

# < DIPIPM > PSS05S73FT

TRANSFER MOLDING TYPE INSULATED TYPE

#### **OUTLINE**



#### MAIN FUNCTION AND RATINGS

- 3 phase DC/AC inverter
- 1200V / 5A (CSTBT)
- N-side IGBT open emitter
- Built-in bootstrap diodes with current limiting resistor

#### **APPLICATION**

 AC 400Vrms(DC voltage:800V or below) class low power motor control

#### INTEGRATED DRIVE, PROTECTION AND SYSTEM CONTROL FUNCTIONS

• For P-side : Drive circuit, High voltage high-speed level shifting, Control supply under-voltage (UV) protection

• For N-side : Drive circuit, Control supply under-voltage protection (UV), Short circuit protection (SC),

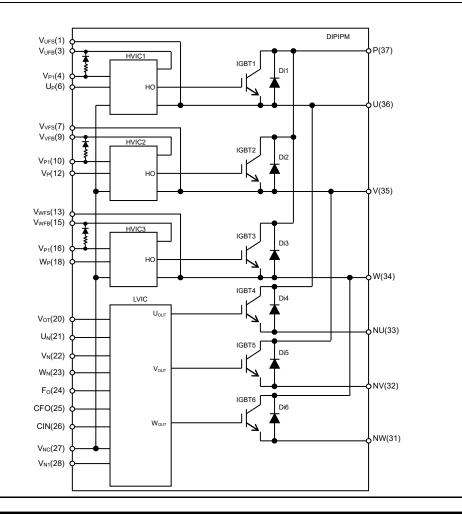
• Fault signaling : Corresponding to SC fault (N-side IGBT), UV fault (N-side supply)

• Temperature output: Outputting LVIC temperature by analog signal

• Input interface : 3, 5V line, Schmitt trigger receiver circuit (High Active)

• UL Recognized : UL1557 File E323585

#### **INTERNAL CIRCUIT**



Publication Date: March 2022

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#### **MAXIMUM RATINGS** (T<sub>j</sub> = 25°C, unless otherwise noted)

#### **INVERTER PART**

Symbol	Parameter	Condition		Ratings	Unit
Vcc	Supply voltage	Applied between P-NU,NV,NW		900	V
V <sub>CC(surge)</sub>	Supply voltage (surge)	Applied between P-NU,NV,NW	Applied between P-NU,NV,NW		V
V <sub>CES</sub>	Collector-emitter voltage			1200	V
±l <sub>C</sub>	Each IGBT collector current	TC= 25°C	(Note 1)	5	Α
±I <sub>CP</sub>	Each IGBT collector current (peak)	T <sub>C</sub> = 25°C, less than 1ms		10	Α
T <sub>jop</sub>	Operation junction temperature	Continuous operation	(Note 2)	-30~+150	°C
T <sub>jmax</sub>	Maximum junction temperature	Temporally operation (e.g. overload)		175	°C

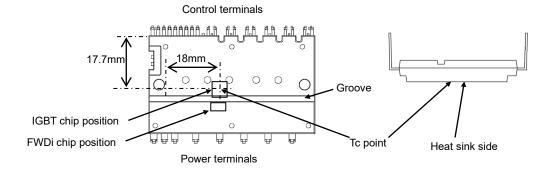
#### **CONTROL (PROTECTION) PART**

Symbol	Parameter	Condition	Ratings	Unit
$V_D$	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	20	V
$V_{DB}$	Control supply voltage	Applied between V <sub>UFB</sub> -V <sub>UFS</sub> , V <sub>VFB</sub> -V <sub>VFS</sub> , V <sub>WFB</sub> -V <sub>WFS</sub>	20	V
$V_{IN}$	Input voltage	Applied between U <sub>P</sub> , V <sub>P</sub> , W <sub>P</sub> , U <sub>N</sub> , V <sub>N</sub> , W <sub>N</sub> -V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V
$V_{FO}$	Fault output supply voltage	Applied between Fo-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V
I <sub>FO</sub>	Fault output current	Sink current at F <sub>0</sub> terminal	5	mA
V <sub>sc</sub>	Current sensing input voltage	Applied between CIN-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V

#### **TOTAL SYSTEM**

Symbol	Parameter	Condition	Ratings	Unit
V <sub>CC(PROT)</sub>	Self protection supply voltage limit (Short circuit protection capability)	V <sub>D</sub> = 13.5~16.5V, Inverter Part T <sub>i</sub> = 150°C, non-repetitive, less than 2μs	800	V
T <sub>C</sub>	Module case operation temperature	Measurement point of Tc is provided in Fig.1	-30~+125	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C
V <sub>iso</sub>	Isolation voltage	60Hz, Sinusoidal, AC 1min, between connected all pins and heat sink plate	2500	V <sub>rms</sub>

Fig. 1: T<sub>C</sub> MEASUREMENT POINT



#### THERMAL RESISTANCE

Cymphal	Danamatan	Condition	Limits			Unit
Symbol Parameter		Condition		Тур.	Max.	Offic
R <sub>th(j-c)Q</sub>	Junction to case thermal	Inverter IGBT part (per 1/6 module)	-	-	2.20	K/W
R <sub>th(j-c)F</sub>	resistance (Note 3)	Inverter FWDi part (per 1/6 module)	-	-	2.70	K/W

Note 3: Grease with good thermal conductivity and long-term endurance should be applied evenly with about +100µm~+200µm on the contacting surface of DIPIPM and heat sink. The contacting thermal resistance between DIPIPM case and heat sink Rth(c-f) is determined by the thickness and the thermal conductivity of the applied grease. For reference, Rth(c-f) is about 0.3K/W (per 1/6 module, grease thickness: 20µm, thermal conductivity: 1.0W/m•k).

Note 1: Pulse width and period are limited due to junction temperature.

Note 2: The maximum junction temperature rating of built-in power chips is 175°C(@Tc≤125°C). However, to ensure safe operation of DIPIPM, the average junction temperature should be limited to Tj(Ave)≤150°C (@Tc≤125°C).

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# **ELECTRICAL CHARACTERISTICS** ( $T_j = 25^{\circ}C$ , unless otherwise noted) **INVERTER PART**

Cumah al	Doromotor	Condition	Limits			I Imia
Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
$V_{\text{CE(sat)}}$	Collector-emitter saturation voltage	$V_D = V_{DB} = 15V, I_C = 5A, V_{IN} = 5V$	-	1.40	2.10	V
V <sub>EC</sub>	FWDi forward voltage	V <sub>IN</sub> = 0V, -I <sub>C</sub> = 5A	-	1.70	2.30	V
t <sub>on</sub>			0.85	1.50	2.20	μs
t <sub>c(on)</sub>		$V_{CC}$ = 600V, $V_{D}$ = $V_{DB}$ = 15V	-	0.30	0.60	μs
t <sub>off</sub>	Switching times	$I_{C}$ = 5A, $T_{j}$ = 25°C, $V_{IN}$ = 0 $\leftrightarrow$ 5V	-	1.75	2.30	μs
t <sub>c(off)</sub>		Inductive Load (upper-lower arm)	-	0.30	0.60	μs
t <sub>rr</sub>			-	0.40	-	μs
I <sub>CES</sub>	Collector-emitter cut-off current	V <sub>CE</sub> =V <sub>CES</sub>	-	-	1	mA

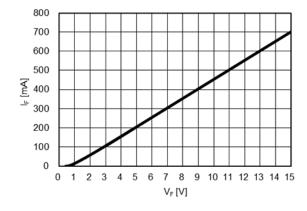
**CONTROL (PROTECTION) PART** 

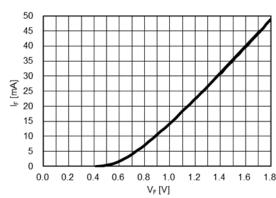
Cumbal	Darameter	Conc	lition		Limits		Unit
Symbol	Parameter	Conc	iluori	Min.	Тур.	Max.	Unit
1		Total of V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	V <sub>D</sub> =15V, V <sub>IN</sub> =0V	-	-	5.60	
I <sub>D</sub>	Circuit current	TOTAL OF VP1-VNC, VN1-VNC	V <sub>D</sub> =15V, V <sub>IN</sub> =5V	-	-	5.60	
	Circuit current	Each part of V <sub>UFB</sub> - V <sub>UFS</sub> ,	$V_D=V_{DB}=15V$ , $V_{IN}=0V$	-	-	0.55	mA
I <sub>DB</sub>		$V_{VFB}$ - $V_{VFS}$ , $V_{WFB}$ - $V_{WFS}$	$V_D=V_{DB}=15V, V_{IN}=5V$	-	-	0.55	
$V_{SC(ref)}$	Short circuit trip level	V <sub>D</sub> = 15V	(Note 4)	0.450	0.480	0.510	V
UV <sub>DBt</sub>	P-side Control supply	Trip level		10.0	-	12.0	V
$UV_DBr$	under-voltage protection(UV)	Reset level		10.5	-	12.5	V
UV <sub>Dt</sub>	N-side Control supply	ply Trip level		10.3	-	12.5	V
$UV_Dr$	under-voltage protection(UV)	Reset level		10.8	-	13.0	V
V <sub>OT</sub>	Temperature Output	LVIC Temperature=85°C, Pull down R=5.1kΩ (Note 5)		2.51	2.64	2.76	V
$V_{FOH}$	Fault output voltage	V <sub>SC</sub> = 0V, F <sub>O</sub> terminal pulled	up to 5V by 10kΩ	4.9	-	-	V
$V_{FOL}$	Fault output voltage	$V_{SC}$ = 1V, $I_{FO}$ = 1mA		-	-	0.95	V
t <sub>FO</sub>	Fault output pulse width	C <sub>FO</sub> =22nF	(Note 6)	1.6	2.4	-	ms
I <sub>IN</sub>	Input current	V <sub>IN</sub> = 5V		0.70	1.00	1.50	mA
$V_{th(on)}$	ON threshold voltage	Applied between Up Vp Vv Vv Vv Vv-Vvc		-	-	2.60	V
$V_{th(off)}$	OFF threshold voltage			0.80	-	-	٧
$V_F$	Bootstrap Di forward voltage	I <sub>F</sub> =10mA including voltage drop by limiting resistor (Note 7)		0.5	0.9	1.3	V
R	Built-in limiting resistance	Included in bootstrap Di		16	20	24	Ω

Note 4 : SC protection works only for N-side IGBT. Please select the external shunt resistance such that the SC trip-level is less than 2.0 times of the current rating.
5 : DIPIPM don't shutdown IGBTs and output fault signal automatically when temperature rises excessively. When temperature exceeds the protective level that user defined, controller (MCU) should stop the DIPIPM. Temperature of LVIC vs. VOT output characteristics is described in Fig. 3. These minimum and maximum curves are based on theoretical designed value excluding LVIC temperature=85°C limits.

7 : The characteristics of bootstrap Di is described in Fig.2.

Fig. 2 Characteristics of bootstrap Di V<sub>F</sub>-I<sub>F</sub> curve (@Ta=25°C) including voltage drop by limiting resistor (Right chart is enlarged chart.)





<sup>6:</sup> Fault signal Fo outputs when SC or UV protection works. Fo pulse width is different for each protection modes. At SC failure, Fo pulse width is a fixed width which is specified by the capacitor connected to C<sub>FO</sub> terminal. (C<sub>FO</sub>=9.1 x 10<sup>-6</sup> x t<sub>FO</sub> [F]), but at UV failure, Fo outputs continuously until recovering from UV state. (But minimum Fo pulse width is the specified time by C<sub>FO</sub>.)

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Fig. 3 Temperature of LVIC vs. VoT output characteristics

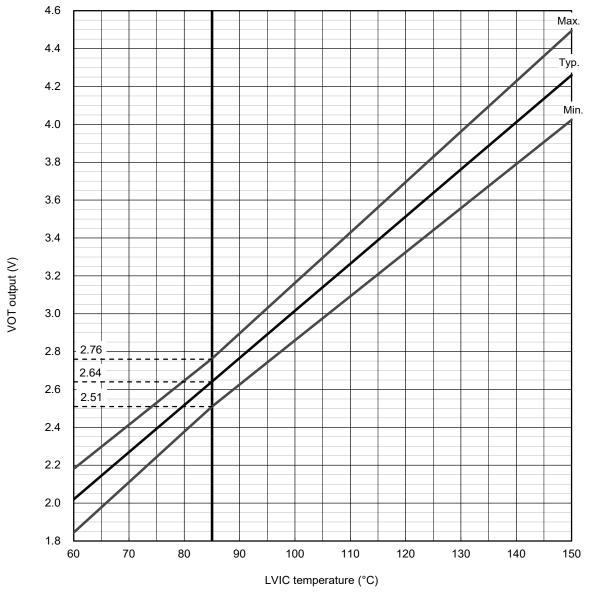
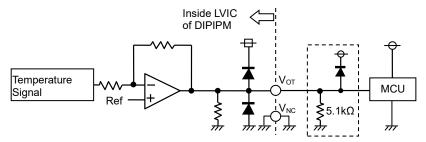


Fig. 4 VoT output circuit



- (1) It is recommended to insert 5.1kΩ pull down resistor for getting linear output characteristics at low temperature below room temperature. When the pull down resistor is inserted between V<sub>OT</sub> and V<sub>NC</sub>(control GND), the extra circuit current, which is calculated approximately by V<sub>OT</sub> output voltage divided by pull down resistance, flows as LVIC circuit current continuously. In the case of using V<sub>OT</sub> for detecting high temperature over room temperature only, it is unnecessary to insert the pull down resistor.
- (2) In the case of using V<sub>OT</sub> with low voltage controller like 3.3V MCU, V<sub>OT</sub> output might exceed control supply voltage 3.3V when temperature rises excessively. If system uses low voltage controller, it is recommended to insert a clamp Di between control supply of the controller and V<sub>OT</sub> output for preventing over voltage destruction.
- (3) In the case of not using  $V_{\text{OT}}$ , leave  $V_{\text{OT}}$  output NC (No Connection).

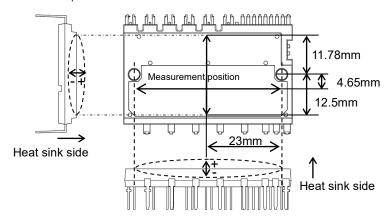
Refer the application note for this product about the usage of Vot.

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#### **MECHANICAL CHARACTERISTICS AND RATINGS**

Parameter	Condition		Reference Limits			Unit	
Faiailletei	Condition		Reference	Min.	Тур.	Max.	Offic
Mounting torque	Mounting screw : M3 (Note 8)	(NI=4= 0)	JEITA-ED-4701	0.59	0.78	0.98	NI m
Mounting torque		(Note 8)	402 Method II				N·m
Townsia at atmosperate would	Load 10N		JEITA-ED-4701	10	-	-	_
Terminal strength pull			401 Method I				S
Townsia at a town with the conditions	Land FN 00 days Days d		JEITA-ED-4701	0			4
Terminal strength bending	Load 5N, 90deg. Bend		401 Method III	2	-	-	times
Weight			-	-	21	-	g
Heat radiation part flatness		(Note 9)	-	-50	-	100	μm

Note 8: Plain washers (ISO 7089~7094) are recommended. Note 9: Measurement positions of heat radiation part flatness are as below.

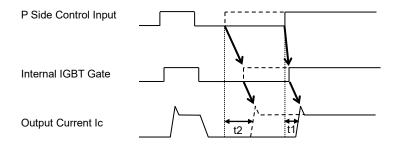


#### **RECOMMENDED OPERATION CONDITIONS**

Symbol	Parameter Condition			Limits	Unit	
Symbol	Farameter	Condition	Min.	Тур.	Max.	Offic
V <sub>CC</sub>	Supply voltage	Applied between P-NU, NV, NW	350	600	800	V
V <sub>D</sub>	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	13.5	15.0	16.5	V
$V_{DB}$	Control supply voltage	Applied between V <sub>UFB</sub> -V <sub>UFS</sub> , V <sub>VFB</sub> -V <sub>VFS</sub> , V <sub>WFB</sub> -V <sub>WFS</sub>	13.0	15.0	18.5	V
$\Delta V_D$ , $\Delta V_{DB}$	Control supply variation		-1	-	+1	V/µs
t <sub>dead</sub>	Arm shoot-through blocking time	For each input signal	2.5	-	-	μs
f <sub>PWM</sub>	PWM input frequency	T <sub>C</sub> ≤ 125°C, T <sub>j</sub> ≤ 150°C	-	-	20	kHz
PWIN(on)	Minimum input pulse width	(Note 10)	1.0	-	-	μs
PWIN(off)	Willimitani input puise widin	(Note 11)	2.0	-	-	μδ
$V_{NC}$	V <sub>NC</sub> variation	Between V <sub>NC</sub> -NU, NV, NW (including surge)	-5.0	-	+5.0	V

Note 10: DIPIPM might not make response if the input signal pulse width is less than PWIN(on).

Note 11: DIPIPM might make no response or delayed response (P-side IGBT only) for input pulse width less than PWIN(off). Over rated collector current (Ic) operation, DIPIPM might make delayed response even if the input signal pulse width is PWIN(off) or more. The timing charts are described as below.

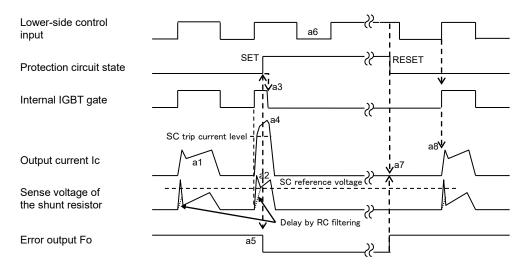


Real line: Normal response; turn on time t1 Broken line: Delayed response; turn on time t2 (t1:Normal switching time)

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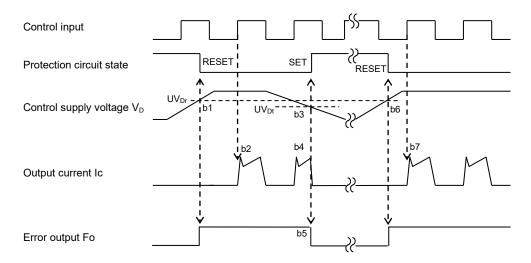
#### Fig. 5 Timing Charts of The DIPIPM Protective Functions

- [A] Short-Circuit Protection (N-side only with the external shunt resistor and RC filter)
- a1. Normal operation: IGBT ON and outputs current.
- a2. Short circuit current detection (SC trigger)
  - (It is recommended to set RC time constant 1.5~2.0µs so that IGBT shut down within 2.0µs when SC.)
- a3. All N-side IGBT's gates are hard interrupted.
- a4. All N-side IGBTs turn OFF.
- a5.  $F_0$  outputs. The pulse width of the Fo signal is set by the external capacitor  $C_{FO}$ .
- a6. Input = "L": IGBT OFF
- a7. Fo finishes output, but IGBTs don't turn on until inputting next ON signal (L→H). (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- a8. Normal operation: IGBT ON and outputs current.



#### [B] Under-Voltage Protection (N-side, UVD)

- b1. Control supply voltage V<sub>D</sub> exceeds under voltage reset level (UV<sub>Dr</sub>), but IGBT turns ON by next ON signal (L→H). (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- b2. Normal operation: IGBT ON and outputs current.
- b3. V<sub>D</sub> level drops to under voltage trip level. (UV<sub>Dt</sub>).
- b4. All N-side IGBTs turn OFF in spite of control input condition.
- b5. Fo outputs for the period set by the capacitance C<sub>FO</sub>, but output is extended during V<sub>D</sub> keeps below UV<sub>Dr</sub>.
- b6.  $V_D$  level reaches  $UV_{Dr}$ .
- b7. Normal operation: IGBT ON and outputs current.



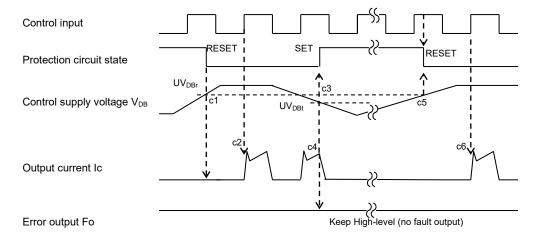
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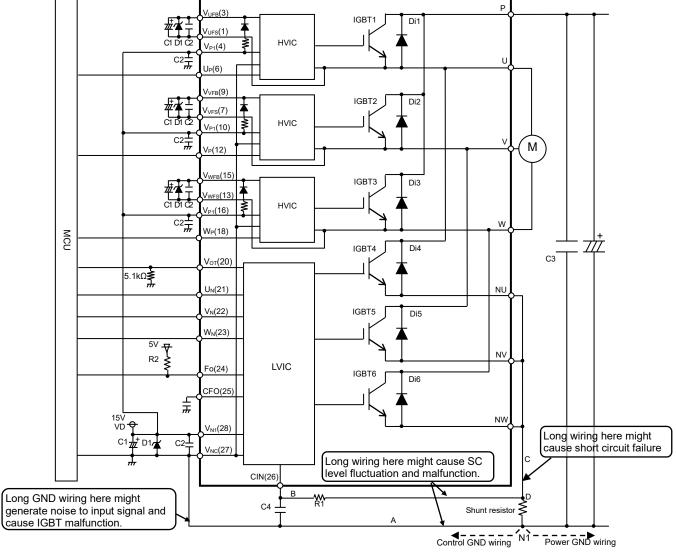
#### [C] Under-Voltage Protection (P-side, UV<sub>DB</sub>)

- c1. Control supply voltage  $V_{DB}$  rises. After the voltage reaches under voltage reset level  $UV_{DBr}$ , IGBT turns on by next ON signal (L $\rightarrow$ H).
- c2. Normal operation: IGBT ON and outputs current.
- c3. V<sub>DB</sub> level drops to under voltage trip level (UV<sub>DBt</sub>).
- c4. IGBT of the correspond phase only turns OFF in spite of control input signal level, but there is no Fo signal output.
- c5.  $V_{DB}$  level reaches  $UV_{DBr}$ .
- c6. Normal operation: IGBT ON and outputs current.



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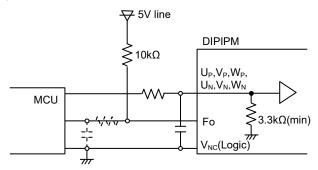
Fig. 6 Example of Application Circuit



- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert a Zener diode D1(24V/1W) between each pair of control supply terminals to prevent surge destruction.
- (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible. Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
- (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type. The time constant R1C4 should be set so that SC current is shut down within 2µs. (1.5µs~2µs is recommended generally.) SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (6) The point D at which the wiring to CIN filter is divided should be near the terminal of shunt resistor. NU, NV, NW terminals should be connected at near NU, NV, NW terminals when it is used by one shunt operation. Low inductance SMD type with tight tolerance, temp-compensated type is recommended for shunt resistor.
- (7) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2:0.22μ-2μF, good temperature, frequency and DC bias characteristic ceramic type are recommended.)
- (8) Input logic is High-active. There is a 3.3kΩ(min.) pull-down resistor in the input circuit of IC. To prevent malfunction, the input wiring should be as short as possible. When using RC coupling, make the input signal level meet the turn-on and turn-off threshold voltage.
- (9) Fo output is open drain type. Fo output will be max 0.95V(@I<sub>FO</sub>=1mA,25°C), so it should be pulled up to MCU or control power supply (e.g. 5V,15V) by a resistor that makes I<sub>FO</sub>up to 1mA. (In the case of pulled up to 5V, 10kΩ is recommended.) About driving opto coupler by Fo output, please refer the application note of this series
- (10) Fo pulse width can be set by the capacitor connected to CFO terminal.  $C_{FO}(F) = 9.1 \times 10^{-6} \times t_{FO}$  (Required Fo pulse width).
- (11) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause DIPIPM erroneous operation. To avoid such problem, line ripple voltage should meet dV/dt ≤+/-1V/μs, Vripple≤2Vp-p.
- (12) For DIPIPM, it isn't recommended to drive same load by parallel connection with other phase IGBT or other DIPIPM.

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Fig. 7 MCU I/O Interface Circuit



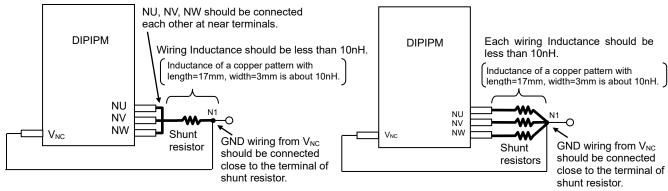
#### Note)

Design for input RC filter depends on PWM control scheme used in the application and wiring impedance of the printed circuit board.

DIPIPM input signal interface integrates a minimum  $3.3k\Omega$  pull-down resistor. Therefore, when inserting RC filter, it is necessary to satisfy turn-on threshold voltage requirement.

Fo output is open drain type. It should be pulled up to the positive side of 5V or 15V power supply with the resistor that limits Fo sink current  $I_{Fo}$  under 1mA. In the case of pulling up to 5V supply, over  $5.1k\Omega$  is needed. (10k $\Omega$  is recommended.)

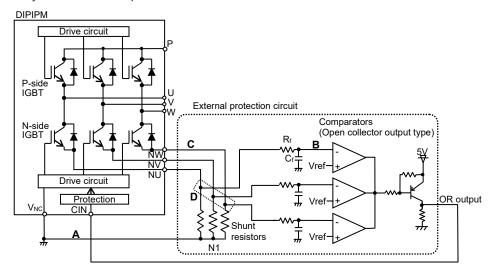
Fig. 8 Pattern Wiring Around the Shunt Resistor



Low inductance shunt resistor like surface mounted (SMD) type is recommended.

Fig. 9 Pattern Wiring Around the Shunt Resistor (for the case of open emitter)

When DIPIPM is operated with three shunt resistors, voltage of each shunt resistor cannot be input to CIN terminal directly. In that case, it is necessary to use the external protection circuit as below.

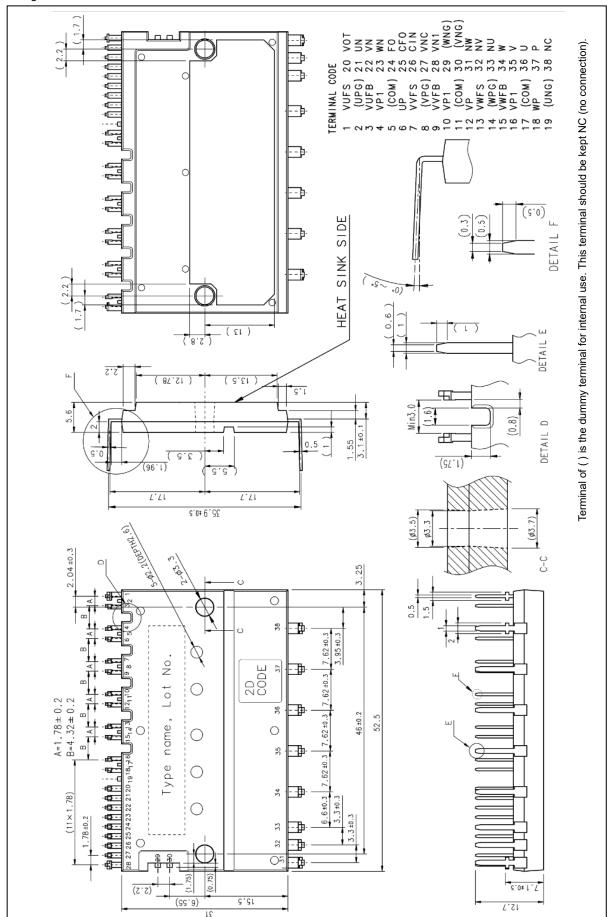


- (1) It is necessary to set the time constant R<sub>f</sub>C<sub>f</sub> of external comparator input so that IGBT stops within 2μs when short circuit occurs. SC interrupting time might vary with the wiring pattern, comparator speed and so on.
- (2) It is recommended for the threshold voltage Vref to set to the same rating of short circuit trip level (Vsc(ref): typ. 0.480V).
- (3) Select the external shunt resistance so that SC trip-level is less than specified value (=2.0 times of rating current).
- (4) To avoid malfunction, the wiring A, B, C should be as short as possible.
- (5) The point D at which the wiring to comparator is divided should be close to the terminal of shunt resistor.
- (6) OR output high level when protection works should be over 0.510V (=maximum Vsc(ref) rating).
- (7) GND of Comparator, GND of Vref circuit and Cf should be not connected to power GND but to control GND wiring.

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Fig. 10 Package Outlines

Dimensions in mm



### **Important Notice**

The information contained in this datasheet shall in no event be regarded as a guarantee of conditions or characteristics. This product has to be used within its specified maximum ratings, and is subject to customer's compliance with any applicable legal requirement, norms and standards.

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