

Description

PIC18F26/45/46Q10 microcontrollers feature analog, core independent, and communication peripherals for a wide range of general purpose and low-power applications. These 28/40/44-pin devices are equipped with a 10-bit ADC with Computation (ADCC) automating Capacitive Voltage Divider (CVD) techniques for advanced touch sensing, averaging, filtering, oversampling and performing automatic threshold comparisons. They also offer a set of core independent peripherals such as Complementary Waveform Generator (CWG), Windowed Watchdog Timer (WWDT), Cyclic Redundancy Check (CRC)/Memory Scan, Zero-Cross Detect (ZCD), Configurable Logic Cell (CLC), and Peripheral Pin Select (PPS), providing increased design flexibility and lower system cost.

Core Features

- C Compiler Optimized RISC Architecture
- Operating Speed:
 - DC – 64 MHz clock input over the full V_{DD} range
 - 62.5 ns minimum instruction cycle
- Programmable 2-Level Interrupt Priority
- 31-Level Deep Hardware Stack
- Three 8-Bit Timers (TMR2/4/6) with Hardware Limit Timer (HLT)
- Four 16-Bit Timers (TMR0/1/3/5)
- Low-Current Power-on Reset (POR)
- Power-up Timer (PWRT)
- Brown-out Reset (BOR)
- Low-Power BOR (LPBOR) Option
- Windowed Watchdog Timer (WWDT):
 - Watchdog Reset on too long or too short interval between watchdog clear events
 - Variable prescaler selection
 - Variable window size selection
 - All sources configurable in hardware or software

Memory

- Up to 64K Bytes Program Flash Memory
- Up to 3615 Bytes Data SRAM Memory
- Up to 1024 Bytes Data EEPROM
- Programmable Code Protection
- Direct, Indirect and Relative Addressing modes

Operating Characteristics

- Operating Voltage Range:
 - 1.8V to 5.5V
- Temperature Range:
 - Industrial: -40°C to 85°C
 - Extended: -40°C to 125°C

Power-Saving Operation Modes

- Doze: CPU and Peripherals Running at Different Cycle Rates (typically CPU is lower)
- Idle: CPU Halted While Peripherals Operate
- Sleep: Lowest Power Consumption
- Peripheral Module Disable (PMD):
 - Ability to selectively disable hardware module to minimize active power consumption of unused peripherals
- Extreme Low-Power mode (XLP)
 - Sleep: 500 nA typical @ 1.8V
 - Sleep and Watchdog Timer: 900 nA typical @ 1.8V

Digital Peripherals

- Configurable Logic Cell (CLC):
 - Integrated combinational and sequential logic
- Complementary Waveform Generator (CWG):
 - Rising and falling edge dead-band control
 - Full-bridge, half-bridge, 1-channel drive
 - Multiple signal sources
- Capture/Compare/PWM (CCP) Modules:
 - Two CCPs
 - 16-bit resolution for Capture/Compare modes
 - 10-bit resolution for PWM mode
- 10-Bit Pulse-Width Modulators (PWM):
 - Two 10-bit PWMs
- Serial Communications:
 - Two enhanced USART (EUSART) with Auto-Baud Detect, Auto-wake-up on Start, RS-232, RS-485, LIN compatible
 - SPI
 - I²C, SMBus and PMBus® compatible
- Up to 35 I/O Pins and One Input Pin:
 - Individually programmable pull-ups
 - Slew rate control
 - Interrupt-on-change on all pins
 - Input level selection control

- Programmable CRC with Memory Scan:
 - Reliable data/program memory monitoring for Fail-Safe operation (e.g., Class B)
 - Calculate CRC over any portion of Flash or EEPROM
 - High-speed or background operation
- Hardware Limit Timer (TMR2/4/6+HLT):
 - Hardware monitoring and Fault detection
- Peripheral Pin Select (PPS):
 - Enables pin mapping of digital I/O
- Data Signal Modulator (DSM)

Analog Peripherals

- 10-Bit Analog-to-Digital Converter with Computation (ADCC):
 - 35 external channels
 - Conversion available during Sleep
 - Four internal analog channels
 - Internal and external trigger options
 - Automated math functions on input signals:
 - Averaging, filter calculations, oversampling and threshold comparison
 - 8-bit hardware acquisition timer
- Hardware Capacitive Voltage Divider (CVD) Support:
 - 8-bit precharge timer
 - Adjustable Sample-and-Hold capacitor array
 - Guard ring digital output drive
- Zero-Cross Detect (ZCD):
 - Detect when AC signal on pin crosses ground
- 5-Bit Digital-to-Analog Converter (DAC):
 - Output available externally
 - Programmable 5-bit voltage (% of V_{DD} , $[V_{REF+} - V_{REF-}]$, FVR)
 - Internal connections to comparators and ADC
- Two Comparators (CMP):
 - Four external inputs
 - External output via PPS
- Fixed Voltage Reference (FVR) Module:
 - 1.024V, 2.048V and 4.096V output levels
 - Two buffered outputs: One for DAC/CMP and one for ADC

Clocking Structure

- High-Precision Internal Oscillator Block (HFINTOSC):
 - Selectable frequencies up to 64 MHz
 - $\pm 1\%$ at calibration
- 32 kHz Low-Power Internal Oscillator (LFINTOSC)
- External 32 kHz Crystal Oscillator (SOSC)

- External High-frequency Oscillator Block:
 - Three crystal/resonator modes
 - Digital Clock Input mode
 - 4x PLL with external sources
- Fail-Safe Clock Monitor:
 - Allows for safe shutdown if external clock stops
- Oscillator Start-up Timer (OST)

Programming/Debug Features

- In-Circuit Serial Programming™ (ICSP™) via Two Pins
- In-Circuit Debug (ICD) with Three Breakpoints via Two Pins
- Debug Integrated On-Chip

PIC18F26/45/46Q10 Family Types

Table 1. Devices Included in This Data Sheet

| Device | Program Memory Flash (bytes) | Data SRAM (bytes)(2) | Data EEPROM (bytes) | I/O Pins | 16-bit Timers | Comparators | 10-bit ADCC (ch) | 5-bit DAC | Zero-Cross Detect | CCP/10-bit PWM | CWG | CLC | Low Voltage Detect (LVD) | 8-bit TMR with HLT | Windowed Watchdog Timer | CRC with Memory Scan | EUSART | I ² C/SPI | PPS | Peripheral Module Disable | Temperature Indicator | Debug(1) |
|-------------|---------------------------------|-------------------------|------------------------|----------|---------------|-------------|------------------|-----------|-------------------|----------------|-----|-----|--------------------------|--------------------|----------------------------|----------------------|--------|----------------------|-----|---------------------------|-----------------------|----------|
| PIC18F26Q10 | 64k | 3615 | 1024 | 25 | 4 | 2 | 24 | 1 | 1 | 2/2 | 1 | 8 | 1 | 3 | Y | Y | 2 | 2 | Y | Y | Y | I |
| PIC18F45Q10 | 32k | 2304 | 256 | 36 | 4 | 2 | 35 | 1 | 1 | 2/2 | 1 | 8 | 1 | 3 | Y | Y | 2 | 2 | Y | Y | Y | I |
| PIC18F46Q10 | 64k | 3615 | 1024 | 36 | 4 | 2 | 35 | 1 | 1 | 2/2 | 1 | 8 | 1 | 3 | Y | Y | 2 | 2 | Y | Y | Y | I |

Note:

1. Debugging Methods: (I) – Integrated on-chip.
2. SRAM includes 256 bytes of SECTOR space which is not included in the data size displayed by MPLAB® X.

Table 2. Devices not Included in This Data Sheet

| Device | Program Memory Flash (bytes) | Data SRAM (bytes)(2) | Data EEPROM (bytes) | I/O Pins | 16-bit Timers | Comparators | 10-bit ADCC (ch) | 5-bit DAC | Zero-Cross Detect | CCP/10-bit PWM | CWG | CLC | Low Voltage Detect (LVD) | 8-bit TMR with HLT | Windowed Watchdog Timer | CRC with Memory Scan | EUSART | I ² C/SPI | PPS | Peripheral Module Disable | Temperature Indicator | Debug(1) |
|-------------|---------------------------------|-------------------------|------------------------|----------|---------------|-------------|------------------|-----------|-------------------|----------------|-----|-----|--------------------------|--------------------|----------------------------|----------------------|--------|----------------------|-----|---------------------------|-----------------------|----------|
| PIC18F24Q10 | 16k | 1280 | 256 | 25 | 4 | 2 | 24 | 1 | 1 | 2/2 | 1 | 0 | 1 | 3 | Y | Y | 1 | 1 | Y | Y | Y | I |
| PIC18F25Q10 | 32k | 2304 | 256 | 25 | 4 | 2 | 24 | 1 | 1 | 2/2 | 1 | 0 | 1 | 3 | Y | Y | 1 | 1 | Y | Y | Y | I |
| PIC18F27Q10 | 128k | 3615 | 1024 | 25 | 4 | 2 | 24 | 1 | 1 | 2/2 | 1 | 8 | 1 | 3 | Y | Y | 2 | 2 | Y | Y | Y | I |
| PIC18F47Q10 | 128k | 3615 | 1024 | 36 | 4 | 2 | 35 | 1 | 1 | 2/2 | 1 | 8 | 1 | 3 | Y | Y | 2 | 2 | Y | Y | Y | I |

Note:


1. Debugging Methods: (I) – Integrated on-chip.
2. SRAM includes 256 bytes of SECTOR space which is not included in the data size displayed by MPLAB® X.

Data Sheet Index:


1. DS40001945 Data Sheet, 28-Pin, 8-bit Flash Microcontrollers

2. DS40002043 Data Sheet, 28/40-Pin, 8-bit Flash Microcontrollers

Packages

 **Important:** For other small form-factor package availability and marking information, visit www.microchip.com/packaging or contact your local Microchip sales office.

| Packages | SPDIP (SP) | SOIC (SO) | SSOP (SS) | QFN (ML) (6x6x0.9) | VQFN (STX) (4x4x1) | TQFP (PT) | PDIP (P) | QFN (MP) (5x5x0.9) |
|-------------|---------------|--------------|--------------|--------------------------|--------------------------|--------------|-------------|--------------------------|
| PIC18F26Q10 | • | • | • | • | • | | | |
| PIC18F45Q10 | | | | | | • | • | • |
| PIC18F46Q10 | | | | | | • | • | • |

 **Important:** Pin details are subject to change.

Pin Allocation Tables

Table 3. 28-Pin Allocation Table

| I/O(2) | 28-Pin SPDIP, SOIC, SSOP | 28-Pin (V)QFN | A/D | Reference | Comparator | Timers | CCP | CWG | ZCD | Interrupt | EUSART | DSM | MSSP | Pull-up | Basic |
|--------|-----------------------------|---------------|------|--|------------------|----------------------|-----|---------------------|-------|------------------------------|--------------------------|-----------------------|--|---------|----------------|
| RA0 | 2 | 27 | ANA0 | — | C1IN0- C2IN0- | — | — | — | — | IOCA0 | — | — | — | Y | — |
| RA1 | 3 | 28 | ANA1 | — | C1IN1- C2IN1- | — | — | — | — | IOCA1 | — | — | — | Y | — |
| RA2 | 4 | 1 | ANA2 | DAC1OUT1 VREF- (DAC) VREF- (ADC) | C1IN0+ C2IN0+ | — | — | — | — | IOCA2 | — | — | — | Y | — |
| RA3 | 5 | 2 | ANA3 | VREF+ (DAC) VREF+ (ADC) | C1IN1+ | — | — | — | — | IOCA3 | — | MDCARL ⁽¹⁾ | — | Y | — |
| RA4 | 6 | 3 | ANA4 | — | — | TOCKI ⁽¹⁾ | — | — | — | IOCA4 | — | MDCARH ⁽¹⁾ | — | Y | — |
| RA5 | 7 | 4 | ANA5 | — | — | — | — | — | — | IOCA5 | — | MDSRC ⁽¹⁾ | SS1 ⁽¹⁾ | Y | — |
| RA6 | 10 | 7 | ANA6 | — | — | — | — | — | — | IOCA6 | — | — | — | Y | CLKOUT OSC2 |
| RA7 | 9 | 6 | ANA7 | — | — | — | — | — | — | IOCA7 | — | — | — | Y | OSC1 CLKIN |
| RB0 | 21 | 18 | ANB0 | — | C2IN1+ | — | — | CWG1 ⁽¹⁾ | ZCDIN | IOCB0 INT0 ⁽¹⁾ | — | — | SS2 ⁽¹⁾ | Y | — |
| RB1 | 22 | 19 | ANB1 | — | C1IN3- C2IN3- | — | — | — | — | IOCB1 INT1 ⁽¹⁾ | — | — | SCK2 ⁽¹⁾ SCL2 ^(3,4) | Y | — |
| RB2 | 23 | 20 | ANB2 | — | — | — | — | — | — | IOCB2 INT2 ⁽¹⁾ | — | — | SDI2 ⁽¹⁾ SDA2 ^(3,4) | Y | — |
| RB3 | 24 | 21 | ANB3 | — | C1IN2- C2IN2- | — | — | — | — | IOCB3 | — | — | — | Y | — |
| RB4 | 25 | 22 | ANB4 | — | — | T5G ⁽¹⁾ | — | — | — | IOCB4 | — | — | — | Y | — |
| RB5 | 26 | 23 | ANB5 | — | — | T1G ⁽¹⁾ | — | — | — | IOCB5 | — | — | — | Y | — |
| RB6 | 27 | 24 | ANB6 | — | — | — | — | — | — | IOCB6 | CK2 ^(1,3) | — | — | Y | ICSPCLK |
| RB7 | 28 | 25 | ANB7 | DAC1OUT2 | — | T6IN ⁽¹⁾ | — | — | — | IOCB7 | RX2/DT2 ^(1,3) | — | — | Y | ICSPDAT |

.....continued

| I/O ⁽²⁾ | 28-Pin SPDIP, SOIC, SSOP | 28-Pin (V)QFN | A/D | Reference | Comparator | Timers | CCP | CWG | ZCD | Interrupt | EUSART | DSM | MSSP | Pull-up | Basic |
|--------------------------------|-----------------------------|---------------|------------------|-----------|----------------|--|------------------------------|----------------------------------|-----|-----------|--|-----|--|---------|-----------------------|
| RC0 | 11 | 8 | ANC0 | — | — | T1CKI ⁽¹⁾ T3CKI ⁽¹⁾ T3G ⁽¹⁾ | — | — | — | IOCC0 | — | — | — | Y | SOSCO |
| RC1 | 12 | 9 | ANC1 | — | — | — | CCP2 ⁽¹⁾ | — | — | IOCC1 | — | — | — | Y | SOSCIN SOSCI |
| RC2 | 13 | 10 | ANC2 | — | — | T5CKI ⁽¹⁾ | CCP1 ⁽¹⁾ | — | — | IOCC2 | — | — | — | Y | — |
| RC3 | 14 | 11 | ANC3 | — | — | T2IN ⁽¹⁾ | — | — | — | IOCC3 | — | — | SCK1 ⁽¹⁾ SCL1 ^(3,4) | Y | — |
| RC4 | 15 | 12 | ANC4 | — | — | — | — | — | — | IOCC4 | — | — | SDI1 ⁽¹⁾ SDA1 ^(3,4) | Y | — |
| RC5 | 16 | 13 | ANC5 | — | — | T4IN ⁽¹⁾ | — | — | — | IOCC5 | — | — | — | Y | — |
| RC6 | 17 | 14 | ANC6 | — | — | — | — | — | — | IOCC6 | CK1 ^(1,3) | — | — | Y | — |
| RC7 | 18 | 15 | ANC7 | — | — | — | — | — | — | IOCC7 | RX1/DT1 ^(1,3) | — | — | Y | — |
| RE3 | 1 | 26 | — | — | — | — | — | — | — | IOCE3 | — | — | — | Y | V _{pp} /MCLR |
| V _{SS} | 19 | 16 | — | — | — | — | — | — | — | — | — | — | — | — | V _{SS} |
| V _{DD} ⁽⁵⁾ | 20 | 17 | — | — | — | — | — | — | — | — | — | — | — | — | V _{DD} |
| V _{SS} | 8 | 5 | — | — | — | — | — | — | — | — | — | — | — | — | V _{SS} |
| OUT ⁽²⁾ | — | — | ADGRDA ADGRDB | — | C1OUT C2OUT | TMR0 | CCP1 CCP2 PWM3 PWM4 | CWG1A CWG1B CWG1C CWG1D | — | — | TX1/CK1 ⁽³⁾ DT1 ⁽³⁾ TX2/CK2 ⁽³⁾ DT2 ⁽³⁾ | DSM | SDO1 SCK1 SDO2 SCK2 | — | — |

Notes:

1. This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins. Refer to the peripheral input selection table for details on which port pins may be used for this signal.
2. All output signals shown in this row are PPS remappable. These signals may be mapped to output onto one of several PORTx pin options as described in the peripheral output selection table.
3. This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.
4. These pins are configured for I²C logic levels; The SCLx/SDAx signals may be assigned to any of these pins. PPS assignments to the other pins (e.g., RB1) will operate, but input logic levels will be standard TTL/ST as selected by the INLV register, instead of the I²C specific or SMBus input buffer thresholds.
5. A 0.1 μ F bypass capacitor to V_{SS} is required on the V_{DD} pin.

Table 4. 40/44-Pin Allocation Table

| I/O ⁽²⁾ | 40-Pin PDIP | 40-Pin QFN | 44-Pin TQFP | A/D | Reference | Comparator | Timers | CCP | CWG | ZCD | Interrupt | EUSART | DSM | MSSP | Pull-up | Basic |
|--------------------|----------------|---------------|----------------|------|---|------------------|----------------------|-----|---------------------|-------|------------------------------|--------|-----------------------|--|---------|----------------|
| RA0 | 2 | 17 | 19 | ANA0 | — | C1INO- C2INO- | — | — | — | — | IOCA0 | — | — | — | Y | — |
| RA1 | 3 | 18 | 20 | ANA1 | — | C1IN1- C2IN1- | — | — | — | — | IOCA1 | — | — | — | Y | — |
| RA2 | 4 | 19 | 21 | ANA2 | DAC1OUT1 V _{REF-} (DAC5) V _{REF-} (ADC) | C1INO+ C2INO+ | — | — | — | — | IOCA2 | — | — | — | Y | — |
| RA3 | 5 | 20 | 22 | ANA3 | V _{REF+} (DAC5) V _{REF+} (ADC) | C1IN1+ | — | — | — | — | IOCA3 | — | MDCARL ⁽¹⁾ | — | Y | — |
| RA4 | 6 | 21 | 23 | ANA4 | — | — | T0CKI ⁽¹⁾ | — | — | — | IOCA4 | — | MDCARH ⁽¹⁾ | — | Y | — |
| RA5 | 7 | 22 | 24 | ANA5 | — | — | — | — | — | — | IOCA5 | — | MDSRC ⁽¹⁾ | SS1 ⁽¹⁾ | Y | — |
| RA6 | 14 | 29 | 31 | ANA6 | — | — | — | — | — | — | IOCA6 | — | — | — | Y | CLKOUT OSC2 |
| RA7 | 13 | 28 | 30 | ANA7 | — | — | — | — | — | — | IOCA7 | — | — | — | Y | OSC1 CLKIN |
| RB0 | 33 | 8 | 8 | ANB0 | — | C2IN1+ | — | — | CWG1 ⁽¹⁾ | ZCDIN | IOCB0 INT0 ⁽¹⁾ | — | — | SS2 ⁽¹⁾ | Y | — |
| RB1 | 34 | 9 | 9 | ANB1 | — | C1IN3- C2IN3- | — | — | — | — | IOCB1 INT1 ⁽¹⁾ | — | — | SCK2 ⁽¹⁾ SCL2 ^(3,4) | Y | — |
| RB2 | 35 | 10 | 10 | ANB2 | — | — | — | — | — | — | IOCB2 INT2 ⁽¹⁾ | — | — | SDI2 ⁽¹⁾ SDA2 ^(3,4) | Y | — |

.....continued

| I/O(2) | 40-Pin PDIP | 40-Pin QFN | 44-Pin TQFP | A/D | Reference | Comparator | Timers | CCP | CWG | ZCD | Interrupt | EUSART | DSM | MSSP | Pull-up | Basic |
|--------------------------------|----------------|---------------|----------------|------------------|-----------|------------------|--|------------------------------|----------------------------------|-----|-----------|--|-----|--|---------|-----------------------|
| RB3 | 36 | 11 | 11 | ANB3 | — | C1IN2- C2IN2- | — | — | — | — | IOCB3 | — | — | — | Y | — |
| RB4 | 37 | 12 | 14 | ANB4 | — | — | T5G ⁽¹⁾ | — | — | — | IOCB4 | — | — | — | Y | — |
| RB5 | 38 | 13 | 15 | ANB5 | — | — | T1G ⁽¹⁾ | — | — | — | IOCB5 | — | — | — | Y | — |
| RB6 | 39 | 14 | 16 | ANB6 | — | — | — | — | — | — | IOCB6 | CK2 ^(1,3) | — | — | Y | ICSPCLK |
| RB7 | 40 | 15 | 17 | ANB7 | DAC1OUT2 | — | T6IN ⁽¹⁾ | — | — | — | IOCB7 | RX2/ DT2 ^(1,3) | — | — | Y | ICSPDAT |
| RC0 | 15 | 30 | 32 | ANC0 | — | — | T1CKI ⁽¹⁾ T3CKI ⁽¹⁾ T3G ⁽¹⁾ | — | — | — | IOCC0 | — | — | — | Y | SOSCO |
| RC1 | 16 | 31 | 35 | ANC1 | — | — | — | CCP2 ⁽¹⁾ | — | — | IOCC1 | — | — | — | Y | SOSCIN SOSCI |
| RC2 | 17 | 32 | 36 | ANC2 | — | — | T5CKI ⁽¹⁾ | CCP1 ⁽¹⁾ | — | — | IOCC2 | — | — | — | Y | — |
| RC3 | 18 | 33 | 37 | ANC3 | — | — | T2IN ⁽¹⁾ | — | — | — | IOCC3 | — | — | SCK1 ⁽¹⁾ SCL1 ^(3,4) | Y | — |
| RC4 | 23 | 38 | 42 | ANC4 | — | — | — | — | — | — | IOCC4 | — | — | SDI1 ⁽¹⁾ SDA1 ^(3,4) | Y | — |
| RC5 | 24 | 39 | 43 | ANC5 | — | — | T4IN ⁽¹⁾ | — | — | — | IOCC5 | — | — | — | Y | — |
| RC6 | 25 | 40 | 44 | ANC6 | — | — | — | — | — | — | IOCC6 | CK1 ^(1,3) | — | — | Y | — |
| RC7 | 26 | 1 | 1 | ANC7 | — | — | — | — | — | — | IOCC7 | RX1/ DT1 ^(1,3) | — | — | Y | — |
| RD0 | 19 | 34 | 38 | AND0 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD1 | 20 | 35 | 39 | AND1 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD2 | 21 | 36 | 40 | AND2 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD3 | 22 | 37 | 41 | AND3 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD4 | 27 | 2 | 2 | AND4 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD5 | 28 | 3 | 3 | AND5 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD6 | 29 | 4 | 4 | AND6 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RD7 | 30 | 5 | 5 | AND7 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RE0 | 8 | 23 | 25 | ANE0 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RE1 | 9 | 24 | 26 | ANE1 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RE2 | 10 | 25 | 27 | ANE2 | — | — | — | — | — | — | — | — | — | — | Y | — |
| RE3 | 1 | 16 | 18 | — | — | — | — | — | — | — | IOCE3 | — | — | — | Y | V _{PP} /MCLR |
| V _{SS} | 12 | 6 | 6 | — | — | — | — | — | — | — | — | — | — | — | — | V _{SS} |
| V _{DD} ⁽⁵⁾ | 11 | 7 | 7 | — | — | — | — | — | — | — | — | — | — | — | — | V _{DD} |
| V _{DD} ⁽⁵⁾ | 32 | 26 | 28 | — | — | — | — | — | — | — | — | — | — | — | — | V _{SS} |
| V _{SS} | 31 | 27 | 29 | — | — | — | — | — | — | — | — | — | — | — | — | V _{SS} |
| OUT ⁽²⁾ | — | — | — | ADGRDA ADGRDB | — | C1OUT C2OUT | TMR0 | CCP1 CCP2 PWM3 PWM4 | CWG1A CWG1B CWG1C CWG1D | — | — | TX1/CK1 ⁽³⁾ DT1 ⁽³⁾ TX2/CK2 ⁽³⁾ DT2 ⁽³⁾ | DSM | SDO1 SCK1 SDO2 SCK2 | — | — |

Notes:

- This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins. Refer to the peripheral input selection table for details on which port pins may be used for this signal.
- All output signals shown in this row are PPS remappable. These signals may be mapped to output onto one of several PORTx pin options as described in the peripheral output selection table.
- This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.
- These pins are configured for I²C logic levels; The SCLx/SDAx signals may be assigned to any of these pins. PPS assignments to the other pins (e.g., RB1) will operate, but input logic levels will be standard TTL/ST as selected by the INLVL register, instead of the I²C specific or SMBus input buffer thresholds.
- A 0.1 μ F bypass capacitor to V_{SS} is required on all V_{DD} pins.

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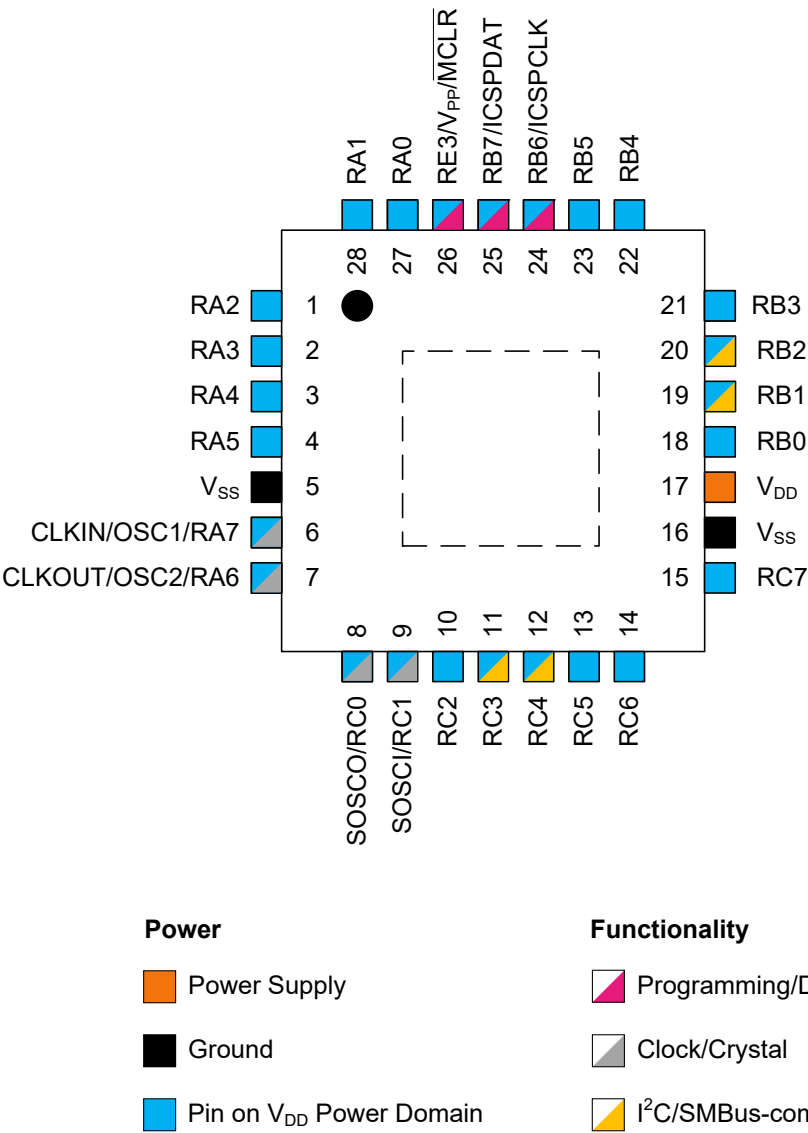
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1. Pin Diagrams

1.1

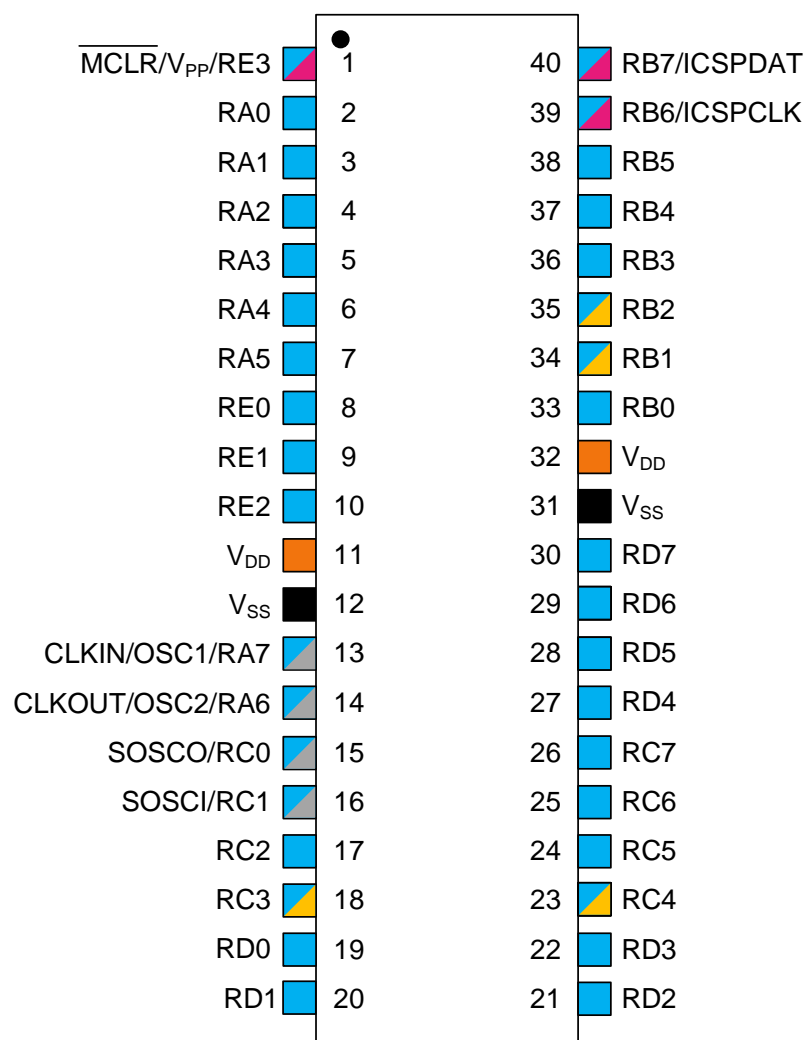
Figure 1-1.
28-Pin VQFN
28-Pin UQFN






1.2




Figure 1-2.
28-Pin SPDIP
28-Pin SSOP
28-Pin SOIC



**Power**

-  Power Supply
-  Ground
-  Pin on V_{DD} Power Domain

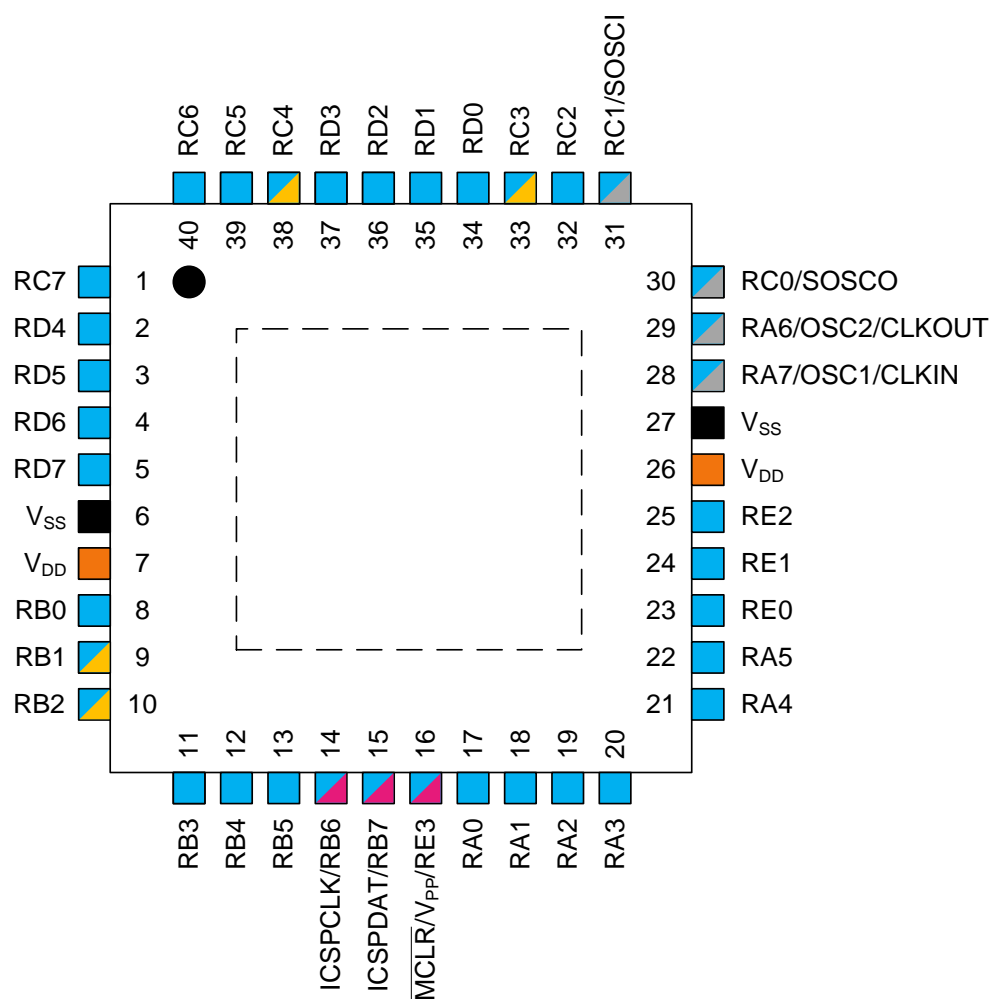
Functionality

-  Programming/Debug
-  Clock/Crystal
-  I²C/SMBus-compatible




1.4

Figure 1-4.




40-Pin QFN



Power

-  Power Supply
-  Ground
-  Pin on V_{DD} Power Domain

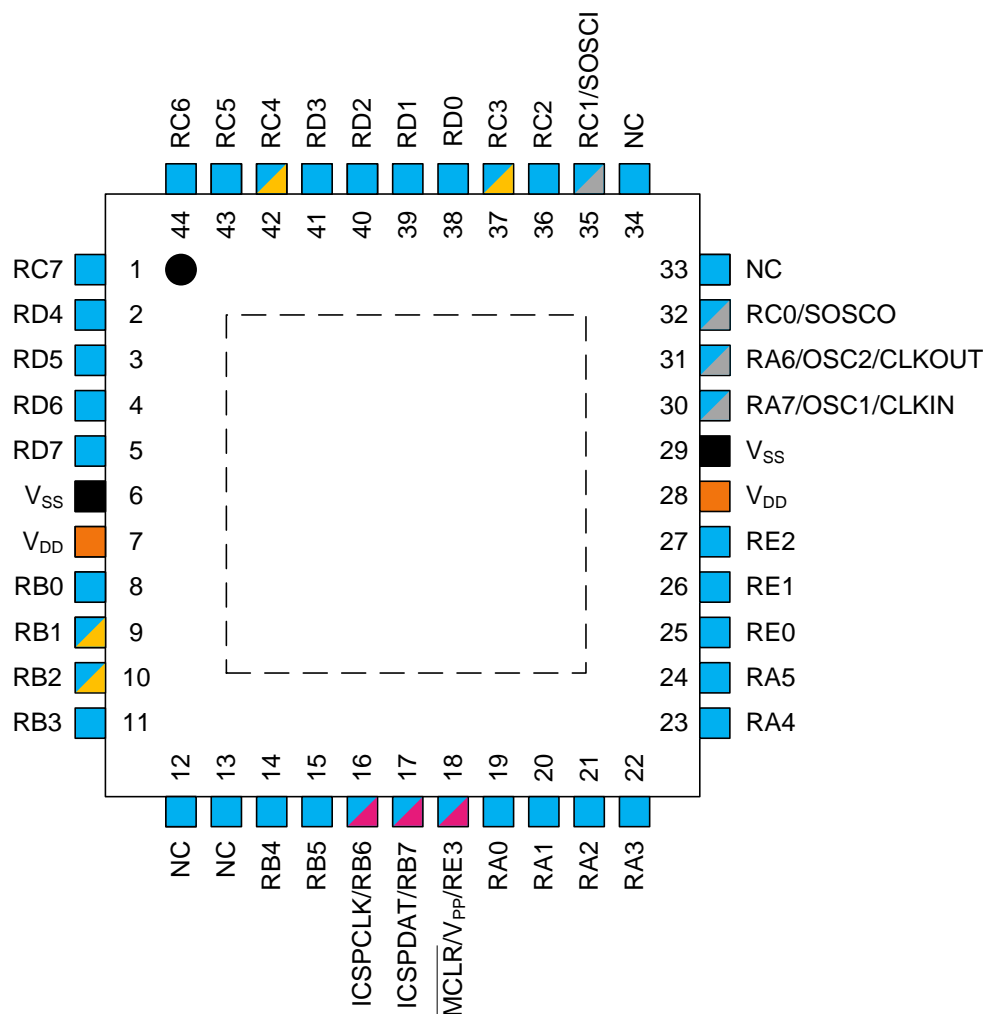
Functionality




-  Programming/Debug
-  Clock/Crystal
-  I²C/SMBus-compatible

1.5




Figure 1-5.

44-Pin TQFP

**Power**

-  Power Supply
-  Ground
-  Pin on V_{DD} Power Domain

Functionality

-  Programming/Debug
-  Clock/Crystal
-  I²C/SMBus-compatible

2. Device Overview

This document contains device specific information for the following devices:

| |
|---------------|
| • PIC18F26Q10 |
| • PIC18F45Q10 |
| • PIC18F46Q10 |

This family offers the advantages of all PIC18 microcontrollers – namely, high computational performance at an economical price – with the addition of high-endurance Program Flash Memory. In addition to these features, the PIC18F26/45/46Q10 family introduces design enhancements that make these microcontrollers a logical choice for many high-performance, power sensitive applications.

2.1 New Core Features

2.1.1 Low-Power Technology

All of the devices in the PIC18F26/45/46Q10 family incorporate a range of features that can significantly reduce power consumption during operation. Key items include:

- Alternate Run modes: By clocking the microcontroller from the secondary oscillator or the internal oscillator block, power consumption during code execution can be reduced by as much as 90%.
- Multiple Idle modes: The controller can also run with its CPU core disabled but the peripherals are still active. In these states, power consumption can be reduced even further, to as little as 4% of normal operation requirements.
- On-the-fly mode switching: The Power-Managed modes are invoked by user code during operation, allowing the user to incorporate power-saving ideas into their application's software design.
- Peripheral Module Disable: Modules that are not being used in the code can be selectively disabled using the PMD module. This further reduces the power consumption.

2.1.2 Multiple Oscillator Options and Features

All of the devices in the PIC18F26/45/46Q10 family offer several different oscillator options. The PIC18F26/45/46Q10 family can be clocked from several different sources:

- HFINTOSC
 - 1-64 MHz precision digitally controlled internal oscillator
- LFINTOSC
 - 31 kHz internal oscillator
- EXTOSC
 - External clock (EC)
 - Low-power oscillator (LP)
 - Medium power oscillator (XT)
 - High power oscillator (HS)
- SOSC
 - Secondary oscillator circuit optimized for 31 kHz clock crystals
- A Phase Lock Loop (PLL) frequency multiplier (4x) is available to the External Oscillator modes enabling clock speeds of up to 64 MHz

- **Fail-Safe Clock Monitor:** This option constantly monitors the main clock source against a reference signal provided by the LFINTOSC. If a clock failure occurs, the controller is switched to the internal oscillator block, allowing for continued operation or a safe application shutdown.

2.2 Other Special Features

- **Memory Endurance:** The Flash cells for both program memory and data EEPROM are rated to last for many thousands of erase/write cycles – up to 10K for program memory and 100K for EEPROM. Data retention without refresh is conservatively estimated to be greater than 40 years.
- **Self-programmability:** These devices can write to their own program memory spaces under internal software control. By using a boot loader routine located in the protected Boot Block at the top of program memory, it becomes possible to create an application that can update itself in the field.
- **Extended Instruction Set:** The PIC18F26/45/46Q10 family includes an optional extension to the PIC18 instruction set, which adds eight new instructions and an Indexed Addressing mode. This extension, enabled as a device configuration option, has been specifically designed to optimize re-entrant application code originally developed in high-level languages, such as C.
- **Enhanced Peripheral Pin Select:** The Peripheral Pin Select (PPS) module connects peripheral inputs and outputs to the device I/O pins. Only digital signals are included in the selections. All analog inputs and outputs remain fixed to their assigned pins.
- **Enhanced Addressable EUSART:** This serial communication module is capable of standard RS-232 operation and provides support for the LIN bus protocol. Other enhancements include automatic baud rate detection and a 16-bit Baud Rate Generator for improved resolution. When the microcontroller is using the internal oscillator block, the EUSART provides stable operation for applications that talk to the outside world without using an external crystal (or its accompanying power requirement).
- **10-bit Analog-to-Digital (ADC) with Computation:** This module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period and thus, reduce code overhead. It has a new module called Analog-to-Digital Converter with Computation (ADCC), which provides a digital filter and threshold interrupt functions.
- **Windowed Watchdog Timer (WWDT):**
 - Timer monitoring of overflow and underflow events
 - Variable prescaler selection
 - Variable window size selection
 - All sources configurable in hardware or software

2.3 Details on Individual Family Members

Devices in the PIC18F26/45/46Q10 family are available in 28-pin and 40/44-pin packages. The block diagram for this device is shown in the [Figure 2-1](#).

The devices have the following differences:

1. Program Flash Memory
2. Data Memory SRAM
3. Data Memory EEPROM
4. Analog-to-Digital (A/D) channels
5. I/O ports
6. Enhanced USART
7. Input Voltage Range/Power Consumption

All other features for devices in this family are identical. These are summarized in the following Device Features table.

The pinouts for all devices are listed in the pin summary tables.

Table 2-1. Device Features

| Features | PIC18F26Q10 | PIC18F45Q10 | PIC18F46Q10 |
|--|--|--|--|
| Program Memory (Bytes) | 65536 | 32768 | 65536 |
| Program Memory (Instructions) | 32768 | 16384 | 32768 |
| Data Memory (Bytes) | 3615 | 2048 | 3615 |
| Data EEPROM Memory (Bytes) | 1024 | 256 | 1024 |
| I/O Ports | A,B,C,E ⁽¹⁾ | A,B,C,D,E | A,B,C,D,E |
| Capture/Compare/PWM Modules (CCP) | 2 | 2 | 2 |
| 10-Bit Pulse-Width Modulator (PWM) | 2 | 2 | 2 |
| 10-Bit A/D Module with Computation Accelerator | 4 internal 24 external | 4 internal 35 external | 4 internal 35 external |
| Packages | 28-pin SPDIP 28-pin SOIC 28-pin SSOP 28-pin VQFN 28-pin QFN | 40-pin PDIP 40-pin QFN 44-pin TQFP | 40-pin PDIP 40-pin QFN 44-pin TQFP |
| Timers (16-/8-bit) | 4/3 | 4/3 | 4/3 |
| Serial Communications | 2 MSSP, 2 EUSART | 2 MSSP, 2 EUSART | 2 MSSP, 2 EUSART |
| Enhanced Complementary Waveform Generator (ECWG) | 1 | 1 | 1 |
| Zero-Cross Detect (ZCD) | 1 | 1 | 1 |
| Data Signal Modulator (DSM) | 1 | 1 | 1 |
| Configurable Logic Cell (CLC) | 8 | 8 | 8 |
| Peripheral Pin Select (PPS) | Yes | Yes | Yes |
| Peripheral Module Disable (PMD) | Yes | Yes | Yes |
| 16-bit CRC with NVMSCAN | Yes | Yes | Yes |
| Programmable High/Low-Voltage Detect (HLVD) | Yes | Yes | Yes |
| Programmable Brown-out Reset (BOR) | Yes | Yes | Yes |
| Resets (and Delays) | POR, BOR, RESET Instruction, Stack Overflow, Stack Underflow (PWRT, OST), MCLR, WDT | POR, BOR, RESET Instruction, Stack Overflow, Stack Underflow (PWRT, OST), MCLR, WDT | POR, BOR, RESET Instruction, Stack Overflow, Stack Underflow (PWRT, OST), MCLR, WDT |
| Instruction Set | 75 Instructions; 83 with Extended Instruction Set enabled | 75 Instructions; 83 with Extended Instruction Set enabled | 75 Instructions; 83 with Extended Instruction Set enabled |
| Operating Frequency | DC – 64 MHz | DC – 64 MHz | DC – 64 MHz |
| Note: 1. PORTE contains the single RE3 read-only bit. | | | |

The diagram illustrates the internal architecture of the PIC16C701 microcontroller. Key components and their interconnections include:

- System Buses:**
 - Data Bus [8]:** Connects the CPU core to external memory and peripherals.
 - Instruction Bus [16]:** Connects the CPU core to the Program Memory.
- CPU Core:**
 - Program Counter (PCU, PCH, PCL):** Controls the flow of instructions.
 - Program Memory:** Stores the program code.
 - Data Memory:** Stores data.
 - ALU [8]:** Performs arithmetic and logic operations.
 - Registers:** Includes the BSR, FSR0, FSR1, FSR2, and various general-purpose registers (PORTA, PORTB, PORTC, PORTD, PORTE).
- Peripherals:**
 - Timers:** Timer0, Timer1/Timer3, Timer2/Timer4/Timer6.
 - Comparators:** Comparators C1/C2.
 - ADC:** 10-bit ADC.
 - DAC:** Digital-to-Analog Converter.
 - Other:** BOR HLVD, NVM Controller, PWM3/PWM4, MSSP1/MSSP2, EUSART1/EUSART2, ECWG, DSM, PMD.
- External Connections:**
 - Oscillator:** OSC1(2) and OSC2(2) pins.
 - MCLR(1):** Master Clear Reset pin.
 - Power-up Timer, Power-on Reset, Watchdog Timer, Brown-out Reset, Fail-Safe Clock Monitor:** These are part of the internal power management and reset logic.

- 

2.4 Register and Bit Naming Conventions

2.4.1 Register Names

When there are multiple instances of the same peripheral in a device, the Peripheral Control registers will be depicted as the concatenation of a peripheral identifier, peripheral instance, and control identifier. The control registers section will show just one instance of all the register names with an 'x' in the place of the peripheral instance number. This naming convention may also be applied to peripherals when there is only one instance of that peripheral in the device to maintain compatibility with other devices in the family that contain more than one.

2.4.2 Bit Names

There are two variants for bit names:

- Short name: Bit function abbreviation
- Long name: Peripheral abbreviation + short name

2.4.2.1 Short Bit Names

Short bit names are an abbreviation for the bit function. For example, some peripherals are enabled with the EN bit. The bit names shown in the registers are the short name variant.

Short bit names are useful when accessing bits in C programs. The general format for accessing bits by the short name is `RegisterNamebits.ShortName`. For example, the enable bit, EN, in the `CM1CON0` register can be set in C programs with the instruction `CM1CON0bits.EN = 1`.

Short names are generally not useful in assembly programs because the same name may be used by different peripherals in different bit positions. When this occurs, during the include file generation, all instances of that short bit name are appended with an underscore plus the name of the register in which the bit resides to avoid naming contentions.

2.4.2.2 Long Bit Names

Long bit names are constructed by adding a peripheral abbreviation prefix to the short name. The prefix is unique to the peripheral, thereby making every long bit name unique. The long bit name for the COG1 enable bit is the COG1 prefix, G1, appended with the enable bit short name, EN, resulting in the unique bit name `G1EN`.



Important: The COG1 peripheral is used as an example. Not all devices have the COG peripheral.

Long bit names are useful in both C and assembly programs. For example, in C the `COG1CON0` enable bit can be set with the `G1EN = 1` instruction. In assembly, this bit can be set with the `BSF COG1CON0, G1EN` instruction.

2.4.2.3 Bit Fields

Bit fields are two or more adjacent bits in the same register. Bit fields adhere only to the short bit naming convention. For example, the three Least Significant bits of the `COG1CON0` register contain the Mode Control bits. The short name for this field is MD. There is no long bit name variant. Bit field access is only possible in C programs. The following example demonstrates a C program instruction for setting the COG1 to the Push-Pull mode:

```
COG1CON0bits.MD = 0x5;
```

Individual bits in a bit field can also be accessed with long and short bit names. Each bit is the field name appended with the number of the bit position within the field. For example, the Most Significant mode bit has the short bit name MD2 and the long bit name is `G1MD2`. The following two examples demonstrate assembly program sequences for setting the COG1 to Push-Pull mode:

Example 1:

```
MOVLW    ~(1<<G1MD1)
ANDWF    COG1CON0,F
MOVLW    1<<G1MD2 | 1<<G1MD0
IORWF    COG1CON0,F
```

Example 2:

```
BSF      COG1CON0,G1MD2
BCF      COG1CON0,G1MD1
BSF      COG1CON0,G1MD0
```

2.4.3 Register and Bit Naming Exceptions

2.4.3.1 Status, Interrupt, and Mirror Bits

Status, interrupt enables, Interrupt flags, and Mirror bits are contained in registers that span more than one peripheral. In these cases, the bit name shown is unique so there is no prefix or short name variant.

2.4.3.2 Legacy Peripherals

There are some peripherals that do not strictly adhere to these naming conventions. Peripherals that have existed for many years and are present in almost every device are the exceptions. These exceptions were necessary to limit the adverse impact of the new conventions on legacy code. Peripherals that do adhere to the new convention will include a table in the registers section indicating the long name prefix for each peripheral instance. Peripherals that fall into the exception category will not have this table. These peripherals include, but are not limited to the following:

- EUSART
- MSSP

2.5 Register Legend

The table below describes the conventions for bit types and bit Reset values used in the current data sheet.

Table 2-2. Register Legend

| Value | Description |
|-------|--|
| RO | Read-only bit |
| W | Writable bit |
| U | Unimplemented bit, read as '0' |
| P | Programmable bit |
| '1' | Bit is set |
| '0' | Bit is cleared |
| x | Bit is unknown |
| u | Bit is unchanged |
| ~n/n | Value at POR and BOR/Value at all other Resets |
| q | Reset Value is determined by hardware |
| f | Reset Value is determined by fuse setting |
| g | Reset Value at POR for PPS re-mappable signals |

3. Guidelines for Getting Started with PIC18F26/45/46Q10 Microcontrollers

3.1 Basic Connection Requirements

Getting started with the PIC18F26/45/46Q10 family of 8-bit microcontrollers requires attention to a minimal set of device pin connections before proceeding with development.

The following pins must always be connected:

- All V_{DD} and V_{SS} pins (see [Power Supply Pins](#))
- All V_{DD} pins must have a 0.1 μF bypass capacitor to V_{SS}

These pins must also be connected if they are being used in the end application:

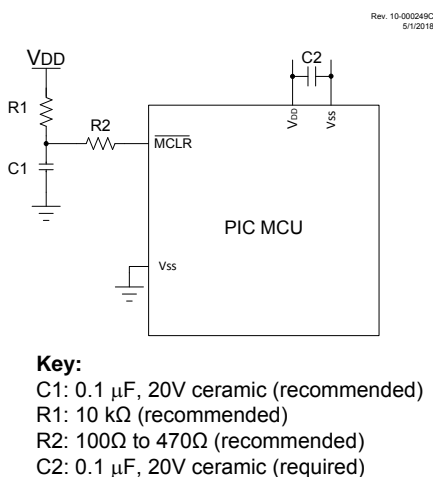
- ICSPCLK/ICSPDAT pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes (see [In-Circuit Serial Programming \(ICSP\) Pins](#))
- OSCI and OSCO pins when an external oscillator source is used (see [External Oscillator Pins](#))
- $\overline{\text{MCLR}}$ pin (see [Master Clear \(\$\overline{\text{MCLR}}\$ Pin\)](#)) when external master clear configuration is selected

Additionally, the following pins may be required:

- V_{REF+}/V_{REF-} pins are used when external voltage reference for analog modules is implemented

The minimum mandatory connections are shown in the figure below.

Figure 3-1. Recommended Minimum Connections



3.2 Power Supply Pins

3.2.1 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins (V_{DD} and V_{SS}) is required.

Consider the following criteria when using decoupling capacitors:

- Value and type of capacitor: A 0.1 μF (100 nF), 10-20V capacitor is required. The capacitor should be a low-ESR device, with a resonance frequency in the range of 200 MHz and higher. Ceramic capacitors are recommended.
- Placement on the printed circuit board: The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as

the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is no greater than 0.25 inch (6 mm).

- **Handling high-frequency noise:** If the board is experiencing high-frequency noise (upward of tens of MHz), add a second ceramic type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μF to 0.001 μF . Place this second capacitor next to each primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible (e.g., 0.1 μF in parallel with 0.001 μF).
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB trace inductance.

3.2.2 Tank Capacitors

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits, including microcontrollers, to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor that meets the acceptable voltage sag at the device. Typical values range from 4.7 μF to 47 μF .

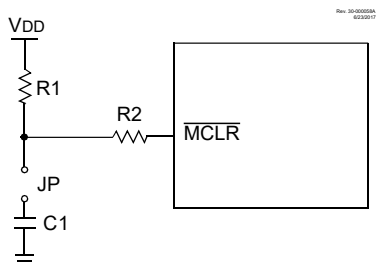
3.3 Master Clear ($\overline{\text{MCLR}}$) Pin

The $\overline{\text{MCLR}}$ pin provides two specific device functions: Device Reset, and Device Programming and Debugging. If programming and debugging are not required in the end application, a direct connection to V_{DD} may be all that is required. The addition of other components, to help increase the application's resistance to spurious Resets from voltage sags, may be beneficial. A typical configuration is shown in [Figure 3-1](#). Other circuit designs may be implemented, depending on the application's requirements.

During programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the $\overline{\text{MCLR}}$ pin. Consequently, specific voltage levels (V_{IH} and V_{IL}) and fast signal transitions must not be adversely affected. Therefore, specific values of $R1$ and $C1$ will need to be adjusted based on the application and PCB requirements. For example, it is recommended that the capacitor, $C1$, be isolated from the $\overline{\text{MCLR}}$ pin during programming and debugging operations by using a jumper as shown in the following figure. The jumper is replaced for normal run-time operations.

Any components associated with the $\overline{\text{MCLR}}$ pin should be placed within 0.25 inch (6 mm) of the pin.

Figure 3-2. Example of $\overline{\text{MCLR}}$ Pin Connections



Notes:

1. $R1 \leq 10 \text{ k}\Omega$ is recommended. A suggested starting value is 10 k Ω . Ensure that the $\overline{\text{MCLR}}$ pin V_{IH} and V_{IL} specifications are met.
2. $R2 \leq 470\Omega$ will limit any current flowing into $\overline{\text{MCLR}}$ from the extended capacitor, C1, in the event of $\overline{\text{MCLR}}$ pin breakdown, due to Electrostatic Discharge (ESD) or Electrical Overstress (EOS). Ensure that the $\overline{\text{MCLR}}$ pin V_{IH} and V_{IL} specifications are met.

3.4 In-Circuit Serial Programming™ (ICSP™) Pins

The ICSPCLK and ICSPDAT pins are used for ICSP and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ω .

Pull-up resistors, series diodes and capacitors on the ICSPCLK and ICSPDAT pins are not recommended as they can interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they must be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits, and pin input voltage high (V_{IH}) and input low (V_{IL}) requirements.

For device emulation, ensure that the Communication Channel Select (i.e., ICSPCLK/ICSPDAT pins), programmed into the device, matches the physical connections for the ICSP to the Microchip debugger/emulator tool.

For more information, refer to the [In-Circuit Serial Programming Guide](#).

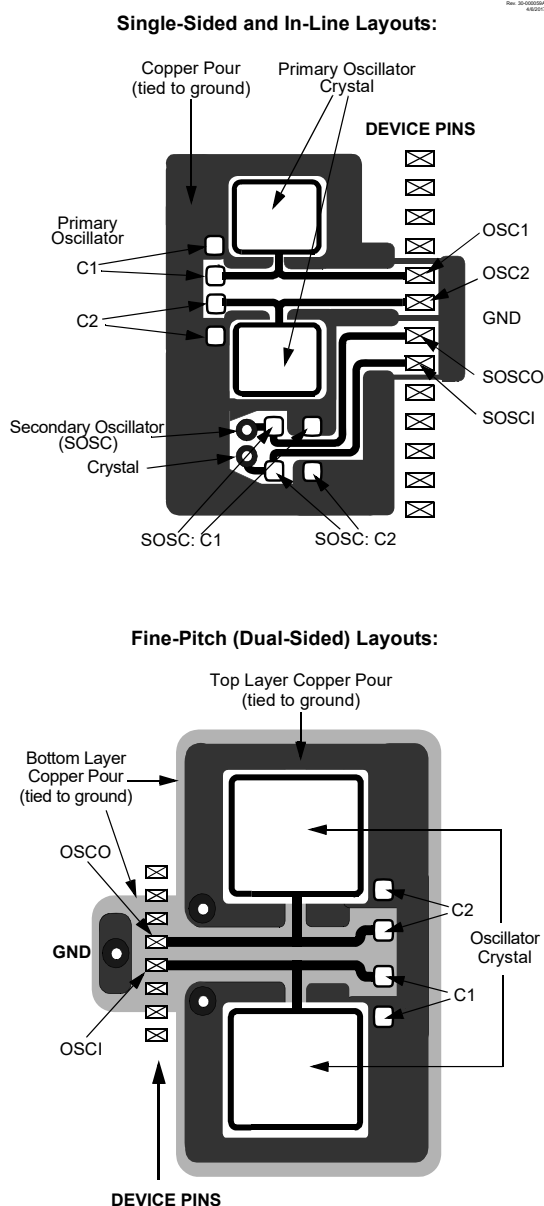
3.5 External Oscillator Pins

Many microcontrollers have options for at least two oscillators: A high-frequency primary oscillator and a low-frequency secondary oscillator.

The oscillator circuit must be placed on the same side of the board as the device. Place the oscillator circuit close to the respective oscillator pins with no more than 0.5 inch (12 mm) between the circuit components and the pins. The load capacitors must be placed next to the oscillator itself, on the same side of the board.

Use a grounded copper pour around the oscillator circuit to isolate it from surrounding circuits. The grounded copper pour may be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed.

Layout suggestions are shown in the following figure. In-line packages may be handled with a single-sided layout that completely encompasses the oscillator pins. With fine-pitch packages, it is not always possible to completely surround the pins and components. A suitable solution is to tie the broken guard sections to a mirrored ground layer. In all cases, the guard trace(s) must be returned to ground.

Figure 3-3. Suggested Placement of the Oscillator Circuit

In planning the application's routing and I/O assignments, ensure that adjacent port pins and other signals in close proximity to the oscillator are benign (i.e., free of high frequencies, short rise and fall times, and other similar noise).

For additional information and design guidance on oscillator circuits, refer to these Microchip application notes, available at the corporate website (www.microchip.com):

- AN826, "Crystal Oscillator Basics and Crystal Selection for *rfPIC™* and *PICmicro®* Devices"
- AN849, "Basic *PICmicro®* Oscillator Design"
- AN943, "Practical *PICmicro®* Oscillator Analysis and Design"
- AN949, "Making Your Oscillator Work"

Related Links

[OSC - Oscillator Module](#)

3.6 Unused I/Os

Unused I/O pins need to be configured as outputs and driven to a Logic Low state. Alternatively, connect a 1 k Ω to 10 k Ω resistor to V_{SS} on unused pins to drive the output to Logic Low.

4. Device Configuration

Device configuration consists of Configuration Words, Code Protection, Device ID and Rev ID.

4.1 Configuration Words

There are six Configuration Words that allow the user to select the device oscillator, Reset, and memory protection options. These are implemented as Configuration Word 1 through Configuration Word 6 at 300000h through 30000Bh.



Important: The $\overline{\text{DEBUG}}$ bit in Configuration Words is managed automatically by device development tools including debuggers and programmers. For normal device operation, this bit must be maintained as a '1'.

4.2 Code Protection

Code protection allows the device to be protected from unauthorized access. Program memory protection and data memory are controlled independently. Internal access to the program memory is unaffected by any code protection setting.

4.2.1 Program Memory Protection

The entire program memory space is protected from external reads and writes by the $\overline{\text{CP}}$ bit. When $\overline{\text{CP}} = 0$, external reads and writes of program memory are inhibited and a read will return all '0's. The CPU can continue to read program memory, regardless of the protection bit settings. Self-writing the program memory is dependent upon the write protection setting.

4.2.2 Data Memory Protection

The entire data EEPROM memory space is protected from external reads and writes by the $\overline{\text{CPD}}$ bit. When $\overline{\text{CPD}} = 0$, external reads and writes of data EEPROM memory are inhibited and a read will return all '0's. The CPU can continue to read data EEPROM memory regardless of the protection bit settings.

4.3 Write Protection

Write protection allows the device to be protected from unintended self-writes. Applications, such as boot loader software, can be protected while allowing other regions of the program memory to be modified.

The WRTn bits define the size of the program memory block that is protected.

4.4 User ID

256 bytes in the memory space (200000h-20000FFh) are designated as ID locations where the user can store checksum or other code identification numbers. These locations are readable and writable during normal execution. See the “**User ID, Device ID and Configuration Word Access**” section in the “**NVM - Nonvolatile Memory Control**” chapter for more information on accessing these memory locations. For more information on checksum calculation, see the “*PIC18F26/45/46Q10 Memory Programming Specification*”, (DS40001874).

4.5 Device ID and Revision ID

The 16-bit Device ID word is located at 0x3FFFE and the 16-bit revision ID is located at 0x3FFFC. These locations are read-only and cannot be erased or modified.

Development tools, such as device programmers and debuggers, may be used to read the Device ID, Revision ID and Configuration Words. Refer to the “**NVM - Nonvolatile Memory Control**” section for more information on accessing these locations.

Related Links

[NVM - Nonvolatile Memory Control](#)

4.6 Register Summary - Configuration Words

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------------------|----------|----------|------------|-------------|---------|--------------|---------|--------------|-----------|----------|--|
| 0x00 ... 0x2FFFFF | Reserved | | | | | | | | | | |
| 0x300000 | CONFIG1 | 7:0 | | RSTOSC[2:0] | | | | FEXTOSC[2:0] | | | |
| | | 15:8 | | | FCMEN | | CSWEN | | | CLKOUTEN | |
| 0x300002 | CONFIG2 | 7:0 | BOREN[1:0] | | LPBOREN | | | | PWRTE | MCLRE | |
| | | 15:8 | XINST | | DEBUG | STVREN | PPS1WAY | ZCD | BORV[1:0] | | |
| 0x300004 | CONFIG3 | 7:0 | | WDTE[1:0] | | WDTCCPS[4:0] | | | | | |
| | | 15:8 | | | | WDTCCS[2:0] | | WDTCCWS[2:0] | | | |
| 0x300006 | CONFIG4 | 7:0 | | | | | WRT3 | WRT2 | WRT1 | WRT0 | |
| | | 15:8 | | | LVP | SCANE | | WRTD | WRTB | WRTC | |
| 0x300008 | CONFIG5 | 7:0 | | | | | | | CPD | CP | |
| | | 15:8 | | | | | | | | | |
| 0x30000A | CONFIG6 | 7:0 | | | | | EBTR3 | EBTR2 | EBTR1 | EBTR0 | |
| | | 15:8 | | | | | | | EBTRB | | |

4.7 Register Definitions: Configuration Words

4.7.1 CONFIG1

Name: CONFIG1
Address: 0x300000

Configuration Word 1

Oscillators

| | | | | | | | | |
|--------|----|----|-------|----|-------|----|---|----------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | | | FCMEN | | CSWEN | | | CLKOUTEN |
| Access | | | R/W | | R/W | | | R/W |
| Reset | | | 1 | | 1 | | | 1 |

| | | | | | | | | |
|--------|---|-----|-------------|-----|---|-----|--------------|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | RSTOSC[2:0] | | | | FEXTOSC[2:0] | |
| Access | | R/W | R/W | R/W | | R/W | R/W | R/W |
| Reset | | 1 | 1 | 1 | | 1 | 1 | 1 |

Bit 13 – FCMEN Fail-Safe Clock Monitor Enable bit

| Value | Description |
|-------|----------------------------------|
| 1 | Fail-Safe Clock Monitor enabled |
| 0 | Fail-Safe Clock Monitor disabled |

Bit 11 – CSWEN Clock Switch Enable bit

| Value | Description |
|-------|---|
| 1 | Writing to NOSC and NDIV is allowed |
| 0 | The NOSC and NDIV bits cannot be changed by user software |

Bit 8 – CLKOUTEN Clock Out Enable bit

If FEXTOSC = HS, XT, LP, then this bit is ignored.
Otherwise:

| Value | Description |
|-------|---|
| 1 | CLKOUT function is disabled; I/O function on OSC2 |
| 0 | CLKOUT function is enabled; $F_{OSC}/4$ clock appears at OSC2 |

Bits 6:4 – RSTOSC[2:0] Power-up Default Value for COSC bits

This value is the Reset default value for COSC and selects the oscillator first used by user software. Refer to COSC operation.

| Value | Description |
|-------|--|
| 111 | EXTOSC operating per FEXTOSC bits (device manufacturing default) |
| 110 | HFINTOSC with HFFRQ = 4 MHz and CDIV = 4:1 |
| 101 | LFINTOSC |
| 100 | SOSC |
| 011 | Reserved |
| 010 | EXTOSC with 4x PLL, with EXTOSC operating per FEXTOSC bits |
| 001 | Reserved |
| 000 | HFINTOSC with HFFRQ = 64 MHz and CDIV = 1:1. Resets COSC/NOSC to b'110'. |

Bits 2:0 – FEXTOSC[2:0] FEXTOSC External Oscillator Mode Selection bits

| Value | Description |
|-------|--|
| 111 | ECH (external clock) above 16 MHz |
| 110 | ECM (external clock) for 500 kHz to 16 MHz |

| Value | Description |
|-------|--|
| 101 | ECL (external clock) below 500 kHz |
| 100 | Oscillator not enabled |
| 011 | Reserved (do not use) |
| 010 | HS (crystal oscillator) above 4 MHz |
| 001 | XT (crystal oscillator) above 500 kHz, below 4 MHz |
| 000 | LP (crystal oscillator) optimized for 32.768 kHz |

Related Links

[OSCFRQ](#)

OSCFRQ

[OSCCON2](#)

OSCCON2

4.7.2 CONFIG2

Name: CONFIG2

Address: 0x300002

Configuration Word 2

Supervisor

| | | | | | | | | |
|--------|--------------|----|--------------|---------------|----------------|------------|------------------|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | XINST | | DEBUG | STVREN | PPS1WAY | ZCD | BORV[1:0] | |
| Access | R/W | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | | 1 | 1 | 1 | 1 | 1 | 1 |

| | | | | | | | | |
|--------|-------------------|-----|----------------|---|---|---|--------------|--------------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | BOREN[1:0] | | LPBOREN | | | | PWRTE | MCLRE |
| Access | R/W | R/W | R/W | | | | R/W | R/W |
| Reset | 0 | 1 | 1 | | | | 1 | 1 |

Bit 15 – XINST Extended Instruction Set Enable bit

| Value | Description |
|-------|---|
| 1 | Extended Instruction Set and Indexed Addressing mode disabled (Legacy mode) |
| 0 | Extended Instruction Set and Indexed Addressing mode enabled |

Bit 13 – DEBUG Debugger Enable bit

| Value | Description |
|-------|------------------------------|
| 1 | Background debugger disabled |
| 0 | Background debugger enabled |

Bit 12 – STVREN Stack Overflow/Underflow Reset Enable bit

| Value | Description |
|-------|--|
| 1 | Stack Overflow or Underflow will cause a Reset |
| 0 | Stack Overflow or Underflow will not cause a Reset |

Bit 11 – PPS1WAY PPSLOCKED bit One-Way Set Enable bit

| Value | Description |
|-------|--|
| 1 | The PPSLOCKED bit can only be set once after an unlocking sequence is executed; once PPSLOCK is set, all future changes to PPS registers are prevented |
| 0 | The PPSLOCKED bit can be set and cleared as needed (provided an unlocking sequence is executed) |

Bit 10 – ZCD ZCD Disable bit

| Value | Description |
|-------|---|
| 1 | ZCD disabled. ZCD can be enabled by setting the ZCDSSEN bit of ZCDCON |
| 0 | ZCD always enabled, PMDx[ZCDMD] bit is ignored |

Bits 9:8 – BORV[1:0] Brown-out Reset Voltage Selection bit

| Value | Description |
|-------|--|
| 11 | Brown-out Reset Voltage (V_{BOR}) set to 1.90V |
| 10 | Brown-out Reset Voltage (V_{BOR}) set to 2.45V |
| 01 | Brown-out Reset Voltage (V_{BOR}) set to 2.7V |
| 00 | Brown-out Reset Voltage (V_{BOR}) set to 2.85V |

Bits 7:6 – BOREN[1:0] Brown-out Reset Enable bits

When enabled, Brown-out Reset Voltage (V_{BOR}) is set by BORV bit

| Value | Description |
|-------|---|
| 11 | Brown-out Reset enabled, SBOREN bit is ignored |
| 10 | Brown-out Reset enabled while running, disabled in Sleep; SBOREN is ignored |
| 01 | Brown-out Reset enabled according to SBOREN |
| 00 | Brown-out Reset disabled |

Bit 5 – LPBOREN Low-Power BOR Enable bit

| Value | Description |
|-------|---------------------------------------|
| 1 | Low-Power Brown-out Reset is disabled |
| 0 | Low-Power Brown-out Reset is enabled |

Bit 1 – PWRTS Power-up Timer Enable bit

| Value | Description |
|-------|---------------|
| 1 | PWRT disabled |
| 0 | PWRT enabled |

Bit 0 – MCLRE Master Clear (\overline{MCLR}) Enable bit

| Value | Condition | Description |
|-------|------------|---|
| x | If LVP = 1 | RE3 pin function is \overline{MCLR} |
| 1 | If LVP = 0 | \overline{MCLR} pin is \overline{MCLR} |
| 0 | If LVP = 0 | \overline{MCLR} pin function is port defined function |

Related Links

[PMD2](#)

PMD2

4.7.3 CONFIG3

Name: CONFIG3

Address: 0x300004

Configuration Word 3

Windowed Watchdog Timer

| | | | | | | | | |
|--------|----|----|-------------|-----|-----|-------------|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | | | WDTCCS[2:0] | | | WDTCWS[2:0] | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 1 | 1 | 1 | 1 | 1 | 1 |

| | | | | | | | | |
|--------|---|-----------|-----|-------------|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | WDTE[1:0] | | WDTCP5[4:0] | | | | |
| Access | | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 13:11 – WDTCCS[2:0] WDT Input Clock Selector bits

| Value | Condition | Description |
|------------|-----------|--|
| x | WDTE = 00 | These bits have no effect |
| 111 | WDTE ≠ 00 | Software Control |
| 110 to 010 | WDTE ≠ 00 | Reserved (Default to LFINTOSC) |
| 001 | WDTE ≠ 00 | WDT reference clock is the 31.25 kHz MFINTOSC |
| 000 | WDTE ≠ 00 | WDT reference clock is the 31.0 kHz LFINTOSC (default value) |

Bits 10:8 – WDTCWS[2:0] WDT Window Select bits

| WDTCWS | WDTCON1[WINDOW] at POR | | | Software Control of WINDOW | Keyed Access Required? |
|--------|------------------------|------------------------------|--------------------------------|----------------------------|------------------------|
| | Value | Window Delay Percent of Time | Window Opening Percent of Time | | |
| 111 | 111 | n/a | 100 | Yes | No |
| 110 | 110 | n/a | 100 | | |
| 101 | 101 | 25 | 75 | | |
| 100 | 100 | 37.5 | 62.5 | No | Yes |
| 011 | 011 | 50 | 50 | | |
| 010 | 010 | 62.5 | 37.5 | | |
| 001 | 001 | 75 | 25 | | |
| 000 | 000 | 87.5 | 12.5 | | |

Bits 6:5 – WDTE[1:0] WDT Operating Mode bits

| Value | Description |
|-------|--|
| 11 | WDT enabled regardless of Sleep; the SEN bit in WDTCON0 is ignored |
| 10 | WDT enabled while Sleep = 0, suspended when Sleep = 1; the SEN bit in WDTCON0 is ignored |
| 01 | WDT enabled/disabled by the SEN bit in WDTCON0 |
| 00 | WDT disabled; the SEN bit in WDTCON0 is ignored |

Bits 4:0 – WDTCP5[4:0] WDT Period Select bits

| WDTCP5 | WDTCON0[WDTP5] at POR | | | Software Control of WDTP5? | |
|--------|-----------------------|---------------|--|----------------------------|-----|
| | Value | Divider Ratio | Typical Time-Out (F _{IN} = 31 kHz) | | |
| 11111 | 01011 | 1:65536 | 2 ¹⁶ | 2s | Yes |

.....continued

| WDTCPS | WDTCN0[WDTPS] at POR | | | | Software Control of WDTPS? |
|-----------------------|-----------------------|---------------|----------|---|----------------------------|
| | Value | Divider Ratio | | Typical Time-Out ($F_{IN} = 31 \text{ kHz}$) | |
| 11110 ... 10011 | 11110 ... 10011 | 1:32 | 2^5 | 1 ms | No |
| 10010 | 10010 | 1:8388608 | 2^{23} | 256s | No |
| 10001 | 10001 | 1:4194304 | 2^{22} | 128s | |
| 10000 | 10000 | 1:2097152 | 2^{21} | 64s | |
| 01111 | 01111 | 1:1048576 | 2^{20} | 32s | |
| 01110 | 01110 | 1:524299 | 2^{19} | 16s | |
| 01101 | 01101 | 1:262144 | 2^{18} | 8s | |
| 01100 | 01100 | 1:131072 | 2^{17} | 4s | |
| 01011 | 01011 | 1:65536 | 2^{16} | 2s | |
| 01010 | 01010 | 1:32768 | 2^{15} | 1s | |
| 01001 | 01001 | 1:16384 | 2^{14} | 512 ms | |
| 01000 | 01000 | 1:8192 | 2^{13} | 256 ms | |
| 00111 | 00111 | 1:4096 | 2^{12} | 128 ms | |
| 00110 | 00110 | 1:2048 | 2^{11} | 64 ms | |
| 00101 | 00101 | 1:1024 | 2^{10} | 32 ms | |
| 00100 | 00100 | 1:512 | 2^9 | 16 ms | |
| 00011 | 00011 | 1:256 | 2^8 | 8 ms | |
| 00010 | 00010 | 1:128 | 2^7 | 4 ms | |
| 00001 | 00001 | 1:64 | 2^6 | 2 ms | |
| 00000 | 00000 | 1:32 | 2^5 | 1 ms | |

4.7.4 CONFIG4

Name: CONFIG4

Address: 0x300006

Configuration Word 4

Memory Write Protection

| | | | | | | | | |
|--------|----|----|-----|-------|----|------|------|------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | | | LVP | SCANE | | WRTD | WRTB | WRTC |
| Access | | | R/W | R/W | | R/W | R/W | R/W |
| Reset | | | 1 | 1 | | 1 | 1 | 1 |

| | | | | | | | | |
|--------|---|---|---|---|------|------|------|------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | WRT3 | WRT2 | WRT1 | WRT0 |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 1 | 1 | 1 | 1 |

Bit 13 – LVP Low-Voltage Programming Enable bit

The LVP bit cannot be written (to zero) while operating from the LVP programming interface. The purpose of this rule is to prevent the user from dropping out of LVP mode while programming from LVP mode, or accidentally eliminating LVP mode from the Configuration state.

| Value | Description |
|-------|---|
| 1 | Low-voltage programming enabled. MCLR/V _{PP} pin function is MCLR. MCLRE Configuration bit is ignored. |
| 0 | HV on MCLR/V _{PP} must be used for programming |

Bit 12 – SCANE Scanner Enable bit

| Value | Description |
|-------|--|
| 1 | Scanner module is available for use, PMD0[SCANMD] bit enables the module |
| 0 | Scanner module is NOT available for use, PMD0[SCANMD] bit is ignored |

Bit 10 – WRTD Data EEPROM Write Protection bit

| Value | Description |
|-------|---------------------------------|
| 1 | Data EEPROM NOT write-protected |
| 0 | Data EEPROM write-protected |

Bit 9 – WRTB Boot Block Write Protection bit

| Value | Description |
|-------|--------------------------------|
| 1 | Boot Block NOT write-protected |
| 0 | Boot Block write-protected |

Bit 8 – WRTC Configuration Register Write Protection bit

| Value | Description |
|-------|---|
| 1 | Configuration Registers NOT write-protected |
| 0 | Configuration Registers write-protected |

Bits 0, 1, 2, 3 – WRTn User NVM Self-Write Protection bits

| Value | Description |
|-------|--|
| 1 | Corresponding Memory Block NOT write-protected |
| 0 | Corresponding Memory Block write-protected |

Related Links

[Program Memory Organization](#)

[Operation During Code-Protect and Write-Protect](#)

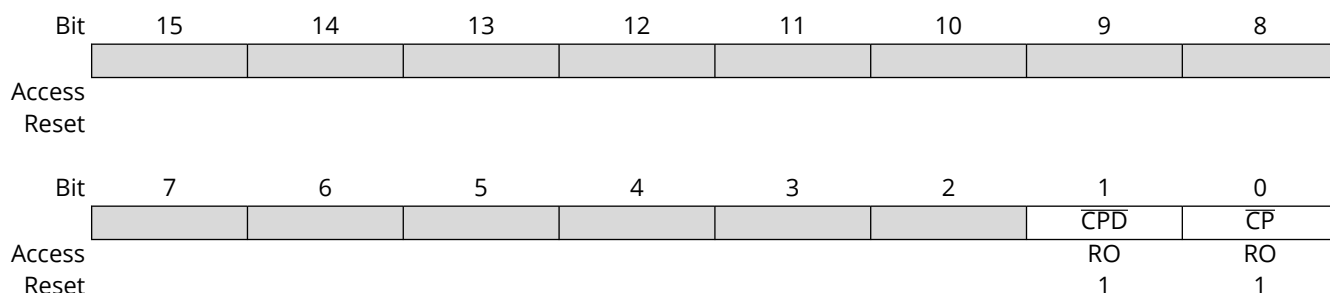
4.7.5 CONFIG5

Name: CONFIG5

Address: 0x300008

Configuration Word 5

Code Protection



Bit 1 – $\overline{\text{CPD}}$ Data NVM (DFM) Memory Code Protection bit

| Value | Description |
|-------|-----------------------------------|
| 1 | Data NVM code protection disabled |
| 0 | Data NVM code protection enabled |

Bit 0 – $\overline{\text{CP}}$ User NVM Program Memory Code Protection bit

| Value | Description |
|-------|-----------------------------------|
| 1 | User NVM code protection disabled |
| 0 | User NVM code protection enabled |

4.7.6 CONFIG6

Name: CONFIG6

Address: 0x30000A

Configuration Word 6

Memory Read Protection

| | | | | | | | | |
|--------|----|----|----|----|----|----|-------|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | | | | | | | EBTRB | |
| Access | | | | | | | R/W | |
| Reset | | | | | | | 1 | |

| | | | | | | | | |
|--------|---|---|---|---|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | EBTR3 | EBTR2 | EBTR1 | EBTR0 |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 1 | 1 | 1 | 1 |

Bit 9 – EBTRB Table Read Protection bit

| Value | Description |
|-------|---|
| 1 | Memory Boot Block not protected from table reads executed in other blocks |
| 0 | Memory Boot Block protected from table reads executed in other blocks |

Bits 0, 1, 2, 3 – EBTRn Table Read Protection bits

| Value | Description |
|-------|--|
| 1 | Corresponding Memory Block not protected from table reads executed in other blocks |
| 0 | Corresponding Memory Block protected from table reads executed in other blocks |

Related Links

[Program Memory Organization](#)

4.8 Register Summary - Device and Revision

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|-------------|----------|-------------|---|---|-------------|-------------|---|---|---|
| 0x00 ... 0x3FFFFB | Reserved | | | | | | | | | |
| 0x3FFFFC | REVISION ID | 7:0 | MJRREV[1:0] | | | MNRREV[5:0] | | | | |
| | | 15:8 | 1010[3:0] | | | | MJRREV[5:2] | | | |
| 0x3FFFFE | DEVICE ID | 7:0 | DEV[7:0] | | | | | | | |
| | | 15:8 | DEV[15:8] | | | | | | | |

4.9 Register Definitions: Device and Revision

4.9.1 DEVICE ID

Name: DEVICE ID
Address: 0x3FFFFE

Device ID Register

| | | | | | | | | |
|--------|-----------|----|----|----|----|----|----|----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | DEV[15:8] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | q | q | q | q | q | q | q | q |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | DEV[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | q | q | q | q | q | q | q | q |

Bits 15:0 – DEV[15:0]
Device ID bits

| Device | Device ID |
|-------------|-----------|
| PIC18F26Q10 | 7180h |
| PIC18F45Q10 | 7140h |
| PIC18F46Q10 | 7120h |

4.9.2 REVISION ID

Name: REVISION ID
Address: 0x3FFFC

Revision ID Register

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|-------------|----|-------------|----|-------------|----|----|----|
| | 1010[3:0] | | | | MJRREV[5:2] | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 1 | 0 | 1 | 0 | q | q | q | q |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | MJRREV[1:0] | | MNRREV[5:0] | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | q | q | q | q | q | q | q | q |

Bits 15:12 – 1010[3:0] Read as '1010'

These bits are fixed with value '1010' for all devices in this family.

Bits 11:6 – MJRREV[5:0] Major Revision ID bits

These bits are used to identify a major revision. A major revision is indicated by an all-layer revision (A0, B0, C0, etc.).

Revision A = b'00 0000'

Bits 5:0 – MNRREV[5:0] Minor Revision ID bits

These bits are used to identify a minor revision.

5. OSC - Oscillator Module

5.1 Overview

The oscillator module has multiple clock sources and selection features that allow it to be used in a wide range of applications while maximizing performance and minimizing power consumption. [Figure 5-1](#) illustrates a block diagram of the oscillator module.

Clock sources can be supplied from external oscillators, quartz-crystal resonators and ceramic resonators. In addition, the system clock source can be supplied from one of two internal oscillators and PLL circuits, with a choice of speeds selectable via software. Additional clock features include:

- Selectable system clock source between external or internal sources via software.
- Fail-Safe Clock Monitor (FSCM) designed to detect a failure of the external clock source (LP, XT, HS, ECH, ECM, ECL) and switch automatically to the internal oscillator.
- Oscillator Start-up Timer (OST) ensures stability of crystal oscillator sources.

The RSTOSC bits of Configuration Word 1 determine the type of oscillator that will be used when the device runs after Reset, including when it is first powered up.

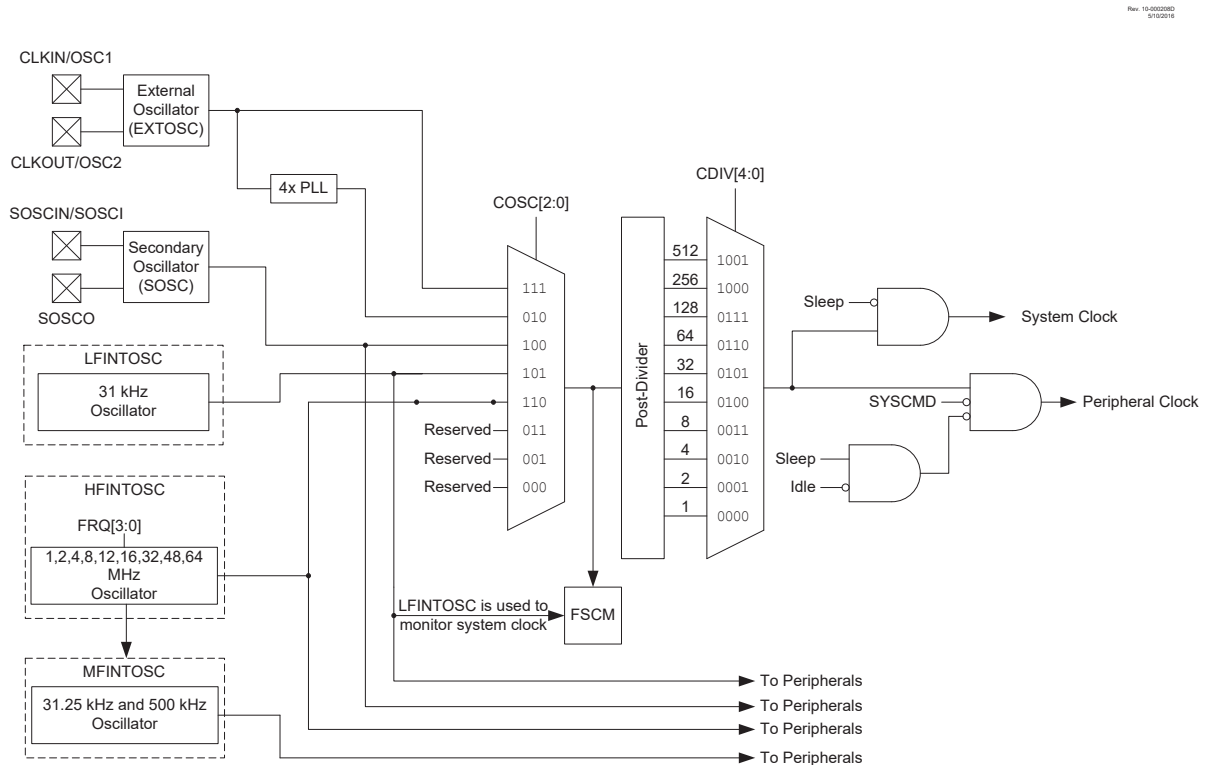
If an external clock source is selected, the FEXTOSC bits of Configuration Word 1 must be used in conjunction with the RSTOSC bits to select the External Clock mode.

The external oscillator module can be configured in one of the following clock modes, by setting the FEXTOSC[2:0] bits of Configuration Word 1:

- ECL – External Clock Low-Power mode (below 100 kHz)
- ECM – External Clock Medium Power mode (100 kHz to 16 MHz)
- ECH – External Clock High-Power mode (above 16 MHz)
- LP – 32 kHz Low-Power Crystal mode
- XT – Medium Gain Crystal or Ceramic Resonator Oscillator mode (between 500 kHz and 4 MHz)
- HS – High Gain Crystal or Ceramic Resonator mode (above 4 MHz)

The ECH, ECM, and ECL Clock modes rely on an external logic level signal as the device clock source. The LP, XT, and HS Clock modes require an external crystal or resonator to be connected to the device. Each mode is optimized for a different frequency range. The internal oscillator block produces low and high-frequency clock sources, designated LFINTOSC and HFINTOSC. Multiple device clock frequencies may be derived from these clock sources.

Figure 5-1. Simplified PIC[®] MCU Clock Source Block Diagram



Related Links

[CONFIG1](#)

CONFIG1

5.2 Clock Source Types

Clock sources can be classified as external or internal.

External clock sources rely on external circuitry for the clock source to function. Examples are: oscillator modules (ECH, ECM, ECL mode), quartz crystal resonators or ceramic resonators (LP, XT and HS modes).

Internal clock sources are contained within the oscillator module. The internal oscillator block has two internal oscillators that are used to generate internal system clock sources. The High-Frequency Internal Oscillator (HFINTOSC) can produce 1, 2, 4, 8, 12, 16, 32, 48 and 64 MHz clock. The frequency can be controlled through the OSCFRQ register. The Low-Frequency Internal Oscillator (LFINTOSC) generates a fixed 31 kHz frequency.

A 4x PLL is provided that can be used in conjunction with the external clock.

The system clock can be selected between external or internal clock sources via the [NOSC](#) bits. The system clock can be made available on the OSC2/CLKOUT pin for any of the modes that do not use the OSC2 pin. The clock out functionality is governed by the [CLKOUTEN](#) bit in the CONFIG1H register. If enabled, the clock out signal is always at a frequency of $F_{OSC}/4$.

Related Links

[OSCFRQ](#)

[OSCFRQ](#)

[4x PLL](#)

[Clock Switching](#)

5.2.1 External Clock Sources

An external clock source can be used as the device system clock by performing one of the following actions:

- Program the RSTOSC[2:0] and FEXTOSC[2:0] bits in the Configuration Words to select an external clock source that will be used as the default system clock upon a device Reset.
- Write the [NOSC\[2:0\]](#) and [NDIV\[3:0\]](#) bits to switch the system clock source.

Related Links

[Clock Switching](#)

5.2.1.1 EC Mode

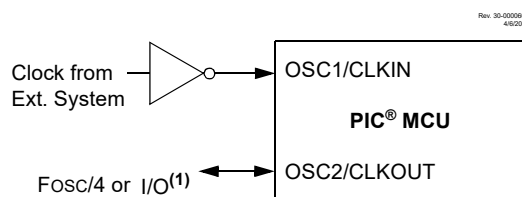
The External Clock (EC) mode allows an externally generated logic level signal to be the system clock source. When operating in this mode, an external clock source is connected to the OSC1 input. OSC2/CLKOUT is available for general purpose I/O or CLKOUT. The following figure shows the pin connections for EC mode.

EC mode has three power modes to select from through Configuration Words:

- ECH – High power, above 16 MHz
- ECM – Medium power, 100 kHz to 16 MHz
- ECL – Low power, below 100 kHz

The Oscillator Start-up Timer (OST) is disabled when EC mode is selected. Therefore, there is no delay in operation after a Power-on Reset (POR) or wake-up from Sleep. Because the PIC® MCU design is fully static, stopping the external clock input will have the effect of halting the device while leaving all data intact. Upon restarting the external clock, the device will resume operation as if no time had elapsed.

Figure 5-2. External Clock (EC) Mode Operation



Note:

1. Output depends upon $\overline{\text{CLKOUTEN}}$ bit of the Configuration Words (CONFIG1H).

5.2.1.2 LP, XT, HS Modes

The LP, XT and HS modes support the use of quartz crystal resonators or ceramic resonators connected to OSC1 and OSC2 ([Figure 5-3](#)). The three modes select a low, medium or high gain setting of the internal inverter-amplifier to support various resonator types and speed.

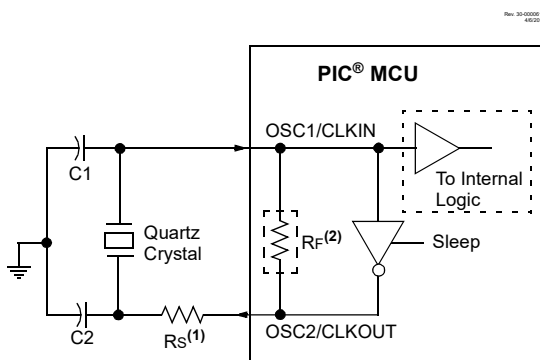
LP Oscillator mode selects the lowest gain setting of the internal inverter-amplifier. LP mode current consumption is the least of the three modes. This mode is designed to drive only 32.768 kHz tuning-fork type crystals (watch crystals).

XT Oscillator mode selects the intermediate gain setting of the internal inverter-amplifier. XT mode current consumption is the medium of the three modes. This mode is best suited to drive resonators with a medium drive level specification (between 100 kHz - 4 MHz).

HS Oscillator mode selects the highest gain setting of the internal inverter-amplifier. HS mode current consumption is the highest of the three modes. This mode is best suited for resonators that require a high drive setting (above 4 MHz).

Figure 5-3 and Figure 5-4 show typical circuits for quartz crystal and ceramic resonators, respectively.

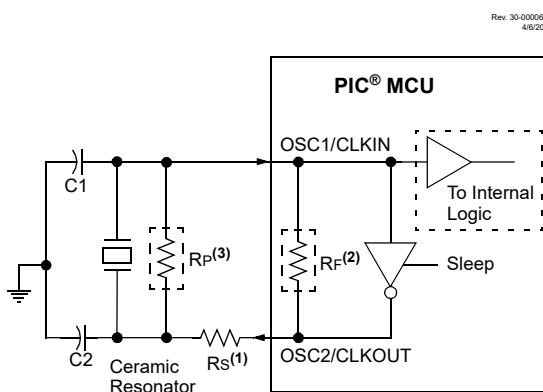
Figure 5-3. Quartz Crystal Operation (LP, XT or HS Mode)



Notes:

1. A series resistor (R_S) may be required for quartz crystals with low drive level.
2. The value of R_F varies with the Oscillator mode selected (typically between 2 M Ω to 10 M Ω).

Figure 5-4. Ceramic Resonator Operation (XT or HS Mode)



Notes:

1. A series resistor (R_S) may be required for ceramic resonators with low drive level.
2. The value of R_F varies with the Oscillator mode selected (typically between 2 M Ω to 10 M Ω).
3. An additional parallel feedback resistor (R_P) may be required for proper ceramic resonator operation.

5.2.1.3 Oscillator Start-up Timer (OST)

If the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) counts 1024 oscillations from OSC1. This occurs following a Power-on Reset (POR), or a wake-up

from Sleep. The OST ensures that the oscillator circuit, using a quartz crystal resonator or ceramic resonator, has started and is providing a stable system clock to the oscillator module.

5.2.1.4 4x PLL

The oscillator module contains a 4x PLL that can be used with the external clock sources to provide a system clock source. The input frequency for the PLL must fall within specifications.

The PLL can be enabled for use by one of two methods:

1. Program the RSTOSC bits in the Configuration Word 1 to '010' (enable EXTOSC with 4x PLL).
2. Write the **NOSC** bits to '010' (enable EXTOSC with 4x PLL).

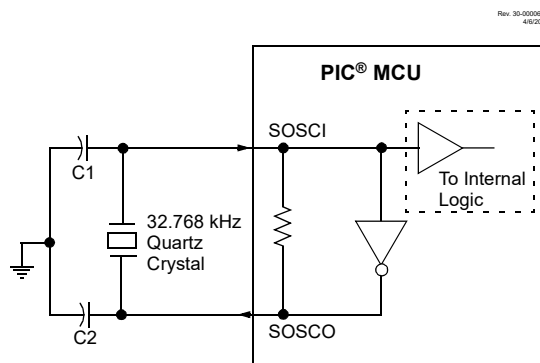
Related Links

[PLL Specifications](#)

5.2.1.5 Secondary Oscillator

The secondary oscillator is a separate oscillator block that can be used as an alternate system clock source. The secondary oscillator is optimized for 32.768 kHz, and can be used with an external crystal oscillator connected to the SOSCI and SOSCO device pins, or an external clock source connected to the SOSCIN pin. The secondary oscillator can be selected during run-time using clock switching.

Figure 5-5. Quartz Crystal Operation (Secondary Oscillator)



Related Links

[Clock Switching](#)

5.2.2 Internal Clock Sources

The device may be configured to use the internal oscillator block as the system clock by performing one of the following actions:

- Program the RSTOSC[2:0] bits in Configuration Words to select the INTOSC clock as the default system clock upon a device Reset.
- Write the **NOSC[2:0]** bits to switch the system clock source to the internal oscillator during run-time.

In INTOSC mode, OSC1/CLKIN is available for general purpose I/O. OSC2/CLKOUT is available for general purpose I/O or CLKOUT.

The function of the OSC2/CLKOUT pin is determined by the $\overline{\text{CLKOUTEN}}$ bit in Configuration Words.

The internal oscillator block has two independent oscillators that can produce two internal system clock sources.

1. The **HFINTOSC** (High-Frequency Internal Oscillator) is factory-calibrated and operates from 1 to 64 MHz. The frequency of HFINTOSC can be selected through the OSCFRQ Frequency Selection register, and fine-tuning can be done via the OSCTUNE register.
2. The **LFINTOSC** (Low-Frequency Internal Oscillator) is factory-calibrated and operates at 31 kHz.

Related Links

[Clock Switching](#)

[OSCFRQ](#)

OSCFRQ

[OSCTUNE](#)

OSCTUNE

5.2.2.1 HFINTOSC

The High-Frequency Internal Oscillator (HFINTOSC) is a precision digitally-controlled internal clock source that produces a stable clock up to 64 MHz. The HFINTOSC can be enabled through one of the following methods:

- Programming the RSTOSC bits in Configuration Word 1 to '110' ($F_{OSC} = 1 \text{ MHz}$) or '000' ($F_{OSC} = 64 \text{ MHz}$) to set the oscillator upon device Power-up or Reset.
- Write to the NOSC bits during run-time.

The HFINTOSC frequency can be selected by setting the HFFRQ bits.

The NDIV bits allow for division of the HFINTOSC output from a range between 1:1 and 1:512.

Related Links

[Clock Switching](#)

5.2.2.2 MFINTOSC

The module provides two (500 kHz and 31.25 kHz) constant clock outputs. These clocks are digital divisors of the HFINTOSC clock. Dynamic divider logic is used to provide constant MFINTOSC clock rates for all settings of HFINTOSC.

The MFINTOSC cannot be used to drive the system but it is used to clock certain modules such as the Timers and WWDT.

5.2.2.3 LFINTOSC

The Low-Frequency Internal Oscillator (LFINTOSC) is a factory-calibrated 31 kHz internal clock source.

The LFINTOSC is the frequency for the Power-up Timer (PWRT), Windowed Watchdog Timer (WWDT) and Fail-Safe Clock Monitor (FSCM).

The LFINTOSC is enabled through one of the following methods:

- Programming the RSTOSC[2:0] bits of Configuration Word 1 to enable LFINTOSC.
- Write to the [NOSC\[2:0\]](#) bits during run-time.

Related Links

[Clock Switching](#)

5.2.2.4 ADCRC (also referred to as FRC)

The ADCRC is an oscillator dedicated to the ADCC module. The ADCRC oscillator can be manually enabled using the [ADOEN](#) bit. The ADCRC runs at a fixed frequency of 600 kHz. ADCRC is automatically enabled if it is selected as the clock source for the ADCC module.

5.2.3 Oscillator Status and Adjustments

5.2.3.1 Internal Oscillator Frequency Adjustment

The internal oscillator is factory-calibrated. This internal oscillator can be adjusted in software by writing to the OSCTUNE register.

OSCTUNE does not affect the LFINTOSC frequency. Operation of features that depend on the LFINTOSC clock source frequency, such as the Power-up Timer (PWRT), WWDT, Fail-Safe Clock Monitor (FSCM) and peripherals, are not affected by the change in frequency.

The default value of the OSCTUNE register is 00h. The value is a 6-bit two's complement number. A value of 1Fh will provide an adjustment to the maximum frequency. A value of 20h will provide an adjustment to the minimum frequency.

When the OSCTUNE register is modified, the oscillator frequency will begin shifting to the new frequency. Code execution continues during this shift. There is no indication that the shift has occurred.

Related Links

[OSCTUNE](#)

OSCTUNE

5.2.3.2 Oscillator Status and Manual Enable

The Ready status of each oscillator (including the ADCRC oscillator) is displayed in OSCSTAT. The oscillators (but not the PLL) may be explicitly enabled through OSCEN.

Related Links

[OSCSTAT](#)

OSCSTAT

[OSCEN](#)

OSCEN

5.2.3.3 HFOR and MFOR Bits

The [HFOR](#) and [MFOR](#) bits indicate that the HFINTOSC and MFINTOSC is ready. These clocks are always valid for use at all times, but only accurate after they are ready.

When a new value is loaded into the OSCFRQ register, the HFOR and MFOR bits will clear, and set again when the oscillator is ready. During pending OSCFRQ changes the MFINTOSC clock will stall at a high or a low state, until the HFINTOSC resumes operation.

5.3 Clock Switching

The system clock source can be switched between external and internal clock sources via software using the New Oscillator Source ([NOSC](#)) bits. The following clock sources can be selected using the following:

- External oscillator
- Internal Oscillator Block (INTOSC)



Important: The Clock Switch Enable bit in Configuration Word 1 can be used to enable or disable the clock switching capability. When cleared, the [NOSC](#) and [NDIV](#) bits cannot be changed by user software. When set, writing to NOSC and NDIV is allowed and switches the clock frequency.

5.3.1 New Oscillator Source (NOSC) and New Divider Selection Request (NDIV) Bits

The New Oscillator Source (NOSC) and New Divider Selection Request (NDIV) bits select the system clock source and frequency that are used for the CPU and peripherals.

When new values of **NOSC** and **NDIV** are written to OSCCON1, the current oscillator selection will continue to operate while waiting for the new clock source to indicate that it is stable and ready. In some cases, the newly requested source may already be in use, and is ready immediately. In the case of a divider-only change, the new and old sources are the same, so the source will be ready immediately. The device may enter Sleep while waiting for the switch.

When the new oscillator is ready, the New Oscillator Ready (**NOSCR**) bit is set and also the Clock Switch Interrupt Flag (CSWIF) bit of PIR1 sets. If Clock Switch Interrupts are enabled (CSWIE = 1), an interrupt will be generated at that time. The Oscillator Ready (**ORDY**) bit can also be polled to determine when the oscillator is ready in lieu of an interrupt.



Important: The CSWIF interrupt will not wake the system from Sleep.

If the Clock Switch Hold (**CSWHOLD**) bit is clear, the oscillator switch will occur when the New Oscillator is Ready bit (**NOSCR**) is set, and the interrupt (if enabled) will be serviced at the new oscillator setting.

If **CSWHOLD** is set, the oscillator switch is suspended, while execution continues using the current (old) clock source. When the **NOSCR** bit is set, software will:

- Set **CSWHOLD** = 0 so the switch can complete, or
- Copy **COSC** into **NOSC** to abandon the switch.

If DOZE is in effect, the switch occurs on the next clock cycle, whether or not the CPU is operating during that cycle.

Changing the clock post-divider without changing the clock source (i.e., changing F_{OSC} from 1 MHz to 2 MHz) is handled in the same manner as a clock source change, as described previously. The clock source will already be active, so the switch is relatively quick. **CSWHOLD** must be clear (**CSWHOLD** = 0) for the switch to complete.

The current **COSC** and **CDIV** are indicated in the OSCCON2 register up to the moment when the switch actually occurs, at which time **OSCCON2** is updated and **ORDY** is set. **NOSCR** is cleared by hardware to indicate that the switch is complete.

Related Links

[Clock Switch and Sleep](#)

5.3.2 PLL Input Switch

Switching between the PLL and any non-PLL source is managed as described above. The input to the PLL is established when **NOSC** selects the PLL, and maintained by the **COSC** setting.

When **NOSC** and **COSC** select the PLL with different input sources, the system continues to run using the **COSC** setting, and the new source is enabled per **NOSC**. When the new oscillator is ready (and **CSWHOLD** = 0), system operation is suspended while the PLL input is switched and the PLL acquires lock. This provides a truly glitch-free clock switch operation.



Important: If the PLL fails to lock, the FSCM will trigger.

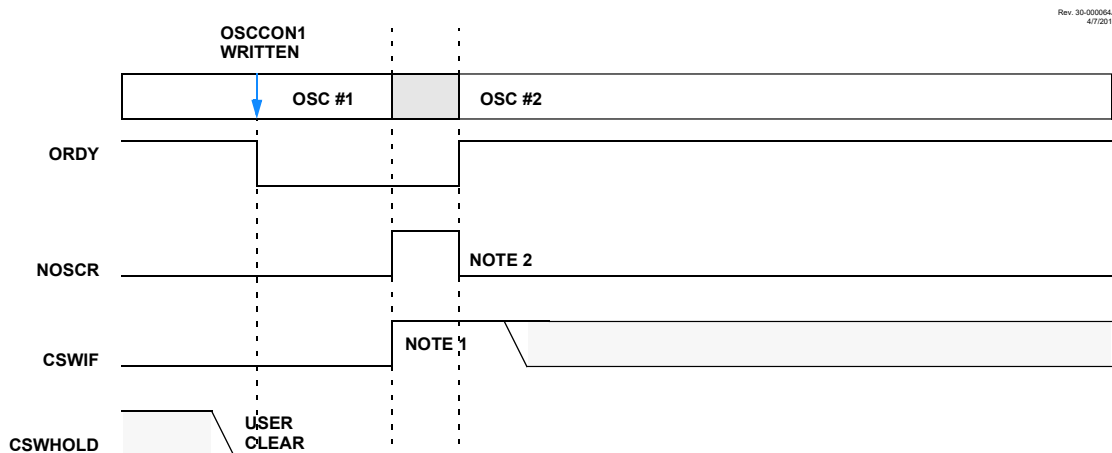
5.3.3 Clock Switch and Sleep

If OSCCON1 is written with a new value and the device is put to Sleep before the switch completes, the switch will not take place and the device will enter Sleep mode.

When the device wakes from Sleep and the CSWHOLD bit is clear, the device will wake with the 'new' clock active, and the Clock Switch Interrupt Flag (CSWIF) bit will be set.

When the device wakes from Sleep and the CSWHOLD bit is set, the device will wake with the 'old' clock active and the new clock will be requested again.

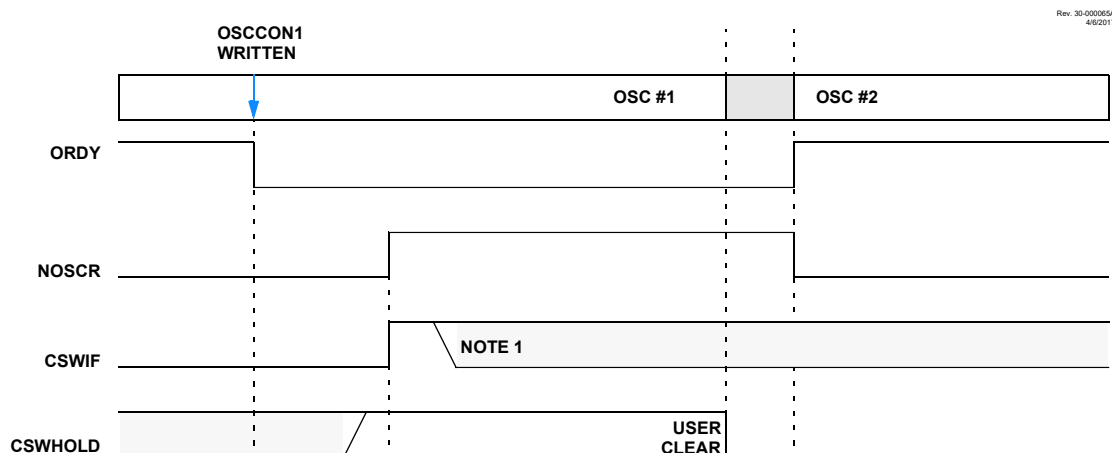
Figure 5-6. Clock Switch (CSWHOLD = 0)



Notes:

1. CSWIF is asserted coincident with NOSCR; interrupt is serviced at OSC #2 speed.
2. The assertion of NOSCR is hidden from the user because it appears only for the duration of the switch.

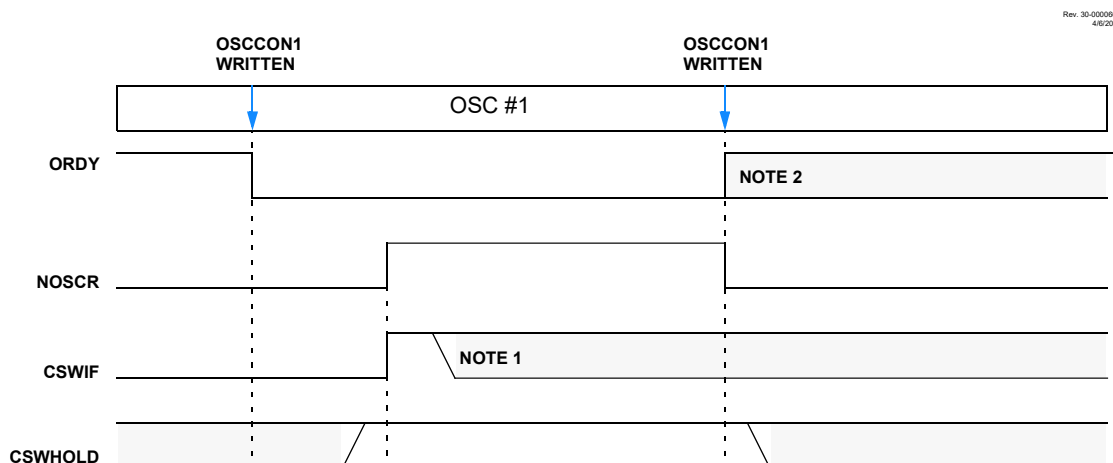
Figure 5-7. Clock Switch (CSWHOLD = 1)



Note:

1. CSWIF is asserted coincident with **NOSCR**, and may be cleared before or after clearing CSWHOLD = 0.

Figure 5-8. Clock Switch Abandoned



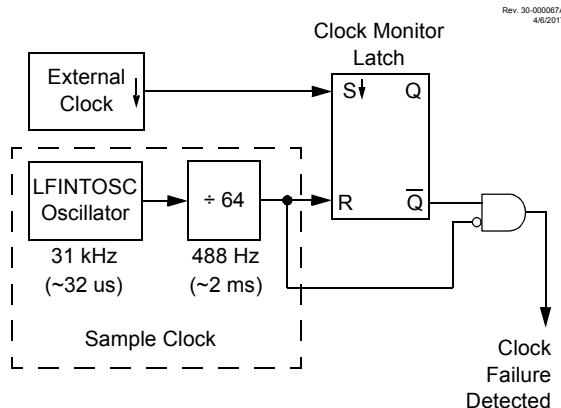
Notes:

1. CSWIF may be cleared before or after rewriting OSCCON1; CSWIF is not automatically cleared.
2. ORDY = 0 if OSCCON1 does not match OSCCON2; a new switch will begin.

5.4 Fail-Safe Clock Monitor

The Fail-Safe Clock Monitor (FSCM) allows the device to continue operating if the external oscillator fails. The FSCM is enabled by setting the FCMEN bit in the Configuration Word 1. The FSCM is applicable to all external Oscillator modes (LP, XT, HS, ECL/M/H and Secondary Oscillator).

Figure 5-9. FSCM Block Diagram



5.4.1 Fail-Safe Detection

The FSCM module detects a failed oscillator by comparing the external oscillator to the FSCM sample clock. The sample clock is generated by dividing the LFINTOSC by 64. See Figure 5-9. Inside the fail detector block is a latch. The external clock sets the latch on each falling edge of the external clock. The sample clock clears the latch on each rising edge of the sample clock. A failure is detected when an entire half-cycle of the sample clock elapses before the external clock goes low.

5.4.2 Fail-Safe Operation

When the external clock fails, the FSCM overwrites the COSC bits to select HFINTOSC (3'b110). The frequency of HFINTOSC is determined by the previous state of the HFFRQ bits and the NDIV/CDIV bits. The bit flag OSCFIF of the PIR1 register is set. Setting this flag will generate an interrupt if the OSCFIE bit of the PIE1 register is also set. The device firmware can then take steps to mitigate the

problems that may arise from a failed clock. The system clock will continue to be sourced from the internal clock source until the device firmware successfully restarts the external oscillator and switches back to external operation, by writing to the NOSC and NDIV bits.

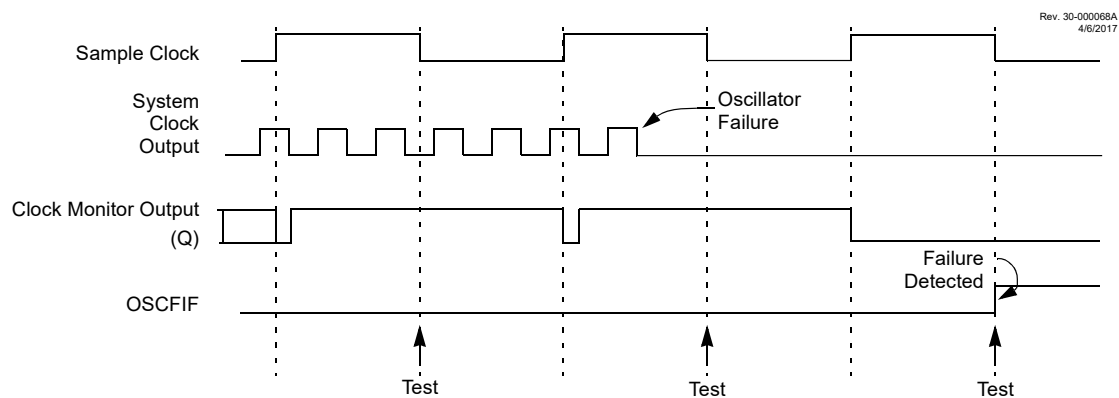
5.4.3 Fail-Safe Condition Clearing

The Fail-Safe condition is cleared after a Reset, executing a `SLEEP` instruction or changing the NOSC and NDIV bits of the OSCCON1 register. When switching to the external oscillator or external oscillator with PLL, the OST is restarted. While the OST is running, the device continues to operate from the INTOSC selected in OSCCON1. When the OST times out, the Fail-Safe condition is cleared after successfully switching to the external clock source. The OSFIF bit must be cleared prior to switching to the external clock source. If the Fail-Safe condition still exists, the OSFIF flag will again be set by hardware.

5.4.4 Reset or Wake-up from Sleep

The FSCM is designed to detect an oscillator failure after the Oscillator Start-up Timer (OST) has expired. The OST is used after waking up from Sleep and after any type of Reset. The OST is not used with the EC Clock modes so that the FSCM will be active as soon as the Reset or wake-up has completed. Therefore, the device will always be executing code while the OST is operating when using one of the EC modes.

Figure 5-10. FSCM Timing Diagram



Note: The system clock is normally at a much higher frequency than the sample clock. The relative frequencies in this example have been chosen for clarity.

5.5 Register Summary - OSC

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|----------|----------|---------|---------|-----------|-------|------------|------------|---|------|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0ED2 | | | | | | | | | | |
| 0x0ED3 | OSCCON1 | 7:0 | | | NOSC[2:0] | | | NDIV[3:0] | | |
| 0x0ED4 | OSCCON2 | 7:0 | | | COSC[2:0] | | | CDIV[3:0] | | |
| 0x0ED5 | OSCCON3 | 7:0 | CSWHOLD | SOSCPWR | | ORDY | NOSCR | | | |
| 0x0ED6 | OSCSTAT | 7:0 | EXTOR | HFOR | MFOR | LFOR | SOR | ADOR | | PLLR |
| 0x0ED7 | OSCEN | 7:0 | EXTOEN | HFOEN | MFOEN | LFOEN | SOSCEN | ADOEN | | |
| 0x0ED8 | OSCTUNE | 7:0 | | | | | HFTUN[5:0] | | | |
| 0x0ED9 | OSCFRQ | 7:0 | | | | | | HFFRQ[3:0] | | |

5.6 Register Definitions: Oscillator Control

5.6.1 OSCCON1

Name: OSCCON1
Address: 0xED3

Oscillator Control Register1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|-----------|-----|-----|-----------|-----|-----|-----|
| | | NOSC[2:0] | | | NDIV[3:0] | | | |
| Access | | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | f | f | f | f | f | f | f |

Bits 6:4 – NOSC[2:0] New Oscillator Source Request bits^(1,2,3)

The setting requests a source oscillator and PLL combination per [Table 5-2](#).

Table 5-1. Default Oscillator Settings

| CONFIG1[RSTOSC] | SFR Reset Values (fff ffff) | | | Initial F _{OSC} Frequency |
|-----------------|-----------------------------|-----------|--------|------------------------------------|
| | NOSC/COSC | NDIV/CDIV | OSCFRQ | |
| 111 | 111 | 0000 | 4 MHz | EXTOSC per FEXTOSC |
| 110 | 110 | 0010 | | F _{OSC} = 1 MHz (4 MHz/4) |
| 101 | 101 | 0000 | | LFINTOSC |
| 100 | 100 | 0000 | | SOSC |
| 011 | Reserved | | | |
| 010 | 010 | 0000 | 4 MHz | EXTOSC + 4xPLL ⁽⁴⁾ |
| 001 | Reserved | | | |
| 000 | 110 | 0000 | 64 MHz | F _{OSC} = 64 MHz |

Table 5-2. NOSC Bit Settings

| NOSC[2:0] | Clock Source |
|-----------|--------------------------------|
| 111 | EXTOSC ⁽⁵⁾ |
| 110 | HFINTOSC ⁽⁶⁾ |
| 101 | LFINTOSC |
| 100 | SOSC |
| 011 | Reserved |
| 010 | EXTOSC + 4x PLL ⁽⁷⁾ |
| 001 | Reserved |
| 000 | Reserved |

Bits 3:0 – NDIV[3:0] New Divider Selection Request bits^(2,3)

The setting determines the new postscaler division ratio per [Table 5-3](#).

Table 5-3. NDIV Bit Settings

| NDIV[3:0] | Clock Divider |
|-----------|---------------|
| 1111-1010 | Reserved |
| 1001 | 512 |
| 1000 | 256 |
| 0111 | 128 |
| 0110 | 64 |
| 0101 | 32 |
| 0100 | 16 |
| 0011 | 8 |
| 0010 | 4 |
| 0001 | 2 |
| 0000 | 1 |

Notes:

1. The default value (f/f) is determined by the CONFIG1[RSTOSC] Configuration bits. See [Table 5-1](#).
2. If NOSC is written with a reserved value ([Table 5-2](#)), the operation is ignored and NOSC is not written.
3. When CONFIG1[CSWEN] = 0, this register is read-only and cannot be changed from the POR value.
4. EXTOSC must meet the PLL specifications.
5. EXTOSC configured by CONFIG1[FEXTOSC].
6. HFINTOSC frequency is set with the [HFFRQ](#) bits.
7. EXTOSC must meet the PLL specifications.

Related Links

[CONFIG1](#)

[CONFIG1](#)

[PLL Specifications](#)

5.6.2 OSCCON2

Name: OSCCON2

Address: 0xED4

Oscillator Control Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|-----------|---|---|-----------|---|---|---|
| | | COSC[2:0] | | | CDIV[3:0] | | | |
| Access | | R | R | R | R | R | R | R |
| Reset | | q | q | q | q | q | q | q |

Bits 6:4 – COSC[2:0] Current Oscillator Source Select bits (read-only)^(1,2)

Indicates the current source oscillator and PLL combination as shown in the following table.

Table 5-4. COSC Bit Settings

| COSC/NOSC | Clock Source |
|-----------|--------------------------------|
| 111 | EXTOSC ⁽³⁾ |
| 110 | HFINTOSC ⁽⁴⁾ |
| 101 | LFINTOSC |
| 100 | SOSC |
| 011 | Reserved |
| 010 | EXTOSC + 4x PLL ⁽⁵⁾ |
| 001 | Reserved |
| 000 | Reserved |

Bits 3:0 – CDIV[3:0] Current Divider Select bits (read-only)^(1,2)

Indicates the current postscaler division ratio as shown in the following table.

Table 5-5. CDIV Bit Settings

| CDIV/NDIV | Clock Divider |
|-----------|---------------|
| 1111-1010 | Reserved |
| 1001 | 512 |
| 1000 | 256 |
| 0111 | 128 |
| 0110 | 64 |
| 0101 | 32 |
| 0100 | 16 |
| 0011 | 8 |
| 0010 | 4 |
| 0001 | 2 |
| 0000 | 1 |

Notes:

1. The POR value is the value present when user code execution begins.
2. The Reset value (q/q) is the same as the [NOSC/NDIV](#) bits.
3. EXTOSC configured by the CONFIG1[FEXTOSC] bits.
4. HFINTOSC frequency is set with the [HFFRQ](#) bits.
5. EXTOSC must meet the PLL specifications.

Related Links

[CONFIG1](#)

[CONFIG1](#)

[PLL Specifications](#)

5.6.3 OSCCON3

Name: OSCCON3
Address: 0xED5

Oscillator Control Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---|------|-------|---|---|---|
| | CSWHOLD | SOSCPWR | | ORDY | NOSCR | | | |
| Access | R/W/HC | R/W | | RO | RO | | | |
| Reset | 0 | 1 | | 0 | 0 | | | |

Bit 7 – CSWHOLD Clock Switch Hold bit

| Value | Description |
|-------|---|
| 1 | Clock switch will hold (with interrupt) when the oscillator selected by NOSC is ready |
| 0 | Clock switch may proceed when the oscillator selected by NOSC is ready; when NOSCR becomes '1', the switch will occur |

Bit 6 – SOSCPWR Secondary Oscillator Power Mode Select bit

| Value | Description |
|-------|---|
| 1 | Secondary oscillator operating in High Power mode |
| 0 | Secondary oscillator operating in Low Power mode |

Bit 4 – ORDY Oscillator Ready bit (read-only)

| Value | Description |
|-------|--|
| 1 | OSCCON1 = OSCCON2; the current system clock is the clock specified by NOSC |
| 0 | A clock switch is in progress |

Bit 3 – NOSCR New Oscillator is Ready bit (read-only)⁽¹⁾

| Value | Description |
|-------|---|
| 1 | A clock switch is in progress and the oscillator selected by NOSC indicates a Ready condition |
| 0 | A clock switch is not in progress, or the NOSC-selected oscillator is not yet ready |

Note:

1. If CSWHOLD = 0, the user may not see this bit set because the bit is set for less than one instruction cycle.

5.6.4 OSCSTAT

Name: OSCSTAT
Address: 0xED6

Oscillator Status Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|------|------|------|-----|------|---|------|
| | EXTOR | HFOR | MFOR | LFOR | SOR | ADOR | | PLLR |
| Access | RO | RO | RO | RO | RO | RO | | RO |
| Reset | q | q | q | q | q | q | | q |

Bit 7 – EXTOR EXTOSC (external) Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 6 – HFOR HFINTOSC Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 5 – MFOR MFINTOSC Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 4 – LFOR LFINTOSC Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 3 – SOR Secondary (Timer1) Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 2 – ADOR ADC Oscillator Ready bit

| Value | Description |
|-------|---|
| 1 | The oscillator is ready to be used |
| 0 | The oscillator is not enabled, or is not yet ready to be used |

Bit 0 – PLLR PLL Ready bit

| Value | Description |
|-------|--|
| 1 | The PLL is ready to be used |
| 0 | The PLL is not enabled, the required input source is not ready, or the PLL is not locked |

5.6.5 OSCFRQ

Name: OSCFRQ
Address: 0xED9

HFINTOSC Frequency Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|------------|-----|-----|-----|
| | | | | | HFFRQ[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | q | q | q | q |

Bits 3:0 – HFFRQ[3:0] HFINTOSC Frequency Selection bits

| HFFRQ | Nominal Freq (MHz) |
|---------------------|--------------------|
| 1001 | Reserved |
| 1010 | |
| 1111 | |
| 1110 | |
| 1101 | |
| 1100 | |
| 1011 | |
| 1000 ⁽¹⁾ | |
| | 64 |
| 0111 | 48 |
| 0110 | 32 |
| 0101 | 16 |
| 0100 | 12 |
| 0011 | 8 |
| 0010 ⁽¹⁾ | 4 |
| 0001 | 2 |
| 0000 | 1 |

Note:

1. Refer to [Table 5-1](#) for more information.

5.6.6 OSCTUNE

Name: OSCTUNE
Address: 0xED8

HFINTOSC Tuning Register

| | | | | | | | | |
|--------|---|---|------------|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | HFTUN[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 5:0 – HFTUN[5:0] HFINTOSC Frequency Tuning bits

| Value | Description |
|---------|---|
| 01 1111 | Maximum frequency |
| 00 0000 | Center frequency. Oscillator module is running at the calibrated frequency (default value). |
| 10 0000 | Minimum frequency |

5.6.7 OSCEN

Name: OSCEN
Address: 0xED7

Oscillator Manual Enable Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|-------|-------|--------|-------|---|---|
| | EXTOEN | HFOEN | MFOEN | LFOEN | SOSCEN | ADOEN | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | | |

Bit 7 – EXTOEN External Oscillator Manual Request Enable bit

| Value | Description |
|-------|--|
| 1 | EXTOSC is explicitly enabled, operating as specified by CONFIG1[FEXTOSC] |
| 0 | EXTOSC is only enabled if requested by a peripheral |

Bit 6 – HFOEN HFINTOSC Oscillator Manual Request Enable bit

| Value | Description |
|-------|--|
| 1 | HFINTOSC is explicitly enabled, operating as specified by OSCFRQ |
| 0 | HFINTOSC is only enabled if requested by a peripheral |

Bit 5 – MFOEN MFINTOSC (500 kHz/31.25 kHz) Oscillator Manual Request Enable bit (Derived from HFINTOSC)

| Value | Description |
|-------|---|
| 1 | MFINTOSC is explicitly enabled |
| 0 | MFINTOSC is only enabled if requested by a peripheral |

Bit 4 – LFOEN LFINTOSC (31 kHz) Oscillator Manual Request Enable bit

| Value | Description |
|-------|---|
| 1 | LFINTOSC is explicitly enabled |
| 0 | LFINTOSC is only enabled if requested by a peripheral |

Bit 3 – SOSCEN Secondary Oscillator Manual Request Enable bit

| Value | Description |
|-------|---|
| 1 | Secondary Oscillator is explicitly enabled, operating as specified by SOSCPWR |
| 0 | Secondary Oscillator is only enabled if requested by a peripheral |

Bit 2 – ADOEN ADC Oscillator Manual Request Enable bit

| Value | Description |
|-------|---|
| 1 | ADC oscillator is explicitly enabled |
| 0 | ADC oscillator is only enabled if requested by a peripheral |

6. REFCLK - Reference Clock Output Module

The reference clock output (REFCLK) module provides the ability to send a clock signal to the clock reference output pin (CLKR). The reference clock output can also be routed internally as a signal for other peripherals, such as the Data Signal Modulator (DSM), memory scanner, and timer module.

The reference clock output module has the following features:

- Selectable Clock Source Using the CLKRCLK Register
- Programmable Clock Divider
- Selectable Duty Cycle

Figure 6-1. Clock Reference Block Diagram

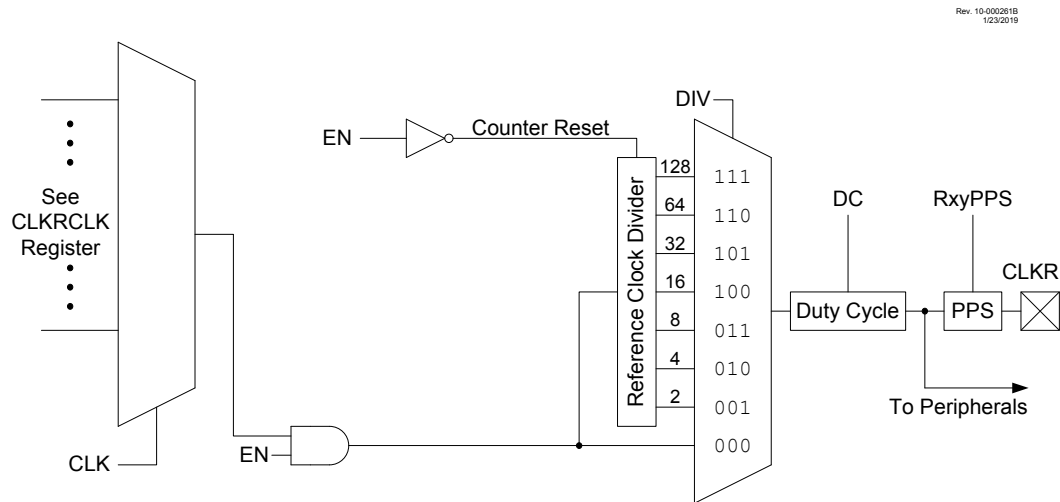
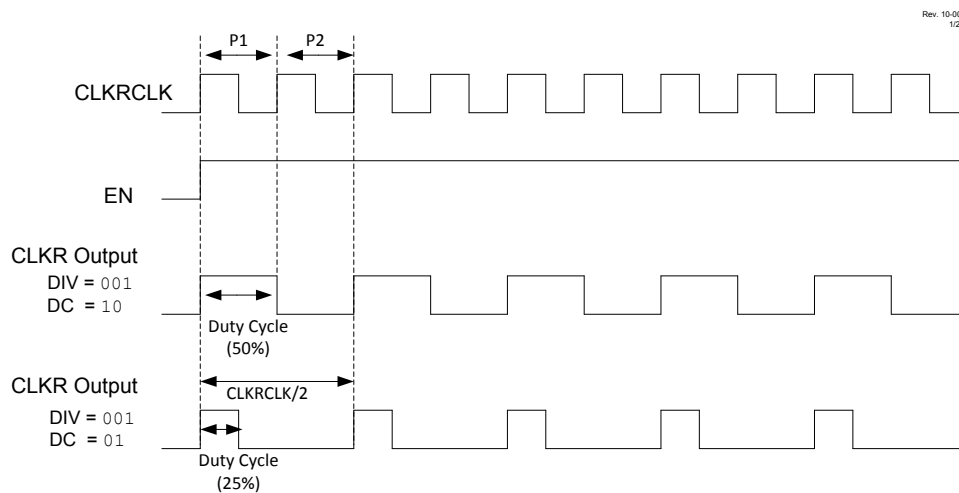


Figure 6-2. Clock Reference Timing



6.1 Clock Source

The clock source of the reference clock peripheral is selected with the **CLK** bits in the CLKRCLK register. The available clock sources are listed below:

- CLCs
- NCO
- Secondary oscillator
- MFINTOSC
- LFINTOSC
- F_{OSC}

6.1.1 Clock Synchronization

The CLKR output signal is ensured to be glitch-free when the **EN** bit in the CLKRCON register is set to start the module and enable the CLKR output.

When the reference clock output is disabled, the output signal will be disabled immediately.

Clock dividers and clock duty cycles can be changed while the module is enabled, but doing so may cause glitches to occur on the output. To avoid possible glitches, clock dividers and clock duty cycles may be changed only when the **EN** bit is clear.

6.2 Programmable Clock Divider

The module takes the clock input and divides it based on the value of the **DIV** bits.

The following configurations are available:

- Base F_{OSC} value
- F_{OSC} divided by 2
- F_{OSC} divided by 4
- F_{OSC} divided by 8
- F_{OSC} divided by 16
- F_{OSC} divided by 32
- F_{OSC} divided by 64
- F_{OSC} divided by 128

The clock divider values can be changed while the module is enabled. However, to prevent glitches on the output, the **DIV** bits may be only changed when the module is disabled (**EN** = 0).

6.3 Selectable Duty Cycle

The **DC** bits in the CLKRCON register are used to modify the duty cycle of the output clock. A duty cycle of 0%, 25%, 50%, or 75% can be selected for all clock rates when the **DIV** value is not 000. When **DIV** = 000, the duty cycle defaults to 50% for all values of **DC** except 00, in which case the duty cycle is 0% (constant low output).



Important: The **DC** value at Reset is 10. This makes the default duty cycle 50% and not 0%.



Important: Clock dividers and clock duty cycles can be changed while the module is enabled but doing so may cause glitches to occur on the output. To avoid possible glitches, clock dividers and clock duty cycles may be changed only when the module is disabled ($EN = 0$).

6.4 Operation in Sleep Mode

The reference clock module continues to operate and provide a signal output in Sleep for all clock source selections except F_{OSC} ($CLK = 0$).

6.5 Register Summary - Reference CLK

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|----|---|---|---------|----------|----------|---|---|
| 0x00 ... 0x0F38 | Reserved | | | | | | | | | |
| 0x0F39 | CLKRCON | 7:0 | EN | | | DC[1:0] | | DIV[2:0] | | |
| 0x0F3A | CLKRCLK | 7:0 | | | | | CLK[3:0] | | | |

6.6 Register Definitions: Reference Clock

Related Links

[Long Bit Names](#)

6.6.1 CLKRCON

Name: CLKRCON
Address: 0xF39

Reference Clock Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|---|---------|-----|----------|-----|-----|
| | EN | | | DC[1:0] | | DIV[2:0] | | |
| Access | R/W | | | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | | | 1 | 0 | 0 | 0 | 0 |

Bit 7 – EN

Reference Clock Module Enable bit

| Value | Description |
|-------|------------------------------------|
| 1 | Reference clock module enabled |
| 0 | Reference clock module is disabled |

Bits 4:3 – DC[1:0]

Reference Clock Duty Cycle bits⁽¹⁾

| Value | Description |
|-------|---------------------------------|
| 11 | Clock outputs duty cycle of 75% |
| 10 | Clock outputs duty cycle of 50% |
| 01 | Clock outputs duty cycle of 25% |
| 00 | Clock outputs duty cycle of 0% |

Bits 2:0 – DIV[2:0]

Reference Clock Divider bits

| Value | Description |
|-------|---------------------------------|
| 111 | Base clock value divided by 128 |
| 110 | Base clock value divided by 64 |
| 101 | Base clock value divided by 32 |
| 100 | Base clock value divided by 16 |
| 011 | Base clock value divided by 8 |
| 010 | Base clock value divided by 4 |
| 001 | Base clock value divided by 2 |
| 000 | Base clock value |

Note:

- Bits are valid for reference clock divider values of two or larger, the base clock cannot be further divided.

6.6.2 CLKRCLK

Name: CLKRCLK

Address: 0xF3A

Clock Reference Clock Selection MUX

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | CLK[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – CLK[3:0] CLKR Clock Selection bits

Table 6-1. CLKR Clock Sources

| CLK | Clock Source |
|-----------|--------------------|
| 1111 | LC8_out |
| 1110 | LC7_out |
| 1101 | LC6_out |
| 1100 | LC5_out |
| 1011 | LC4_out |
| 1010 | LC3_out |
| 1001 | LC2_out |
| 1000 | LC1_out |
| 0111-0101 | 0101 |
| 0100 | SOSC |
| 0011 | MFINTOSC (500 kHz) |
| 0010 | LFINTOSC (31 kHz) |
| 0001 | HFINTOSC |
| 0000 | F _{osc} |

7. Power-Saving Operation Modes

The purpose of the Power-Down modes is to reduce power consumption. There are three Power-Down modes:

- Doze mode
- Idle mode
- Sleep mode

7.1 Doze Mode

Doze mode allows for power-saving by reducing CPU operation and program memory (PFM) access, without affecting peripheral operation. Doze mode differs from Sleep mode because the band gap and system oscillators continue to operate, while only the CPU and PFM are affected. The reduced execution saves power by eliminating unnecessary operations within the CPU and memory.

When the Doze Enable bit is set ($DOZEN = 1$), the CPU executes only one instruction cycle out of every N cycles as defined by the $DOZE$ bits. For example, if $DOZE = 001$, the instruction cycle ratio is 1:4. The CPU and memory execute for one instruction cycle and then lay Idle for three instruction cycles. During the unused cycles, the peripherals continue to operate at the system clock speed.

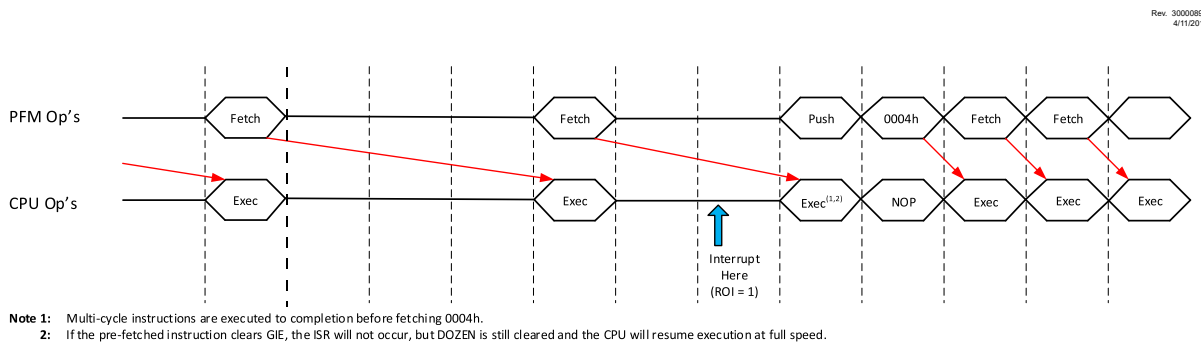
7.1.1 Doze Operation

The Doze operation is illustrated in Figure 7-1. For this example:

- Doze enabled ($DOZEN = 1$)
- $DOZE = 001$ (1:4) ratio
- Recover-on-Interrupt enabled ($ROI = 1$)

As with normal operation, the PFM fetches for the next instruction cycle. The Q-clocks to the peripherals continue throughout.

Figure 7-1. DOZE MODE OPERATION EXAMPLE ($DOZE[2:0] = 001$, 1:4)



7.1.2 Interrupts During Doze

If an interrupt occurs and the Recover-On-Interrupt bit is clear ($ROI = 0$) at the time of the interrupt, the Interrupt Service Routine (ISR) continues to execute at the rate selected by $DOZE[2:0]$. Interrupt latency is extended by the $DOZE[2:0]$ ratio.

If an interrupt occurs and the ROI bit is set ($ROI = 1$) at the time of the interrupt, the $DOZEN$ bit is cleared and the CPU executes at full speed. The prefetched instruction is executed and then the interrupt vector sequence is executed. In Figure 7-1, the interrupt occurs during the 2nd instruction cycle of the Doze period, and immediately brings the CPU out of Doze. If the Doze-On-Exit (DOE) bit is set ($DOE = 1$) when the RETFIE operation is executed, $DOZEN$ is set, and the CPU executes at the reduced rate based on the $DOZE[2:0]$ ratio.

Example 7-1. Doze Software

```
//Mainline operation
bool somethingToDo = FALSE;
void main()
{
    initializeSystem();
    // DOZE = 64:1 (for example)
    // ROI = 1;
    GIE = 1; // enable interrupts
    while (1)
    {
        // If ADC completed, process data
        if (somethingToDo)
        {
            doSomething();
            DOZEN = 1; // resume low-power
        }
    }
    // Data interrupt handler
    void interrupt()
    {
        // DOZEN = 0 because ROI = 1
        if (ADIF)
        {
            somethingToDo = TRUE;
            DOE = 0; // make main() go fast
            ADIF = 0;
        }
        // else check other interrupts...
        if (TMR0IF)
        {
            timerTick++;
            DOE = 1; // make main() go slow
            TMR0IF = 0;
        }
    }
}
```

7.2 Sleep Mode

Sleep mode is entered by executing the `SLEEP` instruction, while the Idle Enable (IDLEN) bit of the `CPUDOZE` register is cleared (IDLEN = 0). If the `SLEEP` instruction is executed while the IDLEN bit is set (IDLEN = 1), the CPU will enter the Idle mode.

Upon entering Sleep mode, the following conditions exist:

1. Resets other than WDT are not affected by Sleep mode; WDT will be cleared but keeps running if enabled for operation during Sleep.
2. The \overline{PD} bit of the STATUS register is cleared.
3. The \overline{TO} bit of the STATUS register is set.
4. The CPU and the System clocks are disabled.
5. 31 kHz LFINTOSC, HFINTOSC and SOSC will remain enabled if any peripheral has requested them as a clock source or if the HFOEN, LFOEN, or SOSCEN bits of the OSCEN register are set.
6. ADC is unaffected if the FRC oscillator is selected. When the ADC clock is something other than FRC, a `SLEEP` instruction causes the present conversion to be aborted and the ADC module is turned off, although the ADON bit remains active.
7. I/O ports maintain the status they had before `SLEEP` was executed (driving high, low, or high-impedance) only if no peripheral connected to the I/O port is active.

Refer to individual chapters for more details on peripheral operation during Sleep.

To minimize current consumption, consider the following conditions:

- I/O pins must not be floating

- External circuitry sinking current from I/O pins
- Internal circuitry sourcing current from I/O pins
- Current draw from pins with internal weak pull-ups
- Modules using any oscillator

I/O pins that are high-impedance inputs need to be pulled to V_{DD} or V_{SS} externally to avoid switching currents caused by floating inputs.

Examples of internal circuitry that might be sourcing current include modules such as the DAC and FVR modules.

Related Links

[DAC - 5-Bit Digital-to-Analog Converter](#)

[FVR - Fixed Voltage Reference](#)

7.2.1 Wake-up from Sleep

The device can wake up from Sleep through one of the following events:

1. External Reset input on \overline{MCLR} pin, if enabled.
2. BOR Reset, if enabled.
3. Low-Power Brown-Out Reset (LPBOR), if enabled.
4. POR Reset.
5. Windowed Watchdog Timer, if enabled.
6. All interrupt sources except clock switch interrupt can wake up the part.

The first five events will cause a device Reset. The last one event is considered a continuation of program execution. To determine whether a device Reset or wake-up event occurred, refer to the “**Determining the Cause of a Reset**” section.

When the `SLEEP` instruction is being executed, the next instruction ($PC + 2$) is prefetched. For the device to wake up through an interrupt event, the corresponding Interrupt Enable bit must be enabled, as well as the Peripheral Interrupt Enable bit ($PEIE = 1$), for every interrupt not in `PIR0`. Wake-up will occur regardless of the state of the `GIE` bit. If the `GIE` bit is disabled, the device continues execution at the instruction after the `SLEEP` instruction. If the `GIE` bit is enabled, the device executes the instruction after the `SLEEP` instruction, the device will then call the Interrupt Service Routine. In cases where the execution of the instruction following `SLEEP` is not desirable, the user will have a `NOP` after the `SLEEP` instruction.

The WDT is cleared when the device wakes up from Sleep, regardless of the source of wake-up.

Upon a wake from a Sleep event, the core will wait for a combination of three conditions before beginning execution. The conditions are:

- PFM Ready
- COSC-selected Oscillator Ready
- BOR Ready (unless BOR is disabled)

Related Links

[Determining the Cause of a Reset](#)

7.2.2 Wake-up Using Interrupts

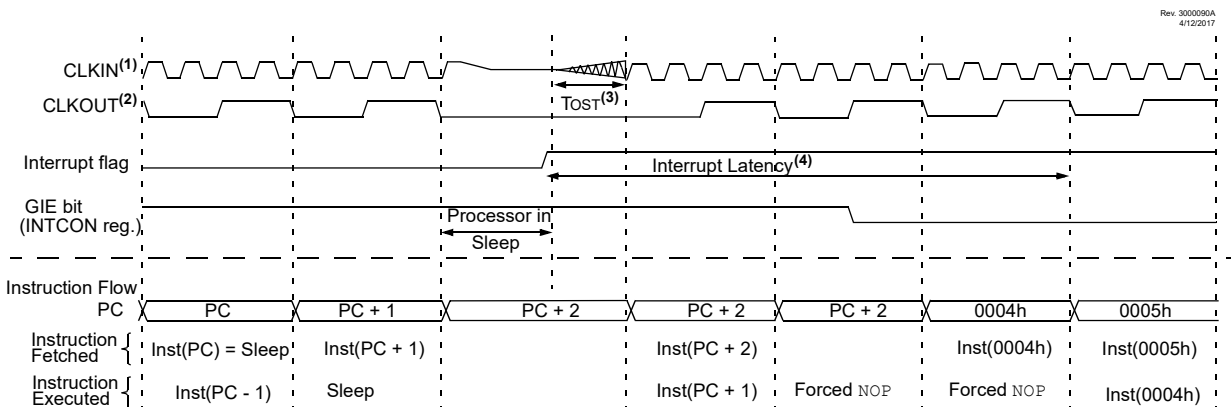
When global interrupts are disabled (`GIE` cleared) and any interrupt source, with the exception of the clock switch interrupt, has both its interrupt enable bit and interrupt flag bit set, one of the following will occur:

- If the interrupt occurs before the execution of a `SLEEP` instruction

- The `SLEEP` instruction will execute as a `NOP`
- WDT and WDT prescaler will not be cleared
- The \overline{TO} bit of the STATUS register will not be set
- The \overline{PD} bit of the STATUS register will not be cleared
- If the interrupt occurs during or after the execution of a `SLEEP` instruction
 - The `SLEEP` instruction will be completely executed
 - Device will immediately wake up from Sleep
 - WDT and WDT prescaler will be cleared
 - The \overline{TO} bit of the STATUS register will be set
 - The \overline{PD} bit of the STATUS register will be cleared

Even if the flag bits were checked before executing a `SLEEP` instruction, it may be possible for flag bits to become set before the `SLEEP` instruction completes. To determine whether a `SLEEP` instruction executed, test the \overline{PD} bit. If the \overline{PD} bit is set, the `SLEEP` instruction was executed as a `NOP`.

Figure 7-2. Wake-up From Sleep Through Interrupt



Notes:

1. External clock. High, Medium, Low mode assumed.
2. CLKOUT is shown here for timing reference.
3. $T_{OST} = 1024 T_{OSC}$. This delay does not apply to EC and INTOSC Oscillator modes.
4. $GIE = 1$ assumed. In this case after wake-up, the processor calls the ISR at 0004h. If $GIE = 0$, execution will continue in-line.

7.2.3 Low-Power Sleep Mode

The PIC18F26/45/46Q10 device family contains an internal Low Dropout (LDO) voltage regulator, which allows the device I/O pins to operate at voltages up to 5.5V while the internal device logic operates at a lower voltage. The LDO and its associated reference circuitry must remain active when the device is in Sleep mode.

The PIC18F26/45/46Q10 devices allows the user to optimize the operating current in Sleep, depending on the application requirements.

Low-Power Sleep mode can be selected by setting the `VREGPM` bit of the `VREGCON` register.

7.2.3.1 Sleep Current vs. Wake-up Time

In the default operating mode, the LDO and reference circuitry remain in the normal configuration while in Sleep. The device is able to exit Sleep mode quickly since all circuits remain active. In

Low-Power Sleep mode, when waking-up from Sleep, an extra delay time is required for these circuits to return to the normal configuration and stabilize.

The Low-Power Sleep mode is beneficial for applications that stay in Sleep mode for long periods of time. The Normal mode is beneficial for applications that need to wake from Sleep quickly and frequently.

7.2.3.2 Peripheral Usage in Sleep

Some peripherals that can operate in Sleep mode will not operate properly with the Low-Power Sleep mode selected. The Low-Power Sleep mode is intended for use with these peripherals:

- Brown-out Reset (BOR)
- Windowed Watchdog Timer (WWDT)
- External interrupt pin/Interrupt-On-Change pins
- Peripherals that run off external secondary clock source

It is the responsibility of the end user to determine what is acceptable for their application when setting the VREGPM settings in order to ensure operation in Sleep.

7.3 Idle Mode

When IDLEN is set (IDLEN = 1), the `SLEEP` instruction will put the device into Idle mode. In Idle mode, the CPU and memory operations are halted, but the peripheral clocks continue to run. This mode is similar to Doze mode, except that in IDLE both the CPU and PFM are shut off.



Important: If `CLKOUTEN` is enabled (`CLKOUTEN` = 0, Configuration Word 1H), the output will continue operating while in Idle.

7.3.1 Idle and Interrupts

Idle mode ends when an interrupt occurs (even if GIE = 0), but IDLEN is not changed. The device can re-enter Idle by executing the `SLEEP` instruction.

If Recover-on-Interrupt is enabled (ROI = 1), the interrupt that brings the device out of Idle also restores full-speed CPU execution when Doze is also enabled.

7.3.2 Idle and WWDT

When in Idle, the WWDT Reset is blocked and will instead wake the device. The WWDT wake-up is not an interrupt, therefore ROI does not apply.



Important: The WWDT can bring the device out of Idle, in the same way it brings the device out of Sleep. The DOZEN bit is not affected.

7.4 Peripheral Operation in Power-Saving Modes

All selected clock sources and the peripherals running off them are active in both IDLE and DOZE mode. Only in Sleep mode, both the F_{OSC} and $F_{OSC}/4$ clocks are unavailable. All the other clock sources are active, if enabled manually or through peripheral clock selection before the part enters Sleep.

7.5 Register Summary - Power Savings Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------|----------|----------|-------|-------|------------|-----|---|-----------|-------------|---|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0ED1 | | | | | | | | | | |
| 0x0ED2 | CPUDOZE | 7:0 | IDLEN | DOZEN | ROI | DOE | | DOZE[2:0] | | |
| 0x0ED3 ... | Reserved | | | | | | | | | |
| 0x0ED9 | | | | | | | | | | |
| 0x0EDA | VREGCON | 7:0 | | | PMSYS[1:0] | | | | VREGPM[1:0] | |

7.6 Register Definitions: Power Savings Control

7.6.1 VREGCON

Name: VREGCON
Address: 0xEDA

Note:

1. System and peripheral inputs should not exceed 500 kHz in ULP mode.

Voltage Regulator Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|------------|----|---|---|-------------|-----|
| | | | PMSYS[1:0] | | | | VREGPM[1:0] | |
| Access | | | RO | RO | | | R/W | R/W |
| Reset | | | g | g | | | 1 | 0 |

Bits 5:4 – PMSYS[1:0] System Power Mode Status bits

| Value | Description |
|-------|-------------------------------------|
| 11 | Reserved |
| 10 | ULP regulator is active |
| 01 | Main regulator in LP mode is active |
| 00 | Main regulator in HP mode is active |

Bits 1:0 – VREGPM[1:0] Voltage Regulator Power Mode Selection bit

| Value | Description |
|-------|------------------------------|
| 11 | Reserved. Do not use. |
| 10 | ULP regulator ⁽¹⁾ |
| 01 | Main regulator in LP mode |
| 00 | Main regulator in HP mode |

7.6.2 CPUDOZE

Name: CPUDOZE
Address: 0xED2

Doze and Idle Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-----------|-----|-----|---|-----------|-----|-----|
| | IDLEN | DOZEN | ROI | DOE | | DOZE[2:0] | | |
| Access | R/W | R/W/HC/HS | R/W | R/W | | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | | 0 | 0 | 0 |

Bit 7 – IDLEN Idle Enable bit

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | A SLEEP instruction inhibits the CPU clock, but not the peripheral clock(s) |
| 0 | A SLEEP instruction places the device into full Sleep mode |

Bit 6 – DOZEN

Doze Enable bit⁽¹⁾

| Value | Description |
|-------|--|
| 1 | The CPU executes instruction cycles according to DOZE setting |
| 0 | The CPU executes all instruction cycles (fastest, highest power operation) |

Bit 5 – ROI Recover-On-Interrupt bit

| Value | Description |
|-------|--|
| 1 | Entering the Interrupt Service Routine (ISR) makes DOZEN = 0, bringing the CPU to full-speed operation |
| 0 | Interrupt entry does not change DOZEN |

Bit 4 – DOE Doze-On-Exit bit

| Value | Description |
|-------|---|
| 1 | Executing RETFIE makes DOZEN = 1, bringing the CPU to reduced speed operation |
| 0 | RETFIE does not change DOZEN |

Bits 2:0 – DOZE[2:0] Ratio of CPU Instruction Cycles to Peripheral Instruction Cycles

| Value | Description |
|-------|-------------|
| 111 | 1:256 |
| 110 | 1:128 |
| 101 | 1:64 |
| 100 | 1:32 |
| 011 | 1:16 |
| 010 | 1:8 |
| 001 | 1:4 |
| 000 | 1:2 |

Note:

- When ROI = 1 or DOE = 1, DOZEN is changed by hardware interrupt entry and/or exit.

8. PMD - Peripheral Module Disable

The PIC18F26/45/46Q10 devices provide the ability to disable selected modules, placing them into the lowest possible Power mode.



Important: For legacy reasons, all modules are ON by default following any Reset.

8.1 Disabling a Module

A peripheral can be disabled by setting the corresponding peripheral disable bit in the [PMDx](#) register. Disabling a module has the following effects:

- All clock and control inputs to the module are suspended; there are no logic transitions, and the module will not function
- The module is held in Reset
 - Writing to the SFRs is disabled
 - Reading returns 0x00
- Analog outputs are disabled; digital outputs read as '0'

Related Links

[I/O Priorities](#)

8.2 Enabling a Module

When the register bit is cleared, the module is re-enabled and will be in its Reset state; SFR data will reflect the POR Reset values. Depending on the module, it may take up to one full instruction cycle for the module to become active.



Important: There must be no interaction with the module (e.g., writing to registers) for at least one instruction after it has been re-enabled.

8.3 Register Summary - PMD

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------------------|----------|---------|---------|---------|---------|--------|--------|--------|--------|
| 0x00 ... 0x0EDB | Reserved | | | | | | | | | |
| 0x0EDC | PMD0 | 7:0 | SYSCMD | FVRMD | HLVDMD | CRCMD | SCANMD | NVMMD | CLKRMD | IOCMD |
| 0x0EDD | PMD1 | 7:0 | | TMR6MD | TMR5MD | TMR4MD | TMR3MD | TMR2MD | TMR1MD | TMR0MD |
| 0x0EDE | PMD2 | 7:0 | | DACMD | ADCMD | | | CMP2MD | CMP1MD | ZCDMD |
| 0x0EDF | PMD3 | 7:0 | CLC8MD | CLC7MD | CLC6MD | CLC5MD | PWM4MD | PWM3MD | CCP2MD | CCP1MD |
| 0x0EE0 | PMD4 | 7:0 | UART2MD | UART1MD | MSSP2MD | MSSP1MD | | | | CWG1MD |
| 0x0EE1 | PMD5 | 7:0 | CLC4MD | CLC3MD | CLC2MD | CLC1MD | | | | DSMMD |

8.4 Register Definitions: Peripheral Module Disable

8.4.1 PMD0

Name: PMD0
Address: 0xEDC

PMD Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|--------|-------|--------|-------|--------|-------|
| | SYSCMD | FVRMD | HLVDMD | CRCMD | SCANMD | NVMMD | CLKRMD | IOCMD |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – SYSCMD Disable Peripheral System Clock Network bit
Disables the System clock network⁽¹⁾

| Value | Description |
|-------|---|
| 1 | System clock network disabled (F_{OSC}) |
| 0 | System clock network enabled |

Bit 6 – FVRMD Disable Fixed Voltage Reference bit

| Value | Description |
|-------|---------------------|
| 1 | FVR module disabled |
| 0 | FVR module enabled |

Bit 5 – HLVDMD Disable High-Low-Voltage Detect bit

| Value | Description |
|-------|----------------------|
| 1 | HLVD module disabled |
| 0 | HLVD module enabled |

Bit 4 – CRCMD Disable CRC Engine bit

| Value | Description |
|-------|---------------------|
| 1 | CRC module disabled |
| 0 | CRC module enabled |

Bit 3 – SCANMD Disable NVM Memory Scanner bit
Disables the Scanner module⁽²⁾

| Value | Description |
|-------|---------------------------------|
| 1 | NVM Memory Scan module disabled |
| 0 | NVM Memory Scan module enabled |

Bit 2 – NVMMD NVM Module Disable bit
Disables the NVM module⁽³⁾

| Value | Description |
|-------|--|
| 1 | All Memory reading and writing is disabled; NVMCON registers cannot be written |
| 0 | NVM module enabled |

Bit 1 – CLKRMD Disable Clock Reference bit

| Value | Description |
|-------|----------------------|
| 1 | CLKR module disabled |
| 0 | CLKR module enabled |

Bit 0 – IOCMD Disable Interrupt-on-Change bit, All Ports

| Value | Description |
|-------|------------------------|
| 1 | IOC module(s) disabled |
| 0 | IOC module(s) enabled |

Notes:

1. Clearing the SYSCMD bit disables the system clock (F_{OSC}) to peripherals, however peripherals clocked by $F_{OSC}/4$ are not affected.
2. Subject to SCANE bit in *Configuration Word 4*.
3. When enabling NVM, a delay of up to 1 μ s is required before accessing data.

Related Links[CONFIG4](#)

CONFIG4

8.4.2 PMD1

Name: PMD1
Address: 0xEDD

PMD Control Register 1

| | | | | | | | | |
|--------|---|--------|--------|--------|--------|--------|--------|--------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | TMR6MD | TMR5MD | TMR4MD | TMR3MD | TMR2MD | TMR1MD | TMR0MD |
| Access | | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6 – TMRnMD Disable Timer n bit

| Value | Description |
|-------|----------------------|
| 1 | TMRn module disabled |
| 0 | TMRn module enabled |

8.4.3 PMD2

Name: PMD2
Address: 0xEDE

PMD Control Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|-------|-------|---|---|--------|--------|-------|
| | | DACMD | ADCMD | | | CMP2MD | CMP1MD | ZCDMD |
| Access | | R/W | R/W | | | R/W | R/W | R/W |
| Reset | | 0 | 0 | | | 0 | 0 | 0 |

Bit 6 – DACMD Disable DAC bit

| Value | Description |
|-------|---------------------|
| 1 | DAC module disabled |
| 0 | DAC module enabled |

Bit 5 – ADCMD Disable ADC bit

| Value | Description |
|-------|---------------------|
| 1 | ADC module disabled |
| 0 | ADC module enabled |

Bits 1, 2 – CMPnMD Disable Comparator CMPn bit

| Value | Description |
|-------|----------------------|
| 1 | CMPn module disabled |
| 0 | CMPn module enabled |

Bit 0 – ZCDMD Disable Zero-Cross Detect module bit⁽¹⁾

| Value | Description |
|-------|---------------------|
| 1 | ZCD module disabled |
| 0 | ZCD module enabled |

Note:

1. Subject to $\overline{\text{ZCD}}$ bit in *Configuration Word 2*.

Related Links

[CONFIG2](#)

CONFIG2

8.4.4 PMD3

Name: PMD3
Address: 0xEDF

PMD Control Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | CLC8MD | CLC7MD | CLC6MD | CLC5MD | PWM4MD | PWM3MD | CCP2MD | CCP1MD |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 4, 5, 6, 7 – CLCnMD Disable CLCn bit

| Value | Description |
|-------|----------------------|
| 1 | CLCn module disabled |
| 0 | CLCn module enabled |

Bits 2, 3 – PWMnMD Disable PWMn bit

| Value | Description |
|-------|----------------------|
| 1 | PWMn module disabled |
| 0 | PWMn module enabled |

Bits 0, 1 – CCPnMD Disable Capture/Compare/PWMn bit

| Value | Description |
|-------|----------------------|
| 1 | CCPn module disabled |
| 0 | CCPn module enabled |

8.4.5 PMD4

Name: PMD4
Address: 0xEE0

PMD Control Register 4

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---|---|---|--------|
| | UART2MD | UART1MD | MSSP2MD | MSSP1MD | | | | CWG1MD |
| Access | R/W | R/W | R/W | R/W | | | | R/W |
| Reset | 0 | 0 | 0 | 0 | | | | 0 |

Bits 6, 7 – UARTnMD Disable EUSARTn bit

| Value | Description |
|-------|-------------------------|
| 1 | EUSARTn module disabled |
| 0 | EUSARTn module enabled |

Bits 4, 5 – MSSPnMD Disable MSSPn bit

| Value | Description |
|-------|-----------------------|
| 1 | MSSPn module disabled |
| 0 | MSSPn module enabled |

Bit 0 – CWG1MD Disable CWG1 Module bit

| Value | Description |
|-------|----------------------|
| 1 | CWG1 module disabled |
| 0 | CWG1 module enabled |

8.4.6 PMD5

Name: PMD5
Address: 0xEE1

PMD Control Register 5

| | | | | | | | | |
|--------|--------|--------|--------|--------|---|---|---|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CLC4MD | CLC3MD | CLC2MD | CLC1MD | | | | DSMMD |
| Access | R/W | R/W | R/W | R/W | | | | R/W |
| Reset | 0 | 0 | 0 | 0 | | | | 0 |

Bits 4, 5, 6, 7 – CLCnMD Disable CLCn bit

| Value | Description |
|-------|----------------------|
| 1 | CLCn module disabled |
| 0 | CLCn module enabled |

Bit 0 – DSMMD Disable DSM bit

| Value | Description |
|-------|---------------------|
| 1 | DSM module disabled |
| 0 | DSM module enabled |

9. Resets

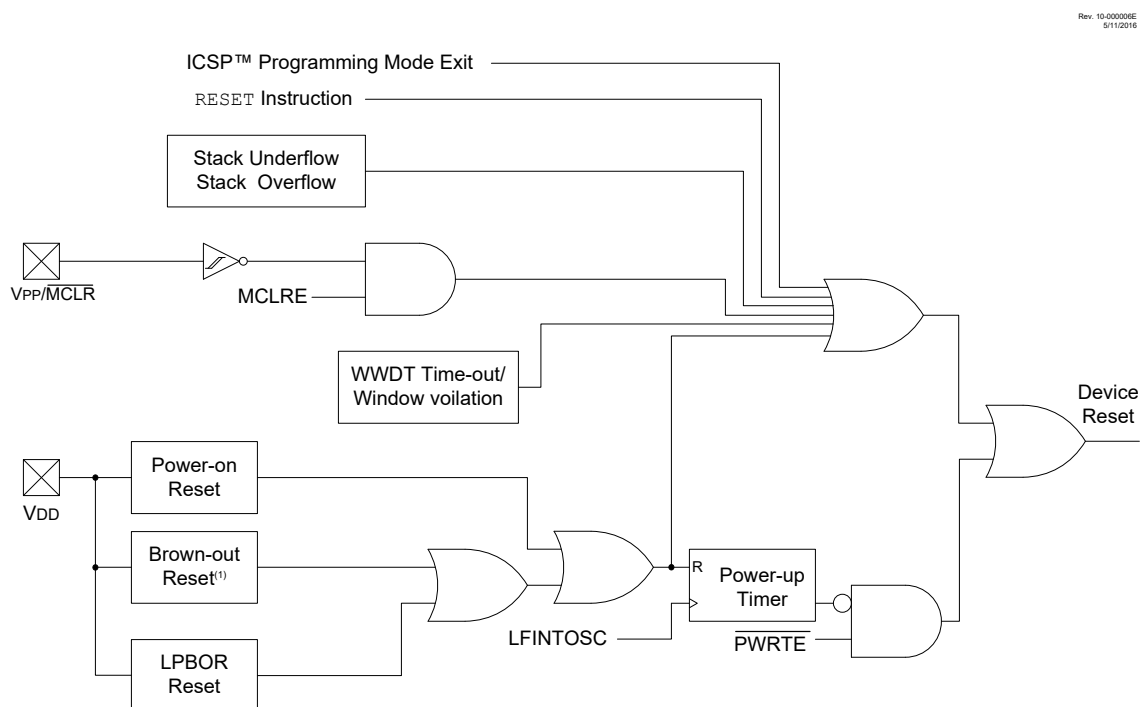
There are multiple ways to reset this device:

- Power-on Reset (POR)
- Brown-out Reset (BOR)
- Low-Power Brown-out Reset (LPBOR)
- $\overline{\text{MCLR}}$ Reset
- WDT Reset
- `RESET` instruction
- Stack Overflow
- Stack Underflow
- Programming mode Exit

To allow V_{DD} to stabilize, an optional Power-up Timer can be enabled to extend the Reset time after a BOR or POR event.

A simplified block diagram of the on-chip Reset circuit is shown in the block diagram below.

Figure 9-1. Simplified Block Diagram of On-Chip Reset Circuit



Note: See the “BOR Operating Modes” table for BOR Active conditions.

9.1 Power-on Reset (POR)

The POR circuit holds the device in Reset until V_{DD} has reached an acceptable level for minimum operation. Slow rising V_{DD} , fast operating speeds or analog performance may require greater than minimum V_{DD} . The `PWRT`, BOR or $\overline{\text{MCLR}}$ features can be used to extend the start-up period until all device operation conditions have been met.

9.2 Brown-out Reset (BOR)

The BOR circuit holds the device in Reset when V_{DD} reaches a selectable minimum level. Between the POR and BOR, complete voltage range coverage for execution protection can be implemented.

The Brown-out Reset module has four operating modes controlled by the BOREN[1:0] bits in [CONFIG2](#). The four operating modes are:

- BOR is always ON
- BOR is OFF when in Sleep
- BOR is controlled by software
- BOR is always OFF

Refer to BOR Operating Modes for more information.

The Brown-out Reset voltage level is selectable by configuring the BORV[1:0] bits in [CONFIG2](#).

A V_{DD} noise rejection filter prevents the BOR from triggering on small events. If V_{DD} falls below V_{BOR} for a duration greater than parameter T_{BORDC} , the device will reset and the BOR bit in the PCON0 register will be cleared, indicating the Brown-out Reset condition occurred. For more details, see the **“Brown-out Situations”** figure in the **“BOR Controlled by Software”** section.

Related Links

[CONFIG2](#)

[CONFIG2](#)

[Reset, WDT, Oscillator Start-up Timer, Power-up Timer, Brown-out Reset and Low-Power Brown-out Reset Specifications](#)

9.2.1 BOR Is Always ON

When the BOREN bits of Configuration Word 2 are programmed to ‘11’, the BOR is always ON. The device start-up will be delayed until the BOR is ready and V_{DD} is higher than the BOR threshold.

BOR protection is active during Sleep. The BOR does not delay wake-up from Sleep.

9.2.2 BOR Is OFF in Sleep

When the BOREN bits of Configuration Word 2 are programmed to ‘10’, the BOR is on, except in Sleep. BOR protection is not active during Sleep, but device wake-up will be delayed until the BOR can determine that V_{DD} is higher than the BOR threshold. The device wake-up will be delayed until the BOR is ready.

9.2.3 BOR Controlled by Software

When the BOREN bits of Configuration Words are programmed to ‘01’, the BOR is controlled by the [SBOREN](#) bit. The device start-up is not delayed by the BOR ready condition or the V_{DD} level.

BOR protection begins as soon as the BOR circuit is ready. The status of the BOR circuit is reflected in the [BORRDY](#) bit.

BOR protection is unchanged by Sleep.

Table 9-1. BOR Operating Modes

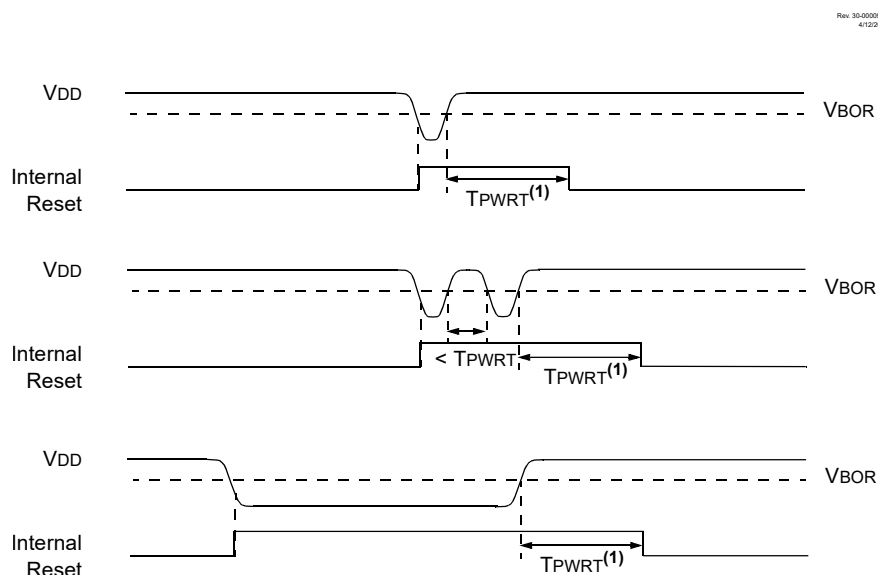
| BOREN[1:0] | SBOREN | Device Mode | BOR Mode | Instruction Execution upon: | |
|------------|--------|-------------|-----------|--------------------------------------|--------------------------------------|
| | | | | Release of POR | Wake-up from Sleep |
| 11 | X | X | Active | Wait for release of BOR (BORRDY = 1) | Begins immediately |
| 10 | X | Awake | Active | Wait for release of BOR (BORRDY = 1) | N/A |
| | | Sleep | Hibernate | N/A | Wait for release of BOR (BORRDY = 1) |

.....continued

| BOREN[1:0] | SBOREN | Device Mode | BOR Mode | Instruction Execution upon: | |
|------------|--------|-------------|-----------|--------------------------------------|--------------------|
| | | | | Release of POR | Wake-up from Sleep |
| 01 | 1 | X | Active | Wait for release of BOR (BORRDY = 1) | Begins immediately |
| | 0 | X | Hibernate | | |
| 00 | X | X | Disabled | Begins immediately | |

Note:

1. In this specific case, “Release of POR” and “Wake-up from Sleep”, there is no delay in start-up. The BOR ready flag (BORRDY = 1) will be set before the CPU is ready to execute instructions because the BOR circuit is forced on by the BOREN[1:0] bits.

Figure 9-2. Brown-out Situations

Note: T_{PWRT} delay only if the $PWRT$ bit is programmed to '0'.

9.2.4 BOR and Bulk Erase

BOR is forced ON during PFM Bulk Erase operations to make sure that the system code protection cannot be compromised by reducing V_{DD} .

During Bulk Erase, the BOR is enabled at 1.9V, even if it is configured to some other value. If V_{DD} falls, the erase cycle will be aborted, but the device will not be reset.

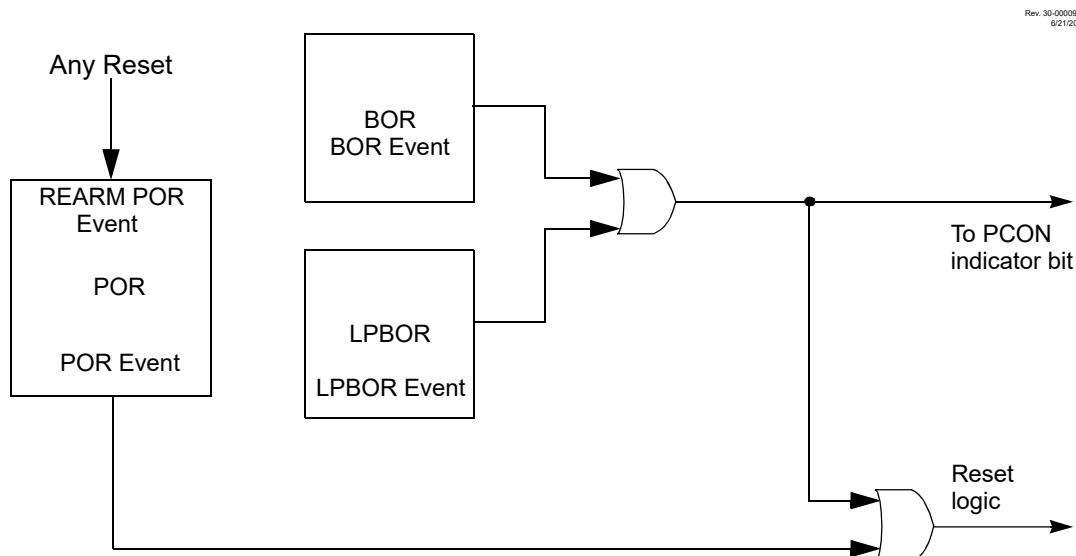
9.3 Low-Power Brown-out Reset (LPBOR)

The Low-Power Brown-out Reset (LPBOR) circuit provides alternative protection against Brown-out conditions. When V_{DD} falls below the LPBOR threshold, the device is held in Reset. When this occurs, the BOR bit of the PCON0 register is cleared to indicate that a Brown-out Reset occurred. The BOR bit will be cleared when either the BOR or the LPBOR circuitry detects a BOR condition.

The LPBOR feature can be used with or without BOR enabled. When used while BOR is enabled, the LPBOR can be used as a secondary protection circuit in case the BOR circuit fails to detect the BOR condition. Additionally, when BOR is enabled except while in Sleep (BOREN[1:0] = 10), the LPBOR circuit will hold the device in Reset while V_{DD} is lower than the LPBOR threshold, and will also re-arm the POR (see [Reset, WDT, Oscillator Start-up Timer, Power-up Timer, Brown-out Reset and Low-Power Brown-out Reset Specifications](#) for LPBOR Reset voltage levels).

When used without BOR enabled, the LPBOR circuit provides a single Reset trip point with the benefit of reduced current consumption.

Figure 9-3. LPBOR, BOR, POR Relationship



9.3.1 Enabling LPBOR

The LPBOR is controlled by the $\overline{\text{LPBOREN}}$ bit of Configuration Word 2. When the device is erased, the LPBOR module defaults to disabled.

Related Links

[CONFIG2](#)

CONFIG2

9.3.1.1 LPBOR Module Output

The output of the LPBOR module is a signal indicating whether or not a Reset is to be asserted. This signal is OR'd together with the Reset signal of the BOR module to provide the generic $\overline{\text{BOR}}$ signal, which goes to the [PCON0](#) register and to the power control block.

9.4 $\overline{\text{MCLR}}$ Reset

The $\overline{\text{MCLR}}$ is an optional external input that can reset the device. The $\overline{\text{MCLR}}$ function is controlled by the MCLRE bit of Configuration Word 2 and the LVP bit of Configuration Word 4 (see the table below). The $\overline{\text{RMCLR}}$ bit in the [PCON0](#) register will be set to '0' if an $\overline{\text{MCLR}}$ has occurred.

Table 9-2. $\overline{\text{MCLR}}$ Configuration

| MCLRE | LVP | $\overline{\text{MCLR}}$ |
|-------|-----|--------------------------|
| x | 1 | Enabled |
| 1 | 0 | Enabled |
| 0 | 0 | Disabled |

9.4.1 $\overline{\text{MCLR}}$ Enabled

When $\overline{\text{MCLR}}$ is enabled and the pin is held low, the device is held in Reset. The $\overline{\text{MCLR}}$ pin is connected to V_{DD} through an internal weak pull-up.

The device has a noise filter in the $\overline{\text{MCLR}}$ Reset path. The filter will detect and ignore small pulses.



Important: An internal Reset event (`RESET` instruction, BOR, WWDT, POR, STKOVF, STKUNF) does not drive the `MCLR` pin low.

9.4.2 `MCLR` Disabled

When `MCLR` is disabled, the `MCLR` becomes input-only and pin functions such as internal weak pull-ups are under software control.

Related Links

[I/O Priorities](#)

9.5 Windowed Watchdog Timer (WWDT) Reset

The Windowed Watchdog Timer generates a Reset if the firmware does not issue a `CLRWDT` instruction within the time-out period or window set. The `TO` and `PD` bits in the STATUS register and the `RWDT` bit are changed to indicate a WDT Reset. The `WDTWV` bit indicates if the WDT Reset has occurred due to a time-out or a window violation.

Related Links

[STATUS](#)

STATUS

[WWDT - Windowed Watchdog Timer](#)

9.6 RESET Instruction

A `RESET` instruction will cause a device Reset. The `RI` bit will be set to '0'. See [Table 9-3](#) for default conditions after a `RESET` instruction has occurred.

9.7 Stack Overflow/Underflow Reset

The device can reset when the Stack Overflows or Underflows. The `STKOVF` or `STKUNF` bits in PCON0 register indicate the Reset condition. These Resets are enabled by setting the STVREN bit in Configuration Word 2.

Related Links

[CONFIG2](#)

CONFIG2

[Stack Overflow and Underflow Resets](#)

9.8 Programming Mode Exit

Upon exit of Programming mode, the device will behave as if a POR had just occurred.

9.9 Power-up Timer (PWRT)

The Power-up Timer provides a nominal 66 ms (2048 cycles of LFINTOSC) time-out on POR or Brown-out Reset.

The device is held in Reset as long as PWRT is active. The PWRT delay allows additional time for the V_{DD} to rise to an acceptable level. The Power-up Timer is enabled by clearing the PWRT \overline{E} bit in Configuration Words.

The Power-up Timer starts after the release of the POR and BOR.

For additional information, refer to Application Note AN607, "Power-up Trouble Shooting" (DS00000607).

9.10 Start-up Sequence

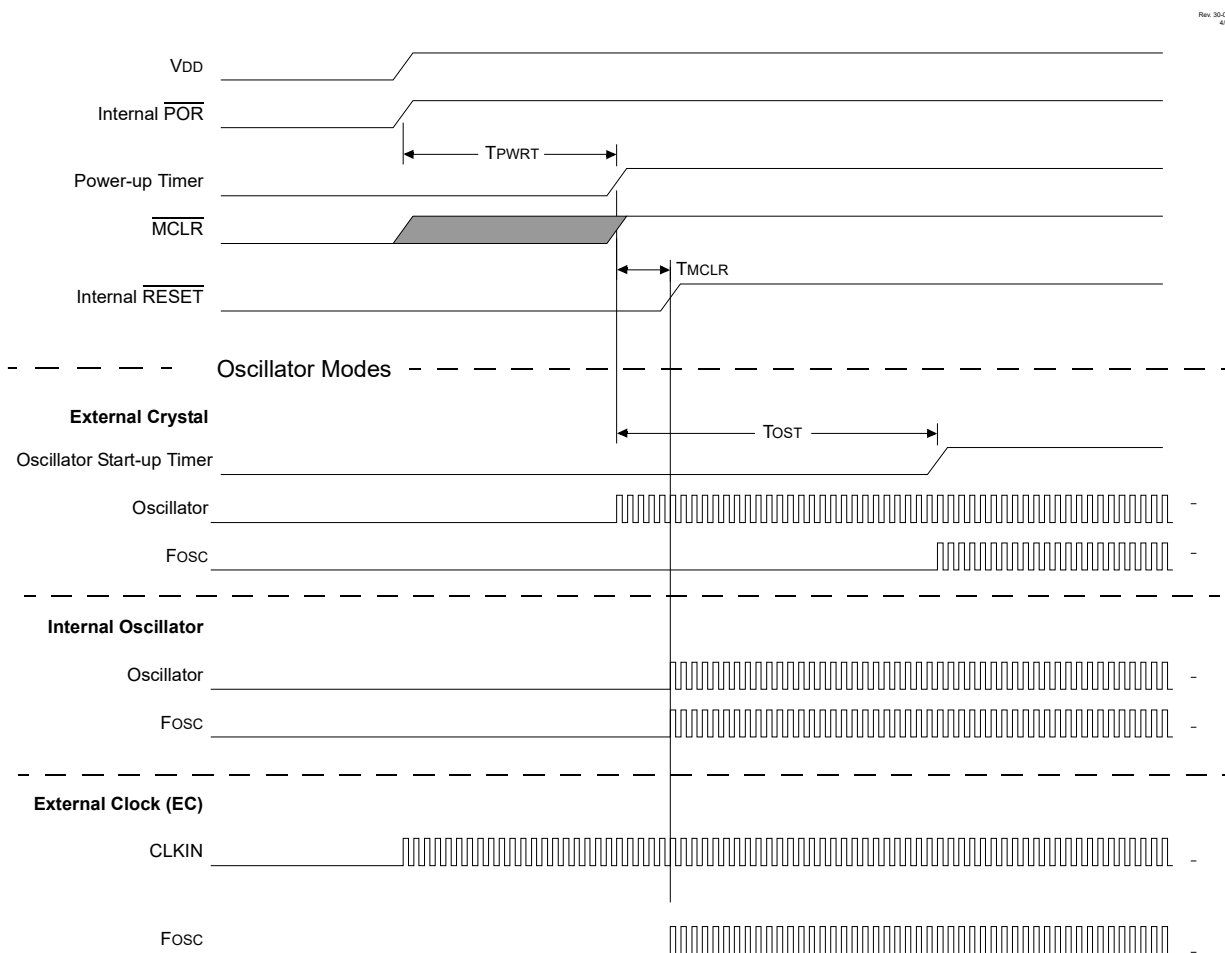
Upon the release of a POR or BOR, the following must occur before the device will begin executing:

1. Power-up Timer runs to completion (if enabled).
2. Oscillator Start-up Timer runs to completion (if required for selected oscillator source).
3. $\overline{\text{MCLR}}$ must be released (if enabled).

The total time-out will vary based on oscillator configuration and Power-up Timer configuration.

The Power-up Timer and Oscillator Start-up Timer run independently of $\overline{\text{MCLR}}$ Reset. If $\overline{\text{MCLR}}$ is kept low long enough, the Power-up Timer and Oscillator Start-up Timer will expire. Upon bringing $\overline{\text{MCLR}}$ high, the device will begin execution after 10 F_{OSC} cycles (see figure below). This is useful for testing purposes or to synchronize more than one device operating in parallel.

Figure 9-4. Reset Start-up Sequence



Related Links

[OSC - Oscillator Module](#)

9.11 Determining the Cause of a Reset

Upon any Reset, multiple bits in the STATUS and PCON0 registers are updated to indicate the cause of the Reset. The following table shows the Reset conditions of these registers.

Table 9-3. Reset Condition for Special Registers

| Condition | Program Counter | STATUS Register ^(2,3) | PCON0 Register | PCON1 Register |
|----------------|-----------------|----------------------------------|----------------|----------------|
| Power-on Reset | 0 | -110 0000 | 0011 110x | ---- -1-1 |

.....continued

| Condition | Program Counter | STATUS Register ^(2,3) | PCON0 Register | PCON1 Register |
|------------------------------------|-----------------------|----------------------------------|----------------|----------------|
| Brown-out Reset | 0 | -110 0000 | 0011 11u0 | ---- -u-u |
| MCLR Reset during normal operation | 0 | -uuu uuuu | uuuu 0uuu | uuuu-u-u |
| MCLR Reset during Sleep | 0 | -10u uuuu | uuuu 0uuu | uuuu-u-u |
| WDT Time-out Reset | 0 | -0uu uuuu | uuu0 uuuu | uuuu-u-u |
| WDT Wake-up from Sleep | PC + 2 | -00u uuuu | uuuu uuuu | uuuu-u-u |
| WWDT Window Violation Reset | 0 | -uuu uuuu | uu0u uuuu | uuuu-u-u |
| Interrupt Wake-up from Sleep | PC + 2 ⁽¹⁾ | -10u 0uuu | uuuu uuuu | uuuu-u-u |
| RESET Instruction Executed | 0 | -uuu uuuu | uuuu u0uu | uuuu-u-u |
| Stack Overflow Reset (STVREN = 1) | 0 | -uuu uuuu | 1uuu uuuu | uuuu-u-u |
| Stack Underflow Reset (STVREN = 1) | 0 | -uuu uuuu | u1uu uuuu | uuuu-u-u |
| Data Protection (Fuse Fault) | 0 | ---u uuuu | uuuu uuuu | ---- -u-0 |
| VREG or ULP Ready Fault | 0 | ---1 1000 | 0011 001u | ---- -0-1 |

Legend: u = unchanged, x = unknown, — = unimplemented bit, reads as '0'.

Notes:

1. When the wake-up is due to an interrupt and Global Interrupt Enable bit (GIE) is set, the return address is pushed on the stack and PC is loaded with the corresponding interrupt vector (depending on source, high or low priority) after execution of PC + 2.
2. If a Status bit is not implemented, that bit will be read as '0'.
3. Status bits Z, C, DC are reset by POR/BOR.

Related Links

[STATUS](#)

STATUS

9.12 Power Control (PCON0) Register

The Power Control (PCON0) register contains flag bits to differentiate between a:

- Brown-out Reset ($\overline{\text{BOR}}$)
- Power-on Reset ($\overline{\text{POR}}$)
- Reset Instruction Reset ($\overline{\text{RI}}$)
- MCLR Reset ($\overline{\text{RMCLR}}$)
- Watchdog Timer Reset ($\overline{\text{RWDT}}$)
- Watchdog Window Violation ($\overline{\text{WDTWV}}$)
- Stack Underflow Reset (STKUNF)
- Stack Overflow Reset (STKOVF)

The Power Control register bits are shown in [PCON0](#).

Hardware will change the corresponding register bit during the Reset process; if the Reset was not caused by the condition, the bit remains unchanged ([Table 9-3](#)).

Software should reset the bit to the Inactive state after restart (hardware will not reset the bit).

Software may also set any PCON0 bit to the Active state, so that user code may be tested, but no Reset action will be generated.

9.13 Register Summary - BOR Control and Power Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------|---------------|----------|--------|--------|-------|------|-------|-------|-----|--------|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0EDA | | | | | | | | | | |
| 0x0EDB | BORCON | 7:0 | SBOREN | | | | | | | BORRDY |
| 0x0EDC ... | Reserved | | | | | | | | | |
| 0x0FD5 | | | | | | | | | | |
| 0x0FD6 | PCON1 | 7:0 | | | | | | RVREG | | RCM |
| 0x0FD7 | PCON0 | 7:0 | STKOVF | STKUNF | WDTWV | RWDT | RMCLR | RI | POR | BOR |

9.14 Register Definitions: Power Control

9.14.1 BORCON

Name: BORCON

Address: 0xEDB

Brown-out Reset Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|---|---|---|---|---|---|--------|
| | SBOREN | | | | | | | BORRDY |
| Access | R/W | | | | | | | R |
| Reset | 1 | | | | | | | q |

Bit 7 – SBOREN Software Brown-out Reset Enable bit

Reset States: POR/BOR = 1

All Other Resets = u

| Value | Condition | Description |
|-------|---------------|--|
| – | If BOREN ≠ 01 | SBOREN is read/write, but has no effect on the BOR |
| 1 | If BOREN = 01 | BOR Enabled |
| 0 | If BOREN = 01 | BOR Disabled |

Bit 0 – BORRDY Brown-out Reset Circuit Ready Status bit

Reset States: POR/BOR = q

All Other Resets = u

| Value | Description |
|-------|--|
| 1 | The Brown-out Reset Circuit is active and armed |
| 0 | The Brown-out Reset Circuit is disabled or is warming up |

Related Links

[CONFIG2](#)

CONFIG2

9.14.2 PCON0

Name: PCON0

Address: 0xFD7

Power Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | STKOVF | STKUNF | WDTWV | RWDT | RMCLR | RI | POR | BOR |
| Access | R/W/HS | R/W/HS | R/W/HC | R/W/HC | R/W/HC | R/W/HC | R/W/HC | R/W/HC |
| Reset | 0 | 0 | 1 | 1 | 1 | 1 | 0 | q |

Bit 7 – STKOVF Stack Overflow Flag bit

Reset States: POR/BOR = 0

All Other Resets = q

| Value | Description |
|-------|--|
| 1 | A Stack Overflow occurred (more CALLs than fit on the stack) |
| 0 | A Stack Overflow has not occurred or set to '0' by firmware |

Bit 6 – STKUNF Stack Underflow Flag bit

Reset States: POR/BOR = 0

All Other Resets = q

| Value | Description |
|-------|--|
| 1 | A Stack Underflow occurred (more RETURNS than CALLs) |
| 0 | A Stack Underflow has not occurred or set to '0' by firmware |

Bit 5 – WDTWV Watchdog Window Violation Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|---|
| 1 | A WDT window violation has not occurred or set to '1' by firmware |
| 0 | A CLRWD instruction was issued when the WDT Reset window was closed (set to '0' in hardware when a WDT window violation Reset occurs) |

Bit 4 – RWDT WDT Reset Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|---|
| 1 | A WDT overflow/time-out Reset has not occurred or set to '1' by firmware |
| 0 | A WDT overflow/time-out Reset has occurred (set to '0' in hardware when a WDT Reset occurs) |

Bit 3 – RMCLR MCLR Reset Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|---|
| 1 | A MCLR Reset has not occurred or set to '1' by firmware |
| 0 | A MCLR Reset has occurred (set to '0' in hardware when a MCLR Reset occurs) |

Bit 2 – RI RESET Instruction Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|---|
| 1 | A RESET instruction has not been executed or set to '1' by firmware |
| 0 | A RESET instruction has been executed (set to '0' in hardware upon executing a RESET instruction) |

Bit 1 – $\overline{\text{POR}}$ Power-on Reset Status bit

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | No Power-on Reset occurred or set to '1' by firmware |
| 0 | A Power-on Reset occurred (set to '0' in hardware when a Power-on Reset occurs) |

Bit 0 – $\overline{\text{BOR}}$ Brown-out Reset Status bit

Reset States: POR/BOR = q
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | No Brown-out Reset occurred or set to '1' by firmware |
| 0 | A Brown-out Reset occurred (set to '0' in hardware when a Brown-out Reset occurs) |

9.14.3 PCON1

Name: PCON1

Address: 0xFD6

Power Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|---|--------|---|--------|
| | | | | | | RVREG | | RCM |
| Access | | | | | | R/W/HC | | R/W/HC |
| Reset | | | | | | 1 | | 1 |

Bit 2 – **RVREG** Main LDO Voltage Regulator Reset Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|--|
| 1 | No LDO or ULP “ready” Reset has occurred; or set to ‘1’ by firmware |
| 0 | LDO or ULP “ready” Reset has occurred (VDDCORE reached its minimum spec) |

Bit 0 – **RCM** Configuration Memory Reset Flag bit

Reset States: POR/BOR = 1

All Other Resets = q

| Value | Description |
|-------|---|
| 1 | The configuration and calibration latches have not been corrupted |
| 0 | A Reset occurred due to corruption of the configuration and/or calibration data latches |

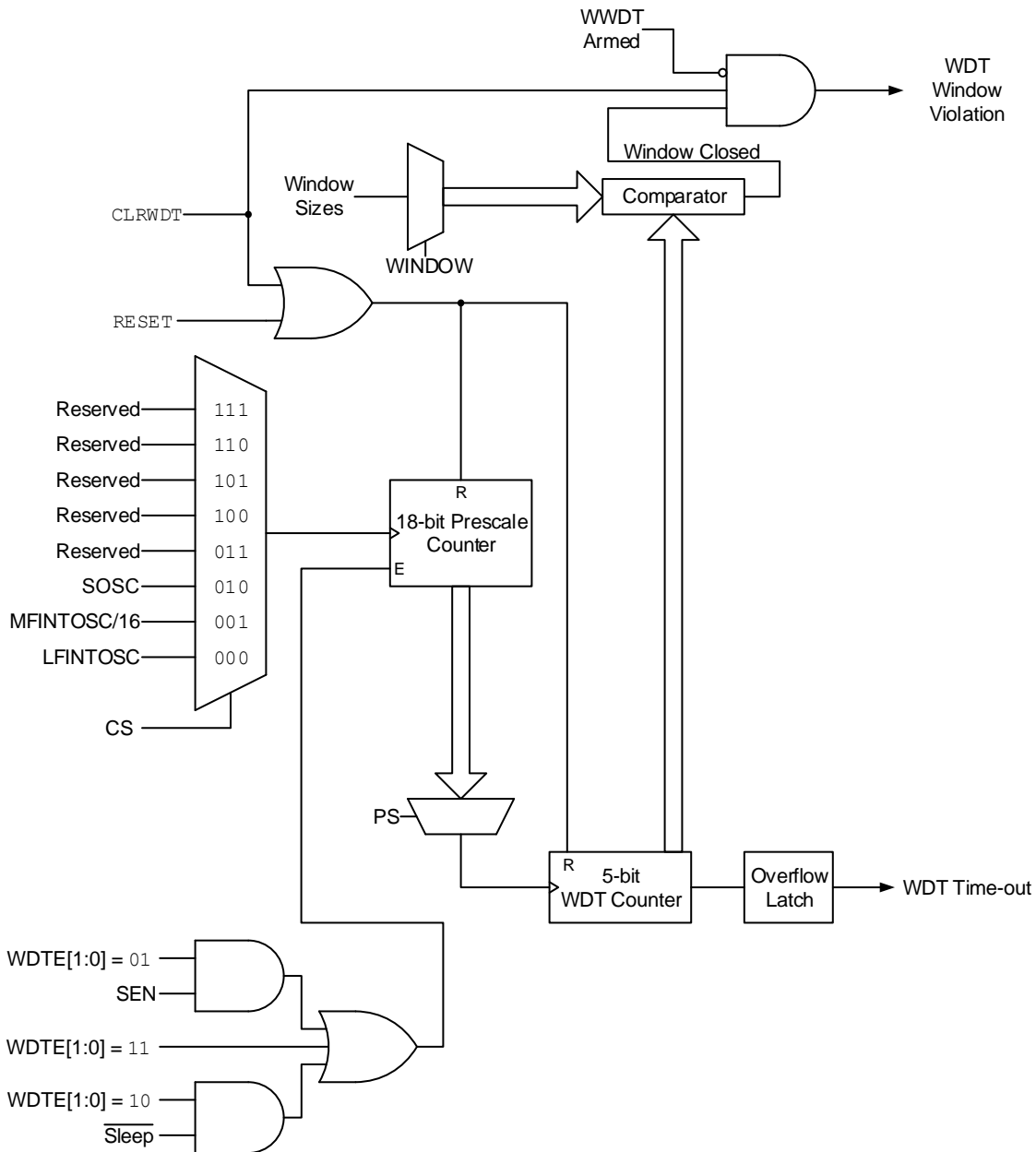
10. WWDT - Windowed Watchdog Timer

The Watchdog Timer (WDT) is a system timer that generates a Reset if the firmware does not issue a `CLRWDT` instruction within the time-out period. The Watchdog Timer is typically used to recover the system from unexpected events. The Windowed Watchdog Timer (WWDT) differs in that `CLRWDT` instructions are only accepted when they are performed within a specific window during the time-out period.

The WWDT has the following features:

- Selectable Clock Source
- Multiple Operating Modes
 - WWDT is always on
 - WWDT is off when in Sleep
 - WWDT is controlled by software
 - WWDT is always off
- Configurable Time-out Period is from 1 ms to 256s (Nominal)
- Configurable Window Size from 12.5% to 100% of the Time-out Period
- Multiple Reset Conditions

Figure 10-1. Windowed Watchdog Timer Block Diagram



10.1 Independent Clock Source

The WWDT can derive its time base from either the 31 kHz LFINTOSC or 31.25 kHz MFINTOSC internal oscillators, depending on the value of the WDTE bits in CONFIG3.

If WDTE = 'b1x, then the clock source will be enabled depending on the WDTCCS bits in CONFIG3.

If WDTE = 'b01, the [SEN](#) bit in the WDTCON0 register must be set by software to enable WWDT, and the clock source is enabled by the [WDTCS](#) bits in the WDTCON1 register.

Time intervals in this chapter are based on a minimum nominal interval of 1 ms. See [Internal Oscillator Parameters\(1\)](#) for LFINTOSC and MFINTOSC tolerances.

Related Links

[CONFIG3](#)

CONFIG3

[Internal Oscillator Parameters\(1\)](#)

10.2 WWDT Operating Modes

The Windowed Watchdog Timer module has four operating modes controlled by the WDTE bits in the CONFIG3. See [Table 10-1](#).

Table 10-1. WWDT Operating Modes

| WDTE[1:0] | SEN | Device Mode | WWDT Mode |
|-----------|-----|-------------|-----------|
| 11 | X | X | Active |
| 10 | X | Awake | Active |
| | | Sleep | Disabled |
| 01 | 1 | X | Active |
| | 0 | X | Disabled |
| 00 | X | X | Disabled |

10.2.1 WWDT Is Always On

When the WDTE bits of Configuration Words are set to '11', the WWDT is always on.

WWDT protection is active during Sleep.

10.2.2 WWDT Is Off in Sleep

When the WDTE bits of Configuration Words are set to '10', the WWDT is on, except in Sleep.

WWDT protection is not active during Sleep.

10.2.3 WWDT Controlled by Software

When the WDTE bits of Configuration Words are set to '01', the WWDT is controlled by the [SEN](#) bit.

WWDT protection is unchanged by Sleep. See the following table for more details.

Table 10-2. WWDT Operating Modes

| WDTE[1:0] | SEN | Device Mode | WWDT Mode |
|-----------|-----|-------------|-----------|
| 11 | X | X | Active |
| 10 | X | Awake | Active |
| | | Sleep | Disabled |
| 01 | 1 | X | Active |
| | 0 | X | Disabled |
| 00 | X | X | Disabled |

10.3 Time-out Period

If the WDTCPs bits in CONFIG3 are set to 0'b11111, then the [WDTPS](#) bits set the time-out period from 1 ms to 256 seconds (nominal). If any value other than the default value is assigned to WDTCPs Configuration bits, then the timer period will be based on the WDTCPs bits in the CONFIG3 register. After a Reset, the default time-out period is 2s.

Related Links

[CONFIG3](#)

CONFIG3

10.4 Watchdog Window

The Windowed Watchdog Timer has an optional Windowed mode that is controlled by the WDTWWS bits in Configuration Word 3 and **WINDOW** bits in the WDTCON1 register. In the Windowed mode, the **CLRWDT** instruction must occur within the allowed window of the WDT period. Any **CLRWDT** instruction that occurs outside of this window will trigger a window violation and will cause a WWDT Reset, similar to a WWDT time-out. See [Figure 10-2](#) for an example.

The window size is controlled by the Watchdog Timer Window Select (**WINDOW**) bits in WDTCON1, if WDTWWS bits in Configuration Word 3 are set to 111.

The WDTTMR bits in the **WDTTMR** register are used to determine whether the window is open, as defined by the **WINDOW** bits.

In the event of a window violation, a Reset will be generated and the **WDTWV** bit of the PCON0 register will be cleared. This bit is set by a POR or can be set in firmware.

Related Links

[PCON0](#)

PCON0

10.5 Clearing the WWDT

The WWDT is cleared when any of the following conditions occur:

- Any Reset
- Valid **CLRWDT** instruction is executed
- Device enters Sleep
- Exit Sleep by interrupt
- WWDT is disabled
- Oscillator Start-up Timer (OST) is running
- Any write to the **WDTCON0** or **WDTCON1** registers

10.5.1 CLRWDT Considerations (Windowed Mode)

When in Windowed mode, the WWDT must be armed before a **CLRWDT** instruction will clear the timer. This is performed by reading the **WDTCON0** register. Executing a **CLRWDT** instruction without performing such an arming action will trigger a window violation regardless of whether the window is open or not.

See [Table 10-3](#) for more information.

10.6 Operation During Sleep

When the device enters Sleep, the WWDT is cleared. If the WWDT is enabled during Sleep, the WWDT resumes counting. When the device exits Sleep, the WWDT is cleared again.

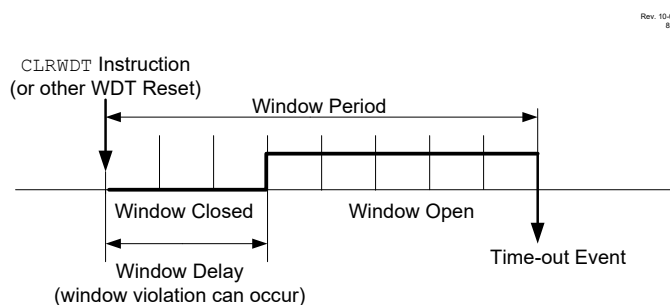
The WWDT remains clear until the Oscillator Start-up Timer (OST) completes, if enabled.

When a WWDT time-out occurs while the device is in Sleep, no Reset is generated. Instead, the device wakes up and resumes operation. The **TO** and **PD** bits in the STATUS register are changed to indicate the event. The **RWDT** bit in the PCON0 register can also be used.

Table 10-3. WWDT Clearing Conditions

| Conditions | WWDT |
|---|------------------------------|
| WDTE = 00 | Cleared |
| WDTE = 01 and SEN = 0 | |
| WDTE = 10 and enter Sleep | |
| CLRWDT Command | |
| Oscillator Fail Detected | |
| Exit Sleep + System Clock = SOSC, EXTRC, INTOSC, EXTCLK | |
| Exit Sleep + System Clock = XT, HS, LP | Cleared until the end of OST |
| Change INTOSC divider (IRCF bits) | Unaffected |

Figure 10-2. Window Period and Delay



Related Links

[Oscillator Start-up Timer \(OST\)](#)

[STATUS](#)

STATUS

[PCON0](#)

PCON0

[Memory Organization](#)

10.7 Register Summary - WDT Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------|----------|---|---|-------------|-------------|------------|-------|-------------|-----|
| 0x00 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0ECC | | | | | | | | | | |
| 0x0ECD | WDTCN0 | 7:0 | | | | | WDTPS[4:0] | | | SEN |
| 0x0ECE | WDTCN1 | 7:0 | | | WDTC[2:0] | | | | WINDOW[2:0] | |
| 0x0ECF | WDTPSL | 7:0 | | | | PSCNTL[7:0] | | | | |
| 0x0ED0 | WDTPSH | 7:0 | | | | PSCNTH[7:0] | | | | |
| 0x0ED1 | WDTTMR | 7:0 | | | WDTTMR[4:0] | | | STATE | PSCNT[1:0] | |

10.8 Register Definitions: Windowed Watchdog Timer Control

10.8.1 WDTCON0

Name: WDTCON0
Address: 0xECD

Watchdog Timer Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|------------|-----|-----|-----|-----|-----|
| | | | WDTPS[4:0] | | | | | SEN |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | q | q | q | q | q | 0 |

Bits 5:1 – WDTPS[4:0] Watchdog Timer Prescale Select bits⁽¹⁾

Bit Value = Prescale Rate

| Value | Description |
|----------------|--|
| 11111 to 10011 | Reserved. Results in minimum interval (1 ms) |
| 10010 | 1:8388608 (2^{23}) (Interval 256s nominal) |
| 10001 | 1:4194304 (2^{22}) (Interval 128s nominal) |
| 10000 | 1:2097152 (2^{21}) (Interval 64s nominal) |
| 01111 | 1:1048576 (2^{20}) (Interval 32s nominal) |
| 01110 | 1:524288 (2^{19}) (Interval 16s nominal) |
| 01101 | 1:262144 (2^{18}) (Interval 8s nominal) |
| 01100 | 1:131072 (2^{17}) (Interval 4s nominal) |
| 01011 | 1:65536 (Interval 2s nominal) (Reset value) |
| 01010 | 1:32768 (Interval 1s nominal) |
| 01001 | 1:16384 (Interval 512 ms nominal) |
| 01000 | 1:8192 (Interval 256 ms nominal) |
| 00111 | 1:4096 (Interval 128 ms nominal) |
| 00110 | 1:2048 (Interval 64 ms nominal) |
| 00101 | 1:1024 (Interval 32 ms nominal) |
| 00100 | 1:512 (Interval 16 ms nominal) |
| 00011 | 1:256 (Interval 8 ms nominal) |
| 00010 | 1:128 (Interval 4 ms nominal) |
| 00001 | 1:64 (Interval 2 ms nominal) |
| 00000 | 1:32 (Interval 1 ms nominal) |

Bit 0 – SEN Software Enable/Disable for Watchdog Timer bit

| Value | Condition | Description |
|-------|--------------|---------------------|
| – | If WDTE = 1x | This bit is ignored |
| 1 | If WDTE = 01 | WDT is turned on |
| 0 | If WDTE = 01 | WDT is turned off |
| – | If WDTE = 00 | This bit is ignored |

Notes:

1. Times are approximate. WDT time is based on 31 kHz LFINTOSC.
2. When WDTCP3 in CONFIG3 = 11111, the Reset value (q) of WDTPS is '01011'. Otherwise, the Reset value of WDTPS is equal to WDTCP3 in CONFIG3.
3. When WDTCP3 in CONFIG3L ≠ 11111, these bits are read-only.

10.8.2 WDTCON1

Name: WDTCON1

Address: 0xECE

Watchdog Timer Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|------------|-----|-----|---|-------------|-----|-----|
| | | WDTCS[2:0] | | | | WINDOW[2:0] | | |
| Access | | R/W | R/W | R/W | | R/W | R/W | R/W |
| Reset | | q | q | q | | q | q | q |

Bits 6:4 – WDTCS[2:0] Watchdog Timer Clock Select bits

| Value | Description |
|------------|--------------------|
| 111 to 010 | Reserved |
| 001 | MFINTOSC 31.25 kHz |
| 000 | LFINTOSC 31 kHz |

Bits 2:0 – WINDOW[2:0] Watchdog Timer Window Select bits

| WINDOW | Window delay Percent of time | Window opening Percent of time |
|--------|------------------------------|--------------------------------|
| 111 | N/A | 100 |
| 110 | 12.5 | 87.5 |
| 101 | 25 | 75 |
| 100 | 37.5 | 62.5 |
| 011 | 50 | 50 |
| 010 | 62.5 | 37.5 |
| 001 | 75 | 25 |
| 000 | 87.5 | 12.5 |

Notes:

1. If WDTCCS in CONFIG3 = 111, the Reset value of WDTCS is '000'.
2. The Reset value (q) of WINDOW is determined by the value of WDTCCS in the CONFIG3 register.
3. If WDTCCS in CONFIG3 ≠ 111, these bits are read-only.
4. If WDTCCS in CONFIG3 ≠ 111, these bits are read-only.

10.8.3 WDTPSL

Name: WDTPSL
Address: 0xECF

WWDT Prescale Select Low Register (Read-Only)

| | | | | | | | | |
|--------|-------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PSCNTL[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – PSCNTL[7:0] Prescale Select Low Byte bits⁽¹⁾

Note:

1. The 18-bit WDT prescale value, PSCNT[17:0], includes the WDTPSL, WDTPSH and the lower two bits of the WDTTMR registers. PSCNT[17:0] is intended for debug operations and may be read during normal operation.

10.8.4 WDTPSH

Name: WDTPSH
Address: 0xED0

WWDT Prescale Select High Register (Read-Only)

| | | | | | | | | |
|--------|-------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PSCNTH[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – PSCNTH[7:0] Prescale Select High Byte bits⁽¹⁾

Note:

1. The 18-bit WDT prescale value, PSCNT[17:0], includes the WDTPSL, WDTPSH and the lower bits of the WDTTMR registers. PSCNT[17:0] is intended for debug operations and may be read during normal operation.

10.8.5 WDTTMR

Name: WDTTMR
Address: 0xED1

WDT Timer Register (Read-Only)

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------------|----|----|----|----|-------|------------|----|
| | WDTTMR[4:0] | | | | | STATE | PSCNT[1:0] | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:3 – WDTTMR[4:0] Watchdog Window Value bits

| WINDOW | WDT Window State | | Open Percent |
|--------|------------------|-------------|--------------|
| | Closed | Open | |
| 111 | N/A | 00000–11111 | 100 |
| 110 | 00000–00011 | 00100–11111 | 87.5 |
| 101 | 00000–00111 | 01000–11111 | 75 |
| 100 | 00000–01011 | 01100–11111 | 62.5 |
| 011 | 00000–01111 | 10000–11111 | 50 |
| 010 | 00000–10011 | 10100–11111 | 37.5 |
| 001 | 00000–10111 | 11000–11111 | 25 |
| 000 | 00000–11011 | 11100–11111 | 12.5 |

Bit 2 – STATE WDT Armed Status bit

| Value | Description |
|-------|------------------|
| 1 | WDT is armed |
| 0 | WDT is not armed |

Bits 1:0 – PSCNT[1:0] Prescale Select Upper bits⁽¹⁾

Note:

1. The 18-bit WDT prescale value, PSCNT[17:0], includes the WDTPSL, WDTPSH and the lower two bits of the WDTTMR registers. PSCNT[17:0] is intended for debug operations and may be read during normal operation.

11. Memory Organization

There are three types of memory in PIC18 enhanced microcontroller devices:

- Program Memory
- Data RAM
- Data EEPROM

In Harvard architecture devices, the data and program memories use separate buses that allows for concurrent access of the two memory spaces. The data EEPROM, for practical purposes, can be regarded as a peripheral device, since it is addressed and accessed through a set of control registers.

Additional detailed information on the operation of the Program Flash Memory and data EEPROM memory is provided in the Nonvolatile Memory (NVM) control section.

11.1 Program Memory Organization

PIC18 microcontrollers implement a 21-bit Program Counter, which is capable of addressing a 2 Mbyte program memory space. Accessing a location between the upper boundary of the physically implemented memory and the 2 Mbyte address will return all '0's (a NOP instruction).

Refer to the following tables for device memory maps and code protection Configuration bits associated with the various sections of PFM.

PIC18 devices have two interrupt vectors. The Reset vector address is at 0000h and the interrupt vector addresses are at 0008h and 0018h.

Figure 11-1. Program and Data Memory Map

Rev. 40-00010
6/16/20

| Address | Device | |
|----------------------|--|------------------------------------|
| | PIC18F45Q10 | PIC18F26Q10 PIC18F46Q10 |
| Note 1 | Stack (31 Levels) | |
| 00 0000h | Reset Vector | |
| ... | ... | |
| 00 0008h | Interrupt Vector High | |
| ... | ... | |
| 00 0018h | Interrupt Vector Low | |
| ... | ... | |
| 00 001Ah | Program Flash Memory (16 KW) | Program Flash Memory (32 KW) |
| 00 7FFFh | | |
| 00 8000h | Not Present ⁽²⁾ | |
| 00 FFFFh | | |
| 01 0000h | | Not Present ⁽²⁾ |
| 01 FFFFh | | |
| 02 0000h | | |
| 1F FFFFh | | |
| 20 0000h 20 00FFh | User IDs (128 Words) ⁽³⁾ | |
| 20 0100h 2F FFFFh | Reserved | |
| 30 0000h 30 00Bh | Configuration Words (6 Words) ⁽³⁾ | |
| 30 00Ch 30 02FFh | Reserved | |
| 30 0300h 30 FFBh | Unimplemented | |
| 31 0000h 31 00FFh | Data EEPROM (256 Bytes) | Data EEPROM (1 k Bytes) |
| 31 0100h 31 03FFh | Unimplemented | |
| 31 0400h 3F FFBh | | |
| 3F FFFCh 3F FFFDh | Revision ID (1 Word) ⁽⁴⁾ | |
| 3F FFFEh 3F FFFFh | Device ID (1 Word) ⁽⁴⁾ | |

Note 1: The stack is a separate SRAM panel, apart from all user memory panels.

2: The addresses do not roll over. The region is read as '0'.

3: Not code-protected.

4: Device/Revision IDs are hard-coded in silicon.

Figure 11-2. Memory Map and Code Protection Control

Rev. 40-000100C
12/19/2017

| Region | Address | Device | |
|----------------|----------------------------|---------------------------------------|---------------------------------------|
| | | PIC18F45Q10 | PIC18F26Q10 PIC18F46Q10 |
| PFM | 00 0000h to 00 07FFh | Boot Block 1 KW CP, WRTB, EBTRB | Boot Block 1 KW CP, WRTB, EBTRB |
| | 00 0800h to 00 1FFFh | Block 0 3 KW CP, WRT0, EBTR0 | Block 0 7 KW CP, WRT0, EBTR0 |
| | 00 2000h to 00 3FFFh | Block 1 4 KW CP, WRT1, EBTR1 | |
| | 00 4000h to 00 5FFFh | Block 2 4 KW CP, WRT2, EBTR2 | Block 1 8 KW CP, WRT1, EBTR1 |
| | 00 6000h to 00 7FFFh | Block 3 4 KW CP, WRT3, EBTR3 | |
| | 00 8000h to 00 BFFFh | | Block 2 8 KW CP, WRT2, EBTR2 |
| | 00 C000h to 00 FFFFh | | Block 3 8 KW CP, WRT3, EBTR3 |
| | 01 0000h to 01 3FFFh | | Not Present |
| | 01 4000h to 01 7FFFh | | |
| | 01 8000h to 01 BFFFh | | |
| | 01 C000h to 01 FFFFh | | |
| | CONFIG | 30 0000h to 30 000Bh | Configuration Words WRTC |
| Data EEPROM | 31 0000h to 31 00FFh | 256 Words CPD, WRTD | 1 KW CPD, WRTD |
| | 31 0100h to 31 01FFh | | |

11.1.1 Program Counter

The Program Counter (PC) specifies the address of the instruction to fetch for execution. The PC is 21 bits wide and is contained in three separate 8-bit registers. The low byte, known as the PCL register, is both readable and writable. The high byte, or PCH register, contains the PC[15:8] bits; it is not directly readable or writable. Updates to the PCH register are performed through the PCLATH register. The upper byte is called PCU. This register contains the PC[20:16] bits; it is also not directly readable or writable. Updates to the PCU register are performed through the PCLATU register.

The contents of PCLATH and PCLATU are transferred to the Program Counter by any operation that writes PCL. Similarly, the upper two bytes of the Program Counter are transferred to PCLATH and PCLATU by an operation that reads PCL. This is useful for computed offsets to the PC (see [Computed GOTO](#)).

The PC addresses bytes in the program memory. To prevent the PC from becoming misaligned with word instructions, the Least Significant bit of PCL is fixed to a value of '0'. The PC increments by two to address sequential instructions in the program memory.

The `CALL`, `RCALL`, `GOTO` and program branch instructions write to the Program Counter directly. For these instructions, the contents of PCLATH and PCLATU are not transferred to the Program Counter.

11.1.2 Return Address Stack

The return address stack allows any combination of up to 31 program calls and interrupts to occur. The PC is pushed onto the stack when a `CALL` or `RCALL` instruction is executed or an interrupt is Acknowledged. The PC value is pulled off the stack on a `RETURN`, `RETLW` or a `RETFIE` instruction. PCLATU and PCLATH are not affected by any of the `RETURN` or `CALL` instructions.

The stack operates as a 31-word by 21-bit RAM and a 5-bit Stack Pointer, or as a 35-word by 21-bit RAM with a 6-bit Stack Pointer in ICD mode. The stack space is not part of either program or data space. The Stack Pointer is readable and writable and the address on the top of the stack is readable and writable through the Top-of-Stack (TOS) Special File registers. Data can also be pushed to, or popped from the stack, using these registers.

A `CALL` type instruction causes a push onto the stack; the Stack Pointer is first incremented and the location pointed to by the Stack Pointer is written with the contents of the PC (already pointing to the instruction following the `CALL`). A `RETURN` type instruction causes a pop from the stack; the contents of the location pointed to by the STKPTR are transferred to the PC and then the Stack Pointer is decremented.

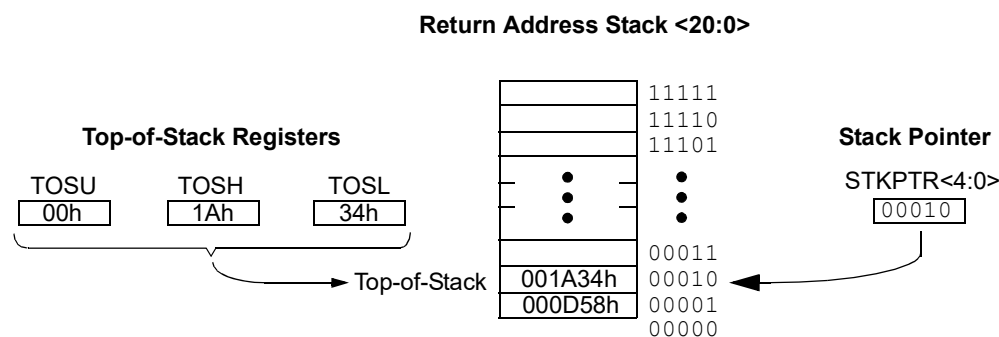
The Stack Pointer is initialized to '0b00000' after all Resets. There is no RAM associated with the location corresponding to a Stack Pointer value of '0b00000'; this is only a Reset value. Status bits in the PCON0 register indicate if the stack is full or has overflowed or has under-flowed.

11.1.2.1 Top-of-Stack Access

Only the top of the return address stack (TOS) is readable and writable. A set of three registers, TOSU:TOSH:TOSL, hold the contents of the stack location pointed to by the STKPTR register (see [Figure 11-3](#)). This allows users to implement a software stack if necessary. After a `CALL`, `RCALL` or interrupt, the software can read the pushed value by reading the TOSU:TOSH:TOSL registers. These values can be placed on a user defined software stack. At return time, the software can return these values to TOSU:TOSH:TOSL and do a return.

The user must disable the Global Interrupt Enable (GIE) bits while accessing the stack to prevent inadvertent stack corruption.

Figure 11-3. Return Address Stack and Associated Registers



11.1.2.2 Return Stack Pointer

The [STKPTR](#) register contains the Stack Pointer value. The STKOVF (Stack Overflow) Status bit and the STKUNF (Stack Underflow) Status bit can be accessed using the PCON0 register. The value of the Stack Pointer can be 0 through 31. On Reset, the Stack Pointer value will be zero. The user may read and write the Stack Pointer value. This feature can be used by a Real-Time Operating System (RTOS) for stack maintenance. After the PC is pushed onto the stack 32 times (without popping any values off the stack), the STKOVF bit is set. The STKOVF bit is cleared by software or by a POR. The action that takes place when the stack becomes full depends on the state of the STVREN (Stack Overflow Reset Enable) Configuration bit.

If STVREN is set (default), a Reset will be generated and a Stack Overflow will be indicated by the STKOVF bit when the 32nd push is initiated. This includes `CALL` and `CALLW` instructions, as well as stacking the return address during an interrupt response. The STKOVF bit will remain set and the Stack Pointer will be set to zero.

If STVREN is cleared, the STKOVF bit will be set on the 32nd push and the Stack Pointer will remain at 31 but no Reset will occur. Any additional pushes will overwrite the 31st push but the STKPTR will remain at 31.

Setting STKOVF = 1 in software will change the bit, but will not generate a Reset.

The STKUNF bit is set when a stack pop returns a value of zero. The STKUNF bit is cleared by software or by POR. The action that takes place when the stack becomes full depends on the state of the STVREN (Stack Overflow Reset Enable) Configuration bit.

If STVREN is set (default) and the stack has been popped enough times to unload the stack, the next pop will return a value of zero to the PC, it will set the STKUNF bit and a Reset will be generated. This condition can be generated by the `RETURN`, `RETLW` and `RETFIE` instructions.

If STVREN is cleared, the STKUNF bit will be set, but no Reset will occur.

➔ Important: Returning a value of zero to the PC on an underflow has the effect of vectoring the program to the Reset vector, where the stack conditions can be verified and appropriate actions can be taken. This is not the same as a Reset, as the contents of the SFRs are not affected.

Related Links

[CONFIG2](#)

CONFIG2

11.1.2.3 Stack Overflow and Underflow Resets

Device Resets on Stack Overflow and Stack Underflow conditions are enabled by setting the STVREN Configuration bit in Configuration. When STVREN is set, a Full or Underflow condition will set the respective STKOVF or STKUNF bit and then cause a device Reset. When STVREN is cleared, a Full or Underflow condition will set the respective STKOVF or STKUNF bit but not cause a device Reset. The STKOVF or STKUNF bits are cleared by the user software or a Power-on Reset.

11.1.2.4 PUSH and POP Instructions

Since the Top-of-Stack is readable and writable, the ability to push values onto the stack and pull values off the stack without disturbing normal program execution is a desirable feature. The PIC18 instruction set includes two instructions, `PUSH` and `POP`, that permit the TOS to be manipulated under software control. TOSU, TOSH and TOSL can be modified to place data or a return address on the stack.

The `PUSH` instruction places the current PC value onto the stack. This increments the Stack Pointer and loads the current PC value onto the stack.

The `POP` instruction discards the current TOS by decrementing the Stack Pointer. The previous value pushed onto the stack then becomes the TOS value.

11.1.2.5 Fast Register Stack

A Fast Register Stack is provided for the STATUS, WREG and BSR registers, to provide a “fast return” option for interrupts. The Stack for each register is only one level deep and is neither readable nor writable. It is loaded with the current value of the corresponding register when the processor vectors for an interrupt. All interrupt sources will push values into the Fast Register Stack. The values in the registers are then loaded back into their associated registers if the `RETFIE, FAST` instruction is used to return from the interrupt.



Important: The \overline{TO} and \overline{PD} bits of the STATUS register are not copied over in this operation.

If both low and high-priority interrupts are enabled, the Stack registers cannot be used reliably to return from low-priority interrupts. If a high-priority interrupt occurs while servicing a low-priority interrupt, the Stack register values stored by the low-priority interrupt will be overwritten. In these cases, users must save the key registers by software during a low-priority interrupt.

If interrupt priority is not used, all interrupts may use the Fast Register Stack for returns from interrupt. If no interrupts are used, the Fast Register Stack can be used to restore the STATUS, WREG and BSR registers at the end of a subroutine call. To use the Fast Register Stack for a subroutine call, a `CALL label, FAST` instruction must be executed to save the STATUS, WREG and BSR registers to the Fast Register Stack. A `RETURN, FAST` instruction is then executed to restore these registers from the Fast Register Stack.

The following example shows a source code example that uses the Fast Register Stack during a subroutine call and return.

Example 11-1. Fast Register Stack Code

```
CALL SUB1, FAST ;STATUS, WREG, BSR SAVED IN FAST REGISTER STACK
:
:
SUB1:
:
:
RETURN, FAST ;RESTORE VALUES SAVED IN FAST REGISTER STACK
```

11.1.3 Look-up Tables in Program Memory

There may be programming situations that require the creation of data structures, or Look-up Tables, in program memory. For PIC18 devices, Look-up Tables can be implemented in two ways:

- Computed GOTO
- Table Reads

11.1.3.1 Computed GOTO

A computed GOTO is accomplished by adding an offset to the Program Counter. An example is shown in the following code example.

A Look-up Table can be formed with an ADDWF PCL instruction and a group of RETLW nn instructions. The W register is loaded with an offset into the table before executing a call to that table. The first instruction of the called routine is the ADDWF PCL instruction. The next instruction executed will be one of the RETLW nn instructions that returns the value 'nn' to the calling function.

The offset value (in WREG) specifies the number of bytes that the Program Counter must advance and must be multiples of two (LSb = 0).

In this method, only one data byte may be stored in each instruction location and room on the return address stack is required.

Example 11-2. Computed GOTO Using an Offset Value

```

RLNCF   OFFSET, W    ; W must be an even number, Max OFFSET = 127
CALL    TABLE

ORG      nn00h        ; 00 in LSByte ensures no addition overflow
TABLE:
ADDWF    PCL          ; Add OFFSET to program counter
RETLW    A            ; Value @ OFFSET=0
RETLW    B            ; Value @ OFFSET=1
RETLW    C            ; Value @ OFFSET=2
.
.
.
```

11.1.3.2 Table Reads and Table Writes

A more compact method of storing data in program memory allows two bytes of data to be stored in each instruction location.

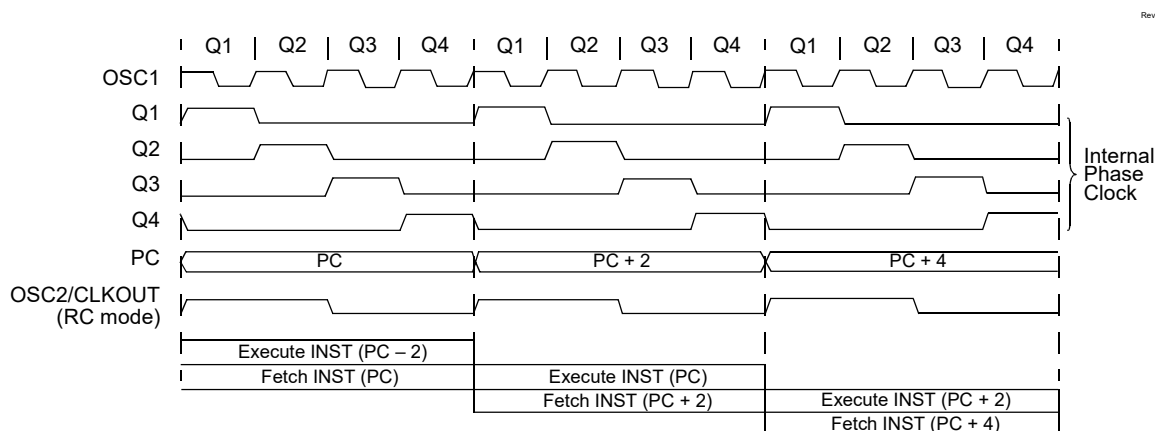
Look-up Table data may be stored two bytes per program word by using table reads and writes. The Table Pointer (TBLPTR) register specifies the byte address and the Table Latch (TABLAT) register contains the data that is read from or written to program memory. Data is transferred to or from program memory one byte at a time.

11.2 PIC18 Instruction Cycle

11.2.1 Clocking Scheme

The microcontroller clock input, whether from an internal or external source, is internally divided by four to generate four nonoverlapping quadrature clocks (Q1, Q2, Q3 and Q4). Internally, the Program Counter is incremented on every Q1; the instruction is fetched from the program memory and latched onto the instruction register during Q4. The instruction is decoded and executed during the following Q1 through Q4. The clocks and instruction execution flow are shown in the following figure.

Figure 11-4. Clock/Instruction Cycle



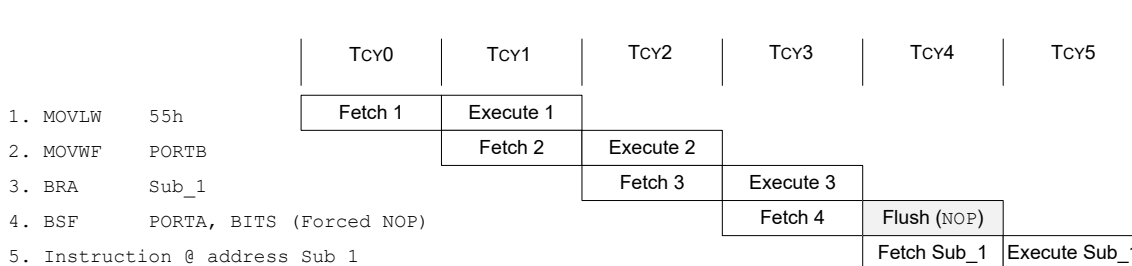
11.2.2 Instruction Flow/Pipelining

An "Instruction Cycle" consists of four Q cycles: Q1 through Q4. The instruction fetch and execute are pipelined in such a manner that a fetch takes one instruction cycle, while the decode and execute take another instruction cycle. However, due to the pipelining, each instruction effectively executes in one cycle. If an instruction causes the Program Counter to change (e.g., GOTO), then two cycles are required to complete the instruction as shown in the figure below.

A fetch cycle begins with the Program Counter (PC) incrementing in Q1.

In the execution cycle, the fetched instruction is latched onto the Instruction Register (IR) in cycle Q1. This instruction is then decoded and executed during the Q2, Q3 and Q4 cycles. Data memory is read during Q2 (operand read) and written during Q4 (destination write).

Figure 11-5. Instruction Pipeline Flow



All instructions are single cycle except for any program branches. These take two cycles since the fetch instruction is "flushed" from the pipeline while the new instruction is being fetched and then executed.

11.2.3 Instructions in Program Memory

The program memory is addressed in bytes. Instructions are stored as either two bytes or four bytes in program memory. The Least Significant Byte of an instruction word is always stored in a program memory location with an even address (LSb = 0). To maintain alignment with instruction boundaries, the PC increments in steps of two and the LSb will always read '0' (see [Program Counter](#)).

The Instructions in Program Memory figure below shows how instruction words are stored in the program memory.

The CALL and GOTO instructions have the absolute program memory address embedded into the instruction. Since instructions are always stored on word boundaries, the data contained in

the instruction is a word address. The word address is written to PC[20:1], which accesses the desired byte address in program memory. Instruction #2 in the example shows how the instruction `GOTO 0006h` is encoded in the program memory. Program branch instructions, which encode a relative address offset, operate in the same manner. The offset value stored in a branch instruction represents the number of single-word instructions that the PC will be offset by. The Instruction Set Summary provides further details of the instruction set.

Figure 11-6. Instructions in Program Memory

| | | | Word Address | |
|------------------------------------|-------|-------|--------------|---------|
| | | | LSB = 1 | LSB = 0 |
| Program Memory Byte Locations → | | | | |
| | | | | 000000h |
| | | | | 000002h |
| | | | | 000004h |
| | | | | 000006h |
| Instruction 1: | MOVLW | 055h | 0Fh | 55h |
| Instruction 2: | GOTO | 0006h | EFh | 03h |
| | | | F0h | 00h |
| | | | C1h | 23h |
| | | | F4h | 56h |
| | | | | 000010h |
| | | | | 000012h |
| | | | | 000014h |

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Related Links

[Instruction Set Summary](#)

11.2.4 Two-Word Instructions

The standard PIC18 instruction set has four two-word instructions: `CALL`, `MOVFF`, `GOTO` and `LFSR`. In all cases, the second word of the instruction always has '1111' as its four Most Significant bits; the other 12 bits are literal data, usually a data memory address.

The use of '1111' in the 4 MSBs of an instruction specifies a special form of `NOF`. If the instruction is executed in proper sequence – immediately after the first word – the data in the second word is accessed and used by the instruction sequence. If the first word is skipped for some reason and the second word is executed by itself, a `NOF` is executed instead. This is necessary for cases when the two-word instruction is preceded by a conditional instruction that changes the PC. The Two-Word Instructions figure below shows how this works.



Important: See the [PIC18 Instruction Execution and the Extended Instruction Set](#) section for information on two-word instructions in the extended instruction set.

Figure 11-7. Two-Word Instructions

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CASE 1:

| Object Code | Source Code |
|---------------------|---------------------------------------|
| 0110 0110 0000 0000 | TSTFSZ REG1 ; is RAM location 0? |
| 1100 0001 0010 0011 | MOVFF REG1, REG2 ; No, skip this word |
| 1111 0100 0101 0110 | ; Execute this word as a NOP |
| 0010 0100 0000 0000 | ADDWF REG3 ; continue code |

CASE 2:

| Object Code | Source Code |
|---------------------|---|
| 0110 0110 0000 0000 | TSTFSZ REG1 ; is RAM location 0? |
| 1100 0001 0010 0011 | MOVFF REG1, REG2 ; Yes, execute this word |
| 1111 0100 0101 0110 | ; 2nd word of instruction |
| 0010 0100 0000 0000 | ADDWF REG3 ; continue code |



11.3 Data Memory Organization



Important: The operation of some aspects of data memory are changed when the PIC18 extended instruction set is enabled. See [PIC18 Instruction Execution and the Extended Instruction Set](#) for more information.

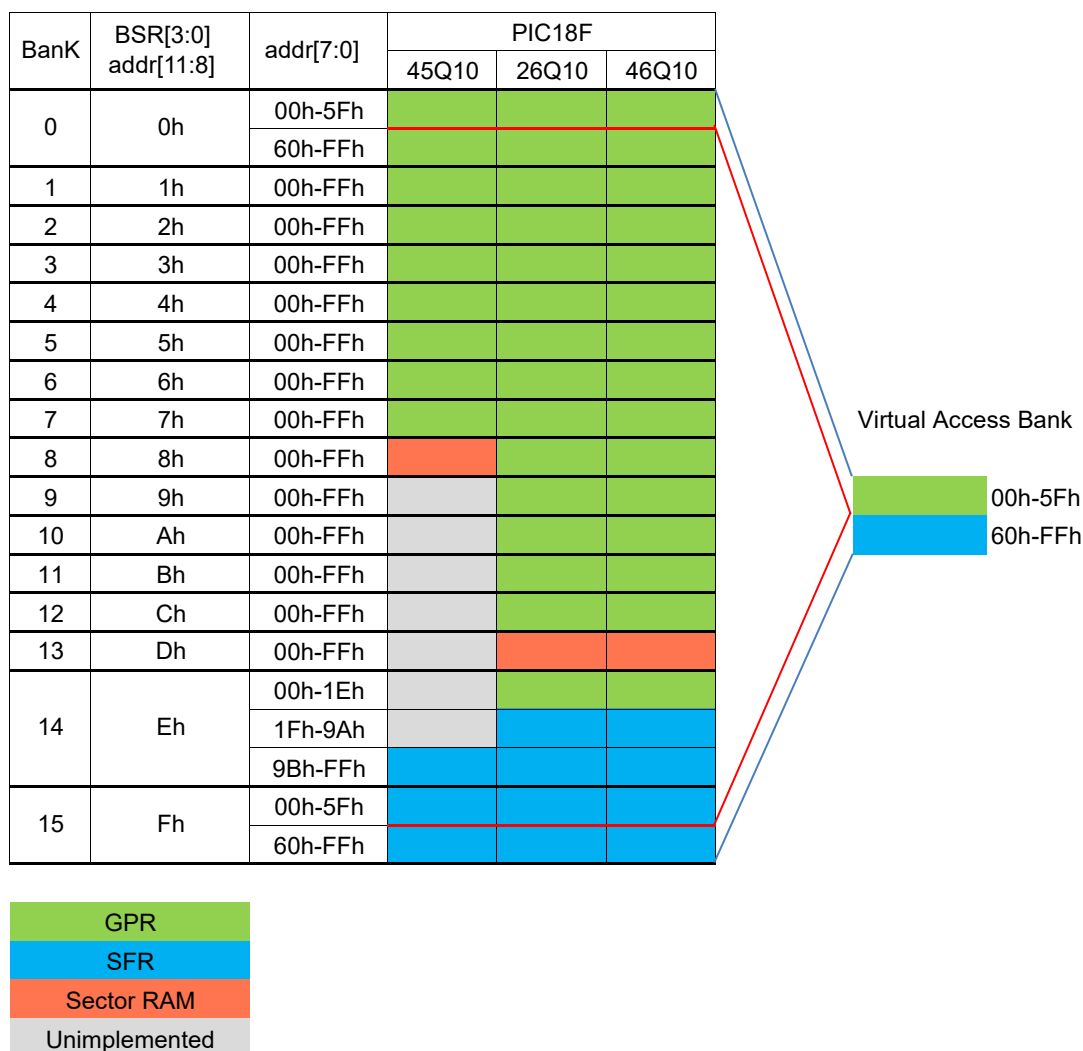
The data memory in PIC18 devices is implemented as static RAM. Each register in the data memory has a 12-bit address, allowing up to 4096 bytes of data memory. The memory space is divided into as many as 16 banks that contain 256 bytes each. The figure below shows the data memory organization for all devices in the device family.

The data memory contains Special Function Registers (SFRs) and General Purpose Registers (GPRs). The SFRs are used for control and status of the controller and peripheral functions, while GPRs are used for data storage and scratchpad operations in the user's application. Any read of an unimplemented location will read as '0's.

The instruction set and architecture allow operations across all banks. The entire data memory may be accessed by Direct, Indirect or Indexed Addressing modes. Addressing modes are discussed later in this subsection.

To ensure that commonly used registers (SFRs and select GPRs) can be accessed in a single cycle, PIC18 devices implement an Access Bank. This is a 256-byte memory space that provides fast access to SFRs and the lower portion of GPR Bank 0 without using the Bank Select Register (BSR). The [Access Bank](#) section provides a detailed description of the Access RAM.

Figure 11-8. Data Memory Map



11.3.1 Bank Select Register

Large areas of data memory require an efficient addressing scheme to make rapid access to any address possible. Ideally, this means that an entire address does not need to be provided for each read or write operation. For PIC18 devices, this is accomplished with a RAM banking scheme. This divides the memory space into 16 contiguous banks of 256 bytes. Depending on the instruction, each location can be addressed directly by its full 12-bit address, or an 8-bit low-order address and a 4-bit Bank Pointer.

Most instructions in the PIC18 instruction set make use of the Bank Pointer, known as the Bank Select Register (BSR). This SFR holds the four Most Significant bits of a location's address; the instruction itself includes the eight Least Significant bits. Only the four lower bits of the BSR are implemented (BSR[3:0]). The upper four bits are unused; they will always read '0' and cannot be written to. The BSR can be loaded directly by using the MOVLB instruction.

The value of the BSR indicates the bank in data memory; the eight bits in the instruction show the location in the bank and can be thought of as an offset from the bank's lower boundary. The

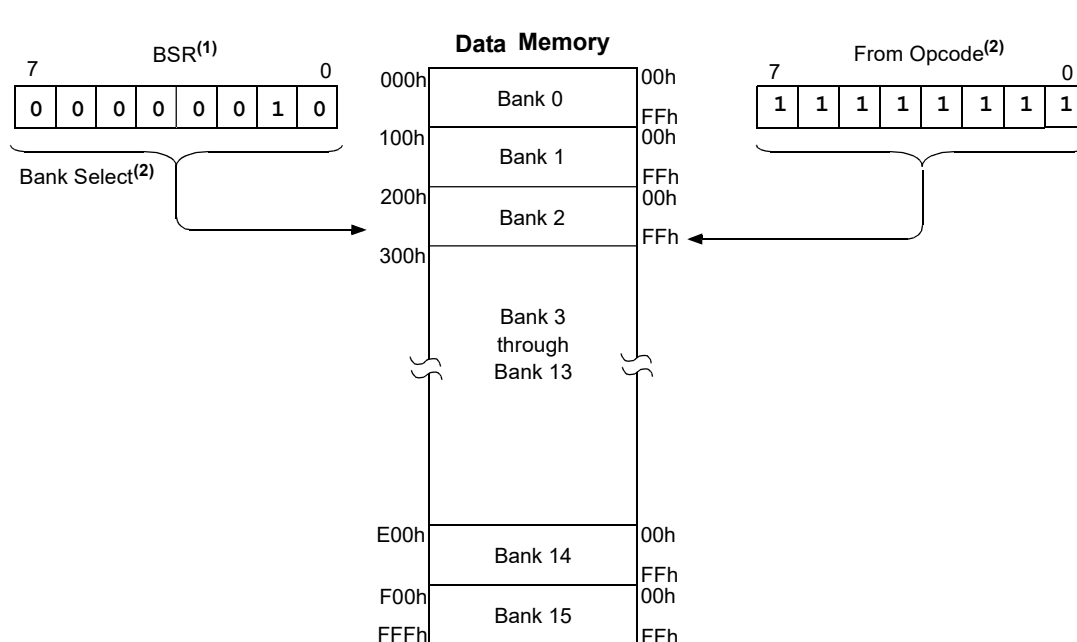
relationship between the BSR's value and the bank division in data memory is shown in the figure below.

Since up to 16 registers may share the same low-order address, the user must always be careful to ensure that the proper bank is selected before performing a data read or write. For example, writing what should be program data to an 8-bit address of F9h while the BSR is 0Fh will end up resetting the Program Counter.

While any bank can be selected, only those banks that are actually implemented can be read or written to. Writes to unimplemented banks are ignored, while reads from unimplemented banks will return '0's. Even so, the STATUS register will still be affected as if the operation was successful. The data memory maps in the following figure indicate which banks are implemented.

In the core PIC18 instruction set, only the `MOVF` instruction fully specifies the 12-bit address of the source and target registers. This instruction ignores the BSR completely when it executes. All other instructions include only the low-order address as an operand and must use either the BSR or the Access Bank to locate their target registers.

Figure 11-9. Use of the Bank Select Register (Direct Addressing)



Notes 1: The Access RAM bit of the instruction can be used to force an override of the selected bank (BSR[3:0]) to the registers of the Access Bank.

2: The `MOVF` instruction embeds the entire 12-bit address in the instruction.

11.3.2 Access Bank

While the use of the BSR with an embedded 8-bit address allows users to address the entire range of data memory, it also means that the user must always ensure that the correct bank is selected. Otherwise, data may be read from or written to the wrong location. This can be disastrous if a GPR is the intended target of an operation, but an SFR is written to instead. Verifying and/or changing the BSR for each read or write to data memory can become very inefficient.

To streamline access for the most commonly used data memory locations, the data memory is configured with an Access Bank, which allows users to access a mapped block of memory without specifying a BSR. The Access Bank consists of the first 96 bytes of memory (00h-5Fh) in Bank 0 and the last 160 bytes of memory (60h-FFh) in Block 15. The lower half is known as the "Access RAM" and is composed of GPRs. This upper half is also where the device's SFRs are mapped. These two areas

are mapped contiguously in the Access Bank and can be addressed in a linear fashion by an 8-bit address (see [Data Memory Map](#)).

The Access Bank is used by core PIC18 instructions that include the Access RAM bit (the 'a' parameter in the instruction). When 'a' is equal to '1', the instruction uses the BSR and the 8-bit address included in the opcode for the data memory address. When 'a' is '0', however, the instruction is forced to use the Access Bank address map; the current value of the BSR is ignored entirely.

Using this “forced” addressing allows the instruction to operate on a data address in a single cycle, without updating the BSR first. For 8-bit addresses of 60h and above, this means that users can evaluate and operate on SFRs more efficiently. The Access RAM below 60h is a good place for data values that the user might need to access rapidly, such as immediate computational results or common program variables. Access RAM also allows for faster and more code efficient context saving and switching of variables.

The mapping of the Access Bank is slightly different when the extended instruction set is enabled (XINST Configuration bit = 1). This is discussed in more detail in the [Mapping the Access Bank in Indexed Literal Offset Mode](#) section.

11.3.3 General Purpose Register File

PIC18 devices may have banked memory in the GPR area. This is data RAM, which is available for use by all instructions. GPRs start at the bottom of Bank 0 (address 000h) and grow upwards towards the bottom of the SFR area. GPRs are not initialized by a Power-on Reset and are unchanged on all other Resets.

11.3.4 Special Function Registers

The Special Function Registers (SFRs) are registers used by the CPU and peripheral modules for controlling the desired operation of the device. These registers are implemented as static RAM. SFRs start at the top of data memory (FFFh) and extend downward. A list of these registers is given in the register summary table.

The SFRs can be classified into two sets: those associated with the “core” device functionality (ALU, Resets and interrupts) and those related to the peripheral functions. The Reset and Interrupt registers are described in their respective chapters, while the ALU's STATUS register is described later in this section. Registers related to the operation of a peripheral feature are described in the chapter for that peripheral.

The SFRs are typically distributed among the peripherals whose functions they control. Unused SFR locations are unimplemented and read as '0's.

Related Links

[Register Summary](#)


11.3.5 Status Register

The [STATUS](#) register contains the arithmetic status of the ALU. As with any other SFR, it can be the operand for any instruction.

If the STATUS register is the destination for an instruction that affects the Z, DC, C, OV or N bits, the results of the instruction are not written; instead, the STATUS register is updated according to the instruction performed. Therefore, the result of an instruction with the STATUS register as its destination may be different than intended. As an example, `CLRF STATUS` will set the Z bit and leave the remaining Status bits unchanged ('000u u1uu').

It is recommended that only `BCF`, `BSF`, `SWAPF`, `MOVFF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect the Z, C, DC, OV or N bits in the STATUS register.


For other instructions that do not affect Status bits, see the instruction set summaries.

 **Important:** The C and DC bits operate as the Borrow and Digit Borrow bits, respectively, in subtraction.

Related Links

[Instruction Set Summary](#)

11.4 Data Addressing Modes

 **Important:** The execution of some instructions in the core PIC18 instruction set are changed when the PIC18 extended instruction set is enabled. See [Data Memory and the Extended Instruction Set](#) for more information.

Information in the data memory space can be addressed in several ways. For most instructions, the Addressing mode is fixed. Other instructions may use up to three modes, depending on which operands are used and whether or not the extended instruction set is enabled.

The Addressing modes are:

- Inherent
- Literal
- Direct
- Indirect

An additional Addressing mode, Indexed Literal Offset, is available when the extended instruction set is enabled (XINST Configuration bit = 1). Its operation is discussed in greater detail in [Indexed Addressing with Literal Offset](#).

11.4.1 Inherent and Literal Addressing

Many PIC18 control instructions do not need any argument at all; they either perform an operation that globally affects the device or they operate implicitly on one register. This Addressing mode is known as Inherent Addressing. Examples include `SLEEP`, `RESET` and `DAW`.

Other instructions work in a similar way but require an additional explicit argument in the opcode. This is known as Literal Addressing mode because they require some literal value as an argument. Examples include `ADDLW` and `MOVLW`, which respectively, add or move a literal value to the W register. Other examples include `CALL` and `GOTO`, which include a 20-bit program memory address.

11.4.2 Direct Addressing

Direct Addressing specifies all or part of the source and/or destination address of the operation within the opcode itself. The options are specified by the arguments accompanying the instruction.

In the core PIC18 instruction set, bit-oriented and byte-oriented instructions use some version of Direct Addressing by default. All of these instructions include some 8-bit literal address as their Least Significant Byte. This address specifies either a register address in one of the banks of data RAM (see [General Purpose Register File](#)) or a location in the Access Bank (see [Access Bank](#)) as the data source for the instruction.

The Access RAM bit 'a' determines how the address is interpreted. When 'a' is '1', the contents of the BSR (see [Bank Select Register](#)) are used with the address to determine the complete 12-bit address of the register. When 'a' is '0', the address is interpreted as being a register in the Access Bank. Addressing that uses the Access RAM is sometimes also known as Direct Forced Addressing mode.

A few instructions, such as `MOVFF`, include the entire 12-bit address (either source or destination) in their opcodes. In these cases, the BSR is ignored entirely.

The destination of the operation's results is determined by the destination bit 'd'. When 'd' is '1', the results are stored back in the source register, overwriting its original contents. When 'd' is '0', the results are stored in the W register. Instructions without the 'd' argument have a destination that is implicit in the instruction; their destination is either the target register being operated on or the W register.

11.4.3 Indirect Addressing

Indirect Addressing allows the user to access a location in data memory without giving a fixed address in the instruction. This is done by using File Select Registers (FSRs) as pointers to the locations which are to be read or written. Since the FSRs are themselves located in RAM as Special File Registers, they can also be directly manipulated under program control. This makes FSRs very useful in implementing data structures, such as tables and arrays in data memory.

The registers for Indirect Addressing are also implemented with Indirect File Operands (INDFs) that permit automatic manipulation of the pointer value with auto-incrementing, auto-decrementing or offsetting with another value. This allows for efficient code, using loops, such as the following example of clearing an entire RAM bank.

Example 11-3. How to Clear RAM (Bank 1) Using Indirect Addressing

```

NEXT:    LFSR    FSR0,100h    ; Set FSR0 to beginning of Bank1
        CLRF    POSTINC0     ; Clear location in Bank1 then increment FSR0

        BTFSS   FSR0H,1      ; Has high FSR0 byte incremented to next bank?
        BRA     NEXT         ; NO, clear next byte in Bank1

CONTINUE:                ; YES, continue

```

11.4.3.1 FSR Registers and the INDF Operand

At the core of Indirect Addressing are three sets of registers: FSR0, FSR1 and FSR2. Each represents a pair of 8-bit registers, FSRnH and FSRnL. Each FSR pair holds a 12-bit value, therefore, the four upper bits of the FSRnH register are not used. The 12-bit FSR value can address the entire range of the data memory in a linear fashion. The FSR register pairs, then, serve as pointers to data memory locations.

Indirect Addressing is accomplished with a set of Indirect File Operands, INDF0 through INDF2. These can be thought of as “virtual” registers; they are mapped in the SFR space but are not physically implemented. Reading or writing to a particular INDF register actually accesses its corresponding FSR register pair. A read from INDF1, for example, reads the data at the address indicated by FSR1H:FSR1L. Instructions that use the INDF registers as operands actually use the contents of their corresponding FSR as a pointer to the instruction's target. The INDF operand is just a convenient way of using the pointer.

Because Indirect Addressing uses a full 12-bit address, the FSR value can target any location in any bank regardless of the BSR value. However, the Access RAM bit must be cleared to 0 to ensure that the INDF register in Access space is the object of the operation instead of a register in one of the other banks. The assembler default value for the Access RAM bit is zero when targeting any of the indirect operands.

11.4.3.2 FSR Registers and POSTINC, POSTDEC, PREINC and PLUSW

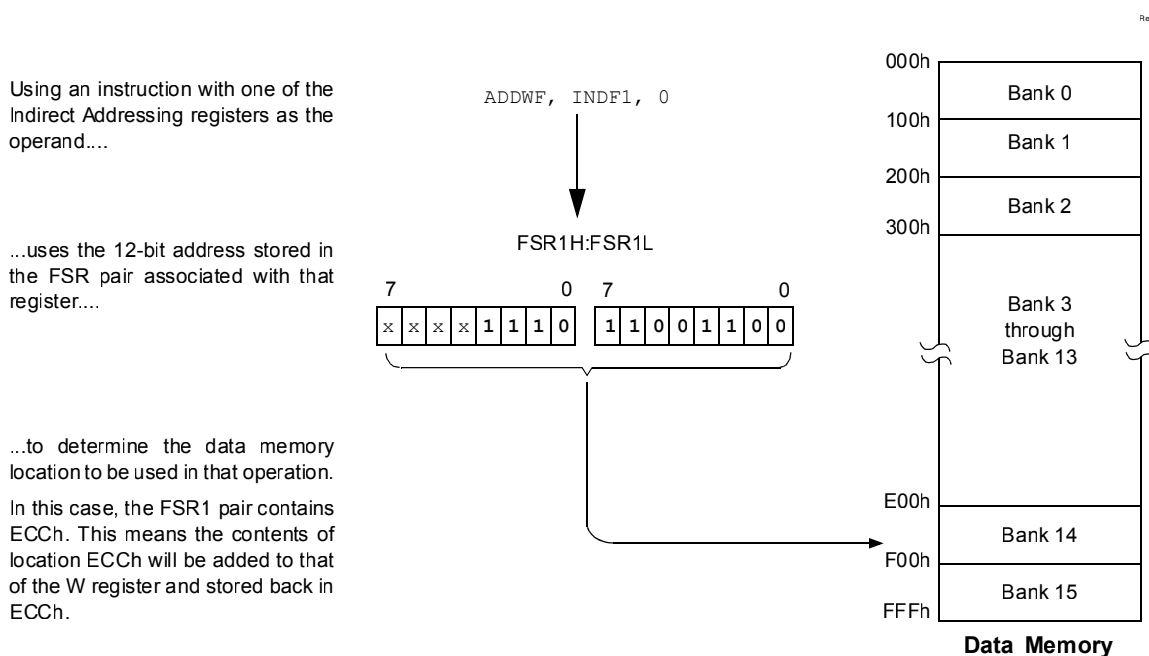
In addition to the INDF operand, each FSR register pair also has four additional indirect operands. Like INDF, these are “virtual” registers that cannot be directly read or written. Accessing these registers actually accesses the location to which the associated FSR register pair points, and also performs a specific action on the FSR value. They are:

- POSTDEC: accesses the location to which the FSR points, then automatically decrements the FSR by 1 afterwards

- **POSTINC:** accesses the location to which the FSR points, then automatically increments the FSR by 1 afterwards
- **PREINC:** automatically increments the FSR by one, then uses the location to which the FSR points in the operation
- **PLUSW:** adds the signed value of the W register (range of -127 to 128) to that of the FSR and uses the location to which the result points in the operation

In this context, accessing an INDF register uses the value in the associated FSR register without changing it. Similarly, accessing a PLUSW register gives the FSR value an offset by that in the W register; however, neither W nor the FSR is actually changed in the operation. Accessing the other virtual registers changes the value of the FSR register.

Figure 11-10. Indirect Addressing



Operations on the FSRs with **POSTDEC**, **POSTINC** and **PREINC** affect the entire register pair; that is, rollovers of the `FSRnL` register from `FFh` to `00h` carry over to the `FSRnH` register. On the other hand, results of these operations do not change the value of any flags in the STATUS register (e.g., Z, N, OV, etc.).

The **PLUSW** register can be used to implement a form of Indexed Addressing in the data memory space. By manipulating the value in the W register, users can reach addresses that are fixed offsets from pointer addresses. In some applications, this can be used to implement some powerful program control structure, such as software stacks, inside of data memory.

11.4.3.3 Operations by FSRs on FSRs

Indirect Addressing operations that target other FSRs or virtual registers represent special cases. For example, using an FSR to point to one of the virtual registers will not result in successful operations. As a specific case, assume that `FSR0H:FSR0L` contains the address of `INDF1`. Attempts to read the value of the `INDF1` using `INDF0` as an operand will return `00h`. Attempts to write to `INDF1` using `INDF0` as the operand will result in a **NOP**.

On the other hand, using the virtual registers to write to an FSR pair may not occur as planned. In these cases, the value will be written to the FSR pair but without any incrementing or decrementing. Thus, writing to either the `INDF2` or `POSTDEC2` register will write the same value to the `FSR2H:FSR2L`.

Since the FSRs are physical registers mapped in the SFR space, they can be manipulated through all direct operations. The users must proceed cautiously when working on these registers, particularly if their code uses Indirect Addressing.

Similarly, operations by Indirect Addressing are permitted on all other SFRs. The users must exercise the appropriate caution that they do not inadvertently change settings that might affect the operation of the device.

11.5 Data Memory and the Extended Instruction Set

Enabling the PIC18 extended instruction set (XINST Configuration bit = 1) significantly changes certain aspects of data memory and its addressing. Specifically, the use of the Access Bank for many of the core PIC18 instructions is different; this is due to the introduction of a new Addressing mode for the data memory space.

What does not change is just as important. The size of the data memory space is unchanged, as well as its linear addressing. The SFR map remains the same. Core PIC18 instructions can still operate in both Direct and Indirect Addressing mode; inherent and literal instructions do not change at all. Indirect addressing with FSR0 and FSR1 also remain unchanged.

11.5.1 Indexed Addressing with Literal Offset

Enabling the PIC18 extended instruction set changes the behavior of Indirect Addressing using the FSR2 register pair within Access RAM. Under the proper conditions, instructions that use the Access Bank – that is, most bit-oriented and byte-oriented instructions – can invoke a form of Indexed Addressing using an offset specified in the instruction. This special Addressing mode is known as Indexed Addressing with Literal Offset, or Indexed Literal Offset mode.

When using the extended instruction set, this Addressing mode requires the following:

- The use of the Access Bank is forced ('a' = 0) and
- The file address argument is less than or equal to 5Fh

Under these conditions, the file address of the instruction is not interpreted as the lower byte of an address (used with the BSR in Direct Addressing), or as an 8-bit address in the Access Bank. Instead, the value is interpreted as an offset value to an Address Pointer, specified by FSR2. The offset and the contents of FSR2 are added to obtain the target address of the operation.

11.5.2 Instructions Affected by Indexed Literal Offset Mode

Any of the core PIC18 instructions that can use Direct Addressing are potentially affected by the Indexed Literal Offset Addressing mode. This includes all byte-oriented and bit-oriented instructions, or almost one-half of the standard PIC18 instruction set. Instructions that only use Inherent or Literal Addressing modes are unaffected.

Additionally, byte-oriented and bit-oriented instructions are not affected if they do not use the Access Bank (Access RAM bit is '1'), or include a file address of 60h or above. Instructions meeting these criteria will continue to execute as before. A comparison of the different possible Addressing modes when the extended instruction set is enabled is shown in the following figure.

Those who desire to use byte-oriented or bit-oriented instructions in the Indexed Literal Offset mode must note the changes to assembler syntax for this mode. This is described in more detail in the **"Extended Instruction Syntax"** section.

Figure 11-11. Comparing Addressing Options for Bit-Oriented and Byte-Oriented Instructions (Extended Instruction Set Enabled)

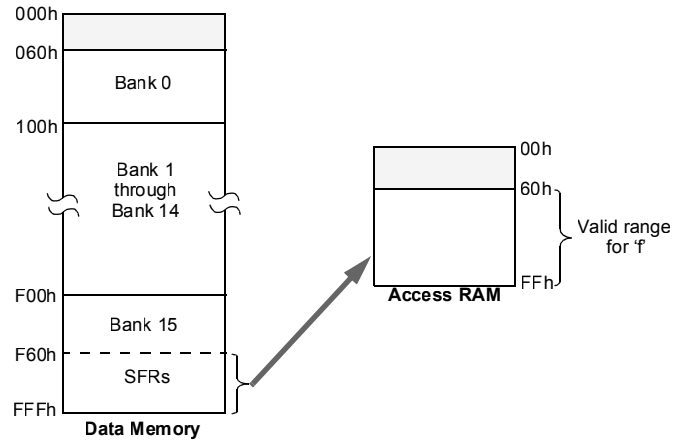
EXAMPLE INSTRUCTION: `ADDWF, f, d, a` (Opcode: `0010 01da ffff ffff`)

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When 'a' = 0 and f ≥ 60h:

The instruction executes in Direct Forced mode. 'f' is interpreted as a location in the Access RAM between 060h and 0FFh. This is the same as locations F60h to FFFh (Bank 15) of data memory.

Locations below 60h are not available in this addressing mode.

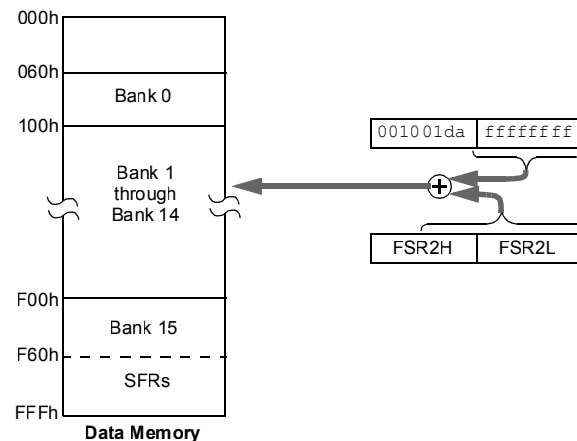


When 'a' = 0 and f ≤ 5Fh:

The instruction executes in Indexed Literal Offset mode. 'f' is interpreted as an offset to the address value in FSR2. The two are added together to obtain the address of the target register for the instruction. The address can be anywhere in the data memory space.

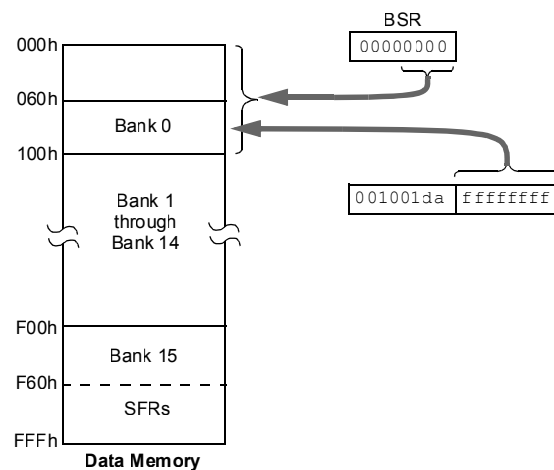
Note that in this mode, the correct syntax is now:

`ADDWF [k], d`
where 'k' is the same as 'f'.



When 'a' = 1 (all values of f):

The instruction executes in Direct mode (also known as Direct Long mode). 'f' is interpreted as a location in one of the 16 banks of the data memory space. The bank is designated by the Bank Select Register (BSR). The address can be in any implemented bank in the data memory space.



Related Links

[Extended Instruction Syntax](#)

11.5.3 Mapping the Access Bank in Indexed Literal Offset Mode

The use of Indexed Literal Offset Addressing mode effectively changes how the first 96 locations of Access RAM (00h to 5Fh) are mapped. Rather than containing just the contents of the bottom section of Bank 0, this mode maps the contents from a user defined “window” that can be located anywhere in the data memory space. The value of FSR2 establishes the lower boundary of the addresses mapped into the window, while the upper boundary is defined by FSR2 plus 95 (5Fh). Addresses in the Access RAM above 5Fh are mapped as previously described (see [Access Bank](#)). An example of Access Bank remapping in this Addressing mode is shown in the following figure.

Figure 11-12. Remapping the Access Bank with Indexed Literal Offset Addressing

Example Situation:

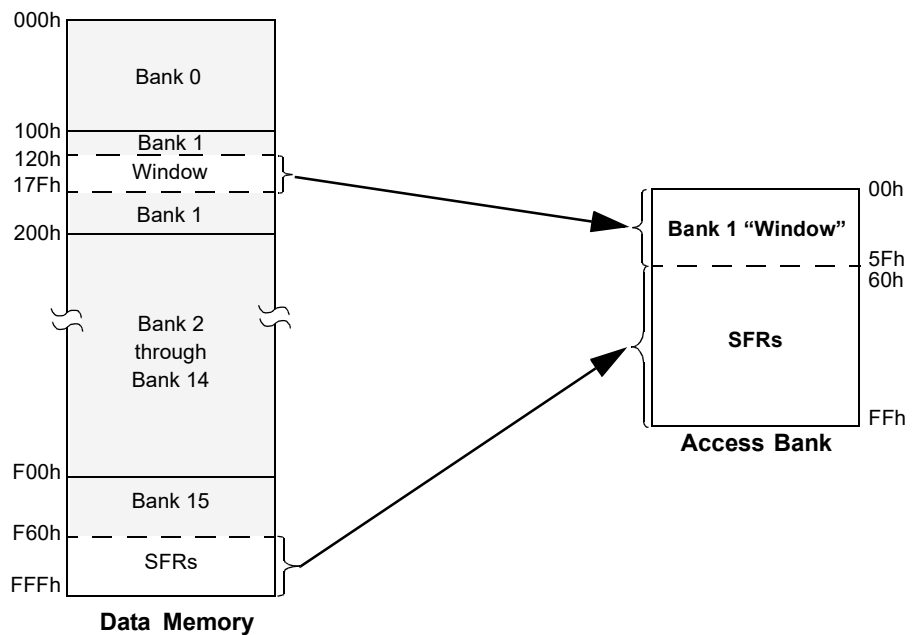
```
ADDWF f, d, a
```

```
FSR2H:FSR2L = 120h
```

Locations in the region from the FSR2 pointer (120h) to the pointer plus 05Fh (17Fh) are mapped to the bottom of the Access RAM (000h-05Fh).

Special File Registers at F60h through FFFh are mapped to 60h through FFh, as usual.

Bank 0 addresses below 5Fh can still be addressed by using the BSR.



Remapping of the Access Bank applies only to operations using the Indexed Literal Offset mode. Operations that use the BSR (Access RAM bit is '1') will continue to use Direct Addressing as before.

11.6 PIC18 Instruction Execution and the Extended Instruction Set

Enabling the extended instruction set adds eight additional commands to the existing PIC18 instruction set. These instructions are executed as described in the Extended Instruction Set section.

Related Links

[Extended Instruction Syntax](#)

11.7 Register Summary - Memory and Status

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------|----------|----------|--------------|----|----|---|----|---|----|---|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0FD7 | | | | | | | | | | |
| 0x0FD8 | STATUS | 7:0 | | TO | PD | N | OV | Z | DC | C |
| 0x0FD9 | FSR2 | 7:0 | FSRL[7:0] | | | | | | | |
| | | 15:8 | FSRH[3:0] | | | | | | | |
| 0x0FDB | PLUSW2 | 7:0 | PLUSW[7:0] | | | | | | | |
| 0x0FDC | PREINC2 | 7:0 | PREINC[7:0] | | | | | | | |
| 0x0FDD | POSTDEC2 | 7:0 | POSTDEC[7:0] | | | | | | | |
| 0x0FDE | POSTINC2 | 7:0 | POSTINC[7:0] | | | | | | | |
| 0x0FDF | INDF2 | 7:0 | INDF[7:0] | | | | | | | |
| 0x0FE0 | BSR | 7:0 | BSR[3:0] | | | | | | | |
| 0x0FE1 | FSR1 | 7:0 | FSRL[7:0] | | | | | | | |
| | | 15:8 | FSRH[3:0] | | | | | | | |
| 0x0FE3 | PLUSW1 | 7:0 | PLUSW[7:0] | | | | | | | |
| 0x0FE4 | PREINC1 | 7:0 | PREINC[7:0] | | | | | | | |
| 0x0FE5 | POSTDEC1 | 7:0 | POSTDEC[7:0] | | | | | | | |
| 0x0FE6 | POSTINC1 | 7:0 | POSTINC[7:0] | | | | | | | |
| 0x0FE7 | INDF1 | 7:0 | INDF[7:0] | | | | | | | |
| 0x0FE8 | WREG | 7:0 | WREG[7:0] | | | | | | | |
| 0x0FE9 | FSR0 | 7:0 | FSRL[7:0] | | | | | | | |
| | | 15:8 | FSRH[3:0] | | | | | | | |
| 0x0FEB | PLUSW0 | 7:0 | PLUSW[7:0] | | | | | | | |
| 0x0FEC | PREINC0 | 7:0 | PREINC[7:0] | | | | | | | |
| 0x0FED | POSTDEC0 | 7:0 | POSTDEC[7:0] | | | | | | | |
| 0x0FEE | POSTINC0 | 7:0 | POSTINC[7:0] | | | | | | | |
| 0x0FEF | INDF0 | 7:0 | INDF[7:0] | | | | | | | |
| 0x0FF0 ... | Reserved | | | | | | | | | |
| 0x0FF8 | | | | | | | | | | |
| 0x0FF9 | PCL | 7:0 | PCL[7:0] | | | | | | | |
| 0x0FFA | PCLAT | 7:0 | PCLATH[7:0] | | | | | | | |
| | | 15:8 | PCLATU[4:0] | | | | | | | |
| 0x0FFC | STKPTR | 7:0 | STKPTR[4:0] | | | | | | | |
| 0x0FFD | TOS | 7:0 | TOSL[7:0] | | | | | | | |
| | | 15:8 | TOSH[7:0] | | | | | | | |
| | | 23:16 | TOSU[4:0] | | | | | | | |

11.8 Register Definitions: Memory and Status

11.8.1 PCL

Name: PCL
Address: 0xFF9

Low byte of the Program Counter

| | | | | | | | | |
|--------|----------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PCL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – PCL[7:0]
Provides direct read and write access to the Program Counter

11.8.2 PCLAT

Name: PCLAT
Address: 0xFFA

Program Counter Latches. Holding register for bits [21:9] of the Program Counter (PC). Reads of the PCL register transfer the upper PC bits to the PCLAT register. Writes to PCL register transfer the PCLAT value to the PC.

| | | | | | | | | |
|--------|-------------|----|----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | PCLATU[4:0] | | | | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PCLATH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 12:8 – PCLATU[4:0] Upper PC Latch register
Holding register for Program Counter bits [21:17]

Bits 7:0 – PCLATH[7:0] High PC Latch register
Holding register for Program Counter bits [16:8]

11.8.3 TOS

Name: TOS
Address: 0xFFD

Top-Of-Stack Registers.

Contents of the stack pointed to by the [STKPTR](#) register. This is the value that will be loaded into the Program Counter upon a `RETURN` or `RETFIE` instruction.

| | | | | | | | | |
|--------|-----------|-----|-----|-----------|-----|-----|-----|-----|
| Bit | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | | | | TOSU[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | TOSH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TOSL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 20:16 – TOSU[4:0] Upper byte of TOS register
Bits [21:17] of the TOS

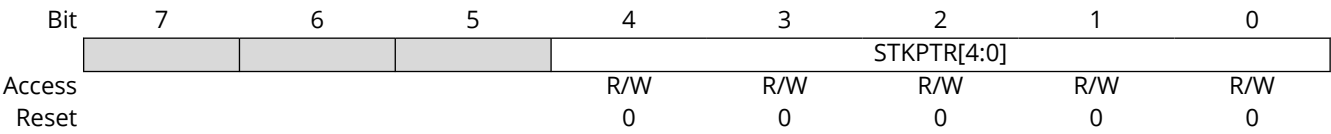
Bits 15:8 – TOSH[7:0] High Byte of the TOS Register
Bits [16:8] of the TOS

Bits 7:0 – TOSL[7:0] Low Byte TOS Register
Bits [7:0] of the TOS

11.8.4 STKPTR

Name: STKPTR
Address: 0xFFC

Stack Pointer Register



Bits 4:0 – STKPTR[4:0] Stack Pointer Location bits

11.8.5 STATUS

Name: STATUS
Address: 0xFD8

Status Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|----|----|-----|-----|-----|-----|-----|
| | | TO | PD | N | OV | Z | DC | C |
| Access | | R | R | R/W | R/W | R/W | R/W | R/W |
| Reset | | 1 | 1 | 0 | 0 | 0 | 0 | 0 |

Bit 6 – TO Time-Out bit

Reset States: POR/BOR = 1
All Other Resets = q

| Value | Description |
|-------|--|
| 1 | Set at power-up or by execution of CLRWDT or SLEEP instruction |
| 0 | A WDT time-out occurred |

Bit 5 – PD Power-Down bit

Reset States: POR/BOR = 1
All Other Resets = q

| Value | Description |
|-------|---|
| 1 | Set at power-up or by execution of CLRWDT instruction |
| 0 | Cleared by execution of the SLEEP instruction |

Bit 4 – N Negative bit

Used for signed arithmetic (two's complement); indicates if the result is negative (ALU MSb = 1).

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|------------------------|
| 1 | The result is negative |
| 0 | The result is positive |

Bit 3 – OV Overflow bit

Used for signed arithmetic (two's complement); indicates an overflow of the 7-bit magnitude, which causes the sign bit (bit 7) to change state.

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | Overflow occurred for current signed arithmetic operation |
| 0 | No overflow occurred |

Bit 2 – Z Zero bit

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|--|
| 1 | The result of an arithmetic or logic operation is zero |
| 0 | The result of an arithmetic or logic operation is not zero |

Bit 1 – DC Digit Carry/Borrow bit

ADDWF, ADDLW, SUBLW, SUBWF instructions⁽¹⁾

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | A carry-out from the 4th low-order bit of the result occurred |
| 0 | No carry-out from the 4th low-order bit of the result |

Bit 0 – C Carry/Borrow bit

ADDWF, ADDLW, SUBLW, SUBWF instructions^(1,2)

Reset States: POR/BOR = 0
All Other Resets = u

| Value | Description |
|-------|---|
| 1 | A carry-out from the Most Significant bit of the result occurred |
| 0 | No carry-out from the Most Significant bit of the result occurred |

Notes:

1. For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand.
2. For Rotate (RRCF, RLCF) instructions, this bit is loaded with either the high or low-order bit of the Source register.

11.8.6 WREG

Name: WREG
Address: 0xFE8

Shadow of Working Data Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|-----|-----|-----|-----|-----|-----|-----|
| | WREG[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 7:0 – WREG[7:0]

11.8.7 INDF

Name: INDFx
Address: 0xFE7, 0xFE7, 0xFDF

Indirect Data Register. This is a virtual register. The GPR/SFR register addressed by the FSRx register is the target for all operations involving the INDFx register.

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|-----|-----|-----|-----|-----|-----|-----|
| | INDF[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – INDF[7:0]

Indirect data pointed to by the FSRx register

11.8.8 POSTDEC

Name: POSTDECx
Address: 0xFED,0xFE5,0xFDD

Indirect Data Register with post decrement. This is a virtual register. The GPR/SFR register addressed by the FSRx register is the target for all operations involving the POSTDECx register. FSRx is decremented after the read or write operation.

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | POSTDEC[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – POSTDEC[7:0]

11.8.9 POSTINC

Name: POSTINCx
Address: 0xFEE,0xFE6,0xFDE

Indirect Data Register with post increment. This is a virtual register. The GPR/SFR register addressed by the FSRx register is the target for all operations involving the POSTINCx register. FSRx is incremented after the read or write operation.

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| | POSTINC[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – POSTINC[7:0]

11.8.10 PREINC

Name: PREINCx
Address: 0xFEC,0xFE4,0xFDC

Indirect Data Register with pre-increment. This is a virtual register. The GPR/SFR register addressed by the FSRx register plus 1 is the target for all operations involving the PREINCx register. FSRx is incremented before the read or write operation.

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| | PREINC[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – PREINC[7:0]

11.8.11 PLUSW

Name: PLUSWx
Address: 0xFEB,0xFE3,0xFDB

Indirect Data Register with WREG offset. This is a virtual register. The GPR/SFR register addressed by the sum of the FSRx register plus the signed value of the W register is the target for all operations involving the PLUSWx register.

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PLUSW[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – PLUSW[7:0]

11.8.12 FSR

Name: FSRx
Address: 0xFE9, 0xFE1, 0xFD9

Indirect Address Register. The FSR value is the address of the data to which the INDF register points.

| | | | | | | | | |
|--------|-----------|-----|-----|-----|-----------|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | | | | | FSRH[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | FSRL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 11:8 – FSRH[3:0]

Most Significant address of INDF data

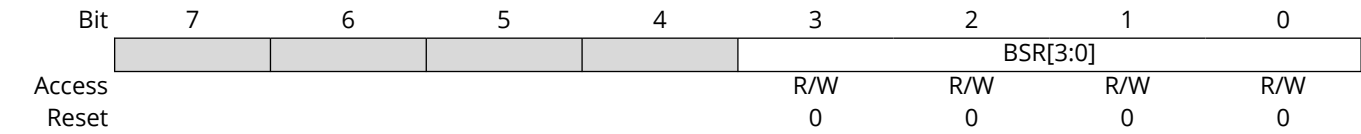
Bits 7:0 – FSRL[7:0]

Least Significant address of INDF data

11.8.13 BSR

Name: BSR
Address: 0xFE0

Bank Select Register
The BSR indicates the data memory bank which is bits 11:8 of the GPR address.



Bits 3:0 – BSR[3:0]
Four Most Significant bits of the data memory address

12. NVM - Nonvolatile Memory Control

Nonvolatile memory is separated into three categories: Program Flash Memory (PFM) including User IDs, Configuration Words and Data Flash Memory (DFM). DFM is also referred to as EEPROM because it is written one byte at a time and the erase before write is automatic. Although User IDs are above the PFM section, they are included in the PFM category because the read and write access is identical for both.

The write and erase times are controlled by an on-chip timer. The write and erase voltages are generated by an on-chip charge pump rated to function over the operating voltage range of the device.

PFM and DFM can be protected in two ways: code protection and write protection. Code protection (Configuration bits \overline{CP} for PFM and \overline{CPD} for DFM) disables read and write access through an external device programmer. Code protection does not affect the self-write and erase functionality, whereas write protection does. Code protection write protection can only be reset by a Bulk Erase performed by an external device programmer. A PFM Bulk Erase clears the program space, Configuration bits and User IDs. A Bulk Erase only clears DFM if the $\overline{CPD} = 0$. When $\overline{CPD} = 1$, then bulk erasing DFM requires setting the Program Counter to the DFM area before the Bulk Erase command is issued, and then only the DFM area is cleared. See the programming specification for more details. Write protection prevents writes to NVM areas tagged for protection by the WRTn Configuration bits. Attempts to write a protected location will set the NVMERR bit.

PFM and Configuration Words can be accessed by either the Table Pointer or NVM controls. DFM can be accessed only by the NVM controls. The PFM access is by single byte, single word or full sector. A sector is 256 bytes (128 PFM words). The sector memory occupies one full bank of RAM space located in the RAM bank following the last occupied GPR bank. Sector memory is also referred to elsewhere in this document as the write block holding registers. The Table Pointer accesses memory by bytes. The NVM control accesses the DFM section by bytes and the other sections by words and sectors.

The NVM controls include five independent access functions with five corresponding control bits. The controls are as follows:

- RD – Single byte/word read
- WR – single byte/word write
- SECRD – Sector read
- SECWR – Sector write
- SECER – Sector erase

The NVMADR registers determine the address of the memory region being accessed by the NVM control. The TBLPTR registers determine the address of the memory being accessed by the Table Pointer functions. The following table indicates which controls operate in each region.

Table 12-1. NVM Organization Table

| Region | Address Range | Table Pointer TBLRD | NVMCON1 | | | | |
|----------|----------------------|---------------------|---------|----|-------|-------|-------|
| | | | RD | WR | SECRD | SECWR | SECER |
| PFM | 00 0000h 01 FFFFh | • | • | • | • | • | • |
| User IDs | 20 0000h 20 00FFh | • | • | • | • | • | • |
| CONFIG | 30 0000h 30 000Bh | • | • | | • | • | |
| DFM | 31 0000h 31 00FFh | | • | • | | | |

12.1 Program Flash Memory

The Program Flash Memory is readable, writable, and erasable during normal operation over the entire V_{DD} range.

A read from program memory is executed one byte at a time. A program memory erase is executed on blocks of n bytes at a time, also referred to as sectors. Refer to the following table for write and erase block sizes. A Bulk Erase operation cannot be issued from user code. A write to program memory can be executed by sectors or single words.

Table 12-2. Flash Memory Organization by Device

| Device | Sector Erase Size (Words) | Holding Registers (Bytes) | TBLPTR LSBs (Holding Address) | Program Flash Memory (Words) | Data Flash Memory (Bytes) |
|-------------|---------------------------|---------------------------|-------------------------------|------------------------------|---------------------------|
| PIC18F26Q10 | 128 | 256 | 8 | 32768 | 1024 |
| PIC18F46Q10 | | | | | |
| PIC18F45Q10 | | | | 16384 | 256 |

Writing or erasing program memory will cease instruction fetches until the operation is complete. The program memory cannot be accessed during the write or erase, therefore, code cannot execute. An internal programming timer terminates program memory writes and erases.

A value written to program memory does not need to be a valid instruction. Executing a program memory location that forms an invalid instruction results in a `NOP`.

It is important to understand the PFM memory structure for erase and programming operations. Program memory word size is 16 bits wide. PFM is arranged in sectors. A sector is the minimum size that can be erased by user software.

After a sector has been erased, all or a portion of this sector can be programmed. Data can be written directly into PFM one 16-bit word at a time using the `NVMADR` and `NVMCON1` controls or as a full sector from sector RAM, which is also referred to as the holding registers. These 8-bit registers are located in the RAM bank following the last GPR RAM bank. The holding registers are directly accessible as any other SFR/GPR register and also may be loaded via sequential writes using the `TBLAT` and `TBLPTR` registers.



Important: To modify only a portion of a previously programmed sector the contents of the entire sector must be read and saved in RAM prior to the sector erase. The `SECRD` operation is the easiest way to do this. Then, the new data can be written into the holding registers to reprogram the sector of PFM. However, any unprogrammed locations can be written using the single word write operation without first erasing the sector.

12.1.1 Table Pointer Operations

To read and write program memory, there are two operations that allow the processor to move bytes between the program memory space and the data RAM:

- Table Read (`TBLRD*`)
- Table Write (`TBLWT*`)

The SFR registers associated with these operations include:

- `TBLAT` register
- `TBLPTR` registers

The program memory space is 16 bits wide, while the data RAM space is eight bits wide. The `TBLPTR` registers determine the address of one byte of the NVM memory. Table reads move one byte of

data from NVM space to the TABLAT register and table writes move the TABLAT data to a holding register ready for a subsequent write to NVM space with the NVM controls.

12.1.1.1 Table Pointer Register

The Table Pointer (**TBLPTR**) register addresses a byte within the program memory. The TBLPTR comprises three SFR registers: Table Pointer Upper Byte, Table Pointer High Byte and Table Pointer Low Byte (TBLPTRU:TBLPTRH:TBLPTRL). These three registers join to form a 22-bit wide pointer (bits 0 through 21). The bits 0 through 20 allow the device to address up to 2 Mbytes of program memory space. Bit 21 allows access to the Device ID, the User ID and the Configuration bits.

The Table Pointer register, TBLPTR, is used by the **TBLRD** and **TBLWT** instructions. These instructions can increment and decrement the TBLPTR depending on specific appended characters as shown in the following table. The increment and decrement operations on the TBLPTR affect only bits 0 through 20.

Table 12-3. Table Pointer Operations with **TBLRD** and **TBLWT** Instructions

| Example | Operation on Table Pointer |
|--------------------|---|
| TBLRD* TBLWT* | TBLPTR is not modified |
| TBLRD*+ TBLWT*+ | TBLPTR is incremented after the read/write |
| TBLRD*- TBLWT*- | TBLPTR is decremented after the read/write |
| TBLRD+* TBLWT+* | TBLPTR is incremented before the read/write |

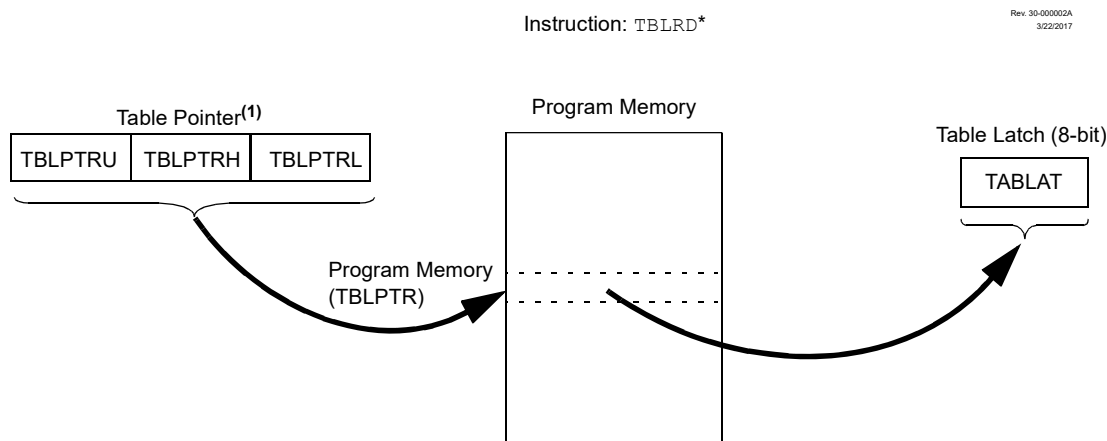
12.1.1.2 Table Latch Register

The Table Latch (**TABLAT**) is an 8-bit register mapped into the SFR space. The Table Latch register receives one byte of NVM data resulting from a **TBLRD*** instruction and is the source of the 8-bit data sent to the holding register space as a result of a **TBLWT*** instruction.

12.1.1.3 Table Read Operations

The table read operation retrieves one byte of data directly from program memory pointed to by the TBLPTR registers and places it into the TABLAT register. **Figure 12-1** shows the operation of a table read.

Figure 12-1. Table Read Operation

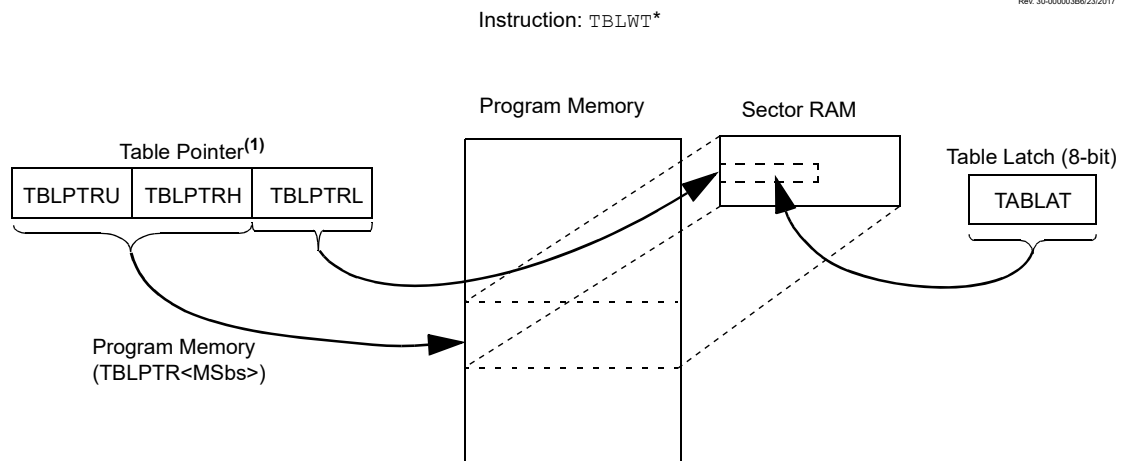


Note 1: Table Pointer register points to a byte in program memory.

12.1.1.4 Table Write Operations

The table write operation stores one byte of data from the TABLAT register into a sector RAM holding register. The following figure shows the operation of a table write from the TABLAT register to the holding register space. The procedure to write the contents of the holding registers into program memory is detailed in the **"Writing to Program Flash Memory"** section.

Figure 12-2. Table Write Operation



Note 1: During table writes the Table Pointer points to two areas. The LSbs of TBLPTRL point to an address within the sector RAM space. The MSbs of the Table Pointer determine where the sector will eventually be written.

Table operations work with byte entities. Tables containing data, rather than program instructions, are not required to be word-aligned. Therefore, a table can start and end at any byte address. If a table write is being used to write executable code into program memory, program instructions will need to be word-aligned.

Related Links

[Writing to Program Flash Memory](#)

12.1.1.5 Table Pointer Boundaries

TBLPTR is used in reads, writes and erases of the Program Flash Memory.

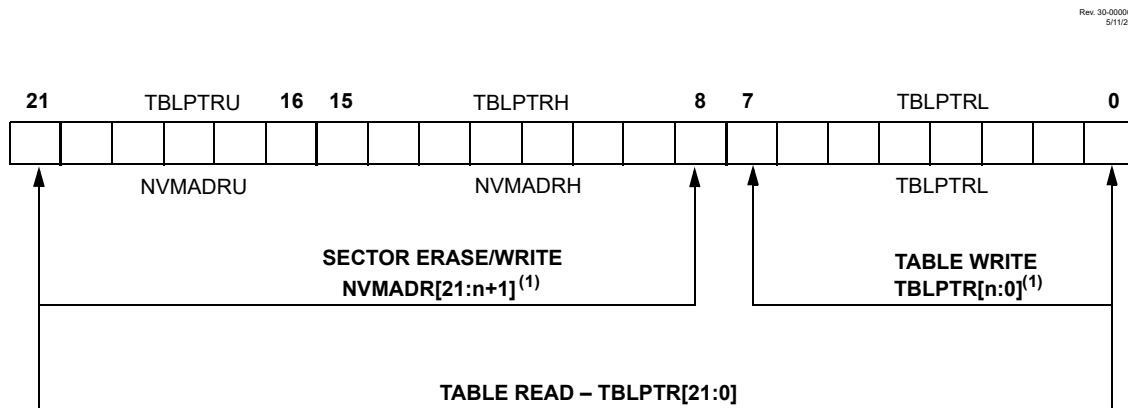
When a TBLRD is executed, all 22 bits of the TBLPTR determine which byte is read from program memory directly into the TABLAT register.

When a TBLWT is executed the byte in the TABLAT register is written, not to Flash memory, but to a holding register in preparation for a program memory write. The holding registers constitute a write block, which may vary depending on the device (see the *"Flash Memory Organization by Device"* table in the **"Program Flash Memory"** section). The LSbs of the TBLPTRL register determine which specific address within the holding register block is written to. The size of the write block determines the number of LSbs. The MSbs of the Table Pointer have no effect during TBLWT operations.

When a PFM sector write is executed the entire holding register block is written to the Flash memory sector at the address determined by the MSbs of the NVMADR. The LSbs are ignored during sector writes. For more detail, see the [Writing to Program Flash Memory](#) section.

The following figure illustrates the relevant boundaries of TBLPTR and NVMADR based on NVM control operations.

Figure 12-3. Table Pointer Boundaries Based on Operation



Note:

1. See the "Flash Memory Organization by Device" table in the "Program Flash Memory" section for the write holding registers block size.

Related Links

[Program Flash Memory](#)

12.1.1.6 Reading the Program Flash Memory

The **TBLRD** instruction retrieves data from program memory at the **TBLPTR** location and places it into the **TABLAT** SFR register. Table reads from program memory are performed one byte at a time. In addition, **TBLPTR** can be modified automatically for the next table read operation.

The CPU operation is suspended during the read, and it resumes immediately after. From the user point of view, **TABLAT** is valid in the next instruction cycle.

The internal program memory is typically organized by words. The Least Significant bit of the address selects between the high and low bytes of the word. [Figure 12-4](#) shows the interface between the internal program memory and the **TABLAT**.

Figure 12-4. Reads from Program Flash Memory

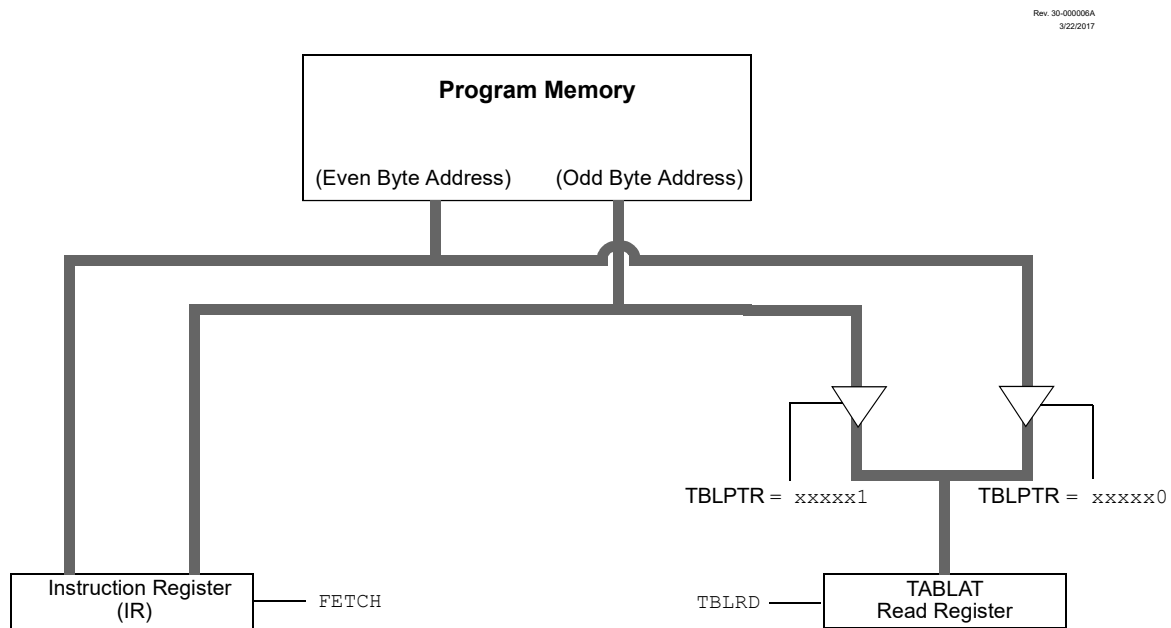
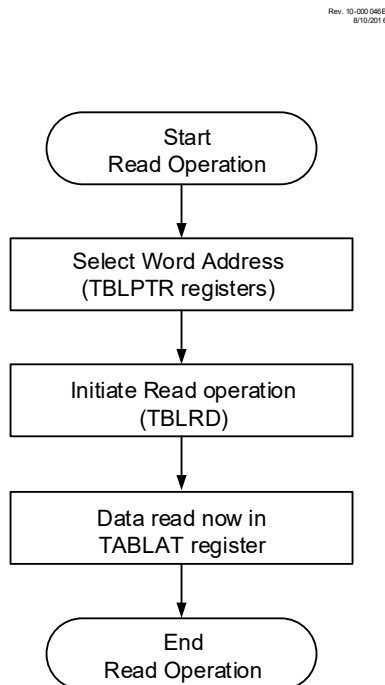


Figure 12-5. Program Flash Memory Read Flowchart



Example 12-1. Reading a Program Flash Memory Word

```

MOVLW  CODE_ADDR_UPPER    ; Load TBLPTR with the base
MOVWF   TBLPTRU            ; address of the word
MOVLW  CODE_ADDR_HIGH
MOVWF   TBLPTRH
MOVLW  CODE_ADDR_LOW

```

```

MOVWF    TBLPTRL
READ_WORD:
TBLRD*+      ; read into TABLAT and increment
MOVF    TABLAT, W      ; get data
MOVWF    WORD_EVEN
TBLRD*+      ; read into TABLAT and increment
MOVFW    TABLAT, W      ; get data
MOVF     WORD_ODD

```

12.1.2 NVM Unlock Sequence

The unlock sequence is a mechanism that protects the NVM from unintended self-write programming, sector reads, and erasing. The sequence must be executed and completed without interruption to successfully complete any of the following operations:

- PFM sector erase
- PFM sector write from holding registers
- PFM sector read into write block holding registers
- PFM word write directly to NVM
- DFM byte write directly to NVM
- Write to Configuration Words

Each of these operations correspond to one of four unlock code sequences as shown in the following table:

Table 12-4. NVM Unlock Codes

| Operation | First Unlock Byte | Second Unlock Byte | NVMCON1 Operation Bit |
|-----------------|-------------------|--------------------|-----------------------|
| Word/Byte write | 55h | AAh | WR |
| Sector write | DDh | 22h | SECWR |
| Sector erase | CCh | 33h | SECEr |
| Sector read | BBh | 44h | SECRD |

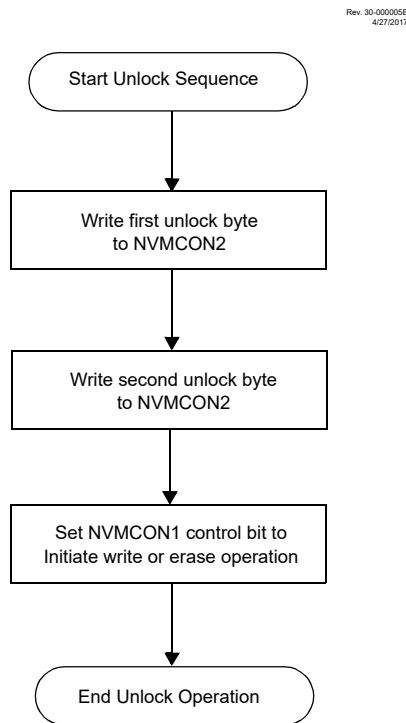
The general unlock sequence consists of the following steps and must be completed in order:

- Write first unlock byte to NVMCON2
- Write second unlock byte to NVMCON2
- Set the operation control bit of NVMCON1

For PFM and Configuration Word operations, once the control bit is set the processor will stall internal operations until the operation is complete and then resume with the next instruction. DFM operations do not stall the CPU.

Since the unlock sequence must not be interrupted, global interrupts should be disabled prior to the unlock sequence and re-enabled after the unlock sequence is completed.

Figure 12-6. NVM Unlock Sequence Flowchart



Example 12-2. NVM Unlock Sequence for PFM word write

```

BCF      INTCON,GIE      ; Recommended so sequence is not interrupted
MOVF     UpperAddr,W     ; set the target address
MOVWF    NVMADRU
MOVF     HighAddr,W
MOVWF    NVMADRH
MOVF     LowAddr,W
MOVWF    NVMADRL
MOVF     HighByte,W      ; high byte of word to be written
MOVWF    NVMDATH         ; store in high byte transfer register
MOVF     LowByte,W       ; low byte of word to be written
MOVWF    NVMDATL         ; store in low byte transfer register
BSF      NVMCON0,NVMEN   ; Enable NVM operation
MOVLW    55h             ; Load first unlock byte
; ----- Required Sequence -----
; MOVWF    NVMCON2       ; Step 1: Load first byte into NVMCON2
; MOVLW    AAh           ; Step 2: Load W with second unlock byte
; MOVWF    NVMCON2       ; Step 3: Load second byte into NVMCON2
; BSF      NVMCON1,WR     ; Step 4: Set WR bit to begin write
; -----
BSF      INTCON,GIE      ; Re-enable interrupts
  
```



Important:

1. Sequence begins when NVMCON2 is written; steps 1-4 must occur in the cycle-accurate order shown. If the timing of the steps 1 to 4 is corrupted by an interrupt or a debugger halt, the action will not take place.
2. Opcodes shown are illustrative; any instruction that has the indicated effect may be used.

12.1.3 Erasing Program Flash Memory (PFM)

The minimum erase block is always one sector. Only through the use of an external programmer, or through ICSP™ control, can larger blocks of program memory be Bulk Erased. Word erase in the Flash array is not supported.

For example, when initiating an erase sequence from a microcontroller with sector erase size of 128 words, a block of 128 words (256 bytes) of program memory is erased. The NVMADR[21:8] bits point to the block being erased. The NVMADR[7:0] bits are ignored.

The NVMCON0 and NVMCON1 registers command the erase operation. The **NVMEN** bit must be set to enable write operations. The **SECER** bit is set to initiate the erase operation.

The NVM unlock sequence described in the [NVM Unlock Sequence](#) section must be used, which guards against accidental writes. This is sometimes referred to as a long write.

A long write is necessary for erasing the internal Flash. Instruction execution is halted during the long write cycle. The long write is terminated by the internal programming timer.

12.1.3.1 PFM Erase Sequence

The sequence of events for erasing a block of internal program memory is:

1. Set NVMADR to an address within the intended sector
2. Set the **NVMEN** bit to enable NVM
3. Perform the unlock sequence as described the [NVM Unlock Sequence](#) section
4. Set the **SECER** bit

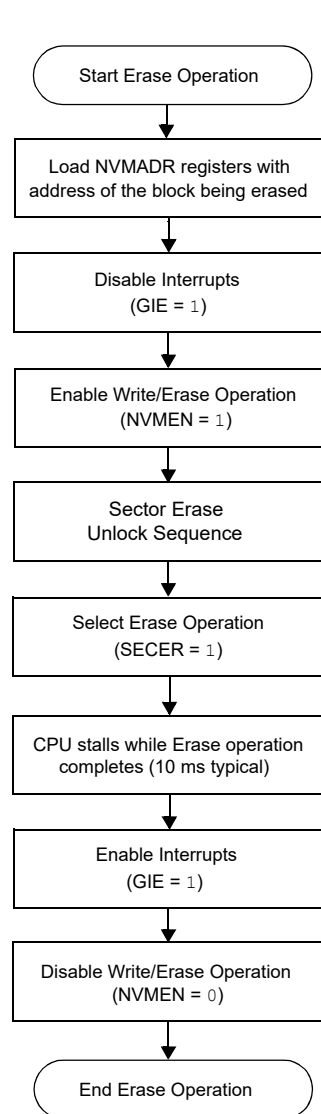
If the PFM address is write-protected, the **SECER** bit will be cleared and the erase operation will not take place, **NVMERR** is signaled in this scenario.

The operation erases the sector indicated by masking the LSbs of the current NVMADR.

While erasing PFM, CPU operation is suspended and it resumes when the operation is complete. Upon completion the **SECER** bit is cleared in hardware, the **NVMIF** is set and an interrupt will occur if the **NVMIE** bit is also set.

The holding register data are not affected by erase operations and **NVMEN** will remain unchanged.

Figure 12-7. PFM Sector Erase Flowchart



Example 12-3. Erasing a Program Flash Memory block

; This sample sector erase routine assumes that the target address
; specified by CODE_ADDR_UPPER and CODE_ADDR_HIGH contain a value within
; the PFM address range of the device.

```

        MOVLW    CODE_ADDR_UPPER    ; load NVMADR with the base
        MOVWF    NVMADRU            ; address of the memory block
        MOVLW    CODE_ADDR_HIGH
        MOVWF    NVMADRH

ERASE_BLOCK:
        BSF      NVMCON0, NVMEN      ; enable Program Flash Memory
        BCF      INTCON, GIE         ; disable interrupts
Required MOVWLW    CCh              ; first unlock byte for erase
Sequence MOVWF    NVMCON2            ; write CCh
        MOVLW    33h                ; second unlock byte for erase
        MOVWF    NVMCON2            ; write 33h
        BSF      NVMCON1, SECER      ; start erase (CPU stalls)
        BSF      INTCON, GIE         ; re-enable interrupts
        BCF      NVMCON0, NVMEN      ; disable writes to memory
  
```

**Important:**

1. If a write or erase operation is terminated by an unexpected event, NVMERR bit will be set which the user can check to decide whether a rewrite of the location(s) is needed.
2. NVMERR is set if SECER is written to '1' while NVMADR points to a write-protected address.
3. NVMERR is set if SECER is written to '1' while NVMADR points to an invalid address location (Refer to the device memory map and NVM Organization Table).

Related Links

[NVM - Nonvolatile Memory Control](#)

12.1.4 Writing to Program Flash Memory

Program memory can be written either one word at a time or a sector at a time.

A single word is written by setting the NVMADR to the target address and loading NVMDAT with the desired word. The word is then transferred to Flash memory with the [WR](#) unlock and write sequence.

A sector is written by first loading a block of holding registers and then executing a sector write sequence. The programming write block size is specified as the holding registers, also referred to as sector RAM, in the Flash memory organization by device table. Table writes are used to write the holding register bytes that are then transferred to Flash memory with the [SECWR](#) unlock and write sequence. There are only as many holding registers as there are bytes in a write block.

Since the table latch ([TABLAT](#)) is only a single byte, the [TBLWT](#) instruction needs to be executed multiple times for each sector programming operation. The write protection state is ignored for table writes. All of the table write operations will essentially be short writes because only the holding registers are written. NVMIF is not affected while writing to the holding registers.

After all the holding registers have been written, the programming operation of that sector of memory is started by setting NVMADR to an address within the target sector and executing a sector write unlock sequence followed immediately by setting the [SECWR](#) bit.

If the PFM address in the NVMADR is write-protected, or if NVMADR points to an invalid location, the SECWR bit is cleared without any effect and the [NVMERR](#) is set.

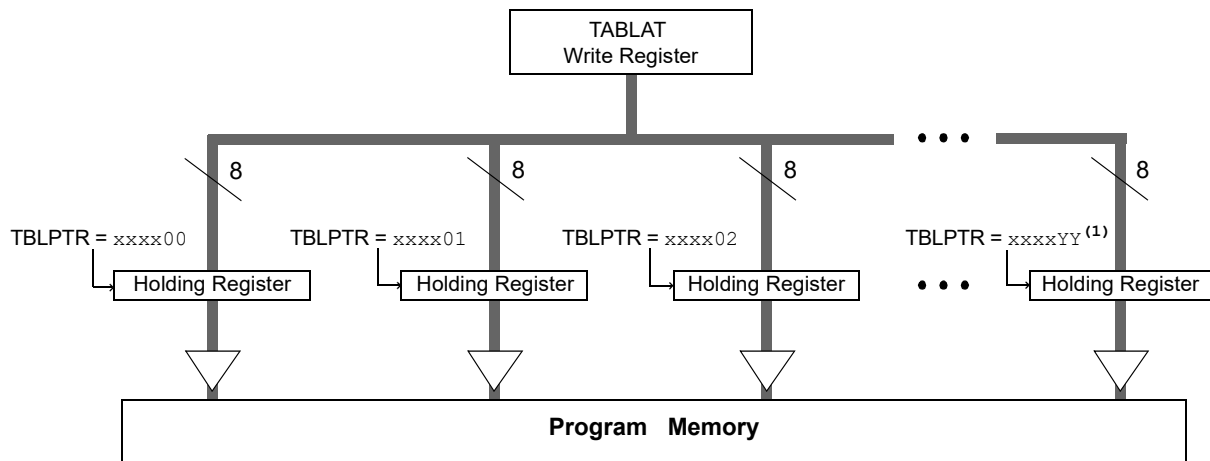
CPU operation is suspended during a long write cycle and resumes when the operation is complete. The long write operation completes in one extended instruction cycle. When complete, the SECWR or WR bit is cleared by hardware and NVMIF is set. An interrupt will occur if NVMIE is also set. The holding registers are unchanged. NVMEN is not changed.

The internal programming timer controls the write time. The write/erase voltages are generated by an on-chip charge pump, rated to operate over the voltage range of the device.



Important: The holding registers are undefined on device Resets and unchanged after write operations. Individual bytes of program memory may be modified, provided that the modification does not attempt to change any bit from a '0' to a '1'. When modifying individual bytes with a sector write operation, it is necessary to load all holding registers with either FFh or the existing contents of memory before executing a long write operation. The fastest way to do this is by performing a sector read operation.

Figure 12-8. Table Writes to Program Flash Memory



Note: Refer to Flash memory organization by device table for number of holding registers (e.g. YY = FFh for 256 holding registers).

Related Links

[Program Flash Memory](#)

12.1.4.1 PFM Sector Write Sequence

The sequence of events for programming a block of internal program memory location should be:

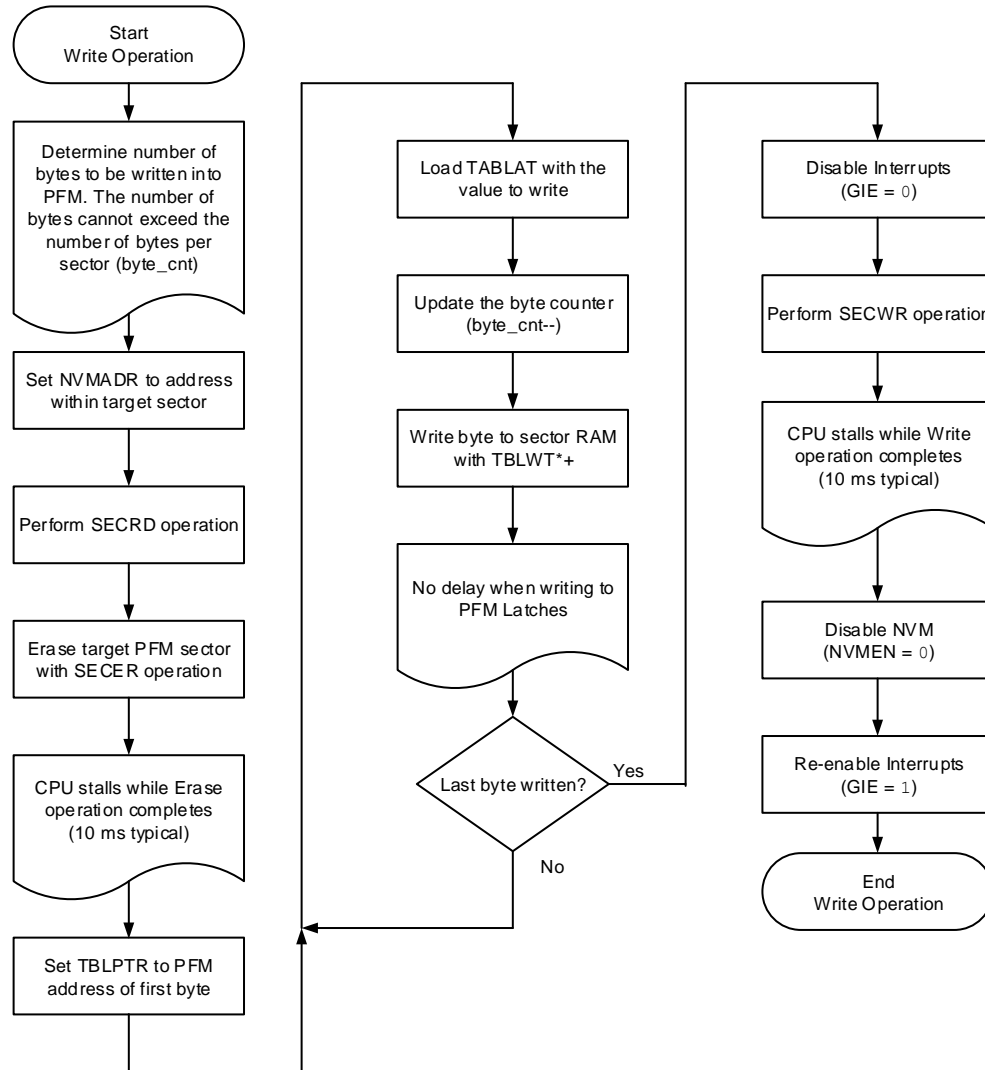
1. Set NVMADR with the target sector address.
2. Read the PFM sector into RAM with the SECRD operation.
3. Execute the sector erase procedure (see [PFM Erase Sequence](#)).
4. SECER is set as the last step in the erase sequence.
5. The CPU will stall for the duration of the erase (about 10 ms using internal timer).
6. Load TBLPTR with address of first byte being updated.
7. Write the n-byte block into the holding registers with auto-increment. Refer to the Flash memory organization by device table for the number of holding registers.
8. Disable interrupts.
9. Execute the sector write unlock sequence (see [NVM Unlock Sequence](#)).
10. SECWR bit is set as last step in the unlock sequence.
11. The CPU will stall for the duration of the write (about 10 ms using internal timer).
12. Re-enable interrupts.
13. Verify the memory (table read).

This procedure will require about 20 ms to update each block of memory. See **“Memory Programming Specifications”** for more details. An example of the required code is given below.

➔ Important: Before setting the SECWR bit, the NVMADR value needs to be within the intended address range of the target PFM sector.

Figure 12-9. Program Flash Memory (PFM) Write Flowchart

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Example 12-4. Writing a Sector of Program Flash Memory

```

; Code sequence to modify one word in a programmed sector of PFM
; Calling routine should check WREG for the following errors:
;
; 00h = Successful modification
; 01h = Read error
; 02h = Erase error
; 03h = Write error
;
READ_BLOCK:
    MOVLW    CODE_ADDR_UPPER    ; Load NVMADR with the base
    MOVWF    NVMADRU            ; address of the memory sector
    MOVLW    CODE_ADDR_HIGH
    MOVWF    NVMADRH
    MOVLW    CODE_ADDR_LOW
    MOVWF    NVMADRL
    BCF      INTCON, GIE        ; Disable interrupts
    BSF      NVMCON0, NVMEN     ; Enable NVM
; ----- Required Sequence -----
    MOVLW    0BBh
    MOVWF    NVMCON2            ; First unlock byte = 0BBh
  
```



```

        MOVLW    44h
        MOVWF    NVMCON2          ; Second unlock byte = 44h
        BSF      NVMCON1, SECRD    ; Start sector read (CPU stall)
; -----
        BTFSC    NVMCON0, NVMERR    ; Verify no error occurred during read
        BRA      NVM_RDERR          ; Return read error code
ERASE_BLOCK:
block
; ----- Required Sequence -----
        MOVLW    0CCh
        MOVWF    NVMCON2          ; First unlock byte = 0CCh
        MOVLW    33h
        MOVWF    NVMCON2          ; Second unlock byte = 33h
        BSF      NVMCON1, SECER    ; start sector erase (CPU stall)
; -----
        BTFSC    NVMCON0, NVMERR    ; Verify no error occurred during erase
        BRA      NVM_ERERR          ; Return erase error code
MODIFY_WORD:
        MOVLW    TARGET_ADDR_UPPER ; Load TBLPTR with the target address
        MOVWF    TBLPTRU           ; of the LSByte
        MOVLW    TARGET_ADDR_HIGH
        MOVWF    TBLPTRH
        MOVLW    TARGET_ADDR_LOW
        MOVWF    TBLPTRL
        MOVLW    NEW_DATA_LOW      ; Update holding register
        MOVWF    TABLAT
        TBLWT*+
        MOVLW    NEW_DATA_HIGH
        MOVWF    TABLAT
        TBLWT*+
PROGRAM_MEMORY:
block
; ----- Required Sequence -----
        MOVLW    0DDh
        MOVWF    NVMCON2          ; First unlock byte = 0DDh
        MOVLW    22h
        MOVWF    NVMCON2          ; Second unlock byte = 22h
        BSF      NVMCON1, SECWR    ; Start sector programming (CPU stall)
; -----
        BTFSC    NVMCON0, NVMERR    ; Verify no error occurred during write
        BRA      NVM_WRERR          ; Return sector write error code
        CLRF     WREG, F           ; Return with no error
        BRA      NVM_EXIT
NVM_RDERR:
        MOVLW    01h
        BRA      NVM_EXIT
NVM_ERERR:
        MOVLW    02h
        BRA      NVM_EXIT
NVM_WRERR:
        MOVLW    03h
NVM_EXIT:
        BCF      NVMCON0, NVMEN    ; Disable NVM
        BSF      INTCON, GIE       ; Re-enable interrupts
        RETURN

```

Related Links

[Memory Programming Specifications](#)

12.1.4.2 PFM Word Write Sequence

The sequence of events for programming an erased single word of internal program memory location should be:

1. Set NVMADR with the target word address.
2. Load NVMDAT with desired word.
3. Disable interrupts.
4. Execute the word/byte write unlock sequence (see [NVM Unlock Sequence](#)).
5. WR bit is set as last step in the unlock sequence.
6. The CPU will stall for the duration of the write (about 50 μ s using internal timer).

7. Re-enable interrupts.
8. Verify the memory (word read).

Example 12-5. Writing a Word of Program Flash Memory

```

; Code sequence to program one erased word of PFM
; Target address is in WORD_ADDR_UPPER:WORD_ADDR_HIGH:WORD_ADDR_LOW
; Target data is in WORD_HIGH_BYTE:WORD_LOW_BYTE
; Calling routine should check WREG for the following errors:
;
; 00h = Successful modification
; 03h = Write error
;
WORD_WRITE:
    MOVF    WORD_ADDR_UPPER, W    ; load NVMADR with the target
    MOVWF   NVMADRU               ; address of the word
    MOVF    WORD_ADDR_HIGH, W
    MOVWF   NVMADRH
    MOVF    WORD_ADDR_LOW, W
    MOVWF   NVMADRL
    MOVF    WORD_HIGH_BYTE, W     ; load NVMDAT with desired
    MOVWF   NVMDATH               ; word
    MOVF    WORD_LOW_BYTE, W
    MOVWF   NVMDATL
    BCF     INTCON, GIE           ; disable interrupts
    BSF     NVMCON0, NVMEN       ; enable NVM
PROGRAM_WORD:
; ----- Required Sequence -----
    MOVLW   055h
    MOVWF   NVMCON2              ; first unlock byte = 055h
    MOVLW   0AAh
    MOVWF   NVMCON2              ; second unlock byte = 0AAh
    BSF     NVMCON1, WR          ; start word programming (CPU stall)
; -----
    BTFSC   NVMCON0, NVMERR      ; Verify no error occurred during write
    BRA     NVM_WRERR           ; return sector write error code
VERIFY_WORD:
    BSF     NVMCON0, RD          ; Retrieve word from PFM
    MOVF    WORD_HIGH_BYTE, W   ; Verify high byte
    CPFSEQ  NVMDATH
    BRA     NVM_RDERR           ; not equal - return error code
    MOVF    WORD_LOW_BYTE, W    ; Verify low byte
    CPFSEQ  NVMDATL
    BRA     NVM_RDERR           ; not equal - return error code

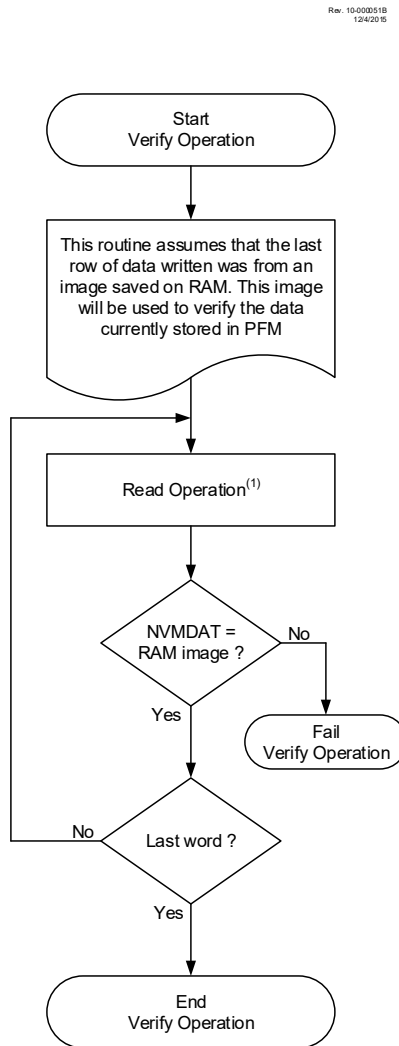
    CLRF    WREG, F             ; return with no error
    BRA     NVM_EXIT
NVM_RDERR:
    MOVLW   01h
    BRA     NVM_EXIT
NVM_WRERR:
    MOVLW   03h
NVM_EXIT:
    BCF     NVMCON0, NVMEN       ; disable NVM
    BSF     INTCON, GIE          ; re-enable interrupts
    RETURN

```

12.1.4.3 Write Verify

Depending on the application, good programming practice may dictate that the value written to the memory should be verified against the original value. This should be used in applications where excessive writes can stress bits near the specification limit. Since program memory is stored as a full page, the stored program memory contents are compared with the intended data stored in sector RAM after the last write is complete.

Figure 12-10. Program Flash Memory Verify Flowchart



12.1.4.4 Unexpected Termination of Write Operation

If a write is terminated by an unplanned event, such as loss of power or an unexpected Reset, the memory location just programmed should be verified and reprogrammed if needed. If the write operation is interrupted by a $\overline{\text{MCLR}}$ Reset or a WDT Time-out Reset during normal operation, the NVMERR bit will be set which the user can check to decide whether a rewrite of the location(s) is needed.

12.1.4.5 Protection Against Spurious Writes

A write sequence is valid only when both the following conditions are met. This prevents spurious writes that might lead to data corruption.

1. The WR, RD, SECWR, SECRD, and SECER bits are gated through the NVMEN bit. It is suggested to have the NVMEN bit cleared at all times except during memory writes and reads. This prevents memory operations if any of the control bits are set accidentally.
2. The NVM unlock sequence must be performed each time before all but the RD operation.

12.2 User ID, Device ID and Configuration Word Access

The NVMADR value determines which NVM address space is accessed. The User IDs and Configuration Words areas allow read and write whereas Device and Revision IDs allow read-only (see NVM organization table).

Reading and writing User ID space is identical to writing to PFM space as described in the preceding paragraphs.

Writing to the Configuration space can only be done with the SECWR operation. A sector erase operation on Configuration space cannot be performed with the SECER operation. When a SECWR operation is performed on the Configuration space a sector erase is performed automatically before the sector write. Any code protection settings that are not enabled will remain not enabled after the sector write operation unless the new values enable them. However, any code protection settings that are enabled cannot be disabled by a self-write of the Configuration space. The user can modify the Configuration space by the following steps:

1. Read Configuration space with the unlock and SECRD sequence.
2. Modify the desired Configuration Word holding registers using TBLPTR address, TABLAT data, and TBLWT* instruction.
3. Write the holding registers to Configuration space with the unlock and SECWR sequence.

Related Links

[NVM - Nonvolatile Memory Control](#)

12.3 Data Flash Memory (DFM)

The data Flash memory is a nonvolatile memory array, also referred to as EEPROM. The DFM is separate from the Program Flash Memory, which is used for long-term storage of program data. The DFM is mapped above program memory space and is indirectly addressed through the NVM Special Function Registers (SFRs). The DFM is readable and writable during normal operation over the entire V_{DD} range.

Five SFRs are used to read and write to the data DFM. They are:

- NVMCON0
- NVMCON1
- NVMCON2
- NVMDAT
- NVMADR

The DFM can only be read and written one byte at a time. When interfacing to the data memory block, NVMDATL holds the 8-bit data for read/write and the [NVMADR](#) register holds the address of the DFM location being accessed.

The DFM is rated for high erase/write cycle endurance. A byte write automatically erases the location and writes the new data (erase-before-write). The write time is controlled by an internal programming timer; it will vary with voltage and temperature as well as from chip-to-chip. Refer to the data EEPROM memory parameters in the electrical specifications section for the limits.

Related Links

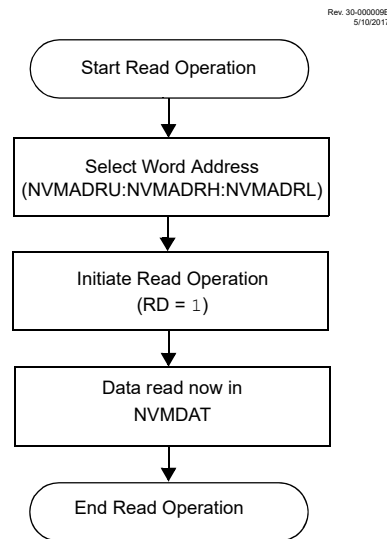
[Memory Programming Specifications](#)

12.3.1 Reading the DFM

To read a DFM location, the user must write the address to the NVMADR register and then set the [RD](#) control bit. The data is available on the very next instruction cycle; therefore, the NVMDAT register can be read by the next instruction. NVMDAT will hold this value until another read operation, or until it is written to by the user (during a write operation).

The basic process is shown in the following flowchart.

Figure 12-11. DFM Read Flowchart



Example 12-6. DFM Read

```

; Data Flash Memory Address to read
MOVWF DFM_ADDR, W           ;
MOVWF NVMADRL, W           ; Setup Address low byte
MOVWF DFM_ADDRH, W         ;
MOVWF NVMADRH, W           ; Setup Address high byte
MOVWF DFM_ADDRU, W         ;
MOVWF NVMADRU, W           ; Setup Address upper byte
BSF NVMCON1, RD             ; Issue EE Read
MOVWF NVMDAT, W             ; W = EE_DATA
  
```

Only byte reads are supported for DFM. Reading a block of DFM with a SECRD operation is not supported.

12.3.2 Writing to DFM

To write a DFM location, the address must first be written to the NVMADR register and the data written to the NVMDATL register. The sequence shown in [NVM Unlock Sequence](#) must be followed to initiate the write cycle. Block writes, also referred to as sector writes, are not supported for the DFM.

The write will not begin if NVM Unlock sequence is not exactly followed for each byte. It is strongly recommended that interrupts be disabled during this code segment.

Additionally, the [NVMEN](#) bit must be set to enable NVM control. This mechanism prevents accidental writes to DFM due to unexpected code execution (i.e., runaway programs). The NVMEN bit should be kept clear at all times, except when updating the DFM. The NVMEN bit is not cleared by hardware.

After a write sequence has been initiated, NVMCON1, NVMADR and NVMDAT cannot be modified. The WR bit will be inhibited from being set unless the NVMEN bit is set.

After a write sequence has been initiated, clearing the NVMEN bit will not affect this write cycle. A single DFM byte is written and the operation includes an implicit erase cycle for that word. CPU execution continues in parallel and at the completion of the write cycle, the WR bit is cleared in hardware and the NVM Interrupt Flag bit (NVMIF) is set. The user can either enable this interrupt or poll this bit. NVMIF must be cleared by software.

Example 12-7. DFM Write

```

; Data Flash Memory Address to write
MOVWF DFM_ADDR_L, W      ;
MOVWF NVMADRL            ; Setup Address low byte
MOVWF DFM_ADDR_H, W      ;
MOVWF NVMADRH            ; Setup Address high byte
MOVWF DFM_ADDR_U, W      ;
MOVWF NVMADRU            ; Setup Address upper byte
; Data Memory Value to write
MOVWF DMF_DATA, W        ;
MOVWF NVMDATL            ;
; Enable writes
BSF    NVMCON0, NVMEN    ; Enable NVM
; Disable interrupts
BCF    INTCON, GIE       ;
; ----- Required Sequence -----
MOVLW  55h              ;
MOVWF  NVMCON2           ;
MOVLW  AAh              ;
MOVWF  NVMCON2           ;
BSF    NVMCON1, WR       ; Set WR bit to begin write
; -----
; Wait for write to complete
BTFSC  NVMCON1, WR       ; DFM writes do not stall the CPU
BRA    $-2
; Enable INT
BSF    INTCON, GIE       ;
; Disable writes
BCF    NVMCON0, NVMEN    ;

```

12.3.3 DFM Write Verify

Depending on the application, good programming practice may dictate that the value written to the memory should be verified against the original value. This should be used in applications where excessive writes can stress bits near the specification limit.

12.3.4 Operation During Code-Protect and Write-Protect

DFM has its own code-protect bits in the Configuration Words. In-Circuit Serial Programming read and write operations are disabled when code protection is enabled. However, internal reads operate normally. Internal writes operate normally provided that write protection is not enabled.

If the DFM is write-protected or if NVMADR points at an invalid address location, the WR bit is cleared without any effect. NVMMERR is signaled in this scenario.

12.3.5 Protection Against Spurious Write

There are conditions when the user may not want to write to the DFM. To protect against spurious DFM writes, various mechanisms have been implemented. On any Reset, the NVMEN bit is cleared. In addition, writes to the DFM are blocked during the Power-up Timer period (T_{PWRT}).

The unlock sequence and the NVMEN bit together help prevent an accidental write during brown-out, power glitch or software malfunction.

12.3.6 Erasing the DFM

DFM can be erased by writing 0xFF to all locations in the memory that need to be erased.

Example 12-8. DFM Erase Routine

```

CLRF   NVMADRL          ; Clear address low byte
CLRF   NVMADRH          ; Clear address high byte
MOVLW  31h              ; EEPROM upper address
MOVWF  NVMADRU          ; Set address upper byte
SETF   NVMDAT           ; Load 0xFF to data register
BCF    INTCON, GIE       ; Disable interrupts
BSF    NVMCON0, NVMEN    ; Enable NVM

```

```

Loop:      MOVLW    0x55          ; Loop to refresh array
           MOVWF    NVMCON2      ; Initiate unlock sequence
           MOVLW    0xAA          ;
           MOVWF    NVMCON2      ;
           BSF      NVMCON1, WR   ; Set WR bit to begin write
           BTFSC    NVMCON1, WR   ; Wait for write to complete
           BRA      $-2
           INCF     NVMADRL, F    ; Increment address low byte
           BRA      Loop         ; Not zero, do it again
; The following 4 lines of code are not needed if EEPROM is 256 bytes or less
           INCF     NVMADRH, F    ; Decrement address high byte
           MOVLW    0x03          ; Move 0x03 to working register
           CPFSGT   NVMADRH      ; Compare address high byte with working
register
           BRA      Loop         ; Skip if greater than working register
           ; Else go back to erase loop
           BCF      NVMCON0, NVMEN ; Disable NVM
           BSF      INTCON, GIE   ; Enable interrupts

```

12.4 Register Summary - NVM Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|--------------|-------|--------------|--------------|----------|---|-------|----|
| 0x00 ... 0x0F78 | Reserved | | | | | | | | | |
| 0x0F79 | NVMADR | 7:0 | NVMADRL[7:0] | | | | | | | |
| | | 15:8 | NVMADRH[7:0] | | | | | | | |
| | | 23:16 | | | NVMADRU[5:0] | | | | | |
| 0x0F7C | NVMDAT | 7:0 | NVMDATL[7:0] | | | | | | | |
| | | 15:8 | NVMDATH[7:0] | | | | | | | |
| 0x0F7E | Reserved | | | | | | | | | |
| 0x0F7F | NVMCON0 | 7:0 | NVMEN | | | NVMERR | Reserved | | | |
| 0x0F80 | NVMCON1 | 7:0 | | SECER | SECWR | WR | | | SECRD | RD |
| 0x0F81 | NVMCON2 | 7:0 | NVMCON2[7:0] | | | | | | | |
| 0x0F82 ... 0x0FF4 | Reserved | | | | | | | | | |
| 0x0FF5 | TABLAT | 7:0 | TABLAT[7:0] | | | | | | | |
| 0x0FF6 | TBLPTR | 7:0 | TBLPTRL[7:0] | | | | | | | |
| | | 15:8 | TBLPTRH[7:0] | | | | | | | |
| | | 23:16 | | | TBLPTR21 | TBLPTRU[4:0] | | | | |

12.5 Register Definitions: Nonvolatile Memory

12.5.1 NVMCON0

Name: NVMCON0

Address: 0xF7F

Nonvolatile Memory Control 0 Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|---|---|--------|----------|---|---|---|
| | NVMEN | | | NVMERR | Reserved | | | |
| Access | R/W | | | R/W/HS | R/W | | | |
| Reset | 0 | | | x | 0 | | | |

Bit 7 – NVMEN NVM Enable bit

| Value | Description |
|-------|--|
| 1 | NVM is enabled for all operations |
| 0 | NVM is disabled for all operations except single byte or word read |

Bit 4 – NVMERR

NVM Error Flag bit

| Value | Description |
|-------|---|
| 1 | An attempted NVM write or sector read did not complete successfully. Must be cleared by software. |
| 0 | All NVM operations have completed successfully |

Bit 3 – Reserved

Reserved - Do not use. This bit must be maintained as '0'.

12.5.2 NVMCON1

Name: NVMCON1

Address: 0xF80

Nonvolatile Memory Control 1 Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|--------|--------|--------|---|---|--------|--------|
| | | SECER | SECWR | WR | | | SECRD | RD |
| Access | | R/S/HC | R/S/HC | R/S/HC | | | R/S/HC | R/S/HC |
| Reset | | 0 | 0 | 0 | | | 0 | 0 |

Bit 6 – SECER

NVM Sector Erase Enable Control bit

| Value | Condition | Description |
|-------|----------------------|---|
| 1 | NVMADR points to PFM | Immediately following the sector erase unlock sequence, perform a sector erase operation. Stays set until operation is complete. Cannot be cleared by software. |
| 0 | NVMADR points to PFM | NVM sector erase operation is complete and inactive |

Bit 5 – SECWR

NVM Sector Write Enable Control bit

| Value | Condition | Description |
|-------|--------------------------------|---|
| 1 | NVMADR points to PFM or CONFIG | Immediately following the sector write unlock sequence, initiates the PFM sector write operation. Stays set until the write is complete. Cannot be cleared by software. |
| 0 | NVMADR points to PFM or CONFIG | NVM sector write operation is complete and inactive |

Bit 4 – WR

NVM Write Control bit

| Value | Condition | Description |
|-------|-----------------------------|--|
| 1 | NVMADR points to DFM | Immediately following the DFM write unlock sequence, initiates a DFM byte erase/write sequence using data in the NVMDATL register. Stays set until the operation is complete. Cannot be cleared by software. |
| 1 | NVMADR points to PFM | Immediately following the PFM write unlock sequence, initiates an NVM word write sequence using data in the NVMDATH:L register pair. Stays set until the operation is complete. Cannot be cleared by software. |
| 0 | NVMADR points to PFM or DFM | NVM byte/word write operation is complete and inactive |

Bit 1 – SECRD

PFM Sector Read Enable Control bit

| Value | Condition | Description |
|-------|--------------------------------|---|
| 1 | NVMADR points to PFM or CONFIG | Immediately following the sector read unlock sequence, initiates a read of one full sector from PFM into sector RAM. Stays set until the read is complete. Cannot be cleared by software. |
| 0 | NVMADR points to PFM or CONFIG | PFM sector read operation is complete and inactive |

Bit 0 – RD

NVM Read Enable Control bit

| Value | Condition | Description |
|-------|----------------------|---|
| 1 | NVMADR points to DFM | Initiates a read of one byte from DFM into the NVMDATL register. Stays set until the read is complete. Cannot be cleared by software. |

| Value | Condition | Description |
|-------|-----------------------------|--|
| 1 | NVMADR points to PFM | Initiates a read of one word from PFM into the NVMDATH:L registers. Stays set until the read is complete. Cannot be cleared by software. |
| 0 | NVMADR points to PFM or DFM | NVM read operation is complete and inactive |

12.5.3 NVMCON2

Name: NVMCON2
Address: 0xF81

Nonvolatile Memory Control 2 Register
Note: This register always reads zeros, regardless of data written.
Refer to the NVM Unlock Sequence section

| | | | | | | | | |
|--------|--------------|----|----|----|----|----|----|----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | NVMCON2[7:0] | | | | | | | |
| Access | WO | WO | WO | WO | WO | WO | WO | WO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – NVMCON2[7:0]

12.5.4 NVMDAT

Name: NVMDAT
Address: 0xF7C

NVM Data Register

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | NVMDATH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | NVMDATL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – NVMDATH[7:0]

NVMDAT Most Significant Byte of data written to and read from PFM.

Bits 7:0 – NVMDATL[7:0]

NVMDAT Least Significant Byte of data written to and read from PFM or DFM.

12.5.5 NVMADR

Name: NVMADR

Address: 0xF79

NVM Address Register

| | | | | | | | | |
|--------|--------------|-----|--------------|-----|-----|-----|-----|-----|
| Bit | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | | | NVMADRU[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | NVMADRH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | NVMADRL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 21:16 – NVMADRU[5:0]

NVM address bits [21:16] .

Bits 15:8 – NVMADRH[7:0]

High byte of NVM address.

Bits 7:0 – NVMADRL[7:0]

Low byte of NVM address.

12.5.6 TABLAT

Name: TABLAT
Address: 0xFF5

Program, Configuration, Device ID, and User ID Memory Data

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| | TABLAT[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – TABLAT[7:0] The value of the NVM memory byte returned from the address contained in TBLPTR after a **TBLRD** command, or the data written to the latch by a **TBLWT** command.

12.5.7 TBLPTR

Name: TBLPTR
Address: 0xFF6

Program, Configuration, Device ID and User ID Memory Address

| | | | | | | | | |
|--------|----|----|----------|--------------|-----|-----|-----|-----|
| Bit | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | | | TBLPTR21 | TBLPTRU[4:0] | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | TBLPTRH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TBLPTRL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 21 – TBLPTR21 NVM Most Significant Address bit

| Value | Description |
|-------|--|
| 1 | Access Configuration, User ID, Device ID, and Revision ID spaces |
| 0 | Access Program Flash Memory space |

Bits 20:16 – TBLPTRU[4:0] NVM Upper Address bits

Bits 15:8 – TBLPTRH[7:0] High Byte of NVM Address bits

Bits 7:0 – TBLPTRL[7:0] Low Byte of NVM Address bits

13. 8x8 Hardware Multiplier

13.1 Introduction

All PIC18 devices include an 8x8 hardware multiplier as part of the ALU. The multiplier performs an unsigned operation and yields a 16-bit result that is stored in the product register pair, PRODH:PRODL. The multiplier's operation does not affect any flags in the STATUS register.

Making multiplication a hardware operation allows it to be completed in a single instruction cycle. This has the advantages of higher computational throughput and reduced code size for multiplication algorithms and allows the PIC18 devices to be used in many applications previously reserved for digital signal processors. A comparison of various hardware and software multiply operations, along with the savings in memory and execution time, is shown in [Table 13-1](#).

13.2 Operation

[Example 13-1](#) shows the instruction sequence for an 8x8 unsigned multiplication. Only one instruction is required when one of the arguments is already loaded in the WREG register.

[Example 13-2](#) shows the sequence to do an 8x8 signed multiplication. To account for the sign bits of the arguments, each argument's Most Significant bit (MSb) is tested and the appropriate subtractions are done.

Example 13-1. 8x8 Unsigned Multiply Routine

```
MOVF    ARG1, W    ;
MULWF   ARG2       ; ARG1 * ARG2 -> PRODH:PRODL
```

Example 13-2. 8x8 Signed Multiply Routine

```
MOVF    ARG1, W
MULWF   ARG2       ; ARG1 * ARG2 -> PRODH:PRODL
BTFSC   ARG2, SB   ; Test Sign Bit
SUBWF   PRODH, F    ; PRODH = PRODH - ARG1
MOVF    ARG2, W
BTFSC   ARG1, SB   ; Test Sign Bit
SUBWF   PRODH, F    ; PRODH = PRODH - ARG2
```

Table 13-1. Performance Comparison for Various Multiply Operations

| Routine | Multiply Method | Program Memory (Words) | Cycles (Max) | Time | | | |
|----------------|---------------------------|------------------------|--------------|--------------|--------------|---------------|-------------|
| | | | | @ 64 MHz | @ 40 MHz | @ 10 MHz | @ 4 MHz |
| 8x8 unsigned | Without hardware multiply | 13 | 69 | 4.3 μ s | 6.9 μ s | 27.6 μ s | 69 μ s |
| | Hardware multiply | 1 | 1 | 62.5 ns | 100 ns | 400 ns | 1 μ s |
| 8x8 signed | Without hardware multiply | 33 | 91 | 5.7 μ s | 9.1 μ s | 36.4 μ s | 91 μ s |
| | Hardware multiply | 6 | 6 | 375 ns | 600 ns | 2.4 μ s | 6 μ s |
| 16x16 unsigned | Without hardware multiply | 21 | 242 | 15.1 μ s | 24.2 μ s | 96.8 μ s | 242 μ s |
| | Hardware multiply | 28 | 28 | 1.8 μ s | 2.8 μ s | 11.2 μ s | 28 μ s |
| 16x16 signed | Without hardware multiply | 52 | 254 | 15.9 μ s | 25.4 μ s | 102.6 μ s | 254 μ s |
| | Hardware multiply | 35 | 40 | 2.5 μ s | 4.0 μ s | 16.0 μ s | 40 μ s |

[Example 13-3](#) shows the sequence to do a 16 x 16 unsigned multiplication. The equation below shows the algorithm that is used. The 32-bit result is stored in four registers (RES[3:0]).

16 x 16 Unsigned Multiplication Algorithm

$$RES3:RES0 = ARG1H:ARG1L \cdot ARG2H:ARG2L = (ARG1H \cdot ARG2H \cdot 2^{16}) + (ARG1H \cdot ARG2L \cdot 2^8) + (ARG1L \cdot ARG2H \cdot 2^8) + (ARG1L \cdot ARG2L)$$

Example 13-3. 16 x 16 Unsigned Multiply Routine

```

MOVWF ARG1L, W
MULWF ARG2L           ; ARG1L * ARG2L → PRODH:PRODL
MOVFF PRODH, RES1
MOVFF PRODL, RES0
;
MOVWF ARG1H, W
MULWF ARG2H           ; ARG1H * ARG2H → PRODH:PRODL
MOVFF PRODH, RES3
MOVFF PRODL, RES2
;
MOVWF ARG1L, W
MULWF ARG2H           ; ARG1L * ARG2H → PRODH:PRODL
MOVF PRODL, W
ADDWF RES1, F         ; Add cross products
MOVF PRODH, W
ADDWFC RES2, F
CLRF WREG
ADDWFC RES3, F
;
MOVWF ARG1H, W
MULWF ARG2L           ; ARG1H * ARG2L → PRODH:PRODL
MOVF PRODL, W
ADDWF RES1, F         ; Add cross products
MOVF PRODH, W
ADDWFC RES2, F
CLRF WREG
ADDWFC RES3, F

```

Example 13-4 shows the sequence to do a 16 x 16 signed multiply. The equation below shows the algorithm used. The 32-bit result is stored in four registers (RES[3:0]). To account for the sign bits of the arguments, the MSb for each argument pair is tested and the appropriate subtractions are done.

16 x 16 Signed Multiplication Algorithm

$$RES3:RES0 = ARG1H:ARG1L \cdot ARG2H:ARG2L = (ARG1H \cdot ARG2H \cdot 2^{16}) + (ARG1H \cdot ARG2L \cdot 2^8) + (ARG1L \cdot ARG2H \cdot 2^8) + (ARG1L \cdot ARG2L) + (-1 \cdot ARG2H < 7 > \cdot ARG1H:ARG1L \cdot 2^{16}) + (-1 \cdot ARG1H < 7 > \cdot ARG2H:ARG2L \cdot 2^{16})$$

Example 13-4. 16 x 16 Signed Multiply Routine

```

MOVWF ARG1L, W
MULW ARG2L           ; ARG1L * ARG2L → PRODH:PRODL
MOVF PRODH, RES1
MOVFF PRODL, RES0
;
MOVWF ARG1H, W
MULWF ARG2H           ; ARG1H * ARG2H → PRODH:PRODL
MOVFF PRODH, RES3
MOVFF PRODL, RES2
;
MOVWF ARG1L, W
MULWF ARG2H           ; ARG1L * ARG2H → PRODH:PRODL
MOVF PRODL, W
ADDWF RES1, F         ; Add cross products
MOVF PRODH, W
ADDWFC RES2, F
CLRF WREG

```

```

        ADDWFC  RES3, F      ;
;
        MOVF    ARG1H, W    ;
        MULWF   ARG2L      ; ARG1H * ARG2L → PRODH:PRODL
        MOVF    PRODL, W    ;
        ADDWF   RES1, F     ; Add cross products
        MOVF    PRODH, W    ;
        ADDWFC  RES2, F     ;
        CLRF    WREG        ;
        ADDWFC  RES3, F     ;
;
        BTFSS   ARG2H, 7    ; ARG2H:ARG2L neg?
        BRA     SIGN_ARG1   ; no, check ARG1
        MOVF    ARG1L, W    ;
        SUBWF   RES2        ;
        MOVF    ARG1H, W    ;
        SUBWFB  RES3
;
SIGN_ARG1:
        BTFSS   ARG1H, 7    ; ARG1H:ARG1L neg?
        BRA     CONT_CODE   ; no, done
        MOVF    ARG2L, W    ;
        SUBWF   RES2        ;
        MOVF    ARG2H, W    ;
        SUBWFB  RES3
;
CONT_CODE:
        ;

```

13.3 Register Summary - 8x8 Hardware Multiplier

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|------------|---|---|---|---|---|---|---|
| 0x00 ... 0x0FF2 | Reserved | | | | | | | | | |
| 0x0FF3 | PROD | 7:0 | PRODL[7:0] | | | | | | | |
| | | 15:8 | PRODH[7:0] | | | | | | | |

13.4 Register Definitions: 8x8 Hardware Multiplier

13.4.1 PROD

Name: PROD
Address: 0xFF3

Product Register Pair

The PROD register stores the 16-bit result yielded by the unsigned operation performed by the 8x8 hardware multiplier.

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | PRODH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | PRODL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 15:8 – PRODH[7:0]
PROD Most Significant bits.

Bits 7:0 – PRODL[7:0]
PROD Least Significant bits.

14. CRC - Cyclic Redundancy Check Module with Memory Scanner

The Cyclic Redundancy Check (CRC) module provides a software-configurable hardware-implemented CRC checksum generator. This module includes the following features:

- Any standard CRC up to 16 bits can be used
- Configurable Polynomial
- Any seed value up to 16 bits can be used
- Standard and reversed bit order available
- Augmented zeros can be added automatically or by the user
- Memory scanner for fast CRC calculations on program memory user data
- Software loadable data registers for communication CRCs

14.1 CRC Module Overview

The CRC module provides a means for calculating a check value of program memory. The CRC module is coupled with a memory scanner for faster CRC calculations. The memory scanner can automatically provide data to the CRC module. The CRC module can also be operated by directly writing data to SFRs, without using a scanner.

14.2 CRC Functional Overview

The CRC module can be used to detect bit errors in the Flash memory using the built-in memory scanner or through user input RAM memory. The CRC module can accept up to a 16-bit polynomial with up to a 16-bit seed value. A CRC calculated check value (or checksum) will then be generated into the [CRCACC](#) registers for user storage. The CRC module uses an XOR shift register implementation to perform the polynomial division required for the CRC calculation.

Figure 14-1. CRC Example

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1/8/2014

CRC-16-ANSI

$$x^{16} + x^{15} + x^2 + 1 \text{ (17 bits)}$$

Standard 16-bit representation = 0x8005

CRCXORH = 0b10000000
CRCXORL = 0b0000010- ⁽¹⁾

Data Sequence:
0x55, 0x66, 0x77, 0x88

DLEN = 0b0111
PLEN = 0b1111

Data entered into the CRC:

SHIFTM = 0:
01010101 01100110 01110111 10001000

SHIFTM = 1:
10101010 01100110 11101110 00010001

Check Value (ACCM = 1):

SHIFTM = 0: 0x32D6
CRCACCH = 0b00110010
CRCACCL = 0b11010110

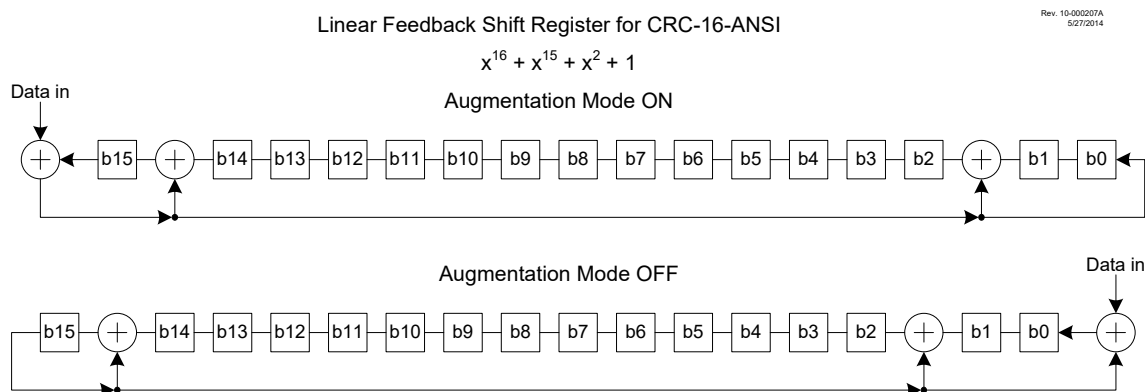
SHIFTM = 1: 0x6BA2
CRCACCH = 0b01101011
CRCACCL = 0b10100010

Note 1: Bit 0 is unimplemented. The LSb of any CRC polynomial is always '1' and will always be treated as a '1' by the CRC for calculating the CRC check value. This bit will be read in software as a '0'.

14.3 CRC Polynomial Implementation

Any polynomial can be used. The polynomial and accumulator sizes are determined by the [PLEN](#) bits. For an n-bit accumulator, PLEN = n-1 and the corresponding polynomial is n+1 bits. Therefore, the accumulator can be any size up to 16 bits with a corresponding polynomial up to 17 bits. The MSb and LSb of the polynomial are always '1' which is forced by hardware. However, the LSb of the CRCXORL register is unimplemented and always reads as '0'.

All polynomial bits between the MSb and LSb are specified by the [CRCXOR](#) registers. For example, when using CRC16-ANSI, the polynomial is defined as $X^{16} + X^{15} + X^2 + 1$. The X^{16} and $X^0 = 1$ terms are the MSb and LSb controlled by hardware. The X^{15} and X^2 terms are specified by setting the corresponding CRCXOR[15:0] bits with the value of 0x8004. The actual value is 0x8005 because the hardware sets the LSb to 1. Refer to [Figure 14-1](#).

Figure 14-2. CRC LFSR Example

14.4 CRC Data Sources

Data can be input to the CRC module in two ways:

- User data using the [CRCDAT](#) registers
- From Flash memory using the program memory scanner

Up to 16 bits of data per word are specified with the [DLEN](#) bits. Only the number of data bits in the CRCDATA registers specified by DLEN will be used, other data bits in CRCDATA registers will be ignored.

Data is moved into the [CRCSHIFT](#) as an intermediate to calculate the check value located in the [CRCACC](#) registers.

The [SHIFTM](#) bit is used to determine the bit order of the data being shifted into the accumulator. If SHIFTM is not set, the data will be shifted in MSb first (Big Endian). The value of DLEN will determine the MSb. If SHIFTM bit is set, the data will be shifted into the accumulator in reversed order, LSb first (Little Endian).

The CRC module can be seeded with an initial value by setting the CRCACC registers to the appropriate value before beginning the CRC.

14.4.1 CRC from User Data

To use the CRC module on data input from the user, the user must write the data to the CRCDAT registers. The data from the CRCDAT registers will be latched onto the shift registers on any write to the CRCDATL register.

14.4.2 CRC from Flash

To use the CRC module on data located in Flash memory, the user can initialize the program memory scanner as defined in the [Program Memory Scan Configuration](#) section.

14.5 CRC Check Value

The CRC check value will be located in the CRCACC registers after the CRC calculation has finished. The check value will depend on the [ACCM](#) and [SHIFTM](#) mode settings.

When the ACCM bit is set, the CRC module augments the data with a number of zeros equal to the length of the polynomial to align the final check value. When the ACCM bit is not set, the CRC will stop at the end of the data. A number of zeros equal to the length of the polynomial can then be entered into CRCDAT to find the same check value as augmented mode. Alternatively, the expected check value can be entered at this point to make the final result equal 0.

When the CRC check value is computed with the SHIFTM bit set, selecting LSb first, and the ACCM bit is set then the final value in the CRCACC registers will be reversed such that the LSb will be in the MSb position and vice versa. This is the expected check value in bit reversed form. When creating a check value to be appended to a data stream, then a bit reversal must be performed on the final value to achieve the correct checksum. CRC can be used to do this reversal by following the steps below:

1. Save CRCACC value in user RAM space.
2. Clear the CRCACC registers.
3. Clear the CRCXOR registers.
4. Write the saved CRCACC value to the CRCDAT input.

The properly oriented check value will be in the CRCACC registers as the result.

14.6 CRC Interrupt

The CRC will generate an interrupt when the **BUSY** bit transitions from 1 to 0. The CRCIF Interrupt Flag bit of the PIRx register is set every time the BUSY bit transitions, regardless of whether or not the CRC interrupt is enabled. The CRCIF bit can only be cleared in software. The CRC interrupt enable is the CRCIE bit of the PIRx register.

14.7 Configuring the CRC

The following steps illustrate how to properly configure the CRC.

1. Determine if the automatic program memory scan will be used with the scanner or manual calculation through the SFR interface and perform the actions specified in [CRC Data Sources](#), depending on which decision was made.
2. If desired, seed a starting CRC value into the **CRCACC** registers.
3. Program the **CRCXOR** registers with the desired generator polynomial.
4. Program the **DLEN** bits with the length of the data word - 1 (refer to [Figure 14-1](#)). This determines how many times the shifter will shift into the accumulator for each data word.
5. Program the **PLEN** bits with the length of the polynomial - 2 (refer to [Figure 14-1](#)).
6. Determine whether shifting in trailing zeros is desired and set the **ACCM** bit accordingly.
7. Likewise, determine whether the MSb or LSb must be shifted first and write the **SHIFTM** bit accordingly.
8. Set the **GO** bit to begin the shifting process.
9. If manual SFR entry is used, monitor the **FULL** bit. When **FULL** = 0, another word of data can be written to the **CRCDAT** registers, keeping in mind that the Most Significant Byte, **CRCDATH**, must be written first if the data has more than eight bits, as the shifter will begin upon the **CRCDATL** register being written.
10. If the scanner is used, the scanner will automatically stuff words into the **CRCDAT** registers as needed, as long as the **SCANGO** bit is set.
11. If using the Flash memory scanner, monitor the PIRx **SCANIF** bit (or the **SCANGO** bit) for the scanner to finish pushing information into the **CRCDAT** registers. After the scanner is completed, monitor the **BUSY** bit to determine that the CRC has been completed and the check value can be read from the **CRCACC** registers. If both the interrupt flags are set (or both **BUSY** and **SCANGO** bits are cleared), the completed CRC calculation can be read from the **CRCACC** registers.
12. If manual entry is used, monitor the **BUSY** bit to determine when the **CRCACC** registers hold the valid check value.

14.8 Program Memory Scan Configuration

The program memory scan module may be used in conjunction with the CRC module to perform a CRC calculation over a range of program memory addresses. To set up the scanner to work with the CRC the following steps need to be performed:

1. Set both the **EN** and **SCANEN** bits. If they get disabled, all internal states of the scanner and the CRC are reset. However, the CRC SFR registers are unaffected.
2. Choose which memory access mode is to be used (see [Scanning Modes](#)) and set the **MODE** bits accordingly.
3. Based on the memory access mode, set the **INTM** bits to the appropriate Interrupt mode (see [Interrupt Interaction](#)).
4. Set the **SCANLADR** and **SCANHADR** registers with the respective beginning and ending locations in memory that are to be scanned.
5. The **GO** bit must be set before setting the **SCANGO** bit. Setting the **SCANGO** bit starts the scan. Both the **EN** and **GO** bits must be enabled to use the scanner. When either of these bits are disabled, the scan aborts and the **INVALID** bit is set. The scanner will wait for the signal from the CRC that it is ready for the first Flash memory location, then begin loading data into the CRC. It will continue to do so until it either hits the configured end address or an address that is unimplemented on the device, at which point the **SCANGO** bit will clear, Scanner functions will cease, and the **SCANIF** interrupt will be triggered. Alternately, the **SCANGO** bit can be cleared in software to terminate the scan early if desired.

14.9 Scanner Interrupt

The scanner will trigger an interrupt when the **SCANGO** bit transitions from '1' to '0'. The **SCANIF** interrupt flag of **PIRx** is set when the last memory location is reached and the data is entered into the **CRCDATA** registers. The **SCANIF** bit can only be cleared in software. The **SCAN** interrupt enable is the **SCANIE** bit of the **PIEx** register.

14.10 Scanning Modes

The memory scanner can scan in four modes: Burst, Peek, Concurrent, and Triggered. These modes are controlled by the **MODE** bits. The four modes are summarized in [Table 14-1](#).

14.10.1 Burst Mode

When **MODE** = 01, the scanner is in Burst mode. In Burst mode, CPU operation is stalled beginning with the operation after the one that sets the **SCANGO** bit, and the scan begins, using the instruction clock to execute. The CPU is held in its current state until the scan stops. Note that because the CPU is not executing instructions, the **SCANGO** bit cannot be cleared in software, so the CPU will remain stalled until one of the hardware end-conditions occurs. Burst mode has the highest throughput for the scanner, but has the cost of stalling other execution while it occurs.

14.10.2 Concurrent Mode

When **MODE** = 00, the scanner is in Concurrent mode. Concurrent mode, like Burst mode, stalls the CPU while performing accesses of memory. However, while Burst mode stalls until all accesses are complete, Concurrent mode allows the CPU to execute in between access cycles.

14.10.3 Triggered mode

When **MODE** = 11, the scanner is in Triggered mode. Triggered mode behaves identically to Concurrent mode, except instead of beginning the scan immediately upon the **SCANGO** bit being set, it waits for a rising edge from a separate trigger source which is determined by the **SCANTRIG** register.

14.10.4 Peek Mode

When $MODE = 10$, the scanner is in Peek mode. Peek mode waits for an instruction cycle in which the CPU does not need to access the NVM (such as a branch instruction) and uses that cycle to do its own NVM access. This results in the lowest throughput for the NVM access (and can take a much longer time to complete a scan than the other modes), but does so without any impact on execution times, unlike the other modes.

Table 14-1. Summary of Scanner Modes

| MODE[1:0] | | Description | | |
|-----------|------------|---|---------------------------|---|
| | | First Scan Access | CPU Operation | |
| 11 | Triggered | As soon as possible following a trigger | Stalled during NVM access | CPU resumes execution following each access |
| 10 | Peek | At the first dead cycle | Timing is unaffected | CPU continues execution following each access |
| 01 | Burst | As soon as possible | Stalled during NVM access | CPU suspended until scan completes |
| 00 | Concurrent | | | CPU resumes execution following each access |

14.10.5 Interrupt Interaction

The **INTM** bit controls the scanner's response to interrupts depending on which mode the NVM scanner is in, as described in the following table.

Table 14-2. Scan Interrupt Modes

| INTM | MODE[1:0] | | |
|------|---|---|---------------------|
| | MODE == Burst | MODE == CONCURRENT or TRIGGERED | MODE == PEEK |
| 1 | Interrupt overrides SCANGO (to zero) to pause the burst and the interrupt handler executes at full speed; Scanner Burst resumes when interrupt completes. | Scanner suspended during interrupt response ($SCANGO = 0$); interrupt executes at full speed and scan resumes when the interrupt is complete. | This bit is ignored |
| 0 | Interrupts do not override SCANGO, and the scan (burst) operation will continue; interrupt response will be delayed until scan completes (latency will be increased). | Scanner accesses NVM during interrupt response. | This bit is ignored |

In general, if $INTM = 0$, the scanner will take precedence over the interrupt, resulting in decreased interrupt processing speed and/or increased interrupt response latency. If $INTM = 1$, the interrupt will take precedence and have a better speed, delaying the memory scan.

14.10.6 WWDT Interaction

Operation of the WWDT is not affected by scanner activity. Hence, it is possible that long scans, particularly in Burst mode, may exceed the WWDT time-out period and result in an undesired device Reset. This may be considered when performing memory scans with an application that also utilizes WWDT.

14.10.7 In-Circuit Debug (ICD) Interaction

The scanner freezes when an ICD halt occurs, and remains frozen until user-mode operation resumes. The debugger may inspect the **SCANCON0** and **SCANLADR** registers to determine the state of the scan.

The ICD interaction with each operating mode is summarized in the following table.

Table 14-3. ICD and Scanner Interactions

| ICD Halt | Scanner Operating Mode | | |
|------------------|--|---|---|
| | Peek | Concurrent Triggered | Burst |
| External Halt | If the scanner will peek an instruction that is not executed (because of ICD entry), the peek will occur after ICD exit, when the instruction executes | If external halt is asserted during a scan cycle, the instruction (delayed by scan) may or may not execute before ICD entry, depending on external halt timing | If external halt is asserted during the BSF(SCANCON.GO), ICD entry occurs, and the burst is delayed until ICD exit. Otherwise, the current NVM-access cycle will complete, and then the scanner will be interrupted for ICD entry. |
| | | If external halt is asserted during the cycle immediately prior to the scan cycle, both scan and instruction execution happen after the ICD exits | If external halt is asserted during the burst, the burst is suspended and will resume with ICD exit |
| PC Breakpoint | | Scan cycle occurs before ICD entry and instruction execution happens after the ICD exits | If PCPB (or single step) is on BSF(SCANCON.GO), the ICD is entered before execution; execution of the burst will occur at ICD exit, and the burst will run to completion. Note that the burst can be interrupted by an external halt. |
| Data Breakpoint | | The instruction with the dataBP executes and ICD entry occurs immediately after. If scan is requested during that cycle, the scan cycle is postponed until the ICD exits. | |
| Single Step | | If a scan cycle is ready after the debug instruction is executed, the scan will read PFM and then the ICD is re-entered | |
| SWBP and ICDINST | | If the scan stalls a SWBP, the scan cycle occurs and the ICD is entered | |

14.10.8 Peripheral Module Disable

Both the CRC and scanner module can be disabled individually by setting the CRCMD and SCANMD bits of the PMD0 register. The SCANMD can be used to enable or disable to the scanner module only if the SCANE bit of Configuration Word 4 is set. If the SCANE bit is cleared, then the scanner module is not available for use and the SCANMD bit is ignored.

14.11 Register Summary - CRC

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------------------|----------|----------|----------------|--------|----------------|-----------|-----------|---|-----------|------|----------|
| 0x00 ... 0x0F43 | Reserved | | | | | | | | | | |
| 0x0F44 | SCANLADR | 7:0 | SCANLADRL[7:0] | | | | | | | | |
| | | 15:8 | SCANLADRH[7:0] | | | | | | | | |
| | | 23:16 | | | SCANLADRU[5:0] | | | | | | |
| 0x0F47 | SCANHADR | 7:0 | SCANHADRL[7:0] | | | | | | | | |
| | | 15:8 | SCANHADRH[7:0] | | | | | | | | |
| | | 23:16 | | | SCANHADRU[5:0] | | | | | | |
| 0x0F4A | SCANCON0 | 7:0 | SCANEN | SCANGO | BUSY | INVALID | INTM | | MODE[1:0] | | |
| 0x0F4B | SCANTRIG | 7:0 | | | | TSEL[4:0] | | | | | |
| 0x0F4C ... 0x0F6E | Reserved | | | | | | | | | | |
| 0x0F6F | CRCDAT | 7:0 | CRCDATL[7:0] | | | | | | | | |
| | | 15:8 | CRCDATH[7:0] | | | | | | | | |
| 0x0F71 | CRCACC | 7:0 | CRCACCL[7:0] | | | | | | | | |
| | | 15:8 | CRCACCH[7:0] | | | | | | | | |
| 0x0F73 | CRCSHIFT | 7:0 | CRCSHIFTL[7:0] | | | | | | | | |
| | | 15:8 | CRCSHIFTH[7:0] | | | | | | | | |
| 0x0F75 | CRCXOR | 7:0 | CRCXORL[6:0] | | | | | | | | CRCXORLO |
| | | 15:8 | CRCXORH[7:0] | | | | | | | | |
| 0x0F77 | CRCCON0 | 7:0 | EN | GO | BUSY | ACCM | | | SHIFTM | FULL | |
| 0x0F78 | CRCCON1 | 7:0 | DLEN[3:0] | | | | PLEN[3:0] | | | | |

14.12 Register Definitions: CRC and Scanner Control

Long bit name prefixes for the CRC are shown in the table below. Refer to the “**Long Bit Names**” section for more information.

Table 14-4. CRC Long Bit Name Prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| CRC | CRC |

Related Links

[Long Bit Names](#)

14.12.1 CRCCON0

Name: CRCCON0
Address: 0xF77
Reset: 0

CRC Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|------|------|---|---|--------|------|
| | EN | GO | BUSY | ACCM | | | SHIFTM | FULL |
| Access | R/W | R/W | RO | R/W | | | R/W | RO |
| Reset | 0 | 0 | 0 | 0 | | | 0 | 0 |

Bit 7 – EN CRC Enable bit

| Value | Description |
|-------|---|
| 1 | CRC module is released from Reset |
| 0 | CRC is disabled and consumes no operating current |

Bit 6 – GO CRC Start bit

| Value | Description |
|-------|-------------------------------|
| 1 | Start CRC serial shifter |
| 0 | CRC serial shifter turned off |

Bit 5 – BUSY CRC Busy bit

| Value | Description |
|-------|--|
| 1 | Shifting in progress or pending |
| 0 | All valid bits in shifter have been shifted into accumulator and EMPTY = 1 |

Bit 4 – ACCM Accumulator Mode bit

| Value | Description |
|-------|----------------------------------|
| 1 | Data is augmented with zeros |
| 0 | Data is not augmented with zeros |

Bit 1 – SHIFTM Shift Mode bit

| Value | Description |
|-------|-------------------|
| 1 | Shift right (LSb) |
| 0 | Shift left (MSb) |

Bit 0 – FULL Data Path Full Indicator bit

| Value | Description |
|-------|--|
| 1 | CRCDATH/L registers are full |
| 0 | CRCDATH/L registers have shifted their data into the shifter |

14.12.2 CRCCON1

Name: CRCCON1
Address: 0xF78
Reset: 0

CRC Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|-----|-----|-----|-----------|-----|-----|-----|
| | DLEN[3:0] | | | | PLEN[3:0] | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:4 – DLEN[3:0] Data Length bits
Denotes the length of the data word -1 (See [Figure 14-1](#))

Bits 3:0 – PLEN[3:0] Polynomial Length bits
Denotes the length of the polynomial -1 (See [Figure 14-1](#))

14.12.3 CRCDAT

Name: CRCDAT
Address: 0xF6F

CRC Data Register

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | CRCDATH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CRCDATL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 15:8 – CRCDATH[7:0] CRC Input/Output Data Most Significant Byte

Bits 7:0 – CRCDATL[7:0] CRC Input/Output Data Least Significant Byte

14.12.4 CRCACC

Name: CRCACC
Address: 0xF71
Reset: 0

CRC Accumulator Register

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| | CRCACCH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CRCACCL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – CRCACCH[7:0] CRC Accumulator Register Most Significant Byte

Writing to this register writes the Most Significant Byte of the CRC accumulator register. Reading from this register reads the Most Significant Byte of the CRC accumulator.

Bits 7:0 – CRCACCL[7:0] CRC Accumulator Register Least Significant Byte

Writing to this register writes the Least Significant Byte of the CRC accumulator register. Reading from this register reads the Least Significant Byte of the CRC accumulator.

14.12.5 CRCSHIFT

Name: CRCSHIFT
Address: 0xF73
Reset: 0

CRC Shift Register

| | | | | | | | | |
|--------|----------------|----|----|----|----|----|----|----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | CRCSHIFTH[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CRCSHIFTL[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – CRCSHIFTH[7:0] CRC Shifter Register Most Significant Byte
 Reading from this register reads the Most Significant Byte of the CRC Shifter.

Bits 7:0 – CRCSHIFTL[7:0] CRC Shifter Register Least Significant Byte
 Reading from this register reads the Least Significant Byte of the CRC Shifter.

14.12.6 CRCXOR**Name:** CRCXOR**Address:** 0xF75

CRC XOR Register

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|--------------|-----|-----|-----|-----|-----|-----|----------|
| | CRCXORH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CRCXORL[6:0] | | | | | | | CRCXORLO |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | U |
| Reset | x | x | x | x | x | x | x | 1 |

Bits 15:8 – CRCXORH[7:0] XOR of Polynomial Term XN Enable Most Significant Byte**Bits 7:1 – CRCXORL[6:0]** XOR of Polynomial Term XN Enable Least Significant Byte**Bit 0 – CRCXORLO** LSb is unimplemented. Read as '1'

14.12.7 SCANCON0**Name:** SCANCON0**Address:** 0xF4A

Scanner Access Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|------|---------|------|---|-----------|-----|
| | SCANEN | SCANGO | BUSY | INVALID | INTM | | MODE[1:0] | |
| Access | R/W | R/W/HC | R | R | R/W | | R/W | R/W |
| Reset | 0 | 0 | 0 | 1 | 0 | | 0 | 0 |

Bit 7 – SCANEN Scanner Enable bit⁽¹⁾

| Value | Description |
|-------|--|
| 1 | Scanner is enabled |
| 0 | Scanner is disabled, internal states are reset |

Bit 6 – SCANGO Scanner GO bit^(2, 3)

| Value | Description |
|-------|--|
| 1 | When the CRC sends a ready signal, NVM will be accessed according to MDx and data passed to the client peripheral. |
| 0 | Scanner operations will not occur |

Bit 5 – BUSY Scanner Busy Indicator bit⁽⁴⁾

| Value | Description |
|-------|--|
| 1 | Scanner cycle is in process |
| 0 | Scanner cycle is complete (or never started) |

Bit 4 – INVALID Scanner Abort Signal bit

| Value | Description |
|-------|---|
| 1 | SCANLADRL/H/U has incremented to an invalid address ⁽⁶⁾ or the scanner was not set up correctly ⁽⁷⁾ |
| 0 | SCANLADRL/H/U points to a valid address |

Bit 3 – INTM NVM Scanner Interrupt Management Mode Select bit

| Value | Condition | Description |
|-------|-----------------|---|
| x | MODE = 10 | This bit is ignored |
| 1 | MODE = 01 | CPU is stalled until all data is transferred. SCANGO is overridden (to zero) during interrupt operation; scanner resumes after returning from interrupt |
| 0 | MODE = 01 | CPU is stalled until all data is transferred. SCANGO is not affected by interrupts, the interrupt response will be affected |
| 1 | MODE = 00 OR 11 | SCANGO is overridden (to zero) during interrupt operation; scan operations resume after returning from interrupt |
| 0 | MODE = 00 OR 11 | Interrupts do not prevent NVM access |

Bits 1:0 – MODE[1:0] Memory Access Mode bits⁽⁵⁾

| Value | Description |
|-------|-----------------|
| 11 | Triggered mode |
| 10 | Peek mode |
| 01 | Burst mode |
| 00 | Concurrent mode |

Notes:

1. Setting SCANEN = 0 (SCANCON0 register) does not affect any other register content.
2. This bit is cleared when LADR > HADR (and a data cycle is not occurring).
3. If INTM = 1, this bit is overridden (to zero, but not cleared) during an interrupt response.
4. BUSY = 1 when the NVM is being accessed, or when the CRC sends a ready signal.
5. See [Table 14-1](#) for more detailed information.
6. An invalid address can occur when the entire range of PFM is scanned and the value of LADR rolls over. An invalid address can also occur if the value in the Scan Low address registers points to a location that is not mapped in the memory map of the device.
7. CRCEN and CRCGO bits must be set before setting SCANGO bit. Refer to [Program Memory Scan Configuration](#).

14.12.8 SCANLADR

Name: SCANLADR
Address: 0xF44
Reset: 0

Scan Low Address Register

| | | | | | | | | |
|--------|----------------|-----|----------------|-----|-----|-----|-----|-----|
| Bit | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | | | SCANLADRU[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | SCANLADRH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | SCANLADRL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 21:16 – SCANLADRU[5:0] Scan Start/Current Address upper byte

Upper bits of the current address to be fetched from, value increments on each fetch of memory.

Bits 15:8 – SCANLADRH[7:0] Scan Start/Current Address high byte

High byte of the current address to be fetched from, value increments on each fetch of memory.

Bits 7:0 – SCANLADRL[7:0] Scan Start/Current Address low byte

Low byte of the current address to be fetched from, value increments on each fetch of memory.

Notes:

1. Registers SCANLADRU/H/L form a 22-bit value, but are not guarded for atomic or asynchronous access; registers should only be read or written while **SCANGO** = 0.
2. While **SCANGO** = 1, writing to this register is ignored.

14.12.9 SCANHADR

Name: SCANHADR
Address: 0xF47
Reset: 0

Scan High Address Register

| | | | | | | | | |
|--------|----------------|-----|----------------|-----|-----|-----|-----|-----|
| Bit | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | | | SCANHADRU[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 1 | 1 | 1 | 1 | 1 | 1 |
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | SCANHADRH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | SCANHADRL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 21:16 – SCANHADRU[5:0] Scan End Address bits
 Upper bits of the address at the end of the designated scan

Bits 15:8 – SCANHADRH[7:0] Scan End Address bits
 High byte of the address at the end of the designated scan

Bits 7:0 – SCANHADRL[7:0] Scan End Address bits
 Low byte of the address at the end of the designated scan

Notes:

1. Registers SCANHADRU/H/L form a 22-bit value but are not guarded for atomic or asynchronous access; registers should only be read or written while **SCANGO** = 0.
2. While **SCANGO** = 1, writing to this register is ignored.

14.12.10 SCANTRIG

Name: SCANTRIG
Address: 0xF4B
Reset: 0

SCAN Trigger Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|-----------|-----|-----|-----|-----|
| | | | | TSEL[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – TSEL[4:0] Scanner Data Trigger Input Selection bits

Table 14-5. SCAN Trigger Sources

| TSEL | Trigger Source |
|---------------|-----------------|
| 11000 – 11111 | Reserved |
| 10111 | CLC8_out |
| 10110 | CLC7_out |
| 10101 | CLC6_out |
| 10100 | CLC5_out |
| 10011 | CLC4_out |
| 10010 | CLC3_out |
| 10001 | CLC2_out |
| 10000 | CLC1_out |
| 01001 – 01111 | Reserved |
| 01000 | TMR6_postscaled |
| 00111 | TMR5_output |
| 00110 | TMR4_postscaled |
| 00101 | TMR3_output |
| 00100 | TMR2_postscaled |
| 00011 | TMR1_output |
| 00010 | TMR0_output |
| 00001 | CLKREF_output |
| 00000 | LFINTOSC |

15. Interrupts

The PIC18F26/45/46Q10 devices have multiple interrupt sources and an interrupt priority feature that allows most interrupt sources to be assigned a high or low-priority level. The high-priority interrupt vector is at 0008h and the low-priority interrupt vector is at 0018h. A high-priority interrupt event will interrupt a low-priority interrupt that may be in progress.

The registers for controlling interrupt operation are:

- INTCON
- PIRx (Interrupt flags)
- PEx (Interrupt enables)
- IPRx (High/Low interrupt priority)

It is recommended that the Microchip header files supplied with MPLAB® IDE be used for the symbolic bit names in these registers. This allows the assembler/compiler to automatically take care of the placement of these bits within the specified register.

In general, interrupt sources have three bits to control their operation. They are:

- **Flag bit** to indicate that an interrupt event occurred
- **Enable bit** that allows program execution to branch to the interrupt vector address when the flag bit is set
- **Priority bit** to select high priority or low priority

15.1 Midrange Compatibility

When the **IPEN** bit is cleared (default state), the interrupt priority feature is disabled and interrupts are compatible with PIC® microcontroller midrange devices. In Compatibility mode, the interrupt priority bits of the IPRx registers have no effect. The **PEIE/GIEL** bit is the global interrupt enable for the peripherals. The **PEIE/GIEL** bit disables only the peripheral interrupt sources and enables the peripheral interrupt sources when the **GIE/GIEH** bit is also set. The **GIE/GIEH** bit is the global interrupt enable which enables all non-peripheral interrupt sources and disables all interrupt sources, including the peripherals. All interrupts branch to address 0008h in Compatibility mode.

15.2 Interrupt Priority

The interrupt priority feature is enabled by setting the **IPEN** bit. When interrupt priority is enabled the **GIE/GIEH** and **PEIE/GIEL** Global Interrupt Enable bits of Compatibility mode are replaced by the **GIEH** high priority, and **GIEL** low priority, global interrupt enables. When the **IPEN** bit is set, the **GIEH** bit enables all interrupts which have their associated bit in the IPRx register set. When the **GIEH** bit is cleared, then all interrupt sources including those selected as low priority in the IPRx register are disabled.

When both **GIEH** and **GIEL** bits are set, all interrupts selected as low priority sources are enabled.

A high-priority interrupt will vector immediately to address 00 0008h and a low-priority interrupt will vector to address 00 0018h.

15.3 Interrupt Response

When an interrupt is responded to, the Global Interrupt Enable bit is cleared to disable further interrupts. The **GIE/GIEH** bit is the Global Interrupt Enable when the **IPEN** bit is cleared. When the **IPEN** bit is set, enabling interrupt priority levels, the **GIEH** bit is the high priority Global Interrupt Enable and the **GIEL** bit is the low priority Global Interrupt Enable. High-priority interrupt sources can interrupt a low-priority interrupt. Low-priority interrupts are not processed while high-priority interrupts are in progress.

The return address is pushed onto the stack and the PC is loaded with the interrupt vector address (0008h or 0018h). Once in the Interrupt Service Routine, the source(s) of the interrupt can be

determined by polling the interrupt flag bits in the INTCONx and PIRx registers. The interrupt flag bits must be cleared by software before re-enabling interrupts to avoid repeating the same interrupt.

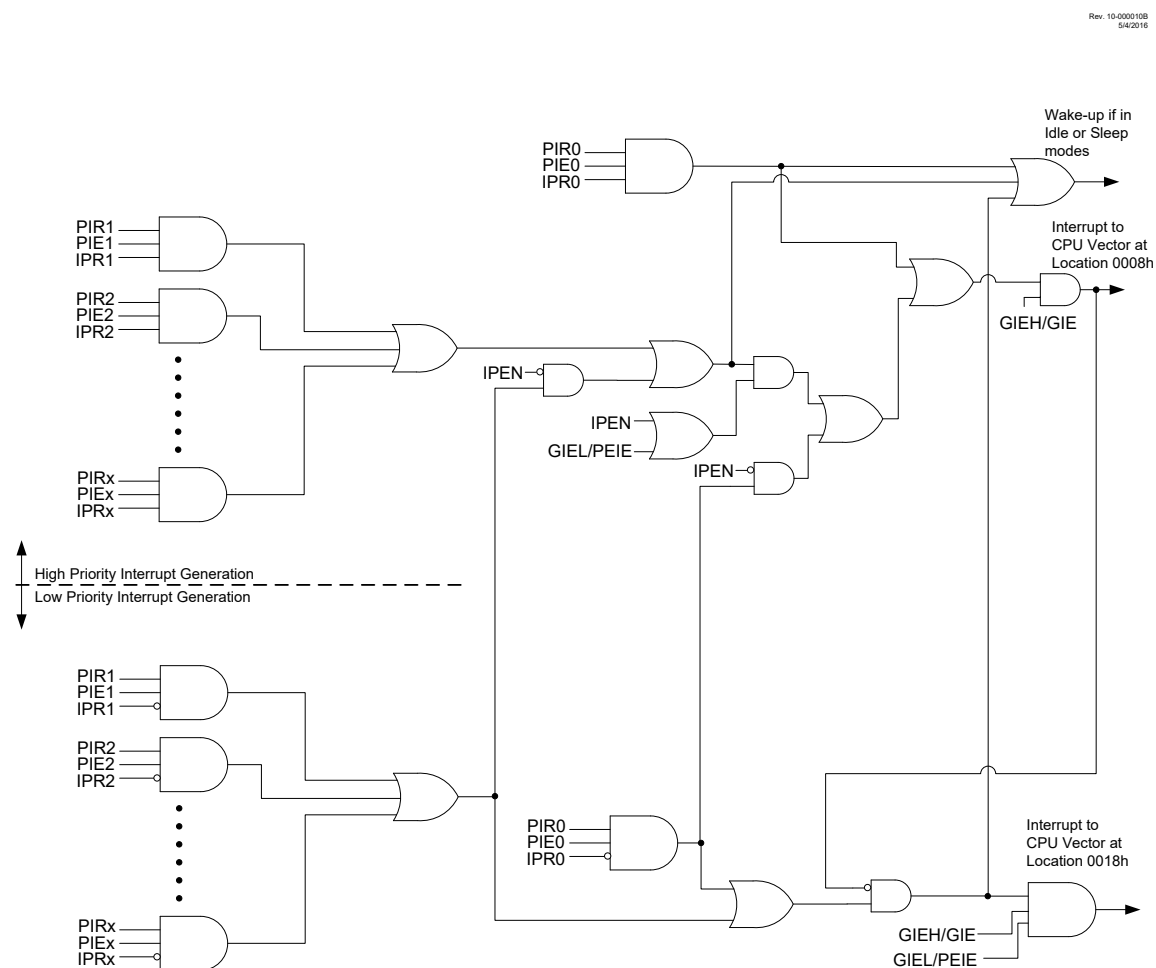
The “return from interrupt” instruction, `RETFIE`, exits the interrupt routine and sets the **GIE/GIEH** bit (GIEH or GIEL if priority levels are used), which re-enables interrupts.

For external interrupt events, such as the INT pins or the interrupt-on-change pins, the interrupt latency will be three to four instruction cycles. The exact latency is the same for one-cycle or two-cycle instructions. Individual interrupt flag bits are set, regardless of the status of their corresponding enable bits or the Global Interrupt Enable bit.



Important: Do not use the `MOVFF` instruction to modify any of the interrupt control registers while any interrupt is enabled. Doing so may cause erratic microcontroller behavior.

Figure 15-1. PIC18 Interrupt Logic



15.4 INTCON Registers

The INTCON registers are readable and writable registers, which contain various enable and priority bits.

15.5 PIR Registers

The PIR registers contain the individual flag bits for the peripheral interrupts. Due to the number of peripheral interrupt sources, there are 8 PIR registers.

15.6 PIE Registers

The PIE registers contain the individual enable bits for the peripheral interrupts. Due to the number of peripheral interrupt sources, there are 8 Peripheral Interrupt Enable registers. When IPEN = 0, the [PEIE/GIEL](#) bit must be set to enable any of these peripheral interrupts.

15.7 IPR Registers

The IPR registers contain the individual priority bits for the peripheral interrupts. Due to the number of peripheral interrupt sources, there are 8 Peripheral Interrupt Priority registers. Using the priority bits requires that the Interrupt Priority Enable ([IPEN](#)) bit be set.

15.8 INTn Pin Interrupts

PIC18F26/45/46Q10 devices have 3 external interrupt sources which can be assigned to any pin on PORTA and PORTB using PPS. The external interrupt sources are edge-triggered. If the corresponding INTxEDG bit in the [INTCON](#) register is set (= 1), the interrupt is triggered by a rising edge. If the bit is clear, the trigger is on the falling edge.

All external interrupts (INT0, INT1, INT2) can wake up the processor from Idle or Sleep modes if bit INTxE was set prior to going into those modes. If the Global Interrupt Enable bit ([GIE/GIEH](#)) is set, the processor will branch to the interrupt vector following wake-up.

Interrupt priority is determined by the value contained in the corresponding interrupt priority bit (INT0P, INT1P, INT2P) of the [IPRO](#) register.

15.9 TMR0 Interrupt

In 8-bit mode (which is the default), an overflow in the TMR0 register (FFh → 00h) will set flag bit, TMR0IF. In 16-bit mode, an overflow in the TMR0H:TMR0L register pair (FFFFh → 0000h) will set TMR0IF. The interrupt can be enabled/disabled by setting/clearing enable bit, [TMR0IE](#). Interrupt priority for Timer0 is determined by the value contained in the interrupt priority bit, [TMR0IP](#). See “**Timer0 Module**” for further details on the Timer0 module.

15.10 Interrupt-on-Change

An input change on any port pins that support IOC sets Flag bit, [IOCIF](#). The interrupt can be enabled/disabled by setting/clearing the enable bit, [IOCIE](#). Pins must also be individually enabled in the IOCxP and IOCxN register. [IOCIF](#) is a read-only bit and the flag can be cleared by clearing the corresponding IOCxF registers. For more information, refer to chapter “*Interrupt-on-Change*”.

Related Links

[Interrupt-on-Change](#)

15.11 Context Saving During Interrupts

During interrupts, the return PC address is saved on the stack. Additionally, the WREG, STATUS and BSR registers are saved on the fast return stack. If a fast return from interrupt is not used the user may need to save the WREG, STATUS and BSR registers on entry to the Interrupt Service Routine. Depending on the user's application, other registers may also need to be saved. [Saving Status, WREG and BSR Registers in RAM](#) saves and restores the WREG, STATUS and BSR registers during an Interrupt Service Routine.

Example 15-1. Saving Status, WREG and BSR Registers in RAM

```
MOVWF    W_TEMP          ; W_TEMP is in virtual bank
MOVFF    STATUS, STATUS_TEMP ; STATUS_TEMP located anywhere
MOVFF    BSR, BSR_TEMP    ; BSR_TEMP located anywhere
```

```
;
; USER ISR CODE
;
    MOVFF    BSR_TEMP, BSR      ; Restore BSR
    MOVF     W_TEMP, W          ; Restore WREG
    MOVFF    STATUS_TEMP, STATUS ; Restore STATUS
```

Related Links

[Fast Register Stack](#)

15.12 Register Summary - Interrupt Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|----------|-----------|--------|--------|--------|---------|---------|---------|
| 0x00 ... 0x0EB4 | Reserved | | | | | | | | | |
| 0x0EB5 | IPR0 | 7:0 | | | TMR0IP | IOCIP | | INT2IP | INT1IP | INT0IP |
| 0x0EB6 | IPR1 | 7:0 | OSCFIP | CSWIP | | | | | ADTIP | ADIP |
| 0x0EB7 | IPR2 | 7:0 | HLVDIP | ZCDIP | | | | | C2IP | C1IP |
| 0x0EB8 | IPR3 | 7:0 | RC2IP | TX2IP | RC1IP | TX1IP | BCL2IP | SSP2IP | BCL1IP | SSP1IP |
| 0x0EB9 | IPR4 | 7:0 | | | TMR6IP | TMR5IP | TMR4IP | TMR3IP | TMR2IP | TMR1IP |
| 0x0EBA | IPR5 | 7:0 | CLC4IP | CLC3IP | CLC2IP | CLC1IP | | TMR5GIP | TMR3GIP | TMR1GIP |
| 0x0EBB | IPR6 | 7:0 | CLC8IP | CLC7IP | CLC6IP | CLC5IP | | | CCP2IP | CCP1IP |
| 0x0EBC | IPR7 | 7:0 | SCANIP | CRCIP | NVMIP | | | | | CWG1IP |
| 0x0EBD | PIE0 | 7:0 | | | TMR0IE | IOCIE | | INT2IE | INT1IE | INT0IE |
| 0x0EBE | PIE1 | 7:0 | OSCFIE | CSWIE | | | | | ADTIE | ADIE |
| 0x0EBF | PIE2 | 7:0 | HLVDIE | ZCDIE | | | | | C2IE | C1IE |
| 0x0EC0 | PIE3 | 7:0 | RC2IE | TX2IE | RC1IE | TX1IE | BCL2IE | SSP2IE | BCL1IE | SSP1IE |
| 0x0EC1 | PIE4 | 7:0 | | | TMR6IE | TMR5IE | TMR4IE | TMR3IE | TMR2IE | TMR1IE |
| 0x0EC2 | PIE5 | 7:0 | CLC4IE | CLC3IE | CLC2IE | CLC1IE | | TMR5GIE | TMR3GIE | TMR1GIE |
| 0x0EC3 | PIE6 | 7:0 | CLC8IE | CLC7IE | CLC6IE | CLC5IE | | | CCP2IE | CCP1IE |
| 0x0EC4 | PIE7 | 7:0 | SCANIE | CRCIE | NVMIE | | | | | CWG1IE |
| 0x0EC5 | PIR0 | 7:0 | | | TMR0IF | IOCIF | | INT2IF | INT1IF | INT0IF |
| 0x0EC6 | PIR1 | 7:0 | OSCFIF | CSWIF | | | | | ADTIF | ADIF |
| 0x0EC7 | PIR2 | 7:0 | HLVDIF | ZCDIF | | | | | C2IF | C1IF |
| 0x0EC8 | PIR3 | 7:0 | RC2IF | TX2IF | RC1IF | TX1IF | BCL2IF | SSP2IF | BCL1IF | SSP1IF |
| 0x0EC9 | PIR4 | 7:0 | | | TMR6IF | TMR5IF | TMR4IF | TMR3IF | TMR2IF | TMR1IF |
| 0x0ECA | PIR5 | 7:0 | CLC4IF | CLC3IF | CLC2IF | CLC1IF | | TMR5GIF | TMR3GIF | TMR1GIF |
| 0x0ECB | PIR6 | 7:0 | CLC8IF | CLC7IF | CLC6IF | CLC5IF | | | CCP2IF | CCP1IF |
| 0x0ECC | PIR7 | 7:0 | SCANIF | CRCIF | NVMIF | | | | | CWG1IF |
| 0x0ECD ... 0x0FF1 | Reserved | | | | | | | | | |
| 0x0FF2 | INTCON | 7:0 | GIE/GIEH | PEIE/GIEL | IPEN | | | INT2EDG | INT1EDG | INT0EDG |

15.13 Register Definitions: Interrupt Control

15.13.1 INTCON

Name: INTCON

Address: 0xFF2

Interrupt Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----------|-----------|------|---|---|---------|---------|---------|
| | GIE/GIEH | PEIE/GIEL | IPEN | | | INT2EDG | INT1EDG | INT0EDG |
| Access | R/W | R/W | R/W | | | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | | | 1 | 1 | 1 |

Bit 7 – GIE/GIEH Global Interrupt Enable bit

| Value | Condition | Description |
|-------|--------------------|---|
| 1 | If IPEN = 1 | Enables all unmasked interrupts and cleared by hardware for high-priority interrupts only |
| 0 | If IPEN = 1 | Disables all interrupts |
| 1 | If IPEN = 0 | Enables all unmasked interrupts and cleared by hardware for all interrupts |
| 0 | If IPEN = 0 | Disables all interrupts |

Bit 6 – PEIE/GIEL Peripheral Interrupt Enable bit

| Value | Condition | Description |
|-------|--------------------|--|
| 1 | If IPEN = 1 | Enables all low-priority interrupts and cleared by hardware for low-priority interrupts only |
| 0 | If IPEN = 1 | Disables all low-priority interrupts |
| 1 | If IPEN = 0 | Enables all unmasked peripheral interrupts |
| 0 | If IPEN = 0 | Disables all peripheral interrupts |

Bit 5 – IPEN Interrupt Priority Enable bit

| Value | Description |
|-------|---------------------------------------|
| 1 | Enable priority levels on interrupts |
| 0 | Disable priority levels on interrupts |

Bits 0, 1, 2 – INTxEDG External Interrupt 'x' Edge Select bit

| Value | Description |
|-------|---------------------------------------|
| 1 | Interrupt on rising edge of INTx pin |
| 0 | Interrupt on falling edge of INTx pin |



Important: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit. User software must ensure the appropriate interrupt flag bits are cleared prior to enabling an interrupt. This feature allows for software polling.

15.13.2 PIR0

Name: PIR0
Address: 0xEC5

Peripheral Interrupt Request (Flag) Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|-------|---|--------|--------|--------|
| | | | TMR0IF | IOCIF | | INT2IF | INT1IF | INT0IF |
| Access | | | R/W | R | | R/W | R/W | R/W |
| Reset | | | 0 | 0 | | 0 | 0 | 0 |

Bit 5 – TMR0IF Timer0 Interrupt Flag bit⁽¹⁾

| Value | Description |
|-------|--|
| 1 | TMR0 register has overflowed (must be cleared by software) |
| 0 | TMR0 register has not overflowed |

Bit 4 – IOCIF Interrupt-on-Change Flag bit^(1,2)

| Value | Description |
|-------|--|
| 1 | IOC event has occurred (must be cleared by software) |
| 0 | IOC event has not occurred |

Bits 0, 1, 2 – INTxIF External Interrupt 'x' Flag bit^(1,3)

| Value | Description |
|-------|---|
| 1 | External Interrupt 'x' has occurred |
| 0 | External Interrupt 'x' has not occurred |

Notes:

1. Interrupts are not disabled by the [PEIE](#) bit.
2. IOCIF is a read-only bit; to clear the interrupt condition, all bits in the IOCIF register must be cleared.
3. The external interrupt GPIO pin is selected by the INTPPS register.

15.13.3 PIR1

Name: PIR1
Address: 0xEC6

Peripheral Interrupt Request (Flag) Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|-------|------|
| | OSCFIF | CSWIF | | | | | ADTIF | ADIF |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 0 | 0 | | | | | 0 | 0 |

Bit 7 – OSCFIF Oscillator Fail Interrupt Flag bit

| Value | Description |
|-------|---|
| 1 | Device oscillator failed, clock input has changed to HFINTOSC (must be cleared by software) |
| 0 | Device clock operating |

Bit 6 – CSWIF Clock-Switch Interrupt Flag bit⁽¹⁾

| Value | Description |
|-------|--|
| 1 | New oscillator is ready for switch (must be cleared by software) |
| 0 | New oscillator is not ready for switch or has not been started |

Bit 1 – ADTIF ADC Threshold Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | ADC Threshold interrupt has occurred (must be cleared by software) |
| 0 | ADC Threshold event is not complete or has not been started |

Bit 0 – ADIF ADC Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | An A/D conversion completed (must be cleared by software) |
| 0 | The A/D conversion is not complete or has not been started |

Note:

1. The CSWIF interrupt will not wake the system from Sleep. The system will Sleep until another interrupt causes the wake-up.

Related Links

[Clock Switch and Sleep](#)

15.13.4 PIR2

Name: PIR2
Address: 0xEC7

Peripheral Interrupt Request (Flag) Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|------|------|
| | HLVDIF | ZCDIF | | | | | C2IF | C1IF |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 0 | 0 | | | | | 0 | 0 |

Bit 7 – HLVDIF HLVD Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | HLVD interrupt event has occurred |
| 0 | HLVD interrupt event has not occurred or has not been set up |

Bit 6 – ZCDIF Zero-Cross Detect Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | ZCD Output has changed (must be cleared in software) |
| 0 | ZCD Output has not changed |

Bits 0, 1 – CxIF Comparator 'x' Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | Comparator Cx output has changed (must be cleared by software) |
| 0 | Comparator Cx output has not changed |

15.13.5 PIR3

Name: PIR3
Address: 0xEC8

Peripheral Interrupt Request (Flag) Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|--------|--------|--------|--------|
| | RC2IF | TX2IF | RC1IF | TX1IF | BCL2IF | SSP2IF | BCL1IF | SSP1IF |
| Access | R | R | R | R | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 5, 7 – RCxIF EUSARTx Receive Interrupt Flag bit

| Value | Description |
|-------|---|
| 1 | The EUSARTx receive buffer, RCxREG, is full (cleared by reading RCxREG) |
| 0 | The EUSARTx receive buffer is empty |

Bits 4, 6 – TXxIF EUSARTx Transmit Interrupt Flag bit

| Value | Description |
|-------|---|
| 1 | The EUSARTx transmit buffer, TXxREG, is empty (cleared by writing TXxREG) |
| 0 | The EUSARTx transmit buffer is full |

Bits 1, 3 – BCLxIF MSSPx Bus Collision Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | A bus collision has occurred while the MSSPx module configured in I ² C host was transmitting (must be cleared in software) |
| 0 | No bus collision occurred |

Bits 0, 2 – SSPxIF Synchronous Serial Port 'x' Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | The transmission/reception is complete (must be cleared in software) |
| 0 | Waiting to transmit/receive |

15.13.6 PIR4

Name: PIR4
Address: 0xEC9

Peripheral Interrupt Request (Flag) Register 4

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|--------|--------|--------|--------|--------|
| | | | TMR6IF | TMR5IF | TMR4IF | TMR3IF | TMR2IF | TMR1IF |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 5 – TMR6IF TMR6 to PR6 Match Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR6 to PR6 match occurred (must be cleared in software) |
| 0 | No TMR6 to PR6 match occurred |

Bit 4 – TMR5IF TMR5 Overflow Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR5 register overflowed (must be cleared in software) |
| 0 | TMR5 register did not overflow |

Bit 3 – TMR4IF TMR4 to PR4 Match Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR4 to PR4 match occurred (must be cleared in software) |
| 0 | No TMR4 to PR4 match occurred |

Bit 2 – TMR3IF TMR3 Overflow Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR3 register overflowed (must be cleared in software) |
| 0 | TMR3 register did not overflow |

Bit 1 – TMR2IF TMR2 to PR2 Match Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR2 to PR2 match occurred (must be cleared in software) |
| 0 | No TMR2 to PR2 match occurred |

Bit 0 – TMR1IF TMR1 Overflow Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR1 register overflowed (must be cleared in software) |
| 0 | TMR1 register did not overflow |

15.13.7 PIR5

Name: PIR5
Address: 0xECA

Peripheral Interrupt Request (Flag) Register 5

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---------|---------|---------|
| | CLC4IF | CLC3IF | CLC2IF | CLC1IF | | TMR5GIF | TMR3GIF | TMR1GIF |
| Access | R/W | R/W | R/W | R/W | | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | | 0 | 0 | 0 |

Bits 4, 5, 6, 7 – CLCxIF CLCx Interrupt Flag bit

| Value | Description |
|-------|----------------------------|
| 1 | A CLCx interrupt occurred |
| 0 | No CLCx interrupt occurred |

Bit 2 – TMR5GIF TMR5 Gate Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR5 gate interrupt occurred (must be cleared in software) |
| 0 | No TMR5 gate occurred |

Bit 1 – TMR3GIF TMR3 Gate Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR3 gate interrupt occurred (must be cleared in software) |
| 0 | No TMR3 gate occurred |

Bit 0 – TMR1GIF TMR1 Gate Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | TMR1 gate interrupt occurred (must be cleared in software) |
| 0 | No TMR1 gate occurred |

15.13.8 PIR6

Name: PIR6
Address: 0xECB

PIR6 Peripheral Interrupt Request (Flag) Register 6

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---|--------|--------|
| | CLC8IF | CLC7IF | CLC6IF | CLC5IF | | | CCP2IF | CCP1IF |
| Access | R/W | R/W | R/W | R/W | | | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | | | 0 | 0 |

Bits 4, 5, 6, 7 – CLCyIF CLCx Interrupt Flag bit

| Value | Description |
|-------|----------------------------|
| 1 | A CLCx interrupt occurred |
| 0 | No CLCx interrupt occurred |

Bit 1 – CCP2IF ECCP2 Interrupt Flag bit

| Value | Condition | Description |
|-------|--------------|---|
| 1 | Capture mode | A TMR register capture occurred (must be cleared in software) |
| 0 | Capture mode | No TMR register capture occurred |
| 1 | Compare mode | A TMR register compare match occurred (must be cleared in software) |
| 0 | Compare mode | No TMR register compare match occurred |
| — | PWM mode | Unused in PWM mode |

Bit 0 – CCP1IF ECCP1 Interrupt Flag bit

| Value | Condition | Description |
|-------|--------------|---|
| 1 | Capture mode | A TMR register capture occurred (must be cleared in software) |
| 0 | Capture mode | No TMR register capture occurred |
| 1 | Compare mode | A TMR register compare match occurred (must be cleared in software) |
| 0 | Compare mode | No TMR register compare match occurred |
| — | PWM mode | Unused in PWM mode |

15.13.9 PIR7

Name: PIR7
Address: 0xECC

Peripheral Interrupt Request (Flag) Register 7

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|-------|---|---|---|---|--------|
| | SCANIF | CRCIF | NVMIF | | | | | CWG1IF |
| Access | R/W | R/W | R/W | | | | | R/W |
| Reset | 0 | 0 | 0 | | | | | 0 |

Bit 7 – SCANIF SCAN Interrupt Flag bit

| Value | Description |
|-------|---|
| 1 | SCAN interrupt has occurred (must be cleared in software) |
| 0 | SCAN interrupt has not occurred or has not been started |

Bit 6 – CRCIF CRC Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | CRC interrupt has occurred (must be cleared in software) |
| 0 | CRC interrupt has not occurred or has not been started |

Bit 5 – NVMIF NVM Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | NVM interrupt has occurred (must be cleared in software) |
| 0 | NVM interrupt has not occurred or has not been started |

Bit 0 – CWG1IF CWG Interrupt Flag bit

| Value | Description |
|-------|--|
| 1 | CWG interrupt has occurred (must be cleared in software) |
| 0 | CWG interrupt has not occurred or has not been started |

15.13.10 PIE0

Name: PIE0
Address: 0xEBD

Peripheral Interrupt Enable Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|-------|---|--------|--------|--------|
| | | | TMR0IE | IOCIE | | INT2IE | INT1IE | INT0IE |
| Access | | | R/W | R/W | | R/W | R/W | R/W |
| Reset | | | 0 | 0 | | 0 | 0 | 0 |

Bit 5 – TMR0IE Timer0 Interrupt Enable bit⁽¹⁾

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 4 – IOCIE Interrupt-on-Change Enable bit⁽¹⁾

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bits 0, 1, 2 – INTxIE External Interrupt 'x' Enable bit⁽¹⁾

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Note:

- PIR0 interrupts are not disabled by the PEIE bit in the INTCON register.

15.13.11 PIE1

Name: PIE1
Address: 0xEBE

Peripheral Interrupt Enable Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|-------|------|
| | OSCFIE | CSWIE | | | | | ADTIE | ADIE |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 0 | 0 | | | | | 0 | 0 |

Bit 7 – OSCFIE Oscillator Fail Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 6 – CSWIE Clock-Switch Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 1 – ADTIE ADC Threshold Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 0 – ADIE ADC Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.12 PIE2

Name: PIE2
Address: 0xEBF

Peripheral Interrupt Enable Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|------|------|
| | HLVDIE | ZCDIE | | | | | C2IE | C1IE |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 0 | 0 | | | | | 0 | 0 |

Bit 7 – HLVDIE HLVD Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 6 – ZCDIE Zero-Cross Detect Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bits 0, 1 – CxIE Comparator 'x' Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.13 PIE3

Name: PIE3
Address: 0xEC0

Peripheral Interrupt Enable Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|--------|--------|--------|--------|
| | RC2IE | TX2IE | RC1IE | TX1IE | BCL2IE | SSP2IE | BCL1IE | SSP1IE |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 5, 7 – RCxIE EUSARTx Receive Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bits 4, 6 – TxIE EUSARTx Transmit Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bits 1, 3 – BCLxIE MSSPx Bus Collision Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bits 0, 2 – SSPxIE Synchronous Serial Port 'x' Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.14 PIE4

Name: PIE4
Address: 0xEC1

Peripheral Interrupt Enable Register 4

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|--------|--------|--------|--------|--------|
| | | | TMR6IE | TMR5IE | TMR4IE | TMR3IE | TMR2IE | TMR1IE |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 5 – TMR6IE TMR6 to PR6 Match Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 4 – TMR5IE TMR5 Overflow Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 3 – TMR4IE TMR4 to PR4 Match Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 2 – TMR3IE TMR3 Overflow Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 1 – TMR2IE TMR2 to PR2 Match Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 0 – TMR1IE TMR1 Overflow Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.15 PIE5

Name: PIE5
Address: 0xEC2

Peripheral Interrupt Enable Register 5

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---------|---------|---------|
| | CLC4IE | CLC3IE | CLC2IE | CLC1IE | | TMR5GIE | TMR3GIE | TMR1GIE |
| Access | R/W | R/W | R/W | R/W | | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | | 0 | 0 | 0 |

Bits 4, 5, 6, 7 – CLCxIE CLCx Interrupt Enable bit

| Value | Description |
|-------|-------------------------|
| 1 | CLCx Interrupt Enabled |
| 0 | CLCx Interrupt Disabled |

Bit 2 – TMR5GIE TMR5 Gate Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 1 – TMR3GIE TMR3 Gate Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 0 – TMR1GIE TMR1 Gate Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.16 PIE6

Name: PIE6
Address: 0xEC3

Peripheral Interrupt Enable Register 6

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---|--------|--------|
| | CLC8IE | CLC7IE | CLC6IE | CLC5IE | | | CCP2IE | CCP1IE |
| Access | R/W | R/W | R/W | R/W | | | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | | | 0 | 0 |

Bits 4, 5, 6, 7 – CLC_yIE CLC_x Interrupt Enable bit

| Value | Description |
|-------|--------------------------------------|
| 1 | CLC _x Interrupts Enabled |
| 0 | CLC _x Interrupts Disabled |

Bit 1 – CCP2IE ECCP2 Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 0 – CCP1IE ECCP1 Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.17 PIE7

Name: PIE7
Address: 0xEC4

Peripheral Interrupt Enable Register 7

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|-------|---|---|---|---|--------|
| | SCANIE | CRCIE | NVMIE | | | | | CWG1IE |
| Access | R/W | R/W | R/W | | | | | R/W |
| Reset | 0 | 0 | 0 | | | | | 0 |

Bit 7 – SCANIE SCAN Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 6 – CRCIE CRC Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 5 – NVMIE NVM Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

Bit 0 – CWG1IE CWG Interrupt Enable bit

| Value | Description |
|-------|-------------|
| 1 | Enabled |
| 0 | Disabled |

15.13.18 IPR0

Name: IPR0
Address: 0xEB5

Peripheral Interrupt Priority Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|-------|---|--------|--------|--------|
| | | | TMR0IP | IOCIP | | INT2IP | INT1IP | INT0IP |
| Access | | | R/W | R/W | | R/W | R/W | R/W |
| Reset | | | 1 | 1 | | 1 | 1 | 1 |

Bit 5 – TMR0IP Timer0 Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 4 – IOCIP Interrupt-on-Change Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bits 0, 1, 2 – INTxIP External Interrupt 'x' Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.19 IPR1

Name: IPR1
Address: 0xEB6

Peripheral Interrupt Priority Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|-------|------|
| | OSCFIP | CSWIP | | | | | ADTIP | ADIP |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 1 | 1 | | | | | 1 | 1 |

Bit 7 – OSCFIP Oscillator Fail Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 6 – CSWIP Clock-Switch Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 1 – ADTIP ADC Threshold Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 0 – ADIP ADC Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.20 IPR2

Name: IPR2
Address: 0xEB7

Peripheral Interrupt Priority Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|---|---|---|------|------|
| | HLVDIP | ZCDIP | | | | | C2IP | C1IP |
| Access | R/W | R/W | | | | | R/W | R/W |
| Reset | 1 | 1 | | | | | 1 | 1 |

Bit 7 – HLVDIP HLVD Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 6 – ZCDIP Zero-Cross Detect Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bits 0, 1 – CxIP Comparator 'x' Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.21 IPR3

Name: IPR3
Address: 0xEB8

Peripheral Interrupt Priority Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|--------|--------|--------|--------|
| | RC2IP | TX2IP | RC1IP | TX1IP | BCL2IP | SSP2IP | BCL1IP | SSP1IP |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 5, 7 – RCxIP EUSARTx Receive Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bits 4, 6 – TxIP EUSARTx Transmit Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bits 1, 3 – BCLxIP MSSPx Bus Collision Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bits 0, 2 – SSPxIP Synchronous Serial Port 'x' Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.22 IPR4

Name: IPR4
Address: 0xEB9

Peripheral Interrupt Priority Register 4

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|--------|--------|--------|--------|--------|--------|
| | | | TMR6IP | TMR5IP | TMR4IP | TMR3IP | TMR2IP | TMR1IP |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 1 | 1 | 1 | 1 | 1 | 1 |

Bit 5 – TMR6IP TMR6 to PR6 Match Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 4 – TMR5IP TMR5 Overflow Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 3 – TMR4IP TMR4 to PR4 Match Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 2 – TMR3IP TMR3 Overflow Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 1 – TMR2IP TMR2 to PR2 Match Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 0 – TMR1IP TMR1 Overflow Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.23 IPR5

Name: IPR5
Address: 0xEBA

Peripheral Interrupt Priority Register 5

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---------|---------|---------|
| | CLC4IP | CLC3IP | CLC2IP | CLC1IP | | TMR5GIP | TMR3GIP | TMR1GIP |
| Access | R/W | R/W | R/W | R/W | | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | | 1 | 1 | 1 |

Bits 4, 5, 6, 7 – CLCxIP CLCx Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 2 – TMR5GIP TMR5 Gate Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 1 – TMR3GIP TMR3 Gate Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 0 – TMR1GIP TMR1 Gate Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.24 IPR6

Name: IPR6
Address: 0xEBB

Peripheral Interrupt Priority Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|---|---|--------|--------|
| | CLC8IP | CLC7IP | CLC6IP | CLC5IP | | | CCP2IP | CCP1IP |
| Access | R/W | R/W | R/W | R/W | | | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | | | 1 | 1 |

Bits 4, 5, 6, 7 – CLCyIP CLCx Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 1 – CCP2IP ECCP2 Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 0 – CCP1IP ECCP1 Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

15.13.25 IPR7

Name: IPR7
Address: 0xEBC

Peripheral Interrupt Priority Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|-------|---|---|---|---|--------|
| | SCANIP | CRCIP | NVMIP | | | | | CWG1IP |
| Access | R/W | R/W | R/W | | | | | R/W |
| Reset | 1 | 1 | 1 | | | | | 1 |

Bit 7 – SCANIP SCAN Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 6 – CRCIP CRC Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 5 – NVMIP NVM Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

Bit 0 – CWG1IP CWG Interrupt Priority bit

| Value | Description |
|-------|---------------|
| 1 | High priority |
| 0 | Low priority |

16. I/O Ports

Table 16-1. Port Availability per Device

| Device | PORTA | PORTB | PORTC | PORTD | PORTE |
|----------------|-------|-------|-------|-------|-------|
| PIC18F26Q10 | • | • | • | | • |
| PIC18F45/46Q10 | • | • | • | • | • |

Each port has eight registers to control the operation. These registers are:

- PORTx registers (reads the levels on the pins of the device)
- LATx registers (output latch)
- TRISx registers (data direction)
- ANSELx registers (analog select)
- WPUx registers (weak pull-up)
- INLVLx (input level control)
- SLRCONx registers (slew rate control)
- ODCONx registers (open-drain control)

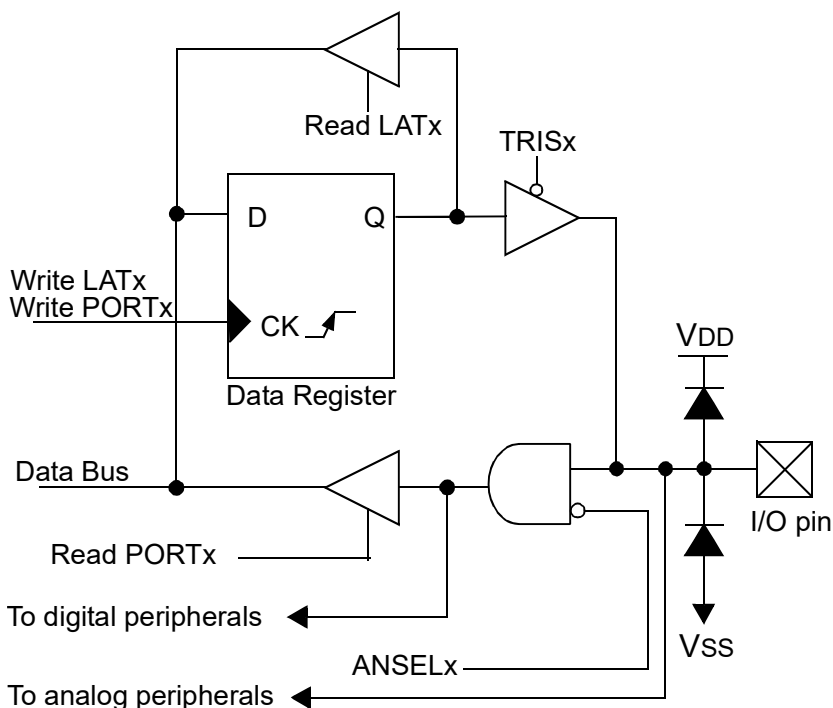
Most port pins share functions with device peripherals, both analog and digital. In general, when a peripheral is enabled on a port pin, that pin cannot be used as a general purpose output; however, the pin can still be read.

The Data Latch (LATx registers) is useful for read-modify-write operations on the value that the I/O pins are driving.

A write operation to the LATx register has the same effect as a write to the corresponding PORTx register. A read of the LATx register reads of the values held in the I/O PORT latches, while a read of the PORTx register reads the actual I/O pin value.

Ports that support analog inputs have an associated ANSELx register. When an ANSELx bit is set, the digital input buffer associated with that bit is disabled.

Disabling the input buffer prevents analog signal levels on the pin between a logic high and low from causing excessive current in the logic input circuitry. A simplified model of a generic I/O port, without the interfaces to other peripherals, is shown in the following figure:

Figure 16-1. Generic I/O Port Operation

16.1 I/O Priorities

Each pin defaults to the PORT data latch after Reset. Other functions are selected with the peripheral pin select logic. See the **“Peripheral Pin Select (PPS) Module”** section for more information.

Analog input functions, such as ADC and comparator inputs, are not shown in the peripheral pin select lists. These inputs are active when the I/O pin is set for Analog mode using the ANSELx register. Digital output functions may continue to control the pin when it is in Analog mode.

Analog outputs, when enabled, take priority over digital outputs and force the digital output driver into a High-Impedance state.

The pin function priorities are as follows:

1. Configuration bits
2. Analog outputs (disable the input buffers)
3. Analog inputs
4. Port inputs and outputs from PPS

Related Links

[PPS - Peripheral Pin Select Module](#)

16.2 PORTx Registers

In this section the generic names such as PORTx, LATx, TRISx, etc. can be associated with all ports. For availability of PORTD refer to [Table 16-1](#). The functionality of PORTE is different compared to other ports and is explained in a separate section.

16.2.1 Data Register

PORTx is an 8-bit wide, bidirectional port. The corresponding data direction register is TRISx. Setting a TRISx bit ('1') will make the corresponding PORTA pin an input (i.e., disable the output driver). Clearing a TRISx bit ('0') will make the corresponding PORTx pin an output (i.e., it enables output

driver and puts the contents of the output latch on the selected pin). [Example 16-1](#) shows how to initialize PORTA.

Reading the PORTx register reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch (LATx).

The PORT data latch LATx holds the output port data and contains the latest value of a LATx or PORTx write.

Example 16-1. EXAMPLE-1: Initializing PORTA

```
; This code example illustrates initializing the PORTA register.
; The other ports are initialized in the same manner.
    CLRF    LATA           ; Set all output bits to zero
    MOVLW   B'11111000'   ; Set RA<7:3> as inputs and RA<2:0> as outputs
    MOVWF   TRISA         ;
    BANKSEL ANSELA
    CLRF    ANSELA        ; All pins are digital I/O
```

16.2.2 Direction Control

The TRISx register controls the PORTx pin output drivers, even when they are being used as analog inputs. The user must ensure the bits in the TRISx register are maintained set when using them as analog inputs. I/O pins configured as analog inputs always read as '0'.

Related Links

[TRISA](#)

TRISA

[TRISB](#)

TRISB

[TRISC](#)

TRISC

[TRISD](#)

TRISD

[TRISE](#)

TRISE

16.2.3 Analog Control

The ANSELx register is used to configure the Input mode of an I/O pin to analog. Setting the appropriate ANSELx bit high will cause all digital reads on the pin to be read as '0' and allow analog functions on the pin to operate correctly.

The state of the ANSELx bits has no effect on digital output functions. A pin with TRIS clear and ANSEL set will still operate as a digital output, but the Input mode will be analog. This can cause unexpected behavior when executing READ-MODIFY-WRITE instructions on the affected port.



Important: The ANSELx bits default to the Analog mode after Reset. To use any pins as digital general purpose or peripheral inputs, the corresponding ANSEL bits must be initialized to '0' by user software.

Related Links[ANSELA](#)

ANSELA

[ANSELB](#)

ANSELB

[ANSELD](#)

ANSELD

[ANSELE](#)

ANSELE

16.2.4 Open-Drain Control

The ODCONx register controls the open-drain feature of the port. Open-drain operation is independently selected for each pin. When an ODCONx bit is set, the corresponding port output becomes an open-drain driver capable of sinking current only. When an ODCONx bit is cleared, the corresponding port output pin is the standard push-pull drive capable of sourcing and sinking current.



Important: It is not necessary to set open-drain control when using the pin for I²C; the I²C module controls the pin and makes the pin open-drain.

Related Links[ODCONA](#)

ODCONA

[ODCONB](#)

ODCONB

[ODCONC](#)

ODCONC

[ODCOND](#)

ODCOND

[ODCONE](#)

ODCONE

16.2.5 Slew Rate Control

The SLRCONx register controls the slew rate option for each PORT pin. Slew rate for each port pin can be controlled independently. When an SLRCONx bit is set, the corresponding PORT pin drive is slew rate limited. When an SLRCONx bit is cleared, The corresponding PORT pin drive slews at the maximum rate possible.

Related Links[SLRCONA](#)

SLRCONA

[SLRCONB](#)

SLRCONB

[SLRCONC](#)

SLRCONC

[SLRCOND](#)

SLRCOND

[SLRCONE](#)

SLRCONE

16.2.6 Input Threshold Control

The INLVLx register controls the input voltage threshold for each of the available PORTx input pins. A selection between the Schmitt Trigger CMOS or the TTL compatible thresholds is available. The input threshold is important in determining the value of a read of the PORTx register and also the level at which an interrupt-on-change occurs, if that feature is enabled.



Important: Changing the input threshold selection may be performed while all peripheral modules are disabled. Changing the threshold level during the time a module is active may inadvertently generate a transition associated with an input pin, regardless of the actual voltage level on that pin.

Related Links

[INLVLA](#)

INLVLA

[INVLVB](#)

INVLVB

[INLVLC](#)

INLVLC

[INLVLD](#)

INLVLD

[INLVLE](#)

INLVLE

16.2.7 Weak Pull-up Control

The WPUx register controls the individual weak pull-ups for each PORT pin.

Related Links

[WPUA](#)

WPUA

[WPUB](#)

WPUB

[WPUC](#)

WPUC

[WPUD](#)

WPUD

[WPUE](#)

WPUE

16.2.8 Edge Selectable Interrupt-on-Change

An interrupt can be generated by detecting a signal at the port pin that has either a rising edge or a falling edge. Individual pins can be independently configured to generate an interrupt. The Interrupt-on-Change module is present on all the pins that are common between 28-pin and 40/44-pin devices. For further details about the IOC module, refer to the “**Interrupt-on-Change**” chapter.

Related Links

[Interrupt-on-Change](#)

16.3 PORTE Registers

Depending on the device selected, PORTE is implemented in two different ways.

16.3.1 PORTE on 28-Pin Devices

For 28-pin devices, PORTE is only available when Master Clear functionality is disabled (MCLRE = 0). In this case, PORTE is a single bit, input-only port comprised of RE3 only. The pin operates as previously described. RE3 in PORTE register is a read-only bit and will read '1' when MCLRE = 1 (i.e., Master Clear enabled).

16.3.2 RE3 Weak Pull-Up

The port RE3 pin has an individually controlled weak internal pull-up. When set, the WPUE3 bit enables the RE3 pin pull-up. When the RE3 port pin is configured as $\overline{\text{MCLR}}$, (CONFIG2L, MCLRE = 1 and CONFIG4H, LVP = 0), or configured for Low-Voltage Programming, (MCLRE = x and LVP = 1), the pull-up is always enabled and the WPUE3 bit has no effect.

16.3.3 PORTE Interrupt-on-Change

The interrupt-on-change feature is available only on the RE3 pin for all devices.

Related Links

[Interrupt-on-Change](#)

16.4 Register Summary - Input/Output

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------|----------|---------|---------|---------|---------|---------|---------|---------|---------|
| 0x00 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F07 | Reserved | | | | | | | | | |
| 0x0F08 | | | | | | | | | | |
| 0x0F09 | INLVLA | 7:0 | INLVLA7 | INLVLA6 | INLVLA5 | INLVLA4 | INLVLA3 | INLVLA2 | INLVLA1 | INLVLA0 |
| 0x0F0A | SLRCONA | 7:0 | SLRA7 | SLRA6 | SLRA5 | SLRA4 | SLRA3 | SLRA2 | SLRA1 | SLRA0 |
| 0x0F0B | ODCONA | 7:0 | ODCA7 | ODCA6 | ODCA5 | ODCA4 | ODCA3 | ODCA2 | ODCA1 | ODCA0 |
| 0x0F0C | WPUA | 7:0 | WPUA7 | WPUA6 | WPUA5 | WPUA4 | WPUA3 | WPUA2 | WPUA1 | WPUA0 |
| 0x0F0D | ANSELA | 7:0 | ANSELA7 | ANSELA6 | ANSELA5 | ANSELA4 | ANSELA3 | ANSELA2 | ANSELA1 | ANSELA0 |
| 0x0F0E | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F0F | Reserved | | | | | | | | | |
| 0x0F10 | | | | | | | | | | |
| 0x0F11 | INVLVB | 7:0 | INVLVB7 | INVLVB6 | INVLVB5 | INVLVB4 | INVLVB3 | INVLVB2 | INVLVB1 | INVLVB0 |
| 0x0F12 | SLRB | 7:0 | SLRB7 | SLRB6 | SLRB5 | SLRB4 | SLRB3 | SLRB2 | SLRB1 | SLRB0 |
| 0x0F13 | ODCONB | 7:0 | ODCB7 | ODCB6 | ODCB5 | ODCB4 | ODCB3 | ODCB2 | ODCB1 | ODCB0 |
| 0x0F14 | WPUB | 7:0 | WPUB7 | WPUB6 | WPUB5 | WPUB4 | WPUB3 | WPUB2 | WPUB1 | WPUB0 |
| 0x0F15 | ANSELB | 7:0 | ANSELB7 | ANSELB6 | ANSELB5 | ANSELB4 | ANSELB3 | ANSELB2 | ANSELB1 | ANSELB0 |
| 0x0F16 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F17 | Reserved | | | | | | | | | |
| 0x0F18 | | | | | | | | | | |
| 0x0F19 | INLVLC | 7:0 | INLVLC7 | INLVLC6 | INLVLC5 | INLVLC4 | INLVLC3 | INLVLC2 | INLVLC1 | INLVLC0 |
| 0x0F1A | SLRCONC | 7:0 | SLRC7 | SLRC6 | SLRC5 | SLRC4 | SLRC3 | SLRC2 | SLRC1 | SLRC0 |
| 0x0F1B | ODCONC | 7:0 | ODCC7 | ODCC6 | ODCC5 | ODCC4 | ODCC3 | ODCC2 | ODCC1 | ODCC0 |
| 0x0F1C | WPUC | 7:0 | WPUC7 | WPUC6 | WPUC5 | WPUC4 | WPUC3 | WPUC2 | WPUC1 | WPUC0 |
| 0x0F1D | ANSELC | 7:0 | ANSELC7 | ANSELC6 | ANSELC5 | ANSELC4 | ANSELC3 | ANSELC2 | ANSELC1 | ANSELC0 |
| 0x0F1E | INLVLD | 7:0 | INLVLD7 | INLVLD6 | INLVLD5 | INLVLD4 | INLVLD3 | INLVLD2 | INLVLD1 | INLVLD0 |
| 0x0F1F | SLRCOND | 7:0 | SLRD7 | SLRD6 | SLRD5 | SLRD4 | SLRD3 | SLRD2 | SLRD1 | SLRD0 |
| 0x0F20 | ODCOND | 7:0 | ODCD7 | ODCD6 | ODCD5 | ODCD4 | ODCD3 | ODCD2 | ODCD1 | ODCD0 |
| 0x0F21 | WPUD | 7:0 | WPUD7 | WPUD6 | WPUD5 | WPUD4 | WPUD3 | WPUD2 | WPUD1 | WPUD0 |
| 0x0F22 | ANSELD | 7:0 | ANSELD7 | ANSELD6 | ANSELD5 | ANSELD4 | ANSELD3 | ANSELD2 | ANSELD1 | ANSELD0 |
| 0x0F23 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F24 | Reserved | | | | | | | | | |
| 0x0F25 | | | | | | | | | | |
| 0x0F26 | INLVLE | 7:0 | | | | | INLVLE3 | | | |
| 0x0F27 | SLRCONC | 7:0 | | | | | | SLRE2 | SLRE1 | SLRE0 |
| 0x0F28 | ODCONC | 7:0 | | | | | | ODCE2 | ODCE1 | ODCE0 |
| 0x0F29 | WPUE | 7:0 | | | | | WPUE3 | | | |
| 0x0F2A | ANSELE | 7:0 | | | | | | ANSELE2 | ANSELE1 | ANSELE0 |
| 0x0F2B | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F81 | Reserved | | | | | | | | | |
| 0x0F82 | | | | | | | | | | |
| 0x0F83 | LATA | 7:0 | LATA7 | LATA6 | LATA5 | LATA4 | LATA3 | LATA2 | LATA1 | LATA0 |
| 0x0F84 | LATB | 7:0 | LATB7 | LATB6 | LATB5 | LATB4 | LATB3 | LATB2 | LATB1 | LATB0 |
| 0x0F85 | LATC | 7:0 | LATC7 | LATC6 | LATC5 | LATC4 | LATC3 | LATC2 | LATC1 | LATC0 |
| 0x0F86 | LATD | 7:0 | LATD7 | LATD6 | LATD5 | LATD4 | LATD3 | LATD2 | LATD1 | LATD0 |
| 0x0F87 | LATE | 7:0 | | | | | | LATE2 | LATE1 | LATE0 |
| 0x0F88 | TRISA | 7:0 | TRISA7 | TRISA6 | TRISA5 | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 |
| 0x0F89 | TRISB | 7:0 | TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 |
| 0x0F8A | TRISC | 7:0 | TRISC7 | TRISC6 | TRISC5 | TRISC4 | TRISC3 | TRISC2 | TRISC1 | TRISC0 |
| 0x0F8B | TRISD | 7:0 | TRISD7 | TRISD6 | TRISD5 | TRISD4 | TRISD3 | TRISD2 | TRISD1 | TRISD0 |
| 0x0F8C | TRISE | 7:0 | | | | | TRISE3 | TRISE2 | TRISE1 | TRISE0 |
| 0x0F8D | PORTA | 7:0 | RA7 | RA6 | RA5 | RA4 | RA3 | RA2 | RA1 | RA0 |
| 0x0F8E | PORTB | 7:0 | RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 |
| 0x0F8F | PORTC | 7:0 | RC7 | RC6 | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 |
| 0x0F90 | PORTD | 7:0 | RD7 | RD6 | RD5 | RD4 | RD3 | RD2 | RD1 | RD0 |
| 0x0F91 | PORTE | 7:0 | | | | | RE3 | RE2 | RE1 | RE0 |

16.5 Register Definitions: Port Control

16.5.1 PORTA

Name: PORTA

Address: 0xF8C

PORTA Register

Note: Writes to PORTA are actually written to the corresponding LATA register.

Reads from PORTA register return actual I/O pin values.

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|-----|-----|-----|-----|-----|-----|
| | RA7 | RA6 | RA5 | RA4 | RA3 | RA2 | RA1 | RA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – RAn Port I/O Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

| Value | Description |
|-------|---------------------------|
| 1 | PORT pin is $\geq V_{IH}$ |
| 0 | PORT pin is $\leq V_{IL}$ |

16.5.2 PORTB

Name: PORTB

Address: 0xF8D

PORTB Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|-----|-----|-----|-----|-----|-----|
| | RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – RBn Port I/O Value bits

Note: Bits RB6 and RB7 read '1' while in Debug mode.

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

| Value | Description |
|-------|---------------------------|
| 1 | PORT pin is $\geq V_{IH}$ |
| 0 | PORT pin is $\leq V_{IL}$ |

Note: Writes to PORTB are actually written to the corresponding LATB register.
Reads from PORTB register return actual I/O pin values.

16.5.3 PORTC

Name: PORTC

Address: 0xF8E

PORTC Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|-----|-----|-----|-----|-----|-----|
| | RC7 | RC6 | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – RCn Port I/O Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

| Value | Description |
|-------|---------------------------|
| 1 | PORT pin is $\geq V_{IH}$ |
| 0 | PORT pin is $\leq V_{IL}$ |

Note: Writes to PORTC are actually written to the corresponding LATC register.
Reads from PORTC register return actual I/O pin values.

16.5.4 PORTD

Name: PORTD

Address: 0xF8F

PORTD Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|-----|-----|-----|-----|-----|-----|
| | RD7 | RD6 | RD5 | RD4 | RD3 | RD2 | RD1 | RD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – RDn Port I/O Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

| Value | Description |
|-------|---------------------------|
| 1 | Port pin is $\geq V_{IH}$ |
| 0 | Port pin is $\leq V_{IL}$ |

Note: Writes to PORTD are actually written to the corresponding LATD register.

Reads from PORTD register return actual I/O pin values.

16.5.5 PORTE

Name: PORTE

Address: 0xF90

PORTE Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|-----|-----|-----|-----|
| | | | | | RE3 | RE2 | RE1 | RE0 |
| Access | | | | | R | R/W | R/W | R/W |
| Reset | | | | | x | | | |

Bit 3 – RE3 PORTE I/O Value bits

Reset States: POR/BOR = x

All Other Resets = u

| Value | Description |
|-------|---------------------------|
| 1 | PORT pin is $\geq V_{IH}$ |
| 0 | PORT pin is $\leq V_{IL}$ |

Bit 3 – RE3 PORTE I/O Value bits

Bit 2 – RE2 PORTE I/O Value bit

Bit 1 – RE1 PORTE I/O Value bit

Bit 0 – RE0 PORTE I/O Value bit

Bits 3:0 – RE_n[3:0] PORTE I/O Value bits

Reset States: POR/BOR = xxxx

All Other Resets = uuuu

| Value | Description |
|-------|---------------------------|
| 1 | PORT pin is $\geq V_{IH}$ |
| 0 | PORT pin is $\leq V_{IL}$ |

Notes:

- Writes to PORTE are actually written to the corresponding LATE register. Reads from PORTE register return actual I/O pin values.
- Bit RE3 is read-only and will read '1' when MCLRE = 1 (master clear enabled) and '0' when $\overline{\text{DEBUG}}$ is enabled.

16.5.6 TRISA

Name: TRISA

Address: 0xF87

Tri-State Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | TRISA7 | TRISA6 | TRISA5 | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – TRISAn TRISA Port I/O Tri-state Control bits

| Value | Description |
|-------|--------------------------------|
| 1 | Port output driver is disabled |
| 0 | Port output driver is enabled |

16.5.7 TRISB

Name: TRISB

Address: 0xF88

Tri-State Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – TRISBn TRISB Port I/O Tri-state Control bits

Note: Bits TRISB6 and TRISB7 read '1' while in Debug mode.

| Value | Description |
|-------|--------------------------------|
| 1 | Port output driver is disabled |
| 0 | Port output driver is enabled |

16.5.8 TRISC

Name: TRISC

Address: 0xF89

Tri-State Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | TRISC7 | TRISC6 | TRISC5 | TRISC4 | TRISC3 | TRISC2 | TRISC1 | TRISC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – TRISCn TRISC Port I/O Tri-state Control bits

| Value | Description |
|-------|--------------------------------|
| 1 | Port output driver is disabled |
| 0 | Port output driver is enabled |

16.5.9 TRISD

Name: TRISD
Address: 0xF8A

Tri-State Control Register

| | | | | | | | | |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TRISD7 | TRISD6 | TRISD5 | TRISD4 | TRISD3 | TRISD2 | TRISD1 | TRISD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – TRISDn TRISD Port I/O Tri-state Control bits

| Value | Description |
|-------|--------------------------------|
| 1 | Port output driver is disabled |
| 0 | Port output driver is enabled |

16.5.10 TRISE

Name: TRISE

Address: 0xF8B

Tri-State Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|--------|--------|--------|--------|
| | | | | | TRISE3 | TRISE2 | TRISE1 | TRISE0 |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3 – TRISEn PortE I/O Tri-state Control bits

Notes:

1. Not available on 28-pin devices.
2. TRISE3 bit is read-only, and will read '1'.

| Value | Description |
|-------|--------------------------------|
| 1 | Port output driver is disabled |
| 0 | Port output driver is enabled |

16.5.11 LATA

Name: LATA

Address: 0xF82

Output Latch Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | LATA7 | LATA6 | LATA5 | LATA4 | LATA3 | LATA2 | LATA1 | LATA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – LATAn Output Latch A Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

Note: Writes to LATA are equivalent with writes to the corresponding PORTA register. Reads from LATA register return register values, not I/O pin values.

16.5.12 LATB

Name: LATB

Address: 0xF83

Output Latch Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | LATB7 | LATB6 | LATB5 | LATB4 | LATB3 | LATB2 | LATB1 | LATB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – LATBn Output Latch B Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuuu

Note: Writes to LATB are equivalent with writes to the corresponding PORTB register. Reads from LATB register return register values, not I/O pin values.

16.5.13 LATC

Name: LATC
Address: 0xF84

Output Latch Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | LATC7 | LATC6 | LATC5 | LATC4 | LATC3 | LATC2 | LATC1 | LATC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – LATCn Output Latch C Value bits

Reset States: POR/BOR = xxxxxxxx
All Other Resets = uuuuuuuuu

Note: Writes to LATC are equivalent with writes to the corresponding PORTC register. Reads from LATC register return register values, not I/O pin values.

16.5.14 LATD**Name:** LATD**Address:** 0xF85

Output Latch Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | LATD7 | LATD6 | LATD5 | LATD4 | LATD3 | LATD2 | LATD1 | LATD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – LATDn Output Latch D Value bits

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuuu

Note: Writes to LATD are equivalent with writes to the corresponding PORTD register. Reads from LATD register return register values, not I/O pin values.

16.5.15 LATE

Name: LATE
Address: 0xF86

Output Latch Register

| | | | | | | | | |
|--------|---|---|---|---|---|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | LATE2 | LATE1 | LATE0 |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | x | x | x |

Bits 0, 1, 2 – LATEn Output Latch E Value bits

Reset States: POR/BOR = xxx
All Other Resets = uuu

Note: Writes to LATE are equivalent with writes to the corresponding PORTE register. Reads from LATE register return register values, not I/O pin values.

16.5.16 ANSELA

Name: ANSELA
Address: 0xF0C

Analog Select Register

| | | | | | | | | |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ANSELA7 | ANSELA6 | ANSELA5 | ANSELA4 | ANSELA3 | ANSELA2 | ANSELA1 | ANSELA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ANSELAn Analog Select on Pins RA[7:0]

| Value | Description |
|-------|--------------------------------------|
| 1 | Digital Input buffers are disabled |
| 0 | ST and TTL input buffers are enabled |

16.5.17 ANSELB**Name:** ANSELB**Address:** 0xF14**Reset:** 0x00

Analog Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | ANSELB7 | ANSELB6 | ANSELB5 | ANSELB4 | ANSELB3 | ANSELB2 | ANSELB1 | ANSELB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ANSELBn Analog Select on Pins RB[7:0]

| Value | Description |
|-------|--------------------------------------|
| 1 | Digital Input buffers are disabled |
| 0 | ST and TTL input buffers are enabled |

16.5.18 ANSELC

Name: ANSELC
Address: 0xF1C

Analog Select Register

| | | | | | | | | |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ANSELC7 | ANSELC6 | ANSELC5 | ANSELC4 | ANSELC3 | ANSELC2 | ANSELC1 | ANSELC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ANSELCn Analog Select on Pins RC[7:0]

| Value | Description |
|-------|--------------------------------------|
| 1 | Digital Input buffers are disabled |
| 0 | ST and TTL input buffers are enabled |

16.5.19 ANSELD

Name: ANSELD
Address: 0xF21

Analog Select Register

| | | | | | | | | |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ANSELD7 | ANSELD6 | ANSELD5 | ANSELD4 | ANSELD3 | ANSELD2 | ANSELD1 | ANSELD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ANSELDn Analog Select on Pins RD<7:0>

| Value | Description |
|-------|--------------------------------------|
| 1 | Digital Input buffers are disabled |
| 0 | ST and TTL input buffers are enabled |

16.5.20 ANSELE

Name: ANSELE
Address: 0xF29

Analog Select Register

| | | | | | | | | |
|--------|---|---|---|---|---|---------|---------|---------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | ANSELE2 | ANSELE1 | ANSELE0 |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | 1 | 1 | 1 |

Bits 0, 1, 2 – ANSELEn Analog Select on Pins RE[7:0]

| Value | Description |
|-------|--------------------------------------|
| 1 | Digital Input buffers are disabled |
| 0 | ST and TTL input buffers are enabled |

16.5.21 WPUA

Name: WPUA
Address: 0xF0B

Weak Pull-up Register

| | | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | WPUA7 | WPUA6 | WPUA5 | WPUA4 | WPUA3 | WPUA2 | WPUA1 | WPUA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – WPUAn Weak Pull-up PORTA Control bits

| Value | Description |
|-------|-----------------------|
| 1 | Weak Pull-up enabled |
| 0 | Weak Pull-up disabled |

16.5.22 WPUB

Name: WPUB
Address: 0xF13

Weak Pull-up Register

| | | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | WPUB7 | WPUB6 | WPUB5 | WPUB4 | WPUB3 | WPUB2 | WPUB1 | WPUB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – WPUBn Weak Pull-up PORTA Control bits

| Value | Description |
|-------|-----------------------|
| 1 | Weak Pull-up enabled |
| 0 | Weak Pull-up disabled |

16.5.23 WPUC

Name: WPUC
Address: 0xF1B

Weak Pull-up Register

| | | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | WPUC7 | WPUC6 | WPUC5 | WPUC4 | WPUC3 | WPUC2 | WPUC1 | WPUC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – WPUCn Weak Pull-up PORTC Control bits

| Value | Description |
|-------|-----------------------|
| 1 | Weak Pull-up enabled |
| 0 | Weak Pull-up disabled |

16.5.24 WPUD

Name: WPUD
Address: 0xF20

Weak Pull-up Register

| | | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | WPUD7 | WPUD6 | WPUD5 | WPUD4 | WPUD3 | WPUD2 | WPUD1 | WPUD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

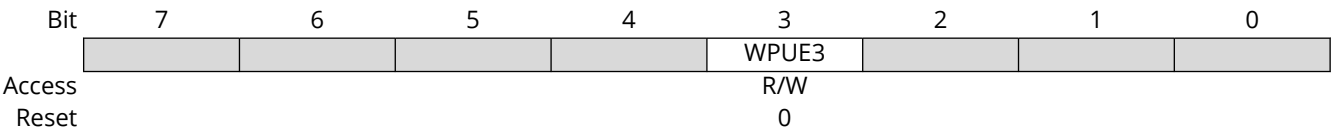
Bits 0, 1, 2, 3, 4, 5, 6, 7 – WPUDn Weak Pull-up PORTD Control bits

| Value | Description |
|-------|-----------------------|
| 1 | Weak Pull-up enabled |
| 0 | Weak Pull-up disabled |

16.5.25 WPUE

Name: WPUE
Address: 0xF28

Weak Pull-up Register



Bit 3 – WPUE3 Weak Pull-up PORTE Control bits
Note: If MCLRE = 1, the weak pull-up in RE3 is always enabled; bit WPUE3 is not affected.

| Value | Description |
|-------|-----------------------|
| 1 | Weak Pull-up enabled |
| 0 | Weak Pull-up disabled |

16.5.26 ODCONA

Name: ODCONA
Address: 0xF0A

Open-Drain Control Register

| | | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ODCA7 | ODCA6 | ODCA5 | ODCA4 | ODCA3 | ODCA2 | ODCA1 | ODCA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ODCAn Open-Drain Configuration on Pins Rx[7:0]

| Value | Description |
|-------|---|
| 1 | Output drives only low-going signals (sink current only) |
| 0 | Output drives both high-going and low-going signals (source and sink current) |

16.5.27 ODCONB**Name:** ODCONB**Address:** 0xF12

Open-Drain Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | ODCB7 | ODCB6 | ODCB5 | ODCB4 | ODCB3 | ODCB2 | ODCB1 | ODCB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ODCBn Open-Drain Configuration on Pins Rx[7:0]

| Value | Description |
|-------|---|
| 1 | Output drives only low-going signals (sink current only) |
| 0 | Output drives both high-going and low-going signals (source and sink current) |

16.5.28 ODCONC**Name:** ODCONC**Address:** 0xF1A

Open-Drain Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | ODCC7 | ODCC6 | ODCC5 | ODCC4 | ODCC3 | ODCC2 | ODCC1 | ODCC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ODCCn Open-Drain Configuration on Pins Rx[7:0]

| Value | Description |
|-------|---|
| 1 | Output drives only low-going signals (sink current only) |
| 0 | Output drives both high-going and low-going signals (source and sink current) |

16.5.29 ODCOND**Name:** ODCOND**Address:** 0xF1F

Open-Drain Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | ODCD7 | ODCD6 | ODCD5 | ODCD4 | ODCD3 | ODCD2 | ODCD1 | ODCD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ODCDn Open-Drain Configuration on Pins Rx[7:0]

| Value | Description |
|-------|---|
| 1 | Output drives only low-going signals (sink current only) |
| 0 | Output drives both high-going and low-going signals (source and sink current) |

16.5.30 ODCONE

Name: ODCONE
Address: 0xF27

Open-Drain Control Register

| | | | | | | | | |
|--------|---|---|---|---|---|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | ODCE2 | ODCE1 | ODCE0 |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | 0 | 0 | 0 |

Bits 0, 1, 2 – ODCEn Open-Drain Configuration on Pins Rx[7:0]

| Value | Description |
|-------|---|
| 1 | Output drives only low-going signals (sink current only) |
| 0 | Output drives both high-going and low-going signals (source and sink current) |

16.5.31 SLRCONA**Name:** SLRCONA**Address:** 0xF09

Slew Rate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | SLRA7 | SLRA6 | SLRA5 | SLRA4 | SLRA3 | SLRA2 | SLRA1 | SLRA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – SLRAn Slew Rate Control on Pins Rx[7:0], respectively

| Value | Description |
|-------|--------------------------------|
| 1 | PORT pin slew rate is limited |
| 0 | PORT pin slews at maximum rate |

16.5.32 SLRCONB**Name:** SLRCONB**Address:** 0xF11

Slew Rate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | SLRB7 | SLRB6 | SLRB5 | SLRB4 | SLRB3 | SLRB2 | SLRB1 | SLRB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – SLRBn Slew Rate Control on Pins Rx[7:0], respectively

| Value | Description |
|-------|--------------------------------|
| 1 | PORT pin slew rate is limited |
| 0 | PORT pin slews at maximum rate |

16.5.33 SLRCONC**Name:** SLRCONC**Address:** 0xF19

Slew Rate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | SLRC7 | SLRC6 | SLRC5 | SLRC4 | SLRC3 | SLRC2 | SLRC1 | SLRC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – SLRCn Slew Rate Control on Pins Rx[7:0], respectively

| Value | Description |
|-------|--------------------------------|
| 1 | PORT pin slew rate is limited |
| 0 | PORT pin slews at maximum rate |

16.5.34 SLRCOND**Name:** SLRCOND**Address:** 0xF1E

Slew Rate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | SLRD7 | SLRD6 | SLRD5 | SLRD4 | SLRD3 | SLRD2 | SLRD1 | SLRD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – SLRDn Slew Rate Control on Pins Rx[7:0], respectively

| Value | Description |
|-------|--------------------------------|
| 1 | Port pin slew rate is limited |
| 0 | Port pin slews at maximum rate |

16.5.35 SLRCONE

Name: SLRCONE
Address: 0xF26

Slew Rate Control Register

| | | | | | | | | |
|--------|---|---|---|---|---|-------|-------|-------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | SLRE2 | SLRE1 | SLRE0 |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | 1 | 1 | 1 |

Bits 0, 1, 2 – SLREn Slew Rate Control on Pins Rx[7:0], respectively

| Value | Description |
|-------|--------------------------------|
| 1 | Port pin slew rate is limited |
| 0 | Port pin slews at maximum rate |

16.5.36 INLVLA**Name:** INLVLA**Address:** 0xF08

Input Level Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | INLVLA7 | INLVLA6 | INLVLA5 | INLVLA4 | INLVLA3 | INLVLA2 | INLVLA1 | INLVLA0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – INLVLA_n Input Level Select on Pins Rx[7:0], respectively

| Value | Description |
|-------|---|
| 1 | ST input used for port reads and interrupt-on-change |
| 0 | TTL input used for port reads and interrupt-on-change |

16.5.37 INLVLB**Name:** INLVLB**Address:** 0xF10

Input Level Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | INLVLB7 | INLVLB6 | INLVLB5 | INLVLB4 | INLVLB3 | INLVLB2 | INLVLB1 | INLVLB0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – INLVLBn Input Level Select on Pins Rx[7:0], respectively**Note:** INLVLB2 / INLVLB1: Pins read the I²C ST inputs when MSSP inputs select these pins, and I²C mode is enabled.

| Value | Description |
|-------|---|
| 1 | ST input used for port reads and interrupt-on-change |
| 0 | TTL input used for port reads and interrupt-on-change |

16.5.38 INLVLC**Name:** INLVLC**Address:** 0xF18

Input Level Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | INLVLC7 | INLVLC6 | INLVLC5 | INLVLC4 | INLVLC3 | INLVLC2 | INLVLC1 | INLVLC0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – INLVLCn Input Level Select on Pins Rx[7:0], respectively**Note:** INLVLC4 / INLVLC3: Pins read the I²C ST inputs when MSSP inputs select these pins, and I²C mode is enabled.

| Value | Description |
|-------|---|
| 1 | ST input used for port reads and interrupt-on-change |
| 0 | TTL input used for port reads and interrupt-on-change |

16.5.39 INLVLD**Name:** INLVLD**Address:** 0xF1D

Input Level Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | INLVLD7 | INLVLD6 | INLVLD5 | INLVLD4 | INLVLD3 | INLVLD2 | INLVLD1 | INLVLD0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

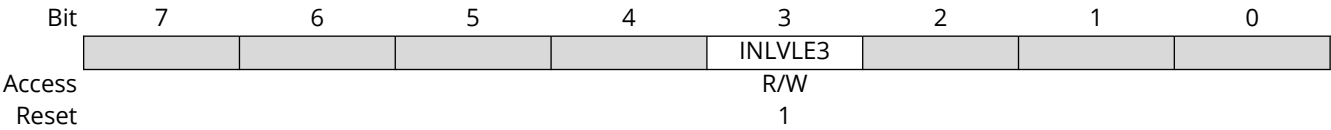
Bits 0, 1, 2, 3, 4, 5, 6, 7 – INLVLDn Input Level Select on Pins Rx[7:0], respectively

| Value | Description |
|-------|---|
| 1 | ST input used for port reads and interrupt-on-change |
| 0 | TTL input used for port reads and interrupt-on-change |

16.5.40 INLVLE

Name: INLVLE
Address: 0xF25

Input Level Control Register



Bit 3 – INLVLE3 Input Level Select on Pins Rx<7:0>, respectively

| Value | Description |
|-------|---|
| 1 | ST input used for port reads and interrupt-on-change |
| 0 | TTL input used for port reads and interrupt-on-change |

17. Interrupt-on-Change

17.1 Features

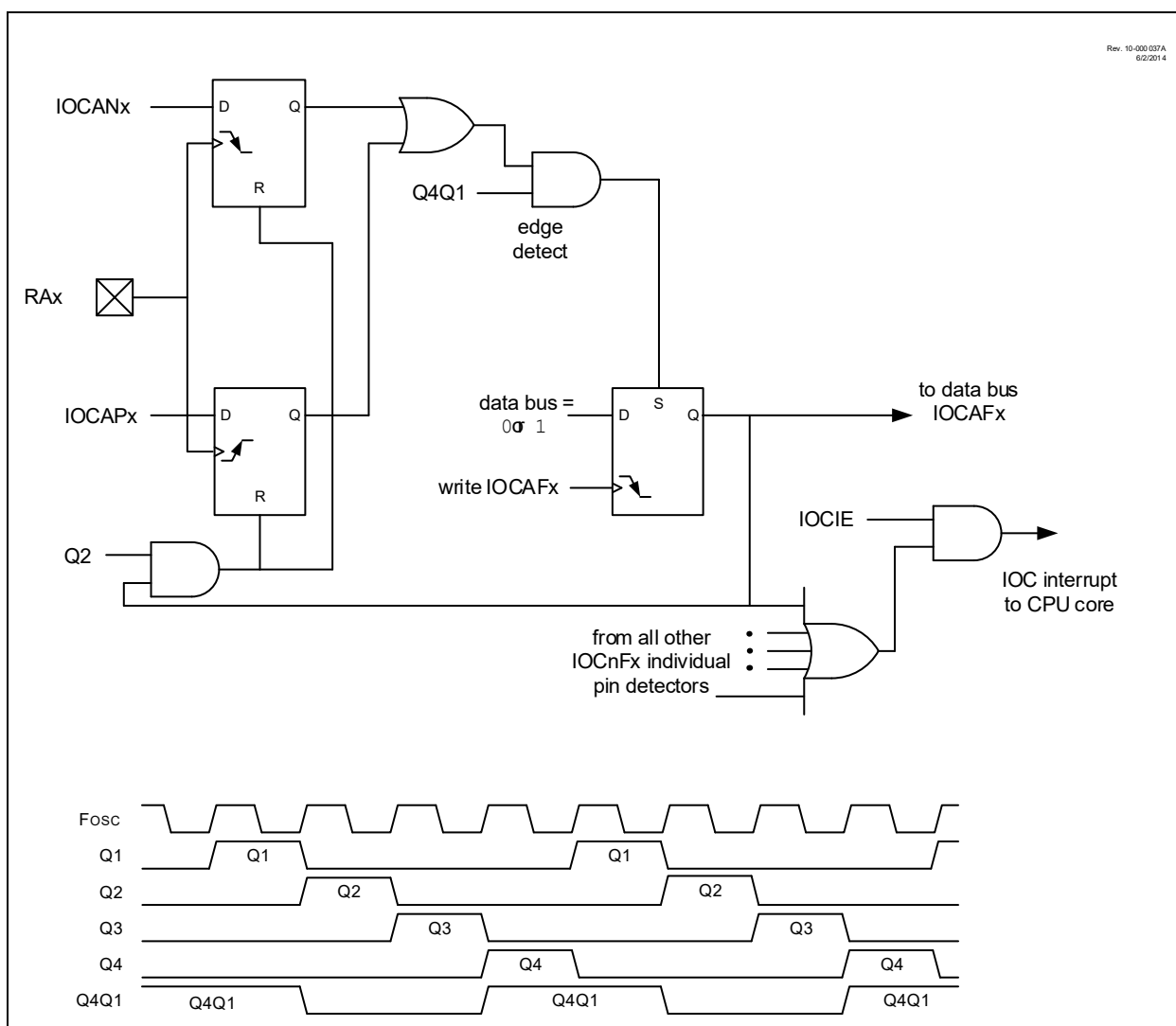
- Interrupt-on-Change Enable
- Individual Pin Configuration
- Rising and Falling Edge Detection
- Individual Pin Interrupt Flags

17.2 Overview

All the pins of PORTA, PORTB, PORTC, and pin RE3 of PORTE can be configured to operate as Interrupt-on-Change (IOC) pins on PIC18F26/45/46Q10 family devices. An interrupt can be generated by detecting a signal that has either a rising edge or a falling edge. Any individual port pin, or combination of port pins, can be configured to generate an interrupt.

17.3 Block Diagram

Figure 17-1. Interrupt-on-Change Block Diagram (PORTA Example)



17.4 Enabling the Module

To allow individual port pins to generate an interrupt, the IOCIE bit of the PIE0 register must be set. If the IOCIE bit is disabled, the edge detection on the pin will still occur, but an interrupt will not be generated.

Related Links

[PIE0](#)

PIE0

17.5 Individual Pin Configuration

For each PORT pin, a rising edge detector and a falling edge detector are present. To enable a pin to detect a rising edge, the associated bit of the IOCxP register is set. To enable a pin to detect a falling edge, the associated bit of the IOCxN register is set.

A pin can be configured to detect rising and falling edges simultaneously by setting both associated bits of the IOCxP and IOCxN registers, respectively.

17.6 Interrupt Flags

The IOCAFx, IOCBFx, IOCCFx and IOCEF3 bits located in the IOCAF, IOCBF, IOCCF and IOCEF registers respectively, are status flags that correspond to the interrupt-on-change pins of the associated port. If an expected edge is detected on an appropriately enabled pin, then the status flag for that pin will be set, and an interrupt will be generated if the IOCIE bit is set. The IOCIF bit of the PIR0 register reflects the status of all IOCAFx, IOCBFx, IOCCFx and IOCEF3 bits.

Related Links

[PIR0](#)

PIR0

17.7 Clearing Interrupt Flags

The individual status flag bits (IOCAFx, IOCBFx, IOCCFx and IOCEF3) can be cleared by resetting them to zero. If another edge is detected during this clearing operation, the associated status flag will be set at the end of the sequence, regardless of the value actually being written.

To ensure that no detected edge is lost while clearing flags, only AND operations masking out known changed bits must be performed. The following sequence is an example of what must be performed.

Example 17-1. Clearing Interrupt Flags (PORTA Example)

```
MOVLW    0xff
XORWF    IOCAF, W
ANDWF    IOCAF, F
```

17.8 Operation in Sleep

The interrupt-on-change interrupt sequence will wake the device from Sleep mode, if the IOCIE bit is set.

If an edge is detected while in Sleep mode, the IOCxF register will be updated prior to the first instruction executed out of Sleep.

17.9 Register Summary - Interrupt-on-Change

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|--------|--------|--------|--------|--------|--------|--------|--------|
| 0x00 ... 0x0F04 | Reserved | | | | | | | | | |
| 0x0F05 | IOCAF | 7:0 | IOCAF7 | IOCAF6 | IOCAF5 | IOCAF4 | IOCAF3 | IOCAF2 | IOCAF1 | IOCAF0 |
| 0x0F06 | IOCAN | 7:0 | IOCAN7 | IOCAN6 | IOCAN5 | IOCAN4 | IOCAN3 | IOCAN2 | IOCAN1 | IOCAN0 |
| 0x0F07 | IOCAP | 7:0 | IOCAP7 | IOCAP6 | IOCAP5 | IOCAP4 | IOCAP3 | IOCAP2 | IOCAP1 | IOCAP0 |
| 0x0F08 ... 0x0F0C | Reserved | | | | | | | | | |
| 0x0F0D | IOCBF | 7:0 | IOCBF7 | IOCBF6 | IOCBF5 | IOCBF4 | IOCBF3 | IOCBF2 | IOCBF1 | IOCBF0 |
| 0x0F0E | IOCBN | 7:0 | IOCBN7 | IOCBN6 | IOCBN5 | IOCBN4 | IOCBN3 | IOCBN2 | IOCBN1 | IOCBN0 |
| 0x0F0F | IOCBP | 7:0 | IOCBP7 | IOCBP6 | IOCBP5 | IOCBP4 | IOCBP3 | IOCBP2 | IOCBP1 | IOCBP0 |
| 0x0F10 ... 0x0F14 | Reserved | | | | | | | | | |
| 0x0F15 | IOCCF | 7:0 | IOCCF7 | IOCCF6 | IOCCF5 | IOCCF4 | IOCCF3 | IOCCF2 | IOCCF1 | IOCCF0 |
| 0x0F16 | IOCCN | 7:0 | IOCCN7 | IOCCN6 | IOCCN5 | IOCCN4 | IOCCN3 | IOCCN2 | IOCCN1 | IOCCN0 |
| 0x0F17 | IOCCP | 7:0 | IOCCP7 | IOCCP6 | IOCCP5 | IOCCP4 | IOCCP3 | IOCCP2 | IOCCP1 | IOCCP0 |
| 0x0F18 ... 0x0F21 | Reserved | | | | | | | | | |
| 0x0F22 | IOCEF | 7:0 | | | | | IOCEF3 | | | |
| 0x0F23 | IOCEN | 7:0 | | | | | IOCEN3 | | | |
| 0x0F24 | IOCEP | 7:0 | | | | | IOCEP3 | | | |

17.10 Register Definitions: Interrupt-on-Change Control

17.10.1 IOCAF

Name: IOCAF

Address: 0xF05

PORTA Interrupt-on-Change Flag Register Example

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCAF7 | IOCAF6 | IOCAF5 | IOCAF4 | IOCAF3 | IOCAF2 | IOCAF1 | IOCAF0 |
| Access | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCAFn Interrupt-on-Change Flag bits

| Value | Condition | Description |
|-------|-------------------------------|---|
| 1 | IOCAP[n] = 1 | A positive edge was detected on the RA[n] pin |
| 1 | IOCAN[n] = 1 | A negative edge was detected on the RA[n] pin |
| 0 | IOCAP[n] = x and IOCAN[n] = x | No change was detected, or the user cleared the detected change |

17.10.2 IOCBF

Name: IOCBF

Address: 0xF0D

PORTB Interrupt-on-Change Flag Register Example

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCBF7 | IOCBF6 | IOCBF5 | IOCBF4 | IOCBF3 | IOCBF2 | IOCBF1 | IOCBF0 |
| Access | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCBFn Interrupt-on-Change Flag bits

| Value | Condition | Description |
|-------|-------------------------------|---|
| 1 | IOCBP[n] = 1 | A positive edge was detected on the RB[n] pin |
| 1 | IOCBN[n] = 1 | A negative edge was detected on the RB[n] pin |
| 0 | IOCBP[n] = x and IOCBN[n] = x | No change was detected, or the user cleared the detected change |

17.10.3 IOCCF

Name: IOCCF

Address: 0xF15

PORTC Interrupt-on-Change Flag Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCCF7 | IOCCF6 | IOCCF5 | IOCCF4 | IOCCF3 | IOCCF2 | IOCCF1 | IOCCF0 |
| Access | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS | R/W/HS |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

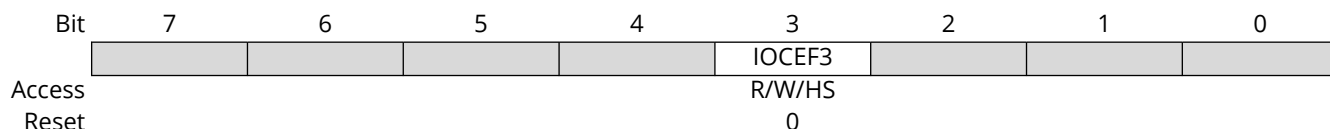
Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCCFn Interrupt-on-Change Flag bits

| Value | Condition | Description |
|-------|-------------------------------|---|
| 1 | IOCCP[n] = 1 | A positive edge was detected on the RC[n] pin |
| 1 | IOCCN[n] = 1 | A negative edge was detected on the RC[n] pin |
| 0 | IOCCP[n] = x and IOCCN[n] = x | No change was detected, or the user cleared the detected change |

17.10.4 IOCEF

Name: IOCEF
Address: 0xF22

PORTE Interrupt-on-Change Flag Register



Bit 3 – IOCEF3 PORTE Interrupt-on-Change Flag bits⁽¹⁾

| Value | Condition | Description |
|-------|-------------------------------|---|
| 1 | IOCEP[n] = 1 | A positive edge was detected on the RE[n] pin |
| 1 | IOCEN[n] = 1 | A negative edge was detected on the RE[n] pin |
| 0 | IOCEP[n] = x and IOCEN[n] = x | No change was detected, or the user cleared the detected change |

Note:

1. If MCLRE = 1 or LVP = 1, RE3 port functionality is disabled and IOC on RE3 is not available.

17.10.5 IOCAN

Name: IOCAN
Address: 0xF06

Interrupt-on-Change Negative Edge Register Example

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCAN7 | IOCAN6 | IOCAN5 | IOCAN4 | IOCAN3 | IOCAN2 | IOCAN1 | IOCAN0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCANn Interrupt-on-Change Negative Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCA pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.6 IOCBN

Name: IOCBN
Address: 0xF0E

Interrupt-on-Change Negative Edge Register Example

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCBN7 | IOCBN6 | IOCBN5 | IOCBN4 | IOCBN3 | IOCBN2 | IOCBN1 | IOCBN0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCBNn Interrupt-on-Change Negative Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCA pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.7 IOCCN

Name: IOCCN
Address: 0xF16

Interrupt-on-Change Negative Edge Register Example

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCCN7 | IOCCN6 | IOCCN5 | IOCCN4 | IOCCN3 | IOCCN2 | IOCCN1 | IOCCN0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCCNn Interrupt-on-Change Negative Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCA pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.8 IOCEN

Name: IOCEN
Address: 0xF23

Interrupt-on-Change Negative Edge Register Example

| | | | | | | | | |
|--------|---|---|---|---|--------|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | IOCEN3 | | | |
| Access | | | | | R/W | | | |
| Reset | | | | | 0 | | | |

Bit 3 – IOCEN3 Interrupt-on-Change Negative Edge Enable bits⁽¹⁾

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCA pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

Note:

1. If MCLRE = 1 or LVP = 1, RE3 port functionality is disabled and IOC on RE3 is not available.

17.10.9 IOCAP

Name: IOCAP
Address: 0xF07

Interrupt-on-Change Positive Edge Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCAP7 | IOCAP6 | IOCAP5 | IOCAP4 | IOCAP3 | IOCAP2 | IOCAP1 | IOCAP0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCAPn Interrupt-on-Change Positive Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCA pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.10 IOCBP

Name: IOCBP
Address: 0xF0F

Interrupt-on-Change Positive Edge Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | IOCBP7 | IOCBP6 | IOCBP5 | IOCBP4 | IOCBP3 | IOCBP2 | IOCBP1 | IOCBP0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCBPn Interrupt-on-Change Positive Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCB pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.11 IOCCP

Name: IOCCP
Address: 0xF17

Interrupt-on-Change Positive Edge Register

| | | | | | | | | |
|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | IOCCP7 | IOCCP6 | IOCCP5 | IOCCP4 | IOCCP3 | IOCCP2 | IOCCP1 | IOCCP0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

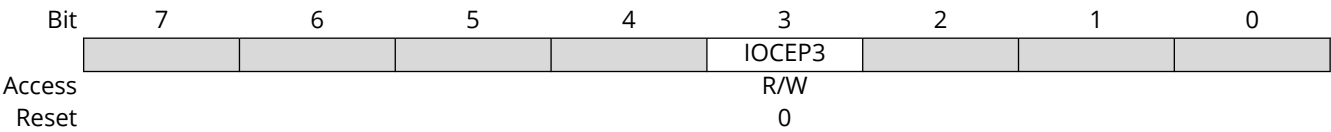
Bits 0, 1, 2, 3, 4, 5, 6, 7 – IOCCPn Interrupt-on-Change Positive Edge Enable bits

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCC pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

17.10.12 IOCEP

Name: IOCEP
Address: 0xF24

Interrupt-on-Change Positive Edge Register



Bit 3 – IOCEP3 Interrupt-on-Change Positive Edge Enable bit⁽¹⁾

| Value | Description |
|-------|---|
| 1 | Interrupt-on-Change enabled on the IOCE pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge. |
| 0 | Interrupt-on-Change disabled for the associated pin |

Note:

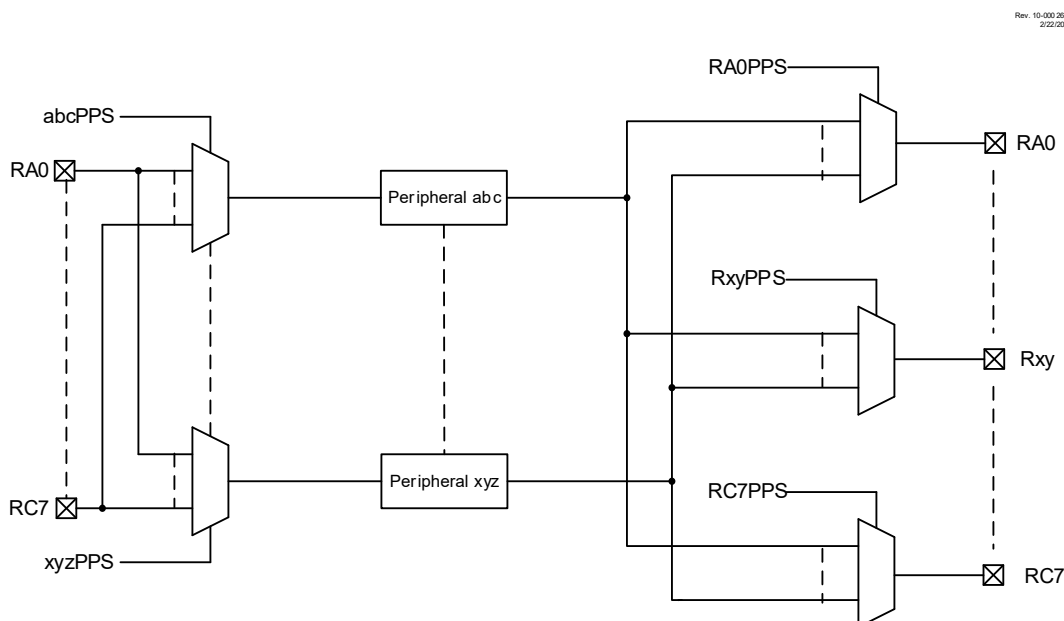
1. If MCLRE = 1 or LVP = 1, RE3 port functionality is disabled and IOC on RE3 is not available.

18. PPS - Peripheral Pin Select Module

The Peripheral Pin Select (PPS) module connects peripheral inputs and outputs to the device I/O pins. Only digital signals are included in the selections. All analog inputs and outputs remain fixed to their assigned pins. Input and output selections are independent as shown in the figure below.

The peripheral input is selected with the peripheral xxxPPS register, and the peripheral output is selected with the PORT RxyPPS register. For example, to select PORTC[7] as the EUSART RX input, set RXxPPS to 0x17 as shown in the input table, and to select PORTC[6] as the EUSART TX output set RC6PPS to 0x09 as shown in the output table.

Figure 18-1. Simplified PPS Block Diagram



18.1 PPS Inputs

Each peripheral has an xxxPPS register with which the input pin to the peripheral is selected. Not all ports are available for input as shown in the following table.

Multiple peripherals can operate from the same source simultaneously. Port reads always return the pin level regardless of peripheral PPS selection. If a pin also has analog functions associated, the ANSEL bit for that pin must be cleared to enable the digital input buffer.

➔ Important: The notation “xxx” in the generic register name is a place holder for the peripheral identifier. For example, xxx = INT for the INTPPS register.

Table 18-1. PPS Input Selection Register Details

| Peripheral | PPS Input Register | Default Pin Selection at POR | Register Reset Value at POR | PORT From Which Input Is Available | | | | | |
|--------------|--------------------|------------------------------|-----------------------------|------------------------------------|---|---|----------------|---|---|
| | | | | 28-Pin Devices | | | 40-Pin Devices | | |
| Interrupt 0 | INT0PPS | RB0 | 0x08 | A | B | — | A | B | — |
| Interrupt 1 | INT1PPS | RB1 | 0x09 | A | B | — | A | B | — |
| Interrupt 2 | INT2PPS | RB2 | 0x0A | A | B | — | A | B | — |
| Timer0 Clock | T0CKIPPS | RA4 | 0x04 | A | B | — | A | B | — |
| Timer1 Clock | T1CKIPPS | RC0 | 0x10 | A | — | C | A | — | C |

.....continued


| Peripheral | PPS Input Register | Default Pin Selection at POR | Register Reset Value at POR | PORT From Which Input Is Available | | | | | |
|------------------------|--------------------|------------------------------|-----------------------------|------------------------------------|---|---|----------------|---|---|
| | | | | 28-Pin Devices | | | 40-Pin Devices | | |
| Timer1 Gate | T1GPPS | RB5 | 0x0D | — | B | C | — | B | C |
| Timer3 Clock | T3CKIPPS | RC0 | 0x10 | — | B | C | — | B | C |
| Timer3 Gate | T3GPPS | RC0 | 0x10 | A | — | C | A | — | C |
| Timer5 Clock | T5CKIPPS | RC2 | 0x12 | A | — | C | A | — | C |
| Timer5 Gate | T5GPPS | RB4 | 0x0C | — | B | C | — | B | D |
| Timer2 Clock | T2INPPS | RC3 | 0x13 | A | — | C | A | — | C |
| Timer4 Clock | T4INPPS | RC5 | 0x15 | — | B | C | — | B | C |
| Timer6 Clock | T6INPPS | RB7 | 0x0F | — | B | C | — | B | D |
| ADC Conversion Trigger | ADACTPPS | RB4 | 0x0C | — | B | C | — | B | D |
| CCP1 | CCP1PPS | RC2 | 0x12 | — | B | C | — | B | C |
| CCP2 | CCP2PPS | RC1 | 0x11 | — | B | C | — | B | C |
| CWG | CWG1PPS | RB0 | 0x08 | — | B | C | — | B | D |
| DSM Carrier Low | MDCARLPPS | RA3 | 0x03 | A | — | C | A | — | D |
| DSM Carrier High | MDCARHPPS | RA4 | 0x04 | A | — | C | A | — | D |
| DSM Source | MDSRCPPS | RA5 | 0x05 | A | — | C | A | — | D |
| EUSART1 Receive | RX1PPS | RC7 | 0x17 | — | B | C | — | B | C |
| EUSART1 Clock | CK1PPS | RC6 | 0x16 | — | B | C | — | B | C |
| EUSART2 Receive | RX2PPS | RB7 | 0x0F | — | B | C | — | B | D |
| EUSART2 Clock | CK2PPS | RB6 | 0x0E | — | B | C | — | B | D |
| MSSP1 Clock | SSP1CLKPPS | RC3 | 0x13 | — | B | C | — | B | C |
| MSSP1 Data | SSP1DATPPS | RC4 | 0x14 | — | B | C | — | B | C |
| MSSP1 Client Select | SSP1SSPPS | RA5 | 0x05 | A | — | C | A | — | D |
| MSSP2 Clock | SSP2CLKPPS | RB1 | 0x09 | — | B | C | — | B | D |
| MSSP2 Data | SSP2DATPPS | RB2 | 0x0A | — | B | C | — | B | D |
| MSSP2 Client Select | SSP2SSPPS | RB0 | 0x08 | — | B | C | — | B | D |
| CLCIN0 | CLCIN0PPS | RA0 | 0x00 | A | — | C | A | — | C |
| CLCIN1 | CLCIN1PPS | RA1 | 0x01 | A | — | C | A | — | C |
| CLCIN2 | CLCIN2PPS | RB6 | 0x0E | — | B | C | — | B | D |
| CLCIN3 | CLCIN3PPS | RB7 | 0x0F | — | B | C | — | B | D |
| CLCIN4 | CLCIN4PPS | RA0 | 0x00 | A | — | C | A | — | C |
| CLCIN5 | CLCIN5PPS | RA1 | 0x01 | A | — | C | A | — | C |
| CLCIN6 | CLCIN6PPS | RB6 | 0x0E | — | B | C | — | B | D |
| CLCIN7 | CLCIN7PPS | RB7 | 0x0F | — | B | C | — | B | D |

18.2 PPS Outputs

Each I/O pin has a PPS register with which the pin output source is selected. With few exceptions, the port TRIS control associated with that pin retains control over the pin output driver. Peripherals that control the pin output driver as part of the peripheral operation will override the TRIS control as needed. These peripherals include:

- EUSART (synchronous operation)
- MSSP (I²C)

Although every pin has its own PPS peripheral selection register, the selections are identical for every pin as shown in [RxyPPS](#).

 **Important:** The notation “Rxy” is a placeholder for the pin identifier. The ‘x’ holds the place of the PORT letter and the ‘y’ holds the place of the bit number. For example, Rxy = RA0 for the RA0PPS register.

The table below shows detailed output routing options for each peripheral.

Table 18-2. Peripheral PPS Output Selection Codes

| RxyPPS | Pin Rxy Output Source | PORT To Which Output Can Be Directed | | | | | | | |
|--------|-----------------------|--------------------------------------|---|---|----------------|---|---|---|---|
| | | 28-Pin Devices | | | 40-Pin Devices | | | | |
| 0x1F | CLC8OUT | — | B | C | — | B | — | D | — |
| 0x1E | CLC7OUT | — | B | C | — | B | — | D | — |
| 0x1D | CLC6OUT | A | — | C | A | — | C | — | — |
| 0x1C | CLC5OUT | A | — | C | A | — | C | — | — |
| 0x1B | CLC4OUT | — | B | C | — | B | — | D | — |
| 0x1A | CLC3OUT | — | B | C | — | B | — | D | — |
| 0x19 | CLC2OUT | A | — | C | A | — | C | — | — |
| 0x18 | CLC1OUT | A | — | C | A | — | C | — | — |
| 0x17 | ADGRDB | A | — | C | A | — | C | — | — |
| 0x16 | ADGRDA | A | — | C | A | — | C | — | — |
| 0x15 | DSM | A | — | C | A | — | — | D | — |
| 0x14 | CLKR | — | B | C | — | B | C | — | — |
| 0x13 | TMR0 | — | B | C | — | B | C | — | — |
| 0x12 | MSSP2 (SDO/SDA) | — | B | C | — | B | — | D | — |
| 0x11 | MSSP2 (SCK/SCL) | — | B | C | — | B | — | D | — |
| 0x10 | MSSP1 (SDO/SDA) | — | B | C | — | B | C | — | — |
| 0x0F | MSSP1 (SCK/SCL) | — | B | C | — | B | C | — | — |
| 0x0E | CMP2 | A | — | C | A | — | — | — | E |
| 0x0D | CMP1 | A | — | C | A | — | — | D | — |
| 0x0C | EUSART2 (DT) | — | B | C | — | B | — | D | — |
| 0x0B | EUSART2 (TX/CK) | — | B | C | — | B | — | D | — |
| 0x0A | EUSART1 (DT) | — | B | C | — | B | C | — | — |
| 0x09 | EUSART1 (TX/CK) | — | B | C | — | B | C | — | — |
| 0x08 | PWM4 | A | — | C | A | — | C | — | — |
| 0x07 | PWM3 | A | — | C | A | — | — | D | — |
| 0x06 | CCP2 | — | B | C | — | B | C | — | — |
| 0x05 | CCP1 | — | B | C | — | B | C | — | — |
| 0x04 | CWG1D | — | B | C | — | B | — | D | — |
| 0x03 | CWG1C | — | B | C | — | B | — | D | — |
| 0x02 | CWG1B | — | B | C | — | B | — | D | — |
| 0x01 | CWG1A | — | B | C | — | B | C | — | — |
| 0x00 | LATxy | A | B | C | A | B | C | D | E |

18.3 Bidirectional Pins

PPS selections for peripherals with bidirectional signals on a single pin must be made so that the PPS input and PPS output select the same pin. Peripherals that have bidirectional signals include:

- EUSART (DT/RXxPPS and TX/CKxPPS pins for synchronous operation)
- MSSP (I²C SDA/SSPxDATPPS and SCL/SSPxCLKPPS)



Important: The I²C default inputs, and a limited number of other alternate pins, are I²C and SMBus compatible. Clock and data signals can be routed to any pin, however pins without I²C compatibility will operate at standard TTL/ST logic levels as selected by the INLVL register. See the INLVL register for each port to determine which pins are I²C and SMBus compatible.

18.4 PPS Lock

The PPS includes a mode in which all input and output selections can be locked to prevent inadvertent changes. PPS selections are locked by setting the PPSLOCKED bit of the PPSLOCK register. Setting and clearing this bit requires a special sequence as an extra precaution against inadvertent changes. Examples of setting and clearing the PPSLOCKED bit are shown in the following examples.

Example 18-1. PPS Lock Sequence

```
; Disable interrupts:
BCF    INTCON,GIE
; Bank to PPSLOCK register
BANKSEL PPSLOCK
MOVLW  55h
; Required sequence, next 4 instructions
MOVWF  PPSLOCK
MOVLW  AAh
MOVWF  PPSLOCK
; Set PPSLOCKED bit to disable writes
; Only a BSF instruction will work
BSF    PPSLOCK,PPSLOCKED
; Enable Interrupts
BSF    INTCON,GIE
```

Example 18-2. PPS Unlock Sequence

```
; Disable interrupts:
BCF    INTCON,GIE
; Bank to PPSLOCK register
BANKSEL PPSLOCK
MOVLW  55h
; Required sequence, next 4 instructions
MOVWF  PPSLOCK
MOVLW  AAh
MOVWF  PPSLOCK
; Clear PPSLOCKED bit to enable writes
; Only a BCF instruction will work
BCF    PPSLOCK,PPSLOCKED
; Enable Interrupts
BSF    INTCON,GIE
```

18.5 PPS One-Way Lock

Using the PPS1WAY Configuration bit, the PPS settings can be locked in. When this bit is set, the PPSLOCKED bit can only be cleared and set one time after a device Reset. This allows for clearing the PPSLOCKED bit so that the input and output selections can be made during initialization. When the PPSLOCKED bit is set after all selections have been made, it will remain set and cannot be cleared until after the next device Reset event.

18.6 Operation During Sleep

PPS input and output selections are unaffected by Sleep.

18.7 Effects of a Reset

A device Power-on-Reset (POR) clears all PPS input and output selections to their default values. All other Resets leave the selections unchanged. The default input selections are shown in the “*PPS Input Selection Register Details*” table. The PPS1WAY is also removed.

18.8 Register Summary - PPS

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|------------|----------|---|---|---|-----------|------|----------|----------|-----------|
| 0x00 ... 0x0E1E | Reserved | | | | | | | | | |
| 0x0E1F | CLCIN0PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E20 | CLCIN1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E21 | CLCIN2PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E22 | CLCIN3PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E23 | CLCIN4PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E24 | CLCIN5PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E25 | CLCIN6PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E26 | CLCIN7PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E27 ... 0x0E87 | Reserved | | | | | | | | | |
| 0x0E88 | RX2PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E89 | CK2PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E8A | SSP2CLKPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E8B | SSP2DATPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E8C | SSP2SSPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0E8D ... 0x0E9A | Reserved | | | | | | | | | |
| 0x0E9B | PPSLOCK | 7:0 | | | | | | | | PPSLOCKED |
| 0x0E9C | INT0PPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0E9D | INT1PPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0E9E | INT2PPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0E9F | T0CKIPPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0EA0 | T1CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA1 | T1GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA2 | T3CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA3 | T3GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA4 | T5CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA5 | T5GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA6 | T2INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA7 | T4INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA8 | T6INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA9 | ADACTPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAA | CCP1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAB | CCP2PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAC | CWG1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAD | MDCARLPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAE | MDCARHPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAF | MDSRCPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB0 | RX1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB1 | CK1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB2 | SSP1CLKPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB3 | SSP1DATPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB4 | SSP1SSPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB5 ... 0x0EE1 | Reserved | | | | | | | | | |
| 0x0EE2 | RA0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE3 | RA1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE4 | RA2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE5 | RA3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE6 | RA4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE7 | RA5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE8 | RA6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE9 | RA7PPS | 7:0 | | | | | | PPS[4:0] | | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|--------|----------|---|---|---|---|---|----------|---|---|
| 0x0EEA | RB0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEB | RB1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEC | RB2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EED | RB3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEE | RB4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEF | RB5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF0 | RB6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF1 | RB7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF2 | RC0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF3 | RC1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF4 | RC2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF5 | RC3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF6 | RC4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF7 | RC5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF8 | RC6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF9 | RC7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFA | RD0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFB | RD1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFC | RD2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFD | RD3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFE | RD4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFF | RD5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F00 | RD6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F01 | RD7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F02 | RE0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F03 | RE1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F04 | RE2PPS | 7:0 | | | | | | PPS[4:0] | | |

18.9 Register Definitions: PPS Input and Output Selection

18.9.1 Peripheral xxx Input Selection

Name: xxxPPS

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|-----------|-----|----------|-----|-----|
| | | | | PORT[1:0] | | PIN[2:0] | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | x | x | g | g | g |

Bits 4:3 – PORT[1:0] Peripheral xxx Input PORT Selection bits

See the “PPS Input Selection Register Details” table for a list of available ports and default pin locations.

| Value | Description |
|-------|-------------|
| 11 | PORTD |
| 10 | PORTC |
| 01 | PORTB |
| 00 | PORTA |

Bits 2:0 – PIN[2:0] Peripheral xxx Input Pin Selection bits

| Value | Description |
|-------|--|
| 111 | Peripheral input is from PORTx Pin 7 (Rx7) |
| 110 | Peripheral input is from PORTx Pin 6 (Rx6) |
| 101 | Peripheral input is from PORTx Pin 5 (Rx5) |
| 100 | Peripheral input is from PORTx Pin 4 (Rx4) |
| 011 | Peripheral input is from PORTx Pin 3 (Rx3) |
| 010 | Peripheral input is from PORTx Pin 2 (Rx2) |
| 001 | Peripheral input is from PORTx Pin 1 (Rx1) |
| 000 | Peripheral input is from PORTx Pin 0 (Rx0) |

18.9.2 Pin Rxy Output Source Selection Register

Name: RxyPPS

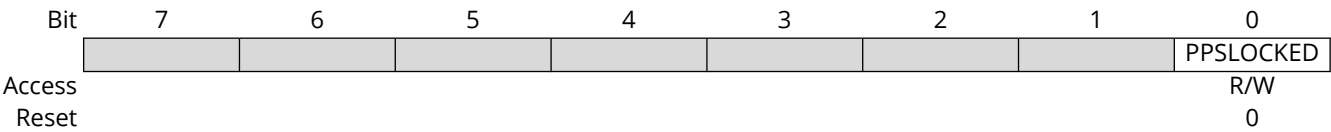
 **Important:** See [Register Summary - PPS](#) for the address offset of each individual register.

| | | | | | | | | |
|--------|---|---|---|-------------|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | RxyPPS[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – RxyPPS[4:0] Pin Rxy Output Source Selection bits
See the “Peripheral PPS Output Selection Codes” table for details about source selection.

18.9.3 PPS Lock Register

Name: PPSLOCK
Address: 0xE9B



Bit 0 – PPSLOCKED PPS Locked bit

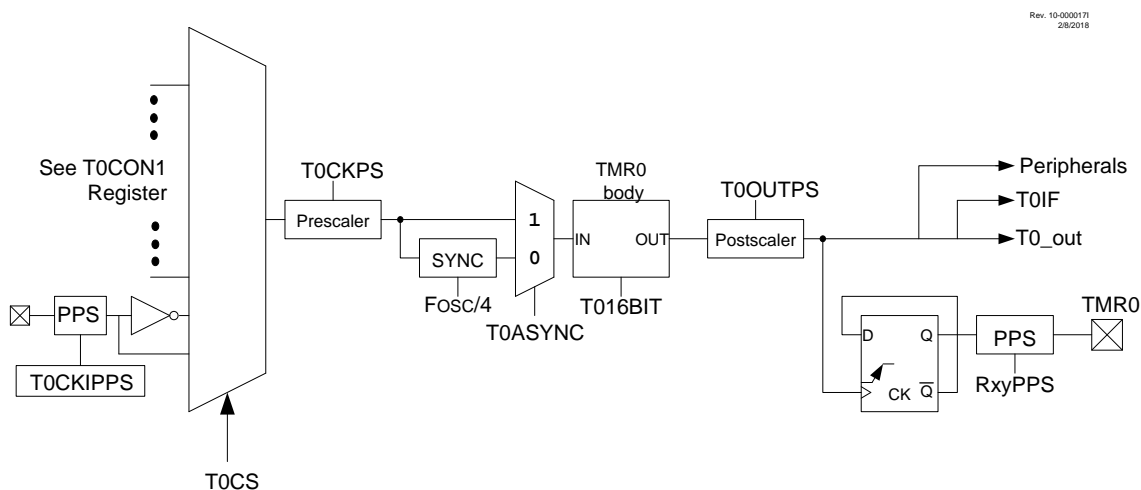
| Value | Description |
|-------|---|
| 1 | PPS is locked. PPS selections can not be changed. |
| 0 | PPS is not locked. PPS selections can be changed. |

19. TMR0 - Timer0 Module

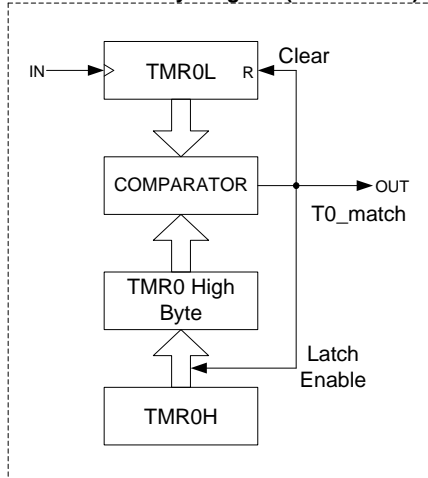
Timer0 module has the following features:

- 8-Bit Timer with Programmable Period
- 16-Bit Timer
- Selectable Clock Sources
- Synchronous and Asynchronous Operation
- Programmable Prescaler and Postscaler
- Interrupt on Match or Overflow
- Output on I/O Pin (via PPS) or to Other Peripherals
- Operation During Sleep

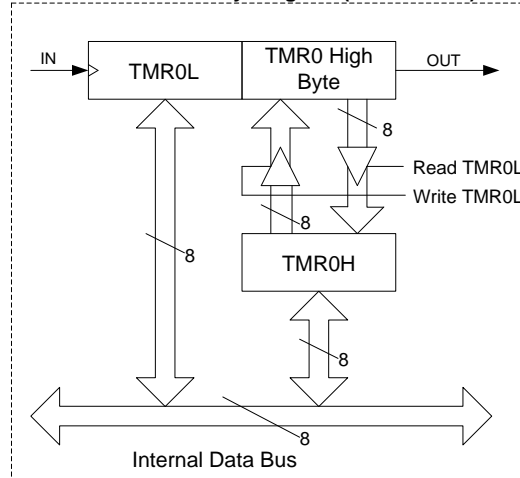
Figure 19-1. Timer0 Block Diagram



8-bit TMR0 Body Diagram (T016BIT = 0)



16-bit TMR0 Body Diagram (T016BIT = 1)



19.1 Timer0 Operation

Timer0 can operate as either an 8-bit or 16-bit timer. The mode is selected with the [T016BIT](#) bit.

19.1.1 8-Bit Mode

In this mode, Timer0 increments on the rising edge of the selected clock source. A prescaler on the clock input gives several prescale options (see prescaler control bits, [T0CKPS](#)).

In this mode, as shown in [Figure 19-1](#), a buffered version of TMR0H is maintained. This is compared with the value of TMR0L on each cycle of the selected clock source. When the two values match, the following events occur:

- TMR0L is reset
- The contents of TMR0H are copied to the TMR0H buffer for next comparison



Important:

When PR0 = 0 (i.e., either loaded with 0 or resets to 0, the TMR0 output ([T0OUT](#)) remains high.

19.1.2 16-Bit Mode

In this mode, Timer0 increments on the rising edge of the selected clock source. A prescaler on the clock input gives several prescale options (see prescaler control bits, [T0CKPS](#)).

In this mode, TMR0H:TMR0L form the 16-bit timer value. As shown in [Figure 19-1](#), read and write of the TMR0H register are buffered. The TMR0H register is updated with the contents of the high byte of Timer0 during a read of the TMR0L register. Similarly, a write to the high byte of Timer0 takes place through the TMR0H buffer register. The high byte is updated with the contents of the TMR0H register when a write occurs to the TMR0L register. This allows all 16 bits of Timer0 to be read and written at the same time.

Timer0 rolls over to 0x0000 on incrementing past 0xFFFF. This makes the timer free-running. The TMR0L/H registers cannot be reloaded in this mode once started.

19.2 Clock Selection

Timer0 has several options for clock source selections, option to operate synchronously/asynchronously and a programmable prescaler.

19.2.1 Clock Source Selection

The [T0CS](#) bits in the T0CON1 register are used to select the clock source for Timer0. Refer to the [Timer0 Clock Source Selections](#) table for possible clock sources.

19.2.2 Synchronous Mode

When the [T0ASYNC](#) bit is clear, Timer0 clock is synchronized to the system clock ($F_{OSC}/4$). When operating in Synchronous mode, Timer0 clock frequency cannot exceed $F_{OSC}/4$. During Sleep mode system clock is not available and Timer0 cannot operate.

19.2.3 Asynchronous Mode

When the [T0ASYNC](#) bit is set, Timer0 increments with each rising edge of the input source (or output of the prescaler, if used). Asynchronous mode allows Timer0 to continue operation during Sleep mode provided the selected clock source is available.

19.2.4 Programmable Prescaler

Timer0 has 16 programmable input prescaler options ranging from 1:1 to 1:32768. The prescaler values are selected using the [T0CKPS](#) bits.

The prescaler counter is not directly readable or writable. The prescaler counter is cleared on the following events:

- A write to the TMR0L register
- A write to either the T0CON0 or T0CON1 registers
- Any device Reset

Related Links

[Resets](#)

19.3 Timer0 Output and Interrupt

19.3.1 Programmable Postscaler

Timer0 has 16 programmable output postscaler options ranging from 1:1 to 1:16. The postscaler values are selected using the [T0OUTPS](#) bits. The postscaler divides the output of Timer0 by the selected ratio.

The postscaler counter is not directly readable or writable. The postscaler counter is cleared on the following events:

- A write to the TMR0L register
- A write to either the T0CON0 or T0CON1 registers
- Any device Reset

19.3.2 Timer0 Output

TMR0_out is the output of the postscaler. TMR0_out toggles on every match between TMR0L and TMR0H in 8-bit mode, or when TMR0H:TMR0L rolls over in 16-bit mode. If the output postscaler is used, the output is scaled by the ratio selected.



Important: When Timer0 is in 8-bit mode and TMR0H = 0, TMR0_out remains high.

The Timer0 output can be routed to an I/O pin via the RxyPPS output selection register. The Timer0 output can be monitored through software via the [T0OUT](#) output bit.

Related Links

[PPS Outputs](#)

19.3.3 Timer0 Interrupt

The Timer0 Interrupt Flag (TMR0IF) bit is set when the TMR0_out toggles. If the Timer0 interrupt is enabled (TMR0IE), the CPU will be interrupted when the TMR0IF bit is set.

When the postscaler bits (T0OUTPS) are set to 1:1 operation (no division), the T0IF flag bit will be set with every TMR0 match or rollover. In general, the TMR0IF flag bit will be set every T0OUTPS + 1 matches or rollovers.

19.3.4 Timer0 Example

Timer0 Configuration:

- Timer0 mode = 16-bit
- Clock Source = $F_{OSC}/4$ (250 kHz)
- Synchronous operation
- Prescaler = 1:1

- Postscaler = 1:2 (T0OUTPS = 1)

In this case, the TMR0_out toggles every two rollovers of TMR0H:TMR0L. i.e., $(0xFFFF) * 2 * (1/250kHz) = 524.28 \text{ ms}$

19.4 Operation During Sleep

When operating synchronously, Timer0 will halt when the device enters Sleep mode.

When operating asynchronously and selected clock source is active, Timer0 will continue to increment and wake the device from Sleep mode if Timer0 interrupt is enabled.

19.5 Register Summary - Timer0

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|------------|---|-------|---------|--------------|---|---|---|
| 0x00 ... 0x0FD1 | Reserved | | | | | | | | | |
| 0x0FD2 | TMR0L | 7:0 | TMR0L[7:0] | | | | | | | |
| 0x0FD3 | TMR0H | 7:0 | TMR0H[7:0] | | | | | | | |
| 0x0FD4 | TOCON0 | 7:0 | TOEN | | TOOUT | T016BIT | TOOUTPS[3:0] | | | |
| 0x0FD5 | TOCON1 | 7:0 | T0CS[2:0] | | | T0ASYNC | T0CKPS[3:0] | | | |

19.6 Register Definitions: Timer0 Control

19.6.1 T0CON0

Name: T0CON0
Address: 0xFD4

Timer0 Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|---|-------|---------|--------------|-----|-----|-----|
| | T0EN | | T0OUT | T016BIT | T0OUTPS[3:0] | | | |
| Access | R/W | | R | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – T0EN TMR0 Enable

| Value | Description |
|-------|-------------------------------------|
| 1 | The module is enabled and operating |
| 0 | The module is disabled |

Bit 5 – T0OUT TMR0 Output

Bit 4 – T016BIT TMR0 Operating as 16-Bit Timer Select

| Value | Description |
|-------|------------------------|
| 1 | TMR0 is a 16-bit timer |
| 0 | TMR0 is an 8-bit timer |

Bits 3:0 – T0OUTPS[3:0] TMR0 Output Postscaler (Divider) Select

| Value | Description |
|-------|-----------------|
| 1111 | 1:16 Postscaler |
| 1110 | 1:15 Postscaler |
| 1101 | 1:14 Postscaler |
| 1100 | 1:13 Postscaler |
| 1011 | 1:12 Postscaler |
| 1010 | 1:11 Postscaler |
| 1001 | 1:10 Postscaler |
| 1000 | 1:9 Postscaler |
| 0111 | 1:8 Postscaler |
| 0110 | 1:7 Postscaler |
| 0101 | 1:6 Postscaler |
| 0100 | 1:5 Postscaler |
| 0011 | 1:4 Postscaler |
| 0010 | 1:3 Postscaler |
| 0001 | 1:2 Postscaler |
| 0000 | 1:1 Postscaler |

19.6.2 T0CON1

Name: T0CON1
Address: 0xFD5

Timer0 Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|-----|-----|---------|-------------|-----|-----|-----|
| | T0CS[2:0] | | | TOASYNC | T0CKPS[3:0] | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:5 – T0CS[2:0] Timer0 Clock Source Select

Table 19-1. Timer 0 Clock Source Selections

| T0CS | Clock Source |
|------|---|
| 111 | CLC1_out |
| 110 | MFINTOSC (500 kHz) |
| 101 | SOSC |
| 100 | LFINTOSC |
| 011 | HFINTOSC |
| 010 | F _{OSC} /4 |
| 001 | Pin selected by T0CKIPPS (Inverted) |
| 000 | Pin selected by T0CKIPPS (Non-inverted) |

Bit 4 – TOASYNC TMR0 Input Asynchronization Enable

| Value | Description |
|-------|--|
| 1 | The input to the TMR0 counter is not synchronized to system clocks |
| 0 | The input to the TMR0 counter is synchronized to F _{OSC} /4 |

Bits 3:0 – T0CKPS[3:0] Prescaler Rate Select

| Value | Description |
|-------|-------------|
| 1111 | 1:32768 |
| 1110 | 1:16384 |
| 1101 | 1:8192 |
| 1100 | 1:4096 |
| 1011 | 1:2048 |
| 1010 | 1:1024 |
| 1001 | 1:512 |
| 1000 | 1:256 |
| 0111 | 1:128 |
| 0110 | 1:64 |
| 0101 | 1:32 |
| 0100 | 1:16 |
| 0011 | 1:8 |
| 0010 | 1:4 |
| 0001 | 1:2 |
| 0000 | 1:1 |

19.6.3 TMR0H

Name: TMR0H
Address: 0xFD3

Timer0 Period/Count High Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | TMR0H[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 7:0 – TMR0H[7:0] TMR0 Most Significant Counter

| Value | Condition | Description |
|----------------------------|-------------|--|
| 11111111 to 00000000 | T016BIT = 0 | 8-bit Timer0 Period Value. TMR0L continues counting from 0 when this value is reached. |
| 11111111 to 00000000 | T016BIT = 1 | 16-bit Timer0 Most Significant Byte |

19.6.4 TMR0L

Name: TMR0L
Address: 0xFD2

Timer0 Period/Count Low Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | TMR0L[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – TMR0L[7:0] TMR0 Least Significant Counter

| Value | Condition | Description |
|----------|-------------|--------------------------------------|
| 0 to 255 | T016BIT = 0 | 8-bit Timer0 Counter bits |
| 0 to 255 | T016BIT = 1 | 16-bit Timer0 Least Significant Byte |

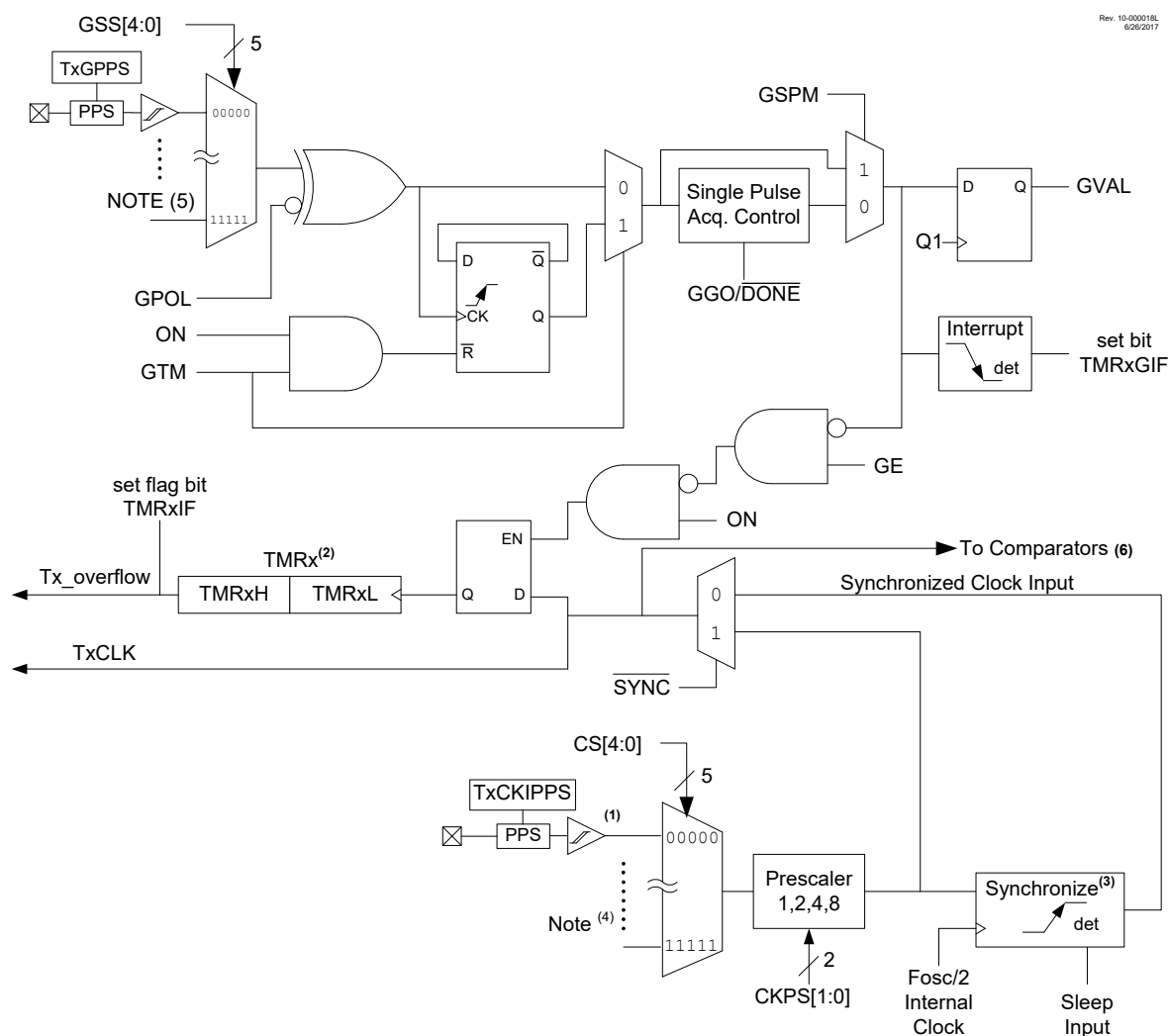
20. TMR1 - Timer1 Module with Gate Control

Timer1 module is a 16-bit timer/counter with the following features:

- 16-Bit Timer/Counter Register Pair (TMRxH:TMRxL)
- Programmable Internal or External Clock Source
- 2-Bit Prescaler
- Optionally Synchronized Comparator Out
- Multiple Timer1 Gate (Count Enable) Sources
- Interrupt-on-Overflow
- Wake-Up on Overflow (External Clock, Asynchronous Mode Only)
- 16-Bit Read/Write Operation
- Time Base for the Capture/Compare Function with the CCP Modules
- Special Event Trigger (with CCP)
- Selectable Gate Source Polarity
- Gate Toggle Mode
- Gate Single Pulse Mode
- Gate Value Status
- Gate Event Interrupt



Important: References to the Timer1 module apply to all the odd numbered timers on this device.

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1. This signal comes from the pin selected by TxCKIPPS.
2. The TMRx register increments on rising edge.
3. Synchronize does not operate while in Sleep.
4. See the [TMRxCLK](#) register for clock source selections.
5. See the [TMRxGATE](#) register for gate source selection.
6. Synchronized comparator output must not be used in conjunction with synchronized input clock.

The Timer1 module is a 16-bit incrementing counter that is accessed through the TMRxH:TMRxL register pair. Writes to TMRxH or TMRxL directly update the counter.

When used with an internal clock source, the module is a timer and increments on every instruction cycle. When used with an external clock source, the module can be used as either a timer or counter and increments on every selected edge of the external source.

Timer1 is enabled by configuring the **ON** and **GE** bits in the TxCON and TxGCON registers, respectively. The table below displays the Timer1 enable selections.

Table 20-1. Timer1 Enable Selections

| ON | GE | Timer1 Operation |
|----|----|------------------|
| 1 | 1 | Count Enabled |
| 1 | 0 | Always On |
| 0 | 1 | Off |
| 0 | 0 | Off |

20.2 Clock Source Selection

The **CS** bits select the clock source for Timer1. These bits allow the selection of several possible synchronous and asynchronous clock sources. The possible clock source are listed in **TMRxCLK** register.

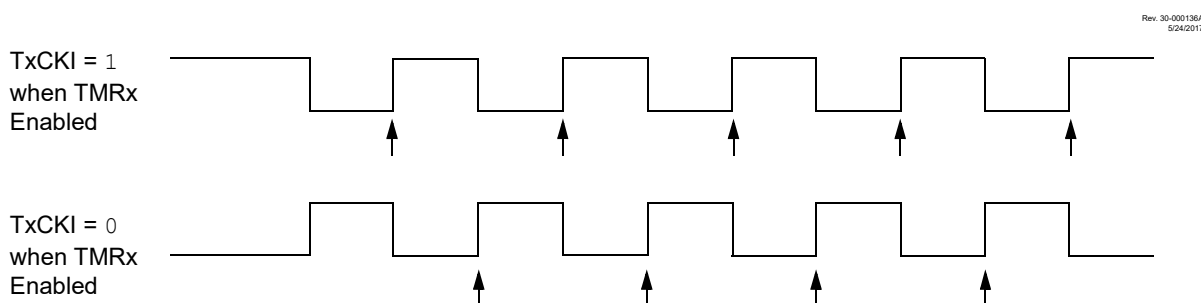
20.2.1 Internal Clock Source

When the internal clock source is selected the TMRxH:TMRxL register pair will increment on multiples of F_{OSC} as determined by the Timer1 prescaler.

When the F_{OSC} internal clock source is selected, the Timer1 register value will increment by four counts every instruction clock cycle. Due to this condition, a 2 LSB error in resolution will occur when reading the Timer1 value. To utilize the full resolution of Timer1, an asynchronous input signal must be used to gate the Timer1 clock input.

- ➔ Important:** In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge after any one or more of the following conditions:
- Timer1 enabled after POR
 - Write to TMRxH or TMRxL
 - Timer1 is disabled
 - Timer1 is disabled (TMRxON = 0) when TxCKI is high then Timer1 is enabled (TMRxON = 1) when TxCKI is low. Refer to the figure below.

Figure 20-2. Timer1 Incrementing Edge



Notes:

1. Arrows indicate counter increments.
2. In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge of the clock.

20.2.2 External Clock Source

When the external clock source is selected, the Timer1 module may work as a timer or a counter.

When enabled to count, Timer1 is incremented on the rising edge of the external clock input of the TxCKIPPS pin. This external clock source can be synchronized to the system clock or it can run asynchronously.

20.3 Timer1 Prescaler

Timer1 has four prescaler options allowing 1, 2, 4 or 8 divisions of the clock input. The [CKPS](#) bits control the prescale counter. The prescale counter is not directly readable or writable; however, the prescaler counter is cleared upon a write to TMRxH or TMRxL.

20.4 Secondary Oscillator

A secondary low-power 32.768 kHz oscillator circuit is built-in between pins SOSCI (input) and SOSCO (amplifier output). This internal circuit is to be used in conjunction with an external 32.768 kHz crystal. The secondary oscillator is not dedicated only to Timer1; it can also be used by other modules.

The oscillator circuit is enabled by setting the SOSCEN bit of the OSCEN register. This can be used as one of the Timer1 clock sources selected with the [CS](#) bits. The oscillator will continue to run during Sleep.



Important: The oscillator requires a start-up and stabilization time before use. Thus, the SOSCEN bit of the OSCEN register should be set and a suitable delay observed prior to enabling Timer1. A software check can be performed to confirm if the secondary oscillator is enabled and ready to use. This is done by polling the SOR bit of the OSCSTAT register.

Related Links

[Secondary Oscillator](#)

20.5 Timer1 Operation in Asynchronous Counter Mode

When the [SYNC](#) control bit is set, the external clock input is not synchronized. The timer increments asynchronously to the internal phase clocks. If external clock source is selected then the timer will continue to run during Sleep and can generate an interrupt on overflow, which will wake-up the processor. However, special precautions in software are needed to read/write the timer (see [Reading and Writing Timer1 in Asynchronous Counter Mode](#)).



Important: When switching from synchronous to asynchronous operation, it is possible to skip an increment. When switching from asynchronous to synchronous operation, it is possible to produce an additional increment.

20.5.1 Reading and Writing Timer1 in Asynchronous Counter Mode

Reading TMRxH or TMRxL while the timer is running from an external asynchronous clock will ensure a valid read (taken care of in hardware). However, reading the 16-bit timer in two 8-bit values itself poses certain problems, since the timer may overflow between the reads. For writes, it is recommended that the user simply stops the timer and writes the desired values. A write contention may occur by writing to the timer registers, while the register is incrementing. This may produce an unpredictable value in the TMRxH:TMRxL register pair.

20.6 Timer1 16-Bit Read/Write Mode

Timer1 can be configured to read and write all 16 bits of data to and from the 8-bit TMRxL and TMRxH registers, simultaneously. The 16-bit read and write operations are enabled by setting the RD16 bit.

To accomplish this function, the TMRxH register value is mapped to a buffer register called the TMRxH buffer register. While in 16-bit mode, the TMRxH register is not directly readable or writable and all read and write operations take place through the use of this TMRxH buffer register.

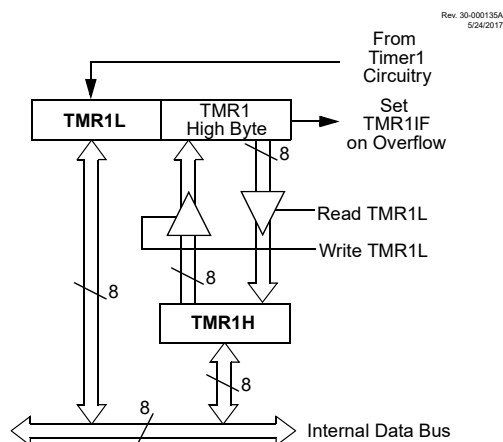
When a read from the TMRxL register is requested, the value of the TMRxH register is simultaneously loaded into the TMRxH buffer register. When a read from the TMRxH register is requested, the value is provided from the TMRxH buffer register instead. This provides the user with the ability to accurately read all 16 bits of the Timer1 value from a single instance in time. Refer to the figure below for more details.

In contrast, when not in 16-bit mode, the user must read each register separately and determine if the values have become invalid due to a rollover that may have occurred between the read operations.

When a write request of the TMRxL register is requested, the TMRxH buffer register is simultaneously updated with the contents of the TMRxH register. The value of TMRxH must be preloaded into the TMRxH buffer register prior to the write request for the TMRxL register. This provides the user with the ability to write all 16 bits to the TMRxL:TMRxH register pair at the same time.

Any requests to write to TMRxH directly does not clear the Timer1 prescaler value. The prescaler value is only cleared through write requests to the TMRxL register.

Figure 20-3. Timer1 16-Bit Read/Write Mode Block Diagram



20.7 Timer1 Gate

Timer1 can be configured to count freely or the count can be enabled and disabled using Timer1 gate circuitry. This is also referred to as Timer1 gate enable.

Timer1 gate can also be driven by multiple selectable sources.

20.7.1 Timer1 Gate Enable

The Timer1 Gate Enable mode is enabled by setting the GE bit. The polarity of the Timer1 Gate Enable mode is configured using the GPOL bit.

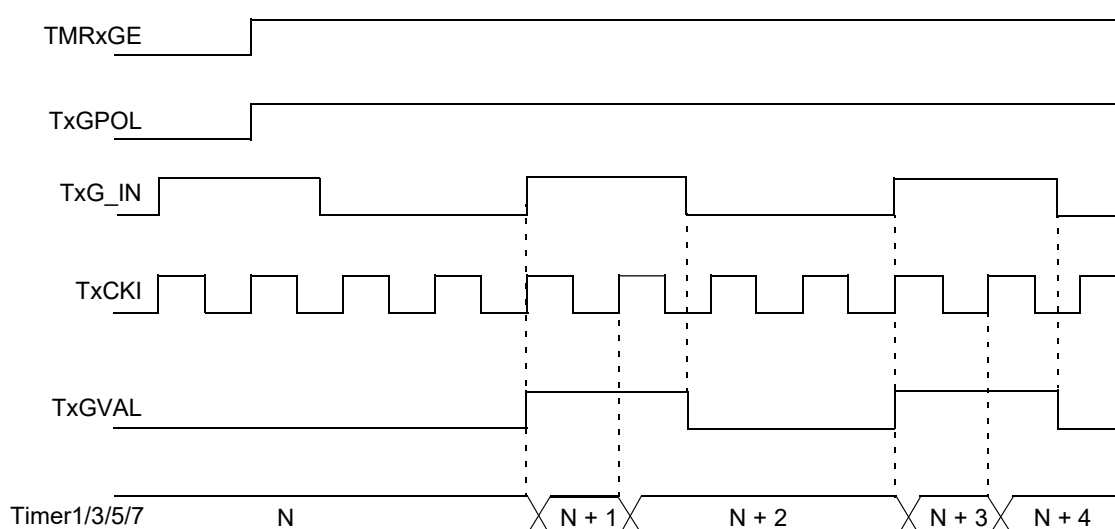
When Timer1 Gate Enable mode is enabled, Timer1 will increment on the rising edge of the Timer1 clock source. When Timer1 Gate signal is inactive, the timer will not increment and hold the current count. Enable mode is disabled, no incrementing will occur, and Timer1 will hold the current count. See the figure below for timing details.

Table 20-2. Timer1 Gate Enable Selections

| TMRxCLK | GPOL | TxG | Timer1 Operation |
|---------|------|-----|------------------|
| ↑ | 1 | 1 | Counts |
| ↑ | 1 | 0 | Holds Count |
| ↑ | 0 | 1 | Holds Count |
| ↑ | 0 | 0 | Counts |

Figure 20-4. Timer1 Gate Enable Mode

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5/24/2017



20.7.2 Timer1 Gate Source Selection

The gate source for Timer1 is selected using the [GSS](#) bits. The polarity selection for the gate source is controlled by the [GPOL](#) bit. The following gate source are available:

- Signal Measurement Timers
- Configurable Logic Cells
- Comparators
- PWM
- NCO
- T1CLKIN

For all options for gate source selection refer to section [TMRxGATE](#).

Related Links

[Comparator Output Synchronization](#)

20.7.3 Timer1 Gate Toggle Mode

When Timer1 Gate Toggle mode is enabled, it is possible to measure the full-cycle length of a Timer1 gate signal, as opposed to the duration of a single level pulse.

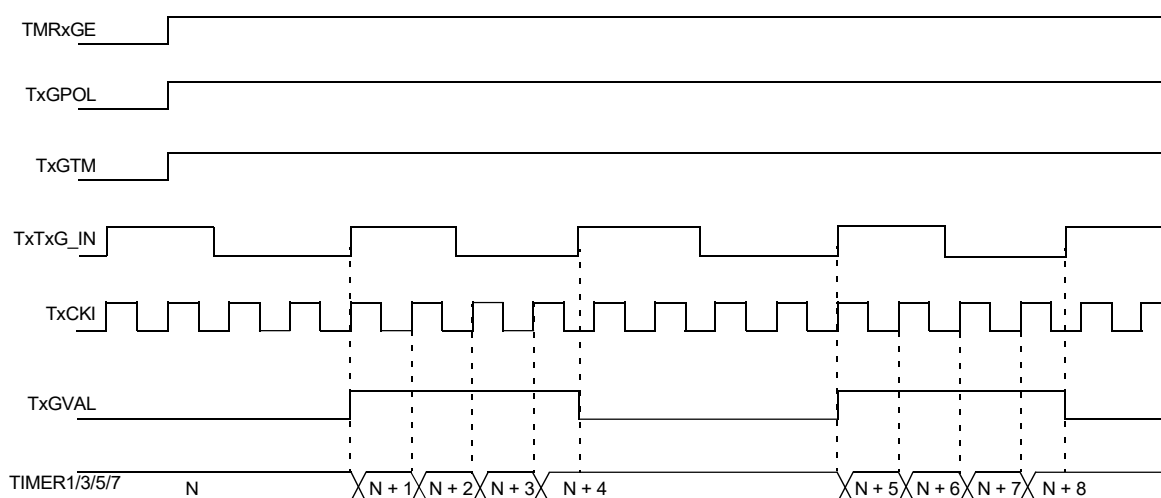
The Timer1 gate source is routed through a flip-flop that changes state on every incrementing edge of the signal. See figure below for timing details.

Timer1 Gate Toggle mode is enabled by setting the **GTM** bit. When the GTM bit is cleared, the flip-flop is cleared and held clear. This is necessary in order to control which edge is measured.



Important: Enabling Toggle mode at the same time as changing the gate polarity may result in indeterminate operation.

Figure 20-5. Timer1 Gate Toggle Mode



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5/25/2017

20.7.4 Timer1 Gate Single Pulse Mode

When Timer1 Gate Single Pulse mode is enabled, it is possible to capture a single pulse gate event. Timer1 Gate Single Pulse mode is first enabled by setting the **GSPM** bit in the TxGCON register. Next, the **GGO/DONE** bit in the TxGCON register must be set. The Timer1 will be fully enabled on the next incrementing edge. On the next trailing edge of the pulse, the **GGO/DONE** bit will automatically be cleared. No other gate events will be allowed to increment Timer1 until the **GGO/DONE** bit is once again set in software.

Clearing the GSPM bit will also clear the **GGO/DONE** bit. See figure below for timing details.

Enabling the Toggle mode and the Single Pulse mode simultaneously will permit both sections to work together. This allows the cycle times on the Timer1 gate source to be measured. See figure below for timing details.

Figure 20-6. Timer1 Gate Single Pulse Mode

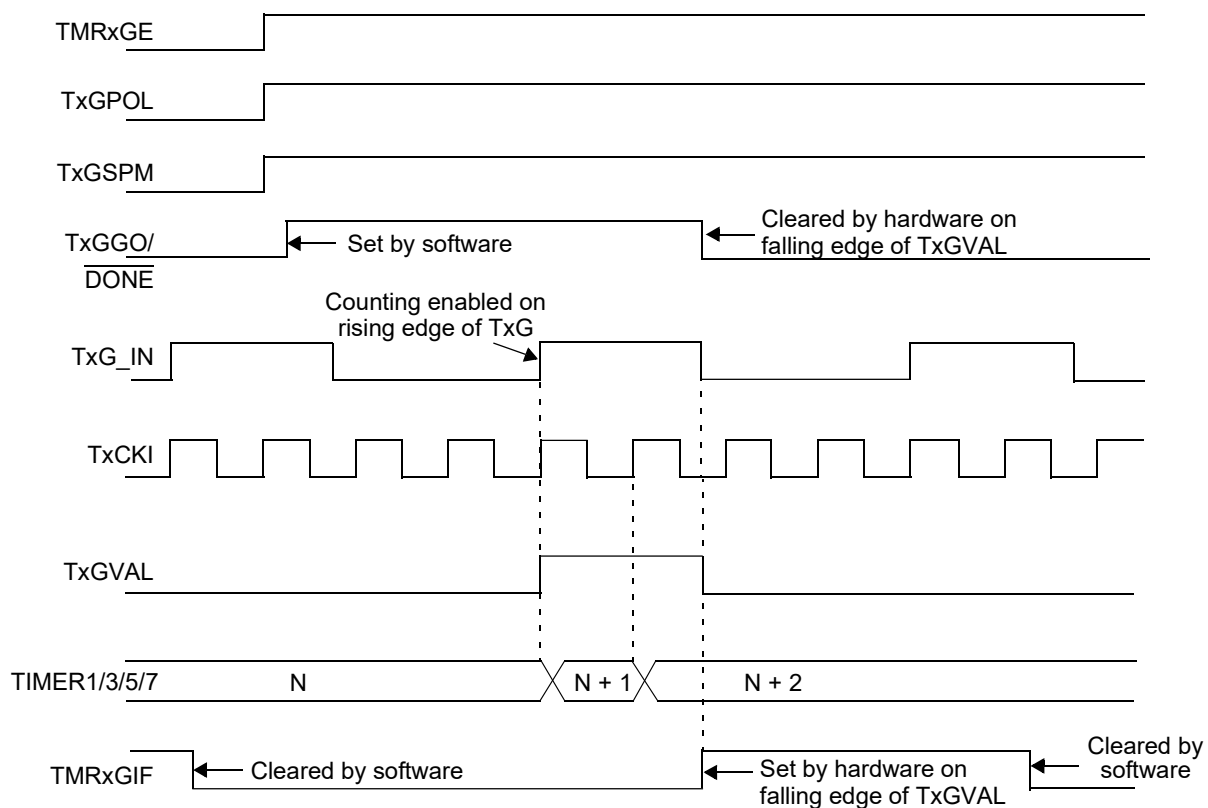
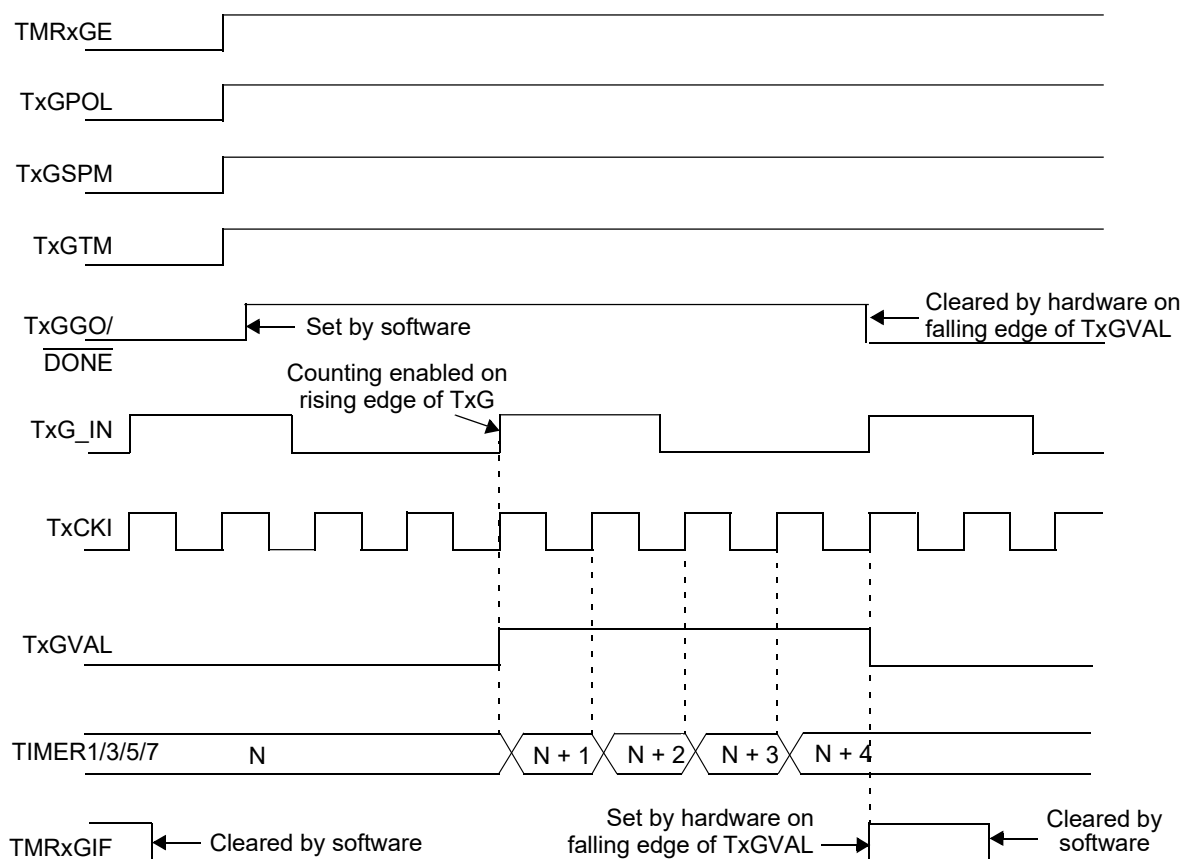
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Figure 20-7. Timer1 Gate Single Pulse and Toggle Combined ModeRev. 30-000140A
5/25/2017

20.7.5 Timer1 Gate Value Status

When Timer1 Gate Value Status is utilized, it is possible to read the most current level of the gate control value. The value is stored in the GVAL bit in the TxGCON register. The GVAL bit is valid even when the Timer1 gate is not enabled (GE bit is cleared).

20.7.6 Timer1 Gate Event Interrupt

When Timer1 gate event interrupt is enabled, it is possible to generate an interrupt upon the completion of a gate event. When the falling edge of GVAL occurs, the TMRxGIF flag bit in the PIR5 register will be set. If the TMRxGIE bit in the PIE5 register is set, then an interrupt will be recognized.

The TMRxGIF flag bit operates even when the Timer1 gate is not enabled (the GE bit is cleared).

For more information on selecting high or low priority status for the Timer1 gate event interrupt, refer to the **"Interrupts"** chapter.



Important: A pulse signal with minimum 100 ns width must be applied to TxGATE for proper operation. Any TxGATE pulse width that is shorter than 100 ns cannot be relied on to trigger an interrupt.

Related Links

[Interrupt Priority](#)

20.8 Timer1 Interrupt

The Timer1 register pair (TMRxH:TMRxL) increments to 0xFFFF and rolls over to 0x0000. When Timer1 rolls over, the Timer1 Interrupt Flag (TMR1IF) bit of the PIR4 register is set. To enable the interrupt-on-rollover, the following bits must be set:

- The TMRxON bit of the TxCON register
- The TMRxIE bits of the PIE4 register
- The PEIE/GIEL bit of the INTCON register
- The GIE/GIEH bit of the INTCON register

The interrupt is cleared by clearing the TMRxIF bit in the Interrupt Service Routine.

For more information on selecting high or low priority status for the Timer1 overflow interrupt, see the **“Interrupts”** chapter.



Important: The TMRxH:TMRxL register pair and the TMRxIF bit must be cleared before enabling interrupts.

Related Links

[Interrupt Priority](#)

20.9 Timer1 Operation During Sleep

Timer1 can only operate during Sleep when configured for Asynchronous Counter mode. In this mode, an external crystal or clock source can be used to increment the counter. To set up the timer to wake the device:

- The TMRxON bit of the TxCON register must be set
- The TMRxIE bit of the PIEx register must be set
- The PEIE/GIEL bit of the INTCON register must be set
- The $\overline{\text{TxSYNC}}$ bit of the TxCON register must be set
- Configure the TMRxCLK register for using secondary oscillator as the clock source
- Enable the SOSSEN bit of the OSCEN register

The device will wake up on an overflow and execute the next instruction. If the GIE/GIEH bit of the INTCON register is set, the device will call the Interrupt Service Routine.

The secondary oscillator will continue to operate in Sleep regardless of the $\overline{\text{TxSYNC}}$ bit setting.

20.10 CCP Capture/Compare Time Base

The CCP modules use the TMRxH:TMRxL register pair as the time base when operating in Capture or Compare mode.

In Capture mode, the value in the TMRxH:TMRxL register pair is copied into the CCPRxH:CCPRxL register pair on a configured event.

In Compare mode, an event is triggered when the value in the CCPRxH:CCPRxL register pair matches the value in the TMRxH:TMRxL register pair. This event can be a Special Event Trigger.

For more information, see the **“Capture/Compare/PWM Module”** chapter.

Related Links

[Capture/Compare/PWM Module](#)

20.11 CCP Special Event Trigger

When any of the CCPs are configured to trigger a special event, the trigger will clear the TMRxH:TMRxL register pair. This special event does not cause a Timer1 interrupt. The CCP module may still be configured to generate a CCP interrupt.

In this mode of operation, the CCPRxH:CCPRxL register pair becomes the period register for Timer1.

Timer1 must be synchronized and $F_{OSC}/4$ must be selected as the clock source to utilize the Special Event Trigger. Asynchronous operation of Timer1 can cause a Special Event Trigger to be missed.

In the event that a write to TMRxH or TMRxL coincides with a Special Event Trigger from the CCP, the write will take precedence.

20.12 Peripheral Module Disable

When a peripheral is not used or inactive, the module can be disabled by setting the Module Disable bit in the PMD registers. This will reduce power consumption to an absolute minimum. Setting the PMD bits holds the module in Reset and disconnects the module's clock source. The Module Disable bits for Timer1 (TMR1MD) are in the PMD1 register. See the **"PMD - Peripheral Module Disable"** chapter for more information.

Related Links

[Register Summary - PMD](#)

20.13 Register Summary - Timer1

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|------------|------|-----|------|----------|------|------|----|
| 0x00 ... 0x0FBF | Reserved | | | | | | | | | |
| 0x0FC0 | TMR5 | 7:0 | TMRx[7:0] | | | | | | | |
| | | 15:8 | TMRx[15:8] | | | | | | | |
| 0x0FC2 | T5CON | 7:0 | CKPS[1:0] | | | | | SYNC | RD16 | ON |
| 0x0FC3 | T5GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| 0x0FC4 | TMR5GATE | 7:0 | GSS[4:0] | | | | | | | |
| 0x0FC5 | TMR5CLK | 7:0 | CS[4:0] | | | | | | | |
| 0x0FC6 | TMR3 | 7:0 | TMRx[7:0] | | | | | | | |
| | | 15:8 | TMRx[15:8] | | | | | | | |
| 0x0FC8 | T3CON | 7:0 | CKPS[1:0] | | | | | SYNC | RD16 | ON |
| 0x0FC9 | T3GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| 0x0FCA | TMR3GATE | 7:0 | GSS[4:0] | | | | | | | |
| 0x0FCB | TMR3CLK | 7:0 | CS[4:0] | | | | | | | |
| 0x0FCC | TMR1 | 7:0 | TMRx[7:0] | | | | | | | |
| | | 15:8 | TMRx[15:8] | | | | | | | |
| 0x0FCE | T1CON | 7:0 | CKPS[1:0] | | | | | SYNC | RD16 | ON |
| 0x0FCF | T1GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| 0x0FD0 | TMR1GATE | 7:0 | GSS[4:0] | | | | | | | |
| 0x0FD1 | TMR1CLK | 7:0 | CS[4:0] | | | | | | | |

20.14 Register Definitions: Timer1

Long bit name prefixes for the odd numbered timers is shown in the following table. Refer to the “**Long Bit Names**” section for more information.

Table 20-3. Timer1 prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| Timer1 | T1 |
| Timer3 | T3 |
| Timer5 | T5 |

Related Links

[Long Bit Names](#)

20.14.1 TxCON

Name: TxCON
Address: 0xFCE, 0xFC8, 0xFC2

Timer Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|-----------|-----|---|------|------|-----|
| | | | CKPS[1:0] | | | SYNC | RD16 | ON |
| Access | | | R/W | R/W | | R/W | R/W | R/W |
| Reset | | | 0 | 0 | | 0 | 0 | 0 |

Bits 5:4 – CKPS[1:0] Timer Input Clock Prescale Select bits

Reset States: POR/BOR = 00
 All Other Resets = uu

| Value | Description |
|-------|--------------------|
| 11 | 1:8 Prescale value |
| 10 | 1:4 Prescale value |
| 01 | 1:2 Prescale value |
| 00 | 1:1 Prescale value |

Bit 2 – SYNC Timer External Clock Input Synchronization Control bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Condition | Description |
|-------|-------------------------------|---|
| x | $CS = F_{OSC}/4$ or F_{OSC} | This bit is ignored. Timer uses the incoming clock as is. |
| 1 | Else | Do not synchronize external clock input |
| 0 | Else | Synchronize external clock input with system clock |

Bit 1 – RD16 16-Bit Read/Write Mode Enable bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|--|
| 1 | Enables register read/write of Timer in one 16-bit operation |
| 0 | Enables register read/write of Timer in two 8-bit operations |

Bit 0 – ON Timer On bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|----------------|
| 1 | Enables Timer |
| 0 | Disables Timer |

20.14.2 TxGCON

Name: TxGCON
Address: 0xFCF, 0xFC9, 0xFC3

Timer Gate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|------|-----|------|----------|------|---|---|
| | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| Access | R/W | R/W | R/W | R/W | R/W | RO | | |
| Reset | 0 | 0 | 0 | 0 | 0 | x | | |

Bit 7 – GE Timer Gate Enable bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Condition | Description |
|-------|-----------|---|
| 1 | ON = 1 | Timer counting is controlled by the Timer gate function |
| 0 | ON = 1 | Timer is always counting |
| x | ON = 0 | This bit is ignored |

Bit 6 – GPOL Timer Gate Polarity bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|--|
| 1 | Timer gate is active-high (Timer counts when gate is high) |
| 0 | Timer gate is active-low (Timer counts when gate is low) |

Bit 5 – GTM Timer Gate Toggle Mode bit

Timer Gate Flip-Flop Toggles on every rising edge when Toggle mode is enabled.

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|--|
| 1 | Timer Gate Toggle mode is enabled |
| 0 | Timer Gate Toggle mode is disabled and Toggle flip-flop is cleared |

Bit 4 – GSPM Timer Gate Single Pulse Mode bit

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|--|
| 1 | Timer Gate Single Pulse mode is enabled and is controlling Timer gate) |
| 0 | Timer Gate Single Pulse mode is disabled |

Bit 3 – GGO/DONE Timer Gate Single Pulse Acquisition Status bit

This bit is automatically cleared when TxGSPM is cleared.

Reset States: POR/BOR = 0
 All Other Resets = u

| Value | Description |
|-------|--|
| 1 | Timer Gate Single Pulse Acquisition is ready, waiting for an edge |
| 0 | Timer Gate Single Pulse Acquisition has completed or has not been started. |

Bit 2 – GVAL Timer Gate Current State bit

Indicates the current state of the timer gate that could be provided to TMRxH:TMRxL

Unaffected by Timer Gate Enable (TMRxGE)

20.14.3 TMRxCLK

Name: TMRxCLK
Address: 0xFD1, 0xFCB, 0xFC5

Timer Clock Source Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---------|-----|-----|-----|-----|
| | | | | CS[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – CS[4:0] Timer Clock Source Selection bits

Table 20-4. Timer Clock Sources

| CS | Clock Source | | |
|-------------|--------------------|--------------------|--------------------|
| | Timer1 | Timer3 | Timer5 |
| 11000-11111 | Reserved | Reserved | Reserved |
| 10111 | CLC8_out | CLC8_out | CLC8_out |
| 10110 | CLC7_out | CLC7_out | CLC7_out |
| 10101 | CLC6_out | CLC6_out | CLC6_out |
| 10100 | CLC5_out | CLC5_out | CLC5_out |
| 10011 | CLC4_out | CLC4_out | CLC4_out |
| 10010 | CLC3_out | CLC3_out | CLC3_out |
| 10001 | CLC2_out | CLC2_out | CLC2_out |
| 10000 | CLC1_out | CLC1_out | CLC1_out |
| 01111-01100 | Reserved | Reserved | Reserved |
| 01011 | TMR5 overflow | TMR5 overflow | Reserved |
| 01010 | TMR3 overflow | Reserved | TMR3 overflow |
| 01001 | Reserved | TMR1 overflow | TMR1 overflow |
| 01000 | TMR0 overflow | TMR0 overflow | TMR0 overflow |
| 00111 | CLKREF | CLKREF | CLKREF |
| 00110 | SOSC | SOSC | SOSC |
| 00101 | MFINTOSC (500 kHz) | MFINTOSC (500 kHz) | MFINTOSC (500 kHz) |
| 00100 | LFINTOSC | LFINTOSC | LFINTOSC |
| 00011 | HFINTOSC | HFINTOSC | HFINTOSC |
| 00010 | Fosc | Fosc | Fosc |
| 00001 | Fosc/4 | Fosc/4 | Fosc/4 |
| 00000 | T1CKIPPS | T3CKIPPS | T5CKIPPS |

Reset States: POR/BOR = 00000
 All Other Resets = uuuuu

20.14.4 TMRxGATE

Name: TMRxGATE
Address: 0xFD0,0xFCA,0xFC4

Timer Gate Source Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|----------|-----|-----|-----|-----|
| | | | | GSS[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – GSS[4:0] Timer Gate Source Selection bits

Table 20-5. Timer Gate Sources

| GSS | Gate Source | | |
|-------------|------------------------|------------------------|------------------------|
| | Timer1 | Timer3 | Timer5 |
| 11000-11111 | Reserved | Reserved | Reserved |
| 10111 | CLC8_out | CLC8_out | CLC8_out |
| 10110 | CLC7_out | CLC7_out | CLC7_out |
| 10101 | CLC6_out | CLC6_out | CLC6_out |
| 10100 | CLC5_out | CLC5_out | CLC5_out |
| 10011 | CLC4_out | CLC4_out | CLC4_out |
| 10010 | CLC3_out | CLC3_out | CLC3_out |
| 10001 | CLC2_out | CLC2_out | CLC2_out |
| 10000 | CLC1_out | CLC1_out | CLC1_out |
| 01111 | Reserved | Reserved | Reserved |
| 01110 | ZCDOUT | ZCDOUT | ZCDOUT |
| 01101 | CMP2OUT | CMP2OUT | CMP2OUT |
| 01100 | CMP1OUT | CMP1OUT | CMP1OUT |
| 01011 | PWM4OUT | PWM4OUT | PWM4OUT |
| 01010 | PWM3OUT | PWM3OUT | PWM3OUT |
| 01001 | CCP2OUT | CCP2OUT | CCP2OUT |
| 01000 | CCP1OUT | CCP1OUT | CCP1OUT |
| 00111 | TMR6OUT (post-scaled) | TMR6OUT (post-scaled) | TMR6OUT (post-scaled) |
| 00110 | TMR5 overflow | TMR5 overflow | Reserved |
| 00101 | TMR4OUT (post-scaled) | TMR4OUT (post-scaled) | TMR4OUT (post-scaled) |
| 00100 | TMR3 overflow | Reserved | TMR3 overflow |
| 00011 | TMR2OUT (post-scaled) | TMR2OUT (post-scaled) | TMR2OUT (post-scaled) |
| 00010 | Reserved | TMR1 overflow | TMR1 overflow |
| 00001 | TMR0 overflow | TMR0 overflow | TMR0 overflow |
| 00000 | Pin selected by T1GPPS | Pin selected by T3GPPS | Pin selected by T5GPPS |

Reset States: POR/BOR = 00000
 All Other Resets = uuuuu

20.14.5 Timer Register

Name: TMRx
Address: 0xFCC, 0xFC6, 0xFC0

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | TMRx[15:8] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TMRx[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:0 – TMRx[15:0] Timer Register Value

Notes: The individual bytes in this multibyte register can be accessed with the following register names:

- TMRxH: Accesses the high byte TMRx[15:8]
- TMRxL: Accesses the low byte TMRx[7:0]

Reset States: POR/BOR = 0000000000000000

All Other Resets = uuuuuuuuuuuuuuuuuu

21. TMR2 - Timer2 Module

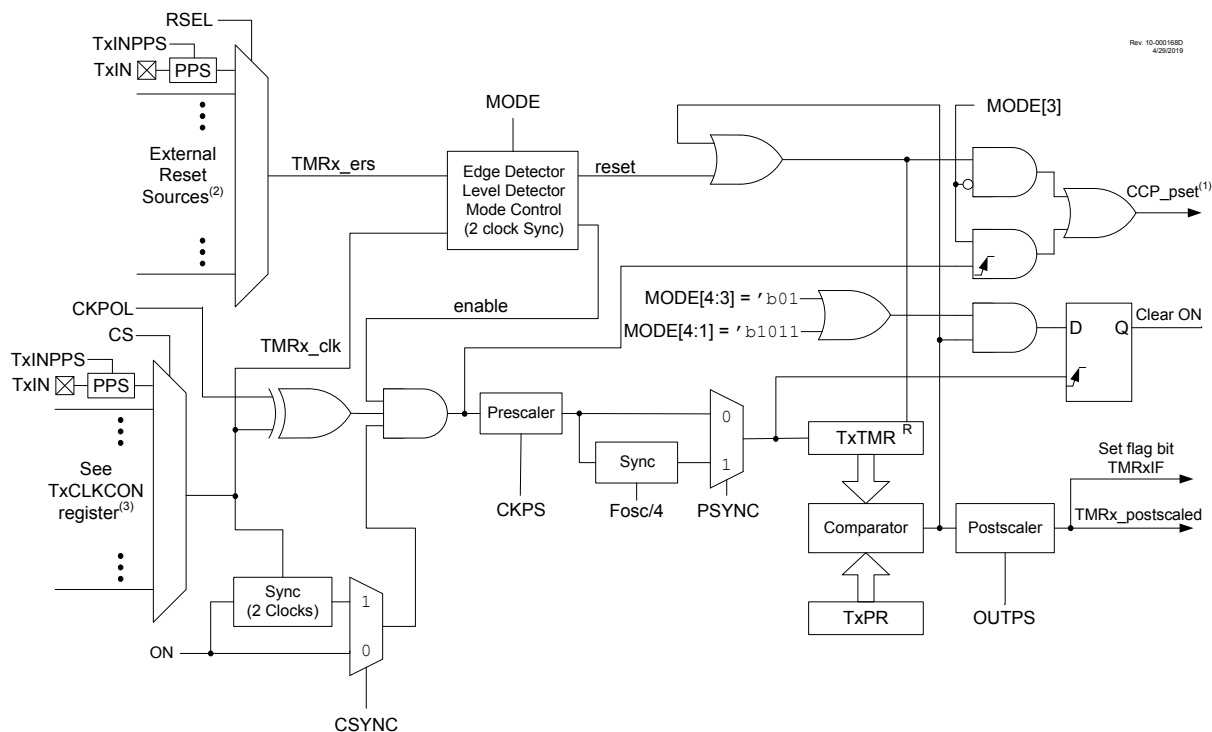
The Timer2 module is a 8-bit timer that incorporates the following features:

- 8-Bit Timer and Period Registers
- Readable and Writable
- Software Programmable Prescaler (1:1 to 1:128)
- Software Programmable Postscaler (1:1 to 1:16)
- Interrupt on T2TMR Match with T2PR
- One-Shot Operation
- Full Asynchronous Operation
- Includes Hardware Limit Timer (HLT)
- Alternate Clock Sources
- External Timer Reset Signal Sources
- Configurable Timer Reset Operation

See Figure 21-1 for a block diagram of Timer2.

➔ Important: References to module Timer2 apply to all the even numbered timers on this device. (Timer2, Timer4, etc.)

Figure 21-1. Timer2 with Hardware Limit Timer (HLT) Block Diagram



Notes:

1. Signal to the CCP to trigger the PWM pulse.
2. See [TxRST](#) for external Reset sources.
3. See [Clock Source Selection](#) table for clock source selection.

21.1 Timer2 Operation

Timer2 operates in three major modes:

- Free Running Period
- One Shot
- Monostable

Within each mode there are several options for starting, stopping, and reset. [Table 21-1](#) lists the options.

In all modes, the T2TMR count register is incremented on the rising edge of the clock signal from the programmable prescaler. When T2TMR equals T2PR, a high level is output to the postscaler counter. T2TMR is cleared on the next clock input.

An external signal from hardware can also be configured to gate the timer operation or force a T2TMR count Reset. In Gate modes, the counter stops when the gate is disabled and resumes when the gate is enabled. In Reset modes, the T2TMR count is reset on either the level or edge from the external source.

The T2TMR and T2PR registers are both directly readable and writable. The T2TMR register is cleared and the T2PR register initializes to FFh on any device Reset. Both the prescaler and postscaler counters are cleared on the following events:

- A write to the T2TMR register
- A write to the T2CON register
- Any device Reset
- External Reset Source event that resets the timer.



Important: T2TMR is not cleared when T2CON is written.

21.1.1 Free-Running Period Mode

The value of T2TMR is compared to that of the Period register, T2PR, on each clock cycle. When the two values match, the comparator resets the value of T2TMR to 00h on the next cycle and increments the output postscaler counter. When the postscaler count equals the value in the [OUTPS](#) bits of the T2CON register then a one clock period wide pulse occurs on the TMR2_postscaled output, and the postscaler count is cleared.

21.1.2 One Shot Mode

The One Shot mode is identical to the Free-Running Period mode, except that the ON bit is cleared and the timer is stopped when T2TMR matches T2PR and will not restart until the ON bit is cycled off and on. Postscaler (OUTPS) values other than zero are ignored in this mode because the timer is stopped at the first period event and the postscaler is reset when the timer is restarted.

21.1.3 Monostable Mode

Monostable modes are similar to One Shot modes except that the ON bit is not cleared and the timer can be restarted by an external Reset event.

21.2 Timer2 Output

The Timer2 module's primary output is TMR2_postscaled, which pulses for a single TMR2_clk period upon each match of the postscaler counter and the OUTPS bits of the T2CON register. The postscaler is incremented each time the T2TMR value matches the T2PR value. This signal can be selected as an input to several other input modules:

- The ADC module, as an auto-conversion trigger
- CWG, as an auto-shutdown source
- The CRC memory scanner, as a trigger for triggered mode
- Gate source for odd numbered timers (Timer1, Timer3, etc.)
- Alternate SPI clock
- Reset signals for other instances of even numbered timers (Timer2, Timer4, etc.)

In addition, the Timer2 is also used by the CCP module for pulse generation in PWM mode. See **"PWM Overview"** and **"Pulse-Width Modulation"** sections for details on setting up Timer2 for use with the CCP and PWM modules.

Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

21.3 External Reset Sources

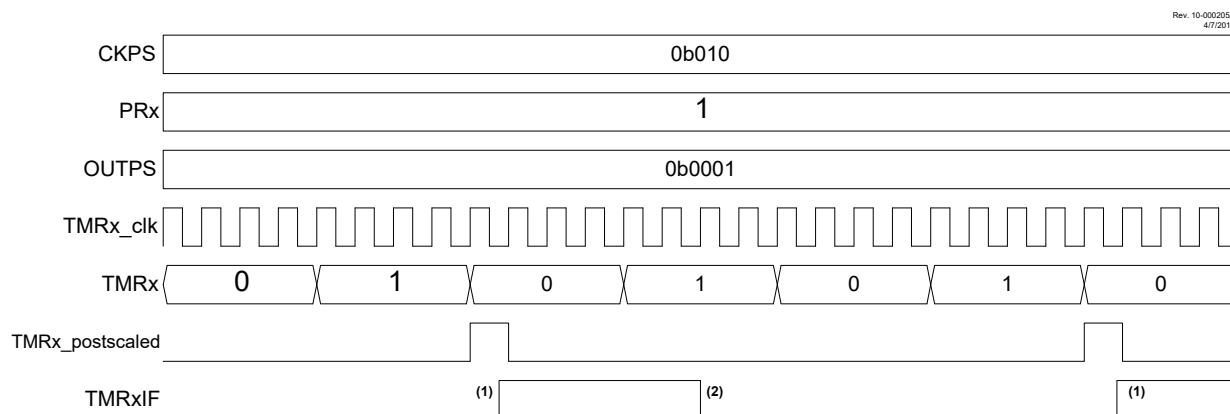
In addition to the clock source, the Timer2 also takes in an external Reset source. This external Reset source is selected for each timer with the corresponding TxRST register. This source can control starting and stopping of the timer, as well as resetting the timer, depending on which mode the timer is in. Reset source selections are shown in the following table.

Refer to the [External Reset Sources](#) table for further information.

21.4 Timer2 Interrupt

Timer2 can also generate a device interrupt. The interrupt is generated when the postscaler counter matches with the selected postscaler value (OUTPS bits of T2CON register). The interrupt is enabled by setting the TMR2IE interrupt enable bit. Interrupt timing is illustrated in the figure below.

Figure 21-2. Timer2 Prescaler, Postscaler, and Interrupt Timing Diagram



Notes:

1. Setting the interrupt flag is synchronized with the instruction clock.
2. Cleared by software.

21.5 Operating Modes

The mode of the timer is controlled by the **MODE** bits of the **T2HLT** register. Edge-Triggered modes require six Timer clock periods between external triggers. Level-Triggered modes require the triggering level to be at least three Timer clock periods long. External triggers are ignored while in Debug mode.

Table 21-1. Operating Modes Table

| Mode | MODE[4:0] | | Output Operation | Operation | Timer Control | | | |
|---------------------|-----------|----------|--|---|-------------------------|--------------|--|--|
| | [4:3] | [2:0] | | | Start | Reset | Stop | |
| Free-Running Period | 00 | 000 | Period Pulse | Software gate (Figure 21-3) | ON = 1 | — | ON = 0 | |
| | | 001 | | Hardware gate, active-high (Figure 21-4) | ON = 1 and TMRx_ers = 1 | — | ON = 0 or TMRx_ers = 0 | |
| | | 010 | | Hardware gate, active-low | ON = 1 and TMRx_ers = 0 | — | ON = 0 or TMRx_ers = 1 | |
| | | 011 | Period Pulse with Hardware Reset | Rising or falling edge Reset | ON = 1 | TMRx_ers ↕ | ON = 0 | |
| | | 100 | | Rising edge Reset (Figure 21-5) | | TMRx_ers ↑ | | |
| | | 101 | | Falling edge Reset | | TMRx_ers ↓ | | |
| | | 110 | | Low-level Reset | | TMRx_ers = 0 | ON = 0 or TMRx_ers = 0 | |
| | | 111 | | High-level Reset (Figure 21-6) | | TMRx_ers = 1 | ON = 0 or TMRx_ers = 1 | |
| One Shot | 01 | 000 | One-shot | Software start (Figure 21-7) | ON = 1 | — | ON = 0 or Next clock after TMRx = PRx (Note 2) | |
| | | 001 | Edge-Triggered Start (Note 1) | Rising edge start (Figure 21-8) | ON = 1 and TMRx_ers ↑ | — | | |
| | | 010 | | Falling edge start | ON = 1 and TMRx_ers ↓ | — | | |
| | | 011 | | Any edge start | ON = 1 and TMRx_ers ↕ | — | | |
| | | 100 | Edge-Triggered Start and Hardware Reset (Note 1) | Rising edge start and Rising edge Reset (Figure 21-9) | ON = 1 and TMRx_ers ↑ | TMRx_ers ↑ | | |
| | | 101 | | Falling edge start and Falling edge Reset | ON = 1 and TMRx_ers ↓ | TMRx_ers ↓ | | |
| | | 110 | | Rising edge start and Low-level Reset (Figure 21-10) | ON = 1 and TMRx_ers ↑ | TMRx_ers = 0 | | |
| | | 111 | | Falling edge start and High-level Reset | ON = 1 and TMRx_ers ↓ | TMRx_ers = 1 | | |
| Monostable | 10 | 000 | Reserved | | | | | |
| | | 001 | Edge-Triggered Start (Note 1) | Rising edge start (Figure 21-11) | ON = 1 and TMRx_ers ↑ | — | ON = 0 or Next clock after TMRx = PRx (Note 3) | |
| | | 010 | | Falling edge start | ON = 1 and TMRx_ers ↓ | — | | |
| | | 011 | | Any edge start | ON = 1 and TMRx_ers ↕ | — | | |
| | | Reserved | 100 | Reserved | | | | |
| | | Reserved | 101 | Reserved | | | | |
| One Shot | | 110 | Level-Triggered Start and | High-level start and Low-level Reset (Figure 21-12) | ON = 1 and TMRx_ers = 1 | TMRx_ers = 0 | ON = 0 or Held in Reset (Note 2) | |
| | | 111 | Hardware Reset | Low-level start and High-level Reset | ON = 1 and TMRx_ers = 0 | TMRx_ers = 1 | | |

.....continued

| Mode | MODE[4:0] | | Output Operation | Operation | Timer Control | | |
|----------|-----------|-------|------------------|-----------|---------------|-------|----------|
| | [4:3] | [2:0] | | | Start | Reset | Stop |
| Reserved | 11 | xxx | | | | | Reserved |

Notes:

1. If ON = 0, then an edge is required to restart the timer after ON = 1.
2. When T2TMR = T2PR, then the next clock clears ON and stops T2TMR at 0x00.
3. When T2TMR = T2PR, then the next clock stops T2TMR at 0x00 but does not clear ON.

21.6 Operation Examples

Unless otherwise specified, the following notes apply to the following timing diagrams:

- Both the prescaler and postscaler are set to 1:1 (both the [CKPS](#) and [OUTPS](#) bits in the T2CON register are cleared).
- The diagrams illustrate any clock except $F_{OSC}/4$ and show clock-sync delays of at least two full cycles for both ON and Timer2_ers. When using $F_{OSC}/4$, the clock-sync delay is at least one instruction period for Timer2_ers; ON applies in the next instruction period.
- ON and Timer2_ers are somewhat generalized, and clock-sync delays may produce results that are slightly different than illustrated.
- The PWM Duty Cycle and PWM output are illustrated assuming that the timer is used for the PWM function of the CCP module as described in the “**PWM Overview**” section. The signals are not a part of the Timer2 module.

Related Links

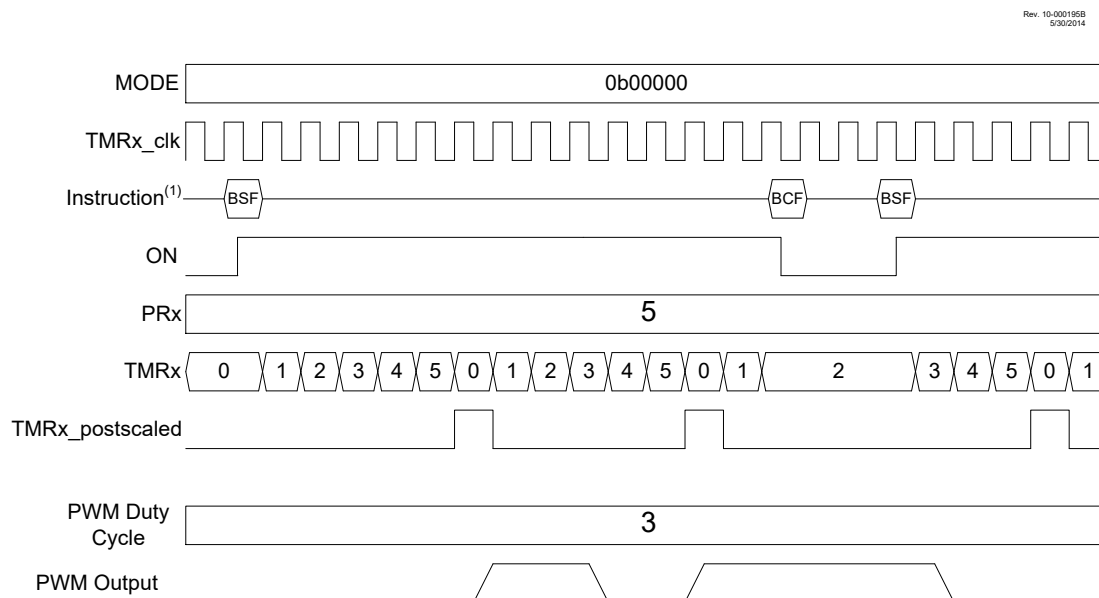
[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

21.6.1 Software Gate Mode

This mode corresponds to legacy Timer2 operation. The timer increments with each clock input when ON = 1 and does not increment when ON = 0. When the TMRx count equals the PRx period count, the timer resets on the next clock and continues counting from 0. Operation with the ON bit software controlled is illustrated in [Figure 21-3](#). With PRx = 5, the counter advances until TMRx = 5, and goes to zero with the next clock.

Figure 21-3. Software Gate Mode Timing Diagram (MODE = 00000)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

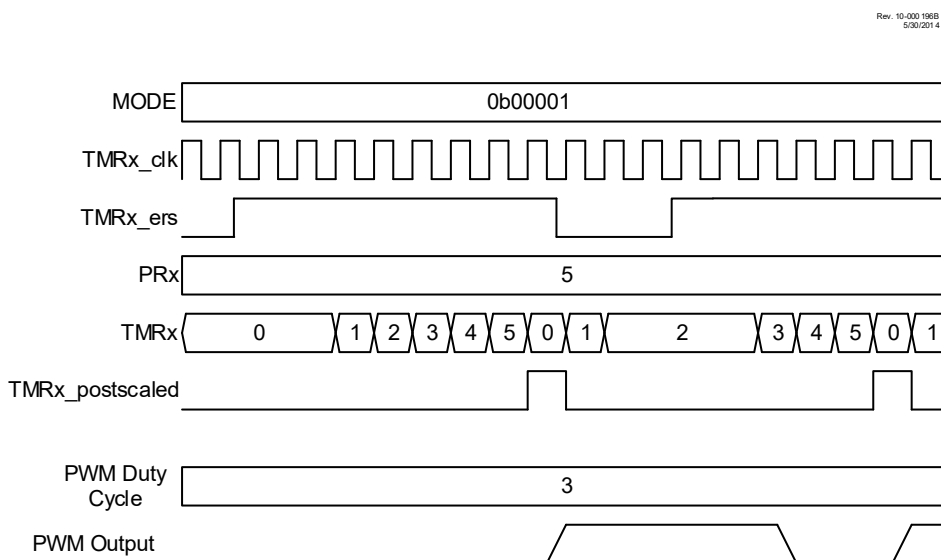
21.6.2 Hardware Gate Mode

The Hardware Gate modes operate the same as the Software Gate mode except the TMRx_ers external signal can also gate the timer. When used with the CCP, the gating extends the PWM period. If the timer is stopped when the PWM output is high, then the duty cycle is also extended.

When MODE[4:0] = 00001 then the timer is stopped when the external signal is high. When MODE[4:0] = 00010, then the timer is stopped when the external signal is low.

Figure 21-4 illustrates the Hardware Gating mode for MODE[4:0] = 00001 in which a high input level starts the counter.

Figure 21-4. Hardware Gate Mode Timing Diagram (MODE = 00001)



Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

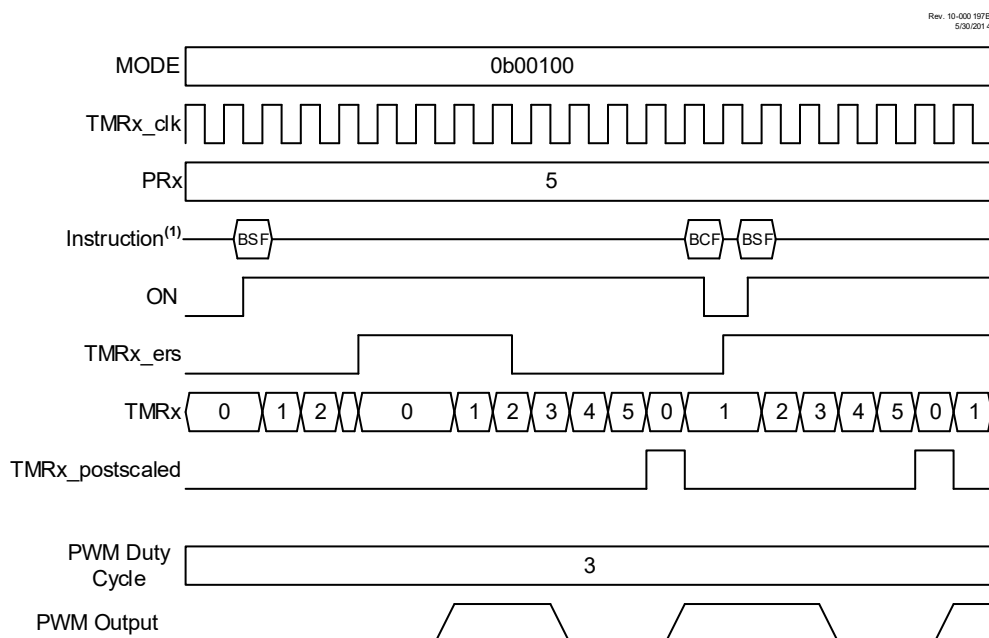
21.6.3 Edge-Triggered Hardware Limit Mode

In Hardware Limit mode, the timer can be reset by the TMRx_ers external signal before the timer reaches the period count. Three types of Resets are possible:

- Reset on rising or falling edge (MODE[4:0] = 00011)
- Reset on rising edge (MODE[4:0] = 00100)
- Reset on falling edge (MODE[4:0] = 00101)

When the timer is used in conjunction with the CCP in PWM mode, then an early Reset shortens the period and restarts the PWM pulse after a two clock delay. Refer to [Figure 21-5](#).

Figure 21-5. Edge-Triggered Hardware Limit Mode Timing Diagram (MODE = 00100)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

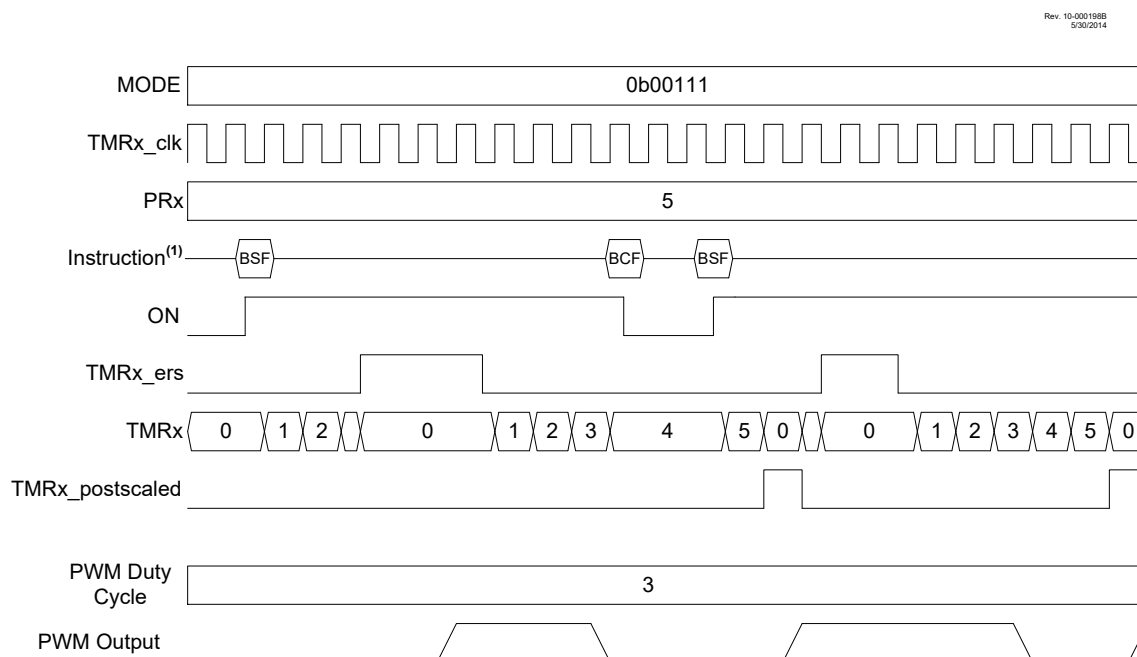
21.6.4 Level-Triggered Hardware Limit Mode

In the Level-Triggered Hardware Limit Timer modes, the counter is reset by high or low levels of the external signal TMRx_ers, as shown in [Figure 21-6](#). Selecting MODE[4:0] = 00110 will cause the timer to reset on a low level external signal. Selecting MODE[4:0] = 00111 will cause the timer to reset on a high level external signal. In the example, the counter is reset while TMRx_ers = 1. ON is controlled by the BSF and BCF instructions. When ON = 0, the external signal is ignored.

When the CCP uses the timer as the PWM time base, then the PWM output will be set high when the timer starts counting and then set low only when the timer count matches the CCPRx value. The timer is reset when either the timer count matches the PRx value or two clock periods after the external Reset signal goes true and stays true.

The timer starts counting, and the PWM output is set high, on either the clock following the PRx match or two clocks after the external Reset signal relinquishes the Reset. The PWM output will remain high until the timer counts up to match the CCPRx pulse-width value. If the external Reset signal goes true while the PWM output is high, then the PWM output will remain high until the Reset signal is released, allowing the timer to count up to match the CCPRx value.

Figure 21-6. Level-Triggered Hardware Limit Mode Timing Diagram (MODE = 00111)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)

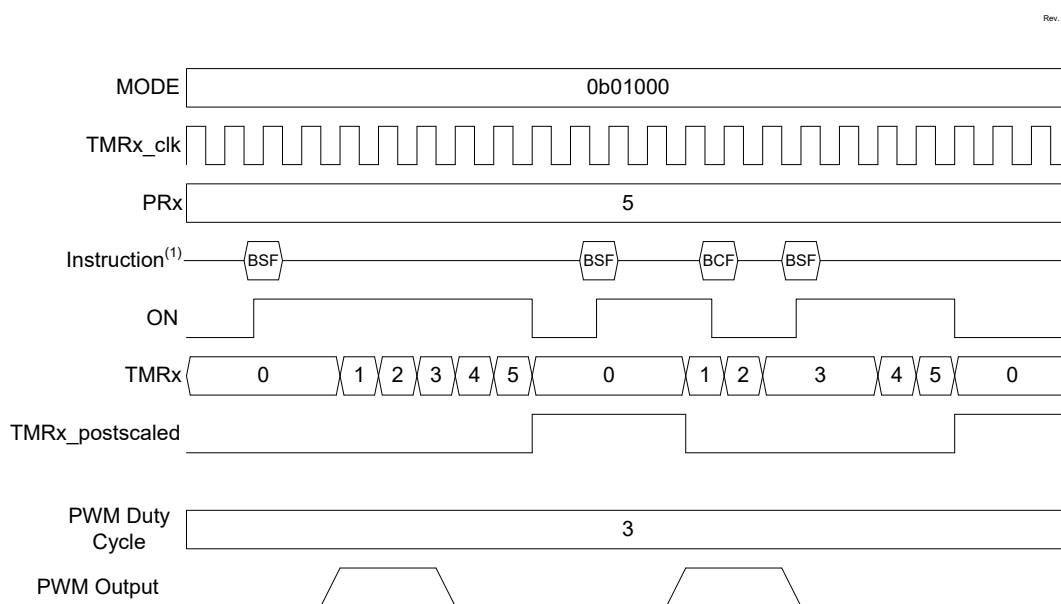
[\(PWM\) Pulse-Width Modulation](#)

21.6.5 Software Start One Shot Mode

In One Shot mode, the timer resets and the ON bit is cleared when the timer value matches the PRx period value. The ON bit must be set by software to start another timer cycle. Setting MODE[4:0] = 01000 selects One Shot mode, which is illustrated in [Figure 21-7](#). In the example, ON is controlled by the BSF and BCF instructions. In the first case, a BSF instruction sets ON and the counter runs to completion and clears ON. In the second case, a BSF instruction starts the cycle, BCF/BSF instructions turn the counter off and on during the cycle, and then it runs to completion.

When One Shot mode is used in conjunction with the CCP PWM operation, the PWM pulse drive starts concurrent with setting the ON bit. Clearing the ON bit while the PWM drive is active will extend the PWM drive. The PWM drive will terminate when the timer value matches the CCPRx pulse-width value. The PWM drive will remain off until software sets the ON bit to start another cycle. If the software clears the ON bit after the CCPRx match, but before the PRx match, then the PWM drive will be extended by the length of time the ON bit remains cleared. Another timing cycle can only be initiated by setting the ON bit after it has been cleared by a PRx period count match.

Figure 21-7. Software Start One Shot Mode Timing Diagram (MODE = 01000)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)
[\(PWM\) Pulse-Width Modulation](#)

21.6.6 Edge-Triggered One Shot Mode

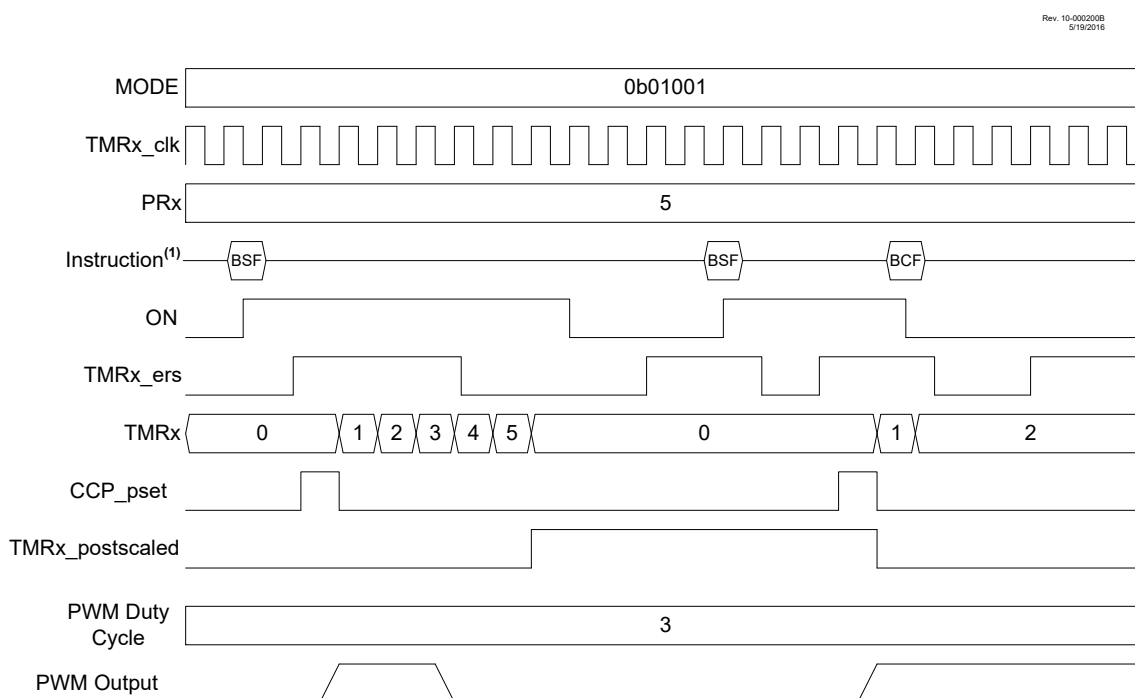
The Edge-Triggered One Shot modes start the timer on an edge from the external signal input, after the ON bit is set, and clear the ON bit when the timer matches the PRx period value. The following edges will start the timer:

- Rising edge (MODE[4:0] = 01001)
- Falling edge (MODE[4:0] = 01010)
- Rising or Falling edge (MODE[4:0] = 01011)

If the timer is halted by clearing the ON bit, then another TMRx_ers edge is required after the ON bit is set to resume counting. [Figure 21-8](#) illustrates operation in the rising edge One Shot mode.

When Edge-Triggered One Shot mode is used in conjunction with the CCP, the edge-trigger will activate the PWM drive, and the PWM drive will deactivate when the timer matches the CCPRx pulse-width value and stay deactivated when the timer halts at the PRx period count match.

Figure 21-8. Edge-Triggered One Shot Mode Timing Diagram (MODE = 01001)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)
(PWM) Pulse-Width Modulation

21.6.7 Edge-Triggered Hardware Limit One Shot Mode

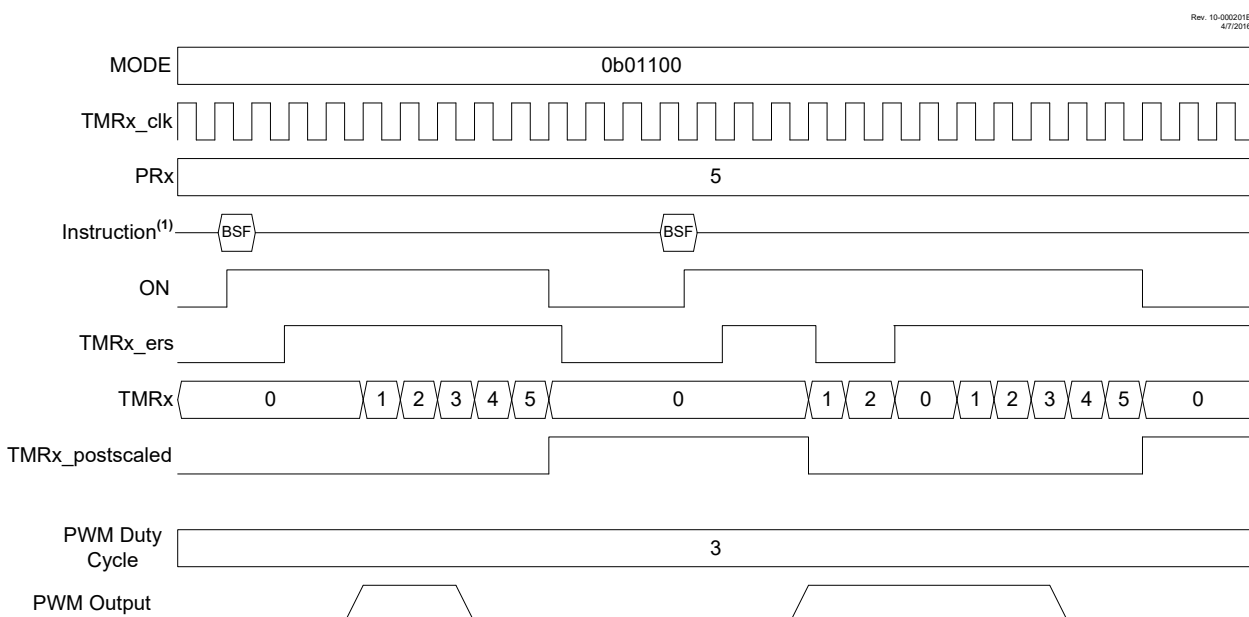
In Edge-Triggered Hardware Limit One Shot modes, the timer starts on the first external signal edge after the ON bit is set and resets on all subsequent edges. Only the first edge after the ON bit is set is needed to start the timer. The counter will resume counting automatically two clocks after all subsequent external Reset edges. Edge triggers are as follows:

- Rising edge start and Reset (MODE[4:0] = 01100)
- Falling edge start and Reset (MODE[4:0] = 01101)

The timer resets and clears the ON bit when the timer value matches the PRx period value. External signal edges will have no effect until after software sets the ON bit. [Figure 21-9](#) illustrates the rising edge hardware limit one-shot operation.

When this mode is used in conjunction with the CCP, the first starting edge trigger and all subsequent Reset edges will activate the PWM drive. The PWM drive will deactivate when the timer matches the CCPRx pulse-width value, and stay deactivated until the timer halts at the PRx period match unless an external signal edge resets the timer before the match occurs.

Figure 21-9. Edge-Triggered Hardware Limit One Shot Mode Timing Diagram (MODE = 01100)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)
(PWM) Pulse-Width Modulation

21.6.8 Level Reset, Edge-Triggered Hardware Limit One Shot Modes

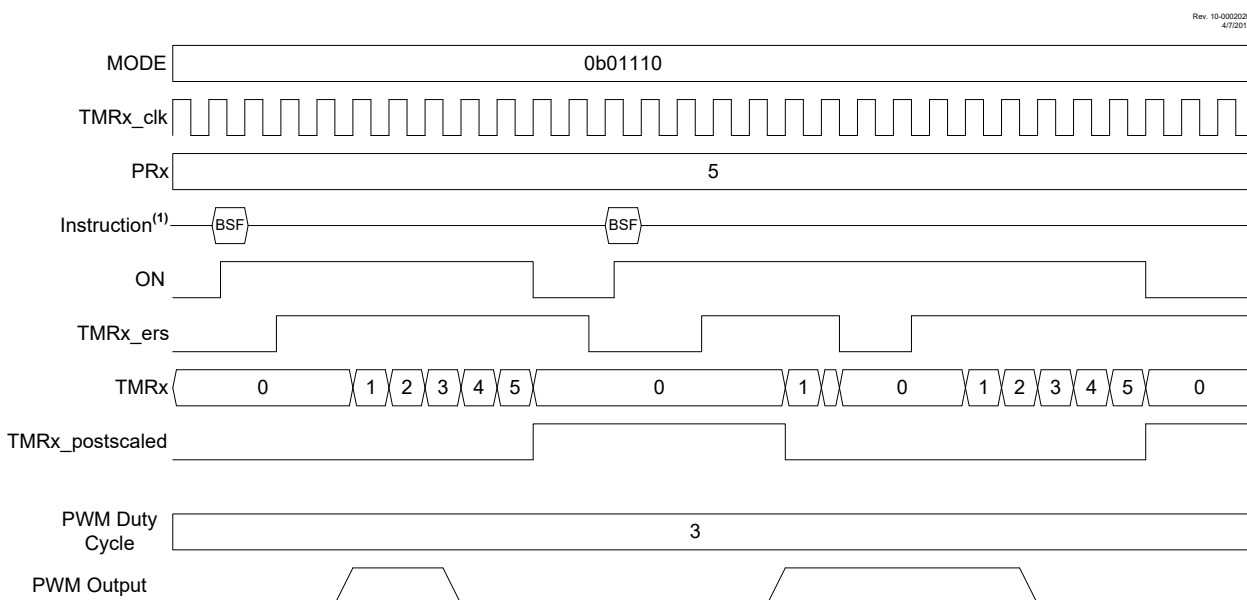
In Level-Triggered One Shot mode, the timer count is reset on the external signal level and starts counting on the rising/falling edge of the transition from the Reset level to the active level while the ON bit is set. Reset levels are selected as follows:

- Low Reset level (MODE[4:0] = 01110)
- High Reset level (MODE[4:0] = 01111)

When the timer count matches the PRx period count, the timer is reset and the ON bit is cleared. When the ON bit is cleared by either a PRx match or by software control, a new external signal edge is required after the ON bit is set to start the counter.

When Level-Triggered Reset One Shot mode is used in conjunction with the CCP PWM operation, the PWM drive goes Active with the external signal edge that starts the timer. The PWM drive goes Inactive when the timer count equals the CCPRx pulse-width count. The PWM drive does not go Active when the timer count clears at the PRx period count match.

Figure 21-10. Low Level Reset, Edge-Triggered Hardware Limit One Shot Mode Timing Diagram (MODE = 01110)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

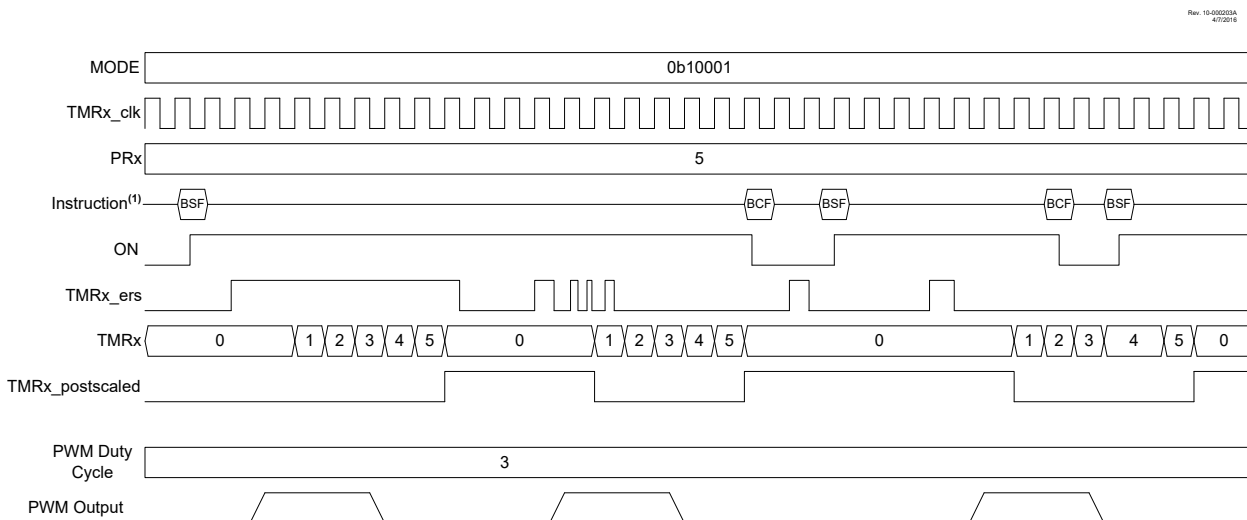
21.6.9 Edge-Triggered Monostable Modes

The Edge-Triggered Monostable modes start the timer on an edge from the external Reset signal input, after the ON bit is set, and stop incrementing the timer when the timer matches the PRx period value. The following edges will start the timer:

- Rising edge (MODE[4:0] = 10001)
- Falling edge (MODE[4:0] = 10010)
- Rising or Falling edge (MODE[4:0] = 10011)

When an Edge-Triggered Monostable mode is used in conjunction with the CCP PWM operation, the PWM drive goes active with the external Reset signal edge that starts the timer, but will not go active when the timer matches the PRx value. While the timer is incrementing, additional edges on the external Reset signal will not affect the CCP PWM.

Figure 21-11. Rising Edge-Triggered Monostable Mode Timing Diagram (MODE = 10001)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)
[\(PWM\) Pulse-Width Modulation](#)

21.6.10 Level-Triggered Hardware Limit One Shot Modes

The Level-Triggered Hardware Limit One Shot modes hold the timer in Reset on an external Reset level, and start counting when both the ON bit is set and the external signal is not at the Reset level. If either the external signal is not in Reset or the ON bit is set, then the other signal being set/made active will start the timer.

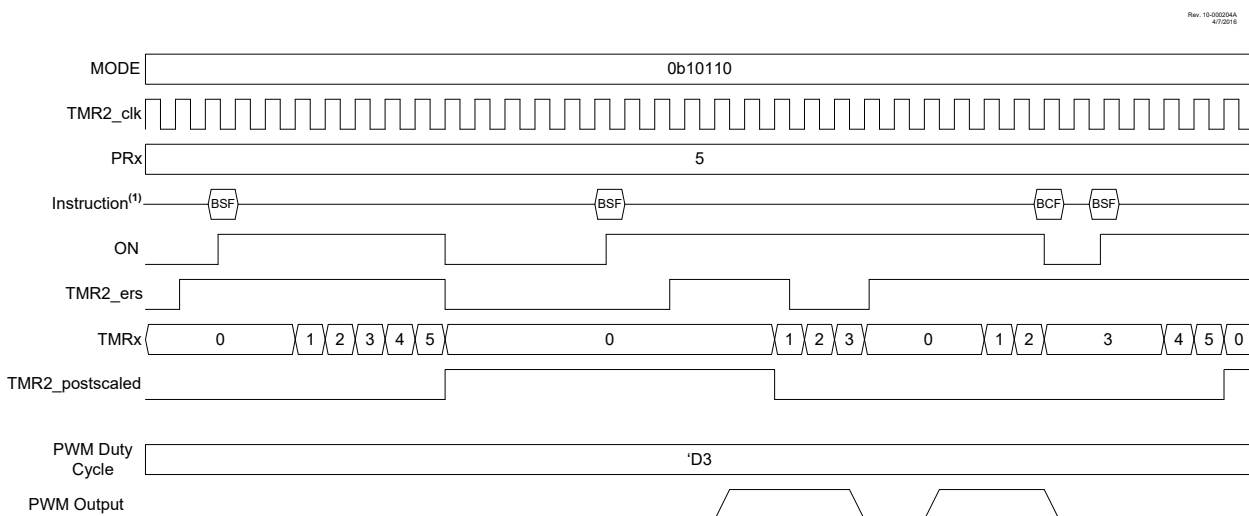
Reset levels are selected as follows:

- Low Reset level (MODE[4:0] = 10110)
- High Reset level (MODE[4:0] = 10111)

When the timer count matches the PRx period count, the timer is reset and the ON bit is cleared. When the ON bit is cleared by either a PRx match or by software control, the timer will stay in Reset until both the ON bit is set and the external signal is not at the Reset level.

When Level-Triggered Hardware Limit One Shot modes are used in conjunction with the CCP PWM operation, the PWM drive goes Active with either the external signal edge or the setting of the ON bit, whichever of the two starts the timer.

Figure 21-12. Level-Triggered Hardware Limit One Shot Mode Timing Diagram (MODE = 10110)



Note:

1. BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

Related Links

[PWM Overview](#)

[\(PWM\) Pulse-Width Modulation](#)

21.7 Timer2 Operation During Sleep

When **PSYNC** = 1, Timer2 cannot be operated while the processor is in Sleep mode. The contents of the T2TMR and T2PR registers will remain unchanged while processor is in Sleep mode.

When **PSYNC** = 0, Timer2 will operate in Sleep as long as the clock source selected is also still running. If any internal oscillator is selected as the clock source, it will stay active during Sleep mode.

21.8 Register Summary - Timer2

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|------------|-----------|-------|-----------|------------|---|---|---|
| 0x00 ... 0x0FAD | Reserved | | | | | | | | | |
| 0x0FAE | T6TMR | 7:0 | TxTMR[7:0] | | | | | | | |
| 0x0FAF | T6PR | 7:0 | TxPR[7:0] | | | | | | | |
| 0x0FB0 | T6CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | |
| 0x0FB1 | T6HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | |
| 0x0FB2 | T6CLKCON | 7:0 | | | | CS[4:0] | | | | |
| 0x0FB3 | T6RST | 7:0 | | | | RSEL[4:0] | | | | |
| 0x0FB4 | T4TMR | 7:0 | TxTMR[7:0] | | | | | | | |
| 0x0FB5 | T4PR | 7:0 | TxPR[7:0] | | | | | | | |
| 0x0FB6 | T4CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | |
| 0x0FB7 | T4HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | |
| 0x0FB8 | T4CLKCON | 7:0 | | | | CS[4:0] | | | | |
| 0x0FB9 | T4RST | 7:0 | | | | RSEL[4:0] | | | | |
| 0x0FBA | T2TMR | 7:0 | TxTMR[7:0] | | | | | | | |
| 0x0FBB | T2PR | 7:0 | TxPR[7:0] | | | | | | | |
| 0x0FBC | T2CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | |
| 0x0FBD | T2HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | |
| 0x0FBE | T2CLKCON | 7:0 | | | | CS[4:0] | | | | |
| 0x0FBF | T2RST | 7:0 | | | | RSEL[4:0] | | | | |

21.9 Register Definitions: Timer2 Control

Long bit name prefixes for the Timer2 peripherals are shown in the table below. Refer to the “**Long Bit Names**” section for more information.

Table 21-2. Timer2 long bit name prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| Timer2 | T2 |
| Timer4 | T4 |
| Timer6 | T6 |

NOTICE

References to module Timer2 apply to all the even numbered timers on this device. (Timer2, Timer4, etc.)

Related Links

[Long Bit Names](#)

21.9.1 TxTMR

Name: TxTMR
Address: 0xFBA,0xFB4,0xFAE

Timer Counter Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | TxTMR[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – TxTMR[7:0] Timerx Counter bits

21.9.2 TxPR

Name: TxPR
Address: 0xFBB,0xFB5,0xFAF

Timer Period Register

| | | | | | | | | |
|--------|-----------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TxPR[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 7:0 – TxPR[7:0] Timer Period Register bits

| Value | Description |
|-----------------------------|---|
| 1111 1111 – 0000 0000 | The timer restarts at '0' when TxTMR reaches the TxPR value |

21.9.3 TxCON

Name: TxCON
Address: 0xFBC, 0xFB6, 0xFB0

Timerx Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-----------|-----|-----|------------|-----|-----|-----|
| | ON | CKPS[2:0] | | | OUTPS[3:0] | | | |
| Access | R/W/HC | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – ON

Timer On bit⁽¹⁾

| Value | Description |
|-------|---|
| 1 | Timer is on |
| 0 | Timer is off: all counters and state machines are reset |

Bits 6:4 – CKPS[2:0] Timer Clock Prescale Select bits

| Value | Description |
|-------|-----------------|
| 111 | 1:128 Prescaler |
| 110 | 1:64 Prescaler |
| 101 | 1:32 Prescaler |
| 100 | 1:16 Prescaler |
| 011 | 1:8 Prescaler |
| 010 | 1:4 Prescaler |
| 001 | 1:2 Prescaler |
| 000 | 1:1 Prescaler |

Bits 3:0 – OUTPS[3:0] Timer Output Postscaler Select bits

| Value | Description |
|-------|-----------------|
| 1111 | 1:16 Postscaler |
| 1110 | 1:15 Postscaler |
| 1101 | 1:14 Postscaler |
| 1100 | 1:13 Postscaler |
| 1011 | 1:12 Postscaler |
| 1010 | 1:11 Postscaler |
| 1001 | 1:10 Postscaler |
| 1000 | 1:9 Postscaler |
| 0111 | 1:8 Postscaler |
| 0110 | 1:7 Postscaler |
| 0101 | 1:6 Postscaler |
| 0100 | 1:5 Postscaler |
| 0011 | 1:4 Postscaler |
| 0010 | 1:3 Postscaler |
| 0001 | 1:2 Postscaler |
| 0000 | 1:1 Postscaler |

Note:

1. In certain modes, the ON bit will be auto-cleared by hardware. See [Table 21-1](#).

21.9.4 TxHLT

Name: TxHLT
Address: 0xFBD, 0xFB7, 0xFB1

Timer Hardware Limit Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|------|-------|-----------|-----|-----|-----|-----|
| | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – PSYNC

Timer Prescaler Synchronization Enable bit^(1, 2)

| Value | Description |
|-------|---|
| 1 | Timer Prescaler Output is synchronized to $F_{OSC}/4$ |
| 0 | Timer Prescaler Output is not synchronized to $F_{OSC}/4$ |

Bit 6 – CPOL

Timer Clock Polarity Selection bit⁽³⁾

| Value | Description |
|-------|--|
| 1 | Falling edge of input clock clocks timer/prescaler |
| 0 | Rising edge of input clock clocks timer/prescaler |

Bit 5 – CSYNC

Timer Clock Synchronization Enable bit^(4, 5)

| Value | Description |
|-------|---|
| 1 | The ON bit is synchronized to timer clock input |
| 0 | The ON bit is not synchronized to timer clock input |

Bits 4:0 – MODE[4:0]

Timer Control Mode Selection bits^(6, 7)

| Value | Description |
|----------------|--------------------------------|
| 00000 to 11111 | See Table 21-1 |

Notes:

- Setting this bit ensures that reading TxTMR will return a valid data value.
- When this bit is '1', Timer cannot operate in Sleep mode.
- CKPOL must not be changed while ON = 1.
- Setting this bit ensures glitch-free operation when the ON bit is enabled or disabled.
- When this bit is set, the timer operation will be delayed by two input clocks after the ON bit is set.
- Unless otherwise indicated, all modes start upon ON = 1 and stop upon ON = 0 (stops occur without affecting the value of TxTMR).
- When TxTMR = TxPR, the next clock clears TxTMR, regardless of the operating mode.

21.9.5 TxCLKCON

Name: TxCLKCON
Address: 0xFBE,0xFB8,0xFB2

Timer Clock Source Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---------|-----|-----|-----|-----|
| | | | | CS[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – CS[4:0] Timer Clock Source Selection bits

Table 21-3. Clock Source Selection

| CS[4:0] | Clock Source | | |
|-------------|-------------------------|-------------------------|-------------------------|
| | Timer2 | Timer4 | Timer6 |
| 11111–11000 | Reserved | Reserved | Reserved |
| 10111 | CLC8_out | CLC8_out | CLC8_out |
| 10110 | CLC7_out | CLC7_out | CLC7_out |
| 10101 | CLC6_out | CLC6_out | CLC6_out |
| 10100 | CLC5_out | CLC5_out | CLC5_out |
| 10011 | CLC4_out | CLC4_out | CLC4_out |
| 10010 | CLC3_out | CLC3_out | CLC3_out |
| 10001 | CLC2_out | CLC2_out | CLC2_out |
| 10000 | CLC1_out | CLC1_out | CLC1_out |
| 01111–01001 | Reserved | Reserved | Reserved |
| 01000 | ZCD_OUT | ZCD_OUT | ZCD_OUT |
| 00111 | CLKREF_OUT | CLKREF_OUT | CLKREF_OUT |
| 00110 | SOSC | SOSC | SOSC |
| 00101 | MFINTOSC (31 kHz) | MFINTOSC (31 kHz) | MFINTOSC (31 kHz) |
| 00100 | LFINTOSC | LFINTOSC | LFINTOSC |
| 00011 | HFINTOSC | HFINTOSC | HFINTOSC |
| 00010 | Fosc | Fosc | Fosc |
| 00001 | Fosc/4 | Fosc/4 | Fosc/4 |
| 00000 | Pin selected by T2INPPS | Pin selected by T4INPPS | Pin selected by T6INPPS |

| Value | Description |
|-------|--|
| n | See the “Clock Source Selection” table |

21.9.6 TxRST

Name: TxRST
Address: 0xFBFB, 0xFB9, 0xFB3

Timer External Reset Signal Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|-----------|-----|-----|-----|-----|
| | | | | RSEL[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – RSEL[4:0]
External Reset Source Selection Bits

Table 21-4. External Reset Sources

| RSEL[4:0] | Reset Source | | |
|-------------|-------------------------|-------------------------|-------------------------|
| | TMR2 | TMR4 | TMR6 |
| 11000–11111 | Reserved | Reserved | Reserved |
| 10111 | CLC8_out | CLC8_out | CLC8_out |
| 10110 | CLC7_out | CLC7_out | CLC7_out |
| 10101 | CLC6_out | CLC6_out | CLC6_out |
| 10100 | CLC5_out | CLC5_out | CLC5_out |
| 10011 | CLC4_out | CLC4_out | CLC4_out |
| 10010 | CLC3_out | CLC3_out | CLC3_out |
| 10001 | CLC2_out | CLC2_out | CLC2_out |
| 10000 | CLC1_out | CLC1_out | CLC1_out |
| 01111 | EUSART2 TX/CK | EUSART2 TX/CK | EUSART2 TX/CK |
| 01110 | EUSART2 DT | EUSART2 DT | EUSART2 DT |
| 01101 | EUSART1 TX/CK | EUSART1 TX/CK | EUSART1 TX/CK |
| 01100 | EUSART1 DT | EUSART1 DT | EUSART1 DT |
| 01011 | Reserved | Reserved | Reserved |
| 01010 | ZCD_OUT | ZCD_OUT | ZCD_OUT |
| 01001 | CMP2OUT | CMP2OUT | CMP2OUT |
| 01000 | CMP1OUT | CMP1OUT | CMP1OUT |
| 00111 | PWM4OUT | PWM4OUT | PWM4OUT |
| 00110 | PWM3OUT | PWM3OUT | PWM3OUT |
| 00101 | CCP2OUT | CCP2OUT | CCP2OUT |
| 00100 | CCP1OUT | CCP1OUT | CCP1OUT |
| 00011 | TMR6 post-scaled | TMR6 post-scaled | Reserved |
| 00010 | TMR4 post-scaled | Reserved | TMR4 post-scaled |
| 00001 | Reserved | TMR2 post-scaled | TMR2 post-scaled |
| 00000 | Pin selected by T2INPPS | Pin selected by T4INPPS | Pin selected by T6INPPS |

| Value | Description |
|-------|--|
| n | See the External Reset Sources table |

22. Capture/Compare/PWM Module

The Capture/Compare/PWM module is a peripheral that allows the user to time and control different events, and to generate Pulse-Width Modulation (PWM) signals. In Capture mode, the peripheral allows the timing of the duration of an event. The Compare mode allows the user to trigger an external event when a predetermined amount of time has expired. The PWM mode can generate Pulse-Width Modulated signals of varying frequency and duty cycle.

This family of devices contains two standard Capture/Compare/PWM modules (CCP1 and CCP2). Each individual CCP module can select the timer source that controls the module. Each module has an independent timer selection which can be accessed using the CxTSEL bits in the [CCPTMRS](#) register. The default timer selection is TMR1 when using Capture/Compare mode and T2TMR when using PWM mode in the CCPx module.

It should be noted that the Capture/Compare mode operation is described with respect to TMR1 and the PWM mode operation is described with respect to T2TMR in the following sections.

The Capture and Compare functions are identical for all CCP modules.



Important:

1. In devices with more than one CCP module, it is very important to pay close attention to the register names used. A number placed after the module acronym is used to distinguish between separate modules. For example, the CCP1CON and CCP2CON control the same operational aspects of two completely different CCP modules.
2. Throughout this section, generic references to a CCP module in any of its operating modes may be interpreted as being equally applicable to CCPx module. Register names, module signals, I/O pins, and bit names may use the generic designator 'x' to indicate the use of a numeral to distinguish a particular module, when required.

22.1 CCP Module Configuration

Each Capture/Compare/PWM module is associated with a control register ([CCPxCON](#)), a capture input selection register ([CCPxCAP](#)) and a data register ([CCPRx](#)). The data register, in turn, is comprised of two 8-bit registers: CCPRxL (low byte) and CCPRxH (high byte).

22.1.1 CCP Modules and Timer Resources

The CCP modules utilize Timers 1 through 6 that vary with the selected mode. Various timers are available to the CCP modules in Capture, Compare or PWM modes, as shown in the table below.

Table 22-1. CCP Mode - Timer Resources

| CCP Mode | Timer Resource |
|----------|--------------------------|
| Capture | Timer1, Timer3 or Timer5 |
| Compare | |
| PWM | Timer2, Timer4 or Timer6 |

The assignment of a particular timer to a module is determined by the timer to CCP enable bits in the [CCPTMRS](#) register. All of the modules may be active at once and may share the same timer resource if they are configured to operate in the same mode (Capture/Compare or PWM) at the same time.

22.1.2 Open-Drain Output Option

When operating in Output mode (the Compare or PWM modes), the drivers for the CCPx pins can be optionally configured as open-drain outputs. This feature allows the voltage level on the pin to be pulled to a higher level through an external pull-up resistor and allows the output to communicate with external circuits without the need for additional level shifters.

22.2 Capture Mode

Capture mode uses the 16-bit odd numbered Timer resources (Timer1, Timer3, etc.). When an event occurs on the capture source, the 16-bit CCPRx register captures and stores the 16-bit value of the TMRx register. An event is defined as one of the following and is configured by the **MODE** bits:

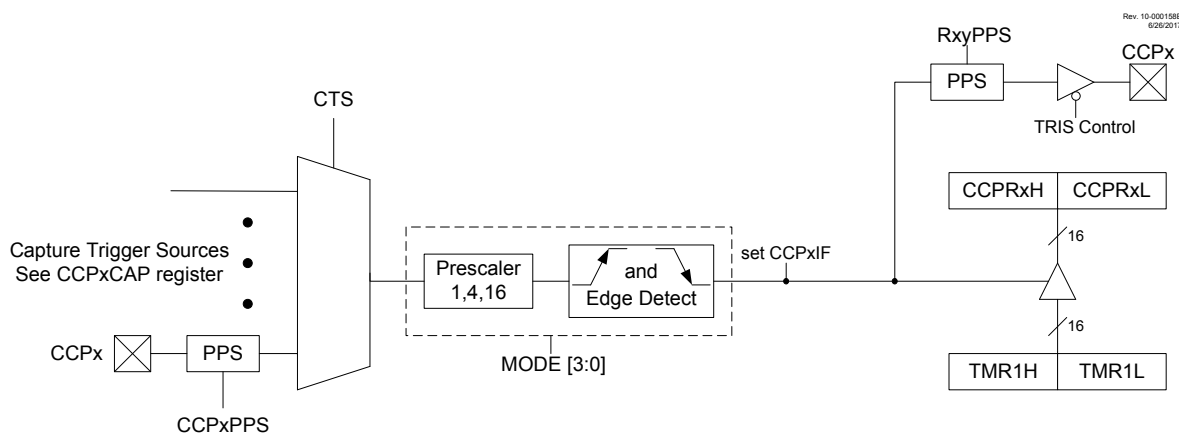
- Every falling edge of CCPx input
- Every rising edge of CCPx input
- Every 4th rising edge of CCPx input
- Every 16th rising edge of CCPx input
- Every edge of CCPx input (rising or falling)

When a capture is made, the Interrupt Request Flag bit CCPxIF of the PIR6 register is set. The interrupt flag must be cleared in software. If another capture occurs before the value in the CCPRx register is read, the old captured value is overwritten by the new captured value.

➔ Important: If an event occurs during a 2-byte read, the high and low-byte data will be from different events. It is recommended while reading the CCPRxH:CCPRxL register pair to either disable the module or read the register pair twice for data integrity.


The following figure shows a simplified diagram of the capture operation.

Figure 22-1. Capture Mode Operation Block Diagram



22.2.1 Capture Sources

In Capture mode, the CCPx pin may be configured as an input by setting the associated TRIS control bit.

 **Important:** If the CCPx pin is configured as an output, a write to the port can cause a Capture condition.

The capture source is selected by configuring the **CTS** bits as shown in the following table:

Table 22-2. Capture Trigger Sources

| CTS | Source |
|-----------|-------------------------|
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0100-0111 | Reserved |
| 0011 | IOC Interrupt |
| 0010 | CMP2_output |
| 0001 | CMP1_output |
| 0000 | Pin selected by CCPxPPS |

22.2.2 Timer1 Mode Resource

Timer1 must be running in Timer mode or Synchronized Counter mode for the CCP module to use the capture feature. In Asynchronous Counter mode, the capture operation may not work.


See the “**Timer1 Module with Gate Control**” section for more information on configuring Timer1.

Related Links

[TMR1 - Timer1 Module with Gate Control](#)

22.2.3 Software Interrupt Mode

When the Capture mode is changed, a false capture interrupt may be generated. The user must keep the CCPxIE Interrupt Priority bit of the PIE6 register clear to avoid false interrupts. Additionally, the user must clear the CCPxIF Interrupt Flag bit of the PIR6 register following any change in Operating mode.

 **Important:** Clocking Timer1 from the system clock (F_{OSC}) may not be used in Capture mode. For Capture mode to recognize the trigger event on the CCPx pin, Timer1 must be clocked from the instruction clock ($F_{OSC}/4$) or from an external clock source.

22.2.4 CCP Prescaler

There are four prescaler settings specified by the **MODE** bits. Whenever the CCP module is turned off, or the CCP module is not in Capture mode, the prescaler counter is cleared. Any Reset will clear the prescaler counter.

Switching from one capture prescaler to another does not clear the prescaler and may generate a false interrupt. To avoid this unexpected operation, turn the module off by clearing the CCPxCON register before changing the prescaler. The example below demonstrates the code to perform this function.

Example 22-1. Changing Between Capture Prescalers

```
BANKSEL CCP1CON      ; (only needed when CCP1CON is not in ACCESS space)
CLRF   CCP1CON        ; Turn CCP module off
MOVLW  NEW_CAPT_PS    ; CCP ON and Prescaler select → W
MOVWF  CCP1CON        ; Load CCP1CON with this value
```

22.2.5 Capture During Sleep

Capture mode depends upon the Timer1 module for proper operation. There are two options for driving the Timer1 module in Capture mode. It can be driven by the instruction clock ($F_{OSC}/4$), or by an external clock source.

When Timer1 is clocked by $F_{OSC}/4$, Timer1 will not increment during Sleep. When the device wakes from Sleep, Timer1 will continue from its previous state.

Capture mode will operate during Sleep when Timer1 is clocked by an external clock source.

22.3 Compare Mode

The Compare mode function described in this section is available and identical for all CCP modules.

Compare mode uses the 16-bit odd numbered Timer resources (Timer1, Timer3, etc.). The 16-bit value of the CCPRx register is constantly compared against the 16-bit value of the TMRx register. When a match occurs, one of the following events can occur:

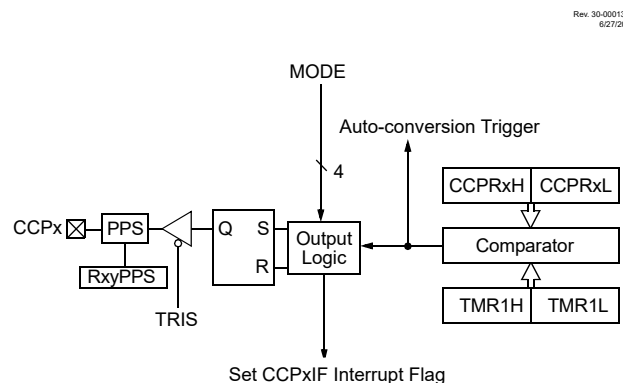
- Toggle the CCPx output and clear TMRx
- Toggle the CCPx output without clearing TMRx
- Set the CCPx output
- Clear the CCPx output
- Pulse output
- Pulse output and clear TMRx

The action on the pin is based on the value of the **MODE** control bits. At the same time, the interrupt flag CCPxIF bit is set, and an ADC conversion can be triggered, if selected.

All Compare modes can generate an interrupt and trigger an ADC conversion. When **MODE** = '0001' or '1011', the CCP resets the TMRx register.

The following figure shows a simplified diagram of the compare operation.


Figure 22-2. Compare Mode Operation Block Diagram



22.3.1 CCPx Pin Configuration

The software must configure the CCPx pin as an output by clearing the associated TRIS bit and defining the appropriate output pin through the RxyPPS registers. See the **“Peripheral Pin Select (PPS) Module”** section for more details.

The CCP output can also be used as an input for other peripherals.

 **Important:** Clearing the CCPxCON register will force the CCPx compare output latch to the default low level. This is not the PORT I/O data latch.


Related Links

[PPS - Peripheral Pin Select Module](#)

22.3.2 Timer1 Mode Resource

In Compare mode, Timer1 must be running in either Timer mode or Synchronized Counter mode. The compare operation may not work in Asynchronous Counter mode.


See the **“Timer1 Module with Gate Control”** section for more information on configuring Timer1.

 **Important:** Clocking Timer1 from the system clock (F_{OSC}) may not be used in Compare mode. For Compare mode to generate the trigger event on the CCPx pin, Timer1 must be clocked from the instruction clock ($F_{OSC}/4$) or from an external clock source.

22.3.3 Auto-Conversion Trigger

All CCPx modes set the CCP Interrupt Flag (CCPxIF). When this flag is set and a match occurs, an auto-conversion trigger can take place if the CCP module is selected as the conversion trigger source.

Refer to the **“Auto-Conversion Trigger”** section for more information.

 **Important:** Removing the Match condition by changing the contents of the CCPRxH and CCPRxL register pair, between the clock edge that generates the auto-conversion trigger and the clock edge that generates the Timer1 Reset, will preclude the Reset from occurring.

Related Links

[Auto-Conversion Trigger](#)

22.3.4 Compare During Sleep

Since F_{OSC} is shut down during Sleep mode, the Compare mode will not function properly during Sleep, unless the timer is running. The device will wake on interrupt (if enabled).

22.4 PWM Overview

Pulse-Width Modulation (PWM) is a scheme that provides power to a load by switching quickly between fully ON and fully OFF states. The PWM signal resembles a square wave where the high portion of the signal is considered the ON state and the low portion of the signal is considered the OFF state. The high portion, also known as the pulse width, can vary in time and is defined in steps. A larger number of steps applied, which lengthens the pulse width, also supplies more power to the load. Lowering the number of steps applied, which shortens the pulse width, supplies less power.

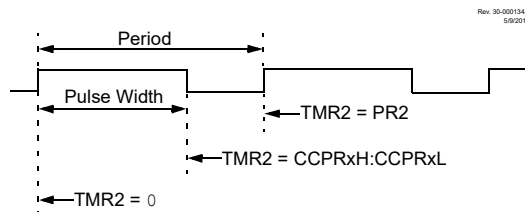
The PWM period is defined as the duration of one complete cycle or the total amount of ON and OFF time combined.

PWM resolution defines the maximum number of steps that can be present in a single PWM period. A higher resolution allows for more precise control of the pulse-width time and in turn the power that is applied to the load.

The term duty cycle describes the proportion of the ON time to the OFF time and is expressed in percentages, where 0% is fully OFF and 100% is fully ON. A lower duty cycle corresponds to less power applied and a higher duty cycle corresponds to more power applied.

The figure below shows a typical waveform of the PWM signal.

Figure 22-3. CCP PWM Output Signal



22.4.1 Standard PWM Operation

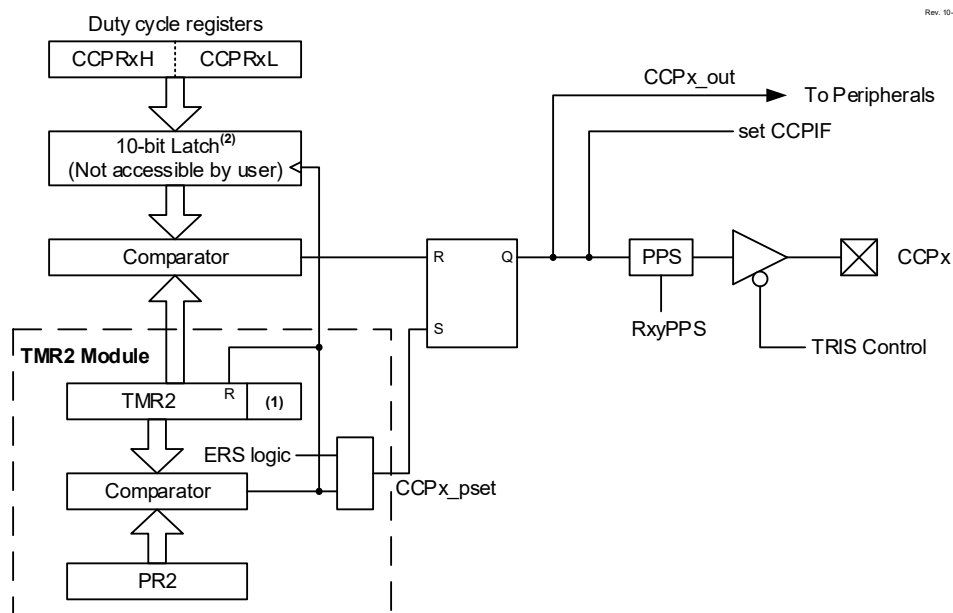
The standard PWM function described in this section is available and identical for all CCP modules.

The standard PWM mode generates a Pulse-Width Modulation (PWM) signal on the CCPx pin with up to ten bits of resolution. The period, duty cycle, and resolution are controlled by the following registers:

- Even numbered TxPR registers (T2PR, T4PR, etc.)
- Even numbered TxCON registers (T2CON, T4CON, etc.)
- 16-bit CCPRx registers
- CCPxCON registers

It is required to have $F_{OSC}/4$ as the clock input to TxTMR for correct PWM operation. The following figure shows a simplified block diagram of the PWM operation.

Figure 22-4. Simplified PWM Block Diagram



Notes:

1. 8-bit timer is concatenated with two bits generated by F_{OSC} or two bits of the internal prescaler to create 10-bit time base.
2. The alignment of the ten bits from the CCPRx register is determined by the CCPxFMT bit.




Important: The corresponding TRIS bit must be cleared to enable the PWM output on the CCPx pin.

22.4.2 Setup for PWM Operation

Take these steps when configuring the CCP module for standard PWM operation:

1. Use the desired output pin RxyPPS control to select CCPx as the source and disable the CCPx pin output driver by setting the associated TRIS bit.
2. Load the T2PR register with the PWM period value.
3. Configure the CCP module for the PWM mode by loading the CCPxCON register with the appropriate values.
4. Load the CCPRx register with the PWM duty cycle value and configure the FMT bit to set the proper register alignment.
5. Configure and start Timer2:
 - Clear the TMR2IF interrupt flag bit of the PIR4 register. See the Note below.
 - Select the timer clock source to be $F_{OSC}/4$ using the TxCLKCON register. This is required for correct operation of the PWM module.
 - Configure the T2CKPS bits of the T2CON register with the timer prescale value
 - Enable the timer by setting the T2ON bit
6. Enable the PWM output pin:

- Wait until the timer overflows and the TMR2IF bit of the PIR4 register is set. See the Note below.
- Enable the CCPx pin output driver by clearing the associated TRIS bit

 **Important:** To send a complete duty cycle and period on the first PWM output, the above steps must be included in the setup sequence. If it is not critical to start with a complete PWM signal on the first output, then step 6 may be ignored.

Related Links

[TxCON](#)

TxCON

22.4.3 Timer2 Timer Resource

The PWM standard mode makes use of the 8-bit Timer2 timer resources to specify the PWM period.

22.4.4 PWM Period

The PWM period is specified by the T2PR register of Timer2. The PWM period can be calculated using the formula in the equation below.


Equation 22-1. PWM Period

$$PWMPeriod = [(T2PR + 1)] \cdot 4 \cdot T_{OSC} \cdot (TMR2PrescaleValue)$$

where $T_{OSC} = 1/F_{OSC}$

When T2TMR is equal to T2PR, the following three events occur on the next increment cycle:

- T2TMR is cleared
- The CCPx pin is set (Exception: If the PWM duty cycle = 0%, the pin will not be set)
- The PWM duty cycle is transferred from the CCPRx register into a 10-bit buffer

 **Important:** The Timer postscaler (see the “**Timer2 Interrupt**” section) is not used in the determination of the PWM frequency.

Related Links

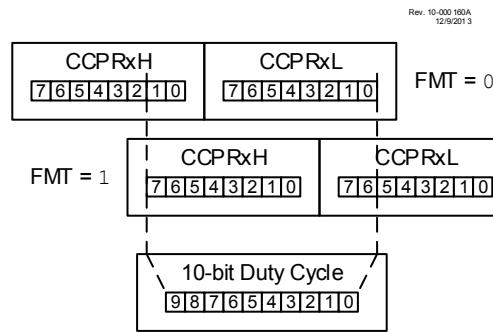
[Timer2 Interrupt](#)

22.4.5 PWM Duty Cycle

The PWM duty cycle is specified by writing a 10-bit value to the CCPRx register. The alignment of the 10-bit value is determined by the FMT bit (see [Figure 22-5](#)). The CCPRx register can be written to at any time. However, the duty cycle value is not latched into the 10-bit buffer until after a match between T2PR and T2TMR.

The equations below are used to calculate the PWM pulse width and the PWM duty cycle ratio.

Figure 22-5. PWM 10-Bit Alignment



Equation 22-2. Pulse Width

$$\text{Pulse Width} = (\text{CCPRxH:CCPRxL register value}) \cdot T_{OSC} \cdot (\text{TMR2 Prescale Value})$$

Equation 22-3. Duty Cycle

$$\text{DutyCycleRatio} = \frac{(\text{CCPRxH:CCPRxL register value})}{4(\text{T2PR} + 1)}$$

The CCPRx register is used to double buffer the PWM duty cycle. This double buffering is essential for glitchless PWM operation.

The 8-bit timer T2TMR register is concatenated with either the 2-bit internal system clock (F_{OSC}), or two bits of the prescaler, to create the 10-bit time base. The system clock is used if the Timer2 prescaler is set to 1:1.

When the 10-bit time base matches the CCPRx register, then the CCPx pin is cleared (see [Figure 22-4](#)).

22.4.6 PWM Resolution

The resolution determines the number of available duty cycles for a given period. For example, a 10-bit resolution will result in 1024 discrete duty cycles, whereas an 8-bit resolution will result in 256 discrete duty cycles.

The maximum PWM resolution is ten bits when T2PR is 255. The resolution is a function of the T2PR register value as shown below.

Equation 22-4. PWM Resolution

$$\text{Resolution} = \frac{\log[4(\text{T2PR} + 1)]}{\log(2)} \text{bits}$$



Important: If the pulse-width value is greater than the period, the assigned PWM pin(s) will remain unchanged.

Table 22-3. Example PWM Frequencies and Resolutions ($F_{OSC} = 20 \text{ MHz}$)

| PWM Frequency | 1.22 kHz | 4.88 kHz | 19.53 kHz | 78.12 kHz | 156.3 kHz | 208.3 kHz |
|---------------------------|----------|----------|-----------|-----------|-----------|-----------|
| Timer Prescale | 16 | 4 | 1 | 1 | 1 | 1 |
| T2PR Value | 0xFF | 0xFF | 0xFF | 0x3F | 0x1F | 0x17 |
| Maximum Resolution (bits) | 10 | 10 | 10 | 8 | 7 | 6.6 |

Table 22-4. Example PWM Frequencies and Resolutions ($F_{OSC} = 8 \text{ MHz}$)

| PWM Frequency | 1.22 kHz | 4.90 kHz | 19.61 kHz | 76.92 kHz | 153.85 kHz | 200.0 kHz |
|---------------------------|----------|----------|-----------|-----------|------------|-----------|
| Timer Prescale | 16 | 4 | 1 | 1 | 1 | 1 |
| T2PR Value | 0x65 | 0x65 | 0x65 | 0x19 | 0x0C | 0x09 |
| Maximum Resolution (bits) | 8 | 8 | 8 | 6 | 5 | 5 |

22.4.7 Operation in Sleep Mode

In Sleep mode, the T2TMR register will not increment and the state of the module will not change. If the CCPx pin is driving a value, it will continue to drive that value. When the device wakes up, T2TMR will continue from the previous state.

22.4.8 Changes in System Clock Frequency

The PWM frequency is derived from the system clock frequency. Any changes in the system clock frequency will result in changes to the PWM frequency. See the “**OSC - Oscillator**” section for additional details.

Related Links

[OSC - Oscillator Module](#)

22.4.9 Effects of Reset

Any Reset will force all ports to Input mode and the CCP registers to their Reset states.

22.5 Register Summary - CCP Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|-------------|---|-------------|-----|-------------|---|-------------|---|
| 0x00 ... 0x0FA4 | Reserved | | | | | | | | | |
| 0x0FA5 | CCPR2 | 7:0 | CCPR[7:0] | | | | | | | |
| | | 15:8 | CCPR[15:8] | | | | | | | |
| 0x0FA7 | CCP2CON | 7:0 | EN | | OUT | FMT | MODE[3:0] | | | |
| 0x0FA8 | CCP2CAP | 7:0 | | | | | CTS[3:0] | | | |
| 0x0FA9 | CCPR1 | 7:0 | CCPR[7:0] | | | | | | | |
| | | 15:8 | CCPR[15:8] | | | | | | | |
| 0x0FAB | CCP1CON | 7:0 | EN | | OUT | FMT | MODE[3:0] | | | |
| 0x0FAC | CCP1CAP | 7:0 | | | | | CTS[3:0] | | | |
| 0x0FAD | CCPTMRS | 7:0 | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | |

22.6 Register Definitions: CCP Control

Long bit name prefixes for the CCP peripherals are shown in the following table. Refer to the “**Long Bit Names**” section for more information.

Table 22-5. CCP Long bit name prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| CCP1 | CCP1 |
| CCP2 | CCP2 |

Related Links

[Long Bit Names](#)

22.6.1 CCPxCON

Name: CCPxCON
Address: 0xFAB, 0xFA7

CCP Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|-----|-----------|-----|-----|-----|
| | EN | | OUT | FMT | MODE[3:0] | | | |
| Access | R/W | | RO | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | | x | 0 | 0 | 0 | 0 | 0 |

Bit 7 – EN CCP Module Enable bit

| Value | Description |
|-------|-----------------|
| 1 | CCP is enabled |
| 0 | CCP is disabled |

Bit 5 – OUT CCP Output Data bit (read-only)

Bit 4 – FMT CCPW (Pulse-Width) Value Alignment bit

| Value | Condition | Description |
|-------|--------------|----------------------|
| x | Capture mode | Not used |
| x | Compare mode | Not used |
| 1 | PWM mode | Left-aligned format |
| 0 | PWM mode | Right-aligned format |

Bits 3:0 – MODE[3:0] CCP Mode Select bits

Table 22-6. CCPx Mode Select Bits

| MODE | Operating Mode | Operation | Set CCPxIF |
|------|----------------|--|------------|
| 11xx | PWM | PWM Operation | Yes |
| 1011 | Compare | Pulse output; clear TMR1 ⁽²⁾ | Yes |
| 1010 | | Pulse output | Yes |
| 1001 | | Clear output ⁽¹⁾ | Yes |
| 1000 | | Set output ⁽¹⁾ | Yes |
| 0111 | Capture | Every 16 th rising edge of CCPx input | Yes |
| 0110 | | Every 4 th rising edge of CCPx input | Yes |
| 0101 | | Every rising edge of CCPx input | Yes |
| 0100 | | Every falling edge of CCPx input | Yes |
| 0011 | | Every edge of CCPx input | Yes |
| 0010 | Compare | Toggle output | Yes |
| 0001 | | Toggle output; clear TMR1 ⁽²⁾ | Yes |
| 0000 | Disabled | | — |

Notes:

1. The set and clear operations of the Compare mode are reset by setting MODE = '0000'.
2. When MODE = '0001' or '1011', then the timer associated with the CCP module is cleared. TMR1 is the default selection for the CCP module, so it is used for indication purpose only.

22.6.2 CCPxCAP

Name: CCPxCAP
Address: 0xFAC,0xFA8

Capture Trigger Input Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | CTS[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – CTS[3:0] Capture Trigger Input Selection bits

Table 22-7. Capture Trigger Sources

| CTS | Source |
|-----------|-------------------------|
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0100–0111 | Reserved |
| 0011 | IOC Interrupt |
| 0010 | CMP2_output |
| 0001 | CMP1_output |
| 0000 | Pin selected by CCPxPPS |

22.6.3 CCPRx

Name: CCPRx
Address: 0xFA9,0xFA5

Capture/Compare/Pulse Width Register

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | CCPR[15:8] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | CCPR[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 15:0 – CCPR[15:0] Capture/Compare/Pulse Width

Notes: The individual bytes in this multi-byte register can be accessed with the following register names:

- When **MODE** = Capture or Compare
 - CCPRxH: Accesses the high byte CCPR[15:8]
 - CCPRxL: Accesses the low byte CCPR[7:0]
- When **MODE** = PWM and **FMT**=0
 - CCPRxH[7:2]: Not used
 - CCPRxH[1:0]: Accesses the two Most Significant bits CCPR[9:8]
 - CCPRxL: Accesses the eight Least Significant bits CCPR[7:0]
- When **MODE** = PWM and **FMT**=1
 - CCPRxH: Accesses the eight Most Significant bits CCPR[9:2]
 - CCPRxL[7:6]: Accesses the two Least Significant bits CCPR[1:0]
 - CCPRxL[5:0]: Not used

22.6.4 CCPTMRS

Name: CCPTMRS
Address: 0xFAD

CCP Timers Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------------|-----|-------------|-----|-------------|-----|-------------|-----|
| | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 |

Bits 4:5, 6:7 – PnTSEL PWMn Timer Selection bits

| Value | Description |
|-------|----------------------|
| 11 | PWMn based on Timer6 |
| 10 | PWMn based on Timer4 |
| 01 | PWMn based on Timer2 |
| 00 | Reserved |

Bits 0:1, 2:3 – CnTSEL CCPn Timer Selection bits

| Value | Description |
|-------|---|
| 11 | CCPn is based off Timer5 in Capture/Compare mode and Timer6 in PWM mode |
| 10 | CCPn is based off Timer3 in Capture/Compare mode and Timer4 in PWM mode |
| 01 | CCPn is based off Timer1 in Capture/Compare mode and Timer2 in PWM mode |
| 00 | Reserved |

23. (PWM) Pulse-Width Modulation

The PWM module generates a Pulse-Width Modulated signal determined by the duty cycle, period, and resolution that are configured by the following registers:

- TxPR
- TxCON
- PWMxDC
- PWMxCON



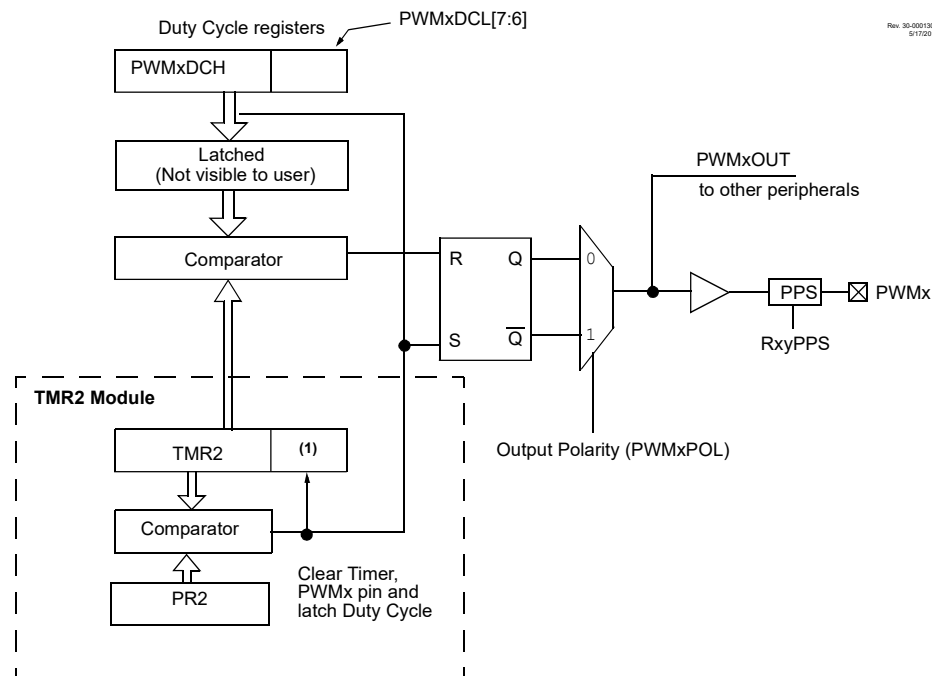
Important: The corresponding TRIS bit must be cleared to enable the PWM output on the PWMx pin.

Each PWM module can select the timer source that controls the module. Each module has an independent timer selection which can be accessed using the CCPTMRS register. Note that the PWM mode operation is described with respect to TMR2 in the following sections.

Figure 23-1 shows a simplified block diagram of PWM operation.

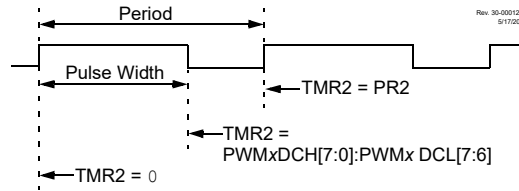
Figure 23-2 shows a typical waveform of the PWM signal.

Figure 23-1. Simplified PWM Block Diagram



Note 1: 8-bit timer is concatenated with the two Least Significant bits of 1/Fosc adjusted by the Timer2 prescaler to create a 10-bit time base.

Figure 23-2. PWM Output



For a step-by-step procedure on how to set up this module for PWM operation, refer to [Setup for PWM Operation Using PWMx Output Pins](#).

23.1 Fundamental Operation

The PWM module produces a 10-bit resolution output. The PWM timer can be selected using the PxTSEL bits in the CCPTMRS register. The default selection for PWMx is TMR2. Note that the PWM module operation in the following sections is described with respect to TMR2. Timer2 and T2PR set the period of the PWM. The PWMxDCH and PWMxDCL registers configure the duty cycle. The period is common to all PWM modules, whereas the duty cycle is independently controlled.

➔ Important: The Timer2 postscaler is not used in the determination of the PWM frequency. The postscaler might be used to have a servo update rate at a different frequency than the PWM output.

All PWM outputs associated with Timer2 are set when T2TMR is cleared. Each PWMx is cleared when TxTMR is equal to the value specified in the corresponding PWMxDCH (8 MSb) and PWMxDCL[7:6] (2 LSb) registers. When the value is greater than or equal to T2PR, the PWM output is never cleared (100% duty cycle).

➔ Important: The PWMxDCH and PWMxDCL registers are double-buffered. The buffers are updated when T2TMR matches T2PR. Care must be taken to update both registers before the timer match occurs.

23.2 PWM Output Polarity

The output polarity is inverted by setting the [POL](#) bit in the PWMxCON register.

23.3 PWM Period

The PWM period is specified by the TxPR register. The PWM period can be calculated using the formula of [Equation 23-1](#). It is required to have $F_{OSC}/4$ as the selected clock input to the timer for correct PWM operation.


Equation 23-1. PWM Period

$$PWMPeriod = [(T2PR) + 1] \cdot 4 \cdot T_{OSC} \cdot (TMR2 \text{ PrescaleValue})$$

Note: $T_{OSC} = 1/F_{OSC}$

When T2TMR is equal to T2PR, the following three events occur on the next increment cycle:

- T2TMR is cleared
- The PWM output is active. (Exception: When the PWM duty cycle = 0%, the PWM output will remain inactive.)
- The PWMxDCH and PWMxDCL register values are latched into the buffers.

 **Important:** The Timer2 postscaler has no effect on the PWM operation.

23.4 PWM Duty Cycle

The PWM duty cycle is specified by writing a 10-bit value to the PWMxDCH and PWMxDCL register pair. The PWMxDCH register contains the eight MSbs and the PWMxDCL[7:6], the two LSbs. The PWMxDCH and PWMxDCL registers can be written to at any time.

The formulas below are used to calculate the PWM pulse width and the PWM duty cycle ratio.

Equation 23-2. Pulse Width

$$PulseWidth = (PWMxDCH:PWMxDCL[7:6]) \cdot T_{OSC} \cdot (TMR2PrescaleValue)$$

Note: $T_{OSC} = 1/F_{OSC}$

Equation 23-3. Duty Cycle Ratio

$$DutyCycleRatio = \frac{(PWMxDCH:PWMxDCL[7:6])}{4(T2PR + 1)}$$

The 8-bit timer T2TMR register is concatenated with the two Least Significant bits of $1/F_{OSC}$, adjusted by the Timer2 prescaler to create the 10-bit time base. The system clock is used if the Timer2 prescaler is set to 1:1.

23.5 PWM Resolution

The resolution determines the number of available duty cycles for a given period. For example, a 10-bit resolution will result in 1024 discrete duty cycles, whereas an 8-bit resolution will result in 256 discrete duty cycles. The maximum PWM resolution is ten bits when T2PR is 255. The resolution is a function of the T2PR register value, as shown below.

Equation 23-4. PWM Resolution

$$Resolution = \frac{\log[4(T2PR + 1)]}{\log(2)} \text{ bits}$$


 **Important:** If the pulse-width value is greater than the period, the assigned PWM pin(s) will remain unchanged.

Table 23-1. Example PWM Frequencies and Resolutions ($F_{OSC} = 20 \text{ MHz}$)

| PWM Frequency | 0.31 kHz | 4.88 kHz | 19.53 kHz | 78.12 kHz | 156.3 kHz | 208.3 kHz |
|---------------------------|----------|----------|-----------|-----------|-----------|-----------|
| Timer Prescale | 64 | 4 | 1 | 1 | 1 | 1 |
| T2PR Value | 0xFF | 0xFF | 0xFF | 0x3F | 0x1F | 0x17 |
| Maximum Resolution (bits) | 10 | 10 | 10 | 8 | 7 | 6.6 |

Table 23-2. Example PWM Frequencies and Resolutions ($F_{OSC} = 8 \text{ MHz}$)

| PWM Frequency | 0.31 kHz | 4.90 kHz | 19.61 kHz | 76.92 kHz | 153.85 kHz | 200.0 kHz |
|---------------------------|----------|----------|-----------|-----------|------------|-----------|
| Timer Prescale | 64 | 4 | 1 | 1 | 1 | 1 |
| T2PR Value | 0x65 | 0x65 | 0x65 | 0x19 | 0x0C | 0x09 |
| Maximum Resolution (bits) | 8 | 8 | 8 | 6 | 5 | 5 |

23.6 Operation in Sleep Mode

In Sleep mode, the T2TMR register will not increment and the state of the module will not change. If the PWMx pin is driving a value, it will continue to drive that value. When the device wakes up, T2TMR will continue from its previous state.

23.7 Changes in System Clock Frequency

The PWM frequency is derived from the system clock frequency (F_{OSC}). Any changes in the system clock frequency will result in changes to the PWM frequency.

Related Links

[OSC - Oscillator Module](#)

23.8 Effects of Reset

Any Reset will force all ports to Input mode and the PWM registers to their Reset states.

23.9 Setup for PWM Operation Using PWMx Output Pins

Take these steps when configuring the module for PWM operation using the PWMx pins:

1. Disable the PWMx pin output driver(s) by setting the associated TRIS bit(s).
2. Clear the PWMxCON register.
3. Load the T2PR register with the PWM period value.
4. Load the PWMxDCH register and bits [7:6] of the PWMxDCL register with the PWM duty cycle value.
5. Configure and start Timer2:
 - Clear the TMR2IF interrupt flag bit of the PIR4 register⁽¹⁾
 - Select the timer clock source to be $F_{OSC}/4$ using the TxCLKCON register. This is required for correct operation of the PWM module.
 - Configure the T2CKPS bits of the T2CON register with the Timer2 prescale value
 - Enable Timer2 by setting the T2ON bit of the T2CON register
6. Enable the PWM output pin and wait until Timer2 overflows, the TMR2IF bit of the PIR4 register is set.⁽²⁾
7. Enable the PWMx pin output driver(s) by clearing the associated TRIS bit(s) and setting the desired pin PPS control bits.
8. Configure the PWM module by loading the PWMxCON register with the appropriate values.

Notes:

1. To send a complete duty cycle and period on the first PWM output, the above steps must be followed in the order given. If it is not critical to start with a complete PWM signal, then move step 8 to replace step 4.
2. For operation with other peripherals only, disable the PWMx pin outputs.

23.9.1 PWMx Pin Configuration

All PWM outputs are multiplexed with the PORT data latch. The user must configure the pins as outputs by clearing the associated TRIS bits.

23.10 Setup for PWM Operation to Other Device Peripherals

Take these steps when configuring the module for PWM operation to be used by other device peripherals:

1. Disable the PWMx pin output driver(s) by setting the associated TRIS bit(s).
2. Clear the PWMxCON register.

3. Load the T2PR register with the PWM period value.
4. Load the PWMxDCH register and bits [7:6] of the PWMxDCL register with the PWM duty cycle value.
5. Configure and start Timer2:
 - Clear the TMR2IF interrupt flag bit of the PIR4 register⁽¹⁾
 - Select the timer clock source to be $F_{OSC}/4$ using the TxCLKCON register. This is required for correct operation of the PWM module.
 - Configure the T2CKPS bits of the T2CON register with the Timer2 prescale value
 - Enable Timer2 by setting the T2ON bit of the T2CON register
6. Wait until Timer2 overflows, the TMR2IF bit of the PIR4 register is set.⁽¹⁾
7. Configure the PWM module by loading the PWMxCON register with the appropriate values.

Note:

1. To send a complete duty cycle and period on the first PWM output, the above steps must be included in the setup sequence. If it is not critical to start with a complete PWM signal on the first output, then step 6 may be ignored.

23.11 Register Summary - Registers Associated with PWM

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|-------------|---|-------------|-----|-------------|---|-------------|---|
| 0x00 ... 0x0F9E | Reserved | | | | | | | | | |
| 0x0F9F | PWM4DC | 7:0 | DCL[1:0] | | | | | | | |
| | | 15:8 | DCH[7:0] | | | | | | | |
| 0x0FA1 | PWM4CON | 7:0 | EN | | OUT | POL | | | | |
| 0x0FA2 | PWM3DC | 7:0 | DCL[1:0] | | | | | | | |
| | | 15:8 | DCH[7:0] | | | | | | | |
| 0x0FA4 | PWM3CON | 7:0 | EN | | OUT | POL | | | | |
| 0x0FA5 ... 0x0FAC | Reserved | | | | | | | | | |
| 0x0FAD | CCPTMRS | 7:0 | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | |

23.12 Register Definitions: PWM Control

Related Links

[Long Bit Names](#)

23.12.1 PWMxCON

Name: PWMxCON
Address: 0xFA4,0xFA1

PWM Control Register

| | | | | | | | | |
|--------|-----|---|-----|-----|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | EN | | OUT | POL | | | | |
| Access | R/W | | RO | R/W | | | | |
| Reset | 0 | | 0 | 0 | | | | |

Bit 7 – EN PWM Module Enable bit

| Value | Description |
|-------|------------------------|
| 1 | PWM module is enabled |
| 0 | PWM module is disabled |

Bit 5 – OUT PWM Module Output Level When Bit is Read

Bit 4 – POL PWM Output Polarity Select bit

| Value | Description |
|-------|------------------------|
| 1 | PWM output is inverted |
| 0 | PWM output is normal |

23.12.2 CCPTMRS

Name: CCPTMRS

Address: 0xFAD

CCP Timers Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------------|-----|-------------|-----|-------------|-----|-------------|-----|
| | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 |

Bits 7:6 – P4TSEL[1:0] PWM4 Timer Selection bits

| Value | Description |
|-------|--------------------|
| 11 | PWM4 based on TMR6 |
| 10 | PWM4 based on TMR4 |
| 01 | PWM4 based on TMR2 |
| 00 | Reserved |

Bits 5:4 – P3TSEL[1:0] PWM3 Timer Selection bits

| Value | Description |
|-------|--------------------|
| 11 | PWM3 based on TMR6 |
| 10 | PWM3 based on TMR4 |
| 01 | PWM3 based on TMR2 |
| 00 | Reserved |

Bits 3:2 – C2TSEL[1:0] CCP2 Timer Selection bits

| Value | Description |
|-------|---|
| 11 | CCP2 is based off Timer5 in Capture/Compare mode and Timer6 in PWM mode |
| 10 | CCP2 is based off Timer3 in Capture/Compare mode and Timer4 in PWM mode |
| 01 | CCP2 is based off Timer1 in Capture/Compare mode and Timer2 in PWM mode |
| 00 | Reserved |

Bits 1:0 – C1TSEL[1:0] CCP1 Timer Selection bits

| Value | Description |
|-------|---|
| 11 | CCP1 is based off Timer5 in Capture/Compare mode and Timer6 in PWM mode |
| 10 | CCP1 is based off Timer3 in Capture/Compare mode and Timer4 in PWM mode |
| 01 | CCP1 is based off Timer1 in Capture/Compare mode and Timer2 in PWM mode |
| 00 | Reserved |

23.12.3 PWMxDC

Name: PWMxDC
Address: 0xFA2,0xF9F

PWM Duty Cycle Register

| | | | | | | | | |
|--------|----------|----|----|----|----|----|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | DCH[7:0] | | | | | | | |
| Access | | | | | | | | |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | DCL[1:0] | | | | | | | |
| Access | | | | | | | | |
| Reset | x | x | | | | | | |

Bits 15:8 – DCH[7:0] PWM Duty Cycle Most Significant bits
These bits are the MSBs of the PWM duty cycle.

Reset States: POR/BOR = xxxxxxxx
All Other Resets = uuuuuuuu

Bits 7:6 – DCL[1:0] PWM Duty Cycle Least Significant bits
These bits are the LSBs of the PWM duty cycle.

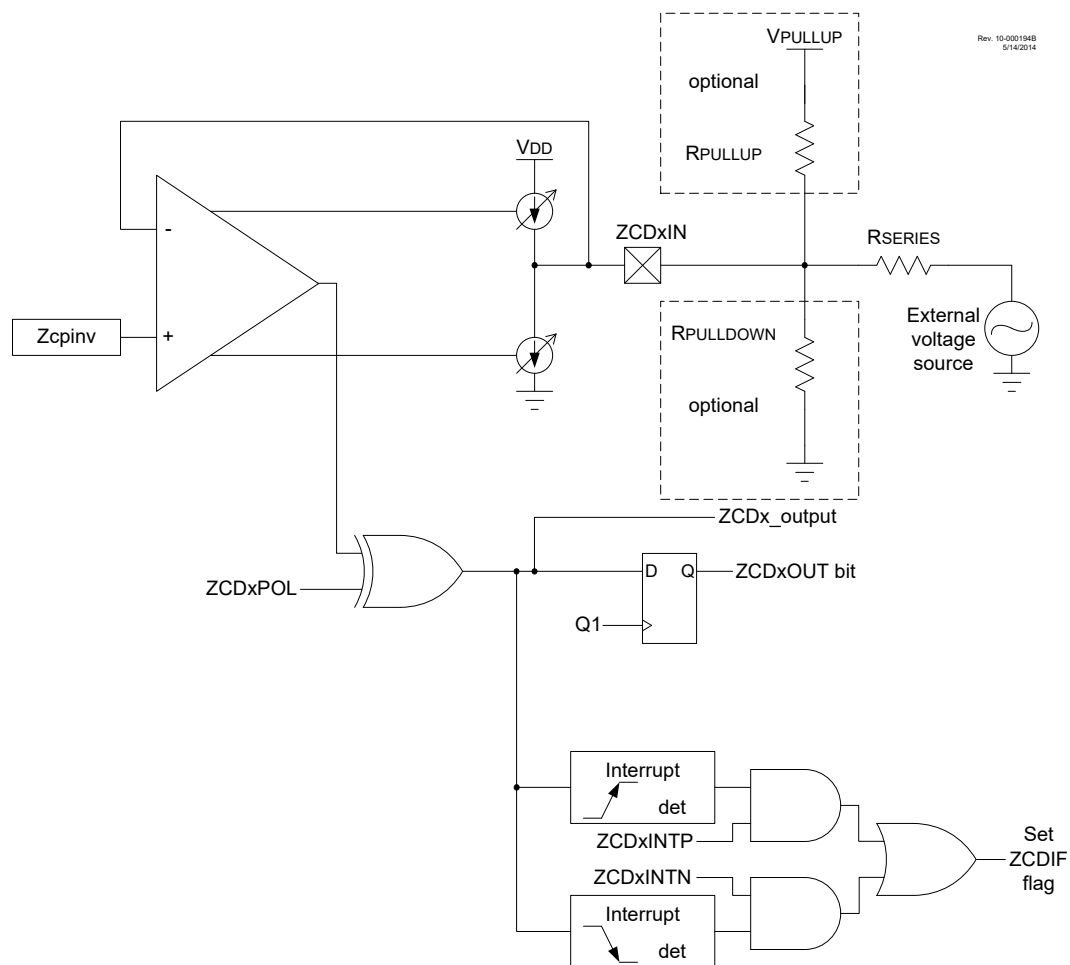
Reset States: POR/BOR = xx
All Other Resets = uu

24. ZCD - Zero-Cross Detection Module

The Zero-Cross Detection (ZCD) module detects when an A/C signal crosses through the ground potential. The actual zero-crossing threshold is the zero-crossing reference voltage, Z_{CPINV} , which is typically 0.75V above ground.

The connection to the signal to be detected is through a series current-limiting resistor. The module applies a current source or sink to the ZCD pin to maintain a constant voltage on the pin, thereby preventing the pin voltage from forward biasing the ESD protection diodes. When the applied voltage is greater than the reference voltage, the module sinks current. When the applied voltage is less than the reference voltage, the module sources current. The current source and sink action keeps the pin voltage constant over the full range of the applied voltage. The ZCD module is shown in the following simplified block diagram.

Figure 24-1. Simplified ZCD Block Diagram



The ZCD module is useful when monitoring an A/C waveform for, but not limited to, the following purposes:

- A/C period measurement
- Accurate long term time measurement
- Dimmer phase delayed drive

- Low EMI cycle switching

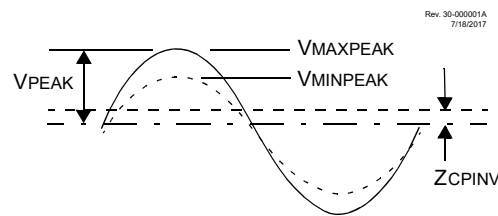
24.1 External Resistor Selection

The ZCD module requires a current-limiting resistor in series with the external voltage source. The impedance and rating of this resistor depends on the external source peak voltage. Select a resistor value that will drop all of the peak voltage when the current through the resistor is nominally 300 μ A. Make sure that the ZCD I/O pin internal weak pull-up is disabled so it does not interfere with the current source and sink.

Equation 24-1. External Resistor

$$R_{SERIES} = \frac{V_{PEAK}}{3 \times 10^{-4}}$$

Figure 24-2. External Voltage Source



24.2 ZCD Logic Output

The ZCD module includes a Status bit, which can be read to determine whether the current source or sink is active. The **OUT** bit is set when the current sink is active, and cleared when the current source is active. The OUT bit is affected by the polarity bit.

The OUT signal can also be used as input to other modules. This is controlled by the registers of the corresponding module. OUT can be used as follows:

- Gate source for TMR1/3/5
- Clock source for TMR2/4/6
- Reset source for TMR2/4/6

24.3 ZCD Logic Polarity

The **POL** bit inverts the OUT bit relative to the current source and sink output. When the POL bit is set, a OUT high indicates that the current source is active, and a low output indicates that the current sink is active.

The POL bit affects the ZCD interrupts.

24.4 ZCD Interrupts

An interrupt will be generated upon a change in the ZCD logic output when the appropriate interrupt enables are set. A rising edge detector and a falling edge detector are present in the ZCD for this purpose.

The ZCDIF bit of the PIR2 register will be set when either edge detector is triggered and its associated enable bit is set. The **INTP** bit in the ZCDxCON register enables rising edge interrupts and the **INTN** bit in the ZCDxCON register enables falling edge interrupts.

To fully enable the interrupt, the following bits must be set:

- ZCDIE bit of the PIE2 register

- INTP bit for rising edge detection
- INTN bit for falling edge detection
- PEIE and GIE bits of the INTCON register

Changing the POL bit will cause an interrupt, regardless of the level of the [SEN](#) bit.

The ZCDIF bit of the PIR2 register must be cleared in software as part of the interrupt service. If another edge is detected while this flag is being cleared, the flag will still be set at the end of the sequence.

24.5 Correction for Z_{CPINV} Offset

The actual voltage at which the ZCD switches is the reference voltage at the noninverting input of the ZCD op amp. For external voltage source waveforms other than square waves, this voltage offset from zero causes the zero-cross event to occur either too early or too late.

24.5.1 Correction by AC Coupling

When the external voltage source is sinusoidal, the effects of the Z_{CPINV} offset can be eliminated by isolating the external voltage source from the ZCD pin with a capacitor, in addition to the voltage reducing resistor. The capacitor will cause a phase shift resulting in the ZCD output switch in advance of the actual zero-crossing event. The phase shift will be the same for both rising and falling zero-crossings, which can be compensated for by either delaying the CPU response to the ZCD switch by a timer or other means, or selecting a capacitor value large enough that the phase shift is negligible.

To determine the series resistor and capacitor values for this configuration, start by computing the impedance, Z , to obtain a peak current of 300 μ A. Next, arbitrarily select a suitably large nonpolar capacitor and compute its reactance, X_C , at the external voltage source frequency. Finally, compute the series resistor, capacitor peak voltage, and phase shift by the formulas shown below.

When this technique is used and the input signal is not present, the ZCD will tend to oscillate. To avoid this oscillation, connect the ZCD pin to V_{DD} or GND with a high-impedance resistor such as 200K.

Equation 24-2. R-C Equations

V_{PEAK} = external voltage source peak voltage

f = external voltage source frequency

C = series capacitor

R = series resistor

V_C = peak capacitor voltage

Φ = capacitor induced zero-crossing phase advance in radians

T_Φ = time ZC event occurs before actual zero-crossing

$$Z = \frac{V_{PEAK}}{3 \times 10^{-4}}$$

$$X_C = \frac{1}{2\pi fC}$$

$$R = \sqrt{Z^2 - X_C^2}$$

$$V_C = X_C(3 \times 10^{-4})$$

$$\Phi = \tan^{-1}\theta\left(\frac{X_C}{R}\right)$$

$$T_\Phi = \frac{\Phi}{2\pi f}$$

Equation 24-3. R-C Calculation Example

$$V_{rms} = 120$$

$$V_{PEAK} = V_{rms} \times \sqrt{2} = 169.7$$

$$f = 60 \text{ Hz}$$

$$C = 0.1 \mu F$$

$$Z = \frac{V_{PEAK}}{3 \times 10^{-4}} = \frac{169.7}{3 \times 10^{-4}} = 565.7 \text{ k}\Omega$$

$$X_C = \frac{1}{2\pi f C} = \frac{1}{2\pi \times 60 \times 10^{-7}} = 26.53 \text{ k}\Omega$$

$$R = \sqrt{Z^2 - X_C^2} = 565.1 \text{ k}\Omega \text{ (computed)}$$

$$R_a = 560 \text{ k}\Omega \text{ (used)}$$

$$Z_R = \sqrt{R_a^2 + X_C^2} = 560.6 \text{ k}\Omega$$

$$I_{PEAK} = \frac{V_{PEAK}}{Z_R} = 302.7 \times 10^{-6} \text{ A}$$

$$V_C = X_C \times I_{PEAK} = 8.0 \text{ V}$$

$$\Phi = \tan^{-1}\theta\left(\frac{X_C}{R}\right) = 0.047 \text{ radians}$$

$$T_\Phi = \frac{\Phi}{2\pi f} = 125.6 \mu s$$

24.5.2 Correction by Offset Current

When the waveform is varying relative to V_{SS} , the zero-cross is detected too early as the waveform falls, and too late as the waveform rises. When the waveform is varying relative to V_{DD} , the zero-cross is detected too late as the waveform rises, and too early as the waveform falls. The actual offset time can be determined for sinusoidal waveforms with the corresponding equations shown below.

Equation 24-4. ZCD Event Offset

When external voltage source is relative to V_{SS} :

$$T_{offset} = \frac{\sin^{-1}\left(\frac{Z_{CPINV}}{V_{PEAK}}\right)}{2\pi f}$$

When external voltage source is relative to V_{DD} :

$$T_{offset} = \frac{\sin^{-1}\left(\frac{V_{DD} - Z_{CPINV}}{V_{PEAK}}\right)}{2\pi f}$$

This offset time can be compensated for by adding a pull-up or pull-down biasing resistor to the ZCD pin. A pull-up resistor is used when the external voltage source is varying relative to V_{SS} . A pull-down resistor is used when the voltage is varying relative to V_{DD} . The resistor adds a bias to the ZCD pin so that the target external voltage source must go to zero to pull the pin voltage to the Z_{CPINV} switching voltage. The pull-up or pull-down value can be determined with the equations shown below.

Equation 24-5. ZCD Pull-up/Pull-down Resistor

When external voltage source is relative to V_{SS} :

$$R_{pullup} = \frac{R_{SERIES}(V_{pullup} - Z_{CPINV})}{Z_{CPINV}}$$

When external voltage source is relative to V_{DD} :

$$R_{pulldown} = \frac{R_{SERIES}(Z_{CPINV})}{(V_{DD} - Z_{CPINV})}$$

24.6 Handling V_{PEAK} Variations

If the peak amplitude of the external voltage is expected to vary, the series resistor must be selected to keep the ZCD current source and sink below the design maximum range of $\pm 600 \mu A$ and above a reasonable minimum range. A general rule of thumb is that the maximum peak voltage can be no more than six times the minimum peak voltage. To ensure that the maximum current does not exceed $\pm 600 \mu A$ and the minimum is at least $\pm 100 \mu A$, compute the series resistance as shown in Equation 24-6. The compensating pull-up for this series resistance can be determined with the equations shown in Equation 24-5 because the pull-up value is independent from the peak voltage.

Equation 24-6. Series R for V range

$$R_{SERIES} = \frac{V_{MAX_PEAK} + V_{MIN_PEAK}}{7 \times 10^{-4}}$$

24.7 Operation During Sleep

The ZCD current sources and interrupts are unaffected by Sleep.

24.8 Effects of a Reset

The ZCD circuit can be configured to default to the Active or Inactive state on Power-on Reset (POR). When the \overline{ZCD} Configuration bit is cleared, the ZCD circuit will be active at POR. When the \overline{ZCD} Configuration bit is set, the **SEN** bit must be set to enable the ZCD module.

24.9 Disabling the ZCD Module

The ZCD module can be disabled in two ways:

1. The \overline{ZCD} Configuration bit disables the ZCD module when set. When this is the case then the ZCD module will be enabled by setting the **SEN** bit. When the \overline{ZCD} bit is cleared, the ZCD is always enabled and the **SEN** bit has no effect.

2. The ZCD can also be disabled using the ZCDMD bit of the PMD3 register. This is subject to the status of the $\overline{\text{ZCD}}$ bit.

24.10 Register Summary - ZCD Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------|----------|-----|---|-----|-----|---|---|------|------|
| 0x00 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0F2C | | | | | | | | | | |
| 0x0F2D | ZCDCON | 7:0 | SEN | | OUT | POL | | | INTP | INTN |

24.11 Register Definitions: ZCD Control

Related Links
[Long Bit Names](#)

24.11.1 ZCDCON

Name: ZCDCON
Address: 0xF2D

Zero-Cross Detect Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|-----|---|---|------|------|
| | SEN | | OUT | POL | | | INTP | INTN |
| Access | R/W | | RO | R/W | | | R/W | R/W |
| Reset | 0 | | x | 0 | | | 0 | 0 |

Bit 7 – SEN Zero-Cross Detect Software Enable bit
This bit is ignored when ZCD fuse is cleared.

| Value | Condition | Description |
|-------|---------------------|---|
| x | ZCD Config fuse = 0 | Zero-cross detect is always enabled. This bit is ignored. |
| 1 | ZCD Config fuse = 1 | Zero-cross detect is enabled. ZCD pin is forced to output to source and sink current. |
| 0 | ZCD Config fuse = 1 | Zero-cross detect is disabled. ZCD pin operates according to PPS and TRIS controls. |

Bit 5 – OUT Zero-Cross Detect Data Output bit

| Value | Condition | Description |
|-------|-----------|-----------------------------|
| 1 | POL = 0 | ZCD pin is sinking current |
| 0 | POL = 0 | ZCD pin is sourcing current |
| 1 | POL = 1 | ZCD pin is sourcing current |
| 0 | POL = 1 | ZCD pin is sinking current |

Bit 4 – POL Zero-Cross Detect Polarity bit

| Value | Description |
|-------|----------------------------------|
| 1 | ZCD logic output is inverted |
| 0 | ZCD logic output is not inverted |

Bit 1 – INTP Zero-Cross Detect Positive-Going Edge Interrupt Enable bit

| Value | Description |
|-------|--|
| 1 | ZCDIF bit is set on low-to-high ZCD_output transition |
| 0 | ZCDIF bit is unaffected by low-to-high ZCD_output transition |

Bit 0 – INTN Zero-Cross Detect Negative-Going Edge Interrupt Enable bit

| Value | Description |
|-------|--|
| 1 | ZCDIF bit is set on high-to-low ZCD_output transition |
| 0 | ZCDIF bit is unaffected by high-to-low ZCD_output transition |

25. CWG - Complementary Waveform Generator

The Complementary Waveform Generator (CWG) produces half-bridge, full-bridge, and steering of PWM waveforms. It is backwards compatible with previous CCP functions. The PIC18F26/45/46Q10 family has 1 instance(s) of the CWG module.

The CWG has the following features:

- Six Operating Modes:
 - Synchronous Steering mode
 - Asynchronous Steering mode
 - Full-Bridge mode, Forward
 - Full-Bridge mode, Reverse
 - Half-Bridge mode
 - Push-Pull mode
- Output Polarity Control
- Output Steering
- Independent 6-Bit Rising and Falling Event Dead-Band Timers:
 - Clocked dead band
 - Independent rising and falling dead-band enables
- Auto-Shutdown Control with:
 - Selectable shutdown sources
 - Auto-restart option
 - Auto-shutdown pin override control

25.1 Fundamental Operation

The CWG generates two output waveforms from the selected input source.

The off-to-on transition of each output can be delayed from the on-to-off transition of the other output, thereby, creating a time delay immediately where neither output is driven. This is referred to as dead time and is covered in section [Dead-Band Control](#).

It may be necessary to guard against the possibility of circuit faults or a feedback event arriving too late or not at all. In this case, the active drive must be terminated before the Fault condition causes damage. This is referred to as auto-shutdown and is covered in section [Auto-Shutdown](#).

25.2 Operating Modes

The CWG module can operate in six different modes, as specified by the [MODE](#) bits:

- Half-Bridge mode
- Push-Pull mode
- Asynchronous Steering mode
- Synchronous Steering mode
- Full-Bridge mode, Forward
- Full-Bridge mode, Reverse

All modes accept a single pulse data input, and provide up to four outputs as described in the following sections.

All modes include auto-shutdown control, as described in [Auto-Shutdown](#).

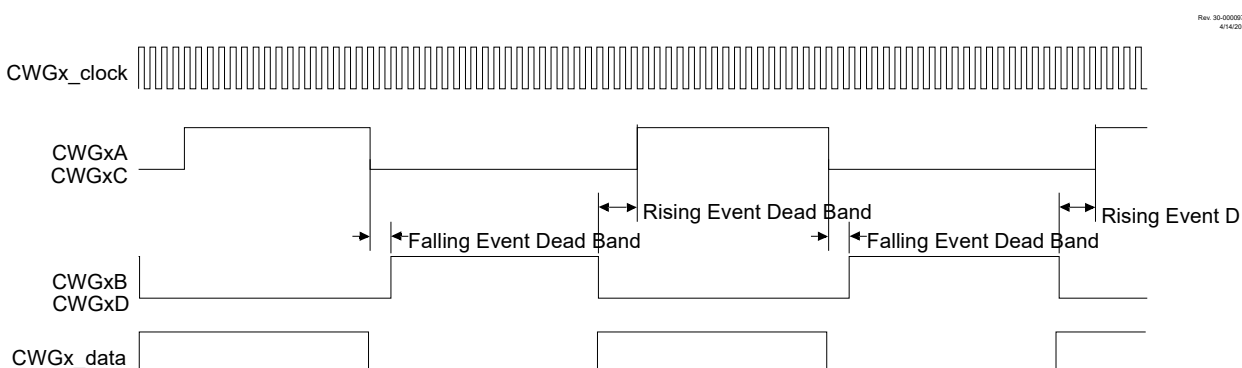
➔ Important: Except as noted for Full-Bridge mode ([Full-Bridge Modes](#)), mode changes may only be performed while **EN** = 0.

25.2.1 Half-Bridge Mode

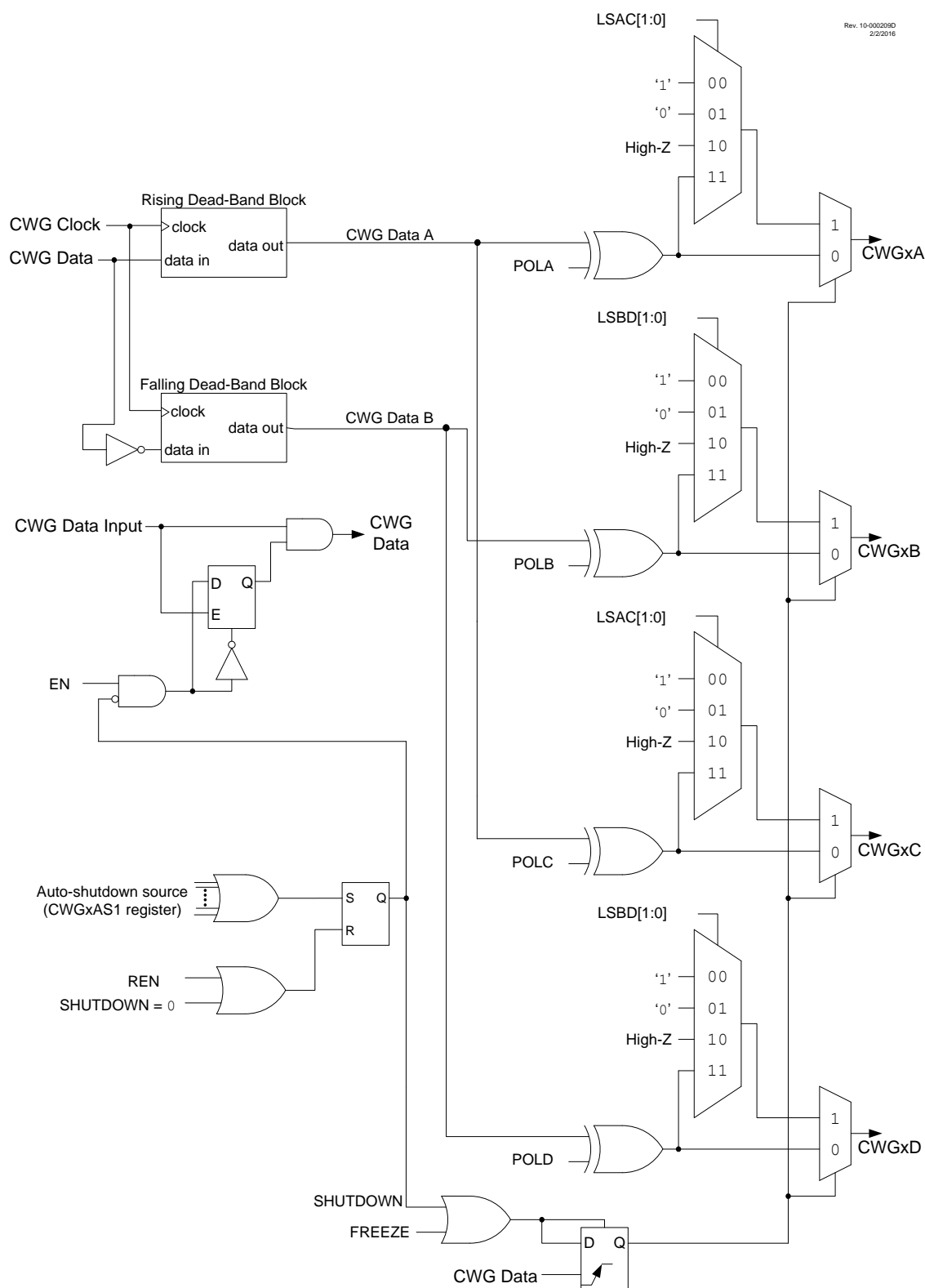
In Half-Bridge mode, two output signals are generated as true and inverted versions of the input as illustrated in [Figure 25-1](#). A non-overlap (dead-band) time is inserted between the two outputs to prevent shoot-through current in various power supply applications. Dead-band control is described in [Dead-Band Control](#). The output steering feature cannot be used in this mode. A basic block diagram of this mode is shown in [Figure 25-2](#).

The unused outputs CWGxC and CWGxD drive similar signals, with polarity independently controlled by the **POLC** and **POLD** bits, respectively.

Figure 25-1. CWG Half-Bridge Mode Operation



Note: CWGx_rising_src = CCP1_out, CWGx_falling_src = ~CCP1_out

Figure 25-2. Simplified CWG Block Diagram (Half-Bridge Mode, MODE[2:0] = 100)

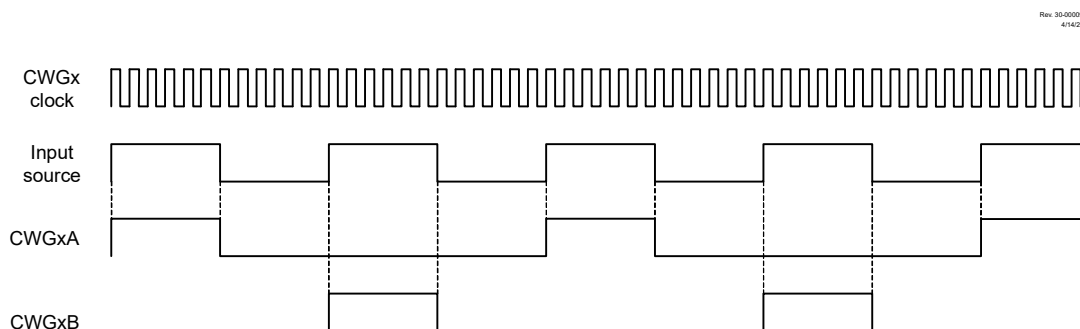
25.2.2 Push-Pull Mode

In Push-Pull mode, two output signals are generated, alternating copies of the input as illustrated in [Figure 25-3](#). This alternation creates the push-pull effect required for driving some transformer-based power supply designs. Steering modes are not used in Push-Pull mode. A basic block diagram for the Push-Pull mode is shown in [Figure 25-4](#).

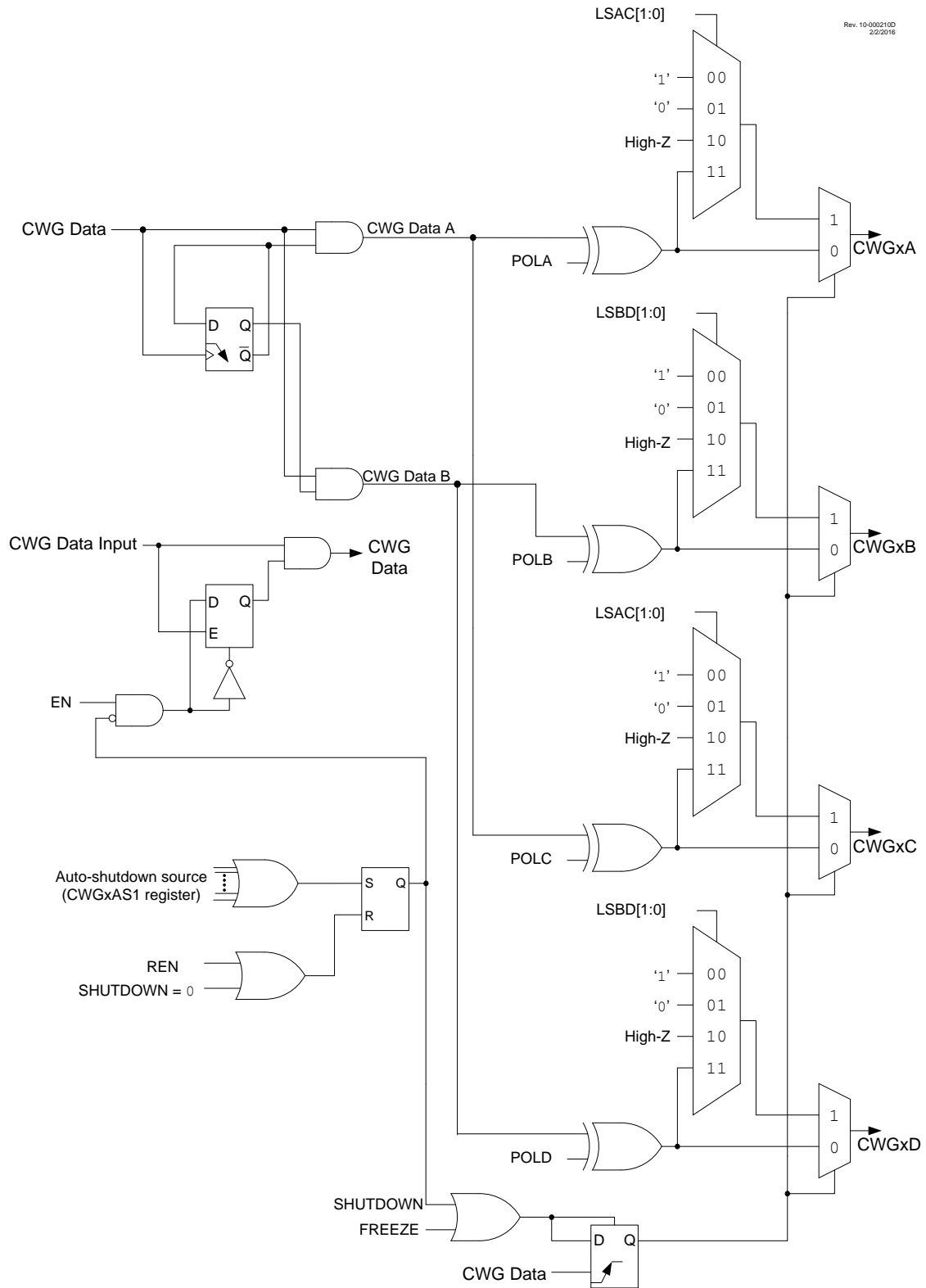
The push-pull sequencer is reset whenever $EN = 0$ or if an auto-shutdown event occurs. The sequencer is clocked by the first input pulse, and the first output appears on CWG1A.

The unused outputs CWGxC and CWGxD drive copies of CWGxA and CWGxB, respectively, but with polarity controlled by the POLC and POLD bits of the CWGxCON1 register, respectively.

Figure 25-3. CWG Push-Pull Mode Operation



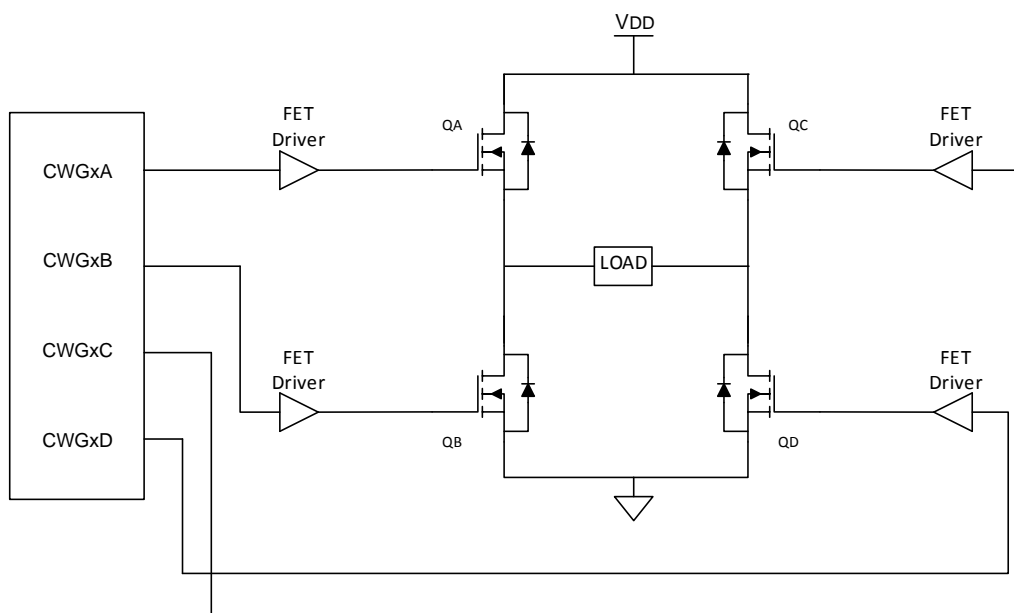
Rev. 10-000210D
2/2/2016



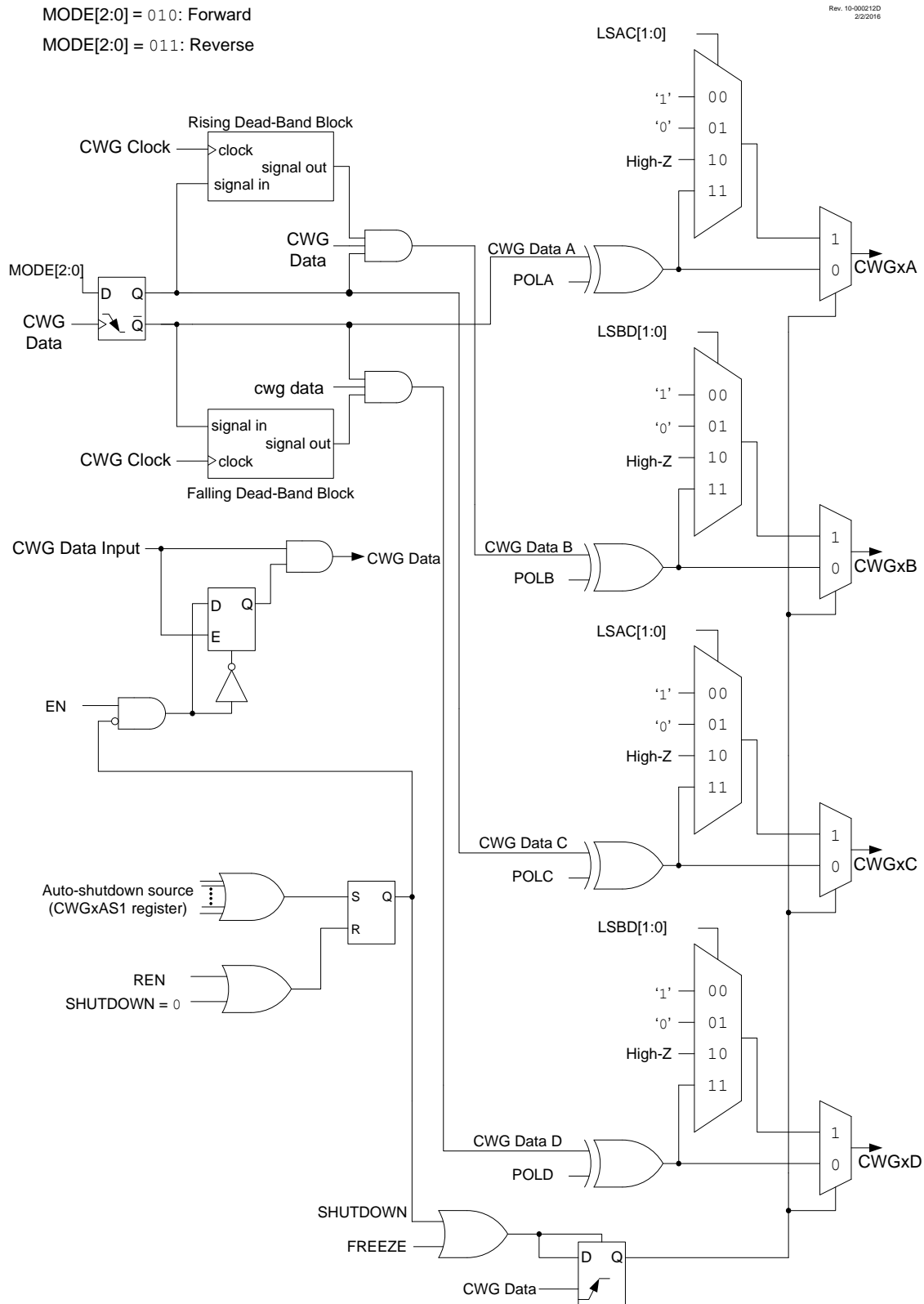
25.2.3 Full-Bridge Modes

In Forward and Reverse Full-Bridge modes, three outputs drive static values while the fourth is modulated by the input data signal. The mode selection may be toggled between forward and reverse by toggling the MODE[0] bit of the CWGxCON0 while keeping MODE[2:1] static, without disabling the CWG module. When connected, as shown in [Figure 25-5](#), the outputs are appropriate for a full-bridge motor driver. Each CWG output signal has independent polarity control, so the circuit can be adapted to high-active and low-active drivers. A simplified block diagram for the Full-Bridge modes is shown in [Figure 25-6](#).

Figure 25-5. Example of Full-Bridge Application



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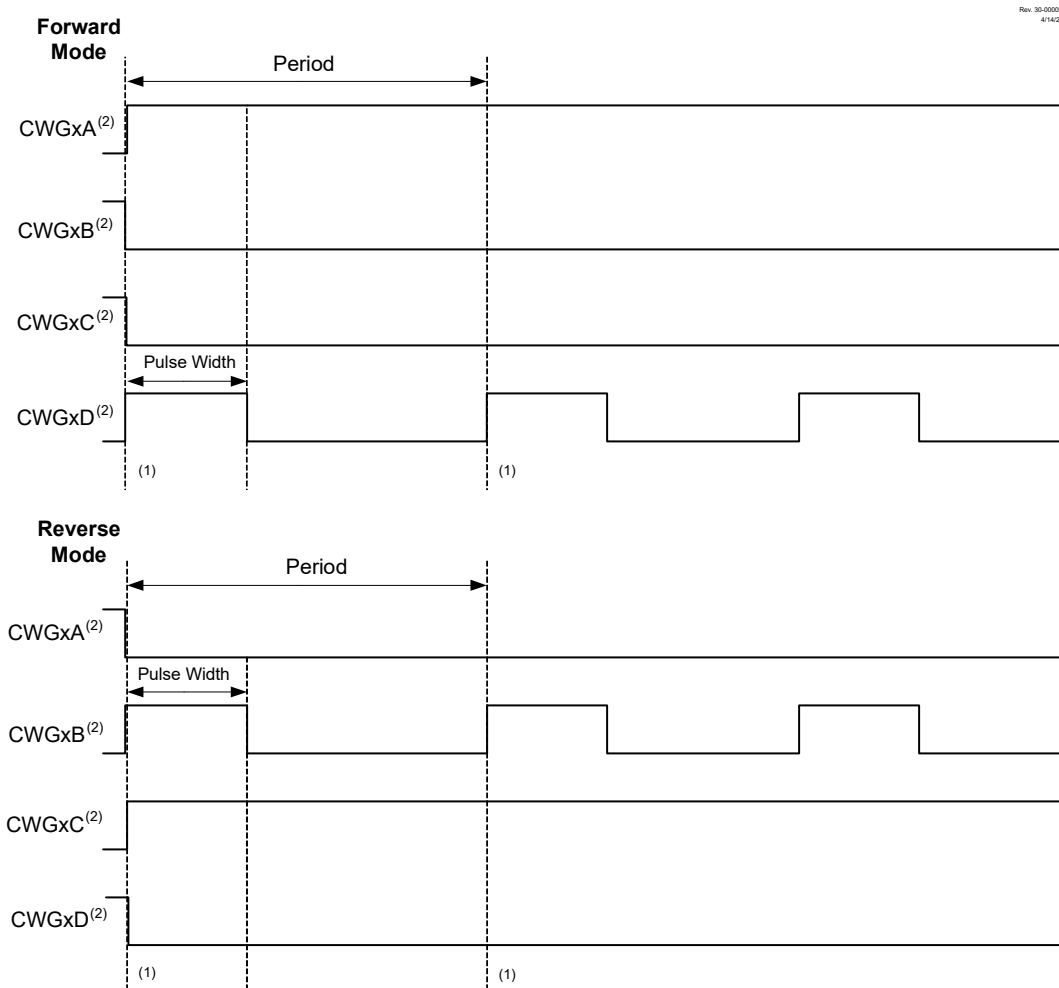
Figure 25-6. Simplified CWG Block Diagram (Forward and Reverse Full-Bridge Modes)

In Forward Full-Bridge mode ($MODE = 010$), CWGxA is driven to its Active state, CWGxB and CWGxC are driven to their Inactive state, and CWGxD is modulated by the input signal, as shown in Figure 25-7.

In Reverse Full-Bridge mode ($MODE = 011$), CWGxC is driven to its Active state, CWGxA and CWGxD are driven to their Inactive states, and CWGxB is modulated by the input signal, as shown in Figure 25-7.

In Full-Bridge mode, the dead-band period is used when there is a switch from forward to reverse or vice versa. This dead-band control is described in [Dead-Band Control](#), with additional details in [Rising Edge and Reverse Dead Band](#) and [Falling Edge and Forward Dead Band](#). Steering modes are not used with either of the Full-Bridge modes. The mode selection may be toggled between forward and reverse toggling the $MODE[0]$ bit of the $CWGxCON0$ while keeping $MODE[2:1]$ static, without disabling the CWG module.

Figure 25-7. Example of Full-Bridge Output



Notes:

1. A rising CWG data input creates a rising event on the modulated output.
2. Output signals shown as active-high; all POL bits are clear.

25.2.3.1 Direction Change in Full-Bridge Mode

In Full-Bridge mode, changing $MODE$ controls the forward/reverse direction. Direction changes occur on the next rising edge of the modulated input.

A direction change is initiated in software by changing the MODE bits. The sequence is illustrated in [Figure 25-8](#).

- The associated active output CWGxA and the inactive output CWGxC are switched to drive in the opposite direction.
- The previously modulated output CWGxD is switched to the Inactive state, and the previously inactive output CWGxB begins to modulate.
- CWG modulation resumes after the direction-switch dead band has elapsed.

25.2.3.2 Dead-Band Delay in Full-Bridge Mode

Dead-band delay is important when either of the following conditions is true:

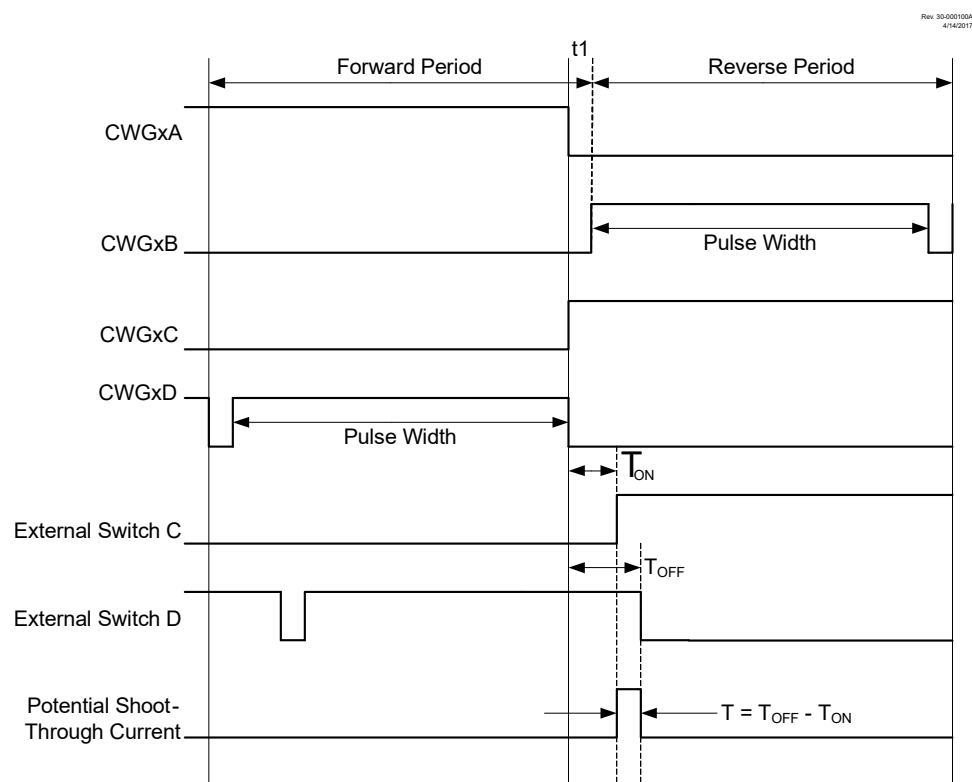
1. The direction of the CWG output changes when the duty cycle of the data input is at or near 100%, or
2. The turn-off time of the power switch, including the power device and driver circuit, is greater than the turn-on time.

The dead-band delay is inserted only when changing directions, and only the modulated output is affected. The statically-configured outputs (CWGxA and CWGxC) are not afforded dead band, and switch essentially simultaneously.

The following figure shows an example of the CWG outputs changing directions from forward to reverse, at near 100% duty cycle. In this example, at time t1, the output of CWGxA and CWGxD become inactive, while output CWGxC becomes active. Since the turn-off time of the power devices is longer than the turn-on time, a shoot-through current will flow through power devices QC and QD for the duration of 't'. The same phenomenon will occur to power devices QA and QB for the CWG direction change from reverse to forward.

When changing the CWG direction at high duty cycle is required for an application, two possible solutions for eliminating the shoot-through current are:

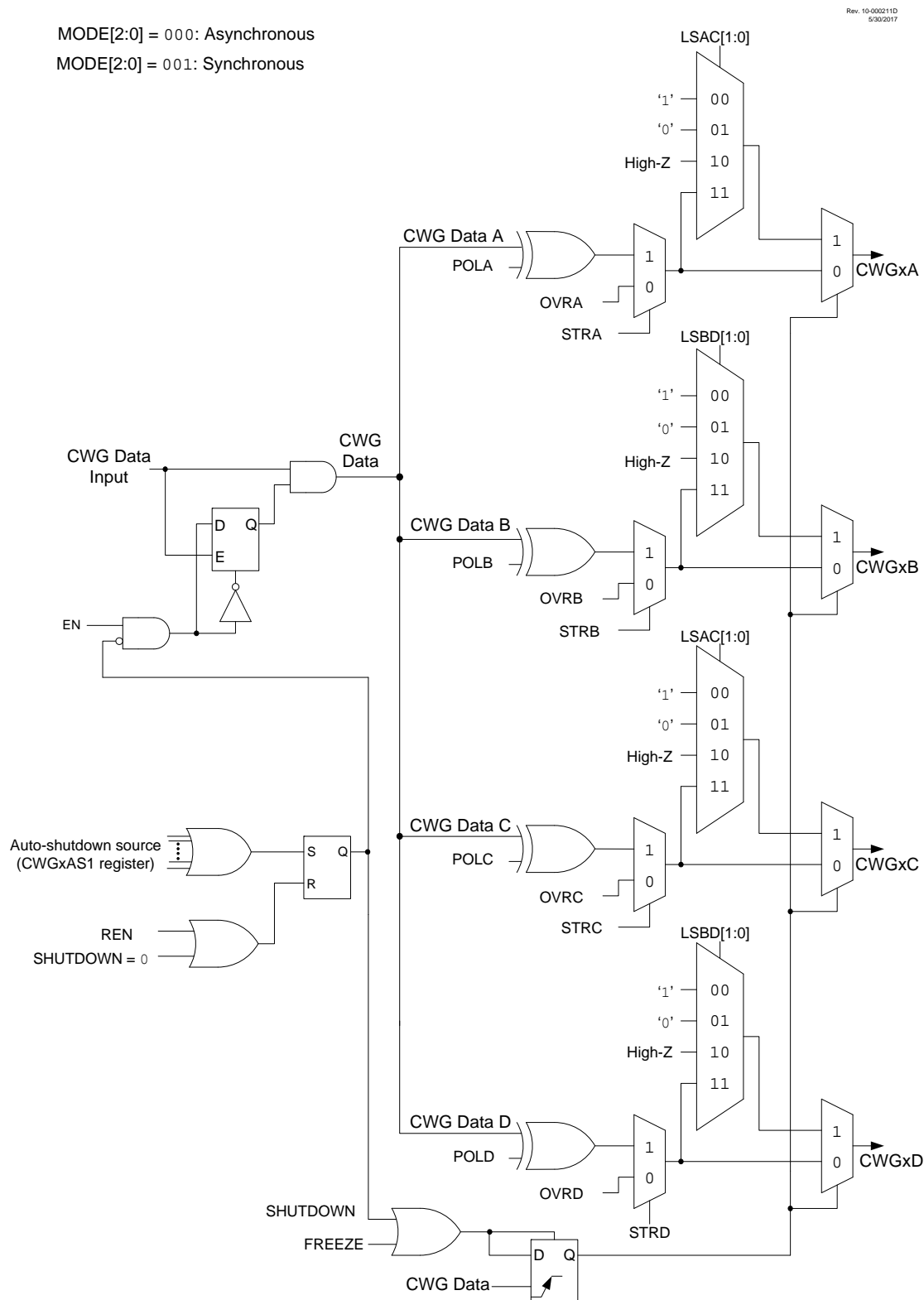
1. Reduce the CWG duty cycle for one period before changing directions.
2. Use switch drivers that can drive the switches off faster than they can drive them on.

Figure 25-8. Example of PWM Direction Change at Near 100% Duty Cycle

25.2.4 Steering Modes

In both Synchronous and Asynchronous Steering modes, the modulated input signal can be steered to any combination of four CWG outputs. A fixed-value will be presented on all the outputs not used for the PWM output. Each output has independent polarity, steering, and shutdown options. Dead-band control is not used in either Steering mode.

Figure 25-9. Simplified CWG Block Diagram (Output Steering Modes)



For example, when **STRA** = 0, the corresponding pin is held at the level defined by **OVRA**. When **STRA** = 1, the pin is driven by the modulated input signal.

The **POLy** bits control the signal polarity only when **STRy** = 1.

The CWG auto-shutdown operation also applies in Steering modes, as described in **Auto-Shutdown**. An auto-shutdown event will only affect pins that have **STRy** = 1.

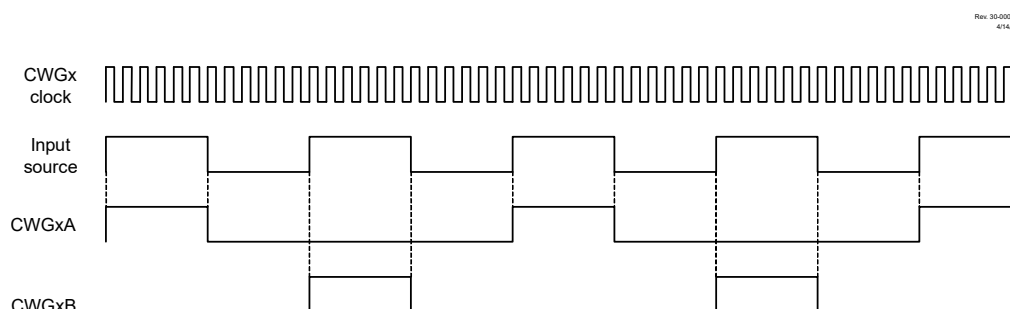
25.2.4.1 Synchronous Steering Mode

In Synchronous Steering mode (**MODE**=001), changes to steering selection registers take effect on the next rising edge of the modulated data input (see figure below). In Synchronous Steering mode, the output will always produce a complete waveform.



Important: Only the **STRx** bits are synchronized; the **OVRx** bits are not synchronized.

Figure 25-10. Example of Synchronous Steering (**MODE** = 001)

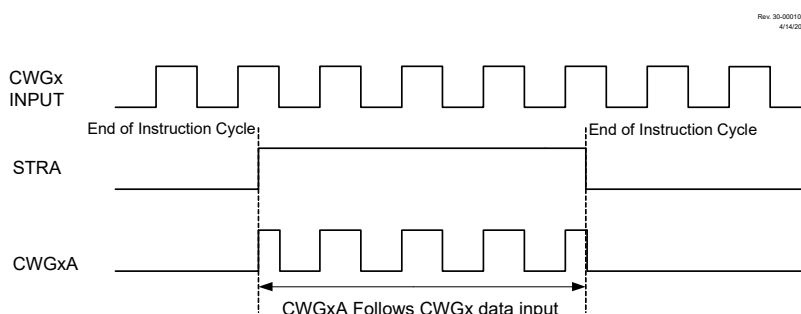


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25.2.4.2 Asynchronous Steering Mode

In Asynchronous mode (**MODE** = 000), steering takes effect at the end of the instruction cycle that writes to **STRx**. In Asynchronous Steering mode, the output signal may be an incomplete waveform (see figure below). This operation may be useful when the user firmware needs to immediately remove a signal from the output pin.

Figure 25-11. Example of Asynchronous Steering (**MODE** = 000)



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25.3 Start-up Considerations

The application hardware must use the proper external pull-up and/or pull-down resistors on the CWG output pins. This is required because all I/O pins are forced to high-impedance at Reset.

The polarity control bits (**POLy**) allow the user to choose whether the output signals are active-high or active-low.

25.4 Clock Source

The clock source is used to drive the dead-band timing circuits. The CWG module allows the following clock sources to be selected:

- F_{OSC} (system clock)
- HFINTOSC

When the HFINTOSC is selected, the HFINTOSC will be kept running during Sleep. Therefore, CWG modes requiring dead band can operate in Sleep, provided that the CWG data input is also active during Sleep. The clock sources are selected using the **CS** bit. The system clock F_{OSC} is disabled in Sleep and thus dead-band control cannot be used.

25.5 Selectable Input Sources

The CWG generates the output waveforms from the input sources which are selected with the **ISM** bits as shown below.

Table 25-1. CWG Data Input Sources

| ISM | Data Source |
|------|-------------------------|
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0111 | DSM_out |
| 0110 | CMP2_out |
| 0101 | CMP1_out |
| 0100 | PWM4_out |
| 0011 | PWM3_out |
| 0010 | CCP2_out |
| 0001 | CCP1_out |
| 0000 | Pin selected by CWGxPPS |

25.6 Output Control

25.6.1 CWG Outputs

Each CWG output can be routed to a Peripheral Pin Select (PPS) output via the RxyPPS register.

Related Links

[PPS - Peripheral Pin Select Module](#)

25.6.2 Polarity Control

The polarity of each CWG output can be selected independently. When the output polarity bit is set, the corresponding output is active-high. Clearing the output polarity bit configures the corresponding output as active-low. However, polarity does not affect the override levels. Output polarity is selected with the **POLy** bits. Auto-shutdown and steering options are unaffected by polarity.

25.7 Dead-Band Control

The dead-band control provides nonoverlapping PWM signals to prevent shoot-through current in PWM switches. Dead-band operation is employed for Half-Bridge and Full-Bridge modes. The CWG

contains two 6-bit dead-band counters. One is used for the rising edge of the input source control in Half-Bridge mode or for reverse dead band in Full-Bridge mode. The other is used for the falling edge of the input source control in Half-Bridge mode or for forward dead band in Full-Bridge mode.

Dead band is timed by counting CWG clock periods from zero up to the value in the rising or falling dead-band counter registers.

25.7.1 Dead-Band Functionality in Half-Bridge Mode

In Half-Bridge mode, the dead-band counters dictate the delay between the falling edge of the normal output and the rising edge of the inverted output. This can be seen in [Figure 25-1](#).

25.7.2 Dead-Band Functionality in Full-Bridge mode

In Full-Bridge mode, the dead-band counters are used when undergoing a direction change. The [MODE\[0\]](#) bit can be set or cleared while the CWG is running, allowing for changes from Forward to Reverse mode. The CWGxA and CWGxC signals will change immediately upon the first rising input edge following a direction change, but the modulated signals (CWGxB or CWGxD, depending on the direction of the change) will experience a delay dictated by the dead-band counters.

25.8 Rising Edge and Reverse Dead Band

In Half-Bridge mode, the rising edge dead band delays the turn-on of the CWGxA output after the rising edge of the CWG data input. In Full-Bridge mode, the reverse dead-band delay is only inserted when changing directions from Forward mode to Reverse mode, and only the modulated output CWGxB is affected.

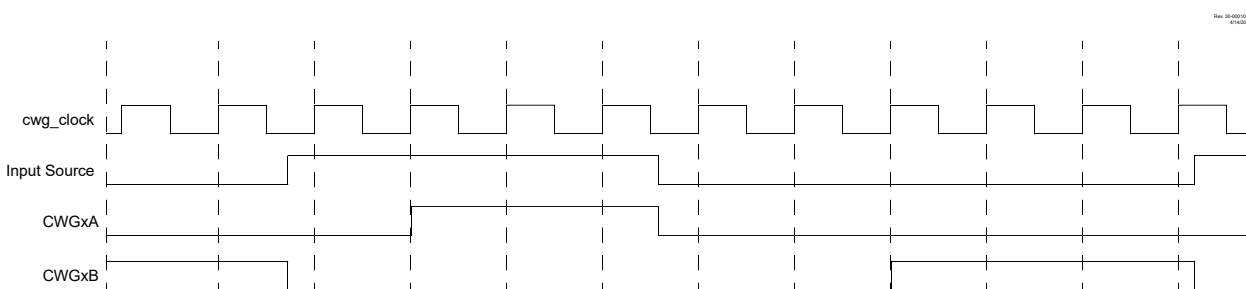
[CWGxDBR](#) determines the duration of the dead-band interval on the rising edge of the input source signal. This duration is from 0 to 64 periods of the CWG clock.

Dead band is always initiated on the edge of the input source signal. A count of zero indicates that no dead band is present.

If the input source signal reverses polarity before the dead-band count is completed, then no signal will be seen on the respective output.

The CWGxDBR register value is double-buffered. When [EN](#) = 0, the buffer is loaded when CWGxDBR is written. When [EN](#) = 1, the buffer will be loaded at the rising edge following the first falling edge of the data input, after the [LD](#) bit is set. Refer to the following figure for an example.

Figure 25-12. Dead-Band Operation, CWGxDBR = 0x01, CWGxDBF = 0x02



25.9 Falling Edge and Forward Dead Band

In Half-Bridge mode, the falling edge dead band delays the turn-on of the CWGxB output at the falling edge of the CWG data input. In Full-Bridge mode, the forward dead-band delay is only inserted when changing directions from Reverse mode to Forward mode, and only the modulated output CWGxD is affected.

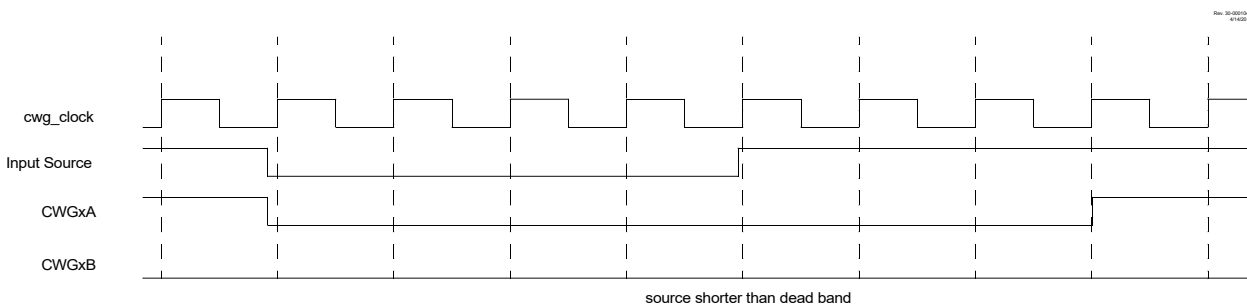
The [CWGxDBF](#) register determines the duration of the dead-band interval on the falling edge of the input source signal. This duration is from zero to 64 periods of CWG clock.

Dead-band delay is always initiated on the edge of the input source signal. A count of zero indicates that no dead band is present.

If the input source signal reverses polarity before the dead-band count is completed, then no signal will be seen on the respective output.

The CWGxDBF register value is double-buffered. When $EN = 0$, the buffer is loaded when CWGxDBF is written. When $EN = 1$, then the buffer will be loaded at the rising edge following the first falling edge of the data input after the LD is set. Refer to the following figure for an example.

Figure 25-13. Dead-Band Operation, CWGxDBR = 0x03, CWGxDBF = 0x06, Source Shorter Than Dead Band



25.10 Dead-Band Jitter

When the rising and falling edges of the input source are asynchronous to the CWG clock, it creates jitter in the dead-band time delay. The maximum jitter is equal to one CWG clock period. Refer to the equations below for more details.

Equation 25-1. Dead-Band Delay Time Calculation

$$T_{DEAD - BAND_MIN} = \frac{1}{F_{CWG_CLOCK}} \cdot DBx < 5:0 >$$

$$T_{DEAD - BAND_MAX} = \frac{1}{F_{CWG_CLOCK}} \cdot DBx < 5:0 > + 1$$

$$T_{JITTER} = T_{DEAD - BAND_MAX} - T_{DEAD - BAND_MIN}$$

$$T_{JITTER} = \frac{1}{F_{CWG_CLOCK}}$$

$$T_{DEAD - BAND_MAX} = T_{DEAD - BAND_MIN} + T_{JITTER}$$

Equation 25-2. Dead-Band Delay Example Calculation

$$DBx < 5:0 > = 0x0A = 10$$

$$F_{CWG_CLOCK} = 8 \text{ MHz}$$

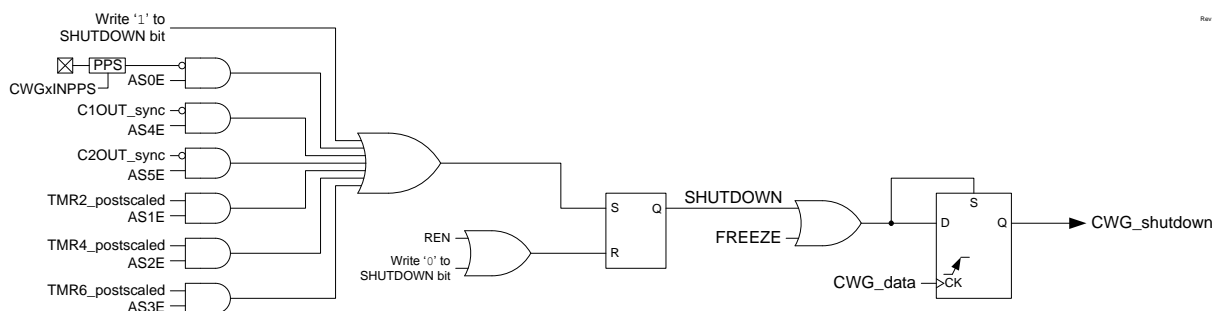
$$T_{JITTER} = \frac{1}{8 \text{ MHz}} = 125 \text{ ns}$$

$$T_{DEAD - BAND_MIN} = 125 \text{ ns} \cdot 10 = 125 \text{ } \mu\text{s}$$

$$T_{DEAD - BAND_MAX} = 1.25 \text{ } \mu\text{s} + 0.125 \text{ } \mu\text{s} = 1.37 \text{ } \mu\text{s}$$

25.11 Auto-Shutdown

Auto-shutdown is a method to immediately override the CWG output levels with specific overrides that allow for safe shutdown of the circuit. The Shutdown state can be either cleared automatically or held until cleared by software. The auto-shutdown circuit is illustrated in the following figure.

Figure 25-14. CWG Shutdown Block Diagram

25.11.1 Shutdown

The Shutdown state can be entered by either of the following two methods:

- Software Generated
- External Input

25.11.1.1 Software Generated Shutdown

Setting the **SHUTDOWN** bit will force the CWG into the shutdown state.

When the auto-restart is disabled, the shutdown state will persist as long as the SHUTDOWN bit is set.

When auto-restart is enabled, the SHUTDOWN bit will clear automatically and resume operation on the next rising edge event. The SHUTDOWN bit indicates when a shutdown condition exists. The bit may be set or cleared in software or by hardware.

25.11.1.2 External Input Source

External shutdown inputs provide the fastest way to safely suspend CWG operation in the event of a Fault condition. When any of the selected shutdown inputs goes active, the CWG outputs will immediately go to the selected override levels without software delay. The override levels are selected by the **LSBD** and **LSAC** bits. Several input sources can be selected to cause a shutdown condition. All input sources are active-low. The shutdown input sources are individually enabled by the **ASyE** bits as shown in the following table:

Table 25-2. Shutdown Sources

| ASyE | Source |
|------|---|
| AS7E | CLC6_out (low causes shutdown) |
| AS6E | CLC2_out (low causes shutdown) |
| AS5E | CMP2_out (low causes shutdown) |
| AS4E | CMP1_out (low causes shutdown) |
| AS3E | TMR6_postscaled (high causes shutdown) |
| AS2E | TMR4_postscaled (high causes shutdown) |
| AS1E | TMR2_postscaled (high causes shutdown) |
| AS0E | Pin selected by CWGxPPS (low causes shutdown) |



Important: Shutdown inputs are level sensitive, not edge sensitive. The shutdown state cannot be cleared, except by disabling auto-shutdown, as long as the shutdown input level persists.

25.11.1.3 Pin Override Levels

The levels driven to the CWG outputs during an auto-shutdown event are controlled by the [LSBD](#) and [LSAC](#) bits. The LSBD bits control CWGxB/D output levels, while the LSAC bits control the CWGxA/C output levels.

25.11.1.4 Auto-Shutdown Interrupts

When an auto-shutdown event occurs, either by software or hardware setting SHUTDOWN, the CWGxIF flag bit of the PIRx register is set.

Related Links

[PIR7](#)

PIR7

25.11.2 Auto-Shutdown Restart

After an auto-shutdown event has occurred, there are two ways to resume operation:

- Software controlled
- Auto-restart

In either case, the shutdown source must be cleared before the restart can take place. That is, either the shutdown condition must be removed, or the corresponding [ASyE](#) bit must be cleared.

25.11.2.1 Software-Controlled Restart

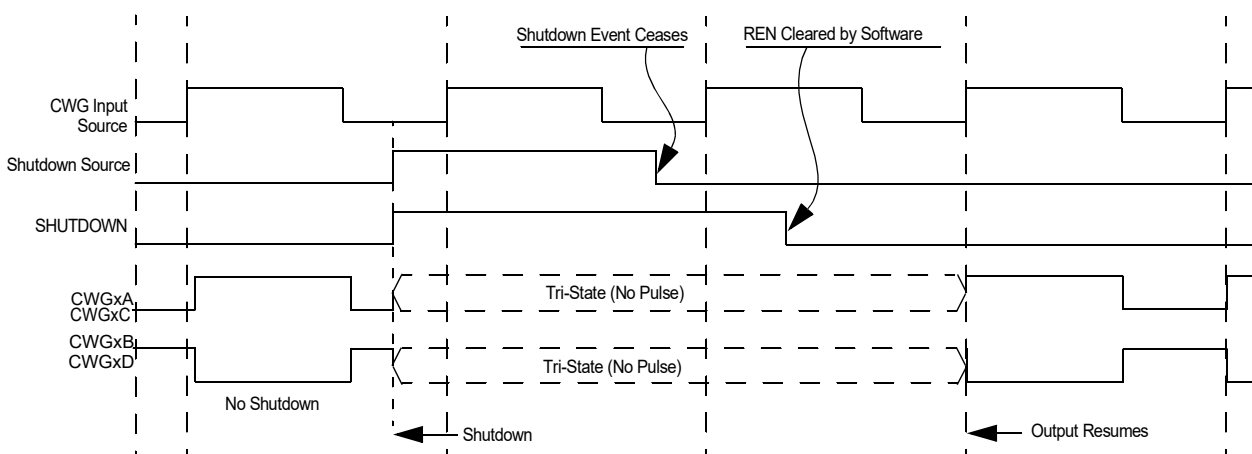
When the [REN](#) bit is clear ($REN = 0$), the CWG module must be restarted after an auto-shutdown event through software.

Once all auto-shutdown sources are removed, the software must clear SHUTDOWN. Once SHUTDOWN is cleared, the CWG module will resume operation upon the first rising edge of the CWG data input.



Important: The SHUTDOWN bit cannot be cleared in software if the auto-shutdown condition is still present.

Figure 25-15. Shutdown Functionality, Auto-Restart Disabled ($REN = 0$, $LSAC = 01$, $LSBD = 01$)



25.11.2.2 Auto-Restart

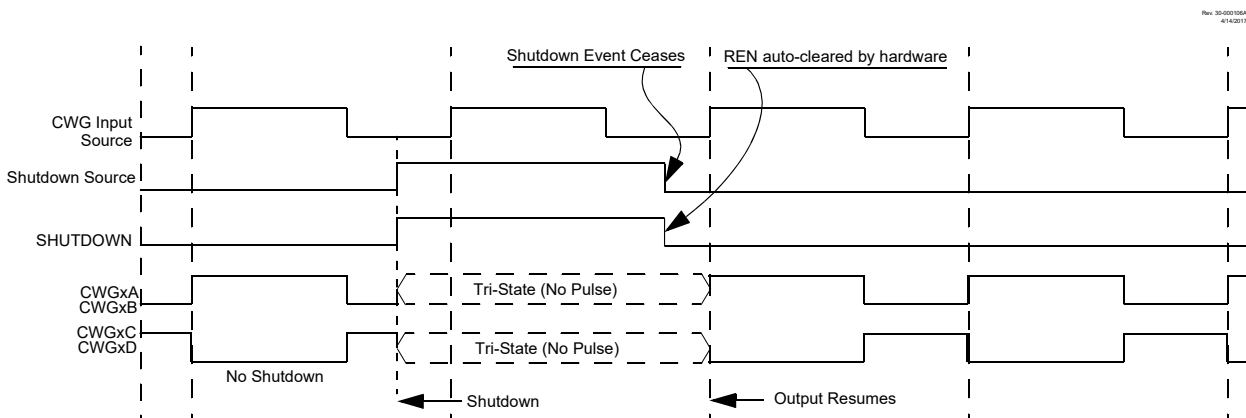
When the REN bit is set ($REN = 1$), the CWG module will restart from the shutdown state automatically.

Once all auto-shutdown conditions are removed, the hardware will automatically clear SHUTDOWN. Once SHUTDOWN is cleared, the CWG module will resume operation upon the first rising edge of the CWG data input.



Important: The SHUTDOWN bit cannot be cleared in software if the auto-shutdown condition is still present.

Figure 25-16. Shutdown Functionality, Auto-Restart Enabled (REN = 1, LSAC = 01, LSB0 = 01)



25.12 Operation During Sleep

The CWG module operates independently from the system clock and will continue to run during Sleep, provided that the clock and input sources selected remain active.

The HFINTOSC remains active during Sleep when all the following conditions are met:

- CWG module is enabled
- Input source is active
- HFINTOSC is selected as the clock source, regardless of the system clock source selected

In other words, if the HFINTOSC is simultaneously selected as the system clock and the CWG clock source, when the CWG is enabled and the input source is active, then the CPU will go Idle during Sleep, but the HFINTOSC will remain active and the CWG will continue to operate. This will have a direct effect on the Sleep mode current.

25.13 Configuring the CWG

1. Ensure that the TRIS control bits corresponding to CWG outputs are set so that all are configured as inputs, ensuring that the outputs are inactive during setup. External hardware must ensure that pin levels are held to safe levels.
2. Clear the **EN** bit, if not already cleared.
3. Configure the **MODE** bits to set the output operating mode.
4. Configure the **POLy** bits to set the output polarities.
5. Configure the **ISM** bits to select the data input source.
6. If a Steering mode is selected, configure the **STRy** bits to select the desired output on the CWG outputs.
7. Configure the **LSBD** and **LSAC** bits to select the Auto-Shutdown Output Override states (this is necessary even if not using auto-shutdown because start-up will be from a Shutdown state).

8. If auto-restart is desired, set the **REN** bit.
9. If auto-shutdown is desired, configure the **ASyE** bits to select the shutdown source.
10. Set the desired rising and falling dead-band times with the CWGxDBR and CWGxDBF registers.
11. Select the clock source with the **CS** bits.
12. Set the EN bit to enable the module.
13. Clear the TRIS bits that correspond to the CWG outputs to set them as outputs.

If auto-restart is to be used, set the REN bit, and the SHUTDOWN bit will be cleared automatically. Otherwise, clear the SHUTDOWN bit in software to start the CWG.

25.14 Register Summary - CWG Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|----------|------|-----------|------|-----------|-----------|------|------|
| 0x00 ... 0x0F3A | Reserved | | | | | | | | | |
| 0x0F3B | CWG1CLK | 7:0 | | | | | | | | CS |
| 0x0F3C | CWG1ISM | 7:0 | | | | | ISM[3:0] | | | |
| 0x0F3D | CWG1DBR | 7:0 | | | DBR[5:0] | | | | | |
| 0x0F3E | CWG1DBF | 7:0 | | | DBF[5:0] | | | | | |
| 0x0F3F | CWG1CON0 | 7:0 | EN | LD | | | | MODE[2:0] | | |
| 0x0F40 | CWG1CON1 | 7:0 | | | IN | | POLD | POLC | POLB | POLA |
| 0x0F41 | CWG1AS0 | 7:0 | SHUTDOWN | REN | LSBD[1:0] | | LSAC[1:0] | | | |
| 0x0F42 | CWG1AS1 | 7:0 | AS7E | AS6E | AS5E | AS4E | AS3E | AS2E | AS1E | AS0E |
| 0x0F43 | CWG1STR | 7:0 | OVRD | OVRC | OVRB | OVRA | STRD | STRC | STRB | STRA |

25.15 Register Definitions: CWG Control

Long bit name prefixes for the CWG peripherals are shown in the table below. Refer to the “**Long Bit Names**” section for more information.

Table 25-3. CWG Bit Name Prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| CWG1 | CWG1 |

25.15.1 CWGxCON0**Name:** CWGxCON0**Address:** 0x0F3F

CWG Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|--------|---|---|---|-----------|-----|-----|
| | EN | LD | | | | MODE[2:0] | | |
| Access | R/W | R/W/HC | | | | R/W | R/W | R/W |
| Reset | 0 | 0 | | | | 0 | 0 | 0 |

Bit 7 – EN CWG1 Enable bit

| Value | Description |
|-------|--------------------|
| 1 | Module is enabled |
| 0 | Module is disabled |

Bit 6 – LD CWG1 Load Buffers bit⁽¹⁾

| Value | Description |
|-------|--|
| 1 | Dead-band count buffers to be loaded on CWG data rising edge, following first falling edge after this bit is set |
| 0 | Buffers remain unchanged |

Bits 2:0 – MODE[2:0] CWG1 Mode bits

| Value | Description |
|-------|---|
| 111 | Reserved |
| 110 | Reserved |
| 101 | CWG outputs operate in Push-Pull mode |
| 100 | CWG outputs operate in Half-Bridge mode |
| 011 | CWG outputs operate in Reverse Full-Bridge mode |
| 010 | CWG outputs operate in Forward Full-Bridge mode |
| 001 | CWG outputs operate in Synchronous Steering mode |
| 000 | CWG outputs operate in Asynchronous Steering mode |

Note:

1. This bit can only be set after EN = 1; it cannot be set in the same cycle when EN is set.

25.15.2 CWGxCON1**Name:** CWGxCON1**Address:** 0x0F40

CWG Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----|---|------|------|------|------|
| | | | IN | | POLD | POLC | POLB | POLA |
| Access | | | RO | | R/W | R/W | R/W | R/W |
| Reset | | | x | | 0 | 0 | 0 | 0 |

Bit 5 – IN CWG Input Value bit (read-only)

| Value | Description |
|-------|------------------------|
| 1 | CWG input is a logic 1 |
| 0 | CWG input is a logic 0 |

Bits 0, 1, 2, 3 – POLy CWG Output 'y' Polarity bit

| Value | Description |
|-------|------------------------------------|
| 1 | Signal output is inverted polarity |
| 0 | Signal output is normal polarity |

25.15.3 CWGxCLK

Name: CWGxCLK
Address: 0x0F3B

CWGx Clock Input Selection Register

| | | | | | | | | |
|--------|---|---|---|---|---|---|---|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | | | CS |
| Access | | | | | | | | R/W |
| Reset | | | | | | | | 0 |

Bit 0 – CS Clock Source
CWG Clock Source Selection Select bits

| Value | Description |
|-------|---|
| 1 | HFINTOSC (remains operating during Sleep) |
| 0 | Fosc |

25.15.4 CWGxISM

Name: CWGxISM

Address: 0x0F3C

CWGx Input Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | ISM[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – ISM[3:0] CWG Data Input Source Select bits

Table 25-4. CWG Data Input Sources

| ISM | Data Source |
|------|-------------------------|
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0111 | DSM_out |
| 0110 | CMP2_out |
| 0101 | CMP1_out |
| 0100 | PWM4_out |
| 0011 | PWM3_out |
| 0010 | CCP2_out |
| 0001 | CCP1_out |
| 0000 | Pin selected by CWGxPPS |

25.15.5 CWGxSTR

Name: CWGxSTR

Address: 0x0F43

CWG Steering Control Register⁽¹⁾

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|------|------|------|------|------|------|------|
| | OVRD | OVRC | OVRB | OVRA | STRD | STRC | STRB | STRA |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 4, 5, 6, 7 – OVRy Steering Data OVR'y' bit

| Value | Condition | Description |
|-------|-----------------------|--|
| x | STRy = 1 | CWGx'y' output has the CWG data input waveform with polarity control from the POLy bit |
| 1 | STRy = 0 and POLy = x | CWGx'y' output is high |
| 0 | STRy = 0 and POLy = x | CWGx'y' output is low |

Bits 0, 1, 2, 3 – STRy STR'y' Steering Enable bit⁽²⁾

| Value | Description |
|-------|--|
| 1 | CWGx'y' output has the CWG data input waveform with polarity control from the POLy bit |
| 0 | CWGx'y' output is assigned to value of the OVRy bit |

Notes:

1. The bits in this register apply only when MODE = '00x' (see [CWGxCON0](#) and the “Steering Modes” section).
2. This bit is double-buffered when MODE = '001'.

25.15.6 CWGxAS0

Name: CWGxAS0
Address: 0x0F41

CWG Auto-Shutdown Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|-----|-----------|-----|-----------|-----|---|---|
| | SHUTDOWN | REN | LSBD[1:0] | | LSAC[1:0] | | | |
| Access | R/W/HS/HC | R/W | R/W | R/W | R/W | R/W | | |
| Reset | 0 | 0 | 0 | 1 | 0 | 1 | | |

Bit 7 – SHUTDOWN Auto-Shutdown Event Status bit^(1,2)

| Value | Description |
|-------|-------------------------------------|
| 1 | An Auto-Shutdown state is in effect |
| 0 | No auto-shutdown event has occurred |

Bit 6 – REN Auto-Restart Enable bit

| Value | Description |
|-------|--------------------------|
| 1 | Auto-restart is enabled |
| 0 | Auto-restart is disabled |

Bits 5:4 – LSBD[1:0] CWGxB and CWGxD Auto-Shutdown State Control bits

| Value | Description |
|-------|--|
| 11 | A logic '1' is placed on CWGxB/D when an auto-shutdown event occurs |
| 10 | A logic '0' is placed on CWGxB/D when an auto-shutdown event occurs |
| 01 | Pin is tri-stated on CWGxB/D when an auto-shutdown event occurs |
| 00 | The Inactive state of the pin, including polarity, is placed on CWGxB/D after the required dead-band interval when an auto-shutdown event occurs |

Bits 3:2 – LSAC[1:0] CWGxA and CWGxC Auto-Shutdown State Control bits

| Value | Description |
|-------|--|
| 11 | A logic '1' is placed on CWGxA/C when an auto-shutdown event occurs |
| 10 | A logic '0' is placed on CWGxA/C when an auto-shutdown event occurs |
| 01 | Pin is tri-stated on CWGxA/C when an auto-shutdown event occurs |
| 00 | The Inactive state of the pin, including polarity, is placed on CWGxA/C after the required dead-band interval when an auto-shutdown event occurs |

Notes:

1. This bit may be written while EN = 0 ([CWGxCON0](#)), to place the outputs into the shutdown configuration.
2. The outputs will remain in Auto-Shutdown state until the next rising edge of the CWG data input after this bit is cleared.

25.15.7 CWGxAS1

Name: CWGxAS1

Address: 0x0F42

CWG Auto-Shutdown Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|------|------|------|------|------|------|------|
| | AS7E | AS6E | AS5E | AS4E | AS3E | AS2E | AS1E | AS0E |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – ASyE CWG Auto-Shutdown Source ASyE Enable bit⁽¹⁾

Table 25-5. Shutdown Sources

| ASyE | Source |
|------|---|
| AS7E | CLC6_out (low causes shutdown) |
| AS6E | CLC2_out (low causes shutdown) |
| AS5E | CMP2_out (low causes shutdown) |
| AS4E | CMP1_out (low causes shutdown) |
| AS3E | TMR6_postscaled (high causes shutdown) |
| AS2E | TMR4_postscaled (high causes shutdown) |
| AS1E | TMR2_postscaled (high causes shutdown) |
| AS0E | Pin selected by CWGxPPS (low causes shutdown) |

| Value | Description |
|-------|---|
| 1 | Auto-shutdown for source ASyE is enabled |
| 0 | Auto-shutdown for source ASyE is disabled |

Notes:

1. This bit may be written while EN = 0 ([CWGxCON0](#)), to place the outputs into the shutdown configuration.
2. The outputs will remain in Auto-Shutdown state until the next rising edge of the CWG data input after this bit is cleared.

25.15.8 CWGxDBR**Name:** CWGxDBR**Address:** 0x0F3D

CWG Rising Dead-Band Count Register

| | | | | | | | | |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | DBR[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – DBR[5:0] CWG Rising Edge-Triggered Dead-Band Count bits

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

| Value | Description |
|-------|---|
| n | Dead band is active no less than n, and no more than n+1, CWG clock periods after the rising edge |
| 0 | 0 CWG clock periods. Dead-band generation is bypassed |

25.15.9 CWGxDBF**Name:** CWGxDBF**Address:** 0x0F3E

CWG Falling Dead-Band Count Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| | | | DBF[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – DBF[5:0] CWG Falling Edge-Triggered Dead-Band Count bits

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

| Value | Description |
|-------|--|
| n | Dead band is active no less than n, and no more than n+1, CWG clock periods after the falling edge |
| 0 | 0 CWG clock periods. Dead-band generation is bypassed |

26. CLC - Configurable Logic Cell

The Configurable Logic Cell (CLC) module provides programmable logic that operates outside the speed limitations of software execution. The logic cell takes up to 64 input signals and, through the use of configurable gates, reduces the 64 inputs to four logic lines that drive one of eight selectable single-output logic functions.

Input sources are a combination of the following:

- I/O pins
- Internal clocks
- Peripherals
- Register bits

The output can be directed internally to peripherals and to an output pin.

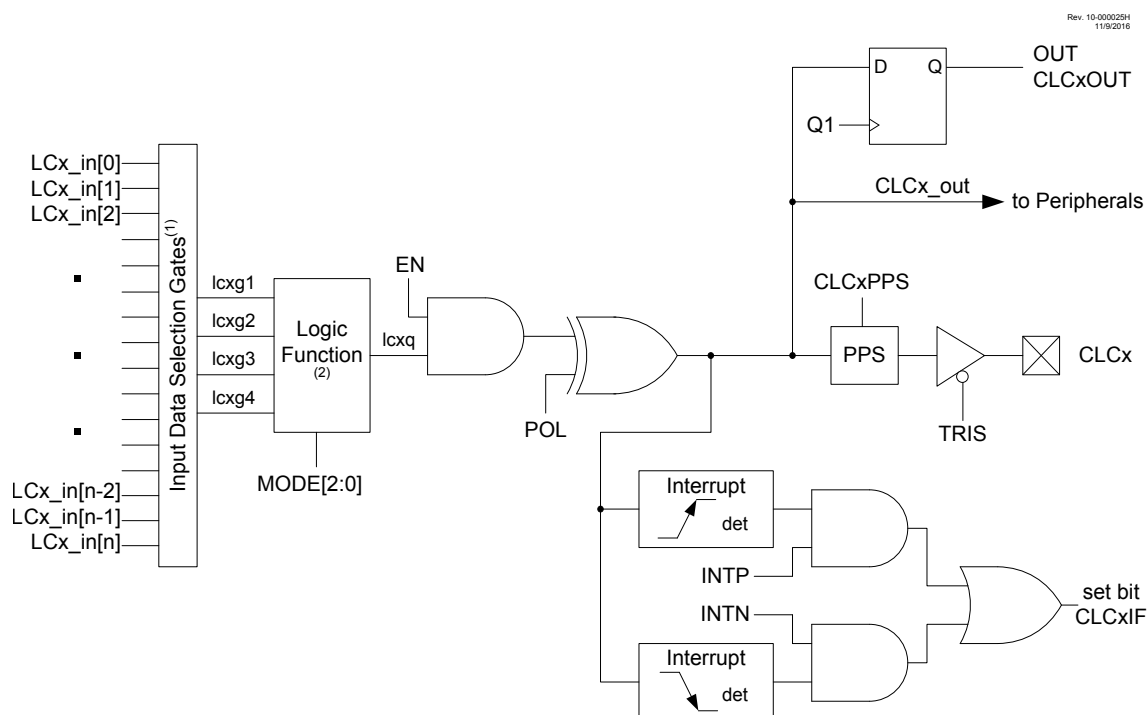


Important: There are several CLC instances on this device. Throughout this section, the lower case 'x' in register names is a generic reference to the CLC instance number. For example, the first instance of the control register is CLC1CON and is generically described in this chapter as CLCxCON.

The following figure is a simplified diagram showing signal flow through the CLC. Possible configurations include:

- Combinatorial Logic:
 - AND
 - NAND
 - AND-OR
 - AND-OR-INVERT
 - OR-XOR
 - OR-XNOR
- Latches:
 - S-R
 - Clocked D with Set and Reset
 - Transparent D with Set and Reset
 - Clocked J-K with Reset

Figure 26-1. CLC Simplified Block Diagram



Notes:

1. See [Figure 26-2](#) for input data selection and gating.
2. See [Figure 26-3](#) for programmable logic functions.

26.1 CLC Setup

Programming the CLC module is performed by configuring the four stages in the logic signal flow. The four stages are:

- Data selection
- Data gating
- Logic function selection
- Output polarity

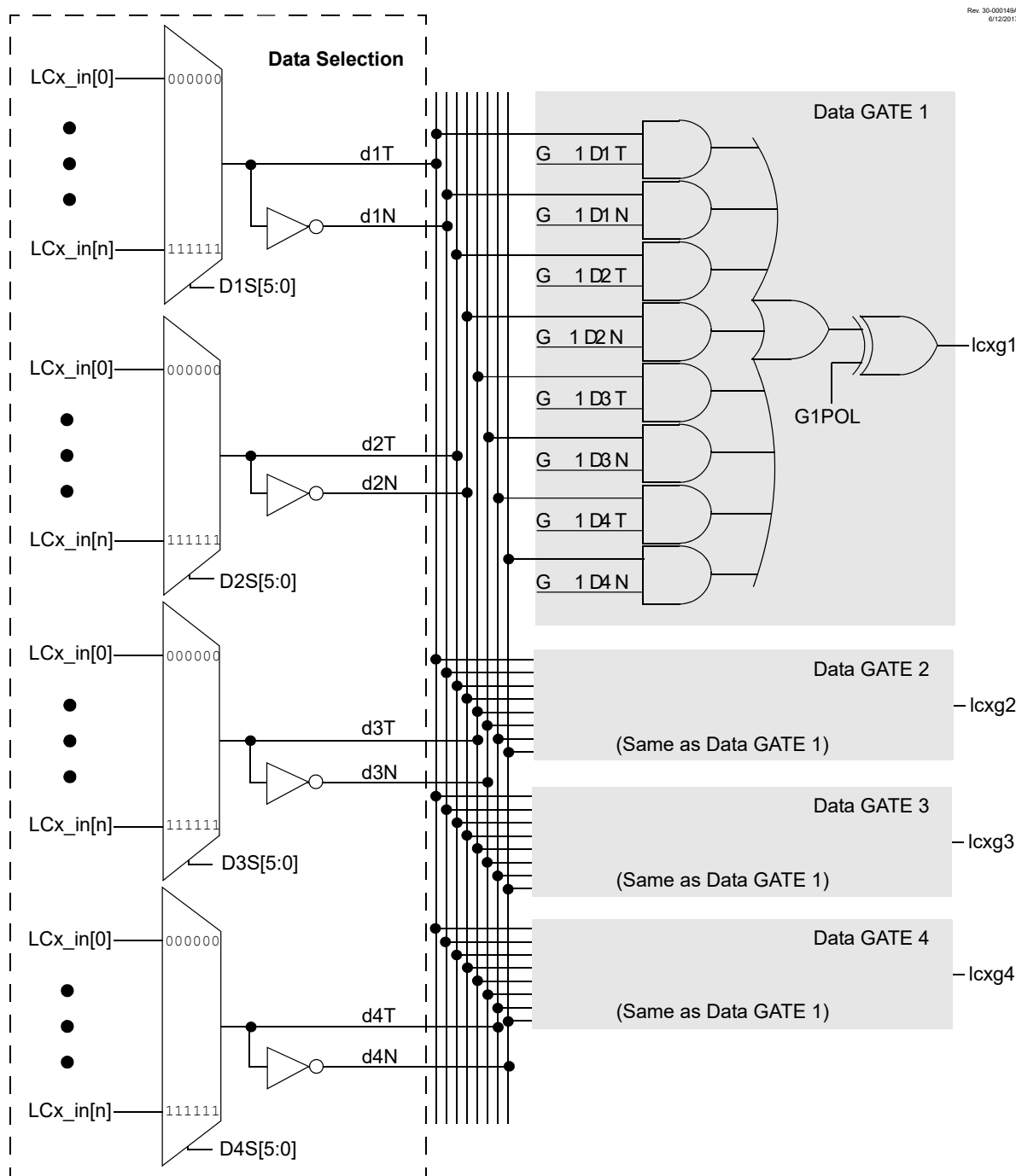
Each stage is set at run time by writing to the corresponding CLC Special Function Registers (SFR). This has an extra advantage of permitting logic reconfiguration on-the-fly during program execution.

26.1.1 Data Selection

There are 64 signals available as inputs to the configurable logic. Four 64-input multiplexers are used to select the inputs to pass on to the next stage.

Data selection is through four multiplexers as indicated on the left side of the following diagram. Data inputs in the figure are identified by a generic numbered input name.

Figure 26-2. Input Data Selection and Gating



Note: All controls are undefined at power-up.

The [CLCxSEL0](#), [CLCxSEL1](#), [CLCxSEL2](#), and [CLCxSEL3](#) Data Input Source registers correlate the generic input name to the actual signal for each CLC module. The column labeled 'DyS Value' indicates the MUX selection code for the selected data input. DyS is an abbreviation for the MUX select input codes: D1S through D4S where 'y' is the gate number.



Important: Data selections are undefined at power-up.

26.1.2 Data Gating

Outputs from the input multiplexers are directed to the desired logic function input through the data gating stage. Each data gate can direct any combination of the four selected inputs.

The gate stage is more than just signal direction. The gate can be configured to direct each input signal as inverted or noninverted data. Directed signals are ANDed together in each gate. The output of each gate can be inverted before going on to the logic function stage.

The gating is in essence a 1-to-4 input AND/NAND/OR/NOR gate. When every input is inverted and the output is inverted, the gate is an AND of all enabled data inputs. When the inputs and output are not inverted, the gate is an OR or all enabled inputs.

The following table summarizes the basic logic that can be obtained in gate 1 by using the gate logic select bits. The table shows the logic of four input variables, but each gate can be configured to use less than four. If no inputs are selected, the output will be zero or one, depending on the gate output polarity bit.

Table 26-1. Data Gating Logic

| CLCxGLSy | GyPOL | Gate Logic |
|----------|-------|------------|
| 0x55 | 1 | AND |
| 0x55 | 0 | NAND |
| 0xAA | 1 | NOR |
| 0xAA | 0 | OR |
| 0x00 | 0 | Logic 0 |
| 0x00 | 1 | Logic 1 |

It is possible (but not recommended) to select both the true and negated values of an input. When this is done, the gate output is zero, regardless of the other inputs, but may emit logic glitches (transient-induced pulses). If the output of the channel must be zero or one, the recommended method is to set all gate bits to zero and use the gate polarity bit to set the desired level.

Data gating is configured with the logic gate select registers as follows:

- Gate 1: [CLCxGLS0](#)
- Gate 2: [CLCxGLS1](#)
- Gate 3: [CLCxGLS2](#)
- Gate 4: [CLCxGLS3](#)

Register number suffixes are different than the gate numbers because other variations of this module have multiple gate selections in the same register.

Data gating is indicated in the right side of [Figure 26-2](#). Only one gate is shown in detail. The remaining three gates are configured identically with the exception that the data enables correspond to the enables for that gate.

26.1.3 Logic Function

There are eight available logic functions including:

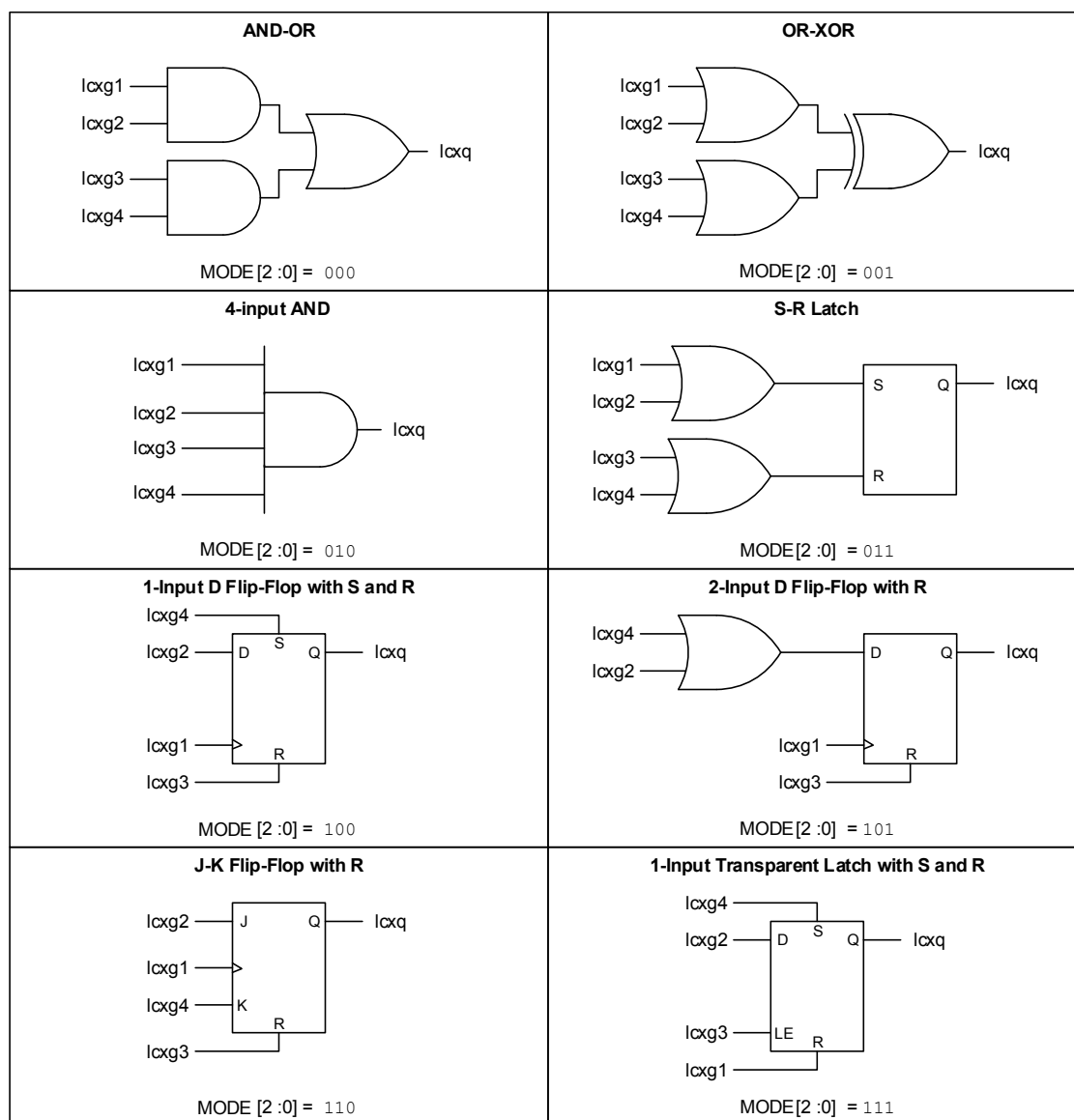
- AND-OR
- OR-XOR
- AND

- S-R Latch
- D Flip-Flop with Set and Reset
- D Flip-Flop with Reset
- J-K Flip-Flop with Reset
- Transparent Latch with Set and Reset

Logic functions are shown in the following diagram. Each logic function has four inputs and one output. The four inputs are the four data gate outputs of the previous stage. The output is fed to the inversion stage and from there to other peripherals, an output pin, and back to the CLC itself.

Figure 26-3. Programmable Logic Functions

Rev: 10-000122B
9/13/2016



26.1.4 Output Polarity

The last stage in the CLC is the output polarity. Setting the **POL** bit in the CLCxPOL register inverts the output signal from the logic stage. Changing the polarity while the interrupts are enabled will cause an interrupt for the resulting output transition.

26.2 CLC Interrupts

An interrupt will be generated upon a change in the output value of the CLCx when the appropriate interrupt enables are set. A rising edge detector and a falling edge detector are present in each CLC for this purpose.

The CLCxIF bit of the associated PIR register will be set when either edge detector is triggered and its associated enable bit is set. The **INTP** enables rising edge interrupts and the **INTN** bit enables falling edge interrupts.

To fully enable the interrupt, set the following bits:

- CLCxIE bit of the respective PIE register
- **INTP** bit (for a rising edge detection)
- **INTN** bit (for a falling edge detection)
- If priority interrupts are not used
 - Clear the IPEN bit of the INTCON register
 - Set the GIE bit of the INTCON register
 - Set the PEIE bit of the INTCON register
- If the CLC is a high-priority interrupt
 - Set the IPEN bit of the INTCON register
 - Set the CLCxIP bit of the respective IPR register
 - Set the GIEH bit of the INTCON register
- If the CLC is a low-priority interrupt
 - Set the IPEN bit of the INTCON register
 - Clear the CLCxIP bit of the respective IPR register
 - Set the GIEL bit of the INTCON register

The CLCxIF bit of the respective PIR register, must be cleared in software as part of the interrupt service. If another edge is detected while this flag is being cleared, the flag will still be set at the end of the sequence.

26.3 Output Mirror Copies

Mirror copies of all CLCxOUT bits are contained in the **CLCDATA** register. Reading this register reads the outputs of all CLCs simultaneously. This prevents any reading skew introduced by testing or reading the OUT bits in the individual CLCxCON registers.

26.4 Effects of a Reset

The CLCxCON register is cleared to zero as the result of a Reset. All other selection and gating values remain unchanged.

26.5 Operation During Sleep

The CLC module operates independently from the system clock and will continue to run during Sleep, provided that the input sources selected remain active.

The HFINTOSC remains active during Sleep when the CLC module is enabled and the HFINTOSC is selected as an input source, regardless of the system clock source selected.

In other words, if the HFINTOSC is simultaneously selected as the system clock and as a CLC input source, when the CLC is enabled, the CPU will go Idle during Sleep, but the CLC will continue to operate and the HFINTOSC will remain active.

This will have a direct effect on the Sleep mode current.

26.6 CLC Setup Steps

Follow these steps when setting up the CLC:

- Disable CLC by clearing the [EN](#) bit
- Select desired inputs using the [CLCxSEL0](#) through [CLCxSEL3](#) registers
- Clear any associated ANSEL bits
- Set all TRIS bits associated with inputs
- Enable the chosen inputs through the four gates using the [CLCxGLS0](#) through [CLCxGLS3](#) registers
- Select the gate output polarities with the [GyPOL](#) bits
- Select the desired logic function with the [MODE](#) bits
- Select the desired polarity of the logic output with the [POL](#) bit (this step may be combined with the previous gate output polarity step)
- If driving a device pin, set the desired pin PPS control register and also clear the TRIS bit corresponding to that output
- Configure the interrupts (optional). See [CLC Interrupts](#).
- Enable the CLC by setting the [EN](#) bit

26.7 Register Summary - CLC Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|-------|-------|----------|-------|-------|-----------|-------|-------|
| 0x00 ... 0x0E26 | Reserved | | | | | | | | | |
| 0x0E27 | CLC1CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E28 | CLC1POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E29 | CLC1SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E2A | CLC1SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E2B | CLC1SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E2C | CLC1SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E2D | CLC1GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E2E | CLC1GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E2F | CLC1GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E30 | CLC1GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E31 | CLC2CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E32 | CLC2POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E33 | CLC2SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E34 | CLC2SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E35 | CLC2SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E36 | CLC2SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E37 | CLC2GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E38 | CLC2GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E39 | CLC2GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E3A | CLC2GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E3B | CLC3CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E3C | CLC3POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E3D | CLC3SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E3E | CLC3SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E3F | CLC3SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E40 | CLC3SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E41 | CLC3GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E42 | CLC3GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E43 | CLC3GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E44 | CLC3GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E45 | CLC4CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E46 | CLC4POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E47 | CLC4SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E48 | CLC4SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E49 | CLC4SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E4A | CLC4SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E4B | CLC4GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E4C | CLC4GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E4D | CLC4GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E4E | CLC4GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E4F | CLC5CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E50 | CLC5POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E51 | CLC5SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E52 | CLC5SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E53 | CLC5SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E54 | CLC5SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E55 | CLC5GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E56 | CLC5GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E57 | CLC5GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E58 | CLC5GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E59 | CLC6CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E5A | CLC6POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E5B | CLC6SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E5C | CLC6SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E5D | CLC6SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E5E | CLC6SEL3 | 7:0 | | | D4S[5:0] | | | | | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|--------------------------|----------|---------|---------|----------|---------|---------|-----------|---------|---------|
| 0x0E5F | CLC6GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E60 | CLC6GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E61 | CLC6GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E62 | CLC6GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E63 | CLC7CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E64 | CLC7POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E65 | CLC7SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E66 | CLC7SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E67 | CLC7SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E68 | CLC7SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E69 | CLC7GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E6A | CLC7GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E6B | CLC7GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E6C | CLC7GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E6D | CLC8CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E6E | CLC8POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E6F | CLC8SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E70 | CLC8SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E71 | CLC8SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E72 | CLC8SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E73 | CLC8GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E74 | CLC8GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E75 | CLC8GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E76 | CLC8GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E77 | CLCDATA | 7:0 | MLC8OUT | MLC7OUT | MLC6OUT | MLC5OUT | MLC4OUT | MLC3OUT | MLC2OUT | MLC1OUT |

26.8 Register Definitions: Configurable Logic Cell

Related Links

[Long Bit Names](#)

26.8.1 CLCxCON

Name: CLCxCON

Address: 0xE27,0xE31,0xE3B,0xE45,0xE4F,0xE59,0xE63,0xE6D

Configurable Logic Cell Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|------|------|-----------|-----|-----|
| | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| Access | R/W | | RO | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – EN

CLC Enable bit

| Value | Description |
|-------|---|
| 1 | Configurable logic cell is enabled and mixing signals |
| 0 | Configurable logic cell is disabled and has logic zero output |

Bit 5 – OUT

Logic cell output data, after LCPOL. Sampled from CLCxOUT

Bit 4 – INTP

Configurable Logic Cell Positive Edge Going Interrupt Enable bit

| Value | Description |
|-------|---|
| 1 | CLCxIF will be set when a rising edge occurs on CLCxOUT |
| 0 | Rising edges on CLCxOUT have no effect on CLCxIF |

Bit 3 – INTN

Configurable Logic Cell Negative Edge Going Interrupt Enable bit

| Value | Description |
|-------|--|
| 1 | CLCxIF will be set when a falling edge occurs on CLCxOUT |
| 0 | Falling edges on CLCxOUT have no effect on CLCxIF |

Bits 2:0 – MODE[2:0]

Configurable Logic Cell Functional Mode Selection bits

| Value | Description |
|-------|--|
| 111 | Cell is 1-input transparent latch with Set and Reset |
| 110 | Cell is J-K flip-flop with Reset |
| 101 | Cell is 2-input D flip-flop with Reset |
| 100 | Cell is 1-input D flip-flop with Set and Reset |
| 011 | Cell is S-R latch |
| 010 | Cell is 4-input AND |
| 001 | Cell is OR-XOR |
| 000 | Cell is AND-OR |

26.8.2 CLCxPOL

Name: CLCxPOL

Address: 0xE28,0xE32,0xE3C,0xE46,0xE50,0xE5A,0xE64,0xE6E

Signal Polarity Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|---|---|-------|-------|-------|-------|
| | POL | | | | G4POL | G3POL | G2POL | G1POL |
| Access | R/W | | | | R/W | R/W | R/W | R/W |
| Reset | 0 | | | | x | x | x | x |

Bit 7 – POL

CLCxOUT Output Polarity Control bit

| Value | Description |
|-------|--|
| 1 | The output of the logic cell is inverted |
| 0 | The output of the logic cell is not inverted |

Bits 0, 1, 2, 3 – GyPOL

Gate Output Polarity Control bit

Reset States: Default = xxxx

POR/BOR = x

All Other Resets = u

| Value | Description |
|-------|--|
| 1 | The gate output is inverted when applied to the logic cell |
| 0 | The output of the gate is not inverted |

26.8.3 CLCxSELO

Name: CLCxSELO

Address: 0xE29,0xE33,0xE3D,0xE47,0xE51,0xE5B,0xE65,0xE6F

Generic CLCx Data 1 Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| | | | D1S[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – D1S[5:0] CLCx Data 1 Input Selection bits

| DyS Value | CLC Input Source | DyS Value | CLC Input Source |
|-------------|-------------------|-------------|--------------------|
| 111111 [63] | Reserved | 011111 [31] | IOC_flag |
| 111110 [62] | Reserved | 011110 [30] | ZCD_out |
| 111101 [61] | Reserved | 011101 [29] | CMP2_out |
| 111100 [60] | Reserved | 011100 [28] | CMP1_out |
| 111011 [59] | Reserved | 011011 [27] | PWM4_out |
| 111010 [58] | Reserved | 011010 [26] | PWM3_out |
| 111001 [57] | Reserved | 011001 [25] | CCP2_out |
| 111000 [56] | Reserved | 011000 [24] | CCP1_out |
| 110111 [55] | Reserved | 010111 [23] | TMR6_out |
| 110110 [54] | Reserved | 010110 [22] | TMR5_overflow |
| 110101 [53] | Reserved | 010101 [21] | TMR4_out |
| 110100 [52] | Reserved | 010100 [20] | TMR3_overflow |
| 110011 [51] | Reserved | 010011 [19] | TMR2_out |
| 110010 [50] | CWG1B_out | 010010 [18] | TMR1_overflow |
| 110001 [49] | CWG1A_out | 010001 [17] | TMR0_overflow |
| 110000 [48] | SCK2 | 010000 [16] | CLKR_out |
| 101111 [47] | SDO2 | 001111 [15] | ADCRC |
| 101110 [46] | SCK1 | 001110 [14] | SOSC |
| 101101 [45] | SDO1 | 001101 [13] | SFINTOSC (1MHz) |
| 101100 [44] | EUSART2_TX/CK_out | 001100 [12] | MFINTOSC (32 kHz) |
| 101011 [43] | EUSART2_DT_out | 001011 [11] | MFINTOSC (500 kHz) |
| 101010 [42] | EUSART1_TX/CK_out | 001010 [10] | LFINTOSC |
| 101001 [41] | EUSART1_DT_out | 001001 [9] | HFINTOSC |
| 101000 [40] | CLC8_out | 001000 [8] | Fosc |
| 100111 [39] | CLC7_out | 000111 [7] | CLCIN7PPS |
| 100110 [38] | CLC6_out | 000110 [6] | CLCIN6PPS |
| 100101 [37] | CLC5_out | 000101 [5] | CLCIN5PPS |
| 100100 [36] | CLC4_out | 000100 [4] | CLCIN4PPS |
| 100011 [35] | CLC3_out | 000011 [3] | CLCIN3PPS |
| 100010 [34] | CLC2_out | 000010 [2] | CLCIN2PPS |
| 100001 [33] | CLC1_out | 000001 [1] | CLCIN1PPS |
| 100000 [32] | DSM1_out | 000000 [0] | CLCIN0PPS |

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

26.8.4 CLCxSEL1

Name: CLCxSEL1

Address: 0xE2A,0xE34,0xE3E,0xE48,0xE52,0xE5C,0xE66,0xE70

Generic CLCx Data 2 Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| | | | D2S[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – D2S[5:0] CLCx Data 2 Input Selection bits

| DyS Value | CLC Input Source | DyS Value | CLC Input Source |
|-------------|-------------------|-------------|--------------------|
| 111111 [63] | Reserved | 011111 [31] | IOC_flag |
| 111110 [62] | Reserved | 011110 [30] | ZCD_out |
| 111101 [61] | Reserved | 011101 [29] | CMP2_out |
| 111100 [60] | Reserved | 011100 [28] | CMP1_out |
| 111011 [59] | Reserved | 011011 [27] | PWM4_out |
| 111010 [58] | Reserved | 011010 [26] | PWM3_out |
| 111001 [57] | Reserved | 011001 [25] | CCP2_out |
| 111000 [56] | Reserved | 011000 [24] | CCP1_out |
| 110111 [55] | Reserved | 010111 [23] | TMR6_out |
| 110110 [54] | Reserved | 010110 [22] | TMR5_overflow |
| 110101 [53] | Reserved | 010101 [21] | TMR4_out |
| 110100 [52] | Reserved | 010100 [20] | TMR3_overflow |
| 110011 [51] | Reserved | 010011 [19] | TMR2_out |
| 110010 [50] | CWG1B_out | 010010 [18] | TMR1_overflow |
| 110001 [49] | CWG1A_out | 010001 [17] | TMR0_overflow |
| 110000 [48] | SCK2 | 010000 [16] | CLKR_out |
| 101111 [47] | SDO2 | 001111 [15] | ADCRC |
| 101110 [46] | SCK1 | 001110 [14] | SOSC |
| 101101 [45] | SDO1 | 001101 [13] | SFINTOSC (1MHz) |
| 101100 [44] | EUSART2_TX/CK_out | 001100 [12] | MFINTOSC (32 kHz) |
| 101011 [43] | EUSART2_DT_out | 001011 [11] | MFINTOSC (500 kHz) |
| 101010 [42] | EUSART1_TX/CK_out | 001010 [10] | LFINTOSC |
| 101001 [41] | EUSART1_DT_out | 001001 [9] | HFINTOSC |
| 101000 [40] | CLC8_out | 001000 [8] | Fosc |
| 100111 [39] | CLC7_out | 000111 [7] | CLCIN7PPS |
| 100110 [38] | CLC6_out | 000110 [6] | CLCIN6PPS |
| 100101 [37] | CLC5_out | 000101 [5] | CLCIN5PPS |
| 100100 [36] | CLC4_out | 000100 [4] | CLCIN4PPS |
| 100011 [35] | CLC3_out | 000011 [3] | CLCIN3PPS |
| 100010 [34] | CLC2_out | 000010 [2] | CLCIN2PPS |
| 100001 [33] | CLC1_out | 000001 [1] | CLCIN1PPS |
| 100000 [32] | DSM1_out | 000000 [0] | CLCIN0PPS |

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

26.8.5 CLCxSEL2

Name: CLCxSEL2

Address: 0xE2B,0xE35,0xE3F,0xE49,0xE53,0xE5D,0xE67,0xE71

Generic CLCx Data 3 Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| | | | D3S[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – D3S[5:0] CLCx Data 3 Input Selection bits

| DyS Value | CLC Input Source | DyS Value | CLC Input Source |
|-------------|-------------------|-------------|--------------------|
| 111111 [63] | Reserved | 011111 [31] | IOC_flag |
| 111110 [62] | Reserved | 011110 [30] | ZCD_out |
| 111101 [61] | Reserved | 011101 [29] | CMP2_out |
| 111100 [60] | Reserved | 011100 [28] | CMP1_out |
| 111011 [59] | Reserved | 011011 [27] | PWM4_out |
| 111010 [58] | Reserved | 011010 [26] | PWM3_out |
| 111001 [57] | Reserved | 011001 [25] | CCP2_out |
| 111000 [56] | Reserved | 011000 [24] | CCP1_out |
| 110111 [55] | Reserved | 010111 [23] | TMR6_out |
| 110110 [54] | Reserved | 010110 [22] | TMR5_overflow |
| 110101 [53] | Reserved | 010101 [21] | TMR4_out |
| 110100 [52] | Reserved | 010100 [20] | TMR3_overflow |
| 110011 [51] | Reserved | 010011 [19] | TMR2_out |
| 110010 [50] | CWG1B_out | 010010 [18] | TMR1_overflow |
| 110001 [49] | CWG1A_out | 010001 [17] | TMR0_overflow |
| 110000 [48] | SCK2 | 010000 [16] | CLKR_out |
| 101111 [47] | SDO2 | 001111 [15] | ADCRC |
| 101110 [46] | SCK1 | 001110 [14] | SOSC |
| 101101 [45] | SDO1 | 001101 [13] | SFINTOSC (1MHz) |
| 101100 [44] | EUSART2_TX/CK_out | 001100 [12] | MFINTOSC (32 kHz) |
| 101011 [43] | EUSART2_DT_out | 001011 [11] | MFINTOSC (500 kHz) |
| 101010 [42] | EUSART1_TX/CK_out | 001010 [10] | LFINTOSC |
| 101001 [41] | EUSART1_DT_out | 001001 [9] | HFINTOSC |
| 101000 [40] | CLC8_out | 001000 [8] | Fosc |
| 100111 [39] | CLC7_out | 000111 [7] | CLCIN7PPS |
| 100110 [38] | CLC6_out | 000110 [6] | CLCIN6PPS |
| 100101 [37] | CLC5_out | 000101 [5] | CLCIN5PPS |
| 100100 [36] | CLC4_out | 000100 [4] | CLCIN4PPS |
| 100011 [35] | CLC3_out | 000011 [3] | CLCIN3PPS |
| 100010 [34] | CLC2_out | 000010 [2] | CLCIN2PPS |
| 100001 [33] | CLC1_out | 000001 [1] | CLCIN1PPS |
| 100000 [32] | DSM1_out | 000000 [0] | CLCIN0PPS |

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

26.8.6 CLCxSEL3

Name: CLCxSEL3

Address: 0xE2C,0xE36,0xE40,0xE4A,0xE54,0xE5E,0xE68,0xE72

Generic CLCx Data 4 Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|----------|-----|-----|-----|-----|-----|
| | | | D4S[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | x | x | x | x | x | x |

Bits 5:0 – D4S[5:0] CLCx Data 4 Input Selection bits

| DyS Value | CLC Input Source | DyS Value | CLC Input Source |
|-------------|-------------------|-------------|--------------------|
| 111111 [63] | Reserved | 011111 [31] | IOC_flag |
| 111110 [62] | Reserved | 011110 [30] | ZCD_out |
| 111101 [61] | Reserved | 011101 [29] | CMP2_out |
| 111100 [60] | Reserved | 011100 [28] | CMP1_out |
| 111011 [59] | Reserved | 011011 [27] | PWM4_out |
| 111010 [58] | Reserved | 011010 [26] | PWM3_out |
| 111001 [57] | Reserved | 011001 [25] | CCP2_out |
| 111000 [56] | Reserved | 011000 [24] | CCP1_out |
| 110111 [55] | Reserved | 010111 [23] | TMR6_out |
| 110110 [54] | Reserved | 010110 [22] | TMR5_overflow |
| 110101 [53] | Reserved | 010101 [21] | TMR4_out |
| 110100 [52] | Reserved | 010100 [20] | TMR3_overflow |
| 110011 [51] | Reserved | 010011 [19] | TMR2_out |
| 110010 [50] | CWG1B_out | 010010 [18] | TMR1_overflow |
| 110001 [49] | CWG1A_out | 010001 [17] | TMR0_overflow |
| 110000 [48] | SCK2 | 010000 [16] | CLKR_out |
| 101111 [47] | SDO2 | 001111 [15] | ADCRC |
| 101110 [46] | SCK1 | 001110 [14] | SOSC |
| 101101 [45] | SDO1 | 001101 [13] | SFINTOSC (1MHz) |
| 101100 [44] | EUSART2_TX/CK_out | 001100 [12] | MFINTOSC (32 kHz) |
| 101011 [43] | EUSART2_DT_out | 001011 [11] | MFINTOSC (500 kHz) |
| 101010 [42] | EUSART1_TX/CK_out | 001010 [10] | LFINTOSC |
| 101001 [41] | EUSART1_DT_out | 001001 [9] | HFINTOSC |
| 101000 [40] | CLC8_out | 001000 [8] | Fosc |
| 100111 [39] | CLC7_out | 000111 [7] | CLCIN7PPS |
| 100110 [38] | CLC6_out | 000110 [6] | CLCIN6PPS |
| 100101 [37] | CLC5_out | 000101 [5] | CLCIN5PPS |
| 100100 [36] | CLC4_out | 000100 [4] | CLCIN4PPS |
| 100011 [35] | CLC3_out | 000011 [3] | CLCIN3PPS |
| 100010 [34] | CLC2_out | 000010 [2] | CLCIN2PPS |
| 100001 [33] | CLC1_out | 000001 [1] | CLCIN1PPS |
| 100000 [32] | DSM1_out | 000000 [0] | CLCIN0PPS |

Reset States: POR/BOR = xxxxxx

All Other Resets = uuuuuu

26.8.7 CLCxGLS0

Name: CLCxGLS0
Address: 0xE2D,0xE37,0xE41,0xE4B,0xE55,0xE5F,0xE69,0xE73

CLCx Gate1 Logic Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 1, 3, 5, 7 – G1DyT

dyT: Gate1 Data 'y' True (noninverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyT is gated into g1 |
| 0 | dyT is not gated into g1 |

Bits 0, 2, 4, 6 – G1DyN

dyN: Gate1 Data 'y' Negated (inverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyN is gated into g1 |
| 0 | dyN is not gated into g1 |

26.8.8 CLCxGLS1

Name: CLCxGLS1

Address: 0xE2E,0xE38,0xE42,0xE4C,0xE56,0xE60,0xE6A,0xE74

CLCx Gate2 Logic Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 1, 3, 5, 7 – G2DyT

dyT: Gate2 Data 'y' True (noninverted) bit

Reset States: Default = xxxx

POR/BOR = x

All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyT is gated into g2 |
| 0 | dyT is not gated into g2 |

Bits 0, 2, 4, 6 – G2DyN

dyN: Gate2 Data 'y' Negated (inverted) bit

Reset States: Default = xxxx

POR/BOR = x

All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyN is gated into g2 |
| 0 | dyN is not gated into g2 |

26.8.9 CLCxGLS2

Name: CLCxGLS2
Address: 0xE2F,0xE39,0xE43,0xE4D,0xE57,0xE61,0xE6B,0xE75

CLCx Gate3 Logic Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 1, 3, 5, 7 – G3DyT

dyT: Gate3 Data 'y' True (non-inverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyT is gated into g3 |
| 0 | dyT is not gated into g3 |

Bits 0, 2, 4, 6 – G3DyN

dyN: Gate3 Data 'y' Negated (inverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyN is gated into g3 |
| 0 | dyN is not gated into g3 |

26.8.10 CLCxGLS3

Name: CLCxGLS3
Address: 0xE30,0xE3A,0xE44,0xE4E,0xE58,0xE62,0xE6C,0xE76

CLCx Gate4 Logic Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 1, 3, 5, 7 – G4DyT

dyT: Gate4 Data 'y' True (non-inverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyT is gated into g4 |
| 0 | dyT is not gated into g4 |

Bits 0, 2, 4, 6 – G4DyN

dyN: Gate4 Data 'y' Negated (inverted) bit

Reset States: Default = xxxx
POR/BOR = x
All Other Resets = u

| Value | Description |
|-------|--------------------------|
| 1 | dyN is gated into g4 |
| 0 | dyN is not gated into g4 |

26.8.11 CLCDATA

Name: CLCDATA

Address: 0xE77

CLC Data Output Register

Mirror copy of

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|---------|---------|---------|---------|---------|---------|---------|
| | MLC8OUT | MLC7OUT | MLC6OUT | MLC5OUT | MLC4OUT | MLC3OUT | MLC2OUT | MLC1OUT |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 0, 1, 2, 3, 4, 5, 6, 7 – MLCxOUT

Mirror copy of CLCx_out bit

| Value | Description |
|-------|---------------|
| 1 | CLCx_out is 1 |
| 0 | CLCx_out is 0 |

27. DSM - Data Signal Modulator Module

The Data Signal Modulator (DSM) is a peripheral that allows the user to mix a data stream, also known as a modulator signal, with a carrier signal to produce a modulated output.

Both the carrier and the modulator signals are supplied to the DSM module either internally, from the output of a peripheral, or externally through an input pin.

The modulated output signal is generated by performing a logical AND operation of both the carrier and modulator signals, and then provided to the MDOUT pin.

The carrier signal is comprised of two distinct and separate signals. A Carrier High (CARH) signal and a Carrier Low (CARL) signal. During the time in which the modulator (MOD) signal is in a Logic High state, the DSM mixes the CARH signal with the modulator signal. When the modulator signal is in a Logic Low state, the DSM mixes the CARL signal with the modulator signal.

Using this method, the DSM can generate the following types of key modulation schemes:

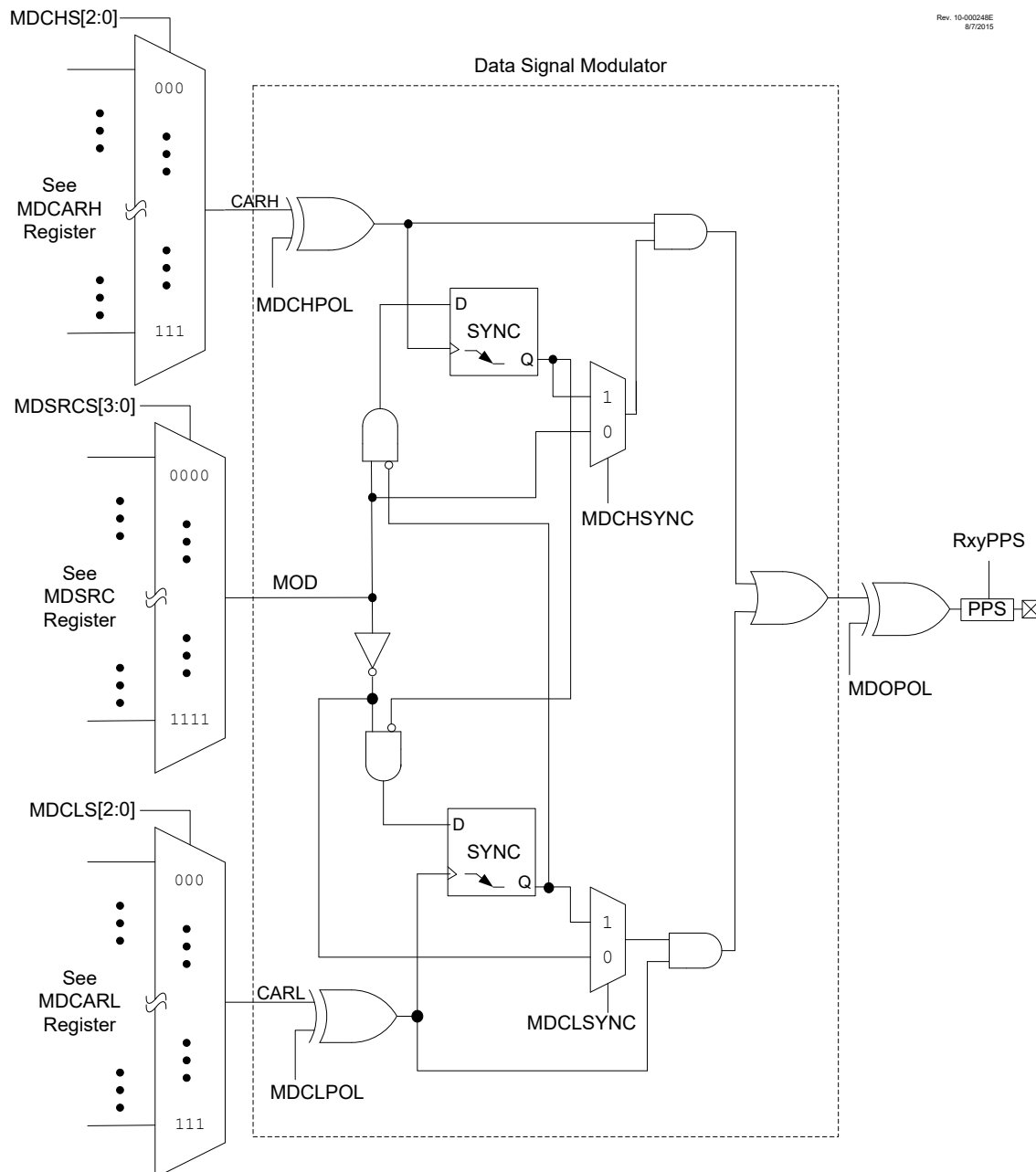
- Frequency-Shift Keying (FSK)
- Phase-Shift Keying (PSK)
- On-Off Keying (OOK)

Additionally, the following features are provided within the DSM module:

- Carrier Synchronization
- Carrier Source Polarity Select
- Programmable Modulator Data
- Modulated Output Polarity Select
- Peripheral Module Disable, which provides the ability to place the DSM module in the lowest power consumption mode

The figure below shows a simplified block diagram of the data signal modulator peripheral.

Figure 27-1. Simplified Block Diagram of the Data Signal Modulator



27.1 DSM Operation

The DSM module can be enabled by setting the [EN](#) bit in the MDCON0 register. Clearing the EN bit, disables the output of the module but retain the carrier and source signal selections. The module will resume operation when the EN bit is set again. The output of the DSM module can be rerouted to several pins using the RxyPPS register. When the EN bit is cleared the output pin is held low.

27.2 Modulator Signal Sources

The modulator signal can be supplied from the following sources:

- EUSART
- MSSP
- CLC
- NCO
- CCP/PWM
- NCO
- internal MDBIT
- I/O pin

The sources are selected using the [SRCS](#) bits in the MDxSRC register.

27.3 Carrier Signal Sources

The carrier high signal and carrier low signal can be supplied from the following sources:

- CCPs
- CLCs
- PWMs
- NCO
- Reference clocks
- System clocks
- I/O pin

The carrier high signal is selected by using the [CHS](#) bits in the MDxCARH register.

The carrier low signal is selected by using the [CLS](#) bits in the MDxCARL register.

27.4 Carrier Synchronization

During the time when the DSM switches between carrier high and carrier low signal sources, the carrier data in the modulated output signal can become truncated. To prevent this, the carrier signal can be synchronized to the modulator signal. When synchronization is enabled, the carrier pulse that is being mixed at the time of the transition is allowed to transition low before the DSM switches over to the next carrier source.

Synchronization is enabled separately for the carrier high and carrier low signal sources. Synchronization for the carrier high signal is enabled by setting the [CHSYNC](#) bit. Synchronization for the carrier low signal is enabled by setting the [CLSYNC](#) bit.

The figures below show the timing diagrams of using various synchronization methods.

Figure 27-2. On Off Keying (OOK) Synchronization

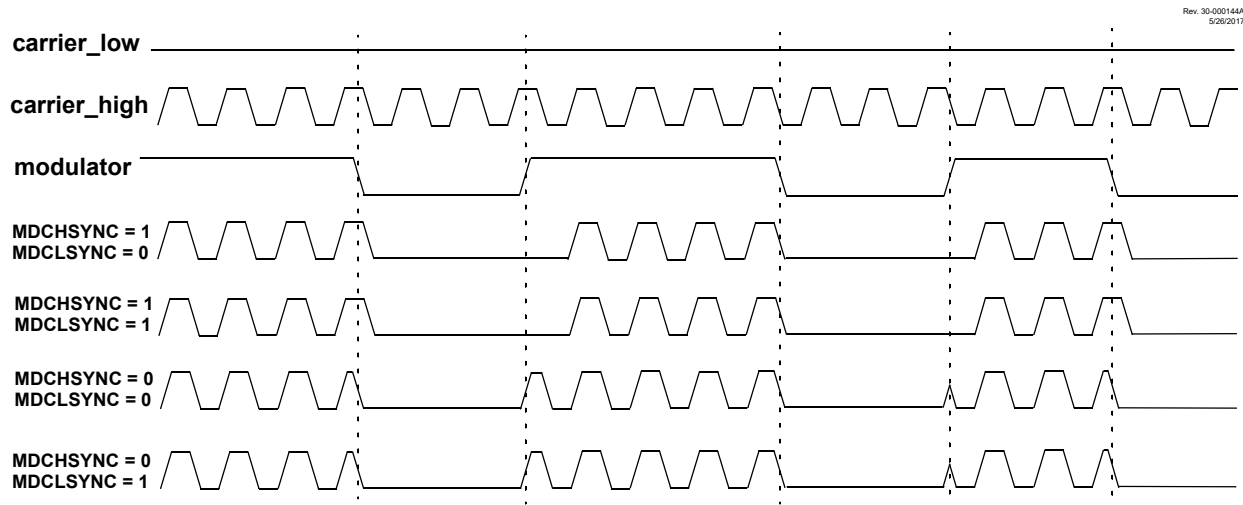


Figure 27-3. No Synchronization (MDCHSYNC = 0, MDCLSYNC = 0)

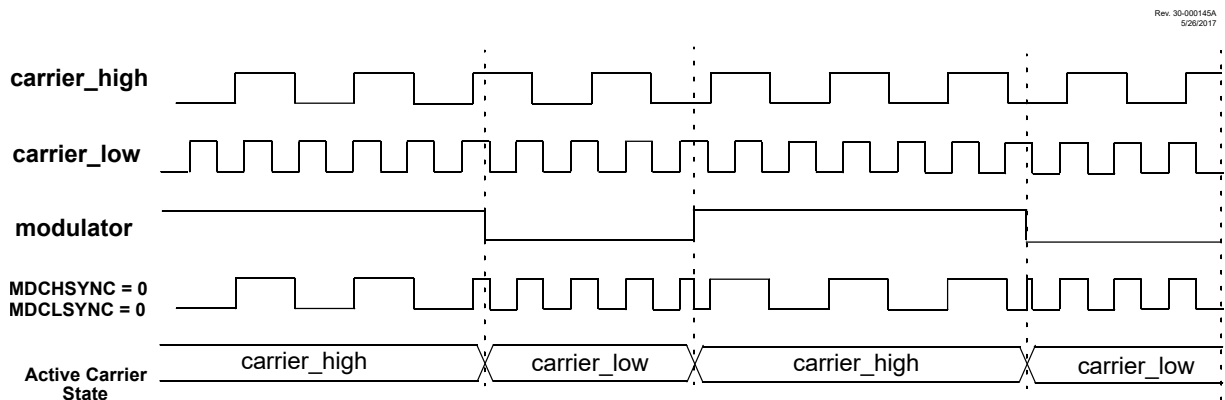


Figure 27-4. Carrier High Synchronization (MDCHSYNC = 1, MDCLSYNC = 0)

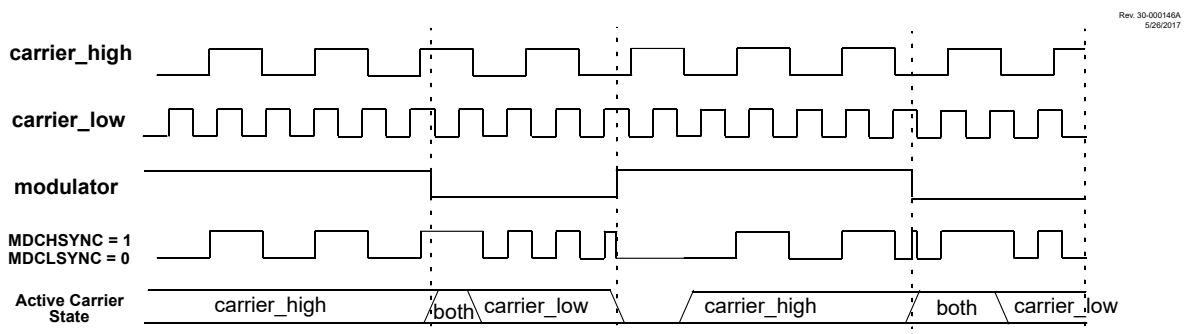


Figure 27-5. Carrier Low Synchronization (MDCHSYNC = 0, MDCLSYNC = 1)

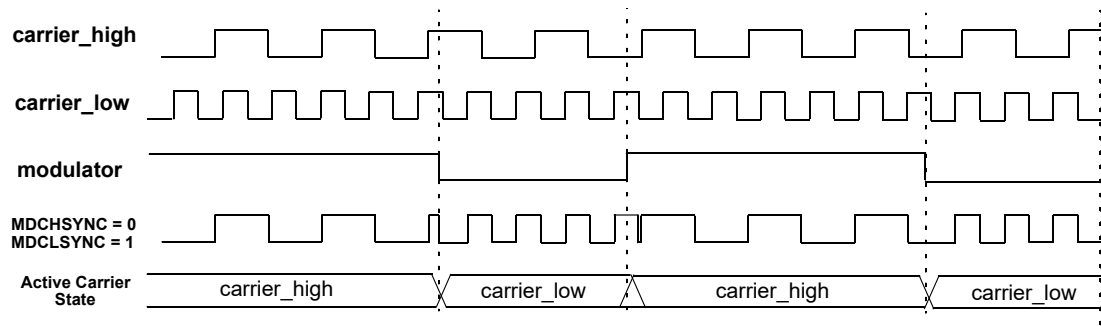
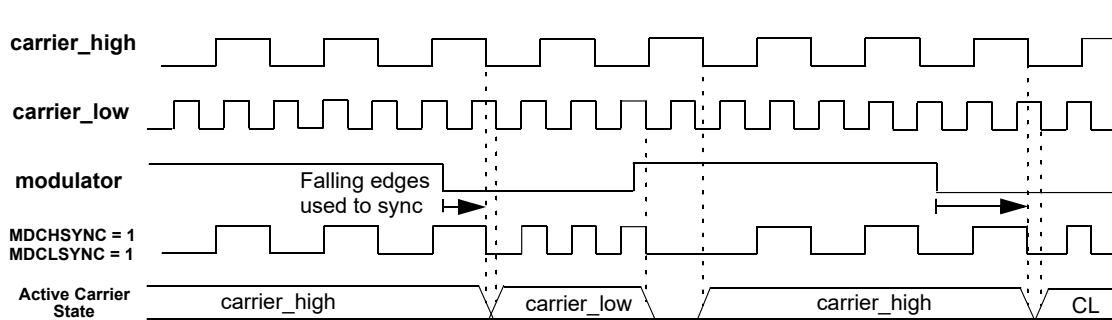


Figure 27-6. Full Synchronization (MDCHSYNC = 1, MDCLSYNC = 1)



27.5 Carrier Source Polarity Select

The signal provided from any selected input source for the carrier high and carrier low signals can be inverted. Inverting the signal for the carrier high and low source is enabled by setting the [CHPOL](#) bit and the [CLPOL](#) bit, respectively.

27.6 Programmable Modulator Data

The [BIT](#) control bit can be selected as the modulation source. This gives the user the ability to provide software driven modulation.

27.7 Modulated Output Polarity

The modulated output signal provided on the DSM pin can also be inverted. Inverting the modulated output signal is enabled by setting the [OPOL](#) bit.

27.8 Operation in Sleep Mode

The DSM can still operate during Sleep, if the carrier and modulator input sources are also still operable during Sleep. Refer to the **“Power-Saving Operation Modes”** section for more details.

Related Links

[Peripheral Operation in Power-Saving Modes](#)

27.9 Effects of a Reset

Upon any device Reset, the DSM module is disabled. The user’s firmware is responsible for initializing the module before enabling the output. All the registers are reset to their default values.

27.10 Peripheral Module Disable

The DSM module can be completely disabled using the PMD module to achieve maximum power saving. When the DSM1MD bit of PMD7 register is set, the DSM module is completely disabled. This

puts the module in its lowest Power Consumption state. When enabled again all the registers of the DSM module default to POR status.

Related Links

[Register Definitions: Peripheral Module Disable](#)

27.11 Register Summary - DSM

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|------------------------|----------|----|---|-------|--------|-----------|---|-------|--------|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0F4B | | | | | | | | | | |
| 0x0F4C | MDCON0 | 7:0 | EN | | OUT | OPOL | | | | BIT |
| 0x0F4D | MDCON1 | 7:0 | | | CHPOL | CHSYNC | | | CLPOL | CLSYNC |
| 0x0F4E | MDSRC | 7:0 | | | | | SRCS[4:0] | | | |
| 0x0F4F | MDCARL | 7:0 | | | | | CLS[3:0] | | | |
| 0x0F50 | MDCARH | 7:0 | | | | | CHS[3:0] | | | |

27.12 Register Definitions: Modulation Control

[Related Links](#)

[Long Bit Names](#)

27.12.1 MDCON0

Name: MDCON0
Address: 0xF4C

Modulation Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|------|---|---|---|-----|
| | EN | | OUT | OPOL | | | | BIT |
| Access | R/W | | R/W | R/W | | | | R/W |
| Reset | 0 | | 0 | 0 | | | | 0 |

Bit 7 – EN Modulator Module Enable bit

| Value | Description |
|-------|--|
| 1 | Modulator module is enabled and mixing input signals |
| 0 | Modulator module is disabled and has no output |

Bit 5 – OUT Modulator Output bit
Displays the current output value of the modulator module.

Bit 4 – OPOL Modulator Output Polarity Select bit

| Value | Description |
|-------|--|
| 1 | Modulator output signal is inverted; idle high output |
| 0 | Modulator output signal is not inverted; idle low output |

Bit 0 – BIT Modulation Source Select Input bit
Allows software to manually set modulation source input to module

Notes:

1. The modulated output frequency can be greater and asynchronous from the clock that updates this register bit, the bit value may not be valid for higher speed modulator or carrier signals.
2. MDBIT must be selected as the modulation source in the MDSRC register for this operation.

27.12.2 MDCON1

Name: MDCON1
Address: 0xF4D

Modulation Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|-------|--------|---|---|-------|--------|
| | | | CHPOL | CHSYNC | | | CLPOL | CLSYNC |
| Access | | | R/W | R/W | | | R/W | R/W |
| Reset | | | 0 | 0 | | | 0 | 0 |

Bit 5 – CHPOL Modulator High Carrier Polarity Select bit

| Value | Description |
|-------|--|
| 1 | Selected high carrier signal is inverted |
| 0 | Selected high carrier signal is not inverted |

Bit 4 – CHSYNC Modulator High Carrier Synchronization Enable bit

| Value | Description |
|-------|---|
| 1 | Modulator waits for a falling edge on the high time carrier signal before allowing a switch to the low time carrier |
| 0 | Modulator output is not synchronized to the high time carrier signal |

Bit 1 – CLPOL Modulator Low Carrier Polarity Select bit

| Value | Description |
|-------|---|
| 1 | Selected low carrier signal is inverted |
| 0 | Selected low carrier signal is not inverted |

Bit 0 – CLSYNC Modulator Low Carrier Synchronization Enable bit

| Value | Description |
|-------|---|
| 1 | Modulator waits for a falling edge on the low time carrier signal before allowing a switch to the high time carrier |
| 0 | Modulator output is not synchronized to the low time carrier signal |

Note:

1. Narrowed carrier pulse widths or spurs may occur in the signal stream if the carrier is not synchronized.

27.12.3 MDCARH

Name: MDCARH
Address: 0xF50

Modulation High Carrier Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | CHS[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – CHS[3:0] Modulator Carrier High Selection bits

Table 27-1. MDCARH Source Selections

| MDCARH | |
|----------|---------------------------|
| CHS[2:0] | Connection |
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0111 | PWM4 OUT |
| 0110 | PWM3 OUT |
| 0101 | CCP2 OUT |
| 0100 | CCP1 OUT |
| 0011 | CLKREF output |
| 0010 | HFINTOSC |
| 0001 | Fosc (system clock) |
| 0000 | Pin selected by MDCARHPPS |

27.12.4 MDCARL

Name: MDCARL
Address: 0xF4F

Modulation Low Carrier Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | CLS[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – CLS[3:0] Modulator Carrier Low Input Selection bits

Table 27-2. MDCARL Source Selections

| MDCARL | |
|----------|---------------------------------|
| CLS[2:0] | Connection |
| 1111 | CLC8_out |
| 1110 | CLC7_out |
| 1101 | CLC6_out |
| 1100 | CLC5_out |
| 1011 | CLC4_out |
| 1010 | CLC3_out |
| 1001 | CLC2_out |
| 1000 | CLC1_out |
| 0111 | PWM4 OUT |
| 0110 | PWM3 OUT |
| 0101 | CCP2 OUT |
| 0100 | CCP1 OUT |
| 0011 | CLKREF output |
| 0010 | HFINTOSC |
| 0001 | F _{OSC} (system clock) |
| 0000 | Pin selected by MDCARLPPS |

27.12.5 MDSRC**Name:** MDSRC**Address:** 0xF4E

Modulation Source Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|-----------|-----|-----|-----|-----|
| | | | | SRCS[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – SRCS[4:0] Modulator Source Selection bits**Table 27-3. MDSRC Selection MUX Connections**

| SRCS[3:0] | Connection |
|-------------|---------------------------|
| 11000-11111 | Reserved |
| 10111 | CLC8_out |
| 10110 | CLC7_out |
| 10101 | CLC6_out |
| 10100 | CLC5_out |
| 10011 | CLC4_out |
| 10010 | CLC3_out |
| 10001 | CLC2_out |
| 10000 | CLC1_out |
| 01111 | Reserved |
| 01110 | Reserved |
| 01101 | EUSART2 TX (TX/CK output) |
| 01100 | EUSART2 RX (DT output) |
| 01011 | MSSP2 - SDO |
| 01010 | MSSP1 - SDO |
| 01001 | EUSART1 TX (TX/CK output) |
| 01000 | EUSART1 RX (DT output) |
| 00111 | CMP2 OUT |
| 00110 | CMP1 OUT |
| 00101 | PWM4 OUT |
| 00100 | PWM3 OUT |
| 00011 | CCP2 OUT |
| 00010 | CCP1 OUT |
| 00001 | MDBIT |
| 00000 | Pin selected by MDSRCPPS |

28. MSSP - Host Synchronous Serial Port Module

The Host Synchronous Serial Port (MSSP) module is a serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D converters, etc. The MSSP module can operate in one of two modes:

- Serial Peripheral Interface (SPI)
- Inter-Integrated Circuit (I²C)

The SPI interface can operate in Host or Client mode and supports the following features:

- Selectable clock parity
- Client select synchronization (Client mode only)
- Daisy-chain connection of client devices

The I²C interface can operate in Host or Client mode and supports the following modes and features:

- Byte NACKing (Client mode)
- Limited multi-host support
- 7-bit and 10-bit addressing
- Start and stop interrupts
- Interrupt masking
- Clock stretching
- Bus collision detection
- General call address matching
- Address masking
- Address Hold and Data Hold modes
- Selectable SDA hold times

28.1 SPI Mode Overview

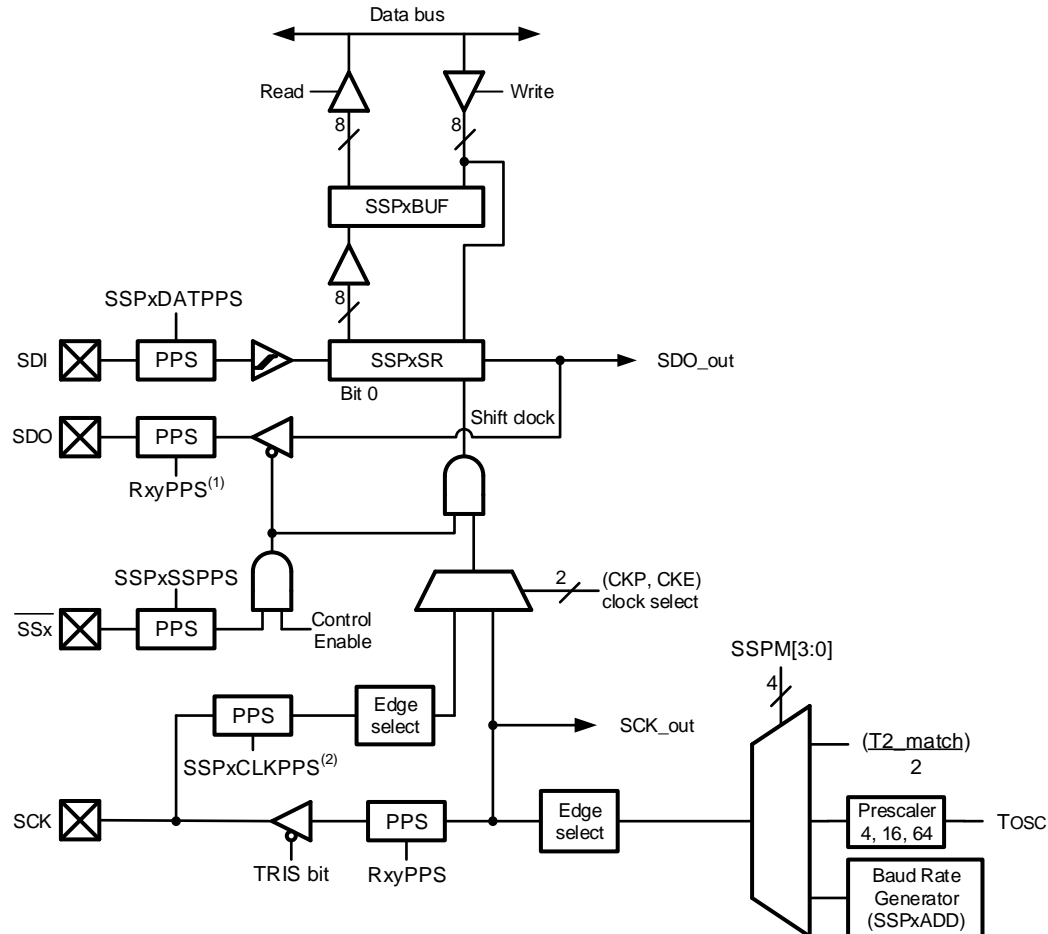
The Serial Peripheral Interface (SPI) is a synchronous serial data communication bus that operates in Full Duplex mode. Devices communicate in a host/client environment where the host device initiates the communication. A client device is selected for communication using the Client Select feature.

The SPI bus specifies four signal connections:

- Serial Clock (SCK)
- Serial Data Out (SDO)
- Serial Data In (SDI)
- Client Select (\overline{SS})

Figure 28-1 shows the block diagram of the MSSP module when operating in SPI mode.

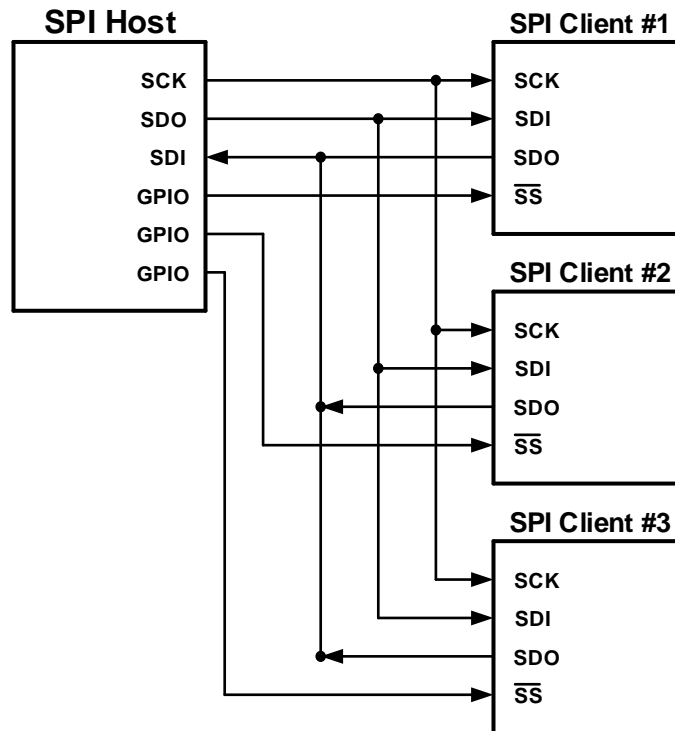
Figure 28-1. MSSP Block Diagram (SPI Mode)



Notes: 1. Output selection for Host mode.
2. Input selection for Client and Host modes.

The SPI bus operates with a single host device and one or more client devices. When multiple client devices are used, an independent Client Select connection is required from the host device to each client device. The host selects only one client at a time. Most client devices have tri-state outputs, so their output signal appears disconnected from the bus when they are not selected.

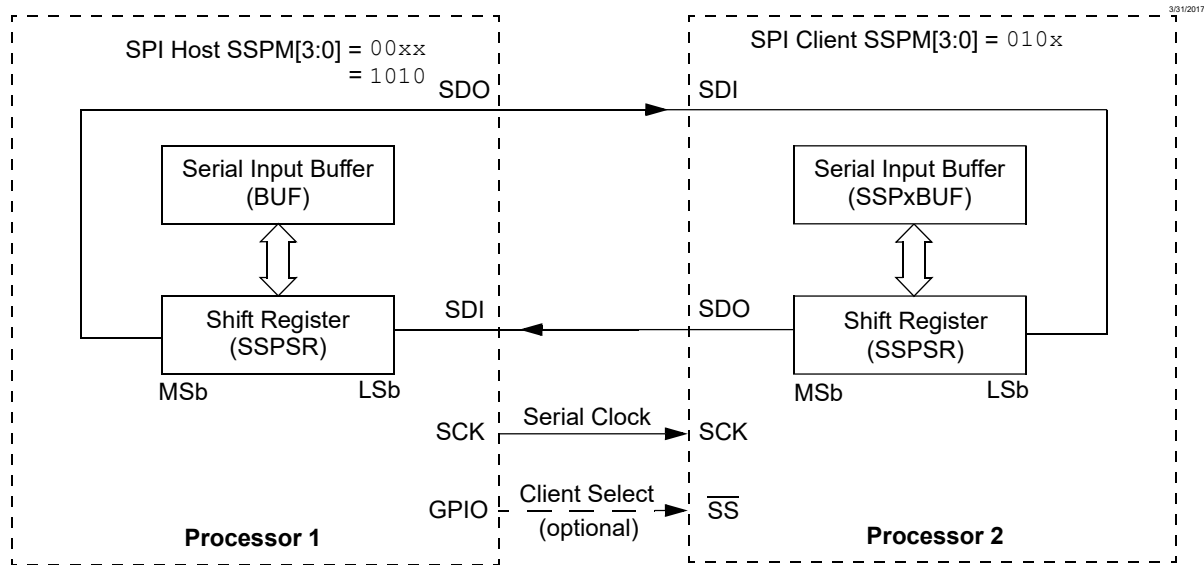
Figure 28-2 shows a typical connection between a host device and multiple client devices.

Figure 28-2. SPI Host and Multiple Client Connection

Transmissions involve two shift registers, eight bits in size: One in the host and one in the client. Data are shifted out one bit at a time, with the Most Significant bit (MSb) shifted out first. At the same time, a new Least Significant bit (LSb) is shifted into the same register.

[Figure 28-3](#) shows a typical connection between two processors configured as host and client devices.

Figure 28-3. SPI Host/Client Connection



Data are shifted out of both shift registers on the programmed clock edge and are latched on the opposite edge of the clock.

The host device transmits information out on its SDO output pin, which is connected to and received by the client's SDI input pin. The client device transmits information out on its SDO output pin, which is connected to and received by the host's SDI input pin.

To begin communication, the host device transmits both the MSb from its shift register and the clock signal. Both the host and client devices need to be configured for the same clock polarity. During each SPI clock cycle, a full-duplex data transmission occurs. This means that while the host device is sending out the MSb from its shift register (on its SDO pin) and the client device is reading this bit and saving it as the LSb of its shift register, the client device is also sending out the MSb from its shift register (on its SDO pin) and the host device is reading this bit and saving it as the LSb of its shift register.

After eight bits have been shifted out, the host and client have exchanged register values. If there is more data to exchange, the shift registers are loaded with new data and the process repeats itself.

Whether the data are meaningful or not (dummy data) depends on the application software. This leads to three scenarios for data transmission:

- Host sends useful data and client sends dummy data
- Host sends useful data and client sends useful data
- Host sends dummy data and client sends useful data

Transmissions must be performed in multiples of eight clock cycles. When there is no more data to be transmitted, the host stops sending the clock signal and it deselects the client.

Every client device connected to the bus that has not been selected through its Client Select line must disregard the clock and transmission signals and must not transmit out any data of its own.

28.1.1 SPI Mode Registers

The MSSP module has six registers for SPI mode operation. They are:

- MSSP Status Register ([SSPxSTAT](#))

- MSSP Control Register 1 ([SSPxCON1](#))
- MSSP Control Register 3 ([SSPxCON3](#))
- MSSP Data Buffer Register ([SSPxBUF](#))
- MSSP Address Register ([SSPxADD](#))
- MSSP Shift (SSPSR) register (not directly accessible)

SSPxCON1 and SSPxSTAT are the control and status registers for SPI mode operation. The SSPxCON1 register is readable and writable. The lower six bits of the SSPxSTAT are read-only. The upper two bits of the SSPxSTAT are read/write.

One of the five SPI Host modes uses the SSPxADD value to determine the Baud Rate Generator clock frequency. More information on the Baud Rate Generator is available in [Baud Rate Generator](#).

SSPSR is the shift register used for shifting data in and out. SSPxBUF provides indirect access to the SSPSR register. SSPxBUF is the buffer register to which data bytes are written and from which data bytes are read.

In receive operations, SSPSR and SSPxBUF together create a buffered receiver. When SSPSR receives a complete byte, it is transferred to SSPxBUF and the SSPxIF interrupt is set.

During transmission, the SSPxBUF is not buffered. A write to SSPxBUF will write to both SSPxBUF and SSPSR.

28.1.2 SPI Mode Operation

When initializing the SPI, several options need to be specified. This is done by programming the appropriate control bits ([SSPxCON1](#)[5:0] and [SSPxSTAT](#)[7:6]). These control bits allow the following to be specified:

- Host mode (SCK is the clock output)
- Client mode (SCK is the clock input)
- Clock Polarity (Idle state of SCK)
- Data Input Sample Phase (middle or end of data output time)
- Clock Edge (output data on rising/falling edge of SCK)
- Clock Rate (Host mode only)
- Client Select mode (Client mode only)

To enable the serial port, the SSP Enable ([SSPEN](#)) bit must be set. To reset or reconfigure SPI mode, clear the SSPEN bit, re-initialize the SSPxCONy registers and then set the SSPEN bit. The SDI, SDO, SCK and \overline{SS} serial port pins are selected with the PPS controls. For the pins to behave as the serial port function, some must have their data direction bits (in the TRIS register) appropriately programmed as follows:

- SDI must have the corresponding TRIS bit set
- SDO must have the corresponding TRIS bit cleared
- SCK (Host mode) must have the corresponding TRIS bit cleared
- SCK (Client mode) must have the corresponding TRIS bit set
- The RxyPPS and SSPxCLKPPS controls must select the same pin
- \overline{SS} must have the corresponding TRIS bit set

Any serial port function that is not desired may be overridden by programming the corresponding data direction (TRIS) register to the opposite value.

The MSSP consists of a Transmit/Receive Shift Register (SSPSR) and a buffer register ([SSPxBUF](#)). The SSPSR shifts the data in and out of the device, MSb first. The SSPxBUF holds the data that

were written to the SSPSR until the received data are ready. Once the eight bits of data have been received, that byte is moved to the SSPxBUF register. Then, the Buffer Full Status (BF) bit and the MSSP Interrupt Flag (SSPxIF) bit are set. This double-buffering of the received data allows the next byte to start reception before reading the data that was just received. Any write to the SSPxBUF register during transmission/reception of data will be ignored and the Write Collision Detect (WCOL) bit will be set. User software must clear the WCOL bit to allow the following write(s) to the SSPxBUF register to complete successfully.

When the application software is expecting to receive valid data, the SSPxBUF must be read before the next byte of data to be transferred is written to the SSPxBUF. The BF bit indicates when SSPxBUF has been loaded with the received data (transmission is complete). When the SSPxBUF is read, the BF bit is cleared. This data may be irrelevant if the SPI is only a transmitter. The MSSP interrupt is used to determine when the transmission/reception has completed. If the interrupt method is not going to be used, then software polling can be done to ensure that a write collision does not occur.



Important: The SSPSR is not directly readable or writable and can only be accessed by addressing the SSPxBUF register.

28.1.2.1 SPI Host Mode

The Host can initiate the data transfer at any time because it controls the SCK line. The Host determines when the client (Processor 2, Figure 28-3) is to broadcast data by the software protocol.

In Host mode, the data are transmitted/received as soon as the SSPxBUF register is written to. If the SPI is only going to receive, the SDO output may be disabled (programmed as an input). The SSPSR register will continue to shift in the signal present on the SDI pin at the programmed clock rate. As each byte is received, it will be loaded into the SSPxBUF register (interrupts and Status bits appropriately set).

The clock polarity is selected by appropriately programming the Clock Polarity Select (CKP) and SPI Clock Edge Select (CKE) bits. Figure 28-4 shows the four clocking configurations. When the CKE bit is set, the SDO data are valid one half of a clock cycle before a clock edge appears on SCK, and transmission occurs on the transition from the Active to Idle clock state. When CKE is clear, the SDO data are valid at the same time as the clock edge appears on SCK, and transmission occurs on the transition from the Idle to Active clock states.

The SPI Data Input Sample (SMP) bit determines when the SDI input is sampled. When SMP is set, input data are sampled at the end of the data output time. When SMP is clear, input data are sampled at the middle of the data output time.

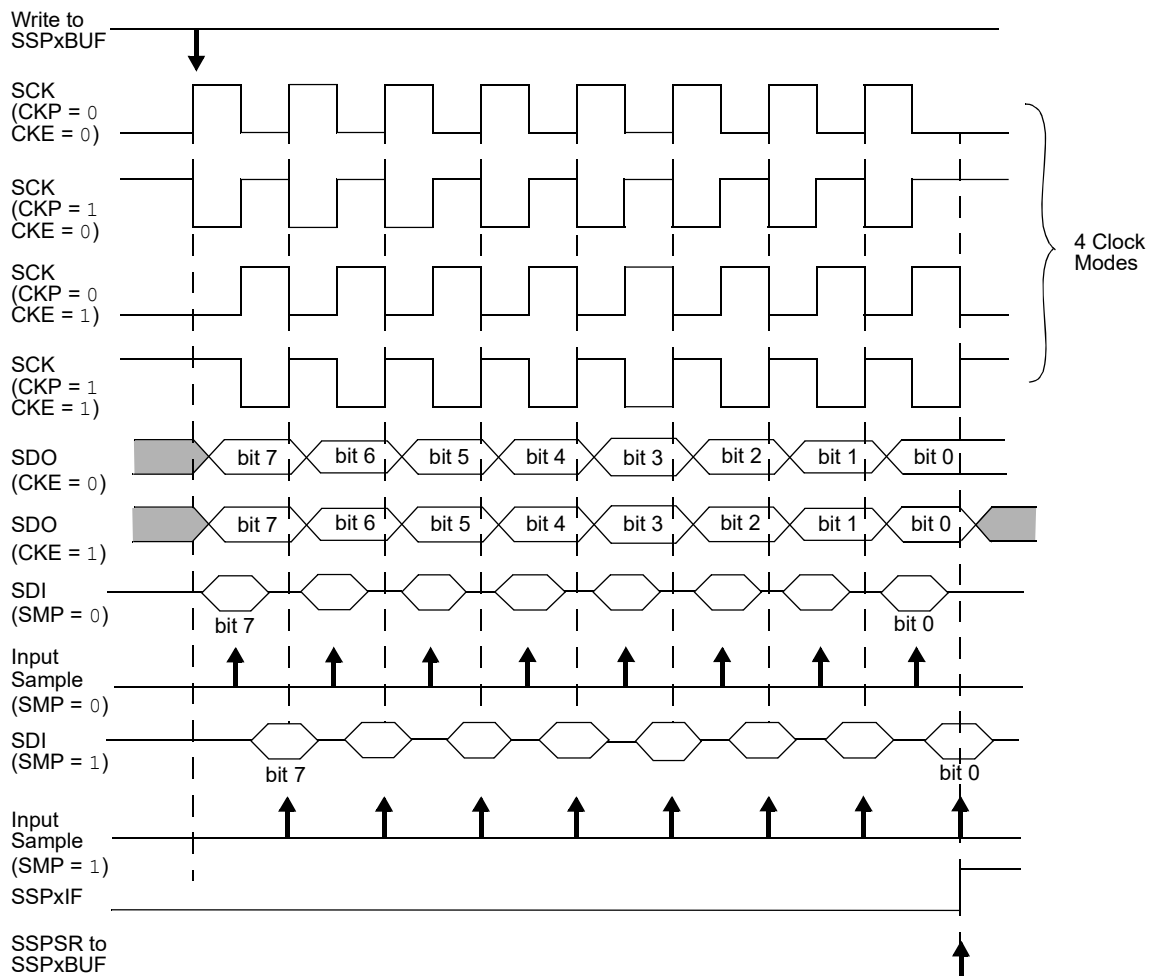
The SPI clock rate (bit rate) is user-programmable to be one of the following:

- $F_{OSC}/4$ (or T_{CY})
- $F_{OSC}/16$ (or $4 * T_{CY}$)
- $F_{OSC}/64$ (or $16 * T_{CY}$)
- Timer2 output/2
- $F_{OSC}/(4 * (SSPxADD + 1))$



Important: In Host mode, the clock signal output to the SCK pin is also the clock signal input to the peripheral. The pin selected for output with the RxyPPS register must also be selected as the peripheral input with the SSPxCLKPPS register.

Figure 28-4. SPI Mode Waveform (Host Mode)



28.1.2.2 SPI Client Mode

In Client mode, the data are transmitted and received as external clock pulses appear on SCK. When the last bit is latched, the SSPxIF Interrupt Flag bit is set.

Before enabling the module in SPI Client mode, the clock line must match the proper Idle state. The clock line can be observed by reading the SCK pin. The Idle state is determined by the CKP bit.

While in Client mode, the external clock is supplied by the external clock source on the SCK pin. This external clock must meet the minimum high and low times as specified in Electrical Specifications.

While in Sleep mode, the client can transmit/receive data. The shift register is clocked from the SCK pin input and when a byte is received, the device will generate an interrupt. If enabled, the device will wake up from Sleep.

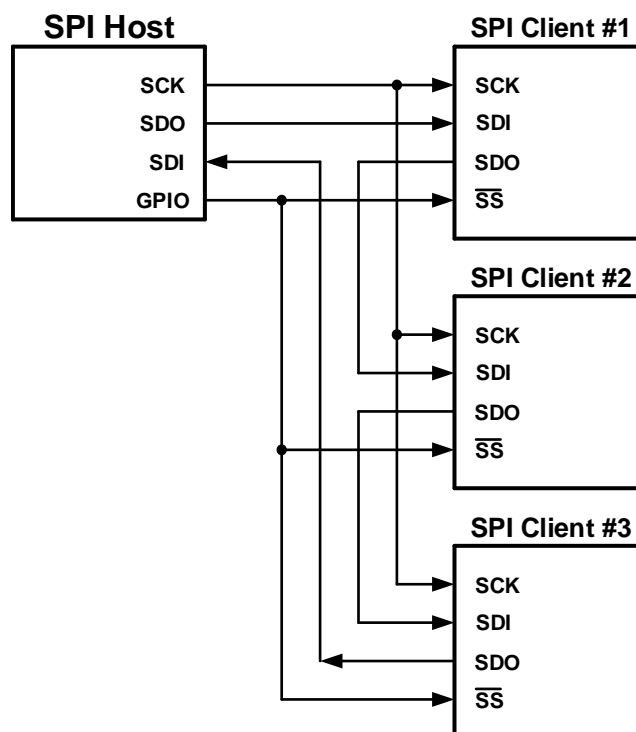
28.1.2.3 Daisy-Chain Configuration

The SPI bus can sometimes be connected in a daisy-chain configuration. The first client output is connected to the second client input, the second client output is connected to the third client input, and so on. The final client output is connected to the host input. Each client sends out, during a second group of clock pulses, an exact copy of what was received during the first group of clock pulses. The whole chain acts as one large communication shift register. The daisy-chain feature only requires a single Client Select line from the host device.

In a daisy-chain configuration, only the most recent byte on the bus is required by the client. Setting the Buffer Overwrite Enable (**BOEN**) bit will enable writes to the **SSPxBUF** register, even if the previous byte has not been read. This allows the software to ignore data that may not apply to it.

Figure 28-5 shows the block diagram of a typical daisy-chain connection when operating in SPI mode.

Figure 28-5. SPI Daisy-Chain Connection



28.1.2.4 Client Select Synchronization

The Client Select can also be used to synchronize communication (see Figure 28-6). The Client Select line is held high until the host device is ready to communicate. When the Client Select line is pulled low, the client knows that a new transmission is starting.

If the client fails to receive the communication properly, it will be reset at the end of the transmission, when the Client Select line returns to a High state. The client is then ready to receive a new transmission when the Client Select line is pulled low again. If the Client Select line is not used, there is a risk that the client will eventually become out of sync with the host. If the client misses a bit, it will always be one bit off in future transmissions. Use of the Client Select line allows the client and host to align themselves at the beginning of each transmission.

The \overline{SS} pin allows a Synchronous Client mode. The SPI must be in Client mode with \overline{SS} pin control enabled (MSSP Mode Select (**SSPM**) bits = 0100).

When the \overline{SS} pin is low, transmission and reception are enabled and the SDO pin is driven.

When the \overline{SS} pin goes high, the SDO pin is no longer driven, even if in the middle of a transmitted byte, and becomes a floating output. External pull-up/pull-down resistors may be desirable depending on the application.

When the SPI module resets, the bit counter is forced to '0'. This can be done by either forcing the \overline{SS} pin to a high level or clearing the **SSPEN** bit.



Important:

1. When the SPI is in Client mode with \overline{SS} pin control enabled (**SSPM** = 0100), the SPI module will reset if the \overline{SS} pin is set to V_{DD} .
2. When the SPI is used in Client mode with **CKE** set, the user must enable \overline{SS} pin control (see Figure 28-8). If **CKE** is clear, \overline{SS} pin control is optional (see Figure 28-7).
3. While operated in SPI Client mode, the **SMP** bit must remain clear.

Figure 28-6. Client Select Synchronous Waveform

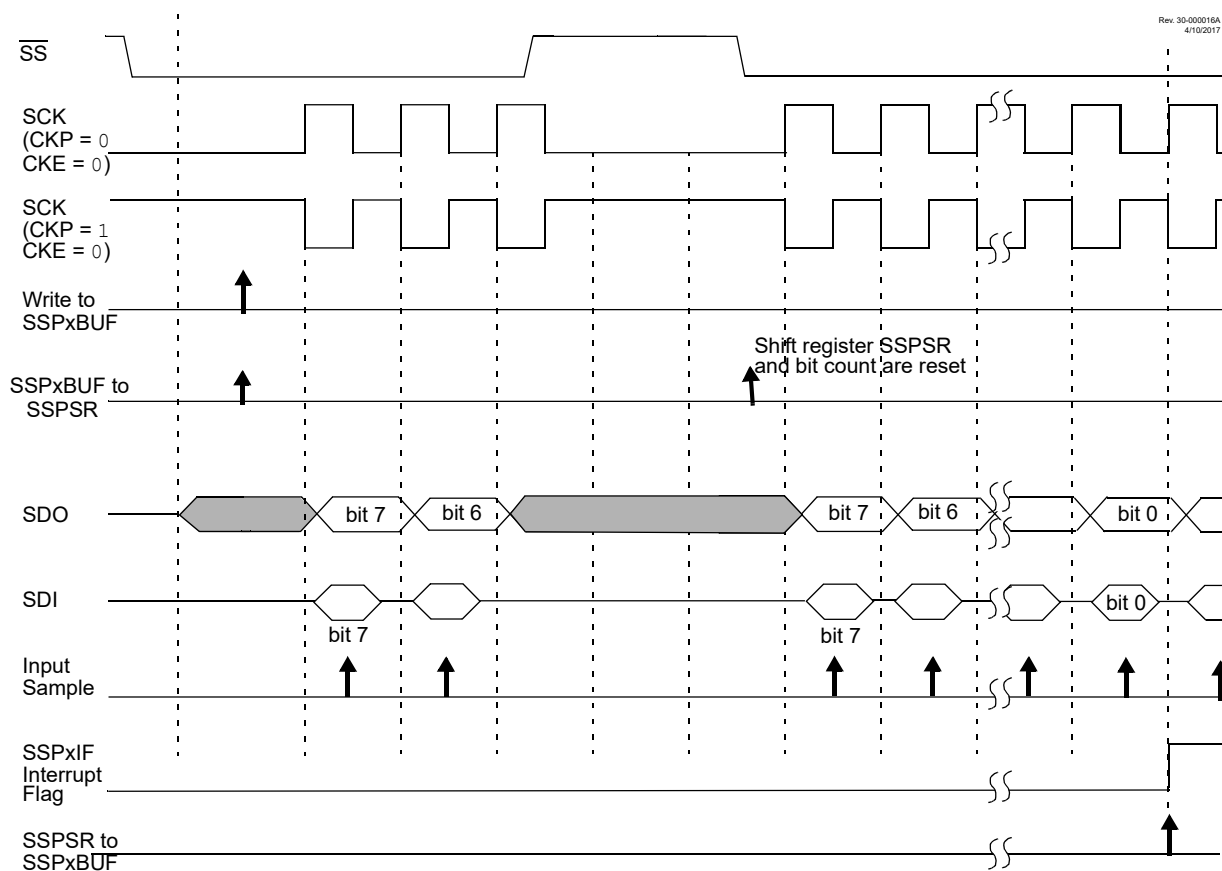


Figure 28-7. SPI Mode Waveform (Client Mode with CKE = 0)

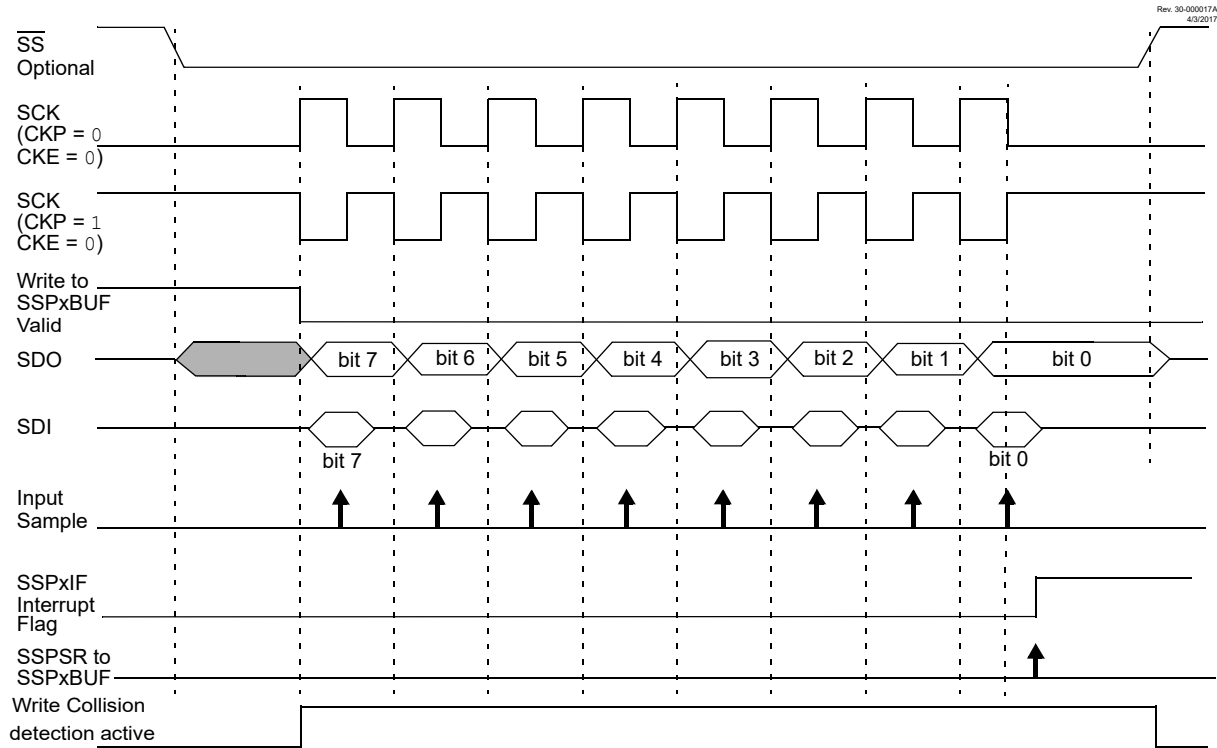
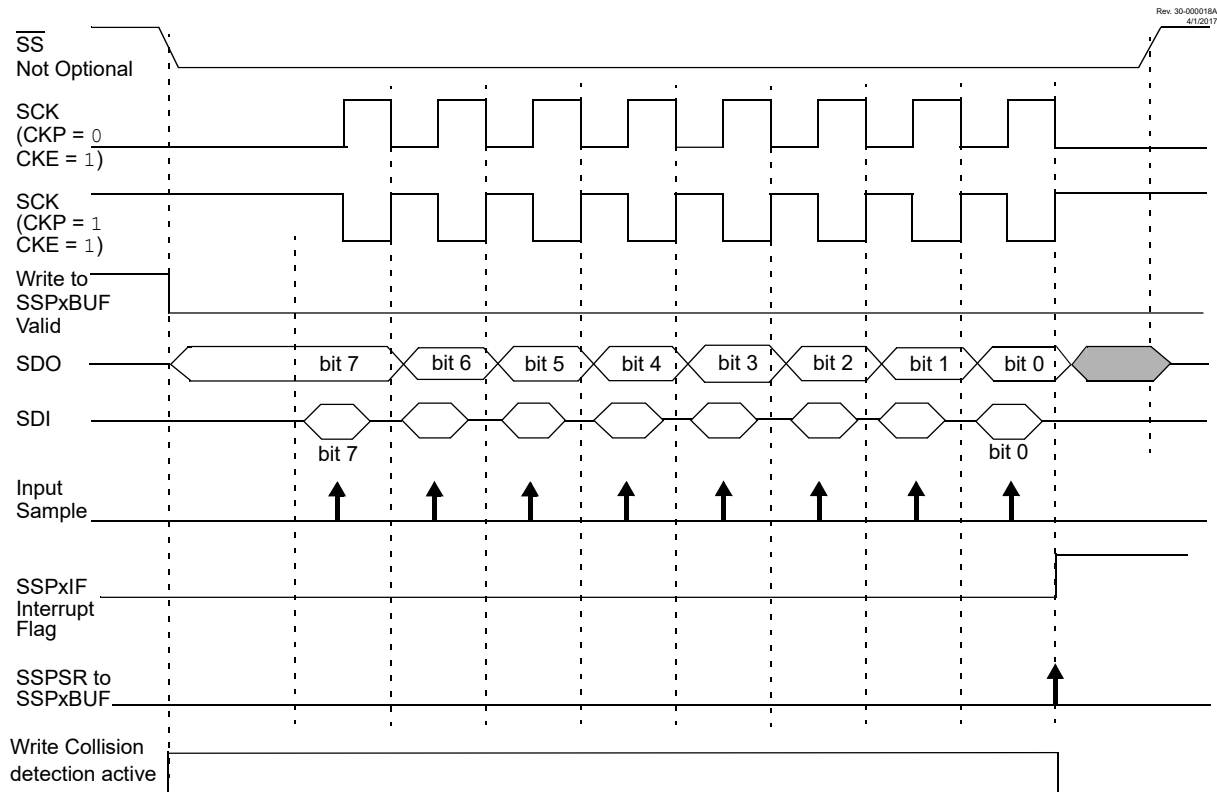


Figure 28-8. SPI Mode Waveform (Client Mode with CKE = 1)



28.1.2.5 SPI Operation in Sleep Mode

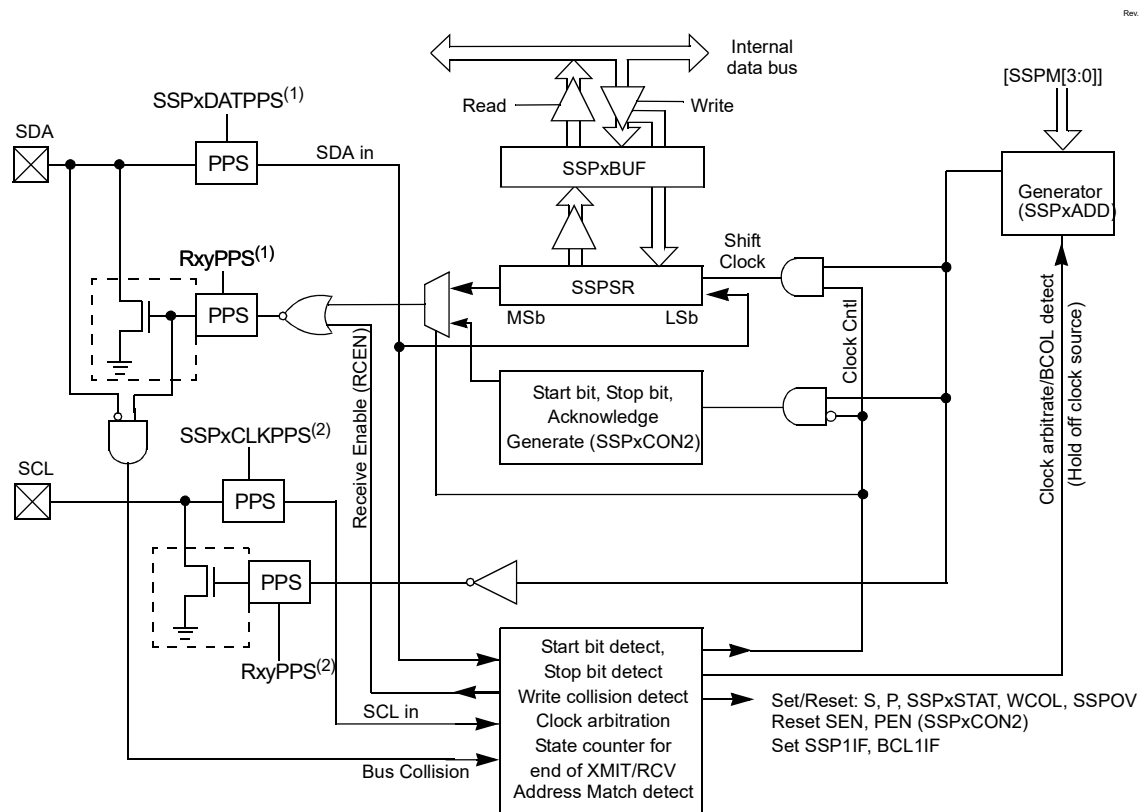
In SPI Host mode, when the Sleep mode is selected, all module clocks are halted and the transmission/reception will remain in that state until the device wakes. After the device returns to Run mode, the module will resume transmitting and receiving data.

In SPI Client mode, the SPI Transmit/Receive Shift register operates asynchronously to the device. This allows the device to be placed in Sleep mode and data to be shifted into the SPI Transmit/Receive Shift register. When all eight bits have been received, the MSSP Interrupt Flag bit will be set and if enabled, will wake the device.

28.2 I²C Mode Overview

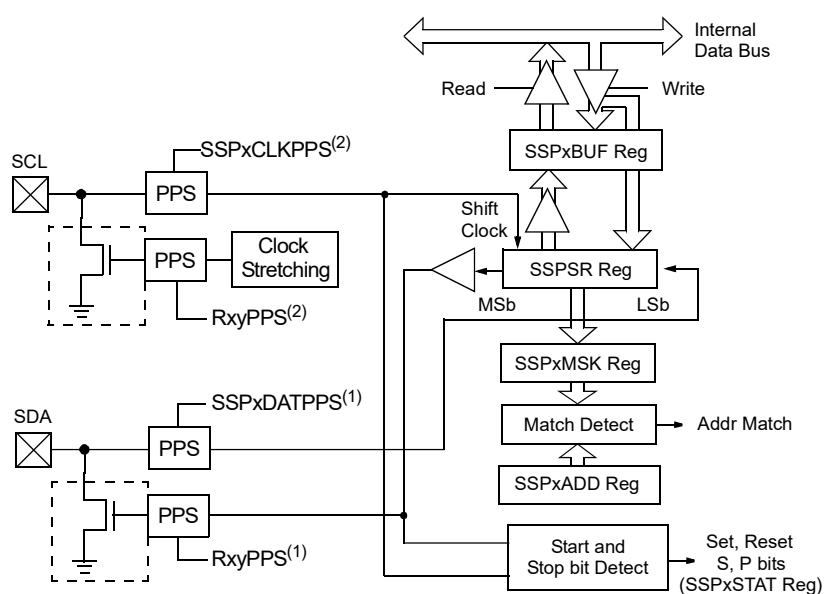
The Inter-Integrated Circuit (I²C) bus is a multi-host serial data communication bus. Devices communicate in a host/client environment where the host devices initiate the communication. A client device is controlled through addressing. [Figure 28-9](#) and [Figure 28-10](#) show block diagrams of the I²C Host and Client modes, respectively.

Figure 28-9. MSSP Block Diagram (I²C Host Mode)



Notes: 1. SDA pin selections must be the same for input and output.

2. SCL pin selections must be the same for input and output.

Figure 28-10. MSSP Block Diagram (I²C Client Mode)Rev. 30-000020A
4/3/2017

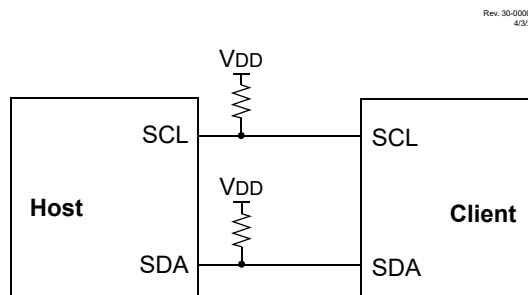
- Notes:**
1. SDA pin selections must be the same for input and output.
 2. SCL pin selections must be the same for input and output.

The I²C bus specifies two signal connections:

- Serial Clock (SCL)
- Serial Data (SDA)

Both the SCL and SDA connections are bidirectional open-drain lines, each requiring pull-up resistors for the supply voltage. Pulling the line to ground is considered a logical zero and letting the line float is considered a logical one.

Figure 28-11 shows a typical connection between two processors configured as host and client devices.

Figure 28-11. I²C Host/Client ConnectionRev. 30-000021A
4/3/2017

The I²C bus can operate with one or more host devices and one or more client devices.

There are four potential modes of operation for a given device:

- Host Transmit mode (host is transmitting data to a client)
- Host Receive mode (host is receiving data from a client)

- Client Transmit mode (client is transmitting data to a host)
- Client Receive mode (client is receiving data from the host)

To begin communication, the host device transmits a Start condition followed by the address byte of the client it intends to communicate with. A Start condition is indicated by a high-to-low transition of the SDA line while the SCL line is held high. Address and data bytes are sent out, MSb first. This is followed by a single Read/Write Information ($\overline{R/W}$) bit, which determines whether the host intends to transmit to or receive data from the client device. The $\overline{R/W}$ bit is sent out as a logical one when the host intends to read data from the client and is sent out as a logical zero when it intends to write data to the client.

If the requested client exists on the bus, it will respond with an Acknowledge sequence, otherwise known as an \overline{ACK} . The Acknowledge sequence is an active-low signal, which holds the SDA line low to indicate to the transmitter that the client device has received the transmitted data and is ready to receive more. The host then continues to either transmit to or receive data from the client.

The transition of a data bit is always performed while the SCL line is held low. Transitions that occur while the SCL line is held high are used to indicate Start and Stop conditions.

If the host intends to write to the client, then it repeatedly sends out a byte of data, with the client responding after each byte with an \overline{ACK} sequence. In this example, the host device is in Host Transmit mode and the client is in Client Receive mode.

If the host intends to read from the client, then it repeatedly receives a byte of data from the client and responds after each byte with an \overline{ACK} sequence. In this example, the host device is in Host Receive mode and the client is in Client Transmit mode.

On the last byte of data communicated, the host device may end the transmission by sending a Stop condition. If the host device is in Receive mode, it sends the Stop condition in place of the last \overline{ACK} sequence. A Stop condition is indicated by a low-to-high transition of the SDA line while the SCL line is held high.

In some cases, the host may want to maintain control of the bus and re-initiate another transmission. If so, the host device may send a Restart condition in place of the Stop condition or last \overline{ACK} sequence when it is in Receive mode.

The I²C bus specifies three message protocols:

- Single message where a host writes data to a client
- Single message where a host reads data from a client
- Combined message where a host initiates a minimum of two writes, two reads, or a combination of writes and reads, to one or more clients

28.2.1 I²C Mode Registers

The MSSP module has eight registers for I²C operation.

These are:

- MSSP Status Register ([SSPxSTAT](#))
- MSSP Control 1 Register ([SSPxCON1](#))
- MSSP Control 2 Register ([SSPxCON2](#))
- MSSP Control 3 Register ([SSPxCON3](#))
- Serial Receive/Transmit Buffer Register ([SSPxBUF](#))
- MSSP Address Register ([SSPxADD](#))
- I²C Client Address Mask Register ([SSPxMSK](#))
- MSSP Shift (SPSR) register – not directly accessible

SSPxCON1, SSPxCON2, SSPxCON3 and SSPxSTAT are the Control and Status registers in I²C mode operation. The SSPxCON1, SSPxCON2 and SSPxCON3 registers are readable and writable. The lower six bits of the SSPxSTAT are read-only. The upper two bits of the SSPxSTAT are read/write. SSPxMSK holds the client address mask value used in address comparison. SSPxADD contains the client device address when the MSSP is configured in I²C Client mode. When the MSSP is configured in Host mode, SSPxADD acts as the Baud Rate Generator reload value.

SSPSR is the shift register used for shifting data in or out. SSPxBUF is the buffer register to which data bytes are written to or read from. In receive operations, SSPSR and SSPxBUF together, create a double-buffered receiver. When SSPSR receives a complete byte, it is transferred to SSPxBUF and the SSPxIF interrupt is set. During transmission, the SSPxBUF is not double-buffered. A write to SSPxBUF will write to both SSPxBUF and SSPSR.

28.2.2 I²C Mode Operation

All MSSP I²C communication is byte oriented and shifted out MSb first. Eight SFR registers and two interrupt flags interface the module with the PIC[®] microcontroller and user software. Two pins, SDA and SCL, are exercised by the module to communicate with other external I²C devices.

28.2.2.1 Definition of I²C Terminology

There is language and terminology in the description of I²C communication that have definitions specific to I²C. That word usage is defined below and may be used in the rest of this document without explanation. This table was adapted from the Philips/NXP I²C Specification.

Table 28-1. I²C Terminology

| Term | Description |
|------------------|---|
| Transmitter | The device that shifts data out onto the bus |
| Receiver | The device that shifts data in from the bus |
| Host | The device that initiates a transfer, generates clock signals, and terminates a transfer |
| Client | The device addressed by the host |
| Multi-Host | A bus with more than one device that can initiate data transfers |
| Arbitration | Procedure to ensure that only one host at a time controls the bus. Winning arbitration ensures that the message is not corrupted. |
| Synchronization | Procedure to synchronize the clocks of two or more devices on the bus |
| Idle | No host is controlling the bus, and both SDA and SCL lines are high |
| Active | Any time one or more host devices are controlling the bus |
| Addressed Client | Client device that has received a matching address and is actively being clocked by a host |
| Matching Address | Address byte that is clocked into a client that matches the value stored in SSPxADD |
| Write Request | Client receives a matching address with the R/ \overline{W} bit clear and is ready to clock in data |
| Read Request | Host sends an address byte with the R/ \overline{W} bit set, indicating that it wishes to clock data out of the client. This data are next and all following bytes until a Restart or Stop. |
| Clock Stretching | When a device on the bus hold SCL low to stall communication |
| Bus Collision | Any time the SDA line is sampled low by the module while it is outputting and expected High state |

28.2.2.2 Byte Format

All communication in I²C is done in 9-bit segments. A byte is sent from a host to a client or vice versa, followed by an Acknowledge sequence sent back. After the eighth falling edge of the SCL line, the device outputting data on the SDA changes that pin to an input and reads the Acknowledge value on the next clock pulse.

The clock signal, SCL, is provided by the host. Data are valid to change while the SCL signal is low and is sampled on the rising edge of the clock. Changes on the SDA line while the SCL line is high define special conditions on the bus, such as a Start or Stop condition.

28.2.2.3 SDA and SCL Pins

Selection of any I²C mode with the **SSPEN** bit set forces the SCL and SDA pins to be open-drain. These pins must be configured as inputs by setting the appropriate TRIS bits.



Important: Any device pin can be selected for SDA and SCL functions with the PPS peripheral. These functions are bidirectional. The SDA input is selected with the SSPxDATPPS registers. The SCL input is selected with the SSPxCLKPPS registers. Outputs are selected with the RxyPPS registers. It is the user's responsibility to make the selections so that both the input and the output for each function is on the same pin.

28.2.2.4 SDA Hold Time

The hold time of the SDA pin is selected by the SDA Hold Time Selection (**SDAHT**) bit. Hold time is the time SDA is held valid after the falling edge of SCL. Setting the SDAHT bit selects a longer 300 ns minimum hold time and may help buses with large capacitance.

28.2.2.5 Clock Stretching

Clock stretching occurs when a device on the bus holds the SCL line low, effectively pausing communication. The client may stretch the clock to allow more time to handle data or prepare a response for the host device. A host device is not concerned with stretching as anytime it is active on the bus and not transferring data it is stretching. Any stretching done by a client is invisible to the host software and handled by the hardware that generates SCL.

The **CKP** bit is used to control stretching in software. Any time the CKP bit is cleared, the module will wait for the SCL line to go low and then hold it. Setting CKP will release SCL and allow more communication.

28.2.2.6 Arbitration

Each host device must monitor the bus for Start and Stop conditions. If the device detects that the bus is busy, it cannot begin a new message until the bus returns to an Idle state.

However, two host devices may try to initiate a transmission on or about the same time. When this occurs, the process of arbitration begins. Each transmitter checks the level of the SDA data line and compares it to the level that it expects to find. The first transmitter to observe that the two levels do not match loses arbitration and must stop transmitting on the SDA line.

For example, if one transmitter holds the SDA line to a logical one (lets SDA float) and a second transmitter holds it to a logical zero (pulls SDA low), the result is that the SDA line will be low. The first transmitter then observes that the level of the line is different than expected and concludes that another transmitter is communicating.

The first transmitter to notice this difference is the one that loses arbitration and must stop driving the SDA line. If this transmitter is also a host device, it also must stop driving the SCL line. It then can monitor the lines for a Stop condition before trying to reissue its transmission. In the meantime, the other device that has not noticed any difference between the expected and actual levels on the SDA line continues with its original transmission. It can do so without any complications, because so far, the transmission appears exactly as expected with no other transmitter disturbing the message.

Client Transmit mode can also be arbitrated, when a host addresses multiple clients, but this is less common.

28.2.2.7 Start Condition

The I²C Specification defines a Start condition as a transition of SDA from a High to a Low state while SCL line is high. A Start condition is always generated by the host and signifies the transition of the bus from an Idle to an Active state. [Figure 28-12](#) shows wave forms for Start and Stop conditions.

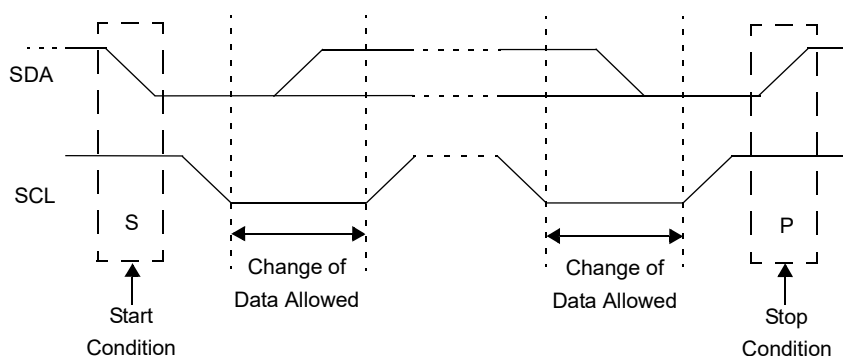
A bus collision can occur on a Start condition if the module samples the SDA line low before asserting it low. This does not conform to the I²C Specification that states no bus collision can occur on a Start.

28.2.2.8 Stop Condition

A Stop condition is a transition of the SDA line from Low-to-High state while the SCL line is high.

➔ Important: At least one SCL low time must appear before a Stop is valid, therefore, if the SDA line goes low then high again while the SCL line stays high, only the Start condition is detected.

Figure 28-12. I²C Start and Stop Conditions



Rev. 30-000022A
4/3/2017

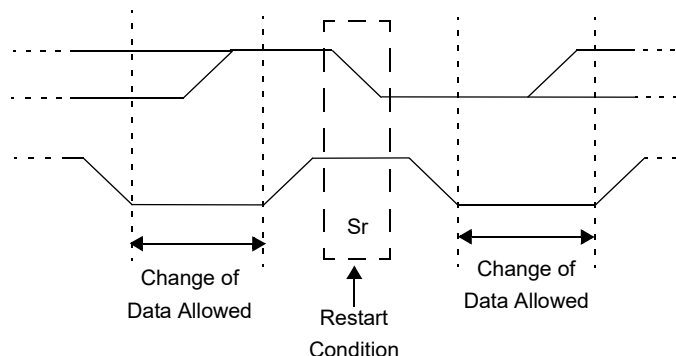
28.2.2.9 Start/Stop Condition Interrupt Masking

The Start Condition Interrupt Enable (SCIE) and Stop Condition Interrupt Enable (PCIE) bits can enable the generation of an interrupt in Client modes that do not typically support this function. These bits will have no effect in Client modes where interrupt on Start and Stop detect are already enabled.

28.2.2.10 Restart Condition

A Restart condition is valid any time that a Stop is valid. A host can issue a Restart if it wishes to hold the bus after terminating the current transfer. A Restart has the same effect on the client that a Start would, resetting all client logic and preparing it to clock in an address. The host may want to address the same or another client. Figure 28-13 shows the waveform for a Restart condition.

In 10-bit Addressing Client mode, a Restart is required for the host to clock data out of the addressed client. Once a client has been fully addressed, matching both high and low address bytes, the host can issue a Restart and the high address byte with the R/W bit set. The client logic will then hold the clock and prepare to clock out data.

Figure 28-13. I²C Restart ConditionRev. 30-000023A
4/9/2017

28.2.2.11 Acknowledge Sequence

The ninth SCL pulse for any transferred byte in I²C is dedicated as an Acknowledge sequence ($\overline{\text{ACK}}$). It allows receiving devices to respond back to the transmitter by pulling the SDA line low. The transmitter must release control of the line during this time to shift in the response. The Acknowledge ($\overline{\text{ACK}}$) is an active-low signal, pulling the SDA line low indicates to the transmitter that the device has received the transmitted data and is ready to receive more.

The result of an $\overline{\text{ACK}}$ is placed in the Acknowledge Status ([ACKSTAT](#)) bit.

The client software, when the Address Hold Enable ([AHEN](#)) and Data Hold Enable ([DHEN](#)) bits are set, allows the user to select the $\overline{\text{ACK}}$ value sent back to the transmitter. The Acknowledge Data ([ACKDT](#)) bit is set/cleared to determine the response.

The client hardware will generate an $\overline{\text{ACK}}$ response under most circumstances. However, if the [BF](#) bit or the Receive Overflow Indicator ([SSPOV](#)) bit are set when a byte is received then the $\overline{\text{ACK}}$ will not be sent by the client.

When the module is addressed, after the eighth falling edge of SCL on the bus, the Acknowledge Time Status ([ACKTIM](#)) bit is set. The [ACKTIM](#) bit indicates the acknowledge time of the active bus. The [ACKTIM](#) bit is only active when either the [AHEN](#) bit or [DHEN](#) bit is enabled.

28.2.3 I²C Client Mode Operation

The MSSP Client mode operates in one of four modes selected by the MSSP Mode Select ([SSPM](#)) bits. The modes can be divided into 7-bit and 10-bit Addressing mode. 10-bit Addressing modes operate the same as 7-bit with some additional overhead for handling the larger addresses.

Modes with Start and Stop condition interrupts operate the same as the other modes with [SSPxIF](#) additionally getting set upon detection of a Start, Restart, or Stop condition.

28.2.3.1 Client Mode Addresses

The [SSPxADD](#) register contains the Client mode address. The first byte received after a Start or Restart condition is compared against the value stored in this register. If the byte matches, the value is loaded into the [SSPxBUF](#) register and an interrupt is generated. If the value does not match, the module goes Idle and no indication is given to the software that anything happened.

The [SSPxMSK](#) register affects the address matching process. See [SSP Mask Register](#) for more information.

28.2.3.1.1 I²C Client 7-Bit Addressing Mode

In 7-bit Addressing mode, the LSb of the received data byte is ignored when determining if there is an address match.

28.2.3.1.2 I²C Client 10-Bit Addressing Mode

In 10-bit Addressing mode, the first received byte is compared to the binary value of '1 1 1 0 A9 A8 0'. A9 and A8 are the two MSBs of the 10-bit address and stored in bits 2 and 1 of the **SSPxADD** register.

After the acknowledge of the high byte the Update Address (**UA**) bit is set and SCL is held low until the user updates **SSPxADD** with the low address. The low address byte is clocked in and all eight bits are compared to the low address value in **SSPxADD**. Even if there is not an address match, **SSPxIF** and **UA** are set, and SCL is held low until **SSPxADD** is updated to receive a high byte again. When **SSPxADD** is updated the **UA** bit is cleared. This ensures the module is ready to receive the high address byte on the next communication.

A high and low address match as a write request is required at the start of all 10-bit addressing communication. A transmission can be initiated by issuing a Restart once the client is addressed and clocking in the high address with the **R/W** bit set. The client hardware will then acknowledge the read request and prepare to clock out data. This is only valid for a client after it has received a complete high and low address byte match.

28.2.3.2 Clock Stretching

Clock stretching occurs when a device on the bus holds the SCL line low, effectively pausing communication. The client may stretch the clock to allow more time to handle data or prepare a response for the host device. A host device is not concerned with stretching as anytime it is active on the bus and not transferring data it is stretching. Any stretching done by a client is invisible to the host software and handled by the hardware that generates SCL.

The **CKP** bit is used to control stretching in software. Any time the **CKP** bit is cleared, the module will wait for the SCL line to go low and then hold it. Setting **CKP** will release SCL and allow more communication.

28.2.3.2.1 Normal Clock Stretching

Following an $\overline{\text{ACK}}$ if the **R/W** bit is set (a read request), the client hardware will clear **CKP**. This allows the client time to update **SSPxBUF** with data to transfer to the host. If the Stretch Enable (**SEN**) bit is set, the client hardware will always stretch the clock after the $\overline{\text{ACK}}$ sequence. Once the client is ready; **CKP** is set by software and communication resumes.

28.2.3.2.2 10-Bit Addressing Mode

In 10-bit Addressing mode, when the **UA** bit is set, the clock is always stretched. This is the only time the SCL is stretched without **CKP** being cleared. SCL is released immediately after a write to **SSPxADD**.

28.2.3.2.3 Byte NACKing

When the **AHEN** bit is set, **CKP** is cleared by hardware after the eighth falling edge of SCL for a received matching address byte. When the **DHEN** bit is set, **CKP** is cleared after the eighth falling edge of SCL for received data.

Stretching after the eighth falling edge of SCL allows the client to look at the received address or data and decide if it wants to acknowledge ($\overline{\text{ACK}}$) the received address or data or not acknowledge (**NACK**) the address or data.

28.2.3.3 Clock Synchronization and the CKP Bit

Any time the **CKP** bit is cleared, the module will wait for the SCL line to go low and then hold it. However, clearing the **CKP** bit will not assert the SCL output low until the SCL output is already sampled low. Therefore, the **CKP** bit will not assert the SCL line until an external I²C host device has already asserted the SCL line. The SCL output will remain low until the **CKP** bit is set and all other devices on the I²C bus have released SCL.

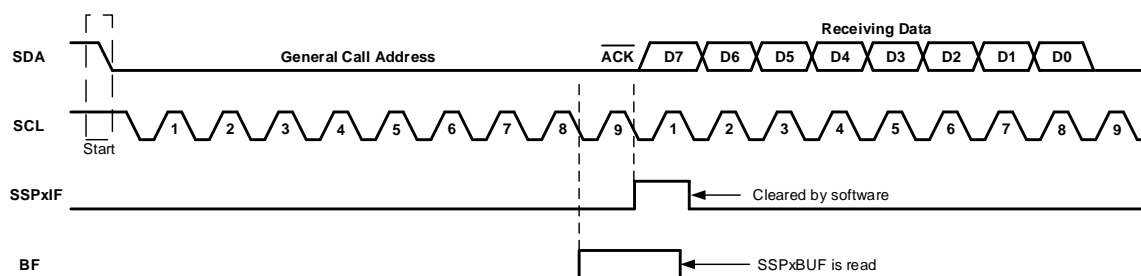
28.2.3.4 General Call Address Support

The addressing procedure for the I²C bus is such that the first byte after the Start condition usually determines which device will be the client addressed by the host device. The exception is the

General Call address that can address all devices. When this address is used, all devices must, in theory, respond with an $\overline{\text{ACK}}$.

The general call address is a reserved address in the I²C protocol, defined as address 0x00. When the General Call Enable (**GCEN**) bit is set, the client module will automatically $\overline{\text{ACK}}$ the reception of this address regardless of the value stored in **SSPxADD**. After the client clocks in an address of all zeros with the **R/W** bit clear, an interrupt is generated and client software can read **SSPxBUF** and respond. Figure 28-14 shows a General Call reception sequence.

Figure 28-14. Client Mode General Call Address Sequence



In 10-bit Address mode, the **UA** bit will not be set on the reception of the general call address. The client will prepare to receive the second byte as data, just as it would in 7-bit mode.

If the **AHEN** bit is set, just as with any other address reception, the client hardware will stretch the clock after the eighth falling edge of SCL. The client must then set its Acknowledge Sequence Enable (**ACKEN**) bit and release the clock.

28.2.3.5 SSP Mask Register

The MSSP Mask (**SSPxMSK**) register is available in I²C Client mode as a mask for the value held in the SSPSR register during an address comparison operation. A zero ('0') bit in the SSPxMSK register has the effect of making the corresponding bit of the received address a "don't care".

This register is reset to all '1's upon any Reset condition and, therefore, has no effect on standard MSSP operation until written with a mask value.

SSPxMSK is active during:

- 7-bit Address mode: Address compare of A[7:1]
- 10-bit Address mode: Address compare of A[7:0] only. The MSSP mask has no effect during the reception of the first (high) byte of the address.

28.2.3.6 Client Reception

When the **R/W** bit of a matching received address byte is clear, the **R/W** bit is cleared. The received address is loaded into the **SSPxBUF** register and acknowledged.

When the Overflow condition exists for a received address, a Not Acknowledge (NACK) is transmitted and the Receive Overflow Indicator (**SSPOV**) bit is set. The Buffer Override Enable (**BOEN**) bit modifies this operation.

An MSSP interrupt is generated for each transferred data byte. The SSPxIF flag bit must be cleared by software.

When the **SEN** bit is set, SCL will be held low (clock stretch) following each received byte. The clock must be released by setting the **CKP** bit, except sometimes in 10-bit mode. See [10-Bit Addressing Mode](#) for more details.

28.2.3.6.1 7-Bit Addressing Reception

This section describes a standard sequence of events for the MSSP module configured as an I²C client in 7-bit Addressing mode. [Figure 28-15](#) and [Figure 28-16](#) are used as a visual reference for this description.

This is a step by step process of what typically must be done to accomplish I²C communication.

1. Start condition detected.
2. The Start (S) bit is set; SSPxIF is set if the Start Condition Interrupt Enable (SCIE) bit is set.
3. Matching address with R/W bit clear is received.
4. The client pulls SDA low, sends an $\overline{\text{ACK}}$ to the host, and sets the SSPxIF bit.
5. Software clears the SSPxIF bit.
6. Software reads received address from SSPxBUF, clearing the BF flag.
7. If SEN = 1; Client software sets the CKP bit to release the SCL line.
8. The host clocks out a data byte.
9. The client drives SDA low, sends an $\overline{\text{ACK}}$ to the host, and sets the SSPxIF bit.
10. Software clears SSPxIF.
11. Software reads the received byte from SSPxBUF, clearing BF.
12. Steps 8-12 are repeated for all received bytes from the host.
13. Host sends Stop condition, setting the Stop (P) bit, and the bus goes Idle.

Figure 28-15. I²C Client, 7-Bit Address, Reception (SEN = 0, AHEN = 0, DHEN = 0)

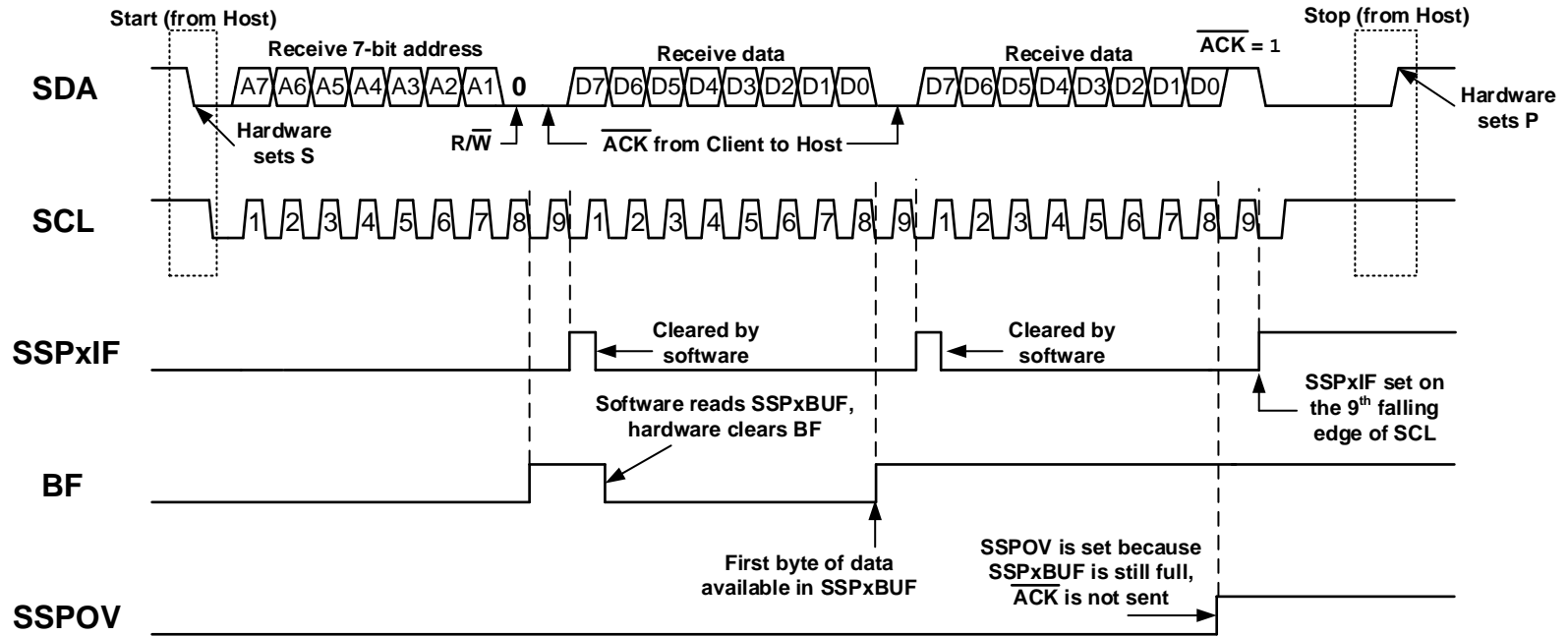
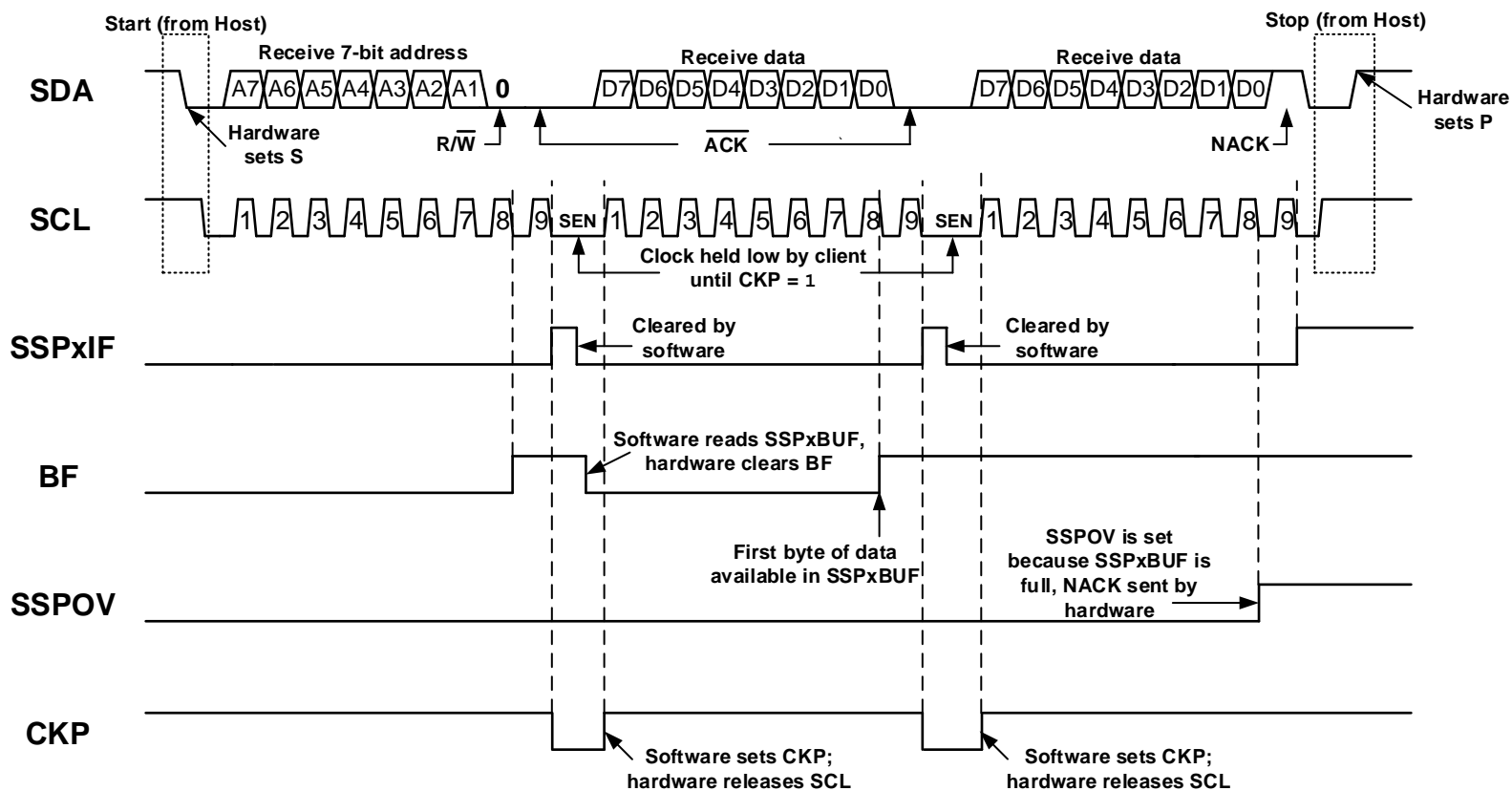


Figure 28-16. I²C Client, 7-Bit Address, Reception (SEN = 1, AHEN = 0, DHEN = 0)



28.2.3.6.2 7-Bit Reception with AHEN and DHEN

Client device reception with **AHEN** and **DHEN** set operate the same as without these options with extra interrupts and clock stretching added after the eighth falling edge of SCL. These additional interrupts allow the client software to decide whether it wants to $\overline{\text{ACK}}$ the receive address or data byte, rather than the hardware. This functionality adds support for PMBus™ that was not present on previous versions of this module.

This list describes the steps that need to be taken by client software to use these options for I²C communication. [Figure 28-17](#) displays a module using both address and data holding. [Figure 28-18](#) includes the operation with the **SEN** bit set.

1. The Start (**S**) bit is set; SSPxIF is set if **SCIE** is set.
2. Matching address with the **R/W** bit clear is clocked in. SSPxIF is set and **CKP** cleared after the eighth falling edge of SCL.
3. Software clears the SSPxIF.
4. Client can look at the **ACKTIM** bit to determine if the SSPxIF was after or before the $\overline{\text{ACK}}$.
5. Client reads the address value from **SSPxBUF**, clearing the **BF** flag.
6. Client transmits an $\overline{\text{ACK}}$ to the host by clearing **ACKDT**.
7. Client releases the clock by setting **CKP**.
8. SSPxIF is set after an $\overline{\text{ACK}}$, not after a NACK.
9. If **SEN** = 1, the client hardware will stretch the clock after the $\overline{\text{ACK}}$.
10. Client clears SSPxIF.



Important: SSPxIF is still set after the ninth falling edge of SCL even if there is no clock stretching and BF has been cleared. Only if a NACK is sent to the host is SSPxIF not set.

11. SSPxIF is set and **CKP** cleared after eighth falling edge of SCL for a received data byte.
12. Client looks at the **ACKTIM** bit to determine the source of the interrupt.
13. Client reads the received data from **SSPxBUF**, clearing **BF**.
14. Steps 7-14 are the same for each received data byte.
15. Communication is ended by either the client sending a NACK or the host sending a Stop condition. If a Stop is sent and the Stop Condition Interrupt Enable (**PCIE**) bit is clear, the client will only know by polling the Stop (**P**) bit.

Figure 28-17. I²C Client, 7-Bit Address, Reception (SEN = 0, AHEN = 1, DHEN = 1)

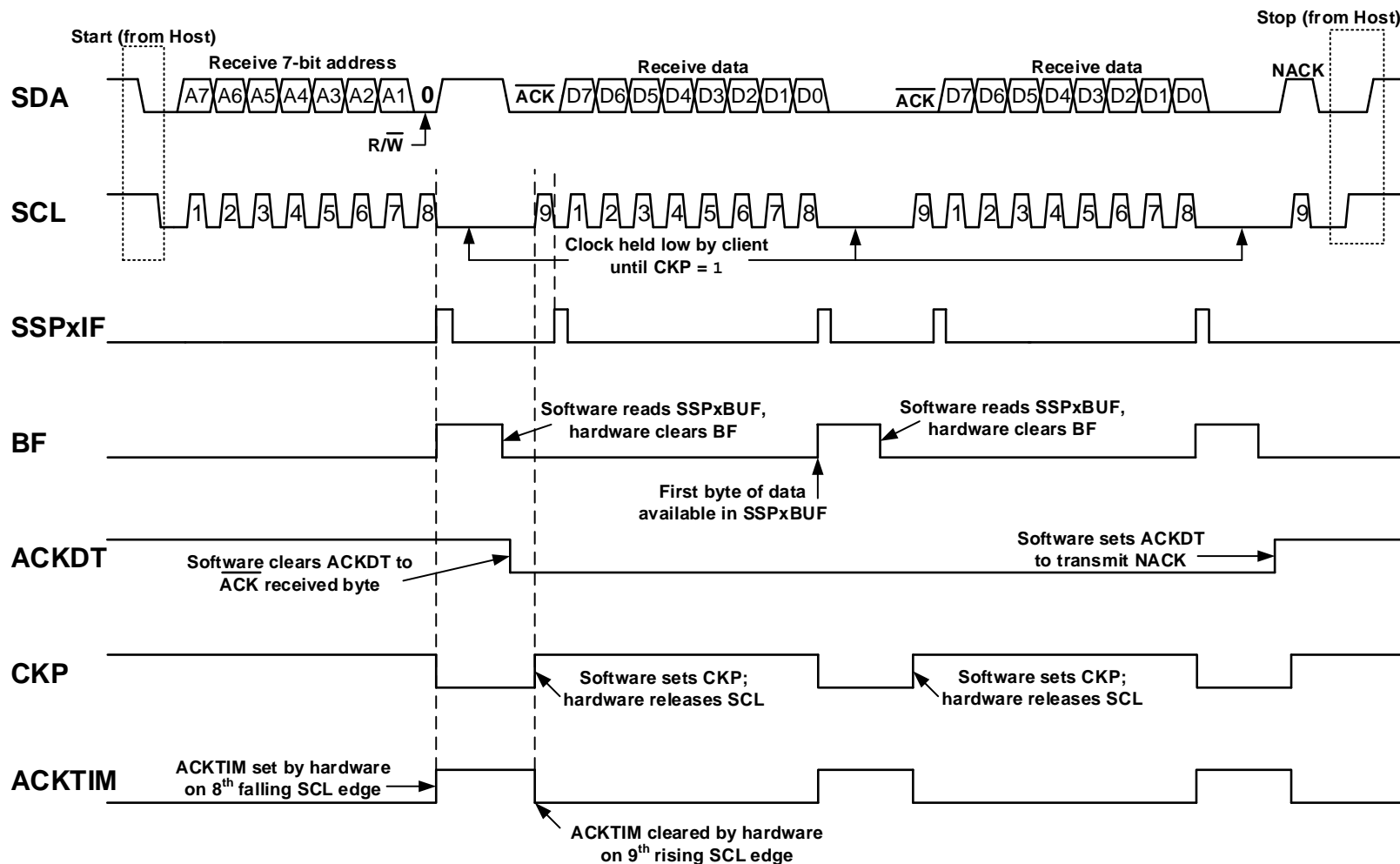
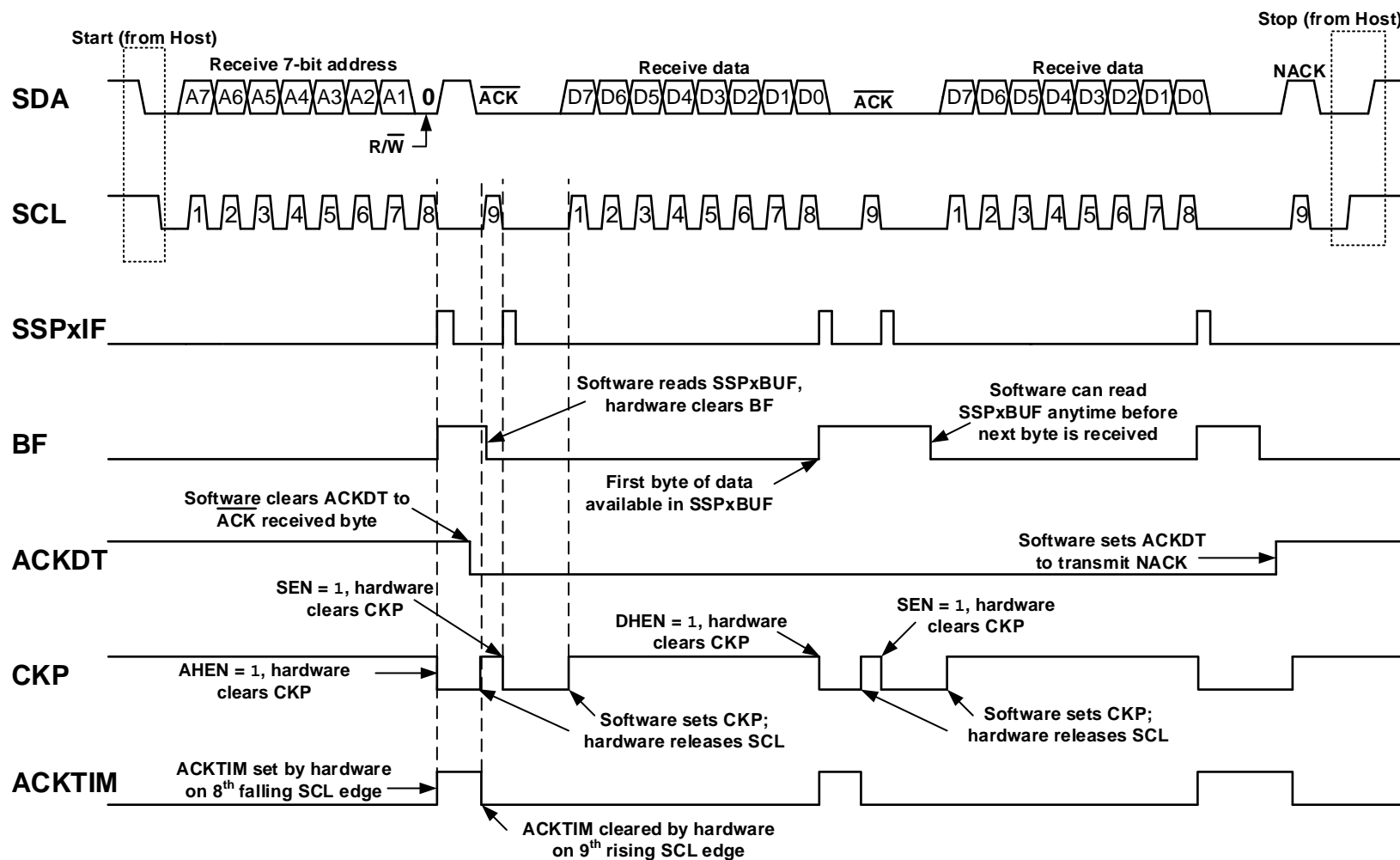


Figure 28-18. I²C Client, 7-Bit Address, Reception (SEN = 1, AHEN = 1, DHEN = 1)



28.2.3.6.3 Client Mode 10-Bit Address Reception


This section describes a standard sequence of events for the MSSP module configured as an I²C client in 10-bit Addressing mode. Figure 28-19 shows a standard waveform for a client receiver in 10-bit Addressing mode with clock stretching enabled.

This is a step-by-step process of what must be done by the client software to accomplish I²C communication.

1. Bus starts Idle.
2. Host sends Start condition; **S** bit is set; SSPxIF is set if **SCIE** is set.
3. Host sends matching high address with the **R/W** bit clear; the **UA** bit is set.
4. Client sends $\overline{\text{ACK}}$ and SSPxIF is set.
5. Software clears the SSPxIF bit.
6. Software reads received address from **SSPxBUF**, clearing the **BF** flag.
7. Client loads low address into **SSPxADD**, releasing SCL.
8. Host sends matching low address byte to the client; **UA** bit is set.

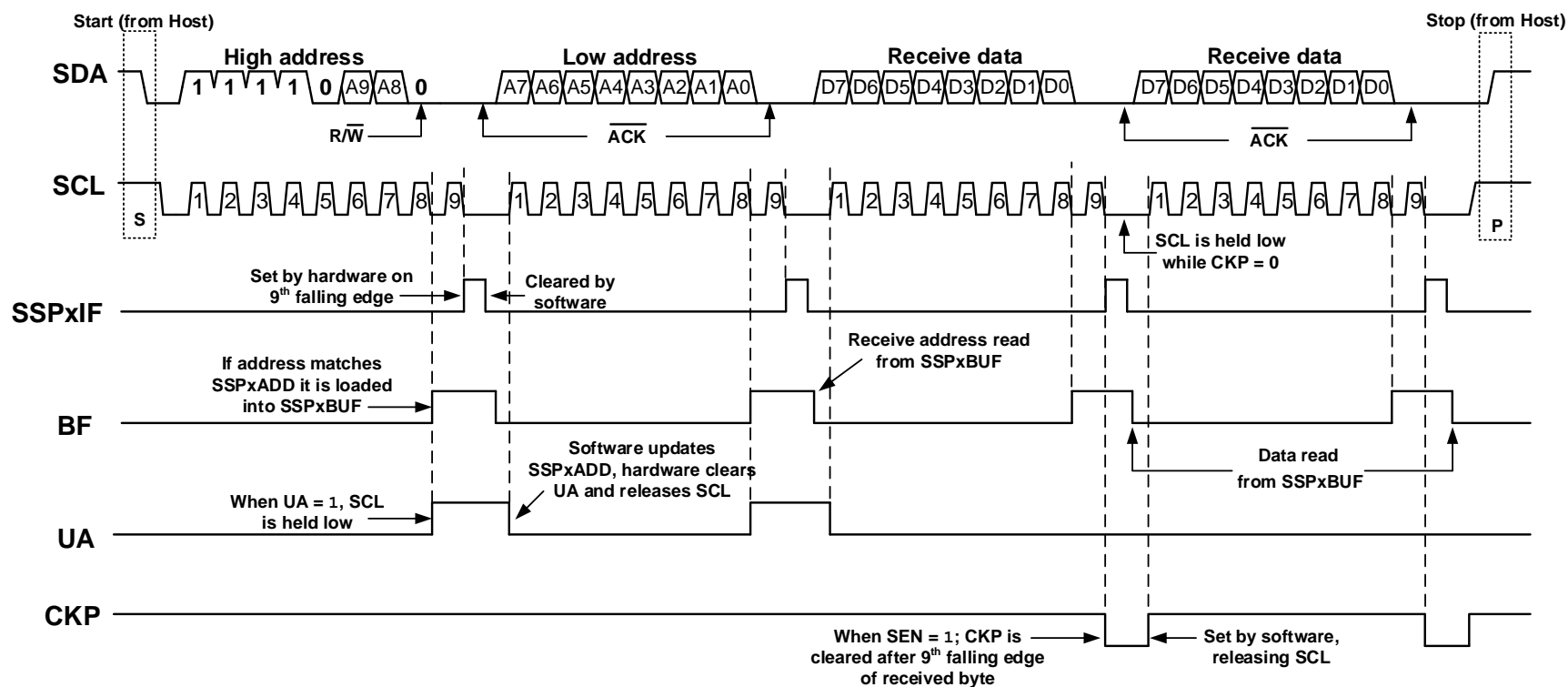
 **Important:** Updates to the SSPxADD register are not allowed until after the $\overline{\text{ACK}}$ sequence.

9. Client sends $\overline{\text{ACK}}$ and SSPxIF is set.

 **Important:** If the low address does not match, SSPxIF and **UA** are still set so that the client software can set SSPxADD back to the high address. **BF** is not set because there is no match. **CKP** is unaffected.

10. Client clears SSPxIF.
11. Client reads the received matching address from SSPxBUF, clearing **BF**.
12. Client loads high address into SSPxADD.
13. Host clocks a data byte to the client and clocks out the client $\overline{\text{ACK}}$ on the ninth SCL pulse; SSPxIF is set.
14. If the **SEN** bit is set, **CKP** is cleared by hardware and the clock is stretched.
15. Client clears SSPxIF.
16. Client reads the received byte from SSPxBUF, clearing **BF**.
17. If **SEN** is set the client software sets **CKP** to release the SCL.
18. Steps 13-17 repeat for each received byte.
19. Host sends Stop to end the transmission.

Figure 28-19. I²C Client, 10-Bit Address, Reception (SEN = 1, AHEN = 0, DHEN = 0)



28.2.3.6.4 10-Bit Addressing with Address or Data Hold

Reception using 10-bit addressing with [AHEN](#) or [DHEN](#) set is the same as with 7-bit modes. The only difference is the need to update the [SSPxADD](#) register using the [UA](#) bit. All functionality, specifically when the [CKP](#) bit is cleared and SCL line is held low, are the same. [Figure 28-20](#) can be used as a reference of a client in 10-bit addressing with AHEN set.

[Figure 28-21](#) shows a standard waveform for a client transmitter in 10-bit Addressing mode.

Figure 28-20. I²C Client, 10-Bit Address, Reception (SEN = 0, AHEN = 1, DHEN = 0)

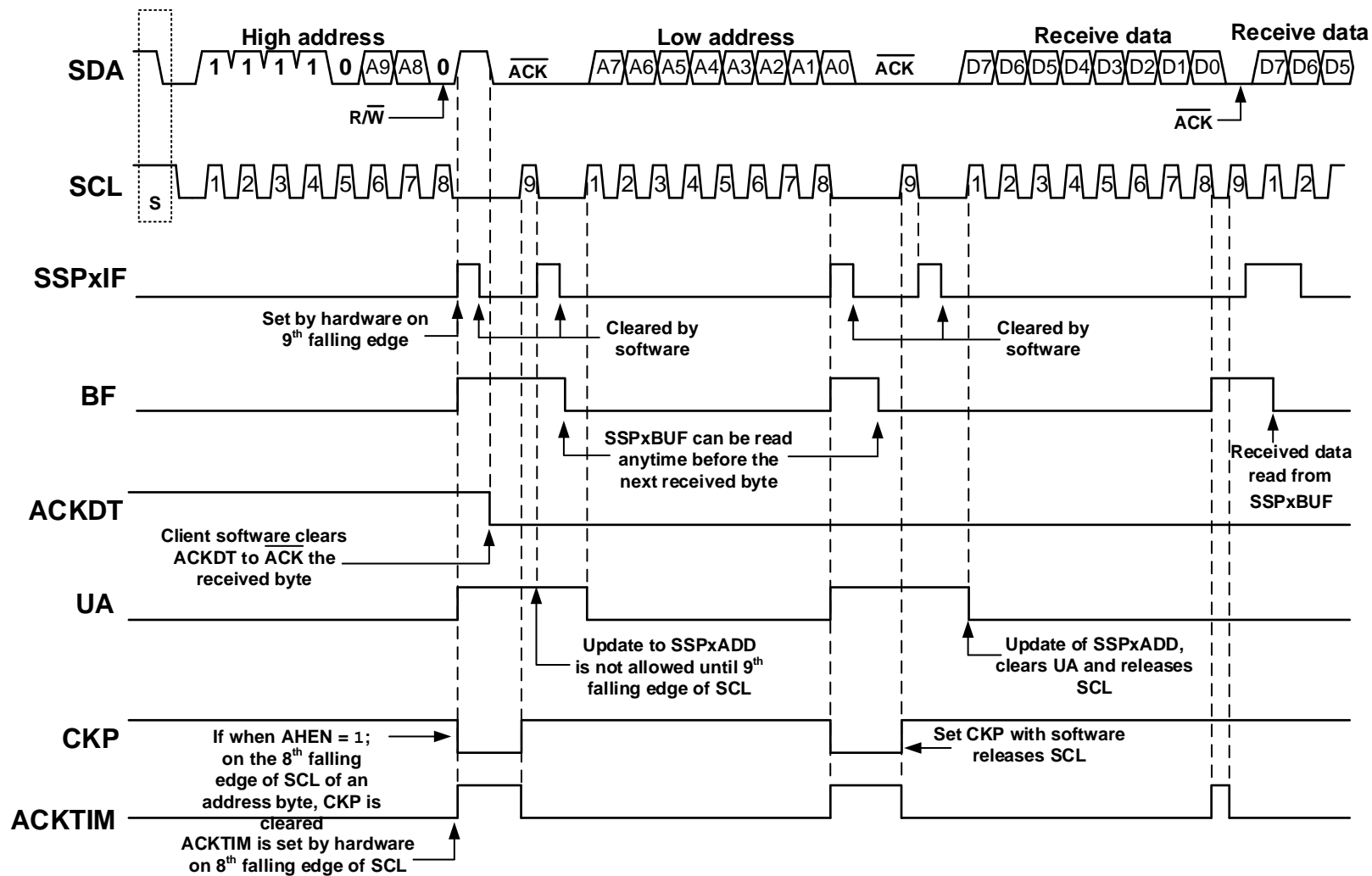
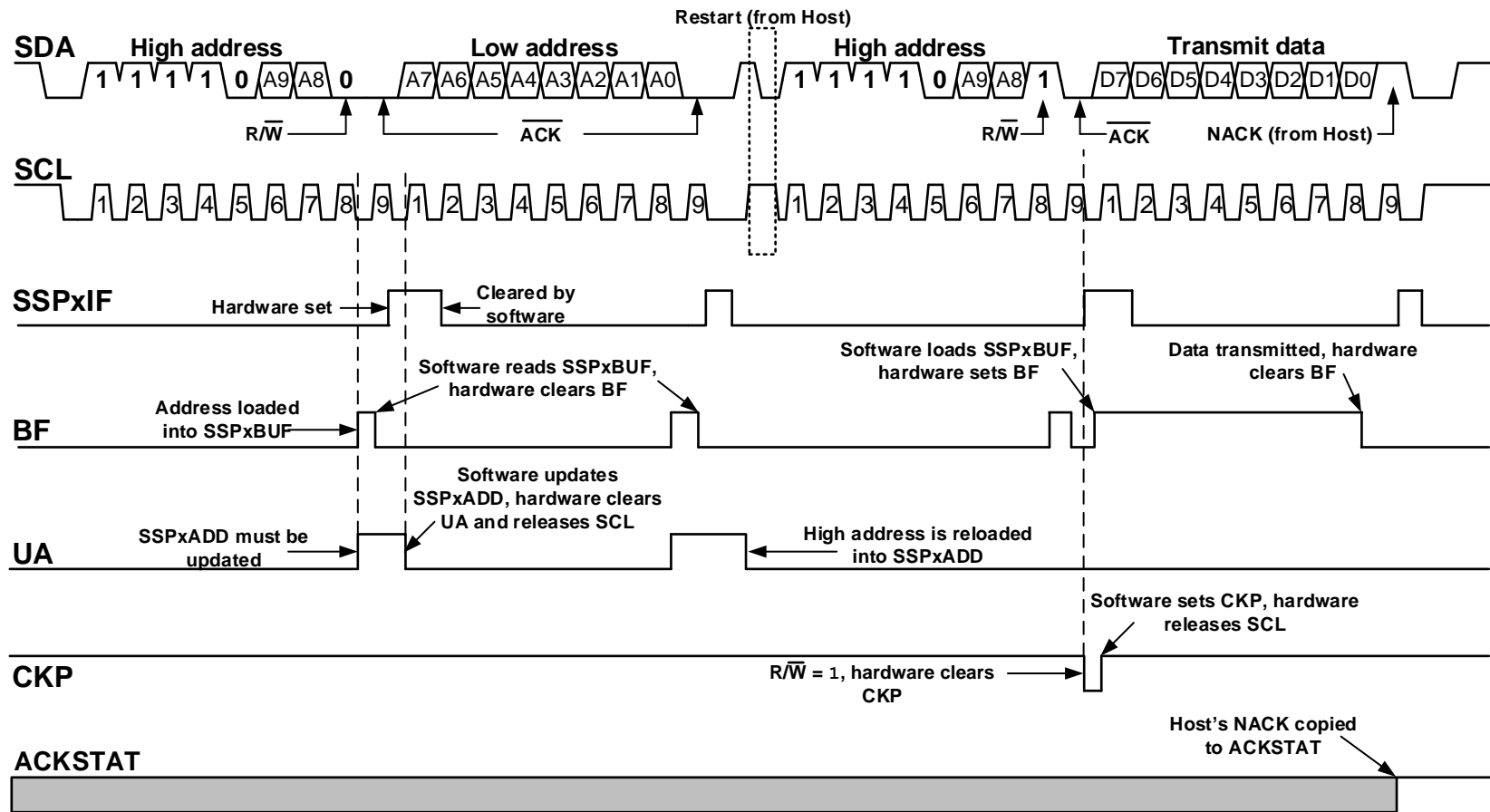


Figure 28-21. I²C Client, 10-Bit Address, Transmission (SEN = 0, AHEN = 0, DHEN = 0)



28.2.3.7 Client Transmission

When the R/\overline{W} bit of the incoming address byte is set and an address match occurs, the R/\overline{W} bit is set. The received address is loaded into the **SSPxBUF** register, and an \overline{ACK} pulse is sent by the client on the ninth bit.

Following the \overline{ACK} , client hardware clears the **CKP** bit and the SCL pin is held low (see [Clock Stretching](#) for more details). By stretching the clock, the host will be unable to assert another clock pulse until the client is done preparing the transmit data.

The transmit data must be loaded into the **SSPxBUF** register, which also loads the **SSPSR** register. Then the SCL pin will be released by setting the **CKP** bit. The eight data bits are shifted out on the falling edge of the SCL input. This ensures that the SDA signal is valid during the SCL high time.

The \overline{ACK} pulse from the host receiver is latched on the rising edge of the ninth SCL input pulse. This \overline{ACK} value is copied to the **ACKSTAT** bit. If **ACKSTAT** is set (NACK), then the data transfer is complete. In this case, when the NACK is latched by the client, the client goes Idle and waits for another occurrence of a Start condition. If the SDA line was low (\overline{ACK}), the next transmit data must be loaded into the **SSPxBUF** register. Again, the SCL pin must be released by setting bit **CKP**.

An MSSP interrupt is generated for each data transfer byte. The **SSPxIF** bit must be cleared by software and the **SSPxSTAT** register is used to determine the status of the byte. The **SSPxIF** bit is set on the falling edge of the ninth clock pulse.

28.2.3.7.1 Client Mode Bus Collision

A client receives a read request and begins shifting data out on the SDA line. If a bus collision is detected and the Client Mode Bus Collision Detect Enable (**SBCDE**) bit is set, the Bus Collision Interrupt Flag (**BCLxIF**) bit of the **PIRx** register is set. Once a bus collision is detected, the client goes Idle and waits to be addressed again. User software can use the **BCLxIF** bit to handle a client bus collision.

28.2.3.7.2 7-Bit Transmission

A host device can transmit a read request to a client and clock data out of the client. The list below outlines what software for a client will need to do to accomplish a standard transmission. [Figure 28-22](#) can be used as a reference to this list.

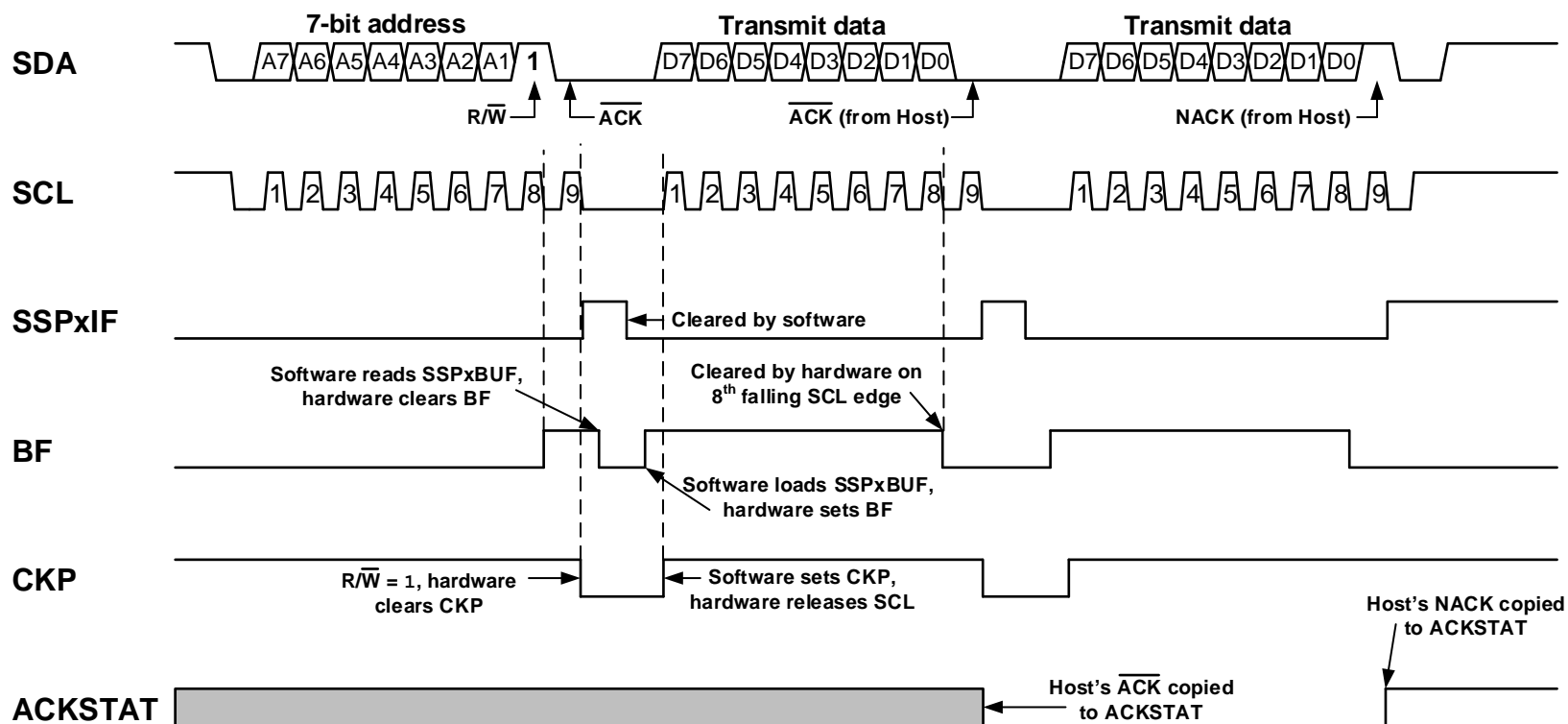
1. Host sends a Start condition.
2. The Start (**S**) bit is set; **SSPxIF** is set if **SCIE** is set.
3. Matching address with R/\overline{W} bit set is received by the Client, setting **SSPxIF** bit.
4. Client hardware generates an \overline{ACK} and sets **SSPxIF**.
5. The **SSPxIF** bit is cleared by software.
6. Software reads the received address from **SSPxBUF**, clearing **BF**.
7. R/\overline{W} is set so **CKP** was automatically cleared after the \overline{ACK} .
8. The client software loads the transmit data into **SSPxBUF**.
9. **CKP** bit is set by software, releasing SCL, allowing the host to clock the data out of the client.
10. **SSPxIF** is set after the \overline{ACK} response from the host is loaded into the **ACKSTAT** bit.
11. **SSPxIF** bit is cleared.
12. The client software checks the **ACKSTAT** bit to see if the host wants to clock out more data.

Important:

1. If the host \overline{ACK} s then the clock will be stretched.
2. **ACKSTAT** is the only bit updated on the rising edge of the ninth SCL clock instead of the falling edge.

13. Steps 9-13 are repeated for each transmitted byte.
14. If the host sends a not \overline{ACK} ; the clock is not held, but SSPxIF is still set.
15. The host sends a Restart condition or a Stop.

Figure 28-22. I²C Client, 7-Bit Address, Transmission (AHEN = 0)



28.2.3.7.3 7-Bit Transmission with Address Hold Enabled

Setting the **AHEN** bit enables additional clock stretching and interrupt generation after the eighth falling edge of a received matching address. Once a matching address has been clocked in, **CKP** is cleared and the **SSPxIF** interrupt is set.

Figure 28-23 displays a standard waveform of a 7-bit address client transmission with **AHEN** enabled.

1. Bus starts Idle.
2. Host sends Start condition; the **S** bit is set; **SSPxIF** is set if **SCIE** is set.
3. Host sends matching address with the **R/W** bit set. After the eighth falling edge of the SCL line the **CKP** bit is cleared and **SSPxIF** interrupt is generated.
4. Client software clears **SSPxIF**.
5. Client software reads the **ACKTIM**, **R/W** and **D/A** bits to determine the source of the interrupt.
6. Client reads the address value from the **SSPxBUF** register, clearing the **BF** bit.
7. Client software decides from this information if it wishes to $\overline{\text{ACK}}$ or **NACK** and sets the **ACKDT** bit accordingly.
8. Client software sets the **CKP** bit, releasing SCL.
9. Host clocks in the $\overline{\text{ACK}}$ value from the client.
10. Client hardware automatically clears the **CKP** bit and sets **SSPxIF** after $\overline{\text{ACK}}$ if the **R/W** bit is set.
11. Client software clears **SSPxIF**.
12. Client loads value to transmit to the host into **SSPxBUF**, setting the **BF** bit.



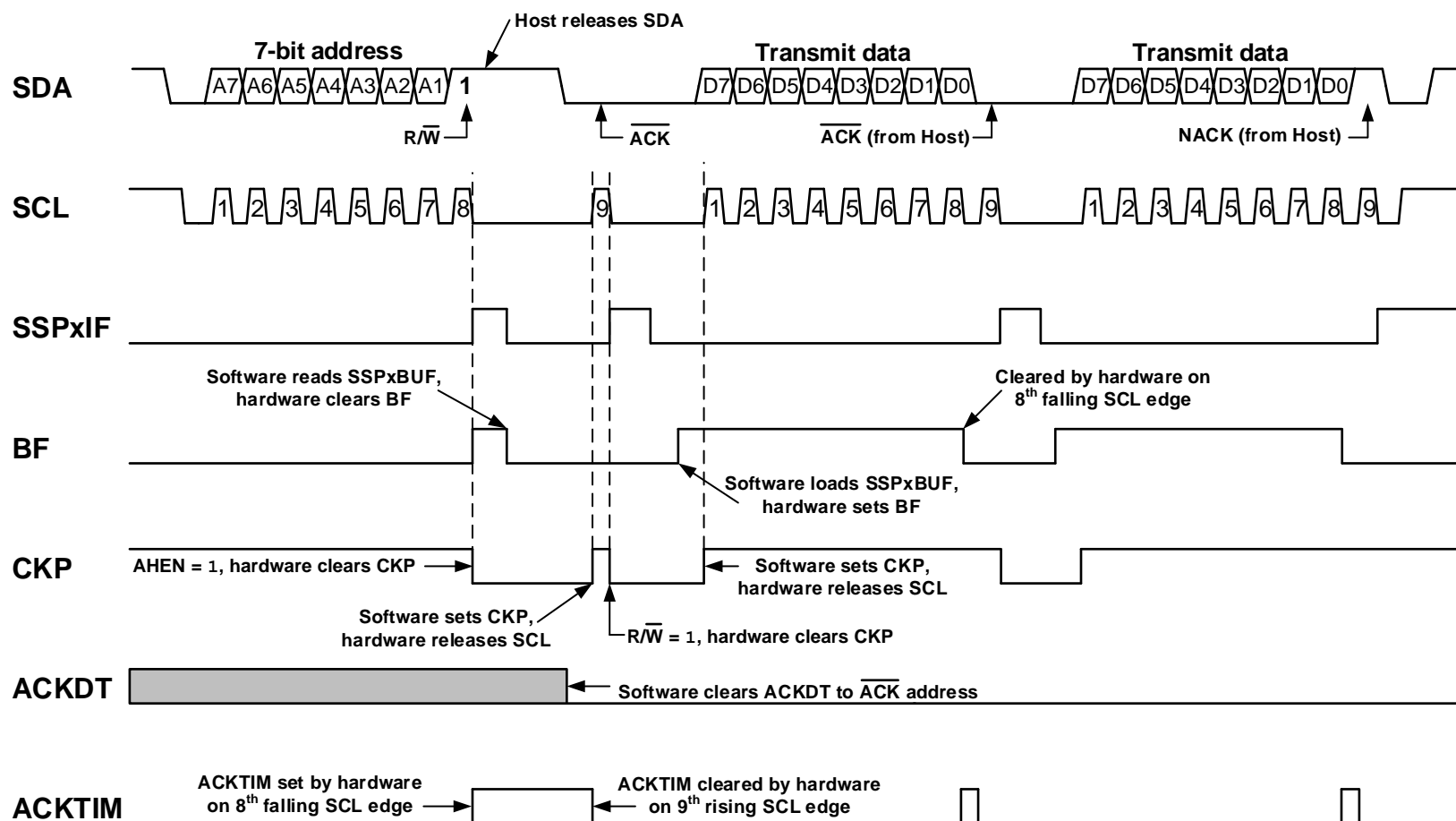
Important: **SSPxBUF** cannot be loaded until after the $\overline{\text{ACK}}$.

13. Client software sets the **CKP** bit, releasing the clock.
14. Host clocks out the data from the client and sends an $\overline{\text{ACK}}$ value on the ninth SCL pulse.
15. Client hardware copies the $\overline{\text{ACK}}$ value into the **ACKSTAT** bit.
16. Steps 10-15 are repeated for each byte transmitted to the host from the client.
17. If the host sends a not $\overline{\text{ACK}}$, the client releases the bus allowing the host to send a Stop and end the communication.



Important: Host must send a not $\overline{\text{ACK}}$ on the last byte to ensure that the client releases the SCL line to receive a Stop.

Figure 28-23. I²C Client, 7-Bit Address, Transmission (AHEN = 1)



28.2.4 I²C Host Mode

Host mode is enabled by configuring the appropriate [SSPM](#) bits and setting the [SSPEN](#) bit. In Host mode, the SDA and SCL pins must be configured as inputs. The MSSP peripheral hardware will override the output driver TRIS controls when necessary to drive the pins low.

Host mode of operation is supported by interrupt generation on the detection of the Start and Stop conditions. The Stop ([P](#)) and Start ([S](#)) bits are cleared from a Reset or when the MSSP module is disabled. Control of the I²C bus may be taken when the P bit is set or when the bus is Idle.

In Firmware Controlled Host mode, user code conducts all I²C bus operations based on Start and Stop condition detection. Start and Stop condition detection is the only active circuitry in this mode. All other communication is done by the user software directly manipulating the SDA and SCL lines.

The following events will cause the MSSP Interrupt Flag (SSPxIF) bit to be set (MSSP interrupt, if enabled):

- Start condition detected
- Stop condition detected
- Data transfer byte transmitted/received
- Acknowledge transmitted/received
- Repeated Start generated



Important:

1. The MSSP module, when configured in I²C Host mode, does not allow queuing of events. For instance, the user is not allowed to initiate a Start condition and immediately write the [SSPxBUF](#) register to initiate transmission before the Start condition is complete. In this case, SSPxBUF will not be written to and the Write Collision Detect ([WCOL](#)) bit will be set, indicating that a write to SSPxBUF did not occur.
2. Host mode suspends Start/Stop detection when sending the Start/Stop condition by means of the [SEN/PEN](#) control bits. The SSPxIF bit is set at the end of the Start/Stop generation when hardware clears the control bit.

28.2.4.1 I²C Host Mode Operation

The host device generates all of the serial clock pulses and the Start and Stop conditions. A transfer is ended with a Stop condition or with a Repeated Start condition. Since the Repeated Start condition is also the beginning of the next serial transfer, the I²C bus will not be released.

In Host Transmitter mode, serial data are output through SDA, while SCL outputs the serial clock. The first byte transmitted contains the client address of the receiving device (seven bits) and the R/W bit. In this case, the [R/W](#) bit will be logic '0'. Serial data are transmitted eight bits at a time. After each byte is transmitted, an Acknowledge bit is received. Start and Stop conditions are output to indicate the beginning and the end of a serial transfer.

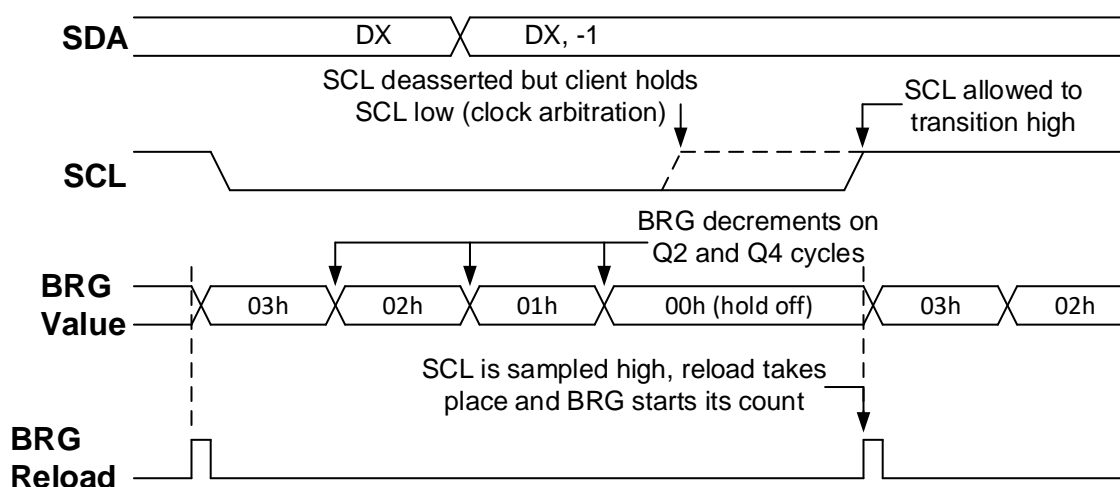
In Host Receive mode, the first byte transmitted contains the client address of the transmitting device (seven bits) and the R/W bit. In this case, the R/W bit will be logic '1'. Thus, the first byte transmitted is a 7-bit client address followed by a '1' to indicate the receive bit. Serial data are received via SDA, while SCL outputs the serial clock. Serial data are received eight bits at a time. After each byte is received, an Acknowledge sequence is transmitted. Start and Stop conditions indicate the beginning and end of transmission.

A Baud Rate Generator is used to set the clock frequency output on SCL. See [Baud Rate Generator](#) for more details.

28.2.4.1.1 Clock Arbitration

Clock arbitration occurs when the host, during any receive, transmit or Repeated Start/Stop condition, releases the SCL pin (SCL allowed to float high). When the SCL pin is allowed to float high, the Baud Rate Generator (BRG) is suspended from counting until the SCL pin is actually sampled high. When the SCL pin is sampled high, the Baud Rate Generator is reloaded with the contents of [SSPxADD](#) and begins counting. This ensures that the SCL high time will always be at least one BRG rollover count in the event that the clock is held low by an external device as shown in [Figure 28-24](#).

Figure 28-24. Baud Rate Generator Timing with Clock Arbitration



28.2.4.1.2 WCOL Status Flag

If the user writes the [SSPxBUF](#) when a Start, Restart, Stop, Receive or Transmit sequence is in progress, the Write Collision Detect ([WCOL](#)) bit is set and the contents of the buffer are unchanged (the write does not occur). Any time the WCOL bit is set it indicates that an action on [SSPxBUF](#) was attempted while the module was not Idle.



Important: Because queuing of events is not allowed, writing to the lower five bits of [SSPxCON2](#) is disabled until the Start condition is complete.

28.2.4.1.3 I²C Host Mode Start Condition Timing

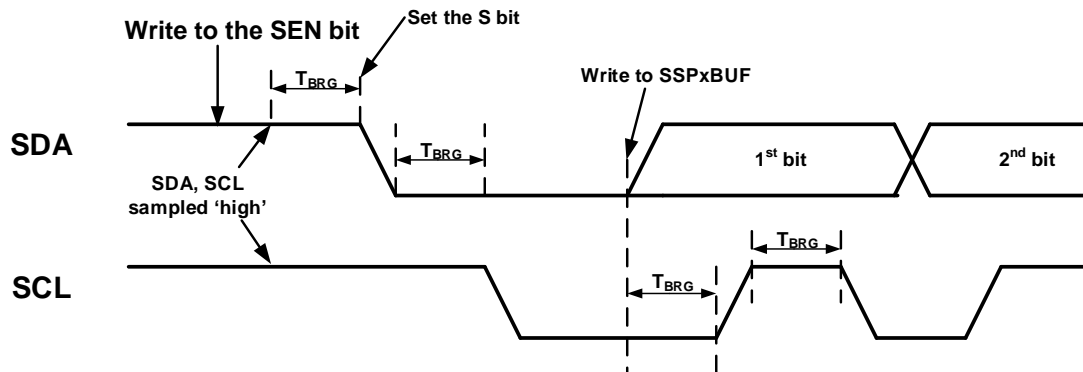
To initiate a Start condition (see [Figure 28-25](#)), the user sets the Start Condition Enable ([SEN](#)) bit. If the SDA and SCL pins are sampled high, the Baud Rate Generator is reloaded with the contents of [SSPxADD](#) and starts its count. If SCL and SDA are both sampled high when the Baud Rate Generator times out (T_{BRG}), the SDA pin is driven low. The action of the SDA being driven low while SCL is high is the Start condition and causes the Start ([S](#)) bit to be set. Following this, the Baud Rate Generator is reloaded with the contents of [SSPxADD](#) and resumes its count. When the Baud Rate Generator times out (T_{BRG}), the [SEN](#) bit will be automatically cleared by hardware; the Baud Rate Generator is suspended, leaving the SDA line held low and the Start condition is complete.

Important:

1. If at the

1. If at the beginning of the Start condition, the SDA and SCL pins are already sampled low, or if during the Start condition, the SCL line is sampled low before the SDA line is driven low, a bus collision occurs, the Bus Collision Interrupt Flag (BCLxIF) is set, the Start condition is aborted, and the I²C module is reset into its Idle state.
2. The Philips I²C Specification states that a bus collision cannot occur on a Start.

Figure 28-25. First Start Bit Timing



28.2.4.1.4 I²C Host Mode Repeated Start Condition Timing

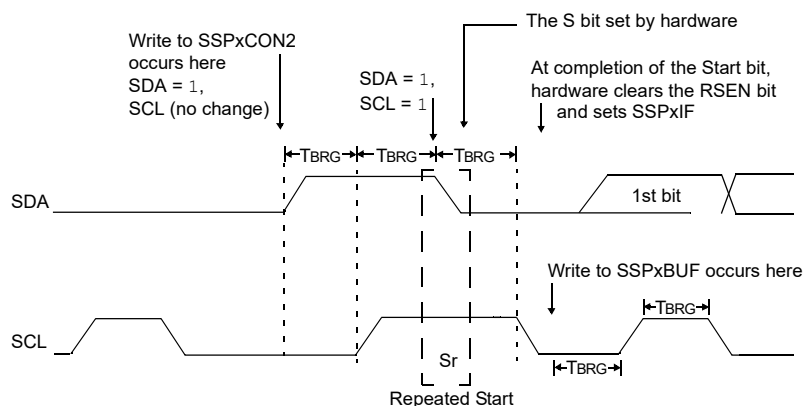
A Repeated Start condition (see [Figure 28-26](#)) occurs when the Repeated Start Condition Enable (RSEN) bit is programmed high and the host state machine is Idle. When the RSEN bit is set, the SCL pin is asserted low. When the SCL pin is sampled low, the Baud Rate Generator is loaded and begins counting. The SDA pin is released (brought high) for one Baud Rate Generator count (T_{BRG}). When the Baud Rate Generator times out, if SDA is sampled high, the SCL pin will be deasserted (brought high). When SCL is sampled high, the Baud Rate Generator is reloaded and begins counting. SDA and SCL must remain high for one T_{BRG} . Module hardware then pulls the SDA line low (while SCL remains high) for one T_{BRG} and then pulls the SCL line low. Following this, the RSEN bit will be automatically cleared and the Baud Rate Generator will not be reloaded, leaving the SDA pin held low. As soon as a Start condition is detected on the SDA and SCL pins, the S bit will be set. The SSPxIF bit will not be set until the Baud Rate Generator has timed out.

Important:

1. If $PCENL$ is

1. If RSEN is programmed while any other event is in progress, it will not take effect.
2. A bus collision during the Repeated Start condition occurs if:
 - SDA is sampled low when SCL goes from low-to-high.
 - SCL goes low before SDA is asserted low. This may indicate that another host is attempting to transmit a data '1'.

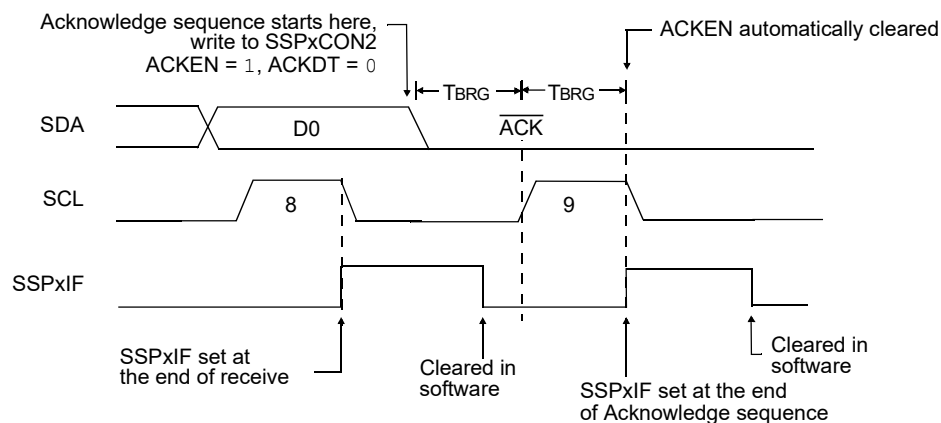
Figure 28-26. Repeated Start Condition Waveform

Rev. 30-000037B
4/10/2017

28.2.4.1.5 Acknowledge Sequence Timing

An Acknowledge sequence (see Figure 28-27) is enabled by setting the Acknowledge Sequence Enable (**ACKEN**) bit. When this bit is set, the SCL pin is pulled low and the contents of the Acknowledge Data (**ACKDT**) bit are presented on the SDA pin. If the user wishes to generate an Acknowledge, then the **ACKDT** bit must be cleared. If not, the user must set the **ACKDT** bit before starting an Acknowledge sequence. The Baud Rate Generator then counts for one rollover period (T_{BRG}) and the SCL pin is deasserted (pulled high). When the SCL pin is sampled high (clock arbitration), the Baud Rate Generator counts for T_{BRG} . The SCL pin is then pulled low. Following this, the **ACKEN** bit is automatically cleared, the Baud Rate Generator is turned off and the MSSP module then goes into Idle mode.

Figure 28-27. Acknowledge Sequence Waveform

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4/3/2017

Note: T_{BRG} = one Baud Rate Generator period.

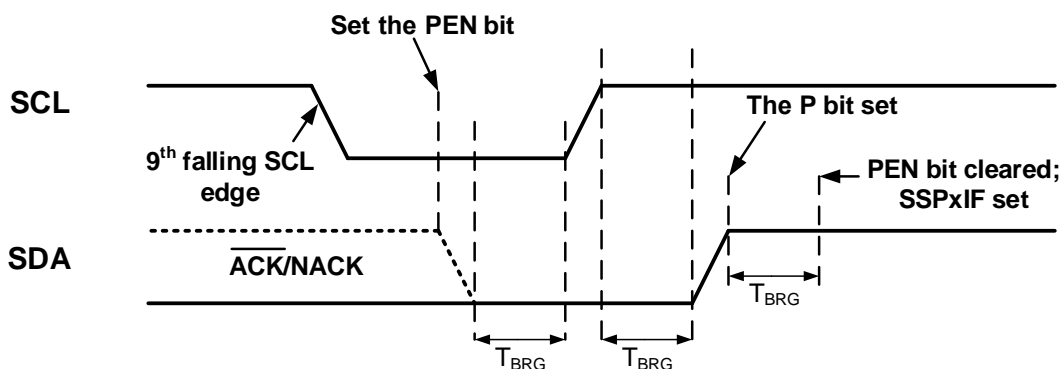
Acknowledge Write Collision

If the user writes the **SSPxBUF** when an Acknowledge sequence is in progress, then the **WCOL** bit is set and the contents of the buffer are unchanged (the write does not occur).

28.2.4.1.6 Stop Condition Timing

A Stop condition (see Figure 28-28) is asserted on the SDA pin at the end of a receive/transmit by setting the Stop Condition Enable (**PEN**) bit. At the end of a receive/transmit, the SCL line is held low after the falling edge of the ninth clock. When the **PEN** bit is set, the host will assert the SDA line low. When the SDA line is sampled low, the Baud Rate Generator is reloaded and counts down to '0'.

Figure 28-28. Stop Condition in Receive or Transmit Mode



If the user writes the **SSPXBUF** when a Stop sequence is in progress, then the **WCOL** bit is set and the contents of the buffer are unchanged (the write does not occur).

While in Sleep mode, the I²C client module can receive addresses or data and when an address match or complete byte transfer occurs, wake the processor from Sleep (if the MSSP interrupt is enabled).

A Reset disables the MSSP module and terminates the current transfer.

Transmission of a data byte, a 7-bit address or the other half of a 10-bit address is accomplished by simply writing a value to the **SSPxBUF** register. This action will set the Buffer Full Status (**BF**) bit and allow the Baud Rate Generator to begin counting and start the next transmission.

After the write to the SSPxBUF, each bit of the address will be shifted out on the falling edge of SCL until all seven address bits and the $\overline{\text{R}/\text{W}}$ bit are completed. On the falling edge of the eighth clock, the host will release the SDA pin, allowing the client to respond with an $\overline{\text{ACK}}$. On the falling edge of the ninth clock, the host will sample the SDA pin to see if the address was recognized by a client. The status of the $\overline{\text{ACK}}$ bit is loaded into the ACKSTAT bit.

Following the falling edge of the ninth clock transmission of the address, the SSPxIF is set, the BF flag is cleared and the Baud Rate Generator is turned off until another write to the SSPxBUF takes place, holding SCL low and allowing SDA to float.

28.2.4.2.1 BF Status Flag

In Transmit mode, the Buffer Full Status (BF) bit is set when the CPU writes to SSPxBUF and is cleared when all eight bits are shifted out.

28.2.4.2.2 WCOL Status Flag

If the user writes the SSPxBUF when a transmit is already in progress (i.e., SSPSR is still shifting out a data byte), the Write Collision Detect (WCOL) bit is set and the contents of the buffer are unchanged (the write does not occur).

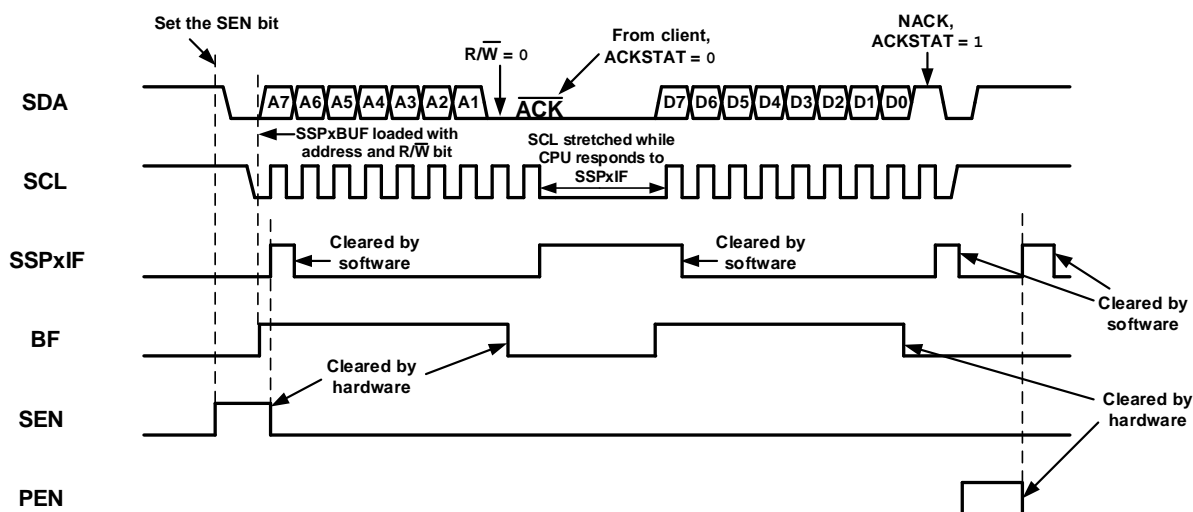
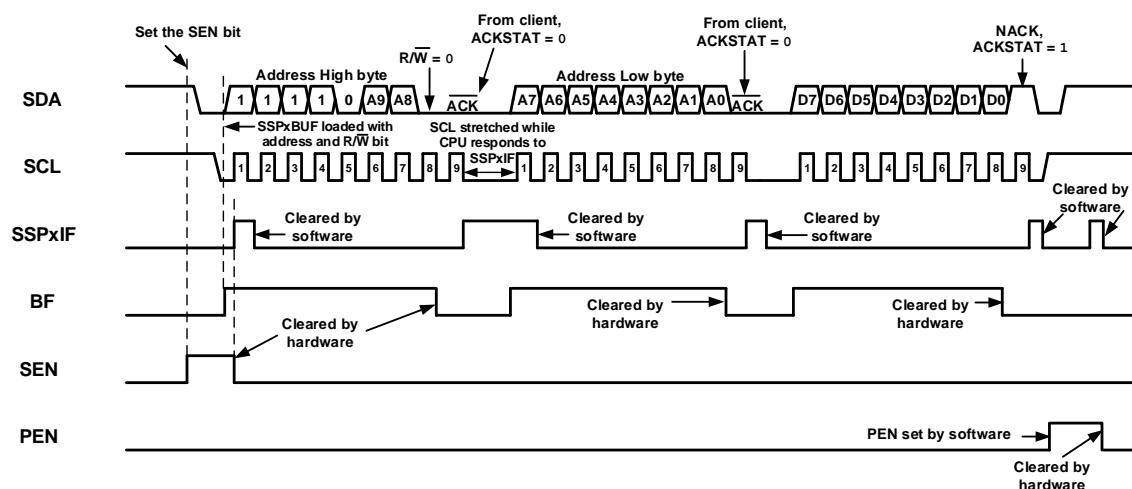
The WCOL bit must be cleared by software before the next transmission.

28.2.4.2.3 ACKSTAT Status Flag

In Transmit mode, the Acknowledge Status (ACKSTAT) bit is cleared when the client has sent an Acknowledge ($\overline{\text{ACK}} = 0$) and is set when the client issues a NACK. A client sends an $\overline{\text{ACK}}$ when it has recognized its address (including a General Call) or when the client has properly received its data.

28.2.4.2.4 Typical Transmit Sequence

1. The Host generates a Start condition by setting the SEN bit.
2. SSPxIF is set by hardware on completion of the Start.
3. SSPxIF is cleared by software.
4. The MSSP module will wait the required start time before any other operation takes place.
5. Software loads the SSPxBUF with the client address and the R/W bit. In Host Transmit mode, the R/W value is zero.
6. Address is shifted out the SDA pin until all eight bits are transmitted. Transmission begins as soon as SSPxBUF is written to.
7. The MSSP module shifts in the $\overline{\text{ACK}}$ value from the client device and writes its into the ACKSTAT bit.
8. The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPxIF bit.
9. Software loads the SSPxBUF with eight bits of data.
10. Data shift out the SDA pin until all eight bits are transmitted.
11. The MSSP module shifts in the $\overline{\text{ACK}}$ bit from the client device and writes its value into the ACKSTAT bit.
12. Steps 8-11 are repeated for all transmitted data bytes.
13. The user generates a Stop or Restart condition by setting the PEN or RSEN bits, respectively. An Interrupt is generated once the Stop/Restart condition is complete.

Figure 28-29. I²C Host Mode Waveform (Transmission, 7-Bit Address)Figure 28-30. I²C Host Mode Waveform (Transmission, 10-Bit Address)

28.2.4.3 I²C Host Mode Reception

Host mode reception (see Figure 28-31) is enabled by setting the Receive Enable (RCEN) bit.



Important: The MSSP module must be in an Idle state before the RCEN bit is set or the RCEN bit will be disregarded.

The Baud Rate Generator begins counting and on each rollover, the state of the SCL pin changes (high-to-low/low-to-high) and data are shifted into the SSPxSR. After the falling edge of the eighth clock all the following events occur:

- RCEN is automatically cleared by hardware.

- The contents of the SSPxSR are loaded into the SSPxBUF.
- The BF flag bit is set.
- The SSPxIF flag bit is set.
- The Baud Rate Generator is suspended from counting.
- The SCL pin is held low.

The MSSP is now in Idle state awaiting the next command. When the buffer is read by the CPU, the BF flag bit is automatically cleared. The Host can then send an Acknowledge sequence at the end of reception by setting the Acknowledge Sequence Enable (ACKEN) bit.

28.2.4.3.1 BF Status Flag

In receive operation, the BF bit is set when an address or data byte is loaded into SSPxBUF from SSPSR. It is cleared when the SSPxBUF register is read.

28.2.4.3.2 SSPOV Status Flag

In receive operation, the SSPOV bit is set when eight bits are received into SSPxSR while the BF flag bit is already set from a previous reception.

28.2.4.3.3 WCOL Status Flag

If the user writes the SSPxBUF when a receive is already in progress (i.e., SSPxSR is still shifting in a data byte), the WCOL bit is set and the contents of the buffer are unchanged (the write does not occur).

28.2.4.3.4 Typical Receive Sequence

1. The Host generates a Start condition by setting the **SEN** bit.
2. SSPxIF is set by hardware on completion of the Start.
3. SSPxIF is cleared by software.
4. Software writes **SSPxBUF** with the client address to transmit and the R/W bit set.
5. Address is shifted out the SDA pin until all eight bits are transmitted. Transmission begins as soon as SSPxBUF is written to.
6. The MSSP module shifts in the \overline{ACK} value from the client device and writes it into the **ACKSTAT** bit.
7. The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPxIF bit.
8. Software sets the **RCEN** bit and the host clocks in a byte from the client.
9. After the eighth falling edge of SCL, SSPxIF and **BF** are set.
10. Host clears SSPxIF and reads the received byte from SSPxBUF, which clears BF.
11. Host clears the **ACKDT** bit and initiates the \overline{ACK} sequence by setting the **ACKEN** bit.
12. Host's \overline{ACK} is clocked out to the client and SSPxIF is set.
13. User clears SSPxIF.
14. Steps 8-13 are repeated for each received byte from the client.
15. Host sends a NACK or Stop to end communication.

Figure 28-31. I²C Host Mode Waveform (Reception, 7-Bit Address)

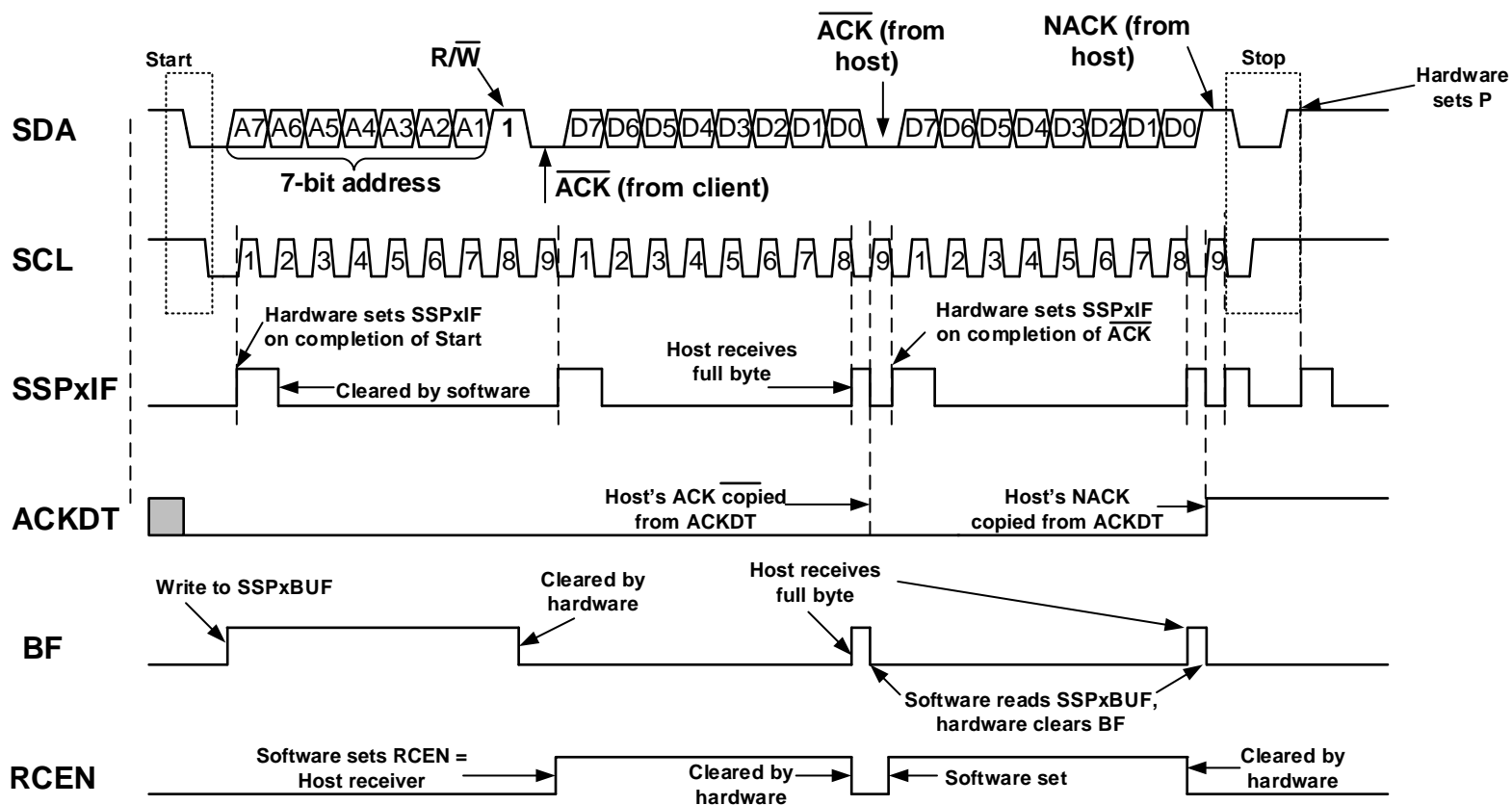
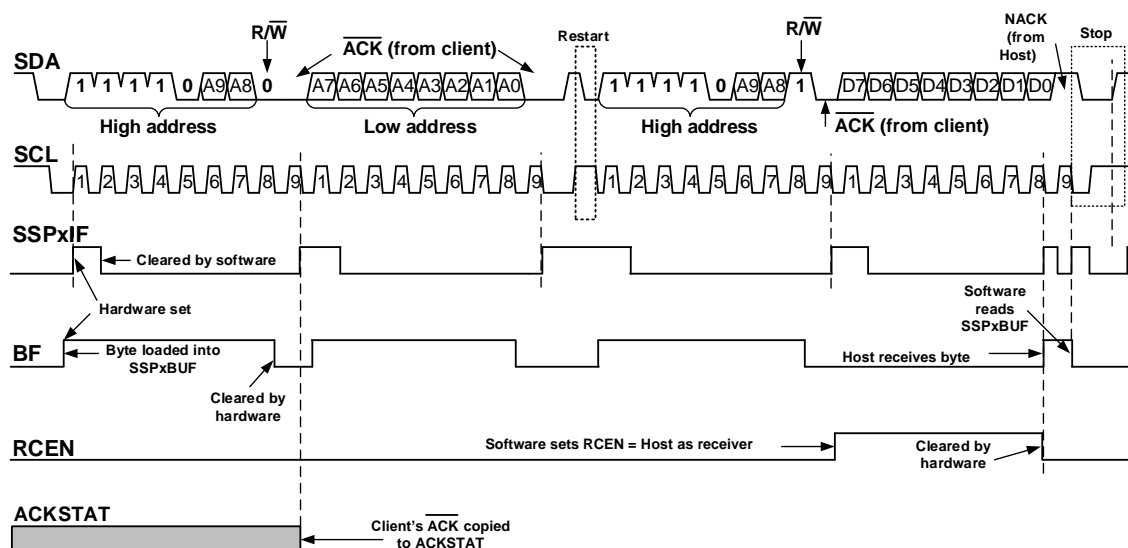


Figure 28-32. I²C Host Mode Waveform (Reception, 10-Bit Address)

28.2.5 Multi-Host Mode

In Multi-Host mode, the interrupt generation on the detection of the Start and Stop conditions allows the determination of when the bus is free. The Stop (P) and Start (S) bits are cleared from a Reset or when the MSSP module is disabled. Control of the I²C bus may be taken when the P bit is set or when the bus is Idle, with both the S and P bits cleared. When the bus is busy, enabling the MSSP interrupt will generate an interrupt when the Stop condition occurs.

In Multi-Host operation, the SDA line must be monitored for arbitration to see if the signal level is the expected output level. This check is performed by hardware with the result placed in the BCLxIF bit.

The states where arbitration can be lost are:

- Address Transfer
- Data Transfer
- A Start Condition
- A Repeated Start Condition
- An Acknowledge Condition

28.2.5.1 Multi-Host Communication, Bus Collision and Bus Arbitration

Multi-Host mode support is achieved by bus arbitration. When the host outputs address/data bits onto the SDA pin, arbitration takes place when the host outputs a '1' on SDA, by letting SDA float high and another host asserts a '0'. When the SCL pin floats high, data may be stable. If the expected data on SDA is a '1' and the data sampled on the SDA pin is '0', then a bus collision has taken place. The host will set the Bus Collision Interrupt Flag (BCLxIF) and reset the I²C port to its Idle state (see Figure 28-33).

If a transmit was in progress when the bus collision occurred, the transmission is halted, the BF flag is cleared, the SDA and SCL lines are deasserted, and the SSPxBUF can be written to. When software services the bus collision Interrupt Service Routine, and if the I²C bus is free, software can resume communication by asserting a Start condition.

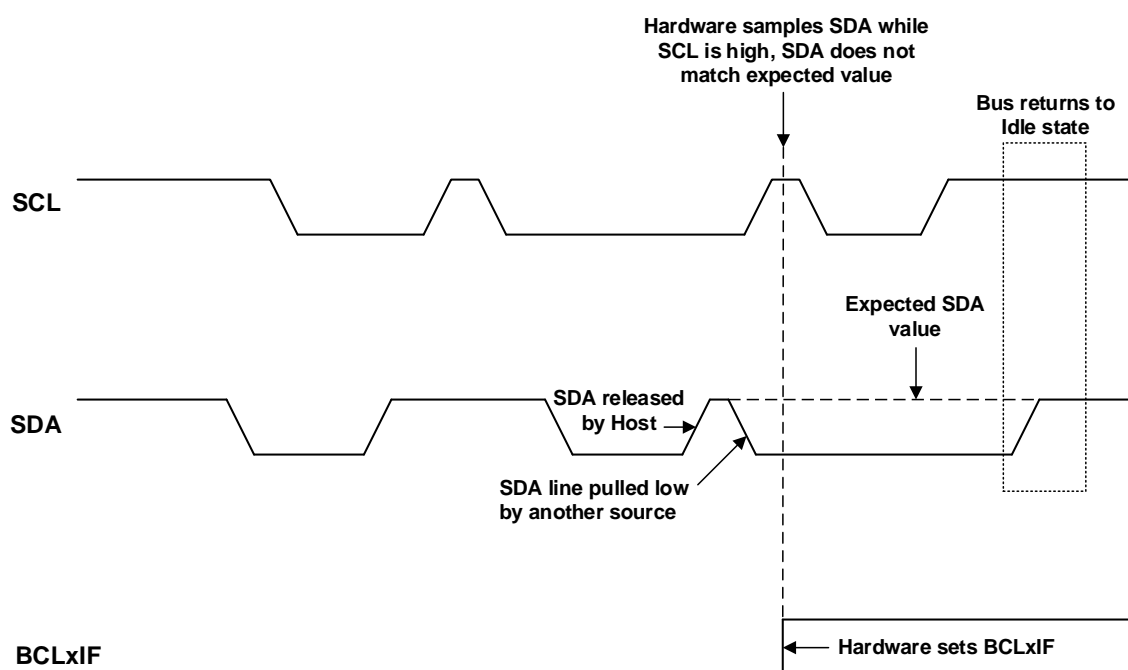
If a Start, Repeated Start, Stop or Acknowledge condition was in progress when the bus collision occurred, the condition is aborted, the SDA and SCL lines are deasserted, and the respective control bits in the [SSPxCON2](#) register are cleared. When software services the bus collision Interrupt Service Routine, and if the I²C bus is free, software can resume communication by asserting a Start condition.

The host will continue to monitor the SDA and SCL pins. If a Stop condition occurs, the SSPxIF bit will be set.

A write to the SSPxBUF will start the transmission of data at the first data bit, regardless of where the transmitter left off when the bus collision occurred.

In Multi-Host mode, the interrupt generation on the detection of Start and Stop conditions allows the determination of when the bus is free. Control of the I²C bus can be taken when the **P** bit is set or when the bus is Idle and the **S** and **P** bits are cleared.

Figure 28-33. Bus Collision Timing for Transmit and Acknowledge



28.2.5.1.1 Bus Collision During a Start Condition

During a Start condition, a bus collision occurs if:

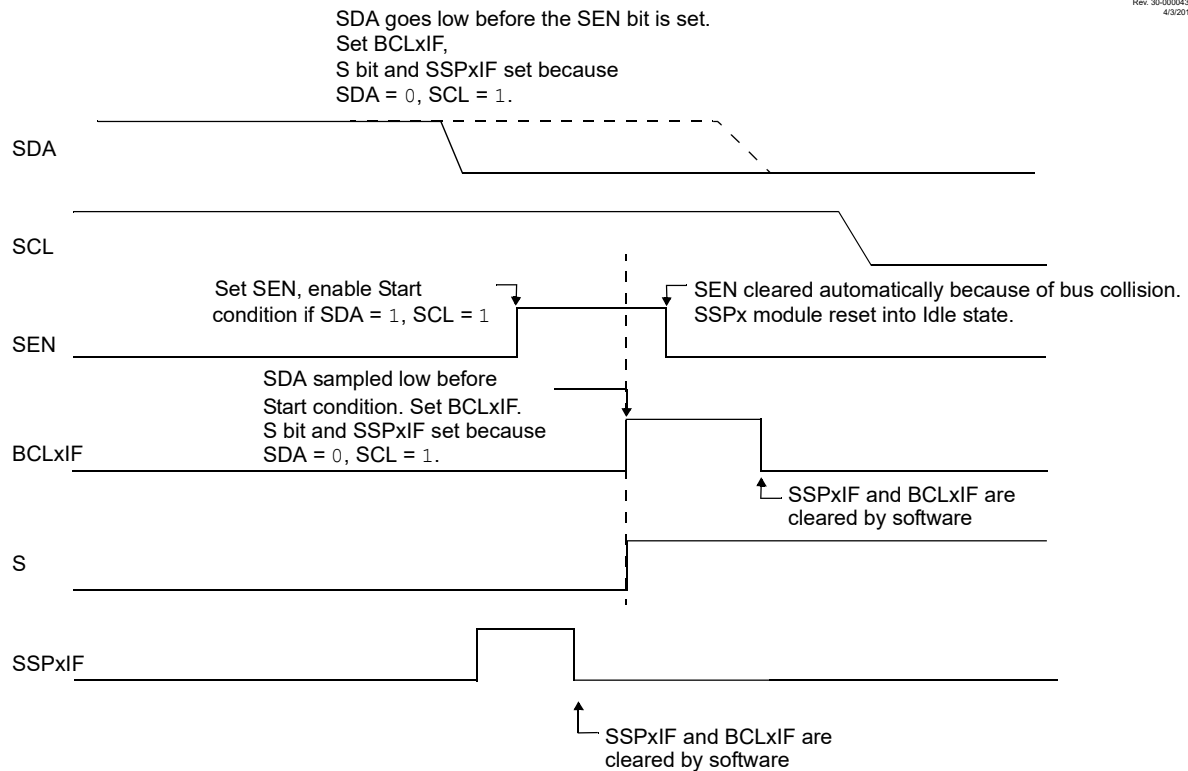
1. SDA or SCL are sampled low at the beginning of the Start condition (see [Figure 28-34](#)).
2. SCL is sampled low before SDA is asserted low (see [Figure 28-35](#)).

During a Start condition, both the SDA and the SCL pins are monitored.

If either the SDA pin or the SCL pin is already low, then all of the following occur:

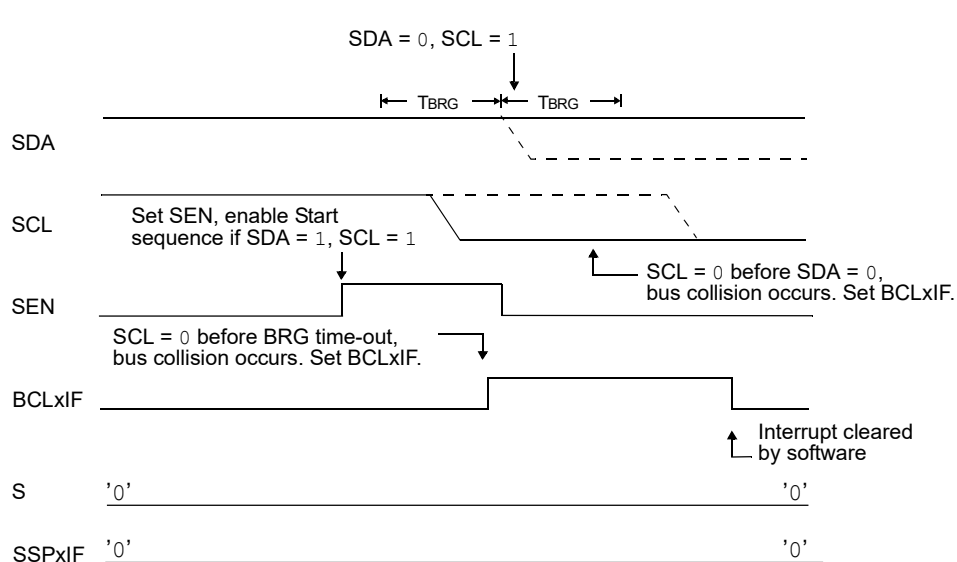
- the Start condition is aborted,
- the BCLxIF flag is set, and
- the MSSP module is reset to its Idle state (see [Figure 28-34](#)).

Figure 28-34. Bus Collision During Start Condition (SDA Only)



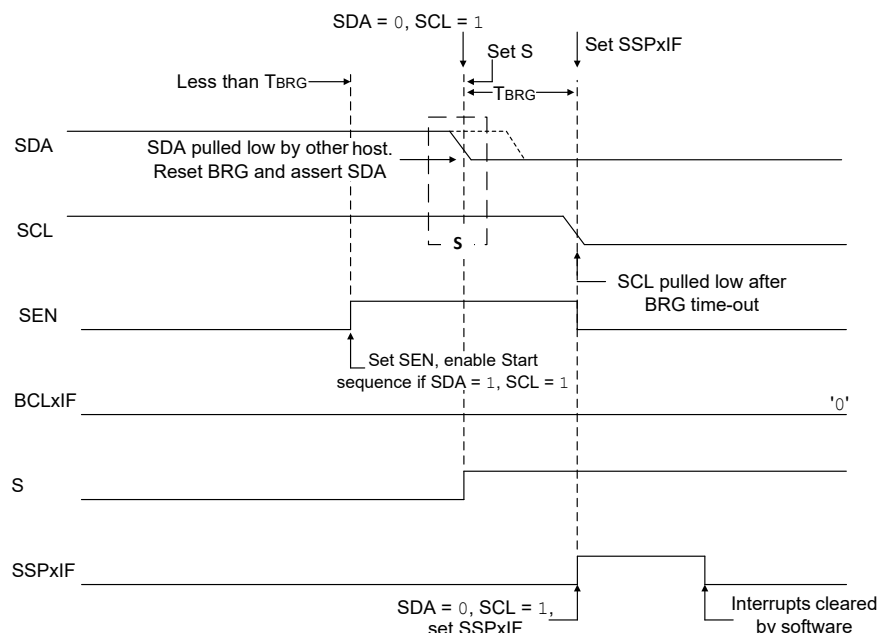
The Start condition begins with the SDA and SCL pins deasserted. When the SDA pin is sampled high, the Baud Rate Generator is loaded and counts down. If the SCL pin is sampled low while SDA is high, a bus collision occurs because it is assumed that another host is attempting to drive a data '1' during the Start condition.

Figure 28-35. Bus Collision During Start Condition (SCL = 0)



If the SDA pin is sampled low during this count, the BRG is reset and the SDA line is asserted early (see Figure 28-36). If, however, a '1' is sampled on the SDA pin, the SDA pin is asserted low at the end of the BRG count. The Baud Rate Generator is then reloaded and counts down to zero; if the SCL pin is sampled as '0' during this time, a bus collision does not occur. At the end of the BRG count, the SCL pin is asserted low.

Figure 28-36. BRG Reset Due to SDA Arbitration During Start Condition



Important: The reason that a bus collision is not a factor during a Start condition is that no two bus hosts can assert a Start condition at the exact same time. Therefore, one host will always assert SDA before the other. This condition does not cause a bus collision because the two hosts must be allowed to arbitrate the first address following the Start condition. If the address is the same, arbitration must be allowed to continue into the data portion, Repeated Start or Stop conditions.

28.2.5.1.2 Bus Collision During a Repeated Start Condition

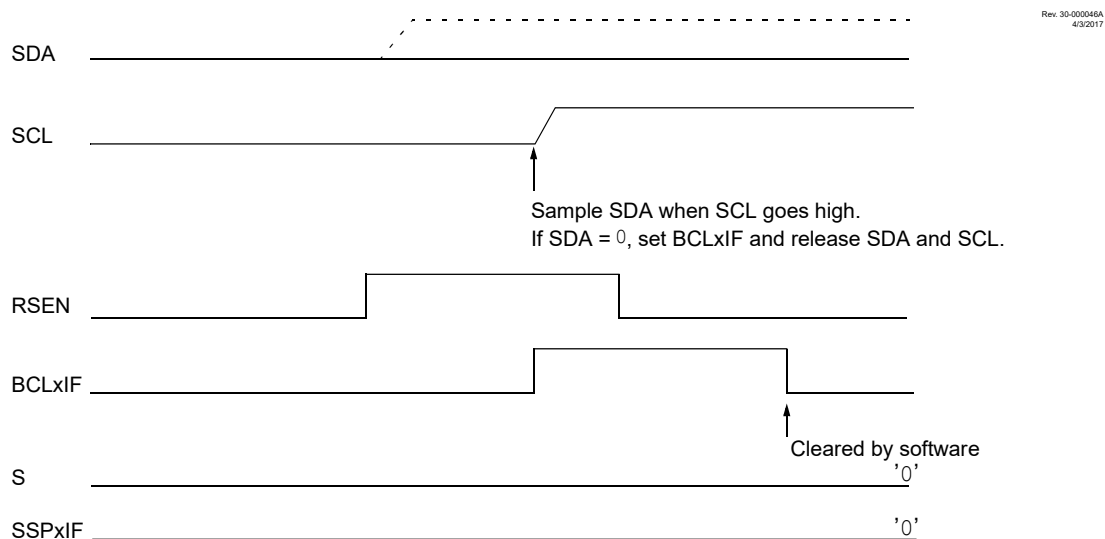
During a Repeated Start condition, a bus collision occurs if:

1. A low level is sampled on SDA when SCL goes from low level to high level (see Figure 28-37).
2. SCL goes low before SDA is asserted low, indicating that another host is attempting to transmit a data '1' (see Figure 28-38).

When the user releases SDA and the pin is allowed to float high, the BRG is loaded with `SSPxADD` and counts down to zero. The SCL pin is then deasserted and when sampled high, the SDA pin is sampled.

If SDA is low, a bus collision has occurred (i.e., another host is attempting to transmit a data '0', see [Figure 28-37](#)). If SDA is sampled high, the BRG is reloaded and begins counting. If SDA goes from high-to-low before the BRG times out, no bus collision occurs because no two hosts can assert SDA at exactly the same time.

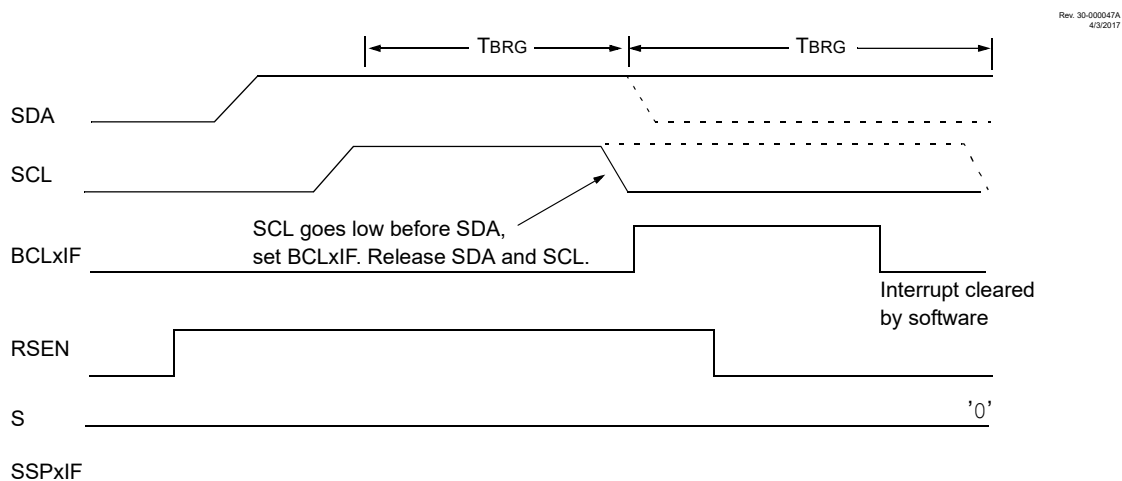
Figure 28-37. Bus Collision During a Repeated Start Condition (Case 1)



If SCL goes from high-to-low before the BRG times out and SDA has not already been asserted, a bus collision occurs. In this case, another host is attempting to transmit a data '1' during the Repeated Start condition (see [Figure 28-38](#)).

If, at the end of the BRG time-out, both SCL and SDA are still high, the SDA pin is driven low and the BRG is reloaded and begins counting. At the end of the count, regardless of the status of the SCL pin, the SCL pin is driven low and the Repeated Start condition is complete.

Figure 28-38. Bus Collision During Repeated Start Condition (Case 2)



28.2.5.1.3 Bus Collision During a Stop Condition

Bus collision occurs during a Stop condition if:

1. After the SDA pin has been deasserted and allowed to float high, SDA is sampled low after the BRG has timed out (see [Figure 28-39](#)).
2. After the SCL pin is deasserted, SCL is sampled low before SDA goes high (see [Figure 28-40](#)).

The Stop condition begins with SDA asserted low. When SDA is sampled low, the SCL pin is allowed to float. When the pin is sampled high (clock arbitration), the Baud Rate Generator is loaded with [SSPxADD](#) and counts down to zero. After the BRG times out, SDA is sampled. If SDA is sampled low, a bus collision has occurred. This is due to another host attempting to drive a data '0' (see [Figure 28-39](#)). If the SCL pin is sampled low before SDA is allowed to float high, a bus collision occurs. This is another case of another host attempting to drive a data '0' ([Figure 28-40](#)).

Figure 28-39. Bus Collision During a Stop Condition (Case 1)

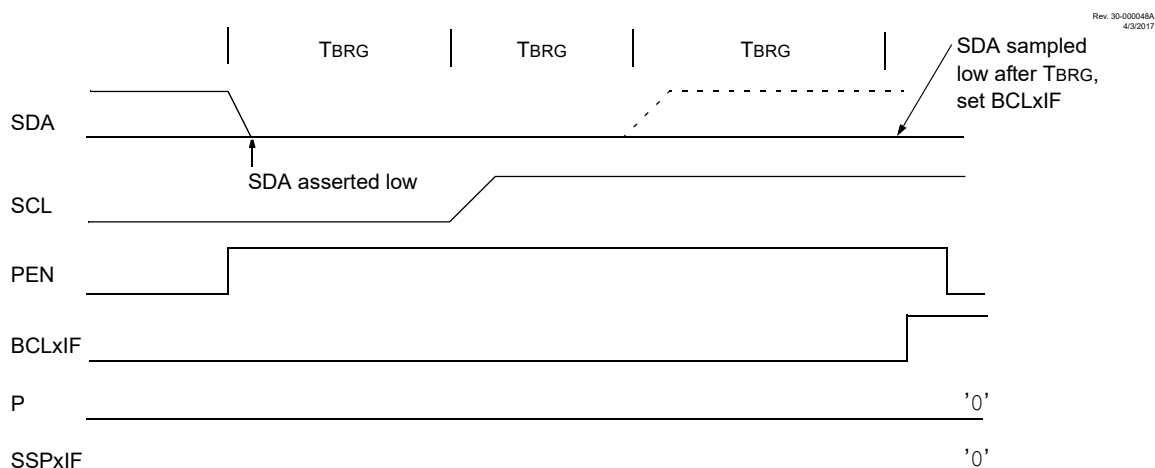


Figure 28-40. Bus Collision During a Stop Condition (Case 2)



28.3 Baud Rate Generator

The MSSP module has a Baud Rate Generator (BRG) available for clock generation in both I²C and SPI Host modes. The BRG reload value is placed in the [SSPxADD](#) register. When a write occurs to

SSPxBUF, the BRG will automatically begin counting down. [Example 28-1](#) shows how the value for SSPxADD is calculated.

Once the given operation is complete, the internal clock will automatically stop counting and the clock pin will remain in its last state.

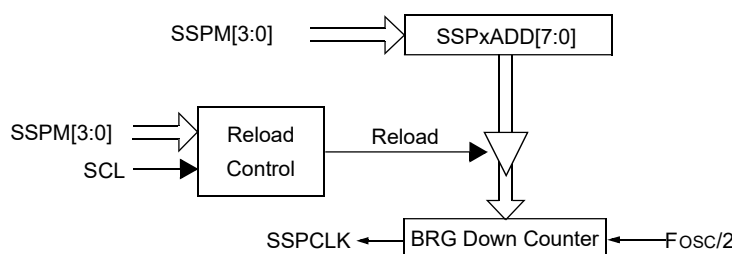
An internal Reload signal, shown in [Figure 28-41](#), triggers the value from SSPxADD to be loaded into the BRG counter. This occurs twice for each oscillation of the module clock line.

[Table 28-2](#) illustrates clock rates based on instruction cycles and the BRG value loaded into SSPxADD.

Example 28-1. MSSP Baud Rate Generator Frequency Equation

$$F_{CLOCK} = \frac{F_{OSC}}{4 \times (SSPxADD + 1)}$$

Figure 28-41. Baud Rate Generator Block Diagram



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Important: Values of 0x00, 0x01 and 0x02 are not valid for SSPxADD when used as a Baud Rate Generator for I²C. This is an implementation limitation.

Table 28-2. MSSP Clock Rate w/BRG

| F _{osc} | F _{CY} | BRG Value | F _{CLOCK} (2 Rollovers of BRG) |
|------------------|-----------------|-----------|--|
| 32 MHz | 8 MHz | 13h | 400 kHz |
| 32 MHz | 8 MHz | 19h | 308 kHz |
| 32 MHz | 8 MHz | 4Fh | 100 kHz |
| 16 MHz | 4 MHz | 09h | 400 kHz |
| 16 MHz | 4 MHz | 0Ch | 308 kHz |
| 16 MHz | 4 MHz | 27h | 100 kHz |
| 4 MHz | 1 MHz | 09h | 100 kHz |

Note: Refer to the I/O port electrical specifications in the “**Electrical Specifications**” chapter, Internal Oscillator Parameters, to ensure the system is designed to support all requirements.

28.4 Register Definitions: MSSP Control

28.4.1 SSPxBUF

Name: SSPxBUF
Address: 0xF91,0xE8D

MSSP Data Buffer Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----------|-----|-----|-----|-----|-----|-----|-----|
| | BUF[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 7:0 – BUF[7:0] MSSP Input and Output Data Buffer bits

28.4.2 SSPxADD

Name: SSPxADD
Address: 0xF92, 0xE8E

MSSP Baud Rate Divider and Address Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----------|-----|-----|-----|-----|-----|-----|-----|
| | ADD[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – ADD[7:0]

- SPI and I²C Host: Baud rate divider
- I²C Client: Address bits

| Value | Mode | Description |
|---------------------------|---|---|
| 11111111 – 00000011 | SPI and I ² C Host | Baud rate divider. SCK/SCL pin clock period = ((n + 1) * 4)/F _{OSC} . Values less than 3 are not valid in I ² C mode. |
| xxxxx11x– xxxxx00x | I ² C 10-bit Client MS Address | Bits [7:3] and Bit 0 are not used and are don't care. Bits [2:1] are bits [9:8] of the 10-bit Client Most Significant Address. |
| 11111111 – 00000000 | I ² C 10-bit Client LS Address | Bits [7:0] of 10-bit Client Least Significant Address |
| 1111111x – 0000000x | I ² C 7-bit Client | Bit 0 is not used and is don't care. Bits [7:1] are the 7-bit Client Address. |

28.4.3 SSPxMSK

Name: SSPxMSK
Address: 0xF93, 0xE8F

MSSP Address Mask Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----------|-----|-----|-----|-----|-----|-----|------|
| | MSK[6:0] | | | | | | | MSK0 |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Bits 7:1 – MSK[6:0] Mask bits

| Value | Mode | Description |
|-------|-------------------------|--|
| 1 | I ² C Client | The received address bit n is compared to SSPxADD bit n to detect I ² C address match |
| 0 | I ² C Client | The received address bit n is not used to detect I ² C address match |

Bit 0 – MSK0 Mask bit for I²C 10-bit Client mode

| Value | Mode | Description |
|-------|--------------------------------|--|
| x | SPI or I ² C 7-bit | This bit is not used |
| 1 | I ² C 10-bit Client | The received address bit 0 is compared to SSPxADD bit 0 to detect I ² C address match |
| 0 | I ² C 10-bit Client | The received address bit 0 is not used to detect I ² C address match |

28.4.4 SSPxSTAT

Name: SSPxSTAT
Address: 0xF94, 0xE90

MSSP Status Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|-------------------|---|---|-------------------|----|----|
| | SMP | CKE | D/ \overline{A} | P | S | R/ \overline{W} | UA | BF |
| Access | R/W | R/W | R | R | R | R | R | R |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – SMP Slew Rate Control bit

| Value | Mode | Description |
|-------|------------------|---|
| 1 | SPI Host | Input data are sampled at the end of data output time |
| 0 | SPI Host | Input data are sampled at the middle of data output time |
| 0 | SPI Client | Bit must be cleared in SPI Client mode |
| 1 | I ² C | Slew rate control is disabled for Standard Speed mode (100 kHz) |
| 0 | I ² C | Slew rate control is enabled for High Speed mode (400 kHz) |

Bit 6 – CKE SPI: Clock Select bit⁽⁴⁾; I²C: SMBus Select bit

| Value | Mode | Description |
|-------|------------------|---|
| 1 | SPI | Transmit occurs on the transition from Active to Idle clock state |
| 0 | SPI | Transmit occurs on the transition from Idle to Active clock state |
| 1 | I ² C | Enables SMBus-specific inputs |
| 0 | I ² C | Disables SMBus-specific inputs |

Bit 5 – D/ \overline{A} Data/Address bit

| Value | Mode | Description |
|-------|------------------------------|--|
| x | SPI or I ² C Host | This bit is not used |
| 1 | I ² C Client | Indicates that the last byte received or transmitted was data |
| 0 | I ² C Client | Indicates that the last byte received or transmitted was address |

Bit 4 – P Stop bit⁽¹⁾

| Value | Mode | Description |
|-------|------------------|--------------------------------|
| x | SPI | This bit is not used |
| 1 | I ² C | Stop bit was detected last |
| 0 | I ² C | Stop bit was not detected last |

Bit 3 – S Start bit⁽¹⁾

| Value | Mode | Description |
|-------|------------------|---------------------------------|
| x | SPI | This bit is not used |
| 1 | I ² C | Start bit was detected last |
| 0 | I ² C | Start bit was not detected last |

Bit 2 – R/ \overline{W} Read/Write Information bit^(2,3)

| Value | Mode | Description |
|-------|-------------------------|-----------------------------|
| x | SPI | This bit is not used |
| 1 | I ² C Client | Read |
| 0 | I ² C Client | Write |
| 1 | I ² C Host | Transmit is in progress |
| 0 | I ² C Host | Transmit is not in progress |

Bit 1 – UA Update Address bit (10-bit I²C Client mode only)

| Value | Mode | Description |
|-------|--------------------------------|---|
| x | All other modes | This bit is not used |
| 1 | I ² C 10-bit Client | Indicates that the user needs to update the address in the SSPxADD register |
| 0 | I ² C 10-bit Client | Address does not need to be updated |

Bit 0 – BF Buffer Full Status bit⁽⁵⁾

| Value | Mode | Description |
|-------|----------------------------------|--|
| 1 | I ² C Transmit | Transmit in progress, SSPxBUF is full |
| 0 | I ² C Transmit | Transmit complete; SSPxBUF is empty |
| 1 | SPI and I ² C Receive | Receive complete, SSPxBUF is full |
| 0 | SPI and I ² C Receive | Receive not complete, SSPxBUF is empty |

Notes:

1. This bit is cleared on Reset and when SSPEN is cleared.
2. In I²C Client mode, this bit holds the R/ \overline{W} bit information following the last address match. This bit is only valid from the address match to the next Start bit, Stop bit or not \overline{ACK} bit.
3. ORing this bit with SEN, RSEN, PEN, RCEN or ACKEN will indicate if the MSSP is in Active mode.
4. Polarity of clock state is set by the CKP bit.
5. I²C receive status does not include \overline{ACK} and Stop bits.

28.4.5 SSPxCON1

Name: SSPxCON1
Address: 0xF95, 0xE91

MSSP Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|-------|-----|-----------|-----|-----|-----|
| | WCOL | SSPOV | SSPEN | CKP | SSPM[3:0] | | | |
| Access | R/W/HS | R/W/HS | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – WCOL Write Collision Detect bit

| Value | Mode | Description |
|-------|---|--|
| x | Host or Client receive | This bit is not used |
| 1 | SPI or I ² C Host or Client transmit | The SSPxBUF register is written while it is still transmitting the previous word (must be cleared in software) |
| 0 | SPI or I ² C Host or Client transmit | No collision |

Bit 6 – SSPOV Receive Overflow Indicator bit⁽¹⁾

| Value | Mode | Description |
|-------|--|--|
| x | SPI Host or I ² C Host transmit | This bit is not used |
| 1 | SPI Client | A byte is received while the SSPxBUF register is still holding the previous byte. Data contained in the shift register will be discarded. The user must read SSPxBUF, even if only transmitting data, to avoid setting overflow (must be cleared in software). |
| 1 | I ² C Receive | A byte is received while the SSPxBUF register is still holding the previous byte (must be cleared in software) |
| 0 | SPI Client or I ² C Receive | No overflow |

Bit 5 – SSPEN Host Synchronous Serial Port Enable bit⁽²⁾

| Value | Description |
|-------|---|
| 1 | Enables the serial port |
| 0 | Disables serial port and configures these pins as I/O PORT pins |

Bit 4 – CKP SCK Release Control bit

| Value | Mode | Description |
|-------|-------------------------|---|
| x | I ² C Host | This bit is not used |
| 1 | SPI | Idle state for the clock is a high level |
| 0 | SPI | Idle state for the clock is a low level |
| 1 | I ² C Client | Releases clock |
| 0 | I ² C Client | Holds clock low (clock stretch), used to ensure data setup time |

Bits 3:0 – SSPM[3:0] Host Synchronous Serial Port Mode Select bits⁽⁴⁾

| Value | Description |
|-------|---|
| 1111 | I ² C Client mode: 10-bit address with Start and Stop bit interrupts enabled |
| 1110 | I ² C Client mode: 7-bit address with Start and Stop bit interrupts enabled |
| 1101 | Reserved - do not use |
| 1100 | Reserved - do not use |
| 1011 | I ² C Firmware Controlled Host mode (client Idle) |
| 1010 | SPI Host mode: Clock = $F_{OSC}/(4 * (SSPxADD + 1))$ |
| 1001 | Reserved - do not use |
| 1000 | I ² C Host mode: Clock = $F_{OSC}/(4 * (SSPxADD + 1))$ ⁽³⁾ |

| Value | Description |
|-------|---|
| 0111 | I ² C Client mode: 10-bit address |
| 0110 | I ² C Client mode: 7-bit address |
| 0101 | SPI Client mode: Clock = SCKx pin. \overline{SSx} pin control is disabled |
| 0100 | SPI Client mode: Clock = SCKx pin. \overline{SSx} pin control is enabled |
| 0011 | SPI Host mode: Clock = TMR2 output/2 |
| 0010 | SPI Host mode: Clock = $F_{OSC}/64$ |
| 0001 | SPI Host mode: Clock = $F_{OSC}/16$ |
| 0000 | SPI Host mode: Clock = $F_{OSC}/4$ |

Notes:

1. In Host mode, the overflow bit is not set since each new reception (and transmission) is initiated by writing to the SSPxBUF register.
2. When enabled, these pins must be properly configured as inputs or outputs.
3. SSPxADD values of 0, 1, and 2 are not supported in I²C mode.
4. Bit combinations not specifically listed here are either reserved or implemented in I²C mode only.

28.4.6 SSPxCON2

Name: SSPxCON2
Address: 0xF96, 0xE92

MSSP Control Register 2

Control Register for I²C Operation Only

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|----------|-------|-------|------|-----|------|-----|
| | GCEN | ACKSTAT | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN |
| Access | R/W | R//HC/HS | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – GCEN General Call Enable bit (Client mode only)

| Value | Mode | Description |
|-------|-------------|-----------------------------|
| x | Host mode | Don't care |
| 1 | Client mode | General Call is enabled |
| 0 | Client mode | General Call is not enabled |

Bit 6 – ACKSTAT Acknowledge Status bit (Host Transmit mode only)

| Value | Description |
|-------|--|
| 1 | Acknowledge was not received from client |
| 0 | Acknowledge was received from client |

Bit 5 – ACKDT Acknowledge Data bit (Host Receive mode only)⁽¹⁾

| Value | Description |
|-------|-----------------|
| 1 | Not Acknowledge |
| 0 | Acknowledge |

Bit 4 – ACKEN Acknowledge Sequence Enable bit⁽²⁾

| Value | Description |
|-------|--|
| 1 | Initiates Acknowledge sequence on SDAx and SCLx pins and transmits ACKDT data bit; automatically cleared by hardware |
| 0 | Acknowledge sequence is Idle |

Bit 3 – RCEN Receive Enable bit (Host Receive mode only)⁽²⁾

| Value | Description |
|-------|---|
| 1 | Enables Receive mode for I ² C |
| 0 | Receive is Idle |

Bit 2 – PEN Stop Condition Enable bit (Host mode only)⁽²⁾

| Value | Description |
|-------|---|
| 1 | Initiates Stop condition on SDAx and SCLx pins; automatically cleared by hardware |
| 0 | Stop condition is Idle |

Bit 1 – RSEN Repeated Start Condition Enable bit (Host mode only)⁽²⁾

| Value | Description |
|-------|---|
| 1 | Initiates Repeated Start condition on SDAx and SCLx pins; automatically cleared by hardware |
| 0 | Repeated Start condition is Idle |

Bit 0 – SEN Start Condition Enable bit⁽²⁾

| Value | Mode | Description |
|-------|--------|--|
| 1 | Host | Initiates Start condition on SDAx and SCLx pins; automatically cleared by hardware |
| 0 | Host | Start condition is Idle |
| 1 | Client | Clock stretching is enabled |
| 0 | Client | Clock stretching is disabled |

Notes:

1. The value that will be transmitted when the user initiates an Acknowledge sequence at the end of a receive.
2. If the I²C module is active, these bits may not be set (no spooling) and the SSPxBUF may not be written (or writes to the SSPxBUF are disabled).

28.4.7 SSPxCON3

Name: SSPxCON3
Address: 0xF97,0xE93

MSSP Control Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---------|------|------|------|-------|-------|------|------|
| | ACKTIM | PCIE | SCIE | BOEN | SDAHT | SBCDE | AHEN | DHEN |
| Access | R/HS/HC | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – ACKTIM Acknowledge Time Status bit

| Value | Mode | Description |
|-------|--|---|
| x | SPI or I ² C Host | This bit is not used |
| 1 | I ² C Client and AHEN = 1 or DHEN = 1 | Eighth falling edge of SCL has occurred and the $\overline{\text{ACK}}$ /NACK state is Active |
| 0 | I ² C Client | $\overline{\text{ACK}}$ /NACK state is not Active. Transitions low on ninth rising edge of SCL. |

Bit 6 – PCIE Stop Condition Interrupt Enable bit

| Value | Mode | Description |
|-------|---------------------------------------|---|
| x | SPI or SSPM = 1111 or 1110 | This bit is not used |
| 1 | SSPM \neq 1111 and SSPM \neq 1110 | Enable interrupt on detection of Stop condition |
| 0 | SSPM \neq 1111 and SSPM \neq 1110 | Stop detection interrupts are disabled |

Bit 5 – SCIE Start Condition Interrupt Enable bit

| Value | Mode | Description |
|-------|---------------------------------------|--|
| x | SPI or SSPM = 1111 or 1110 | This bit is not used |
| 1 | SSPM \neq 1111 and SSPM \neq 1110 | Enable interrupt on detection of Start condition |
| 0 | SSPM \neq 1111 and SSPM \neq 1110 | Start detection interrupts are disabled |

Bit 4 – BOEN Buffer Overwrite Enable bit⁽¹⁾

| Value | Mode | Description |
|-------|------------------|--|
| 1 | SPI | SSPxBUF is updated every time a new data byte is available, ignoring the BF bit |
| 0 | SPI | If a new byte is receive with BF set then SSPOV is set and SSPxBUF is not updated |
| 1 | I ² C | SSPxBUF is updated every time a new data byte is available, ignoring the SSPOV effect on updating the buffer |
| 0 | I ² C | SSPxBUF is only updated when SSPOV is clear |

Bit 3 – SDAHT SDA Hold Time Selection bit

| Value | Mode | Description |
|-------|------------------|--|
| x | SPI | Not used in SPI mode |
| 1 | I ² C | Minimum of 300 ns hold time on SDA after the falling edge of SCL |
| 0 | I ² C | Minimum of 100 ns hold time on SDA after the falling edge of SCL |

Bit 2 – SBCDE Client Mode Bus Collision Detect Enable bit Unused in Host mode.

| Value | Mode | Description |
|-------|------------------------------|--|
| x | SPI or I ² C Host | This bit is not used |
| 1 | I ² C Client | Bus Collision detection is enabled |
| 0 | I ² C Client | Bus Collision detection is not enabled |

Bit 1 – AHEN Address Hold Enable bit

| Value | Mode | Description |
|-------|------------------------------|---|
| x | SPI or I ² C Host | This bit is not used |
| 1 | I ² C Client | Address hold is enabled. As a result, CKP is cleared after the eighth falling SCL edge of an address byte reception. Software must set the CKP bit to resume operation. |
| 0 | I ² C Client | Address hold is not enabled |

Bit 0 – DHEN Data Hold Enable bit

| Value | Mode | Description |
|-------|------------------------------|--|
| x | SPI or I ² C Host | This bit is not used |
| 1 | I ² C Client | Data hold is enabled. As a result, CKP is cleared after the eighth falling SCL edge of a data byte reception. Software must set the CKP bit to resume operation. |
| 0 | I ² C Client | Data hold is not enabled |

Note:

1. For daisy-chained SPI operation; allows the user to ignore all except the last received byte. SSPOV is still set when a new byte is received and BF = 1, but hardware continues to write the most recent byte to SSPxBUF.

28.5 Register Summary - MSSP Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|----------|---------|-------|-------|-----------|-------|------|------|
| 0x00 ... 0x0E8C | Reserved | | | | | | | | | |
| 0x0E8D | SSP2BUF | 7:0 | BUF[7:0] | | | | | | | |
| 0x0E8E | SSP2ADD | 7:0 | ADD[7:0] | | | | | | | |
| 0x0E8F | SSP2MSK | 7:0 | MSK[6:0] | | | | | | | MSK0 |
| 0x0E90 | SSP2STAT | 7:0 | SMP | CKE | D/Ā | P | S | R/W | UA | BF |
| 0x0E91 | SSP2CON1 | 7:0 | WCOL | SSPOV | SSPEN | CKP | SSPM[3:0] | | | |
| 0x0E92 | SSP2CON2 | 7:0 | GCEN | ACKSTAT | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN |
| 0x0E93 | SSP2CON3 | 7:0 | ACKTIM | PCIE | SCIE | BOEN | SDAHT | SBCDE | AHEN | DHEN |
| 0x0E94 ... 0x0F90 | Reserved | | | | | | | | | |
| 0x0F91 | SSP1BUF | 7:0 | BUF[7:0] | | | | | | | |
| 0x0F92 | SSP1ADD | 7:0 | ADD[7:0] | | | | | | | |
| 0x0F93 | SSP1MSK | 7:0 | MSK[6:0] | | | | | | | MSK0 |
| 0x0F94 | SSP1STAT | 7:0 | SMP | CKE | D/Ā | P | S | R/W | UA | BF |
| 0x0F95 | SSP1CON1 | 7:0 | WCOL | SSPOV | SSPEN | CKP | SSPM[3:0] | | | |
| 0x0F96 | SSP1CON2 | 7:0 | GCEN | ACKSTAT | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN |
| 0x0F97 | SSP1CON3 | 7:0 | ACKTIM | PCIE | SCIE | BOEN | SDAHT | SBCDE | AHEN | DHEN |

29. EUSART - Enhanced Universal Synchronous Asynchronous Receiver Transmitter

The Enhanced Universal Synchronous Asynchronous Receiver Transmitter (EUSART) module is a serial I/O communications peripheral. It contains all the clock generators, shift registers and data buffers necessary to perform an input or output serial data transfer independent of device program execution. The EUSART, also known as a Serial Communications Interface (SCI), can be configured as a full-duplex asynchronous system or half-duplex synchronous system.

Full Duplex mode is useful for communications with peripheral systems, such as CRT terminals and personal computers. Half Duplex Synchronous mode is intended for communications with peripheral devices, such as A/D or D/A integrated circuits, serial EEPROMs or other microcontrollers. These devices typically do not have internal clocks for baud rate generation and require the external clock signal provided by a host synchronous device.

The EUSART module includes the following capabilities:

- Full-duplex asynchronous transmit and receive
- Two-character input buffer
- One-character output buffer
- Programmable 8-bit or 9-bit character length
- Address detection in 9-bit mode
- Input buffer overrun error detection
- Received character framing error detection
- Half-duplex synchronous host
- Half-duplex synchronous client
- Programmable clock polarity in Synchronous modes
- Sleep operation

The EUSART module implements the following additional features, making it ideally suited for use in Local Interconnect Network (LIN) bus systems:

- Automatic detection and calibration of the baud rate
- Wake-up on Break reception
- 13-bit Break character transmit

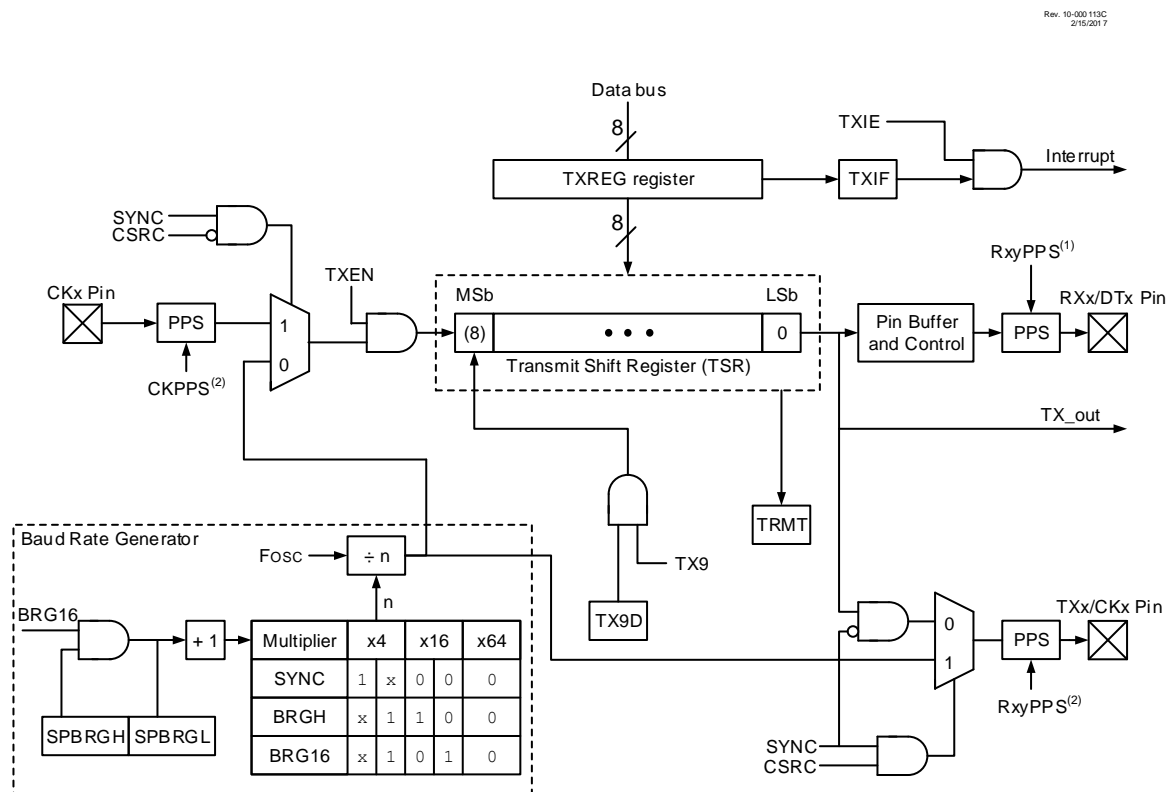
Block diagrams of the EUSART transmitter and receiver are shown in [Figure 29-1](#) and [Figure 29-2](#).

The operation of the EUSART module consists of six registers:

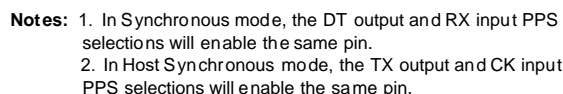
- Transmit Status and Control ([TXxSTA](#))
- Receive Status and Control ([RCxSTA](#))
- Baud Rate Control ([BAUDxCON](#))
- Baud Rate Value ([SPxBRG](#))
- Receive Data Register ([RCxREG](#))
- Transmit Data Register ([TXxREG](#))

The RXx/DTx and TXx/CKx input pins are selected with the RXxPPS and TXxPPS registers, respectively. TXx, CKx, and DTx output pins are selected with each pin's RxyPPS register. Since the RX input is coupled with the DT output in Synchronous mode, it is the user's responsibility to select the same pin for both of these functions when operating in Synchronous mode. The EUSART control logic will control the data direction drivers automatically.

Figure 29-1. EUSART Transmit Block Diagram



- Notes:**
1. In Synchronous mode, the DT output and RX input PPS selections will enable the same pin.
 2. In Host Synchronous mode, the TX output and CK input PPS selections will enable the same pin.

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- The EUSART Mode Select ([SYNC](#)) bit is set to '0' to configure the EUSART for asynchronous operation
- The Serial Port Enable ([SPEN](#)) bit is set to '1' to enable the EUSART interface and to enable automatically the output drivers for the RxyPPS selected as the TXx/CKx output

All other EUSART control bits are assumed to be in their default state.

If the TXx/CKx pin is shared with an analog peripheral, the analog I/O function must be disabled by clearing the corresponding ANSEL bit.



Important: The TXxIF Transmitter Interrupt Flag in the PIRx register is set when the TXEN enable bit is set and the Transmit Shift Register (TSR) is Idle.

29.1.1.2 Transmitting Data

A transmission is initiated by writing a character to the [TXxREG](#) register. If this is the first character, or the previous character has been completely flushed from the TSR, the data in the TXxREG is immediately transferred to the TSR register. If the TSR still contains all or part of a previous character, the new character data are held in the TXxREG until the Stop bit of the previous character has been transmitted. The pending character in the TXxREG is then transferred to the TSR in one T_{CY} immediately following the Stop bit transmission. The transmission of the Start bit, data bits and Stop bit sequence commences immediately following the transfer of the data to the TSR from the TXxREG.

29.1.1.3 Transmit Data Polarity

The polarity of the transmit data can be controlled with the Clock/Transmit Polarity Select ([SCKP](#)) bit. The default state of this bit is '0', which selects high true transmit Idle and data bits. Setting the SCKP bit to '1' will invert the transmit data resulting in low true Idle and data bits. The SCKP bit controls transmit data polarity in Asynchronous mode only. In Synchronous mode, the SCKP bit has a different function. See [Clock Polarity](#) for more details.

29.1.1.4 Transmit Interrupt Flag

The EUSART Transmit Interrupt Flag (TXxIF) bit of the PIRx register is set whenever the EUSART transmitter is enabled and no character is being held for transmission in the [TXxREG](#). In other words, the TXxIF bit is only cleared when the TSR is busy with a character and a new character has been queued for transmission in the TXxREG. The TXxIF flag bit is not cleared immediately upon writing TXxREG. TXxIF becomes valid in the second instruction cycle following the write execution. Polling TXxIF immediately following the TXxREG write will return invalid results. The TXxIF bit is read-only, it cannot be set or cleared by software.

The TXxIF interrupt can be enabled by setting the EUSART Transmit Interrupt Enable (TXxIE) bit of the PIRx register. However, the TXxIF flag bit will be set whenever the TXxREG is empty, regardless of the state of TXxIE enable bit.

To use interrupts when transmitting data, set the TXxIE bit only when there is more data to send. Clear the TXxIE interrupt enable bit upon writing the last character of the transmission to the TXxREG.

29.1.1.5 TSR Status

The Transmit Shift Register Status ([TRMT](#)) bit indicates the status of the TSR register. This is a read-only bit. The TRMT bit is set when the TSR register is empty and is cleared when a character is transferred to the TSR register from the [TXxREG](#). The TRMT bit remains clear until all bits have been shifted out of the TSR register. No interrupt logic is tied to this bit, so the user needs to poll this bit to determine the TSR status.



Important: The TSR register is not mapped in data memory, so it is not available to the user.

29.1.1.6 Transmitting 9-Bit Characters

The EUSART supports 9-bit character transmissions. When the 9-Bit Transmit Enable (**TX9**) bit is set, the EUSART will shift nine bits out for each character transmitted. The **TX9D** bit is the ninth and Most Significant data bit. When transmitting 9-bit data, the **TX9D** data bit must be written before writing the eight Least Significant bits into the **TXxREG**. All nine bits of data will be transferred to the TSR register immediately after the **TXxREG** is written.

A special 9-bit Address mode is available for use with multiple receivers. See [Address Detection](#) for more information on the Address mode.

29.1.1.7 Asynchronous Transmission Setup

1. Initialize the **SPxBRGH:SPxBRGL** register pair and the **BRGH** and **BRG16** bits to achieve the desired baud rate (see [EUSART Baud Rate Generator \(BRG\)](#)).
2. Select the transmit output pin by writing the appropriate value to the **RxyPPS** register.
3. Enable the asynchronous serial port by clearing the **SYNC** bit and setting the **SPEN** bit.
4. If 9-bit transmission is desired, set the **TX9** control bit. That will indicate that the eight Least Significant data bits are an address when the receiver is set for address detection.
5. Set **SCKP** bit if inverted transmit is desired.
6. Enable the transmission by setting the **TXEN** control bit. This will cause the **TXxIF** interrupt bit to be set.
7. If interrupts are desired, set the **TXxIE** interrupt enable bit of the **PIEx** register.
8. An interrupt will occur immediately provided that the **GIE** and **PEIE** bits of the **INTCON** register are also set.
9. If 9-bit transmission is selected, the ninth bit will be loaded into the **TX9D** data bit.
10. Load 8-bit data into the **TXxREG** register. This will start the transmission.

Figure 29-3. Asynchronous Transmission

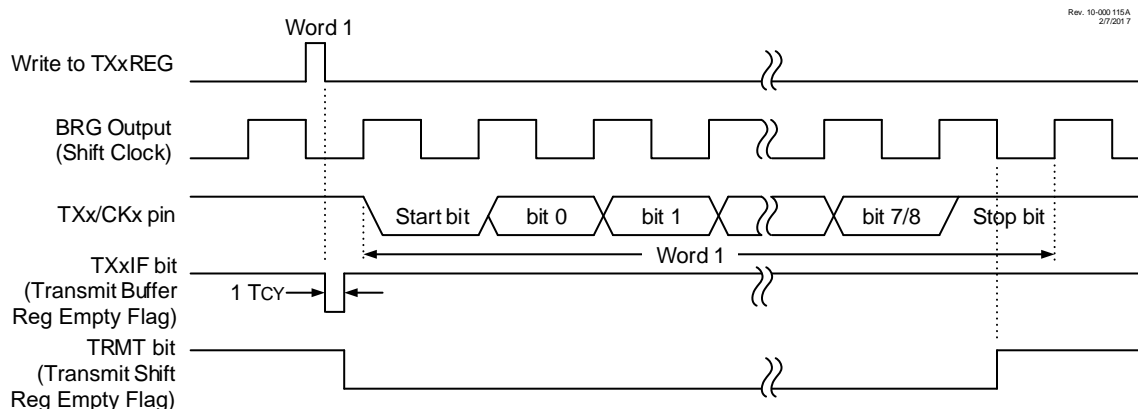
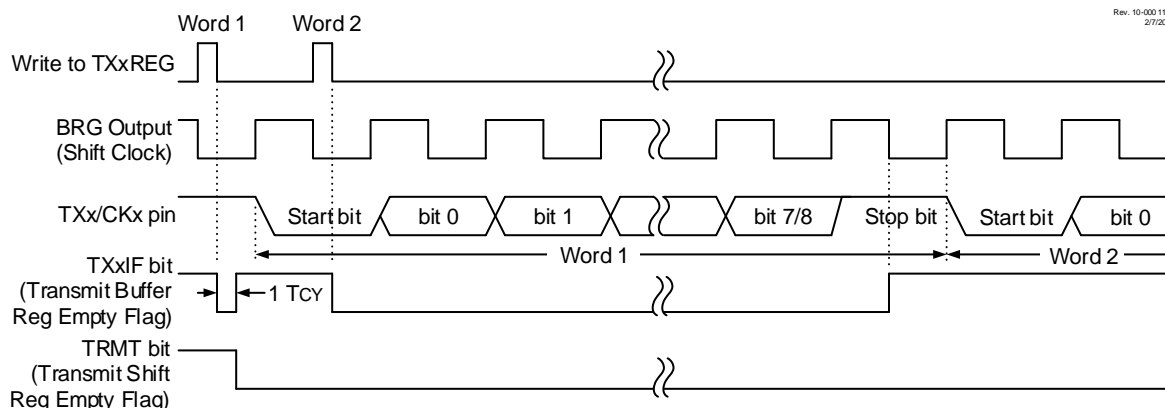


Figure 29-4. Asynchronous Transmission (Back-to-Back)

29.1.2 EUSART Asynchronous Receiver

The Asynchronous mode is typically used in RS-232 systems. A simplified representation of the receiver is shown in Figure 29-2. The data are received on the RXx/DTx pin and drive the data recovery block. The data recovery block is actually a high-speed shifter operating at 16 times the baud rate, whereas the serial Receive Shift Register (RSR) operates at the bit rate. When all eight or nine bits of the character have been shifted in, they are immediately transferred to a two character First-In-First-Out (FIFO) memory. The FIFO buffering allows reception of two complete characters and the start of a third character before software must start servicing the EUSART receiver. The FIFO and RSR registers are not directly accessible by software. Access to the received data is via the RCxREG register.

29.1.2.1 Enabling the Receiver

The EUSART receiver is enabled for asynchronous operation by configuring the following three control bits:

- The Continuous Receive Enable (CREN) bit is set to '1' to enables the receiver circuitry of the EUSART
- The EUSART Mode Select (SYNC) bit is set to '0' to configure the EUSART for asynchronous operation
- The Serial Port Enable (SPEN) bit is set to '1' to enable the EUSART interface

All other EUSART control bits are assumed to be in their default state.

The user must set the RXxPPS register to select the RXx/DTx I/O pin and set the corresponding TRIS bit to configure the pin as an input.



Important: If the RX/DT function is on an analog pin, the corresponding ANSEL bit must be cleared for the receiver to function.

29.1.2.2 Receiving Data

The receiver data recovery circuit initiates character reception on the falling edge of the first bit. The first bit, also known as the Start bit, is always a zero. The data recovery circuit counts one-half bit time to the center of the Start bit and verifies that the bit is still a zero. If it is not a zero, then the data recovery circuit aborts character reception without generating an error and resumes looking for the falling edge of the Start bit. If the Start bit zero verification succeeds, then the data recovery circuit counts a full bit time to the center of the next bit. The bit is then sampled by a majority detect circuit and the resulting '0' or '1' is shifted into the RSR. This repeats until all data bits have been sampled and shifted into the RSR. One final bit time is measured and the level sampled. This is the

Stop bit, which is always a '1'. If the data recovery circuit samples a '0' in the Stop bit position, then a framing error is set for this character, otherwise the framing error is cleared for this character. See [Receive Framing Error](#) for more information on framing errors.

Immediately after all data bits and the Stop bit have been received, the character in the RSR is transferred to the EUSART receive FIFO, and the EUSART Receive Interrupt Flag (RCxIF) bit of the PIRx register is set. The top character in the FIFO is transferred out of the FIFO by reading the [RCxREG](#) register.



Important: If the receive FIFO is overrun, no additional characters will be received until the Overrun condition is cleared. See [Receive Framing Error](#) for more information.

29.1.2.3 Receive Interrupts

The EUSART Receive Interrupt Flag (RCxIF) bit of the PIRx register is set whenever the EUSART receiver is enabled and there is an unread character in the receive FIFO. The RCxIF Interrupt Flag bit is read-only, it cannot be set or cleared by software.

RCxIF interrupts are enabled by setting all of the following bits:

- RCxIE, Interrupt Enable bit of the PIRx register
- PEIE, Peripheral Interrupt Enable bit of the INTCON register
- GIE, Global Interrupt Enable bit of the INTCON register

The RCxIF Interrupt Flag bit will be set when there is an unread character in the FIFO, regardless of the state of interrupt enable bits.

29.1.2.4 Receive Framing Error

Each character in the receive FIFO buffer has a corresponding framing error Status bit. A framing error indicates that a Stop bit was not seen at the expected time. The framing error status is accessed via the Framing Error ([FERR](#)) bit. The FERR bit represents the status of the top unread character in the receive FIFO. Therefore, the FERR bit must be read before reading the [RCxREG](#) register.

The FERR bit is read-only and only applies to the top unread character in the receive FIFO. A framing error (FERR = 1) does not preclude reception of additional characters. It is not necessary to clear the FERR bit. Reading the next character from the FIFO buffer will advance the FIFO to the next character and the next corresponding framing error.

The FERR bit can be forced clear by clearing the [SPEN](#) bit, which resets the EUSART. Clearing the [CREN](#) bit does not affect the FERR bit. A framing error by itself does not generate an interrupt.



Important: If all receive characters in the receive FIFO have framing errors, repeated reads of the RCxREG register will not clear the FERR bit.

29.1.2.5 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before the FIFO is accessed. When this happens the Overrun Error ([OERR](#)) bit is set. The characters already in the FIFO buffer can be read but no additional characters will be received until the error is cleared. The error must be cleared by either clearing the [CREN](#) bit or by resetting the EUSART by clearing the [SPEN](#) bit.

29.1.2.6 Receiving 9-Bit Characters

The EUSART supports 9-bit character reception. When the 9-Bit Receive Enable ([RX9](#)) bit is set, the EUSART will shift nine bits into the RSR for each character received. The [RX9D](#) bit is the ninth

and Most Significant data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the eight Least Significant bits from the [RCxREG](#) register.

29.1.2.7 Address Detection

A special Address Detection mode is available for use when multiple receivers share the same transmission line, such as in RS-485 systems. Address detection is enabled by setting the Address Detect Enable ([ADDEN](#)) bit.

Address detection requires 9-bit character reception. When address detection is enabled, only characters with the ninth data bit set will be transferred to the receive FIFO buffer, thereby setting the RCxIF interrupt bit. All other characters will be ignored.

Upon receiving an address character, user software determines if the address matches its own. Upon address match, user software must disable address detection by clearing the ADDEN bit before the next Stop bit occurs. When user software detects the end of the message, determined by the message protocol used, software places the receiver back into the Address Detection mode by setting the ADDEN bit.

29.1.2.8 Asynchronous Reception Setup

1. Initialize the [SPxBRGH:SPxBRGL](#) register pair and the [BRGH](#) and [BRG16](#) bits to achieve the desired baud rate (see [EUSART Baud Rate Generator \(BRG\)](#)).
2. Set the RXxPPS register to select the RXx/DTx input pin.
3. Clear the ANSEL bit for the RXx pin (if applicable).
4. Enable the serial port by setting the [SPEN](#) bit. The [SYNC](#) bit must be cleared for asynchronous operation.
5. If interrupts are desired, set the RCxIE bit of the PEx register and the GIE and PEIE bits of the INTCON register.
6. If 9-bit reception is desired, set the [RX9](#) bit.
7. Enable reception by setting the [CREN](#) bit.
8. The RCxIF Interrupt Flag bit will be set when a character is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCxIE interrupt enable bit was also set.
9. Read the [RCxSTA](#) register to get the Error flags and, if 9-bit data reception is enabled, the ninth data bit.
10. Get the received eight Least Significant data bits from the receive buffer by reading the [RCxREG](#) register.
11. If an overrun occurred, clear the [OERR](#) flag by clearing the CREN receiver enable bit.

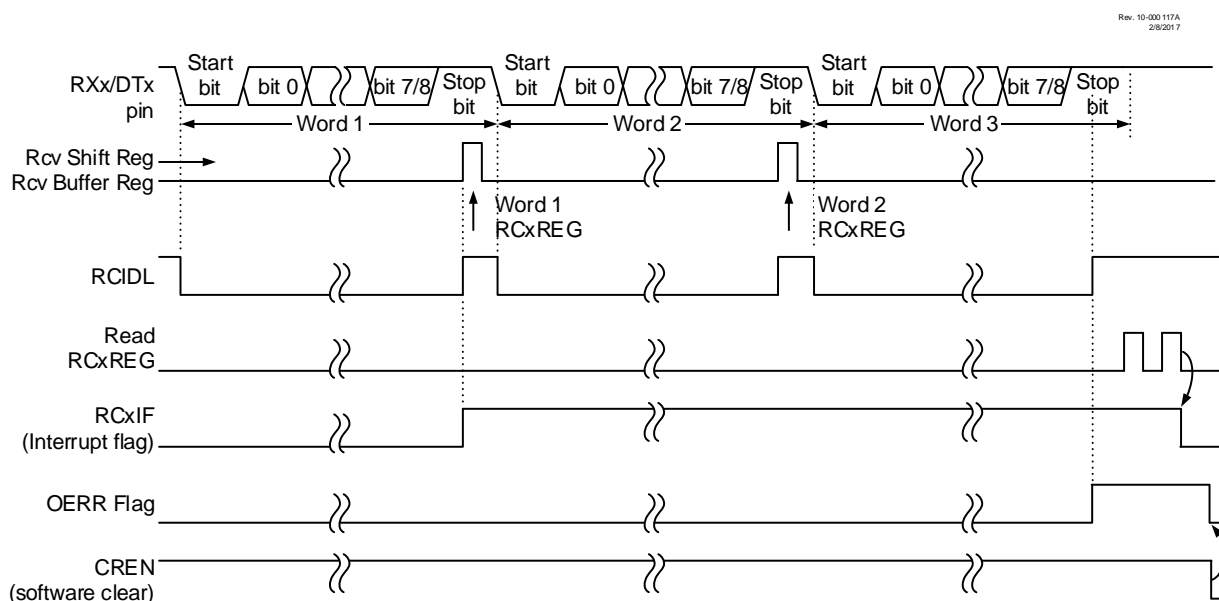
29.1.2.9 9-Bit Address Detection Mode Setup

This mode is typically used in RS-485 systems. To set up an Asynchronous Reception with Address Detect Enable, follow these steps:

1. Initialize the [SPxBRGH:SPxBRGL](#) register pair and the [BRGH](#) and [BRG16](#) bits to achieve the desired baud rate (see [EUSART Baud Rate Generator \(BRG\)](#)).
2. Set the RXxPPS register to select the RXx input pin.
3. Clear the ANSEL bit for the RXx pin (if applicable).
4. Enable the serial port by setting the [SPEN](#) bit. The [SYNC](#) bit must be cleared for asynchronous operation.
5. If interrupts are desired, set the RCxIE bit of the PEx register and the GIE and PEIE bits of the INTCON register.
6. Enable 9-bit reception by setting the [RX9](#) bit.

7. Enable address detection by setting the [ADDEN](#) bit.
8. Enable reception by setting the [CREN](#) bit.
9. The RCxIF Interrupt Flag bit will be set when a character with the ninth bit set is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCxIE interrupt enable bit is also set.
10. Read the [RCxSTA](#) register to get the Error flags. The ninth data bit will always be set.
11. Get the received eight Least Significant data bits from the receive buffer by reading the [RCxREG](#) register. Software determines if this is the device's address.
12. If an overrun occurred, clear the [OERR](#) flag by clearing the CREN receiver enable bit.
13. If the device has been addressed, clear the ADDEN bit to allow all received data into the receive buffer and generate interrupts.

Figure 29-5. Asynchronous Reception



Note: This timing diagram shows three bytes appearing on the RXx input. The OERR flag is set because the RCxREG register is not read before the third word is received.

29.2 Clock Accuracy with Asynchronous Operation

The factory calibrates the internal oscillator block output (INTOSC). However, the INTOSC frequency may drift as V_{DD} or temperature changes, directly affecting the asynchronous baud rate. Two methods may be used to adjust the baud rate clock, but both require a reference clock source of some kind.

The first (preferred) method uses the OSCTUNE register to adjust the INTOSC output. Adjusting the value in the OSCTUNE register allows for fine resolution changes to the system clock source.

The other method adjusts the value in the Baud Rate Generator. This can be done automatically with the Auto-Baud Detect feature (see [Auto-Baud Detect](#)). There may not be fine enough resolution when adjusting the Baud Rate Generator to compensate for a gradual change in the peripheral clock frequency.

29.3 EUSART Baud Rate Generator (BRG)

The Baud Rate Generator (BRG) is an 8-bit or 16-bit timer that is dedicated to the support of both the asynchronous and synchronous EUSART operations. By default, the BRG operates in 8-bit mode. Setting the **BRG16** bit selects 16-bit mode.

The SPxBRGH:SPxBRGL register pair determines the period of the free-running baud rate timer. In Asynchronous mode, the multiplier of the baud rate period is determined by both the **BRGH** and the BRG16 bits. In Synchronous mode, the BRGH bit is ignored.

Table 29-1 contains the formulas for determining the baud rate. **Equation 29-1** provides a sample calculation for determining the baud rate and baud rate error.

Typical baud rates and error values for various Asynchronous modes have been computed and are shown in the table below. It may be advantageous to use the high baud rate (BRGH = 1) or the 16-bit BRG (BRG16 = 1) to reduce the baud rate error. The 16-bit BRG mode is used to achieve slow baud rates for fast oscillator frequencies. The BRGH bit is used to achieve very high baud rates.

Writing a new value to the SPxBRGH:SPxBRGL register pair causes the BRG timer to be reset (or cleared). This ensures that the BRG does not wait for a timer overflow before outputting the new baud rate.

If the system clock is changed during an active receive operation, a receive error or data loss may result. To avoid this, check the status of the Receive Idle Flag (**RCIDL**) bit to make sure the receive operation is idle before changing the system clock.

Equation 29-1. Calculating Baud Rate Error

For a device with F_{OSC} of 16 MHz, desired baud rate of 9600, Asynchronous mode, 8-bit BRG:

$$DesiredBaudrate = \frac{F_{OSC}}{64 \times (SPxBRG + 1)}$$

Solving for SPxBRG:

$$SPxBRG = \frac{F_{OSC}}{64 \times DesiredBaudrate} - 1$$

$$SPxBRG = \frac{16000000}{64 \times 9600} - 1$$

$$SPxBRG = 25.042 \approx 25$$

$$CalculatedBaudrate = \frac{16000000}{64 \times (25 + 1)}$$

$$CalculatedBaudrate = 9615$$

$$Error = \frac{CalculatedBaudrate - DesiredBaudrate}{DesiredBaudrate}$$

$$Error = \frac{9615 - 9600}{9600}$$

$$Error = 0.16\%$$

Table 29-1. Baud Rate Formulas

| Configuration Bits | | | BRG/EUSART Mode | Baud Rate Formula |
|--------------------|-------|------|---------------------|----------------------|
| SYNC | BRG16 | BRGH | | |
| 0 | 0 | 0 | 8-bit/Asynchronous | $F_{OSC}/[64 (n+1)]$ |
| 0 | 0 | 1 | 8-bit/Asynchronous | $F_{OSC}/[16 (n+1)]$ |
| 0 | 1 | 0 | 16-bit/Asynchronous | |

.....continued

| Configuration Bits | | | BRG/EUSART Mode | Baud Rate Formula |
|--------------------|-------|------|---------------------|--------------------|
| SYNC | BRG16 | BRGH | | |
| 0 | 1 | 1 | 16-bit/Asynchronous | $F_{OSC}/[4(n+1)]$ |
| 1 | 0 | x | 8-bit/Synchronous | |
| 1 | 1 | x | 16-bit/Synchronous | |

Note: x = Don't care, n = value of SPxBRGH:SPxBRGL register pair.**Table 29-2.** Sample Baud Rates for Asynchronous Modes

| Baud Rate | SYNC = 0, BRGH = 0, BRG16 = 0 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|--------------------------------|---------|-----------------------|
| | $F_{OSC} = 32.000\text{ MHz}$ | | | $F_{OSC} = 20.000\text{ MHz}$ | | | $F_{OSC} = 18.432\text{ MHz}$ | | | $F_{OSC} = 11.0592\text{ MHz}$ | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | — | — | — | — | — | — | — | — | — | — | — | — |
| 1200 | — | — | — | 1221 | 1.73 | 255 | 1200 | 0.00 | 239 | 1200 | 0.00 | 143 |
| 2400 | 2404 | 0.16 | 207 | 2404 | 0.16 | 129 | 2400 | 0.00 | 119 | 2400 | 0.00 | 71 |
| 9600 | 9615 | 0.16 | 51 | 9470 | -1.36 | 32 | 9600 | 0.00 | 29 | 9600 | 0.00 | 17 |
| 10417 | 10417 | 0.00 | 47 | 10417 | 0.00 | 29 | 10286 | -1.26 | 27 | 10165 | -2.42 | 16 |
| 19.2k | 19.23k | 0.16 | 25 | 19.53k | 1.73 | 15 | 19.20k | 0.00 | 14 | 19.20k | 0.00 | 8 |
| 57.6k | 55.55k | -3.55 | 3 | — | — | — | 57.60k | 0.00 | 7 | 57.60k | 0.00 | 2 |
| 115.2k | — | — | — | — | — | — | — | — | — | — | — | — |

| Baud Rate | SYNC = 0, BRGH = 0, BRG16 = 0 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|
| | $F_{OSC} = 8.000\text{ MHz}$ | | | $F_{OSC} = 4.000\text{ MHz}$ | | | $F_{OSC} = 3.6864\text{ MHz}$ | | | $F_{OSC} = 1.000\text{ MHz}$ | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | — | — | — | 300 | 0.16 | 207 | 300 | 0.00 | 191 | 300 | 0.16 | 51 |
| 1200 | 1202 | 0.16 | 103 | 1202 | 0.16 | 51 | 1200 | 0.00 | 47 | 1202 | 0.16 | 12 |
| 2400 | 2404 | 0.16 | 51 | 2404 | 0.16 | 25 | 2400 | 0.00 | 23 | — | — | — |
| 9600 | 9615 | 0.16 | 12 | — | — | — | 9600 | 0.00 | 5 | — | — | — |
| 10417 | 10417 | 0.00 | 11 | 10417 | 0.00 | 5 | — | — | — | — | — | — |
| 19.2k | — | — | — | — | — | — | 19.20k | 0.00 | 2 | — | — | — |
| 57.6k | — | — | — | — | — | — | 57.60k | 0.00 | 0 | — | — | — |
| 115.2k | — | — | — | — | — | — | — | — | — | — | — | — |

| Baud Rate | SYNC = 0, BRGH = 1, BRG16 = 0 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|--------------------------------|---------|-----------------------|
| | $F_{OSC} = 32.000\text{ MHz}$ | | | $F_{OSC} = 20.000\text{ MHz}$ | | | $F_{OSC} = 18.432\text{ MHz}$ | | | $F_{OSC} = 11.0592\text{ MHz}$ | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | — | — | — | — | — | — | — | — | — | — | — | — |
| 1200 | — | — | — | — | — | — | — | — | — | — | — | — |
| 2400 | — | — | — | — | — | — | — | — | — | — | — | — |
| 9600 | 9615 | 0.16 | 207 | 9615 | 0.16 | 129 | 9600 | 0.00 | 119 | 9600 | 0.00 | 71 |
| 10417 | 10417 | 0.00 | 191 | 10417 | 0.00 | 119 | 10378 | -0.37 | 110 | 10473 | 0.53 | 65 |
| 19.2k | 19.23k | 0.16 | 103 | 19.23k | 0.16 | 64 | 19.20k | 0.00 | 59 | 19.20k | 0.00 | 35 |
| 57.6k | 57.14k | -0.79 | 34 | 56.82k | -1.36 | 21 | 57.60k | 0.00 | 19 | 57.60k | 0.00 | 11 |

| | | | | | | | | | | | | |
|--------|---------|------|----|---------|-------|----|--------|------|---|--------|------|---|
| 115.2k | 117.64k | 2.12 | 16 | 113.64k | -1.36 | 10 | 115.2k | 0.00 | 9 | 115.2k | 0.00 | 5 |
|--------|---------|------|----|---------|-------|----|--------|------|---|--------|------|---|

| Baud Rate | SYNC = 0, BRGH = 1, BRG16 = 0 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|
| | F _{OSC} = 8.000 MHz | | | F _{OSC} = 4.000 MHz | | | F _{OSC} = 3.6864 MHz | | | F _{OSC} = 1.000 MHz | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | — | — | — | — | — | — | — | — | — | 300 | 0.16 | 207 |
| 1200 | — | — | — | 1202 | 0.16 | 207 | 1200 | 0.00 | 191 | 1202 | 0.16 | 51 |
| 2400 | 2404 | 0.16 | 207 | 2404 | 0.16 | 103 | 2400 | 0.00 | 95 | 2404 | 0.16 | 25 |
| 9600 | 9615 | 0.16 | 51 | 9615 | 0.16 | 25 | 9600 | 0.00 | 23 | — | — | — |
| 10417 | 10417 | 0.00 | 47 | 10417 | 0.00 | 23 | 10473 | 0.53 | 21 | 10417 | 0.00 | 5 |
| 19.2k | 19231 | 0.16 | 25 | 19.23k | 0.16 | 12 | 19.2k | 0.00 | 11 | — | — | — |
| 57.6k | 55556 | -3.55 | 8 | — | — | — | 57.60k | 0.00 | 3 | — | — | — |
| 115.2k | — | — | — | — | — | — | 115.2k | 0.00 | 1 | — | — | — |

| Baud Rate | SYNC = 0, BRGH = 0, BRG16 = 1 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|--------------------------------|---------|-----------------------|
| | F _{OSC} = 32.000 MHz | | | F _{OSC} = 20.000 MHz | | | F _{OSC} = 18.432 MHz | | | F _{OSC} = 11.0592 MHz | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | 300.0 | 0.00 | 6666 | 300.0 | -0.01 | 4166 | 300.0 | 0.00 | 3839 | 300.0 | 0.00 | 2303 |
| 1200 | 1200 | -0.02 | 3332 | 1200 | -0.03 | 1041 | 1200 | 0.00 | 959 | 1200 | 0.00 | 575 |
| 2400 | 2401 | -0.04 | 832 | 2399 | -0.03 | 520 | 2400 | 0.00 | 479 | 2400 | 0.00 | 287 |
| 9600 | 9615 | 0.16 | 207 | 9615 | 0.16 | 129 | 9600 | 0.00 | 119 | 9600 | 0.00 | 71 |
| 10417 | 10417 | 0.00 | 191 | 10417 | 0.00 | 119 | 10378 | -0.37 | 110 | 10473 | 0.53 | 65 |
| 19.2k | 19.23k | 0.16 | 103 | 19.23k | 0.16 | 64 | 19.20k | 0.00 | 59 | 19.20k | 0.00 | 35 |
| 57.6k | 57.14k | -0.79 | 34 | 56.818 | -1.36 | 21 | 57.60k | 0.00 | 19 | 57.60k | 0.00 | 11 |
| 115.2k | 117.6k | 2.12 | 16 | 113.636 | -1.36 | 10 | 115.2k | 0.00 | 9 | 115.2k | 0.00 | 5 |

| Baud Rate | SYNC = 0, BRGH = 0, BRG16 = 1 | | | | | | | | | | | |
|-----------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|
| | F _{OSC} = 8.000 MHz | | | F _{OSC} = 4.000 MHz | | | F _{OSC} = 3.6864 MHz | | | F _{OSC} = 1.000 MHz | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | 299.9 | -0.02 | 1666 | 300.1 | 0.04 | 832 | 300.0 | 0.00 | 767 | 300.5 | 0.16 | 207 |
| 1200 | 1199 | -0.08 | 416 | 1202 | 0.16 | 207 | 1200 | 0.00 | 191 | 1202 | 0.16 | 51 |
| 2400 | 2404 | 0.16 | 207 | 2404 | 0.16 | 103 | 2400 | 0.00 | 95 | 2404 | 0.16 | 25 |
| 9600 | 9615 | 0.16 | 51 | 9615 | 0.16 | 25 | 9600 | 0.00 | 23 | — | — | — |
| 10417 | 10417 | 0.00 | 47 | 10417 | 0.00 | 23 | 10473 | 0.53 | 21 | 10417 | 0.00 | 5 |
| 19.2k | 19.23k | 0.16 | 25 | 19.23k | 0.16 | 12 | 19.20k | 0.00 | 11 | — | — | — |
| 57.6k | 55556 | -3.55 | 8 | — | — | — | 57.60k | 0.00 | 3 | — | — | — |
| 115.2k | — | — | — | — | — | — | 115.2k | 0.00 | 1 | — | — | — |

| Baud Rate | SYNC = 0, BRGH = 1, BRG16 = 1 or SYNC = 1, BRG16 = 1 | | | | | | | | | | | |
|-----------|--|---------|-----------------------|-------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|--------------------------------|---------|-----------------------|
| | F _{OSC} = 32.000 MHz | | | F _{OSC} = 20.000 MHz | | | F _{OSC} = 18.432 MHz | | | F _{OSC} = 11.0592 MHz | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |

| | | | | | | | | | | | | |
|--------|--------|-------|-------|--------|-------|-------|--------|------|-------|--------|------|------|
| 300 | 300.0 | 0.00 | 26666 | 300.0 | 0.00 | 16665 | 300.0 | 0.00 | 15359 | 300.0 | 0.00 | 9215 |
| 1200 | 1200 | 0.00 | 6666 | 1200 | -0.01 | 4166 | 1200 | 0.00 | 3839 | 1200 | 0.00 | 2303 |
| 2400 | 2400 | 0.01 | 3332 | 2400 | 0.02 | 2082 | 2400 | 0.00 | 1919 | 2400 | 0.00 | 1151 |
| 9600 | 9604 | 0.04 | 832 | 9597 | -0.03 | 520 | 9600 | 0.00 | 479 | 9600 | 0.00 | 287 |
| 10417 | 10417 | 0.00 | 767 | 10417 | 0.00 | 479 | 10425 | 0.08 | 441 | 10433 | 0.16 | 264 |
| 19.2k | 19.18k | -0.08 | 416 | 19.23k | 0.16 | 259 | 19.20k | 0.00 | 239 | 19.20k | 0.00 | 143 |
| 57.6k | 57.55k | -0.08 | 138 | 57.47k | -0.22 | 86 | 57.60k | 0.00 | 79 | 57.60k | 0.00 | 47 |
| 115.2k | 115.9k | 0.64 | 68 | 116.3k | 0.94 | 42 | 115.2k | 0.00 | 39 | 115.2k | 0.00 | 23 |

| Baud Rate | SYNC = 0, BRGH = 1, BRG16 = 1 or SYNC = 1, BRG16 = 1 | | | | | | | | | | | |
|-----------|--|---------|-----------------------|------------------------------|---------|-----------------------|-------------------------------|---------|-----------------------|------------------------------|---------|-----------------------|
| | F _{OSC} = 8.000 MHz | | | F _{OSC} = 4.000 MHz | | | F _{OSC} = 3.6864 MHz | | | F _{OSC} = 1.000 MHz | | |
| | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) | Actual Rate | % Error | SPBRG value (decimal) |
| 300 | 300.0 | 0.00 | 6666 | 300.0 | 0.01 | 3332 | 300.0 | 0.00 | 3071 | 300.1 | 0.04 | 832 |
| 1200 | 1200 | -0.02 | 1666 | 1200 | 0.04 | 832 | 1200 | 0.00 | 767 | 1202 | 0.16 | 207 |
| 2400 | 2401 | 0.04 | 832 | 2398 | 0.08 | 416 | 2400 | 0.00 | 383 | 2404 | 0.16 | 103 |
| 9600 | 9615 | 0.16 | 207 | 9615 | 0.16 | 103 | 9600 | 0.00 | 95 | 9615 | 0.16 | 25 |
| 10417 | 10417 | 0 | 191 | 10417 | 0.00 | 95 | 10473 | 0.53 | 87 | 10417 | 0.00 | 23 |
| 19.2k | 19.23k | 0.16 | 103 | 19.23k | 0.16 | 51 | 19.20k | 0.00 | 47 | 19.23k | 0.16 | 12 |
| 57.6k | 57.14k | -0.79 | 34 | 58.82k | 2.12 | 16 | 57.60k | 0.00 | 15 | — | — | — |
| 115.2k | 117.6k | 2.12 | 16 | 111.1k | -3.55 | 8 | 115.2k | 0.00 | 7 | — | — | — |

29.3.1 Auto-Baud Detect

The EUSART module supports automatic detection and calibration of the baud rate.

In the Auto-Baud Detect (ABD) mode, the clock to the BRG is reversed. Rather than the BRG clocking the incoming RX signal, the RX signal is timing the BRG. The Baud Rate Generator is used to time the period of a received 55h (ASCII "U") which is the Sync character for the LIN bus. The unique feature of this character is that it has five rising edges, including the Stop bit edge.

Setting the Auto-Baud Detect Enable ([ABDEN](#)) bit starts the auto-baud calibration sequence. While the ABD sequence takes place, the EUSART state machine is held in Idle. On the first rising edge of the receive line, after the Start bit, the [SPxBRG](#) register begins counting up using the BRG counter clock as shown in [Figure 29-6](#). The fifth rising edge will occur on the RXx pin at the end of the eighth bit period. At that time, an accumulated value totaling the proper BRG period is left in the SPxBRGH:SPxBRGL register pair, the ABDEN bit is automatically cleared, and the RCxIF interrupt flag is set. The value in the [RCxREG](#) register needs to be read to clear the RCxIF interrupt. RCxREG content may be discarded. When calibrating for modes that do not use the SPxBRGH register, the user can verify that the SPxBRGL register did not overflow by checking for 00h in the SPxBRGH register.

The BRG auto-baud clock is determined by the [BRG16](#) and [BRGH](#) bits, as shown in [Table 29-3](#). During ABD, both the SPxBRGH and SPxBRGL registers are used as a 16-bit counter, independent of the BRG16 bit setting. While calibrating the baud rate period, the SPxBRGH and SPxBRGL registers are clocked at 1/8th the BRG base clock rate. The resulting byte measurement is the average bit time when clocked at full speed.

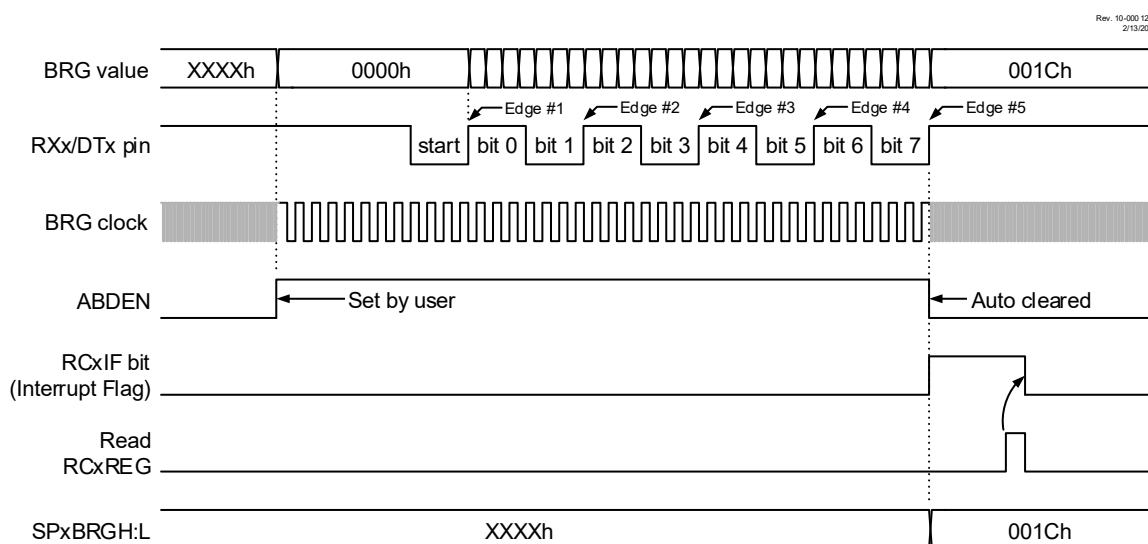
Notes:

1. If the Wake-Up Enable ([WUE](#)) bit is set with the ABDEN bit, auto-baud detection will occur on the byte following the Break character (see [Auto-Wake-Up on Break](#)).
2. It is up to the user to determine that the incoming character baud rate is within the range of the selected BRG clock source. Some combinations of oscillator frequency and EUSART baud rates are not possible.
3. During the auto-baud process, the auto-baud counter starts counting at one. Upon completion of the auto-baud sequence, to achieve maximum accuracy, subtract 1 from the SPxBRGH:SPxBRGL register pair.

Table 29-3. BRG Counter Clock Rates

| BRG16 | BRGH | BRG Base Clock | BRG ABD Clock |
|-------|------|----------------|---------------|
| 1 | 1 | $F_{OSC}/4$ | $F_{OSC}/32$ |
| 1 | 0 | $F_{OSC}/16$ | $F_{OSC}/128$ |
| 0 | 1 | $F_{OSC}/16$ | $F_{OSC}/128$ |
| 0 | 0 | $F_{OSC}/64$ | $F_{OSC}/512$ |

Note: During the ABD sequence, the SPxBRGL and SPxBRGH registers are both used as a 16-bit counter, independent of the BRG16 setting.

Figure 29-6. Automatic Baud Rate Calibration**29.3.2 Auto-Baud Overflow**

During the course of automatic baud detection, the Auto-Baud Detect Overflow ([ABDOVF](#)) bit will be set if the baud rate counter overflows before the fifth rising edge is detected on the RX pin. The ABDOVF bit indicates that the counter has exceeded the maximum count that can fit in the 16 bits of the [SPxBRGH:SPxBRGL](#) register pair. After the ABDOVF bit has been set, the counter continues to count until the fifth rising edge is detected on the RX pin. Upon detecting the fifth RX edge, the hardware will set the RCxIF interrupt flag and clear the [ABDEN](#) bit. The RCxIF flag can be subsequently cleared by reading the [RCxREG](#) register. The ABDOVF bit can be cleared by software directly.

To terminate the auto-baud process before the RCxIF flag is set, clear the ABDEN bit then clear the ABDOVF bit. The ABDOVF bit will remain set if the ABDEN bit is not cleared first.

29.3.3 Auto-Wake-Up on Break

During Sleep mode, all clocks to the EUSART are suspended. Because of this, the Baud Rate Generator is inactive and a proper character reception cannot be performed. The Auto-Wake-Up feature allows the controller to wake up due to activity on the RX/DT line. This feature is available only in Asynchronous mode.

The Auto-Wake-Up feature is enabled by setting the **WUE** bit. Once set, the normal receive sequence on RX/DT is disabled, and the EUSART remains in an Idle state, monitoring for a wake-up event independent of the CPU mode. A wake-up event consists of a high-to-low transition on the RX/DT line. This coincides with the start of a Sync Break or a wake-up signal character for the LIN protocol.

The EUSART module generates an RCxIF interrupt coincident with the wake-up event. The interrupt is generated synchronously to the Q clocks in normal CPU operating modes, as shown in Figure 29-7, and asynchronously if the device is in Sleep mode, as shown in Figure 29-8. The Interrupt condition is cleared by reading the **RCxREG** register.

The WUE bit is automatically cleared by the low-to-high transition on the RX line at the end of the Break. This signals to the user that the Break event is over. At this point, the EUSART module is in Idle mode waiting to receive the next character.

29.3.3.1 Special Considerations

Break Character

To avoid character errors or character fragments during a wake-up event, the wake-up character must be all zeros.

When the wake-up is enabled, the function works independent of the low time on the data stream. If the **WUE** bit is set and a valid nonzero character is received, the low time from the Start bit to the first rising edge will be interpreted as the wake-up event. The remaining bits in the character will be received as a fragmented character and subsequent characters can result in framing or overrun errors.

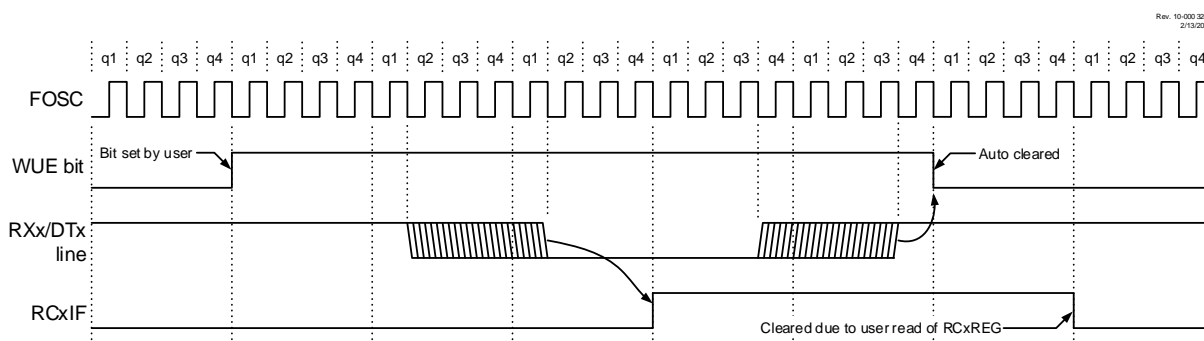
Therefore, the initial character in the transmission must be all '0's. This must be 10 or more bit times, 13-bit times recommended for LIN bus, or any number of bit times for standard RS-232 devices.

WUE Bit

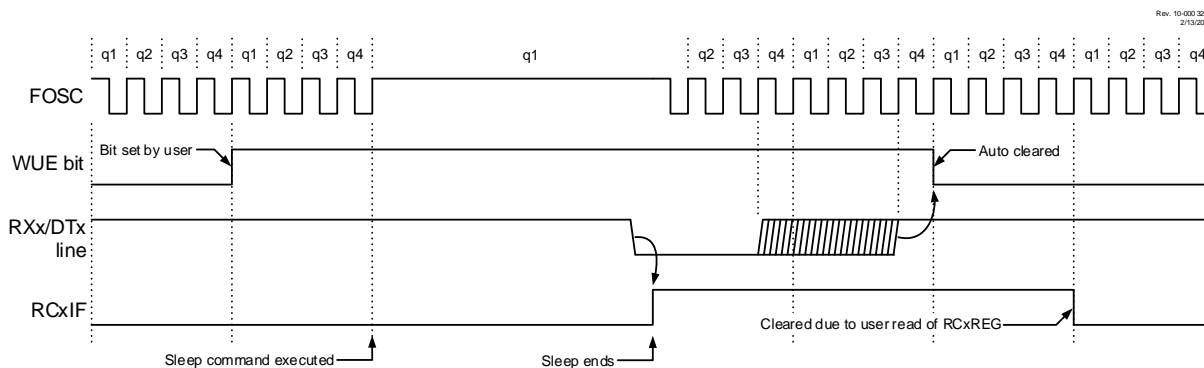
The wake-up event causes a receive interrupt by setting the RCxIF bit. The WUE bit is cleared in hardware by a rising edge on RX/DT. The Interrupt condition is then cleared in software by reading the **RCxREG** register and discarding its contents.

To ensure that no actual data are lost, check the **RCIDL** bit to verify that a receive operation is not in process before setting the WUE bit. If a receive operation is not occurring, the WUE bit may then be set just prior to entering the Sleep mode.

Figure 29-7. Auto-Wake-Up (WUE) Bit Timing During Normal Operation



Note: The EUSART remains in Idle while the WUE bit is set.

Figure 29-8. Auto-Wake-Up (WUE) Bit Timings During Sleep

Note: The EUSART remains in Idle while the WUE bit is set.

29.3.4 Break Character Sequence

The EUSART module has the capability of sending the special Break character sequences that are required by the LIN bus standard. A Break character consists of a Start bit, followed by 12 '0' bits and a Stop bit.

To send a Break character, set the Send Break Character (**SENDB**) and Transmit Enable (**TXEN**) bits. The Break character transmission is then initiated by a write to the **TXxREG**. The value of data written to **TXxREG** will be ignored and all '0's will be transmitted.

The **SENDB** bit is automatically reset by hardware after the corresponding Stop bit is sent. This allows the user to preload the transmit FIFO with the next transmit byte following the Break character (typically, the Sync character in the LIN specification).

The Transmit Shift Register Status (**TRMT**) bit indicates when the transmit operation is Active or Idle, just as it does during normal transmission. See [Figure 29-9](#) for more details.

29.3.4.1 Break and Sync Transmit Sequence

The following sequence will start a message frame header made up of a Break, followed by an auto-baud Sync byte. This sequence is typical of a LIN bus host.

1. Configure the EUSART for the desired mode.
2. Set the **TXEN** and **SENDB** bits to enable the Break sequence.
3. Load the **TXxREG** with a dummy character to initiate transmission (the value is ignored).
4. Write '55h' to **TXxREG** to load the Sync character into the transmit FIFO buffer.
5. After the Break has been sent, the **SENDB** bit is reset by hardware and the Sync character is then transmitted.

When the **TXxREG** becomes empty, as indicated by **TXxIF**, the next data byte can be written to **TXxREG**.

29.3.5 Receiving a Break Character

The EUSART module can receive a Break character in two ways.

The first method to detect a Break character uses the Framing Error (**FERR**) bit and the received data as indicated by **RCxREG**. The Baud Rate Generator is assumed to have been initialized to the expected baud rate.

A Break character has been received when all three of the following conditions are true:

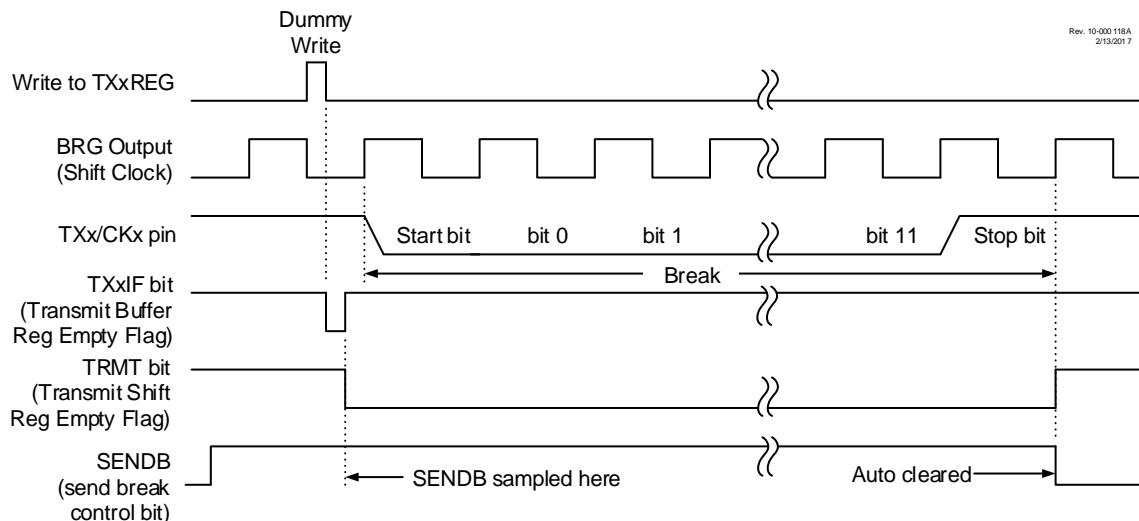
- **RCxIF** bit is set

- FERR bit is set
- RCxREG = 00h

The second method uses the Auto-Wake-Up feature described in [Auto-Wake-Up on Break](#). By enabling this feature, the EUSART will sample the next two transitions on RX/DT, cause an RCxIF interrupt, and receive the next data byte followed by another interrupt.

Note that following a Break character, the user will typically want to enable the Auto-Baud Detect feature. For both methods, the user can set the [ABDEN](#) bit before placing the EUSART in Sleep mode.

Figure 29-9. Send Break Character Sequence



29.4 EUSART Synchronous Mode

Synchronous serial communications are typically used in systems with a single host and one or more clients. The host device contains the necessary circuitry for baud rate generation and supplies the clock for all devices in the system. Client devices can take advantage of the host clock by eliminating the internal clock generation circuitry.

There are two signal lines in Synchronous mode: A bidirectional data line (DT) and a clock line (CK). The clients use the external clock supplied by the host to shift the serial data into and out of their respective receive and transmit shift registers. Since the data line is bidirectional, synchronous operation is half-duplex only. Half-duplex refers to the fact that host and client devices can receive and transmit data but not both simultaneously. The EUSART can operate as either a host or client device.

Start and Stop bits are not used in synchronous transmissions.

29.4.1 Synchronous Host Mode

The following bits are used to configure the EUSART for synchronous host operation:

- The [SYNC](#) bit is set to '1' to configure the EUSART for synchronous operation
- The Clock Source Select ([CSRC](#)) bit is set to '1' to configure the EUSART as the host
- The Single Receive Enable ([SREN](#)) bit is set to '0' for transmit; SREN = 1 for receive (recommended setting to receive 1 byte)
- The Continuous Receive Enable ([CREN](#)) bit is set to '0' for transmit; CREN = 1 to receive continuously

- The **SPEN** bit is set to '1' to enable the EUSART interface



Important: Clearing the SREN and CREN bits ensure that the device is in the Transmit mode, otherwise the device will be configured to receive.

29.4.1.1 Host Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a host transmits the clock on the TX/CK line. The TXx/CKx pin output driver is automatically enabled when the EUSART is configured for synchronous transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One clock cycle is generated for each data bit. Only as many clock cycles are generated as there are data bits.

29.4.1.2 Clock Polarity

A clock polarity option is provided for Microwire compatibility. Clock polarity is selected with the Clock/Transmit Polarity Select (**SCKP**) bit. Setting the SCKP bit sets the clock Idle state as high. When the SCKP bit is set, the data changes on the falling edge of each clock. Clearing the SCKP bit sets the Idle state as low. When the SCKP bit is cleared, the data changes on the rising edge of each clock.

29.4.1.3 Synchronous Host Transmission

Data are transferred out of the device on the RXx/DTx pin. The RXx/DTx and TXx/CKx pin output drivers are automatically enabled when the EUSART is configured for synchronous host transmit operation.

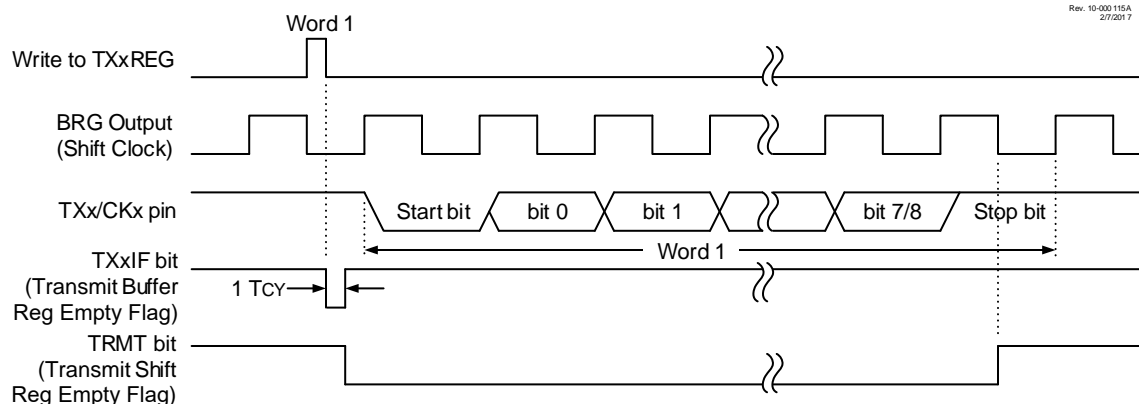
A transmission is initiated by writing a character to the **TXxREG** register. If the TSR still contains all or part of a previous character the new character data are held in the TXxREG until the last bit of the previous character has been transmitted. If this is the first character, or the previous character has been completely flushed from the TSR, the data in the TXxREG is immediately transferred to the TSR. The transmission of the character commences immediately following the transfer of the data to the TSR from the TXxREG.

Each data bit changes on the leading edge of the host clock and remains valid until the subsequent leading clock edge.

Note: The TSR register is not mapped in data memory, so it is not available to the user.

29.4.1.4 Synchronous Host Transmission Setup

1. Initialize the **SPxBRGH;SPxBRGL** register pair and the **BRG16** bit to achieve the desired baud rate (see **EUSART Baud Generator (BRG)**).
2. Select the transmit output pin by writing the appropriate values to the RxyPPS register and RXxPPS register. Both selections may enable the same pin.
3. Select the clock output pin by writing the appropriate values to the RxyPPS register and TXxPPS register. Both selections may enable the same pin.
4. Enable the synchronous host serial port by setting bits **SYNC**, **SPEN** and **CSRC**.
5. Disable Receive mode by clearing the **SREN** and **CREN** bits.
6. Enable Transmit mode by setting the **TXEN** bit.
7. If 9-bit transmission is desired, set the **TX9** bit.
8. If interrupts are desired, set the TXxIE bit of the PEx register and the GIE and PEIE bits of the INTCON register.
9. If 9-bit transmission is selected, the ninth bit will be loaded in the **TX9D** bit.
10. Start transmission by loading data to the **TXxREG** register.

Figure 29-10. Synchronous Transmission

29.4.1.5 Synchronous Host Reception

Data are received at the RXx/DTx pin. The RXx/DTx pin output driver is automatically disabled when the EUSART is configured for synchronous host receive operation.

In Synchronous mode, reception is enabled by setting either the Single Receive Enable (**SREN**) bit or the Continuous Receive Enable (**CREN**) bit.

When SREN is set and CREN is clear, only as many clock cycles are generated as there are data bits in a single character. The SREN bit is automatically cleared at the completion of one character. When CREN is set, clocks are continuously generated until CREN is cleared. If CREN is cleared in the middle of a character the CK clock stops immediately and the partial character is discarded. If SREN and CREN are both set, then SREN is cleared at the completion of the first character and CREN takes precedence.

To initiate reception, set either SREN or CREN. Data are sampled at the RXx/DTx pin on the trailing edge of the TX/CK clock pin and is shifted into the Receive Shift Register (RSR). When a complete character is received into the RSR, the RCxIF bit is set and the character is automatically transferred to the two character receive FIFO. The eight Least Significant bits of the top character in the receive FIFO are available in **RCxREG**. The RCxIF bit remains set as long as there are unread characters in the receive FIFO.

Note: If the RX/DT function is on an analog pin, the corresponding ANSEL bit must be cleared for the receiver to function.

29.4.1.6 Client Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a client receives the clock on the TX/CK line. The TXx/CKx pin output driver is automatically disabled when the device is configured for synchronous client transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One data bit is transferred for each clock cycle. Only as many clock cycles may be received as there are data bits.



Important: If the device is configured as a client and the TX/CK function is on an analog pin, the corresponding ANSEL bit must be cleared.

29.4.1.7 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before the FIFO is accessed. When this happens the Overrun Error (**OERR**) bit is set. The characters already in the FIFO buffer can be read but no additional

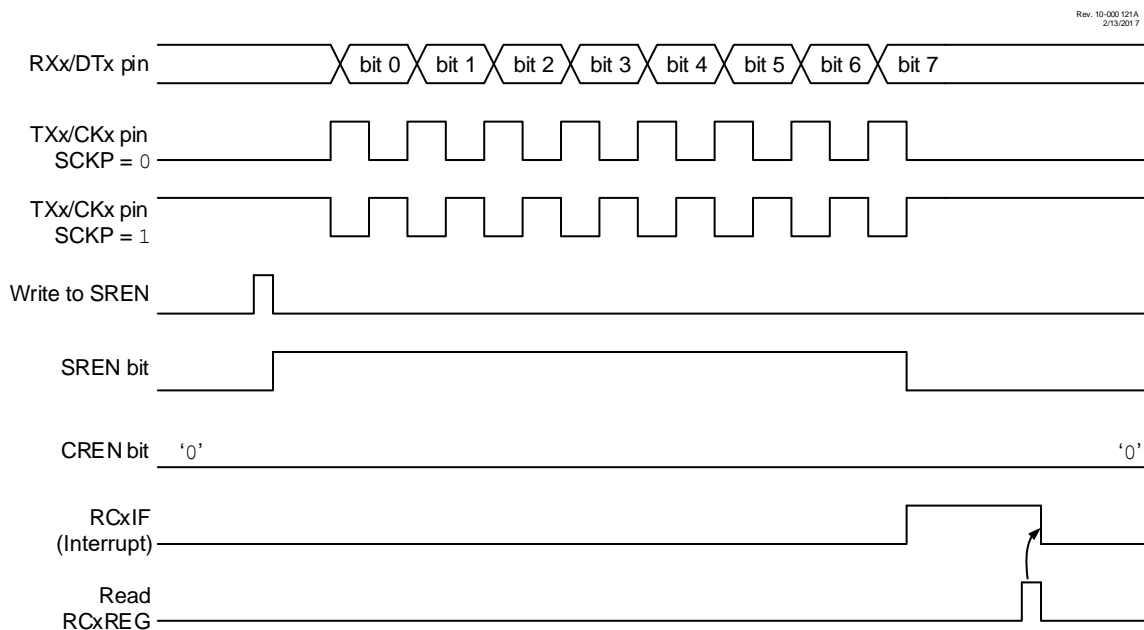
characters will be received until the error is cleared. The error must be cleared by either clearing the **CREN** bit or by resetting the EUSART by clearing the **SPEN** bit.

29.4.1.8 Receiving 9-Bit Characters

The EUSART supports 9-bit character reception. When the 9-Bit Receive Enable (**RX9**) bit is set, the EUSART will shift nine bits into the RSR for each character received. The **RX9D** bit is the ninth and Most Significant data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the **RX9D** data bit must be read before reading the eight Least Significant bits from the **RCxREG** register.

29.4.1.9 Synchronous Host Reception Setup

1. Initialize the **SPxBRGH:SPxBRGL** register pair and set or clear the **BRG16** bit, as required, to achieve the desired baud rate.
2. Select the receive input pin by writing the appropriate values to the **RxyPPS** and **RXxPPS** registers. Both selections may enable the same pin.
3. Select the clock output pin by writing the appropriate values to the **RxyPPS** and **TXxPPS** registers. Both selections may enable the same pin.
4. Clear the **ANSEL** bit for the **RXx** pin (if applicable).
5. Enable the synchronous host serial port by setting the **SYNC**, **SPEN** and **CSRC** bits.
6. Ensure that the **CREN** and **SREN** bits are cleared.
7. If interrupts are desired, set the **RCxIE** bit of the **PIEx** register and the **GIE** and **PEIE** bits of the **INTCON** register.
8. If 9-bit reception is desired, set the **RX9** bit.
9. Start reception by setting the **SREN** bit or, for continuous reception, set the **CREN** bit.
10. The **RCxIF** Interrupt Flag bit will be set when reception of a character is complete. An interrupt will be generated if the **RCxIE** enable bit was set.
11. Read the **RCxSTA** register to get the ninth bit (if enabled) and determine if any error occurred during reception.
12. Read the 8-bit received data by reading the **RCxREG** register.
13. If an overrun error occurs, clear the error by either clearing the **CREN** bit or by clearing the **SPEN** bit which resets the EUSART.

Figure 29-11. Synchronous Reception (Host Mode, SREN)

29.4.2 Synchronous Client Mode

The following bits are used to configure the EUSART for synchronous client operation:

- **SYNC** = 1 (configures the EUSART for synchronous operation)
- **CSRC** = 0 (configures the EUSART as a client)
- **SREN** = 0 (for transmit); SREN = 1 (for single byte receive)
- **CREN** = 0 (for transmit); CREN = 1 (recommended setting for continuous receive)
- **SPEN** = 1 (enables the EUSART)



Important: Clearing the SREN and CREN bits ensure that the device is in Transmit mode, otherwise the device will be configured to receive.

29.4.2.1 EUSART Synchronous Client Transmit

The operation of the Synchronous Host and Client modes are identical (see [Synchronous Host Transmission](#)), except in the case of the Sleep mode.

If two words are written to the **TXxREG** and then the **SLEEP** instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in the TXxREG register.
3. The TXxIF bit will not be set.
4. After the first character has been shifted out of TSR, the TXxREG register will transfer the second character to the TSR and the TXxIF bit will now be set.
5. If the PEIE and TXxIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

29.4.2.2 Synchronous Client Transmission Setup

1. Set the **SYNC** and **SPEN** bits and clear the **CSRC** bit.
2. Select the transmit output pin by writing the appropriate values to the RxyPPS register and RXxPPS register. Both selections may enable the same pin.
3. Select the clock input pin by writing the appropriate value to the TXxPPS register.
4. Clear the ANSEL bit for the CKx pin (if applicable).
5. Clear the **CREN** and **SREN** bits.
6. If interrupts are desired, set the TXxIE bit of the PIRx register and the GIE and PEIE bits of the INTCON register.
7. If 9-bit transmission is desired, set the **TX9** bit.
8. Enable transmission by setting the **TXEN** bit.
9. If 9-bit transmission is selected, insert the Most Significant bit into the **TX9D** bit.
10. Prepare for transmission by writing the eight Least Significant bits to the **TXxREG** register. The word will be transmitted in response to the Host clocks at the CKx pin.

29.4.2.3 EUSART Synchronous Client Reception

The operation of the Synchronous Host and Client modes is identical (see [Synchronous Host Reception](#)), with the following exceptions:

- Sleep
- **CREN** bit is always set, therefore the receiver is never Idle
- **SREN** bit, which is a “don’t care” in Client mode

A character may be received while in Sleep mode by setting the CREN bit prior to entering Sleep. Once the word is received, the RSR register will transfer the data to the **RCxREG** register. If the RCxIE enable bit is set, the interrupt generated will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will branch to the interrupt vector.

29.4.2.4 Synchronous Client Reception Setup

1. Set the **SYNC** and **SPEN** bits and clear the **CSRC** bit.
2. Select the receive input pin by writing the appropriate value to the RXxPPS register.
3. Select the clock input pin by writing the appropriate values to the TXxPPS register.
4. Clear the ANSEL bit for both the TXx/CKx and RXx/DTx pins (if applicable).
5. If interrupts are desired, set the RCxIE bit of the PIRx register and the GIE and PEIE bits of the INTCON register.
6. If 9-bit reception is desired, set the **RX9** bit.
7. Set the **CREN** bit to enable reception.
8. The RCxIF bit will be set when reception is complete. An interrupt will be generated if the RCxIE bit was set.
9. If 9-bit mode is enabled, retrieve the Most Significant bit from the **RX9D** bit.
10. Retrieve the eight Least Significant bits from the receive FIFO by reading the **RCxREG** register.
11. If an overrun error occurs, clear the error by either clearing the CREN bit or by clearing the SPEN bit which resets the EUSART.

29.5 EUSART Operation During Sleep

The EUSART will remain active during Sleep only in the Synchronous Client mode. All other modes require the system clock and therefore cannot generate the necessary signals to run the Transmit or Receive Shift registers during Sleep.

Synchronous Client mode uses an externally generated clock to run the Transmit and Receive Shift registers.

29.5.1 Synchronous Receive During Sleep

To receive during Sleep, all the following conditions must be met before entering Sleep mode:

- [RCxSTA](#) and [TXxSTA](#) Control registers must be configured for Synchronous Client Reception (see [Synchronous Client Reception Setup](#)).
- If interrupts are desired, set the RCxIE bit of the PIEx register and the GIE and PEIE bits of the INTCON register.
- The RCxIF interrupt flag must be cleared by reading [RCxREG](#) to unload any pending characters in the receive buffer.

Upon entering Sleep mode, the device will be ready to accept data and clocks on the RXx/DTx and TXx/CKx pins, respectively. When the data word has been completely clocked in by the external device, the RCxIF Interrupt Flag bit of the PIRx register will be set. Thereby, waking the processor from Sleep.

Upon waking from Sleep, the instruction following the `SLEEP` instruction will be executed. If the Global Interrupt Enable (GIE) bit of the INTCON register is also set, then the Interrupt Service Routine (ISR) will be called.

29.5.2 Synchronous Transmit During Sleep

To transmit during Sleep, the following conditions must be met before entering Sleep mode:

- The [RCxSTA](#) and [TXxSTA](#) Control registers must be configured for synchronous client transmission (see [Synchronous Client Transmission Setup](#)).
- The TXxIF interrupt flag must be cleared by writing the output data to the [TXxREG](#), thereby filling the TSR and transmit buffer.
- The TXxIE interrupt enable bits of the PIEx register and PEIE of the INTCON register must be written to '1'.
- If interrupts are desired, set the GIE bit of the INTCON register.

Upon entering Sleep mode, the device will be ready to accept clocks on the TXx/CKx pin and transmit data on the RXx/DTx pin. When the data word in the TSR register has been completely clocked out by the external device, the pending byte in the TXxREG will transfer to the TSR and the TXxIF flag will be set. Thereby, waking the processor from Sleep. At this point, the TXxREG is available to accept another character for transmission. Writing TXxREG will clear the TXxIF flag.

Upon waking from Sleep, the instruction following the `SLEEP` instruction will be executed. If the Global Interrupt Enable (GIE) bit is also set then the Interrupt Service Routine (ISR) will be called.

29.6 Register Definitions: EUSART Control

29.6.1 TXxSTA

Name: TXxSTA
Address: 0xF9D, 0xE99

Transmit Status and Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|-----|------|------|-------|------|------|------|
| | CSRC | TX9 | TXEN | SYNC | SENDB | BRGH | TRMT | TX9D |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |

Bit 7 – CSRC Clock Source Select

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 1 | Host mode (clock generated internally from BRG) |
| 0 | SYNC = 1 | Client mode (clock from external source) |
| X | SYNC = 0 | Don't care |

Bit 6 – TX9 9-Bit Transmit Enable

| Value | Description |
|-------|----------------------------|
| 1 | Selects 9-bit transmission |
| 0 | Selects 8-bit transmission |

Bit 5 – TXEN Transmit Enable Enables transmitter⁽¹⁾

| Value | Description |
|-------|-------------------|
| 1 | Transmit enabled |
| 0 | Transmit disabled |

Bit 4 – SYNC EUSART Mode Select

| Value | Description |
|-------|-------------------|
| 1 | Synchronous mode |
| 0 | Asynchronous mode |

Bit 3 – SENDB Send Break Character

| Value | Condition | Description |
|-------|-----------|--|
| 1 | SYNC = 0 | Send Sync Break on next transmission (cleared by hardware upon completion) |
| 0 | SYNC = 0 | Sync Break transmission disabled or completed |
| X | SYNC = 1 | Don't care |

Bit 2 – BRGH High Baud Rate Select

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 0 | High speed, if BRG16 = 1, baud rate is baudclk/4; else baudclk/16 |
| 0 | SYNC = 0 | Low speed |
| X | SYNC = 1 | Don't care |

Bit 1 – TRMT Transmit Shift Register (TSR) Status

| Value | Description |
|-------|------------------|
| 1 | TSR is empty |
| 0 | TSR is not empty |

Bit 0 – TX9D Ninth Bit of Transmit Data

Can be address/data bit or a parity bit.

Note: 1. The [SREN](#) and [CREN](#) bits override TXEN in Sync mode.

29.6.2 RCxSTA

Name: RCxSTA
Address: 0xF9C, 0xE98

Receive Status and Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|-----|--------|------|-------|------|------|------|
| | SPEN | RX9 | SREN | CREN | ADDEN | FERR | OERR | RX9D |
| Access | R/W | R/W | R/W/HC | R/W | R/W | R | R/HC | R/HC |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – SPEN Serial Port Enable

| Value | Description |
|-------|--------------------------------------|
| 1 | Serial port enabled |
| 0 | Serial port disabled (held in Reset) |

Bit 6 – RX9 9-Bit Receive Enable

| Value | Description |
|-------|-------------------------|
| 1 | Selects 9-bit reception |
| 0 | Selects 8-bit reception |

Bit 5 – SREN Single Receive Enable

Controls reception. This bit is cleared by hardware when reception is complete

| Value | Condition | Description |
|-------|-----------------------|----------------------------|
| 1 | SYNC = 1 AND CSRC = 1 | Start single receive |
| 0 | SYNC = 1 AND CSRC = 1 | Single receive is complete |
| X | SYNC = 0 OR CSRC = 0 | Don't care |

Bit 4 – CREN Continuous Receive Enable

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 1 | Enables continuous receive until enable bit CREN is cleared (CREN overrides SREN) |
| 0 | SYNC = 1 | Disables continuous receive |
| 1 | SYNC = 0 | Enables receiver |
| 0 | SYNC = 0 | Disables receiver |

Bit 3 – ADDEN Address Detect Enable

| Value | Condition | Description |
|-------|----------------------|---|
| 1 | SYNC = 0 AND RX9 = 1 | The receive buffer is loaded and the interrupt occurs only when the ninth received bit is set |
| 0 | SYNC = 0 AND RX9 = 1 | All bytes are received and interrupt always occurs. Ninth bit can be used as parity bit |
| X | RX9 = 0 OR SYNC = 1 | Don't care |

Bit 2 – FERR Framing Error

| Value | Description |
|-------|---|
| 1 | Unread byte in RCxREG has a framing error |
| 0 | Unread byte in RCxREG does not have a framing error |

Bit 1 – OERR Overrun Error

| Value | Description |
|-------|--|
| 1 | Overrun error (can be cleared by clearing either SPEN or CREN bit) |

| Value | Description |
|-------|------------------|
| 0 | No overrun error |

Bit 0 – RX9D Ninth bit of Received Data

This can be address/data bit or a parity bit which is determined by user firmware.

29.6.3 BAUDxCON

Name: BAUDxCON
Address: 0xF9E, 0xE9A

Baud Rate Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-------|---|------|-------|---|-----|-------|
| | ABDOVF | RCIDL | | SCKP | BRG16 | | WUE | ABDEN |
| Access | R | R | | R/W | R/W | | R/W | R/W |
| Reset | 0 | 1 | | 0 | 0 | | 0 | 0 |

Bit 7 – ABDOVF Auto-Baud Detect Overflow

| Value | Condition | Description |
|-------|-----------|----------------------------------|
| 1 | SYNC = 0 | Auto-baud timer overflowed |
| 0 | SYNC = 0 | Auto-baud timer did not overflow |
| X | SYNC = 1 | Don't care |

Bit 6 – RCIDL Receive Idle Flag

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 0 | Receiver is Idle |
| 0 | SYNC = 0 | Start bit has been received and the receiver is receiving |
| X | SYNC = 1 | Don't care |

Bit 4 – SCKP Clock/Transmit Polarity Select

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 0 | Idle state for transmit (TX) is a low level (transmit data are inverted) |
| 0 | SYNC = 0 | Idle state for transmit (TX) is a high level (transmit data are non-inverted) |
| 1 | SYNC = 1 | Data are clocked on rising edge of the clock |
| 0 | SYNC = 1 | Data are clocked on falling edge of the clock |

Bit 3 – BRG16 16-bit Baud Rate Generator Select

| Value | Description |
|-------|------------------------------------|
| 1 | 16-bit Baud Rate Generator is used |
| 0 | 8-bit Baud Rate Generator is used |

Bit 1 – WUE Wake-Up Enable

| Value | Condition | Description |
|-------|-----------|---|
| 1 | SYNC = 0 | Receiver is waiting for a falling edge. Upon falling edge, no character will be received and the RCxIF flag will be set. WUE will automatically clear after RCxIF is set. |
| 0 | SYNC = 0 | Receiver is operating normally |
| X | SYNC = 1 | Don't care |

Bit 0 – ABDEN Auto-Baud Detect Enable

| Value | Condition | Description |
|-------|-----------|--|
| 1 | SYNC = 0 | Auto-Baud Detect mode is enabled (clears when auto-baud is complete) |
| 0 | SYNC = 0 | Auto-Baud Detect is complete or mode is disabled |
| X | SYNC = 1 | Don't care |

29.6.4 RCxREG

Name: RCxREG
Address: 0xF98,0xE94

Receive Data Register

| | | | | | | | | |
|--------|------------|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | RCREG[7:0] | | | | | | | |
| Access | R | R | R | R | R | R | R | R |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – RCREG[7:0] Receive data

29.6.5 TXxREG

Name: TXxREG
Address: 0xF99,0xE95

Transmit Data Register

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | TXREG[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – TXREG[7:0] Transmit Data

29.6.6 SPxBRG

Name: SPxBRG
Address: 0xF9A,0xE96

EUSART Baud Rate Generator

| | | | | | | | | |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | SPBRG[15:8] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | SPBRG[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:0 – SPBRG[15:0] Baud Rate Register

- Notes:** The individual bytes in this multibyte register can be accessed with the following register names:
- SPxBRGH: Accesses the high byte SPBRG[15:8]
 - SPxBRGL: Accesses the low byte SPBRG[7:0]

29.7 Register Summary - EUSART

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------|----------|----------|-------------|-------|------|------|-------|------|------|-------|
| 0x00 ... 0x0E93 | Reserved | | | | | | | | | |
| 0x0E94 | RC2REG | 7:0 | RCREG[7:0] | | | | | | | |
| 0x0E95 | TX2REG | 7:0 | TXREG[7:0] | | | | | | | |
| 0x0E96 | SP2BRG | 7:0 | SPBRG[7:0] | | | | | | | |
| | | 15:8 | SPBRG[15:8] | | | | | | | |
| 0x0E98 | RC2STA | 7:0 | SPEN | RX9 | SREN | CREN | ADDEN | FERR | OERR | RX9D |
| 0x0E99 | TX2STA | 7:0 | CSRC | TX9 | TXEN | SYNC | SENDB | BRGH | TRMT | TX9D |
| 0x0E9A | BAUD2CON | 7:0 | ABDOVF | RCIDL | | SCKP | BRG16 | | WUE | ABDEN |
| 0x0E9B ... 0x0F97 | Reserved | | | | | | | | | |
| 0x0F98 | RC1REG | 7:0 | RCREG[7:0] | | | | | | | |
| 0x0F99 | TX1REG | 7:0 | TXREG[7:0] | | | | | | | |
| 0x0F9A | SP1BRG | 7:0 | SPBRG[7:0] | | | | | | | |
| | | 15:8 | SPBRG[15:8] | | | | | | | |
| 0x0F9C | RC1STA | 7:0 | SPEN | RX9 | SREN | CREN | ADDEN | FERR | OERR | RX9D |
| 0x0F9D | TX1STA | 7:0 | CSRC | TX9 | TXEN | SYNC | SENDB | BRGH | TRMT | TX9D |
| 0x0F9E | BAUD1CON | 7:0 | ABDOVF | RCIDL | | SCKP | BRG16 | | WUE | ABDEN |

30. FVR - Fixed Voltage Reference

The Fixed Voltage Reference (FVR) is a stable voltage reference, independent of V_{DD} , with the following selectable output levels:

- 1.024V
- 2.048V
- 4.096V

The output of the FVR can be configured to supply a reference voltage to the following:

- ADC input channel
- ADC positive reference
- Comparator input
- Digital-to-Analog Converter (DAC)

The FVR can be enabled by setting the FVREN bit of the FVRCON register.



Important: Fixed Voltage Reference output cannot exceed V_{DD} .

30.1 Independent Gain Amplifiers

The output of the FVR, which is connected to the ADC, Comparators, and DAC, is routed through two independent programmable gain amplifiers. Each amplifier can be programmed for a gain of 1x, 2x or 4x, to produce the three possible voltage levels.

The ADFVR[1:0] bits of the FVRCON register are used to enable and configure the gain amplifier settings for the reference supplied to the ADC module.

The CDAFVR[1:0] bits of the FVRCON register are used to enable and configure the gain amplifier settings for the reference supplied to the DAC and comparator module.

Related Links

[ADCC - Analog-to-Digital Converter with Computation Module](#)

[CMP - Comparator Module](#)

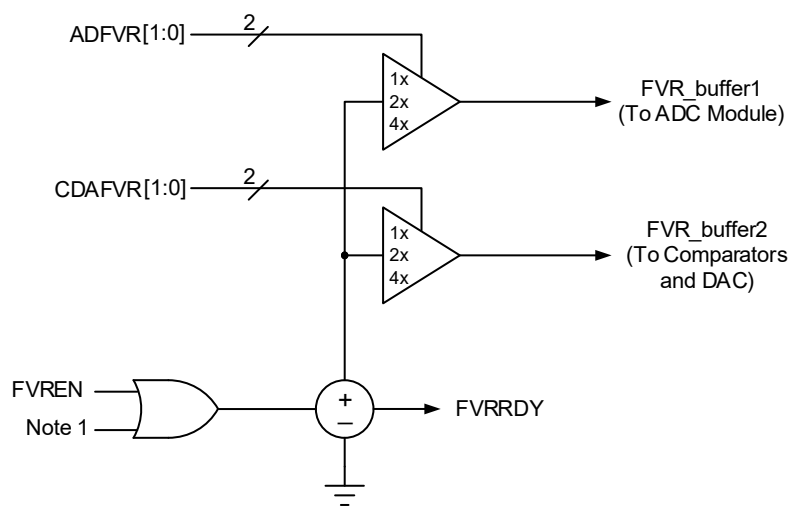
[DAC - 5-Bit Digital-to-Analog Converter](#)

30.2 FVR Stabilization Period

When the Fixed Voltage Reference module is enabled, it requires time for the reference and amplifier circuits to stabilize. Once the circuits stabilize and are ready for use, the FVRRDY bit of the FVRCON register will be set.

Figure 30-1. Voltage Reference Block Diagram

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12/05/2013



Note:

1. Any peripheral requiring the FVR

30.3 Register Summary - FVR

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------------|----------|----------|-------|--------|------|-------|-------------|---|------------|---|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0F2B 0x0F2C | FVRCON | 7:0 | FVREN | FVRRDY | TSEN | TSRNG | CDAFVR[1:0] | | ADFVR[1:0] | |

30.4 Register Definitions: FVR Control

30.4.1 FVRCON

Name: FVRCON
Address: 0xF2C

Fixed Voltage Reference Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|--------|------|-------|-------------|-----|------------|-----|
| | FVREN | FVRRDY | TSEN | TSRNG | CDAFVR[1:0] | | ADFVR[1:0] | |
| Access | R/W | R | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – FVREN Fixed Voltage Reference Enable bit

| Value | Description |
|-------|-------------------------------------|
| 1 | Fixed Voltage Reference is enabled |
| 0 | Fixed Voltage Reference is disabled |

Bit 6 – FVRRDY Fixed Voltage Reference Ready Flag bit ⁽³⁾

| Value | Description |
|-------|--|
| 1 | Fixed Voltage Reference output is ready for use |
| 0 | Fixed Voltage Reference output is not ready or not enabled |

Bit 5 – TSEN Temperature Indicator Enable bit⁽²⁾

| Value | Description |
|-------|-----------------------------------|
| 1 | Temperature Indicator is enabled |
| 0 | Temperature Indicator is disabled |

Bit 4 – TSRNG Temperature Indicator Range Selection bit⁽²⁾

| Value | Description |
|-------|---|
| 1 | $V_{OUT} = V_{DD} - 4 V_T$ (High Range) |
| 0 | $V_{OUT} = V_{DD} - 2 V_T$ (Low Range) |

Bits 3:2 – CDAFVR[1:0] Comparator FVR Buffer Gain Selection bits

| Value | Description |
|-------|---|
| 11 | Comparator FVR Buffer Gain is 4x, (4.096V) ⁽¹⁾ |
| 10 | Comparator FVR Buffer Gain is 2x, (2.048V) ⁽¹⁾ |
| 01 | Comparator FVR Buffer Gain is 1x, (1.024V) |
| 00 | Comparator FVR Buffer is off |

Bits 1:0 – ADFVR[1:0] ADC FVR Buffer Gain Selection bit

| Value | Description |
|-------|--|
| 11 | ADC FVR Buffer Gain is 4x, (4.096V) ⁽¹⁾ |
| 10 | ADC FVR Buffer Gain is 2x, (2.048V) ⁽¹⁾ |
| 01 | ADC FVR Buffer Gain is 1x, (1.024V) |
| 00 | ADC FVR Buffer is off |

Notes:

- Fixed Voltage Reference output cannot exceed V_{DD} .
- See the “**Temperature Indicator Module**” section for additional information.
- FVRRDY is always ‘1’.

Related Links

[Temperature Indicator Module](#)

31. Temperature Indicator Module

This family of devices is equipped with a temperature circuit designed to measure the operating temperature of the silicon die. The circuit's range of operating temperature falls between -40°C and +85°C. The output is a voltage that is proportional to the device temperature. The output of the temperature indicator is internally connected to the device ADC.

The circuit may be used as a temperature threshold detector or a more accurate temperature indicator, depending on the level of calibration performed. A one-point calibration allows the circuit to indicate a temperature closely surrounding that point. A two-point calibration allows the circuit to sense the entire range of temperature more accurately. Refer to Application Note AN1333, *"Use and Calibration of the Internal Temperature Indicator"* (DS00001333) for more details regarding the calibration process.

31.1 Circuit Operation

Figure 31-1 shows a simplified block diagram of the temperature circuit. The proportional voltage output is achieved by measuring the forward voltage drop across multiple silicon junctions.

The following equation describes the output characteristics of the temperature indicator.

Equation 31-1. V_{OUT} Ranges

High Range: $V_{OUT} = V_{DD} - 4V_T$

Low Range: $V_{OUT} = V_{DD} - 2V_T$

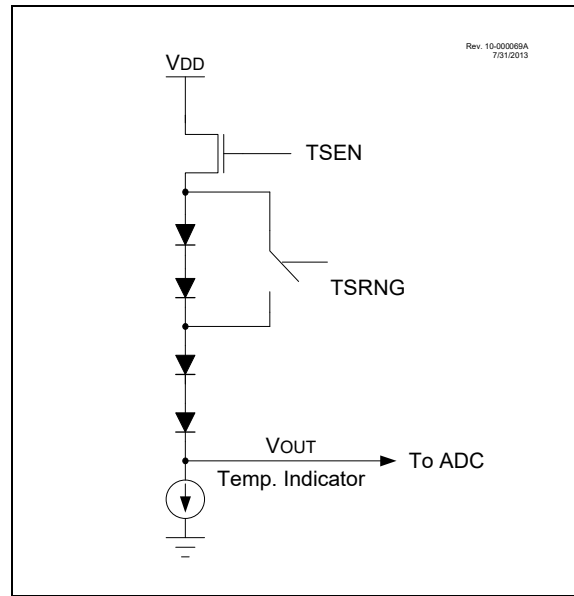
The temperature sense circuit is integrated with the Fixed Voltage Reference (FVR) module. See **"FVR - Fixed Voltage Reference"** chapter for more information.

The circuit is enabled by setting the TSEN bit of the FVRCON register. When disabled, the circuit draws no current.

The circuit operates in either high or low range. The high range, selected by setting the TSRNG bit of the FVRCON register, provides a wider output voltage. This provides more resolution over the temperature range, but may be less consistent from part to part. This range requires a higher bias voltage to operate and thus, a higher V_{DD} is needed.

The low range is selected by clearing the TSRNG bit of the FVRCON register. The low range generates a lower voltage drop and thus, a lower bias voltage is needed to operate the circuit. The low range is provided for low voltage operation.

Figure 31-1. Temperature Circuit Diagram



Related Links

[FVR - Fixed Voltage Reference](#)

31.2 Minimum Operating V_{DD}

When the temperature circuit is operated in low range, the device may be operated at any operating voltage that is within specifications.

When the temperature circuit is operated in high range, the device operating voltage, V_{DD} , must be high enough to ensure that the temperature circuit is correctly biased.

[Table 31-1](#) shows the recommended minimum V_{DD} vs. range setting.

Table 31-1. Recommended V_{DD} vs. Range

| Min. V_{DD} , TSRNG = 1 | Min. V_{DD} , TSRNG = 0 |
|---------------------------|---------------------------|
| 3.6V | 1.8V |

31.3 Temperature Output

The output of the circuit is measured using the internal Analog-to-Digital Converter. A channel is reserved for the temperature circuit output. Refer to the **"Analog-to-Digital Converter with Computation (ADCC) Module"** chapter for detailed information.

Related Links

[ADCC - Analog-to-Digital Converter with Computation Module](#)

31.4 ADC Acquisition Time

To ensure accurate temperature measurements, the user must wait at least 200 μ s after the ADC input multiplexer is connected to the temperature indicator output before the conversion is performed. In addition, the user must wait 200 μ s between consecutive conversions of the temperature indicator output.

32. DAC - 5-Bit Digital-to-Analog Converter

The Digital-to-Analog Converter supplies a variable voltage reference, ratiometric with the input source, with 32 selectable output levels.

The positive input source ($V_{SOURCE+}$) of the DAC can be connected to:

- FVR Buffer
- External V_{REF+} pin
- V_{DD} supply voltage

The negative input source ($V_{SOURCE-}$) of the DAC can be connected to:

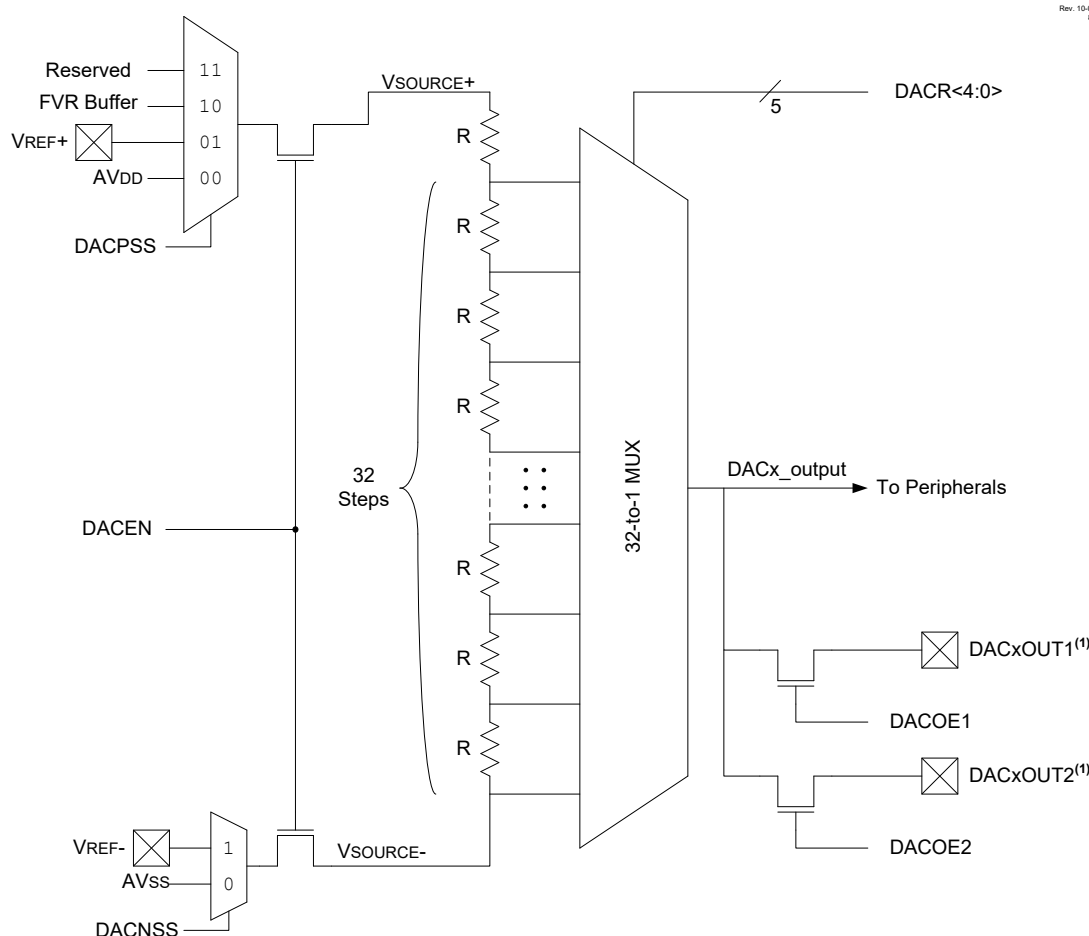
- External V_{REF-} pin
- V_{SS}

The output of the DAC (DACx_output) can be selected as a reference voltage to the following:

- Comparator positive input
- ADC input channel
- DACxOUT1 pin
- DACxOUT2 pin

The Digital-to-Analog Converter (DAC) can be enabled by setting the [EN](#) bit.

Figure 32-1. Digital-to-Analog Converter Block Diagram



32.1 Output Voltage Selection

The DAC has 32 voltage level ranges. The 32 levels are set with the [DAC1R](#) bits.

The DAC output voltage can be determined by using the following equation.

Equation 32-1. DAC Output Voltage

$$DACx_{output} = \left(\left(V_{SOURCE+} - V_{SOURCE-} \right) \times \frac{DACR[4:0]}{32} \right) + V_{SOURCE-}$$

Note: See the [DAC1CON0](#) register for the available $V_{SOURCE+}$ and $V_{SOURCE-}$ selections.

32.2 Ratiometric Output Level

The DAC output value is derived using a resistor ladder with each end of the ladder tied to a positive and negative voltage reference input source. If the voltage of either input source fluctuates, a similar fluctuation will result in the DAC output value.

The value of the individual resistors within the ladder can be found in the “5-Bit DAC Specifications” table from the “**Electrical Specifications**” chapter.

Related Links

[5-Bit DAC Specifications](#)

32.3 DAC Voltage Reference Output

The unbuffered DAC voltage can be output to the DACxOUTn pin(s) by setting the respective **OEn** bit(s). Selecting the DAC reference voltage for output on either DACxOUTn pin automatically overrides the digital output buffer, the weak pull-up and digital input threshold detector functions of that pin.

Reading the DACxOUTn pin when it has been configured for DAC reference voltage output will always return a '0'.



Important: The unbuffered DAC output (DACxOUTn) is not intended to drive an external load.

32.4 Operation During Sleep

The DAC continues to function during Sleep. When the device wakes up from Sleep through an interrupt or a Watchdog Timer time-out, the contents of the DAC1CON0 register are not affected.

32.5 Effects of a Reset

A device Reset affects the following:

- DACx is disabled
- DACx output voltage is removed from the DACxOUTn pin(s)
- The **DAC1R** range select bits are cleared

32.6 Register Summary - DAC Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|--------------------------|----------|----|---|-----|------------|----------|---|---|-----|
| 0x00 ... 0x0F2D | Reserved | | | | | | | | | |
| 0x0F2E | DAC1CON0 | 7:0 | EN | | OE1 | OE2 | PSS[1:0] | | | NSS |
| 0x0F2F | DAC1CON1 | 7:0 | | | | DAC1R[4:0] | | | | |

32.7 Register Definitions: DAC Control

[Related Links](#)

[Long Bit Names](#)

32.7.1 DAC1CON0**Name:** DAC1CON0**Address:** 0xF2E

DAC Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|-----|----------|-----|---|-----|
| | EN | | OE1 | OE2 | PSS[1:0] | | | NSS |
| Access | R/W | | R/W | R/W | R/W | R/W | | R/W |
| Reset | 0 | | 0 | 0 | 0 | 0 | | 0 |

Bit 7 – EN DAC Enable bit

| Value | Description |
|-------|-----------------|
| 1 | DAC is enabled |
| 0 | DAC is disabled |

Bit 5 – OE1 DAC Voltage Output Enable bit

| Value | Description |
|-------|---|
| 1 | DAC voltage level is output on the DAC1OUT1 pin |
| 0 | DAC voltage level is disconnected from the DAC1OUT1 pin |

Bit 4 – OE2 DAC Voltage Output Enable bit

| Value | Description |
|-------|---|
| 1 | DAC voltage level is output on the DAC1OUT2 pin |
| 0 | DAC voltage level is disconnected from the DAC1OUT2 pin |

Bits 3:2 – PSS[1:0] DAC Positive Source Select bit

| Value | Description |
|-------|-------------------|
| 11 | Reserved |
| 10 | FVR buffer |
| 01 | V _{REF+} |
| 00 | AV _{DD} |

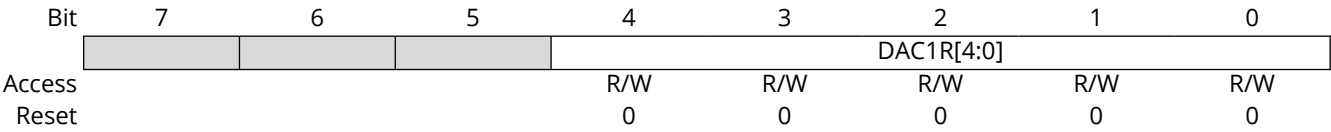
Bit 0 – NSS DAC Negative Source Select bit

| Value | Description |
|-------|-------------------|
| 1 | V _{REF-} |
| 0 | AV _{SS} |

32.7.2 DAC1CON1

Name: DAC1CON1
Address: 0xF2F

DAC Data Register



Bits 4:0 – DAC1R[4:0] Data Input Register for DAC bits

33. ADCC - Analog-to-Digital Converter with Computation Module

The Analog-to-Digital Converter with Computation (ADCC) allows conversion of an analog input signal to a 10-bit binary representation of that signal. This device uses analog inputs that are multiplexed into a single Sample-and-Hold circuit. The output of the Sample-and-Hold is connected to the input of the converter. The converter generates a 10-bit binary result via successive approximation and stores the conversion result into the ADC result registers ([ADRES](#)).

Additionally, the following features are provided within the ADC module:

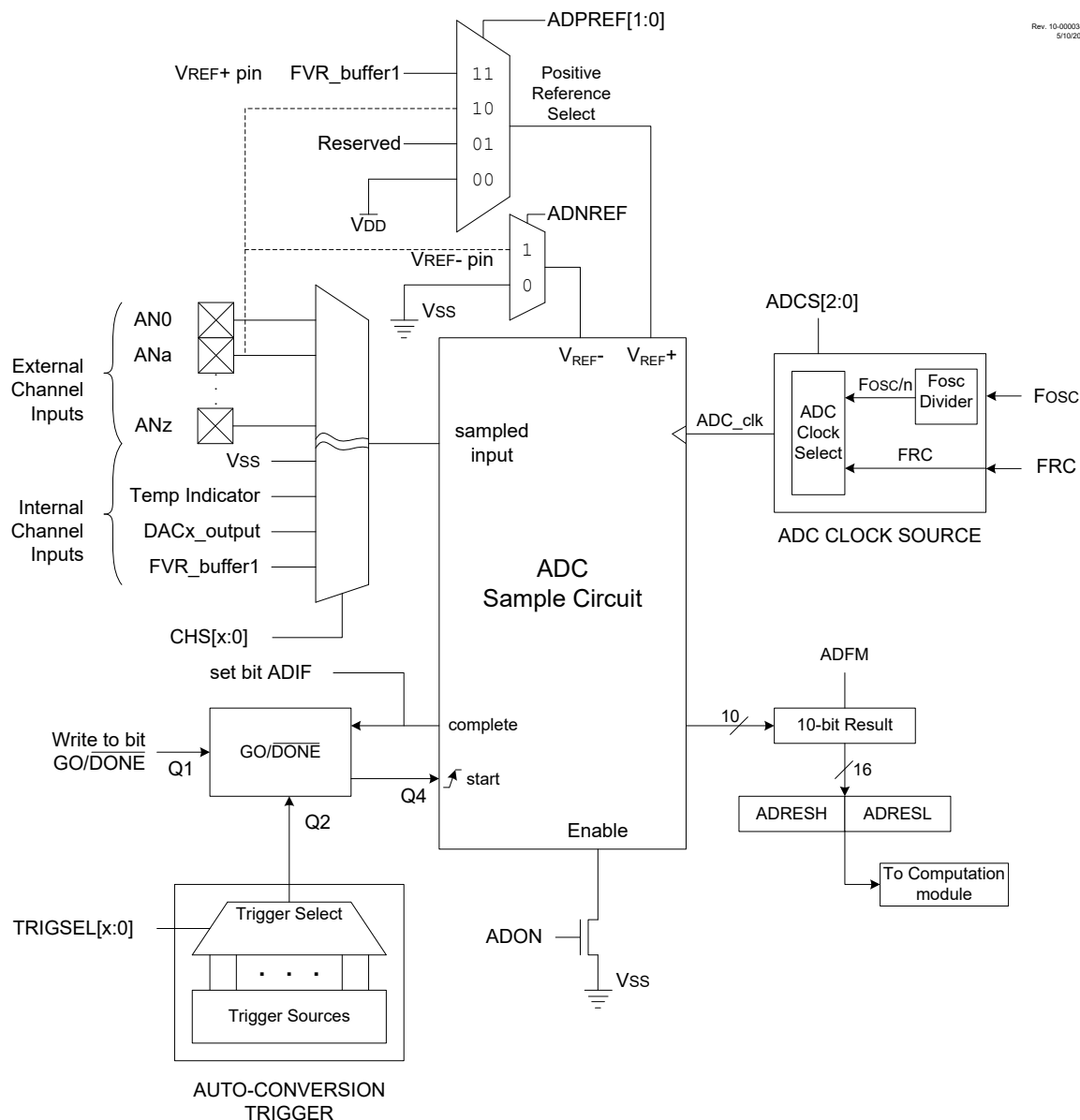
- 8-bit Acquisition Timer
- Hardware Capacitive Voltage Divider (CVD) support:
 - 8-bit precharge timer
 - Adjustable Sample-and-Hold capacitor array
 - Guard ring digital output drive
- Automatic Repeat and Sequencing:
 - Automated double sample conversion for CVD
 - Two sets of Result registers (Result and Previous Result)
 - Auto-conversion trigger
 - Internal retrigger
- Computation Features:
 - Averaging and low-pass filter functions
 - Reference comparison
 - 2-level threshold comparison
 - Selectable interrupts

[Figure 33-1](#) shows the block diagram of the ADC.

The ADC voltage reference is software selectable to be either internally generated or externally supplied.

The ADC can generate an interrupt upon completion of a conversion and upon threshold comparison. These interrupts can be used to wake up the device from Sleep.

Figure 33-1. ADCC Block Diagram



33.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- Port Configuration
- Channel Selection
- ADC Voltage Reference Selection
- ADC Conversion Clock Source
- Interrupt Control
- Result Formatting
- Conversion Trigger Selection
- ADC Acquisition Time

- ADC Precharge Time
- Additional Sample-and-Hold Capacitor
- Single/Double Sample Conversion
- Guard Ring Outputs

33.1.1 Port Configuration

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin may be configured for analog by setting the associated TRIS and ANSEL bits. Refer to the “**I/O Ports**” section for more information.



Important: Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

Related Links

[I/O Ports](#)

33.1.2 Channel Selection

The [ADPCH](#) register determines which channel is connected to the Sample-and-Hold circuit.

There are several channel selections available as shown in the following selection table:

Table 33-1. ADC Positive Input Channel Selections

| ADPCH | ADC Positive Channel Input |
|---------------|--|
| 111111 | Fixed Voltage Reference (FVR) ⁽²⁾ |
| 111110 | DAC1 output ⁽¹⁾ |
| 111101 | Temperature Indicator ⁽³⁾ |
| 111100 | AV _{SS} (Analog Ground) |
| 100011–111011 | Reserved. No channel connected. |
| 100010 | RE2/ANE2 ⁽¹⁾ |
| 100001 | RE1/ANE1 ⁽¹⁾ |
| 100000 | RE0/ANE0 ⁽¹⁾ |
| 011111 | RD7/AND7 ⁽¹⁾ |
| 011110 | RD6/AND6 ⁽¹⁾ |
| 011101 | RD5/AND5 ⁽¹⁾ |
| 011100 | RD4/AND4 ⁽¹⁾ |
| 011011 | RD3/AND3 ⁽¹⁾ |
| 011010 | RD2/AND2 ⁽¹⁾ |
| 011001 | RD1/AND1 ⁽¹⁾ |
| 011000 | RD0/AND0 ⁽¹⁾ |
| 010111 | RC7/ANC7 |
| 010110 | RC6/ANC6 |
| 010101 | RC5/ANC5 |
| 010100 | RC4/ANC4 |
| 010011 | RC3/ANC3 |
| 010010 | RC2/ANC2 |
| 010001 | RC1/ANC1 |
| 010000 | RC0/ANC0 |
| 001111 | RB7/ANB7 |

.....continued

| ADPCH | ADC Positive Channel Input |
|--------|----------------------------|
| 001110 | RB6/ANB6 |
| 001101 | RB5/ANB5 |
| 001100 | RB4/ANB4 |
| 001011 | RB3/ANB3 |
| 001010 | RB2/ANB2 |
| 001001 | RB1/ANB1 |
| 001000 | RB0/ANB0 |
| 000111 | RA7/ANA7 |
| 000110 | RA6/ANA6 |
| 000101 | RA5/ANA5 |
| 000100 | RA4/ANA4 |
| 000011 | RA3/ANA3 |
| 000010 | RA2/ANA2 |
| 000001 | RA1/ANA1 |
| 000000 | RA0/ANA0 |

Note:

1. 40/44-pin devices only.

When changing channels, a delay is required before starting the next conversion.

Refer to the “[ADC Operation](#)” section for more information.



Important: It is recommended to discharge the Sample-and-Hold capacitor when switching between ADC channels by starting a conversion on a channel connected to V_{SS} and terminating the conversion after the acquisition time has elapsed. If the ADC does not have a dedicated V_{SS} input channel, the V_{SS} selection (DAC1R[4:0] = b'00000') through the DAC output channel can be used. If the DAC is in use, a free input channel can be connected to V_{SS} , and can be used in place of the DAC.

33.1.3 ADC Voltage Reference

The [ADPREF](#) bits provide control of the positive voltage reference. The positive voltage reference can be:

- V_{REF+} pin
- V_{DD}
- FVR 1.024V
- FVR 2.048V
- FVR 4.096V

The [ADNREF](#) bit provides control of the negative voltage reference. The negative voltage reference can be:

- V_{REF-} pin
- V_{SS}

33.1.4 Conversion Clock

The conversion clock source is software selected with the [ADCS](#) bit. When $ADCS = 1$ the ADC clock source is an internal fixed-frequency clock referred to as FRC. When $ADCS = 0$ the ADC clock

frequencies are derived from F_{OSC} . The **ADCLK** register selects one of 64 possible clock options from $F_{OSC}/2$ to $F_{OSC}/128$.

The time to complete one bit conversion is defined as the T_{AD} . One full 10-bit conversion requires 11.5 T_{AD} periods as shown in [Figure 33-2](#).

For correct conversion, the appropriate T_{AD} specification must be met. Refer to the "ADC Timing Specifications" for more information. The "ADC Clock Period" table below gives examples of appropriate ADC clock selections.



Important:

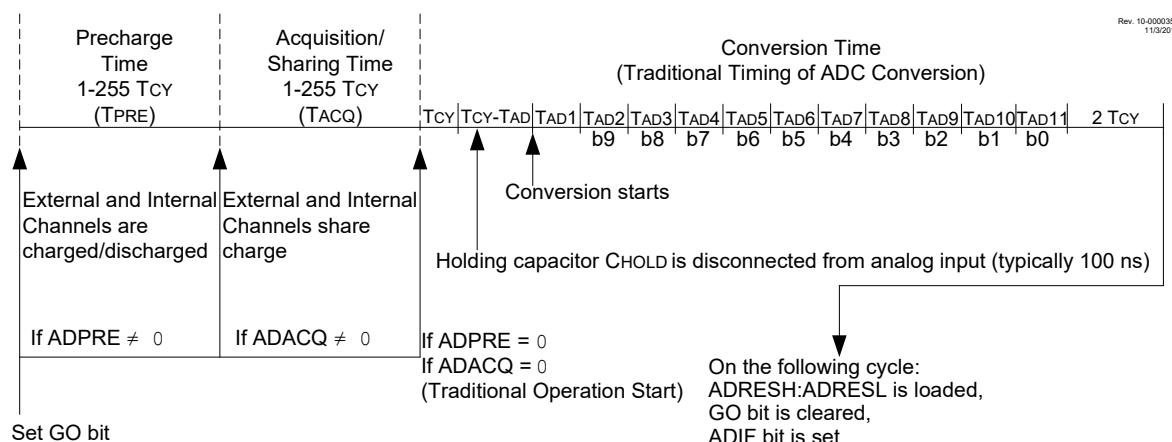
1. Except for the FRC clock source, any changes in the system clock frequency will change the ADC clock frequency, which may adversely affect the ADC result.
2. The internal control logic of the ADC runs off of the clock selected by **ADCS**. When the **ADCS** is set to '1' (ADC runs on FRC), there may be unexpected delays in operation when setting ADC control bits.

Table 33-2. ADC Clock Period (T_{AD}) Vs. Device Operating Frequencies^(1,4)

| ADC Clock Period (T_{AD}) | | | Device Frequency (F_{OSC}) | | | | | | |
|-------------------------------|------|--------|--------------------------------|-------------------------|-----------------------|-----------------------|-----------------------------|-----------------------------|------------------------------|
| ADC Clock Source | ADCS | ADCLK | 64 MHz | 32 MHz | 20 MHz | 16 MHz | 8 MHz | 4 MHz | 1 MHz |
| $F_{OSC}/2$ | 0 | 000000 | 31.25 ns ⁽²⁾ | 62.5 ns ⁽²⁾ | 100 ns ⁽²⁾ | 125 ns ⁽²⁾ | 250 ns ⁽²⁾ | 500 ns ⁽²⁾ | 2.0 μ s |
| $F_{OSC}/4$ | 0 | 000001 | 62.5 ns ⁽²⁾ | 125 ns ⁽²⁾ | 200 ns ⁽²⁾ | 250 ns ⁽²⁾ | 500 ns ⁽²⁾ | 1.0 μ s | 4.0 μ s |
| $F_{OSC}/6$ | 0 | 000010 | 125 ns ⁽²⁾ | 187.5 ns ⁽²⁾ | 300 ns ⁽²⁾ | 375 ns ⁽²⁾ | 750 ns ⁽²⁾ | 1.5 μ s | 6.0 μ s |
| $F_{OSC}/8$ | 0 | 000011 | 187.5 ns ⁽²⁾ | 250 ns ⁽²⁾ | 400 ns ⁽²⁾ | 500 ns ⁽²⁾ | 1.0 μ s | 2.0 μ s | 8.0 μ s ⁽³⁾ |
| ... | ... | ... | ... | ... | ... | ... | ... | ... | ... |
| $F_{OSC}/16$ | 0 | 000111 | 250 ns ⁽²⁾ | 500 ns ⁽²⁾ | 800 ns ⁽²⁾ | 1.0 μ s | 2.0 μ s | 4.0 μ s | 16.0 μ s ⁽³⁾ |
| ... | ... | ... | ... | ... | ... | ... | ... | ... | ... |
| $F_{OSC}/128$ | 0 | 111111 | 2.0 μ s | 4.0 μ s | 6.4 μ s | 8.0 μ s | 16.0 μ s ⁽³⁾ | 32.0 μ s ⁽²⁾ | 128.0 μ s ⁽²⁾ |
| FRC | 1 | – | 1.0-6.0 μ s | 1.0-6.0 μ s | 1.0-6.0 μ s | 1.0-6.0 μ s | 1.0-6.0 μ s | 1.0-6.0 μ s | 1.0-6.0 μ s |

Notes:

1. See T_{AD} parameter in the "Electrical Specifications" section for FRC source typical T_{AD} value.
2. These values violate the required T_{AD} time.
3. Outside the recommended T_{AD} time.
4. The ADC clock period (T_{AD}) and total ADC conversion time can be minimized when the ADC clock is derived from the system clock F_{OSC} . However, the FRC oscillator source must be used when conversions are to be performed with the device in Sleep mode.

Figure 33-2. Analog-to-Digital Conversion T_{AD} Cycles

Related Links

[Analog-to-Digital Converter \(ADC\) Conversion Timing Specifications](#)

33.1.5 Interrupts

The ADC module allows for the ability to generate an interrupt upon completion of an Analog-to-Digital Conversion. The ADC Interrupt Flag is the ADIF bit in the PIR1 register. The ADC Interrupt Enable is the ADIE bit in the PIE1 register. The ADIF bit must be cleared in software.



Important:

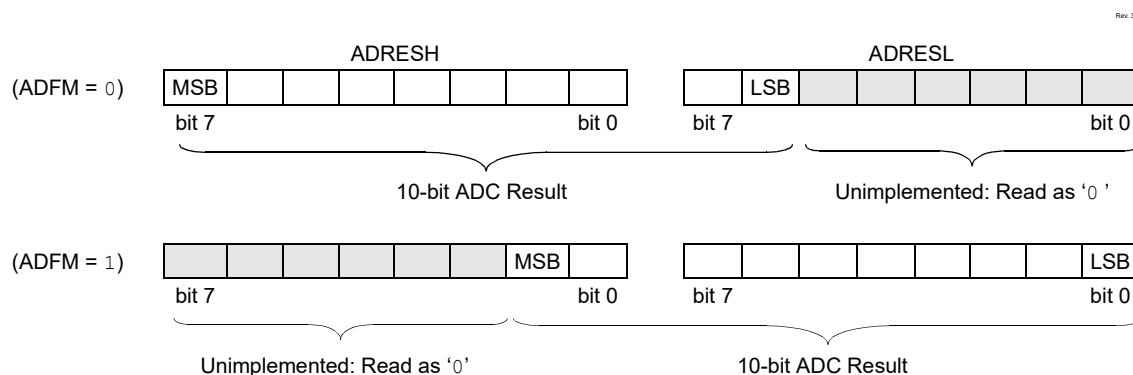
1. The ADIF bit is set at the completion of every conversion, regardless of whether or not the ADC interrupt is enabled.
2. The ADC operates during Sleep only when the FRC oscillator is selected.

This interrupt can be generated while the device is operating or while in Sleep. If the device is in Sleep, the interrupt will wake up the device. Upon waking from Sleep, the next instruction following the `SLEEP` instruction is always executed. If the user is attempting to wake up from Sleep and resume in-line code execution, the ADIE bit and the PEIE bit of the INTCON register must both be set, and the GIE bit of the INTCON register must be cleared. If these bits are set, the execution will switch to the Interrupt Service Routine.

33.1.6 Result Formatting

The 10-bit ADC conversion result can be supplied in two formats, left justified or right justified. The **ADFM** bit controls the output format as shown in the following figure.

Figure 33-3. 10-Bit ADC Conversion Result Format



33.2 ADC Operation

33.2.1 Starting a Conversion

To enable the ADC module, the **ADON** must be set to a '1'. A conversion may be started by any of the following:

- Software setting the **ADGO** bit to '1'
- An external trigger (source selected by **ADACT**)
- A continuous-mode retrigger (see section **Continuous Sampling Mode**)

➔ Important: The **ADGO** bit must not be set in the same instruction that turns on the ADC. Refer to **ADC Conversion Procedure (Basic Mode)**.

33.2.2 Completion of a Conversion

When any individual conversion is complete, the value already in **ADRES** is written into **ADPREV** (if **ADPSIS** = 0) and the new conversion results appear in **ADRES**. When the conversion completes, the ADC module will:

- Clear the **ADGO** bit (unless the **ADCONT** bit is set)
- Set the **ADIF** Interrupt Flag bit
- Set the **ADMATH** bit
- Update **ADACC**

After every conversion when **ADDSEN** = 0, or after every other conversion when **ADDSEN** = 1, the following events occur:

- **ADERR** is calculated
- **ADTIF** interrupt is set if **ADERR** calculation meets threshold comparison

➔ Important: Filter and threshold computations occur after the conversion itself is complete. As such, interrupt handlers responding to **ADIF** will check **ADTIF** before reading filter and threshold results.

33.2.3 Terminating a Conversion

If a conversion must be terminated before completion, the ADGO bit can be cleared in software. The partial conversion results will be discarded and the ADRES registers will retain the value from the previous conversion.



Important: A device Reset forces all registers to their Reset state. Thus, the ADC module is turned off and any pending conversion is terminated.

33.2.4 ADC Operation During Sleep

The ADC module can operate during Sleep. This requires the ADC clock source to be set to the FRC option. When the FRC oscillator source is selected, the ADC waits one additional instruction before starting the conversion. This allows the `SLEEP` instruction to be executed, which can reduce system noise during the conversion. If the ADC interrupt is enabled, the device will wake up from Sleep when the conversion completes. If the ADC interrupt is disabled, the ADC module is turned off after the conversion completes, although the ADON bit remains set.

33.2.5 External Trigger During Sleep

If the external trigger is received during Sleep while the ADC clock source is set to the FRC, the ADC module will perform the conversion and set the ADIF bit upon completion.

If an external trigger is received when the ADC clock source is something other than FRC, the trigger will be recorded, but the conversion will not begin until the device exits Sleep.

33.2.6 Auto-Conversion Trigger

The auto-conversion trigger allows periodic ADC measurements without software intervention. When a rising edge of the selected source occurs, the ADGO bit is set by hardware.

The auto-conversion trigger source is selected with the `ADACT` bits.

Using the auto-conversion trigger does not assure proper ADC timing. It is the user's responsibility to ensure that the ADC timing requirements are met. See the following table for auto-conversion sources.

Table 33-3. ADC Auto-Conversion Trigger Sources

| ADACT | Auto-conversion Trigger Source |
|----------------|------------------------------------|
| 11111 | Software write to ADPCH |
| 11110 | Reserved, do not use |
| 11101 | Software read of ADRESH |
| 11100 | Software read of ADERRH |
| 11000 to 11011 | Reserved, do not use |
| 10111 | CLC8_out |
| 10110 | CLC7_out |
| 10101 | CLC6_out |
| 10100 | CLC5_out |
| 10011 | CLC4_out |
| 10010 | CLC3_out |
| 10001 | CLC2_out |
| 10000 | CLC1_out |
| 01111 | Interrupt-on-Change Interrupt Flag |
| 01110 | C2_out |

.....continued

| ADACT | Auto-conversion Trigger Source |
|-------|--------------------------------|
| 01101 | C1_out |
| 01100 | PWM4_out |
| 01011 | PWM3_out |
| 01010 | CCP2_trigger |
| 01001 | CCP1_trigger |
| 01000 | TMR6_postscaled |
| 00111 | TMR5_overflow |
| 00110 | TMR4_postscaled |
| 00101 | TMR3_overflow |
| 00100 | TMR2_postscaled |
| 00011 | TMR1_overflow |
| 00010 | TMR0_overflow |
| 00001 | Pin selected by ADACPPS |
| 00000 | External Trigger Disabled |

33.2.7 ADC Conversion Procedure (Basic Mode)

This is an example procedure for using the ADC to perform an Analog-to-Digital Conversion:

- Configure the Port:
 - Disable the pin output driver (Refer to the TRISx register)
 - Configure the pin as analog (Refer to the ANSELx register)
- Configure the ADC module:
 - Select the ADC conversion clock
 - Configure the voltage reference
 - Select the ADC input channel (precharge+acquisition)
 - Turn on ADC module
- Configure the ADC interrupt (optional):
 - Clear the ADC interrupt flag
 - Enable the ADC interrupt
 - Enable the peripheral interrupt (PEIE bit)
 - Enable the global interrupt (GIE bit)⁽¹⁾
- If ADACQ = 0, software must wait the required acquisition time⁽²⁾.
- Start the conversion by setting the ADGO bit.
- Wait for the ADC conversion to complete by one of the following:
 - Polling the ADGO bit
 - Waiting for the ADC interrupt (interrupts enabled)
- Read the ADC Result.
- Clear the ADC interrupt flag (required if interrupt is enabled).



Important:

- With global interrupts disabled, the device will wake from Sleep but will not enter an Interrupt Service Routine.
- Refer to [ADC Acquisition Requirements](#).

Example 33-1. ADC Conversion (assembly)

```
; This code block configures the ADC for polling, Vdd and Vss references,
; FRC oscillator, and AN0 input.
; Conversion start & polling for completion are included.
```

```
BANKSEL ADCON1
clrf ADCON1 ;
clrf ADCON2 ; Legacy mode, no filtering, ADRES->ADPREV
clrf ADCON3 ; no math functions
clrf ADREF ; Vref = Vdd & Vss
clrf ADPCH ; select RA0/AN0
clrf ADACQ ; software controlled acquisition time
clrf ADCAP ; default S&H capacitance
clrf ADRPT ; no repeat measurements
clrf ADOACT ; auto-conversion disabled
movlw B'10010100' ; ADC On, right-justified, FRC clock
movwf ADCON0
BANKSEL TRISA ;
bsf TRISA,0 ; Set RA0 to input
BANKSEL ANSEL ;
bsf ANSEL,0 ; Set RA0 to analog
call SampleTime ; Acquisition delay
BANKSEL ADCON0
bsf ADCON0,ADGO ; Start conversion
btfsc ADCON0,ADGO ; Is conversion done?
goto $-2 ; No, test again
BANKSEL ADRESH ;
movf ADRESH,W ; Read upper 2 bits
movwf RESULTHI ; store in GPR space
movf ADRESL,W ; Read lower 8 bits
movwf RESULTLO ; Store in GPR space
```

Example 33-2. ADC Conversion (C)

```
/*This code block configures the ADC
for polling, VDD and VSS references, ADCRC
oscillator and AN0 input.
Conversion start & polling for completion
are included.
*/
void main() {
    //System Initialize
    initializeSystem();

    //Setup ADC
    ADCON0bits.FM = 1; //right justify
    ADCON0bits.CS = 1; //FRC Clock
    ADPCH = 0x00; //RA0 is Analog channel
    TRISAbits.TRISA0 = 1; //Set RA0 to input
    ANSELbits.ANSELA0 = 1; //Set RA0 to analog
    ADCON0bits.ON = 1; //Turn ADC On

    while (1) {
        ADCON0bits.GO = 1; //Start conversion
        while (ADCON0bits.GO); //Wait for conversion done
        resultHigh = ADRESH; //Read result
        resultLow = ADRESL; //Read result
    }
}
```

33.3 ADC Acquisition Requirements

For the ADC to meet its specified accuracy, the charge holding capacitor (C_{HOLD}) must be allowed to fully charge to the input channel voltage level. The analog input model is shown in [Figure 33-4](#). The source impedance (R_S) and the internal sampling switch (R_{SS}) impedance directly affect the time required to charge the capacitor C_{HOLD} . The sampling switch (R_{SS}) impedance varies over the device voltage (V_{DD}), refer to [Figure 33-4](#). The maximum recommended impedance for analog sources is

10 kΩ. As the source impedance is decreased, the acquisition time may be decreased. After the analog input channel is selected (or changed), an ADC acquisition must be completed before the conversion can be started. To calculate the minimum acquisition time, Equation 33-1 may be used. This equation assumes that 1/2 LSB error is used (1024 steps for the ADC). The 1/2 LSB error is the maximum error allowed for the ADC to meet its specified resolution.

Equation 33-1. Acquisition Time Example

Assumptions: Temperature = 50°C; External impedance = 10kΩ; V_{DD} = 5.0V

T_{ACQ} = Amplifier Settling Time + Hold Capacitor Charging Time + Temperature Coefficient

$$T_{ACQ} = T_{AMP} + T_C + T_{COFF}$$

$$T_{ACQ} = 2\mu s + T_C + [(Temperature - 25^\circ C) (0.05\mu s/^\circ C)]$$

The value for T_C can be approximated with the following equations:

$$V_{APPLIED} \left(1 - \frac{1}{(2^{n+1}) - 1} \right) = V_{CHOLD}; [1] V_{CHOLD} \text{ charged to within } \frac{1}{2} \text{ lsb}$$

$$V_{APPLIED} \left(1 - e^{-\frac{T_C}{RC}} \right) = V_{CHOLD}; [2] V_{CHOLD} \text{ charge response to } V_{APPLIED}$$

$$V_{APPLIED} \left(1 - e^{-\frac{T_C}{RC}} \right) = V_{APPLIED} \left(1 - \frac{1}{(2^{n+1}) - 1} \right); \text{Combining [1] and [2]}$$

Note: Where n = ADC resolution in bits

Solving for T_C:

$$T_C = -C_{HOLD}(R_{IC} + R_{SS} + R_S) \ln (1/2047)$$

$$T_C = -10pF(1k\Omega + 7k\Omega + 10k\Omega) \ln (0.0004885)$$

$$T_C = 1.37\mu s$$

Therefore:

$$T_{ACQ} = 2\mu s + 892ns + [(50^\circ C - 25^\circ C) (0.05\mu s/^\circ C)]$$

$$T_{ACQ} = 4.62 \mu s$$

Notes:

1. The reference voltage (V_{REF}) has no effect on the equation, since it cancels itself out.
2. The charge holding capacitor (C_{HOLD}) is not discharged after each conversion.
3. The maximum recommended impedance for analog sources is 10 kΩ. This is required to meet the pin leakage specification.

Figure 33-4. Analog Input Model

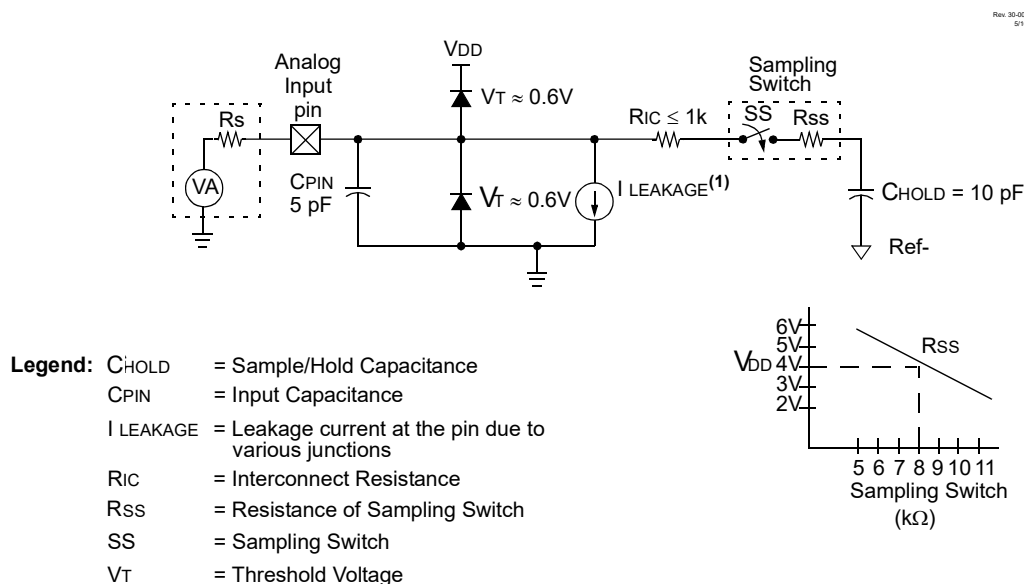
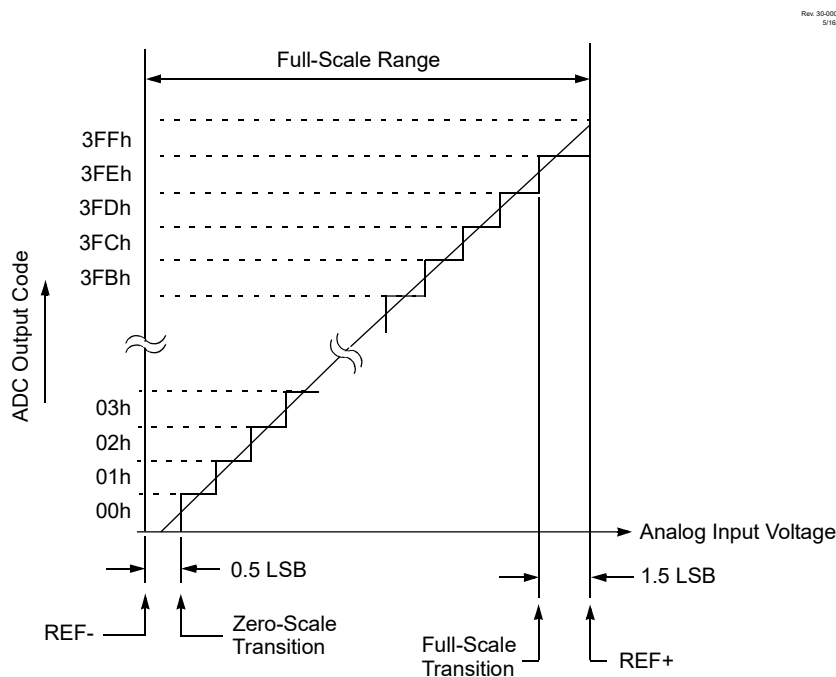


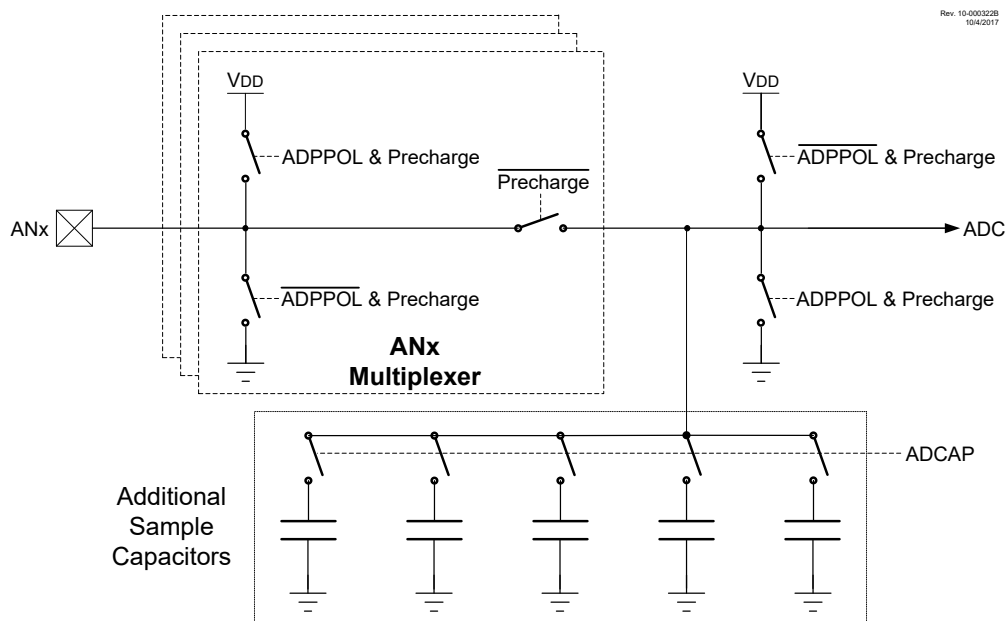
Figure 33-5. ADC Transfer Function



33.4 Capacitive Voltage Divider (CVD) Features

The ADC module contains several features that allow the user to perform a relative capacitance measurement on any ADC channel using the internal ADC Sample-and-Hold capacitance as a reference. This relative capacitance measurement can be used to implement capacitive touch or proximity sensing applications. The following figure shows the basic block diagram of the CVD portion of the ADC module.

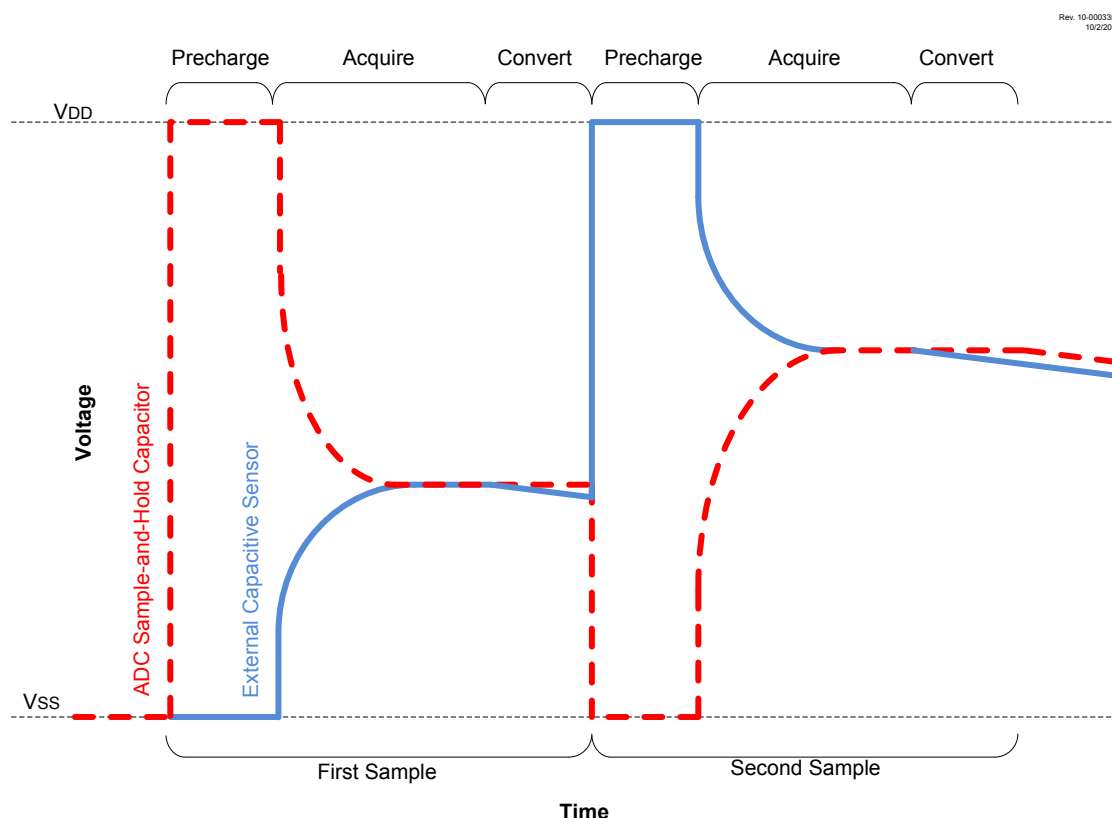
Figure 33-6. Hardware Capacitive Voltage Divider Block Diagram



33.4.1 CVD Operation

A CVD operation begins with the ADC's internal Sample-and-Hold capacitor (C_{HOLD}) being disconnected from the path which connects it to the external capacitive sensor node. While disconnected, C_{HOLD} is precharged to V_{DD} or V_{SS} the sensor node is also charged to V_{SS} or V_{DD} , respectively to the level opposite that of C_{HOLD} . When the precharge phase is complete, the $V_{\text{DD}}/V_{\text{SS}}$ bias paths for the two nodes are shut off and the paths between C_{HOLD} and the external sensor node is reconnected, at which time the acquisition phase of the CVD operation begins. During acquisition, a capacitive voltage divider is formed between the precharged C_{HOLD} and sensor nodes, which results in a final voltage level setting on C_{HOLD} which is determined by the capacitances and precharge levels of the two nodes. After acquisition, the ADC converts the voltage level on C_{HOLD} . This process is then repeated with the selected precharge levels inverted for both the C_{HOLD} and the sensor nodes. The waveform for two CVD measurements, which is known as differential CVD measurement, is shown in the following figure.

Figure 33-7. Differential CVD Measurement Waveform



33.4.2 Precharge Control

The Precharge stage is an optional period of time that brings the external channel and internal Sample-and-Hold capacitor to known voltage levels. Precharge is enabled by writing a nonzero value to the ADPRE register. This stage is initiated when an ADC conversion begins, either from setting the ADGO bit, a Special Event Trigger, or a conversion restart from the computation functionality. If the ADPRE register is cleared when an ADC conversion begins, this stage is skipped.

During the precharge time, C_{HOLD} is disconnected from the outer portion of the sample path that leads to the external capacitive sensor and is connected to either V_{DD} or V_{SS} , depending on the value of the ADPPOL bit. At the same time, the port pin logic of the selected analog channel is overridden to drive a digital high or low out, in order to precharge the outer portion of the ADC's sample path, which includes the external sensor. The output polarity of this override is also determined by the ADPPOL bit such that the external sensor cap is charged opposite that of the internal C_{HOLD} cap. The amount of time that this charging needs is controlled by the ADPRE register.



Important: The external charging overrides the TRIS setting of the respective I/O pin. If there is a device attached to this pin, precharge must not be used.

33.4.3 Acquisition Control for CVD (ADPRE > 0)

The Acquisition stage allows time for the voltage on the internal Sample-and-Hold capacitor to charge or discharge from the selected analog channel. This acquisition time is controlled by the

ADACQ register. When $ADPRE = 0$, acquisition starts at the beginning of conversion. When $ADPRE > 0$, the acquisition stage begins when precharge ends.

At the start of the acquisition stage, the port pin logic of the selected analog channel is overridden to turn off the digital high/low output drivers so they do not affect the final result of the charge averaging. Also, the selected ADC channel is connected to C_{HOLD} . This allows charge averaging to proceed between the precharged channel and the C_{HOLD} capacitor.



Important: When $ADPRE > 0$ setting ADACQ to '0' will set a maximum acquisition time (256 ADC clock cycles). When precharge is disabled, setting ADACQ to '0' will disable hardware acquisition time control.

33.4.4 Guard Ring Outputs

Figure 33-8 shows a typical guard ring circuit. C_{GUARD} represents the capacitance of the guard ring trace placed on the PCB board. The user selects values for R_A and R_B that will create a voltage profile on C_{GUARD} , which will match the selected acquisition channel.

The purpose of the guard ring is to generate a signal in phase with the CVD sensing signal to minimize the effects of the parasitic capacitance on sensing electrodes. It also can be used as a mutual drive for mutual capacitive sensing. For more information about active guard and mutual drive, see AN1478, “*mTouch™ Sensing Solution Acquisition Methods Capacitive Voltage Divider*”.

The ADC has two guard ring drive outputs, ADGRDA and ADGRDB. These outputs can be routed through PPS controls to I/O pins (see “**Peripheral Pin Select (PPS) Module**” for details). The polarity of these outputs are controlled by the ADGPOL and ADIPEN bits.

At the start of the first precharge stage, both outputs are set to match the ADGPOL bit. Once the acquisition stage begins, ADGRDA changes polarity, while ADGRDB remains unchanged. When performing a double sample conversion, setting the ADIPEN bit causes both guard ring outputs to transition to the opposite polarity of ADGPOL at the start of the second precharge stage, and ADGRDA toggles again for the second acquisition. For more information on the timing of the guard ring output, refer to Figure 33-8 and Figure 33-9.

Figure 33-8. Guard Ring Circuit

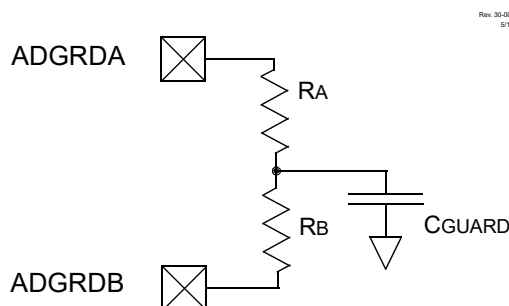


Figure 33-9. Differential CVD with Guard Ring Output Waveform

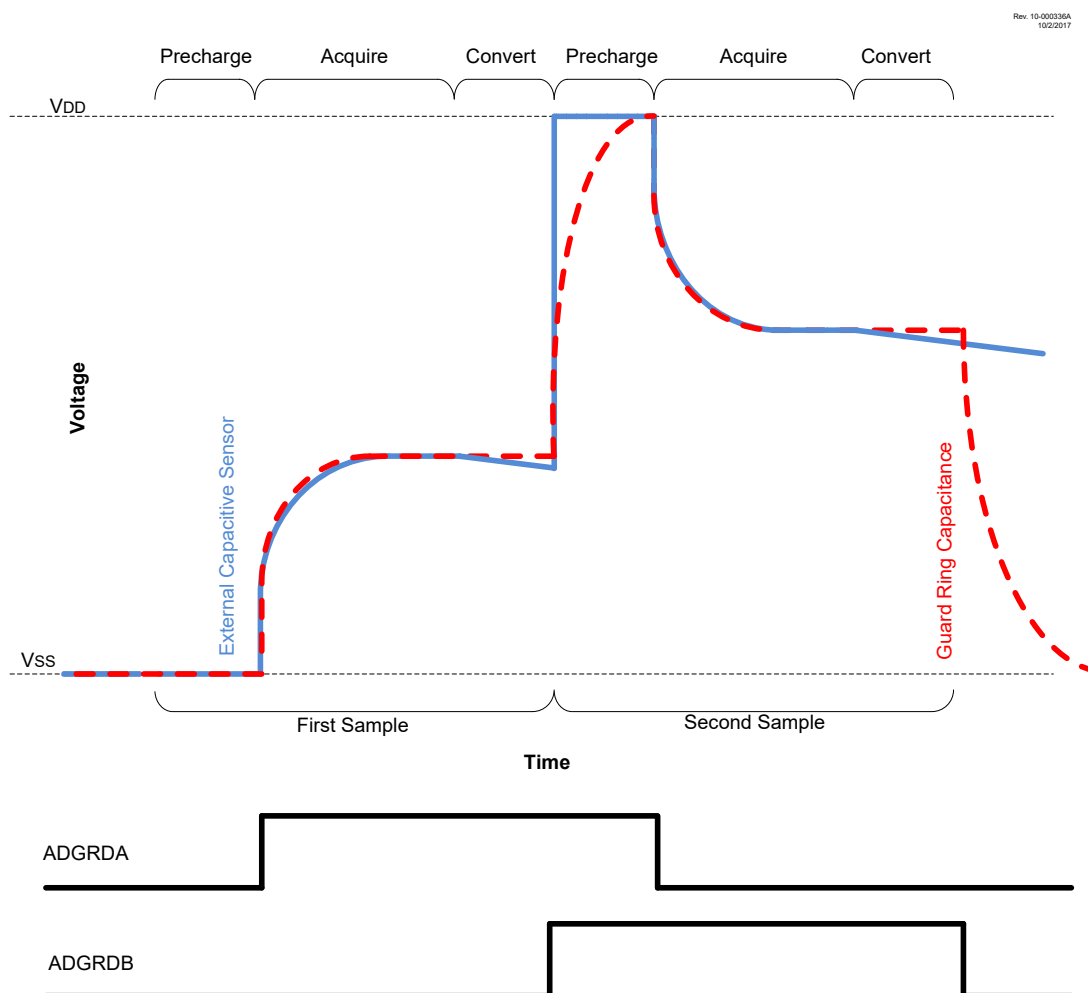
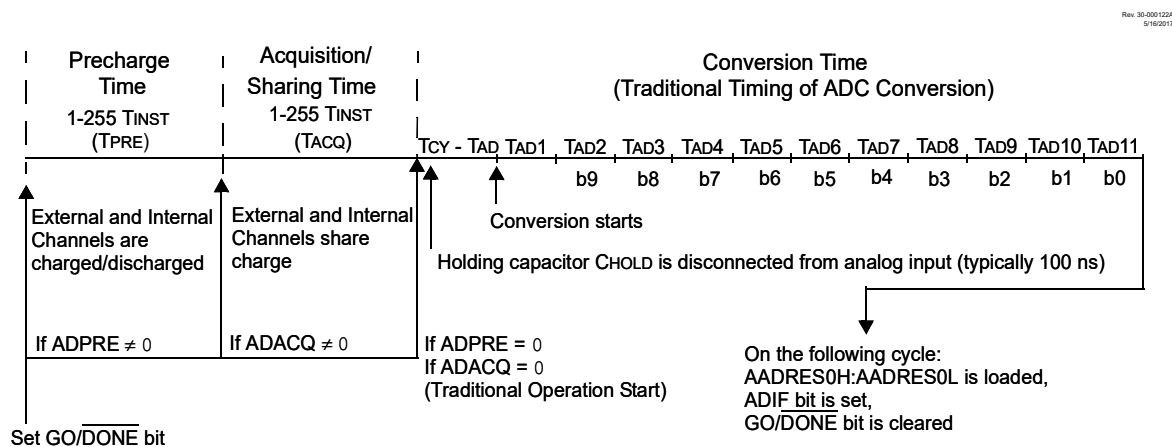


Figure 33-10. Hardware CVD Sequence Timing Diagram



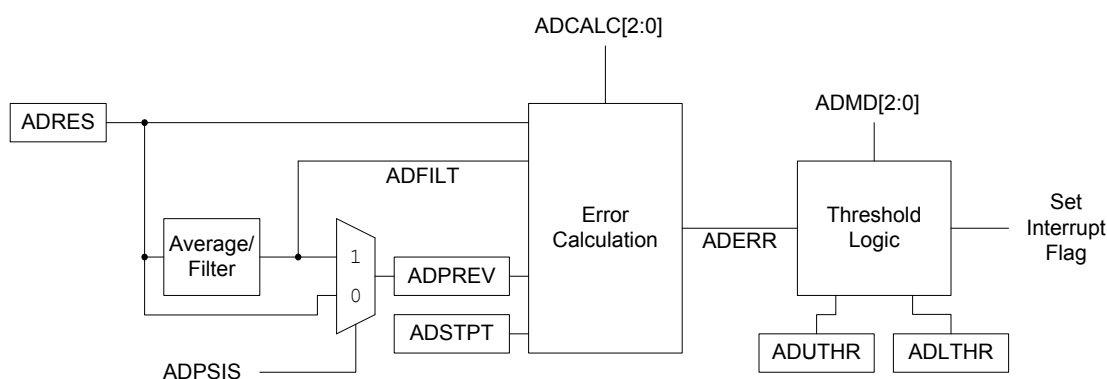
33.4.5 Additional Sample-and-Hold Capacitance

Additional capacitance can be added in parallel with the internal Sample-and-Hold capacitor (C_{HOLD}) by using the ADCAP register. This register selects a digitally programmable capacitance that is added to the ADC conversion bus, increasing the effective internal capacitance of the Sample-and-Hold capacitor in the ADC module. This is used to improve the match between internal and external capacitance for a better sensing performance. The additional capacitance does not affect analog performance of the ADC because it is not connected during conversion. See [Figure 33-11](#).

33.5 Computation Operation

The ADC module hardware is equipped with post conversion computation features. These features provide data post-processing functions that can be operated on the ADC conversion result, including digital filtering/averaging and threshold comparison functions.

Figure 33-11. Computational Features Simplified Block Diagram



The operation of the ADC computational features is controlled by the [ADMD](#) bits.

The module can be operated in one of five modes:

- **Basic:** This is a legacy mode. In this mode, ADC conversion occurs on single ($\text{ADDSEN} = 0$) or double ($\text{ADDSEN} = 1$) samples. ADIF is set after each conversion is complete.
- **Accumulate:** With each trigger, the ADC conversion result is added to the accumulator and ADCNT increments. ADIF is set after each conversion. ADTIF is set according to the calculation mode.
- **Average:** With each trigger, the ADC conversion result is added to the accumulator. When the ADRPT number of samples have been accumulated, a threshold test is performed. Upon the next trigger, the accumulator is cleared. For the subsequent tests, additional ADRPT samples are required to be accumulated.
- **Burst Average:** At the trigger, the accumulator is cleared. The ADC conversion results are then collected repetitively until ADRPT samples are accumulated and finally the threshold is tested.
- **Low-Pass Filter (LPF):** With each trigger, the ADC conversion result is sent through a filter. When ADRPT samples have occurred, a threshold test is performed. Every trigger after that the ADC conversion result is sent through the filter and another threshold test is performed.

The five modes are summarized in the following table.

Table 33-4. Computation Modes

| Mode | ADMD | Register Clear Event | Value after Cycle ⁽²⁾ Completion | | Threshold Operations | | | Value at ADTIF Interrupt | | |
|------------------|------|---|---|--|----------------------------------|---------------------|-------------------|--------------------------|--------------------------|-------|
| | | ADACC and ADCNT | ADACC ⁽¹⁾ | ADCNT | Retrigger | Threshold Test | Interrupt | ADAOV | ADFLTR | ADCNT |
| Basic | 0 | ADACLR = 1 | Unchanged | Unchanged | No | Every Sample | If threshold=true | N/A | N/A | count |
| Accumulate | 1 | ADACLR = 1 | S1 + ADACC or (S2-S1) + ADACC | If (ADCNT=FF): ADCNT, otherwise: ADCNT+1 | No | Every Sample | If threshold=true | ADACC Overflow | ADACC/2 ^{ADCRS} | count |
| Average | 2 | ADACLR = 1 or ADCNT ≥ ADRPT at ADGO or retrigger | S1 + ADACC or (S2-S1) + ADACC | If (ADCNT=FF): ADCNT, otherwise: ADCNT+1 | No | If ADCNT ≥ ADRPT | If threshold=true | ADACC Overflow | ADACC/2 ^{ADCRS} | count |
| Burst Average | 3 | ADACLR = 1 or ADGO set or retrigger | Each repetition: same as Average End with sum of all samples | Each repetition: same as Average End with ADCNT=ADRPT | Repeat while ADCNT < ADRPT | If ADCNT ≥ ADRPT | If threshold=true | ADACC Overflow | ADACC/2 ^{ADCRS} | ADRPT |
| Low-pass Filter | 4 | ADACLR = 1 | S1 + ADACC-ADACC/ 2 ^{ADCRS} or (S2-S1) + ADACC- ADACC/2 ^{ADCRS} | If (ADCNT=FF): ADCNT, otherwise: ADCNT+1 | No | If ADCNT ≥ ADRPT | If threshold=true | ADACC Overflow | Filtered Value | count |

Notes:

- S1 and S2 are abbreviations for Sample 1 and Sample 2, respectively. When ADDSEN = 0, S1 = ADRES. When ADDSEN = 1, S1 = ADPREV and S2 = ADRES.
- When ADDSEN = 0, then Cycle means one conversion. When ADDSEN = 1 then Cycle means two conversions.

33.5.1 Digital Filter/Average

The digital filter/average module consists of an accumulator with data feedback options, and control logic to determine when threshold tests need to be applied. The accumulator is a 16-bit wide register that can be accessed through the [ADACC](#) registers.

Upon each trigger event (the ADGO bit set or external event trigger), the ADC conversion result is added to the accumulator. If the accumulated value exceeds $2^{(\text{accumulator_width})-1} = 2^{16} = 65535$, the [ADAOV](#) overflow bit is set.

The number of samples to be accumulated is determined by the ADRPT (A/D Repeat Setting) register. Each time a sample is added to the accumulator, the ADCNT register is incremented. Once ADRPT samples are accumulated (ADCNT = ADRPT), an accumulator clear command can be issued by the software by setting the [ADACLR](#) bit. Setting the ADACLR bit will also clear the [ADAOV](#) (Accumulator overflow) bit, as well as the ADCNT register. The ADACLR bit is cleared by the hardware when accumulator clearing action is complete.



Important: When ADC is operating from FRC, five FRC clock cycles are required to execute the ADACC clearing operation.

The [ADCRS](#) bits control the data shift on the accumulator result, which effectively divides the value in accumulator ([ADACC](#)) registers. For the Accumulate mode of the digital filter, the shift provides a simple scaling operation. For the Average/Burst Average mode, the shift bits are used to determine number of samples for averaging. For the Low-pass Filter mode, the shift is an integral part of the filter, and determines the cutoff frequency of the filter. [Table 33-5](#) shows the -3 dB cutoff frequency in ωT (radians) and the highest signal attenuation obtained by this filter at nyquist frequency ($\omega T = \pi$).

Table 33-5. Low-pass Filter -3 dB Cutoff Frequency

| ADCRS | ωT (radians) @ -3 dB Frequency | dB @ $F_{\text{Nyquist}}=1/(2T)$ |
|-------|--|----------------------------------|
| 1 | 0.72 | -9.5 |
| 2 | 0.284 | -16.9 |
| 3 | 0.134 | -23.5 |
| 4 | 0.065 | -29.8 |
| 5 | 0.032 | -36.0 |
| 6 | 0.016 | -42.0 |

33.5.2 Basic Mode

Basic mode (ADMD = 000) disables all additional computation features. In this mode, no accumulation occurs but threshold error comparison is performed. Double sampling, Continuous mode, and all CVD features are still available, but no features involving the digital filter/average features are used.

33.5.3 Accumulate Mode

In Accumulate mode (ADMD = 001), after every conversion, the ADC result is added to the ADACC register. The ADACC register is right-shifted by the value of the [ADCRS](#) bits. This right-shifted value is copied in to the ADFLT register. The Formatting mode does not affect the right-justification of the ADACC value. Upon each sample, ADCNT is also incremented, incrementing the number of samples accumulated. After each sample and accumulation, the ADACC value has a threshold comparison performed on it (see [Threshold Comparison](#)) and the ADTIF interrupt may trigger.

33.5.4 Average Mode

In Average Mode (ADMD = 010), the ADACC registers accumulate with each ADC sample, much as in Accumulate mode, and the ADCNT register increments with each sample. The ADFLT register is

also updated with the right-shifted value of the ADACC register. The value of the ADCRS bits governs the number of right shifts. However, in Average mode, the threshold comparison is performed upon ADCNT being greater than or equal to a user-defined ADRPT value. In this mode when $ADRPT = 2^{ADCNT}$, then the final accumulated value will be divided by number of samples, allowing for a threshold comparison operation on the average of all gathered samples.

33.5.5 Burst Average Mode

The Burst Average mode (ADMD = 011) acts the same as the Average mode in most respects. The one way it differs is that it continuously retriggers ADC sampling until the ADCNT value is greater than or equal to ADRPT, even if Continuous Sampling mode (see [Continuous Sampling Mode](#)) is not enabled. This allows for a threshold comparison on the average of a short burst of ADC samples.

33.5.6 Low-pass Filter Mode

The Low-pass Filter mode (ADMD = 100) acts similarly to the Average mode in how it handles samples (accumulates samples until ADCNT value greater than or equal to ADRPT, then triggers threshold comparison), but instead of a simple average, it performs a low-pass filter operation on all of the samples, reducing the effect of high-frequency noise on the average, then performs a threshold comparison on the results. (see [Computation Operation](#) for a more detailed description of the mathematical operation). In this mode, the ADCRS bits determine the cutoff frequency of the low-pass filter (as demonstrated by [Digital Filter/Average](#)).

33.5.7 Threshold Comparison

At the end of each computation:

- The conversion results are latched and held stable at the end-of-conversion.
- The error (ADERR) is calculated based on a difference calculation which is selected by the ADCALC bits. The value can be one of the following calculations (see [Table 33-6](#) for more details):
 - The first derivative of single measurements
 - The CVD result when double-sampling is enabled
 - The current result vs. a setpoint
 - The current result vs. the filtered/average result
 - The first derivative of the filtered/average value
 - Filtered/average value vs. a setpoint
- The result of the calculation (ADERR) is compared to the upper and lower thresholds, ADUTH and ADLTH registers, to set the ADUTHR and ADLTHR flag bits. The threshold logic is selected by ADTMD bits. The threshold trigger option can be one of the following:
 - Never interrupt
 - Error is less than lower threshold
 - Error is greater than or equal to lower threshold
 - Error is between thresholds (inclusive)
 - Error is outside of thresholds
 - Error is less than or equal to upper threshold
 - Error is greater than upper threshold
 - Always interrupt regardless of threshold test results
 - If the threshold condition is met, the threshold interrupt flag ADTIF is set.

Notes:

1. The threshold tests are signed operations.
2. If ADAOV is set, a threshold interrupt is signaled. It is good practice for threshold interrupt handlers to verify the validity of the threshold by checking ADAOV.

Table 33-6. ADC Error Calculation Mode

| ADCALC | ADERR | | Application |
|--------|-------------------------------|--|--|
| | ADDSEN = 0 Single-Sample Mode | ADDSEN = 1 CVD Double-Sample Mode ⁽¹⁾ | |
| 111 | ADFLTR | ADFLTR | Filtered results above or below the threshold. |
| 110 | ADRES | ADRES | Measurement above or below the threshold |
| 101 | ADFLTR-ADSTPT | ADFLTR-ADSTPT | Average/filtered value vs. setpoint |
| 100 | ADPREV-ADFLTR | ADPREV-ADFLTR | First derivative of filtered value ⁽³⁾ (negative) |
| 011 | Reserved | Reserved | Reserved |
| 010 | ADRES-ADFLTR | (ADRES-ADPREV)-ADFLTR | Actual result vs. averaged/filtered value |
| 001 | ADRES-ADSTPT | (ADRES-ADPREV)-ADSTPT | Actual result vs. setpoint |
| 000 | ADRES-ADPREV | ADRES-ADPREV | First derivative of single measurement ⁽²⁾ |
| | | | Actual CVD result ^(1,2) |

Notes:

1. When ADDSEN=1, ADERR is computed only after every second sample.
2. When ADPSIS = 0.
3. When ADPSIS = 1.

33.5.8 Continuous Sampling Mode

Setting the **ADCONT** bit register automatically retriggers a new conversion cycle after updating the ADACC register. That means the ADGO bit is set to generate automatic retriggering, until the device Reset occurs or the **ADSOI** A/D Stop-on-interrupt bit is set (correct logic).

33.5.9 Double Sample Conversion

Double sampling is enabled by setting the **ADDSEN** bit. When this bit is set, two conversions are required before the module will calculate threshold error. Each conversion must still be triggered separately when **ADCONT** = 0. The first conversion will set the **ADMATH** bit and update ADACC, but will not calculate ADERR or trigger ADTIF. When the second conversion completes, the first value is transferred to ADPREV (depending on the setting of ADPSIS) and the value of the second conversion is placed into ADRES. Only upon the completion of the second conversion is ADERR calculated and ADTIF triggered (depending on the value of ADCALC).

33.6 Register Summary - ADC Control

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|----------|----------|--------------|--------|-------------|------------|--------|-------------|-------------|---------|
| 0x00 ... 0x0F50 | Reserved | | | | | | | | | |
| 0x0F51 | ADACT | 7:0 | | | | ADACT[4:0] | | | | |
| 0x0F52 | ADCLK | 7:0 | | | ADCS[5:0] | | | | | |
| 0x0F53 | ADREF | 7:0 | | | | ADNREF | | | ADPREF[1:0] | |
| 0x0F54 | ADCON1 | 7:0 | ADPPOL | ADIPEN | ADGPOL | | | | | ADDSSEN |
| 0x0F55 | ADCON2 | 7:0 | ADPSIS | | ADCRS[2:0] | | ADACLR | | ADMMD[2:0] | |
| 0x0F56 | ADCON3 | 7:0 | | | ADCALC[2:0] | | ADSOI | | ADTMD[2:0] | |
| 0x0F57 | ADACQ | 7:0 | ADACQ[7:0] | | | | | | | |
| 0x0F58 | ADCAP | 7:0 | | | | ADCAP[4:0] | | | | |
| 0x0F59 | ADPRE | 7:0 | ADPRE[7:0] | | | | | | | |
| 0x0F5A | ADPCH | 7:0 | ADPCH[5:0] | | | | | | | |
| 0x0F5B | ADCON0 | 7:0 | ADON | ADCONT | | ADCS | | ADFM | | ADGO |
| 0x0F5C | ADPREV | 7:0 | ADPREVL[7:0] | | | | | | | |
| | | 15:8 | ADPREVH[7:0] | | | | | | | |
| 0x0F5E | ADRES | 7:0 | ADRESL[7:0] | | | | | | | |
| | | 15:8 | ADRESH[7:0] | | | | | | | |
| 0x0F60 | ADSTAT | 7:0 | ADAOV | ADUTHR | ADLTHR | ADMATH | | ADSTAT[2:0] | | |
| 0x0F61 | ADRPT | 7:0 | ADRPT[7:0] | | | | | | | |
| 0x0F62 | ADCNT | 7:0 | ADCNT[7:0] | | | | | | | |
| 0x0F63 | ADSTPT | 7:0 | ADSTPTL[7:0] | | | | | | | |
| | | 15:8 | ADSTPTH[7:0] | | | | | | | |
| 0x0F65 | ADLTH | 7:0 | ADLTHL[7:0] | | | | | | | |
| | | 15:8 | ADLTHH[7:0] | | | | | | | |
| 0x0F67 | ADUTH | 7:0 | ADUTHL[7:0] | | | | | | | |
| | | 15:8 | ADUTHH[7:0] | | | | | | | |
| 0x0F69 | ADERR | 7:0 | ADERRL[7:0] | | | | | | | |
| | | 15:8 | ADERRH[7:0] | | | | | | | |
| 0x0F6B | ADACC | 7:0 | ADACCL[7:0] | | | | | | | |
| | | 15:8 | ADACCH[7:0] | | | | | | | |
| 0x0F6D | ADFLTR | 7:0 | ADFLTRL[7:0] | | | | | | | |
| | | 15:8 | ADFLTRH[7:0] | | | | | | | |

33.7 Register Definitions: ADC Control

33.7.1 ADCON0

Name: ADCON0

Address: 0xF5B

ADC Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------|--------|---|------|---|------|---|--------|
| | ADON | ADCONT | | ADCS | | ADFM | | ADGO |
| Access | R/W | R/W | | R/W | | R/W | | R/W/HC |
| Reset | 0 | 0 | | 0 | | 0 | | 0 |

Bit 7 – ADON ADC Enable bit

| Value | Description |
|-------|-----------------|
| 1 | ADC is enabled |
| 0 | ADC is disabled |

Bit 6 – ACONT ADC Continuous Operation Enable bit

| Value | Description |
|-------|---|
| 1 | ADGO is retrigged upon completion of each conversion trigger until ADTIF is set (if ADSOI is set) or until ADGO is cleared (regardless of the value of ADSOI) |
| 0 | ADC is cleared upon completion of each conversion trigger |

Bit 4 – ADCS ADC Clock Selection bit

| Value | Description |
|-------|---|
| 1 | Clock supplied from FRC dedicated oscillator |
| 0 | Clock supplied by Fosc, divided according to ADCLK register |

Bit 2 – ADFM ADC results Format/alignment Selection

| Value | Description |
|-------|---|
| 1 | ADRES and ADPREV data are right justified |
| 0 | ADRES and ADPREV data are left justified, zero-filled |

Bit 0 – ADGO ADC Conversion Status bit

| Value | Description |
|-------|--|
| 1 | ADC conversion cycle in progress. Setting this bit starts an ADC conversion cycle. The bit is cleared by hardware as determined by the ACONT bit |
| 0 | ADC conversion completed/not in progress |

33.7.2 ADCON1

Name: ADCON1

Address: 0xF54

ADC Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|---|---|---|---|--------|
| | ADPPOL | ADIPEN | ADGPOL | | | | | ADDSEN |
| Access | R/W | R/W | R/W | | | | | R/W |
| Reset | 0 | 0 | 0 | | | | | 0 |

Bit 7 – ADPPOL Precharge Polarity bit
Action During 1st Precharge Stage

| Value | Condition | Description |
|-------|-------------------------------------|---|
| x | ADPRE = 0 | Bit has no effect |
| 1 | ADPRE > 0 and ADC input is I/O pin | Pin shorted to AV _{DD} |
| 0 | ADPRE > 0 and ADC input is I/O pin | Pin shorted to V _{SS} |
| 1 | ADPRE > 0 and ADC input is internal | C _{HOLD} shorted to AV _{DD} |
| 0 | ADPRE > 0 and ADC input is internal | C _{HOLD} shorted to V _{SS} |

Bit 6 – ADIPEN A/D Inverted Precharge Enable bit

| Value | Condition | Description |
|-------|------------|---|
| x | ADDSEN = 0 | Bit has no effect |
| 1 | ADDSEN = 1 | The precharge and guard signals in the second conversion cycle are the opposite polarity of the first cycle |
| 0 | ADDSEN = 1 | Both conversion cycles use the precharge and guards specified by ADPPOL and ADGPOL |

Bit 5 – ADGPOL Guard Ring Polarity Selection bit

| Value | Description |
|-------|---|
| 1 | ADC guard ring outputs start as digital high during Precharge stage |
| 0 | ADC guard ring outputs start as digital low during Precharge stage |

Bit 0 – ADDSEN Double-Sample Enable bit

| Value | Description |
|-------|---|
| 1 | Two conversions are processed as a pair. The selected computation is performed after every second conversion. |
| 0 | Selected computation is performed after every conversion |

33.7.3 ADCON2

Name: ADCON2

Address: 0xF55

ADC Control Register 2

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|------------|-----|-----|--------|-----------|-----|-----|
| | ADPSIS | ADCRS[2:0] | | | ADACL | ADMD[2:0] | | |
| Access | R/W | R/W | R/W | R/W | R/W/HC | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 7 – ADPSIS ADC Previous Sample Input Select bits

| Value | Description |
|-------|--|
| 1 | ADFLTR is transferred to ADPREV at start-of-conversion |
| 0 | ADRES is transferred to ADPREV at start-of-conversion |

Bits 6:4 – ADCRS[2:0] ADC Accumulated Calculation Right Shift Select bits

| Value | Condition | Description |
|--------|-----------------------|---|
| 1 to 6 | ADMD = 'b100 | Low-pass filter time constant is 2^{ADCRS} , filter gain is 1:1 ⁽²⁾ |
| 1 to 6 | ADMD = 'b011 to 'b001 | The accumulated value is right-shifted by ADCRS (divided by 2^{ADCRS})(1,2) |
| x | ADMD = 'b000 | These bits are ignored |

Bit 3 – ADACL A/D Accumulator Clear Command bit⁽³⁾

| Value | Description |
|-------|--|
| 1 | ADACC, ADAOV and ADCNT registers are cleared |
| 0 | Clearing action is complete (or not started) |

Bits 2:0 – ADMD[2:0] ADC Operating Mode Selection bits⁽⁴⁾

| Value | Description |
|---------|----------------------|
| 111-101 | Reserved |
| 100 | Low-pass Filter mode |
| 011 | Burst Average mode |
| 010 | Average mode |
| 001 | Accumulate mode |
| 000 | Basic (Legacy) mode |

Notes:

1. To correctly calculate an average, the number of samples (set in ADRPT) must be 2^{ADCRS} .
2. ADCRS = 'b111 and 'b000 are reserved.
3. This bit is cleared by hardware when the accumulator operation is complete; depending on oscillator selections, the delay may be many instructions.
4. See [Table 33-4](#) for Full mode descriptions.

33.7.4 ADCON3**Name:** ADCON3**Address:** 0xF56

ADC Control Register 3

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|-------------|-----|-----|--------|------------|-----|-----|
| | | ADCALC[2:0] | | | ADSOI | ADTMD[2:0] | | |
| Access | | R/W | R/W | R/W | R/W/HC | R/W | R/W | R/W |
| Reset | | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 6:4 – ADCALC[2:0] ADC Error Calculation Mode Select bitsSee [Table 33-6](#) for selection details.**Bit 3 – ADSOI** ADC Stop-on-Interrupt bit

| Value | Condition | Description |
|-------|------------|--|
| 1 | ADCONT = 1 | ADGO is cleared when the threshold conditions are met, otherwise the conversion is retrigged |
| 0 | ADCONT = 1 | ADGO is not cleared by hardware, must be cleared by software to stop retriggers |
| x | ADCONT = 0 | This bit is not used |

Bits 2:0 – ADTMD[2:0] Threshold Interrupt Mode Select bits

| Value | Description |
|-------|--|
| 111 | Interrupt regardless of threshold test results |
| 110 | Interrupt if ADERR > ADUTH |
| 101 | Interrupt if ADERR ≤ ADUTH |
| 100 | Interrupt if ADERR < ADLTH or ADERR > ADUTH |
| 011 | Interrupt if ADERR > ADLTH and ADERR < ADUTH |
| 010 | Interrupt if ADERR ≥ ADLTH |
| 001 | Interrupt if ADERR < ADLTH |
| 000 | Never interrupt |

33.7.5 ADSTAT

Name: ADSTAT

Address: 0xF60

ADC Status Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|--------|--------|-----------|---|-------------|----|----|
| | ADAOV | ADUTHR | ADLTHR | ADMATH | | ADSTAT[2:0] | | |
| Access | R/C/HS/HC | RO | RO | R/C/HS/HC | | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | | 0 | 0 | 0 |

Bit 7 – ADAOV ADC Accumulator Overflow bit

| Value | Description |
|-------|---|
| 1 | ADC accumulator or ADERR calculation have overflowed |
| 0 | ADC accumulator and ADERR calculation have not overflowed |

Bit 6 – ADUTHR ADC Module Greater-than Upper Threshold Flag bit

| Value | Description |
|-------|---------------|
| 1 | ADERR > ADUTH |
| 0 | ADERR ≤ ADUTH |

Bit 5 – ADLTHR ADC Module Less-than Lower Threshold Flag bit

| Value | Description |
|-------|---------------|
| 1 | ADERR < ADLTH |
| 0 | ADERR ≥ ADLTH |

Bit 4 – ADMATH ADC Module Computation Status bit

| Value | Description |
|-------|--|
| 1 | Registers ADACC, ADLTHR, ADUTH, ADLTH and the ADAOV bit are updating or have already updated |
| 0 | Associated registers/bits have not changed since this bit was last cleared |

Bits 2:0 – ADSTAT[2:0]

ADC Module Cycle Multi-Stage Status bits⁽¹⁾

| Value | Description |
|-------|--|
| 111 | ADC module is in 2 nd conversion stage |
| 110 | ADC module is in 2 nd acquisition stage |
| 101 | ADC module is in 2 nd precharge stage |
| 100 | ADC computation is suspended between 1 st and 2 nd sample; the computation results are incomplete and awaiting data from the 2 nd sample ^(2,3) |
| 011 | ADC module is in 1 st conversion stage |
| 010 | ADC module is in 1 st acquisition stage |
| 001 | ADC module is in 1 st precharge stage |
| 000 | ADC module is not converting |

Notes:

1. If ADCS = 1, and $F_{OSC} < F_{RC}$, the indicated status may not be valid.
2. If ADC clock source is ADCRC and $F_{OSC} < ADRC$, the indicated status may not be valid.
3. STAT = 'b100 appears between the two triggers when DSEN = 1 and CONT = 0.

33.7.6 ADCLK

Name: ADCLK
Address: 0xF52

ADC Clock Selection Register

| | | | | | | | | |
|--------|---|---|-----------|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | ADCS[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 5:0 – ADCS[5:0] ADC Conversion Clock Select bits

| Value | Description |
|-------|---|
| n | ADC Clock frequency = $F_{OSC}/(2*(n+1))$ |

33.7.7 ADREF**Name:** ADREF**Address:** 0xF53

ADC Reference Selection Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|--------|---|---|-------------|-----|
| | | | | ADNREF | | | ADPREF[1:0] | |
| Access | | | | R/W | | | R/W | R/W |
| Reset | | | | 0 | | | 0 | 0 |

Bit 4 – ADNREF ADC Negative Voltage Reference Selection bit

| Value | Description |
|-------|--|
| 1 | V_{REF-} is connected to external V_{REF-} |
| 0 | V_{REF-} is connected to AV_{SS} |

Bits 1:0 – ADPREF[1:0] ADC Positive Voltage Reference Selection bits

| Value | Description |
|-------|--|
| 11 | V_{REF+} is connected to internal Fixed Voltage Reference (FVR) module |
| 10 | V_{REF+} is connected to external V_{REF+} |
| 01 | Reserved |
| 00 | V_{REF+} is connected to V_{DD} |

33.7.8 ADPCH

Name: ADPCH
Address: 0xF5A

ADC Positive Channel Selection Register

| | | | | | | | | |
|--------|---|---|------------|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | ADPCH[5:0] | | | | | |
| Access | | | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | | | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 5:0 – ADPCH[5:0] ADC Positive Input Channel Selection bits
See [Channel Selection Table](#) for input selection details.

33.7.9 ADPRE**Name:** ADPRE**Address:** 0xF59

ADC Precharge Time Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | ADPRE[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – ADPRE[7:0] Precharge Time Select bits

| ADPRE | Precharge Time | |
|-------------------------|---|-------------------------------|
| ADCS != F _{RC} | ADCS = F _{RC} | |
| 255 | 255 clocks of F _{OSC} | 255 clocks of F _{RC} |
| 254 | 254 clocks of F _{OSC} | 254 clocks of F _{RC} |
| ... | ... | |
| 2 | 2 clocks of F _{OSC} | 2 clocks of F _{RC} |
| 1 | 1 clock of F _{OSC} | 1 clocks of F _{RC} |
| 0 | Not included in the data conversion cycle | |

33.7.10 ADACQ**Name:** ADACQ**Address:** 0xF57

ADC Acquisition Time Control Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| | ADACQ[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – ADACQ[7:0] Acquisition (charge share time) Select bits**Table 33-7.**

| ADACQ | Acquisition Time | |
|-------|--|------------------------------|
| | ADCS != F _{RC} | ADCS = F _{RC} |
| 255 | 255 clock of F _{OSC} | 255 clock of F _{RC} |
| 254 | 254 clock of F _{OSC} | 254 clock of F _{RC} |
| ... | ... | ... |
| 2 | 2 clock of F _{OSC} | 2 clock of F _{RC} |
| 1 | 1 clock of F _{OSC} | 1 clock of F _{RC} |
| 0 | Not included in the data conversion cycle ⁽¹⁾ | |

Note:

1. If ADPRE is not equal to '0', then ADACQ = 0b0000_0000 means Acquisition Time is 256 clocks of F_{OSC} or F_{RC}.

33.7.11 ADCAP

Name: ADCAP
Address: 0xF58

ADC Additional Sample Capacitor Selection Register

| | | | | | | | | |
|--------|---|---|---|------------|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | ADCAP[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – ADCAP[4:0] ADC Additional Sample Capacitor Selection bits

| Value | Description |
|---------|--|
| 1 to 31 | Number of pF in the additional capacitance |
| 0 | No additional capacitance |

33.7.12 ADRPT

Name: ADRPT
Address: 0xF61

ADC Repeat Setting Register

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADRPT[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – ADRPT[7:0] ADC Repeat Threshold bits
Determines the number of times that the ADC is triggered for a threshold check. When ADCNT reaches this value the error threshold is checked. Used when the computation mode is Low-pass Filter, Burst Average, or Average. See [Table 33-4](#) for more details.

33.7.13 ADCNT

Name: ADCNT
Address: 0xF62

ADC Repeat Counter Register

| | | | | | | | | |
|--------|------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADCNT[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 7:0 – ADCNT[7:0] ADC Repeat Count bits
Counts the number of times that the ADC is triggered before the threshold is checked. When this value reaches ADPRT then the threshold is checked. Used when the computation mode is Low-pass Filter, Burst Average, or Average. See [Table 33-4](#) for more details.

33.7.14 ADFLTR**Name:** ADFLTR**Address:** 0xF6D

ADC Filter Register. In Accumulate, Average, and Burst Average mode, this is equal to ADACC right shifted by the ADCRS bits of ADCON2. In LPF mode, this is the output of the low-pass filter.

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|--------------|----|----|----|----|----|----|----|
| | ADFLTRH[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADFLTRL[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | x | x | x | x | x | x | x | x |

Bits 15:8 – ADFLTRH[7:0] ADC Filter Output Most Significant bits

Bits 7:0 – ADFLTRL[7:0] ADC Filter Output Least Significant bits

33.7.15 ADRES**Name:** ADRES**Address:** 0xF5E

ADC Result Register

| | | | | | | | | |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADRESH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADRESL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADRESH[7:0] ADC Result Register bits. High bits

| Value | Condition | Description |
|------------------------|-----------|------------------------|
| 0x00, 0x01, 0x02, 0x03 | ADFM = 1 | Upper 2 bits of result |
| 0 to 0xFF | ADFM = 0 | Upper 8 bits of result |

Bits 7:0 – ADRESL[7:0] ADC Result Register bits. Lower bits

| Value | Condition | Description |
|------------------------|-----------|------------------------|
| 0 to 0xFF | ADFM = 1 | Lower 8 bits of result |
| 0x00, 0x40, 0x80, 0xC0 | ADFM = 0 | Lower 2 bits of result |

33.7.16 ADPREV**Name:** ADPREV**Address:** 0xF5C

ADC Previous Result Register

| | | | | | | | | |
|--------|--------------|----|----|----|----|----|----|----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADPREVH[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADPREVL[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADPREVH[7:0] Previous ADC Result Most Significant bits

| Value | Condition | Description |
|-----------|------------|---|
| 0 to 0xFF | ADPSIS = 1 | Upper byte of ADFLTR at the start of current ADC conversion |
| varies | ADPSIS = 0 | Upper bits of ADRES at the start of current ADC conversion ⁽¹⁾ |

Bits 7:0 – ADPREVL[7:0] Previous ADC Result Least Significant bits

| Value | Condition | Description |
|-----------|------------|---|
| 0 to 0xFF | ADPSIS = 1 | Lower byte of ADFLTR at the start of current ADC conversion |
| varies | ADPSIS = 0 | Lower bits of ADRES at the start of current ADC conversion ⁽¹⁾ |

Note: If ADPSIS = 0, ADPREVH and ADPREVL are formatted the same way as ADRES is, depending on the ADFM bit.

33.7.17 ADACC**Name:** ADACC**Address:** 0xF6B

ADC Accumulator Register

See [Table 33-4](#) for more details.

| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| | ADACCH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADACCL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | x | x | x | x | x | x | x | x |

Bits 15:8 – ADACCH[7:0]

ADC Accumulator Most Significant Byte.

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

Bits 7:0 – ADACCL[7:0]

ADC Accumulator Least Significant Byte.

Reset States: POR/BOR = xxxxxxxx

All Other Resets = uuuuuuuu

33.7.18 ADSTPT

Name: ADSTPT
Address: 0xF63

ADC Threshold Setpoint Register
Depending on [ADCALC](#), may be used to determine ADERR. See [Table 33-6](#) for more details.

| | | | | | | | | |
|--------|--------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADSTPTH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADSTPTL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADSTPTH[7:0]
ADC Threshold Setpoint Most Significant Byte.

Bits 7:0 – ADSTPTL[7:0]
ADC Threshold Setpoint Least Significant Byte.

33.7.19 ADERR**Name:** ADERR**Address:** 0xF69ADC Setpoint Error Register. ADC Setpoint Error calculation is determined by the [ADCALC](#) bits.

| | | | | | | | | |
|--------|-------------|----|----|----|----|----|----|----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADERRH[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADERRL[7:0] | | | | | | | |
| Access | RO | RO | RO | RO | RO | RO | RO | RO |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADERRH[7:0]

ADC Setpoint Error MSB

Bits 7:0 – ADERRL[7:0]

ADC Setpoint Error LSB

33.7.20 ADLTH**Name:** ADLTH**Address:** 0xF65

ADC Lower Threshold Register

ADLTH and ADUTH are compared with ADERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

| | | | | | | | | |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADLTHH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADLTHL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADLTHH[7:0] ADC Lower Threshold MSB**Bits 7:0 – ADLTHL[7:0]** ADC Lower Threshold LSB

33.7.21 ADUTH**Name:** ADUTH**Address:** 0xF67

ADC Upper Threshold Register

ADLTH and ADUTH are compared with ADERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

| | | | | | | | | |
|--------|-------------|-----|-----|-----|-----|-----|-----|-----|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| | ADUTHH[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | ADUTHL[7:0] | | | | | | | |
| Access | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15:8 – ADUTHH[7:0] ADC Upper Threshold MSB**Bits 7:0 – ADUTHL[7:0]** ADC Upper Threshold LSB

33.7.22 ADACT

Name: ADACT
Address: 0xF51

ADC AUTO Conversion Trigger Source Selection Register

| | | | | | | | | |
|--------|---|---|---|------------|-----|-----|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | ADACT[4:0] | | | | |
| Access | | | | R/W | R/W | R/W | R/W | R/W |
| Reset | | | | 0 | 0 | 0 | 0 | 0 |

Bits 4:0 – ADACT[4:0] Auto-Conversion Trigger Select Bits

| Value | Description |
|----------------|---|
| 00000 to 11111 | See Auto-Conversion Trigger Sources table |

34. CMP - Comparator Module

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. Comparators are very useful mixed-signal building blocks because they provide analog functionality independent of program execution. The PIC18F26/45/46Q10 devices have two comparators (C1/C2).

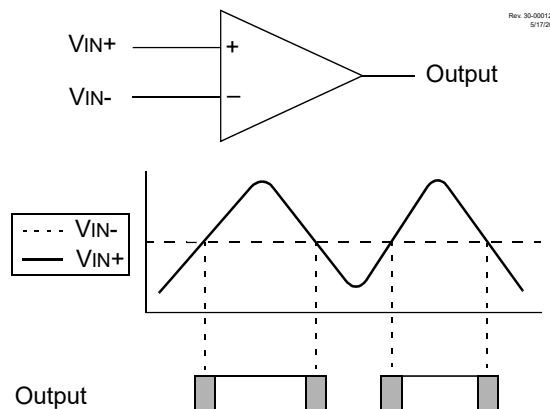
The analog comparator module includes the following features:

- Programmable Input Selection
- Programmable Output Polarity
- Rising/Falling Output Edge Interrupts
- Wake-up from Sleep
- CWG Auto-Shutdown Source
- Selectable Voltage Reference
- ADC Auto-Trigger
- Odd Numbered Timers (Timer1, Timer3, etc.) Gate
- Even Numbered Timers (Timer2, Timer4, etc.) Reset
- CCP Capture Mode Input
- DSM Modulator Source
- Input and Window Signal-to-Signal Measurement Timer

34.1 Comparator Overview

A single comparator is shown in [Figure 34-1](#) along with the relationship between the analog input levels and the digital output. When the analog voltage at V_{IN+} is less than the analog voltage at V_{IN-} , the output of the comparator is a digital low level. When the analog voltage at V_{IN+} is greater than the analog voltage at V_{IN-} , the output of the comparator is a digital high level.

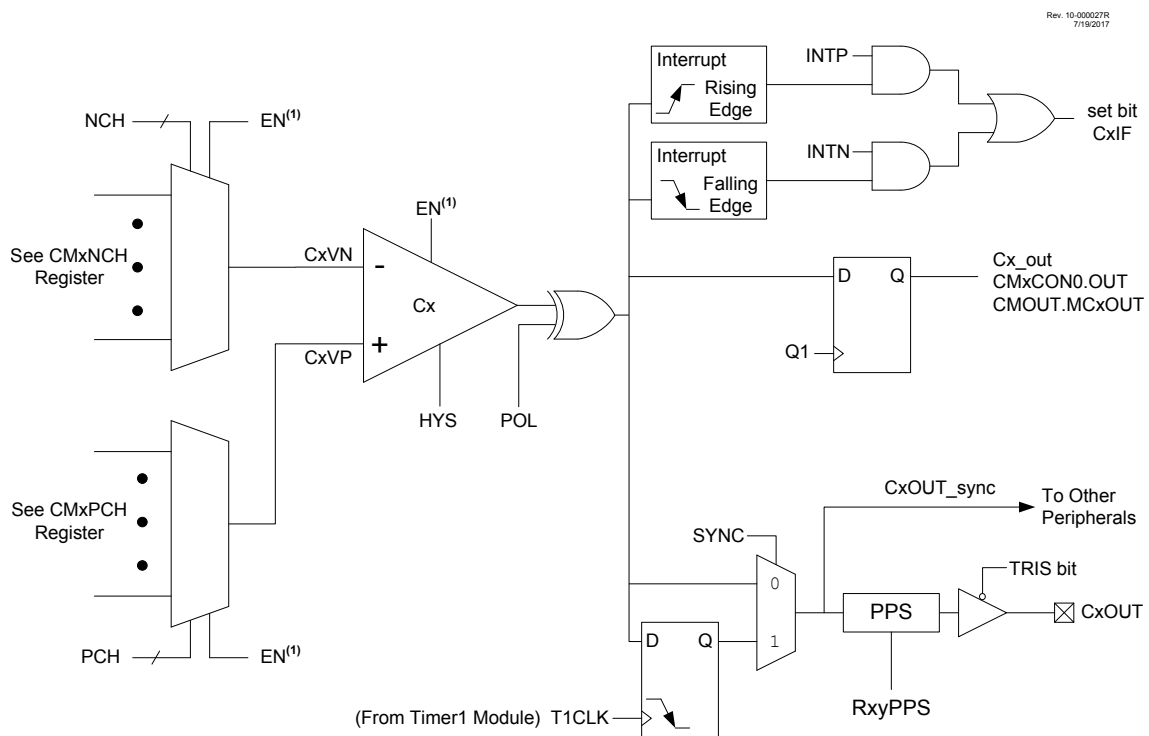
Figure 34-1. Single Comparator



Note:

1. The black areas of the output of the comparator represent the uncertainty due to input offsets and response time.

Figure 34-2. Comparator Module Simplified Block Diagram



Note 1: When EN = 0, all multiplexer inputs are disconnected and the Comparator will produce a '0' at the output.

Related Links

[CMxNCH](#)

CMxNCH

[CMxPCH](#)

CMxPCH

34.2 Comparator Control

Each comparator has two control registers: CMxCON0 and CMxCON1.

The [CMxCON0](#) register contains Control and Status bits for the following:

- Enable
- Output
- Output Polarity
- Hysteresis Enable
- Timer1 Output Synchronization

The [CMxCON1](#) register contains Control bits for the following:

- Interrupt on Positive/Negative Edge Enables
- Positive Input Channel Selection
- Negative Input Channel Selection

34.2.1 Comparator Enable

Setting the [EN](#) bit enables the comparator for operation. Clearing the CxEN bit disables the comparator, resulting in minimum current consumption.

34.2.2 Comparator Output

The output of the comparator can be monitored by reading either the [CxOUT](#) bit or the [MCxOUT](#) bit.

The comparator output can also be routed to an external pin through the RxyPPS register. The corresponding TRIS bit must be clear to enable the pin as an output.

Note:

1. The internal output of the comparator is latched with each instruction cycle. Unless otherwise specified, external outputs are not latched.

Related Links

[RxyPPS](#)

Pin Rxy Output Source Selection Register

34.2.3 Comparator Output Polarity

Inverting the output of the comparator is functionally equivalent to swapping the comparator inputs. The polarity of the comparator output can be inverted by setting the [CxPOL](#) bit. Clearing the CxPOL bit results in a non-inverted output.

[Table 34-1](#) shows the output state versus input conditions, including polarity control.

Table 34-1. Comparator Output State vs. Input Conditions

| Input Condition | CxPOL | CxOUT |
|-----------------|-------|-------|
| $CxVn > CxVp$ | 0 | 0 |
| $CxVn < CxVp$ | 0 | 1 |
| $CxVn > CxVp$ | 1 | 1 |
| $CxVn < CxVp$ | 1 | 0 |

34.3 Comparator Hysteresis

A selectable amount of separation voltage can be added to the input pins of each comparator to provide a hysteresis function to the overall operation. Hysteresis is enabled by setting the [CxHYS](#) bit.

See the “**Comparator Specifications**” section for more information.

Related Links

[Comparator Specifications](#)

34.4 Operation with Timer1 Gate

The output resulting from a comparator operation can be used as a source for gate control of the odd numbered timers (Timer1, Timer3, etc.). See [Timer1 Gate](#) for more information. This feature is useful for timing the duration or interval of an analog event.

It is recommended that the comparator output be synchronized to the timer by setting the [SYNC](#) bit in the CMxCON0 register. This ensures that the timer does not increment while a change in the comparator is occurring. However, synchronization is only possible with the Timer1 clock source. Synchronization with the other odd numbered timers is only possible when they use the same clock source as Timer1.

Related Links

[Timer1 Gate](#)

34.4.1 Comparator Output Synchronization

The output from a comparator can be synchronized with Timer1 by setting the [SYNC](#) bit.

Once enabled, the comparator output is latched on the falling edge of the Timer1 source clock. If a prescaler is used with Timer1, the comparator output is latched after the prescaling function. To prevent a race condition, the comparator output is latched on the falling edge of the Timer1 clock source and Timer1 increments on the rising edge of its clock source. See the [Figure 34-2](#) Comparator Block Diagram and the Timer1 Block Diagram for more information.

Related Links

[TMR1 - Timer1 Module with Gate Control](#)

34.5 Comparator Interrupt

An interrupt can be generated when either the rising edge or falling edge detector detects a change in the output value of each comparator.

When either edge detector is triggered and its associated enable bit is set ([CxINTP](#) and/or [CxINTN](#) bits), the corresponding Interrupt Flag bit (the CxIF bit of the PIR2 register) will be set.

To enable the interrupt, the following bits must be set:

- The [EN](#) and [POL](#) bits
- The CxIE bit of the PIE2 register
- The [INTP](#) bit (for a rising edge detection)
- The [INTN](#) bit (for a falling edge detection)
- The PEIE and GIE bits of the INTCON register

The associated Interrupt Flag bit, the CxIF bit of the PIR2 register, must be cleared in software. If another edge is detected while this flag is being cleared, the flag will still be set at the end of the sequence.



Important: Although a comparator is disabled, an interrupt can be generated by changing the output polarity with the [CxPOL](#) bit, or by switching the comparator on or off with the [CxEN](#) bit.

34.6 Comparator Positive Input Selection

Configuring the [PCH](#) bits in the CMxPCH register direct an internal voltage reference or an analog pin to the noninverting input of the comparator:

- CxINy+ analog pin
- DAC output
- Fixed Voltage Reference (FVR)



Important: To use CxINy+ pins as analog input, the appropriate bits must be set in the ANSEL register and the corresponding TRIS bits must also be set to disable the output drivers.

Any time the comparator is disabled ($CxEN = 0$), all comparator inputs are disabled.

Related Links

[FVR - Fixed Voltage Reference](#)

[DAC - 5-Bit Digital-to-Analog Converter](#)

34.7 Comparator Negative Input Selection

The **NCH** bits in the CMxNCH register direct an analog input pin and internal reference voltage or analog ground to the inverting input of the comparator:

- CxINy- analog pin
- Fixed Voltage Reference (FVR)



Important: To use CxINy- pins as analog input, the appropriate bits must be set in the ANSEL register and the corresponding TRIS bits must also be set to disable the output drivers.

34.8 Comparator Response Time

The comparator output is indeterminate for a period of time after the change of an input source or the selection of a new reference voltage. This period is referred to as the response time. The response time of the comparator differs from the settling time of the voltage reference. Therefore, both of these times must be considered when determining the total response time to a comparator input change. See the Comparator and Voltage Reference Specifications in Comparator Specifications and Fixed Voltage Reference (FVR) Specifications for more details.

Related Links

[Comparator Specifications](#)

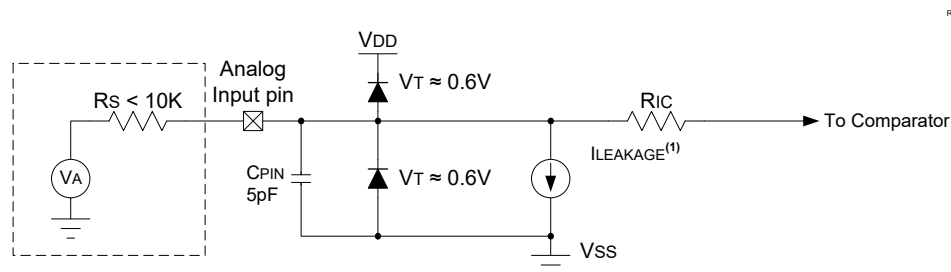
[Fixed Voltage Reference \(FVR\) Specifications](#)

34.9 Analog Input Connection Considerations

A simplified circuit for an analog input is shown in [Figure 34-3](#). Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to V_{DD} and V_{SS} . The analog input, therefore, must be between V_{SS} and V_{DD} . If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of 10 k Ω is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

Figure 34-3. Analog Input Model



Legend: CPIN = Input Capacitance
 ILEAKAGE = Leakage Current at the pin due to various junctions
 RIC = Interconnect Resistance
 RS = Source Impedance
 VA = Analog Voltage
 VT = Threshold Voltage

Related Links

[Electrical Specifications](#)

34.10 CWG1 Auto-Shutdown Source

The output of the comparator module can be used as an auto-shutdown source for the CWG1 module. When the output of the comparator is active and the corresponding WGASxE is enabled, the CWG operation will be suspended immediately.

Related Links

[External Input Source](#)

34.11 ADC Auto-Trigger Source

The output of the comparator module can be used to trigger an ADC conversion. When the ADACT register is set to trigger on a comparator output, an ADC conversion will trigger when the comparator output goes high.

34.12 Even Numbered Timers Reset

The output of the comparator module can be used to reset the even numbered timers (Timer2, Timer4, etc.). When the TxERS register is appropriately set, the timer will reset when the comparator output goes high.

34.13 Operation in Sleep Mode

The comparator module can operate during Sleep. The comparator clock source is based on the Timer1 clock source. If the Timer1 clock source is either the system clock (F_{OSC}) or the instruction clock ($F_{OSC}/4$), Timer1 will not operate during Sleep, and synchronized comparator outputs will not operate.

A comparator interrupt will wake the device from Sleep. The CxIE bits of the PIE2 register must be set to enable comparator interrupts.

34.14 Register Summary - Comparator

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|-------------------------|----------|----|-----|---|-----|---|---|----------|--------|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0F2F | | | | | | | | | | |
| 0x0F30 | CM2CON0 | 7:0 | EN | OUT | | POL | | | HYS | SYNC |
| 0x0F31 | CM2CON1 | 7:0 | | | | | | | INTP | INTN |
| 0x0F32 | CM2NCH | 7:0 | | | | | | | NCH[2:0] | |
| 0x0F33 | CM2PCH | 7:0 | | | | | | | PCH[2:0] | |
| 0x0F34 | CM1CON0 | 7:0 | EN | OUT | | POL | | | HYS | SYNC |
| 0x0F35 | CM1CON1 | 7:0 | | | | | | | INTP | INTN |
| 0x0F36 | CM1NCH | 7:0 | | | | | | | NCH[2:0] | |
| 0x0F37 | CM1PCH | 7:0 | | | | | | | PCH[2:0] | |
| 0x0F38 | CMOUT | 7:0 | | | | | | | MC2OUT | MC1OUT |

34.15 Register Definitions: Comparator Control

Related Links

[Long Bit Names](#)

34.15.1 CMxCON0

Name: CMxCON0
Address: 0xF34,0xF30

Comparator x Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|-----|---|-----|---|---|-----|------|
| | EN | OUT | | POL | | | HYS | SYNC |
| Access | R/W | RO | | R/W | | | R/W | R/W |
| Reset | 0 | 0 | | 0 | | | 0 | 0 |

Bit 7 – EN Comparator Enable bit

| Value | Description |
|-------|---|
| 1 | Comparator is enabled |
| 0 | Comparator is disabled and consumes no active power |

Bit 6 – OUT Comparator Output bit

| Value | Condition | Description |
|-------|---|-------------|
| 1 | If POL = 0 (noninverted polarity): | CxVP > CxVN |
| 0 | If POL = 0 (noninverted polarity): | CxVP < CxVN |
| 1 | If POL = 1 (inverted polarity): | CxVP < CxVN |
| 0 | If POL = 1 (inverted polarity): | CxVP > CxVN |

Bit 4 – POL Comparator Output Polarity Select bit

| Value | Description |
|-------|-----------------------------------|
| 1 | Comparator output is inverted |
| 0 | Comparator output is not inverted |

Bit 1 – HYS Comparator Hysteresis Enable bit

| Value | Description |
|-------|--------------------------------|
| 1 | Comparator hysteresis enabled |
| 0 | Comparator hysteresis disabled |

Bit 0 – SYNC Comparator Output Synchronous Mode bit

Output updated on the falling edge of prescaled Timer1 clock.

| Value | Description |
|-------|---|
| 1 | Comparator output to Timer1 and I/O pin is synchronous to changes on the prescaled Timer1 clock |
| 0 | Comparator output to Timer1 and I/O pin is asynchronous |

34.15.2 CMxCON1

Name: CMxCON1
Address: 0xF35,0xF31

Comparator x Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|---|---|------|------|
| | | | | | | | INTP | INTN |
| Access | | | | | | | R/W | R/W |
| Reset | | | | | | | 0 | 0 |

Bit 1 – INTP Comparator Interrupt on Positive-Going Edge Enable bit

| Value | Description |
|-------|---|
| 1 | The CxIF interrupt flag will be set upon a positive-going edge of the CxOUT bit |
| 0 | No interrupt flag will be set on a positive-going edge of the CxOUT bit |

Bit 0 – INTN Comparator Interrupt on Negative-Going Edge Enable bit

| Value | Description |
|-------|---|
| 1 | The CxIF interrupt flag will be set upon a negative-going edge of the CxOUT bit |
| 0 | No interrupt flag will be set on a negative-going edge of the CxOUT bit |

34.15.3 CMxNCH

Name: CMxNCH
Address: 0xF36,0xF32

Comparator x Inverting Channel Select Register

| | | | | | | | | |
|--------|---|---|---|---|---|----------|-----|-----|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | NCH[2:0] | | |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | 0 | 0 | 0 |

Bits 2:0 – NCH[2:0] Comparator Inverting Input Channel Select bits

| NCH | Negative Input Sources |
|-----|------------------------|
| 111 | AVSS |
| 110 | FVR_Buffer2 |
| 101 | CxNCH not connected |
| 100 | CxNCH not connected |
| 011 | CxIN3- |
| 010 | CxIN2- |
| 001 | CxIN1- |
| 000 | CxIN0- |

34.15.4 CMxPCH

Name: CMxPCH
Address: 0xF37,0xF33

Comparator x Noninverting Channel Select Register

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|---|----------|-----|-----|
| | | | | | | PCH[2:0] | | |
| Access | | | | | | R/W | R/W | R/W |
| Reset | | | | | | 0 | 0 | 0 |

Bits 2:0 – PCH[2:0] Comparator Noninverting Input Channel Select bits

| PCH | Positive Input Source |
|-----|-----------------------|
| 111 | AVSS |
| 110 | FVR_Buffer2 |
| 101 | DAC_Output |
| 100 | CxPCH not connected |
| 011 | CxPCH not connected |
| 010 | CxPCH not connected |
| 001 | CxIN1+ |
| 000 | CxIN0+ |

34.15.5 CMOUT

Name: CMOUT
Address: 0xF38
Comparator Output Register

| | | | | | | | | |
|--------|---|---|---|---|---|---|--------|--------|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | | | | | | MC2OUT | MC1OUT |
| Access | | | | | | | RO | RO |
| Reset | | | | | | | 0 | 0 |

Bits 0, 1 – MCxOUT Mirror copy of CxOUT bit

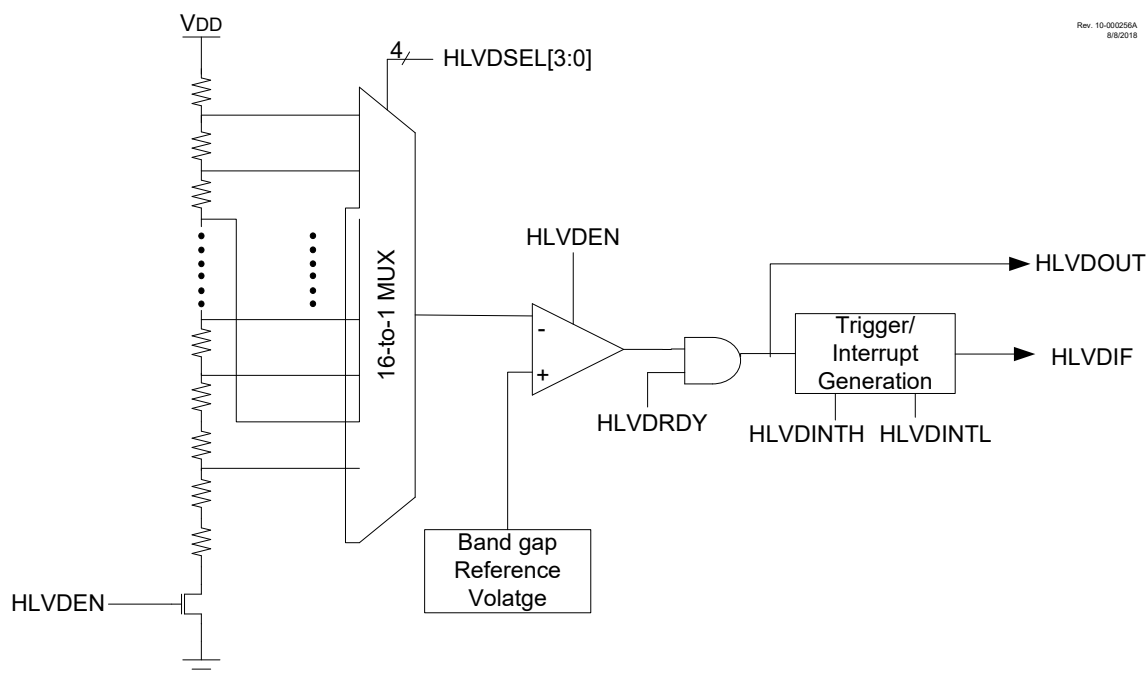
35. HLVD - High/Low-Voltage Detect

The HLVD module can be configured to monitor the device voltage. This is useful in battery monitoring applications.

Complete control of the HLVD module is provided through the [HLVDCON0](#) and [HLVDCON1](#) registers.

The module's block diagram is shown in the figure below.

Figure 35-1. HLVD Module Block Diagram



Since the HLVD can be software enabled through the HLVDEN bit, setting and clearing the enable bit does not produce a false HLVD event glitch. Each time the HLVD module is enabled, the [RDY](#) bit can be used to detect when the module is stable and ready to use.

The [INTH](#) and [INTL](#) bits determine the overall operation of the module. When [INTH](#) is set, the module monitors for rises in V_{DD} above the trip point set by the bits. When [INTL](#) is set, the module monitors for drops in V_{DD} below the trip point set by the [SEL](#) bits. When both the [INTH](#) and [INTL](#) bits are set, any changes above or below the trip point set by the [SEL](#) bits can be monitored.

The [OUT](#) bit can be read to determine if the voltage is greater than or less than the selected trip point.

35.1 Operation

When the HLVD module is enabled, a comparator uses an internally generated voltage reference as the set point. The set point is compared with the trip point, where each node in the resistor divider represents a trip point voltage. The “trip point” voltage is the voltage level at which the device detects a high or low-voltage event, depending on the configuration of the module.

When the supply voltage is equal to the trip point, the voltage tapped off of the resistor array is equal to the internal reference voltage generated by the voltage reference module. The comparator then generates an interrupt signal by setting the HLVDIF bit.

The trip point voltage is software programmable to any of 16 values. The trip point is selected by programming the [SEL](#) bits.

35.2 Setup

To set up the HLVD module:

1. Select the desired HLVD trip point by writing the value to the [SEL](#) bits of the HLVDCON1 register.
2. Depending on the application to detect high-voltage peaks or low-voltage drops or both, set the INTH or INTL bit appropriately.
3. Enable the HLVD module by setting the [EN](#) bit.
4. Clear the HLVD interrupt flag (HLVDIF), which may have been set from a previous interrupt.
5. If interrupts are desired, enable the HLVD interrupt by setting the HLVDIE and GIE bits.
An interrupt will not be generated until the [RDY](#) bit is set.



Important: Before changing any module settings (interrupts and tripping point), first disable the module ($EN = 0$), make the changes and re-enable the module. This prevents the generation of false HLVD events.

Related Links

[PIR2](#)

[PIR2](#)

[PIE3](#)

[PIE3](#)

35.3 Current Consumption

When the module is enabled, the HLVD comparator and voltage divider are enabled and consume static current. The total current consumption, when enabled, is specified in electrical specification Parameter D206.

Depending on the application, the HLVD module does not need to operate constantly. To reduce current consumption, the module can be enabled for short periods where the voltage is checked. After such a check, the module may be disabled.

Related Links

[Power-Down Current \(IPD\)\(1,2\)](#)

35.4 HLVD Start-up Time

If the HLVD or other circuits using the internal voltage reference are disabled to lower the device's current consumption, the reference voltage circuit will require time to become stable before a low or high-voltage condition can be reliably detected. This start-up time, T_{FVRS} , is an interval that is independent of device clock speed. It is specified in electrical specification.

The HLVD interrupt flag is not enabled until T_{FVRS} has expired and a stable reference voltage is reached. For this reason, brief excursions beyond the set point may not be detected during this interval (see the figures below).

Figure 35-2. Low-Voltage Detect Operation (INTL = 1)

Rev. 30-000141A
5/26/2017

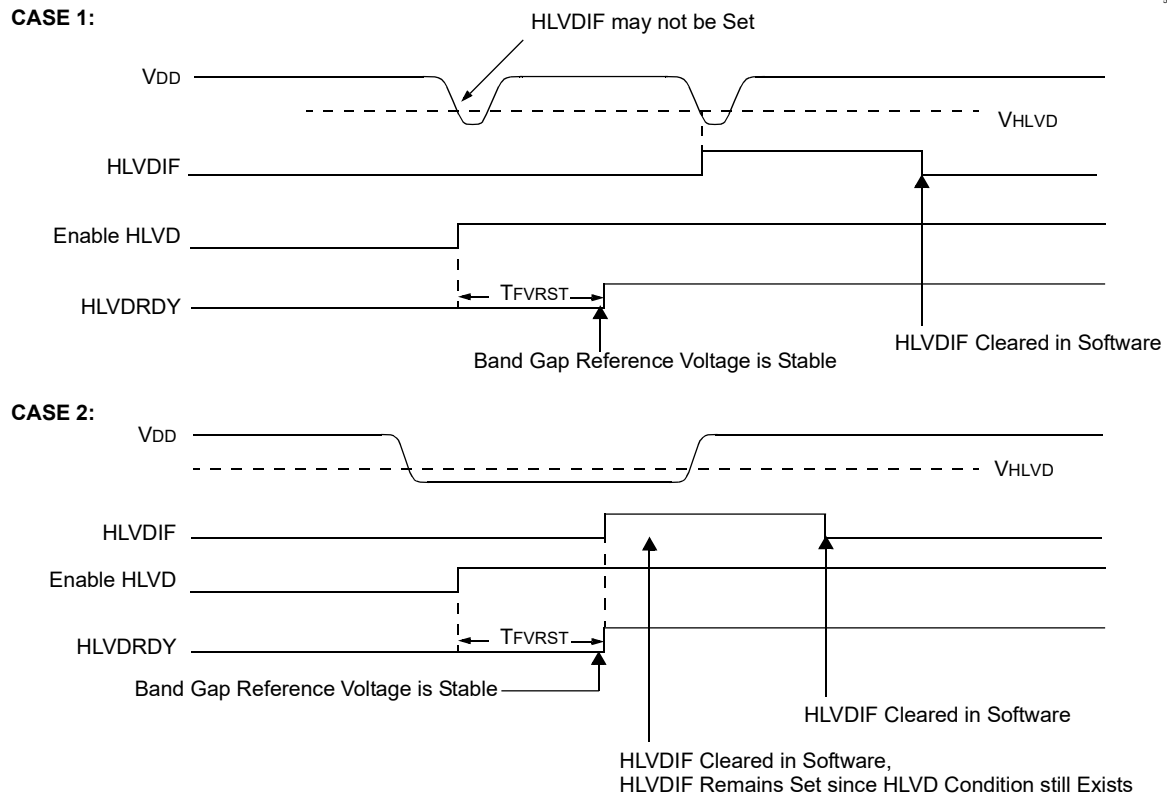
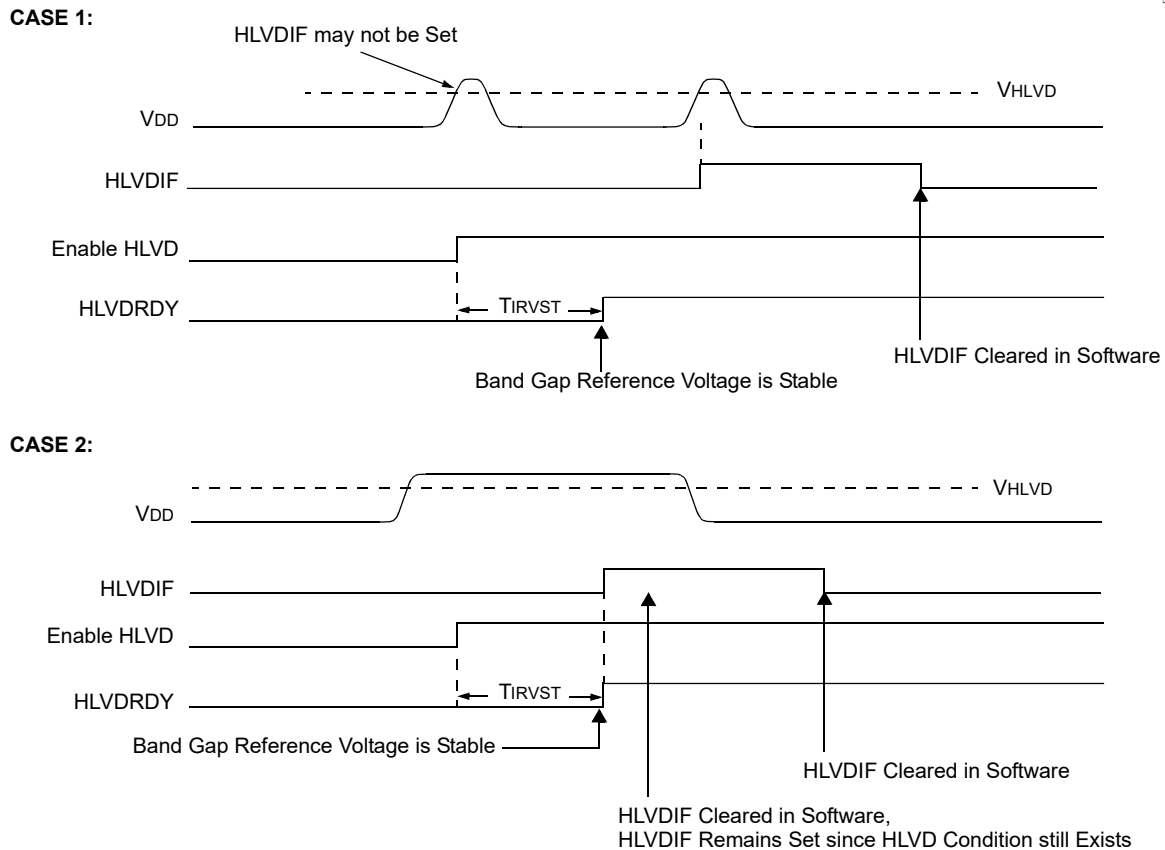


Figure 35-3. High-Voltage Detect Operation (INTH = 1)

Rev. 30-000142A
5/26/2017

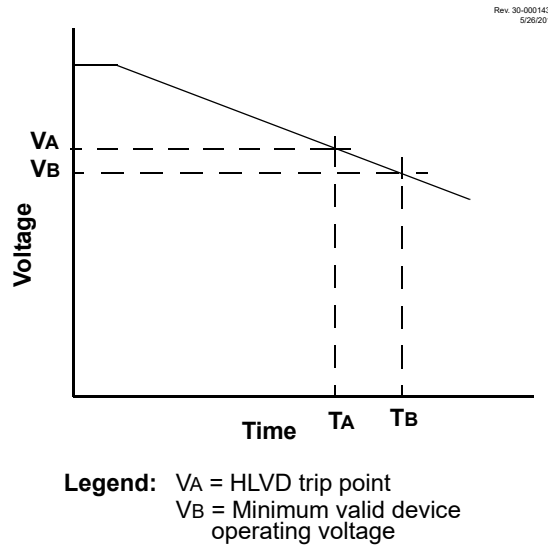


35.5 Applications

In many applications, it is desirable to detect a drop below, or rise above, a particular voltage threshold. For example, the HLVD module can be periodically enabled to detect Universal Serial Bus (USB) attach or detach. This assumes the device is powered by a lower voltage source than the USB when detached. An attach will indicate a High-Voltage Detect from, for example, 3.3V to 5V (the voltage on USB) and vice versa for a detach. This feature can save a design a few extra components and an attach signal (input pin).

For general battery applications, the figure below shows a possible voltage curve. Over time, the device voltage decreases. When the device voltage reaches voltage V_A , the HLVD logic generates an interrupt at time T_A . The interrupt can cause the execution of an Interrupt Service Routine (ISR), which will allow the application to perform “housekeeping tasks” and a controlled shutdown before the device voltage exits the valid operating range at T_B . This will give the application a time window, represented by the difference between T_A and T_B , to safely exit.

Figure 35-4. Typical Low-Voltage Detect Application



35.6 Operation During Sleep

When enabled, the HLVD circuitry continues to operate during Sleep. If the device voltage crosses the trip point, the HLVDIF bit will be set and the device will wake up from Sleep. Device execution will continue from the interrupt vector address if interrupts have been globally enabled.

35.7 Operation During Idle and Doze Modes

In both Idle and Doze modes, the module is active and events are generated if peripheral is enabled.

35.8 Effects of a Reset

A device Reset forces all registers to their Reset state. This forces the HLVD module to be turned off.

35.9 Register Summary - HLVD

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|--------------------------|----------|----|---|-----|-----|----------|---|------|------|
| 0x00 ... | Reserved | | | | | | | | | |
| 0x0F29 | | | | | | | | | | |
| 0x0F2A | HLVDCON0 | 7:0 | EN | | OUT | RDY | | | INTH | INTL |
| 0x0F2B | HLVDCON1 | 7:0 | | | | | SEL[3:0] | | | |

35.10 Register Definitions: HLVD Control

Long bit name prefixes for the HLVD peripheral is shown in the following table. Refer to the “**Long Bit Names**” section for more information.

Table 35-1. HLVD Long Bit Name Prefixes

| Peripheral | Bit Name Prefix |
|------------|-----------------|
| HLVD | HLVD |

Related Links

[Long Bit Names](#)

35.10.1 HLVDCON0

Name: HLVDCON0
Address: 0xF2A

High/Low-Voltage Detect Control Register 0

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----|---|-----|-----|---|---|------|------|
| | EN | | OUT | RDY | | | INTH | INTL |
| Access | R/W | | RO | RO | | | R/W | R/W |
| Reset | 0 | | x | x | | | 0 | 0 |

Bit 7 – EN High/Low-voltage Detect Power Enable bit

| Value | Description |
|-------|--------------------------|
| 1 | Enables the HLVD module |
| 0 | Disables the HLVD module |

Bit 5 – OUT HLVD Comparator Output bit

| Value | Description |
|-------|---|
| 1 | Voltage \leq selected detection limit (SEL) |
| 0 | Voltage \geq selected detection limit (SEL) |

Bit 4 – RDY Band Gap Reference Voltages Stable Status Flag bit

| Value | Description |
|-------|---|
| 1 | Indicates HLVD Module is ready and output is stable |
| 0 | Indicates HLVD Module is not ready |

Bit 1 – INTH HLVD Positive going (High Voltage) Interrupt Enable

| Value | Description |
|-------|---|
| 1 | HLVDIF will be set when voltage \geq selected detection limit (SEL) |
| 0 | HLVDIF will not be set |

Bit 0 – INTL HLVD Negative going (Low Voltage) Interrupt Enable

| Value | Description |
|-------|---|
| 1 | HLVDIF will be set when voltage \leq selected detection limit (SEL) |
| 0 | HLVDIF will not be set |

35.10.2 HLVDCON1

Name: HLVDCON1
Address: 0xF2B

Low-Voltage Detect Control Register 1

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|----------|-----|-----|-----|
| | | | | | SEL[3:0] | | | |
| Access | | | | | R/W | R/W | R/W | R/W |
| Reset | | | | | 0 | 0 | 0 | 0 |

Bits 3:0 – SEL[3:0] High/Low-Voltage Detection Limit Selection bits

Table 35-2. HLVD Detection Limits

| SEL | Detection Limit |
|--------------|---|
| 1111 | Reserved |
| 1110 to 0000 | See High/Low-voltage detect characteristics |

Reset States: POR/BOR = 0000
All other resets = uuuu

Related Links

[High/Low-Voltage Detect Characteristics](#)

36. Register Summary

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----------------------|-----------|----------|-------|-------|----------|-----------|-------|-----------|-------|-------|
| 0x00 ... 0x0E1E | Reserved | | | | | | | | | |
| 0x0E1F | CLCIN0PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E20 | CLCIN1PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E21 | CLCIN2PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E22 | CLCIN3PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E23 | CLCIN4PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E24 | CLCIN5PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E25 | CLCIN6PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E26 | CLCIN7PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | |
| 0x0E27 | CLC1CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E28 | CLC1POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E29 | CLC1SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E2A | CLC1SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E2B | CLC1SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E2C | CLC1SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E2D | CLC1GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E2E | CLC1GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E2F | CLC1GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E30 | CLC1GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E31 | CLC2CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E32 | CLC2POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E33 | CLC2SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E34 | CLC2SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E35 | CLC2SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E36 | CLC2SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E37 | CLC2GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E38 | CLC2GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E39 | CLC2GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E3A | CLC2GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E3B | CLC3CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E3C | CLC3POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E3D | CLC3SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E3E | CLC3SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E3F | CLC3SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E40 | CLC3SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E41 | CLC3GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E42 | CLC3GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E43 | CLC3GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E44 | CLC3GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E45 | CLC4CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E46 | CLC4POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E47 | CLC4SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E48 | CLC4SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E49 | CLC4SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E4A | CLC4SEL3 | 7:0 | | | D4S[5:0] | | | | | |
| 0x0E4B | CLC4GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N |
| 0x0E4C | CLC4GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N |
| 0x0E4D | CLC4GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N |
| 0x0E4E | CLC4GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N |
| 0x0E4F | CLC5CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | |
| 0x0E50 | CLC5POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL |
| 0x0E51 | CLC5SEL0 | 7:0 | | | D1S[5:0] | | | | | |
| 0x0E52 | CLC5SEL1 | 7:0 | | | D2S[5:0] | | | | | |
| 0x0E53 | CLC5SEL2 | 7:0 | | | D3S[5:0] | | | | | |
| 0x0E54 | CLC5SEL3 | 7:0 | | | D4S[5:0] | | | | | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------|------------|----------|-------------|---------|----------|-----------|-----------|-----------|---------|-----------|------|
| 0x0E55 | CLC5GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N | |
| 0x0E56 | CLC5GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N | |
| 0x0E57 | CLC5GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N | |
| 0x0E58 | CLC5GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N | |
| 0x0E59 | CLC6CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | | |
| 0x0E5A | CLC6POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL | |
| 0x0E5B | CLC6SEL0 | 7:0 | | | D1S[5:0] | | | | | | |
| 0x0E5C | CLC6SEL1 | 7:0 | | | D2S[5:0] | | | | | | |
| 0x0E5D | CLC6SEL2 | 7:0 | | | D3S[5:0] | | | | | | |
| 0x0E5E | CLC6SEL3 | 7:0 | | | D4S[5:0] | | | | | | |
| 0x0E5F | CLC6GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N | |
| 0x0E60 | CLC6GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N | |
| 0x0E61 | CLC6GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N | |
| 0x0E62 | CLC6GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N | |
| 0x0E63 | CLC7CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | | |
| 0x0E64 | CLC7POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL | |
| 0x0E65 | CLC7SEL0 | 7:0 | | | D1S[5:0] | | | | | | |
| 0x0E66 | CLC7SEL1 | 7:0 | | | D2S[5:0] | | | | | | |
| 0x0E67 | CLC7SEL2 | 7:0 | | | D3S[5:0] | | | | | | |
| 0x0E68 | CLC7SEL3 | 7:0 | | | D4S[5:0] | | | | | | |
| 0x0E69 | CLC7GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N | |
| 0x0E6A | CLC7GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N | |
| 0x0E6B | CLC7GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N | |
| 0x0E6C | CLC7GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N | |
| 0x0E6D | CLC8CON | 7:0 | EN | | OUT | INTP | INTN | MODE[2:0] | | | |
| 0x0E6E | CLC8POL | 7:0 | POL | | | | G4POL | G3POL | G2POL | G1POL | |
| 0x0E6F | CLC8SEL0 | 7:0 | | | D1S[5:0] | | | | | | |
| 0x0E70 | CLC8SEL1 | 7:0 | | | D2S[5:0] | | | | | | |
| 0x0E71 | CLC8SEL2 | 7:0 | | | D3S[5:0] | | | | | | |
| 0x0E72 | CLC8SEL3 | 7:0 | | | D4S[5:0] | | | | | | |
| 0x0E73 | CLC8GLS0 | 7:0 | G1D4T | G1D4N | G1D3T | G1D3N | G1D2T | G1D2N | G1D1T | G1D1N | |
| 0x0E74 | CLC8GLS1 | 7:0 | G2D4T | G2D4N | G2D3T | G2D3N | G2D2T | G2D2N | G2D1T | G2D1N | |
| 0x0E75 | CLC8GLS2 | 7:0 | G3D4T | G3D4N | G3D3T | G3D3N | G3D2T | G3D2N | G3D1T | G3D1N | |
| 0x0E76 | CLC8GLS3 | 7:0 | G4D4T | G4D4N | G4D3T | G4D3N | G4D2T | G4D2N | G4D1T | G4D1N | |
| 0x0E77 | CLCDATA | 7:0 | MLC8OUT | MLC7OUT | MLC6OUT | MLC5OUT | MLC4OUT | MLC3OUT | MLC2OUT | MLC1OUT | |
| 0x0E78 | Reserved | | | | | | | | | | |
| ... | | | | | | | | | | | |
| 0x0E87 | | | | | | | | | | | |
| 0x0E88 | RX2PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | | |
| 0x0E89 | CK2PPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | | |
| 0x0E8A | SSP2CLKPPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | | |
| 0x0E8B | SSP2DATPPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | | |
| 0x0E8C | SSP2SPPS | 7:0 | | | | PORT[1:0] | | PIN[2:0] | | | |
| 0x0E8D | SSP2BUF | 7:0 | BUF[7:0] | | | | | | | | |
| 0x0E8E | SSP2ADD | 7:0 | ADD[7:0] | | | | | | | | |
| 0x0E8F | SSP2MSK | 7:0 | MSK[6:0] | | | | | | | | MSK0 |
| 0x0E90 | SSP2STAT | 7:0 | SMP | CKE | D/Ā | P | S | R/Ā | UA | BF | |
| 0x0E91 | SSP2CON1 | 7:0 | WCOL | SSPOV | SSPEN | CKP | SSPM[3:0] | | | | |
| 0x0E92 | SSP2CON2 | 7:0 | GCEN | ACKSTAT | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN | |
| 0x0E93 | SSP2CON3 | 7:0 | ACKTIM | PCIE | SCIE | BOEN | SDAHT | SBCDE | AHEN | DHEN | |
| 0x0E94 | RC2REG | 7:0 | RCREG[7:0] | | | | | | | | |
| 0x0E95 | TX2REG | 7:0 | TXREG[7:0] | | | | | | | | |
| 0x0E96 | SP2BRG | 7:0 | SPBRG[7:0] | | | | | | | | |
| | | 15:8 | SPBRG[15:8] | | | | | | | | |
| 0x0E98 | RC2STA | 7:0 | SPEN | RX9 | SREN | CREN | ADDEN | FERR | OERR | RX9D | |
| 0x0E99 | TX2STA | 7:0 | CSRC | TX9 | TXEN | SYNC | SENDB | BRGH | TRMT | TX9D | |
| 0x0E9A | BAUD2CON | 7:0 | ABDOVF | RCIDL | | SCKP | BRG16 | | WUE | ABDEN | |
| 0x0E9B | PPSLOCK | 7:0 | | | | | | | | PPSLOCKED | |
| 0x0E9C | INT0PPS | 7:0 | | | | | PORT | PIN[2:0] | | | |
| 0x0E9D | INT1PPS | 7:0 | | | | | PORT | PIN[2:0] | | | |

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| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|------------|----------|---------|---------|-------------|-----------|-------------|------------|-------------|---------|
| 0x0E9E | INT2PPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0E9F | T0CKIPPS | 7:0 | | | | | PORT | | PIN[2:0] | |
| 0x0EA0 | T1CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA1 | T1GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA2 | T3CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA3 | T3GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA4 | T5CKIPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA5 | T5GPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA6 | T2INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA7 | T4INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA8 | T6INPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EA9 | ADACTPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAA | CCP1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAB | CCP2PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAC | CWG1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAD | MDCARLPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAE | MDCARHPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EAF | MDSRCPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB0 | RX1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB1 | CK1PPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB2 | SSP1CLKPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB3 | SSP1DATPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB4 | SSP1SSPPS | 7:0 | | | | PORT[1:0] | | | PIN[2:0] | |
| 0x0EB5 | IPR0 | 7:0 | | | TMR0IP | IOCIP | | INT2IP | INT1IP | INT0IP |
| 0x0EB6 | IPR1 | 7:0 | OSCFIP | CSWIP | | | | | ADTIP | ADIP |
| 0x0EB7 | IPR2 | 7:0 | HLVDIP | ZCDIP | | | | | C2IP | C1IP |
| 0x0EB8 | IPR3 | 7:0 | RC2IP | TX2IP | RC1IP | TX1IP | BCL2IP | SSP2IP | BCL1IP | SSP1IP |
| 0x0EB9 | IPR4 | 7:0 | | | TMR6IP | TMR5IP | TMR4IP | TMR3IP | TMR2IP | TMR1IP |
| 0x0EBA | IPR5 | 7:0 | CLC4IP | CLC3IP | CLC2IP | CLC1IP | | TMR5GIP | TMR3GIP | TMR1GIP |
| 0x0EBB | IPR6 | 7:0 | CLC8IP | CLC7IP | CLC6IP | CLC5IP | | | CCP2IP | CCP1IP |
| 0x0EBC | IPR7 | 7:0 | SCANIP | CRCIP | NVMIP | | | | | CWG1IP |
| 0x0EBD | PIE0 | 7:0 | | | TMR0IE | IOCIE | | INT2IE | INT1IE | INT0IE |
| 0x0EBE | PIE1 | 7:0 | OSCFIE | CSWIE | | | | | ADTIE | ADIE |
| 0x0EBF | PIE2 | 7:0 | HLVDIE | ZCDIE | | | | | C2IE | C1IE |
| 0x0EC0 | PIE3 | 7:0 | RC2IE | TX2IE | RC1IE | TX1IE | BCL2IE | SSP2IE | BCL1IE | SSP1IE |
| 0x0EC1 | PIE4 | 7:0 | | | TMR6IE | TMR5IE | TMR4IE | TMR3IE | TMR2IE | TMR1IE |
| 0x0EC2 | PIE5 | 7:0 | CLC4IE | CLC3IE | CLC2IE | CLC1IE | | TMR5GIE | TMR3GIE | TMR1GIE |
| 0x0EC3 | PIE6 | 7:0 | CLC8IE | CLC7IE | CLC6IE | CLC5IE | | | CCP2IE | CCP1IE |
| 0x0EC4 | PIE7 | 7:0 | SCANIE | CRCIE | NVMIE | | | | | CWG1IE |
| 0x0EC5 | PIR0 | 7:0 | | | TMR0IF | IOCIF | | INT2IF | INT1IF | INT0IF |
| 0x0EC6 | PIR1 | 7:0 | OSCFIF | CSWIF | | | | | ADTIF | ADIF |
| 0x0EC7 | PIR2 | 7:0 | HLVDIF | ZCDIF | | | | | C2IF | C1IF |
| 0x0EC8 | PIR3 | 7:0 | RC2IF | TX2IF | RC1IF | TX1IF | BCL2IF | SSP2IF | BCL1IF | SSP1IF |
| 0x0EC9 | PIR4 | 7:0 | | | TMR6IF | TMR5IF | TMR4IF | TMR3IF | TMR2IF | TMR1IF |
| 0x0ECA | PIR5 | 7:0 | CLC4IF | CLC3IF | CLC2IF | CLC1IF | | TMR5GIF | TMR3GIF | TMR1GIF |
| 0x0ECB | PIR6 | 7:0 | CLC8IF | CLC7IF | CLC6IF | CLC5IF | | | CCP2IF | CCP1IF |
| 0x0ECC | PIR7 | 7:0 | SCANIF | CRCIF | NVMIF | | | | | CWG1IF |
| 0x0ECD | WDTCON0 | 7:0 | | | | | WDTPS[4:0] | | | SEN |
| 0x0ECE | WDTCON1 | 7:0 | | | WDTCS[2:0] | | | | WINDOW[2:0] | |
| 0x0ECF | WDTPSL | 7:0 | | | | | PSCNTL[7:0] | | | |
| 0x0ED0 | WDTPSH | 7:0 | | | | | PSCNTH[7:0] | | | |
| 0x0ED1 | WDTTMR | 7:0 | | | WDTTMR[4:0] | | | STATE | PSCNT[1:0] | |
| 0x0ED2 | CPUDOZE | 7:0 | IDLEN | DOZEN | ROI | DOE | | | DOZE[2:0] | |
| 0x0ED3 | OSCCON1 | 7:0 | | | NOSC[2:0] | | | | NDIV[3:0] | |
| 0x0ED4 | OSCCON2 | 7:0 | | | COSC[2:0] | | | | CDIV[3:0] | |
| 0x0ED5 | OSCCON3 | 7:0 | CSWHOLD | SOSCPWR | | ORDY | NOSCR | | | |
| 0x0ED6 | OSCSTAT | 7:0 | EXTOR | HFOR | MFOR | LFOR | SOR | ADOR | | PLL |
| 0x0ED7 | OSCEN | 7:0 | EXTOEN | HFOEN | MFOEN | LFOEN | SOSCEN | ADOEN | | |
| 0x0ED8 | OSCTUNE | 7:0 | | | | | HFTUN[5:0] | | | |
| 0x0ED9 | OSCFRQ | 7:0 | | | | | | HFFRQ[3:0] | | |

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| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|---------|----------|---------|---------|------------|---------|---------|----------|-------------|---------|
| 0x0EDA | VREGCON | 7:0 | | | PMSYS[1:0] | | | | VREGPM[1:0] | |
| 0x0EDB | BORCON | 7:0 | SBOREN | | | | | | | BORRDY |
| 0x0EDC | PMD0 | 7:0 | SYSCMD | FVRMD | HLVDMD | CRCMD | SCANMD | NVMMD | CLKRMD | IOCMD |
| 0x0EDD | PMD1 | 7:0 | | TMR6MD | TMR5MD | TMR4MD | TMR3MD | TMR2MD | TMR1MD | TMR0MD |
| 0x0EDE | PMD2 | 7:0 | | DACMD | ADCMD | | | CMP2MD | CMP1MD | ZCDMD |
| 0x0EDF | PMD3 | 7:0 | CLC8MD | CLC7MD | CLC6MD | CLC5MD | PWM4MD | PWM3MD | CCP2MD | CCP1MD |
| 0x0EE0 | PMD4 | 7:0 | UART2MD | UART1MD | MSSP2MD | MSSP1MD | | | | CWG1MD |
| 0x0EE1 | PMD5 | 7:0 | CLC4MD | CLC3MD | CLC2MD | CLC1MD | | | | DSMMD |
| 0x0EE2 | RA0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE3 | RA1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE4 | RA2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE5 | RA3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE6 | RA4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE7 | RA5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE8 | RA6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EE9 | RA7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEA | RB0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEB | RB1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEC | RB2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EED | RB3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEE | RB4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EEF | RB5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF0 | RB6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF1 | RB7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF2 | RC0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF3 | RC1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF4 | RC2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF5 | RC3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF6 | RC4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF7 | RC5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF8 | RC6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EF9 | RC7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFA | RD0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFB | RD1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFC | RD2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0efd | RD3PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFE | RD4PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0EFF | RD5PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F00 | RD6PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F01 | RD7PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F02 | RE0PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F03 | RE1PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F04 | RE2PPS | 7:0 | | | | | | PPS[4:0] | | |
| 0x0F05 | IOCAF | 7:0 | IOCAF7 | IOCAF6 | IOCAF5 | IOCAF4 | IOCAF3 | IOCAF2 | IOCAF1 | IOCAF0 |
| 0x0F06 | IOCAN | 7:0 | IOCAN7 | IOCAN6 | IOCAN5 | IOCAN4 | IOCAN3 | IOCAN2 | IOCAN1 | IOCAN0 |
| 0x0F07 | IOCAP | 7:0 | IOCAP7 | IOCAP6 | IOCAP5 | IOCAP4 | IOCAP3 | IOCAP2 | IOCAP1 | IOCAP0 |
| 0x0F08 | INLVLA | 7:0 | INLVLA7 | INLVLA6 | INLVLA5 | INLVLA4 | INLVLA3 | INLVLA2 | INLVLA1 | INLVLA0 |
| 0x0F09 | SLRCONA | 7:0 | SLRA7 | SLRA6 | SLRA5 | SLRA4 | SLRA3 | SLRA2 | SLRA1 | SLRA0 |
| 0x0F0A | ODCONA | 7:0 | ODCA7 | ODCA6 | ODCA5 | ODCA4 | ODCA3 | ODCA2 | ODCA1 | ODCA0 |
| 0x0F0B | WPUA | 7:0 | WPUA7 | WPUA6 | WPUA5 | WPUA4 | WPUA3 | WPUA2 | WPUA1 | WPUA0 |
| 0x0F0C | ANSELA | 7:0 | ANSELA7 | ANSELA6 | ANSELA5 | ANSELA4 | ANSELA3 | ANSELA2 | ANSELA1 | ANSELA0 |
| 0x0F0D | IOCBF | 7:0 | IOCBF7 | IOCBF6 | IOCBF5 | IOCBF4 | IOCBF3 | IOCBF2 | IOCBF1 | IOCBF0 |
| 0x0F0E | IOCBN | 7:0 | IOCBN7 | IOCBN6 | IOCBN5 | IOCBN4 | IOCBN3 | IOCBN2 | IOCBN1 | IOCBN0 |
| 0x0F0F | IOCBP | 7:0 | IOCBP7 | IOCBP6 | IOCBP5 | IOCBP4 | IOCBP3 | IOCBP2 | IOCBP1 | IOCBP0 |
| 0x0F10 | INLVLB | 7:0 | INLVLB7 | INLVLB6 | INLVLB5 | INLVLB4 | INLVLB3 | INLVLB2 | INLVLB1 | INLVLB0 |
| 0x0F11 | SLRCONB | 7:0 | SLRB7 | SLRB6 | SLRB5 | SLRB4 | SLRB3 | SLRB2 | SLRB1 | SLRB0 |
| 0x0F12 | ODCONB | 7:0 | ODCB7 | ODCB6 | ODCB5 | ODCB4 | ODCB3 | ODCB2 | ODCB1 | ODCB0 |
| 0x0F13 | WPUB | 7:0 | WPUB7 | WPUB6 | WPUB5 | WPUB4 | WPUB3 | WPUB2 | WPUB1 | WPUB0 |
| 0x0F14 | ANSELB | 7:0 | ANSELB7 | ANSELB6 | ANSELB5 | ANSELB4 | ANSELB3 | ANSELB2 | ANSELB1 | ANSELB0 |
| 0x0F15 | IOCCF | 7:0 | IOCCF7 | IOCCF6 | IOCCF5 | IOCCF4 | IOCCF3 | IOCCF2 | IOCCF1 | IOCCF0 |

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| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------|----------|----------------|---------|-----------|----------------|-------------|-----------|------------|---------|
| 0x0F16 | IOCCN | 7:0 | IOCCN7 | IOCCN6 | IOCCN5 | IOCCN4 | IOCCN3 | IOCCN2 | IOCCN1 | IOCCN0 |
| 0x0F17 | IOCCP | 7:0 | IOCCP7 | IOCCP6 | IOCCP5 | IOCCP4 | IOCCP3 | IOCCP2 | IOCCP1 | IOCCP0 |
| 0x0F18 | INLVLC | 7:0 | INLVLC7 | INLVLC6 | INLVLC5 | INLVLC4 | INLVLC3 | INLVLC2 | INLVLC1 | INLVLC0 |
| 0x0F19 | SLRCONC | 7:0 | SLRC7 | SLRC6 | SLRC5 | SLRC4 | SLRC3 | SLRC2 | SLRC1 | SLRC0 |
| 0x0F1A | ODCONC | 7:0 | ODCC7 | ODCC6 | ODCC5 | ODCC4 | ODCC3 | ODCC2 | ODCC1 | ODCC0 |
| 0x0F1B | WPUC | 7:0 | WPUC7 | WPUC6 | WPUC5 | WPUC4 | WPUC3 | WPUC2 | WPUC1 | WPUC0 |
| 0x0F1C | ANSELC | 7:0 | ANSELC7 | ANSELC6 | ANSELC5 | ANSELC4 | ANSELC3 | ANSELC2 | ANSELC1 | ANSELC0 |
| 0x0F1D | INLVLD | 7:0 | INLVLD7 | INLVLD6 | INLVLD5 | INLVLD4 | INLVLD3 | INLVLD2 | INLVLD1 | INLVLD0 |
| 0x0F1E | SLRCOND | 7:0 | SLRD7 | SLRD6 | SLRD5 | SLRD4 | SLRD3 | SLRD2 | SLRD1 | SLRD0 |
| 0x0F1F | ODCOND | 7:0 | ODCD7 | ODCD6 | ODCD5 | ODCD4 | ODCD3 | ODCD2 | ODCD1 | ODCD0 |
| 0x0F20 | WPUD | 7:0 | WPUD7 | WPUD6 | WPUD5 | WPUD4 | WPUD3 | WPUD2 | WPUD1 | WPUD0 |
| 0x0F21 | ANSELD | 7:0 | ANSELD7 | ANSELD6 | ANSELD5 | ANSELD4 | ANSELD3 | ANSELD2 | ANSELD1 | ANSELD0 |
| 0x0F22 | IOCEF | 7:0 | | | | | IOCEF3 | | | |
| 0x0F23 | IOCEM | 7:0 | | | | | IOCEM3 | | | |
| 0x0F24 | IOCEP | 7:0 | | | | | IOCEP3 | | | |
| 0x0F25 | INLVLE | 7:0 | | | | | INLVLE3 | | | |
| 0x0F26 | SLRCONE | 7:0 | | | | | | SLRE2 | SLRE1 | SLRE0 |
| 0x0F27 | ODCONE | 7:0 | | | | | | ODCE2 | ODCE1 | ODCE0 |
| 0x0F28 | WPUE | 7:0 | | | | | WPUE3 | | | |
| 0x0F29 | ANSELE | 7:0 | | | | | | ANSELE2 | ANSELE1 | ANSELE0 |
| 0x0F2A | HLVDON0 | 7:0 | EN | | OUT | RDY | | | INTH | INTL |
| 0x0F2B | HLVDON1 | 7:0 | | | | | SEL[3:0] | | | |
| 0x0F2C | FVRCON | 7:0 | FVREN | FVRRDY | TSEN | TSRNG | CDAFVR[1:0] | | ADFVR[1:0] | |
| 0x0F2D | ZCDCON | 7:0 | SEN | | OUT | POL | | | INTP | INTN |
| 0x0F2E | DAC1CON0 | 7:0 | EN | | OE1 | OE2 | PSS[1:0] | | | NSS |
| 0x0F2F | DAC1CON1 | 7:0 | | | | | DAC1R[4:0] | | | |
| 0x0F30 | CM2CON0 | 7:0 | EN | OUT | | POL | | | HYS | SYNC |
| 0x0F31 | CM2CON1 | 7:0 | | | | | | | INTP | INTN |
| 0x0F32 | CM2NCH | 7:0 | | | | | | NCH[2:0] | | |
| 0x0F33 | CM2PCH | 7:0 | | | | | | PCH[2:0] | | |
| 0x0F34 | CM1CON0 | 7:0 | EN | OUT | | POL | | | HYS | SYNC |
| 0x0F35 | CM1CON1 | 7:0 | | | | | | | INTP | INTN |
| 0x0F36 | CM1NCH | 7:0 | | | | | | NCH[2:0] | | |
| 0x0F37 | CM1PCH | 7:0 | | | | | | PCH[2:0] | | |
| 0x0F38 | CMOUT | 7:0 | | | | | | | MC2OUT | MC1OUT |
| 0x0F39 | CLKRCON | 7:0 | EN | | | DC[1:0] | | DIV[2:0] | | |
| 0x0F3A | CLKRCLK | 7:0 | | | | | CLK[3:0] | | | |
| 0x0F3B | CWG1CLK | 7:0 | | | | | | | | CS |
| 0x0F3C | CWG1ISM | 7:0 | | | | | ISM[3:0] | | | |
| 0x0F3D | CWG1DBR | 7:0 | | | | DBR[5:0] | | | | |
| 0x0F3E | CWG1DBF | 7:0 | | | | DBF[5:0] | | | | |
| 0x0F3F | CWG1CON0 | 7:0 | EN | LD | | | | MODE[2:0] | | |
| 0x0F40 | CWG1CON1 | 7:0 | | | IN | | POLD | POLC | POLB | POLA |
| 0x0F41 | CWG1AS0 | 7:0 | SHUTDOWN | REN | LSBD[1:0] | | LSAC[1:0] | | | |
| 0x0F42 | CWG1AS1 | 7:0 | AS7E | AS6E | AS5E | AS4E | AS3E | AS2E | AS1E | AS0E |
| 0x0F43 | CWG1STR | 7:0 | OVRD | OVRC | OVRE | OVRA | STRD | STRC | STRB | STRA |
| 0x0F44 | SCANLADR | 7:0 | SCANLADRL[7:0] | | | | | | | |
| | | 15:8 | SCANLADRH[7:0] | | | | | | | |
| | | 23:16 | | | | SCANLADRU[5:0] | | | | |
| 0x0F47 | SCANHADR | 7:0 | SCANHADRL[7:0] | | | | | | | |
| | | 15:8 | SCANHADRH[7:0] | | | | | | | |
| | | 23:16 | | | | SCANHADRU[5:0] | | | | |
| 0x0F4A | SCANCON0 | 7:0 | SCANEN | SCANGO | BUSY | INVALID | INTM | | MODE[1:0] | |
| 0x0F4B | SCANTRIG | 7:0 | | | | TSEL[4:0] | | | | |
| 0x0F4C | MDCON0 | 7:0 | EN | | OUT | OPOL | | | | BIT |
| 0x0F4D | MDCON1 | 7:0 | | | CHPOL | CHSYNC | | | CLPOL | CLSYNC |
| 0x0F4E | MDSRC | 7:0 | | | | SRCS[4:0] | | | | |
| 0x0F4F | MDCARL | 7:0 | | | | | CLS[3:0] | | | |
| 0x0F50 | MDCARH | 7:0 | | | | | CHS[3:0] | | | |
| 0x0F51 | ADACT | 7:0 | | | | ADACT[4:0] | | | | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------|----------|----------|----------------|--------|--------------|------------|--------------|-------------|-------------|---------|----------|
| 0x0F52 | ADCLK | 7:0 | | | ADCS[5:0] | | | | | | |
| 0x0F53 | ADREF | 7:0 | | | | ADNREF | | | ADPREF[1:0] | | |
| 0x0F54 | ADCON1 | 7:0 | ADPPOL | ADIPEN | ADGPOL | | | | | ADDSSEN | |
| 0x0F55 | ADCON2 | 7:0 | ADPSIS | | ADCRS[2:0] | | ADACLR | | ADMMD[2:0] | | |
| 0x0F56 | ADCON3 | 7:0 | | | ADCALC[2:0] | | ADSOI | | ADTMD[2:0] | | |
| 0x0F57 | ADACQ | 7:0 | ADACQ[7:0] | | | | | | | | |
| 0x0F58 | ADCAP | 7:0 | | | | ADCAP[4:0] | | | | | |
| 0x0F59 | ADPRE | 7:0 | ADPRE[7:0] | | | | | | | | |
| 0x0F5A | ADPCH | 7:0 | | | ADPCH[5:0] | | | | | | |
| 0x0F5B | ADCON0 | 7:0 | ADON | ADCONT | | ADCS | | ADFM | | ADGO | |
| 0x0F5C | ADPREV | 7:0 | ADPREVL[7:0] | | | | | | | | |
| | | 15:8 | ADPREVH[7:0] | | | | | | | | |
| 0x0F5E | ADRES | 7:0 | ADRESL[7:0] | | | | | | | | |
| | | 15:8 | ADRESH[7:0] | | | | | | | | |
| 0x0F60 | ADSTAT | 7:0 | ADAOV | ADUTHR | ADLTHR | ADMATH | | ADSTAT[2:0] | | | |
| 0x0F61 | ADRPT | 7:0 | ADRPT[7:0] | | | | | | | | |
| 0x0F62 | ADCNT | 7:0 | ADCNT[7:0] | | | | | | | | |
| 0x0F63 | ADSTPT | 7:0 | ADSTPTL[7:0] | | | | | | | | |
| | | 15:8 | ADSTPTH[7:0] | | | | | | | | |
| 0x0F65 | ADLTH | 7:0 | ADLTHL[7:0] | | | | | | | | |
| | | 15:8 | ADLTHH[7:0] | | | | | | | | |
| 0x0F67 | ADUTH | 7:0 | ADUTHL[7:0] | | | | | | | | |
| | | 15:8 | ADUTHH[7:0] | | | | | | | | |
| 0x0F69 | ADERR | 7:0 | ADERRL[7:0] | | | | | | | | |
| | | 15:8 | ADERRH[7:0] | | | | | | | | |
| 0x0F6B | ADACC | 7:0 | ADACCL[7:0] | | | | | | | | |
| | | 15:8 | ADACCH[7:0] | | | | | | | | |
| 0x0F6D | ADFLTR | 7:0 | ADFLTRL[7:0] | | | | | | | | |
| | | 15:8 | ADFLTRH[7:0] | | | | | | | | |
| 0x0F6F | CRCDAT | 7:0 | CRCDATL[7:0] | | | | | | | | |
| | | 15:8 | CRCDATH[7:0] | | | | | | | | |
| 0x0F71 | CRCACC | 7:0 | CRCACCL[7:0] | | | | | | | | |
| | | 15:8 | CRCACCH[7:0] | | | | | | | | |
| 0x0F73 | CRCSHIFT | 7:0 | CRCSHIFTL[7:0] | | | | | | | | |
| | | 15:8 | CRCSHIFTH[7:0] | | | | | | | | |
| 0x0F75 | CRCXOR | 7:0 | CRCXORL[6:0] | | | | | | | | CRCXORL0 |
| | | 15:8 | CRCXORH[7:0] | | | | | | | | |
| 0x0F77 | CRCCON0 | 7:0 | EN | GO | BUSY | ACCM | | | SHIFTM | FULL | |
| 0x0F78 | CRCCON1 | 7:0 | DLEN[3:0] | | | | PLEN[3:0] | | | | |
| 0x0F79 | NVMADR | 7:0 | | | | | NVMADRL[7:0] | | | | |
| | | 15:8 | | | | | NVMADRH[7:0] | | | | |
| | | 23:16 | | | NVMADRU[5:0] | | | | | | |
| 0x0F7C | NVMDAT | 7:0 | | | | | NVMDATL[7:0] | | | | |
| | | 15:8 | | | | | NVMDATH[7:0] | | | | |
| 0x0F7E | Reserved | | | | | | | | | | |
| 0x0F7F | NVMCON0 | 7:0 | NVMEN | | | NVMERR | Reserved | | | | |
| 0x0F80 | NVMCON1 | 7:0 | | SECEM | SECWR | WR | | | SECRD | RD | |
| 0x0F81 | NVMCON2 | 7:0 | NVMCON2[7:0] | | | | | | | | |
| 0x0F82 | LATA | 7:0 | LATA7 | LATA6 | LATA5 | LATA4 | LATA3 | LATA2 | LATA1 | LATA0 | |
| 0x0F83 | LATB | 7:0 | LATB7 | LATB6 | LATB5 | LATB4 | LATB3 | LATB2 | LATB1 | LATB0 | |
| 0x0F84 | LATC | 7:0 | LATC7 | LATC6 | LATC5 | LATC4 | LATC3 | LATC2 | LATC1 | LATC0 | |
| 0x0F85 | LATD | 7:0 | LATD7 | LATD6 | LATD5 | LATD4 | LATD3 | LATD2 | LATD1 | LATD0 | |
| 0x0F86 | LATE | 7:0 | | | | | | LATE2 | LATE1 | LATE0 | |
| 0x0F87 | TRISA | 7:0 | TRISA7 | TRISA6 | TRISA5 | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 | |
| 0x0F88 | TRISB | 7:0 | TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 | |
| 0x0F89 | TRISC | 7:0 | TRISC7 | TRISC6 | TRISC5 | TRISC4 | TRISC3 | TRISC2 | TRISC1 | TRISC0 | |
| 0x0F8A | TRISD | 7:0 | TRISD7 | TRISD6 | TRISD5 | TRISD4 | TRISD3 | TRISD2 | TRISD1 | TRISD0 | |
| 0x0F8B | TRISE | 7:0 | | | | | TRISE3 | TRISE2 | TRISE1 | TRISE0 | |
| 0x0F8C | PORTA | 7:0 | RA7 | RA6 | RA5 | RA4 | RA3 | RA2 | RA1 | RA0 | |
| 0x0F8D | PORTB | 7:0 | RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------|----------|----------|-------------|-----------|-------------|-----------|-------------|-------|-------------|-------|------|
| 0x0F8E | PORTC | 7:0 | RC7 | RC6 | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 | |
| 0x0F8F | PORTD | 7:0 | RD7 | RD6 | RD5 | RD4 | RD3 | RD2 | RD1 | RD0 | |
| 0x0F90 | PORTE | 7:0 | | | | | RE3 | RE2 | RE1 | RE0 | |
| 0x0F91 | SSP1BUF | 7:0 | BUF[7:0] | | | | | | | | |
| 0x0F92 | SSP1ADD | 7:0 | ADD[7:0] | | | | | | | | |
| 0x0F93 | SSP1MSK | 7:0 | MSK[6:0] | | | | | | | | MSK0 |
| 0x0F94 | SSP1STAT | 7:0 | SMP | CKE | D/Ā | P | S | R/W | UA | BF | |
| 0x0F95 | SSP1CON1 | 7:0 | WCOL | SSPOV | SSPEN | CKP | SSPM[3:0] | | | | |
| 0x0F96 | SSP1CON2 | 7:0 | GCEN | ACKSTAT | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN | |
| 0x0F97 | SSP1CON3 | 7:0 | ACKTIM | PCIE | SCIE | BOEN | SDAHT | SBCDE | AHEN | DHEN | |
| 0x0F98 | RC1REG | 7:0 | RCREG[7:0] | | | | | | | | |
| 0x0F99 | TX1REG | 7:0 | TXREG[7:0] | | | | | | | | |
| 0x0F9A | SP1BRG | 7:0 | SPBRG[7:0] | | | | | | | | |
| | | 15:8 | SPBRG[15:8] | | | | | | | | |
| 0x0F9C | RC1STA | 7:0 | SPEN | RX9 | SREN | CREN | ADDEN | FERR | OERR | RX9D | |
| 0x0F9D | TX1STA | 7:0 | CSRC | TX9 | TXEN | SYNC | SENDB | BRGH | TRMT | TX9D | |
| 0x0F9E | BAUD1CON | 7:0 | ABDOVF | RCIDL | | SCKP | BRG16 | | WUE | ABDEN | |
| 0x0F9F | PWM4DC | 7:0 | DCL[1:0] | | | | | | | | |
| | | 15:8 | DCH[7:0] | | | | | | | | |
| 0x0FA1 | PWM4CON | 7:0 | EN | | OUT | POL | | | | | |
| 0x0FA2 | PWM3DC | 7:0 | DCL[1:0] | | | | | | | | |
| | | 15:8 | DCH[7:0] | | | | | | | | |
| 0x0FA4 | PWM3CON | 7:0 | EN | | OUT | POL | | | | | |
| 0x0FA5 | CCPR2 | 7:0 | CCPR[7:0] | | | | | | | | |
| | | 15:8 | CCPR[15:8] | | | | | | | | |
| 0x0FA7 | CCP2CON | 7:0 | EN | | OUT | FMT | MODE[3:0] | | | | |
| 0x0FA8 | CCP2CAP | 7:0 | | | | | CTS[3:0] | | | | |
| 0x0FA9 | CCPR1 | 7:0 | CCPR[7:0] | | | | | | | | |
| | | 15:8 | CCPR[15:8] | | | | | | | | |
| 0x0FAB | CCP1CON | 7:0 | EN | | OUT | FMT | MODE[3:0] | | | | |
| 0x0FAC | CCP1CAP | 7:0 | | | | | CTS[3:0] | | | | |
| 0x0FAD | CCPTMRS | 7:0 | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | | |
| 0x0FAD | CCPTMRS | 7:0 | P4TSEL[1:0] | | P3TSEL[1:0] | | C2TSEL[1:0] | | C1TSEL[1:0] | | |
| 0x0FAE | T6TMR | 7:0 | TxTMR[7:0] | | | | | | | | |
| 0x0FAF | T6PR | 7:0 | TxPR[7:0] | | | | | | | | |
| 0x0FB0 | T6CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | | |
| 0x0FB1 | T6HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | | |
| 0x0FB2 | T6CLKCON | 7:0 | | | | CS[4:0] | | | | | |
| 0x0FB3 | T6RST | 7:0 | | | | RSEL[4:0] | | | | | |
| 0x0FB4 | T4TMR | 7:0 | TxTMR[7:0] | | | | | | | | |
| 0x0FB5 | T4PR | 7:0 | TxPR[7:0] | | | | | | | | |
| 0x0FB6 | T4CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | | |
| 0x0FB7 | T4HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | | |
| 0x0FB8 | T4CLKCON | 7:0 | | | | CS[4:0] | | | | | |
| 0x0FB9 | T4RST | 7:0 | | | | RSEL[4:0] | | | | | |
| 0x0FBA | T2TMR | 7:0 | TxTMR[7:0] | | | | | | | | |
| 0x0FBB | T2PR | 7:0 | TxPR[7:0] | | | | | | | | |
| 0x0FBC | T2CON | 7:0 | ON | CKPS[2:0] | | | OUTPS[3:0] | | | | |
| 0x0FBD | T2HLT | 7:0 | PSYNC | CPOL | CSYNC | MODE[4:0] | | | | | |
| 0x0FBE | T2CLKCON | 7:0 | | | | CS[4:0] | | | | | |
| 0x0FBF | T2RST | 7:0 | | | | RSEL[4:0] | | | | | |
| 0x0FC0 | TMR5 | 7:0 | TMRx[7:0] | | | | | | | | |
| | | 15:8 | TMRx[15:8] | | | | | | | | |
| 0x0FC2 | T5CON | 7:0 | | | CKPS[1:0] | | | SYNC | RD16 | ON | |
| 0x0FC3 | T5GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | | |
| 0x0FC4 | TMR5GATE | 7:0 | | | | GSS[4:0] | | | | | |
| 0x0FC5 | TMR5CLK | 7:0 | | | | CS[4:0] | | | | | |
| 0x0FC6 | TMR3 | 7:0 | TMRx[7:0] | | | | | | | | |
| | | 15:8 | TMRx[15:8] | | | | | | | | |
| 0x0FC8 | T3CON | 7:0 | | | CKPS[1:0] | | | SYNC | RD16 | ON | |

.....continued

| Address | Name | Bit Pos. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|----------|----------|----------|-----------|----------|-----------|----------|--------------|---------|---------|
| 0x0FC9 | T3GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| 0x0FCA | TMR3GATE | 7:0 | | | | | | GSS[4:0] | | |
| 0x0FCB | TMR3CLK | 7:0 | | | | | | CS[4:0] | | |
| 0x0FCC | TMR1 | 7:0 | | | | | | TMRx[7:0] | | |
| | | 15:8 | | | | | | TMRx[15:8] | | |
| 0x0FCE | T1CON | 7:0 | | | | CKPS[1:0] | | SYNC | RD16 | ON |
| 0x0FCF | T1GCON | 7:0 | GE | GPOL | GTM | GSPM | GGO/DONE | GVAL | | |
| 0x0FD0 | TMR1GATE | 7:0 | | | | | | GSS[4:0] | | |
| 0x0FD1 | TMR1CLK | 7:0 | | | | | | CS[4:0] | | |
| 0x0FD2 | TMR0L | 7:0 | | | | | | TMR0L[7:0] | | |
| 0x0FD3 | TMR0H | 7:0 | | | | | | TMR0H[7:0] | | |
| 0x0FD4 | T0CON0 | 7:0 | TOEN | | TOOUT | TO16BIT | | TOOUTPS[3:0] | | |
| 0x0FD5 | T0CON1 | 7:0 | | TOCS[2:0] | | TOASYNC | | TOCKPS[3:0] | | |
| 0x0FD6 | PCON1 | 7:0 | | | | | | RVREG | | RCM |
| 0x0FD7 | PCON0 | 7:0 | STKOVF | STKUNF | WDTWV | RWDT | RMCLR | RI | POR | BOR |
| 0x0FD8 | STATUS | 7:0 | | TO | PD | N | OV | Z | DC | C |
| 0x0FD9 | FSR2 | 7:0 | | | | | | FSRL[7:0] | | |
| | | 15:8 | | | | | | FSRH[3:0] | | |
| 0x0FDB | PLUSW2 | 7:0 | | | | | | PLUSW[7:0] | | |
| 0x0FDC | PREINC2 | 7:0 | | | | | | PREINC[7:0] | | |
| 0x0FDD | POSTDEC2 | 7:0 | | | | | | POSTDEC[7:0] | | |
| 0x0FDE | POSTINC2 | 7:0 | | | | | | POSTINC[7:0] | | |
| 0x0FDF | INDF2 | 7:0 | | | | | | INDF[7:0] | | |
| 0x0FE0 | BSR | 7:0 | | | | | | BSR[3:0] | | |
| 0x0FE1 | FSR1 | 7:0 | | | | | | FSRL[7:0] | | |
| | | 15:8 | | | | | | FSRH[3:0] | | |
| 0x0FE3 | PLUSW1 | 7:0 | | | | | | PLUSW[7:0] | | |
| 0x0FE4 | PREINC1 | 7:0 | | | | | | PREINC[7:0] | | |
| 0x0FE5 | POSTDEC1 | 7:0 | | | | | | POSTDEC[7:0] | | |
| 0x0FE6 | POSTINC1 | 7:0 | | | | | | POSTINC[7:0] | | |
| 0x0FE7 | INDF1 | 7:0 | | | | | | INDF[7:0] | | |
| 0x0FE8 | WREG | 7:0 | | | | | | WREG[7:0] | | |
| 0x0FE9 | FSR0 | 7:0 | | | | | | FSRL[7:0] | | |
| | | 15:8 | | | | | | FSRH[3:0] | | |
| 0x0FEB | PLUSW0 | 7:0 | | | | | | PLUSW[7:0] | | |
| 0x0FEC | PREINC0 | 7:0 | | | | | | PREINC[7:0] | | |
| 0x0FED | POSTDEC0 | 7:0 | | | | | | POSTDEC[7:0] | | |
| 0x0FEE | POSTINC0 | 7:0 | | | | | | POSTINC[7:0] | | |
| 0x0FEF | INDF0 | 7:0 | | | | | | INDF[7:0] | | |
| 0x0FF0 | Reserved | | | | | | | | | |
| ... | | | | | | | | | | |
| 0x0FF1 | | | | | | | | | | |
| 0x0FF2 | INTCON | 7:0 | GIE/GIEH | PEIE/GIEL | IPEN | | | INT2EDG | INT1EDG | INT0EDG |
| 0x0FF3 | PROD | 7:0 | | | | | | PRODL[7:0] | | |
| | | 15:8 | | | | | | PRODH[7:0] | | |
| 0x0FF5 | TABLAT | 7:0 | | | | | | TABLAT[7:0] | | |
| 0x0FF6 | TBLPTR | 7:0 | | | | | | TBLPTRL[7:0] | | |
| | | 15:8 | | | | | | TBLPTRH[7:0] | | |
| | | 23:16 | | | TBLPTR21 | | | TBLPTRU[4:0] | | |
| 0x0FF9 | PCL | 7:0 | | | | | | PCL[7:0] | | |
| 0x0FFA | PCLAT | 7:0 | | | | | | PCLATH[7:0] | | |
| | | 15:8 | | | | | | PCLATU[4:0] | | |
| 0x0FFC | STKPTR | 7:0 | | | | | | STKPTR[4:0] | | |
| 0x0FFD | TOS | 7:0 | | | | | | TOSL[7:0] | | |
| | | 15:8 | | | | | | TOSH[7:0] | | |
| | | 23:16 | | | | | | TOSU[4:0] | | |

37. ICSP™ - In-Circuit Serial Programming™

ICSP programming allows customers to manufacture circuit boards with unprogrammed devices. Programming can be done after the assembly process, allowing the device to be programmed with the most recent firmware or a custom firmware. Five pins are needed for ICSP programming:

- ICSPCLK
- ICSPDAT
- $\overline{\text{MCLR}}/\text{V}_{\text{PP}}$
- V_{DD}
- V_{SS}

In Program/Verify mode, the program memory, User IDs and the Configuration Words are programmed through serial communications. The ICSPDAT pin is a bidirectional I/O used for transferring the serial data, and the ICSPCLK pin is the clock input. For more information on ICSP, refer to “Memory Programming Specification”(DS40001874).

37.1 High-Voltage Programming Entry Mode

The device is placed into High-Voltage Programming Entry mode by holding the ICSPCLK and ICSPDAT pins low then raising the voltage on $\overline{\text{MCLR}}/\text{V}_{\text{PP}}$ to V_{IH} .

37.2 Low-Voltage Programming Entry Mode

The Low-Voltage Programming Entry mode allows the PIC® Flash MCUs to be programmed using V_{DD} only, without high voltage. When the LVP bit of the Configuration Word 4 register is set to ‘1’, the low-voltage ICSP programming entry is enabled. To disable the Low-Voltage ICSP mode, the LVP bit must be programmed to ‘0’.

Entry into the Low-Voltage Programming Entry mode requires the following steps:

1. $\overline{\text{MCLR}}$ is brought to V_{IL} .
2. A 32-bit key sequence is presented on ICSPDAT, while clocking ICSPCLK.

Once the key sequence is complete, $\overline{\text{MCLR}}$ must be held at V_{IL} for as long as Program/Verify mode is to be maintained.

If low-voltage programming is enabled ($\text{LVP} = 1$), the $\overline{\text{MCLR}}$ Reset function is automatically enabled and cannot be disabled. See the “**MCLR**” section for more information.

The LVP bit can only be reprogrammed to ‘0’ by using the High-Voltage Programming mode.

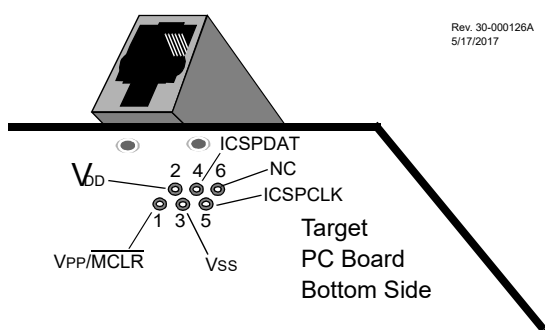
Related Links

[MCLR Reset](#)

37.3 Common Programming Interfaces

Connection to a target device is typically done through an ICSP header. A commonly found connector on development tools is the RJ-11 in the 6P6C (6-pin, 6-connector) configuration. See [Figure 37-1](#).

Figure 37-1. ICD RJ-11 Style Connector Interface



Pin Description*

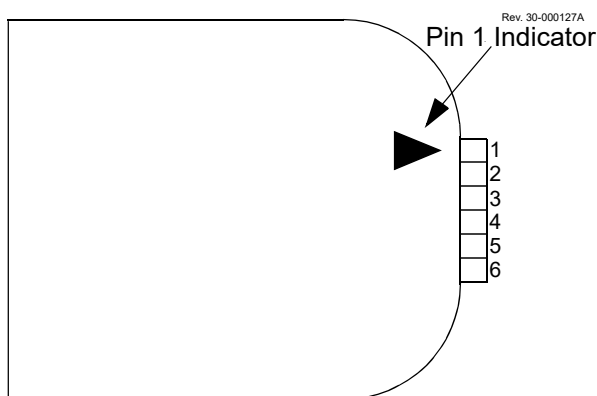
- 1 = V_{PP}/\overline{MCLR}
- 2 = V_{DD} Target
- 3 = V_{SS} (ground)
- 4 = ICSPDAT
- 5 = ICSPCLK
- 6 = No Connect

Another connector often found in use with the PICkit™ programmers is a standard 6-pin header with 0.1 inch spacing. Refer to [Figure 37-2](#).

For additional interface recommendations, refer to the specific device programmer manual prior to PCB design.

It is recommended that isolation devices be used to separate the programming pins from other circuitry. The type of isolation is highly dependent on the specific application and may include devices such as resistors, diodes, or even jumpers. See [Figure 37-3](#) for more information.

Figure 37-2. PICkit™ Programmer Style Connector Interface



Pin Description⁽¹⁾

- 1 = V_{PP}/\overline{MCLR}
- 2 = V_{DD} Target
- 3 = V_{SS} (ground)
- 4 = ICSPDAT

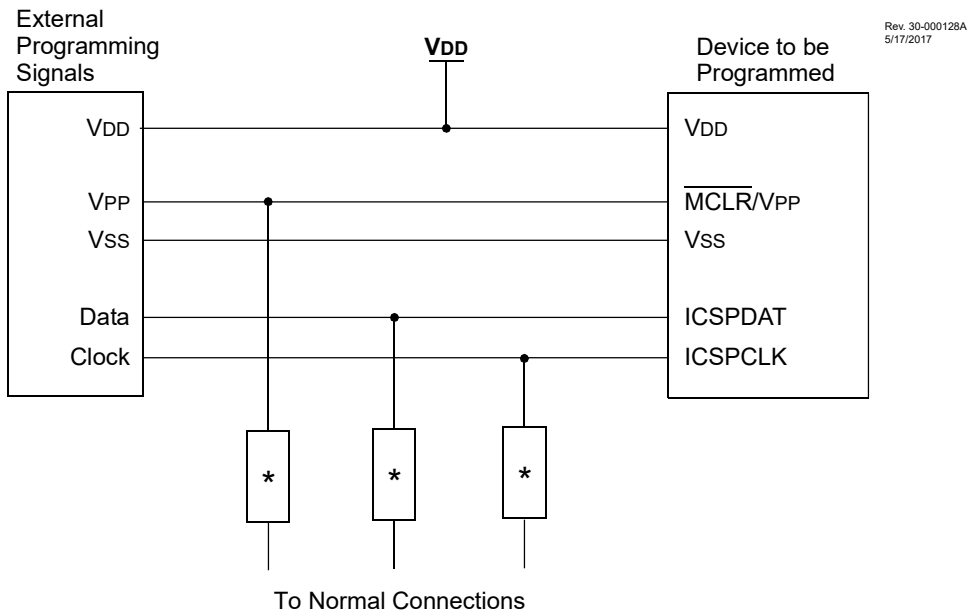
5 = ICSPCLK

6 = No Connect

Note:

1. **Note:** The 6-pin header (0.100" spacing) accepts 0.025" square pins.

Figure 37-3. Typical Connection for ICSP™ Programming



* Isolation devices (as required).

38. Instruction Set Summary

PIC18F26/45/46Q10 devices incorporate the standard set of 75 PIC18 core instructions, as well as an extended set of eight new instructions, for the optimization of code that is recursive or that utilizes a software stack. The extended set is discussed later in this section.

38.1 Standard Instruction Set

The standard PIC18 instruction set adds many enhancements to the previous PIC[®] MCU instruction sets, while maintaining an easy migration from these PIC[®] MCU instruction sets. Most instructions are a single program memory word (16 bits), but there are four instructions that require two program memory locations.

Each single-word instruction is a 16-bit word divided into an opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into four basic categories:

- Byte-oriented operations
- Bit-oriented operations
- Literal operations
- Control operations

The PIC18 instruction set summary in [Table 38-2](#) lists byte-oriented, bit-oriented, literal and control operations. [Table 38-1](#) shows the opcode field descriptions.

Most byte-oriented instructions have three operands:

1. The file register (specified by 'f')
2. The destination of the result (specified by 'd')
3. The accessed memory (specified by 'a')

The file register designator 'f' specifies which file register is to be used by the instruction. The destination designator 'd' specifies where the result of the operation is to be placed. If 'd' is zero, the result is placed in the WREG register. If 'd' is one, the result is placed in the file register specified in the instruction.

All bit-oriented instructions have three operands:

1. The file register (specified by 'f')
2. The bit in the file register (specified by 'b')
3. The accessed memory (specified by 'a')

The bit field designator 'b' selects the number of the bit affected by the operation, while the file register designator 'f' represents the number of the file in which the bit is located.

The literal instructions may use some of the following operands:

- A literal value to be loaded into a file register (specified by 'k')
- The desired FSR register to load the literal value into (specified by 'f')
- No operand required (specified by '—')

The control instructions may use some of the following operands:

- A program memory address (specified by 'n')
- The mode of the `CALL` or `RETURN` instructions (specified by 's')

- The mode of the table read and table write instructions (specified by 'm')
- No operand required (specified by '—')

All instructions are a single word, except for four double-word instructions. These instructions were made double-word to contain the required information in 32 bits. In the second word, the four MSBs are '1's. If this second word is executed as an instruction (by itself), it will execute as a `NOB`.

All single-word instructions are executed in a single instruction cycle, unless a conditional test is true or the Program Counter is changed as a result of the instruction. In these cases, the execution takes two instruction cycles, with the additional instruction cycle(s) executed as a `NOB`.

The double-word instructions execute in two instruction cycles.

One instruction cycle consists of four oscillator periods. Thus, for an oscillator frequency of 4 MHz, the normal instruction execution time is 1 μ s. If a conditional test is true, or the Program Counter is changed as a result of an instruction, the instruction execution time is 2 μ s. Two-word branch instructions (if true) would take 3 μ s.

Figure 38-1 shows the general formats that the instructions can have. All examples use the convention 'nnh' to represent a hexadecimal number.

The Instruction Set Summary, shown in Table 38-2, lists the standard instructions recognized by the Microchip Assembler (MPASM™).

Standard Instruction Set

Details provides a description of each instruction.

Table 38-1. Opcode Field Descriptions

| Field | Description |
|-----------------|---|
| a | RAM access bit a = 0: RAM location in Access RAM (BSR register is ignored) a = 1: RAM bank is specified by BSR register |
| bbb | Bit address within an 8-bit file register (0 to 7) |
| BSR | Bank Select Register. Used to select the current RAM bank. |
| C, DC, Z, OV, N | ALU Status bits: Carry, Digit Carry, Zero, Overflow, Negative |
| d | Destination select bit d = 0: store result in WREG d = 1: store result in file register f |
| dest | Destination: Either the WREG register or the specified register file location |
| f | 8-bit Register file address (00h to FFh) or 2-bit FSR designator (0h to 3h) |
| f _s | 12-bit Register file address (000h to FFFh). This is the source address. |
| f _d | 12-bit Register file address (000h to FFFh). This is the destination address. |
| GIE | Global Interrupt Enable bit |
| k | Literal field, constant data or label (may be either an 8-bit, 12-bit or a 20-bit value) |

.....continued

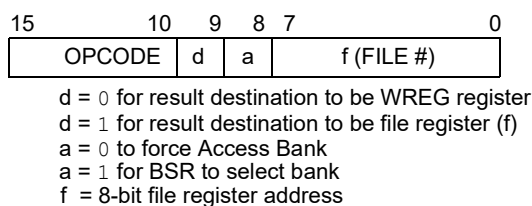
| Field | Description |
|--------|---|
| label | Label name |
| mm | The mode of the TBLPTR register for the table read and table write instructions. Only used with table read and table write instructions: |
| * | No change to register (such as TBLPTR with table reads and writes) |
| *+ | Post-Increment register (such as TBLPTR with table reads and writes) |
| *- | Post-Decrement register (such as TBLPTR with table reads and writes) |
| ++ | Pre-Increment register (such as TBLPTR with table reads and writes) |
| n | The relative address (two's complement number) for relative branch instructions or the direct address for CALL/BRANCH and RETURN instructions |
| PC | Program Counter |
| PCL | Program Counter Low Byte |
| PCH | Program Counter High Byte |
| PCLATH | Program Counter High Byte Latch |
| PCLATU | Program Counter Upper Byte Latch |
| PD | Power-Down bit |
| PRODH | Product of Multiply High Byte |
| PRODL | Product of Multiply Low Byte |
| s | Fast Call/Return mode select bit s = 0: do not update into/from shadow registers s = 1: certain registers loaded into/from shadow registers (Fast mode) |
| TBLPTR | 21-bit Table Pointer (points to a Program Memory location) |
| TABLAT | 8-bit Table Latch |
| TO | Time-Out bit |
| TOS | Top-of-Stack |
| u | Unused or unchanged |
| WDT | Watchdog Timer |
| WREG | Working register (accumulator) |

.....continued

| Field | Description |
|----------------|--|
| x | Don't care ('0' or '1'). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools. |
| z _s | 7-bit offset value for Indirect Addressing of register files (source) |
| z _d | 7-bit offset value for Indirect Addressing of register files (destination) |
| { } | Optional argument |
| [text] | Indicates an indexed address |
| (text) | The contents of text |
| [expr]<n> | Specifies bit n of the register indicated by the pointer expr. |
| → | Assigned to |
| [] | Register bit field |
| ∈ | In the set of |
| <i>italics</i> | User defined term (font is Courier) |

Figure 38-1. General Format for Instructions

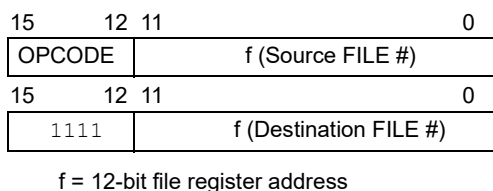
Byte-oriented file register operations



Example Instruction

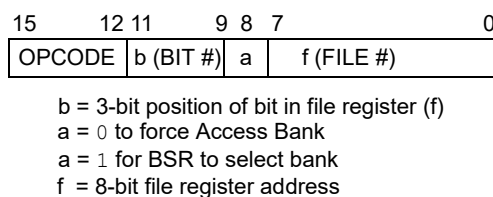
ADDWF MYREG, W, B

Byte to Byte move operations (2-word)



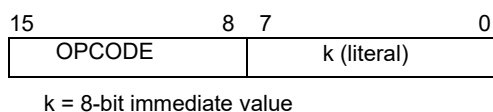
MOVFF MYREG1, MYREG2

Bit-oriented file register operations



BSF MYREG, bit, B

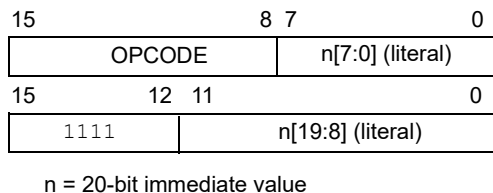
Literal operations



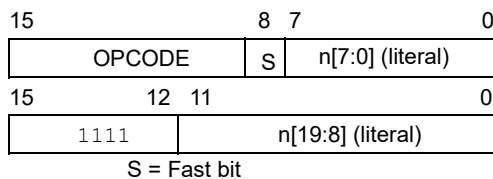
MOVLW 7Fh

Control operations

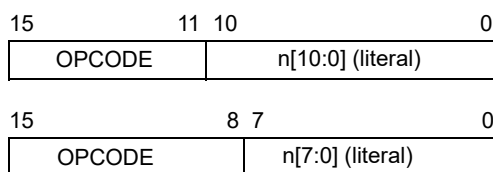
CALL, GOTO and Branch operations



GOTO Label



CALL MYFUNC



BRA MYFUNC

BC MYFUNC

Table 38-2. Instruction Set

| Mnemonic, Operands | | Description | Cycles | 16-Bit Instruction Word | | | | Status Affected | Notes |
|--------------------------|---------------------------------|--|------------|-------------------------|------|------|------|--------------------|------------|
| | | | | MSb | | | LSb | | |
| BYTE-ORIENTED OPERATIONS | | | | | | | | | |
| ADDWF | f, d, a | Add WREG and f | 1 | 0010 | 01da | ffff | ffff | C, DC, Z, OV, N | 1, 2 |
| ADDWFC | f, d, a | Add WREG and CARRY bit to f | 1 | 0010 | 00da | ffff | ffff | C, DC, Z, OV, N | 1, 2 |
| ANDWF | f, d, a | AND WREG with f | 1 | 0001 | 01da | ffff | ffff | Z, N | 1, 2 |
| CLRF | f, a | Clear f | 1 | 0110 | 101a | ffff | ffff | Z | 2 |
| COMF | f, d, a | Complement f | 1 | 0001 | 11da | ffff | ffff | Z, N | 1, 2 |
| CPFSEQ | f, a | Compare f with WREG, skip = | 1 (2 or 3) | 0110 | 001a | ffff | ffff | None | 4 |
| CPFSGT | f, a | Compare f with WREG, skip > | 1 (2 or 3) | 0110 | 010a | ffff | ffff | None | 4 |
| CPFSLT | f, a | Compare f with WREG, skip < | 1 (2 or 3) | 0110 | 000a | ffff | ffff | None | 1, 2 |
| DECF | f, d, a | Decrement f | 1 | 0000 | 01da | ffff | ffff | C, DC, Z, OV, N | 1, 2, 3, 4 |
| DECFSZ | f, d, a | Decrement f, Skip if 0 | 1 (2 or 3) | 0010 | 11da | ffff | ffff | None | 1, 2, 3, 4 |
| DCFSNZ | f, d, a | Decrement f, Skip if Not 0 | 1 (2 or 3) | 0100 | 11da | ffff | ffff | None | 1, 2 |
| INCF | f, d, a | Increment f | 1 | 0010 | 10da | ffff | ffff | C, DC, Z, OV, N | 1, 2, 3, 4 |
| INCFSZ | f, d, a | Increment f, Skip if 0 | 1 (2 or 3) | 0011 | 11da | ffff | ffff | None | 4 |
| INFSNZ | f, d, a | Increment f, Skip if Not 0 | 1 (2 or 3) | 0100 | 11da | ffff | ffff | None | 1, 2 |
| IORWF | f, d, a | Inclusive OR WREG with f | 1 | 0001 | 00da | ffff | ffff | Z, N | 1, 2 |
| MOVF | f, d, a | Move f | 1 | 0101 | 00da | ffff | ffff | Z, N | 1 |
| MOVFF | f _s , f _d | Move f _s (source) to 1st word | 2 | 1100 | ffff | ffff | ffff | None | |
| | | f _d (destination) 2nd word | | 1111 | ffff | ffff | ffff | | |
| MOVWF | f, a | Move WREG to f | 1 | 0110 | 111a | ffff | ffff | None | |
| MULWF | f, a | Multiply WREG with f | 1 | 0000 | 001a | ffff | ffff | None | 1, 2 |
| NEGF | f, a | Negate f | 1 | 0110 | 110a | ffff | ffff | C, DC, Z, OV, N | |

.....continued

| Mnemonic, Operands | | Description | Cycles | 16-Bit Instruction Word | | | | Status Affected | Notes |
|-------------------------|---------|----------------------------------|------------------|-------------------------|------|------|------|--------------------|-------|
| | | | | MSb | | | LSb | | |
| RLCF | f, d, a | Rotate Left f through Carry | 1 | 0011 | 01da | ffff | ffff | C, Z, N | 1, 2 |
| RLNCF | f, d, a | Rotate Left f (No Carry) | 1 | 0100 | 01da | ffff | ffff | Z, N | |
| RRCF | f, d, a | Rotate Right f through Carry | 1 | 0011 | 00da | ffff | ffff | C, Z, N | |
| RRNCF | f, d, a | Rotate Right f (No Carry) | 1 | 0100 | 00da | ffff | ffff | Z, N | |
| SETF | f, a | Set f | 1 | 0110 | 00da | ffff | ffff | None | 1, 2 |
| SUBFWB | f, d, a | Subtract f from WREG with borrow | 1 | 0101 | 01da | ffff | ffff | C, DC, Z, OV, N | |
| SUBWF | f, d, a | Subtract WREG from f | 1 | 0101 | 11da | ffff | ffff | C, DC, Z, OV, N | 1, 2 |
| SUBWFB | f, d, a | Subtract WREG from f with borrow | 1 | 0101 | 10da | ffff | ffff | C, DC, Z, OV, N | |
| SWAPF | f, d, a | Swap nibbles in f | 1 | 0011 | 10da | ffff | ffff | None | 4 |
| TSTFSZ | f, a | Test f, skip if 0 | 1 (2 or 3) | 0110 | 011a | ffff | ffff | None | 1, 2 |
| XORWF | f, d, a | Exclusive OR WREG with f | 1 | 0001 | 10da | ffff | ffff | Z, N | |
| BIT-ORIENTED OPERATIONS | | | | | | | | | |
| BCF | f, b, a | Bit Clear f | 1 | 1001 | bbba | ffff | ffff | None | 1, 2 |
| BSF | f, b, a | Bit Set f | 1 | 1000 | bbba | ffff | ffff | None | 1, 2 |
| BTFSC | f, b, a | Bit Test f, Skip if Clear | 1 (2 or 3) | 1011 | bbba | ffff | ffff | None | 3, 4 |
| BTFSS | f, b, a | Bit Test f, Skip if Set | 1 (2 or 3) | 1010 | bbba | ffff | ffff | None | 3, 4 |
| BTG | f, b, a | Bit Toggle f | 1 | 0111 | bbba | ffff | ffff | None | 1, 2 |
| CONTROL OPERATIONS | | | | | | | | | |
| BC | n | Branch if Carry | 1 ⁽²⁾ | 1110 | 0010 | nnnn | nnnn | None | 4 |
| BN | n | Branch if Negative | 1 ⁽²⁾ | 1110 | 0110 | nnnn | nnnn | None | |
| BNC | n | Branch if Not Carry | 1 ⁽²⁾ | 1110 | 0011 | nnnn | nnnn | None | |
| BNN | n | Branch if Not Negative | 1 ⁽²⁾ | 1110 | 0111 | nnnn | nnnn | None | |
| BNOV | n | Branch if Not Overflow | 1 ⁽²⁾ | 1110 | 0101 | nnnn | nnnn | None | |

.....continued

| Mnemonic, Operands | | Description | Cycles | 16-Bit Instruction Word | | | | Status Affected | Notes |
|-----------------------|------|--------------------------------|------------------|-------------------------|------|------|------|------------------------|-------|
| | | | | MSb | | | LSb | | |
| BNZ | n | Branch if Not Zero | 1 ⁽²⁾ | 1110 | 0001 | nnnn | nnnn | None | 4 |
| BOV | n | Branch if Overflow | 1 ⁽²⁾ | 1110 | 0100 | nnnn | nnnn | None | |
| BRA | n | Branch Unconditionally | 2 | 1101 | 0nnn | nnnn | nnnn | None | |
| BZ | n | Branch if Zero | 1 ⁽²⁾ | 1110 | 0000 | nnnn | nnnn | None | |
| CALL | k, s | Call subroutine 1st word | 2 | 1110 | 110s | kkkk | kkkk | None | |
| | | 2nd word | | 1111 | kkkk | kkkk | kkkk | | |
| CLRWDT | — | Clear Watchdog Timer | 1 | 0000 | 0000 | 0000 | 0100 | TO, PD | |
| DAW | — | Decimal Adjust WREG | 1 | 0000 | 0000 | 0000 | 0111 | C | |
| GOTO | k | Go to address 1st word | 2 | 1110 | 1111 | kkkk | kkkk | None | |
| | | 2nd word | | 1111 | kkkk | kkkk | kkkk | | |
| NOP | — | No Operation | 1 | 0000 | 0000 | 0000 | 0000 | None | |
| NOP | — | No Operation | 1 | 1111 | xxxx | xxxx | xxxx | None | |
| POP | — | Pop top of return stack (TOS) | 1 | 0000 | 0000 | 0000 | 0110 | None | |
| PUSH | — | Push top of return stack (TOS) | 1 | 0000 | 0000 | 0000 | 0101 | None | |
| RCALL | n | Relative Call | 2 | 1101 | 1nnn | nnnn | nnnn | None | |
| RESET | | Software device Reset | 1 | 0000 | 0000 | 1111 | 1111 | All | |
| RETFIE | s | Return from interrupt enable | 2 | 0000 | 0000 | 0001 | 000s | GIE/GIEH, PEIE/GIEL | |
| RETLW | k | Return with literal in WREG | 2 | 0000 | 1100 | kkkk | kkkk | None | |
| RETURN | s | Return from Subroutine | 2 | 0000 | 0000 | 0001 | 001s | None | |
| SLEEP | — | Go into Standby mode | 1 | 0000 | 0000 | 0000 | 0011 | TO, PD | |
| LITERAL OPERATIONS | | | | | | | | | |

.....continued

| Mnemonic, Operands | | Description | Cycles | 16-Bit Instruction Word | | | | Status Affected | Notes |
|---|------|---------------------------------|--------|-------------------------|------|------|------|--------------------|-------|
| | | | | MSb | | | LSb | | |
| ADDLW | k | Add literal and WREG | 1 | 0000 | 1111 | kkkk | kkkk | C, DC, Z, OV, N | |
| ANDLW | k | AND literal with WREG | 1 | 0000 | 1011 | kkkk | kkkk | Z, N | |
| IORLW | k | Inclusive OR literal with WREG | 1 | 0000 | 1001 | kkkk | kkkk | Z, N | |
| LFSR | f, k | Move literal (12-bit) 2nd word | 2 | 1110 | 1110 | 00ff | kkkk | None | |
| | | to FSR(f) 1st word | | 1111 | 0000 | kkkk | kkkk | | |
| MOVLB | k | Move literal to BSR[3:0] | 1 | 0000 | 0001 | 0000 | kkkk | None | |
| MOVLW | k | Move literal to WREG | 1 | 0000 | 1110 | kkkk | kkkk | None | |
| MULLW | k | Multiply literal with WREG | 1 | 0000 | 1101 | kkkk | kkkk | None | |
| RETLW | k | Return with literal in WREG | 2 | 0000 | 1100 | kkkk | kkkk | None | |
| SUBLW | k | Subtract WREG from literal | 1 | 0000 | 1000 | kkkk | kkkk | C, DC, Z, OV, N | |
| XORLW | k | Exclusive OR literal with WREG | 1 | 0000 | 1010 | kkkk | kkkk | Z, N | |
| DATA MEMORY ↔ PROGRAM MEMORY OPERATIONS | | | | | | | | | |
| TBLRD* | | Table Read | 2 | 0000 | 0000 | 0000 | 1000 | None | |
| TBLRD*+ | | Table Read with post-increment | | 0000 | 0000 | 0000 | 1001 | None | |
| TBLRD*- | | Table Read with post-decrement | | 0000 | 0000 | 0000 | 1010 | None | |
| TBLRD*+ | | Table Read with pre-increment | | 0000 | 0000 | 0000 | 1011 | None | |
| TBLWT* | | Table Write | 2 | 0000 | 0000 | 0000 | 1100 | None | |
| TBLWT*+ | | Table Write with post-increment | | 0000 | 0000 | 0000 | 1101 | None | |
| TBLWT*- | | Table Write with post-decrement | | 0000 | 0000 | 0000 | 1110 | None | |
| TBLWT*+ | | Table Write with pre-increment | | 0000 | 0000 | 0000 | 1111 | None | |

Notes:

1. When a PORT register is modified as a function of itself (e.g., `MOVF PORTB, 1, 0`), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.
2. If this instruction is executed on the TMR0 register (and where applicable, 'd' = 1), the prescaler will be cleared if assigned.
3. If Program Counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a `NOP`.
4. Some instructions are two-word instructions. The second word of these instructions will be executed as a `NOP` unless the first word of the instruction retrieves the information embedded in these 16 bits. This ensures that all program memory locations have a valid instruction.

38.1.1 Standard Instruction Set Details

| ADDLW | ADD literal to W | | | |
|------------------|---|------|------|------|
| Syntax: | ADDLW k | | | |
| Operands: | $0 \leq k \leq 255$ | | | |
| Operation: | $(W) + k \rightarrow W$ | | | |
| Status Affected: | N, OV, C, DC, Z | | | |
| Encoding: | 0000 | 1111 | kkkk | kkkk |
| Description: | The contents of W are added to the 8-bit literal 'k' and the result is placed in W. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to W |

| | | |
|-------------------------------|-------|-----|
| Example: | ADDLW | 15h |
| Before Instruction W = 10h | | |
| After Instruction W = 25h | | |

| ADDWF | ADD W to f | | | |
|------------------|---|------|------|------|
| Syntax: | ADDWF f {d {a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | $(W) + (f) \rightarrow \text{dest}$ | | | |
| Status Affected: | N, OV, C, DC, Z | | | |
| Encoding: | 0010 | 01da | ffff | ffff |

.....continued

| ADDWF | ADD W to f | | | |
|--------------|---|--|--|--|
| Description: | Add W to register 'f'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | | |
|--|-------|------|------|
| Example: | ADDWF | REG, | 0, 0 |
| Before Instruction W = 17h REG = 0C2h After Instruction W = 0D9h REG = 0C2h | | | |



Important: All PIC18 instructions may take an optional label argument preceding the instruction mnemonic for use in symbolic addressing. If a label is used, the instruction format then becomes: {label} instruction argument(s).

| ADDWFC | ADD W and CARRY bit to f | | | |
|------------------|---|------|------|------|
| Syntax: | ADDWFC f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | $(W) + (f) + (C) \rightarrow \text{dest}$ | | | |
| Status Affected: | N,OV, C, DC, Z | | | |
| Encoding: | 0010 | 00da | ffff | ffff |
| Description: | Add W, the CARRY flag and data memory location 'f'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed in data memory location 'f'. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|----|----|----|
| Q1 | Q2 | Q3 | Q4 |

| | | | |
|--------|-------------------|--------------|----------------------|
| Decode | Read register 'f' | Process Data | Write to destination |
|--------|-------------------|--------------|----------------------|

| | | | |
|---|--------|------|------|
| Example: | ADDWFC | REG, | 0, 1 |
| Before Instruction CARRY bit = 1 REG = 02h W = 4Dh After Instruction CARRY bit = 0 REG = 02h W = 50h | | | |

| ANDLW | AND literal with W | | |
|------------------|---|------|------|
| Syntax: | ANDLW k | | |
| Operands: | $0 \leq k \leq 255$ | | |
| Operation: | (W) .AND. k \rightarrow W | | |
| Status Affected: | N, Z | | |
| Encoding: | 0000 | 1011 | kkkk |
| Description: | The contents of W are AND'ed with the 8-bit literal 'k'. The result is placed in W. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| | | | |
|-------------------|------------------|--------------|------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to W |

| | | |
|---|-------|------|
| Example: | ANDLW | 05Fh |
| Before Instruction W = A3h After Instruction W = 03h | | |

| ANDWF | AND W with f | | |
|------------------|---|------|------|
| Syntax: | ANDWF f {d {a}} | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | |
| Operation: | (W) .AND. (f) \rightarrow dest | | |
| Status Affected: | N, Z | | |
| Encoding: | 0001 | 01da | ffff |
| Description: | The contents of W are AND'ed with register 'f'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |

.....continued

| ANDWF | AND W with f |
|---------|--------------|
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | | |
|----------|-------|------|------|
| Example: | ANDWF | REG, | 0, 0 |
|----------|-------|------|------|

Before Instruction

W = 17h

REG = C2h

After Instruction

W = 02h

REG = C2h

| BC | Branch if Carry |
|------------------|--|
| Syntax: | BC n |
| Operands: | $-128 \leq n \leq 127$ |
| Operation: | if CARRY bit is '1' (PC) + 2 + 2n → PC |
| Status Affected: | None |
| Encoding: | 1110 0010 nnnn nnnn |
| Description: | If the CARRY bit is '1', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. |
| Words: | 1 |
| Cycles: | 1(2) |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------|
| If Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|----------|------|----|---|
| Example: | HERE | BC | 5 |
|----------|------|----|---|

Before Instruction

PC = address (HERE)

After Instruction

If CARRY = 1;

PC = address (HERE + 12)

If CARRY = 0;

PC = address (HERE + 2)

| BCF | Bit Clear f |
|------------------|---|
| Syntax: | BCF f, b {,a} |
| Operands: | $0 \leq f \leq 255$ $0 \leq b \leq 7$ $a \in [0,1]$ |
| Operation: | $0 \rightarrow f$ |
| Status Affected: | None |
| Encoding: | <div>1001</div> <div>bbba</div> <div>ffff</div> <div>ffff</div> |
| Description: | Bit 'b' in register 'f' is cleared. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. |
| Words: | 1 |
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | |
|---|-----|----------------|
| Example: | BCF | FLAG_REG, 7, 0 |
| Before Instruction FLAG_REG = C7h After Instruction FLAG_REG = 47h | | |

| BN | Branch if Negative |
|------------------|---|
| Syntax: | BN n |
| Operands: | $-128 \leq n \leq 127$ |
| Operation: | if NEGATIVE bit is '1' $(PC) + 2 + 2n \rightarrow PC$ |
| Status Affected: | None |
| Encoding: | <div>1110</div> <div>0110</div> <div>nnnn</div> <div>nnnn</div> |
| Description: | If the NEGATIVE bit is '1', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be $PC + 2 + 2n$. This instruction is then a two-cycle instruction. |
| Words: | 1 |
| Cycles: | 1(2) |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------|
| If Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|----|------|
| Example: | HERE | BN | Jump |
| Before Instruction PC = address (HERE) After Instruction If NEGATIVE = 1; PC = address (Jump) If NEGATIVE = 0; PC = address (HERE + 2) | | | |

| BNC | Branch if Not Carry | | |
|------------------|---|------|------|
| Syntax: | BNC n | | |
| Operands: | $-128 \leq n \leq 127$ | | |
| Operation: | if CARRY bit is '0' (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1110 | 0011 | nnnn |
| Description: | If the CARRY bit is '0', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | |
| Words: | 1 | | |
| Cycles: | 1(2) | | |

| | | | |
|-------------------|------------------|--------------|--------------|
| Q Cycle Activity: | | | |
| If Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|-----|------|
| Example: | HERE | BNC | Jump |
| Before Instruction PC = address (HERE) After Instruction If CARRY = 0; PC = address (Jump) If CARRY = 1; PC = address (HERE + 2) | | | |

| BNN | Branch if Not Negative | | |
|------------------|--|------|------|
| Syntax: | BNN n | | |
| Operands: | $-128 \leq n \leq 127$ | | |
| Operation: | if NEGATIVE bit is '0' (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1110 | 0111 | nnnn |

.....continued

| BNN | Branch if Not Negative | | |
|--------------|---|--|--|
| Description: | If the NEGATIVE bit is '0', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | |
| Words: | 1 | | |
| Cycles: | 1(2) | | |

| Q Cycle Activity: If Jump: | | | |
|-------------------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|-----|------|
| Example: | HERE | BNN | Jump |
| Before Instruction PC = address (HERE) After Instruction If NEGATIVE = 0; PC = address (Jump) If NEGATIVE = 1; PC = address (HERE + 2) | | | |

| BNOV | Branch if Not Overflow | | |
|------------------|---|------|------|
| Syntax: | BNOV n | | |
| Operands: | $-128 \leq n \leq 127$ | | |
| Operation: | if OVERFLOW bit is '0' (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1110 | 0101 | nnnn |
| Description: | If the OVERFLOW bit is '0', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | |
| Words: | 1 | | |
| Cycles: | 1(2) | | |

| Q Cycle Activity: If Jump: | | | |
|-------------------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|------|------|
| Example: | HERE | BNOV | Jump |
| Before Instruction PC = address (HERE) After Instruction If OVERFLOW = 0; PC = address (Jump) If OVERFLOW = 1; PC = address (HERE + 2) | | | |

| BNZ | Branch if Not Zero | | |
|------------------|--|------|------|
| Syntax: | BNZ n | | |
| Operands: | $-128 \leq n \leq 127$ | | |
| Operation: | if ZERO bit is '0' (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1110 | 0001 | nnnn |
| Description: | If the ZERO bit is '0', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | |
| Words: | 1 | | |
| Cycles: | 1(2) | | |

| | | | |
|-------------------|------------------|--------------|--------------|
| Q Cycle Activity: | | | |
| If Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|-----|------|
| Example: | HERE | BNZ | Jump |
| Before Instruction PC = address (HERE) After Instruction If ZERO = 0; PC = address (Jump) If ZERO = 1; PC = address (HERE + 2) | | | |

| BRA | Unconditional Branch | | |
|------------------|---|------|------|
| Syntax: | BRA n | | |
| Operands: | $-1024 \leq n \leq 1023$ | | |
| Operation: | (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1101 | 0nnn | nnnn |
| Description: | Add the two's complement number '2n' to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is a two-cycle instruction. | | |

.....continued

| BRA | Unconditional Branch | | | |
|---------|----------------------|--|--|--|
| Words: | 1 | | | |
| Cycles: | 2 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |

| | | | |
|----------|------|-----|------|
| Example: | HERE | BRA | Jump |
|----------|------|-----|------|

Before Instruction
PC = address (HERE)
After Instruction
PC = address (Jump)

| BSF | Bit Set f | | | |
|------------------|---|------|------|------|
| Syntax: | BSF f, b {,a} | | | |
| Operands: | $0 \leq f \leq 255$ $0 \leq b \leq 7$ $a \in [0,1]$ | | | |
| Operation: | $1 \rightarrow f$ | | | |
| Status Affected: | None | | | |
| Encoding: | 1000 | bbba | ffff | ffff |
| Description: | Bit 'b' in register 'f' is set. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | |
|----------|-----|----------------|
| Example: | BSF | FLAG_REG, 7, 1 |
|----------|-----|----------------|

Before Instruction
FLAG_REG = 0Ah
After Instruction
FLAG_REG = 8Ah

| BTFSC | Bit Test File, Skip if Clear | | | |
|-----------|---|--|--|--|
| Syntax: | BTFSC f, b {,a} | | | |
| Operands: | $0 \leq f \leq 255$ $0 \leq b \leq 7$ $a \in [0,1]$ | | | |

.....continued

| BTFSC | Bit Test File, Skip if Clear | | |
|------------------|---|------|------|
| Operation: | skip if (f) = 0 | | |
| Status Affected: | None | | |
| Encoding: | 1011 | bbba | ffff |
| Description: | <p>If bit 'b' in register 'f' is '0', then the next instruction is skipped. If bit 'b' is '0', then the next instruction fetched during the current instruction execution is discarded and a NOP is executed instead, making this a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| | | | |
|-------------------|-------------------|--------------|--------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| | | | |
|---|--------------|--------------|--------------|
| If skip: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | | | |
|---|-----------------------|-----------------|------------|
| Example: | HERE FALSE TRUE | BTFSC : : | FLAG, 1, 0 |
| Before Instruction PC = address (HERE) After Instruction If FLAG<1> = 0; PC = address (TRUE) If FLAG<1> = 1; PC = address (FALSE) | | | |

| BTFSS | Bit Test File, Skip if Set | | |
|------------------|--|------|------|
| Syntax: | BTFSS f, b {,a} | | |
| Operands: | $0 \leq f \leq 255$ $0 \leq b < 7$ $a \in [0,1]$ | | |
| Operation: | skip if (f) = 1 | | |
| Status Affected: | None | | |
| Encoding: | 1010 | bbba | ffff |

.....continued

| BTFSS | Bit Test File, Skip If Set |
|--------------|--|
| Description: | <p>If bit 'b' in register 'f' is '1', then the next instruction is skipped. If bit 'b' is '1', then the next instruction fetched during the current instruction execution is discarded and a <code>NOF</code> is executed instead, making this a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |
| Words: | 1 |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | | | |
|--|--------------------------------|--------------------------|-------------------|
| Example: | <p>HERE FALSE TRUE</p> | <p>BTFSS : :</p> | <p>FLAG, 1, 0</p> |
| <p>Before Instruction PC = address (HERE)</p> <p>After Instruction If FLAG<1> = 0; PC = address (FALSE)</p> <p>If FLAG<1> = 1; PC = address (TRUE)</p> | | | |

| BTG | Bit Toggle f |
|------------------|--|
| Syntax: | BTG f, b {,a} |
| Operands: | $0 \leq f \leq 255$ $0 \leq b < 7$ $a \in [0,1]$ |
| Operation: | $(f \ll b) \rightarrow f \ll b$ |
| Status Affected: | None |
| Encoding: | <p>0111 bbba ffff ffff</p> |
| Description: | <p>Bit 'b' in data memory location 'f' is inverted.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |

.....continued

| BTG | Bit Toggle f | | | |
|---------|--------------|--|--|--|
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | | |
|----------|-----|--------|------|
| Example: | BTG | PORTC, | 4, 0 |
|----------|-----|--------|------|

Before Instruction:
PORTC = 0111 0101 [75h]
After Instruction:
PORTC = 0110 0101 [65h]

| BOV | Branch if Overflow | | | |
|------------------|---|------|------|------|
| Syntax: | BOV n | | | |
| Operands: | $-128 \leq n \leq 127$ | | | |
| Operation: | if OVERFLOW bit is '1' (PC) + 2 + 2n → PC | | | |
| Status Affected: | None | | | |
| Encoding: | 1110 | 0100 | nnnn | nnnn |
| Description: | If the OVERFLOW bit is '1', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | | |
| Words: | 1 | | | |
| Cycles: | 1(2) | | | |

| Q Cycle Activity: If Jump: | | | |
|-------------------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|----------|------|-----|------|
| Example: | HERE | BOV | Jump |
|----------|------|-----|------|

Before Instruction
PC = address (HERE)
After Instruction
If OVERFLOW = 1;
PC = address (Jump)
If OVERFLOW = 0;
PC = address (HERE + 2)

| BZ | Branch if Zero | | | |
|------------------|--|------|------|------|
| Syntax: | BZ n | | | |
| Operands: | $-128 \leq n \leq 127$ | | | |
| Operation: | if ZERO bit is '1' (PC) + 2 + 2n → PC | | | |
| Status Affected: | None | | | |
| Encoding: | 1110 | 0000 | nnnn | nnnn |
| Description: | If the ZERO bit is '1', then the program will branch. The two's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is then a two-cycle instruction. | | | |
| Words: | 1 | | | |
| Cycles: | 1(2) | | | |

| | | | |
|-------------------------------|------------------|--------------|--------------|
| Q Cycle Activity: If Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |
| If No Jump: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' | Process Data | No operation |

| | | | |
|--|------|----|------|
| Example: | HERE | BZ | Jump |
| Before Instruction PC = address (HERE) After Instruction If ZERO = 1; PC = address (Jump) If ZERO = 0; PC = address (HERE + 2) | | | |

| CALL | Subroutine Call | | | |
|-------------------|--|---------------------|--------------------|-------------------|
| Syntax: | CALL k {,s} | | | |
| Operands: | $0 \leq k \leq 1048575$ $s \in [0,1]$ | | | |
| Operation: | (PC) + 4 → TOS, k → PC<20:1>, if s = 1 (W) → WS, (Status) → STATUSS, (BSR) → BSRS | | | |
| Status Affected: | None | | | |
| Encoding: | | | | |
| 1st word (k<7:0>) | 1110 | 110s | k ₇ kkk | kkkk ₀ |
| 2nd word(k<19:8>) | 1111 | k ₁₉ kkk | kkkk | kkkk ₈ |

.....continued

| CALL | Subroutine Call | | | |
|--------------|--|--|--|--|
| Description: | Subroutine call of entire 2-Mbyte memory range. First, return address (PC + 4) is pushed onto the return stack. If 's' = 1, the W, Status and BSR registers are also pushed into their respective shadow registers, WS, STATUSS and BSRS. If 's' = 0, no update occurs (default). Then, the 20-bit value 'k' is loaded into PC<20:1>. CALL is a two-cycle instruction. | | | |
| Words: | 2 | | | |
| Cycles: | 2 | | | |

| | | | |
|-------------------|------------------------|------------------|-------------------------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k'<7:0>, | PUSH PC to stack | Read literal 'k'<19:8>, Write to PC |
| No operation | No operation | No operation | No operation |

| | | | |
|--|------|------|----------|
| Example: | HERE | CALL | THERE, 1 |
| Before Instruction PC = address (HERE) After Instruction PC = address (THERE) TOS = address (HERE + 4) WS = W BSRS = BSR STATUSS = Status | | | |

| CLRF | Clear f | | | |
|------------------|--|------|------|------|
| Syntax: | CLRF f {,a} | | | |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ | | | |
| Operation: | $000h \rightarrow f$ $1 \rightarrow Z$ | | | |
| Status Affected: | Z | | | |
| Encoding: | 0110 | 101a | ffff | ffff |
| Description: | Clears the contents of the specified register. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|-------------------|--------------|--------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | |
|----------|------|-------------|
| Example: | CLRF | FLAG_REG, 1 |
|----------|------|-------------|

Before Instruction
FLAG_REG = 5Ah
After Instruction
FLAG_REG = 00h

| CLRWDT | Clear Watchdog Timer | | | |
|------------------|---|------|------|------|
| Syntax: | CLRWDT | | | |
| Operands: | None | | | |
| Operation: | 000h → WDT, 000h → WDT postscaler, 1 → \overline{TO} , 1 → \overline{PD} | | | |
| Status Affected: | \overline{TO} , \overline{PD} | | | |
| Encoding: | 0000 | 0000 | 0000 | 0100 |
| Description: | CLRWDT instruction resets the Watchdog Timer. It also resets the postscaler of the WDT. Status bits, \overline{TO} and \overline{PD} , are set. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | Process Data | No operation |

Example:

CLRWDT

Before Instruction
WDT Counter = ?
After Instruction
WDT Counter = 00h
WDT Postscaler = 0
 \overline{TO} = 1
 \overline{PD} = 1

| COMF | Complement f | | | |
|------------------|---|------|------|------|
| Syntax: | COMF f {,d {,a}} | | | |
| Operands: | 0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1] | | | |
| Operation: | (f) → dest | | | |
| Status Affected: | N, Z | | | |
| Encoding: | 0001 | 11da | ffff | ffff |
| Description: | The contents of register 'f' are complemented. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | | |
|--|------|------|------|
| Example: | COMF | REG, | 0, 0 |
| Before Instruction REG = 13h After Instruction REG = 13h W = ECh | | | |

| CPFSEQ | Compare f with W, skip if f = W | | |
|------------------|--|------|------|
| Syntax: | CPFSEQ f {,a} | | |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ | | |
| Operation: | (f) – (W), skip if (f) = (W) (unsigned comparison) | | |
| Status Affected: | None | | |
| Encoding: | 0110 | 001a | ffff |
| Description: | Compares the contents of data memory location 'f' to the contents of W by performing an unsigned subtraction. If 'f' = W, then the fetched instruction is discarded and a NOP is executed instead, making this a two-cycle instruction. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | |
|----------|--|
| Example: | HERE CPFSEQ REG, 0 NEQUAL : EQUAL : |
|----------|--|

Before Instruction
PC Address = HERE
W = ?
REG = ?
After Instruction
If REG = W;
PC = Address (EQUAL)
If REG ≠ ;
PC = Address (NEQUAL)

| CPFSGT | Compare f with W, skip if f > W | | |
|------------------|--|------|------|
| Syntax: | CPFSGT f {,a} | | |
| Operands: | 0 ≤ f ≤ 255 a ∈ [0,1] | | |
| Operation: | (f) – (), skip if (f) > (W) (unsigned comparison) | | |
| Status Affected: | None | | |
| Encoding: | 0110 | 010a | ffff |
| Description: | <p>Compares the contents of data memory location 'f' to the contents of the W by performing an unsigned subtraction.</p> <p>If the contents of 'f' are greater than the contents of WREG, then the fetched instruction is discarded and a NOP is executed instead, making this a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | |
|----------|--|
| Example: | <pre> HERE CPFSGT REG, 0 NGREATER : GREATER : </pre> |
|----------|--|

Before Instruction
PC = Address (HERE)
W = ?
After Instruction
If REG > W;
PC = Address (GREATER)
If REG ≤ W;
PC = Address (NGREATER)

| CPFSLT | Compare f with W, skip if f < W | | |
|------------------|--|------|------|
| Syntax: | CPFSLT f {,a} | | |
| Operands: | 0 ≤ f ≤ 255 a ∈ [0,1] | | |
| Operation: | (f) − (), skip if (f) < (W) (unsigned comparison) | | |
| Status Affected: | None | | |
| Encoding: | 0110 | 000a | ffff |
| Description: | Compares the contents of data memory location 'f' to the contents of W by performing an unsigned subtraction. If the contents of 'f' are less than the contents of W, then the fetched instruction is discarded and a NOP is executed instead, making this a two-cycle instruction. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | |
|----------|---|
| Example: | <pre> HERE CPFSLT REG, 1 NLESS : LESS :</pre> |
|----------|---|

Before Instruction
PC = Address (HERE)
W = ?
After Instruction
If REG < W;
PC = Address (LESS)
If REG ≥ W;
PC = Address (NLESS)

| DAW | Decimal Adjust W Register | | | |
|------------------|---|------|------|------|
| Syntax: | DAW | | | |
| Operands: | None | | | |
| Operation: | If [W<3:0> > 9] or [DC = 1] then (W<3:0>) + 6 → W<3:0>; else (W<3:0>) → W<3:0>; If [W<7:4> + DC > 9] or [C = 1] then (W<7:4>) + 6 + DC → W<7:4>; else (W<7:4>) + DC → W<7:4> | | | |
| Status Affected: | C | | | |
| Encoding: | 0000 | 0000 | 0000 | 0111 |
| Description: | DAW adjusts the 8-bit value in W, resulting from the earlier addition of two variables (each in packed BCD format) and produces a correct packed BCD result. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|-----------------|--------------|---------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register W | Process Data | Write W |

| | |
|--|-----|
| Example1: | DAW |
| Before Instruction W = A5h C = 0 DC = 0 After Instruction W = 05h C = 1 DC = 0 Example 2: Before Instruction W = CEh C = 0 DC = 0 After Instruction W = 34h C = 1 DC = 0 | |

| DECF | Decrement f | | | |
|------------------|---|------|------|------|
| Syntax: | DECF f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | (f) - 1 → dest | | | |
| Status Affected: | C, DC, N, OV, Z | | | |
| Encoding: | 0000 | 01da | ffff | ffff |

.....continued

| DECF | Decrement f | | |
|--------------|--|--|--|
| Description: | Decrement register 'f'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | |
|---|----------------|
| Example: | DECF CNT, 1, 0 |
| Before Instruction CNT = 01h Z = 0 After Instruction CNT = 00h Z = 1 | |

| DECFSZ | Decrement f, skip if 0 | | |
|------------------|--|------|------|
| Syntax: | DECFSZ f {,d {,a}} | | |
| Operands: | 0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1] | | |
| Operation: | (f) – 1 → dest, skip if result = 0 | | |
| Status Affected: | None | | |
| Encoding: | 0010 | 11da | ffff |
| Description: | The contents of register 'f' are decremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). If the result is '0', the next instruction, which is already fetched, is discarded and a NOP is executed instead, making it a two-cycle instruction. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | |
|----------|--|--|
| If skip: | | |
|----------|--|--|

| Q1 | Q2 | Q3 | Q4 |
|---|--------------|--------------|--------------|
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

Example:

```
HERE    DECFSZ  CNT, 1, 1
GOTO    LOOP
CONTINUE
```

Before Instruction
PC = Address (HERE)

After Instruction

CNT = CNT - 1

If CNT = 0;

PC = Address (CONTINUE)

If CNT ≠ 0;

PC = Address (HERE + 2)

| DCFSNZ | Decrement f, skip if not 0 |
|------------------|---|
| Syntax: | DCFSNZ f {,d {,a}} |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ |
| Operation: | (f) - 1 → dest, skip if result ≠ 0 |
| Status Affected: | None |
| Encoding: | <div>0100</div> <div>11da</div> <div>ffff</div> <div>ffff</div> |
| Description: | <p>The contents of register 'f' are decremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If the result is not '0', the next instruction, which is already fetched, is discarded and a NOP is executed instead, making it a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |
| Words: | 1 |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |

| | | | |
|--------------|--------------|--------------|--------------|
| No operation | No operation | No operation | No operation |
|--------------|--------------|--------------|--------------|

| | |
|---|---|
| Example: | <pre> HERE DCFSNZ TEMP, 1, 0 ZERO : NZERO : </pre> |
| <p>Before Instruction TEMP = ?</p> <p>After Instruction TEMP = TEMP - 1, If TEMP = 0; PC = Address (ZERO) If TEMP ≠ 0; PC = Address (NZERO)</p> | |

| GOTO | Unconditional Branch | | | |
|-------------------|--|---------------------|--------------------|-------------------|
| Syntax: | GOTO k | | | |
| Operands: | $0 \leq k \leq 1048575$ | | | |
| Operation: | $k \rightarrow PC<20:1>$ | | | |
| Status Affected: | None | | | |
| Encoding: | | | | |
| 1st word (k<7:0>) | 1110 | 1111 | k ₇ kkk | kkkk ₀ |
| 2nd word(k<19:8>) | 1111 | k ₁₉ kkk | kkkk | kkkk ₈ |
| Description: | GOTO allows an unconditional branch anywhere within entire 2-Mbyte memory range. The 20-bit value 'k' is loaded into PC<20:1>. GOTO is always a two-cycle instruction. | | | |
| Words: | 2 | | | |
| Cycles: | 2 | | | |

| | | | |
|-------------------|------------------------|--------------|-------------------------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k'<7:0>, | No operation | Read literal 'k'<19:8>, Write to PC |
| No operation | No operation | No operation | No operation |

| | |
|---|------------|
| Example: | GOTO THERE |
| <p>After Instruction PC = Address (THERE)</p> | |

| INCF | Increment f | | | |
|------------------|---|------|------|------|
| Syntax: | INCF f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | $(f) + 1 \rightarrow \text{dest}$ | | | |
| Status Affected: | C, DC, N, OV, Z | | | |
| Encoding: | 0010 | 10da | ffff | ffff |

.....continued

| INCF | Increment f | | | |
|--------------|---|--|--|--|
| Description: | <p>The contents of register 'f' are incremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | | |
|--|------|------|------|
| Example: | INCF | CNT, | 1, 0 |
| <p>Before Instruction CNT = FFh Z = 0 C = ? DC = ?</p> <p>After Instruction CNT = 00h Z = 1 C = 1 DC = 1</p> | | | |

| INCFSZ | Increment f, skip if 0 | | | |
|------------------|---|------|------|------|
| Syntax: | INCFSZ f {,d {,a}} | | | |
| Operands: | <p>0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1]</p> | | | |
| Operation: | (f) + 1 → dest, skip if result = 0 | | | |
| Status Affected: | None | | | |
| Encoding: | 0011 | 11da | ffff | ffff |
| Description: | <p>The contents of register 'f' are incremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If the result is '0', the next instruction, which is already fetched, is discarded and a NOP is executed instead, making it a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | | |
| Words: | 1 | | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | | |

| | | |
|-------------------|--|--|
| Q Cycle Activity: | | |
|-------------------|--|--|

| Q1 | Q2 | Q3 | Q4 |
|--------|-------------------|--------------|----------------------|
| Decode | Read register 'f' | Process Data | Write to destination |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

| | |
|---|---|
| Example: | <pre> HERE INCFSZ CNT, 1, 0 NZERO : ZERO : </pre> |
| <p>Before Instruction PC = Address (HERE)</p> <p>After Instruction CNT = CNT + 1 If CNT = 0; PC = Address (ZERO) If CNT ≠ 0; PC = Address (NZERO)</p> | |

| INFSNZ | Increment f, skip if not 0 |
|------------------|---|
| Syntax: | INFSNZ f {,d {,a}} |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ |
| Operation: | (f) + 1 → dest, skip if result ≠ 0 |
| Status Affected: | None |
| Encoding: | <div>0100</div> <div>10da</div> <div>ffff</div> <div>ffff</div> |
| Description: | <p>The contents of register 'f' are incremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If the result is not '0', the next instruction, which is already fetched, is discarded and a NOP is executed instead, making it a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |
| Words: | 1 |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |
| If skip: | | | |

| Q1 | Q2 | Q3 | Q4 |
|---|--------------|--------------|--------------|
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

Example:

```
HERE    INFSNZ  REG, 1, 0
ZERO
NZERO
```

Before Instruction
PC = Address (HERE)

After Instruction

REG = REG + 1

If REG ≠ 0;

PC = Address (NZERO)

If REG = 0;

PC = Address (ZERO)

| IORLW | Inclusive OR literal with W | | | |
|------------------|---|------|------|------|
| Syntax: | IORLW k | | | |
| Operands: | 0 ≤ k ≤ 255 | | | |
| Operation: | (W) .OR. k → W | | | |
| Status Affected: | N, Z | | | |
| Encoding: | 0000 | 1001 | kkkk | kkkk |
| Description: | The contents of W are ORed with the 8-bit literal 'k'. The result is placed in W. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

Q Cycle Activity:

| Q1 | Q2 | Q3 | Q4 |
|--------|------------------|--------------|------------|
| Decode | Read literal 'k' | Process Data | Write to W |

Example:

```
IORLW
```

```
35h
```

Before Instruction

W = 9Ah

After Instruction

W = BFh

| IORWF | Inclusive OR W with f | | | |
|------------------|---------------------------------------|------|------|------|
| Syntax: | IORWF f {d {a}} | | | |
| Operands: | 0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1] | | | |
| Operation: | (W) .OR. (f) → dest | | | |
| Status Affected: | N, Z | | | |
| Encoding: | 0001 | 00da | ffff | ffff |

.....continued

| IORWF | Inclusive OR W with f | | | |
|--------------|--|--|--|--|
| Description: | Inclusive OR W with register 'f'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | |
|---|--------------------|
| Example: | IORWF RESULT, 0, 1 |
| Before Instruction RESULT = 13h W = 91h After Instruction RESULT = 13h W = 93h | |

| LFSR | Load FSR | | | |
|------------------|---|--------------|----------------------------|-----------------------------|
| Syntax: | LFSR f, k | | | |
| Operands: | 0 ≤ f ≤ 2 0 ≤ k ≤ 4095 | | | |
| Operation: | k → FSRf | | | |
| Status Affected: | None | | | |
| Encoding: | 1110 1111 | 1110 0000 | 00ff k ₇ kkk | k ₁₁ kkk kkkk |
| Description: | The 12-bit literal 'k' is loaded into the File Select Register pointed to by 'f'. | | | |
| Words: | 2 | | | |
| Cycles: | 2 | | | |

| Q Cycle Activity: | | | |
|-------------------|----------------------|--------------|--------------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' MSB | Process Data | Write literal 'k' MSB to FSRfH |
| Decode | Read literal 'k' LSB | Process Data | Write literal 'k' to FSRfL |

| | |
|---|-------------------|
| Example: | LFSR 2, 3ABh |
| After Instruction FSR2H = 03h FSR2L = ABh | |

| MOVF | Move f | | |
|---------|------------------|--|--|
| Syntax: | MOVF f {,d {,a}} | | |

.....continued

| MOVf | Move f |
|------------------|--|
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ |
| Operation: | $f \rightarrow \text{dest}$ |
| Status Affected: | N, Z |
| Encoding: | <div>0101</div> <div>00da</div> <div>ffff</div> <div>ffff</div> |
| Description: | <p>The contents of register 'f' are moved to a destination dependent upon the status of 'd'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). Location 'f' can be anywhere in the 256-byte bank.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |
| Words: | 1 |
| Cycles: | 1 |

| | | | |
|-------------------|-------------------|--------------|---------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write W |

| | |
|---|----------------|
| Example: | MOVf REG, 0, 0 |
| Before Instruction REG = 22h W = FFh After Instruction REG = 22h W = 22h | |

| MOVFF | Move f to f |
|------------------|--|
| Syntax: | MOVFF f_s, f_d |
| Operands: | $0 \leq f_s \leq 4095$ $0 \leq f_d \leq 4095$ |
| Operation: | $(f_s) \rightarrow f_d$ |
| Status Affected: | None |
| Encoding: | <div>1100</div> <div>1111</div> <div>ffff</div> <div>ffff</div> <div>ffff₅</div> <div>ffff_d</div> |
| Description: | <p>The contents of source register 'f_s' are moved to destination register 'f_d'. The location of source 'f_s' can be anywhere in the 4096-byte data space (000h to FFFh) and location of destination 'f_d' can also be anywhere from 000h to FFFh.</p> <p>Either source or destination can be W (a useful special situation).</p> <p>MOVFF is particularly useful for transferring a data memory location to a peripheral register (such as the transmit buffer or an I/O port).</p> <p>The MOVFF instruction cannot use the PCL, TOSU, TOSH or TOSL as the destination register.</p> |
| Words: | 2 |

.....continued

| MOVFF | Move f to f |
|---------|-------------|
| Cycles: | 2 (3) |

| Q Cycle Activity: | | | |
|-------------------|-------------------------------|--------------|---------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' (src) | Process Data | No operation |
| Decode | No operation No dummy read | No operation | Write register 'f' (dest) |

| | |
|---|------------------|
| Example: | MOVFF REG1, REG2 |
| Before Instruction REG1 = 33h REG2 = 11h After Instruction REG1 = 33h REG2 = 33h | |

| MOVLB | Move literal to low nibble in BSR |
|------------------|--|
| Syntax: | MOVLW k |
| Operands: | $0 \leq k \leq 255$ |
| Operation: | $k \rightarrow \text{BSR}$ |
| Status Affected: | None |
| Encoding: | 0000 0001 kkkk kkkk |
| Description: | The 8-bit literal 'k' is loaded into the Bank Select Register (BSR). The value of BSR<7:4> always remains '0', regardless of the value of k _{7:k₄} . |
| Words: | 1 |
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write literal 'k' to BSR |

| | | |
|---|-------|---|
| Example: | MOVLB | 5 |
| Before Instruction BSR Register = 02h After Instruction BSR Register = 05h | | |

| MOVLW | Move literal to W |
|------------------|---|
| Syntax: | MOVLW k |
| Operands: | $0 \leq k \leq 255$ |
| Operation: | $k \rightarrow W$ |
| Status Affected: | None |
| Encoding: | 0000 1110 kkkk kkkk |
| Description: | The 8-bit literal 'k' is loaded into W. |

.....continued

| MOVLW | Move literal to W | | | |
|---------|-------------------|--|--|--|
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to W |

| | | |
|------------------------------|-------|-----|
| Example: | MOVLW | 5Ah |
| After Instruction W = 5Ah | | |

| MOVWF | Move W to f | | | |
|------------------|--|------|------|------|
| Syntax: | MOVWF f {,a} | | | |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ | | | |
| Operation: | (W) \rightarrow f | | | |
| Status Affected: | None | | | |
| Encoding: | 0110 | 111a | ffff | ffff |
| Description: | Move data from W to register 'f'. The location 'f' can be anywhere in the 256-byte bank. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | |
|---|-------|--------|
| Example: | MOVWF | REG, 0 |
| Before Instruction W = 4Fh REG = FFh After Instruction W = 4Fh REG = 4Fh | | |

| MULLW | Multiply literal with W | | | |
|------------------|--|--|--|--|
| Syntax: | MULLW k | | | |
| Operands: | $0 \leq k \leq 255$ | | | |
| Operation: | (W) \times k \rightarrow PRODH:PRODL | | | |
| Status Affected: | None | | | |

.....continued

| MULLW | Multiply literal with W | | | |
|--------------|--|------|------|------|
| Encoding: | 0000 | 1101 | kkkk | kkkk |
| Description: | <p>An unsigned multiplication is carried out between the contents of W and the 8-bit literal 'k'. The 16-bit result is placed in the PRODH:PRODL register pair. PRODH contains the high byte. W is unchanged.</p> <p>None of the Status flags are affected.</p> <p>Note that neither overflow nor carry is possible in this operation. A zero result is possible but not detected.</p> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|-----------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write registers PRODH:PRODL |

| | |
|--|------------|
| Example: | MULLW 0C4h |
| <p>Before Instruction</p> <p>W = E2h</p> <p>PRODH = ?</p> <p>PRODL = ?</p> <p>After Instruction</p> <p>W = E2h</p> <p>PRODH = ADh</p> <p>PRODL = 08h</p> | |

| MULWF | Multiply W with f | | | |
|------------------|--|------|------|------|
| Syntax: | MULWF f {,a} | | | |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ | | | |
| Operation: | $(W) \times (f) \rightarrow \text{PRODH:PRODL}$ | | | |
| Status Affected: | None | | | |
| Encoding: | 0000 | 001a | ffff | ffff |
| Description: | <p>An unsigned multiplication is carried out between the contents of W and the register file location 'f'. The 16-bit result is stored in the PRODH:PRODL register pair. PRODH contains the high byte. Both W and 'f' are unchanged.</p> <p>None of the Status flags are affected.</p> <p>Note that neither overflow nor carry is possible in this operation. A zero result is possible but not detected.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|-----------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write registers PRODH:PRODL |

| | |
|---|--------------|
| Example: | MULWF REG, 1 |
| Before Instruction W = C4h REG = B5h PRODH = ? PRODL = ? After Instruction W = C4h REG = B5h PRODH = 8Ah PRODL = 94h | |

| NEGF | Negate f |
|------------------|---|
| Syntax: | NEGF f {,a} |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ |
| Operation: | $(f) + 1 \rightarrow f$ |
| Status Affected: | N, OV, C, DC, Z |
| Encoding: | <div>0110</div> <div>110a</div> <div>ffff</div> <div>ffff</div> |
| Description: | Location 'f' is negated using two's complement. The result is placed in the data memory location 'f'. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. |
| Words: | 1 |
| Cycles: | 1 |

| | | | |
|-------------------|-------------------|--------------|--------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | |
|---|-------------|
| Example: | NEGF REG, 1 |
| Before Instruction REG = 0011 1010 [3Ah] After Instruction REG = 1100 0110 [C6h] | |

| NOP | No Operation |
|------------------|---|
| Syntax: | NOP |
| Operands: | None |
| Operation: | No operation |
| Status Affected: | None |
| Encoding: | <div>0000</div> <div>1111</div> <div>0000</div> <div>xxxx</div> <div>0000</div> <div>xxxx</div> <div>0000</div> <div>xxxx</div> |
| Description: | No operation. |
| Words: | 1 |
| Cycles: | 1 |

| | | | |
|-------------------|--------------|--------------|--------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | No operation | No operation |

Example:

None.

| POP | Pop Top of Return Stack | | |
|------------------|--|------|-----------|
| Syntax: | POP | | |
| Operands: | None | | |
| Operation: | (TOS) → bit bucket | | |
| Status Affected: | None | | |
| Encoding: | 0000 | 0000 | 0000 0110 |
| Description: | The TOS value is pulled off the return stack and is discarded. The TOS value then becomes the previous value that was pushed onto the return stack. This instruction is provided to enable the user to properly manage the return stack to incorporate a software stack. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| | | | |
|-------------------|--------------|---------------|--------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | POP TOS value | No operation |

Example:

POP
GOTO

NEW

Before Instruction

TOS = 0031A2h

Stack (1 level down) = 014332h

After Instruction

TOS = 014332h

PC = NEW

| PUSH | Push Top of Return Stack | | |
|------------------|--|------|-----------|
| Syntax: | PUSH | | |
| Operands: | None | | |
| Operation: | (PC + 2) → TOS | | |
| Status Affected: | None | | |
| Encoding: | 0000 | 0000 | 0000 0101 |
| Description: | The PC + 2 is pushed onto the top of the return stack. The previous TOS value is pushed down on the stack. This instruction allows implementing a software stack by modifying TOS and then pushing it onto the return stack. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| | | | |
|-------------------|-------------------------------|--------------|--------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | PUSH PC + 2 onto return stack | No operation | No operation |

| | | | |
|---|------|--|--|
| Example: | PUSH | | |
| Before Instruction TOS = 345Ah PC = 0124h After Instruction PC = 0126h TOS = 0126h Stack (1 level down) = 345Ah | | | |

| RCALL | Relative Call | | |
|------------------|--|------|------|
| Syntax: | RCALL n | | |
| Operands: | $-1024 \leq n \leq 1023$ | | |
| Operation: | (PC) + 2 → TOS, (PC) + 2 + 2n → PC | | |
| Status Affected: | None | | |
| Encoding: | 1101 | 1nnn | nnnn |
| Description: | Subroutine call with a jump up to 1K from the current location. First, return address (PC + 2) is pushed onto the stack. Then, add the two's complement number '2n' to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC + 2 + 2n. This instruction is a two-cycle instruction. | | |
| Words: | 1 | | |
| Cycles: | 2 | | |

| | | | |
|-------------------|--------------------------------------|--------------|--------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'n' PUSH PC to stack | Process Data | Write to PC |
| No operation | No operation | No operation | No operation |

| | | | |
|---|------|-------|------|
| Example: | HERE | RCALL | Jump |
| Before Instruction PC = Address (HERE) After Instruction PC = Address (Jump) TOS = Address (HERE + 2) | | | |

| RESET | Reset | | |
|------------------|--|------|------|
| Syntax: | RESET | | |
| Operands: | None | | |
| Operation: | Reset all registers and flags that are affected by a MCLR Reset. | | |
| Status Affected: | All | | |
| Encoding: | 0000 | 0000 | 1111 |
| Description: | This instruction provides a way to execute a MCLR Reset by software. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| | | | |
|-------------------|----|----|----|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |

| | | | |
|--------|-------------|--------------|--------------|
| Decode | Start Reset | No operation | No operation |
|--------|-------------|--------------|--------------|

| | | | |
|--|-------|--|--|
| Example: | RESET | | |
| After Instruction Registers = Reset Value Flags* = Reset Value | | | |

| RETFIE | Return from Interrupt | | |
|------------------|--|------|-----------|
| Syntax: | RETFIE {s} | | |
| Operands: | $s \in [0,1]$ | | |
| Operation: | (TOS) \rightarrow PC, 1 \rightarrow GIE/GIEH or PEIE/GIEL, if $s = 1$ (WS) \rightarrow W, (STATUS) \rightarrow Status, (BSRS) \rightarrow BSR, PCLATU, PCLATH are unchanged. | | |
| Status Affected: | GIE/GIEH, PEIE/GIEL. | | |
| Encoding: | 0000 | 0000 | 0001 000s |
| Description: | Return from interrupt. Stack is popped and Top-of-Stack (TOS) is loaded into the PC. Interrupts are enabled by setting either the high- or low-priority Global Interrupt Enable bit. If 's' = 1, the contents of the shadow registers, WS, STATUS and BSRS, are loaded into their corresponding registers, W, Status and BSR. If 's' = 0, no update of these registers occurs (default). | | |
| Words: | 1 | | |
| Cycles: | 2 | | |

| Q Cycle Activity: | | | |
|-------------------|--------------|--------------|---------------------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | No operation | POP PC from stack Set GIEH or GIEL |
| No operation | No operation | No operation | No operation |

| | | | |
|---|----------|--|--|
| Example: | RETFIE 1 | | |
| After Interrupt PC = TOS W = WS BSR = BSRS Status = STATUS GIE/GIEH, PEIE/GIEL = 1 | | | |

| RETLW | Return literal to W | | |
|------------------|---|------|-----------|
| Syntax: | RETLW k | | |
| Operands: | $0 \leq k \leq 255$ | | |
| Operation: | k \rightarrow W, (TOS) \rightarrow PC, PCLATU, PCLATH are unchanged | | |
| Status Affected: | None | | |
| Encoding: | 0000 | 1100 | kkkk kkkk |

.....continued

| RETLW | Return literal to W | | |
|--------------|--|--|--|
| Description: | W is loaded with the 8-bit literal 'k'. The Program Counter is loaded from the top of the stack (the return address). The high address latch (PCLATH) remains unchanged. | | |
| Words: | 1 | | |
| Cycles: | 2 | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|-------------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | POP PC from stack, Write to W |
| No operation | No operation | No operation | No operation |

Example:

```

CALL TABLE          ; contains table
; offset value
; W now has
; table value
:
TABLE
ADDWF PCL             ; W = offset
RETLW k0              ; Begin table
RETLW k1              ;
:
:
RETLW kn              ; End of table

```

Before Instruction

W = 07h

After Instruction

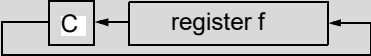
W = value of kn

| RETURN | Return from Subroutine | | |
|------------------|--|------|-----------|
| Syntax: | RETURN {s} | | |
| Operands: | s ∈ [0,1] | | |
| Operation: | (TOS) → PC, if s = 1 (WS) → W, (STATUS) → Status, (BSRS) → BSR, PCLATU, PCLATH are unchanged | | |
| Status Affected: | None | | |
| Encoding: | 0000 | 0000 | 0001 001s |
| Description: | Return from subroutine. The stack is popped and the top of the stack (TOS) is loaded into the Program Counter. If 's' = 1, the contents of the shadow registers, WS, STATUS and BSRS, are loaded into their corresponding registers, W, Status and BSR. If 's' = 0, no update of these registers occurs (default). | | |
| Words: | 1 | | |
| Cycles: | 2 | | |

| Q Cycle Activity: | | | |
|-------------------|--------------|--------------|-------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | Process Data | POP PC from stack |
| No operation | No operation | No operation | No operation |

| | |
|----------|--------|
| Example: | RETURN |
|----------|--------|

After Instruction:
PC = TOS

| RLCF | Rotate Left f through Carry | | |
|------------------|---|------|------|
| Syntax: | RLCF f {,d {,a}} | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | |
| Operation: | $(f<n>) \rightarrow \text{dest}<n + 1>$, $(f<7>) \rightarrow C$, $(C) \rightarrow \text{dest}<0>$ | | |
| Status Affected: | C, N, Z | | |
| Encoding: | 0011 | 01da | ffff |
| Description: | <p>The contents of register 'f' are rotated one bit to the left through the CARRY flag. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p>  | | |
| Words: | 1 | | |
| Cycles: | 1 | | |


| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | |
|----------|------|-----------|
| Example: | RLCF | REG, 0, 0 |
|----------|------|-----------|

Before Instruction
REG = 1110 0110
C = 0
After Instruction
REG = 1110 0110
W = 1100 1100
C = 1

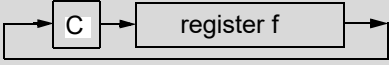
| RLNCF | Rotate Left f (No Carry) | | |
|------------------|--|--|--|
| Syntax: | RLNCF f {,d {,a}} | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | |
| Operation: | $(f<n>) \rightarrow \text{dest}<n + 1>$, $(f<7>) \rightarrow \text{dest}<0>$ | | |
| Status Affected: | N, Z | | |

.....continued

| RLNCF | Rotate Left f (No Carry) | | | |
|--------------|---|------|------|------|
| Encoding: | 0100 | 01da | ffff | ffff |
| Description: | <p>The contents of register 'f' are rotated one bit to the left. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> <div style="text-align: center;">  </div> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|-------------------|--------------|----------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

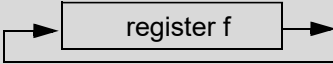
| | | |
|--|-------|-----------|
| Example: | RLNCF | REG, 1, 0 |
| <p>Before Instruction REG = 1010 1011</p> <p>After Instruction REG = 0101 0111</p> | | |

| RRCF | Rotate Right f through Carry | | | |
|------------------|---|------|------|------|
| Syntax: | RRCF f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | $(f < n) \rightarrow \text{dest} < n - 1 >$, $(f < 0) \rightarrow C$, $(C) \rightarrow \text{dest} < 7 >$ | | | |
| Status Affected: | C, N, Z | | | |
| Encoding: | 0011 | 00da | ffff | ffff |
| Description: | <p>The contents of register 'f' are rotated one bit to the right through the CARRY flag. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> <div style="text-align: center;">  </div> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|----|----|----|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |

| Decode | Read register 'f' | Process Data | Write to destination |
|--------|-------------------|--------------|----------------------|
|--------|-------------------|--------------|----------------------|

| | | |
|--|------|-----------|
| Example: | RRCF | REG, 0, 0 |
| Before Instruction REG = 1110 0110 C = 0 After Instruction REG = 1110 0110 W = 0111 0011 C = 0 | | |

| RRNCF | Rotate Right f (No Carry) | | |
|------------------|---|------|------|
| Syntax: | RRNCF f {,d {,a}} | | |
| Operands: | 0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1] | | |
| Operation: | (f<n>) → dest<n - 1>, (f<0>) → dest<7> | | |
| Status Affected: | N, Z | | |
| Encoding: | 0100 | 00da | ffff |
| Description: | The contents of register 'f' are rotated one bit to the right. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). If 'a' is '0', the Access Bank will be selected (default), overriding the BSR value. If 'a' is '1', then the bank will be selected as per the BSR value. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. <div style="text-align: center;">  </div> | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| | | | |
|-------------------|-------------------|--------------|----------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | |
|---|-----------------|
| Example 1: | RRNCF REG, 1, 0 |
| Before Instruction REG = 1101 0111 After Instruction REG = 1110 1011 | |
| Example 2: | RRNCF REG, 0, 0 |

Before Instruction
W = ?
REG = 1101 0111
After Instruction
W = 1110 1011
REG = 1101 0111

| SETF | Set f |
|------------------|--|
| Syntax: | SETF f {,a} |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ |
| Operation: | $FFh \rightarrow f$ |
| Status Affected: | None |
| Encoding: | 0110100affff |
| Description: | The contents of the specified register are set to FFh. If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. |
| Words: | 1 |
| Cycles: | 1 |

| | | | |
|-------------------|-------------------|--------------|--------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write register 'f' |

| | | |
|---------------------------------|------|--------|
| Example: | SETF | REG, 1 |
| Before Instruction REG = 5Ah | | |
| After Instruction REG = FFh | | |

| SLEEP | Enter Sleep mode |
|------------------|---|
| Syntax: | SLEEP |
| Operands: | None |
| Operation: | $00h \rightarrow WDT$, $0 \rightarrow WDT$ postscaler, $1 \rightarrow \overline{TO}$, $0 \rightarrow \overline{PD}$ |
| Status Affected: | \overline{TO} , \overline{PD} |
| Encoding: | 0000000000000011 |
| Description: | The Power-Down (\overline{PD}) Status bit is cleared. The Time-out (\overline{TO}) Status bit is set. Watchdog Timer and its postscaler are cleared. The processor is put into Sleep mode with the oscillator stopped. |
| Words: | 1 |
| Cycles: | 1 |

| | | |
|-------------------|--|--|
| Q Cycle Activity: | | |
|-------------------|--|--|

| Q1 | Q2 | Q3 | Q4 |
|--------|--------------|--------------|-------------|
| Decode | No operation | Process Data | Go to Sleep |

Example:

SLEEP

Before Instruction

$\overline{TO} = ?$

$\overline{PD} = ?$

After Instruction

$\overline{TO} = 1 \dagger$

$\overline{PD} = 0$

\dagger If WDT causes wake-up, this bit is cleared.

| SUBFWB | Subtract f from W with borrow (Continued) | | |
|------------------|--|------|------|
| Syntax: | SUBFWB f {,d {,a}} | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | |
| Operation: | $(W) - (f) - (\overline{C}) \rightarrow \text{dest}$ | | |
| Status Affected: | N, OV, C, DC, Z | | |
| Encoding: | 0101 | 01da | ffff |
| Description: | Subtract register 'f' and CARRY flag (borrow) from W (two's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

Q Cycle Activity:

| Q1 | Q2 | Q3 | Q4 |
|--------|-------------------|--------------|----------------------|
| Decode | Read register 'f' | Process Data | Write to destination |

Example 1:

SUBFWB REG, 1, 0

Before Instruction

REG = 3

W = 2

C = 1

After Instruction

REG = FF

W = 2

C = 0

Z = 0

N = 1 ; result is negative

Example 2:

SUBFWB REG, 0, 0

Before Instruction
REG = 2
W = 5
C = 1
After Instruction
REG = 2
W = 3
C = 1
Z = 0
N = 0 ; result is positive

Example 3: SUBFWB REG, 1, 0

Before Instruction
REG = 1
W = 2
C = 0
After Instruction
REG = 0
W = 2
C = 1
Z = 1 ; result is zero
N = 0

| SUBLW | Subtract W from literal | | | |
|------------------|--|------|------|------|
| Syntax: | SUBLW k | | | |
| Operands: | $0 \leq k \leq 255$ | | | |
| Operation: | $k - (W) \rightarrow$ | | | |
| Status Affected: | N, OV, C, DC, Z | | | |
| Encoding: | 0000 | 1000 | kkkk | kkkk |
| Description | W is subtracted from the 8-bit literal 'k'. The result is placed in W. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|------------------|--------------|------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to W |

Example 1: SUBLW 02h

Before Instruction
W = 01h
C = ?
After Instruction
W = 01h
C = 1 ; result is positive
Z = 0
N = 0

Example 2: SUBLW 02h

Before Instruction
W = 02h
C = ?
After Instruction
W = 00h
C = 1 ; result is zero
Z = 1
N = 0

Example 3:

SUBLW

02h

Before Instruction
W = 03h
C = ?
After Instruction
W = FFh ; (two's complement)
C = 0 ; result is negative
Z = 0
N = 1

| SUBWF | Subtract W from f | | |
|------------------|---|------|------|
| Syntax: | SUBWF f {,d {,a}} | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | |
| Operation: | $(f) - (W) \rightarrow \text{dest}$ | | |
| Status Affected: | N, OV, C, DC, Z | | |
| Encoding: | 0101 | 11da | ffff |
| Description: | Subtract W from register 'f' (two's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | |
| Words: | 1 | | |
| Cycles: | 1 | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

Example 1:

SUBWF REG, 1, 0

Before Instruction

REG = 3

W = 2

C = ?

After Instruction

REG = 1

W = 2

C = 1 ; result is positive

Z = 0

N = 0

Example 2:

SUBWF REG, 0, 0

Before Instruction

REG = 2

W = 2

C = ?

After Instruction

REG = 2

W = 0

C = 1 ; result is zero

Z = 1

N = 0

Example 3:

SUBWF REG, 1, 0

Before Instruction

REG = 1

W = 2

C = ?

After Instruction

REG = FFh ; (two's complement)

W = 2

C = 0 ; result is negative

Z = 0

N = 1

| SUBWFB | Subtract W from f with Borrow | | | |
|------------------|---|------|------|------|
| Syntax: | SUBWFB f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | $(f) - (W) - (\bar{C}) \rightarrow \text{dest}$ | | | |
| Status Affected: | N, OV, C, DC, Z | | | |
| Encoding: | 0101 | 10da | ffff | ffff |
| Description: | Subtract W and the CARRY flag (borrow) from register 'f' (two's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |
| Words: | 1 | | | |

.....continued

| SUBWFB | Subtract W from f with Borrow |
|---------|-------------------------------|
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | |
|------------|------------------|
| Example 1: | SUBWFB REG, 1, 0 |
|------------|------------------|

Before Instruction
REG = 19h (0001 1001)
W = 0Dh (0000 1101)
C = 1
After Instruction
REG = 0Ch (0000 1100)
W = 0Dh (0000 1101)
C = 1
Z = 0
N = 0 ; result is positive

| | |
|------------|------------------|
| Example 2: | SUBWFB REG, 0, 0 |
|------------|------------------|

Before Instruction
REG = 1Bh (0001 1011)
W = 1Ah (0001 1010)
C = 0
After Instruction
REG = 1Bh (0001 1011)
W = 00h
C = 1
Z = 1 ; result is zero
N = 0

| | |
|------------|------------------|
| Example 3: | SUBWFB REG, 1, 0 |
|------------|------------------|

Before Instruction
REG = 03h (0000 0011)
W = 0Eh (0000 1110)
C = 1
After Instruction
REG = F5h (1111 0101)
; [two's complement]
W = 0Eh (0000 1110)
C = 0
Z = 0
N = 1 ; result is negative

| SWAPF | Swap f |
|---------|-----------------|
| Syntax: | SWAPF f {d {a}} |

.....continued

| SWAPF | Swap f |
|------------------|---|
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ |
| Operation: | $(f<3:0>) \rightarrow \text{dest}<7:4>$, $(f<7:4>) \rightarrow \text{dest}<3:0>$ |
| Status Affected: | None |
| Encoding: | <div>0011</div> <div>10da</div> <div>ffff</div> <div>ffff</div> |
| Description: | <p>The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> |
| Words: | 1 |
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | |
|---|-------|-----------|
| Example: | SWAPF | REG, 1, 0 |
| Before Instruction REG = 53h After Instruction REG = 35h | | |

| TBLRD | Table Read |
|------------------|---|
| Syntax: | TBLRD (*, **; *, **; +*) |
| Operands: | None |
| Operation: | <p>if TBLRD *, (Prog Mem (TBLPTR)) → TABLAT; TBLPTR – No Change;</p> <p>if TBLRD **+, (Prog Mem (TBLPTR)) → TABLAT; (TBLPTR) + 1 → TBLPTR;</p> <p>if TBLRD *- , (Prog Mem (TBLPTR)) → TABLAT; (TBLPTR) – 1 → TBLPTR;</p> <p>if TBLRD +*, (TBLPTR) + 1 → TBLPTR; (Prog Mem (TBLPTR)) → TABLAT;</p> |
| Status Affected: | None |

.....continued

| TBLRD | Table Read | | | |
|--------------|--|------|------|---|
| Encoding: | 0000 | 0000 | 0000 | 10nn nn=0 * =1 *+ =2 *- =3 +* |
| Description: | <p>This instruction is used to read the contents of Program Memory (P.M.). To address the program memory, a pointer called Table Pointer (TBLPTR) is used. The TBLPTR (a 21-bit pointer) points to each byte in the program memory. TBLPTR has a 2-Mbyte address range.</p> <p>TBLPTR[0] = 0: Least Significant Byte of Program Memory Word TBLPTR[0] = 1: Most Significant Byte of Program Memory Word</p> <p>The TBLRD instruction can modify the value of TBLPTR as follows:</p> <ul style="list-style-type: none"> no change post-increment post-decrement pre-increment | | | |
| Words: | 1 | | | |
| Cycles: | 2 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------------------------|--------------|-----------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | No operation | No operation | No operation |
| No operation | No operation (Read Program Memory) | No operation | No operation (Write TABLAT) |

| TBLRD | Table Read (Continued) |
|--|------------------------|
| Example1: | TBLRD *+ ; |
| <p>Before Instruction TABLAT = 55h TBLPTR = 00A356h MEMORY (00A356h) = 34h</p> <p>After Instruction TABLAT = 34h TBLPTR = 00A357h</p> | |
| Example2: | TBLRD ++ ; |
| <p>Before Instruction TABLAT = AAh TBLPTR = 01A357h MEMORY (01A357h) = 12h MEMORY (01A358h) = 34h</p> <p>After Instruction TABLAT = 34h TBLPTR = 01A358h</p> | |

| TBLWT (Continued) | Table Write |
|----------------------|------------------------|
| Syntax: | TBLWT (*, *+, *-, +*) |

.....continued

| TBLWT (Continued) | Table Write | | | |
|----------------------|--|----------------------------|--------------|---|
| Operands: | None | | | |
| Operation: | if TBLWT*, (TABLAT) → Holding Register; TBLPTR – No Change; if TBLWT*+, (TABLAT) → Holding Register; (TBLPTR) + 1 → TBLPTR; if TBLWT*-, (TABLAT) → Holding Register; (TBLPTR) – 1 → TBLPTR; if TBLWT*+*, (TBLPTR) + 1 → TBLPTR; (TABLAT) → Holding Register; | | | |
| Status Affected: | None | | | |
| Encoding: | 0000 | 0000 | 0000 | 11nn nn=0 * =1 *+ =2 *- =3 +* |
| Description: | <p>This instruction uses the LSBs of TBLPTR to determine which of the holding registers the TABLAT is written to. The holding registers are used to program the contents of Program Memory (P.M.). Refer to the “Program Flash Memory” section for additional details on programming Flash memory.</p> <p>The TBLPTR (a 21-bit pointer) points to each byte in the program memory. TBLPTR has a 2-MByte address range. The LSB of the TBLPTR selects which byte of the program memory location to access.</p> <p>TBLPTR[0] = 0: Least Significant Byte of Program Memory Word TBLPTR[0] = 1: Most Significant Byte of Program Memory Word</p> <p>The TBLWT instruction can modify the value of TBLPTR as follows:</p> <ul style="list-style-type: none">• no change• post-increment• post-decrement• pre-increment | | | |
| Words: | 1 | | | |
| Cycles: | 2 | | | |
| Q Cycle Activity: | | | | |
| | Q1 | Q2 | Q3 | Q4 |
| | Decode | No operation | No operation | No operation |
| | No operation | No operation (Read TABLAT) | No operation | No operation (Write to Holding Register) |
| TBLWT | | Table Write (Continued) | | |
| Example1: | | TBLWT *+; | | |

Before Instruction
TABLAT = 55h
TBLPTR = 00A356h
HOLDING REGISTER
(00A356h) = FFh
After Instructions (table write completion)
TABLAT = 55h
TBLPTR = 00A357h
HOLDING REGISTER
(00A356h) = 55h

Example 2: TBLWT +*;

Before Instruction
TABLAT = 34h
TBLPTR = 01389Ah
HOLDING REGISTER
(01389Ah) = FFh
HOLDING REGISTER
(01389Bh) = FFh
After Instruction (table write completion)
TABLAT = 34h
TBLPTR = 01389Bh
HOLDING REGISTER
(01389Ah) = FFh
HOLDING REGISTER
(01389Bh) = 34h

| TSTFSZ | Test f, skip if 0 | | |
|------------------|--|------|------|
| Syntax: | TSTFSZ f {,a} | | |
| Operands: | $0 \leq f \leq 255$ $a \in [0,1]$ | | |
| Operation: | skip if f = 0 | | |
| Status Affected: | None | | |
| Encoding: | 0110 | 011a | ffff |
| Description: | <p>If 'f' = 0, the next instruction fetched during the current instruction execution is discarded and a NOP is executed, making this a two-cycle instruction.</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details.</p> | | |
| Words: | 1 | | |
| Cycles: | 1(2) Note: Three cycles if skip and followed by a two-word instruction. | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | No operation |

| If skip: | | | |
|---|--------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| No operation | No operation | No operation | No operation |
| If skip and followed by two-word instruction: | | | |

| Q1 | Q2 | Q3 | Q4 |
|--------------|--------------|--------------|--------------|
| No operation | No operation | No operation | No operation |
| No operation | No operation | No operation | No operation |

Example:

```
HERE    TSTFSZ  CNT, 1
NZERO   :
ZERO    :
```

Before Instruction
PC = Address (HERE)

After Instruction

If CNT = 00h,

PC = Address (ZERO)

If CNT ≠ 00h,

PC = Address (NZERO)

| XORLW | Exclusive OR literal with W | | | |
|------------------|--|------|------|------|
| Syntax: | XORLW k | | | |
| Operands: | $0 \leq k \leq 255$ | | | |
| Operation: | (W) .XOR. k → | | | |
| Status Affected: | N, Z | | | |
| Encoding: | 0000 | 1010 | kkkk | kkkk |
| Description: | The contents of W are XORed with the 8-bit literal 'k'. The result is placed in W. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to W |

Example:

XORLW

0AFh

Before Instruction

W = B5h

After Instruction

W = 1Ah

| XORWF | Exclusive OR W with f | | | |
|------------------|---|------|------|------|
| Syntax: | XORWF f {,d {,a}} | | | |
| Operands: | $0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$ | | | |
| Operation: | (W) .XOR. (f) → dest | | | |
| Status Affected: | N, Z | | | |
| Encoding: | 0001 | 10da | ffff | ffff |
| Description: | Exclusive OR the contents of W with register 'f'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in the register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode for details. | | | |

.....continued

| XORWF | Exclusive OR W with f | | | |
|---------|-----------------------|--|--|--|
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | |
|---|-----------------|
| Example: | XORWF REG, 1, 0 |
| Before Instruction REG = AFh W = B5h After Instruction REG = 1Ah W = B5h | |

38.2 Extended Instruction Set

In addition to the standard 75 instructions of the PIC18 instruction set, the PIC18F26/45/46Q10 devices also provide an optional extension to the core CPU functionality. The added features include eight additional instructions that augment Indirect and Indexed Addressing operations and the implementation of Indexed Literal Offset Addressing mode for many of the standard PIC18 instructions.

The additional features of the extended instruction set are disabled by default. To enable them, users must set the XINST Configuration bit.

The instructions in the extended set can all be classified as literal operations, which either manipulate the File Select Registers, or use them for Indexed Addressing. Two of the instructions, ADDFSR and SUBFSR, each have an additional special instantiation for using FSR2. These versions (ADDULNK and SUBULNK) allow for automatic return after execution.

The extended instructions are specifically implemented to optimize re-entrant program code (that is, code that is recursive or that uses a software stack) written in high-level languages, particularly C. Among other things, they allow users working in high-level languages to perform certain operations on data structures more efficiently. These include:

- dynamic allocation and deallocation of software stack space when entering and leaving subroutines
- function pointer invocation
- software Stack Pointer manipulation
- manipulation of variables located in a software stack

A summary of the instructions in the extended instruction set is provided in [Extended Instruction Syntax](#). Detailed descriptions are provided in [Extended Instruction Set](#). The opcode field descriptions in [Standard Instruction Set](#) apply to both the standard and extended PIC18 instruction sets.

➔ Important: The instruction set extension and the Indexed Literal Offset Addressing mode were designed for optimizing applications written in C; the user may likely never use these instructions directly in assembler. The syntax for these commands is provided as a reference for users who may be reviewing code that has been generated by a compiler.

38.2.1 Extended Instruction Syntax

Most of the extended instructions use indexed arguments, using one of the File Select Registers and some offset to specify a source or destination register. When an argument for an instruction serves as part of Indexed Addressing, it is enclosed in square brackets ("[]"). This is done to indicate that the argument is used as an index or offset. MPASM™ Assembler will flag an error if it determines that an index or offset value is not bracketed.

When the extended instruction set is enabled, brackets are also used to indicate index arguments in byte-oriented and bit-oriented instructions. This is in addition to other changes in their syntax. For more details, see [Extended Instruction Syntax with Standard PIC18 Commands](#).

➔ Important: In the past, square brackets have been used to denote optional arguments in the PIC18 and earlier instruction sets. In this text and going forward, optional arguments are denoted by braces ("{}").

Table 38-3. Extensions to the PIC18 Instruction Set

| Mnemonic, Operands | | Description | Cycles | 16-Bit Instruction Word | | | | Status Affected |
|-----------------------|---------------------------------|--|--------|-------------------------|------|------|------|--------------------|
| | | | | MSb | | | LSb | |
| ADDFSR | f, k | Add literal to FSR | 1 | 1110 | 1000 | ffkk | kkkk | None |
| ADDULNK | k | Add literal to FSR2 and return | 2 | 1110 | 1000 | 11kk | kkkk | None |
| CALLW | | Call subroutine using WREG | 2 | 0000 | 0000 | 0001 | 0100 | None |
| MOVSF | z _s , f _d | Move z _s (source) to 1st word | 2 | 1110 | 1011 | 0zzz | zzzz | None |
| | | f _d (destination) 2nd word | | 1111 | ffff | ffff | ffff | |
| MOVSS | z _s , z _d | Move z _s (source) to 1st word | 2 | 1110 | 1011 | 1zzz | zzzz | None |
| | | z _d (destination) 2nd word | | 1111 | xxxx | xzzz | zzzz | |
| PUSHL | k | Store literal at FSR2, decrement FSR2 | 1 | 1110 | 1010 | kkkk | kkkk | None |
| SUBFSR | f, k | Subtract literal from FSR | 1 | 1110 | 1001 | ffkk | kkkk | None |
| SUBULNK | k | Subtract literal from FSR2 and return | 2 | 1110 | 1001 | 11kk | kkkk | None |

38.2.2 Extended Instruction Set

| ADDFSR | Add Literal to FSR |
|------------------|---|
| Syntax: | ADDFSR f, k |
| Operands: | $0 \leq k \leq 63$ $f \in [0, 1, 2]$ |
| Operation: | $FSR(f) + k \rightarrow FSR(f)$ |
| Status Affected: | None |
| Encoding: | 1110 1000 fffk kkkk |
| Description: | The 6-bit literal 'k' is added to the contents of the FSR specified by 'f'. |
| Words: | 1 |
| Cycles: | 1 |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to FSR |

| | |
|------------------------------------|---------------|
| Example: | ADDFSR 2, 23h |
| Before Instruction FSR2 = 03FFh | |
| After Instruction FSR2 = 0422h | |

| ADDULNK | Add Literal to FSR2 and Return |
|------------------|---|
| Syntax: | ADDULNK k |
| Operands: | $0 \leq k \leq 63$ |
| Operation: | $FSR2 + k \rightarrow FSR2,$ $(TOS) \rightarrow PC$ |
| Status Affected: | None |
| Encoding: | 1110 1000 11kk kkkk |
| Description: | The 6-bit literal 'k' is added to the contents of FSR2. A RETURN is then executed by loading the PC with the TOS. The instruction takes two cycles to execute; a NOP is performed during the second cycle. This may be thought of as a special case of the ADDFSR instruction, where $f = 3$ (binary '11'); it operates only on FSR2. |
| Words: | 1 |
| Cycles: | 2 |

| Q Cycle Activity: | | | |
|-------------------|------------------|--------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read literal 'k' | Process Data | Write to FSR |
| No Operation | No Operation | No Operation | No Operation |

| | |
|----------|-------------|
| Example: | ADDULNK 23h |
|----------|-------------|

Before Instruction
FSR2 = 03FFh
PC = 0100h
After Instruction
FSR2 = 0422h
PC = (TOS)



Important: All PIC18 instructions may take an optional label argument preceding the instruction mnemonic for use in symbolic addressing. If a label is used, the instruction syntax then becomes: {label} instruction argument(s).

| CALLW | Subroutine Call Using WREG | | |
|------------------|---|------|-----------|
| Syntax: | CALLW | | |
| Operands: | None | | |
| Operation: | (PC + 2) → TOS, (W) → PCL, (PCLATH) → PCH, (PCLATU) → PCU | | |
| Status Affected: | None | | |
| Encoding: | 0000 | 0000 | 0001 0100 |
| Description | First, the return address (PC + 2) is pushed onto the return stack. Next, the contents of W are written to PCL; the existing value is discarded. Then, the contents of PCLATH and PCLATU are latched onto PCH and PCU, respectively. The second cycle is executed as a NOP instruction while the new next instruction is fetched. Unlike CALL, there is no option to update W, Status or BSR. | | |
| Words: | 1 | | |
| Cycles: | 2 | | |

| Q Cycle Activity: | | | |
|-------------------|--------------|------------------|--------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read WREG | PUSH PC to stack | No operation |
| No operation | No operation | No operation | No operation |

| | | |
|--|------|-------|
| Example: | HERE | CALLW |
| Before Instruction PC = address (HERE) PCLATH = 10h PCLATU = 00h W = 06h After Instruction PC = 001006h TOS = address (HERE + 2) PCLATH = 10h PCLATU = 00h W = 06h | | |

| MOVSF | Move Indexed to f | | | |
|--|--|------------------|------------------|----------------------|
| Syntax: | MOVSF [z_s], f_d | | | |
| Operands: | $0 \leq z_s \leq 127$ $0 \leq f_d \leq 4095$ | | | |
| Operation: | $((FSR2) + z_s) \rightarrow f_d$ | | | |
| Status Affected: | None | | | |
| Encoding: 1st word (source) 2nd word (destin.) | 1110 1111 | 1011 $ffff$ | $0zzz$ $ffff$ | $zzzz_s$ $ffff_d$ |
| Description: | <p>The contents of the source register are moved to destination register 'f_d'. The actual address of the source register is determined by adding the 7-bit literal offset 'z_s' in the first word to the value of FSR2. The address of the destination register is specified by the 12-bit literal 'f_d' in the second word. Both addresses can be anywhere in the 4096-byte data space (000h to FFFh).</p> <p>The MOVSF instruction cannot use the PCL, TOSU, TOSH or TOSL as the destination register.</p> <p>If the resultant source address points to an Indirect Addressing register, the value returned will be 00h.</p> | | | |
| Words: | 2 | | | |
| Cycles: | 2 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------------------|-----------------------|-------------------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Determine source addr | Determine source addr | Read source reg |
| Decode | No operation No dummy read | No operation | Write register ' f ' (dest) |

| | |
|---|--------------------------|
| Example: | MOVSF [$05h$], REG2 |
| <p>Before Instruction FSR2 = 80h Contents of 85h = 33h REG2 = 11h After Instruction FSR2 = 80h Contents of 85h = 33h REG2 = 33h</p> | |

| MOVSS | Move Indexed to Indexed |
|------------------|--|
| Syntax: | MOVSS [z_s], [z_d] |
| Operands: | $0 \leq z_s \leq 127$ $0 \leq z_d \leq 127$ |
| Operation: | $((FSR2) + z_s) \rightarrow ((FSR2) + z_d)$ |
| Status Affected: | None |

.....continued

| MOVSS | Move Indexed to Indexed | | | |
|--|--|--------------|--------------|--|
| Encoding: 1st word (source) 2nd word (dest.) | 1110 1111 | 1011 xxxx | 1zzz xzzz | zzzz _s zzzz _d |
| Description | <p>The contents of the source register are moved to the destination register. The addresses of the source and destination registers are determined by adding the 7-bit literal offsets 'z_s' or 'z_d', respectively, to the value of FSR2. Both registers can be located anywhere in the 4096-byte data memory space (000h to FFFh). The MOVSS instruction cannot use the PCL, TOSU, TOSH or TOSL as the destination register. If the resultant source address points to an Indirect Addressing register, the value returned will be 00h. If the resultant destination address points to an Indirect Addressing register, the instruction will execute as a NOP.</p> | | | |
| Words: | 2 | | | |
| Cycles: | 2 | | | |

| | | | |
|-------------------|-----------------------|-----------------------|-------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Determine source addr | Determine source addr | Read source reg |
| Decode | Determine dest addr | Determine dest addr | Write to dest reg |

| | |
|---|--------------------|
| Example: | MOVSS [05h], [06h] |
| <p>Before Instruction FSR2 = 80h Contents of 85h = 33h Contents of 86h = 11h After Instruction FSR2 = 80h Contents of 85h = 33h Contents of 86h = 33h</p> | |

| PUSHL | Store Literal at FSR2, Decrement FSR2 | | | |
|------------------|---|------|------|------|
| Syntax: | PUSHL k | | | |
| Operands: | 0 ≤ k ≤ 255 | | | |
| Operation: | k → (FSR2), FSR2 – 1 → FSR2 | | | |
| Status Affected: | None | | | |
| Encoding: | 1111 | 1010 | kkkk | kkkk |
| Description: | <p>The 8-bit literal 'k' is written to the data memory address specified by FSR2. FSR2 is decremented by 1 after the operation. This instruction allows users to push values onto a software stack.</p> | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| | | | |
|-------------------|----------|--------------|----------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read 'k' | Process data | Write to destination |

Example:

PUSHL 08h

Before Instruction
FSR2H:FSR2L = 01ECh
Memory (01ECh) = 00h
After Instruction
FSR2H:FSR2L = 01EBh
Memory (01ECh) = 08h

| SUBFSR | Subtract Literal from FSR |
|------------------|--|
| Syntax: | SUBFSR f, k |
| Operands: | $0 \leq k \leq 63$ $f \in [0, 1, 2]$ |
| Operation: | $FSR(f) - k \rightarrow FSRf$ |
| Status Affected: | None |
| Encoding: | 1110 1001 ffkk kkkk |
| Description: | The 6-bit literal 'k' is subtracted from the contents of the FSR specified by 'f'. |
| Words: | 1 |
| Cycles: | 1 |

| | | | |
|-------------------|-------------------|--------------|----------------------|
| Q Cycle Activity: | | | |
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

Example:

SUBFSR 2, 23h

Before Instruction
FSR2 = 03FFh
After Instruction
FSR2 = 03DCh

| SUBULNK | Subtract Literal from FSR2 and Return |
|------------------|--|
| Syntax: | SUBULNK k |
| Operands: | $0 \leq k \leq 63$ |
| Operation: | $FSR2 - k \rightarrow FSR2$ (TOS) \rightarrow PC |
| Status Affected: | None |
| Encoding: | 1110 1001 11kk kkkk |
| Description: | The 6-bit literal 'k' is subtracted from the contents of the FSR2. A RETURN is then executed by loading the PC with the TOS. The instruction takes two cycles to execute; a NOP is performed during the second cycle. This may be thought of as a special case of the SUBFSR instruction, where f = 3 (binary '11'); it operates only on FSR2. |
| Words: | 1 |

.....continued

| SUBULNK | Subtract Literal from FSR2 and Return |
|---------|---------------------------------------|
| Cycles: | 2 |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |
| No Operation | No Operation | No Operation | No Operation |

| Example: | SUBULNK 23h |
|---|-------------|
| Before Instruction FSR2 = 03FFh PC = 0100h After Instruction FSR2 = 03DCh PC = (TOS) | |

38.2.3 Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode



Important: Enabling the PIC18 instruction set extension may cause legacy applications to behave erratically or fail entirely.

In addition to eight new commands in the extended set, enabling the extended instruction set also enables Indexed Literal Offset Addressing mode (Section “Indexed Addressing with Literal Offset”). This has a significant impact on the way that many commands of the standard PIC18 instruction set are interpreted.

When the extended set is disabled, addresses embedded in opcodes are treated as literal memory locations: either as a location in the Access Bank ('a' = 0), or in a GPR bank designated by the BSR ('a' = 1). When the extended instruction set is enabled and 'a' = 0, however, a file register argument of 5Fh or less is interpreted as an offset from the pointer value in FSR2 and not as a literal address. For practical purposes, this means that all instructions that use the Access RAM bit as an argument – that is, all byte-oriented and bit-oriented instructions, or almost half of the core PIC18 instructions – may behave differently when the extended instruction set is enabled.

When the content of FSR2 is 00h, the boundaries of the Access RAM are essentially remapped to their original values. This may be useful in creating backward compatible code. If this technique is used, it may be necessary to save the value of FSR2 and restore it when moving back and forth between C and assembly routines in order to preserve the Stack Pointer. Users must also keep in mind the syntax requirements of the extended instruction set (see [Extended Instruction Syntax with Standard PIC18 Commands](#)).

Although the Indexed Literal Offset Addressing mode can be very useful for dynamic stack and pointer manipulation, it can also be very annoying if a simple arithmetic operation is carried out on the wrong register. Users who are accustomed to the PIC18 programming must keep in mind that, when the extended instruction set is enabled, register addresses of 5Fh or less are used for Indexed Literal Offset Addressing.

Representative examples of typical byte-oriented and bit-oriented instructions in the Indexed Literal Offset Addressing mode are provided on the following page to show how execution is affected. The operand conditions shown in the examples are applicable to all instructions of these types.

Related Links[Data Memory and the Extended Instruction Set](#)**38.2.3.1 Extended Instruction Syntax with Standard PIC18 Commands**

When the extended instruction set is enabled, the file register argument, 'f', in the standard byte-oriented and bit-oriented commands is replaced with the literal offset value, 'k'. As already noted, this occurs only when 'f' is less than or equal to 5Fh. When an offset value is used, it must be indicated by square brackets ("[]"). As with the extended instructions, the use of brackets indicates to the compiler that the value is to be interpreted as an index or an offset. Omitting the brackets, or using a value greater than 5Fh within brackets, will generate an error in the MPASM assembler.

If the index argument is properly bracketed for Indexed Literal Offset Addressing, the Access RAM argument is never specified; it will automatically be assumed to be '0'. This is in contrast to standard operation (extended instruction set disabled) when 'a' is set on the basis of the target address. Declaring the Access RAM bit in this mode will also generate an error in the MPASM assembler.

The destination argument, 'd', functions as before.

In the latest versions of the MPASM™ assembler, language support for the extended instruction set must be explicitly invoked. This is done with either the command-line option, /y, or the PE directive in the source listing.

Related Links[Data Memory and the Extended Instruction Set](#)**38.2.4 Considerations when Enabling the Extended Instruction Set**

It is important to note that the extensions to the instruction set may not be beneficial to all users. In particular, users who are not writing code that uses a software stack may not benefit from using the extensions to the instruction set.

Additionally, the Indexed Literal Offset Addressing mode may create issues with legacy applications written to the PIC18 assembler. This is because instructions in the legacy code may attempt to address registers in the Access Bank below 5Fh. Since these addresses are interpreted as literal offsets to FSR2 when the instruction set extension is enabled, the application may read or write to the wrong data addresses.

When porting an application to the PIC18F26/45/46Q10 it is very important to consider the type of code. A large, re-entrant application that is written in 'C' and would benefit from efficient compilation will do well when using the instruction set extensions. Legacy applications that heavily use the Access Bank will most likely not benefit from using the extended instruction set.

| ADDWF | ADD W to Indexed (Indexed Literal Offset mode) | | | |
|-------------------|---|------|------|------|
| Syntax: | ADDWF [k] {,d} | | | |
| Operands: | $0 \leq k \leq 95$ $d \in [0,1]$ | | | |
| Operation: | $(W) + ((FSR2) + k) \rightarrow \text{dest}$ | | | |
| Status Affected: | N, OV, C, DC, Z | | | |
| Encoding: | 0010 | 01d0 | kkkk | kkkk |
| Description: | The contents of W are added to the contents of the register indicated by FSR2, offset by the value 'k'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default). | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |
| Q Cycle Activity: | | | | |

| Q1 | Q2 | Q3 | Q4 |
|--------|----------|--------------|----------------------|
| Decode | Read 'k' | Process Data | Write to destination |

| | | | |
|----------|-------|--------|-----|
| Example: | ADDWF | [OFST] | , 0 |
|----------|-------|--------|-----|

Before Instruction
W = 17h
OFST = 2Ch
FSR2 = 0A00h
Contents
of 0A2Ch = 20h
After Instruction
W = 37h
Contents
of 0A2Ch = 20h

| BSF | Bit Set Indexed (Indexed Literal Offset mode) | | | |
|------------------|---|------|------|------|
| Syntax: | BSF [k], b | | | |
| Operands: | $0 \leq f \leq 95$ $0 \leq b \leq 7$ | | | |
| Operation: | $1 \rightarrow ((FSR2) + k) \langle b \rangle$ | | | |
| Status Affected: | None | | | |
| Encoding: | 1000 | bbb0 | kkkk | kkkk |
| Description: | Bit 'b' of the register indicated by FSR2, offset by the value 'k', is set. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|-------------------|--------------|----------------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read register 'f' | Process Data | Write to destination |

| | | |
|----------|-----|----------------|
| Example: | BSF | [FLAG_OFST], 7 |
|----------|-----|----------------|

Before Instruction
FLAG_OFST = 0Ah
FSR2 = 0A00h
Contents
of 0A0Ah = 55h
After Instruction
Contents
of 0A0Ah = D5h

| SETF | Set Indexed (Indexed Literal Offset mode) | | | |
|------------------|--|------|------|------|
| Syntax: | SETF [k] | | | |
| Operands: | $0 \leq k \leq 95$ | | | |
| Operation: | $FFh \rightarrow ((FSR2) + k)$ | | | |
| Status Affected: | None | | | |
| Encoding: | 0110 | 1000 | kkkk | kkkk |

.....continued

| SETF | Set Indexed (Indexed Literal Offset mode) | | | |
|--------------|--|--|--|--|
| Description: | The contents of the register indicated by FSR2, offset by 'k', are set to FFh. | | | |
| Words: | 1 | | | |
| Cycles: | 1 | | | |

| Q Cycle Activity: | | | |
|-------------------|----------|--------------|----------------|
| Q1 | Q2 | Q3 | Q4 |
| Decode | Read 'k' | Process Data | Write register |

| | | |
|---|------|--------|
| Example: | SETF | [OFST] |
| Before Instruction OFST = 2Ch FSR2 = 0A00h Contents of 0A2Ch = 00h After Instruction Contents of 0A2Ch = FFh | | |

38.2.5 Special Considerations with Microchip MPLAB® IDE Tools

The latest versions of Microchip's software tools have been designed to fully support the extended instruction set of the PIC18F26/45/46Q10 family of devices. This includes the MPLAB C18 C compiler, MPASM assembly language and MPLAB Integrated Development Environment (IDE).

When selecting a target device for software development, MPLAB IDE will automatically set default Configuration bits for that device. The default setting for the XINST Configuration bit is '0', disabling the extended instruction set and Indexed Literal Offset Addressing mode. For proper execution of applications developed to take advantage of the extended instruction set, XINST must be set during programming.

To develop software for the extended instruction set, the user must enable support for the instructions and the Indexed Addressing mode in their language tool(s). Depending on the environment being used, this may be done in several ways:

- A menu option, or dialog box within the environment, that allows the user to configure the language tool and its settings for the project
- A command-line option
- A directive in the source code

These options vary between different compilers, assemblers and development environments. Users are encouraged to review the documentation accompanying their development systems for the appropriate information.

39. Electrical Specifications

39.1 Absolute Maximum Ratings^(†)

| Parameter | Rating |
|---|--|
| Ambient temperature under bias | -40°C to +125°C |
| Storage temperature | -65°C to +150°C |
| Voltage on pins with respect to V _{SS} | |
| • on V _{DD} pin: | -0.3V to +6.5V |
| • on MCLR pin: | -0.3V to +9.0V |
| • on all other pins: | -0.3V to (V _{DD} + 0.3V) |
| Maximum current ⁽¹⁾ | |
| • on V _{SS} pin | -40°C ≤ T _A ≤ +85°C 350 mA 85°C < T _A ≤ +125°C 120 mA |
| • on V _{DD} pin (28-pin devices) | -40°C ≤ T _A ≤ +85°C 250 mA 85°C < T _A ≤ +125°C 85 mA |
| • on V _{DD} pin (40-pin devices) | -40°C ≤ T _A ≤ +85°C 350 mA 85°C < T _A ≤ +125°C 120 mA |
| • on any standard I/O pin | ±50 mA |
| Clamp current, I _K (V _{PIN} < 0 or V _{PIN} > V _{DD}) | ±20 mA |
| Total power dissipation ⁽²⁾ | 800 mW |



Important:

- Maximum current rating requires even load distribution across I/O pins. Maximum current rating may be limited by the device package power dissipation characterizations, see the [Thermal Characteristics](#) table to calculate device specifications.
- Power dissipation is calculated as follows:

$$P_{DIS} = V_{DD} \times \{I_{DD} - \sum I_{OH}\} + \sum \{(V_{DD} - V_{OH}) \times I_{OH}\} + \sum (V_{OI} \times I_{OL})$$
- Internal Power Dissipation is calculated as follows: $P_{INTERNAL} = I_{DD} \times V_{DD}$, where I_{DD} is the current to run the chip alone without driving any load on the output pins.
- I/O Power Dissipation is calculated as follows: $P_{I/O} = \sum (I_{OL} \times V_{OL}) + \sum (I_{OH} \times (V_{DD} - V_{OH}))$
- Derated Power is calculated as follows: $P_{DER} = P_{D_{MAX}}(T_J - T_A)/\theta_{JA}$, where T_A = Ambient Temperature, T_J = Junction Temperature.

NOTICE: Stresses above those listed under “*Absolute Maximum Ratings*” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability.

39.2 Standard Operating Conditions

The standard operating conditions for any device are defined as:

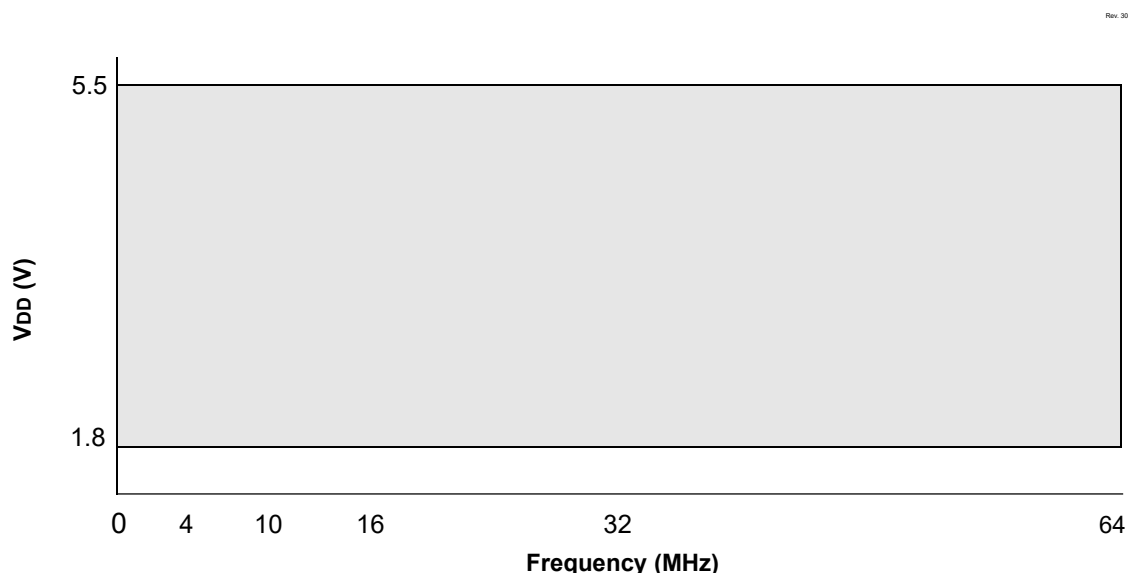
Operating Voltage: $V_{DDMIN} \leq V_{DD} \leq V_{DDMAX}$

$T_{A_MIN} \leq T_A \leq T_{A_MAX}$

Operating
Temperature:

| Parameter | Ratings | |
|--|--------------------|--------|
| V_{DD} — Operating Supply Voltage⁽¹⁾ | V _{DDMIN} | +1.8V |
| | V _{DDMAX} | +5.5V |
| T_A — Operating Ambient Temperature Range | | |
| Industrial Temperature | T _{A_MIN} | -40°C |
| | T _{A_MAX} | +85°C |
| Extended Temperature | T _{A_MIN} | -40°C |
| | T _{A_MAX} | +125°C |

Figure 39-1. Voltage Frequency Graph, -40°C ≤ T_A ≤ +125°C



Notes:

1. The shaded region indicates the permissible combinations of voltage and frequency.
2. Refer to [External Clock/Oscillator Timing Requirements](#) for each Oscillator mode's supported frequencies.

39.3 DC Characteristics

39.3.1 Supply Voltage

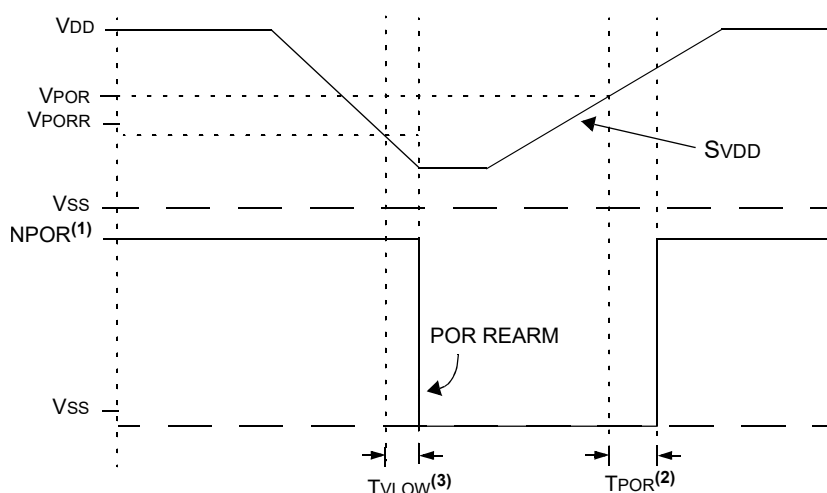
Table 39-1.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-------------------|----------------|------|-------------------|------|-------|---------------------------------------|
| Param. No. | Sym. | Characteristic | Min. | Typ. [†] | Max. | Units | Conditions |
| Supply Voltage | | | | | | | |
| D002 | V _{DD} | | 1.8 | — | 5.5 | V | |
| RAM Data Retention⁽¹⁾ | | | | | | | |
| D003 | V _{DR} | | 1.7 | — | — | V | Device in SLEEP mode |
| Power-on Reset Release Voltage⁽²⁾ | | | | | | | |
| D004 | V _{POR} | | — | 1.6 | — | V | BOR and LPBOR disabled ⁽³⁾ |
| Power-on Reset Rearm Voltage⁽²⁾ | | | | | | | |
| D005 | V _{PORR} | | — | 1 | — | V | BOR and LPBOR disabled ⁽³⁾ |

.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|--|------------------|----------------|------|-------|------|-------|---------------------------------------|
| Param. No. | Sym. | Characteristic | Min. | Typ.† | Max. | Units | Conditions |
| V_{DD} Rise Rate to ensure internal Power-on Reset signal⁽²⁾ | | | | | | | |
| D006 | S _{VDD} | | 0.05 | — | — | V/ms | BOR and LPBOR disabled ⁽³⁾ |
| † Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested. | | | | | | | |
| Notes: | | | | | | | |
| 1. This is the limit to which V _{DD} can be lowered in Sleep mode without losing RAM data. | | | | | | | |
| 2. See the following figure, POR and POR REARM with Slow Rising V _{DD} . | | | | | | | |
| 3. See Reset, WDT, Oscillator Start-up Timer, Power-up Timer, Brown-out Reset and Low-Power Brown-out Reset Specifications for BOR and LPBOR trip point information. | | | | | | | |

Figure 39-2. POR and POR Rearm with Slow Rising V_{DD}



Notes:

1. When NPOR is low, the device is held in Reset.
2. T_{POR} 1 μs typical.
3. T_{VLOW} 2.7 μs typical.

39.3.2 Supply Current (I_{DD})^(1,2,4)

Table 39-2.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | |
|---|-----------------------|------------------------|------|-------|------|-------|-----------------|----------------------|
| Param. No. | Sym. | Device Characteristics | Min. | Typ.† | Max. | Units | Conditions | |
| | | | | | | | V _{DD} | Note |
| D100 | I _{DDXT4} | XT = 4 MHz | — | 490 | 770 | μA | 3.0V | |
| D100A | I _{DDXT4} | XT = 4 MHz | — | 410 | — | μA | 3.0V | All PMD bits are '1' |
| D101 | I _{DDHFO16} | HFINTOSC = 16 MHz | — | 1.3 | 1.7 | mA | 3.0V | |
| D101A | I _{DDHFO16} | HFINTOSC = 16 MHz | — | 1.1 | — | mA | 3.0V | All PMD bits are '1' |
| D102 | I _{DDHFOPLL} | HFINTOSC = 64 MHz | — | 4.4 | 5.8 | mA | 3.0V | |

.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | |
|---|-------------------------------------|---|------|-------------------|------|-------|-----------------|----------------------|
| Param. No. | Sym. | Device Characteristics | Min. | Typ. [†] | Max. | Units | Conditions | |
| | | | | | | | V _{DD} | Note |
| D102A | I _{DD_HFOPLL} | HFINTOSC = 64 MHz | — | 3.4 | — | mA | 3.0V | All PMD bits are '1' |
| D103 | I _{DD_HSPLL64} | HS+PLL = 64 MHz | — | 4.3 | 5.7 | mA | 3.0V | |
| D103A | I _{DD_HSPLL64} | HS + PLL = 64 MHz | — | 3.3 | — | mA | 3.0V | All PMD bits are '1' |
| D104 | I _{DD_IDLE} | IDLE mode, HFINTOSC = 16 MHz | — | 0.6 | — | mA | 3.0V | |
| D105 | I _{DD_DOZE} ⁽³⁾ | DOZE mode, HFINTOSC = 16 MHz, Doze Ratio = 16 | — | 0.7 | — | mA | 3.0V | |

[†] Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Notes:

1. The test conditions for all I_{DD} measurements in active operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins are outputs driven low; MCLR = V_{DD}; WDT disabled.
2. The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.
3. I_{DD_DOZE} = [I_{DD_IDLE} * (N-1)/N] + I_{DD_HFO} 16/N where N = DOZE Ratio (see *CPUDOZE* register).
4. PMD bits are all in the default state, no modules are disabled.

Related Links

[CPUDOZE](#)

CPUDOZE

39.3.3 Power-Down Current (I_{PD})^(1,2)

Table 39-3.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | | | |
|---|-----------------------|--|------|-------------------|------------|-------------|-------|-----------------|----------------|-----------------------|
| Param. No. | Sym. | Device Characteristics | Min. | Typ. [†] | Max. +85°C | Max. +125°C | Units | Conditions | | |
| | | | | | | | | V _{DD} | VREGPM | Note |
| D200 | I _{PD} | I _{PD} Base | — | — | — | — | — | — | b'11' | Reserved |
| D200A | I _{PD} | I _{PD} Base | — | 0.6 | 4.0 | 12 | μA | 3.0V | b'10' | |
| D200B | | | — | 50 | — | 90 | μA | 3.0V | b'01' | |
| D200C | | | — | 170 | — | 280 | μA | 3.0V | b'00' | |
| D201 | I _{PD_WDT} | Low-Frequency Internal Oscillator/WDT | — | 0.9 | 5.0 | 13 | μA | 3.0V | b'10' | |
| D202* | I _{PD_SOSC} | Secondary Oscillator (S _{Osc}) | — | 1.6 | 4.3 | 10 | μA | 3.0V | b'10' | SOSCPWR = 0 |
| D203 | I _{PD_LPBOR} | Low-Power Brown-out Reset (LPBOR) | — | 0.9 | 5.0 | 13 | μA | 3.0V | b'10' | |
| D204 | I _{PD_FVR} | FVR | — | 70 | 105 | 110 | μA | 3.0V | b'10' or b'01' | FVRCON = 0x81 or 0x84 |
| D205 | I _{PD_BOR} | Brown-out Reset (BOR) | — | 30 | 60 | 63 | μA | 3.0V | b'10' | |

.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | | |
|---|----------------------|--------------------------------|------|-------|------------|-------------|-------|-----------------|---|
| Param. No. | Sym. | Device Characteristics | Min. | Typ.† | Max. +85°C | Max. +125°C | Units | Conditions | |
| | | | | | | | | V _{DD} | Note |
| D206 | I _{PD_HLVD} | High/Low Voltage Detect (HLVD) | — | 22 | — | — | μA | 3.0V | b'10' |
| D207 | I _{PD_ADCA} | ADC - Active | — | 330 | — | — | μA | 3.0V | b'10' or b'01' ADC is converting ⁽⁴⁾ |
| D208 | I _{PD_CMP} | Comparator | — | 60 | 85 | 90 | μA | 3.0V | b'10' |

* These parameters are characterized but not tested.

† Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Notes:

- The peripheral current is the sum of the base I_{DD} and the additional current consumed when this peripheral is enabled. The peripheral Δ current can be determined by subtracting the base I_{DD} or I_{DD} current from this limit. Max. values should be used when calculating total current consumption.
- The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode with all I/O pins in high-impedance state and tied to V_{SS}.
- All peripheral currents listed are on a per-peripheral basis if more than one instance of a peripheral is available.
- ADC clock source is FRC.

39.3.4 I/O Ports

Table 39-4.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-----------------|--------------------------------|---------------------------|-------|----------------------|-------|-------------------------------|
| Param. No. | Sym. | Device Characteristics | Min. | Typ.† | Max. | Units | Conditions |
| Input Low Voltage | | | | | | | |
| | V _{IL} | I/O PORT: | | | | | |
| D300 | | • with TTL buffer | — | — | 0.8 | V | 4.5V ≤ V _{DD} ≤ 5.5V |
| D301 | | | — | — | 0.15 V _{DD} | V | 1.8V ≤ V _{DD} < 4.5V |
| D302 | | • with Schmitt Trigger buffer | — | — | 0.2 V _{DD} | V | 2.0V ≤ V _{DD} ≤ 5.5V |
| D303 | | • with I ² C levels | — | — | 0.3 V _{DD} | V | |
| D304 | | • with SMBus levels | — | — | 0.8 | V | 2.7V ≤ V _{DD} ≤ 5.5V |
| D305 | | MCLR | — | — | 0.2 V _{DD} | V | |
| High/Low Voltage | | | | | | | |
| | V _{IH} | I/O PORT: | | | | | |
| D320 | | • with TTL buffer | 2.0 | — | — | V | 4.5V ≤ V _{DD} ≤ 5.5V |
| D321 | | | 0.25 V _{DD} +0.8 | — | — | V | 1.8V ≤ V _{DD} < 4.5V |
| D322 | | • with Schmitt Trigger buffer | 0.8V _{DD} | — | — | V | 2.0V ≤ V _{DD} ≤ 5.5V |
| D323 | | • with I ² C levels | 0.7 V _{DD} | — | — | V | |
| D324 | | • with SMBus levels | 2.1 | — | — | V | 2.7V ≤ V _{DD} ≤ 5.5V |
| D325 | | MCLR | 0.7 V _{DD} | — | — | V | |
| Input Leakage Current ⁽¹⁾ | | | | | | | |

.....continued

Standard Operating Conditions (unless otherwise stated)

| Param. No. | Sym. | Device Characteristics | Min. | Typ.† | Max. | Units | Conditions |
|------------|-----------------|------------------------|------|-------|-------|-------|---|
| D340 | I _{IL} | I/O PORTS | — | ±5 | ±125 | nA | V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 85°C |
| D341 | | | — | ±5 | ±1000 | nA | V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 125°C |
| D342 | | MCLR ⁽²⁾ | — | ±50 | ±200 | nA | V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 85°C |

Weak Pull-up Current

| | | | | | | | |
|------|------------------|--|----|-----|-----|----|--|
| D350 | I _{PUR} | | 80 | 140 | 200 | μA | V _{DD} = 3.0V, V _{PIN} = V _{SS} |
|------|------------------|--|----|-----|-----|----|--|

Output Low Voltage

| | | | | | | | |
|------|-----------------|-----------|---|---|-----|---|---|
| D360 | V _{OL} | I/O PORTS | — | — | 0.6 | V | I _{OL} = 10.0 mA, V _{DD} = 3.0V |
|------|-----------------|-----------|---|---|-----|---|---|

Output High Voltage

| | | | | | | | |
|------|-----------------|-----------|----------------------|---|---|---|--|
| D370 | V _{OH} | I/O PORTS | V _{DD} -0.7 | — | — | V | I _{OH} = 6.0 mA, V _{DD} = 3.0V |
|------|-----------------|-----------|----------------------|---|---|---|--|

All I/O Pins

| | | | | | | | |
|------|-----------------|--|---|---|----|----|--|
| D380 | C _{IO} | | — | 5 | 50 | pF | |
|------|-----------------|--|---|---|----|----|--|

† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Notes:

- Negative current is defined as current sourced by the pin.
- The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

39.3.5 Memory Programming Specifications

Table 39-5.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|--|--------------------|---|--------------------|------|--------------------|-------|---|
| Param No. | Sym. | Device Characteristics | Min. | Typ† | Max. | Units | Conditions |
| Data EEPROM Memory Specifications | | | | | | | |
| MEM20 | E _D | DataEE Byte Endurance | 100k | — | — | E/W | -40°C ≤ T _A ≤ +85°C |
| MEM21 | T _{D_RET} | Characteristic Retention | — | 40 | — | Year | Provided no other specifications are violated |
| MEM22 | N _{D_REF} | Total Erase/Write Cycles before Refresh | 1M | 10M | — | E/W | -40°C ≤ T _A ≤ +85°C |
| MEM23 | V _{D_RW} | V _{DD} for Read or Erase/Write operation | V _{DDMIN} | — | V _{DDMAX} | V | |
| MEM24 | T _{D_BEW} | Byte Erase and Write Cycle Time | — | 10 | 11 | ms | |
| Program Flash Memory Specifications | | | | | | | |
| MEM30 | E _p | Flash Memory Cell Endurance | 10k | — | — | E/W | -40°C ≤ T _a ≤ +85°C (Note 1) |
| MEM32 | T _{P_RET} | Characteristic Retention | — | 40 | — | Year | Provided no other specifications are violated |
| MEM33 | V _{P_RD} | V _{DD} for Read operation | V _{DDMIN} | — | V _{DDMAX} | V | |
| MEM34 | V _{P_REW} | V _{DD} for Row Erase or Write operation | V _{DDMIN} | — | V _{DDMAX} | V | |
| MEM35 | T _{P_REW} | Self-Timed Sector Write | — | 6 | 10 | ms | |
| MEM36 | T _{SE} | Self-Timed Sector Erase | — | 10 | 14 | ms | |
| MEM37 | T _{P_WRD} | Self-Timed Word Write | — | 55 | 80 | μs | |
| † Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested. | | | | | | | |
| Note: | | | | | | | |
| 1. Flash Memory Cell Endurance for the Flash memory is defined as: One Row Erase operation and one Self-Timed Write. | | | | | | | |

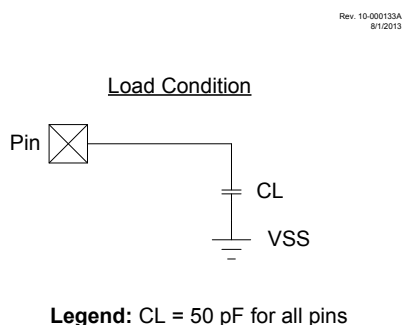
39.3.6 Thermal Characteristics

Table 39-6.

| Standard Operating Conditions (unless otherwise stated) | | | | | |
|--|---------------|--|------|-------|----------------------------|
| Param No. | Sym. | Characteristic | Typ. | Units | Conditions |
| TH01 | θ_{JA} | Thermal Resistance Junction to Ambient | 60 | °C/W | 28-pin SPDIP package |
| | | | 80 | °C/W | 28-pin SOIC package |
| | | | 90 | °C/W | 28-pin SSOP package |
| | | | 27.5 | °C/W | 28-pin VQFN 4x4 mm package |
| | | | 27.5 | °C/W | 28-pin QFN 6x6 mm package |
| | | | 47.2 | °C/W | 40-pin PDIP package |
| | | | 28.9 | °C/W | 40-pin QFN package |
| | | | 46 | °C/W | 44-pin TQFP package |
| TH03 | T_{JMAX} | Maximum Junction Temperature | 150 | °C | |
| Note: 1. See “Absolute Maximum Ratings” for total power dissipation. | | | | | |

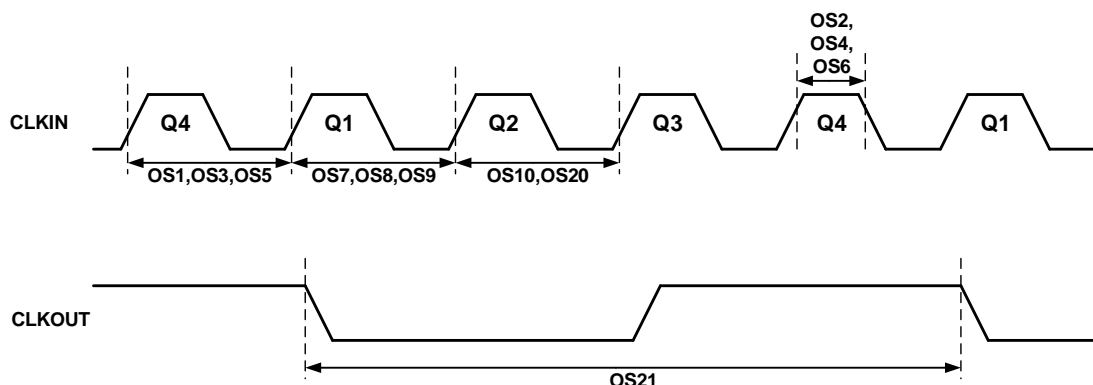
39.4 AC Characteristics

Figure 39-3. Load Conditions



39.4.1 External Clock/Oscillator Timing Requirements

Figure 39-4. Clock Timing



Note: See the table below.

Table 39-7.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|---------------|------------------------|------|-------------|------|-------|------------------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| ECL Oscillator | | | | | | | |
| OS1 | F_{ECL} | Clock Frequency | — | — | 1 | MHz | |
| OS2 | T_{ECL_DC} | Clock Duty Cycle | 40 | — | 60 | % | |
| ECM Oscillator | | | | | | | |
| OS3 | F_{ECM} | Clock Frequency | — | — | 16 | MHz | |
| OS4 | T_{ECM_DC} | Clock Duty Cycle | 40 | — | 60 | % | |
| ECH Oscillator | | | | | | | |
| OS5 | F_{ECH} | Clock Frequency | — | — | 64 | MHz | |
| OS6 | T_{ECH_DC} | Clock Duty Cycle | 40 | — | 60 | % | |
| LP Oscillator | | | | | | | |
| OS7 | F_{LP} | Clock Frequency | — | — | 100 | kHz | Note 4 |
| XT Oscillator | | | | | | | |
| OS8 | F_{XT} | Clock Frequency | — | — | 4 | MHz | Note 4 |
| HS Oscillator | | | | | | | |
| OS9 | F_{HS} | Clock Frequency | — | — | 20 | MHz | $V_{DD} > 2.5V$ Note 4 |
| Secondary Oscillator | | | | | | | |
| OS10 | F_{SEC} | Clock Frequency | 32.4 | 32.768 | 33.1 | kHz | Note 4 |
| System Oscillator | | | | | | | |
| OS20 | F_{OSC} | System Clock Frequency | — | — | 64 | MHz | (Note 2, Note 3) |
| OS21 | F_{CY} | Instruction Frequency | — | $F_{OSC}/4$ | — | MHz | |
| OS22 | T_{CY} | Instruction Period | 62.5 | $1/F_{CY}$ | — | ns | |

.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|--|------|----------------|------|--------|------|-------|------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| Notes: | | | | | | | |
| 1. Instruction cycle period (TCY) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at “min” values with an external clock applied to OSC1 pin. When an external clock input is used, the “max” cycle time limit is “DC” (no clock) for all devices. | | | | | | | |
| 2. The system clock frequency (FOSC) is selected by the “main clock switch controls” as described in the “ Power Saving Operation Modes ” section. | | | | | | | |
| 3. The system clock frequency (FOSC) must meet the voltage requirements defined in the “ Standard Operating Conditions ” section. | | | | | | | |
| 4. LP, XT and HS oscillator modes require an appropriate crystal or resonator to be connected to the device. For clocking the device with the external square wave, one of the EC mode selections must be used. | | | | | | | |

Related Links

[Standard Operating Conditions](#)

[Power-Saving Operation Modes](#)

39.4.2 Internal Oscillator Parameters⁽¹⁾

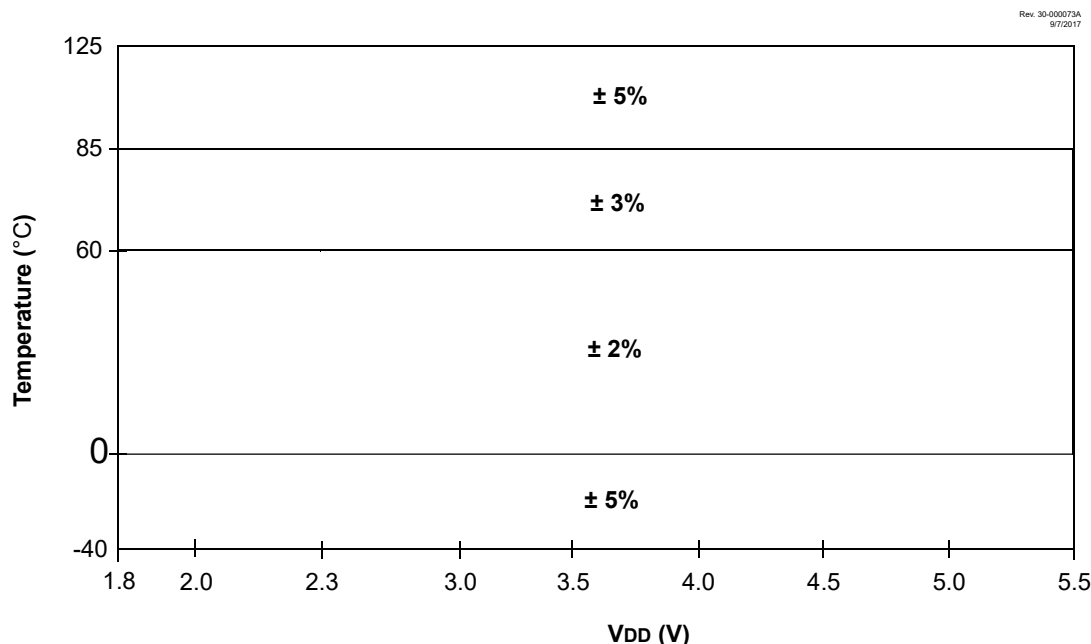
Table 39-8.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|----------------------|---|--------|--------------------------------------|---------|------------|---|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| OS50 | F _{HFOSC} | Precision Calibrated HFINTOSC Frequency | — | 4 8 12 16 32 48 64 | — | MHz | (Note 2) |
| OS51 | F _{HFOSCLP} | Low-Power Optimized HFINTOSC Frequency | — — | 1 2 | — — | MHz MHz | Fundamental Freq. 1 MHz Fundamental Freq. 2 MHz |
| OS52 | F _{MFOSC} | Internal Calibrated MFINTOSC Frequency | — | 500 | — | kHz | |
| OS53* | F _{LFOSC} | Internal LFINTOSC Frequency | — | 31 | — | kHz | |
| OS54* | T _{HFOSCST} | HFINTOSC Wake-up from Sleep Start-up Time | — — | 14 100 | 20 — | μs μs | VREGPM = 0x VREGPM = 1x System Clock at 4 MHz |
| OS56 | T _{LFOSCST} | LFINTOSC Wake-up from Sleep Start-up Time | — | 0.3 | — | ms | |

.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|------|----------------|------|--------|------|-------|------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| * These parameters are characterized but not tested. | | | | | | | |
| † Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested. | | | | | | | |
| Notes: | | | | | | | |
| 1. To ensure these oscillator frequency tolerances, V_{DD} and V_{SS} must be capacitively decoupled as close to the device as possible. 0.1 μ F and 0.01 μ F values in parallel are recommended. | | | | | | | |
| 2. See the figure below. | | | | | | | |

Figure 39-5. Precision Calibrated HFINTOSC Frequency Accuracy Over Device V_{DD} and Temperature



39.4.3 PLL Specifications

Table 39-9.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|--|---------------------|--------------------------------|-------|--------|------|---------|------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| PLL01 | F _{PLLIN} | PLL Input Frequency Range | 4 | — | 16 | MHz | |
| PLL02 | F _{PLLOUT} | PLL Output Frequency Range | 16 | — | 64 | MHz | (Note 1) |
| PLL03* | F _{PLLST} | PLL Lock Time | — | 10 | — | μ s | |
| PLL04* | F _{PLLJIT} | PLL Output Frequency Stability | -0.25 | — | 0.25 | % | |
| * These parameters are characterized but not tested. | | | | | | | |
| † Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested. | | | | | | | |
| Note: | | | | | | | |
| 1. The output frequency of the PLL must meet the F _{OSC} requirements listed in Parameter D002 . | | | | | | | |

39.4.4 I/O and CLKOUT Timing Specifications

Figure 39-6. CLKOUT and I/O Timing

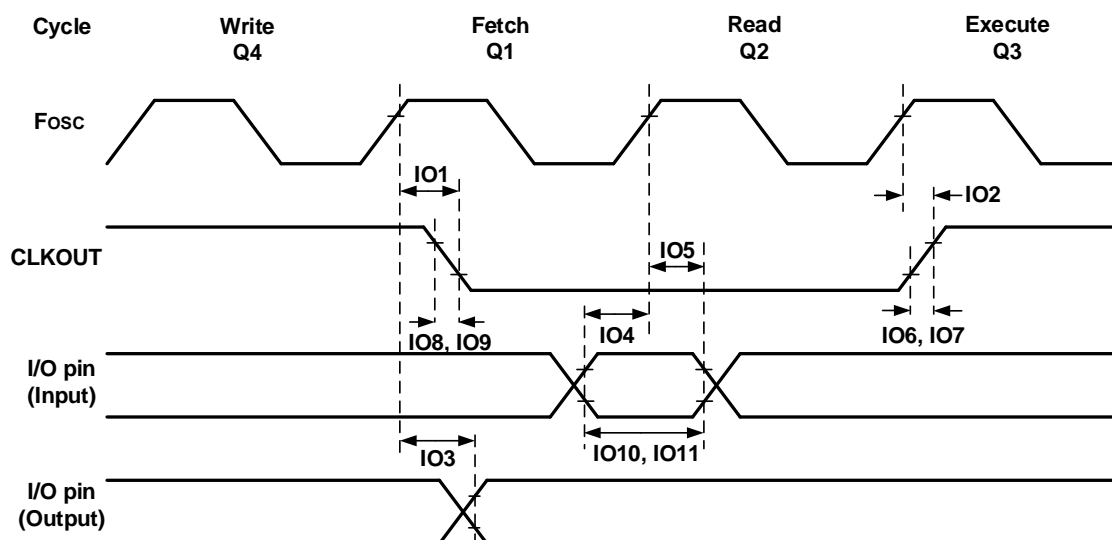


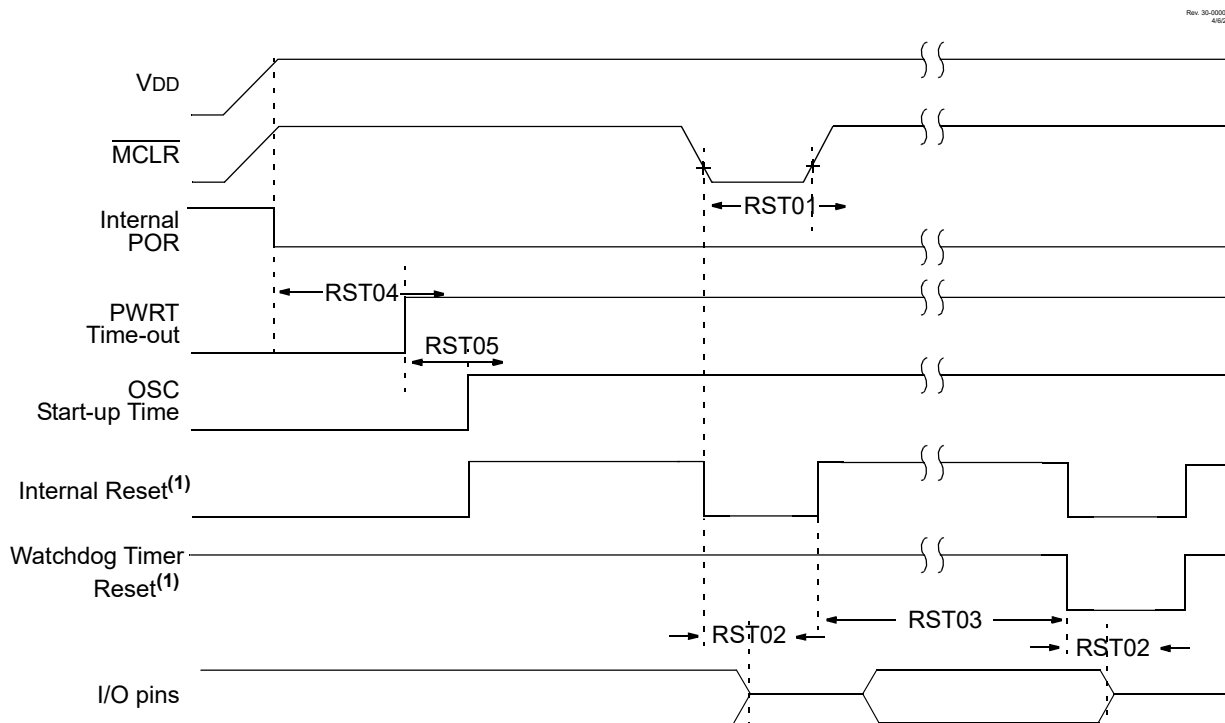
Table 39-10. I/O and CLKOUT Timing Specifications

| Standard Operating Conditions (unless otherwise stated) | | | | | | |
|---|-------------------------|---|------|--------|------|-------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units |
| IO1* | T _{CLKOUTH} | CLKOUT rising edge delay (rising edge F _{OSC} (Q1 cycle) to falling edge CLKOUT) | — | — | 70 | ns |
| IO2* | T _{CLKOUTL} | CLKOUT falling edge delay (rising edge F _{OSC} (Q3 cycle) to rising edge CLKOUT) | — | — | 72 | ns |
| IO3* | T _{IO_VALID} | Port output valid time (rising edge F _{OSC} (Q1 cycle) to port valid) | — | 50 | 70 | ns |
| IO4* | T _{IO_SETUP} | Port input setup time (Setup time before rising edge F _{OSC} – Q2 cycle) | 20 | — | — | ns |
| IO5* | T _{IO_HOLD} | Port input hold time (Hold time after rising edge F _{OSC} – Q2 cycle) | 50 | — | — | ns |
| IO6* | T _{IOR_SLREN} | Port I/O rise time, slew rate enabled | — | 25 | — | ns |
| IO7* | T _{IOR_SLRDIS} | Port I/O rise time, slew rate disabled | — | 5 | — | ns |
| IO8* | T _{IOF_SLREN} | Port I/O fall time, slew rate enabled | — | 25 | — | ns |
| IO9* | T _{IOF_SLRDIS} | Port I/O fall time, slew rate disabled | — | 5 | — | ns |
| IO10* | T _{INT} | INT pin high or low time to trigger an interrupt | 25 | — | — | ns |
| IO11* | T _{IOC} | Interrupt-on-Change minimum high or low time to trigger interrupt | 25 | — | — | ns |

* These parameters are characterized but not tested.

39.4.5 Reset, WDT, Oscillator Start-up Time, Power-up Timer, Brown-out Reset and Low-Power Brown-out Reset Specifications

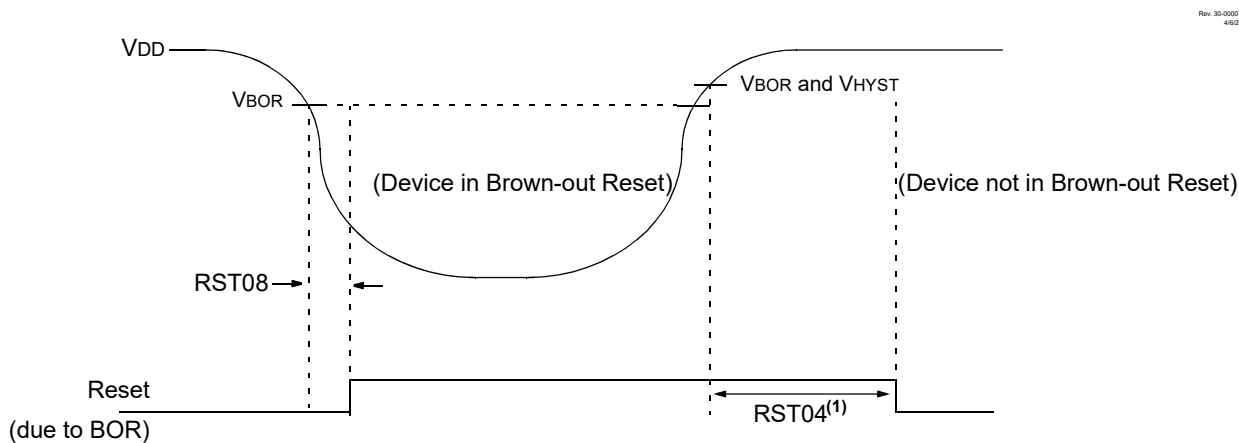
Figure 39-7. Reset, Watchdog Timer, Oscillator Start-up Time and Power-up Timer Timing



Note:

1. Asserted low.

Figure 39-8. Brown-out Reset Timing and Characteristics



Note:

1. Only if the $\overline{\text{PWRTE}}$ bit in the Configuration Word register is programmed to '1'; 2 ms delay if $\overline{\text{PWRTE}} = 0$.

Table 39-11.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-------------------|--------------------------------------|------|--------|------|---------------|------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| RST01* | T_{MCLR} | MCLR Pulse Width Low to ensure Reset | 2 | — | — | μs | |

.....continued

Standard Operating Conditions (unless otherwise stated)

| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
|-----------|---------------------|---|------|--------|------|------------------|-----------------|
| RST02* | T _{IOZ} | I/O high-impedance from Reset detection | — | — | 2 | μs | |
| RST03 | T _{WDT} | Watchdog Timer Time-out Period | — | 16 | — | ms | WDTCPSS = 00100 |
| RST04* | T _{PWRT} | Power-up Timer Period | — | 65 | — | ms | |
| RST05 | T _{OST} | Oscillator Start-up Timer Period ^(1,2) | — | 1024 | — | T _{Osc} | |
| RST06 | V _{BOR} | Brown-out Reset Voltage | 2.7 | 2.85 | 3.0 | V | BORV = 00 |
| | | | 2.55 | 2.7 | 2.85 | V | BORV = 01 |
| | | | 2.3 | 2.45 | 2.6 | V | BORV = 10 |
| | | | 1.8 | 1.9 | 2.1 | V | BORV = 11 |
| RST07 | V _{BORHYS} | Brown-out Reset Hysteresis | — | 60 | — | mV | BORV = 00 |
| RST08 | T _{BORDC} | Brown-out Reset Response Time | — | 3 | — | μs | |
| RST09 | V _{LPBOR} | Low-Power Brown-out Reset Voltage | 1.8 | 1.9 | 2.2 | V | |

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Notes:

- By design, the Oscillator Start-up Timer (OST) counts the first 1024 cycles, independent of frequency.
- To ensure these voltage tolerances, V_{DD} and V_{SS} must be capacitively decoupled as close to the device as possible. 0.1 μF and 0.01 μF values in parallel are recommended.

39.4.6 High/Low-Voltage Detect Characteristics

Table 39-12.

Standard Operating Conditions (unless otherwise stated)

| Param No. | Sym. | Characteristic | Min. | Typ. | Max. | Units | Conditions |
|-----------|------------------|----------------|------|------|------|-------|-------------------|
| HLVD01 | V _{DET} | Voltage Detect | — | 1.90 | — | V | HLVDSEL = b'0000' |
| | | | — | 2.10 | — | V | HLVDSEL = b'0001' |
| | | | — | 2.25 | — | V | HLVDSEL = b'0010' |
| | | | — | 2.50 | — | V | HLVDSEL = b'0011' |
| | | | — | 2.60 | — | V | HLVDSEL = b'0100' |
| | | | — | 2.75 | — | V | HLVDSEL = b'0101' |
| | | | — | 2.90 | — | V | HLVDSEL = b'0110' |
| | | | — | 3.15 | — | V | HLVDSEL = b'0111' |
| | | | — | 3.35 | — | V | HLVDSEL = b'1000' |
| | | | — | 3.60 | — | V | HLVDSEL = b'1001' |
| | | | — | 3.75 | — | V | HLVDSEL = b'1010' |
| | | | — | 4.00 | — | V | HLVDSEL = b'1011' |
| | | | — | 4.20 | — | V | HLVDSEL = b'1100' |
| | | | — | 4.35 | — | V | HLVDSEL = b'1101' |
| | | | — | 4.65 | — | V | HLVDSEL = b'1110' |

39.4.7 Analog-to-Digital Converter (ADC) Accuracy Specifications^(1,2)

Table 39-13.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|--|-------------|---|-------------|-----------|-------------|------------|---|
| $V_{DD} = 3.0V$, $T_A = 25^\circ C$, $T_{AD} = 1\mu s$ | | | | | | | |
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| AD01 | N_R | Resolution | — | — | 10 | bit | |
| AD02 | E_{IL} | Integral Non-Linearity Error | — | ± 0.1 | ± 1.0 | LSb | $ADC_{REF+} = 3.0V$, $ADC_{REF-} = 0V$ |
| AD03 | E_{DL} | Differential Non-Linearity Error | — | ± 0.1 | ± 1.0 | LSb | $ADC_{REF+} = 3.0V$, $ADC_{REF-} = 0V$ |
| AD04 | E_{OFF} | Offset Error | — | 0.5 | ± 2.0 | LSb | $ADC_{REF+} = 3.0V$, $ADC_{REF-} = 0V$ |
| AD05 | E_{GN} | Gain Error | — | ± 0.2 | ± 2.0 | LSb | $ADC_{REF+} = 3.0V$, $ADC_{REF-} = 0V$ |
| AD06 | V_{ADREF} | ADC Reference Voltage ($AD_{REF+} - AD_{REF-}$) | 1.8 | — | V_{DD} | V | |
| AD07 | V_{AIN} | Full-Scale Range | AD_{REF-} | — | AD_{REF+} | V | |
| AD08 | Z_{AIN} | Recommended Impedance of Analog Voltage Source | — | 10 | — | k Ω | |
| AD09 | R_{VREF} | ADC Voltage Reference Ladder Impedance | — | 50 | — | k Ω | (Note 3) |

* These parameters are characterized but not tested.
† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Notes:

1. Total Absolute Error is the sum of the offset, gain and integral non-linearity (INL) errors.
2. The ADC conversion result never decreases with an increase in the input and has no missing codes.
3. This is the impedance seen by the V_{REF} pads when the external reference pads are selected.

39.4.8 Analog-to-Digital Converter (ADC) Conversion Timing Specifications

Table 39-14.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-----------|--------------------------------|------|----------------|------|----------|---|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| AD20 | T_{AD} | ADC Clock Period | 1 | — | 9 | μs | Using F_{OSC} as the ADC clock source $ADOCS = 0$ |
| AD21 | | | 1 | 2 | 6 | μs | Using F_{RC} as the ADC clock source $ADOCS = 1$ |
| AD22 | T_{CNV} | Conversion Time ⁽¹⁾ | — | $11 + 3T_{CY}$ | — | T_{AD} | Set of GO/DONE bit to Clear of GO/DONE bit |
| AD23 | T_{ACQ} | Acquisition Time | — | 2 | — | μs | |

* These parameters are characterized but not tested.
† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note:

1. Does not apply for the ADCRC oscillator.

Figure 39-9. ADC Conversion Timing (ADC Clock F_{OSC} -Based)

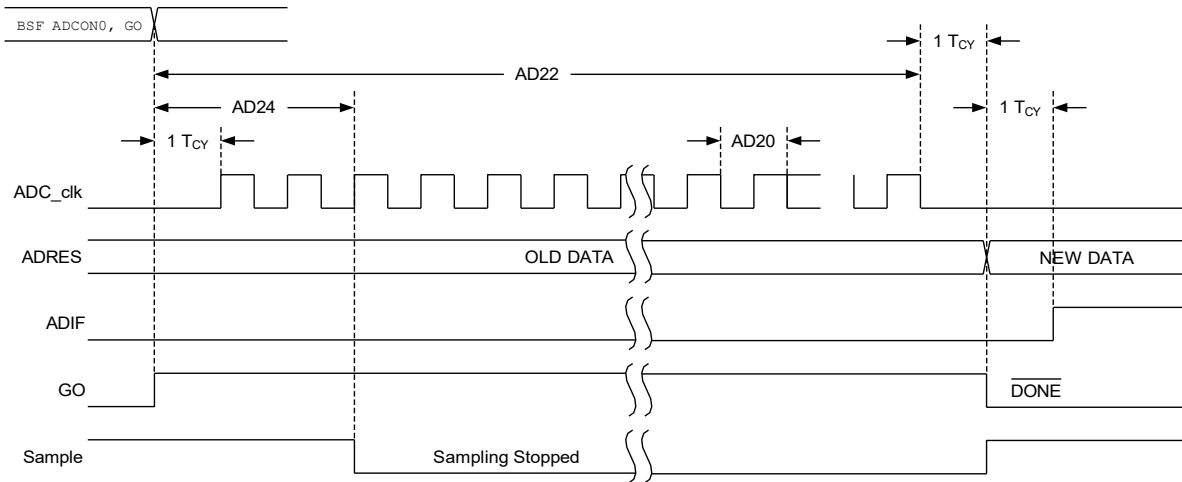
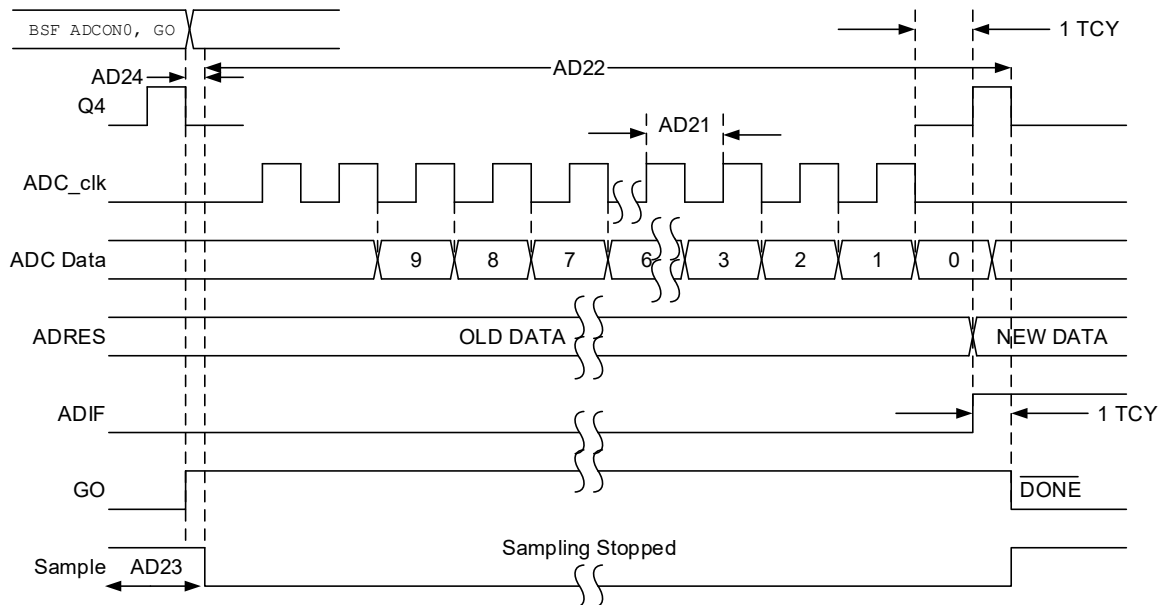


Figure 39-10. ADC Conversion Timing (ADC Clock from F_{RC})



Note:

1. If the ADC clock source is selected as F_{RC} , a time of T_{CY} is added before the ADC clock starts. This allows the `SLEEP` instruction to be executed.

39.4.9 Comparator Specifications

Table 39-15.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|------------|-----------------------------------|------|--------|----------|-------|----------------------|
| $V_{DD} = 3.0V$, $T_A = 25^\circ C$ | | | | | | | |
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| CM01 | V_{IOFF} | Input Offset Voltage | — | — | ± 30 | mV | $V_{ICM} = V_{DD}/2$ |
| CM02 | V_{ICM} | Input Common Mode Range | GND | — | V_{DD} | V | |
| CM03 | CMRR | Common Mode Input Rejection Ratio | — | 50 | — | dB | |

.....continued

Standard Operating Conditions (unless otherwise stated)

$V_{DD} = 3.0V, T_A = 25^{\circ}C$

| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
|-----------|------------------|-----------------------------|------|--------|------|-------|------------|
| CM04 | V_{HYST} | Comparator Hysteresis | 10 | 25 | 40 | mV | |
| CM05 | $T_{RESP}^{(1)}$ | Response Time, Rising Edge | — | 300 | 600 | ns | |
| | | Response Time, Falling Edge | — | 220 | 500 | ns | |

* These parameters are characterized but not tested.

† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note:

1. Response time measured with one comparator input at $V_{DD}/2$, while the other input transitions from V_{SS} to V_{DD} .

39.4.10 5-Bit DAC Specifications

Table 39-16.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|------------|------------------------------|------|----------------------------------|------|-------|------------|
| $V_{DD} = 3.0V, T_A = 25^{\circ}C$ | | | | | | | |
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| DSB01 | V_{LSB} | Step-Size | — | $(V_{DACREF+} - V_{DACREF-})/32$ | — | V | |
| DSB02 | V_{ACC} | Absolute Accuracy | — | — | ±0.5 | LSb | |
| DSB03* | R_{UNIT} | Unit Resistor Value | — | 5000 | — | Ω | |
| DSB04* | T_{ST} | Settling Time ⁽¹⁾ | — | — | 10 | μs | |
| <p>* These parameters are characterized but not tested.</p> <p>† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.</p> <p>Note:</p> <p>1. Settling time measured while DACR[4:0] transitions from ‘00000’ to ‘01111’.</p> | | | | | | | |

39.4.11 Fixed Voltage Reference (FVR) Specifications

Table 39-17.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-------------|-------------------|------|--------|------|-------|--|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| FVR01 | V_{FVR1} | 1x Gain (1.024V) | -4 | — | +4 | % | $V_{DD} \geq 2.5V, -40^{\circ}C$ to $85^{\circ}C$ |
| FVR02 | V_{FVR2} | 2x Gain (2.048V) | -4 | — | +4 | % | $V_{DD} \geq 2.5V, -40^{\circ}C$ to $85^{\circ}C$ |
| FVR03 | V_{FVR4} | 4x Gain (4.096V) | -4 | — | +4 | % | $V_{DD} \geq 4.75V, -40^{\circ}C$ to $85^{\circ}C$ |
| FVR04 | T_{FVRST} | FVR Start-up Time | — | 25 | — | μs | |

39.4.12 Zero-Cross Detect (ZCD) Specifications

Table 39-18.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|----------------|--------------------------------|------|--------|------|-------|------------|
| $V_{DD} = 3.0V, T_A = 25^{\circ}C$ | | | | | | | |
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| ZC01 | V_{PINZC} | Voltage on Zero Cross Pin | — | 0.9 | — | V | |
| ZC02 | I_{ZCD_MAX} | Maximum source or sink current | — | — | 600 | μA | |

.....continued

Standard Operating Conditions (unless otherwise stated)

$V_{DD} = 3.0V$, $T_A = 25^\circ C$

| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
|-----------|--------------------|-----------------------------|------|--------|------|-------|------------|
| ZC03 | T _{RESPH} | Response Time, Rising Edge | — | 1 | — | μs | |
| | T _{RESPL} | Response Time, Falling Edge | — | 1 | — | μs | |

† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

39.4.13 Timer0 and Timer1 External Clock Requirements

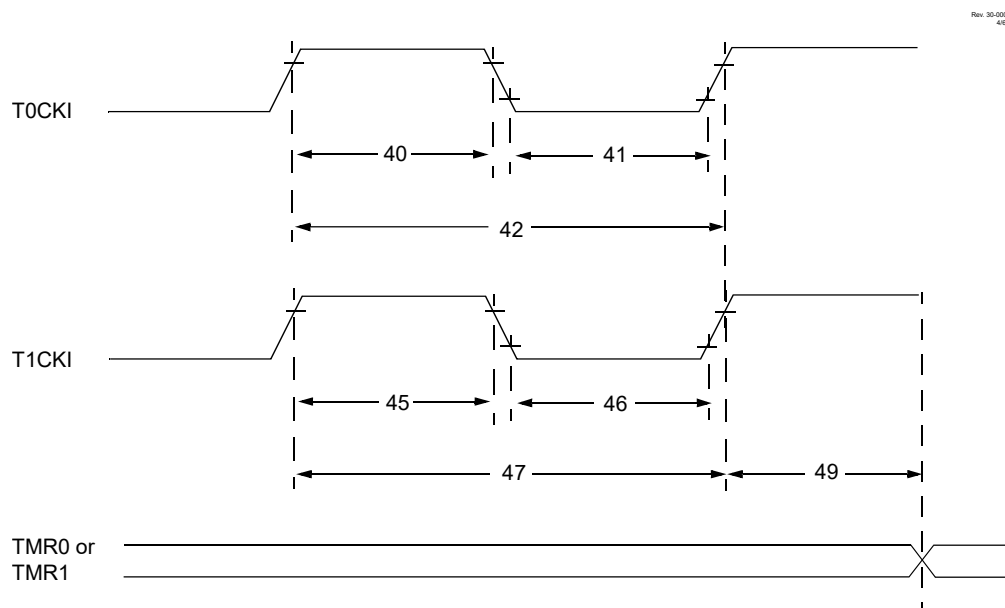
Table 39-19.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | |
|---|-----------------------|---|-----------------------------|-----------------------------------|--------|--------------------|-------|---------------------|
| Operating Temperature: $-40^\circ C \leq T_A \leq +125^\circ C$ | | | | | | | | |
| Param No. | Sym. | Characteristic | | Min. | Typ. † | Max. | Units | Conditions |
| 40* | T _{0H} | T0CKI High Pulse Width | No Prescaler | $0.5T_{CY}+20$ | — | — | ns | |
| | | | With Prescaler | 10 | — | — | ns | |
| 41* | T _{0L} | T0CKI Low Pulse Width | No Prescaler | $0.5T_{CY}+20$ | — | — | ns | |
| | | | With Prescaler | 10 | — | — | ns | |
| 42* | T _{0P} | T0CKI Period | | Greater of: 20 or $(T_{CY}+40)/N$ | — | — | ns | N = Prescale value |
| 45* | T _{1H} | T1CKI High Time | Synchronous, No Prescaler | $0.5T_{CY}+20$ | — | — | ns | |
| | | | Synchronous, with Prescaler | 15 | — | — | ns | |
| | | | Asynchronous | 30 | — | — | ns | |
| 46* | T _{1L} | T1CKI Low Time | Synchronous, No Prescaler | $0.5T_{CY}+20$ | — | — | ns | |
| | | | Synchronous, with Prescaler | 15 | — | — | ns | |
| | | | Asynchronous | 30 | — | — | ns | |
| 47* | T _{1P} | T1CKI Input Period | Synchronous | Greater of: 30 or $(T_{CY}+40)/N$ | — | — | ns | N = Prescale value |
| | | | Asynchronous | 60 | — | — | ns | |
| 49* | TCKEZ _{TMR1} | Delay from External Clock Edge to Timer Increment | | 2 T _{OSC} | — | 7 T _{OSC} | — | Timers in Sync mode |

* These parameters are characterized but not tested.

† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Figure 39-11. Timer0 and Timing1 External Clock Timings



39.4.14 Capture/Compare/PWM Requirements (CCP)

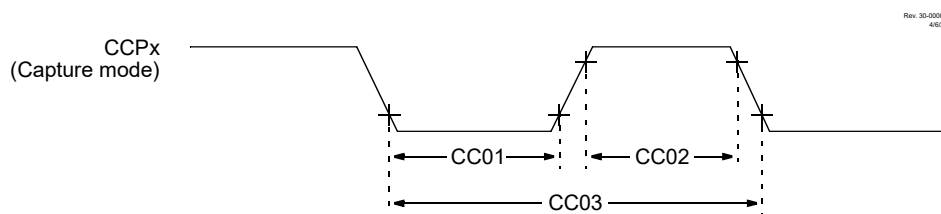
Table 39-20.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | |
|---|------------------|----------------------|----------------|--------------------|--------|------|-------|--------------------|
| Operating Temperature: $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ | | | | | | | | |
| Param No. | Sym. | Characteristic | | Min. | Typ. † | Max. | Units | Conditions |
| CC01* | T _{CCL} | CCPx Input Low Time | No Prescaler | $0.5T_{CY} + 20$ | — | — | ns | |
| | | | With Prescaler | 20 | — | — | ns | |
| CC02* | T _{CCH} | CCPx Input High Time | No Prescaler | $0.5T_{CY} + 20$ | — | — | ns | |
| | | | With Prescaler | 20 | — | — | ns | |
| CC03* | T _{CCP} | CCPx Input Period | | $(3T_{CY} + 40)/N$ | — | — | ns | N = Prescale value |

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Figure 39-12. Capture/Compare/PWM Timings (CCP)



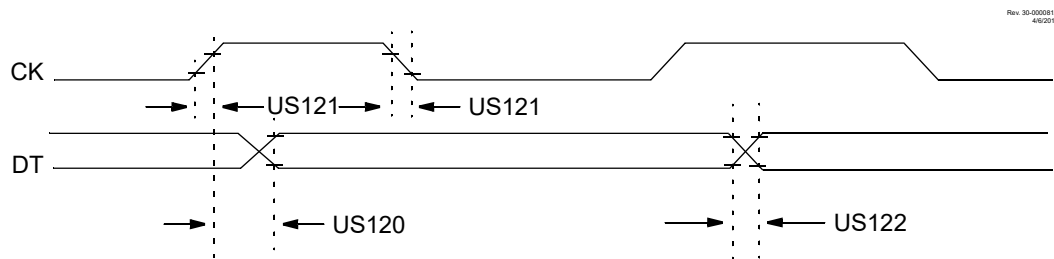
Note: Refer to [Figure 39-3](#) for load conditions.

39.4.15 EUSART Synchronous Transmission Requirements

Table 39-21.

| Standard Operating Conditions (unless otherwise stated) | | | | | | |
|---|---------------|---|------|------|-------|------------------------------|
| Param No. | Sym. | Characteristic | Min. | Max. | Units | Conditions |
| US120 | $T_{CKH2DTV}$ | SYNC XMIT (Host and Client) | — | 80 | ns | $3.0V \leq V_{DD} \leq 5.5V$ |
| | | Clock high to data-out valid | — | 100 | ns | $1.8V \leq V_{DD} \leq 5.5V$ |
| US121 | T_{CKRF} | Clock out rise time and fall time (Host mode) | — | 45 | ns | $3.0V \leq V_{DD} \leq 5.5V$ |
| | | | — | 50 | ns | $1.8V \leq V_{DD} \leq 5.5V$ |
| US122 | T_{DTRF} | Data-out rise time and fall time | — | 45 | ns | $3.0V \leq V_{DD} \leq 5.5V$ |
| | | | — | 50 | ns | $1.8V \leq V_{DD} \leq 5.5V$ |

Figure 39-13. EUSART Synchronous Transmission (Host/Client) Timing



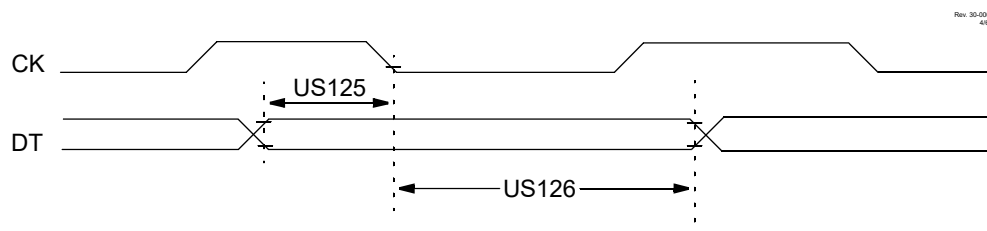
Note: Refer to Figure 39-3 for load conditions.

39.4.16 EUSART Synchronous Receive Requirements

Table 39-22.

| Standard Operating Conditions (unless otherwise stated) | | | | | | |
|---|---------------|---------------------------------------|------|------|-------|------------|
| Param No. | Sym. | Characteristic | Min. | Max. | Units | Conditions |
| US125 | $T_{DTV2CKL}$ | SYNC RCV (Host and Client) | 10 | — | ns | |
| | | Data-setup before CK ↓ (DT hold time) | | | | |
| US126 | $T_{CKL2DTL}$ | Data-hold after CK ↓ (DT hold time) | 15 | — | ns | |

Figure 39-14. EUSART Synchronous Receive (Host/Client) Timing



Note: Refer to Figure 39-3 for load conditions.

39.4.17 SPI Mode Requirements

Table 39-23.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|----------------------------------|--|---------------------|--------|------|-------|------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| SP70* | $T_{SSL2SCH}$, $T_{SSL2SCL}$ | $\overline{SS} \downarrow$ to SCK \downarrow or SCK \uparrow input | $2.25 \cdot T_{CY}$ | — | — | ns | |
| SP71* | T_{SCH} | SCK input high time | $T_{CY} + 20$ | — | — | ns | |

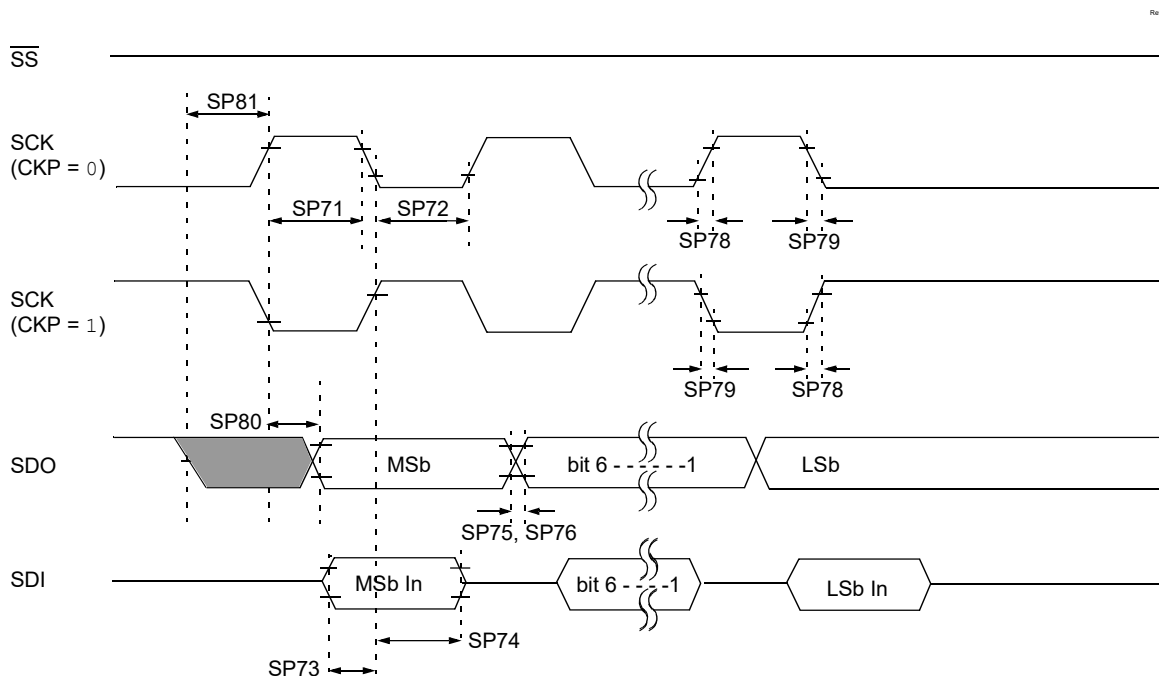
.....continued

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|---|--|--------------------------|--------|------|-------|-------------------------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| SP72* | T _{ScL} | SCK input low time | T _{CY} + 20 | — | — | ns | |
| SP73* | T _{DI} V2 _{ScH} , T _{DI} V2 _{ScL} | Setup time of SDI data input to SCK edge | 100 | — | — | ns | |
| SP74* | T _{ScH} 2 _{DI} L, T _{ScL} 2 _{DI} L | Hold time of SDI data input to SCK edge | 100 | — | — | ns | |
| SP75* | T _{DO} R | SDO data output rise time | — | 10 | 25 | ns | 3.0V ≤ V _{DD} ≤ 5.5V |
| | | | — | 25 | 50 | ns | 1.8V ≤ V _{DD} ≤ 5.5V |
| SP76* | T _{DO} F | SDO data output fall time | — | 10 | 25 | ns | |
| SP77* | T _{SS} H2 _{DO} Z | \overline{SS} ↑ to SDO output high-impedance | 10 | — | 50 | ns | |
| SP78* | T _{Sc} R | SCK output rise time | — | 10 | 25 | ns | 3.0V ≤ V _{DD} ≤ 5.5V |
| | | | — | 25 | 50 | ns | 1.8V ≤ V _{DD} ≤ 5.5V |
| SP79* | T _{Sc} F | SCK output fall time | — | 10 | 25 | ns | |
| SP80* | T _{ScH} 2 _{DO} V, T _{ScL} 2 _{DO} V | SDO data output valid after SCK edge | — | — | 50 | ns | 3.0V ≤ V _{DD} ≤ 5.5V |
| | | | — | — | 145 | ns | 1.8V ≤ V _{DD} ≤ 5.5V |
| SP81* | T _{DO} V2 _{ScH} , T _{DO} V2 _{ScL} | SDO data output setup to SCK edge | 1 T _{CY} | — | — | ns | |
| SP82* | T _{SS} L2 _{DO} V | SDO data output valid after \overline{SS} ↓ edge | — | — | 50 | ns | |
| SP83* | T _{ScH} 2 _{SS} H, T _{ScL} 2 _{SS} H | \overline{SS} ↑ after SCK edge | 1.5 T _{CY} + 40 | — | — | ns | |

* These parameters are characterized but not tested.

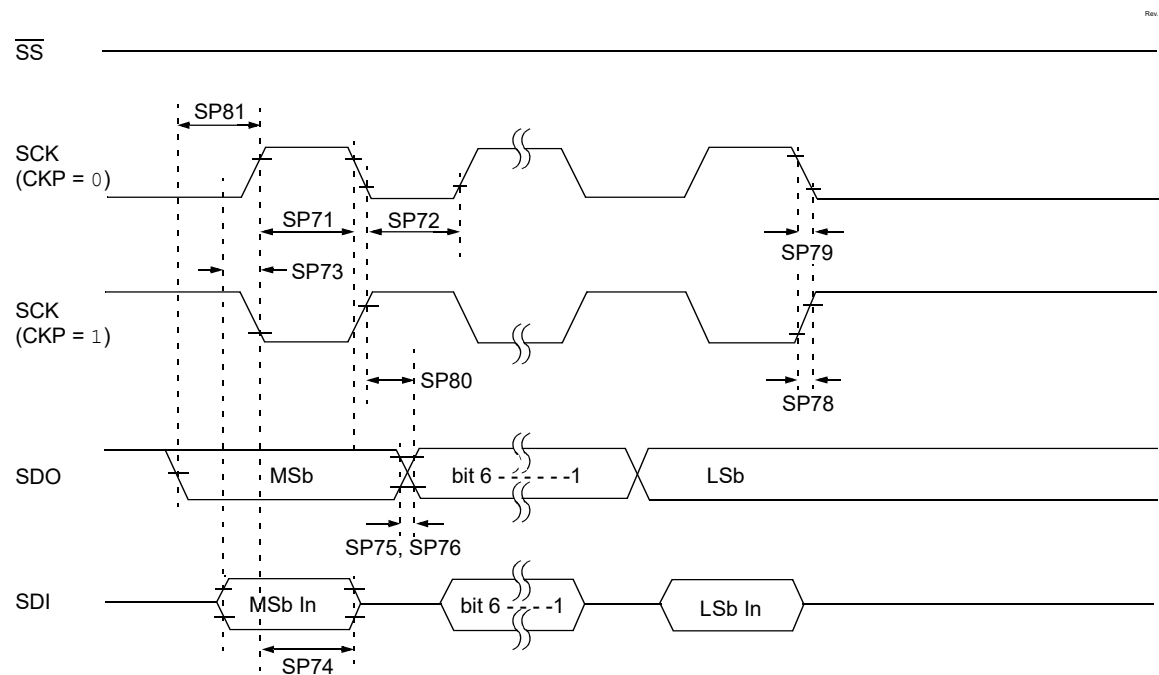
† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Figure 39-15. SPI Host Mode Timing (CKE = 0, SMP = 0)



Note: Refer to [Figure 39-3](#) for load conditions.

Figure 39-16. SPI Host Mode Timing (CKE = 1, SMP = 1)



Note: Refer to [Figure 39-3](#) for load conditions.

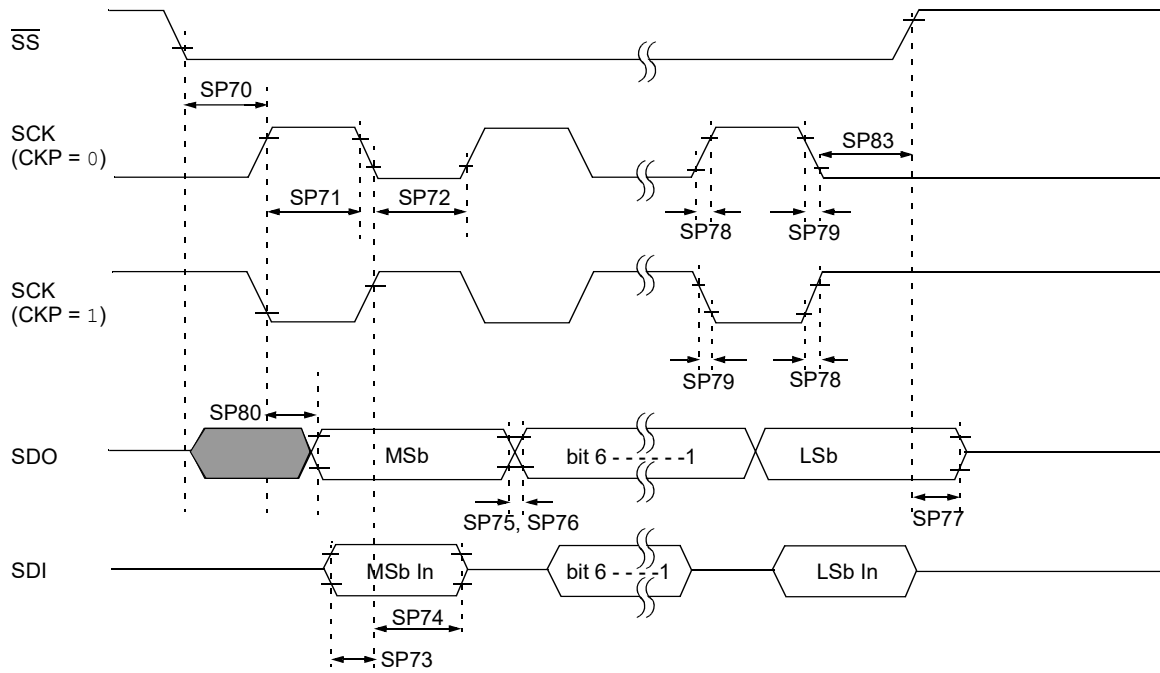
Table 39-24.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|----------------------------------|---|---------------------|--------|------|-------|------------------------------|
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| SP70* | $T_{SSL2SCH}$, $T_{SSL2SCL}$ | $\overline{SS}\downarrow$ to SCK \downarrow or SCK \uparrow input | $2.25 \cdot T_{CY}$ | — | — | ns | |
| SP71* | T_{SCH} | SCK input high time | $T_{CY} + 20$ | — | — | ns | |
| SP72* | T_{SCL} | SCK input low time | $T_{CY} + 20$ | — | — | ns | |
| SP73* | $T_{D1V2SCH}$, $T_{D1V2SCL}$ | Setup time of SDI data input to SCK edge | 100 | — | — | ns | |
| SP74* | $T_{SCH2D1L}$, $T_{SCL2D1L}$ | Hold time of SDI data input to SCK edge | 100 | — | — | ns | |
| SP75* | T_{DOR} | SDO data output rise time | — | 10 | 25 | ns | $3.0V \leq V_{DD} \leq 5.5V$ |
| | | | — | 25 | 50 | ns | $1.8V \leq V_{DD} \leq 5.5V$ |
| SP76* | T_{DOF} | SDO data output fall time | — | 10 | 25 | ns | |
| SP77* | $T_{SSH2DOZ}$ | $\overline{SS}\uparrow$ to SDO output high-impedance | 10 | — | 50 | ns | |
| SP80* | $T_{SCH2DOV}$, $T_{SCL2DOV}$ | SDO data output valid after SCK edge | — | — | 50 | ns | $3.0V \leq V_{DD} \leq 5.5V$ |
| | | | — | — | 145 | ns | $1.8V \leq V_{DD} \leq 5.5V$ |
| SP81* | $T_{DOV2SCH}$, $T_{DOV2SCL}$ | SDO data output setup to SCK edge | $1 T_{CY}$ | — | — | ns | |
| SP82* | $T_{SSL2DOV}$ | SDO data output valid after $\overline{SS}\downarrow$ edge | — | — | 50 | ns | |
| SP83* | $T_{SCH2SSH}$, $T_{SCL2SSH}$ | $\overline{SS}\uparrow$ after SCK edge | $1.5 T_{CY} + 40$ | — | — | ns | |

* These parameters are characterized but not tested.

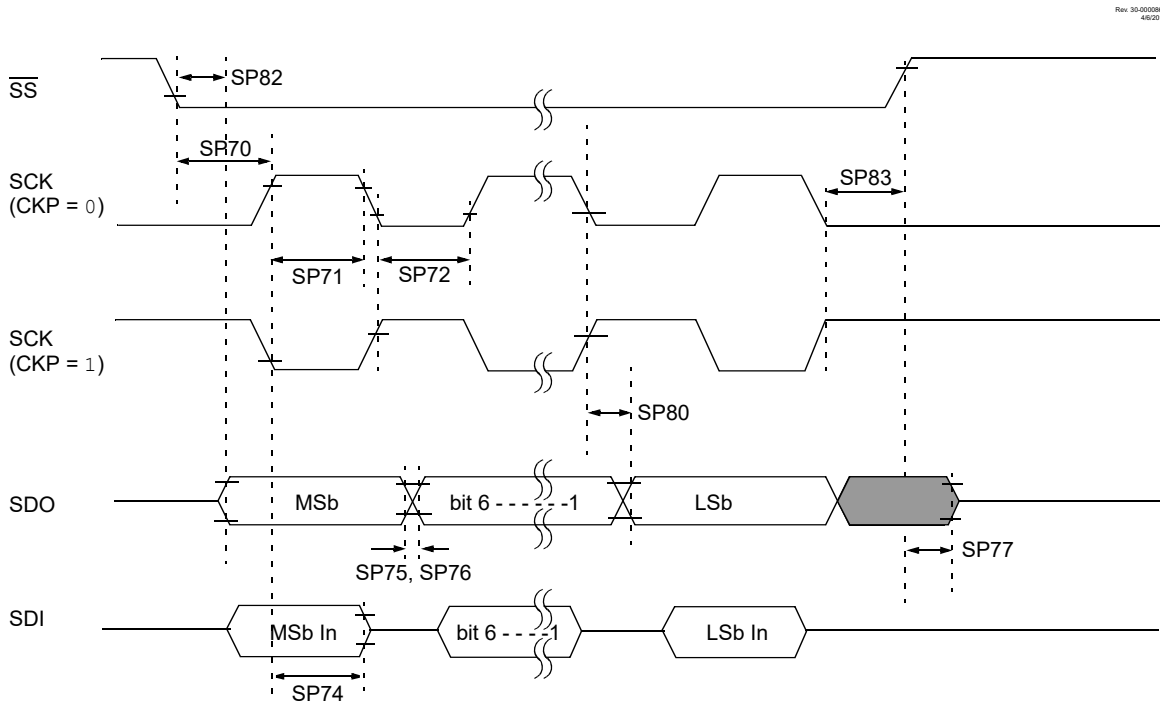
† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Figure 39-17. SPI Client Mode Timing (CKE = 0)



Note: Refer to [Figure 39-3](#) for load conditions.

Figure 39-18. SPI Client Mode Timing (CKE = 1)



Note: Refer to [Figure 39-3](#) for load conditions.

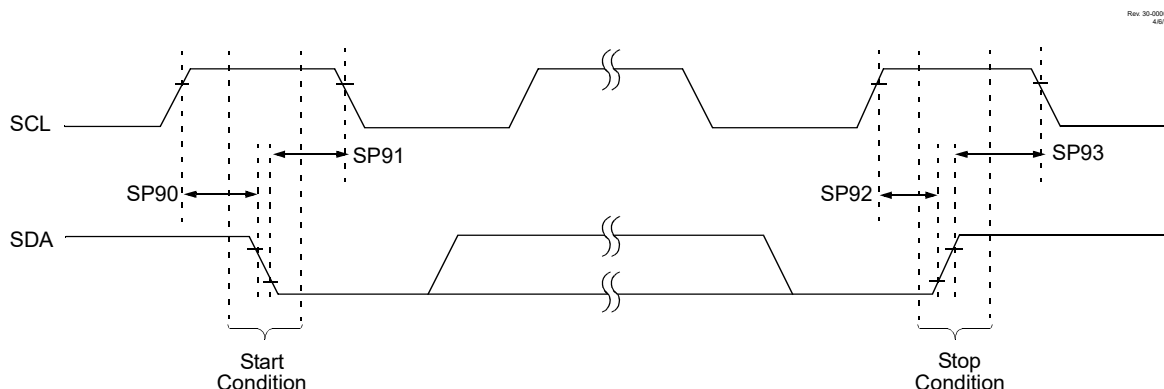
39.4.18 I²C Bus Start/Stop Bits Requirements

Table 39-25.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | | |
|---|---------------------|-----------------|--------------|--------|------|-------|------------|---|
| Param. No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions | |
| SP90* | T _{SU:STA} | Start condition | 100 kHz mode | 4700 | — | — | ns | Only relevant for Repeated Start Setup time 400 kHz mode 600 condition |
| | | Setup time | 400 kHz mode | 600 | — | — | | |
| SP91* | T _{HD:STA} | Start condition | 100 kHz mode | 4000 | — | — | ns | After this period, the first clock Hold time 400 kHz mode 600 — pulse is generated |
| | | Hold time | 400 kHz mode | 600 | — | — | | |
| SP92* | T _{SU:STO} | Stop condition | 100 kHz mode | 4700 | — | — | ns | |
| | | Setup time | 400 kHz mode | 600 | — | — | | |
| SP93* | T _{HD:STO} | Stop condition | 100 kHz mode | 4000 | — | — | ns | |
| | | Hold time | 400 kHz mode | 600 | — | — | | |

* These parameters are characterized but not tested.

Figure 39-19. I²C Bus Start/Stop Bits Timing



Note: Refer to Figure 39-3 for load conditions.

39.4.19 I²C Bus Data Requirements

Table 39-26.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-------------------|-----------------------|--------------|------------------------|-------|------------|--|
| Param. No. | Sym. | Characteristic | Min. | Max. | Units | Conditions | |
| SP100* | T _{HIGH} | Clock high time | 100 kHz mode | 4.0 | — | μs | Device must operate at a minimum of 1.5 MHz |
| | | | 400 kHz mode | 0.6 | — | μs | Device must operate at a minimum of 10 MHz |
| | | | SSP module | 1.5T _{CY} | — | | |
| SP101* | T _{LOW} | Clock low time | 100 kHz mode | 4.7 | — | μs | Device must operate at a minimum of 1.5 MHz |
| | | | 400 kHz mode | 1.3 | — | μs | Device must operate at a minimum of 10 MHz |
| | | | SSP module | 1.5T _{CY} | — | | |
| SP102* | T _R | SDA and SCL rise time | 100 kHz mode | — | 1000 | ns | |
| | | | 400 kHz mode | 20 + 0.1C _B | 300 | ns | C _B is specified to be from 10-400 pF |

.....continued

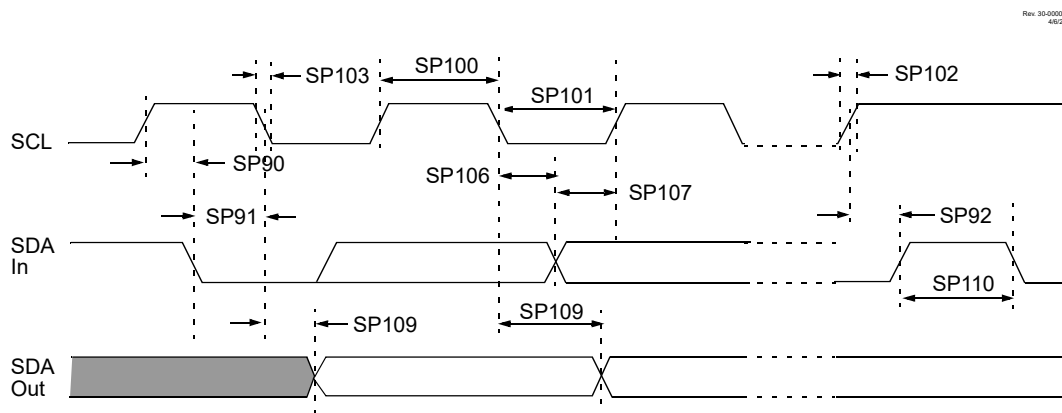
| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|--------------|-------------------------|--------------|---------------|------|---------|---|
| Param. No. | Sym. | Characteristic | | Min. | Max. | Units | Conditions |
| SP103* | T_F | SDA and SCL fall time | 100 kHz mode | — | 250 | ns | C_B is specified to be from 10-400 pF |
| | | | 400 kHz mode | $20 + 0.1C_B$ | 250 | ns | |
| SP106* | $T_{HD:DAT}$ | Data input hold time | 100 kHz mode | 0 | — | ns | |
| | | | 400 kHz mode | 0 | 0.9 | μ s | |
| SP107* | $T_{SU:DAT}$ | Data input setup time | 100 kHz mode | 250 | — | ns | (Note 2) |
| | | | 400 kHz mode | 100 | — | ns | |
| SP109* | T_{AA} | Output valid from clock | 100 kHz mode | — | 3500 | ns | (Note 1) |
| | | | 400 kHz mode | — | — | ns | |
| SP110* | T_{BUF} | Bus free time | 100 kHz mode | 4.7 | — | μ s | Time the bus must be free before a new transmission can start |
| | | | 400 kHz mode | 1.3 | — | μ s | |
| SP111 | C_B | Bus capacitive loading | | — | | pF | |

* These parameters are characterized but not tested.

Notes:

1. As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (min. 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.
2. A Fast mode (400 kHz) I²C bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement $T_{SU:DAT} \geq 250$ ns must then be met. This will automatically be the case if the device does not stretch the low period of the SCL signal. If such a device does stretch the low period of the SCL signal, it must output the next data bit to the SDA line $TR_{max} + T_{SU:DAT} = 1000 + 250 = 1250$ ns (according to the Standard mode I²C bus specification), before the SCL line is released.

Figure 39-20. I²C Bus Data Timing



Note: Refer to Figure 39-3 for load conditions.

39.4.20 Configurable Logic Cell (CLC) Characteristics

Table 39-27.

| Standard Operating Conditions (unless otherwise stated) | | | | | | | |
|---|-------------|---|------|--------|------|-------|------------------------|
| Operating Temperature: $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ | | | | | | | |
| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
| CLC01* | T_{CLCIN} | CLC input time | — | 7 | OS17 | ns | (Note1) |
| CLC02* | T_{CLC} | CLC module input to output propagation time | — | 24 | — | ns | $V_{DD} = 1.8\text{V}$ |
| | | | — | 12 | — | ns | $V_{DD} > 3.6\text{V}$ |

.....continued

Standard Operating Conditions (unless otherwise stated)

Operating Temperature: $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$

| Param No. | Sym. | Characteristic | Min. | Typ. † | Max. | Units | Conditions |
|-----------|---------------------|---------------------------------|------|--------|------|-------|------------|
| CLC03* | T_{CLCOUT} | CLC output time | | | | | |
| | | Rise Time | — | OS18 | — | — | (Note1) |
| CLC03* | T_{CLCOUT} | Fall Time | — | OS19 | — | — | (Note1) |
| CLC04* | F_{CLCMAX} | CLC maximum switching frequency | — | — | OS20 | — | |

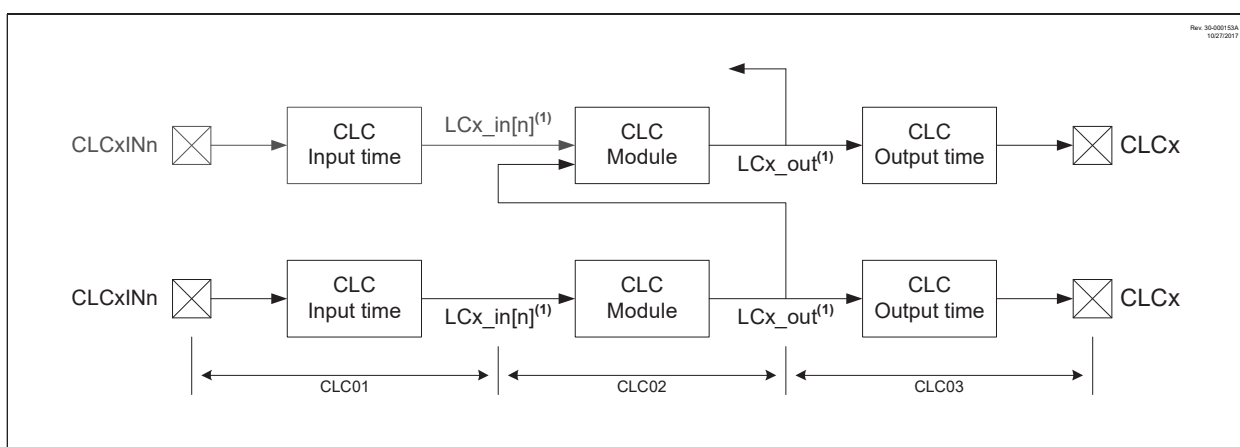
* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note:

- See "I/O and CLKOUT Timing Specifications" for OS7, OS8 and OS9 rise and fall times.

Figure 39-21. CLC Propagation Timing



40. DC and AC Characteristics Graphs and Tables

The graphs and tables provided in this section are for design guidance and are not tested. In some graphs or tables, the data presented are outside specified operating range (i.e., outside specified V_{DD} range). This is for information only and devices are ensured to operate properly only within the specified range. Unless otherwise noted, all graphs apply to both the L and LF devices.

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore, outside the warranted range.

Note: "Typical" represents the mean of the distribution at 25°C. "Maximum" (Max.) and "Minimum" (Min.) represent (mean + 3σ) or (mean - 3σ), respectively, where σ is a standard deviation over each temperature range.

40.1 Analog-to-Digital Converter Oscillator Graphs

Figure 40-1. ADC RC Oscillator Period vs. V_{DD}

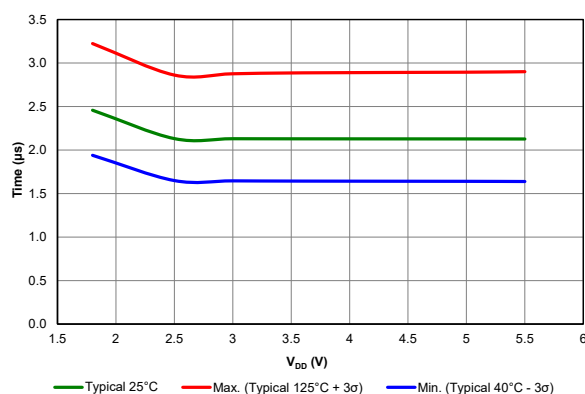
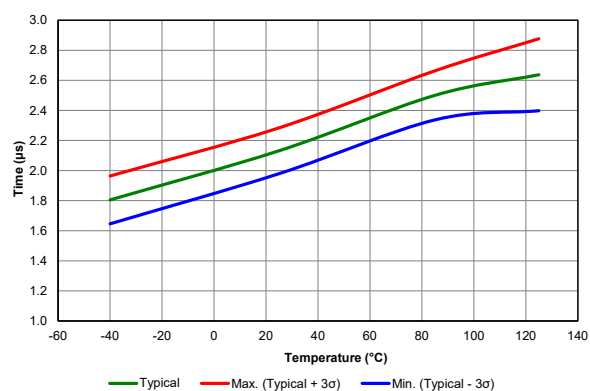


Figure 40-2. ADC RC Oscillator Period vs. Temperature ($V_{DD} = 3.0V$)



40.2 Analog-to-Digital Converter (10-bit) Graphs

Figure 40-3. ADC, DNL, $V_{DD} = 3.0V$, $T_{AD} = 1 \mu s$, $25^\circ C$

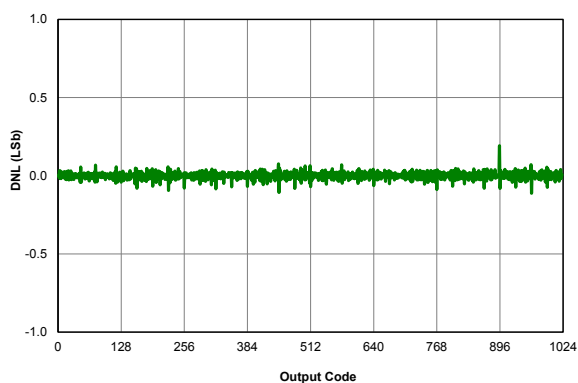


Figure 40-4. ADC, DNL, $V_{DD} = 3.0V$, $T_{AD} = 4 \mu s$, $25^\circ C$

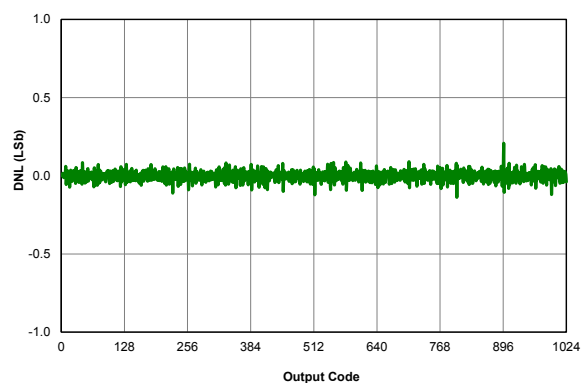


Figure 40-5. ADC, INL, $V_{DD} = 3.0V$, $T_{AD} = 1 \mu s$, $25^{\circ}C$

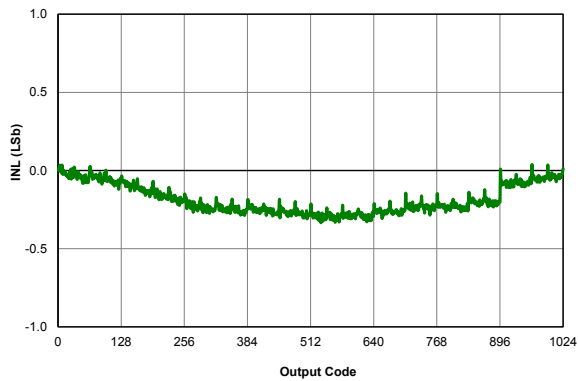


Figure 40-6. ADC, INL, $V_{DD} = 3.0V$, $T_{AD} = 4 \mu s$, $25^{\circ}C$

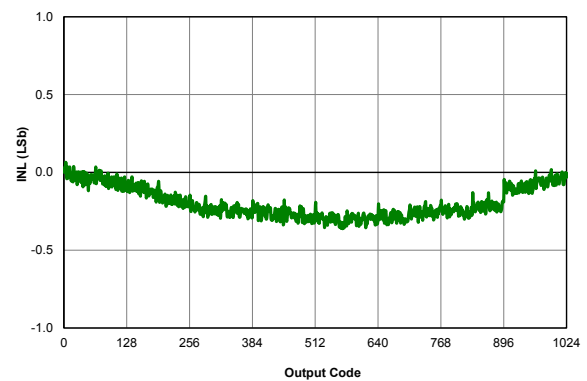


Figure 40-7. ADC 10-bit, DNL, $V_{DD} = 3.0V$, $V_{REF} = 3.0V$, Min and Max values at $125^{\circ}C + 3\sigma$

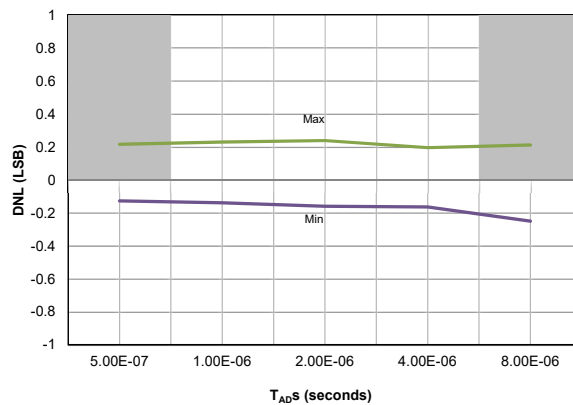


Figure 40-8. ADC 10-bit, INL, $V_{DD} = 3.0V$, $V_{REF} = 3.0V$, Min and Max values at $125^{\circ}C + 3\sigma$

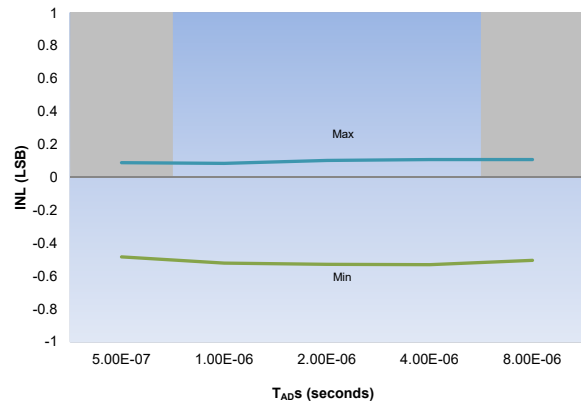


Figure 40-9. ADC 10-bit, DNL, $V_{DD} = 3.0V$, $T_{AD} = 1 \mu s$, Min and Max values at $125^{\circ}C + 3\sigma$

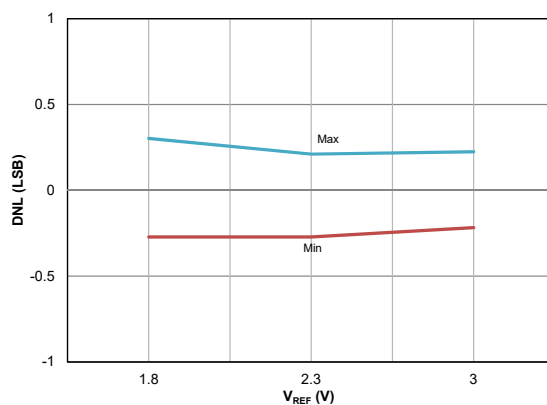
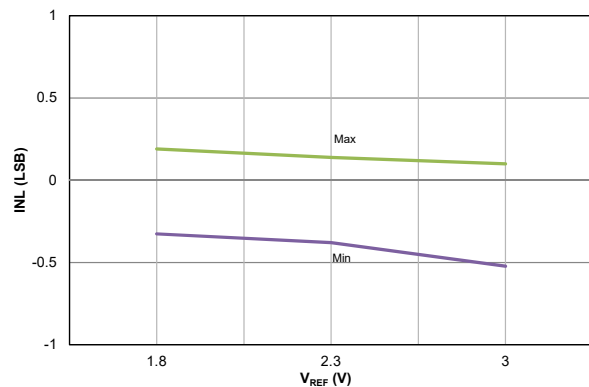
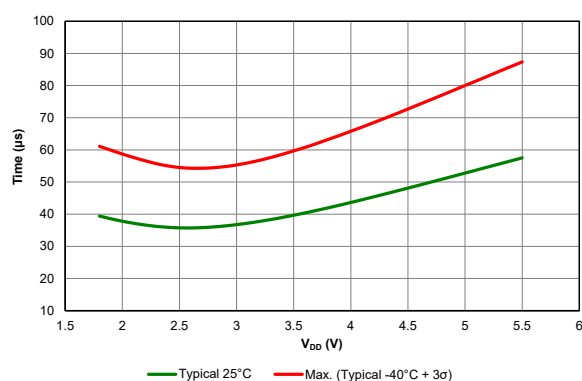


Figure 40-10. ADC 10-BIT, INL, $V_{DD} = 3.0V$, $T_{AD} = 1 \mu s$, Min and Max values at $125^{\circ}C + 3\sigma$



40.3 Bandgap Ready Graphs

Figure 40-11. Bandgap Ready Time



40.4 Brown-Out Reset Graphs

Figure 40-12. Brown-Out Reset Voltage, Trip Point (BORV = 00)

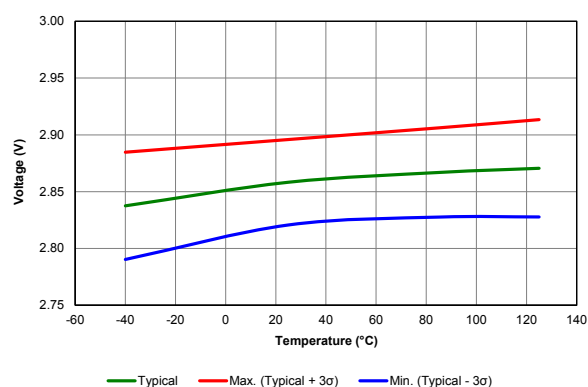


Figure 40-13. Brown-Out Reset Hysteresis, Trip Point (BORV = 00)

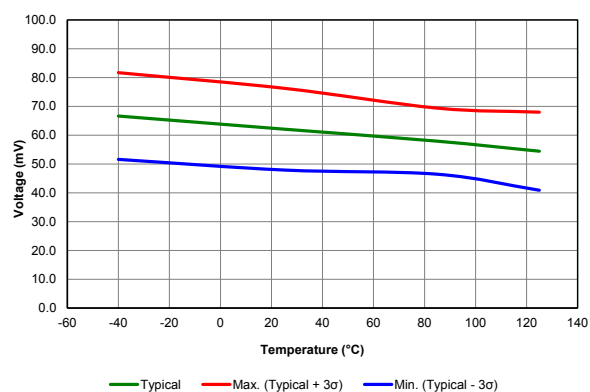


Figure 40-14. Brown-Out Reset Voltage, Trip Point
(BORV = 01)

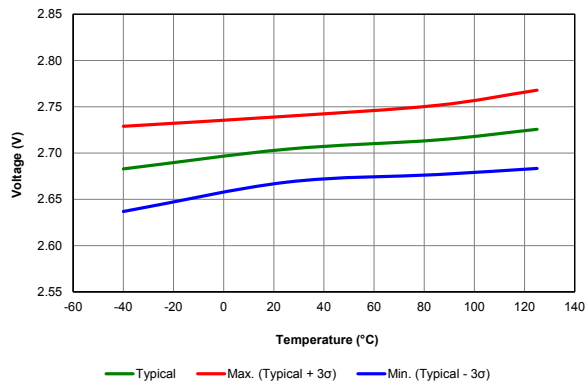


Figure 40-15. Brown-Out Reset Hysteresis, Trip Point
(BORV = 01)

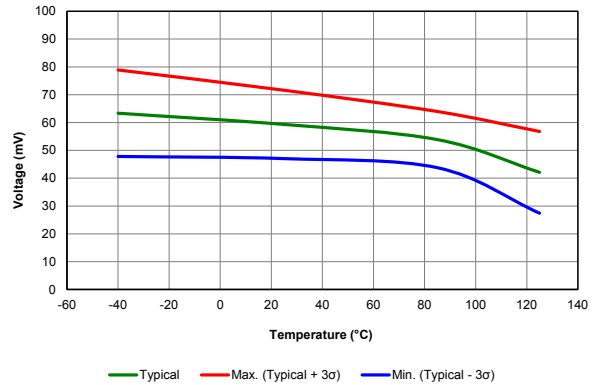


Figure 40-16. Brown-Out Reset Voltage, Trip Point
(BORV = 10)

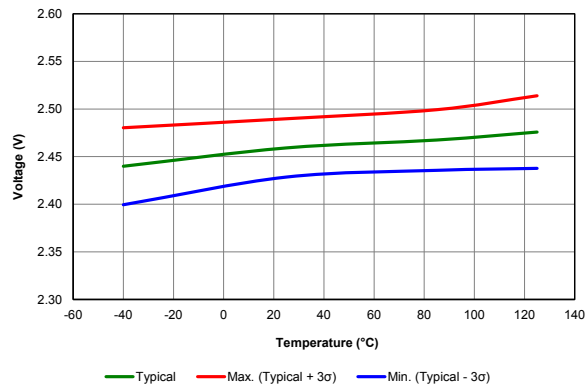


Figure 40-17. Brown-Out Reset Hysteresis, Trip Point
(BORV = 10)

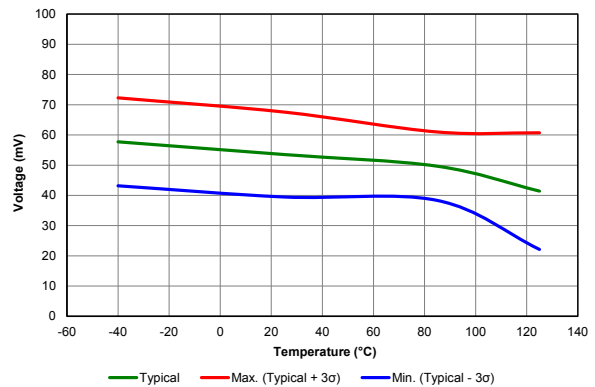


Figure 40-18. Brown-Out Reset Voltage, Trip Point
(BORV = 11)

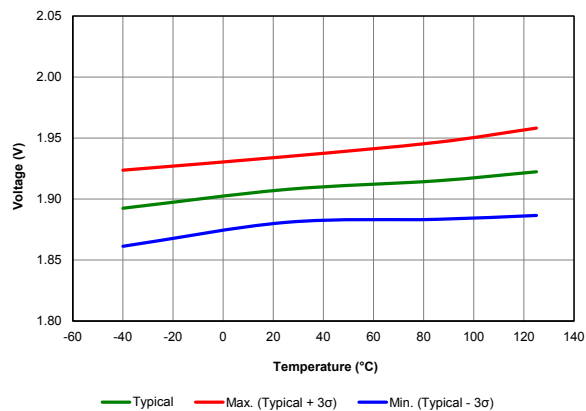


Figure 40-19. Brown-Out Reset Hysteresis, Trip Point
(BORV = 11)

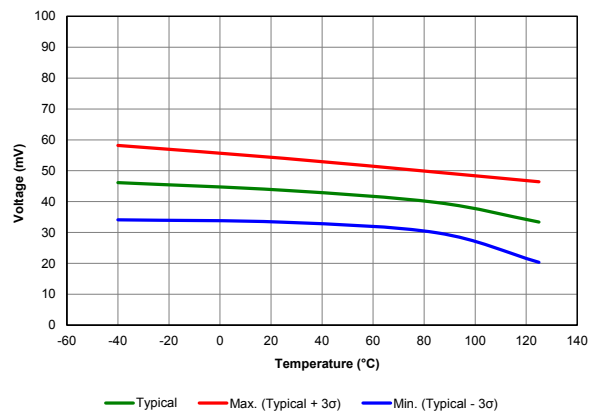
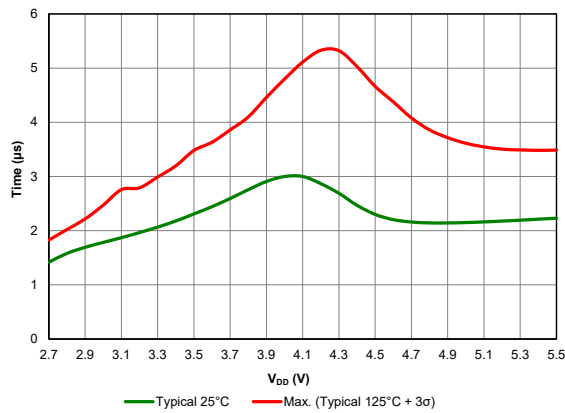


Figure 40-20. BOR Response Time



40.5 Comparator Graphs

Figure 40-21. Comparator Hysteresis, Normal Power Mode (CxSP = 1), V_{DD} = 3.0V, Typical Measured Values

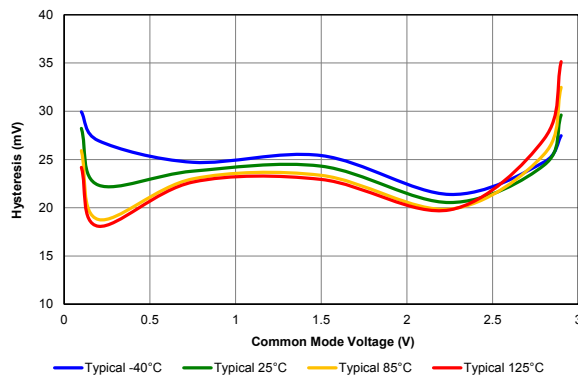


Figure 40-22. Comparator Offset, Normal Power Mode (CxSP = 1), V_{DD} = 3.0V, Typical Measured Values at 25°C

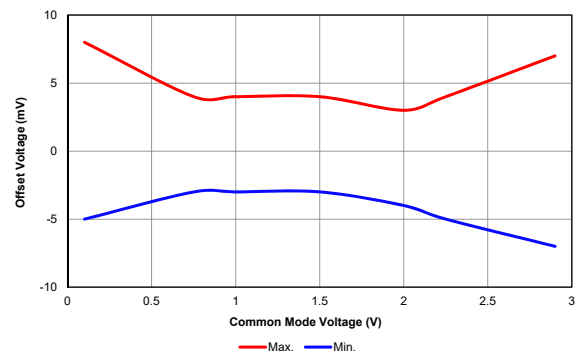


Figure 40-23. Comparator Offset, Normal Power Mode ($C_{xSP} = 1$), $V_{DD} = 3.0V$, Typical Measured Values from $-40^{\circ}C$ to $125^{\circ}C$

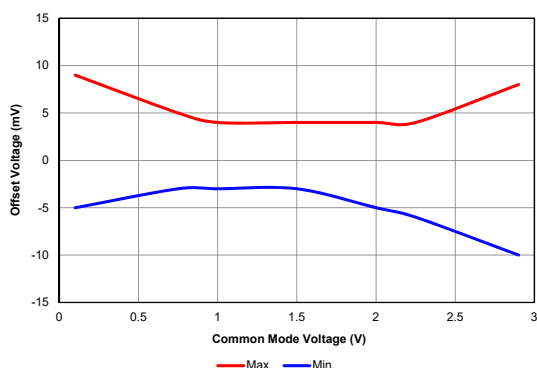


Figure 40-24. Comparator Hysteresis, Normal Power Mode ($C_{xSP} = 1$), $V_{DD} = 5.5V$, Typical Measured Values

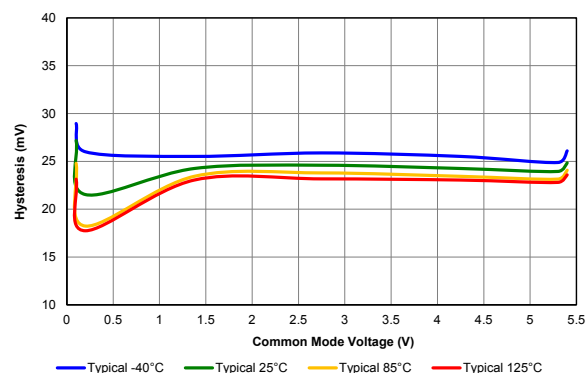


Figure 40-25. Comparator Offset, Normal Power Mode ($C_{xSP} = 1$), $V_{DD} = 5.5V$, Typical Measured Values at $25^{\circ}C$

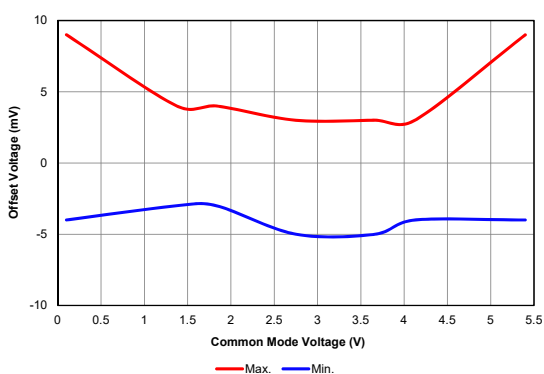


Figure 40-26. Comparator Offset, Normal Power Mode ($C_{xSP} = 1$), $V_{DD} = 5.5V$, Typical Measured Values from $-40^{\circ}C$ to $125^{\circ}C$

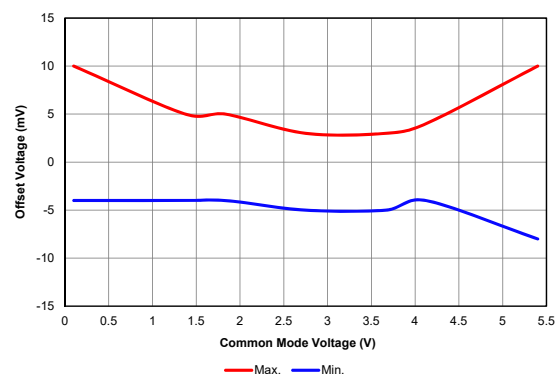


Figure 40-27. Comparator Response Time, Falling Edge

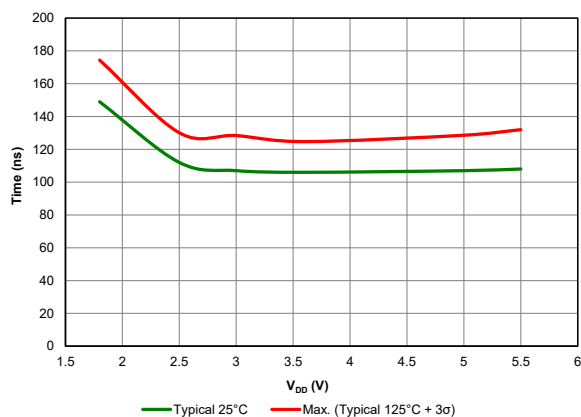
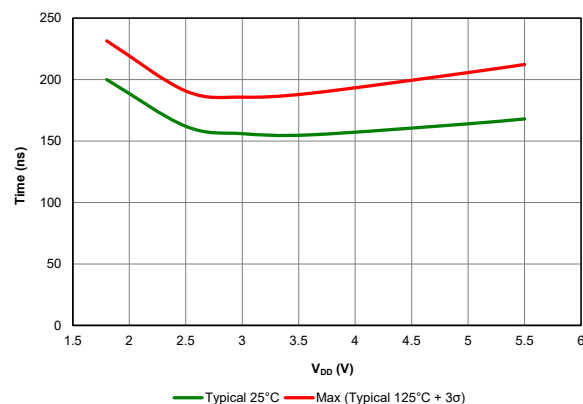


Figure 40-28. Comparator Response Time, Rising Edge



40.6 Fixed Voltage Reference Graphs

Figure 40-29. FVR Voltage Error 1x ($V_{DD} = 5.5\text{ V}$)

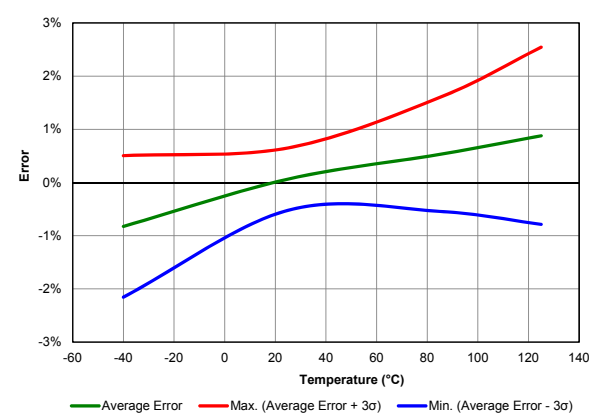


Figure 40-30. FVR Voltage Error 2x ($V_{DD} = 5.5\text{ V}$)

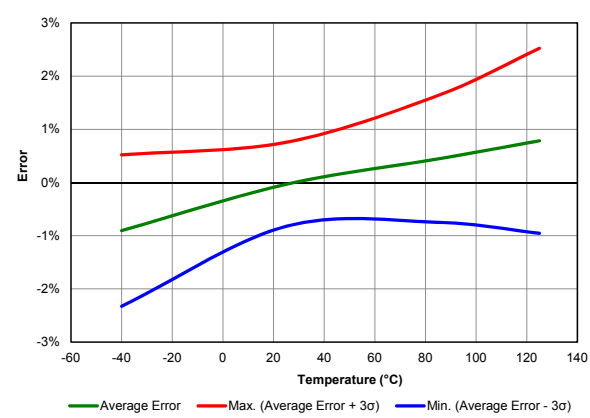
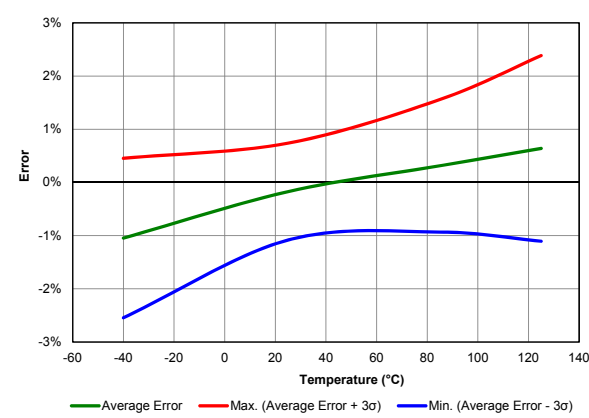


Figure 40-31. FVR Voltage Error 4x ($V_{DD} = 5.5\text{ V}$)



40.7 I/O Rise/Fall Times Graphs

Figure 40-32. Rise Time, Slew Rate Control Enabled

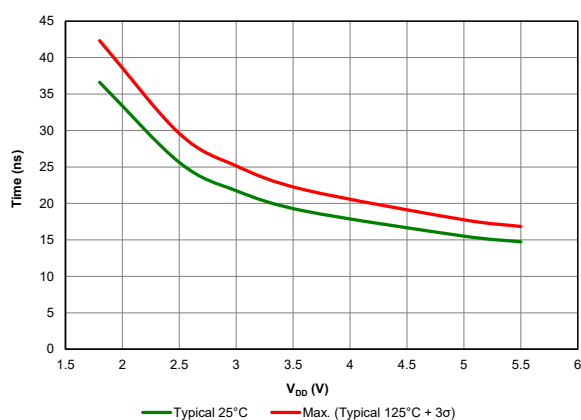


Figure 40-33. Fall Time, Slew Rate Control Enabled

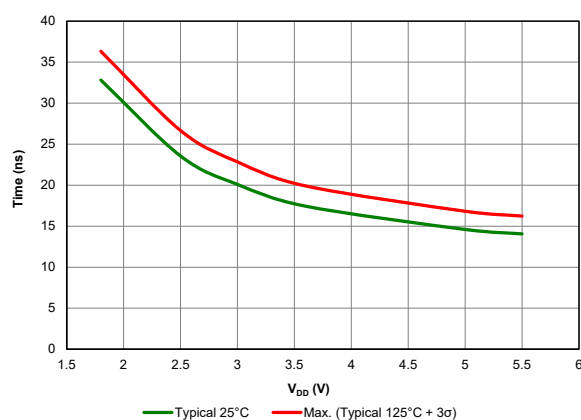


Figure 40-34. Rise Time, Slew Rate Control Disabled

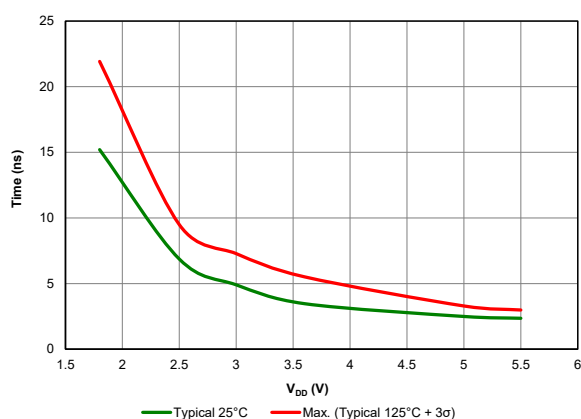
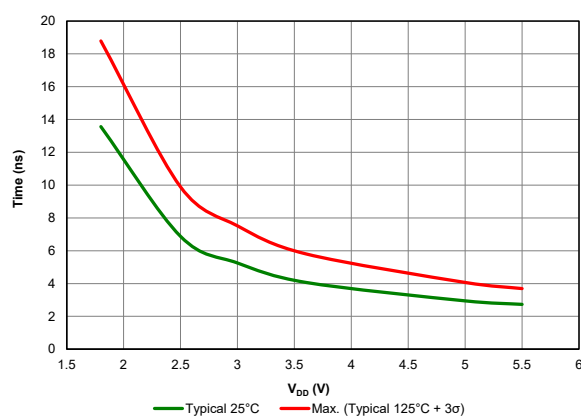


Figure 40-35. Fall Time, Slew Rate Control Disabled



40.8 I_{DD} Graphs

Figure 40-36. I_{DD}, LFINT, FOSC = 31 kHz

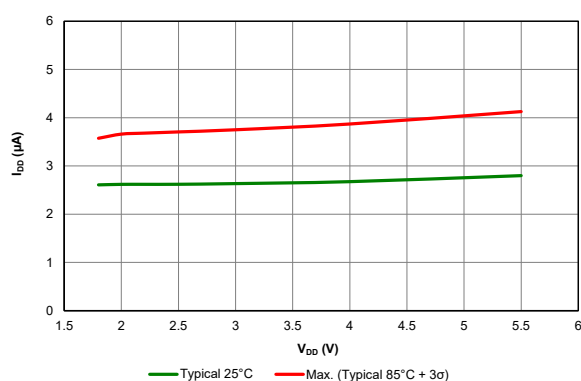


Figure 40-37. I_{DD}, INT Oscillator, Typical

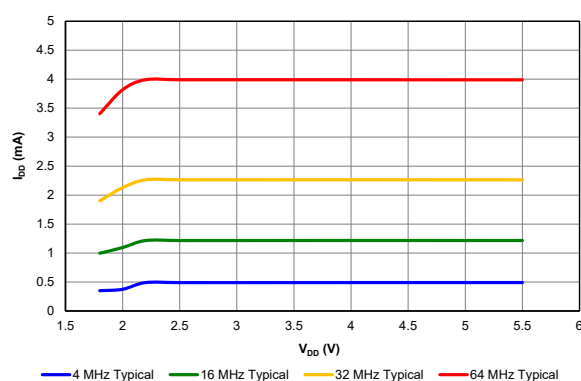


Figure 40-38. I_{DD}, INT Oscillator, Maximum

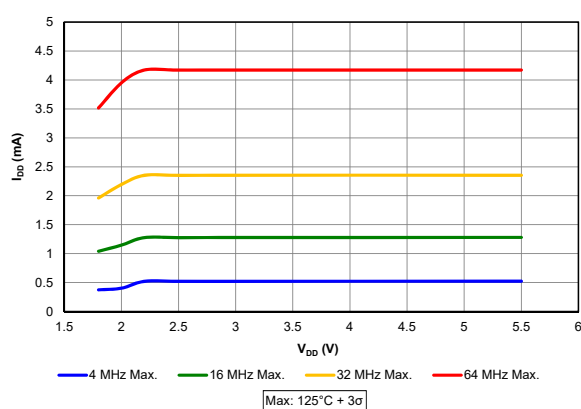


Figure 40-39. I_{DD}, ECM Oscillator, F_{OSC} = 4 MHz

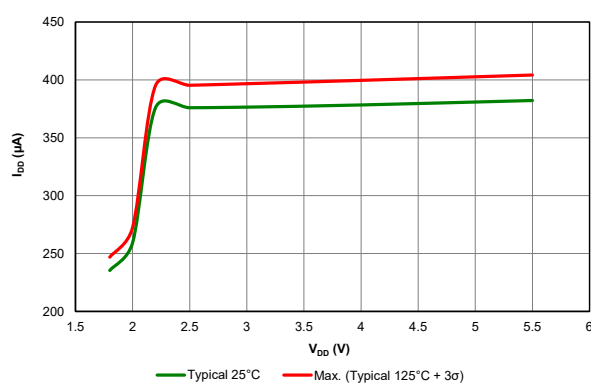


Figure 40-40. I_{DD}, ECH Oscillator, Typical

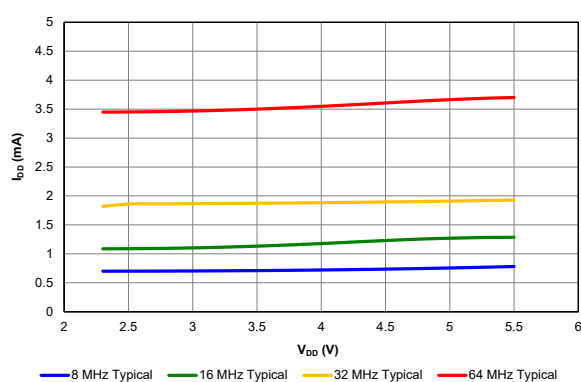
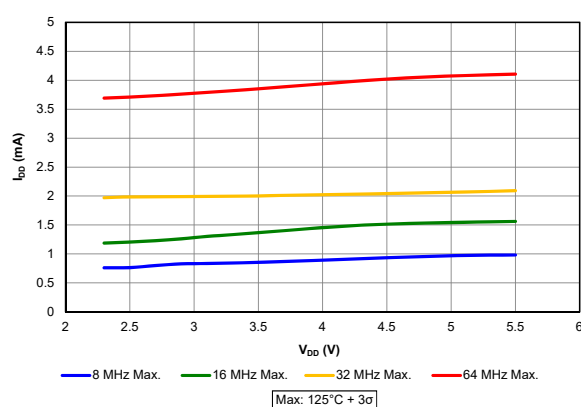


Figure 40-41. I_{DD}, ECH Oscillator, Maximum



40.9 Input Buffer Graphs

Figure 40-42. Schmitt Trigger High Values

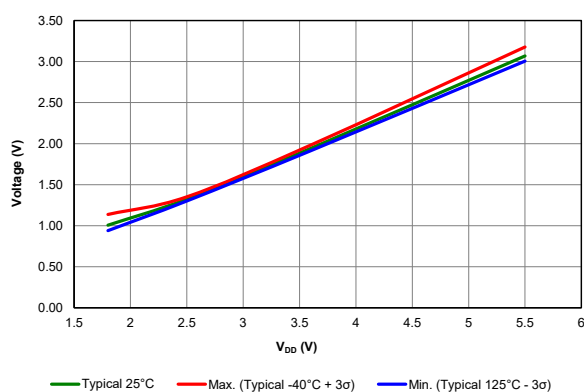


Figure 40-43. Schmitt Trigger Low Values

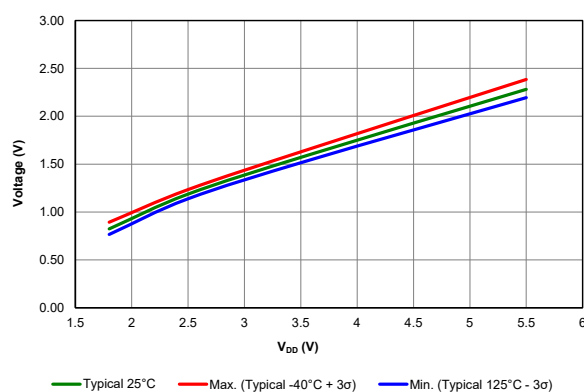
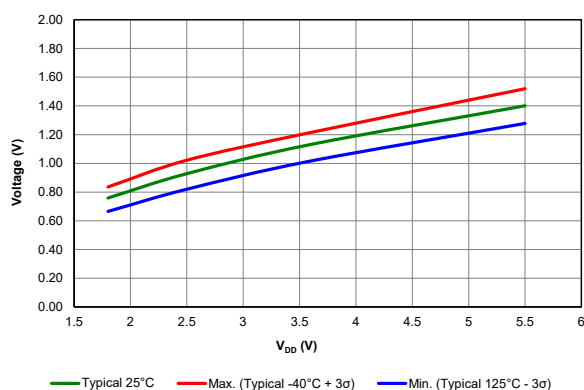


Figure 40-44. TTL Input Level



40.10 I_{PD} Graphs

Figure 40-45. I_{PD}, Brown-Out Reset (BOR)

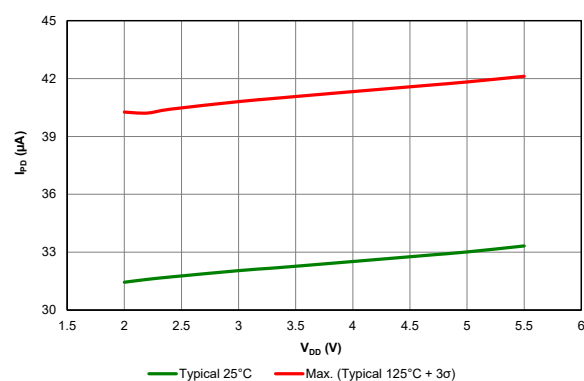


Figure 40-46. I_{PD}, Comparator

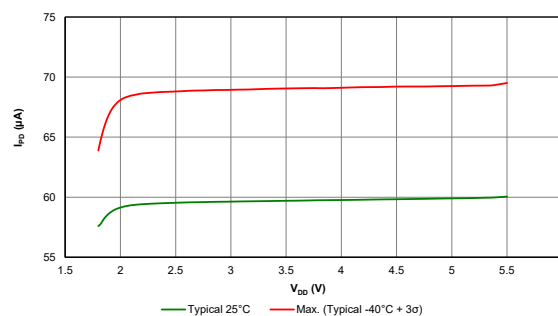
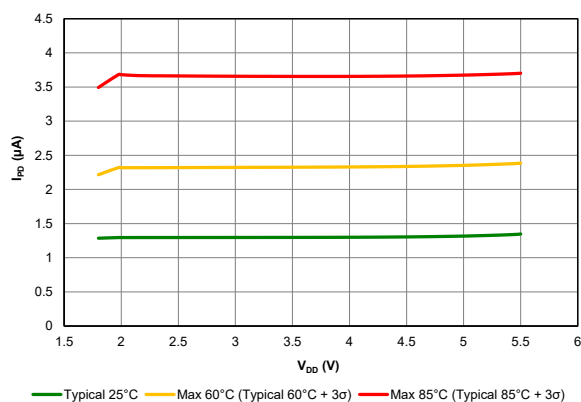
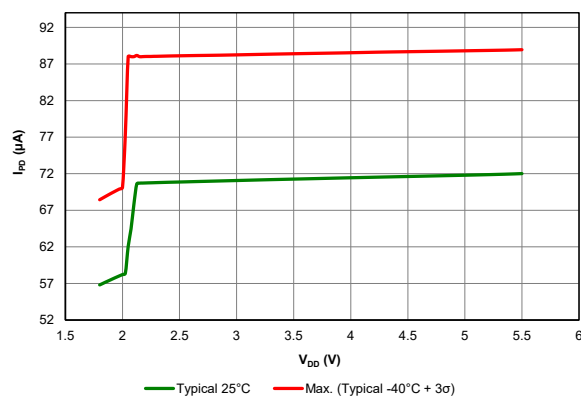
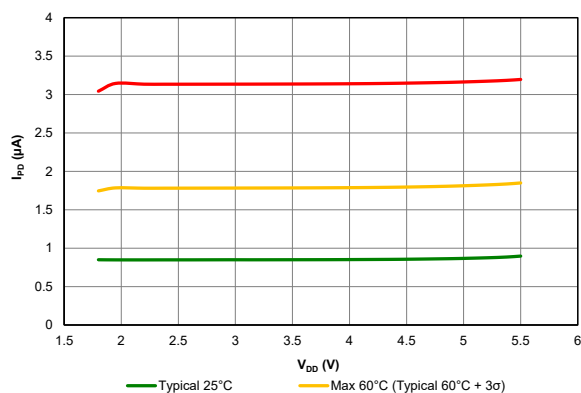
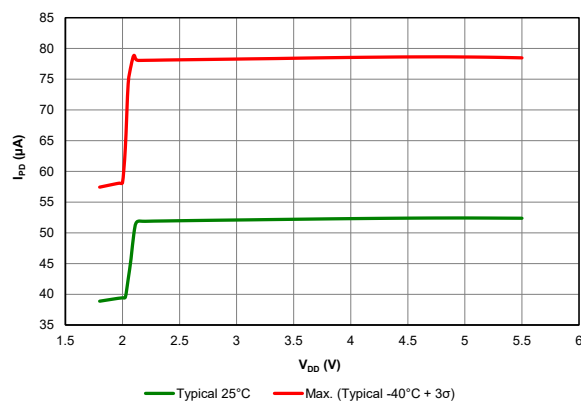
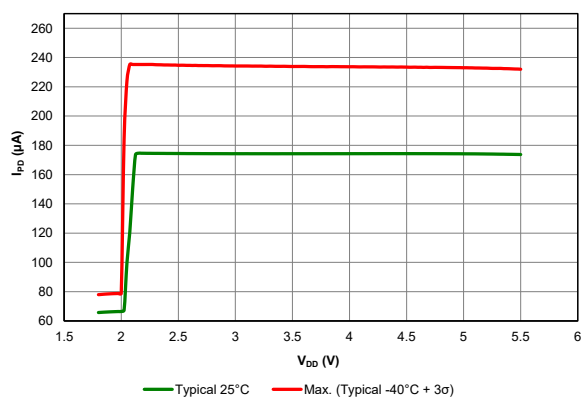


Figure 40-47. I_{PD} , Watchdog Timer (WDT)**Figure 40-48.** I_{PD} , Fixed Voltage Reference (FVR)**Figure 40-49.** I_{PD} Base (VREGPM = 10)**Figure 40-50.** I_{PD} Base (VREGPM = 01)**Figure 40-51.** I_{PD} Base (VREGPM = 00)

40.11 HFINTOSC Wake From Sleep Graphs

Figure 40-52. Wake from Sleep, VREGPM = 0x, HFINTOSC = 4 MHz

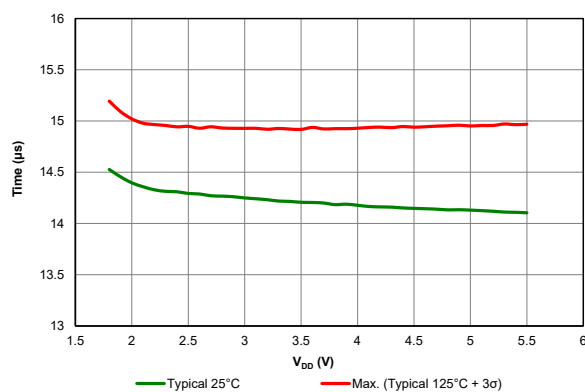


Figure 40-53. Wake from Sleep, VREGPM = 10, HFINTOSC = 4 MHz

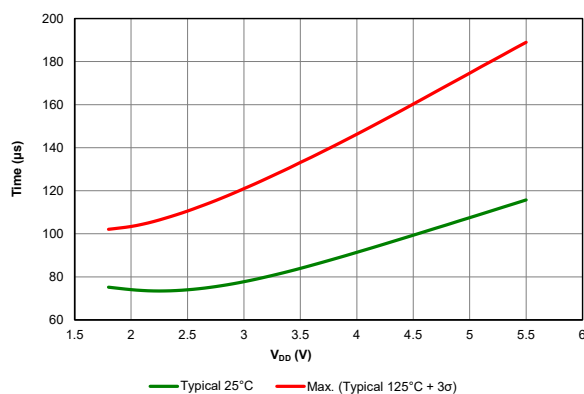


Figure 40-54. Wake from Sleep, VREGPM = 0x, HFINTOSC = 16 MHz

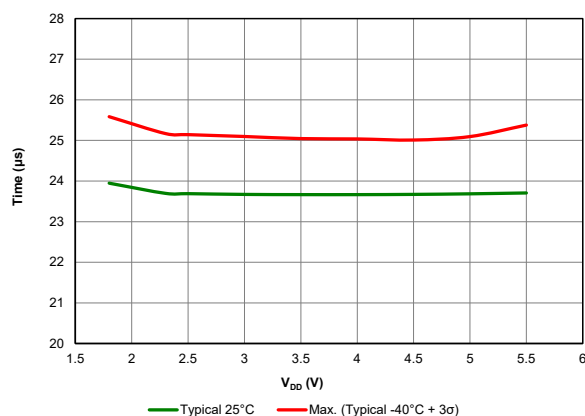
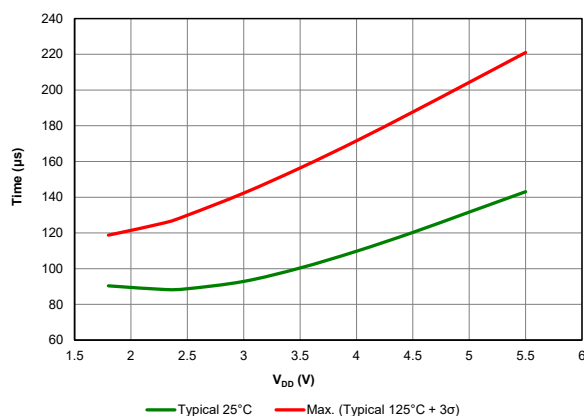
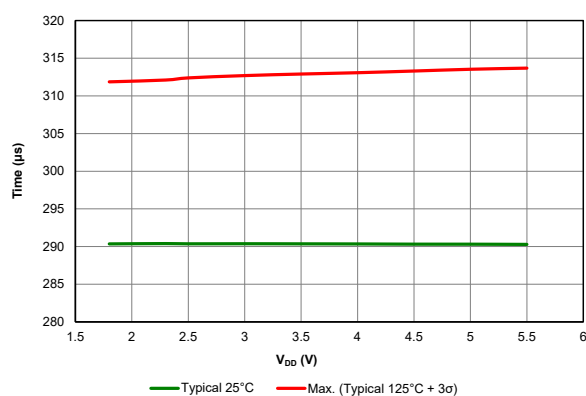


Figure 40-55. Wake from Sleep, VREGPM = 10, HFINTOSC = 16 MHz



40.12 LFINTOSC Wake From Sleep Graphs

Figure 40-56. Wake from Sleep, VREGPM = 01



40.13 Low-Power Brown-Out Reset Graphs

Figure 40-57. Low-Power Brown-Out Reset Release Voltage

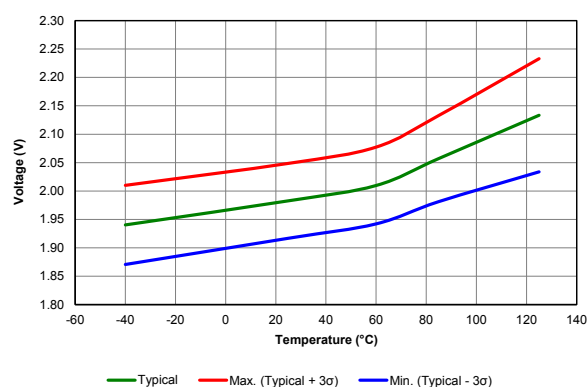


Figure 40-58. Low-Power Brown-Out Reset Rearm Voltage

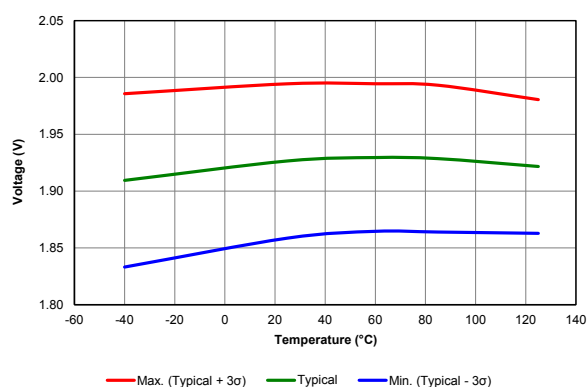
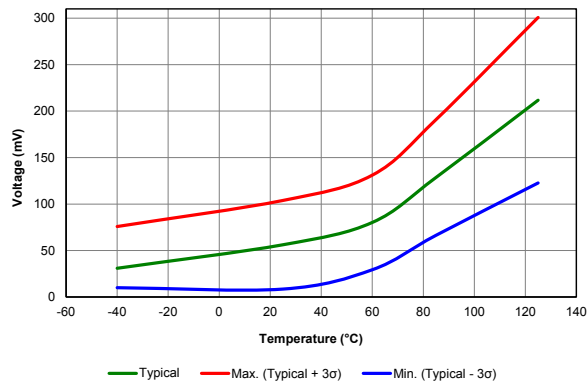


Figure 40-59. Low-Power Brown-Out Reset Hysteresis



40.14 Low-Voltage Detect Graphs

Figure 40-60. LVD Comparator Output High Trip Points

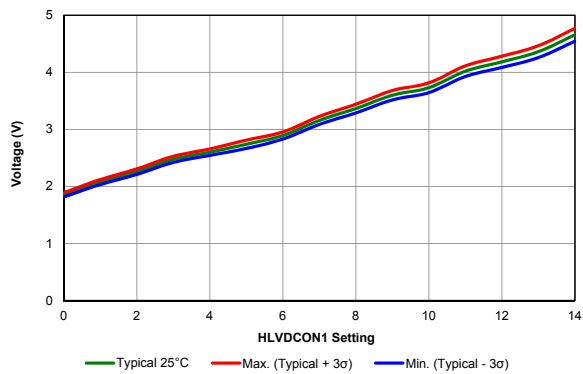
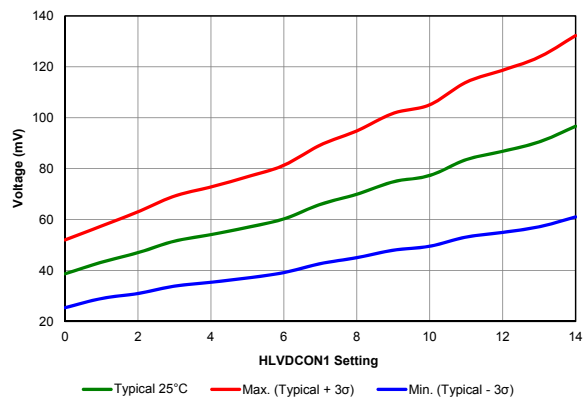
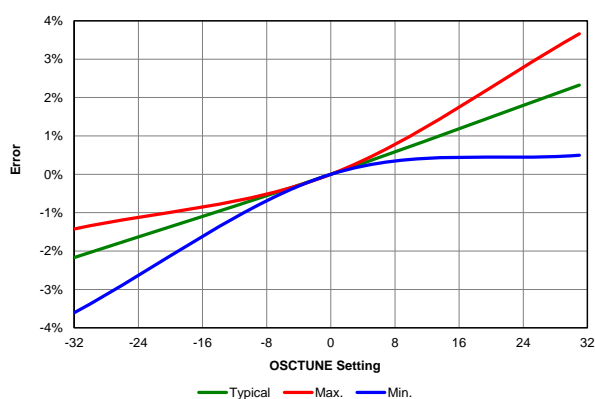


Figure 40-61. LVD Comparator Output Low Trip Points



40.15 OSCTUNE Graphs

Figure 40-62. OSCTUNE Frequency Range (Normalized to Center Frequency)



40.16 Power-On Reset Graphs

Figure 40-63. POR Release Voltage (VREGPM = 1x)

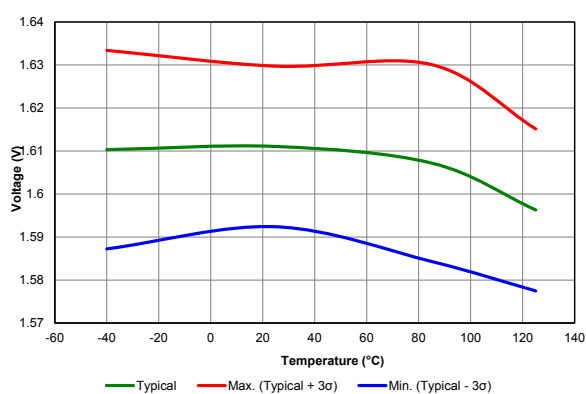


Figure 40-64. POR Release Voltage (VREGPM = 0x)

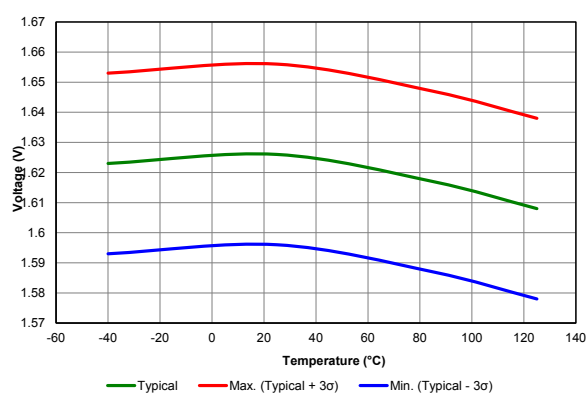
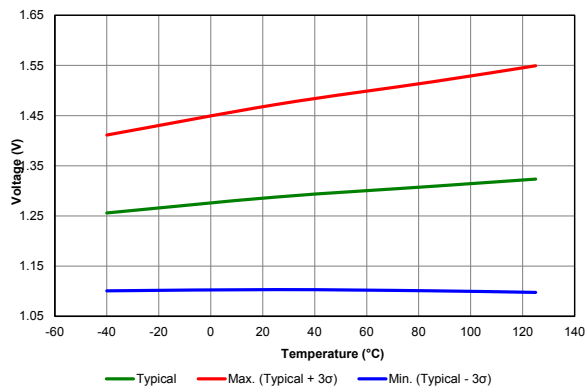


Figure 40-65. POR Rearm Voltage ($V_{REGPM} = 1\times$)



40.17 Power-Up Timer Graphs

Figure 40-66. PWRT Period vs. V_{DD}

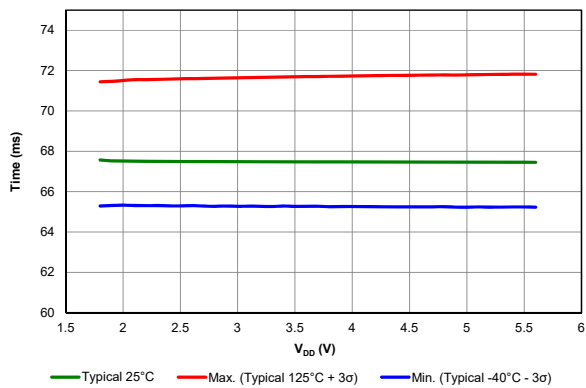
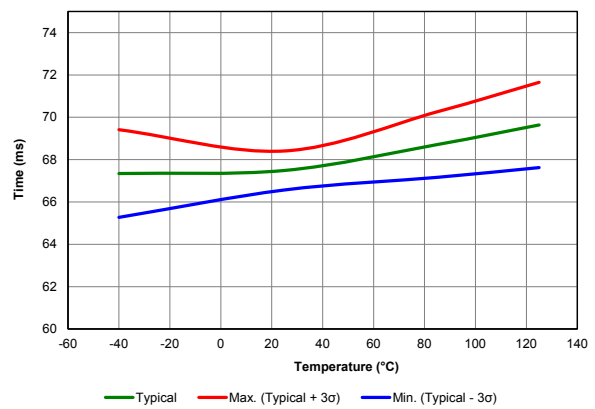


Figure 40-67. PWRT Period vs. Temperature ($V_{DD} = 3.0V$)



40.18 Temperature Indicator Graphs



Important: For all temperature indicator graphs: V_{REF+} set to V_{DD} , V_{REF-} set to V_{SS}

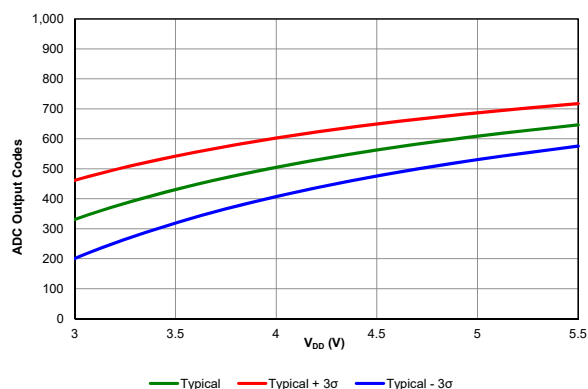
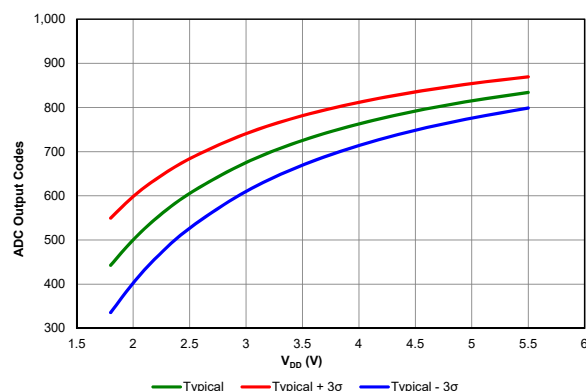
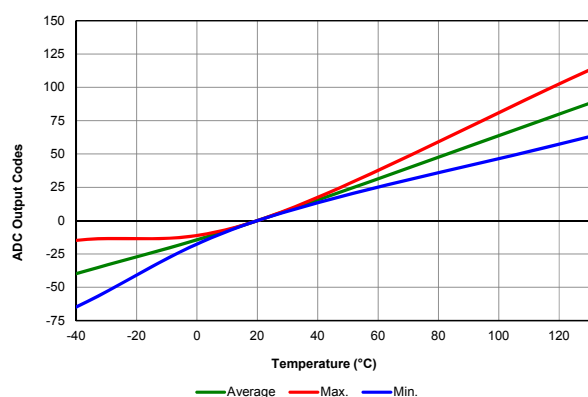
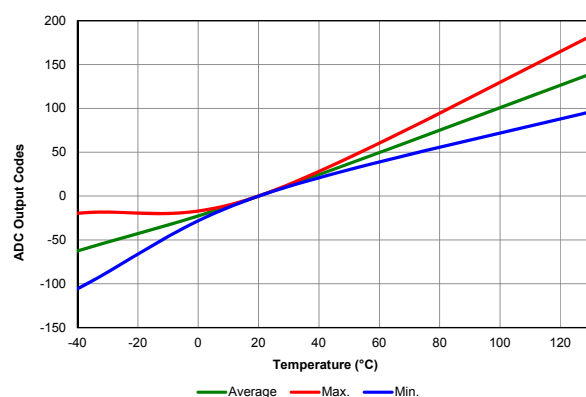
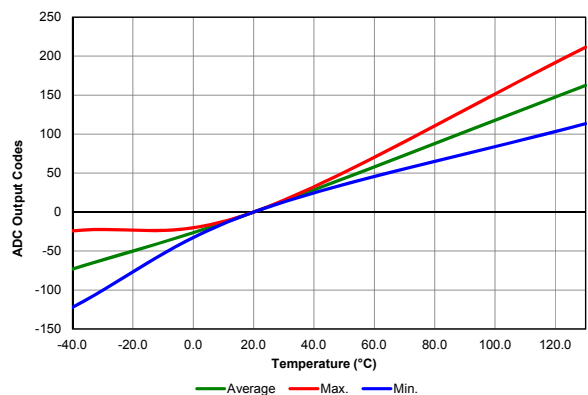
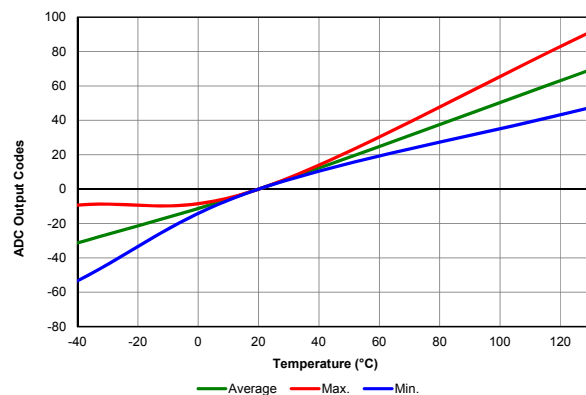
Figure 40-68. Temperature Indicator Initial Offset, High Range, Temp = 20°C**Figure 40-69.** Temperature Indicator Initial Offset, Low Range, Temp = 20°C**Figure 40-70.** Temperature Indicator Slope Normalized to 20°C, High Range, $V_{DD} = 5.5V$ **Figure 40-71.** Temperature Indicator Slope Normalized to 20°C, High Range, $V_{DD} = 3.5V$ **Figure 40-72.** Temperature Indicator Slope Normalized to 20°C, High Range, $V_{DD} = 3.0V$ **Figure 40-73.** Temperature Indicator Slope Normalized to 20°C, Low Range, $V_{DD} = 3.5V$ 

Figure 40-74. Temperature Indicator Slope Normalized to 20°C, Low Range, $V_{DD} = 3.0V$

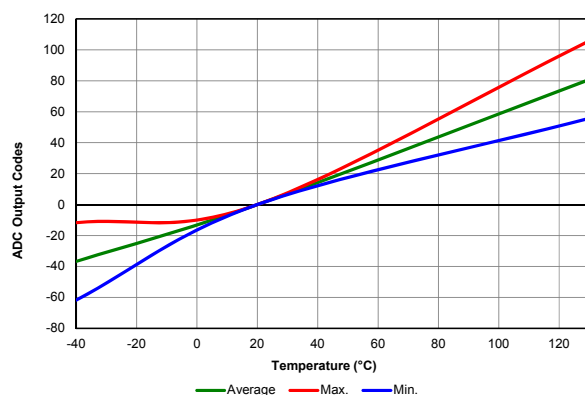
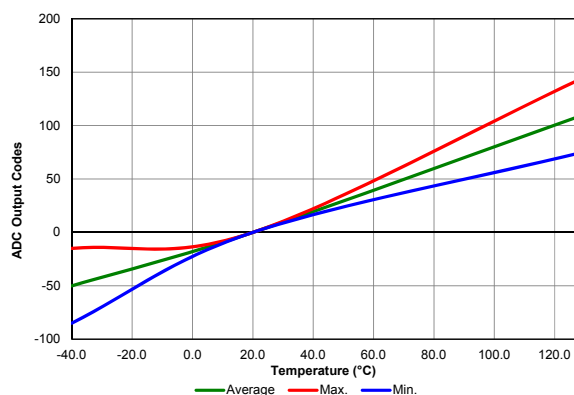


Figure 40-75. Temperature Indicator Slope Normalized to 20°C, Low Range, $V_{DD} = 2.2V$



40.19 VOH - VOL Graphs

Figure 40-76. V_{OH} vs. I_{OH} over Temperature, $V_{DD} = 5.5V$

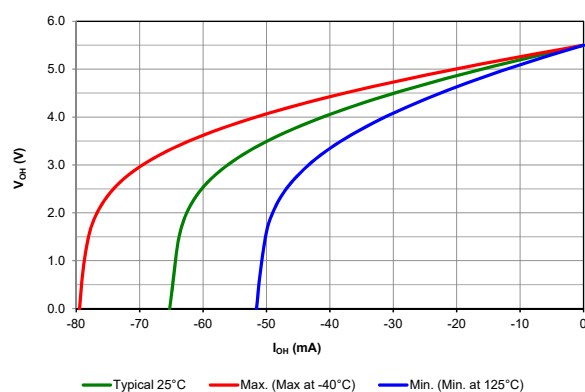


Figure 40-77. V_{OH} vs. I_{OH} over Temperature, $V_{DD} = 3V$

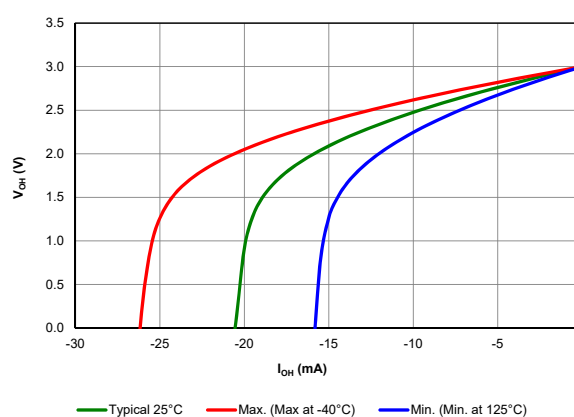
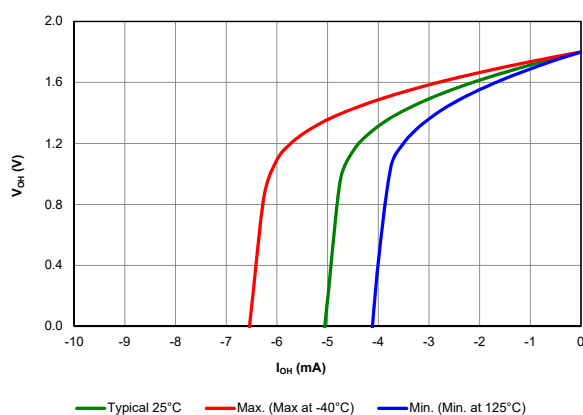
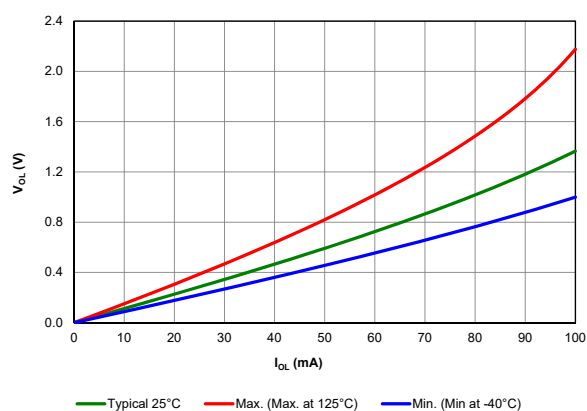
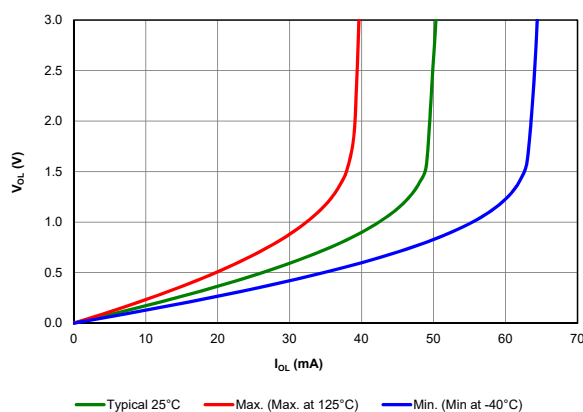
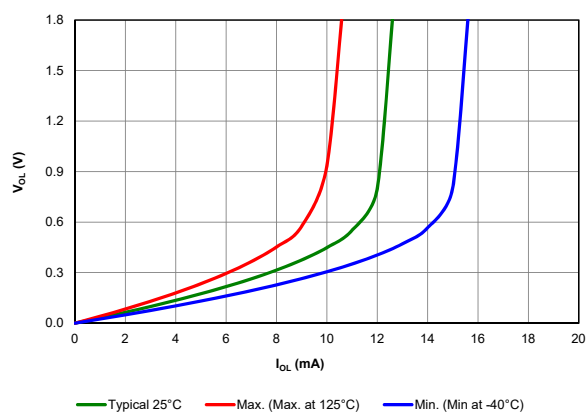


Figure 40-78. V_{OH} vs. I_{OH} over Temperature, $V_{DD} = 1.8V$ **Figure 40-79.** V_{OL} vs. I_{OL} over Temperature, $V_{DD} = 5.5V$ **Figure 40-80.** V_{OL} vs. I_{OL} over Temperature, $V_{DD} = 3V$ **Figure 40-81.** V_{OL} vs. I_{OL} over Temperature, $V_{DD} = 1.8V$ 

40.20 Watchdog Timer Graphs

Figure 40-82. WDT Base Time-Out Period (WDTPS = 0)

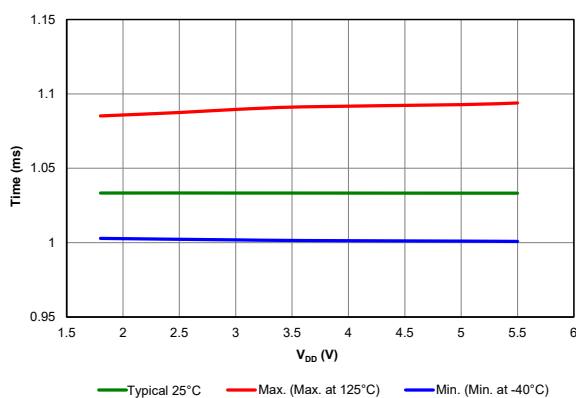
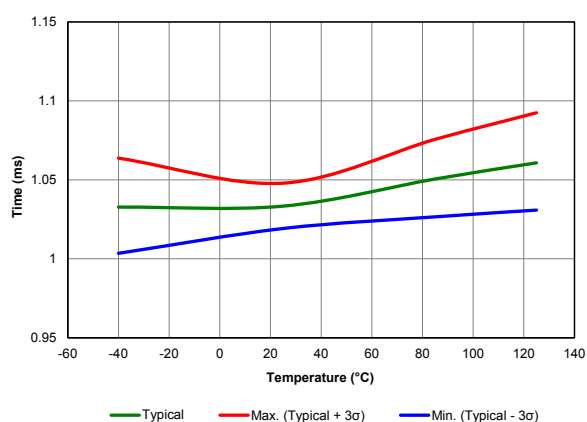
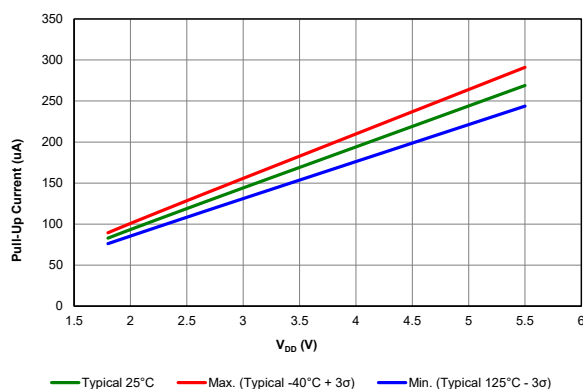


Figure 40-83. WDT Base Time-Out Period (WDTPS = 0, V_{DD} = 3.0V)



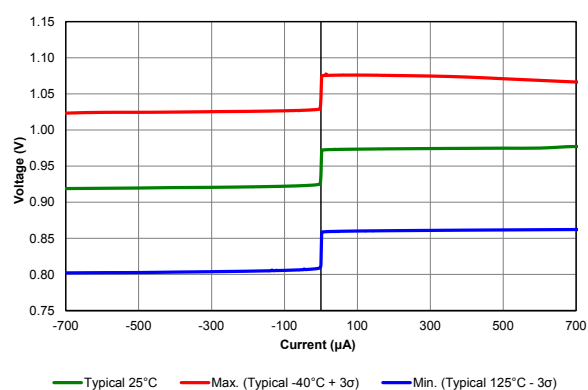
40.21 Weak Pull-Up Graphs

Figure 40-84. Weak Pull-Up Current



40.22 Zero-Cross Detection Graphs

Figure 40-85. ZCD Behavior, $V_{DD} = 5.5V$



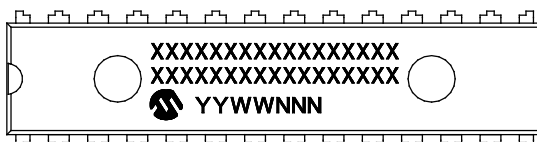
41. Packaging Information

Package Marking Information

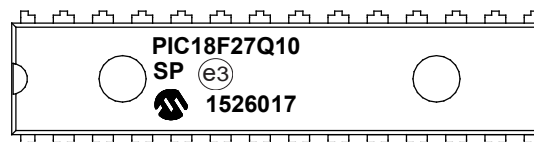
| | | |
|----------------|--------|--|
| Legend: | XX...X | Customer-specific information or Microchip part number |
| | Y | Year code (last digit of calendar year) |
| | YY | Year code (last 2 digits of calendar year) |
| | WW | Week code (week of January 1 is week '01') |
| | NNN | Alphanumeric traceability code |
| | (e3) | Pb-free JEDEC® designator for Matte Tin (Sn) |

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

28-Lead SPDIP (.300")

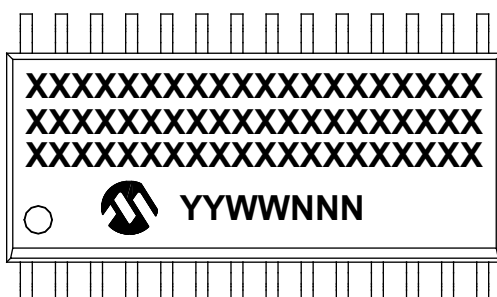


Example

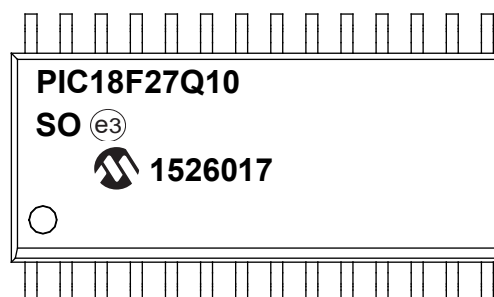


Rev. 30-009028A
5/17/2017

28-Lead SOIC (7.50 mm)

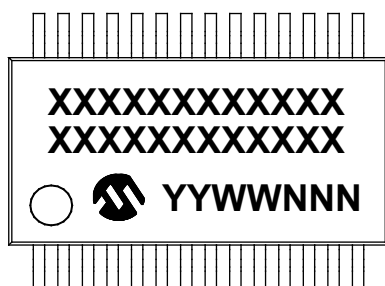


Example

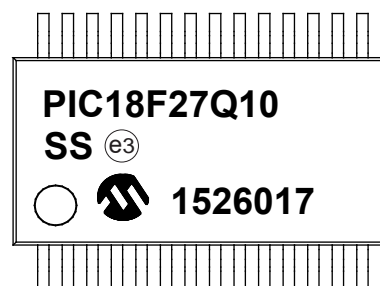


Rev. 30-009028B
5/17/2017

28-Lead SSOP (5.30 mm)

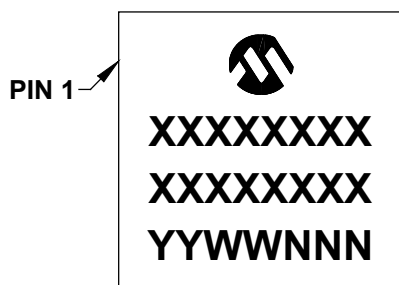


Example

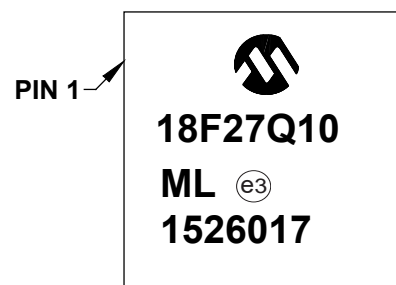


Rev. 30-000028D
9/17/2017

28-Lead QFN (6x6 mm)

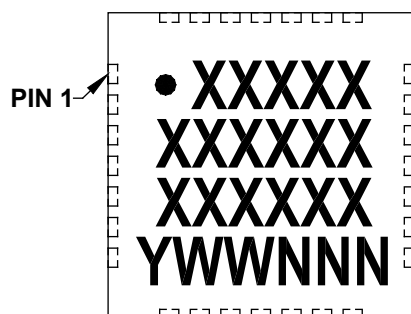


Example

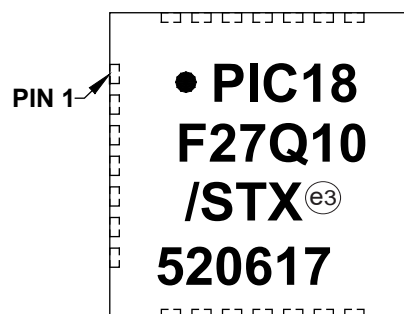


Rev. 30-000028F
4/2/2018

28-Lead VQFN (4x4x1 mm)

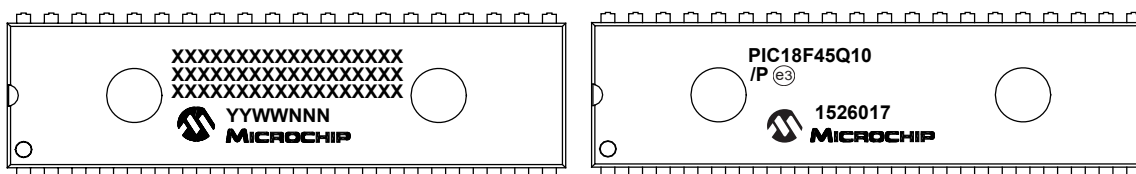


Example



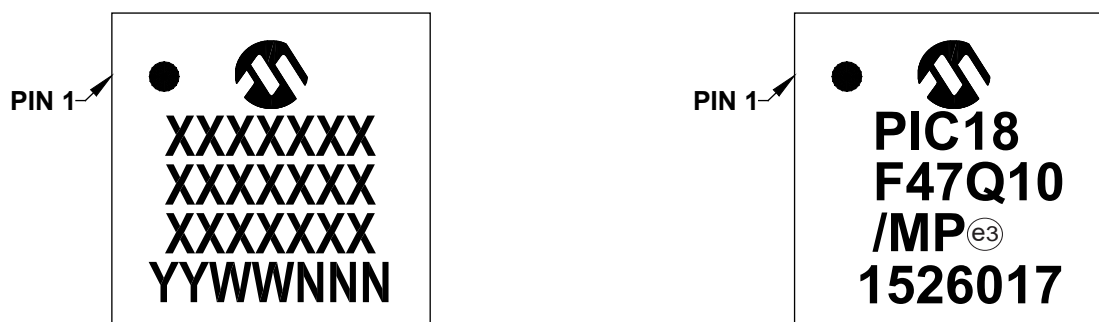
40-Lead PDIP (600 mil)

Example



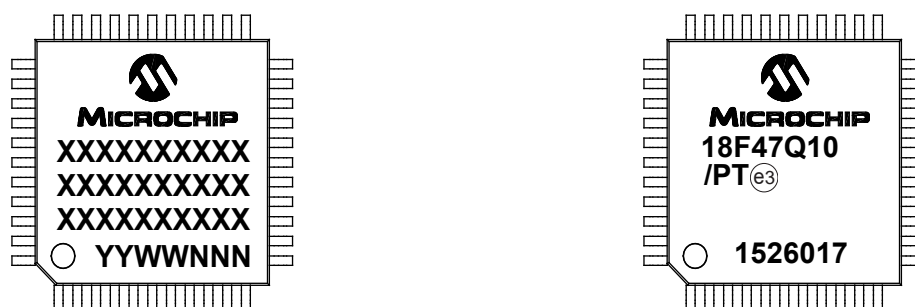
40-Lead QFN (5x5x0.9 mm)

Example



44-Lead TQFP (10x10x1 mm)

Example

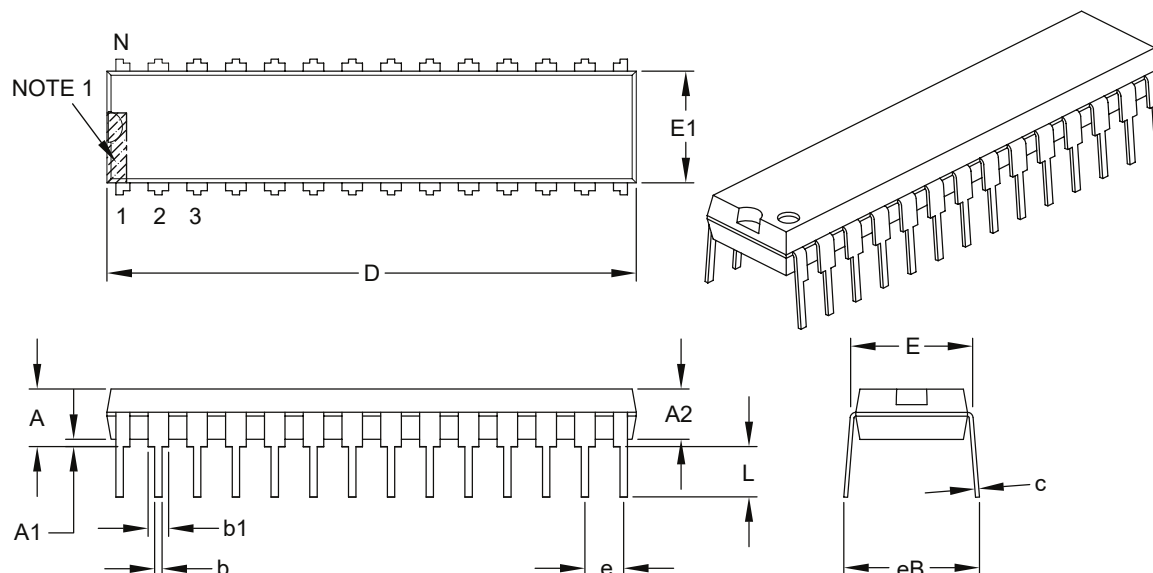


41.1 Package Details

The following sections give the technical details of the packages.

28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| | | Units | INCHES | | |
|----------------------------|----|-------|----------|-------|-------|
| Dimension Limits | | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | | |
| Pitch | e | | .100 BSC | | |
| Top to Seating Plane | A | | – | – | .200 |
| Molded Package Thickness | A2 | | .120 | .135 | .150 |
| Base to Seating Plane | A1 | | .015 | – | – |
| Shoulder to Shoulder Width | E | | .290 | .310 | .335 |
| Molded Package Width | E1 | | .240 | .285 | .295 |
| Overall Length | D | | 1.345 | 1.365 | 1.400 |
| Tip to Seating Plane | L | | .110 | .130 | .150 |
| Lead Thickness | c | | .008 | .010 | .015 |
| Upper Lead Width | b1 | | .040 | .050 | .070 |
| Lower Lead Width | b | | .014 | .018 | .022 |
| Overall Row Spacing § | eB | | – | – | .430 |

Notes:

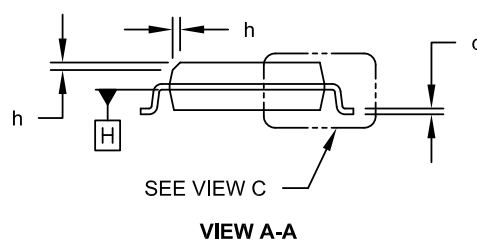
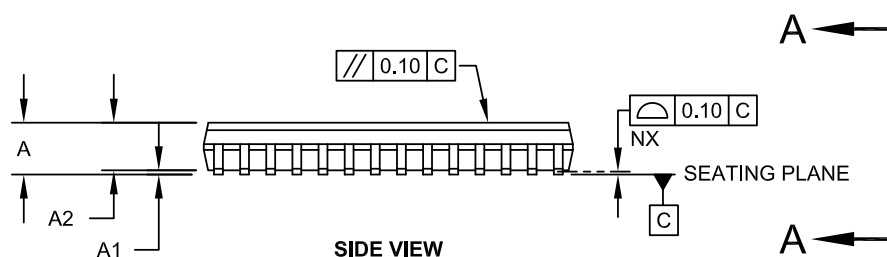
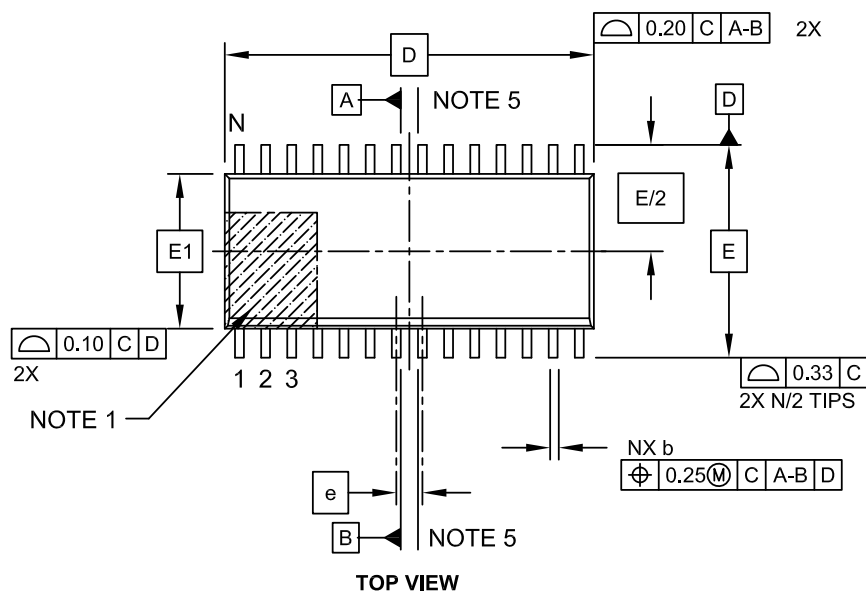
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

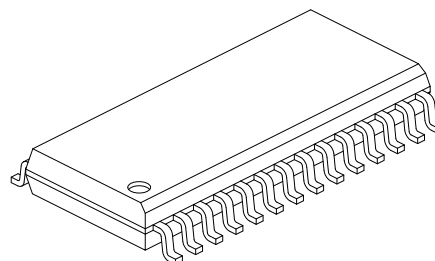
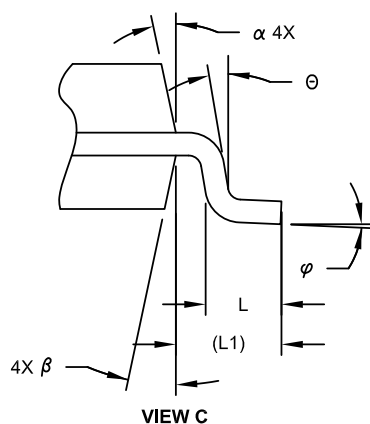
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-052C Sheet 1 of 2

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Units | | MILLIMETERS | | |
|--------------------------|----|-------------|-----|------|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | 28 | | |
| Pitch | e | 1.27 BSC | | |
| Overall Height | A | - | - | 2.65 |
| Molded Package Thickness | A2 | 2.05 | - | - |
| Standoff § | A1 | 0.10 | - | 0.30 |
| Overall Width | E | 10.30 BSC | | |
| Molded Package Width | E1 | 7.50 BSC | | |
| Overall Length | D | 17.90 BSC | | |
| Chamfer (Optional) | h | 0.25 | - | 0.75 |
| Foot Length | L | 0.40 | - | 1.27 |
| Footprint | L1 | 1.40 REF | | |
| Lead Angle | θ | 0° | - | - |
| Foot Angle | φ | 0° | - | 8° |
| Lead Thickness | c | 0.18 | - | 0.33 |
| Lead Width | b | 0.31 | - | 0.51 |
| Mold Draft Angle Top | α | 5° | - | 15° |
| Mold Draft Angle Bottom | β | 5° | - | 15° |

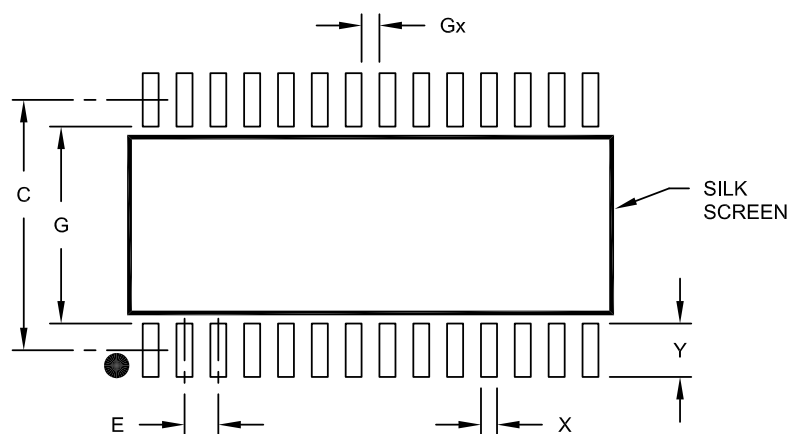
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.
- Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|--------------------------|----|-------------|------|------|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 1.27 BSC | | |
| Contact Pad Spacing | C | | 9.40 | |
| Contact Pad Width (X28) | X | | | 0.60 |
| Contact Pad Length (X28) | Y | | | 2.00 |
| Distance Between Pads | Gx | 0.67 | | |
| Distance Between Pads | G | 7.40 | | |

Notes:

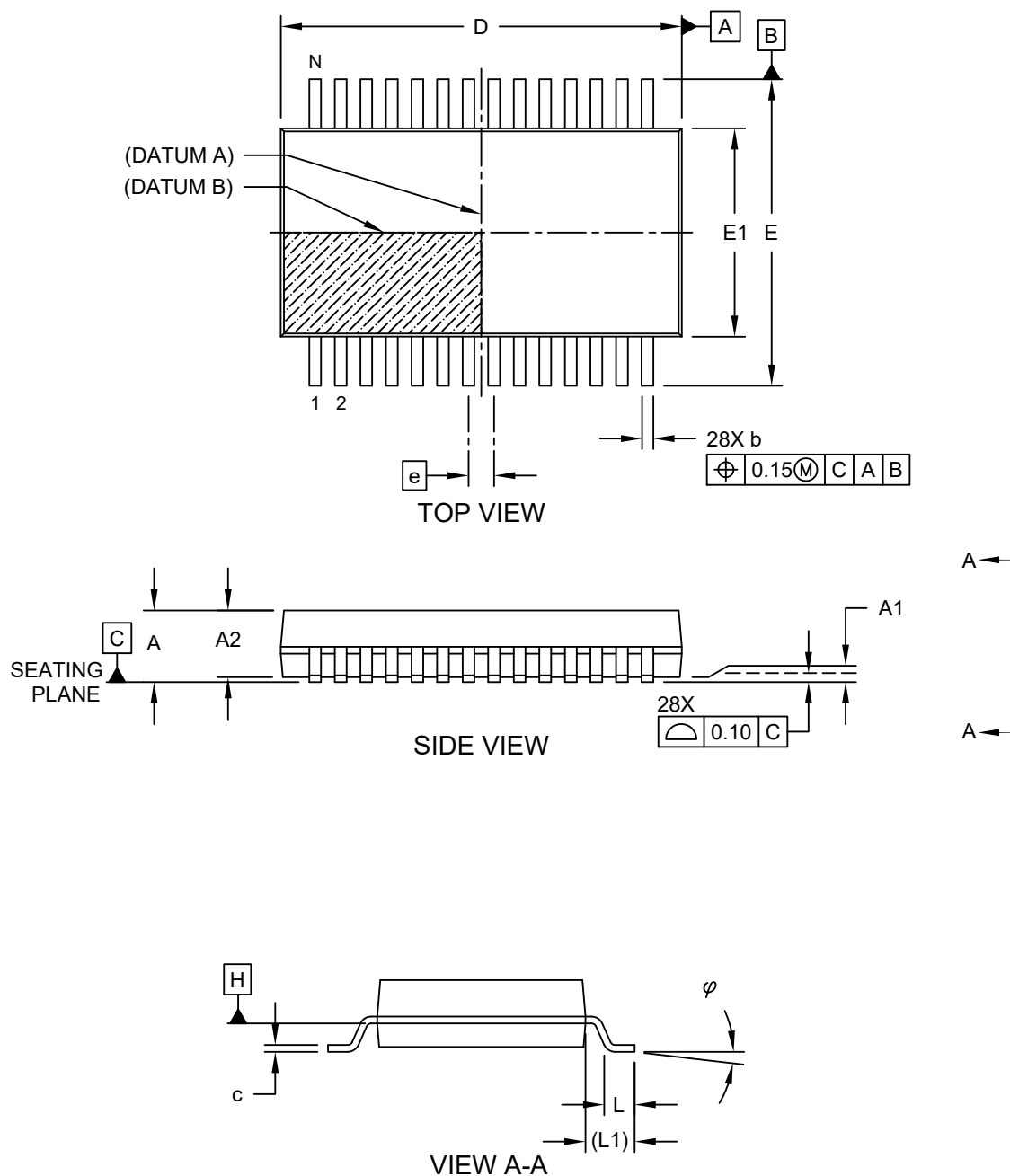
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A

28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

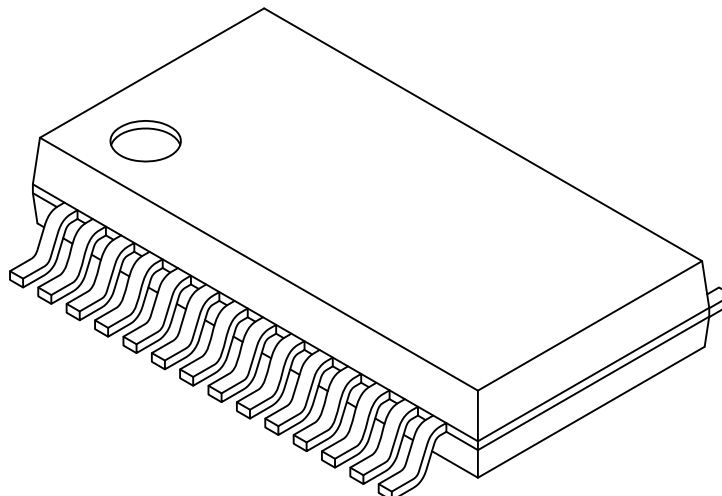
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-073 Rev C Sheet 1 of 2

28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Units | | MILLIMETERS | | |
|--------------------------|----|-------------|-------|-------|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | 28 | | |
| Pitch | e | 0.65 BSC | | |
| Overall Height | A | - | - | 2.00 |
| Molded Package Thickness | A2 | 1.65 | 1.75 | 1.85 |
| Standoff | A1 | 0.05 | - | - |
| Overall Width | E | 7.40 | 7.80 | 8.20 |
| Molded Package Width | E1 | 5.00 | 5.30 | 5.60 |
| Overall Length | D | 9.90 | 10.20 | 10.50 |
| Foot Length | L | 0.55 | 0.75 | 0.95 |
| Footprint | L1 | 1.25 REF | | |
| Lead Thickness | c | 0.09 | - | 0.25 |
| Foot Angle | φ | 0° | 4° | 8° |
| Lead Width | b | 0.22 | - | 0.38 |

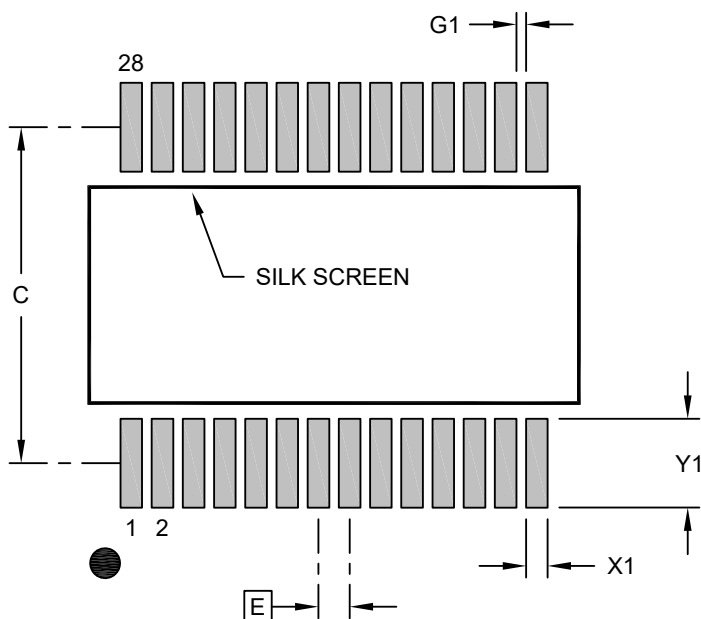
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-073 Rev C Sheet 2 of 2

28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---------------------------------|----|-------------|------|------|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 0.65 BSC | | |
| Contact Pad Spacing | C | | 7.00 | |
| Contact Pad Width (X28) | X1 | | | 0.45 |
| Contact Pad Length (X28) | Y1 | | | 1.85 |
| Contact Pad to Center Pad (X26) | G1 | 0.20 | | |

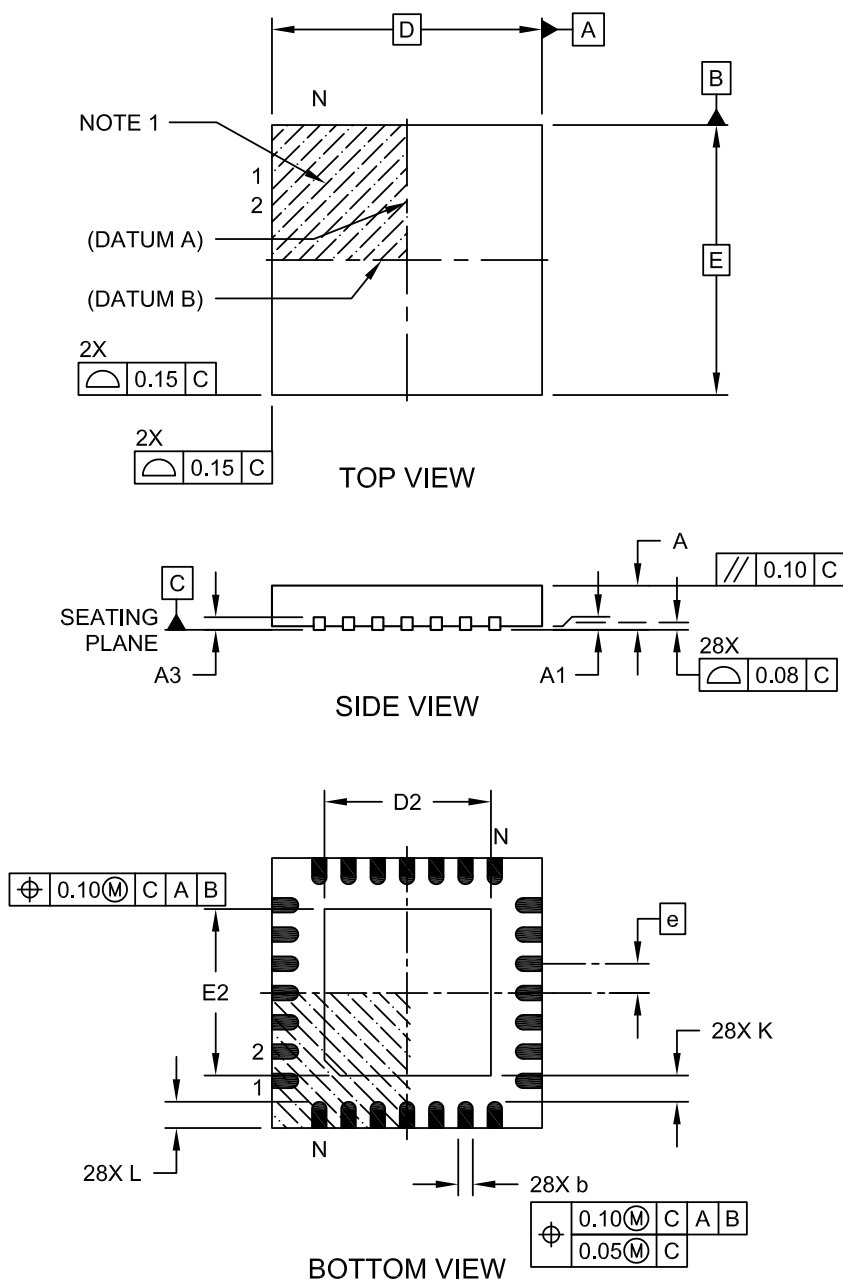
Notes:

- Dimensioning and tolerancing per ASME Y14.5M
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2073 Rev B

28-Lead Plastic Quad Flat, No Lead Package (ML) - 6x6 mm Body [QFN] **With 0.55 mm Terminal Length**

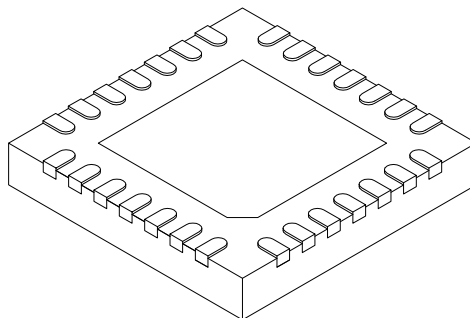
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-105C Sheet 1 of 2

28-Lead Plastic Quad Flat, No Lead Package (ML) - 6x6 mm Body [QFN] With 0.55 mm Terminal Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension | Units | MILLIMETERS | | |
|-------------------------|--------|-------------|------|------|
| | Limits | MIN | NOM | MAX |
| Number of Pins | N | 28 | | |
| Pitch | e | 0.65 BSC | | |
| Overall Height | A | 0.80 | 0.90 | 1.00 |
| Standoff | A1 | 0.00 | 0.02 | 0.05 |
| Terminal Thickness | A3 | 0.20 REF | | |
| Overall Width | E | 6.00 BSC | | |
| Exposed Pad Width | E2 | 3.65 | 3.70 | 4.20 |
| Overall Length | D | 6.00 BSC | | |
| Exposed Pad Length | D2 | 3.65 | 3.70 | 4.20 |
| Terminal Width | b | 0.23 | 0.30 | 0.35 |
| Terminal Length | L | 0.50 | 0.55 | 0.70 |
| Terminal-to-Exposed Pad | K | 0.20 | - | - |

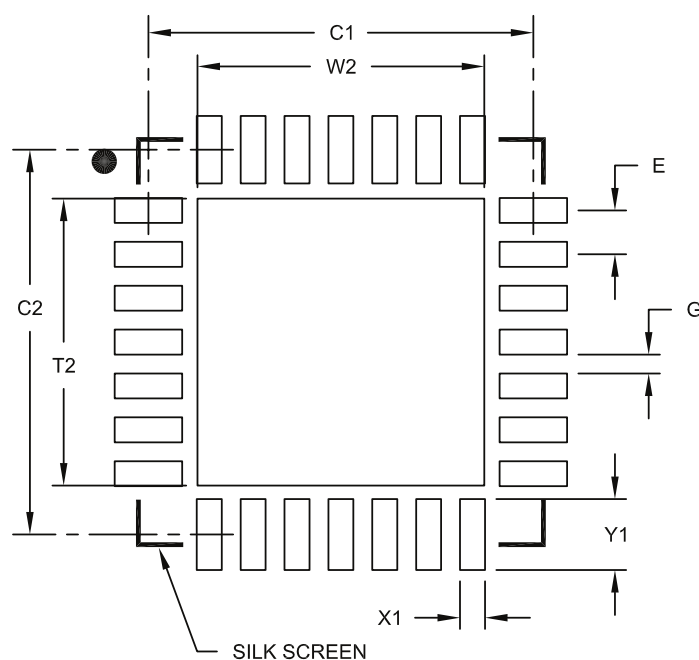
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated
- Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105C Sheet 2 of 2

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| | | Units | MILLIMETERS | | |
|----------------------------|----|-------|-------------|----------|------|
| Dimension Limits | | | MIN | NOM | MAX |
| Contact Pitch | E | | | 0.65 BSC | |
| Optional Center Pad Width | W2 | | | | 4.25 |
| Optional Center Pad Length | T2 | | | | 4.25 |
| Contact Pad Spacing | C1 | | | 5.70 | |
| Contact Pad Spacing | C2 | | | 5.70 | |
| Contact Pad Width (X28) | X1 | | | | 0.37 |
| Contact Pad Length (X28) | Y1 | | | | 1.00 |
| Distance Between Pads | G | | 0.20 | | |

Notes:

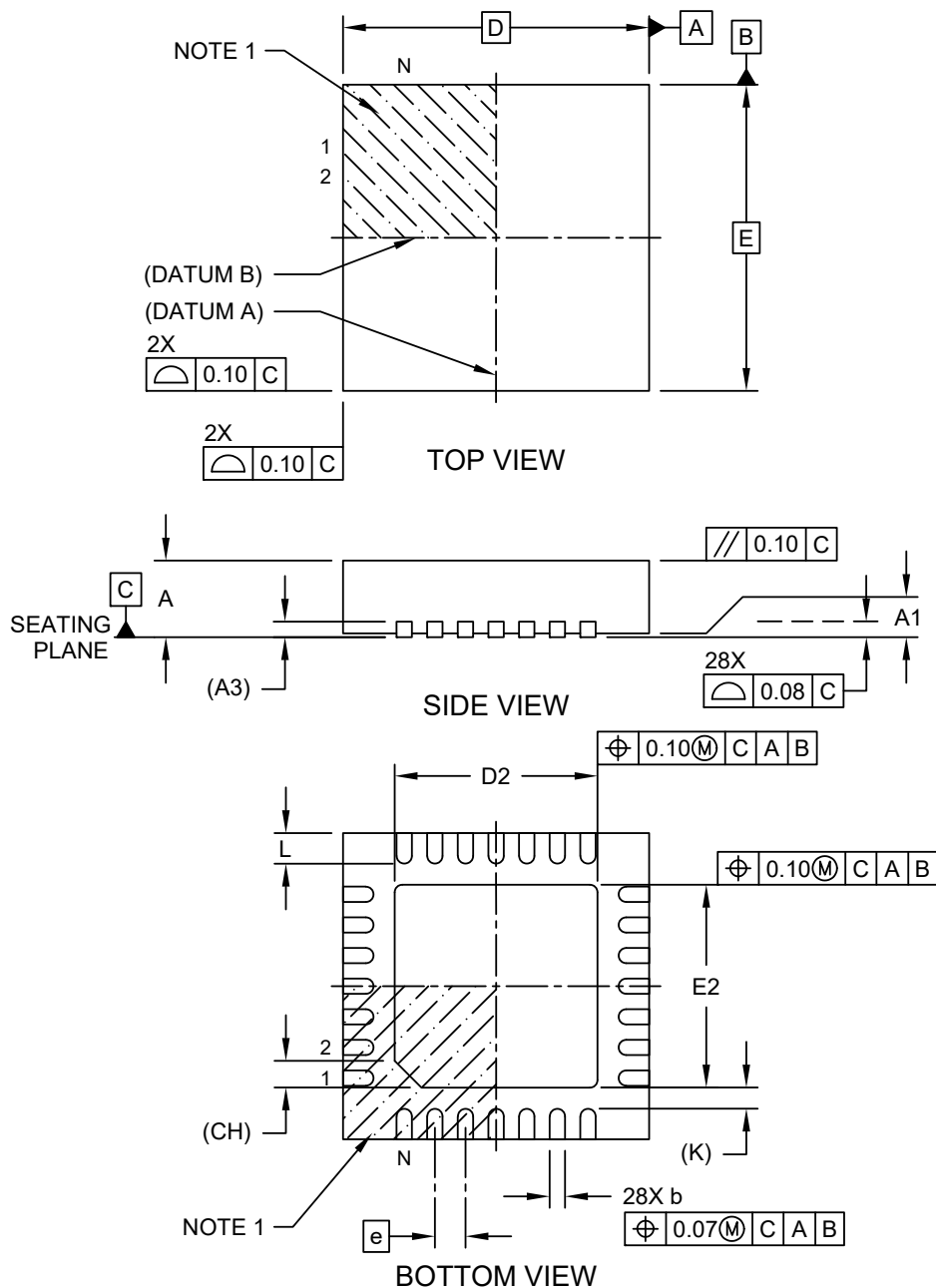
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

**28-Lead Very Thin Plastic Quad Flat, No Lead (STX) - 4x4x1.0 mm Body [VQFN]
With 2.65x2.65 mm Exposed Pad**

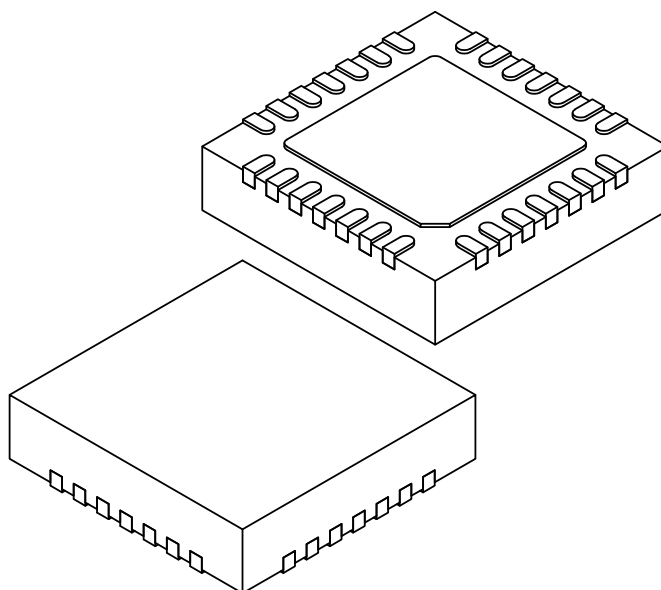
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-456 Rev C Sheet 1 of 2

28-Lead Very Thin Plastic Quad Flat, No Lead (STX) - 4x4x1.0 mm Body [VQFN] With 2.65x2.65 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Units | | MILLIMETERS | | |
|----------------------------|----|-------------|------|------|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Terminals | N | 28 | | |
| Pitch | e | 0.40 BSC | | |
| Overall Height | A | 0.80 | 0.90 | 1.00 |
| Standoff | A1 | 0.00 | 0.02 | 0.05 |
| Terminal Thickness | A3 | 0.203 REF | | |
| Overall Length | D | 4.00 BSC | | |
| Exposed Pad Length | D2 | 2.55 | 2.65 | 2.75 |
| Overall Width | E | 4.00 BSC | | |
| Exposed Pad Width | E2 | 2.55 | 2.65 | 2.75 |
| Exposed Pad Corner Chamfer | CH | 0.35 REF | | |
| Terminal Width | b | 0.15 | 0.20 | 0.25 |
| Terminal Length | L | 0.30 | 0.40 | 0.50 |
| Terminal-to-Exposed-Pad | K | 0.275 REF | | |

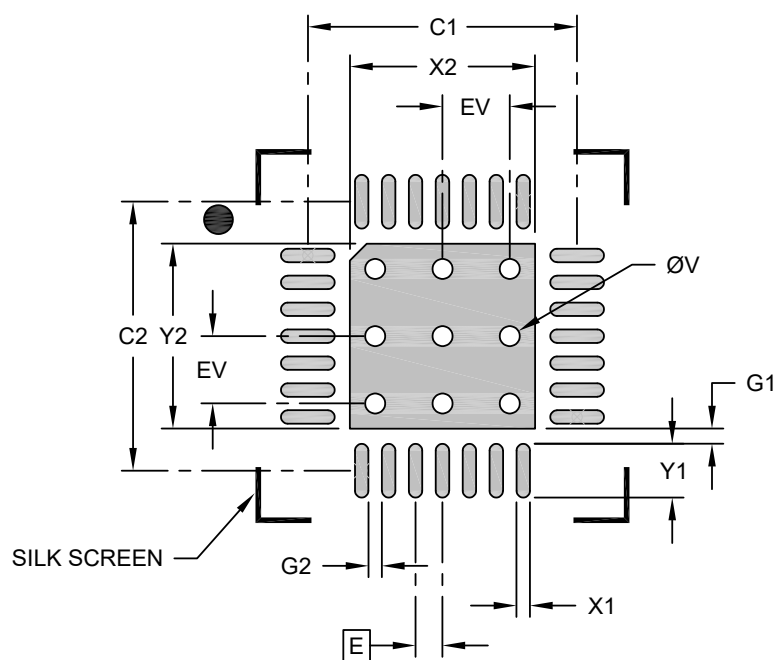
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-456 Rev C Sheet 2 of 2

28-Lead Very Thin Plastic Quad Flat, No Lead (STX) - 4x4x1.0 mm Body [VQFN] With 2.65x2.65 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|----------------------------------|----|-------------|------|------|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 0.40 BSC | | |
| Optional Center Pad Width | X2 | | | 2.75 |
| Optional Center Pad Length | Y2 | | | 2.75 |
| Contact Pad Spacing | C1 | | 4.00 | |
| Contact Pad Spacing | C2 | | 4.00 | |
| Contact Pad Width (X28) | X1 | | | 0.20 |
| Contact Pad Length (X28) | Y1 | | | 0.80 |
| Contact Pad to Center Pad (X28) | G1 | 0.23 | | |
| Contact Pad to Contact Pad (X24) | G2 | 0.20 | | |
| Thermal Via Diameter | V | | 0.30 | |
| Thermal Via Pitch | EV | | 1.00 | |

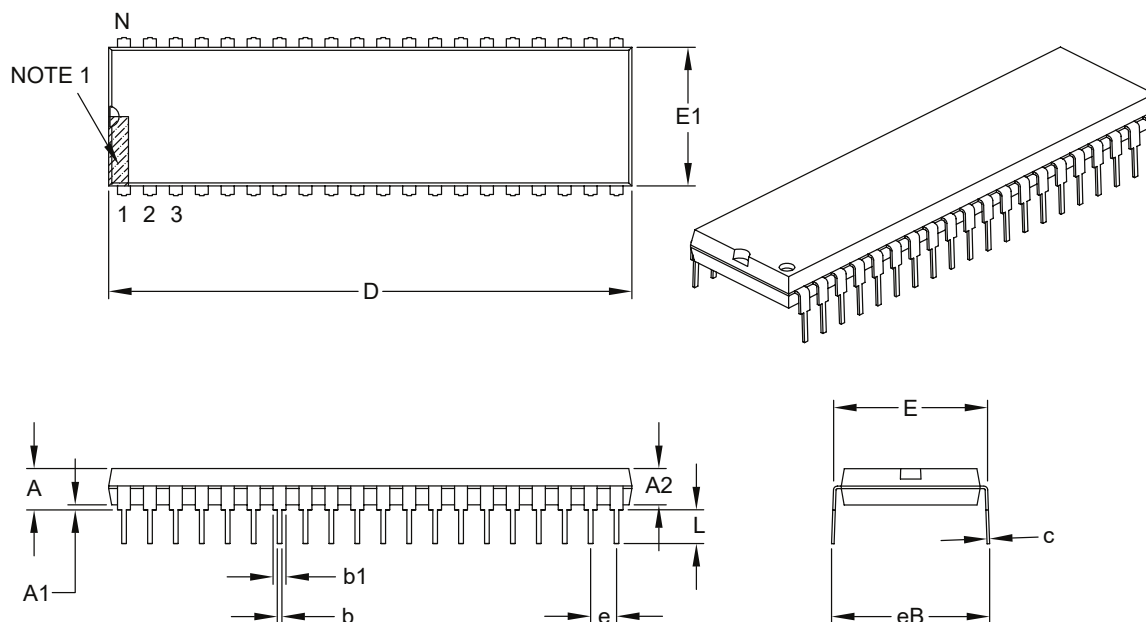
Notes:

- Dimensioning and tolerancing per ASME Y14.5M
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2456 Rev C

40-Lead Plastic Dual In-Line (P) – 600 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Units | | INCHES | | |
|----------------------------|----|----------|-----|-------|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | 40 | | |
| Pitch | e | .100 BSC | | |
| Top to Seating Plane | A | – | – | .250 |
| Molded Package Thickness | A2 | .125 | – | .195 |
| Base to Seating Plane | A1 | .015 | – | – |
| Shoulder to Shoulder Width | E | .590 | – | .625 |
| Molded Package Width | E1 | .485 | – | .580 |
| Overall Length | D | 1.980 | – | 2.095 |
| Tip to Seating Plane | L | .115 | – | .200 |
| Lead Thickness | c | .008 | – | .015 |
| Upper Lead Width | b1 | .030 | – | .070 |
| Lower Lead Width | b | .014 | – | .023 |
| Overall Row Spacing § | eB | – | – | .700 |

Notes:

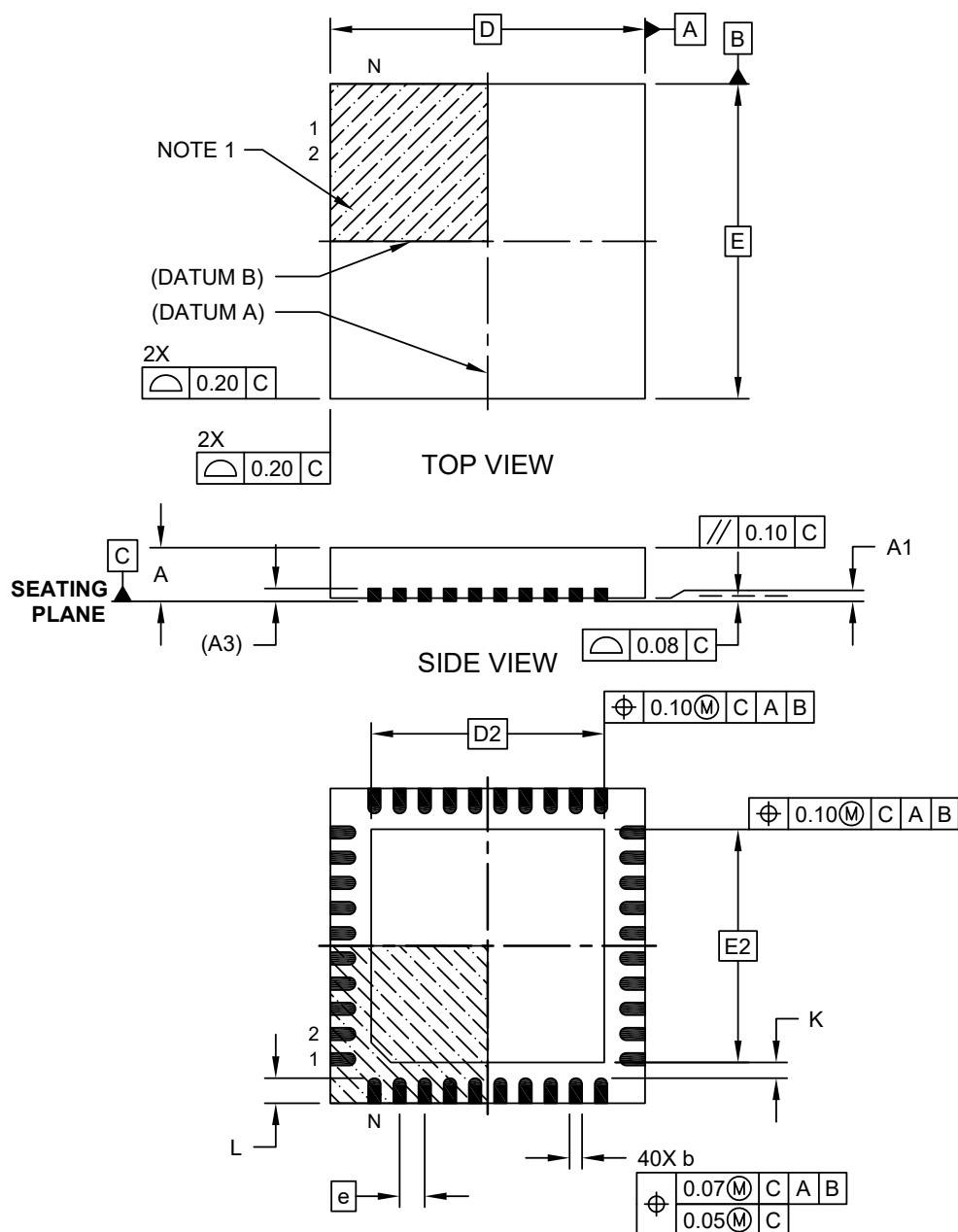
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-016B

**40-Lead Plastic Quad Flat, No Lead Package (MP) - 5x5 mm Body [QFN]
With 3.7x3.7 mm Exposed Pad**

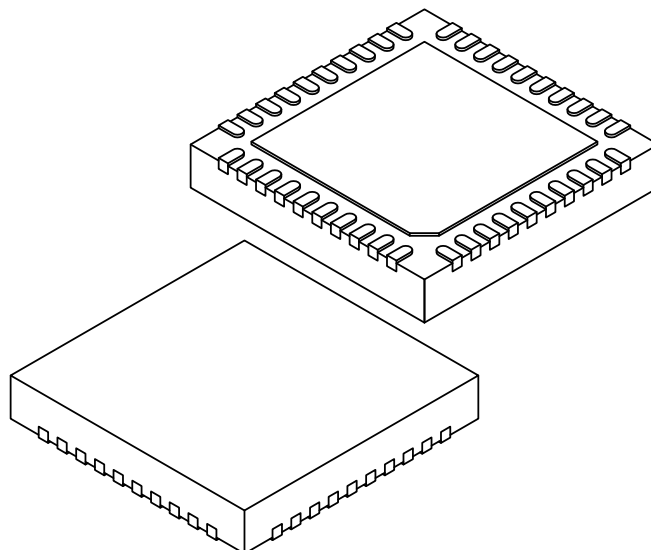
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-047-002A Sheet 1 of 2

40-Lead Plastic Quad Flat, No Lead Package (MP) - 5x5 mm Body [QFN] With 3.7x3.7 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| | | Units | MILLIMETERS | | |
|-------------------------|----|-------|-------------|------|------|
| Dimension Limits | | | MIN | NOM | MAX |
| Number of Terminals | N | | 40 | | |
| Pitch | e | | 0.40 BSC | | |
| Overall Height | A | | 0.80 | 0.85 | 0.90 |
| Standoff | A1 | | 0.00 | 0.02 | 0.05 |
| Terminal Thickness | A3 | | 0.20 REF | | |
| Overall Width | E | | 5.00 BSC | | |
| Exposed Pad Width | E2 | | 3.70 BSC | | |
| Overall Length | D | | 5.00 BSC | | |
| Exposed Pad Length | D2 | | 3.70 BSC | | |
| Terminal Width | b | | 0.15 | 0.20 | 0.25 |
| Terminal Length | L | | 0.30 | 0.40 | 0.50 |
| Terminal-to-Exposed-Pad | K | | 0.20 | - | - |

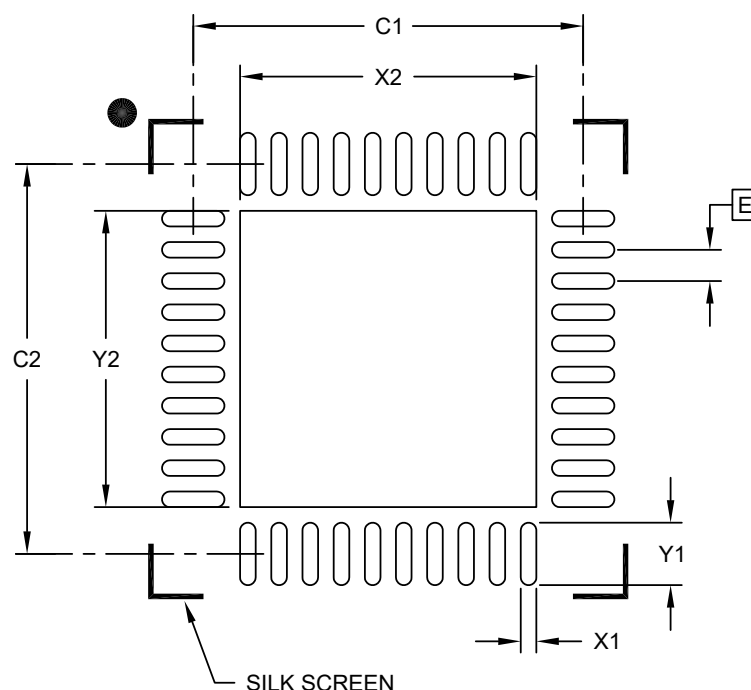
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-047-002A Sheet 2 of 2

40-Lead Plastic Quad Flat, No Lead Package (MP) - 5x5 mm Body [QFN] With 3.7x3.7 mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Dimension Limits | Units | MILLIMETERS | | |
|----------------------------|-------|-------------|------|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | 0.40 BSC | | |
| Optional Center Pad Width | X2 | | | 3.80 |
| Optional Center Pad Length | Y2 | | | 3.80 |
| Contact Pad Spacing | C1 | | 5.00 | |
| Contact Pad Spacing | C2 | | 5.00 | |
| Contact Pad Width (X40) | X1 | | | 0.20 |
| Contact Pad Length (X40) | Y1 | | | 0.80 |

Notes:

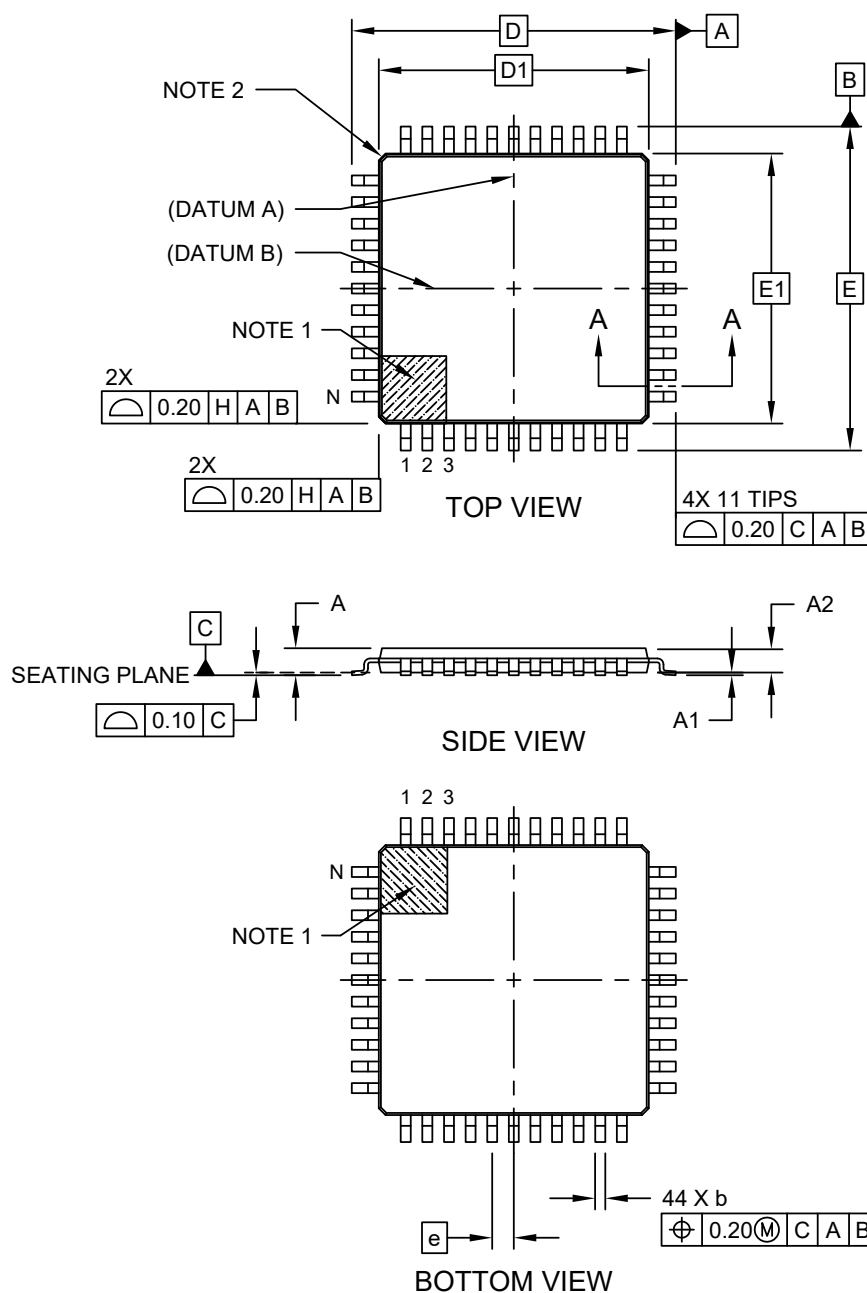
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2047-002A

44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

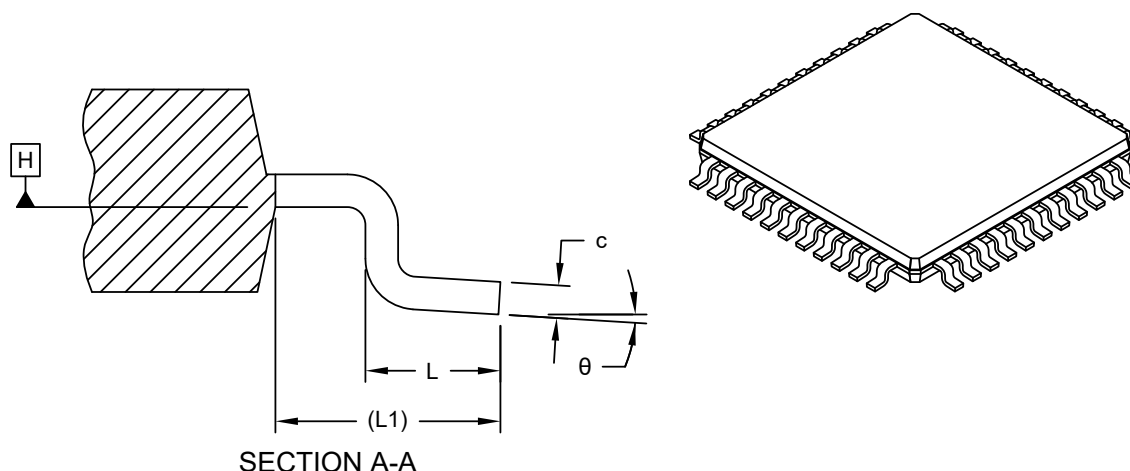
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-076C Sheet 1 of 2

44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension Limits | Units | MILLIMETERS | | |
|--------------------------|-------|-------------|------|------|
| | | MIN | NOM | MAX |
| Number of Leads | N | 44 | | |
| Lead Pitch | e | 0.80 BSC | | |
| Overall Height | A | - | - | 1.20 |
| Standoff | A1 | 0.05 | - | 0.15 |
| Molded Package Thickness | A2 | 0.95 | 1.00 | 1.05 |
| Overall Width | E | 12.00 BSC | | |
| Molded Package Width | E1 | 10.00 BSC | | |
| Overall Length | D | 12.00 BSC | | |
| Molded Package Length | D1 | 10.00 BSC | | |
| Lead Width | b | 0.30 | 0.37 | 0.45 |
| Lead Thickness | c | 0.09 | - | 0.20 |
| Lead Length | L | 0.45 | 0.60 | 0.75 |
| Footprint | L1 | 1.00 REF | | |
| Foot Angle | θ | 0° | 3.5° | 7° |

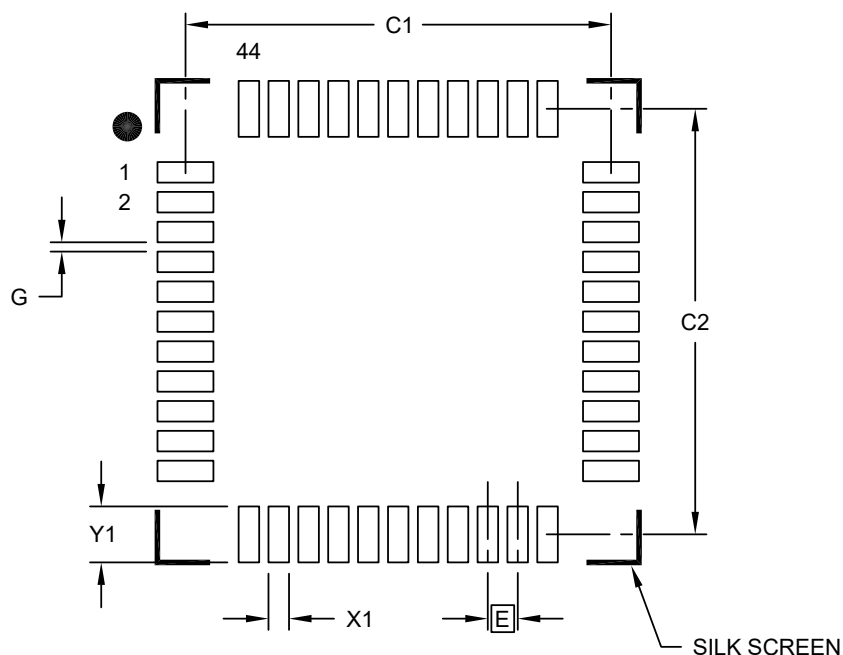
Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Exact shape of each corner is optional.
- Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-076C Sheet 2 of 2

44-Lead Plastic Thin Quad Flatpack (PT) - 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Dimension Limits | Units | MILLIMETERS | | |
|--------------------------|-------|-------------|----------|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | | 0.80 BSC | |
| Contact Pad Spacing | C1 | | 11.40 | |
| Contact Pad Spacing | C2 | | 11.40 | |
| Contact Pad Width (X44) | X1 | | | 0.55 |
| Contact Pad Length (X44) | Y1 | | | 1.50 |
| Distance Between Pads | G | 0.25 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B

42. Appendix A: Revision History

| Doc Rev. | Date | Comments |
|----------|---------|---|
| F | 09/2024 | Update reset values for IPR0, IPR3, IPR5, IPR6, OSCCON3, TMR0H and BAUDxCON |
| E | 11/2020 | Updated figures: 40-8, 40-9, 40-10, 40-41 Removed figure 40-61 |
| D | 09/2019 | Updated AC/DC Graphs; Tables 39-3, 39-8, 39-14; Figure 39-2; Section 40 |
| C | 05/2019 | Removed 44-pin QFN packages Corrected Tables 1, 2, 39-3, 39-5, 39-6, 39-8, 39-13, 39-15, and 39-18; Corrected Figures 39-9 and 39-10 |
| B | 11/2018 | Corrected capitalization and hyphens Changes to: Sections 14.12.7, 22.3.2 (note), 22.6.1 (note), 24.11.1, 25.11.1.3, 26, 26.4.5 (note1), 33.1.2 (note) Figures 1, 25-3 through 25-11, 25-14, 25-15 Tables 2, 39-4, 39-6 Trademarks |
| A | 03/2018 | Initial document release |

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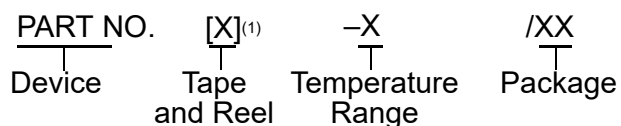
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| | | |
|---------------------|---------------------------------------|-------------------------------|
| Device: | PIC18F26Q10, PIC18F45Q10, PIC18F46Q10 | |
| Tape & Reel Option: | Blank | = Tube |
| | T | = Tape & Reel |
| Temperature Range: | I | = -40°C to +85°C (Industrial) |
| | E | = -40°C to +125°C (Extended) |
| Package: | STX | = 28-lead VQFN 4x4x1 mm |
| | ML | = 28-lead QFN 6x6x0.9 mm |
| | SO | = 28-lead SOIC |
| | SP | = 28-lead Skinny Plastic DIP |
| | SS | = 28-lead SSOP |
| | P | = 40-lead PDIP |
| | MP | = 40-lead QFN 5x5x0.9 mm |
| | PT | = 44-lead TQFP |

Examples:

- PIC18F26Q10-E/P 301: Extended temp., PDIP package, QTP pattern #301.
- PIC18F45Q10-E/PT = Extended temp., TQFP package.
- PIC18F46Q10T-I/MP = Tape and reel, Industrial temp., QFN package.

Notes:

1. Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.
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