

## 200 Msps, 12-Bit Low-Power ADC with 8-Channel MUX

### Features

- Sample Rates:
  - 200 Msps for single-channel mode
  - 200 Msps/number of channels used
- SNR with  $f_{IN} = 15$  MHz and -1 dBFS:
  - 71.3 dBFS (typical) at 200 Msps
- SFDR with  $f_{IN} = 15$  MHz and -1 dBFS:
  - 90 dBc (typical) at 200 Msps
- Power Dissipation with LVDS Digital I/O:
  - 468 mW at 200 Msps
- Power Dissipation with CMOS Digital I/O:
  - 436 mW at 200 Msps, Output Clock = 100 MHz
- Power Dissipation Excluding Digital I/O:
  - 387 mW at 200 Msps
- Power-Saving Modes:
  - 144 mW during Standby
  - 28 mW during Shutdown
- Supply Voltage:
  - Digital Section: 1.2V, 1.8V
  - Analog Section: 1.2V, 1.8V
- Selectable Full-Scale Input Range: up to  $2.975 V_{P-P}$
- Input Channel Bandwidth: 500 MHz
- Channel-to-Channel Crosstalk in Multi-Channel Mode (Input = 15 MHz, -1 dBFS): >95 dB
- Output Data Format:
  - Parallel CMOS, DDR LVDS
- Optional Output Data Randomizer
- Built-In ADC Linearity Calibration Algorithms:
  - Harmonic Distortion Correction (HDC)
  - DAC Noise Cancellation (DNC)
  - Dynamic Element Matching (DEM)
  - Flash Error Calibration

- Digital Signal Post-Processing (DSPP) Options:
  - Decimation filters for improved SNR
  - Fractional Delay Recovery (FDR) for time-delay corrections in multi-channel operations (dual-/octal-channel modes)
  - Noise-Shaping Requantizer (NSR)
  - Phase, Offset and Gain adjust of individual channels
  - Digital Down-Conversion (DDC) with I/Q or  $f_s/8$  output (MCP37D11-200)
  - Continuous wave beamforming for octal-channel mode (MCP37D11-200)
- Serial Peripheral Interface (SPI)
- AutoSync Mode to Synchronize Multiple Devices to the Same Clock
- AEC-Q100 Qualified (Automotive Applications)
- Package Options:
  - (a) TFBGA-121 (8 mm x 8 mm x 1.08 mm):
    - AEC-Q100 qualified
    - Temperature Grade 1: -40°C to +125°C
    - Includes embedded decoupling capacitors for reference pins and bandgap output pin
  - (b) VTLA-124 (9 mm x 9 mm x 0.9 mm)
    - Temperature Range: -40°C to +85°C

### Typical Applications

- Communication Instruments
- Microwave Digital Radio
- Cellular Base Stations
- Lidar and Radar
- Ultrasound and Sonar Imaging
- Low-Power High-Speed Instruments

### MCP372X1/MCP37DX1-200 Family Comparison <sup>(1)</sup>

Part Number	Sample Rate	Resolution	Digital Decimation <sup>(2)</sup>	Digital Down-Conversion <sup>(3)</sup>	CW Beamforming <sup>(4)</sup>	Noise-Shaping Requantizer <sup>(2)</sup>
MCP37231-200	200 Msps	16	Yes	No	No	No
MCP37221-200	200 Msps	14	Yes	No	No	No
MCP37211-200	200 Msps	12	Yes	No	No	Yes
MCP37D31-200	200 Msps	16	Yes	Yes	Yes	No
MCP37D21-200	200 Msps	14	Yes	Yes	Yes	No
MCP37D11-200	200 Msps	12	Yes	Yes	Yes	Yes

**Note 1:** Devices in the same package type are pin-to-pin compatible.

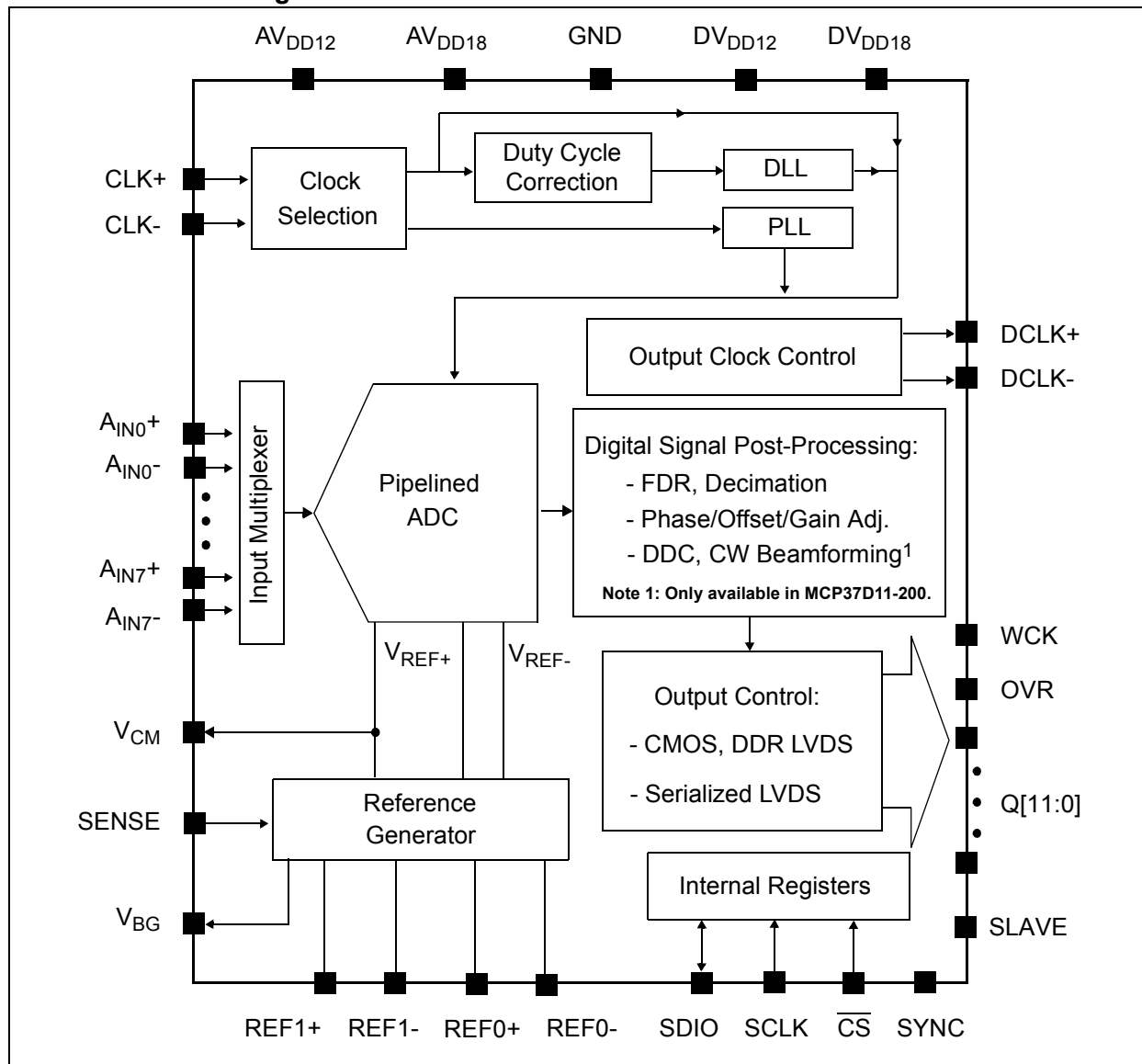
**2:** Available in single- and dual-channel modes.

**3:** Available in single- and dual-channel modes, and octal-channel mode when CW beamforming is enabled.

**4:** Available in octal-channel mode.

# MCP37211-200 AND MCP37D11-200

**Functional Block Diagram**



# MCP37211-200 AND MCP37D11-200

## Description

The MCP37211-200 is Microchip's baseline 12-bit 200 Msps pipelined ADC, featuring built-in high-order digital decimation filters, noise-shaping requantizer, gain and offset adjustment per channel and fractional delay recovery.

The MCP37D11-200 device features digital down-conversion and CW beamforming capability, in addition to the features offered by the MCP37211-200.

All devices feature harmonic distortion correction and DAC noise cancellation that enable high-performance specifications with SNR of 71.3 dBFS (typical) and SFDR of 90 dBc (typical).

These A/D converters exhibit industry-leading low-power performance with only 468 mW operation while using the LVDS interface at 200 Msps. This superior low-power operation coupled with high dynamic performance makes these devices ideal for various high-performance, high-speed data acquisition systems, including communications equipment, radar and portable instrumentation.

In single or dual-channel mode, the Noise-Shaping Requantizer (NSR) feature can allow the ADC to improve SNR beyond a conventional 11- or 12-bit ADC. The NSR reshapes the quantization noise, such that most of the noise power is pushed outside the frequency of interest. As a result, SNR is improved significantly within a selected frequency band of interest while SFDR is not affected.

The digital down-conversion option in the MCP37D10-200 can be utilized with the decimation and quadrature output (I and Q data) option, and offers great flexibility in various digital communication system designs, including cellular base-stations and narrow-band communication systems.

The output decimation filter option improves SNR performance up to 73.7 dBFS. The digital down-conversion option, in conjunction with the decimation and quadrature output options, offers great flexibility in digital communication system design, including cellular base-stations and narrow-band communications.

These devices can have up to eight differential input channels through an input MUX. The sampling rate is up to 200 Msps when a single channel is used, or 25 Msps per channel when all eight input channels are used.

In dual or octal-channel mode, the Fractional Delay Recovery (FDR) feature digitally corrects the difference in sampling instance between different channels, so that all inputs appear to have been sampled at the same time.

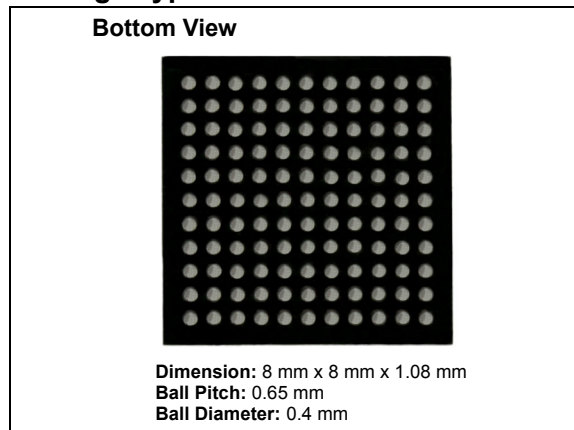
AutoSync mode offers a great design flexibility when multiple devices are used in applications. It allows multiple devices to sample input synchronously at the same clock.

The differential full-scale analog input range is programmable up to  $2.975 V_{P-P}$ . The ADC output data can be coded in two's complement or offset binary representation, with or without the data randomizer option. The output data is available as full-rate CMOS or Double-Data-Rate (DDR) LVDS.

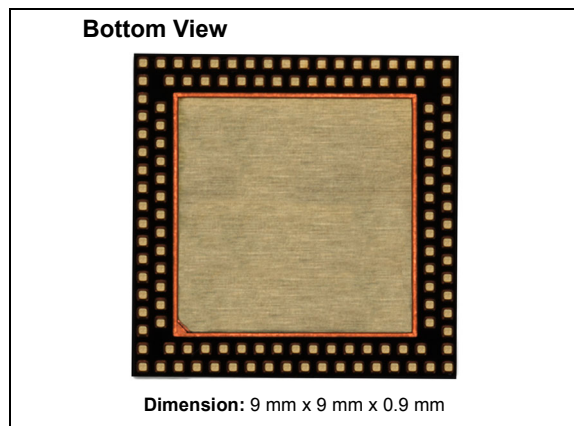
These devices also include various features designed to maximize flexibility in the user's applications and minimize system cost, such as a programmable PLL clock, output data rate control and phase alignment and programmable digital pattern generation. The device's operational modes and feature sets are configured by setting up the user-programmable registers.

The device is available in Pb-free TFBGA-121 and VTLA-124 packages. The device with a TFBGA-121 package is AEC-Q100 qualified for automotive applications and operates over the extended temperature range of  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

## Package Types



**(a) TFBGA-121 Package (AEC-Q100 Qualified).**



**(b) VTLA-124 Package<sup>1</sup>.**

**Note 1:** Contact Microchip Technology Inc. for the VTLA-124 package availability.

# MCP37211-200 AND MCP37D11-200

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NOTES:

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## 1.0 PACKAGE PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

**Top View**  
(Not to Scale)

	1	2	3	4	5	6	7	8	9	10	11
A	SDIO	V <sub>CM</sub>	REF1+	REF1-	V <sub>BG</sub>	REF0+	REF0-	GND	GND	A <sub>IN4-</sub>	A <sub>IN2+</sub>
B	SCLK	$\overline{\text{CS}}$	GND	GND	SENSE	AV <sub>DD12</sub>	AV <sub>DD12</sub>	AV <sub>DD18</sub>	AV <sub>DD18</sub>	A <sub>IN4+</sub>	A <sub>IN2-</sub>
C	WCK/ OVR- (WCK)	WCK/ OVR+ (OVR)	GND	GND	AV <sub>DD12</sub>	AV <sub>DD12</sub>	AV <sub>DD12</sub>	GND	GND	A <sub>IN6-</sub>	A <sub>IN0+</sub>
D	Q10/Q5-	Q11/Q5+	GND	GND	AV <sub>DD12</sub>	AV <sub>DD12</sub>	AV <sub>DD12</sub>	GND	GND	A <sub>IN6+</sub>	A <sub>IN0-</sub>
E	Q8/Q4-	Q9/Q4+	GND	GND	AV <sub>DD12</sub>	AV <sub>DD12</sub>	AV <sub>DD12</sub>	GND	GND	A <sub>IN5+</sub>	A <sub>IN1+</sub>
F	Q6/Q3-	Q7/Q3+	DV <sub>DD18</sub>	DV <sub>DD18</sub>	AV <sub>DD12</sub>	AV <sub>DD12</sub>	AV <sub>DD12</sub>	GND	GND	A <sub>IN5-</sub>	A <sub>IN1-</sub>
G	Q4/Q2-	Q5/Q2+	DV <sub>DD18</sub>	DV <sub>DD18</sub>	GND	GND	AV <sub>DD12</sub>	AV <sub>DD12</sub>	GND	A <sub>IN7-</sub>	A <sub>IN3+</sub>
H	Q2/Q1-	Q3/Q1+	DV <sub>DD12</sub>	DV <sub>DD12</sub>	GND	GND	GND	GND	GND	A <sub>IN7+</sub>	A <sub>IN3-</sub>
J	Q0/Q0-	Q1/Q0+	DV <sub>DD12</sub>	DV <sub>DD12</sub>	GND	GND	GND	GND	GND	V <sub>CMIN+</sub>	V <sub>CMIN-</sub>
K	TP	TP	TP	DCLK-	CAL	GND	SLAVE	ADR0	ADR1	GND	GND
L	TP	TP	TP	DCLK+	$\overline{\text{RESET}}$	SYNC	GND	CLK+	CLK-	GND	AV <sub>DD18</sub>

Analog  
 Digital  
 All others: Supply Voltage

### Notes:

- Die dimension: 8 mm x 8 mm x 1.08 mm.
- Ball dimension: (a) Ball Pitch = 0.65 mm, (b) Ball Diameter = 0.4 mm.
- Flip-chip solder ball composition: Sn with Ag 1.8%.
- Solder sphere composition: SAC-405 (Sn/Au 4%/Cu 0.5%).

**FIGURE 1-1:** TFBGA-121 Package. See [Table 1-1](#) for the pin descriptions. Decoupling capacitors for reference pins and V<sub>BG</sub> are embedded in the package. Leave TP pins floating always.

# MCP37211-200 AND MCP37D11-200

**TABLE 1-1: PIN FUNCTION TABLE FOR TFBGA-121**

Ball No.	Name	I/O Type	Description
A1	SDIO	Digital Input/Output	SPI data input/output
A2	V <sub>CM</sub>	Analog Output	Common-mode output voltage (900 mV) for analog input signal Connect a decoupling capacitor (0.1 $\mu$ F) <sup>(1)</sup>
A3	REF1+		Differential reference voltage 1 (+/-). Decoupling capacitors are embedded in the TFBGA package. Leave these pins floating.
A4	REF1-		
A5	V <sub>BG</sub>		Internal bandgap output voltage A decoupling capacitor (2.2 $\mu$ F) is embedded in the TFBGA package. Leave this pin floating.
A6	REF0+		Differential reference 0 (+/-) voltage. Decoupling capacitors are embedded in the TFBGA package. Leave these pins floating.
A7	REF0-		
A8	GND	Supply	Common ground for analog and digital sections
A9			
A10	A <sub>IN4-</sub>	Analog Input	Channel 4 differential analog input (-)
A11	A <sub>IN2+</sub>		Channel 2 differential analog input (+)
B1	SCLK	Digital Input	SPI serial clock input
B2	$\overline{\text{CS}}$		SPI Chip Select input
B3	GND	Supply	Common ground for analog and digital sections
B4			
B5	SENSE	Analog Input	Analog input range selection. See <a href="#">Table 4-2</a> for SENSE voltage settings.
B6	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
B7			
B8	AV <sub>DD18</sub>		Supply voltage input (1.8V) for analog section
B9			
B10	A <sub>IN4+</sub>	Analog Input	Channel 4 differential analog input (+)
B11	A <sub>IN2-</sub>		Channel 2 differential analog input (-)
C1	WCK/OVR- (WCK)	Digital Output	<b>WCK:</b> Word clock sync digital output <b>OVR:</b> Input overrange indication digital output <sup>(2)</sup>
C2	WCK/OVR+ (OVR)		
C3	GND	Supply	Common ground for analog and digital sections
C4			
C5	AV <sub>DD12</sub>		Supply voltage input (1.2V) for analog section
C6			
C7			
C8	GND		Common ground pin for analog and digital sections
C9			
C10	A <sub>IN6-</sub>	Analog Input	Channel 6 differential analog input (-)
C11	A <sub>IN0+</sub>		Channel 0 differential analog input (+)
D1	Q10/Q5-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q10 DDR LVDS = Q5-
D2	Q11/Q5+		Digital data output <sup>(3)</sup> CMOS = Q11 DDR LVDS = Q5+
D3	GND	Supply	Common ground for analog and digital sections
D4			

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**TABLE 1-1: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
D5	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
D6			
D7			
D8	GND		Common ground for analog and digital sections
D9			
D10	A <sub>IN6+</sub>	Analog Input	Channel 6 differential analog input (+)
D11	A <sub>IN0-</sub>		Channel 0 differential analog input (-)
E1	Q8/Q4-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q8 DDR LVDS = Q4-
E2	Q9/Q4+		Digital data output <sup>(3)</sup> CMOS = Q9 DDR LVDS = Q4+
E3	GND	Supply	Common ground for analog and digital sections
E4			
E5	AV <sub>DD12</sub>		Supply voltage input (1.2V) for analog section
E6			
E7			
E8	GND		Common ground for analog and digital sections
E9			
E10	A <sub>IN5+</sub>	Analog Input	Channel 5 differential analog input (+)
E11	A <sub>IN1+</sub>		Channel 1 differential analog input (+)
F1	Q6/Q3-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q6 DDR LVDS = Q3-
F2	Q7/Q3+		Digital data output <sup>(3)</sup> CMOS = Q7 DDR LVDS = Q3+
F3	DV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for digital section. All digital input pins are driven by the same DV <sub>DD18</sub> potential.
F4			
F5	AV <sub>DD12</sub>		Supply voltage input (1.2V) for analog section
F6			
F7			
F8	GND		Common ground for analog and digital sections
F9			
F10	A <sub>IN5-</sub>	Analog Input	Channel 5 differential analog input (-)
F11	A <sub>IN1-</sub>		Channel 1 differential analog input (-)
G1	Q4/Q2-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q4 DDR LVDS = Q2-
G2	Q5/Q2+		Digital data output <sup>(3)</sup> CMOS = Q5 DDR LVDS = Q2+
G3	DV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for digital section All digital input pins are driven by the same DV <sub>DD18</sub> potential
G4			
G5	GND		Common ground for analog and digital sections
G6			

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**TABLE 1-1: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
G7	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
G8			
G9	GND		Common ground for analog and digital sections
G10	A <sub>IN7-</sub>	Analog Input	Channel 7 differential analog input (-)
G11	A <sub>IN3+</sub>		Channel 3 differential analog input (+)
H1	Q2/Q1-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q2 DDR LVDS = Q1-
H2	Q3/Q1+		Digital data output <sup>(3)</sup> CMOS = Q3 DDR LVDS = Q1+
H3	DV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for digital section
H4			
H5	GND		Common ground for analog and digital sections
H6			
H7			
H8			
H9			
H10	A <sub>IN7+</sub>	Analog Input	Channel 7 differential analog input (+)
H11	A <sub>IN3-</sub>		Channel 3 differential analog input (-)
J1	Q0/Q0-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q0 DDR LVDS = Q0-
J2	Q1/Q0+		Digital data output <sup>(3)</sup> CMOS = Q1 DDR LVDS = Q0+
J3	DV <sub>DD12</sub>	Supply	DC supply voltage input pin for digital section (1.2V)
J4			
J5	GND		Common ground for analog and digital sections
J6			
J7			
J8			
J9			
J10	V <sub>CMIN+</sub>	Analog Input	Common-mode voltage input for auto-calibration <sup>(4)</sup> These two pins should be tied together and connected to V <sub>CM</sub> voltage.
J11	V <sub>CMIN-</sub>		
K1	TP	Digital Output	Output test pints. Leave these pins floating always <sup>(8)</sup>
K2			
K3			
K4	DCLK-		<b>LVDS:</b> Differential digital clock output (-) <b>CMOS:</b> Not used (leave floating)
K5	CAL	Digital Output	Calibration status flag digital output <sup>(5)</sup> <b>High:</b> Calibration is complete <b>Low:</b> Calibration is not complete
K6	GND	Supply	Common ground pin for analog and digital sections
K7	SLAVE	Digital Input	Slave or Master selection pin in AutoSync <sup>(10)</sup> . If not used, tie to GND.
K8	ADR0		SPI address selection pin (A0 bit). Tie to GND or DV <sub>DD18</sub> <sup>(6)</sup>
K9	ADR1		SPI address selection pin (A1 bit). Tie to GND or DV <sub>DD18</sub> <sup>(6)</sup>



# MCP37211-200 AND MCP37D11-200

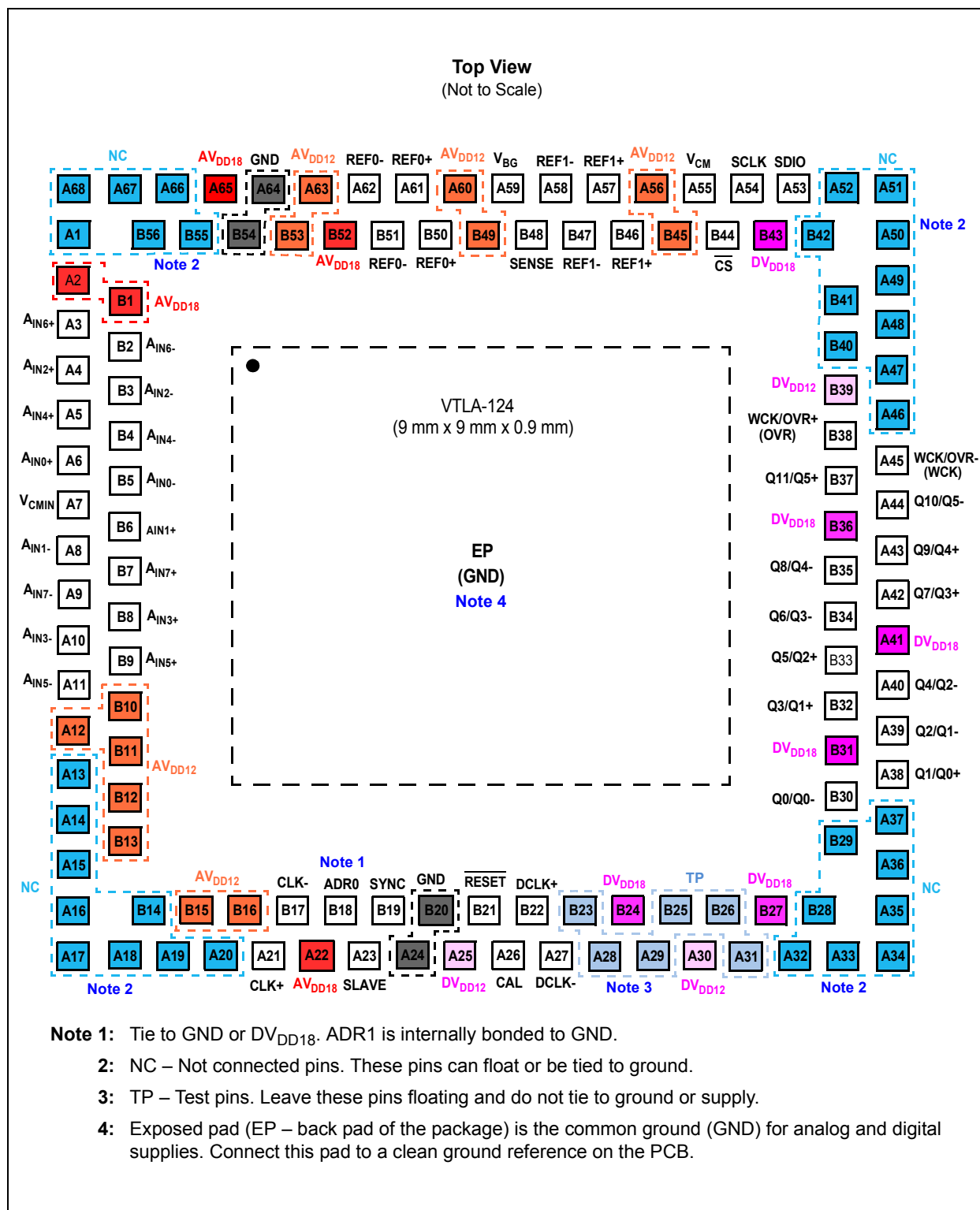
**TABLE 1-1: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
K10	GND	Supply	Common ground for analog and digital sections
K11			
L1	TP	Digital Output	Output test pints. Leave these pins floating always <sup>(8)</sup>
L2			
L3			
L4	DCLK-		<b>LVDS:</b> Differential digital clock output (+) <b>CMOS:</b> Digital clock output <sup>(7)</sup>
L5	RESET	Digital Input	Reset control input: <b>High:</b> Normal operating mode <b>Low:</b> Reset mode <sup>(9)</sup>
L6	SYNC	Digital Input/ Output	Digital synchronization pin for AutoSync. <sup>(10)</sup> If not used, leave it floating.
L7	GND	Supply	Common ground for analog and digital sections
L8	CLK+	Analog Input	Differential clock input (+)
L9	CLK-		Differential clock input (-)
L10	GND	Supply	Common ground for analog and digital sections
L11	AV <sub>DD18</sub>	Analog Input	Supply voltage input (1.8V) for analog section

## Notes:

- When the  $V_{CM}$  output is used for the common-mode voltage of analog inputs (i.e. by connecting to the center-tap of a balun), the  $V_{CM}$  pin should be decoupled with a 0.1  $\mu$ F capacitor, and should be directly tied to the  $V_{CMIN+}$  and  $V_{CMIN-}$  pins.
- CMOS output mode:** WCK/OVR- is WCK and WCK/OVR+ is OVR.  
**DDR LVDS output mode:** The rising edge of DCLK+ is WCK and the falling edge is OVR.  
**OVR:** OVR will be held "High" when analog input overrange is detected. Digital signal post-processing will cause OVR to assert early relative to the output data. See Figure 2-2 for LVDS timing of these bits.  
**WCK:** WCK is normally "Low". WCK is "High" while data from the first channel is sent out. In single-channel mode, WCK stays "High" except when in I/Q output mode. See Section 4.12.4 "Word Clock (WCK)" for further WCK description.
- DDR LVDS:** Two data bits are multiplexed onto each differential output pair. The output pins shown here are for the "Even bit first", which is the default setting of OUTPUT\_MODE<1:0> in Address 0x62 (Register 5-20). The even data bits (Q0, Q2, Q4, Q6, Q8, Q10) appear when DCLK+ is "High". The odd data bits (Q1, Q3, Q5, Q7, Q9, Q11) appear when DCLK+ is "Low". See Addresses 0x65 (Register 5-23) and 0x68 (Register 5-26) for output polarity control. See Figure 2-2 for LVDS output timing diagram.
- $V_{CMIN}$  is used for Auto-Calibration only.  $V_{CMIN+}$  and  $V_{CMIN-}$  should be tied together always. There should be no voltage difference between the two pins. Typically both  $V_{CMIN+}$  and  $V_{CMIN-}$  are tied to the  $V_{CM}$  output pin together, but they can be tied to another common-mode voltage if external  $V_{CM}$  is used. This pin has High Z input in Shutdown, Standby and Reset modes.
- CAL pin stays "Low" at power-up until the first power-up calibration is completed. When the first calibration has completed, this pin has "High" output. It stays "High" until the internal calibration is restarted by hardware or a soft reset command. In Reset mode, this pin is "Low". In Standby and Shutdown modes, this pin will maintain the prior condition.
- If the SPI address is dynamically controlled, the Address pin must be held constant while  $\overline{CS}$  is "Low".
- The phase of DCLK relative to the data output bits may be adjusted depending on the operating mode. This is controlled differently depending on the configuration of the digital signal post-processing, PLL and/or DLL. Also see Addresses 0x52, 0x64 and 0x6D (Registers 5-7, 5-22 and 5-28) for more details.
- Do not tie to ground or supply.
- The device is in Reset mode while this pin stays "Low". On the rising edge of  $\overline{RESET}$ , the device exits Reset mode, initializes all internal user registers to default values, and begins power-up calibration.
- a) SLAVE = "High": The device is selected as slave and the SYNC pin becomes input pin.  
b) SLAVE = "Low": The device is selected as master and the SYNC pin becomes output pin. In SLAVE/SYNC operation, master and slave devices are synchronized to the same clock.

# MCP37211-200 AND MCP37D11-200



**FIGURE 1-2:** VTLA-124 Package. See Table 1-2 for the pin descriptions. Decoupling capacitors for reference pins and V<sub>BG</sub> are embedded in the package. Leave TP pins floating always.

# MCP37211-200 AND MCP37D11-200

**TABLE 1-2: PIN FUNCTION TABLE FOR VTLA-124**

Pin No.	Name	I/O Type	Description
Power Supply Pins			
A2, A22, A65, B1, B52	AV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for analog section
A12, A56, A60, A63, B10, B11, B12, B13, B15, B16, B45, B49, B53	AV <sub>DD12</sub>		Supply voltage input (1.2V) for analog section
A25, A30, B39	DV <sub>DD12</sub>		Supply voltage input (1.2V) for digital section
A41, B24, B27, B31, B36, B43	DV <sub>DD18</sub>		Supply voltage input (1.8V) for digital section and all digital I/O
EP	GND		Exposed pad: Common ground pin for digital and analog sections
ADC Analog Input Pins			
A3	A <sub>IN6+</sub>	Analog Input	Channel 6 differential analog input (+)
B2	A <sub>IN6-</sub>		Channel 6 differential analog input (-)
A4	A <sub>IN2+</sub>		Channel 2 differential analog input (+)
B3	A <sub>IN2-</sub>		Channel 2 differential analog input (-)
A5	A <sub>IN4+</sub>		Channel 4 differential analog input (+)
B4	A <sub>IN4-</sub>		Channel 4 differential analog input (-)
A6	A <sub>IN0+</sub>		Channel 0 differential analog input (+)
B5	A <sub>IN0-</sub>		Channel 0 differential analog input (-)
B6	A <sub>IN1+</sub>		Channel 1 differential analog input (+)
A8	A <sub>IN1-</sub>		Channel 1 differential analog input (-)
B7	A <sub>IN7+</sub>		Channel 7 differential analog input (+)
A9	A <sub>IN7-</sub>		Channel 7 differential analog input (-)
B8	A <sub>IN3+</sub>		Channel 3 differential analog input (+)
A10	A <sub>IN3-</sub>		Channel 3 differential analog input (-)
B9	A <sub>IN5+</sub>		Channel 5 differential analog input (+)
A11	A <sub>IN5-</sub>		Channel 5 differential analog input (-)
A21	CLK+		Differential clock input (+)
B17	CLK-	Differential clock input (-)	
Reference Pins <sup>(1)</sup>			
A57, B46	REF1+	Analog Output	Differential reference 1 (+) voltage
A58, B47	REF1-		Differential reference 1 (-) voltage
A61, B50	REF0+		Differential reference 0 (+) voltage
A62, B51	REF0-		Differential reference 0 (-) voltage
SENSE, Bandgap and Common-Mode Voltage Pins			
B48	SENSE	Analog Input	Analog input full-scale range selection. See <a href="#">Table 4-2</a> for SENSE voltage settings.
A59	V <sub>BG</sub>	Analog Output	Internal bandgap output voltage Connect a decoupling capacitor (2.2 μF)
A7	V <sub>CMIN</sub>	Analog Input	Common-mode voltage input for auto-calibration Connect V <sub>CM</sub> voltage <sup>(2)</sup>
A55	V <sub>CM</sub>		Common-mode output voltage (900 mV) for analog input signal Connect a decoupling capacitor (0.1 μF) <sup>(3)</sup>

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TABLE 1-2: PIN FUNCTION TABLE FOR VTLA-124 (CONTINUED)

Pin No.	Name	I/O Type	Description
Digital I/O Pins			
B18	ADR0	Digital Input	SPI address selection pin (A0 bit). Tie to GND or DV <sub>DD18</sub> . <sup>(4)</sup>
A23	SLAVE		Slave or Master selection pin in AutoSync <sup>(11)</sup> If not used, tie to GND.
B19	SYNC	Digital Input/ Output	Digital synchronization pin for AutoSync <sup>(11)</sup> If not used, leave it floating.
B21	RESET	Digital Input	Reset control input: <b>High:</b> Normal operating mode <b>Low:</b> Reset mode <sup>(5)</sup>
A26	CAL	Digital Output	Calibration status flag digital output: <b>High:</b> Calibration is complete <b>Low:</b> Calibration is not complete <sup>(5)</sup>
B22	DCLK+		<b>LVDS:</b> Differential digital clock output (+) <b>CMOS:</b> Digital clock output <sup>(7)</sup>
A27	DCLK-		<b>LVDS:</b> Differential digital clock output (-) <b>CMOS:</b> Unused (leave floating)
ADC Output Pins <sup>(8)</sup>			
B30	Q0/Q0-	Digital Output	Digital data output: CMOS = Q0, DDR LVDS = Q0-
A38	Q1/Q0+		Digital data output: CMOS = Q1, DDR LVDS = Q0+
A39	Q2/Q1-		Digital data output: CMOS = Q2, DDR LVDS = Q1-
B32	Q3/Q1+		Digital data output: CMOS = Q3, DDR LVDS = Q1+
A40	Q4/Q2-		Digital data output: CMOS = Q4, DDR LVDS = Q2-
B33	Q5/Q2+		Digital data output: CMOS = Q5, DDR LVDS = Q2+
B34	Q6/Q3-		Digital data output: CMOS = Q6, DDR LVDS = Q3-
A42	Q7/Q3+		Digital data output: CMOS = Q7, DDR LVDS = Q3+
B35	Q8/Q4-		Digital data output: CMOS = Q8, DDR LVDS = Q4-
A43	Q9/Q4+		Digital data output: CMOS = Q9, DDR LVDS = Q4+
A44	Q10/Q5-		Digital data output: CMOS = Q10, DDR LVDS = Q5-
B37	Q11/Q5+		Digital data output: CMOS = Q11, DDR LVDS = Q5+
B38	WCK/OVR+ (OVR)		<b>WCK:</b> Word clock sync digital output <b>OVR:</b> Input over-range indication digital output <sup>(10)</sup>
A45	WCK/OVR- (WCK)		
SPI Interface Pins			
A53	SDIO	Digital Input/ Output	SPI data input/output
A54	SCLK	Digital Input	SPI serial clock input
B44	CS		SPI Chip Select input
Not Connected Pins			
A1, A13 - A20, A32 - A37, A46 - A52, A66 - A68, B14, B28, B29, B40, B41, B42, B55, B56	NC		These pins can be tied to ground or left floating.
Pins that need to be grounded			
A24, A64, B20, B54	GND		These pins are not supply pins, but need to be tied to ground.
Output Test Pins			
A28, A29, A31, B23, B25, B26	TP	Digital Output	Output test pins. Do not use. Always Leave these pins floating. <sup>(9)</sup>

# MCP37211-200 AND MCP37D11-200

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## Notes:

1. These pins are for the internal reference voltage outputs. They should not be driven. External decoupling circuits are required. See [Section 4.5.3, "Decoupling Circuits for Internal Voltage Reference and Bandgap Output"](#) for details.
2.  $V_{CMIN}$  is used for Auto-Calibration only.  $V_{CMIN+}$  and  $V_{CMIN-}$  should be tied together always. There should be no voltage difference between the two pins. Typically both  $V_{CMIN+}$  and  $V_{CMIN-}$  are tied to the  $V_{CM}$  output pin together, but they can be tied to another common-mode voltage if external  $V_{CM}$  is used. This pin has High Z input in Shutdown, Standby and Reset modes.
3. When the  $V_{CM}$  output is used for the common-mode voltage of analog inputs (i.e. by connecting to the center-tap of a balun), the  $V_{CM}$  pin should be decoupled with a 0.1  $\mu$ F capacitor, and should be directly tied to the  $V_{CMIN+}$  and  $V_{CMIN-}$  pins.
4.  $ADR1$  (for  $A1$  bit) is internally bonded to GND ('0'). If  $ADR0$  is dynamically controlled,  $ADR0$  must be held constant while  $CS$  is "Low".
5. The device is in Reset mode while this pin stays "Low". On the rising edge of  $\overline{RESET}$ , the device exits Reset mode, initializes all internal user registers to default values, and begins power-up calibration.
6.  $CAL$  pin stays "Low" at power-up until the first power-up calibration is completed. When the first calibration has completed, this pin has "High" output. It stays "High" until the internal calibration is restarted by hardware or a soft reset command. In Reset mode, this pin is "Low". In Standby and Shutdown modes, this pin will maintain the prior condition.
7. The phase of  $DCLK$  relative to the data output bits may be adjusted depending on the operating mode. This is controlled differently depending on the configuration of the digital signal post-processing, PLL and/or DLL. Also see Addresses 0x52, 0x64 and 0x6D ([Registers 5-7, 5-22 and 5-28](#)) for more details.
8. **DDR LVDS:** Two data bits are multiplexed onto each differential output pair. The output pins shown here are for the "Even bit first", which is the default setting of  $OUTPUT\_MODE<1:0>$  in Address 0x62 ([Register 5-20](#)). The even data bits (Q0, Q2, Q4, Q6, Q8, Q10) appear when  $DCLK+$  is "High". The odd data bits (Q1, Q3, Q5, Q7, Q9, Q11) appear when  $DCLK+$  is "Low". See Addresses 0x65 ([Register 5-23](#)) and 0x68 ([Register 5-26](#)) for output polarity control. See [Figure 2-2](#) for LVDS output timing diagram.
9. Do not tie to ground or supply.
10. **CMOS output mode:**  $WCK/OVR-$  is  $WCK$  and  $WCK/OVR+$  is  $OVR$ .  
**DDR LVDS output mode:** The rising edge of  $DCLK+$  is  $WCK$  and the falling edge is  $OVR$ .  
**OVR:**  $OVR$  will be held "High" when analog input overrange is detected. Digital signal post-processing will cause  $OVR$  to assert early relative to the output data. See [Figure 2-2](#) for LVDS timing of these bits.  
**WCK:**  $WCK$  is normally "Low".  $WCK$  is "High" while data from the first channel is sent out. In single-channel mode,  $WCK$  stays "High" except when in I/Q output mode. See [Section 4.12.4 "Word Clock \(WCK\)"](#) for further  $WCK$  description.
11. (a)  $SLAVE = "High"$ : The device is selected as slave and the  $SYNC$  pin becomes input pin.  
(b)  $SLAVE = "Low"$ : The device is selected as master and the  $SYNC$  pin becomes output pin. In  $SLAVE/SYNC$  operation, master and slave devices are synchronized to the same clock.

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NOTES:

# MCP37211-200 AND MCP37D11-200

## 2.0 ELECTRICAL SPECIFICATIONS

### 2.1 Absolute Maximum Ratings†

Analog and Digital Supply Voltage (AV <sub>DD12</sub> , DV <sub>DD12</sub> )	-0.3V to 1.32V
Analog and Digital Supply Voltage (AV <sub>DD18</sub> , DV <sub>DD18</sub> )	-0.3V to 1.98V
All Inputs and Outputs with respect to GND	-0.3V to AV <sub>DD18</sub> + 0.3V
Differential Input Voltage	AV <sub>DD18</sub> - GND
Current at Input Pins	±2 mA
Current at Output and Supply Pins	±250 mA
Storage Temperature	-65°C to +150°C
Ambient Temperature with Power Applied (T <sub>A</sub> )	-55°C to +125°C
Maximum Junction Temperature (T <sub>J</sub> )	+150°C
ESD Protection	2kV HBM on all pins, CDM: 750V on corner pins and 250V on all other pins
Solder Reflow Profile	See Microchip Application Note AN233 (DS00233)

**Notice†:** Stresses above those listed under “Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

### 2.2 Electrical Specifications

**TABLE 2-1: ELECTRICAL CHARACTERISTICS**

**Electrical Specifications:** Unless otherwise specified, all parameters apply for T<sub>A</sub> = -40°C to +125°C, AV<sub>DD18</sub> = DV<sub>DD18</sub> = 1.8V, AV<sub>DD12</sub> = DV<sub>DD12</sub> = 1.2V, GND = 0V, SENSE = AV<sub>DD12</sub>, Single-channel mode, Differential Analog Input (A<sub>IN</sub>) = Sine wave with amplitude of -1 dBFS, f<sub>IN</sub> = 70 MHz, Clock Input = 200 MHz, f<sub>S</sub> = 200 Msps (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100Ω termination, LVDS driver current setting = 3.5 mA, +25°C is applied for typical value.

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Power Supply Requirements						
Analog Supply Voltage	AV <sub>DD18</sub>	1.71	1.8	1.89	V	
	AV <sub>DD12</sub>	1.14	1.2	1.26	V	
Digital Supply Voltage	DV <sub>DD18</sub>	1.71	1.8	1.89	V	Note 1
	DV <sub>DD12</sub>	1.14	1.2	1.26	V	
Analog Supply Current During Conversion						
At AV <sub>DD18</sub> Pin	I <sub>DD_A18</sub>	— —	27 27	46 50	mA	T <sub>A</sub> = -40°C to +85°C T <sub>A</sub> = -40°C to +125°C
At AV <sub>DD12</sub> Pin	I <sub>DD_A12</sub>	— —	185 185	252 300	mA	T <sub>A</sub> = -40°C to +85°C T <sub>A</sub> = -40°C to +125°C
Digital Supply Current						
Digital Supply Current During Conversion at DV <sub>DD12</sub> Pin	I <sub>DD_D12</sub>	— —	97 97	226 232	mA	T <sub>A</sub> = -40°C to +85°C T <sub>A</sub> = -40°C to +125°C
Digital I/O Current in CMOS Output Mode	I <sub>DD_D18</sub>	—	27	—	mA	at DV <sub>DD18</sub> pin DCLK = 100 MHz
Digital I/O Current in LVDS Mode	I <sub>DD_D18</sub>	Measured at DV <sub>DD18</sub> Pin				
		—	45	66	mA	3.5 mA mode
			33	—	mA	1.8 mA mode
			57		5.4 mA mode	
Supply Current during Power-Saving Modes						
During Standby Mode	I <sub>STANDBY_AN</sub>	—	84	—	mA	Address 0x00<4:3> = 1, 1 <sup>(2)</sup>
	I <sub>STANDBY_DIG</sub>	—	36	—		
During Shutdown Mode	I <sub>DD_SHDN</sub>	—	23	—	mA	Address 0x00<7,0> = 1, 1 <sup>(3)</sup>

# MCP37211-200 AND MCP37D11-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

**Electrical Specifications:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $GND = 0\text{V}$ ,  $SENSE = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS,  $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz,  $f_S = 200\text{ Msps}$  (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$  termination, LVDS driver current setting = 3.5 mA,  $+25^{\circ}\text{C}$  is applied for typical value.

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
PLL Circuit						
PLL Circuit Current	I <sub>DD_PLL</sub>	—	17	—	mA	PLL enabled. Included in analog supply current specification.
Total Power Dissipation <sup>(4)</sup>						
Power Dissipation During Conversion, Excluding Digital I/O	P <sub>DISS_ADC</sub>	—	387	—	mW	
Total Power Dissipation During Conversion with CMOS Output Mode	P <sub>DISS_CMOS</sub>	—	436	—	mW	f <sub>S</sub> = 200 Msps, DCLK = 100 MHz
Total Power Dissipation During Conversion with LVDS Output Mode	P <sub>DISS_LVDS</sub>	—	468	—	mW	3.5 mA mode
			446	—		1.8 mA mode
			490	—		5.4 mA mode
During Standby Mode	P <sub>DISS_-STANDBY</sub>	—	144	—	mW	Address 0x00<4:3> = 1, 1 <sup>(2)</sup>
During Shutdown Mode	P <sub>DISS_SHDN</sub>	—	27.6	—	mW	Address 0x00<7,0> = 1, 1 <sup>(3)</sup>
Power-on Reset (POR) Voltage						
Threshold Voltage	V <sub>POR</sub>	—	800	—	mV	Applicable to AV <sub>DD12</sub> only (POR tracks AV <sub>DD12</sub> )
Hysteresis	V <sub>POR_HYST</sub>	—	40	—	mV	
Power-on Reset Stabilization Time	T <sub>POR-S</sub>	—	2 <sup>18</sup>	—	Clocks	2 <sup>18</sup> sample clocks after Power-on Reset
SENSE Input <sup>(5,7)</sup>						
SENSE Input Voltage	V <sub>SENSE</sub>	GND	—	AV <sub>DD12</sub>	V	V <sub>SENSE</sub> selects reference
SENSE Pin Input Resistance	R <sub>IN_SENSE</sub>	—	500	—	Ω	To virtual ground at 0.55V. 400 mV < V <sub>SENSE</sub> < 800 mV
Current Sink into SENSE Pin	I <sub>SENSE</sub>	—	4.5	—	μA	SENSE = 1.2V
			636			SENSE = 0.8V
			-2			SENSE = 0V
Reference and Common-Mode Voltages						
Internal Reference Voltage (Selected by V <sub>SENSE</sub> )	V <sub>REF</sub>	—	0.74	—	V	V <sub>SENSE</sub> = GND
		—	1.49	—		V <sub>SENSE</sub> = AV <sub>DD12</sub>
		—	1.86 x V <sub>SENSE</sub>	—		400 mV < V <sub>SENSE</sub> < 800 mV
Common-Mode Voltage Output	V <sub>CM</sub>	—	0.9	—	V	Available at V <sub>CM</sub> pin
Reference Voltage Output <sup>(7,8)</sup>	V <sub>REF1</sub>	—	0.4	—	V	V <sub>SENSE</sub> = GND
		—	0.8	—		V <sub>SENSE</sub> = AV <sub>DD12</sub>
		—	0.4 - 0.8	—		400 mV < V <sub>SENSE</sub> < 800 mV
	V <sub>REF0</sub>	—	0.7	—	V	V <sub>SENSE</sub> = GND
		—	1.4	—		V <sub>SENSE</sub> = AV <sub>DD12</sub>
		—	0.7 - 1.4	—		400 mV < V <sub>SENSE</sub> < 800 mV
Bandgap Voltage Output	V <sub>BG</sub>	—	0.55	—	V	Available at V <sub>BG</sub> pin



# MCP37211-200 AND MCP37D11-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msps}$ (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Analog Inputs</b>						
Full-Scale Differential Analog Input Range <sup>(5,7)</sup>	$A_{FS}$	—	1.4875	—	$V_{P-P}$	$V_{SENSE} = \text{GND}$
		—	2.975	—		$V_{SENSE} = AV_{DD12}$
		—	$3.71875 \times V_{SENSE}$	—		$400\text{ mV} < V_{SENSE} < 800\text{ mV}$
Analog Input Bandwidth	$f_{IN\_3dB}$	—	500	—	MHz	$A_{IN} = -3\text{ dBFS}$
Differential Input Capacitance	$C_{IN}$	5	6	7	pF	Note 5, Note 9
Analog Input Channel Cross-Talk	XTALK	—	100	—	dBc	Note 10
Analog Input Leakage Current ( $A_{IN+}$ , $A_{IN-}$ Pins)	$I_{LI\_AH}$	—	—	+1	$\mu\text{A}$	$V_{IH} = AV_{DD12}$
	$I_{LI\_AL}$	-1	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}$
<b>ADC Conversion Rate<sup>(11)</sup></b>						
Conversion Rate	$f_S$	40	—	200	MspS	Tested at 200 MspS
<b>Clock Inputs (CLK+, CLK-)<sup>(12)</sup></b>						
Clock Input Frequency	$f_{CLK}$	—	—	250	MHz	Note 5
Differential Input Voltage	$V_{CLK\_IN}$	300	—	800	mV <sub>P-P</sub>	Note 5
Clock Jitter	$CLK_{JITTER}$	—	175	—	$f_{SRMS}$	Note 5
Clock Input Duty Cycle <sup>(5)</sup>		49	50	51	%	Duty cycle correction disabled
		30	50	70	%	Duty cycle correction enabled
Input Leakage Current at CLK Input Pin	$I_{LI\_CLKH}$	—	—	+180	$\mu\text{A}$	$V_{IH} = AV_{DD12}$
	$I_{LI\_CLKL}$	-20 -30	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}$ $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$
<b>Converter Accuracy<sup>(6)</sup></b>						
ADC Resolution (with no missing code)		—	—	12	bits	
Offset Error		—	$\pm 0.31$	$\pm 3.8$	LSb	
Gain Error	$G_{ER}$	—	$\pm 0.5$	—	% of FS	
Integral Nonlinearity	INL	—	$\pm 0.125$	—	LSb	
Differential Nonlinearity	DNL	—	$\pm 0.03$	—	LSb	
Analog Input Common-Mode Rejection Ratio	$CMRR_{DC}$	—	70	—	dB	DC measurement

# MCP37211-200 AND MCP37D11-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msps}$ (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Dynamic Accuracy<sup>(6,15)</sup></b>						
Spurious Free Dynamic Range	SFDR	78	90	—	dBc	$f_{IN} = 15\text{ MHz}$
		77	85	—	dBc	$f_{IN} = 70\text{ MHz}$
Signal-to-Noise Ratio	SNR	70.63	71.33	—	dBFS	$f_{IN} = 15\text{ MHz}$
	SNR	—	71.09	—	dBFS	$f_{IN} = 70\text{ MHz}$
Effective Number of Bits (ENOB) <sup>(13)</sup>	ENOB	11.44	11.56	—	bits	$f_{IN} = 15\text{ MHz}$
	ENOB	—	11.52	—	bits	$f_{IN} = 70\text{ MHz}$
Total Harmonic Distortion (for all resolutions, first 13 harmonics)	THD	78	89	—	dBc	$f_{IN} = 15\text{ MHz}$
		77	82	—	dBc	$f_{IN} = 70\text{ MHz}$
Worst Second or Third Harmonic Distortion	HD2 or HD3	—	90	—	dBc	$f_{IN} = 15\text{ MHz}$
		—	83	—	dBc	$f_{IN} = 70\text{ MHz}$
Two-Tone Intermodulation Distortion $f_{IN1} = 17.6\text{ MHz}$ , $f_{IN2} = 20.6\text{ MHz}$	IMD	—	90.5	—	dBc	$A_{IN} = -7\text{ dBFS}$ , with two input frequencies
<b>Digital Logic Input and Output (Except LVDS Output)</b>						
Schmitt Trigger High-Level Input Voltage	$V_{IH}$	0.7 $DV_{DD18}$	—	$DV_{DD18}$	V	
Schmitt Trigger Low-Level Input Voltage	$V_{IL}$	GND	—	0.3 $DV_{DD18}$	V	
Hysteresis of Schmitt Trigger Inputs (All Digital Inputs)	$V_{HYST}$	—	0.05 $DV_{DD18}$	—	V	
Low-Level Output Voltage	$V_{OL}$	—	—	0.3	V	$I_{OL} = -3\text{ mA}$ , all digital I/O pins
High-Level Output Voltage	$V_{OH}$	$DV_{DD18} - 0.5$	1.8	—	V	$I_{OL} = +3\text{ mA}$ , all digital I/O pins
<b>Digital Data Output (CMOS Mode)</b>						
Maximum External Load Capacitance	$C_{LOAD}$	—	10	—	pF	From output pin to GND
Internal I/O Capacitance	$C_{INT}$	—	4	—	pF	<b>Note 5</b>
<b>Digital Data Output (LVDS Mode)<sup>(5)</sup></b>						
LVDS High-Level Differential Output Voltage	$V_{H\_LVDS}$	200	300	400	mV	100 $\Omega$ differential termination, LVDS bias = 3.5 mA
LVDS Low-Level Differential Output Voltage	$V_{L\_LVDS}$	-400	-300	-200	mV	100 $\Omega$ differential termination, LVDS bias = 3.5 mA
LVDS Common-Mode Voltage	$V_{CM\_LVDS}$	1	1.15	1.4	V	
Output Capacitance	$C_{INT\_LVDS}$	—	4	—	pF	Internal capacitance from output pin to GND
Differential Load Resistance (LVDS)	$R_{LVDS}$	—	100	—	$\Omega$	Across LVDS output pairs

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**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msps}$ (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Input Leakage Current on Digital I/O Pins</b>						
Data Output Pins	$I_{LI\_DH}$	—	—	+1	$\mu\text{A}$	$V_{IH} = DV_{DD18}$
	$I_{LI\_DL}$	-1 -1.2	— —	— —	$\mu\text{A}$	$V_{IL} = \text{GND}$ $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ $T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$
I/O Pins except Data Output Pins	$I_{LI\_DH}$	—	—	+6	$\mu\text{A}$	$V_{IH} = DV_{DD18}$
	$I_{LI\_DL}$	-35	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}^{(14)}$

**Notes:**

- This 1.8V digital supply voltage is used for the digital I/O circuit, including SPI, CMOS and LVDS data output drivers.
- Standby Mode: Most of the internal circuits are turned off, except the internal reference, clock, bias circuits and SPI interface.
- Shutdown Mode: All circuits including reference and clock are turned off except the SPI interface.
- Power dissipation (typical) is calculated by using the following equation:  
 (a) During operation:  
 $P_{DISS} = V_{DD18} \times (I_{DD\_A18} + I_{DD\_D18}) + V_{DD12} \times (I_{DD\_A12} + I_{DD\_D12})$ , where  $I_{DD\_D18}$  is the digital I/O current for LVDS or CMOS output.  $V_{DD18} = 1.8\text{V}$  and  $V_{DD12} = 1.2\text{V}$  are used for typical value calculation.  
 (b) During Standby mode:  
 $P_{DISS\_STANDBY} = (I_{STANDBY\_AN} + I_{STANDBY\_DIG}) \times 1.2\text{V}$   
 (c) During Shutdown mode:  
 $P_{DISS\_SHDN} = I_{DD\_SHDN} \times 1.2\text{V}$
- This parameter is ensured by design, but not 100% tested in production.
- This parameter is ensured by characterization, but not 100% tested in production.
- See [Table 4-2](#) for details.
- Differential reference voltage output at REF1+/- and REF0+/- pins.  $V_{REF1} = V_{REF1+} - V_{REF1-}$ .  $V_{REF0} = V_{REF0+} - V_{REF0-}$ . These references should not be driven.
- Input capacitance refers to the effective capacitance between one differential input pin pair.
- Channel cross-talk is measured when  $A_{IN} = -1\text{ dBFS}$  at 12 MHz is applied on one channel while other channel(s) are terminated with 50 $\Omega$ . See [Figure 3-45](#) for details.
- The ADC core conversion rate. In multi-channel mode, the conversion rate of an individual channel is  $f_S/N$ , where N is the number of input channels used.
- See [Figure 4-8](#) for the details of the clock input circuit.
- $\text{ENOB} = (\text{SINAD} - 1.76)/6.02$ .
- This leakage current is due to the internal pull-up resistor.
- Dynamic performance is characterized with  $\text{CH}(n)\_DIG\_GAIN<7:0> = 0011-1000$ .

# MCP37211-200 AND MCP37D11-200

**TABLE 2-2: TIMING REQUIREMENTS - LVDS AND CMOS OUTPUTS**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for T <sub>A</sub> = -40°C to +125°C, AV <sub>DD18</sub> = DV <sub>DD18</sub> = 1.8V, AV <sub>DD12</sub> = DV <sub>DD12</sub> = 1.2V, GND = 0V, SENSE = AV <sub>DD12</sub> , Single-channel mode, Differential Analog Input (A <sub>IN</sub> ) = Sine wave with amplitude of -1 dBFS, f <sub>IN</sub> = 70 MHz, Clock Input = 200 MHz, f <sub>S</sub> = 200 Msp/s (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100Ω termination, LVDS driver current setting = 3.5 mA, +25°C is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Aperture Delay	t <sub>A</sub>	—	1	—	ns	<a href="#">Note 1</a>
Out-of-Range Recovery Time	t <sub>OVR</sub>	—	1	—	Clocks	<a href="#">Note 1</a>
Output Clock Duty Cycle		—	50	—	%	<a href="#">Note 1</a>
Pipeline Latency	T <sub>LATENCY</sub>	—	28	—	Clocks	<a href="#">Note 2</a> , <a href="#">Note 4</a>
<b>System Calibration<sup>(1)</sup></b>						
Power-Up Calibration Time	T <sub>PCAL</sub>	—	2 <sup>27</sup>	—	Clocks	First 2 <sup>27</sup> sample clocks after T <sub>POR-S</sub>
Background Calibration Update Rate	T <sub>BCAL</sub>	—	2 <sup>30</sup>	—	Clocks	Per 2 <sup>30</sup> sample clocks after T <sub>PCAL</sub>
$\overline{\text{RESET}}$ Low Time	T <sub>RESET</sub>	5	—	—	ns	See <a href="#">Figure 2-6</a> for details <sup>(1)</sup>
<b>AutoSync<sup>(1,6)</sup></b>						
Sync Output Time Delay	T <sub>SYNC_OUT</sub>	—	1	—	Clocks	
Maximum Recommended ADC Clock Rate for AutoSync		—	200	—	MHz	<b>Single-Channel mode</b>
		—	160	—		T <sub>A</sub> = -40°C to +85°C
		—	160	—		T <sub>A</sub> = -40°C to +125°C
<b>Multi-Channel mode</b>						
<b>LVDS Data Output Mode<sup>(1,5)</sup></b>						
Input Clock to Output Clock Propagation Delay	t <sub>CPD</sub>	—	5.7	—	ns	
Output Clock to Data Propagation Delay	t <sub>DC</sub>	—	0.5	—	ns	
Input Clock to Output Data Propagation Delay	t <sub>PD</sub>	—	5.8	—	ns	
<b>CMOS Data Output Mode</b>						
Input Clock to Output Clock Propagation Delay	t <sub>CPD</sub>	—	3.8	—	ns	
Output Clock to Data Propagation Delay	t <sub>DC</sub>	—	0.7	—	ns	
Input Clock to Output Data Propagation Delay	t <sub>PD</sub>	—	4.5	—	ns	

**Note 1:** This parameter is ensured by design, but not 100% tested in production.

**2:** This parameter is ensured by characterization, but not 100% tested in production.

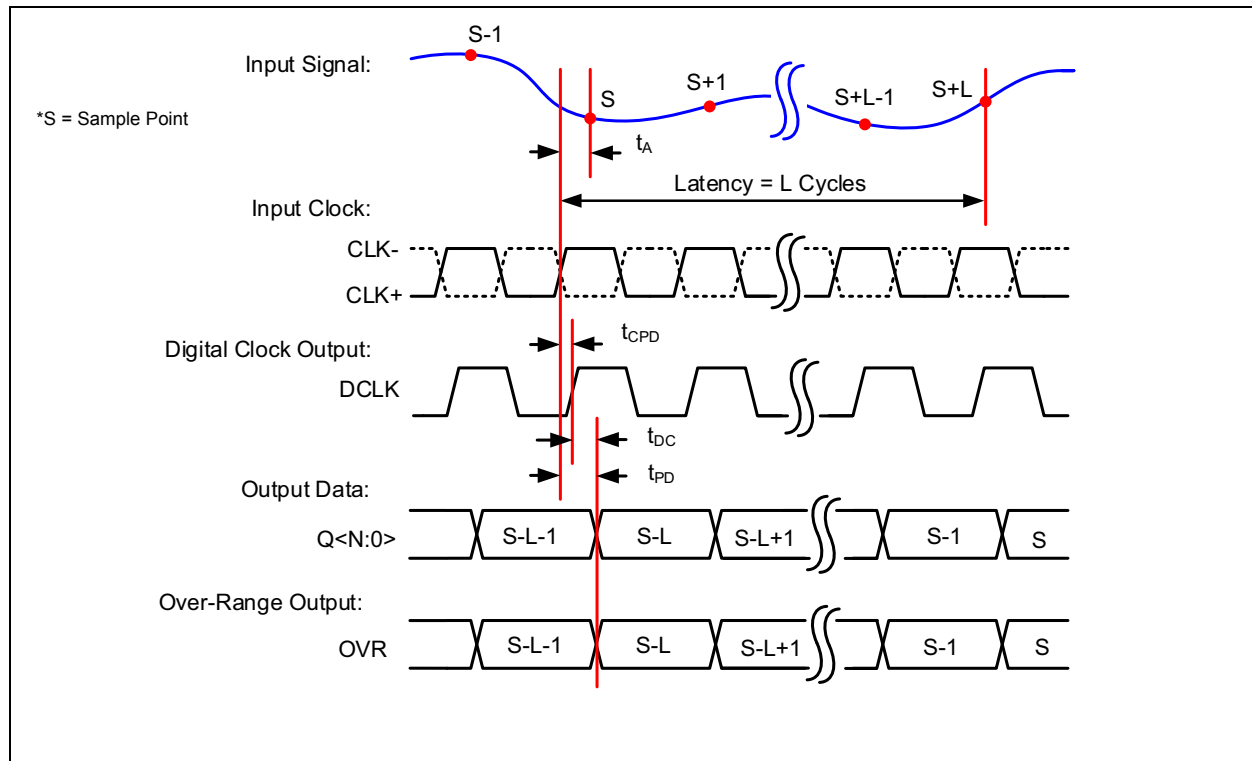
**3:**  $t_{RISE}$  = approximately less than 10% of duty cycle.

**4:** Output latency is measured without using fractional delay recovery (FDR), decimation filter or digital down-converter options.

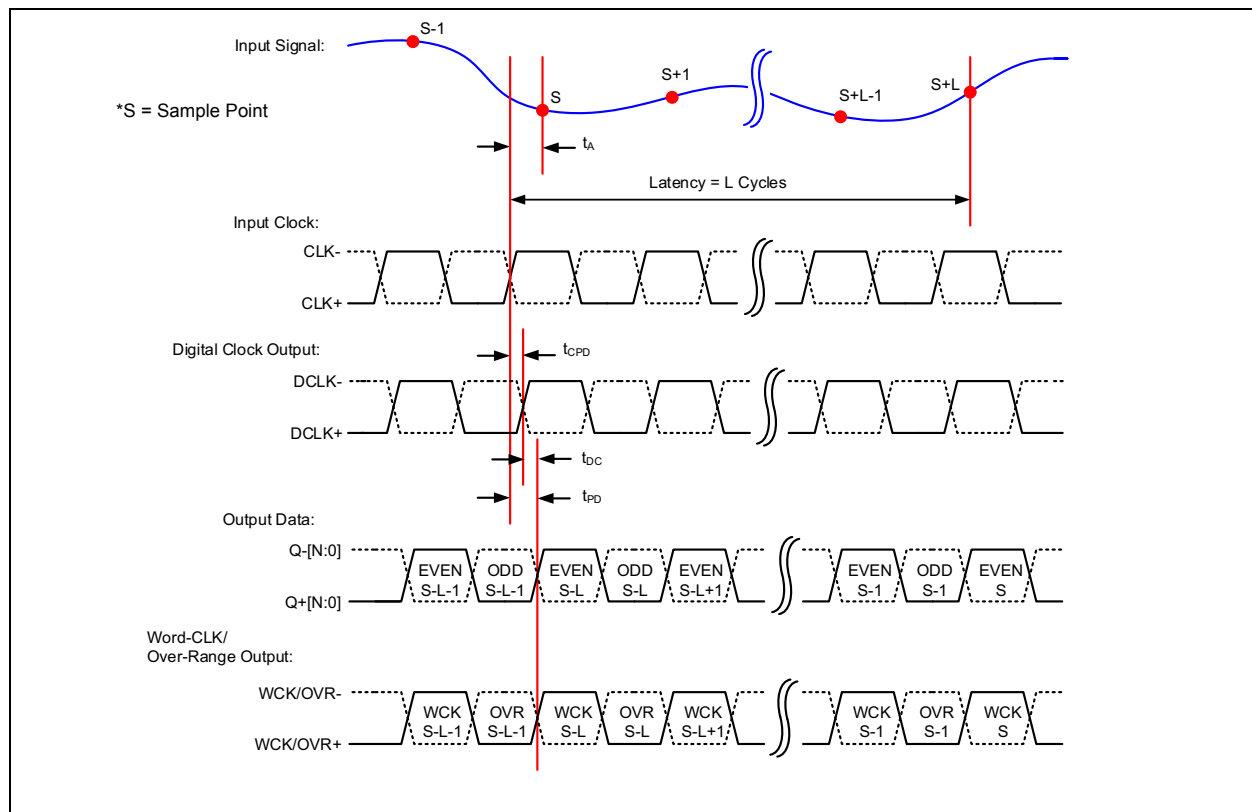
**5:** The time delay can be adjusted with the  $\text{DCLK\_PHDLY\_DLL}<2:0>$  setting.

**6:** Characterized with a single slave device. The maximum ADC sample rate for AutoSync mode may be reduced if multiple slave devices are used. See [Figure 2-7](#) - [Figure 2-9](#), and [Figure 4-28](#) for details.

# MCP37211-200 AND MCP37D11-200



**FIGURE 2-1:** Timing Diagram - CMOS Output.



**FIGURE 2-2:** Timing Diagram - LVDS Output with Even Bit First Option.

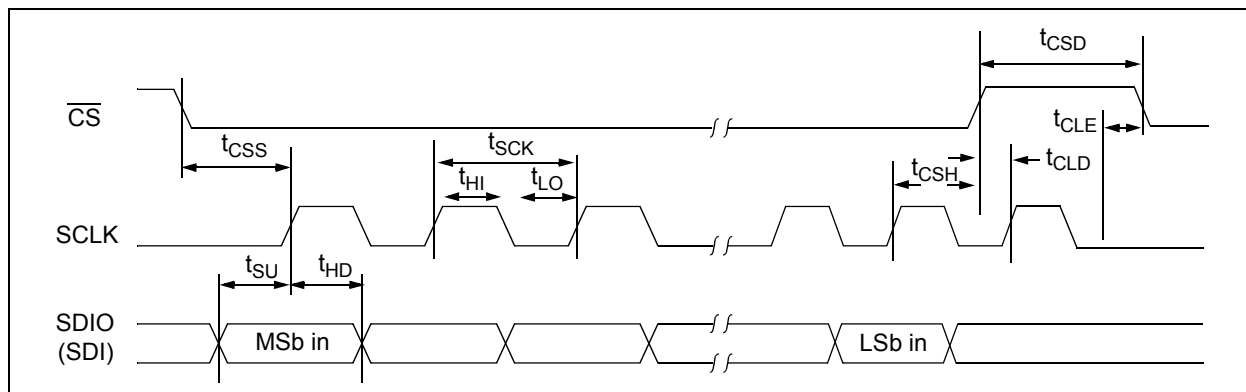
# MCP37211-200 AND MCP37D11-200

**TABLE 2-3: SPI SERIAL INTERFACE TIMING SPECIFICATIONS**

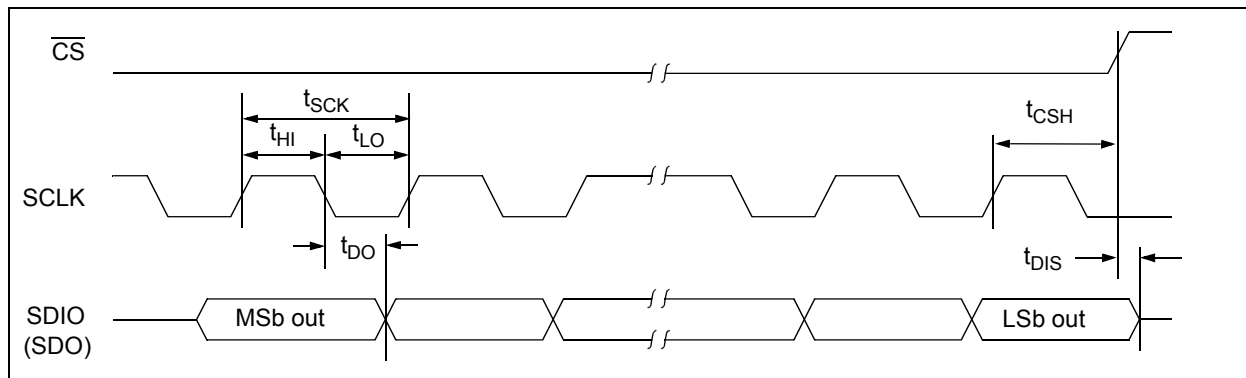
**Electrical Specifications:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS,  $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz,  $f_S = 200\text{ Msp}$ s (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$  termination, LVDS driver current setting = 3.5 mA,  $+25^{\circ}\text{C}$  is applied for typical value. All timings are measured at 50%.

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Serial Clock frequency, <math>f_{\text{SCK}} = 50\text{ MHz}</math></b>						
$\overline{\text{CS}}$ Setup Time	$t_{\text{CSS}}$	10	—	—	ns	
$\overline{\text{CS}}$ Hold Time	$t_{\text{CSH}}$	20	—	—	ns	
$\overline{\text{CS}}$ Disable Time	$t_{\text{CSD}}$	20	—	—	ns	
Data Setup Time	$t_{\text{SU}}$	2	—	—	ns	
Data Hold Time	$t_{\text{HD}}$	4	—	—	ns	
Serial Clock High Time	$t_{\text{HI}}$	8	—	—	ns	
Serial Clock Low Time	$t_{\text{LO}}$	8	—	—	ns	Note 1
Serial Clock Delay Time	$t_{\text{CLD}}$	20	—	—	ns	
Serial Clock Enable Time	$t_{\text{CLE}}$	20	—	—	ns	
Output Valid from SCK Low	$t_{\text{DO}}$	—	—	20	ns	
Output Disable Time	$t_{\text{DIS}}$	—	—	10	ns	Note 1

**Note 1:** This parameter is ensured by design, but not 100% tested.

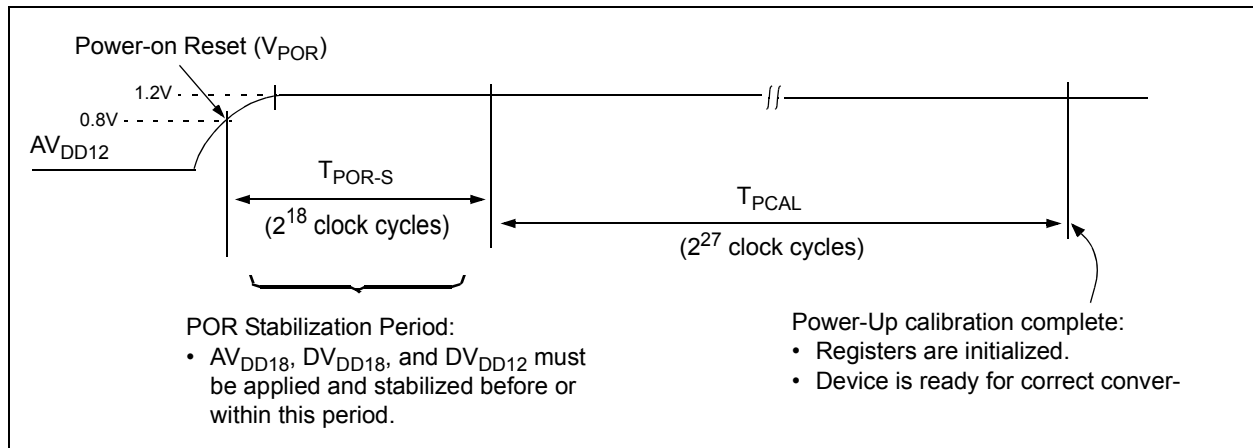


**FIGURE 2-3:** SPI Serial Input Timing Diagram.

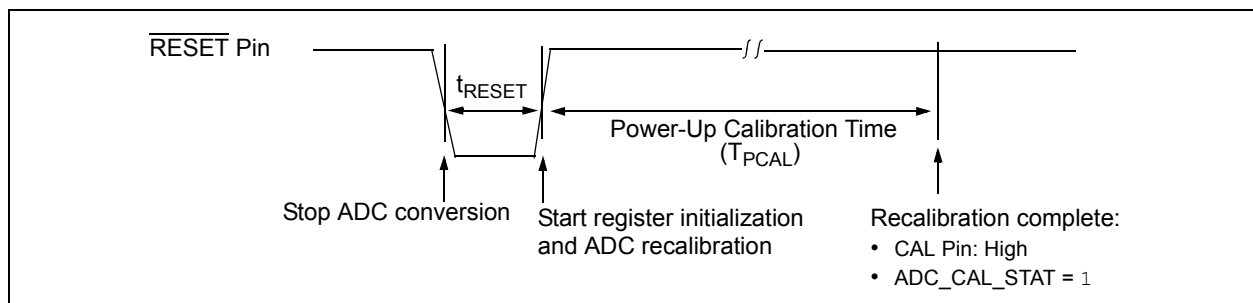


**FIGURE 2-4:** SPI Serial Output Timing Diagram.

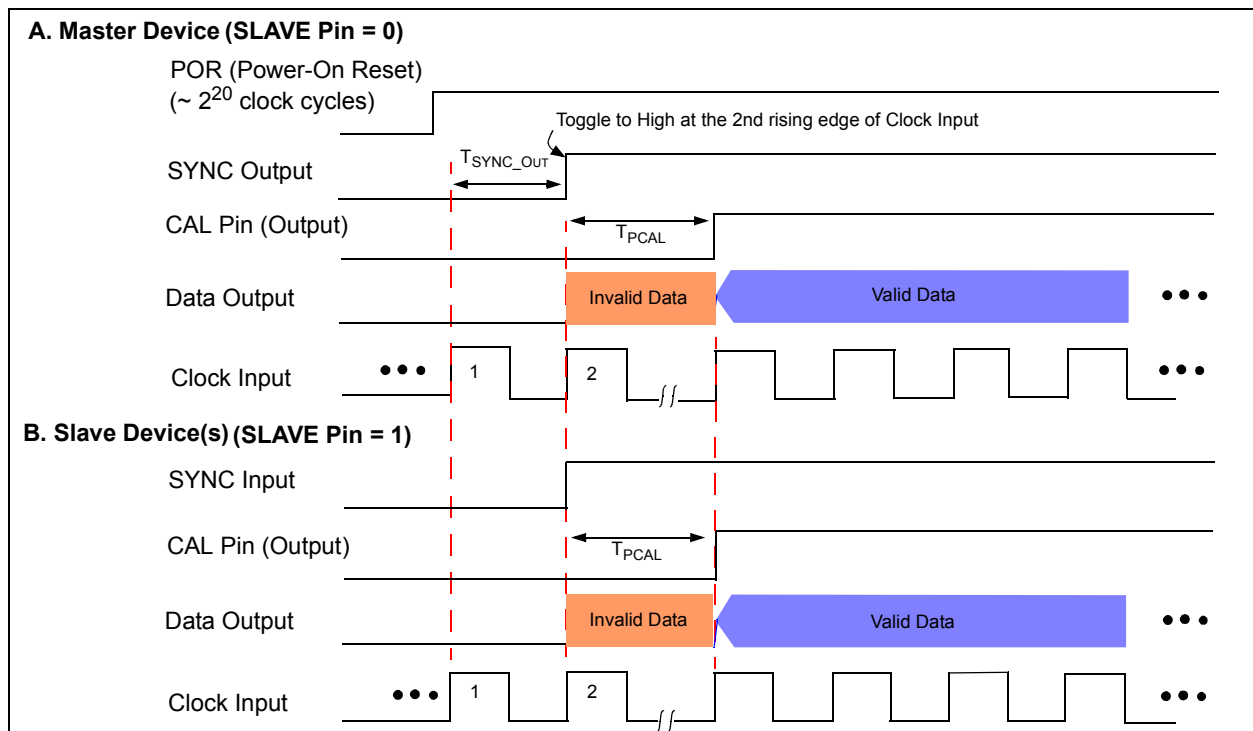
# MCP37211-200 AND MCP37D11-200



**FIGURE 2-5:** Internal Power-Up Sequence Events.

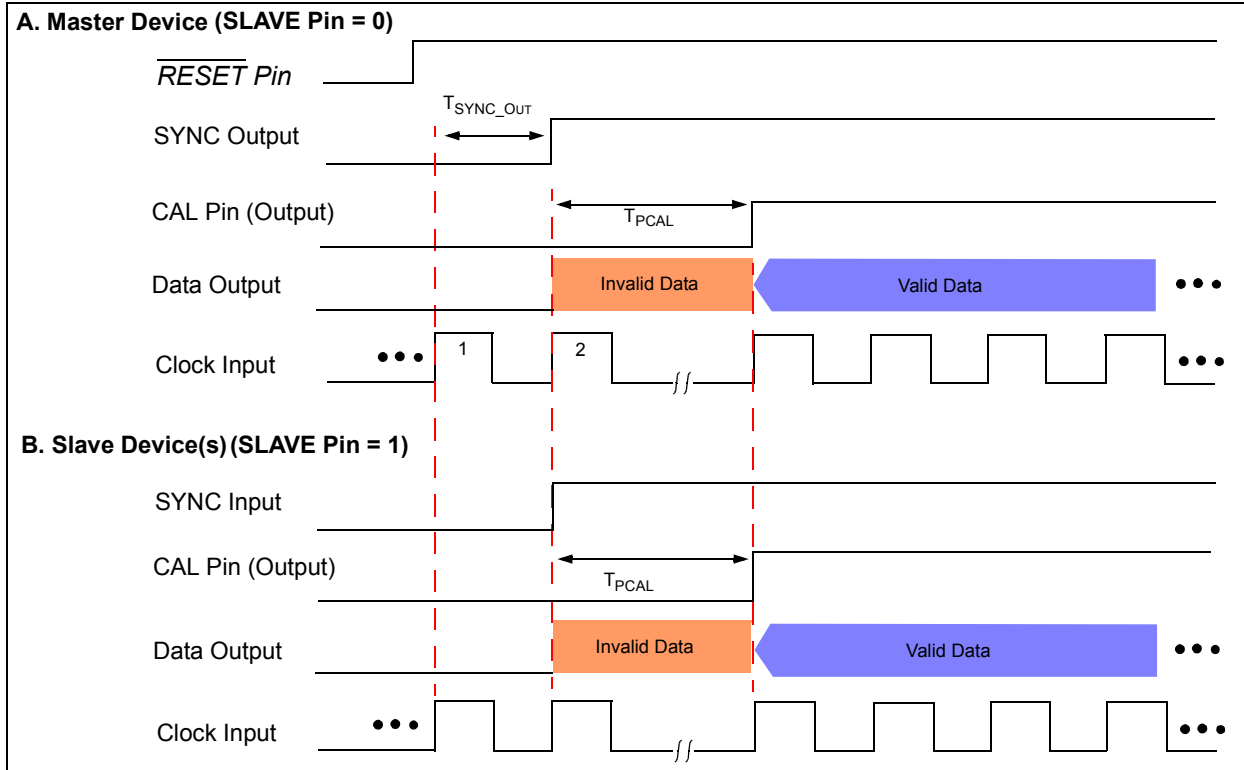


**FIGURE 2-6:** RESET Pin Timing Diagram.

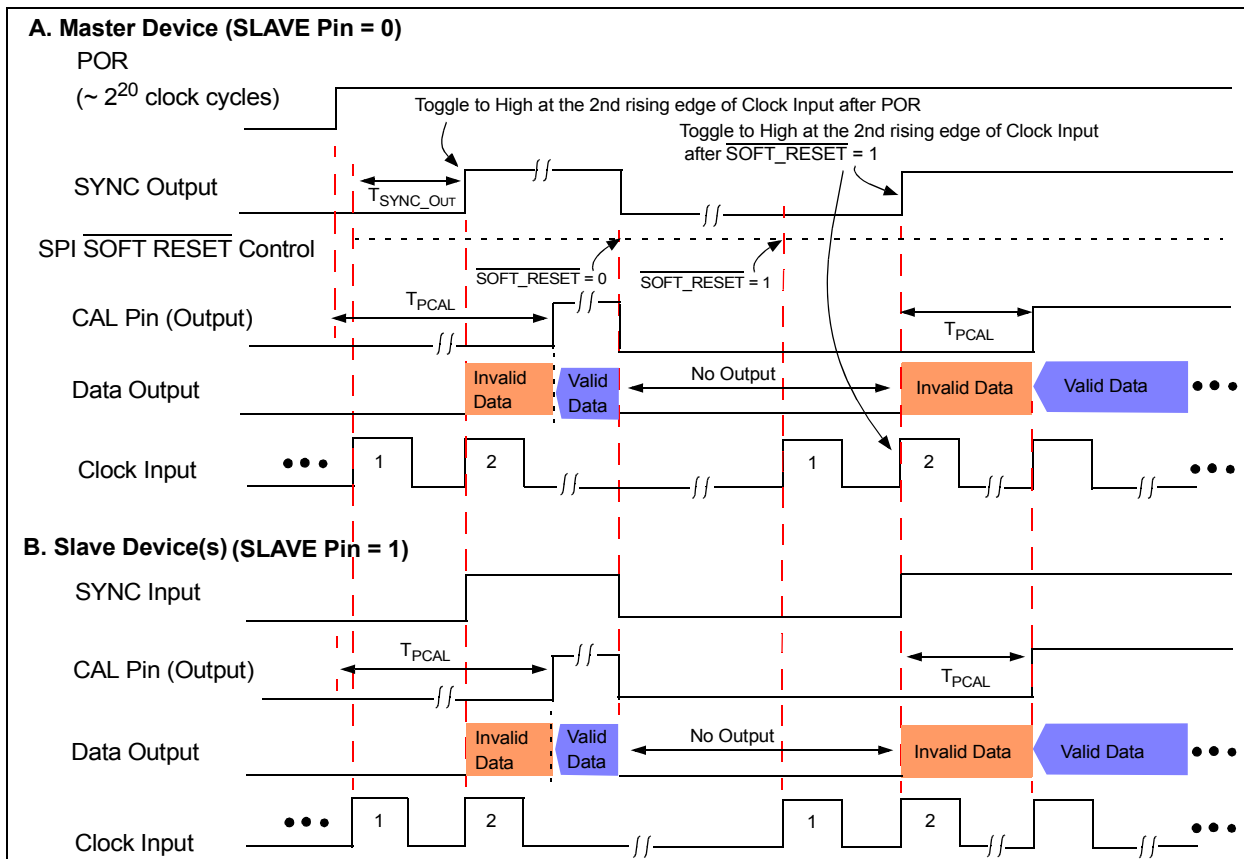


**FIGURE 2-7:** Figure 2-5 Sync Timing Diagram with Power-On Reset.

# MCP37211-200 AND MCP37D11-200



**FIGURE 2-8:** Sync Timing Diagram with  $\overline{\text{RESET}}$  Pin Operation.



**FIGURE 2-9:** Sync Timing Diagram with  $\overline{\text{SOFT\_RESET}}$  Bit Setting.



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**TABLE 2-4: TEMPERATURE CHARACTERISTICS**

**Electrical Specifications:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS,  $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz,  $f_S = 200\text{ Msps}$  (ADC Core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS =  $100\Omega$  termination, LVDS driver current setting = 3.5 mA,  $+25^{\circ}\text{C}$  is applied for typical value.

Parameters		Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Temperature Ranges<sup>(1)</sup></b>							
Operating Temperature Range		$T_A$	-40	—	+125	$^{\circ}\text{C}$	
<b>Thermal Package Resistances<sup>(2)</sup></b>							
121L Ball-TFBGA (8 mm x 8 mm)	Junction-to-Ambient Thermal Resistance	$\theta_{JA}$	—	40.2	—	$^{\circ}\text{C/W}$	
	Junction-to-Case Thermal Resistance	$\theta_{JC}$	—	8.4	—	$^{\circ}\text{C/W}$	
124L – VTLA (9 mm x 9 mm)	Junction-to-Ambient Thermal Resistance	$\theta_{JA}$	—	21	—	$^{\circ}\text{C/W}$	$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$
	Junction-to-Case (top) Thermal Resistance	$\theta_{JC}$	—	8.7	—	$^{\circ}\text{C/W}$	

**Note 1:** Maximum allowed power-dissipation ( $P_{\text{DMAX}} = (T_{\text{JMAX}} - T_A)/\theta_{JA}$ ).

**Note 2:** This parameter value is achieved by package simulations.

# MCP37211-200 AND MCP37D11-200

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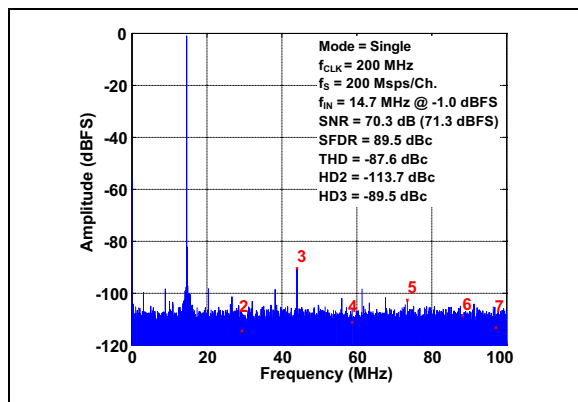
NOTES:

# MCP37211-200 AND MCP37D11-200

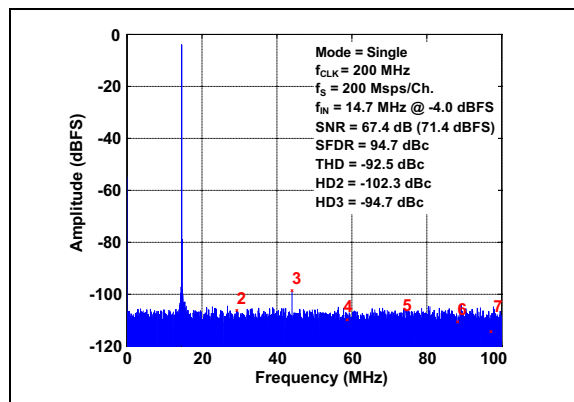
## 3.0 TYPICAL PERFORMANCE CURVES

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

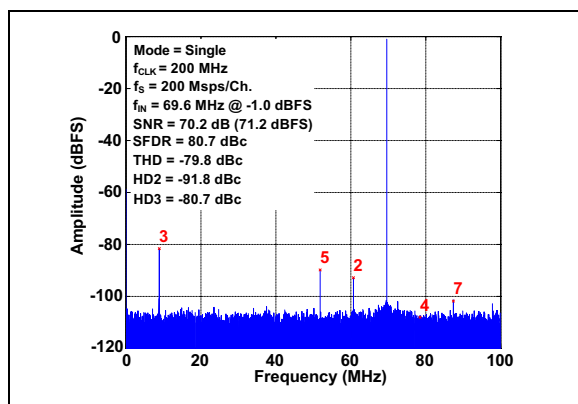
**Note:** Unless otherwise specified, all plots are at +25°C,  $AV_{DD18} = DV_{DD18} = 1.8V$ ,  $AV_{DD12} = DV_{DD12} = 1.2V$ ,  $GND = 0V$ ,  $SENSE = AV_{DD12}$ , Single-channel mode, Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS,  $f_{IN} = 70$  MHz, Clock Input = 200 MHz,  $f_S = 200$  Msp/s (ADC Core), PLL and decimation filters are disabled. When NSR option is used, 12-bit mode is applied and the noise is calculated within the NSR bandwidth (25% of sampling frequency).



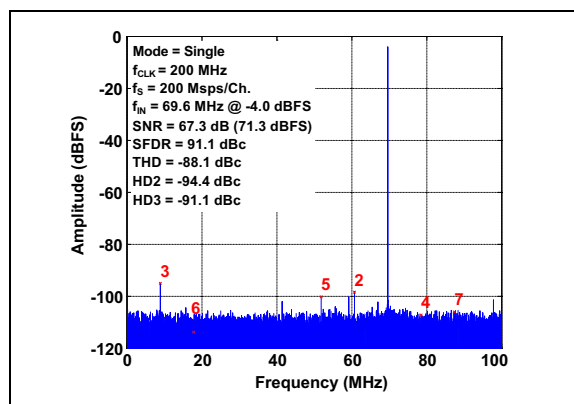
**FIGURE 3-1:** FFT for 14.7 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -1$  dBFS.



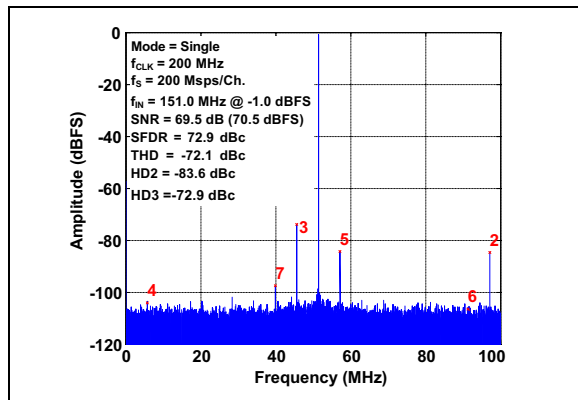
**FIGURE 3-4:** FFT for 14.7 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -4$  dBFS.



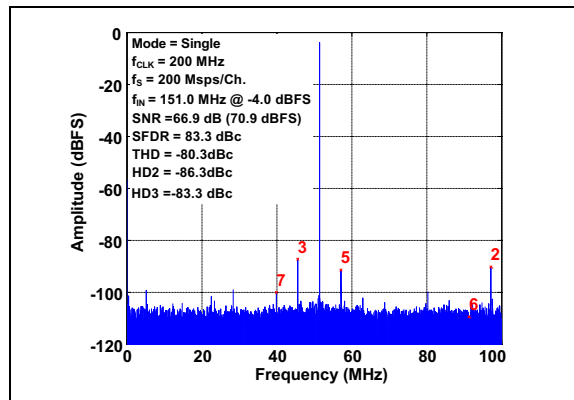
**FIGURE 3-2:** FFT for 69.6 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -1$  dBFS.



**FIGURE 3-5:** FFT for 69.6 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -4$  dBFS.

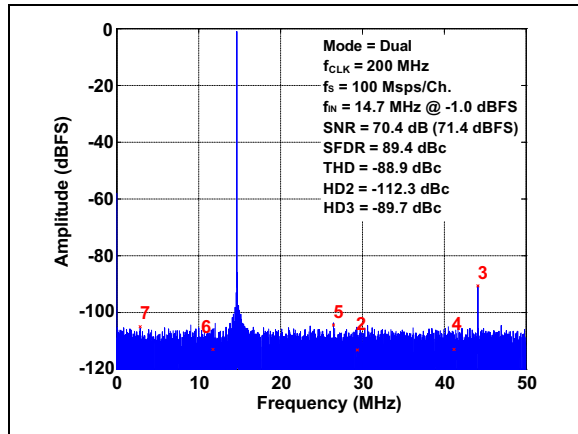


**FIGURE 3-3:** FFT for 151 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -1$  dBFS.

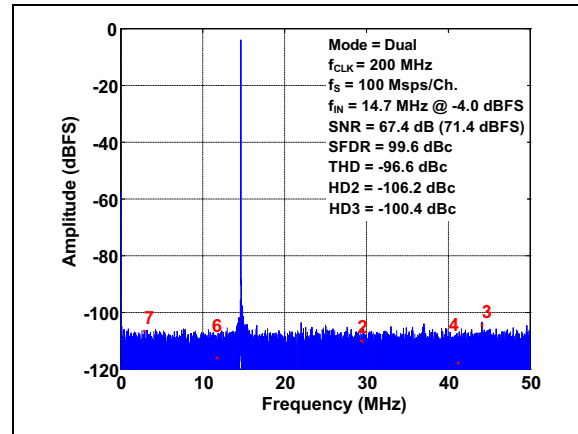


**FIGURE 3-6:** FFT for 151 MHz Input  
Signal:  $f_S = 200$  Msp/s/Ch.,  $A_{IN} = -4$  dBFS.

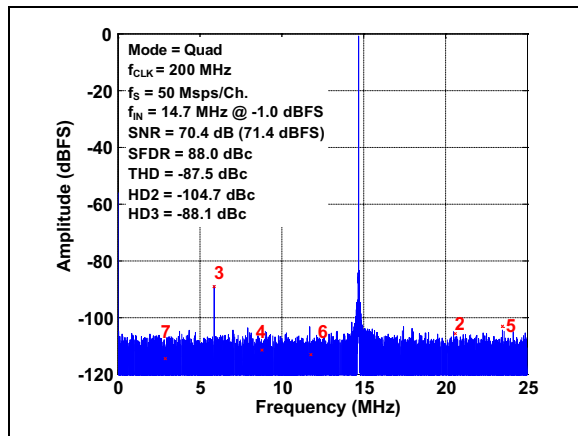
# MCP37211-200 AND MCP37D11-200



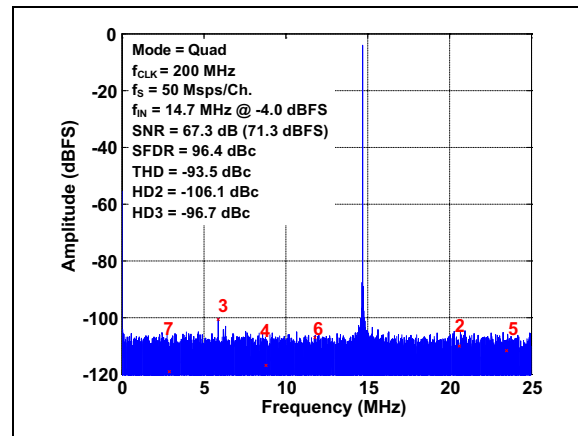
**FIGURE 3-7:** FFT for 14.7 MHz Input  
Signal:  $f_s = 100$  Msps/Ch., Dual,  $A_{IN} = -1$  dBFS.



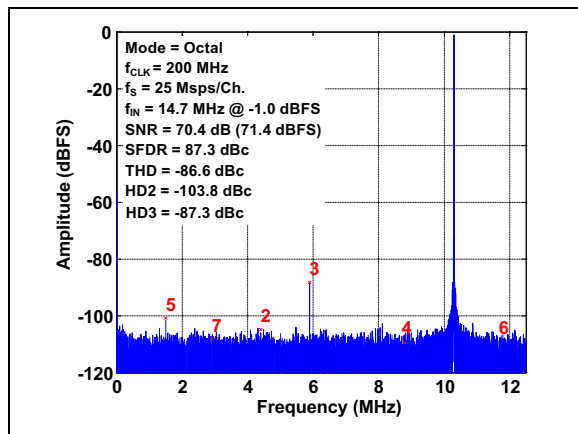
**FIGURE 3-10:** FFT for 14.7 MHz Input  
Signal:  $f_s = 100$  Msps/Ch., Dual,  $A_{IN} = -4$  dBFS.



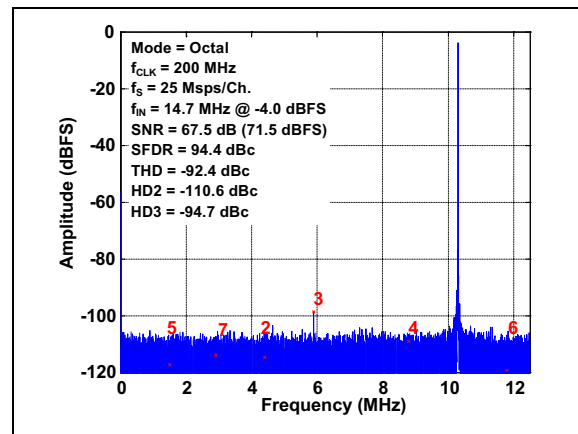
**FIGURE 3-8:** FFT for 14.7 MHz Input  
Signal:  $f_s = 50$  Msps/Ch., Quad,  $A_{IN} = -1$  dBFS.



**FIGURE 3-11:** FFT for 14.7 MHz Input  
Signal:  $f_s = 50$  Msps/Ch., Quad,  $A_{IN} = -4$  dBFS.

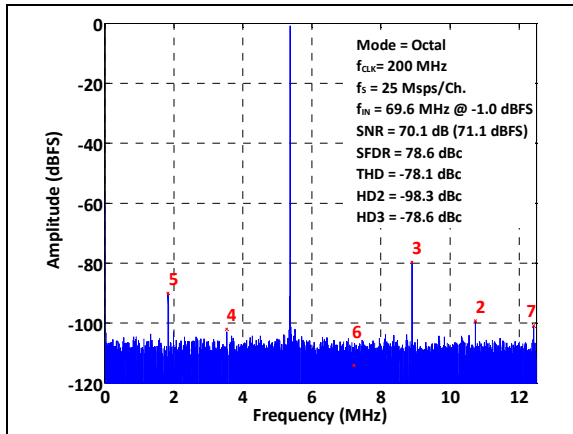


**FIGURE 3-9:** FFT for 14.7 MHz Input  
Signal:  $f_s = 25$  Msps/Ch., Octal,  $A_{IN} = -1$  dBFS.

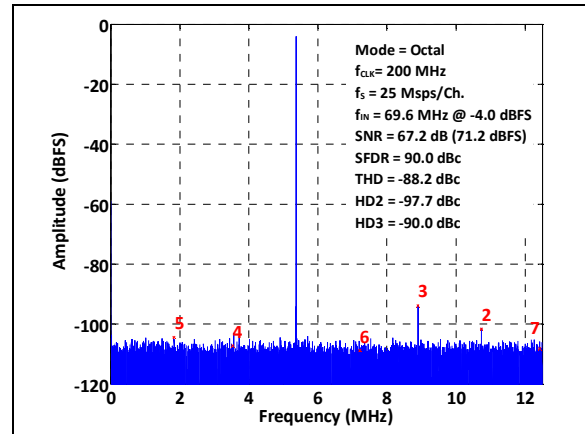


**FIGURE 3-12:** FFT for 14.7 MHz Input  
Signal:  $f_s = 25$  Msps/Ch., Octal,  $A_{IN} = -4$  dBFS.

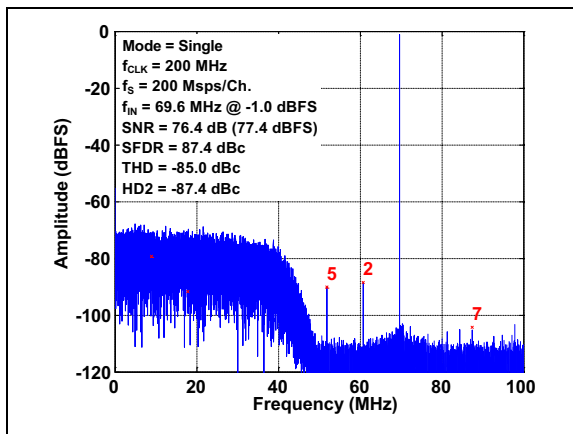
# MCP37211-200 AND MCP37D11-200



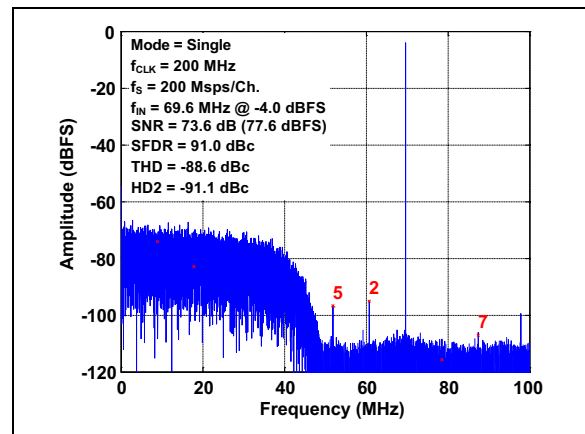
**FIGURE 3-13:** FFT for 69.6 MHz Input  
Signal:  $f_S = 25$  Msps/Ch., Octal,  $A_{IN} = -1$  dBFS.



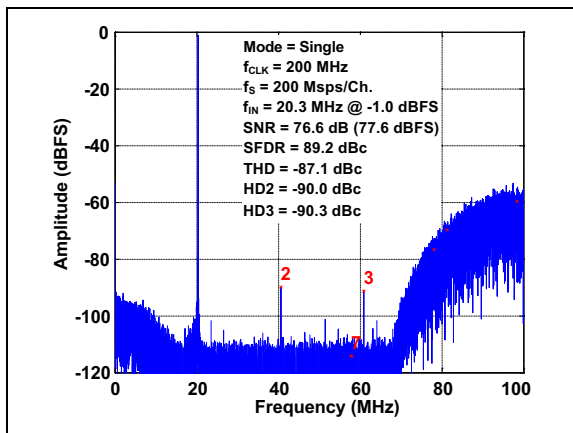
**FIGURE 3-16:** FFT for 69.6 MHz Input  
Signal:  $f_S = 25$  Msps/Ch., Octal,  $A_{IN} = -4$  dBFS.



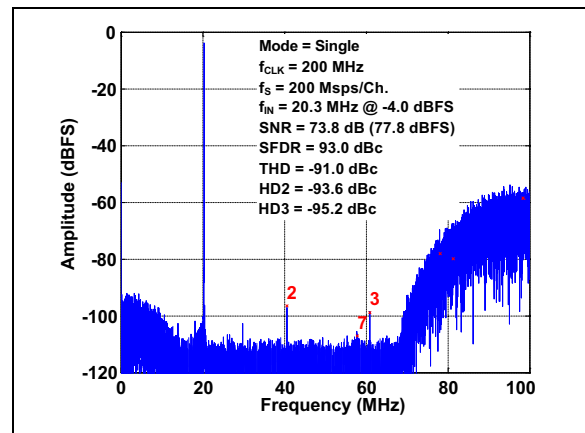
**FIGURE 3-14:** FFT for 69.6 MHz Input  
Signal with NSR enabled: NSR = 20,  
 $f_S = 200$  Msps/Ch.,  $A_{IN} = -1$  dBFS.



**FIGURE 3-17:** FFT for 69.6 MHz Input  
Signal with NSR enabled: NSR = 20,  
 $f_S = 200$  Msps/Ch.,  $A_{IN} = -4$  dBFS.

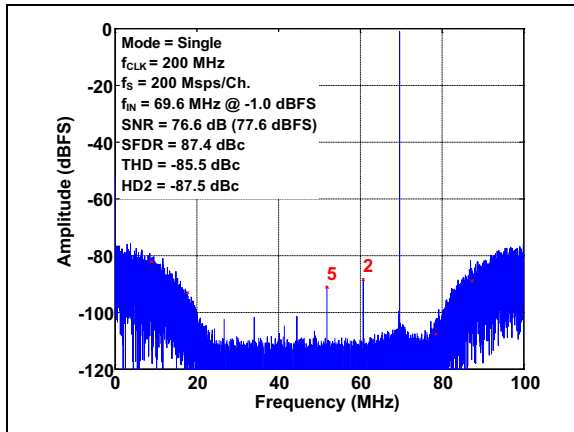


**FIGURE 3-15:** FFT for 20.3 MHz Input  
Signal with NSR enabled: NSR = 27,  
 $f_S = 200$  Msps/Ch.,  $A_{IN} = -1$  dBFS.

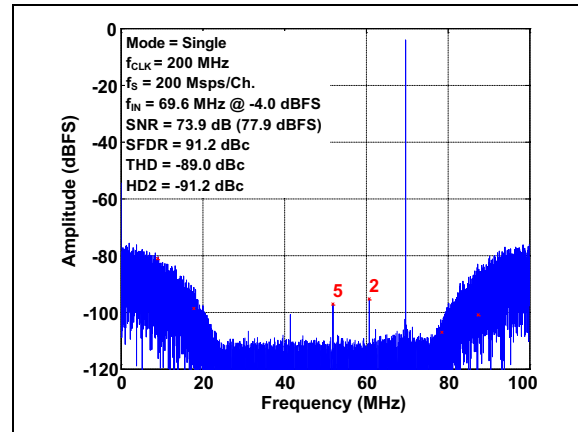


**FIGURE 3-18:** FFT for 20.3 MHz Input  
Signal with NSR enabled: NSR = 27,  
 $f_S = 200$  Msps/Ch.,  $A_{IN} = -4$  dBFS.

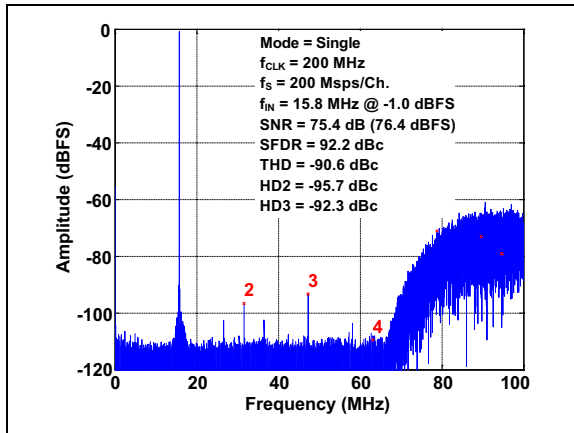
# MCP37211-200 AND MCP37D11-200



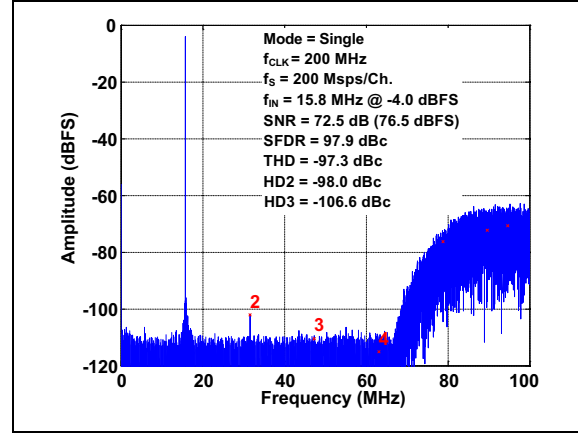
**FIGURE 3-19:** FFT for 69.6 MHz Input Signal with NSR enabled: NSR = 52,  $f_S = 200$  Msps/Ch.,  $A_{IN} = -1$  dBFS.



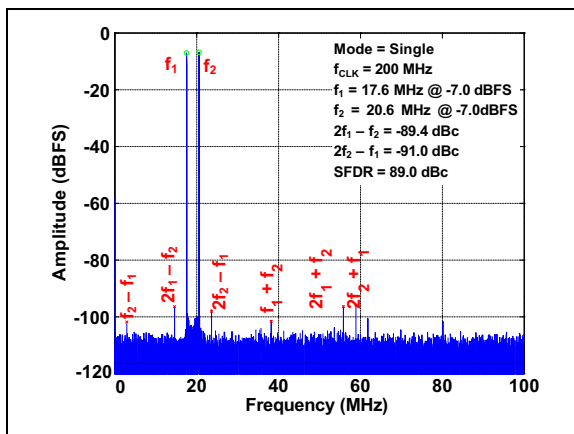
**FIGURE 3-22:** FFT for 69.6 MHz Input Signal with NSR enabled: NSR = 52,  $f_S = 200$  Msps/Ch.,  $A_{IN} = -4$  dBFS.



**FIGURE 3-20:** FFT for 15.8 MHz Input Signal with NSR enabled: NSR = 63,  $f_S = 200$  Msps/Ch.,  $A_{IN} = -1$  dBFS.

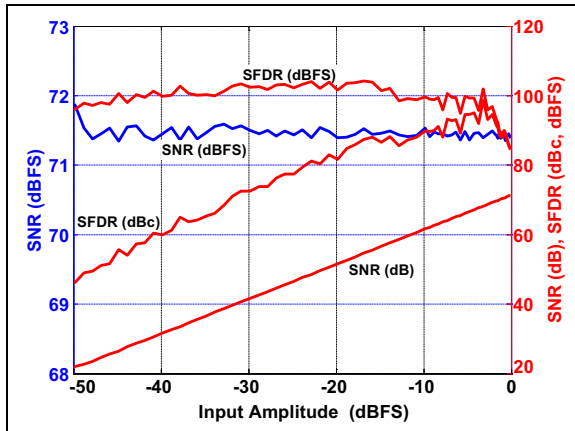


**FIGURE 3-23:** FFT for 15.8 MHz Input Signal with NSR enabled: NSR = 63,  $f_S = 200$  Msps/Ch.,  $A_{IN} = -4$  dBFS.

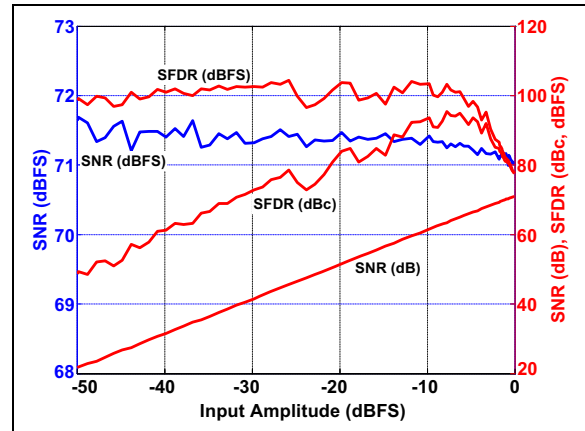


**FIGURE 3-21:** Two-Tone FFT:  $f_{IN1} = 17.6$  MHz and  $f_{IN2} = 20.6$  MHz,  $A_{IN} = -7$  dBFS per Tone,  $f_S = 200$  Msps.

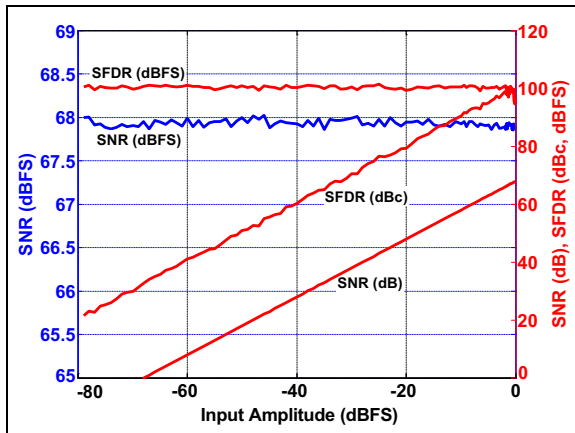
# MCP37211-200 AND MCP37D11-200



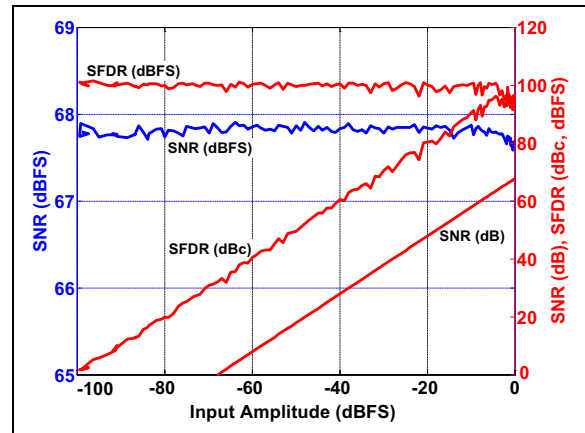
**FIGURE 3-24:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 15$  MHz, High-Reference Mode ( $SENSE = AV_{DD12}$ ).



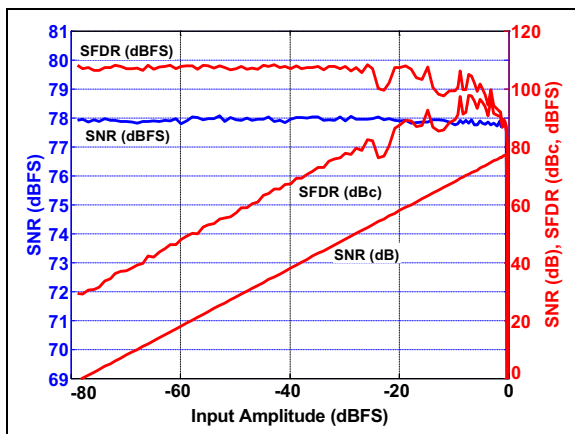
**FIGURE 3-27:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 70$  MHz, High-Reference Mode ( $SENSE = AV_{DD12}$ ).



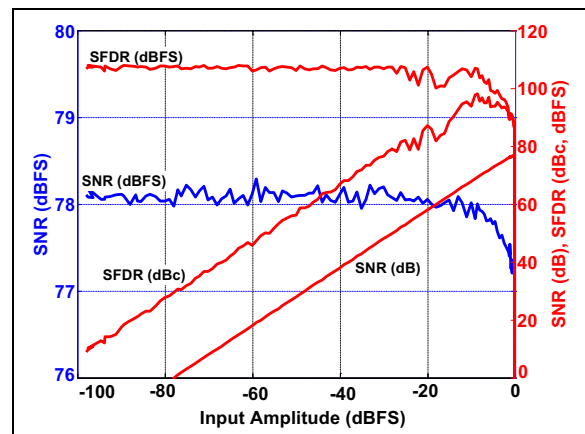
**FIGURE 3-25:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 15$  MHz, Low-Reference Mode ( $SENSE = GND$ ).



**FIGURE 3-28:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 70$  MHz, Low-Reference Mode ( $SENSE = GND$ ).

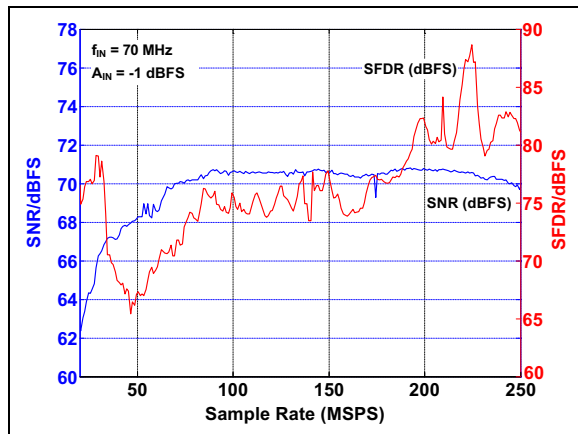


**FIGURE 3-26:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 15$  MHz, High-Reference Mode ( $SENSE = AV_{DD12}$ ) with NSR enabled.  $A_{IN} \leq 0.8$  dBFS for NSR.

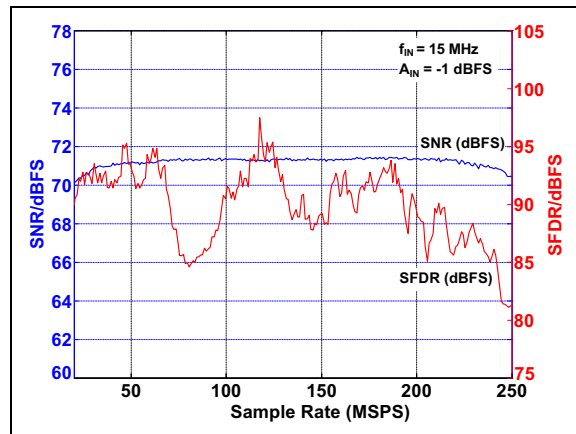


**FIGURE 3-29:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200$  Mps,  $f_{IN} = 70$  MHz, High-Reference Mode ( $SENSE = AV_{DD12}$ ) with NSR enabled.  $A_{IN} \leq 0.8$  dBFS for NSR.

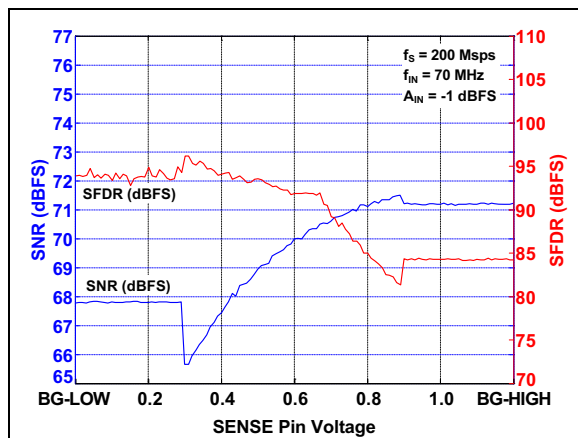
# MCP37211-200 AND MCP37D11-200



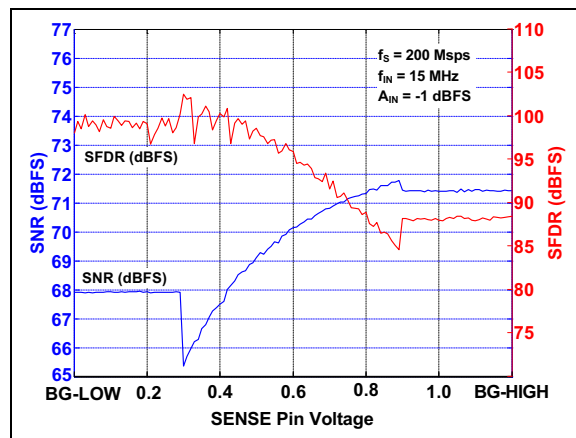
**FIGURE 3-30:** SNR/SFDR vs. Sample Rate (MSPS):  $f_{IN} = 70$  MHz.



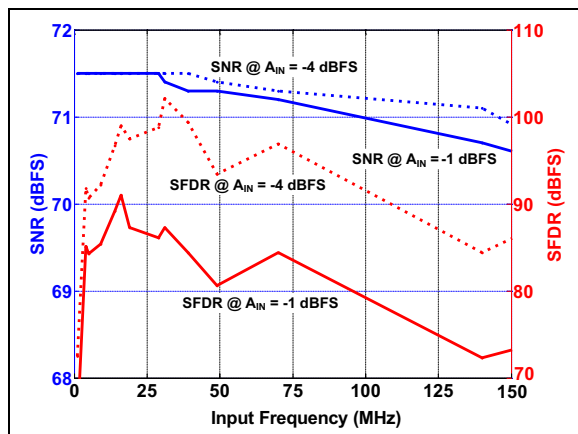
**FIGURE 3-33:** SNR/SFDR vs. Sample Rate (MSPS):  $f_{IN} = 15$  MHz.



**FIGURE 3-31:** SNR/SFDR vs. SENSE Pin Voltage:  $f_S = 200$  Mps,  $f_{IN} = 70$  MHz.



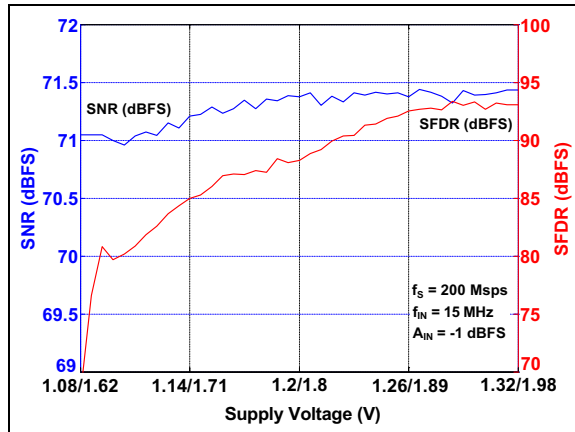
**FIGURE 3-34:** SNR/SFDR vs. SENSE Pin Voltage:  $f_S = 200$  Mps,  $f_{IN} = 15$  MHz.



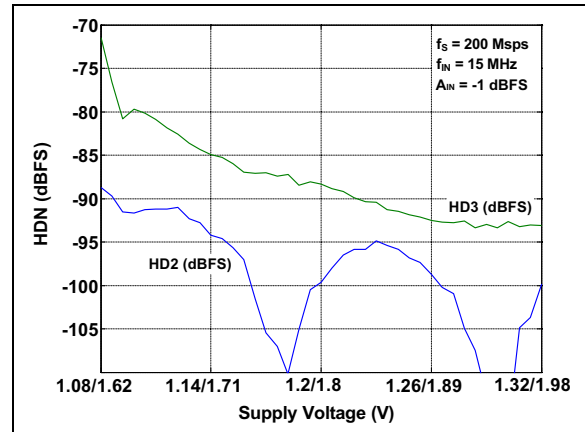
**FIGURE 3-32:** SNR/SFDR vs. Input Frequency.



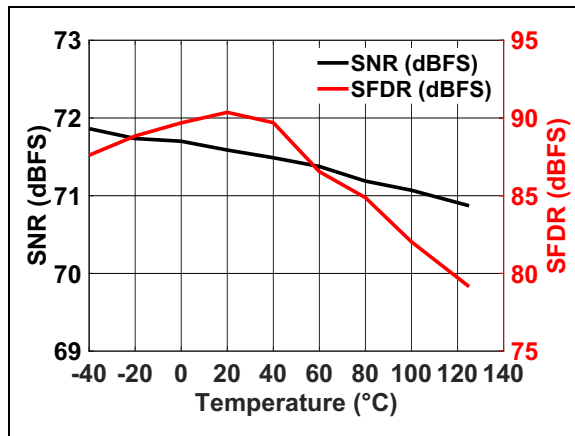
# MCP37211-200 AND MCP37D11-200



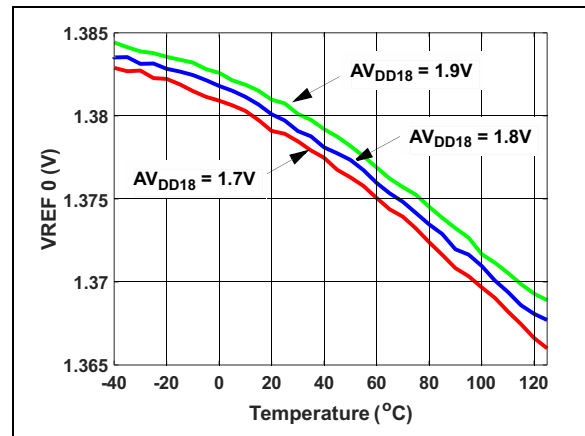
**FIGURE 3-35:** SNR/SFDR vs. Supply Voltage:  $f_s = 200$  Mps,  $f_{IN} = 15$  MHz.



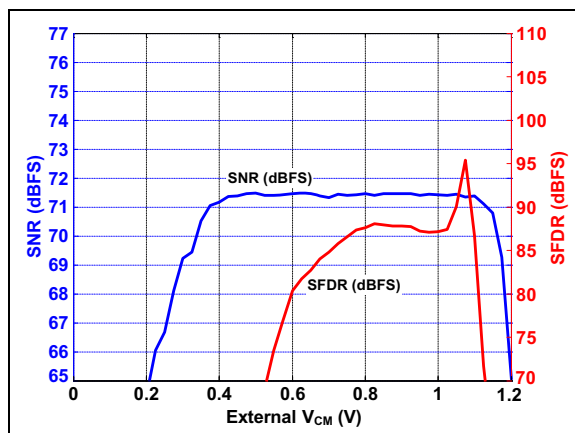
**FIGURE 3-38:** HD2/HD3 vs. Supply Voltage:  $f_s = 200$  Mps,  $f_{IN} = 15$  MHz.



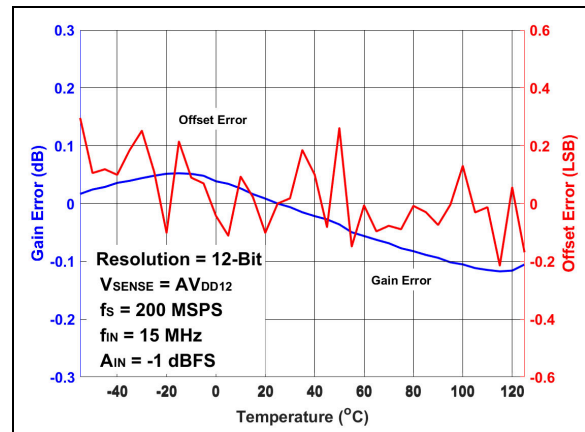
**FIGURE 3-36:** SNR/SFDR vs. Temperature:  $f_s = 200$  Mps,  $f_{IN} = 20$  MHz,  $V_{SENSE} = AV_{DD12}$ ,  $A_{IN} = -1$  dBFS.



**FIGURE 3-39:**  $V_{REF0}$  vs. Temperature.

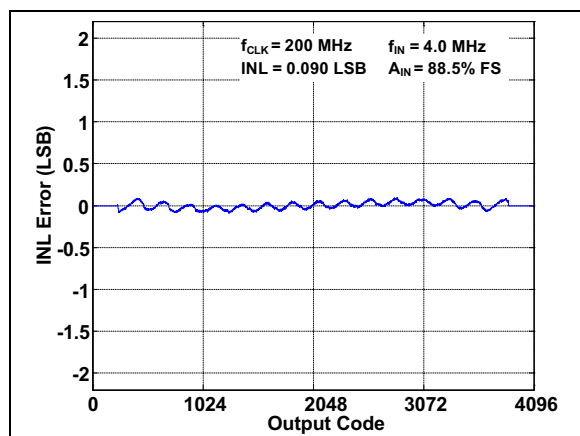


**FIGURE 3-37:** SNR/SFDR vs.  $V_{CM}$  Voltage (Externally Applied):  $f_s = 200$  Mps,  $f_{IN} = 15$  MHz.

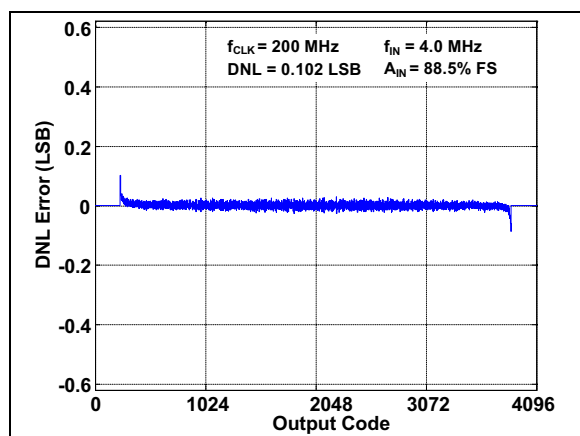


**FIGURE 3-40:** Gain and Offset Error Drifts vs. Temperature Using Internal Reference, with Respect to  $+25^{\circ}\text{C}$ :  $f_s = 200$  Mps.

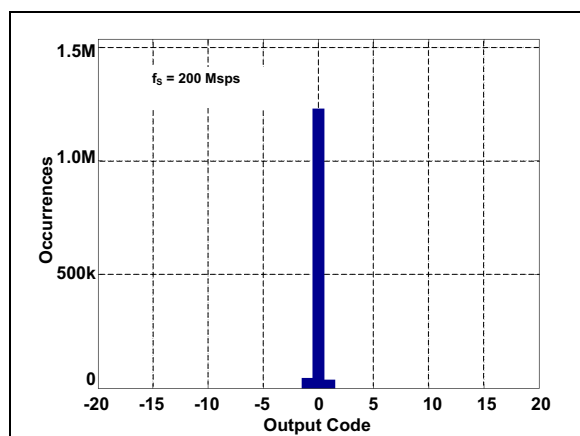
# MCP37211-200 AND MCP37D11-200



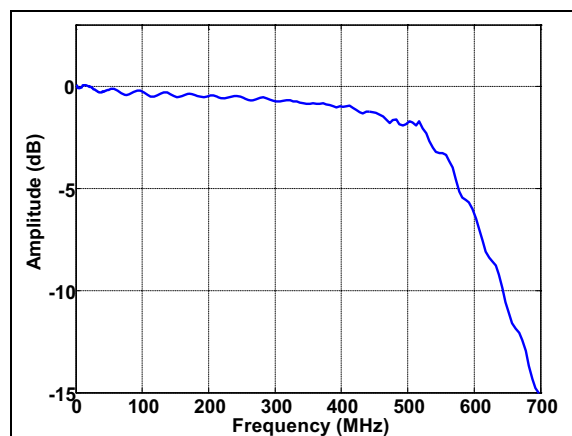
**FIGURE 3-41:** INL Error vs. Output Code:  
 $f_S = 200$  Msp/s,  $f_{IN} = 4$  MHz.



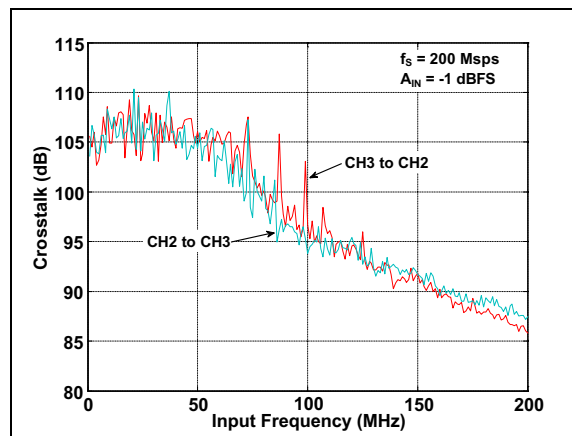
**FIGURE 3-42:** DNL Error vs. Output Code:  
 $f_S = 200$  Msp/s,  $f_{IN} = 4$  MHz.



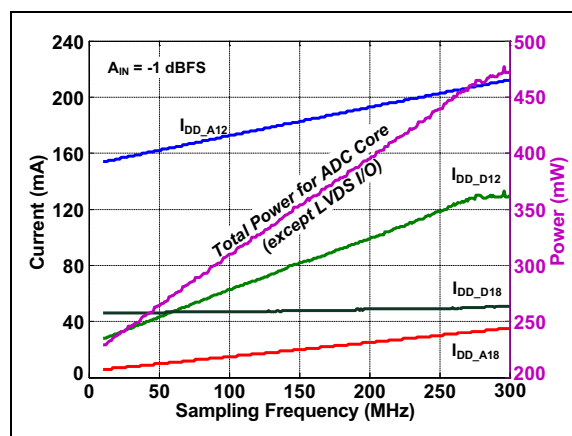
**FIGURE 3-43:** Shorted Input Histogram.



**FIGURE 3-44:** Input Bandwidth.



**FIGURE 3-45:** Input Channel Crosstalk.



**FIGURE 3-46:** Power Consumption vs. Sampling Frequency (LVDS Mode).

# MCP37211-200 AND MCP37D11-200

## 4.0 THEORY OF OPERATION

The MCP37211-200 and MCP37D11-200 device family is a low-power, 12-bit, 200 Msps Analog-to-Digital Converter (ADC) with built-in features including Harmonic Distortion Correction (HDC), DAC Noise Cancellation (DNC), Dynamic Element Matching (DEM) and flash error calibration.

The devices offer various built-in digital signal post-processing features. Both the MCP37211-200 and MCP37D11-200 offer high-order FIR digital decimation filters, noise-shaping requantizer (NSR), gain and offset adjustment per channel and fractional delay recovery (FDR). The MCP37D11-200 includes additional features such as digital down-conversion (DDC) and CW beamforming capability. These built-in advanced digital signal post-processing sub-blocks, which are individually controlled using Configuration register bit settings, can be used for various special applications such as I/Q demodulation, digital down-conversion and ultrasound imaging.

When the device is first powered-up, it performs internal calibrations by itself and runs with default settings. From this point, the user can configure the device registers using the SPI command.

In multi-channel mode, the input channel selection and MUX scan order are user-configurable, and the inputs are sequentially multiplexed by the input MUX defined by the scan order.

The device samples the analog input on the rising edge of the clock. The digital output code is available after 28 clock cycles of data latency. Latency will increase if any of the various digital signal post-processing (DSPP) options are enabled.

The output data can be coded in two's complement or offset binary format, and randomized using the user option. Data can be output using either the CMOS or LVDS (Low-Voltage Differential Signaling) interface.

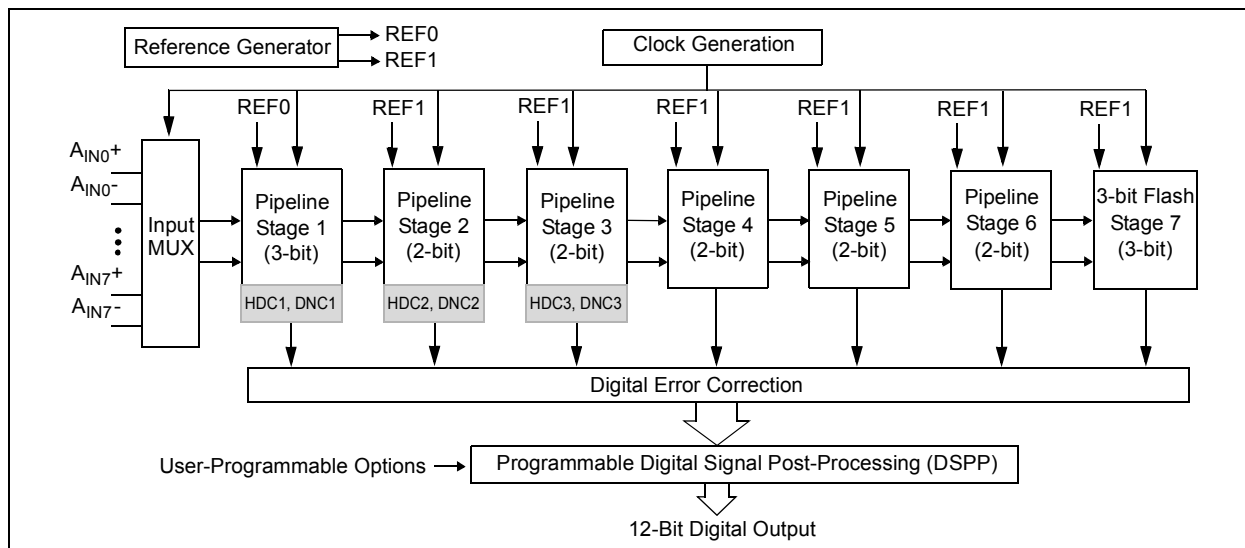
## 4.1 ADC Core Architecture

Figure 4-1 shows the simplified block diagram of the ADC core. The first stage consists of a 17-level flash ADC, multi-level Digital-to-Analog Converter (DAC) and a residue amplifier with a gain of 8. Stages 2 to 6 consist of a 9-level (3-bit) flash ADC, multi-level DAC and a residue amplifier with a gain of 4. The last stage is a 9-level 3-bit flash ADC. Dither is added in each of the first three stages. The digital outputs from all seven stages are combined in a digital error correction logic block and digitally processed for the final output.

The first three stages include patented digital calibration features:

- Harmonic Distortion Correction (HDC) algorithm that digitally measures and cancels ADC errors arising from distortions introduced by the residue amplifiers
- DAC Noise Cancellation (DNC) algorithm that corrects DAC's nonlinearity errors
- Dynamic Element Matching (DEM) which randomizes DAC errors, thereby converting harmonic distortion to white noise

These digital correction algorithms are first applied during the Power-on Reset sequence and then operate in the background during normal operation of the pipelined ADC. These algorithms automatically track and correct any environmental changes in the ADC. More details of the system correction algorithms are shown in [Section 4.13 "System Calibration"](#).



**FIGURE 4-1:** ADC Core Block Diagram.

# MCP37211-200 AND MCP37D11-200

## 4.2 Supply Voltage (DV<sub>DD</sub>, AV<sub>DD</sub>, GND)

The device operates from two sets of supplies and a common ground:

- Digital Supplies (DV<sub>DD</sub>) for the digital section: 1.8V and 1.2V
- Analog Supplies (AV<sub>DD</sub>) for the analog section: 1.8V and 1.2V
- Ground (GND): Common ground for both digital and analog sections.

The supply pins require an appropriate bypass capacitor (ceramic) to attenuate the high-frequency noise present in most application environments. The ground pins provide the current return path. These ground pins must connect to the ground plane of the PCB through a low-impedance connection. A ferrite bead can be used to separate analog and digital supply lines if a common power supply is used for both analog and digital sections.

The voltage regulators for each supply need to have sufficient output current capabilities to support a stable ADC operation.

### 4.2.1 POWER-UP SEQUENCE

Figure 2-5 shows the internal power-up sequence events of the device. The power-up sequence of the device is initiated by a Power-on reset (POR) circuit which monitors the analog 1.2V supply voltage (AV<sub>DD12</sub>):

(a) Once the AV<sub>DD12</sub> reaches the Power-on Reset threshold (~ 0.8V), there will be a Power-on Reset stabilization period (2<sup>18</sup> clock cycles) before triggering the power-up calibration (T<sub>PCAL</sub>).

(b) All other supply voltages (AV<sub>DD18</sub>, DV<sub>DD18</sub>, DV<sub>DD12</sub>) must be stabilized before or within the POR stabilization period (T<sub>POR-S</sub>). The order that these supply voltages are applied and stabilized will not affect the power-up sequence.

## 4.3 Input Sample Rate

In single-channel mode, the device samples the input at full speed. In multi-channel mode, the core ADC is multiplexed between the selected channels. The resulting effective sample rate per channel is shown in Equation 4-1.

For example, with 200 Msps operation, the input is sampled at the full 200 Msps rate if a single channel is used, or at 25 Msps per channel if all eight channels are used.

### EQUATION 4-1: SAMPLE RATE PER CHANNEL

$$\text{Sample Rate/Channel} = \frac{\text{Full ADC Sample Rate}(fs)}{\text{Number of Channel Used}}$$

## 4.4 Analog Input Channel Selection

The analog input is auto-multiplexed sequentially as defined by the channel-order selection bit setting. The user can configure the input MUX using the following registers:

- SEL\_NCH<2:0> in Address 0x01 (Register 5-2): Select the total number of input channels to be used.
- Addresses 0x7D – 0x7F (Registers 5-38–5-40): Select auto-scan channel order.

The user can select up to eight input channels. If all eight input channels are to be used, SEL\_NCH<2:0> is set to 000 and the input channel sampling order is set using Addresses 0x7D – 0x7F (Registers 5-38–5-40).

Regardless of how many channels are selected, all eight channels must be programmed in Addresses 0x7D – 0x7F (Registers 5-38–5-40) without duplication. Program the addresses of the selected channels in sequential order, followed by the unused channels. The order of the unused channels has no effect. The device samples the first N-Channels listed in Addresses 0x7D – 0x7F (Registers 5-38–5-40) sequentially, where N is the total number of channels to be used, defined by the SEL\_NCH<2:0>. Table 4-1 shows examples of input channel selection using Addresses 0x7D – 0x7F (Registers 5-38–5-40).

# MCP37211-200 AND MCP37D11-200

TABLE 4-1: EXAMPLE: CHANNEL ORDER SELECTION USING ADDRESSES 0X7D – 0X7F

No. of Channels <sup>(1)</sup>	Selected Channels	Channel Order <sup>(2)</sup>	Address 0x7F								Address 0x7E								Address 0x7D							
			b 7						b 0	b 7							b 0	b 7								b 0
8			Channel Order Bit Settings																							
			5th Ch.	4th Ch.	6th Ch.	3rd Ch.	7th Ch.	2nd Ch.	8th Ch.	1st Ch.																
	[0 1 2 3 4 5 6 7]	[0 1 2 3 4 5 6 7] (Default)	1 0 0	0 1 1	1 0 1	0 1 0	1 1 0	0 0 1	1 1 1	0 0 0																
	[7 6 5 4 3 2 1 0]	[7 6 5 4 3 2 1 0]	0 1 1	1 0 0	0 1 0	1 0 1	0 0 1	1 1 0	0 0 0	1 1 1																
	[0 2 4 6 1 3 5 7]	[0 2 4 6 1 3 5 7]	0 0 1	1 1 0	0 1 1	1 0 0	1 0 1	0 1 0	1 1 1	0 0 0																
7			Channel Order Bit Settings																							
			Unused	4th Ch.	5th Ch.	3rd Ch.	6th Ch.	2nd Ch.	7th Ch.	1st Ch.																
	[0 1 2 3 4 5 6]	[0 1 2 3 4 5 6 7]	1 1 1	0 1 1	1 0 0	0 1 0	1 0 1	0 0 1	1 1 0	0 0 0																
6			Channel Order Bit Settings																							
			Unused	Unused	4th Ch.	3rd Ch.	5th Ch.	2nd Ch.	6th Ch.	1st Ch.																
	[0 1 2 3 4 5]	[0 1 2 3 4 5 6 7]	1 1 1	1 1 0	0 1 1	0 1 0	1 0 0	0 0 1	1 0 1	0 0 0																
5			Channel Order Bit Settings																							
			Unused	Unused	Unused	3rd Ch.	4th Ch.	2nd Ch.	5th Ch.	1st Ch.																
	[0 1 2 3 4]	[0 1 2 3 4 5 6 7]	1 1 0	1 0 1	1 1 1	0 1 0	0 1 1	0 0 1	1 0 0	0 0 0																
4			Channel Order Bit Settings																							
			Unused	Unused	Unused	Unused	3rd Ch.	2nd Ch.	4th Ch.	1st Ch.																
	[0 1 2 3]	[0 1 2 3 4 5 6 7]	1 1 0	1 0 1	1 1 1	1 0 0	0 1 0	0 0 1	0 1 1	0 0 0																
	[4 5 6 7]	[4 5 6 7 0 1 2 3]	0 1 0	0 0 1	0 1 1	0 0 0	1 1 0	1 0 1	1 1 1	1 0 0																
	[0 2 4 6]	[0 2 4 6 1 3 5 7]	1 0 1	0 1 1	1 1 1	0 0 1	1 0 0	0 1 0	1 1 0	0 0 0																
3			Channel Order Bit Settings																							
			Unused	Unused	Unused	Unused	Unused	2nd Ch.	3rd Ch.	1st Ch.																
	[0 1 2]	[0 1 2 3 4 5 6 7]	1 0 1	1 0 0	1 1 0	0 1 1	1 1 1	0 0 1	0 1 0	0 0 0																
2			Channel Order Bit Settings																							
			Unused	Unused	Unused	Unused	Unused	Unused	2nd Ch.	1st Ch.																
	[0 1]	[0 1 2 3 4 5 6 7]	1 0 1	1 0 0	1 1 0	0 1 1	1 1 1	0 1 0	0 0 1	0 0 0																
	[2 3]	[2 3 0 1 4 5 6 7]	1 0 1	1 0 0	1 1 0	0 0 1	1 1 1	0 0 0	0 1 1	0 1 0																
	[4 5]	[4 5 0 1 2 3 6 7]	0 1 1	0 1 0	1 1 0	0 0 1	1 0 1	0 0 0	1 0 1	1 0 0																
			Channel Order Bit Settings																							
	[6 7]	[6 7 0 1 2 3 4 5]	0 1 1	0 1 0	1 0 0	0 0 1	1 0 1	0 0 0	1 1 1	1 1 0																

**Note 1:** Defined by SEL\_NCH<2:0> in Address 0x01 (Register 5-2).

**Note 2:** Individual channel order should not be repeated. Unused channels are still assigned after the selected channel address. The order of the unused channel addresses has no meaning since they are not used.

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TABLE 4-1: EXAMPLE: CHANNEL ORDER SELECTION USING ADDRESSES 0X7D – 0X7F

No. of Channels <sup>(1)</sup>	Selected Channels	Channel Order <sup>(2)</sup>	Address 0x7F							Address 0x7E							Address 0x7D									
			b 7						b 0	b 7							b 0	b 7							b 0	
1			Channel Order Bit Settings																							
			Unused			Unused			Unused			Unused			Unused			Unused			Unused			1st Ch.		
	[0]	[0 1 2 3 4 5 6 7]	1	0	0	0	1	1	1	0	1	0	1	0	1	1	0	0	0	1	1	1	1	0	0	0
	[1]	[1 0 2 3 4 5 6 7]	1	0	0	0	1	1	1	0	1	0	1	0	1	1	0	0	0	0	1	1	1	0	0	1
	[2]	[2 0 1 3 4 5 6 7]	1	0	0	0	1	1	1	0	1	0	0	1	1	1	0	0	0	0	1	1	1	0	1	0
	[3]	[3 0 1 2 4 5 6 7]	1	0	0	0	1	0	1	0	1	0	0	1	1	1	0	0	0	0	1	1	1	0	1	1
	[4]	[4 0 1 2 3 5 6 7]	0	1	1	0	1	0	1	0	1	0	0	1	1	1	0	0	0	0	1	1	1	1	0	0
	[5]	[5 0 1 2 3 4 6 7]	0	1	1	0	1	0	1	0	0	0	0	1	1	1	0	0	0	0	1	1	1	1	0	1
	[6]	[6 0 1 2 3 4 5 7]	0	1	1	0	1	0	1	0	0	0	0	1	1	0	1	0	0	0	1	1	1	1	1	0
	[7]	[7 0 1 2 3 4 5 6]	0	1	1	0	1	0	1	0	0	0	0	1	1	0	1	0	0	0	1	1	0	1	1	1

**Note 1:** Defined by SEL\_NCH<2:0> in Address 0x01 ([Register 5-2](#)).

**Note 2:** Individual channel order should not be repeated. Unused channels are still assigned after the selected channel address. The order of the unused channel addresses has no meaning since they are not used.

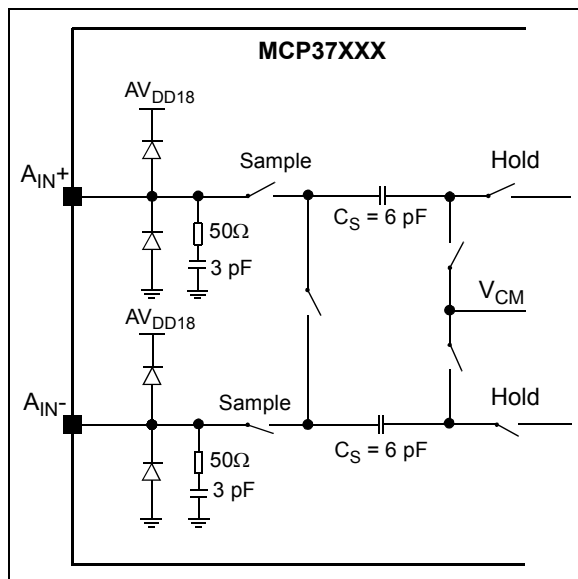
# MCP37211-200 AND MCP37D11-200

## 4.5 Analog Input Circuit

The analog input ( $A_{IN}$ ) of all MCP37XXX devices is a differential, CMOS switched capacitor sample-and-hold circuit. Figure 4-2 shows the equivalent input structure of the device.

The input impedance of the device is mostly governed by the input sampling capacitor ( $C_S = 6 \text{ pF}$ ) and input sampling frequency ( $f_S$ ). The performance of the device can be affected by the input signal conditioning network (see Figure 4-3). The analog input signal source must have sufficiently low output impedance to charge the sampling capacitors ( $C_S = 6 \text{ pF}$ ) within one clock cycle. A small external resistor (e.g.,  $50 \Omega$ ) in series with each input is recommended, as it helps reduce transient currents and dampens ringing behavior. A small differential shunt capacitor at the chip side of the resistors may be used to provide dynamic charging currents and may improve performance. The resistors form a low-pass filter with the capacitor and their values must be determined by application requirements and input frequency.

The  $V_{CM}$  pin provides a common-mode voltage reference ( $0.9V$ ), which can be used for a center-tap voltage of an RF transformer or balun. If the  $V_{CM}$  pin voltage is not used, the user may create a common-mode voltage at mid-supply level ( $AV_{DD18}/2$ ).



**FIGURE 4-2:** Equivalent Input Circuit.

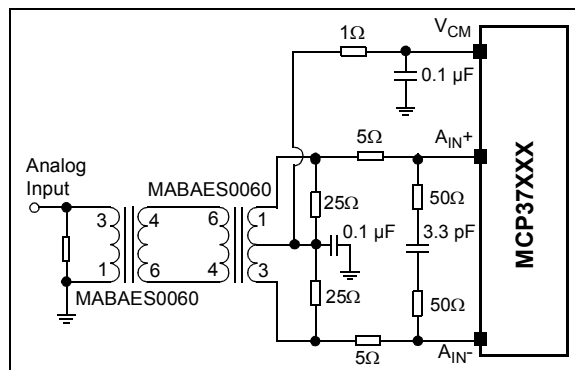
### 4.5.1 ANALOG INPUT DRIVING CIRCUIT

#### 4.5.1.1 Differential Input Configuration

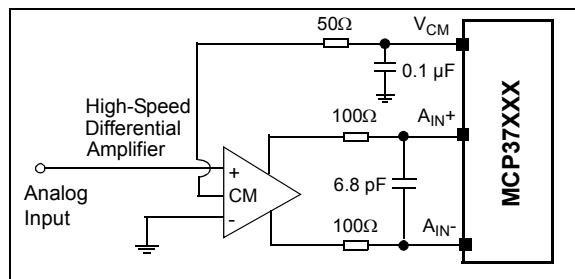
The device achieves optimum performance when the input is driven differentially, where common-mode noise immunity and even-order harmonic rejection are significantly improved. If the input is single-ended, it must be converted to a differential signal in order to properly drive the ADC input. The differential conversion and common-mode application can be accomplished by using an RF transformer or balun with a center-tap. Additionally, one or more anti-aliasing filters may be added for optimal noise performance and should be tuned such that the corner frequency is appropriate for the system.

Figure 4-3 shows an example of the differential input circuit with transformer. Note that the input-driving circuits are terminated by  $50 \Omega$  near the ADC side through a pair of  $25 \Omega$  resistors from each input to the common-mode ( $V_{CM}$ ) from the device. The RF transformer must be carefully selected to avoid artificially high harmonic distortion. The transformer can be damaged if a strong RF input is applied or an RF input is applied while the MCP37XXX is powered-off. The transformer has to be selected to handle sufficient RF input power.

Figure 4-4 shows an input configuration example when a differential output amplifier is used.



**FIGURE 4-3:** Transformer Coupled Input Configuration.



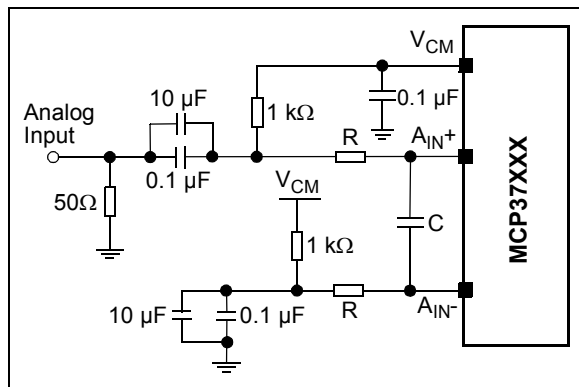
**FIGURE 4-4:** DC-Coupled Input Configuration with Preamplifier: the external signal conditioning circuit and associated component values are for reference only. Typically, the amplifier manufacturer provides reference circuits and component values.



# MCP37211-200 AND MCP37D11-200

## 4.5.1.2 Single-Ended Input Configuration

Figure 4-5 shows an example of a single-ended input configuration. This single-ended input configuration is not recommended for the best performance. SNR and SFDR performance degrades significantly when the device is operated in a single-ended configuration. The unused negative side of the input should be AC-coupled to ground using a capacitor.

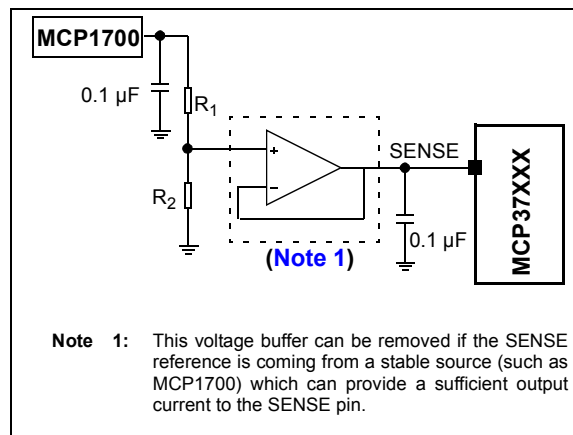


**FIGURE 4-5:** Singled-Ended Input Configuration.

## 4.5.2 SENSE VOLTAGE AND INPUT FULL-SCALE RANGE

The device has a bandgap-based differential internal reference voltage. The SENSE pin voltage is used to select the reference voltage source and configure the input full-scale range. A comparator detects the SENSE pin voltage and configures the full-scale input range into one of the three possible modes which are summarized in Table 4-2. Figure 4-6 shows an example of how the SENSE pin should be driven.

The SENSE pin can sink or source currents as high as 500  $\mu$ A across all operational conditions. Therefore, it may require a driver circuit, unless the SENSE reference source provides sufficient output current.



**FIGURE 4-6:** SENSE Pin Voltage Setup.

**TABLE 4-2: SENSE PIN VOLTAGE AND INPUT FULL-SCALE RANGE**

SENSE Pin Voltage ( $V_{\text{SENSE}}$ )	Selected Reference Voltage ( $V_{\text{REF}}$ )	Full-Scale Input Voltage Range ( $A_{\text{FS}}$ )	LSb Size (Calculated with $A_{\text{FS}}$ )	Condition
Tied to GND	0.7V	$1.4875 V_{\text{P-P}}^{(1)}$	363.16 $\mu$ V	Low-Reference Mode <sup>(4)</sup>
0.4V – 0.8V	0.7V – 1.4V	$1.4875 V_{\text{P-P}}$ to $2.975 V_{\text{P-P}}^{(2)}$	Adjustable	Sense Mode <sup>(5)</sup>
Tied to $AV_{\text{DD12}}$	1.4875V	$2.975 V_{\text{P-P}}^{(3)}$	726.32 $\mu$ V	High-Reference Mode <sup>(4)</sup>

**Note 1:**  $A_{\text{FS}} = (17/16) \times 1.4 V_{\text{P-P}} = 1.487 V_{\text{P-P}}$

**Note 2:**  $A_{\text{FS}} = (17/16) \times 2.8 V_{\text{P-P}} \times (V_{\text{SENSE}})/0.8 = 1.4875 V_{\text{P-P}}$  to  $2.975 V_{\text{P-P}}$

**Note 3:**  $A_{\text{FS}} = (17/16) \times 2.8 V_{\text{P-P}} = 2.975 V_{\text{P-P}}$

**Note 4:** Based on internal bandgap voltage.

**Note 5:** Based on  $V_{\text{SENSE}}$ .



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## 4.5.2.1 SENSE Selection Vs. SNR/SFDR Performance

The SENSE pin is used to configure the full-scale input range of the ADC. Depending on the application conditions, the SNR, SFDR and dynamic range performance are affected by the SENSE pin configuration. [Table 4-3](#) summarizes these settings.

### • High-Reference Mode

This mode is enabled by setting the SENSE pin to  $AV_{DD12}$  (1.2V). This mode provides the highest input full-scale range ( $2.975 V_{P-P}$ ) and the highest SNR performance. In this mode, the internal thermal noise is less than 1 LSB of the 12-bit ADC ( $726 \mu V$ ). This has the consequence of making it difficult to resolve small input signals unless some dither is added to the ADC input. In typical applications, thermal noise generated by the system driving the ADC will provide the necessary dithering effect. [Figure 3-24](#) and [Figure 3-27](#) show SNR/SFDR versus input amplitude in High-Reference mode.

**Note:** Adding dither to the ADC has a negative side effect of reducing the maximum achievable SNR.

### • Low-Reference Mode

This mode is enabled by setting the SENSE pin to ground. This mode is suitable for applications which have a smaller input full-scale range. This mode provides improved SFDR characteristics, but SNR is reduced by -3 dB compared to the High-Reference Mode.

### • SENSE Mode

This mode is enabled by driving the SENSE pin with an external voltage source between 0.4V and 0.8V. This mode allows the user to adjust the input full-scale range such that SNR and dynamic range are optimized in a given application system environment.

### • NSR Mode

The use of the Noise-Shaping Requantizer (NSR), further described in [Section 4.8.2 “Noise-Shaping Requantizer \(NSR\)”](#), is best suited for applications which require a high SNR and a wide dynamic range as well as a relatively narrow bandwidth.

When the NSR is enabled, the noise level in a selected portion of the frequency band is reduced to a level below that of a conventional 12-bit ADC, while the noise level outside of this band remains significantly higher. The SNR achievable in this mode is about 78 dBFS when integrated across 50% of the Nyquist bandwidth. This is an optimum selection for applications where the full Nyquist bandwidth of the ADC is not needed, and where the digital signal post-processing of the ADC data is capable of removing the out-of-band noise added by the NSR.

[Figures 3-26](#) and [3-29](#) show the SNR/SFDR versus input amplitude with NSR enabled.

**TABLE 4-3: SENSE VS. SNR/SFDR PERFORMANCE**

SENSE	Descriptions
High-Reference Mode (SENSE pin = $AV_{DD12}$ )	High-input full-scale range ( $2.975 V_{P-P}$ ) and optimized SNR
Low-Reference Mode (SENSE pin = ground)	Low-input full-scale range ( $1.4875 V_{P-P}$ ) and reduced SNR, but optimized SFDR
Sense Mode (SENSE pin = 0.4V to 0.8V)	Adjustable-input full-scale range ( $1.4875 V_{P-P}$ - $2.975 V_{P-P}$ ). Dynamic trade-off between High-Reference and Low-Reference modes can be used.
Noise-Shaping Requantizer (NSR)	Optimized SNR, but reduced usable bandwidth. NSR can be employed in any SENSE pin configuration.

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## 4.5.3 DECOUPLING CIRCUITS FOR INTERNAL VOLTAGE REFERENCE AND BANDGAP OUTPUT

### 4.5.3.1 Decoupling Circuits for REF1 and REF0 Pins

The device has two internal voltage references, and these references are available at pins REF0 and REF1. REF0 is the internal voltage reference for the ADC input stage, while REF1 is for all remaining stages.

**VTLA-124 Package Device:** Figure 4-7 shows the recommended circuit for the REF1 and REF0 pins for the VTLA-124 package. Placing a 2.2  $\mu\text{F}$  ceramic capacitor with two additional optional capacitors (22 nF and 220 nF) between the positive and negative reference pins is recommended. The negative reference pin is then grounded through a 220 nF capacitor. The capacitors should be placed as close to the ADC as possible with short and thick traces. Vias on the PCB are not recommended for this reference pin circuit.

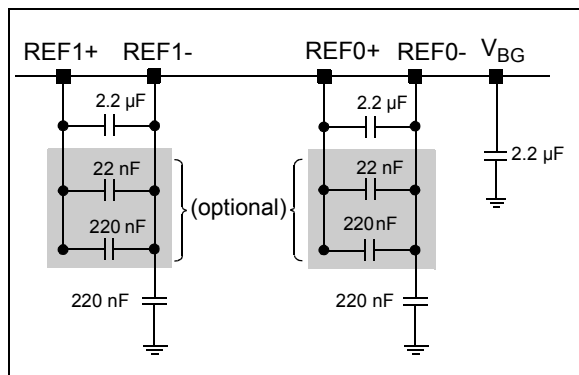
**TFBGA-121 Package Device:** The decoupling capacitor is embedded in the package. Therefore, no external circuit is required on the PCB.

### 4.5.3.2 Decoupling Circuit for $V_{BG}$ Pin

The bandgap circuit is a part of the reference circuit and the output is available at the  $V_{BG}$  pin.

**VTLA-124 Package Device:**  $V_{BG}$  pin needs an external decoupling capacitor (2.2  $\mu\text{F}$ ) as shown in Figure 4-7.

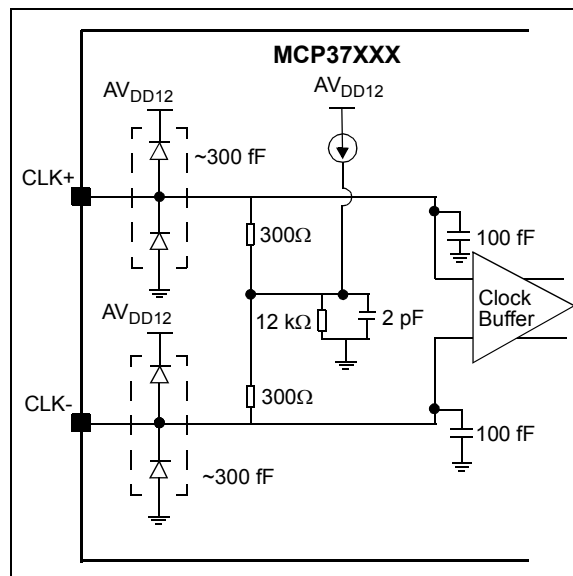
**TFBGA-121 Package Device:** The decoupling capacitor is embedded in the package. Therefore, no external circuit is required on the PCB.



**FIGURE 4-7:** External Circuit for Voltage Reference and  $V_{BG}$  pins for the VTLA-124 Package. Note that this external circuit is not required for the TFBGA-121 package.

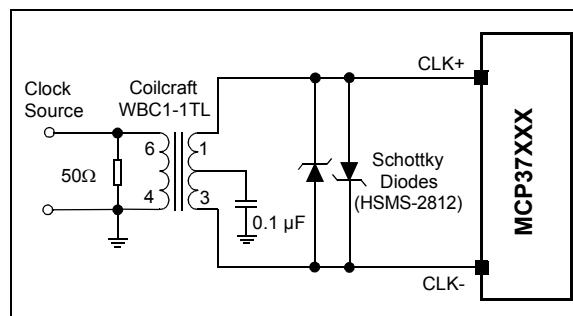
## 4.6 External Clock Input

For optimum performance, the MCP37XXX requires a low-jitter differential clock input at the CLK+ and CLK- pins. Figure 4-8 shows the equivalent clock input circuit.



**FIGURE 4-8:** Equivalent Clock Input Circuit.

The clock input amplitude range is between 300 mV<sub>P-P</sub> and 800 mV<sub>P-P</sub>. When a single-ended clock source is used, an RF transformer or balun can be used to convert the clock into a differential signal for the best ADC performance. Figure 4-9 shows an example clock input circuit. The common-mode voltage is internally generated and a center-tap is not required. The back-to-back Schottky diodes across the transformer's secondary current limit the clock amplitude to approximately 0.8 V<sub>P-P</sub> differential. This limiter helps prevent large voltage swings of the input clock while preserving the high slew rate that is critical for low jitter.



**FIGURE 4-9:** Transformer-Coupled Differential Clock Input Configuration.

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## 4.6.1 CLOCK JITTER AND SNR PERFORMANCE

In a high-speed pipelined ADC, the SNR performance is directly limited by thermal noise and clock jitter. Thermal noise is independent of input clock and dominant term at low-input frequency. On the other hand, the clock jitter becomes a dominant term as input frequency increases. Equation 4-2 shows the SNR jitter component, which is expressed in terms of the input frequency ( $f_{IN}$ ) and the total amount of clock jitter ( $T_{Jitter}$ ), where  $T_{Jitter}$  is a sum of the following two components:

- Input clock jitter (phase noise)
- Internal aperture jitter (due to noise of the clock input buffer).

### EQUATION 4-2: SNR VS. CLOCK JITTER

$$SNR_{Jitter}(dBc) = -20 \times \log_{10}(2\pi \times f_{IN} \times T_{Jitter})$$

where the total jitter term ( $T_{jitter}$ ) is given by:

$$T_{Jitter} = \sqrt{(t_{Jitter, Clock Input})^2 + (t_{Aperture, ADC})^2}$$

The clock jitter can be minimized by using a high-quality clock source and jitter cleaners as well as a band-pass filter at the external clock input, while a faster clock slew rate improves the ADC aperture jitter.

With a fixed amount of clock jitter, the SNR degrades as the input frequency increases. This is illustrated in Figure 4-10. If the input frequency increases from 10 MHz to 20 MHz, the maximum achievable SNR degrades about 6 dB. For every decade (e.g. 10 MHz to 100 MHz), the maximum achievable SNR due to clock jitter is reduced by 20 dB.

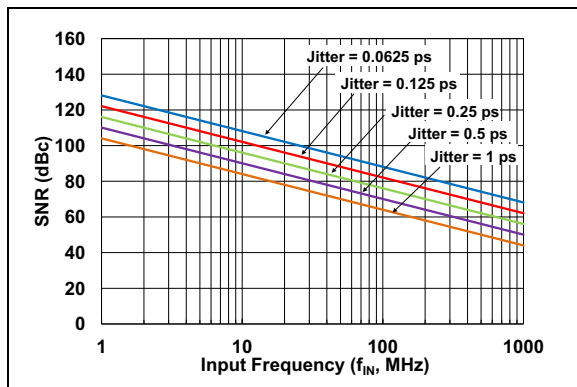


FIGURE 4-10: SNR vs. Clock Jitter.

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## 4.7 ADC Clock Selection

This section describes the ADC clock selection and how to use the built-in Delay-Locked Loop (DLL) and Phase-Locked Loop (PLL) blocks.

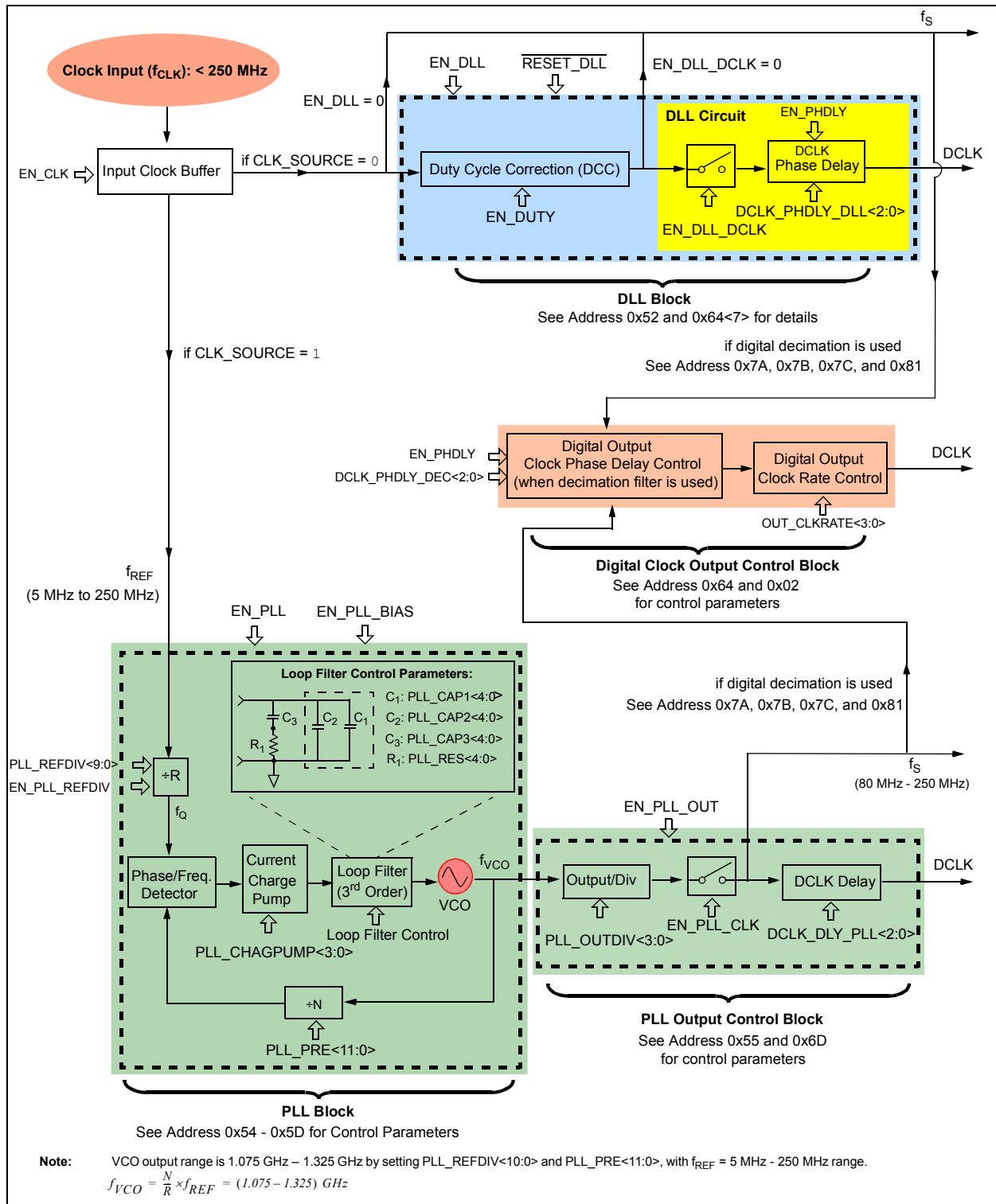
When the device is first powered-up, the external clock input (CLK+/-) is directly used for the ADC timing as default. After this point, the user can enable the DLL or PLL circuit by setting the register bits. [Figure 4-11](#) shows the clock control blocks. [Table 4-4](#) shows an example of how to select the ADC clock depending on the operating conditions.

**TABLE 4-4: ADC CLOCK SELECTION (EXAMPLE)**

Operating Conditions	Control Bit Settings <sup>(1)</sup>	Features	
		Input Clock Duty Cycle Correction	DCLK Output Phase Delay Control
CLK_SOURCE = 0 (Default) <sup>(2)</sup>			
<ul style="list-style-type: none"><li>DLL output is not used</li><li>Decimation is not used (Default)<sup>(3)</sup></li></ul>	EN_DLL = 0 EN_DLL_DCLK = 0 EN_PHDLY = 0	Not Available	Not Available
	EN_DLL = 1 EN_DLL_DCLK = 0 EN_PHDLY = 0	Available	
<ul style="list-style-type: none"><li>DLL output is used</li><li>Decimation is not used</li></ul>	EN_DLL = 1 EN_DLL_DCLK = 1 EN_PHDLY = 1	Available	Available
<ul style="list-style-type: none"><li>DLL output is not used</li><li>Decimation is used<sup>(4)</sup></li></ul>	EN_DLL = 0 EN_DLL_DCLK = x EN_PHDLY = 1	Not Available	
	EN_DLL = 1 EN_DLL_DCLK = 0 EN_PHDLY = 1	Available	
CLK_SOURCE = 1 <sup>(5)</sup>			
<ul style="list-style-type: none"><li>Decimation is not used</li></ul>	EN_DLL = x EN_DLL_DCLK = x EN_PHDLY = 0	Not Available	Available
<ul style="list-style-type: none"><li>Decimation is used<sup>(4)</sup></li></ul>	EN_DLL = x EN_DLL_DCLK = x EN_PHDLY = 1		

- Note**
- 1: See Addresses 0x52, 0x53, and 0x64 for bit settings.
  - 2: The sampling frequency ( $f_S$ ) of the ADC core comes directly from the input clock buffer.
  - 3: Output data is synchronized with the output data clock (DCLK), which comes directly from the input clock buffer.
  - 4: While using decimation, output clock rate and phase delay are controlled by the digital clock output control block.
  - 5: The sampling frequency ( $f_S$ ) is generated by the PLL circuit. The external clock input is used as the reference input clock for the PLL block.

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**FIGURE 4-11:** Timing Clock Control Blocks.

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## 4.7.1 USING DLL MODE

Using the DLL block is the best option when output clock phase control is needed while the clock multiplication and digital decimation are not required. When the DLL block is enabled, the user can control the input clock Duty Cycle Correction (DCC) and the output clock phase delay.

See the DLL block in [Figure 4-11](#) for details. [Table 4-5](#) summarizes the DLL control register bits. In addition, see [Table 4-24](#) for the output clock phase control.

**TABLE 4-5: DLL CONTROL REGISTER BITS**

Control Parameter	Register	Descriptions
CLK_SOURCE	0x53	CLK_SOURCE = 0: external clock input becomes input of the DLL block
EN_DUTY	0x52	Input clock duty cycle correction control bit <sup>(1)</sup>
EN_DLL	0x52	EN_DLL = 1: enable DLL block
EN_DLL_DCLK	0x52	DLL output clock enable bit
EN_PHDLY<2:0>	0x52	Phase delay control bits of digital output clock (DCLK) when DLL or decimation filter is used <sup>(2)</sup>
RESET_DLL	0x52	Reset control bit for the DLL block

**Note 1:** Duty cycle correction is not recommended when a high-quality external clock is used.

**2:** If decimation is used, the output clock phase delay is controlled using DCLK\_PHDLY\_DEC<2:0> in Address 0x64.

### 4.7.1.1 Input Clock Duty Cycle Correction

The ADC performance is sensitive to the clock duty cycle. The ADC achieves optimum performance with 50% duty cycle, and all performance characteristics are ensured when the duty cycle is 50% with  $\pm 1\%$  tolerance.

When CLK\_SOURCE = 0, the external clock is used as the sampling frequency ( $f_S$ ) of the ADC core. When the external input clock is not high-quality (for example, duty cycle is not 50%), the user can enable the internal clock duty cycle correction circuit by setting the EN\_DUTY bit in Address 0x52 ([Register 5-7](#)). When duty cycle correction is enabled (EN\_DUTY=1), only the falling edge of the clock signal is modified (rising edge is unaffected).

Because the duty cycle correction process adds additional jitter noise to the clock signal, this option is recommended only when an asymmetrical input clock source causes significant performance degradation or when the input clock source is not stable.

**Note:** The clock duty cycle correction is only applicable when the DLL block is enabled (EN\_DLL = 1). It is not applicable for the PLL output.

### 4.7.1.2 DLL Block Reset Event

The DLL must be reset if the clock frequency is changed. The DLL reset is controlled by using the RESET\_DLL bit in Address 0x52 ([Register 5-7](#)). The DLL has an automatic reset with the following events:

- During power-up: Stay in reset until the RESET\_DLL bit is cleared.
- When a **SOFT\_RESET** command is issued while the DLL is enabled: the RESET\_DLL bit is automatically cleared after reset.

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## 4.7.2 USING PLL MODE

The PLL block is mainly used when clock multiplication is needed. When `CLK_SOURCE = 1`, the sampling frequency ( $f_S$ ) of the ADC core is coming from the internal PLL block.

The recommended PLL output clock range is from 80 MHz to 250 MHz. The external clock input is used as the PLL reference frequency. The range of the clock input frequency is from 5 MHz to 250 MHz.

**Note:** The PLL mode is only supported for sampling frequencies between 80 MHz and 250 MHz.

### 4.7.2.1 PLL Output Frequency and Output Control Parameters

The internal PLL can provide a stable timing output ranging from 80 MHz to 250 MHz. Figure 4-11 shows the PLL block using a charge-pump-based integer N PLL and the PLL output control block. The PLL block includes various user control parameters for the desired output frequency. Table 4-6 summarizes the PLL control register bits and Table 4-7 shows an example of register bit settings for the PLL charge pump and loop filter.

The PLL block consists of:

- Reference Frequency Divider (R)
- Prescaler - which is a feedback divider (N)
- Phase/Frequency Detector (PFD)
- Current Charge Pump
- Loop Filter - a 3<sup>rd</sup> order RC low-pass filter
- Voltage-Controlled Oscillator (VCO)

The external clock at the CLK+ and CLK- pins is the input frequency to the PLL. The range of input frequency ( $f_{REF}$ ) is from 5 MHz to 250 MHz. This input frequency is divided by the reference frequency divider (R) which is controlled by the 10-bit-wide `PLL_REFDIV<9:0>` setting. In the feedback loop, the VCO frequency is divided by the prescaler (N) using `PLL_PRE<11:0>`.

The ADC core sampling frequency ( $f_S$ ), ranging from 80 MHz to 250 MHz, is obtained after the output frequency divider (`PLL_OUTDIV<3:0>`). For stable operation, the user needs to configure the PLL with the following limits:

- Input clock frequency ( $f_{REF}$ ) = 5 MHz to 250 MHz
- Charge pump input frequency = 4 MHz to 50 MHz (after PLL reference divider)
- VCO output frequency = 1.075 to 1.325 GHz
- PLL output frequency after output divider = 80 MHz to 250 MHz

The charge pump is controlled by the PFD, and forces sink (DOWN) or source (UP) current pulses onto the loop filter. The charge pump bias current is controlled by the `PLL_CHAGPUMP<3:0>` bits, approximately 25  $\mu$ A per step. The loop filter consists of a 3<sup>rd</sup> order passive RC filter. Table 4-7 shows the recommended

settings of the charge pump and loop filter parameters, depending on the charge pump input frequency range (output of the reference frequency divider).

When the PLL is locked, it tracks the input frequency ( $f_{REF}$ ) with the ratio of dividers (N/R). The PLL operating status is monitored by the PLL status indication bits: `<PLL_VCOL_STAT>` and `<PLL_VCOH_STAT>` in Address 0xD1 (Register 5-81).

Equation 4-3 shows the VCO output frequency ( $f_{VCO}$ ) as a function of the two dividers and reference frequency:

#### EQUATION 4-3: VCO OUTPUT FREQUENCY

$$f_{VCO} = \left(\frac{N}{R}\right)f_{REF} = 1.075 \text{ (GHz) to } 1.325 \text{ (GHz)}$$

Where:

N = 1 to 4095 controlled by `PLL_PRE<11:0>`

R = 1 to 1023 controlled by `PLL_REFDIV<9:0>`

See Addresses 0x54 to 0x57 (Registers 5-9 – 5-12) for these bits settings.

The tuning range of the VCO is 1.075 GHz to 1.325 GHz. N and R values must be chosen so the VCO is within this range. In general, lower values of the VCO frequency ( $f_{VCO}$ ) and higher values of the charge pump frequency ( $f_Q$ ) should be chosen to optimize the clock jitter. Once the VCO output frequency is determined to be within this range, set the final ADC sampling frequency ( $f_S$ ) with the PLL output divider using `PLL_OUTDIV<3:0>`. Equation 4-4 shows how to obtain the ADC core sampling frequency:

#### EQUATION 4-4: SAMPLING FREQUENCY

$$f_S = \left(\frac{f_{VCO}}{PLL\_OUTDIV}\right) = 80 \text{ MHz to } 250 \text{ MHz}$$

Table 4-8 shows an example of generating  $f_S = 200$  MHz output using the PLL control parameters.

### 4.7.2.2 PLL Calibration

The PLL should be recalibrated following a change in clock input frequency or in the PLL Configuration register bit settings (Addresses 0x54 - 0x57; Registers 5-9 – 5-12).

The PLL can be calibrated by toggling the `PLL_CAL_TRIG` bit in Address 0x6B (Register 5-27) or by sending a `SOFT_RESET` command (See Address 0x00, Register 5-1). The PLL calibration status is observed by the `PLL_CAL_STAT` bit in Address 0xD1 (Register 5-81).

### 4.7.2.3 Monitoring of PLL Drifts

The PLL drifts can be monitored using the status monitoring bits in Address 0xD1 (Register 5-81). Under normal operation, the PLL maintains a lock across all temperature ranges. It is not necessary to actively monitor the PLL unless extreme variations in the supply voltage are expected or if the input reference clock frequency has been changed.



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**TABLE 4-6: PLL CONTROL REGISTER BITS**

Control Parameter	Register	Descriptions
<b>PLL Global Control Bits</b>		
EN_PLL	0x59	Master enable bit for the PLL circuit
EN_PLL_OUT	0x5F	Master enable bit for the PLL output
EN_PLL_BIAS	0x5F	Master enable bit for the PLL bias
EN_PLL_REFDIV	0x59	Master enable bit for the PLL reference divider
<b>PLL Block Setting Bits</b>		
PLL_REFDIV<9:0>	0x54-0x55	PLL reference divider (R) (See <a href="#">Table 4-8</a> )
PLL_PRE<11:0>	0x56-0x57	PLL prescaler (N) (See <a href="#">Table 4-8</a> )
PLL_CHAGPUMP<3:0>	0x58	PLL charge pump bias current control: from 25 $\mu$ A to 375 $\mu$ A, 25 $\mu$ A per step
PLL_RES<4:0>	0x5A	PLL loop filter resistor value selection (See <a href="#">Table 4-7</a> )
PLL_CAP3<4:0>	0x5B	PLL loop filter capacitor 3 value selection (See <a href="#">Table 4-7</a> )
PLL_CAP2<4:0>	0x5D	PLL loop filter capacitor 2 value selection (See <a href="#">Table 4-7</a> )
PLL_CAP1<4:0>	0x5C	PLL loop filter capacitor 1 value selection (See <a href="#">Table 4-7</a> )
<b>PLL Output Control Bits</b>		
PLL_OUTDIV<3:0>	0x55	PLL output divider (See <a href="#">Table 4-8</a> )
DCLK_DLY_PLL<2:0>	0x6D	Delay DCLK output up to 15 cycles of VCO clocks
EN_PLL_CLK	0x6D	EN_PLL_CLK = 1 enable PLL output clock to the ADC circuits
<b>PLL Drift Monitoring Bits</b>		
PLL_VCOL_STAT	0xD1	PLL drift status monitoring bit
PLL_VCOH_STAT	0xD1	PLL drift status monitoring bit
<b>PLL Block Calibration Bits</b>		
PLL_CAL_TRIG	0x6B	Forcing recalibration of the PLL
SOFT_RESET	0x00	PLL is calibrated when exiting soft reset mode
PLL_CAL_STAT	0xD1	PLL auto-calibration status indication



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**TABLE 4-7: RECOMMENDED PLL CHARGE PUMP AND LOOP FILTER BIT SETTINGS**

PLL Charge Pump and Loop Filter Parameter	$f_Q = f_{REF}/PLL\_REFDIV$		
	$f_Q < 5 \text{ MHz}$	$5 \text{ MHz} \leq f_Q < 25 \text{ MHz}$	$f_Q \geq 25 \text{ MHz}$
PLL_CHAGPUMP<3:0>	0x04	0x04	0x04
PLL_RES<4:0>	0x1F	0x1F	0x07
PLL_CAP3<4:0>	0x07	0x02	0x07
PLL_CAP2<4:0>	0x07	0x01	0x08
PLL_CAP1<4:0>	0x07	0x01	0x08

**TABLE 4-8: EXAMPLE OF PLL CONTROL BIT SETTINGS FOR  $f_S = 200 \text{ MHz}$  WITH  $f_{REF} = 100 \text{ MHz}$**

PLL Control Parameter	Value	Descriptions
$f_{REF}$	100 MHz	$f_{REF}$ is coming from the external clock input
Target $f_S$ <sup>(1)</sup>	200 MHz	ADC sampling frequency
Target $f_{VCO}$ <sup>(2)</sup>	1.2 GHz	Range of $f_{VCO} = 1.0375 \text{ GHz} - 1.325 \text{ GHz}$
Target $f_Q$ <sup>(3)</sup>	10 MHz	$f_Q = f_{REF}/PLL\_REFDIV$ (See <a href="#">Table 4-7</a> )
PLL Reference Divider (R)	10	$PLL\_REFDIV<9:0> = 0x0A$
PLL Prescaler (N)	120	$PLL\_PRE<11:0> = 0x78$
PLL Output Divider	6	$PLL\_OUTDIV<3:0> = 0x06$

- Note 1:**  $f_S = f_{VCO}/PLL\_OUTDIV = 1.2 \text{ GHz}/6 = 200 \text{ MHz}$   
**Note 2:**  $f_{VCO} = (N/R) \times f_{REF} = (12) \times 100 \text{ MHz} = 1.2 \text{ GHz}$   
**Note 3:**  $f_Q$  should be maximized for the best noise performance.

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## 4.8 Digital Signal Post-Processing (DSPP) Options

While the device converts the analog input signals to digital output codes, the user can enable various digital signal post-processing (DSPP) options for special applications. These options are individually enabled or disabled by setting the Configuration bits. [Table 4-9](#) summarizes the digital signal post-processing (DSPP) options that are available for each device family.

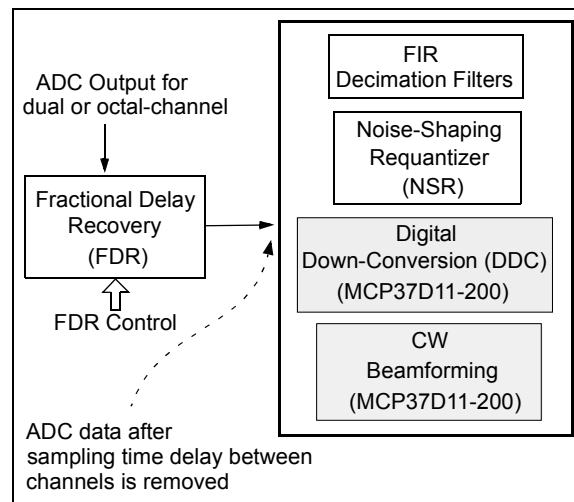
**TABLE 4-9: DIGITAL SIGNAL POST PROCESSING (DSPP) OPTIONS**

Digital Signal Post Processing Option	Available Operating Mode
Fractional Delay Recovery (FDR)	Dual and octal-channel modes
FIR Decimation Filters	<ul style="list-style-type: none"> <li>Single and dual-channel modes</li> <li>CW octal-channel mode</li> <li>DDC for I and Q data</li> </ul>
Noise-Shaping Requantizer (NSR)	Single and dual-channel modes
Digital Gain and Offset correction per channel	Available for all channels
Digital-Down Conversion (DDC)	Single and dual-channel modes CW octal-channel mode
Continuous Wave (CW) Beamforming	CW octal-channel mode

### 4.8.1 FRACTIONAL DELAY RECOVERY FOR DUAL- AND OCTAL-CHANNEL MODES

The FDR feature is available in dual and octal-channel modes only. When FDR is enabled, the built-in high-order, band-limited interpolation filter compensates for the time delay between input samples of different channels. Due to the finite bandwidth of the interpolation filter, the fractional delay recovery is not guaranteed for input frequencies near the Nyquist frequency ( $f_s/2$ ). For example, in dual-channel mode, FDR can operate correctly for input frequencies in the range from 0 to  $0.45 \cdot f_s$  (or from  $0.55 \cdot f_s$  to  $f_s$  if the input is in the 2nd Nyquist band). In octal-channel mode, FDR can operate correctly for input frequencies in the range from 0 to  $0.38 \cdot f_s$ . See [Table 4-11](#) for the summary of the input bandwidth requirement for FDR. The FDR process takes place in the digital domain and requires 59 clock cycles of processing time. Therefore, the output data latency is also increased by 59 clock periods.

[Figure 4-12](#) shows the simplified block diagram for the ADC output data path with FDR. The related Configuration register bits are listed in [Table 4-10](#). [Table 4-11](#) shows the input bandwidth limits of the FDR feature for distortion less than 0.1 mdB ( $0.1 \times 10^{-3}$  dB), where  $f_s$  is the sampling frequency per channel. [Figures 4-13](#) and [4-14](#) show the responses of the dual-channel and octal-channel FDRs, respectively.



**FIGURE 4-12:** Simplified Block Diagram for ADC Output Data Path with Fractional Delay Recovery Option. Note that Fractional Delay Recovery occurs prior to other DSPP features.

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**TABLE 4-10: CONTROL PARAMETERS FOR FRACTIONAL DELAY RECOVERY (FDR)**

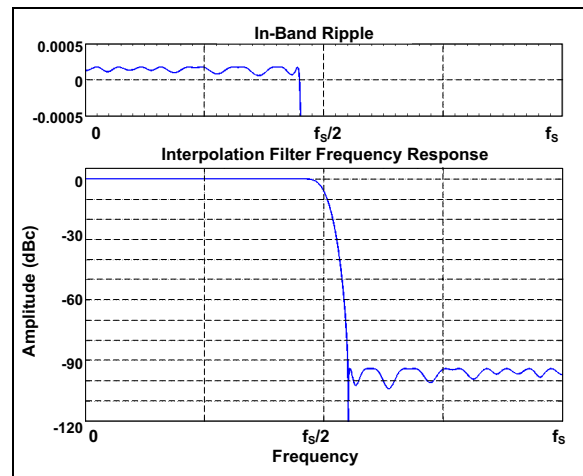
Channel Operation	Control Parameter	Register	Descriptions
Global control for both dual and octal-channel modes	EN_FDR = 1	0x7A	Enable FDR features
	FDR_BAND	0x81	Select 1 <sup>st</sup> or 2 <sup>nd</sup> Nyquist band
Dual-channel	SEL_FDR = 0	0x81	Select FDR for dual-channel mode
	EN_DSPP_8 = 0	0x81	Select digital signal post-processing feature for dual-channel mode
	EN_DSPP_2 = 1	0x79	Enable all digital post-processing functions for dual-channel operation
Octal-channel	SEL_FDR = 1	0x81	Select FDR for octal-channel mode
	EN_DSPP_8 = 1	0x81	Select digital signal post-processing feature for octal-channel operation

**TABLE 4-11: INPUT BANDWIDTH REQUIREMENT FOR FDR**

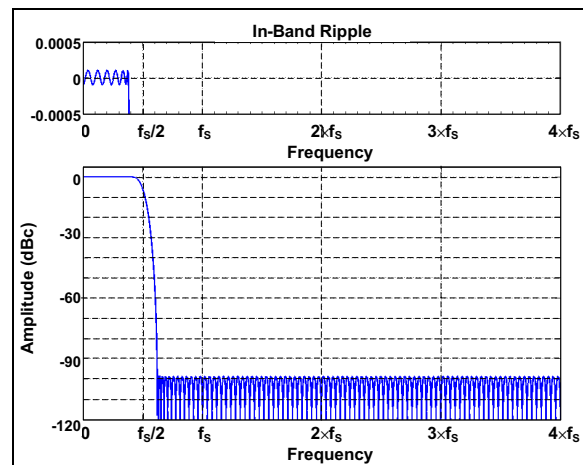
Bandwidth in percentage of $f_s^{(1)}$	Nyquist Band <sup>(2)</sup>
<b>Dual-Channel Mode</b>	
0 – 45%	1 <sup>st</sup> Nyquist Band (FDR_BAND = 0)
55 – 100%	2 <sup>nd</sup> Nyquist Band (FDR_BAND = 1)
45 – 55%	Avoid
<b>Octal-Channel Mode</b>	
0 – 38%	1 <sup>st</sup> Nyquist Band (FDR_BAND = 0)

**Note 1:**  $f_s$  is sampling frequency per channel. Distortion is less than 0.1 mdB.

**2:** See Address 0x81 for FDR\_BAND bit setting



**FIGURE 4-13:** Response of the Dual-Channel Fractional Delay Recovery (1<sup>st</sup> Nyquist Band).  $f_s$  is the Sampling Frequency.



**FIGURE 4-14:** Response of the Octal-Channel Fractional Delay Recovery (1<sup>st</sup> Nyquist Band).  $f_s$  is the Sampling Frequency.

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## 4.8.2 NOISE-SHAPING REQUANTIZER (NSR)

The device includes 11-bit and 12-bit digital Noise-Shaping Requantizer (NSR) options. When this function is enabled (see [Register 5-33](#)), output data is requantized to 11-bit or 12-bit, respectively. The NSR reshapes the requantization noise function and pushes most of the noise outside the frequency band of interest. As a result, the noise floor within the selected bandwidth is substantially lower than that of a typical 12-bit ADC.

To ensure the stability of the NSR, the input signal to the NSR should be limited to less than -0.8 dBFS (~90% of full scale). This can be achieved either by limiting the analog input level or by adjusting the digital gain control. See [Section 4.9 “Digital Offset and Digital Gain Settings”](#) and [Registers 5-63 to 5-70](#) for details on the digital gain control. Input levels higher than -0.8 dBFS may corrupt the NSR output and should be avoided.

The NSR feature is available only for the single- and dual-channel modes and can be independently controlled per channel via the register settings. Two NSRs are used:

- NSRA for channel A
- NSRB for channel B

In single-channel mode, only NSRA is used. In dual-channel mode, both NSRA and NSRB are used: NSRA is used for the first selected channel, and NSRB is used for the second selected channel. Both have 11-bit and 12-bit options. Each NSR block consists of a series of filters which are selectable using the NSRA<6:0> and NSRB<6:0> register bit settings. Each filter is defined by a specific percentage bandwidth and center frequency. The available percentage bandwidths are:

- 11-bit mode: 22% and 25% of the sampling frequency
- 12-bit mode: 25% and 29% of the sampling frequency

The center frequency of the band is tunable such that the frequency band of interest can be placed anywhere within the Nyquist band. [Table 4-12](#) lists all the NSR-related registers. [Equations 4-5](#) and [4-6](#) describe the NSR bandwidth of the 11-bit and 12-bit options, respectively.

## EQUATION 4-5: NSR BANDWIDTH FOR 11-BIT OPTION

(a) 22% BW:

$$\frac{f_{Center}}{f_S} = 0.12 + \frac{0.26}{20} \times NSR$$

where  $0 \leq NSR \leq 20$

(b) 25% BW:

$$\frac{f_{Center}}{f_S} = 0.125 + \frac{0.25}{20} \times (NSR - 21)$$

where  $21 \leq NSR \leq 41$

NSR represents the NSR filter number. See [Tables 4-13](#) and [4-14](#) for details.

## EQUATION 4-6: NSR BANDWIDTH FOR 12-BIT OPTION

(a) 25% BW:

$$\frac{f_{Center}}{f_S} = 0.125 + \frac{0.25}{20} \times (NSR - 42)$$

where  $42 \leq NSR \leq 62$

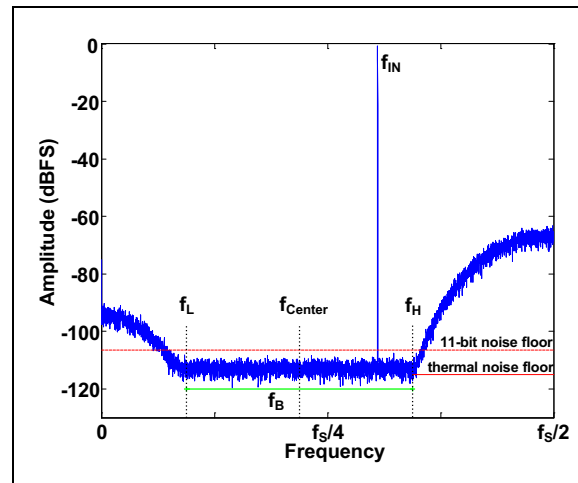
(b) 29% BW:

$$\frac{f_{Center}}{f_S} = 0.15 + \frac{0.2}{12} \times (NSR - 63)$$

where  $63 \leq NSR \leq 76$

NSR represents the NSR filter number. See [Tables 4-13](#) and [4-14](#) for details.

The center frequency of the band is tuned such that the frequency spectrum of interest can be placed anywhere within the Nyquist band. [Figure 4-15](#) shows a graphical demonstration of the NSR bandwidth, which is a percentage of the ADC sampling frequency.



**FIGURE 4-15:** Graphical demonstration of the NSR filter's transfer function. Note that  $f_B$  is controlled as a percentage of the sampling frequency ( $f_S$ ).

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Tables 4-13 and 4-14 show the NSR filter selections. The selectable filters (tuning word) for each mode are:

- 11-bit mode: 0 to 41
- 12-bit mode: 42 to 76

NSR does not affect harmonic distortion. Various FFT spectrum plots when NSR is applied are shown in Figures 3-14 to 3-15, Figures 3-17 to 3-20 and Figures 3-22 to 3-23. SNR and SFDR performance versus input amplitude when NSR is enabled is shown in Figures 3-26 and 3-29.

In this case, SNR and SFDR are measured within the 12-bit mode NSR bandwidth (25% of the sampling frequency). When the NSR block is disabled, the ADC data is provided directly to the output.

**TABLE 4-12: REGISTER CONTROL PARAMETERS FOR NSR**

Control Parameter	Register	Descriptions
<b>NSR Enable bits</b>		
<EN_NSRA_11>	0x7A	Enable 11-bit NSR for channel A
<EN_NSRA_12>	0x7A	Enable 12-bit NSR for channel A
<EN_NSRB_11>	0x7A	Enable 11-bit NSR for channel B
<EN_NSRB_12>	0x7A	Enable 12-bit NSR for channel B
<b>NSR Settings</b>		
NSRA<6:0>	0x78	NSR A settings for single-channel or channel A for dual-channel mode
NSRB<6:0>	0x79	NSR B settings for channel B in dual-channel mode
<b>NSR Block Reset Control</b>		
<EN_NSR_RESET>	0x78	Resets NSR in the event of overload
<b>Digital Post Processing (DPP) Function Block Settings</b>		
EN_DPPDUAL	0x79	Enable DPP block for dual-channel mode

**TABLE 4-13: 11-BIT NSR FILTER SELECTION<sup>(1)</sup>**

NSR Filter No. (Tuning Word)	$f_{\text{Center}}/f_s$	$f_B$ (% of $f_s$ )	NSRA<6:0> NSRB<6:0>
0	0.12	22	000-0000
1	0.133	22	000-0001
2	0.146	22	000-0010
—			
—			
19	0.367	22	001-0011
20	0.38	22	001-0100
21	0.125	25	001-0101
22	0.1375	25	001-0110
23	0.15	25	001-0111
—			
—			
40	0.3625	25	010-1000
41	0.375	25	010-1001

**Note 1:** Filters 0 - 41 are used for 11-bit mode only. If these are used for 12-bit mode, the output becomes unknown state.

**TABLE 4-14: 12-BIT NSR FILTER SELECTION<sup>(1)</sup>**

NSR Filter No. (Tuning Word)	$f_{\text{Center}}/f_s$	$f_B$ (% of $f_s$ )	NSRA<6:0> NSRB<6:0>
42	0.125	25	010-1010
43	0.1375	25	010-1011
44	0.15	25	010-1100
—			
61	0.3625	25	011-1101
62	0.375	25	011-1110
63	0.15	29	011-1111
64	0.1667	29	100-0000
65	0.1833	29	100-0001
—			
—			
75	0.35	29	100-1011
76	0.3667	29	100-1100

**Note 1:** Filters 42 - 76 are used for 12-bit mode only. If these are used for 11-bit mode, the output becomes unknown state.

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## 4.8.3 DECIMATION FILTERS

The decimation feature is available in single and dual-channel modes and CW octal-channel mode. [Figure 4-16](#) shows a simplified decimation filter block, and [Table 4-16](#) shows the register settings. The decimation rate is controlled by FIR\_A<8:0> and FIR\_B<7:0> register settings (Addresses 0x7A – 0x7C: [Registers 5-35 - 5-37](#)). These registers are thermometer encoded.

In single-channel mode, FIR B is disabled and only FIR A is used. In this mode, the maximum programmable decimation rate is 512x using nine cascaded decimation stages.

In dual-channel mode or when using the Digital Down-Conversion (DDC) in I/Q mode, both FIR A and FIR B are used (see [Figure 4-16](#)). In this case, both channels are set to the same decimation rate. Note that stage 1A in FIR A is unused: the user must clear FIR\_A<0> in Address 0x7A ([Register 5-35](#)). In dual-channel mode, the maximum programmable decimation rate is up to 256x, which is half the single-channel decimation rate (512x).

The overall SNR performance can be improved with higher decimation rate, but limited to about 73.7 dBFS after 16x. This limitation is mainly due to the relative quantization noise level with respect to the 12-bit LSB size. Decimation rates beyond 16x do not further improve SNR but do serve to filter the output data and reduce the overall output data rate. [Table 4-15](#) summarizes decimation rate versus SNR.

**TABLE 4-15: DECIMATION RATE VS. SNR PERFORMANCE**

Decimation Rate	SNR (dBFS)
2x	71.4
4x	72.2
8x	72.9
16x	73.3
32x	73.7
64x	
128x	
256x	
512x	

**Note:** The above data is validated with  $f_S = 200$  Msps,  $f_{IN} = 5$  MHz,  $A_{IN} = -1$  dBFS.

### 4.8.3.1 Output Data Rate and Clock Phase Control When Decimation is Used

When decimation is used, it also reduces the output clock rate and output bandwidth by a factor equal to the decimation rate applied: the output clock rate is therefore no longer equal to the ADC sampling clock. The user needs to adjust the output clock and data rates in Address 0x02 ([Register 5-3](#)) based on the decimation applied. This allows the output data to be synchronized to the output data clock.

Phase shifts in the output clock can be achieved using DCLK\_PHDLY\_DEC<2:0> in Address 0x64 ([Register 5-22](#)). Only four output sampling phases are available when a decimation rate of 2x is used, while all eight clock phases are available for other decimation rates. See [Section 4.12.8 “Output Data and Clock Rates”](#) for more details.

### 4.8.3.2 Using Decimation with CW Beamforming and Digital Down-Conversion

Decimation can be used in conjunction with CW octal-channel mode or DDC. In CW octal-channel mode operation, the eight input channels are summed into a single channel prior to entering the decimation filters. When DDC is enabled, the I and Q outputs can be decimated using the same signal path for the dual-channel mode: I and Q data are fed into Channel A and B, respectively.

In DDC mode, the half-band filter already includes a 2x decimation rate. Therefore, the maximum decimation rate setting for I/Q filtering is 128x for the FIR\_A<8:1> and FIR\_B<7:0>. See [Section 4.8.4 “Digital Down-Conversion \(MCP37D11-200 only\)”](#) for details.

**Note:** Fractional Delay Recovery, Digital Gain/Offset adjustment and DDC for I/Q data options occur prior to the decimation filters if they are enabled.

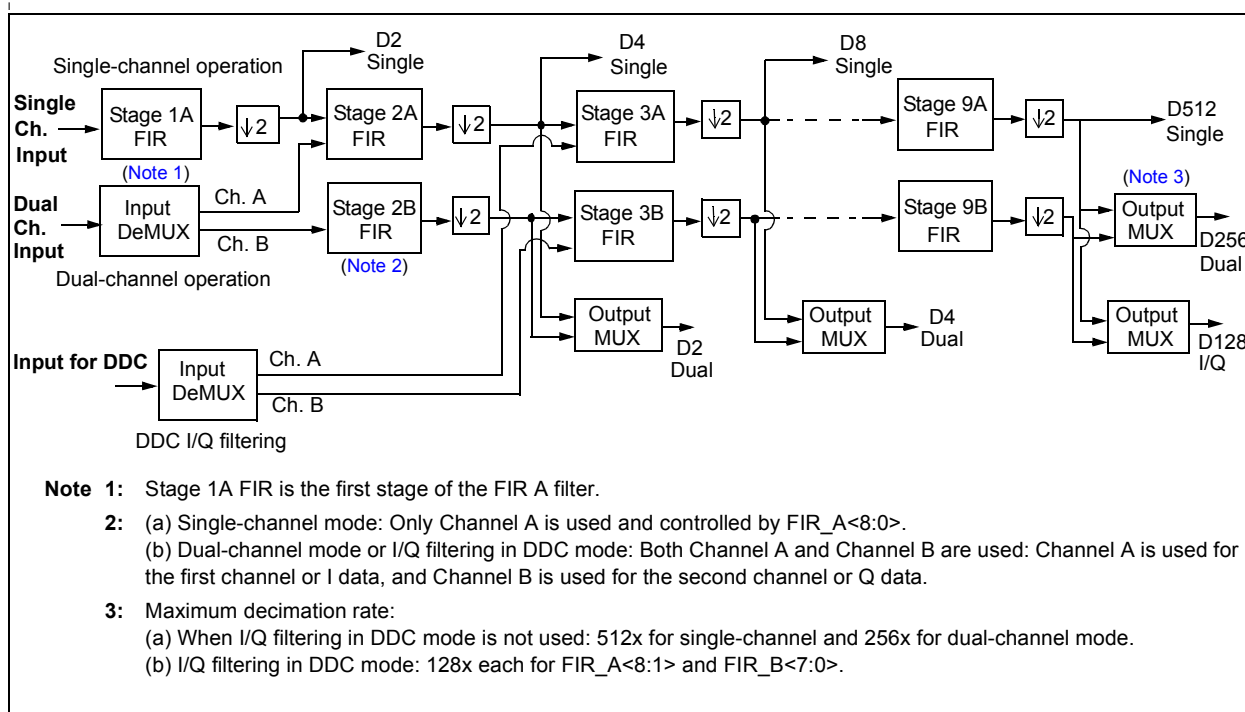
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**TABLE 4-16: REGISTER CONTROL PARAMETERS FOR USING DECIMATION FILTERS**

Control Parameter	Register	Descriptions
<b>Decimation Filter Settings</b>		
FIR_A<8:0>	0x7A, 0x7B	Channel A FIR configuration for single- or dual-channel mode
FIR_B<7:0>	0x7C	Channel B FIR configuration for single- or dual-channel mode
<b>Output Data Rate and Clock Rate Settings<sup>(1)</sup></b>		
OUT_DATARATE<3:0>	0x02	Output data rate: Equal to decimation rate
OUT_CLKRATE<3:0>	0x02	Output clock rate: Equal to decimation rate
<b>Output Clock Phase Control Settings<sup>(2)</sup></b>		
EN_PHDLY	0x64	Enable digital output phase delay when decimation filter is used
DCLK_PHDLY_DEC<2:0>	0x64	Digital output clock phase delay control
<b>Digital Signal Post-Processing (DSPP) Function Block Settings</b>		
EN_DSPP_2 = 1	0x79	Enable dual-channel decimation

**Note 1:** The output data and clock rates must be updated when decimation rates are changed.

**Note 2:** Output clock (DCLK) phase control is used when the output clock is divided by OUT\_CLKRATE<3:0> bit settings.



**FIGURE 4-16:** Simplified Block Diagram of Decimation Filters.



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## 4.8.4 DIGITAL DOWN-CONVERSION (MCP37D11-200 ONLY)

The Digital Down-Conversion (DDC) feature is available in single-, dual- and CW octal-channel modes in the MCP37D11-200. This feature can be optionally combined with the decimation filter and used to:

- translate the input frequency spectrum to a lower frequency band
- remove the unwanted out-of-band portion
- output the resulting signal as either I/Q data or as a real signal centered at 25% of the output data rate.

Figure 4-17 and Figure 4-18 show the DDC configuration for single- and dual-channel DDC mode, respectively. The DDC includes a 32-bit, complex numerically controlled oscillator (NCO), a selectable (high/low) half-band filter, optional decimation, and two output modes (I/Q or  $f_s/8$ ).

Frequency translation is accomplished with the NCO. The NCO frequency is programmable from 0 Hz to  $f_s$ . Phase and amplitude dither can be enabled to improve spurious performance of the NCO.

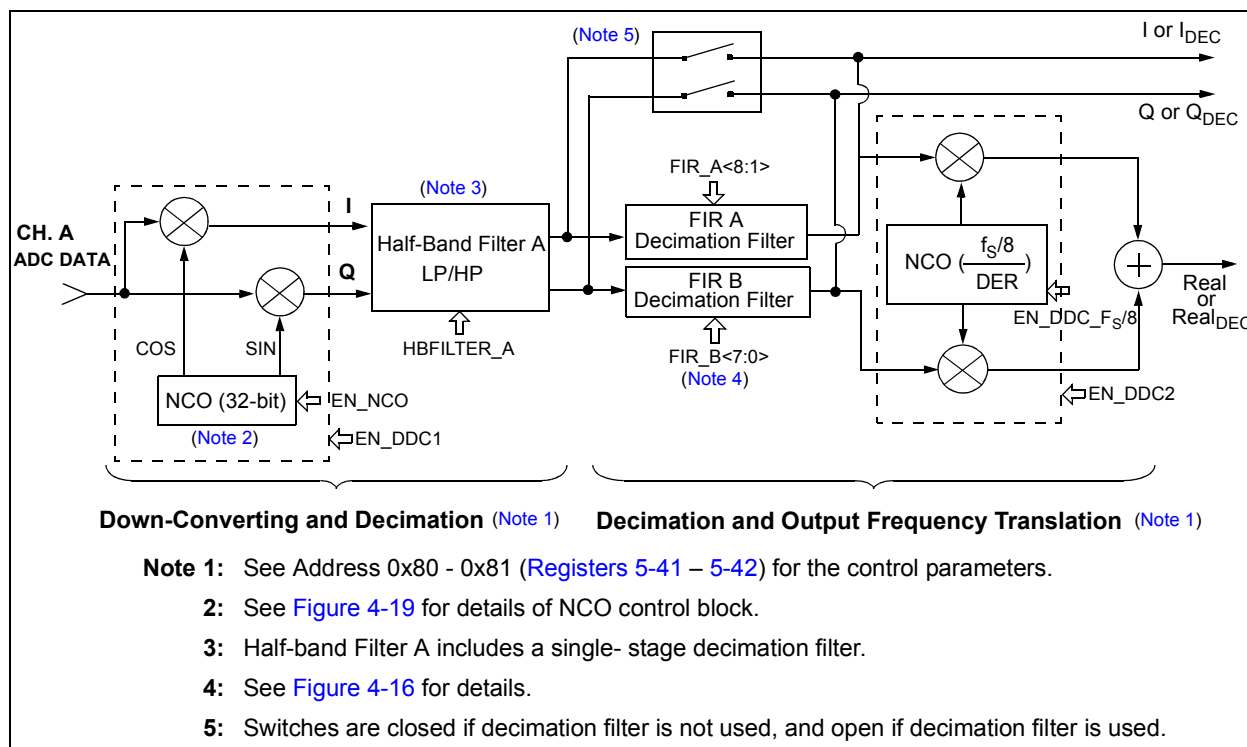
This DDC feature can be used in a variety of high-speed signal-processing applications, including digital radio, wireless base stations, radar, cable modems, digital video, MRI imaging, etc.

### Example:

If the ADC is sampling an input at 200 Msps, but the user is only interested in a 5 MHz span which is centered at 67 MHz, the digital down-conversion may be used to mix the sampled ADC data with 67 MHz to convert it to DC. The resulting signal can then be decimated by 16x such that the bandwidth of the ADC output is 6.25 MHz (200 Msps/16x decimation gives 12.5 Msps with 6.25 MHz Nyquist bandwidth). If  $f_s/8$  mode is selected, then a single 25 Msps channel is output, where 6.25 MHz in the output data corresponds to 67 MHz at the ADC input. If I/Q mode is selected, then two 12.5 Msps channels are output, where DC corresponds to 67 MHz and the channels represent in-phase (I) and quadrature (Q) components of the down-conversion.

### 4.8.4.1 Single-Channel DDC

Figure 4-17 shows the single-channel DDC configuration. Each of these processing sub-blocks are individually controlled. Examples of setting registers for selected output type are shown in Tables 4-17 and 4-18.



**FIGURE 4-17:** Simplified DDC Block Diagram for Single-Channel Mode. See Tables 4-17 and 4-18 for Using This DDC Block.

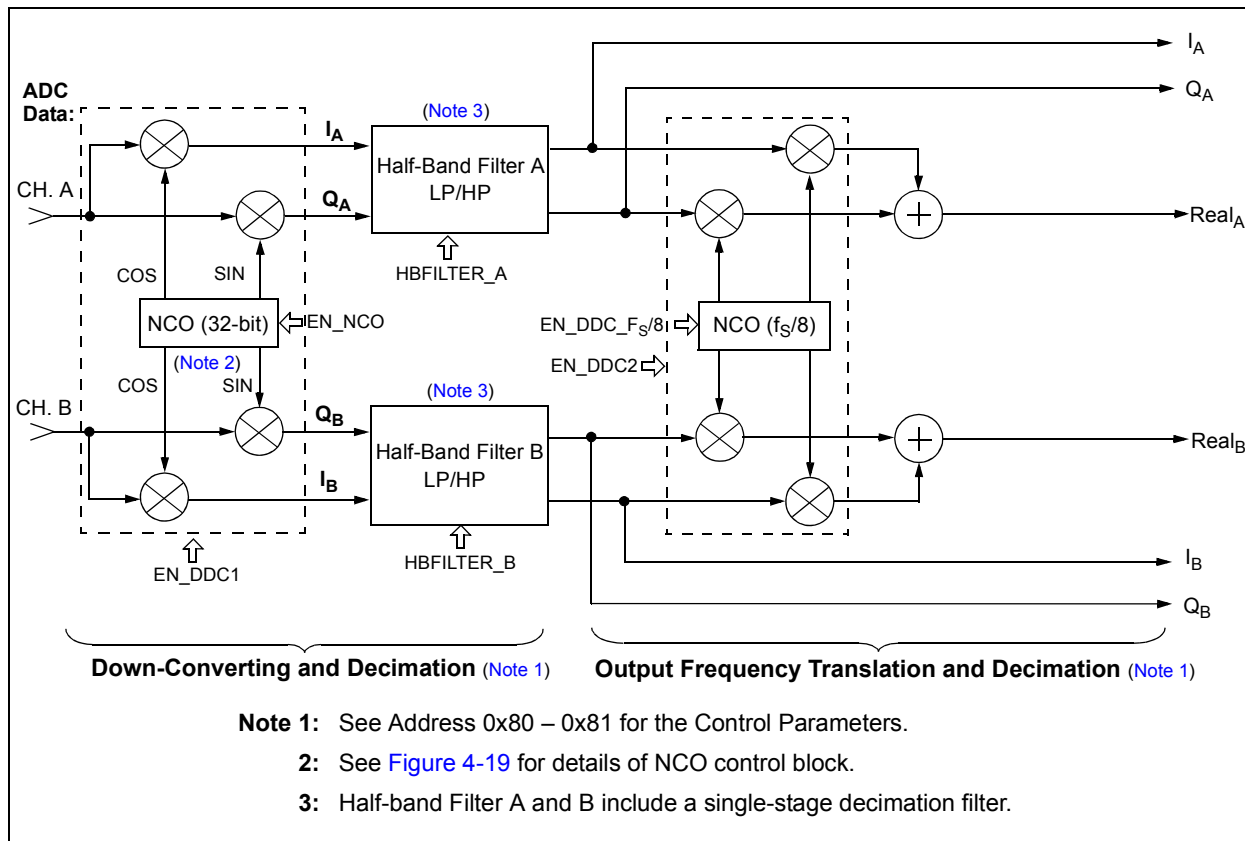


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## 4.8.4.2 Dual-Channel DDC

Figure 4-18 shows the dual-channel DDC configuration. Each channel includes the same processing elements as shown in the single-channel DDC, however the I/Q outputs cannot be separately decimated since the device only supports two channels of decimation (four would be required for I/Q of Channel A and I/Q of Channel B). The decimation option can be used if the DDC output after the half-band filter is up-converted by

$f_s/8$  for each channel. Otherwise, I/Q of each channel will be output separately, similar to a four-channel input device with the WCK output pin toggling synchronously with the I-data of Channel A. Note that the NCO phase can be adjusted uniquely for each of the two input channels (see Figure 4-19). Examples of setting registers for selected output type are shown in Tables 4-19 and 4-20.



**FIGURE 4-18:** Simplified DDC Block Diagram for Dual-Channel Mode. See Tables 4-19 and 4-20 for Using this DDC Block.

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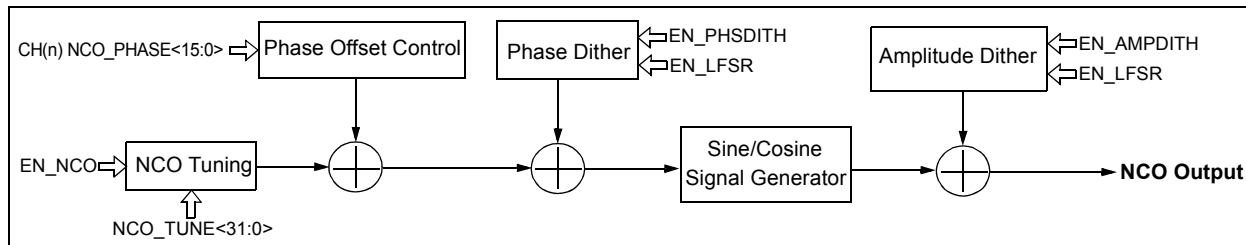
## 4.8.4.3 Numerically Controlled Oscillator (NCO)

The on-board Numerically Controlled Oscillator (NCO) provides the frequency reference for the in-phase and quadrature mixers in the digital down-converter (DDC).

The NCO serves as a quadrature local oscillator, capable of producing an NCO frequency of between 0 Hz and  $f_S$  with a resolution of  $f_S/2^{32}$ , where  $f_S$  is the ADC core sampling frequency.

Figure 4-19 shows the control signals associated with the NCO. In octal- or dual-channel mode, the NCO allows the output phase to be adjusted on a per-channel basis.

**Note:** The NCO is only used for DDC or CW octal-channel mode. It should be disabled when not in use.



**FIGURE 4-19:** NCO Block Diagram.

### • NCO Frequency Control:

The NCO frequency is programmed from 0 Hz to  $f_S$ , using the 32-bit-wide unsigned register variable `NCO_TUNE<31:0>` in Addresses 0x82 – 0x85 (Registers 5-43 – 5-46).

The following equation is used to set the `NCO_TUNE<31:0>` register:

### EQUATION 4-7: NCO FREQUENCY

$$NCO\_TUNE<31:0> = \text{round}\left(2^{32} \times \frac{\text{Mod}(f_{NCO}, f_S)}{f_S}\right)$$

Where:

$f_S$  = sampling frequency (Hz)

$f_{NCO}$  = desired NCO frequency (Hz)

$\text{Mod}(f_{NCO}, f_S)$  = gives the remainder of  $f_{NCO}/f_S$

$\text{Mod}()$  is a remainder function. For example,  $\text{Mod}(5,2) = 1$  and  $\text{Mod}(1.999, 2) = 1.999$ .

#### Example 1:

If  $f_{NCO}$  is 100 MHz and  $f_S$  is 200 MHz:

$$\begin{aligned} \text{Mod}(f_{NCO}, f_S) &= \text{Mod}(100, 200) = 100 \\ NCO\_TUNE<31:0> &= \text{round}\left(2^{32} \times \frac{\text{Mod}(100, 200)}{200}\right) \\ &= 0x8000\ 0000 \end{aligned}$$

#### Example 2:

If  $f_{NCO}$  is 199.99999994 MHz and  $f_S$  is 200 MHz:

$$\begin{aligned} \text{Mod}(f_{NCO}, f_S) &= \text{Mod}(199.99999994, 200) = 199.99999994 \\ NCO\_TUNE<31:0> &= \text{round}\left(2^{32} \times \frac{\text{Mod}(199.99999994, 200)}{200}\right) \\ &= 0xFFFF\ FFFF \end{aligned}$$

### 4.8.4.4 NCO Amplitude and Phase Dither

The `EN_AMPDITH` and `EN_PHSDITH` parameters in Address 0x80 (Register 5-41) can be used for amplitude and phase dithering, respectively. In principle, these will dither the quantization error created by the use of digital circuits in the mixer and local oscillator, thus reducing spurs at the expense of noise. In practice, the DDC circuitry has been designed with sufficient noise and spurious performance for most applications. In the worst-case scenario, the NCO has an SFDR of greater than 116 dB when the amplitude dither is enabled, and 112 dB when disabled. Although the SNR ( $\approx 93$  dB) of the DDC is not significantly affected by the dithering option, using the NCO with dithering options enabled is always recommended for the best performance.

### 4.8.4.5 NCO for $f_S/8$ and $f_S/(8 \times \text{DER})$

The output of the first down-conversion block (DDC1) is a complex signal (comprising I and Q data) which can then be optionally decimated further up to 128x to provide both a lower output data rate and input channel filtering. If  $f_S/8$  mode is enabled, a second mixer stage (DDC2) will convert the I/Q signals to a real signal centered at half of the current Nyquist frequency; i.e., if the output data rate in I/Q mode is 25 Msps per channel (12.5 MHz Nyquist), then in  $f_S/8$  mode the output data rate would be 50 Msps (25 Msps each for I and Q), and the signal would be re-centered around 12.5 MHz. In single-channel mode, this is done at the output of the decimation filters (if used). In dual-channel mode, this must be done prior to the decimation.

When decimation is enabled, the I/Q outputs are up-converted by  $f_S/(8 \times \text{DER})$ , where DER is the additional decimation rate added by the FIR decimation filters. This provides a decimated output signal centered at  $f_S/8$  or  $f_S/(8 \times \text{DER})$  in the frequency domain.

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## 4.8.4.6 NCO Phase Offset Control

The user can add phase offset to the NCO frequency using the NCO phase offset control registers (Addresses 0x86 to 0x95, [Registers 5-47 – 5-62](#)). CH(n)\_NCO\_PHASE<15:0> is the 16-bit-wide NCO phase offset control parameter for Channel *n*. A 0x0000 value in the register corresponds to no offset, and a 0xFFFF corresponds to an offset of 359.995°. The phase offset can be controlled with 0.005° per step. The following equation is used to program the NCO phase offset register:

### EQUATION 4-8: NCO PHASE OFFSET

$$CH(n)\_NCO\_PHASE<15:0> = 2^{16} \times \frac{\text{Offset Value } (\phi)}{360}$$

Where:

*n* = channel number  
Offset Value ( $\phi$ ) = desired phase offset value in degrees

A decimal number is used for the binary contents of CH(n)\_NCO\_PHASE<15:0>.

## 4.8.4.7 In-Phase and Quadrature Signals

When the first down-conversion is enabled, it produces In-phase (I) and Quadrature (Q) components as shown in [Equation 4-9](#):

### EQUATION 4-9: I AND Q SIGNALS

$$I = ADC \times \cos(2\pi f_{NCO}t + \phi) \quad (a)$$

$$Q = ADC \times \sin(2\pi f_{NCO}t + \phi) \quad (b)$$

where:

$$\phi = 360 \times \frac{CH(n)\_NCO\_PHASE<15:0>}{2^{16}} \quad (c)$$

$$= 0.005493164^\circ \times CH(n)\_NCO\_PHASE<15:0>$$

where:

ADC = output of the ADC block  
 $\phi$  = NCO phase offset of selected channel, which is defined by CH(n)\_NCO\_PHASE<15:0> in Addresses 0x86 - 0x95  
*t* = *k*/f<sub>S</sub>, with *k* = 1, 2, 3,..., *n*  
f<sub>NCO</sub> = NCO frequency

I and Q outputs are interleaved where I data is output on the rising edge of the WCK. If I and Q outputs are selected in dual-channel mode with DDC enabled, I data of Channel 0 is output at the rising edge of WCK, followed by Q data of Channel 0, then I and Q data of Channel 1 in the same way.

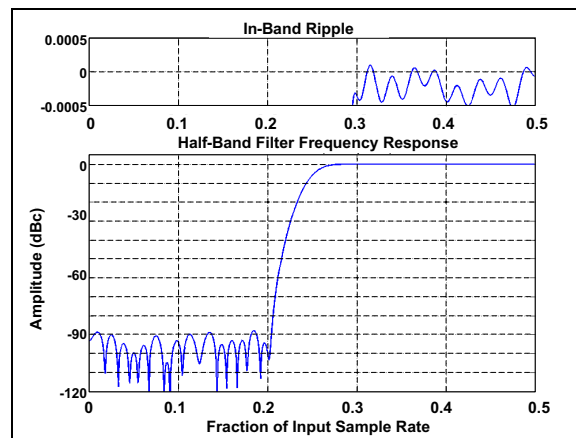
## 4.8.4.8 Half-Band Filter

The frequency translation is followed by a half-band digital filter, which is used to reduce the sample rate by a factor of two while rejecting aliases that fall into the band of interest.

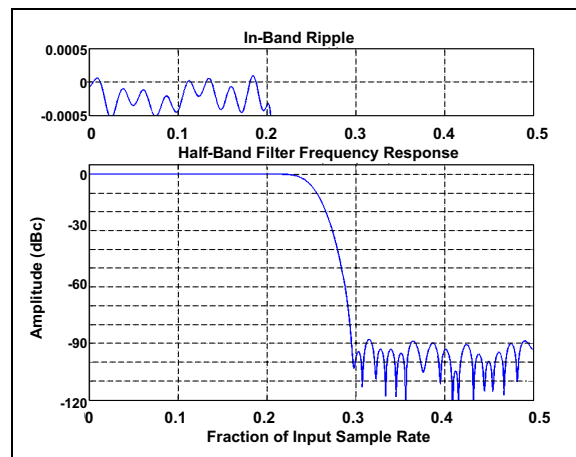
The user can select high- or low-pass half-band filter using the HBFILTER\_A and HBFILTER\_B bits in Address 0x80 ([Register 5-41](#)). These filters provide greater than 90 dB of attenuation in the attenuation band and less than 1 mdB (10<sup>-3</sup> dB) of ripple in the passband region of 20% of the input sampling rate. For example, for an ADC sample rate of 200 MSPS, these filters provide less than 1 mdB of ripple over a bandwidth of 40 MHz.

The filter responses shown in [Figures 4-16 and 4-17](#) indicate a ripple of 0.5 mdB and an alias rejection of 90 dB. The output of the half-band filter is a DC-centered complex signal (I and Q). This I and Q signal is then carried to the next down-conversion stage (DDC2) for frequency translation (up-conversion), if the DDC is enabled.

**Note:** The half-band filter delays the data output by 80 clock cycles: 2 (due to decimation) x 40 cycles (due to group delay)



**FIGURE 4-20:** High-Pass (HP) Response of Half-Band Filter.



**FIGURE 4-21:** Low-Pass (LP) Response of Half-Band Filter.

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## 4.8.5 EXAMPLES OF REGISTER SETTINGS FOR USING DDC AND DECIMATION

The following tables show examples of setting registers for using decimation and digital down-conversion (DDC) depending on the output type selection. This feature is available in the MCP37D11-200 device only.

**TABLE 4-17: REGISTER SETTINGS FOR DECIMATION AND DDC OPTIONS FOR SINGLE-CHANNEL MODE – EXAMPLE**

Decimation Rate (by FIR A and FIR B) <sup>(1)</sup>	DDC Mode	Addr. 0x02 <sup>(2)</sup>	FIR A Filter		FIR B Filter	DDC1	DDC2	Dual-Channel DSPP Control	Output
			0x7A<6> (FIR_A<0>)	0x7B (FIR_A<8:1>)	0x7C (FIR_B<7:0>)	0x80<5,1,0> <sup>(3)</sup>	0x81<6,3,2> <sup>(4)</sup>	0x79<7> (EN_DSPP_2)	
0	Disabled	0x00	0	0x00	0x00	0, 0, 0	0, 0, 0	0	ADC
8	Disabled	0x33	1	0x03	0x00	0, 0, 0	0, 0, 0	0	ADC with decimation (÷8)
512	Disabled	0x99	1	0xFF	0x00	0, 0, 0	0, 0, 0	0	ADC with decimation (÷512)
0	I/Q	0x00 <sup>(5)</sup>	0	0x00	0x00	1, 0, 1	0, 0, 0	0	I/Q Data
8	I/Q	0x33	0	0x07	0x07	1, 0, 1	0, 0, 0	0	Decimated I/Q (÷8)
0	f <sub>S</sub> /8	0x11 <sup>(6)</sup>	0	0x00	0x00	1, 1, 1	0, 0, 0	0	Real without additional decimation
8	f <sub>S</sub> /8	0x44	0	0x07	0x07	1, 0, 1	1, 0, 0	0	Real with decimation (÷16)

- Note 1:** When DDC is used, the actual total decimation is 2x larger since 2x is included from the DDC Half-Band Filter.  
Example: Decimation = 8x with DDC-I/Q option actually has 16x decimation with 8x provided by the decimation filter and 2x from the DDC Half-Band Filter.
- 2:** Output data and clock rate control register.
- 3:** 0x80<5,1,0> = <EN\_NCO, EN\_DDC\_FS/8, EN\_DDC1>.
- 4:** 0x81<6,3,2> = <EN\_DDC2, EN\_DSPP\_8, 8CH\_CW>.
- 5:** Each of I/Q has 1/2 of f<sub>S</sub> bandwidth. The combined bandwidth is the same as the f<sub>S</sub> bandwidth. Therefore the data rate adjustment is not needed.
- 6:** The Half-Band Filter A includes decimation of 2.

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**TABLE 4-18: OUTPUT TYPE VS. CONTROL PARAMETERS FOR SINGLE-CHANNEL DDC (EXAMPLE)**

Output Type	Control Parameter	Register	Descriptions
Complex: I and Q	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 0	0x80	NCO( $f_S/8/DER$ ) is disabled
	EN_DDC2 = 0	0x81	DDC2 is disabled
	FIR_A<8:1> = 0x00	0x7B	FIR A decimation filter is disabled
	FIR_B<7:0> = 0x00	0x7C	FIR B decimation filter is disabled
	OUT_CLKRATE<3:0>	0x02	Output clock rate is not affected (no need to change)
Decimated I and Q: $I_{DEC}$ , $Q_{DEC}$	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 0	0x80	NCO( $f_S/8/DER$ ) is disabled
	EN_DDC2 = 0	0x81	DDC2 is disabled
	FIR_A<8:1>	0x7B	Program FIR A filter for extra decimation <sup>(1)</sup>
	FIR_B<7:0>	0x7C	Program FIR B filter for extra decimation <sup>(1)</sup>
	OUT_CLKRATE<3:0>	0x02	Adjust the output clock rate to the decimation rate
Real: $Real_A$ after DDC( $f_S/8/DER$ ) without using Decimation Filter	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO( $f_S/8/DER$ ) is enabled. This translates the input signal from dc to $f_S/8$ <sup>(2)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1> = 0x00	0x7B	Decimation filter FIR A is disabled
	FIR_B<7:0> = 0x00	0x7C	Decimation filter FIR B is disabled
	OUT_CLKRATE<3:0> = 0001	0x02	Adjust the output clock rate to divided by 2 <sup>(3)</sup>
Decimated Real: $Real_{A\_DEC}$ after Decimation Filter and DDC( $f_S/8/DER$ )	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO( $f_S/8/DER$ ) is enabled. This translates the input signal from dc to $f_S/8/DER$ <sup>(2)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1>	0x7B	Program FIR B filter for extra decimation <sup>(4)</sup>
	FIR_B<7:0>	0x7C	Program FIR B filter for extra decimation <sup>(4)</sup>
	OUT_CLKRATE<3:0>	0x02	Adjust the output clock rate to the total decimation rate including the 2x decimation by the Half-Band Filter A

**Note 1:** For I/Q decimation, the maximum decimation rate for the FIR A and FIR B filters is 128x each since the input is already decimated by 2x in the Half-Band Filter. See [Figure 4-16](#) for details.

**2:** DER is the decimation rate setting of the FIR A and FIR B filters.

**3:** Divided by 2 is due to the 2x decimation included in the Half-Band Filter A.

**4:** When this filter is used, the up-conversion frequency is reduced by the extra decimation rates (DER).

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**TABLE 4-19: REGISTER SETTINGS FOR DECIMATION AND DDC OPTIONS FOR DUAL-CHANNEL MODE EXAMPLE**

Decimation Rate (by FIR A and FIR B) <sup>(1)</sup>	DDC-Mode	Address 0x02 <sup>(2)</sup>	FIR A Filter		FIR B Filter	DDC1	DDC2	Dual-Channel DSPP Control	Output
			0x7A<6> (FIR_A<0>)	0x7B (FIR_A<8:1>)	0x7C (FIR_B<7:0>)	0x80<5,1,0> <sup>(3)</sup>	0x81<6,3,2> <sup>(4)</sup>	0x79<7> (EN_DSPP_2)	
0	Disabled	0x00	0	0x00	0x00	0,0,0	0,0,0	0	ADC
8	Disabled	0x33	0	0x07	0x07	0,0,0	0,0,0	0	ADC with decimation (+8)
256	Disabled	0x88	0	0xFF	0xFF	0,0,0	0,0,0	0	ADC with decimation (+256)
0	I/Q	0x00 <sup>(5)</sup>	0	0x00	0x00	1,0,1	0,0,0	1	I/Q data
0	$f_S/8$	0x11 <sup>(6)</sup>	0	0x00	0x00	1,1,1	0,0,0	1	Real without additional decimation
8	$f_S/8$	0x44	0	0x0E	0x0E <sup>(7)</sup>	1,1,1	0,0,0	1	Real with decimation filter (+16)

- Note 1:** When DDC is used, the actual total decimation is 2x larger since 2x is included from the DDC Half-Band Filter.  
Example: Decimation = 8x with DDC- $f_S/2$  option actually has 16x decimation with 8x provided by the decimation filter and 2x from the DDC Half-Band Filter.
- Note 2:** Output data and clock rate control register.
- Note 3:** 0x80<5,1,0> = <EN\_NCO, EN\_DDC\_FS/8, EN\_DDC1>.
- Note 4:** 0x81<6,3,2> = <EN\_DDC2, EN\_DSPP\_8, 8CH\_CW>.
- Note 5:** Each of I/Q has 1/2 of  $f_S$  bandwidth. The combined bandwidth is the same as the  $f_S$  bandwidth. Therefore the data rate adjustment is not needed.
- Note 6:** The Half-Band Filter A/B includes decimation of 2.
- Note 7:** 0x0E takes into account the stages 1 and 2 are bypassed. See [Figure 4-16](#) for “dual-channel Input” for DDC.

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**TABLE 4-20: OUTPUT TYPE VS. CONTROL PARAMETERS FOR DUAL-CHANNEL DDC EXAMPLE**

Output Type	Control Parameter	Register	Descriptions
Complex: I and Q	EN_DSPP_2 = 1	0x79	Enable all digital post-processing functions for dual-channel operations
	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	HBFILTER_B = 1	0x80	Enable Half-Band Filter B, includes 2x decimation
	EN_DDC_FS/8 = 0	0x80	NCO( $f_S/8/DER$ ) is disabled
	EN_DDC2 = 0	0x81	DDC2 is disabled
	FIR_A<8:1> = 0x00	0x7B	FIR A decimation filter is disabled
	FIR_B<7:0> = 0x00	0x7C	FIR B decimation filter is disabled
	OUT_CLKRATE<3:0>	0x02	Output clock rate is not affected (no need to change)
Real: Real <sub>A</sub> for Channel A and Real <sub>B</sub> for Channel B after NCO( $f_S/8/DER$ ) Without Using Decimation Filter	EN_DSPP_2 = 1	0x79	Enable all digital post-processing functions for dual-channel operations
	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	HBFILTER_B = 1	0x80	Enable Half-Band Filter B, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO( $f_S/8/DER$ ) is enabled. This translates the input signal from DC to $f_S/8$ <sup>(1)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1> = 0x00	0x7B	Decimation filter FIR A is disabled
	FIR_B<7:0> = 0x00	0x7C	Decimation filter FIR B is disabled
	OUT_CLKRATE<3:0> = 0001	0x02	Adjust the output clock rate to divided by 2 <sup>(2)</sup>
Decimated Real: Real <sub>A_DEC</sub> for Channel A and Real <sub>B_DEC</sub> for Channel B after NCO( $f_S/8/DER$ ) and Decimation Filter	EN_DSPP_2 = 1	0x79	Enable all digital signal post-processing functions for dual-channel operation
	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	HBFILTER_B = 1	0x80	Enable Half-Band Filter B, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO( $f_S/8/DER$ ) is enabled. This translates the input signal from DC to $f_S/8/DER$ <sup>(1)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1>	0x7B	Program FIR A filter for extra decimation <sup>(3)</sup>
	FIR_B<7:0>	0x7C	Program FIR B filter for extra decimation <sup>(3)</sup>
	OUT_CLKRATE<3:0>	0x02	Adjust the output clock rate to the total decimation rate including the 2x decimation by the Half-Band Filter A

**Note 1:** DER is the decimation rate setting of the FIR A and FIR B filters.

**2:** Divided by 2 is due to the 2x decimation included in the Half-Band Filter A.

**3:** When this filter is used, the up-conversion frequency is reduced by the extra decimation rates (DER).



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## 4.9 Digital Offset and Digital Gain Settings

Figure 4-22 shows a simplified block diagram of the digital offset and gain settings. Offset is applied prior to the gain. Offset and gain adjustments occur prior to DDC, Decimation or FDR when these features are used.

### 4.9.1 DIGITAL OFFSET SETTINGS

The offset can be corrected using a 16-bit-wide global offset correction register (0x66) for all channels, offset correction registers for individual channels (0x9E-0xA7) or by combining both global and individual offset correction registers. The offset control for individual channels can be used with DIG\_OFFSET\_WEIGHT<1:0> in 0xA7. The corresponding registers for each correction are shown in Figure 4-22.

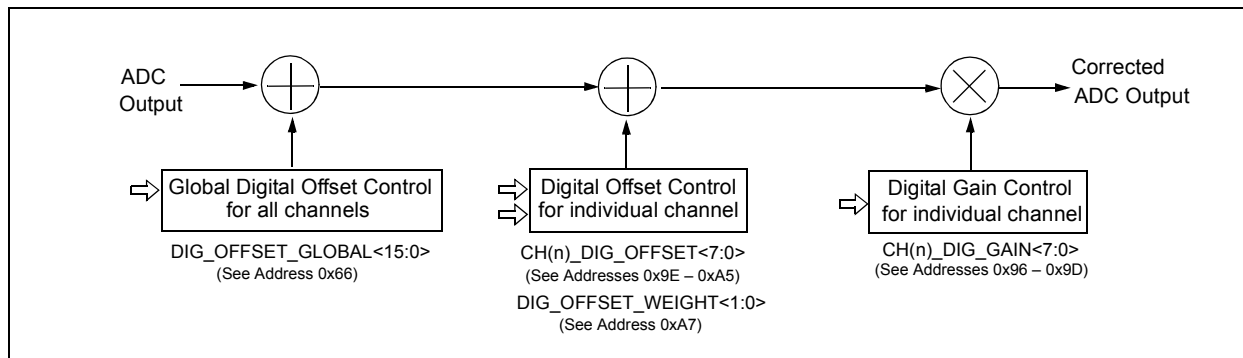
Note that, except for the octal-channel mode, the offset setting registers for individual channels, 0x9E-0xA7 (Registers 5-71 – 5-79), do not sequentially correspond to the channel order defined by CH\_ORDER<23:0>. Table 4-21 shows the details of the offset registers that correspond to the actual channels, depending on the number of channels used.

### 4.9.2 DIGITAL GAIN SETTINGS

CH(N)\_DIG\_GAIN<7:0> in Addresses 0x96 – 0x9D (Registers 5-63 – 5-70) is used to adjust the digital gain per channel.

**Note 1:** Digital Offset Setting: Register mapping (0x9E – 0xA7) to the corresponding channel is not sequential to the channel order defined by CH\_ORDER<23:0>, except for the octal-channel mode. See Table 4-21 for details.

**2:** Gain and NCO Phase Offset: Register mapping to the corresponding channel is sequential to the channel order defined by CH\_ORDER<23:0>.



**FIGURE 4-22:** Simplified Block Diagram for Digital Offset and Gain Settings.

**TABLE 4-21: REGISTER ASSIGNMENT FOR OFFSET SETTING**

Number of Channel Used	Register Address for Offset Setting							
	1 <sup>st</sup> Channel	2 <sup>nd</sup> Channel	3 <sup>rd</sup> Channel	4 <sup>th</sup> Channel	5 <sup>th</sup> Channel	6 <sup>th</sup> Channel	7 <sup>th</sup> Channel	8 <sup>th</sup> Channel
1	0x9F	—	—	—	—	—	—	—
2	0xA0	0x9F	—	—	—	—	—	—
3	0xA1	0x9F	0xA0	—	—	—	—	—
4	0xA2	0x9F	0xA0	0xA1	—	—	—	—
5	0xA3	0x9F	0xA0	0xA1	0xA2	—	—	—
6	0xA4	0x9F	0xA0	0xA1	0xA2	0xA3	—	—
7	0xA5	0x9F	0xA0	0xA1	0xA2	0xA3	0xA4	—
8	0x9E	0x9F	0xA0	0xA1	0xA2	0xA3	0xA4	0xA5



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## 4.10 Continuous Wave (CW) Beamforming and Ultrasound Doppler Signal Processing Using CW Octal-Channel Mode (MCP37D11-200 only)

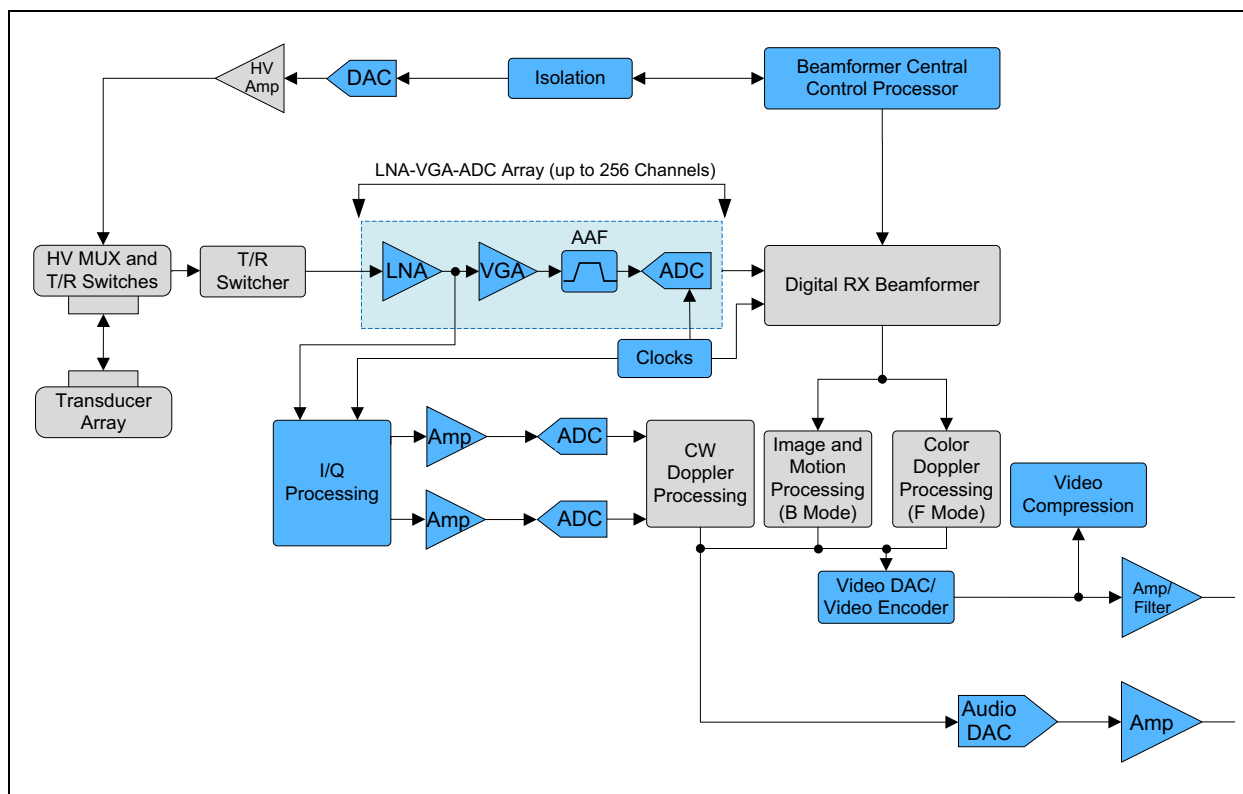
In modern ultrasound medical applications, large numbers of transducers are often used. The signals from these sensors are then coherently combined for higher transducer gain and directivity. The signals from each sensor arrive at the detection device with a different time delay. Also, in multi-channel scanning operations using the MUX, there is a time delay between acquiring input signals (see [Section 4.8.1 “Fractional Delay Recovery for Dual- and Octal-Channel Modes”](#)). These time delays may need to be corrected before all input signals are combined for the signal processing.

Digital beamforming is a digital signal processing technique that requires summing all input signals from different channels after correcting for time delay. The time-delay correction involves the phase alignment of the detected signals with respect to a reference.

Along with beamforming, many modern medical ultrasound devices support Doppler imaging, which processes phase information in addition to the classical magnitude detection (for brightness imaging). Ultrasound Doppler signal processing is used to determine movement in the body as represented by blood flow, which can help diagnose the functioning of a heart valve or blood vessel, etc. In a traditional ultrasound system, all of these functions are typically accomplished with discrete components. [Figure 4-24](#) shows an example of an ultrasound system implementation using various specialized components.

The MCP37D11-200 device has a built-in feature that can perform some of the functions that are done traditionally using extra components. Continuous wave (CW) digital beamforming and Doppler signal processing features are available, but these are offered in octal-channel operation only.

[Figure 4-23](#) shows a simplified block diagram for the ultrasound beamforming with DDC I/Q decimation. Note that the sub-blocks shown after the MUX are commonly used for all input channels.



**FIGURE 4-23:** Example of Ultrasound System Building Block.

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## 4.10.1 BEAMFORMING

Beamforming is achieved by scanning all inputs while correcting the phase of each channel with respect to a reference. This can be done using:

- Fractional Delay Recovery (FDR)
- Phase offset settings of each individual channel
- Gain setting per channel

While the CW input channel is multiplexed sequentially, the phase offset can be added to the NCO output (each channel individually).  $CH(n)_{NCO\_PHASE<15:0>}$ , in Addresses 0x86 to 0x95 ([Registers 5-47](#) – [5-62](#)), corrects the time delay of the incoming signals with respect to the reference.

The phase-compensated input signal is then down-converted by a wide dynamic range I/Q demodulator. The digital beamforming of the inputs is then obtained by summing I and Q data from individual channels. The combined I and Q data are fed to the half-band filter. [Equation 4-10](#) shows the I and Q data of an individual channel with phase correction (phase offset), and the resulting digital beamforming signal.

The processing blocks after the digital beamforming are the same as the sub-blocks used in single-channel operation described in [Section 4.8.4.1 “Single-Channel DDC”](#), except only limited decimation rates of the FIR A and FIR B filters are used due to the processing time requirement for summing the input signals from all channels.

### EQUATION 4-10: BEAMFORMING SIGNALS

$$I_{CH(n)} = ADC \times \cos(2\pi f_{NCO}t + \phi(n))$$

$$Q_{CH(n)} = ADC \times \sin(2\pi f_{NCO}t + \phi(n))$$

$$I = \sum_{n=0}^N I_{CH(n)}$$

$$Q = \sum_{n=0}^N Q_{CH(n)}$$

$$\begin{aligned}\phi(n) &= 360^\circ \times \frac{CH(n)_{NCO\_PHASE<15:0>}}{2^{16}} \\ &= 0.005493164^\circ \times CH(n)_{NCO\_PHASE<15:0>}\end{aligned}$$

Where:

$\phi(n)$  = NCO phase offset of channel  $n$

ADC = the output of the ADC block

The NCO phase offset can be controlled by  $0.005493164^\circ$  per step. See [Section 4.8.4.6 “NCO Phase Offset Control”](#) for details.

## 4.10.2 ULTRASOUND DOPPLER SIGNAL PROCESSING

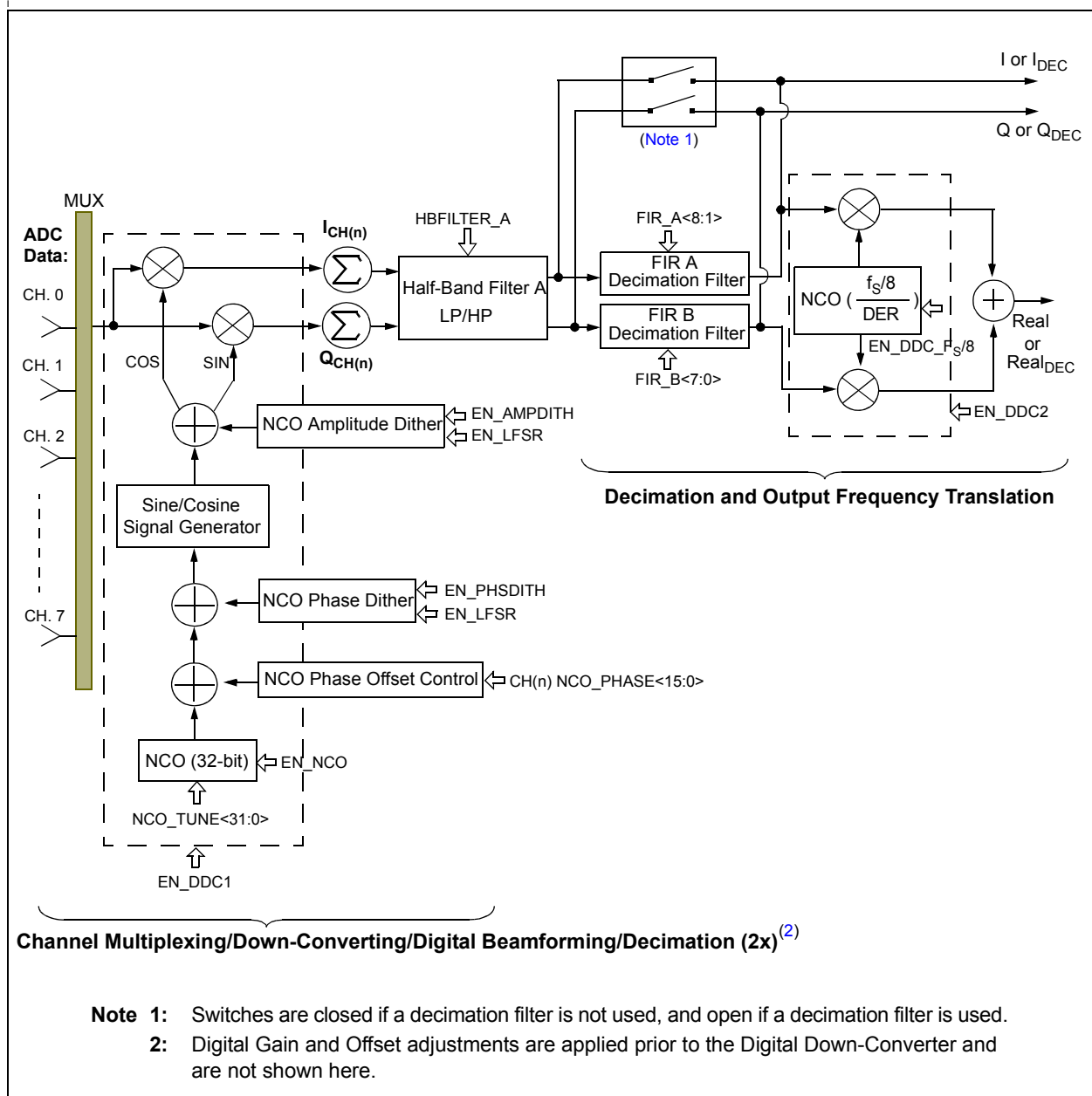
Doppler shift measurement requires summing the input signals from multiple transducer channels and mixing them with a phase-controlled local oscillator frequency. The resulting low-frequency output is then centered near DC and can measure a Doppler shift produced by moving objects, such as blood flow and changes in blood pressure in arteries, etc. In traditional Doppler measurement, many discrete analog components are typically used along with a high-resolution ADC (~18-bit range).

This device has unique built-in features that are suitable for ultrasound Doppler shift measurements. By utilizing these features, system engineers can reduce many discrete components which are otherwise necessary for an ultrasound Doppler measurement system.

The following built-in digital signal post-processing (DSPP) features in the MCP37D11-200 can be effectively used for the ultrasound Doppler signal processing applications:

- **Fractional Delay Recovery (FDR):** Correct the time delay of signal sampled between channels. See details in [Section 4.8.1 “Fractional Delay Recovery for Dual- and Octal-Channel Modes”](#).
- **Digital Gain and Offset adjustment for each channel:** See details in [Section 4.9 “Digital Offset and Digital Gain Settings”](#).
- **Down-Conversion for each channel** with a unique phase of the same NCO frequency prior to summing the eight channels as shown in [Figure 4-24](#).
- After down-conversion by the DDC, the resulting signal can then be decimated to achieve very high SNR in a narrow bandwidth.

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**FIGURE 4-24:** Simplified Block Diagram of CW Beamforming and I/Q Signal Processing - Available in MCP37D11-200 Only.

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## 4.11 Output Data format

The device can output the ADC data in offset binary or two's complement. The data format is selected by the DATA\_FORMAT bit in Address 0x62 ([Register 5-20](#)).

[Table 4-22](#) shows the relationship between the analog input voltage, the digital data output bits and the overrange bit. By default, the output data format is two's complement.

**TABLE 4-22: ADC OUTPUT CODE VS. INPUT VOLTAGE (12-BIT MODE)**

Input Range	Offset Binary <sup>(1)</sup>	Two's Complement <sup>(1)</sup>	Overrange (OVR)
$A_{IN} > A_{FS}$	1111-1111-1111	0111-1111-1111	1
$A_{IN} = A_{FS}$	1111-1111-1111	0111-1111-1111	0
$A_{IN} = A_{FS} - 1 \text{ LSb}$	1111-1111-1110	0111-1111-1110	0
$A_{IN} = A_{FS} - 2 \text{ LSb}$	1111-1111-1100	0111-1111-1100	0
⋮			
$A_{IN} = A_{FS}/2$	1100-0000-0000	0100-0000-0000	0
$A_{IN} = 0$	1000-0000-0000	0000-0000-0000	0
$A_{IN} = -A_{FS}/2$	0011-1111-1111	1011-1111-1111	0
⋮			
$A_{IN} = -A_{FS} + 2 \text{ LSb}$	0000-0000-0010	1000-0000-0010	0
$A_{IN} = -A_{FS} + 1 \text{ LSb}$	0000-0000-0001	1000-0000-0001	0
$A_{IN} = -A_{FS}$	0000-0000-0000	1000-0000-0000	0
$A_{IN} < -A_{FS}$	0000-0000-0000	1000-0000-0000	1

**Note 1:** MSb is sign bit

## 4.12 Digital Output

The device can operate in one of the following two digital output modes:

- Full-Rate CMOS
- Double-Data-Rate (DDR) LVDS

The outputs are powered by  $DV_{DD18}$  and GND. LVDS mode is recommended for data rates above 80 Msps. The digital output mode is selected by the OUTPUT\_MODE<1:0> bits in Address 0x62 ([Register 5-20](#)). [Figures 2-1](#) – [2-2](#) show the timing diagrams of the digital output.

### 4.12.1 FULL RATE CMOS MODE

In full-rate CMOS mode, the data outputs (Q11 to Q0, overrange indicator (OVR), word clock (WCK) and the data output clock (DCLK+, DCLK-) have CMOS output levels. The digital output should drive minimal capacitive loads. If the load capacitance is larger than 10 pF, a digital buffer should be used.

### 4.12.2 DOUBLE DATA RATE LVDS MODE

In double-data-rate LVDS mode, the output is a parallel data stream which changes on each edge of the output clock. See [Figure 2-2](#) for details.

In multi-channel configuration, the data is output sequentially with the WCK that is synchronized to the first sampled channel.

The device outputs the following LVDS output pairs:

- Output Data: Q5+/Q5- through Q0+/Q0-
- OVR/WCK
- DCLK+/DCLK-

A 100Ω differential termination resistor is required for each LVDS output pin pair. The termination resistor should be located as close as possible to the LVDS receiver. By default, the outputs are standard LVDS levels: 3.5 mA output current with a 1.15V output common-mode voltage on a 100Ω differential load. See Address 0x63 ([Register 5-21](#)) for more details of the LVDS mode control.

**Note:** **Output Data Rate in LVDS Mode:** In octal-channel mode, the input sample rate per channel is  $f_S/8$ . Therefore, the output data rate required to shift out all 12 bits in DDR is still equivalent to  $f_S$ . For example, if  $f_S = 200 \text{ Msps}$ , each channel's sample rate is  $f_S/8 = 25 \text{ Msps}$ , and the output clock rate (DCLK) for 12-bit DDR output is 200 MHz.

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## 4.12.3 OVERRANGE BIT (OVR)

The input overrange status bit is asserted (logic high) when the analog input has exceeded the full-scale range of the ADC in either the positive or negative direction. In LVDS DDR Output mode, the OVR bit is multiplexed with the word clock (WCK) output bit such that OVR is output on the falling edge of the data output clock and WCK on the rising edge.

The OVR bit has the same pipeline latency as the ADC data bits. In multi-channel mode, the OVR is output independently for each input channel and is synchronized to the data. See Address 0x68 (Register 5-26) for OVR and WCK control options.

If DSPP options are enabled, OVR pipeline latency will be unaffected; however, the data will incur additional delay. This has the effect of allowing the OVR indicator to precede the affected data.

## 4.12.4 WORD CLOCK (WCK)

The word clock output bit indicates the start of a new data set. In single-channel mode, this bit is disabled except for I/Q output mode. In DDR output with multi-channel mode, it is always asserted coincidentally with the data from the first sampled channel, and multiplexed with the OVR bit. See Address 0x07 (Register 5-5) and Address 0x68 (Register 5-26) for OVR and WCK control options.

## 4.12.5 LVDS OUTPUT POLARITY CONTROL

In LVDS mode, the output polarity can be controlled independently for each LVDS pair. Table 4-23 summarizes the LVDS output polarity control register bits.

**TABLE 4-23: LVDS OUTPUT POLARITY CONTROL**

Control Parameter	Register	Descriptions
POL_LVDS<7:0>	0x65	Control polarity of LVDS data pairs
POL_WCK_OVR	0x68	Control polarity of WCK and OVR bit pair

## 4.12.6 PROGRAMMABLE LVDS OUTPUT

In LVDS mode, the default output driver current is 3.5 mA. This current can be adjusted by using the LVDS\_IMODE<2:0> bit setting in Address 0x63 (Register 5-21). Available output drive currents are 1.8 mA, 3.5 mA, 5.4 mA and 7.2 mA.

## 4.12.7 OPTIONAL LVDS DRIVER INTERNAL TERMINATION

In most cases, using an external 100Ω termination resistor will give excellent LVDS signal integrity. In addition, an optional internal 100Ω termination resistor can be enabled by setting the LVDS\_LOAD bit in

Address 0x63 (Register 5-21). The internal termination helps absorb any reflections caused by imperfect impedance termination at the receiver.

## 4.12.8 OUTPUT DATA AND CLOCK RATES

The user can reduce output data and output clock rates using Address 0x02 (Register 5-3). When decimation or digital down-conversion (DDC) is used, the output data rate has to be reduced to synchronize with the reduced output clock rate.

## 4.12.9 PHASE SHIFTING OF OUTPUT CLOCK (DCLK)

In full-rate CMOS mode, the data output bit transition occurs at the rising edge of DCLK+, so the falling edge of DCLK+ can be used to latch the output data.

In double-data-rate LVDS mode, the data transition occurs at both the rising and falling edges of DCLK+. For adequate setup and hold time when latching the data into the external host device, the user can shift the phase of the digital clock output (DCLK+/DCLK-) relative to the data output bits.

The output phase shift (delay) is controlled by each unique register depending on which timing source is used or if decimation is used. Table 4-24 shows the output clock phase control registers for each Configuration mode: (a) when DLL is used, (b) when decimation is used, and (c) when PLL is used.

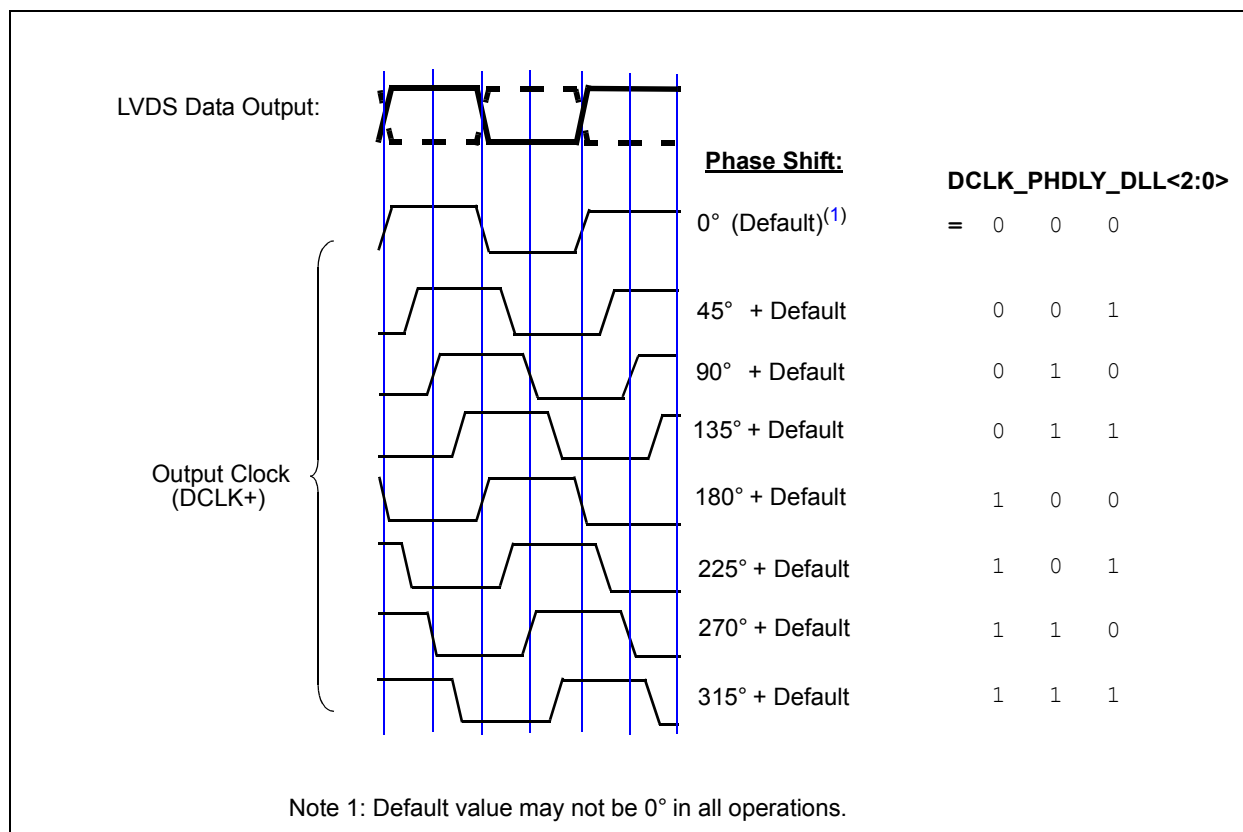
Figure 4-25 shows an example of the output clock phase delay control using the DCLK\_PHDLY\_DLL<2:0> when DLL is used.

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**TABLE 4-24: OUTPUT CLOCK (DCLK) PHASE CONTROL PARAMETERS**

Control Parameter	Register	Operating Condition <sup>(1)</sup>
When DLL is used:		
EN_PHDLY	0x64	EN_PHDLY = 1: Enable output clock phase delay control
DCLK_PHDLY_DLL<2:0>	0x52	DCLK phase delay control when DLL is used. Decimation is not used.
When decimation is used:		
EN_PHDLY	0x64	EN_PHDLY = 1: Enable output clock phase delay control
DCLK_PHDLY_DEC<2:0>		DCLK phase delay control when decimation filter is used. The phase delay is controlled in digital clock output control block.
When PLL is used:		
DCLK_DLY_PLL<2:0>	0x6D	DCLK delay control when PLL is used.

**Note 1:** See [Figure 4-11](#) for details.



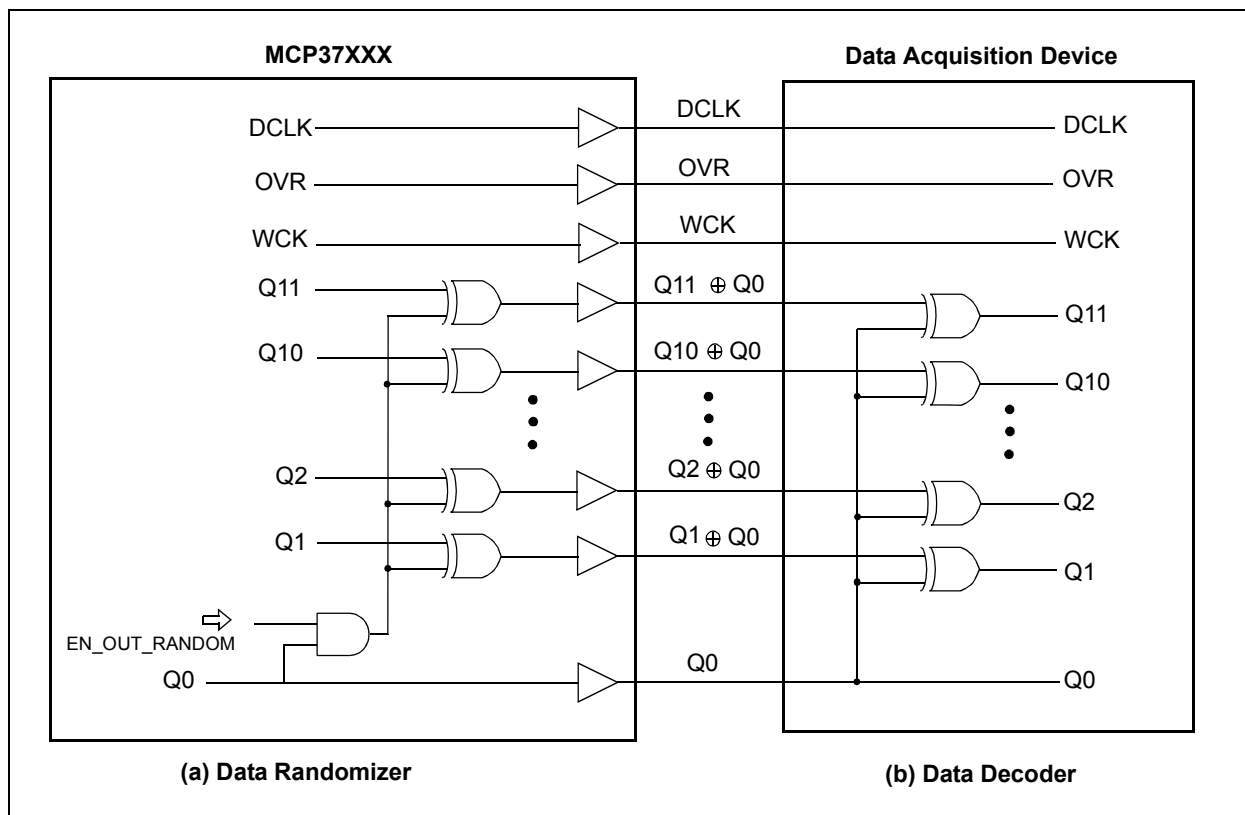
**FIGURE 4-25:** Example of Phase Shifting of Digital Output Clock (DCLK+) when DLL is Used.

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## 4.12.10 DIGITAL OUTPUT RANDOMIZER

Depending on PCB layout considerations and power supply coupling, SFDR may be improved by decorrelating the ADC input from the ADC digital output data. The device includes an output data randomizer option. When this option is enabled, the digital output is randomized by applying an exclusive-OR logic operation between the LSb (D0) and all other data output bits.

To decode the randomized data, the reverse operation is applied: an exclusive-OR operation is applied between the LSb (D0) and all other bits. The DCLK, OVR, WCK and LSb (D0) outputs are not affected. Figure 4-26 shows the block diagram of the data randomizer and decoder logic. The output randomizer is enabled by setting the EN\_OUT\_RANDOM bit in Address 0x07 (Register 5-5).



**FIGURE 4-26:** Logic Diagram for Digital Output Randomizer and Decoder.

## 4.12.11 OUTPUT DISABLE

The digital output can be disabled by setting OUTPUT\_MODE<1:0> = 00 in Address 0x62 (Register 5-20). All digital outputs are disabled, including OVR, WCK, DCLK, etc.

## 4.12.12 OUTPUT TEST PATTERNS

To facilitate testing of the I/O interface, the device can produce various predefined or user-defined patterns on the digital outputs. See TEST\_PATTERNS<2:0> in Address 0x62 (Register 5-20) for the predefined test patterns. For the user-defined patterns, Addresses 0x74 – 0x77 (Registers 5-29 – 5-32) can be programmed using the SPI interface. When an output test mode is enabled, the ADC's analog section can still be operational, but does not drive the digital outputs. The outputs are driven only with the selected test pattern.



# MCP37211-200 AND MCP37D11-200

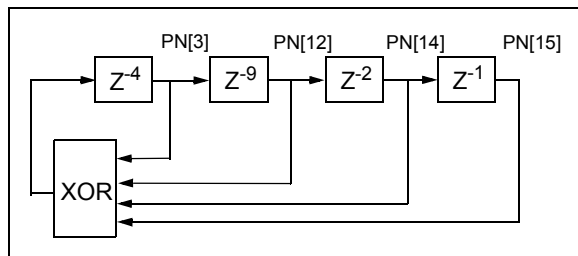
## 4.12.12.1 Pseudo-Random Number (PN) Sequence Output

When TEST\_PATTERNS<2:0> = 111, the device outputs a pseudo-random number (PN) sequence which is defined by the polynomial of degree 16, as shown in Equation 4-11. Figure 4-27 shows the block diagram of a 16-bit Linear Feedback Shift Register (LFSR) for the PN sequence.

### EQUATION 4-11: POLYNOMIAL FOR PN

$$P(x) = 1 + x^4 + x^{13} + x^{15} + x^{16}$$

The output PN[15:4] is directly applied to the output pins Qn[11:0]. In addition to the output at the Qn[11:0] pins, the two MSBs, PN[15] and PN[14], are copied to the OVR and WCK pins, respectively.



**FIGURE 4-27:** Block Diagram of 16-Bit LFSR for Pseudo-Random Number (PN) Sequence for Output Test Pattern.

## 4.13 System Calibration

The built-in system calibration algorithm includes:

- Harmonic Distortion Correction (HDC)
- DAC Noise Cancellation (DNC)
- Dynamic Element Matching (DEM)

HDC and DNC correct the nonlinearity in the residue amplifier and DAC, respectively. The system calibration is performed by:

- Power-up calibration, which takes place during the Power-on Reset sequence (requires  $2^{27}$  clock cycles)
- Background calibration, which takes place during normal operation (per  $2^{30}$  clock cycles).

Background calibration time is invisible to the user, and primarily affects the ADC's ability to track variations in ambient temperature.

The calibration status is monitored by the CAL pin or the ADC\_CAL\_STAT bit in Address 0xC0 ([Register 5-80](#)). See Address 0x07 ([Register 5-5](#)) and 0x1E ([Register 5-6](#)) for time delay control of the auto-calibration. [Table 4-25](#) shows the calibration time for various ADC core sample rates.

**TABLE 4-25: CALIBRATION TIME VS. ADC CORE SAMPLE RATE**

$f_s$ (Msps)	200	150	100	70	50
Power-Up Calibration Time (s)	0.67	0.9	1.34	1.92	2.68
Background Calibration Time (s)	5.37	7.16	10.73	15.34	21.48

### 4.13.1 RESET COMMAND

Although the background calibration will track changes in temperature or supply voltage, changes in clock frequency or register configuration should be followed by a recalibration of the ADC. This can be accomplished via either the Hard or Soft Reset command. The recalibration time is the same as the power-up calibration time ( $2^{27}$  clock cycles). Resetting the device is highly recommended when exiting from Shutdown or Standby mode after an extended amount of time. During the reset, the device has the following state:

- No ADC output
- No change in power-on condition of internal reference
- Most of the internal clocks are not distributed
- Contents of internal user registers:
  - Not affected by Soft Reset
  - Reset to default values by Hardware Reset
- Current consumption of the digital section is negligible, but no change in the analog section.



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## 4.13.1.1 Hardware Reset

A hard reset is triggered by toggling the  $\overline{\text{RESET}}$  pin. On the rising edge, all internal calibration registers and user registers are initialized to their default states and recalibration of the ADC begins. The recalibration time is the same as the power-up calibration time. See [Figure 2-6](#) for the timing details of the hardware  $\overline{\text{RESET}}$  pin.

## 4.13.1.2 Soft Reset

The user can issue a Soft Reset command for a fast recalibration of the ADC by setting the  $\overline{\text{SOFT\_RESET}}$  bit to '0' in Address 0x00 ([Register 5-1](#)). During Soft Reset, all internal calibration registers are initialized to their initial default states. User registers are unaffected. When exiting the Soft Reset (changing from '0' to '1'), an automatic device calibration takes place.

## 4.14 Power Dissipation and Power Savings

The power dissipation of the ADC core is proportional to the sample rate ( $f_s$ ). The digital power dissipation of the CMOS outputs are determined primarily by the strength of the digital drivers and the load condition on each output pin. The maximum digital load current ( $I_{\text{LOAD}}$ ) can be calculated as:

### EQUATION 4-12: CMOS OUTPUT LOAD CURRENT

$$I_{\text{LOAD}} = DV_{\text{DD1.8}} \times f_{\text{DCLK}} \times N \times C_{\text{LOAD}}$$

Where:

N = Number of bits

$C_{\text{LOAD}}$  = Capacitive load of output pin

The capacitive load presented at the output pins needs to be minimized to minimize digital power consumption. The output load current of the LVDS output is constant, since it is set by LVDS\_IMODE<2:0> in Address 0x63 ([Register 5-21](#)).

## 4.14.1 POWER-SAVING MODES

This device has two power-saving modes:

- Shutdown
- Standby

They are set by the SHUTDOWN and STANDBY bits in Address 0x00 ([Register 5-1](#)).

In Shutdown mode, most of the internal circuitry, including the reference and clock, are turned off with the exception of the SPI interface. During Shutdown, the device consumes 23 mA (typical), primarily due to digital leakage. When exiting from Shutdown, issuing a Soft Reset at the same time is highly recommended.

This will perform a fast recalibration of the ADC. The contents of the internal registers are not affected by the Soft Reset.

In Standby mode, most of the internal circuitry is disabled except for the reference, clock and SPI interface. If the device has been in standby for an extended period of time, the current calibration value may not be accurate. Therefore, when exiting from Standby mode, executing the device Soft Reset at the same time is highly recommended.

## 4.15 AutoSync Mode: Synchronizing Multiple ADCs at the Same Clock using Master and Slave Configuration

AutoSync allows multiple devices to sample input synchronously at the same clock, and output the conversion data at the same times if they are using the same digital signal post-processing. [Figure 4-28](#) shows the system configuration using the AutoSync feature. Three examples with timing diagram are shown in [Figure 2-7](#) – [Figure 2-9](#).

Once the devices are synchronized, each device performs internal calibration ( $T_{\text{PCAL}}$ ) before sending out valid data output. Any ADC data output before the calibration is complete should be ignored.

Note that the calibration time varies slightly from device to device, and the internal calibration status can be monitored using the CAL pin or ADC\_CAL\_STAT bit in the Register Address 0xC0.

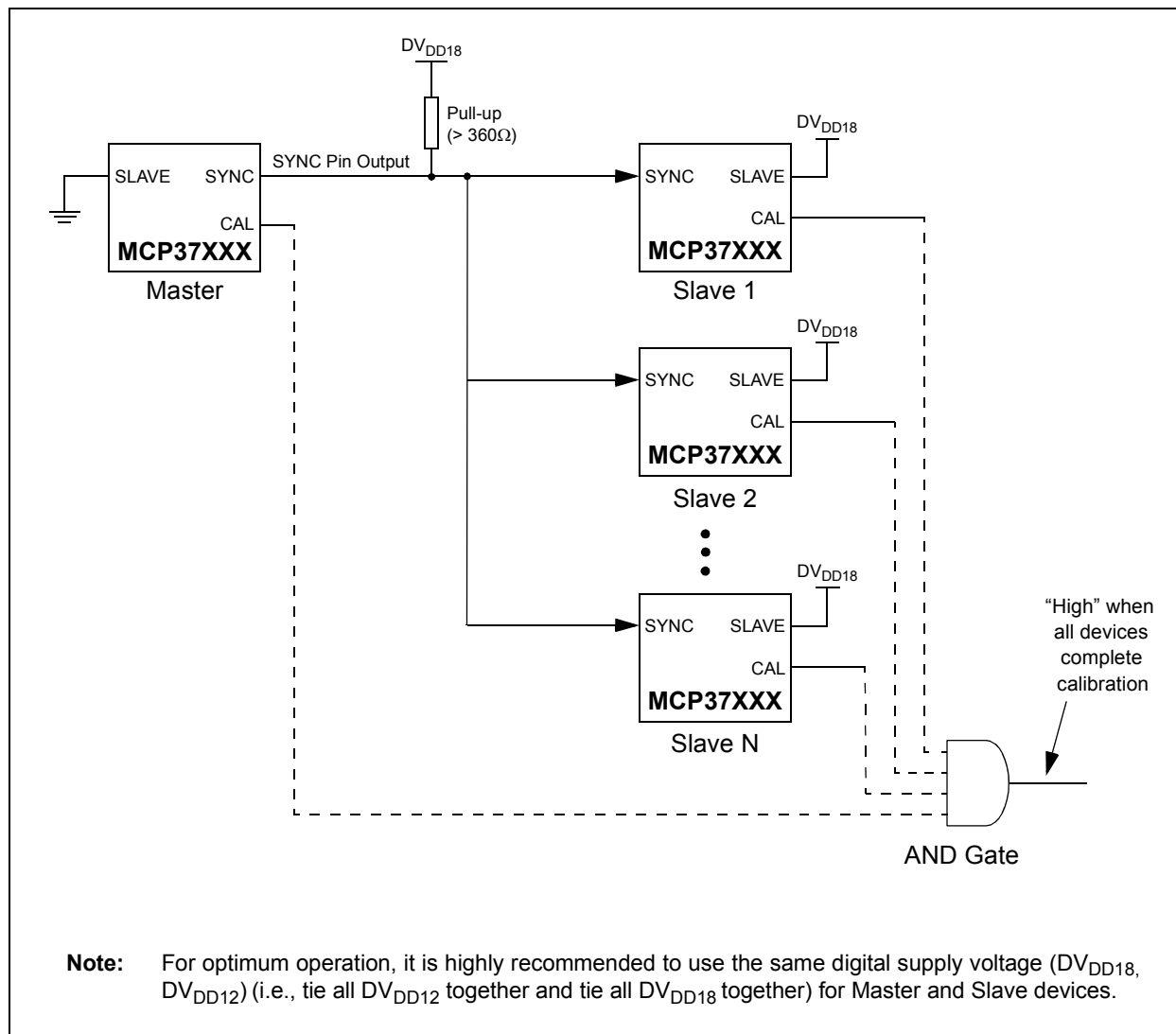
The valid synchronized output is available when all devices complete their own internal calibration. For this reason, the user has two options for the synchronized output: (a) monitor the calibration status of individual devices and wait until all devices complete calibrations or (b) use an external AND gate as shown in [Figure 4-27](#). Master and all Slave devices are synchronized when the AND gate output toggles to "High".

The AutoSync feature can be used with the following steps:

- Master device is selected by setting SLAVE pin to "GND": SYNC pin becomes output pin.
- Slave device is selected by setting SLAVE pin to "High" (or tie to DVDD18): SYNC pin becomes input pin.
- Feed the Master's SYNC pin output to Slave's SYNC pin.
- Use AutoSync mode using (a) Power-On Reset ([Figure 2-7](#)), (b)  $\overline{\text{RESET}}$  Pin ([Figure 2-8](#)), or (c)  $\overline{\text{SOFT\_RESET}}$  bit ([Figure 2-9](#)).

**Note:** The maximum sample rate may be affected by the PCB layout due to the parasitic capacitances between the Master and Slave devices.

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**FIGURE 4-28:** Synchronizing Multiple ADCs Using AutoSync Feature.

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NOTES:

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## 5.0 SERIAL PERIPHERAL INTERFACE (SPI)

The user can configure the ADC for specific functions or optimized performance by setting the device's internal registers through the serial peripheral interface (SPI). The SPI communication uses three pins:  $\overline{\text{CS}}$ , SCLK and SDIO. [Table 5-1](#) summarizes the SPI pin functions. The SCLK is used as a serial timing clock and can be used up to 50 MHz. SDIO (Serial Data Input/Output) is a dual-purpose pin that allows data to be sent or read from the internal registers. The Chip Select pin ( $\overline{\text{CS}}$ ) enables SPI communication when active-low. The falling edge of  $\overline{\text{CS}}$  followed by a rising edge of SCLK determines the start of the SPI communication. When  $\overline{\text{CS}}$  is tied to high, SPI communication is disabled and the SPI pins are placed in high-impedance mode. The internal registers are accessible by their address.

[Figures 5-1](#) and [5-2](#) show the SPI data communication protocols for this device with MSb-first and LSb-first options, respectively. It consists of:

- 16-bit wide instruction header + Data byte 1 + Data byte 2 + . . . + Data Byte N

[Table 5-2](#) summarizes the bit functions. The  $\text{R}/\overline{\text{W}}$  bit of the instruction header indicates whether the command is a read ('1') or a write ('0'):

- If the  $\text{R}/\overline{\text{W}}$  bit is '1', the SDIO pin changes direction from an input (SDI) to an output (SDO) after the 16-bit wide instruction header.

By selecting the  $\text{R}/\overline{\text{W}}$  bit, the user can write the register or read back the register contents. The W1 and W2 bits in the instruction header indicate the number of data bytes to transmit or receive in the following data frame.

Bits A2 – A0 are the SPI device address bits. These bits are used when multiple devices are used in the same SPI bus. A2 is internally hardcoded to '0'. Bits A1 and A0 correspond to the logic level of the ADR1 and ADR0 pins, respectively.

**Note:** In the VTLA-124 package, ADR1 is internally bonded to ground (logic '0').

The R9 – R0 bits represent the starting address of the Configuration register to write or read. The data bytes following the instruction header are the register data. All register data is eight bits wide. Data can be sent in MSb-first mode (default) or in LSb-first mode, which is determined by the  $\text{LSb\_FIRST}$  bit setting in Address 0x00 ([Register 5-1](#)). In Write mode, the data is clocked in at the rising edge of the SCLK. In the Read mode, the data is clocked out at the falling edge of the SCLK.

**TABLE 5-1: SPI PIN FUNCTIONS**

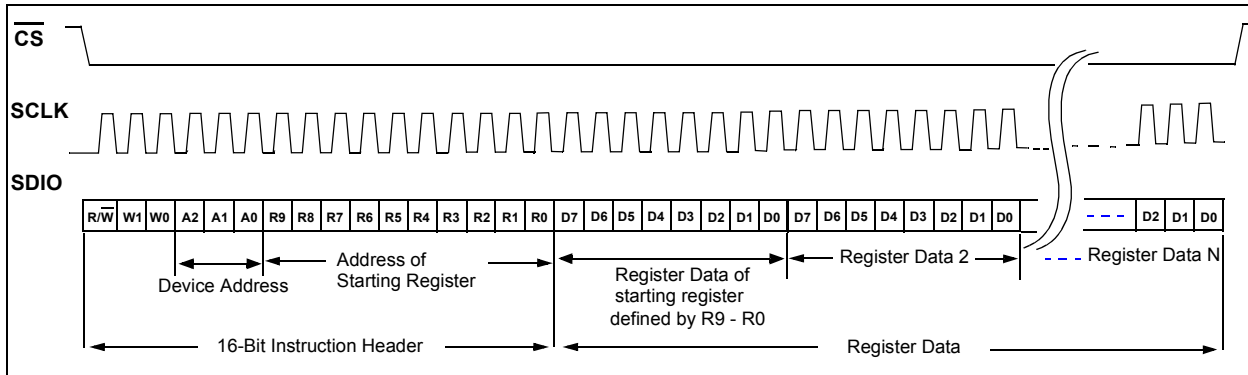
Pin Name	Descriptions
$\overline{\text{CS}}$	Chip Select pin. SPI mode is initiated at the falling edge. It needs to maintain active-low for the entire period of the SPI communication. The device exits the SPI communication at the rising edge.
SCLK	Serial clock input pin. <ul style="list-style-type: none"><li>• Writing to the device: Data is latched at the rising edge of SCLK</li><li>• Reading from the device: Data is latched at the falling edge of SCLK</li></ul>
SDIO	Serial data input/output pin. This pin is initially an input pin (SDI) during the first 16-bit instruction header. After the instruction header, its I/O status can be changed depending on the $\text{R}/\overline{\text{W}}$ bit: <ul style="list-style-type: none"><li>• if <math>\text{R}/\overline{\text{W}} = 0</math>: Data input pin (SDI) for writing</li><li>• if <math>\text{R}/\overline{\text{W}} = 1</math>: Data output pin (SDO) for reading</li></ul>

**TABLE 5-2: SPI DATA PROTOCOL BIT FUNCTIONS**

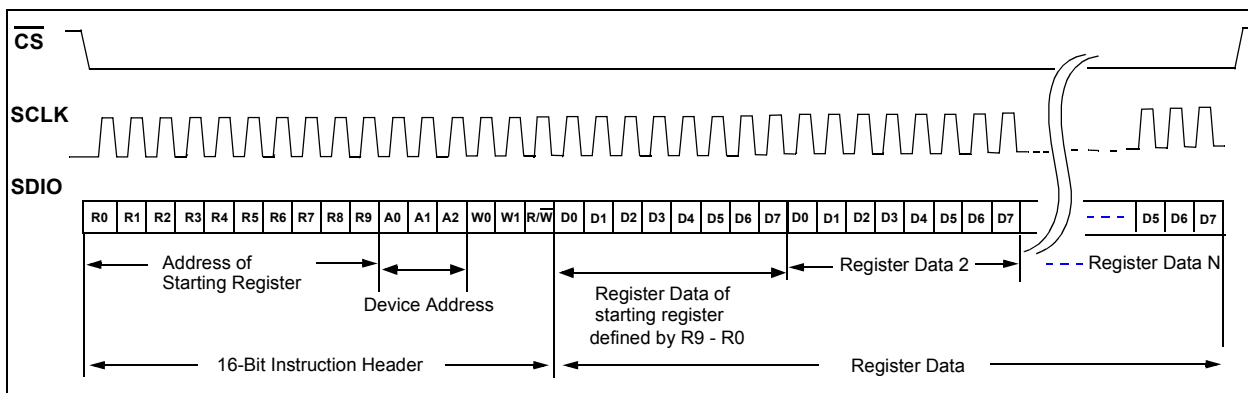
Bit Name	Descriptions
$\text{R}/\overline{\text{W}}$	1 = Read Mode 0 = Write Mode
W1, W0 (Data Length)	00 = Data for one register (1 byte) 01 = Data for two registers (2 bytes) 10 = Data for three registers (3 bytes) 11 = Continuous reading or writing by clocking SCLK <sup>(1)</sup>
A2 - A0	Device SPI Address for multiple devices in SPI bus A2: Internally hardcoded to '0' A1: Logic level of ADR1 pin A0: Logic level of ADR0 pin
R9 - R0	Address of starting register
D7 - D0	Register data. MSb or LSb first, depending on the $\text{LSb\_FIRST}$ bit setting in 0x00

**Note 1:** The register address counter is incremented by one per step. The counter does not automatically reset to 0x00 after reaching the last address (0x15D). Be aware that the user registers are not sequentially allocated.

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**FIGURE 5-1:** SPI Serial Data Communication Protocol with MSb-first. See [Figures 2-3](#) and [2-4](#) for Timing Specifications.



**FIGURE 5-2:** SPI Serial Data Communication Protocol - with LSb-First. See [Figures 2-3](#) and [2-4](#) for Timing Specifications.

## 5.1 Register Initialization

The internal Configuration registers are initialized to their default values under two different conditions:

- After  $2^{20}$  clock cycles of delay from the Power-on Reset (POR).
- Resetting the hardware reset pin ( $\overline{\text{RESET}}$ ).

[Figures 2-3](#) and [2-4](#) show the timing details.

- Note 1:** All address and bit locations that are not included in the following register map table should not be written or modified by the user.
- 2:** Some registers include factory-controlled bits (FCB). Do not overwrite these bits.

## 5.2 Configuration Registers

The internal registers are mapped from Addresses 0x00 – 0x15D. These user registers are not sequentially located. Some user Configuration registers include factory-controlled bits. The factory-controlled bits should not be overwritten by the user.

All user Configuration registers are read/write, except for the last four registers, which are read-only. Each register is made of an 8-bit-wide volatile memory, and their default values are loaded during the power-up sequence or by using the hardware  $\overline{\text{RESET}}$  pin. All registers are accessible by the SPI command using the register address. [Table 5-3](#) shows the user-register memory map, and [Registers 5-1](#) – [5-83](#) show the details of the register bit functions.

**TABLE 5-3: REGISTER MAP TABLE**

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x00	SPI Bit Ordering and ADC Mode Selection	SHUTDOWN 1 = Shutdown	LSb-FIRST 1 = Lsb first 0 = MSb first	SOFT_RESET 0 = Soft Reset	STANDBY 1 = Standby	STANDBY 1 = Standby	SOFT_RESET 0=Soft Reset	LSb-FIRST 1 = Lsb first 0 = MSb first	SHUTDOWN 1 = Shutdown	0x24
0x01	No. of Channel Selection and Independency Control of Output Data and Clock Divider	EN_DATCLK_IND	FCB<3> = 0	SEL_NCH<2:0>			FCB<2:0> = 111			0x0F
0x02	Output Data and Clock Rate Control	OUT_DATARATE<3:0>				OUT_CLKRATE<3:0>				0x00
0x04	SPI SDO Timing Control	SDO_TIME	FCB<6:0> = 0011111							0x9F
0x07	Output Randomizer and WCK Polarity Control	POL_WCK	EN_AUTOCAL_TIMEDLY	FCB<4:0> = 10001					EN_OUT_RANDOM	0x62
0x1E	Auto-Calibration Time Delay Control	AUTOCAL_TIMEDLY<7:0>								0x80
0x52	DLL Control	EN_DUTY	DCLK_PHDLY_DLL<2:0>			EN_DLL_DCLK	EN_DLL	EN_CLK	RESET_DLL	0x0A
0x53	Clock Source Selection	FCB<6:4>= 010			CLK_SOURCE	FCB<3:0>= 0101				0x45
0x54	PLL Reference Divider	PLL_REFDIV<7:0>								0x00
0x55	PLL Output and Reference Divider	PLL_OUTDIV<3:0>				FCB<1:0> = 10		PLL_REFDIV<9:8>		0x48
0x56	PLL Prescaler (LSb)	PLL_PRE (LSB)<7:0>								0x78
0x57	PLL Prescaler (MSb)	FCB<3:0> = 0100				PLL_PRE (MSB)<11:8>				0x40
0x58	PLL Charge Pump	FCB<2:0> = 000			PLL_BIAS	PLL_CHAGPUMP<3:0>				0x12
0x59	PLL Enable Control 1	U	FCB<4:3> = 10		EN_PLL_REFDIV	FCB<2:1> = 00		EN_PLL	FCB<0> = 1	0x41
0x5A	PLL Loop Filter Resistor	U	FCB<1:0> = 01		PLL_RES<4:0>					0x2F
0x5B	PLL Loop Filter Cap3	U	FCB<1:0> = 01		PLL_CAP3<4:0>					0x27
0x5C	PLL Loop Filter Cap1	U	FCB<1:0> = 01		PLL_CAP1<4:0>					0x27
0x5D	PLL Loop Filter Cap2	U	FCB<1:0> = 01		PLL_CAP2<4:0>					0x27
0x5F	PLL Enable Control 2	FCB<5:2> = 1111				EN_PLL_OUT	EN_PLL_BIAS	FCB<1:0> = 01		0xF1
0x62	Output Data Format and Output Test Pattern	U	FCB<0> = 0	DATA_FORMAT	OUTPUT_MODE<1:0>		TEST_PATTERNS<2:0>			0x10
0x63	LVDS Output Load and Drive Current Control	FCB<3:0> = 0000				LVDS_LOAD	LVDS_IMODE<2:0>			0x01
0x64	Output Clock Phase Control when Decimation Filter is used	EN_PHDLY	DCLK_PHDLY_DEC<2:0>			FCB<3:0> = 0011				0x03
0x65	LVDS Output Polarity Control	POL_LVDS<5:0>						NO EFFECT<1:0>		0x00
0x66	Digital Offset Correction - Lower Byte	DIG_OFFSET_GLOBAL<7:0>								0x00

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled Bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown  
 2: Read-only register. Preprogrammed at the factory for internal use.

TABLE 5-3: REGISTER MAP TABLE (CONTINUED)

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x67	Digital Offset Correction - Upper Byte	DIG_OFFSET_GLOBAL<15:8>								0x00
0x68	WCK and OVR	FCB<5:2> = 0010				POL_WCK_OVR	EN_WCK_OVR	FCB<1:0> = 00		0x24
0x6B	PLL Calibration	FCB<6:2> = 00001					PLL_CAL_TRIG	FCB<1:0> = 00		0x08
0x6D	PLL Output and Output Clock Phase	U<1:0>		EN_PLL_CLK	FCB<1> = 0		DCLK_DLY_PLL<2:0>		FCB<0> = 0	0x00
0x74	User-Defined Output Pattern A - Lower Nibble	PATTERN A<3:0>				Do not use (Leave these bits as '0000')				0x00
0x75	User-Defined Output Pattern A - Upper Byte	PATTERN A<11:4>								0x00
0x76	User-Defined Output Pattern B - Lower Nibble	PATTERN B<3:0>				Do not use (Leave these bits as '0000')				0x00
0x77	User-Defined Output Pattern B - Upper Byte	PATTERN B<11:4>								0x00
0x78	Noise-Shaping Requantizer Channel A Filter	NSR_RESET	NSRA<6:0>							0x00
0x79	Dual-Channel DSPP Control	EN_DSPP_2	NSRB<6:0>							0x00
0x7A	FIRA0 Filter, FDR and NSR Control	FCB<1> = 0	FIR_A<0>	EN_FDR	FCB<0> = 0	EN_NS RB_11	EN_NS RB_12	EN_NS RA_11	EN_NS RA_12	0x00
0x7B	FIR A Filter	FIR_A<8:1>								0x00
0x7C	FIR B Filter	FIR_B<7:0>								0x00
0x7D	Auto-Scan Channel Order - Lower Byte	CH_ORDER<7:0>								0x78
0x7E	Auto-Scan Channel Order - Middle Byte	CH_ORDER<15:8>								0xAC
0x7F	Auto-Scan Channel Order - Upper Byte	CH_ORDER<23:16>								0x8E
0x80	Digital Down-Converter Control 1	HBFILTER_B	HBFILTER_A	EN_NCO	EN_AMPDITH	EN_PHSDITH	EN_LFSR	EN_DDC_FS/8	EN_DDC1	0x00
0x81	Digital Down-Converter Control 2	FDR_BAND	EN_DDC2	GAIN_HBF_DDC	SEL_FDR	EN_DSPP_8	8CH_CW	GAIN_8CH<1:0>		0x00
0x82	Numerically Controlled Oscillator (NCO) Tuning - Lower Byte	NCO_TUNE<7:0>								0x00
0x83	Numerically Controlled Oscillator (NCO) Tuning - Middle Lower Byte	NCO_TUNE<15:8>								0x00
0x84	Numerically Controlled Oscillator (NCO) Tuning - Middle Upper Byte	NCO_TUNE<23:16>								0x00

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled Bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown  
 2: Read-only register. Preprogrammed at the factory for internal use.

**TABLE 5-3: REGISTER MAP TABLE (CONTINUED)**

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x85	Numerically Controlled Oscillator (NCO) Tuning - Upper Byte	NCO_TUNE<31:24>								0x00
0x86	CH0 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH0_NCO_PHASE<7:0>								0x00
0x87	CH0 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH0_NCO_PHASE<15:8>								0x00
0x88	CH1 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH1_NCO_PHASE<7:0>								0x00
0x89	CH1 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH1_NCO_PHASE<15:8>								0x00
0x8A	CH2 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH2_NCO_PHASE<7:0>								0x00
0x8B	CH2 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH2_NCO_PHASE<15:8>								0x00
0x8C	CH3 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH3_NCO_PHASE<7:0>								0x00
0x8D	CH3 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH3_NCO_PHASE<15:8>								0x00
0x8E	CH4 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH4_NCO_PHASE<7:0>								0x00
0x8F	CH4 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH4_NCO_PHASE<15:8>								0x00
0x90	CH5 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH5_NCO_PHASE<7:0>								0x00
0x91	CH5 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH5_NCO_PHASE<15:8>								0x00
0x92	CH6 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH6_NCO_PHASE<7:0>								0x00
0x93	CH6 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH6_NCO_PHASE<15:8>								0x00
0x94	CH7 NCO Phase Offset in CW or DDC Mode - Lower Byte	CH7_NCO_PHASE<7:0>								0x00
0x95	CH7 NCO Phase Offset in CW or DDC Mode - Upper Byte	CH7_NCO_PHASE<15:8>								0x00
0x96	CH0 Digital Gain	CH0_DIG_GAIN<7:0>								0x3C
0x97	CH1 Digital Gain	CH1_DIG_GAIN<7:0>								0x3C
0x98	CH2 Digital Gain	CH2_DIG_GAIN<7:0>								0x3C
0x99	CH3 Digital Gain	CH3_DIG_GAIN<7:0>								0x3C

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled Bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown  
2: Read-only register. Preprogrammed at the factory for internal use.



TABLE 5-3: REGISTER MAP TABLE (CONTINUED)

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x9A	CH4 Digital Gain	CH4_DIG_GAIN<7:0>								0x3C
0x9B	CH5 Digital Gain	CH5_DIG_GAIN<7:0>								0x3C
0x9C	CH6 Digital Gain	CH6_DIG_GAIN<7:0>								0x3C
0x9D	CH7 Digital Gain	CH7_DIG_GAIN<7:0>								0x3C
0x9E	CH0 Digital Offset	CH0_DIG_OFFSET<7:0>								0x00
0x9F	CH1 Digital Offset	CH1_DIG_OFFSET<7:0>								0x00
0xA0	CH2 Digital Offset	CH2_DIG_OFFSET<7:0>								0x00
0xA1	CH3 Digital Offset	CH3_DIG_OFFSET<7:0>								0x00
0xA2	CH4 Digital Offset	CH4_DIG_OFFSET<7:0>								0x00
0xA3	CH5 Digital Offset	CH5_DIG_OFFSET<7:0>								0x00
0xA4	CH6 Digital Offset	CH6_DIG_OFFSET<7:0>								0x00
0xA5	CH7 Digital Offset	CH7_DIG_OFFSET<7:0>								0x00
0xA7	Digital Offset Weight Control	FCB<5:3> = 010			DIG_OFFSET_WEIGHT<1:0>		FCB<2:0> = 111			0x47
0xC0	Calibration Status Indication (Read only)	ADC_CAL_STAT	FCB<6:0> = 000-0000							—
0xD1	PLL Calibration Status and PLL Drift Status Indication (Read only)	FCB<4:3> = xx		PLL_CAL_STAT	FCB<2:1> = xx		PLL_VCOL_STAT	PLL_VCOH_STAT	FCB<0> = x	—
0x15C	CHIP ID - Lower Byte <sup>(2)</sup> (Read only)	CHIP_ID<7:0>								—
0x15D	CHIP ID - Upper Byte <sup>(2)</sup> (Read only)	CHIP_ID<15:8>								—

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled Bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown

2: Read-only register. Preprogrammed at the factory for internal use.

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## REGISTER 5-1: ADDRESS 0X00 – SPI BIT ORDERING AND ADC MODE SELECTION<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
SHUTDOWN	LSb_FIRST	SOFT_RESET	STANDBY	STANDBY	SOFT_RESET	LSb_FIRST	SHUTDOWN
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 7 **SHUTDOWN:** Shutdown mode setting for power-saving<sup>(2)</sup>

- 1 = ADC in Shutdown mode
- 0 = Not in Shutdown mode **(Default)**

bit 6 **LSb\_FIRST:** Select SPI communication bit order

- 1 = Start SPI communication with LSb first
- 0 = Start SPI communication with MSb first **(Default)**

bit 5 **SOFT\_RESET:** Soft Reset control bit<sup>(3)</sup>

- 1 = Not in Soft Reset mode **(Default)**
- 0 = ADC in Soft Reset

bit 4 **STANDBY:** Send the device into a power-saving Standby mode<sup>(4)</sup>

- 1 = ADC in Standby mode
- 0 = Not in Standby mode **(Default)**

bit 3 **STANDBY:** Send the device into a power-saving Standby mode<sup>(4)</sup>

- 1 = ADC in Standby mode
- 0 = Not in Standby mode **(Default)**

bit 2 **SOFT\_RESET:** Soft Reset control bit<sup>(3)</sup>

- 1 = Not in Soft Reset mode **(Default)**
- 0 = ADC in Soft Reset

bit 1 **LSb\_FIRST:** Select SPI communication bit order

- 1 = Start SPI communication with LSb first
- 0 = Start SPI communication with MSb first **(Default)**

bit 0 **SHUTDOWN:** Shutdown mode setting for power-saving<sup>(2)</sup>

- 1 = ADC in Shutdown mode
- 0 = Not in Shutdown mode **(Default)**

- Note**
- 1: Upper and lower nibble are mirrored, which makes the MSb- or LSb-first mode interchangeable. The lower nibble (bit <3:0>) has a higher priority when the mirrored bits have different values.
  - 2: During Shutdown mode, most of the internal circuits including the reference and clock are turned-off except for the SPI interface. When exiting from Shutdown (changing from '1' to '0'), executing the device Soft Reset simultaneously is highly recommended for a fast recalibration of the ADC. The internal user registers are not affected.
  - 3: This bit forces the device into Soft Reset mode, which initializes the internal calibration registers to their initial default states. The user-registers are not affected. When exiting Soft Reset mode (changing from '0' to '1'), the device performs an automatic device calibration including PLL calibration if PLL is enabled. DLL is reset if enabled. During Soft Reset, the device has the following states:
    - no ADC output
    - no change in power-on condition of internal reference
    - most of the internal clocks are not distributed
    - power consumption: (a) digital section - negligible, (b) analog section - no change
  - 4: During Standby mode, most of the internal circuits are turned off except for the reference, clock and SPI interface. When exiting from Standby mode (changing from '1' to '0') after an extended amount of time, executing Soft Reset simultaneously is highly recommended. The internal user registers are not affected.

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## REGISTER 5-2: ADDRESS 0X01 – NUMBER OF CHANNELS, INDEPENDENCY CONTROL OF OUTPUT DATA AND CLOCK DIVIDER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1
EN_DATCLK_IND	FCB<3>	SEL_NCH<2:0>			FCB<2:0>		
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7      **EN\_DATCLK\_IND:** Enable data and clock divider independently<sup>(1)</sup>  
1 = Enabled  
0 = Disabled **(Default)**
- bit 6      **FCB<3>:** Factory-Controlled Bit. This is not for the user. Do not change default setting.
- bit 5-3    **SEL\_NCH<2:0>:** Select the total number of input channels to be used<sup>(2)</sup>  
111 = 7 inputs  
110 = 6 inputs  
101 = 5 inputs  
100 = 4 inputs  
011 = 3 inputs  
010 = 2 inputs  
001 = 1 input **(Default)**  
000 = 8 inputs
- bit 2-0    **FCB<2:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.
- Note**    1: EN\_DATCLK\_IND = 1 enables OUT\_CLKRATE<3:0> settings in Address 0x02 ([Register 5-3](#)).  
          2: See Addresses 0x7D – 0x7F ([Registers 5-38 – 5-40](#)) for selecting the input channel order.

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## REGISTER 5-3: ADDRESS 0X02 – OUTPUT DATA AND CLOCK RATE CONTROL<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OUT_DATARATE<3:0>				OUT_CLKRATE<3:0>			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4

**OUT\_DATARATE<3:0>**: Output data rate control bits

1111 = Output data is all 0's  
 1110 = Output data is all 0's  
 1101 = Output data is all 0's  
 1100 = Internal test only<sup>(2)</sup>  
 1011 = Internal test only<sup>(2)</sup>  
 1010 = Internal test only<sup>(2)</sup>  
 1001 = Full speed divided by 512  
 1000 = Full speed divided by 256  
 0111 = Full speed divided by 128  
 0110 = Full speed divided by 64  
 0101 = Full speed divided by 32  
 0100 = Full speed divided by 16  
 0011 = Full speed divided by 8  
 0010 = Full speed divided by 4  
 0001 = Full speed divided by 2  
 0000 = Full-speed rate (**Default**)

bit 3-0

**OUT\_CLKRATE<3:0>**: Output clock rate control bits<sup>(3,4)</sup>

1111 = Full-speed rate  
 1110 = No clock output  
 1101 = No clock output  
 1100 = No clock output  
 1011 = No clock output  
 1010 = No clock output  
 1001 = Full speed divided by 512  
 1000 = Full speed divided by 256  
 0111 = Full speed divided by 128  
 0110 = Full speed divided by 64  
 0101 = Full speed divided by 32  
 0100 = Full speed divided by 16  
 0011 = Full speed divided by 8  
 0010 = Full speed divided by 4  
 0001 = Full speed divided by 2  
 0000 = No clock output (**Default**)

- Note**
- 1: This register should be used to realign the output data and clock when the decimation or digital down-conversion (DDC) option is used.
  - 2: 1100 – 1010: Do not reprogram. These settings are used for the internal test only. If these bits are reprogrammed with different settings, the outputs will be in an undefined state.
  - 3: Bits <3:0> become active if EN\_DATCLK\_IND = 1 in Address 0x01 ([Register 5-2](#)).
  - 4: When no clock output is selected (Bits 1110 – 1010): clock output is not available at the DCLK+/DCLK- pins.

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## REGISTER 5-4: ADDRESS 0X04 – SPI SDO OUTPUT TIMING CONTROL

R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
SDO_TIME	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **SDO\_TIME**: SPI SDO output timing control bit  
 1 = SDO output at the falling edge of clock (**Default**)  
 0 = SDO output at the rising edge of clock

bit 6-0 **FCB<6:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

## REGISTER 5-5: ADDRESS 0X07 – OUTPUT RANDOMIZER AND WCK POLARITY CONTROL

R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0
POL_WCK	EN_AUTOCAL_TIMEDLY	FCB<4:0>					EN_OUT_RANDOM
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **POL\_WCK**: WCK polarity control bit<sup>(1)</sup>  
 1 = Inverted  
 0 = Not inverted (**Default**)

bit 6 **EN\_AUTOCAL\_TIMEDLY**: Auto-calibration starter time delay counter control bit<sup>(2)</sup>  
 1 = Enabled (**Default**)  
 0 = Disabled

bit 5-1 **FCB<4:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 0 **EN\_OUT\_RANDOM**: Output randomizer control bit  
 1 = Enabled: ADC data output is randomized  
 0 = Disabled (**Default**)

**Note 1:** See Address 0x68 ([Register 5-26](#)) for WCK/OVR pair control.

**Note 2:** This bit enables the AUTOCAL\_TIMEDLY<7:0> settings. See Address 0x1E ([Register 5-6](#)).

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## REGISTER 5-6: ADDRESS 0X1E – AUTOCAL TIME DELAY CONTROL<sup>(1)</sup>

R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AUTOCAL_TIMEDLY<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **AUTOCAL\_TIMEDLY<7:0>**: Auto-calibration start time delay control bits  
                                  1111-1111 = Maximum value  
                                  ...  
                                  1000-0000 = **(Default)**  
                                  ...  
                                  0000-0000 = Minimum value

**Note 1:** EN\_AUTOCAL\_TIMEDLY in Address 0x07 ([Register 5-5](#)) enables this register setting. This register controls the time delay before the auto-calibration starts. The value increases linearly with the bit settings, from minimum to maximum values.

## REGISTER 5-7: ADDRESS 0X52 – DLL CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1	R/W-0
EN_DUTY	DCLK_PHDLY_DLL<2:0>			EN_DLL_DCLK	EN_DLL	EN_CLK	RESET_DLL
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **EN\_DUTY**: Enable DLL circuit for duty cycle correction (DCC) of input clock  
                                  1 = Correction is ON  
                                  0 = Correction is OFF **(Default)**

bit 6-4                      **DCLK\_PHDLY\_DLL<2:0>**: Select the phase delay of the digital clock output when using DLL<sup>(1)</sup>  
                                  111 = +315° phase-shifted from default  
                                  110 = +270° phase-shifted from default  
                                  101 = +225° phase-shifted from default  
                                  100 = +180° phase-shifted from default  
                                  011 = +135° phase-shifted from default  
                                  010 = +90° phase-shifted from default  
                                  001 = +45° phase-shifted from default  
                                  000 = **(Default)**

bit 3                      **EN\_DLL\_DCLK**: Enable DLL digital clock output  
                                  1 = Enabled **(Default)**  
                                  0 = Disabled: DLL digital clock is turned off. ADC output is not available when DLL is used.

bit 2                      **EN\_DLL**: Enable DLL circuitry to provide a selectable phase clock to digital output clock.  
                                  1 = Enabled  
                                  0 = Disabled. DLL block is disabled **(Default)**

bit 1                      **EN\_CLK**: Enable clock input buffer  
                                  1 = Enabled **(Default)**.  
                                  0 = Disabled. No clock is available to the internal circuits, ADC output is not available.

bit 0                      **RESET\_DLL**: DLL circuit reset control<sup>(2)</sup>  
                                  1 = DLL is active  
                                  0 = DLL circuit is held in reset **(Default)**

**Note 1:** These bits have an effect only if EN\_PHDLY = 1 and decimation is not used.  
**Note 2:** DLL reset control procedure: Set this bit to '0' (reset) and then to '1'.

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## REGISTER 5-8: ADDRESS 0X53 – CLOCK SOURCE SELECTION

R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1
FCB<6:4>			CLK_SOURCE	FCB<3:0>			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **FCB<6:4>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4 **CLK\_SOURCE**: Select internal timing source

1 = PLL output is selected as timing source

0 = External clock input is selected as timing source (**Default**)

bit 3-0 **FCB<3:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

## REGISTER 5-9: ADDRESS 0X54 – PLL REFERENCE DIVIDER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PLL_REFDIV<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **PLL\_REFDIV<7:0>**: PLL Reference clock divider control bits<sup>(1)</sup>

1111-1111 = PLL reference divided by 255 (if PLL\_REFDIV<9:8> = 00)

1111-1110 = PLL reference divided by 254 (if PLL\_REFDIV<9:8> = 00)

...

0000-0011 = PLL reference divided by 3 (if PLL\_REFDIV<9:8> = 00)

0000-0010 = **Do not use (No effect)**

0000-0001 = PLL reference divided by 1 (if PLL\_REFDIV<9:8> = 00)

0000-0000 = PLL reference not divided (if PLL\_REFDIV<9:8> = 00) (**Default**)

**Note 1:** PLL\_REFDIV is a 10-bit wide setting. See Address 0x55 ([Register 5-10](#)) for the upper two bits and [Table 5-4](#) for PLL\_REFDIV<9:0> bit settings. This setting controls the clock division ratio of the PLL reference clock (external clock input at the CLK pin) before the PLL phase-frequency detector circuitry. Note that the divider value of 2 is not supported. EN\_PLL\_REFDIV in Address 0x59 ([Register 5-14](#)) must be set.

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## REGISTER 5-10: ADDRESS 0X55 – PLL OUTPUT AND REFERENCE DIVIDER

R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
PLL_OUTDIV<3:0>				FCB<1:0>		PLL_REFDIV<9:8>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **PLL\_OUTDIV<3:0>**: PLL output divider control bits<sup>(1)</sup>

1111 = PLL output divided by 15

1110 = PLL output divided by 14

...

0100 = PLL output divided by 4 (**Default**)

0011 = PLL output divided by 3

0010 = PLL output divided by 2

0001 = PLL output divided by 1

0000 = PLL output not divided

bit 3-2 **FCB<1:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 1-0 **PLL\_REFDIV<9:8>**: Upper two MSb bits of PLL\_REFDIV<9:0><sup>(2)</sup>

00 = see [Table 5-4](#). (**Default**)

**Note 1:** PLL\_OUTDIV<3:0> controls the PLL output clock divider: VCO output is divided by the PLL\_OUTDIV<3:0> setting.

**Note 2:** See Address 0x54 ([Register 5-9](#)) and [Table 5-4](#) for PLL\_REFDIV<9:0> settings. EN\_PLL\_REFDIV in Address 0x59 ([Register 5-14](#)) must be set.

**TABLE 5-4: EXAMPLE – PLL REFERENCE DIVIDER BIT SETTINGS VS. PLL REFERENCE INPUT FREQUENCY**

PLL_REFDIV<9:0>	PLL Reference Frequency
11-1111-1111	Reference frequency divided by 1023
11-1111-1110	Reference frequency divided by 1022
—	—
00-0000-0011	Reference frequency divided by 3
00-0000-0010	Do not use (not supported)
00-0000-0001	Reference frequency divided by 1
00-0000-0000	Reference frequency divided by 1



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**REGISTER 5-11: ADDRESS 0X56 – PLL PRESCALER (LSB)**

R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
PLL_PRE<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **PLL\_PRE<7:0>**: PLL prescaler selection<sup>(1)</sup>  
                                  1111–1111 = VCO clock divided by 255 (if PLL\_PRE<11:8> = 0000)  
                                  ...  
                                  0111–1000 = VCO clock divided by 120 (if PLL\_PRE<11:8> = 0000) **(Default)**  
                                  ...  
                                  0000–0010 = VCO clock divided by 2 (if PLL\_PRE<11:8> = 0000)  
                                  0000–0001 = VCO clock divided by 1 (if PLL\_PRE<11:8> = 0000)  
                                  0000–0000 = VCO clock not divided (if PLL\_PRE<11:8> = 0000)

**Note 1:** PLL\_PRE is a 12-bit-wide setting. The upper four bits (PLL\_PRE<11:8>) are defined in Address 0x57. See [Table 5-5](#) for the PLL\_PRE<11:0> settings. The PLL Prescaler is used to divide down the VCO output clock in the PLL phase-frequency detector loop circuit.

**REGISTER 5-12: ADDRESS 0X57 – PLL PRESCALER (MSB)**

R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<3:0>				PLL_PRE<11:8>			
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-4                      **FCB<3:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.  
 bit 3-0                      **PLL\_PRE<11:8>**: PLL prescaler selection<sup>(1)</sup>  
                                  1111 =  $2^{12} - 1$  (max), if PLL\_PRE<7:0> = 0xFF  
                                  ...  
                                  0000 = **Default**

**Note 1:** PLL\_PRE is a 12-bit-wide setting. See the lower eight bit settings (PLL\_PRE<7:0>) in Address 0x56 ([Register 5-11](#)). See [Table 5-5](#) for the PLL\_PRE<11:0> settings for PLL feedback frequency.

**TABLE 5-5: Example: PLL Prescaler Bit Settings and PLL Feedback Frequency**

PLL_PRE<11:0>	PLL Feedback Frequency
1111–1111–1111	VCO clock divided by 4095 ( $2^{12} - 1$ )
1111–1111–1110	VCO clock divided by 4094 ( $2^{12} - 2$ )
—	—
0000–0000–0011	VCO clock divided by 3
0000–0000–0010	VCO clock divided by 2
0000–0000–0001	VCO clock divided by 1
0000–0000–0000	VCO clock divided by 1

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## REGISTER 5-13: ADDRESS 0X58 – PLL CHARGE-PUMP

R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0
FCB<2:0>:			PLL_BIAS	PLL_CHAGPUMP<3:0>			
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **FCB<2:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4 **PLL\_BIAS**: PLL charge-pump bias source selection bit

1 = Self-biasing coming from AV<sub>DD</sub> (**Default**)

0 = Bandgap voltage from the reference generator (1.2V)

bit 3-0 **PLL\_CHAGPUMP<3:0>**: PLL charge pump bias current control bits<sup>(1)</sup>

1111 = Maximum current

...

0010 = (**Default**)

...

0000 = Minimum current

**Note 1:** PLL\_CHAGPUMP<3:0> should be set based on the phase detector comparison frequency. The bias current amplitude increases linearly with increasing the bit setting values. The increase is from approximately 25  $\mu$ A to 375  $\mu$ A, 25  $\mu$ A per step. See [Section 4.7.2.1, "PLL Output Frequency and Output Control Parameters"](#) for more details of the PLL block.

## REGISTER 5-14: ADDRESS 0X59 – PLL ENABLE CONTROL 1

U-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
—	FCB<4:3>		EN_PLL_REFDIV	FCB<2:1>		EN_PLL	FCB<0>
bit 7			bit 0				

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented**: Not used.

bit 6-5 **FCB<4:3>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4 **EN\_PLL\_REFDIV**: Enable PLL Reference Divider (PLL\_REFDIV<9:0>).

1 = Enabled

0 = Reference divider is bypassed (**Default**)

bit 3-2 **FCB<2:1>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 1 **EN\_PLL**: Enable PLL circuit.

1 = Enabled

0 = Disabled (**Default**)

bit 0 **FCB<0>**: Factory-Controlled Bit. This is not for the user. Do not change default setting.

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## REGISTER 5-15: ADDRESS 0X5A – PLL LOOP FILTER RESISTOR

U-0	R/W-0	R/W-1	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_RES<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7      **Unimplemented:** Not used.  
 bit 6-5      **FCB<1:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.  
 bit 4-0      **PLL\_RES<4:0>:** Resistor value selection bits for PLL loop filter<sup>(1)</sup>  
              11111 = Maximum value  
              ...  
              01111 = **(Default)**  
              ...  
              00000 = Minimum value

**Note 1:** PLL\_RES<4:0> should be set based on the phase detector comparison frequency. The resistor value increases linearly with the bit settings, from minimum to maximum values. See the PLL loop filter section in [Section 4.7, "ADC Clock Selection"](#).

## REGISTER 5-16: ADDRESS 0X5B – PLL LOOP FILTER CAP3

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP3<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7      **Unimplemented:** Not used.  
 bit 6-5      **FCB<1:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.  
 bit 4-0      **PLL\_CAP3<4:0>:** Capacitor 3 value selection bits for PLL loop filter<sup>(1)</sup>  
              11111 = Maximum value  
              ...  
              00111 = **(Default)**  
              ...  
              00000 = Minimum value

**Note 1:** This capacitor is in series with the shunt resistor, which is set by PLL\_RES<4:0>. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.

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## REGISTER 5-17: ADDRESS 0X5C – PLL LOOP FILTER CAP1

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP1<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used.

bit 6-5 **FCB<1:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4-0 **PLL\_CAP1<4:0>:** Capacitor 1 value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

00111 = (Default)

...

00000 = Minimum value

**Note 1:** This capacitor is located between the charge pump output and ground, and in parallel with the shunt resistor which is defined by the PLL\_RES<4:0>. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.

## REGISTER 5-18: ADDRESS 0X5D – PLL LOOP FILTER CAP2

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP2<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used.

bit 6-5 **FCB<1:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4-0 **PLL\_CAP2<4:0>:** Capacitor 2 value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

00111 = (Default)

...

00000 = Minimum value

**Note 1:** This capacitor is located between the charge pump output and ground, and in parallel with CAP1 which is defined by the PLL\_CAP1<4:0>. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.

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## REGISTER 5-19: ADDRESS 0X5F – PLL ENABLE CONTROL 2<sup>(1)</sup>

R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1
FCB<5:2>				EN_PLL_OUT	EN_PLL_BIAS	FCB<1:0>	
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4      **FCB<5:2>**: Factory-Controlled Bits. This is not for the user. Do not change the default settings.

bit 3      **EN\_PLL\_OUT**: Enable PLL output.

1 = Enabled

0 = Disabled (**Default**)

bit 2      **EN\_PLL\_BIAS**: Enable PLL bias

1 = Enabled

0 = Disabled (**Default**)

bit 1-0      **FCB<1:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

**Note 1:** To enable PLL output, EN\_PLL\_OUT, EN\_PLL\_BIAS and EN\_PLL in Address 0x59 ([Register 5-14](#)) must be set.

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**REGISTER 5-20: ADDRESS 0X62 – OUTPUT DATA FORMAT AND OUTPUT TEST PATTERN**

U-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
—	FCB	DATA_FORMAT	OUTPUT_MODE<1:0>	TEST_PATTERNS<2:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used.

bit 6 **FCB:** Factory-controlled bit. This is not for the user. Do not change default setting.

bit 5 **DATA\_FORMAT:** Output data format selection

1 = Offset binary (unsigned)

0 = Two's complement (**Default**)

bit 4-3 **OUTPUT\_MODE<1:0>:** Output mode selection<sup>(1)</sup>

11 = Do not use. Output is undefined

10 = Select DDR LVDS output mode with even bit first<sup>(2)</sup>(**Default**)

01 = Select CMOS output mode

00 = Output disabled

bit 2-0 **TEST\_PATTERNS<2:0>:** Test output data pattern selection<sup>(3)</sup>

111 = Output data is pseudo-random number (PN) sequence<sup>(4)</sup>

110 = Sync Pattern for LVDS output

Output: '11111111 0000'

101 = Alternating Sequence for LVDS mode

Output: '01010101 1010'

100 = Alternating Sequence for CMOS mode

Output: '11111111 1111' alternating with '00000000 0000'

011 = Alternating Sequence for CMOS

Output: '01010101 0101' alternating with '10101010 1010'

010 = Ramp Pattern: Output (Q0) is incremented by 1 LSB per 64 clock cycles<sup>(5)</sup>

001 = Double Custom Patterns

Output: Alternating custom pattern A (see Addresses 0X74 - 0X75 – [Registers 5-29 –5-30](#)) and custom pattern B (see Address 0X76 - 0X77 – [Registers 5-31 – 5-32](#))<sup>(6)</sup>

000 = Normal Operation. Output: ADC data (**Default**)

**Note 1:** See [Figures 2-1 –2-2](#) for the timing diagrams.

**2:** Rising edge: Q10, Q8, Q6, Q4, Q2, Q0.

Falling edge: Q11, Q9, Q7, Q5, Q3, Q1.

**3:** See [Section 4.12.12 “Output Test Patterns”](#) for more details.

(a) In LVDS mode: only the active pins (per register settings) are active. Inactive output pins are High Z state.

(b) In CMOS mode: all data output pins (Q11-Q0), output test pins (TP), OVR and WCK pins are active, even if they are disabled by register settings.

Since the output test pins (TP) can toggle during this test, the output test pins can draw extra current if they are connected to the supply pin or ground. To avoid the extra current draws, always leave the TP pins floating (not connected).

**4:** Pseudo-random number (PN) code is generated by the linear feedback shift register (LFSR). See [Section 4.12.12.1, “Pseudo-Random Number \(PN\) Sequence Output”](#) for more details.

**5:** OVR and WCK bits are incremented by 1 per 219 and 218 clock cycles, respectively.

**6:** Pattern A<11:0> and B<11:0> are applied to Q<11:0>. Q11 = OVR, Q10 = WCK.

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**REGISTER 5-21: ADDRESS 0X63 – LVDS OUTPUT LOAD AND DRIVER CURRENT CONTROL**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
FCB<3:0>				LVDS_LOAD	LVDS_IMODE<2:0>		
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-4      **FCB<3:0>**: Factory-controlled bits. This is not for the user. Do not change default setting.

bit 3      **LVDS\_LOAD**: Internal LVDS load termination  
             1 = Enable internal load termination  
             0 = Disable internal load termination (**Default**)

bit 2-0      **LVDS\_IMODE<2:0>**: LVDS driver current control bits  
             111 = 7.2 mA  
             011 = 5.4 mA  
             001 = 3.5 mA (**Default**)  
             000 = 1.8 mA

Do not use the following settings<sup>(1)</sup>:

110, 101, 100, 010

**Note 1:** Do not use these settings. These settings can result in unknown output currents.

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## REGISTER 5-22: ADDRESS 0X64 – OUTPUT CLOCK PHASE CONTROL WHEN DECIMATION FILTER IS USED

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EN_PHDLY	DCLK_PHDLY_DEC<2:0>			FCB<3:0>			
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **EN\_PHDLY:** Enable digital output clock phase delay control when DLL or decimation filter is used.  
 1 = Enabled  
 0 = Disabled (**Default**)

bit 6-4 **DCLK\_PHDLY\_DEC<2:0>:** Digital output clock phase delay control when decimation filter is used<sup>(2)</sup>  
 111 = +315° phase-shifted from default<sup>(2)</sup>  
 110 = +270° phase-shifted from default  
 101 = +225° phase-shifted from default<sup>(2)</sup>  
 100 = +180° phase-shifted from default  
 011 = +135° phase-shifted from default<sup>(2)</sup>  
 010 = +90° phase-shifted from default  
 001 = +45° phase-shifted from default<sup>(2)</sup>  
 000 = **Default**<sup>(3)</sup>

bit 3-0 **FCB<3:0>:** Factory-Controlled Bits. This is not for the user. Do not change default settings.

- Note**
- 1: These bits have an effect only if EN\_PHDLY = 1. See Address 0x52 ([Register 5-7](#)) for the same feature when DLL is used.
  - 2: Only available when the decimation filter setting is greater than 2. When FIR\_A/B <8:1> = 0's (default) and FIR\_A<6> = 0, only 4-phase shifts are available (+45°, +135°, +225°, +315°) from default. See Addresses 0x7A, 0x7B and 0x7C ([Registers 5-35 – 5-37](#)). See Addresses 0x6D and 0x52 ([Registers 5-28 and 5-7](#)) for DCLK phase shift for other modes.
  - 3: The phase delay for all other settings is referenced to this default phase.

## REGISTER 5-23: ADDRESS 0X65 – LVDS OUTPUT POLARITY CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
POL_LVDS<5:0>						NO EFFECT<1:0>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-2 **POL\_LVDS<5:0>:** Control polarity of LVDS data pairs (Q5+/Q5- – Q0+/Q0-)  
 111111 = Invert all LVDS pairs  
 111110 = Invert all LVDS pairs except the LSb pair  
 ...  
 100000 = Invert MSb LVDS pair  
 ...  
 000001 = Invert LSb LVDS pair  
 000000 = No inversion of LVDS bit pairs (**Default**)

bit 1-0 **NO EFFECT<1:0>:** No effect bits.



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## REGISTER 5-24: ADDRESS 0X66 – DIGITAL OFFSET CORRECTION (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIG_OFFSET_GLOBAL<7:0>							
bit 7							
							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **DIG\_OFFSET\_GLOBAL<7:0>**: Lower byte of DIG\_OFFSET\_GLOBAL<15:0> for all channels<sup>(-)</sup>

0000-0000 = **Default**

-Offset is added to the ADC output. Setting is two's complement using two combined registers (16-bits wide).

Setting range:  $(-2^{15} \text{ to } 2^{15} - 1) \times 0.125 \text{ LSB(s)}$

## REGISTER 5-25: ADDRESS 0X67 – DIGITAL OFFSET CORRECTION (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIG_OFFSET_GLOBAL<15:8>							
bit 7							
							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **DIG\_OFFSET\_GLOBAL<15:8>**: Upper byte of DIG\_OFFSET\_GLOBAL<15:0> for all channels<sup>(1)</sup>

0000-0000 = **Default**

**Note 1:** See [Note](#) - in Address 0x66 ([Register 5-24](#))

## REGISTER 5-26: ADDRESS 0X68 – WCK AND OVR BIT CONTROL

R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
FCB<5:2>				POL_WCK_OVR	EN_WCK_OVR	FCB<1:0>	
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **FCB<5:2>**: Factory-controlled bits. This is not for the user. Do not change default settings.

bit 3 **POL\_WCK\_OVR**: Polarity control for WCK and OVR bit pair in LVDS mode

1 = Inverted

0 = Not inverted (**Default**)

bit 2 **EN\_WCK\_OVR**: Enable WCK and OVR output bit pair

1 = Enabled (**Default**)

0 = Disabled

bit 1-0 **FCB<1:0>**: Factory-controlled bits. This is not for the user. Do not change default settings.

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## REGISTER 5-27: ADDRESS 0X6B – PLL CALIBRATION

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
FCB<6:2>					PLL_CAL_TRIG	FCB<1:0>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-3 **FCB<6:2>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 2 **PLL\_CAL\_TRIG**: Manually force recalibration of the PLL at the state of bit transition<sup>(1)</sup>  
Toggle from "1" to "0", or "0" to "1" = Start PLL calibration

bit 1-0 **FCB<1:0>**: Factory-Controlled Bits. This is not for the user. Do not program.

**Note 1:** See PLL\_CAL\_STAT in Address 0xD1 ([Register 5-81](#)) for calibration status indication.

## REGISTER 5-28: ADDRESS 0X6D – PLL OUTPUT AND OUTPUT CLOCK PHASE<sup>(1)</sup>

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—		EN_PLL_CLK	FCB<1>		DCLK_DLY_PLL<2:0>		FCB<0>
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented**: Not used

bit 5 **EN\_PLL\_CLK**: Enable PLL output clock  
1 = PLL output clock is enabled to the ADC core  
0 = PLL clock output is disabled (**Default**)

bit 4 **FCB<1>**: Factory-Controlled Bit. This is not for the user. Do not change default settings.

bit 3-1 **DCLK\_DLY\_PLL<2:0>**: Output clock is delayed by the number of VCO clock cycles from the nominal PLL output<sup>(2)</sup>  
111 = Delay of 15 cycles  
110 = Delay of 14 cycles  
...  
001 = Delay of one cycle  
000 = No delay (**Default**)

bit 0 **FCB<0>**: Factory-Controlled Bit. This is not for the user. Do not change default setting.

**Note 1:** This register has effect only when the PLL clock is selected by the CLK\_SOURCE bit in Address 0x53 ([Register 5-8](#)) and PLL circuit is enabled by EN\_PLL bit in Address 0x59 ([Register 5-14](#)).

**2:** This bit setting enables the output clock phase delay. This phase delay control option is applicable when PLL is used as the clock source and the decimation is not used.

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## REGISTER 5-29: ADDRESS 0X74 – USER-DEFINED OUTPUT PATTERN A (LOWER NIBBLE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_A<3:0>				Do not use (Leave these bits as '0000')			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **PATTERN\_A<3:0>**: Lower nibble of PATTERN\_A<11:0><sup>(1)</sup>

bit 3-0 **Do not use**: Leave these bits to default settings ('0000')<sup>(2)</sup>

- Note** 1: See PATTERN\_A<11:4> in Address 0x75 ([Register 5-30](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).  
2: The output from these bit settings is on "Unused Output Pattern Test Pins", which are recommended to be not connected to the host device. Therefore, the effect of these bit settings is not monitored. Leave these bits as default settings ('0000') all the time.

## REGISTER 5-30: ADDRESS 0X75 – USER-DEFINED OUTPUT PATTERN A (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_A<11:4>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **PATTERN\_A<11:4>**: Upper byte of PATTERN\_A<11:0><sup>(1)</sup>

- Note** 1: See PATTERN\_A<3:0> in Address 0x74 ([Register 5-29](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).

## REGISTER 5-31: ADDRESS 0X76 – USER-DEFINED OUTPUT PATTERN B (LOWER NIBBLE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_B<3:0>				Do not use (Leave these bits as '0000')			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **PATTERN\_B<3:0>**: Lower nibble of PATTERN\_B<11:0><sup>(1)</sup>

bit 3-0 **Do not use**: Leave these bits to default settings ('0000')<sup>(2)</sup>

- Note** 1: See PATTERN\_B<11:4> in Address 0x77 ([Register 5-32](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).  
2: The output from these bit settings is on "Unused Output Pattern Test Pins", which are recommended to be not connected to the host device. Therefore, the effect of these bit settings is not monitored. Leave these bits as default settings ('0000') all the time.

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## REGISTER 5-32: ADDRESS 0X77 – USER-DEFINED OUTPUT PATTERN B (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_B<11:4>							
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **PATTERN\_B<11:4>**: Upper byte of PATTERN\_B<11:0><sup>(1)</sup>

**Note 1:** See PATTERN\_B<3:0> in Address 0x76 ([Register 5-31](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).

## REGISTER 5-33: ADDRESS 0X78 – NOISE-SHAPING REQUANTIZER RESET CONTROL AND CHANNEL A FILTER (NSRA)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NSR_RESET	NSRA<6:0>						
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **NSR\_RESET**: Toggle of this bit causes a reset of the NSRA and NSRB state.

- Toggle from '1' to '0' or from '0' to '1' = Reset of NSRA and NSRB<sup>(2)</sup>
- Otherwise = No effect (**Default**)

bit 6-0                      **NSRA<6:0>**: NSRA filter settings. See [Tables 4-13 to 4-14](#) for the NSR filter settings<sup>(3)</sup>  
 000-0000 = (**Default**)

**Note 1:** This register is used for single- and dual-channel modes only.

**2:** The NSR filter will be also automatically reset if the filter setting is changed.

**3:** In dual-channel mode, NSRA<6:0> is used for channel A.

## REGISTER 5-34: ADDRESS 0X79 – DUAL-CHANNEL DIGITAL SIGNAL POST-PROCESSING CONTROL AND NOISE-SHAPING REQUANTIZER CHANNEL B FILTER (NSRB)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
EN_DSPP_2	NSRB<6:0>						
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **EN\_DSPP\_2**: Enable digital post-processing functions for dual-channel operations  
 1 = Enabled  
 0 = Disabled (**Default**)

bit 6-0                      **NSRB<6:0>**: NSRB filter settings. See [Tables 4-13 to 4-14](#) for the NSR filter settings<sup>(2)</sup>  
 000-0000 = (**Default**)

**Note 1:** This register is used for single- and dual-channel modes only.

**2:** In dual-channel mode, NSRB<6:0> is used for channel B.

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## REGISTER 5-35: ADDRESS 0X7A – FIR\_A0 FILTER, FDR AND NSR CONTROL<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<1>	FIR_A<0>	EN_FDR	FCB<0>	EN_NSRB_11	EN_NSRB_12	EN_NSRA_11	EN_NSRA_12
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **FCB<1>**: Factory-Controlled Bit. This is not for the user. Do not change default setting.

bit 6 **FIR\_A<0>**: Enable the first 2x decimation (Stage 1A in FIR A) in single-channel mode<sup>(2)</sup>

1 = Enabled

0 = Disabled (**Default**)

bit 5 **EN\_FDR**: Enable fractional delay recovery (FDR) option

1 = Enabled (with delay of 59 clock cycles).

0 = Disabled (**Default**)

bit 4 **FCB<0>**: Factory-Controlled Bit. This is not for the user. Do not change default setting.

bit 3 **EN\_NSRB\_11**: Enable 11-bit noise-shaping requantizer for Channel B

1 = Enabled

0 = Disabled (**Default**)

bit 2 **EN\_NSRB\_12**: Enable 12-bit noise-shaping requantizer for Channel B

1 = Enabled

0 = Disabled (**Default**)

bit 1 **EN\_NSRA\_11**: Enable 11-bit noise-shaping requantizer for Channel A

1 = Enabled

0 = Disabled (**Default**)

bit 0 **EN\_NSRA\_12**: Enable 12-bit noise-shaping requantizer for Channel A

1 = Enabled

0 = Disabled (**Default**)

**Note 1:** This register is used only for single- and dual-channel modes.

**Note 2:** This is the LSB of the FIR A filter settings. For the first 2x decimation, set FIR\_A<0> = 1 for single-channel operation, and FIR\_A<0> = 0 for dual-channel operation. See Address 0x7B ([Register 5-36](#)) for FIR\_A<8:1> settings.

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## REGISTER 5-36: ADDRESS 0X7B – FIR A FILTER<sup>(1,5)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FIR_A<8:1>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **FIR\_A<8:1>**: Decimation Filter FIR A settings for Channel A (or I)<sup>(2)</sup>

### Single-Channel Mode:<sup>(3)</sup>

#### **FIR\_A<8:0> =**

- 1-1111-1111 = Stage 1 - 9 filters (decimation rate: 512)
- 0-1111-1111 = Stage 1 - 8 filters
- 0-0111-1111 = Stage 1 - 7 filters
- 0-0011-1111 = Stage 1 - 6 filters
- 0-0001-1111 = Stage 1 - 5 filters
- 0-0000-1111 = Stage 1 - 4 filters
- 0-0000-0111 = Stage 1 - 3 filters (decimation rate = 8)
- 0-0000-0011 = Stage 1 - 2 filters (decimation rate = 4)
- 0-0000-0001 = Stage 1 filter (decimation rate = 2)
- 0-0000-0000 = Disabled all FIR A filters. **(Default)**

### Dual-Channel Mode:<sup>(4)</sup>

#### **FIR\_A<8:0> =**

- 1-1111-1110 = Stage 2 - 9 filters (decimation rate: 256)
- 0-1111-1110 = Stage 2 - 8 filters
- 0-0111-1110 = Stage 2 - 7 filters
- 0-0011-1110 = Stage 2 - 6 filters
- 0-0001-1110 = Stage 2 - 5 filters
- 0-0000-1110 = Stage 2 - 4 filters
- 0-0000-0110 = Stage 2 - 3 filters
- 0-0000-0010 = Stage 2 filter (decimation rate = 2)
- 0-0000-0000 = Disabled all FIR A filters. **(Default)**

- Note**
- 1: This register is used only for single and dual-channel modes. The register values are thermometer encoded.
  - 2: FIR\_A<0> is placed in Address 0x7A ([Register 5-35](#)).
  - 3: In single-channel mode, the 1st stage filter is selected by FIR\_A<0> = 1 in Address 0x7A ([Register 5-35](#)).
  - 4: In dual-channel mode, the 1st stage filter is disabled by setting FIR\_A<0> = 0 in Address 0x7A.
  - 5: SNR is improved by approximately 2.5 dB per each filter stage, and output data rate is reduced by a factor of two per stage. The data and clock rates in Address 0x02 ([Register 5-3](#)) need to be updated accordingly. Address 0x64 ([Register 5-22](#)) setting is also affected. The maximum decimation rate for the single-channel mode is 512, and 256 for the dual-channel mode.

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## REGISTER 5-37: ADDRESS 0X7C – FIR B FILTER<sup>(1,2)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FIR_B<7:0>							
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **FIR\_B<7:0>**: Decimation Filter FIR B settings for Channel B (or Q)<sup>(3)</sup>

1111-1111 = Stage 2 - 9 filters (decimation rate = 256)  
 0111-1111 = Stage 2 - 8 filters  
 0011-1111 = Stage 2 - 7 filters  
 0001-1111 = Stage 2 - 6 filters  
 0000-1111 = Stage 2 - 5 filters  
 0000-0111 = Stage 2 - 4 filters  
 0000-0011 = Stage 2 - 3 filters  
 0000-0001 = Stage 2 filter (decimation rate = 2)  
 0000-0000 = Disabled all FIR B Filters. **(Default)**

- Note** 1: This register is used for the dual-channel mode only. The register values are thermometer encoded.  
 2: EN\_DSPP\_2 bit in Address 0x79 ([Register 5-34](#)) must be set when using decimation in dual-channel mode.  
 3: SNR is improved by approximately 2.5 dB per each filter stage, and output data rate is reduced by a factor of two per stage. The data and clock rates in Address 0x02 ([Register 5-3](#)) need to be updated accordingly. Address 0x64 ([Register 5-22](#)) setting is also affected. The maximum decimation factor for the dual-channel mode is 256.

## REGISTER 5-38: ADDRESS 0X7D – AUTO-SCAN CHANNEL ORDER (LOWER BYTE)

R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
CH_ORDER<7:0>							
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH\_ORDER<7:0>**: Lower byte of CH\_ORDER<31:0><sup>(1)</sup>  
 0111-1000 = **Default**

- Note** 1: See [Table 5-3](#) for the channel order selection. See SEL\_NCH<2:0> in Address 0x01 ([Register 5-2](#)) for the number of channels to be selected.

## REGISTER 5-39: ADDRESS 0X7E – AUTO-SCAN CHANNEL ORDER (MIDDLE BYTE)

R/W-1	R/W-0	R/W-1	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0
CH_ORDER<15:8>							
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH\_ORDER<15:8>**: Middle byte of CH\_ORDER<31:0><sup>(1)</sup>  
 1010-1100 = **Default**

- Note** 1: See [Table 5-3](#) for the channel order selection. See SEL\_NCH<2:0> in Address 0x01 ([Register 5-2](#)) for the number of channels to be selected.

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## REGISTER 5-40: ADDRESS 0X7F – AUTO-SCAN CHANNEL ORDER (UPPER BYTE)

R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-0
CH_ORDER<23:16>							
bit 7				bit 0			

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH\_ORDER<23:16>**: Upper byte of CH\_ORDER<31:0><sup>(1)</sup>  
1000-1110 = **Default**

**Note 1:** See [Table 5-3](#) for the channel order selection. See SEL\_NCH<2:0> in Address 0x01 ([Register 5-2](#)) for the number of channels to be selected.

## REGISTER 5-41: ADDRESS 0X80 – DIGITAL DOWN-CONVERTER CONTROL 1<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
HBFILTER_B	HBFILTER_A	EN_NCO	EN_AMPDITH	EN_PHSDITH	EN_LFSR	EN_DDC_FS/8	EN_DDC1
bit 7				bit 0			

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 7      **HBFILTER\_B**: Select half-bandwidth filter at DDC output of channel B in dual-channel mode<sup>(2)</sup>  
1 = Select High-Pass filter at DDC output  
0 = Select Low-Pass filter at DDC output (**Default**)
- bit 6      **HBFILTER\_A**: Select half-bandwidth filter at DDC output of channel A<sup>(2)</sup>  
1 = Select High-Pass filter at DDC output  
0 = Select Low-Pass filter at DDC output (**Default**)
- bit 5      **EN\_NCO**: Enable NCO of DDC1  
1 = Enabled  
0 = Disabled (**Default**)
- bit 4      **EN\_AMPDITH**: Enable amplitude dithering for NCO<sup>(3, 4)</sup>  
1 = Enabled  
0 = Disabled (**Default**)
- bit 3      **EN\_PHSDITH**: Enable phase dithering for NCO<sup>(3, 4)</sup>  
1 = Enabled  
0 = Disabled (**Default**)
- bit 2      **EN\_LFSR**: Enable linear feedback shift register (LFSR) for amplitude and phase dithering for NCO  
1 = Enabled  
0 = Disabled (**Default**)
- bit 1      **EN\_DDC\_FS/8**: Enable NCO for the DDC2 to center the DDC output signal to be around  $f_s/8/DER$ <sup>(5)</sup>  
1 = Enabled  
0 = Disabled (**Default**)
- bit 0      **EN\_DDC1**: Enable digital down converter 1 (DDC1)  
1 = Enabled<sup>(6)</sup>  
0 = Disabled (**Default**)

- Note 1:** This register is used for single-, dual- and octal-channel modes when CW feature is enabled (8CH\_CW = 1).  
**Note 2:** This filter includes a decimation of 2.  
- Single-channel mode: HBFILTER\_A is used.  
- Dual-channel mode: Both HBFILTER\_A and HBFILTER\_B are used.  
**Note 3:** This requires the LFSR to be enabled: EN\_LFSR=1  
**Note 4:** EN\_AMPDITH = 1 and EN\_PHSDITH = 1 are recommended for the best performance.  
**Note 5:** DER is the decimation rate defined by FIR A or FIR B filter. If up-converter is not enabled (disabled), output is I/Q data.  
**Note 6:** DDC and NCO are enabled. For DDC function, bits 0, 2 and 5 need to be enabled all together.



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## REGISTER 5-42: ADDRESS 0X81 – DIGITAL DOWN-CONVERTER CONTROL 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FDR_BAND	EN_DDC2	GAIN_HBF_DDC	SEL_FDR	EN_DSPP_8	8CH_CW	GAIN_8CH<1:0>	
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 7                      **FDR\_BAND:** Select 1st or 2nd Nyquist band  
1 = 2nd Nyquist band  
0 = 1st Nyquist band (**Default**)
- bit 6                      **EN\_DDC2:** Enable DDC2 after the digital half-band filter (HBF) in DDC.  
1 = Enabled  
0 = Disabled (**Default**)
- bit 5                      **GAIN\_HBF\_DDC:** Gain selection for the output of the digital half-band filter (HBF) in DDC<sup>(1)</sup>  
1 = x2  
0 = x1 (**Default**)
- bit 4                      **SEL\_FDR:** Select fractional delay recovery (FDR)  
1 = FDR for 8-channel  
0 = FDR for dual-channel (**Default**)
- bit 3                      **EN\_DSPP\_8:** Enable digital signal post-processing (DSPP) features for 8-channel operation<sup>(2)</sup>  
1 = Enabled  
0 = Disabled (**Default**)
- bit 2                      **8CH\_CW:** Enable CW mode in octal-channel mode<sup>(2, 3)</sup>  
1 = Enabled  
0 = Disabled (**Default**)
- bit 1-0                      **GAIN\_8CH<1:0>:** Select gain factor for CW signal in octal-channel modes.  
11 = x8, 10 = x4, 01 = x2, 00 = x1 (**Default**)
- Note** 1: See [Section 4.8.3, "Decimation Filters"](#).  
2: By enabling this bit, the phase offset corrections in Addresses 0x086 – 0x095 ([Registers 5-47 – 5-62](#)) are also enabled. EN\_DSPP\_8 is a global setting bit to enable SEL\_FDR and LVDS\_8CH bits (Address 0x62 - [Register 5-20](#)).  
3: When CW mode is enabled, the ADC output is the result of the summation (addition) of all eight channels' data after each channel's digital phase offset, digital gain, and digital offset are controlled using the Addresses 0x86 - 0xA7 ([Registers 5-47 to 5-79](#)). The result is similar to the beamforming in the phased-array sensors.

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## REGISTER 5-43: ADDRESS 0X82 – NUMERICALLY CONTROLLED OSCILLATOR TUNING (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_TUNE <7:0>**: Lower byte of NCO\_TUNE<31:0><sup>(1)</sup>  
0000–0000 = DC (0 Hz) when NCO\_TUNE<31:0> = 0x00000000 (**Default**)

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-46](#)).

## REGISTER 5-44: ADDRESS 0X83 – NUMERICALLY CONTROLLED OSCILLATOR TUNING (MIDDLE-LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_TUNE <15:8>**: Middle lower byte of NCO\_TUNE<31:0><sup>(1)</sup>  
0000–0000 = **Default**

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-46](#)).

## REGISTER 5-45: ADDRESS 0X84 – NUMERICALLY CONTROLLED OSCILLATOR TUNING (MIDDLE-UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<23:16>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_TUNE <23:16>**: Middle upper byte of NCO\_TUNE<31:0><sup>(1)</sup>  
0000–0000 = **Default**

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-46](#)).

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## REGISTER 5-46: ADDRESS 0X85 – NUMERICALLY CONTROLLED OSCILLATOR TUNING (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<31:24>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_TUNE<31:24>**: Upper byte of NCO\_TUNE<31:0><sup>(1,2)</sup>  
1111-1111 =  $f_S$  if NCO\_TUNE<31:0> = 0xFFFF FFFF  
...  
0000-0000 = **Default**

- Note** 1: This Register is used only when DDC is enabled: EN\_DDC1 = 1 in Address 0x80 (Register 5-41). See Section 4.8.4.3, "Numerically Controlled Oscillator (NCO)" for the details of NCO.  
2: NCO frequency = (NCO\_TUNE<31:0>/2<sup>32</sup>) x  $f_S$ , where  $f_S$  is the sampling clock frequency.

## REGISTER 5-47: ADDRESS 0X86 – CH0 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH0\_NCO\_PHASE<7:0>**: Lower byte of CH0\_NCO\_PHASE<15:0><sup>(1,2,3)</sup>  
1111-1111 = 1.4° when CH0\_NCO\_PHASE<15:0> = 0x00FF  
...  
0000-0000 = 0° when CH0\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

- Note** 1: This register is not used in the MCP37211. In the MCP37D11, this register has an effect when the following modes are used:  
- CW with DDC mode in octal-channel mode  
- Single and dual-channel mode with DDC.  
2: CH0 is the 1<sup>st</sup> channel selected by CH\_ORDER<23:0>.  
3: CH(n)\_NCO\_PHASE<15:0> = 2<sup>16</sup> x Phase Offset Value/360.

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## REGISTER 5-48: ADDRESS 0X87: CH0 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0_NCO_PHASE<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH0\_NCO\_PHASE<15:8>**: Upper byte of CH0\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH0\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH0\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) - [Note 3](#) in [Register 5-47](#).

## REGISTER 5-49: ADDRESS 0X88 – CH1 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH1_NCO_PHASE<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH1\_NCO\_PHASE<7:0>**: Lower byte of CH1\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 1.4° when CH1\_NCO\_PHASE<15:0> = 0x00FF

...

0000-0000 = 0° when CH1\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) - [Note 3](#) in [Register 5-47](#). CH1 is the 2nd channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-50: ADDRESS 0X89 – CH1 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH1_NCO_PHASE<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH1\_NCO\_PHASE <15:8>**: Upper byte of CH1\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH1\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH1\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) - [Note 3](#) in [Register 5-47](#). CH1 is the 2nd channel selected by CH\_ORDER<23:0> bits.

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## REGISTER 5-51: ADDRESS 0X8A – CH2 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH2_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH2\_NCO\_PHASE<7:0>**: Lower byte of CH2\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 1.4° when CH2\_NCO\_PHASE<15:0> = 0x00FF  
...  
0000-0000 = 0° when CH2\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH2 is the 3rd channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-52: ADDRESS 0X8B – CH2 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH2_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH2\_NCO\_PHASE <15:8>**: Upper byte of CH2\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 359.995° when CH2\_NCO\_PHASE<15:0> = 0xFFFF  
...  
0000-0000 = 0° when CH2\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH2 is the 3rd channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-53: ADDRESS 0X8C – CH3 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH3_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH3\_NCO\_PHASE<7:0>**: Lower byte of CH3\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 1.4° when CH3\_NCO\_PHASE<15:0> = 0x00FF  
...  
0000-0000 = 0° when CH3\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH3 is the 4th channel selected by CH\_ORDER<23:0> bits.

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## REGISTER 5-54: ADDRESS 0X8D – CH3 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH3_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH3\_NCO\_PHASE <15:8>**: Upper byte of CH3\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH3\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH3\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH3 is the 4th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-55: ADDRESS 0X8E – CH4 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH4_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH4\_NCO\_PHASE <7:0>**: Lower byte of CH4\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 1.4° when CH4\_NCO\_PHASE<15:0> = 0x00FF

...

0000-0000 = 0° when CH4\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH4 is the 5th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-56: ADDRESS 0X8F – CH4 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH4_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH4\_NCO\_PHASE <15:8>**: Upper byte of CH4\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH4\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH4\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH4 is the 5th channel selected by CH\_ORDER<23:0> bits.

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## REGISTER 5-57: ADDRESS 0X90 – CH5 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH5_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH5\_NCO\_PHASE<7:0>**: Lower byte of CH5\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 1.4° when CH5\_NCO\_PHASE<15:0> = 0x00FF  
...  
0000-0000 = 0° when CH5\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH5 is the 6th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-58: ADDRESS 0X91 – CH5 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH5_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH5\_NCO\_PHASE <15:8>**: Upper byte of CH5\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 359.995° when CH5\_NCO\_PHASE<15:0> = 0xFFFF  
...  
0000-0000 = 0° when CH5\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH5 is the 6th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-59: ADDRESS 0X92 – CH6 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH6_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH6\_NCO\_PHASE<7:0>**: Lower byte of CH6\_NCO\_PHASE<15:0><sup>(1)</sup>  
1111-1111 = 1.4° when CH6\_NCO\_PHASE<15:0> = 0x00FF  
...  
0000-0000 = 0° when CH6\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH6 is the 7th channel selected by CH\_ORDER<23:0> bits.

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-60: ADDRESS 0X93 – CH6 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH6_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH6\_NCO\_PHASE <15:8>**: Upper byte of CH6\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH6\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH6\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH6 is the 7th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-61: ADDRESS 0X94 – CH7 NCO PHASE OFFSET IN CW OR DDC MODE (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH7_NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH7\_NCO\_PHASE <7:0>**: Lower byte of CH7\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 1.4° when CH7\_NCO\_PHASE<15:0> = 0x00FF

...

0000-0000 = 0° when CH7\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH7 is the 8th channel selected by CH\_ORDER<23:0> bits.

## REGISTER 5-62: ADDRESS 0X95 – CH7 NCO PHASE OFFSET IN CW OR DDC MODE (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH7_NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH7\_NCO\_PHASE <15:8>**: Upper byte of CH7\_NCO\_PHASE<15:0><sup>(1)</sup>

1111-1111 = 359.995° when CH7\_NCO\_PHASE<15:0> = 0xFFFF

...

0000-0000 = 0° when CH7\_NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1 - Note 3](#) in [Register 5-47](#). CH7 is the 8th channel selected by CH\_ORDER<23:0> bits.



# MCP37211-200 AND MCP37D11-200

## REGISTER 5-63: ADDRESS 0X96 – CH0 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH0_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH0\_DIG\_GAIN<7:0>**: Digital gain setting for channel 0<sup>(1,2)</sup>

1111-1111 = -0.03125  
1111-1110 = -0.0625  
1111-1101 = -0.09375  
1111-1100 = -0.125  
...  
1000-0011 = -3.90625  
1000-0010 = -3.9375  
1000-0001 = -3.96875  
1000-0000 = -4  
0111-1111 = 3.96875 (MAX)  
0111-1110 = 3.9375  
0111-1101 = 3.90625  
0111-1100 = 3.875  
...  
0011-1100 = 1.875 (Default)  
...  
0000-0011 = 0.09375  
0000-0010 = 0.0625  
0000-0001 = 0.03125  
0000-0000 = 0.0

- Note** 1: CH0 is the 1<sup>st</sup> channel selected by CH\_ORDER<23:0>.  
2: Max = 0x7F(3.96875), Min = 0x80 (-4), Step size = 0x01 (0.03125). Bits from 0x81-0xFF are two's complementary of 0x00-0x80. Negative gain setting inverts output. See Addresses 0x7D - 0x7F ([Registers 5-38 – 5-40](#)) for channel selection.

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-64: ADDRESS 0X97 – CH1 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH1_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CH1\_DIG\_GAIN<7:0>**: Digital gain setting for channel 1<sup>(1,2)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

**Note 1:** CH1 is the 2<sup>nd</sup> channel selected by CH\_ORDER<23:0>.

**Note 2:** See [Note 2](#) in [Register 5-63](#).

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-65: ADDRESS 0X98 – CH2 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH2_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH2\_DIG\_GAIN<7:0>**: Digital gain setting for channel 2<sup>(1,2)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

- Note** 1: CH2 is the 3<sup>rd</sup> channel selected by CH\_ORDER<23:0> bits.  
2: See [Note 2](#) in [Register 5-63](#).

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## REGISTER 5-66: ADDRESS 0X99 – CH3 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH3_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CH3\_DIG\_GAIN<7:0>**: Digital gain setting for channel 3<sup>(1,2)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

**Note 1:** CH3 is the 4<sup>th</sup> channel selected by CH\_ORDER<23:0> bits.

**Note 2:** See [Note 2](#) in [Register 5-63](#).

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-67: ADDRESS 0X9A – CH4 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH4_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH4\_DIG\_GAIN<7:0>**: Digital gain setting for channel 4<sup>(1,2)</sup>

1111-1111 = -0.03125  
1111-1110 = -0.0625  
1111-1101 = -0.09375  
1111-1100 = -0.125  
...  
1000-0011 = -3.90625  
1000-0010 = -3.9375  
1000-0001 = -3.96875  
1000-0000 = -4  
0111-1111 = 3.96875 (MAX)  
0111-1110 = 3.9375  
0111-1101 = 3.90625  
0111-1100 = 3.875  
...  
0011-1100 = 1.875 (Default)  
...  
0000-0011 = 0.09375  
0000-0010 = 0.0625  
0000-0001 = 0.03125  
0000-0000 = 0.0

- Note** 1: CH4 is the 5<sup>th</sup> channel selected by CH\_ORDER<23:0>.  
2: See [Note 2](#) in [Register 5-63](#).

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## REGISTER 5-68: ADDRESS 0X9B – CH5 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH5_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CH5\_DIG\_GAIN<7:0>**: Digital gain setting for channel 5<sup>(1,2)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

- Note**    1: CH5 is the 6<sup>th</sup> channel selected by CH\_ORDER<23:0>.  
          2: See [Note 2](#) in [Register 5-63](#).

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## REGISTER 5-69: ADDRESS 0X9C – CH6 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH6_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH6\_DIG\_GAIN<7:0>**: Digital gain setting for channel 6<sup>(1,2)</sup>

1111-1111 = -0.03125  
1111-1110 = -0.0625  
1111-1101 = -0.09375  
1111-1100 = -0.125  
...  
1000-0011 = -3.90625  
1000-0010 = -3.9375  
1000-0001 = -3.96875  
1000-0000 = -4  
0111-1111 = 3.96875 (MAX)  
0111-1110 = 3.9375  
0111-1101 = 3.90625  
0111-1100 = 3.875  
...  
0011-1100 = 1.875 (Default)  
...  
0000-0011 = 0.09375  
0000-0010 = 0.0625  
0000-0001 = 0.03125  
0000-0000 = 0.0

- Note** 1: CH6 is the 7<sup>th</sup> channel selected by CH\_ORDER<23:0>.  
2: See [Note 2](#) in [Register 5-63](#).

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## REGISTER 5-70: ADDRESS 0X9D – CH7 DIGITAL GAIN

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
CH7_DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CH7\_DIG\_GAIN<7:0>**: Digital gain setting for channel 7<sup>(1,2)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

- Note**    1: CH7 is the 8<sup>th</sup> channel selected by CH\_ORDER<23:0>.  
          2: See [Note 2](#) in [Register 5-63](#).



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## REGISTER 5-71: ADDRESS 0X9E – CH0 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH0\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 0<sup>(1)</sup>

1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Table 4-21](#) for the corresponding channel. Offset value is two's complement. This value is multiplied by DIG\_OFFSET\_WEIGHT<1:0> in Address 0xA7 ([Register 5-79](#)).

## REGISTER 5-72: ADDRESS 0X9F – CH1 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH1_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH1\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 1<sup>(1)</sup>

1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

## REGISTER 5-73: ADDRESS 0XA0 – CH2 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH2_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH2\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 2<sup>(1)</sup>

1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

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## REGISTER 5-74: ADDRESS 0XA1 – CH3 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH3_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH3\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 3<sup>(1)</sup>

1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

## REGISTER 5-75: ADDRESS 0XA2 – CH4 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH4_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH4\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 4<sup>(1)</sup>

1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

## REGISTER 5-76: ADDRESS 0XA3 – CH5 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH5_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CH5\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 5<sup>(1)</sup>

1111-1111 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>

...

0000-0001 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>

0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

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## REGISTER 5-77: ADDRESS 0XA4 – CH6 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH6_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH6\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 6<sup>(1)</sup>  
 1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>  
 ...  
 0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>  
 0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

## REGISTER 5-78: ADDRESS 0XA5 – CH7 DIGITAL OFFSET

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH7_DIG_OFFSET<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **CH7\_DIG\_OFFSET <7:0>**: Digital offset setting bits for channel 7<sup>(1)</sup>  
 1111-1111 = 0xFF x DIG\_OFFSET\_WEIGHT<1:0>  
 ...  
 0000-0001 = 0x01 x DIG\_OFFSET\_WEIGHT<1:0>  
 0000-0000 = 0 (Default)

**Note 1:** See [Note 1](#) in [Register 5-71](#).

## REGISTER 5-79: ADDRESS 0XA7 – DIGITAL OFFSET WEIGHT CONTROL

R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
FCB<5:3>			DIG_OFFSET_WEIGHT<1:0>		FCB<2:0>		
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-5      **FCB<5:3>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

bit 4-3      **DIG\_OFFSET\_WEIGHT<1:0>**: Control the weight of the digital offset settings<sup>(1)</sup>  
 11 = 2 LSb x Digital Gain  
 10 = LSb x Digital Gain  
 01 = LSb/2 x Digital Gain  
 00 = LSb/4 x Digital Gain, (Default)

bit 2-0      **FCB<2:0>**: Factory-Controlled Bits. This is not for the user. Do not change default settings.

**Note 1:** This bit setting is used for the digital offset setting registers in Addresses 0x9E - 0xA7 ([Registers 5-71](#) – [5-79](#)).

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-80: ADDRESS 0XC0 – CALIBRATION STATUS INDICATION

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
ADC_CAL_STAT	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **ADC\_CAL\_STAT:** Power-up auto-calibration status indication flag bit

1 = Device power-up calibration is completed

0 = Device power-up calibration is not completed

bit 6-0 **FCB<6:0>:** Factory-Controlled Bits. These bits are read only, and have no meaning for the user.

## REGISTER 5-81: ADDRESS 0XD1 – PLL CALIBRATION STATUS AND PLL DRIFT STATUS INDICATION

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
FCB<4:3>	PLL_CAL_STAT	FCB<2:1>	PLL_VCOL_STAT	PLL_VCOH_STAT	FCB<0>		
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **FCB<4:3>:** Factory-Controlled Bits. These bits are read only, and have no meaning for the user.

bit 5 **PLL\_CAL\_STAT:** PLL auto-calibration status indication flag bit<sup>(1)</sup>

1 = Complete: PLL auto-calibration is completed

0 = Incomplete: PLL auto-calibration is not completed

bit 4-3 **FCB<2:1>:** Factory-Controlled Bits. These bits are read only, and have no meaning for the user.

bit 2 **PLL\_VCOL\_STAT:** PLL drift status indication bit

1 = PLL drifts out of lock with low VCO frequency

0 = PLL operates as normal

bit 1 **PLL\_VCOH\_STAT:** PLL drift status indication bit

1 = PLL drifts out of lock with high VCO frequency

0 = PLL operates as normal

bit 0 **FCB<0>:** Factory-Controlled Bit. This bit is readable, but has no meaning for the user.

**Note 1:** See PLL\_CAL\_TRIG bit setting in Address 0x6B ([Register 5-27](#)).

# MCP37211-200 AND MCP37D11-200

## REGISTER 5-82: ADDRESS 0X15C – CHIP ID (LOWER BYTE)

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
CHIP_ID<7:0>							
bit 7							
							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CHIP\_ID<7:0>**: Device identification number. Lower byte of the CHIP ID<15:0><sup>(1)</sup>

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

**Example:** MCP37211-200: '0000 1000 0011 0000'

MCP37D11-200: '0000 1010 0011 0000'

## REGISTER 5-83: ADDRESS 0X15D – CHIP ID (UPPER BYTE)

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
CHIP_ID<15:8>							
bit 7							
							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **CHIP\_ID<15:8>**: Device identification number. Lower byte of the CHIP ID<15:0><sup>(1)</sup>

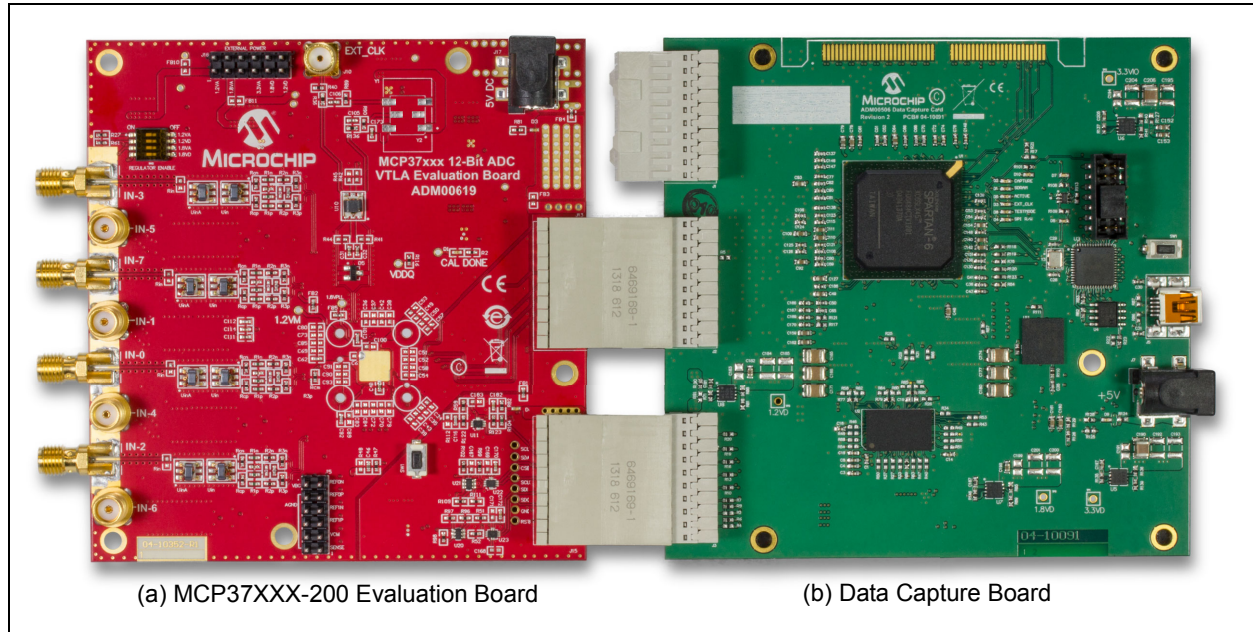
**Note 1:** See [Note 1](#) in [Register 5-82](#).

# MCP37211-200 AND MCP37D11-200

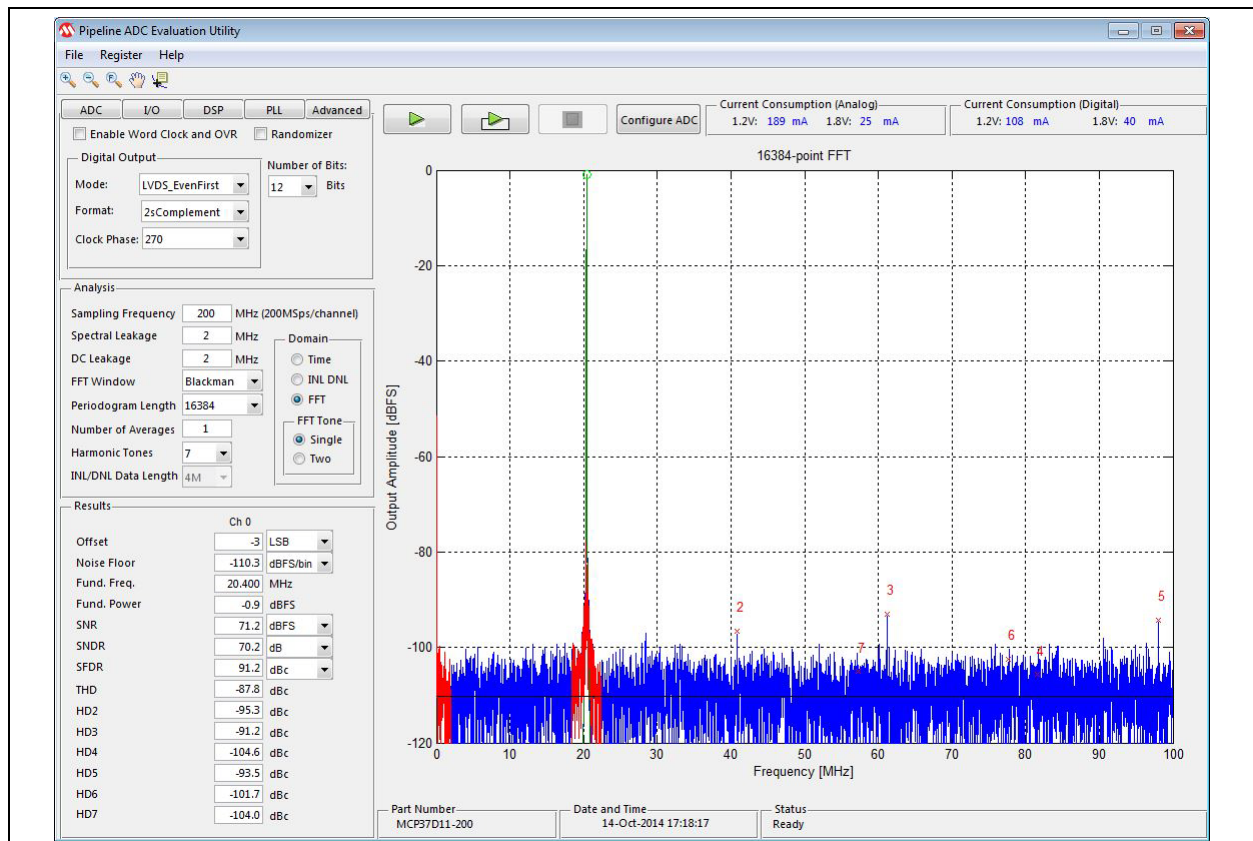
## 6.0 DEVELOPMENT SUPPORT

Microchip offers a high-speed ADC evaluation platform which can be used to evaluate Microchip's high-speed ADC products. The platform consists of an MCP37XXX evaluation board, an FPGA-based data capture card board, and PC-based Graphical User Interface (GUI)

software for ADC configuration and evaluation. Figure 6-1 and Figure 6-2 show this evaluation tool. This evaluation platform allows users to quickly evaluate the ADC's performance for their specific application requirements. More information is available at <http://www.microchip.com>.



**FIGURE 6-1:** MCP37XXX Evaluation Kit.



**FIGURE 6-2:** PC-Based Graphical User Interface Software.

# MCP37211-200 AND MCP37D11-200

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NOTES:

# MCP37211-200 AND MCP37D11-200

## 7.0 TERMINOLOGY

### Analog Input Bandwidth (Full-Power Bandwidth)

The analog input frequency at which the spectral power of the fundamental frequency (as determined by FFT analysis) is reduced by 3 dB.

### Aperture Delay or Sampling Delay

This is the time delay between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

### Aperture Uncertainty

The sample-to-sample variation in aperture delay.

### Aperture Delay Jitter

The variation in the aperture delay time from conversion to conversion. This random variation will result in noise when sampling an AC input. The signal-to-noise ratio due to the jitter alone will be:

#### EQUATION 7-1:

$$SNR_{JITTER} = -20\log(2\pi \times f_{IN} \times t_{JITTER})$$

### Calibration Algorithms

This device utilizes two patented analog and digital calibration algorithms, Harmonic Distortion Correction (HDC) and DAC Noise Cancellation (DNC), to improve the ADC performance. The algorithms compensate various sources of linear impairments such as capacitance mismatch, charge injection error and finite gain of operational amplifiers. These algorithms execute in both power-up sequence (foreground) and background mode:

- Power-Up Calibration: The calibration is conducted within the first  $2^{27}$  clock cycles after power-up. The user needs to wait this Power-Up Calibration period after the device is powered-up for an accurate ADC performance.
- Background Calibration: This calibration is conducted in the background while the ADC performs conversions. The update rate is about every  $2^{30}$  clock cycles.

### Channel Crosstalk

This is a measure of the internal coupling of a signal from an adjacent channel into the channel of interest in the multi-channel mode. It is measured by applying a full-scale input signal in the adjacent channel. Crosstalk is the ratio of the power of the coupling signal (as measured at the output of the channel of interest) to the power of the signal applied at the adjacent channel input. It is typically expressed in dBc.

### Pipeline Delay (LATENCY)

LATENCY is the number of clock cycles between the initiation of conversion and when that data is presented to the output driver stage. Data for any given sample is available after the pipeline delay plus the output delay after that sample is taken. New data is available at every clock cycle, but the data lags the conversion by the pipeline delay plus the output delay. Latency is increased if digital signal post-processing is used.

### Clock Pulse Width and Duty Cycle

The clock duty cycle is the ratio of the time the clock signal remains at a logic high (clock pulse width) to one clock period. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.

### Differential Nonlinearity (DNL, No Missing Codes)

An ideal ADC exhibits code transitions that are exactly 1 LSB apart. DNL is the deviation from this ideal value. No missing codes to 12-bit resolution indicates that all 4096 codes must be present over all the operating conditions.

### Integral Nonlinearity (INL)

INL is the maximum deviation of each individual code from an ideal straight line drawn from negative full scale through positive full scale.

### Signal-to-Noise Ratio (SNR)

SNR is the ratio of the power of the fundamental ( $P_S$ ) to the noise floor power ( $P_N$ ), below the Nyquist frequency and excluding the power at DC and the first nine harmonics.

#### EQUATION 7-2:

$$SNR = 10\log\left(\frac{P_S}{P_N}\right)$$

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.



# MCP37211-200 AND MCP37D11-200

## Signal-to-Noise and Distortion (SINAD)

SINAD is the ratio of the power of the fundamental ( $P_S$ ) to the power of all the other spectral components including noise ( $P_N$ ) and distortion ( $P_D$ ) below the Nyquist frequency, but excluding DC:

### EQUATION 7-3:

$$\begin{aligned} \text{SINAD} &= 10\log\left(\frac{P_S}{P_D + P_N}\right) \\ &= -10\log\left[10^{\frac{\text{SNR}}{10}} - 10^{\frac{\text{THD}}{10}}\right] \end{aligned}$$

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

## Effective Number of Bits (ENOB)

The effective number of bits for a sine wave input at a given input frequency can be calculated directly from its measured SINAD using the following formula:

### EQUATION 7-4:

$$\text{ENOB} = \frac{\text{SINAD} - 1.76}{6.02}$$

## Gain Error

Gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range.

Gain error is usually expressed in LSb or as a percentage of full-scale range (%FSR).

## Gain-Error Drift

Gain-error drift is the variation in gain-error due to a change in ambient temperature, typically expressed in ppm/°C.

## Offset Error

The major carry transition should occur for an analog value of 50% LSb below  $A_{IN+} = A_{IN-}$ . Offset error is defined as the deviation of the actual transition from that point.

## Temperature Drift

The temperature drift for offset error and gain error specifies the maximum change from the initial (+25°C) value to the value across the  $T_{MIN}$  to  $T_{MAX}$  range.

## Maximum Conversion Rate

The maximum clock rate at which parametric testing is performed.

## Minimum Conversion Rate

The minimum clock rate at which parametric testing is performed.

## Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier) or dBFS.

## Total Harmonic Distortion (THD)

THD is the ratio of the power of the fundamental ( $P_S$ ) to the summed power of the first 13 harmonics ( $P_D$ ).

### EQUATION 7-5:

$$\text{THD} = 10\log\left(\frac{P_S}{P_D}\right)$$

THD is typically given in units of dBc (dB to carrier). THD is also shown by:

### EQUATION 7-6:

$$\text{THD} = -20\log\frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + \dots + V_n^2}}{V_1}$$

Where:

$V_1$  = RMS amplitude of the fundamental frequency

$V_1$  through  $V_n$  = Amplitudes of the second through  $n^{\text{th}}$  harmonics

## Two-Tone Intermodulation Distortion (Two-Tone IMD, IMD3)

Two-tone IMD is the ratio of the power of the fundamental (at frequencies  $f_{IN1}$  and  $f_{IN2}$ ) to the power of the worst spectral component at either frequency  $2f_{IN1} - f_{IN2}$  or  $2f_{IN2} - f_{IN1}$ . Two-tone IMD is a function of the input amplitudes and frequencies ( $f_{IN1}$  and  $f_{IN2}$ ). It is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the ADC full-scale range.

# MCP37211-200 AND MCP37D11-200

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## Common-Mode Rejection Ratio (CMRR)

Common-mode rejection is the ability of a device to reject a signal that is common to both sides of a differential input pair. The common-mode signal can be an AC or DC signal or a combination of the two. CMRR is measured using the ratio of the differential signal gain to the common-mode signal gain and expressed in dB with the following equation:

### EQUATION 7-7:

$$CMRR = 20\log\left(\frac{A_{DIFF}}{A_{CM}}\right)$$

Where:

$A_{DIFF} = \Delta\text{Output Code}/\Delta\text{Differential Voltage}$

$A_{CM} = \Delta\text{Output Code}/\Delta\text{Common Mode Voltage}$

# MCP37211-200 AND MCP37D11-200

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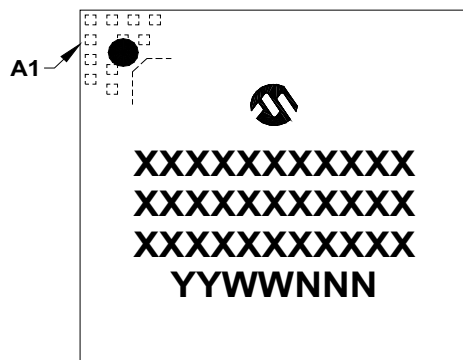
NOTES:

# MCP37211-200 AND MCP37D11-200

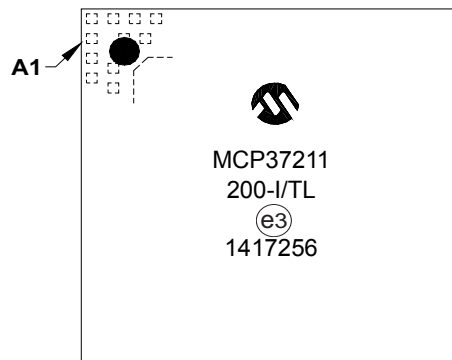
## 8.0 PACKAGING INFORMATION

### 8.1 Package Marking Information

124-Lead VTLA (9x9x0.9 mm)



Example



<b>Legend:</b>	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC <sup>®</sup> designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.

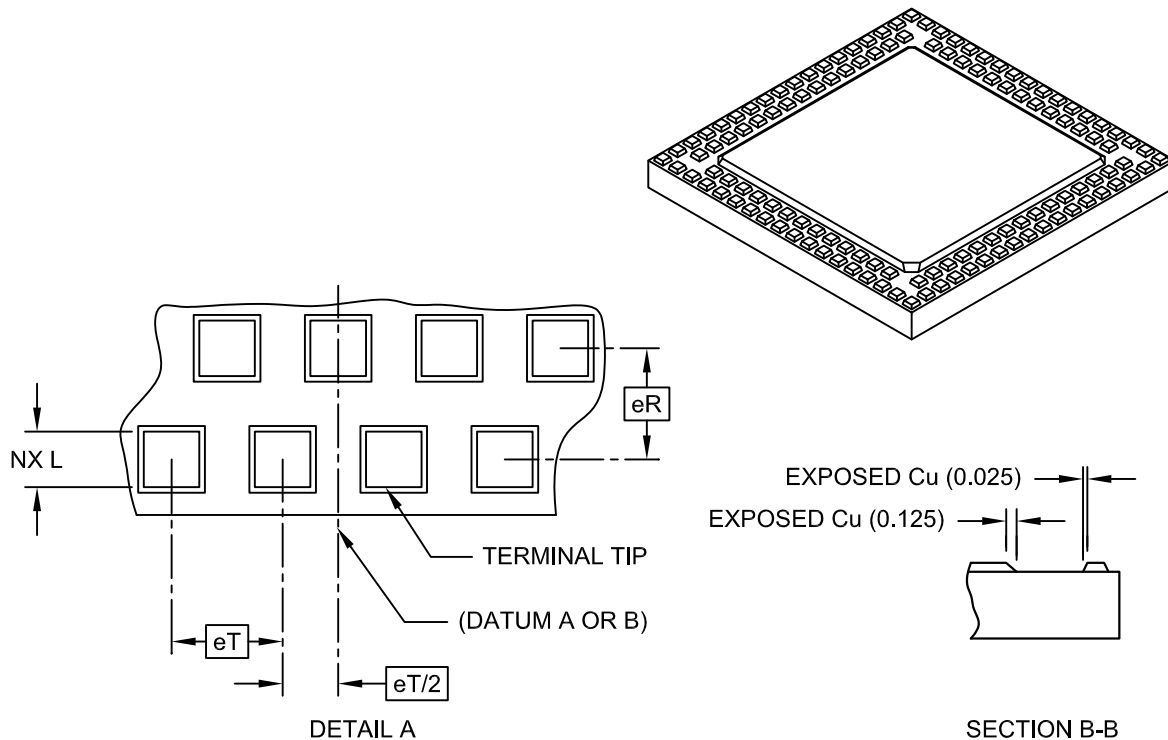
**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.



# MCP37211-200 AND MCP37D11-200

## 124-Terminal Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	124		
Pitch	eT	0.50 BSC		
Pitch (Inner to outer terminal ring)	eR	0.50 BSC		
Overall Height	A	0.80	0.85	0.90
Standoff	A1	0.00	-	0.05
Overall Width	E	9.00 BSC		
Exposed Pad Width	E2	6.40	6.55	6.70
Overall Length	D	9.00 BSC		
Exposed Pad Length	D2	6.40	6.55	6.70
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.20	0.25	0.30
Contact-to-Exposed Pad	K	0.20	-	-

### Notes:

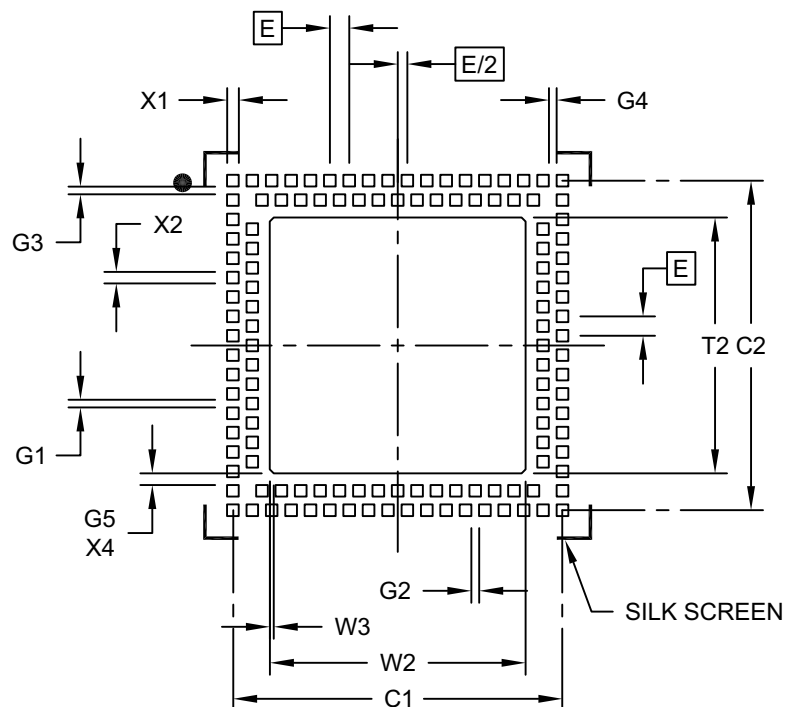
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated.
- Dimensioning and tolerancing per ASME Y14.5M.  
BSC: Basic Dimension. Theoretically exact value shown without tolerances.  
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-193A Sheet 2 of 2

# MCP37211-200 AND MCP37D11-200

## 124-Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.50 BSC		
Pad Clearance	G1	0.20		
Pad Clearance	G2	0.20		
Pad Clearance	G3	0.20		
Pad Clearance	G4	0.20		
Contact to Center Pad Clearance (X4)	G5	0.30		
Optional Center Pad Width	T2			6.60
Optional Center Pad Length	W2			6.60
Optional Center Pad Chamfer (X4)	W3		0.10	
Contact Pad Spacing	C1		8.50	
Contact Pad Spacing	C2		8.50	
Contact Pad Width (X124)	X1			0.30
Contact Pad Length (X124)	X2			0.30

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2193A

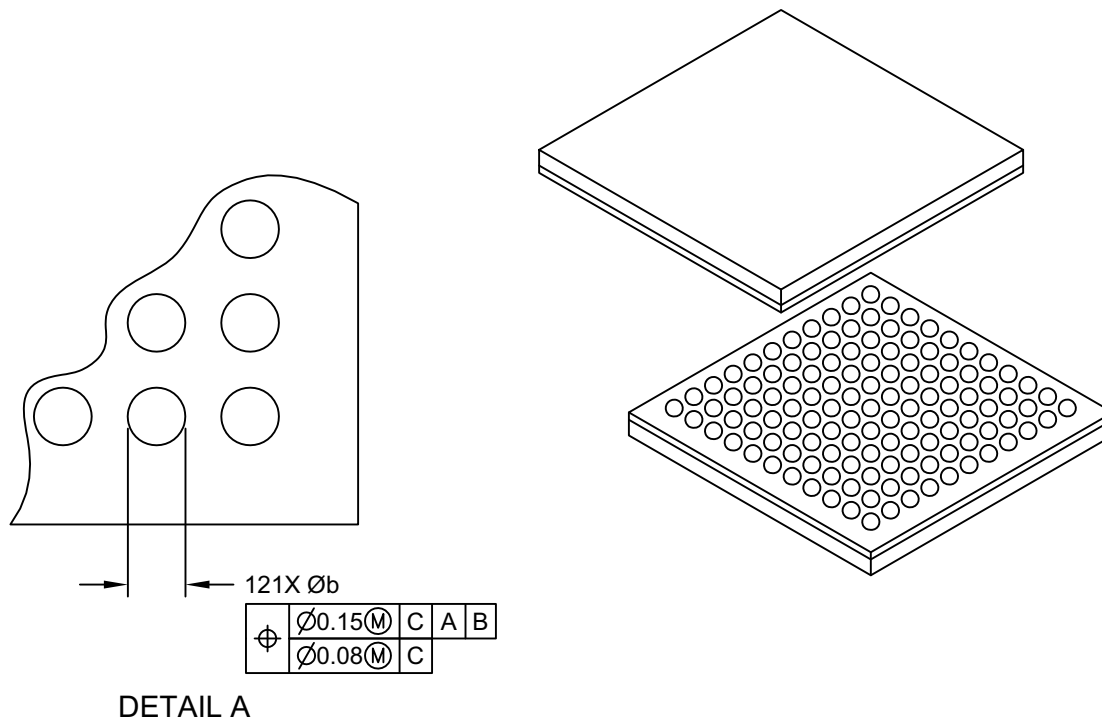




# MCP37211-200 AND MCP37D11-200

## 121-Ball Thin Fine Pitch Ball Grid Array (TE) - 8x8 mm Body [TFBGA] System In Package

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Terminals	N	121		
Pitch	eE	0.65 BSC		
Pitch	eD	0.65 BSC		
Overall Height	A	-	-	1.08
Standoff	A1	0.21	0.32	-
Cap Thickness	A2	0.40	0.45	0.50
Overall Width	E	8.00 BSC		
Overall Pitch	E1	6.50 BSC		
Overall Length	D	8.00 BSC		
Overall Pitch	D1	6.50 BSC		
Terminal Diameter	b	0.35	0.40	0.45

### Notes:

1. Terminal A1 visual index feature may vary, but must be located within the hatched area.
2. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

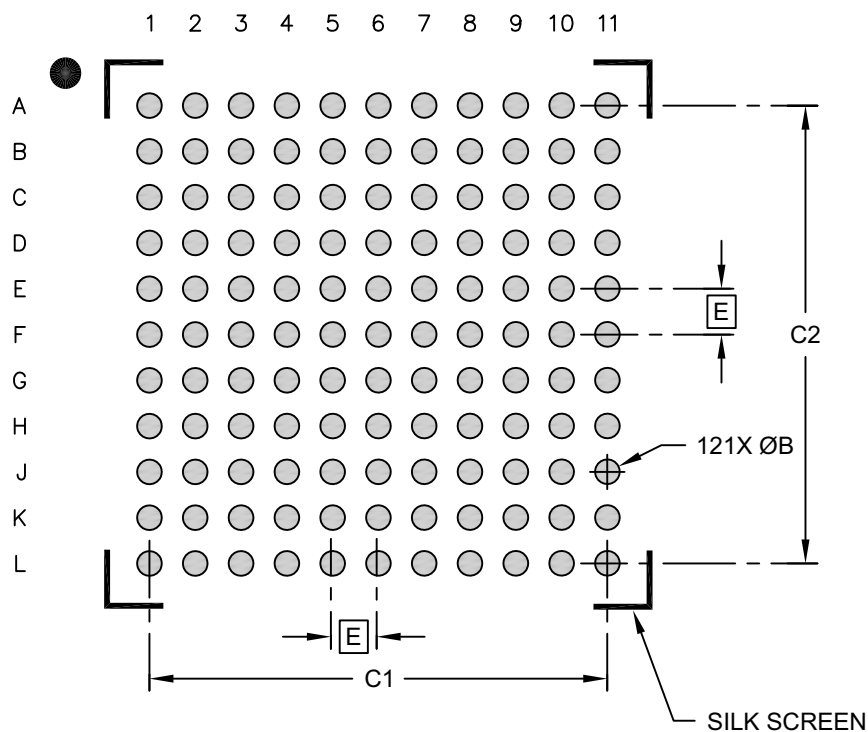
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-212-TE Rev C Sheet 2 of 2

# MCP37211-200 AND MCP37D11-200

## 121-Ball Thin Fine Pitch Ball Grid Array (TE) - 8x8 mm Body [TFBGA] System In Package

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C1		6.50	
Contact Pad Spacing	C2		6.50	
Contact Pad Diameter (X121)	B		0.35	

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2212-TE Rev C

# MCP37211-200 AND MCP37D11-200

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NOTES:

# MCP37211-200 AND MCP37D11-200

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## APPENDIX A: REVISION HISTORY

### Revision D (December 2019)

The following is the list of modifications:

- Added the AEC-Q100 automotive qualification.
- Updated [Section “Typical Applications”](#) and [Section “Description”](#).
- Updated [Section 2.0, Electrical Specifications](#).
- Updated [Figure 2-5](#)
- Updated [Figure 3-36](#), [Figure 3-39](#), and [Figure 3-40](#).
- Updated [Section 4.15, AutoSync Mode: Synchronizing Multiple ADCs at the Same Clock using Master and Slave Configuration](#).
- Updated [Section “Product Identification System”](#).

### Revision C (August 2016)

The following is the list of modifications:

- Updated availability of TFBGA package.
- Added [Figure 2-7](#), [Figure 2-8](#) and [Figure 2-9](#).
- Added [Section 4.15, AutoSync Mode: Synchronizing Multiple ADCs at the Same Clock using Master and Slave Configuration](#).

### Revision B (July 2015)

- Updated the [Features](#) list.
- Updated the [Functional Block Diagram](#).
- Updated the [Description](#) section.
- Updated and added notes in [Tables 1-2](#) and [1-1](#).
- Updated values and notes in [Tables 2-1](#) and [2-2](#).
- Updated value in [Figure 2-1](#).
- Updated note in [Section 3.0 “Typical Performance Curves”](#).
- Updated text title in [Figures 3-26](#) and [3-29](#).
- Updated text in [Section 4.0 “Theory of Operation”](#).
- Updated text in [Section 4.5.1 “Analog Input Driving Circuit”](#).
- Added new column to [Table 4-2](#).
- Added [Section 4.5.2.1 “SENSE Selection Vs. SNR/SFDR Performance”](#) and [Section 4.5.3.1 “Decoupling Circuits for REF1 and REF0 Pins”](#).
- Replaced text in [Section 4.5.3.1 “Decoupling Circuits for REF1 and REF0 Pins”](#).
- Updated values in [Figure 4-7](#).
- Added note after [Figure 4-7](#).
- Replaced the entire [Section 4.7 “ADC Clock Selection”](#).
- Updated text in [Section 4.8.1 “Fractional Delay](#)

### [Recovery for Dual- and Octal-Channel Modes”](#).

- Updated [Figure 4-11](#).
- Changed parameters and updated/added notes in [Tables 4-5](#), [4-6](#), [4-9](#), [4-10](#), [4-12](#), [4-13](#) and [4-14](#).
- Changed value in [Equation 4-6](#).
- Deleted Note in [Section 4.8.3 “Decimation Filters”](#).
- Added [Section 4.8.3.1 “Output Data Rate and Clock Phase Control When Decimation is Used”](#).
- Changed parameter in [Table 4-15](#) and bit names in [Tables 4-17](#), [4-19](#), [4-20](#).
- Replaced and added text and reorganized structure in [Section 4.8.4 “Digital Down-Conversion \(MCP37D11-200 only\)”](#).
- Replaced text in [Section 4.8.4.3 “Numerically Controlled Oscillator \(NCO\)”](#).
- Updated values in [Section 4.8.4.5 “NCO for fS/8 and fS/\(8xDER\)”](#).
- Updated parameters and notes in [Tables 4-16](#), [4-17](#), [4-18](#) and [4-19](#).
- Reorganized and added text to [Section 4.11 “Output Data format”](#) and [Section 4.12 “Digital Output”](#).
- Updated [Figure 4-25](#).
- Updated [Section 5.2 “Configuration Registers”](#).
- Updated [Table 5-3](#).
- Updated [Registers 5-1](#) to [5-3](#), [5-7](#), [5-8](#), [5-10](#), [5-11](#), [5-13](#), [5-22](#), [5-24](#), [5-25](#), [5-27](#), [5-28](#), [5-34](#), [5-35](#), [5-36](#), [5-37](#), [5-42](#), [5-43](#) to [5-46](#), [5-47](#), [5-63](#), [5-79](#) and [5-80](#).
- Deleted “Power Supply Rejection Ration” section from [Section 7.0 “Terminology”](#).
- Updated [Section “Product Identification System”](#).
- Minor typographical corrections.

### Revision A (October 2014)

- Original release of this document.

# MCP37211-200 AND MCP37D11-200

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NOTES:

# MCP37211-200 AND MCP37D11-200

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>PART NO.</u>	<u>/X/</u> <sup>(1)</sup>	<u>-XXX</u>	<u>X</u>	<u>/XX</u>	<b>Examples:</b>
Device	Tape and Reel Option	Sample Rate	Temperature Range	Package	
<b>Device:</b> MCP37211-200: 12-Bit Low-Power ADC with 8-Channel MUX MCP37D11-200: 12-Bit Low-Power ADC with 8-Channel MUX, Digital Down-Converter and CW Beamforming					a) MCP37211-200E/TE: 200 Msps, Extended temperature, 121LD TFBGA package
<b>Tape and Reel Option:</b> Blank = Standard packaging (tube or tray) T = Tape and Reel <sup>(1)</sup>					b) MCP37211T-200E/TE: 200 Msps, Tape and Reel, Extended temperature, 121LD TFBGA package
<b>Sample Rate:</b> 200 = 200 Msps					c) MCP37211-200I/TE: 200 Msps, Industrial temperature, 121LD TFBGA package
<b>Temperature Range:</b> E = -40°C to +125°C (Extended) I = -40°C to +85°C (Industrial)					d) MCP37211T-200I/TE: 200 Msps, Tape and Reel, Industrial temperature, 121LD TFBGA package
<b>Package:</b> TE = Ball Plastic Thin Profile Fine Pitch Ball Grid Array - 8x8x1.08 mm Body (TFBGA), 121-Lead TL = Terminal Very Thin Leadless Array Package - 9x9x0.9 mm Body (VTLA), 124-Lead					e) MCP37D11-200E/TE: 200 Msps, Extended temperature, 121LD TFBGA package
					f) MCP37D11T-200E/TE: 200 Msps, Tape and Reel, Extended temperature, 121LD TFBGA package
					g) MCP37D11-200I/TE: 200 Msps, Industrial temperature, 121LD TFBGA package
					h) MCP37D11T-200I/TE: 200 Msps, Tape and Reel, Industrial temperature, 121LD TFBGA package
					i) MCP37211-200I/TL: 200 Msps, Industrial temperature, 124LD VTLA package
					j) MCP37211T-200I/TL: 200 Msps, Tape and Reel, Industrial temperature, 124LD VTLA package
					k) MCP37D11-200I/TL: 200 Msps, Industrial temperature, 124LD VTLA package
					l) MCP37D11T-200I/TL: 200 Msps, Tape and Reel, Industrial temperature, 124LD VTLA package

**Note 1:** Tape and Reel identifier appears only in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

# MCP37211-200 AND MCP37D11-200

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NOTES:

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**Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as “unbreakable.”

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

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