

# Power Step 2 Click



PID: MIKROE-6524

**Power Step 2 Click** is a compact add-on board for precise motion control applications. It is based on the [powerSTEP01](#), a powerful 1/128 microstepping controller from [STMicroelectronics](#), that integrates eight N-channel MOSFETs with ultra-low RDS(on). This board operates at voltages up to 85V, delivering up to 10A RMS output current while supporting both voltage mode driving and advanced current control. It features a high-speed 5MHz SPI interface, multiple safety protections, and additional control pins for enhanced functionality, including step clock input and motor initialization. The board also provides LED indicators for quick status monitoring and supports external clock synchronization. With its robust design and precise microstepping capabilities, Power Step 2 Click is ideal for industrial automation, medical equipment, robotics, antenna positioning, CCTV and security systems, and dome cameras.

For more information about **Power Step 2 Click** visit the official [product page](#).

## How does it work?

Power Step 2 Click is based on the powerSTEP01, an a power 1/128 microstepping controller from STMicroelectronics. This system-in-package solution integrates eight N-channel MOSFETs with an ultra-low RDS(on) of just 16mΩ, enabling precise control of stepper motors operating at voltages up to 85V while delivering a maximum output current of 10A RMS. The board is designed to offer full digital motion control, using an SPI-programmable interface for speed profile generation and accurate positioning. With its powerful combination of high voltage handling, precise microstepping control, and an extensive safety feature set, the Power Step 2 Click is an ideal solution for applications requiring precise motor control, including industrial process automation, medical analysis equipment, robotics, antenna positioning, CCTV and security systems, and dome camera mechanisms.

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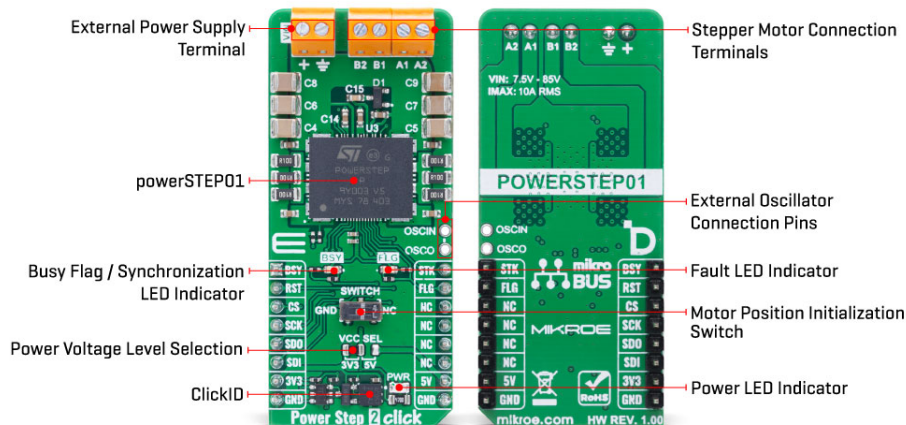
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At the core of the powerSTEP01 is its capability to support both voltage mode driving and advanced current control, making it adaptable to a variety of motor control applications. With its embedded dual full-bridge configuration and non-dissipative overcurrent protection, it ensures reliability even in demanding environments. The digital control engine allows users to define custom motion profiles, including acceleration, deceleration, speed, and target positioning, all of which can be conveniently programmed through a dedicated register set via the high-speed 5MHz SPI interface. Safety and robustness are key aspects of the powerSTEP01 architecture. It includes a comprehensive set of protection features such as thermal shutdown, low bus voltage detection, overcurrent protection, and motor stall detection, ensuring uninterrupted and secure operation under all conditions.

In addition to the SPI interface pins, Power Step 2 Click uses several additional control pins for enhanced functionality. The RST pin serves as both a standby and reset control, where pulling it to a LOW logic level places the device in standby mode and resets its logic. The STK pin acts as the step clock input, allowing precise motor motion control in step-clock mode. Each rising edge of the step-clock signal applied to this pin advances the motor by one microstep in the programmed direction while simultaneously updating the absolute position. Furthermore, the board features a SWITCH, which plays a crucial role in motor initialization. Since the initial position of the stepper motor is often undefined at power-up, an initialization sequence is required to move it to a known position. The GoUntil and ReleaseSW commands, in conjunction with this switch, makes a straightforward method for setting the motor's reference position.

This Click board™ also includes two important status pins for monitoring device operation. The FLG pin serves as a status flag output whenever a programmed alarm condition is triggered. These conditions may include step loss, overcurrent detection (OCD), thermal pre-warning or shutdown, undervoltage lockout (UVLO), invalid commands, or non-performable commands. The BSY pin, on the other hand, is primarily used to indicate when the device is actively executing a command by default. However, it can also be configured to generate a synchronization signal if required. Both of these signals are accompanied by dedicated LED indicators - a red LED for FLG and a yellow LED for BSY - providing clear visual feedback for quick status monitoring and troubleshooting.

The Power Step 2 Click also includes two unpopulated pins, OSCIN and OSCO, which allow for the connection of an external oscillator or clock source. When an external clock is not used, the internal oscillator provides a configurable clock signal through the OSCO pin, which can output frequencies of 2MHz, 4MHz, 8MHz, or 16MHz, depending on the selected settings. This flexibility enables users to synchronize the motor driver with other system components or

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optimize performance based on specific application requirements.


This Click board™ can operate with either 3.3V or 5V logic voltage levels selected via the VCC SEL jumper. This way, both 3.3V and 5V capable MCUs can use the communication lines properly. Also, this Click board™ comes equipped with a library containing easy-to-use functions and an example code that can be used as a reference for further development.

## Specifications

Type	Stepper
Applications	Ideal for industrial automation, medical equipment, robotics, antenna positioning, CCTV and security systems, and dome cameras
On-board modules	powerSTEP01 - power 1/128 microstepping controller from STMicroelectronics
Key Features	Stepper motor driver with 1/128 microstepping resolution, integrated eight N-channel MOSFETs with ultra-low RDS(on), supports both voltage mode driving and advanced current control, SPI-programmable interface, dual full-bridge architecture with non-dissipative overcurrent protection, safety features, additional control pins for step clock input, standby/reset, and motor initialization, and more
Interface	SPI
Feature	ClickID
Compatibility	mikroBUS™
Click board size	L (57.15 x 25.4 mm)
Input Voltage	3.3V or 5V, External

## Pinout diagram

This table shows how the pinout on Power Step 2 Click corresponds to the pinout on the mikroBUS™ socket (the latter shown in the two middle columns).

Notes	Pin					Pin	Notes
Busy Status / Synchronization	<b>BSY</b>	1	AN	PWM	16	<b>STK</b>	Step-Clock Signal
Reset / ID SEL	<b>RST</b>	2	RST	INT	15	<b>FLG</b>	Fault Indicator
SPI Select / ID COMM	<b>CS</b>	3	CS	RX	14	NC	
SPI Clock	<b>SCK</b>	4	SCK	TX	13	NC	
SPI Data OUT	<b>SDO</b>	5	MISO	SCL	12	NC	
SPI Data IN	<b>SDI</b>	6	MOSI	SDA	11	NC	
Power Supply	<b>3.3V</b>	7	3.3V	5V	10	<b>5V</b>	Power Supply
Ground	<b>GND</b>	8	GND	GND	9	<b>GND</b>	Ground

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## Onboard settings and indicators

Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator
LD2	FLG	-	Fault LED Indicator
LD3	BSY	-	Busy Flag / Synchronization LED Indicator
JP1	VCC SEL	Left	Power Voltage Level Selection 3V3/5V: Left position 3V3, Right position 5V
SW1	SWITCH	Left	Motor Position Initialization Switch

## Power Step 2 Click electrical specifications

Description	Min	Typ	Max	Unit
Supply Voltage	3.3	-	5	V
External Power Supply	7.5	-	85	V
Output Current (RMS)	-	-	10	A

## Software Support

[Power Step 2 Click](#) demo application is developed using the [NECTO Studio](#), ensuring compatibility with [mikroSDK](#)'s open-source libraries and tools. Designed for plug-and-play implementation and testing, the demo is fully compatible with all development, starter, and mikromedia boards featuring a [mikroBUS™](#) socket.

## Example Description

This example demonstrates the use of the Power Step 2 Click board for precise control of stepper motors. The application showcases various step modes, directions, and speeds while demonstrating the board's ability to control motors using different operation modes.

### Key Functions

- powerstep2\_cfg\_setup Config Object Initialization function.
- powerstep2\_init Initialization function.
- powerstep2\_default\_cfg Click Default Configuration function.
- powerstep2\_set\_step\_mode This function sets the step mode (microstepping level) of the Power Step 2 device.
- powerstep2\_set\_speed This function sets the minimum and maximum speeds for motor movement.
- powerstep2\_move This function moves the motor a specified number of steps in a given direction.

### Application Init

Initializes the logger and configures the Power Step 2 Click board. The default settings are applied to prepare the device for motor control operations.

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## Application Task

Demonstrates motor control with various configurations. The example alternates between multiple step modes (1/8, 1/16, 1/32, 1/4), directions (CW, CCW), speeds, and control modes (voltage, current). Each configuration is applied sequentially, with the motor driven through specified steps before switching to the next configuration.

## Application Output

This Click board can be interfaced and monitored in two ways:

- Application Output - Use the "Application Output" window in Debug mode for real-time data monitoring. Set it up properly by following [this tutorial](#).
- UART Terminal - Monitor data via the UART Terminal using a [USB to UART converter](#). For detailed instructions, check out [this tutorial](#).

## Additional Notes and Information

The complete application code and a ready-to-use project are available through the NECTO Studio Package Manager for direct installation in the [NECTO Studio](#). The application code can also be found on the MIKROE [GitHub](#) account.

## Resources

[mikroBUS™](#)

[mikroSDK](#)

[Click board™ Catalog](#)

[Click boards™](#)

[ClickID](#)

## Downloads

[Power Step 2 click example package](#)

[Power Step 2 click 2D and 3D files v100](#)

[Power Step 2 click schematic v100](#)

[powerSTEP01 datasheet](#)

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