

mikroBoard for ARM 144-pin™

User manual

All MikroElektronika's development systems represent irreplaceable tools for programming and developing microcontroller-based devices. Carefully chosen components and the use of machines of the last generation for mounting and testing thereof are the best guarantee of high reliability of our devices. Due to simple design, a large number of add-on modules and ready to use examples, all our users, regardless of their experience, have the possibility to develop their project in a fast and efficient way.

Development system



SOFTWARE AND HARDWARE SOLUTIONS FOR EMBEDDED WORLD ...making it simple

TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in Mikroelektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

A handwritten signature in white ink, appearing to read 'N. Matic', is positioned above the name and title.

Nebojsa Matic
General Manager

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1. General information

MikroBoard for ARM 144-pin is primarily intended to be connected to the EasyARM v6 development system but can also be used as a stand-alone device. The board features the LPC2214 microcontroller, flash module, USB connector, microSD connector, JTAG connector, USB UART, voltage regulator and connectors that enable connection with the development system.

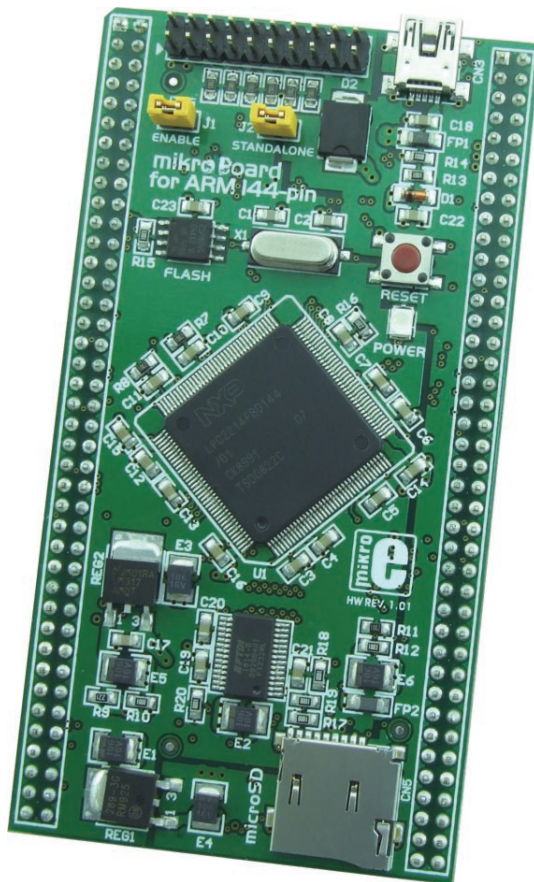


Figure 1-1: mikroBoard for ARM 144-pin

2. LPC2214 microcontroller

The LPC2214 microcontroller in 144-pin LQFP package is soldered on the mikroBoard for ARM 144-pin. Some of its key features are:

- 16/32-bit ARM7TDMI-S microcontroller in a LQFP144 package
- 16 kB on-chip static RAM and 256 kB on-chip flash program memory. 128-bit wide interface/accelerator enables high speed 60 MHz operation.
- In-System Programming (ISP) and In-Application Programming (IAP) via on-chip bootloader software.

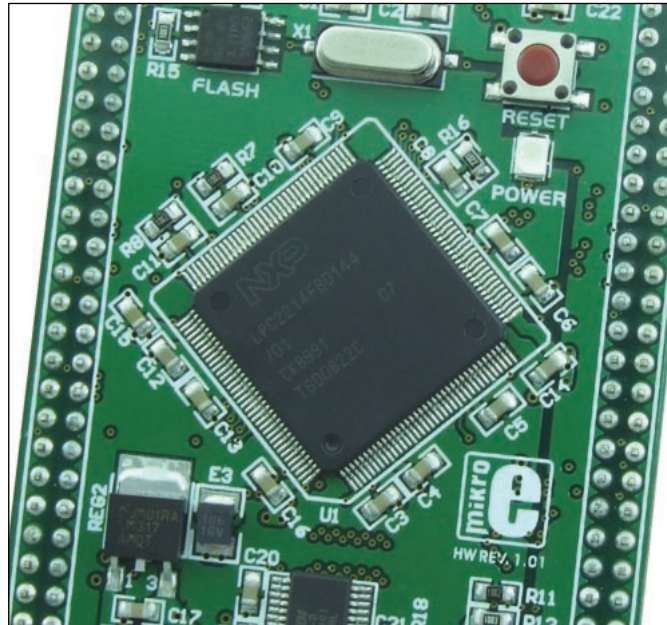


Figure 2-1: LPC2214 microcontroller

LPC2214 is connected to on board modules via pins which are also connected to CN1 and CN2 connectors. These two connectors enable the board to be connected to the EasyARM v6 development system or some other device.



Figure 2-2: LPC2214 microcontroller with oscillators connection schematic

The LPC2214 microcontroller is connected to the X1 oscillator. The X1 oscillator generates a clock used for the operation of the microcontroller. The microcontroller can be cleared by feeding the reset pin with a logic 0, i.e. by pressing the RESET button.



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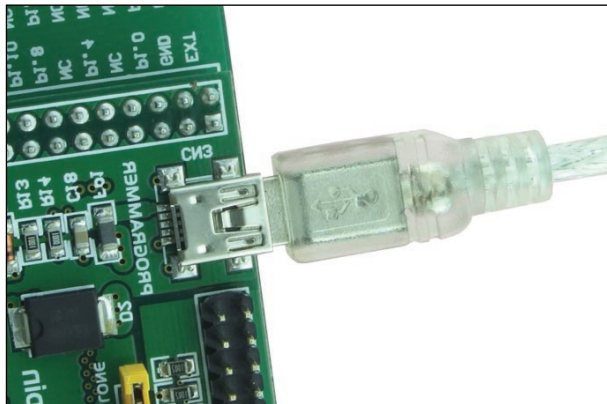
Figure 3-1: USB connector for programming

Figure 3-2: USB UART module connection schematic

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In next few steps is explained how to program microcontroller with bootloader via Flash Magic application.

STEP 1: Connect the system to a PC



Connect the mikroBoard for ARM 144-pin to available USB port on your PC.

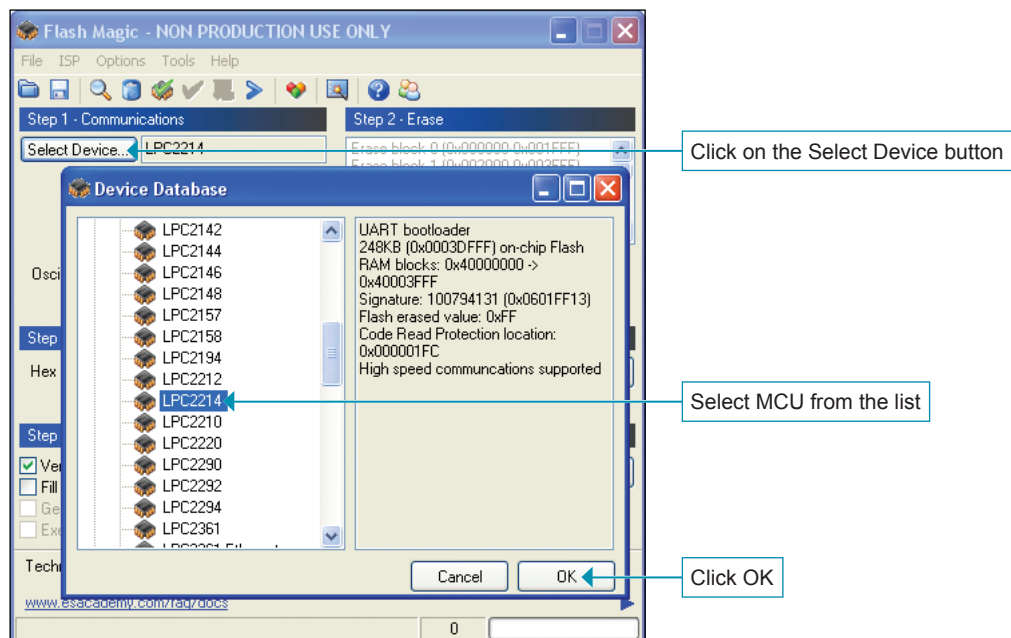
STEP 2: Start Flash Magic

Download the Flash Magic application from <http://www.flashmagictool.com/download.html&d=FlashMagic.exe> and install it on your PC

When the installation is finished double click on the Flash Magic icon



STEP 3: Select MCU



STEP 4: Settings

The screenshot shows the mikroC IDE configuration window with two tabs: "Step 1 - Communications" and "Step 2 - Erase".

Step 1 - Communications:

- Select Device...: LPC2214
- COM Port: COM 5
- Baud Rate: 230400
- Interface: None (ISP)
- Oscillator (MHz): 14.74568

Step 2 - Erase:

- Erase block 0 (0x000000-0x001FFF)
- Erase block 1 (0x002000-0x003FFF)
- Erase block 2 (0x004000-0x005FFF)
- Erase block 3 (0x006000-0x007FFF)
- Erase block 4 (0x008000-0x009FFF)
- Erase block 5 (0x00A000-0x00BFFF)
- ☒ Erase all Flash+Code Rd Prot
- ☐ Erase blocks used by Hex file

Annotations:

- From drop-down menu select the COM port on your PC
- Set Baud Rate to 230400
- Enter 14.74568 (if you use different oscillator set the appropriate value in MHz)

Device Manager on your PC contains information on which COM port is used for USB communication with the mikroBoard for ARM 144-pin development system. In this case the COM5 port is used.

The screenshot shows the Windows Device Manager and the USB Serial Port (COM5) Properties dialog.

Device Manager:

- Ports (COM & LPT)
 - Communications Port (COM1)
 - Printer Port (LPT1)
 - USB Serial Port (COM5)
- Processors
- Sound, video and game controllers
- System devices
- Universal Serial Bus controllers

Annotations:

- From pop-up window select the Port Settings tab
- Right click on USB port, then on Properties
- Click on the Advanced... button

USB Serial Port (COM5) Properties:

- General tab: Bits per second: 9600, Data bits: 8, Parity: None, Stop bits: 1, Flow control: None
- Port Settings tab: Advanced... button

The screenshot shows the Advanced Settings for COM5 dialog.

COM Port Number: COM5

USB Transfer Sizes:

- Receive (Bytes): 4096
- Transmit (Bytes): 4096

BM Options:

- Latency Timer (msec): 16

Timeouts:

- Minimum Read Timeout (msec): 0
- Minimum Write Timeout (msec): 0

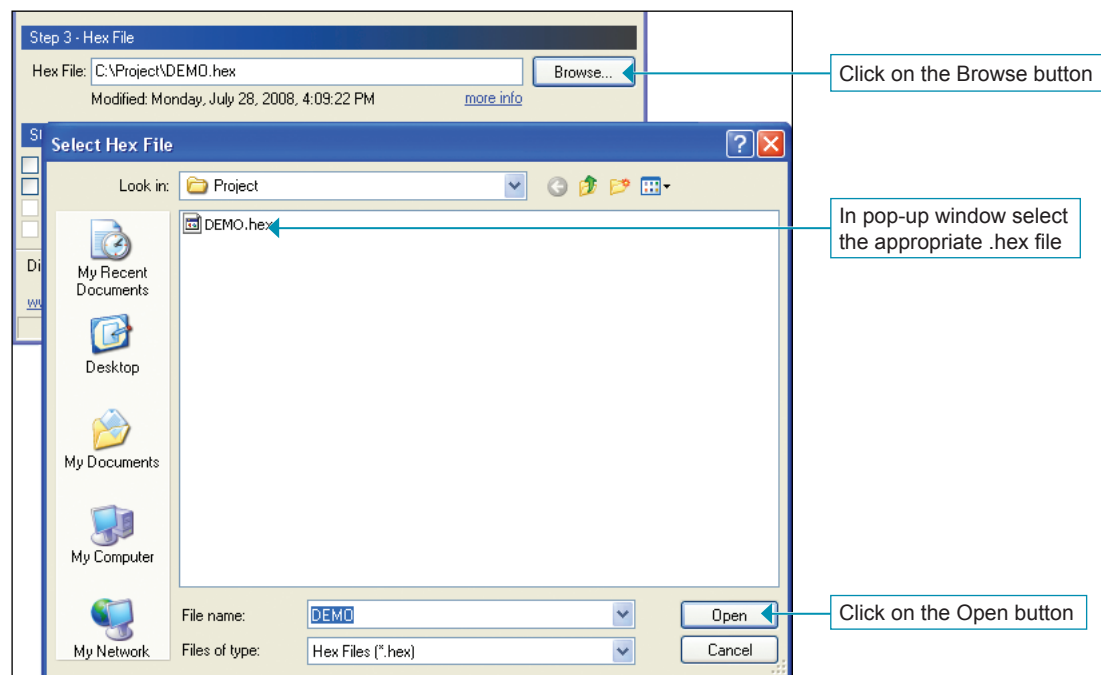
Miscellaneous Options:

- ☐ Serial Enumerator
- ☐ Serial Printer
- ☐ Cancel If Power Off
- ☐ Event On Surprise Removal
- ☐ Set RTS On Close
- ☐ Disable Modem Ctrl At Startup

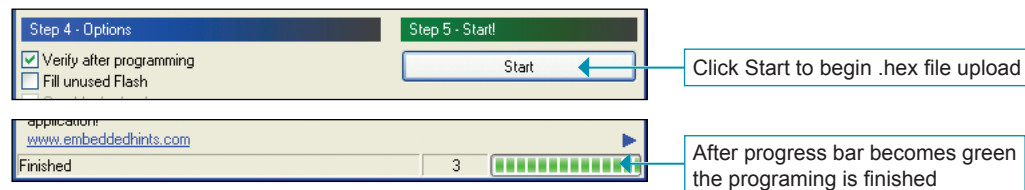
Annotations:

- In pop-up window uncheck the Serial Enumeration option and click OK

STEP 5: Browse for .hex file



STEP 6: Upload .hex file



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4. Voltage regulator

The microcontroller require dual power supply: 1.8V for CPU and 3.3V for I/O. The board is powered with the 5V power supply voltage via the CN3 USB connector supplied on the board.

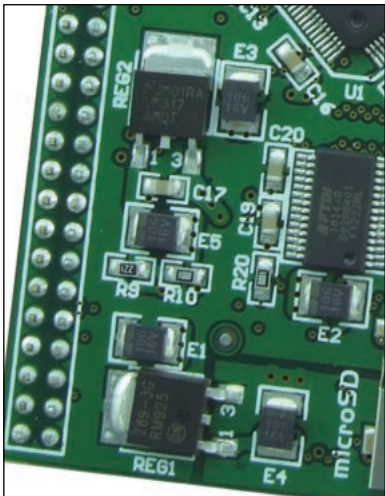


Figure 4-1: Voltage regulator

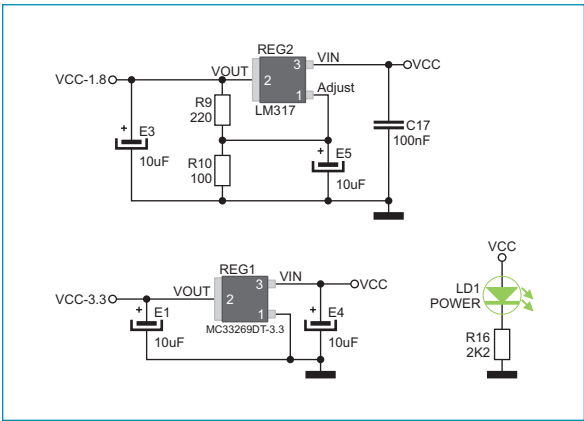


Figure 4-2: Voltage regulator connection schematic

If the board is powered by the development system (EasyARM v6), the function of the voltage regulator remains the same. In this case, it is necessary to remove jumper J2 (STANDALONE), Figure 4-3.

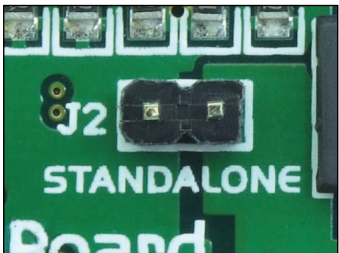


Figure 4-3: Standalone mode disabled

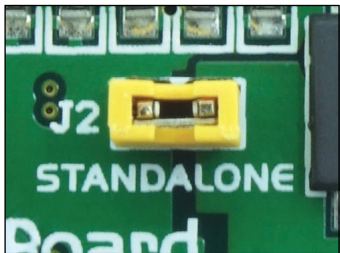


Figure 4-4: Standalone mode enabled

5. MicroSD connector

There is a connector CN5 provided on the board that enables the use of microSD card. When inserted, the microSD card provides additional memory space that the microcontroller can use to store data. Communication between the microSD card and the microcontroller is performed via the Serial Peripheral Interface (SPI).

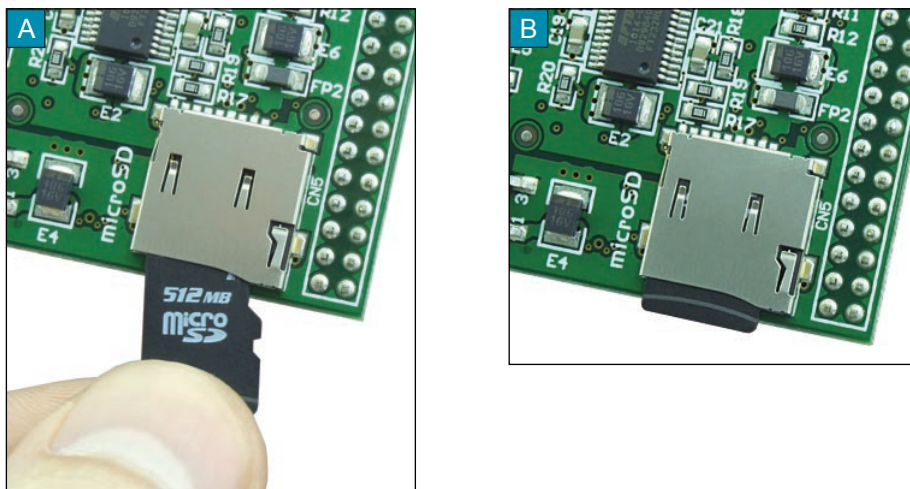


Figure 5-1: MicroSD connector

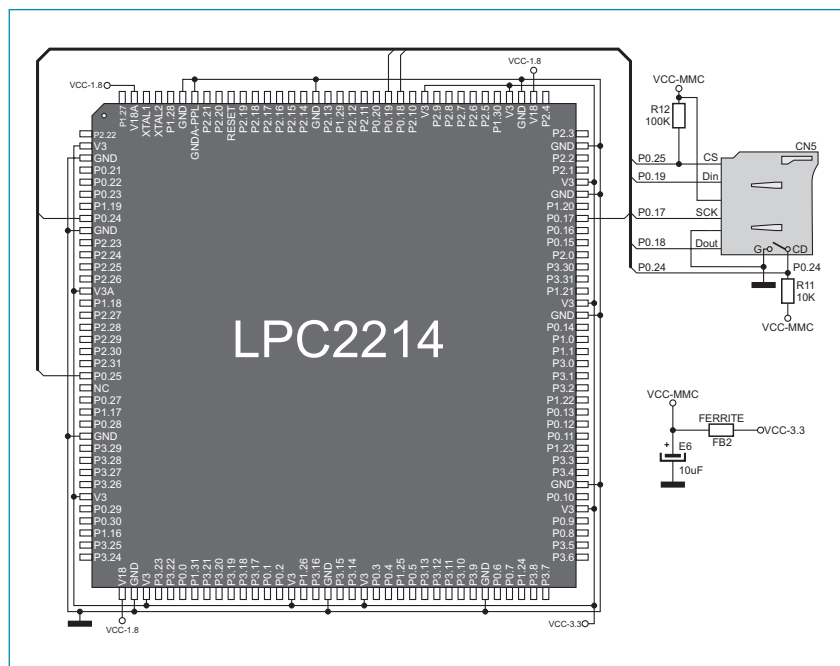


Figure 5-2: microSD connector connection schematic

The pins' designations have the following meaning:

- CS - Chip Select
- Din - Master Out/Slave In (MOSI)
- SCK - Clock
- Dout - Master In/Slave Out (MISO)

6. Flash module

Flash module provides additional 8Mbit of flash memory that the microcontroller can use via the Serial Peripheral Interface (SPI).



Figure 6-1: Flash memory

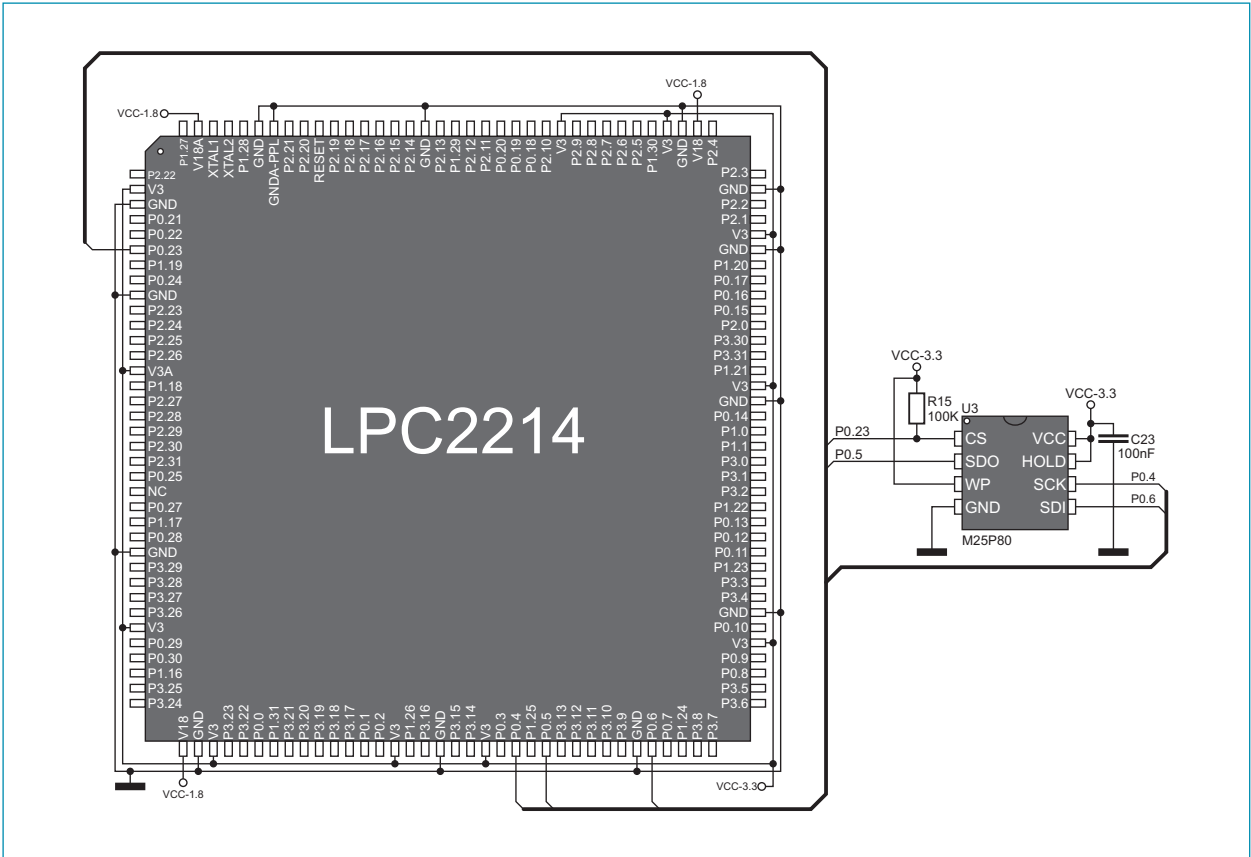


Figure 6-2: Flash module connection schematic

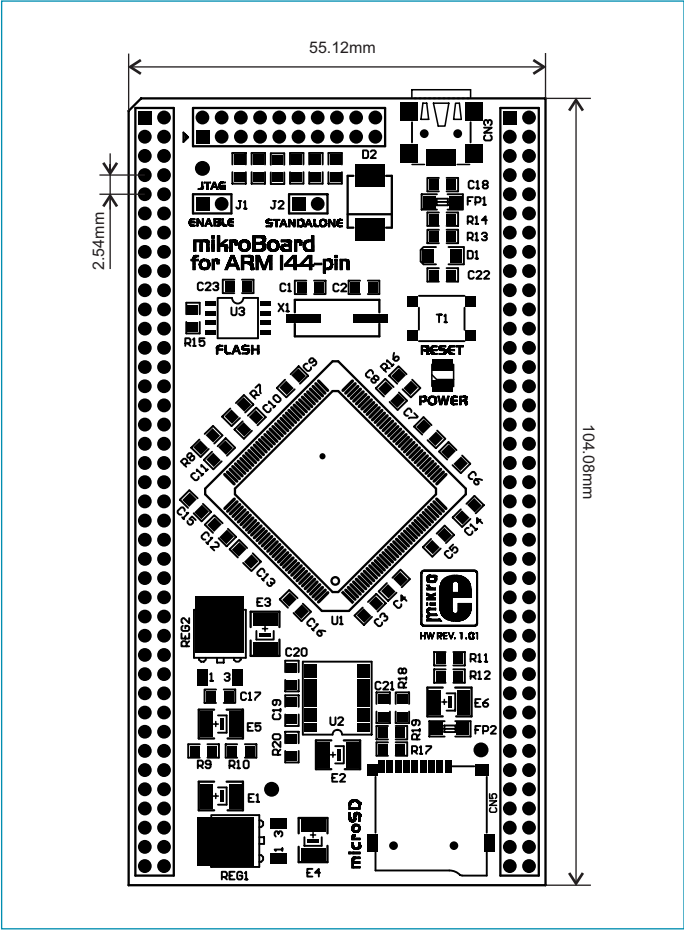


Figure 6-3: Dimensions of the mikroBoard for ARM 144-pin

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