

## 28/44-Pin General Purpose, 16-Bit Flash Microcontrollers

### High-Performance CPU

- Modified Harvard Architecture
- Up to 16 MIPS Operation @ 32 MHz
- 8 MHz Internal Oscillator with 4x PLL Option and Multiple Divide Options
- 17-Bit by 17-Bit Single-Cycle Hardware Multiplier
- 32-Bit by 16-Bit Hardware Divider
- 16-Bit x 16-Bit Working Register Array
- C Compiler Optimized Instruction Set Architecture:
  - 76 base instructions
  - Flexible addressing modes
- Two Address Generation Units (AGUs) for Separate Read and Write Addressing of Data Memory

### Special Microcontroller Features

- Operating Voltage Range of 2.0V to 3.6V
- 5.5V Tolerant Input (digital pins only)
- High-Current Sink/Source (18 mA/18 mA) on All I/O Pins
- Flash Program Memory:
  - 10,000 erase/write
  - 20-year data retention minimum
- Power Management modes:
  - Sleep, Idle, Doze and Alternate Clock modes
  - Operating current: 650  $\mu$ A/MIPS, typical at 2.0V
  - Sleep current: 150 nA, typical at 2.0V
- Fail-Safe Clock Monitor (FSCM) Operation:
  - Detects clock failure and switches to on-chip, low-power RC oscillator
- On-Chip, 2.5V Regulator with Tracking mode
- Power-on Reset (POR), Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Flexible Watchdog Timer (WDT) with On-Chip, Low-Power RC Oscillator for Reliable Operation
- In-Circuit Serial Programming™ (ICSP™) and In-Circuit Debug (ICD) via 2 Pins
- JTAG Boundary Scan Support

### Analog Features

- 10-Bit, up to 13-Channel Analog-to-Digital Converter:
  - 500 ksp/s conversion rate
  - Conversion available during Sleep and Idle
- Dual Analog Comparators with Programmable Input/Output Configuration

### Peripheral Features

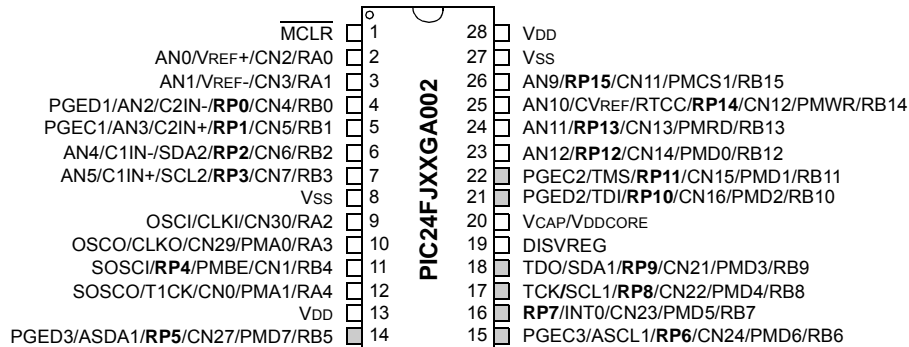
- Peripheral Pin Select (PPS):
  - Allows independent I/O mapping of many peripherals
  - Up to 26 available pins (44-pin devices)
  - Continuous hardware integrity checking and safety interlocks prevent unintentional configuration changes
- 8-Bit Parallel Master/Slave Port (PMP/PSP):
  - Up to 16-bit multiplexed addressing, with up to 11 dedicated address pins on 44-pin devices
  - Programmable polarity on control lines
- Hardware Real-Time Clock/Calendar (RTCC):
  - Provides clock, calendar and alarm functions
- Programmable Cyclic Redundancy Check (CRC)
- Two 3-Wire/4-Wire SPI modules (support 4 Frame modes) with 8-Level FIFO Buffer
- Two I<sup>2</sup>C™ modules Support Multi-Master/Slave mode and 7-Bit/10-Bit Addressing
- Two UART modules:
  - Supports RS-485, RS-232, and LIN/J2602
  - On-chip hardware encoder/decoder for IrDA®
  - Auto-wake-up on Start bit
  - Auto-Baud Detect
  - 4-level deep FIFO buffer
- Five 16-Bit Timers/Counters with Programmable Prescaler
- Five 16-Bit Capture Inputs
- Five 16-Bit Compare/PWM Outputs
- Configurable Open-Drain Outputs on Digital I/O Pins
- Up to 3 External Interrupt Sources

Device	Pins	Program Memory (bytes)	SRAM (bytes)	Remappable Peripherals						I <sup>2</sup> C™	10-Bit A/D (ch)	Comparators	PMP/PSP	JTAG
				Remappable Pins	Timers 16-Bit	Capture Input	Compare/PWM Output	UART w/ IrDA®	SPI					
PIC24FJ16GA002	28	16K	4K	16	5	5	5	2	2	2	10	2	Y	Y
PIC24FJ32GA002	28	32K	8K	16	5	5	5	2	2	2	10	2	Y	Y
PIC24FJ48GA002	28	48K	8K	16	5	5	5	2	2	2	10	2	Y	Y
PIC24FJ64GA002	28	64K	8K	16	5	5	5	2	2	2	10	2	Y	Y
PIC24FJ16GA004	44	16K	4K	26	5	5	5	2	2	2	13	2	Y	Y
PIC24FJ32GA004	44	32K	8K	26	5	5	5	2	2	2	13	2	Y	Y
PIC24FJ48GA004	44	48K	8K	26	5	5	5	2	2	2	13	2	Y	Y
PIC24FJ64GA004	44	64K	8K	26	5	5	5	2	2	2	13	2	Y	Y

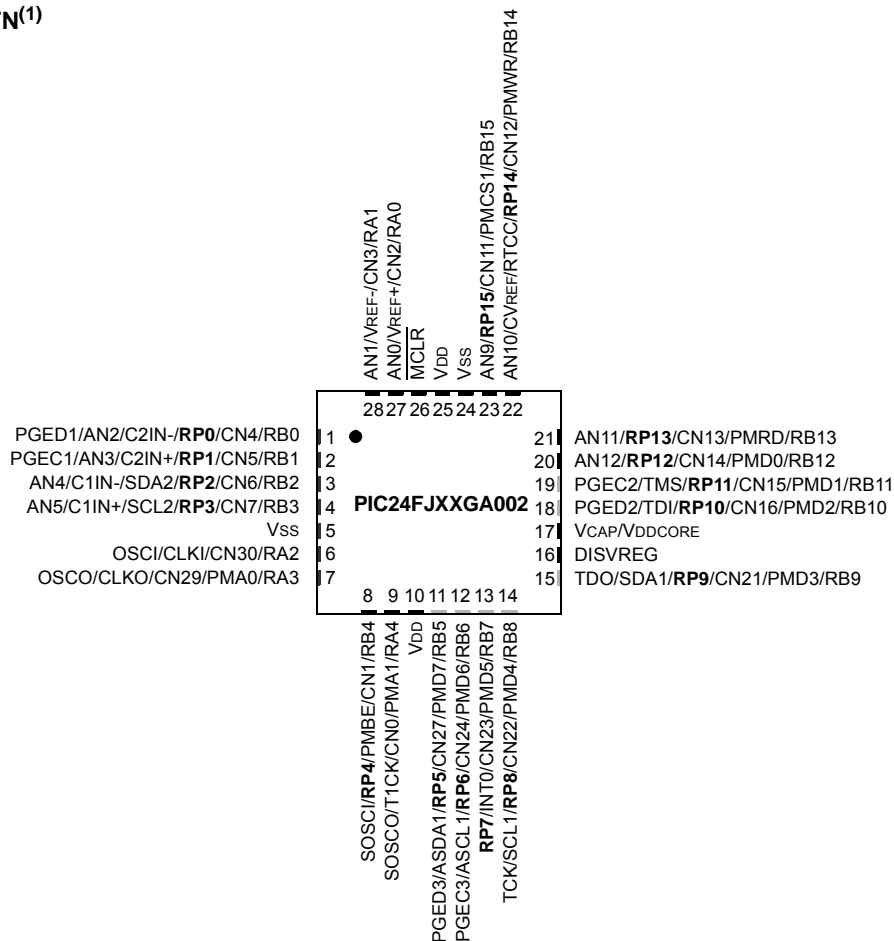
# PIC24FJ64GA004 FAMILY

## Pin Diagrams

### 28-Pin SPDIP, SSOP, SOIC



### 28-Pin QFN<sup>(1)</sup>



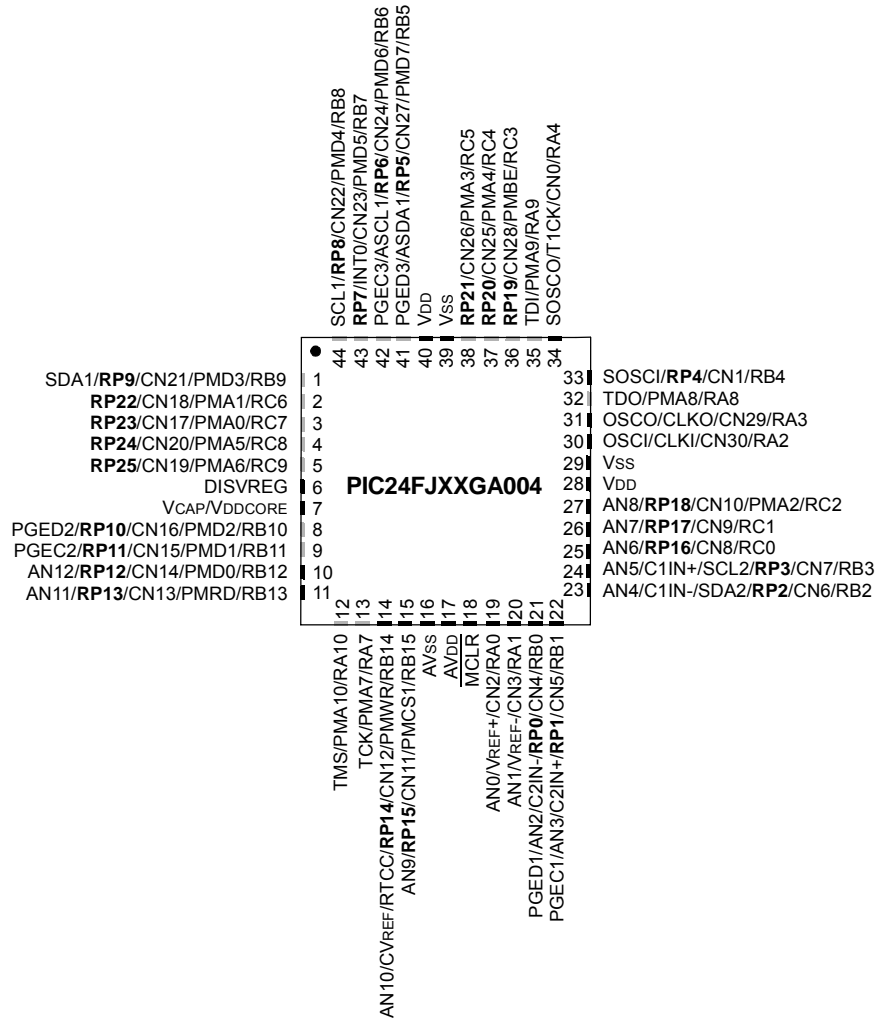
**Legend:** RPn represents remappable peripheral pins. Gray shading indicates 5.5V tolerant input pins.

**Note 1:** Back pad on QFN devices should be connected to Vss.

# PIC24FJ64GA004 FAMILY

## Pin Diagrams (Continued)

### 44-Pin QFN<sup>(1)</sup>



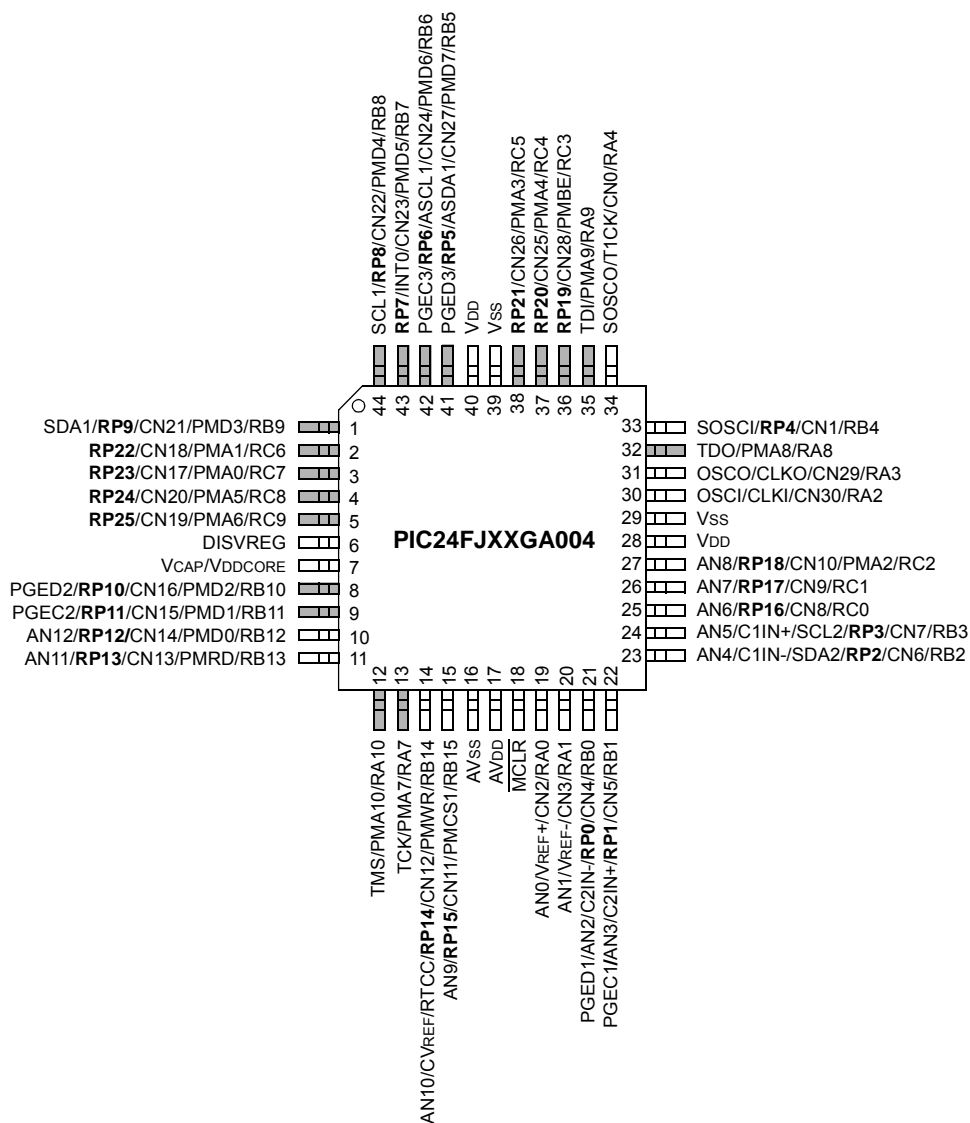
**Legend:** **RPn** represents remappable peripheral pins. Gray shading indicates 5.5V tolerant input pins.

**Note 1:** Back pad on QFN devices should be connected to Vss.

# PIC24FJ64GA004 FAMILY

## Pin Diagrams (Continued)

44-Pin TQFP



**Legend:** RPN represents remappable peripheral pins. Gray shading indicates 5.5V tolerant input pins.

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# PIC24FJ64GA004 FAMILY

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## 1.0 DEVICE OVERVIEW

This document contains device-specific information for the following devices:

- PIC24FJ16GA002
- PIC24FJ32GA002
- PIC24FJ48GA002
- PIC24FJ64GA002
- PIC24FJ16GA004
- PIC24FJ32GA004
- PIC24FJ48GA004
- PIC24FJ64GA004

This family introduces a new line of Microchip devices: a 16-bit microcontroller family with a broad peripheral feature set and enhanced computational performance. The PIC24FJ64GA004 family offers a new migration option for those high-performance applications which may be outgrowing their 8-bit platforms, but don't require the numerical processing power of a digital signal processor.

### 1.1 Core Features

#### 1.1.1 16-BIT ARCHITECTURE

Central to all PIC24F devices is the 16-bit modified Harvard architecture, first introduced with Microchip's dsPIC® Digital Signal Controllers (DSCs). The PIC24F CPU core offers a wide range of enhancements, such as:

- 16-bit data and 24-bit address paths with the ability to move information between data and memory spaces
- Linear addressing of up to 12 Mbytes (program space) and 64 Kbytes (data)
- A 16-element working register array with built-in software stack support
- A 17 x 17 hardware multiplier with support for integer math
- Hardware support for 32 by 16-bit division
- An instruction set that supports multiple addressing modes and is optimized for high-level languages such as 'C'
- Operational performance up to 16 MIPS

#### 1.1.2 POWER-SAVING TECHNOLOGY

All of the devices in the PIC24FJ64GA004 family incorporate a range of features that can significantly reduce power consumption during operation. Key items include:

- **On-the-Fly Clock Switching:** The device clock can be changed under software control to the Timer1 source or the internal, low-power RC oscillator during operation, allowing the user to incorporate power-saving ideas into their software designs.
- **Doze Mode Operation:** When timing-sensitive applications, such as serial communications, require the uninterrupted operation of peripherals, the CPU clock speed can be selectively reduced, allowing incremental power savings without missing a beat.
- **Instruction-Based Power-Saving Modes:** The microcontroller can suspend all operations, or selectively shut down its core while leaving its peripherals active, with a single instruction in software.

#### 1.1.3 OSCILLATOR OPTIONS AND FEATURES

All of the devices in the PIC24FJ64GA004 family offer five different oscillator options, allowing users a range of choices in developing application hardware. These include:

- Two Crystal modes using crystals or ceramic resonators.
- Two External Clock modes offering the option of a divide-by-2 clock output.
- A Fast Internal Oscillator (FRC) with a nominal 8 MHz output, which can also be divided under software control to provide clock speeds as low as 31 kHz.
- A Phase Lock Loop (PLL) frequency multiplier, available to the External Oscillator modes and the FRC oscillator, which allows clock speeds of up to 32 MHz.
- A separate internal RC oscillator (LPRC) with a fixed 31 kHz output, which provides a low-power option for timing-insensitive applications.

The internal oscillator block also provides a stable reference source for the Fail-Safe Clock Monitor. This option constantly monitors the main clock source against a reference signal provided by the internal oscillator and enables the controller to switch to the internal oscillator, allowing for continued low-speed operation or a safe application shutdown.

# PIC24FJ64GA004 FAMILY

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## 1.1.4 EASY MIGRATION

Regardless of the memory size, all devices share the same rich set of peripherals, allowing for a smooth migration path as applications grow and evolve.

The consistent pinout scheme used throughout the entire family also aids in migrating to the next larger device. This is true when moving between devices with the same pin count, or even jumping from 28-pin to 44-pin devices.

The PIC24F family is pin-compatible with devices in the dsPIC33 family, and shares some compatibility with the pinout schema for PIC18 and dsPIC30. This extends the ability of applications to grow from the relatively simple, to the powerful and complex, yet still selecting a Microchip device.

## 1.2 Other Special Features

- **Communications:** The PIC24FJ64GA004 family incorporates a range of serial communication peripherals to handle a range of application requirements. There are two independent I<sup>2</sup>C modules that support both Master and Slave modes of operation. Devices also have, through the Peripheral Pin Select (PPS) feature, two independent UARTs with built-in IrDA encoder/decoders and two SPI modules.
- **Peripheral Pin Select (PPS):** The Peripheral Pin Select feature allows most digital peripherals to be mapped over a fixed set of digital I/O pins. Users may independently map the input and/or output of any one of the many digital peripherals to any one of the I/O pins.
- **Parallel Master/Enhanced Parallel Slave Port:** One of the general purpose I/O ports can be reconfigured for enhanced parallel data communications. In this mode, the port can be configured for both master and slave operations, and supports 8-bit and 16-bit data transfers with up to 16 external address lines in Master modes.
- **Real-Time Clock/Calendar (RTCC):** This module implements a full-featured clock and calendar with alarm functions in hardware, freeing up timer resources and program memory space for use of the core application.
- **10-Bit A/D Converter:** This module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period, as well as faster sampling speeds.

## 1.3 Details on Individual Family Members

Devices in the PIC24FJ64GA004 family are available in 28-pin and 44-pin packages. The general block diagram for all devices is shown in [Figure 1-1](#).

The devices are differentiated from each other in two ways:

1. Flash program memory (64 Kbytes for PIC24FJ64GA devices, 48 Kbytes for PIC24FJ48GA devices, 32 Kbytes for PIC24FJ32GA devices and 16 Kbytes for PIC24FJ16GA devices).
2. Internal SRAM memory (4k for PIC24FJ16GA devices, 8k for all other devices in the family).
3. Available I/O pins and ports (21 pins on 2 ports for 28-pin devices and 35 pins on 3 ports for 44-pin devices).

All other features for devices in this family are identical. These are summarized in [Table 1-1](#).

A list of the pin features that are available on the PIC24FJ64GA004 family devices, sorted by function, is shown in [Table 1-2](#). Note that this table shows the pin location of individual peripheral features and not how they are multiplexed on the same pin. This information is provided in the pinout diagrams in the beginning of the data sheet. Multiplexed features are sorted by the priority given to a feature, with the highest priority peripheral being listed first.



# PIC24FJ64GA004 FAMILY

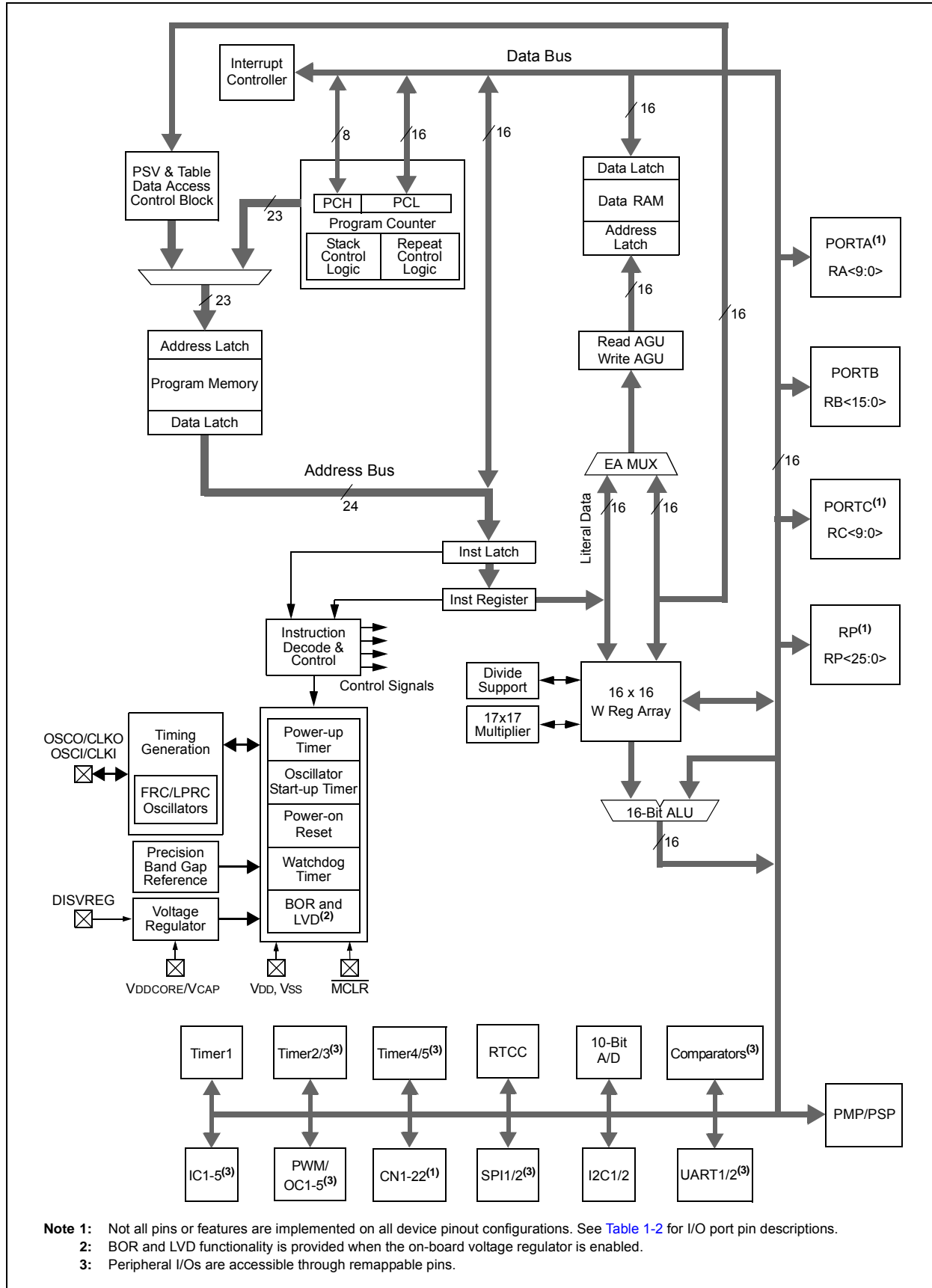
**TABLE 1-1: DEVICE FEATURES FOR THE PIC24FJ64GA004 FAMILY**

Features	16GA002	32GA002	48GA002	64GA002	16GA004	32GA004	48GA004	64GA004
Operating Frequency	DC – 32 MHz							
Program Memory (bytes)	16K	32K	48K	64K	16K	32K	48K	64K
Program Memory (instructions)	5,504	11,008	16,512	22,016	5,504	11,008	16,512	22,016
Data Memory (bytes)	4096	8192			4096	8192		
Interrupt Sources (soft vectors/NMI traps)	43 (39/4)							
I/O Ports	Ports A, B				Ports A, B, C			
Total I/O Pins	21				35			
Timers:	5 <sup>(1)</sup>							
Total Number (16-bit)								
32-Bit (from paired 16-bit timers)	2							
Input Capture Channels	5 <sup>(1)</sup>							
Output Compare/PWM Channels	5 <sup>(1)</sup>							
Input Change Notification Interrupt	21				30			
Serial Communications:	2 <sup>(1)</sup>							
UART								
SPI (3-wire/4-wire)								
I <sup>2</sup> C™	2							
Parallel Communications (PMP/PSP)	Yes							
JTAG Boundary Scan	Yes							
10-Bit Analog-to-Digital Module (input channels)	10				13			
Analog Comparators	2							
Remappable Pins	16				26			
Resets (and delays)	POR, BOR, RESET Instruction, MCLR, WDT, Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (PWRT, OST, PLL Lock)							
Instruction Set	76 Base Instructions, Multiple Addressing Mode Variations							
Packages	28-Pin SPDIP/SSOP/SOIC/QFN				44-Pin QFN/TQFP			

**Note 1:** Peripherals are accessible through remappable pins.

# PIC24FJ64GA004 FAMILY

**FIGURE 1-1: PIC24FJ64GA004 FAMILY GENERAL BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

**TABLE 1-2: PIC24FJ64GA004 FAMILY PINOUT DESCRIPTIONS**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/SSOP/SOIC	28-Pin QFN	44-Pin QFN/TQFP			
AN0	2	27	19	I	ANA	A/D Analog Inputs.
AN1	3	28	20	I	ANA	
AN2	4	1	21	I	ANA	
AN3	5	2	22	I	ANA	
AN4	6	3	23	I	ANA	
AN5	7	4	24	I	ANA	
AN6	—	—	25	I	ANA	
AN7	—	—	26	I	ANA	
AN8	—	—	27	I	ANA	
AN9	26	23	15	I	ANA	
AN10	25	22	14	I	ANA	
AN11	24	21	11	I	ANA	
AN12	23	20	10	I	ANA	
ASCL1	15	12	42	I/O	I <sup>2</sup> C	Alternate I2C1 Synchronous Serial Clock Input/Output. <sup>(1)</sup>
ASDA1	14	11	41	I/O	I <sup>2</sup> C	Alternate I2C2 Synchronous Serial Clock Input/Output. <sup>(1)</sup>
AVDD	—	—	17	P	—	Positive Supply for Analog Modules.
AVSS	—	—	16	P	—	Ground Reference for Analog Modules.
C1IN-	6	3	23	I	ANA	Comparator 1 Negative Input.
C1IN+	7	4	24	I	ANA	Comparator 1 Positive Input.
C2IN-	4	1	21	I	ANA	Comparator 2 Negative Input.
C2IN+	5	2	22	I	ANA	Comparator 2 Positive Input.
CLKI	9	6	30	I	ANA	Main Clock Input Connection.
CLKO	10	7	31	O	—	System Clock Output.

**Legend:** TTL = TTL input buffer  
ANA = Analog level input/output

ST = Schmitt Trigger input buffer  
I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.

# PIC24FJ64GA004 FAMILY

**TABLE 1-2: PIC24FJ64GA004 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/ SSOP/SOIC	28-Pin QFN	44-Pin QFN/TQFP			
CN0	12	9	34	I	ST	Interrupt-on-Change Inputs.
CN1	11	8	33	I	ST	
CN2	2	27	19	I	ST	
CN3	3	28	20	I	ST	
CN4	4	1	21	I	ST	
CN5	5	2	22	I	ST	
CN6	6	3	23	I	ST	
CN7	7	4	24	I	ST	
CN8	—	—	25	I	ST	
CN9	—	—	26	I	ST	
CN10	—	—	27	I	ST	
CN11	26	23	15	I	ST	
CN12	25	22	14	I	ST	
CN13	24	21	11	I	ST	
CN14	23	20	10	I	ST	
CN15	22	19	9	I	ST	
CN16	21	18	8	I	ST	
CN17	—	—	3	I	ST	
CN18	—	—	2	I	ST	
CN19	—	—	5	I	ST	
CN20	—	—	4	I	ST	
CN21	18	15	1	I	ST	
CN22	17	14	44	I	ST	
CN23	16	13	43	I	ST	
CN24	15	12	42	I	ST	
CN25	—	—	37	I	ST	
CN26	—	—	38	I	ST	
CN27	14	11	41	I	ST	
CN28	—	—	36	I	ST	
CN29	10	7	31	I	ST	
CN30	9	6	30	I	ST	
CVREF	25	22	14	O	ANA	Comparator Voltage Reference Output.
DISVREG	19	16	6	I	ST	Voltage Regulator Disable.
INT0	16	13	43	I	ST	External Interrupt Input.
MCLR	1	26	18	I	ST	Master Clear (device Reset) Input. This line is brought low to cause a Reset.

**Legend:** TTL = TTL input buffer      ST = Schmitt Trigger input buffer  
ANA = Analog level input/output      I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.

# PIC24FJ64GA004 FAMILY

**TABLE 1-2: PIC24FJ64GA004 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/SSOP/SOIC	28-Pin QFN	44-Pin QFN/TQFP			
OSCI	9	6	30	I	ANA	Main Oscillator Input Connection.
OSCO	10	7	31	O	ANA	Main Oscillator Output Connection.
PGEC1	5	2	22	I/O	ST	In-Circuit Debugger/Emulator and ICSP™ Programming Clock.
PGEC2	22	19	9	I/O	ST	
PGEC3	14	12	42	I/O	ST	
PGED1	4	1	21	I/O	ST	In-Circuit Debugger/Emulator and ICSP Programming Data.
PGED2	21	18	8	I/O	ST	
PGED3	15	11	41	I/O	ST	
PMA0	10	7	3	I/O	ST/TTL	Parallel Master Port Address Bit 0 Input (Buffered Slave modes) and Output (Master modes).
PMA1	12	9	2	I/O	ST/TTL	Parallel Master Port Address Bit 1 Input (Buffered Slave modes) and Output (Master modes).
PMA2	—	—	27	O	—	Parallel Master Port Address (Demultiplexed Master modes).
PMA3	—	—	38	O	—	
PMA4	—	—	37	O	—	
PMA5	—	—	4	O	—	
PMA6	—	—	5	O	—	
PMA7	—	—	13	O	—	
PMA8	—	—	32	O	—	
PMA9	—	—	35	O	—	
PMA10	—	—	12	O	—	
PMA11	—	—	—	O	—	
PMA12	—	—	—	O	—	
PMA13	—	—	—	O	—	
PMBE	11	8	36	O	—	Parallel Master Port Byte Enable Strobe.
PMCS1	26	23	15	O	—	Parallel Master Port Chip Select 1 Strobe/Address Bit 14.
PMD0	23	20	10	I/O	ST/TTL	Parallel Master Port Data (Demultiplexed Master mode) or Address/Data (Multiplexed Master modes).
PMD1	22	19	9	I/O	ST/TTL	
PMD2	21	18	8	I/O	ST/TTL	
PMD3	18	15	1	I/O	ST/TTL	
PMD4	17	14	44	I/O	ST/TTL	
PMD5	16	13	43	I/O	ST/TTL	
PMD6	15	12	42	I/O	ST/TTL	
PMD7	14	11	41	I/O	ST/TTL	
PMRD	24	21	11	O	—	Parallel Master Port Read Strobe.
PMWR	25	22	14	O	—	Parallel Master Port Write Strobe.

**Legend:** TTL = TTL input buffer  
ANA = Analog level input/output

ST = Schmitt Trigger input buffer  
I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.

# PIC24FJ64GA004 FAMILY

**TABLE 1-2: PIC24FJ64GA004 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/SSOP/SOIC	28-Pin QFN	44-Pin QFN/TQFP			
RA0	2	27	19	I/O	ST	PORTA Digital I/O.
RA1	3	28	20	I/O	ST	
RA2	9	6	30	I/O	ST	
RA3	10	7	31	I/O	ST	
RA4	12	9	34	I/O	ST	
RA7	—	—	13	I/O	ST	
RA8	—	—	32	I/O	ST	
RA9	—	—	35	I/O	ST	
RA10	—	—	12	I/O	ST	
RB0	4	1	21	I/O	ST	PORTB Digital I/O.
RB1	5	2	22	I/O	ST	
RB2	6	3	23	I/O	ST	
RB3	7	4	24	I/O	ST	
RB4	11	8	33	I/O	ST	
RB5	14	11	41	I/O	ST	
RB6	15	12	42	I/O	ST	
RB7	16	13	43	I/O	ST	
RB8	17	14	44	I/O	ST	
RB9	18	15	1	I/O	ST	
RB10	21	18	8	I/O	ST	
RB11	22	19	9	I/O	ST	
RB12	23	20	10	I/O	ST	
RB13	24	21	11	I/O	ST	
RB14	25	22	14	I/O	ST	
RB15	26	23	15	I/O	ST	
RC0	—	—	25	I/O	ST	PORTC Digital I/O.
RC1	—	—	26	I/O	ST	
RC2	—	—	27	I/O	ST	
RC3	—	—	36	I/O	ST	
RC4	—	—	37	I/O	ST	
RC5	—	—	38	I/O	ST	
RC6	—	—	2	I/O	ST	
RC7	—	—	3	I/O	ST	
RC8	—	—	4	I/O	ST	
RC9	—	—	5	I/O	ST	

**Legend:** TTL = TTL input buffer      ST = Schmitt Trigger input buffer  
ANA = Analog level input/output      I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.

# PIC24FJ64GA004 FAMILY

**TABLE 1-2: PIC24FJ64GA004 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/SSOP/SOIC	28-Pin QFN	44-Pin QFN/TQFP			
RP0	4	1	21	I/O	ST	Remappable Peripheral.
RP1	5	2	22	I/O	ST	
RP2	6	3	23	I/O	ST	
RP3	7	4	24	I/O	ST	
RP4	11	8	33	I/O	ST	
RP5	14	11	41	I/O	ST	
RP6	15	12	42	I/O	ST	
RP7	16	13	43	I/O	ST	
RP8	17	14	44	I/O	ST	
RP9	18	15	1	I/O	ST	
RP10	21	18	8	I/O	ST	
RP11	22	19	9	I/O	ST	
RP12	23	20	10	I/O	ST	
RP13	24	21	11	I/O	ST	
RP14	25	22	14	I/O	ST	
RP15	26	23	15	I/O	ST	
RP16	—	—	25	I/O	ST	
RP17	—	—	26	I/O	ST	
RP18	—	—	27	I/O	ST	
RP19	—	—	36	I/O	ST	
RP20	—	—	37	I/O	ST	
RP21	—	—	38	I/O	ST	
RP22	—	—	2	I/O	ST	
RP23	—	—	3	I/O	ST	
RP24	—	—	4	I/O	ST	
RP25	—	—	5	I/O	ST	
RTCC	25	22	14	O	—	Real-Time Clock Alarm Output.
SCL1	17	14	44	I/O	I <sup>2</sup> C	I2C1 Synchronous Serial Clock Input/Output.
SCL2	7	4	24	I/O	I <sup>2</sup> C	I2C2 Synchronous Serial Clock Input/Output.
SDA1	18	15	1	I/O	I <sup>2</sup> C	I2C1 Data Input/Output.
SDA2	6	3	23	I/O	I <sup>2</sup> C	I2C2 Data Input/Output.
SOSCI	11	8	33	I	ANA	Secondary Oscillator/Timer1 Clock Input.
SOSCO	12	9	34	O	ANA	Secondary Oscillator/Timer1 Clock Output.

**Legend:** TTL = TTL input buffer  
ANA = Analog level input/output

ST = Schmitt Trigger input buffer  
I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.

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[illegible]

**Legend:** TTL = TTL input buffer                      ST = Schmitt Trigger input buffer  
ANA = Analog level input/output            I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

**Note 1:** Alternative multiplexing when the I2C1SEL Configuration bit is cleared.



# PIC24FJ64GA004 FAMILY

## 2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT MICROCONTROLLERS

### 2.1 Basic Connection Requirements

Getting started with the PIC24FJ64GA004 family of 16-bit microcontrollers requires attention to a minimal set of device pin connections before proceeding with development.

The following pins must always be connected:

- All VDD and VSS pins (see [Section 2.2 “Power Supply Pins”](#))
- All AVDD and AVSS pins, regardless of whether or not the analog device features are used (see [Section 2.2 “Power Supply Pins”](#))
- MCLR pin (see [Section 2.3 “Master Clear \(MCLR\) Pin”](#))
- ENVREG/DISVREG and VCAP/VDDCORE pins (PIC24F J devices only) (see [Section 2.4 “Voltage Regulator Pins \(ENVREG/DISVREG and VCAP/VDDCORE\)”](#))

These pins must also be connected if they are being used in the end application:

- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes (see [Section 2.5 “ICSP Pins”](#))
- OSCI and OSCO pins when an external oscillator source is used (see [Section 2.6 “External Oscillator Pins”](#))

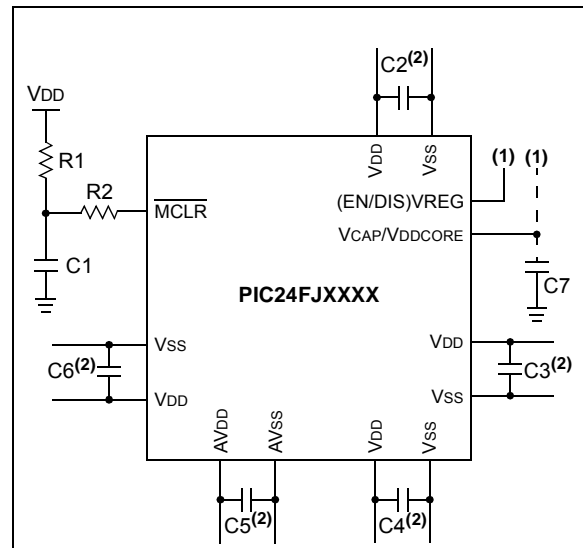
Additionally, the following pins may be required:

- VREF+/VREF- pins used when external voltage reference for analog modules is implemented

**Note:** The AVDD and AVSS pins must always be connected, regardless of whether any of the analog modules are being used.

The minimum mandatory connections are shown in [Figure 2-1](#).

FIGURE 2-1: RECOMMENDED MINIMUM CONNECTIONS



**Key (all values are recommendations):**

C1 through C6: 0.1  $\mu$ F, 20V ceramic

C7: 10  $\mu$ F, 6.3V or greater, tantalum or ceramic

R1: 10 k $\Omega$

R2: 100 $\Omega$  to 470 $\Omega$

**Note 1:** See [Section 2.4 “Voltage Regulator Pins \(ENVREG/DISVREG and VCAP/VDDCORE\)”](#) for an explanation of the ENVREG/DISVREG pin connections.

**2:** The example shown is for a PIC24F device with five VDD/VSS and AVDD/AVSS pairs. Other devices may have more or less pairs; adjust the number of decoupling capacitors appropriately.

# PIC24FJ64GA004 FAMILY

## 2.2 Power Supply Pins

### 2.2.1 DECOUPLING CAPACITORS

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- **Value and type of capacitor:** A 0.1  $\mu\text{F}$  (100 nF), 10-20V capacitor is recommended. The capacitor should be a low-ESR device with a resonance frequency in the range of 200 MHz and higher. Ceramic capacitors are recommended.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is no greater than 0.25 inch (6 mm).
- **Handling high-frequency noise:** If the board is experiencing high-frequency noise (upward of tens of MHz), add a second ceramic type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01  $\mu\text{F}$  to 0.001  $\mu\text{F}$ . Place this second capacitor next to each primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible (e.g., 0.1  $\mu\text{F}$  in parallel with 0.001  $\mu\text{F}$ ).
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB trace inductance.

### 2.2.2 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits including microcontrollers to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7  $\mu\text{F}$  to 47  $\mu\text{F}$ .

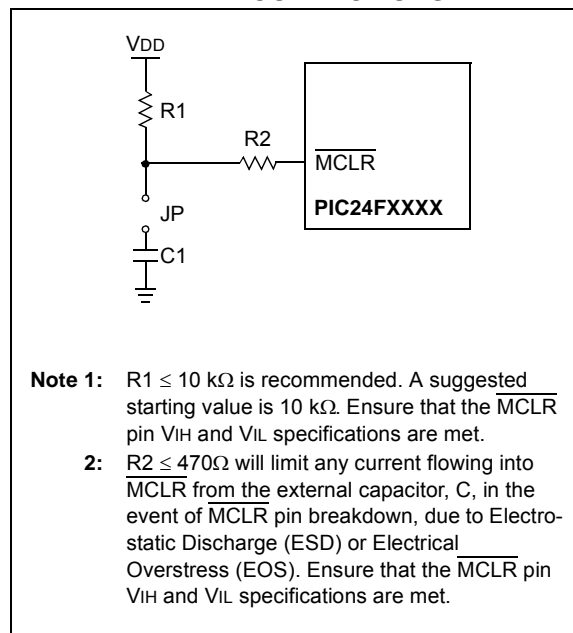
## 2.3 Master Clear ( $\overline{\text{MCLR}}$ ) Pin

The  $\overline{\text{MCLR}}$  pin provides two specific device functions: device Reset, and device programming and debugging. If programming and debugging are not required in the end application, a direct connection to VDD may be all that is required. The addition of other components, to help increase the application's resistance to spurious Resets from voltage sags, may be beneficial. A typical configuration is shown in Figure 2-1. Other circuit designs may be implemented, depending on the application's requirements.

During programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the  $\overline{\text{MCLR}}$  pin. Consequently, specific voltage levels ( $V_{IH}$  and  $V_{IL}$ ) and fast signal transitions must not be adversely affected. Therefore, specific values of R1 and C1 will need to be adjusted based on the application and PCB requirements. For example, it is recommended that the capacitor, C1, be isolated from the  $\overline{\text{MCLR}}$  pin during programming and debugging operations by using a jumper (Figure 2-2). The jumper is replaced for normal run-time operations.

Any components associated with the  $\overline{\text{MCLR}}$  pin should be placed within 0.25 inch (6 mm) of the pin.

**FIGURE 2-2: EXAMPLE OF  $\overline{\text{MCLR}}$  PIN CONNECTIONS**



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## 2.4 Voltage Regulator Pins (ENVREG/DISVREG and VCAP/VDDCORE)

**Note:** This section applies only to PIC24F J devices with an on-chip voltage regulator.

The on-chip voltage regulator enable/disable pin (ENVREG or DISVREG, depending on the device family) must always be connected directly to either a supply voltage or to ground. The particular connection is determined by whether or not the regulator is to be used:

- For ENVREG, tie to VDD to enable the regulator, or to ground to disable the regulator
- For DISVREG, tie to ground to enable the regulator or to VDD to disable the regulator

Refer to [Section 24.2 “On-Chip Voltage Regulator”](#) for details on connecting and using the on-chip regulator.

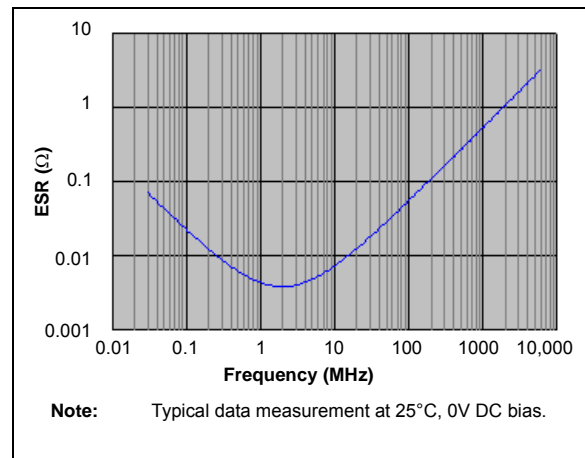
When the regulator is enabled, a low-ESR ( $< 5\Omega$ ) capacitor is required on the VCAP/VDDCORE pin to stabilize the voltage regulator output voltage. The VCAP/VDDCORE pin must not be connected to VDD and must use a capacitor of 10  $\mu\text{F}$  connected to ground. The type can be ceramic or tantalum. Suitable examples of capacitors are shown in [Table 2-1](#). Capacitors with equivalent specification can be used.

Designers may use [Figure 2-3](#) to evaluate ESR equivalence of candidate devices.

The placement of this capacitor should be close to VCAP/VDDCORE. It is recommended that the trace length not exceed 0.25 inch (6 mm). Refer to [Section 27.0 “Electrical Characteristics”](#) for additional information.

When the regulator is disabled, the VCAP/VDDCORE pin must be tied to a voltage supply at the VDDCORE level. Refer to [Section 27.0 “Electrical Characteristics”](#) for information on VDD and VDDCORE.

**FIGURE 2-3: FREQUENCY vs. ESR PERFORMANCE FOR SUGGESTED VCAP**



**TABLE 2-1: SUITABLE CAPACITOR EQUIVALENTS**

Make	Part #	Nominal Capacitance	Base Tolerance	Rated Voltage	Temp. Range
TDK	C3216X7R1C106K	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +125°C
TDK	C3216X5R1C106K	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +85°C
Panasonic	ECJ-3YX1C106K	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +125°C
Panasonic	ECJ-4YB1C106K	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +85°C
Murata	GRM32DR71C106KA01L	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +125°C
Murata	GRM31CR61C106KC31L	10 $\mu\text{F}$	$\pm 10\%$	16V	-55 to +85°C

# PIC24FJ64GA004 FAMILY

## 2.4.1 CONSIDERATIONS FOR CERAMIC CAPACITORS

In recent years, large value, low-voltage, surface-mount ceramic capacitors have become very cost effective in sizes up to a few tens of microfarad. The low-ESR, small physical size and other properties make ceramic capacitors very attractive in many types of applications.

Ceramic capacitors are suitable for use with the internal voltage regulator of this microcontroller. However, some care is needed in selecting the capacitor to ensure that it maintains sufficient capacitance over the intended operating range of the application.

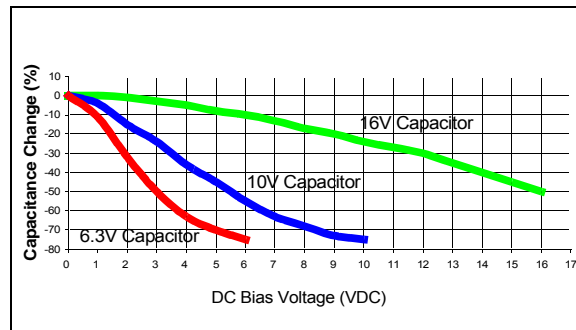
Typical low-cost, 10  $\mu$ F ceramic capacitors are available in X5R, X7R and Y5V dielectric ratings (other types are also available, but are less common). The initial tolerance specifications for these types of capacitors are often specified as  $\pm 10\%$  to  $\pm 20\%$  (X5R and X7R), or  $-20\%/+80\%$  (Y5V). However, the effective capacitance that these capacitors provide in an application circuit will also vary based on additional factors, such as the applied DC bias voltage and the temperature. The total in-circuit tolerance is, therefore, much wider than the initial tolerance specification.

The X5R and X7R capacitors typically exhibit satisfactory temperature stability (ex:  $\pm 15\%$  over a wide temperature range, but consult the manufacturer's data sheets for exact specifications). However, Y5V capacitors typically have extreme temperature tolerance specifications of  $+22\%/-82\%$ . Due to the extreme temperature tolerance, a 10  $\mu$ F nominal rated Y5V type capacitor may not deliver enough total capacitance to meet minimum internal voltage regulator stability and transient response requirements. Therefore, Y5V capacitors are not recommended for use with the internal regulator if the application must operate over a wide temperature range.

In addition to temperature tolerance, the effective capacitance of large value ceramic capacitors can vary substantially, based on the amount of DC voltage applied to the capacitor. This effect can be very significant, but is often overlooked or is not always documented.

Typical DC bias voltage vs. capacitance graph for X7R type capacitors is shown in [Figure 2-4](#).

**FIGURE 2-4: DC BIAS VOLTAGE vs. CAPACITANCE CHARACTERISTICS**



When selecting a ceramic capacitor to be used with the internal voltage regulator, it is suggested to select a high-voltage rating, so that the operating voltage is a small percentage of the maximum rated capacitor voltage. For example, choose a ceramic capacitor rated at 16V for the 2.5V or 1.8V core voltage. Suggested capacitors are shown in [Table 2-1](#).

## 2.5 ICSP Pins

The PGECx and PGEDx pins are used for In-Circuit Serial Programming (ICSP) and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of ohms, not to exceed 100 $\Omega$ .

Pull-up resistors, series diodes and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high ( $V_{IH}$ ) and input low ( $V_{IL}$ ) requirements.

For device emulation, ensure that the "Communication Channel Select" (i.e., PGECx/PGEDx pins), programmed into the device, matches the physical connections for the ICSP to the Microchip debugger/emulator tool.

For more information on available Microchip development tools connection requirements, refer to [Section 25.0 "Development Support"](#).

## 2.6 External Oscillator Pins

Many microcontrollers have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to [Section 8.0 “Oscillator Configuration”](#) for details).

The oscillator circuit should be placed on the same side of the board as the device. Place the oscillator circuit close to the respective oscillator pins with no more than 0.5 inch (12 mm) between the circuit components and the pins. The load capacitors should be placed next to the oscillator itself, on the same side of the board.

Use a grounded copper pour around the oscillator circuit to isolate it from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed.

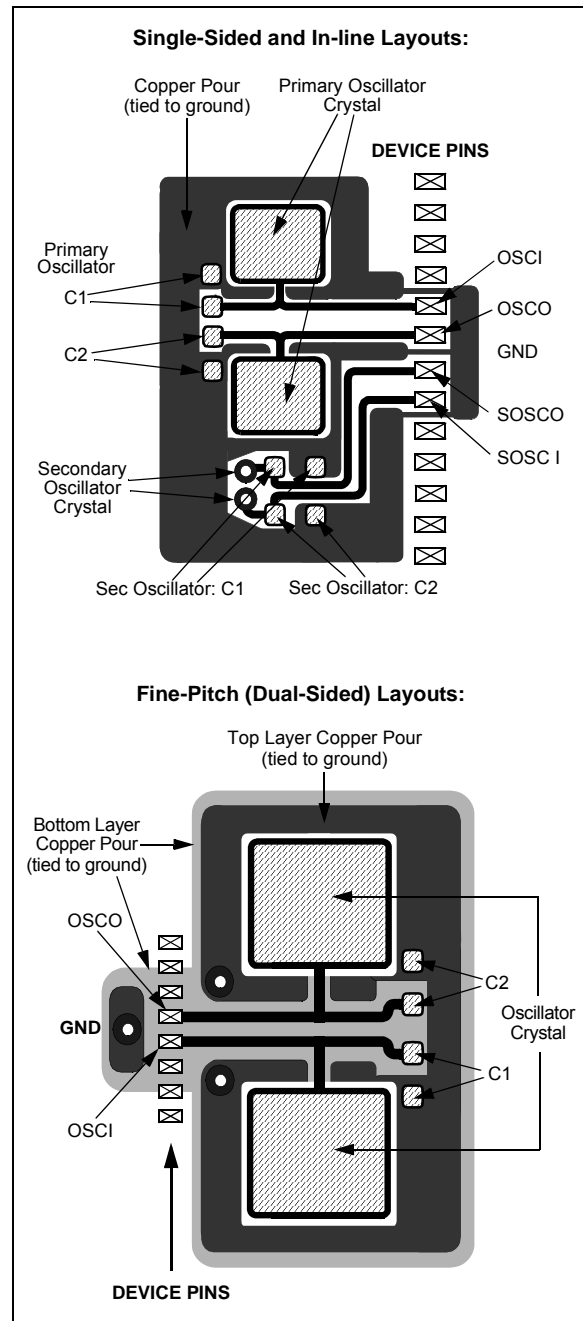
Layout suggestions are shown in [Figure 2-5](#). In-line packages may be handled with a single-sided layout that completely encompasses the oscillator pins. With fine-pitch packages, it is not always possible to completely surround the pins and components. A suitable solution is to tie the broken guard sections to a mirrored ground layer. In all cases, the guard trace(s) must be returned to ground.

In planning the application's routing and I/O assignments, ensure that adjacent port pins, and other signals in close proximity to the oscillator, are benign (i.e., free of high frequencies, short rise and fall times and other similar noise).

For additional information and design guidance on oscillator circuits, please refer to these Microchip Application Notes, available at the corporate web site ([www.microchip.com](http://www.microchip.com)):

- AN826, “Crystal Oscillator Basics and Crystal Selection for rPIC™ and PICmicro® Devices”
- AN849, “Basic PICmicro® Oscillator Design”
- AN943, “Practical PICmicro® Oscillator Analysis and Design”
- AN949, “Making Your Oscillator Work”

**FIGURE 2-5: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT**



# PIC24FJ64GA004 FAMILY

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## 2.7 Configuration of Analog and Digital Pins During ICSP Operations

If an ICSP compliant emulator is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as “digital” pins. Depending on the particular device, this is done by setting all bits in the ADnPCFG register(s), or clearing all bit in the ANSx registers.

All PIC24F devices will have either one or more ADnPCFG registers or several ANSx registers (one for each port); no device will have both. Refer to [Section 21.0 “10-Bit High-Speed A/D Converter”](#) for more specific information.

The bits in these registers that correspond to the A/D pins that initialized the emulator must not be changed by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must modify the appropriate bits during initialization of the A/D module, as follows:

- For devices with an ADnPCFG register, clear the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.
- For devices with ANSx registers, set the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.

When a Microchip debugger/emulator is used as a programmer, the user application firmware must correctly configure the ADnPCFG or ANSx registers. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic ‘0’, which may affect user application functionality.

## 2.8 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic low state. Alternatively, connect a 1 kΩ to 10 kΩ resistor to Vss on unused pins and drive the output to logic low.



## 3.0 CPU

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “CPU” (DS39703).

The PIC24F CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set and a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M instructions of user program memory space. A single-cycle instruction prefetch mechanism is used to help maintain throughput and provides predictable execution. All instructions execute in a single cycle, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction and the table instructions. Overhead-free program loop constructs are supported using the REPEAT instructions, which are interruptible at any point.

PIC24F devices have sixteen, 16-bit working registers in the programmer's model. Each of the working registers can act as a data, address or address offset register. The 16th working register (W15) operates as a Software Stack Pointer for interrupts and calls.

The upper 32 Kbytes of the data space memory map can optionally be mapped into program space at any 16K word boundary defined by the 8-bit Program Space Visibility Page Address (PSVPAG) register. The program to data space mapping feature lets any instruction access program space as if it were data space.

The Instruction Set Architecture (ISA) has been significantly enhanced beyond that of the PIC18, but maintains an acceptable level of backward compatibility. All PIC18 instructions and addressing modes are supported, either directly, or through simple macros. Many of the ISA enhancements have been driven by compiler efficiency needs.

The core supports Inherent (no operand), Relative, Literal, Memory Direct and three groups of addressing modes. All modes support Register Direct and various Register Indirect modes. Each group offers up to seven addressing modes. Instructions are associated with predefined addressing modes depending upon their functional requirements.

For most instructions, the core is capable of executing a data (or program data) memory read, a working register (data) read, a data memory write and a program (instruction) memory read per instruction cycle. As a result, three parameter instructions can be supported, allowing trinary operations (that is,  $A + B = C$ ) to be executed in a single cycle.

A high-speed, 17-bit by 17-bit multiplier has been included to significantly enhance the core arithmetic capability and throughput. The multiplier supports Signed, Unsigned and Mixed mode, 16-bit by 16-bit or 8-bit by 8-bit, integer multiplication. All multiply instructions execute in a single cycle.

The 16-bit ALU has been enhanced with integer divide assist hardware that supports an iterative non-restoring divide algorithm. It operates in conjunction with the REPEAT instruction looping mechanism and a selection of iterative divide instructions to support 32-bit (or 16-bit), divided by 16-bit, integer signed and unsigned division. All divide operations require 19 cycles to complete, but are interruptible at any cycle boundary.

The PIC24F has a vectored exception scheme with up to 8 sources of non-maskable traps and up to 118 interrupt sources. Each interrupt source can be assigned to one of seven priority levels.

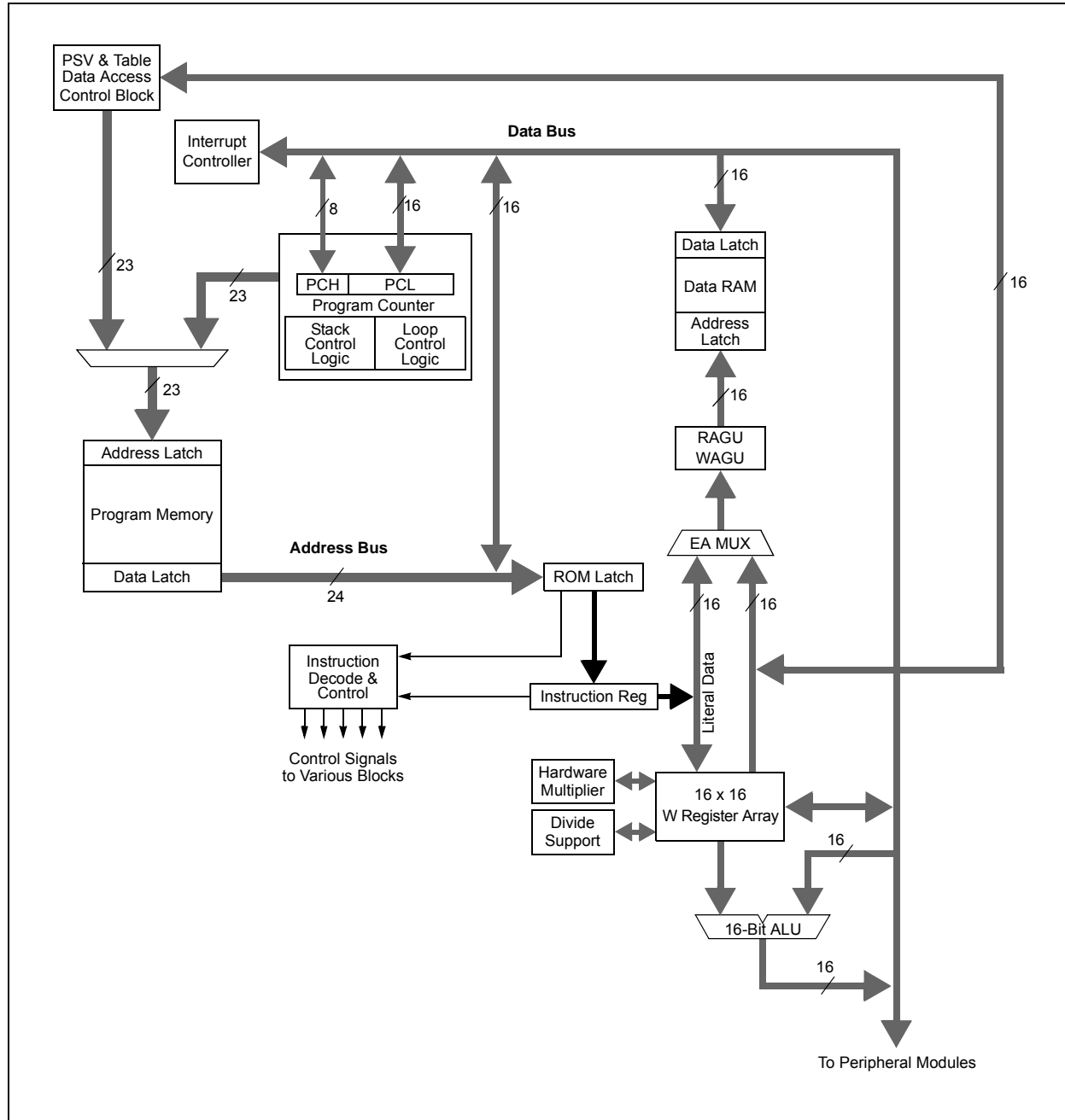
A “block diagram of the CPU is shown in [Figure 3-1](#).

### 3.1 Programmer's Model

The programmer's model for the PIC24F is shown in [Figure 3-2](#). All registers in the programmer's model are memory mapped and can be manipulated directly by instructions. A description of each register is provided in [Table 3-1](#). All registers associated with the programmer's model are memory mapped.

# PIC24FJ64GA004 FAMILY

**FIGURE 3-1: PIC24F CPU CORE BLOCK DIAGRAM**



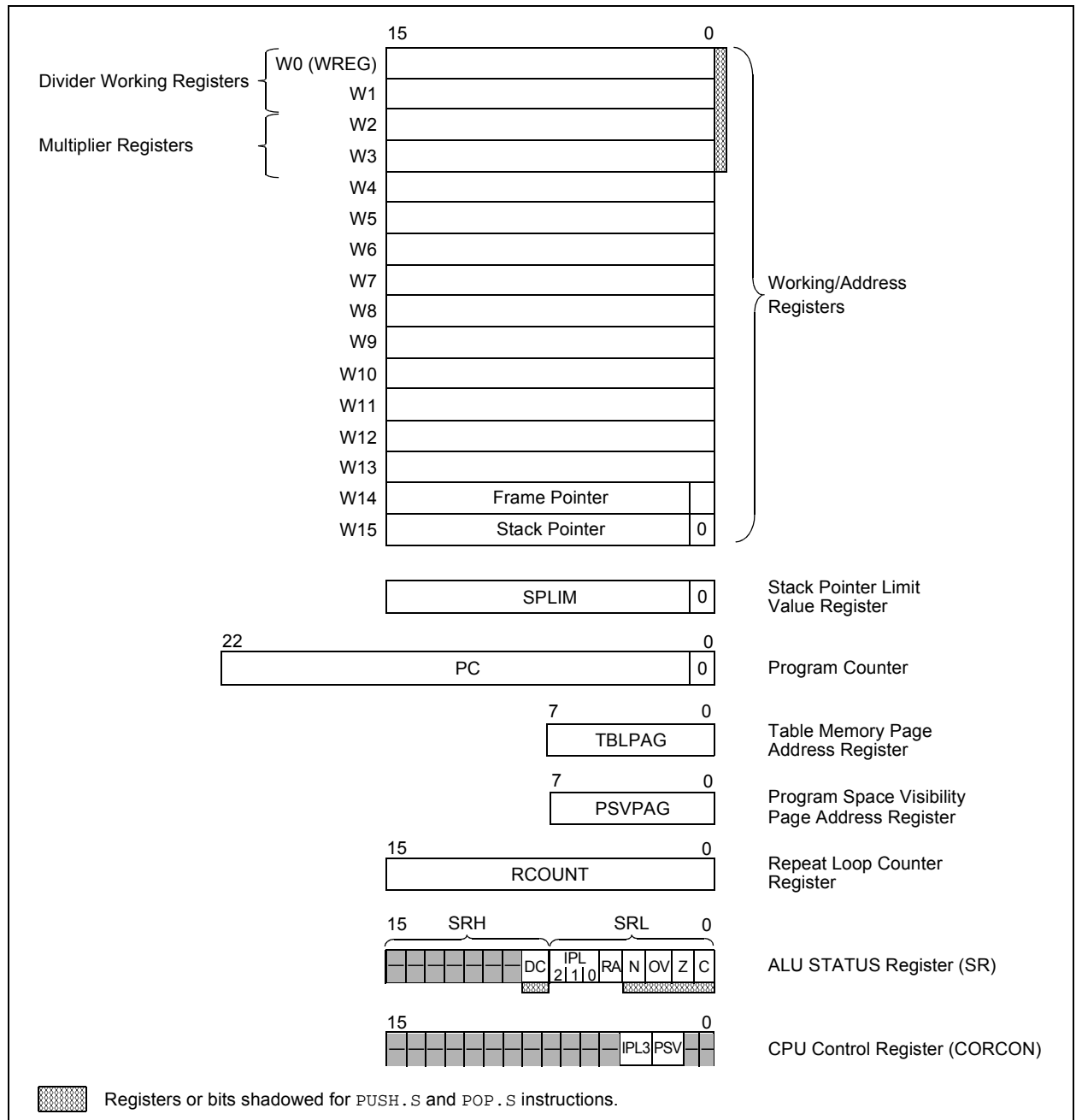


# PIC24FJ64GA004 FAMILY

**TABLE 3-1: CPU CORE REGISTERS**

Register(s) Name	Description
W0 through W15	Working Register Array
PC	23-Bit Program Counter
SR	ALU STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
PSVPAG	Program Space Visibility Page Address Register
RCOUNT	Repeat Loop Counter Register
CORCON	CPU Control Register

**FIGURE 3-2: PROGRAMMER'S MODEL**



# PIC24FJ64GA004 FAMILY

## 3.2 CPU Control Registers

**REGISTER 3-1: SR: ALU STATUS REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	DC
bit 15							bit 8

R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 <sup>(2)</sup>	IPL1 <sup>(2)</sup>	IPL0 <sup>(2)</sup>	RA	N	OV	Z	C
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8 **DC:** ALU Half Carry/Borrow bit

1 = A carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred

0 = No carry-out from the 4th or 8th low-order bit of the result has occurred

bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits<sup>(1,2)</sup>

111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled

110 = CPU Interrupt Priority Level is 6 (14)

101 = CPU Interrupt Priority Level is 5 (13)

100 = CPU Interrupt Priority Level is 4 (12)

011 = CPU Interrupt Priority Level is 3 (11)

010 = CPU Interrupt Priority Level is 2 (10)

001 = CPU Interrupt Priority Level is 1 (9)

000 = CPU Interrupt Priority Level is 0 (8)

bit 4 **RA:** REPEAT Loop Active bit

1 = REPEAT loop in progress

0 = REPEAT loop not in progress

bit 3 **N:** ALU Negative bit

1 = Result was negative

0 = Result was non-negative (zero or positive)

bit 2 **OV:** ALU Overflow bit

1 = Overflow occurred for signed (2's complement) arithmetic in this arithmetic operation

0 = No overflow has occurred

bit 1 **Z:** ALU Zero bit

1 = An operation which effects the Z bit has set it at some time in the past

0 = The most recent operation which effects the Z bit has cleared it (i.e., a non-zero result)

bit 0 **C:** ALU Carry/Borrow bit

1 = A carry-out from the Most Significant bit of the result occurred

0 = No carry-out from the Most Significant bit of the result occurred

**Note 1:** The IPL Status bits are read-only when NSTDIS (INTCON1<15>) = 1.

**Note 2:** The IPL Status bits are concatenated with the IPL3 bit (CORCON<3>) to form the CPU Interrupt Priority Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1.

# PIC24FJ64GA004 FAMILY

**REGISTER 3-2: CORCON: CPU CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			
U-0	U-0	U-0	U-0	R/C-0	R/W-0	U-0	U-0
—	—	—	—	IPL3 <sup>(1)</sup>	PSV	—	—
bit 7				bit 0			

<b>Legend:</b>	C = Clearable bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15-4      **Unimplemented:** Read as '0'
- bit 3      **IPL3:** CPU Interrupt Priority Level Status bit<sup>(1)</sup>  
             1 = CPU Interrupt Priority Level is greater than 7  
             0 = CPU Interrupt Priority Level is 7 or less
- bit 2      **PSV:** Program Space Visibility in Data Space Enable bit  
             1 = Program space is visible in data space  
             0 = Program space is not visible in data space
- bit 1-0      **Unimplemented:** Read as '0'

**Note 1:** User interrupts are disabled when IPL3 = 1.

## 3.3 Arithmetic Logic Unit (ALU)

The PIC24F ALU is 16 bits wide, and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are 2's complement in nature. Depending on the operation, the ALU may affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array, or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

The PIC24F CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

### 3.3.1 MULTIPLIER

The ALU contains a high-speed, 17-bit x 17-bit multiplier. It supports unsigned, signed or mixed sign operation in several multiplication modes:

1. 16-bit x 16-bit signed
2. 16-bit x 16-bit unsigned
3. 16-bit signed x 5-bit (literal) unsigned
4. 16-bit unsigned x 16-bit unsigned
5. 16-bit unsigned x 5-bit (literal) unsigned
6. 16-bit unsigned x 16-bit signed
7. 8-bit unsigned x 8-bit unsigned

# PIC24FJ64GA004 FAMILY

## 3.3.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. Sixteen-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor ( $W_n$ ), and any W register (aligned) pair ( $W(m+1):W_m$ ) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

## 3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided below in [Table 3-2](#).

**TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE AND MULTI-BIT SHIFT OPERATION**

Instruction	Description
ASR	Arithmetic shift right source register by one or more bits.
SL	Shift left source register by one or more bits.
LSR	Logical shift right source register by one or more bits.

# PIC24FJ64GA004 FAMILY

## 4.0 MEMORY ORGANIZATION

As Harvard architecture devices, PIC24F micro-controllers feature separate program and data memory spaces and buses. This architecture also allows the direct access of program memory from the data space during code execution.

### 4.1 Program Address Space

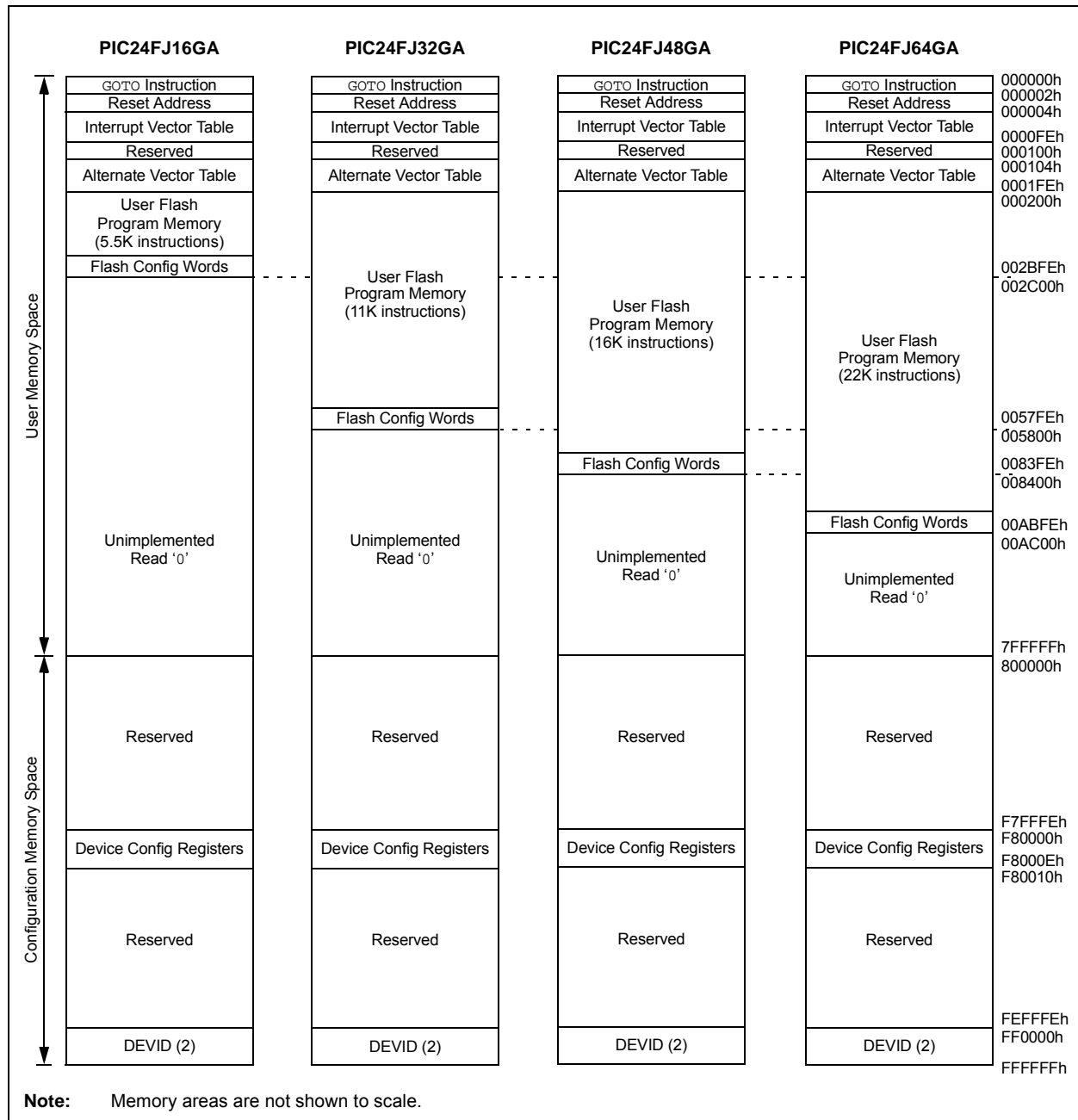
The program address memory space of the PIC24FJ64GA004 family devices is 4M instructions. The space is addressable by a 24-bit value derived

from either the 23-bit Program Counter (PC) during program execution, or from table operation or data space remapping, as described in [Section 4.3 “Interfacing Program and Data Memory Spaces”](#).

User access to the program memory space is restricted to the lower half of the address range (000000h to 7FFFFFFh). The exception is the use of TBLRD/TBLWT operations which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

Memory maps for the PIC24FJ64GA004 family of devices are shown in [Figure 4-1](#).

**FIGURE 4-1: PROGRAM SPACE MEMORY MAP FOR PIC24FJ64GA004 FAMILY DEVICES**



# PIC24FJ64GA004 FAMILY

## 4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-2).

Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented by two during code execution. This arrangement also provides compatibility with data memory space addressing and makes it possible to access data in the program memory space.

## 4.1.2 HARD MEMORY VECTORS

All PIC24F devices reserve the addresses between 00000h and 000200h for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user at 000000h with the actual address for the start of code at 000002h.

PIC24F devices also have two Interrupt Vector Tables (IVT), located from 000004h to 0000FFh and 000100h to 0001FFh. These vector tables allow each of the many device interrupt sources to be handled by separate ISRs. A more detailed discussion of the Interrupt Vector Tables is provided in Section 7.1 “Interrupt Vector Table”.

## 4.1.3 FLASH CONFIGURATION WORDS

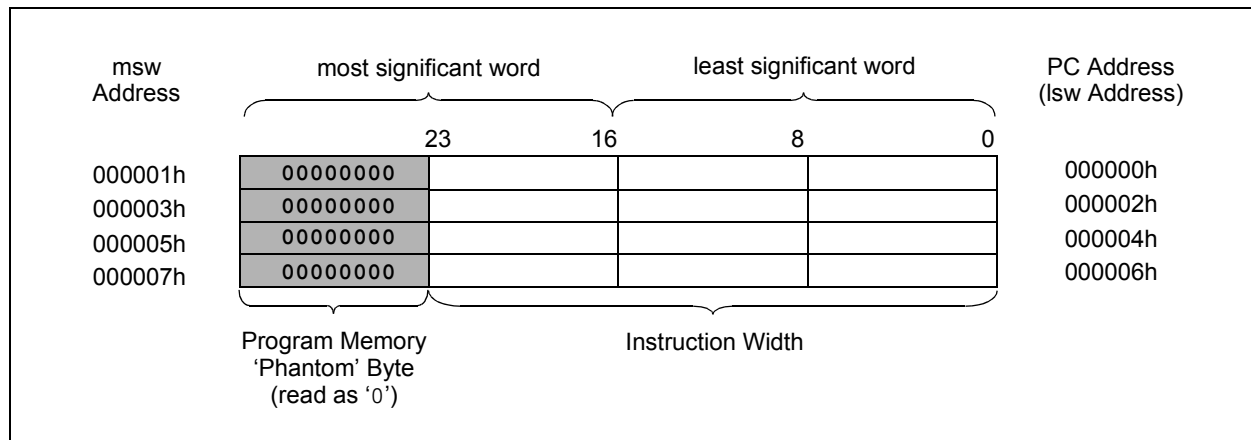
In PIC24FJ64GA004 family devices, the top two words of on-chip program memory are reserved for configuration information. On device Reset, the configuration information is copied into the appropriate Configuration registers. The addresses of the Flash Configuration Word for devices in the PIC24FJ64GA004 family are shown in Table 4-1. Their location in the memory map is shown with the other memory vectors in Figure 4-1.

The Configuration Words in program memory are a compact format. The actual Configuration bits are mapped in several different registers in the configuration memory space. Their order in the Flash Configuration Words does not reflect a corresponding arrangement in the configuration space. Additional details on the device Configuration Words are provided in Section 24.1 “Configuration Bits”.

**TABLE 4-1: FLASH CONFIGURATION WORDS FOR PIC24FJ64GA004 FAMILY DEVICES**

Device	Program Memory (K words)	Configuration Word Addresses
PIC24FJ16GA	5.5	002BFCh: 002BFEh
PIC24FJ32GA	11	0057FCh: 0057FEh
PIC24FJ48GA	16	0083FCh: 0083FEh
PIC24FJ64GA	22	00ABFCh: 00ABFEh

**FIGURE 4-2: PROGRAM MEMORY ORGANIZATION**



# PIC24FJ64GA004 FAMILY

## 4.2 Data Address Space

The PIC24F core has a separate, 16-bit wide data memory space, addressable as a single linear range. The data space is accessed using two Address Generation Units (AGUs), one each for read and write operations. The data space memory map is shown in Figure 4-3.

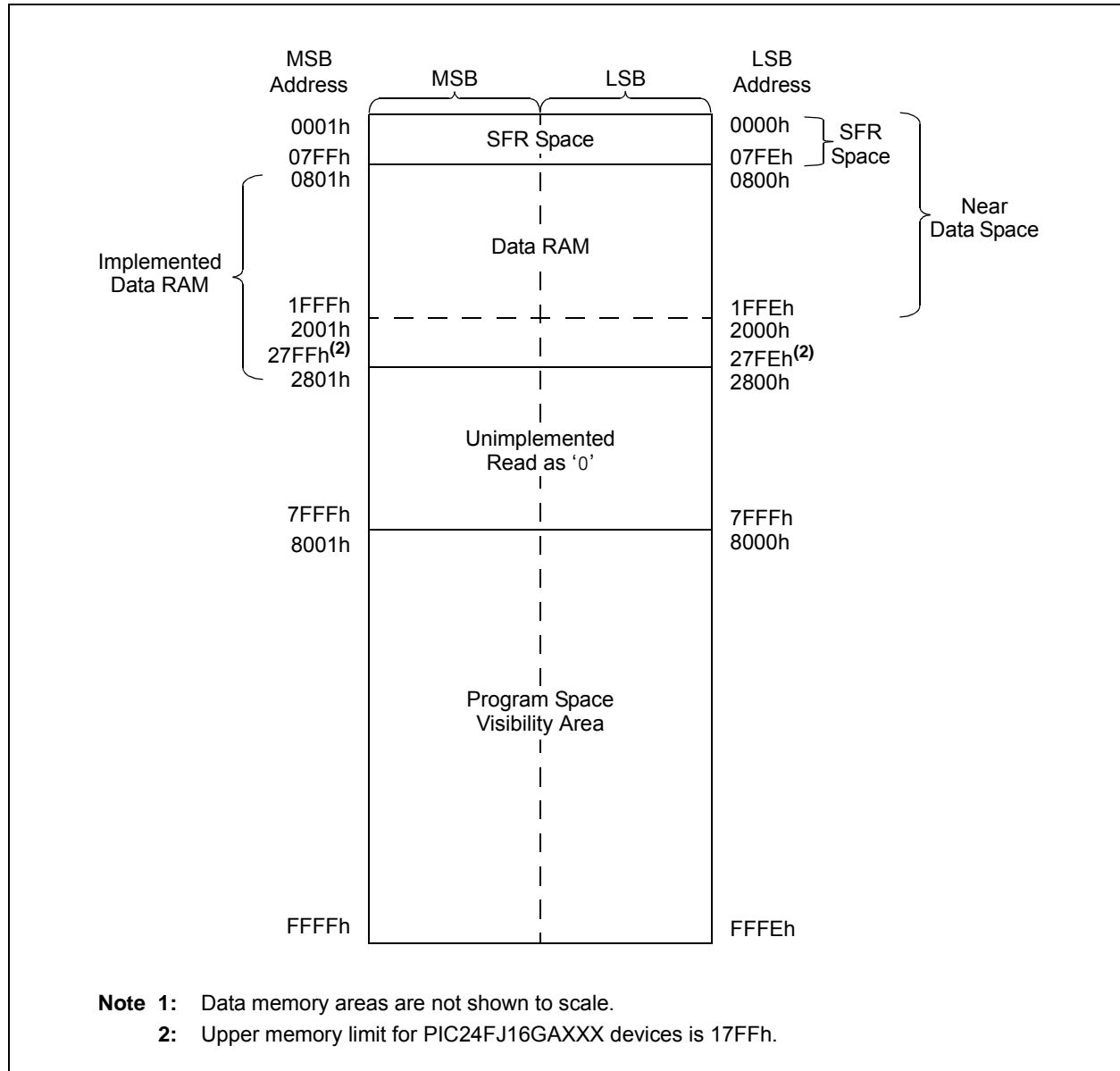
All Effective Addresses (EAs) in the data memory space are 16 bits wide and point to bytes within the data space. This gives a data space address range of 64 Kbytes or 32K words. The lower half of the data memory space (that is, when  $EA<15> = 0$ ) is used for implemented memory addresses, while the upper half ( $EA<15> = 1$ ) is reserved for the Program Space Visibility (PSV) area (see Section 4.3.3 “Reading Data From Program Memory Using Program Space Visibility”).

PIC24FJ64GA004 family devices implement a total of 8 Kbytes of data memory. Should an EA point to a location outside of this area, an all zero word or byte will be returned.

### 4.2.1 DATA SPACE WIDTH

The data memory space is organized in byte-addressable, 16-bit wide blocks. Data is aligned in data memory and registers as 16-bit words, but all data space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

FIGURE 4-3: DATA SPACE MEMORY MAP FOR PIC24FJ64GA004 FAMILY DEVICES<sup>(1)</sup>



# PIC24FJ64GA004 FAMILY

## 4.2.2 DATA MEMORY ORGANIZATION AND ALIGNMENT

To maintain backward compatibility with PIC® devices and improve data space memory usage efficiency, the PIC24F instruction set supports both word and byte operations. As a consequence of byte accessibility, all Effective Address (EA) calculations are internally scaled to step through word-aligned memory. For example, the core recognizes that Post-Modified Register Indirect Addressing mode [Ws++] will result in a value of Ws + 1 for byte operations and Ws + 2 for word operations.

Data byte reads will read the complete word which contains the byte, using the LSb of any EA to determine which byte to select. The selected byte is placed onto the LSB of the data path. That is, data memory and registers are organized as two parallel, byte-wide entities with shared (word) address decode but separate write lines. Data byte writes only write to the corresponding side of the array or register which matches the byte address.

All word accesses must be aligned to an even address. Misaligned word data fetches are not supported, so care must be taken when mixing byte and word operations, or translating from 8-bit MCU code. If a misaligned read or write is attempted, an address error trap will be generated. If the error occurred on a read, the instruction underway is completed; if it occurred on a write, the instruction will be executed but the write will not occur. In either case, a trap is then executed, allowing the system and/or user to examine the machine state prior to execution of the address Fault.

All byte loads into any W register are loaded into the Least Significant Byte. The Most Significant Byte is not modified.

A Sign-Extend (SE) instruction is provided to allow users to translate 8-bit signed data to 16-bit signed values. Alternatively, for 16-bit unsigned data, users can clear the MSB of any W register by executing a Zero-Extend (ZE) instruction on the appropriate address.

Although most instructions are capable of operating on word or byte data sizes, it should be noted that some instructions operate only on words.

## 4.2.3 NEAR DATA SPACE

The 8-Kbyte area between 0000h and 1FFFh is referred to as the Near Data Space. Locations in this space are directly addressable via a 13-bit absolute address field within all memory direct instructions. The remainder of the data space is addressable indirectly. Additionally, the whole data space is addressable using MOV instructions, which support Memory Direct Addressing with a 16-bit address field.

## 4.2.4 SFR SPACE

The first 2 Kbytes of the Near Data Space, from 0000h to 07FFh, are primarily occupied with Special Function Registers (SFRs). These are used by the PIC24F core and peripheral modules for controlling the operation of the device.

SFRs are distributed among the modules that they control and are generally grouped together by module. Much of the SFR space contains unused addresses; these are read as '0'. A diagram of the SFR space, showing where SFRs are actually implemented, is shown in Table 4-2. Each implemented area indicates a 32-byte region where at least one address is implemented as an SFR. A complete listing of implemented SFRs, including their addresses, is shown in Tables 4-3 through 4-24.

**TABLE 4-2: IMPLEMENTED REGIONS OF SFR DATA SPACE**

SFR Space Address								
	xx00	xx20	xx40	xx60	xx80	xxA0	xxC0	xxE0
000h	Core			ICN	Interrupts			—
100h	Timers		Capture	—	Compare	—	—	—
200h	I <sup>2</sup> C™	UART	SPI		—	—	I/O	
300h	A/D		—	—	—	—	—	—
400h	—	—	—	—	—	—	—	—
500h	—	—	—	—	—	—	—	—
600h	PMP	RTC/Comp	CRC	—	PPS			
700h	—	—	System	NVM/PMD	—	—	—	—

**Legend:** — = No implemented SFRs in this block



**TABLE 4-3: CPU CORE REGISTERS MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
WREG0	0000	Working Register 0																0000
WREG1	0002	Working Register 1																0000
WREG2	0004	Working Register 2																0000
WREG3	0006	Working Register 3																0000
WREG4	0008	Working Register 4																0000
WREG5	000A	Working Register 5																0000
WREG6	000C	Working Register 6																0000
WREG7	000E	Working Register 7																0000
WREG8	0010	Working Register 8																0000
WREG9	0012	Working Register 9																0000
WREG10	0014	Working Register 10																0000
WREG11	0016	Working Register 11																0000
WREG12	0018	Working Register 12																0000
WREG13	001A	Working Register 13																0000
WREG14	001C	Working Register 14																0000
WREG15	001E	Working Register 15																0800
SPLIM	0020	Stack Pointer Limit Value Register																xxxx
PCL	002E	Program Counter Low Byte Register																0000
PCH	0030	—	—	—	—	—	—	—	—	Program Counter Register High Byte								0000
TBLPAG	0032	—	—	—	—	—	—	—	—	Table Memory Page Address Register								0000
PSVPAG	0034	—	—	—	—	—	—	—	—	Program Space Visibility Page Address Register								0000
RCOUNT	0036	Repeat Loop Counter Register																xxxx
SR	0042	—	—	—	—	—	—	—	DC	IPL2	IPL1	IPL0	RA	N	OV	Z	C	0000
CORCON	0044	—	—	—	—	—	—	—	—	—	—	—	—	IPL3	PSV	—	—	0000
DISICNT	0052	—	—	Disable Interrupts Counter Register														xxxx

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-4: ICN REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CNEN1	0060	CN15IE	CN14IE	CN13IE	CN12IE	CN11IE	CN10IE <sup>(1)</sup>	CN9IE <sup>(1)</sup>	CN8IE <sup>(1)</sup>	CN7IE	CN6IE	CN5IE	CN4IE	CN3IE	CN2IE	CN1IE	CN0IE	0000
CNEN2	0062	—	CN30IE	CN29IE	CN28IE <sup>(1)</sup>	CN27IE	CN26IE <sup>(1)</sup>	CN25IE <sup>(1)</sup>	CN24IE	CN23IE	CN22IE	CN21IE	CN20IE <sup>(1)</sup>	CN19IE <sup>(1)</sup>	CN18IE <sup>(1)</sup>	CN17IE <sup>(1)</sup>	CN16IE	0000
CNPU1	0068	CN15PUE	CN14PUE	CN13PUE	CN12PUE	CN11PUE	CN10PUE <sup>(1)</sup>	CN9PUE <sup>(1)</sup>	CN8PUE <sup>(1)</sup>	CN7PUE	CN6PUE	CN5PUE	CN4PUE	CN3PUE	CN2PUE	CN1PUE	CN0PUE	0000
CNPU2	006A	—	CN30PUE	CN29PUE	CN28PUE <sup>(1)</sup>	CN27PUE	CN26PUE <sup>(1)</sup>	CN25PUE <sup>(1)</sup>	CN24PUE	CN23PUE	CN22PUE	CN21PUE	CN20PUE <sup>(1)</sup>	CN19PUE <sup>(1)</sup>	CN18PUE <sup>(1)</sup>	CN17PUE <sup>(1)</sup>	CN16PUE	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits are not available on 28-pin devices; read as '0'.

**TABLE 4-5: INTERRUPT CONTROLLER REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	0080	NSTDIS	—	—	—	—	—	—	—	—	—	—	MATHERR	ADDRERR	STKERR	OSCFail	—	0000
INTCON2	0082	ALTIPT	DISI	—	—	—	—	—	—	—	—	—	—	—	INT2EP	INT1EP	INT0EP	0000
IFS0	0084	—	—	AD1IF	U1TXIF	U1RXIF	SP11IF	SPF1IF	T3IF	T2IF	OC2IF	IC2IF	—	T1IF	OC1IF	IC1IF	INT0IF	0000
IFS1	0086	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	—	—	—	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF	0000
IFS2	0088	—	—	PMPIF	—	—	—	OC5IF	—	IC5IF	IC4IF	IC3IF	—	—	—	SPI2IF	SPF2IF	0000
IFS3	008A	—	RTCIF	—	—	—	—	—	—	—	—	—	—	—	MI2C2IF	SI2C2IF	—	0000
IFS4	008C	—	—	—	—	—	—	—	LVDIF	—	—	—	—	CRCIF	U2ERIF	U1ERIF	—	0000
IEC0	0094	—	—	AD1IE	U1TXIE	U1RXIE	SP11IE	SPF1IE	T3IE	T2IE	OC2IE	IC2IE	—	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0096	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	—	—	—	—	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE	0000
IEC2	0098	—	—	PMPIE	—	—	—	OC5IE	—	IC5IE	IC4IE	IC3IE	—	—	—	SPI2IE	SPF2IE	0000
IEC3	009A	—	RTCIE	—	—	—	—	—	—	—	—	—	—	—	MI2C2IE	SI2C2IE	—	0000
IEC4	009C	—	—	—	—	—	—	—	LVDIE	—	—	—	—	CRCIE	U2ERIE	U1ERIE	—	0000
IPC0	00A4	—	T1IP2	T1IP1	T1IP0	—	OC1IP2	OC1IP1	OC1IP0	—	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0	4444
IPC1	00A6	—	T2IP2	T2IP1	T2IP0	—	OC2IP2	OC2IP1	OC2IP0	—	IC2IP2	IC2IP1	IC2IP0	—	—	—	—	4444
IPC2	00A8	—	U1RXIP2	U1RXIP1	U1RXIP0	—	SP11IP2	SP11IP1	SP11IP0	—	SPF1IP2	SPF1IP1	SPF1IP0	—	T3IP2	T3IP1	T3IP0	4444
IPC3	00AA	—	—	—	—	—	—	—	—	—	AD1IP2	AD1IP1	AD1IP0	—	U1TXIP2	U1TXIP1	U1TXIP0	4444
IPC4	00AC	—	CNIP2	CNIP1	CNIP0	—	CMIP2	CMIP1	CMIP0	—	MI2C1P2	MI2C1P1	MI2C1P0	—	SI2C1P2	SI2C1P1	SI2C1P0	4444
IPC5	00AE	—	—	—	—	—	—	—	—	—	—	—	—	—	INT1IP2	INT1IP1	INT1IP0	4444
IPC6	00B0	—	T4IP2	T4IP1	T4IP0	—	OC4IP2	OC4IP1	OC4IP0	—	OC3IP2	OC3IP1	OC3IP0	—	—	—	—	4444
IPC7	00B2	—	U2TXIP2	U2TXIP1	U2TXIP0	—	U2RXIP2	U2RXIP1	U2RXIP0	—	INT2IP2	INT2IP1	INT2IP0	—	T5IP2	T5IP1	T5IP0	4444
IPC8	00B4	—	—	—	—	—	—	—	—	—	SPI2IP2	SPI2IP1	SPI2IP0	—	SPF2IP2	SPF2IP1	SPF2IP0	4444
IPC9	00B6	—	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0	—	IC3IP2	IC3IP1	IC3IP0	—	—	—	—	4444
IPC10	00B8	—	—	—	—	—	—	—	—	—	OC5IP2	OC5IP1	OC5IP0	—	—	—	—	4444
IPC11	00BA	—	—	—	—	—	—	—	—	—	PMP2IP2	PMP2IP1	PMP2IP0	—	—	—	—	4444
IPC12	00BC	—	—	—	—	—	MI2C2P2	MI2C2P1	MI2C2P0	—	SI2C2P2	SI2C2P1	SI2C2P0	—	—	—	—	4444
IPC15	00C2	—	—	—	—	—	RTCIP2	RTCIP1	RTCIP0	—	—	—	—	—	—	—	—	4444
IPC16	00C4	—	CRCIP2	CRCIP1	CRCIP0	—	U2ERIP2	U2ERIP1	U2ERIP0	—	U1ERIP2	U1ERIP1	U1ERIP0	—	—	—	—	4444
IPC18	00C8	—	—	—	—	—	—	—	—	—	—	—	—	—	LVDIP2	LVDIP1	LVDIP0	4444
INTTREG	00E0	CPUIRQ	—	VHOLD	—	ILR3	ILR2	ILR1	ILR0	—	VECN6	VECN5	VECN4	VECN3	VECN2	VECN1	VECN0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-6: TIMER REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TMR1	0100	Timer1 Register																0000
PR1	0102	Timer1 Period Register																FFFF
T1CON	0104	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS1	TCKPS0	—	TSYNC	TCS	—	0000
TMR2	0106	Timer2 Register																0000
TMR3HLD	0108	Timer3 Holding Register (for 32-bit timer operations only)																0000
TMR3	010A	Timer3 Register																0000
PR2	010C	Timer2 Period Register																FFFF
PR3	010E	Timer3 Period Register																FFFF
T2CON	0110	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS1	TCKPS0	T32	—	TCS	—	0000
T3CON	0112	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS1	TCKPS0	—	—	TCS	—	0000
TMR4	0114	Timer4 Register																0000
TMR5HLD	0116	Timer5 Holding Register (for 32-bit operations only)																0000
TMR5	0118	Timer5 Register																0000
PR4	011A	Timer4 Period Register																FFFF
PR5	011C	Timer5 Period Register																FFFF
T4CON	011E	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS1	TCKPS0	T32	—	TCS	—	0000
T5CON	0120	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS1	TCKPS0	—	—	TCS	—	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-7: INPUT CAPTURE REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IC1BUF	0140	Input Capture 1 Register																FFFF
IC1CON	0142	—	—	ICSIDL	—	—	—	—	—	ICTMR	IC11	IC10	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC2BUF	0144	Input Capture 2 Register																FFFF
IC2CON	0146	—	—	ICSIDL	—	—	—	—	—	ICTMR	IC11	IC10	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC3BUF	0148	Input Capture 3 Register																FFFF
IC3CON	014A	—	—	ICSIDL	—	—	—	—	—	ICTMR	IC11	IC10	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC4BUF	014C	Input Capture 4 Register																FFFF
IC4CON	014E	—	—	ICSIDL	—	—	—	—	—	ICTMR	IC11	IC10	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC5BUF	0150	Input Capture 5 Register																FFFF
IC5CON	0152	—	—	ICSIDL	—	—	—	—	—	ICTMR	IC11	IC10	ICOV	ICBNE	ICM2	ICM1	ICM0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-8: OUTPUT COMPARE REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC1RS	0180	Output Compare 1 Secondary Register																FFFF
OC1R	0182	Output Compare 1 Register																FFFF
OC1CON	0184	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM2	OCM1	OCM0	0000
OC2RS	0186	Output Compare 2 Secondary Register																FFFF
OC2R	0188	Output Compare 2 Register																FFFF
OC2CON	018A	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM2	OCM1	OCM0	0000
OC3RS	018C	Output Compare 3 Secondary Register																FFFF
OC3R	018E	Output Compare 3 Register																FFFF
OC3CON	0190	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM2	OCM1	OCM0	0000
OC4RS	0192	Output Compare 4 Secondary Register																FFFF
OC4R	0194	Output Compare 4 Register																FFFF
OC4CON	0196	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM2	OCM1	OCM0	0000
OC5RS	0198	Output Compare 5 Secondary Register																FFFF
OC5R	019A	Output Compare 5 Register																FFFF
OC5CON	019C	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM2	OCM1	OCM0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-9: I<sup>2</sup>C™ REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
I2C1RCV	0200	—	—	—	—	—	—	—	—	I2C1 Receive Register								0000
I2C1TRN	0202	—	—	—	—	—	—	—	—	I2C1 Transmit Register								00FF
I2C1BRG	0204	—	—	—	—	—	—	—	Baud Rate Generator Register 1									0000
I2C1CON	0206	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C1STAT	0208	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/ $\overline{A}$	P	S	R/ $\overline{W}$	RBF	TBF	0000
I2C1ADD	020A	—	—	—	—	—	—	I2C1 Address Register										0000
I2C1MSK	020C	—	—	—	—	—	—	AMSK9	AMSK8	AMSK7	AMSK6	AMSK5	AMSK4	AMSK3	AMSK2	AMSK1	AMSK0	0000
I2C2RCV	0210	—	—	—	—	—	—	—	—	I2C2 Receive Register								0000
I2C2TRN	0212	—	—	—	—	—	—	—	—	I2C2 Transmit Register								00FF
I2C2BRG	0214	—	—	—	—	—	—	—	Baud Rate Generator Register 2									0000
I2C2CON	0216	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C2STAT	0218	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/ $\overline{A}$	P	S	R/ $\overline{W}$	RBF	TBF	0000
I2C2ADD	021A	—	—	—	—	—	—	I2C2 Address Register										0000
I2C2MSK	021C	—	—	—	—	—	—	AMSK9	AMSK8	AMSK7	AMSK6	AMSK5	AMSK4	AMSK3	AMSK2	AMSK1	AMSK0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-10: UART REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
U1MODE	0220	UARTEN	—	USIDL	IREN	RTSMO	—	UEN1	UEN0	WAKE	LPBACK	ABAUO	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000
U1STA	0222	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110
U1TXREG	0224	—	—	—	—	—	—	—	UTX8	UTX7	UTX6	UTX5	UTX4	UTX3	UTX2	UTX1	UTX0	0000
U1RXREG	0226	—	—	—	—	—	—	—	URX8	URX7	URX6	URX5	URX4	URX3	URX2	URX1	URX0	0000
U1BRG	0228	Baud Rate Generator Prescaler Register																0000
U2MODE	0230	UARTEN	—	USIDL	IREN	RTSMO	—	UEN1	UEN0	WAKE	LPBACK	ABAUO	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000
U2STA	0232	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110
U2TXREG	0234	—	—	—	—	—	—	—	UTX8	UTX7	UTX6	UTX5	UTX4	UTX3	UTX2	UTX1	UTX0	0000
U2RXREG	0236	—	—	—	—	—	—	—	URX8	URX7	URX6	URX5	URX4	URX3	URX2	URX1	URX0	0000
U2BRG	0238	Baud Rate Generator Prescaler																0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-11: SPI REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI1STAT	0240	SPIEN	—	SPIIDL	—	—	SPIBEC2	SPIBEC1	SPIBEC0	SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF	0000
SPI1CON1	0242	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0	0000
SPI1CON2	0244	FRMEN	SPIFSD	SPIFPOL	—	—	—	—	—	—	—	—	—	—	—	SPIFE	SPIBEN	0000
SPI1BUF	0248	SPI1 Transmit/Receive Buffer																0000
SPI2STAT	0260	SPIEN	—	SPIIDL	—	—	SPIBEC2	SPIBEC1	SPIBEC0	SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF	0000
SPI2CON1	0262	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0	0000
SPI2CON2	0264	FRMEN	SPIFSD	SPIFPOL	—	—	—	—	—	—	—	—	—	—	—	SPIFE	SPIBEN	0000
SPI2BUF	0268	SPI2 Transmit/Receive Buffer																0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-12: PORTA REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	02C0	—	—	—	—	—	TRISA10 <sup>(1)</sup>	TRISA9 <sup>(1)</sup>	TRISA8 <sup>(1)</sup>	TRISA7 <sup>(1)</sup>	—	—	TRISA4	TRISA3 <sup>(2)</sup>	TRISA2 <sup>(3)</sup>	TRISA1	TRISA0	079F
PORTA	02C2	—	—	—	—	—	RA10 <sup>(1)</sup>	RA9 <sup>(1)</sup>	RA8 <sup>(1)</sup>	RA7 <sup>(1)</sup>	—	—	RA4	RA3 <sup>(2)</sup>	RA2 <sup>(3)</sup>	RA1	RA0	0000
LATA	02C4	—	—	—	—	—	LATA10 <sup>(1)</sup>	LATA9 <sup>(1)</sup>	LATA8 <sup>(1)</sup>	LATA7 <sup>(1)</sup>	—	—	LATA4	LATA3 <sup>(2)</sup>	LATA2 <sup>(3)</sup>	LATA1	LATA0	0000
ODCA	02C6	—	—	—	—	—	ODA10 <sup>(1)</sup>	ODA9 <sup>(1)</sup>	ODA8 <sup>(1)</sup>	ODA7 <sup>(1)</sup>	—	—	ODA4	ODA3 <sup>(2)</sup>	ODA2 <sup>(3)</sup>	ODA1	ODA0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits are not available on 28-pin devices; read as '0'.

**2:** These bits are only available when the primary oscillator is disabled (POSCMD<1:0> = 00); otherwise, read as '0'.

**3:** These bits are only available when the primary oscillator is disabled or EC mode is selected (POSCMD<1:0> = 00 or 11) and CLK0 is disabled (OSCIOFNC = 0); otherwise, read as '0'.

**TABLE 4-13: PORTB REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	02CA	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	0000
LATB	02CC	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	0000
ODCB	02CE	ODB15	ODB14	ODB13	ODB12	ODB11	ODB10	ODB9	ODB8	ODB7	ODB6	ODB5	ODB4	ODB3	ODB2	ODB1	ODB0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-14: PORTC REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISC <sup>(1)</sup>	02D0	—	—	—	—	—	—	TRISC9	TRISC8	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	03FF
PORTC <sup>(1)</sup>	02D2	—	—	—	—	—	—	RC9	RC8	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	0000
LATC <sup>(1)</sup>	02D4	—	—	—	—	—	—	LATC9	LATC8	LATC7	LATC6	LATC5	LATC4	LATC3	LATC2	LATC1	LATC0	0000
ODCC <sup>(1)</sup>	02D6	—	—	—	—	—	—	ODC9	OSC8	ODC7	ODC6	ODC5	ODC4	ODC3	ODC2	ODC1	ODC0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Bits are not available on 28-pin devices; read as '0'.

**TABLE 4-15: PAD CONFIGURATION REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PADCFG1	02FC	—	—	—	—	—	—	—	—	—	—	—	—	—	—	RTSECSSEL	PMPTTL	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-16: A/D REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300	A/D Data Buffer 0																xxxx
ADC1BUF1	0302	A/D Data Buffer 1																xxxx
ADC1BUF2	0304	A/D Data Buffer 2																xxxx
ADC1BUF3	0306	A/D Data Buffer 3																xxxx
ADC1BUF4	0308	A/D Data Buffer 4																xxxx
ADC1BUF5	030A	A/D Data Buffer 5																xxxx
ADC1BUF6	030C	A/D Data Buffer 6																xxxx
ADC1BUF7	030E	A/D Data Buffer 7																xxxx
ADC1BUF8	0310	A/D Data Buffer 8																xxxx
ADC1BUF9	0312	A/D Data Buffer 9																xxxx
ADC1BUFA	0314	A/D Data Buffer 10																xxxx
ADC1BUFB	0316	A/D Data Buffer 11																xxxx
ADC1BUFC	0318	A/D Data Buffer 12																xxxx
ADC1BUFD	031A	A/D Data Buffer 13																xxxx
ADC1BUFE	031C	A/D Data Buffer 14																xxxx
ADC1BUFF	031E	A/D Data Buffer 15																xxxx
AD1CON1	0320	ADON	—	ADSIDL	—	—	—	FORM1	FORM0	SSRC2	SSRC1	SSRC0	—	—	ASAM	SAMP	DONE	0000
AD1CON2	0322	VCFG2	VCFG1	VCFG0	—	—	CSCNA	—	—	BUFS	—	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS	0000
AD1CON3	0324	ADRC	—	—	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0	ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0	0000
AD1CHS	0328	CH0NB	—	—	—	CH0SB3	CH0SB2	CH0SB1	CH0SB0	CH0NA	—	—	—	CH0SA3	CH0SA2	CH0SA1	CH0SA0	0000
AD1PCFG	032C	PCFG15	—	—	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8 <sup>(1)</sup>	PCFG7 <sup>(1)</sup>	PCFG6 <sup>(1)</sup>	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000
AD1CSSL	0330	CSSL15	—	—	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8 <sup>(1)</sup>	CSSL7 <sup>(1)</sup>	CSSL6 <sup>(1)</sup>	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits are not available on 28-pin devices; read as '0'.

**TABLE 4-17: PARALLEL MASTER/SLAVE PORT REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMCON	0600	PMPEN	—	PSIDL	ADRMUX1	ADRMUX0	PTBEEN	PTWREN	PTRDEN	CSF1	CSF0	ALP	—	CS1P	BEP	WRSP	RDSP	0000
PMMODE	0602	BUSY	IRQM1	IRQM0	INCM1	INCM0	MODE16	MODE1	MODE0	WAITB1	WAITB0	WAITM3	WAITM2	WAITM1	WAITM0	WAITE1	WAITE0	0000
PMADDR	0604	—	CS1	—	—	—	ADDR10	ADDR9	ADDR8	ADDR7	ADDR6	ADDR5	ADDR4	ADDR3	ADDR2	ADDR1	ADDR0	0000
PMDOUT1		Parallel Port Data Out Register 1 (Buffers 0 and 1)																0000
PMDOUT2	0606	Parallel Port Data Out Register 2 (Buffers 2 and 3)																0000
PMDIN1	0608	Parallel Port Data In Register 1 (Buffers 0 and 1)																0000
PMDIN2	060A	Parallel Port Data In Register 2 (Buffers 2 and 3)																0000
PMAEN	060C	—	PTEN14	—	—	—	PTEN10	PTEN9	PTEN8	PTEN7	PTEN6	PTEN5	PTEN4	PTEN3	PTEN2	PTEN1	PTEN0	0000
PMSTAT	060E	IBF	IBOV	—	—	IB3F	IB2F	IB1F	IB0F	OBE	OBUF	—	—	OB3E	OB2E	OB1E	OB0E	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-18: REAL-TIME CLOCK AND CALENDAR REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ALRMVAL	0620	Alarm Value Register Window Based on ALRMPTR<1:0>																xxxx
ALCFGRPT	0622	ALRMEN	CHIME	AMASK3	AMASK2	AMASK1	AMASK0	ALRMPTR1	ALRMPTR0	ARPT7	ARPT6	ARPT5	ARPT4	ARPT3	ARPT2	ARPT1	ARPT0	0000
RTCVAL	0624	RTCC Value Register Window Based on RTCPTR<1:0>																xxxx
RCFGCAL	0626	RTCEN	—	RTCWREN	RTCSYNC	HALFSEC	RTCOE	RTCPTR1	RTCPTR0	CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-19: DUAL COMPARATOR REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CMCON	0630	CMIDL	—	C2EVT	C1EVT	C2EN	C1EN	C2OUTEN	C1OUTEN	C2OUT	C1OUT	C2INV	C1INV	C2NEG	C2POS	C1NEG	C1POS	0000
CVRCON	0632	—	—	—	—	—	—	—	—	CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-20: CRC REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CRCCON	0640	—	—	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0	CRCFUL	CRCMPT	—	CRCGO	PLEN3	PLEN2	PLEN1	PLEN0	0040
CRCXOR	0642	X15	X14	X13	X12	X11	X10	X9	X8	X7	X6	X5	X4	X3	X2	X1	—	0000
CRCDAT	0644	CRC Data Input Register																0000
CRCWDAT	0646	CRC Result Register																0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



**TABLE 4-21: PERIPHERAL PIN SELECT REGISTER MAP (PPS)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPINR0	0680	—	—	—	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0	—	—	—	—	—	—	—	—	1F00
RPINR1	0682	—	—	—	—	—	—	—	—	—	—	—	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0	001F
RPINR3	0686	—	—	—	T3CKR4	T3CKR3	T3CKR2	T3CKR1	T3CKR0	—	—	—	T2CKR4	T2CKR3	T2CKR2	T2CKR1	T2CKR0	1F1F
RPINR4	0688	—	—	—	T5CKR4	T5CKR3	T5CKR2	T5CKR1	T5CKR0	—	—	—	T4CKR4	T4CKR3	T4CKR2	T4CKR1	T4CKR0	1F1F
RPINR7	068E	—	—	—	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0	—	—	—	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0	1F1F
RPINR8	0690	—	—	—	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0	—	—	—	IC3R4	IC3R3	IC3R2	IC3R1	IC3R0	1F1F
RPINR9	0692	—	—	—	—	—	—	—	—	—	—	—	IC5R4	IC5R3	IC5R2	IC5R1	IC5R0	001F
RPINR11	0696	—	—	—	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0	—	—	—	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0	1F1F
RPINR18	06A4	—	—	—	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0	—	—	—	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0	1F1F
RPINR19	06A6	—	—	—	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0	—	—	—	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0	1F1F
RPINR20	06A8	—	—	—	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0	—	—	—	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0	1F1F
RPINR21	06AA	—	—	—	—	—	—	—	—	—	—	—	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0	001F
RPINR22	06AC	—	—	—	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0	—	—	—	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0	1F1F
RPINR23	06AE	—	—	—	—	—	—	—	—	—	—	—	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0	001F
RPOR0	06C0	—	—	—	RP1R4	RP1R3	RP1R2	RP1R1	RP1R0	—	—	—	RP0R4	RP0R3	RP0R2	RP0R1	RP0R0	0000
RPOR1	06C2	—	—	—	RP3R4	RP3R3	RP3R2	RP3R1	RP3R0	—	—	—	RP2R4	RP2R3	RP2R2	RP2R1	RP2R0	0000
RPOR2	06C4	—	—	—	RP5R4	RP5R3	RP5R2	RP5R1	RP5R0	—	—	—	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0	0000
RPOR3	06C6	—	—	—	RP7R4	RP7R3	RP7R2	RP7R1	RP7R0	—	—	—	RP6R4	RP6R3	RP6R2	RP6R1	RP6R0	0000
RPOR4	06C8	—	—	—	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0	—	—	—	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0	0000
RPOR5	06CA	—	—	—	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0	—	—	—	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0	0000
RPOR6	06CC	—	—	—	RP13R4	RP13R3	RP13R2	RP13R1	RP13R0	—	—	—	RP12R4	RP12R3	RP12R2	RP12R1	RP12R0	0000
RPOR7	06CE	—	—	—	RP15R4	RP15R3	RP15R2	RP15R1	RP15R0	—	—	—	RP14R4	RP14R3	RP14R2	RP14R1	RP14R0	0000
RPOR8	06D0	—	—	—	RP17R4 <sup>(1)</sup>	RP17R3 <sup>(1)</sup>	RP17R2 <sup>(1)</sup>	RP17R1 <sup>(1)</sup>	RP17R0 <sup>(1)</sup>	—	—	—	RP16R4 <sup>(1)</sup>	RP16R3 <sup>(1)</sup>	RP16R2 <sup>(1)</sup>	RP16R1 <sup>(1)</sup>	RP16R0 <sup>(1)</sup>	0000
RPOR9	06D2	—	—	—	RP19R4 <sup>(1)</sup>	RP19R3 <sup>(1)</sup>	RP19R2 <sup>(1)</sup>	RP19R1 <sup>(1)</sup>	RP19R0 <sup>(1)</sup>	—	—	—	RP18R4 <sup>(1)</sup>	RP18R3 <sup>(1)</sup>	RP18R2 <sup>(1)</sup>	RP18R1 <sup>(1)</sup>	RP18R0 <sup>(1)</sup>	0000
RPOR10	06D4	—	—	—	RP21R4 <sup>(1)</sup>	RP21R3 <sup>(1)</sup>	RP21R2 <sup>(1)</sup>	RP21R1 <sup>(1)</sup>	RP21R0 <sup>(1)</sup>	—	—	—	RP20R4 <sup>(1)</sup>	RP20R3 <sup>(1)</sup>	RP20R2 <sup>(1)</sup>	RP20R1 <sup>(1)</sup>	RP20R0 <sup>(1)</sup>	0000
RPOR11	06D6	—	—	—	RP23R4 <sup>(1)</sup>	RP23R3 <sup>(1)</sup>	RP23R2 <sup>(1)</sup>	RP23R1 <sup>(1)</sup>	RP23R0 <sup>(1)</sup>	—	—	—	RP22R4 <sup>(1)</sup>	RP22R3 <sup>(1)</sup>	RP22R2 <sup>(1)</sup>	RP22R1 <sup>(1)</sup>	RP22R0 <sup>(1)</sup>	0000
RPOR12	06D8	—	—	—	RP25R4 <sup>(1)</sup>	RP25R3 <sup>(1)</sup>	RP25R2 <sup>(1)</sup>	RP25R1 <sup>(1)</sup>	RP25R0 <sup>(1)</sup>	—	—	—	RP24R4 <sup>(1)</sup>	RP24R3 <sup>(1)</sup>	RP24R2 <sup>(1)</sup>	RP24R1 <sup>(1)</sup>	RP24R0 <sup>(1)</sup>	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** These bits are only available on 44-pin devices; otherwise, they read as '0'.

**TABLE 4-22: CLOCK CONTROL REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	—	—	—	—	CM	PMSLP	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	(Note 1)
OSCCON	0742	—	COSC2	COSC1	COSC0	—	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	—	CF	—	SOSCEN	OSWEN	(Note 2)
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	RCDIV2	RCDIV1	RCDIV0	—	—	—	—	—	—	—	—	3140
OSCTUN	0748	—	—	—	—	—	—	—	—	—	—	TUN5	TUN4	TUN3	TUN2	TUN1	TUN0	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** RCON register Reset values are dependent on the type of Reset.

**2:** OSCCON register Reset values are dependent on configuration fuses and by the type of Reset.

**TABLE 4-23: NVM REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	—	—	—	—	—	—	ERASE	—	—	NVMOP3	NVMOP2	NVMOP1	NVMOP0	0000 <sup>(1)</sup>
NVMKEY	0766	—	—	—	—	—	—	—	—	NVMKEY<7:0>								0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** Reset value shown is for a POR only. The value on other Reset states is dependent on the state of the memory write or erase operations at the time of Reset.

**TABLE 4-24: PMD REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	T5MD	T4MD	T3MD	T2MD	T1MD	—	—	—	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	ADC1MD	0000
PMD2	0772	—	—	—	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD	—	—	—	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0774	—	—	—	—	—	CMPMD	RTCCMD	PMPMD	CRCPMD	—	—	—	—	—	I2C2MD	—	0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

## 4.2.5 SOFTWARE STACK

In addition to its use as a working register, the W15 register in PIC24F devices is also used as a Software Stack Pointer. The pointer always points to the first available free word and grows from lower to higher addresses. It pre-decrements for stack pops and post-increments for stack pushes, as shown in [Figure 4-4](#). Note that for a PC push during any `CALL` instruction, the MSB of the PC is zero-extended before the push, ensuring that the MSB is always clear.

**Note:** A PC push during exception processing will concatenate the SRL register to the MSB of the PC prior to the push.

The Stack Pointer Limit Value register (SPLIM), associated with the Stack Pointer, sets an upper address boundary for the stack. SPLIM is uninitialized at Reset. As is the case for the Stack Pointer, SPLIM<0> is forced to '0' because all stack operations must be word-aligned. Whenever an EA is generated using W15 as a source or destination pointer, the resulting address is compared with the value in SPLIM. If the contents of the Stack Pointer (W15) and the SPLIM register are equal, and a push operation is performed, a stack error trap will not occur. The stack error trap will occur on a subsequent push operation. Thus, for example, if it is desirable to cause a stack error trap when the stack grows beyond address 2000h in RAM, initialize the SPLIM with the value, 1FFEh.

Similarly, a Stack Pointer underflow (stack error) trap is generated when the Stack Pointer address is found to be less than 0800h. This prevents the stack from interfering with the Special Function Register (SFR) space.

A write to the SPLIM register should not be immediately followed by an indirect read operation using W15.

## 4.3 Interfacing Program and Data Memory Spaces

The PIC24F architecture uses a 24-bit wide program space and 16-bit wide data space. The architecture is also a modified Harvard scheme, meaning that data can also be present in the program space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the PIC24F architecture provides two methods by which program space can be accessed during operation:

- Using table instructions to access individual bytes or words anywhere in the program space
- Remapping a portion of the program space into the data space (Program Space Visibility)

Table instructions allow an application to read or write to small areas of the program memory. This makes the method ideal for accessing data tables that need to be updated from time to time. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for look-ups from a large table of static data. It can only access the least significant word of the program word.

### 4.3.1 ADDRESSING PROGRAM SPACE

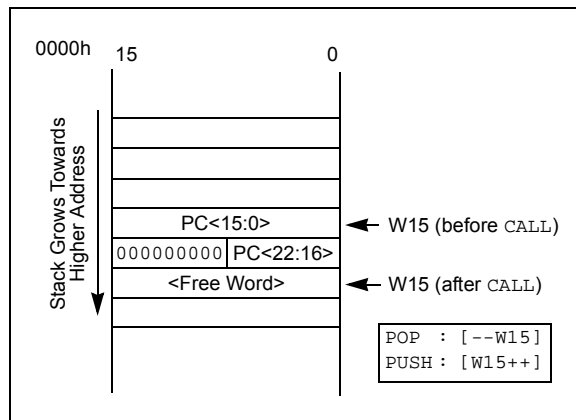
Since the address ranges for the data and program spaces are 16 and 24 bits, respectively, a method is needed to create a 23-bit or 24-bit program address from 16-bit data registers. The solution depends on the interface method to be used.

For table operations, the 8-bit Table Memory Page Address register (TBLPAG) is used to define a 32K word region within the program space. This is concatenated with a 16-bit EA to arrive at a full 24-bit program space address. In this format, the Most Significant bit of TBLPAG is used to determine if the operation occurs in the user memory (TBLPAG<7> = 0) or the configuration memory (TBLPAG<7> = 1).

For remapping operations, the 8-bit Program Space Visibility Page Address register (PSVPAG) is used to define a 16K word page in the program space. When the Most Significant bit of the EA is '1', PSVPAG is concatenated with the lower 15 bits of the EA to form a 23-bit program space address. Unlike table operations, this limits remapping operations strictly to the user memory area.

[Table 4-25](#) and [Figure 4-5](#) show how the program EA is created for table operations and remapping accesses from the data EA. Here, P<23:0> refers to a program space word, whereas D<15:0> refers to a data space word.

**FIGURE 4-4: CALL STACK FRAME**



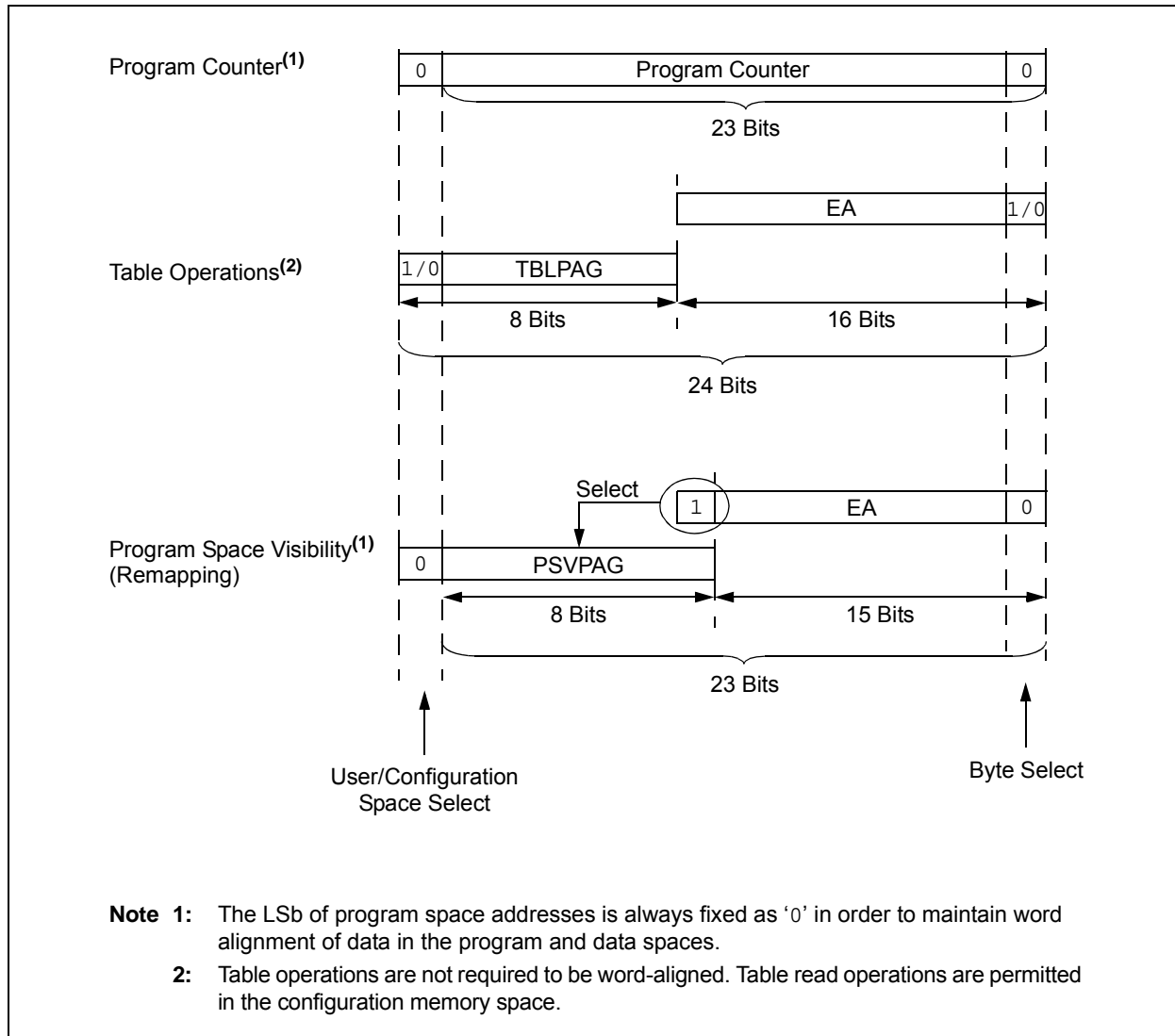
# PIC24FJ64GA004 FAMILY

**TABLE 4-25: PROGRAM SPACE ADDRESS CONSTRUCTION**

Access Type	Access Space	Program Space Address				
		<23>	<22:16>	<15>	<14:1>	<0>
Instruction Access (Code Execution)	User	0	PC<22:1>			0
		0xx xxxx xxxx xxxx xxxx xxx0				
TBLRD/TBLWT (Byte/Word Read/Write)	User	TBLPAG<7:0>		Data EA<15:0>		
		0xxx xxxxx xxxxx xxxxx xxxxx xxxxx				
	Configuration	TBLPAG<7:0>		Data EA<15:0>		
		1xxx xxxxx xxxxx xxxxx xxxxx xxxxx				
Program Space Visibility (Block Remap/Read)	User	0	PSVPAG<7:0>		Data EA<14:0> <sup>(1)</sup>	
		0	xxxx xxxxx xxx xxxxx xxxxx xxxxx			

**Note 1:** Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is PSVPAG<0>.

**FIGURE 4-5: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION**



## 4.3.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The **TBLRDL** and **TBLWTL** instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The **TBLRDH** and **TBLWTH** instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two 16-bit word-wide address spaces, residing side by side, each with the same address range. **TBLRDL** and **TBLWTL** access the space which contains the least significant data word, and **TBLRDH** and **TBLWTH** access the space which contains the upper data byte.

Two table instructions are provided to move byte or word-sized (16-bit) data to and from program space. Both function as either byte or word operations.

1. **TBLRDL** (Table Read Low): In Word mode, it maps the lower word of the program space location ( $P<15:0>$ ) to a data address ( $D<15:0>$ ). In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when byte select is '1'; the lower byte is selected when it is '0'.

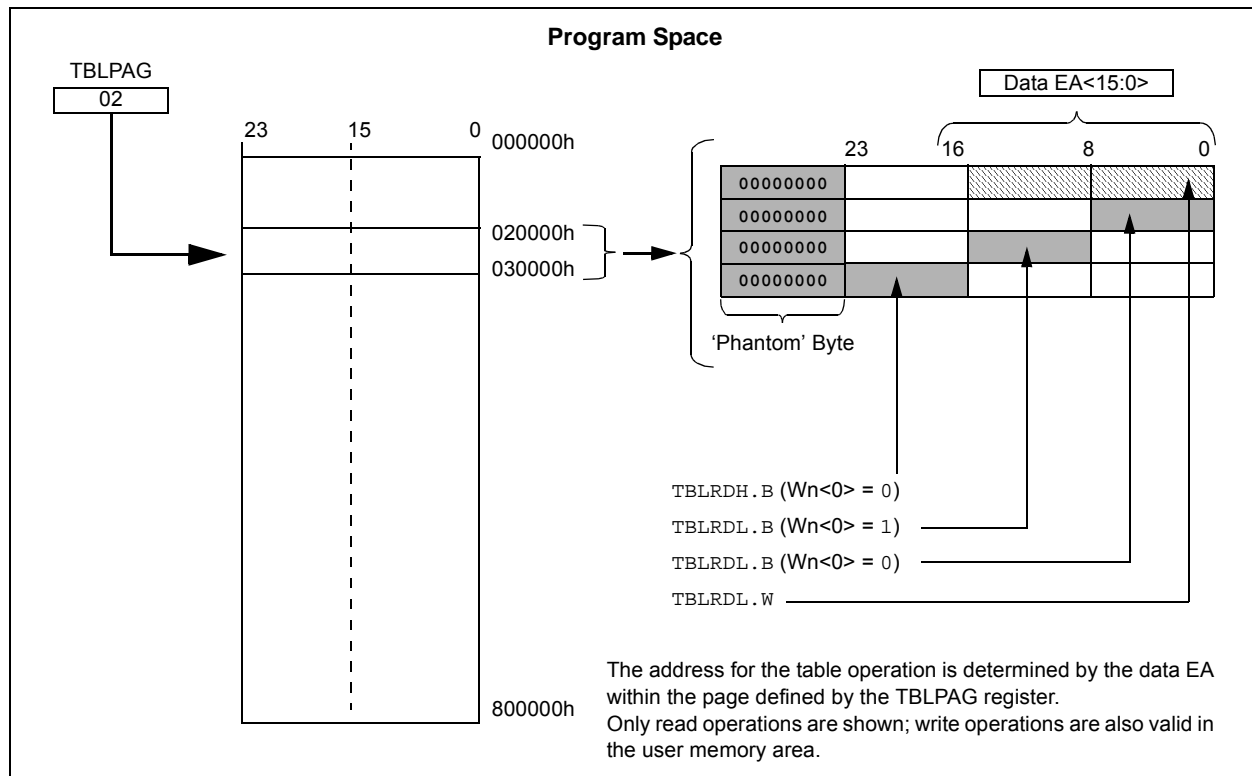
2. **TBLRDH** (Table Read High): In Word mode, it maps the entire upper word of a program address ( $P<23:16>$ ) to a data address. Note that  $D<15:8>$ , the 'phantom' byte, will always be '0'. In Byte mode, it maps the upper or lower byte of the program word to  $D<7:0>$  of the data address, as above. Note that the data will always be '0' when the upper 'phantom' byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, **TBLWTH** and **TBLWTL**, are used to write individual bytes or words to a program space address. The details of their operation are explained in [Section 5.0 "Flash Program Memory"](#).

For all table operations, the area of program memory space to be accessed is determined by the Table Memory Page Address register (**TBLPAG**). **TBLPAG** covers the entire program memory space of the device, including user and configuration spaces. When  $TBLPAG<7> = 0$ , the table page is located in the user memory space. When  $TBLPAG<7> = 1$ , the page is located in configuration space.

**Note:** Only table read operations will execute in the configuration memory space, and only then, in implemented areas, such as the Device ID. Table write operations are not allowed.

**FIGURE 4-6: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS**



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## 4.3.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of data space may optionally be mapped into any 16K word page of the program space. This provides transparent access of stored constant data from the data space without the need to use special instructions (i.e., `TBLRDH/H`).

Program space access through the data space occurs if the Most Significant bit of the data space EA is '1' and Program Space Visibility is enabled by setting the PSV bit in the CPU Control register (`CORCON<2>`). The location of the program memory space to be mapped into the data space is determined by the Program Space Visibility Page Address register (`PSVPAG`). This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, `PSVPAG` functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits. Note that by incrementing the PC by 2 for each program memory word, the lower 15 bits of data space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads to this area add an additional cycle to the instruction being executed, since two program memory fetches are required.

Although each data space address, 8000h and higher, maps directly into a corresponding program memory address (see Figure 4-7), only the lower 16 bits of the

24-bit program word are used to contain the data. The upper 8 bits of any program space locations used as data should be programmed with '1111 1111' or '0000 0000' to force a NOP. This prevents possible issues should the area of code ever be accidentally executed.

**Note:** PSV access is temporarily disabled during table reads/writes.

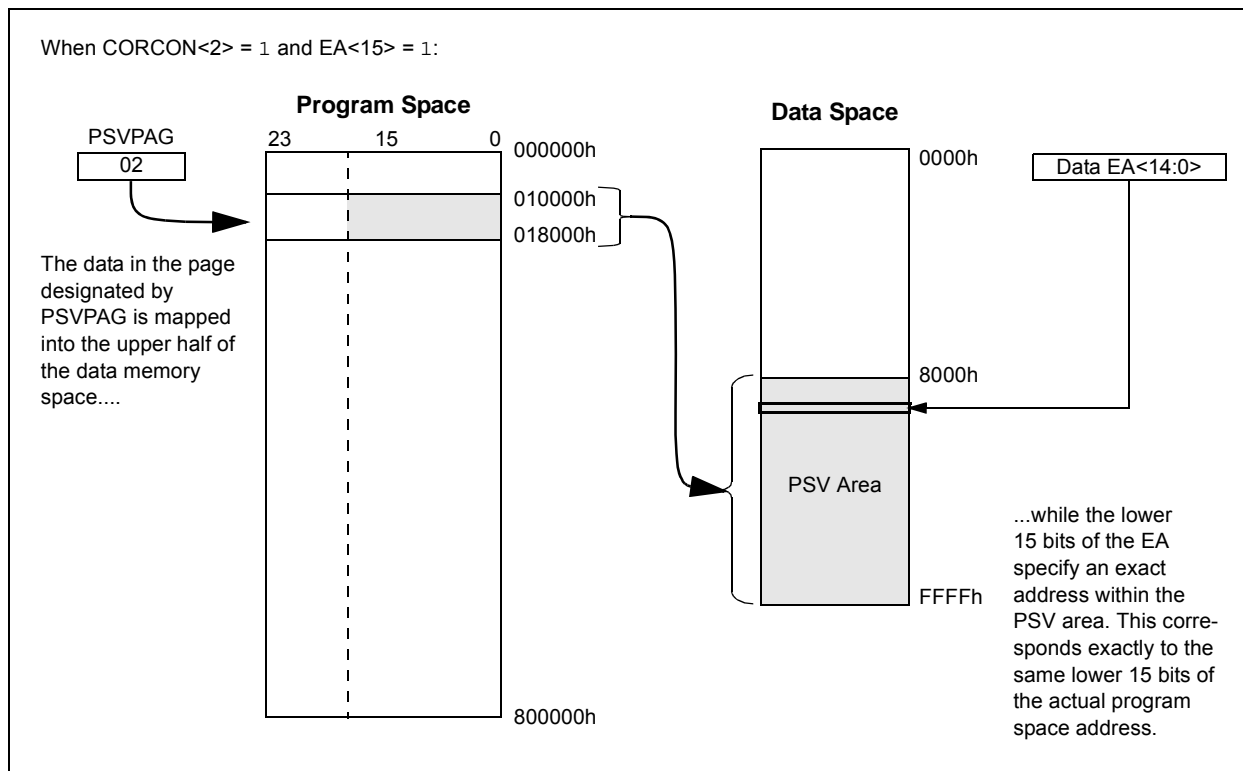
For operations that use PSV and are executed outside a `REPEAT` loop, the `MOV` and `MOV.D` instructions will require one instruction cycle in addition to the specified execution time. All other instructions will require two instruction cycles in addition to the specified execution time.

For operations that use PSV which are executed inside a `REPEAT` loop, there will be some instances that require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the `REPEAT` loop will allow the instruction accessing data, using PSV, to execute in a single cycle.

**FIGURE 4-7: PROGRAM SPACE VISIBILITY OPERATION**



# PIC24FJ64GA004 FAMILY

## 5.0 FLASH PROGRAM MEMORY

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Program Memory” (DS39715).

The PIC24FJ64GA004 family of devices contains internal Flash program memory for storing and executing application code. The memory is readable, writable and erasable when operating with VDD over 2.25V.

Flash memory can be programmed in three ways:

- In-Circuit Serial Programming™ (ICSP™)
- Run-Time Self-Programming (RTSP)
- Enhanced In-Circuit Serial Programming (Enhanced ICSP)

ICSP allows a PIC24FJ64GA004 family device to be serially programmed while in the end application circuit. This is simply done with two lines for the programming clock and programming data (which are named PGCx and PGDx, respectively), and three other lines for power (VDD), ground (VSS) and Master Clear (MCLR). This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

RTSP is accomplished using TBLRD (Table Read) and TBLWT (Table Write) instructions. With RTSP, the user may write program memory data in blocks of 64 instructions (192 bytes) at a time and erase program memory in blocks of 512 instructions (1536 bytes) at a time.

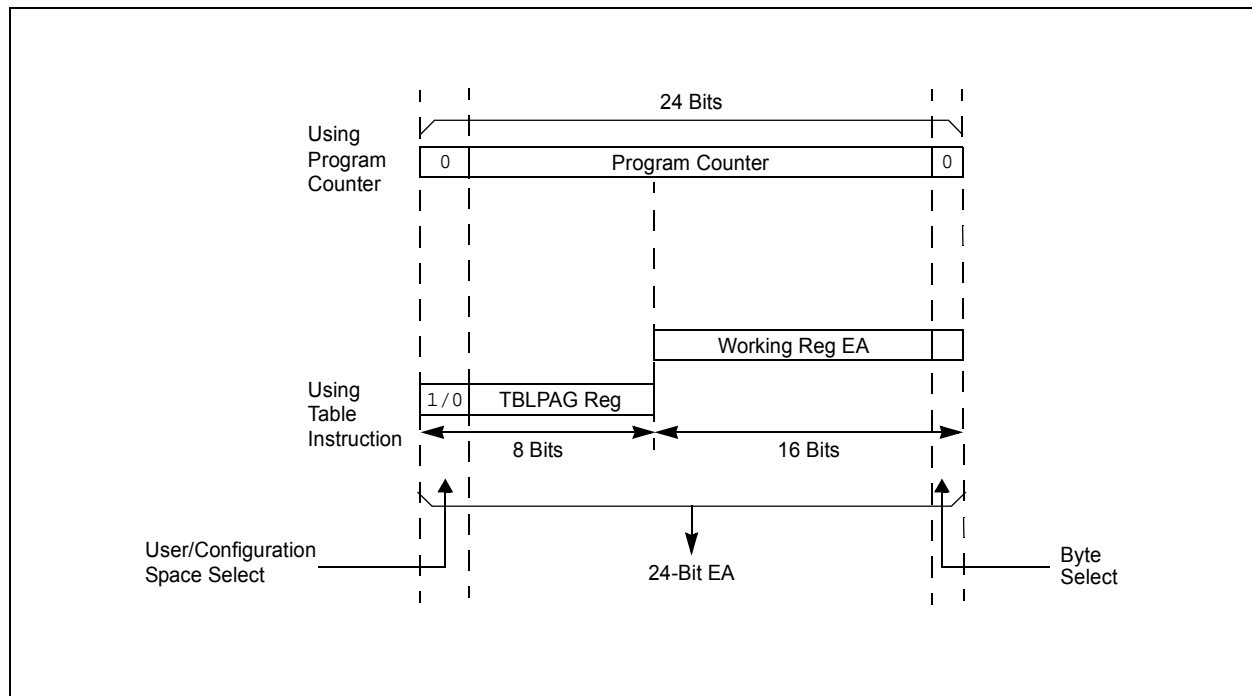
### 5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the table read and table write instructions. These allow direct read and write access to the program memory space from the data memory while the device is in normal operating mode. The 24-bit target address in the program memory is formed using the TBLPAG<7:0> bits and the Effective Address (EA) from a W register, specified in the table instruction, as shown in Figure 5-1.

The TBLRDL and the TBLWTL instructions are used to read or write to bits<15:0> of program memory. TBLRDL and TBLWTL can access program memory in both Word and Byte modes.

The TBLRDH and TBLWTH instructions are used to read or write to bits<23:16> of program memory. TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

**FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS**





# PIC24FJ64GA004 FAMILY

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## 5.2 RTSP Operation

The PIC24F Flash program memory array is organized into rows of 64 instructions or 192 bytes. RTSP allows the user to erase blocks of eight rows (512 instructions) at a time and to program one row at a time. It is also possible to program single words.

The 8-row erase blocks and single row write blocks are edge-aligned, from the beginning of program memory, on boundaries of 1536 bytes and 192 bytes, respectively.

When data is written to program memory using `TBLWT` instructions, the data is not written directly to memory. Instead, data written using table writes is stored in holding latches until the programming sequence is executed.

Any number of `TBLWT` instructions can be executed and a write will be successfully performed. However, 64 `TBLWT` instructions are required to write the full row of memory.

To ensure that no data is corrupted during a write, any unused addresses should be programmed with `FFFFFFh`. This is because the holding latches reset to an unknown state, so if the addresses are left in the Reset state, they may overwrite the locations on rows which were not rewritten.

The basic sequence for RTSP programming is to set up a Table Pointer, then do a series of `TBLWT` instructions to load the buffers. Programming is performed by setting the control bits in the `NVMCON` register.

Data can be loaded in any order and the holding registers can be written to multiple times before performing a write operation. Subsequent writes, however, will wipe out any previous writes.

<b>Note:</b> Writing to a location multiple times without erasing it is <i>not</i> recommended.
-------------------------------------------------------------------------------------------------

All of the table write operations are single-word writes (2 instruction cycles), because only the buffers are written. A programming cycle is required for programming each row.

## 5.3 Enhanced In-Circuit Serial Programming

Enhanced In-Circuit Serial Programming uses an on-board bootloader, known as the Program Executive (PE), to manage the programming process. Using an SPI data frame format, the Program Executive can erase, program and verify program memory. For more information on Enhanced ICSP, see the device programming specification.

## 5.4 Control Registers

There are two SFRs used to read and write the program Flash memory: `NVMCON` and `NVMKEY`.

The `NVMCON` register ([Register 5-1](#)) controls which blocks are to be erased, which memory type is to be programmed and when the programming cycle starts.

`NVMKEY` is a write-only register that is used for write protection. To start a programming or erase sequence, the user must consecutively write `55h` and `AAh` to the `NVMKEY` register. Refer to [Section 5.5 “Programming Operations”](#) for further details.

## 5.5 Programming Operations

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. During a programming or erase operation, the processor stalls (waits) until the operation is finished. Setting the `WR` bit (`NVMCON<15>`) starts the operation and the `WR` bit is automatically cleared when the operation is finished.

Configuration Word values are stored in the last two locations of program memory. Performing a page erase operation on the last page of program memory clears these values and enables code protection. As a result, avoid performing page erase operations on the last page of program memory.



# PIC24FJ64GA004 FAMILY

## REGISTER 5-1: NVMCON: FLASH MEMORY CONTROL REGISTER

R/SO-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	ERASE	—	—	NVMOP3 <sup>(1)</sup>	NVMOP2 <sup>(1)</sup>	NVMOP1 <sup>(1)</sup>	NVMOP0 <sup>(1)</sup>
bit 7							bit 0

<b>Legend:</b>	SO = Settable Only bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **WR:** Write Control bit  
1 = Initiates a Flash memory program or erase operation; the operation is self-timed and the bit is cleared by hardware once operation is complete  
0 = Program or erase operation is complete and inactive
- bit 14      **WREN:** Write Enable bit  
1 = Enables Flash program/erase operations  
0 = Inhibits Flash program/erase operations
- bit 13      **WRERR:** Write Sequence Error Flag bit  
1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit)  
0 = The program or erase operation completed normally
- bit 12-7    **Unimplemented:** Read as '0'
- bit 6        **ERASE:** Erase/Program Enable bit  
1 = Performs the erase operation specified by the NVMOP<3:0> bits on the next WR command  
0 = Performs the program operation specified by the NVMOP<3:0> bits on the next WR command
- bit 5-4     **Unimplemented:** Read as '0'
- bit 3-0     **NVMOP<3:0>:** NVM Operation Select bits<sup>(1)</sup>  
1111 = Memory bulk erase operation (ERASE = 1) or no operation (ERASE = 0)<sup>(2)</sup>  
0011 = Memory word program operation (ERASE = 0) or no operation (ERASE = 1)  
0010 = Memory page erase operation (ERASE = 1) or no operation (ERASE = 0)  
0001 = Memory row program operation (ERASE = 0) or no operation (ERASE = 1)

- Note 1:** All other combinations of NVMOP<3:0> are unimplemented.  
**Note 2:** Available in ICSP™ mode only. Refer to the device programming specifications.

# PIC24FJ64GA004 FAMILY

## 5.5.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

The user can program one row of Flash program memory at a time. To do this, it is necessary to erase the 8-row erase block containing the desired row. The general process is:

1. Read eight rows of program memory (512 instructions) and store in data RAM.
2. Update the program data in RAM with the desired new data.
3. Erase the block (see [Example 5-1](#)):
  - a) Set the NVMOPx bits (NVMCON<3:0>) to '0010' to configure for block erase. Set the ERASE (NVMCON<6>) and WREN (NVMCON<14>) bits.
  - b) Write the starting address of the block to be erased into the TBLPAG and W registers.
  - c) Write 55h to NVMKEY.
  - d) Write AAh to NVMKEY.
  - e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.
4. Write the first 64 instructions from data RAM into the program memory buffers (see [Example 5-1](#)).
5. Write the program block to Flash memory:
  - a) Set the NVMOPx bits to '0001' to configure for row programming. Clear the ERASE bit and set the WREN bit.
  - b) Write 55h to NVMKEY.
  - c) Write AAh to NVMKEY.
  - d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
6. Repeat Steps 4 and 5, using the next available 64 instructions from the block in data RAM by incrementing the value in TBLPAG, until all 512 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPs, as shown in [Example 5-3](#).

### EXAMPLE 5-1: ERASING A PROGRAM MEMORY BLOCK

```
; Set up NVMCON for block erase operation
MOV    #0x4042, W0          ;
MOV    W0, NVMCON           ; Initialize NVMCON
; Init pointer to row to be ERASED
MOV    #tblpage(PROG_ADDR), W0 ;
MOV    W0, TBLPAG           ; Initialize PM Page Boundary SFR
MOV    #tbloffset(PROG_ADDR), W0 ; Initialize in-page EA[15:0] pointer
TBLWTL W0, [W0]             ; Set base address of erase block
DISI    #5                  ; Block all interrupts with priority <7
                        ; for next 5 instructions

MOV    #0x55, W0
MOV    W0, NVMKEY           ; Write the 55 key
MOV    #0xAA, W1
MOV    W1, NVMKEY           ; Write the AA key
BSET    NVMCON, #WR         ; Start the erase sequence
NOP                      ; Insert two NOPs after the erase
NOP                      ; command is asserted
```

# PIC24FJ64GA004 FAMILY

## EXAMPLE 5-2: LOADING THE WRITE BUFFERS

```
; Set up NVMCON for row programming operations
MOV    #0x4001, W0                ;
MOV    W0, NVMCON                 ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
MOV    #0x0000, W0                ;
MOV    W0, TBLPAG                 ; Initialize PM Page Boundary SFR
MOV    #0x6000, W0                ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
MOV    #LOW_WORD_0, W2            ;
MOV    #HIGH_BYTE_0, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
; 1st_program_word
MOV    #LOW_WORD_1, W2            ;
MOV    #HIGH_BYTE_1, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
; 2nd_program_word
MOV    #LOW_WORD_2, W2            ;
MOV    #HIGH_BYTE_2, W3          ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0++]                ; Write PM high byte into program latch
.
.
.
; 63rd_program_word
MOV    #LOW_WORD_31, W2           ;
MOV    #HIGH_BYTE_31, W3         ;
TBLWTL W2, [W0]                  ; Write PM low word into program latch
TBLWTH W3, [W0]                  ; Write PM high byte into program latch
```

## EXAMPLE 5-3: INITIATING A PROGRAMMING SEQUENCE

```
DISI    #5                        ; Block all interrupts with priority <7
                                           ; for next 5 instructions
MOV     #0x55, W0
MOV     W0, NVMKEY                 ; Write the 55 key
MOV     #0xAA, W1
MOV     W1, NVMKEY                 ; Write the AA key
BSET    NVMCON, #WR               ; Start the erase sequence
NOP                                           ; 2 NOPs required after setting WR
NOP                                           ;
BTSC    NVMCON, #15               ; Wait for the sequence to be completed
BRA     $-2                       ;
```

# PIC24FJ64GA004 FAMILY

## 5.5.2 PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY

If a Flash location has been erased, it can be programmed using table write instructions to write an instruction word (24-bit) into the write latch. The TBLPAG register is loaded with the 8 Most Significant Bytes of the Flash address. The TBLWTL and TBLWTH

instructions write the desired data into the write latches and specify the lower 16 bits of the program memory address to write to. To configure the NVMCON register for a word write, set the NVMOPx bits (NVMCON<3:0>) to '0011'. The write is performed by executing the unlock sequence and setting the WR bit (see [Example 5-4](#)).

### EXAMPLE 5-4: PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY

```
; Setup a pointer to data Program Memory
MOV    #tblpage(PROG_ADDR), W0      ;
MOV    W0, TBLPAG                   ;Initialize PM Page Boundary SFR
MOV    #tbloffset(PROG_ADDR), W0    ;Initialize a register with program memory address

MOV    #LOW_WORD_N, W2               ;
MOV    #HIGH_BYTE_N, W3             ;
TBLWTL W2, [W0]                     ; Write PM low word into program latch
TBLWTH W3, [W0++]                   ; Write PM high byte into program latch

; Setup NVMCON for programming one word to data Program Memory
MOV    #0x4003, W0                  ;
MOV    W0, NVMCON                   ; Set NVMOP bits to 0011

DISI    #5                          ; Disable interrupts while the KEY sequence is written
MOV    #0x55, W0                    ; Write the key sequence
MOV    W0, NVMKEY
MOV    #0xAA, W0
MOV    W0, NVMKEY
BSET    NVMCON, #WR                 ; Start the write cycle
NOP                                           ; 2 NOPs required after setting WR
NOP                                           ;
```

# PIC24FJ64GA004 FAMILY

## 6.0 RESETS

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Reset” (DS39712).

The Reset module combines all Reset sources and controls the device Master Reset Signal,  $\overline{\text{SYSRST}}$ . The following is a list of device Reset sources:

- POR: Power-on Reset
- MCLR: Pin Reset
- SWR: RESET Instruction
- WDT: Watchdog Timer Reset
- BOR: Brown-out Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- IOPUWR: Illegal Opcode Reset
- UWR: Uninitialized W Register Reset

A simplified block diagram of the Reset module is shown in [Figure 6-1](#).

Any active source of Reset will make the  $\overline{\text{SYSRST}}$  signal active. Many registers associated with the CPU and peripherals are forced to a known Reset state. Most registers are unaffected by a Reset; their status is unknown on POR and unchanged by all other Resets.

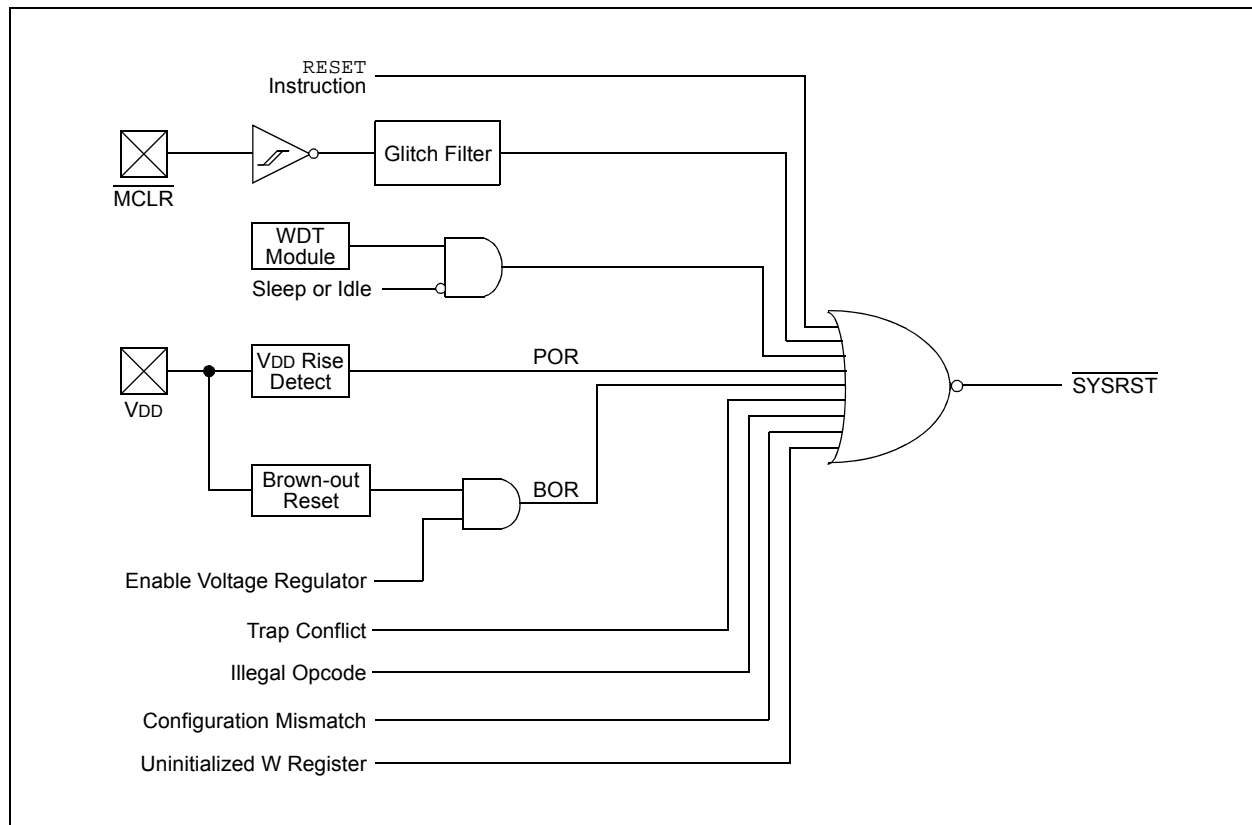
**Note:** Refer to the specific peripheral or CPU section of this manual for register Reset states.

All types of device Reset will set a corresponding status bit in the RCON register to indicate the type of Reset (see [Register 6-1](#)). A Power-on Reset will clear all bits except for the BOR and POR bits ( $\text{RCON}<1:0>$ ) which are set. The user may set or clear any bit at any time during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software will not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this manual.

**Note:** The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset will be meaningful.

**FIGURE 6-1: RESET SYSTEM BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## REGISTER 6-1: RCON: RESET CONTROL REGISTER<sup>(1)</sup>

R/W-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
TRAPR	IOPUWR	—	—	—	—	CM	PMSLP
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EXTR	SWR	SWDTEN <sup>(2)</sup>	WDTO	SLEEP	IDLE	BOR	POR
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **TRAPR:** Trap Reset Flag bit  
1 = A Trap Conflict Reset has occurred  
0 = A Trap Conflict Reset has not occurred
- bit 14 **IOPUWR:** Illegal Opcode or Uninitialized W Access Reset Flag bit  
1 = An illegal opcode detection, an illegal address mode or Uninitialized W register used as an Address Pointer caused a Reset  
0 = An illegal opcode or Uninitialized W register Reset has not occurred
- bit 13-10 **Unimplemented:** Read as '0'
- bit 9 **CM:** Configuration Word Mismatch Reset Flag bit  
1 = A Configuration Word Mismatch Reset has occurred  
0 = A Configuration Word Mismatch Reset has not occurred
- bit 8 **PMSLP:** Program Memory Power During Sleep bit  
1 = Program memory bias voltage remains powered during Sleep  
0 = Program memory bias voltage is powered down during Sleep and voltage regulator enters Standby mode
- bit 7 **EXTR:** External Reset ( $\overline{\text{MCLR}}$ ) Pin bit  
1 = A Master Clear (pin) Reset has occurred  
0 = A Master Clear (pin) Reset has not occurred
- bit 6 **SWR:** Software Reset (Instruction) Flag bit  
1 = A RESET instruction has been executed  
0 = A RESET instruction has not been executed
- bit 5 **SWDTEN:** Software Enable/Disable of WDT bit<sup>(2)</sup>  
1 = WDT is enabled  
0 = WDT is disabled
- bit 4 **WDTO:** Watchdog Timer Time-out Flag bit  
1 = WDT time-out has occurred  
0 = WDT time-out has not occurred
- bit 3 **SLEEP:** Wake from Sleep Flag bit  
1 = Device has been in Sleep mode  
0 = Device has not been in Sleep mode

**Note 1:** All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

**2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

# PIC24FJ64GA004 FAMILY

## REGISTER 6-1: RCON: RESET CONTROL REGISTER<sup>(1)</sup> (CONTINUED)

- bit 2      **IDLE:** Wake-up from Idle Flag bit  
1 = Device has been in Idle mode  
0 = Device has not been in Idle mode
- bit 1      **BOR:** Brown-out Reset Flag bit  
1 = A Brown-out Reset has occurred (note that BOR is also set after a Power-on Reset)  
0 = A Brown-out Reset has not occurred
- bit 0      **POR:** Power-on Reset Flag bit  
1 = A Power-on Reset has occurred  
0 = A Power-on Reset has not occurred

**Note 1:** All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

**2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

**TABLE 6-1: RESET FLAG BIT OPERATION**

Flag Bit	Setting Event	Clearing Event
TRAPR (RCON<15>)	Trap Conflict Event	POR
IOPUWR (RCON<14>)	Illegal Opcode or Uninitialized W Register Access	POR
CM (RCON<9>)	Configuration Mismatch Reset	POR
EXTR (RCON<7>)	MCLR Reset	POR
SWR (RCON<6>)	RESET Instruction	POR
WDTO (RCON<4>)	WDT Time-out	PWRSV Instruction, POR
SLEEP (RCON<3>)	PWRSV #SLEEP Instruction	POR
IDLE (RCON<2>)	PWRSV #IDLE Instruction	POR
BOR (RCON<1>)	POR, BOR	—
POR (RCON<0>)	POR	—

**Note:** All Reset flag bits may be set or cleared by the user software.

# PIC24FJ64GA004 FAMILY

## 6.1 Clock Source Selection at Reset

If clock switching is enabled, the system clock source at device Reset is chosen, as shown in [Table 6-2](#). If clock switching is disabled, the system clock source is always selected according to the Oscillator Configuration bits. Refer to [Section 8.0 “Oscillator Configuration”](#) for further details.

**TABLE 6-2: OSCILLATOR SELECTION vs. TYPE OF RESET (CLOCK SWITCHING ENABLED)**

Reset Type	Clock Source Determinant
POR	FNOSC<2:0> Configuration bits (CW2<10:8>)
BOR	
MCLR	COSC<2:0> Control bits (OSCCON<14:12>)
WDTO	
SWR	

## 6.2 Device Reset Times

The Reset times for various types of device Reset are summarized in [Table 6-3](#). Note that the system Master Reset Signal,  $\overline{\text{SYSRST}}$ , is released after the POR and PWRT delay times expire.

The time that the device actually begins to execute code will also depend on the system oscillator delays, which include the Oscillator Start-up Timer (OST) and the PLL lock time. The OST and PLL lock times occur in parallel with the applicable  $\overline{\text{SYSRST}}$  delay times.

The FSCM delay determines the time at which the FSCM begins to monitor the system clock source after the  $\overline{\text{SYSRST}}$  signal is released.

**TABLE 6-3: RESET DELAY TIMES FOR VARIOUS DEVICE RESETS**

Reset Type	Clock Source	$\overline{\text{SYSRST}}$ Delay	System Clock Delay	Notes
POR <sup>(6)</sup>	EC	TPOR + TPWRT + TRST	—	<a href="#">1</a> , <a href="#">2</a> , <a href="#">7</a>
	FRC, FRCDIV	TPOR + TPWRT + TRST	TFRC	<a href="#">1</a> , <a href="#">2</a> , <a href="#">3</a> , <a href="#">7</a>
	LPRC	TPOR + TPWRT + TRST	TLPRC	<a href="#">1</a> , <a href="#">2</a> , <a href="#">3</a> , <a href="#">7</a>
	ECPLL	TPOR + TPWRT + TRST	TLOCK	<a href="#">1</a> , <a href="#">2</a> , <a href="#">4</a> , <a href="#">7</a>
	FRCPLL	TPOR + TPWRT + TRST	TFRC + TLOCK	<a href="#">1</a> , <a href="#">2</a> , <a href="#">3</a> , <a href="#">4</a> , <a href="#">7</a>
	XT, HS, SOSC	TPOR + TPWRT + TRST	TOST	<a href="#">1</a> , <a href="#">2</a> , <a href="#">5</a> , <a href="#">7</a>
	XTPLL, HSPLL	TPOR + TPWRT + TRST	TOST + TLOCK	<a href="#">1</a> , <a href="#">2</a> , <a href="#">4</a> , <a href="#">5</a> , <a href="#">7</a>
BOR	EC	TPWRT + TRST	—	<a href="#">2</a> , <a href="#">7</a>
	FRC, FRCDIV	TPWRT + TRST	TFRC	<a href="#">2</a> , <a href="#">3</a> , <a href="#">7</a>
	LPRC	TPWRT + TRST	TLPRC	<a href="#">2</a> , <a href="#">3</a> , <a href="#">7</a>
	ECPLL	TPWRT + TRST	TLOCK	<a href="#">2</a> , <a href="#">4</a> , <a href="#">7</a>
	FRCPLL	TPWRT + TRST	TFRC + TLOCK	<a href="#">2</a> , <a href="#">3</a> , <a href="#">4</a> , <a href="#">7</a>
	XT, HS, SOSC	TPWRT + TRST	TOST	<a href="#">2</a> , <a href="#">5</a> , <a href="#">7</a>
	XTPLL, HSPLL	TPWRT + TRST	TFRC + TLOCK	<a href="#">2</a> , <a href="#">3</a> , <a href="#">4</a> , <a href="#">7</a>
All Others	Any Clock	TRST	—	<a href="#">7</a>

**Note 1:** TPOR = Power-on Reset delay.

**2:** TPWRT = 64 ms nominal if regulator is disabled (ENVREG tied to Vss).

**3:** TFRC and TLPRC = RC Oscillator Start-up Times.

**4:** TLOCK = PLL Lock Time.

**5:** TOST = Oscillator Start-up Timer (OST). A 10-bit counter waits 1024 oscillator periods before releasing the oscillator clock to the system.

**6:** If Two-Speed Start-up is enabled, regardless of the primary oscillator selected, the device starts with FRC, and in such cases, FRC start-up time is valid.

**7:** TRST = Internal State Reset Timer



## 6.2.1 POR AND LONG OSCILLATOR START-UP TIMES

The oscillator start-up circuitry and its associated delay timers are not linked to the device Reset delays that occur at power-up. Some crystal circuits (especially low-frequency crystals) will have a relatively long start-up time. Therefore, one or more of the following conditions is possible after `SYSRST` is released:

- The oscillator circuit has not begun to oscillate.
- The Oscillator Start-up Timer has not expired (if a crystal oscillator is used).
- The PLL has not achieved a lock (if PLL is used).

The device will not begin to execute code until a valid clock source has been released to the system. Therefore, the oscillator and PLL start-up delays must be considered when the Reset delay time must be known.

## 6.2.2 FAIL-SAFE CLOCK MONITOR (FSCM) AND DEVICE RESETS

If the FSCM is enabled, it will begin to monitor the system clock source when `SYSRST` is released. If a valid clock source is not available at this time, the device will automatically switch to the FRC oscillator and the user can switch to the desired crystal oscillator in the Trap Service Routine.

## 6.2.2.1 FSCM Delay for Crystal and PLL Clock Sources

When the system clock source is provided by a crystal oscillator and/or the PLL, a small delay, `TFSCM`, will automatically be inserted after the POR and `PWRT` delay times. The FSCM will not begin to monitor the system clock source until this delay expires. The FSCM delay time is nominally 100  $\mu$ s and provides additional time for the oscillator and/or PLL to stabilize. In most cases, the FSCM delay will prevent an oscillator failure trap at a device Reset when the `PWRT` is disabled.

## 6.3 Special Function Register Reset States

Most of the Special Function Registers (SFRs) associated with the PIC24F CPU and peripherals are reset to a particular value at a device Reset. The SFRs are grouped by their peripheral or CPU function and their Reset values are specified in each section of this manual.

The Reset value for each SFR does not depend on the type of Reset, with the exception of four registers. The Reset value for the Reset Control register, `RCON`, will depend on the type of device Reset. The Reset value for the Oscillator Control register, `OSCCON`, will depend on the type of Reset and the programmed values of the `FNOSCx` bits in the `CW2` register (see [Table 6-2](#)). The `RCFGCAL` and `NVMCON` registers are only affected by a POR.

# PIC24FJ64GA004 FAMILY

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NOTES:

## 7.0 INTERRUPT CONTROLLER

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Interrupts” (DS39707).

The PIC24F interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the PIC24F CPU. It has the following features:

- Up to 8 processor exceptions and software traps
- 7 user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- A unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

### 7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) is shown in [Figure 7-1](#). The IVT resides in program memory, starting at location, 000004h. The IVT contains 126 vectors, consisting of 8 non-maskable trap vectors, plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority; this is linked to their position in the vector table. All other things being equal, lower addresses have a higher natural priority. For example, the interrupt associated with Vector 0 will take priority over interrupts at any other vector address.

PIC24FJ64GA004 family devices implement non-maskable traps and unique interrupts. These are summarized in [Table 7-1](#) and [Table 7-2](#).

### 7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in [Figure 7-1](#). Access to the AIVT is provided by the ALTIVT control bit (INTCON2<15>). If the ALTIVT bit is set, all interrupt and exception processes will use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

The AIVT supports emulation and debugging efforts by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

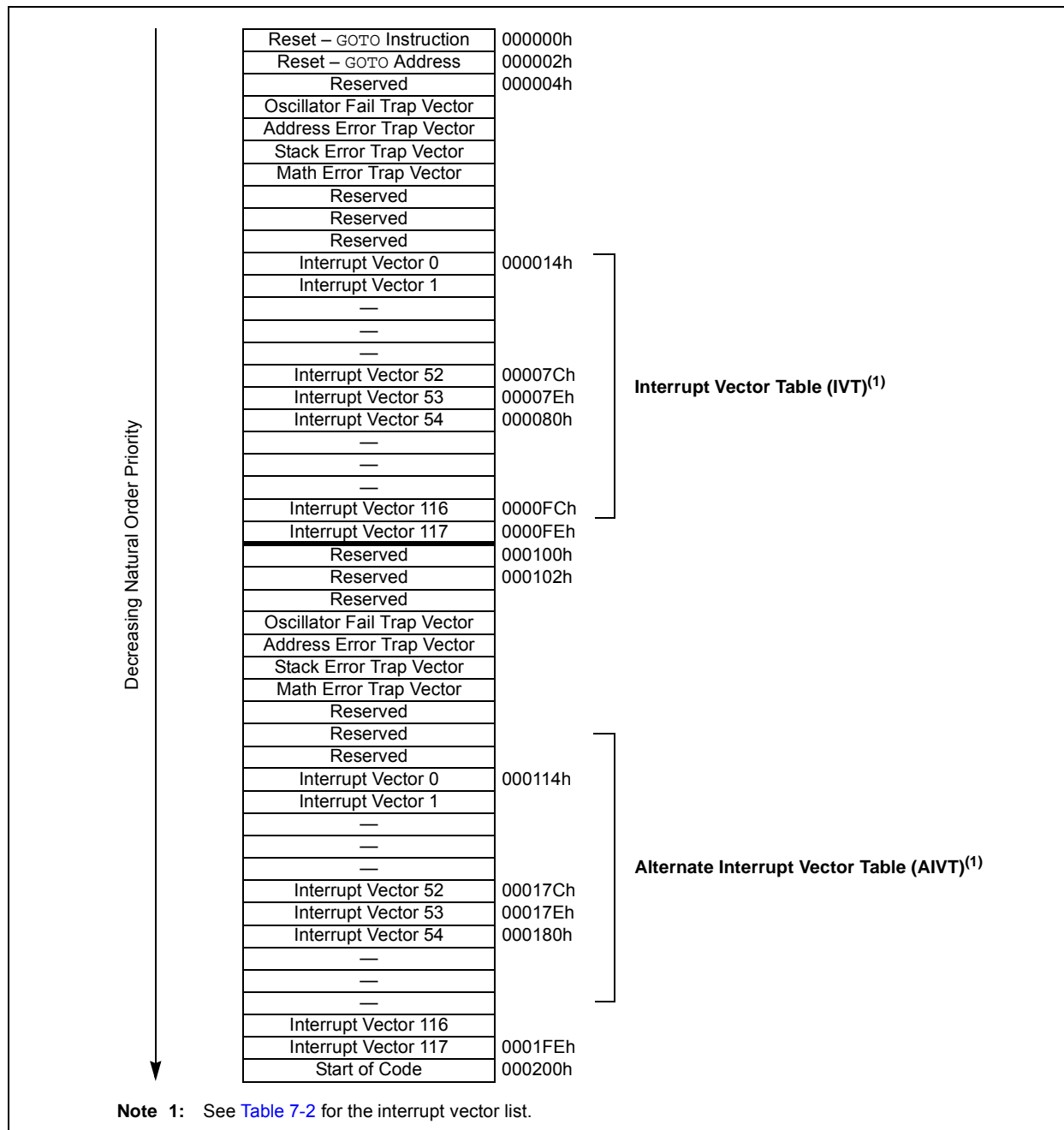
## 7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The PIC24F devices clear their registers in response to a Reset which forces the PC to zero. The microcontroller then begins program execution at location, 000000h. The user programs a GOTO instruction at the Reset address, which redirects program execution to the appropriate start-up routine.

**Note:** Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

# PIC24FJ64GA004 FAMILY

**FIGURE 7-1: PIC24F INTERRUPT VECTOR TABLE**



**TABLE 7-1: TRAP VECTOR DETAILS**

Vector Number	IVT Address	AIVT Address	Trap Source
0	000004h	000104h	Reserved
1	000006h	000106h	Oscillator Failure
2	000008h	000108h	Address Error
3	00000Ah	00010Ah	Stack Error
4	00000Ch	00010Ch	Math Error
5	00000Eh	00010Eh	Reserved
6	000010h	000110h	Reserved
7	000012h	000112h	Reserved

# PIC24FJ64GA004 FAMILY

**TABLE 7-2: IMPLEMENTED INTERRUPT VECTORS**

Interrupt Source	Vector Number	IVT Address	AIVT Address	Interrupt Bit Locations		
				Flag	Enable	Priority
ADC1 Conversion Done	13	00002Eh	00012Eh	IFS0<13>	IEC0<13>	IPC3<6:4>
Comparator Event	18	000038h	000138h	IFS1<2>	IEC1<2>	IPC4<10:8>
CRC Generator	67	00009Ah	00019Ah	IFS4<3>	IEC4<3>	IPC16<14:12>
External Interrupt 0	0	000014h	000114h	IFS0<0>	IEC0<0>	IPC0<2:0>
External Interrupt 1	20	00003Ch	00013Ch	IFS1<4>	IEC1<4>	IPC5<2:0>
External Interrupt 2	29	00004Eh	00014Eh	IFS1<13>	IEC1<13>	IPC7<6:4>
I2C1 Master Event	17	000036h	000136h	IFS1<1>	IEC1<1>	IPC4<6:4>
I2C1 Slave Event	16	000034h	000034h	IFS1<0>	IEC1<0>	IPC4<2:0>
I2C2 Master Event	50	000078h	000178h	IFS3<2>	IEC3<2>	IPC12<10:8>
I2C2 Slave Event	49	000076h	000176h	IFS3<1>	IEC3<1>	IPC12<6:4>
Input Capture 1	1	000016h	000116h	IFS0<1>	IEC0<1>	IPC0<6:4>
Input Capture 2	5	00001Eh	00011Eh	IFS0<5>	IEC0<5>	IPC1<6:4>
Input Capture 3	37	00005Eh	00015Eh	IFS2<5>	IEC2<5>	IPC9<6:4>
Input Capture 4	38	000060h	000160h	IFS2<6>	IEC2<6>	IPC9<10:8>
Input Capture 5	39	000062h	000162h	IFS2<7>	IEC2<7>	IPC9<14:12>
Input Change Notification	19	00003Ah	00013Ah	IFS1<3>	IEC1<3>	IPC4<14:12>
Output Compare 1	2	000018h	000118h	IFS0<2>	IEC0<2>	IPC0<10:8>
Output Compare 2	6	000020h	000120h	IFS0<6>	IEC0<6>	IPC1<10:8>
Output Compare 3	25	000046h	000146h	IFS1<9>	IEC1<9>	IPC6<6:4>
Output Compare 4	26	000048h	000148h	IFS1<10>	IEC1<10>	IPC6<10:8>
Output Compare 5	41	000066h	000166h	IFS2<9>	IEC2<9>	IPC10<6:4>
Parallel Master Port	45	00006Eh	00016Eh	IFS2<13>	IEC2<13>	IPC11<6:4>
Real-Time Clock/Calendar	62	000090h	000190h	IFS3<14>	IEC3<14>	IPC15<10:8>
SPI1 Error	9	000026h	000126h	IFS0<9>	IEC0<9>	IPC2<6:4>
SPI1 Event	10	000028h	000128h	IFS0<10>	IEC0<10>	IPC2<10:8>
SPI2 Error	32	000054h	000154h	IFS2<0>	IEC0<0>	IPC8<2:0>
SPI2 Event	33	000056h	000156h	IFS2<1>	IEC2<1>	IPC8<6:4>
Timer1	3	00001Ah	00011Ah	IFS0<3>	IEC0<3>	IPC0<14:12>
Timer2	7	000022h	000122h	IFS0<7>	IEC0<7>	IPC1<14:12>
Timer3	8	000024h	000124h	IFS0<8>	IEC0<8>	IPC2<2:0>
Timer4	27	00004Ah	00014Ah	IFS1<11>	IEC1<11>	IPC6<14:12>
Timer5	28	00004Ch	00014Ch	IFS1<12>	IEC1<12>	IPC7<2:0>
UART1 Error	65	000096h	000196h	IFS4<1>	IEC4<1>	IPC16<6:4>
UART1 Receiver	11	00002Ah	00012Ah	IFS0<11>	IEC0<11>	IPC2<14:12>
UART1 Transmitter	12	00002Ch	00012Ch	IFS0<12>	IEC0<12>	IPC3<2:0>
UART2 Error	66	000098h	000198h	IFS4<2>	IEC4<2>	IPC16<10:8>
UART2 Receiver	30	000050h	000150h	IFS1<14>	IEC1<14>	IPC7<10:8>
UART2 Transmitter	31	000052h	000152h	IFS1<15>	IEC1<15>	IPC7<14:12>
Low-Voltage Detect (LVD)	72	0000A4h	000124h	IFS4<8>	IEC4<8>	IPC17<2:0>

# PIC24FJ64GA004 FAMILY

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## 7.3 Interrupt Control and Status Registers

The PIC24FJ64GA004 family of devices implements a total of 29 registers for the interrupt controller:

- INTCON1
- INTCON2
- IFS0 through IFS4
- IEC0 through IEC4
- IPC0 through IPC12, IPC15, IPC16 and IPC18
- INTTREG

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable (NSTDIS) bit, as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table.

The IFSx registers maintain all of the interrupt request flags. Each source of interrupt has a status bit which is set by the respective peripherals, or external signal, and is cleared via software.

The IECx registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

The IPCx registers are used to set the Interrupt Priority Level (IPL) for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels.

The INTTREG register contains the associated interrupt vector number and the new CPU Interrupt Priority Level, which are latched into the Vector Number (VECNUM<6:0>) and the Interrupt Level (ILR<3:0>) bit fields in the INTTREG register. The new Interrupt Priority Level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence that they are listed in [Table 7-2](#). For example, the INT0 (External Interrupt 0) is shown as having a vector number and a natural order priority of 0. Thus, the INT0IF status bit is found in IFS0<0>, the INT0IE enable bit in IEC0<0> and the INT0IP<2:0> priority bits in the first position of IPC0 (IPC0<2:0>).

Although they are not specifically part of the interrupt control hardware, two of the CPU control registers contain bits that control interrupt functionality. The ALU STATUS Register (SR) contains the IPL<2:0> bits (SR<7:5>). These indicate the current CPU Interrupt Priority Level. The user may change the current CPU priority level by writing to the IPLx bits.

The CORCON register contains the IPL3 bit, which together with IPL<2:0>, also indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All Interrupt registers are described in [Register 7-1](#) through [Register 7-31](#), in the following pages.

# PIC24FJ64GA004 FAMILY

## REGISTER 7-1: SR: ALU STATUS REGISTER (IN CPU)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	DC <sup>(1)</sup>
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 <sup>(2,3)</sup>	IPL1 <sup>(2,3)</sup>	IPL0 <sup>(2,3)</sup>	RA <sup>(1)</sup>	N <sup>(1)</sup>	OV <sup>(1)</sup>	Z <sup>(1)</sup>	C <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-5      **IPL<2:0>: CPU Interrupt Priority Level Status bits<sup>(2,3)</sup>**

111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled  
 110 = CPU Interrupt Priority Level is 6 (14)  
 101 = CPU Interrupt Priority Level is 5 (13)  
 100 = CPU Interrupt Priority Level is 4 (12)  
 011 = CPU Interrupt Priority Level is 3 (11)  
 010 = CPU Interrupt Priority Level is 2 (10)  
 001 = CPU Interrupt Priority Level is 1 (9)  
 000 = CPU Interrupt Priority Level is 0 (8)

- Note 1:** See [Register 3-1](#) for the description of the remaining bit(s) that are not dedicated to interrupt control functions.
- 2:** The IPLx bits are concatenated with the IPL3 bit (CORCON<3>) to form the CPU interrupt Priority Level. The value in parentheses indicates the Interrupt Priority Level if IPL3 = 1.
- 3:** The IPLx Status bits are read-only when NSTDIS (INTCON1<15>) = 1.

## REGISTER 7-2: CORCON: CPU CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	R/C-0	R/W-0	U-0	U-0
—	—	—	—	IPL3 <sup>(2)</sup>	PSV <sup>(1)</sup>	—	—
bit 7							bit 0

### Legend:

C = Clearable bit  
 R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 3      **IPL3: CPU Interrupt Priority Level Status bit<sup>(2)</sup>**

1 = CPU Interrupt Priority Level is greater than 7  
 0 = CPU Interrupt Priority Level is 7 or less

- Note 1:** See [Register 3-2](#) for the description of the remaining bit(s) that are not dedicated to interrupt control functions.
- 2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt priority Level.

# PIC24FJ64GA004 FAMILY

## REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1

R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
NSTDIS	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
—	—	—	MATHERR	ADDRERR	STKERR	OSCFAIL	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **NSTDIS:** Interrupt Nesting Disable bit  
                  1 = Interrupt nesting is disabled  
                  0 = Interrupt nesting is enabled
- bit 14-5    **Unimplemented:** Read as '0'
- bit 4        **MATHERR:** Arithmetic Error Trap Status bit  
                  1 = Overflow trap has occurred  
                  0 = Overflow trap has not occurred
- bit 3        **ADDRERR:** Address Error Trap Status bit  
                  1 = Address error trap has occurred  
                  0 = Address error trap has not occurred
- bit 2        **STKERR:** Stack Error Trap Status bit  
                  1 = Stack error trap has occurred  
                  0 = Stack error trap has not occurred
- bit 1        **OSCFAIL:** Oscillator Failure Trap Status bit  
                  1 = Oscillator failure trap has occurred  
                  0 = Oscillator failure trap has not occurred
- bit 0        **Unimplemented:** Read as '0'



# PIC24FJ64GA004 FAMILY

## REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2

R/W-0	R-0	U-0	U-0	U-0	U-0	U-0	U-0
ALTIVT	DISI	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	INT2EP	INT1EP	INT0EP
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **ALTIVT:** Enable Alternate Interrupt Vector Table bit  
                  1 = Uses Alternate Interrupt Vector Table  
                  0 = Uses standard (default) Interrupt Vector Table
- bit 14      **DISI:** DISI Instruction Status bit  
                  1 = DISI instruction is active  
                  0 = DISI instruction is not active
- bit 13-3    **Unimplemented:** Read as '0'
- bit 2        **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 1        **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge
- bit 0        **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit  
                  1 = Interrupt on negative edge  
                  0 = Interrupt on positive edge

# PIC24FJ64GA004 FAMILY

## REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPF1IF	T3IF
bit 15							
							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IF	OC2IF	IC2IF	—	T1IF	OC1IF	IC1IF	INT0IF
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **AD1IF:** A/D Conversion Complete Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 12 **U1TXIF:** UART1 Transmitter Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 11 **U1RXIF:** UART1 Receiver Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 10 **SPI1IF:** SPI1 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 9 **SPF1IF:** SPI1 Fault Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 8 **T3IF:** Timer3 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 7 **T2IF:** Timer2 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 6 **OC2IF:** Output Compare Channel 2 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 5 **IC2IF:** Input Capture Channel 2 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **T1IF:** Timer1 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 2 **OC1IF:** Output Compare Channel 1 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred

## REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0 (CONTINUED)

- bit 1      **IC1IF:** Input Capture Channel 1 Interrupt Flag Status bit  
            1 = Interrupt request has occurred  
            0 = Interrupt request has not occurred
- bit 0      **INT0IF:** External Interrupt 0 Flag Status bit  
            1 = Interrupt request has occurred  
            0 = Interrupt request has not occurred

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## REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **U2TXIF:** UART2 Transmitter Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 14 **U2RXIF:** UART2 Receiver Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 13 **INT2IF:** External Interrupt 2 Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 12 **T5IF:** Timer5 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 11 **T4IF:** Timer4 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 10 **OC4IF:** Output Compare Channel 4 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 9 **OC3IF:** Output Compare Channel 3 Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 8-5 **Unimplemented:** Read as '0'
- bit 4 **INT1IF:** External Interrupt 1 Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 3 **CNIF:** Input Change Notification Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 2 **CMIF:** Comparator Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 1 **MI2C1IF:** Master I2C1 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 0 **SI2C1IF:** Slave I2C1 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred

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## REGISTER 7-7: IFS2: INTERRUPT FLAG STATUS REGISTER 2

U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	U-0
—	—	PMPIF	—	—	—	OC5IF	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
IC5IF	IC4IF	IC3IF	—	—	—	SPI2IF	SPF2IF
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14    **Unimplemented:** Read as '0'
- bit 13      **PMPIF:** Parallel Master Port Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 12-10   **Unimplemented:** Read as '0'
- bit 9        **OC5IF:** Output Compare Channel 5 Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 8        **Unimplemented:** Read as '0'
- bit 7        **IC5IF:** Input Capture Channel 5 Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 6        **IC4IF:** Input Capture Channel 4 Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 5        **IC3IF:** Input Capture Channel 3 Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 4-2      **Unimplemented:** Read as '0'
- bit 1        **SPI2IF:** SPI2 Event Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred
- bit 0        **SPF2IF:** SPI2 Fault Interrupt Flag Status bit
  - 1 = Interrupt request has occurred
  - 0 = Interrupt request has not occurred

# PIC24FJ64GA004 FAMILY

## REGISTER 7-8: IFS3: INTERRUPT FLAG STATUS REGISTER 3

U-0	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0
—	RTCIF	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	U-0
—	—	—	—	—	MI2C2IF	SI2C2IF	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **RTCIF:** Real-Time Clock/Calendar Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 13-3    **Unimplemented:** Read as '0'
- bit 2      **MI2C2IF:** Master I2C2 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 1      **SI2C2IF:** Slave I2C2 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 0      **Unimplemented:** Read as '0'

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## REGISTER 7-9: IFS4: INTERRUPT FLAG STATUS REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	LVDIF
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
—	—	—	—	CRCIF	U2ERIF	U1ERIF	—
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-9      **Unimplemented:** Read as '0'
- bit 8      **LVDIF:** Low-Voltage Detect Interrupt Flag Status bit  
             1 = Interrupt request has occurred  
             0 = Interrupt request has not occurred
- bit 7-4      **Unimplemented:** Read as '0'
- bit 3      **CRCIF:** CRC Generator Interrupt Flag Status bit  
             1 = Interrupt request has occurred  
             0 = Interrupt request has not occurred
- bit 2      **U2ERIF:** UART2 Error Interrupt Flag Status bit  
             1 = Interrupt request has occurred  
             0 = Interrupt request has not occurred
- bit 1      **U1ERIF:** UART1 Error Interrupt Flag Status bit  
             1 = Interrupt request has occurred  
             0 = Interrupt request has not occurred
- bit 0      **Unimplemented:** Read as '0'

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## REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPF1IE	T3IE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IE	OC2IE	IC2IE	—	T1IE	OC1IE	IC1IE	INT0IE <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **AD1IE:** A/D Conversion Complete Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 12 **U1TXIE:** UART1 Transmitter Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 11 **U1RXIE:** UART1 Receiver Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 10 **SPI1IE:** SPI1 Transfer Complete Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 9 **SPF1IE:** SPI1 Fault Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 8 **T3IE:** Timer3 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 7 **T2IE:** Timer2 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 6 **OC2IE:** Output Compare Channel 2 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 5 **IC2IE:** Input Capture Channel 2 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **T1IE:** Timer1 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled

**Note 1:** If INTxIE = 1, this external interrupt input must be configured to an available RPN pin. See [Section 10.4 "Peripheral Pin Select \(PPS\)"](#) for more information.



## REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0 (CONTINUED)

bit 2	<b>OC1IE:</b> Output Compare Channel 1 Interrupt Enable bit 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 1	<b>IC1IE:</b> Input Capture Channel 1 Interrupt Enable bit 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 0	<b>INT0IE:</b> External Interrupt 0 Enable bit <sup>(1)</sup> 1 = Interrupt request is enabled 0 = Interrupt request is not enabled

**Note 1:** If INTxIE = 1, this external interrupt input must be configured to an available RPN pin. See [Section 10.4](#) “**Peripheral Pin Select (PPS)**” for more information.

# PIC24FJ64GA004 FAMILY

## REGISTER 7-11: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
U2TXIE	U2RXIE	INT2IE <sup>(1)</sup>	T5IE	T4IE	OC4IE	OC3IE	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	INT1IE <sup>(1)</sup>	CNIE	CMIE	MI2C1IE	SI2C1IE
bit 7							bit 0

### Legend:

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15      **U2TXIE:** UART2 Transmitter Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 14      **U2RXIE:** UART2 Receiver Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 13      **INT2IE:** External Interrupt 2 Enable bit<sup>(1)</sup>  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 12      **T5IE:** Timer5 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 11      **T4IE:** Timer4 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 10      **OC4IE:** Output Compare Channel 4 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 9        **OC3IE:** Output Compare Channel 3 Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 8-5     **Unimplemented:** Read as '0'
- bit 4        **INT1IE:** External Interrupt 1 Enable bit<sup>(1)</sup>  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 3        **CNIE:** Input Change Notification Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 2        **CMIE:** Comparator Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 1        **MI2C1IE:** Master I2C1 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled
- bit 0        **SI2C1IE:** Slave I2C1 Event Interrupt Enable bit  
1 = Interrupt request is enabled  
0 = Interrupt request is not enabled

**Note 1:** If INTxIE = 1, this external interrupt input must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

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## REGISTER 7-12: IEC2: INTERRUPT ENABLE CONTROL REGISTER 2

U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	U-0
—	—	PMPIE	—	—	—	OC5IE	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
IC5IE	IC4IE	IC3IE	—	—	—	SPI2IE	SPF2IE
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-14    **Unimplemented:** Read as '0'
- bit 13       **PMPIE:** Parallel Master Port Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 12-10   **Unimplemented:** Read as '0'
- bit 9        **OC5IE:** Output Compare Channel 5 Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 8        **Unimplemented:** Read as '0'
- bit 7        **IC5IE:** Input Capture Channel 5 Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 6        **IC4IE:** Input Capture Channel 4 Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 5        **IC3IE:** Input Capture Channel 3 Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 4-2      **Unimplemented:** Read as '0'
- bit 1        **SPI2IE:** SPI2 Event Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 0        **SPF2IE:** SPI2 Fault Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled

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## REGISTER 7-13: IEC3: INTERRUPT ENABLE CONTROL REGISTER 3

U-0	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0
—	RTCIE	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	U-0
—	—	—	—	—	MI2C2IE	SI2C2IE	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **RTCIE:** Real-Time Clock/Calendar Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 13-3    **Unimplemented:** Read as '0'
- bit 2        **MI2C2IE:** Master I2C2 Event Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 1        **SI2C2IE:** Slave I2C2 Event Interrupt Enable bit  
               1 = Interrupt request is enabled  
               0 = Interrupt request is not enabled
- bit 0        **Unimplemented:** Read as '0'

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**REGISTER 7-14: IEC4: INTERRUPT ENABLE CONTROL REGISTER 4**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	LVDIE
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
—	—	—	—	CRCIE	U2ERIE	U1ERIE	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-9     **Unimplemented:** Read as '0'
- bit 8        **LVDIE:** Low-Voltage Detect Interrupt Enable Status bit
  - 1 = Interrupt request is enabled
  - 0 = Interrupt request is not enabled
- bit 7-4     **Unimplemented:** Read as '0'
- bit 3        **CRCIE:** CRC Generator Interrupt Enable bit
  - 1 = Interrupt request is enabled
  - 0 = Interrupt request is not enabled
- bit 2        **U2ERIE:** UART2 Error Interrupt Enable bit
  - 1 = Interrupt request is enabled
  - 0 = Interrupt request is not enabled
- bit 1        **U1ERIE:** UART1 Error Interrupt Enable bit
  - 1 = Interrupt request is enabled
  - 0 = Interrupt request is not enabled
- bit 0        **Unimplemented:** Read as '0'

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## REGISTER 7-15: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T1IP2	T1IP1	T1IP0	—	OC1IP2	OC1IP1	OC1IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **T1IP<2:0>:** Timer1 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OC1IP<2:0>:** Output Compare Channel 1 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IC1IP<2:0>:** Input Capture Channel 1 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **INT0IP<2:0>:** External Interrupt 0 Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

**REGISTER 7-16: IPC1: INTERRUPT PRIORITY CONTROL REGISTER 1**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T2IP2	T2IP1	T2IP0	—	OC2IP2	OC2IP1	OC2IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	IC2IP2	IC2IP1	IC2IP0	—	—	—	—
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>Unimplemented:</b> Read as '0'
bit 14-12	<b>T2IP&lt;2:0&gt;:</b> Timer2 Interrupt Priority bits
	111 = Interrupt is Priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is Priority 1
	000 = Interrupt source is disabled
bit 11	<b>Unimplemented:</b> Read as '0'
bit 10-8	<b>OC2IP&lt;2:0&gt;:</b> Output Compare Channel 2 Interrupt Priority bits
	111 = Interrupt is Priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is Priority 1
	000 = Interrupt source is disabled
bit 7	<b>Unimplemented:</b> Read as '0'
bit 6-4	<b>IC2IP&lt;2:0&gt;:</b> Input Capture Channel 2 Interrupt Priority bits
	111 = Interrupt is Priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is Priority 1
	000 = Interrupt source is disabled
bit 3-0	<b>Unimplemented:</b> Read as '0'

# PIC24FJ64GA004 FAMILY

## REGISTER 7-17: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U1RXIP2	U1RXIP1	U1RXIP0	—	SPI1IP2	SPI1IP1	SPI1IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPF1IP2	SPF1IP1	SPF1IP0	—	T3IP2	T3IP1	T3IP0
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14-12    **U1RXIP<2:0>:** UART1 Receiver Interrupt Priority bits  
               111 = Interrupt is Priority 7 (highest priority interrupt)  
               •  
               •  
               •  
               001 = Interrupt is Priority 1  
               000 = Interrupt source is disabled
- bit 11      **Unimplemented:** Read as '0'
- bit 10-8    **SPI1IP<2:0>:** SPI1 Event Interrupt Priority bits  
               111 = Interrupt is Priority 7 (highest priority interrupt)  
               •  
               •  
               •  
               001 = Interrupt is Priority 1  
               000 = Interrupt source is disabled
- bit 7      **Unimplemented:** Read as '0'
- bit 6-4    **SPF1IP<2:0>:** SPI1 Fault Interrupt Priority bits  
               111 = Interrupt is Priority 7 (highest priority interrupt)  
               •  
               •  
               •  
               001 = Interrupt is Priority 1  
               000 = Interrupt source is disabled
- bit 3      **Unimplemented:** Read as '0'
- bit 2-0    **T3IP<2:0>:** Timer3 Interrupt Priority bits  
               111 = Interrupt is Priority 7 (highest priority interrupt)  
               •  
               •  
               •  
               001 = Interrupt is Priority 1  
               000 = Interrupt source is disabled



# PIC24FJ64GA004 FAMILY

## REGISTER 7-18: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	AD1IP2	AD1IP1	AD1IP0	—	U1TXIP2	U1TXIP1	U1TXIP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **AD1IP<2:0>:** A/D Conversion Complete Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-19: IPC4: INTERRUPT PRIORITY CONTROL REGISTER 4

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CNIP2	CNIP1	CNIP0	—	CMIP2	CMIP1	CMIP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	MI2C1P2	MI2C1P1	MI2C1P0	—	SI2C1P2	SI2C1P1	SI2C1P0
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **Unimplemented:** Read as '0'
- bit 14-12 **CNIP<2:0>:** Input Change Notification Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled
- bit 11 **Unimplemented:** Read as '0'
- bit 10-8 **CMIP<2:0>:** Comparator Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled
- bit 7 **Unimplemented:** Read as '0'
- bit 6-4 **MI2C1P<2:0>:** Master I2C1 Event Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled
- bit 3 **Unimplemented:** Read as '0'
- bit 2-0 **SI2C1P<2:0>:** Slave I2C1 Event Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-20: IPC5: INTERRUPT PRIORITY CONTROL REGISTER 5

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	INT1IP2	INT1IP1	INT1IP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3

**Unimplemented:** Read as '0'

bit 2-0

**INT1IP<2:0>:** External Interrupt 1 Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-21: IPC6: INTERRUPT PRIORITY CONTROL REGISTER 6

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T4IP2	T4IP1	T4IP0	—	OC4IP2	OC4IP1	OC4IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	OC3IP2	OC3IP1	OC3IP0	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **T4IP<2:0>:** Timer4 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OC4IP<2:0>:** Output Compare Channel 4 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **OC3IP<2:0>:** Output Compare Channel 3 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

# PIC24FJ64GA004 FAMILY

## REGISTER 7-22: IPC7: INTERRUPT PRIORITY CONTROL REGISTER 7

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U2TXIP2	U2TXIP1	U2TXIP0	—	U2RXIP2	U2RXIP1	U2RXIP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	INT2IP2	INT2IP1	INT2IP0	—	T5IP2	T5IP1	T5IP0
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>Unimplemented:</b> Read as '0'
bit 14-12	<b>U2TXIP&lt;2:0&gt;:</b> UART2 Transmitter Interrupt Priority bits 111 = Interrupt is Priority 7 (highest priority interrupt) . . . 001 = Interrupt is Priority 1 000 = Interrupt source is disabled
bit 11	<b>Unimplemented:</b> Read as '0'
bit 10-8	<b>U2RXIP&lt;2:0&gt;:</b> UART2 Receiver Interrupt Priority bits 111 = Interrupt is Priority 7 (highest priority interrupt) . . . 001 = Interrupt is Priority 1 000 = Interrupt source is disabled
bit 7	<b>Unimplemented:</b> Read as '0'
bit 6-4	<b>INT2IP&lt;2:0&gt;:</b> External Interrupt 2 Priority bits 111 = Interrupt is Priority 7 (highest priority interrupt) . . . 001 = Interrupt is Priority 1 000 = Interrupt source is disabled
bit 3	<b>Unimplemented:</b> Read as '0'
bit 2-0	<b>T5IP&lt;2:0&gt;:</b> Timer5 Interrupt Priority bits 111 = Interrupt is Priority 7 (highest priority interrupt) . . . 001 = Interrupt is Priority 1 000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-23: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI2IP2	SPI2IP1	SPI2IP0	—	SPF2IP2	SPF2IP1	SPF2IP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **SPI2IP<2:0>:** SPI2 Event Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SPF2IP<2:0>:** SPI2 Fault Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)  
 •  
 •  
 •  
 001 = Interrupt is Priority 1  
 000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-24: IPC9: INTERRUPT PRIORITY CONTROL REGISTER 9

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	IC3IP2	IC3IP1	IC3IP0	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **IC5IP<2:0>:** Input Capture Channel 5 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **IC4IP<2:0>:** Input Capture Channel 4 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IC3IP<2:0>:** Input Capture Channel 3 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

# PIC24FJ64GA004 FAMILY

**REGISTER 7-25: IPC10: INTERRUPT PRIORITY CONTROL REGISTER 10**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	OC5IP2	OC5IP1	OC5IP0	—	—	—	—
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **OC5IP<2:0>:** Output Compare Channel 5 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

**REGISTER 7-26: IPC11: INTERRUPT PRIORITY CONTROL REGISTER 11**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	PMP2IP2	PMP2IP1	PMP2IP0	—	—	—	—
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **PMP2IP<2:0>:** Parallel Master Port Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'



# PIC24FJ64GA004 FAMILY

## REGISTER 7-27: IPC12: INTERRUPT PRIORITY CONTROL REGISTER 12

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	MI2C2P2	MI2C2P1	MI2C2P0
bit 15						bit 8	

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	SI2C2P2	SI2C2P1	SI2C2P0	—	—	—	—
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **MI2C2P<2:0>:** Master I2C2 Event Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SI2C2P<2:0>:** Slave I2C2 Event Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

# PIC24FJ64GA004 FAMILY

## REGISTER 7-28: IPC15: INTERRUPT PRIORITY CONTROL REGISTER 15

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	RTCIP2	RTCIP1	RTCIP0
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **RTCIP<2:0>:** Real-Time Clock/Calendar Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7-0 **Unimplemented:** Read as '0'

# PIC24FJ64GA004 FAMILY

**REGISTER 7-29: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CRCIP2	CRCIP1	CRCIP0	—	U2ERIP2	U2ERIP1	U2ERIP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	U1ERIP2	U1ERIP1	U1ERIP0	—	—	—	—
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **CRCIP<2:0>:** CRC Generator Error Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **U2ERIP<2:0>:** UART2 Error Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **U1ERIP<2:0>:** UART1 Error Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

# PIC24FJ64GA004 FAMILY

## REGISTER 7-30: IPC18: INTERRUPT PRIORITY CONTROL REGISTER 18

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	LVDIP2	LVDIP1	LVDIP0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3

**Unimplemented:** Read as '0'

bit 2-0

**LVDIP<2:0>:** Low-Voltage Detect Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

# PIC24FJ64GA004 FAMILY

## REGISTER 7-31: INTTREG: INTERRUPT CONTROL AND STATUS REGISTER

R-0	U-0	R/W-0	U-0	R-0	R-0	R-0	R-0
CPUIRQ	—	VHOLD	—	ILR3	ILR2	ILR1	ILR0
bit 15							bit 8

U-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
—	VECNUM6	VECNUM5	VECNUM4	VECNUM3	VECNUM2	VECNUM1	VECNUM0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **CPUIRQ:** Interrupt Request from Interrupt Controller CPU bit  
 1 = An interrupt request has occurred but has not yet been Acknowledged by the CPU; this happens when the CPU priority is higher than the interrupt priority  
 0 = No interrupt request is unacknowledged
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **VHOLD:** Vector Number Capture Configuration bit  
 1 = VECNUMx bits contain the value of the highest priority pending interrupt  
 0 = VECNUMx bits contain the value of the last Acknowledged interrupt (i.e., the last interrupt that has occurred with higher priority than the CPU, even if other interrupts are pending)
- bit 12 **Unimplemented:** Read as '0'
- bit 11-8 **ILR<3:0>:** New CPU Interrupt Priority Level bits  
 1111 = CPU Interrupt Priority Level is 15  
 •  
 •  
 •  
 0001 = CPU Interrupt Priority Level is 1  
 0000 = CPU Interrupt Priority Level is 0
- bit 7 **Unimplemented:** Read as '0'
- bit 6-0 **VECNUM<6:0>:** Pending Interrupt Vector ID bits (pending vector number is VECNUM + 8)  
 01111111 = Interrupt vector pending is Number 135  
 •  
 •  
 •  
 00000001 = Interrupt vector pending is Number 9  
 00000000 = Interrupt vector pending is Number 8

# PIC24FJ64GA004 FAMILY

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## 7.4 Interrupt Setup Procedures

### 7.4.1 INITIALIZATION

To configure an interrupt source:

1. Set the NSTDIS Control bit (INTCON1<15>) if nested interrupts are not desired.
2. Select the user-assigned priority level for the interrupt source by writing the control bits in the appropriate IPCx register. The priority level will depend on the specific application and type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits for all enabled interrupt sources may be programmed to the same non-zero value.

**Note:** At a device Reset, the IPCx registers are initialized, such that all user interrupt sources are assigned to Priority Level 4.

3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

### 7.4.2 INTERRUPT SERVICE ROUTINE

The method that is used to declare an ISR and initialize the IVT with the correct vector address will depend on the programming language (i.e., 'C' or assembler) and the language development toolsuite that is used to develop the application. In general, the user must clear the interrupt flag in the appropriate IFSx register for the source of the interrupt that the ISR handles. Otherwise, the ISR will be re-entered immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a RETFIE instruction to unstack the saved PC value, SRL value and old CPU priority level.

### 7.4.3 TRAP SERVICE ROUTINE

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

### 7.4.4 INTERRUPT DISABLE

All user interrupts can be disabled using the following procedure:

1. Push the current SR value onto the software stack using the PUSH instruction.
2. Force the CPU to Priority Level 7 by inclusive ORing the value, OEh, with SRL.

To enable user interrupts, the POP instruction may be used to restore the previous SR value.

Note that only user interrupts with a priority level of 7 or less can be disabled. Trap sources (Levels 8-15) cannot be disabled.

The DISI instruction provides a convenient way to disable interrupts of Priority Levels 1-6 for a fixed period of time. Level 7 interrupt sources are not disabled by the DISI instruction.

# PIC24FJ64GA004 FAMILY

## 8.0 OSCILLATOR CONFIGURATION

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Oscillator” (DS39700).

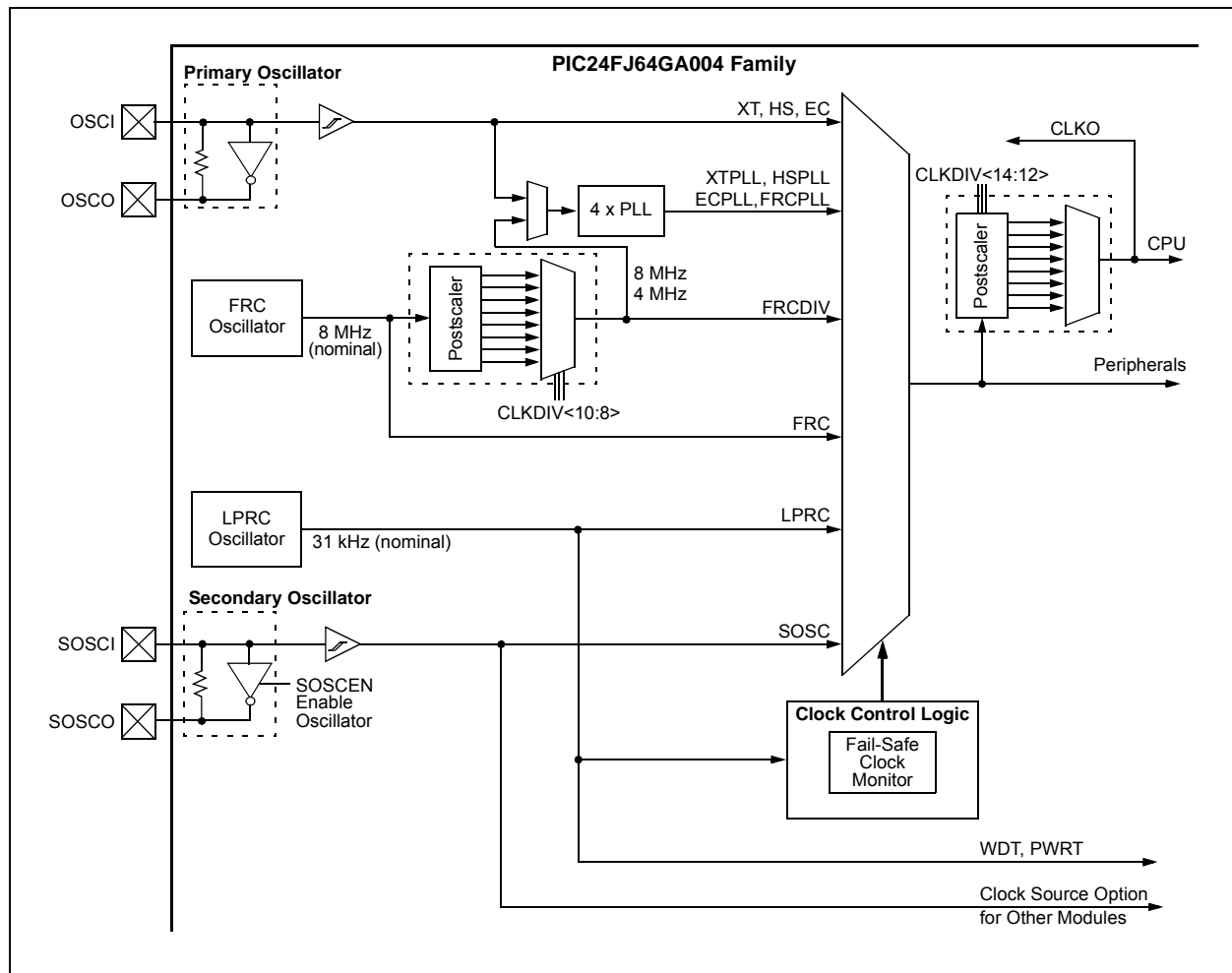
- Software-controllable switching between various clock sources
- Software-controllable postscaler for selective clocking of CPU for system power savings
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and permits safe application recovery or shutdown

A simplified diagram of the oscillator system is shown in [Figure 8-1](#).

The oscillator system for PIC24FJ64GA004 family devices has the following features:

- A total of four external and internal oscillator options as clock sources, providing 11 different clock modes
- On-chip 4x PLL to boost internal operating frequency on select internal and external oscillator sources

**FIGURE 8-1: PIC24FJ64GA004 FAMILY CLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## 8.1 CPU Clocking Scheme

The system clock source can be provided by one of four sources:

- Primary Oscillator (POSC) on the OSCI and OSCO pins
- Secondary Oscillator (SOSC) on the SOSCI and SOSCO pins
- Fast Internal RC (FRC) Oscillator
- Low-Power Internal RC (LPRC) Oscillator

The primary oscillator and FRC sources have the option of using the internal 4x PLL. The frequency of the FRC clock source can optionally be reduced by the programmable clock divider. The selected clock source generates the processor and peripheral clock sources.

The processor clock source is divided by two to produce the internal instruction cycle clock, Fcy. In this document, the instruction cycle clock is also denoted by Fosc/2. The internal instruction cycle clock, Fosc/2, can be provided on the OSCO I/O pin for some operating modes of the primary oscillator.

## 8.2 Initial Configuration on POR

The oscillator source (and operating mode) that is used at a device Power-on Reset event is selected using Configuration bit settings. The Oscillator Configuration bit settings are located in the Configuration registers in the program memory (refer to [Section 24.1 “Configuration Bits”](#) for further details). The Primary Oscillator Configuration bits, POSCMD<1:0> (Configuration Word 2<1:0>), and the Initial Oscillator Select Configuration bits, FNOSC<2:0> (Configuration Word 2<10:8>), select the oscillator source that is used at a Power-on Reset. The FRC Primary Oscillator with Postscaler (FRCDIV) is the default (unprogrammed) selection. The Secondary Oscillator, or one of the internal oscillators, may be chosen by programming these bit locations.

The Configuration bits allow users to choose between the various clock modes, shown in [Table 8-1](#).

### 8.2.1 CLOCK SWITCHING MODE CONFIGURATION BITS

The FCKSM<1:0> Configuration bits (Configuration Word 2<7:6>) are used to jointly configure device clock switching and the Fail-Safe Clock Monitor (FSCM). Clock switching is enabled only when FCKSM1 is programmed ('0'). The FSCM is enabled only when FCKSM<1:0> are both programmed ('00').

**TABLE 8-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION**

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>	Notes
Fast RC Oscillator with Postscaler (FRCDIV)	Internal	11	111	<a href="#">1</a> , <a href="#">2</a>
(Reserved)	Internal	xx	110	<a href="#">1</a>
Low-Power RC Oscillator (LPRC)	Internal	11	101	<a href="#">1</a>
Secondary (Timer1) Oscillator (SOSC)	Secondary	00	100	<a href="#">1</a>
Primary Oscillator (XT) with PLL Module (XTPLL)	Primary	01	011	
Primary Oscillator (EC) with PLL Module (ECPLL)	Primary	00	011	
Primary Oscillator (HS)	Primary	10	010	
Primary Oscillator (XT)	Primary	01	010	
Primary Oscillator (EC)	Primary	00	010	
Fast RC Oscillator with PLL Module (FRCPLL)	Internal	11	001	<a href="#">1</a>
Fast RC Oscillator (FRC)	Internal	11	000	<a href="#">1</a>

**Note 1:** OSCO pin function is determined by the OSCIOFCN Configuration bit.

**2:** This is the default oscillator mode for an unprogrammed (erased) device.



# PIC24FJ64GA004 FAMILY

## 8.3 Control Registers

The operation of the oscillator is controlled by three Special Function Registers:

- OSCCON
- CLKDIV
- OSCTUN

The OSCCON register (Register 8-1) is the main control register for the oscillator. It controls clock source switching and allows the monitoring of clock sources.

The Clock Divider register (Register 8-2) controls the features associated with Doze mode, as well as the postscaler for the FRC oscillator.

The FRC Oscillator Tune register (Register 8-3) allows the user to fine-tune the FRC oscillator over a range of approximately  $\pm 12\%$ .

### REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER

U-0	R-0	R-0	R-0	U-0	R/W-x <sup>(1)</sup>	R/W-x <sup>(1)</sup>	R/W-x <sup>(1)</sup>
—	COSC2	COSC1	COSC0	—	NOSC2	NOSC1	NOSC0
bit 15							bit 8

R/SO-0	R/W-0	R-0 <sup>(3)</sup>	U-0	R/CO-0	U-0	R/W-0	R/W-0
CLKLOCK	IOLOCK <sup>(2)</sup>	LOCK	—	CF	—	SOSCEN	OSWEN
bit 7							bit 0

<b>Legend:</b>	CO = Clearable Only bit	SO = Settable Only bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits

- 111 = Fast RC Oscillator with Postscaler (FRCDIV)
- 110 = Reserved
- 101 = Low-Power RC Oscillator (LPRC)
- 100 = Secondary Oscillator (SOSC)
- 011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL)
- 010 = Primary Oscillator (XT, HS, EC)
- 001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL)
- 000 = Fast RC Oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits<sup>(1)</sup>

- 111 = Fast RC Oscillator with Postscaler (FRCDIV)
- 110 = Reserved
- 101 = Low-Power RC Oscillator (LPRC)
- 100 = Secondary Oscillator (SOSC)
- 011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL)
- 010 = Primary Oscillator (XT, HS, EC)
- 001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL)
- 000 = Fast RC Oscillator (FRC)

**Note 1:** Reset values for these bits are determined by the FNOSCx Configuration bits.

**2:** The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1' once the IOLOCK bit is set, it cannot be cleared.

**3:** Also resets to '0' during any valid clock switch or whenever a non-PLL Clock mode is selected.

# PIC24FJ64GA004 FAMILY

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## REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER (CONTINUED)

bit 7	<b>CLKLOCK:</b> Clock Selection Lock Enable bit <u>If FSCM is enabled (FCKSM1 = 1):</u> 1 = Clock and PLL selections are locked 0 = Clock and PLL selections are not locked and may be modified by setting the OSWEN bit <u>If FSCM is disabled (FCKSM1 = 0):</u> Clock and PLL selections are never locked and may be modified by setting the OSWEN bit.
bit 6	<b>IOLOCK:</b> I/O Lock Enable bit <sup>(2)</sup> 1 = I/O lock is active 0 = I/O lock is not active
bit 5	<b>LOCK:</b> PLL Lock Status bit <sup>(3)</sup> 1 = PLL module is in lock or PLL module start-up timer is satisfied 0 = PLL module is out of lock, PLL start-up timer is running or PLL is disabled
bit 4	<b>Unimplemented:</b> Read as '0'
bit 3	<b>CF:</b> Clock Fail Detect bit 1 = FSCM has detected a clock failure 0 = No clock failure has been detected
bit 2	<b>Unimplemented:</b> Read as '0'
bit 1	<b>SOSCEN:</b> 32 kHz Secondary Oscillator (SOSC) Enable bit 1 = Enables Secondary Oscillator 0 = Disables Secondary Oscillator
bit 0	<b>OSWEN:</b> Oscillator Switch Enable bit 1 = Initiates an oscillator switch to a clock source specified by the NOSC<2:0> bits 0 = Oscillator switch is complete

**Note 1:** Reset values for these bits are determined by the FNOSC<sub>x</sub> Configuration bits.

**2:** The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1' once the IOLOCK bit is set, it cannot be cleared.

**3:** Also resets to '0' during any valid clock switch or whenever a non-PLL Clock mode is selected.

# PIC24FJ64GA004 FAMILY

## REGISTER 8-2: CLKDIV: CLOCK DIVIDER REGISTER

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1
ROI	DOZE2	DOZE1	DOZE0	DOZEN <sup>(1)</sup>	RCDIV2	RCDIV1	RCDIV0
bit 15				bit 8			

U-0	U-1	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **ROI:** Recover on Interrupt bit  
 1 = Interrupts clear the DOZEN bit and reset the CPU peripheral clock ratio to 1:1  
 0 = Interrupts have no effect on the DOZEN bit
- bit 14-12 **DOZE<2:0>:** CPU Peripheral Clock Ratio Select bits  
 111 = 1:128  
 110 = 1:64  
 101 = 1:32  
 100 = 1:16  
 011 = 1:8  
 010 = 1:4  
 001 = 1:2  
 000 = 1:1
- bit 11 **DOZEN:** DOZE Enable bit<sup>(1)</sup>  
 1 = DOZE<2:0> bits specify the CPU peripheral clock ratio  
 0 = CPU peripheral clock ratio is set to 1:1
- bit 10-8 **RCDIV<2:0>:** FRC Postscaler Select bits  
 111 = 31.25 kHz (divide-by-256)  
 110 = 125 kHz (divide-by-64)  
 101 = 250 kHz (divide-by-32)  
 100 = 500 kHz (divide-by-16)  
 011 = 1 MHz (divide-by-8)  
 010 = 2 MHz (divide-by-4)  
 001 = 4 MHz (divide-by-2)  
 000 = 8 MHz (divide-by-1)
- bit 7 **Unimplemented:** Read as '0'
- bit 6 **Unimplemented:** Read as '1'
- bit 5-0 **Unimplemented:** Read as '0'

**Note 1:** This bit is automatically cleared when the ROI bit is set and an interrupt occurs.

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**REGISTER 8-3: OSCTUN: FRC OSCILLATOR TUNE REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	TUN5 <sup>(1)</sup>	TUN4 <sup>(1)</sup>	TUN3 <sup>(1)</sup>	TUN2 <sup>(1)</sup>	TUN1 <sup>(1)</sup>	TUN0 <sup>(1)</sup>
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-6 **Unimplemented:** Read as '0'

bit 5-0 **TUN<5:0>:** FRC Oscillator Tuning bits<sup>(1)</sup>

011111 = Maximum frequency deviation

011110 =

•

•

•

000001 =

000000 = Center frequency, oscillator is running at factory calibrated frequency

111111 =

•

•

•

100001 =

100000 = Minimum frequency deviation

**Note 1:** Increments or decrements of TUN<5:0> may not change the FRC frequency in equal steps over the FRC tuning range and may not be monotonic.

## 8.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the four clock sources (POSC, SOSC, FRC and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

**Note:** The Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMDx Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

### 8.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in Flash Configuration Word 2 must be programmed to '0'. (Refer to [Section 24.1 "Configuration Bits"](#) for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSCx control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSCx bits (OSCCON<14:12>) will reflect the clock source selected by the FNOSCx Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled; it is held at '0' at all times.

## 8.4.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

1. If desired, read the COSCx bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSCx bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSCx bits with the new value of the NOSCx bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and CF (OSCCON<3>) bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware will wait until the OST expires. If the new source is using the PLL, then the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSCx bit values are transferred to the COSCx bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or SOSC (if SOSSEN remains set).

**Note 1:** The processor will continue to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

- 2: Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.

A recommended code sequence for a clock switch includes the following:

1. Disable interrupts during the OSCCON register unlock and write sequence.
2. Execute the unlock sequence for the OSCCON high byte by writing 78h and 9Ah to OSCCON<15:8> in two back-to-back instructions.
3. Write the new oscillator source to the NOSCx bits in the instruction immediately following the unlock sequence.
4. Execute the unlock sequence for the OSCCON low byte by writing 46h and 57h to OSCCON<7:0> in two back-to-back instructions.
5. Set the OSWEN bit in the instruction immediately following the unlock sequence.
6. Continue to execute code that is not clock-sensitive (optional).
7. Invoke an appropriate amount of software delay (cycle counting) to allow the selected oscillator and/or PLL to start and stabilize.
8. Check to see if OSWEN is '0'. If it is, the switch was successful. If OSWEN is still set, then check the LOCK bit to determine the cause of failure.

The core sequence for unlocking the OSCCON register and initiating a clock switch is shown in [Example 8-1](#).

### EXAMPLE 8-1: BASIC CODE SEQUENCE FOR CLOCK SWITCHING

```
.global __reset
#include "p24fxxxx.inc"
.text
__reset:
;Place the new oscillator selection in W0
;OSCCONH (high byte) Unlock Sequence
DISI    #18
PUSH    w1
PUSH    w2
PUSH    w3
MOV      #OSCCONH, w1
MOV      #0x78, w2
MOV      #0x9A, w3
MOV.b    w2, [w1]
MOV.b    w3, [w1]
;Set new oscillator selection
MOV.b    WREG, OSCCONH
;OSCCONL (low byte) unlock sequence
MOV      #OSCCONL, w1
MOV      #0x46, w2
MOV      #0x57, w3
MOV.b    w2, [w1]
MOV.b    w3, [w1]
;Start oscillator switch operation
BSET     OSCCON, #0
POP      w3
POP      w2
POP      w1
.end
```

# PIC24FJ64GA004 FAMILY

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## 8.4.3 SECONDARY OSCILLATOR LOW-POWER OPERATION

**Note:** This feature is implemented only on PIC24FJ64GA004 family devices with a major silicon revision level of B or later (DEVREV register value is 3042h or greater).

The Secondary Oscillator (SOSC) can operate in two distinct levels of power consumption based on device configuration. In Low-Power mode, the oscillator operates in a low gain, low-power state. By default, the oscillator uses a higher gain setting, and therefore, requires more power. The Secondary Oscillator Mode Selection bits, SOSCSEL<1:0> (CW2<12:11>), determine the oscillator's power mode.

When Low-Power mode is used, care must be taken in the design and layout of the SOSC circuit to ensure that the oscillator will start up and oscillate properly. The lower gain of this mode makes the SOSC more sensitive to noise and requires a longer start-up time.

## 8.4.4 OSCILLATOR LAYOUT

On low pin count devices, such as those in the PIC24FJ64GA004 family, due to pinout limitations, the SOSC is more susceptible to noise than other PIC24F devices. Unless proper care is taken in the design and layout of the SOSC circuit, it is possible for inaccuracies to be introduced into the oscillator's period.

In general, the crystal circuit connections should be as short as possible. It is also good practice to surround the crystal circuit with a ground loop or ground plane. For more detailed information on crystal circuit design, please refer to the "PIC24F Family Reference Manual", "Oscillator" (DS39700) and Microchip Application Notes: AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC® and PICmicro® Devices" (DS00826) and AN849, "Basic PICmicro® Oscillator Design" (DS00849).

## 9.0 POWER-SAVING FEATURES

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Power-Saving Features” (DS39698). Additional power-saving tips can also be found in [Appendix B: “Additional Guidance for PIC24FJ64GA004 Family Applications”](#) of this document.

The PIC24FJ64GA004 family of devices provides the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. All PIC24F devices manage power consumption in four different ways:

- Clock Frequency
- Instruction-Based Sleep and Idle modes
- Software Controlled Doze mode
- Selective Peripheral Control in Software

Combinations of these methods can be used to selectively tailor an application’s power consumption, while still maintaining critical application features, such as timing-sensitive communications.

### 9.1 Clock Frequency and Clock Switching

PIC24F devices allow for a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC<sub>x</sub> bits. The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in [Section 8.0 “Oscillator Configuration”](#).

### 9.2 Instruction-Based Power-Saving Modes

PIC24F devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution; Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembly syntax of the PWRSAV instruction is shown in [Example 9-1](#).

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to “wake-up”.

**Note:** SLEEP\_MODE and IDLE\_MODE are constants defined in the assembler include file for the selected device.

#### 9.2.1 SLEEP MODE

Sleep mode includes these features:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption will be reduced to a minimum provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor does not operate during Sleep mode since the system clock source is disabled.
- The LPRC clock will continue to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals may continue to operate in Sleep mode. This includes items such as the Input Change Notification on the I/O ports, or peripherals that use an external clock input. Any peripheral that requires the system clock source for its operation will be disabled in Sleep mode.

Additional power reductions can be achieved by disabling the on-chip voltage regulator whenever Sleep mode is invoked. This is done by clearing the PMSLP bit (RCON<8>). Disabling the regulator adds an additional delay of about 190 μs to the device wake-up time. It is recommended that applications not using the voltage regulator leave the PMSLP bit set. For additional details on the regulator and Sleep mode, see [Section 24.2.5 “Voltage Regulator Standby Mode”](#).

The device will wake-up from Sleep mode on any of these events:

- On any interrupt source that is individually enabled.
- On any form of device Reset.
- On a WDT time-out.

On wake-up from Sleep, the processor will restart with the same clock source that was active when Sleep mode was entered.

#### EXAMPLE 9-1: PWRSAV INSTRUCTION SYNTAX

```
PWRSAV    #SLEEP_MODE      ; Put the device into SLEEP mode
PWRSAV    #IDLE_MODE        ; Put the device into IDLE mode
```



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## 9.2.2 IDLE MODE

Idle mode includes these features:

- The CPU will stop executing instructions.
- The WDT is automatically cleared.
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see [Section 9.4 “Selective Peripheral Module Control”](#)).
- If the WDT or FSCM is enabled, the LPRC will also remain active.

The device will wake from Idle mode on any of these events:

- Any interrupt that is individually enabled.
- Any device Reset.
- A WDT time-out.

On wake-up from Idle, the clock is reapplied to the CPU and instruction execution begins immediately, starting with the instruction following the `PWRSV` instruction or the first instruction in the ISR.

## 9.2.3 INTERRUPTS COINCIDENT WITH POWER SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a `PWRSV` instruction will be held off until entry into Sleep or Idle mode has completed. The device will then wake-up from Sleep or Idle mode.

## 9.3 Doze Mode

Generally, changing clock speed and invoking one of the power-saving modes are the preferred strategies for reducing power consumption. There may be circumstances, however, where this is not practical. For example, it may be necessary for an application to maintain uninterrupted synchronous communication, even while it is doing nothing else. Reducing system clock speed may introduce communication errors, while using a power-saving mode may stop communications completely.

Doze mode is a simple and effective alternative method to reduce power consumption while the device is still executing code. In this mode, the system clock continues to operate from the same source and at the same speed. Peripheral modules continue to be clocked at the same speed while the CPU clock speed is reduced. Synchronization between the two clock domains is maintained, allowing the peripherals to access the SFRs while the CPU executes code at a slower rate.

Doze mode is enabled by setting the `DOZEN` bit (`CLKDIV<11>`). The ratio between peripheral and core clock speed is determined by the `DOZE<2:0>` bits (`CLKDIV<14:12>`). There are eight possible configurations, from 1:1 to 1:256, with 1:1 being the default.

It is also possible to use Doze mode to selectively reduce power consumption in event driven applications. This allows clock-sensitive functions, such as synchronous communications, to continue without interruption while the CPU Idles, waiting for something to invoke an interrupt routine. Enabling the automatic return to full-speed CPU operation on interrupts is enabled by setting the `ROI` bit (`CLKDIV<15>`). By default, interrupt events have no effect on Doze mode operation.

## 9.4 Selective Peripheral Module Control

Idle and Doze modes allow users to substantially reduce power consumption by slowing or stopping the CPU clock. Even so, peripheral modules still remain clocked and thus, consume power. There may be cases where the application needs what these modes do not provide: the allocation of power resources to CPU processing with minimal power consumption from the peripherals.

PIC24F devices address this requirement by allowing peripheral modules to be selectively disabled, reducing or eliminating their power consumption. This can be done with two control bits:

- The Peripheral Enable bit, generically named, “`XXXEN`”, located in the module’s main control SFR.
- The Peripheral Module Disable (PMD) bit, generically named, “`XXXMD`”, located in one of the PMD control registers.

Both bits have similar functions in enabling or disabling its associated module. Setting the PMD bit for a module disables all clock sources to that module, reducing its power consumption to an absolute minimum. In this state, the control and status registers associated with the peripheral will also be disabled, so writes to those registers will have no effect and read values will be invalid. Many peripheral modules have a corresponding PMD bit.

In contrast, disabling a module by clearing its `XXXEN` bit disables its functionality, but leaves its registers available to be read and written to. Power consumption is reduced, but not by as much as the PMD bit does. Most peripheral modules have an enable bit; exceptions include capture, compare and RTCC.

To achieve more selective power savings, peripheral modules can also be selectively disabled when the device enters Idle mode. This is done through the control bit of the generic name format, “`XXXIDL`”. By default, all modules that can operate during Idle mode will do so. Using the disable on Idle feature allows further reduction of power consumption during Idle mode, enhancing power savings for extremely critical power applications.



# PIC24FJ64GA004 FAMILY

## 10.0 I/O PORTS

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “I/O Ports with Peripheral Pin Select (PPS)” (DS39711).

All of the device pins (except VDD, VSS, MCLR and OSC1/CLKI) are shared between the peripherals and the Parallel I/O (PIO) ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity.

### 10.1 Parallel I/O (PIO) Ports

A Parallel I/O port that shares a pin with a peripheral is, in general, subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port has ownership of the output data and control signals of the I/O pin. The logic also prevents “loop through”, in which a port's digital output can drive the input of a peripheral that shares the same pin. Figure 10-1 shows how ports are shared with other peripherals and the associated I/O pin to which they are connected.

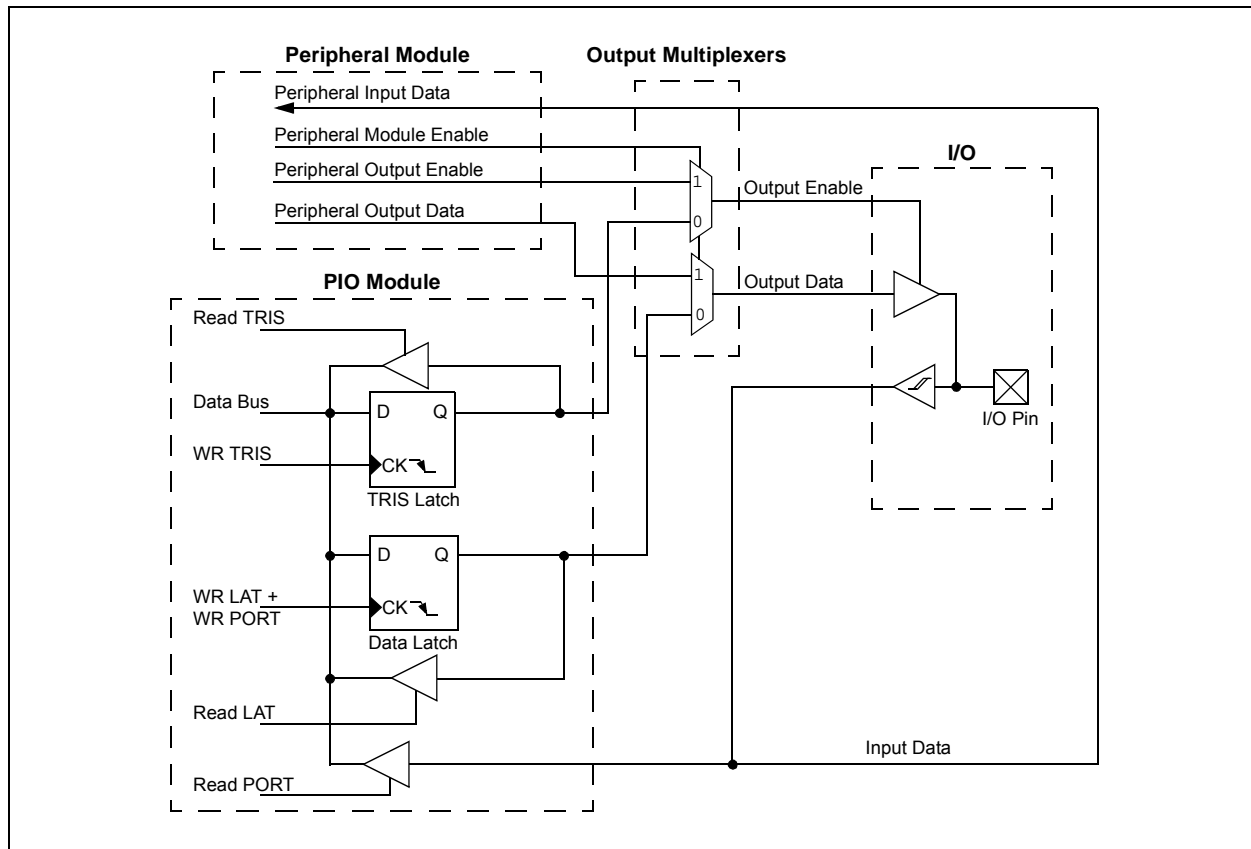
When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin may be read, but the output driver for the parallel port bit will be disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin may be driven by a port.

All port pins have three registers directly associated with their operation as digital I/O. The Data Direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a ‘1’, then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the Output Latch register (LATx), read the latch. Writes to the latch, write the latch. Reads from the port (PORTx), read the port pins, while writes to the port pins, write the latch.

Any bit and its associated data and control registers that are not valid for a particular device will be disabled. That means the corresponding LATx and TRISx registers and the port pin will read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless, regarded as a dedicated port because there is no other competing source of outputs.

**FIGURE 10-1: BLOCK DIAGRAM OF A TYPICAL SHARED PORT STRUCTURE**



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## 10.1.1 OPEN-DRAIN CONFIGURATION

In addition to the PORT, LAT and TRIS registers for data control, each port pin can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any desired digital only pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

## 10.2 Configuring Analog Port Pins

The use of the AD1PCFG and TRIS registers control the operation of the A/D port pins. The port pins that are desired as analog inputs must have their corresponding TRIS bit set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) will be converted.

When reading the PORT register, all pins configured as analog input channels will read as cleared (a low level).

Pins configured as digital inputs will not convert an analog input. Analog levels on any pin that is defined as a digital input (including the ANx pins) may cause the input buffer to consume current that exceeds the device specifications.

### 10.2.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be a NOP.

### 10.2.2 ANALOG INPUT PINS AND VOLTAGE CONSIDERATIONS

The voltage tolerance of pins used as device inputs is dependent on the pin's input function. Pins that are used as digital only inputs are able to handle DC voltages up to 5.5V, a level typical for digital logic circuits. In contrast, pins that also have analog input functions of any kind can only tolerate voltages up to VDD. Voltage excursions beyond VDD on these pins are always to be avoided. [Table 10-1](#) summarizes the input capabilities. Refer to [Section 27.1 "DC Characteristics"](#) for more details.

**TABLE 10-1: INPUT VOLTAGE LEVELS**

Port or Pin	Tolerated Input	Description
PORTA<4:0>	VDD	Only VDD input levels are tolerated.
PORTB<15:12>		
PORTB<4:0>		
PORTC<2:0> <sup>(1)</sup>		
PORTA<10:7> <sup>(1)</sup>	5.5V	Tolerates input levels above VDD, useful for most standard logic.
PORTB<11:5>		
PORTC<9:3> <sup>(1)</sup>		

**Note 1:** Unavailable on 28-pin devices.

## 10.3 Input Change Notification

The Input Change Notification function of the I/O ports allows the PIC24FJ64GA004 family of devices to generate interrupt requests to the processor in response to a Change-of-State (COS) on selected input pins. This feature is capable of detecting input Change-of-States even in Sleep mode, when the clocks are disabled. Depending on the device pin count, there are up to 22 external signals that may be selected (enabled) for generating an interrupt request on a Change-of-State.

There are four control registers associated with the CN module. The CNEN1 and CNEN2 registers contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin also has a weak pull-up connected to it. The pull-ups act as a current source that is connected to the pin, and eliminate the need for external resistors when push button or keypad devices are connected. The pull-ups are enabled separately using the CNPU1 and CNPU2 registers, which contain the control bits for each of the CN pins. Setting any of the control bits enables the weak pull-ups for the corresponding pins.

When the internal pull-up is selected, the pin pulls up to VDD – 0.7V (typical). Make sure that there is no external pull-up source when the internal pull-ups are enabled, as the voltage difference can cause a current path.

**Note:** Pull-ups on Change Notification pins should always be disabled whenever the port pin is configured as a digital output.

### EXAMPLE 10-1: PORT WRITE/READ EXAMPLE

```
MOV    0xFF00, W0          ; Configure PORTB<15:8> as inputs
MOV    W0, TRISBB          ; and PORTB<7:0> as outputs
NOP                                ; Delay 1 cycle
BTSS   PORTB, #13          ; Next Instruction
```

## 10.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin count devices similar to the PIC24FJ64GA family. In an application that needs to use more than one peripheral multiplexed on a single pin, inconvenient work arounds in application code or a complete redesign may be the only option.

The Peripheral Pin Select feature provides an alternative to these choices by enabling the user's peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of any one of many digital peripherals to any one of these I/O pins. Peripheral Pin Select is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

### 10.4.1 AVAILABLE PINS

The Peripheral Pin Select feature is used with a range of up to 26 pins; the number of available pins is dependent on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the designation, "RPn", in their full pin designation, where "RP" designates a remappable peripheral and "n" is the remappable pin number. See [Table 1-2](#) for pinout options in each package offering.

### 10.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the Peripheral Pin Select are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and external interrupt inputs. Also included are the outputs of the comparator module, since these are discrete digital signals.

The Peripheral Pin Select module is not applied to I<sup>2</sup>C™, Change Notification inputs, RTCC alarm outputs or peripherals with analog inputs.

A key difference between pin select and non-pin select peripherals is that pin select peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-pin select peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

### 10.4.2.1 Peripheral Pin Select Function Priority

Pin-selectable peripheral outputs (for example, OC and UART transmit) take priority over any general purpose digital functions permanently tied to that pin, such as PMP and port I/O. Specialized digital outputs, such as USB functionality, take priority over PPS outputs on the same pin. The pin diagrams at the beginning of this data sheet list peripheral outputs in order of priority. Refer to them for priority concerns on a particular pin.

Unlike devices with fixed peripherals, pin-selectable peripheral inputs never take ownership of a pin. The pin's output buffer is controlled by the pin's TRIS bit setting or by a fixed peripheral on the pin. If the pin is configured in Digital mode, then the PPS input will operate correctly, reading the input. If an analog function is enabled on the same pin, the pin-selectable input will be disabled.

### 10.4.3 CONTROLLING PERIPHERAL PIN SELECT

Peripheral Pin Select features are controlled through two sets of Special Function Registers: one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on if an input or an output is being mapped.

#### 10.4.3.1 Input Mapping

The inputs of the Peripheral Pin Select options are mapped on the basis of the peripheral; that is, a control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see [Register 10-1](#) through [Register 10-14](#)). Each register contains two sets of 5-bit fields, with each set associated with one of the pin-selectable peripherals. Programming a given peripheral's bit field with an appropriate 5-bit value maps the RPn pin with that value to that peripheral. For any given device, the valid range of values for any of the bit fields corresponds to the maximum number of Peripheral Pin Selections supported by the device.

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**TABLE 10-2: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)<sup>(1)</sup>**

Input Name	Function Name	Register	Configuration Bits
External Interrupt 1	INT1	RPINR0	INTR1<4:0>
External Interrupt 2	INT2	RPINR1	INTR2R<4:0>
Timer2 External Clock	T2CK	RPINR3	T2CKR<4:0>
Timer3 External Clock	T3CK	RPINR3	T3CKR<4:0>
Timer4 External Clock	T4CK	RPINR4	T4CKR<4:0>
Timer5 External Clock	T5CK	RPINR4	T5CKR<4:0>
Input Capture 1	IC1	RPINR7	IC1R<4:0>
Input Capture 2	IC2	RPINR7	IC2R<4:0>
Input Capture 3	IC3	RPINR8	IC3R<4:0>
Input Capture 4	IC4	RPINR8	IC4R<4:0>
Input Capture 5	IC5	RPINR9	IC5R<4:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<4:0>
Output Compare Fault B	OCFB	RPINR11	OCFBR<4:0>
UART1 Receive	U1RX	RPINR18	U1RXR<4:0>
UART1 Clear-to-Send	$\overline{\text{U1CTS}}$	RPINR18	U1CTSR<4:0>
UART2 Receive	U2RX	RPINR19	U2RXR<4:0>
UART2 Clear-to-Send	$\overline{\text{U2CTS}}$	RPINR19	U2CTSR<4:0>
SPI1 Data Input	SDI1	RPINR20	SDI1R<4:0>
SPI1 Clock Input	SCK1IN	RPINR20	SCK1R<4:0>
SPI1 Slave Select Input	SS1IN	RPINR21	SS1R<4:0>
SPI2 Data Input	SDI2	RPINR22	SDI2R<4:0>
SPI2 Clock Input	SCK2IN	RPINR22	SCK2R<4:0>
SPI2 Slave Select Input	SS2IN	RPINR23	SS2R<4:0>

**Note 1:** Unless otherwise noted, all inputs use the Schmitt Trigger input buffers.

## 10.4.3.2 Output Mapping

In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Like the RPINRx registers, each register contains two 5-bit fields; each field being associated with one RPN pin (see [Register 10-15](#) through [Register 10-27](#)). The value of the bit field corresponds to one of the peripherals and that peripheral's output is mapped to the pin (see [Table 10-3](#)).

Because of the mapping technique, the list of peripherals for output mapping also includes a null value of '00000'. This permits any given pin to remain disconnected from the output of any of the pin-selectable peripherals.

**TABLE 10-3: SELECTABLE OUTPUT SOURCES (MAPS FUNCTION TO OUTPUT)**

Function	Output Function Number <sup>(1)</sup>	Output Name
NULL <sup>(2)</sup>	0	NULL
C1OUT	1	Comparator 1 Output
C2OUT	2	Comparator 2 Output
U1TX	3	UART1 Transmit
U1RTS <sup>(3)</sup>	4	UART1 Request-to-Send
U2TX	5	UART2 Transmit
U2RTS <sup>(3)</sup>	6	UART2 Request-to-Send
SDO1	7	SPI1 Data Output
SCK1OUT	8	SPI1 Clock Output
SS1OUT	9	SPI1 Slave Select Output
SDO2	10	SPI2 Data Output
SCK2OUT	11	SPI2 Clock Output
SS2OUT	12	SPI2 Slave Select Output
OC1	18	Output Compare 1
OC2	19	Output Compare 2
OC3	20	Output Compare 3
OC4	21	Output Compare 4
OC5	22	Output Compare 5

- Note 1:** Value assigned to the RPN<4:0> pins corresponds to the peripheral output function number.
- 2:** The NULL function is assigned to all RPN outputs at device Reset and disables the RPN output function.
- 3:** IrDA® BCLK functionality uses this output.

## 10.4.3.3 Mapping Limitations

The control schema of the Peripheral Pin Select is extremely flexible. Other than systematic blocks that prevent signal contention, caused by two physical pins being configured as the same functional input or two functional outputs configured as the same pin, there are no hardware enforced lockouts. The flexibility extends to the point of allowing a single input to drive multiple peripherals or a single functional output to drive multiple output pins.

## 10.4.4 CONTROLLING CONFIGURATION CHANGES

Because peripheral remapping can be changed during run time, some restrictions on peripheral remapping are needed to prevent accidental configuration changes. PIC24F devices include three features to prevent alterations to the peripheral map:

- Control register lock sequence
- Continuous state monitoring
- Configuration bit remapping lock

### 10.4.4.1 Control Register Lock

Under normal operation, writes to the RPINRx and RPORx registers are not allowed. Attempted writes will appear to execute normally, but the contents of the registers will remain unchanged. To change these registers, they must be unlocked in hardware. The register lock is controlled by the IOLOCK bit (OSCCON<6>). Setting IOLOCK prevents writes to the control registers; clearing IOLOCK allows writes.

To set or clear IOLOCK, a specific command sequence must be executed:

1. Write 46h to OSCCON<7:0>.
2. Write 57h to OSCCON<7:0>.
3. Clear (or set) IOLOCK as a single operation.

Unlike the similar sequence with the oscillator's LOCK bit, IOLOCK remains in one state until changed. This allows all of the Peripheral Pin Selects to be configured with a single unlock sequence, followed by an update to all control registers, then locked with a second lock sequence.

### 10.4.4.2 Continuous State Monitoring

In addition to being protected from direct writes, the contents of the RPINRx and RPORx registers are constantly monitored in hardware by shadow registers. If an unexpected change in any of the registers occurs (such as cell disturbances caused by ESD or other external events), a Configuration Mismatch Reset will be triggered.

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## 10.4.4.3 Configuration Bit Pin Select Lock

As an additional level of safety, the device can be configured to prevent more than one write session to the RPINRx and RPORx registers. The IOL1WAY (CW2<4>) Configuration bit blocks the IOLOCK bit from being cleared after it has been set once. If IOLOCK remains set, the register unlock procedure will not execute and the Peripheral Pin Select Control registers cannot be written to. The only way to clear the bit and re-enable peripheral remapping is to perform a device Reset.

In the default (unprogrammed) state, IOL1WAY is set, restricting users to one write session. Programming IOL1WAY allows users unlimited access (with the proper use of the unlock sequence) to the Peripheral Pin Select registers.

## 10.4.5 CONSIDERATIONS FOR PERIPHERAL PIN SELECTION

The ability to control Peripheral Pin Selection introduces several considerations into application design that could be overlooked. This is particularly true for several common peripherals that are available only as remappable peripherals.

The main consideration is that the Peripheral Pin Selects are not available on default pins in the device's default (Reset) state. Since all RPINRx registers reset to '11111' and all RPORx registers reset to '00000', all Peripheral Pin Select inputs are tied to RP31 and all Peripheral Pin Select outputs are disconnected.

**Note:** In tying Peripheral Pin Select inputs to RP31, RP31 does not have to exist on a device for the registers to be reset to it.

This situation requires the user to initialize the device with the proper peripheral configuration before any other application code is executed. Since the IOLOCK bit resets in the unlocked state, it is not necessary to execute the unlock sequence after the device has come out of Reset. For application safety, however, it is best to set IOLOCK and lock the configuration after writing to the control registers.

Because the unlock sequence is timing critical, it must be executed as an assembly language routine in the same manner as changes to the oscillator configuration. If the bulk of the application is written in C or another high-level language, the unlock sequence should be performed by writing in-line assembly.

Choosing the configuration requires the review of all Peripheral Pin Selects and their pin assignments, especially those that will not be used in the application. In all cases, unused pin-selectable peripherals should be disabled completely. Unused peripherals should have their inputs assigned to an unused RPn pin function. I/O pins with unused RPn functions should be configured with the null peripheral output.

The assignment of a peripheral to a particular pin does not automatically perform any other configuration of the pin's I/O circuitry. In theory, this means adding a pin-selectable output to a pin may mean inadvertently driving an existing peripheral input when the output is driven. Users must be familiar with the behavior of other fixed peripherals that share a remappable pin and know when to enable or disable them. To be safe, fixed digital peripherals that share the same pin should be disabled when not in use.

Along these lines, configuring a remappable pin for a specific peripheral does not automatically turn that feature on. The peripheral must be specifically configured for operation and enabled, as if it were tied to a fixed pin. Where this happens in the application code (immediately following device Reset and peripheral configuration or inside the main application routine) depends on the peripheral and its use in the application.

A final consideration is that Peripheral Pin Select functions neither override analog inputs, nor reconfigure pins with analog functions for digital I/O. If a pin is configured as an analog input on device Reset, it must be explicitly reconfigured as a digital I/O when used with a Peripheral Pin Select.

Example 10-2 shows a configuration for bidirectional communication with flow control using UART1. The following input and output functions are used:

- Input Functions: U1RX, U1CTS
- Output Functions: U1TX, U1RTS

### EXAMPLE 10-2: CONFIGURING UART1 INPUT AND OUTPUT FUNCTIONS

```
// Unlock Registers
__builtin_write_OSCCONL(OSCCON & 0xBF);

// Configure Input Functions (Table 10-2)
// Assign U1RX To Pin RP0
RPINR18bits.U1RXR = 0;
// Assign U1CTS To Pin RP1
RPINR18bits.U1CTSR = 1;
// Configure Output Functions (Table 10-3)
// Assign U1TX To Pin RP2
RPOR1bits.RP2R = 3;
// Assign U1RTS To Pin RP3
RPOR1bits.RP3R = 4;

// Lock Registers
__builtin_write_OSCCONL(OSCCON | 0x40);
```



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## 10.5 Peripheral Pin Select Registers

The PIC24FJ64GA004 family of devices implements a total of 27 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (14)
- Output Remappable Peripheral Registers (13)

**Note:** Input and output register values can only be changed if IOLOCK (OSCCON<6>) = 0. See [Section 10.4.4.1 “Control Register Lock”](#) for a specific command sequence.

### REGISTER 10-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							
							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							
							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **INT1R<4:0>:** Assign External Interrupt 1 (INT1) to the Corresponding RPn Pin bits

bit 7-0 **Unimplemented:** Read as '0'

### REGISTER 10-2: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							
							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0
bit 7							
							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4-0 **INT2R<4:0>:** Assign External Interrupt 2 (INT2) to the Corresponding RPn Pin bits

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## REGISTER 10-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T3CKR4	T3CKR3	T3CKR2	T3CKR1	T3CKR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T2CKR4	T2CKR3	T2CKR2	T2CKR1	T2CKR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **T3CKR<4:0>:** Assign Timer3 External Clock (T3CK) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **T2CKR<4:0>:** Assign Timer2 External Clock (T2CK) to the Corresponding RPn Pin bits

## REGISTER 10-4: RPINR4: PERIPHERAL PIN SELECT INPUT REGISTER 4

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T5CKR4	T5CKR3	T5CKR2	T5CKR1	T5CKR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T4CKR4	T4CKR3	T4CKR2	T4CKR1	T4CKR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **T5CKR<4:0>:** Assign Timer5 External Clock (T5CK) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **T4CKR<4:0>:** Assign Timer4 External Clock (T4CK) to the Corresponding RPn Pin bits



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**REGISTER 10-5: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **IC2R<4:0>:** Assign Input Capture 2 (IC2) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **IC1R<4:0>:** Assign Input Capture 1 (IC1) to the Corresponding RPn Pin bits

**REGISTER 10-6: RPINR8: PERIPHERAL PIN SELECT INPUT REGISTER 8**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	IC3R4	IC3R3	IC3R2	IC3R1	IC3R0
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **IC4R<4:0>:** Assign Input Capture 4 (IC4) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **IC3R<4:0>:** Assign Input Capture 3 (IC3) to the Corresponding RPn Pin bits

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## REGISTER 10-7: RPINR9: PERIPHERAL PIN SELECT INPUT REGISTER 9

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	IC5R4	IC5R3	IC5R2	IC5R1	IC5R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4-0 **IC5R<4:0>:** Assign Input Capture 5 (IC5) to the Corresponding RPn Pin bits

## REGISTER 10-8: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **OCFBR<4:0>:** Assign Output Compare Fault B (OCFB) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **OCFAR<4:0>:** Assign Output Compare Fault A (OCFA) to the Corresponding RPn Pin bits

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## REGISTER 10-9: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **U1CTSR<4:0>:** Assign UART1 Clear-to-Send ( $\overline{\text{U1CTS}}$ ) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **U1RXR<4:0>:** Assign UART1 Receive (U1RX) to the Corresponding RPn Pin bits

## REGISTER 10-10: RPINR19: PERIPHERAL PIN SELECT INPUT REGISTER 19

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **U2CTSR<4:0>:** Assign UART2 Clear-to-Send ( $\overline{\text{U2CTS}}$ ) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **U2RXR<4:0>:** Assign UART2 Receive (U2RX) to the Corresponding RPn Pin bits

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## REGISTER 10-11: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **SCK1R<4:0>:** Assign SPI1 Clock Input (SCK1IN) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **SDI1R<4:0>:** Assign SPI1 Data Input (SDI1) to the Corresponding RPn Pin bits

## REGISTER 10-12: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4-0 **SS1R<4:0>:** Assign SPI1 Slave Select Input (SS1IN) to the Corresponding RPn Pin bits

# PIC24FJ64GA004 FAMILY

## REGISTER 10-13: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **SCK2R<4:0>:** Assign SPI2 Clock Input (SCK2IN) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **SDI2R<4:0>:** Assign SPI2 Data Input (SDI2) to the Corresponding RPn Pin bits

## REGISTER 10-14: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4-0 **SS2R<4:0>:** Assign SPI2 Slave Select Input (SS2IN) to the Corresponding RPn Pin bits

# PIC24FJ64GA004 FAMILY

## REGISTER 10-15: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP1R4	RP1R3	RP1R2	RP1R1	RP1R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP0R4	RP0R3	RP0R2	RP0R1	RP0R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP1R<4:0>:** Peripheral Output Function is Assigned to RP1 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP0R<4:0>:** Peripheral Output Function is Assigned to RP0 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

## REGISTER 10-16: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP3R4	RP3R3	RP3R2	RP3R1	RP3R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP2R4	RP2R3	RP2R2	RP2R1	RP2R0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP3R<4:0>:** Peripheral Output Function is Assigned to RP3 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP2R<4:0>:** Peripheral Output Function is Assigned to RP2 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

# PIC24FJ64GA004 FAMILY

## REGISTER 10-17: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP5R4	RP5R3	RP5R2	RP5R1	RP5R0
bit 15						bit 8	

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP5R<4:0>:** Peripheral Output Function is Assigned to RP5 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP4R<4:0>:** Peripheral Output Function is Assigned to RP4 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)

## REGISTER 10-18: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP7R4	RP7R3	RP7R2	RP7R1	RP7R0
bit 15						bit 8	

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP6R4	RP6R3	RP6R2	RP6R1	RP6R0
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP7R<4:0>:** Peripheral Output Function is Assigned to RP7 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP6R<4:0>:** Peripheral Output Function is Assigned to RP6 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)

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## REGISTER 10-19: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP9R<4:0>:** Peripheral Output Function is Assigned to RP9 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP8R<4:0>:** Peripheral Output Function is Assigned to RP8 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)

## REGISTER 10-20: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP11R<4:0>:** Peripheral Output Function is Assigned to RP11 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP10R<4:0>:** Peripheral Output Function is Assigned to RP10 Output Pin bits  
 (see [Table 10-3](#) for peripheral function numbers)



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## REGISTER 10-21: RPOR6: PERIPHERAL PIN SELECT OUTPUT REGISTER 6

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP13R4	RP13R3	RP13R2	RP13R1	RP13R0
bit 15						bit 8	

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP12R4	RP12R3	RP12R2	RP12R1	RP12R0
bit 7						bit 0	

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP13R<4:0>:** Peripheral Output Function is Assigned to RP13 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP12R<4:0>:** Peripheral Output Function is Assigned to RP12 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

## REGISTER 10-22: RPOR7: PERIPHERAL PIN SELECT OUTPUT REGISTER 7

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP15R4	RP15R3	RP15R2	RP15R1	RP15R0
bit 15						bit 8	

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP14R4	RP14R3	RP14R2	RP14R1	RP14R0
bit 7						bit 0	

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP15R<4:0>:** Peripheral Output Function is Assigned to RP15 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP14R<4:0>:** Peripheral Output Function is Assigned to RP14 Output Pin bits  
(see [Table 10-3](#) for peripheral function numbers)

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## REGISTER 10-23: RPOR8: PERIPHERAL PIN SELECT OUTPUT REGISTER 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP17R4 <sup>(1)</sup>	RP17R3 <sup>(1)</sup>	RP17R2 <sup>(1)</sup>	RP17R1 <sup>(1)</sup>	RP17R0 <sup>(1)</sup>
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP16R4 <sup>(1)</sup>	RP16R3 <sup>(1)</sup>	RP16R2 <sup>(1)</sup>	RP16R1 <sup>(1)</sup>	RP16R0 <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP17R<4:0>:** Peripheral Output Function is Assigned to RP17 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP16R<4:0>:** Peripheral Output Function is Assigned to RP16 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

**Note 1:** These bits are only available on the 44-pin devices; otherwise, they read as '0'.

## REGISTER 10-24: RPOR9: PERIPHERAL PIN SELECT OUTPUT REGISTER 9

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP19R4 <sup>(1)</sup>	RP19R3 <sup>(1)</sup>	RP19R2 <sup>(1)</sup>	RP19R1 <sup>(1)</sup>	RP19R0 <sup>(1)</sup>
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP18R4 <sup>(1)</sup>	RP18R3 <sup>(1)</sup>	RP18R2 <sup>(1)</sup>	RP18R1 <sup>(1)</sup>	RP18R0 <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP19R<4:0>:** Peripheral Output Function is Assigned to RP19 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP18R<4:0>:** Peripheral Output Function is Assigned to RP18 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

**Note 1:** These bits are only available on the 44-pin devices; otherwise, they read as '0'.

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## REGISTER 10-25: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP21R4 <sup>(1)</sup>	RP21R3 <sup>(1)</sup>	RP21R2 <sup>(1)</sup>	RP21R1 <sup>(1)</sup>	RP21R0 <sup>(1)</sup>
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP20R4 <sup>(1)</sup>	RP20R3 <sup>(1)</sup>	RP20R2 <sup>(1)</sup>	RP20R1 <sup>(1)</sup>	RP20R0 <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP21R<4:0>:** Peripheral Output Function is Assigned to RP21 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP20R<4:0>:** Peripheral Output Function is Assigned to RP20 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

**Note 1:** These bits are only available on the 44-pin devices; otherwise, they read as '0'.

## REGISTER 10-26: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP23R4 <sup>(1)</sup>	RP23R3 <sup>(1)</sup>	RP23R2 <sup>(1)</sup>	RP23R1 <sup>(1)</sup>	RP23R0 <sup>(1)</sup>
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP22R4 <sup>(1)</sup>	RP22R3 <sup>(1)</sup>	RP22R2 <sup>(1)</sup>	RP22R1 <sup>(1)</sup>	RP22R0 <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP23R<4:0>:** Peripheral Output Function is Assigned to RP23 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP22R<4:0>:** Peripheral Output Function is Assigned to RP22 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

**Note 1:** These bits are only available on the 44-pin devices; otherwise, they read as '0'.

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## REGISTER 10-27: RPOR12: PERIPHERAL PIN SELECT OUTPUT REGISTER 12

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP25R4 <sup>(1)</sup>	RP25R3 <sup>(1)</sup>	RP25R2 <sup>(1)</sup>	RP25R1 <sup>(1)</sup>	RP25R0 <sup>(1)</sup>
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP24R4 <sup>(1)</sup>	RP24R3 <sup>(1)</sup>	RP24R2 <sup>(1)</sup>	RP24R1 <sup>(1)</sup>	RP24R0 <sup>(1)</sup>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13     **Unimplemented:** Read as '0'

bit 12-8     **RP25R<4:0>:** Peripheral Output Function is Assigned to RP25 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

bit 7-5     **Unimplemented:** Read as '0'

bit 4-0     **RP24R<4:0>:** Peripheral Output Function is Assigned to RP24 Output Pin bits<sup>(1)</sup>  
(see [Table 10-3](#) for peripheral function numbers)

**Note 1:** These bits are only available on the 44-pin devices; otherwise, they read as '0'.



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## REGISTER 11-1: T1CON: TIMER1 CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
—	TGATE	TCKPS1	TCKPS0	—	TSYNC	TCS	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **TON:** Timer1 On bit  
               1 = Starts 16-bit Timer1  
               0 = Stops 16-bit Timer1
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **TSIDL:** Timer1 Stop in Idle Mode bit  
               1 = Discontinues module operation when device enters Idle mode  
               0 = Continues module operation in Idle mode
- bit 12-7    **Unimplemented:** Read as '0'
- bit 6      **TGATE:** Timer1 Gated Time Accumulation Enable bit  
               When TCS = 1:  
               This bit is ignored.  
               When TCS = 0:  
               1 = Gated time accumulation is enabled  
               0 = Gated time accumulation is disabled
- bit 5-4    **TCKPS<1:0>:** Timer1 Input Clock Prescale Select bits  
               11 = 1:256  
               10 = 1:64  
               01 = 1:8  
               00 = 1:1
- bit 3      **Unimplemented:** Read as '0'
- bit 2      **TSYNC:** Timer1 External Clock Input Synchronization Select bit  
               When TCS = 1:  
               1 = Synchronizes external clock input  
               0 = Does not synchronize external clock input  
               When TCS = 0:  
               This bit is ignored.
- bit 1      **TCS:** Timer1 Clock Source Select bit  
               1 = External clock from T1CK pin (on the rising edge)  
               0 = Internal clock (Fosc/2)
- bit 0      **Unimplemented:** Read as '0'

## 12.0 TIMER2/3 AND TIMER4/5

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Timers” (DS39704).

The Timer2/3 and Timer4/5 modules are 32-bit timers, which can also be configured as four independent, 16-bit timers with selectable operating modes.

As a 32-bit timer, Timer2/3 and Timer4/5 operate in three modes:

- Two independent, 16-bit timers (Timer2 and Timer3) with all 16-bit operating modes (except Asynchronous Counter mode)
- Single 32-bit timer
- Single 32-bit synchronous counter

They also support these features:

- Timer gate operation
- Selectable prescaler settings
- Timer operation during Idle and Sleep modes
- Interrupt on a 32-Bit Period register match
- A/D Event Trigger (Timer2/3 only)

Individually, all four of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed above, except for the A/D Event Trigger; this is implemented only with Timer3. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON, T3CON, T4CON and T5CON registers. T2CON and T4CON are shown in generic form in [Register 12-1](#); T3CON and T5CON are shown in generic form in [Register 12-2](#).

For 32-bit timer/counter operation, Timer2 and Timer4 are the least significant word; Timer3 and Timer4 are the most significant word of the 32-bit timers.

**Note:** For 32-bit operation, T3CON and T5CON control bits are ignored. Only T2CON and T4CON control bits are used for setup and control. Timer2 and Timer4 clock and gate inputs are utilized for the 32-bit timer modules, but an interrupt is generated with the Timer3 or Timer5 interrupt flags.

To configure Timer2/3 or Timer4/5 for 32-bit operation:

1. Set the T32 bit (T2CON<3> or T4CON<3> = 1).
2. Select the prescaler ratio for Timer2 or Timer4 using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. If TCS is set to the external clock, RPNRx (TxCK) must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
4. Load the timer period value. PR3 (or PR5) will contain the most significant word of the value while PR2 (or PR4) contains the least significant word.
5. If interrupts are required, set the Timer3/5 Interrupt Enable bit, T3IE or T5IE; use the priority bits, T3IP<2:0> or T5IP<2:0>, to set the interrupt priority. Note that while Timer2 or Timer4 controls the timer, the interrupt appears as a Timer3 or Timer5 interrupt.
6. Set the TON bit (= 1).

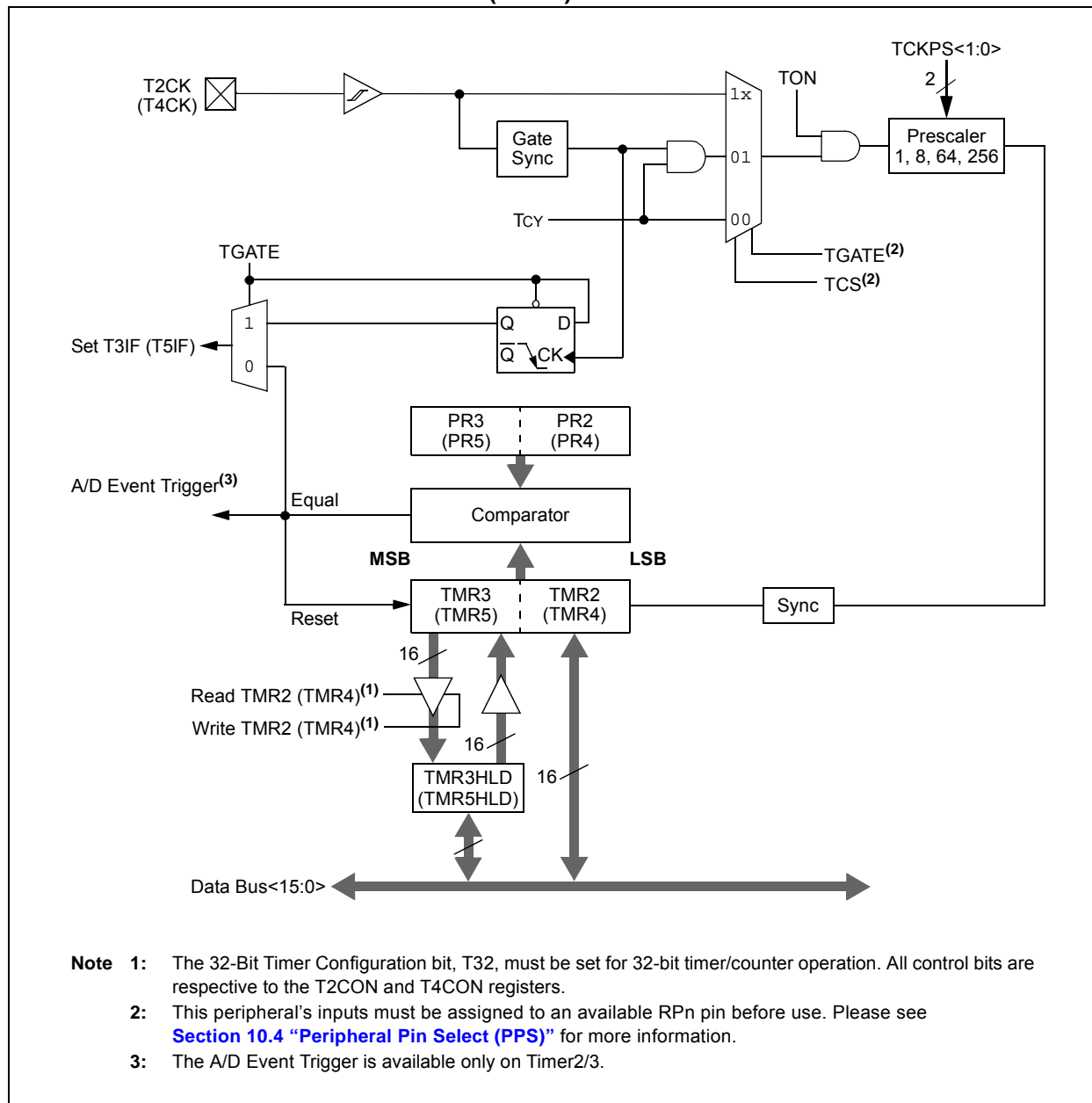
The timer value, at any point, is stored in the register pair, TMR3:TMR2 (or TMR5:TMR4). TMR3 (TMR5) always contains the most significant word of the count, while TMR2 (TMR4) contains the least significant word.

To configure any of the timers for individual 16-bit operation:

1. Clear the T32 bit corresponding to that timer (T2CON<3> for Timer2 and Timer3 or T4CON<3> for Timer4 and Timer5).
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
4. Load the timer period value into the PRx register.
5. If interrupts are required, set the Timerx Interrupt Enable bit, TxIE; use the priority bits, TxIP<2:0>, to set the interrupt priority.
6. Set the TON bit (TxCON<15> = 1).

# PIC24FJ64GA004 FAMILY

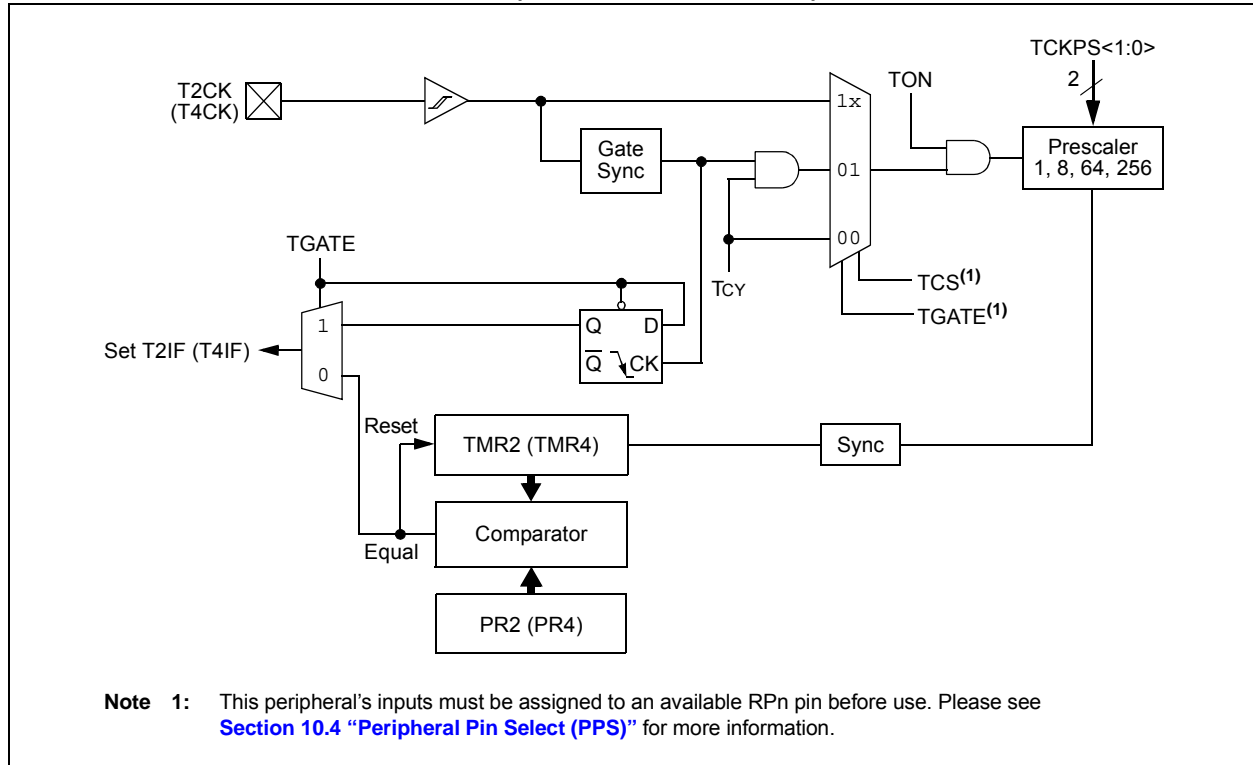
**FIGURE 12-1: TIMER2/3 AND TIMER4/5 (32-BIT) BLOCK DIAGRAM**



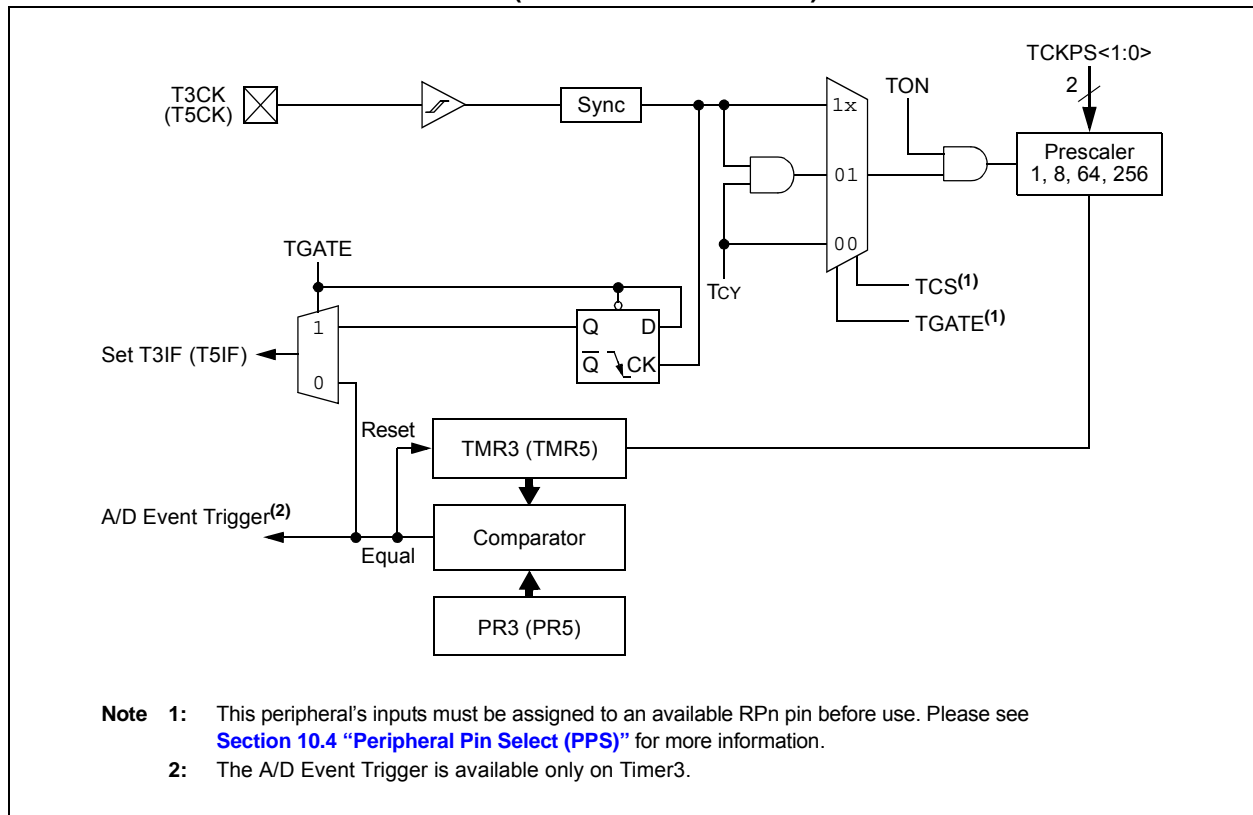


# PIC24FJ64GA004 FAMILY

**FIGURE 12-2: TIMER2 AND TIMER4 (16-BIT SYNCHRONOUS) BLOCK DIAGRAM**



**FIGURE 12-3: TIMER3 AND TIMER5 (16-BIT SYNCHRONOUS) BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## REGISTER 12-1: TxCON: TIMER2 AND TIMER4 CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
—	TGATE	TCKPS1	TCKPS0	T32 <sup>(1)</sup>	—	TCS <sup>(2)</sup>	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **TON:** Timerx On bit

When TxCON<3> = 1:

1 = Starts 32-bit Timerx/y

0 = Stops 32-bit Timerx/y

When TxCON<3> = 0:

1 = Starts 16-bit Timerx

0 = Stops 16-bit Timerx

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Timerx Stop in Idle Mode bit

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timerx Gated Time Accumulation Enable bit

When TCS = 1:

This bit is ignored.

When TCS = 0:

1 = Gated time accumulation is enabled

0 = Gated time accumulation is disabled

bit 5-4 **TCKPS<1:0>:** Timerx Input Clock Prescale Select bits

11 = 1:256

10 = 1:64

01 = 1:8

00 = 1:1

bit 3 **T32:** 32-Bit Timer Mode Select bit<sup>(1)</sup>

1 = Timerx and Timery form a single 32-bit timer

0 = Timerx and Timery act as two 16-bit timers

In 32-bit mode, T3CON control bits do not affect 32-bit timer operation.

bit 2 **Unimplemented:** Read as '0'

bit 1 **TCS:** Timerx Clock Source Select bit<sup>(2)</sup>

1 = External clock from pin, TxCK (on the rising edge)

0 = Internal clock (Fosc/2)

bit 0 **Unimplemented:** Read as '0'

**Note 1:** In 32-bit mode, the T3CON or T5CON control bits do not affect 32-bit timer operation.

**Note 2:** If TCS = 1, RPNRx (TxCK) must be configured to an available RPN pin. For more information, see [Section 10.4 "Peripheral Pin Select \(PPS\)"](#).

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**REGISTER 12-2: TyCON: TIMER3 AND TIMER5 CONTROL REGISTER**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON <sup>(1)</sup>	—	TSIDL <sup>(1)</sup>	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
—	TGATE <sup>(1)</sup>	TCKPS1 <sup>(1)</sup>	TCKPS0 <sup>(1)</sup>	—	—	TCS <sup>(1,2)</sup>	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **TON:** Timery On bit<sup>(1)</sup>

1 = Starts 16-bit Timery

0 = Stops 16-bit Timery

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Timery Stop in Idle Mode bit<sup>(1)</sup>

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timery Gated Time Accumulation Enable bit<sup>(1)</sup>

When TCS = 1:

This bit is ignored.

When TCS = 0:

1 = Gated time accumulation is enabled

0 = Gated time accumulation is disabled

bit 5-4 **TCKPS<1:0>:** Timery Input Clock Prescale Select bits<sup>(1)</sup>

11 = 1:256

10 = 1:64

01 = 1:8

00 = 1:1

bit 3-2 **Unimplemented:** Read as '0'

bit 1 **TCS:** Timery Clock Source Select bit<sup>(1,2)</sup>

1 = External clock from pin, TyCK (on the rising edge)

0 = Internal clock (FOSC/2)

bit 0 **Unimplemented:** Read as '0'

**Note 1:** When 32-bit operation is enabled (T2CON<3> or T4CON<3> = 1), these bits have no effect on Timery operation; all timer functions are set through T2CON and T4CON.

**2:** If TCS = 1, RPNRx (TxCK) must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

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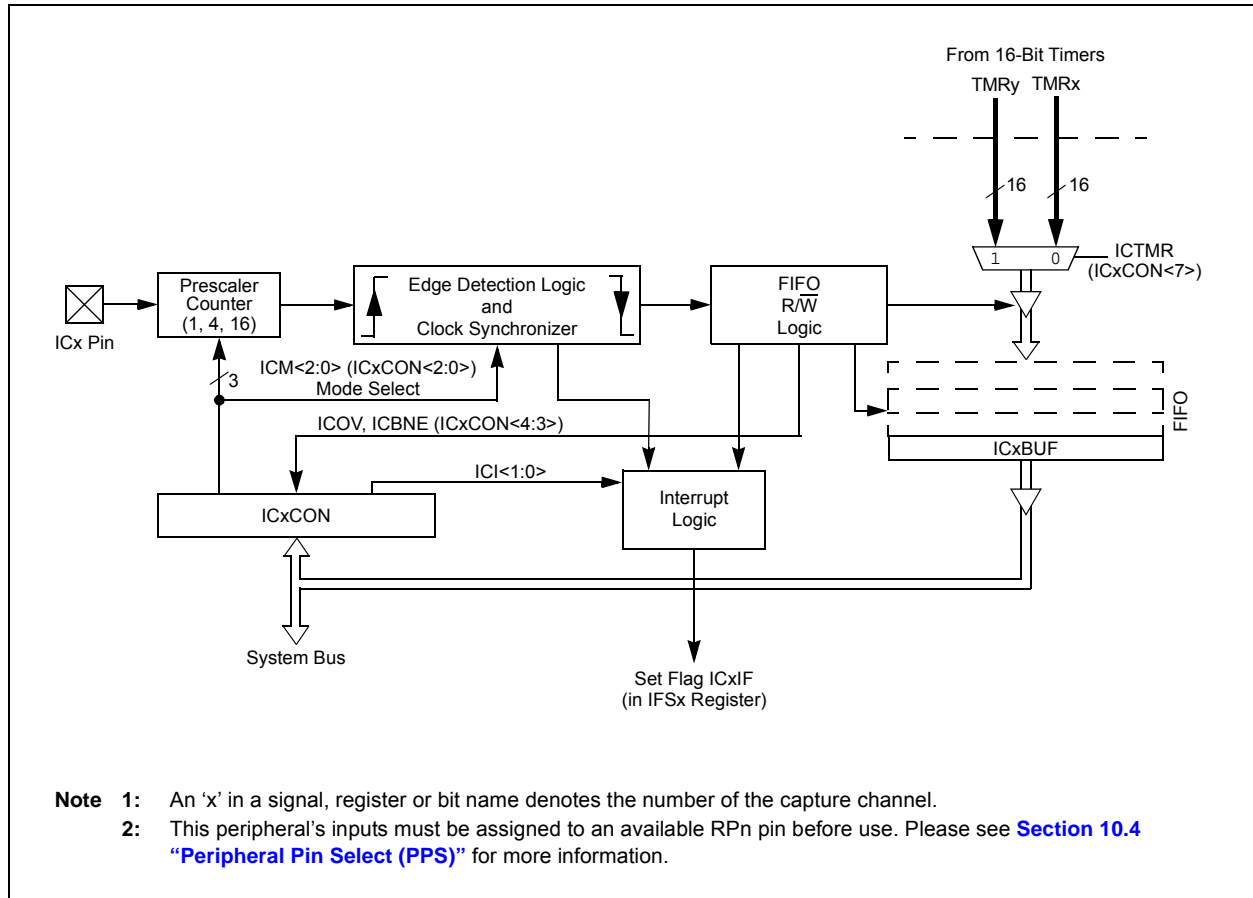
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NOTES:

## 13.0 INPUT CAPTURE

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Input Capture” (DS39701).

**FIGURE 13-1: INPUT CAPTURE x BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## 13.1 Input Capture Registers

**REGISTER 13-1: ICxCON: INPUT CAPTURE x CONTROL REGISTER**

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	ICSIDL	—	—	—	—	—
bit 15						bit 8	
R/W-0	R/W-0	R/W-0	R-0, HC	R-0, HC	R/W-0	R/W-0	R/W-0
ICTMR	ICI1	ICI0	ICOV	ICBNE	ICM2 <sup>(1)</sup>	ICM1 <sup>(1)</sup>	ICM0 <sup>(1)</sup>
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **ICSIDL:** Input Capture x Stop in Idle Control bit  
 1 = Input capture module will halt in CPU Idle mode  
 0 = Input capture module will continue to operate in CPU Idle mode
- bit 12-8 **Unimplemented:** Read as '0'
- bit 7 **ICTMR:** Input Capture x Timer Select bit  
 1 = TMR2 contents are captured on capture event  
 0 = TMR3 contents are captured on capture event
- bit 6-5 **ICI<1:0>:** Select Number of Captures per Interrupt bits  
 11 = Interrupt on every fourth capture event  
 10 = Interrupt on every third capture event  
 01 = Interrupt on every second capture event  
 00 = Interrupt on every capture event
- bit 4 **ICOV:** Input Capture x Overflow Status Flag bit (read-only)  
 1 = Input capture overflow occurred  
 0 = No input capture overflow occurred
- bit 3 **ICBNE:** Input Capture x Buffer Empty Status bit (read-only)  
 1 = Input capture buffer is not empty, at least one more capture value can be read  
 0 = Input capture buffer is empty
- bit 2-0 **ICM<2:0>:** Input Capture x Mode Select bits<sup>(1)</sup>  
 111 = Input capture functions as interrupt pin only when device is in Sleep or Idle mode (rising edge detect only, all other control bits are not applicable)  
 110 = Unused (module is disabled)  
 101 = Capture mode, every 16th rising edge  
 100 = Capture mode, every 4th rising edge  
 011 = Capture mode, every rising edge  
 010 = Capture mode, every falling edge  
 001 = Capture mode, every edge (rising and falling) – ICI<1:0> bits do not control interrupt generation for this mode  
 000 = Input capture module is turned off

**Note 1:** RPINRx (ICxRx) must be configured to an available RPN pin. For more information, see [Section 10.4 “Peripheral Pin Select \(PPS\)”](#).

## 14.0 OUTPUT COMPARE

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **"Output Compare"** (DS39706).

### 14.1 Setup for Single Output Pulse Generation

When the OCM<2:0> control bits (OCxCON<2:0>) are set to '100', the selected output compare channel initializes the OCx pin to the low state and generates a single output pulse.

To generate a single output pulse, the following steps are required (these steps assume the timer source is initially turned off, but this is not a requirement for the module operation):

1. Determine the instruction clock cycle time. Take into account the frequency of the external clock to the timer source (if one is used) and the timer prescaler settings.
2. Calculate the time to the rising edge of the output pulse relative to the TMRy start value (0000h).
3. Calculate the time to the falling edge of the pulse based on the desired pulse width and the time to the rising edge of the pulse.
4. Write the values computed in Steps 2 and 3 above into the Output Compare x register, OCxR, and the Output Compare x Secondary register, OCxRS, respectively.
5. Set the Timery Period register, PRy, to a value equal to or greater than the value in OCxRS, the Output Compare x Secondary register.
6. Set the OCMx bits to '100' and the OCTSEL (OCxCON<3>) bit to the desired timer source. The OCx pin state will now be driven low.
7. Set the TON (TyCON<15>) bit to '1', which enables the compare time base to count.
8. Upon the first match between TMRy and OCxR, the OCx pin will be driven high.
9. When the incrementing timer, TMRy, matches the Output Compare x Secondary register, OCxRS, the second and trailing edge (high-to-low) of the pulse is driven onto the OCx pin. No additional pulses are driven onto the OCx pin and it remains at low. As a result of the second compare match event, the OCxIF interrupt flag bit is set, which will result in an interrupt if it is enabled, by setting the OCxIE bit. For further information on peripheral interrupts, refer to [Section 7.0 "Interrupt Controller"](#).

10. To initiate another single pulse output, change the Timer and Compare register settings, if needed, and then issue a write to set the OCMx bits to '100'. Disabling and re-enabling the timer and clearing the TMRy register are not required, but may be advantageous for defining a pulse from a known event time boundary.

The output compare module does not have to be disabled after the falling edge of the output pulse. Another pulse can be initiated by rewriting the value of the OCxCON register.

### 14.2 Setup for Continuous Output Pulse Generation

When the OCM<2:0> control bits (OCxCON<2:0>) are set to '101', the selected output compare channel initializes the OCx pin to the low state and generates output pulses on each and every compare match event.

For the user to configure the module for the generation of a continuous stream of output pulses, the following steps are required (these steps assume the timer source is initially turned off, but this is not a requirement for the module operation):

1. Determine the instruction clock cycle time. Take into account the frequency of the external clock to the timer source (if one is used) and the timer prescaler settings.
2. Calculate the time to the rising edge of the output pulse relative to the TMRy start value (0000h).
3. Calculate the time to the falling edge of the pulse based on the desired pulse width and the time to the rising edge of the pulse.
4. Write the values computed in Steps 2 and 3 above into the Output Compare x register, OCxR, and the Output Compare x Secondary register, OCxRS, respectively.
5. Set the Timery Period register, PRy, to a value equal to or greater than the value in OCxRS.
6. Set the OCMx bits to '101' and the OCTSEL bit to the desired timer source. The OCx pin state will now be driven low.
7. Enable the compare time base by setting the TON (TyCON<15>) bit to '1'.
8. Upon the first match between TMRy and OCxR, the OCx pin will be driven high.
9. When the compare time base, TMRy, matches the OCxRS, the second and trailing edge (high-to-low) of the pulse is driven onto the OCx pin.
10. As a result of the second compare match event, the OCxIF interrupt flag bit set.
11. When the compare time base and the value in its respective Timery Period register match, the TMRy register resets to 0x0000 and resumes counting.
12. Steps 8 through 11 are repeated and a continuous stream of pulses is generated indefinitely. The OCxIF flag is set on each OCxRS/TMRy compare match event.

# PIC24FJ64GA004 FAMILY

## 14.3 Pulse-Width Modulation Mode

**Note:** This peripheral contains input and output functions that may need to be configured by the Peripheral Pin Select. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

The following steps should be taken when configuring the output compare module for PWM operation:

1. Set the PWM period by writing to the selected Timery Period register (PRy).
2. Set the PWM duty cycle by writing to the OCxRS register.
3. Write the OCxR register with the initial duty cycle.
4. Enable interrupts, if required, for the timer and output compare modules. The output compare interrupt is required for PWM Fault pin utilization.
5. Configure the output compare module for one of two PWM Operation modes by writing to the Output Compare Mode bits, OCM<2:0> (OCxCON<2:0>).
6. Set the TMRY prescale value and enable the time base by setting TON (TyCON<15>) = 1.

**Note:** The OCxR register should be initialized before the output compare module is first enabled. The OCxR register becomes a read-only Duty Cycle register when the module is operated in the PWM modes. The value held in OCxR will become the PWM duty cycle for the first PWM period. The contents of the Output Compare x Secondary register, OCxRS, will not be transferred into OCxR until a time base period match occurs.

### 14.3.1 PWM PERIOD

The PWM period is specified by writing to PRy, the Timery Period register. The PWM period can be calculated using [Equation 14-1](#).

### EQUATION 14-1: CALCULATING THE PWM PERIOD<sup>(1)</sup>

$$\text{PWM Period} = [\text{PRy} + 1] \cdot \text{TCY} \cdot (\text{Timer Prescale Value})$$

Where:

$$\text{PWM Frequency} = 1/[\text{PWM Period}]$$

**Note 1:** Based on TCY = 2 \* TOSC; Doze mode and PLL are disabled.

**Note:** A PRy value of N will produce a PWM period of N + 1 time base count cycles. For example, a value of 7 written into the PRy register will yield a period consisting of 8 time base cycles.

### 14.3.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing to the OCxRS register. The OCxRS register can be written to at any time, but the duty cycle value is not latched into OCxR until a match between PRy and TMRY occurs (i.e., the period is complete). This provides a double buffer for the PWM duty cycle and is essential for glitch-less PWM operation. In the PWM mode, OCxR is a read-only register.

Some important boundary parameters of the PWM duty cycle include:

- If the Output Compare x register, OCxR, is loaded with 0000h, the OCx pin will remain low (0% duty cycle).
- If OCxR is greater than PRy (Timery Period register), the pin will remain high (100% duty cycle).
- If OCxR is equal to PRy, the OCx pin will be low for one time base count value and high for all other count values.

See [Example 14-1](#) for PWM mode timing details. [Table 14-1](#) and [Table 14-2](#) show example PWM frequencies and resolutions for a device operating at 4 and 16 MIPS.

### EQUATION 14-2: CALCULATION FOR MAXIMUM PWM RESOLUTION<sup>(1)</sup>

$$\text{Maximum PWM Resolution (bits)} = \frac{\log_{10} \left( \frac{\text{FCY}}{\text{FPWM} \cdot (\text{Timer Prescale Value})} \right)}{\log_{10}(2)} \text{ bits}$$

**Note 1:** Based on FCY = FOSC/2; Doze mode and PLL are disabled.



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## EXAMPLE 14-1: PWM PERIOD AND DUTY CYCLE CALCULATIONS<sup>(1)</sup>

- Find the Timer Period register value for a desired PWM frequency of 52.08 kHz, where FOSC = 8 MHz with PLL (32 MHz device clock rate) and a Timer2 prescaler setting of 1:1.  

$$T_{CY} = 2 \cdot T_{OSC} = 62.5 \text{ ns}$$

$$\text{PWM Period} = 1/\text{PWM Frequency} = 1/52.08 \text{ kHz} = 19.2 \text{ } \mu\text{s}$$

$$\text{PWM Period} = (\text{PR2} + 1) \cdot T_{CY} \cdot (\text{Timer2 Prescale Value})$$

$$19.2 \text{ } \mu\text{s} = (\text{PR2} + 1) \cdot 62.5 \text{ ns} \cdot 1$$

$$\text{PR2} = 306$$
- Find the maximum resolution of the duty cycle that can be used with a 52.08 kHz frequency and a 32 MHz device clock rate:  

$$\text{PWM Resolution} = \log_{10}(\text{FCY}/\text{FPWM})/\log_{10}(2) \text{ bits}$$

$$= (\log_{10}(16 \text{ MHz}/52.08 \text{ kHz})/\log_{10}(2)) \text{ bits}$$

$$= 8.3 \text{ bits}$$

**Note 1:** Based on  $T_{CY} = 2 \cdot T_{OSC}$ ; Doze mode and PLL are disabled.

## TABLE 14-1: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 4 MIPS (FCY = 4 MHz)<sup>(1)</sup>

PWM Frequency	7.6 Hz	61 Hz	122 Hz	977 Hz	3.9 kHz	31.3 kHz	125 kHz
Timer Prescaler Ratio	8	1	1	1	1	1	1
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh
Resolution (bits)	16	16	15	12	10	7	5

**Note 1:** Based on  $\text{FCY} = \text{FOSC}/2$ ; Doze mode and PLL are disabled.

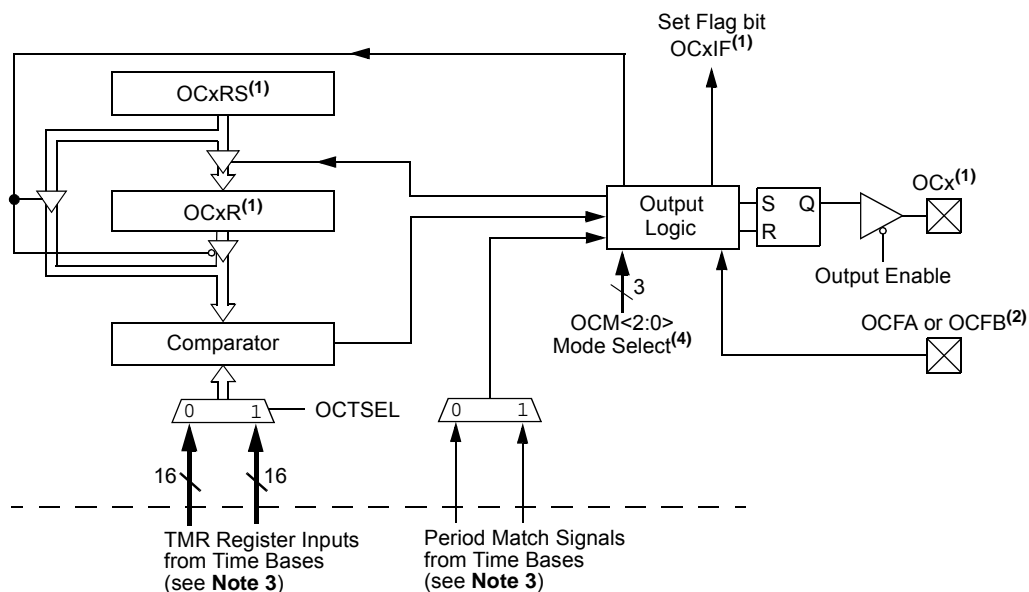
## TABLE 14-2: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 16 MIPS (FCY = 16 MHz)<sup>(1)</sup>

PWM Frequency	30.5 Hz	244 Hz	488 Hz	3.9 kHz	15.6 kHz	125 kHz	500 kHz
Timer Prescaler Ratio	8	1	1	1	1	1	1
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh
Resolution (bits)	16	16	15	12	10	7	5

**Note 1:** Based on  $\text{FCY} = \text{FOSC}/2$ ; Doze mode and PLL are disabled.

# PIC24FJ64GA004 FAMILY

**FIGURE 14-1: OUTPUT COMPARE x MODULE BLOCK DIAGRAM**



- Note 1:** Where 'x' is shown, reference is made to the registers associated with the respective Output Compare Channels 1 through 5.
- Note 2:** The OCFA pin controls the OC1-OC4 channels. The OCFB pin controls the OC5 channel.
- Note 3:** Each output compare channel can use one of two selectable time bases. Refer to the device data sheet for the time bases associated with the module.
- Note 4:** This peripheral's inputs and outputs must be assigned to an available RPN pin before use. Please see [Section 10.4 "Peripheral Pin Select \(PPS\)"](#) for more information.

# PIC24FJ64GA004 FAMILY

## 14.4 Output Compare Register

**REGISTER 14-1: OCxCON: OUTPUT COMPARE x CONTROL REGISTER**

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	OCSIDL	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R-0, HC	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	OCFLT	OCTSEL	OCM2 <sup>(1)</sup>	OCM1 <sup>(1)</sup>	OCM0 <sup>(1)</sup>
bit 7							bit 0

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **OCSIDL:** Output Compare x Stop in Idle Mode Control bit  
 1 = Output Compare x halts in CPU Idle mode  
 0 = Output Compare x continues to operate in CPU Idle mode
- bit 12-5 **Unimplemented:** Read as '0'
- bit 4 **OCFLT:** PWM Fault Condition Status bit  
 1 = PWM Fault condition has occurred (cleared in HW only)  
 0 = No PWM Fault condition has occurred (this bit is only used when OCM<2:0> = 111)
- bit 3 **OCTSEL:** Output Compare x Timer Select bit  
 1 = Timer3 is the clock source for Output Compare x  
 0 = Timer2 is the clock source for Output Compare x  
 Refer to the device data sheet for specific time bases available to the output compare module.
- bit 2-0 **OCM<2:0>:** Output Compare x Mode Select bits<sup>(1)</sup>  
 111 = PWM mode on OCx; Fault pin, OCFx, is enabled<sup>(2)</sup>  
 110 = PWM mode on OCx; Fault pin, OCFx, is disabled<sup>(2)</sup>  
 101 = Initializes OCx pin low, generates continuous output pulses on OCx pin  
 100 = Initializes OCx pin low, generates single output pulse on OCx pin  
 011 = Compare event toggles OCx pin  
 010 = Initializes OCx pin high, compare event forces OCx pin low  
 001 = Initializes OCx pin low, compare event forces OCx pin high  
 000 = Output compare channel is disabled

**Note 1:** RPORx (OCx) must be configured to an available RPN pin. For more information, see [Section 10.4 "Peripheral Pin Select \(PPS\)"](#).

**2:** The OCFA pin controls the OC1-OC4 channels. The OCFB pin controls the OC5 channel.

# PIC24FJ64GA004 FAMILY

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NOTES:

## 15.0 SERIAL PERIPHERAL INTERFACE (SPI)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, **"Serial Peripheral Interface (SPI)"** (DS39699)

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D Converters, etc. The SPI module is compatible with the SPI and SIOP Motorola® interfaces.

The module supports operation in two buffer modes. In Standard mode, data is shifted through a single serial buffer. In Enhanced Buffer mode, data is shifted through an 8-level FIFO buffer.

**Note:** Do not perform read-modify-write operations (such as bit-oriented instructions) on the SPIxBUF register in either Standard or Enhanced Buffer mode.

The module also supports a basic framed SPI protocol while operating in either Master or Slave mode. A total of four framed SPI configurations are supported.

The SPI serial interface consists of four pins:

- SDIx: Serial Data Input
- SDOx: Serial Data Output
- SCKx: Shift Clock Input or Output
- $\overline{\text{SS}}\text{x}$ : Active-Low Slave Select or Frame Synchronization I/O Pulse

The SPI module can be configured to operate using 2, 3 or 4 pins. In the 3-pin mode,  $\overline{\text{SS}}\text{x}$  is not used. In the 2-pin mode, both SDOx and  $\overline{\text{SS}}\text{x}$  are not used.

Block diagrams of the module in Standard and Enhanced modes are shown in [Figure 15-1](#) and [Figure 15-2](#).

Depending on the pin count, PIC24FJ64GA004 family devices offer one or two SPI modules on a single device.

**Note:** In this section, the SPI modules are referred to together as SPIx or separately as SPI1 and SPI2. Special Function Registers will follow a similar notation. For example, SPIxCON1 or SPIxCON2 refers to the control register for the SPI1 or SPI2 module.

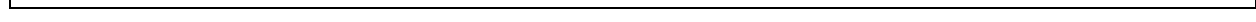
To set up the SPIx module for the Standard Master mode of operation:

1. If using interrupts:
  - a) Clear the SPIxIF bit in the respective IFSx register.
  - b) Set the SPIxIE bit in the respective IECx register.
  - c) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
2. Write the desired settings to the SPIxCON1 and SPIxCON2 registers with the MSTEN bit (SPIxCON1<5>) = 1.
3. Clear the SPIROV bit (SPIxSTAT<6>).
4. Enable SPIx operation by setting the SPIEN bit (SPIxSTAT<15>).
5. Write the data to be transmitted to the SPIxBUF register. Transmission (and reception) will start as soon as data is written to the SPIxBUF register.

To set up the SPIx module for the Standard Slave mode of operation:

1. Clear the SPIxBUF register.
2. If using interrupts:
  - a) Clear the SPIxIF bit in the respective IFSx register.
  - b) Set the SPIxIE bit in the respective IECx register.
  - c) Write the SPIxIP bits in the respective IPCx register to set the interrupt priority.
3. Write the desired settings to the SPIxCON1 and SPIxCON2 registers with the MSTEN bit (SPIxCON1<5>) = 0.
4. Clear the SMP bit (SPIxCON1<9>).
5. If the CKE bit is set, then the  $\overline{\text{SEN}}$  bit (SPIxCON1<7>) must be set to enable the  $\overline{\text{SS}}\text{x}$  pin.
6. Clear the SPIROV bit (SPIxSTAT<6>).
7. Enable SPIx operation by setting the SPIEN bit (SPIxSTAT<15>).

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# PIC24FJ64GA004 FAMILY

## REGISTER 15-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	R-0	R-0	R-0
SPIEN <sup>(1)</sup>	—	SPISIDL	—	—	SPIBEC2	SPIBEC1	SPIBEC0
bit 15							bit 8

R-0	R/C-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0
SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **SPIEN:** SPIx Enable bit<sup>(1)</sup>  
 1 = Enables module and configures SCKx, SDOx, SDIx and  $\overline{SSx}$  as serial port pins  
 0 = Disables module
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **SPISIDL:** SPIx Stop in Idle Mode bit  
 1 = Discontinues module operation when device enters Idle mode  
 0 = Continues module operation in Idle mode
- bit 12-11 **Unimplemented:** Read as '0'
- bit 10-8 **SPIBEC<2:0>:** SPIx Buffer Element Count bits (valid in Enhanced Buffer mode)  
Master mode:  
 Number of SPI transfers pending.  
Slave mode:  
 Number of SPI transfers unread.
- bit 7 **SRMPT:** SPIx Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode)  
 1 = SPIx Shift register is empty and ready to send or receive  
 0 = SPIx Shift register is not empty
- bit 6 **SPIROV:** SPIx Receive Overflow Flag bit  
 1 = A new byte/word is completely received and discarded; the user software has not read the previous data in the SPIxBUF register  
 0 = No overflow has occurred
- bit 5 **SRXMPT:** SPIx Receive FIFO Empty bit (valid in Enhanced Buffer mode)  
 1 = Receive FIFO is empty  
 0 = Receive FIFO is not empty
- bit 4-2 **SISEL<2:0>:** SPIx Buffer Interrupt Mode bits (valid in Enhanced Buffer mode)  
 111 = Interrupt when the SPIx transmit buffer is full (SPITBF bit is set)  
 110 = Interrupt when the last bit is shifted into SPIxSR; as a result, the TX FIFO is empty  
 101 = Interrupt when the last bit is shifted out of SPIxSR; now the transmit is complete  
 100 = Interrupt when one data is shifted into the SPIxSR; as a result, the TX FIFO has one open spot  
 011 = Interrupt when the SPIx receive buffer is full (SPIRBF bit set)  
 010 = Interrupt when the SPIx receive buffer is 3/4 or more full  
 001 = Interrupt when data is available in the receive buffer (SRMPT bit is set)  
 000 = Interrupt when the last data in the receive buffer is read; as a result, the buffer is empty (SRXMPT bit is set)

**Note 1:** If SPIEN = 1, these functions must be assigned to available RPn pins before use. See [Section 10.4 "Peripheral Pin Select \(PPS\)"](#) for more information.



## REGISTER 15-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER (CONTINUED)

- bit 1      **SPITBF:** SPIx Transmit Buffer Full Status bit  
1 = Transmit has not yet started, SPIxTXB is full  
0 = Transmit has started, SPIxTXB is empty  
In Standard Buffer mode:  
Automatically set in hardware when CPU writes the SPIxBUF location, loading SPIxTXB. Automatically cleared in hardware when the SPIx module transfers data from SPIxTXB to SPIxSR.  
In Enhanced Buffer mode:  
Automatically set in hardware when CPU writes the SPIxBUF location, loading the last available buffer location. Automatically cleared in hardware when a buffer location is available for a CPU write.
- bit 0      **SPIRBF:** SPIx Receive Buffer Full Status bit  
1 = Receive is complete, SPIxRXB is full  
0 = Receive is not complete, SPIxRXB is empty  
In Standard Buffer mode:  
Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB. Automatically cleared in hardware when the core reads the SPIxBUF location, reading SPIxRXB.  
In Enhanced Buffer mode:  
Automatically set in hardware when SPIx transfers data from SPIxSR to the buffer, filling the last unread buffer location. Automatically cleared in hardware when a buffer location is available for a transfer from SPIxSR.

**Note 1:** If SPIEN = 1, these functions must be assigned to available RPN pins before use. See [Section 10.4](#) “Peripheral Pin Select (PPS)” for more information.

# PIC24FJ64GA004 FAMILY

**REGISTER 15-2: SPIxCON1: SPIx CONTROL REGISTER 1**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	DISSCK <sup>(1)</sup>	DISSDO <sup>(2)</sup>	MODE16	SMP	CKE <sup>(3)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEN <sup>(4)</sup>	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **DISSCK:** Disables SCKx Pin bit (SPI Master modes only)<sup>(1)</sup>

1 = Internal SPI clock is disabled; pin functions as I/O

0 = Internal SPI clock is enabled

bit 11 **DISSDO:** Disables SDOx Pin bit<sup>(2)</sup>

1 = SDOx pin is not used by the module; pin functions as I/O

0 = SDOx pin is controlled by the module

bit 10 **MODE16:** Word/Byte Communication Select bit

1 = Communication is word-wide (16 bits)

0 = Communication is byte-wide (8 bits)

bit 9 **SMP:** SPIx Data Input Sample Phase bit

Master mode:

1 = Input data is sampled at end of data output time

0 = Input data is sampled at middle of data output time

Slave mode:

SMP must be cleared when SPIx is used in Slave mode.

bit 8 **CKE:** SPIx Clock Edge Select bit<sup>(3)</sup>

1 = Serial output data changes on transition from active clock state to Idle clock state (see bit 6)

0 = Serial output data changes on transition from Idle clock state to active clock state (see bit 6)

bit 7 **SSEN:** Slave Select Enable bit (Slave mode)<sup>(4)</sup>

1 =  $\overline{SSx}$  pin is used for Slave mode

0 =  $\overline{SSx}$  pin is not used by the module; pin is controlled by port function

bit 6 **CKP:** Clock Polarity Select bit

1 = Idle state for the clock is a high level; active state is a low level

0 = Idle state for the clock is a low level; active state is a high level

bit 5 **MSTEN:** Master Mode Enable bit

1 = Master mode

0 = Slave mode

**Note 1:** If DISSCK = 0, SCKx must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

**2:** If DISSDO = 0, SDOx must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

**3:** The CKE bit is not used in the Framed SPI modes. The user should program this bit to '0' for the Framed SPI modes (FRMEN = 1).

**4:** If SSEN = 1,  $\overline{SSx}$  must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

# PIC24FJ64GA004 FAMILY

## REGISTER 15-2: SPIxCON1: SPIx CONTROL REGISTER 1 (CONTINUED)

bit 4-2 **SPRE<2:0>**: Secondary Prescale bits (Master mode)

111 = Secondary prescale 1:1  
 110 = Secondary prescale 2:1  
 ...  
 000 = Secondary prescale 8:1

bit 1-0 **PPRE<1:0>**: Primary Prescale bits (Master mode)

11 = Primary prescale 1:1  
 10 = Primary prescale 4:1  
 01 = Primary prescale 16:1  
 00 = Primary prescale 64:1

- Note 1:** If DISSCK = 0, SCKx must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
- 2:** If DISSDO = 0, SDOx must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
- 3:** The CKE bit is not used in the Framed SPI modes. The user should program this bit to ‘0’ for the Framed SPI modes (FRMEN = 1).
- 4:** If SSEN = 1, SSx must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

## REGISTER 15-3: SPIxCON2: SPIx CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
FRMEN	SPIFSD	SPIFPOL	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	SPIFE	SPIBEN
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as ‘0’  
 -n = Value at POR                      ‘1’ = Bit is set                      ‘0’ = Bit is cleared                      x = Bit is unknown

bit 15 **FRMEN**: Framed SPIx Support bit

1 = Framed SPIx support is enabled  
 0 = Framed SPIx support is disabled

bit 14 **SPIFSD**: SPIx Frame Sync Pulse Direction Control on SSx Pin bit

1 = Frame sync pulse input (slave)  
 0 = Frame sync pulse output (master)

bit 13 **SPIFPOL**: SPIx Frame Sync Pulse Polarity bit (Frame mode only)

1 = Frame sync pulse is active-high  
 0 = Frame sync pulse is active-low

bit 12-2 **Unimplemented**: Read as ‘0’

bit 1 **SPIFE**: SPIx Frame Sync Pulse Edge Select bit

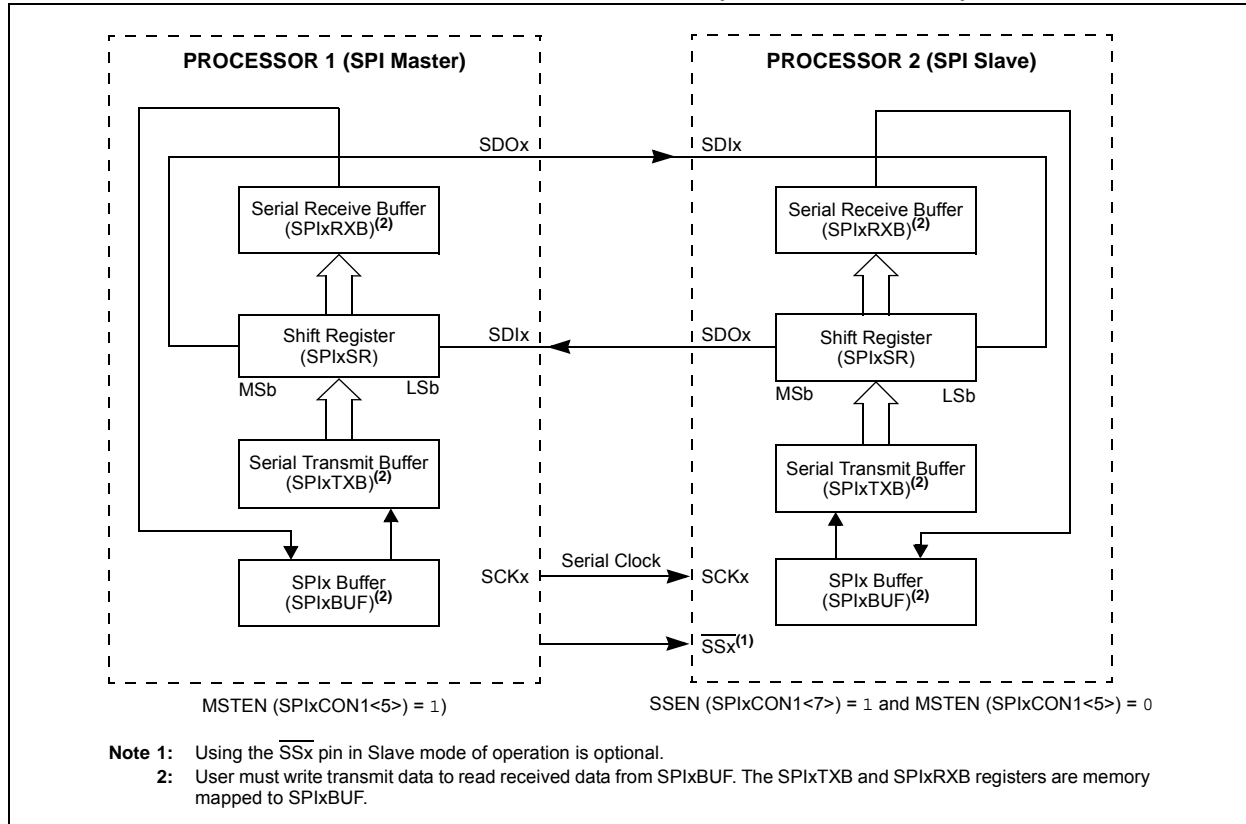
1 = Frame sync pulse coincides with first bit clock  
 0 = Frame sync pulse precedes first bit clock

bit 0 **SPIBEN**: SPIx Enhanced Buffer Enable bit

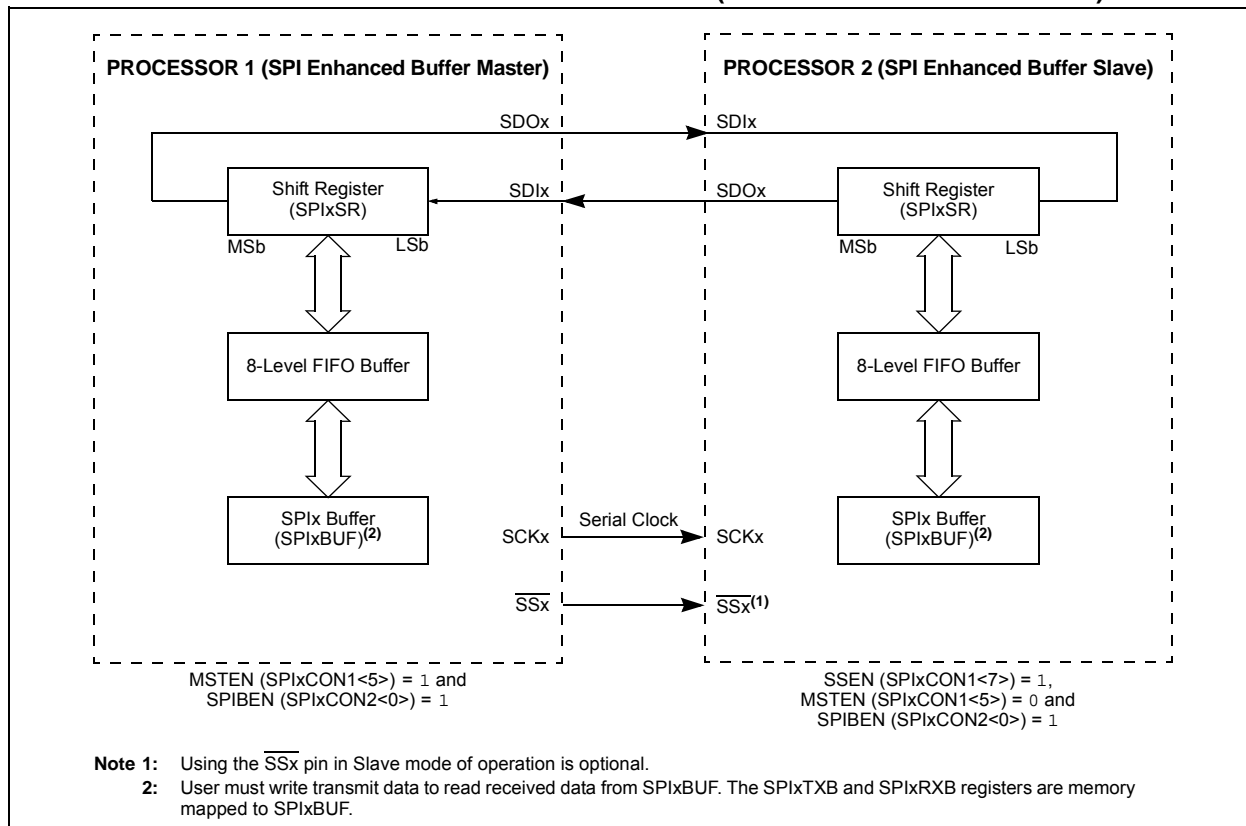
1 = Enhanced Buffer is enabled  
 0 = Enhanced Buffer is disabled (Legacy mode)

# PIC24FJ64GA004 FAMILY

**FIGURE 15-3: SPIx MASTER/SLAVE CONNECTION (STANDARD MODE)**

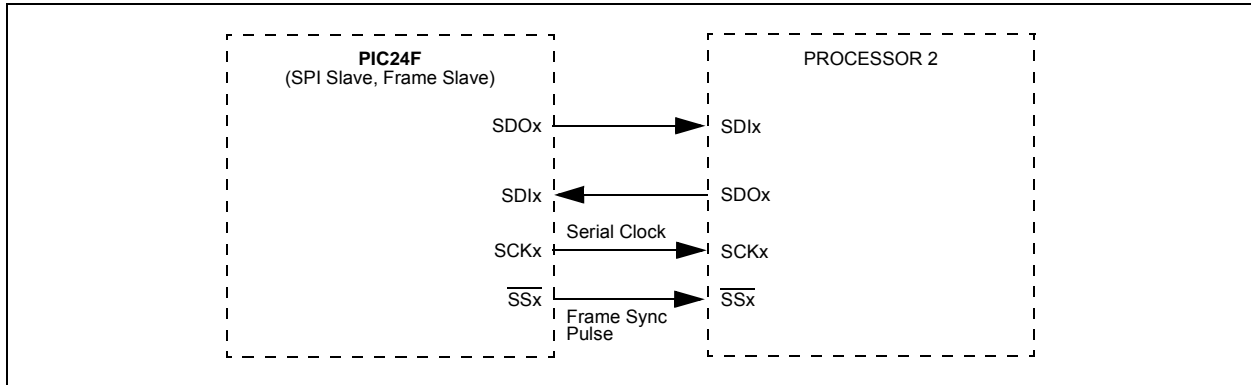


**FIGURE 15-4: SPIx MASTER/SLAVE CONNECTION (ENHANCED BUFFER MODES)**

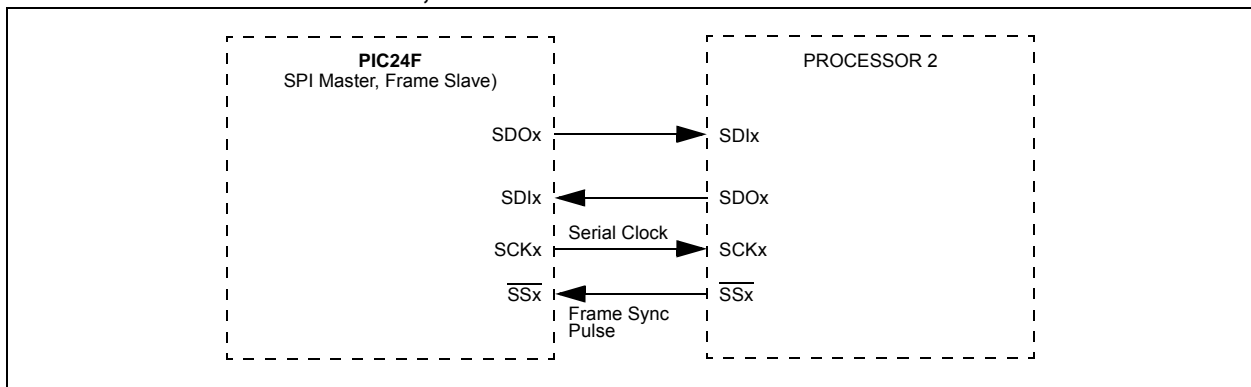


# PIC24FJ64GA004 FAMILY

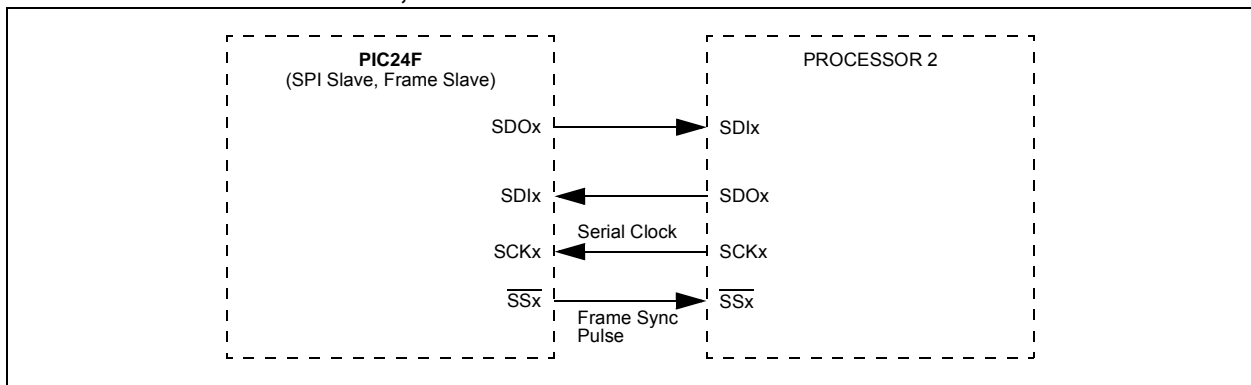
**FIGURE 15-5: SPIx MASTER, FRAME MASTER CONNECTION DIAGRAM**



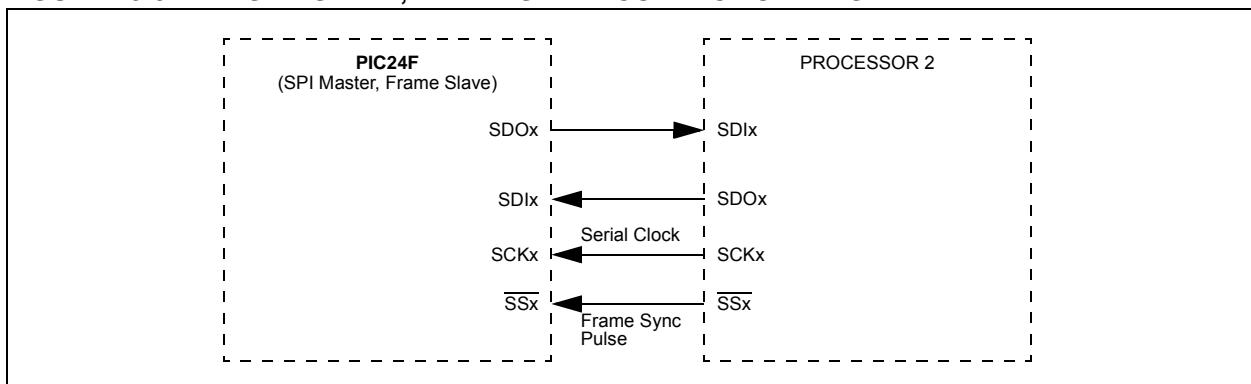
**FIGURE 15-6: SPIx MASTER, FRAME SLAVE CONNECTION DIAGRAM**



**FIGURE 15-7: SPIx SLAVE, FRAME MASTER CONNECTION DIAGRAM**



**FIGURE 15-8: SPIx SLAVE, FRAME SLAVE CONNECTION DIAGRAM**



# PIC24FJ64GA004 FAMILY

**EQUATION 15-1: RELATIONSHIP BETWEEN DEVICE AND SPIx CLOCK SPEED<sup>(1)</sup>**

$$F_{SCK} = \frac{F_{CY}}{\text{Primary Prescaler} * \text{Secondary Prescaler}}$$

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

**TABLE 15-1: SAMPLE SCKx FREQUENCIES<sup>(1,2)</sup>**

F <sub>CY</sub> = 16 MHz		Secondary Prescaler Settings				
		1:1	2:1	4:1	6:1	8:1
Primary Prescaler Settings	1:1	Invalid	8000	4000	2667	2000
	4:1	4000	2000	1000	667	500
	16:1	1000	500	250	167	125
	64:1	250	125	63	42	31
F <sub>CY</sub> = 5 MHz						
Primary Prescaler Settings	1:1	5000	2500	1250	833	625
	4:1	1250	625	313	208	156
	16:1	313	156	78	52	39
	64:1	78	39	20	13	10

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

**2:** SCKx frequencies are shown in kHz.

## 16.0 INTER-INTEGRATED CIRCUIT (I<sup>2</sup>C™)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Inter-Integrated Circuit™ (I<sup>2</sup>C™)” (DS39702).

The Inter-Integrated Circuit™ (I<sup>2</sup>C™) module is a serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, display drivers, A/D Converters, etc.

The I<sup>2</sup>C module supports these features:

- Independent master and slave logic
- 7-bit and 10-bit device addresses
- General call address, as defined in the I<sup>2</sup>C protocol
- Clock stretching to provide delays for the processor to respond to a slave data request
- Both 100 kHz and 400 kHz bus specifications
- Configurable address masking
- Multi-Master modes to prevent loss of messages in arbitration
- Bus Repeater mode, allowing the acceptance of all messages as a slave regardless of the address
- Automatic SCL

A block diagram of the module is shown in [Figure 16-1](#).

### 16.1 Peripheral Remapping Options

The I<sup>2</sup>C modules are tied to fixed pin assignments and cannot be reassigned to alternate pins using Peripheral Pin Select. To allow some flexibility with peripheral multiplexing, the I2C1 module in all devices can be reassigned to the alternate pins, designated as ASCL1 and ASDA1, during device configuration.

Pin assignment is controlled by the I2C1SEL Configuration bit; programming this bit (= 0) multiplexes the module to the ASCL1 and ASDA1 pins.

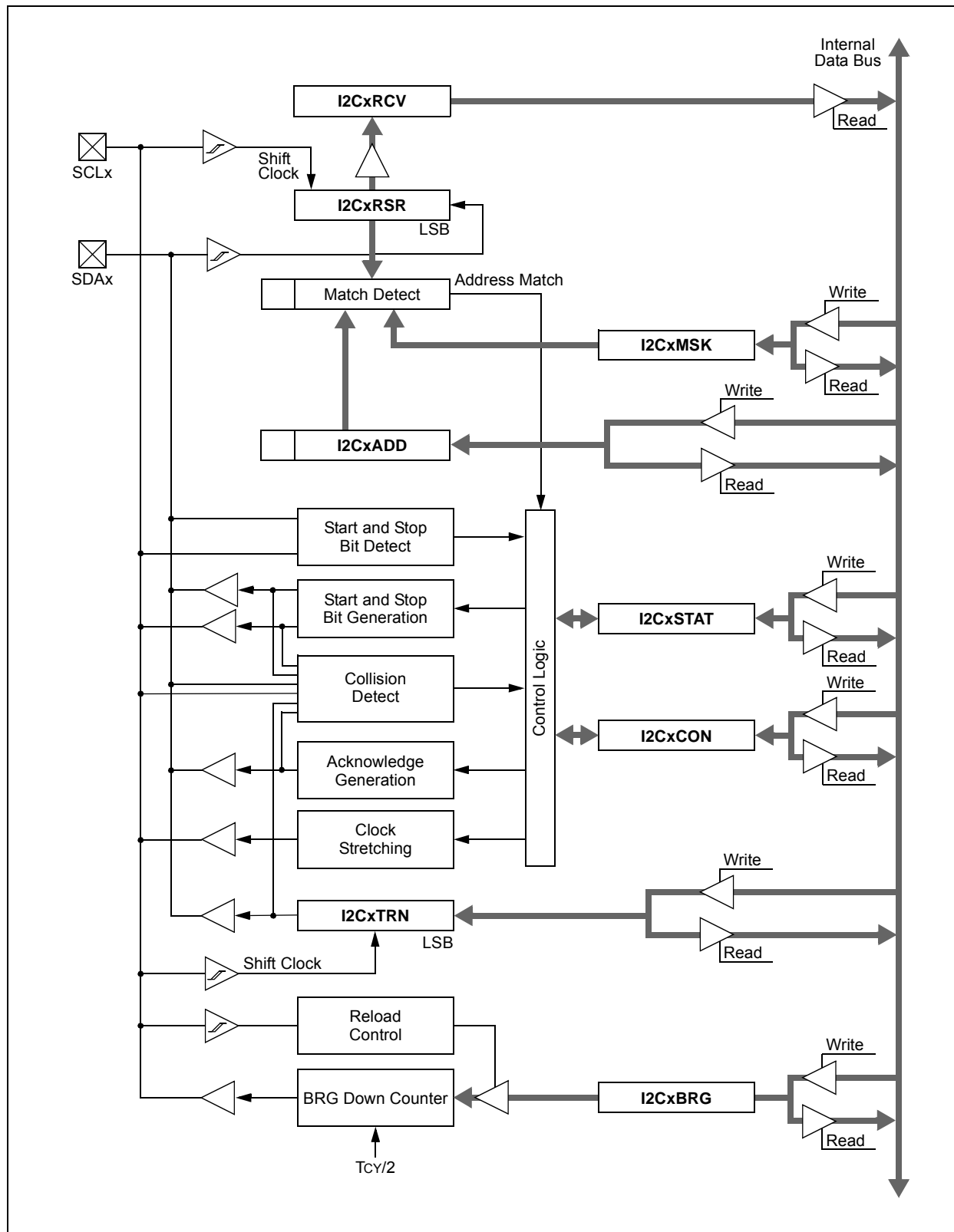
## 16.2 Communicating as a Master in a Single Master Environment

The details of sending a message in Master mode depends on the communications protocol for the device being communicated with. Typically, the sequence of events is as follows:

1. Assert a Start condition on SDAx and SCLx.
2. Send the I<sup>2</sup>C device address byte to the slave with a write indication.
3. Wait for and verify an Acknowledge from the slave.
4. Send the first data byte (sometimes known as the command) to the slave.
5. Wait for and verify an Acknowledge from the slave.
6. Send the serial memory address low byte to the slave.
7. Repeat Steps 4 and 5 until all data bytes are sent.
8. Assert a Repeated Start condition on SDAx and SCLx.
9. Send the device address byte to the slave with a read indication.
10. Wait for and verify an Acknowledge from the slave.
11. Enable master reception to receive serial memory data.
12. Generate an ACK or NACK condition at the end of a received byte of data.
13. Generate a Stop condition on SDAx and SCLx.

# PIC24FJ64GA004 FAMILY

FIGURE 16-1: I<sup>2</sup>C™ BLOCK DIAGRAM





# PIC24FJ64GA004 FAMILY

## 16.3 Setting Baud Rate When Operating as a Bus Master

To compute the Baud Rate Generator reload value, use Equation 16-1.

**EQUATION 16-1: COMPUTING BAUD RATE RELOAD VALUE<sup>(1)</sup>**

$$F_{SCL} = \frac{F_{CY}}{I2CxBRG + 1 + \frac{F_{CY}}{10,000,000}}$$

or

$$I2CxBRG = \left( \frac{F_{CY}}{F_{SCL}} - \frac{F_{CY}}{10,000,000} \right) - 1$$

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

## 16.4 Slave Address Masking

The I2CxMSK register (Register 16-3) designates address bit positions as “don’t care” for both 7-Bit and 10-Bit Addressing modes. Setting a particular bit location (= 1) in the I2CxMSK register causes the slave module to respond whether the corresponding address bit value is a ‘0’ or a ‘1’. For example, when I2CxMSK is set to ‘00100000’, the slave module will detect both addresses, ‘00000000’ and ‘00100000’.

To enable address masking, the IPMI (Intelligent Peripheral Management Interface) must be disabled by clearing the IPMIEN bit (I2CxCON<11>).

**Note:** As a result of changes in the I<sup>2</sup>C™ protocol, the addresses in Table 16-2 are reserved and will not be Acknowledged in Slave mode. This includes any address mask settings that include any of these addresses.

**TABLE 16-1: I<sup>2</sup>C™ CLOCK RATES<sup>(1)</sup>**

Required System F <sub>SCL</sub>	F <sub>CY</sub>	I2CxBRG Value		Actual F <sub>SCL</sub>
		(Decimal)	(Hexadecimal)	
100 kHz	16 MHz	157	9D	100 kHz
100 kHz	8 MHz	78	4E	100 kHz
100 kHz	4 MHz	39	27	99 kHz
400 kHz	16 MHz	37	25	404 kHz
400 kHz	8 MHz	18	12	404 kHz
400 kHz	4 MHz	9	9	385 kHz
400 kHz	2 MHz	4	4	385 kHz
1 MHz	16 MHz	13	D	1.026 MHz
1 MHz	8 MHz	6	6	1.026 MHz
1 MHz	4 MHz	3	3	0.909 MHz

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

**TABLE 16-2: I<sup>2</sup>C™ RESERVED ADDRESSES<sup>(1)</sup>**

Slave Address	R/W Bit	Description
0000 000	0	General Call Address <sup>(2)</sup>
0000 000	1	Start Byte
0000 001	x	Cbus Address
0000 010	x	Reserved
0000 011	x	Reserved
0000 1xx	x	HS Mode Master Code
1111 1xx	x	Reserved
1111 0xx	x	10-Bit Slave Upper Byte <sup>(3)</sup>

**Note 1:** The address bits listed here will never cause an address match, independent of the address mask settings.

**2:** The address will be Acknowledged only if GCEN = 1.

**3:** A match on this address can only occur on the upper byte in 10-Bit Addressing mode.

# PIC24FJ64GA004 FAMILY

## REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL <sup>(1)</sup>	IPMIEN	A10M	DISSLW	SMEN
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC
GCEN	STREN <sup>(1)</sup>	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15     **I2CEN:** I2Cx Enable bit  
1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins  
0 = Disables the I2Cx module; all I<sup>2</sup>C™ pins are controlled by port functions
- bit 14     **Unimplemented:** Read as '0'
- bit 13     **I2CSIDL:** I2Cx Stop in Idle Mode bit  
1 = Discontinues module operation when device enters an Idle mode  
0 = Continues module operation in Idle mode
- bit 12     **SCLREL:** SCLx Release Control bit (when operating as I<sup>2</sup>C Slave)<sup>(1)</sup>  
1 = Releases SCLx clock  
0 = Holds SCLx clock low (clock stretch)  
If STREN = 1:  
Bit is R/W (i.e., software may write '0' to initiate stretch and write '1' to release clock). Hardware is clear at the beginning of slave transmission. Hardware is clear at the end of slave reception.  
If STREN = 0:  
Bit is R/S (i.e., software may only write '1' to release clock). Hardware is clear at the beginning of slave transmission.
- bit 11     **IPMIEN:** Intelligent Peripheral Management Interface (IPMI) Enable bit  
1 = IPMI Support mode is enabled; all addresses are Acknowledged  
0 = IPMI mode is disabled
- bit 10     **A10M:** 10-Bit Slave Addressing bit  
1 = I2CxADD is a 10-bit slave address  
0 = I2CxADD is a 7-bit slave address
- bit 9     **DISSLW:** Disable Slew Rate Control bit  
1 = Slew rate control is disabled  
0 = Slew rate control is enabled
- bit 8     **SMEN:** SMBus Input Levels bit  
1 = Enables I/O pin thresholds compliant with the SMBus specification  
0 = Disables the SMBus input thresholds
- bit 7     **GCEN:** General Call Enable bit (when operating as I<sup>2</sup>C slave)  
1 = Enables interrupt when a general call address is received in the I2CxRSR (module is enabled for reception)  
0 = General call address is disabled
- bit 6     **STREN:** SCLx Clock Stretch Enable bit (when operating as I<sup>2</sup>C slave)<sup>(1)</sup>  
Used in conjunction with the SCLREL bit.  
1 = Enables software or receive clock stretching  
0 = Disables software or receive clock stretching

**Note 1:** In Slave mode, the module will not automatically clock stretch after receiving the address byte.

# PIC24FJ64GA004 FAMILY

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## REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)

- bit 5      **ACKDT:** Acknowledge Data bit (when operating as I<sup>2</sup>C master, applicable during master receive)  
Value that will be transmitted when the software initiates an Acknowledge sequence.  
1 = Sends a NACK during Acknowledge  
0 = Sends an ACK during Acknowledge
- bit 4      **ACKEN:** Acknowledge Sequence Enable bit (when operating as I<sup>2</sup>C master, applicable during master receive)  
1 = Initiates Acknowledge sequence on SDAx and SCLx pins and transmits the ACKDT data bit.  
Hardware is clear at the end of master Acknowledge sequence.  
0 = Acknowledge sequence is not in progress
- bit 3      **RCEN:** Receive Enable bit (when operating as I<sup>2</sup>C master)  
1 = Enables Receive mode for I<sup>2</sup>C. Hardware is clear at the end of eighth bit of master receive data byte.  
0 = Receive sequence is not in progress
- bit 2      **PEN:** Stop Condition Enable bit (when operating as I<sup>2</sup>C master)  
1 = Initiates Stop condition on SDAx and SCLx pins. Hardware is clear at the end of master Stop sequence.  
0 = Stop condition is not in progress
- bit 1      **RSEN:** Repeated Start Condition Enable bit (when operating as I<sup>2</sup>C master)  
1 = Initiates Repeated Start condition on SDAx and SCLx pins. Hardware is clear at the end of master Repeated Start sequence.  
0 = Repeated Start condition is not in progress
- bit 0      **SEN:** Start Condition Enable bit (when operating as I<sup>2</sup>C master)  
1 = Initiates Start condition on SDAx and SCLx pins. Hardware is clear at the end of master Start sequence.  
0 = Start condition is not in progress

**Note 1:** In Slave mode, the module will not automatically clock stretch after receiving the address byte.

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## REGISTER 16-2: I2CxSTAT: I2Cx STATUS REGISTER

R-0, HSC	R-0, HSC	U-0	U-0	U-0	R/C-0, HS	R-0, HSC	R-0, HSC
ACKSTAT <sup>(1)</sup>	TRSTAT	—	—	—	BCL	GCSTAT	ADD10
bit 15						bit 8	

R/C-0, HS	R/C-0, HS	R-0, HSC	R/C-0, HSC	R/C-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IWCOL	I2COV	D/A	P	S	R/W	RBF	TBF
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit	HS = Hardware Settable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown
HSC = Hardware Settable/Clearable bit		

- bit 15 **ACKSTAT:** Acknowledge Status bit<sup>(1)</sup>  
 1 = NACK was detected last  
 0 = ACK was detected last  
 Hardware is set or clear at the end of Acknowledge.
- bit 14 **TRSTAT:** Transmit Status bit (when operating as I<sup>2</sup>C™ master, applicable to master transmit operation)  
 1 = Master transmit is in progress (8 bits + ACK)  
 0 = Master transmit is not in progress  
 Hardware is set at the beginning of master transmission. Hardware is clear at the end of slave Acknowledge.
- bit 13-11 **Unimplemented:** Read as '0'
- bit 10 **BCL:** Master Bus Collision Detect bit  
 1 = A bus collision has been detected during a master operation  
 0 = No collision  
 Hardware is set at the detection of bus collision.
- bit 9 **GCSTAT:** General Call Status bit  
 1 = General call address was received  
 0 = General call address was not received  
 Hardware is set when an address matches the general call address. Hardware is clear at Stop detection.
- bit 8 **ADD10:** 10-Bit Address Status bit  
 1 = 10-bit address was matched  
 0 = 10-bit address was not matched  
 Hardware is set at the match of the 2nd byte of matched 10-bit address. Hardware is clear at Stop detection.
- bit 7 **IWCOL:** I2Cx Write Collision Detect bit  
 1 = An attempt to write to the I2CxTRN register failed because the I<sup>2</sup>C module is busy  
 0 = No collision  
 Hardware is set at the occurrence of a write to I2CxTRN while busy (cleared by software).
- bit 6 **I2COV:** I2Cx Receive Overflow Flag bit  
 1 = A byte was received while the I2CxRCV register is still holding the previous byte  
 0 = No overflow  
 Hardware is set at an attempt to transfer I2CxRSR to I2CxRCV (cleared by software).

**Note 1:** In both Master and Slave modes, the ACKSTAT bit is only updated when transmitting data resulting in the reception of an ACK or NACK from another device. Do not check the state of ACKSTAT when receiving data, either as a slave or a master. Reading ACKSTAT after receiving address or data bytes returns an invalid result.

# PIC24FJ64GA004 FAMILY

## REGISTER 16-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

bit 5	<b>D/A:</b> Data/Address bit (when operating as I <sup>2</sup> C slave) 1 = Indicates that the last byte received was data 0 = Indicates that the last byte received was a device address Hardware is clear at a device address match. Hardware is set by a write to I2CxTRN or by reception of a slave byte.
bit 4	<b>P:</b> Stop bit 1 = Indicates that a Stop bit has been detected last 0 = Stop bit was not detected last Hardware is set or clear when Start, Repeated Start or Stop is detected.
bit 3	<b>S:</b> Start bit 1 = Indicates that a Start (or Repeated Start) bit has been detected last 0 = Start bit was not detected last Hardware is set or clear when Start, Repeated Start or Stop is detected.
bit 2	<b>R/W:</b> Read/Write Information bit (when operating as I <sup>2</sup> C slave) 1 = Read – Indicates data transfer is output from slave 0 = Write – Indicates data transfer is input to slave Hardware is set or clear after reception of an I <sup>2</sup> C device address byte.
bit 1	<b>RBF:</b> Receive Buffer Full Status bit 1 = Receive is complete, I2CxRCV is full 0 = Receive is not complete, I2CxRCV is empty Hardware is set when I2CxRCV is written with received byte. Hardware is clear when software reads I2CxRCV.
bit 0	<b>TBF:</b> Transmit Buffer Full Status bit 1 = Transmit is in progress, I2CxTRN is full 0 = Transmit is complete, I2CxTRN is empty Hardware is set when software writes I2CxTRN. Hardware is clear at completion of data transmission.

**Note 1:** In both Master and Slave modes, the ACKSTAT bit is only updated when transmitting data resulting in the reception of an ACK or NACK from another device. Do not check the state of ACKSTAT when receiving data, either as a slave or a master. Reading ACKSTAT after receiving address or data bytes returns an invalid result.

## REGISTER 16-3: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	AMSK9	AMSK8
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AMSK7	AMSK6	AMSK5	AMSK4	AMSK3	AMSK2	AMSK1	AMSK0
bit 7						bit 0	

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

bit 15-10 **Unimplemented:** Read as '0'

bit 9-0 **AMSK<9:0>:** Mask for Address Bit x Select bits

- 1 = Enables masking for bit x of incoming message address; bit match is not required in this position
- 0 = Disables masking for bit x; bit match is required in this position

# PIC24FJ64GA004 FAMILY

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NOTES:

## 17.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “UART” (DS39708).

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the PIC24F device family. The UART is a full-duplex, asynchronous system that can communicate with peripheral devices, such as personal computers, LIN/J2602, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins, and also includes an IrDA® encoder and decoder.

The primary features of the UART module are:

- Full-Duplex, 8 or 9-Bit Data Transmission through the UxTX and UxRX Pins
- Even, Odd or No Parity Options (for 8-bit data)
- One or Two Stop bits
- Hardware Flow Control Option with  $\overline{\text{UxCTS}}$  and UxRTS Pins
- Fully Integrated Baud Rate Generator with 16-Bit Prescaler

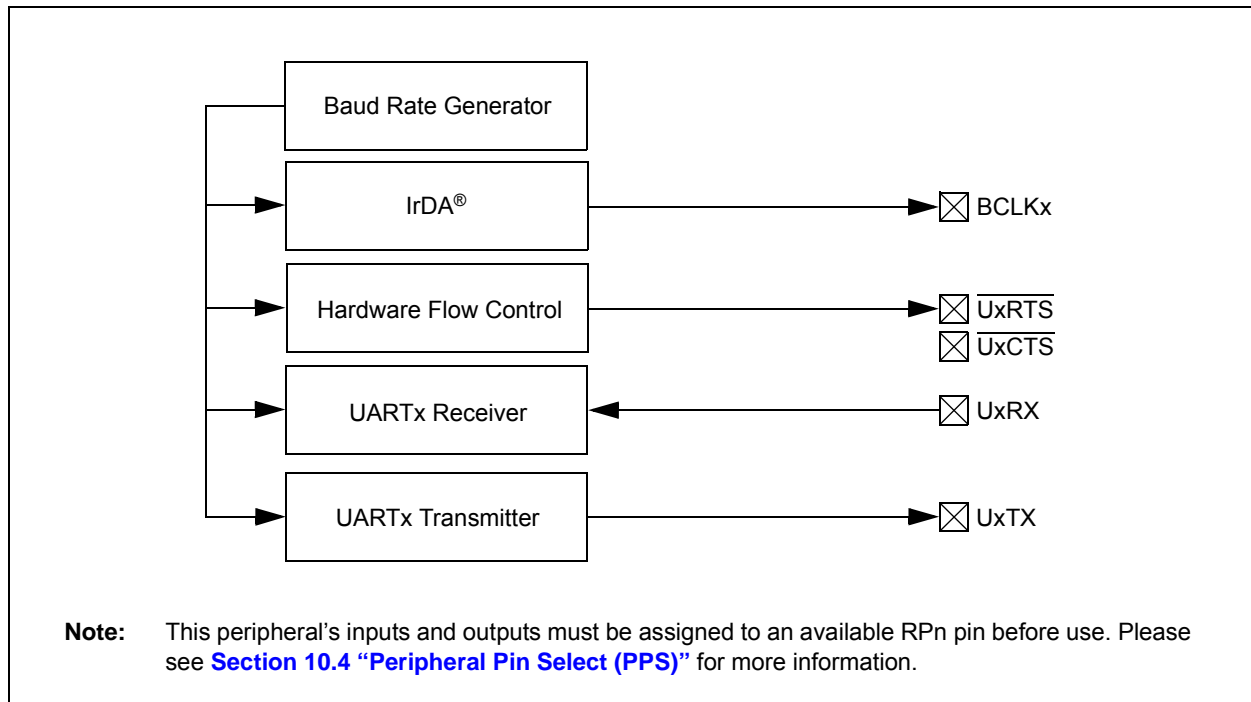
- Baud Rates Ranging from 1 Mbps to 15 bps at 16 MIPS
- 4-Deep, First-In-First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- Transmit and Receive Interrupts
- Loopback mode for Diagnostic Support
- Support for Sync and Break Characters
- Supports Automatic Baud Rate Detection
- IrDA Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA Support

A simplified block diagram of the UART is shown in Figure 17-1. The UART module consists of these key important hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

**Note:** In this section, the UART modules are referred to together as UARTx or separately as UART1 and UART2.

**FIGURE 17-1: UARTx SIMPLIFIED BLOCK DIAGRAM**



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## 17.1 UARTx Baud Rate Generator (BRG)

The UARTx module includes a dedicated 16-bit Baud Rate Generator. The UxBRG register controls the period of a free-running, 16-bit timer. Equation 17-1 shows the formula for computation of the baud rate with BRGH = 0.

### EQUATION 17-1: UARTx BAUD RATE WITH BRGH = 0<sup>(1)</sup>

$$\text{Baud Rate} = \frac{\text{FCY}}{16 \cdot (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{\text{FCY}}{16 \cdot \text{Baud Rate}} - 1$$

**Note 1:** Based on FCY = FOSC/2; Doze mode and PLL are disabled.

Example 17-1 shows the calculation of the baud rate error for the following conditions:

- FCY = 4 MHz
- Desired Baud Rate = 9600

The maximum baud rate (BRGH = 0) possible is FCY/16 (for UxBRG = 0) and the minimum baud rate possible is FCY/(16 \* 65536).

Equation 17-2 shows the formula for computation of the baud rate with BRGH = 1.

### EQUATION 17-2: UARTx BAUD RATE WITH BRGH = 1<sup>(1)</sup>

$$\text{Baud Rate} = \frac{\text{FCY}}{4 \cdot (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{\text{FCY}}{4 \cdot \text{Baud Rate}} - 1$$

**Note 1:** Based on FCY = FOSC/2; Doze mode and PLL are disabled.

The maximum baud rate (BRGH = 1) possible is FCY/4 (for UxBRG = 0) and the minimum baud rate possible is FCY/(4 \* 65536).

Writing a new value to the UxBRG register causes the BRG timer to be reset (cleared). This ensures the BRG does not wait for a timer overflow before generating the new baud rate.

### EXAMPLE 17-1: BAUD RATE ERROR CALCULATION (BRGH = 0)<sup>(1)</sup>

$$\text{Desired Baud Rate} = \text{FCY}/(16 (\text{UxBRG} + 1))$$

Solving for UxBRG value:

$$\text{UxBRG} = ((\text{FCY}/\text{Desired Baud Rate})/16) - 1$$

$$\text{UxBRG} = ((4000000/9600)/16) - 1$$

$$\text{UxBRG} = 25$$

$$\begin{aligned}\text{Calculated Baud Rate} &= 4000000/(16 (25 + 1)) \\ &= 9615\end{aligned}$$

$$\begin{aligned}\text{Error} &= (\text{Calculated Baud Rate} - \text{Desired Baud Rate}) / \text{Desired Baud Rate} \\ &= (9615 - 9600)/9600 \\ &= 0.16\%\end{aligned}$$

**Note 1:** Based on FCY = FOSC/2; Doze mode and PLL are disabled.



## 17.2 Transmitting in 8-Bit Data Mode

1. Set up the UARTx:
  - a) Write appropriate values for data, parity and Stop bits.
  - b) Write appropriate baud rate value to the UxBRG register.
  - c) Set up transmit and receive interrupt enable and priority bits.
2. Enable the UARTx.
3. Set the UTXEN bit (causes a transmit interrupt 2 cycles after being set).
4. Write data byte to lower byte of UxTXREG word. The value will be immediately transferred to the Transmit Shift Register (TSR) and the serial bit stream will start shifting out with the next rising edge of the baud clock.
5. Alternately, the data byte may be transferred while UTXEN = 0 and then the user may set UTXEN. This will cause the serial bit stream to begin immediately because the baud clock will start from a cleared state.
6. A transmit interrupt will be generated as per interrupt control bits, UTXISEL<1:0>.

## 17.3 Transmitting in 9-Bit Data Mode

1. Set up the UARTx (as described in [Section 17.2 “Transmitting in 8-Bit Data Mode”](#)).
2. Enable the UARTx.
3. Set the UTXEN bit (causes a transmit interrupt 2 cycles after being set).
4. Write UxTXREG as a 16-bit value only.
5. A word write to UxTXREG triggers the transfer of the 9-bit data to the TSR. The serial bit stream will start shifting out with the first rising edge of the baud clock.
6. A transmit interrupt will be generated as per the setting of control bits, UTXISEL<1:0>.

## 17.4 Break and Sync Transmit Sequence

The following sequence will send a message frame header made up of a Break, followed by an auto-baud Sync byte.

1. Configure the UARTx for the desired mode.
2. Set UTXEN and UTXBRK – sets up the Break character.
3. Load the UxTXREG with a dummy character to initiate transmission (value is ignored).
4. Write '55h' to UxTXREG – loads the Sync character into the transmit FIFO.
5. After the Break has been sent, the UTXBRK bit is reset by hardware. The Sync character now transmits.

## 17.5 Receiving in 8-Bit or 9-Bit Data Mode

1. Set up the UARTx (as described in [Section 17.2 “Transmitting in 8-Bit Data Mode”](#)).
2. Enable the UARTx.
3. A receive interrupt will be generated when one or more data characters have been received as per interrupt control bits, URXISEL<1:0>.
4. Read the OERR bit to determine if an overrun error has occurred. The OERR bit must be reset in software.
5. Read UxRXREG.

The act of reading the UxRXREG character will move the next character to the top of the receive FIFO, including a new set of PERR and FERR values.

## 17.6 Operation of $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ Control Pins

UARTx Clear-to-Send ( $\overline{\text{UxCTS}}$ ) and Request-to-Send ( $\overline{\text{UxRTS}}$ ) are the two hardware-controlled pins that are associated with the UARTx module. These two pins allow the UARTx to operate in Simplex and Flow Control mode. They are implemented to control the transmission and reception between the Data Terminal Equipment (DTE). The UEN<1:0> bits in the UxMODE register configure these pins.

## 17.7 Infrared Support

The UARTx module provides two types of infrared UART support: one is the IrDA clock output to support external IrDA encoder and decoder device (legacy module support), and the other is the full implementation of the IrDA encoder and decoder. Note that because the IrDA modes require a 16x baud clock, they will only work when the BRGH bit (UxMODE<3>) is '0'.

### 17.7.1 EXTERNAL IrDA SUPPORT – IrDA CLOCK OUTPUT

To support external IrDA encoder and decoder devices, the BCLKx pin (same as the UxRTS pin) can be configured to generate the 16x baud clock. With UEN<1:0> = 11, the BCLKx pin will output the 16x baud clock if the UARTx module is enabled. It can be used to support the IrDA codec chip.

### 17.7.2 BUILT-IN IrDA ENCODER AND DECODER

The UARTx has full implementation of the IrDA encoder and decoder as part of the UARTx module. The built-in IrDA encoder and decoder functionality is enabled using the IREN bit (UxMODE<12>). When enabled (IREN = 1), the receive pin (UxRX) acts as the input from the infrared receiver. The transmit pin (UxTX) acts as the output to the infrared transmitter.

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## REGISTER 17-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0 <sup>(3)</sup>	R/W-0 <sup>(3)</sup>
UARTEN <sup>(1)</sup>	—	USIDL	IREN <sup>(2)</sup>	RTSMD	—	UEN1	UEN0
bit 15						bit 8	

R/C-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7						bit 0	

<b>Legend:</b>	C = Clearable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **UARTEN:** UARTx Enable bit<sup>(1)</sup>  
 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>  
 0 = UARTx is disabled; all UARTx pins are controlled by PORT latches; UARTx power consumption is minimal
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **USIDL:** UARTx Stop in Idle Mode bit  
 1 = Discontinues module operation when device enters Idle mode  
 0 = Continues module operation in Idle mode
- bit 12 **IREN:** IrDA<sup>®</sup> Encoder and Decoder Enable bit<sup>(2)</sup>  
 1 = IrDA encoder and decoder are enabled  
 0 = IrDA encoder and decoder are disabled
- bit 11 **RTSMD:** Mode Selection for  $\overline{\text{UxRTS}}$  Pin bit  
 1 =  $\overline{\text{UxRTS}}$  pin in Simplex mode  
 0 =  $\overline{\text{UxRTS}}$  pin in Flow Control mode
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **UEN<1:0>:** UARTx Enable bits<sup>(3)</sup>  
 11 = UxTX, UxRX and BCLKx pins are enabled and used;  $\overline{\text{UxCTS}}$  pin is controlled by PORT latches  
 10 = UxTX, UxRX,  $\overline{\text{UxCTS}}$  and  $\overline{\text{UxRTS}}$  pins are enabled and used  
 01 = UxTX, UxRX and  $\overline{\text{UxRTS}}$  pins are enabled and used;  $\overline{\text{UxCTS}}$  pin is controlled by PORT latches  
 00 = UxTX and UxRX pins are enabled and used;  $\overline{\text{UxCTS}}$  and  $\overline{\text{UxRTS}}$ /BCLKx pins are controlled by PORT latches
- bit 7 **WAKE:** Wake-up on Start Bit Detect During Sleep Mode Enable bit  
 1 = UARTx will continue to sample the UxRX pin; interrupt is generated on falling edge, bit is cleared in hardware on following rising edge  
 0 = No wake-up is enabled
- bit 6 **LPBACK:** UARTx Loopback Mode Select bit  
 1 = Enables Loopback mode  
 0 = Loopback mode is disabled
- bit 5 **ABAUD:** Auto-Baud Enable bit  
 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion  
 0 = Baud rate measurement is disabled or completed

**Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

**2:** This feature is only available for the 16x BRG mode (BRGH = 0).

**3:** Bit availability depends on pin availability.

## REGISTER 17-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 4	<b>RXINV:</b> Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	<b>BRGH:</b> High Baud Rate Enable bit 1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode) 0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)
bit 2-1	<b>PDSEL&lt;1:0&gt;:</b> Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	<b>STSEL:</b> Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).
- 3:** Bit availability depends on pin availability.

# PIC24FJ64GA004 FAMILY

## REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN <sup>(1)</sup>	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 15,13 **UTXISEL<1:0>:** UARTx Transmission Interrupt Mode Selection bits  
 11 = Reserved; do not use  
 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR) and as a result, the transmit buffer becomes empty  
 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed  
 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 **UTXINV:** IrDA® Encoder Transmit Polarity Inversion bit  
If IREN = 0:  
 1 = UxTX Idle state is '0'  
 0 = UxTX Idle state is '1'  
If IREN = 1:  
 1 = UxTX Idle state is '1'  
 0 = UxTX Idle state is '0'
- bit 12 **Unimplemented:** Read as '0'
- bit 11 **UTXBRK:** UARTx Transmit Break bit  
 1 = Sends Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion  
 0 = Sync Break transmission is disabled or completed
- bit 10 **UTXEN:** UARTx Transmit Enable bit<sup>(1)</sup>  
 1 = Transmit is enabled, UxTX pin is controlled by UARTx  
 0 = Transmit is disabled, any pending transmission is aborted and buffer is reset; UxTX pin is controlled by the PORT register
- bit 9 **UTXBF:** UARTx Transmit Buffer Full Status bit (read-only)  
 1 = Transmit buffer is full  
 0 = Transmit buffer is not full, at least one more character can be written
- bit 8 **TRMT:** Transmit Shift Register Empty bit (read-only)  
 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)  
 0 = Transmit Shift Register is not empty, a transmission is in progress or queued
- bit 7-6 **URXISEL<1:0>:** UARTx Receive Interrupt Mode Selection bits  
 11 = Interrupt is set on RSR transfer, making the receive buffer full (i.e., has 4 data characters)  
 10 = Interrupt is set on RSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)  
 0x = Interrupt is set when any character is received and transferred from the RSR to the receive buffer; receive buffer has one or more characters

**Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

## REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)

bit 5	<b>ADDEN:</b> Address Character Detect bit (bit 8 of received data = 1) 1 = Address Detect mode is enabled; if 9-bit mode is not selected, this does not take effect 0 = Address Detect mode is disabled
bit 4	<b>RIDLE:</b> Receiver Idle bit (read-only) 1 = Receiver is Idle 0 = Receiver is active
bit 3	<b>PERR:</b> Parity Error Status bit (read-only) 1 = Parity error has been detected for the current character (character at the top of the receive FIFO) 0 = Parity error has not been detected
bit 2	<b>FERR:</b> Framing Error Status bit (read-only) 1 = Framing error has been detected for the current character (character at the top of the receive FIFO) 0 = Framing error has not been detected
bit 1	<b>OERR:</b> Receive Buffer Overrun Error Status bit (clear/read-only) 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed (clearing a previously set OERR bit (1 → 0 transition) will reset the receiver buffer and the RSR to the empty state)
bit 0	<b>URXDA:</b> UARTx Receive Buffer Data Available bit (read-only) 1 = Receive buffer has data; at least one more character can be read 0 = Receive buffer is empty

**Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

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## REGISTER 17-3: UxTXREG: UARTx TRANSMIT REGISTER

U-x	U-x	U-x	U-x	U-x	U-x	U-x	W-x
—	—	—	—	—	—	—	UTX8
bit 15							bit 8

W-x	W-x	W-x	W-x	W-x	W-x	W-x	W-x
UTX7	UTX6	UTX5	UTX4	UTX3	UTX2	UTX1	UTX0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8 **UTX8:** UARTx Data of the Transmitted Character bit (in 9-bit mode)

bit 7-0 **UTX<7:0>:** UARTx Data of the Transmitted Character bits

## REGISTER 17-4: UxRXREG: UARTx RECEIVE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R-0
—	—	—	—	—	—	—	URX8
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
URX7	URX6	URX5	URX4	URX3	URX2	URX1	URX0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8 **URX8:** UARTx Data of the Received Character bit (in 9-bit mode)

bit 7-0 **URX<7:0>:** UARTx Data of the Received Character bits

## 18.0 PARALLEL MASTER PORT (PMP)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Parallel Master Port (PMP)” (DS39713).

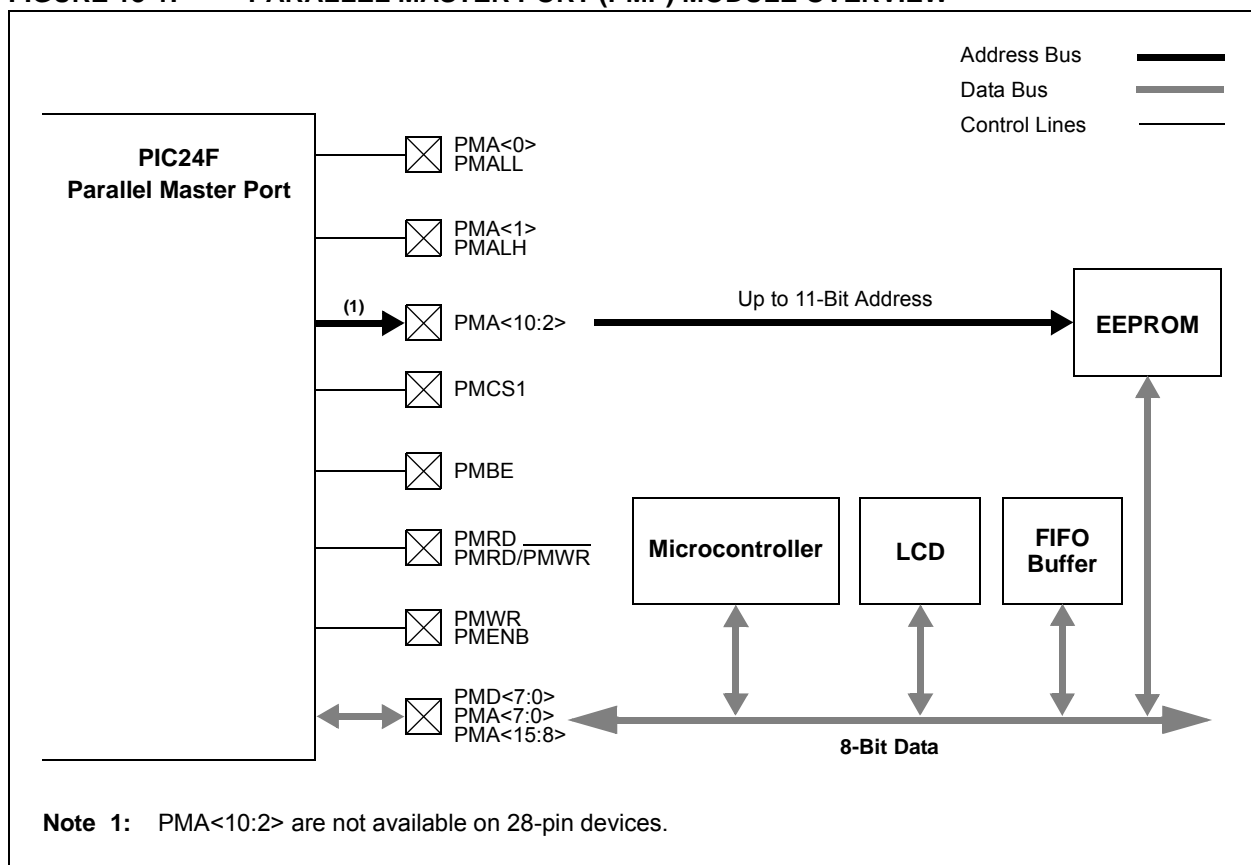
The Parallel Master Port (PMP) module is a parallel 8-bit I/O module, specifically designed to communicate with a wide variety of parallel devices, such as communication peripherals, LCDs, external memory devices and microcontrollers. Because the interface to parallel peripherals varies significantly, the PMP is highly configurable.

**Note:** A number of the pins for the PMP are not present on PIC24FJ64GA004 devices. Refer to the specific device's pinout to determine which pins are available.

Key features of the PMP module include:

- Up to 16 Programmable Address Lines
- One Chip Select Line
- Programmable Strobe Options:
  - Individual Read and Write Strobes or;
  - Read/Write Strobe with Enable Strobe
- Address Auto-Increment/Auto-Decrement
- Programmable Address/Data Multiplexing
- Programmable Polarity on Control Signals
- Legacy Parallel Slave Port Support
- Enhanced Parallel Slave Support:
  - Address Support
  - 4-Byte Deep Auto-Incrementing Buffer
- Programmable Wait States
- Selectable Input Voltage Levels

**FIGURE 18-1: PARALLEL MASTER PORT (PMP) MODULE OVERVIEW**



# PIC24FJ64GA004 FAMILY

## REGISTER 18-1: PMCON: PARALLEL PORT CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PMPEN	—	PSIDL	ADMUX1 <sup>(1)</sup>	ADMUX0 <sup>(1)</sup>	PTBEEN	PTWREN	PTRDEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0 <sup>(2)</sup>	U-0	R/W-0 <sup>(2)</sup>	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP	—	CS1P	BEP	WRSP	RDSP
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15      **PMPEN:** PMP Enable bit  
             1 = PMP is enabled  
             0 = PMP is disabled, no off-chip access is performed
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **PSIDL:** PMP Stop in Idle Mode bit  
             1 = Discontinues module operation when device enters Idle mode  
             0 = Continues module operation in Idle mode
- bit 12-11   **ADMUX<1:0>:** Address/Data Multiplexing Selection bits<sup>(1)</sup>  
             11 = Reserved  
             10 = All 16 bits of address are multiplexed on the PMD<7:0> pins  
             01 = Lower 8 bits of address are multiplexed on the PMD<7:0> pins, upper 3 bits are multiplexed on PMA<10:8>  
             00 = Address and data appear on separate pins
- bit 10      **PTBEEN:** PMP Byte Enable Port Enable bit (16-Bit Master mode)  
             1 = PMBE port is enabled  
             0 = PMBE port is disabled
- bit 9       **PTWREN:** PMP Write Enable Strobe Port Enable bit  
             1 = PMWR/PMENB port is enabled  
             0 = PMWR/PMENB port is disabled
- bit 8       **PTRDEN:** PMP Read/Write Strobe Port Enable bit  
             1 = PMRD/PMWR port is enabled  
             0 = PMRD/PMWR port is disabled
- bit 7-6     **CSF<1:0>:** Chip Select Function bits  
             11 = Reserved  
             10 = PMCS1 functions as chip set  
             01 = Reserved  
             00 = Reserved
- bit 5       **ALP:** Address Latch Polarity bit<sup>(2)</sup>  
             1 = Active-high (PMALL and PMALH)  
             0 = Active-low (PMALL and PMALH)
- bit 4       **Unimplemented:** Read as '0'
- bit 3       **CS1P:** Chip Select 1 Polarity bit<sup>(2)</sup>  
             1 = Active-high (PMCS1/PMCS1)  
             0 = Active-low (PMCS1/PMCS1)

**Note 1:** PMA<10:2> bits are not available on 28-pin devices.

**2:** These bits have no effect when their corresponding pins are used as address lines.



# PIC24FJ64GA004 FAMILY

---

## REGISTER 18-1: PMCON: PARALLEL PORT CONTROL REGISTER (CONTINUED)

- bit 2      **BEP:** Byte Enable Polarity bit  
1 = Byte enable is active-high (PMBE)  
0 = Byte enable is active-low (PMBE)
- bit 1      **WRSP:** Write Strobe Polarity bit  
For Slave Modes and Master Mode 2 (PMMODE<9:8> = 00, 01, 10):  
1 = Write strobe is active-high (PMWR)  
0 = Write strobe is active-low (PMWR)  
For Master Mode 1 (PMMODE<9:8> = 11):  
1 = Enable strobe is active-high (PMENB)  
0 = Enable strobe is active-low (PMENB)
- bit 0      **RDSP:** Read Strobe Polarity bit  
For Slave Modes and Master Mode 2 (PMMODE<9:8> = 00, 01, 10):  
1 = Read strobe is active-high (PMRD)  
0 = Read strobe is active-low (PMRD)  
For Master Mode 1 (PMMODE<9:8> = 11):  
1 = Read/write strobe is active-high (PMRD/PMWR)  
0 = Read/write strobe is active-low (PMRD/PMWR)

**Note 1:** PMA<10:2> bits are not available on 28-pin devices.

**2:** These bits have no effect when their corresponding pins are used as address lines.

# PIC24FJ64GA004 FAMILY

## REGISTER 18-2: PMMODE: PARALLEL PORT MODE REGISTER

R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUSY	IRQM1	IRQM0	INCM1	INCM0	MODE16	MODE1	MODE0
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAITB1 <sup>(1)</sup>	WAITB0 <sup>(1)</sup>	WAITM3	WAITM2	WAITM1	WAITM0	WAITE1 <sup>(1)</sup>	WAITE0 <sup>(1)</sup>
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **BUSY:** Busy bit (Master mode only)  
 1 = Port is busy (not useful when the processor stall is active)  
 0 = Port is not busy
- bit 14-13 **IRQM<1:0>:** Interrupt Request Mode bits  
 11 = Interrupt is generated when Read Buffer 3 is read or Write Buffer 3 is written (Buffered PSP mode) or on a read or write operation when PMA<1:0> = 11 (Addressable PSP mode only)  
 10 = No interrupt is generated, processor stall is activated  
 01 = Interrupt is generated at the end of the read/write cycle  
 00 = No interrupt is generated
- bit 12-11 **INCM<1:0>:** Increment Mode bits  
 11 = PSP read and write buffers auto-increment (Legacy PSP mode only)  
 10 = Decrements ADDR<10:0> by 1 every read/write cycle  
 01 = Increments ADDR<10:0> by 1 every read/write cycle  
 00 = No increment or decrement of address
- bit 10 **MODE16:** 8/16-Bit Mode bit  
 1 = 16-Bit Mode: Data register is 16 bits, a read or write to the Data register invokes two 8-bit transfers  
 0 = 8-Bit Mode: Data register is 8 bits, a read or write to the Data register invokes one 8-bit transfer
- bit 9-8 **MODE<1:0>:** Parallel Port Mode Select bits  
 11 = Master Mode 1 (PMCS1, PMRD/PMWR, PMENB, PMBE, PMA<x:0> and PMD<7:0>)  
 10 = Master Mode 2 (PMCS1, PMRD, PMWR, PMBE, PMA<x:0> and PMD<7:0>)  
 01 = Enhanced PSP, control signals (PMRD, PMWR, PMCS1, PMD<7:0> and PMA<1:0>)  
 00 = Legacy Parallel Slave Port, control signals (PMRD, PMWR, PMCS1 and PMD<7:0>)
- bit 7-6 **WAITB<1:0>:** Data Setup to Read/Write Wait State Configuration bits<sup>(1)</sup>  
 11 = Data wait of 4 Tcy; multiplexed address phase of 4 Tcy  
 10 = Data wait of 3 Tcy; multiplexed address phase of 3 Tcy  
 01 = Data wait of 2 Tcy; multiplexed address phase of 2 Tcy  
 00 = Data wait of 1 Tcy; multiplexed address phase of 1 Tcy
- bit 5-2 **WAITM<3:0>:** Read to Byte Enable Strobe Wait State Configuration bits  
 1111 = Wait of additional 15 Tcy  
 ...  
 0001 = Wait of additional 1 Tcy  
 0000 = No additional wait cycles (operation forced into one Tcy)
- bit 1-0 **WAITE<1:0>:** Data Hold After Strobe Wait State Configuration bits<sup>(1)</sup>  
 11 = Wait of 4 Tcy  
 10 = Wait of 3 Tcy  
 01 = Wait of 2 Tcy  
 00 = Wait of 1 Tcy

**Note 1:** WAITBx and WAITE<sub>x</sub> bits are ignored whenever WAITM<3:0> = 0000.

# PIC24FJ64GA004 FAMILY

**REGISTER 18-3: PMADDR: PARALLEL PORT ADDRESS REGISTER**

U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	CS1	—	—	—	ADDR10 <sup>(1)</sup>	ADDR9 <sup>(1)</sup>	ADDR8 <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADDR7 <sup>(1)</sup>	ADDR6 <sup>(1)</sup>	ADDR5 <sup>(1)</sup>	ADDR4 <sup>(1)</sup>	ADDR3 <sup>(1)</sup>	ADDR2 <sup>(1)</sup>	ADDR1 <sup>(1)</sup>	ADDR0 <sup>(1)</sup>
bit 7							bit 0

**Legend:**

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'  
 bit 14      **CS1:** Chip Select 1 bit  
                  1 = Chip Select 1 is active  
                  0 = Chip Select 1 is inactive  
 bit 13-11      **Unimplemented:** Read as '0'  
 bit 10-0      **ADDR<10:0>:** Parallel Port Destination Address bits<sup>(1)</sup>

**Note 1:** PMA<10:2> bits are not available on 28-pin devices.

**REGISTER 18-4: PMAEN: PARALLEL PORT ENABLE REGISTER**

U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	PTEN14	—	—	—	PTEN10 <sup>(1)</sup>	PTEN9 <sup>(1)</sup>	PTEN8 <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTEN7 <sup>(1)</sup>	PTEN6 <sup>(1)</sup>	PTEN5 <sup>(1)</sup>	PTEN4 <sup>(1)</sup>	PTEN3 <sup>(1)</sup>	PTEN2 <sup>(1)</sup>	PTEN1	PTEN0
bit 7							bit 0

**Legend:**

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'  
 bit 14      **PTEN14:** PMCS1 Strobe Enable bit  
                  1 = PMCS1 pin functions as chip select  
                  0 = PMCS1 pin functions as port I/O  
 bit 13-11      **Unimplemented:** Read as '0'  
 bit 10-2      **PTEN<10:2>:** PMP Address Port Enable bits<sup>(1)</sup>  
                  1 = PMA<10:2> function as PMP address lines  
                  0 = PMA<10:2> function as port I/O  
 bit 1-0      **PTEN<1:0>:** PMALH/PMALL Strobe Enable bits  
                  1 = PMA1 and PMA0 function as either PMA<1:0> or PMALH and PMALL  
                  0 = PMA1 and PMA0 pads functions as port I/O

**Note 1:** PMA<10:2> bits are not available on 28-pin devices.

# PIC24FJ64GA004 FAMILY

## REGISTER 18-5: PMSTAT: PARALLEL PORT STATUS REGISTER

R-0	R/W-0, HS	U-0	U-0	R-0	R-0	R-0	R-0
IBF	IBOV	—	—	IB3F	IB2F	IB1F	IB0F
bit 15				bit 8			

R-1	R/W-0, HS	U-0	U-0	R-1	R-1	R-1	R-1
OBE	OBUE	—	—	OB3E	OB2E	OB1E	OB0E
bit 7				bit 0			

<b>Legend:</b>	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **IBF:** Input Buffer Full Status bit  
1 = All writable Input Buffer registers are full  
0 = Some or all of the writable Input Buffer registers are empty
- bit 14      **IBOV:** Input Buffer Overflow Status bit  
1 = A write attempt to a full Input Byte register occurred (must be cleared in software)  
0 = No overflow occurred
- bit 13-12      **Unimplemented:** Read as '0'
- bit 11-8      **IB3F:IB0F:** Input Buffer x Status Full bits  
1 = Input Buffer x contains data that has not been read (reading buffer will clear this bit)  
0 = Input Buffer x does not contain any unread data
- bit 7      **OBE:** Output Buffer Empty Status bit  
1 = All readable Output Buffer registers are empty  
0 = Some or all of the readable Output Buffer registers are full
- bit 6      **OBUE:** Output Buffer Underflow Status bit  
1 = A read occurred from an empty Output Byte register (must be cleared in software)  
0 = No underflow occurred
- bit 5-4      **Unimplemented:** Read as '0'
- bit 3-0      **OB3E:OB0E:** Output Buffer x Status Empty bits  
1 = Output Buffer x is empty (writing data to the buffer will clear this bit)  
0 = Output Buffer x contains data that has not been transmitted

# PIC24FJ64GA004 FAMILY

**REGISTER 18-6: PADCFG1: PAD CONFIGURATION CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL <sup>(1)</sup>	PMPTTL
bit 7							bit 0

**Legend:**

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-2      **Unimplemented:** Read as '0'
- bit 1      **RTSECSEL:** RTCC Seconds Clock Output Select bit<sup>(1)</sup>  
             1 = RTCC seconds clock is selected for the RTCC pin  
             0 = RTCC alarm pulse is selected for the RTCC pin
- bit 0      **PMPTTL:** PMP Module TTL Input Buffer Select bit  
             1 = PMP module uses TTL input buffers  
             0 = PMP module uses Schmitt Trigger input buffers

**Note 1:** To enable the actual RTCC output, the RTCOE (RCFGCAL) bit needs to be set.

# PIC24FJ64GA004 FAMILY

FIGURE 18-2: LEGACY PARALLEL SLAVE PORT EXAMPLE

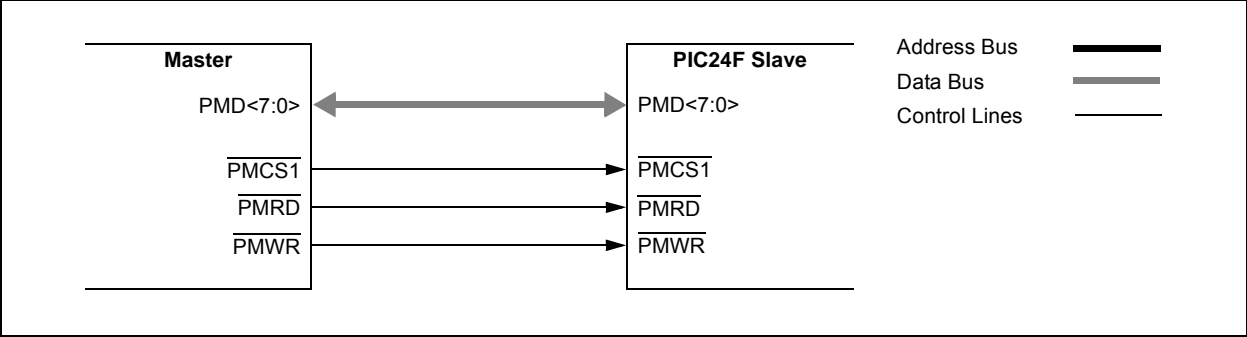


FIGURE 18-3: ADDRESSABLE PARALLEL SLAVE PORT EXAMPLE

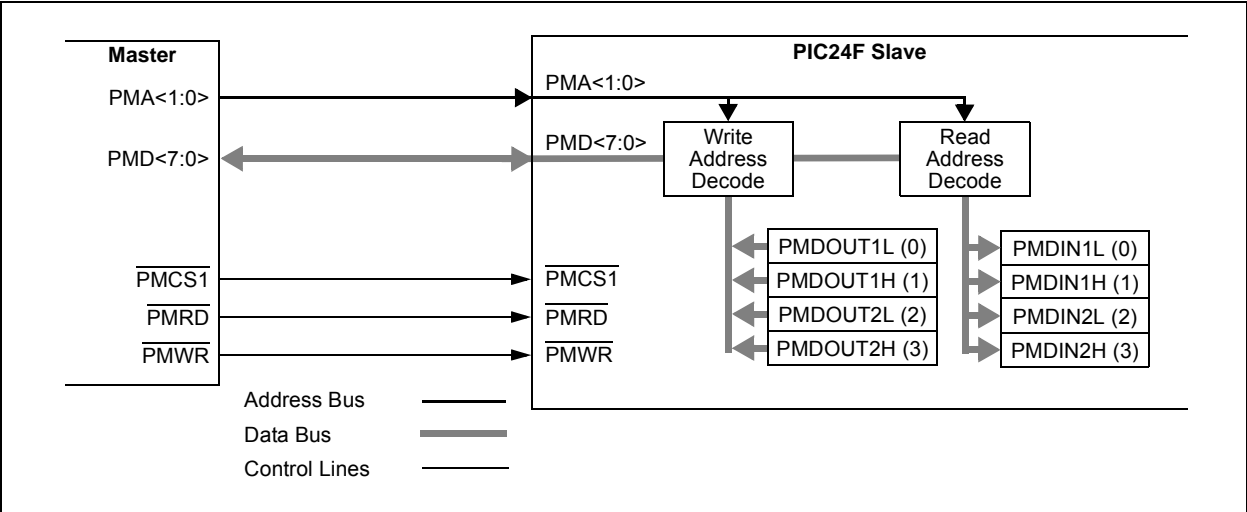
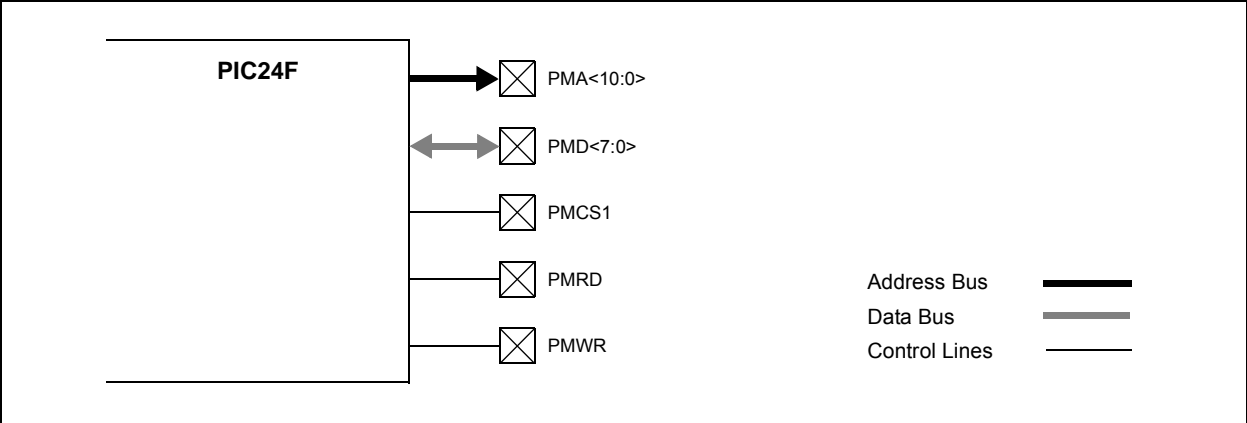


TABLE 18-1: SLAVE MODE ADDRESS RESOLUTION

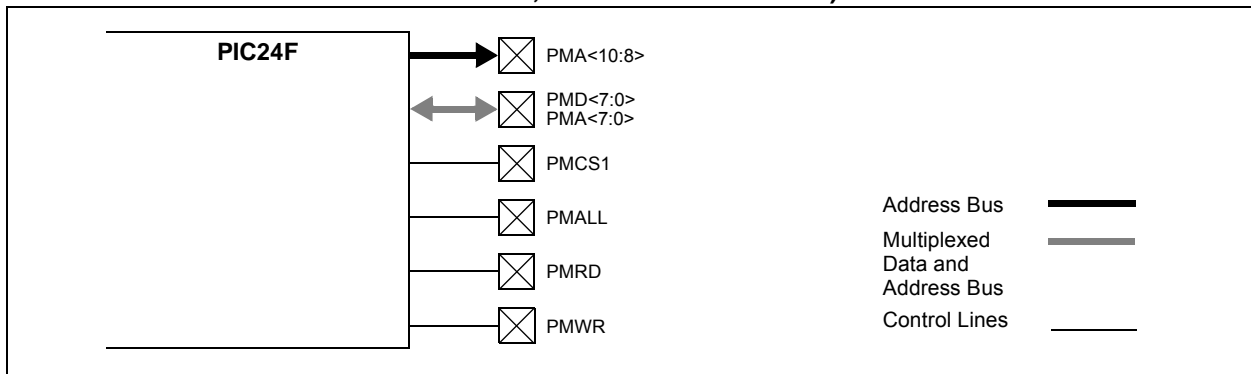
PMA<1:0>	Output Register (Buffer)	Input Register (Buffer)
00	PMDOUT1<7:0> (0)	PMDIN1<7:0> (0)
01	PMDOUT1<15:8> (1)	PMDIN1<15:8> (1)
10	PMDOUT2<7:0> (2)	PMDIN2<7:0> (2)
11	PMDOUT2<15:8> (3)	PMDIN2<15:8> (3)

FIGURE 18-4: MASTER MODE, DEMULTIPLEXED ADDRESSING (SEPARATE READ AND WRITE STROBES, SINGLE CHIP SELECT)

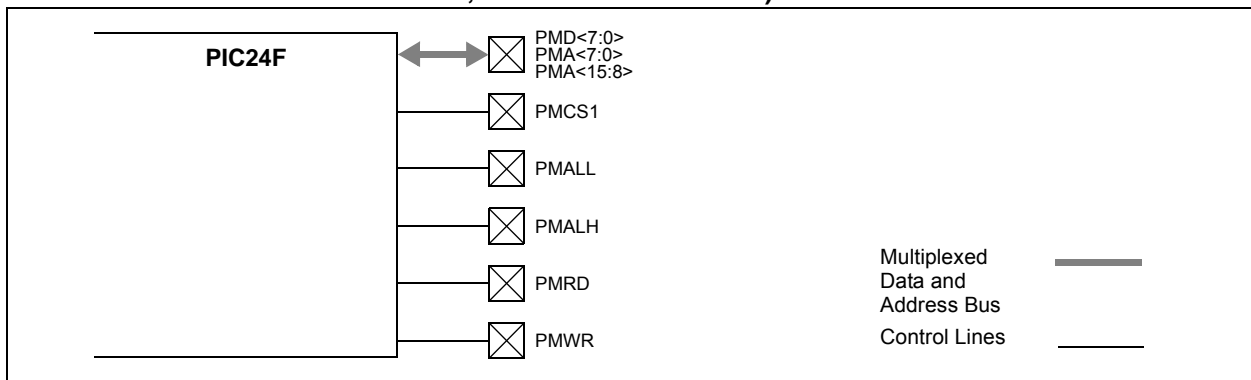


# PIC24FJ64GA004 FAMILY

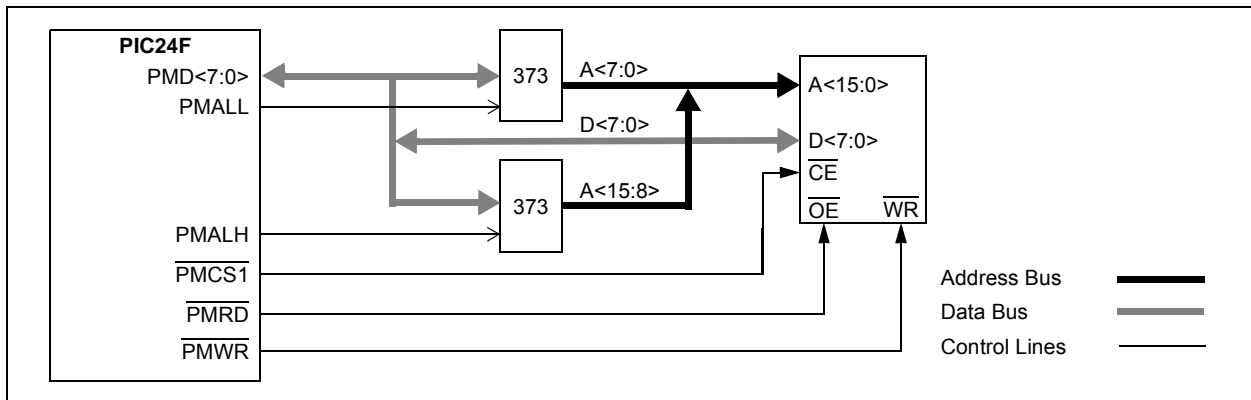
**FIGURE 18-5: MASTER MODE, PARTIALLY MULTIPLEXED ADDRESSING (SEPARATE READ AND WRITE STROBES, SINGLE CHIP SELECT)**



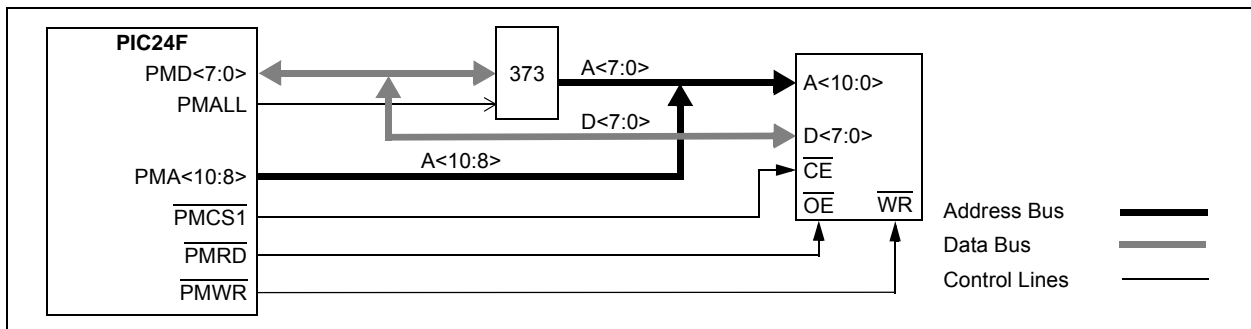
**FIGURE 18-6: MASTER MODE, FULLY MULTIPLEXED ADDRESSING (SEPARATE READ AND WRITE STROBES, SINGLE CHIP SELECT)**



**FIGURE 18-7: EXAMPLE OF A MULTIPLEXED ADDRESSING APPLICATION**



**FIGURE 18-8: EXAMPLE OF A PARTIALLY MULTIPLEXED ADDRESSING APPLICATION**



# PIC24FJ64GA004 FAMILY

FIGURE 18-9: EXAMPLE OF AN 8-BIT MULTIPLEXED ADDRESS AND DATA APPLICATION

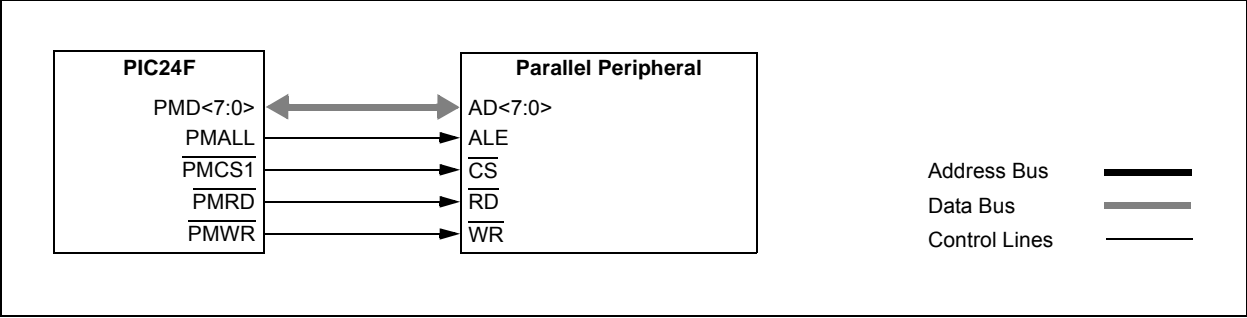


FIGURE 18-10: PARALLEL EEPROM EXAMPLE (UP TO 11-BIT ADDRESS, 8-BIT DATA)

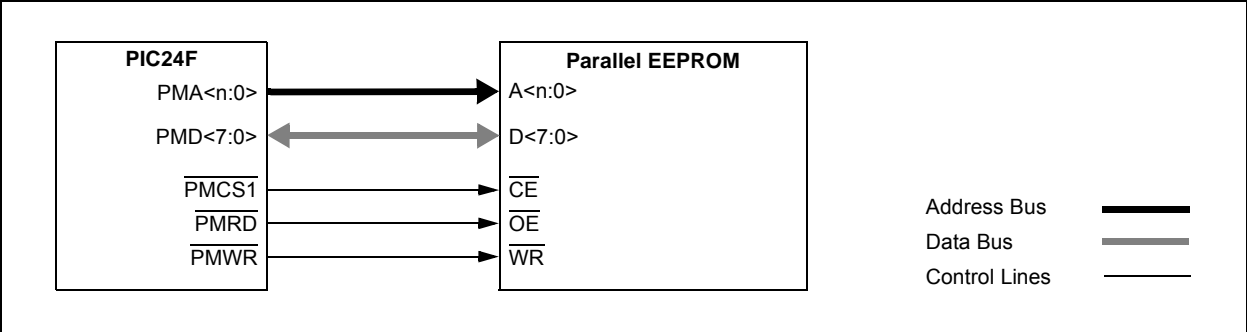


FIGURE 18-11: PARALLEL EEPROM EXAMPLE (UP TO 11-BIT ADDRESS, 16-BIT DATA)

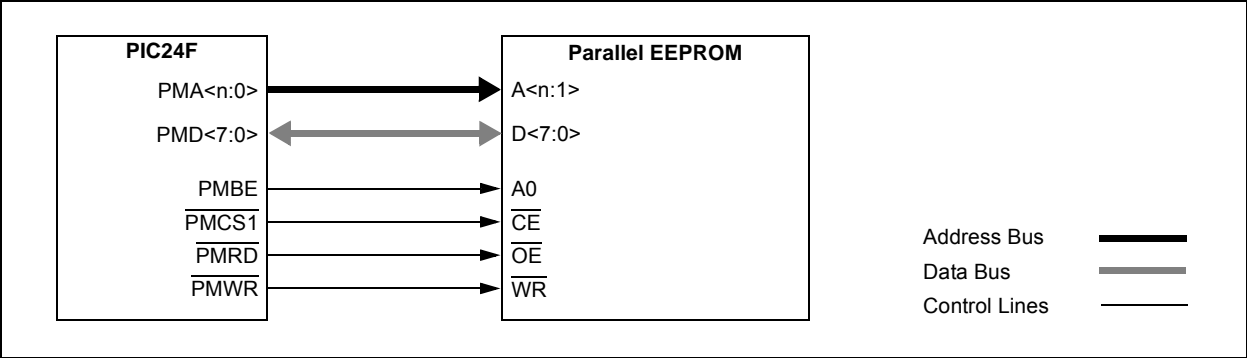
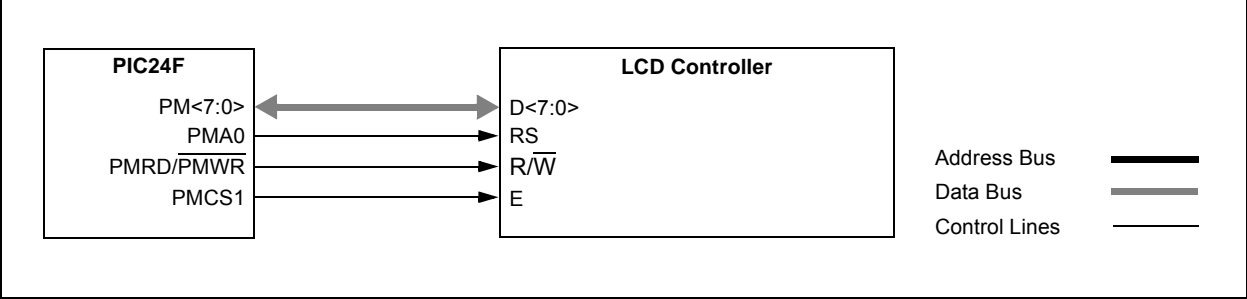


FIGURE 18-12: LCD CONTROL EXAMPLE (BYTE MODE OPERATION)





## 19.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Real-Time Clock and Calendar (RTCC)” (DS39696).

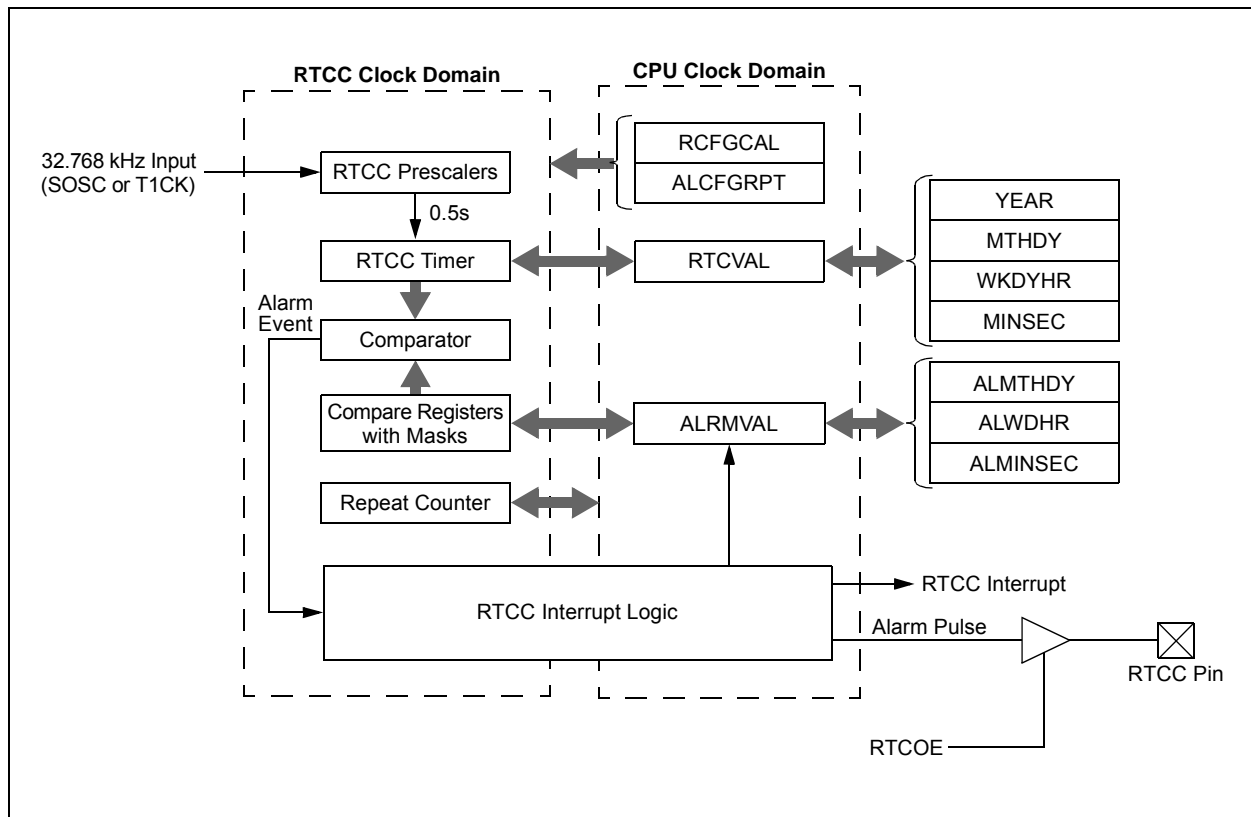
The Real-Time Clock and Calendar (RTCC) provides on-chip, hardware-based clock and calendar functionality with little or no CPU overhead. It is intended for applications where accurate time must be maintained for extended periods, with minimal CPU activity and with limited power resources, such as battery-powered applications.

Key features include:

- Time data in hours, minutes and seconds, with a granularity of one-half second
- 24-hour format (military time) display option
- Calendar data as date, month and year
- Automatic, hardware-based day of week and leap year calculations for dates from 2000 through 2099
- Time and calendar data in BCD format for compact firmware
- Highly configurable alarm function
- External output pin with selectable alarm signal or seconds “tick” signal output
- Time base input from Secondary Oscillator (SOSC) or the T1CK digital clock input (32.768 kHz)
- User calibration feature with auto-adjust

A simplified block diagram of the module is shown in Figure 19-1. The SOSC and RTCC will both remain running while the device is held in Reset with MCLR, and will continue running after MCLR is released.

FIGURE 19-1: RTCC BLOCK DIAGRAM



# PIC24FJ64GA004 FAMILY

## 19.1 RTCC Module Registers

The RTCC module registers are organized into three categories:

- RTCC Control Registers
- RTCC Value Registers
- Alarm Value Registers

### 19.1.1 REGISTER MAPPING

To limit the register interface, the RTCC Timer and Alarm Time registers are accessed through corresponding register pointers. The RTCC Value register window (RTCVALH and RTCVALL) uses the RTCPTR<1:0> bits (RCFGCAL<9:8>) to select the desired Timer register pair (see [Table 19-1](#)).

By writing the RTCVALH byte, the RTCC Pointer value (the RTCPTR<1:0> bits) decrements by one until the bits reach '00'. Once they reach '00', the MINUTES and SECONDS value will be accessible through RTCVALH and RTCVALL until the pointer value is manually changed.

**TABLE 19-1: RTCVAL REGISTER MAPPING**

RTCPTR <1:0>	RTCC Value Register Window	
	RTCVAL<15:8>	RTCVAL<7:0>
00	MINUTES	SECONDS
01	WEEKDAY	HOURS
10	MONTH	DAY
11	—	YEAR

The Alarm Value register window (ALRMVALH and ALRMVALL) uses the ALRMPTR bits (ALCFGRPT<9:8>) to select the desired Alarm register pair (see [Table 19-2](#)).

By writing the ALRMVALH byte, the Alarm Pointer value (the ALRMPTR<1:0> bits) decrements by one until the bits reach '00'. Once they reach '00', the ALRMMIN and ALRMSEC value will be accessible through ALRMVALH and ALRMVALL until the pointer value is manually changed.

### EXAMPLE 19-1: SETTING THE RTCWREN BIT

```
asm volatile("push w7");
asm volatile("push w8");
asm volatile("disi #5");
asm volatile("mov #0x55, w7");
asm volatile("mov w7, _NVMKEY");
asm volatile("mov #0xAA, w8");
asm volatile("mov w8, _NVMKEY");
asm volatile("bset _RCFGCAL, #13"); //set the RTCWREN bit
asm volatile("pop w8");
asm volatile("pop w7");
```

**TABLE 19-2: ALRMVAL REGISTER MAPPING**

ALRMPTR <1:0>	Alarm Value Register Window	
	ALRMVAL<15:8>	ALRMVAL<7:0>
00	ALRMMIN	ALRMSEC
01	ALRMWD	ALRMHR
10	ALRMMNTH	ALRMDAY
11	—	—

Considering that the 16-bit core does not distinguish between 8-bit and 16-bit read operations, the user must be aware that when reading either the ALRMVALH or ALRMVALL, the bytes will decrement the ALRMPTR<1:0> value. The same applies to the RTCVALH or RTCVALL bytes with the RTCPTR<1:0> being decremented.

**Note:** This only applies to read operations and not write operations.

### 19.1.2 WRITE LOCK

In order to perform a write to any of the RTCC Timer registers, the RTCWREN bit (RCFGCAL<13>) must be set (refer to [Example 19-1](#)).

**Note:** To avoid accidental writes to the timer, it is recommended that the RTCWREN bit (RCFGCAL<13>) is kept clear at any other time. For the RTCWREN bit to be set, there is only 1 instruction cycle time window allowed between the 55h/AA sequence and the setting of RTCWREN; therefore, it is recommended that code follow the procedure in [Example 19-1](#).

# PIC24FJ64GA004 FAMILY

## 19.1.3 RTCC CONTROL REGISTERS

### REGISTER 19-1: RCFGAL: RTCC CALIBRATION AND CONFIGURATION REGISTER<sup>(1)</sup>

R/W-0	U-0	R/W-0	R-0	R-0	R/W-0	R/W-0	R/W-0
RTCEN <sup>(2)</sup>	—	RTCWREN	RTCSYNC	HALFSEC <sup>(3)</sup>	RTCOE	RTCPTR1	RTCPTR0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0
bit 7							bit 0

#### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15      **RTCEN:** RTCC Enable bit<sup>(2)</sup>  
             1 = RTCC module is enabled  
             0 = RTCC module is disabled
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **RTCWREN:** RTCC Value Registers Write Enable bit  
             1 = RTCVALH and RTCVALL registers can be written to by the user  
             0 = RTCVALH and RTCVALL registers are locked out from being written to by the user
- bit 12      **RTCSYNC:** RTCC Value Registers Read Synchronization bit  
             1 = RTCVALH, RTCVALL and ALCFGRPT registers can change while reading due to a rollover ripple resulting in an invalid data read. If the register is read twice and results in the same data, the data can be assumed to be valid.  
             0 = RTCVALH, RTCVALL or ALCFGRPT register can be read without concern over a rollover ripple
- bit 11      **HALFSEC:** Half-Second Status bit<sup>(3)</sup>  
             1 = Second half period of a second  
             0 = First half period of a second
- bit 10      **RTCOE:** RTCC Output Enable bit  
             1 = RTCC output is enabled  
             0 = RTCC output is disabled
- bit 9-8      **RTCPTR<1:0>:** RTCC Value Register Window Pointer bits  
             Points to the corresponding RTCC Value registers when reading the RTCVALH and RTCVALL registers; the RTCPTR<1:0> value decrements on every read or write of RTCVALH until it reaches '00'.  
             RTCVAL<15:8>:  
             00 = MINUTES  
             01 = WEEKDAY  
             10 = MONTH  
             11 = Reserved  
             RTCVAL<7:0>:  
             00 = SECONDS  
             01 = HOURS  
             10 = DAY  
             11 = YEAR

**Note 1:** The RCFGAL register is only affected by a POR.

**2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.

**3:** This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

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## REGISTER 19-1: RCFGAL: RTCC CALIBRATION AND CONFIGURATION REGISTER<sup>(1)</sup>

bit 7-0      **CAL<7:0>**: RTCC Drift Calibration bits  
01111111 = Maximum positive adjustment; adds 508 RTC clock pulses every one minute  
...  
01111111 = Minimum positive adjustment; adds 4 RTC clock pulses every one minute  
00000000 = No adjustment  
11111111 = Minimum negative adjustment; subtracts 4 RTC clock pulses every one minute  
...  
10000000 = Maximum negative adjustment; subtracts 512 RTC clock pulses every one minute

- Note 1:** The RCFGAL register is only affected by a POR.  
**2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.  
**3:** This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

## REGISTER 19-2: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL <sup>(1)</sup>	PMPTTL
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 15-2      **Unimplemented:** Read as '0'  
bit 1      **RTSECSEL:** RTCC Seconds Clock Output Select bit<sup>(1)</sup>  
1 = RTCC seconds clock is selected for the RTCC pin  
0 = RTCC alarm pulse is selected for the RTCC pin  
bit 0      **PMPTTL:** PMP Module TTL Input Buffer Select bit  
1 = PMP module uses TTL input buffers  
0 = PMP module uses Schmitt Trigger input buffers

- Note 1:** To enable the actual RTCC output, the RTCOE (RCFGAL) bit needs to be set.

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## REGISTER 19-3: ALCFGRPT: ALARM CONFIGURATION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ALRMEN	CHIME	AMASK3	AMASK2	AMASK1	AMASK0	ALRMPTR1	ALRMPTR0
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ARPT7	ARPT6	ARPT5	ARPT4	ARPT3	ARPT2	ARPT1	ARPT0
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15      **ALRMEN:** Alarm Enable bit  
 1 = Alarm is enabled (cleared automatically after an alarm event whenever ARPT<7:0> = 00h and CHIME = 0)  
 0 = Alarm is disabled
- bit 14      **CHIME:** Chime Enable bit  
 1 = Chime is enabled; ARPT<7:0> bits are allowed to roll over from 00h to FFh  
 0 = Chime is disabled; ARPT<7:0> bits stop once they reach 00h
- bit 13-10      **AMASK<3:0>:** Alarm Mask Configuration bits  
 0000 = Every half second  
 0001 = Every second  
 0010 = Every 10 seconds  
 0011 = Every minute  
 0100 = Every 10 minutes  
 0101 = Every hour  
 0110 = Once a day  
 0111 = Once a week  
 1000 = Once a month  
 1001 = Once a year (except when configured for February 29th, once every 4 years)  
 101x = Reserved; do not use  
 11xx = Reserved; do not use
- bit 9-8      **ALRMPTR<1:0>:** Alarm Value Register Window Pointer bits  
 Points to the corresponding Alarm Value registers when reading ALRMVALH and ALRMVALL registers; the ALRMPTR<1:0> value decrements on every read or write of ALRMVALH until it reaches '00'.  
ALRMVAL<15:8>:  
 00 = ALRMMIN  
 01 = ALRMWD  
 10 = ALRMMNTH  
 11 = Unimplemented  
ALRMVAL<7:0>:  
 00 = ALRMSEC  
 01 = ALRMHR  
 10 = ALRMDAY  
 11 = Unimplemented
- bit 7-0      **ARPT<7:0>:** Alarm Repeat Counter Value bits  
 11111111 = Alarm will repeat 255 more times  
 ...  
 00000000 = Alarm will not repeat  
 The counter decrements on any alarm event. The counter is prevented from rolling over from 00h to FFh unless CHIME = 1.

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## 19.1.4 RTCVAL REGISTER MAPPINGS

### REGISTER 19-4: YEAR: YEAR VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
YRTEN3	YRTEN2	YRTEN1	YRTEN0	YRONE3	YRONE2	YRONE1	YRONE0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-4 **YRTEN<3:0>:** Binary Coded Decimal Value of Year's Tens Digit bits  
Contains a value from 0 to 9.

bit 3-0 **YRONE<3:0>:** Binary Coded Decimal Value of Year's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

### REGISTER 19-5: MTHDY: MONTH AND DAY VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	R-x	R-x	R-x	R-x	R-x
—	—	—	MHTTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	DAYTEN1	DAYTEN0	DAYONE3	DAYONE2	DAYONE1	DAYONE0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **MHTTEN0:** Binary Coded Decimal Value of Month's Tens Digit bit  
Contains a value of '0' or '1'.

bit 11-8 **MTHONE<3:0>:** Binary Coded Decimal Value of Month's Ones Digit bits  
Contains a value from 0 to 9.

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **DAYTEN<1:0>:** Binary Coded Decimal Value of Day's Tens Digit bits  
Contains a value from 0 to 3.

bit 3-0 **DAYONE<3:0>:** Binary Coded Decimal Value of Day's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

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**REGISTER 19-6: WKDYHR: WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15						bit 8	

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7						bit 0	

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15-11     **Unimplemented:** Read as '0'
- bit 10-8     **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit bits  
Contains a value from 0 to 6.
- bit 7-6     **Unimplemented:** Read as '0'
- bit 5-4     **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit bits  
Contains a value from 0 to 2.
- bit 3-0     **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

**REGISTER 19-7: MINSEC: MINUTES AND SECONDS VALUE REGISTER**

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
bit 15						bit 8	

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0
bit 7						bit 0	

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15     **Unimplemented:** Read as '0'
- bit 14-12   **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit bits  
Contains a value from 0 to 5.
- bit 11-8   **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit bits  
Contains a value from 0 to 9.
- bit 7     **Unimplemented:** Read as '0'
- bit 6-4   **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit bits  
Contains a value from 0 to 5.
- bit 3-0   **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit bits  
Contains a value from 0 to 9.

# PIC24FJ64GA004 FAMILY

## 19.1.5 ALRMVAL REGISTER MAPPINGS

### REGISTER 19-8: ALMTHDY: ALARM MONTH AND DAY VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	MHTTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	DAYTEN1	DAYTEN0	DAYONE3	DAYONE2	DAYONE1	DAYONE0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **MHTTEN0:** Binary Coded Decimal Value of Month's Tens Digit bit

Contains a value of '0' or '1'.

bit 11-8 **MTHONE<3:0>:** Binary Coded Decimal Value of Month's Ones Digit bits

Contains a value from 0 to 9.

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **DAYTEN<1:0>:** Binary Coded Decimal Value of Day's Tens Digit bits

Contains a value from 0 to 3.

bit 3-0 **DAYONE<3:0>:** Binary Coded Decimal Value of Day's Ones Digit bits

Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.



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## REGISTER 19-9: ALWDHR: ALARM WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15						bit 8	

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit bits  
Contains a value from 0 to 6.

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit bits  
Contains a value from 0 to 2.

bit 3-0 **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

## REGISTER 19-10: ALMINSEC: ALARM MINUTES AND SECONDS VALUE REGISTER

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
bit 15						bit 8	

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit bits  
Contains a value from 0 to 5.

bit 11-8 **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit bits  
Contains a value from 0 to 9.

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit bits  
Contains a value from 0 to 5.

bit 3-0 **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit bits  
Contains a value from 0 to 9.

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## 19.2 Calibration

The real-time crystal input can be calibrated using the periodic auto-adjust feature. When properly calibrated, the RTCC can provide an error of less than 3 seconds per month. This is accomplished by finding the number of error clock pulses and storing the value into the lower half of the RCFGAL register. The 8-bit signed value, loaded into the lower half of RCFGAL, is multiplied by four and will be either added or subtracted from the RTCC timer, once every minute. Refer to the steps below for RTCC calibration:

1. Using another timer resource on the device, the user must find the error of the 32.768 kHz crystal.
2. Once the error is known, it must be converted to the number of error clock pulses per minute.

### EQUATION 19-1:

$$\frac{(\text{Ideal Frequency}^\dagger - \text{Measured Frequency}) * 60}{\text{Clocks per Minute}} \\ \dagger \text{ Ideal frequency} = 32,768 \text{ Hz}$$

3. a) If the oscillator is faster than ideal (negative result from Step 2), the RCFGAL register value needs to be negative. This causes the specified number of clock pulses to be subtracted from the timer counter, once every minute.  
b) If the oscillator is slower than ideal (positive result from Step 2), the RCFGAL register value needs to be positive. This causes the specified number of clock pulses to be subtracted from the timer counter, once every minute.
4. Divide the number of error clocks per minute by 4 to get the correct CAL<7:0> bits value and load the RCFGAL register with the correct value.  
(Each 1-bit increment in the CALx bits value adds or subtracts 4 pulses).

Writes to the lower half of the RCFGAL register should only occur when the timer is turned off or immediately after the rising edge of the seconds pulse.

**Note:** It is up to the user to include in the error value the initial error of the crystal, drift due to temperature and drift due to crystal aging.

## 19.3 Alarm

- Configurable from half second to one year
- Enabled using the ALRMEN bit (ALCFGRPT<15>, [Register 19-3](#))
- One-time alarm and repeat alarm options are available

### 19.3.1 CONFIGURING THE ALARM

The alarm feature is enabled using the ALRMEN bit. This bit is cleared when an alarm is issued. Writes to ALRMVAL should only take place when ALRMEN = 0.

As shown in [Figure 19-2](#), the interval selection of the alarm is configured through the AMASK<3:0> bits (ALCFGRPT<13:10>). These bits determine which and how many digits of the alarm must match the clock value for the alarm to occur.

The alarm can also be configured to repeat based on a preconfigured interval. The amount of times this occurs, once the alarm is enabled, is stored in the ARPT<7:0> bits (ALCFGRPT<7:0>). When the value of the ARPTx bits equals 00h and the CHIME bit (ALCFGRPT<14>) is cleared, the repeat function is disabled and only a single alarm will occur. The alarm can be repeated up to 255 times by loading ARPT<7:0> with FFh.

After each alarm is issued, the value of the ARPTx bits is decremented by one. Once the value has reached 00h, the alarm will be issued one last time, after which, the ALRMEN bit will be cleared automatically and the alarm will turn off.

Indefinite repetition of the alarm can occur if CHIME (ALCFGRPT<14>) = 1. Instead of the alarm being disabled when the value of the ARPTx bits reaches 00h, it rolls over to FFh and continues counting indefinitely while CHIME is set.

### 19.3.2 ALARM INTERRUPT

At every alarm event, an interrupt is generated. In addition, an alarm pulse output is provided that operates at half the frequency of the alarm. This output is completely synchronous to the RTCC clock and can be used as a trigger clock to other peripherals.

**Note:** Changing any of the registers, other than the RCFGAL and ALCFGRPT registers and the CHIME bit while the alarm is enabled (ALRMEN = 1), can result in a false alarm event leading to a false alarm interrupt. To avoid a false alarm event, the timer and alarm values should only be changed while the alarm is disabled (ALRMEN = 0). It is recommended that the ALCFGRPT register and CHIME bit be changed when RTCSYNC = 0.

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**FIGURE 19-2: ALARM MASK SETTINGS**

Alarm Mask Setting (AMASK<3:0>)	Day of the Week	Month	Day	Hours	Minutes	Seconds
0000 – Every half second 0001 – Every second	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>
0010 – Every 10 seconds	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> s
0011 – Every minute	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> s <input type="checkbox"/> s
0100 – Every 10 minutes	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s
0101 – Every hour	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s
0110 – Every day	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> h <input type="checkbox"/> h	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s
0111 – Every week	<input type="checkbox"/> d	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> h <input type="checkbox"/> h	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s
1000 – Every month	<input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> d <input type="checkbox"/> d	<input type="checkbox"/> h <input type="checkbox"/> h	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s
1001 – Every year <sup>(1)</sup>	<input type="checkbox"/>	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> d <input type="checkbox"/> d	<input type="checkbox"/> h <input type="checkbox"/> h	<input type="checkbox"/> m <input type="checkbox"/> m	<input type="checkbox"/> s <input type="checkbox"/> s

**Note 1:** Annually, except when configured for February 29.

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NOTES:

## 20.0 PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Programmable Cyclic Redundancy Check (CRC)” (DS39714).

The programmable CRC generator offers the following features:

- User-programmable polynomial CRC equation
- Interrupt output
- Data FIFO

The module implements a software configurable CRC generator. The terms of the polynomial and its length can be programmed using the X<15:1> bits (CRCXOR<15:1>) and the PLEN<3:0> bits (CRCCON<3:0>), respectively.

Consider the following equation:

**EQUATION 20-1: CRC POLYNOMIAL**

$$x^{16} + x^{12} + x^5 + 1$$

To program this polynomial into the CRC generator, the CRC register bits should be set as shown in [Table 20-1](#).

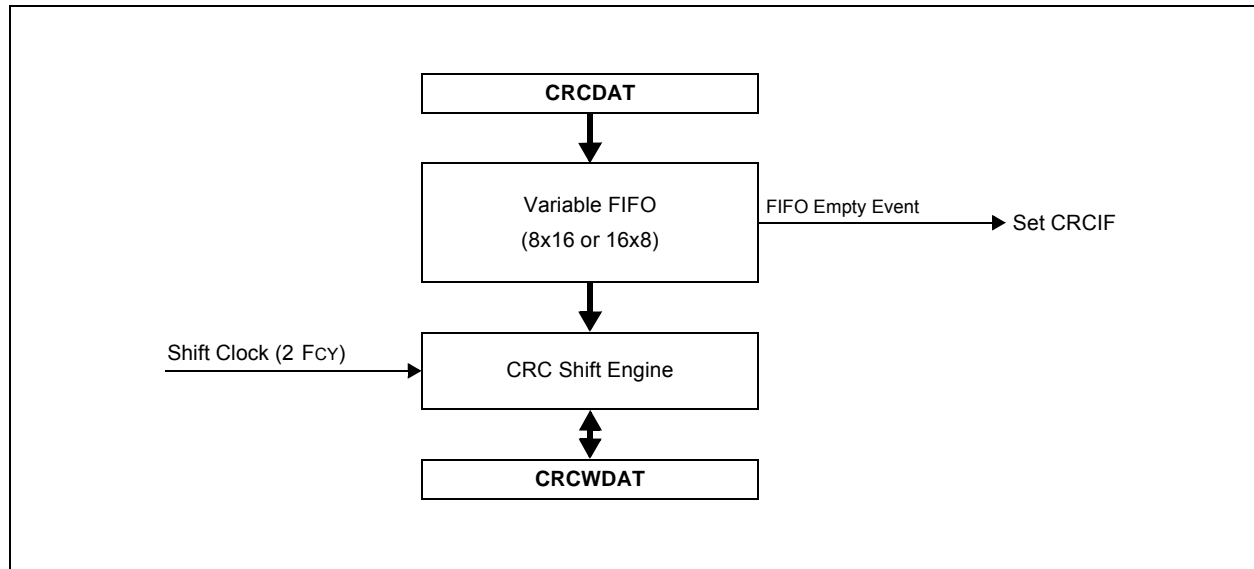
**TABLE 20-1: EXAMPLE CRC SETUP**

Bit Name	Bit Value
PLEN<3:0>	1111
X<15:1>	000100000010000

Note that for the value of X<15:1>, the 12th bit and the 5th bit are set to ‘1’, as required by the equation. The 0 bit, required by the equation, is always XORed. For a 16-bit polynomial, the 16th bit is also always assumed to be XORed; therefore, the X<15:1> bits do not have the 0 bit or the 16th bit.

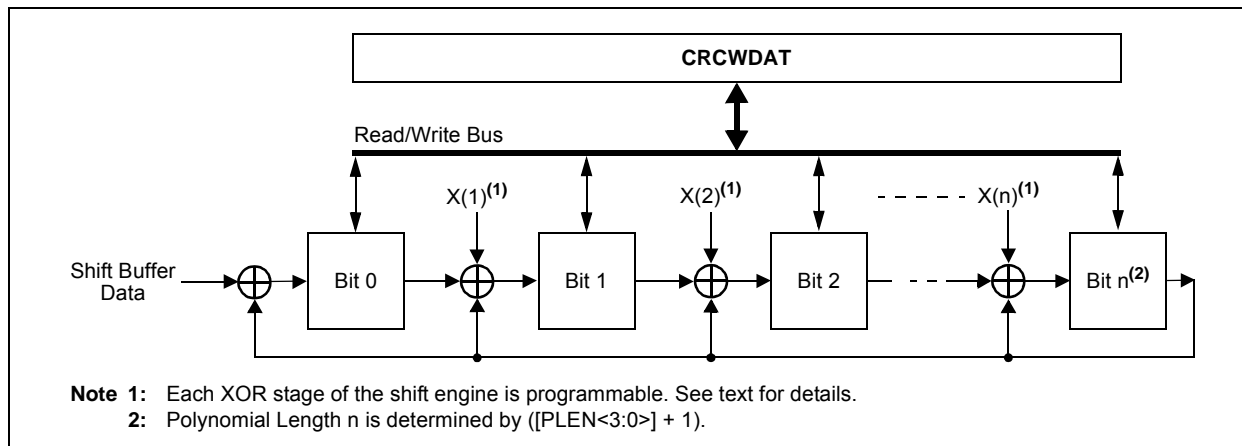
A simplified block diagram of the module is shown in [Figure 20-1](#). The general topology of the shift engine is shown in [Figure 20-2](#).

**FIGURE 20-1: CRC BLOCK DIAGRAM**



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**FIGURE 20-2: CRC SHIFT ENGINE DETAIL**



## 20.1 User Interface

### 20.1.1 DATA INTERFACE

To start serial shifting, a '1' must be written to the CRCGO bit.

The module incorporates a FIFO that is 8 deep when  $PLEN<3:0> (CRCCON<3:0>) > 7$  and 16 deep, otherwise. The data for which the CRC is to be calculated must first be written into the FIFO. The smallest data element that can be written into the FIFO is one byte. For example, if  $PLEN<3:0> = 5$ , then the size of the data is  $PLEN<3:0> + 1 = 6$ . When loading data, the two MSBs of the data byte are ignored.

Once data is written into the CRCWDAT MSb (as defined by  $PLENx$ ), the value of  $VWORD<4:0> (CRCCON<12:8>)$  increments by one. When  $CRCGO = 1$  and  $VWORDx > 0$ , a word of data to be shifted is moved from the FIFO into the shift engine. When the data word moves from the FIFO to the shift engine, the  $VWORDx$  bits decrement by one. The serial shifter continues to receive data from the FIFO, shifting until the  $VWORDx$  bits reach 0. The last bit of data will be shifted through the CRC module ( $PLENx + 1$ )/2 clock cycles after the  $VWORDx$  bits reach 0. This is when the module is completed with the CRC calculation.

Therefore, for a given value of  $PLENx$ , it will take  $(PLENx + 1)/2 * VWORDx$  number of clock cycles to complete the CRC calculations.

When the  $VWORD<4:0>$  bits reach 8 (or 16), the  $CRCFUL$  bit will be set. When the  $VWORD<4:0>$  bits reach 0, the  $CRCMPT$  bit will be set.

To continually feed data into the CRC engine, the recommended mode of operation is to initially "prime" the FIFO with a sufficient number of words, so no interrupt is generated before the next word can be written. Once that is done, start the CRC by setting the  $CRCGO$  bit to '1'. From that point onward, the  $VWORDx$  bits should be polled. If they read less than 8 or 16, another word can be written into the FIFO.

To empty words already written into a FIFO, the  $CRCGO$  bit must be set to '1' and the CRC shifter allowed to run until the  $CRCMPT$  bit is set.

Also, to get the correct CRC reading, it will be necessary to wait for the  $CRCMPT$  bit to go high before reading the  $CRCWDAT$  register.

If a word is written when the  $CRCFUL$  bit is set, the  $VWORDx$  Pointer will roll over to 0. The hardware will then behave as if the FIFO is empty. However, the condition to generate an interrupt will not be met; therefore, no interrupt will be generated (See [Section 20.1.2 "Interrupt Operation"](#)).

At least one instruction cycle must pass after a write to  $CRCWDAT$  before a read of the  $VWORDx$  bits is done.

### 20.1.2 INTERRUPT OPERATION

When the  $VWORD<4:0>$  bits make a transition from a value of '1' to '0', an interrupt will be generated. Note that the CRC calculation is not complete at this point; an additional time of  $(PLEN + 1)/2$  clock cycles is required before the output can be read.

## 20.2 Operation in Power Save Modes

### 20.2.1 SLEEP MODE

If Sleep mode is entered while the module is operating, the module will be suspended in its current state until clock execution resumes.

### 20.2.2 IDLE MODE

To continue full module operation in Idle mode, the  $CSIDL$  bit must be cleared prior to entry into the mode.

If  $CSIDL = 1$ , the module will behave the same way as it does in Sleep mode; pending interrupt events will be passed on, even though the module clocks are not available.

# PIC24FJ64GA004 FAMILY

## 20.3 Registers

There are four registers used to control programmable CRC operation:

- CRCCON
- CRCXOR
- CRCDAT
- CRCWDAT

### REGISTER 20-1: CRCCON: CRC CONTROL REGISTER

U-0	U-0	R/W-0	R-0	R-0	R-0	R-0	R-0
—	—	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0
bit 15		bit 8					

R-0		R-1		U-0		R/W-0		R/W-0		R/W-0		R/W-0		R/W-0	
CRCFUL		CRCMPT		—		CRCGO		PLEN3		PLEN2		PLEN1		PLEN0	
bit 7														bit 0	

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **CSIDL:** CRC Stop in Idle Mode bit

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12-8 **VWORD<4:0>:** Pointer Value bits

Indicates the number of valid words in the FIFO. Has a maximum value of 8 when PLEN<3:0> > 7 or 16 when PLEN<3:0> ≤ 7.

bit 7 **CRCFUL:** CRC FIFO Full bit

1 = FIFO is full

0 = FIFO is not full

bit 6 **CRCMPT:** CRC FIFO Empty Bit

1 = FIFO is empty

0 = FIFO is not empty

bit 5 **Unimplemented:** Read as '0'

bit 4 **CRCGO:** CRC Start bit

1 = Starts CRC serial shifter

0 = CRC serial shifter is turned off

bit 3-0 **PLEN<3:0>:** Polynomial Length bits

Denotes the length of the polynomial to be generated minus 1.

# PIC24FJ64GA004 FAMILY

## REGISTER 20-2: CRCXOR: CRC XOR POLYNOMIAL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
X15	X14	X13	X12	X11	X10	X9	X8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
X7	X6	X5	X4	X3	X2	X1	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-1      **X<15:1>:** XOR of Polynomial Term  $X^n$  Enable bits

bit 0      **Unimplemented:** Read as '0'



## 21.0 10-BIT HIGH-SPEED A/D CONVERTER

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “10-Bit A/D Converter” (DS39705).

The 10-bit A/D Converter has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 500 ksps
- Up to 13 analog input pins
- External voltage reference input pins
- Automatic Channel Scan mode
- Selectable conversion trigger source
- 16-word conversion result buffer
- Selectable Buffer Fill modes
- Four result alignment options
- Operation during CPU Sleep and Idle modes

Depending on the particular device pinout, the 10-bit A/D Converter can have up to three analog input pins, designated AN0 through AN12. In addition, there are two analog input pins for external voltage reference connections. These voltage reference inputs may be shared with other analog input pins. The actual number of analog input pins and the external voltage reference input configuration will depend on the specific device.

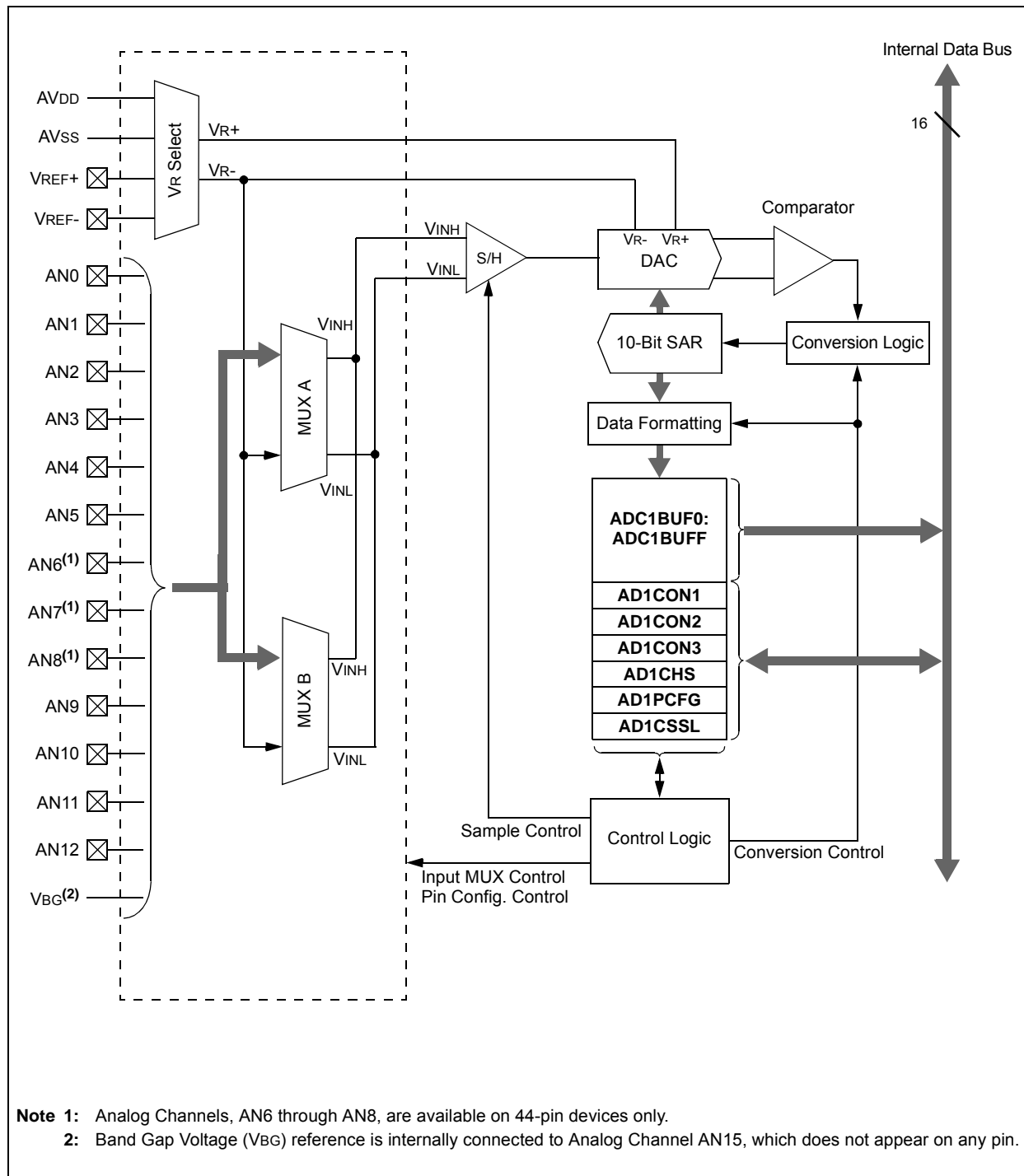
A block diagram of the A/D Converter is shown in [Figure 21-1](#).

To perform an A/D conversion:

1. Configure the A/D module:
  - a) Select the port pins as analog inputs (AD1PCFG<15:0>).
  - b) Select the voltage reference source to match the expected range on the analog inputs (AD1CON2<15:13>).
  - c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
  - d) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
  - e) Select how conversion results are presented in the buffer (AD1CON1<9:8>).
  - f) Select the interrupt rate (AD1CON2<5:2>).
  - g) Turn on the A/D module (AD1CON1<15>).
2. Configure the A/D interrupt (if required):
  - a) Clear the AD1IF bit.
  - b) Select the A/D interrupt priority.

# PIC24FJ64GA004 FAMILY

**FIGURE 21-1: 10-BIT HIGH-SPEED A/D CONVERTER BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## REGISTER 21-1: AD1CON1: A/D CONTROL REGISTER 1

R/W-0	U-0	R/C-0	U-0	U-0	U-0	R/W-0	R/W-0
ADON <sup>(1)</sup>	—	ADSIDL	—	—	—	FORM1	FORM0
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0, HSC	R/W-0, HSC
SSRC2	SSRC1	SSRC0	—	—	ASAM	SAMP	DONE
bit 7						bit 0	

<b>Legend:</b>	C = Clearable bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **ADON:** A/D Operating Mode bit<sup>(1)</sup>  
1 = A/D Converter module is operating  
0 = A/D Converter is off
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **ADSIDL:** A/D Stop in Idle Mode bit  
1 = Discontinues module operation when device enters Idle mode  
0 = Continues module operation in Idle mode
- bit 12-10 **Unimplemented:** Read as '0'
- bit 9-8 **FORM<1:0>:** Data Output Format bits  
11 = Signed fractional (sddd dddd dd00 0000)  
10 = Fractional (dddd dddd dd00 0000)  
01 = Signed integer (ssss sssd dddd dddd)  
00 = Integer (0000 00dd dddd dddd)
- bit 7-5 **SSRC<2:0>:** Conversion Trigger Source Select bits  
111 = Internal counter ends sampling and starts conversion (auto-convert)  
110 = Reserved  
10x = Reserved  
011 = Reserved  
010 = Timer3 compare ends sampling and starts conversion  
001 = Active transition on INT0 pin ends sampling and starts conversion  
000 = Clearing the SAMP bit ends sampling and starts conversion
- bit 4-3 **Unimplemented:** Read as '0'
- bit 2 **ASAM:** A/D Sample Auto-Start bit  
1 = Sampling begins immediately after last conversion completes; SAMP bit is auto-set  
0 = Sampling begins when SAMP bit is set
- bit 1 **SAMP:** A/D Sample Enable bit  
1 = A/D Sample-and-Hold (S/H) amplifier is sampling input  
0 = A/D Sample-and-Hold amplifier is holding
- bit 0 **DONE:** A/D Conversion Status bit  
1 = A/D conversion is done  
0 = A/D conversion is NOT done

**Note 1:** The ADC1BUFn registers do not retain their values when ADON is cleared. Read out any conversion values from the buffer before disabling the module.

# PIC24FJ64GA004 FAMILY

## REGISTER 21-2: AD1CON2: A/D CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0	U-0
VCFG2	VCFG1	VCFG0	—	—	CSCNA	—	—
bit 15						bit 8	

R-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUFS	—	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **VCFG<2:0>**: Voltage Reference Configuration bits

VCFG<2:0>	V <sub>R+</sub>	V <sub>R-</sub>
000	AVDD*	AVSS*
001	External VREF+ Pin	AVSS*
010	AVDD*	External VREF- Pin
011	External VREF+ Pin	External VREF- Pin
1xx	AVDD*	AVSS*

\* AVDD and AVSS inputs are tied to VDD and VSS on 28-pin devices.

bit 12-11 **Unimplemented**: Read as '0'

bit 10 **CSCNA**: Scan Input Selections for CH0+ S/H Input for MUX A Input Multiplexer Setting bit

1 = Scans inputs

0 = Does not scan inputs

bit 9-8 **Unimplemented**: Read as '0'

bit 7 **BUFS**: Buffer Fill Status bit (valid only when BUFM = 1)

1 = A/D is currently filling Buffer 08-0F, user should access data in 00-07

0 = A/D is currently filling Buffer 00-07, user should access data in 08-0F

bit 6 **Unimplemented**: Read as '0'

bit 5-2 **SMPI<3:0>**: Sample/Convert Sequences Per Interrupt Selection bits

1111 = Interrupts at the completion of conversion for each 16th sample/convert sequence

1110 = Interrupts at the completion of conversion for each 15th sample/convert sequence

.....

0001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence

0000 = Interrupts at the completion of conversion for each sample/convert sequence

bit 1 **BUFM**: Buffer Mode Select bit

1 = Buffer configured as two 8-word buffers (ADC1BUF<sub>n</sub><15:8> and ADC1BUF<sub>n</sub><7:0>)

0 = Buffer configured as one 16-word buffer (ADC1BUF<sub>n</sub><15:0>)

bit 0 **ALTS**: Alternate Input Sample Mode Select bit

1 = Uses MUX A input multiplexer settings for first sample, then alternates between MUX B and MUX A input multiplexer settings for all subsequent samples

0 = Always uses MUX A input multiplexer settings

# PIC24FJ64GA004 FAMILY

## REGISTER 21-3: AD1CON3: A/D CONTROL REGISTER 3

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADRC	—	—	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **ADRC:** A/D Conversion Clock Source bit

1 = A/D internal RC clock

0 = Clock derived from system clock

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **SAMC<4:0>:** Auto-Sample Time bits

11111 = 31 TAD

.....

00001 = 1 TAD

00000 = 0 TAD (not recommended)

bit 7-0 **ADCS<7:0>:** A/D Conversion Clock Select bits

11111111

..... = Reserved

01000000

00111111 = 64 • T<sub>CY</sub>

.....

00000001 = 2 • T<sub>CY</sub>

00000000 = T<sub>CY</sub>

# PIC24FJ64GA004 FAMILY

## REGISTER 21-4: AD1CHS: A/D INPUT SELECT REGISTER

R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB	—	—	—	CH0SB3 <sup>(1,2)</sup>	CH0SB2 <sup>(1,2)</sup>	CH0SB1 <sup>(1,2)</sup>	CH0SB0 <sup>(1,2)</sup>
bit 15				bit 8			

R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA	—	—	—	CH0SA3 <sup>(1,2)</sup>	CH0SA2 <sup>(1,2)</sup>	CH0SA1 <sup>(1,2)</sup>	CH0SA0 <sup>(1,2)</sup>
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **CH0NB:** Channel 0 Negative Input Select for MUX B Multiplexer Setting bit  
               1 = Channel 0 negative input is AN1  
               0 = Channel 0 negative input is VR-
- bit 14-12    **Unimplemented:** Read as '0'
- bit 11-8     **CH0SB<3:0>:** Channel 0 Positive Input Select for MUX B Multiplexer Setting bits<sup>(1,2)</sup>  
               1111 = Channel 0 positive input is AN15 (band gap voltage reference)  
               1100 = Channel 0 positive input is AN12  
               1011 = Channel 0 positive input is AN11  
               .....  
               0001 = Channel 0 positive input is AN1  
               0000 = Channel 0 positive input is AN0
- bit 7        **CH0NA:** Channel 0 Negative Input Select for MUX A Multiplexer Setting bit  
               1 = Channel 0 negative input is AN1  
               0 = Channel 0 negative input is VR-
- bit 6-4      **Unimplemented:** Read as '0'
- bit 3-0      **CH0SA<3:0>:** Channel 0 Positive Input Select for MUX A Multiplexer Setting bits<sup>(1,2)</sup>  
               1111 = Channel 0 positive input is AN15 (band gap voltage reference)  
               1100 = Channel 0 positive input is AN12  
               1011 = Channel 0 positive input is AN11  
               .....  
               0001 = Channel 0 positive input is AN1  
               0000 = Channel 0 positive input is AN0

**Note 1:** Combinations, '1101' and '1110', are unimplemented; do not use.

**2:** Analog Channels, AN6, AN7 and AN8, are unavailable on 28-pin devices; do not use.

# PIC24FJ64GA004 FAMILY

**REGISTER 21-5: AD1PCFG: A/D PORT CONFIGURATION REGISTER**

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG15	—	—	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8 <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG7 <sup>(1)</sup>	PCFG6 <sup>(1)</sup>	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15            **PCFG15:** Analog Input Pin Configuration Control bit  
                     1 = Band gap voltage reference is disabled  
                     0 = Band gap voltage reference is enabled
- bit 14-13       **Unimplemented:** Read as '0'
- bit 12-0        **PCFG<12:0>:** Analog Input Pin Configuration Control bits<sup>(1)</sup>  
                     1 = Pin for corresponding analog channel is configured in Digital mode; I/O port read is enabled  
                     0 = Pin is configured in Analog mode; I/O port read is disabled, A/D samples pin voltage

**Note 1:** Analog Channels, AN6, AN7 and AN8, are unavailable on 28-pin devices; leave these corresponding bits set.

**REGISTER 21-6: AD1CSSL: A/D INPUT SCAN SELECT REGISTER**

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL15	—	—	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8 <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL7 <sup>(1)</sup>	CSSL6 <sup>(1)</sup>	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15            **CSSL15:** Band Gap Reference Input Pin Scan Selection bit  
                     1 = Band gap voltage reference channel is selected for input scan  
                     0 = Band gap voltage reference channel is omitted from input scan
- bit 14-13       **Unimplemented:** Read as '0'
- bit 12-0        **CSSL<12:0>:** A/D Input Pin Scan Selection bits<sup>(1)</sup>  
                     1 = Corresponding analog channel is selected for input scan  
                     0 = Analog channel is omitted from input scan

**Note 1:** Analog Channels, AN6, AN7 and AN8, are unavailable on 28-pin devices; leave these corresponding bits cleared.

# PIC24FJ64GA004 FAMILY

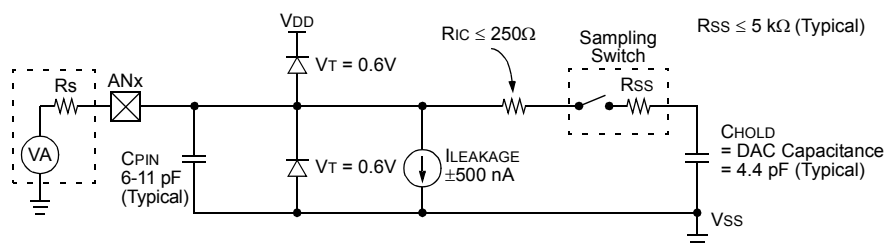
## EQUATION 21-1: A/D CONVERSION CLOCK PERIOD<sup>(1)</sup>

$$T_{AD} = T_{CY} \cdot (ADCS + 1)$$

$$ADCS = \frac{T_{AD}}{T_{CY}} - 1$$

**Note 1:** Based on  $T_{CY} = 2 \cdot T_{OSC}$ ; Doze mode and PLL are disabled.

**FIGURE 21-2: 10-BIT A/D CONVERTER ANALOG INPUT MODEL**



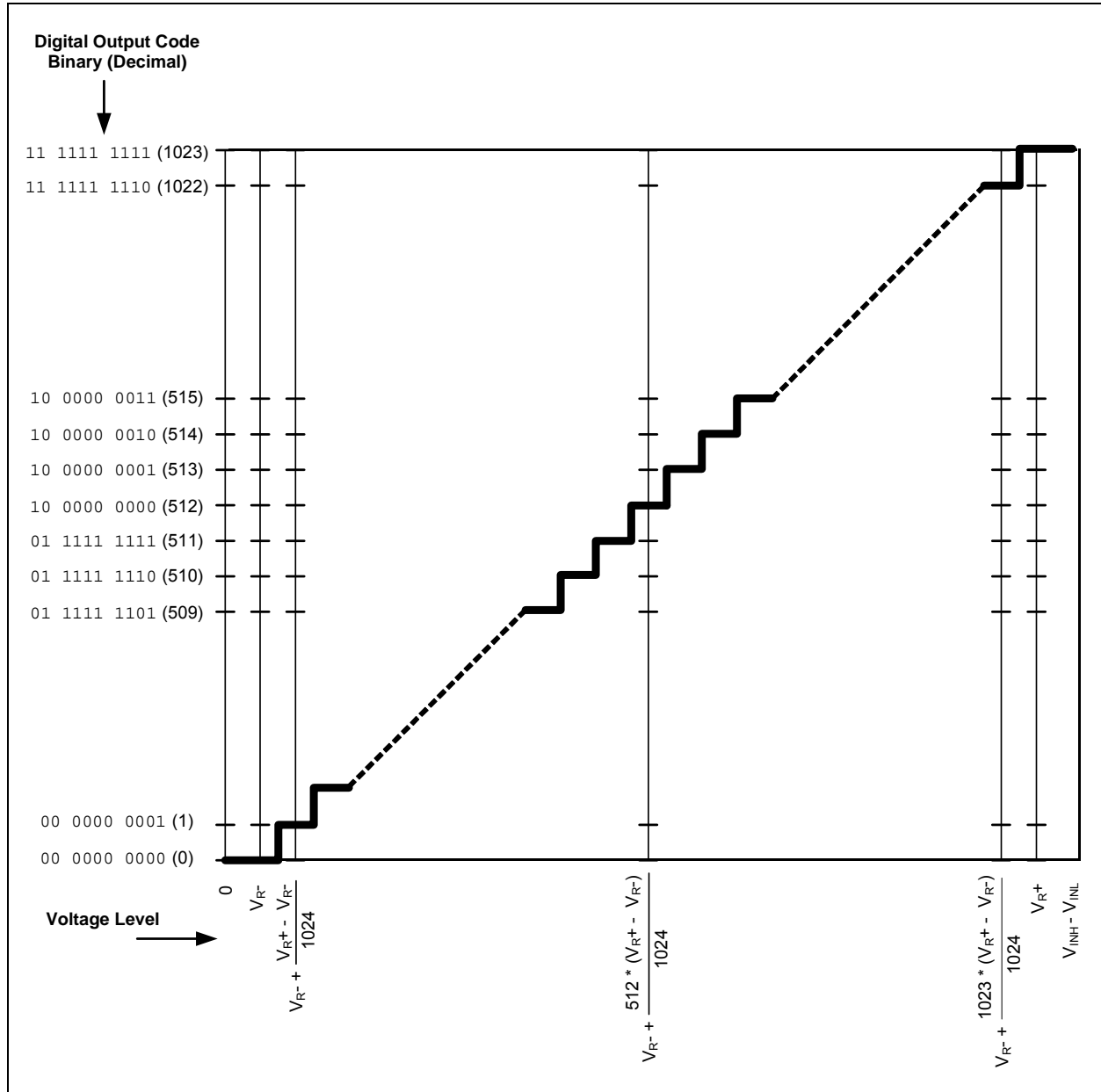
<b>Legend:</b>	CPIN	= Input Capacitance
	VT	= Threshold Voltage
	ILEAKAGE	= Leakage Current at the pin due to various junctions
	RIC	= Interconnect Resistance
	RSS	= Sampling Switch Resistance
	CHOLD	= Sample/Hold Capacitance (from DAC)

**Note:** CPIN value depends on device package and is not tested. The effect of CPIN is negligible if  $R_s \leq 5 \text{ k}\Omega$ .



# PIC24FJ64GA004 FAMILY

**FIGURE 21-3: A/D TRANSFER FUNCTION**



# PIC24FJ64GA004 FAMILY

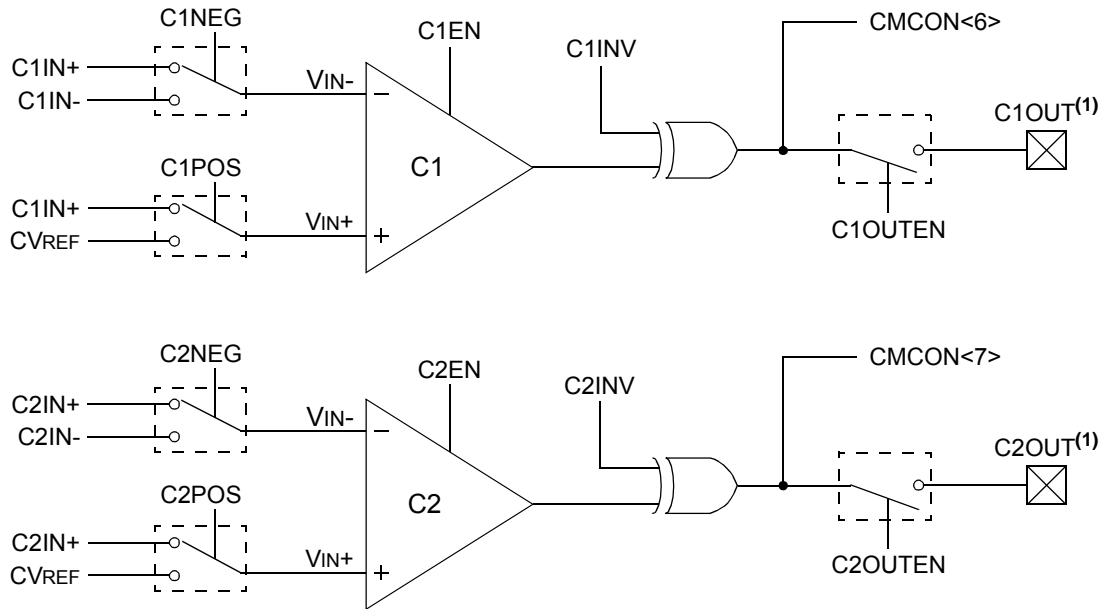
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NOTES:

## 22.0 COMPARATOR MODULE

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Output Compare” (DS39706).

**FIGURE 22-1: COMPARATOR I/O OPERATING MODES**



**Note 1:** This peripheral's outputs must be assigned to an available RPN pin before use. Please see [Section 10.4 "Peripheral Pin Select \(PPS\)"](#) for more information.

# PIC24FJ64GA004 FAMILY

## REGISTER 22-1: CMCON: COMPARATOR CONTROL REGISTER

R/W-0	U-0	R/C-0	R/C-0	R/W-0	R/W-0	R/W-0	R/W-0
CMIDL	—	C2EVT	C1EVT	C2EN	C1EN	C2OUTEN <sup>(1)</sup>	C1OUTEN <sup>(2)</sup>
bit 15						bit 8	

R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
C2OUT	C1OUT	C2INV	C1INV	C2NEG	C2POS	C1NEG	C1POS
bit 7						bit 0	

<b>Legend:</b>	C = Clearable bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	'1' = Bit is set
-n = Value at POR	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **CMIDL:** Comparator Stop in Idle Mode bit  
 1 = When device enters Idle mode, module does not generate interrupts; module is still enabled  
 0 = Continues normal module operation in Idle mode
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **C2EVT:** Comparator 2 Event  
 1 = Comparator output changed states  
 0 = Comparator output did not change states
- bit 12 **C1EVT:** Comparator 1 Event  
 1 = Comparator output changed states  
 0 = Comparator output did not change states
- bit 11 **C2EN:** Comparator 2 Enable  
 1 = Comparator is enabled  
 0 = Comparator is disabled
- bit 10 **C1EN:** Comparator 1 Enable  
 1 = Comparator is enabled  
 0 = Comparator is disabled
- bit 9 **C2OUTEN:** Comparator 2 Output Enable<sup>(1)</sup>  
 1 = Comparator output is driven on the output pad  
 0 = Comparator output is not driven on the output pad
- bit 8 **C1OUTEN:** Comparator 1 Output Enable<sup>(2)</sup>  
 1 = Comparator output is driven on the output pad  
 0 = Comparator output is not driven on the output pad
- bit 7 **C2OUT:** Comparator 2 Output bit  
When C2INV = 0:  
 1 = C2 VIN+ > C2 VIN-  
 0 = C2 VIN+ < C2 VIN-  
When C2INV = 1:  
 0 = C2 VIN+ > C2 VIN-  
 1 = C2 VIN+ < C2 VIN-

- Note 1:** If C2OUTEN = 1, the C2OUT peripheral output must be configured to an available RPn pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
- 2:** If C1OUTEN = 1, the C1OUT peripheral output must be configured to an available RPn pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

## REGISTER 22-1: CMCON: COMPARATOR CONTROL REGISTER (CONTINUED)

bit 6	<b>C1OUT:</b> Comparator 1 Output bit <u>When C1INV = 0:</u> 1 = C1 VIN+ > C1 VIN- 0 = C1 VIN+ < C1 VIN- <u>When C1INV = 1:</u> 0 = C1 VIN+ > C1 VIN- 1 = C1 VIN+ < C1 VIN-
bit 5	<b>C2INV:</b> Comparator 2 Output Inversion bit 1 = C2 output is inverted 0 = C2 output is not inverted
bit 4	<b>C1INV:</b> Comparator 1 Output Inversion bit 1 = C1 output is inverted 0 = C1 output is not inverted
bit 3	<b>C2NEG:</b> Comparator 2 Negative Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to VIN- See <a href="#">Figure 22-1</a> for the Comparator modes.
bit 2	<b>C2POS:</b> Comparator 2 Positive Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to CVREF See <a href="#">Figure 22-1</a> for the Comparator modes.
bit 1	<b>C1NEG:</b> Comparator 1 Negative Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to VIN- See <a href="#">Figure 22-1</a> for the Comparator modes.
bit 0	<b>C1POS:</b> Comparator 1 Positive Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to CVREF See <a href="#">Figure 22-1</a> for the Comparator modes.

- Note 1:** If C2OUTEN = 1, the C2OUT peripheral output must be configured to an available RPn pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.
- 2:** If C1OUTEN = 1, the C1OUT peripheral output must be configured to an available RPn pin. See [Section 10.4 “Peripheral Pin Select \(PPS\)”](#) for more information.

# PIC24FJ64GA004 FAMILY

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NOTES:

## 23.0 COMPARATOR VOLTAGE REFERENCE

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, “Comparator Voltage Reference Module” (DS39709).

### 23.1 Configuring the Comparator Voltage Reference

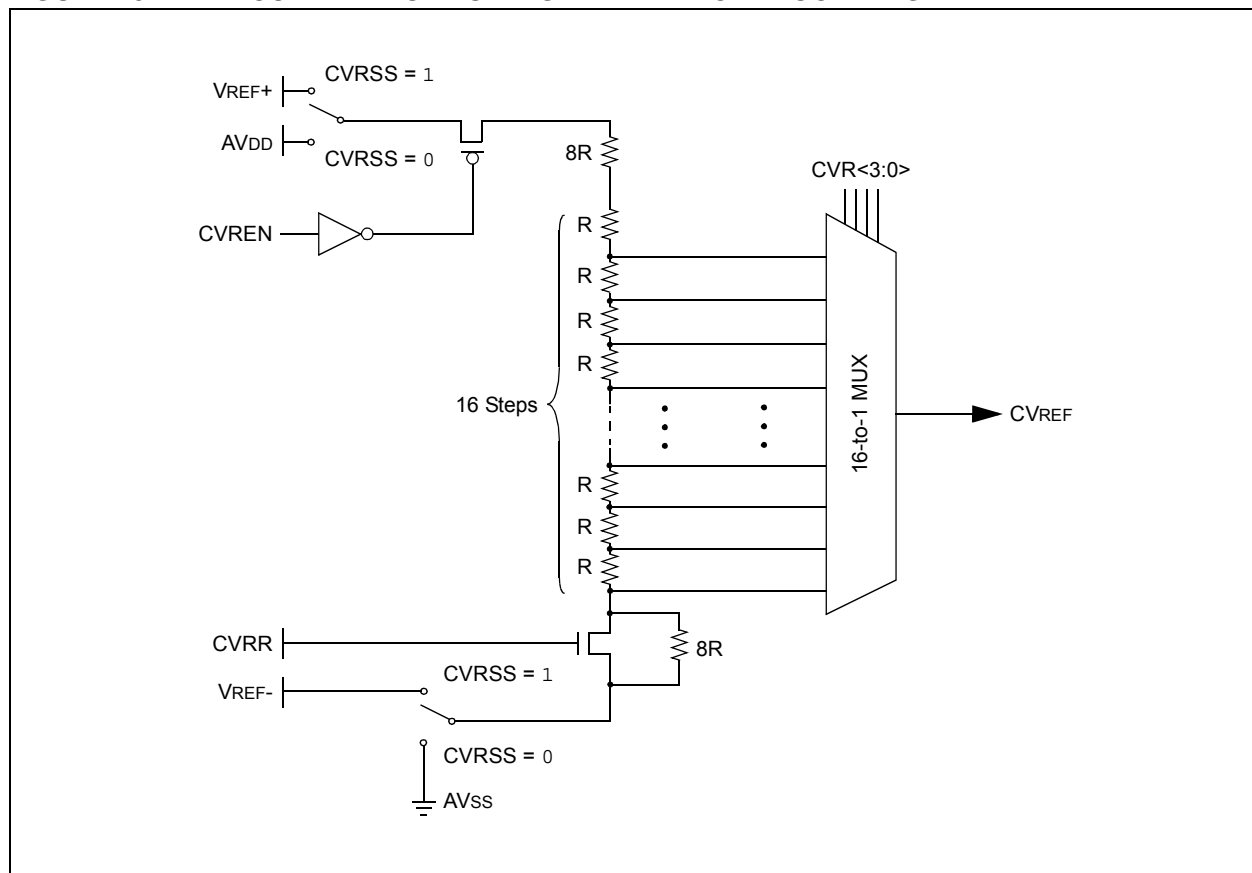
The comparator voltage reference module is controlled through the CVRCON register ([Register 23-1](#)). The comparator voltage reference provides two ranges of

output voltage, each with 16 distinct levels. The range to be used is selected by the CVRR bit (CVRCON<5>). The primary difference between the ranges is the size of the steps selected by the CVREF Selection bits (CVR<3:0>), with one range offering finer resolution.

The comparator reference supply voltage can come from either VDD and VSS, or the external VREF+ and VREF-. The voltage source is selected by the CVRSS bit (CVRCON<4>).

The settling time of the comparator voltage reference must be considered when changing the CVREF output.

**FIGURE 23-1: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM**



# PIC24FJ64GA004 FAMILY

## REGISTER 23-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **CVREN:** Comparator Voltage Reference Enable bit

1 = CVREF circuit is powered on

0 = CVREF circuit is powered down

bit 6 **CVROE:** Comparator VREF Output Enable bit

1 = CVREF voltage level is output on the CVREF pin

0 = CVREF voltage level is disconnected from the CVREF pin

bit 5 **CVRR:** Comparator VREF Range Selection bit

1 = CVRSRC range should be 0 to 0.625 CVRSRC with CVRSRC/24 step-size

0 = CVRSRC range should be 0.25 to 0.719 CVRSRC with CVRSRC/32 step-size

bit 4 **CVRSS:** Comparator VREF Source Selection bit

1 = Comparator reference source, CVRSRC = VREF+ – VREF-

0 = Comparator reference source, CVRSRC = AVDD – AVSS

bit 3-0 **CVR<3:0>:** Comparator VREF Value Selection  $0 \leq \text{CVR<3:0>} \leq 15$  bits

When CVRR = 1:

$\text{CVREF} = (\text{CVR<3:0>/24}) \cdot (\text{CVRSRC})$

When CVRR = 0:

$\text{CVREF} = 1/4 \cdot (\text{CVRSRC}) + (\text{CVR<3:0>/32}) \cdot (\text{CVRSRC})$



# PIC24FJ64GA004 FAMILY

## 24.0 SPECIAL FEATURES

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the following sections of the “PIC24F Family Reference Manual”:

- “**Watchdog Timer (WDT)**” (DS39697)
- “**High-Level Device Integration**” (DS39719)
- “**Programming and Diagnostics**” (DS39716)

PIC24FJ64GA004 family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming
- In-Circuit Emulation

### 24.1 Configuration Bits

The Configuration bits can be programmed (read as ‘0’), or left unprogrammed (read as ‘1’), to select various device configurations. These bits are mapped starting at program memory location, F80000h. A complete list of locations is shown in [Table 24-1](#). A detailed explanation of the various bit functions is provided in [Register 24-1](#) through [Register 24-4](#).

Note that address, F80000h, is beyond the user program memory space. In fact, it belongs to the configuration memory space (800000h-FFFFFFh), which can only be accessed using table reads and table writes.

#### 24.1.1 CONSIDERATIONS FOR CONFIGURING PIC24FJ64GA004 FAMILY DEVICES

In PIC24FJ64GA004 family devices, the configuration bytes are implemented as volatile memory. This means that configuration data must be programmed each time the device is powered up. Configuration data is stored in the two words at the top of the on-chip program memory space, known as the Flash Configuration Words. Their specific locations are shown in [Table 24-1](#). These are packed representations of the actual device Configuration bits, whose actual locations are distributed among five locations in configuration space. The configuration data is automatically loaded from the Flash Configuration Words to the proper Configuration registers during device Resets.

**Note:** Configuration data is reloaded on all types of device Resets.

**TABLE 24-1: FLASH CONFIGURATION WORD LOCATIONS FOR PIC24FJ64GA004 FAMILY DEVICES**

Device	Configuration Word Addresses	
	1	2
PIC24FJ16GA	002BFEh	002BFCh
PIC24FJ32GA	0057FEh	0057FCh
PIC24FJ48GA	0083FEh	0083FCh
PIC24FJ64GA	00ABFEh	00ABFCh

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration Word for configuration data. This is to make certain that program code is not stored in this address when the code is compiled.

The Configuration bits are reloaded from the Flash Configuration Word on any device Reset.

The upper byte of both Flash Configuration Words in program memory should always be ‘1111 1111’. This makes them appear to be NOP instructions in the remote event that their locations are ever executed by accident. Since Configuration bits are not implemented in the corresponding locations, writing ‘1’s to these locations has no effect on device operation.

# PIC24FJ64GA004 FAMILY

## REGISTER 24-1: CW1: FLASH CONFIGURATION WORD 1

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23							bit 16

r-x	R/PO-1	R/PO-1	R/PO-1	R/PO-1	r-1	R/PO-1	R/PO-1
r	JTAGEN	GCP	GWRP	DEBUG	r	ICS1	ICS0
bit 15							bit 8

R/PO-1	R/PO-1	r	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
FWDTEN	WINDIS	r	FWPSA	WDTPS3	WDTPS2	WDTPS1	WDTPS0
bit 7							bit 0

**Legend:** r = Reserved bit  
R = Readable bit PO = Program Once bit U = Unimplemented bit, read as '0'  
-n = Value when device is unprogrammed '1' = Bit is set '0' = Bit is cleared

- bit 23-16 **Unimplemented:** Read as '1'
- bit 15 **Reserved:** The value is unknown; program as '0'
- bit 14 **JTAGEN:** JTAG Port Enable bit
  - 1 = JTAG port is enabled
  - 0 = JTAG port is disabled
- bit 13 **GCP:** General Segment Program Memory Code Protection bit
  - 1 = Code protection is disabled
  - 0 = Code protection is enabled for the entire program memory space
- bit 12 **GWRP:** General Segment Code Flash Write Protection bit
  - 1 = Writes to program memory are allowed
  - 0 = Writes to program memory are disabled
- bit 11 **DEBUG:** Background Debugger Enable bit
  - 1 = Device resets into Operational mode
  - 0 = Device resets into Debug mode
- bit 10 **Reserved:** Always maintain as '1'
- bit 9-8 **ICS<1:0>:** Emulator Pin Placement Select bits
  - 11 = Emulator EMUC1/EMUD1 pins are shared with PGC1/PGD1
  - 10 = Emulator EMUC2/EMUD2 pins are shared with PGC2/PGD2
  - 01 = Emulator EMUC3/EMUD3 pins are shared with PGC3/PGD3
  - 00 = Reserved; do not use
- bit 7 **FWDTEN:** Watchdog Timer Enable bit
  - 1 = Watchdog Timer is enabled
  - 0 = Watchdog Timer is disabled
- bit 6 **WINDIS:** Windowed Watchdog Timer Disable bit
  - 1 = Standard Watchdog Timer is enabled
  - 0 = Windowed Watchdog Timer is enabled; FWDTEN must be '1'
- bit 5 **Reserved**
- bit 4 **FWPSA:** WDT Prescaler Ratio Select bit
  - 1 = Prescaler ratio of 1:128
  - 0 = Prescaler ratio of 1:32

## REGISTER 24-1: CW1: FLASH CONFIGURATION WORD 1 (CONTINUED)

bit 3-0      **WDTPS<3:0>**: Watchdog Timer Postscaler Select bits

1111 = 1:32,768  
1110 = 1:16,384  
1101 = 1:8,192  
1100 = 1:4,096  
1011 = 1:2,048  
1010 = 1:1,024  
1001 = 1:512  
1000 = 1:256  
0111 = 1:128  
0110 = 1:64  
0101 = 1:32  
0100 = 1:16  
0011 = 1:8  
0010 = 1:4  
0001 = 1:2  
0000 = 1:1

# PIC24FJ64GA004 FAMILY

## REGISTER 24-2: CW2: FLASH CONFIGURATION WORD 2

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23				bit 16			

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
IESO	WUTSEL1 <sup>(1)</sup>	WUTSEL0 <sup>(1)</sup>	SOSCSEL1 <sup>(1)</sup>	SOSCSEL0 <sup>(1)</sup>	FNOSC2	FNOSC1	FNOSC0
bit 15				bit 8			

R/PO-1	R/PO-1	R/PO-1	R/PO-1	r	R/PO-1	R/PO-1	R/PO-1
FCKSM1	FCKSM0	OSCIOFCN	IOL1WAY	r	I2C1SEL	POSCMD1	POSCMD0
bit 7				bit 0			

<b>Legend:</b>	r = Reserved bit
R = Readable bit	PO = Program Once bit
-n = Value when device is unprogrammed	U = Unimplemented bit, read as '0'
	'1' = Bit is set
	'0' = Bit is cleared

bit 23-16 **Unimplemented:** Read as '1'

bit 15 **IESO:** Internal External Switchover bit  
 1 = IESO mode (Two-Speed Start-up) is enabled  
 0 = IESO mode (Two-Speed Start-up) is disabled

bit 14-13 **WUTSEL<1:0>:** Voltage Regulator Standby Mode Wake-up Time Select bits<sup>(1)</sup>  
 11 = Default regulator start-up time is used  
 01 = Fast regulator start-up time is used  
 x0 = Reserved; do not use

bit 12-11 **SOSCSEL<1:0>:** Secondary Oscillator Power Mode Select bits<sup>(1)</sup>  
 11 = Default (High Drive Strength) mode  
 01 = Low-Power (Low Drive Strength) mode  
 x0 = Reserved; do not use

bit 10-8 **FNOSC<2:0>:** Initial Oscillator Select bits  
 111 = Fast RC Oscillator with Postscaler (FRCDIV)  
 110 = Reserved  
 101 = Low-Power RC Oscillator (LPRC)  
 100 = Secondary Oscillator (SOSC)  
 011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL)  
 010 = Primary Oscillator (XT, HS, EC)  
 001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL)  
 000 = Fast RC Oscillator (FRC)

bit 7-6 **FCKSM<1:0>:** Clock Switching and Fail-Safe Clock Monitor Configuration bits  
 1x = Clock switching and Fail-Safe Clock Monitor are disabled  
 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled  
 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled

bit 5 **OSCIOFCN:** OSCO Pin Configuration bit  
If POSCMD<1:0> = 11 or 00:  
 1 = OSCO/CLKO/RA3 functions as CLKO (Fosc/2)  
 0 = OSCO/CLKO/RA3 functions as port I/O (RA3)  
If POSCMD<1:0> = 10 or 01:  
 OSCIOFCN has no effect on OSCO/CLKO/RA3.

**Note 1:** These bits are implemented only in devices with a major silicon revision level of B or later (DEVREV register value is 3042h or greater). Refer to [Section 28.0 "Packaging Information"](#) in the device data sheet for the location and interpretation of product date codes.

# PIC24FJ64GA004 FAMILY

## REGISTER 24-2: CW2: FLASH CONFIGURATION WORD 2 (CONTINUED)

- bit 4      **IOL1WAY:** IOLOCK One-Way Set Enable bit  
           1 = The IOLOCK (OSCCON<6>) bit can be set once, provided the unlock sequence has been completed. Once set, the Peripheral Pin Select registers cannot be written to a second time.  
           0 = The IOLOCK (OSCCON<6>) bit can be set and cleared as needed, provided the unlock sequence has been completed
- bit 3      **Reserved**
- bit 2      **I2C1SEL:** I2C1 Pin Select bit  
           1 = Use default SCL1/SDA1 pins  
           0 = Use alternate SCL1/SDA1 pins
- bit 1-0    **POSCMD<1:0>:** Primary Oscillator Configuration bits  
           11 = Primary oscillator is disabled  
           10 = HS Oscillator mode is selected  
           01 = XT Oscillator mode is selected  
           00 = EC Oscillator mode is selected

**Note 1:** These bits are implemented only in devices with a major silicon revision level of B or later (DEVREV register value is 3042h or greater). Refer to [Section 28.0 “Packaging Information”](#) in the device data sheet for the location and interpretation of product date codes.

## REGISTER 24-3: DEVID: DEVICE ID REGISTER

U	U	U	U	U	U	U	U
—	—	—	—	—	—	—	—
bit 23							bit 16

U	U	R	R	R	R	R	R
—	—	FAMID7	FAMID6	FAMID5	FAMID4	FAMID3	FAMID2
bit 15							bit 8

R	R	R	R	R	R	R	R
FAMID1	FAMID0	DEV5	DEV4	DEV3	DEV2	DEV1	DEV0
bit 7							bit 0

**Legend:** R = Read-only bit      U = Unimplemented bit

- bit 23-14    **Unimplemented:** Read as ‘1’
- bit 13-6    **FAMID<7:0>:** Device Family Identifier bits  
           00010001 = PIC24FJ64GA004 family
- bit 5-0      **DEV<5:0>:** Individual Device Identifier bits  
           000100 = PIC24FJ16GA002  
           000101 = PIC24FJ32GA002  
           000110 = PIC24FJ48GA002  
           000111 = PIC24FJ64GA002  
           001100 = PIC24FJ16GA004  
           001101 = PIC24FJ32GA004  
           001110 = PIC24FJ48GA004  
           001111 = PIC24FJ64GA004

# PIC24FJ64GA004 FAMILY

## REGISTER 24-4: DEVREV: DEVICE REVISION REGISTER

U	U	U	U	U	U	U	U
—	—	—	—	—	—	—	—
bit 23							bit 16

U	U	U	U	U	U	U	R
—	—	—	—	—	—	—	MAJRV2
bit 15							bit 8

R	R	U	U	U	R	R	R
MAJRV1	MAJRV0	—	—	—	DOT2	DOT1	DOT0
bit 7							bit 0

<b>Legend:</b> R = Read-only bit	U = Unimplemented bit
----------------------------------	-----------------------

- bit 23-9      **Unimplemented:** Read as '0'
- bit 8-6      **MAJRV<2:0>:** Major Revision Identifier bits
- bit 5-3      **Unimplemented:** Read as '0'
- bit 2-0      **DOT<2:0>:** Minor Revision Identifier bits

# PIC24FJ64GA004 FAMILY

## 24.2 On-Chip Voltage Regulator

All of the PIC24FJ64GA004 family devices power their core digital logic at a nominal 2.5V. This may create an issue for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the PIC24FJ64GA004 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator is controlled by the DISVREG pin. Tying VSS to the pin enables the regulator, which in turn, provides power to the core from the other VDD pins. When the regulator is enabled, a low-ESR capacitor (such as ceramic) must be connected to the VDDCORE/VCAP pin (Figure 24-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in [Section 27.1 “DC Characteristics”](#).

If DISVREG is tied to VDD, the regulator is disabled. In this case, separate power for the core logic at a nominal 2.5V must be supplied to the device on the VDDCORE/VCAP pin to run the I/O pins at higher voltage levels, typically 3.3V. Alternatively, the VDDCORE/VCAP and VDD pins can be tied together to operate at a lower nominal voltage. Refer to Figure 24-1 for possible configurations.

### 24.2.1 VOLTAGE REGULATOR TRACKING MODE AND LOW-VOLTAGE DETECTION

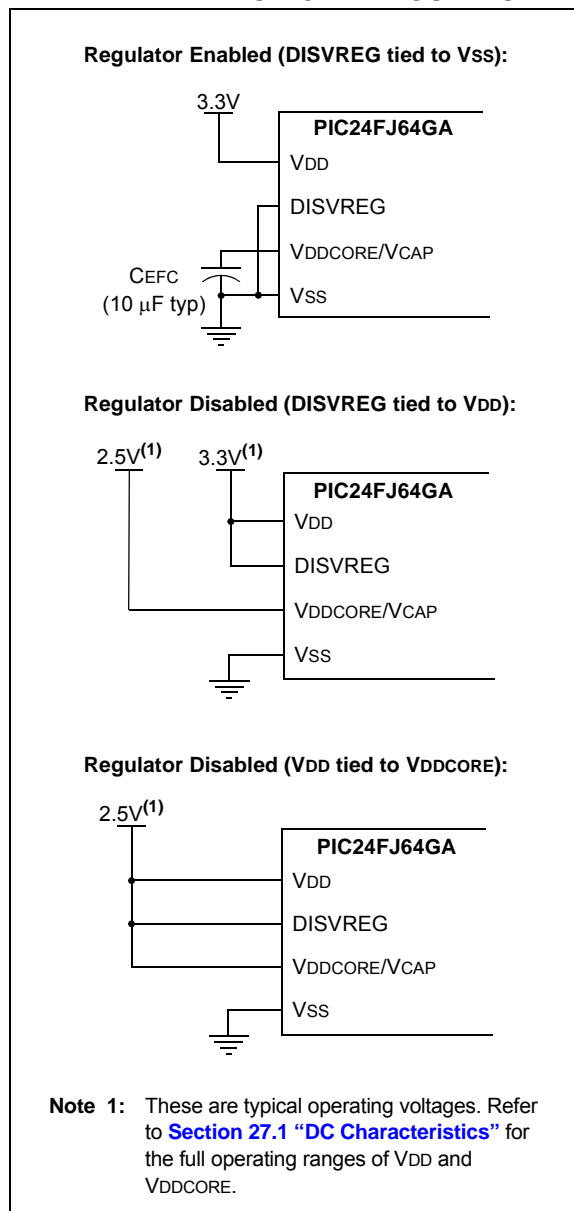
When it is enabled, the on-chip regulator provides a constant voltage of 2.5V nominal to the digital core logic.

The regulator can provide this level from a VDD of about 2.5V, all the way up to the device's VDDMAX. It does not have the capability to boost VDD levels below 2.5V. In order to prevent “brown out” conditions, when the voltage drops too low for the regulator, the regulator enters Tracking mode. In Tracking mode, the regulator output follows VDD, with a typical voltage drop of 100 mV.

When the device enters Tracking mode, it is no longer possible to operate at full speed. To provide information about when the device enters Tracking mode, the on-chip regulator includes a simple, Low-Voltage Detect (LVD) circuit. When VDD drops below full-speed operating voltage, the circuit sets the Low-Voltage Detect Interrupt Flag, LVDIF (IFS4<8>). This can be used to generate an interrupt and put the application into a low-power operational mode or trigger an orderly shutdown.

Low-Voltage Detection is only available when the regulator is enabled.

FIGURE 24-1: CONNECTIONS FOR THE ON-CHIP REGULATOR



### 24.2.2 ON-CHIP REGULATOR AND BOR

When the on-chip regulator is enabled, PIC24FJ64GA004 family devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain the tracking level, the regulator Reset circuitry will generate a Brown-out Reset. This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage levels are specified in [Section 27.1 “DC Characteristics”](#).

# PIC24FJ64GA004 FAMILY

## 24.2.3 ON-CHIP REGULATOR AND POR

When the voltage regulator is enabled, it takes approximately 10  $\mu$ s for it to generate output. During this time, designated as TVREG, code execution is disabled. TVREG is applied every time the device resumes operation after any power-down, including Sleep mode. TVREG is determined by the setting of the PMSLP bit (RCON<8>) and the WUTSELx Configuration bits (CW2<14:13>). For more information on TVREG, see [Section 27.0 “Electrical Characteristics”](#).

If the regulator is disabled, a separate Power-up Timer (PWRT) is automatically enabled. The PWRT adds a fixed delay of 64 ms nominal delay at device start-up (POR or BOR only). When waking up from Sleep with the regulator disabled, TVREG is used to determine the wake-up time. To decrease the device wake-up time when operating with the regulator disabled, the PMSLP bit can be set.

## 24.2.4 POWER-UP REQUIREMENTS

The on-chip regulator is designed to meet the power-up requirements for the device. If the application does not use the regulator, then strict power-up conditions must be adhered to. While powering up, VDDCORE must never exceed VDD by 0.3 volts.

**Note:** For more information, see [Section 27.0 “Electrical Characteristics”](#).

## 24.2.5 VOLTAGE REGULATOR STANDBY MODE

When enabled, the on-chip regulator always consumes a small incremental amount of current over IDD/IPD, including when the device is in Sleep mode, even though the core digital logic does not require power. To provide additional savings in applications where power resources are critical, the regulator automatically places itself into Standby mode whenever the device goes into Sleep mode. This feature is controlled by the PMSLP bit (RCON<8>). By default, this bit is cleared, which enables Standby mode.

For select PIC24FJ64GA004 family devices, the time required for regulator wake-up from Standby mode is controlled by the WUTSEL<1:0> Configuration bits (CW2<14:13>). The default wake-up time for all devices is 190  $\mu$ s. Where the WUTSELx Configuration bits are implemented, a fast wake-up option is also available. When WUTSEL<1:0> = 01, the regulator wake-up time is 25  $\mu$ s.

**Note:** This feature is implemented only on PIC24FJ64GA004 family devices with a major silicon revision level of B or later (DEVREV register value is 3042h or greater).

When the regulator's Standby mode is turned off (PMSLP = 1), Flash program memory stays powered in Sleep mode and the device can wake-up in less than 10  $\mu$ s. When PMSLP is set, the power consumption while in Sleep mode will be approximately 40  $\mu$ A higher than power consumption when the regulator is allowed to enter Standby mode.

## 24.3 Watchdog Timer (WDT)

For PIC24FJ64GA004 family devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

The nominal WDT clock source from LPRC is 31 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the FWPSA Configuration bit. With a 31 kHz input, the prescaler yields a nominal WDT Time-out period (TWDT) of 1 ms in 5-bit mode or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPS<3:0> Configuration bits (CW1<3:0>), which allow the selection of a total of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods, ranges from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSCx bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

If the WDT is enabled, it will continue to run during Sleep or Idle modes. When the WDT time-out occurs, the device will wake the device and code execution will continue from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bits (RCON<3:2>) will need to be cleared in software after the device wakes up.

The WDT Flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

**Note:** The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.





# PIC24FJ64GA004 FAMILY

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## 24.4 JTAG Interface

PIC24FJ64GA004 family devices implement a JTAG interface, which supports boundary scan device testing.

## 24.5 Program Verification and Code Protection

For all devices in the PIC24FJ64GA004 family, the on-chip program memory space is treated as a single block. Code protection for this block is controlled by one Configuration bit, GCP. This bit inhibits external reads and writes to the program memory space. It has no direct effect in normal execution mode.

Write protection is controlled by the GWRP bit in Configuration Word 1. When GWRP is programmed to '0', internal write and erase operations to program memory are blocked.

### 24.5.1 CONFIGURATION REGISTER PROTECTION

The Configuration registers are protected against inadvertent or unwanted changes, or reads in two ways. The primary protection method is the same as that of the RP registers – shadow registers contain a complimentary value which is constantly compared with the actual value.

To safeguard against unpredictable events, Configuration bit changes, resulting from individual cell level disruptions (such as ESD events), will cause a parity error and trigger a device Reset.

The data for the Configuration registers is derived from the Flash Configuration Words in program memory. When the GCP bit is set, the source data for device configuration is also protected as a consequence.

## 24.6 In-Circuit Serial Programming

PIC24FJ64GA004 family microcontrollers can be serially programmed while in the end application circuit. This is simply done with two lines for clock (PGCx) and data (PGDx), and three other lines for power, ground and the programming voltage. This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

## 24.7 In-Circuit Debugger

When MPLAB® ICD 2 is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the EMUCx (Emulation/Debug Clock) and EMUDx (Emulation/Debug Data) pins.

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, VSS, PGCx, PGDx and the EMUDx/EMUCx pin pair. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

## 25.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/  
MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for  
Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICKit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,  
Evaluation Kits and Starter Kits
- Third-party development tools

## 25.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

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## 25.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16, and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

## 25.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

## 25.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

## 25.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

## 25.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

## 25.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

## 25.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

## 25.9 PICkit 3 In-Circuit Debugger/Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

## 25.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

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## 25.11 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page ([www.microchip.com](http://www.microchip.com)) for the complete list of demonstration, development and evaluation kits.

## 25.12 Third-Party Development Tools

Microchip also offers a great collection of tools from third-party vendors. These tools are carefully selected to offer good value and unique functionality.

- Device Programmers and Gang Programmers from companies, such as SoftLog and CCS
- Software Tools from companies, such as Gimpel and Trace Systems
- Protocol Analyzers from companies, such as Saleae and Total Phase
- Demonstration Boards from companies, such as MikroElektronika, Digilent® and Olimex
- Embedded Ethernet Solutions from companies, such as EZ Web Lynx, WIZnet and IPLogika®

## 26.0 INSTRUCTION SET SUMMARY

**Note:** This chapter is a brief summary of the PIC24F Instruction Set Architecture (ISA) and is not intended to be a comprehensive reference source.

The PIC24F instruction set adds many enhancements to the previous PIC® MCU instruction sets, while maintaining an easy migration from previous PIC MCU instruction sets. Most instructions are a single program memory word. Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction. The instruction set is highly orthogonal and is grouped into four basic categories:

- Word or byte-oriented operations
- Bit-oriented operations
- Literal operations
- Control operations

Table 26-1 shows the general symbols used in describing the instructions. The PIC24F instruction set summary in Table 26-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand which is typically a register 'Wb' without any address modifier
- The second source operand which is typically a register 'Ws' with or without an address modifier
- The destination of the result which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- The file register specified by the value, 'f'
- The destination, which could either be the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register, 'Wb')

The literal instructions that involve data movement may use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by the value of 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand which is a register 'Wb' without any address modifier
- The second source operand which is a literal value
- The destination of the result (only if not the same as the first source operand) which is typically a register 'Wd' with or without an address modifier

The control instructions may use some of the following operands:

- A program memory address
- The mode of the table read and table write instructions

All instructions are a single word, except for certain double-word instructions, which were made double-word instructions so that all the required information is available in these 48 bits. In the second word, the 8 MSBs are '0's. If this second word is executed as an instruction (by itself), it will execute as a NOP.

Most single-word instructions are executed in a single instruction cycle, unless a conditional test is true or the Program Counter (PC) is changed as a result of the instruction. In these cases, the execution takes two instruction cycles, with the additional instruction cycle(s) executed as a NOP. Notable exceptions are the BRA (unconditional/computed branch), indirect CALL/GOTO, all table reads and writes, and RETURN/RETFIE instructions, which are single-word instructions but take two or three cycles.

Certain instructions that involve skipping over the subsequent instruction require either two or three cycles if the skip is performed, depending on whether the instruction being skipped is a single-word or two-word instruction. Moreover, double-word moves require two cycles. The double-word instructions execute in two instruction cycles.

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**TABLE 26-1: SYMBOLS USED IN OPCODE DESCRIPTIONS**

Field	Description
#text	Means literal defined by "text"
(text)	Means "content of text"
[text]	Means "the location addressed by text"
{ }	Optional field or operation
<n:m>	Register bit field
.b	Byte mode selection
.d	Double-Word mode selection
.S	Shadow register select
.w	Word mode selection (default)
bit4	4-bit bit selection field (used in word addressed instructions) $\in \{0...15\}$
C, DC, N, OV, Z	MCU Status bits: Carry, Digit Carry, Negative, Overflow, Sticky Zero
Expr	Absolute address, label or expression (resolved by the linker)
f	File register address $\in \{0000h...1FFFh\}$
lit1	1-bit unsigned literal $\in \{0,1\}$
lit4	4-bit unsigned literal $\in \{0...15\}$
lit5	5-bit unsigned literal $\in \{0...31\}$
lit8	8-bit unsigned literal $\in \{0...255\}$
lit10	10-bit unsigned literal $\in \{0...255\}$ for Byte mode, $\{0:1023\}$ for Word mode
lit14	14-bit unsigned literal $\in \{0...16384\}$
lit16	16-bit unsigned literal $\in \{0...65535\}$
lit23	23-bit unsigned literal $\in \{0...8388608\}$ ; LSB must be '0'
None	Field does not require an entry, may be blank
PC	Program Counter
Slit10	10-bit signed literal $\in \{-512...511\}$
Slit16	16-bit signed literal $\in \{-32768...32767\}$
Slit6	6-bit signed literal $\in \{-16...16\}$
Wb	Base W register $\in \{W0..W15\}$
Wd	Destination W register $\in \{Wd, [Wd], [Wd++] , [Wd--], [++Wd], [--Wd] \}$
Wdo	Destination W register $\in \{Wnd, [Wnd], [Wnd++] , [Wnd--], [++Wnd], [--Wnd], [Wnd+Wb] \}$
Wm,Wn	Dividend, Divisor working register pair (direct addressing)
Wn	One of 16 working registers $\in \{W0..W15\}$
Wnd	One of 16 destination working registers $\in \{W0..W15\}$
Wns	One of 16 source working registers $\in \{W0..W15\}$
WREG	W0 (working register used in file register instructions)
Ws	Source W register $\in \{Ws, [Ws], [Ws++] , [Ws--], [++Ws], [--Ws] \}$
Wso	Source W register $\in \{Wns, [Wns], [Wns++] , [Wns--], [++Wns], [--Wns], [Wns+Wb] \}$



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**TABLE 26-2: INSTRUCTION SET OVERVIEW**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
ADD	ADD f	$f = f + \text{WREG}$	1	1	C, DC, N, OV, Z
	ADD f, WREG	$\text{WREG} = f + \text{WREG}$	1	1	C, DC, N, OV, Z
	ADD #lit10, Wn	$\text{Wd} = \text{lit10} + \text{Wd}$	1	1	C, DC, N, OV, Z
	ADD Wb, Ws, Wd	$\text{Wd} = \text{Wb} + \text{Ws}$	1	1	C, DC, N, OV, Z
	ADD Wb, #lit5, Wd	$\text{Wd} = \text{Wb} + \text{lit5}$	1	1	C, DC, N, OV, Z
ADDC	ADDC f	$f = f + \text{WREG} + (\text{C})$	1	1	C, DC, N, OV, Z
	ADDC f, WREG	$\text{WREG} = f + \text{WREG} + (\text{C})$	1	1	C, DC, N, OV, Z
	ADDC #lit10, Wn	$\text{Wd} = \text{lit10} + \text{Wd} + (\text{C})$	1	1	C, DC, N, OV, Z
	ADDC Wb, Ws, Wd	$\text{Wd} = \text{Wb} + \text{Ws} + (\text{C})$	1	1	C, DC, N, OV, Z
	ADDC Wb, #lit5, Wd	$\text{Wd} = \text{Wb} + \text{lit5} + (\text{C})$	1	1	C, DC, N, OV, Z
AND	AND f	$f = f .\text{AND. WREG}$	1	1	N, Z
	AND f, WREG	$\text{WREG} = f .\text{AND. WREG}$	1	1	N, Z
	AND #lit10, Wn	$\text{Wd} = \text{lit10} .\text{AND. Wd}$	1	1	N, Z
	AND Wb, Ws, Wd	$\text{Wd} = \text{Wb} .\text{AND. Ws}$	1	1	N, Z
	AND Wb, #lit5, Wd	$\text{Wd} = \text{Wb} .\text{AND. lit5}$	1	1	N, Z
ASR	ASR f	$f = \text{Arithmetic Right Shift } f$	1	1	C, N, OV, Z
	ASR f, WREG	$\text{WREG} = \text{Arithmetic Right Shift } f$	1	1	C, N, OV, Z
	ASR Ws, Wd	$\text{Wd} = \text{Arithmetic Right Shift } \text{Ws}$	1	1	C, N, OV, Z
	ASR Wb, Wns, Wnd	$\text{Wnd} = \text{Arithmetic Right Shift } \text{Wb by } \text{Wns}$	1	1	N, Z
	ASR Wb, #lit4, Wnd	$\text{Wnd} = \text{Arithmetic Right Shift } \text{Wb by } \text{lit4}$	1	1	N, Z
BCLR	BCLR f, #bit4	Bit Clear f	1	1	None
	BCLR Ws, #bit4	Bit Clear Ws	1	1	None
BRA	BRA C, Expr	Branch if Carry	1	1 (2)	None
	BRA GE, Expr	Branch if Greater than or Equal	1	1 (2)	None
	BRA GEU, Expr	Branch if Unsigned Greater than or Equal	1	1 (2)	None
	BRA GT, Expr	Branch if Greater than	1	1 (2)	None
	BRA GTU, Expr	Branch if Unsigned Greater than	1	1 (2)	None
	BRA LE, Expr	Branch if Less than or Equal	1	1 (2)	None
	BRA LEU, Expr	Branch if Unsigned Less than or Equal	1	1 (2)	None
	BRA LT, Expr	Branch if Less than	1	1 (2)	None
	BRA LTU, Expr	Branch if Unsigned Less than	1	1 (2)	None
	BRA N, Expr	Branch if Negative	1	1 (2)	None
	BRA NC, Expr	Branch if Not Carry	1	1 (2)	None
	BRA NN, Expr	Branch if Not Negative	1	1 (2)	None
	BRA NOV, Expr	Branch if Not Overflow	1	1 (2)	None
	BRA NZ, Expr	Branch if Not Zero	1	1 (2)	None
	BRA OV, Expr	Branch if Overflow	1	1 (2)	None
	BRA Expr	Branch Unconditionally	1	2	None
	BRA Z, Expr	Branch if Zero	1	1 (2)	None
	BRA Wn	Computed Branch	1	2	None
BSET	BSET f, #bit4	Bit Set f	1	1	None
	BSET Ws, #bit4	Bit Set Ws	1	1	None
BSW	BSW.C Ws, Wb	Write C bit to Ws<Wb>	1	1	None
	BSW.Z Ws, Wb	Write Z bit to Ws<Wb>	1	1	None
BTG	BTG f, #bit4	Bit Toggle f	1	1	None
	BTG Ws, #bit4	Bit Toggle Ws	1	1	None
BTSC	BTSC f, #bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
	BTSC Ws, #bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None

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**TABLE 26-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
BTSS	BTSS $f, \#bit4$	Bit Test $f$ , Skip if Set	1	1 (2 or 3)	None
	BTSS $Ws, \#bit4$	Bit Test $Ws$ , Skip if Set	1	1 (2 or 3)	None
BTST	BTST $f, \#bit4$	Bit Test $f$	1	1	Z
	BTST.C $Ws, \#bit4$	Bit Test $Ws$ to C	1	1	C
	BTST.Z $Ws, \#bit4$	Bit Test $Ws$ to Z	1	1	Z
	BTST.C $Ws, Wb$	Bit Test $Ws < Wb >$ to C	1	1	C
	BTST.Z $Ws, Wb$	Bit Test $Ws < Wb >$ to Z	1	1	Z
BTSTS	BTSTS $f, \#bit4$	Bit Test then Set $f$	1	1	Z
	BTSTS.C $Ws, \#bit4$	Bit Test $Ws$ to C, then Set	1	1	C
	BTSTS.Z $Ws, \#bit4$	Bit Test $Ws$ to Z, then Set	1	1	Z
CALL	CALL $lit23$	Call Subroutine	2	2	None
	CALL $Wn$	Call Indirect Subroutine	1	2	None
CLR	CLR $f$	$f = 0x0000$	1	1	None
	CLR WREG	WREG = $0x0000$	1	1	None
	CLR $Ws$	$Ws = 0x0000$	1	1	None
CLRWDT	CLRWDT	Clear Watchdog Timer	1	1	WDTO, Sleep
COM	COM $f$	$f = \bar{f}$	1	1	N, Z
	COM $f, WREG$	WREG = $\bar{f}$	1	1	N, Z
	COM $Ws, Wd$	$Wd = \overline{Ws}$	1	1	N, Z
CP	CP $f$	Compare $f$ with WREG	1	1	C, DC, N, OV, Z
	CP $Wb, \#lit5$	Compare $Wb$ with $lit5$	1	1	C, DC, N, OV, Z
	CP $Wb, Ws$	Compare $Wb$ with $Ws$ ( $Wb - Ws$ )	1	1	C, DC, N, OV, Z
CP0	CP0 $f$	Compare $f$ with $0x0000$	1	1	C, DC, N, OV, Z
	CP0 $Ws$	Compare $Ws$ with $0x0000$	1	1	C, DC, N, OV, Z
CPB	CPB $f$	Compare $f$ with WREG, with Borrow	1	1	C, DC, N, OV, Z
	CPB $Wb, \#lit5$	Compare $Wb$ with $lit5$ , with Borrow	1	1	C, DC, N, OV, Z
	CPB $Wb, Ws$	Compare $Wb$ with $Ws$ , with Borrow ( $Wb - Ws - C$ )	1	1	C, DC, N, OV, Z
CPSEQ	CPSEQ $Wb, Wn$	Compare $Wb$ with $Wn$ , Skip if =	1	1 (2 or 3)	None
CPSGT	CPSGT $Wb, Wn$	Compare $Wb$ with $Wn$ , Skip if >	1	1 (2 or 3)	None
CPSLT	CPSLT $Wb, Wn$	Compare $Wb$ with $Wn$ , Skip if <	1	1 (2 or 3)	None
CPSNE	CPSNE $Wb, Wn$	Compare $Wb$ with $Wn$ , Skip if $\neq$	1	1 (2 or 3)	None
DAW	DAW.B $Wn$	$Wn =$ Decimal Adjust $Wn$	1	1	C
DEC	DEC $f$	$f = f - 1$	1	1	C, DC, N, OV, Z
	DEC $f, WREG$	WREG = $f - 1$	1	1	C, DC, N, OV, Z
	DEC $Ws, Wd$	$Wd = Ws - 1$	1	1	C, DC, N, OV, Z
DEC2	DEC2 $f$	$f = f - 2$	1	1	C, DC, N, OV, Z
	DEC2 $f, WREG$	WREG = $f - 2$	1	1	C, DC, N, OV, Z
	DEC2 $Ws, Wd$	$Wd = Ws - 2$	1	1	C, DC, N, OV, Z
DISI	DISI $\#lit14$	Disable Interrupts for $k$ Instruction Cycles	1	1	None
DIV	DIV.SW $Wm, Wn$	Signed 16/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.SD $Wm, Wn$	Signed 32/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.UW $Wm, Wn$	Unsigned 16/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.UD $Wm, Wn$	Unsigned 32/16-bit Integer Divide	1	18	N, Z, C, OV
EXCH	EXCH $Wns, Wnd$	Swap $Wns$ with $Wnd$	1	1	None
FBCL	FBCL $Ws, Wnd$	Find Bit Change from left (MSb) Side	1	1	None
FF1L	FF1L $Ws, Wnd$	Find First One from Left (MSb) Side	1	1	C
FF1R	FF1R $Ws, Wnd$	Find First One from Right (LSb) Side	1	1	C

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**TABLE 26-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
GOTO	GOTO Expr	Go to Address	2	2	None
	GOTO Wn	Go to Indirect	1	2	None
INC	INC f	$f = f + 1$	1	1	C, DC, N, OV, Z
	INC f, WREG	WREG = $f + 1$	1	1	C, DC, N, OV, Z
	INC Ws, Wd	Wd = Ws + 1	1	1	C, DC, N, OV, Z
INC2	INC2 f	$f = f + 2$	1	1	C, DC, N, OV, Z
	INC2 f, WREG	WREG = $f + 2$	1	1	C, DC, N, OV, Z
	INC2 Ws, Wd	Wd = Ws + 2	1	1	C, DC, N, OV, Z
IOR	IOR f	$f = f . \text{IOR. WREG}$	1	1	N, Z
	IOR f, WREG	WREG = $f . \text{IOR. WREG}$	1	1	N, Z
	IOR #lit10, Wn	Wd = lit10 . IOR. Wd	1	1	N, Z
	IOR Wb, Ws, Wd	Wd = Wb . IOR. Ws	1	1	N, Z
	IOR Wb, #lit5, Wd	Wd = Wb . IOR. lit5	1	1	N, Z
LNK	LNK #lit14	Link Frame Pointer	1	1	None
LSR	LSR f	$f = \text{Logical Right Shift } f$	1	1	C, N, OV, Z
	LSR f, WREG	WREG = Logical Right Shift f	1	1	C, N, OV, Z
	LSR Ws, Wd	Wd = Logical Right Shift Ws	1	1	C, N, OV, Z
	LSR Wb, Wns, Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N, Z
	LSR Wb, #lit4, Wnd	Wnd = Logical Right Shift Wb by lit4	1	1	N, Z
MOV	MOV f, Wn	Move f to Wn	1	1	None
	MOV [Wns+Slit10], Wnd	Move [Wns+Slit10] to Wnd	1	1	None
	MOV f	Move f to f	1	1	N, Z
	MOV f, WREG	Move f to WREG	1	1	None
	MOV #lit16, Wn	Move 16-bit Literal to Wn	1	1	None
	MOV.b #lit8, Wn	Move 8-bit Literal to Wn	1	1	None
	MOV Wn, f	Move Wn to f	1	1	None
	MOV Wns, [Wns+Slit10]	Move Wns to [Wns+Slit10]	1	1	None
	MOV Wso, Wdo	Move Ws to Wd	1	1	None
	MOV WREG, f	Move WREG to f	1	1	None
	MOV.D Wns, Wd	Move Double from W(ns):W(ns+1) to Wd	1	2	None
	MOV.D Ws, Wnd	Move Double from Ws to W(nd+1):W(nd)	1	2	None
MUL	MUL.SS Wb, Ws, Wnd	{Wnd+1, Wnd} = Signed(Wb) * Signed(Ws)	1	1	None
	MUL.SU Wb, Ws, Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(Ws)	1	1	None
	MUL.US Wb, Ws, Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Signed(Ws)	1	1	None
	MUL.UU Wb, Ws, Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(Ws)	1	1	None
	MUL.SU Wb, #lit5, Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(lit5)	1	1	None
	MUL.UU Wb, #lit5, Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(lit5)	1	1	None
	MUL f	W3:W2 = $f * \text{WREG}$	1	1	None
NEG	NEG f	$f = \bar{f} + 1$	1	1	C, DC, N, OV, Z
	NEG f, WREG	WREG = $\bar{f} + 1$	1	1	C, DC, N, OV, Z
	NEG Ws, Wd	Wd = $\overline{\text{Ws}} + 1$	1	1	C, DC, N, OV, Z
NOP	NOP	No Operation	1	1	None
	NOPR	No Operation	1	1	None
POP	POP f	Pop f from Top-of-Stack (TOS)	1	1	None
	POP Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
	POP.D Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd+1)	1	2	None
	POP.S	Pop Shadow Registers	1	1	All
PUSH	PUSH f	Push f to Top-of-Stack (TOS)	1	1	None
	PUSH Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
	PUSH.D Wns	Push W(ns):W(ns+1) to Top-of-Stack (TOS)	1	2	None
	PUSH.S	Push Shadow Registers	1	1	None

# PIC24FJ64GA004 FAMILY

**TABLE 26-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
PWRSV	PWRSV #lit1	Go into Sleep or Idle mode	1	1	WDTO, Sleep
RCALL	RCALL Expr	Relative Call	1	2	None
	RCALL Wn	Computed Call	1	2	None
REPEAT	REPEAT #lit14	Repeat Next Instruction lit14 + 1 times	1	1	None
	REPEAT Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
RESET	RESET	Software Device Reset	1	1	None
RETFIE	RETFIE	Return from Interrupt	1	3 (2)	None
RETLW	RETLW #lit10, Wn	Return with Literal in Wn	1	3 (2)	None
RETURN	RETURN	Return from Subroutine	1	3 (2)	None
RLC	RLC f	f = Rotate Left through Carry f	1	1	C, N, Z
	RLC f, WREG	WREG = Rotate Left through Carry f	1	1	C, N, Z
	RLC Ws, Wd	Wd = Rotate Left through Carry Ws	1	1	C, N, Z
RLNC	RLNC f	f = Rotate Left (No Carry) f	1	1	N, Z
	RLNC f, WREG	WREG = Rotate Left (No Carry) f	1	1	N, Z
	RLNC Ws, Wd	Wd = Rotate Left (No Carry) Ws	1	1	N, Z
RRC	RRC f	f = Rotate Right through Carry f	1	1	C, N, Z
	RRC f, WREG	WREG = Rotate Right through Carry f	1	1	C, N, Z
	RRC Ws, Wd	Wd = Rotate Right through Carry Ws	1	1	C, N, Z
RRNC	RRNC f	f = Rotate Right (No Carry) f	1	1	N, Z
	RRNC f, WREG	WREG = Rotate Right (No Carry) f	1	1	N, Z
	RRNC Ws, Wd	Wd = Rotate Right (No Carry) Ws	1	1	N, Z
SE	SE Ws, Wnd	Wnd = Sign-Extended Ws	1	1	C, N, Z
SETM	SETM f	f = FFFFh	1	1	None
	SETM WREG	WREG = FFFFh	1	1	None
	SETM Ws	Ws = FFFFh	1	1	None
SL	SL f	f = Left Shift f	1	1	C, N, OV, Z
	SL f, WREG	WREG = Left Shift f	1	1	C, N, OV, Z
	SL Ws, Wd	Wd = Left Shift Ws	1	1	C, N, OV, Z
	SL Wb, Wns, Wnd	Wnd = Left Shift Wb by Wns	1	1	N, Z
	SL Wb, #lit4, Wnd	Wnd = Left Shift Wb by lit4	1	1	N, Z
SUB	SUB f	f = f – WREG	1	1	C, DC, N, OV, Z
	SUB f, WREG	WREG = f – WREG	1	1	C, DC, N, OV, Z
	SUB #lit10, Wn	Wn = Wn – lit10	1	1	C, DC, N, OV, Z
	SUB Wb, Ws, Wd	Wd = Wb – Ws	1	1	C, DC, N, OV, Z
	SUB Wb, #lit5, Wd	Wd = Wb – lit5	1	1	C, DC, N, OV, Z
SUBB	SUBB f	f = f – WREG – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB f, WREG	WREG = f – WREG – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB #lit10, Wn	Wn = Wn – lit10 – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB Wb, Ws, Wd	Wd = Wb – Ws – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB Wb, #lit5, Wd	Wd = Wb – lit5 – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
SUBR	SUBR f	f = WREG – f	1	1	C, DC, N, OV, Z
	SUBR f, WREG	WREG = WREG – f	1	1	C, DC, N, OV, Z
	SUBR Wb, Ws, Wd	Wd = Ws – Wb	1	1	C, DC, N, OV, Z
	SUBR Wb, #lit5, Wd	Wd = lit5 – Wb	1	1	C, DC, N, OV, Z
SUBBR	SUBBR f	f = WREG – f – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR f, WREG	WREG = WREG – f – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR Wb, Ws, Wd	Wd = Ws – Wb – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR Wb, #lit5, Wd	Wd = lit5 – Wb – ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
SWAP	SWAP.b Wn	Wn = Nibble Swap Wn	1	1	None
	SWAP Wn	Wn = Byte Swap Wn	1	1	None

# PIC24FJ64GA004 FAMILY

**TABLE 26-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
TBLRDH	TBLRDH <i>Ws, Wd</i>	Read Prog<23:16> to Wd<7:0>	1	2	None
TBLRDL	TBLRDL <i>Ws, Wd</i>	Read Prog<15:0> to Wd	1	2	None
TBLWTH	TBLWTH <i>Ws, Wd</i>	Write Ws<7:0> to Prog<23:16>	1	2	None
TBLWTL	TBLWTL <i>Ws, Wd</i>	Write Ws to Prog<15:0>	1	2	None
ULNK	ULNK	Unlink Frame Pointer	1	1	None
XOR	XOR <i>f</i>	$f = f \text{ .XOR. WREG}$	1	1	N, Z
	XOR <i>f, WREG</i>	$WREG = f \text{ .XOR. WREG}$	1	1	N, Z
	XOR <i>#lit10, Wn</i>	$Wd = \text{lit10} \text{ .XOR. } Wd$	1	1	N, Z
	XOR <i>Wb, Ws, Wd</i>	$Wd = Wb \text{ .XOR. } Ws$	1	1	N, Z
	XOR <i>Wb, #lit5, Wd</i>	$Wd = Wb \text{ .XOR. lit5}$	1	1	N, Z
ZE	ZE <i>Ws, Wnd</i>	$Wnd = \text{Zero-Extend } Ws$	1	1	C, Z, N

# PIC24FJ64GA004 FAMILY

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NOTES:

# PIC24FJ64GA004 FAMILY

## 27.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of the PIC24FJ64GA004 family electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the PIC24FJ64GA004 family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these, or any other conditions above the parameters indicated in the operation listings of this specification, is not implied.

### Absolute Maximum Ratings<sup>(†)</sup>

Ambient temperature under bias .....	-40°C to +135°C
Storage temperature .....	-65°C to +150°C
Voltage on VDD with respect to VSS .....	-0.3V to +4.0V
Voltage on any combined analog and digital pin and MCLR, with respect to VSS .....	-0.3V to (VDD + 0.3V)
Voltage on any digital only pin with respect to VSS .....	-0.3V to +6.0V
Voltage on VDDCORE with respect to VSS .....	-0.3V to +3.0V
Maximum current out of VSS pin .....	300 mA
Maximum current into VDD pin ( <b>Note 1</b> ).....	250 mA
Maximum output current sunk by any I/O pin.....	25 mA
Maximum output current sourced by any I/O pin .....	25 mA
Maximum current sunk by all ports .....	200 mA
Maximum current sourced by all ports ( <b>Note 1</b> ).....	200 mA

**Note 1:** Maximum allowable current is a function of device maximum power dissipation (see [Table 27-1](#)).

† **NOTICE:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

# PIC24FJ64GA004 FAMILY

## 27.1 DC Characteristics

FIGURE 27-1: PIC24FJ64GA004 FAMILY VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)

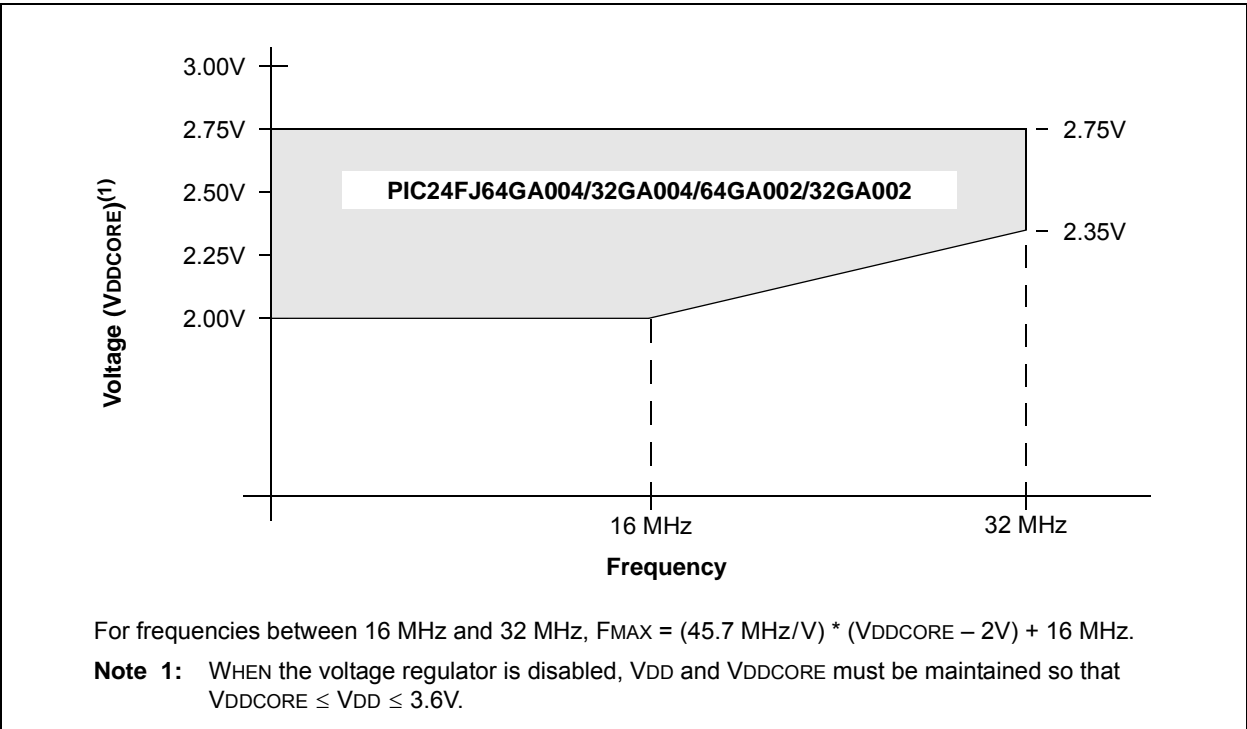
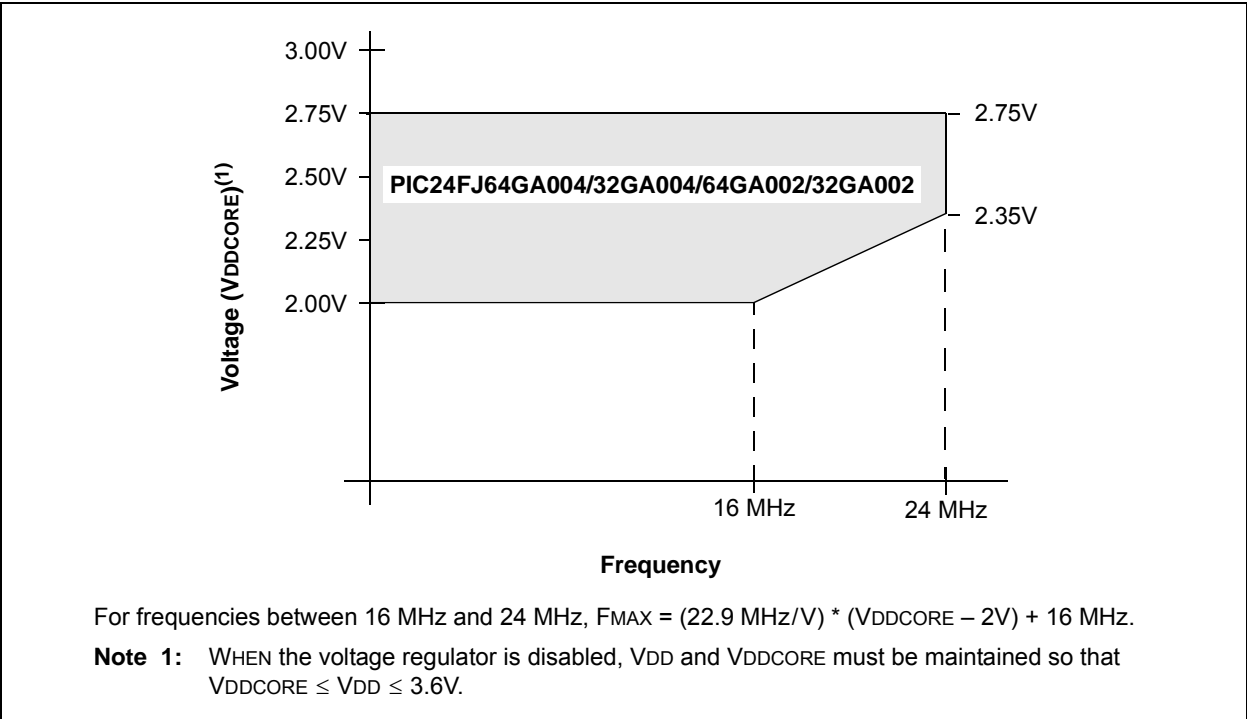


FIGURE 27-2: PIC24FJ64GA004 FAMILY VOLTAGE-FREQUENCY GRAPH (EXTENDED TEMPERATURE)





# PIC24FJ64GA004 FAMILY

**TABLE 27-1: THERMAL OPERATING CONDITIONS**

Rating	Symbol	Min	Typ	Max	Unit
PIC24FJ64GA004 Family:					
Operating Junction Temperature Range	T <sub>J</sub>	-40	—	+140	°C
Operating Ambient Temperature Range	T <sub>A</sub>	-40	—	+125	°C
Power Dissipation: Internal Chip Power Dissipation: $P_{INT} = V_{DD} \times (I_{DD} - \sum I_{OH})$ I/O Pin Power Dissipation: $P_{I/O} = \sum (\{V_{DD} - V_{OH}\} \times I_{OH}) + \sum (V_{OL} \times I_{OL})$	P <sub>D</sub>	P <sub>INT</sub> + P <sub>I/O</sub>			W
Maximum Allowed Power Dissipation	P <sub>DMAX</sub>	(T <sub>J</sub> – T <sub>A</sub> )/θ <sub>JA</sub>			W

**TABLE 27-2: THERMAL PACKAGING CHARACTERISTICS**

Characteristic	Symbol	Typ	Max	Unit	Notes
Package Thermal Resistance, 300 mil SOIC	θ <sub>JA</sub>	49	—	°C/W	(Note 1)
Package Thermal Resistance, 6x6x0.9 mm QFN	θ <sub>JA</sub>	33.7	—	°C/W	(Note 1)
Package Thermal Resistance, 8x8x1 mm QFN	θ <sub>JA</sub>	28	—	°C/W	(Note 1)
Package Thermal Resistance, 10x10x1 mm TQFP	θ <sub>JA</sub>	39.3	—	°C/W	(Note 1)

**Note 1:** Junction to ambient thermal resistance; Theta-JA (θ<sub>JA</sub>) numbers are achieved by package simulations.

# PIC24FJ64GA004 FAMILY

**TABLE 27-3: DC CHARACTERISTICS: TEMPERATURE AND VOLTAGE SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
<b>Operating Voltage</b>							
DC10	<b>Supply Voltage</b>						
	VDD		VBORMIN	—	3.6	V	Regulator enabled
	VDD		VDDCORE	—	3.6	V	Regulator disabled
	VDDCORE		2.0	—	2.75	V	Regulator disabled
DC12	VDR	<b>RAM Data Retention Voltage<sup>(2)</sup></b>	1.5	—	—	V	
DC16	VPOR	<b>VDD Start Voltage</b> to Ensure Internal Power-on Reset Signal	—	—	VSS	V	
DC17	SVDD	<b>VDD Rise Rate</b> to Ensure Internal Power-on Reset Signal	0.05	—	—	V/ms	0-3.3V in 0.1s 0-2.5V in 60 ms
DC18	VBOR	<b>Brown-out Reset Voltage</b>	1.8	2.1	2.2	V	

**Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** This is the limit to which VDD can be lowered without losing RAM data.

# PIC24FJ64GA004 FAMILY

**TABLE 27-4: DC CHARACTERISTICS: OPERATING CURRENT (IDD)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions	
Operating Current (I <sub>DD</sub> ): PMD Bits are Set <sup>(2)</sup>					
DC20	0.650	0.850	mA	-40°C	2.0V <sup>(3)</sup>  1 MIPS
DC20a	0.650	0.850	mA	+25°C	
DC20b	0.650	0.850	mA	+85°C	
DC20c	0.650	0.850	mA	+125°C	
DC20d	1.2	1.6	mA	-40°C	3.3V <sup>(4)</sup>  1 MIPS
DC20e	1.2	1.6	mA	+25°C	
DC20f	1.2	1.6	mA	+85°C	
DC20g	1.2	1.6	mA	+125°C	
DC23	2.6	3.4	mA	-40°C	2.0V <sup>(3)</sup>  4 MIPS
DC23a	2.6	3.4	mA	+25°C	
DC23b	2.6	3.4	mA	+85°C	
DC23c	2.6	3.4	mA	+125°C	
DC23d	4.1	5.4	mA	-40°C	3.3V <sup>(4)</sup>  4 MIPS
DC23e	4.1	5.4	mA	+25°C	
DC23f	4.1	5.4	mA	+85°C	
DC23g	4.1	5.4	mA	+125°C	
DC24	13.5	17.6	mA	-40°C	2.5V <sup>(3)</sup>  16 MIPS
DC24a	13.5	17.6	mA	+25°C	
DC24b	13.5	17.6	mA	+85°C	
DC24c	13.5	17.6	mA	+125°C	
DC24d	15	20	mA	-40°C	3.3V <sup>(4)</sup>  16 MIPS
DC24e	15	20	mA	+25°C	
DC24f	15	20	mA	+85°C	
DC24g	15	20	mA	+125°C	
DC31	13	17	μA	-40°C	2.0V <sup>(3)</sup>  LPRC (31 kHz)
DC31a	13	17	μA	+25°C	
DC31b	20	26	μA	+85°C	
DC31c	40	50	μA	+125°C	
DC31d	54	70	μA	-40°C	3.3V <sup>(4)</sup>  LPRC (31 kHz)
DC31e	54	70	μA	+25°C	
DC31f	95	124	μA	+85°C	
DC31g	120	260	μA	+125°C	

**Note 1:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows: OSC1 driven with external square wave from rail-to-rail. All I/O pins are configured as inputs and pulled to VDD.  
MCLR = VDD; WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating and all of the Peripheral Module Disable (PMD) bits are set.

**3:** On-chip voltage regulator is disabled (DISVREG tied to VDD).

**4:** On-chip voltage regulator is enabled (DISVREG tied to VSS). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.

# PIC24FJ64GA004 FAMILY

**TABLE 27-5: DC CHARACTERISTICS: IDLE CURRENT (I<sub>IDLE</sub>)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions	
Idle Current (IDLE): Core Off, Clock On Base Current, PMD Bits are Set <sup>(2)</sup>					
DC40	150	200	μA	-40°C	2.0V <sup>(3)</sup>  1 MIPS
DC40a	150	200	μA	+25°C	
DC40b	150	200	μA	+85°C	
DC40c	165	220	μA	+125°C	
DC40d	250	325	μA	-40°C	
DC40e	250	325	μA	+25°C	
DC40f	250	325	μA	+85°C	
DC40g	275	360	μA	+125°C	
DC43	0.55	0.72	mA	-40°C	2.0V <sup>(3)</sup>  4 MIPS
DC43a	0.55	0.72	mA	+25°C	
DC43b	0.55	0.72	mA	+85°C	
DC43c	0.60	0.8	mA	+125°C	
DC43d	0.82	1.1	mA	-40°C	
DC43e	0.82	1.1	mA	+25°C	
DC43f	0.82	1.1	mA	+85°C	
DC43g	0.91	1.2	mA	+125°C	
DC47	3	4	mA	-40°C	2.5V <sup>(3)</sup>  3.3V <sup>(4)</sup>  16 MIPS
DC47a	3	4	mA	+25°C	
DC47b	3	4	mA	+85°C	
DC47c	3.3	4.4	mA	+125°C	
DC47d	3.5	4.6	mA	-40°C	
DC47e	3.5	4.6	mA	+25°C	
DC47f	3.5	4.6	mA	+85°C	
DC47g	3.9	5.1	mA	+125°C	
DC50	0.85	1.1	mA	-40°C	2.0V <sup>(3)</sup>  3.3V <sup>(4)</sup>  FRC (4 MIPS)
DC50a	0.85	1.1	mA	+25°C	
DC50b	0.85	1.1	mA	+85°C	
DC50c	0.94	1.2	mA	+125°C	
DC50d	1.2	1.6	mA	-40°C	
DC50e	1.2	1.6	mA	+25°C	
DC50f	1.2	1.6	mA	+85°C	
DC50g	1.3	1.8	mA	+125°C	

**Note 1:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** The test conditions for all I<sub>IDLE</sub> measurements are as follows: OSC<sub>I</sub> driven with external square wave from rail-to-rail. All I/O pins are configured as inputs and pulled to V<sub>DD</sub>. MCLR = V<sub>DD</sub>; WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating and all of the Peripheral Module Disable (PMD) bits are set.

**3:** On-chip voltage regulator is disabled (DISVREG tied to V<sub>DD</sub>).

**4:** On-chip voltage regulator is enabled (DISVREG tied to V<sub>SS</sub>). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.

# PIC24FJ64GA004 FAMILY

**TABLE 27-5: DC CHARACTERISTICS: IDLE CURRENT (I<sub>IDLE</sub>) (CONTINUED)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)	
			Operating temperature	-40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions
<b>Idle Current (I<sub>IDLE</sub>): Core Off, Clock On Base Current, PMD Bits are Set<sup>(2)</sup></b>				
DC51	4	6	μA	-40°C
DC51a	4	6	μA	+25°C
DC51b	8	16	μA	+85°C
DC51c	20	50	μA	+125°C
DC51d	42	55	μA	-40°C
DC51e	42	55	μA	+25°C
DC51f	70	91	μA	+85°C
DC51g	100	180	μA	+125°C

**Note 1:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** The test conditions for all I<sub>IDLE</sub> measurements are as follows: OSC<sub>I</sub> driven with external square wave from rail-to-rail. All I/O pins are configured as inputs and pulled to V<sub>DD</sub>. MCLR = V<sub>DD</sub>; WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating and all of the Peripheral Module Disable (PMD) bits are set.

**3:** On-chip voltage regulator is disabled (DISVREG tied to V<sub>DD</sub>).

**4:** On-chip voltage regulator is enabled (DISVREG tied to V<sub>SS</sub>). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.

# PIC24FJ64GA004 FAMILY

**TABLE 27-6: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions	
Power-Down Current (IPD): PMD Bits are Set, PMSLP Bit is '0' <sup>(2)</sup>					
DC60	0.1	1	μA	-40°C	Base Power-Down Current <sup>(5)</sup>
DC60a	0.15	1	μA	+25°C	
DC60m	2.2	7.4	μA	+60°C	
DC60b	3.7	12	μA	+85°C	
DC60j	15	50	μA	+125°C	
DC60c	0.2	1	μA	-40°C	
DC60d	0.25	1	μA	+25°C	
DC60n	2.6	15	μA	+60°C	
DC60e	4.2	25	μA	+85°C	
DC60k	16	100	μA	+125°C	
DC60f	3.3	9	μA	-40°C	
DC60g	3.5	10	μA	+25°C	
DC60o	6.7	22	μA	+60°C	
DC60h	9	30	μA	+85°C	
DC60l	36	120	μA	+125°C	
DC61	1.75	3	μA	-40°C	Watchdog Timer Current: ΔI <sub>WDT</sub> <sup>(5)</sup>
DC61a	1.75	3	μA	+25°C	
DC61m	1.75	3	μA	+60°C	
DC61b	1.75	3	μA	+85°C	
DC61j	3.5	6	μA	+125°C	
DC61c	2.4	4	μA	-40°C	
DC61d	2.4	4	μA	+25°C	
DC61n	2.4	4	μA	+60°C	
DC61e	2.4	4	μA	+85°C	
DC61k	4.8	8	μA	+125°C	
DC61f	2.8	5	μA	-40°C	
DC61g	2.8	5	μA	+25°C	
DC61o	2.8	5	μA	+60°C	
DC61h	2.8	5	μA	+85°C	
DC61l	5.6	10	μA	+125°C	

**Note 1:** Data in the Typical column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled high. WDT, etc., are all switched off.

**3:** On-chip voltage regulator is disabled (DISVREG tied to VDD).

**4:** On-chip voltage regulator is enabled (DISVREG tied to VSS). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.

**5:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.

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**TABLE 27-6: DC CHARACTERISTICS: POWER-DOWN CURRENT (I<sub>PD</sub>) (CONTINUED)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)		
			Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions	
Power-Down Current (IPD): PMD Bits are Set, PMSLP Bit is '0' <sup>(2)</sup>					
DC62	8	16	μA	-40°C	RTCC + Timer1 w/32 kHz Crystal: ΔRTCC, ΔIT132 <sup>(5)</sup>
DC62a	12	16	μA	+25°C	
DC62m	12	16	μA	+60°C	
DC62b	12	16	μA	+85°C	
DC62j	18	23	μA	+125°C	
DC62c	9	16	μA	-40°C	
DC62d	12	16	μA	+25°C	
DC62n	12	16	μA	+60°C	
DC62e	12.5	16	μA	+85°C	
DC62k	20	25	μA	+125°C	
DC62f	10.3	18	μA	-40°C	
DC62g	13.4	18	μA	+25°C	
DC62o	14.0	18	μA	+60°C	
DC62h	14.2	18	μA	+85°C	
DC62l	23	28	μA	+125°C	
DC63	2	—	μA	-40°C	RTCC + Timer1 w/Low-Power 32 kHz Crystal (SOCSEL<1:0> = 01): ΔRTCC, ΔIT132 <sup>(5)</sup>
DC63a	2	—	μA	+25°C	
DC63b	6	—	μA	+85°C	
DC63c	2	—	μA	-40°C	
DC63d	2	—	μA	+25°C	
DC63e	7	—	μA	+85°C	
DC63f	2	—	μA	-40°C	
DC63g	3	—	μA	+25°C	
DC63h	7	—	μA	+85°C	

**Note 1:** Data in the Typical column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

- 2:** Base I<sub>PD</sub> is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled high. WDT, etc., are all switched off.
- 3:** On-chip voltage regulator is disabled (DISVREG tied to V<sub>DD</sub>).
- 4:** On-chip voltage regulator is enabled (DISVREG tied to V<sub>SS</sub>). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.
- 5:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base I<sub>PD</sub> current.

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**TABLE 27-7: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI10 DI11 DI15 DI16 DI17 DI18 DI19	V <sub>IL</sub>	<b>Input Low Voltage<sup>(4)</sup></b>					
		I/O Pins	V <sub>SS</sub>	—	0.2 V <sub>DD</sub>	V	PMPTTL = 1
		PMP Pins	V <sub>SS</sub>	—	0.15 V <sub>DD</sub>	V	
		MCLR	V <sub>SS</sub>	—	0.2 V <sub>DD</sub>	V	
		OSCI (XT mode)	V <sub>SS</sub>	—	0.2 V <sub>DD</sub>	V	
		OSCI (HS mode)	V <sub>SS</sub>	—	0.2 V <sub>DD</sub>	V	SMBus disabled
		I/O Pins with I <sup>2</sup> C™ Buffer	V <sub>SS</sub>	—	0.3 V <sub>DD</sub>	V	
		I/O Pins with SMBus Buffer	V <sub>SS</sub>	—	0.8	V	SMBus enabled
DI20 DI21 DI25 DI26 DI27 DI28 DI29	V <sub>IH</sub>	<b>Input High Voltage<sup>(4)</sup></b>					
		I/O Pins:					PMPTTL = 1
		with Analog Functions	0.8 V <sub>DD</sub>	—	V <sub>DD</sub>	V	
		Digital Only	0.8 V <sub>DD</sub>	—	5.5	V	
		PMP Pins:					
		with Analog Functions	0.25 V <sub>DD</sub> + 0.8	—	V <sub>DD</sub>	V	PMPTTL = 1
		Digital Only	0.25 V <sub>DD</sub> + 0.8	—	5.5	V	
		MCLR	0.8 V <sub>DD</sub>	—	V <sub>DD</sub>	V	
		OSCI (XT mode)	0.7 V <sub>DD</sub>	—	V <sub>DD</sub>	V	
		OSCI (HS mode)	0.7 V <sub>DD</sub>	—	V <sub>DD</sub>	V	2.5V ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub>
		I/O Pins with I <sup>2</sup> C Buffer:					
		with Analog Functions	0.7 V <sub>DD</sub>	—	V <sub>DD</sub>	V	
		Digital Only	0.7 V <sub>DD</sub>	—	5.5	V	
DI29		I/O Pins with SMBus Buffer:					
		with Analog Functions	2.1	—	V <sub>DD</sub>	V	
		Digital Only	2.1	—	5.5	V	
DI30	ICNPU	<b>CNxx Pull-up Current</b>	50	250	400	μA	V <sub>DD</sub> = 3.3V, V <sub>PIN</sub> = V <sub>SS</sub>

- Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.
- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** Refer to [Table 1-2](#) for I/O pin buffer types.
- 5:** Parameter is characterized but not tested.
- 6:** Non-5V tolerant pins, V<sub>IH</sub> source > (V<sub>DD</sub> + 0.3), 5V tolerant pins V<sub>IH</sub> source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources greater than 5.5V.
- 8:** Injection currents > | 0 | can affect the performance of all analog peripherals (e.g., A/D, comparators, internal band gap reference, etc.)
- 9:** Any number and/or combination of I/O pins not excluded under I<sub>ICL</sub> or I<sub>ICH</sub> conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.



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**TABLE 27-7: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI31	IPU	Maximum Load Current for Digital High Detection with Internal Pull-up	—	—	30	μA	VDD = 2.0V
			—	—	100	μA	VDD = 3.3V
DI50	IIL	Input Leakage Current <sup>(2,3)</sup> I/O Ports	—	—	±1	μA	VSS ≤ VPIN ≤ VDD, Pin at high-impedance
DI51		Analog Input Pins	—	—	±1	μA	VSS ≤ VPIN ≤ VDD, Pin at high-impedance
DI55		MCLR	—	—	±1	μA	VSS ≤ VPIN ≤ VDD
DI56		OSCI	—	—	±1	μA	VSS ≤ VPIN ≤ VDD, XT and HS modes
DI60a	IICL	Input Low Injection Current	0	—	-5 <sup>(5,8)</sup>	mA	All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP, RB11, SOSCI, SOSCO, D+, D-, VUSB, and VBUS
DI60b	IICH	Input High Injection Current	0	—	+5 <sup>(6,7,8)</sup>	mA	All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP, RB11, SOSCI, SOSCO, D+, D-, VUSB, and VBUS, and all 5V tolerant pins <sup>(7)</sup>
DI60c	ΣICT	Total Input Injection Current (sum of all I/O and control pins)	-20 <sup>(9)</sup>	—	+20 <sup>(9)</sup>	mA	Absolute instantaneous sum of all ± input injection currents from all I/O pins (  IICL   +   IICH  ) ≤ ΣICT

- Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.
- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** Refer to [Table 1-2](#) for I/O pin buffer types.
- 5:** Parameter is characterized but not tested.
- 6:** Non-5V tolerant pins, VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources greater than 5.5V.
- 8:** Injection currents > | 0 | can affect the performance of all analog peripherals (e.g., A/D, comparators, internal band gap reference, etc.)
- 9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

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**TABLE 27-8: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO10   DO16	VOL	<b>Output Low Voltage</b> All I/O Pins	—	—	0.4	V	IOL = 8.5 mA, VDD = 3.6V
			—	—	0.4	V	IOL = 5.0 mA, VDD = 2.0V
			—	—	0.4	V	IOL = 8.0 mA, VDD = 3.6V, +125°C
			—	—	0.4	V	IOL = 4.5 mA, VDD = 2.0V, +125°C
DO20   DO26	VOH	<b>Output High Voltage</b> All I/O Pins	3	—	—	V	IOH = -3.0 mA, VDD = 3.6V
			1.65	—	—	V	IOH = -1.0 mA, VDD = 2.0V
			3	—	—	V	IOH = -2.5 mA, VDD = 3.6V, +125°C
			1.65	—	—	V	IOH = -0.5 mA, VDD = 2.0V, +125°C

**Note 1:** Data in "Typ" column is at +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**TABLE 27-9: DC CHARACTERISTICS: PROGRAM MEMORY**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
<b>Program Flash Memory</b>							
D130	EP	Cell Endurance	10000	—	—	E/W	-40°C to +125°C
D131	VPR	VDD for Read	VMIN	—	3.6	V	VMIN = Minimum operating voltage
D132B	VPEW	VDDCORE for Self-Timed Write	2.25	—	2.75	V	
D133A	TIW	Self-Timed Write Cycle Time	—	3	—	ms	
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated
D135	IDDP	Supply Current during Programming	—	7	—	mA	

**Note 1:** Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.

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**TABLE 27-10: COMPARATOR SPECIFICATIONS**

Operating Conditions: 2.0V < VDD < 3.6V, -40°C < TA < +85°C (unless otherwise stated)							
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Comments
D300	VIOFF	Input Offset Voltage*	—	10	30	mV	
D301	VICM	Input Common-Mode Voltage*	0	—	VDD	V	
D302	CMRR	Common-Mode Rejection Ratio*	55	—	—	dB	
300	TRESP	Response Time*(1)	—	150	400	ns	
301	TMC2OV	Comparator Mode Change to Output Valid*	—	—	10	μs	

\* Parameters are characterized but not tested.

**Note 1:** Response time is measured with one comparator input at (VDD – 1.5)/2, while the other input transitions from VSS to VDD.

**TABLE 27-11: COMPARATOR VOLTAGE REFERENCE SPECIFICATIONS**

Operating Conditions: 2.0V < VDD < 3.6V, -40°C < TA < +85°C (unless otherwise stated)							
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Comments
VRD310	CVRES	Resolution	VDD/24	—	VDD/32	LSb	
VRD311	CVRAA	Absolute Accuracy	—	—	1	LSb	
VRD312	CVRUR	Unit Resistor Value (R)	—	2k	—	Ω	
VR310	TSET	Settling Time(1)	—	—	10	μs	

**Note 1:** Settling time is measured while CVRR = 1 and the CVR<3:0> bits transition from '0000' to '1111'.

**TABLE 27-12: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS**

Operating Conditions: -40°C < TA < +125°C (unless otherwise stated)							
Param No.	Symbol	Characteristics	Min	Typ	Max	Units	Comments
	VRGOUT	Regulator Output Voltage	—	2.5	—	V	
	VBG	Band Gap Reference Voltage	—	1.2	—	V	
	CEFC	External Filter Capacitor Value	4.7	10	—	μF	Series resistance < 3 Ohm recommended; < 5 Ohm required
	TVREG	Voltage Regulator Start-up Time	—	10	—	μs	POR, BOR or when PMSLP = 1
			—	25	—	μs	PMSLP = 0, WUTSEL<1:0> = 01(1)
			—	190	—	μs	PMSLP = 0, WUTSEL<1:0> = 11(2)
	TPWRT		—	64	—	ms	DISVREG = VDD

**Note 1:** Available only in devices with a major silicon revision level of B or later (DEVREV register value is 3042h or greater).

**2:** WUTSELx Configuration bits setting is applicable only in devices with a major silicon revision level of B or later. This specification also applies to all devices prior to Revision Level B whenever PMSLP = 0.

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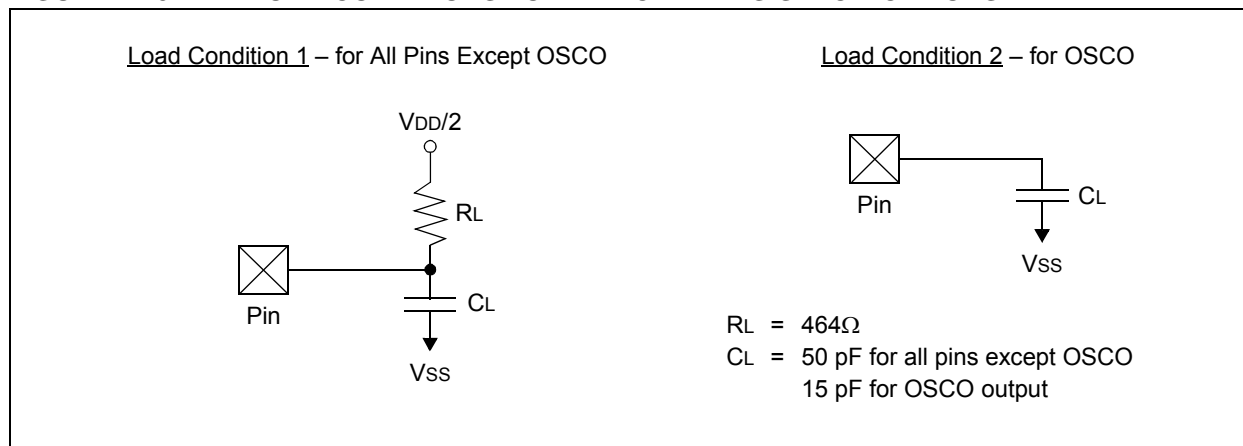
## 27.2 AC Characteristics and Timing Parameters

The information contained in this section defines the PIC24FJ64GA004 family AC characteristics and timing parameters.

**TABLE 27-13: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

AC CHARACTERISTICS	<b>Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)</b>	
	Operating temperature	-40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended
	Operating voltage VDD range as described in	<a href="#">Section 27.1 “DC Characteristics”</a> .

**FIGURE 27-3: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



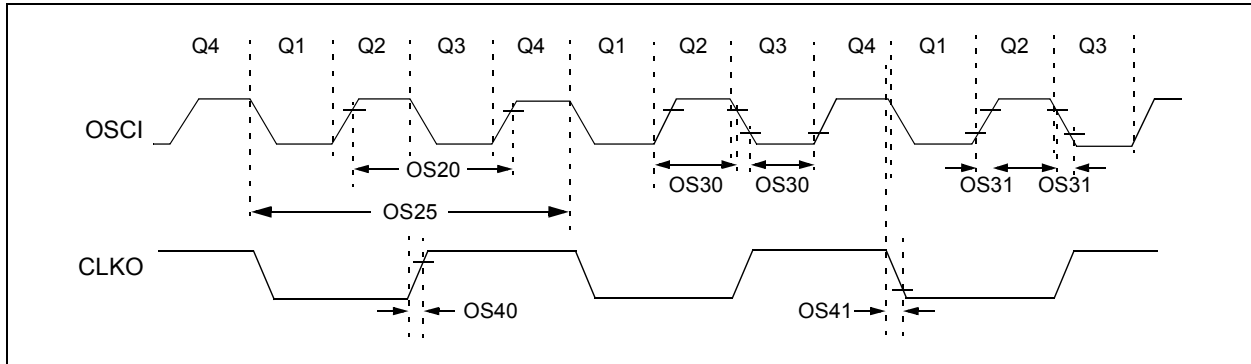
**TABLE 27-14: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO50	Cosc2	OSCO/CLKO Pin	—	—	15	pF	In XT and HS modes when external clock is used to drive OSCI
DO56	Cio	All I/O Pins and OSCO	—	—	50	pF	EC mode
DO58	Cb	SCLx, SDAx	—	—	400	pF	In I <sup>2</sup> C™ mode

**Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

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**FIGURE 27-4: EXTERNAL CLOCK TIMING**



**TABLE 27-15: EXTERNAL CLOCK TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0 to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
OS10	Fosc	External CLKI Frequency (External clocks allowed only in EC mode)	DC	—	32	MHz	EC, -40°C ≤ TA ≤ +85°C
			4	—	8	MHz	ECPLL, -40°C ≤ TA ≤ +85°C
			DC	—	24	MHz	EC, -40°C ≤ TA ≤ +125°C
			4	—	6	MHz	ECPLL, -40°C ≤ TA ≤ +125°C
		Oscillator Frequency	3	—	10	MHz	XT
			3	—	8	MHz	XTPLL, -40°C ≤ TA ≤ +85°C
			10	—	32	MHz	HS, -40°C ≤ TA ≤ +85°C
			31	—	33	kHz	SOSC
			3	—	6	MHz	XTPLL, -40°C ≤ TA ≤ +125°C
			10	—	24	MHz	HS, -40°C ≤ TA ≤ +125°C
OS20	Tosc	Tosc = 1/Fosc	—	—	—	—	See Parameter OS10 for Fosc value
OS25	Tcy	Instruction Cycle Time <sup>(2)</sup>	62.5	—	DC	ns	
OS30	TosL, TosH	External Clock In (OSCI) High or Low Time	0.45 x Tosc	—	—	ns	EC
OS31	TosR, TosF	External Clock In (OSCI) Rise or Fall Time	—	—	20	ns	EC
OS40	TckR	CLKO Rise Time <sup>(3)</sup>	—	6	10	ns	
OS41	TckF	CLKO Fall Time <sup>(3)</sup>	—	6	10	ns	

**Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** Instruction cycle period (Tcy) equals two times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type, under standard operating conditions, with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at “Min.” values with an external clock applied to the OSCI/CLKI pin. When an external clock input is used, the “Max.” cycle time limit is “DC” (no clock) for all devices.

**3:** Measurements are taken in EC mode. The CLKO signal is measured on the OSCO pin. CLKO is low for the Q1-Q2 period (1/2 Tcy) and high for the Q3-Q4 period (1/2 Tcy).

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**TABLE 27-16: PLL CLOCK TIMING SPECIFICATIONS (V<sub>DD</sub> = 2.0V TO 3.6V)**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
OS50	FPLLI	PLL Input Frequency Range	3	—	8	MHz	ECPLL, HSPLL, XTPLL modes, -40°C ≤ TA ≤ +85°C
			3	—	6	MHz	ECPLL, HSPLL, XTPLL modes, -40°C ≤ TA ≤ +125°C
OS51	FSYS	PLL Output Frequency Range	8	—	32	MHz	-40°C ≤ TA ≤ +85°C
			8	—	24	MHz	-40°C ≤ TA ≤ +125°C
OS52	TLOCK	PLL Start-up Time (Lock Time)	—	—	2	ms	
OS53	DCLK	CLKO Stability (Jitter)	-2	1	2	%	Measured over 100 ms period

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**TABLE 27-17: INTERNAL RC OSCILLATOR SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions
	TFRC	FRC Start-up Time	—	15	—	μs	
	TLPRC	LPRC Start-up Time	—	40	—	μs	

**TABLE 27-18: AC CHARACTERISTICS: INTERNAL RC ACCURACY**

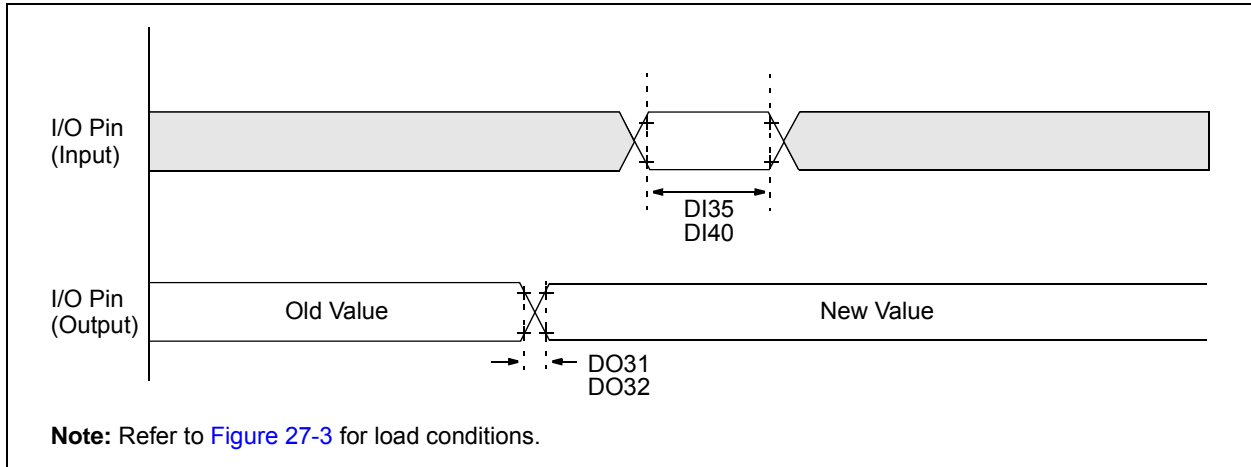
AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
F20	Internal FRC @ 8 MHz <sup>(1)</sup>	-2	—	2	%	+25°C	3.0V ≤ V <sub>DD</sub> ≤ 3.6V
		-5	—	5	%	-40°C ≤ TA ≤ +85°C	
		-7	—	7	%	+125°C	
F21	LPRC @ 31 kHz <sup>(2)</sup>	-15	—	15	%	+25°C	3.0V ≤ V <sub>DD</sub> ≤ 3.6V
		-15	—	15	%	-40°C ≤ TA ≤ +85°C	
		-30	—	30	%	+125°C	

**Note 1:** Frequency calibrated at +25°C and 3.3V. OSCTUN bits can be used to compensate for temperature drift.

**2:** Change of LPRC frequency as V<sub>DD</sub> changes.

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**FIGURE 27-5: CLKO AND I/O TIMING CHARACTERISTICS**



**TABLE 27-19: CLKO AND I/O TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Sym	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO31	TioR	Port Output Rise Time	—	10	25	ns	
DO32	TioF	Port Output Fall Time	—	10	25	ns	
DI35	TINP	INTx Pin High or Low Time (output)	20	—	—	ns	
DI40	TRBP	CNx High or Low Time (input)	2	—	—	Tcy	

**Note 1:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.

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**TABLE 27-20: A/D MODULE SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ	Max.	Units	Conditions
Device Supply							
AD01	AVDD	Module VDD Supply	Greater of: VDD – 0.3 or 2.0	—	Lesser of: VDD + 0.3 or 3.6	V	
AD02	AVSS	Module VSS Supply	VSS – 0.3	—	VSS + 0.3	V	
Reference Inputs							
AD05	VREFH	Reference Voltage High	AVSS + 1.7	—	AVDD	V	
AD06	VREFL	Reference Voltage Low	AVSS	—	AVDD – 1.7	V	
AD07	VREF	Absolute Reference Voltage	AVSS – 0.3	—	AVDD + 0.3	V	
AD08	IVREF	Reference Voltage Input Current	—	—	1.25	mA	Measured during conversion, 3.3V, +25°C (Note 1)
AD09	ZREF	Reference Input Impedance	—	10k	—	Ω	Measured during sampling, 3.3V, +25°C
Analog Input							
AD10	VINH-VINL	Full-Scale Input Span	VREFL	—	VREFH	V	(Note 1)
AD11	VIN	Absolute Input Voltage	AVSS – 0.3	—	AVDD + 0.3	V	
AD12	VINL	Absolute VINL Input Voltage	AVSS – 0.3	—	AVDD/2	V	
AD13	—	Leakage Current	—	±1	±610	nA	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V, Source Impedance = 2.5 kΩ
AD17	RIN	Recommended Impedance of Analog Voltage Source	—	—	2.5K	Ω	10-bit
A/D Accuracy							
AD20b	Nr	Resolution	—	10	—	bits	
AD21b	INL	Integral Nonlinearity	—	±1	<±2	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD22b	DNL	Differential Nonlinearity	—	±1	<±1.25	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD23b	GERR	Gain Error	—	±1	±3	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD24b	E <sub>OFF</sub>	Offset Error	—	±1	±2	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD25b	—	Monotonicity <sup>(2)</sup>	—	—	—	—	Guaranteed

**Note 1:** Measurements are taken with external VREF+ and VREF- used as the A/D voltage reference.

**2:** The A/D conversion result never decreases with an increase in the input voltage and has no missing codes.



# PIC24FJ64GA004 FAMILY

**TABLE 27-21: A/D CONVERSION TIMING REQUIREMENTS<sup>(1)</sup>**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature				
			-40°C ≤ TA ≤ +85°C for Industrial				
			-40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ	Max.	Units	Conditions
<b>Clock Parameters</b>							
AD50	TAD	A/D Clock Period	75	—	—	ns	Tcy = 75 ns, AD1CON3 in default state
AD51	tRC	A/D Internal RC Oscillator Period	—	250	—	ns	
<b>Conversion Rate</b>							
AD55	tCONV	Conversion Time	—	12	—	TAD	
AD56	FCNV	Throughput Rate	—	—	500	ksps	AVDD ≥ 2.7V
AD57	tsAMP	Sample Time	—	1	—	TAD	
<b>Clock Parameters</b>							
AD61	tpSS	Sample Start Delay from Setting Sample bit (SAMP)	2	—	3	TAD	

**Note 1:** Because the sample caps will eventually lose charge, clock rates below 10 kHz can affect linearity performance, especially at elevated temperatures.

# PIC24FJ64GA004 FAMILY

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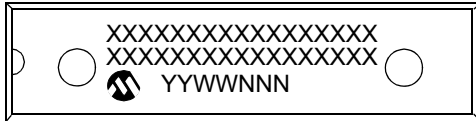
NOTES:

# PIC24FJ64GA004 FAMILY

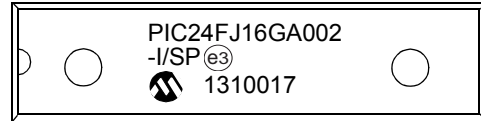
## 28.0 PACKAGING INFORMATION

### 28.1 Package Marking Information

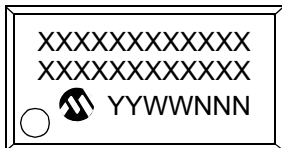
28-Lead SPDIP (.300")



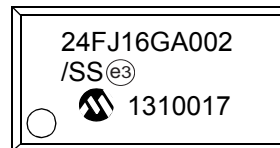
Example



28-Lead SSOP (5.30 mm)



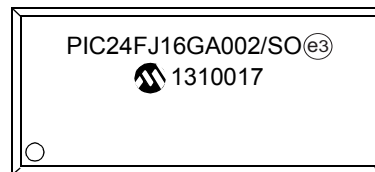
Example



28-Lead SOIC (7.50 mm)



Example



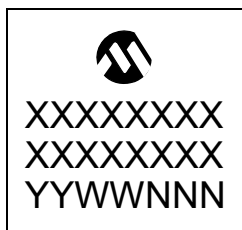
<b>Legend:</b>	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	*	Pb-free JEDEC designator for Matte Tin (Sn)
		This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

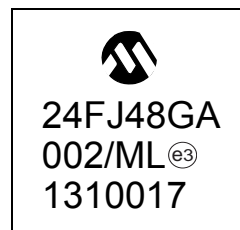
# PIC24FJ64GA004 FAMILY

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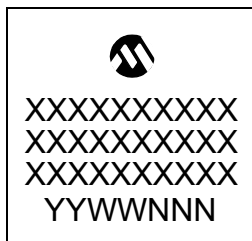
28-Lead QFN (6X6 mm)



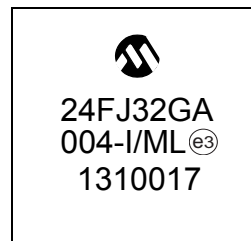
Example



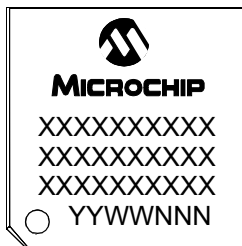
44-Lead QFN (8x8x0.9 mm)



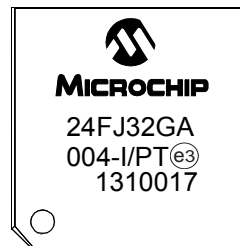
Example



44-Lead TQFP (10x10x1 mm)



Example



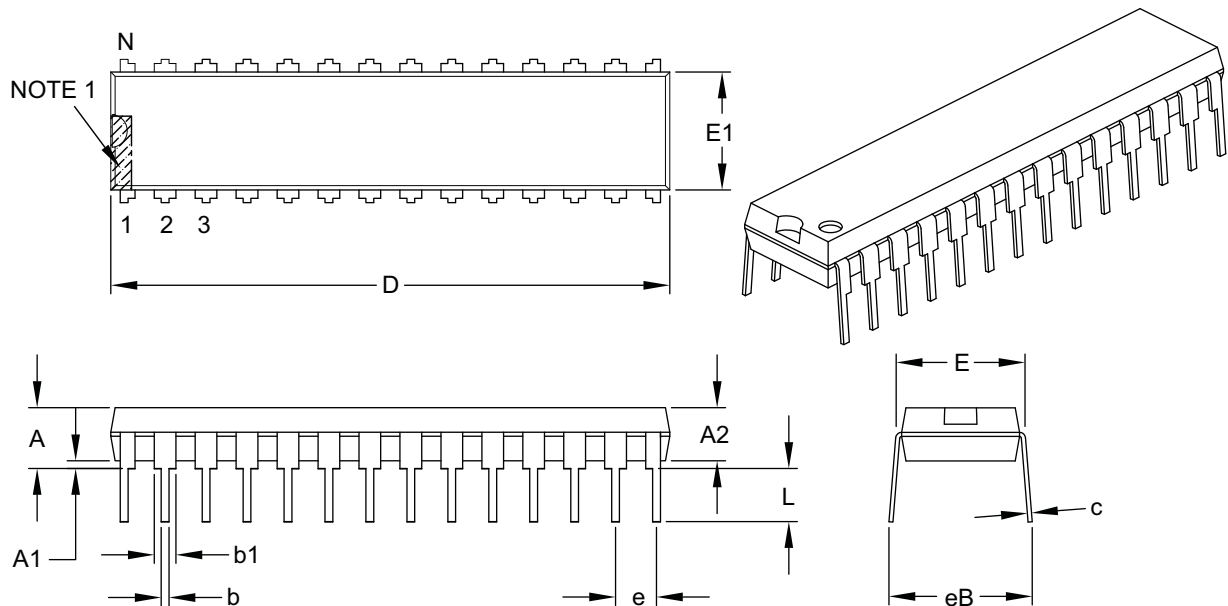
# PIC24FJ64GA004 FAMILY

## 28.2 Package Details

The following sections give the technical details of the packages.

### 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	.100 BSC		
Top to Seating Plane	A	–	–	.200
Molded Package Thickness	A2	.120	.135	.150
Base to Seating Plane	A1	.015	–	–
Shoulder to Shoulder Width	E	.290	.310	.335
Molded Package Width	E1	.240	.285	.295
Overall Length	D	1.345	1.365	1.400
Tip to Seating Plane	L	.110	.130	.150
Lead Thickness	c	.008	.010	.015
Upper Lead Width	b1	.040	.050	.070
Lower Lead Width	b	.014	.018	.022
Overall Row Spacing §	eB	–	–	.430

**Notes:**

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- Dimensioning and tolerancing per ASME Y14.5M.

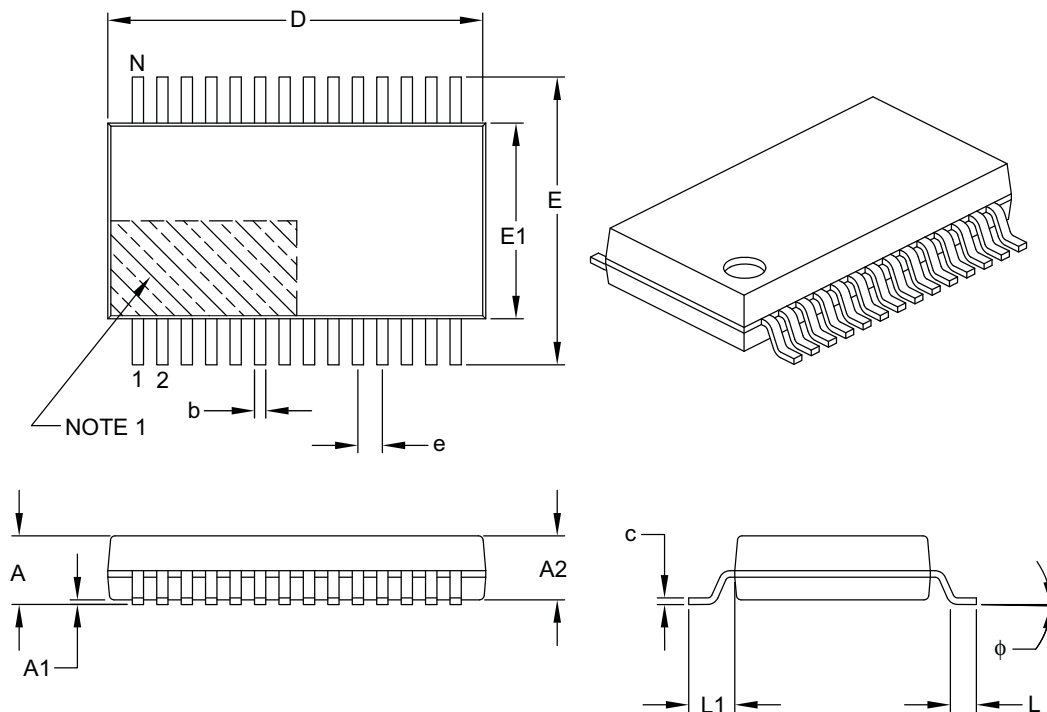
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

# PIC24FJ64GA004 FAMILY

## 28-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	0.65 BSC		
Overall Height	A	–	–	2.00
Molded Package Thickness	A2	1.65	1.75	1.85
Standoff	A1	0.05	–	–
Overall Width	E	7.40	7.80	8.20
Molded Package Width	E1	5.00	5.30	5.60
Overall Length	D	9.90	10.20	10.50
Foot Length	L	0.55	0.75	0.95
Footprint	L1	1.25 REF		
Lead Thickness	c	0.09	–	0.25
Foot Angle	φ	0°	4°	8°
Lead Width	b	0.22	–	0.38

### Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

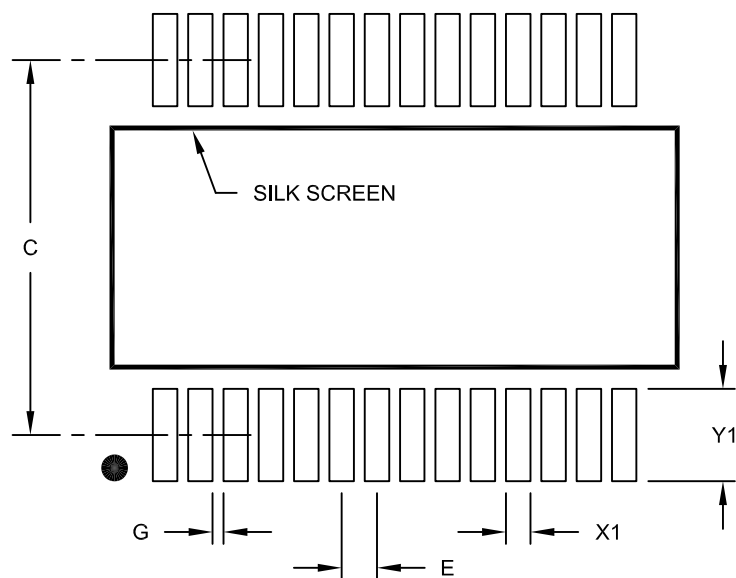
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-073B

# PIC24FJ64GA004 FAMILY

28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C		7.20	
Contact Pad Width (X28)	X1			0.45
Contact Pad Length (X28)	Y1			1.75
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

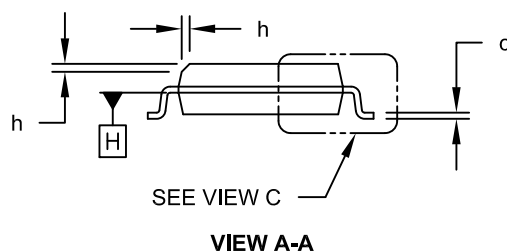
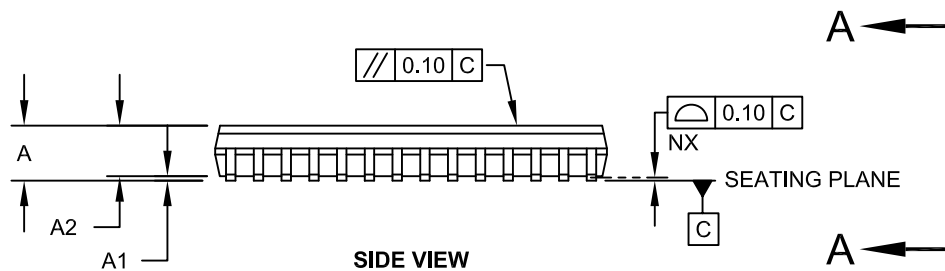
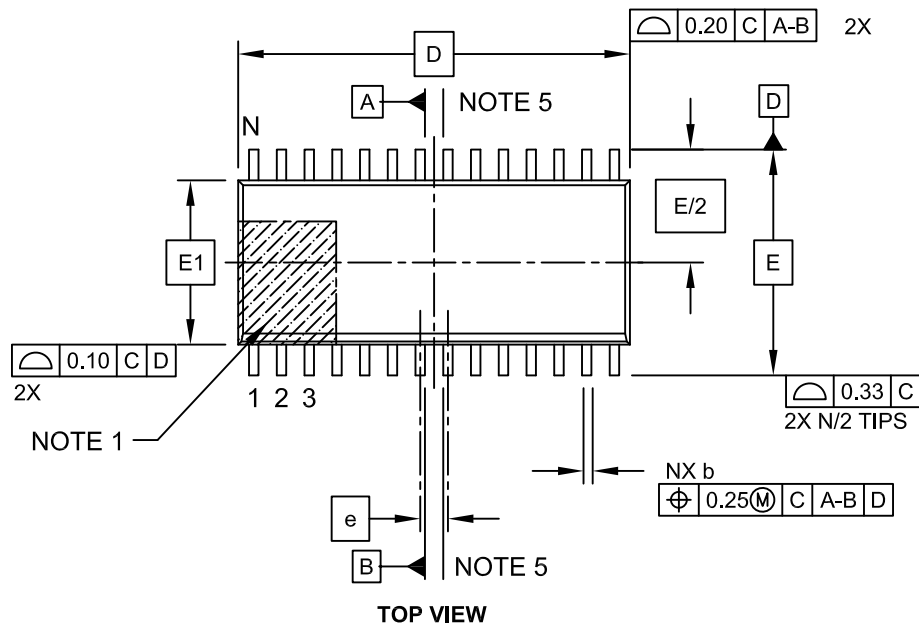
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2073A

# PIC24FJ64GA004 FAMILY

## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



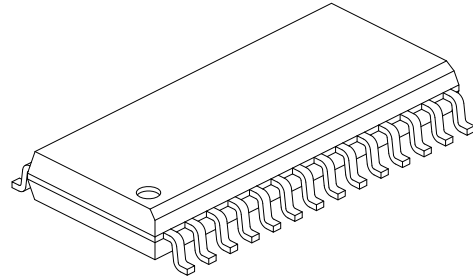
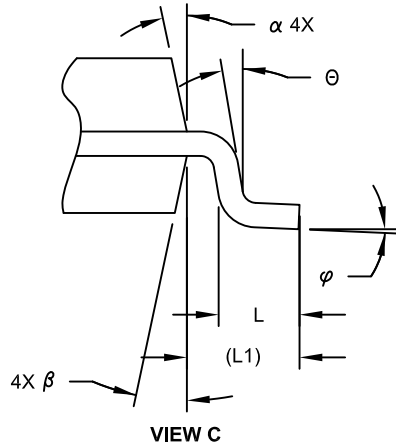
Microchip Technology Drawing C04-052C Sheet 1 of 2



# PIC24FJ64GA004 FAMILY

## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	1.27 BSC		
Overall Height	A	-	-	2.65
Molded Package Thickness	A2	2.05	-	-
Standoff §	A1	0.10	-	0.30
Overall Width	E	10.30 BSC		
Molded Package Width	E1	7.50 BSC		
Overall Length	D	17.90 BSC		
Chamfer (Optional)	h	0.25	-	0.75
Foot Length	L	0.40	-	1.27
Footprint	L1	1.40 REF		
Lead Angle	Θ	0°	-	-
Foot Angle	φ	0°	-	8°
Lead Thickness	c	0.18	-	0.33
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

### Notes:

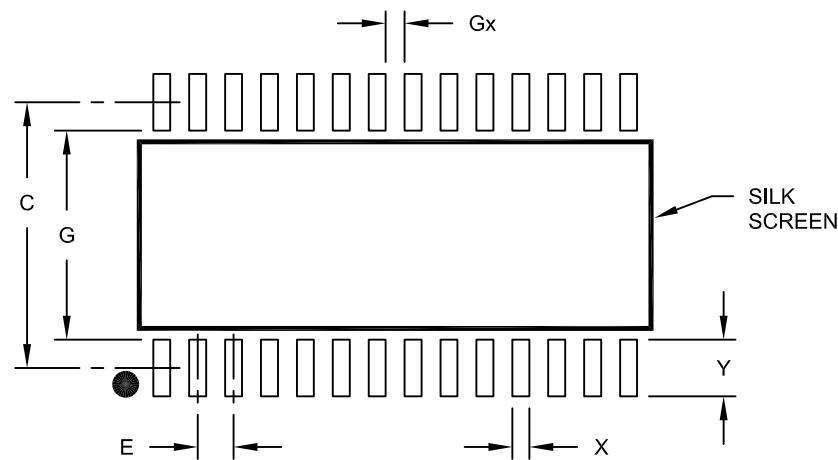
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.
- Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

# PIC24FJ64GA004 FAMILY

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packages>



## RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	1.27 BSC		
Contact Pad Spacing	C		9.40	
Contact Pad Width (X28)	X			0.60
Contact Pad Length (X28)	Y			2.00
Distance Between Pads	Gx	0.67		
Distance Between Pads	G	7.40		

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

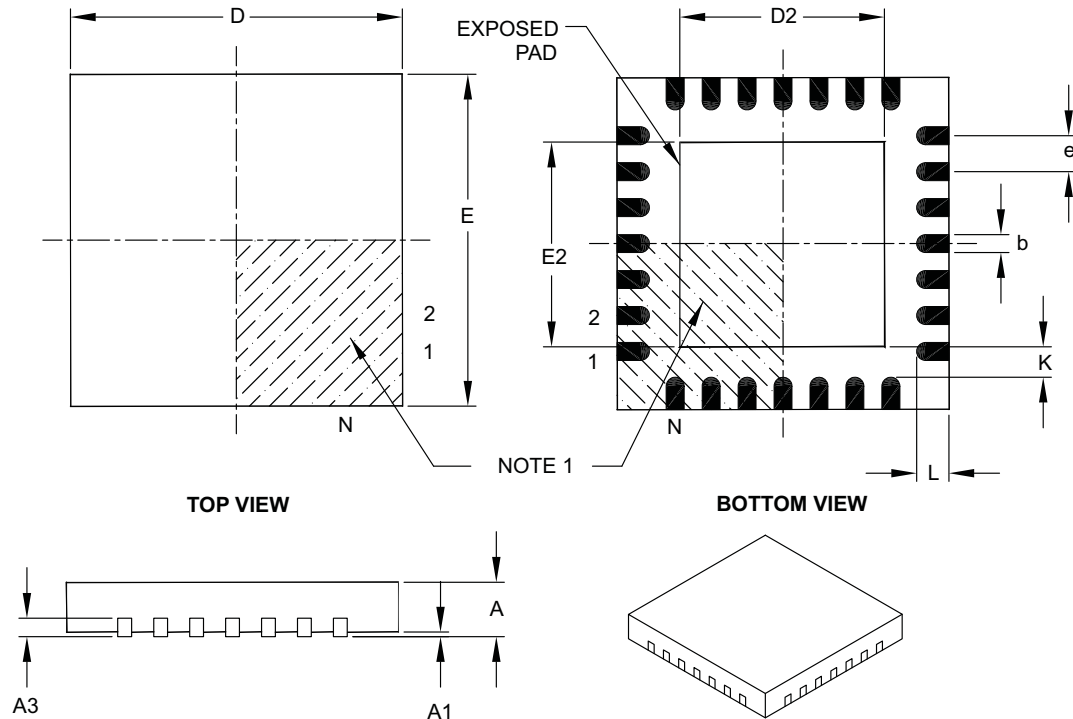
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A

# PIC24FJ64GA004 FAMILY

## 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	0.65 BSC		
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3	0.20 REF		
Overall Width	E	6.00 BSC		
Exposed Pad Width	E2	3.65	3.70	4.20
Overall Length	D	6.00 BSC		
Exposed Pad Length	D2	3.65	3.70	4.20
Contact Width	b	0.23	0.30	0.35
Contact Length	L	0.50	0.55	0.70
Contact-to-Exposed Pad	K	0.20	–	–

**Notes:**

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

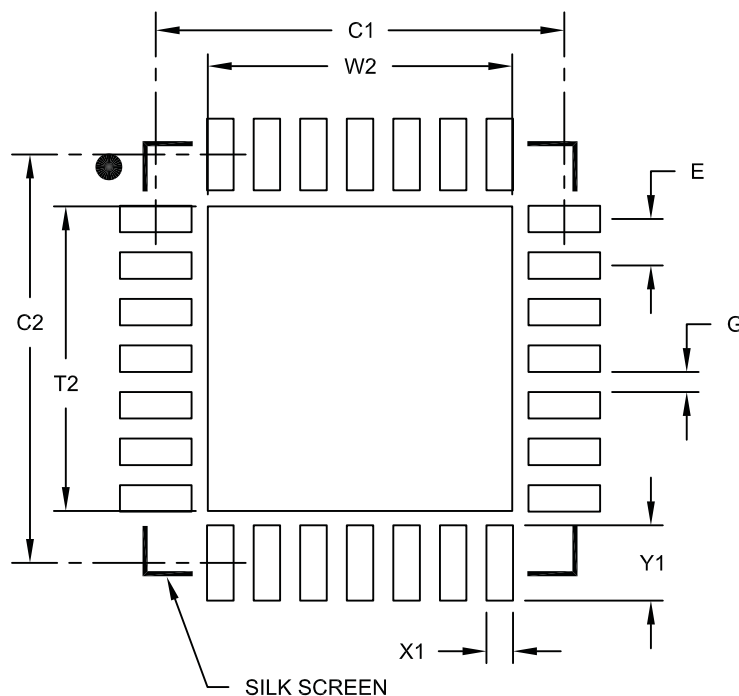
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105B

# PIC24FJ64GA004 FAMILY

## 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			4.25
Optional Center Pad Length	T2			4.25
Contact Pad Spacing	C1		5.70	
Contact Pad Spacing	C2		5.70	
Contact Pad Width (X28)	X1			0.37
Contact Pad Length (X28)	Y1			1.00
Distance Between Pads	G	0.20		

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

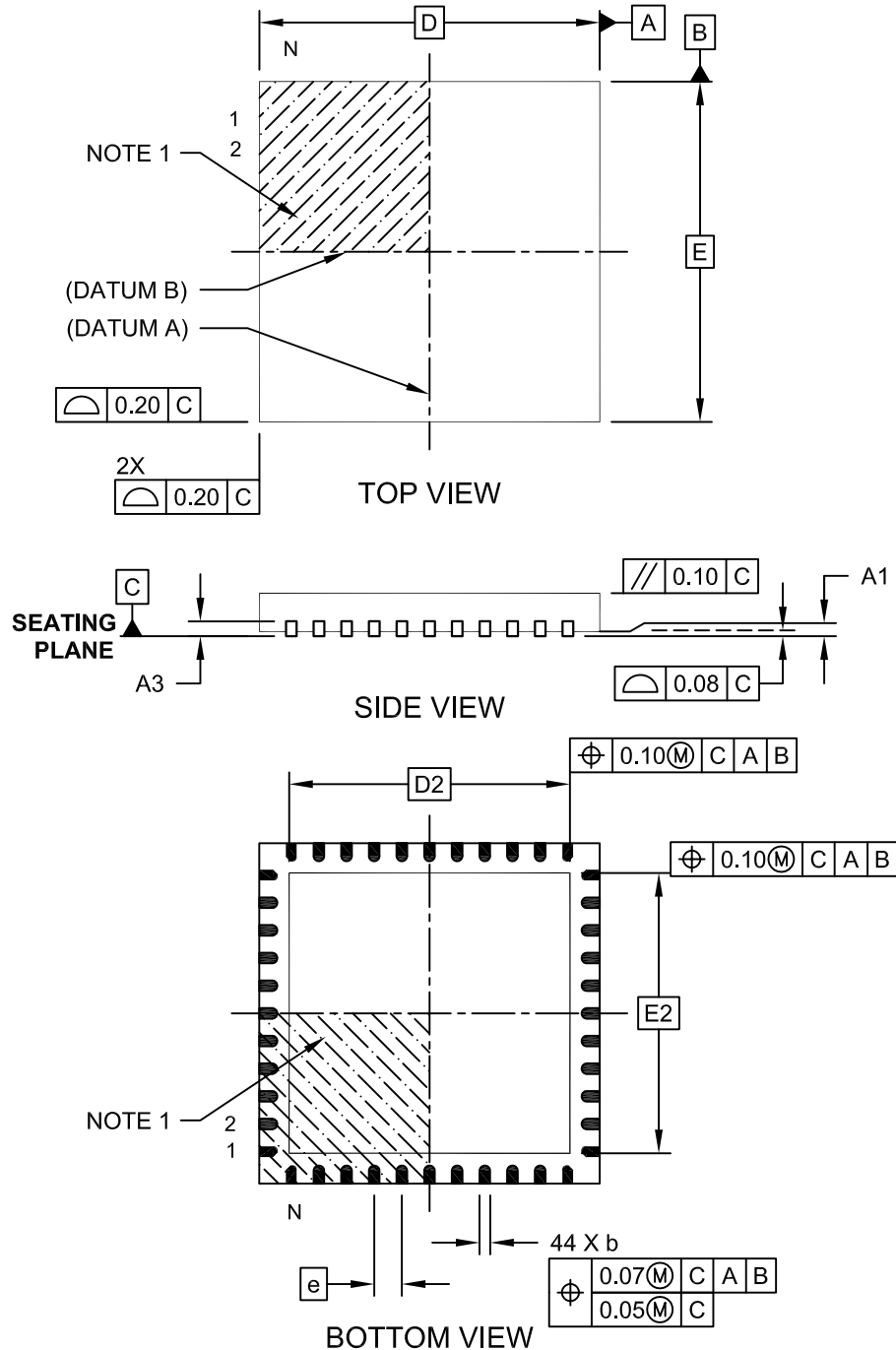
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

# PIC24FJ64GA004 FAMILY

## 44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

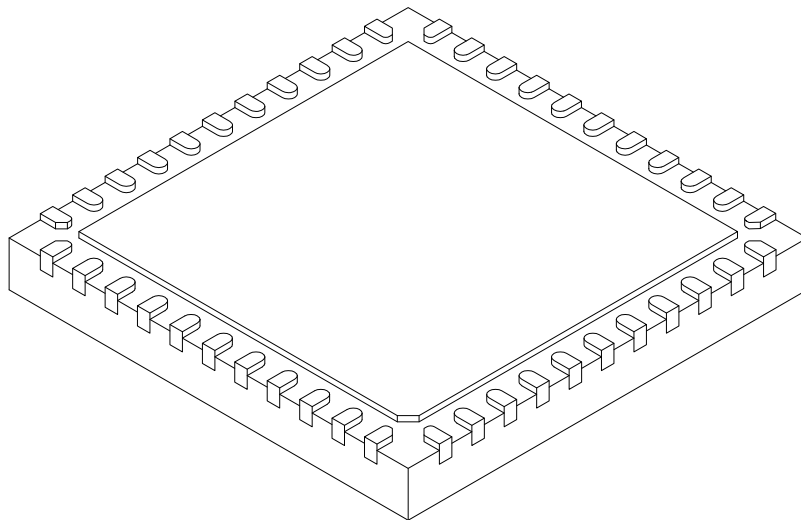


Microchip Technology Drawing C04-103C Sheet 1 of 2

# PIC24FJ64GA004 FAMILY

## 44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	44		
Pitch	e	0.65 BSC		
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.20 REF		
Overall Width	E	8.00 BSC		
Exposed Pad Width	E2	6.25	6.45	6.60
Overall Length	D	8.00 BSC		
Exposed Pad Length	D2	6.25	6.45	6.60
Terminal Width	b	0.20	0.30	0.35
Terminal Length	L	0.30	0.40	0.50
Terminal-to-Exposed-Pad	K	0.20	-	-

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated
3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

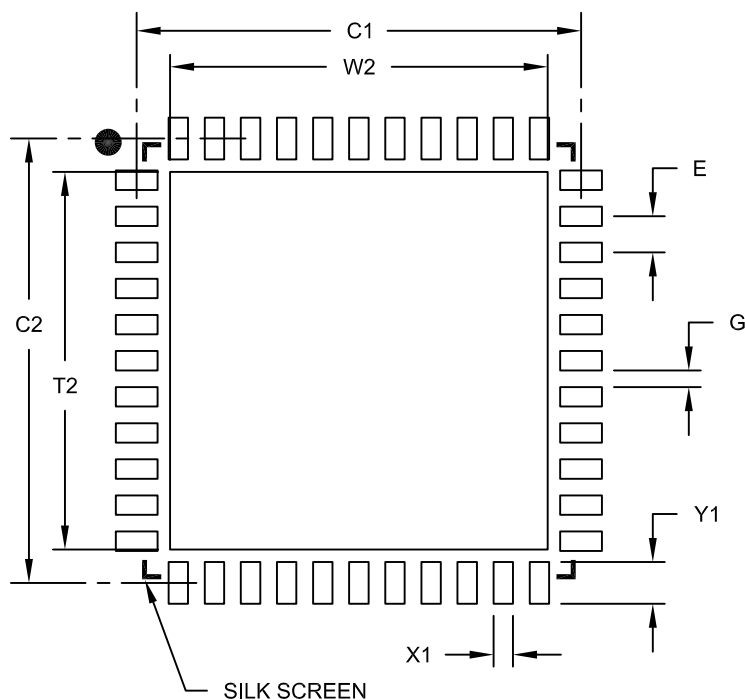
REF: Reference Dimension. usually without tolerance. for information purposes only.

Microchip Technology Drawing C04-103C Sheet 2 of 2

# PIC24FJ64GA004 FAMILY

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			6.60
Optional Center Pad Length	T2			6.60
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

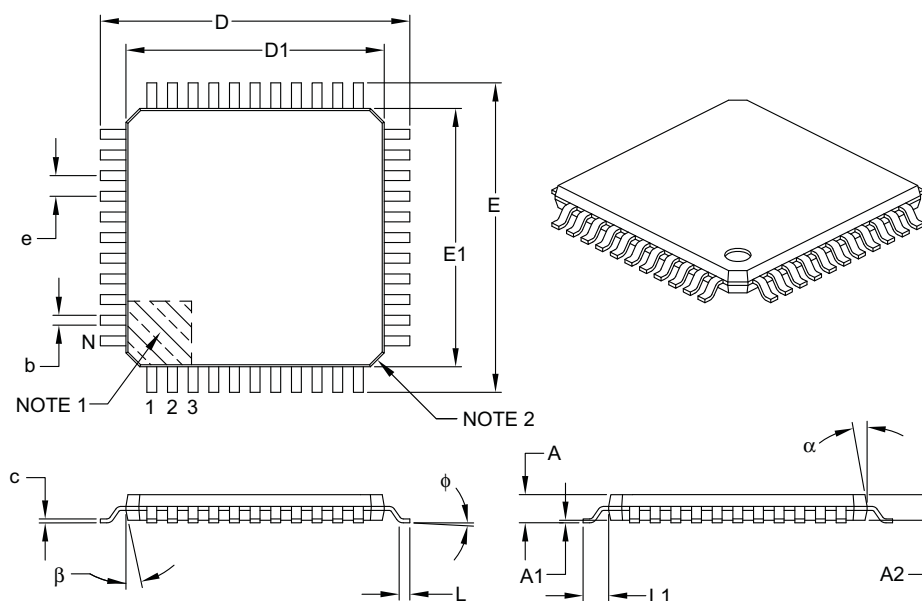
BSC; Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103B

# PIC24FJ64GA004 FAMILY

## 44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packageing>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Leads	N	44		
Lead Pitch	e	0.80 BSC		
Overall Height	A	–	–	1.20
Molded Package Thickness	A2	0.95	1.00	1.05
Standoff	A1	0.05	–	0.15
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	φ	0°	3.5°	7°
Overall Width	E	12.00 BSC		
Overall Length	D	12.00 BSC		
Molded Package Width	E1	10.00 BSC		
Molded Package Length	D1	10.00 BSC		
Lead Thickness	c	0.09	–	0.20
Lead Width	b	0.30	0.37	0.45
Mold Draft Angle Top	α	11°	12°	13°
Mold Draft Angle Bottom	β	11°	12°	13°

### Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Chamfers at corners are optional; size may vary.
- Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

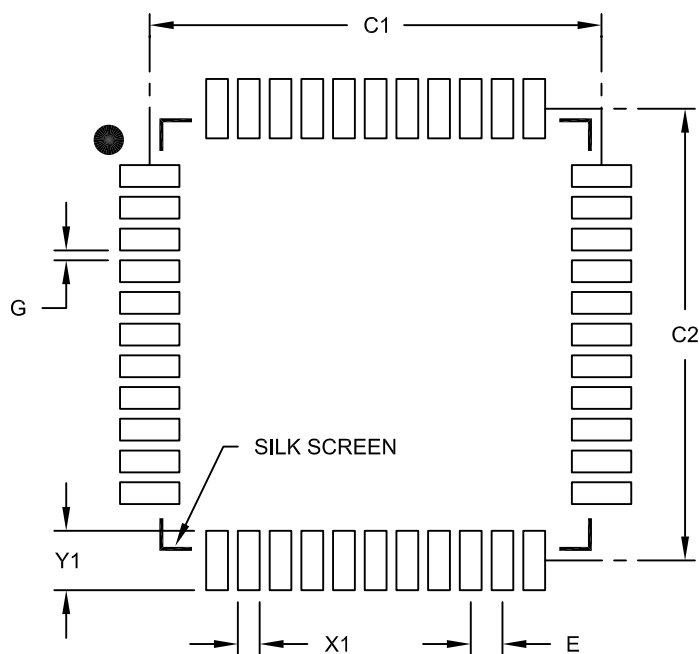
Microchip Technology Drawing C04-076B



# PIC24FJ64GA004 FAMILY

44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.80 BSC		
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B

# PIC24FJ64GA004 FAMILY

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NOTES:

## APPENDIX A: REVISION HISTORY

### Revision A (March 2007)

Original data sheet for the PIC24FJ64GA004 family of devices.

### Revision B (March 2007)

Changes to Table 26-8; packaging diagrams updated.

### Revision C (January 2008)

- Update of electrical specifications to include DC characteristics for Extended Temperature devices.
- Update for A/D converter chapter to include information on internal band gap voltage reference.
- Added “**Appendix B: “Additional Guidance for PIC24FJ64GA004 Family Applications”**”.
- General revisions to incorporate corrections included in document errata to date (DS80333).

### Revision D (January 2010)

- Update of electrical specifications to include 60°C specifications for power-down current to DC characteristics.
- Removes references to JTAG programming throughout the document.
- Other minor typographic corrections throughout.

### Revision E (May 2013)

- Updates all pin diagrams to indicate 5V tolerant pins.
- Updates all package labeling diagrams.
- Changes the VREGS bit name (RCON<8>) to PMSLP in all occurrences throughout the data sheet; also updates the description of the bit's functionality in [Register 6-1](#). (The actual operation of the bit remains unchanged.)
- Adds additional explanatory text to the following sections:
  - [Section 9.2.1 “Sleep Mode”](#)
  - [Section 10.4.2.1 “Peripheral Pin Select Function Priority”](#)
  - [Section 24.2.3 “On-Chip Regulator and POR”](#)

- Updates [Section 2.0 “Guidelines for Getting Started with 16-Bit Microcontrollers”](#) with the most current information on VCAP selection.
- Replaces [Table 6-3](#) (Reset Delay Times) with an updated version.
- Updates [Section 7.0 “Interrupt Controller”](#) by adding a description of the INTTREG register ([Register 7-31](#)).
- Updates [Section 8.0 “Oscillator Configuration”](#) by correcting the external oscillator inputs in [Figure 8-1](#) and a new unlock code sequence in [Example 8-1](#).
- Replaces [Example 10-2](#) with a new code example.
- Updates [Section 19.0 “Real-Time Clock and Calendar \(RTCC\)”](#) to add introductory text and amend input sources in [Figure 19-1](#).
- Updates [Section 20.0 “Programmable Cyclic Redundancy Check \(CRC\) Generator”](#) with a more current version (no technical changes to the module or its operation).
- Updates [Section 26.0 “Instruction Set Summary”](#):
  - Updates syntax of ASR, DAW, LSR, MOV and SL instructions to conform with the *Programmer's Reference Manual*
  - Adds previously omitted instruction, FBCL
- Adds to [Section 27.0 “Electrical Characteristics”](#):
  - New Specification DC18 (VBOR) to [Table 27-3](#)
  - New Specifications DI60a (IICL), DI60b (IICH) and DI60c (ΣIICL) to [Table 27-7](#)
  - New [Table 27-10](#) (Comparator Specifications) and [Table 27-11](#) (Comparator Voltage Reference Specifications); previous Table 27-10 is now renumbered as [Table 27-12](#), and all subsequent tables renumbered accordingly
  - New [Table 27-17](#) (Internal RC Oscillator Specifications)
  - New specifications, AD08 (IVREF), AD09 (ZREF) and AD13 (Leakage Current), to [Table 27-20](#)
  - Combines previous Table 27-15 (AC Characteristics: Internal RC Accuracy) and Table 27-16 (Internal RC Accuracy) into a new [Table 27-18](#) (AC Characteristics: Internal RC Accuracy)
- Other minor typographic corrections throughout.

# PIC24FJ64GA004 FAMILY

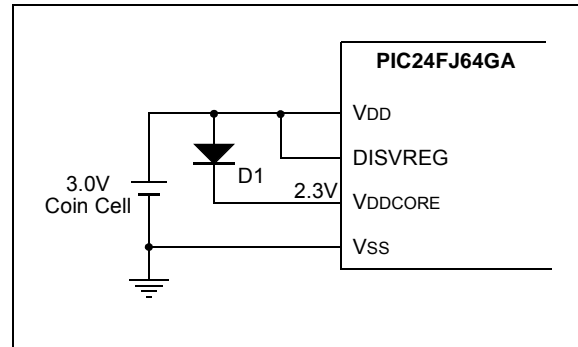
## APPENDIX B: ADDITIONAL GUIDANCE FOR PIC24FJ64GA004 FAMILY APPLICATIONS

### B.1 Additional Methods for Power Reduction

Devices in the PIC24FJ64GA004 family include a number of core features to significantly reduce the application's power requirements. For truly power-sensitive applications, it is possible to further reduce the application's power demands by taking advantage of the device's regulator architecture. These methods help decrease power in two ways: by disabling the internal voltage regulator to eliminate its power consumption, and by reducing the voltage on VDDCORE to lower the device's dynamic current requirements. Using these methods, it is possible to reduce Sleep currents (IPD) from 3.5  $\mu$ A to 250 nA (typical values, refer to Parameters DC60d and DC60g in [Table 27-6](#)). For dynamic power consumption, the reduction in VDDCORE from 2.5V provided by the regulator, to 2.0V, can provide a power reduction of about 30%.

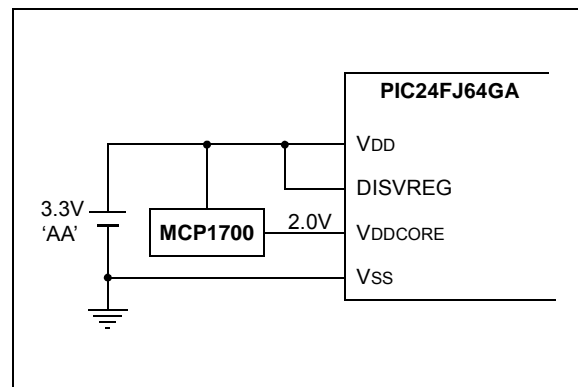
When using a regulated power source or a battery with a constant output voltage, it is possible to decrease power consumption by disabling the regulator. In this case ([Figure B-1](#)), a simple diode can be used to reduce the voltage from 3V or greater to the 2V-2.5V required for VDDCORE. This method is only advised on power supplies, such as Lithium Coin cells, which maintain a constant voltage over the life of the battery.

FIGURE B-1: POWER REDUCTION EXAMPLE FOR CONSTANT VOLTAGE SUPPLIES



A similar method can be used for non-regulated sources ([Figure B-2](#)). In this case, it can be beneficial to use a low quiescent current, external voltage regulator. Devices, such as the MCP1700, consume only 1  $\mu$ A to regulate to 2V or 2.5V, which is lower than the current required to power the internal voltage regulator.

FIGURE B-2: POWER REDUCTION EXAMPLE FOR NON-REGULATED SUPPLIES



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# PIC24FJ64GA004 FAMILY

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<div><div>PIC 24 FJ 64 GA0 04 T - I / PT - XXX</div><div><div>Microchip Trademark</div><div>Architecture</div><div>Flash Memory Family</div><div>Program Memory Size (KB)</div><div>Product Group</div><div>Pin Count</div><div>Tape and Reel Flag (if applicable)</div><div>Temperature Range</div><div>Package</div><div>Pattern</div></div></div>		<b>Examples:</b>  a) PIC24FJ32GA002-I/ML: General Purpose PIC24F, 32-Kbyte Program Memory, 28-Pin, Industrial Temp., QFN Package.  b) PIC24FJ64GA004-E/PT: General Purpose PIC24F, 64-Kbyte Program Memory, 44-Pin, Extended Temp., TQFP Package.																																										
<table><tr><td>Architecture</td><td>24</td><td>= 16-bit modified Harvard without DSP</td></tr><tr><td>Flash Memory Family</td><td>FJ</td><td>= Flash program memory</td></tr><tr><td>Product Group</td><td>GA0</td><td>= General purpose microcontrollers</td></tr><tr><td>Pin Count</td><td>02</td><td>= 28-pin</td></tr><tr><td></td><td>04</td><td>= 44-pin</td></tr><tr><td>Temperature Range</td><td>E</td><td>= -40°C to +125°C (Extended)</td></tr><tr><td></td><td>I</td><td>= -40°C to +85°C (Industrial)</td></tr><tr><td>Package</td><td>SP</td><td>= SPDIP</td></tr><tr><td></td><td>SO</td><td>= SOIC</td></tr><tr><td></td><td>SS</td><td>= SSOP</td></tr><tr><td></td><td>ML</td><td>= QFN</td></tr><tr><td></td><td>PT</td><td>= TQFP</td></tr><tr><td>Pattern</td><td colspan="2">Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise)</td></tr><tr><td></td><td>ES</td><td>= Engineering Sample</td></tr></table>		Architecture	24	= 16-bit modified Harvard without DSP	Flash Memory Family	FJ	= Flash program memory	Product Group	GA0	= General purpose microcontrollers	Pin Count	02	= 28-pin		04	= 44-pin	Temperature Range	E	= -40°C to +125°C (Extended)		I	= -40°C to +85°C (Industrial)	Package	SP	= SPDIP		SO	= SOIC		SS	= SSOP		ML	= QFN		PT	= TQFP	Pattern	Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise)			ES	= Engineering Sample	
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# PIC24FJ64GA004 FAMILY

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NOTES:

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ISBN: 978-1-62077-201-0

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