

EV6543HB-L-00A 3V to 22V, Three-Phase Brushless DC Motor Driver Evaluation Board

DESCRIPTION

The EV6543HB-L-00A is an evaluation board for the MP6543HGL-B, a three-phase brushless DC motor driver.

The EV6543HB-L-00A operates from a supply voltage up to 22V. It integrates three halfbridges consisting of six N-channel power MOSFETs. The rotor position information is provided by the Hall sensors assembled in the motor, and the driving control signals are generated by the external controller, such as an MCU or FPGA.

ELECTRICAL SPECIFICATIONS

| Parameter | Symbol | Value | Units |
|-------------------|-----------------------|---------|-------|
| Input voltage | VIN | 3 to 22 | V |
| LDO input voltage | $V_{\text{IN}_{LDO}}$ | 3 to 22 | V |
| VREF voltage | V_{REF} | 3.3 | V |
| VCC voltage | Vcc | 3.3 | V |

FEATURES

- Wide 3V to 22V Input Voltage Range
- Built-In 3.3V, 100mA LDO Regulator
- Integrated Bidirectional Current-Sense Amplifiers
- Support 100% Duty Cycle Operation
- Hall Logic Input
- Over-Current Protection (OCP), Over-Temperature Protection (OTP)
- Fault Indication Output

APPLICATIONS

- Three-Phase Brushless DC Motors and Permanent Magnet Synchronous Motors
- Drones
- Robotics

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EV6543HB-L-00A EVALUATION BOARD



(LxW) 6.35cmx6.35cm

| Board Number | MPS IC Number | | |
|----------------|---------------|--|--|
| EV6543HB-L-00A | MP6543HGL-B | | |

EV6543HB-L-00A Rev. 1.0 MonolithicPower.com 6/2/2020 MPS Proprietary Information. Patent Protected. Unauthorized Photocopy and Duplication Prohibited. © 2020 MPS. All Rights Reserved.

EV6543HB-L-00A – 22V, THREE-PHASE BLDC MOTOR DRIVER EVAL BOARD

QUICK START GUIDE

- 1. Attach the input voltage ($3V \le V_{IN} \le 22V$) to the VIN connector, and attach the input ground to the GND connector.
- 2. Attach the LDO input voltage ($3V \le V_{IN_LDO} \le 22V$) to the VIN_LDO connector, and attach the input ground to the GND connector.
- 3. Attach a 3.3V constant voltage to the VCC connector, then switch SW1 to position 1 (top side) to enable the chip.
- 4. Attach a 3.3V constant voltage to the VREF connector to set the current-sense output reference voltage.
- 5. Attach the motor's Hall signals to the Hall sensor connector. Table 1 shows the commutation table.

| Logic Inputs | | | | Motor Terminals | | |
|--------------|----|----|-----|-----------------|-----|-----|
| HA | HB | HC | DIR | SA | SB | SC |
| 1 | 0 | 1 | 1 | PWM | Z | L |
| 1 | 0 | 0 | 1 | Z | PWM | L |
| 1 | 1 | 0 | 1 | L | PWM | Z |
| 0 | 1 | 0 | 1 | L | Z | PWM |
| 0 | 1 | 1 | 1 | Z | L | PWM |
| 0 | 0 | 1 | 1 | PWM | L | Z |
| 1 | 0 | 1 | 0 | L | Z | PWM |
| 0 | 0 | 1 | 0 | L | PWM | Z |
| 0 | 1 | 1 | 0 | Z | PWM | L |
| 0 | 1 | 0 | 0 | PWM | Z | L |
| 1 | 1 | 0 | 0 | PWM | L | Z |
| 1 | 0 | 0 | 0 | Z | L | PWM |
| 0 | 0 | 0 | Х | Z | Z | Z |
| 1 | 1 | 1 | Х | Z | Z | Z |

Table 1: Commutation Table of the MP6543HGL-B (nBRAKE = 1)

6. Attach the driving control signals generated by the external controller to the CN1 connector.



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EVALUATION BOARD SCHEMATIC

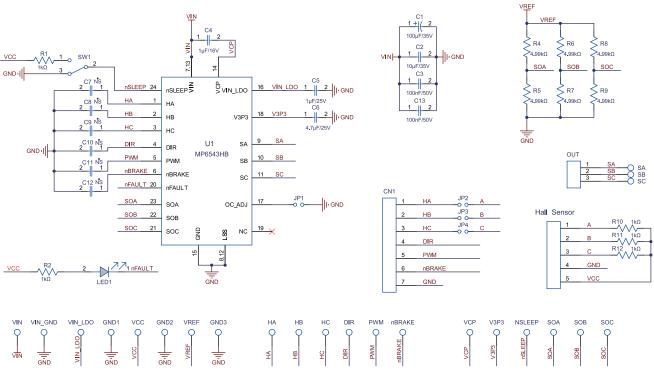


Figure 1: Evaluation Board Schematic



| Qty | Ref | Value | Description | Package | Manufacturer | Manufacturer P/N |
|-----|---|-------------------|---|---------------------|----------------------|------------------------|
| 5 | R1, R2, R10, R11, R12 | 1kΩ | Film resistor, 1% | 0603 | Yageo | RC0603FR-071KL |
| 6 | R4, R5, R6, R7, R8, R9 | 4.99kΩ | Film resistor, 1% | 0603 | Yageo | RC0603FR-074K99L |
| 1 | C1 | 100µF | Electrolytic capacitor, 35V | DIP | Jianghai | CD287-35V100 |
| 1 | C2 | 10µF | Ceramic capacitor, 35V, X7R | 1210 | Murata | GRM32ER7YA106KA1 2L |
| 2 | C3, C13 | 100nF | Ceramic capacitor, 50V, X7R | 0603 | Wurth | 885012206095 |
| 1 | C4 | 1µF | Ceramic capacitor, 16V, X7R | 0603 | Wurth | 885012206052 |
| 1 | C5 | 1µF | Ceramic capacitor, 25V, X5R | 0603 | Wurth | 885012106022 |
| 1 | C6 | 4.7µF | Ceramic capacitor, 25V, X5R | 0603 | Murata | GRM188R61E475KE11 D |
| 6 | C7, C8, C9, C10, C11, C12 | NS | | | | |
| 1 | LED1 | Red | LED | 0805 | Baihong | BL-HUE35A-AV-TRB |
| 1 | U1 | 22V, 2A | Three-phase brushless DC motor driver | QFN-24 (3mmx4mm) | MPS | MP6543HGL-B |
| 1 | SW1 | SPDT | Button | DIP | Wurth | 450301014042 |
| 4 | JP1, JP2, JP3, JP4 | 2-bits/ 2.54mm | Connector | DIP | Electrical market | 61304011121 |
| 4 | JP1, JP2, JP3, JP4 | 2-bits/ 2.54mm | Short jumper | DIP | Electrical market | 60900213421 |
| 1 | CN1 | 7-bits/ 2.54mm | Connector | DIP | Electrical market | 61304011121 |
| 1 | Hall sensor | 5-bits/ 2.54mm | Connector | DIP | Electrical market | 61304011121 |
| 1 | PWMA, PWMB, PWMC, ENA, ENB, ENC | 6-bits/ 2.54mm | Connector | DIP | Electrical market | 61304011121 |
| 1 | OUT | 3-bits/ 2.54mm | Connector | DIP | Electrical market | 61304011121 |
| 6 | VCP, V3P3, SOA, SOB, SOC, NSLEEP | Yellow | Test point | DIP | Electrical market | Test point |
| 2 | VIN, VIN_GND | Φ = 2mm | Connector | DIP | Electrical market | Φ = 2mm Needle |
| 9 | VIN_LDO, VREF, VCC, GND, GND, GND, SA, SB, SC | Φ = 1mm | Connector | DIP | Electrical market | Φ = 1mm Needle |

EV6543HB-L-00A BILL OF MATERIALS

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PCB LAYOUT

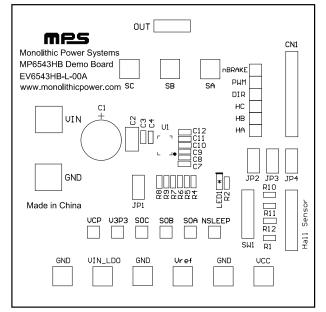


Figure 2: Top Silk Layer

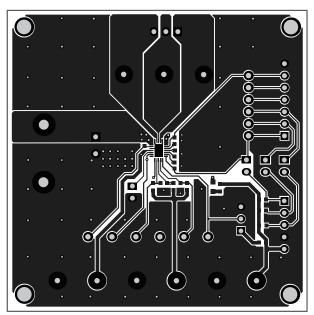


Figure 3: Top Layer

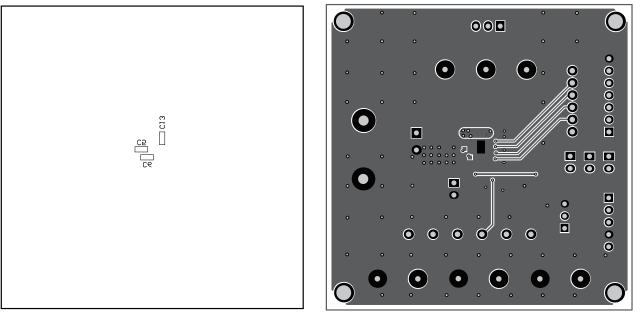


Figure 4: Bottom Silk Layer

Figure 5: Bottom Layer

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