

## Stand-alone USB Type-C<sup>TM</sup> Power Delivery 3.0 Controller

#### Highlights

- USB Type-C<sup>™ (1)</sup> Power Delivery (PD) Solution for
  - Source-only applications (UPD301B)
  - Sink-only, Dual Role Power, and Dual Role Data applications (UPD301C)
- Companion device for USB PD Software Framework (PSF) open source firmware stack
- · Fully Customizable software
- Standard Power Delivery power profiles (15/27/45/60/100W) supported with no software modification
- USB Power Delivery 3.0 compliant MAC
- USB Type-C<sup>™</sup> connector support with connection detection and control
- Integrated Analog Discrete Components Reduce Bill of Materials and Design Footprint
- Easily Supports up to 3 additional Power Delivery ports Port via UPD350 Add-on
- Commercial, Industrial, and Automotive Temperature Support

### **Target Applications**

- · Point-of-Sale Terminals
- · Charging Lockers
- IoT Products and Sensors
- Smart Speakers and Monitors
- Conference Systems
- Power Tools
- Multi-port Charging Docks
- · Automotive Rear Seat Charging Ports

### **Key Benefits**

- · Fully Customizable Power Delivery Firmware
  - Industry standard MPLABX development and programming environment
  - Supports all Standard Power Delivery profiles (15/27/45/60/100W) and custom profiles
  - Supports Dual Role Port (DRP) operation (UPD301C only)
  - Supports Alternate Mode operation
  - PSF software framework enables customized PD applications

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- 32-bit ARM Cortex-M0+ CPU
  - 64KB Flash, 8KB RAM
- Optional Two, Three, or Four Port Solution via External UPD350
  - SPI for External UPD350 Communication
  - Power Delivery Firmware Controls All Ports
- Integrated Analog Discrete Components
  - VCONN FETs with Rp/Rd Switching
  - Dead Battery Rd termination (UPD301C only)
  - Programmable Current Sense for Overcurrent Conditions
  - · Voltage Sense for Overvoltage Conditions
- USB Power Delivery MAC
  - Compliant with USB Power Delivery Specification Revision 3.0
  - Power Delivery Packet Framing
  - CRC Checking/Generation
  - 4B/5B Encoding/Decoding
  - BMC Encoding/Decoding
  - EOP/SOP Generation for PD Frames
  - SOP Detection and SOP Header Processing
  - Separate RX/TX FIFOs
  - Automatic GoodCRC Message Generation
  - Automatic Retry Generation
  - Error Handling
  - Low Standby Power Support
- USB Type-C Cable Detect Logic
  - Auto Cable Attach & Orientation Detection
  - Routes Baseband Communication to Respective CC Pin per Detected Orientation
  - VCONN Supply Control for Active Cable
  - Charging Current Capability Detection
- Power and I/Os
  - Integrated 1.8V Voltage Regulator
  - 10 Configurable General Purpose I/O Pins
- Package
  - 40-VQFN (6.0mm x 6.0mm)
- Environmental
  - Commercial Temperature Range (0°C to +70°C)
  - Industrial / AEC-Q100 Automotive Grade 3 Temperature Range (-40°C to +85°C)

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## 1.0 PREFACE

## 1.1 Glossary of Terms

### TABLE 1-1: GLOSSARY OF TERMS

Term	Definition
BCI	Baseband CC Interface
Billboard	USB Billboard Device. A required USB device class for UFPs which support Alternate Modes in order to provide product information to the USB Host.
BIST	Built-In Self Test
BMC	Bi-phase Mark Coding
Byte	8-bits
CC	Generic reference to USB Type-C <sup>™</sup> Cable / Connector CC1/CC2 pins
CSR	Control and Status Register
DFP	Downstream Facing Port (USB Type-C™ Specification definition)
DP	DisplayPort (a VESA standard interface)
DRP	Dual-Role Power
ESD	Electro-Static Discharge
FIFO	First In First Out buffer
GPIO	General Purpose Input/Output
Host	External system (Includes processor, application software, etc.)
НВМ	Human Body Model (Simulates ESD from humans)
HS	High-Speed
LDO	Linear Drop-Out regulator
MAC	Media Access Controller
Microchip	Microchip Technology Incorporated
N/A	Not Applicable
NC	No Connect (pin)
OCS	Over-Current Sense
PD / UPD	USB Power Delivery
PDO	Power Delivery Object (USB PD Specification definition) PDOs enable the port to indicate its Port Partner supported combinations of Voltage/Current or Power as well as the type of supply (Fixed, Variable, Battery) in Source Role or Sink Role.
PIO	General Purpose I/O
POR	Power-On Reset
Port Partner	Remote port which is connected to the UPD301B/C's local port
PRBS	Pseudo Random Binary Sequence
Source Role	USB Type-C port is sinking power from its Port Partner
Source-only Operation	Operation exclusively in USB Type-C / Power Delivery Source Role as defined in the USB Type-C and Power-Delivery specifications. In this mode of operation, USB Type-C Dual-Role Power Operation is not supported and there is no support for USB Power Role Swap.
SPI	Serial Peripheral Interface
SS	SuperSpeed
Stand-alone Mode	Chip operation without the control or configuration by an external MCU. Policy is defined locally by the UPD301B/C firmware. Configuration is achieved by use of configuration straps.
UFP	Upstream Facing Port (USB Type-C™ Specification definition)
USB	Universal Serial Bus

Term	Definition
USB Power Delivery Operation	Port is operating using USB Power Delivery protocols in conformance to the USB PD Specification.
USB Power Role Swap	Message sequence as defined in the USB PD Specification, enabling a transition between Source Role and Sink Role during USB Power Delivery Operation
USB Type-C™	USB Type-C™ Cable / Connector

#### TABLE 1-1: GLOSSARY OF TERMS (CONTINUED)

#### 1.2 Buffer Types

#### TABLE 1-2:BUFFER TYPES

Buffer Type	Description
I	Input
IS	Schmitt-triggered input
O2	Output with 2 mA sink and 2 mA source
OD2	Open-drain output with 2 mA sink and 2 mA source
O8	Output with 8 mA sink and 8 mA source
PD	200kΩ (typical) internal pull-down.
	<b>Note:</b> Internal pull-down resistors prevent unconnected inputs from floating. Do not rely on internal resistors to drive signals external to the device. When connected to a load that must be pulled low, an external resistor must be added.
AI	Analog input
AO	Analog output
AIO	Analog bidirectional
Р	Power pin

**Note:** Refer to Section 5.5, "DC Characteristics," on page 33 for the electrical characteristics of the various buffers.

#### 1.3 References

- Microchip UPD350 Datasheet: <u>https://www.microchip.com/wwwproducts/en/UPD350</u>
- Microchip SAM D20 Datasheet: <u>http://ww1.microchip.com/downloads/en/DeviceDoc/SAM\_D20\_%20Family\_Datasheet\_DS60001504C.pdf</u>
- USB Power Delivery: https://www.usb.org/document-library/usb-power-delivery.
- USB Type-C™ Specification: i<u>https://www.usb.org/document-library/usb-type-cr-cable-and-connector-specifica-</u> tion-revision-14-march-29-2019

## 2.0 INTRODUCTION

### 2.1 General Description

The UPD301B/C is a stand-alone, small form factor USB Type-C<sup>™</sup> Power Delivery (PD) Port Controller designed to adhere to the USB Type-C<sup>™</sup> Cable and Connector Specification and USB Power Delivery 3.0 Specification. The UPD301B/C provides stand-alone operation for a wide range of PD applications, enabling cable plug orientation and detection for a USB Type-C receptacle, and implementing baseband communication with a partner USB Type-C device via the integrated USB Power Delivery 3.0 MAC.

The UPD301B/C is an integrated PD solution with SAMD20 (32-bit ARM Cortex-M0+) microcontroller and UPD350 PD MAC/PHY functionality. The embedded 32-bit ARM Cortex-M0+ can execute the USB Power Delivery Framework (PSF) Power Delivery stack. Optionally, a second, third, or fourth PD port is supported via SPI connection of additional external Microchip UPD350 devices. The UPD301B/C devices are shipped blank and require programming with compiled application specific code before operation.

Additionally, the UPD301B/C integrates many of the analog discrete components required for USB Type-C PD applications, including two VCONN FETs with Rp/Rd switching and current/voltage sense circuitry for over-voltage/current detection. By integrating the PD firmware and many of the analog discrete components required for USB Type-C PD applications, the UPD301B/C provides a low cost, stand-alone, fast time-to-market solution for consumer, industrial, and automotive applications.

The Microchip UPD301B/C family includes the following devices:

- UPD301B
- UPD301C

The UPD301B/C is available in commercial (0°C to +70°C) and industrial/automotive grade 3 (-40°C to +85°C) temperature ranges. The UPD301B/C is available with dead battery support enabled or disabled in hardware. Device specific features that do not pertain to the entire UPD301B/C family are called out independently throughout this document. Table 2-1 provides a summary of the feature differences between family members. For ordering information, refer to the Product Identification System on page 43.

Part Number	Package	Dead Battery Rd Terminations	DRP & Sink-Only Application Support	Source-Only Application Support	Customizable PD Software	32-bit ARM Cortex-M0+ CPU	USB Power Delivery MAC	USB Type-C Cable Detect Logic	Commercial -0º To +70ºC	AEC-Q100 -40° To +85°C
UPD301B	40-VQFN			х	x	x	х	х	x	x
UPD301C	40-VQFN	X	Х		X	X	X	Х	X	X

#### TABLE 2-1:UPD301B/C FAMILY FEATURE MATRIX

#### 2.2 USB Power Delivery Software Framework

The PSF firmware stack allows for a wide range of USB Power Delivery applications, including but not limited to: Single or Multi-Port source Only applications, Bus-Powered Sink applications, Battery-Powered Sink applications, and Dual Role Data / Dual Role Power applications such as PD-based docking stations or PD-based dongles.

The PSF firmware stack is continuously deployed. Not all features that are able to be supported by the UPD301B/C device are necessarily supported by PSF. The supported features may be expanded over time. The PSF firmware stack can be downloaded from the UPD301B/C product page. Refer to the UPD301B/C product page and PSF Online code repository for details on the currently supported feature set and future development road-map. Additional feature development may be requested through Microchip support channels.

#### 2.3 Example Applications

The UPD301B/C has been designed for multiple applications, including:

#### • UPD301B

- Source-Only Applications (E.G., Charging Ports) (UPD301B Only)
- Two-Port, Three-Port, and Four-Port Source-Only Applications (E.G., Automotive Rear Seat Charging) (UPD301B Only)
- UPD301C
  - Bus-Powered or Battery Powered Sink-Only Applications (UPD301C Only)
  - Dual Role Power/Data Application (5V Source, High Voltage Sink) (UPD301C Only)
  - Dual Role Power/Data Application (High Voltage Source, 5V @ 0A Sink) (UPD301C Only)
  - 2-Port Dual Role Power/Data Application 'Charge-Through Adapter' (UPD301C Only)

**Note:** Single-Port Source, Single-Port Sink, and Dual-Port Source modes are the only supported modes of operation. Dual-Port Sink and Source + Sink modes are not supported without custom firmware.

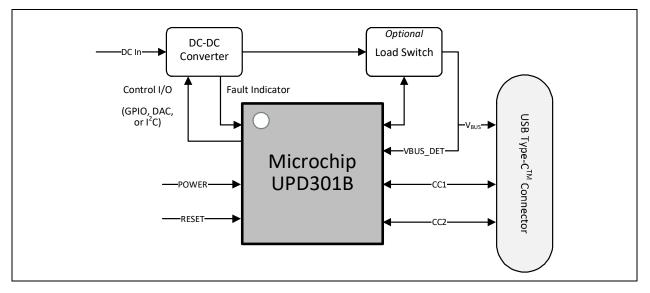
#### 2.3.1 SOURCE-ONLY APPLICATIONS (E.G., CHARGING PORTS) (UPD301B ONLY)

The simplest UPD301B application is a power source (Source-Only), as shown in Figure 2-1. The UPD301B control I/O configures the DC-DC converter, selecting the output voltage, and controls the load switch to regulate and protect the output voltage. The load switch can also be replaced by discrete FETs and over-current / over-voltage protection circuits.

Additional notes on Source-Only Charging Port Applications:

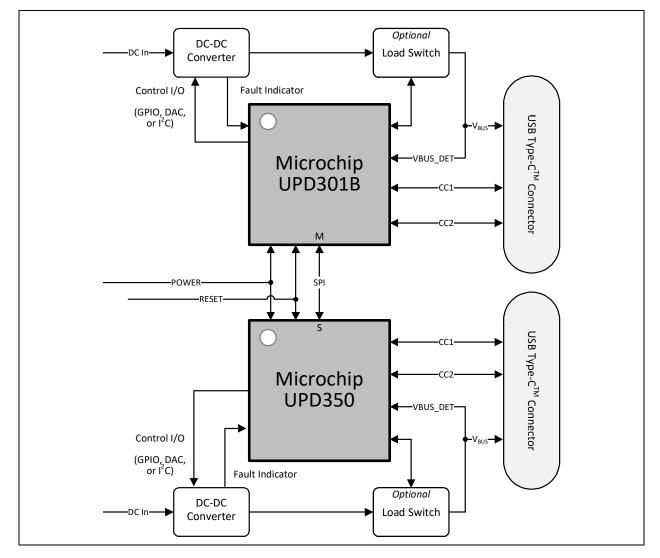
- Supporting USB data is not required for a Charging Port.
- A Power Source Load Switch is optional for Source-Only ports. Source-Only ports are permitted to maintain a large bulk capacitance on VBUS at all times, even when the port is in the detached state.
- USB3 operation is optional for PD docking ports.

#### FIGURE 2-1: SYSTEM BLOCK DIAGRAM - SOURCE-ONLY APPLICATION



#### 2.3.2 TWO-PORT, THREE-PORT, AND FOUR-PORT SOURCE-ONLY APPLICATIONS (E.G., AUTOMOTIVE REAR SEAT CHARGING) (UPD301B ONLY)

Some applications, such as a automotive rear seat charging port, may need multiple USB Type-C<sup>™</sup> power delivery ports. These ports can be implemented by connecting a UPD301B and a UPD350 via the SPI interface, as shown in Figure 2-2. The UPD301B will execute the stack for the UPD350. The two-port implementation supports dynamic power allocation (e.g., go-to power min based on an external input).



#### FIGURE 2-2: SYSTEM BLOCK DIAGRAM - TWO-PORT APPLICATION

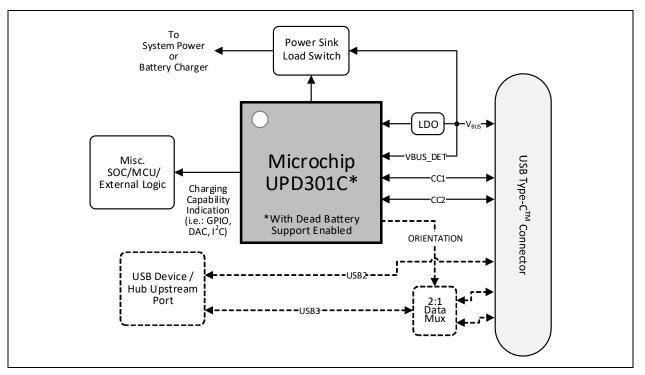
#### 2.3.3 BUS-POWERED OR BATTERY POWERED SINK-ONLY APPLICATIONS (UPD301C ONLY)

An example of a bus powered power sink (Sink-Only) application is shown in Figure 2-3. A bus powered Sink-Only application derives all power from the upstream VBUS connection and does not have any other power source. The UPD301C device with dead battery support should be selected for all Sink-Only devices. The dead battery Rp terminations allow the Sink-Only device to be detected and powered from an attached DFP port when connected in an unpowered state.

Additional notes on Bus-Power or Battery Powered Sink-Only Applications:

- USB data support is optional.
- If USB3 data is supported, a 2:1 multiplexer may be required to handle Type-C cable insertion reversibility. Device controllers and hubs specifically designed to support USB Type-C may also integrate the reversibility functionality.
- USB Alternate Modes may also be supported in Sink-Only applications.
- · DisplayPort support is optional for mobile device ports.
- USB2 signals may be connected directly to the Type-C connector; a multiplexer is not necessary as long as the USB2 signal layout is carefully managed to keep branches at a minimum.

#### FIGURE 2-3: SYSTEM BLOCK DIAGRAM - SINK-ONLY APPLICATION



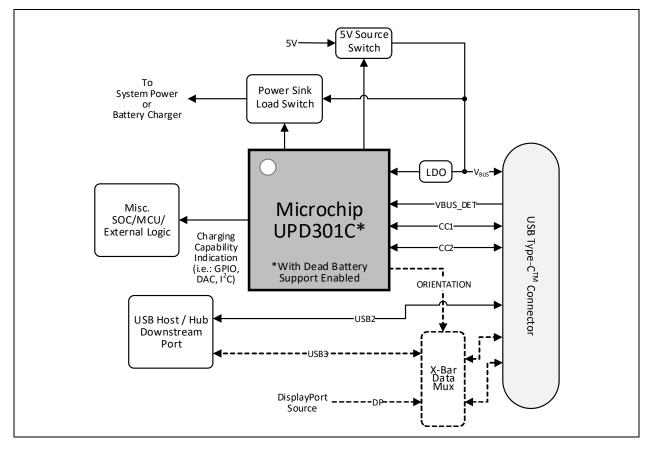
## 2.3.4 DUAL ROLE POWER/DATA APPLICATION (5V SOURCE, HIGH VOLTAGE SINK) (UPD301C ONLY)

An example of a mobile device port is shown in Figure 2-4. In this example a mobile device, such as a notebook, smartphone, or tablet, is capable of operating as a USB host (and device if the processor is capable of OTG operation), receiving a charge, and driving an external video display through a single Type-C connection. A cross-bar switch is shown for routing DisplayPort Alternate Mode and USB3 data to the connector, allowing port expansion and video display.

Additional notes on Dual Role Power/Data (5V Source, High Voltage Sink) Applications:

- A typical mobile device will limit the power sourcing capability to 5V only in order to preserve battery life. This is
  not explicitly required and a mobile device may optionally provide up to the maximum 100W capability if the system supports it.
- When the port is operating as a power sink/data UFP, the USB Host / Hub Downstream Port block is not required to support USB Device / Hub Upstream Port operation.
- A 5V Source Load Switch device must be tolerant of the maximum supported sinking voltage.
- · USB3 operation is optional for mobile device ports.
- DisplayPort support is optional for mobile device ports.
- · If both USB3 and DisplayPort operation are omitted, the crossbar data switch is not necessary.
- USB2 signals may be connected directly to the Type-C connector; a multiplexer is not necessary as long as the USB2 signal layout is carefully managed to keep branches to a minimum.

#### FIGURE 2-4: SYSTEM BLOCK DIAGRAM - DUAL ROLE POWER/DATA APPLICATION (5V SOURCE, HIGH VOLTAGE SINK)



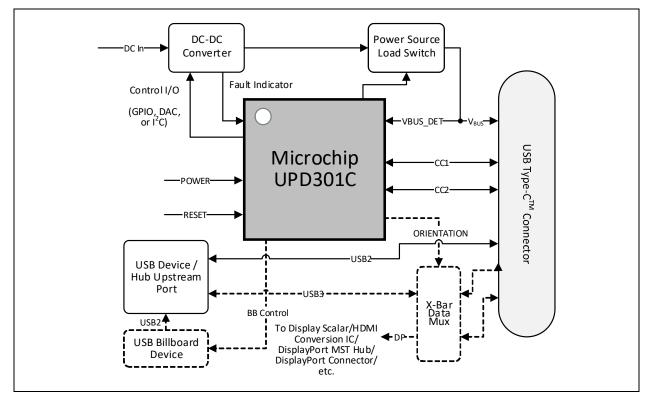
## 2.3.5 DUAL ROLE POWER/DATA APPLICATION (HIGH VOLTAGE SOURCE, 5V @ 0A SINK) (UPD301C ONLY)

An example of a PD docking port is shown in Figure 2-5. In this example a battery powered mobile device, such as a notebook, smart-phone, or tablet may connect to the docking PD port and receive a charge, access the USB device tree, and drive an external video display through a single Type-C connection. A cross-bar switch is shown for routing DisplayPort Alternate Mode and USB3 data to the connector, allowing port expansion and video display.

Additional notes on Dual Role Power/Data (High Voltage Source, 5V @ 0A Sink) Applications:

- While a PD docking port may technically resolve into a power sink role, a typical PD dock will not attempt to sink any power while operating as a power sink. This type of operation may be referred to a "5V @ 0A Sink".
- When the port is operating as a power sink/data UFP, the USB Device/Hub Upstream Port block is not required to support USB Host/Hub Downstream Port operation.
- A Power Source Load Switch device is necessary, as the DC-DC converters bulk capacitance must be isolated from VBUS when the port is operating as a 5V @ 0A Sink.
- · USB3 operation is optional for PD docking ports.
- · DisplayPort support is optional for PD docking ports.
- If an Alternate Mode such as DisplayPort is supported, a Billboard device must also be included within the system and be exposed following an Alternate Mode negotiation failure (A Billboard device may optionally be connected at all times and communicate a successful Alternate Mode connection, but this is optional).
- · If both USB3 and DisplayPort operation are omitted, the crossbar data switch is not necessary.
- USB2 signals may be connected directly to the Type-C connector; a multiplexer is not necessary as long as the USB2 signal layout is carefully managed to keep branches to a minimum.

## FIGURE 2-5: SYSTEM BLOCK DIAGRAM - DUAL ROLE POWER/DATA APPLICATION (HIGH VOLTAGE SOURCE, 5V @ 0A SINK)



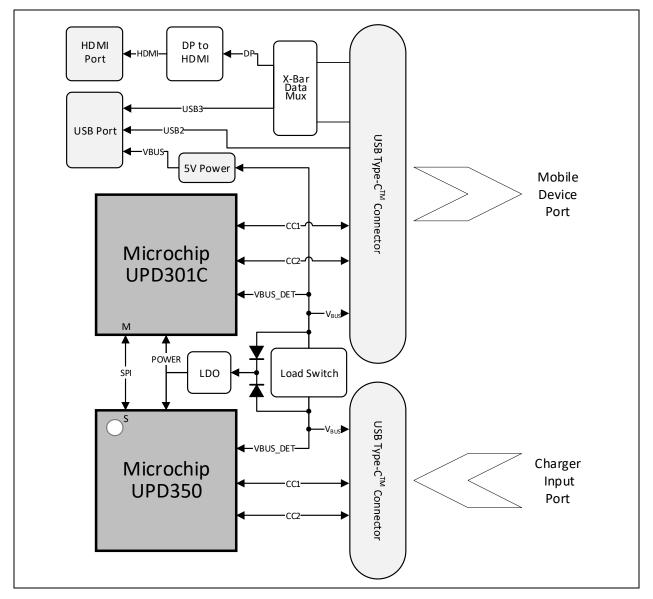
## 2.3.6 2-PORT DUAL ROLE POWER/DATA APPLICATION 'CHARGE-THROUGH ADAPTER' (UPD301C ONLY)

An example of a charge through adapter/mobile dock device is shown in Figure 2-6. In this example, the 'Charger Input Port' may pass a high voltage power profile through the system to an attached mobile device. If a charger is not inserted into the 'Charger Input Port'. then the mobile device may power the adapter with 5V power.

A cross-bar switch is shown for routing DisplayPort Alternate Mode and USB3 data to the connector, allowing port expansion and video display.

An LDO is shown connected to a power OR circuit to ensure power to the system is available regardless of which Type--C port is supplying power to the system. The LDO should be selected to operate at the maximum supported charge-through voltage.

#### FIGURE 2-6: SYSTEM BLOCK DIAGRAM - 2-PORT DUAL ROLE POWER/DATA APPLICATION 'CHARGE-THROUGH ADAPTER'

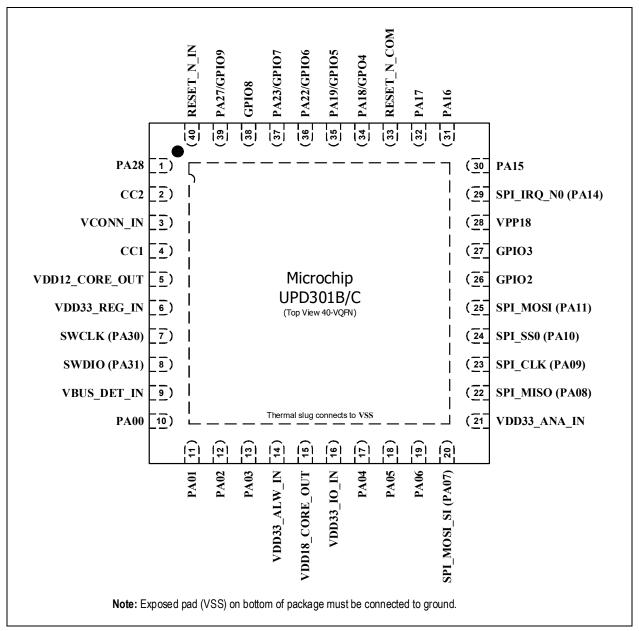


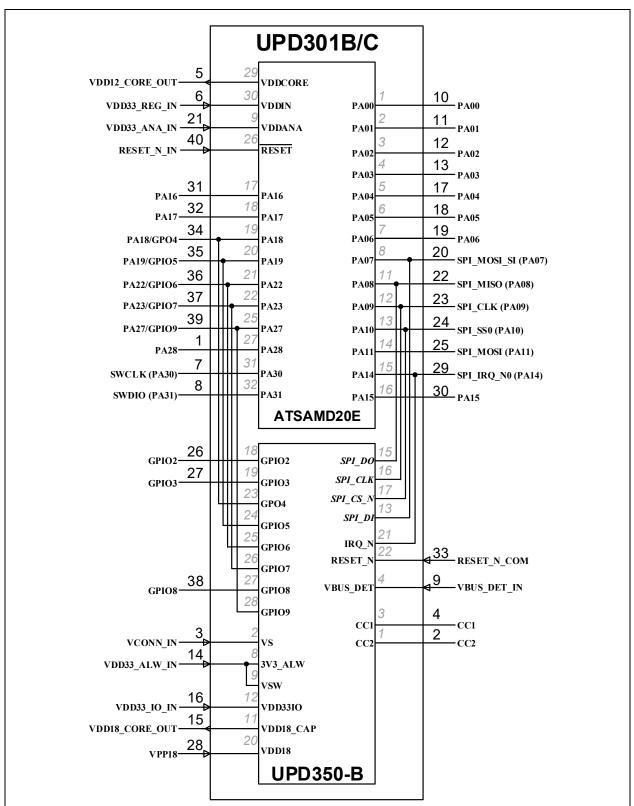
## 3.0 PIN DESCRIPTIONS AND CONFIGURATION

#### 3.1 Pin Assignments

The device pin diagram for the UPD301B/C can be seen in Figure 3-1. Table 3-1 provides a UPD301B/C pin assignment table. The internal bonding diagram (simplified) is shown in Figure 3-2. Pin descriptions are provided in Section 3.2, "Pin Descriptions".







#### FIGURE 3-2: SIMPLIFIED INTERNAL BONDING DIAGRAM

Pin	Pin Name	Bond to SAMD20E	Bond to UPD350-B
1	PA28	PA28	-
2	CC2	-	CC2
3	VCONN_IN	-	VS
4	CC1	-	CC1
5	VDD12_CORE_OUT	VDDCORE	-
6	VDD33_REG_IN	VDDIN	-
7	SWCLK (PA30)	PA30	-
8	SWDIO (PA31)	PA31	-
9	VBUS_DET_IN	-	VBUS_DET
10	PA00	PA00	-
11	PA01	PA01	-
12	PA02	PA02	-
13	PA03	PA03	-
14	VDD33_ALW_IN	-	3V3_ALW & VSW
15	VDD18_CORE_OUT	-	VDD18_CAP
16	VDD33_IO_IN	-	VDD33IO
17	PA04	PA04	-
18	PA05	PA05	-
19	PA06	PA06	-
20	SPI_MOSI_SI (PA07)	PA07	SPI_DI
21	VDD33_ANA_IN	VDDANA	-
22	SPI_MISO (PA08)	PA08	SPI_DO
23	SPI_CLK(PA09)	PA09	SPI_CLK
24	SPI_SS0 (PA10)	PA10	SPI_CS_N
25	SPI_MOSI (PA11)	PA11	-
26	GPIO2	-	GPIO2
27	GPIO3	-	GPIO3
28	VPP18	-	VDD18
29	SPI_IRQ_N0 (PA14)	PA14	IRQ_N
30	PA15	PA15	-
31	PA16	PA16	-
32	PA17	PA17	-
33	RESET_N_COM	-	RESET_N
34	PA18/GPO4 (Note 1)	PA18	GPO4
35	PA19/GPIO5 (Note 1)	PA19	GPIO5
36	PA22/GPIO6 (Note 1)	PA22	GPIO6
37	PA23/GPIO7 (Note 1)	PA23	GPIO7
38	GPIO8	-	GPIO8
39	PA27/GPIO9 (Note 1)	PA27	GPIO9
40	RESET_N_IN	RESET	-

TABLE 3-1: UPD301B/C PIN ASSIGNMENTS

**Note 1:** This pin is double bonded to the internal SAMD20E and UPD301B/C and should not be simultaneously driven by both sources under normal use cases.

### 3.2 Pin Descriptions

This sections details the functions of the various device signals.

#### TABLE 3-2: PIN DESCRIPTIONS

Name	Symbol	Buffer Type	Description
		USB	Type-C™
Configuration Channel 1	CC1	AIO	Configuration Channel (CC) used in the discovery, configu- ration and management of connections across a USB Type-C cable. ( <i>CC1 in UPD350</i> )
Configuration Channel 2	CC2	AIO	Configuration Channel (CC) used in the discovery, configu- ration and management of connections across a USB Type-C cable. ( <i>CC2 in UPD350</i> )
VBUS Detection	VBUS_DET_IN	AIO	Scaled down version of VBUS input used for VBUS detec- tion. Tie this signal to VBUS via a resistor divider. (VBUS_DET in UPD350)
		SPI	Interface
SPI Clock	SPI_CLK	IS	SPI clock. The maximum supported SPI clock frequency is 8 MHz. (SPI_CLK in UPD350 and PA09 in SAMD20)
SPI Data Master In / Slave Out	SPI_MISO	I/O8	SPI data master in, slave out. (SPI_DO in UPD350 and PA08 in SAMD20)
SPI Data Master Out / Slave In	SPI_MOSI	02	SPI data master out / slave in. This pin must be connected to SPI_MOSI_SI for proper operation. (PA11 in SAMD20)
SPI Data Slave In	SPI_MOSI_SI	IS	SPI data slave in. This pin must be connected to <b>SPI_MOSI</b> for proper operation. (SPI_DI in UPD350 and PA07 in SAMD20)
SPI Chip Enable 0	SPI_SS0	IS	Active low SPI chip enable input for UPD301B/C. (SPI_CS_N in UPD350 and PA10 in SAMD20)
SPI Interrupt 0	SPI_IRQ_N0	Ι	SPI interrupt indicating request for service from optional external UPD350. ( <i>IRQ_N in UPD350 and PA14 in SAMD20</i> )
		Serial Wire	Debug Interface
Serial Wire Debug Clock	SWCLK	IS	Serial wire debug clock. (PA30 in SAMD20)
Serial Wire Debug Data	SWDIO	I/O	Serial wire debug bidirectional data. (PA31 in SAMD20)
		Misc	cellaneous
System Reset Input	RESET_N_IN	Ι	Active low SAMD20 system reset input. This reset is used for reset of the SAMD20 portion of the UPD301B/C by a companion MCU. ( <i>RESET in SAMD20</i> )
System Reset Common	RESET_N_COM	IS	Active low UPD350 system reset input. This reset is used for reset of the UPD350 portion of the UPD301B/C by a companion MCU. ( <i>RESET_N in UPD350</i> )
		General	Purpose I/Os
Misc. SAMD20E I/O	PA00, PA01, PA02, PA03, PA04, PA05, PA06, PA15, PA16, PA17, PA18, PA19, PA22, PA23, PA27, PA28	I/O	Refer to SAMD20E Datasheet for pin function, peripheral detail, and characteristics. ( <i>PAxx in SAMD20</i> ) Note: PA18, PA19, PA22, PA23, and PA27 are multiplexed with UPD350 GPIOs. Refer to Table 3-1

Name	Symbol	Buffer Type	Description
UPD350 GPIO	GPIO2, GPIO3, GPO4, GPIO5, GPIO6, GPIO7, GPIO8, GPIO9	I/O	Refer to UPD350 Datasheet for pin function, peripheral detail, and characteristics. ( <i>GPIOx, GPO4 in UPD350</i> )
			Note: GPO4, GPIO5, GPIO6, GPIO7, and GPIO9 are multiplexed with SAMD20 GPIOs. Refer to Table 3-1 for more information.
		Powe	er/Ground
+5V Port Power Switch Input	VCONN_IN	Р	+5V VCONN FET power source. (VS in UPD350)
+3.3V I/O Power Supply Input	VDD33_IO_IN	Ρ	+3.3V I/O power supply input. (VDD33IO in UPD350)
+3.3V Analog Power Supply Input	VDD33_ANA_IN	Р	+3.3V analog power supply input. ( <i>VDDANA in SAMD20</i> )
+3.3V Always Supply Input	VDD33_ALW_IN	Ρ	+3.3V always supply input. (3V3_ALW & VSW in UPD350) Note: This pin must be connect to a 2.2 uF capacitor to ground.
+3.3V Regulator Power Supply Input	VDD33_REG_IN	Р	+3.3V regulator power supply input. (VDDIN in SAMD20)
+1.8V Core Voltage Power Supply Input	VPP18	Р	+1.8V core voltage power supply input. (VDD18 in UPD350)
+1.8V Digital Core Power Supply Output	VDD18_CORE_OUT	Р	+1.8V digital core power supply output. This signal must be connected to a 1uF capacitor to ground for proper operation. ( <i>VDD18_CAP in UPD350</i> )
+1.2V Core Power Supply Output	VDD12_CORE_OUT	Р	+1.2V core power supply output. This signal must be con- nected to a 1uF capacitor to ground for proper operation. (VDDCORE in SAMD20)
Ground	VSS	Р	Ground pins.

#### TABLE 3-2: PIN DESCRIPTIONS (CONTINUED)

## 4.0 FUNCTIONAL DESCRIPTIONS

This section provides functional descriptions of the following:

- Serial Peripheral Interface (SPI)
- Power States
- Cable Plug Orientation and Detection
- Baseband CC Interface (BCI)
- Power Delivery MAC
- Supported Power Delivery (PD) Functionality

#### 4.1 Serial Peripheral Interface (SPI)

The UPD301B/C integrates a SPI master/slave controller which includes the following features:

- • Full-duplex, four-wire interface (SPI\_MISO, SPI\_MOSI, SPI\_SCK, SPI\_SS)
- • Single-buffered transmitter, double-buffered receiver
- · · Supports all four SPI modes of operation
- · · Single data direction operation allows alternate function on SPI\_MISO or SPI\_MOSI pin
- • Selectable LSB- or MSB-first data transfer
- • Master operation:
  - - Serial clock speed, f<sub>SCK</sub>=1/t<sub>SCK</sub>(Note 4-1)
  - - 8-bit clock generator
- · · Slave operation:
  - - Serial clock speed, f<sub>SCK</sub>=1/t<sub>SSCK</sub>(Note 4-1)
  - - Optional 8-bit address match operation
  - - Operation in all sleep modes

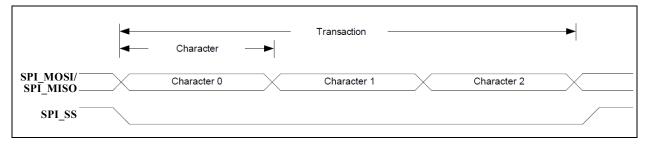
#### Note 4-1 For t<sub>SCK</sub> and t<sub>SSCK</sub> values, refer to Section 5.6.2, "SPI Timing"

The SPI is a high-speed synchronous data transfer interface which allows high-speed communication between the device and peripheral devices. The SPI can operate as a master or slave. As a master, the SPI initiates and controls all data transactions. The SPI is single buffered for transmitting and double buffered for receiving.

When transmitting data, a Data register is loaded with the next character to be transmitted during the current transmission. When receiving, the data is transferred to the two-level receive buffer, and the receiver is ready for a new character.

The SPI transaction format is shown in Figure 4-1. Each transaction can contain one or more characters. The character size is configurable, and can be either 8 or 9 bits.

#### FIGURE 4-1: SPI TRANSACTION FORMAT



The SPI master pulls the slave select line (SPI\_SS) of the desired slave low to initiate a transaction. The master and slave prepare data to send via their respective shift registers, and the master generates the serial clock on the SPI\_SCK line.

Data is always shifted from master to slave on the Master Output Slave Input line (SPI\_MOSI); data is shifted from slave to master on the Master Input Slave Output line (SPI\_MISO).

Each time character is shifted out from the master, a character will be shifted out from the slave simultaneously. To signal the end of a transaction, the master will pull the SPI\_SS line high.

#### 4.2 Power States

The device supports the following power states, as defined in their respective sub-sections:

- SLEEP
- HIBERNATE
- STANDBY
- ATTACHED IDLE (FRS Enabled)
- ATTACHED IDLE (FRS Disabled)
- ACTIVE

#### 4.2.1 SLEEP

This is the lowest power state of the device. The SLEEP state is entered via assertion of the **PWR\_DN** pin. Virtually all of the device is powered off in this mode with minimal circuity in the 3.3V domain to detect deassertion of **PWR\_DN**.

This mode is intended to minimize power consumption when the device is not being used in battery powered applications. In these applications, a wake up event such as a button press, can cause the host CPU to deassert **PWR\_DN**.

#### 4.2.2 HIBERNATE

In this state, the port is disabled by the USB PD firmware and the **PWR\_DN** pin is low. Attach detection is disabled due to CC terminations in the high-impedance state.

#### 4.2.3 STANDBY

STANDBY is the lowest power functional state of the device. The majority of the device is powered off in this state. The internal CC comparator and 20 KHz oscillator are enabled in this state as well as requisite analog components (1.8V LDO, PORs, Biases, etc).

The CC lines are constantly monitored for an attach condition which shall result in an interrupt assertion to the host. If an attachment has been made, this state can detect a change in the partner's advertisement as well as a detach.

STANDBY is the power state that the UPD301B/C device will be in when in USB Type-C<sup>™</sup> Unattached.SRC.

#### 4.2.4 ATTACHED IDLE (FRS ENABLED)

In this state, a USB Type-C<sup>™</sup> device is connected and the USB PD bus is idle (no USB packets in transit). The CC signals are constantly being monitored for packet transmission and Fast Role Swap (FRS) signal detection is enabled.

#### 4.2.5 ATTACHED IDLE (FRS DISABLED)

In this state, a USB Type-C<sup>™</sup> device is connected and the USB PD bus is idle (no USB packets in transit). The CC signals are constantly being monitored for packet transmission and Fast Role Swap (FRS) signal detection is disabled.

#### 4.2.6 ACTIVE

This state defines the condition of the device after an attachment occurred. In this state, Power Delivery communication is supported. This state is also used for any condition in which the 48 MHz Relaxation Oscillator must be enabled, such as when it is desired to debounce a GPIO within the micro-second range.

When transmitting a Power Delivery packet, an additional 5 mA may be consumed. Additional power consumption results from enabling the OCS comparator, VBUS comparator and other modules. When VCONN FETs are enabled, there is an additional 70 mW of power consumption.

This section details the functions that control and monitor the CC pins, monitor the VBUS\_DET pin, control the VCONN FETs, and sample the CFG\_SEL pin.

### 4.3 Cable Plug Orientation and Detection

#### 4.3.1 CC COMPARATOR

The device integrates a comparator and DAC circuit to implement Type-C attach and detach functions. It supports up to eight programmable thresholds for attach detection between UFP and DFP. When operating as a UFP, the device supports detecting changes in the DFP's advertised thresholds to determine current sourcing capability. The default nominal values for the thresholds detected by the CC comparators are:

- 0.20 V
- 0.40 V
- 0.66 V
- 0.80 V
- 1.23 V
- 1.60 V
- 2.60 V
- 3.0 V Proprietary Mode

Parameter	Threshold CSR	Description	Min	Тур	Max
DFP_ACT_DEF	CC_THR0	Detecting an active cable when configured as DFP and advertising default USB current.		0.20 V	
UFP_DFP_DEF	CC_THR0	Detecting DFP attach when configured as UFP and DFP is advertising default USB current.		0.20 V	
DFP_ACT_1A5	CC_THR1	Detecting an active cable when configured as DFP and advertising 1.5A.		0.40 V	
UFP_DFP_1A5	CC_THR2	Detecting DFP attach when configured as UFP and DFP is advertising 1.5A.		0.66 V	
DFP_ACT_3A0	CC_THR3	Detecting an active cable when configured as DFP and advertising 3.0A.		0.80 V	
UFP_DFP_3A0	CC_THR4	Detecting DFP attach when configured as UFP and DFP is advertising 3.0A.		1.23 V	
DFP_UFP_DEF	CC_THR5	Detecting UFP attach when configured as DFP advertising default USB current.		1.60 V	
DFP_UFP_1A5	CC_THR5	Detecting UFP attach when configured as DFP advertising 1.5A.		1.60 V	
DFP_UFP_3A0	CC_THR6	Detecting UFP attach when configured as DFP advertising 3.0A.		2.60 V	

#### TABLE 4-1: CABLE DETECT SUMMARY

The following tables summarizes the expected thresholds to be matched for various configurations.

CC State	CC THR0	CC THR1	CC THR2	CC THR3	CC THR4	CC THR5	CC THR6	CC THR7
Advertise Default USB Current and connected to powered cable	0	0	0	0	0	0	0	0
Advertise 1.5 A and connected to powered cable	0	0	0	0	0	0	0	0
Advertise 3.0 A and connected to powered cable	0	0	0	0	0	0	0	0
Advertise Default USB Current and connected to UFP	1	0	0	0	0	0	0	0
Advertise 1.5 A and connected to UFP	0	1	0	0	0	0	0	0
Advertise 3.0 A and connected to UFP	0	0	0	1	0	0	0	0
Advertise Default USB Current and no connect (vOpen)	1	0	0	0	0	1	0	0
Advertise 1.5 A and no connect (vOpen)	0	1	0	0	0	1	0	0
Advertise 3.0 A and no connect (vOpen)	0	0	0	1	0	0	1	0
Proprietary Mode and no connect (vOpen)	0	0	0	0	0	0	0	1

#### TABLE 4-2:DFP CC MATCH SUMMARY

#### TABLE 4-3: UFP CC MATCH SUMMARY

CC State	CC THR0	CC_ THR1	CC THR2	CC THR3	CC THR4	CC THR5	CC THR6	CC THR7
Powered cable detected.	0	0	0	0	0	0	0	0
No Connect (SNK.Open)	0	0	0	0	0	0	0	0
DFP Connected and advertising default USB current	1	0	0	0	0	0	0	0
DFP Connected and advertising 1.5 A	1	0	1	0	0	0	0	0
DFP Connected and advertising 3.0 A	1	0	1	0	1	0	0	0
DFP Connected and advertising pro- prietary current	1	0	1	0	1	0	0	1

#### 4.3.2 DFP OPERATION

The device implements current sources to advertise current charging capabilities on both CC pins when operating as a DFP.

When a UFP connection is established, the current driven across the CC pins creates a voltage across the UFP's Rd pull-down that can be detected by the integrated CC comparator. The voltages monitored are summarized in Table 4-4. When connected to an active cable, an alternative pull-down (Ra) appears on the CC pin.

The DFP also integrates two 5V FETs for implementing the VCONN function. This is further discussed in Section 4.3.9, "VCONN Operation".

CC1	CC2	Connection State	CC Comparator State	VBUS	VCONN
Open	Open	Nothing Attached	Monitor both CC pins for attach	Off	Off
Rd	Open	UFP Attached	Monitor CC1 for detach	On	Off
Open	Rd	UFP Attached	Monitor CC2 for detach	On	Off
Ra	Open	Powered Cable, No UFP attached	Monitor CC2 for UFP attach. Monitor CC1 for cable detach.	Off	Off
Open	Ra	Powered Cable, No UFP attached	Monitor CC1 for UFP attach. Monitor CC2 for cable detach.	Off	Off
Ra	Rd	Powered Cable, UFP attached	Monitor CC2 for UFP detach. CC1 is not monitored for detach.	On	On
Rd	Ra	Powered Cable, UFP attached	Monitor CC1 for UFP detach. CC2 is not monitored for detach.	On	On
Rd	Rd	Debug accessory mode attached	Monitor both CC pins for detach	Off	Off
Ra	Ra	Audio accessory mode attached.	Monitor both CC pins for detach	Off	Off

#### TABLE 4-4:SOURCE DETECTION

#### 4.3.3 RP CURRENT SOURCES

In order to advertise the current charging capabilities of the device via the integrated port power controller or external power circuit, Rp current sources are used. The current source can be selected by software. Table 4-5 summarizes the values supported by the current sources in regards to the programmed value.

#### TABLE 4-5: RP CURRENT SOURCES

DFP Advertisement	Current source (1.7V to 5.5V)	RPx Value
Disab	00b	
Default USB Power	80 uA +/-20%	01b
1.5A @ 5V	180 uA +/-8%	10b
3.0A @ 5V	330 uA +/-8%	11b

The current source coupled with the CC pins for RP advertisement is also used for sampling the CFG\_SEL pin. When the CFG\_SEL pin is sampled, current is steered away from the CC pins and no RP value is advertised.

#### 4.3.4 UFP OPERATION

When operating as a UFP, the device applies an Rd pull-down on both CC lines and waits for a DFP connection from the assertion of VBUS. The CC comparator is used to determine the advertised current charger capabilities supported by the DFP.

#### 4.3.5 DRP OPERATION (LEGACY)

In this configuration, software utilizes the device to alternate between a Source and Sink advertisement with an interval of tDRP per the USB Type-C<sup>™</sup> Specification.

#### 4.3.6 DRP OFFLOAD

DRP offload enables the device to manage the DRP toggle. This is beneficial as it allows the host CPU to remain in a low power state until a connection is detected.

DRP offload toggles between Source and Sink advertisement by alternating between enabling Rp current sources and Rd pull-downs for a period of tDRP (DRP Time Register). The duty cycle between Source and Sink advertisement is determined by the DRP Duty Cycle Register. The DRP Time Register may be written by firmware or generated automatically via a pseudo random number generator. The latter approach should be used to reduce the probability of collisions when connecting. It is selectable whether the DRP cycle shall first advertise UFP or DFP.

A connection is detected after a successful debounce for a period defined by the Match Debounce Register. VBUS is checked to be below vSafe0v for the DFP case. This results in IRQ\_N assertion and automatic disablement of the DRP toggle. Firmware must further debounces for the period tPDDebounce before determining if a valid match is present. If a match has not occurred, firmware will enable DRP again.

A pseudo random number generator, implemented via a LFSR, is utilized to generate the DRP period. The LFSR operates off of the 20 KHz clock and updates every 100 us when enabled.

Hardware limits the total DRP period to be between 50 ms and 100 ms in order to comply with the USB Type-C<sup>™</sup> specification.

#### 4.3.7 COLLISION AVOIDANCE

An alternative mode of operation is required to enable the CC detection circuit to facilitate software implementation of collision detection which was incorporated into version 3.0 of the USB PD Specification.

In order to avoid message collisions due to asynchronous Messaging (AMS) sent from the Sink, the Source sets Rp to SinkTxOk (3A@5V) to indicate to the Sink that it is OK to initiate an AMS. When the Source wishes to initiate an AMS it sets Rp to SinkTxNG (1.5A@5V). When the Sink detects that Rp is set to SinkTxOk it may initiate an AMS. When the Sink detects that Rp is set to SinkTxNG it shall not initiate an AMS and shall only send Messages that are part of an AMS the Source has initiated.

When operating as a Sink, a mechanism is required for quickly determining whether the Source is advertising SinkTxNG or SinkTxOK on Rp.

A collision avoidance mechanism exists to enable software to instruct the device to sample only a single threshold on a single CC pin. This results in a cycle through both thresholds taking only 100 us, making it easier for software to meet the timing constraints mandated by SinkTxOk in the specification.

#### 4.3.8 FAST ROLE SWAP (FRS)

This feature is used to detect when a partner source has lost power. Upon detection of FRS signaling, the "Old Sink" transitions to be a Source and begins supplying VBUS.

When operating as a Sink, the FRS mode of operation enables detection of FRS signaling. Detection results in **IRQ\_N** assertion and this event may also be mapped as a PIO override source. When operating as a Source, upon detection of loss of power, the device will transmit FRS signaling. This is initiated by either assertion of a selected PIO or a CSR write.

The following FRS related features are supported:

- · Ability to detect reception of FRS signaling
- High bandwidth and current boost mode for CC comparator to increase sampling frequency
- Interrupt, and PIO, assertion upon FRS detection
- · PIO override support for FRS detection as a source
- · Ability to initiate FRS signaling via GPIO assertion or register write.
- Control 5 Ohm (Rsw) pull-down resistor

#### 4.3.8.1 FRS Sink Operation

When operating as a Sink, the device is configured to detect FRS signaling by setting FRS Detect Enable (FRS\_DE-T\_EN) in FRS Control Register. The CC detection logic is programmed to detect three thresholds (SinkTxOK, Sink-TXNG, FRSWAP) and samples each threshold in round robin fashion. The sampling rate is determined by CC Sample Clock Register.

When a match is detected on FRSWAP threshold, the CC detection logic will "park" at this threshold and continue monitoring the output of the comparator. While "parked" the output of the CC comparator will be sampled at an increased rate of 12 MHz. This higher sampling rate will prevent PD messages from inadvertently looking like FRS signaling which will happen on occasion when the sampling rate is similar or slower than the ~270 kbps rate of PD messages.

It will continue debouncing for the amount of time specified in FRS CC Debounce Register. The FRSWAP threshold is indicated by FRS Threshold Select Register.

If the debounce is successful, then the FRS\_RCV\_STS interrupt is asserted and the CC detection logic resumes sampling all enabled thresholds. If the FRS debounce fails, the CC detection logic resumes sampling all enabled thresholds.

In this mode of operation the CC Comparator operates at a faster rate in order to minimize the FRS detection latency. This is enabled by placing this the comparator into a high bandwidth mode.

After detecting the FRS signaling, the "old Sink" must start supplying vSafe5V at USB Type-C<sup>™</sup> current VBUS no later than tSrcFRSwap (150 us) after VBUS has dropped below vSafe5V. This must be accomplished via circuitry external to the device.

**Note:** The upper threshold used for vSafe5V should be used for determining when VBUS has dropped below vSafe5v to help meet tSrcFRSwap requirement.

**Note:** Matching of a VBUS threshold may be selected as a source to a PIO override. Additionally, VBUS threshold match ANDed with FRS signal detect may also be used as a PIO override source.

#### 4.3.8.2 FRS Source Operation

The initial Source shall signal a FRS request by driving the CC pin to ground with a resistance of less than 5 Ohms for a period defined by FRS Transmission Length Register. The FRS request signaling is initiated by either a CSR write or GPIO assertion.

The former case is implemented by setting the FRS Request (FRS\_REQ\_EN) bit in FRS Control Register. This bit self clears after the FRS request is transmitted. For the latter case, the PIO is selected by the FRS Request PIO (FRS\_REQ\_PIO) field in FRS Control Register.

Transmission of FRS signaling will take precedence over PD MAC TX communication. The FRS PD resistor is enabled in tandem on the CC pin determined by FRS CC Select (FRS\_CC\_SEL) in FRS Control Register. This configuration remains until FRS transmission has completed.

#### 4.3.8.3 Dead Battery (UPD301C Only)

The UPD301C device includes two variations of the Rd resistor implementation: Rd (Dead Battery) and Rd (Trimmed). The CC pins are configured to present either Hi-Z or an untrimmed Rd pull-down resistance when connected to a DFP advertising a pull-up resistance.

Figure 4-2 illustrates the configuration for supporting dead battery cases. The UFP pull-up activates the FET in series with RD\_DB and enables the untrimmed dead battery pull-down.



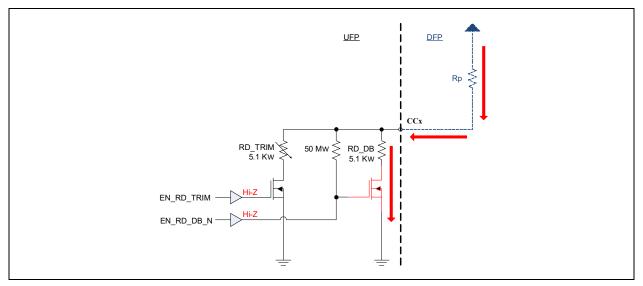
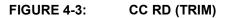
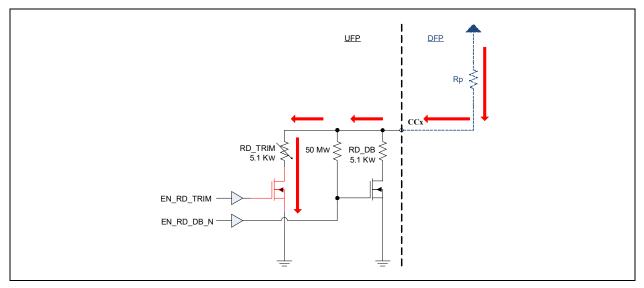


Figure 4-3 illustrates operation after the UFP has been powered over VBUS by the DFP. After the device is powered, EN\_RD\_DB asserts by default to keep the RD\_DB pull-down activated.

Upon powering the host CPU, software simultaneously deasserts EN\_RD\_DB and asserts EN\_RD\_TRIM. Going forward the device presents RD\_TRIM.





The Rd resistor presented, trimmed or untrimmed, is controlled by the CC1 and CC2 Pull-Down Values in the CC Control Register (CC\_CTL). These register fields serve the basis for the EN\_RD\_TRIM and EN\_RD\_DB\_N control signals depicted.

#### 4.3.9 VCONN OPERATION

VCONN is a 5V supply that is used to power circuitry in the USB Type-C<sup>™</sup> plug, which is required to implement Electronically Marked Cables. By default, the DFP always sources VCONN when connected to an active cable. However, this may be changed by software.

The VCONN FETs are enabled/disabled by software via the VCONN1 Control and VCONN2 Control control bits in the CC Control Register (CC\_CTL).

#### APPLICATION NOTE: It is not envisioned to ever enable both FETs simultaneously.

VCONN is monitored for an over current condition via an internal monitoring circuit. A VCONN over current condition is recognized when the event persists for a time longer than specified. When an over-current VCONN event is detected, an interrupt asserts. The device may be configured to automatically disable the VCONN FET upon detection of a CC1/ CC2 Back-Drive Error or VCONN Discharge Error. In the event of the detection of a debounced over-current VCONN event, the enabled VCONN FET will be disabled.

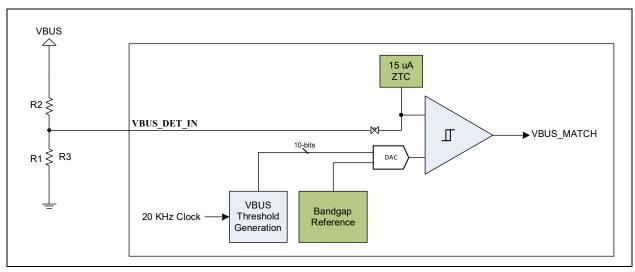
#### 4.3.10 VBUS DETECTION

The device implements a comparator for determining when VBUS is within a programmed range, vSafe5V, or vSafe0v. VBUS is divided down externally via a 1:9 resistor divider to generate VBUS\_DET\_IN. VBUS\_DET\_IN is compared with an 8-bit threshold generated by an integrated DAC. The comparator is also shared by the CFG\_SEL pin which is sampled automatically after a system reset.

Figure 4-4 illustrates the VBUS\_DET\_IN circuit. In a typical use case, VBUS\_DET\_IN thresholds are programmed to track the following voltage ranges as defined in Table 4-5.

**Note:** Table 4-5 illustrates the values of VBUS\_DET\_IN utilizing +/-1% accurate resistors where R1 is 10K Ohms and R2 is 90 kOhms.





For a DFP, the VBUS comparator is useful to detect when VBUS is within the desired range per PD negotiations. This is the case when VBUS is generated by a source external to the device.

For a UFP, the VBUS comparator is required to determine when a DFP is attached or detached. It may also use the comparator to determine when VBUS is within a new voltage range negotiated via PD.

If supported, the ranges 8V, 12V and 20V may be programmed in VBUS Threshold 2 and VBUS Threshold 3 registers. Likewise 5V range, vSafe5v, can be programmed in VBUS Threshold 0 and VBUS Threshold 1 registers.

The threshold for vSafe0V is programmable.

VBUS\_DET\_IN monitoring logic operates off of the 20 KHz oscillator which cycles through each threshold. Including vSafe0v, a total of five values are compared.

The VBUS Match Register (VBUS\_MATCH) indicates when the value on VBUS\_DET\_IN is higher than the corresponding programmed threshold and can therefore be used to determine if VBUS is in the desired range.

A change in the state of the VBUS match may trigger assertion of the IRQ\_N pin if appropriately configured.

#### 4.4 Baseband CC Interface (BCI)

The device integrates a Baseband CC Interface (BCI) to facilitate USB Power Delivery communication. This module bridges between the PD MAC/BMC and the analog front end. Baseband communication is initiated by the PD MAC, which interfaces to the BCI. The BCI implements the digital functions required to control TX baseband components.

#### 4.4.1 BASEBAND TX DATA-FLOW

The key responsibility of the BCI is to generate the wave form required for baseband communication. To this end, the BMC has a group of eight registers that define the Lo-Hi and Hi-Lo transitions for the generated BMC signal.

When instructed to transition from Lo-Hi, the BCI steps through all BB TX Rise Registers. Likewise when instructed to transition from Hi-Lo, the BCI steps through all BB TX Fall Registers

**APPLICATION NOTE:** The user may replicate values if it is desired to use less than twelve unique values for this purpose.

#### 4.4.2 BASEBAND RX DATA-FLOW

Baseband RX data is received by the BCI from the RX analog front end where it is compared to a threshold programmed by software. The CC RX DAC Value defines the trip point used for reception of baseband data. The field shall be programmed to be 175 mV below the RX Eye center, as defined in the PD Specification for the mode in which the device is operating (Sourcing Power, Sinking Power, Power Neutral).

#### 4.5 **Power Delivery MAC**

The PD MAC implements certain features of the protocol layer and physical layer of the Universal Serial Bus Power Delivery Specification. On one end the PD MAC interfaces to the software implementing the bulk of protocol and higher level layers and on the other end it interfaces to a BMC encoder / decoder module.

In addition to the normal TX and RX functions, the PD MAC implements the test mode logic defined in the USB PD specification (BIST).

The PD MAC supports the following features:

- Automatic TX Mode for packet framing and CRC32 insertion.
- Raw TX Mode for bit level packet control.
- Automatic GoodCRC response to received messages.
- Automatic BIST Error Count Message in BIST RX Mode.
- GoodCRCTimer implementation.
- Automatic retries with programmable retry count.
- Redundant receive packets automatically dropped in auto response mode.
- 74 byte TX queue.
- 128 byte RX queue.
- Programmable TX Bit-time. Allows for changing operating frequency.
- Programmable preamble length.
- · BIST TX and RX logic.
- Programmable TX and RX queue modes buffer mode and FIFO mode.
- CRC32 generator for TX.
- CRC32 calculator and comparator for RX.

#### 4.5.1 PD MAC TRANSMITTER

The PD MAC transmitter is comprised of three major blocks:

#### • TX Queue:

The TX Queue is where software loads the message to be transmitted.

• TX Control:

The TX Control implements the necessary control logic. It is responsible for reading the data from the TX queue and based on the data processing mode (automatic or raw), processing the data to make it suitable (nibbles with control information) for use by the TX Comm. It is also responsible for generating packet framing and terminating the packet in automatic mode, and generating messages for automatic response (GoodCRC and BIST Error Count). TX Control also handles the selection of the SOP type that is to be transmitted.

• TX Comm:

The TX Comm is comprised of a TX CRC generator, a 4b5b encoder, serializer, preamble generator, and TX bit timer. It takes the nibble data, computes and inserts the CRC, 5b encodes, and generates the baseband serial data. Preamble insertion is also performed by this logic.

#### 4.5.2 PD MAC RECEIVER

The PD MAC receiver is comprised of three major blocks:

#### • RX Queue:

The RX Queue is where software reads the received messages.

RX Control:

The RX Control implements the necessary control logic. It is responsible for validating the received packet, updating the RX Queue status, and triggering automatic responses, if required.

RX Comm:

The RX Comm is comprised of the Clock and Data Recovery (CDR), RX DES (de-serializer) (serial-to-parallel converter, 4b5b decoder, and framing detector), RX CRC32 (CRC calculator, receive timer), and other logic to detect valid packet reception.

#### 4.5.3 PD MAC BIST

The PD MAC incorporates BIST functions as defined in the USB PD Specification. It is comprised of a TX and RX block.

The BIST TX block contains a PRBS (Pseudo Random Binary Sequence) generator, BIST pattern generation logic, and its own bit-timing logic. The SOP type used by TX BIST Test Frames is a 20-bit static vector which is created by multiplexing between the five SOP ordered sets based on a register setting. The resultant 20-bit vector is simply bit selected when the packet is transmitted.

The BIST RX block contains a PRBS generator and bit error detection logic. BIST RX is used only during the BIST Receiver Test.

#### 4.6 Supported Power Delivery (PD) Functionality

#### 4.6.1 SUPPORTED PD MESSAGES

The UPD301B/C is capable of supporting the USB PD Control messages defined within the.*USB Power Delivery 3.0 Specification.* The complete list of supported messages depends on the release version of the USB Power Delivery Software Framework (PSF). The minimum set of supported features are:

- GoodCRC
- Accept
- Reject
- Ping
- PS\_RDY
- Get\_Source\_Cap (Sink Role only)
- Get\_Sink\_Cap (Source Role only)
- VCONN\_Swap
- Wait
- Soft\_Reset

The following USB PD Data messages are supported:

- Source Capabilities (Source Role only)
- Request
- BIST
- Sink\_Capabilities (Sink Role only)

The following USB PD Extended messages are supported:

- Firmware\_Update\_Request
- Firmware\_Update\_Response

The following USB PD Control messages can also be supported UPD301B/C. Check the release notes of the latest PSF release for the most up-to-date list of supported messages. Support to specific messages may also be added by modification of the PDF source code.

- GotoMin
- DR\_Swap
- PR\_Swap
- Get\_Source\_Cap\_Extended
- · Get\_Status
- FR\_Swap
- Get\_PPS\_Status
- Get\_Country\_Codes

The following USB PD Data messages are not supported:

- Battery\_Status
- Alert
- Get\_Country\_Info
- Vendor\_Defined

The following USB PD Extended messages are not supported:

- Source\_Capabilities\_Extended
- Status
- Get\_Battery\_Cap
- Get\_Battery\_Status
- Battery\_Capabilities
- · Manufacturer Info
- Security\_Request
- Security\_Response
- · PPS\_Status
- Country\_Info
- Country\_Codes

#### 4.6.2 SOURCE POWER DELIVERY OBJECTS (PDOS)

The PDOs defined in the USB PD Specification Section 10.2.2 are configurable within the PSF configuration. These are the PDOs returned in the PD Source\_Capabilities message and correspond to the capabilities of the Source power supply. Augmented PDOs (APDOs) are also supported for enabling Programmable Power Supply (PPS) operation.

#### 4.6.3 SINK POWER DELIVERY OBJECTS (PDOS)

The PDOs defined in the USB PD Specification Section 10.2.2 are configurable within the PSF configuration. These are the PDOs returned in the PD Sink\_Capabilities message and correspond to the requirements of the Sink with respect to Source capabilities. Note that the PDOs defined in the USB Power Delivery Specification Section 10.2.2 are defined for Sources, but correspond to the Source PDOs the Sink is able to operate with.

## 5.0 OPERATIONAL CHARACTERISTICS

### 5.1 Absolute Maximum Ratings\*

Supply Voltage (VCONN_IN) (Note 5-1)	0.3 V to +6.0 V
Supply Voltage (VDD33_ALW_IN, VDD33_IO_IN) (Note 5-1)	0 V to +6.0 V
Supply Voltage (VDD33_REG_IN, VDD33_ANA_IN) (Note 5-1)	0 V to +3.8 V
Supply Voltage (VPP18) (Note 5-1).	0 V to +7.75 V
Pin voltage with respect to ground (Note 5-2)	VSS-0.6 V to VDD33_REG_IN+0.6 V
Pin voltage with respect to ground (vBus_DET_IN)	0.5 V to +3.96 V
Pin voltage with respect to ground (CC1, CC2, SPI_MOSI_SI, EN_VBUS, RESET_N_COM, VBUS_DIS, <u>I2C_ADDR_SEL</u> )	-0.5 V to +6.0 V
Storage Temperature	55°C to +150°C
Lead Temperature Range	Refer to JEDEC Spec. J-STD-020
HBM ESD Performance	+/-2 kV

- **Note 5-1** When powering this device from laboratory or system power supplies, it is important that the absolute maximum ratings not be exceeded or device failure can result. Some power supplies exhibit voltage spikes on their outputs when AC power is switched on or off. In addition, voltage transients on the AC power line may appear on the DC output. If this possibility exists, it is suggested to use a clamp circuit.
- Note 5-2 This rating does not apply to the following pins: VBUS\_DET\_IN, CC1, CC2, SPI\_MOSI\_SI, EN\_VBUS, RESET\_N\_IN, VBUS\_DIS

\*Stresses exceeding those listed in this section could cause permanent damage to the device. This is a stress rating only. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at any condition exceeding those indicated in Section 5.2, "Operating Conditions\*\*", Section 5.5, "DC Characteristics", or any other applicable section of this specification is not implied.

### 5.2 Operating Conditions\*\*

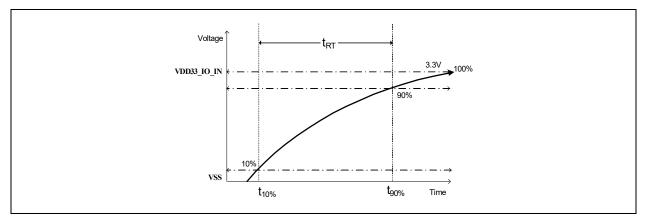
Supply Voltage (vconn_in)
Supply Voltage (VDD33_ALW_IN, VDD33_IO_IN)
Supply Voltage (VDD33_REG_IN, VDD33_ANA_IN)
Supply Voltage (VPP18)
Pin voltage with respect to ground (Note 5-3)
Positive pin voltage with respect to ground (VBUS_DET_IN) VDD33_IO_IN-0.3 V to VDD33_IO_IN+0.3 V
Negative pin voltage with respect to ground (VBUS_DET_IN) $\dots \dots \dots$
Positive pin voltage with respect to ground (cc1, cc2, spi_mosi_si, en_vbus, reset_n_com, vbus_dis, i2c_addr_sel)
Negative pin voltage with respect to ground
(CC1, CC2, SPI_MOSI_SI, EN_VBUS, RESET_N_COM, VBUS_DIS, <u>12C_ADDR_SEL</u> ) $\dots \dots \dots$
Power Supply Rise Time Max (T <sub>RT</sub> ) (VDD33_IO_IN) (Figure 5-1)
Power Supply Rise Rate Max (vdd33_ana_in, vdd33_reg_in)0.1 V/µs
Ambient Operating Temperature in Still Air (T <sub>A</sub> ) Note 5-4

Note 5-3 This rating does not apply to the following pins: VBUS\_DET\_IN, CC1, CC2, SPI\_MOSI\_SI, EN\_VBUS, RESET\_N\_COM, VBUS\_DIS

**Note 5-4**  $0^{\circ}$ C to +70°C for commercial version, -40°C to +85°C for industrial version.

\*\*Proper operation of the device is assured only within the ranges specified in this section.

#### FIGURE 5-1: SUPPLY RISE TIME MODEL



### 5.3 Package Thermal Specifications

#### TABLE 5-1: PACKAGE THERMAL PARAMETERS

Parameter	Symbol	°C/W
Thermal Resistance Junction to Ambient (@ 0 air flow)	$\Theta_{JA}$	36.6
Thermal Resistance Junction to Top of Case	$\Theta_{JC}$	9.2
Thermal Resistance Junction to Board	$\Theta_{JB}$	15.7
Thermal Resistance Junction to Bottom of Case (@ 0 air flow)	$\Psi_{JT}$	0.2

Note: Thermal parameters are measured or estimated for devices in a multi-layer 2S2P PCB per JESDN51.

#### TABLE 5-2: POWER DISSIPATION

Parameter	Symbol	Мах	Units	
Power Dissipation	P <sub>dis</sub>	214	mW	

**Note:** This is the worst-case power dissipation as a consequence of maximum loading (before current-limiting protections take effect) upon the VCONN power switch, 3.3V power-ORing switch, analog blocks, and core digital logic.

### 5.4 Current Consumption

TADLE 3-3. ITFICAL DEVICE CURRENT CONSUMPTION	TABLE 5-3:	TYPICAL DEVICE CURRENT CONSUMPTION
---	------------	------------------------------------

Power State	3	3.3V Supply Current					
Power State	Typical	Max	Units				
RESET	1.27	-	mA				
STANDBY (source)	7.49	-	mA				
ATTACHED IDLE (source)	11.40	-	mA				
ACTIVE (with PD packet transmitting)	-	23.84	mA				

**Note 1:** This table details the power consumption of the UPD301B/C device as measured during various modes of operation for a single port Source-Only implementation (i.e.: loading a PSF Source-only configuration and programming with default settings). The power consumption may vary significantly depending on the utilization SAMD20 MCU to handle any additional custom system-specific functions. Refer to the respective SAMD20E and UPD350 datasheets for more details on the power consumption of these two devices under certain specific usage scenarios. Also refer to Section 4.2, "Power States" for additional information. Power dissipation is determined by temperature, supply voltage, and external source/sink requirements. Maximum values represent very short bursts of activity over a small amount of time. Typical values represent averaged current consumption over time.

- 2: STANDBY is equivalent to USB Type-C™ specification's Unattached.SRC
- 3: Currents measured with all 3.3V rails tied together.

### 5.5 DC Characteristics

Parameter	Symbol	Min	Тур	Мах	Units	Notes
I Type Input Buffer						
Low Input Level	V <sub>IL</sub>		0.3*VDD33_REG_IN		V	
High Input Level	V <sub>IH</sub>	0.55*VDD33_REG_IN				
Input Leakage	I <sub>LEAK</sub>	-1	±0.015 1		μA	
IS_1 Type Input Buffer						
Low Input Level	V <sub>IL</sub>			0.3*VDD33_REG_IN	v	
High Input Level	V <sub>IH</sub>	0.55*VDD33_REG_IN			v	
Input Leakage	I <sub>IH</sub>	-1	±0.015	1	μA	
IS_2 Type Input Buffer						
Low Input Level	V <sub>ILI</sub>	-0.3		0.8	v	
High Input Level	VIHI	2.0		3.6	v	
Negative-Going Threshold	V <sub>ILT</sub>	1.21	1.33	1.8	v	Schmitt trigger
Positive-Going Threshold	V <sub>IHT</sub>	1.31	1.58	1.8	v	Schmitt trigger
Schmitt Trigger Hysteresis (V <sub>IHT</sub> - V <sub>ILT</sub> )	V <sub>HYS</sub>	100	133	200	mV	
Input Leakage (V <sub>IN</sub> = VSS or VDD33_IO_IN)	IIH	-10		10	μA	Note 5-5
Input Capacitance	C <sub>IN</sub>			3	pF	
O2 Type Output Buffer						
Low Output Level	V <sub>OL</sub>		0.1*VDD33_REG_IN	0.2*VDD33_REG_IN	v	I <sub>OL</sub> = -2 mA
High Output Level	V <sub>OH</sub>	0.8*VDD33_REG_IN	0.9*VDD33_REG_IN		v	I <sub>OH</sub> = 2 mA
OD2 Type Output Buffer						
Low Output Level	V <sub>OL</sub>		0.1*VDD33_REG_IN	0.2*VDD33_REG_IN	v	I <sub>OL</sub> = -2 mA
O8_1 Type Output Buffer						
Low Output Level	V <sub>OL</sub>		0.1*VDD33_REG_IN 0.2*VDD33_REG_IN		v	I <sub>OL</sub> = -8 mA
High Output Level	V <sub>OH</sub>	0.8*VDD33_REG_IN	0.9*VDD33_REG_IN		v	I <sub>OH</sub> = 8 mA
O8_2 Type Output Buffer						
Low Output Level	V <sub>OL</sub>			0.4	V	I <sub>OL</sub> = -8 mA
High Output Level	V <sub>OH</sub>	VDD33_IO_IN - 0.4			v	I <sub>OH</sub> = 8 mA

TABLE 5-4: DC ELECTRICAL CHARACTERISTICS

**Note 5-5** This specification applies to all inputs and tri-stated bi-directional pins. Internal pull-down and pull-up resistors add +/- 50 μA per-pin (typical).

TABLE 5-5:	VOLTAGE REGULATOR OPERATING RANGES

Pin Name	Parameter	Min	Тур	Мах	Units
VDD18_CORE_OUT	DC uncalibrated output voltage	1.62	1.80	1.91	V
VDD12_CORE_OUT	DC calibrated output voltage	1.10	1.23	1.30	V

#### TABLE 5-6: VCONN SOURCE DC PARAMETERS

Parameter	Symbol	Min	Тур	Max	Units	Notes
ILIM	I <sub>LIM_VCONN</sub>		600		mA	vconn_in=5V
On Resistance	R <sub>ON_VCONN</sub>		270		mΩ	

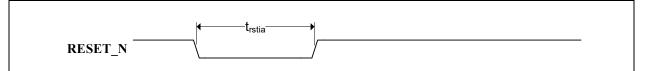
#### 5.6 AC Characteristics and Timing

This section details the various AC timing specifications of the device.

#### 5.6.1 **RESET\_N TIMING**

Figure 5-2 illustrates the **RESET\_N** timing requirements. Assertion of **RESET\_N** is not a requirement. However, if used, it must be asserted for the minimum period specified

### FIGURE 5-2: RESET\_N TIMING

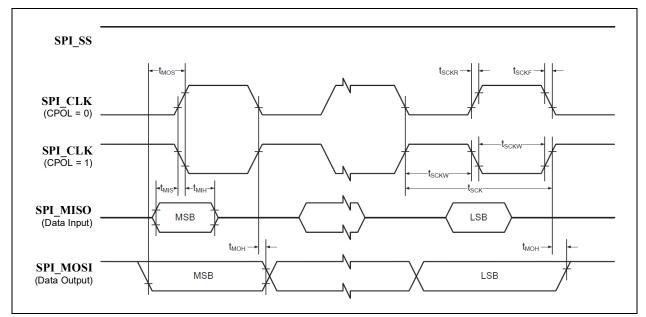


#### TABLE 5-7: RESET\_N TIMING VALUES

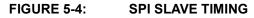
Symbol	Description		Тур	Max	Units
t <sub>rstia</sub>	t <sub>rstia</sub> RESET_N input assertion time				μs

#### 5.6.2 SPI TIMING

Figure 5-3 and Figure 5-4 illustrate the SPI master and slave timing requirements, respectively. Refer to Section 4.1, "Serial Peripheral Interface (SPI)" for additional information.







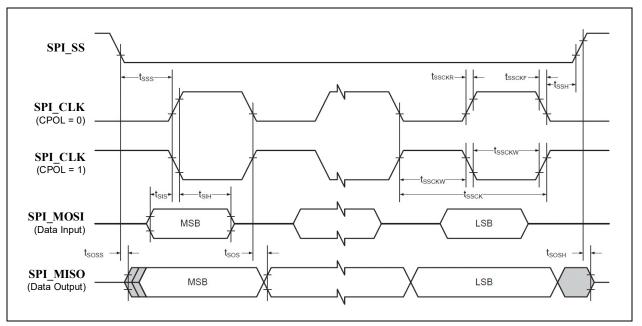


TABLE 5-8:	SPI TIMING VALUES
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Symbol	Description	Min	Тур	Max	Units
t <sub>SCK</sub>	SPI_CLK period (Master)		84		
t <sub>SCKW</sub>	SPI_CLK high/low width (Master)		0.5*t <sub>SCK</sub>		
t <sub>SCKR</sub>	SPI_CLK rise time (Master)		7		ns
t <sub>SCKF</sub>	SPI_CLK fall time (Master)		9.5		ns
t <sub>MIS</sub>	SPI_MISO setup to SPI_CLK (Master)		29		ns
t <sub>MIH</sub>	SPI_MISO hold after SPI_CLK (Master)		8		ns
t <sub>MOS</sub>	SPI_MOSI setup to SPI_CLK (Master)		t <sub>SCK</sub> /2 - 16		ns
t <sub>MOH</sub>	SPI_MOSI hold after SPI_CLK (Master)		16		ns
t <sub>SSCK</sub>	SPI_CLK period (Slave)	1*t <sub>CLK_APB</sub>			ns
t <sub>SSCKW</sub>	SPI_CLK high/low width (Slave)	0.5*t <sub>SSCK</sub>			ns
t <sub>SSCKR</sub>	SPI_CLK rise time (Slave)		7		ns
t <sub>SSCKF</sub>	SPI_CLK fall time (Slave)		9.5		ns
t <sub>SIS</sub>	SPI_MOSI setup to SPI_CLK (Slave)	t <sub>SSCK</sub> /2-19			ns
t <sub>SIH</sub>	SPI_MOSI hold after SPI_CLK (Slave)	t <sub>SSCK</sub> /2-5			ns
t <sub>SSS</sub>	SPI_SS setup to SPI_CLK (Slave, PRELOADEN=1)	2*t <sub>CLK_APB</sub> + t <sub>SOS</sub>			ns
	SPI_SS setup to SPI_CLK (Slave, PRELOADEN=0)	t <sub>SOS</sub> +7			ns
t <sub>SSH</sub>	SPI_SS hold after SPI_CLK (Slave)	t <sub>SIH</sub> -4			ns
t <sub>SOS</sub>	SPI_MISO setup to SPI_CLK (Slave)		t <sub>SSCK</sub> /2-20		ns
t <sub>SOH</sub>	SPI_MISO hold after SPI_CLK (Slave)		20		ns
t <sub>SOSS</sub>	SPI_MISO setup after SPI_SS low (Slave)		16		ns
t <sub>SOSH</sub>	SPI_MISO setup after SPI_SS high (Slave)		11		ns

## 6.0 PACKAGE INFORMATION

Note:	For the most current package drawings, please see the Microchip Packaging Specification located at
	http://www.microchip.com/packaging.

#### FIGURE 6-1: PACKAGE MARKING INFORMATION

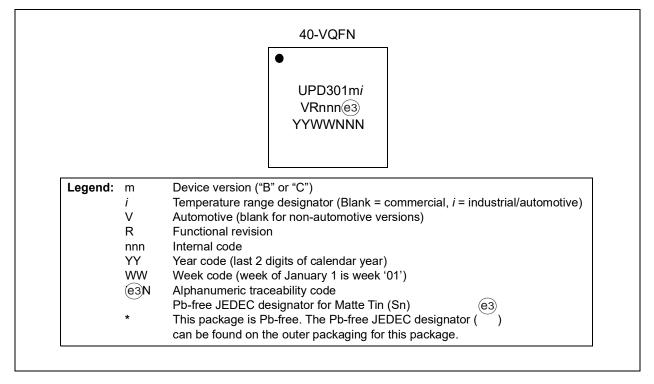
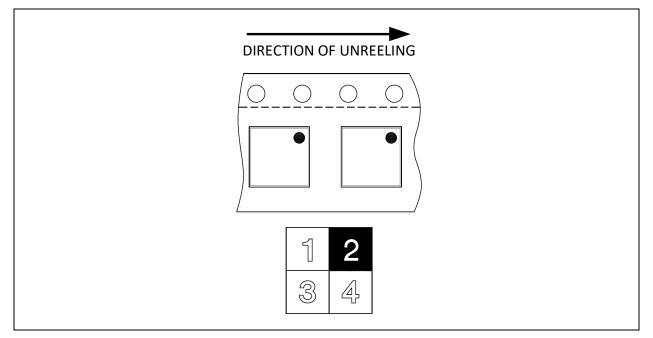
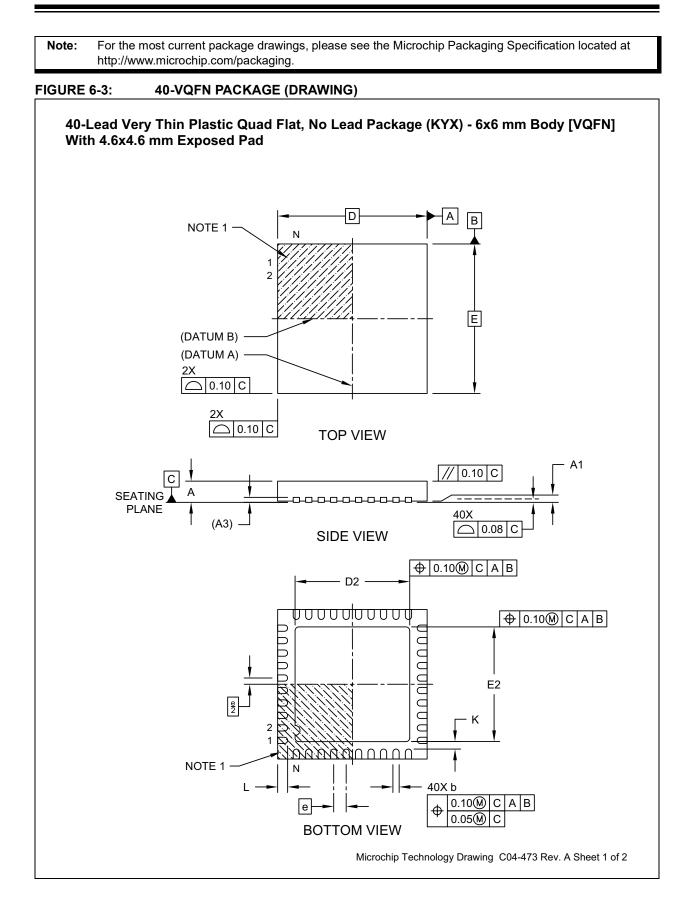
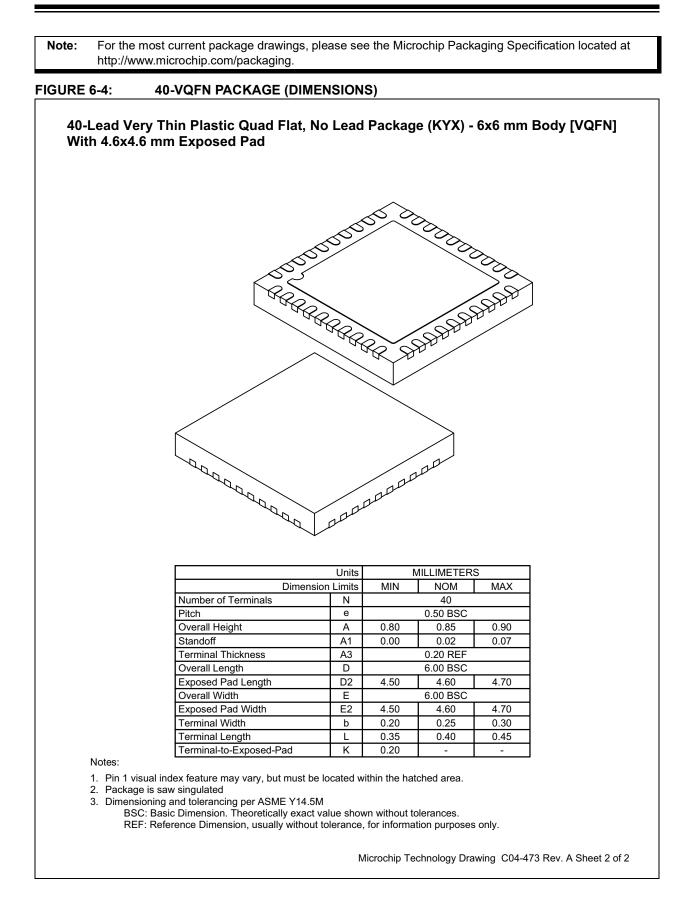
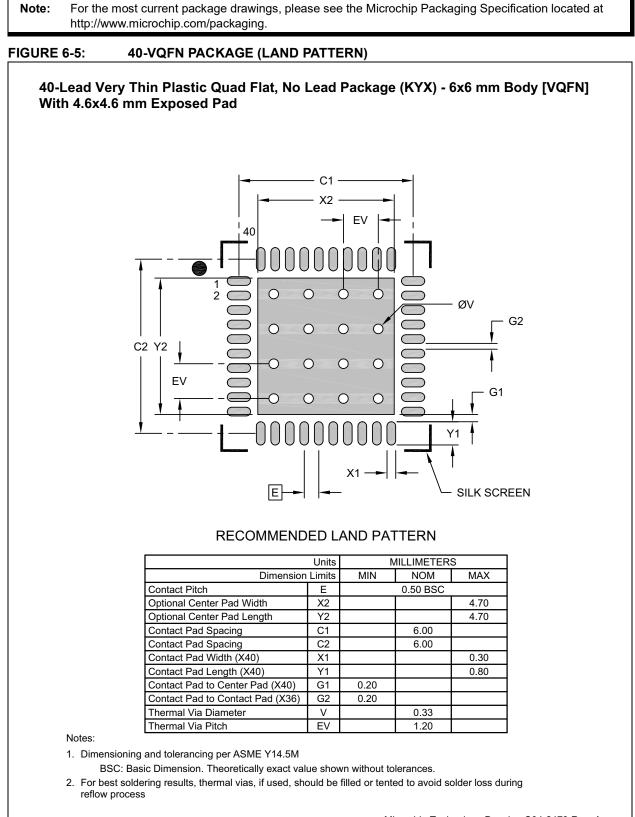


FIGURE 6-2: TAPE & REEL DEVICE ORIENTATION









### APPENDIX A: DATA SHEET REVISION HISTORY

Revision	Section/Figure/Entry	Correction		
DS00003412A (04-06-20)	Initial Document Release			

#### TABLE A-1: REVISION HISTORY

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PART NO.		Examples:
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