Features

- Fast read access time 45ns
- Low-power CMOS operation
 - 100µA max standby
 - 25mA max active at 5MHz
- JEDEC standard packages
 - 32-lead PDIP
 - 32-lead PLCC
- 5V ± 10% supply
- High-reliability CMOS technology
 - 2000V ESD protection
 - 200mA latchup immunity
- Rapid programming algorithm 100 µs/byte (typical)
- CMOS- and TTL-compatible inputs and outputs
- Integrated product identification code
- Industrial temperature range
- Green (Pb/halide-free) packaging option

1. Description

The Atmel[®] AT27C010 is a low-power, high-performance 1,048,576-bit, one-time programmable, read-only memory (OTP EPROM) organized as 128K by 8 bits. Thedevice requires only one 5V power supply in normal read mode operation. Any byte can be accessed in less than 45ns, eliminating the need for speed reducing WAIT states on highperformance microprocessor systems.

In read mode, the AT27C010 typically consumes only 8mA. Standby mode supply current is typically less than $10\mu A.$

The AT27C010 is available in a choice of industry standard, JEDEC approved, one-time programmable (OTP) PDIP and PLCC packages. All devices feature two-line control (\overline{CE} , \overline{OE}) to give designers the flexibility to prevent bus contention.

With 128K byte storage capability, the AT27C010 allows firmware to be stored reliably and to be accessed by the system without the delays of mass storage media.

The AT27C010 has additional features to ensure high quality and efficient production use. The rapid programming algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100 µs/byte. The integrated product identification code electronically identifies the device and manufacturer. This feature is used by industry standard programming equipment to select the proper programming algorithms and voltages.



1Mb (128K x 8) One-time Programmable, Read-only Memory

Atmel AT27C010

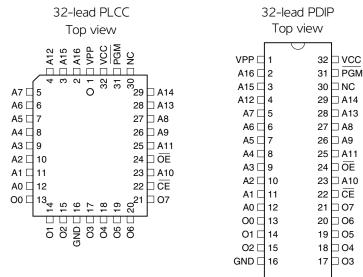






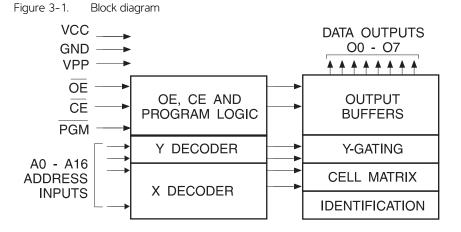
2. Pin configurations

| Pin name | Function |
|----------|----------------|
| A0 - A16 | Addresses |
| 00 - 07 | Outputs |
| CE | Chip enable |
| ŌĒ | Output enable |
| PGM | Program strobe |
| NC | No connect |



3. System considerations

Switching between active and standby conditions via the chip enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device nonconformance. At a minimum, a 0.1μ F, high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V_{CC} and ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7μ F bulk electrolytic capacitor should be utilized, again connected between the V_{CC} and ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.



4. Absolute maximum ratings*

| Temperature under bias55°C to +125°C |
|---|
| Storage temperature65°C to +150°C |
| Voltage on any pin with respect to ground2.0V to +7.0V ⁽¹⁾ |
| Voltage on A9 with respect to ground2.0V to +14.0V ⁽¹⁾ |
| V _{PP} supply voltage with respect to ground2.0V to +14.0V ⁽¹⁾ |
| Noto: 1 Minimum voltago is 0.6V/DC which may under |

*NOTICE: Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20ns. Maximum output pin voltage is V_{CC} + 0.75V DC, which may overshoot to +7.0V for pulses of less than 20ns.

5. DC and AC characteristics

| Table 5-1. | Operating modes |
|------------|-----------------|
| | |

| Mode/Pin | CE | ŌĒ | PGM | Ai | V _{PP} | Outputs |
|---------------------------------------|-----------------|-----------------|------------------|--|-----------------|---------------------|
| Read | V _{IL} | V _{IL} | X ⁽¹⁾ | Ai | Х | D _{OUT} |
| Output disable | Х | V _{IH} | Х | Х | Х | High Z |
| Standby | V _{IH} | Х | Х | Х | Х | High Z |
| Rapid program ⁽²⁾ | V _{IL} | V _{IH} | V _{IL} | Ai | V _{PP} | D _{IN} |
| PGM verify | V _{IL} | V _{IL} | V _{IH} | Ai | V _{PP} | D _{OUT} |
| PGM inhibit | V _{IH} | Х | Х | Х | V _{PP} | High Z |
| Product identification ⁽⁴⁾ | V _{IL} | V _{IL} | х | $A9 = V_{H}^{(3)}$ $A0 = V_{H} \text{ or } V_{L}$ $A1 - A16 = V_{L}$ | Х | Identification code |

Note: 1. X can be V_{IL} or V_{IH} .

2. Refer to programming characteristics.

3. $V_{\rm H} = 12.0 \pm 0.5 V.$

4. Two identifier bytes may be selected. All Ai inputs are held low (V_{IL}) , except A9, which is set to $V_{H'}$ and A0, which is toggled low (V_{IL}) to select the manufacturer's identification byte and high (V_{IL}) to select the device code byte.

Table 5-2. DC and AC operating conditions for read operation

| | | Atmel AT27C010 | | |
|------------------------------|------|----------------|--------------|--|
| | | -45 | -70 | |
| Operating temp. (case) | Ind. | -40°C - 85°C | -40°C - 85°C | |
| V _{CC} power supply | | 5V ± 10% | 5V ± 10% | |





| Symbol | Parameter | Condition | Condition | | Max | Units |
|---------------------|--|---|---|-----|-----------------------|-------|
| I _U | Input load current | $V_{IN} = 0V$ to V_{CC} | Ind. | | ± 1 | μA |
| I _{LO} | Output leakage current | $V_{OUT} = 0V \text{ to } V_{CC}$ | Ind. | | ± 5 | μA |
| IPP1 ⁽²⁾ | V _{PP} ⁽¹⁾⁾ read/standby current | $V_{PP} = V_{CC}$ | V _{PP} = V _{CC} | | 10 | μΑ |
| 1 | | I_{SB1} (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$ | | | 100 | μA |
| I _{SB} | V _{CC} ^{CC} standby current | $V_{CC}^{(1)}$ standby current $I_{SB2}^{(TTL)}$, $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$ | | | 1 | mA |
| I _{CC} | V _{CC} active current | f = 5MHz, I_{OUT} = 0mA, \overline{CE} = V_{IL} | $f = 5MHz$, $I_{OUT} = 0mA$, $\overline{CE} = V_{IL}$ | | 25 | mA |
| V _{IL} | Input low voltage | | | | 0.8 | V |
| V _{IH} | Input high voltage | | | 2.0 | V _{CC} + 0.5 | V |
| V _{OL} | Output low voltage | I _{OL} = 2.1mA | | | 0.4 | V |
| V _{OH} | Output high voltage | I _{OH} = -400μA | | 2.4 | | V |

Table 5-3. DC and operating characteristics for read operation

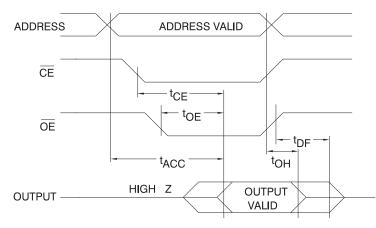
Notes: 1. V_{CC} must be applied simultaneously or before V_{PP} , and removed simultaneously or after V_{PP} .

2. V_{PP} may be connected directly to $V_{CC'}$ except during programming. The supply current would then be the sum of I_{CC} and I_{PP} .

| | | | | Atmel A | F27C010 | | |
|-----------------------------------|---|--|-----|---------|---------|-----|-------|
| | | | - | 45 | - | 70 | |
| Symbol | Parameter | Condition | Min | Max | Min | Max | Units |
| t _{ACC} ⁽³⁾ | Address to output delay | $\overline{CE} = \overline{OE} = V_{IL}$ | | 45 | | 70 | ns |
| t _{CE} ⁽²⁾ | CE to output delay | $\overline{OE} = V_{IL}$ | | 45 | | 70 | ns |
| t _{OE} ⁽²⁾⁽³⁾ | OE to output delay | $\overline{CE} = V_{IL}$ | | 20 | | 30 | ns |
| t _{DF} ⁽⁴⁾⁽⁵⁾ | $\overline{\text{OE}}$ or $\overline{\text{CE}}$ high to output float, which | ever occurred first | | 20 | | 25 | ns |
| t _{OH} | Output hold from address, \overline{CE} or \overline{OE} , whichever occurred first | | 7 | | 7 | | ns |

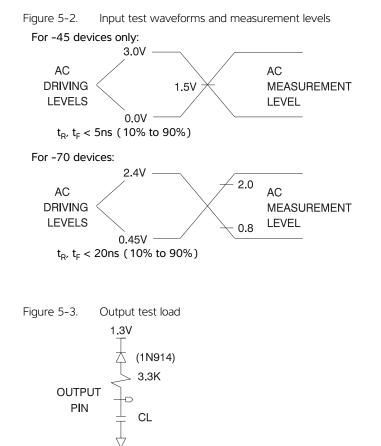
Table 5-4. AC characteristics for read operation

Figure 5-1. AC waveforms for read operation⁽¹⁾



- Notes: 1. Timing measurement reference level is 1.5V for -45 devices. Input AC drive levels are $V_{IL} = 0.0V$ and $V_{IH} = 3.0V$. Timing measurement reference levels for all other speed grades are $V_{OL} = 0.8V$ and $V_{OH} = 2.0V$. Input AC drive levels are $V_{IL} = 0.45V$ and $V_{IH} = 2.4V$.
 - 2. $\overline{\text{OE}}$ may be delayed up to t_{CE} t_{OE} after the falling edge of $\overline{\text{CE}}$ without impact on t_{CE} .
 - 3. $\overline{\text{OE}}$ may be delayed up to t_{ACC} t_{OE} after the address is valid without impact on t_{ACC} .
 - 4. This parameter is only sampled, and is not 100% tested.
 - 5. Output float is defined as the point when data is no longer driven.

4 Atmel AT27C010



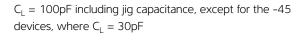


Table 5-5. Pin capacitance f = 1MHz, $T = 25^{\circ}C^{(1)}$

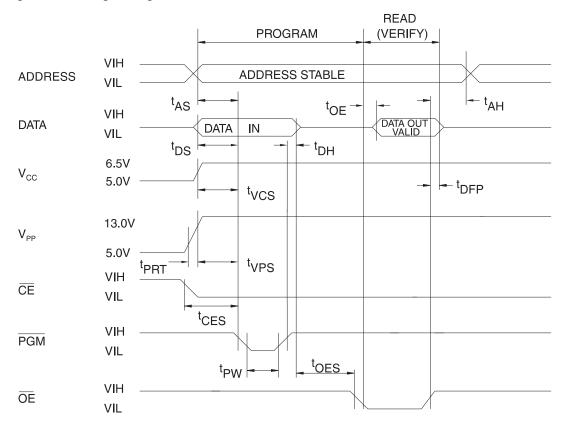
| Symbol | Тур | Мах | Units | Conditions |
|------------------|-----|-----|-------|-----------------------|
| C _{IN} | 4 | 8 | pF | $V_{IN} = 0V$ |
| C _{OUT} | 8 | 12 | pF | V _{OUT} = 0V |

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled, and is not 100% tested.





Figure 5-4. Programming Waveforms⁽¹⁾



Notes: 1. The input timing reference is 0.8V for $V_{\rm IL}$ and 2.0V for $V_{\rm IH}$

- 2. $t_{\mbox{\scriptsize OE}}$ and $t_{\mbox{\scriptsize DFP}}$ are characteristics of the device, but must be accommodated by the programmer.
- 3. When programming the Atmel AT27C010, a 0.1 μ F capacitor is required across V_{pp} and ground to suppress spurious voltage transients.

Table 5-6. DC programming characteristics $T_{A} = 25 \pm 5^{\circ}\text{C}, \, V_{CC} = 6.5 \pm 0.25 \text{V}, \, V_{PP} = 13.0 \pm 0.25 \text{V}$

| | | | Limits | | |
|------------------|---|---|--------|---------------------|-------|
| Symbol | Parameter | Test conditions | Min | Max | Units |
| ILI | Input load current | $V_{IN} = V_{IL'} V_{IH}$ | | ±10 | μA |
| V _{IL} | Input low level | | -0.6 | 0.8 | V |
| $V_{\rm IH}$ | Input high level | | 2.0 | V _{CC} + 1 | V |
| V _{OL} | Output low voltage | I _{OL} = 2.1mA | | 0.4 | V |
| V _{OH} | Output high voltage | I _{OH} = -400μA | 2.4 | | V |
| I _{CC2} | V _{CC} supply current (program and verify) | | | 40 | mA |
| I _{PP2} | V _{PP} supply current | $\overline{CE} = \overline{PGM} = V_{IL}$ | | 20 | mA |
| V _{ID} | A9 product identification voltage | | 11.5 | 12.5 | V |

Table 5-7. AC programming characteristics

| | | | Lin | nits | |
|------------------|--|--|-----|------|-------|
| Symbol | Parameter | Test conditions ⁽¹⁾ | Min | Max | Units |
| t _{AS} | Address setup time | | 2 | | μs |
| t _{CES} | CE setup time | | 2 | | μs |
| t _{OES} | OE setup time | Input rise and fall times | 2 | | μs |
| t _{DS} | Data setup time | (10% to 90%) 20ns Input pulse levels 0.45V to 2.4V Input timing reference level 0.8V to 2.0V | 2 | | μs |
| t _{AH} | Address hold time | | 0 | | μs |
| t _{DH} | Data hold time | | 2 | | μs |
| t _{DFP} | $\overline{\text{OE}}$ high to output float delay ⁽²⁾ | | 0 | 130 | ns |
| t _{VPS} | V _{PP} setup time | | 2 | | μs |
| t _{VCS} | V _{CC} setup time | | 2 | | μs |
| t _{PW} | PGM program pulse width ⁽³⁾ | Output timing reference level 0.8V to 2.0V | 95 | 105 | μs |
| t _{OE} | Data valid from OE | | | 150 | ns |
| t _{PRT} | V _{PP} pulse rise time during programming | | 50 | | ns |

Notes: 1. V_{CC} must be applied simultaneously with or before V_{PP} and removed simultaneously with or after V_{PP} .

2. This parameter is only sampled, and is not 100% tested. Output float is defined as the point where data is no longer driven. See timing diagram.

3. Program pulse width tolerance is $100\mu \text{sec} \pm 5\%$.

| Table 5-8. | The Atmel AT27C010 integrated product identification code |
|------------|---|
|------------|---|

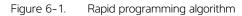
| | | Pins | | | | | Hex | | | |
|--------------|----|------|----|----|----|----|-----|----|----|------|
| Codes | A0 | 07 | O6 | 05 | 04 | O3 | 02 | 01 | 00 | data |
| Manufacturer | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 1E |
| Device type | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 05 |

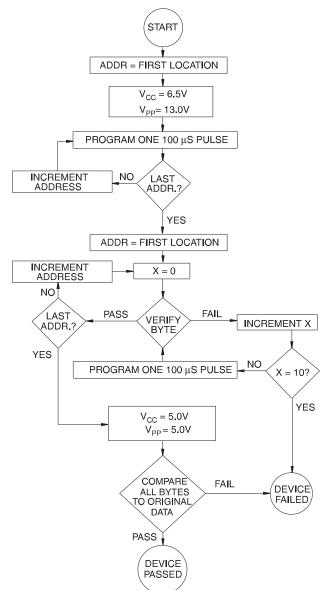


| MEL |
|------------|
| |

6. Rapid programming algorithm

A 100µs \overrightarrow{PGM} pulse width is used to program. The address is set to the first location. V_{CC} is raised to 6.5V and V_{PP} is raised to 13.0V. Each address is first programmed with one 100µs \overrightarrow{PGM} pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive 100µs pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked. V_{PP} is then lowered to 5.0V and V_{CC} to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.





7. Ordering information

| t _{ACC} | I _{CC} (mA) | | | | | |
|------------------|----------------------|---------|--------------------------------|-------------|------------------------|-------------------------------|
| (ns) | Active | Standby | Atmel ordering code | Package | Lead finish | Operation range |
| 45 | 25 | 0.1 | AT27C010-45JU | 32J | Matte tin | Industrial (-40°C to 85°C) |
| 70 | 25 | 0.1 | AT27C010-70JU AT27C010-70PU | 32J 32P6 | Matte tin Matte tin | Industrial (-40°C to 85°C) |

Green package option (Pb/halide-free)

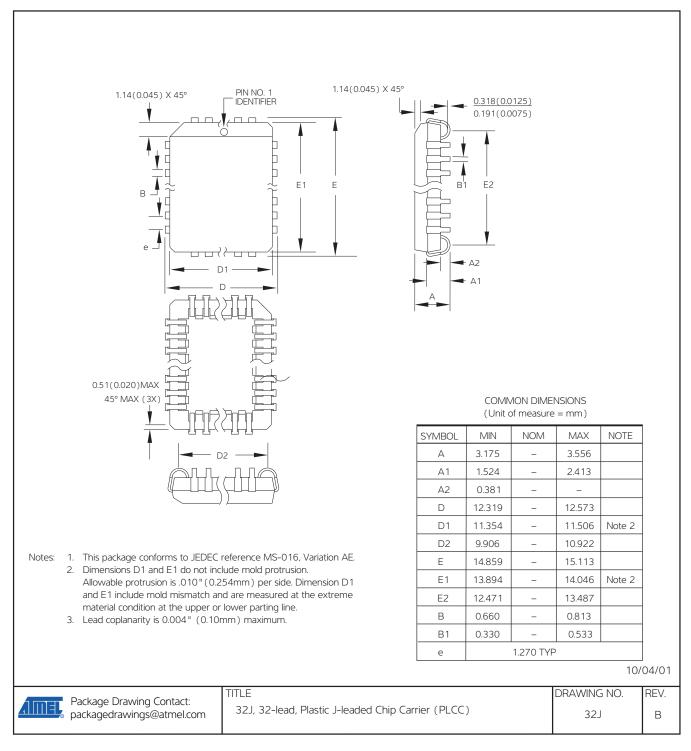
| Package type | | | | | |
|--------------|---|--|--|--|--|
| 32J | 32-lead, plastic, J-leaded chip carrier (PLCC) | | | | |
| 32P6 | 32-lead, 0.600" wide, plastic, dual inline package (PDIP) | | | | |



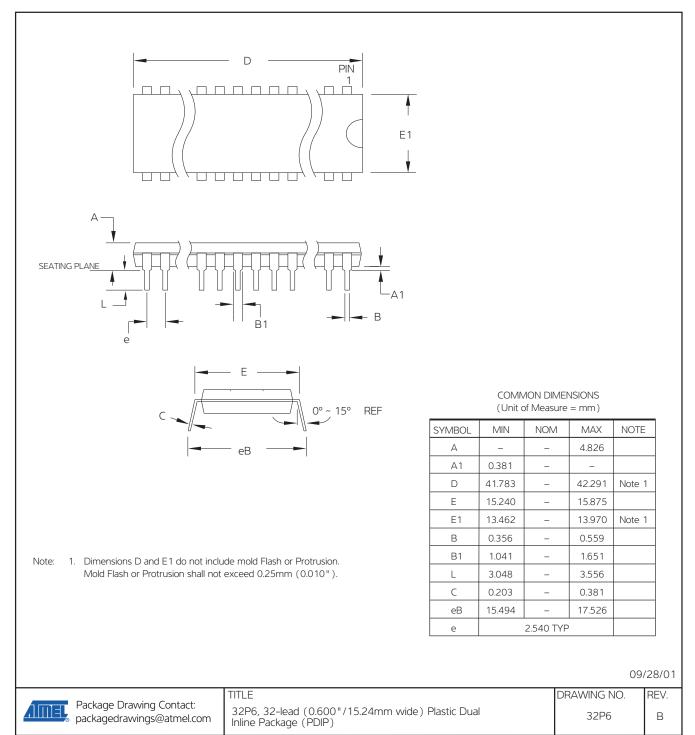


8. Package Information

32J – PLCC



32P6 – PDIP







9. Revision history

| Doc. Rev. | Date | Comments |
|-----------|---------|--|
| 0321N | 04/2011 | Remove TSOP package Add lead finish to ordering information |
| 0321M | 12/2007 | |



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