

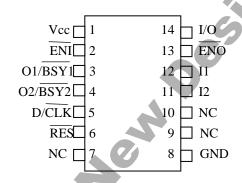
### 1-Wire Bus Master with Overdrive

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#### **FEATURES**

- Provides a synchronous interface to Dallas Semiconductor 1-Wire devices
- Compatible with low power parallel ports (can be used with microcontrollers)
- Can be cascaded with other DS1481s
- Allows print spooler and other processes to run during 1-Wire I/O
- Provides high speed communication with overdrive capable devices
- Space saving 14-pin (150 mil), SO package
- Recommended for short 1-Wire networks less than 3 inches. Longer 1-Wire lengths can be achieved with the DS2480B.

#### PIN CONFIGURATION



14-PIN SO (150 MIL)

## **PIN DESCRIPTION**

$V_{CC}$	-	Supply
ENI	-	Enable In
D/CLK	-	Data/Clock

RES - Reset

O1/BSY1 - Output 1/Busy 1 O2/BSY2 - Output 2/Busy 2

GND - Ground

I1 - Input 1

I2 - Input 2

I/O - 1-Wire

ENO - Enable Out

NC - No connection

## **DESCRIPTION**

The DS1481 is a dedicated 1-Wire<sup>®</sup> timing generator. The device is normally used in conjunction with a parallel port controller to provide the necessary interface to the host processor. Busy signals allow the host processor to perform other tasks while 1-Wire "time-slots" are completed. The DS1481 also saves the state of D/CLK and RES, allowing print spoolers to operate without affecting 1-Wire communication.

DS1481 based devices can be cascaded. The first device's O1/BSY1 and O2/BSY2 connect to the PC printer port's BUSY and SELECT OUT signals (pins 11 and 13 respectively). The next DS1481 connects its O1/BSY1 and O2/BSY2 to the first device's I1 and I2 respectively. ENO of the first device connects to ENI of the second device. More DS1481s can be stacked in a similar manner. The last device's I1 and I2 connect to BUSY and SELECT of the attached printer.

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The DS1481's 3V operation insures compatibility with most low power parallel ports (i.e., portable computers).

#### **DEVICE OPERATION**

1-Wire communication is executed in "time slots". The DS1481 generates either a read/write bit "time slot" or a reset on the I/O pin. The operation performed is determined by the states of the  $D/\overline{CLK}$  and  $\overline{RES}$  pins as follows:

TIME SLOT	D/CLK	RES
Toggle Speed	logic low	logic low (see Figure 7)
Read 0, Read 1, Write 1	logic high	logic high (see Figure 4)
Write 0	logic low	logic high (see Figure 5)
1-Wire Reset	logic high	logic low (see Figure 6)

After D/CLK and RES have been set, the time slot begins when ENI is driven to its active state. A falling edge on ENI causes the DS1481 to save the state of D/CLK and RES. If the time slot is a 1-Wire reset the DS1481 will issue a busy signal by driving O1/BSY1 low and O2/BSY2 high. After 2µs O2/BSY2 is driven low. Both outputs will remain low until the communication on the I/O line is finished. A busy signal for a bit time slot differs from the reset busy signal only in that both O1/BSY1 and O2/BSY2 are driven low immediately.

While the busy signal is asserted, the host processor is free to perform other tasks (including running the print spooler). When the time slot is complete, the DS1481 restores both O1/BSY1 and O2/BSY2 to the states of I1 and I2 (see Figure 1).

When the host detects that one or both of the busy signals has returned high, it must query the result of the time slot. This is accomplished by driving D/CLK low. If the result of the time slot was low (Read 0, Write 0 or presence detect) the DS1481 drives both O1/BSY1 and O2/BSY2 low (this state is held until ENI returns high). Otherwise it propagates the states of I1 and I2.

After the host reads the result of the time slot it must drive ENI to its inactive state (high). The DS1481 will then set O1/BSY1 and O2/BSY2 to the states of I1 and

## 1-WIRE TIMING GENERATION

For all time slots, the DS1481 samples the I/O pin at  $t_{SO}$  (see Figure 4). The DS1481 waits a minimum of 60µs from the start of the time slot and de-asserts O1/ $\overline{BSY1}$  and O2/ $\overline{BSY2}$ .

When a reset is requested, the DS1481 drives the I/O pin low for at least 480µs and then releases it. During a normal reset the I/O pin immediately begins to return high.

If a 1-Wire device is present on the I/O line it pulls I/O low after time T ( $15\mu s \le T \le 60\mu s$ ) from the previous rising edge. The 1-Wire device(s) holds the I/O line low for 4T and then releases it, allowing the I/O line to return high. This is the presence detect pulse. The I/O line must remain high (in its idle state) for at least 3T before the 1-Wire device(s) is ready for further communication. To ensure this idle high time is satisfied, the DS1481 does not release O1/BSY1 and O2/BSY2 for at least 960 $\mu s$  (measured from the 1st falling edge on the I/O pin).

If after  $480\mu s$  of low time the I/O line did not return high, either the I/O line has been shorted to ground or there is at least one 1-Wire device connected to the I/O line which is issuing an alarm interrupt (see Figure 6). In this case the DS1481 waits for I/O to return high for an additional  $3840\mu s$  (64\*60). If time expires the I/O line is assumed to be shorted and the DS1481 releases O1/BSY1 and O2/BSY2. If the I/O line returns high, the DS1481 continues to monitor the presence detect portion of the reset (as described above) as for the non-interrupt case. Note that the 3T idle high time is still required after the presence detect ends.

#### **OVERDRIVE**

The DS1481 also supports overdrive communication with overdrive capable 1-Wire devices. When the DS1481 powers <u>up it</u> is in normal mode (i.e., OD = 0, Figure 1). To toggle to overdrive mode the host sets D/CLK and RES low and <u>drives ENI low. The DS1481</u> toggles the OD bit to a logic high and returns the states of I1 and I2 on O1/BSY1 <u>and O2/BSY2</u>. <u>Overdrive mode is cleared in the same way</u>. When overdrive is turned off (OD = 0). O1/BSY1 and O2/BSY2 are driven low to report the state of the OD bit.

When OD = 1, communication with the 1-Wire device is exactly as described in the operation section above. The actual 1-Wire timing for both modes of operation is described in Figures 4, 5, and 6.

Note that when toggling the OD bit there is no change on the I/O line.

#### PRINTER COEXISTENCE

In order to coexist with parallel <u>port</u> printers, the <u>DS1481</u> utilizes two input pins (I1 and I2) and two output pins (O1/BSY1 and O2/BSY2). When <u>ENI</u> is low these pins <u>are</u> used for transmitting <u>data</u> received on the I/O pin or for issuing an unmistakable busy signal. When <u>ENI</u> is inactive (high) O1/BSY1 and O2/BSY2 propagate the states of I1 and I2.

If a printer is attached to a DS1481, I1 is connected to the printers BUSY signal (low only if printer is on line and busy), and I2 is connected to SELECT OUT (driven low if printer is off line), see Figure 2.

If the attached printer is "powered up" and on line, the DS1481 uses SELECT OUT for communication regardless of the state of the printer's BUSY signal. If the printer is off line its BUSY signal is inactive (high) and this line is used by the DS1481 for host communication.

If the attached printer is powered off, both SELECT OUT and BUSY will be low. This prevents meaningful communication with the DS1481 because it is unable to de-assert its busy signal  $(O1/\overline{BSY1}$  and  $O2/\overline{BSY2}$  low) or return a high sample of the I/O pin.

To solve this problem, the DS1481 uses the busy signal issued during a reset to detect the presence of another DS1481 based device attached behind it on the parallel port. If this busy signal is not detected by the DS1481, it assumes that it is the last DS1481 based device on the port.

If the <u>DS1</u>481 determines that it is the last device on the port it ignores the states of its I1 and I2 pins while <u>ENI</u> is low. It also leaves the <u>ENO</u> pin <u>high</u> to prevent sending line feed signals to the printer. This gives the last device the ability to control O1/BSY1 and O2/BSY2 without affecting stackability.

#### **EPP/ECP TRANSPARENT MODE**

When the DS1481 first powers up it is in a transparent mode in which the three signal lines (auto line feed, busy and select) that pass through the part are directly connected by transmission gates. This allows bi-directional printers (or other parallel port peripherals) to communicate in either the EPP or ECP mode of the PC parallel port. The DS1481 pin sets connected are as follows:

ENI	ENO
$O1/\overline{BSY1}$	<b>I</b> 1
O2/BSY2	I2

1-Wire communication using the DS1481 is impossible in transparent mode. To toggle to normal mode four consecutive overdrive toggle commands must be issued. If this sequence has been issued and the ENI pin remains high for at least 10ms the part will enter its normal mode of operation. Note that any other 1-Wire time slot command issued during the sequence resets the sequence. The steps needed to return to transparent mode are as described above with the exception that no additional wait is required at the end of the four overdrive toggles to enter transparent mode.

While in transparent mode if the DS1481 detects that the ENO pin has been held low for more than 10ms it turns off the transmission gate connecting ENI and ENO. This guarantees the host will have the ability to take the DS1481 out of transparent mode and perform 1-Wire I/O operations.

Figure 1. DS1481 FUNCTIONAL BLOCK DIAGRAM

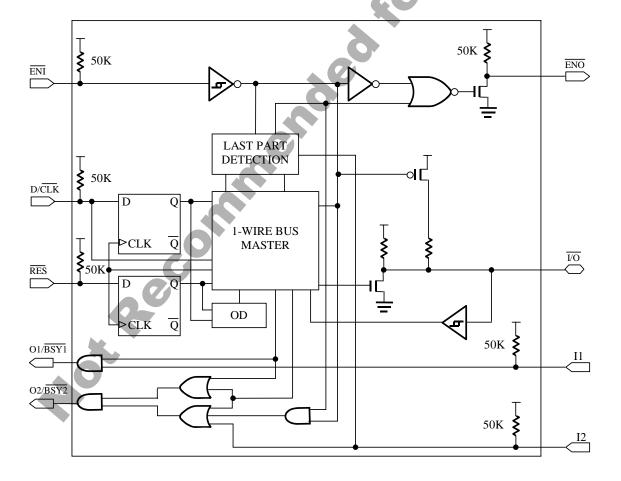


Figure 2. CONNECTION TO PC TYPE PARALLEL PORTS

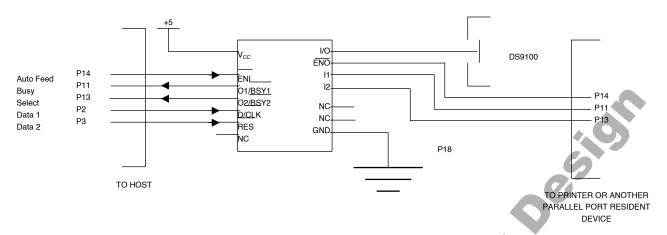
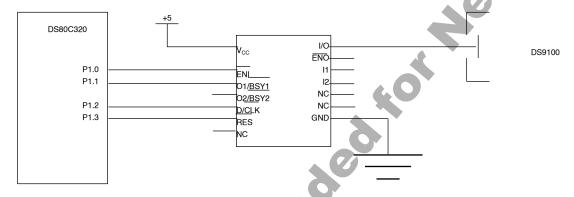


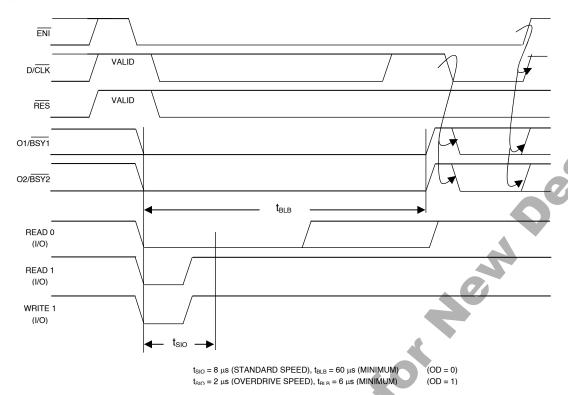
Figure 3. CONNECTION TO MICROCONTROLLERS



The logic states of  $D/\overline{CLK}$  and  $\overline{RES}$  determine the type of 1-Wire function to be executed. These signals are transferred into the DS1481 by activating  $\overline{ENI}$ . This also activates the busy signals.

In Figures 4 through 6 below, during time slots or reset presence sequences the busy lines are active. Once the busy state is over the computer queries the result of the time slot or reset presence sequence by generating a falling edge on  $D/\overline{CLK}$ . The result is found on the busy lines until  $\overline{ENI}$  is de-activated.

Figure 4. TIMING DIAGRAM: HOST INTERFACE



READ O, READ 1, WRITE 1 BIT TIME SLOTS

Figure 5. TIMING DIAGRAM: HOST INTERFACE

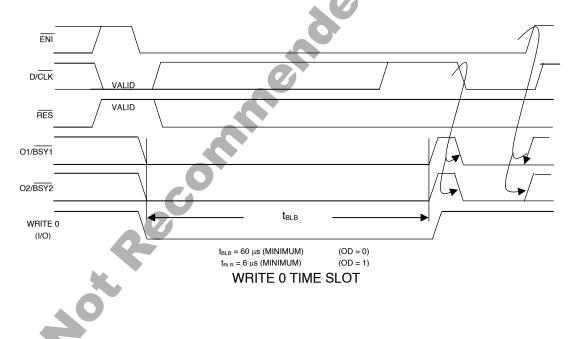


Figure 6. TIMING DIAGRAM: HOST INTERFACE

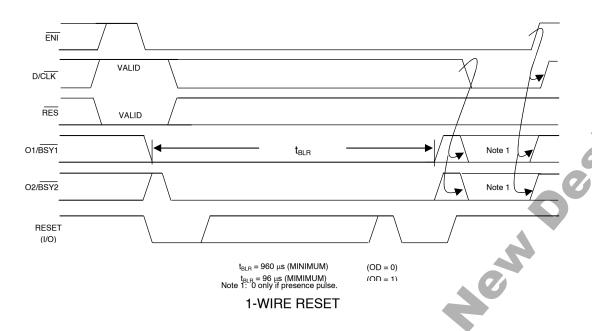
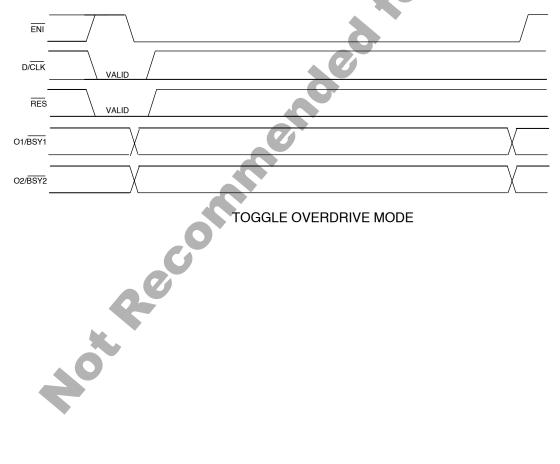


Figure 7. TIMING DIAGRAM: HOST INTERFACE



TOGGLE OVERDRIVE MODE

## **DETAILED PIN DESCRIPTION**

PIN	TYPE	DESCRIPTION
$V_{CC}$		DC supply voltage.
ĒNĪ	I	Chip enable, driven low to begin 1-Wire I/O.
		Driven low during time slot (to indicate a DS1481 busy
		condition). Set to state of I1 after time slot has finished.
O1/BSY1	O	O1/BSY1 will go low after D/CLK goes low if sample of I/O
		communication was low. Returns to state of I1 when ENI
		goes back high (see Figure 1).
		Driven low during time slot (to indicate a DS1481 busy
		condition). Set to state of I2 after time slot has finished.
O2/BSY2	O	O2/BSY2 will go low after D/CLK goes low if sample of I/O
		communication was low. Returns to state of I2 when ENI
		goes back high (see Figure 1).
		Data/Clock pin. Used to specify type of time slot before
D/CLK	I	communication begins. After the time slot has been
D/CLK	1	completed this pin is driven low in order to solicit the result
		of the time slot.
RES	I	Set low (before ENI is driven low) to specify that a reset
KES	1	pulse should be generated on the I/O pin.
GND		System ground.
		Can be connected to the O1/BSY1 of another DS1481. May
I1	I	also be connected to parallel port printer's BUSY signal.
		Internally pulled high via a weak resistor.
		Can be connected to the O2/BSY2 of another DS1481. Can
I2	I	also be connected to a parallel port printer SELECT OUT
		signal. Internally pulled high via a weak resistor.
ENO	O	Set to ENI if not the last part on port. Open-drain output with
LIVO	0	weak internal pullup resistor.
I/O	I/O	1-Wire I/O line. Bidirectional line with open-drain output.
	*	
	7	

## **ABSOLUTE MAXIMUM RATINGS\***

Voltage on Any Pin Relative to Ground	-1.0V	to	+7.0V
Operating Temperature Range	0°C	to	+70°C
Storage Temperature Range	-55°C	to	+125°C
Soldering Temperature	See IPC/	JEDEC JSTD-	020A

<sup>\*</sup>This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

## RECOMMENDED DC OPERATING CONDITIONS (0°C to 40°C)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Logic 1	$V_{IH}$	2.4		$V_{CC} + 0.3$	V	1
Logic 0	$V_{\rm IL}$	-0.3		+0.8	V	1
Supply	$V_{CC}$	2.7	5.0	5.5	V	1

# **DC ELECTRICAL CHARACTERISTICS** (0°C to 40°C; $2.7 \le V_{CC} \le 5.5$ )

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Input Leakage	${ m I}_{ m IL}$	-1		+1	μΑ	5
Output Leakage	$I_{LO}$	-1		+1	μΑ	
$V_{OL}$ @ $I_{SINK} = -2mA$				0.4	V	
I1 Pullup Resistance	$Z_{I1}$		50		$\mathrm{k}\Omega$	
I2 Pullup Resistance	$Z_{I2}$		50		kΩ	
ENI Pullup Resistance	Z <sub>ENI</sub>		50		kΩ	
ENO Pullup Resistance	Z <sub>ENO</sub>		50		kΩ	
D/CLK Pullup Resistance	$Z_{DC}$		50		kΩ	
RES Pullup Resistance	$Z_R$		50		kΩ	
Active Current	$I_{CC}$			500	μΑ	2
Available I/O Current	$I_{I/O}$		40		mA	6
Available I/O Current						
40						

## **AC ELECTRICAL CHARACTERISTICS: HOST INTERFACE**

PARAMETER  Sample Time (For Bit Time Slot, OD = 0) (For Bit Time Slot, OD = 1)  Recovery Time	SYMBOL					
(For Bit Time Slot, OD = 0) (For Bit Time Slot, OD = 1)	R	MIN	TYP	MAX	UNITS	NOTES
(For Bit Time Slot, $OD = 1$ )						
	$t_{ m SIO}$		8  OD = 0		μs	
Recovery Time				2  OD = 1		
	$t_{REC}$	1			μs	
Data to Enable Hold	$t_{ m DE}$	40			μs	
Reset to Enable Hold	$t_{ m RE}$	40			μs	
Clock Low Time	$t_{\mathrm{CL}}$	200			ns	
Clock Low to O1, O2 Valid	t <sub>COV</sub>			200	ns	
BSY1, BSY2 Low Time						
(For Bit Time Slot, $OD = 0$ )	$t_{ m BLB}$	60			μs	3
(OD = 1)		6				
BSY1, BSY2 Low Time					7	
(For Reset Time Slot, $OD = 0$ )	$t_{ m BLR}$	960			μs	4
(OD = 1)		96		40	•	
NOTES:						
1. All voltages are referenced to	ground.					
2. Measured with outputs open	and I1, I2 high	1.	4.0			
3. Minimum time required for 1	_					
4. Minimum time required for 1						
<del>-</del>			<b>O</b>			
5. Only pins without pullups.						
6. Overdrive mode only.						
4						
200						
R. C. C.						
AO'L PEC						
40.60						
AO'C CO						

#### **NOTES:**

- 1. All voltages are referenced to ground.
- 2. Measured with outputs open and I1, I2 high.
- 3. Minimum time required for 1-wire bit time slot.
- 4. Minimum time required for 1-wire reset time slot.
- 5. Only pins without pullups.
- 6. Overdrive mode only.

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