

MAX17643

4.5V–60V, 2A, High-Efficiency, Synchronous Step-Down DC-DC Converter with Internal Compensation

General Description

The Himalaya series of voltage regulator ICs, power modules, and chargers enable cooler, smaller, and simpler power-supply solutions. The MAX17643 high-efficiency, high-voltage, Himalaya synchronous step-down DC-DC converter with integrated MOSFETs operates over a 4.5V to 60V input. The converter can deliver up to 2A and generates output voltages from 0.9V up to $(0.9 \times V_{IN})V$. The feedback (FB) voltage is accurate to within $\pm 1.4\%$ over -40°C to $+125^{\circ}\text{C}$. Built-in compensation across the output-voltage range eliminates the need for external components. The MAX17643 features peak-current-mode control architecture and operates in fixed frequency forced PWM mode. The current-limit settings of the MAX17643 allow the device to supply load-current peaks up to 2A. This allows the device to support pulsed load applications such as communication modules with minimal output-voltage droop. The MAX17643 offers a low minimum on-time that allows high switching frequencies and a smaller solution size.

The device is available in a 12-pin (3mm \times 3mm) TDFN package. Simulation models are available.

Applications

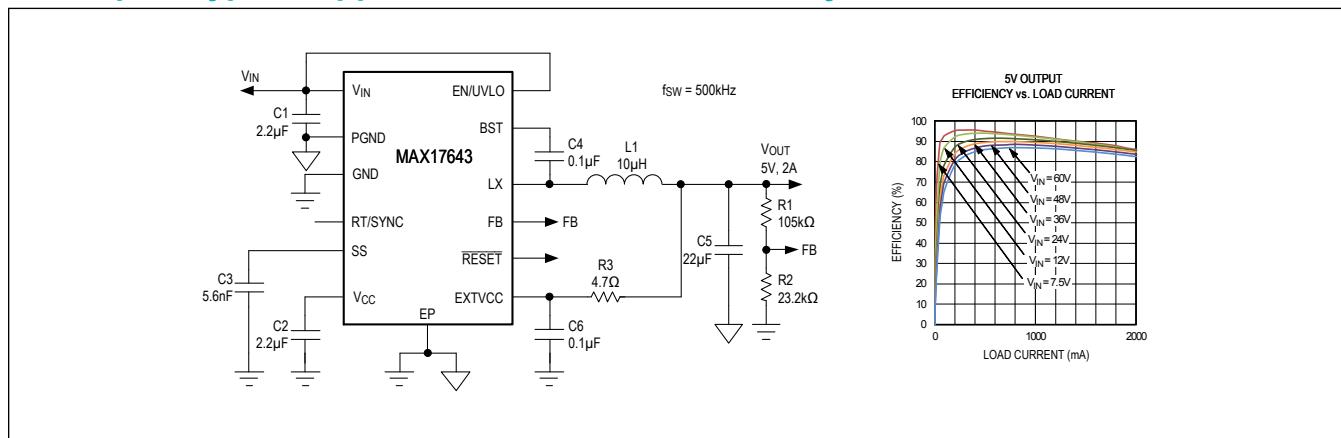
- Industrial-Control Power Supplies
- General-Purpose Point-of-Load
- Distributed Supply Regulation
- Base-Station Power Supplies
- Wall Transformer Regulation
- High-Voltage, Single-Board Systems
- Pulsed-Load Applications
- Communication Modules

Benefits and Features

- Reduces External Components and Total Cost
 - No Schottky-Synchronous Operation
 - Internal Compensation for Any Output Voltage
 - All-Ceramic Capacitors, Compact Layout
- Reduces Number of DC-DC Regulators to Stock
 - Wide 4.5V to 60V Input
 - Adjustable 0.9V to $(0.9 \times V_{IN})$ Output
 - Up to 2A Peak-Load Current
 - 400kHz to 2.2MHz Adjustable Switching Frequency with External Synchronization
- Reduces Power Dissipation
 - Peak Efficiency of 91.6%
 - Auxiliary Bootstrap LDO for Improved Efficiency
 - 4.65 μA Shutdown Current
- Operates Reliably in Adverse Industrial Environments
 - Hiccup-Mode Overload Protection
 - Adjustable Soft-Start
 - Built-In Output-Voltage Monitoring with $\overline{\text{RESET}}$
 - Programmable EN/UVLO Threshold
 - Monotonic Startup into Prebiased Load
 - Overtemperature Protection
- Wide Industrial -40°C to $+125^{\circ}\text{C}$ Ambient Operating Temperature Range/ -40°C to $+150^{\circ}\text{C}$ Junction Temperature Range
- Complies with CISPR22 (EN55022) Class B Conducted and Radiated Emissions

Ordering Information appears at end of datasheet.

5V Output: Typical Application Circuit and Efficiency vs. Load Current



Absolute Maximum Ratings

V_{IN} to PGND.....	-0.3V to +65V	V_{CC} to GND.....	-0.3V to +6.5V
EN/UVLO to GND.....	-0.3V to ($V_{IN} + 0.3V$)	LX Total RMS Current.....	$\pm 2.1A$
EXTVCC to GND.....	-0.3V to +26V	Continuous Power Dissipation ($T_A = +70^\circ C$ Derate 24.4mW/ $^\circ C$ above $+70^\circ C$; Multilayer Board).....	1951mW
BST to PGND.....	-0.3V to +70V	Output Short-Circuit Duration.....	Continuous
LX to PGND.....	-0.3V to ($V_{IN} + 0.3V$)	Junction Temperature (Note 1).....	$+150^\circ C$
BST to LX.....	-0.3V to +6.5V	Storage Temperature Range.....	$-65^\circ C$ to $+160^\circ C$
BST to V_{CC}	-0.3V to +65V	Lead Temperature (soldering, 10s).....	$+300^\circ C$
RESET, SS, RT/SYNC to GND.....	-0.3V to +6.5V	Soldering Temperature (reflow).....	$+260^\circ C$
PGND to GND.....	-0.3V to +0.3V		
FB to GND.....	-0.3V to +1.5V		

Note 1: Junction temperature greater than $+125^\circ C$ degrades operating lifetimes.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

12 PIN TDFN

Package Code	TD1233+1C
Outline Number	21-0664
Land Pattern Number	90-0397
Thermal Resistance, Four-Layer Board:	
Junction to Ambient (θ_{JA})	$41^\circ C/W$
Junction to Case (θ_{JC})	$8.5^\circ C/W$

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

Electrical Characteristics

($V_{IN} = V_{EN/UVLO} = 24V$, $R_{RT/SYNC} = 40.2k$, $C_{VCC} = 2.2\mu F$, $V_{PGND} = V_{GND} = EXTVCC = 0$, $LX = SS = \overline{RESET} = OPEN$, V_{BST} to $V_{LX} = 5V$, $V_{FB} = 1V$, $T_A = -40^\circ C$ to $125^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
INPUT SUPPLY (V_{IN})						
Input-Voltage Range	V_{IN}		4.5		60	V
Input-Shutdown Current	I_{IN-SH}	$V_{EN/UVLO} = 0V$ (shutdown mode)		4.65	7.25	μA
Input-Quiescent Current	I_{Q_PWM}	Normal switching mode, $f_{SW} = 500kHz$, $V_{FB} = 0.8$, $EXTVCC = GND$		5.65		mA
ENABLE/UVLO (EN/UVLO)						
EN/UVLO Threshold	V_{ENR}	$V_{EN/UVLO}$ rising	1.19	1.215	1.26	V
	V_{ENF}	$V_{EN/UVLO}$ falling	1.068	1.09	1.131	
EN/UVLO Input-Leakage Current	I_{ENLKG}	$V_{EN/UVLO} = 1.25V$, $T_A = 25^\circ C$	-50		+50	nA

Electrical Characteristics (continued)

($V_{IN} = V_{EN/UVLO} = 24V$, $R_{RT/SYNC} = 40.2k$, $C_{VCC} = 2.2\mu F$, $V_{PGND} = V_{GND} = EXT_{VCC} = 0$, $LX = SS = \overline{RESET} = OPEN$, V_{BST} to $V_{LX} = 5V$, $V_{FB} = 1V$, $T_A = -40^\circ C$ to $125^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
V _{CC} LDO						
V _{CC} Output-Voltage Range	V _{CC}	1mA ≤ I _{VCC} ≤ 15mA	4.75	5	5.25	V
		6V ≤ V _{IN} ≤ 60V; I _{VCC} = 1mA	4.75	5	5.25	
V _{CC} Current Limit	I _{VCC-MAX}	V _{CC} = 4.3V, V _{IN} = 6.5V	25	54	100	mA
V _{CC} Dropout	V _{CC-DO}	V _{IN} = 4.5V , I _{VCC} = 15mA	4.15			V
V _{CC} UVLO	V _{CC-UVR}	Rising	4.05	4.2	4.3	V
	V _{CC-UVF}	Falling	3.65	3.8	3.9	
EXTVCC LDO						
EXTVCC Switchover Voltage		EXTVCC rising	4.56	4.7	4.84	V
		EXTVCC falling	4.3	4.45	4.6	
EXTVCC Dropout	EXTVCC _{DO}	EXTVCC = 4.75V , I _{EXTVCC} = 15mA			0.3	V
EXTVCC Current Limit	EXTVCC _{ILIM}	V _{CC} = 4.3V, EXTVCC = 5V	26.5	60	100	mA
HIGH-SIDE MOSFET AND LOW-SIDE MOSFET DRIVER						
High-Side nMOS On-Resistance	R _{DS-ONH}	I _{LX} = 0.3A		330	620	mΩ
Low-Side nMOS On-Resistance	R _{DS-ONL}	I _{LX} = 0.3A		170	320	mΩ
LX Leakage Current (LX to PGND ₋)	I _{LXLKG}	V _{LX} = V _{IN} - 1V; V _{LX} = V _{PGND} + 1V; T _A = 25°C	-2		+2	μA
SOFT-START						
Soft-Start Current	I _{SS}	V _{SS} = 0.5 V	4.7	5	5.3	μA
FEEDBACK						
FB Regulation Voltage	V _{FB_REG}	PWM version	0.887	0.9	0.913	V
FB Input-Bias Current	I _{FB}	0 ≤ V _{FB} ≤ 1V, T _A = 25°C	-50		+50	nA
CURRENT LIMIT						
Peak Current-Limit Threshold	I _{PEAK-LIMIT}		2.69	3.25	3.63	A
Runaway-Peak Current-Limit Threshold	I _{RUNAWAY-LIMIT}		3.2	3.6	4	A
Negative Current-Limit Threshold				1		A
RT						
Switching Frequency	f _{SW}	R _{RT} = 52kΩ	370	400	430	kHz
		R _{RT} = 40.2kΩ	475	500	525	
		R _{RT} = 8.06kΩ	1950	2200	2450	
		R _{RT} = OPEN	430	490	550	
V _{OUT} Undervoltage Trip-Level to Cause HICCUP	V _{OUT-HICF}		0.56	0.58	0.65	V

Electrical Characteristics (continued)

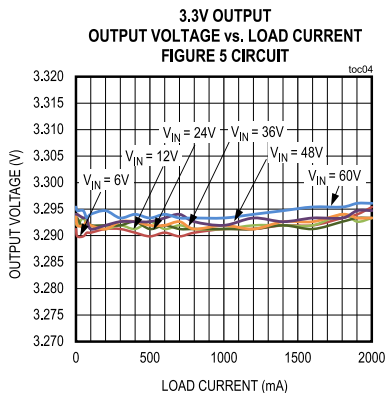
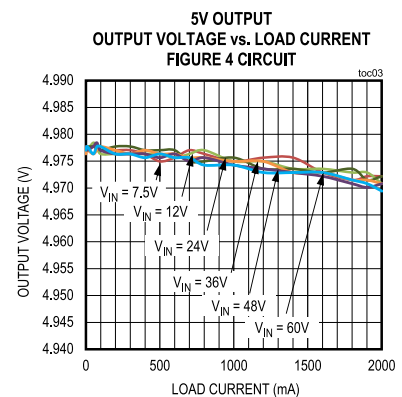
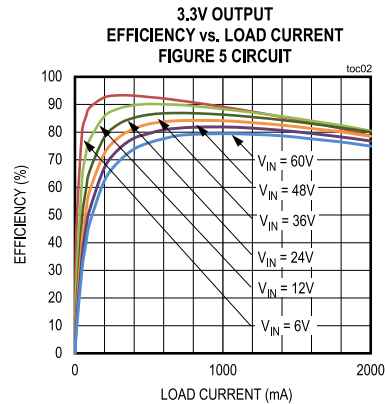
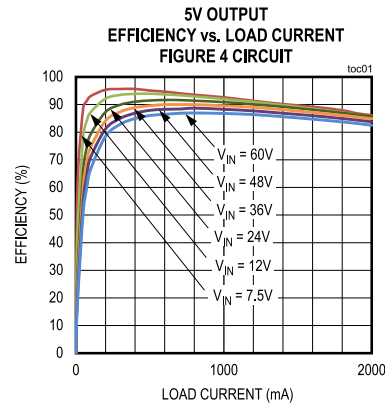
($V_{IN} = V_{EN/UVLO} = 24V$, $R_{RT/SYNC} = 40.2k$, $C_{VCC} = 2.2\mu F$, $V_{PGND} = V_{GND} = EXT_{VCC} = 0$, $LX = SS = \overline{RESET} = OPEN$, V_{BST} to $V_{LX} = 5V$, $V_{FB} = 1V$, $T_A = -40^\circ C$ to $125^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
HICCUP Timeout			32768			Cycles
Minimum On-Time	t _{ON_MIN}		6090			ns
Minimum Off-Time	t _{OFF_MIN}		140	150	160	ns
SYNC Frequency Capture Range		f _{SW} set by R _{RT}	1.1 x f _{SW}		1.4 x f _{SW}	
SYNC Pulse-Width			50			ns
SYNC Threshold	V _{IH}		2.1			V
	V _{IL}		0.8			
LX Dead Time			5			ns
RESET						
RESET Output Level Low		I _{RESET} = 10mA	400			mV
RESET Output-Leakage Current High		T _A = T _J = 25°C, V _{RESET} = 5.5V	-100+100			nA
V _{OUT} Threshold for RESET Assertion	V _{OUT-OKF}	V _{FB} Falling	90.5	92	94.6	%
V _{OUT} Threshold for RESET Deassertion	V _{OUT-OKR}	V _{FB} Falling	93.8	95	97.8	%
RESET Delay after FB Reaches 95% Regulation			1024			Cycles
THERMAL SHUTDOWN						
Thermal-Shutdown Threshold	T _{SHDNR}	Temperature rising	165			°C
Thermal-Shutdown Hysteresis	T _{SHDNHY}		15			°C

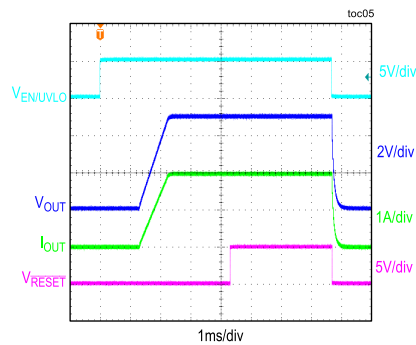
Note 2: All limits are 100% tested at $T_A = +25^\circ C$. Limits over the operating temperature range and relevant supply-voltage range are guaranteed by design and characterization

Typical Operating Characteristics

($V_{IN} = V_{EN/UVLO} = 24V$, $V_{GND} = V_{PGND} = 0V$, $C_{VCC} = 2.2\mu F$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. All voltages are referenced to GND.)

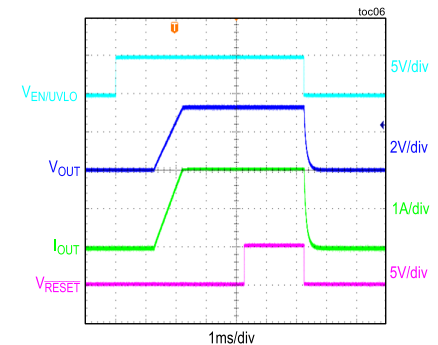


**STARTUP/SHUTDOWN THROUGH EN/UVLO
2.5Ω RESISTIVE LOAD
FIGURE 4 CIRCUIT**



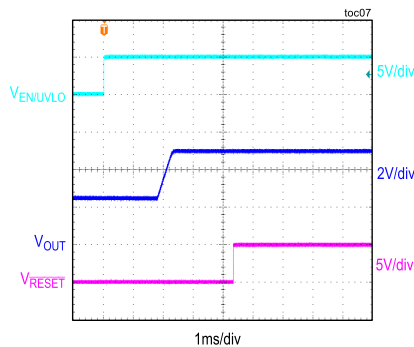
CONDITION: RESET IS PULLED UP TO V_{CC} WITH A $10k\Omega$ RESISTOR

**STARTUP/SHUTDOWN THROUGH EN/UVLO
1.65Ω RESISTIVE LOAD
FIGURE 5 CIRCUIT**



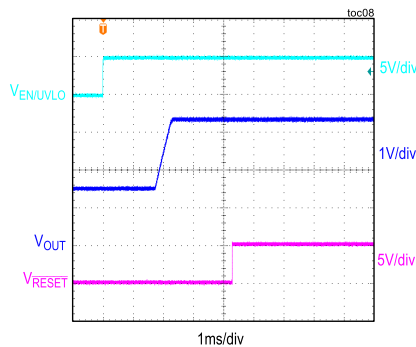
CONDITION: RESET IS PULLED UP TO V_{CC} WITH A $10k\Omega$ RESISTOR

**SOFT-START WITH 2.5V PREBIAS
5V OUTPUT
FIGURE 4 CIRCUIT**



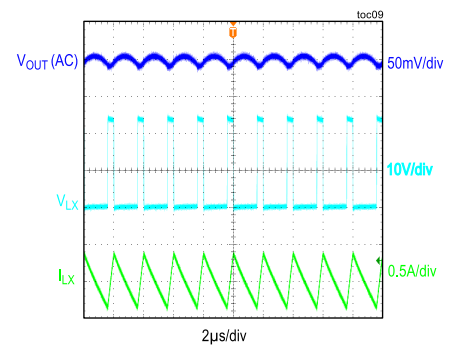
CONDITION: RESET IS PULLED UP TO V_{CC} WITH A $10k\Omega$ RESISTOR

**SOFT-START WITH 1.5V PREBIAS
3.3V OUTPUT
FIGURE 5 CIRCUIT**



CONDITION: RESET IS PULLED UP TO V_{CC} WITH A $10k\Omega$ RESISTOR

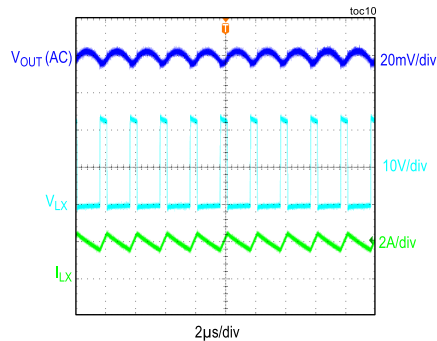
**STEADY-STATE SWITCHING WAVEFORMS
5V OUTPUT, NO LOAD
FIGURE 4 CIRCUIT**



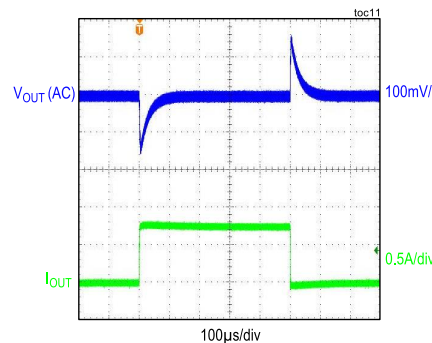
Typical Operating Characteristics (continued)

($V_{IN} = V_{EN/UVLO} = 24V$, $V_{GND} = V_{PGND} = 0V$, $C_{VCC} = 2.2\mu F$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. All voltages are referenced to GND.)

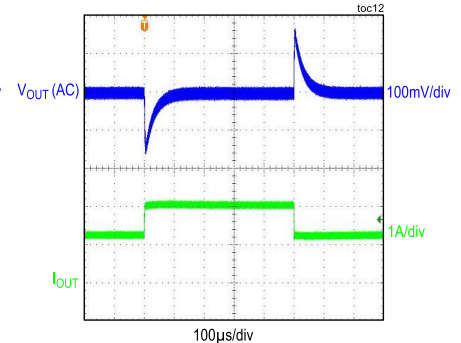
STEADY-STATE SWITCHING WAVEFORMS
5V OUTPUT, 2A LOAD CURRENT
FIGURE 4 CIRCUIT



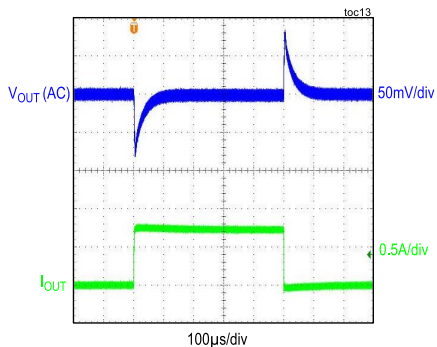
5V OUTPUT
LOAD CURRENT STEPPED FROM NO LOAD TO 0.75A
FIGURE 4 CIRCUIT



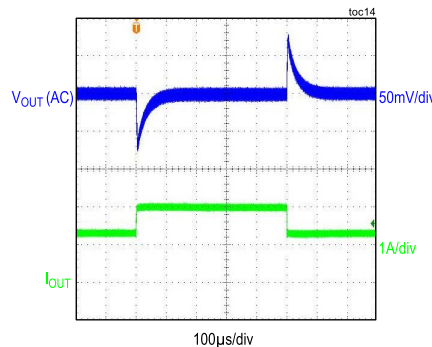
5V OUTPUT
LOAD CURRENT STEPPED FROM 1.25A TO 2A
FIGURE 4 CIRCUIT



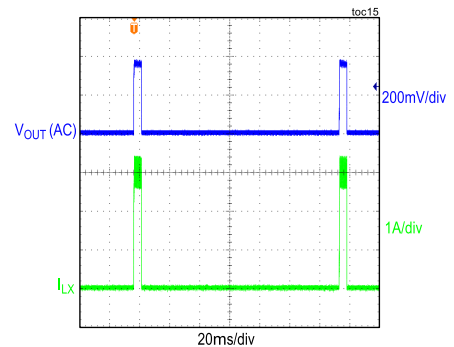
3.3V OUTPUT
LOAD CURRENT STEPPED FROM NO LOAD TO 0.75A
FIGURE 5 CIRCUIT



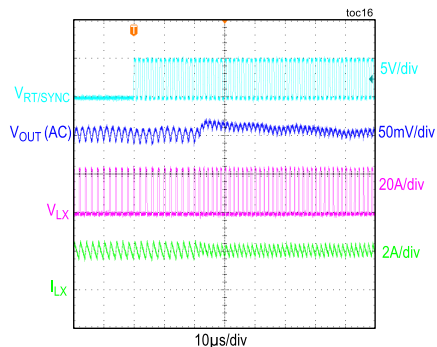
3.3V OUTPUT
LOAD CURRENT STEPPED FROM 1.25A TO 2A
FIGURE 5 CIRCUIT



OVERLOAD PROTECTION
5V OUTPUT
FIGURE 4 CIRCUIT

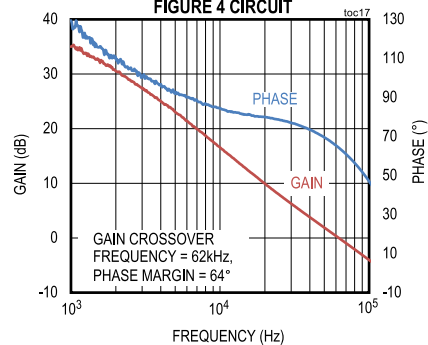


EXTERNAL-CLOCK SYNCHRONIZATION
FIGURE 4 CIRCUIT

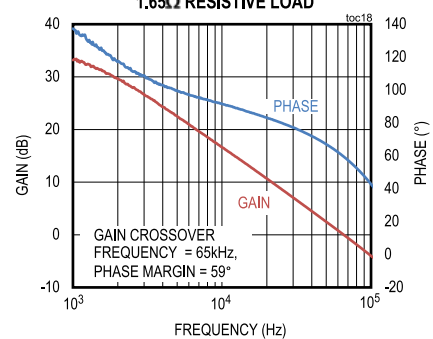


CONDITIONS: 5V OUTPUT, 2A LOAD CURRENT, $f_{SW} = 500kHz$,
EXTERNAL-CLOCK FREQUENCY = 700kHz

BODE PLOT, 5V OUTPUT
2.5Ω RESISTIVE LOAD
FIGURE 4 CIRCUIT

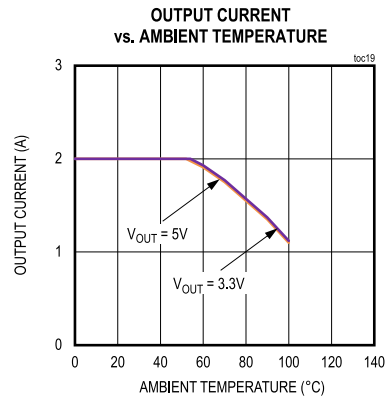


BODE PLOT, 3.3V OUTPUT
1.65Ω RESISTIVE LOAD



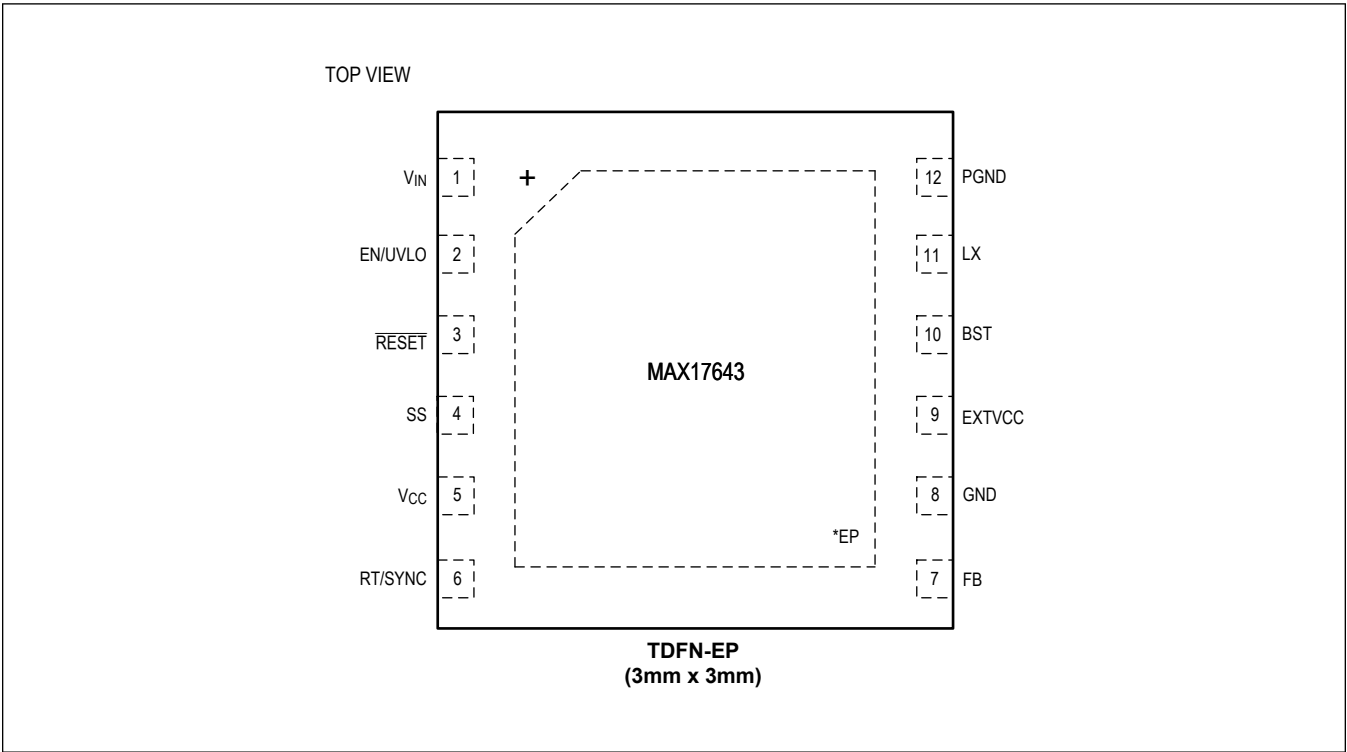
Typical Operating Characteristics (continued)

($V_{IN} = V_{EN/UVLO} = 24V$, $V_{GND} = V_{PGND} = 0V$, $C_{VCC} = 2.2\mu F$, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$. All voltages are referenced to GND.)



Pin Configuration

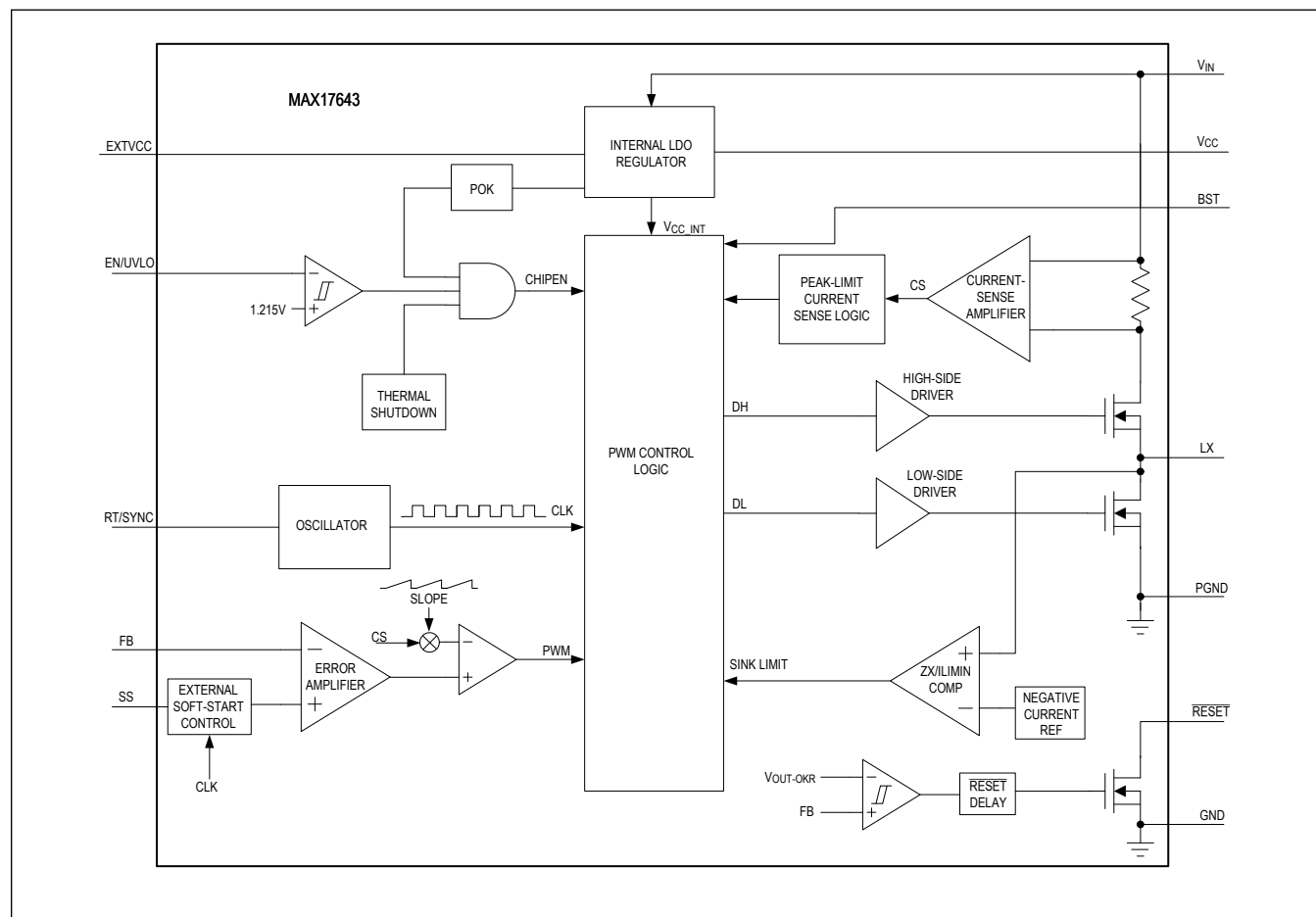
MAX17643



Pin Description

PIN	NAME	FUNCTION
1	V _{IN}	Power Supply Input. The input supply range is from 4.5V to 60V.
2	EN/UVLO	Enable/Undervoltage Lockout Input. Drive EN/UVLO high to enable the output voltage. Connect to the centre of the resistive divider between V _{IN} and GND to set the input voltage (undervoltage threshold) at which the device turns on. Pull up to V _{IN} for always-on.
3	RESET	Open-Drain RESET Output. The RESET output is driven low if FB drops below 92% of its set value. RESET goes high 1024 clock cycles after FB rises above 95% of its set value. RESET is valid when the device is enabled and V _{IN} is above 4.5V.
4	SS	Soft-Start Input. Connect a capacitor from SS to GND to set the soft-start time.
5	V _{CC}	5V LDO Output. Bypass V _{CC} with 2.2μF or 4.7μF ceramic capacitor to GND.
6	RT/SYNC	Oscillator Timing Resistor Input. Connect a resistor from RT/SYNC to GND to program the switching frequency from 400kHz to 2.2MHz. An external pulse can be applied to RT/SYNC through a coupling capacitor to synchronize the internal clock to the external pulse frequency. See the Switching Frequency Selection and External Frequency Synchronization section for details.
7	FB	Feedback Input. Connect FB to the center of the resistive divider between output voltage and GND.
8	GND	Analog Ground
9	EXTVCC	External Power-Supply Input for the Internal LDO. Applying a voltage between 4.84V and 24V at the EXTVCC pin bypasses the internal LDO and improves efficiency.
10	BST	Boost Strap Capacitor Node. Connect a 0.1μF ceramic capacitor between BST and LX.
11	LX	Switching Node. Connect LX to the switching side of the inductor. LX is high impedance when the device is in shutdown mode.
12	PGND	Power Ground. Connect PGND externally to the power ground plane. Connect GND and PGND pins together at the ground return path of the V _{CC} bypass capacitor.
—	EP	Exposed Pad. Always connect EP to the GND pin of the IC. Also, connect EP to a large GND plane with several thermal vias for best thermal performance. Refer to the MAX17643 EV kit data sheet for an example of the correct method for EP connection and thermal vias.

Functional Diagram



Detailed Description

The MAX17643 high-efficiency, high-voltage, synchronous step-down DC-DC converter with integrated MOSFETs operates over a 4.5V to 60V input. The converter can deliver up to 2A and generates output voltages from 0.9V up to $(0.9 \times V_{IN})V$. The feedback (FB) voltage is accurate to within $\pm 1.4\%$ over -40°C to $+125^{\circ}\text{C}$.

The device features a peak-current-mode control architecture and operates in fixed frequency forced PWM mode. An internal transconductance error amplifier produces an integrated error voltage at an internal node that sets the duty cycle using a PWM comparator, a high-side current-sense amplifier, and a slope-compensation generator. At each rising edge of the clock, the high-side MOSFET turns on and remains on until either the appropriate or maximum duty cycle is reached, or the peak current limit is detected. During the high-side MOSFET on-time, the inductor current ramps up. During the second-half of the switching cycle, the high-side MOSFET turns off and the low-side MOSFET turns on. The inductor releases the stored energy as its current ramps down and provides current to the output.

The device features a RT/SYNC pin to program the switching frequency and to synchronize to an external clock. The device also features adjustable-input, undervoltage-lockout, adjustable soft-start, open-drain $\overline{\text{RESET}}$, and auxiliary bootstrap LDO.

Linear Regulator (V_{CC})

The device has two internal low-dropout regulators (LDOs), which power V_{CC} . One LDO is powered from V_{IN} and the other LDO is powered from EXTVCC (EXTVCC LDO). Only one of the two LDOs is in operation at a time, depending on the voltage levels present at EXTVCC. If EXTVCC voltage is greater than 4.7V (typ), V_{CC} is powered from EXTVCC. If EXTVCC is lower than 4.7V (typ), V_{CC} is powered from V_{IN} . Powering V_{CC} from EXTVCC increases efficiency at higher input voltages. EXTVCC voltage should not exceed 24V.

Typical V_{CC} output voltage is 5V. Bypass V_{CC} to GND with either a 2.2 μF or a 4.7 μF ceramic capacitor. V_{CC} powers the internal blocks and the low-side MOSFET driver and recharges the external bootstrap capacitor. Both LDO can source up to 60mA (typ). The MAX17643 employs an undervoltage-lockout circuit that forces the converter off when V_{CC} falls below 3.8V (typ). The converter is enabled again when V_{CC} is higher than 4.2V. The 400mV UVLO hysteresis prevents chattering on power-up and power-down.

In applications where the buck converter output is connected to the EXTVCC pin, if the output is shorted to ground, then transfer from EXTVCC LDO to the internal LDO happens seamlessly without any impact on the normal functionality

Switching Frequency Selection and External Frequency Synchronization

The switching frequency of the MAX17643 can be programmed from 400kHz to 2.2MHz by using a resistor connected from the RT/SYNC pin to GND. When no resistor is used, the frequency is programmed to 490kHz. The switching frequency (f_{SW}) is related to the resistor connected at the RT/SYNC pin ($R_{\text{RT/SYNC}}$) by the following equation:

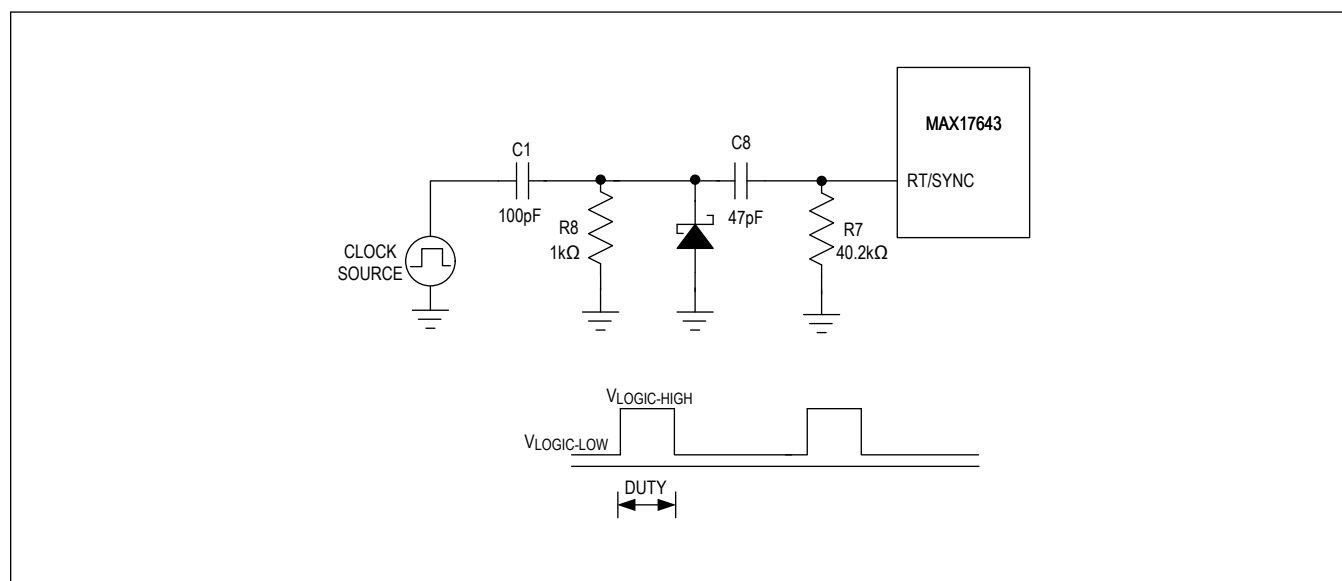
$$R_{\text{RT/SYNC}} = \frac{21 \times 10^3}{f_{\text{SW}}} - 1.7$$

where $R_{\text{RT/SYNC}}$ is in k Ω and f_{SW} is in kHz. See [Table 1](#) for RT/SYNC resistor values for a few common switching frequencies.

The RT/SYNC pin can be used to synchronize the device internal oscillator to an external system clock. A resistor must be connected from the RT/SYNC pin to GND to be able to synchronize the MAX17643 to an external clock. The external clock should be coupled to the RT/SYNC pin through a network as shown in [Figure 1](#). When an external clock is applied to the RT/SYNC pin, the internal oscillator frequency changes to the external clock frequency (from original frequency based on the RT/SYNC setting) after detecting 16 external clock edges. The external clock logic-high level should be higher than 2.1V, a logic-low level lower than 0.8V, and the pulse-width of the external clock should be more than 50ns. The RT/SYNC resistor should be selected to set the switching frequency at 10% lower than the external clock frequency

Table 1. Switching Frequency vs. RT/SYNC Resistor

SWITCHING FREQUENCY (kHz)	RT/SYNC RESISTOR (kΩ)
500	OPEN
1000	19.1
2200	8.06

**Figure 1. External Clock Synchronization****Operating Input-Voltage Range**

The minimum and maximum operating input voltages for a given output voltage should be calculated as follows:

$$V_{IN(MIN)} = \frac{V_{OUT} + (I_{OUT(MAX)} \times (R_{DCR(MAX)} + R_{DS_ONL(MAX)}))}{1 - (f_{SW(MAX)} \times t_{OFF_MIN(MAX)})} + (I_{OUT(MAX)} \times (R_{DS_ONH(MAX)} - R_{DS_ONL(MAX)}))$$

$$V_{IN(MAX)} = \frac{V_{OUT}}{f_{SW(MAX)} \times t_{ON_MIN(MAX)}}$$

where:

V_{OUT} = Steady-state output voltage

$I_{OUT(MAX)}$ = Maximum load current

$R_{DCR(MAX)}$ = Worst-case DC resistance of the inductor

$f_{SW(MAX)}$ = Maximum switching frequency

$t_{OFF_MIN(MAX)}$ = Worst-case minimum switch off-time (160ns)

$t_{ON_MIN(MAX)}$ = Worst-case minimum switch on-time (90ns)

$R_{DS_ONH(MAX)}$ = Worst-case on-state resistances and high-side internal MOSFET

$R_{DS_ONL(MAX)}$ = Worst-case on-state resistances and low-side external MOSFET

Overcurrent Protection

The device is provided with a robust overcurrent protection scheme that protects the device under overload and output short-circuit conditions. A cycle-by-cycle peak current limit turns off the high-side MOSFET whenever the high-side switch current exceeds an internal limit of 3.25A (typ). A runaway current limit on the high-side switch current at 3.6A (typ) protects the device under high input voltage, short-circuit conditions when there is insufficient output voltage available to restore the inductor current built up during the on period of the step-down converter. One occurrence of runaway current limit triggers a hiccup mode. In addition, due to any fault, if the feedback voltage drops below 0.58V any time after soft-start is completed, then hiccup mode is activated. In hiccup mode, the converter is protected by suspending switching for a hiccup timeout period of 32,768 clock cycles of half the switching frequency. Once the hiccup timeout period expires, soft-start is attempted again. Note that when soft-start is attempted under overload conditions, if feedback voltage does not exceed 0.58V, the device continues to switch at half the programmed switching frequency for the time duration of the programmed soft-start time and 1024 clock cycles. Hiccup mode of operation ensures low power dissipation under output short-circuit conditions.

RESET Output

The device includes a RESET comparator to monitor the status of the output voltage. The open-drain RESET output requires an external pullup resistor. RESET goes high (high impedance) 1024 switching cycles after the regulator output increases above 95% of the designed nominal regulated voltage. RESET goes low when the regulator output voltage drops to below 92% of the set nominal output voltage. RESET also goes low during thermal shutdown or when the EN/UVLO pin goes below V_{ENF} .

Thermal-Shutdown Protection

Thermal-shutdown protection limits total power dissipation in the device. When the junction temperature of the device exceeds +165°C, an on-chip thermal sensor shuts down the device, allowing the device to cool. The device turns on with soft-start after the junction temperature reduces by 15°C. The MAX17643 can enter thermal shutdown for load currents greater than 2A. Carefully evaluate the total power dissipation (see the [Power Dissipation](#) section) to avoid unwanted triggering of the thermal shutdown protection in normal operation.

Applications Information

Input Capacitor Selection

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by circuit switching. The input capacitor RMS current (I_{RMS}) is defined by the following equation:

$$I_{RMS} = I_{OUT(MAX)} \times \frac{\sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$

where, $I_{OUT(MAX)}$ is the maximum load current. I_{RMS} has a maximum value when the input voltage equals twice the output voltage ($V_{IN} = 2 \times V_{OUT}$), so $I_{RMS(MAX)} = \frac{I_{OUT(MAX)}}{2}$.

Choose an input capacitor that exhibits less than +10°C temperature rise at the RMS input current for optimal long-term reliability. Use low-ESR ceramic capacitors with high-ripple-current capability at the input. X7R capacitors are recommended in industrial applications for their temperature stability. Calculate the input capacitance using the following equation:

$$C_{IN} = \frac{I_{OUT(MAX)} \times D \times (1 - D)}{\eta \times f_{SW} \times \Delta V_{IN}}$$

where:

$D = V_{OUT} / V_{IN}$ and is the duty ratio of the converter,

f_{SW} = Switching frequency,

ΔV_{IN} = Allowable input voltage ripple

η = Efficiency

In applications where the source is located distant from the device input, an electrolytic capacitor should be added in parallel to the ceramic capacitor to provide necessary damping for potential oscillations caused by the inductance of the longer input power path and input ceramic capacitor.

Inductor Selection

Three key inductor parameters must be specified for operation with the device: inductance value (L), inductor saturation current (I_{SAT}), and DC resistance (R_{DCR}). The switching frequency and output voltage determine the inductor value as follows:

$$L = \frac{1.1 \times V_{OUT}}{f_{SW}}$$

where V_{OUT} and f_{SW} are nominal values and f_{SW} is in Hz. Select an inductor whose value is nearest to the value calculated by the previous formula.

Select a low-loss inductor closest to the calculated value with acceptable dimensions and having the lowest possible DC resistance. The saturation current rating (I_{SAT}) of the inductor must be high enough to ensure that saturation can occur only above the peak current-limit value.

Output Capacitor Selection

X7R ceramic output capacitors are preferred due to their stability over temperature in industrial applications. The output capacitors are usually sized to support a step load of 50% of the maximum output current in the application, so the output voltage deviation is contained to 3% of the output-voltage change. The minimum required output capacitance can be calculated as follows: $C_{OUT} = \frac{90}{V_{OUT}}$

Where C_{OUT} is in μF . Derating of ceramic capacitors with DC voltage must be considered while selecting the output capacitor. Derating curves are available from all major ceramic capacitor vendors.

Soft-Start Capacitor Selection

The device implements adjustable soft-start operation to reduce inrush current. A capacitor connected from the SS pin to GND programs the soft-start time. The selected output capacitance (C_{SEL}) and the output voltage (V_{OUT}) determine the minimum required soft-start capacitor as follows:

$$C_{SS} \geq 56 \times 10^{-6} \times C_{SEL} \times V_{OUT}$$

The soft-start time (t_{SS}) is related to the capacitor connected at SS (C_{SS}) by the following equation:

$$t_{SS} = \frac{C_{SS}}{5.55 \times 10^{-6}}$$

For example, to program a 2ms soft-start time, a 12nF capacitor should be connected from the SS pin to GND. Note that during startup, the device operates at half the programmed switching frequency until the output voltage reaches 66.7% of the set output nominal voltage.

Adjusting Output Voltage

Set the output voltage with a resistive voltage-divider connected from the positive terminal of the output capacitor (V_{OUT}) to SGND (see [Figure 2](#)). Connect the center node of the divider to the FB pin. Use the following procedure to choose the resistive voltage-divider values:

Calculate resistor R4 from the output to the FB pin as follows:

$$R4 = \frac{1635}{C_{OUT_SEL}}$$

Where C_{OUT_SEL} (μF) is the actual derated value of the output capacitance used and R4 is in k Ω . The minimum allowable value of R4 is $(5.6 \times V_{OUT})$, where R4 is in k Ω . If the value of R4 calculated using the above equation is less than $(5.6 \times V_{OUT})$, increase the value of R4 to at least $(5.6 \times V_{OUT})$.

$$R5 = \frac{R4 \times 0.9}{(V_{OUT} - 0.9)}$$

R5 is in k Ω .

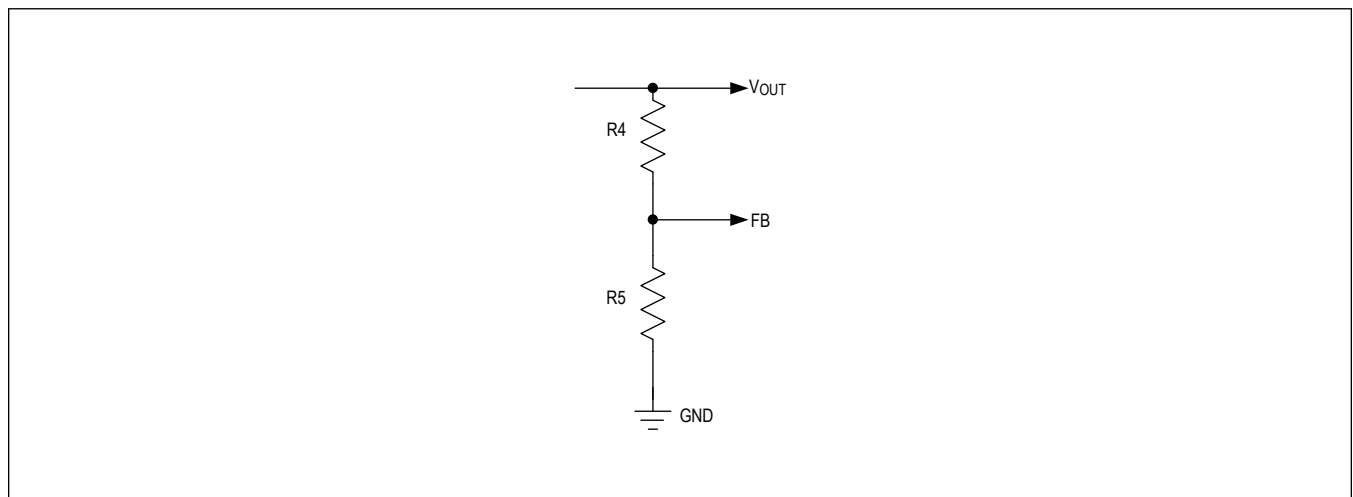


Figure 2. Adjusting Output Voltage

Setting the Undervoltage Lockout Level

The device offers an adjustable input undervoltage-lockout level. Set the voltage at which the device turns on with a

resistive voltage-divider connected from V_{IN} to SGND ([Figure 3](#)). Connect the center node of the divider to EN/UVLO. Choose R1 to be 3.32M Ω and then calculate R2 as follows:

$$R2 = \frac{1.215 \times R1}{(V_{INU} - 1.215)}$$

where V_{INU} is the voltage at which the device is required to turn on. Ensure that V_{INU} is higher than $0.8 \times V_{OUT}$. To avoid hiccup during slow power-up (slower than soft-start) or power-down.

If the EN/UVLO pin is driven from an external signal source, it is recommended that a series resistance of minimum 1k Ω is placed between the signal source output and the EN/UVLO pin to reduce voltage ringing on the line.

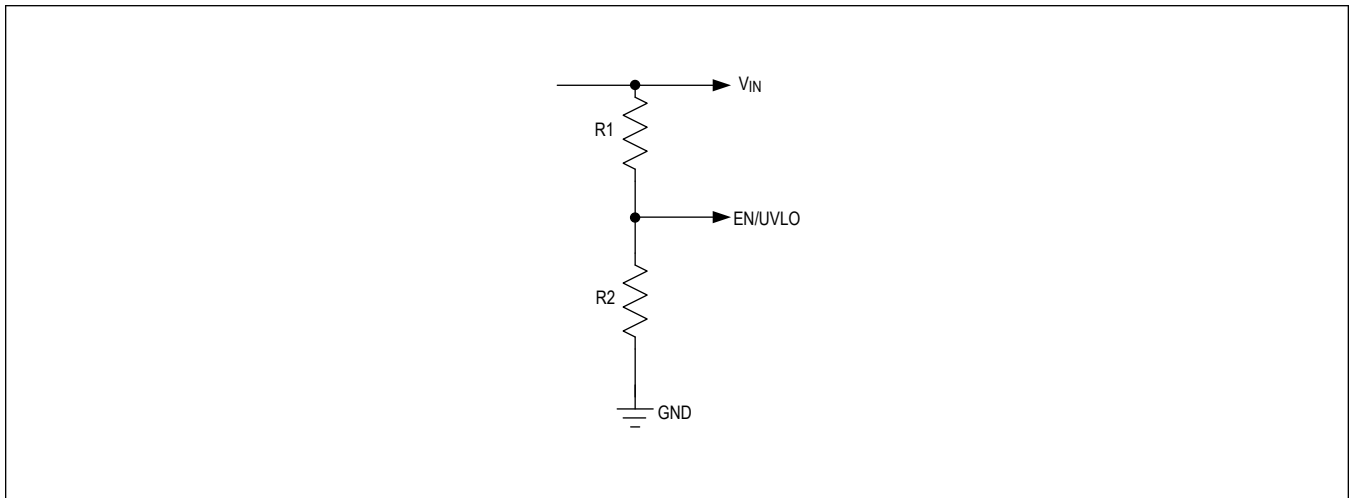


Figure 3. Setting the Input Undervoltage Lockout

Power Dissipation

At a particular operating condition, the power losses that lead to temperature rise of the part are estimated as follows:

$$P_{LOSS} = (P_{OUT} \times (\frac{1}{\eta} - 1)) - (I_{OUT}^2 \times R_{DCR})$$

$$P_{OUT} = V_{OUT} \times I_{OUT}$$

where:

P_{OUT} = Output power

η = Efficiency of the converter

R_{DCR} = DC resistance of the inductor (see the [Typical Operating Characteristics](#) for more information on efficiency at typical operating conditions).

For a typical multilayer board, the thermal performance metrics for the package are given below:

$$\theta_{JA} = 41^\circ \text{C} / \text{W}$$

$$\theta_{JC} = 8.5^\circ \text{C} / \text{W}$$

The junction temperature of the device can be estimated at any given maximum ambient temperature ($T_{A(MAX)}$) from the following equation:

$$T_{J(MAX)} = T_{A(MAX)} + (\theta_{JA} \times P_{LOSS})$$

If the application has a thermal-management system that ensures that the exposed pad of the device is maintained at

a given temperature ($T_{EP(MAX)}$) by using proper heat sinks, the junction temperature of the device can be estimated at any given maximum ambient temperature as:

$$T_{J(MAX)} = T_{EP(MAX)} + (\theta_{JC} \times P_{LOSS})$$

Junction temperatures greater than +125°C degrades operating lifetimes.

PCB Layout Guidelines

Careful PCB layout is critical to achieving a clean and stable operation. The switching power stage requires particular attention. Follow the guidelines below for a good PCB layout.

- Place the input ceramic capacitor as close as possible to the V_{IN} and GND pins.
- Place the output capacitor as close as possible to the OUT pin.
- Place the GND terminals of the input capacitor, output capacitor, and the inductor as close as possible and connect them to the GND plane.
- Connect the negative terminal of the V_{CC} bypass capacitor to the GND pin with shortest possible trace or ground plane.
- Minimize the area formed by the LX pin and the inductor connection to reduce the radiated EMI.
- Place the V_{CC} decoupling capacitor as close as possible to the V_{CC} pin.
- Place the BST capacitor close to the BST and LX pins.
- Place the RT/SYNC resistor and the feedback resistor divider as close as possible to their respective pins.
- Keep all the power connections and load connections short.
- Ensure that all feedback connections are short and direct.
- Route the high-speed switching node (LX) away from the FB/ V_{OUT} , \overline{RESET} , and MODE pins.

For a sample layout that ensures first pass success, refer to the MAX17643 evaluation kit layout available at www.maximintegrated.com.

Typical Application Circuits

5V Output with 500kHz Switching Frequency

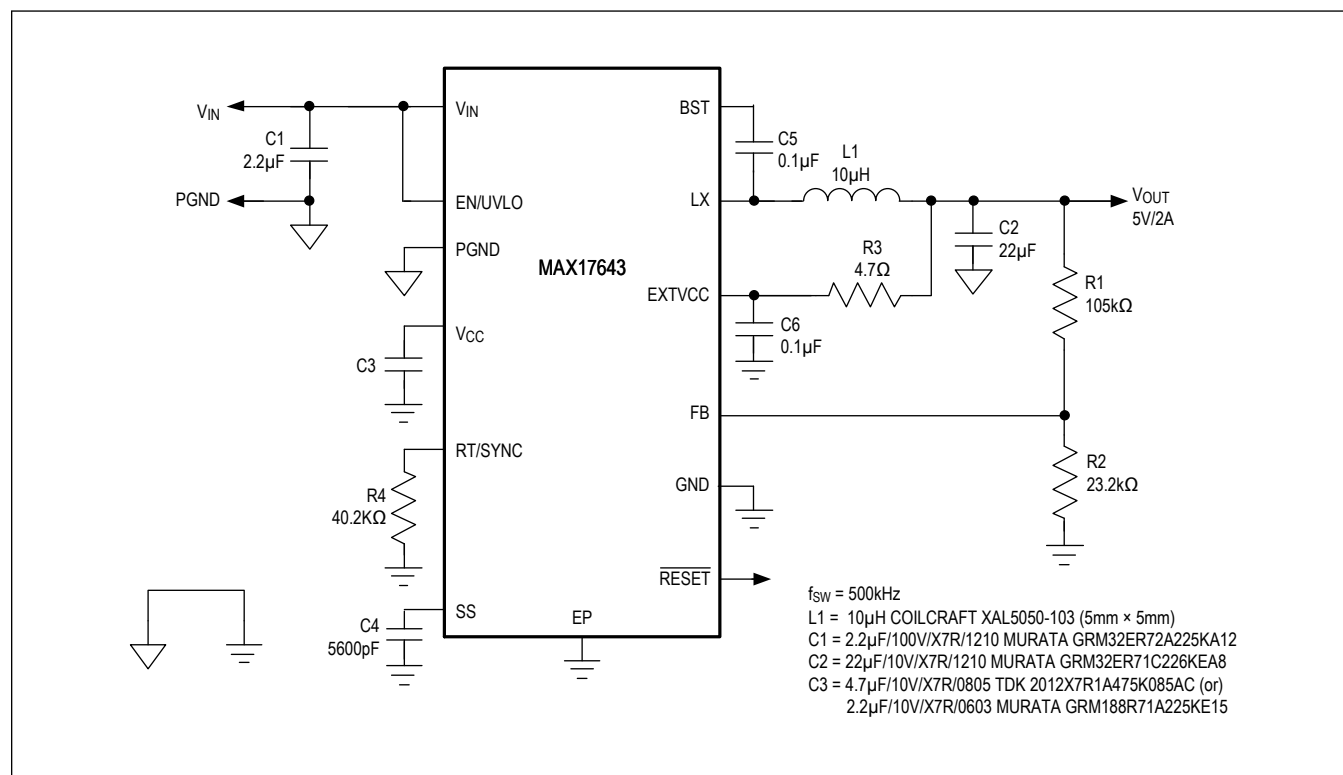


Figure 4. Typical Application Circuit for 5V Output with 500kHz Switching Frequency

Typical Application Circuits (continued)

3.3V Output with 500kHz Switching Frequency

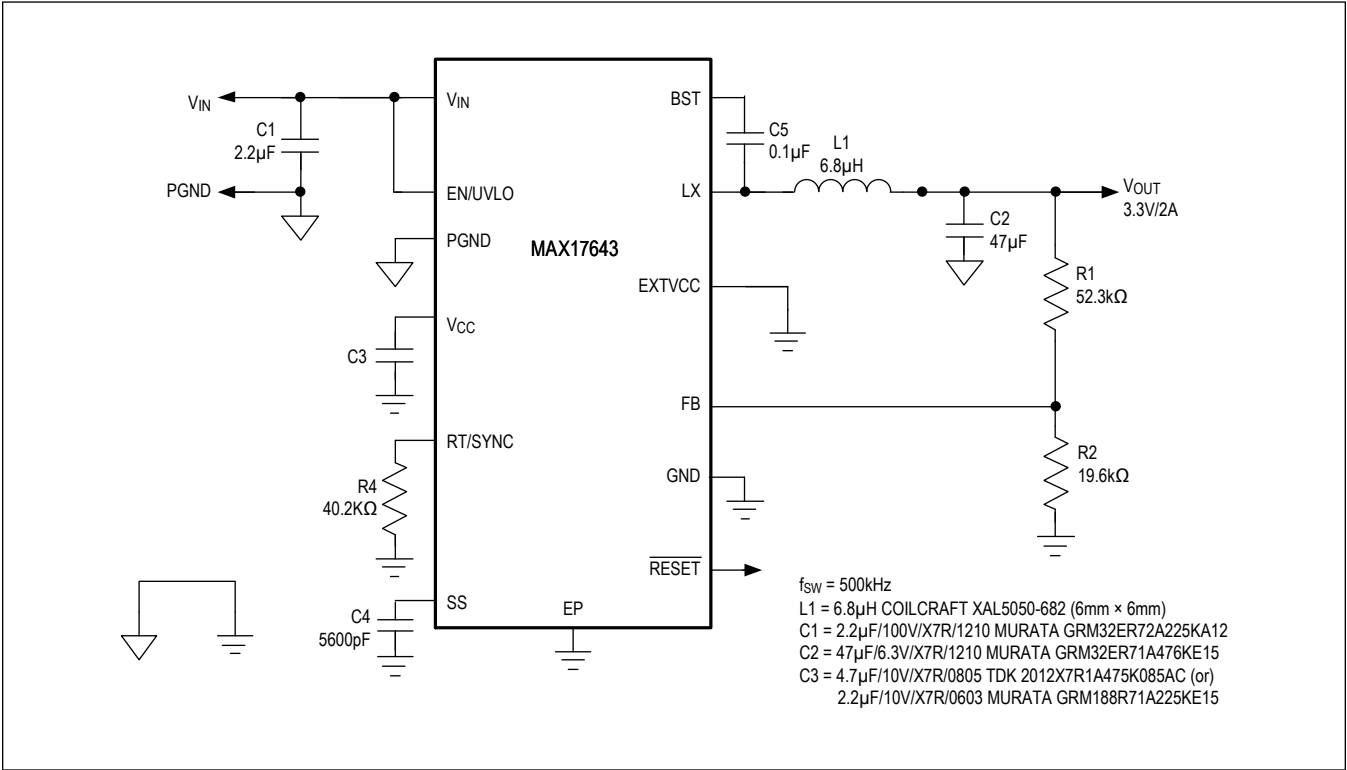


Figure 5. Typical Application Circuit for 3.3V Output with 500kHz Switching Frequency

Ordering Information

PART	PIN-PACKAGE	PACKAGE SIZE
MAX17643ATC+	12-TDFN EP*	3mm x 3mm
MAX17643ATC+T	12-TDFN EP*	3mm x 3mm

+Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

*EP = Exposed pad.

MAX17643

4.5V–60V, 2A, High-Efficiency,
Synchronous Step-Down DC-DC Converter with
Internal Compensation

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	10/20	Release for Market Intro	—

For pricing, delivery, and ordering information, please visit Maxim Integrated's online storefront at <https://www.maximintegrated.com/en/storefront/storefront.html>.

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