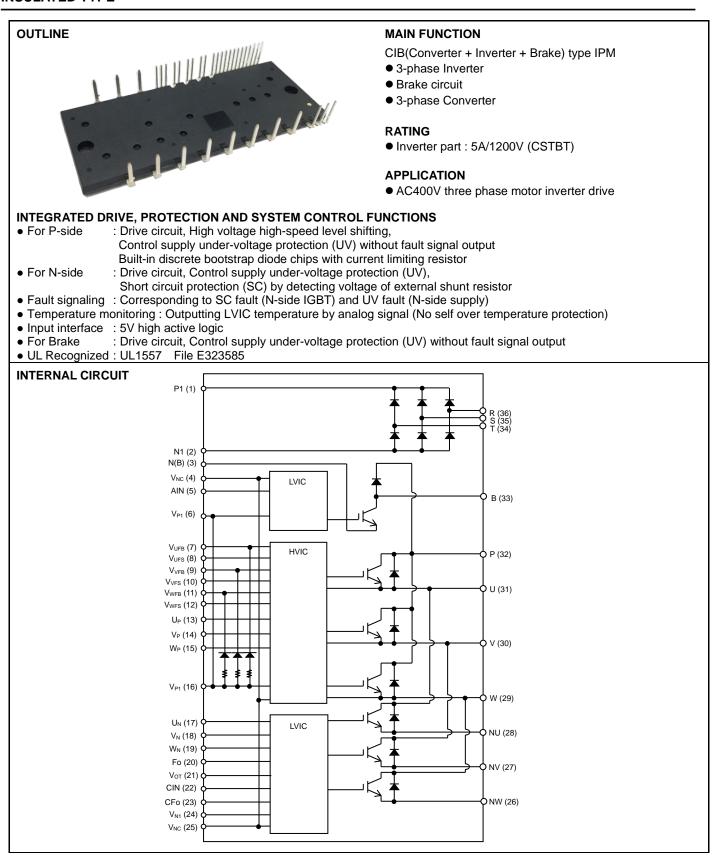


< DIPIPM > **PSS05MC1FT** TRANSFER MOLDING TYPE

INSULATED TYPE



## **MAXIMUM RATINGS** ( $T_j = 25^{\circ}C$ , unless otherwise noted)

### INVERTER PART

Symbol	Parameter	Condition		Ratings	Unit
V <sub>cc</sub>	Supply voltage	Applied between P-NU,NV,NW		900	V
V <sub>CC(surge)</sub>	Supply voltage (surge)	Applied between P-NU,NV,NW		1000	V
V <sub>CES</sub>	Collector-emitter voltage			1200	V
±l <sub>C</sub>	Each IGBT collector current	T <sub>c</sub> = 25°C	(Note 1)	5	Α
±I <sub>CP</sub>	Each IGBT collector current (peak)	T <sub>C</sub> = 25°C, less than 1ms		10	Α
Tj	Junction temperature			-30~+150	°C

#### **BRAKE PART**

Symbol	Parameter	Condition	Ratings	Unit
V <sub>cc</sub>	Supply voltage	Applied between P-N(B)	900	V
V <sub>CC(surge)</sub>	Supply voltage (surge)	Applied between P-N(B)	1000	V
V <sub>CES</sub>	Collector-emitter voltage		1200	V
I <sub>C</sub>	Each IGBT collector current	$T_{C}= 25^{\circ}C$ (Note 1)	5	Α
I <sub>CP</sub>	Each IGBT collector current (peak)	$T_{C}$ = 25°C, less than 1ms	10	Α
V <sub>RRM</sub>	Repetitive peak reverse voltage		1200	V
I <sub>F</sub>	Forward current	T <sub>C</sub> = 25°C	5	Α
I <sub>FP</sub>	Forward current (peak)		10	Α
Tj	Junction temperature		-30~+150	°C

## **CONVERTER PART**

Symbol	Parameter	Condition	Ratings	Unit
V <sub>RRM</sub>	Repetitive peak reverse voltage		1600	V
lo	DC output current	3-phase full wave rectification	5	А
I <sub>FSM</sub>	Surge forward current	Peak value of half cycle at 60Hz, Non-repetitive	150	А
l <sup>2</sup> t	l <sup>2</sup> t capability	Value for 1 cycle of surge current	94.5	A <sup>2</sup> s
Tj	Junction temperature		-30~+150	°C

#### **CONTROL (PROTECTION) PART**

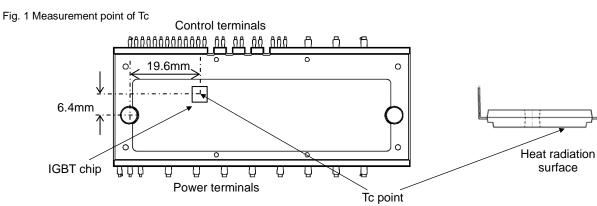
Symbol	Parameter		Condition		Unit
VD	Control supply voltage	Applied between V	/ <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	20	V
V <sub>DB</sub>	Control supply voltage	Applied between V	/ <sub>UFB</sub> -V <sub>UFS</sub> , V <sub>VFB</sub> -V <sub>VFS</sub> , V <sub>WFB</sub> -V <sub>WFS</sub>	20	V
V <sub>IN</sub>	Input voltage	Applied between L	$J_P, V_P, W_P, U_N, V_N, W_N, AIN-V_{NC}$	-0.5~V <sub>D</sub> +0.5	V
V <sub>FO</sub>	Fault output supply voltage	Applied between F	F <sub>o</sub> -V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V
I <sub>FO</sub>	Fault output current	Sink current at Fo term	Sink current at Fo terminal		mA
V <sub>SC</sub>	Current sensing input voltage	Applied between	CIN-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V

Note1: Pulse width and period are limited due to junction temperature.

#### TOTAL SYSTEM

Symbol	Parameter	Condition	Ratings	Unit
V <sub>CC(PROT)</sub>	Self protection supply voltage limit (Short circuit protection capability)	$V_D = 13.5 \sim 16.5 V$ , Inverter Part T <sub>i</sub> = 125°C, non-repetitive, less than 2µs	800	V
Tc	Module case operation temperature	(Note 2)	-30~+110	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C
V <sub>iso</sub>	Isolation voltage	60Hz, Sinusoidal, AC 1min, between connected all pins and heat sink plate	2500	V <sub>rms</sub>

Note2: Measurement point of Tc is described in Fig.1.



### THERMAL RESISTANCE

Symbol	Parameter	Condition		Limits			
Symbol	-,	Condition	Min.	Тур.	Max.	Unit	
R <sub>th(j-c)Q</sub>	Junction to case thermal resistance (Note 3)	Inverter IGBT part (per 1/6 module)	-	-	1.90		
R <sub>th(j-c)F</sub>		Inverter FWD part (per 1/6 module)	-	-	2.50		
R <sub>th(j-c)Q</sub>		Brake IGBT part (per 1module)	-	-	1.90	K/W	
R <sub>th(j-c)F</sub>		Brake FWD part (per 1module)	-	-	2.50		
R <sub>th(j-c)R</sub>		Converter part (per 1/6module)	-	-	1.60		

Note 3: Grease with good thermal conductivity and long-term endurance should be applied evenly with about +100µm~+200µm on the contacting surface of DIPIPM and heat sink. The contacting thermal resistance between DIPIPM case and heat sink Rth(c-f) is determined by the thickness and the thermal conductivity of the applied grease. For reference, Rth(c-f) is about 0.25K/W (per 1chip, grease thickness: 20µm, thermal conductivity: 1.0W/m•K).

# **ELECTRICAL CHARACTERISTICS** ( $T_j = 25^{\circ}C$ , unless otherwise noted)

# INVERTER PART

Cumbal	Doromotor	Cond	ition			1.1.4.14		
Symbol	Parameter	Cond	Condition		Min.	Тур.	Max.	Unit
V	Collector-emitter saturation	$V_{D} = V_{DB} = 15V, V_{IN} = 5V$	I <sub>C</sub> = 5A,	T <sub>j</sub> = 25°C	-	1.30	1.70	V
V <sub>CE(sat)</sub>	voltage	$v_{\rm D} = v_{\rm DB} = 13v, v_{\rm IN} = 5v$	I <sub>C</sub> = 5A,	T <sub>j</sub> = 125°C	-	1.50	1.90	v
V <sub>EC</sub>	FWDi forward voltage	$V_{IN}=0V, -I_C=5A$		-	1.90	2.40	V	
t <sub>on</sub>					1.10	1.90	2.60	μs
t <sub>C(on)</sub>		$V_{CC}$ = 600V, $V_{D}$ = $V_{DB}$ = 15V			-	0.60	0.90	μs
t <sub>off</sub>	Switching times	I <sub>C</sub> = 5A, T <sub>j</sub> = 125°C, V <sub>IN</sub> = 0↔5V	,		-	2.80	3.80	μs
t <sub>C(off)</sub>		Inductive Load (upper-lower a	arm)		-	0.50	1.00	μs
t <sub>rr</sub>					-	0.60	-	μs
	Collector-emitter cut-off		T <sub>j</sub> = 25°C	-	-	1		
ICES	current	V <sub>CE</sub> =V <sub>CES</sub>		T <sub>j</sub> = 125°C	-	-	10	mA

#### **BRAKE PART**

Sumbol	Parameter	Cond	ition				Unit	
Symbol	Falameter	Cond	Condition		Min.	Тур.	Max.	Unit
V	Collector-emitter saturation	$V_{D} = V_{DB} = 15V, V_{IN} = 5V$	I <sub>C</sub> = 5A, T <sub>j</sub> = 25°0	)	-	1.30	1.70	V
V <sub>CE(sat)</sub>	voltage	$v_{\text{D}} = v_{\text{DB}} = 13v, v_{\text{IN}} = 3v$	I <sub>C</sub> = 5A, T <sub>j</sub> = 125°	С	-	1.50	1.90	v
V <sub>F</sub>	FWDi forward voltage	$V_{IN}=0V, I_F=5A$		-	1.90	2.40	V	
t <sub>on</sub>					1.00	1.80	2.40	μs
t <sub>C(on)</sub>		$V_{CC}$ = 600V, $V_{D}$ = $V_{DB}$ = 15V			-	0.40	0.70	μs
t <sub>off</sub>	Switching times	I <sub>C</sub> = 5A, T <sub>j</sub> = 125°C, V <sub>IN</sub> = 0↔5V			-	2.60	3.60	μs
t <sub>C(off)</sub>		Inductive Load			-	0.50	1.00	μs
t <sub>rr</sub>				-	0.50	-	μs	
1	Collector-emitter cut-off	V <sub>CE</sub> =V <sub>CES</sub>	T <sub>j</sub> = 25°	C	-	-	1	mA
I <sub>CES</sub>	current	V CE= V CES	T <sub>j</sub> = 125°C	°C	-	-	10	mA

#### CONVERTER PART

Symbol Parameter	Perometer	Condition	Limits			Unit
	Condition	Min.	Тур.	Max.	Unit	
I <sub>RRM</sub>	Repetitive reverse current	V <sub>R</sub> =V <sub>RRM</sub> , Tj=125°C	-	-	7.0	mA
V <sub>F</sub>	Forward voltage drop	I <sub>F</sub> =5A	-	1.1	1.4	V

# CONTROL (PROTECTION) PART

Sumbol	Parameter	Conc	lition		Limits		Unit
Symbol	Parameter	Conc	illion	Min.	Тур.	Max.	Unit
1			Total of $V_{P1}$ - $V_{NC}$ , $V_{N1}$ - $V_{NC}$ $V_D$ =15V, $V_{IN}$ =0V		-	5.70	
ID	Circuit current	IDIALOI $V_{P1} V_{NC}$ , $V_{N1} V_{NC}$	V <sub>D</sub> =15V, V <sub>IN</sub> =5V	-	-	5.70	mA
1		Each part of V <sub>UFB</sub> -V <sub>UFS</sub> ,	$V_D = V_{DB} = 15V, V_{IN} = 0V$	-	-	0.55	mA
I <sub>DB</sub>		$V_{VFB}$ - $V_{VFS}$ , $V_{WFB}$ - $V_{WFS}$	$V_D = V_{DB} = 15V, V_{IN} = 5V$	-	-	0.55	
V <sub>SC(ref)</sub>	Short circuit trip level	V <sub>D</sub> = 15V	(Note 4)	0.455	0.480	0.505	V
UV <sub>DBt</sub>	Control supply under-voltage		Trip level	10.0	-	12.0	V
UV <sub>DBr</sub>	protection(UV) for P-side of inverter part		Reset level	10.5	-	12.5	V
UV <sub>Dt</sub>	Control supply under-voltage		Trip level	10.3	-	12.5	V
UV <sub>Dr</sub>	protection(UV) for N-side of inverter part and brake part		Reset level	10.8	-	13.0	V
V <sub>OT</sub>	Temperature Output	Pull down R=5.1kΩ, LVIC Terr	nperature=100°C (Note 5)	2.89	3.02	3.14	V
V <sub>FOH</sub>		$V_{SC}$ = 0V, F <sub>0</sub> terminal pulled u	p to 5V by 10kΩ	4.9	-	-	V
V <sub>FOL</sub>	Fault output voltage	$V_{SC} = 1V$ , $I_{FO} = 1mA$		-	-	0.95	V
t <sub>FO</sub>	Fault output pulse width	In case of $C_{Fo}=22nF$	(Note 6,7)	1.6	2.4	-	ms
I <sub>IN</sub>	Input current	$V_{IN} = 5V$		0.70	1.00	1.50	mA
V <sub>th(on)</sub>	ON threshold voltage			-	-	3.5	v
V <sub>th(off)</sub>	OFF threshold voltage	Applied between $U_P$ , $V_P$ , $W_P$ , $U_N$ , $V_N$ , $W_N$ , AIN- $V_{NC}$		0.8	-	-	V
V <sub>F</sub>	Bootstrap Di forward voltage	I <sub>F</sub> =10mA including voltage drop	o by limiting resistor (Note 8)	-	0.9	1.3	V
R	Built-in limiting resistance	Included in bootstrap Di		16	20	24	Ω

Note 4 : SC protection works only for N-side IGBT in inverter part. Please select the external shunt resistance such that the SC trip-level is less than 1.7 times of the current rating.

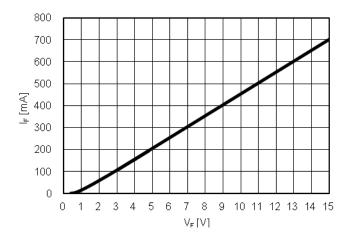
5: DIPIPM don't shutdown IGBTs and output fault signal automatically when temperature rises excessively. When temperature exceeds the protective level that user defined, controller (MCU) should stop the DIPIPM. Temperature of LVIC vs. Vot output characteristics is described in Fig. 3.

6 : Fault signal Fo outputs when SC or UV protection works for N-side IGBT in inverter part. The fault output pulse-width tFo is depended on the capacitance value of CFO (CFO = tFO × 9.1 × 10<sup>-6</sup> [F]).

7: UV protection also works for P-side IGBT in inverter part or brake part without fault signal Fo.

8 : The characteristics of bootstrap Di is described in Fig.2.

Fig. 2 Characteristics of Bootstrap Di V<sub>F</sub>-I<sub>F</sub> curve (@Ta=25°C) Including Voltage Drop by Limiting Resistor (Right chart is enlarged chart.)



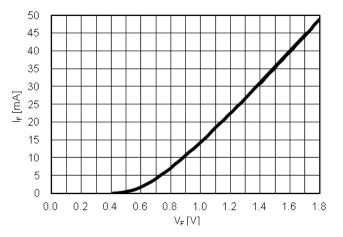


Fig. 3 Temperature of LVIC vs.  $V_{OT}$  Output Characteristics

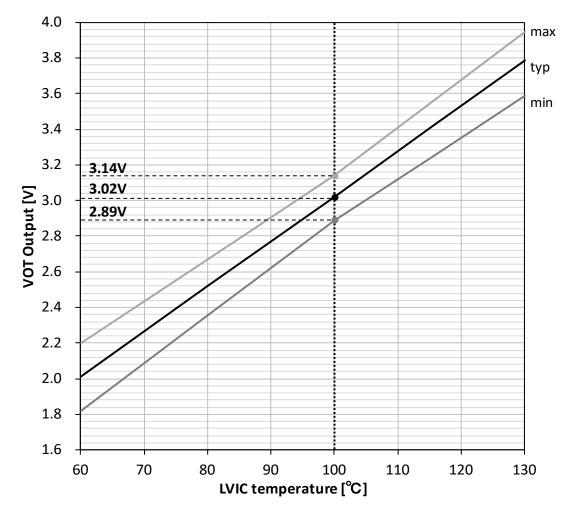
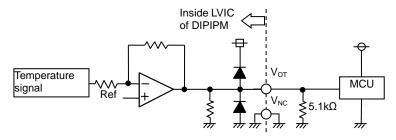


Fig. 4 Pattern Wiring Around the Analog Voltage Output Circuit [Vot terminal]



(1) Vor outputs the analog signal that is amplified signal of temperature detecting element on LVIC by inverting amplifier. (2) It is recommended to insert 5kΩ (5.1kΩ is recommended) pull down resistor for getting linear output characteristics at low temperature below room temperature. When the pull down resistor is inserted between VoT and VNC (control GND), the extra circuit current, which is calculated approximately by Vor output voltage divided by pull down resistance, flows as LVIC circuit current continuously. In the case of using Vor for detecting high temperature over room temperature only, it is unnecessary to insert the pull down resistor. (3) In the case of not using  $V_{OT}$ , leave  $V_{OT}$  output NC (No Connection).

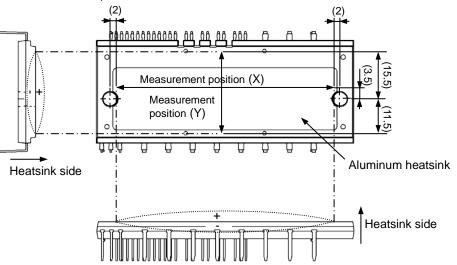
Refer the application note for DIPIPM+ series about the usage of Vor.

#### MECHANICAL CHARACTERISTICS AND RATINGS

Parameter	Cond	ition			Unit	
Parameter	Condition		Min.	Тур.	Max.	Unit
Mounting torque	Mounting screw : M4 (Note 9)	Recommended 1.18N·m	0.98	1.18	1.47	N∙m
Terminal pulling strength	20N load	EIAJ-ED-4701	10	-	-	s
Terminal bending strength	90deg bending with 10N load	EIAJ-ED-4701	2	-	-	times
Weight			-	40	-	g
Heat radiation part flatness	(Note 10)		-50	-	+100	μm

Note 9: Plain washers (ISO 7089~7094) are recommended.

Note 10: Measurement positions of heat radiation part flatness are as below.



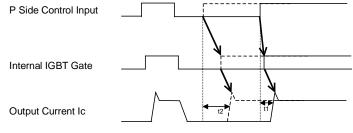
#### **RECOMMENDED OPERATION CONDITIONS**

Symbol	Parameter	Condition		Limits			Unit
Symbol	Falameter	Condition		Min.	Тур.	Max.	Unit
V <sub>cc</sub>	Supply voltage	Applied between P-NU,NV,NW		0	600	800	V
V <sub>D</sub>	Control supply voltage	Applied between $V_{P1}$ - $V_{NC}$ , $V_{N1}$ - $V_{NC}$		13.5	15.0	16.5	V
V <sub>DB</sub>	Control supply voltage	Applied between VUFB-VUFS, VVFB-VV	<sub>VFS</sub> ,V <sub>WFB</sub> -V <sub>WFS</sub>	13.0	15.0	18.5	V
$\Delta V_D, \Delta V_{DB}$	Control supply variation			-1	-	1	V/µs
t <sub>dead</sub>	Arm shoot-through blocking time	For each input signal		3.0	-	-	μs
f <sub>PWM</sub>	PWM input frequency	T <sub>C</sub> ≤100°C, T <sub>i</sub> ≤125°C		-	-	20	kHz
PWIN(on)		I <sub>C</sub> ≤1.7 times of rated current	(Note 11)	1.5	-	-	
		0≤V <sub>CC</sub> ≤800V, 13.5≤V <sub>D</sub> ≤16.5V,	Less than rated current	3.0	-	-	
PWIN(off)	Minimum input pulse width	$\begin{array}{llllllllllllllllllllllllllllllllllll$	From rated current to 1.7 times of rated current	3.5	-	-	μs
V <sub>NC</sub>	V <sub>NC</sub> variation	Between V <sub>NC</sub> - NU、NV、NW (includ	ing surge)	-5.0	-	+5.0	V
Tj	Junction temperature			-20	-	125	°C

Note 11: DIPIPM might not make response if the input signal pulse width is less than PWIN(on).

12: DIPIPM might make no response or delayed response (P-side IGBT only) for the input signal with off pulse width less than PWIN(off). Please refer below figure about delayed response.

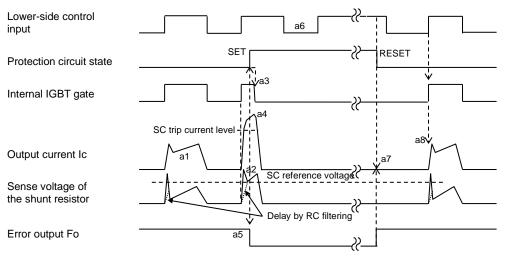
About Delayed Response Against Shorter Input Off Signal Than PWIN(off) (P side only)



Real line…off pulse width>PWIN(off); turn on time t1 Broken line…off pulse width<PWIN(off); turn on time t2 Fig. 5 Timing Charts of The DIPIPM Protective Functions

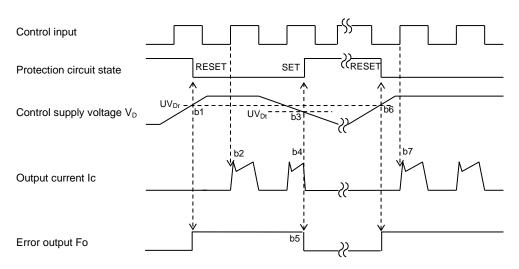
[A] Short-Circuit Protection (N-side only with the external shunt resistor and RC filter)

- a1. Normal operation: IGBT ON and outputs current.
- a2. Short circuit current detection (SC trigger)
- (It is recommended to set RC time constant 1.5~2.0µs so that IGBT shut down within 2.0µs when SC.)
- a3. All N-side IGBT's gates are hard interrupted.
- a4. All N-side IGBTs turn OFF.
- a5. LVIC starts outputting fault signal (fault signal output time is controlled by external capacitor  $C_{\mbox{\scriptsize FO}})$
- a6. Input = "L": IGBT OFF
- a7. Fo finishes output, but IGBTs don't turn on until inputting next ON signal (L $\rightarrow$ H).
- (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- a8. Normal operation: IGBT ON and outputs current.



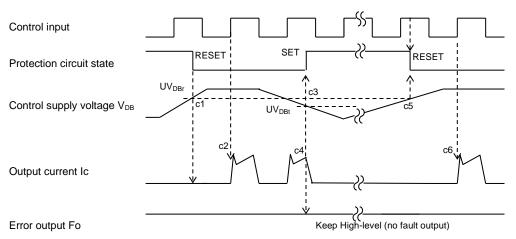
[B] Under-Voltage Protection (N-side, UV<sub>D</sub>)

- b1. Control supply voltage  $V_D$  exceeds under voltage reset level (UV<sub>Dr</sub>), but IGBT turns ON by next ON signal (L $\rightarrow$ H). (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- b2. Normal operation: IGBT ON and outputs current.
- b3. V<sub>D</sub> level drops to under voltage trip level. (UV<sub>Dt</sub>).
- b4. All N-side IGBTs turn OFF in spite of control input condition.
- b5. Fo outputs for the period set by external capacitor C<sub>FO</sub>, but output is extended during V<sub>D</sub> keeps below UV<sub>Dr</sub>.
- b6.  $V_D$  level reaches  $UV_{Dr}$ .
- b7. Normal operation: IGBT ON and outputs current.



[C] Under-Voltage Protection (P-side,  $UV_{DB}$ )

- c1. Control supply voltage  $V_{DB}$  rises. After the voltage reaches under voltage reset level  $UV_{DBr}$ , IGBT turns on by next ON signal (L $\rightarrow$ H).
- c2. Normal operation: IGBT ON and outputs current.
- c3.  $V_{\text{DB}}$  level drops to under voltage trip level (UV\_{\text{DBt}}).
- c4. IGBT of the correspond phase only turns OFF in spite of control input signal level, but there is no  $F_0$  signal output.
- c5.  $V_{\text{DB}}$  level reaches  $UV_{\text{DBr}}$
- c6. Normal operation: IGBT ON and outputs current.



[D] UV protection sequence for Brake circuit (UV<sub>D</sub>)

- d1. Control supply voltage  $V_D$  rises. After the voltage reaches under voltage reset level  $UV_{Dr}$ , IGBT turns on by next ON signal (L $\rightarrow$ H).
- d2. Normal operation: (turning IGBT on and starting conducting current)
- d3.  $V_{\text{D}}$  level drops to under voltage trip level (UV\_{\text{Dt}}).
- d4. IGBT of the Brake circuit turns OFF in spite of control input signal level, but there is no Fo signal output.
- d5.  $V_{DB}$  level reaches  $UV_{Dr}$ .
- d6. Normal operation: (turning IGBT on and starting conducting current)

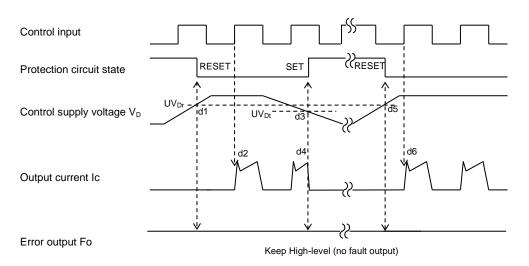
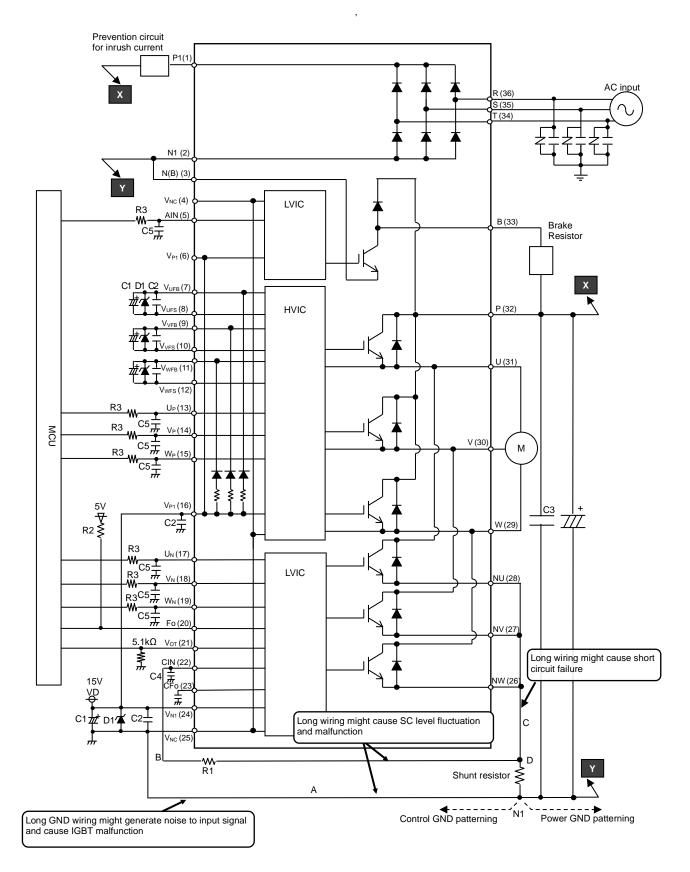


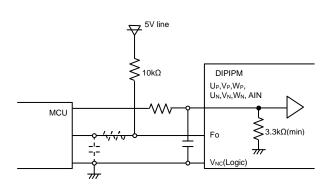
Fig. 6 Example of Application Circuit



#### Note for the previous application circuit

- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert a Zener diode D1(24V/1W) between each pair of control supply terminals to prevent surge destruction.
- (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible.
- Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
- (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type. The time constant R1C4 should be set so that SC current is shut down within 2µs. (1.5µs~2µs is recommended generally.) SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (6) The point D at which the wiring to CIN filter is divided should be near the terminal of shunt resistor. NU, NV, NW terminals should be connected each other at near those three terminals when it is used by one shunt operation. Low inductance SMD type with tight tolerance, temp-compensated type is recommended for shunt resistor.
- (7) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2:0.01µ-2µF, good temperature, frequency and DC bias characteristic ceramic type are recommended.)
- (8) Input logic is High-active. There is a 3.3kΩ(min.) pull-down resistor in the input circuit of IC. To prevent malfunction, the input wiring should be as short as possible. When using RC coupling, make the input signal level meet the turn-on and turn-off threshold voltage.
- (9) Fo output is open drain type. Fo output will be max 0.95V(@I<sub>FO</sub>=1mA,25°C), so it should be pulled up to MCU or control power supply (e.g. 5V,15V) by a resistor that makes I<sub>FO</sub>up to 1mA. (In the case of pulled up to 5V, 10kΩ is recommended.) About driving opto coupler by Fo output, please refer the application note of this series.
- (10) Fo pulse width can be set by the capacitor connected to CFO terminal.  $C_{FO}(F) = 9.1 \times 10^{-6} \times t_{FO}$  (Required Fo pulse width).
- (11) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause DIPIPM erroneous operation. To avoid such problem, line ripple voltage should meet dV/dt ≤+/-1V/µs, Vripple≤2Vp-p.
- (12) For DIPIPM, it isn't recommended to drive same load by parallel connection with other phase IGBT or other DIPIPM.
- (13) No.4 and No.25 V<sub>NC</sub> terminals (GND terminal for control supply) are connected mutually inside of DIPIPM+ and also No.6 and No.16 V<sub>P1</sub> terminals are connected mutually inside, please connect either No.4 or No.25 terminal to GND and also connect either No.6 or No.16 terminal to supply and make the unused terminal leave no connection.

Fig. 7 MCU I/O Interface Circuit



Note)

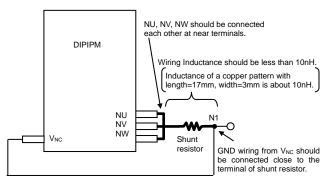
Design for input RC filter depends on the PWM control scheme used in the application and the wiring impedance of the printed circuit board. But because noisier in the application for 1200V rating it is strongly.

But because noisier in the application for 1200V rating, it is strongly recommended to insert RC filter. (Time constant: over 100ns. e.g.  $100\Omega$ , 1000pF)

The DIPIPM input signal interface integrates a min.  $3.3k\Omega$  pull-down resistor. Therefore, when using RC filter, be careful to satisfy turn-on threshold voltage requirement.

Fo output is open drain type. It should be pulled up to the positive side of 5V or 15V power supply with the resistor that limits Fo sink current  $I_{Fo}$  under 1mA. In the case of pulling up to 5V supply, over 5.1k $\Omega$  is needed. (10k $\Omega$  is recommended.)

#### Fig. 8 Pattern Wiring Around the Shunt Resistor



Low inductance shunt resistor like surface mounted (SMD) type is recommended.

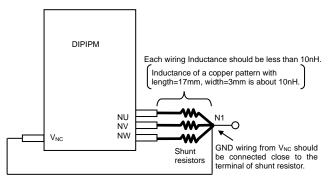
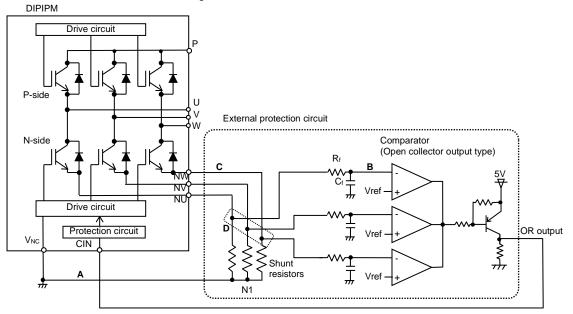
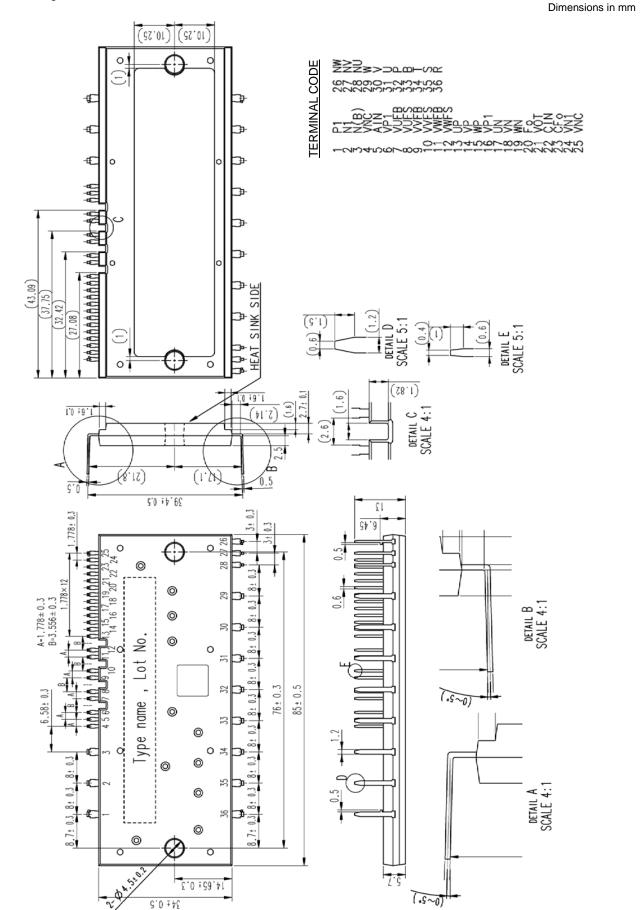


Fig. 9 External SC Protection Circuit with Using Three Shunt Resistors



- (1) It is necessary to set the time constant R<sub>f</sub>C<sub>f</sub> of external comparator input so that IGBT stop within 2µs when short circuit occurs. SC interrupting time might vary with the wiring pattern, comparator speed and so on.
- (2) The threshold voltage Vref should be set up the same rating of short circuit trip level (Vsc(ref) typ. 0.48V).
- (3) Select the external shunt resistance so that SC trip-level is less than specified value.
- (4) To avoid malfunction, the wiring A, B, C should be as short as possible.
- (5) The point D at which the wiring to comparator is divided should be near the terminal of shunt resistor.
- (6) OR output high level should be over 0.505V (=maximum Vsc(ref)).
- (7) GND of Comparator, Vref circuit and Cf should be not connected to noisy power GND but to control GND wiring.

Fig. 10 Package Outlines



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