Creating the first project in

mikroPascal PRO for PIC32°



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Nebojsa Matic General Manager

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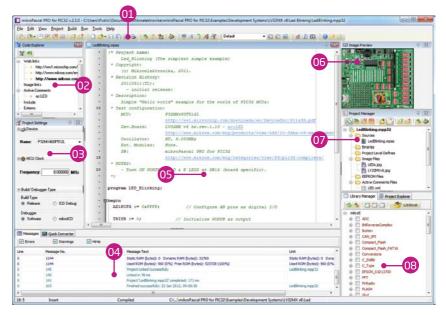
1. Introduction to mikroPascal PRO for PIC32[®]

mikroPascal PRO for PIC32[®] organizes applications into projects consisting of a single project file (file with the **.mpp32** extension) and one or more source files (files with the .mpas extension). The mikroPascal PRO for PIC32[®] compiler allows you to manage several projects at a time. Source files can be compiled only if they are part of the project.

A project file contains:

- Project name and optional description;
- Target device in use;
- Device clock;
- List of the project source files;
- Binary files (*.emcl); and
- Other files.

In this reference guide, we will create a new project, write code, compile it and test the results. The purpose of this project is to make microcontroller PORTB LEDs blink, which will be easy to test.





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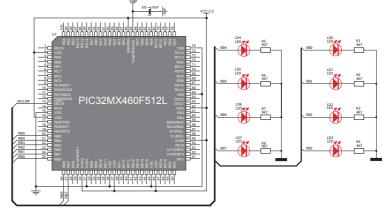


2. Hardware Connection

Figure 2-1: Hardware connection schematics

Let's make a simple "Hello world" example for the selected microcontroller. First thing embedded programmers usually write is a simple **LED blinking** program. So, let's do that in a few simple lines of Pascal code.

LED blinking is just turning ON and OFF LEDs that are connected to desired PORT pins. In order to see the example in action, it is necessary to connect the target microcontroller according to schematics shown on **Figure 2-1**. In the project we are about to write, we will use only **PORTB**, so you should connect the LEDs to PORTB only. Eight LEDs are more then enough for demonstration. You don't have to connect all 16 PORTB pins.



Prior to creating a new project, it is necessary to do the following:

Step 1: Install the compiler

Install the mikroPascal PRO for PIC32[®] compiler from the **Product DVD** or download it from the MikroElektronika website:

Step 2: Start up the compiler

Double click on the compiler icon in the Start menu, or on your desktop to Start up the mikroPascal PRO for PIC32[®] compiler. The mikroPascal PRO for PIC32[®] IDE (Integrated Development Environment) will appear on the screen. Now you are ready to start creating a new project.

3. Creating a New Project

The process of creating a new project is very simple. Select the **New Project** option from the **Project menu** as shown below. The **New Project Wizard** window appears. It can also be opened by clicking the **New Project icon** from the **Project toolbar**.

<u>P</u> roj	ect	<u>B</u> uild	<u>R</u> un	<u>T</u> ools	<u>H</u> elp
8	<u>N</u> e	w Projec	:t	Shift	t+Ctrl+N
8	<u>О</u> р	en Proje	ect	Shift	t+Ctrl+O
8	Op	en Proje	ct Gro	up	
	<u>R</u> ec	ent Pro	jects		•

The **New Project Wizard** (Figure 3-1) will guide you through the process of creating a new project. The introductory window of this application contains a list of actions to be performed when creating a new project.





Figure 3-1: Introductory window of the New Project Wizard

Step 1 - Project Settings

First thing we have to do is to specify the general project information. This is done by selecting the target microcontroller, it's operating clock frequency, and of course - naming our project. This is an important step, because compiler will adjust the internal settings based on this information. Default configuration is already suggested to us at the begining. We will not change the microcontroller, and we will leave the default **PIC32MX460F512L** as the choice for this project.

New Project Wiza	rd	×
Step 1: Project 9	Settings:	
Device Name:	C:\Users\Public\Documents\Mikroelektronika\mikro(P32MX460F512L	Browse
Device Clock:	10.000000 MHz	
(for example: 96	ne, project folder, select device name and enter a device clock 235). ame and project folder must not be left empty.	
	◆ <u>B</u> ack Next →	<u>C</u> ancel

Figure 3-2: You can specify project name, path, device and clock in the first step

Step 1 - Project Settings

If you do not want to use the suggested path for storing your new project, you can **change the destination folder**. In order to do that, follow a simple procedure:

- OI Click the Browse button of the Project Settings window to open the Browse for Folder dialog.
 - Select the desired folder to be the destination path for storing your new project files.
- Click the **OK** button to confirm your selection and apply the new path.

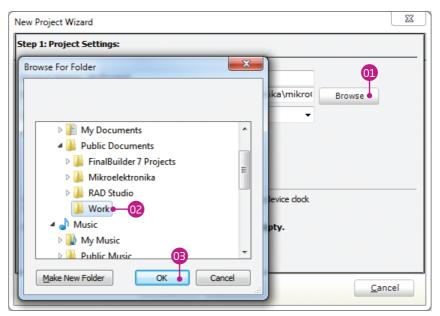


Figure 3-3: Change the destination folder using Browse For Folder dialog

Step 1 - Project Settings

Once we have selected the destination project folder, let's do the rest of the project settings:

- Enter the name of your project. Since we are going to blink some LEDs, it's appropriate to call the project "LedBlinking"
- For this demonstration, we will use the default **80MHz clock (PLL enabled)**. Clock speed depends on your target hardware, and whether you are using PLL or not. But however you configure your hardware, make sure to specify the exact clock (**Fosc**) that the microcontroller is operating at.



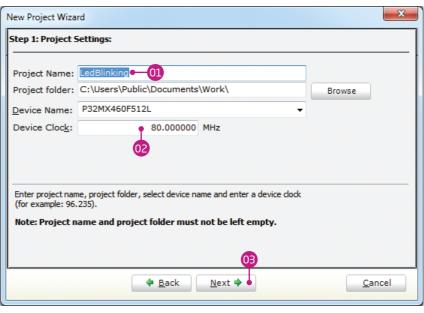


Figure 3-4: Enter project name and change device clock speed if necessary

Step 2 - Add files

This step allows you to include additional files that you need in your project: some headers or source files that you already wrote, and that you might need in further development. Since we are building a simple application, we won't be adding any files at this moment.



New Project Wizard	×
Step 2: Select files you want to add to project.	
Add File To Project:	
l l l l l l l l l l l l l l l l l l l	<u>A</u> dd
File Name	<u>R</u> emove
	Re <u>m</u> ove All
01	
◆ <u>B</u> ack Next →	<u>C</u> ancel

Figure 3-5: Add existing headers, sources or other files if necessary

Step 3 - Include Libraries

Following step allows you to quickly set whether you want to include all libraries in your project, or not. Even if all libraries are included, they will not consume any memory unless they are explicitely used from within your code. The main advantage of including all libraries is that you will have over **500 functions** available for use in your code right away, and visible from **Code Assistant [CTRL+Space]**. We will leave this in default configuration:



Make sure to leave **"Include All"** selected.

2 Click Next.

New Project Wizard	X
Step 3: Select initial state for library manager:	
Include Libraries Include All (Default) Include None (Advanced)	
Selecting all libraries is recommended for beginners. Selecting libraries manually using Library Manager (recommended for advanced users) results in faster compilation.	Library Manager Help
↓ Back Next →	Cancel

Figure 3-6: Include all libraries in the project, which is a default configuration.

Step 4 - Finishing

After all configuration is done, final step allows you to do just a bit more.

There is a check-box called "Open Edit 01 Project window to set Configuration bits" at the final step. Edit Project is a specialized window which allows you to do all the necessary oscillator and PLL settings, as well as to set other configuration bits. We made sure that everything is described in plain English, so you will be able to do the settings without having to open the datasheet. Anyway, since we are only building a simple application, we will leave it at default configuration (HS oscillator with PLL enabled). Therefore, leave the checkbox unchecked.

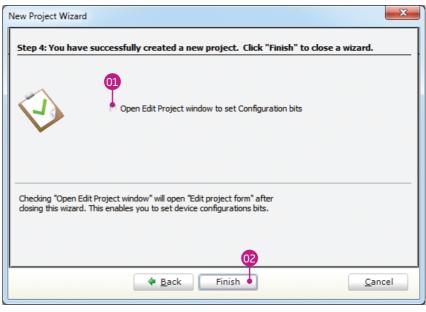


Figure 3-7: Choose whether to open Edit Project window after dialog closes.

Blank new project created

New project is finally created. A new source file called "LedBlinking.mpas" is created and it contains the begin...end. block, which will hold the program. You may notice that project is configured according to the settings done in the New Project Wizard.

SVIC	e
Name:	P32MX460F512L
	Clock
Frequen	cy: 80.000000 MHz
uid/ De	bugger Type
	Baggor 1790

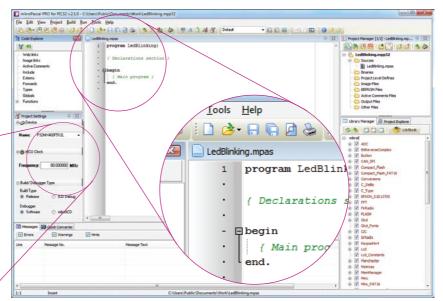


Figure 3-8: New blank project is created with your configuration

4. Code Example

Time has come to do some coding. First thing we need to do is to disable analog function of PORTB pins, so they act as digital only:

```
// Configure AN pins as digital I/O
AD1PCFG := 0xFFFF;
```

Now we have to initialize PORTB to act as digital output. TRISB register, associated with PORTB, is used to set whether each pin acts as input or output.

```
// set PORTB to be digital output
TRISB := 0;
```

LATB register is used instead of PORTB for digital output. We can now initialize it with logic zeros on every pin:

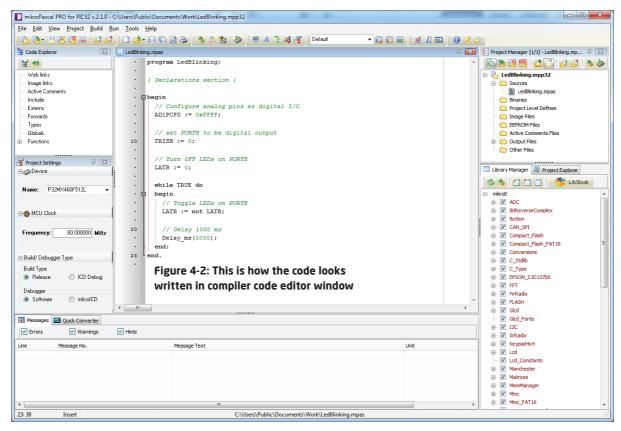
```
// Turn OFF LEDs on PORTB
LATB := 0;
```

Finally, in a **while** loop we will toggle the PORTB value, and put a 1000 ms delay, so the blinking is not too fast (see **Figure 4-1**).

LedBlinking.mpas - source code

```
program LedBlinking;
 1
 2
    begin
      // Configure analog pins as digital I/O
 3
      AD1PCFG := 0xFFFF;
 4
 5
 6
      // set PORTB to be digital output
 7
      TRISB := 0:
 8
 9
      // Turn OFF LEDs on PORTB
10
      LATB := 0;
11
      while TRUE do
12
13
      begin
14
        // Toggle LEDs on PORTB
15
        LATB := not LATB;
16
17
        // Delav 1000 ms
        Delay ms(1000);
18
19
      end:
    end.
20
```

Figure 4-1: Complete source code of the PORTB LED blinking



5. Building the Source

When we are done writing our first LedBlinking code, we can now build the project and create a **.HEX** file which can be loaded into our target microcontroller, so we can test the program on real hardware. "Building" includes compilation, linking and

<u>B</u> uil	d	<u>R</u> un	<u>T</u> ools	He	lp
�	B	uild			Ctrl+F9
	R	ebuild	All Sour	ces	Alt+F9
3	В	<u>u</u> ild Al	l Project	s	Shift+F9
	<u>S</u>	top Bu	ild All		Ctrl+F12
2	В	u <u>i</u> ld +	Program	1	Ctrl+F11

optimization which are done automatically. Build your code by clicking on the sicon in the main toolbar, or simply go to **Build menu** and click **Build [CTRL+F9]**. Message window will report the details of the building process (**Figure 5-2**). Compiler automatically creates necessary output files. **LedBlinking.hex** (**Figure 5-1**) is among them.

Name	Date modified	Туре	Size
LedBlinking.asm	1/22/2012 10:20 AM	ASM File	1 KB
LedBlinking.brk	1/22/2012 10:21 AM	BRK File	1 KB
LedBlinking.cfg	1/22/2012 10:21 AM	CFG File	1 KB
LedBlinking.dbg	1/22/2012 10:20 AM	DBG File	102 KB
📕 LedBlinking	1/22/2012 10:21 AM	Adobe Illustrator S	157 KB
LedBlinking.dlt	1/22/2012 10:20 AM	DLT File	4 KB
LedBlinking.emcl	1/22/2012 10:20 AM	EMCL File	14 KB
LedBlinking.hex	1/22/2012 10:20 AM	HEX File	2 KB
LedBlinking	1/22/2012 10:20 AM	Text Document	3 KB
LedBlinking.lst	1/22/2012 10:20 AM	LST File	8 KB
🕎 LedBlinking.mpas	1/22/2012 10:20 AM	mikroPascal sourc	1 KB
LedBlinking.mpas	1/22/2012 10:21 AM	Configuration sett	1 KB
LedBlinking.mpp32	1/22/2012 10:21 AM	mikroPascal proje	2 KB
LedBlinking.mpp32_callerta	1/22/2012 10:20 AM	Text Document	1 KB
LedBlinking.user	1/22/2012 10:21 AM	Text Document	0 KB

Figure 5-1: Listing of project files after building is done

-				
🔢 Message	es 🔜 Quick Converter			
Errors	Warnings Hint	3		
Line	Message No.	Message Text		Unit
0	1144	Static RAM (bytes	s): 64 Dynamic RAM (bytes): 32765	Static RAM (bytes): 64 Dyn
0	1144	Used ROM (bytes): 484 (0%) Free ROM (bytes): 523804 (100%)	Used ROM (bytes): 484 (0%
0	145	Project Linked Su	ccessfully	LedBlinking.mpp32
0	140	Linked in 749 ms		_
0	141	Project 'LedBlinkin	ng.mpp32' completed: 1108 ms	E
0	103	Finished successf	ully: 22 Jan 2012, 10:23:04	LedBlinking.mpp32
•		"	1	4
23: 38	Insert	Compiled	C:\Users\Public\Documents\Work\LedBlinking.mpas	

Figure 5-2: After the successful compilation and linking, the message window should look something like this

6. Changing Project Settings

If you need to change the target microcontroller or clock speed, you don't have to go through the new project wizard all over again. This can be done quickly in the **Edit Project** window. You can open it using **Project->Edit Project [CTRL+SHIFT+E]** menu option.

2x Divider PLL Multiplier 20x Multi	PLL Input Divider	MCU and Oscillator
PLL Pruitapiter 20x Multiplier 20x	2x Divider	
USB PLL Input Divider I2X Divider Interrupt Control: I2X Divider Interrupt Control: Disabled and Bypassed Single Vector Base Address EBASE: 0x 9FC0 1000 System PLL Output Clock Divider Wild Vector PLL Divide by 1 Vector Spacing (VS): SRS Priority Level: Oscillator Selection Bits Primary Oscillator Enable Vector Spacing (VS): SRS Priority 7 Enabled Vector Spacing (VS): SRS Priority 7 Load Scheme Enabled Vector Spacing (VS): SRS Priority 7 Save Scheme Enabled Vector Spacing (VS): SRS Priority 7 Load Scheme Enabled Vector Spacing (VS): SRS Priority 7 Load Scheme Enabled Vector Spacing (VS): SRS Priority 7 Load Scheme Enabled Vector Spacing (VS): Save Scheme Save Scheme Configuration Registers DSVCFG2 S1FC02FF4 0x00008751 Default DSVCFG0 S1FC02FFC 0x110FF00B QK	PLL Multiplier	MCU Name P32MX460F512L
USB PLL Input Divider 12x Divider USB PLL Enable Disabled and Bypassed System PLL Output Clock Divider PLL Divide by 1 Oscillator Selection Bits Primary Osc w/PLL (XT+,HS+,EC+PLL) Secondary Oscillator Enable Enabled Thremal/External Switch Over Enabled MT osc mode CLKO Output Signal Active on the OSCO Pin Enabled The output Signal Active on the OSCO Pin Enabled Configuration MT osc mode CLKO Output Signal Active on the OSCO Pin Enabled Configuration MT osc mode CLKO Output Signal Active on the OSCO Pin Enabled Configuration MT osc mode CLKO Output Signal Active on the OSCO Pin Enabled Configuration MT osc mode CLKO Output Signal Active on the OSCO Pin Enabled CONFIGURATION CLKO Output Signal Active on the OSCO Pin Enabled CLKO OUTput Signal Active on the OSCO Pin CLKO OUTput Signal Active OSCO Pin CLKO OUTput Sig	20x Multiplier	
USS PLL Enable Disabled and Bypassed System PLL Output Clock Divider PLL Divide by 1 Oscillator Selection Bits Primary Oscillator Enable Enabled Internal/External Switch Over Enabled Primary Oscillator Configuration XT osc mode QK	USB PLL Input Divider	Uscillator Frequency [MHz] 80.000000
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Disabled and Bypassed • System PLL Output Clock Divider PLL Divide by 1 • Oscillator Selection Bits • Primary Oscillator Enable • Enabled • Primary Oscillator Configuration • XT osc mode • Internal/External Switch Over • Enabled • CLKO Output Signal Active on the OSCO Pin • Enabled • Custor Space (C) • Output Signal Active on the OSCO Pin • Enabled • Output Signal Active on the OSCO Pin • Enabled • Output Signal Active on the OSCO Pin • Enabled • Output Signal Active on the OSCO Pin • Enabled • • • • • • • • • • • • • • • • • • • • •	USB PLL Enable	
System PLL Output Clock Divider PLL Divide by 1 Oscillator Selection Bits Primary Oscillator Enable Enabled Internal/External Switch Over Enabled Primary Oscillator Configuration XT osc mode QLK Output Signal Active on the OSCO Pin Enabled Custo List Internal/External Switch Over Enabled Output Signal Active on the OSCO Pin Enabled Custo List Internal/External Switch Over DEVCFG2 : \$1FC02FF4 : 0x00008751 Default DEVCFG2 : \$1FC02FF6 : 0x110FF00B QK	Disabled and Bypassed	
PIL Divide by 1 V Oscillator Selection Bits Vector Spacing (VS): SRS Priority Level: Primary Osc w/PLL (XT+,HS+,EC+PLL) Vector Spacing (VS): SRS Priority 7 Secondary Oscillator Enable Vector Spacing (VS): SRS Priority 7 Enabled Vector Spacing (VS): SRS Priority 7 Internal/External Switch Over Build Type Heap Enabled Vector Spacing (VS): SRS Priority 7 Primary Oscillator Configuration Vector Spacing (VS): SRS Priority 7 Vir osc mode Vector Spacing (VS): SRS Priority 7 CLKO Output Signal Active on the OSCO Pin Enabled Vector Spacing (VS): Enabled Vector Spacing (VS): SRS Priority 7 Origination Registers DEVCFG2 : \$1FC02FF4 : 0x00008751 Default DEVCFG0 : \$1FC02FF6 : 0x110FF00B QK	System PLL Output Clock Divider	
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Primary Osc w/PLL (XT+,HS+,EC+PLL) • Secondary Oscillator Enable • Enabled • Internal/External Switch Over • Enabled • Primary Oscillator Configuration • XT osc mode • CLKO Output Signal Active on the OSCO Pin • Enabled • Output Signal Active on the OSCO Pin • Enabled •	Oscillator Selection Bits	
Secondary Oscillator Enable	Primary Osc w/PLL (XT+,HS+,EC+PLL)	
Internal/External Switch Over Rabled Primary Oscillator Configuration XT osc mode CLKO Output Signal Active on the OSCO Pin Enabled Enabled	Secondary Oscillator Enable	Load Scheme
Internal/External Switch Over Internal/External Switch Over Enabled Primary Oscillator Configuration XT osc mode CLKO Output Signal Active on the OSCO Pin Enabled Enabled	Enabled	
Primary Oscillator Configuration DEVCFG2 : \$1FC02FF4 : 0x00008751 XT osc mode CLKO Output Signal Active on the OSCO Pin DEVCFG0 : \$1FC02FFC : 0x110FF00B Enabled	Internal/External Switch Over	Size Scheme
KT osc mode Image: Construction of the construction of t	Enabled	Configuration Registers
CLKO Output Signal Active on the OSCO Pin Enabled	Primary Oscillator Configuration	DEVCFG2 :\$1FC02FF4 : 0x00008751 Default
CLKO Output Signal Active on the OSCO Pin Enabled V	XT osc mode	
	CLKO Output Signal Active on the OSCO Pin	
Peripheral Clock Divisor Cancel	Enabled	▼
	Peripheral Clock Divisor	Cancel

) To change your MCU, just select the desired microcontroller from the dropdown list.

- To change your settings enter the oscillator value and adjust configuration register bits using drop-down boxes.
- Several most commonly used settings can be loaded using the provided oscillator "schemes". Load the desired scheme by clicking the **Load Scheme** button.
- Select whether to build a Debug HEX, which is necessary for hardware debugging, or a final Release HEX.

Figure 6-1: Edit Project Window

7. What's next?

More examples

mikroPascal PRO for PIC32[®] comes with **80 examples** which demonstrate a variety of features. They represent the best starting point when developing a new project. You will find projects written for mikroElektronika development boards, additional boards, internal MCU modules and other examples. This way **you always have a starting point**, and don't have to start from scratch. In most cases, you can combine different simple projects to create a more complex one. For example, if you want to build a temperature datalogger, you can combine temperature sensor example with MMC/SD example and do the job in much less time. All projects are delivered with a working .HEX files, so you don't have to buy a compiler license in order to test them. You can load them into your development board right away without the need for building them.

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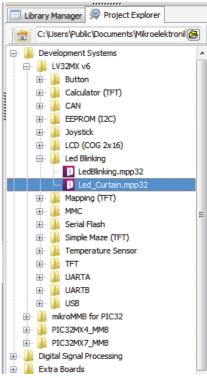


Figure 7-1: Project explorer window enables you to easily access provided examples and load them quickly

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