse density modulation interface

The pulse density modulation (PDM) module enables input of pulse density modulated signals from external audio frontends, for example, digital microphones. The PDM module generates the PDM clock and supports single-channel or dual-channel (Left and Right) data input. Data is transferred directly to RAM buffers using EasyDMA.

Listed here are the main features for PDM:

- Up to two PDM microphones configured as a Left/Right pair using the same data input
- 16 kHz output sample rate, 16-bit samples
- · EasyDMA support for sample buffering
- · HW decimation filters
- Selectable ratio of 64 or 80 between PDM_CLK and output sample rate

The PDM module illustrated in PDM module on page 145 is interfacing up to two digital microphones with the PDM interface. It implements EasyDMA, which relieves real-time requirements associated with controlling the PDM slave from a low priority CPU execution context. It also includes all the necessary digital filter elements to produce PCM samples. The PDM module allows continuous audio streaming.

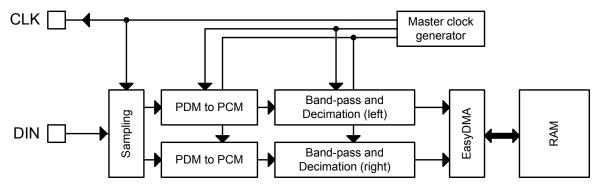


Figure 34: PDM module

6.9.1 Master clock generator

The FREQ field in the master clock's PDMCLKCTRL register allows adjusting the PDM clock's frequency.

The master clock generator does not add any jitter to the HFCLK source chosen. It is recommended (but not mandatory) to use the Xtal as HFCLK source.

6.9.2 Module operation

By default, bits from the left PDM microphone are sampled on PDM_CLK falling edge, bits for the right are sampled on the rising edge of PDM_CLK, resulting in two bitstreams. Each bitstream is fed into a digital



filter which converts the PDM stream into 16-bit PCM samples, and filters and down-samples them to reach the appropriate sample rate.

The EDGE field in the MODE register allows swapping Left and Right, so that Left will be sampled on rising edge, and Right on falling.

The PDM module uses EasyDMA to store the samples coming out from the filters into one buffer in RAM.

Depending on the mode chosen in the OPERATION field in the MODE register, memory either contains alternating left and right 16-bit samples (Stereo), or only left 16-bit samples (Mono).

To ensure continuous PDM sampling, it is up to the application to update the EasyDMA destination address pointer as the previous buffer is filled.

The continuous transfer can be started or stopped by sending the START and STOP tasks. STOP becomes effective after the current frame has finished transferring, which will generate the STOPPED event. The STOPPED event indicates that all activity in the module are finished, and that the data is available in RAM (EasyDMA has finished transferring as well). Attempting to restart before receiving the STOPPED event may result in unpredictable behaviour.

6.9.3 Decimation filter

In order to convert the incoming data stream into PCM audio samples, a decimation filter is included in the PDM interface module.

The input of the filter is the two-channel PDM serial stream (with left channel on clock high, right channel on clock low). Depending on the RATIO selected, its output is 2×16 -bit PCM samples at a sample rate either 64 times or 80 times (depending on the RATIO register) lower than the PDM clock rate.

The filter stage of each channel is followed by a digital volume control, to attenuate or amplify the output samples in a range of -20 dB to +20 dB around the default (reset) setting, defined by $G_{PDM,default}$. The gain is controlled by the GAINL and GAINR registers.

As an example, if the goal is to achieve 2500 RMS output samples (16 bit) with a 1 kHz 90 dBA signal into a -26 dBFS sensitivity PDM microphone, the user will have to sum the PDM module's default gain ($G_{PDM,default}$) and the gain introduced by the microphone and acoustic path of his implementation (an attenuation would translate into a negative gain), and adjust GAINL and GAINR by this amount. Assuming that only the PDM module influences the gain, GAINL and GAINR must be set to - $G_{PDM,default}$ dB to achieve the requirement.

With G_{PDM,default}=3.2 dB, and as GAINL and GAINR are expressed in 0.5 dB steps, the closest value to program would be 3.0 dB, which can be calculated as:

```
GAINL = GAINR = (DefaultGain - (2 * 3))
```

Remember to check that the resulting values programmed into GAINL and GAINR fall within MinGain and MaxGain.

6.9.4 EasyDMA

Samples will be written directly to RAM, and EasyDMA must be configured accordingly.

The address pointer for the EasyDMA channel is set in SAMPLE.PTR register. If the destination address set in SAMPLE.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

DMA supports Stereo (Left+Right 16-bit samples) and Mono (Left only) data transfer, depending on setting in the OPERATION field in the MODE register. The samples are stored little endian.



MODE.OPERATION	Bits per sample	Result stored per RAM	Physical RAM allocated	Result boundary indexes Note						
		word	(32 bit words)	in RAM						
Stereo	32 (2x16)	L+R	ceil(SAMPLE.MAXCNT/2)	R0=[31:16]; L0=[15:0]	Default					
Mono	16	2xL	ceil(SAMPLE.MAXCNT/2)	L1=[31:16]; L0=[15:0]						

Table 51: DMA sample storage

The destination buffer in RAM consists of one block, the size of which is set in SAMPLE.MAXCNT register. Format is number of 16-bit samples. The physical RAM allocated is always:

```
(RAM allocation, in bytes) = SAMPLE.MAXCNT * 2;
```

(but the mapping of the samples depends on MODE.OPERATION.

If OPERATION=Stereo, RAM will contain a succession of Left and Right samples.

If OPERATION=Mono, RAM will contain a succession of mono samples.

For a given value of SAMPLE.MAXCNT, the buffer in RAM can contain half the stereo sampling time as compared to the mono sampling time.

The PDM acquisition can be started by the START task, after the SAMPLE.PTR and SAMPLE.MAXCNT registers have been written. When starting the module, it will take some time for the filters to start outputting valid data. Transients from the PDM microphone itself may also occur. The first few samples (typically around 50) might hence contain invalid values or transients. It is therefore advised to discard the first few samples after a PDM start.

As soon as the STARTED event is received, the firmware can write the next SAMPLE.PTR value (this register is double-buffered), to ensure continuous operation.

When the buffer in RAM is filled with samples, an END event is triggered. The firmware can start processing the data in the buffer. Meanwhile, the PDM module starts acquiring data into the new buffer pointed to by SAMPLE.PTR, and sends a new STARTED event, so that the firmware can update SAMPLE.PTR to the next buffer address.

6.9.5 Hardware example

Connect the microphone clock to CLK, and data to DIN.

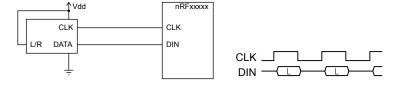


Figure 35: Example of a single PDM microphone, wired as left

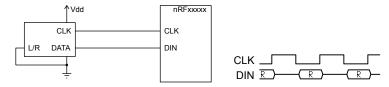


Figure 36: Example of a single PDM microphone, wired as right

Note that in a single-microphone (mono) configuration, depending on the microphone's implementation, either the left or the right channel (sampled at falling or rising CLK edge respectively) will contain reliable data. If two microphones are used, one of them has to be set as left, the other as right (L/R pin tied high or



to GND on the respective microphone). It is strongly recommended to use two microphones of exactly the same brand and type so that their timings in left and right operation match.

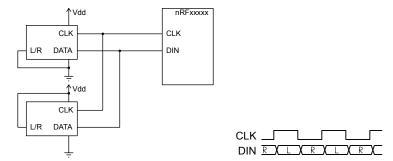


Figure 37: Example of two PDM microphones

6.9.6 Pin configuration

The CLK and DIN signals associated to the PDM module are mapped to physical pins according to the configuration specified in the PSEL.CLK and PSEL.DIN registers respectively. If the CONNECT field in any PSEL register is set to Disconnected, the associated PDM module signal will not be connected to the required physical pins, and will not operate properly.

The PSEL.CLK and PSEL.DIN registers and their configurations are only used as long as the PDM module is enabled, and retained only as long as the device is in System ON mode. See POWER — Power control on page 58 for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register.

To ensure correct behaviour in the PDM module, the pins used by the PDM module must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 148 before enabling the PDM module. This is to ensure that the pins used by the PDM module are driven correctly if the PDM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the PDM module is supposed to be connected to an external PDM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behaviour.

PDM signal	PDM pin	Direction	Output value	Comment
CLK	As specified in PSEL.CLK	Output	0	
DIN	As specified in PSEL.DIN	Input	Not applicable	

Table 52: GPIO configuration before enabling peripheral

6.9.7 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50026000	DDM	PDM:S	uc	CA	Pulse density modulation	
0x40026000	PDM	PDM: NS	US	SA	(digital microphone) interface	2

Table 53: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Starts continuous PDM transfer
TASKS_STOP	0x004		Stops PDM transfer
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP



Register	Offset	Security	Description
EVENTS_STARTED	0x100		PDM transfer has started
EVENTS_STOPPED	0x104		PDM transfer has finished
EVENTS_END	0x108		The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last
			sample after a STOP task has been received) to Data RAM
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_END	0x188		Publish configuration for event END
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PDM module enable register
PDMCLKCTRL	0x504		PDM clock generator control
MODE	0x508		Defines the routing of the connected PDM microphones' signals
GAINL	0x518		Left output gain adjustment
GAINR	0x51C		Right output gain adjustment
RATIO	0x520		Selects the ratio between PDM_CLK and output sample rate. Change PDMCLKCTRL
			accordingly.
PSEL.CLK	0x540		Pin number configuration for PDM CLK signal
PSEL.DIN	0x544		Pin number configuration for PDM DIN signal
SAMPLE.PTR	0x560		RAM address pointer to write samples to with EasyDMA
SAMPLE.MAXCNT	0x564		Number of samples to allocate memory for in EasyDMA mode

Table 54: Register overview

6.9.7.1 TASKS_START

Address offset: 0x000

Starts continuous PDM transfer

Bit r	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_START			Starts continuous PDM transfer
		Trigger	1	Trigger task

6.9.7.2 TASKS_STOP

Address offset: 0x004 Stops PDM transfer

Bit n	umber		31 30 29 28 27	26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	et 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W TASKS_STOP				Stops PDM transfer
		Trigger	1		Trigger task

6.9.7.3 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START



Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		В	АААА
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CHIDX		[150]	Channel that task START will subscribe to
B RW EN			
	Disabled	0	Disable subscription
	Enabled	1	Enable subscription

6.9.7.4 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.9.7.5 EVENTS_STARTED

Address offset: 0x100

PDM transfer has started

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_STARTED			PDM transfer has started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.9.7.6 EVENTS_STOPPED

Address offset: 0x104

PDM transfer has finished

Bit n	umber		31	30	29	28 2	27 2	26 2	5 2	24 2	3 2	22 2	21 2	0 1	9 18	8 1	7 1	6 1	5 14	4 13	12	11	10	9	8	7	6 !	5 4	1 3	2	1	0
ID																																Α
Rese	et 0x00000000		0	0	0	0	0	0 0) (0 0) (0	0 0) (0	0) (0	0	0	0	0	0	0	0	0	0 (0 (0	0	0	0
ID																																
Α	RW EVENTS_STOPPED									Р	D٨	∕l tr	ans	fer	has	s fir	nish	ned														
		NotGenerated	0							E	ver	nt r	not (ger	era	tec	ł															
		Generated	1							E	ver	nt g	gene	erat	ted																	

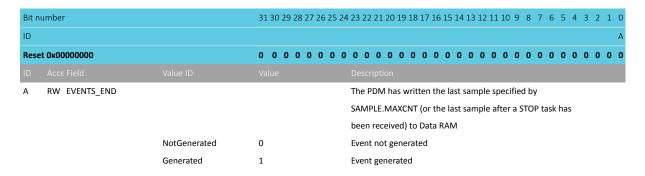
6.9.7.7 EVENTS_END

Address offset: 0x108





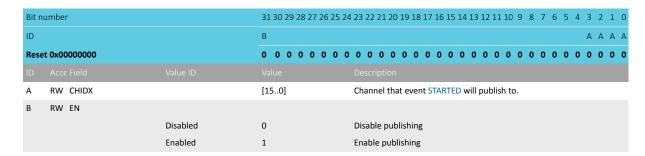
The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after a STOP task has been received) to Data RAM



6.9.7.8 PUBLISH_STARTED

Address offset: 0x180

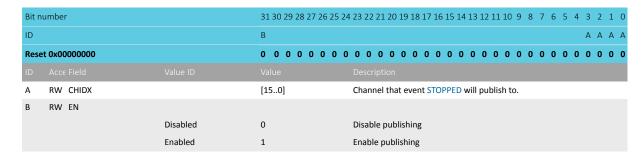
Publish configuration for event STARTED



6.9.7.9 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED



6.9.7.10 PUBLISH END

Address offset: 0x188

Publish configuration for event END



Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		В	АААА
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CHIDX		[150]	Channel that event END will publish to.
B RW EN			
	Disabled	0	Disable publishing
	Enabled	1	Enable publishing

6.9.7.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STARTED			Enable or disable interrupt for event STARTED
		Disabled	0	Disable
		Enabled	1	Enable
В	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
С	RW END			Enable or disable interrupt for event END
		Disabled	0	Disable
		Enabled	1	Enable

6.9.7.12 INTENSET

Address offset: 0x304

Enable interrupt

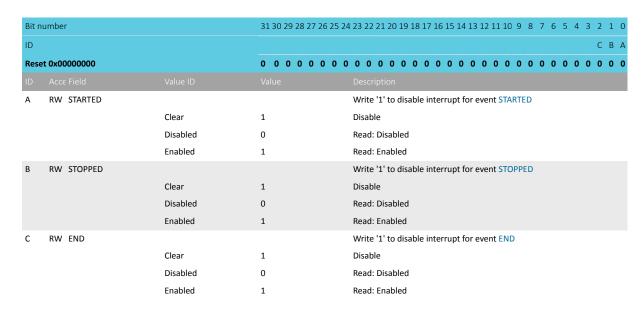
Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STARTED			Write '1' to enable interrupt for event STARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW END			Write '1' to enable interrupt for event END
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.9.7.13 INTENCLR

Address offset: 0x308



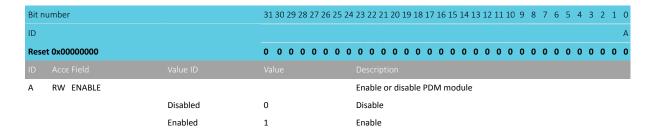
Disable interrupt



6.9.7.14 ENABLE

Address offset: 0x500

PDM module enable register



6.9.7.15 PDMCLKCTRL

Address offset: 0x504

PDM clock generator control

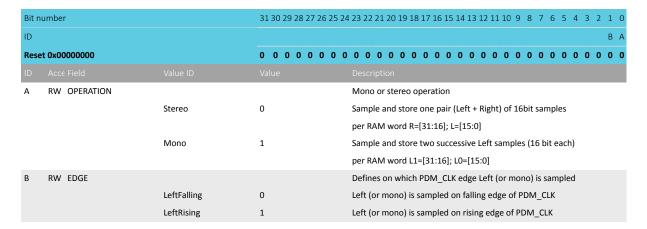
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A A A A A A A A A A A A A
Reset 0x08400000	0 0 0 0 1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	
A RW FREQ	PDM_CLK frequency
1000K	0x08000000 PDM_CLK = 32 MHz / 32 = 1.000 MHz
Default	0x08400000 PDM_CLK = 32 MHz / 31 = 1.032 MHz. Nominal clock for
	RATIO=Ratio64.
1067K	0x08800000 PDM_CLK = 32 MHz / 30 = 1.067 MHz
1231K	0x09800000 PDM_CLK = 32 MHz / 26 = 1.231 MHz
1280K	0x0A000000 PDM_CLK = 32 MHz / 25 = 1.280 MHz. Nominal clock for
	RATIO=Ratio80.
1333K	0x0A800000 PDM_CLK = 32 MHz / 24 = 1.333 MHz



6.9.7.16 MODE

Address offset: 0x508

Defines the routing of the connected PDM microphones' signals



6.9.7.17 GAINL

Address offset: 0x518

Left output gain adjustment

Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A
Reset 0x00000028	Reset 0x00000028		$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field Va	alue ID	Value	Description
A RW GAINL			Left output gain adjustment, in 0.5 dB steps, around the
			default module gain (see electrical parameters)
			0x00 -20 dB gain adjust
			0x01 -19.5 dB gain adjust
			()
			0x27 -0.5 dB gain adjust
			0x28 0 dB gain adjust
			0x29 +0.5 dB gain adjust
			()
			0x4F +19.5 dB gain adjust
			0x50 +20 dB gain adjust
M	⁄linGain	0x00	-20dB gain adjustment (minimum)
D	efault Gain	0x28	0dB gain adjustment
M	/laxGain	0x50	+20dB gain adjustment (maximum)

6.9.7.18 GAINR

Address offset: 0x51C

Right output gain adjustment

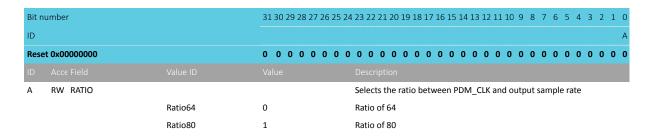


Bit n	umber		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A
Rese	et 0x00000028		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW GAINR			Right output gain adjustment, in 0.5 dB steps, around the
				default module gain (see electrical parameters)
		MinGain	0x00	-20dB gain adjustment (minimum)
		DefaultGain	0x28	OdB gain adjustment
		MaxGain	0x50	+20dB gain adjustment (maximum)

6.9.7.19 RATIO

Address offset: 0x520

Selects the ratio between PDM_CLK and output sample rate. Change PDMCLKCTRL accordingly.



6.9.7.20 PSEL.CLK

Address offset: 0x540

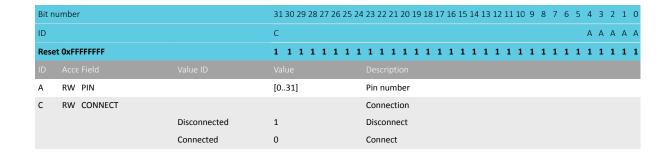
Pin number configuration for PDM CLK signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	ААААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.9.7.21 PSEL.DIN

Address offset: 0x544

Pin number configuration for PDM DIN signal



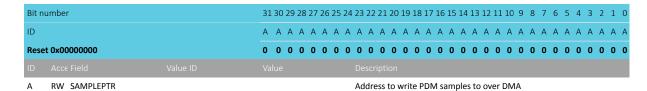




6.9.7.22 SAMPLE.PTR

Address offset: 0x560

RAM address pointer to write samples to with EasyDMA

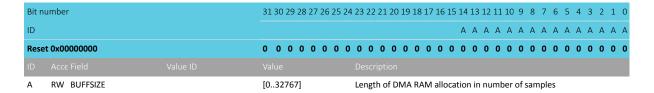


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.9.7.23 SAMPLE.MAXCNT

Address offset: 0x564

Number of samples to allocate memory for in EasyDMA mode



6.9.8 Electrical specification

6.9.8.1 PDM Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{PDM,CLK,64}	PDM clock speed. PDMCLKCTRL = Default (Setting needed		1.032		MHz
	for 16MHz sample frequency @ RATIO = Ratio64)				
f _{PDM,CLK,80}	PDM clock speed. PDMCLKCTRL = 1280K (Setting needed for				MHz
	16MHz sample frequency @ RATIO = Ratio80)				
t _{PDM,JITTER}	Jitter in PDM clock output			20	ns
T _{dPDM,CLK}	PDM clock duty cycle	40	50	60	%
t _{PDM,DATA}	Decimation filter delay			5	ms
t _{PDM,cv}	Allowed clock edge to data valid			125	ns
t _{PDM,ci}	Allowed (other) clock edge to data invalid	0			ns
t _{PDM,s}	Data setup time at $f_{\text{PDM,CLK}}\!\!=\!\!1.024$ MHz or 1.280 MHz	65			ns
t _{PDM,h}	Data hold time at f _{PDM,CLK} =1.024 MHz or 1.280 MHz	0			ns
G _{PDM,default}	Default (reset) absolute gain of the PDM module		3.2		dB



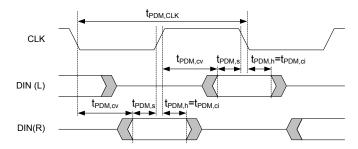


Figure 38: PDM timing diagram

6.10 PWM — Pulse width modulation

The pulse with modulation (PWM) module enables the generation of pulse width modulated signals on GPIO. The module implements an up or up-and-down counter with four PWM channels that drive assigned GPIOs.

The following are the main features of a PWM module:

- Programmable PWM frequency
- · Up to four PWM channels with individual polarity and duty cycle values
- Edge or center-aligned pulses across PWM channels
- Multiple duty cycle arrays (sequences) defined in RAM
- Autonomous and glitch-free update of duty cycle values directly from memory through EasyDMA (no CPU involvement)
- Change of polarity, duty cycle, and base frequency possibly on every PWM period
- RAM sequences can be repeated or connected into loops

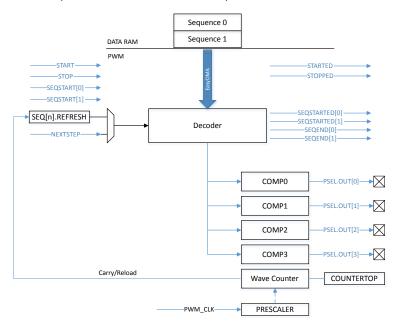


Figure 39: PWM module

6.10.1 Wave counter

The wave counter is responsible for generating the pulses at a duty cycle that depends on the compare values, and at a frequency that depends on COUNTERTOP.

There is one common 15-bit counter with four compare channels. Thus, all four channels will share the same period (PWM frequency), but can have individual duty cycle and polarity. The polarity is set by a



value read from RAM (see figure Decoder memory access modes on page 161). Whether the counter counts up, or up and down, is controlled by the MODE register.

The timer top value is controlled by the COUNTERTOP register. This register value, in conjunction with the selected PRESCALER of the PWM_CLK, will result in a given PWM period. A COUNTERTOP value smaller than the compare setting will result in a state where no PWM edges are generated. OUT[n] is held high, given that the polarity is set to FallingEdge. All compare registers are internal and can only be configured through decoder presented later. COUNTERTOP can be safely written at any time.

Sampling follows the START task. If DECODER.LOAD=WaveForm, the register value is ignored and taken from RAM instead (see section Decoder with EasyDMA on page 161 for more details). If DECODER.LOAD is anything else than the WaveForm, it is sampled following a STARTSEQ[n] task and when loading a new value from RAM during a sequence playback.

The following figure shows the counter operating in up mode (MODE=PWM_MODE_Up), with three PWM channels with the same frequency but different duty cycle:

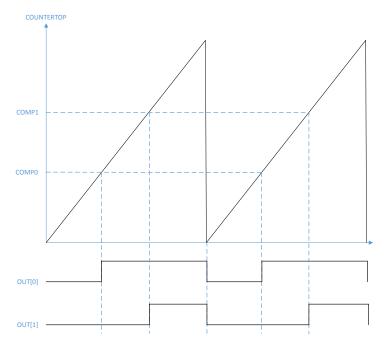


Figure 40: PWM counter in up mode example - FallingEdge polarity

The counter is automatically reset to zero when COUNTERTOP is reached and OUT[n] will invert. OUT[n] is held low if the compare value is 0 and held high if set to COUNTERTOP, given that the polarity is set to



FallingEdge. Counter running in up mode results in pulse widths that are edge-aligned. The following is the code for the counter in up mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->PSEL.OUT[1] = (second_pin << PWM_PSEL_OUT_PIN_Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF_PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER_DIV_1 <<
                                                   PWM_PRESCALER_PRESCALER_Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF_PWM0->LOOP = (PWM_LOOP_CNT_Disabled << PWM_LOOP_CNT_Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(pwm_seq) << PWM_SEQ_PTR_PTR_Pos);
NRF_PWM0->SEQ[0].CNT = ((sizeof(pwm_seq) / sizeof(uint16_t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

When the counter is running in up mode, the following formula can be used to compute the PWM period and the step size:

```
PWM period: T_{PWM (Up)} = T_{PWM \_CLK} * COUNTERTOP
Step width/Resolution: T_{steps} = T_{PWM \_CLK}
```

The following figure shows the counter operating in up-and-down mode (MODE=PWM_MODE_UpAndDown), with two PWM channels with the same frequency but different duty cycle and output polarity:



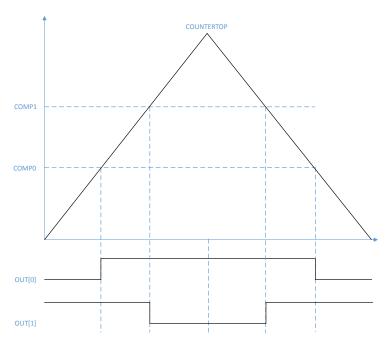


Figure 41: PWM counter in up-and-down mode example

The counter starts decrementing to zero when COUNTERTOP is reached and will invert the OUT[n] when compare value is hit for the second time. This results in a set of pulses that are center-aligned. The following is the code for the counter in up-and-down mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM_PSEL_OUT_CONNECT_Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
                     = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
NRF PWM0->ENABLE
NRF_PWM0->MODE
                     = (PWM MODE UPDOWN UpAndDown << PWM MODE UPDOWN Pos);
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF PWM0->LOOP = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                     (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t) (pwm seq) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[0].CNT = ((sizeof(pwm_seq) / sizeof(uint16_t)) <<
                                                PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF_PWM0->TASKS_SEQSTART[0] = 1;
```

When the counter is running in up-and-down mode, the following formula can be used to compute the PWM period and the step size:

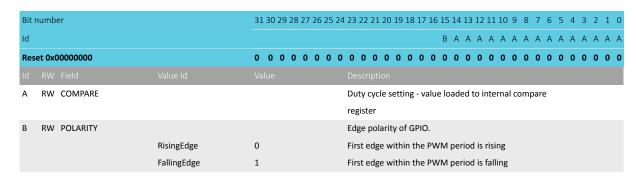
```
T_{PWM\,(Up\ And\ Down)} = T_{PWM\_CLK} * 2 * COUNTERTOP
Step width/Resolution: T_{steps} = T_{PWM\ CLK} * 2
```



6.10.2 Decoder with EasyDMA

The decoder uses EasyDMA to take PWM parameters stored in RAM and update the internal compare registers of the wave counter, based on the mode of operation.

PWM parameters are organized into a sequence containing at least one half word (16 bit). Its most significant bit[15] denotes the polarity of the OUT[n] while bit[14:0] is the 15-bit compare value.



The DECODER register controls how the RAM content is interpreted and loaded into the internal compare registers. The LOAD field controls if the RAM values are loaded to all compare channels, or to update a group or all channels with individual values. The following figure illustrates how parameters stored in RAM are organized and routed to various compare channels in different modes:

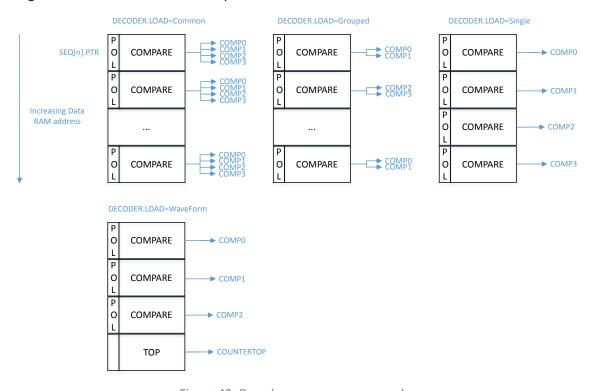


Figure 42: Decoder memory access modes

A special mode of operation is available when DECODER.LOAD is set to WaveForm. In this mode, up to three PWM channels can be enabled - OUT[0] to OUT[2]. In RAM, four values are loaded at a time: the first, second and third location are used to load the values, and the fourth RAM location is used to load the COUNTERTOP register. This way one can have up to three PWM channels with a frequency base that changes on a per PWM period basis. This mode of operation is useful for arbitrary wave form generation in applications, such as LED lighting.



The register SEQ[n].REFRESH=N (one per sequence n=0 or 1) will instruct a new RAM stored pulse width value on every (N+1)th PWM period. Setting the register to zero will result in a new duty cycle update every PWM period, as long as the minimum PWM period is observed.

Note that registers SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored when DECODER.MODE=NextStep. The next value is loaded upon every received NEXTSTEP task.

SEQ[n].PTR is the pointer used to fetch COMPARE values from RAM. If the SEQ[n].PTR is not pointing to a RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions. After the SEQ[n].PTR is set to the desired RAM location, the SEQ[n].CNT register must be set to number of 16-bit half words in the sequence. It is important to observe that the Grouped mode requires one half word per group, while the Single mode requires one half word per channel, thus increasing the RAM size occupation. If PWM generation is not running when the SEQSTART[n] task is triggered, the task will load the first value from RAM and then start the PWM generation. A SEQSTARTED[n] event is generated as soon as the EasyDMA has read the first PWM parameter from RAM and the wave counter has started executing it. When LOOP.CNT=0, sequence n=0 or 1 is played back once. After the last value in the sequence has been loaded and started executing, a SEQEND[n] event is generated. The PWM generation will then continue with the last loaded value. The following figure illustrates an example of such simple playback:

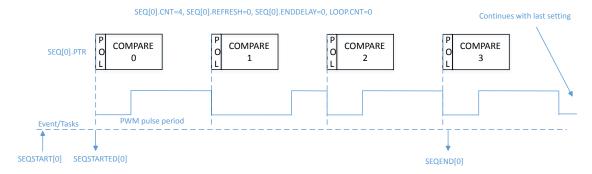


Figure 43: Simple sequence example



Figure depicts the source code used for configuration and timing details in a sequence where only sequence 0 is used and only run once with a new PWM duty cycle for each period.

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (PWM_LOOP_CNT_Disabled << PWM_LOOP_CNT_Pos);
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                    PWM SEQ CNT CNT Pos);
NRF_PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

To completely stop the PWM generation and force the associated pins to a defined state, a STOP task can be triggered at any time. A STOPPED event is generated when the PWM generation has stopped at the end of currently running PWM period, and the pins go into their idle state as defined in GPIO OUT register. PWM generation can then only be restarted through a SEQSTART[n] task. SEQSTART[n] will resume PWM generation after having loaded the first value from the RAM buffer defined in the SEQ[n].PTR register.

The table below indicates when specific registers get sampled by the hardware. Care should be taken when updating these registers to avoid that values are applied earlier than expected.



Register	Taken into account by hardware	Recommended (safe) update
SEQ[n].PTR	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[n].CNT	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[0].ENDDELAY	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	Every time a new value from sequence [0] has been loaded from	When no more value from sequence [0] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[0] event)
	PWMPERIODEND event)	At any time during sequence [1] (which starts when the
		SEQSTARTED[1] event is generated)
SEQ[1].ENDDELAY	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	When no more value from sequence [1] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[1] event)
	PWMPERIODEND event)	At any time during sequence [0] (which starts when the
		SEQSTARTED[0] event is generated)
SEQ[0].REFRESH	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	Every time a new value from sequence [0] has been loaded from	At any time during sequence [1] (which starts when the
	RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[1] event is generated)
	PWMPERIODEND event)	
SEQ[1].REFRESH	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	At any time during sequence [0] (which starts when the
	RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[0] event is generated)
	PWMPERIODEND event)	
COUNTERTOP	In DECODER.LOAD=WaveForm: this register is ignored.	Before starting PWM generation through a SEQSTART[n] task
	In all other LOAD modes: at the end of current PWM period	After a STOP task has been triggered, and the STOPPED event has
	(indicated by the PWMPERIODEND event)	been received.
MODE	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
DECODER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PRESCALER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
LOOP	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PSEL.OUT[n]	Immediately	Before enabling the PWM instance through the ENABLE register

Table 55: When to safely update PWM registers

Note: SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored at the end of a complex sequence, indicated by a LOOPSDONE event. The reason for this is that the last value loaded from RAM is maintained until further action from software (restarting a new sequence, or stopping PWM generation).

A more complex example, where LOOP.CNT>0, is shown in the following figure:



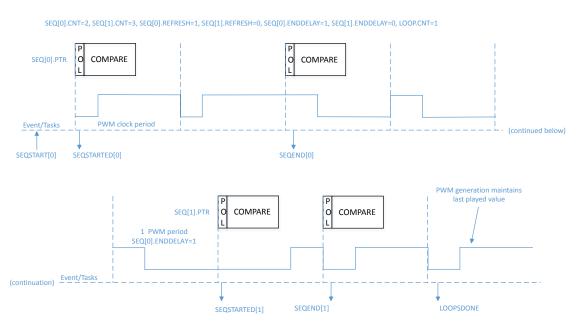


Figure 44: Example using two sequences

In this case, an automated playback takes place, consisting of SEQ[0], delay 0, SEQ[1], delay 1, then again SEQ[0], etc. The user can choose to start a complex playback with SEQ[0] or SEQ[1] through sending the SEQSTART[0] or SEQSTART[1] task. The complex playback always ends with delay 1.

The two sequences 0 and 1 are defined by the addresses of value tables in RAM (pointed to by SEQ[n].PTR) and the buffer size (SEQ[n].CNT). The rate at which a new value is loaded is defined individually for each sequence by SEQ[n].REFRESH. The chaining of sequence 1 following the sequence 0 is implicit, the LOOP.CNT register allows the chaining of sequence 1 to sequence 0 for a determined number of times. In other words, it allows to repeat a complex sequence a number of times in a fully automated way.

In the following code example, sequence 0 is defined with SEQ[0].REFRESH set to 1, meaning that a new PWM duty cycle is pushed every second PWM period. This complex sequence is started with the SEQSTART[0] task, so SEQ[0] is played first. Since SEQ[0].ENDDELAY=1 there will be one PWM period delay between last period on sequence 0 and the first period on sequence 1. Since SEQ[1].ENDDELAY=0 there is no delay 1, so SEQ[0] would be started immediately after the end of SEQ[1]. However, as LOOP.CNT is



1, the playback stops after having played SEQ[1] only once, and both SEQEND[1] and LOOPSDONE are generated (their order is not guaranteed in this case).

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (1 << PWM_LOOP_CNT_Pos);</pre>
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(seq0_ram) << PWM_SEQ_PTR_PTR_Pos);</pre>
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                    PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 1;
NRF PWM0->SEQ[0].ENDDELAY = 1;
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq1 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq1_ram) / sizeof(uint16_t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[1].REFRESH = 0;
NRF PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

The decoder can also be configured to asynchronously load new PWM duty cycle. If the DECODER.MODE register is set to NextStep, then the NEXTSTEP task will cause an update of internal compare registers on the next PWM period.

The following figures provide an overview of each part of an arbitrary sequence, in various modes (LOOP.CNT=0 and LOOP.CNT>0). In particular, the following are represented:

- Initial and final duty cycle on the PWM output(s)
- Chaining of SEQ[0] and SEQ[1] if LOOP.CNT>0
- Influence of registers on the sequence
- Events generated during a sequence
- DMA activity (loading of next value and applying it to the output(s))



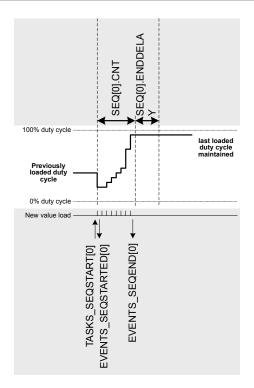


Figure 45: Single shot (LOOP.CNT=0)

Note: The single-shot example also applies to SEQ[1]. Only SEQ[0] is represented for simplicity.

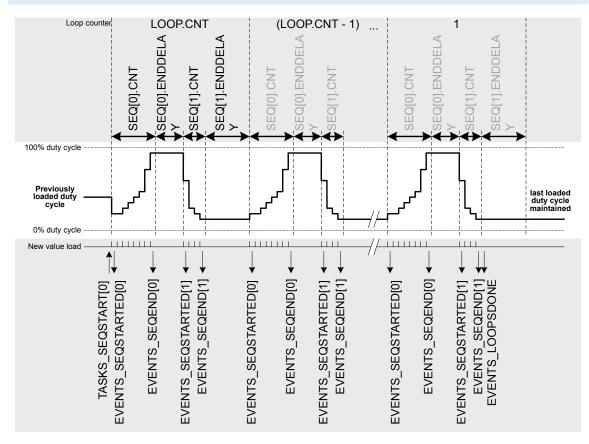


Figure 46: Complex sequence (LOOP.CNT>0) starting with SEQ[0]



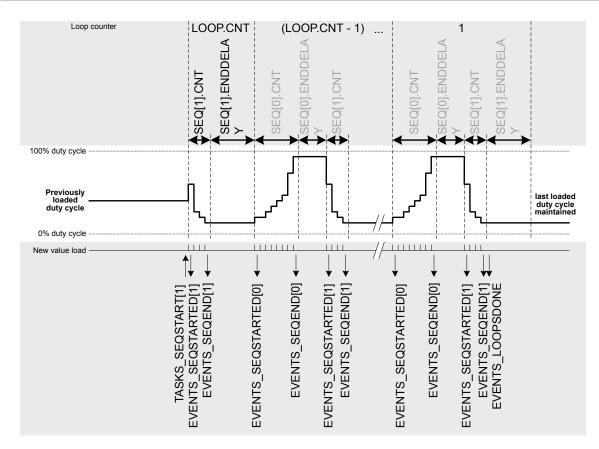


Figure 47: Complex sequence (LOOP.CNT>0) starting with SEQ[1]

Note: If a sequence is in use in a simple or complex sequence, it must have a length of SEQ[n].CNT > 0.

6.10.3 Limitations

Previous compare value is repeated if the PWM period is shorter than the time it takes for the EasyDMA to retrieve from RAM and update the internal compare registers. This is to ensure a glitch-free operation even for very short PWM periods.

6.10.4 Pin configuration

The OUT[n] (n=0..3) signals associated with each PWM channel are mapped to physical pins according to the configuration of PSEL.OUT[n] registers. If PSEL.OUT[n].CONNECT is set to Disconnected, the associated PWM module signal will not be connected to any physical pins.

The PSEL.OUT[n] registers and their configurations are used as long as the PWM module is enabled and the PWM generation active (wave counter started). They are retained only as long as the device is in System ON mode (see section POWER for more information about power modes).

To ensure correct behavior in the PWM module, the pins that are used must be configured in the GPIO peripheral in the following way before the PWM module is enabled:

PWM signal	PWM pin	Direction	Output value	Comment
OUT[n]	As specified in PSEL.OUT[n]	Output	0	Idle state defined in GPIO OUT
	(n=03)			register

Table 56: Recommended GPIO configuration before starting PWM generation



The idle state of a pin is defined by the OUT register in the GPIO module, to ensure that the pins used by the PWM module are driven correctly. If PWM generation is stopped by triggering a STOP task, the PWM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected pins (I/Os) for as long as the PWM module is supposed to be connected to an external PWM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

6.10.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50021000	PWM	PWM0:S	US	SA	Pulse width modulation unit (1
0x40021000	PVVIVI	PWM0: NS	US	SA	Puise width modulation unit t	,
0x50022000	PWM	PWM1:S	US	SA	Pulse width modulation unit	
0x40022000	PVVIVI	PWM1:NS	03	<i>3</i> A	ruise wiatii iiloadiatioii aiiit 1	L
0x50023000	PWM	PWM2:S	US	SA	Pulse width modulation unit 2	1
0x40023000	PVVIVI	PWM2 : NS	US	3A	Pulse width modulation unit a	2
0x50024000	PWM	PWM3:S	US	SA	Pulse width modulation unit 3	
0x40024000	PVVIVI	PWM3:NS	US	SA	Pulse width modulation unit s	5

Table 57: Instances

Register	Offset	Security	Description
TASKS_STOP	0x004		Stops PWM pulse generation on all channels at the end of current PWM period,
			and stops sequence playback
TASKS_SEQSTART[0]	0x008		Loads the first PWM value on all enabled channels from sequence 0, and
			starts playing that sequence at the rate defined in SEQ[0]REFRESH and/or
			DECODER.MODE. Causes PWM generation to start if not running.
TASKS_SEQSTART[1]	0x00C		Loads the first PWM value on all enabled channels from sequence 1, and
			starts playing that sequence at the rate defined in SEQ[1]REFRESH and/or
			DECODER.MODE. Causes PWM generation to start if not running.
TASKS_NEXTSTEP	0x010		Steps by one value in the current sequence on all enabled channels if
			DECODER.MODE=NextStep. Does not cause PWM generation to start if not
			running.
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_SEQSTART[0]	0x088		Subscribe configuration for task SEQSTART[0]
SUBSCRIBE_SEQSTART[1]	0x08C		Subscribe configuration for task SEQSTART[1]
SUBSCRIBE_NEXTSTEP	0x090		Subscribe configuration for task NEXTSTEP
EVENTS_STOPPED	0x104		Response to STOP task, emitted when PWM pulses are no longer generated
EVENTS_SEQSTARTED[0]	0x108		First PWM period started on sequence 0
EVENTS_SEQSTARTED[1]	0x10C		First PWM period started on sequence 1
EVENTS_SEQEND[0]	0x110		Emitted at end of every sequence 0, when last value from RAM has been applied
			to wave counter
EVENTS_SEQEND[1]	0x114		Emitted at end of every sequence 1, when last value from RAM has been applied
			to wave counter
EVENTS_PWMPERIODEND	0x118		Emitted at the end of each PWM period
EVENTS_LOOPSDONE	0x11C		Concatenated sequences have been played the amount of times defined in
			LOOP.CNT
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_SEQSTARTED[0]	0x188		Publish configuration for event SEQSTARTED[0]
PUBLISH_SEQSTARTED[1]	0x18C		Publish configuration for event SEQSTARTED[1]
PUBLISH_SEQEND[0]	0x190		Publish configuration for event SEQEND[0]
PUBLISH_SEQEND[1]	0x194		Publish configuration for event SEQEND[1]

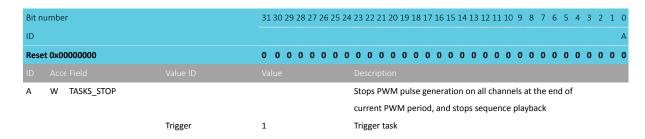
Register	Offset	Security	Description
PUBLISH_PWMPERIODEN	ID 0x198		Publish configuration for event PWMPERIODEND
PUBLISH_LOOPSDONE	0x19C		Publish configuration for event LOOPSDONE
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PWM module enable register
MODE	0x504		Selects operating mode of the wave counter
COUNTERTOP	0x508		Value up to which the pulse generator counter counts
PRESCALER	0x50C		Configuration for PWM_CLK
DECODER	0x510		Configuration of the decoder
LOOP	0x514		Number of playbacks of a loop
SEQ[0].PTR	0x520		Beginning address in RAM of this sequence
SEQ[0].CNT	0x524		Number of values (duty cycles) in this sequence
SEQ[0].REFRESH	0x528		Number of additional PWM periods between samples loaded into compare
			register
SEQ[0].ENDDELAY	0x52C		Time added after the sequence
SEQ[1].PTR	0x540		Beginning address in RAM of this sequence
SEQ[1].CNT	0x544		Number of values (duty cycles) in this sequence
SEQ[1].REFRESH	0x548		Number of additional PWM periods between samples loaded into compare
			register
SEQ[1].ENDDELAY	0x54C		Time added after the sequence
PSEL.OUT[0]	0x560		Output pin select for PWM channel 0
PSEL.OUT[1]	0x564		Output pin select for PWM channel 1
PSEL.OUT[2]	0x568		Output pin select for PWM channel 2
PSEL.OUT[3]	0x56C		Output pin select for PWM channel 3

Table 58: Register overview

6.10.5.1 TASKS_STOP

Address offset: 0x004

Stops PWM pulse generation on all channels at the end of current PWM period, and stops sequence playback



6.10.5.2 TASKS_SEQSTART[n] (n=0..1)

Address offset: $0x008 + (n \times 0x4)$

Loads the first PWM value on all enabled channels from sequence n, and starts playing that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM generation to start if not running.



Bit nu	ımber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_SEQSTART			Loads the first PWM value on all enabled channels from
				sequence n, and starts playing that sequence at the rate
				defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes
				PWM generation to start if not running.
		Trigger	1	Trigger task

6.10.5.3 TASKS_NEXTSTEP

Address offset: 0x010

Steps by one value in the current sequence on all enabled channels if DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_NEXTSTEP			Steps by one value in the current sequence on all enabled
				channels if DECODER.MODE=NextStep. Does not cause
				PWM generation to start if not running.
		Trigger	1	Trigger task

6.10.5.4 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.10.5.5 SUBSCRIBE_SEQSTART[n] (n=0..1)

Address offset: $0x088 + (n \times 0x4)$

Subscribe configuration for task SEQSTART[n]

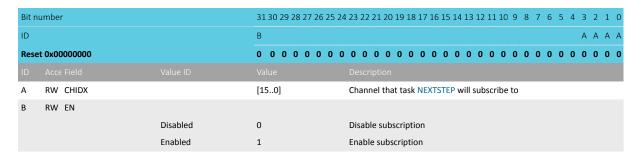
Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task SEQSTART[n] will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription



6.10.5.6 SUBSCRIBE_NEXTSTEP

Address offset: 0x090

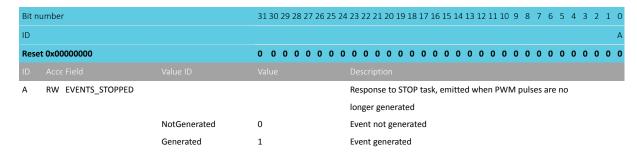
Subscribe configuration for task NEXTSTEP



6.10.5.7 EVENTS_STOPPED

Address offset: 0x104

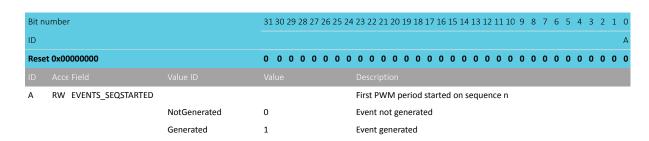
Response to STOP task, emitted when PWM pulses are no longer generated



6.10.5.8 EVENTS SEQSTARTED[n] (n=0..1)

Address offset: $0x108 + (n \times 0x4)$

First PWM period started on sequence n



6.10.5.9 EVENTS SEQEND[n] (n=0..1)

Address offset: $0x110 + (n \times 0x4)$

Emitted at end of every sequence n, when last value from RAM has been applied to wave counter



Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_SEQEND			Emitted at end of every sequence n, when last value from
			RAM has been applied to wave counter
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.10.5.10 EVENTS_PWMPERIODEND

Address offset: 0x118

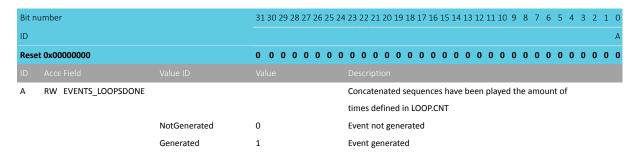
Emitted at the end of each PWM period

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_PWMPERIODE	ND		Emitted at the end of each PWM period
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.10.5.11 EVENTS_LOOPSDONE

Address offset: 0x11C

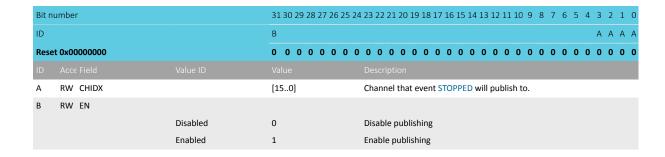
Concatenated sequences have been played the amount of times defined in LOOP.CNT



6.10.5.12 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

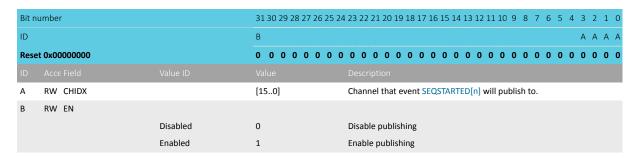




6.10.5.13 PUBLISH_SEQSTARTED[n] (n=0..1)

Address offset: 0x188 + (n × 0x4)

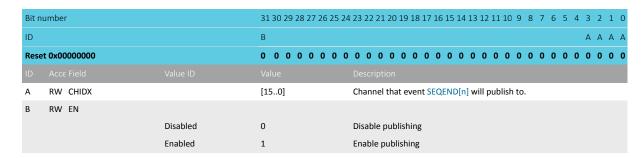
Publish configuration for event SEQSTARTED[n]



6.10.5.14 PUBLISH_SEQEND[n] (n=0..1)

Address offset: $0x190 + (n \times 0x4)$

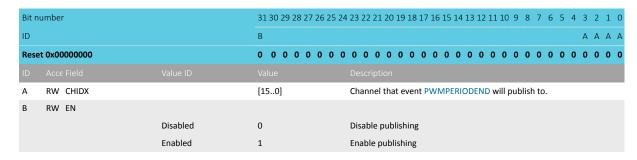
Publish configuration for event SEQEND[n]



6.10.5.15 PUBLISH PWMPERIODEND

Address offset: 0x198

Publish configuration for event PWMPERIODEND



6.10.5.16 PUBLISH_LOOPSDONE

Address offset: 0x19C

Publish configuration for event LOOPSDONE



Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event LOOPSDONE will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.10.5.17 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit nur	mber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E D C B A
Reset (0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
Α	RW SEQENDO_STOP			Shortcut between event SEQEND[0] and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW SEQEND1_STOP			Shortcut between event SEQEND[1] and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
С	RW LOOPSDONE_SEQSTART	0		Shortcut between event LOOPSDONE and task SEQSTART[0]
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW LOOPSDONE_SEQSTART:	1		Shortcut between event LOOPSDONE and task SEQSTART[1]
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
E	RW LOOPSDONE_STOP			Shortcut between event LOOPSDONE and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.10.5.18 INTEN

Address offset: 0x300

Enable or disable interrupt

	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
		H G F E D C B
	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Enable or disable interrupt for event STOPPED
Disabled	0	Disable
Enabled	1	Enable
		Enable or disable interrupt for event SEQSTARTED[i]
Disabled	0	Disable
Enabled	1	Enable
		Enable or disable interrupt for event SEQEND[i]
Disabled	0	Disable
Enabled	1	Enable
		Enable or disable interrupt for event PWMPERIODEND
	Disabled Enabled Disabled Enabled Disabled	Value ID Value Disabled 0 Enabled 0 Enabled 1 Disabled 0 Enabled 1



Bit r	umber		313	0 29	9 28	3 27	26	25	24	23	22 :	21 2	0 1	9 18	3 17	' 16	15	14	13	12 1	1 10	9	8	7	6	5	4	3	2 1	0
ID																								Н	G	F	Ε	D	В	
Rese	et 0x00000000		0	0 0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0
ID																														
		Disabled	0							Dis	abl	е																		
		Enabled	1							Ena	able	9																		
Н	RW LOOPSDONE									Ena	able	or	disa	ble	int	errı	ıpt	for	eve	nt L	.00	PSD	ON	E						
		Disabled	0							Dis	abl	e																		
		Enabled	1							Ena	able	è																		

6.10.5.19 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			H G F E D C B
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
B RW STOPPED			Write '1' to enable interrupt for event STOPPED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
C-D RW SEQSTARTED[i]	(i=01)		Write '1' to enable interrupt for event SEQSTARTED[i]
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
E-F RW SEQEND[i] (i=0	1)		Write '1' to enable interrupt for event SEQEND[i]
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
G RW PWMPERIODE	ND		Write '1' to enable interrupt for event PWMPERIODEND
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
H RW LOOPSDONE			Write '1' to enable interrupt for event LOOPSDONE
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.10.5.20 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number	31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		HGFEDCB
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		
B RW STOPPED		Write '1' to disable interrupt for event STOPPED
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled





Bit nu	ımber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				HGFEDCB
Reset	0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
C-D	RW SEQSTARTED[i] (i=01)			Write '1' to disable interrupt for event SEQSTARTED[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E-F	RW SEQEND[i] (i=01)			Write '1' to disable interrupt for event SEQEND[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW PWMPERIODEND			Write '1' to disable interrupt for event PWMPERIODEND
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW LOOPSDONE			Write '1' to disable interrupt for event LOOPSDONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.10.5.21 ENABLE

Address offset: 0x500

PWM module enable register

Bit number		31 30 29 28 27 26	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable PWM module
	Disabled	0	Disabled
	Enabled	1	Enable

6.10.5.22 MODE

Address offset: 0x504

Selects operating mode of the wave counter

Bit r	number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW UPDOWN			Selects up mode or up-and-down mode for the counter
		Up	0	Up counter, edge-aligned PWM duty cycle
		UpAndDown	1	Up and down counter, center-aligned PWM duty cycle

6.10.5.23 COUNTERTOP

Address offset: 0x508

Value up to which the pulse generator counter counts

NORDIC*

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A	AAAA
Rese	et 0x000003FF	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1 1 1 1
Α	RW COUNTERTOP	[332767] Value up to which the pulse generator counter counts. This	
		register is ignored when DECODER.MODE=WaveForm and	
		only values from RAM are used.	

6.10.5.24 PRESCALER

Address offset: 0x50C

Configuration for PWM_CLK

Bit n	umber		31 30 29 28 27 2	5 25 2	4 23 22 21 20	19 18 1	.7 16 :	15 1	4 13 1	2 11	10 9	8	7	6 5	4	3	2 1	1 0
ID																	A A	4 A
Rese	t 0x00000000		0 0 0 0 0 0	0 (0 0 0 0	0 0	0 0	0 0	0	0 0	0 0	0	0	0 0	0	0	0 (0 0
Α	RW PRESCALER				Prescaler of	f PWM_	CLK											
		DIV_1	0		Divide by 1	(16 MH	z)											
		DIV_2	1		Divide by 2	(8 MHz)											
		DIV_4	2		Divide by 4	(4 MHz)											
		DIV_8	3		Divide by 8	(2 MHz)											
		DIV_16	4		Divide by 1	6 (1 MH	z)											
		DIV_32	5		Divide by 3	2 (500 k	Hz)											
		DIV_64	6		Divide by 6	4 (250 k	Hz)											
		DIV_128	7		Divide by 1	28 (125	kHz)											

6.10.5.25 DECODER

Address offset: 0x510

Configuration of the decoder

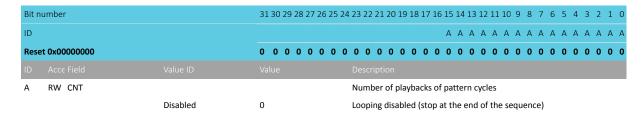
Bit n	umber		31	. 30 2	29 2	28 27	7 26	25 2	24 2	23 2	22 21	1 20	19 1	18 1	17 1	6 1	5 14	113	12	111	0 9	8	7	6	5	4	3 2	1	0
ID																						В						Α	Α
Rese	et 0x00000000		0	0	0	0 0	0	0	0 (0 0	0 0	0	0	0	0 0) (0	0	0	0 (0	0	0	0	0	0	0 0	0	0
ID																													
Α	RW LOAD								H	low	v a s	equ	ence	e is	read	d fr	om	RAN	Лar	ıd sı	orea	d to	th	e					
									c	om	pare	e re	giste	er															
		Common	0						1	Lst h	half	wor	d (1	6-b	it) u	ise	d in	all F	٧N	1 ch	ann	els	03						
		Grouped	1						1	Lst h	half	wor	d (1	6-b	it) u	ise	d in	cha	nne	0	1; 2r	nd v	vor	d in					
									c	har	nnel	23																	
		Individual	2						1	lst h	half	wor	d (1	6-b	it) ir	n cl	1.0;	2nd	in o	h.1	;;	4th	in	ch.3	3				
		WaveForm	3						1	Lst h	half	wor	d (1	6-b	it) ir	n cl	1.0;	2nd	in o	h.1	;;	4th	in						
									C	COU	JNTE	ERTO	P																
В	RW MODE								S	Sele	cts s	sour	ce f	or a	dva	nci	ng 1	the a	activ	e se	eque	ence	9						
		RefreshCount	0						S	EQ	[n].F	REFF	RESH	l is	use	d to	de	terr	nine	loa	ding	g in	terr	ıal					
									c	om	pare	e re	giste	ers															
		NextStep	1						١	NEX.	TSTE	EP ta	ask o	cau	ses	a n	ew	valu	e to	be	load	ed	to i	nte	rna	I			
									C	om	pare	e re	giste	ers															

6.10.5.26 LOOP

Address offset: 0x514



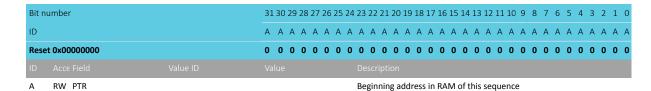
Number of playbacks of a loop



6.10.5.27 SEQ[n].PTR (n=0..1)

Address offset: $0x520 + (n \times 0x20)$

Beginning address in RAM of this sequence

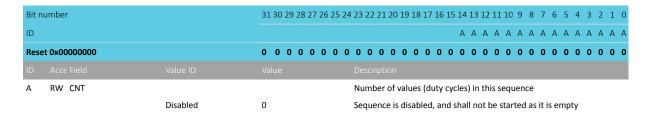


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.10.5.28 SEQ[n].CNT (n=0..1)

Address offset: $0x524 + (n \times 0x20)$

Number of values (duty cycles) in this sequence



6.10.5.29 SEQ[n].REFRESH (n=0..1)

Address offset: $0x528 + (n \times 0x20)$

Number of additional PWM periods between samples loaded into compare register

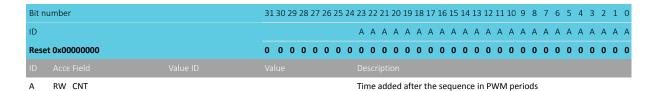
Bit n	umber		313	30	29 2	8 2	7 26	5 25	5 24	1 23	3 22	2 2 1	20	19	18	17	16	15 :	14 1	L3 1	2 1	1 10	9	8	7	6	5	4	3 2	1	0
ID										Α	A	Α	Α	Α	Α	Α	Α	Α	Α.	Α,	A A	A	Α	Α	Α	Α	Α	A	ДД	A	Α
Rese	t 0x0000001		0	0	0 (0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 (0	0	0	0	0	0	0	0 0	0	1
ID																															
Α	RW CNT									N	um	ber	of a	add	itio	nal	PW	۷M	pei	riod	ls b	etwe	en	sar	npl	es					
										lo	ade	ed i	nto	con	npa	ire i	regi	iste	r (le	oad	lev	ery F	REF	RES	H.C	NT	+1				
										Р١	WN	1 pe	rio	ds)																	
		Continuous	0							U	pda	ite (eve	ry P	WN	Ир	erio	od													



6.10.5.30 SEQ[n].ENDDELAY (n=0..1)

Address offset: $0x52C + (n \times 0x20)$

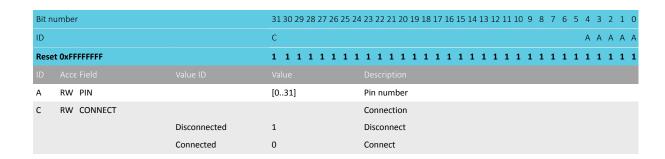
Time added after the sequence



6.10.5.31 PSEL.OUT[n] (n=0..3)

Address offset: $0x560 + (n \times 0x4)$

Output pin select for PWM channel n



6.11 RTC — Real-time counter

The real-time counter (RTC) module provides a generic, low power timer on the low frequency clock source (LFCLK).

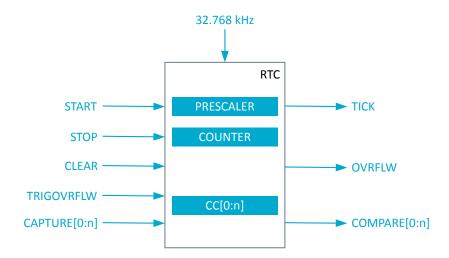


Figure 48: RTC block diagram

The RTC module features a 24-bit COUNTER, a 12-bit (1/X) prescaler, capture/compare registers, and a tick event generator for low power, tickless RTOS implementation.

6.11.1 Clock source

The RTC will run off the LFCLK.



When started, the RTC will automatically request the LFCLK source with RC oscillator if the LFCLK is not already running.

See CLOCK — Clock control on page 64 for more information about clock sources.

6.11.2 Resolution versus overflow and the prescaler

The relationship between the prescaler, counter resolution and overflow is summarized in a table.

Prescaler	Counter resolution	Overflow
0	30.517 μs	512 seconds
2 ⁸ -1	7812.5 μs	131072 seconds
2 ¹² -1	125 ms	582.542 hours

Table 59: RTC resolution versus overflow

Counter increment frequency is given by the following equation:

```
f_{RTC} [kHz] = 32.768 / (PRESCALER + 1 )
```

The PRESCALER register is read/write when the RTC is stopped. Once the RTC is started, the prescaler register is read-only and thus writing to it when the RTC is started has no effect.

The prescaler is restarted on tasks START, CLEAR and TRIGOVRFLW. That is, the prescaler value is latched to an internal register (<<PRESC>>) on these tasks.

Examples:

1. Desired COUNTER frequency 100 Hz (10 ms counter period)

```
PRESCALER = round(32.768 kHz / 100 Hz) - 1 = 327 f_{RTC} = 99.9 Hz 10009.576 \mus counter period
```

2. Desired COUNTER frequency 8 Hz (125 ms counter period)

```
PRESCALER = round(32.768 kHz / 8 Hz) - 1 = 4095 f_{RTC} = 8 Hz
125 ms counter period
```

6.11.3 Counter register

The counter increments on LFCLK when the internal PRESCALER register (<<PRESC>>) is 0x00. <<PRESC>> is reloaded from the PRESCALER register. If enabled, the TICK event occurs on each increment of the COUNTER. The TICK event is disabled by default.



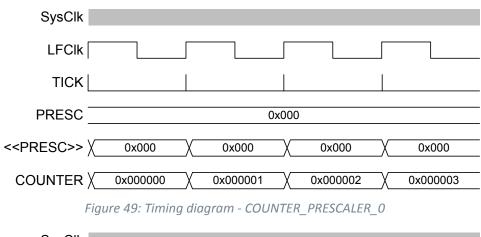


Figure 50: Timing diagram - COUNTER_PRESCALER_1

6.11.4 Overflow

An OVRFLW event is generated on COUNTER register overflow (overflowing from 0xFFFFFF to 0).

The TRIGOVRFLW task will then set the COUNTER value to 0xFFFFF0, to allow software test of the overflow condition.

Note: The OVRFLW event is disabled by default.

6.11.5 Tick event

The TICK event enables low power tick-less RTOS implementation, as it optionally provides a regular interrupt source for an RTOS without the need to use the ARM[®] SysTick feature.

Using the TICK event, rather than the SysTick, allows the CPU to be powered down while still keeping RTOS scheduling active.

Note: The TICK event is disabled by default.

6.11.6 Event control

To optimize RTC power consumption, events in the RTC can be individually disabled to prevent PCLK16M and HFCLK from being requested when those events are triggered. This is managed using the EVTEN register.

For example, if the TICK event is not required for an application, it should be disabled, since its frequent occurrences may increase power consumption when HFCLK otherwise could be powered down for long periods of time.



This means that the RTC implements a slightly different task and event system compared to the standard system described in Peripheral interface on page 15. The RTC task and event system is illustrated in the figure below.

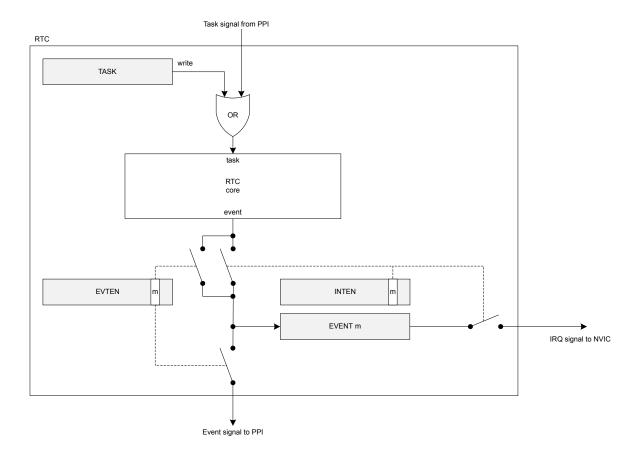


Figure 51: Tasks, events and interrupts in the RTC

6.11.7 Compare

The RTC implements one COMPARE event for every available capture/compare register.

When the COUNTER is incremented and then becomes equal to the value specified in the capture compare register CC[n], the corresponding compare event COMPARE[n] is generated.

When setting a compare register, the following behavior of the RTC COMPARE event should be noted:

• If a CC register value is 0 when a CLEAR task is set, this will not trigger a COMPARE event.



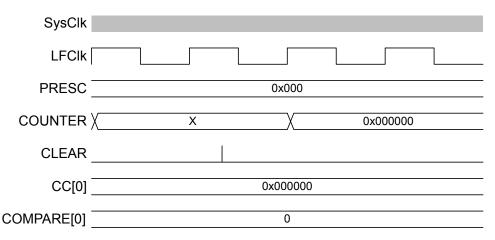


Figure 52: Timing diagram - COMPARE_CLEAR

• If a CC register is N and the COUNTER value is N when the START task is set, this will not trigger a COMPARE event.

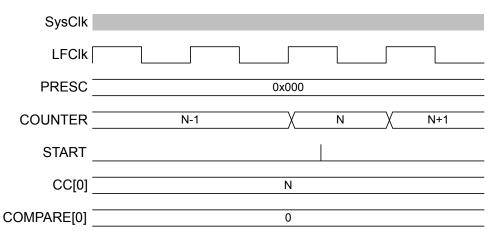


Figure 53: Timing diagram - COMPARE_START

• A COMPARE event occurs when a CC register is N and the COUNTER value transitions from N-1 to N.

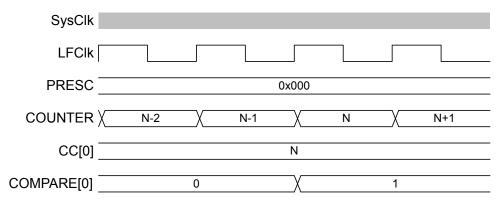


Figure 54: Timing diagram - COMPARE

• If the COUNTER is N, writing N+2 to a CC register is guaranteed to trigger a COMPARE event at N+2.



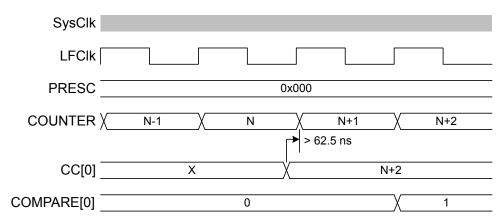


Figure 55: Timing diagram - COMPARE_N+2

• If the COUNTER is N, writing N or N+1 to a CC register may not trigger a COMPARE event.

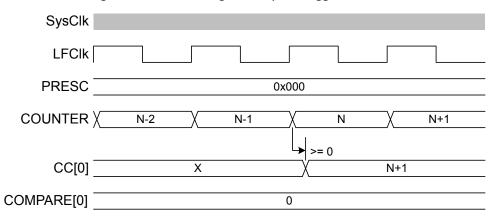


Figure 56: Timing diagram - COMPARE N+1

• If the COUNTER is N and the current CC register value is N+1 or N+2 when a new CC value is written, a match may trigger on the previous CC value before the new value takes effect. If the current CC value greater than N+2 when the new value is written, there will be no event due to the old value.

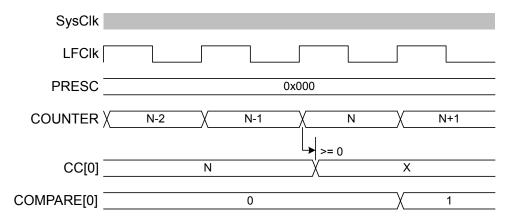


Figure 57: Timing diagram - COMPARE_N-1

6.11.8 Task and event jitter/delay

Jitter or delay in the RTC is due to the peripheral clock being a low frequency clock (LFCLK) which is not synchronous to the faster PCLK16M.

Registers in the peripheral interface, part of the PCLK16M domain, have a set of mirrored registers in the LFCLK domain. For example, the COUNTER value accessible from the CPU is in the PCLK16M domain and is latched on read from an internal COUNTER register in the LFCLK domain. The COUNTER register is modified each time the RTC ticks. The registers are synchronised between the two clock domains (PCLK16M and LFCLK).

NORDIC

1. CLEAR and STOP (and TRIGOVRFLW; not shown) will be delayed as long as it takes for the peripheral to clock a falling edge and rising of the LFCLK. This is between 15.2585 μ s and 45.7755 μ s – rounded to 15 μ s and 46 μ s for the remainder of the section.

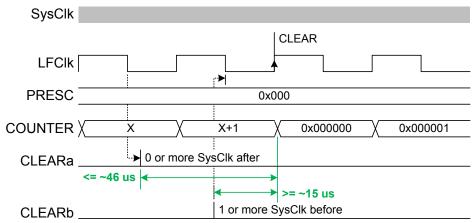


Figure 58: Timing diagram - DELAY_CLEAR

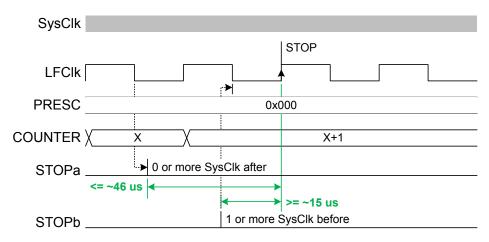


Figure 59: Timing diagram - DELAY_STOP

2. The START task will start the RTC. Assuming that the LFCLK was previously running and stable, the first increment of COUNTER (and instance of TICK event) will be typically after 30.5 μ s +/-15 μ s. In some cases, in particular if the RTC is started before the LFCLK is running, that timing can be up to ~250 μ s. The software should therefore wait for the first TICK if it has to make sure the RTC is running. Sending a TRIGOVRFLW task sets the COUNTER to a value close to overflow. However, since the update of COUNTER relies on a stable LFCLK, sending this task while LFCLK is not running will start LFCLK, but the update will then be delayed by the same amount of time of up to ~250 μ s. The figures show the smallest and largest delays on the START task, appearing as a +/-15 μ s jitter on the first COUNTER increment.

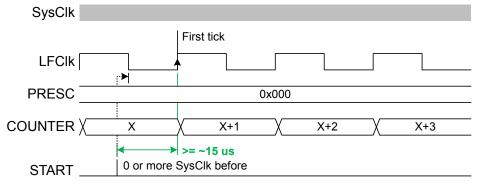


Figure 60: Timing diagram - JITTER_START-



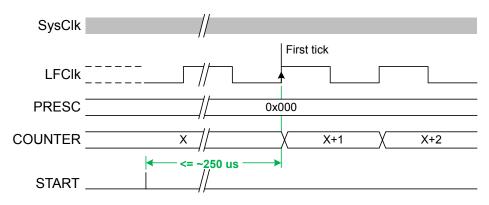


Figure 61: Timing diagram - JITTER_START+

Tables below summarize the jitter introduced on tasks and events.

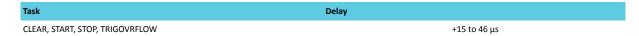


Table 60: RTC jitter magnitudes on tasks

Operation/Function	Jitter
START to COUNTER increment	+/- 15 μs
COMPARE to COMPARE ⁸	+/- 62.5 ns

Table 61: RTC jitter magnitudes on events

6.11.9 Reading the counter register

To read the COUNTER register, the internal <<COUNTER>> value is sampled.

To ensure that the <<COUNTER>> is safely sampled (considering that an LFCLK transition may occur during a read), the CPU and core memory bus are halted for three cycles by lowering the core PREADY signal. The read takes the CPU two cycles in addition, resulting in the COUNTER register read taking fixed five PCLK16M clock cycles.

6.11.10 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50014000	RTC	RTC0 : S	uc	NA	Real time counter 0	
0x40014000	RIC	RTC0 : NS	US	NA	Real time counter o	
0x50015000	RTC	RTC1:S	US	NA	Real time counter 1	
0x40015000	RIC	RTC1: NS	US	NA	Real time counter 1	

Table 62: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Start RTC counter
TASKS_STOP	0x004		Stop RTC counter
TASKS_CLEAR	0x008		Clear RTC counter

 $^{^{\}rm 8}\,$ Assumes RTC runs continuously between these events.

Note: 32.768 kHz clock jitter is additional to the numbers provided above.

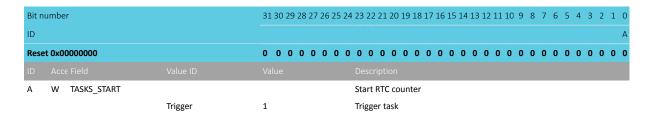
NORDIC*

Register	Offset	Security	Description
TASKS_TRIGOVRFLW	0x00C		Set counter to 0xFFFFF0
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_CLEAR	0x088		Subscribe configuration for task CLEAR
SUBSCRIBE_TRIGOVRFLW	0x08C		Subscribe configuration for task TRIGOVRFLW
EVENTS_TICK	0x100		Event on counter increment
EVENTS_OVRFLW	0x104		Event on counter overflow
EVENTS_COMPARE[0]	0x140		Compare event on CC[0] match
EVENTS_COMPARE[1]	0x144		Compare event on CC[1] match
EVENTS_COMPARE[2]	0x148		Compare event on CC[2] match
EVENTS_COMPARE[3]	0x14C		Compare event on CC[3] match
PUBLISH_TICK	0x180		Publish configuration for event TICK
PUBLISH_OVRFLW	0x184		Publish configuration for event OVRFLW
PUBLISH_COMPARE[0]	0x1C0		Publish configuration for event COMPARE[0]
PUBLISH_COMPARE[1]	0x1C4		Publish configuration for event COMPARE[1]
PUBLISH_COMPARE[2]	0x1C8		Publish configuration for event COMPARE[2]
PUBLISH_COMPARE[3]	0x1CC		Publish configuration for event COMPARE[3]
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
EVTEN	0x340		Enable or disable event routing
EVTENSET	0x344		Enable event routing
EVTENCLR	0x348		Disable event routing
COUNTER	0x504		Current counter value
PRESCALER	0x508		12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written
			when RTC is stopped.
CC[n]	0x540		Compare register n

Table 63: Register overview

6.11.10.1 TASKS_START

Address offset: 0x000 Start RTC counter



6.11.10.2 TASKS_STOP

Address offset: 0x004

Stop RTC counter



Bit n	um	ber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	et O	x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	/ TASKS_STOP			Stop RTC counter
			Trigger	1	Trigger task

6.11.10.3 TASKS_CLEAR

Address offset: 0x008 Clear RTC counter

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_CLEAR			Clear RTC counter
		Trigger	1	Trigger task

6.11.10.4 TASKS_TRIGOVRFLW

Address offset: 0x00C Set counter to 0xFFFFF0

Bit r	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_TRIGOVRFLW			Set counter to 0xFFFFF0
		Trigger	1	Trigger task

6.11.10.5 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.11.10.6 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP



Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.11.10.7 SUBSCRIBE_CLEAR

Address offset: 0x088

Subscribe configuration for task CLEAR

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task CLEAR will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.11.10.8 SUBSCRIBE_TRIGOVRFLW

Address offset: 0x08C

Subscribe configuration for task TRIGOVRFLW

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task TRIGOVRFLW will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.11.10.9 EVENTS_TICK

Address offset: 0x100

Event on counter increment

Bit n	umber		31	30	29 2	28 2	7 2	26 2	5 2	24 2	3 2	22	21 2	20 :	19 1	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																																	Α
Rese	t 0x00000000		0	0	0	0 (0	0 ()	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0
ID	Acce Field	Value ID	Val	ue						[)es	cri	ptic	n																			
Α	RW EVENTS_TICK									E	ve	nt	on (cou	inte	r ir	ncr	em	en	t													
		NotGenerated	0							E	ve	nt	not	ge	ner	ate	d																
		Generated	1							E	ve	nt	gen	era	ited	ı																	

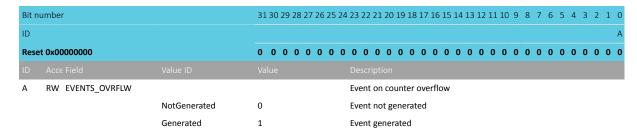




6.11.10.10 EVENTS_OVRFLW

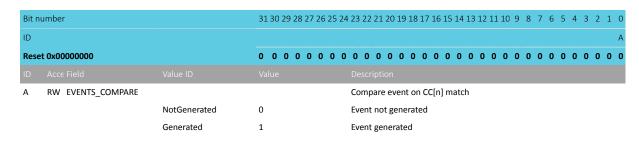
Address offset: 0x104

Event on counter overflow



6.11.10.11 EVENTS COMPARE[n] (n=0..3)

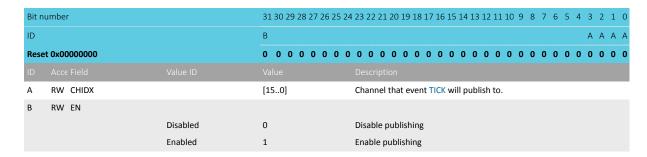
Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match



6.11.10.12 PUBLISH_TICK

Address offset: 0x180

Publish configuration for event TICK



6.11.10.13 PUBLISH_OVRFLW

Address offset: 0x184

Publish configuration for event OVRFLW



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A /
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event OVRFLW will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.11.10.14 PUBLISH_COMPARE[n] (n=0..3)

Address offset: $0x1C0 + (n \times 0x4)$

Publish configuration for event COMPARE[n]

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event COMPARE[n] will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.11.10.15 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

6.11.10.16 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW TICK			Write '1' to enable interrupt for event TICK
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW OVRFLW			Write '1' to enable interrupt for event OVRFLW
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-F	RW COMPARE[i] (i=03)			Write '1' to enable interrupt for event COMPARE[i]
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



6.11.10.17 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW TICK			Write '1' to disable interrupt for event TICK
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW OVRFLW			Write '1' to disable interrupt for event OVRFLW
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
C-F	RW COMPARE[i] (i=03)			Write '1' to disable interrupt for event COMPARE[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.11.10.18 EVTEN

Address offset: 0x340

Enable or disable event routing

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW TICK			Enable or disable event routing for event TICK
		Disabled	0	Disable
		Enabled	1	Disable
В	RW OVRFLW			Enable or disable event routing for event OVRFLW
		Disabled	0	Disable
		Enabled	1	Disable
C-F	RW COMPARE[i] (i=03)			Enable or disable event routing for event COMPARE[i]
		Disabled	0	Disable
		Enabled	1	Disable

6.11.10.19 EVTENSET

Address offset: 0x344 Enable event routing

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW TICK			Write '1' to enable event routing for event TICK
	Disabled	0	Read: Disabled



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		Enabled	1	Read: Enabled
		Set	1	Enable
В	RW OVRFLW			Write '1' to enable event routing for event OVRFLW
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
		Set	1	Enable
C-F	RW COMPARE[i] (i=03)			Write '1' to enable event routing for event COMPARE[i]
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
		Set	1	Enable

6.11.10.20 EVTENCLR

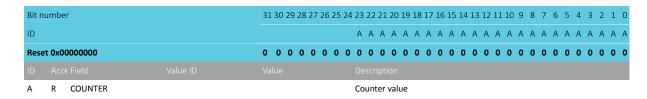
Address offset: 0x348

Disable event routing

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW TICK			Write '1' to disable event routing for event TICK
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
		Clear	1	Disable
В	RW OVRFLW			Write '1' to disable event routing for event OVRFLW
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
		Clear	1	Disable
C-F	RW COMPARE[i] (i=03)			Write '1' to disable event routing for event COMPARE[i]
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
		Clear	1	Disable

6.11.10.21 COUNTER

Address offset: 0x504 Current counter value



6.11.10.22 PRESCALER

Address offset: 0x508

12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written when RTC is stopped.

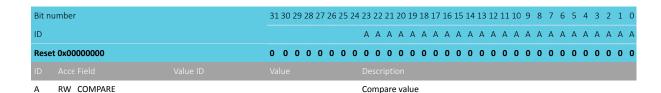


ID Acce Field			
neset executed			
Reset 0x00000000	0 0 0 0 0 0	000000000000000000000000000000000000000	0 0
ID		A A A A A A A A A A A A A A A A A A A	. A A
Bit number	31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0

6.11.10.23 CC[n] (n=0..3)

Address offset: $0x540 + (n \times 0x4)$

Compare register n



6.11.11 Electrical specification

6.12 SAADC — Successive approximation analog-to-digital converter

The ADC is a differential successive approximation register (SAR) analog-to-digital converter.

Listed here are the main features of SAADC:

- 8/10/12-bit resolution, 14-bit resolution with oversampling
- · Up to eight input channels
 - One channel per single-ended input and two channels per differential input
 - Scan mode can be configured with both single-ended channels and differential channels.
- Full scale input range (0 to VDD)
- Sampling triggered via a task from software or a PPI channel for full flexibility on sample frequency source from low power 32.768kHz RTC or more accurate 1/16MHz Timers
- One-shot conversion mode to sample a single channel
- Scan mode to sample a series of channels in sequence. Sample delay between channels is t_{ack} + t_{conv} which may vary between channels according to user configuration of t_{ack}.
- Support for direct sample transfer to RAM using EasyDMA
- Interrupts on single sample and full buffer events
- Samples stored as 16-bit 2's complement values for differential and single-ended sampling
- · Continuous sampling without the need of an external timer
- · Internal resistor string
- · Limit checking on the fly

6.12.1 Shared resources

The ADC can coexist with COMP and other peripherals using one of AIN0-AIN7, provided these are assigned to different pins.

It is not recommended to select the same analog input pin for both modules.



6.12.2 Overview

The ADC supports up to eight external analog input channels, depending on package variant. It can be operated in a one-shot mode with sampling under software control, or a continuous conversion mode with a programmable sampling rate.

The analog inputs can be configured as eight single-ended inputs, four differential inputs or a combination of these. Each channel can be configured to select AINO to AIN7 pins, or the VDD pin. Channels can be sampled individually in one-shot or continuous sampling modes, or, using scan mode, multiple channels can be sampled in sequence. Channels can also be oversampled to improve noise performance.

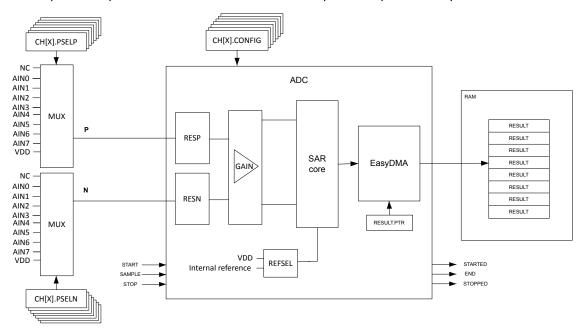


Figure 62: Simplified ADC block diagram

Internally, the ADC is always a differential analog-to-digital converter, but by default it is configured with single-ended input in the MODE field of the CH[n].CONFIG register. In single-ended mode, the negative input will be shorted to ground internally.

The assumption in single-ended mode is that the internal ground of the ADC is the same as the external ground that the measured voltage is referred to. The ADC is thus sensitive to ground bounce on the PCB in single-ended mode. If this is a concern we recommend using differential measurement.

6.12.3 Digital output

The output result of the ADC depends on the settings in the CH[n].CONFIG and RESOLUTION registers as follows:

```
RESULT = [V(P) - V(N)] * GAIN/REFERENCE * 2 (RESOLUTION - m)
```

where

V(P)

is the voltage at input P

V(N)

is the voltage at input N

GAIN

is the selected gain setting



REFERENCE

is the selected reference voltage

and m=0 if CONFIG.MODE=SE, or m=1 if CONFIG.MODE=Diff.

The result generated by the ADC will deviate from the expected due DC errors like offset, gain, differential non-linearity (DNL), and integral non-linearity (INL). See Electrical specification for details on these parameters. The result can also vary due to AC errors like non-linearities in the GAIN block, settling errors due to high source impedance and sampling jitter. For battery measurement the DC errors are most noticeable.

The ADC has a wide selection of gains controlled in the GAIN field of the CH[n].CONFIG register. If CH[n].CONFIG.REFSEL=0, the input range of the ADC core is nominally ± 0.6 V differential and the input must be scaled accordingly.

The ADC has a temperature dependent offset. If the ADC is to operate over a large temperature range, we recommend running CALIBRATEOFFSET at regular intervals. The CALIBRATEDONE event will be fired when the calibration has been completed. Note that the DONE and RESULTDONE events will also be generated.

6.12.4 Analog inputs and channels

Up to eight analog input channels, CH[n](n=0..7), can be configured.

See Shared resources on page 195 for shared input with comparators.

Any one of the available channels can be enabled for the ADC to operate in one-shot mode. If more than one CH[n] is configured, the ADC enters scan mode.

An analog input is selected as a positive converter input if CH[n].PSELP is set, setting CH[n].PSELP also enables the particular channel.

An analog input is selected as a negative converter input if CH[n].PSELN is set. The CH[n].PSELN register will have no effect unless differential mode is enabled, see MODE field in CH[n].CONFIG register.

If more than one of the CH[n].PSELP registers is set, the device enters scan mode. Input selections in scan mode are controlled by the CH[n].PSELP and CH[n].PSELN registers, where CH[n].PSELN is only used if the particular scan channel is specified as differential, see MODE field in CH[n].CONFIG register.

Important: Channels selected for COMP cannot be used at the same time for ADC sampling, though channels not selected for use by these blocks can be used by the ADC.

6.12.5 Operation modes

The ADC input configuration supports one-shot mode, continuous mode and scan mode.

Scan mode and oversampling cannot be combined.

6.12.5.1 One-shot mode

One-shot operation is configured by enabling only one of the available channels defined by CH[n].PSELP, CH[n].PSELN, and CH[n].CONFIG registers.

Upon a SAMPLE task, the ADC starts to sample the input voltage. The CH[n].CONFIG.TACQ controls the acquisition time.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA. For more information, see EasyDMA on page 199.



6.12.5.2 Continuous mode

Continuous sampling can be achieved by using the internal timer in the ADC, or triggering the SAMPLE task from one of the general purpose timers through the PPI.

Care shall be taken to ensure that the sample rate fulfils the following criteria, depending on how many channels are active:

```
f_{SAMPLE} < 1/[t_{ACO} + t_{conv}]
```

The SAMPLERATE register can be used as a local timer instead of triggering individual SAMPLE tasks. When SAMPLERATE.MODE is set to Timers, it is sufficient to trigger SAMPLE task only once in order to start the SAADC and triggering the STOP task will stop sampling. The SAMPLERATE.CC field controls the sample rate.

The SAMPLERATE timer mode cannot be combined with SCAN mode, and only one channel can be enabled in this mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.5.3 Oversampling

An accumulator in the ADC can be used to average noise on the analog input. In general, oversampling improves the signal-to-noise ratio (SNR). Oversampling, however, does not improve the integral non-linearity (INL), or differential non-linearity (DNL).

Oversampling and scan should not be combined, since oversampling and scan will average over input channels.

The accumulator is controlled in the OVERSAMPLE register. The SAMPLE task must be set 2^{OVERSAMPLE} number of times before the result is written to RAM. This can be achieved by:

- Configuring a fixed sampling rate using the local timer or a general purpose timer and PPI to trigger a SAMPLE task
- Triggering SAMPLE 2^{OVERSAMPLE} times from software
- · Enabling BURST mode

CH[n].CONFIG.BURST can be enabled to avoid setting SAMPLE task $2^{OVERSAMPLE}$ times. With BURST = 1 the ADC will sample the input $2^{OVERSAMPLE}$ times as fast as it can (actual timing: $<(t_{ACQ}+t_{CONV})\times 2^{OVERSAMPLE})$. Thus, for the user it will just appear like the conversion took a bit longer time, but other than that, it is similar to one-shot mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals that enough conversions have taken place for an oversampled result to get transferred into RAM. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.5.4 Scan mode

A channel is considered enabled if CH[n].PSELP is set. If more than one channel, CH[n], is enabled, the ADC enters scan mode.

In scan mode, one SAMPLE task will trigger one conversion per enabled channel. The time it takes to sample all channels is:

```
Total time < Sum(CH[x].t_{ACQ}+t_{CONV}), x=0..enabled channels
```

A DONE event signals that one sample has been taken.



In this mode, the RESULTDONE event signals has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual values have been transferred into RAM by EasyDMA.

Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled on page 199 provides an example of results placement in Data RAM, with an even RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled.

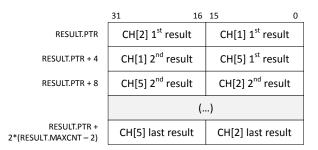


Figure 63: Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled

Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled on page 199 provides an example of results placement in Data RAM, with an odd RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled. The last 32-bit word is populated only with one 16-bit result.

	31 16	15 0
RESULT.PTR	CH[2] 1 st result	CH[1] 1 st result
RESULT.PTR + 4	CH[1] 2 nd result	CH[5] 1 st result
RESULT.PTR + 8	CH[5] 2 nd result	CH[2] 2 nd result
	()
RESULT.PTR + 2*(RESULT.MAXCNT – 1)		CH[5] last result

Figure 64: Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled

6.12.6 EasyDMA

After configuring RESULT.PTR and RESULT.MAXCNT, the ADC resources are started by triggering the START task. The ADC is using EasyDMA to store results in a Result buffer in RAM.

The Result buffer is located at the address specified in the RESULT.PTR register. The RESULT.PTR register is double-buffered and it can be updated and prepared for the next START task immediately after the STARTED event is generated. The size of the Result buffer is specified in the RESULT.MAXCNT register and the ADC will generate an END event when it has filled up the Result buffer, see ADC on page 200. Results are stored in little-endian byte order in Data RAM. Every sample will be sign extended to 16 bit before stored in the Result buffer.

The ADC is stopped by triggering the STOP task. The STOP task will terminate an ongoing sampling. The ADC will generate a STOPPED event when it has stopped. If the ADC is already stopped when the STOP task is triggered, the STOPPED event will still be generated.



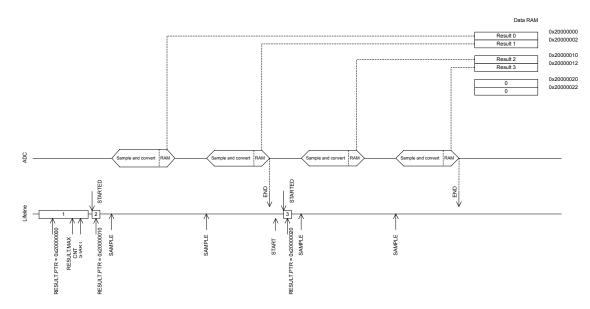


Figure 65: ADC

If the RESULT.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

The EasyDMA will have finished accessing the RAM when the END or STOPPED event has been generated.

The RESULT.AMOUNT register can be read following an END event or a STOPPED event to see how many results have been transferred to the Result buffer in RAM since the START task was triggered.

In scan mode, SAMPLE tasks can be triggered once the START task is triggered. The END event is generated when the number of samples transferred to memory reaches the value specified by RESULT.MAXCNT.

After an END event, the START task needs to be triggered again before new samples can be taken. Also make sure that the size of the Result buffer is large enough to have space for minimum one result from each of the enabled channels, by specifying RESULT.MAXCNT >= number of channels enabled. For more information about the scan mode, see Scan mode on page 198.

6.12.7 Resistor ladder

The ADC has an internal resistor string for positive and negative input.

See Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP) on page 201. The resistors are controlled in the CH[n].CONFIG.RESP and CH[n].CONFIG.RESN registers.



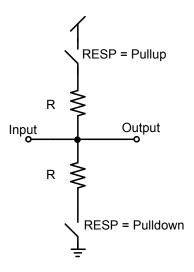


Figure 66: Resistor ladder for positive input (negative input is equivalent, using RESN) instead of RESP)

6.12.8 Reference

The ADC can use two different references, controlled in the REFSEL field of the CH[n].CONFIG register.

These are:

- Internal reference
- VDD as reference

The internal reference results in an input range of ± 0.6 V on the ADC core. VDD as reference results in an input range of $\pm VDD/4$ on the ADC core. The gain block can be used to change the effective input range of the ADC.

```
Input range = (+- 0.6 \text{ V or } +-\text{VDD}/4)/\text{Gain}
```

For example, choosing VDD as reference, single ended input (grounded negative input), and a gain of 1/4 the input range will be:

```
Input range = (VDD/4)/(1/4) = VDD
```

With internal reference, single ended input (grounded negative input), and a gain of 1/6 the input range will be:

```
Input range = (0.6 \text{ V})/(1/6) = 3.6 \text{ V}
```

The AINO-AIN7 inputs cannot exceed VDD, or be lower than VSS.

6.12.9 Acquisition time

To sample the input voltage, the ADC connects a capacitor to the input.

For illustration, see Simplified ADC sample network on page 202. The acquisition time indicates how long the capacitor is connected, see TACQ field in CH[n].CONFIG register. The required acquisition time depends on the source (R_{source}) resistance. For high source resistance the acquisition time should be increased, see Acquisition time on page 202.



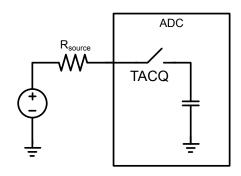


Figure 67: Simplified ADC sample network

TACQ [µs]	Maximum source resistance [kOhm]
3	10
5	40
10	100
15	200
20	400
40	800

Table 64: Acquisition time

6.12.10 Limits event monitoring

A channel can be event monitored by configuring limit register CH[n].LIMIT.

If the conversion result is higher than the defined high limit, or lower than the defined low limit, the appropriate event will get fired.

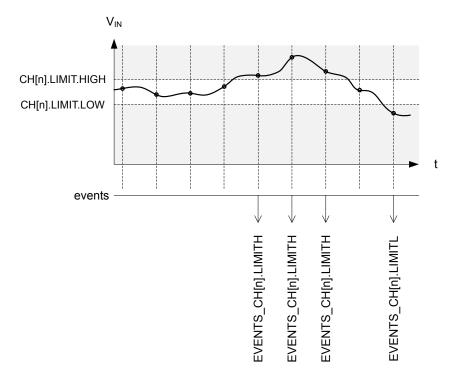


Figure 68: Example of limits monitoring on channel 'n'



Note that when setting the limits, CH[n].LIMIT.HIGH shall always be higher than or equal to CH[n].LIMIT.LOW . In other words, an event can be fired only when the input signal has been sampled outside of the defined limits. It is not possible to fire an event when the input signal is inside a defined range by swapping high and low limits.

The comparison to limits always takes place, there is no need to enable it. If comparison is not required on a channel, the software shall simply ignore the related events. In that situation, the value of the limits registers is irrelevant, so it does not matter if CH[n].LIMIT.LOW is lower than CH[n].LIMIT.HIGH or not.

6.12.11 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000E000	SAADC	SAADC : S	US	SA	Analog to digital converter	
0x4000E000	SAADC	SAADC : NS	03	SA	Analog to digital converter	

Table 65: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Start the ADC and prepare the result buffer in RAM
TASKS_SAMPLE	0x004		Take one ADC sample, if scan is enabled all channels are sampled
TASKS_STOP	0x008		Stop the ADC and terminate any on-going conversion
TASKS_CALIBRATEOFFSET	0x00C		Starts offset auto-calibration
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_SAMPLE	0x084		Subscribe configuration for task SAMPLE
SUBSCRIBE_STOP	0x088		Subscribe configuration for task STOP
SUBSCRIBE_CALIBRATEOFF	0x08C		Subscribe configuration for task CALIBRATEOFFSET
EVENTS_STARTED	0x100		The ADC has started
EVENTS_END	0x104		The ADC has filled up the Result buffer
EVENTS_DONE	0x108		A conversion task has been completed. Depending on the mode, multiple
			conversions might be needed for a result to be transferred to RAM.
EVENTS_RESULTDONE	0x10C		A result is ready to get transferred to RAM.
EVENTS_CALIBRATEDONE	0x110		Calibration is complete
EVENTS_STOPPED	0x114		The ADC has stopped
EVENTS_CH[0].LIMITH	0x118		Last results is equal or above CH[0].LIMIT.HIGH
EVENTS_CH[0].LIMITL	0x11C		Last results is equal or below CH[0].LIMIT.LOW
EVENTS_CH[1].LIMITH	0x120		Last results is equal or above CH[1].LIMIT.HIGH
EVENTS_CH[1].LIMITL	0x124		Last results is equal or below CH[1].LIMIT.LOW
EVENTS_CH[2].LIMITH	0x128		Last results is equal or above CH[2].LIMIT.HIGH
EVENTS_CH[2].LIMITL	0x12C		Last results is equal or below CH[2].LIMIT.LOW
EVENTS_CH[3].LIMITH	0x130		Last results is equal or above CH[3].LIMIT.HIGH
EVENTS_CH[3].LIMITL	0x134		Last results is equal or below CH[3].LIMIT.LOW
EVENTS_CH[4].LIMITH	0x138		Last results is equal or above CH[4].LIMIT.HIGH
EVENTS_CH[4].LIMITL	0x13C		Last results is equal or below CH[4].LIMIT.LOW
EVENTS_CH[5].LIMITH	0x140		Last results is equal or above CH[5].LIMIT.HIGH
EVENTS_CH[5].LIMITL	0x144		Last results is equal or below CH[5].LIMIT.LOW
EVENTS_CH[6].LIMITH	0x148		Last results is equal or above CH[6].LIMIT.HIGH
EVENTS_CH[6].LIMITL	0x14C		Last results is equal or below CH[6].LIMIT.LOW
EVENTS_CH[7].LIMITH	0x150		Last results is equal or above CH[7].LIMIT.HIGH
EVENTS_CH[7].LIMITL	0x154		Last results is equal or below CH[7].LIMIT.LOW
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_END	0x184		Publish configuration for event END
PUBLISH_DONE	0x188		Publish configuration for event DONE
PUBLISH_RESULTDONE	0x18C		Publish configuration for event RESULTDONE
PUBLISH_CALIBRATEDONE	0x190		Publish configuration for event CALIBRATEDONE

Register	Offset	Security	Description
PUBLISH_STOPPED	0x194		Publish configuration for event STOPPED
PUBLISH CH[0].LIMITH	0x198		Publish configuration for event CH[0].LIMITH
PUBLISH_CH[0].LIMITL	0x19C		Publish configuration for event CH[0].LIMITL
PUBLISH_CH[1].LIMITH	0x1A0		Publish configuration for event CH[1].LIMITH
PUBLISH_CH[1].LIMITL	0x1A4		Publish configuration for event CH[1].LIMITL
PUBLISH_CH[2].LIMITH	0x1A8		Publish configuration for event CH[2].LIMITH
PUBLISH_CH[2].LIMITL	0x1AC		Publish configuration for event CH[2].LIMITL
PUBLISH CH[3].LIMITH	0x1B0		Publish configuration for event CH[3].LIMITH
PUBLISH_CH[3].LIMITL	0x1B4		Publish configuration for event CH[3].LIMITL
PUBLISH_CH[4].LIMITH	0x1B8		Publish configuration for event CH[4].LIMITH
PUBLISH_CH[4].LIMITL	0x1BC		Publish configuration for event CH[4].LIMITL
PUBLISH_CH[5].LIMITH	0x1C0		Publish configuration for event CH[5].LIMITH
PUBLISH_CH[5].LIMITL	0x1C4		Publish configuration for event CH[5].LIMITL
PUBLISH CH[6].LIMITH	0x1C8		Publish configuration for event CH[6].LIMITH
PUBLISH_CH[6].LIMITL	0x1CC		Publish configuration for event CH[6].LIMITL
PUBLISH_CH[7].LIMITH	0x1D0		Publish configuration for event CH[7].LIMITH
PUBLISH CH[7].LIMITL	0x1D4		Publish configuration for event CH[7].LIMITL
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x304		Disable interrupt
STATUS	0x400		Status
ENABLE	0x500		Enable or disable ADC
CH[0].PSELP	0x510		Input positive pin selection for CH[0]
CH[0].PSELN	0x514		
CH[0].CONFIG	0x514 0x518		Input negative pin selection for CH[0]
CH[0].LIMIT	0x516		Input configuration for CH[0] High/low limits for event monitoring a channel
CH[1].PSELP	0x520 0x524		Input positive pin selection for CH[1]
CH[1].PSELN CH[1].CONFIG			Input negative pin selection for CH[1]
	0x528		Input configuration for CH[1]
CH[1].LIMIT	0x52C		High/low limits for event monitoring a channel
CH[2].PSELP	0x530		Input positive pin selection for CH[2] Input negative pin selection for CH[2]
CH[2].PSELN	0x534		, , , , , , , , , , , , , , , , , , , ,
CH[2].CONFIG	0x538		Input configuration for CH[2]
CH[2].LIMIT	0x53C		High/low limits for event monitoring a channel
CH[3].PSELP	0x540		Input positive pin selection for CH[3]
CH[3].PSELN	0x544		Input negative pin selection for CH[3]
CH[3].CONFIG	0x548		Input configuration for CH[3]
CH[3].LIMIT	0x54C		High/low limits for event monitoring a channel
CH[4].PSELP	0x550		Input positive pin selection for CH[4]
CH[4].PSELN	0x554		Input negative pin selection for CH[4]
CH[4].CONFIG	0x558		Input configuration for CH[4]
CH[4].LIMIT	0x55C		High/low limits for event monitoring a channel
CH[5].PSELP	0x560		Input positive pin selection for CH[5]
CH[5].PSELN	0x564		Input negative pin selection for CH[5]
CH[5].CONFIG	0x568		Input configuration for CH[5]
CH[5].LIMIT	0x56C		High/low limits for event monitoring a channel
CH[6].PSELP	0x570		Input positive pin selection for CH[6]
CH[6].PSELN	0x574		Input negative pin selection for CH[6]
CH[6].CONFIG	0x578		Input configuration for CH[6]
CH[6].LIMIT	0x57C		High/low limits for event monitoring a channel
CH[7].PSELP	0x580		Input positive pin selection for CH[7]
CH[7].PSELN	0x584		Input negative pin selection for CH[7]
CH[7].CONFIG	0x588		Input configuration for CH[7]



Register	Offset	Security	Description
CH[7].LIMIT	0x58C		High/low limits for event monitoring a channel
RESOLUTION	0x5F0		Resolution configuration
OVERSAMPLE	0x5F4		Oversampling configuration. OVERSAMPLE should not be combined with SCAN.
			The RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher
			RESOLUTION should be used.
SAMPLERATE	0x5F8		Controls normal or continuous sample rate
RESULT.PTR	0x62C		Data pointer
RESULT.MAXCNT	0x630		Maximum number of buffer words to transfer
RESULT.AMOUNT	0x634		Number of buffer words transferred since last START

Table 66: Register overview

6.12.11.1 TASKS_START

Address offset: 0x000

Start the ADC and prepare the result buffer in RAM

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_START			Start the ADC and prepare the result buffer in RAM
		Trigger	1	Trigger task

6.12.11.2 TASKS_SAMPLE

Address offset: 0x004

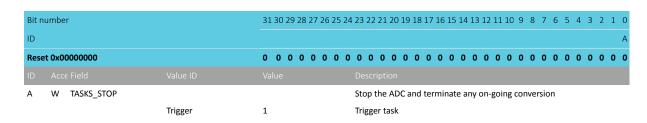
Take one ADC sample, if scan is enabled all channels are sampled

Bit r	number		313	30 2	9 28	3 27	26	25	24	23	22	2 2 1	20	19	9 18	3 17	7 16	5 15	5 14	1 13	12	11	10	9	8	7	6	5 4	4 3	2	1	. 0
ID																																Α
Res	et 0x00000000		0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 (0	0	0
ID																																
Α	W TASKS_SAMPLE									Ta	ke	one	e Al	DC	sar	npl	e, i	f sc	an	is e	nal	oled	d all	cha	ann	els	are					
										sa	mp	oled	i																			
		Trigger	1							Tri	igg	er t	ask	(

6.12.11.3 TASKS_STOP

Address offset: 0x008

Stop the ADC and terminate any on-going conversion

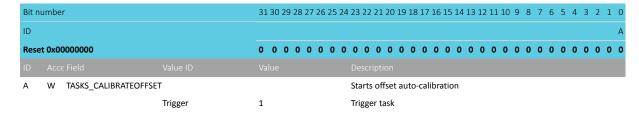


6.12.11.4 TASKS_CALIBRATEOFFSET

Address offset: 0x00C



Starts offset auto-calibration



6.12.11.5 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.12.11.6 SUBSCRIBE_SAMPLE

Address offset: 0x084

Subscribe configuration for task SAMPLE

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task SAMPLE will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.12.11.7 SUBSCRIBE_STOP

Address offset: 0x088

Subscribe configuration for task STOP

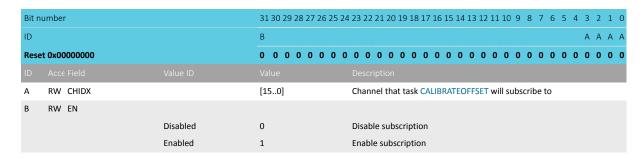
Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription



6.12.11.8 SUBSCRIBE_CALIBRATEOFFSET

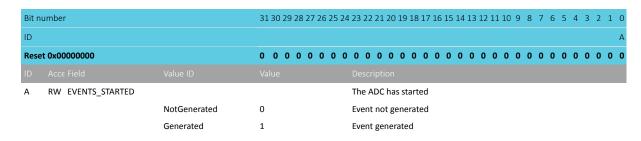
Address offset: 0x08C

Subscribe configuration for task CALIBRATEOFFSET



6.12.11.9 EVENTS_STARTED

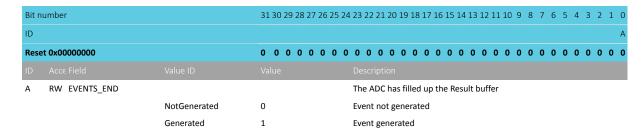
Address offset: 0x100
The ADC has started



6.12.11.10 EVENTS_END

Address offset: 0x104

The ADC has filled up the Result buffer



6.12.11.11 EVENTS_DONE

Address offset: 0x108

A conversion task has been completed. Depending on the mode, multiple conversions might be needed for a result to be transferred to RAM.



Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW EVENTS_DONE			A conversion task has been completed. Depending on the
				mode, multiple conversions might be needed for a result to
				be transferred to RAM.
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.12.11.12 EVENTS_RESULTDONE

Address offset: 0x10C

A result is ready to get transferred to RAM.

Bit number		31	130	29	28	27	26 2	25 :	24 2	23 :	22	21 2	20 :	19 1	18 1	17 1	6 1	5 1	4 13	3 12	11	10	9 8	3 7	7 6	5	4	3	2	1 0
ID																														Α
Reset 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0) (0	0	0	0	0 (0 () (0	0	0	0	0 0
ID Acce Field																														
A RW EVENTS_RESULTDONE									,	٩r	esu	lt is	re	ady	to	get	tra	nsf	erre	d to	o R	٩M.								
	NotGenerated	0							-	eve	ent	not	ge	ner	ate	d														
	Generated	1							١	ve	ent	gen	era	itec	ı															

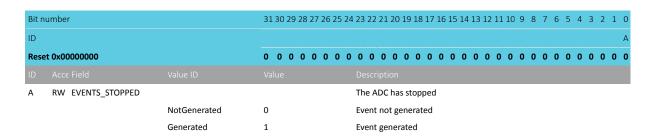
6.12.11.13 EVENTS_CALIBRATEDONE

Address offset: 0x110
Calibration is complete

Bit n	umber		31	30	29 2	28 2	7 26	25	24	23 :	22 2	21 2	20 1	19 18	3 17	16	15	14 1	3 12	2 11	10	9 8	7	6	5	4	3	2 1	. 0
ID																													Α
Rese	et 0x00000000		0	0	0	0 (0 0	0	0	0	0	0	0	0 0	0	0	0	0	0 0	0	0	0 0	0	0	0	0	0	0 (0
ID																													
Α	RW EVENTS_CALIBRATEDON	NE .								Cali	ibra	atio	n is	con	nple	te													
		NotGenerated	0							Eve	ent i	not	ger	nera	ted														
		Generated	1							Eve	ent g	gen	era	ted															

6.12.11.14 EVENTS STOPPED

Address offset: 0x114
The ADC has stopped



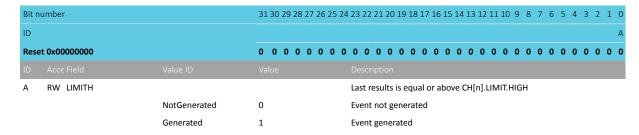
6.12.11.15 EVENTS_CH[n].LIMITH (n=0..7)

Address offset: $0x118 + (n \times 0x8)$





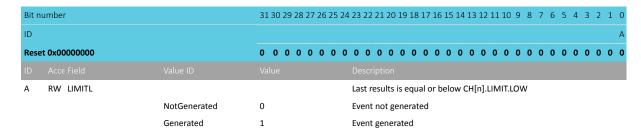
Last results is equal or above CH[n].LIMIT.HIGH



6.12.11.16 EVENTS CH[n].LIMITL (n=0..7)

Address offset: $0x11C + (n \times 0x8)$

Last results is equal or below CH[n].LIMIT.LOW



6.12.11.17 PUBLISH STARTED

Address offset: 0x180

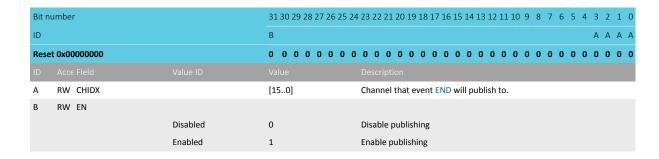
Publish configuration for event STARTED

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID				
Α	RW CHIDX		[150]	Channel that event STARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.12.11.18 PUBLISH END

Address offset: 0x184

Publish configuration for event END

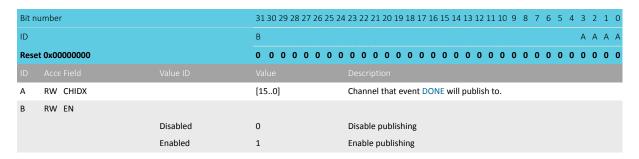




6.12.11.19 PUBLISH_DONE

Address offset: 0x188

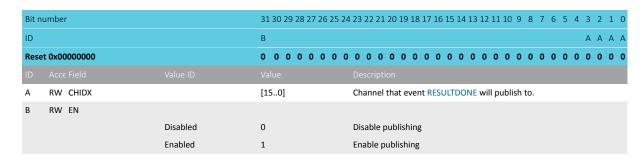
Publish configuration for event **DONE**



6.12.11.20 PUBLISH_RESULTDONE

Address offset: 0x18C

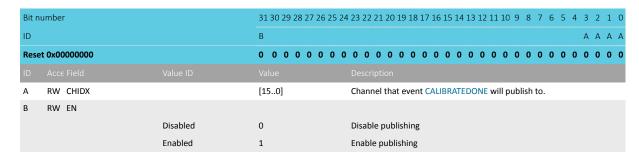
Publish configuration for event RESULTDONE



6.12.11.21 PUBLISH CALIBRATEDONE

Address offset: 0x190

Publish configuration for event CALIBRATEDONE



6.12.11.22 PUBLISH_STOPPED

Address offset: 0x194

Publish configuration for event STOPPED



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event STOPPED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.12.11.23 PUBLISH_CH[n].LIMITH (n=0..7)

Address offset: $0x198 + (n \times 0x8)$

Publish configuration for event CH[n].LIMITH

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event CH[n].LIMITH will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.12.11.24 PUBLISH_CH[n].LIMITL (n=0..7)

Address offset: $0x19C + (n \times 0x8)$

Publish configuration for event CH[n].LIMITL

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event CH[n].LIMITL will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.12.11.25 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number		31 30 29 28 27 2	6 25 24	4 23 22	21 2	0 19	18 1	17 1	6 15	14	13 1	2 11	10	9 8	3 7	6	5	4	3 2	1 0
ID						۷١	J T	S	R C	Q P	0	N N	M L	K	J	ΙН	G	F	Ε	D C	ВА
Res	et 0x00000000		0 0 0 0 0	0 0	0 0	0 0	0	0	0 (0	0	0	0 0	0	0 (0 0	0	0	0	0 0	0 0
ID																					
Α	RW STARTED				Enabl	e or o	disak	ole ir	nter	rupt	for	eve	nt S1	ART	ED						
		Disabled	0		Disab	le															
		Enabled	1		Enabl	е															
В	RW END				Enabl	e or o	disab	ole ir	nter	rupt	for	eve	nt El	ND							
		Disabled	0		Disab	le															
		Enabled	1		Enabl	е															



Bit r	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
С	RW DONE			Enable or disable interrupt for event DONE
		Disabled	0	Disable
		Enabled	1	Enable
D	RW RESULTDONE			Enable or disable interrupt for event RESULTDONE
		Disabled	0	Disable
		Enabled	1	Enable
E	RW CALIBRATEDONE			Enable or disable interrupt for event CALIBRATEDONE
		Disabled	0	Disable
		Enabled	1	Enable
F	RW STOPPED			Enable or disable interrupt for event STOPPED
		Disabled	0	Disable
		Enabled	1	Enable
G	RW CHOLIMITH			Enable or disable interrupt for event CHOLIMITH
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW CHOLIMITL		_	Enable or disable interrupt for event CHOLIMITL
		Disabled	0	Disable
	DIA CHALIMITH	Enabled	1	Enable
I	RW CH1LIMITH	Disabled	0	Enable or disable interrupt for event CH1LIMITH
		Enabled	1	Disable Enable
J	RW CH1LIMITL	Ellableu	1	Enable or disable interrupt for event CH1LIMITL
,	NW CHILINITE	Disabled	0	Disable
		Enabled	1	Enable
K	RW CH2LIMITH		-	Enable or disable interrupt for event CH2LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
L	RW CH2LIMITL			Enable or disable interrupt for event CH2LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
М	RW CH3LIMITH			Enable or disable interrupt for event CH3LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
N	RW CH3LIMITL			Enable or disable interrupt for event CH3LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
0	RW CH4LIMITH			Enable or disable interrupt for event CH4LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
Р	RW CH4LIMITL			Enable or disable interrupt for event CH4LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
Q	RW CH5LIMITH			Enable or disable interrupt for event CH5LIMITH
		Disabled	0	Disable
		Enabled	1	Enable
R	RW CH5LIMITL			Enable or disable interrupt for event CH5LIMITL
		Disabled	0	Disable
		Enabled	1	Enable
S	RW CH6LIMITH	D		Enable or disable interrupt for event CH6LIMITH
		Disabled	0	Disable



Bit n	umber		31 30 29 28 27	26 25 2	4 23	3 22 2	21 20	19	18	17 1	.6 1	l5 1	4 13	3 12	11	10 9	8 (7	6	5	4	3 2	2 1	0
ID						\	V U	Т	S	R (Q	P C	N	М	L	Κ.	l I	Н	G	F	Е	D (СВ	Α
Rese	t 0x00000000		0 0 0 0 0	0 0 0	0	0 (0 0	0	0	0 (0	0 (0	0	0	0 (0	0	0	0	0	0 (0 0	0
ID																								
		Enabled	1		Er	nable																		
Т	RW CH6LIMITL				Er	nable	or d	lisab	ole ii	nter	ru	ot fo	r ev	/ent	CH	6LIN	1ITL							
		Disabled	0		Di	isable	9																	
		Enabled	1		Er	nable																		
U	RW CH7LIMITH				Er	nable	or d	lisab	ole ii	nter	ru	ot fo	r ev	/ent	t CH	7LIN	1ITH	4						
		Disabled	0		Di	isable	9																	
		Enabled	1		Er	nable																		
٧	RW CH7LIMITL				Er	nable	or d	lisab	ole ii	nter	ru	ot fo	r ev	/ent	t CH	7LIN	1ITL							
		Disabled	0		Di	isable	9																	
		Enabled	1		Er	nable																		

6.12.11.26 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			Description
Α	RW STARTED		Write '1' to enable interrupt for event STARTED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
В	RW END		Write '1' to enable interrupt for event END
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
С	RW DONE		Write '1' to enable interrupt for event DONE
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
D	RW RESULTDONE		Write '1' to enable interrupt for event RESULTDONE
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
Ε	RW CALIBRATEDONE		Write '1' to enable interrupt for event CALIBRATEDONE
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
F	RW STOPPED		Write '1' to enable interrupt for event STOPPED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
G	RW CHOLIMITH		Write '1' to enable interrupt for event CHOLIMITH
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
Н	RW CHOLIMITL		Write '1' to enable interrupt for event CHOLIMITL



Bit r	number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
ı	RW CH1LIMITH			Write '1' to enable interrupt for event CH1LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW CH1LIMITL			Write '1' to enable interrupt for event CH1LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
K	RW CH2LIMITH			Write '1' to enable interrupt for event CH2LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
L	RW CH2LIMITL			Write '1' to enable interrupt for event CH2LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
М	RW CH3LIMITH			Write '1' to enable interrupt for event CH3LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
N	RW CH3LIMITL			Write '1' to enable interrupt for event CH3LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
0	RW CH4LIMITH			Write '1' to enable interrupt for event CH4LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Р	RW CH4LIMITL			Write '1' to enable interrupt for event CH4LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Q	RW CH5LIMITH			Write '1' to enable interrupt for event CH5LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
R	RW CH5LIMITL			Write '1' to enable interrupt for event CH5LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
S	RW CH6LIMITH			Write '1' to enable interrupt for event CH6LIMITH
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Т	RW CH6LIMITL			Write '1' to enable interrupt for event CH6LIMITL
		Set	1	Enable
		Disabled	0	Read: Disabled



Bit number		31 30 29 28 27	26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		0100232027	20202	V U T S R Q P O N M L K J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	Enabled	1		Read: Enabled
U RW CH7LIMITH				Write '1' to enable interrupt for event CH7LIMITH
	Set	1		Enable
	Disabled	0		Read: Disabled
	Enabled	1		Read: Enabled
V RW CH7LIMITL				Write '1' to enable interrupt for event CH7LIMITL
	Set	1		Enable
	Disabled	0		Read: Disabled
	Enabled	1		Read: Enabled

6.12.11.27 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW STARTED			Write '1' to disable interrupt for event STARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW DONE			Write '1' to disable interrupt for event DONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW RESULTDONE			Write '1' to disable interrupt for event RESULTDONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW CALIBRATEDONE			Write '1' to disable interrupt for event CALIBRATEDONE
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW CHOLIMITH			Write '1' to disable interrupt for event CHOLIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW CHOLIMITL			Write '1' to disable interrupt for event CHOLIMITL
		Clear	1	Disable



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	Acce Field		Value	Description
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
ı	RW CH1LIMITH			Write '1' to disable interrupt for event CH1LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW CH1LIMITL			Write '1' to disable interrupt for event CH1LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
K	RW CH2LIMITH			Write '1' to disable interrupt for event CH2LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
L	RW CH2LIMITL			Write '1' to disable interrupt for event CH2LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
М	RW CH3LIMITH			Write '1' to disable interrupt for event CH3LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
N	RW CH3LIMITL			Write '1' to disable interrupt for event CH3LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
0	RW CH4LIMITH			Write '1' to disable interrupt for event CH4LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Р	RW CH4LIMITL			Write '1' to disable interrupt for event CH4LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Q	RW CH5LIMITH			Write '1' to disable interrupt for event CH5LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
R	RW CH5LIMITL			Write '1' to disable interrupt for event CH5LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
S	RW CH6LIMITH			Write '1' to disable interrupt for event CH6LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Т	RW CH6LIMITL			Write '1' to disable interrupt for event CH6LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
U	RW CH7LIMITH			Write '1' to disable interrupt for event CH7LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
V	RW CH7LIMITL			Write '1' to disable interrupt for event CH7LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.12.11.28 STATUS

Address offset: 0x400

Status

Bit number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R STATUS			Status
	Ready	0	ADC is ready. No on-going conversion.
	Busy	1	ADC is busy. Conversion in progress.

6.12.11.29 ENABLE

Address offset: 0x500 Enable or disable ADC

Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable ADC
	Disabled	0	Disable ADC
	Enabled	1	Enable ADC
			When enabled, the ADC will acquire access to the analog
			input pins specified in the CH[n].PSELP and CH[n].PSELN
			registers.

6.12.11.30 CH[n].PSELP (n=0..7)

Address offset: $0x510 + (n \times 0x10)$

Input positive pin selection for CH[n]



Bit n	umber		31 30 29 28 27 2	6 25 2	4 23	3 22 2	1 20	19	18 1	17 1	6 1	5 14	4 13	12	11 1	.0 9	8	7	6	5 .	4 3	2	1	0
ID																					4 Α	Α	Α	Α
Rese	et 0x00000000		0 0 0 0 0	0 0 (0 0	0 0	0 0	0	0	0 () (0 0	0	0	0	0 0	0	0	0	0	0 0	0	0	0
Α	RW PSELP				Ar	nalog	pos	itive	inp	ut c	ha	nne	I											
		NC	0		No	ot cor	nnec	ted																
		AnalogInput0	1		ΑI	NO																		
		AnalogInput1	2		ΑI	N1																		
		AnalogInput2	3		ΑI	N2																		
		AnalogInput3	4		ΑI	IN3																		
		AnalogInput4	5		ΑI	N4																		
		AnalogInput5	6		ΑI	IN5																		
		AnalogInput6	7		ΑI	N6																		
		AnalogInput7	8		ΑI	N7																		
		VDD	9		VI	DD																		

6.12.11.31 CH[n].PSELN (n=0..7)

Address offset: $0x514 + (n \times 0x10)$ Input negative pin selection for CH[n]

Bit r	number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АААА
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW PSELN			Analog negative input, enables differential channel
		NC	0	Not connected
		AnalogInput0	1	AINO
		AnalogInput1	2	AIN1
		AnalogInput2	3	AIN2
		AnalogInput3	4	AIN3
		AnalogInput4	5	AIN4
		AnalogInput5	6	AIN5
		AnalogInput6	7	AIN6
		AnalogInput7	8	AIN7
		VDD	9	VDD

6.12.11.32 CH[n].CONFIG (n=0..7)

Address offset: $0x518 + (n \times 0x10)$ Input configuration for CH[n]

Bit number		31 30 29 28 27 26 25	$24\ 23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID			G F E E E D C C C B B A A
Reset 0x00020000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW RESP			Positive channel resistor control
	Bypass	0	Bypass resistor ladder
	Pulldown	1	Pull-down to GND
	Pullup	2	Pull-up to VDD
	VDD1_2	3	Set input at VDD/2
B RW RESN			Negative channel resistor control
	Bypass	0	Bypass resistor ladder



Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			G FEEE D C C C B B A A
Reset 0x00020000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field	Value ID	Value	Description
	Pulldown	1	Pull-down to GND
	Pullup	2	Pull-up to VDD
	VDD1_2	3	Set input at VDD/2
C RW GAIN			Gain control
	Gain1_6	0	1/6
	Gain1_5	1	1/5
	Gain1_4	2	1/4
	Gain1_3	3	1/3
	Gain1_2	4	1/2
	Gain1	5	1
	Gain2	6	2
	Gain4	7	4
D RW REFSEL			Reference control
	Internal	0	Internal reference (0.6 V)
	VDD1_4	1	VDD/4 as reference
E RW TACQ			Acquisition time, the time the ADC uses to sample the input
			voltage
	3us	0	3 us
	5us	1	5 us
	10us	2	10 us
	15us	3	15 us
	20us	4	20 us
	40us	5	40 us
F RW MODE			Enable differential mode
	SE	0	Single ended, PSELN will be ignored, negative input to ADC
			shorted to GND
	Diff	1	Differential
G RW BURST			Enable burst mode
	Disabled	0	Burst mode is disabled (normal operation)
	Enabled	1	Burst mode is enabled. SAADC takes 2^OVERSAMPLE
			number of samples as fast as it can, and sends the average
			to Data RAM.

6.12.11.33 CH[n].LIMIT (n=0..7)

Address offset: $0x51C + (n \times 0x10)$

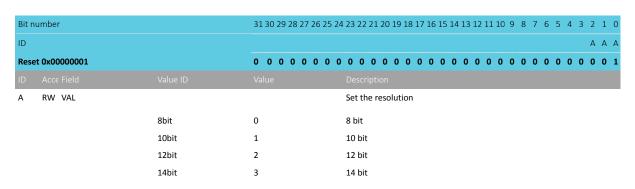
High/low limits for event monitoring a channel

Bit n	number	313	30 2	29 2	28 2	7 26	5 25	5 24	1 23	22	21	20	19 1	18 1	.7 1	6 1	5 14	13	12	11 :	10 9	9 8	3 7	6	5	4	3 2	1	0
ID		В	В	В	ВЕ	3 B	В	В	В	В	В	В	В	В	ВЕ	3 Δ	A	Α	Α	Α	A	4 4	A	Α	Α	Α	Α Α	Α	Α
Rese	et 0x7FFF8000	0	1	1	1 1	l 1	1	. 1	1	1	1	1	1	1 :	1 1	L 1	. 0	0	0	0	0 (0 (0	0	0	0	0 0	0	0
ID																													
Α	RW LOW	[-32	276	8 to	+3	276	7]		Lo	w l	eve	l lin	nit																_
В	RW HIGH	[-32	276	8 to	+3	276	7]		Hi	gh l	leve	el lir	nit																

6.12.11.34 RESOLUTION

Address offset: 0x5F0
Resolution configuration

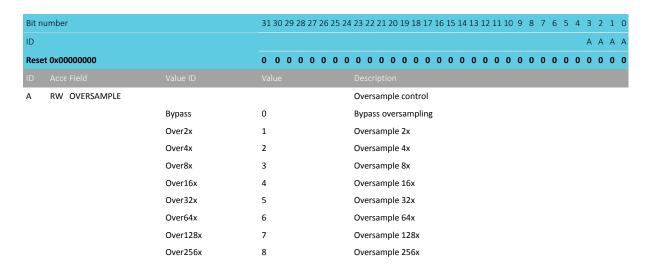




6.12.11.35 OVERSAMPLE

Address offset: 0x5F4

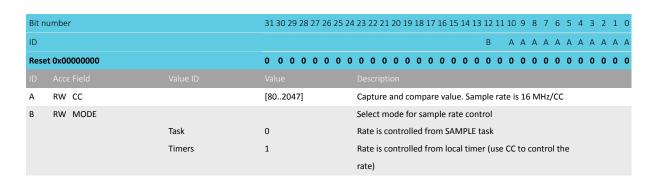
Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION should be used.



6.12.11.36 SAMPLERATE

Address offset: 0x5F8

Controls normal or continuous sample rate



6.12.11.37 RESULT.PTR

Address offset: 0x62C

Data pointer



ID Acce Field	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.12.11.38 RESULT.MAXCNT

Address offset: 0x630

Maximum number of buffer words to transfer

Α	RW MAXCNT		Maximum number of buffer words to transfer
ID			
Res	et 0x00000000	0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID			A A A A A A A A A A A A A A A A A A A
Bit	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.12.11.39 RESULT.AMOUNT

Address offset: 0x634

Number of buffer words transferred since last START

Α	R AMOUNT		Number of buffer words transferred since last START. This								
ID											
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0	0000000	0000	0 0 0 0					
ID				A A A A A A	A A A A	A A A A					
Bit	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15	5 14 13 12 11 10 9 8	3 7 6 5 4	3 2 1 0					

register can be read after an END or STOPPED event.

6.12.12 Electrical specification

6.12.12.1 SAADC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
DNL ₁₀	Differential non-linearity, 10-bit resolution	-0.95	<1		LSB10b
INL ₁₀	Integral non-linearity, 10-bit resolution		1		LSB1(
V_{OS}	Differential offset error (calibrated), 10-bit resolution ^a	-15		15	LSB10b
DNL ₁₂	Differential non-linearity, 12-bit resolution				LSB12
INL ₁₂	Integral non-linearity, 12-bit resolution				LSB12b
C _{EG}	Gain error temperature coefficient	-0.05		0.05	%/°C
f _{SAMPLE}	Maximum sampling rate			200	kHz
t _{ACQ,10k}	Acquisition time (configurable), source Resistance <=		3		μs
	10kOhm				
t _{ACQ,40k}	Acquisition time (configurable), source Resistance <=		5		μs
	40kOhm				

^a Digital output code at zero volt differential input.

Symbol	Description	Min.	Тур.	Max.	Units
t _{ACQ,100k}	Acquisition time (configurable), source Resistance <=		10		μs
	100kOhm				
t _{ACQ,200k}	Acquisition time (configurable), source Resistance <=		15		μs
	200kOhm				
t _{ACQ,400k}	Acquisition time (configurable), source Resistance <=		20		μs
	400kOhm				
t _{ACQ,800k}	Acquisition time (configurable), source Resistance <=		40		μs
	800kOhm				
t _{CONV}	Conversion time		<2		μs
E _{G1/6}	Error ^b for Gain = 1/6	-3		3	%
E _{G1/4}	Error ^b for Gain = 1/4	-3		3	%
E _{G1/2}	Error ^b for Gain = 1/2	-3		4	%
E _{G1}	Error ^b for Gain = 1	-3		4	%
C _{SAMPLE}	Sample and hold capacitance at maximum gain ⁹		2.5		pF
R _{INPUT}	Input resistance		>1		ΜΩ
E _{NOB}	Effective number of bits, differential mode, 12-bit		9		Bit
	resolution, $1/1$ gain, $3~\mu s$ acquisition time, crystal HFCLK,				
	200 ksps				
S _{NDR}	Peak signal to noise and distortion ratio, differential mode,		56		dB
	12-bit resolution, $1/1$ gain, 3 μs acquisition time, crystal				
	HFCLK, 200 ksps				
S _{FDR}	Spurious free dynamic range, differential mode, 12-bit		70		dBc
	resolution, 1/1 gain, 3 μs acquisition time, crystal HFCLK,				
	200 ksps				
R _{LADDER}	Ladder resistance		160		kΩ

6.12.13 Performance factors

Clock jitter, affecting sample timing accuracy, and circuit noise can affect ADC performance.

Jitter can be between START tasks or from START task to acquisition. START timer accuracy and startup times of regulators and references will contribute to variability. Sources of circuit noise may include CPU activity and the DC/DC regulator. Best ADC performance is achieved using START timing based on the TIMER module, HFXO clock source, and Constant Latency mode.

6.13 SPIM — Serial peripheral interface master with EasyDMA

The SPI master can communicate with multiple slaves using individual chip select signals for each of the slave devices attached to a bus.

Listed here are the main features for the SPIM

- SPI mode 0-3
- EasyDMA direct transfer to/from RAM for both SPI Slave and SPI Master
- Individual selection of IO pin for each SPI signal



b Does not include temperature drift

⁹ Maximum gain corresponds to highest capacitance.

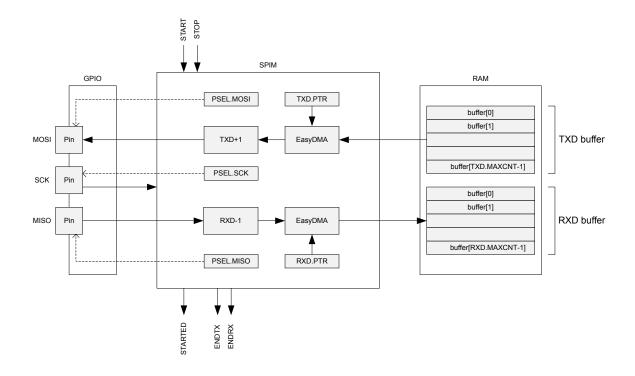


Figure 69: SPIM — SPI master with EasyDMA

The SPIM does not implement support for chip select directly. Therefore, the CPU must use available GPIOs to select the correct slave and control this independently of the SPI master. The SPIM supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.

Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Leading)
SPI_MODE1	0 (Active High)	1 (Trailing)
SPI_MODE2	1 (Active Low)	0 (Leading)
SPI_MODE3	1 (Active Low)	1 (Trailing)

Table 67: SPI modes

6.13.1 SPI master transaction sequence

An SPI master transaction consists of a sequence started by the START task followed by a number of events, and finally the STOP task.

An SPI master transaction is started by triggering the START task. The ENDTX event will be generated when the transmitter has transmitted all bytes in the TXD buffer as specified in the TXD.MAXCNT register. The ENDRX event will be generated when the receiver has filled the RXD buffer, i.e. received the last possible byte as specified in the RXD.MAXCNT register.

Following a START task, the SPI master will generate an END event when both ENDRX and ENDTX have been generated.

The SPI master is stopped by triggering the STOP task. A STOPPED event is generated when the SPI master has stopped.

If the ENDRX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDRX event explicitly even though the RX buffer is not full.



If the ENDTX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

The SPI master is a synchronous interface, and for every byte that is sent, a different byte will be received at the same time; this is illustrated in SPI master transaction on page 224.

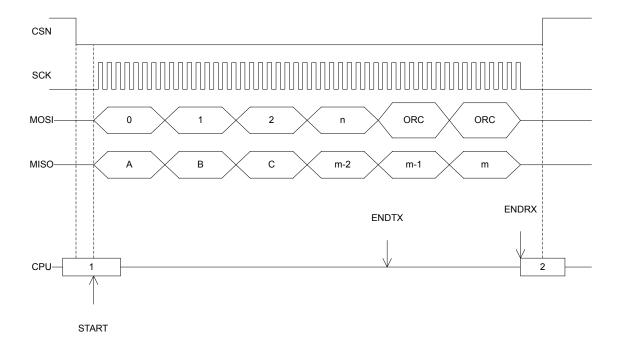


Figure 70: SPI master transaction

6.13.2 Master mode pin configuration

The SCK, MOSI, and MISO signals associated with the SPI master are mapped to physical pins according to the configuration specified in the PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively.

The PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCK, PSEL.MOSI and PSEL.MISO must only be configured when the SPI master is disabled.

To secure correct behavior in the SPI, the pins used by the SPI must be configured in the GPIO peripheral as described in GPIO configuration on page 224 prior to enabling the SPI. This configuration must be retained in the GPIO for the selected IOs as long as the SPI is enabled.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI master signal	SPI master pin	Direction	Output value
SCK	As specified in PSEL.SCK	Output	Same as CONFIG.CPOL
MOSI	As specified in PSEL.MOSI	Output	0
MISO	As specified in PSEL.MISO	Input	Not applicable

Table 68: GPIO configuration



6.13.3 EasyDMA

The SPI master implements EasyDMA for reading and writing of data packets from and to the DATA RAM without CPU involvement.

RXD.PTR and TXD.PTR point to the RXD buffer (receive buffer) and TXD buffer (transmit buffer) respectively, see SPIM — SPI master with EasyDMA on page 223. RXD.MAXCNT and TXD.MAXCNT specify the maximum number of bytes allocated to the buffers. The SPI master will automatically stop transmitting after TXD.MAXCNT bytes have been transmitted and RXD.MAXCNT bytes have been received. If TXD.MAXCNT is larger than RXD.MAXCNT, the superfluous received bytes will be ignored. If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register.

If RXD.PTR and TXD.PTR are not pointing to Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next transmission immediately after having received the STARTED event.

The ENDRX/ENDTX events indicate that EasyDMA has finished accessing the RX/TX buffer in RAM respectively. The END events are generated when both RX and TX are finished accessing the buffers in RAM.

EasyDMA supports the following list types:

· Array list

6.13.3.1 EasyDMA array list

The EasyDMA array list can be represented by the data structure ArrayList type.

For illustration, see the code example below. This data structure includes only a buffer with size equal to Channel.MAXCNT. EasyDMA will use the Channel.MAXCNT register to determine when the buffer is full. Replace 'Channel' by the specific data channel you want to use, for instance 'NRF_SPIM->RXD', 'NRF_SPIM->TXD', 'NRF_TWIM->RXD', etc.

The Channel.MAXCNT register cannot be specified larger than the actual size of the buffer. If Channel.MAXCNT is specified larger than the size of the buffer, the EasyDMA channel may overflow the buffer.



This array list does not provide a mechanism to explicitly specify where the next item in the list is located. Instead, it assumes that the list is organized as a linear array where items are located one after the other in RAM.



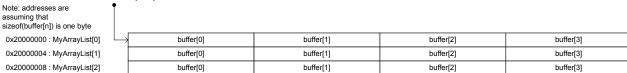


Figure 71: EasyDMA array list

6.13.4 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.13.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	SPIM	SPIM0:S	US	SA	SPI master 0	
0x40008000	SPIIVI	SPIM0 : NS	03	SA	3FT IIIdStel U	
0x50009000	SPIM	SPIM1:S	US	SA	SPI master 1	
0x40009000	SPIIVI	SPIM1: NS	03	эА	SPI Master 1	
0x5000A000	SPIM	SPIM2:S	US	SA	SPI master 2	
0x4000A000	SPIIVI	SPIM2 : NS	SA SPITIASTEL 2	SPI Master 2		
0x5000B000	SPIM	SPIM3:S	US	SA	SPI master 3	
0x4000B000	SPIIVI	SPIM3 : NS	03	ЭА	ori illaster o	

Table 69: Instances



Register	Offset	Security	Description
TASKS_START	0x010		Start SPI transaction
TASKS_STOP	0x014		Stop SPI transaction
TASKS_SUSPEND	0x01C		Suspend SPI transaction
TASKS_RESUME	0x020		Resume SPI transaction
SUBSCRIBE_START	0x090		Subscribe configuration for task START
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_STOPPED	0x104		SPI transaction has stopped
EVENTS_ENDRX	0x110		End of RXD buffer reached
EVENTS_END	0x118		End of RXD buffer and TXD buffer reached
EVENTS_ENDTX	0x120		End of TXD buffer reached
EVENTS_STARTED	0x14C		Transaction started
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_END	0x198		Publish configuration for event END
PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
PUBLISH_STARTED	0x1CC		Publish configuration for event STARTED
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		Enable SPIM
PSEL.SCK	0x508		Pin select for SCK
PSEL.MOSI	0x50C		Pin select for MOSI signal
PSEL.MISO	0x510		Pin select for MISO signal
FREQUENCY	0x524		SPI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
TXD.LIST	0x550		EasyDMA list type
CONFIG	0x554		Configuration register
ORC	0x5C0		Over-read character. Character clocked out in case and over-read of the TXD
			buffer.

Table 70: Register overview

6.13.5.1 TASKS_START

Address offset: 0x010 Start SPI transaction

Bit no	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_START			Start SPI transaction
		Trigger	1	Trigger task



6.13.5.2 TASKS_STOP

Address offset: 0x014 Stop SPI transaction

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOP			Stop SPI transaction
		Trigger	1	Trigger task

6.13.5.3 TASKS_SUSPEND

Address offset: 0x01C Suspend SPI transaction

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_SUSPEND			Suspend SPI transaction
		Trigger	1	Trigger task

6.13.5.4 TASKS_RESUME

Address offset: 0x020 Resume SPI transaction

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_RESUME			Resume SPI transaction
		Trigger	1	Trigger task

6.13.5.5 SUBSCRIBE_START

Address offset: 0x090

Subscribe configuration for task START

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

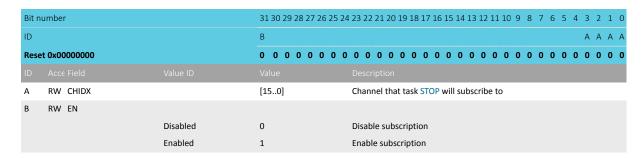




6.13.5.6 SUBSCRIBE_STOP

Address offset: 0x094

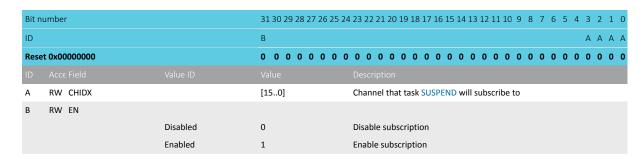
Subscribe configuration for task STOP



6.13.5.7 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND



6.13.5.8 SUBSCRIBE RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x0000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task RESUME will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.13.5.9 EVENTS_STOPPED

Address offset: 0x104

SPI transaction has stopped



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW EVENTS_STOPPED			SPI transaction has stopped
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.13.5.10 EVENTS_ENDRX

Address offset: 0x110 End of RXD buffer reached

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_ENDRX			End of RXD buffer reached
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.13.5.11 EVENTS_END

Address offset: 0x118

End of RXD buffer and TXD buffer reached

Bit nu	mber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Reset	0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_END			End of RXD buffer and TXD buffer reached
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.13.5.12 EVENTS_ENDTX

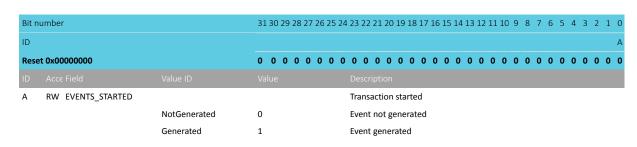
Address offset: 0x120 End of TXD buffer reached

Bit n	umber		31	30	29	28	27	26	25	24	23	22	2 2 1	L 20	19	18	3 17	16	5 15	14	13	12	11	10	9 8	8 7	7 (6 5	5 4	1 3	2	1	0
ID																																	Α
Rese	t 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 () (0 () (0	0	0	0
ID																																	
Α	RW EVENTS_ENDTX										En	d c	of T	ΧD	bu	ffe	re	ach	ied														
		NotGenerated	0								Ev	ent	t no	ot g	en	era	ted																
		Generated	1								Ev	ent	t ge	ene	rat	ed																	

6.13.5.13 EVENTS_STARTED

Address offset: 0x14C
Transaction started





6.13.5.14 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event STOPPED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.13.5.15 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event ENDRX will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.13.5.16 PUBLISH_END

Address offset: 0x198

Publish configuration for event END

Bit r	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event END will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing



6.13.5.17 PUBLISH_ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX

Bit n	umber		31 30 2	29 2	8 27	' 26	25	24	23 2	22 2	21 20	0 19	18	17	16	15 1	4 13	3 12	11	10 9	8	7	6	5	4	3	2 :	1 0
ID			В																							A	4 /	A A
Rese	t 0x00000000		0 0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0	0 (0	0	0	0 0	0	0	0	0	0	0	0 () O
ID									Des																			
Α	RW CHIDX		[150]						Cha	nn	el th	at e	ever	nt El	VDT	X w	ill p	ubli	sh to).								
В	RW EN																											
		Disabled	0						Disa	able	e pul	blisl	hing	3														
		Enabled	1						Ena	ble	pub	lish	ing															

6.13.5.18 PUBLISH_STARTED

Address offset: 0x1CC

Publish configuration for event STARTED

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event STARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.13.5.19 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW END_START			Shortcut between event END and task START
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.13.5.20 INTENSET

Address offset: 0x304

Enable interrupt

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10	8 (7 6	5 4	3 2 1 0
ID	E	D	С	В	А
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 (0 0	0 0	0 0 0 0
ID Acce Field Value ID	Value Description				

A RW STOPPED Write '1' to enable interrupt for event STOPPED



80	24 20 20 27 27 26 25	24.22.22.24.20.40.40.47.46.45.44.24.24.40.40.00.00.7.6.5.4.2.2.2.4.0
Bit number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		E D C B A
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value I		
Set	1	Enable
Disable	ed 0	Read: Disabled
Enable	d 1	Read: Enabled
B RW ENDRX		Write '1' to enable interrupt for event ENDRX
Set	1	Enable
Disable	ed 0	Read: Disabled
Enable	d 1	Read: Enabled
C RW END		Write '1' to enable interrupt for event END
Set	1	Enable
Disable	ed 0	Read: Disabled
Enable	d 1	Read: Enabled
D RW ENDTX		Write '1' to enable interrupt for event ENDTX
Set	1	Enable
Disable	ed 0	Read: Disabled
Enable	d 1	Read: Enabled
E RW STARTED		Write '1' to enable interrupt for event STARTED
Set	1	Enable
Disable	ed 0	Read: Disabled
Enable	d 1	Read: Enabled

6.13.5.21 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E D C B A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW ENDRX			Write '1' to disable interrupt for event ENDRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW END			Write '1' to disable interrupt for event END
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ENDTX			Write '1' to disable interrupt for event ENDTX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Ε	RW STARTED			Write '1' to disable interrupt for event STARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



6.13.5.22 ENABLE

Address offset: 0x500

Enable SPIM

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			ААА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable SPIM
	Disabled	0	Disable SPIM
	Enabled	7	Enable SPIM

6.13.5.23 PSEL.SCK

Address offset: 0x508
Pin select for SCK

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.13.5.24 PSEL.MOSI

Address offset: 0x50C

Pin select for MOSI signal

Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.13.5.25 PSEL.MISO

Address offset: 0x510

Pin select for MISO signal



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.13.5.26 FREQUENCY

Address offset: 0x524

SPI frequency. Accuracy depends on the HFCLK source selected.

Bit n	umber		31	30 2	29 2	28 2	27 2	26 2	5 2	24 2	23 2	22 2	21 2	20 1	9 1	3 17	16	5 15	5 14	13	12	11	10	9	8	7	5 5	5 4	3	2	1	0
ID			Α	Α	A ,	A A	Α ,	A A	Δ.	A	Α	A ,	Α.	A A	λ Α	A	Α	Α	Α	Α	Α	Α	Α	Α	Α /	Δ,	4 <i>A</i>	A A	Α	Α	Α	Α
Rese	t 0x04000000		0	0	0	0 (0 :	1 (0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 (0	0 (0	0	0	0	0
ID																																
Α	RW FREQUENCY									9	SPI	ma	ste	r da	ta r	ate																
		K125	0x	0200	000	00				-	125	kb	ps																			
		K250	0x	0400	000	00				2	250	kb	ps																			
		K500	0x	080	000	00				į	500	kb	ps																			
		M1	0x	1000	000	00				1	ΙV	lbps	S																			
		M2	0x	2000	000	00				2	2 N	lbps	S																			
		M4	0x	4000	000	00				4	1 IV	lbps	S																			
		M8	0x	8000	000	00				8	3 N	lbps	s																			

6.13.5.27 RXD.PTR

Address offset: 0x534

Data pointer

Bit n	ımber	31	130	29	28	27	26	25	24	23	22	21 2	20 1	9 1	8 17	16	15	14 :	13 1	2 1	1 10	9	8	7	6	5	4	3	2	1 0
ID		Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A A	λ Δ	A	Α	Α	Α	Α.	A A	4 A	Α	Α	Α	Α	Α	Α	Α .	Α.	A A
Rese	t 0x00000000	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0 0
ID																														
Α	RW PTR									Da	ta p	oin	ter																	

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.13.5.28 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer

Α	RW MAXCNT	[10x1FFF]	Maximum number of bytes in receive buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

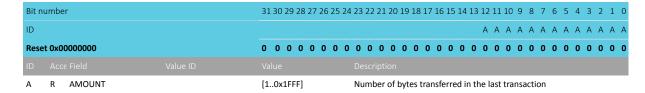




6.13.5.29 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction



6.13.5.30 RXD.LIST

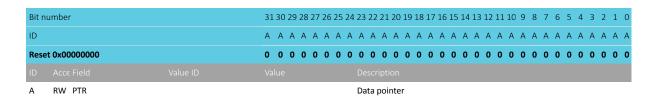
Address offset: 0x540 EasyDMA list type

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW LIST			List type
		Disabled	0	Disable EasyDMA list
		ArrayList	1	Use array list

6.13.5.31 TXD.PTR

Address offset: 0x544

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.13.5.32 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

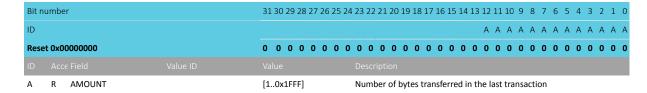
Α	RW MAXCNT	[10x1FFF]	Maximum number of bytes in transmit buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



6.13.5.33 TXD.AMOUNT

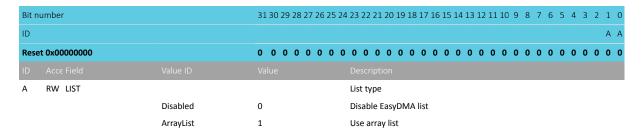
Address offset: 0x54C

Number of bytes transferred in the last transaction



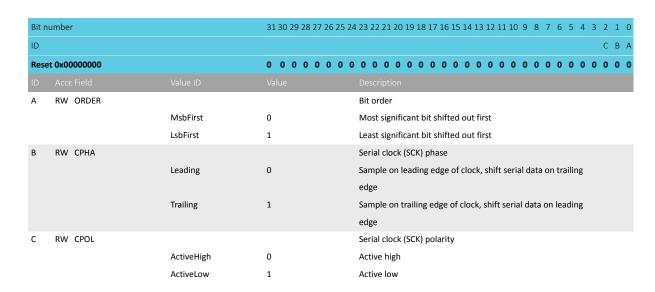
6.13.5.34 TXD.LIST

Address offset: 0x550 EasyDMA list type



6.13.5.35 CONFIG

Address offset: 0x554 Configuration register



6.13.5.36 ORC

Address offset: 0x5C0

Over-read character. Character clocked out in case and over-read of the TXD buffer.



Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	Value Description
A RW ORC	Over-read character. Character clocked out in case and over-

read of the TXD buffer.

6.13.6 Electrical specification

6.13.6.1 SPIM master interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIM}	Bit rates for SPIM ¹⁰				Mbps
t _{SPIM} ,START	Time from START task to transmission started		1		μs

6.13.6.2 Serial Peripheral Interface Master (SPIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIM} ,CSCK	SCK period		125		ns
t _{SPIM,RSCK,LD}	SCK rise time, standard drive ^a			t _{RF,25pF}	
$t_{SPIM,RSCK,HD}$	SCK rise time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,FSCK,LD}	SCK fall time, standard drive ^a			t _{RF,25pF}	
$t_{\text{SPIM,FSCK,HD}}$	SCK fall time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,WHSCK}	SCK high time ^a	(0.5*t _{CSC}	СК		
		- t _{RSCK}			
t _{SPIM,WLSCK}	SCK low time ^a	(0.5*t _{CSC}	ck)		
		$-t_{FSCK}$			
t _{SPIM,SUMI}	MISO to CLK edge setup time	19			ns
t _{SPIM,HMI}	CLK edge to MISO hold time	18			ns
t _{SPIM,VMO}	CLK edge to MOSI valid			59	ns
t _{SPIM,HMO}	MOSI hold time after CLK edge	20			ns

High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

a At 25pF load, including GPIO pin capacitance, see GPIO spec.

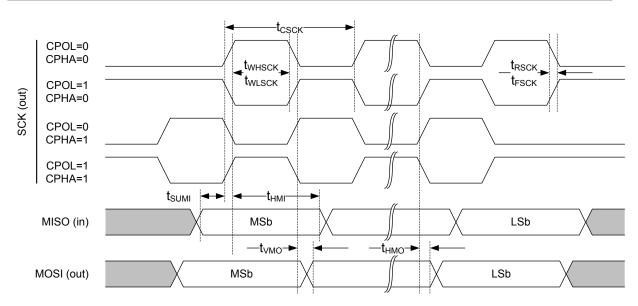


Figure 72: SPIM timing diagram

6.14 SPIS — Serial peripheral interface slave with EasyDMA

SPI slave (SPIS) is implemented with EasyDMA support for ultra low power serial communication from an external SPI master. EasyDMA in conjunction with hardware-based semaphore mechanisms removes all real-time requirements associated with controlling the SPI slave from a low priority CPU execution context.

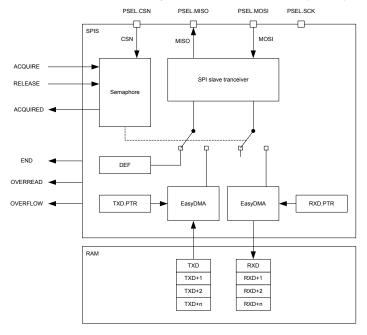


Figure 73: SPI slave

The SPIS supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.



Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Leading)	0 (Active High)
SPI_MODE1	0 (Leading)	1 (Active Low)
SPI_MODE2	1 (Trailing)	0 (Active High)
SPI_MODE3	1 (Trailing)	1 (Active Low)

Table 71: SPI modes

6.14.1 Shared resources

The SPI slave shares registers and other resources with other peripherals that have the same ID as the SPI slave. Therefore, you must disable all peripherals that have the same ID as the SPI slave before the SPI slave can be configured and used.

Disabling a peripheral that has the same ID as the SPI slave will not reset any of the registers that are shared with the SPI slave. It is important to configure all relevant SPI slave registers explicitly to secure that it operates correctly.

The Instantiation table in Instantiation on page 23 shows which peripherals have the same ID as the SPI slave.

6.14.2 EasyDMA

The SPI slave implements EasyDMA for reading and writing to and from the RAM. The END event indicates that EasyDMA has finished accessing the buffer in RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

6.14.3 SPI slave operation

SPI slave uses two memory pointers, RXD.PTR and TXD.PTR, that point to the RXD buffer (receive buffer) and TXD buffer (transmit buffer) respectively. Since these buffers are located in RAM, which can be accessed by both the SPI slave and the CPU, a hardware based semaphore mechanism is implemented to enable safe sharing.

See SPI transaction when shortcut between END and ACQUIRE is enabled on page 242.

Before the CPU can safely update the RXD.PTR and TXD.PTR pointers it must first acquire the SPI semaphore. The CPU can acquire the semaphore by triggering the ACQUIRE task and then receiving the ACQUIRED event. When the CPU has updated the RXD.PTR and TXD.PTR pointers the CPU must release the semaphore before the SPI slave will be able to acquire it. The CPU releases the semaphore by triggering the RELEASE task. This is illustrated in SPI transaction when shortcut between END and ACQUIRE is enabled on page 242. Triggering the RELEASE task when the semaphore is not granted to the CPU will have no effect.

The semaphore mechanism does not, at any time, prevent the CPU from performing read or write access to the RXD.PTR register, the TXD.PTR registers, or the RAM that these pointers are pointing to. The semaphore is only telling when these can be updated by the CPU so that safe sharing is achieved.

The semaphore is by default assigned to the CPU after the SPI slave is enabled. No ACQUIRED event will be generated for this initial semaphore handover. An ACQUIRED event will be generated immediately if the ACQUIRE task is triggered while the semaphore is assigned to the CPU.

The SPI slave will try to acquire the semaphore when CSN goes low. If the SPI slave does not manage to acquire the semaphore at this point, the transaction will be ignored. This means that all incoming data on MOSI will be discarded, and the DEF (default) character will be clocked out on the MISO line throughout the whole transaction. This will also be the case even if the semaphore is released by the CPU during the



transaction. In case of a race condition where the CPU and the SPI slave try to acquire the semaphore at the same time, as illustrated in lifeline item 2 in SPI transaction when shortcut between END and ACQUIRE is enabled on page 242, the semaphore will be granted to the CPU.

If the SPI slave acquires the semaphore, the transaction will be granted. The incoming data on MOSI will be stored in the RXD buffer and the data in the TXD buffer will be clocked out on MISO.

When a granted transaction is completed and CSN goes high, the SPI slave will automatically release the semaphore and generate the END event.

As long as the semaphore is available the SPI slave can be granted multiple transactions one after the other. If the CPU is not able to reconfigure the TXD.PTR and RXD.PTR between granted transactions, the same TX data will be clocked out and the RX buffers will be overwritten. To prevent this from happening, the END_ACQUIRE shortcut can be used. With this shortcut enabled the semaphore will be handed over to the CPU automatically after the granted transaction has completed, giving the CPU the ability to update the TXPTR and RXPTR between every granted transaction.

If the CPU tries to acquire the semaphore while it is assigned to the SPI slave, an immediate handover will not be granted. However, the semaphore will be handed over to the CPU as soon as the SPI slave has released the semaphore after the granted transaction is completed. If the END_ACQUIRE shortcut is enabled and the CPU has triggered the ACQUIRE task during a granted transaction, only one ACQUIRE request will be served following the END event.

The MAXRX register specifies the maximum number of bytes the SPI slave can receive in one granted transaction. If the SPI slave receives more than MAXRX number of bytes, an OVERFLOW will be indicated in the STATUS register and the incoming bytes will be discarded.

The MAXTX parameter specifies the maximum number of bytes the SPI slave can transmit in one granted transaction. If the SPI slave is forced to transmit more than MAXTX number of bytes, an OVERREAD will be indicated in the STATUS register and the ORC character will be clocked out.

The RXD.AMOUNT and TXD.AMOUNT registers are updated when a granted transaction is completed. The TXD.AMOUNT register indicates how many bytes were read from the TX buffer in the last transaction, that is, ORC (over-read) characters are not included in this number. Similarly, the RXD.AMOUNT register indicates how many bytes were written into the RX buffer in the last transaction.

The ENDRX event is generated when the RX buffer has been filled.



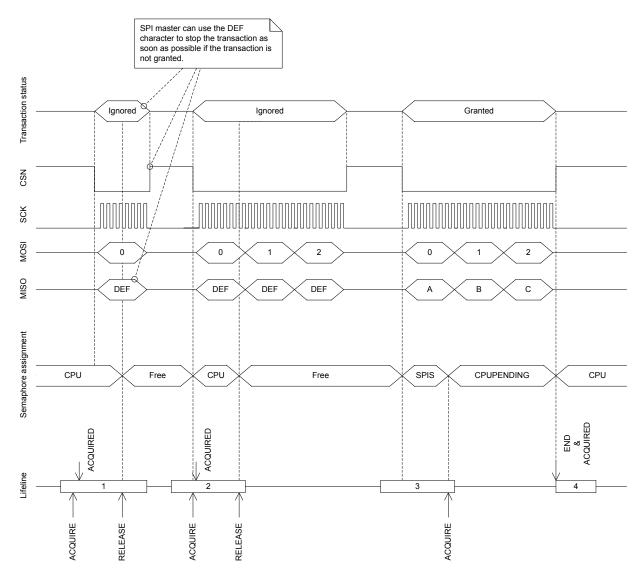


Figure 74: SPI transaction when shortcut between END and ACQUIRE is enabled

6.14.4 Pin configuration

The CSN, SCK, MOSI, and MISO signals associated with the SPI slave are mapped to physical pins according to the configuration specified in the PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively. If the CONNECT field of any of these registers is set to Disconnected, the associated SPI slave signal will not be connected to any physical pins.

The PSEL.CSN, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI slave is enabled, and retained only as long as the device is in System ON mode, see POWER — Power control on page 58 chapter for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO must only be configured when the SPI slave is disabled.

To secure correct behavior in the SPI slave, the pins used by the SPI slave must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 243 before enabling the SPI slave. This is to secure that the pins used by the SPI slave are driven correctly if the SPI slave itself is temporarily disabled, or if the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the SPI slave is to be recognized by an external SPI master.

The MISO line is set in high impedance as long as the SPI slave is not selected with CSN.



Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI signal	SPI pin	Direction	Output value Comment
CSN	As specified in PSEL.CSN	Input	Not applicable
SCK	As specified in PSEL.SCK	Input	Not applicable
MOSI	As specified in PSEL.MOSI	Input	Not applicable
MISO	As specified in PSEL.MISO	Input	Not applicable Emulates that the SPI slave is not selected.

Table 72: GPIO configuration before enabling peripheral

6.14.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	SPIS	SPIS0 : S	US	SA	SPI slave 0	
0x40008000	3113	SPIS0 : NS	03	JA.	SFI Slave 0	
0x50009000	SPIS	SPIS1:S	US	SA	SPI slave 1	
0x40009000	3113	SPIS1 : NS	03	JA.	SFI Slave 1	
0x5000A000	SPIS	SPIS2 : S	US	SA	SPI slave 2	
0x4000A000	3113	SPIS2 : NS	03	JA.	SFI Slave 2	
0x5000B000	SPIS	SPIS3 : S	US	SA	SPI slave 3	
0x4000B000	SPIS	SPIS3 : NS	03	JA	SPI Sidve 5	

Table 73: Instances

Register	Offset	Security	Description	
TASKS_ACQUIRE	0x024		Acquire SPI semaphore	
TASKS_RELEASE	0x028		Release SPI semaphore, enabling the SPI slave to acquire it	
SUBSCRIBE_ACQUIRE	0x0A4		Subscribe configuration for task ACQUIRE	
SUBSCRIBE_RELEASE	0x0A8		Subscribe configuration for task RELEASE	
EVENTS_END	0x104		Granted transaction completed	
EVENTS_ENDRX	0x110		End of RXD buffer reached	
EVENTS_ACQUIRED	0x128		Semaphore acquired	
PUBLISH_END	0x184		Publish configuration for event END	
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX	
PUBLISH_ACQUIRED	0x1A8		Publish configuration for event ACQUIRED	
SHORTS	0x200		Shortcuts between local events and tasks	
INTENSET	0x304		Enable interrupt	
INTENCLR	0x308		Disable interrupt	
SEMSTAT	0x400		Semaphore status register	
STATUS	0x440		Status from last transaction	
ENABLE	0x500		Enable SPI slave	
PSEL.SCK	0x508		Pin select for SCK	
PSEL.MISO	0x50C		Pin select for MISO signal	
PSEL.MOSI	0x510		Pin select for MOSI signal	
PSEL.CSN	0x514		Pin select for CSN signal	
PSELSCK	0x508		Pin select for SCK	Deprecated
PSELMISO	0x50C		Pin select for MISO	Deprecated
PSELMOSI	0x510		Pin select for MOSI	Deprecated
PSELCSN	0x514		Pin select for CSN	Deprecated
RXD.PTR	0x534		RXD data pointer	
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer	
RXD.AMOUNT	0x53C		Number of bytes received in last granted transaction	

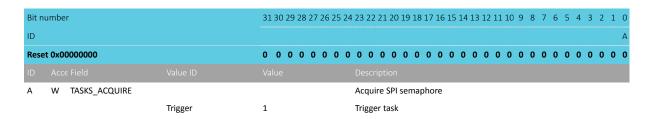


Register	Offset	Security	Description	
RXDPTR	0x534		RXD data pointer	Deprecated
MAXRX	0x538		Maximum number of bytes in receive buffer	Deprecated
AMOUNTRX	0x53C		Number of bytes received in last granted transaction	Deprecated
TXD.PTR	0x544		TXD data pointer	
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer	
TXD.AMOUNT	0x54C		Number of bytes transmitted in last granted transaction	
TXDPTR	0x544		TXD data pointer	Deprecated
MAXTX	0x548		Maximum number of bytes in transmit buffer	Deprecated
AMOUNTTX	0x54C		Number of bytes transmitted in last granted transaction	Deprecated
CONFIG	0x554		Configuration register	
DEF	0x55C		Default character. Character clocked out in case of an ignored transaction.	
ORC	0x5C0		Over-read character	

Table 74: Register overview

6.14.5.1 TASKS ACQUIRE

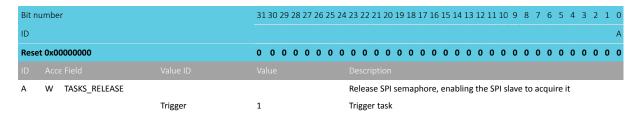
Address offset: 0x024 Acquire SPI semaphore



6.14.5.2 TASKS_RELEASE

Address offset: 0x028

Release SPI semaphore, enabling the SPI slave to acquire it



6.14.5.3 SUBSCRIBE_ACQUIRE

Address offset: 0x0A4

Subscribe configuration for task $\ensuremath{\mathsf{ACQUIRE}}$



Bit number		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		В	АААА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CHIDX		[150]	Channel that task ACQUIRE will subscribe to
B RW EN			
	Disabled	0	Disable subscription
	Enabled	1	Enable subscription

6.14.5.4 SUBSCRIBE_RELEASE

Address offset: 0x0A8

Subscribe configuration for task RELEASE

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task RELEASE will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.14.5.5 EVENTS_END

Address offset: 0x104

Granted transaction completed

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_END			Granted transaction completed
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.14.5.6 EVENTS_ENDRX

Address offset: 0x110

End of RXD buffer reached

Bit n	umber		31	30	29	28 2	27 2	26 2	5 2	4 23	3 2:	2 2	1 20	0 19	9 18	3 17	16	5 15	14	13	12	11 :	10 9	8	7	6	5	4	3	2	1 0
ID																															Α
Rese	t 0x00000000		0	0	0	0	0	0 0) (0	0) (0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0 0
ID																															
Α	RW EVENTS_ENDRX									Eı	nd	of I	RXD	bu	ıffe	r re	acł	ned													
		NotGenerated	0							Ev	/en	nt n	ot g	gen	era	ted															
		Generated	1							E۱	/en	nt g	ene	rat	ed																

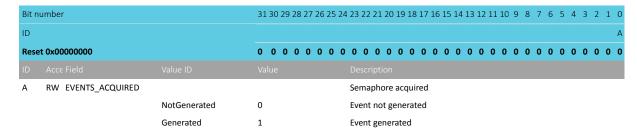
6.14.5.7 EVENTS_ACQUIRED

Address offset: 0x128





Semaphore acquired



6.14.5.8 PUBLISH_END

Address offset: 0x184

Publish configuration for event END

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event END will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.14.5.9 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x0000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event ENDRX will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.14.5.10 PUBLISH_ACQUIRED

Address offset: 0x1A8

Publish configuration for event ACQUIRED

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event ACQUIRED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing



6.14.5.11 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field			Description
A RW END_ACQUIRE			Shortcut between event END and task ACQUIRE
	Disabled	0	Disable shortcut
	Enabled	1	Enable shortcut

6.14.5.12 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW END			Write '1' to enable interrupt for event END
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW ENDRX			Write '1' to enable interrupt for event ENDRX
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
C RW ACQUIRED			Write '1' to enable interrupt for event ACQUIRED
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.14.5.13 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number		31 30 29 28 27 26	5 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Reset 0x00000000		0 0 0 0 0 0	0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field				
A RW END				Write '1' to disable interrupt for event END
	Clear	1		Disable
	Disabled	0		Read: Disabled
	Enabled	1		Read: Enabled
B RW ENDRX				Write '1' to disable interrupt for event ENDRX
	Clear	1		Disable
	Disabled	0		Read: Disabled
	Enabled	1		Read: Enabled



Bit number		31 30 2	9 28	27 2	26 25	5 24	23 2	22 2	21 2	0 19	18	17	16 1	15 1	4 13	3 12	11	10 9	8	7	6	5	4	3	2 1	. 0
ID																		С					В		A	
Reset 0x00000000		0 0	0 0	0	0 0	0	0	0	0 0	0	0	0	0	0 (0	0	0	0 0	0	0	0	0	0	0 (0	0
ID Acce Field																										
C RW ACQUIRED							Wri	ite '	'1' to	o dis	sabl	e in	terr	upt	for	ever	nt A	cqu	IRE	D						
	Clear	1					Disa	able	е																	
I	Disabled	0					Rea	id:	Disa	bled	t															
	Enabled	1					Rea	id:	Enal	oled																

6.14.5.14 SEMSTAT

Address offset: 0x400

Semaphore status register

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A
Rese	et 0x0000001		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	R SEMSTAT			Semaphore status
		Free	0	Semaphore is free
		CPU	1	Semaphore is assigned to CPU
		SPIS	2	Semaphore is assigned to SPI slave
		CPUPending	3	Semaphore is assigned to SPI but a handover to the CPU is
				pending

6.14.5.15 STATUS

Address offset: 0x440

Status from last transaction

Individual bits are cleared by writing a '1' to the bits that shall be cleared

Bit numbe	er		313	30 2	9 28	27	26 2	5 24	1 2	3 22	2 2 1	1 20	19	18 1	.7 1	6 1	5 14	13	12	11 1	.0 9	8	7	6	5	4 3	3 2	1	0
ID																												В	Α
Reset 0x0	0000000		0	0 (0 0	0	0 (0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0 0	0	0	0	0	0 (0	0	0
ID Acc																													
A RW	OVERREAD								T.	X bı	ıffe	er ov	er-ı	reac	l de	tec	ed,	and	d pr	eve	nted								
		NotPresent	0						R	ead	: er	rror	not	pre	sen	t													
		Present	1						R	ead	: er	rror	pre	sen	t														
		Clear	1						W	Vrite	e: cl	lear	err	or o	n w	ritii	ng '	1'											
B RW	OVERFLOW								R	X bı	uffe	er ov	/erf	low	det	ect	ed,	and	pre	ever	ted								
		NotPresent	0						R	ead	: er	rror	not	pre	sen	t													
		Present	1						R	ead	: er	rror	pre	sen	t														
		Clear	1						W	Vrite	e: cl	lear	err	or o	n w	ritii	ng '	1'											

6.14.5.16 ENABLE

Address offset: 0x500

Enable SPI slave



Bit number		31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			ААА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable SPI slave
	Disabled	0	Disable SPI slave
	Enabled	2	Enable SPI slave

6.14.5.17 PSEL.SCK

Address offset: 0x508
Pin select for SCK

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.14.5.18 PSEL.MISO

Address offset: 0x50C

Pin select for MISO signal

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.14.5.19 PSEL.MOSI

Address offset: 0x510

Pin select for MOSI signal

Bit r	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect



6.14.5.20 PSEL.CSN

Address offset: 0x514

Pin select for CSN signal

Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.14.5.21 PSELSCK (Deprecated)

Address offset: 0x508

Pin select for SCK

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			AAAAAA	A A A A A A A A A A A A A A A A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PSELSCK		[031]	Pin number configuration for SPI SCK signal
		Disconnected	0xFFFFFFF	Disconnect

6.14.5.22 PSELMISO (Deprecated)

Address offset: 0x50C Pin select for MISO

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A	
Rese	Reset 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PSELMISO		[031]	Pin number configuration for SPI MISO signal
		Disconnected	0xFFFFFFF	Disconnect

6.14.5.23 PSELMOSI (Deprecated)

Address offset: 0x510
Pin select for MOSI

		Disconnected	Oxeeeeee	Disconnect
Α	RW PSELMOSI		[031]	Pin number configuration for SPI MOSI signal
ID				
Res	et 0xFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID			A A A A A A	. A A A A A A A A A A A A A A A A A A A
Bit	number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0





6.14.5.24 PSELCSN (Deprecated)

Address offset: 0x514

Pin select for CSN

		Disconnected	0xFFFFFFF	Disconnect
Α	RW PSELCSN		[031]	Pin number configuration for SPI CSN signal
ID				Description
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 :	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID			A A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.14.5.25 RXD.PTR

Address offset: 0x534

RXD data pointer

Δ	RW PTR	value 15	RXD data pointer
ID	Acce Field		Value Description
Rese	et 0x0000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.5.26 RXD.MAXCNT

Address offset: 0x538

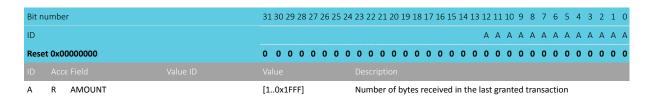
Maximum number of bytes in receive buffer

A	RW MAXCNT		[10x1FFF]	Maximum number of bytes in receive buffer
ID				
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	ID			A A A A A A A A A A A A A A A A A A A
Bit r	number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.14.5.27 RXD.AMOUNT

Address offset: 0x53C

Number of bytes received in last granted transaction

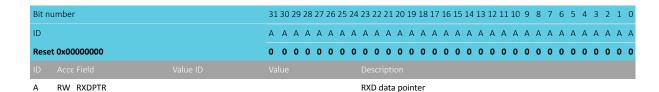


6.14.5.28 RXDPTR (Deprecated)

Address offset: 0x534



RXD data pointer

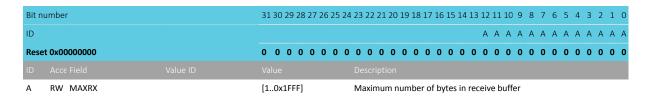


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.5.29 MAXRX (Deprecated)

Address offset: 0x538

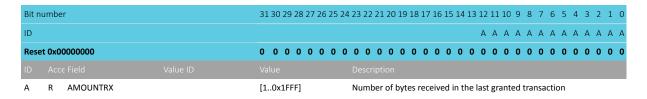
Maximum number of bytes in receive buffer



6.14.5.30 AMOUNTRX (Deprecated)

Address offset: 0x53C

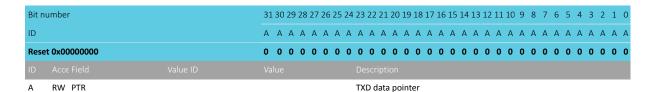
Number of bytes received in last granted transaction



6.14.5.31 TXD.PTR

Address offset: 0x544

TXD data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.5.32 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



Α	RW MAXCNT	[10x1FF	F1		N	Лахіг	num	num	ber c	of byt	es i	n tra	nsm	it b	uffe	r						
ID																						
Res	et 0x00000000	0 0 0	0 0	0 0	0 (0 0	0 0	0	0 0	0	0 (0 0	0	0 (0 0	0	0	0	0 (0	0	0 0
ID													Α .	Δ ,	4 A	Α	Α	Α	A A	A A	Α	A A
Bit r	umber	31 30 29	28 27	26 25	24 2	3 22	21 2	0 19	18 17	7 16 :	15 1	4 13	12 1	.1 1	.0 9	8	7	6	5 4	1 3	2	1 0

6.14.5.33 TXD.AMOUNT

Address offset: 0x54C

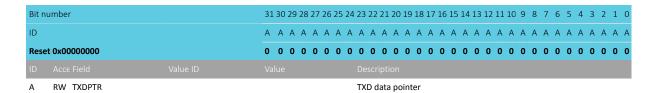
Number of bytes transmitted in last granted transaction

A R AMOUNT	[10x1FFF]	Number of bytes transmitted in last granted transaction
ID Acce Field		
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.14.5.34 TXDPTR (Deprecated)

Address offset: 0x544

TXD data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.5.35 MAXTX (Deprecated)

Address offset: 0x548

Maximum number of bytes in transmit buffer

Δ	RW MAXTX	[10x1FFF]	Maximum number of bytes in transmit buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.14.5.36 AMOUNTTX (Deprecated)

Address offset: 0x54C

Number of bytes transmitted in last granted transaction



Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	A R AMOUNTTX	[10x1FFF]	Number of by	tes tran	smitte	ed in la	st gra	ntec	l tra	ınsad	ctio	า			
ID A A A A A A A A A A A A A A A A A A A	ID Acce Field														
	Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0	0 0	0 0	0 0	0 0	0	0 (0	0	0 (0	0 () 0
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	ID						A A	Α	A A	A A	Α	A A	AA	A A	A A
	Bit number	31 30 29 28 27 26 25 24	1 23 22 21 20 19	9 18 17 :	16 15	14 13	12 11	10	9 8	3 7	6	5 4	1 3	2 1	L O

6.14.5.37 CONFIG

Address offset: 0x554 Configuration register

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
				Description
Α	RW ORDER			Bit order
		MsbFirst	0	Most significant bit shifted out first
		LsbFirst	1	Least significant bit shifted out first
В	RW CPHA			Serial clock (SCK) phase
		Leading	0	Sample on leading edge of clock, shift serial data on trailing
				edge
		Trailing	1	Sample on trailing edge of clock, shift serial data on leading
				edge
С	RW CPOL			Serial clock (SCK) polarity
		ActiveHigh	0	Active high
		ActiveLow	1	Active low

6.14.5.38 DEF

Address offset: 0x55C

Default character. Character clocked out in case of an ignored transaction.

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field	Value Description
A RW DEF	Default character. Character clocked out in case of an
	ignored transaction.

6.14.5.39 ORC

Address offset: 0x5C0

Over-read character

A RW ORC		Over-rea	d charact	er. Cha	aracte	r clock	ed ou	t afte	er ar	ove	er-			
ID Acce Field														
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0	0 0 0	0 0	0 0	0 0	0 0	0	0 0	0	0	0 0	0	0 0
ID									A	Α	Α	А А	Α	A A
Bit number	31 30 29 28 27 26	25 24 23 22 21	20 19 18	17 16	15 14	13 12	11 10	9	8 7	6	5	4 3	2	1 0

Over-read character. Character clocked out after an overread of the transmit buffer.



6.14.6 Electrical specification

6.14.6.1 SPIS slave interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIS}	Bit rates for SPIS ¹¹			8 ¹²	Mbps
t _{SPIS,START}	Time from RELEASE task to receive/transmit (CSN active)				μs

6.14.6.2 Serial Peripheral Interface Slave (SPIS) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIS,CSCKIN}	SCK input period				ns
t _{SPIS,RFSCKIN}	SCK input rise/fall time			30	ns
t _{SPIS,WHSCKIN}	SCK input high time	30			ns
t _{SPIS,WLSCKIN}	SCK input low time	30			ns
t _{SPIS,SUCSN}	CSN to CLK setup time	1000			ns
t _{SPIS,HCSN}	CLK to CSN hold time	2000			ns
t _{SPIS,ASA}	CSN to MISO driven				ns
t _{SPIS,ASO}	CSN to MISO valid ^a			1000	ns
t _{SPIS,DISSO}	CSN to MISO disabled ^a			68	ns
t _{SPIS,CWH}	CSN inactive time	300			ns
t _{SPIS,VSO}	CLK edge to MISO valid			19	ns
t _{SPIS,HSO}	MISO hold time after CLK edge	18 ¹³			ns
t _{SPIS,SUSI}	MOSI to CLK edge setup time	59			ns
t _{SPIS,HSI}	CLK edge to MOSI hold time	20			ns

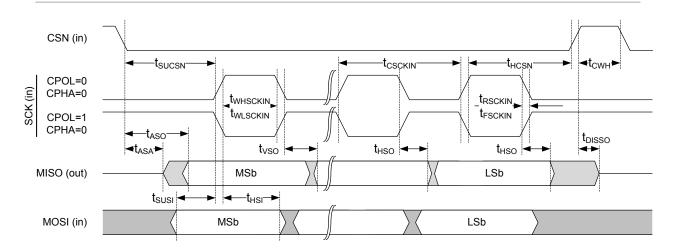


High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

The actual maximum data rate depends on the master's CLK to MISO and MOSI setup and hold timings

^a At 25pF load, including GPIO capacitance, see GPIO spec.

This is to ensure compatibility to SPI masters sampling MISO on the same edge as MOSI is output



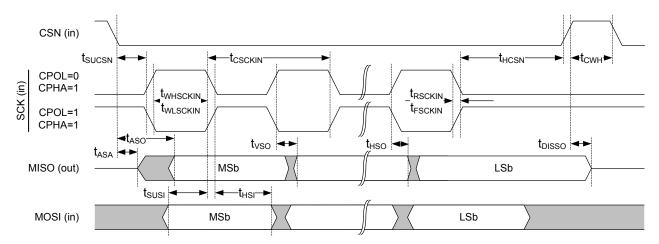


Figure 75: SPIS timing diagram

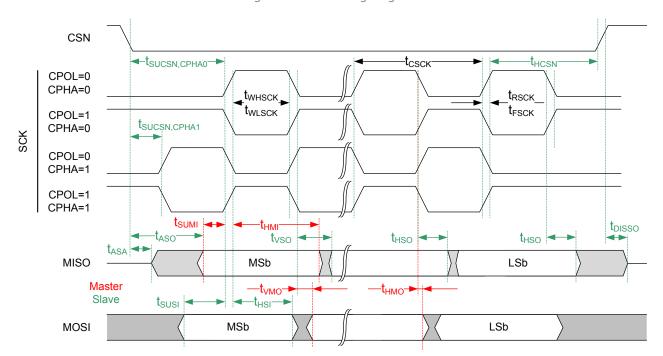


Figure 76: Common SPIM and SPIS timing diagram



6.15 SPU - System protection unit

SPU is the central point in the system to control access to memories, peripherals and other resources.

Listed here are the main features of the SPU:

- ARM[®] TrustZone[®] support, allowing definition of secure, non-secure and non-secure callable memory regions
- Extended ARM[®]TrustZone[®], protecting memory regions and peripherals from non-CPU devices like EasyDMA transfer
- Pin access protection, preventing non-secure code and peripherals from accessing secure pin resources
- DPPI access protection, realized by preventing non-secure code and peripherals to publish from or subscribe to secured DPPI channels
- External domain access protection, controlling access rights from other MCUs

6.15.1 General concepts

SPU provides a register interface to control the various internal logic blocks that monitor access to memory-mapped slave devices (RAM, flash, peripherals, etc) and other resources (device pins, DPPI channels, etc).

For memory-mapped devices like RAM, flash and peripherals, the internal logic checks the address and attributes (e.g. read, write, execute, secure) of the incoming transfer to block it if necessary. Whether a secure resource can be accessed by a given master is defined:

For a CPU-type master

By the security state of the CPU and the security state reported by the SPU, for the address in the bus transfer

For a non-CPU master

By the security attribute of the master that initiates the transfer, defined by a SPU register The Simplified view of the protection of RAM, flash and peripherals using SPU on page 257 shows a simplified view of the SPU registers controlling several internal modules.

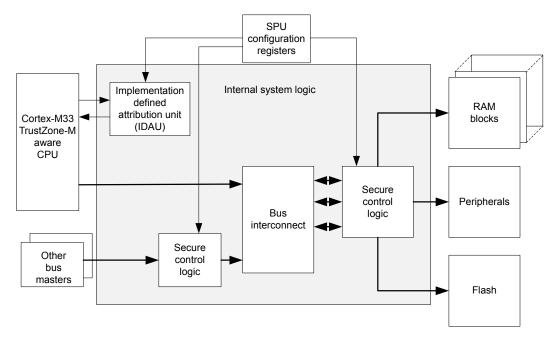


Figure 77: Simplified view of the protection of RAM, flash and peripherals using SPU



The protection logic implements a read-as-zero/write-ignore (RAZ/WI) policy:

- A blocked read operation will always return a zero value on the bus, preventing information leak
- A write operation to a forbidden region or peripheral will be ignored

An error is reported through dedicated error signals. For security state violations from an M33 master this will be a SecureFault exception, for other violations this will be an SPU event. The SPU event can be configured to generate an interrupt towards the CPU.

Other resources like pins and DPPI channels are protected by comparing the security attributes of the protected resource with the security attribute of the peripheral that wants to access it. The SPU is the only place where those security attributes can be configured.

6.15.1.1 Special considerations for ARM TrustZone for Cortex-M enabled system

For a ARM[®] TrustZone[®] for Cortex[®]-M enabled CPU, the SPU also controls custom logic.

Custom logic is shown as the implementation defined attribution unit (IDAU) in figure Simplified view of the protection of RAM, flash and peripherals using SPU on page 257. Full support is provided for:

- ARM[®] TrustZone[®] for Cortex[®]-M related instructions, like test target (TT) for reporting the security attributes of a region
- · Non-secure callable (NSC) regions, to implement secure entry points from non-secure code

The SPU provides the necessary registers to configure the security attributes for memory regions and peripherals. However, as a requirement to use the SPU, the secure attribution unit (SAU) needs to be disabled and all memory set as non-secure in the ARM core. This will allow the SPU to control the IDAU and set the security attribution of all addresses as originally intended.

6.15.2 Flash access control

The flash memory space is divided into 32 regions of 32 KiB. For each region, four different types of permissions can be configured.

The four types of permissions are:

Read

Allows data read access to the region. Note that code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write or erase access to the region

Execute

Allows code fetch from this region, even if data read is disabled

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a flash region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked by using the FLASHPERM[].PERM.LOCK bit, to prevent subsequent modifications.

Note that the debugger is able to step through execute-protected memory regions.

The following figure shows the flash memory space and the divided regions:



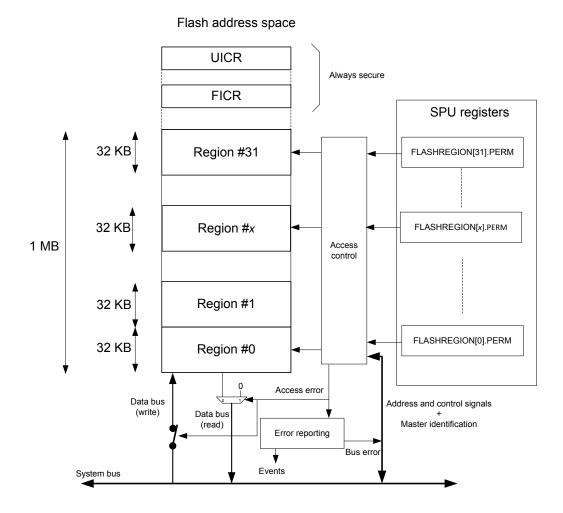


Figure 78: Region definition in the flash memory space

6.15.2.1 Non-secure callable (NSC) region definition in flash

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- FLASHNSC[].REGION, used to select the secure region that will contain the NSC sub-region
- FLASHNSC[].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



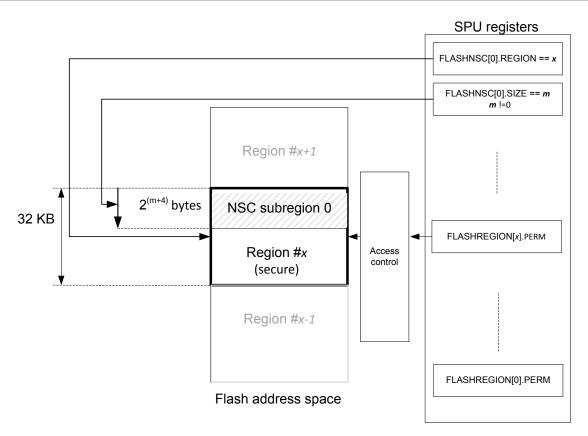


Figure 79: Non-secure callable region definition in the flash memory space

The NSC sub-region will only be defined if:

- FLASHNSC[i].SIZE value is non zero
- FLASHNSC[i].REGION defines a secure region

If FLASHNSC[i].REGION and FLASHNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of FLASHNSC[i].SIZE and FLASHNSC[j].SIZE.

If FLASHNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.2.2 Flash access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the flash ports:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the
 master. Moreover, the SPU will receive an event that can optionally trigger an interrupt towards the
 CPU.
- SecureFault exception will be triggered if security violation is detected for access from Cortex[®]-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex[®]-M33
- FLASHACCERR event will be triggered if any access violations are detected for all master types except for Cortex[®]-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:



Master type	Security violation	Read/Write/Execute protection violation
Cortex [®] -M33	SecureFault exception	BusFault exception, FLASHACCERR event
EasyDMA	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event
Other masters	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event

Table 75: Error reporting for flash access errors

For a Cortex[®]-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.2.3 UICR and FICR protections

The user information configuration registers (UICR) and factory information configuration registers (FICR) are always considered as secure. FICR registers are read-only. UICR registers can be read and written by secure code only.

Writing new values to user information configuration registers must follow the procedure described in NVMC — Non-volatile memory controller on page 28. Code execution from FICR and UICR address spaces will always be reported as access violation, an exception to this rule applies during a debug session.

6.15.3 RAM access control

Each RAM memory space region has a set of permissions that can be set independently.

The RAM memory space is divided into 32 regions of 8 KiB.

For each region, four different types of permissions can be configured:

Read

Allows data read access to the region. Code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write access to the region

Execute

Allows code fetch from this region

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a RAM region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked to prevent subsequent modifications by using the RAMPERM[].PERM.LOCK bit.

The following figure shows the RAM memory space and the devided regions:



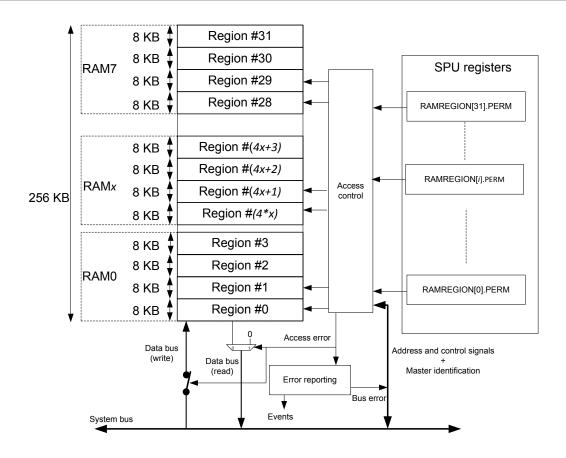


Figure 80: Region definition in the RAM memory space

6.15.3.1 Non-secure callable (NSC) region definition in RAM

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- RAMNSC[].REGION, used to select the secure region that will contain the NSC sub-region
- RAMNSC[].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



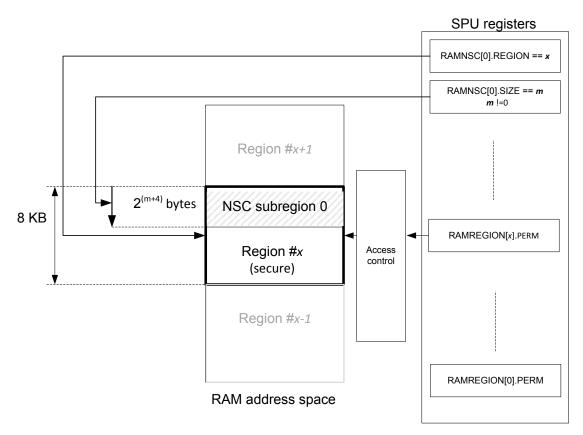


Figure 81: Non-secure callable region definition in the RAM memory space

The NSC sub-region will only be defined if:

- RAMNSC[i].SIZE value is non zero
- RAMNSC[i].REGION defines a secure region

If RAMNSC[i].REGION and RAMNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of RAMNSC[i].SIZE and RAMNSC[j].SIZE.

If RAMNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.3.2 RAM access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the RAM ports:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the master
- SecureFault exception will be triggered if security violation is detected for access from Cortex[®]-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex[®]-M33. The SPU will also generate an event that can optionally trigger an interrupt towards the CPU.
- RAMACCERR event will be triggered if any access violations are detected for all master types but for Cortex[®]-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:



Master type	Security violation	Read/Write/Execute protection violation
Cortex [®] -M33	SecureFault exception	BusFault exception, RAMACCERR event
EasyDMA	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event
Other masters	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event

Table 76: Error reporting for RAM access errors

For a Cortex[®]-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.4 Peripheral access control

Access controls are defined by the characteristics of the peripheral.

Peripherals can have their security attribute set as:

Always secure

For a peripheral related to system control

Always non-secure

For some general-purpose peripherals

Configurable

For general-purpose peripherals that may be configured for secure only access

The full list of peripherals and their corresponding security attributes can be found in Memory map on page 22. For each peripheral with ID *id*, PERIPHID[*id*]. PERM will show whether the security attribute for this peripheral is configurable or not.

If not hardcoded, the security attribute can configured using the PERIPHID[id].PERM.

At reset, all user-selectable and split security peripherals are set to be secure, with secure DMA where present.

Secure code can access both secure peripherals and non-secure peripherals.

6.15.4.1 Peripherals with split security

Peripherals with split security are defined to handle use-cases when both secure and non-secure code needs to control the same resource.

When peripherals with split security have their security attribute set to non-secure, access to specific registers and bitfields within some registers is dependent on the security attribute of the bus transfer. For example, some registers will not be accessible for a non-secure transfer.

When peripherals with split security have their security attribute set to secure, then only secure transfers can access their registers.

See Instantiation on page 23 for an overview of split security peripherals. Respective peripheral chapters explain the specific security behavior of each peripheral.

6.15.4.2 Peripheral address mapping

Peripherals that have non-secure security mapping have their address starting with 0x4XXX_XXXX. Peripherals that have secure security mapping have their address starting with 0x5XXX_XXXX.

Peripherals with a user-selectable security mapping are available at an address starting with:

- 0x4XXX XXXX, if the peripheral security attribute is set to non-secure
- 0x5XXX_XXXX, if the peripheral security attribute is set to secure



Peripherals with a split security mapping are available at an address starting with:

- 0x4XXX_XXXX for non-secure access and 0x5XXX_XXXX for secure access, if the peripheral security attribute is set to non-secure
 - Secure registers in the 0x4XXX_XXXX range are not visible for secure or non-secure code, and an attempt to access such a register will result in write-ignore, read-as-zero behavior
 - Secure code can access both non-secure and secure registers in the 0x5XXX_XXXX range
- 0x5XXX XXXX, if the peripheral security attribute is set to secure

Any attempt to access the 0x5000_0000-0x5FFF_FFFF address range from non-secure code will be ignored and generate a SecureFault exception.

The table below illustrates the address mapping for the three type of peripherals in all possible configurations

Security-features and configuration	Is mapped at 0x4XXX_XXXX?	Is mapped at 0x5XXX_XXXX?
Secure peripheral	No	Yes
Non-secure peripheral	Yes	No
Split-security peripheral, with attribute=secure	No	Yes
Split-security peripheral, with attribute=non-secure	Yes, restricted functionality	Yes

Table 77: Peripheral's address mapping in relation to its security-features and configuration

6.15.4.3 Special considerations for peripherals with DMA master

Peripherals containing a DMA master can be configured so the security attribute of the DMA transfers is different from the security attribute of the peripheral itself. This allows a secure peripheral to do non-secure data transfers to or from the system memories.

The following conditions must be met:

- The DMA field of PERIPHID[].PERM.SECURITYMAPPING should read as "SeparateAttribute"
- The peripheral itself should be secure (PERIPHID[].PERM.SECATTR == 1)

Then it is possible to select the security attribute of the DMA transfers using the field DMASEC (PERIPHID[].PERM.DMASEC == Secure and PERIPHID[].PERM.DMASEC == NonSecure) in PERIPHID[].PERM.

6.15.4.4 Peripheral access error reporting

Peripherals send error reports once access violation is detected.

The following will happen if the logic controlled by the SPU detects an access violation on one of the peripherals:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback is sent to the master through specific bus error signals, if this is supported by the master. If the master is a processor supporting ARM[®] TrustZone[®] for Cortex[®]-M, a SecureFault exception will be generated for security related errors.
- The PERIPHACCERR event will be triggered

6.15.5 Pin access control

Access to device pins can be controlled by the SPU. A pin can be declared as secure so that only secure peripherals or secure code can access it.

The security attribute of each pin can be individually configured in SPU's GPIOPORT[0].PERM register. When the secure attribute is set for a pin, only peripherals that have the secure attribute set will be able to read the value of the pin or change it.



Peripherals can select the pin(s) they need access to through their PSEL register(s). If a peripheral has its attribute set to non-secure, but one of its PSEL registers selects a pin with the attribute set to secure, the SPU controlled logic will ensure that the pin selection is not propagated. In addition, the pin value will always be read as zero, to prevent a non-secure peripheral from obtaining a value from a secure pin. Whereas access to other pins with attribute set as non-secure will not be blocked.

Peripherals located in other domains (other than the application domain) can access pins only if the security attribute of the domain allows access to the pins they are trying to access. That is, secure domains can access both secure and non-secure pins, whereas non-secure domains can only access non-secure pins. This is illustrated in the following figure:

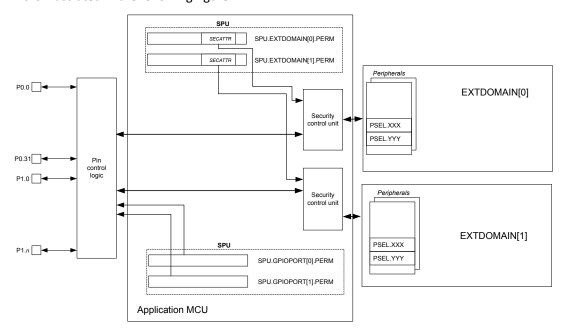


Figure 82: Pin access for domains other than the application domain

6.15.5.1 Direct pin control through the GPIO peripheral

Pins can be controlled directly through the general purpose input/output (GPIO) peripheral. It is a split-security peripheral, meaning that both secure and non-secure accesses are allowed.

Non-secure peripheral accesses will only be able to configure and control pins defined as non-secure in the GPIOPORT.PERM[] register(s). Attempts to access a register or a bitfield controlling a pin marked as secure in GPIO.PERM[] register(s) will be ignored:

- Write accesses will have no effect
- Read accesses will always return a zero value

No exception is triggered when a non-secure access targets a register or bitfield controlling a secure pin. For example, if the bit *i* is set in the GPIO.PERM[0] register (declaring Pin PO.*i* as secure), then

- non-secure write accesses to OUT, OUTSET, OUTCLR, DIR, DIRSET, DIRCLR and LATCH registers will not be able to write to bit *i* of those registers
- non-secure write accesses to register PIN_CNF[i] will be ignored
- non-secure read accesses to registers OUT, OUTSET, OUTCLR, IN, DIR, DIRSET, DIRCLR and LATCH will always read a 0 for the bit at position *i*
- non-secure read accesses to register PIN_CNF[i] will always return 0

The GPIO.DETECTMODE and GPIO.DETECTMODE_SEC registers are handled differently than the other registers mentioned before. When securely accessed, the DETECTMODE_SEC register controls the source for the DETECT_SEC signal for the pins marked as secure. Upon a non-secure access, the DETECTMODE_SEC is read as zero and write access are ignored. The GPIO.DETECTMODE register controls the source for the DETECT_NSEC signal for the pins defined as non-secured.



The DETECT_NSEC signal is routed to the non-secure GPIOTE peripheral, GPIOTE1, allowing generation of events and interrupts from pins marked as non-secured. The DETECT_SEC signal is routed to the secure GPIOTE peripheral, GPIOTE0, allowing generation of events and interrupts from pins marked as secured. The following figure illustrates how the DETECT_NSEC and DETECT_SEC signals are generated from the GPIO PIN[].DETECT signals.

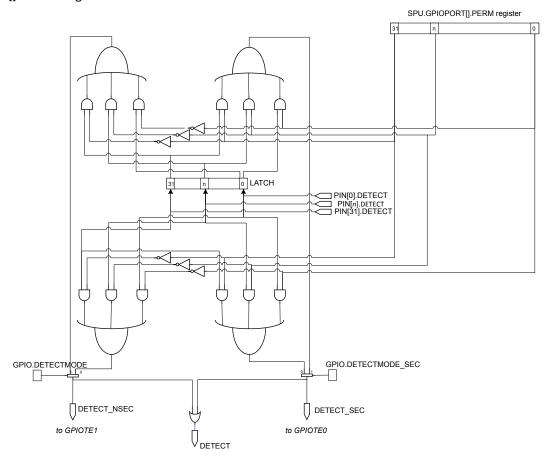


Figure 83: Principle of direct pin access

6.15.6 DPPI access control

Access to DPPI channels can be restricted. A channel can be declared as secure so that only secure peripherals can access it.

The security attribute of a DPPI channel is configured in . When the secure attribute is set for a channel, only peripherals that have the secure attribute set will be able to publish events to this channel or subscribe to this channel to receive tasks.

The DPPI controller peripheral (DPPIC) is a split security peripheral, i.e., its security behavior depends on the security attributes of both the DPPIC and the accessing party. See Special considerations regarding the DPPIC configuration registers on page 268 for more information about the DPPIC security behavior.

If a non-secure peripheral wants to publish an event on a secure DPPI channel, the channel will ignore the event. If a non-secure peripheral subscribes to a secure DPPI channel, it will not receive any events from this channel. The following figure illustrates the principle of operation of the security logic for a subscribed channel:



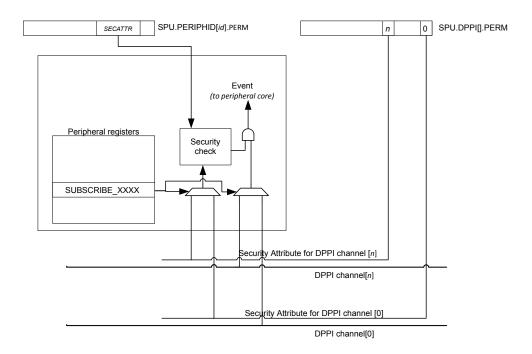


Figure 84: Subscribed channel security concept

No error reporting mechanism is associated with the DPPI access control logic.

6.15.6.1 Special considerations regarding the DPPIC configuration registers

DPPI channels can be enabled, disabled and grouped through the DPPI controller (DPPIC). The DPPIC is a split-security peripheral, and handles both secure and non-secure accesses.

A non-secure peripheral access will only be able to configure and control DPPI channels defined as non-secure in SPU's DPPI[n].PERM register(s). A secure peripheral access can control all DPPI channels, independently of the configuration in the DPPI[n].PERM register(s).

The DPPIC allows the creation of group of channels to be able to enable or disable all channels within a group simultaneously. The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all channels (enabled or not) in the group are non-secure, then the group is considered non-secure
- If at least one of the channels (enabled or not) in the group is secure, then the group is considered secure

A non-secure access to a DPPIC register, or a bitfield controlling a channel marked as secure in SPU.DDPI[n].PERM register(s), will be ignored:

- · Write accesses will have no effect
- Read will always return a zero value

No exceptions are thrown when a non-secure access targets a register or bitfield controlling a secure channel. For example, if the bit i is set in the SPU.DPPI[0].PERM register (declaring the DPPI channel i as secure), then:

- Non-secure write accesses to registers CHEN, CHENSET and CHENCLR will not be able to write to bit i of those registers
- Non-secure write accesses to registers TASK_CHG[j].EN and TASK_CHG[j].DIS will be ignored if the
 channel group j contains at least one channel defined as secure (it can be the channel i itself or any
 channel declared as secured)

NORDIC SEMICONDUCTOR

Non-secure read accesses to registers CHEN, CHENSET and CHENCLR will always read zero for the bit at
position i

For the channel configuration registers (DPPIC.CHG[...]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a DPPIC.CHG[g] register included one or more secure channels, then the group g is considered as secure and only a secure transfer can read or write DPPIC.CHG[g]. A non-secure write will be ignored and a non-secure read will return zero.

The DPPIC can subscribe to secure or non-secure channels through SUBSCRIBE_CHG[] registers in order to trigger task for enabling or disabling groups of channels. But an event from a non-secure channel will be ignored if the group subscribing to this channel is secure. An event from a secure channel can trigger both secure and non-secure tasks.

6.15.7 External domain access control

Other domains with their own CPUs can access peripherals, flash and RAM memories. The SPU allows controlling accesses from those bus masters.

The external domains can access application MCU memories and peripherals. External domains are assigned security attributes as described in register EXTDOMAIN[n].PERM.

Domain	Capability register	Permission register
LTE modem	Modem is always a non-secure domain	Not applicable

Table 78: Register mapping for external domains

The figure below illustrates how the security control units are used to assign security attributes to transfers initiated by the external domains:



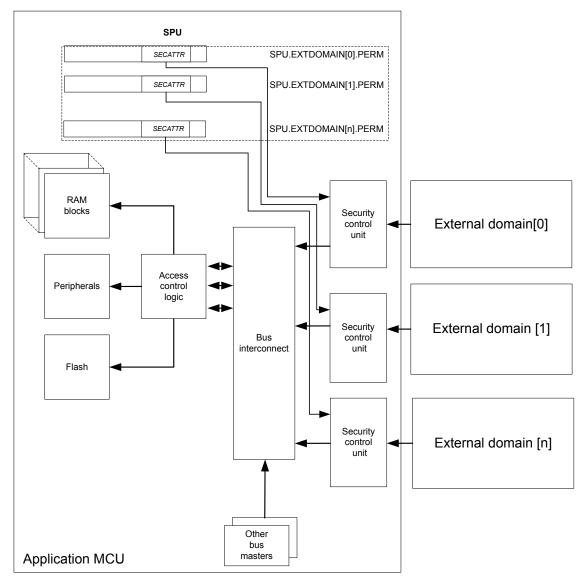


Figure 85: Access control from external domains

6.15.8 TrustZone for Cortex-M ID allocation

Flash and RAM regions, as well as non-secure and secure peripherals, are assigned unique $TrustZone^{@}$ IDs.

Note: TrustZone[®] ID should not be confounded with the peripheral ID used to identify peripherals.

The table below shows the TrustZone® ID allocation:

Regions	TrustZone Cortex-M ID
Flash regions 031	031
RAM regions 015	6479
Non-secure peripherals	253
Secure peripherals	254

Table 79: TrustZone ID allocation



6.15.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50003000	SPU	SPU	S	NA	System Protection Unit	

Table 80: Instances

Register	Offset	Security	Description	
EVENTS_RAMACCERR	0x100		A security violation has been detected for the RAM memory space	
EVENTS_FLASHACCERR	0x104		A security violation has been detected for the flash memory space	
EVENTS_PERIPHACCERR	0x108		A security violation has been detected on one or several peripherals	
PUBLISH_RAMACCERR	0x180		Publish configuration for event RAMACCERR	
PUBLISH_FLASHACCERR	0x184		Publish configuration for event FLASHACCERR	
PUBLISH_PERIPHACCERR	0x188		Publish configuration for event PERIPHACCERR	
INTEN	0x300		Enable or disable interrupt	
INTENSET	0x304		Enable interrupt	
INTENCLR	0x308		Disable interrupt	
CAP	0x400		Show implemented features for the current device	
EXTDOMAIN[0].PERM	0x440		Access for bus access generated from the external domain 0	
			List capabilities of the external domain 0	
DPPI[0].PERM	0x480		Select between secure and non-secure attribute for the DPPI channels.	
DPPI[0].LOCK	0x484		Prevent further modification of the corresponding PERM register	
GPIOPORT[0].PERM	0x4C0		Select between secure and non-secure attribute for pins 0 to 31 of port 0.	Retained
GPIOPORT[0].LOCK	0x4C4		Prevent further modification of the corresponding PERM register	
FLASHNSC[0].REGION	0x500		Define which flash region can contain the non-secure callable (NSC) region 0	
FLASHNSC[0].SIZE	0x504		Define the size of the non-secure callable (NSC) region 0	
FLASHNSC[1].REGION	0x508		Define which flash region can contain the non-secure callable (NSC) region 1	
FLASHNSC[1].SIZE	0x50C		Define the size of the non-secure callable (NSC) region 1	
RAMNSC[0].REGION	0x540		Define which RAM region can contain the non-secure callable (NSC) region 0	
RAMNSC[0].SIZE	0x544		Define the size of the non-secure callable (NSC) region 0	
RAMNSC[1].REGION	0x548		Define which RAM region can contain the non-secure callable (NSC) region 1	
RAMNSC[1].SIZE	0x54C		Define the size of the non-secure callable (NSC) region 1	
FLASHREGION[n].PERM	0x600		Access permissions for flash region n	
RAMREGION[n].PERM	0x700		Access permissions for RAM region n	
PERIPHID[n].PERM	0x800		List capabilities and access permissions for the peripheral with ID n	

Table 81: Register overview

6.15.9.1 EVENTS_RAMACCERR

Address offset: 0x100

A security violation has been detected for the RAM memory space

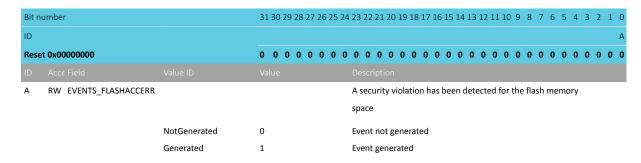
Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_RAMACCERR			A security violation has been detected for the RAM memory
				space
		NotGenerated	0	Event not generated
		Generated	1	Event generated



6.15.9.2 EVENTS_FLASHACCERR

Address offset: 0x104

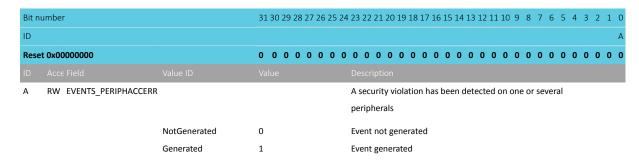
A security violation has been detected for the flash memory space



6.15.9.3 EVENTS PERIPHACCERR

Address offset: 0x108

A security violation has been detected on one or several peripherals



6.15.9.4 PUBLISH RAMACCERR

Address offset: 0x180

Publish configuration for event RAMACCERR

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event RAMACCERR will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.15.9.5 PUBLISH_FLASHACCERR

Address offset: 0x184

Publish configuration for event FLASHACCERR



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event FLASHACCERR will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.15.9.6 PUBLISH_PERIPHACCERR

Address offset: 0x188

Publish configuration for event PERIPHACCERR

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event PERIPHACCERR will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.15.9.7 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	umber		31 30 29 28 27 2	26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x00000000		0 0 0 0 0	0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW RAMACCERR				Enable or disable interrupt for event RAMACCERR
		Disabled	0		Disable
		Enabled	1		Enable
В	RW FLASHACCERR				Enable or disable interrupt for event FLASHACCERR
		Disabled	0		Disable
		Enabled	1		Enable
С	RW PERIPHACCERR				Enable or disable interrupt for event PERIPHACCERR
		Disabled	0		Disable
		Enabled	1		Enable

6.15.9.8 INTENSET

Address offset: 0x304

Enable interrupt



Bit r	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW RAMACCERR			Write '1' to enable interrupt for event RAMACCERR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW FLASHACCERR			Write '1' to enable interrupt for event FLASHACCERR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW PERIPHACCERR			Write '1' to enable interrupt for event PERIPHACCERR
		Set	1	Enable
		Disabled	0	Read: Disabled

6.15.9.9 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW RAMACCERR			Write '1' to disable interrupt for event RAMACCERR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW FLASHACCERR			Write '1' to disable interrupt for event FLASHACCERR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW PERIPHACCERR			Write '1' to disable interrupt for event PERIPHACCERR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.15.9.10 CAP

Address offset: 0x400

Show implemented features for the current device

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000001		0 0 0 0 0 0 0	$\begin{smallmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 $
ID Acce Field			
A R TZM			Show ARM TrustZone status
	NotAvailable	0	ARM TrustZone support not available
	Enabled	1	ARM TrustZone support is available

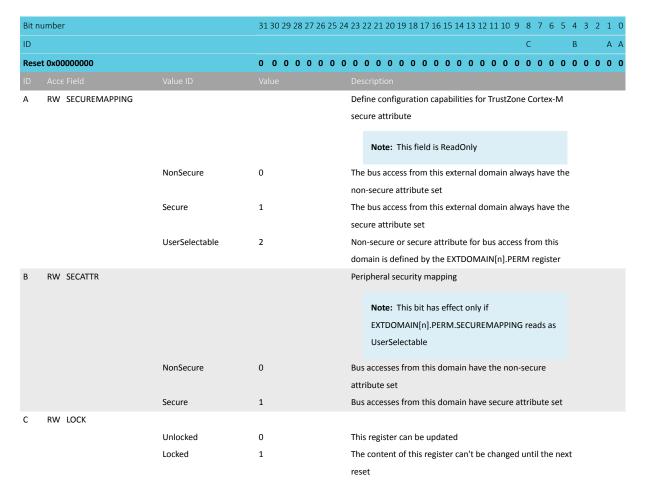


6.15.9.11 EXTDOMAIN[n].PERM (n=0..0)

Address offset: $0x440 + (n \times 0x4)$

Access for bus access generated from the external domain n

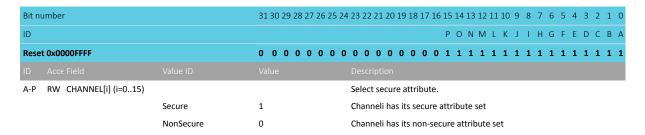
List capabilities of the external domain n



6.15.9.12 DPPI[n].PERM (n=0..0)

Address offset: $0x480 + (n \times 0x8)$

Select between secure and non-secure attribute for the DPPI channels.



6.15.9.13 DPPI[n].LOCK (n=0..0)

Address offset: $0x484 + (n \times 0x8)$

Prevent further modification of the corresponding PERM register



Bit number		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW LOCK			
	Locked	1	DPPI[n].PERM register can't be changed until next reset
	Unlocked	0	DPPI[n].PERM register content can be changed

6.15.9.14 GPIOPORT[n].PERM (n=0..0) (Retained)

Address offset: $0x4C0 + (n \times 0x8)$ This register is a retained register

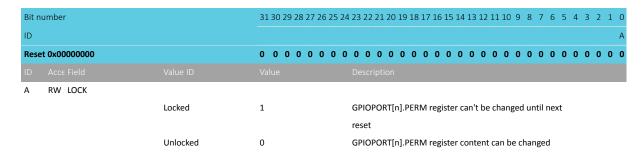
Select between secure and non-secure attribute for pins 0 to 31 of port n.

Bit n	umber		31	30	29	28 2	27 2	26 2	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11 1	0 9	8	7	6	5	4	3	2	1 0
ID			f	е	d	С	b	а	Z	Υ	Х	W	٧	U	Т	S	R	Q	Р	0	N	M	L	()	- 1	Н	G	F	Ε	D	С	ВА
Rese	t OxFFFFFFF		1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1 :	L 1	. 1	1	1	1	1	1	1	1 1
ID																																
A-f	RW PIN[i] (i=031)										Sel	lect	t se	cur	e a	ttril	but	e a	ttri	but	e fo	or P	IN i									
		Secure	1								Pin	nih	nas	its	sec	ure	att	rib	ute	se	t											
		NonSecure	0								Pin	nih	nas	its	noı	n-se	cui	re a	ittr	ibu	te s	et										

6.15.9.15 GPIOPORT[n].LOCK (n=0..0)

Address offset: $0x4C4 + (n \times 0x8)$

Prevent further modification of the corresponding PERM register



6.15.9.16 FLASHNSC[n].REGION (n=0..1)

Address offset: $0x500 + (n \times 0x8)$

Define which flash region can contain the non-secure callable (NSC) region n

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW REGION			Region number
В	RW LOCK			
		Unlocked	0	This register can be updated
		Locked	1	The content of this register can't be changed until the next
				reset



6.15.9.17 FLASHNSC[n].SIZE (n=0..1)

Address offset: $0x504 + (n \times 0x8)$

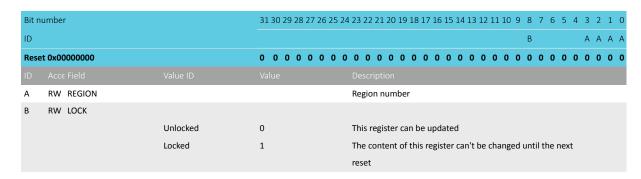
Define the size of the non-secure callable (NSC) region n

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			в ааа
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW SIZE			Size of the non-secure callable (NSC) region n
	Disabled	0	The region n is not defined as a non-secure callable region.
			Normal security attributes (secure or non-secure) are
			enforced.
	32	1	The region n is defined as non-secure callable with a 32-
			byte size
	64	2	The region n is defined as non-secure callable with a 64-
			byte size
	128	3	The region n is defined as non-secure callable with a 128-
			byte size
	256	4	The region n is defined as non-secure callable with a 256-
			byte size
	512	5	The region n is defined as non-secure callable with a 512-
			byte size
	1024	6	The region n is defined as non-secure callable with a 1024-
			byte size
	2048	7	The region n is defined as non-secure callable with a 2048-
			byte size
	4096	8	The region n is defined as non-secure callable with a 4096-
			byte size
B RW LOCK			
	Unlocked	0	This register can be updated
	Locked	1	The content of this register can't be changed until the next
			reset

6.15.9.18 RAMNSC[n].REGION (n=0..1)

Address offset: $0x540 + (n \times 0x8)$

Define which RAM region can contain the non-secure callable (NSC) region n



6.15.9.19 RAMNSC[n].SIZE (n=0..1)

Address offset: $0x544 + (n \times 0x8)$

Define the size of the non-secure callable (NSC) region n



Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID		В ААА
Reset 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A RW SIZE		Size of the non-secure callable (NSC) region n
	Disabled	0 The region n is not defined as a non-secure callable region.
		Normal security attributes (secure or non-secure) are
		enforced.
	32	1 The region n is defined as non-secure callable with a 32-
	byte size	
	64	2 The region n is defined as non-secure callable with a 64-
		byte size
	128	The region n is defined as non-secure callable with a 128-
		byte size
	256	4 The region n is defined as non-secure callable with a 256-
		byte size
	512	5 The region n is defined as non-secure callable with a 512-
		byte size
	1024	6 The region n is defined as non-secure callable with a 1024-
		byte size
	2048	7 The region n is defined as non-secure callable with a 2048-
		byte size
	4096	8 The region n is defined as non-secure callable with a 4096-
		byte size
B RW LOCK		
	Unlocked	0 This register can be updated
	Locked	1 The content of this register can't be changed until the next
		reset

6.15.9.20 FLASHREGION[n].PERM (n=0..31)

Address offset: $0x600 + (n \times 0x4)$ Access permissions for flash region n

Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			
ID				E D C B A			
Res	et 0x00000017		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			
ID							
Α	RW EXECUTE			Configure instruction fetch permissions from flash region n			
		Enable	1	Allow instruction fetches from flash region n			
		Disable	0	Block instruction fetches from flash region n			
В	RW WRITE			Configure write permission for flash region n			
		Enable	1	Allow write operation to region n			
		Disable	0	Block write operation to region n			
С	RW READ			Configure read permissions for flash region n			
		Enable	1	Allow read operation from flash region n			
		Disable	0	Block read operation from flash region n			
D	RW SECATTR			Security attribute for flash region n			
		Non_Secure	0	Flash region n security attribute is non-secure			
		Secure	1	Flash region n security attribute is secure			
Е	RW LOCK						
		Unlocked	0	This register can be updated			



ID E D Reset 0x00000017 O 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID	
ID E D	
ID E D	0 1 1 1
S130 29 20 27 20 23 24 23 22 21 20 19 10 17 10 13 14 15 12 11 10 9 0 7 0 3 4	СВА
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	

6.15.9.21 RAMREGION[n].PERM (n=0..31)

Address offset: $0x700 + (n \times 0x4)$ Access permissions for RAM region n

Bit	number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				E D C B A
Res	et 0x00000017		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW EXECUTE			Configure instruction fetch permissions from RAM region n
		Enable	1	Allow instruction fetches from RAM region n
		Disable	0	Block instruction fetches from RAM region n
В	RW WRITE			Configure write permission for RAM region n
		Enable	1	Allow write operation to RAM region n
		Disable	0	Block write operation to RAM region n
С	RW READ			Configure read permissions for RAM region n
		Enable	1	Allow read operation from RAM region n
		Disable	0	Block read operation from RAM region n
D	RW SECATTR			Security attribute for RAM region n
		Non_Secure	0	RAM region n security attribute is non-secure
		Secure	1	RAM region n security attribute is secure
Ε	RW LOCK			
		Unlocked	0	This register can be updated
		Locked	1	The content of this register can't be changed until the next
				reset

6.15.9.22 PERIPHID[n].PERM (n=0..66)

Address offset: $0x800 + (n \times 0x4)$

List capabilities and access permissions for the peripheral with ID n

Reset values are unique per peripheral instantation. Please refer to the peripheral instantiation table. Entries not listed in the instantiation table are undefined.

Bit number		31 30 29 28 27	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID		F	E DCBBA.
Reset 0x00000012		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
A R SECUREMAPP	ING		Define configuration capabilities for TrustZone Cortex-M secure attribute
			Note: This field is read only
	NonSecure	0	This peripheral is always accessible as a non-secure
			peripheral
	Secure	1	This peripheral is always accessible as a secure peripheral



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			F	E DCBBA.
Rese	t 0x00000012		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		UserSelectable	2	Non-secure or secure attribute for this peripheral is defined by the PERIPHID[n].PERM register
		Split	3	This peripheral implements the split security mechanism.
		Spiit	3	Non-secure or secure attribute for this peripheral is defined
				by the PERIPHID[n].PERM register.
В	R DMA			Indicate if the peripheral has DMA capabilities and if DMA
				transfer can be assigned to a different security attribute
				than the peripheral itself
		NoDMA	0	Peripheral has no DMA capability
		NoSeparateAttribute	1	Peripheral has DMA and DMA transfers always have the
		,		same security attribute as assigned to the peripheral
		SeparateAttribute	2	Peripheral has DMA and DMA transfers can have a different
		·		security attribute than the one assigned to the peripheral
С	RW SECATT	R		Peripheral security mapping
				Note: This bit has effect only if
				PERIPHID[n].PERM.SECUREMAPPING reads as
				UserSelectable or Split
		Secure	1	Peripheral is mapped in secure peripheral address space
		NonSecure	0	If SECUREMAPPING == UserSelectable: Peripheral is
				mapped in non-secure peripheral address space.
				If SECUREMAPPING == Split: Peripheral is mapped in non-
				secure and secure peripheral address space.
D	RW DMASE	С		Security attribution for the DMA transfer
				Note: This bit has effect only if
				PERIPHID[n].PERM.SECATTR is set to secure
		Secure	1	DMA transfers initiated by this peripheral have the secure
				attribute set
		NonSecure	0	DMA transfers initiated by this peripheral have the non-
				secure attribute set
E	RW LOCK			
		Unlocked	0	This register can be updated
		Locked	1	The content of this register can't be changed until the next reset
F	R PRESEN	Т		Indicate if a peripheral is present with ID n
		N . D	•	
		NotPresent	0	Peripheral is not present

6.16 TIMER — Timer/counter

The TIMER can operate in two modes: timer and counter.



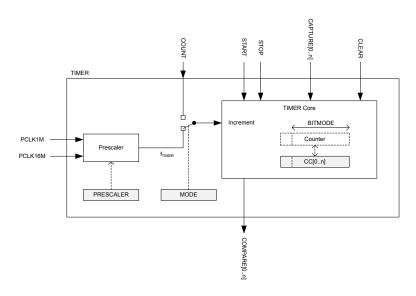


Figure 86: Block schematic for timer/counter

The timer/counter runs on the high-frequency clock source (HFCLK) and includes a four-bit (1/2X) prescaler that can divide the timer input clock from the HFCLK controller. Clock source selection between PCLK16M and PCLK1M is automatic according to TIMER base frequency set by the prescaler. The TIMER base frequency is always given as 16 MHz divided by the prescaler value.

The PPI system allows a TIMER event to trigger a task of any other system peripheral of the device. The PPI system also enables the TIMER task/event features to generate periodic output and PWM signals to any GPIO. The number of input/outputs used at the same time is limited by the number of GPIOTE channels.

The TIMER can operate in two modes, Timer mode and Counter mode. In both modes, the TIMER is started by triggering the START task, and stopped by triggering the STOP task. After the timer is stopped the timer can resume timing/counting by triggering the START task again. When timing/counting is resumed, the timer will continue from the value it had prior to being stopped.

In Timer mode, the TIMER's internal Counter register is incremented by one for every tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 281. The timer frequency is derived from PCLK16M as shown below, using the values specified in the PRESCALER register:

```
f_{TIMER} = 16 \text{ MHz} / (2^{PRESCALER})
```

When $f_{TIMER} \le 1$ MHz the TIMER will use PCLK1M instead of PCLK16M for reduced power consumption.

In counter mode, the TIMER's internal Counter register is incremented by one each time the COUNT task is triggered, that is, the timer frequency and the prescaler are not utilized in counter mode. Similarly, the COUNT task has no effect in Timer mode.

The TIMER's maximum value is configured by changing the bit-width of the timer in the BITMODE on page 288 register.

PRESCALER on page 289 and the BITMODE on page 288 must only be updated when the timer is stopped. If these registers are updated while the TIMER is started then this may result in unpredictable behavior.

When the timer is incremented beyond its maximum value the Counter register will overflow and the TIMER will automatically start over from zero.



The Counter register can be cleared, that is, its internal value set to zero explicitly, by triggering the CLEAR task

The TIMER implements multiple capture/compare registers.

Independent of prescaler setting the accuracy of the TIMER is equivalent to one tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 281.

6.16.1 Capture

The TIMER implements one capture task for every available capture/compare register.

Every time the CAPTURE[n] task is triggered, the Counter value is copied to the CC[n] register.

6.16.2 Compare

The TIMER implements one COMPARE event for every available capture/compare register.

A COMPARE event is generated when the Counter is incremented and then becomes equal to the value specified in one of the capture compare registers. When the Counter value becomes equal to the value specified in a capture compare register CC[n], the corresponding compare event COMPARE[n] is generated.

BITMODE on page 288 specifies how many bits of the Counter register and the capture/compare register that are used when the comparison is performed. Other bits will be ignored.

6.16.3 Task delays

After the TIMER is started, the CLEAR task, COUNT task and the STOP task will guarantee to take effect within one clock cycle of the PCLK16M.

6.16.4 Task priority

If the START task and the STOP task are triggered at the same time, that is, within the same period of PCLK16M, the STOP task will be prioritized.

6.16.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000F000	TIMER	TIMER0 : S	US	NA	Timer 0	
0x4000F000	HIVIEN	TIMER0 : NS	03	IVA	Timer o	
0x50010000	TIMER	TIMER1: S	US	NA	Timer 1	
0x40010000	THVILIX	TIMER1 : NS	03	IVA	Timer 1	
0x50011000	TIMER	TIMER2 : S	HS	NA	Timer 2	
0x40011000		TIMER2 : NS	US		Tilliel Z	

Table 82: Instances

Register	Offset	Security	Description	
TASKS_START	0x000		Start Timer	
TASKS_STOP	0x004		Stop Timer	
TASKS_COUNT	0x008		Increment Timer (Counter mode only)	
TASKS_CLEAR	0x00C		Clear time	
TASKS_SHUTDOWN	0x010		Shut down timer	Deprecated
TASKS_CAPTURE[0]	0x040		Capture Timer value to CC[0] register	
TASKS_CAPTURE[1]	0x044		Capture Timer value to CC[1] register	
TASKS_CAPTURE[2]	0x048		Capture Timer value to CC[2] register	



TASSE_CAPTURE[3]	Register	Offset	Security	Description	
TASKS_CAPTURE[3]	TASKS_CAPTURE[3]	0x04C		Capture Timer value to CC[3] register	
SUBSCRIBE_START 0x080 Subscribe configuration for task START SUBSCRIBE_STOP 0x084 Subscribe configuration for task STOP SUBSCRIBE_CEAR 0x086 Subscribe configuration for task COUNT SUBSCRIBE_CEAR 0x08C Subscribe configuration for task CAPTURE SUBSCRIBE_SHUTDOWN 0x090 Subscribe configuration for task SHUTDOWN Deprecated SUBSCRIBE_CAPTURE[1] 0x0C4 Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] 0x0C8 SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[3] 0x0C SUBSCRIBE_CAPTURE[3] 0x0D Subscribe configuration for task CAPTURE[3] 0x0D Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[3] 0x1D4 Subscribe configuration for task CAPTURE[3] 0x1D4	TASKS_CAPTURE[4]	0x050		Capture Timer value to CC[4] register	
SUBSCRIBE_STOP Divided Subscribe configuration for task STOP SUBSCRIBE_CAUNT Divided Subscribe configuration for task COUNT SUBSCRIBE_CAPTURE[0] Divided Subscribe configuration for task CAPTURE[0] SUBSCRIBE_CAPTURE[1] Divided Subscribe configuration for task CAPTURE[0] SUBSCRIBE_CAPTURE[1] Divided Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] Divided Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] Divided Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[3] Divided Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[3] Divided Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] Divided Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[6] Divided Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[1] Divided Compare event on CC[0] match EVENTS_COMPARE[1] Divided Compare event on CC[1] match EVENTS_COMPARE[3] Divided Compare event on CC[3] match EVENTS_COMPARE[3] Divided Compare event on CC[3] match EVENTS_COMPARE[3] Divided Compare event on CC[4] match EVENTS_COMPARE[3] Divided Compare event on CC[6] match EVENTS_COMPARE[4] Divided Compare event on CC[6] match EVENTS_COMPARE[6] Divided Compare event on CC[6] match EVENTS_COMPARE[1] Divided Compare event on CC[6] match EVENTS_COMPARE[6] Divided Compare event on CC	TASKS_CAPTURE[5]	0x054		Capture Timer value to CC[5] register	
SUBSCRIBE_COUNT 0x088 Subscribe configuration for task COUNT SUBSCRIBE_CLEAR 0x08C Subscribe configuration for task SHUTDOWN Deprecated SUBSCRIBE_CAPTURE[0] 0x00C Subscribe configuration for task SHUTDOWN Deprecated SUBSCRIBE_CAPTURE[1] 0x00C Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] SUBSCRIBE_CAPTURE[3] 0x00C Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[3] SUBSCRIBE_CAPTURE[3] 0x00D Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x00D SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[3] 0x0D4 SUBSCRIBE_CAPTURE[3] 0x0D4 Subscribe configuration for task CAPTURE[5] 0x0D4 EVENTS_COMPARE[6] 0x140 Compare event on CC[0] match 0x140 0x144 0x14	SUBSCRIBE_START	0x080		Subscribe configuration for task START	
SUBSCRIBE_CLEAR	SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP	
SUBSCRIBE_SHUTDOWN 0x090 Subscribe configuration for task SHUTDOWN Deprecated SUBSCRIBE_CAPTURE[0] 0x0C0 Subscribe configuration for task CAPTURE[0] SUBSCRIBE_CAPTURE[1] 0x0C4 Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] 0x0C8 Subscribe configuration for task CAPTURE[2] SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[6] SUBSCRIBE_CAPTURE[6] 0x140 Compare event on CC[0] match EVENTS_COMPARE[0] 0x144 Compare event on CC[1] match EVENTS_COMPARE[1] 0x144 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[4] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[6] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x154 Compare event cOMPARE[6] FUBLISH_COMPARE[6] 0x154 Publish configuration for event COMPARE[6] FUBLISH_COMPARE[6] 0x164 Publish configuration for event COMPARE[1] FUBLISH_COMPARE[7] 0x168 Publish configuration for event COMPARE[8] FUBLISH_COMPARE[8] 0x104 Publish configuration for event COMPARE[9] FUBLISH_COMPARE[8] 0x104 Publish configuration for event COMPARE[9] FUBLISH_COMPARE[9] 0x104 Publish configuration for event COMPARE[9] FUBLISH_COMPARE[9] 0x104 Publish configuration for event COM	SUBSCRIBE_COUNT	0x088		Subscribe configuration for task COUNT	
SUBSCRIBE_CAPTURE[0] 0x0C4 Subscribe configuration for task CAPTURE[0] SUBSCRIBE_CAPTURE[1] 0x0C4 Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] 0x0C8 Subscribe configuration for task CAPTURE[2] SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[1] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[2] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[6] 0x154 Compare event on CC[5] match EVENTS_COMPARE[1] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[1] PUBLISH_COMPARE[4] 0x1C0 Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1C0 Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1C0 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register 0 CC[1] 0x544 Capture/Compare register 0 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SUBSCRIBE_CLEAR	0x08C		Subscribe configuration for task CLEAR	
SUBSCRIBE_CAPTURE[1] 0x0C4 Subscribe configuration for task CAPTURE[1] SUBSCRIBE_CAPTURE[2] 0x0C8 Subscribe configuration for task CAPTURE[2] SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[1] 0x144 Compare event on CC[2] match EVENTS_COMPARE[2] 0x148 Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[4] 0x150 Compare event on CC[5] match EVENTS_COMPARE[4] 0x150 Compare event on CC[5] match PUBLISH_COMPARE[6] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[2] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[6] SHORTS 0x304 Enable interrupt INTENSET 0x304 Enable interrupt INTEN	SUBSCRIBE_SHUTDOWN	0x090		Subscribe configuration for task SHUTDOWN	Deprecated
SUBSCRIBE_CAPTURE[2] 0x0C8 Subscribe configuration for task CAPTURE[2] SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[2] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x150 Compare event on CC[6] match EVENTS_COMPARE[6] 0x154 Publish configuration for event COMPARE[7] PUBLISH_COMPARE[1] 0x155 Publish configuration for event COMPARE[7] PUBLISH_COMPARE[1] 0x155 Publish configuration for event COMPARE[8] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable interrupt INTENSET 0x305 Disable interrupt INTENSET 0x306 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[7] 0x544 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[1] 0x544 Capture/Compare register 2 CC[3] 0x540 Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 3	SUBSCRIBE_CAPTURE[0]	0x0C0		Subscribe configuration for task CAPTURE[0]	
SUBSCRIBE_CAPTURE[3] 0x0CC Subscribe configuration for task CAPTURE[3] SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[1] 0x14C Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[3] match EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match EVENTS_COMPARE[6] 0x150 Compare event on CC[6] match EVENTS_COMPARE[1] 0x150 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C0 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[1] 0x1C0 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[3] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[3] 0x1D0 Publish configuration for event COMPARE[3] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[6] SHORTS 0x200 Shortcuts between local event and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 3	SUBSCRIBE_CAPTURE[1]	0x0C4		Subscribe configuration for task CAPTURE[1]	
SUBSCRIBE_CAPTURE[4] 0x0D0 Subscribe configuration for task CAPTURE[4] SUBSCRIBE_CAPTURE[5] 0x0D4 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[1] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[3] 0x14C Compare event on CC[4] match EVENTS_COMPARE[4] 0x150 Compare event on CC[5] match EVENTS_COMPARE[5] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x160 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x164 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[1] 0x164 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x16C Publish configuration for event COMPARE[3] PUBLISH_COMPARE[3] 0x16C Publish configuration for event COMPARE[4] PUBLISH_COMPARE[3] 0x10D Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[6] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable interrupt INTENSET 0x308 Disable interrupt INTENSET 0x504 Timer mode selection BITMODE 0x504 Timer mode selection BITMODE 0x504 Timer mode selection BITMODE 0x504 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register 0 CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SUBSCRIBE_CAPTURE[2]	0x0C8		Subscribe configuration for task CAPTURE[2]	
SUBSCRIBE_CAPTURE[5] 0x004 Subscribe configuration for task CAPTURE[5] EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[2] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[5] match EVENTS_COMPARE[5] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SUBSCRIBE_CAPTURE[3]	0x0CC		Subscribe configuration for task CAPTURE[3]	
EVENTS_COMPARE[0] 0x140 Compare event on CC[0] match EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[2] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[6] match EVENTS_COMPARE[6] 0x154 Compare event on CC[6] match EVENTS_COMPARE[7] 0x154 Compare event on CC[6] match PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[4] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSCLR 0x308 Disable interrupt INTENSCLR 0x504 Timer mode selection BITMODE 0x504 Timer mode selection BITMODE 0x504 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register 0 CC[0] 0x540 Capture/Compare register 1 CC[0] 0x544 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SUBSCRIBE_CAPTURE[4]	0x0D0		Subscribe configuration for task CAPTURE[4]	
EVENTS_COMPARE[1] 0x144 Compare event on CC[1] match EVENTS_COMPARE[2] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match EVENTS_COMPARE[6] 0x154 Compare event on CC[5] match PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x504 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SUBSCRIBE_CAPTURE[5]	0x0D4		Subscribe configuration for task CAPTURE[5]	
EVENTS_COMPARE[2] 0x148 Compare event on CC[2] match EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 4	EVENTS_COMPARE[0]	0x140		Compare event on CC[0] match	
EVENTS_COMPARE[3] 0x14C Compare event on CC[3] match EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x548 Capture/Compare register 2 CC[3] 0x54C <td>EVENTS_COMPARE[1]</td> <td>0x144</td> <td></td> <td>Compare event on CC[1] match</td> <td></td>	EVENTS_COMPARE[1]	0x144		Compare event on CC[1] match	
EVENTS_COMPARE[4] 0x150 Compare event on CC[4] match EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	EVENTS_COMPARE[2]	0x148		Compare event on CC[2] match	
EVENTS_COMPARE[5] 0x154 Compare event on CC[5] match PUBLISH_COMPARE[0] 0x1C0 Publish configuration for event COMPARE[0] PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	EVENTS_COMPARE[3]	0x14C		Compare event on CC[3] match	
PUBLISH_COMPARE[0]	EVENTS_COMPARE[4]	0x150		Compare event on CC[4] match	
PUBLISH_COMPARE[1] 0x1C4 Publish configuration for event COMPARE[1] PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 2 CC[2] 0x548 Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	EVENTS_COMPARE[5]	0x154		Compare event on CC[5] match	
PUBLISH_COMPARE[2] 0x1C8 Publish configuration for event COMPARE[2] PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x504 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	PUBLISH_COMPARE[0]	0x1C0		Publish configuration for event COMPARE[0]	
PUBLISH_COMPARE[3] 0x1CC Publish configuration for event COMPARE[3] PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 4	PUBLISH_COMPARE[1]	0x1C4		Publish configuration for event COMPARE[1]	
PUBLISH_COMPARE[4] 0x1D0 Publish configuration for event COMPARE[4] PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 4	PUBLISH_COMPARE[2]	0x1C8		Publish configuration for event COMPARE[2]	
PUBLISH_COMPARE[5] 0x1D4 Publish configuration for event COMPARE[5] SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	PUBLISH_COMPARE[3]	0x1CC		Publish configuration for event COMPARE[3]	
SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	PUBLISH_COMPARE[4]	0x1D0		Publish configuration for event COMPARE[4]	
INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	PUBLISH_COMPARE[5]	0x1D4		Publish configuration for event COMPARE[5]	
INTENCLR 0x308 Disable interrupt MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	SHORTS	0x200		Shortcuts between local events and tasks	
MODE 0x504 Timer mode selection BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	INTENSET	0x304		Enable interrupt	
BITMODE 0x508 Configure the number of bits used by the TIMER PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	INTENCLR	0x308		Disable interrupt	
PRESCALER 0x510 Timer prescaler register CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	MODE	0x504		Timer mode selection	
CC[0] 0x540 Capture/Compare register 0 CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	BITMODE	0x508		Configure the number of bits used by the TIMER	
CC[1] 0x544 Capture/Compare register 1 CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	PRESCALER	0x510		Timer prescaler register	
CC[2] 0x548 Capture/Compare register 2 CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	CC[0]	0x540		Capture/Compare register 0	
CC[3] 0x54C Capture/Compare register 3 CC[4] 0x550 Capture/Compare register 4	CC[1]	0x544		Capture/Compare register 1	
CC[4] 0x550 Capture/Compare register 4	CC[2]	0x548		Capture/Compare register 2	
	CC[3]	0x54C		Capture/Compare register 3	
CC[5] 0x554 Capture/Compare register 5	CC[4]	0x550		Capture/Compare register 4	
	CC[5]	0x554		Capture/Compare register 5	

Table 83: Register overview

6.16.5.1 TASKS_START

Address offset: 0x000

Start Timer

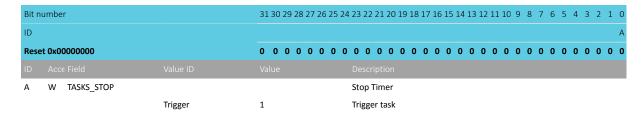
Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_START			Start Timer
		Trigger	1	Trigger task



6.16.5.2 TASKS_STOP

Address offset: 0x004

Stop Timer



6.16.5.3 TASKS COUNT

Address offset: 0x008

Increment Timer (Counter mode only)

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_COUNT			Increment Timer (Counter mode only)
		Trigger	1	Trigger task

6.16.5.4 TASKS_CLEAR

Address offset: 0x00C

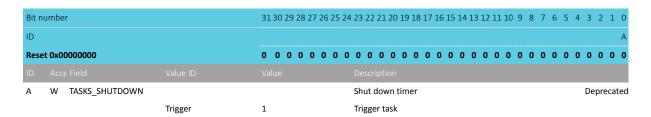
Clear time

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x0000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_CLEAR			Clear time
		Trigger	1	Trigger task

6.16.5.5 TASKS_SHUTDOWN (Deprecated)

Address offset: 0x010

Shut down timer

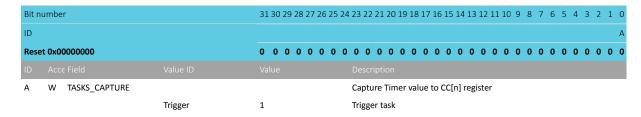


6.16.5.6 TASKS_CAPTURE[n] (n=0..5)

Address offset: $0x040 + (n \times 0x4)$



Capture Timer value to CC[n] register



6.16.5.7 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.16.5.8 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID			В	ААА	Α
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0
ID					
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to	
В	RW EN				
		Disabled	0	Disable subscription	
		Enabled	1	Enable subscription	

6.16.5.9 SUBSCRIBE_COUNT

Address offset: 0x088

Subscribe configuration for task COUNT

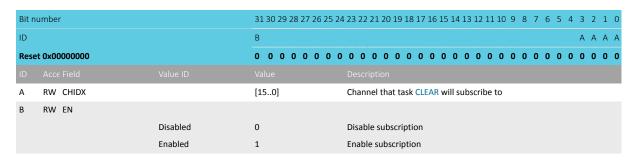
Bit r	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task COUNT will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription



6.16.5.10 SUBSCRIBE_CLEAR

Address offset: 0x08C

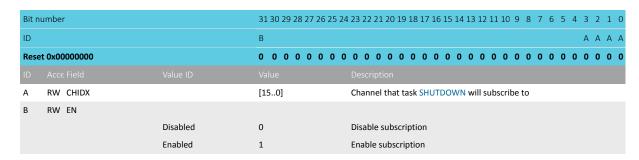
Subscribe configuration for task CLEAR



6.16.5.11 SUBSCRIBE_SHUTDOWN (Deprecated)

Address offset: 0x090

Subscribe configuration for task SHUTDOWN



6.16.5.12 SUBSCRIBE CAPTURE[n] (n=0..5)

Address offset: $0x0C0 + (n \times 0x4)$

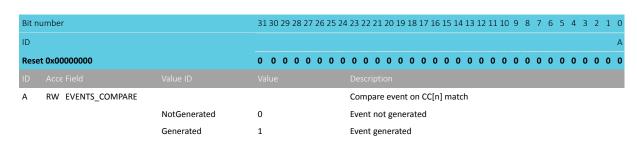
Subscribe configuration for task CAPTURE[n]

Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				
Α	RW CHIDX		[150]	Channel that task CAPTURE[n] will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.16.5.13 EVENTS_COMPARE[n] (n=0..5)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

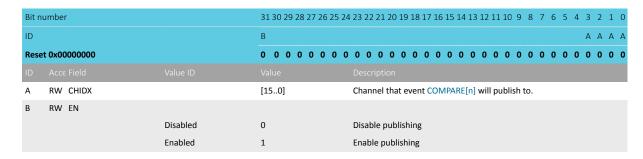




6.16.5.14 PUBLISH_COMPARE[n] (n=0..5)

Address offset: $0x1C0 + (n \times 0x4)$

Publish configuration for event COMPARE[n]



6.16.5.15 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit number	31 30 29 28 27	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		L K J I H G F E D C B A
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value		Description
A-F RW COMPARE[i]_CLEAR		Shortcut between event COMPARE[i] and task CLEAR
(i=05)		
Disabl	ed 0	Disable shortcut
Enable	ed 1	Enable shortcut
G-L RW COMPARE[i]_STOP		Shortcut between event COMPARE[i] and task STOP
(i=05)		
Disabl	ed 0	Disable shortcut
Enable	ed 1	Enable shortcut

6.16.5.16 INTENSET

Address offset: 0x304

Enable interrupt



Bit number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		F E D C B A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A-F RW COMPARE[i] (i=05)		Write '1' to enable interrupt for event COMPARE[i]
Set	1	Enable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled

6.16.5.17 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		FEDCBA
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A-F RW COMPARE[i] (i=05)		Write '1' to disable interrupt for event COMPARE[i]
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled

6.16.5.18 MODE

Address offset: 0x504
Timer mode selection

Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5	4 3 2 1 0
ID					АА
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0
ID					
Α	RW MODE			Timer mode	
		Timer	0	Select Timer mode	
		Counter	1	Select Counter mode	Deprecated

6.16.5.19 BITMODE

Address offset: 0x508

Configure the number of bits used by the TIMER

Bit number			31 30 29 28 27	26 25 2	4 23 22	21 2	0 19	18 1	7 16	5 15	14 1	.3 12	2 11	10 9	8	7	6	5	4	3	2	1 0
ID																						А А
Reset 0x00000000			0 0 0 0 0	0 0 0	0 0	0 (0 0	0 (0	0	0	0 0	0	0 0	0	0	0	0	0	0	0	0 0
ID																						
Α	RW BITMODE					Timer bit width																
		16Bit	0	0				16 bit timer bit width														
		08Bit	1		8 bit	8 bit timer bit width																
		24Bit	2		24 bit	bit timer bit width 4 bit timer bit width																
		32Bit	3		32 bit	time	er bit	widt	th													





6.16.5.20 PRESCALER

Address offset: 0x510

Timer prescaler register

Bit n	umber	313	0 29	28	27	26 2	25 2	24 2	3 2	2 2	1 20	0 19	18	17	16	15	14	13 :	12 1	1 10	9	8	7	6	5	4	3 2	2 1	1 0
ID																											A A	A A	4 А
Rese	t 0x00000004	0	0 0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 1	۱ (0 0
ID																													
Α	RW PRESCALER	[09	9]					P	res	cale	er v	alu	9																

6.16.5.21 CC[n] (n=0..5)

Address offset: $0x540 + (n \times 0x4)$ Capture/Compare register n

			Only the number of bits indicated by BITMODE will be used
Α	RW CC		Capture/Compare value
Rese	et 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit n	umber	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

by the TIMER.

6.16.6 Electrical specification

$6.17 \text{ TWIM} - I^2 \text{C}$ compatible two-wire interface master with EasyDMA

TWI master with EasyDMA (TWIM) is a two-wire half-duplex master which can communicate with multiple slave devices connected to the same bus

Listed here are the main features for TWIM:

- I²C compatible
- 100 kbps, 250 kbps, or 400 kbps
- Support for clock stretching (non I²C compliant)
- EasyDMA

The two-wire interface can communicate with a bi-directional wired-AND bus with two lines (SCL, SDA). The protocol makes it possible to interconnect up to 127 individually addressable devices. TWIM is not compatible with CBUS.

The GPIOs used for each two-wire interface line can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.



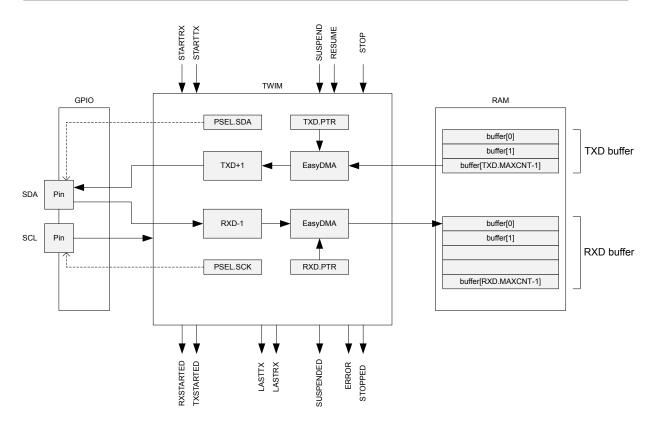


Figure 87: TWI master with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see A typical TWI setup comprising one master and three slaves on page 290. This TWIM is only able to operate as a single master on the TWI bus. Multi-master bus configuration is not supported.

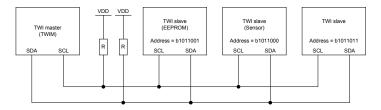


Figure 88: A typical TWI setup comprising one master and three slaves

This TWI master supports clock stretching performed by the slaves. Note that the SCK pulse following a stretched clock cycle may be shorter than specified by the I2C specification.

The TWI master is started by triggering the STARTTX or STARTRX tasks, and stopped by triggering the STOP task. The TWI master will generate a STOPPED event when it has stopped following a STOP task. The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.

After the TWI master is started, the STARTTX task or the STARTRX task should not be triggered again before the TWI master has stopped, i.e. following a LASTRX, LASTTX or STOPPED event.

If a NACK is clocked in from the slave, the TWI master will generate an ERROR event.

6.17.1 EasyDMA

The TWI master implements EasyDMA for reading and writing to and from the RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

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The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.

6.17.2 Master write sequence

A TWI master write sequence is started by triggering the STARTTX task. After the STARTTX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1).

The address must match the address of the slave device that the master wants to write to. The READ/ WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) generated by the slave.

After receiving the ACK bit, the TWI master will clock out the data bytes found in the transmit buffer located in RAM at the address specified in the TXD.PTR register. Each byte clocked out from the master will be followed by an ACK/NACK bit clocked in from the slave.

A typical TWI master write sequence is illustrated in TWI master writing data to a slave on page 291. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect; this event can be used to synchronize the software.

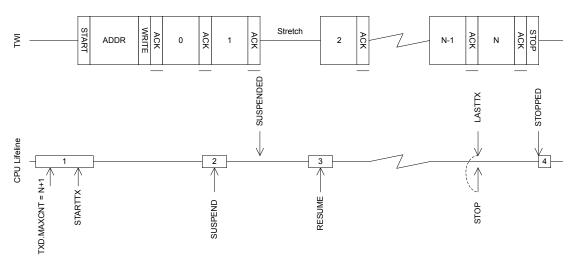


Figure 89: TWI master writing data to a slave

The TWI master will generate a LASTTX event when it starts to transmit the last byte, this is illustrated in TWI master writing data to a slave on page 291

The TWI master is stopped by triggering the STOP task, this task should be triggered during the transmission of the last byte to secure that the TWI will stop as fast as possible after sending the last byte. It is safe to use the shortcut between LASTTX and STOP to accomplish this.

Note that the TWI master does not stop by itself when the whole RAM buffer has been sent, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.

6.17.3 Master read sequence

A TWI master read sequence is started by triggering the STARTRX task. After the STARTRX task has been triggered the TWI master will generate a start condition on the TWI bus, followed by clocking out the



address and the READ/WRITE bit set to 1 (WRITE = 0, READ = 1). The address must match the address of the slave device that the master wants to read from. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK = 1) generated by the slave.

After having sent the ACK bit the TWI slave will send data to the master using the clock generated by the master.

Data received will be stored in RAM at the address specified in the RXD.PTR register. The TWI master will generate an ACK after all but the last byte received from the slave. The TWI master will generate a NACK after the last byte received to indicate that the read sequence shall stop.

A typical TWI master read sequence is illustrated in The TWI master reading data from a slave on page 292. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect; this event can be used to synchronize the software.

The TWI master will generate a LASTRX event when it is ready to receive the last byte, this is illustrated in The TWI master reading data from a slave on page 292. If RXD.MAXCNT > 1 the LASTRX event is generated after sending the ACK of the previously received byte. If RXD.MAXCNT = 1 the LASTRX event is generated after receiving the ACK following the address and READ bit.

The TWI master is stopped by triggering the STOP task, this task must be triggered before the NACK bit is supposed to be transmitted. The STOP task can be triggered at any time during the reception of the last byte. It is safe to use the shortcut between LASTRX and STOP to accomplish this.

Note that the TWI master does not stop by itself when the RAM buffer is full, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

The TWI master cannot get stopped while it is suspended, so the STOP task has to be issued after the TWI master has been resumed.

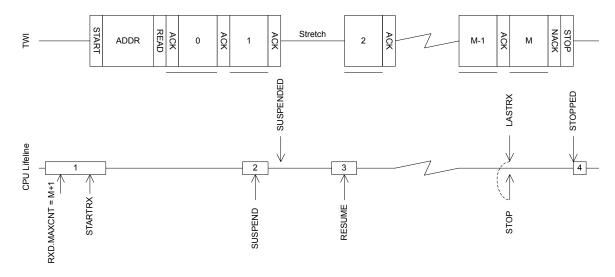


Figure 90: The TWI master reading data from a slave

6.17.4 Master repeated start sequence

A typical repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave. This example uses shortcuts to perform the simplest type of repeated start sequence, i.e. one write followed by one read. The same approach can be used to perform a repeated start sequence where the sequence is read followed by write.



The figure A repeated start sequence, where the TWI master writes two bytes followed by reading 4 bytes from the slave on page 293 illustrates this:

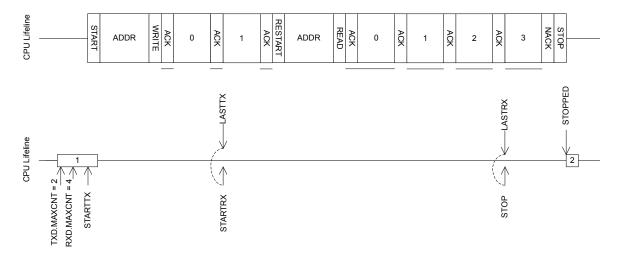


Figure 91: A repeated start sequence, where the TWI master writes two bytes followed by reading 4 bytes from the slave

If a more complex repeated start sequence is needed and the TWI firmware drive is serviced in a low priority interrupt it may be necessary to use the SUSPEND task and SUSPENDED event to guarantee that the correct tasks are generated at the correct time. This is illustrated in A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts on page 293.

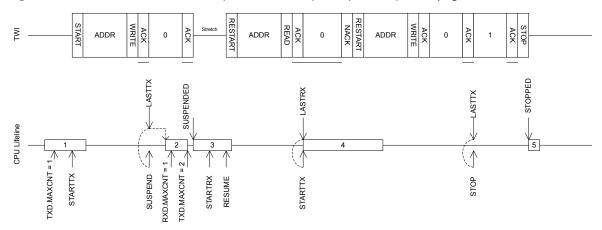


Figure 92: A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts

6.17.5 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.17.6 Master mode pin configuration

The SCL and SDA signals associated with the TWI master are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI master is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins

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will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL, PSEL.SDA must only be configured when the TWI master is disabled.

To secure correct signal levels on the pins used by the TWI master when the system is in OFF mode, and when the TWI master is disabled, these pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 294.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI master signal	TWI master pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 84: GPIO configuration before enabling peripheral

6.17.7 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	TWIM	TWIM0 : S	US	SA	Two-wire interface master 0	
0x40008000	IVVIIVI	TWIM0 : NS	03	SA	Two-wire interface master o	
0x50009000	TWIM	TWIM1:S	US	SA	Two-wire interface master 1	
0x40009000		TWIM1: NS	03	SA	TWO-WITE IIITETTACE THASTET 1	
0x5000A000	TWIM	TWIM2:S	US	SA	Two-wire interface master 2	
0x4000A000	IVVIIVI	TWIM2 : NS	03	SA	TWO-WITE IIITETTACE THASTET 2	
0x5000B000	TWIM	TWIM3:S	LIC.	64	Two-wire interface master 3	
0x4000B000	IVVIIVI	TWIM3 : NS	US	SA	TWO-WITE IIITEFFACE MASTER 3	

Table 85: Instances

	Offset	Security	Description
TASKS_STARTRX	0x000		Start TWI receive sequence
TASKS_STARTTX	0x008		Start TWI transmit sequence
TASKS_STOP	0x014		Stop TWI transaction. Must be issued while the TWI master is not suspended.
TASKS_SUSPEND	0x01C		Suspend TWI transaction
TASKS_RESUME	0x020		Resume TWI transaction
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_STOPPED	0x104		TWI stopped
EVENTS_ERROR	0x124		TWI error
EVENTS_SUSPENDED	0x148		Last byte has been sent out after the SUSPEND task has been issued, TWI traffic is
			now suspended.
EVENTS_RXSTARTED	0x14C		Receive sequence started
EVENTS_TXSTARTED	0x150		Transmit sequence started
EVENTS_LASTRX	0x15C		Byte boundary, starting to receive the last byte
EVENTS_LASTTX	0x160		Byte boundary, starting to transmit the last byte
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_SUSPENDED	0x1C8		Publish configuration for event SUSPENDED
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED



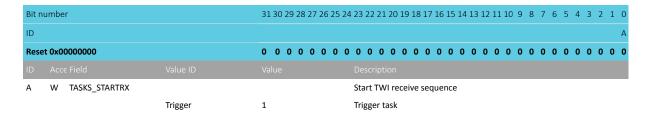
Register	Offset	Security	Description
PUBLISH_LASTRX	0x1DC		Publish configuration for event LASTRX
PUBLISH_LASTTX	0x1E0		Publish configuration for event LASTTX
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x4C4		Error source
ENABLE	0x500		Enable TWIM
PSEL.SCL	0x508		Pin select for SCL signal
PSEL.SDA	0x50C		Pin select for SDA signal
FREQUENCY	0x524		TWI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
TXD.LIST	0x550		EasyDMA list type
ADDRESS	0x588		Address used in the TWI transfer

Table 86: Register overview

6.17.7.1 TASKS_STARTRX

Address offset: 0x000

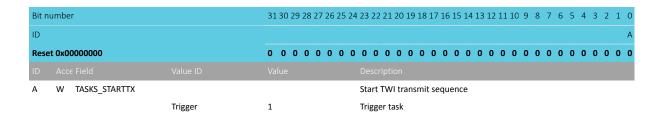
Start TWI receive sequence



6.17.7.2 TASKS STARTTX

Address offset: 0x008

Start TWI transmit sequence



6.17.7.3 TASKS_STOP

Address offset: 0x014

Stop TWI transaction. Must be issued while the TWI master is not suspended.

Bit number		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A W TASKS_STOP			Stop TWI transaction. Must be issued while the TWI master
			is not suspended.
	Trigger	1	Trigger task

6.17.7.4 TASKS_SUSPEND

Address offset: 0x01C
Suspend TWI transaction

Bit ni	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_SUSPEND			Suspend TWI transaction
		Trigger	1	Trigger task

6.17.7.5 TASKS_RESUME

Address offset: 0x020
Resume TWI transaction

Bit n	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_RESUME			Resume TWI transaction
		Trigger	1	Trigger task

6.17.7.6 SUBSCRIBE_STARTRX

Address offset: 0x080

Subscribe configuration for task STARTRX

Bit n	Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STARTRX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.17.7.7 SUBSCRIBE_STARTTX

Address offset: 0x088

Subscribe configuration for task STARTTX

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		В	АААА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CHIDX		[150]	Channel that task STARTTX will subscribe to
B RW EN			
	Disabled	0	Disable subscription
	Enabled	1	Enable subscription

6.17.7.8 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.17.7.9 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit n	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task SUSPEND will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.17.7.10 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

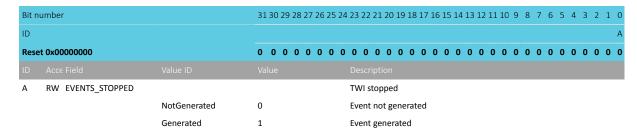
Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task RESUME will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription



6.17.7.11 EVENTS_STOPPED

Address offset: 0x104

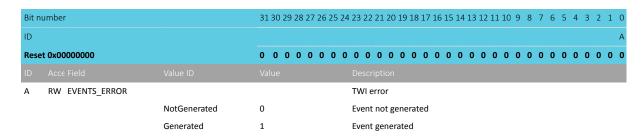
TWI stopped



6.17.7.12 EVENTS_ERROR

Address offset: 0x124

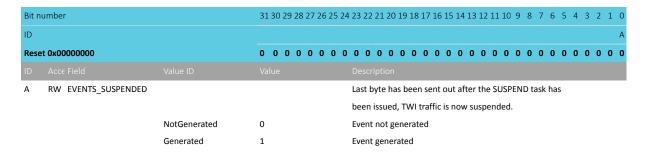
TWI error



6.17.7.13 EVENTS SUSPENDED

Address offset: 0x148

Last byte has been sent out after the SUSPEND task has been issued, TWI traffic is now suspended.



6.17.7.14 EVENTS RXSTARTED

Address offset: 0x14C

Receive sequence started



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_RXSTARTED			Receive sequence started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.17.7.15 EVENTS_TXSTARTED

Address offset: 0x150

Transmit sequence started

Bit n	umber		31	30	29 2	28 2	7 26	25	24 :	23 2	22 2	1 20	0 19	18	17 :	16 1	.5 1	4 13	12 :	11 1	.0 9	8	7	6	5	4 3	3 2	1	0
ID																													Α
Rese	t 0x00000000		0	0	0	0 (0 0	0	0	0	0 0	0	0	0	0	0 (0 0	0	0	0	0 0	0	0	0	0	0 (0	0	0
ID																													
Α	RW EVENTS_TXSTARTED									Trar	nsm	it se	equ	ence	sta	rte	d												
		NotGenerated	0						-	Eve	nt n	ot g	gene	erate	ed														
		Generated	1						-	Eve	nt g	ene	erate	ed															

6.17.7.16 EVENTS_LASTRX

Address offset: 0x15C

Byte boundary, starting to receive the last byte

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_LASTRX			Byte boundary, starting to receive the last byte
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.17.7.17 EVENTS_LASTTX

Address offset: 0x160

Byte boundary, starting to transmit the last byte

Bit nu	ımber		31	30	29	28 2	27 2	26 2	5 2	24 2	3 2	22 2	21 2	0 1	9 1	8 1	7 16	5 15	14	13	12	11 1	.0 9	8	7	6	5	4	3	2	1 0
ID																															Α
Rese	0x00000000		0	0	0	0	0	0 () (0 () (0 (0 0	0 (0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 (0 0
ID																															
Α	RW EVENTS_LASTTX									В	syte	e bo	oun	daı	ry, s	tari	ing	to	trai	nsm	it tl	ne l	ast l	yte							
		NotGenerated	0							E	ver	nt n	not (ger	nera	tec	l														
		Generated	1							E	ver	nt g	gene	era	ted																

6.17.7.18 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

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Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event STOPPED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.17.7.19 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event ERROR will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.17.7.20 PUBLISH_SUSPENDED

Address offset: 0x1C8

Publish configuration for event SUSPENDED

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6	5 4	1 3	2 1	. 0
ID			В			Α	A A	A A
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0	0 (0 0	0
ID								
Α	RW CHIDX		[150]	Channel that event SUSPENDED will publish to.				
В	RW EN							
		Disabled	0	Disable publishing				
		Enabled	1	Enable publishing				

6.17.7.21 PUBLISH_RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event RXSTARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

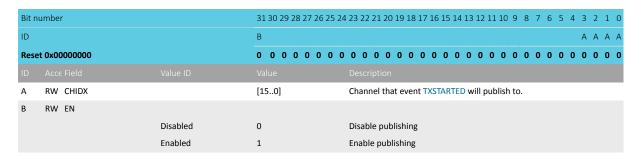




6.17.7.22 PUBLISH_TXSTARTED

Address offset: 0x1D0

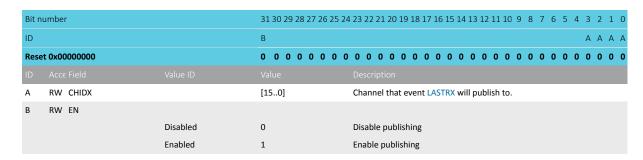
Publish configuration for event TXSTARTED



6.17.7.23 PUBLISH_LASTRX

Address offset: 0x1DC

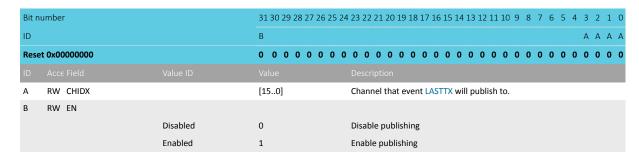
Publish configuration for event LASTRX



6.17.7.24 PUBLISH LASTTX

Address offset: 0x1E0

Publish configuration for event LASTTX



6.17.7.25 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks



	mber		31 30 29 28 27 26 25 24	¹ 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				FEDCBA
Reset	0x0000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
Α	RW LASTTX_STARTRX			Shortcut between event LASTTX and task STARTRX
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
В	RW LASTTX_SUSPEND			Shortcut between event LASTTX and task SUSPEND
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
С	RW LASTTX_STOP			Shortcut between event LASTTX and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW LASTRX_STARTTX			Shortcut between event LASTRX and task STARTTX
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
E	RW LASTRX_SUSPEND			Shortcut between event LASTRX and task SUSPEND
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
F	RW LASTRX_STOP			Shortcut between event LASTRX and task STOP
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.17.7.26 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber		313	30 2	29 28	27	26 25	5 24	1 23	3 22 :	21	20 1	19 1	8 1	7 16	5 15	14	13 1	2 1	1 10	9	8	7	6 5	4	3	2 :	L 0
ID								J	- 1			н	G	F							D						A	١
Rese	t 0x00000000		0	0	0 0	0	0 0	0	0	0 0	0	0	0	0 (0	0	0	0	0 (0	0	0	0	0 0	0	0	0 (0
Α	RW STOPPED								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt S	ТОР	PE)						
		Disabled	0						D	isabl	e																	
		Enabled	1						Eı	nable	e																	
D	RW ERROR								E	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt E	RRC	DR							
		Disabled	0						D	isabl	е																	
		Enabled	1						Eı	nable	е																	
F	RW SUSPENDED								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt S	USP	ENI	DED						
		Disabled	0						D	isabl	e																	
		Enabled	1						Eı	nable	е																	
G	RW RXSTARTED								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt F	RXST	ART	ED						
		Disabled	0						D	isabl	e																	
		Enabled	1						Eı	nable	9																	
Н	RW TXSTARTED								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt T	XST	ART	ED						
		Disabled	0						D	isabl	e																	
		Enabled	1						Eı	nable	9																	
1	RW LASTRX								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt L	AST	RX							
		Disabled	0						D	isabl	e																	
		Enabled	1						Eı	nable	9																	
J	RW LASTTX								Eı	nable	e oi	r dis	abl	e in	terr	upt	for	eve	nt L	AST	TX							
		Disabled	0						D	isabl	e																	
		Enabled	1						E	nable	е																	



6.17.7.27 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				JI HGF D A
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW STOPPED			Write '1' to enable interrupt for event STOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ERROR			Write '1' to enable interrupt for event ERROR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW SUSPENDED			Write '1' to enable interrupt for event SUSPENDED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	G RW RXSTARTED			Write '1' to enable interrupt for event RXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW TXSTARTED			Write '1' to enable interrupt for event TXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
1	RW LASTRX			Write '1' to enable interrupt for event LASTRX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW LASTTX			Write '1' to enable interrupt for event LASTTX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.17.7.28 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		313	30 2	9 28	27 2	26 2	5 24	4 23	3 22	21	20 1	19 1	.8 1	7 16	5 15	5 14	13	12	11 :	10 9	8	7	6	5	4	3	2 1	. 0
ID								J	- 1			Н	G	F							C							A	l l
Rese	t 0x00000000		0	0 (0 (0	0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 0	0
ID																													
Α	RW STOPPED								W	/rite	'1'	to d	lisa	ble i	nte	rru	pt f	or e	ver	nt S	ОРІ	PED							
		Clear	1						D	isab	le																		
		Disabled	0						R	ead:	: Dis	sable	ed																
		Enabled	1						R	ead:	: En	able	ed																
D	RW ERROR								W	/rite	'1'	to d	lisa	ble i	nte	rru	pt f	or e	ver	nt El	RRO	3							
		Clear	1						D	isab	le																		



Bit number		31 30 29 28 27 26 25 2	
ID			J I H G F D A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
F RW SUSPENDE)		Write '1' to disable interrupt for event SUSPENDED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
G RW RXSTARTED			Write '1' to disable interrupt for event RXSTARTED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
H RW TXSTARTED			Write '1' to disable interrupt for event TXSTARTED
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
I RW LASTRX			Write '1' to disable interrupt for event LASTRX
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
J RW LASTTX			Write '1' to disable interrupt for event LASTTX
	Clear	1	Disable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.17.7.29 ERRORSRC

Address offset: 0x4C4

Error source

Bit r	number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Res	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
Α	RW OVERRUN			Overrun error
				A new byte was received before previous byte got
				transferred into RXD buffer. (Previous data is lost)
		NotReceived	0	Error did not occur
		Received	1	Error occurred
В	RW ANACK			NACK received after sending the address (write '1' to clear)
		NotReceived	0	Error did not occur
		Received	1	Error occurred
С	RW DNACK			NACK received after sending a data byte (write '1' to clear)
		NotReceived	0	Error did not occur
		Received	1	Error occurred

6.17.7.30 ENABLE

Address offset: 0x500

Enable TWIM



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АААА
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW ENABLE			Enable or disable TWIM
	Disabled	0	Disable TWIM
	Enabled	6	Enable TWIM

6.17.7.31 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.17.7.32 PSEL.SDA

Address offset: 0x50C Pin select for SDA signal

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.17.7.33 FREQUENCY

Address offset: 0x524

TWI frequency. Accuracy depends on the HFCLK source selected.

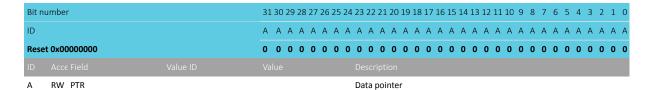
Bit r	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A	. A A A A A A A A A A A A A A A A A A A
Rese	et 0x04000000		0 0 0 0 0 1 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW FREQUENCY			TWI master clock frequency
		K100	0x01980000	100 kbps
		K250	0x04000000	250 kbps
		K400	0x06400000	400 kbps



6.17.7.34 RXD.PTR

Address offset: 0x534

Data pointer

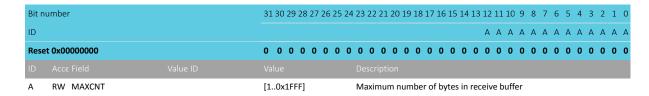


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.17.7.35 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer



6.17.7.36 RXD.AMOUNT

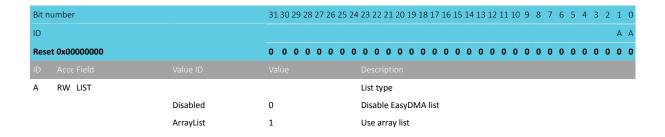
Address offset: 0x53C

Number of bytes transferred in the last transaction

		of NACK array includes the NACK ad buts	
A R AMOUN	NT	[10x1FFF] Number of bytes transferred in the last transaction. In case	
ID Acce Field			
Reset 0x00000000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID		A A A A A A A A A A A A A A A A A A A	A A
Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0

6.17.7.37 RXD.LIST

Address offset: 0x540 EasyDMA list type



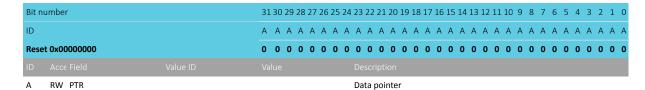




6.17.7.38 TXD.PTR

Address offset: 0x544

Data pointer

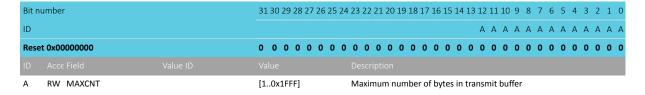


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.17.7.39 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



6.17.7.40 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last transaction

Bit number	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A A A A A A A A A A A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID Acce Field Value		Description
A R AMOUNT	[10x1FFF]	Number of bytes transferred in the last transaction. In case
		of NACK error, includes the NACK'ed byte.

6.17.7.41 TXD.LIST

Address offset: 0x550 EasyDMA list type

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		A A
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW LIST		List type
Disabled	0	Disable EasyDMA list
ArrayList	1	Use array list

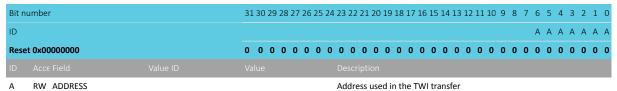




6.17.7.42 ADDRESS

Address offset: 0x588

Address used in the TWI transfer



A KW ADDRESS used in the TWI translet

6.17.8 Electrical specification

6.17.8.1 TWIM interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIM,SCL}	Bit rates for TWIM ¹⁴	100		400	kbps
t _{TWIM,START}	Time from STARTRX/STARTTX task to transmission started				μs

6.17.8.2 Two Wire Interface Master (TWIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{TWIM} ,su_DAT	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIM,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
$t_{TWIM,HD_STA,100kbps}$	TWIM master hold time for START and repeated START	10000			ns
	condition, 100 kbps				
$t_{TWIM,HD_STA,250kbps}$	TWIM master hold time for START and repeated START	4000			ns
	condition, 250kbps				
$t_{TWIM,HD_STA,400kbps}$	TWIM master hold time for START and repeated START	2500			ns
	condition, 400 kbps				
$t_{TWIM,SU_STO,100kbps}$	TWIM master setup time from SCL high to STOP condition,	5000			ns
	100 kbps				
t _{TWIM} ,su_sto,250kbps	TWIM master setup time from SCL high to STOP condition,	2000			ns
	250 kbps				
$t_{\text{TWIM},\text{SU_STO},400\text{kbps}}$	TWIM master setup time from SCL high to STOP condition,	1250			ns
	400 kbps				
t _{TWIM,BUF,100kbps}	TWIM master bus free time between STOP and START	5800			ns
	conditions, 100 kbps				
t _{TWIM,BUF,250kbps}	TWIM master bus free time between STOP and START	2700			ns
	conditions, 250 kbps				
t _{TWIM,BUF,400kbps}	TWIM master bus free time between STOP and START	2100			ns
	conditions, 400 kbps				



High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

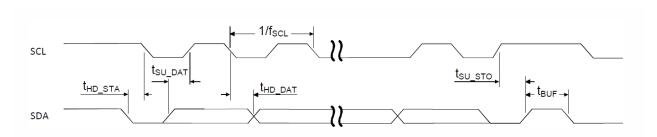


Figure 93: TWIM timing diagram, 1 byte transaction

6.17.9 Pullup resistor

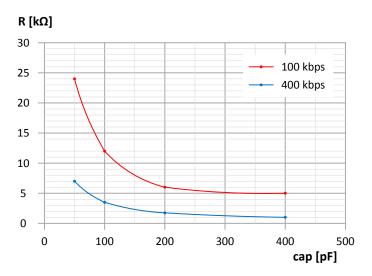


Figure 94: Recommended TWIM pullup value vs. line capacitance

- The I2C specification allows a line capacitance of 400 pF at most.
- The value of internal pullup resistor (R_{PU}) for nRF9160 can be found in GPIO General purpose input/output on page 91.

$6.18 \text{ TWIS} - I^2 \text{C}$ compatible two-wire interface slave with EasyDMA

TWI slave with EasyDMA (TWIS) is compatible with I²C operating at 100 kHz and 400 kHz. The TWI transmitter and receiver implement EasyDMA.

NORDIC

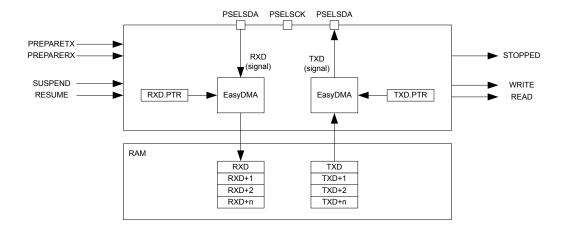


Figure 95: TWI slave with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see A typical TWI setup comprising one master and three slaves on page 310. TWIS is only able to operate with a single master on the TWI bus.



Figure 96: A typical TWI setup comprising one master and three slaves

The TWI slave state machine is illustrated in TWI slave state machine on page 311 and TWI slave state machine symbols on page 311 is explaining the different symbols used in the state machine.



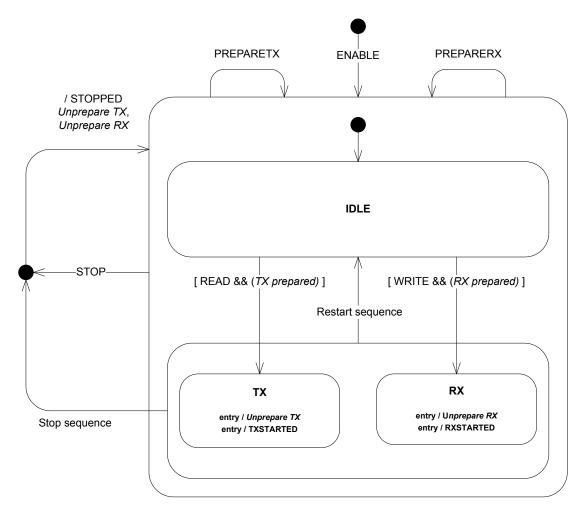


Figure 97: TWI slave state machine

Symbol	Туре	Description
ENABLE	Register	The TWI slave has been enabled via the ENABLE register
PREPARETX	Task	The TASKS_PREPARETX task has been triggered
STOP	Task	The TASKS_STOP task has been triggered
PREPARERX	Task	The TASKS_PREPARERX task has been triggered
STOPPED	Event	The EVENTS_STOPPED event was generated
RXSTARTED	Event	The EVENTS_RXSTARTED event was generated
TXSTARTED	Event	The EVENTS_TXSTARTED event was generated
TX prepared	Internal	Internal flag indicating that a TASKS_PREPARETX task has been triggered. This flag is not visible to the
		user.
RX prepared	Internal	Internal flag indicating that a TASKS_PREPARERX task has been triggered. This flag is not visible to the
		user.
Unprepare TX	Internal	Clears the internal 'TX prepared' flag until next TASKS_PREPARETX task.
Unprepare RX	Internal	Clears the internal 'RX prepared' flag until next TASKS_PREPARERX task.
Stop sequence	TWI protocol	A TWI stop sequence was detected
Restart sequence	TWI protocol	A TWI restart sequence was detected

Table 87: TWI slave state machine symbols

The TWI slave supports clock stretching performed by the master.

The TWI slave operates in a low power mode while waiting for a TWI master to initiate a transfer. As long as the TWI slave is not addressed, it will remain in this low power mode.

NORDIC

To secure correct behaviour of the TWI slave, PSEL.SCL, PSEL.SDA, CONFIG and the ADDRESS[n] registers, must be configured prior to enabling the TWI slave through the ENABLE register. Similarly, changing these settings must be performed while the TWI slave is disabled. Failing to do so may result in unpredictable behaviour.

6.18.1 EasyDMA

The TWI slave implements EasyDMA for reading and writing to and from the RAM.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

6.18.2 TWI slave responding to a read command

Before the TWI slave can respond to a read command the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled the TWI slave will be in its IDLE state where it will consume $I_{\rm IDLE}$.

A read command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the TWI slave.

The TWI slave is able to listen for up to two addresses at the same time. Which addresses to listen for is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the read command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a READ event when it acknowledges the read command.

The TWI slave is only able to detect a read command from the IDLE state.

The TWI slave will set an internal 'TX prepared' flag when the PREPARETX task is triggered.

When the read command is received the TWI slave will enter the TX state if the internal 'TX prepared' flag is set.

If the internal 'TX prepared' flag is not set when the read command is received, the TWI slave will stretch the master's clock until the PREPARETX task is triggered and the internal 'TX prepared' flag is set.

The TWI slave will generate the TXSTARTED event and clear the 'TX prepared' flag ('unprepare TX') when it enters the TX state. In this state the TWI slave will send the data bytes found in the transmit buffer to the master using the master's clock. The TWI slave will consume I_{TX} in this mode.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the TX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the 'TX prepared' flag ('unprepare TX') and go back to the IDLE state when it has stopped.

The transmit buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to send TXD.MAXCNT bytes from the transmit buffer for each transaction. If the TWI master forces the slave to send more than TXD.MAXCNT bytes, the slave will send the byte specified in the ORC register to the master instead. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see TXD.PTR etc., are latched when the TXSTARTED event is generated.



The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the 'TX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 315.

Each byte sent from the slave will be followed by an ACK/NACK bit sent from the master. The TWI master will generate a NACK following the last byte that it wants to receive to tell the slave to release the bus so that the TWI master can generate the stop condition. The TXD.AMOUNT register can be queried after a transaction to see how many bytes were sent.

A typical TWI slave read command response is illustrated in The TWI slave responding to a read command on page 313. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

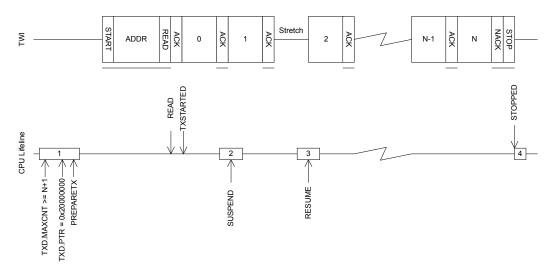


Figure 98: The TWI slave responding to a read command

6.18.3 TWI slave responding to a write command

Before the TWI slave can respond to a write command the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled the TWI slave will be in its IDLE state where it will consume $I_{\rm IDLE}$.

A write command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the slave.

The TWI slave is able to listen for up to two addresses at the same time. Which addresses to listen for is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the write command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a WRITE event if it acknowledges the write command.

The TWI slave is only able to detect a write command from the IDLE state.

The TWI slave will set an internal 'RX prepared' flag when the PREPARERX task is triggered.

When the write command is received the TWI slave will enter the RX state if the internal 'RX prepared' flag is set.

If the internal 'RX prepared' flag is not set when the write command is received, the TWI slave will stretch the master's clock until the PREPARERX task is triggered and the internal 'RX prepared' flag is set.

The TWI slave will generate the RXSTARTED event and clear the internal 'RX prepared' flag ('unprepare RX') when it enters the RX state. In this state the TWI slave will be able to receive the bytes sent by the TWI master. The TWI slave will consume I_{RX} in this mode.



The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the RX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the internal 'RX prepared' flag ('unprepare RX') and go back to the IDLE state when it has stopped.

The receive buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to receive as many bytes as specified in the RXD.MAXCNT register. If the TWI master tries to send more bytes to the slave than the slave is able to receive, these bytes will be discarded and the bytes will be NACKed by the slave. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see RXD.PTR etc., are latched when the RXSTARTED event is generated.

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the internal 'RX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 315.

The TWI slave will generate an ACK after every byte received from the master. The RXD.AMOUNT register can be queried after a transaction to see how many bytes were received.

A typical TWI slave write command response is illustrated in The TWI slave responding to a write command on page 314. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

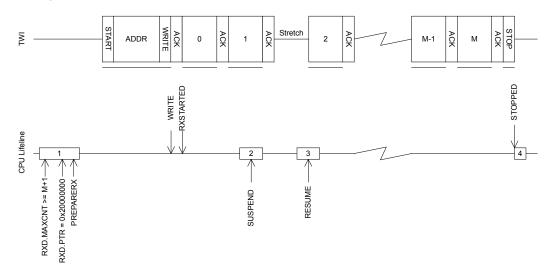


Figure 99: The TWI slave responding to a write command

6.18.4 Master repeated start sequence

An example of a repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave.

This is illustrated in A repeated start sequence, where the TWI master writes two bytes followed by reading four bytes from the slave on page 315.

It is here assumed that the receiver does not know in advance what the master wants to read, and that this information is provided in the first two bytes received in the write part of the repeated start sequence. To guarantee that the CPU is able to process the received data before the TWI slave starts to reply to the read command, the SUSPEND task is triggered via a shortcut from the READ event generated when the read command is received. When the CPU has processed the incoming data and prepared the correct data response, the CPU will resume the transaction by triggering the RESUME task.



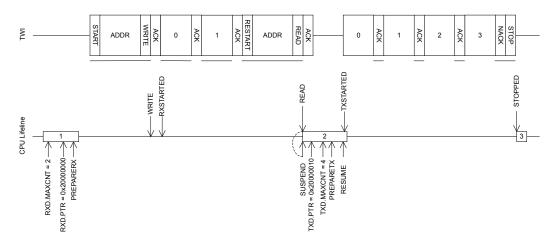


Figure 100: A repeated start sequence, where the TWI master writes two bytes followed by reading four bytes from the slave

6.18.5 Terminating an ongoing TWI transaction

In some situations, e.g. if the external TWI master is not responding correctly, it may be required to terminate an ongoing transaction.

This can be achieved by triggering the STOP task. In this situation a STOPPED event will be generated when the TWI has stopped independent of whether or not a STOP condition has been generated on the TWI bus. The TWI slave will release the bus when it has stopped and go back to its IDLE state.

6.18.6 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.18.7 Slave mode pin configuration

The SCL and SDA signals associated with the TWI slave are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI slave is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL and PSEL.SDA must only be configured when the TWI slave is disabled.

To secure correct signal levels on the pins used by the TWI slave when the system is in OFF mode, and when the TWI slave is disabled, these pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 315.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI slave signal	TWI slave pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 88: GPIO configuration before enabling peripheral



6.18.8 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	TWIS	TWIS0 : S	US	SA	Two-wire interface slave 0	
0x40008000	1 4413	TWIS0 : NS	03	SA	Two-wife lifterface slave o	
0x50009000	TWIS	TWIS1 : S	US	SA	Two-wire interface slave 1	
0x40009000	1 4413	TWIS1 : NS	03	SA	TWO-WITE IIITETTACE STAVE 1	
0x5000A000	TWIS	TWIS2 : S	US	SA	Two-wire interface slave 2	
0x4000A000	1 4413	TWIS2 : NS	03	SA	TWO-WITE IIITETTACE STAVE 2	
0x5000B000	TWIS	TWIS3 : S	US	SA	Two-wire interface slave 3	
0x4000B000	1 1 1 1 1 1	TWIS3 : NS	03	3A	TWO-WITE IIITETTACE STAVE 3	

Table 89: Instances

Register	Offset	Security	Description				
TASKS_STOP	0x014		Stop TWI transaction				
TASKS_SUSPEND	0x01C		Suspend TWI transaction				
TASKS_RESUME	0x020		Resume TWI transaction				
TASKS_PREPARERX	0x030		Prepare the TWI slave to respond to a write command				
TASKS_PREPARETX	0x034		Prepare the TWI slave to respond to a read command				
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP				
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND				
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME				
SUBSCRIBE_PREPARERX	0x0B0		Subscribe configuration for task PREPARERX				
SUBSCRIBE_PREPARETX	0x0B4		Subscribe configuration for task PREPARETX				
EVENTS_STOPPED	0x104		TWI stopped				
EVENTS_ERROR	0x124		TWI error				
EVENTS_RXSTARTED	0x14C		Receive sequence started				
EVENTS_TXSTARTED	0x150		Transmit sequence started				
EVENTS_WRITE	0x164		Write command received				
EVENTS_READ	0x168		Read command received				
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED				
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR				
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED				
PUBLISH_TXSTARTED	0x1D0	Publish configuration for event TXSTARTED					
PUBLISH_WRITE	0x1E4		Publish configuration for event WRITE				
PUBLISH_READ	0x1E8		Publish configuration for event READ				
SHORTS	0x200		Shortcuts between local events and tasks				
INTEN	0x300		Enable or disable interrupt				
INTENSET	0x304		Enable interrupt				
INTENCLR	0x308		Disable interrupt				
ERRORSRC	0x4D0		Error source				
MATCH	0x4D4		Status register indicating which address had a match				
ENABLE	0x500		Enable TWIS				
PSEL.SCL	0x508		Pin select for SCL signal				
PSEL.SDA	0x50C		Pin select for SDA signal				
RXD.PTR	0x534		RXD Data pointer				
RXD.MAXCNT	0x538		Maximum number of bytes in RXD buffer				
RXD.AMOUNT	0x53C		Number of bytes transferred in the last RXD transaction				
TXD.PTR	0x544		TXD Data pointer				
TXD.MAXCNT	0x548		Maximum number of bytes in TXD buffer				
TXD.AMOUNT	0x54C		Number of bytes transferred in the last TXD transaction				
ADDRESS[0]	0x588		TWI slave address 0				



Register	Offset	Security	Description
ADDRESS[1]	0x58C		TWI slave address 1
CONFIG	0x594		Configuration register for the address match mechanism
ORC	0x5C0		Over-read character. Character sent out in case of an over-read of the transmit
			buffer.

Table 90: Register overview

6.18.8.1 TASKS_STOP

Address offset: 0x014 Stop TWI transaction

Bit n	umber		31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				
Rese	et 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_STOP			Stop TWI transaction
		Trigger	1	Trigger task

6.18.8.2 TASKS_SUSPEND

Address offset: 0x01C
Suspend TWI transaction

Bit n	umb	er		313	30 2	29 28	3 27	26 2	25 24	1 2	3 22	21	. 20 1	19 1	18 17	⁷ 16	15	14 1	l3 1	2 11	10	9	8 7	6	5	4	3 2	2 1	0
ID																													Α
Rese	et Ox	00000000		0	0	0 0	0	0	0 0	(0	0	0	0	0 0	0	0	0	0 (0 0	0	0	0 0	0	0	0	0 (0 0	0
ID																													
Α	W	TASKS_SUSPEND								S	uspe	end	TW	l tra	ansa	ctio	n												
			Trigger	1						Т	rigge	er ta	ask																

6.18.8.3 TASKS_RESUME

Address offset: 0x020
Resume TWI transaction

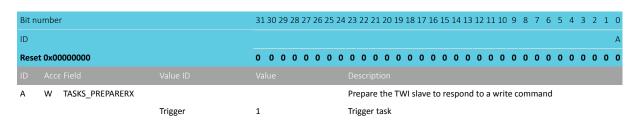
Bit number	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID Acce Field		Description
A W TASKS RESUME		Resume TWI transaction
7. 17 17 17 18 18 18 18 18 18 18 18 18 18 18 18 18		Nesume (W) transaction

6.18.8.4 TASKS_PREPARERX

Address offset: 0x030

Prepare the TWI slave to respond to a write command





6.18.8.5 TASKS_PREPARETX

Address offset: 0x034

Prepare the TWI slave to respond to a read command

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_PREPARETX			Prepare the TWI slave to respond to a read command
		Trigger	1	Trigger task

6.18.8.6 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOP will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.18.8.7 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task SUSPEND will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.18.8.8 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME



Bit ni	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task RESUME will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.18.8.9 SUBSCRIBE_PREPARERX

Address offset: 0x0B0

Subscribe configuration for task PREPARERX

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task PREPARERX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.18.8.10 SUBSCRIBE_PREPARETX

Address offset: 0x0B4

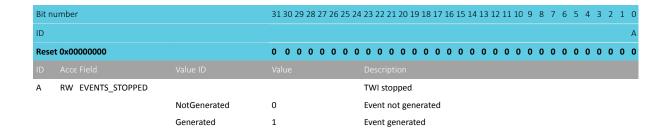
Subscribe configuration for task PREPARETX

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that task PREPARETX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.18.8.11 EVENTS_STOPPED

Address offset: 0x104

TWI stopped







6.18.8.12 EVENTS_ERROR

Address offset: 0x124

TWI error

Bit r	umber		31	30	29	28	27	26 2	25 :	24	23	22	21	20	19	18	17 :	16	15 1	14 :	13 :	.2 1	1 1	0 9	8	7	6	5	4	3	2	1 0
ID																																А
Rese	et 0x00000000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0 0
ID											De:																					
Α	RW EVENTS_ERROR										TW	/I e	rror																			
		NotGenerated	0								Eve	ent	not	ge	ner	ate	ed															
		Generated	1								Eve	ent	ger	era	ate	t																

6.18.8.13 EVENTS_RXSTARTED

Address offset: 0x14C

Receive sequence started

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_RXSTARTED			Receive sequence started
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.18.8.14 EVENTS_TXSTARTED

Address offset: 0x150

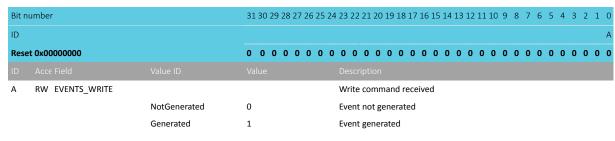
Transmit sequence started

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_TXSTARTED			Transmit sequence started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.18.8.15 EVENTS_WRITE

Address offset: 0x164

Write command received

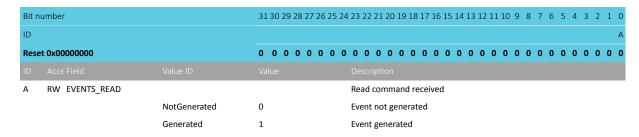






6.18.8.16 EVENTS_READ

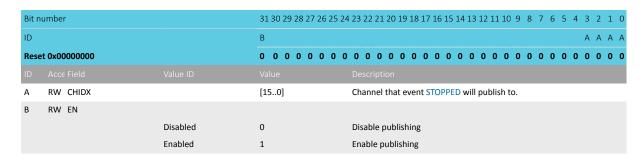
Address offset: 0x168
Read command received



6.18.8.17 PUBLISH STOPPED

Address offset: 0x184

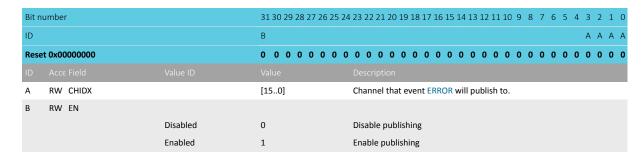
Publish configuration for event STOPPED



6.18.8.18 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR



6.18.8.19 PUBLISH RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event RXSTARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.18.8.20 PUBLISH_TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event TXSTARTED will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.18.8.21 PUBLISH_WRITE

Address offset: 0x1E4

Publish configuration for event WRITE

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event WRITE will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.18.8.22 PUBLISH_READ

Address offset: 0x1E8

Publish configuration for event READ

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event READ will publish to.
В	RW EN			
		Disabled	0	Disable publishing



6.18.8.23 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit number			31 30	29 2	28 27	26 2	5 2	4 23	3 22	21 2	0 1	9 18	3 17	16	15 1	L4 1	3 12	2 11	10	9	8 7	6	5	4	3	2 :	1 0
ID																В	4										
Reset 0x000	000000		0 0	0	0 0	0	0 0	0 0	0	0 (0 (0 0	0	0	0	0 (0	0	0	0	0 0	0	0	0	0	0 (0 0
ID Acce I																											
A RW	WRITE_SUSPEND							Sh	orto	cut b	etv	veei	ı ev	ent	WR	ITE	and	tas	k SL	ISP	END						
		Disabled	0					Di	sabl	le sh	ort	cut															
		Enabled	1					En	nable	e sho	orto	cut															
B RW I	READ_SUSPEND							Sh	orto	cut b	etv	veei	ı ev	ent	REA	AD a	ınd 1	task	SUS	SPE	ND						
		Disabled	0					Di	sabl	le sh	ort	cut															
		Enabled	1					En	nable	e sho	orto	cut															

6.18.8.24 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber	3	1 30 29 2	28 27 :	26 25	24 2	3 22 21	. 20 1	.9 18	17 10	5 15 1	4 13 1	.2 1	1 10 9	8	7	6 5	4	3 2	1 0
ID					H G			F	E					E	3					Α
Rese	et 0x00000000	0	0 0	0 0	0 0	0 (0 0	0 (0 0	0 0	0 (0 0	0 0	0 (0	0	0 0	0	0 0	0 0
ID																				
Α	RW STOPPED					Е	nable c	or dis	able	interi	upt fo	or eve	nt S	TOPPE	D					
	Disabl	ed 0				D	isable													
	Enable	ed 1				Е	nable													
В	RW ERROR					Е	nable c	or dis	able	interi	upt fo	or eve	nt E	RROR						
	Disabl	ed 0				D	isable													
	Enable	ed 1				Е	nable													
Ε	RW RXSTARTED					E	nable c	or dis	able	interi	upt fo	or eve	nt R	XSTAF	TED					
	Disabl	ed 0				D	isable													
	Enable	ed 1				E	nable													
F	RW TXSTARTED					Е	nable c	or dis	able	interi	upt fo	or eve	nt T	XSTAR	TED					
	Disabl	ed 0				D	isable													
	Enable	ed 1				E	nable													
G	RW WRITE					Е	nable c	or dis	able	interi	upt fo	or eve	nt V	/RITE						
	Disabl	ed 0				D	isable													
	Enable	ed 1				E	nable													
Н	RW READ					E	nable c	or dis	able	interi	rupt fo	or eve	nt R	EAD						
	Disabl	ed 0				D	isable													
	Enable	ed 1				E	nable													

6.18.8.25 INTENSET

Address offset: 0x304

Enable interrupt



Bit number			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0													
ID			H G	F E B A													
Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0													
ID	Acce Field	Value ID	Value	Description													
Α	RW STOPPED			Write '1' to enable interrupt for event STOPPED													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													
В	RW ERROR			Write '1' to enable interrupt for event ERROR													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													
E	RW RXSTARTED			Write '1' to enable interrupt for event RXSTARTED													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													
F	RW TXSTARTED			Write '1' to enable interrupt for event TXSTARTED													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													
G	RW WRITE			Write '1' to enable interrupt for event WRITE													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													
Н	RW READ			Write '1' to enable interrupt for event READ													
		Set	1	Enable													
		Disabled	0	Read: Disabled													
		Enabled	1	Read: Enabled													

6.18.8.26 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber		31 30 29 28	3 27 26	25 24	1 23 2	2 21 2	20 19	18 1	.7 16	15 1	L4 1	3 12	11 1	.0 9	8	7	5	4	3 2	1 0
ID				Н	G			F E							В						Α
Rese	Reset 0x00000000		0 0 0 0	0 0	0 0	0 (0 0	0 0	0 (0 0	0	0 (0 0	0 (0 0	0	0	0 0	0	0 0	0 0
ID																					
Α	RW STOPPED					Writ	te '1' t	o disa	able	inte	rrupt	for	eve	nt ST	OPP	ED					
		Clear	1			Disa	ble														
		Disabled	0			Read	d: Disa	abled													
		Enabled	1			Read	d: Ena	bled													
В	RW ERROR					Writ	te '1' t	o disa	able	inte	rrupt	for	eve	nt EF	RROF	ł					
		Clear	1			Disa	ble														
		Disabled	0			Read	d: Disa	abled													
		Enabled	1			Read	d: Ena	bled													
Ε	RW RXSTARTED					Writ	te '1' t	o disa	able	inte	rrupt	for	eve	nt R)	(STA	RTE)				
		Clear	1			Disa	ble														
		Disabled	0			Read	d: Disa	abled													
		Enabled	1			Read	d: Ena	bled													
F	RW TXSTARTED					Writ	te '1' t	o disa	able	inte	rrupt	for	eve	nt T>	(STA	RTEC)				
		Clear	1			Disa	ble														
		Disabled	0			Read	d: Disa	abled													



Bit number	3:	1 30 29 28	27 26	25 2	24 23	3 22 21	1 20	19 1	8 17	16 1	L5 14	13 1	2 11	10	9 8	3 7	6	5	4	3 2	1	0
ID			Н	G			F	Е							В						Α	
Reset 0x00000000	0	0 0 0	0 0	0	0 0	0 0	0	0 (0 0	0	0 0	0 (0 0	0	0 0	0	0	0	0	0 0	0	0
ID Acce Field Valu																						
Ena	bled 1				Re	ead: Ei	nabl	ed														
G RW WRITE					W	rite '1	L' to	disal	ole in	terr	upt 1	or ev	ent \	NRI	ГΕ							
Clea	ar 1	-			Di	sable																
Disa	abled 0)			Re	ead: D	isabl	led														
Ena	bled 1	<u>-</u>			Re	ead: Ei	nabl	ed														
H RW READ					W	rite '1	L' to	disal	ole in	terr	upt 1	or ev	ent F	REAL)							
Clea	ar 1				Dis	sable																
Disa	abled 0)			Re	ead: D	isabl	led														
Ena	bled 1				Re	ead: Ei	nabl	ed														

6.18.8.27 ERRORSRC

Address offset: 0x4D0

Error source

Bit r	number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW OVERFLOW			RX buffer overflow detected, and prevented
		NotDetected	0	Error did not occur
		Detected	1	Error occurred
В	RW DNACK			NACK sent after receiving a data byte
		NotReceived	0	Error did not occur
		Received	1	Error occurred
С	RW OVERREAD			TX buffer over-read detected, and prevented
		NotDetected	0	Error did not occur
		Detected	1	Error occurred

6.18.8.28 MATCH

Address offset: 0x4D4

Status register indicating which address had a match

Bit n	umber	31 30 29 28 27 26 25 24 23 22 21	20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Rese	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			
Α	R MATCH	[01] Which of	f the addresses in {ADDRESS} matched the incoming
		address	

6.18.8.29 ENABLE

Address offset: 0x500

Enable TWIS



Bit number		31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			ААА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW ENABLE			Enable or disable TWIS
	Disabled	0	Disable TWIS
	Enabled	9	Enable TWIS

6.18.8.30 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.18.8.31 PSEL.SDA

Address offset: 0x50C

Pin select for SDA signal

Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.18.8.32 RXD.PTR

Address offset: 0x534

RXD Data pointer

Δ	RW/ PTR	RXD Data pointer	
ID			
Res	et 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A	. A A A A A A A A A A
Bit r	umber	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12	2 11 10 9 8 7 6 5 4 3 2 1 0

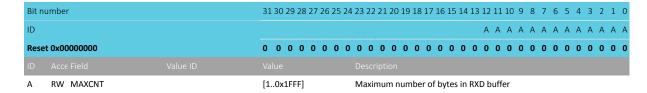
Note: See the memory chapter for details about which memories are available for EasyDMA.



6.18.8.33 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in RXD buffer



6.18.8.34 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last RXD transaction

A R AMOUNT	[10x1FFF] Number of bytes transferred in the last RXD transaction	
ID Acce Field		
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0
ID	A A A A A A A A	A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2 1 0

6.18.8.35 TXD.PTR

Address offset: 0x544

TXD Data pointer

A	RW PTR	value ID	V-	aru											poi	nte	r																		
ID	Acce Field			alue		U		, 0		, ,			crip					J	U	U	U	U	U	U	U	U	U	U	U	U	U	U	U	U	U
Pos	et 0x00000000			_		_							_	^	^	_	n ,	n	^	_	_	_	_	_	_	_	^	^	_	^	_	_	^	0	^
ID			А	Δ	A	Α	. 4	A	. A	۱ ۸	١,	Δ.	Α,	Α.	Α.	Δ.	Δ,	4	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
Bit r	umber		3	1 30	0 29	9 28	3 2	7 26	6 2	5 2	4 2	3 2	22 2	21 2	20 1	.9 1	.8 1	7 :	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.18.8.36 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in TXD buffer

Α	RW MAXCNT	[10x1FFF]	Maximum number of bytes in TXD buffer
ID			
Rese	et 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit n	umber	31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.18.8.37 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last TXD transaction

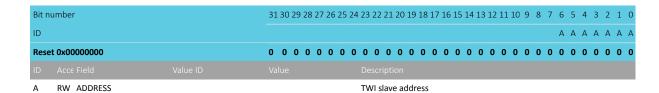


A R AMO	INT	[10x1FFF]	Number of bytes transferred in the last TXD transaction
ID Acce Field			
Reset 0x0000000	0	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.18.8.38 ADDRESS[n] (n=0..1)

Address offset: $0x588 + (n \times 0x4)$

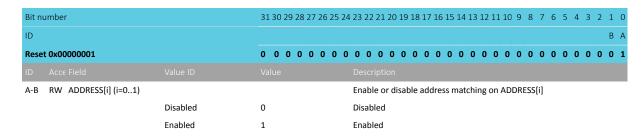
TWI slave address n



6.18.8.39 CONFIG

Address offset: 0x594

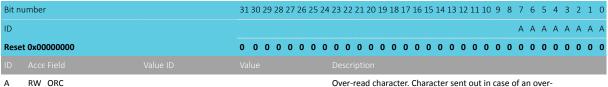
Configuration register for the address match mechanism



6.18.8.40 ORC

Address offset: 0x5C0

Over-read character. Character sent out in case of an over-read of the transmit buffer.



Over-read character. Character sent out in case of an over-

read of the transmit buffer.



6.18.9 Electrical specification

6.18.9.1 TWIS slave timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIS,SCL}	Bit rates for TWIS ¹⁵				kbps
t _{TWIS,START}	Time from PREPARERX/PREPARETX task to ready to receive/ transmit				μs
t _{TWIS,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t_{TWIS,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
$t_{TWIS,HD_STA,100kbps}$	TWI slave hold time from for START condition (SDA low to SCL low), 100 kbps	5200			ns
t _{TWIS,HD_STA,400kbps}	TWI slave hold time from for START condition (SDA low to SCL low), 400 kbps	1300			ns
t _{TWIS,SU_STO,100kbps}	TWI slave setup time from SCL high to STOP condition, 100 kbps	5200			ns
t _{TWIS,SU_STO,400kbps}	TWI slave setup time from SCL high to STOP condition, 400 kbps	1300			ns
t _{TWIS,BUF,100kbps}	TWI slave bus free time between STOP and START conditions, 100 kbps		4700		ns
t _{TWIS,BUF,400kbps}	TWI slave bus free time between STOP and START conditions, 400 kbps		1300		ns

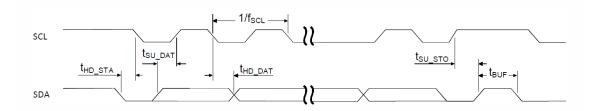


Figure 101: TWIS timing diagram, 1 byte transaction

6.19 UARTE — Universal asynchronous receiver/ transmitter with EasyDMA

The Universal asynchronous receiver/transmitter with EasyDMA (UARTE) offers fast, full-duplex, asynchronous serial communication with built-in flow control (CTS, RTS) support in hardware at a rate up to 1 Mbps, and EasyDMA data transfer from/to RAM.

Listed here are the main features for UARTE:

- Full-duplex operation
- · Automatic hardware flow control
- Optional even parity bit checking and generation
- EasyDMA
- Up to 1 Mbps baudrate
- · Return to IDLE between transactions supported (when using HW flow control)
- One or two stop bit



High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

· Least significant bit (LSB) first

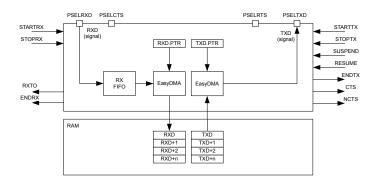


Figure 102: UARTE configuration

The GPIOs used for each UART interface can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

6.19.1 EasyDMA

The UARTE implements EasyDMA for reading and writing to and from the RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 20 for more information about the different memory regions.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The ENDRX/ENDTX event indicates that EasyDMA has finished accessing respectively the RX/TX buffer in RAM.

6.19.2 Transmission

The first step of a DMA transmission is storing bytes in the transmit buffer and configuring EasyDMA. This is achieved by writing the initial address pointer to TXD.PTR, and the number of bytes in the RAM buffer to TXD.MAXCNT. The UARTE transmission is started by triggering the STARTTX task.

After each byte has been sent over the TXD line, a TXDRDY event will be generated.

When all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have been transmitted, the UARTE transmission will end automatically and an ENDTX event will be generated.

A UARTE transmission sequence is stopped by triggering the STOPTX task, a TXSTOPPED event will be generated when the UARTE transmitter has stopped.

If the ENDTX event has not already been generated when the UARTE transmitter has come to a stop, the UARTE will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

If flow control is enabled through the HWFC field in the CONFIG register, a transmission will be automatically suspended when CTS is deactivated and resumed when CTS is activated again, as illustrated in UARTE transmission on page 331. A byte that is in transmission when CTS is deactivated will be fully transmitted before the transmission is suspended.



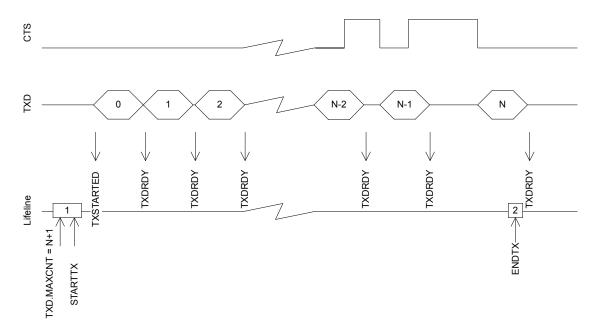


Figure 103: UARTE transmission

The UARTE transmitter will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTTX or after it has been stopped via STOPTX and the TXSTOPPED event has been generated. See POWER — Power control on page 58 for more information about power modes.

6.19.3 Reception

The UARTE receiver is started by triggering the STARTRX task. The UARTE receiver is using EasyDMA to store incoming data in an RX buffer in RAM.

The RX buffer is located at the address specified in the RXD.PTR register. The RXD.PTR register is double-buffered and it can be updated and prepared for the next STARTRX task immediately after the RXSTARTED event is generated. The size of the RX buffer is specified in the RXD.MAXCNT register and the UARTE will generate an ENDRX event when it has filled up the RX buffer, see UARTE reception on page 332.

For each byte received over the RXD line, an RXDRDY event will be generated. This event is likely to occur before the corresponding data has been transferred to Data RAM.

The RXD.AMOUNT register can be queried following an ENDRX event to see how many new bytes have been transferred to the RX buffer in RAM since the previous ENDRX event.



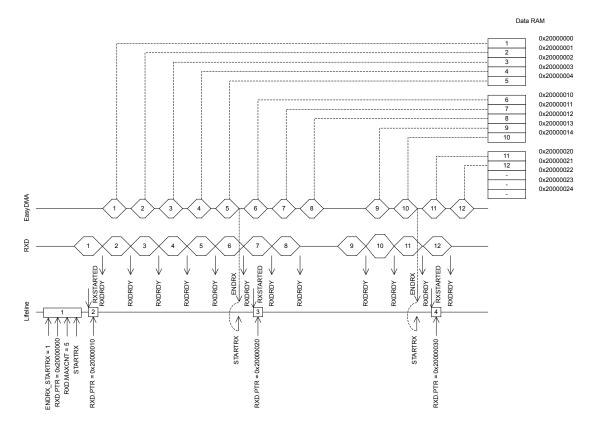


Figure 104: UARTE reception

The UARTE receiver is stopped by triggering the STOPRX task. An RXTO event is generated when the UARTE has stopped. The UARTE will make sure that an impending ENDRX event will be generated before the RXTO event is generated. This means that the UARTE will guarantee that no ENDRX event will be generated after RXTO, unless the UARTE is restarted or a FLUSHRX command is issued after the RXTO event is generated.

Important: If the ENDRX event has not already been generated when the UARTE receiver has come to a stop, which implies that all pending content in the RX FIFO has been moved to the RX buffer, the UARTE will generate the ENDRX event explicitly even though the RX buffer is not full. In this scenario the ENDRX event will be generated before the RXTO event is generated.

To be able to know how many bytes have actually been received into the RX buffer, the CPU can read the RXD.AMOUNT register following the ENDRX event or the RXTO event.

The UARTE is able to receive up to four bytes after the STOPRX task has been triggered as long as these are sent in succession immediately after the RTS signal is deactivated. This is possible because after the RTS is deactivated the UARTE is able to receive bytes for an extended period equal to the time it takes to send 4 bytes on the configured baud rate.

After the RXTO event is generated the internal RX FIFO may still contain data, and to move this data to RAM the FLUSHRX task must be triggered. To make sure that this data does not overwrite data in the RX buffer, the RX buffer should be emptied or the RXD.PTR should be updated before the FLUSHRX task is triggered. To make sure that all data in the RX FIFO is moved to the RX buffer, the RXD.MAXCNT register must be set to RXD.MAXCNT > 4, see UARTE reception with forced stop via STOPRX on page 333. The UARTE will generate the ENDRX event after completing the FLUSHRX task even if the RX FIFO was empty or if the RX buffer does not get filled up. To be able to know how many bytes have actually been received into the RX buffer in this case, the CPU can read the RXD.AMOUNT register following the ENDRX event.



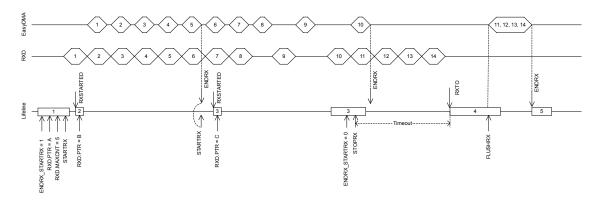


Figure 105: UARTE reception with forced stop via STOPRX

If HW flow control is enabled through the HWFC field in the CONFIG register, the RTS signal will be deactivated when the receiver is stopped via the STOPRX task or when the UARTE is only able to receive four more bytes in its internal RX FIFO.

With flow control disabled, the UARTE will function in the same way as when the flow control is enabled except that the RTS line will not be used. This means that no signal will be generated when the UARTE has reached the point where it is only able to receive four more bytes in its internal RX FIFO. Data received when the internal RX FIFO is filled up, will be lost.

The UARTE receiver will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTRX or after it has been stopped via STOPRX and the RXTO event has been generated. See POWER — Power control on page 58 for more information about power modes.

6.19.4 Error conditions

An ERROR event, in the form of a framing error, will be generated if a valid stop bit is not detected in a frame. Another ERROR event, in the form of a break condition, will be generated if the RXD line is held active low for longer than the length of a data frame. Effectively, a framing error is always generated before a break condition occurs.

An ERROR event will not stop reception. If the error was a parity error, the received byte will still be transferred into Data RAM, and so will following incoming bytes. If there was a framing error (wrong stop bit), that specific byte will NOT be stored into Data RAM, but following incoming bytes will.

6.19.5 Using the UARTE without flow control

If flow control is not enabled, the interface will behave as if the CTS and RTS lines are kept active all the time.

6.19.6 Parity and stop bit configuration

When parity is enabled through the PARITY field in the CONFIG register, the parity will be generated automatically from the even parity of TXD and RXD for transmission and reception respectively.

The amount of stop bits can be configured through the STOP field in the CONFIG register.

6.19.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOPTX and STOPRX tasks may not be always needed (the peripheral might already be stopped), but if STOPTX and/or STOPRX is sent, software shall wait until the TXSTOPPED and/or RXTO event is received in response, before disabling the peripheral through the ENABLE register.



6.19.8 Pin configuration

The different signals RXD, CTS (Clear To Send, active low), RTS (Request To Send, active low), and TXD associated with the UARTE are mapped to physical pins according to the configuration specified in the PSEL.RXD, PSEL.RTS, and PSEL.TXD registers respectively.

The PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers and their configurations are only used as long as the UARTE is enabled, and retained only for the duration the device is in ON mode. PSEL.RXD, PSEL.RTS, PSEL.RTS and PSEL.TXD must only be configured when the UARTE is disabled.

To secure correct signal levels on the pins by the UARTE when the system is in OFF mode, the pins must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 334.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

UARTE signal	UARTE pin	Direction	Output value
RXD	As specified in PSEL.RXD	Input	Not applicable
CTS	As specified in PSEL.CTS	Input	Not applicable
RTS	As specified in PSEL.RTS	Output	1
TXD	As specified in PSEL.TXD	Output	1

Table 91: GPIO configuration before enabling peripheral

6.19.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000		UARTE0 : S			Universal asynchronous	
0x40008000	UARTE	UARTEO : NS	US	SA	receiver/transmitter with	
0x40006000		UARTEU . NS			EasyDMA 0	
0x50009000		UARTE1:S			Universal asynchronous	
0x40009000	UARTE	UARTE1: NS	US	SA	receiver/transmitter with	
0.40003000		OANTEL . NO			EasyDMA 1	
0x5000A000		UARTE2 : S			Universal asynchronous	
0x4000A000	UARTE	UARTE2 : NS	US	SA	receiver/transmitter with	
0.4000A000		OARTEZ . NO			EasyDMA 2	
0x5000B000		UARTE3 : S			Universal asynchronous	
0x4000B000	UARTE	UARTE3 : NS	US	SA	receiver/transmitter with	
0.40000000		OANIES . NS			EasyDMA 3	

Table 92: Instances

Register	Offset	Security	Description
TASKS_STARTRX	0x000		Start UART receiver
TASKS_STOPRX	0x004		Stop UART receiver
TASKS_STARTTX	0x008		Start UART transmitter
TASKS_STOPTX	0x00C		Stop UART transmitter
TASKS_FLUSHRX	0x02C		Flush RX FIFO into RX buffer
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STOPRX	0x084		Subscribe configuration for task STOPRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOPTX	0x08C		Subscribe configuration for task STOPTX
SUBSCRIBE_FLUSHRX	0x0AC		Subscribe configuration for task FLUSHRX
EVENTS_CTS	0x100		CTS is activated (set low). Clear To Send.



Register	Offset	Security	Description
EVENTS_NCTS	0x104		CTS is deactivated (set high). Not Clear To Send.
EVENTS_RXDRDY	0x108		Data received in RXD (but potentially not yet transferred to Data RAM)
EVENTS_ENDRX	0x110		Receive buffer is filled up
EVENTS_TXDRDY	0x11C		Data sent from TXD
EVENTS_ENDTX	0x120		Last TX byte transmitted
EVENTS_ERROR	0x124		Error detected
EVENTS_RXTO	0x144		Receiver timeout
EVENTS_RXSTARTED	0x14C		UART receiver has started
EVENTS_TXSTARTED	0x150		UART transmitter has started
EVENTS_TXSTOPPED	0x158		Transmitter stopped
PUBLISH_CTS	0x180		Publish configuration for event CTS
PUBLISH_NCTS	0x184		Publish configuration for event NCTS
PUBLISH_RXDRDY	0x188		Publish configuration for event RXDRDY
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_TXDRDY	0x19C		Publish configuration for event TXDRDY
PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_RXTO	0x1C4		Publish configuration for event RXTO
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_TXSTOPPED	0x1D8		Publish configuration for event TXSTOPPED
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x480		Error source
			Note : this register is read / write one to clear.
ENABLE	0x500		Enable UART
PSEL.RTS	0x508		Pin select for RTS signal
PSEL.TXD	0x50C		Pin select for TXD signal
PSEL.CTS	0x510		Pin select for CTS signal
PSEL.RXD	0x514		Pin select for RXD signal
BAUDRATE	0x524		Baud rate. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
CONFIG	0x56C		Configuration of parity and hardware flow control

Table 93: Register overview

6.19.9.1 TASKS_STARTRX

Address offset: 0x000 Start UART receiver



Bit n	um	nber			313	0 29	28	27 2	26 2	25 2	4 2	23 2	22 :	21	20	19	18 :	17	16 1	15 :	14 1	.3 1	12 :	11	10	9	8	7	6	5	4	3 2	2	1 0
ID																																		Α
Rese	et O)x00	000000		0 (0	0	0	0	0 (י	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (D O
ID																																		
Α	٧	N	TASKS_STARTRX								9	itar	tι	JAR	RT r	ece	ive	r																
				Trigger	1						1	rig	gei	r ta	sk																			

6.19.9.2 TASKS_STOPRX

Address offset: 0x004 Stop UART receiver

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOPRX			Stop UART receiver
		Trigger	1	Trigger task

6.19.9.3 TASKS_STARTTX

Address offset: 0x008
Start UART transmitter

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STARTTX			Start UART transmitter
		Trigger	1	Trigger task

6.19.9.4 TASKS_STOPTX

Address offset: 0x00C Stop UART transmitter

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	W TASKS_STOPTX			Stop UART transmitter
		Trigger	1	Trigger task

6.19.9.5 TASKS_FLUSHRX

Address offset: 0x02C

Flush RX FIFO into RX buffer



Bit n	um	nber			31 30 2	29 28	27 2	6 25	5 24	23 2	22 2	21 20	0 19	18	17 :	16 1	.5 1	.4 13	3 12	11	10	9	8 7	' 6	5	4	3	2	1 0
ID																													Α
Rese	et O)x00	000000		0 0	0 0	0 0	0	0	0	0	0 0	0	0	0	0 (0 (0 0	0	0	0	0	0 0) (0	0	0	0	0 0
ID																													
Α	٧	Ν	TASKS_FLUSHRX							Flus	h F	RX FI	FO	nto	RX	buf	fer												
				Trigger	1					Trig	ger	tas	k																

6.19.9.6 SUBSCRIBE_STARTRX

Address offset: 0x080

Subscribe configuration for task STARTRX

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STARTRX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.19.9.7 SUBSCRIBE_STOPRX

Address offset: 0x084

Subscribe configuration for task STOPRX

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STOPRX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.19.9.8 SUBSCRIBE_STARTTX

Address offset: 0x088

Subscribe configuration for task ${\sf STARTTX}$

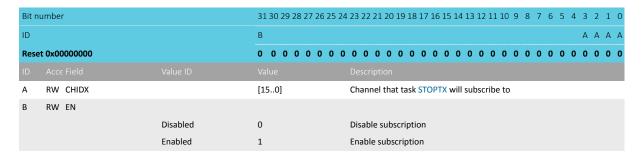
Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	ААА
Rese	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task STARTTX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.19.9.9 SUBSCRIBE_STOPTX

Address offset: 0x08C



Subscribe configuration for task STOPTX



6.19.9.10 SUBSCRIBE_FLUSHRX

Address offset: 0x0AC

Subscribe configuration for task FLUSHRX

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	A A A A
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task FLUSHRX will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.19.9.11 EVENTS_CTS

Address offset: 0x100

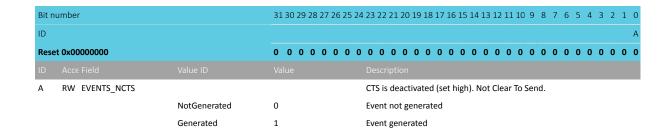
CTS is activated (set low). Clear To Send.

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				Α
Rese	et 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW EVENTS_CTS			CTS is activated (set low). Clear To Send.
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.19.9.12 EVENTS_NCTS

Address offset: 0x104

CTS is deactivated (set high). Not Clear To Send.



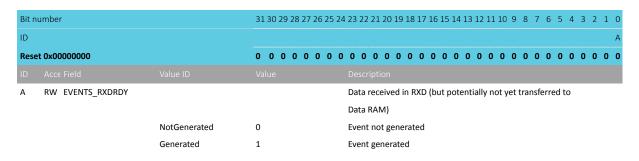




6.19.9.13 EVENTS_RXDRDY

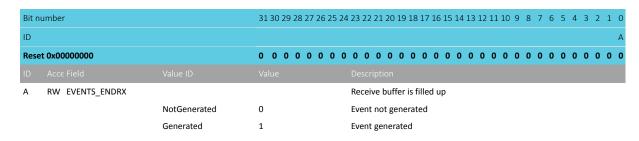
Address offset: 0x108

Data received in RXD (but potentially not yet transferred to Data RAM)



6.19.9.14 EVENTS_ENDRX

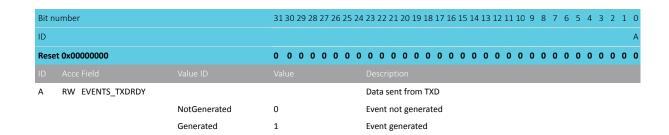
Address offset: 0x110 Receive buffer is filled up



6.19.9.15 EVENTS_TXDRDY

Address offset: 0x11C

Data sent from TXD



6.19.9.16 EVENTS_ENDTX

Address offset: 0x120 Last TX byte transmitted



Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_ENDTX			Last TX byte transmitted
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.19.9.17 EVENTS_ERROR

Address offset: 0x124

Error detected

Bit n	umber		31	30	29	28 2	27 26	5 25	24	23	22	21 2	20 1	19 1	3 17	16	15	14 :	13 1	2 11	. 10	9	8 7	7 6	5 5	4	3	2	1 0
ID																													Α
Rese	t 0x00000000		0	0	0	0	0 0	0	0	0	0	0	0	0 0	0	0	0	0	0 (0	0	0	0 () (0	0	0	0	0 0
ID																													
Α	RW EVENTS_ERROR									Err	ror (dete	ecte	ed															
		NotGenerated	0							Eve	ent	not	gei	nera	ted														
		Generated	1							Eve	ent	gen	era	ted															

6.19.9.18 EVENTS_RXTO

Address offset: 0x144 Receiver timeout

Bit number	31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A RW EVENTS_RXTO		Receiver timeout
NotGenerated	0	Event not generated
Generated	1	Event generated

6.19.9.19 EVENTS_RXSTARTED

Address offset: 0x14C
UART receiver has started

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW EVENTS_RXSTARTED			UART receiver has started
		NotGenerated	0	Event not generated
		Generated	1	Event generated

6.19.9.20 EVENTS_TXSTARTED

Address offset: 0x150

UART transmitter has started

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_TXSTARTED			UART transmitter has started
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.19.9.21 EVENTS_TXSTOPPED

Address offset: 0x158 Transmitter stopped

Bit n	umber		31	30	29 2	28 2	7 26	25	24 2	23 2	22 2	1 20	0 19	18	17 1	6 1	5 14	13	12 1	1 10	9	8	7	6	5 -	4 3	2	1 0
ID																												А
Rese	t 0x00000000		0	0	0	0 0	0	0	0	0 (0 0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0 0	0	0 0
ID																												
Α	RW EVENTS_TXSTOPPED								1	Γran	nsm	itte	r sto	oppe	ed													
		NotGenerated	0						E	ever	nt n	ot g	gene	erate	ed													
		Generated	1						E	ever	nt g	ene	rate	ed														

6.19.9.22 PUBLISH_CTS

Address offset: 0x180

Publish configuration for event CTS

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event CTS will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.19.9.23 PUBLISH_NCTS

Address offset: 0x184

Publish configuration for event NCTS

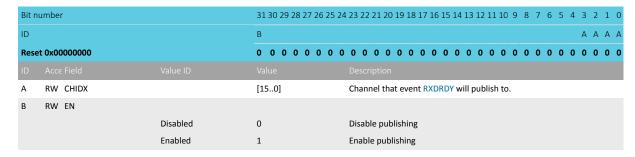
Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				
Α	RW CHIDX		[150]	Channel that event NCTS will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.19.9.24 PUBLISH_RXDRDY

Address offset: 0x188



Publish configuration for event RXDRDY



6.19.9.25 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		В	АААА
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CHIDX		[150]	Channel that event ENDRX will publish to.
B RW EN			
	Disabled	0	Disable publishing
	Enabled	1	Enable publishing

6.19.9.26 PUBLISH_TXDRDY

Address offset: 0x19C

Publish configuration for event TXDRDY

Bit n	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event TXDRDY will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.19.9.27 PUBLISH_ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX



Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
ID			В	A A A /
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event ENDTX will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.19.9.28 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR

Bit n	umber		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID			В	ААА
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that event ERROR will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.19.9.29 PUBLISH_RXTO

Address offset: 0x1C4

Publish configuration for event RXTO

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event RXTO will publish to.
В	RW EN			
		Disabled	0	Disable publishing

6.19.9.30 PUBLISH_RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED

Bit n	umber		31 30 29 28 27 26 2	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1		
ID			В	АААА		
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID						
Α	RW CHIDX		[150]	Channel that event RXSTARTED will publish to.		
В	RW EN					
		Disabled	0	Disable publishing		
		Enabled	1	Enable publishing		

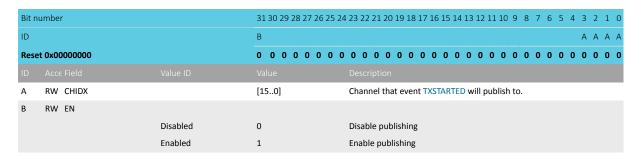




6.19.9.31 PUBLISH_TXSTARTED

Address offset: 0x1D0

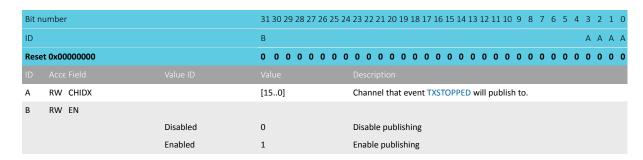
Publish configuration for event TXSTARTED



6.19.9.32 PUBLISH_TXSTOPPED

Address offset: 0x1D8

Publish configuration for event TXSTOPPED



6.19.9.33 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit r	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
С	RW ENDRX_STARTRX			Shortcut between event ENDRX and task STARTRX
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut
D	RW ENDRX_STOPRX			Shortcut between event ENDRX and task STOPRX
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut

6.19.9.34 INTEN

Address offset: 0x300

Enable or disable interrupt



Bit n	number		31 30 29 28 27 26 3	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
ID	idilibei			L J I H G F E D C B A
	-+ 0::0000000		0 0 0 0 0	
	et 0x00000000			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	Acce Field	Value ID	Value	Description CTS
Α	RW CTS	Divided I	0	Enable or disable interrupt for event CTS
		Disabled	0	Disable
В	RW NCTS	Enabled	1	Enable
Б	RVV INCIS	Disabled	0	Enable or disable interrupt for event NCTS Disable
			1	Enable
С	RW RXDRDY	Enabled	1	
C	KW KADRDI	Disabled	0	Enable or disable interrupt for event RXDRDY Disable
		Enabled	1	Enable
D	RW ENDRX	Enabled	1	Enable or disable interrupt for event ENDRX
U	NVV ENDRA	Disabled	0	Disable
		Enabled	1	Enable
E	RW TXDRDY	Lilabled	1	Enable or disable interrupt for event TXDRDY
-	KW INDIE	Disabled	0	Disable
		Enabled	1	Enable
F	RW ENDTX	Enabled	<u> </u>	Enable or disable interrupt for event ENDTX
		Disabled	0	Disable
		Enabled	1	Enable
G	RW ERROR			Enable or disable interrupt for event ERROR
		Disabled	0	Disable
		Enabled	1	Enable
Н	RW RXTO			Enable or disable interrupt for event RXTO
		Disabled	0	Disable
		Enabled	1	Enable
I	RW RXSTARTED			Enable or disable interrupt for event RXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
J	RW TXSTARTED			Enable or disable interrupt for event TXSTARTED
		Disabled	0	Disable
		Enabled	1	Enable
L	RW TXSTOPPED			Enable or disable interrupt for event TXSTOPPED
		Disabled	0	Disable
		Enabled	1	Enable

6.19.9.35 INTENSET

Address offset: 0x304

Enable interrupt

Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			L J I H G F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW CTS			Write '1' to enable interrupt for event CTS
	Set	1	Enable
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled
B RW NCTS			Write '1' to enable interrupt for event NCTS
	Set	1	Enable



Bit r	number		31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
ID				L J I H G F E D C B A
	et 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to enable interrupt for event RXDRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ENDRX			Write '1' to enable interrupt for event ENDRX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW TXDRDY			Write '1' to enable interrupt for event TXDRDY
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW ENDTX			Write '1' to enable interrupt for event ENDTX
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW ERROR			Write '1' to enable interrupt for event ERROR
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW RXTO			Write '1' to enable interrupt for event RXTO
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
I	RW RXSTARTED			Write '1' to enable interrupt for event RXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW TXSTARTED			Write '1' to enable interrupt for event TXSTARTED
		Set	1	Enable
		Disabled	0	Read: Disabled
	DW TYCTODDED	Enabled	1	Read: Enabled
L	RW TXSTOPPED	Cat	1	Write '1' to enable interrupt for event TXSTOPPED
		Set	1	Enable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.19.9.36 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	L J I H G F E D C B A
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	Value Description

A RW CTS Write '1' to disable interrupt for event CTS



Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				L J I H G F E D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
В	RW NCTS			Write '1' to disable interrupt for event NCTS
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
С	RW RXDRDY			Write '1' to disable interrupt for event RXDRDY
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ENDRX			Write '1' to disable interrupt for event ENDRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
E	RW TXDRDY	Endored	-	Write '1' to disable interrupt for event TXDRDY
-	NW INDIE	Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW ENDTX	Lilabieu	1	Write '1' to disable interrupt for event ENDTX
-	RW ENDIA	Clear	1	Disable
		Disabled	0	Read: Disabled
_	DW FDDOD	Enabled	1	Read: Enabled
G	RW ERROR	Class.	4	Write '1' to disable interrupt for event ERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
	D	Enabled	1	Read: Enabled
Н	RW RXTO			Write '1' to disable interrupt for event RXTO
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
ı	RW RXSTARTED			Write '1' to disable interrupt for event RXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW TXSTARTED			Write '1' to disable interrupt for event TXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
L	RW TXSTOPPED			Write '1' to disable interrupt for event TXSTOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.19.9.37 ERRORSRC

Address offset: 0x480

Error source

Note: this register is read / write one to clear.



Bit r	number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Res	et 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW OVERRUN			Overrun error
				A start bit is received while the previous data still lies in
				RXD. (Previous data is lost.)
		NotPresent	0	Read: error not present
		Present	1	Read: error present
В	RW PARITY			Parity error
				A character with bad parity is received, if HW parity check is
				enabled.
		NotPresent	0	Read: error not present
		Present	1	Read: error present
С	RW FRAMING			Framing error occurred
				A valid stop bit is not detected on the serial data input after
				all bits in a character have been received.
		NotPresent	0	Read: error not present
		Present	1	Read: error present
D	RW BREAK			Break condition
				The serial data input is '0' for longer than the length of a
				data frame. (The data frame length is 10 bits without parity
				bit, and 11 bits with parity bit.).
		NotPresent	0	Read: error not present
		Present	1	Read: error present

6.19.9.38 ENABLE

Address offset: 0x500

Enable UART

Bit number		31 30 29 28 2	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АААА
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			Description
A RW ENABLE			Enable or disable UARTE
	Disabled	0	Disable UARTE
	Enabled	8	Enable UARTE

6.19.9.39 PSEL.RTS

Address offset: 0x508

Pin select for RTS signal



Bit no	umber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C	A A A A
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.19.9.40 PSEL.TXD

Address offset: 0x50C

Pin select for TXD signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.19.9.41 PSEL.CTS

Address offset: 0x510

Pin select for CTS signal

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

6.19.9.42 PSEL.RXD

Address offset: 0x514

Pin select for RXD signal

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			С	АААА
Rese	t 0xFFFFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
С	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

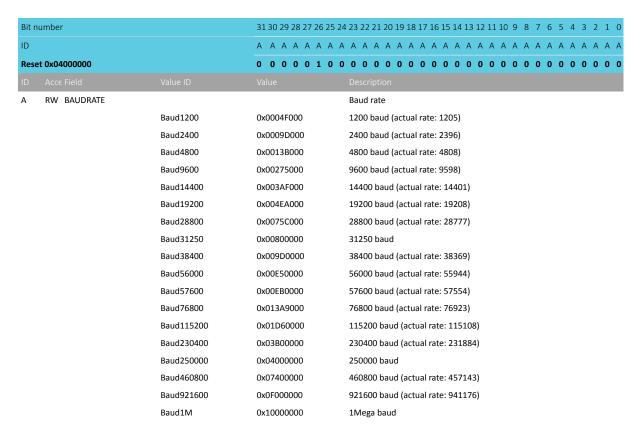




6.19.9.43 BAUDRATE

Address offset: 0x524

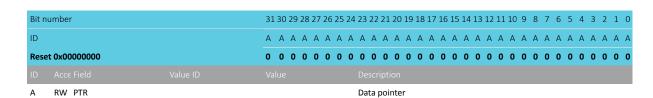
Baud rate. Accuracy depends on the HFCLK source selected.



6.19.9.44 RXD.PTR

Address offset: 0x534

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.45 RXD.MAXCNT

Address offset: 0x538

4418_1177 v0.7.1

Maximum number of bytes in receive buffer

350 NORDIC*

Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 1 D
ID A A A A A A A A A A A A A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 1

6.19.9.46 RXD.AMOUNT

Address offset: 0x53C

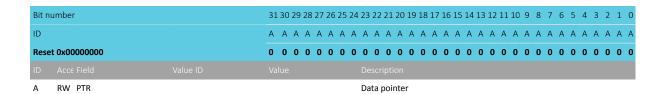
Number of bytes transferred in the last transaction

A R AM	OUNT	[10)x1F	FF]				Nu	mb	er o	of by	tes	tran	sfe	rred	in t	he I	ast	trar	ısad	tior	1					
ID Acce Fiel																											
Reset 0x00000	000	0	0 0	0	0 0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0 0) (0	0	0	0	0 0
ID																	Α	Α	Α	Α	A A	<i>A</i>	A	Α	Α	Α	A A
Bit number		313	0 29	9 28 :	27 2	6 25	24	23	22 :	21 2	20 1	9 18	17	16	15 1	4 13	3 12	11	10	9	8 7	' 6	5	4	3	2	1 0

6.19.9.47 TXD.PTR

Address offset: 0x544

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.48 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

Δ	RW MAXCNT	[10x1FFF]	Maximum number of bytes in transmit buffer
ID			
Res	et 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			A A A A A A A A A A A A A A A A A A A
Bit r	number	31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.19.9.49 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last transaction

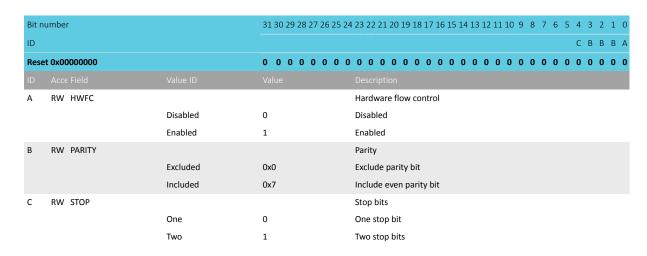


A R AMOUNT	[10x1FFF]	Number of bytes transferred in the last transaction
ID Acce Field		Description
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID		A A A A A A A A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.19.9.50 CONFIG

Address offset: 0x56C

Configuration of parity and hardware flow control



6.19.10 Electrical specification

6.19.10.1 UARTE electrical specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{UARTE}	Baud rate for UARTE ¹⁶ .			1000	kbps
t _{UARTE,CTSH}	CTS high time	1			μs
t _{UARTE.START}	Time from STARTRX/STARTTX task to transmission started				μs

6.20 WDT — Watchdog timer

A countdown watchdog timer using the low-frequency clock source (LFCLK) offers configurable and robust protection against application lock-up.

The watchdog timer is started by triggering the START task.

The watchdog can be paused during long CPU sleep periods for low power applications and when the debugger has halted the CPU. The watchdog is implemented as a down-counter that generates a TIMEOUT event when it wraps over after counting down to 0. When the watchdog timer is started through the START task, the watchdog counter is loaded with the value specified in the CRV register. This counter is also reloaded with the value specified in the CRV register when a reload request is granted.



High baud rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

The watchdog's timeout period is given by:

```
timeout [s] = ( CRV + 1 ) / 32768
```

When started, the watchdog will automatically force the 32.768 kHz RC oscillator on as long as no other 32.768 kHz clock source is running and generating the 32.768 kHz system clock, see chapter CLOCK — Clock control on page 64.

6.20.1 Reload criteria

The watchdog has eight separate reload request registers, which shall be used to request the watchdog to reload its counter with the value specified in the CRV register. To reload the watchdog counter, the special value 0x6E524635 needs to be written to all enabled reload registers.

One or more RR registers can be individually enabled through the RREN register.

6.20.2 Temporarily pausing the watchdog

By default, the watchdog will be active counting down the down-counter while the CPU is sleeping and when it is halted by the debugger. It is however possible to configure the watchdog to automatically pause while the CPU is sleeping as well as when it is halted by the debugger.

6.20.3 Watchdog reset

A TIMEOUT event will automatically lead to a watchdog reset.

See Reset on page 54 for more information about reset sources. If the watchdog is configured to generate an interrupt on the TIMEOUT event, the watchdog reset will be postponed with two 32.768 kHz clock cycles after the TIMEOUT event has been generated. Once the TIMEOUT event has been generated, the impending watchdog reset will always be effectuated.

The watchdog must be configured before it is started. After it is started, the watchdog's configuration registers, which comprise registers CRV, RREN, and CONFIG, will be blocked for further configuration.

The watchdog can be reset from several reset sources, see Reset behavior on page 55.

When the device starts running again, after a reset, or waking up from OFF mode, the watchdog configuration registers will be available for configuration again.

6.20.4 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50018000	WDT	WDT:S	US	NA	Watchdog timer	
0x40018000	וטייי	WDT : NS	03	INA	wateriog timer	

Table 94: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Start the watchdog
SUBSCRIBE_START	0x080		Subscribe configuration for task START
EVENTS_TIMEOUT	0x100		Watchdog timeout
PUBLISH_TIMEOUT	0x180		Publish configuration for event TIMEOUT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RUNSTATUS	0x400		Run status



Register	Offset	Security	Description
REQSTATUS	0x404		Request status
CRV	0x504		Counter reload value
RREN	0x508		Enable register for reload request registers
CONFIG	0x50C		Configuration register
RR[0]	0x600		Reload request 0
RR[1]	0x604		Reload request 1
RR[2]	0x608		Reload request 2
RR[3]	0x60C		Reload request 3
RR[4]	0x610		Reload request 4
RR[5]	0x614		Reload request 5
RR[6]	0x618		Reload request 6
RR[7]	0x61C		Reload request 7

Table 95: Register overview

6.20.4.1 TASKS_START

Address offset: 0x000 Start the watchdog

Bit n	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	W TASKS_START			Start the watchdog
		Trigger	1	Trigger task

6.20.4.2 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW CHIDX		[150]	Channel that task START will subscribe to
В	RW EN			
		Disabled	0	Disable subscription
		Enabled	1	Enable subscription

6.20.4.3 EVENTS_TIMEOUT

Address offset: 0x100 Watchdog timeout



Bit number		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A RW EVENTS_TIMEOUT			Watchdog timeout
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.20.4.4 PUBLISH_TIMEOUT

Address offset: 0x180

Publish configuration for event TIMEOUT

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW CHIDX		[150]	Channel that event TIMEOUT will publish to.
В	RW EN			
		Disabled	0	Disable publishing
		Enabled	1	Enable publishing

6.20.4.5 INTENSET

Address offset: 0x304

Enable interrupt

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6	5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0
ID Acce Field Value ID		
A RW TIMEOUT	Write '1' to enable interrupt for event TIMEOUT	
Set	1 Enable	
Disabled	0 Read: Disabled	
Enabled	1 Read: Enabled	

6.20.4.6 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A
Rese	et 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
Α	RW TIMEOUT			Write '1' to disable interrupt for event TIMEOUT
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled



6.20.4.7 RUNSTATUS

Address offset: 0x400

Run status

Bit number		31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R RUNSTATUSWDT			Indicates whether or not the watchdog is running
	NotRunning	0	Watchdog not running
	Running	1	Watchdog is running

6.20.4.8 REQSTATUS

Address offset: 0x404

Request status

Bit number		31 30 29 28 27 26 25 2	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0								
ID			H G F E D C B A								
Reset 0x00000001		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0								
ID Acce Field			Description								
A-H R RR[i] (i=07)			Request status for RR[i] register								
	DisabledOrRequested		RR[i] register is not enabled, or are already requesting								
			reload								
	EnabledAndUnrequeste	14	RR[i] register is enabled, and are not yet requesting reload								

6.20.4.9 CRV

Address offset: 0x504 Counter reload value

Bit n	umber	31 3	0 29	28	27	26	25	24	23 :	22 :	21 2	20 1	9 1	8 17	16	15	14	13 1	2 1	1 10	9	8	7	6	5	4	3 2	1	0
ID		Α Α	A A	Α	Α	Α	Α	Α	Α	Α	Α	A A	\ <i>A</i>	A	Α	Α	Α	Α .	Δ Δ	A	Α	Α	Α	Α	Α	Α	ΑА	A	Α
Rese	t OxFFFFFFF	1 1	l 1	1	1	1	1	1	1	1	1	1 1	l 1	. 1	1	1	1	1	1 1	. 1	1	1	1	1	1	1	1 1	1	1
ID									Des																				
Α	RW CRV	[0x0]	000	000	F0	xFF	FFF	FFI	E j ot	unte	er r	eloa	ıd v	alue	in	nur	nbe	er of	сус	les	of t	he :	32.	768	kH	lz			
									clo	ck																			

6.20.4.10 RREN

Address offset: 0x508

Enable register for reload request registers

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			HGFEDCBA
Reset 0x00000001		0 0 0 0 0 0 0	$\begin{smallmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 $
ID Acce Field V			
A-H RW RR[i] (i=07)			Enable or disable RR[i] register
D	isabled	0	Disable RR[i] register
E	nabled	1	Enable RR[i] register





6.20.4.11 CONFIG

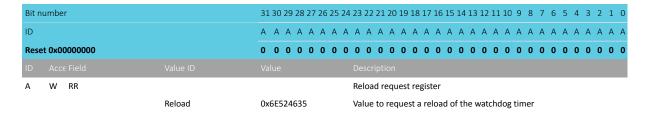
Address offset: 0x50C Configuration register

Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			C A
Reset 0x00000001		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID Acce Field Va			Description
A RW SLEEP			Configure the watchdog to either be paused, or kept
			running, while the CPU is sleeping
Pa	ause	0	Pause watchdog while the CPU is sleeping
R	tun	1	Keep the watchdog running while the CPU is sleeping
C RW HALT			Configure the watchdog to either be paused, or kept
			running, while the CPU is halted by the debugger
Pa	ause	0	Pause watchdog while the CPU is halted by the debugger
R	tun	1	Keep the watchdog running while the CPU is halted by the
			debugger

6.20.4.12 RR[n] (n=0..7)

Address offset: $0x600 + (n \times 0x4)$

Reload request n



6.20.5 Electrical specification

6.20.5.1 Watchdog Timer Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t_{WDT}	Time out interval	31 µs		36 h	



7 LTE modem

7.1 Introduction

The long term evolution (LTE) modem consists of baseband processing and RF parts, which together implement a complete 3GPP LTE release 13 (Rel-13) Cat-M1 and Cat-NB1 and LTE release 14 (Rel-14) Cat-NB1 and Cat-NB2 capable product.

As illustrated in the image below, the following is a part of the LTE modem:

- RF transceiver
- Modem baseband (BB)
- Embedded flash/RAM
- Modem host processor and peripherals

The modem baseband and host processor provide functions for the LTE L1, L2 and L3 (layer 1, 2 and 3 respectively) as well as IP communication layers. Modem peripherals provide hardware services for modem operating system and for modem secure execution environment.

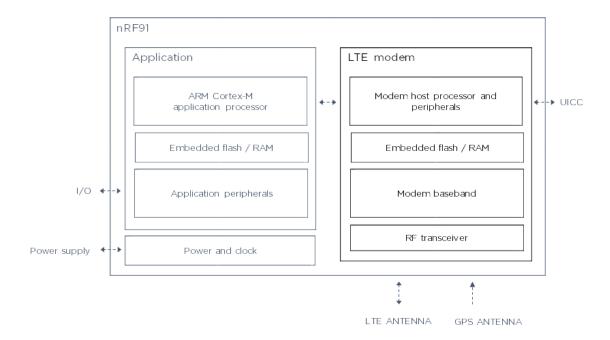


Figure 106: LTE modem within the nRF91

Application and modem domains are interacting through interprocessor communication (IPC) mechanism. LTE modem is accessible to user through the modem API.



The application processor is the master in the system and responsible for starting and stopping of the modem. LTE modem enables the clocks and power required for its own operation. Shared resources, such as e.g. clocks, are handled within the platform and require no user involvement. In cases where a hard fault is detected in the modem, the application domain will perform a hard reset for the modem.

Note: For details regarding the modem API, please refer to *nRF Connect SDK* document and *nRF91 AT Commands, Command Reference Guide* document.

Key features of the LTE modem are:

- Complete modem with baseband and RF transceiver
- 3GPP release 13 compliant LTE categories:
 - Cat-M1 (eMTC enhanced machine type communication)
 - Cat-NB1 (NB-IoT narrowband internet of things (IoT))
- 3GPP release 14 compliant LTE categories:
 - Cat-NB1 (NB-IoT)
 - Cat-NB2 (NB-IoT)
- · Power saving modes
- Supporting LTE bands from 700 MHz to 2.2 GHz through a single typical 50 Ω antenna pin.
- RX sensitivity: -108 dBm for Cat-M1 and -114 dBm for Cat-NB1 and Cat-NB2
 - As defined in 3GPP conformance test specification TS 36.521-1
- 1.8 V MIPI RFFE (RF front-end) digital control interface and MAGPIO control interface for external RF applications.
- 1.8 V UICC (universal integrated circuit card) interface, based on ISO/IEC 7816-3 and compliant with:
 - ICC (ETSI TS 102 221)
 - eUICC (ETSI TS 103 383)

Note: nRF9160 is able to run different modem FW builds that define the final modem feature set in a specific nRF9160 based application.

7.2 SIM card interface

LTE modem supports the UICC (universal integrated circuit card) interface.

Only the UICCs with the electrical interface specified in ISO/IEC 7816-3 are supported, meaning that the UICCs with IC-USB, CLF or MMC interfaces are not supported.

The supported UICC/eUICC interface is compliant with:

- ETSI TS 102 221: Smart Cards; UICC-Terminal interface; Physical and logical characteristics
- ETSI TS 103 383: Smart Cards; Embedded UICC; Requirements Specification

The physical interface towards the eUICC is the same as towards the removable UICC.

Only the class C (supply voltage 1.8 V nominal) operation is supported. Support for the legacy class B (supply voltage 3.0 V nominal) operation must be built with external components, including the external power supply and the level shifters towards the LTE modem UICC interface.

LTE modem controls the physical interfaces towards the UICC and implements the transport protocol over the four-pin ISO/IEC 7816-3 interface:

- VCC (power supply): LTE modem drives this
- · CLK (clock signal): LTE modem drives this
- RST (reset signal): LTE modem drives this



• I/O (input/output serial data): Bi-directional

The interface and the connections between LTE modem, UICC connector, and the ESD device is shown in the figure below.

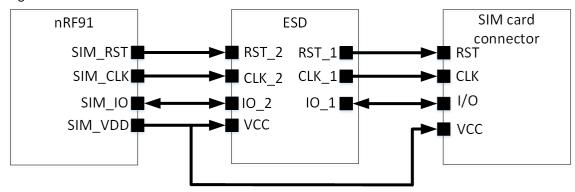


Figure 107: Connections between LTE modem, card connector, and the ESD device

Only standard transmission speeds are supported as specified in ETSI TS 102 221.

Important: LTE modem must be stopped through the modem API, before removing the UICC.

An ESD (electrostatic discharge) protection device compatible with UICC cards must be used between the removable card and the LTE modem, to protect LTE modem against a harmful electrostatic discharge from the card connector.

7.3 LTE modem coexistence interface

LTE modem uses a dedicated three-pin interface for RF interference avoidance towards a companion radio device e.g. an external Bluetooth[®] Low Energy device.

The inputs and outputs for this interface:

- COEXO: Input to the LTE modem from the external device. When active high, indicates that the external device transceiver is turned on.
- COEX1: Output from the LTE modem to the external device. Active high time mark pulse, which is synchronous to LTE system time.
- COEX2: Output from the LTE modem to the external device. When active high, indicates that the LTE modem transceiver is turned on.
 - COEX2 can also be treated as active low grant from LTE modem to the external device, indicating
 grant to transmit.
 - Note: COEX2 pin requires an external pull-down resistor in 100 k Ω size range to be used.

Simultaneous receiving by LTE modem and external device is always possible, and by so means no coexistence signaling needed when only receiving is done on the external device side.

7.4 LTE modem RF control external interface

LTE modem provides dedicated 1.8 V digital interfaces for controlling external RF applications, such as antenna tuner devices:

- MIPI RFFE interface pins: VIO, SCLK, SDATA.
- MAGPIO interface pins: MAGPIO0, MAGPIO1, MAGPIO2.



LTE modem drives these outputs timing accurately according to LTE protocol timing to set e.g. the correct antenna tuner settings per used frequency.

User needs to inform the LTE modem through the modem API about the particular RF application e.g. antenna tuner device configuration, so that LTE modem knows how to drive it.

Note: For details regarding the modem API and supported RF external control features, please refer to *nRF91 AT Commands, Command Reference Guide* document.

7.5 RF front-end interface

nRF9160 has a single-ended (SE) 50 Ω antenna interface to connect directly to antenna.

7.6 Electrical specification

7.6.1 Key RF parameters for Cat-M1

Note: The bands listed in this table define the certified bands.

Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE		
			Rel-13		
			Cat-M1		
			HD-FDD		
Bands supported	Certified bands supported		USA and		
			Canada:		
			B4, B13.		
			Europe:		
			B3, B20.		
Transmission	Maximum bandwidth		1.4		MHz
bandwidth					

7.6.2 Key RF parameters for Cat-NB1 and Cat-NB2

Note: The bands listed in this table define the certified bands.



Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE		
			Rel-13		
			Cat-		
			NB1 HD	•	
			FDD, LTE		
			Rel-14		
			Cat-NB1		
			and Cat-		
			NB2 HD	-	
			FDD		
Bands supported	Certified bands supported		For Cat-		
			NB1,		
			Europe:		
			B3, B20		
Transmission	Maximum bandwidth		200		kHz
bandwidth					

7.6.3 Receiver parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	RX operation frequency range at ANT (pin 61)	729		2200	MHz
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low	LTE 1.4 MHz without coverage extension	-103	-108		dBm
band					
Sensitivity, mid	LTE 1.4 MHz without coverage extension	-103	-107		dBm
band					

7.6.4 Receiver parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	RX operation frequency range at ANT (pin 61)	729		2200	MHz
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low	NB 200 kHz without coverage extension	-108	-114		dBm
band					
Sensitivity, mid	NB 200 kHz without coverage extension	-108	-113		dBm
band					

7.6.5 Transmitter parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
$Freq_{range_ANT_TX}$	TX operation frequency range at ANT (pin 61)	699		1910	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output	Maximum output power, 3GPP specification		23		dBm
power					
Minimum output	Minimum output power, 3GPP specification		-40		dBm
power					
Pout maximum	Pout maximum accuracy, internal specification		+-2		dB
accuracy					





7.6.6 Transmitter parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_TX}	TX operation frequency range at ANT (pin 61)	699		1910	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output power	Maximum output power, 3GPP specification		23		dBm
Minimum output	Minimum output power, 3GPP specification		-40		dBm
Pout maximum accuracy	>Pout maximum accuracy, Internal specification		+-2		dB



8 GPS receiver

The GPS receiver supports GPS L1C/A reception. Operation is time multiplexed with LTE modem, and it is possible to obtain the GPS position while LTE is in DRX or PSM mode.

GPS receiver is visible to user only through GPS API.

Key features of the GPS receiver are:

- GPS L1C/A is supported
- Modes of operation:
 - Single shot (cold start mode by default)
 - Position fix per fixed interval, e.g. 2 minutes (starts with cold start, sequential fixes with hot start)
- Power saving modes
- Antenna interface options:
 - Dedicated GPS antenna or shared antenna with LTE M1/NB1
 - With or without external low-noise amplifier (LNA)
- Performance:
 - Acquisition sensitivity: -144 dBm for cold start, -147 dBm for hot start
 - Acquisition time: 30 seconds for cold start, 5 seconds for hot start
 - Tracking sensitivity: -149 dBm (open sky received power ≥ -130 dBm)
 - Accuracy: 5 m



9 Debug and trace

9.1 Overview

The debug and trace system offers a flexible and powerful mechanism for non-intrusive debugging.

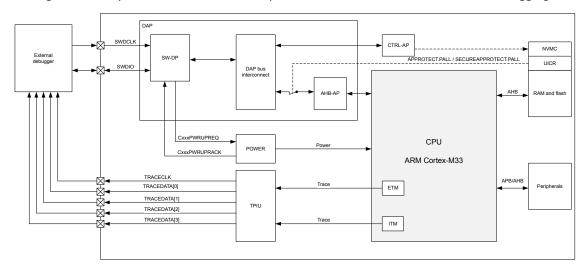


Figure 108: Debug and trace overview

The main features of the debug and trace system are:

- Two-pin serial wire debug (SWD) interface, protocol version 1
- Access port connection
 - Breakpoint unit (BPU) supports eight hardware breakpoint comparators
 - Data watchpoint and trace (DWT) unit supports four watchpoint comparators
 - Instrumentation trace macrocell (ITM)
 - Embedded trace macrocell (ETM)
 - Access protection through APPROTECT, ERASEPROTECT and SECUREAPPROTECT
- Trace port interface unit (TPUI)
 - 4-bit parallel trace of ITM and ETM trace data

Note: When a system contains multiple CPU domains, it is important to notice that if one domain (subsystem A) has master rights on another domain (subsystem B), the master subsystem can have access to data from the slave subsytem. In this example, even if subsystem B is locked by APPROTECT or ERASEPROTECT, subsystem A can access some data for subsystem B. Consequently, even if the security permissions are managed per subsystem, it is mandatory to have a global approach to the protection. Protecting a slave subsystem does not guarantee system security if the master subsystem is not protected.

9.1.1 Special consideration regarding debugger access

A debugger can be restricted to debug non-secure code only, and access non-secure memory regions and peripherals using register SECUREAPPROTECT on page 43. Register APPROTECT on page 42 will block all debugger access.

Debugger accesses are controlled as described in table below.



Debugging capability	UICR.APPROTECT.PALL	UICR.SECUREAPPROTECT.PALL
Secure and non-secure code	Unprotected	Unprotected
Non-secure code only	Unprotected	Protected
No debugging possible	Protected	-

Table 96: Debugger access control

If a RAM or flash region has its permission set to allow code execution, the content of this region will be visible to the debugger even if the read permission is not set. This allows a debugger to display the content of the code being executed.

9.1.2 DAP - Debug access port

An external debugger can access the device via the debug access port (DAP).

The DAP implements a standard ARM[®] CoreSight[™] serial wire debug port (SW-DP). The SW-DP implements the serial wire debug (SWD) protocol that is a two-pin serial interface, see SWDCLK and SWDIO illustrated in figure Debug and trace overview on page 365.

In addition to the default access port in the application CPU (AHB-AP), the DAP includes a custom control access port (CTRL-AP). The CTRL-AP is described in more detail in CTRL-AP - Control access port on page 368.

Note:

- The SWDIO line has an internal pull-up resistor.
- The SWDCLK line has an internal pull-down resistor.

There are several access ports that connect to different parts of the system. An overview is given in the table below.

AP ID	Туре	Description
0	AHB-AP	Application subsystem access port
4	CTRL-AP	Application subsystem control access port

Table 97: Access port overview

The AHB-AP and APB-AP are standard ARM[®] components, and documented in *ARM CoreSight SoC-400 Technical Reference Manual, revision r3p2*. The control access port (CTRL-AP) is proprietary, and described in more detail in CTRL-AP - Control access port on page 368.

9.1.3 Debug interface mode

Before the external debugger can access the CPU's access port (AHB-AP) or the control access port (CTRL-AP), the debugger must first request the device to power up via CxxxPWRUPREQ in the SWJ-DP.

As long as the debugger is requesting power via CxxxPWRUPREQ, the device will be in debug interface mode. Otherwise, the device is in normal mode. When a debug session is over, the external debugger must make sure to put the device back into normal mode and then a pin reset should be performed. The reason is that the overall power consumption is higher in debug interface mode compared to normal mode.

Some peripherals behave differently in debug interface mode compared to normal mode. The differences are described in more detail in the chapters of the peripherals that are affected.



For details on how to use the debug capabilities, please read the debug documentation of your IDE.

If the device is in System OFF when power is requested via CxxxPWRUPREQ, the system will wake up and the DIF flag in RESETREAS on page 63 will be set.

9.1.4 Real-time debug

The device supports real-time debugging, which allows interrupts to execute to completion in real time when breakpoints are set in thread mode or lower priority interrupts.

Real-time debugging thus enables the developer to set a breakpoint and single-step through their code without a failure of the real-time event-driven threads running at higher priority. For example, this enables the device to continue to service the high-priority interrupts of an external controller or sensor without failure or loss of state synchronization while the developer steps through code in a low-priority thread.

9.1.5 Trace

The device supports ETM and ITM trace.

Trace data from the ETM and the ITM is sent to an external debugger via a 4-bit wide parallel trace port (TPIU), see TRACEDATA[0] through TRACEDATA[3], and TRACECLK in Debug and trace overview on page 365.

For details on how to use the trace capabilities, please read the debug documentation of your IDE.

TPIU's trace pins are multiplexed with GPIOs, see Pin assignments on page 379 for more information.

Trace speed is configured in the TRACEPORTSPEED on page 378 register. The speed of the trace pins depends on the DRIVE setting of the GPIOs that the trace pins are multiplexed with. Only SOS1 and H0H1 drives are suitable for debugging. SOS1 is the default DRIVE at reset. If parallel or serial trace port signals are not fast enough in the debugging conditions, all GPIOs in use for tracing should be set to high drive (H0H1). The user shall make sure that DRIVE setting for these GPIOs is not overwritten by software during the debugging session.

9.1.6 Registers

Register	Offset	Security	Description
TARGETID	0x042		The TARGETID register provides information about the target when the host is
			connected to a single device.
			The TARGETID register is accessed by a read of DP register 0x4 when the
			DPBANKSEL bit in the SELECT register is set to 0x2.

Table 98: Register overview

9.1.6.1 TARGETID

Address offset: 0x042

The TARGETID register provides information about the target when the host is connected to a single device

The TARGETID register is accessed by a read of DP register 0x4 when the DPBANKSEL bit in the SELECT register is set to 0x2.



Bit n	umbe	er		31	30 29	9 2	8 27	7 26	6 25	5 24	1 23	3 22	21	20	19	18	17	16	15	14 :	13 1	2 13	1 10	9	8	7	6	5	4	3 2	2 1	. 0
ID				D	D D) [) C	. C	. C	С	C	. c	С	С	С	С	С	С				В	В	В	В	В	В	В	В	В	3 E	3 A
Rese	t 0x1	0090289		0	0 0) 1	L O	0	0	0	0	0	0	0	1	0	0	1	0	0	0	0 0	0	1	0	1	0	0	0	1 (0) 1
ID																																
Α	R	UNUSED									Re	eser	vec	d, re	ead	-as	-on	e														
В	R	TDESIGNER									Aı	n 11	L-bi	t co	de	JE	DEC) JE	P10)6 c	ont	inua	tio	n co	de	an	d					
										identity code. The ID identifies the designer of the part.																						
			NordicSemi	0x1	L44						N	ordi	ic S	emi	icor	ndu	cto	r A	SA													
С	R	TPARTNO									Pa	art n	num	nbe	r																	
			nRF91	9							nl	RF9:	1 Se	erie	S																	
D	R	TREVISION									Ta	arge	t re	visi	ion																	
			<keyword< td=""><td>1</td><th></th><th></th><td></td><td></td><td></td><td></td><td>nl</td><td>RF9:</td><td>160</td><td>)</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><th></th><th></th><td></td><td></td><td></td><td></td><td></td></keyword<>	1							nl	RF9:	160)																		
keyref="devicename" />																																

9.1.7 Electrical specification

9.1.7.1 Trace port

Symbol	Description	Min.	Тур.	Max.	Units
T _{cyc}	Clock period, as defined by ARM (See ARM Infocenter,				ns
	Embedded Trace Macrocell Architecture Specification, Trace				
	Port Physical Interface, Timing specifications)				

9.2 CTRL-AP - Control access port

The control access port (CTRL-AP) is a custom access port that enables control of the device when other access ports in the debug access port (DAP) are disabled by the access port protection.

For overview of other access ports in DAP, see DAP - Debug access port on page 366.

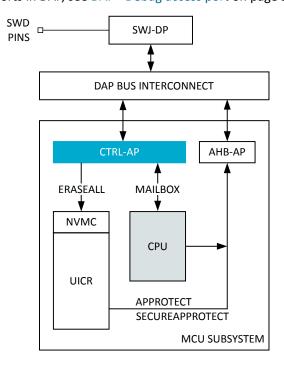


Figure 109: Control access port details



Access port protection (APPROTECT) blocks the debugger access to the AHB-AP, and prevents read and write access to all CPU registers and memory-mapped addresses. It is possible to enable access port protection for both secure and non-secure mode, using registers UICR.SECUREAPPROTECT and UICR.APPROTECT respectively. The debugger can use register APPROTECT.STATUS on page 372 to read the status of secure and non-secure access port protection.

Control access port has the following features:

- Soft reset
- Erase all
- Mailbox interface
- · Debug of protected devices

9.2.1 Reset request

The debugger can request the device to perform a soft reset.

Register RESET on page 371 is used to request the soft reset. Once the soft reset is performed, the reset reason is accessible to on-chip firmware through register. For more information about the soft reset, see Reset on page 54.

9.2.2 Erase all

Erase all function gives debugger the possibility of triggering an erase of flash, user information configuration registers (UICR), RAM, including all peripheral settings, as well as removing the access port protection.

To trigger an erase all function, the debugger can write the register ERASEALL on page 371. Register ERASEALLSTATUS on page 371 will read as busy for the duration of the operation. After the next reset, the access port protection is removed.

For slave MCU's, the ERASEALL command will also affect the application MCU. The ERASEALL command is performed on the application MCU first, independently of how the application is protected, and then on the slave MCU.

Erase all protection

It is possible to prevent debugger from performing an erase all operation by writing to register ERASEPROTECT on page 43. Once the register is configured and the device reset, the control access port ERASEALL operation is disabled, and all flash write and erase operations are restricted to firmware. In addition, it is still possible to write/erase from debugger as long as APPROTECT on page 42 is not set.

Note: Setting ERASEPROTECT on page 43 has no effect on debugger access, only on erase all operation.

Register ERASEPROTECT.STATUS on page 372 holds the status for erase protection.

9.2.3 Mailbox interface

CTRL-AP implements a mailbox interface which enables the CPU to communicate with a debugger over the SWD interface.

The mailbox interface consists of a transmit register MAILBOX.TXDATA on page 373 with its corresponding status register MAILBOX.TXSTATUS on page 373, and a receive register MAILBOX.RXDATA on page 373 with its corresponding status register MAILBOX.RXSTATUS on page 373. Status bits in registers TXSTATUS/RXSTATUS will be set and cleared automatically when registers TXDATA/RXDATA are written to and read from, independently of the direction.



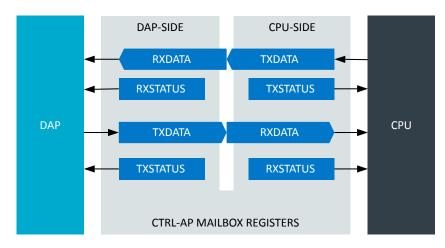


Figure 110: Mailbox register interface

Mailbox transfer sequence

- 1. Sender writes TXDATA
- 2. Hardware sets sender's TXSTATUS to DataPending
- 3. Hardware sets receiver's RXSTATUS to DataPending
- 4. Receiver reads RXDATA
- 5. Hardware sets receiver's RXSTATUS to NoDataPending
- 6. Hardware sets sender's TXSTATUS to NoDataPending

9.2.4 Unlocking of access port

The access port protection mechanisms can be temporarily bypassed to erase or debug the device.

Note: The mailbox feature of the CTRL-AP can be used by firmware to authenticate the debugger before allowing it to use the access port.

Disabling the erase all protection

To bypass ERASEPROTECT setting, making it possible for the access port to erase all memories, both the debugger and firmware must set the ERASEALL field in their respective ERASEPROTECTDISABLE registers. As soon as both registers have been written, the device is automatically erased using erase all function as described in Erase all on page 369, and then the access port is made available.

Note: To prevent misuse, the write-once register ERASEPROTECT.DISABLE on page 375 should be set to Default as early in the start-up process as possible. Once written, it will not be possible to remove the erase protection until next reset.

9.2.5 Registers

Register	Offset	Security	Description
RESET	0x000		Soft reset request.
ERASEALL	0x004		Perform a secure erase of the device. The device will be returned to factory
			default settings upon next reset.
ERASEALLSTATUS	0x008		Status register for the ERASEALL operation
APPROTECT.STATUS	0x00C		Status register for access port protection
ERASEPROTECT.STATUS	0x018		Status register for UICR ERASEPROTECT configuration
ERASEPROTECT.DISABLE	0x01C		Unlock ERASEPROTECT and perform ERASEALL



Register	Offset	Security	Description
MAILBOX.TXDATA	0x020		Data sent from the debugger to the CPU
MAILBOX.TXSTATUS	0x024		Status to indicate if data sent from the debugger to the CPU has been read
MAILBOX.RXDATA	0x028		Data sent from the CPU to the debugger
MAILBOX.RXSTATUS	0x02C		Status to indicate if data sent from the CPU to the debugger has been read
IDR	0x0FC		CTRL-AP Identification Register, IDR

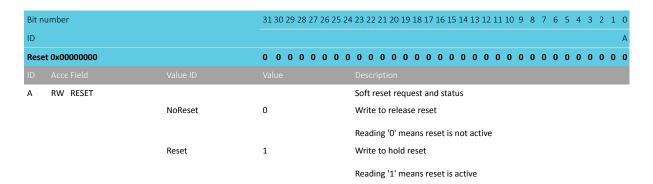
Table 99: Register overview

9.2.5.1 RESET

Address offset: 0x000

Soft reset request.

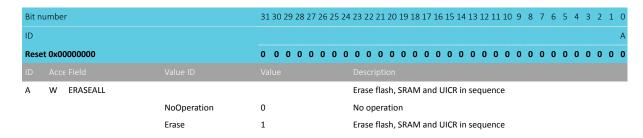
This register is automatically deactivated by writing Erase to ERASEALL, it is then kept inactive until a reset source affecting the debug system is asserted. See Reset behavior on page 55.



9.2.5.2 ERASEALL

Address offset: 0x004

Perform a secure erase of the device. The device will be returned to factory default settings upon next reset.



9.2.5.3 ERASEALLSTATUS

Address offset: 0x008

Status register for the ERASEALL operation



Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field			
A R ERASEALLSTATUS			Status register for the ERASEALL operation
	Ready	0	ERASEALL is ready
	Busy	1	ERASEALL is busy (on-going)

9.2.5.4 APPROTECT.STATUS

Address offset: 0x00C

Status register for access port protection

Bit n	umbe	er		31 30	29	28	3 27	26	25	24	23 2	2 2	21 2	0 1	19 1	.8 1	17 1	6 1	.5 1	.4 1	L3 1	2 1	11	o 9	8	7	6	5	4	3	2	1 0
ID																																ВА
Rese	t OxO	0000000		0 0	0	0	0	0	0	0	0	0	0 (0 (0 (0	0 ()	0	0	0	0 () (0	0	0	0	0	0	0	0	0 0
ID											Des																					
Α	R	APPROTECT									Stat	us	bit	for	aco	es	s po	rt	pro	te	tio	n										
			Enabled	0							APP	RO	TEC	Τi	s ei	nak	led															
			Disabled	1							APP	RO	TEC	Τi	s di	sal	olec	I														
В	R	SECUREAPPROTECT									Stat	us	bit	for	sec	ur	e ad	ce	ss p	or	t pr	ote	ctic	n								
			Enabled	0							SEC	URI	EAP	PR	ОТІ	ECT	۱is	ena	able	ed												
			Disabled	1							SEC	URI	EAP	PR	ОТІ	ECT	۱is	dis	abl	ed												

9.2.5.5 ERASEPROTECT.STATUS

Address offset: 0x018

Status register for UICR ERASEPROTECT configuration

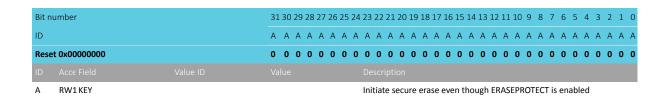
Bit number	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		А
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID		Description
A R PALL		ERASEALL status
Enabled	0	ERASEALL protection is enabled
Disabled	1	ERASELL protection is not enabled and device can be erased

9.2.5.6 ERASEPROTECT.DISABLE

Address offset: 0x01C

Unlock ERASEPROTECT and perform ERASEALL

This register can only be written once per reset



if KEY fields match

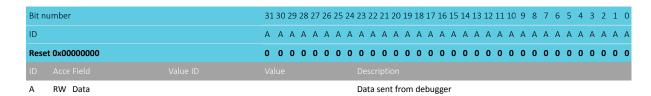


9.2.5.7 MAILBOX.TXDATA

Address offset: 0x020

Data sent from the debugger to the CPU

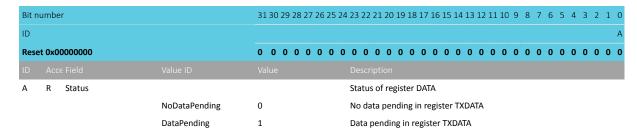
Writing to this register will automatically set field DataPending in register TXSTATUS



9.2.5.8 MAILBOX.TXSTATUS

Address offset: 0x024

Status to indicate if data sent from the debugger to the CPU has been read

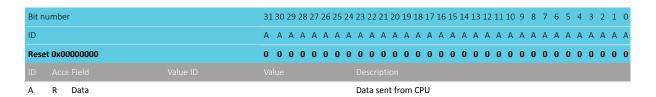


9.2.5.9 MAILBOX.RXDATA

Address offset: 0x028

Data sent from the CPU to the debugger

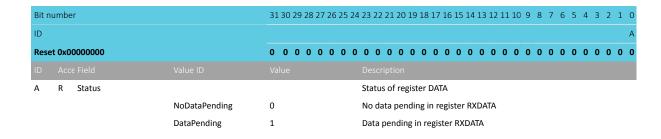
Reading from this register will automatically set field NoDataPending in register RXSTATUS



9.2.5.10 MAILBOX.RXSTATUS

Address offset: 0x02C

Status to indicate if data sent from the CPU to the debugger has been read



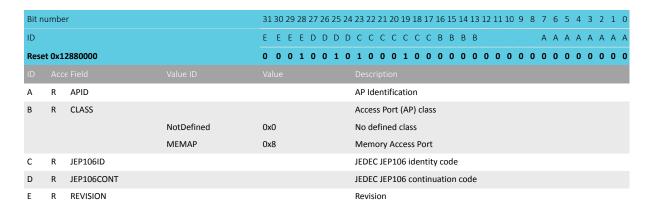




9.2.5.11 IDR

Address offset: 0x0FC

CTRL-AP Identification Register, IDR



9.2.6 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50006000	CTRLAPPERI	CTRL_AP_PE	RI S	NA	CTRL-AP-PERI	

Table 100: Instances

Register	Offset	Security	Description
MAILBOX.RXDATA	0x400		Data sent from the debugger to the CPU
MAILBOX.RXSTATUS	0x404		Status to indicate if data sent from the debugger to the CPU has been read
MAILBOX.TXDATA	0x480		Data sent from the CPU to the debugger
MAILBOX.TXSTATUS	0x484		Status to indicate if data sent from the CPU to the debugger status has been read
ERASEPROTECT.LOCK	0x500		Lock ERASEALL mechanism
ERASEPROTECT.DISABLE	0x504		Unlock ERASEPROTECT and perform ERASEALL

Table 101: Register overview

9.2.6.1 MAILBOX.RXDATA

Address offset: 0x400

Data sent from the debugger to the CPU

Reading from this register will automatically set field NoDataPending in register RXSTATUS

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	. A A A A A A A A A A A A A A A A A A A
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID Acce Field Value ID	Value	Description

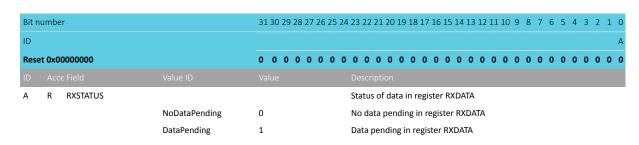
R RXDATA Data received from debugger

9.2.6.2 MAILBOX.RXSTATUS

Address offset: 0x404

Status to indicate if data sent from the debugger to the CPU has been read



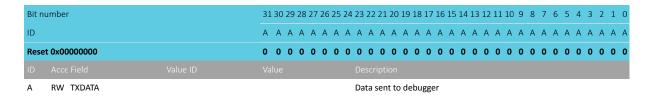


9.2.6.3 MAILBOX.TXDATA

Address offset: 0x480

Data sent from the CPU to the debugger

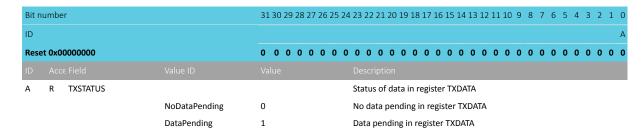
Writing to this register will automatically set field DataPending in register TXSTATUS



9.2.6.4 MAILBOX.TXSTATUS

Address offset: 0x484

Status to indicate if data sent from the CPU to the debugger status has been read



9.2.6.5 ERASEPROTECT.LOCK

Address offset: 0x500

Lock ERASEALL mechanism

This register can only be written once per reset

Bit r	umber		31	30	29 :	28 2	27 2	26 2	5 2	4 2	3 2	2 2	1 20) 19	18	17	16	15	14	13	12	11 :	10	9 8	3 7	7 6	5	4	3	2	1 0
ID																															Α
Rese	et 0x00000000		0	0	0	0	0	0 0) (0 0) (0 (0 0	0	0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0 0
ID																															
Α	RW1 ERASEPROTECTLOCK									Е	nal	ble	or c	lisal	ble '	the	ER	ASI	EAL	L m	ech	nan	ism								
		Unlocked	0							Е	RA:	SEA	ALL (an	be i	ssu	ed														
		Locked	1							Е	RA:	SEA	ALL i	s lo	cke	b															

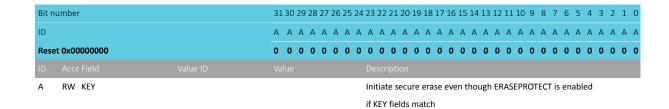
9.2.6.6 ERASEPROTECT.DISABLE

Address offset: 0x504

Unlock ERASEPROTECT and perform ERASEALL



This register can only be written once per reset



9.3 TAD - Trace and debug control

Configuration interface for trace and debug

9.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0xE0080000	TAD	TAD	S	NA	Trace and debug control	

Table 102: Instances

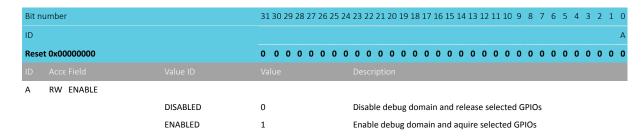
Register	Offset	Security	Description
ENABLE	0x500		Enable debug domain and aquire selected GPIOs
PSEL.TRACECLK	0x504		Pin number configuration for TRACECLK
PSEL.TRACEDATA0	0x508		Pin number configuration for TRACEDATA[0]
PSEL.TRACEDATA1	0x50C		Pin number configuration for TRACEDATA[1]
PSEL.TRACEDATA2	0x510		Pin number configuration for TRACEDATA[2]
PSEL.TRACEDATA3	0x514		Pin number configuration for TRACEDATA[3]
TRACEPORTSPEED	0x518		Clocking options for the Trace Port debug interface

Table 103: Register overview

9.3.1.1 ENABLE

Address offset: 0x500

Enable debug domain and aquire selected GPIOs



9.3.1.2 PSEL.TRACECLK

Address offset: 0x504

Pin number configuration for TRACECLK



Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
В	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

9.3.1.3 PSEL.TRACEDATAO

Address offset: 0x508

Pin number configuration for TRACEDATA[0]

Bit no	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	t OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
В	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

9.3.1.4 PSEL.TRACEDATA1

Address offset: 0x50C

Pin number configuration for TRACEDATA[1]

Bit n	umber		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
В	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

9.3.1.5 PSEL.TRACEDATA2

Address offset: 0x510

Pin number configuration for TRACEDATA[2]

Bit n	umber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			В	АААА
Rese	et OxFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				Description
Α	RW PIN		[031]	Pin number
В	RW CONNECT			Connection
		Disconnected	1	Disconnect
		Connected	0	Connect

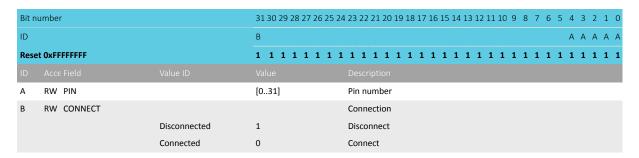




9.3.1.6 PSEL.TRACEDATA3

Address offset: 0x514

Pin number configuration for TRACEDATA[3]



9.3.1.7 TRACEPORTSPEED

Address offset: 0x518

Clocking options for the Trace Port debug interface

This register is a retained register. Reset behavior is the same as debug components.

Bit number	r		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0				
ID				A A				
Reset 0x00	0000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				
ID Acce								
A RW	TRACEPORTSPEED			Speed of Trace Port clock. Note that the TRACECLK pin will				
				output this clock divided by two.				
		32MHz	0 32 MHz Trace Port clock (TRACECLK = 16 MHz)					
	16MHz		1 16 MHz Trace Port clock (TRACECLK = 8 MHz)					
		8MHz	2	8 MHz Trace Port clock (TRACECLK = 4 MHz)				
		4MHz	3	4 MHz Trace Port clock (TRACECLK = 2 MHz)				



10 Hardware and layout

10.1 Pin assignments

This section describes the pin assignment and the pin functions.

This device provides flexibility when it comes to routing and configuration of the GPIO pins. However, some pins have recommendations for how the pin should be configured or what it should be used for. See LGA pin assignments on page 379 for more information about this.

10.1.1 Pin assignments

The pin assignment table and figure describe the assignments for this variant of the chip.

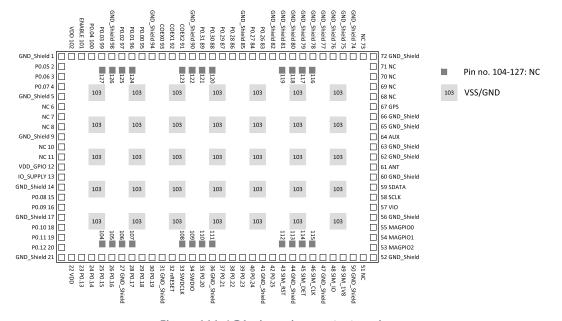


Figure 111: LGA pin assignments, top view

Pin no	Pin name	Function	Description
1	GND_Shield	Power	Ground
2	P0.05	Digital I/O (SoC)	General purpose I/O
3	P0.06	Digital I/O (SoC)	General purpose I/O
4	P0.07	Digital I/O (SoC)	General purpose I/O
5	GND_Shield	Power	Ground
6	NC		Not connected/reserved for Nordic use
7	NC		Not connected/reserved for Nordic use
8	NC		Not connected/reserved for Nordic use
9	GND_Shield	Power	Ground
10	NC		Not connected/reserved for Nordic use
11	NC		Not connected/reserved for Nordic use
12	VDD_GPIO	Power	GPIO power supply input and logic level
13	IO_SUPPLY	Power	Reserved for Nordic use
14	GND_Shield	Power	Ground
15	P0.08	Digital I/O (SoC)	General purpose I/O
16	P0.09	Digital I/O (SoC)	General purpose I/O



Pin no	Pin name	Function	Description
17	GND_Shield	Power	Ground
18	P0.10	Digital I/O (SoC)	General purpose I/O
19	P0.11	Digital I/O (SoC)	General purpose I/O
20	P0.12	Digital I/O (SoC)	General purpose I/O
21	GND_Shield	Power	Ground
22	VDD	Power	Supply voltage input
23	P0.13	Digital I/O (SoC)	General purpose I/O.
	AIN0	Analog input	Analog input.
24	P0.14	Digital I/O (SoC)	General purpose I/O.
	AIN1	Analog input	Analog input.
25	P0.15	Digital I/O (SoC)	General purpose I/O.
	AIN2	Analog input	Analog input.
26	P0.16	Digital I/O (SoC)	General purpose I/O.
	AIN3	Analog input	Analog input.
27	GND_Shield	Power	Ground
28	P0.17	Digital I/O (SoC)	General purpose I/O.
	AIN4	Analog input	Analog input.
29	P0.18	Digital I/O (SoC)	General purpose I/O.
	AIN5	Analog input	Analog input.
30	P0.19	Digital I/O (SoC)	General purpose I/O.
	AIN6	Analog input	Analog input.
31	GND_Shield	Power	Ground
32	nRESET	Digital I/O (SoC)	System reset
33	SWDCLK	Digital input	Serial wire debug clock input for debug and programming
34	SWDIO	Digital I/O	Serial wire debug I/O for debug and programming
35	P0.20	Digital I/O (SoC)	General purpose I/O.
	AIN7	Analog input	Analog input.
36	GND_Shield	Power	Ground
37	P0.21	Digital I/O (SoC)	General purpose I/O.
	TRACECLK	Trace clock	Trace buffer clock (optional).
38	P0.22	Digital I/O (SoC)	General purpose I/O.
	TRACEDATA0	Trace data	Trace buffer TRACEDATA[0] (optional).
39	P0.23	Digital I/O (SoC)	General purpose I/O.
	TRACEDATA1	Trace data	Trace buffer TRACEDATA[1] (optional).
40	P0.24	Digital I/O (SoC)	General purpose I/O.
	TRACEDATA2	Trace data	Trace buffer TRACEDATA[2] (optional).
41	GND_Shield	Power	Ground
42	P0.25	Digital I/O (SoC)	General purpose I/O.
	TRACEDATA3	Trace data	Trace buffer TRACEDATA[3] (optional).
43	SIM_RST	Digital I/O (SoC)	SIM reset
44	GND_Shield	Power	Ground
45	SIM_DET	Digital I/O (SoC)	SIM detect
46	SIM_CLK	Digital I/O (SoC)	SIM clock
47	GND_Shield	Power	Ground
48	SIM_IO	Digital I/O (SoC)	SIM data
49	SIM_1V8	Power	SIM 1.8 V power supply output
50	GND_Shield	Power	Ground
51 52	NC GND_Shield	Power	Not connected/reserved for Nordic use Ground
32	GIAD_2UIICIO	I OWEI	Ground



Pin no	Pin name	Function	Description
53	MAGPIO2	Digital I/O (SoC)	Reserved for Nordic use
4	MAGPIO1	Digital I/O (SoC)	Reserved for Nordic use
5	MAGPIO0	Digital I/O (SoC)	Reserved for Nordic use
6	GND_Shield	Power	Ground
57	VIO	Power	Reserved for Nordic use
8	SCLK	Digital I/O (SoC)	Reserved for Nordic use
59	SDATA	Digital I/O (SoC)	Reserved for Nordic use
50	GND_Shield	Power	Ground
1	ANT	RF	Single-ended radio antenna connection
i2	GND_Shield	Power	Ground
i3	GND_Shield	Power	Ground
4	AUX	RF	ANT output port
55	GND_Shield	Power	Ground
6	GND_Shield	Power	Ground
7	GPS	RF	GPS receiver input
8	NC		Not connected/reserved for Nordic use
9	NC		Not connected/reserved for Nordic use
0	NC		Not connected/reserved for Nordic use
'1	NC		Not connected/reserved for Nordic use
'2	GND_Shield	Power	Ground
'3	NC		Not connected/reserved for Nordic use
4	GND_Shield	Power	Ground
5	GND_Shield	Power	Ground
6	GND_Shield	Power	Ground
7	GND_Shield	Power	Ground
' 8	GND_Shield	Power	Ground
'9	GND_Shield	Power	Ground
30	GND_Shield	Power	Ground
1	GND_Shield	Power	Ground
32	GND_Shield	Power	Ground
3	P0.26	Digital I/O (SoC)	General purpose I/O
4	P0.27	Digital I/O (SoC)	General purpose I/O
5	GND_Shield	Power	Ground
6	P0.28	Digital I/O (SoC)	General purpose I/O
37	P0.29	Digital I/O (SoC)	General purpose I/O
38	P0.30	Digital I/O (SoC)	General purpose I/O
9	P0.31	Digital I/O (SoC)	General purpose I/O
90	GND_Shield	Power	Ground
1	COEX2	Digital I/O (SoC)	Coexistence interface
)2	COEX1	Digital I/O (SoC)	Coexistence interface
)3	COEX0	Digital I/O (SoC)	Coexistence interface
)4	GND_Shield	Power	Ground
15	P0.00	Digital I/O (SoC)	General purpose I/O
16	P0.01	Digital I/O (SoC)	General purpose I/O
7	P0.02	Digital I/O (SoC)	General purpose I/O
8	GND_Shield	Power	Ground
9	P0.03	Digital I/O (SoC)	General purpose I/O
00	P0.04	Digital I/O (SoC)	General purpose I/O
.00	ENABLE	Digital I/O (30C)	Enable for the SIP internal regulator for the nRF91 SoC.
101	ENABLE		Note: The nRF91 will not start until this pin is enabled.

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Power

Supply voltage

102

VDD



Pin no	Pin name	Function	Description
103	VSS	Power	Ground
104-127	NC		Not connected/reserved for Nordic use (do not connect)

Table 104: LGA pin assignments

10.2 Mechanical specifications

The mechanical specifications for the packages show the dimensions in millimeters.

10.2.1 16.00 x 10.50 mm package

Dimensions in millimeters for the nRF9160 LGA 16.00 x 10.50 mm package.

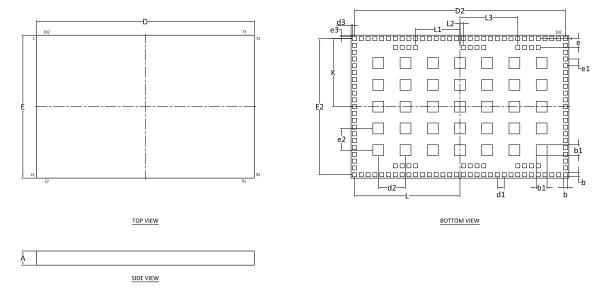


Figure 112: LGA 16.00 x 10.50 mm package

	Α	b	b1	D	E	е	d1	e1	D2	E2	d2	e2	d3	е3	К	L	L1	L2	L3
Min.	0.98			15.90	10.40														
Nom.	1.04	0.30	0.80	16.00	10.50	0.65	0.50	0.50	15.50	10.00	2.00	1.60	0.10	0.10	5.00	7.75	3.25	0.25	4.25
Max.	1.10			16.10	10.60														

Table 105: LGA dimensions in millimeters

10.3 Reference circuitry

To ensure good RF performance when designing PCBs, it is highly recommended to use the PCB layouts and component values provided by Nordic Semiconductor.

Documentation for the different package reference circuits, including Altium Designer files, PCB layout files, and PCB production files can be downloaded from www.nordicsemi.com.

10.3.1 Schematic

The bill of material (BOM) is TBD.



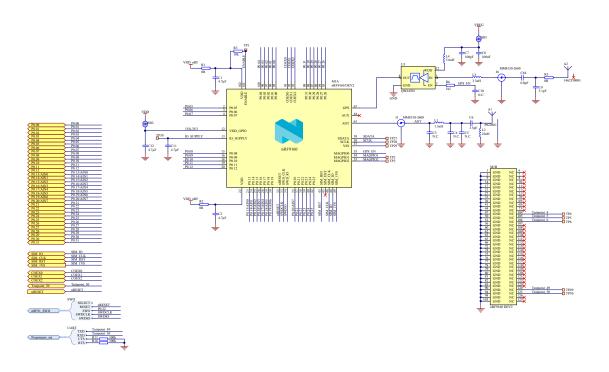


Figure 113: Schematic, with antenna details

10.3.2 PCB layout example

The PCB layout shown below is a part of an example reference layout for the LGA package, showing antenna details.



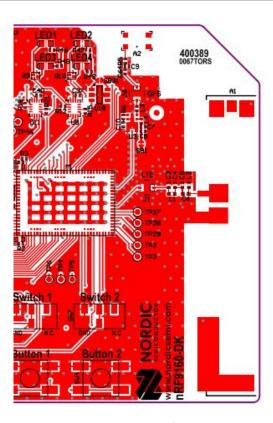


Figure 114: Top layer

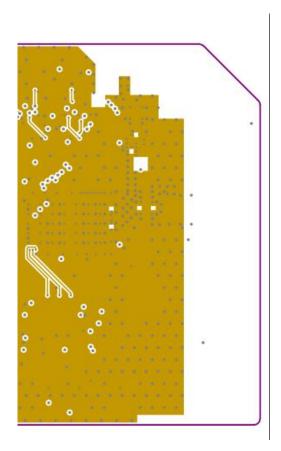


Figure 115: Mid layer 1

10.3.3 PCB laminate specification



STACKUP 4021 custom 1.6mm 1/2oz/1oz Copper plating 18 um Copper layer 0.1 mm FR-4 -- IPC-4101 /21 2 35 um Copper layer 1.2 mm FR-4 -- IPC-4101 /21 35 um Copper layer 0.1 mm FR-4 -- IPC-4101 /21 18 um Copper layer Copper plating

Figure 116: Elprint's 4 layer 4001 stackup



11 Recommended operating conditions

The operating conditions are the physical parameters that the chip can operate within.

Symbol	Parameter	Notes	Min.	Nom.	Max.	Units
VDD	Battery input voltage	Including voltage drop, ripple and	3.0	3.8	5.5	V
		spikes.				
		RF 3GPP compliancy requires 3.3 V.				
VDD_GPIO	GPIO input voltage		1.7		3.6	V
GPIO _H	GPIO high level voltage				VDD_GPIO	V
MAGPIO _H	MAGPIO high level voltage			1.8	1.8	V
$t_{R_VDD_GPIO}$	VDD_GPIO rise time (0 V to 1.7 V)	IO_SUPPLY should be ramped			60	ms
		up before or in parallel with				
		VDD_GPIO				
TA	Operating temperature		-40	25	85	°C

Table 106: Recommended operating conditions

Note: There can be excessive leakage at VDD and/or VDD_GPIO if any of these supply voltages is outside its range given in Recommended operating conditions on page 386.

11.1 VDD_GPIO considerations

VDD_GPIO is the supply to the general purpose I/O.

The following restrictions should be taken into considerations:

- VDD GPIO should be applied after VDD has been supplied
- VDD_GPIO should be removed before removing VDD
- If VDD is supplied and VDD_GPIO is grounded, an extra current consumption can be generated on VDD



12 Absolute maximum ratings

Maximum ratings are the extreme limits to which the chip can be exposed for a limited amount of time without permanently damaging it. Exposure to absolute maximum ratings for prolonged periods of time may affect the reliability of the device.

	Note	Min.	Max.	Unit
Supply voltages				
VDD		-0.3	5.5	V
VDD_GPIO		-0.3	3.9	V
VSS			0	V
I/O pin voltage				
$V_{I/O}$, $VDD_GPIO \le 3.6 V$		-0.3	VDD_GPIO + 0.3	V
$V_{I/O}$, VDD_GPIO > 3.6 V		-0.3	3.9	V
Radio				
RF input level			10	dBm
Environmental (LGA package)				
Storage temperature		-40	125	°C
MSL	Moisture Sensitivity Level		2	
ESD HBM	Human Body Model		2	kV
ESD CDM	Charged Device Model		500	V
Flash memory				
Endurance		10 000		Write/erase cycles
Retention		10 years at 85°C		

Table 107: Absolute maximum ratings





13 Ordering information

This chapter contains information on IC marking, ordering codes, and container sizes.

13.1 IC marking

The nRF9160 IC package is marked like described below.

N	9	1	6	0	
<p< th=""><th>P></th><th><></th><th>></th><th>+</th><th><p></p></th></p<>	P>	<>	>	+	<p></p>
<y< th=""><th>Y></th><th><w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<></th></y<>	Y>	<w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<>	W>	<l< th=""><th>L></th></l<>	L>

Figure 117: Package marking

13.2 Box labels

Here are the box labels used for the nRF9160.

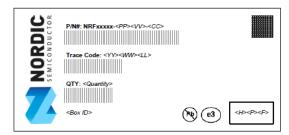


Figure 118: Inner box label



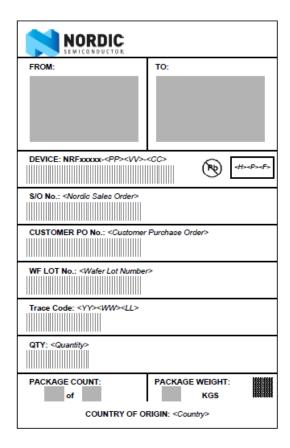


Figure 119: Outer box label

13.3 Order code

Here are the nRF9160 order codes and definitions.



Figure 120: Order code



Abbreviation	Definition and implemented codes
N91/nRF91	nRF91 Series product
60	Part code
<pp></pp>	Package variant code
<vv></vv>	Function variant code
<h><p><f></f></p></h>	Build code H - Hardware version code P - Production configuration code (production site, etc.) F - Firmware version code (only visible on shipping container label)
<yy><ww><ll></ll></ww></yy>	Tracking code YY - Year code WW - Assembly week number LL - Wafer lot code
<cc></cc>	Container code

Table 108: Abbreviations

13.4 Code ranges and values

Defined here are the nRF9160 code ranges and values.

<pp></pp>	Package	Size (mm)	Pin/Ball count	Pitch (mm)

Table 109: Package variant codes

<vv></vv>	Flash (kB)	RAM (kB)

Table 110: Function variant codes

<h>></h>	Description
[A Z]	Hardware version/revision identifier (incremental)

Table 111: Hardware version codes

<p></p>	Description
[09]	Production device identifier (incremental)
[A Z]	Engineering device identifier (incremental)

Table 112: Production configuration codes



<f></f>	Description
[A N, P Z]	Version of preprogrammed firmware
[0]	Delivered without preprogrammed firmware

Table 113: Production version codes

<yy></yy>	Description
[1599]	Production year: 2015 to 2099

Table 114: Year codes

<ww></ww>	Description
[152]	Week of production

Table 115: Week codes

<ll></ll>	Description
[AA ZZ]	Wafer production lot identifier

Table 116: Lot codes

<cc></cc>	Description
R7	7" Reel
R	13" Reel
Т	Tray

Table 117: Container codes

13.5 Product options

Defined here are the nRF9160 product options.

Order code	Minimum ordering quantity (MOQ)	Comment
nRF9160-SICA-R	2500	LTE-M/NB-IoT/GPS product
nRF9160-SIAA-R	2500	LTE-M only product
nRF9160-SIBA-R	2500	NB-IoT only product

Table 118: nRF9160 order codes



Order code	Description
nRF9160-DK	

Table 119: Development tools order code



14 FCC/ISED regulatory notices

Modification statement

Nordic Semiconductor has not approved any changes or modifications to this device by the user. Any changes or modifications could void the user's authority to operate the equipment.

Nordic Semiconductor n'approuve aucune modification apportée à l'appareil par l'utilisateur, quelle qu'en soit la nature. Tout changement ou modification peuvent annuler le droit d'utilisation de l'appareil par l'utilisateur.

Interference statement

This device complies with Part 15 of the FCC Rules and Industry Canada's licence-exempt RSS standards. Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Wireless notice

This equipment complies with FCC and ISED radiation exposure limits set forth for an uncontrolled environment. The antenna should be installed and operated with minimum distance of 20 cm between the radiator and your body. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

Cet appareil est conforme aux limites d'exposition aux rayonnements de l'ISDE pour un environnement non contrôlé. L'antenne doit être installée de façon à garder une distance minimale de 20 centimètres entre la source de rayonnements et votre corps. L'émetteur ne doit pas être colocalisé ni fonctionner conjointement avec à autre antenne ou autre émetteur.

Permitted antenna

This radio transmitter has been approved by FCC and ISED to operate with the antenna types listed below with the maximum permissible gain indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Туре	Band	Max gain
SMD	Band 4	6 dBi
	Band 13	6.9 dBi

Le présent émetteur radio a été approuvé par ISDE pour fonctionner avec les types d'antenne énumérés ci dessous et ayant un gain admissible maximal. Les types d'antenne non inclus dans cette liste, et dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.



Туре	Bande	Gain maximal
CMS	Bande 4	6 dBi
	Bande 13	6.9 dBi

FCC Class B digital device notice

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna
- Increase the separation between the equipment and receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or an experienced radio/TV technician for help

CAN ICES-3 (B)/NMB-3 (B)

This Class B digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de classe B est conforme à la norme canadienne ICES-003.

Labeling requirements for the host device

The host device shall be properly labelled to identify the modules within the host device. The certification label of the module shall be clearly visible at all times when installed in the host device, otherwise the host device must be labelled to display the FCC ID and IC of the module, preceded by the words "Contains transmitter module", or the word "Contains", or similar wording expressing the same meaning, as follows:

Contains FCC ID: 2ANPO00NRF9160 Contains IC: 24529-NRF9160

L'équipement hôte doit être correctement étiqueté pour identifier les modules dans l'équipement. L'étiquette de certification du module doit être clairement visible en tout temps lorsqu'il est installé dans l'hôte, l'équipement hôte doit être étiqueté pour afficher le FCC ID et IC du module, précédé des mots "Contient le module émetteur", ou le mot "Contient", ou un libellé similaire exprimant la même signification, comme suit:

Contient FCC ID: 2ANPO00NRF9160 Contient IC: 24529-NRF9160



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